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1.1 Installing scikit-learn

There are different ways to install scikit-learn:

- **Install the latest official release.** This is the best approach for most users. It will provide a stable version and pre-built packages are available for most platforms.

- Install the version of scikit-learn provided by your *operating system or Python distribution*. This is a quick option for those who have operating systems or Python distributions that distribute scikit-learn. It might not provide the latest release version.

- **Building the package from source.** This is best for users who want the latest-and-greatest features and aren’t afraid of running brand-new code. This is also needed for users who wish to contribute to the project.

1.1.1 Installing the latest release

Then run:

In order to check your installation you can use

Note that in order to avoid potential conflicts with other packages it is strongly recommended to use a virtual environment, e.g. `python3 virtualenv` (see `python3 virtualenv documentation`) or `conda environments`.

Using an isolated environment makes possible to install a specific version of scikit-learn and its dependencies independently of any previously installed Python packages. In particular under Linux is it discouraged to install pip packages alongside the packages managed by the package manager of the distribution (apt, dnf, pacman...).

Note that you should always remember to activate the environment of your choice prior to running any Python command whenever you start a new terminal session.

If you have not installed NumPy or SciPy yet, you can also install these using conda or pip. When using pip, please ensure that *binary wheels* are used, and NumPy and SciPy are not recompiled from source, which can happen when using particular configurations of operating system and hardware (such as Linux on a Raspberry Pi).

If you must install scikit-learn and its dependencies with pip, you can install it as `scikit-learn[alldeps]`.

Scikit-learn plotting capabilities (i.e., functions start with “plot_” and classes end with “Display”) require Matplotlib. The examples require Matplotlib and some examples require scikit-image, pandas, or seaborn. The minimum version of Scikit-learn dependencies are listed below along with its purpose.
### Third party distributions of scikit-learn

Some third-party distributions provide versions of scikit-learn integrated with their package-management systems. These can make installation and upgrading much easier for users since the integration includes the ability to automatically install dependencies (numpy, scipy) that scikit-learn requires.

The following is an incomplete list of OS and python distributions that provide their own version of scikit-learn.

#### Arch Linux

Arch Linux’s package is provided through the official repositories as python-scikit-learn for Python. It can be installed by typing the following command:

```
$ sudo pacman -S python-scikit-learn
```
Debian/Ubuntu

The Debian/Ubuntu package is split in three different packages called `python3-sklearn` (python modules), `python3-sklearn-lib` (low-level implementations and bindings), `python3-sklearn-doc` (documentation). Only the Python 3 version is available in the Debian Buster (the more recent Debian distribution). Packages can be installed using `apt-get`:

```bash
$ sudo apt-get install python3-sklearn python3-sklearn-lib python3-sklearn-doc
```

Fedora

The Fedora package is called `python3-scikit-learn` for the python 3 version, the only one available in Fedora30. It can be installed using `dnf`:

```bash
$ sudo dnf install python3-scikit-learn
```

NetBSD

`scikit-learn` is available via `pkgsrc-wip`:

http://pkgsrc.se/math/py-scikit-learn

MacPorts for Mac OSX

The MacPorts package is named `py<XY>-scikits-learn`, where `XY` denotes the Python version. It can be installed by typing the following command:

```bash
$ sudo port install py36-scikit-learn
```

Anaconda and Enthought Deployment Manager for all supported platforms

Anaconda and Enthought Deployment Manager both ship with scikit-learn in addition to a large set of scientific python library for Windows, Mac OSX and Linux.

Anaconda offers scikit-learn as part of its free distribution.

Intel conda channel

Intel maintains a dedicated conda channel that ships scikit-learn:

```bash
$ conda install -c intel scikit-learn
```

This version of scikit-learn comes with alternative solvers for some common estimators. Those solvers come from the DAAL C++ library and are optimized for multi-core Intel CPUs.

Note that those solvers are not enabled by default, please refer to the `daal4py` documentation for more details.

Compatibility with the standard scikit-learn solvers is checked by running the full scikit-learn test suite via automated continuous integration as reported on https://github.com/IntelPython/daal4py.
WinPython for Windows

The WinPython project distributes scikit-learn as an additional plugin.

1.1.3 Troubleshooting

Error caused by file path length limit on Windows

It can happen that pip fails to install packages when reaching the default path size limit of Windows if Python is installed in a nested location such as the AppData folder structure under the user home directory, for instance:

```
C:\Users\username>C:\Users\username\AppData\Local\Microsoft\WindowsApps\python.exe -m ...
--pip install scikit-learn
Collecting scikit-learn
... Installing collected packages: scikit-learn
ERROR: Could not install packages due to an EnvironmentError: [Errno 2] No such file...
--or directory: 'C:\\Users\\username\\AppData\\Local\\Packages\\
--PythonSoftwareFoundation.Python.3.7_qbz5n2kfra8p0\\LocalCache\\local-packages\\
--Python37\\site-packages\\sklearn\\datasets\\tests\\data\\openml\\292\\api-v1-json-
--data-list-data_name-australian-limit-2-data_version-1-status-deactivated.json.gz'
```

In this case it is possible to lift that limit in the Windows registry by using the regedit tool:

1. Type “regedit” in the Windows start menu to launch regedit.
2. Go to the Computer\HKEY_LOCAL_MACHINE\SYSTEM\CurrentControlSet\Control\FileSystem key.
3. Edit the value of the LongPathsEnabled property of that key and set it to 1.
4. Reinstall scikit-learn (ignoring the previous broken installation): $ pip install --exists-action=i scikit-learn

1.2 Frequently Asked Questions

Here we try to give some answers to questions that regularly pop up on the mailing list.

1.2.1 What is the project name (a lot of people get it wrong)?

scikit-learn, but not scikit or SciKit nor sci-kit learn. Also not scikits.learn or scikits-learn, which were previously used.
1.2.2 How do you pronounce the project name?

sy-kit learn. sci stands for science!

1.2.3 Why scikit?

There are multiple scikits, which are scientific toolboxes built around SciPy. You can find a list at https://scikits.appspot.com/scikits. Apart from scikit-learn, another popular one is scikit-image.

1.2.4 How can I contribute to scikit-learn?

See Contributing. Before wanting to add a new algorithm, which is usually a major and lengthy undertaking, it is recommended to start with known issues. Please do not contact the contributors of scikit-learn directly regarding contributing to scikit-learn.

1.2.5 What’s the best way to get help on scikit-learn usage?

For general machine learning questions, please use Cross Validated with the [machine-learning] tag.

For scikit-learn usage questions, please use Stack Overflow with the [scikit-learn] and [python] tags. You can alternatively use the mailing list.

Please make sure to include a minimal reproduction code snippet (ideally shorter than 10 lines) that highlights your problem on a toy dataset (for instance from sklearn.datasets or randomly generated with functions of numpy.random with a fixed random seed). Please remove any line of code that is not necessary to reproduce your problem.

The problem should be reproducible by simply copy-pasting your code snippet in a Python shell with scikit-learn installed. Do not forget to include the import statements.

More guidance to write good reproduction code snippets can be found at:

https://stackoverflow.com/help/mcve

If your problem raises an exception that you do not understand (even after googling it), please make sure to include the full traceback that you obtain when running the reproduction script.

For bug reports or feature requests, please make use of the issue tracker on GitHub.

There is also a scikit-learn Gitter channel where some users and developers might be found.

Please do not email any authors directly to ask for assistance, report bugs, or for any other issue related to scikit-learn.

1.2.6 How should I save, export or deploy estimators for production?

See Model persistence.
1.2.7 How can I create a bunch object?

Bunch objects are sometimes used as an output for functions and methods. They extend dictionaries by enabling values to be accessed by key, `bunch["value_key"]`, or by an attribute, `bunch.value_key`.

They should not be used as an input; therefore you almost never need to create a `Bunch` object, unless you are extending the scikit-learn’s API.

1.2.8 How can I load my own datasets into a format usable by scikit-learn?

Generally, scikit-learn works on any numeric data stored as numpy arrays or scipy sparse matrices. Other types that are convertible to numeric arrays such as pandas DataFrame are also acceptable.

For more information on loading your data files into these usable data structures, please refer to loading external datasets.

1.2.9 What are the inclusion criteria for new algorithms?

We only consider well-established algorithms for inclusion. A rule of thumb is at least 3 years since publication, 200+ citations, and wide use and usefulness. A technique that provides a clear-cut improvement (e.g. an enhanced data structure or a more efficient approximation technique) on a widely-used method will also be considered for inclusion.

From the algorithms or techniques that meet the above criteria, only those which fit well within the current API of scikit-learn, that is a `fit`, `predict`, `transform` interface and ordinarily having input/output that is a numpy array or sparse matrix, are accepted.

The contributor should support the importance of the proposed addition with research papers and/or implementations in other similar packages, demonstrate its usefulness via common use-cases/applications and corroborate performance improvements, if any, with benchmarks and/or plots. It is expected that the proposed algorithm should outperform the methods that are already implemented in scikit-learn at least in some areas.

Inclusion of a new algorithm speeding up an existing model is easier if:

- it does not introduce new hyper-parameters (as it makes the library more future-proof),
- it is easy to document clearly when the contribution improves the speed and when it does not, for instance “when `n_features >> n_samples`”,
- benchmarks clearly show a speed up.

Also, note that your implementation need not be in scikit-learn to be used together with scikit-learn tools. You can implement your favorite algorithm in a scikit-learn compatible way, upload it to GitHub and let us know. We will be happy to list it under Related Projects. If you already have a package on GitHub following the scikit-learn API, you may also be interested to look at scikit-learn-contrib.

1.2.10 Why are you so selective on what algorithms you include in scikit-learn?

Code comes with maintenance cost, and we need to balance the amount of code we have with the size of the team (and add to this the fact that complexity scales non linearly with the number of features). The package relies on core developers using their free time to fix bugs, maintain code and review contributions. Any algorithm that is added needs future attention by the developers, at which point the original author might long have lost interest. See also What are the inclusion criteria for new algorithms?. For a great read about long-term maintenance issues in open-source software, look at the Executive Summary of Roads and Bridges.
1.2.11 Why did you remove HMMs from scikit-learn?

See Will you add graphical models or sequence prediction to scikit-learn?.

1.2.12 Will you add graphical models or sequence prediction to scikit-learn?

Not in the foreseeable future. scikit-learn tries to provide a unified API for the basic tasks in machine learning, with pipelines and meta-algorithms like grid search to tie everything together. The required concepts, APIs, algorithms and expertise required for structured learning are different from what scikit-learn has to offer. If we started doing arbitrary structured learning, we’d need to redesign the whole package and the project would likely collapse under its own weight.

There are two projects with API similar to scikit-learn that do structured prediction:

- **pystruct** handles general structured learning (focuses on SSVMs on arbitrary graph structures with approximate inference; defines the notion of sample as an instance of the graph structure)
- **seqlearn** handles sequences only (focuses on exact inference; has HMMs, but mostly for the sake of completeness; treats a feature vector as a sample and uses an offset encoding for the dependencies between feature vectors)

1.2.13 Will you add GPU support?

No, or at least not in the near future. The main reason is that GPU support will introduce many software dependencies and introduce platform specific issues. scikit-learn is designed to be easy to install on a wide variety of platforms. Outside of neural networks, GPUs don’t play a large role in machine learning today, and much larger gains in speed can often be achieved by a careful choice of algorithms.

1.2.14 Do you support PyPy?

In case you didn’t know, **PyPy** is an alternative Python implementation with a built-in just-in-time compiler. Experimental support for PyPy3-v5.10+ has been added, which requires Numpy 1.14.0+, and scipy 1.1.0+.

1.2.15 How do I deal with string data (or trees, graphs . . . )?

scikit-learn estimators assume you’ll feed them real-valued feature vectors. This assumption is hard-coded in pretty much all of the library. However, you can feed non-numerical inputs to estimators in several ways.

If you have text documents, you can use a term frequency features; see Text feature extraction for the built-in text vectorizers. For more general feature extraction from any kind of data, see Loading features from dicts and Feature hashing.

Another common case is when you have non-numerical data and a custom distance (or similarity) metric on these data. Examples include strings with edit distance (aka. Levenshtein distance; e.g., DNA or RNA sequences). These can be encoded as numbers, but doing so is painful and error-prone. Working with distance metrics on arbitrary data can be done in two ways.

Firstly, many estimators take precomputed distance/similarity matrices, so if the dataset is not too large, you can compute distances for all pairs of inputs. If the dataset is large, you can use feature vectors with only one “feature”, which is an index into a separate data structure, and supply a custom metric function that looks up the actual data in this data structure. E.g., to use DBSCAN with Levenshtein distances:
>>> from leven import levenshtein
>>> import numpy as np
>>> from sklearn.cluster import dbscan

```
>>> data = ["ACCTCCTAGAAG", "ACCTACTAGAAGTT", "GAATATTAGGCCGA"]
>>> def lev_metric(x, y):
...     i, j = int(x[0]), int(y[0])  # extract indices
...     return levenshtein(data[i], data[j])
...
>>> X = np.arange(len(data)).reshape(-1, 1)
>>> X
array([[0],
       [1],
       [2]])
>>> # We need to specify algorithm='brute' as the default assumes
>>> # a continuous feature space.
>>> dbscan(X, metric=lev_metric, eps=5, min_samples=2, algorithm='brute')
... ([0, 1], array([ 0, 0, -1]))
```

(This uses the third-party edit distance package leven.)

Similar tricks can be used, with some care, for tree kernels, graph kernels, etc.

### 1.2.16 Why do I sometime get a crash/freeze with n_jobs > 1 under OSX or Linux?

Several scikit-learn tools such as GridSearchCV and cross_val_score rely internally on Python’s multiprocessing module to parallelize execution onto several Python processes by passing n_jobs > 1 as an argument.

The problem is that Python multiprocessing does a fork system call without following it with an exec system call for performance reasons. Many libraries like (some versions of) Accelerate / vecLib under OSX, (some versions of) MKL, the OpenMP runtime of GCC, nvidia’s Cuda (and probably many others), manage their own internal thread pool. Upon a call to fork, the thread pool state in the child process is corrupted: the thread pool believes it has many threads while only the main thread state has been forked. It is possible to change the libraries to make them detect when a fork happens and reinitialize the thread pool in that case: we did that for OpenBLAS (merged upstream in master since 0.2.10) and we contributed a patch to GCC’s OpenMP runtime (not yet reviewed).

But in the end the real culprit is Python’s multiprocessing that does fork without exec to reduce the overhead of starting and using new Python processes for parallel computing. Unfortunately this is a violation of the POSIX standard and therefore some software editors like Apple refuse to consider the lack of fork-safety in Accelerate / vecLib as a bug.

In Python 3.4+ it is now possible to configure multiprocessing to use the ‘forkserver’ or ‘spawn’ start methods (instead of the default ‘fork’) to manage the process pools. To work around this issue when using scikit-learn, you can set the JOBLIB_START_METHOD environment variable to ‘forkserver’. However the user should be aware that using the ‘forkserver’ method prevents joblib.Parallel to call function interactively defined in a shell session.

If you have custom code that uses multiprocessing directly instead of using it via joblib you can enable the ‘forkserver’ mode globally for your program: Insert the following instructions in your main script:

```
import multiprocessing

# other imports, custom code, load data, define model...
if __name__ == '__main__':
    multiprocessing.set_start_method('forkserver')
```

(continues on next page)
You can find more default on the new start methods in the multiprocessing documentation.

1.2.17 Why does my job use more cores than specified with n_jobs?

This is because `n_jobs` only controls the number of jobs for routines that are parallelized with `joblib`, but parallel code can come from other sources:

- some routines may be parallelized with OpenMP (for code written in C or Cython).
- scikit-learn relies a lot on numpy, which in turn may rely on numerical libraries like MKL, OpenBLAS or BLIS which can provide parallel implementations.

For more details, please refer to our Parallelism notes.

1.2.18 Why is there no support for deep or reinforcement learning / Will there be support for deep or reinforcement learning in scikit-learn?

Deep learning and reinforcement learning both require a rich vocabulary to define an architecture, with deep learning additionally requiring GPUs for efficient computing. However, neither of these fit within the design constraints of scikit-learn; as a result, deep learning and reinforcement learning are currently out of scope for what scikit-learn seeks to achieve.

You can find more information about addition of gpu support at Will you add GPU support?.

Note that scikit-learn currently implements a simple multilayer perceptron in `sklearn.neural_network`. We will only accept bug fixes for this module. If you want to implement more complex deep learning models, please turn to popular deep learning frameworks such as tensorflow, keras and pytorch.

1.2.19 Why is my pull request not getting any attention?

The scikit-learn review process takes a significant amount of time, and contributors should not be discouraged by a lack of activity or review on their pull request. We care a lot about getting things right the first time, as maintenance and later change comes at a high cost. We rarely release any “experimental” code, so all of our contributions will be subject to high use immediately and should be of the highest quality possible initially.

Beyond that, scikit-learn is limited in its reviewing bandwidth; many of the reviewers and core developers are working on scikit-learn on their own time. If a review of your pull request comes slowly, it is likely because the reviewers are busy. We ask for your understanding and request that you not close your pull request or discontinue your work solely because of this reason.
1.2.20 How do I set a random_state for an entire execution?

Please refer to Controlling randomness.

1.2.21 Why do categorical variables need preprocessing in scikit-learn, compared to other tools?

Most of scikit-learn assumes data is in NumPy arrays or SciPy sparse matrices of a single numeric dtype. These do not explicitly represent categorical variables at present. Thus, unlike R’s data.frames or pandas.DataFrame, we require explicit conversion of categorical features to numeric values, as discussed in Encoding categorical features. See also Column Transformer with Mixed Types for an example of working with heterogeneous (e.g. categorical and numeric) data.

1.2.22 Why does Scikit-learn not directly work with, for example, pandas.DataFrame?

The homogeneous NumPy and SciPy data objects currently expected are most efficient to process for most operations. Extensive work would also be needed to support Pandas categorical types. Restricting input to homogeneous types therefore reduces maintenance cost and encourages usage of efficient data structures.

1.2.23 Do you plan to implement transform for target y in a pipeline?

Currently transform only works for features X in a pipeline. There’s a long-standing discussion about not being able to transform y in a pipeline. Follow on github issue #4143. Meanwhile check out TransformedTargetRegressor, pipegraph, imbalanced-learn. Note that Scikit-learn solved for the case where y has an invertible transformation applied before training and inverted after prediction. Scikit-learn intends to solve for use cases where y should be transformed at training time and not at test time, for resampling and similar uses, like at imbalanced learn. In general, these use cases can be solved with a custom meta estimator rather than a Pipeline

1.3 Support

There are several ways to get in touch with the developers.

1.3.1 Mailing List

- The main mailing list is scikit-learn.
- There is also a commit list scikit-learn-commits, where updates to the main repository and test failures get notified.
1.3.2 User questions

- Some scikit-learn developers support users on StackOverflow using the [scikit-learn] tag.
- For general theoretical or methodological Machine Learning questions stack exchange is probably a more suitable venue.

In both cases please use a descriptive question in the title field (e.g. no “Please help with scikit-learn!” as this is not a question) and put details on what you tried to achieve, what were the expected results and what you observed instead in the details field.

Code and data snippets are welcome. Minimalistic (up to ~20 lines long) reproduction script very helpful.

Please describe the nature of your data and how you preprocessed it: what is the number of samples, what is the number and type of features (i.e. categorical or numerical) and for supervised learning tasks, what target are you trying to predict: binary, multiclass (1 out of $n_{classes}$) or multilabel ($k$ out of $n_{classes}$) classification or continuous variable regression.

User questions should not be asked on the bug tracker, as it crowds the list of issues and makes the development of the project harder.

1.3.3 Bug tracker

If you think you’ve encountered a bug, please report it to the issue tracker:

https://github.com/scikit-learn/scikit-learn/issues

Don’t forget to include:

- steps (or better script) to reproduce,
- expected outcome,
- observed outcome or Python (or gdb) tracebacks

To help developers fix your bug faster, please link to a https://gist.github.com holding a standalone minimalistic python script that reproduces your bug and optionally a minimalistic subsample of your dataset (for instance, exported as CSV files using numpy.savetxt).

Note: Gists are Git cloneable repositories and thus you can use Git to push datafiles to them.

Gitter ===

Some developers like to hang out on scikit-learn Gitter room: https://gitter.im/scikit-learn/scikit-learn.

1.3.4 Documentation resources

This documentation is relative to 0.24.0. Documentation for other versions can be found here.

Printable pdf documentation for old versions can be found here.
1.4 Related Projects

Projects implementing the scikit-learn estimator API are encouraged to use the scikit-learn-contrib template which facilitates best practices for testing and documenting estimators. The scikit-learn-contrib GitHub organisation also accepts high-quality contributions of repositories conforming to this template.

Below is a list of sister-projects, extensions and domain specific packages.

1.4.1 Interoperability and framework enhancements

These tools adapt scikit-learn for use with other technologies or otherwise enhance the functionality of scikit-learn’s estimators.

Data formats

- **Fast svmlight / libsvm file loader** Fast and memory-efficient svmlight / libsvm file loader for Python.
- **sklearn_pandas** bridge for scikit-learn pipelines and pandas data frame with dedicated transformers.
- **sklearn_xarray** provides compatibility of scikit-learn estimators with xarray data structures.

Auto-ML

- **auto-sklearn** An automated machine learning toolkit and a drop-in replacement for a scikit-learn estimator
- **autoviml** Automatically Build Multiple Machine Learning Models with a Single Line of Code. Designed as a faster way to use scikit-learn models without having to preprocess data.
- **TPOT** An automated machine learning toolkit that optimizes a series of scikit-learn operators to design a machine learning pipeline, including data and feature preprocessors as well as the estimators. Works as a drop-in replacement for a scikit-learn estimator.
- **Featuretools** A framework to perform automated feature engineering. It can be used for transforming temporal and relational datasets into feature matrices for machine learning.
- **Neuraxle** A library for building neat pipelines, providing the right abstractions to both ease research, development, and deployment of machine learning applications. Compatible with deep learning frameworks and scikit-learn API, it can stream minibatches, use data checkpoints, build funky pipelines, and serialize models with custom per-step savers.

Experimentation frameworks

- **REP** Environment for conducting data-driven research in a consistent and reproducible way
- **Scikit-Learn Laboratory** A command-line wrapper around scikit-learn that makes it easy to run machine learning experiments with multiple learners and large feature sets.

Model inspection and visualisation

- **dtreeviz** A python library for decision tree visualization and model interpretation.
- **eli5** A library for debugging/inspecting machine learning models and explaining their predictions.
- **mlxtend** Includes model visualization utilities.
- **yellowbrick** A suite of custom matplotlib visualizers for scikit-learn estimators to support visual feature analysis, model selection, evaluation, and diagnostics.

Model selection

- **scikit-optimize** A library to minimize (very) expensive and noisy black-box functions. It implements several methods for sequential model-based optimization, and includes a replacement for GridSearchCV or RandomizedSearchCV to do cross-validated parameter search using any of these strategies.
Model export for production
- onnxtools Serializes many Scikit-learn pipelines to ONNX for interchange and prediction.
- sklearn2pmml Serialization of a wide variety of scikit-learn estimators and transformers into PMML with the help of JPMML-SkLearn library.
- sklearn-porter Transpile trained scikit-learn models to C, Java, Javascript and others.
- treelite Compiles tree-based ensemble models into C code for minimizing prediction latency.

1.4.2 Other estimators and tasks

Not everything belongs or is mature enough for the central scikit-learn project. The following are projects providing interfaces similar to scikit-learn for additional learning algorithms, infrastructures and tasks.

Structured learning
- tslearn A machine learning library for time series that offers tools for pre-processing and feature extraction as well as dedicated models for clustering, classification and regression.
- sktime A scikit-learn compatible toolbox for machine learning with time series including time series classification/regression and (supervised/panel) forecasting.
- HMMLearn Implementation of hidden markov models that was previously part of scikit-learn.
- PyStruct General conditional random fields and structured prediction.
- pomegranate Probabilistic modelling for Python, with an emphasis on hidden Markov models.
- sklearn-crfsuite Linear-chain conditional random fields (CRFsuite wrapper with sklearn-like API).

Deep neural networks etc.
- nolearn A number of wrappers and abstractions around existing neural network libraries
- keras Deep Learning library capable of running on top of either TensorFlow or Theano.
- lasagne A lightweight library to build and train neural networks in Theano.
- skorch A scikit-learn compatible neural network library that wraps PyTorch.

Broad scope
- mlxtend Includes a number of additional estimators as well as model visualization utilities.
- scikit-lego A number of scikit-learn compatible custom transformers, models and metrics, focusing on solving practical industry tasks.

Other regression and classification
- xgboost Optimised gradient boosted decision tree library.
- ML-Ensemble Generalized ensemble learning (stacking, blending, subsemble, deep ensembles, etc.).
- lightning Fast state-of-the-art linear model solvers (SDCA, AdaGrad, SVRG, SAG, etc…).
- py-earth Multivariate adaptive regression splines
- Kernel Regression Implementation of Nadaraya-Watson kernel regression with automatic bandwidth selection
- gplearn Genetic Programming for symbolic regression tasks.
- scikit-multilearn Multi-label classification with focus on label space manipulation.
- seglearn Time series and sequence learning using sliding window segmentation.

1.4. Related Projects
• **libOPF** Optimal path forest classifier
• **fastFM** Fast factorization machine implementation compatible with scikit-learn

**Decomposition and clustering**

• **lda**: Fast implementation of latent Dirichlet allocation in Cython which uses Gibbs sampling to sample from the true posterior distribution. (scikit-learn’s `LatentDirichletAllocation` implementation uses variational inference to sample from a tractable approximation of a topic model’s posterior distribution.)
• **kmodes** k-modes clustering algorithm for categorical data, and several of its variations.
• **hdbscan** HDBSCAN and Robust Single Linkage clustering algorithms for robust variable density clustering.
• **spherecluster** Spherical K-means and mixture of von Mises Fisher clustering routines for data on the unit hypersphere.

**Pre-processing**

• **categorical-encoding** A library of sklearn compatible categorical variable encoders.
• **imbalanced-learn** Various methods to under- and over-sample datasets.
• **Feature-engine** A library of sklearn compatible transformers for missing data imputation, categorical encoding, variable transformation, discretization, outlier handling and more. Feature-engine allows the application of preprocessing steps to selected groups of variables and it is fully compatible with the Scikit-learn Pipeline.

**Topological Data Analysis**

• **giotto-tda** A library for Topological Data Analysis aiming to provide a scikit-learn compatible API. It offers tools to transform data inputs (point clouds, graphs, time series, images) into forms suitable for computations of topological summaries, and components dedicated to extracting sets of scalar features of topological origin, which can be used alongside other feature extraction methods in scikit-learn.

### 1.4.3 Statistical learning with Python

Other packages useful for data analysis and machine learning.

• **Pandas** Tools for working with heterogeneous and columnar data, relational queries, time series and basic statistics.
• **statsmodels** Estimating and analysing statistical models. More focused on statistical tests and less on prediction than scikit-learn.
• **PyMC** Bayesian statistical models and fitting algorithms.
• **Sacred** Tool to help you configure, organize, log and reproduce experiments
• **Seaborn** Visualization library based on matplotlib. It provides a high-level interface for drawing attractive statistical graphics.
Recommendation Engine packages

- implicit, Library for implicit feedback datasets.
- lightfm A Python/Cython implementation of a hybrid recommender system.
- OpenRec TensorFlow-based neural-network inspired recommendation algorithms.
- Spotlight Pytorch-based implementation of deep recommender models.
- Surprise Lib Library for explicit feedback datasets.

Domain specific packages

- scikit-image Image processing and computer vision in python.
- Natural language toolkit (nltk) Natural language processing and some machine learning.
- gensim A library for topic modelling, document indexing and similarity retrieval
- NiLearn Machine learning for neuro-imaging.
- AstroML Machine learning for astronomy.
- MSMBuilder Machine learning for protein conformational dynamics time series.

1.5 About us

1.5.1 History

This project was started in 2007 as a Google Summer of Code project by David Cournapeau. Later that year, Matthieu Brucher started work on this project as part of his thesis.

In 2010 Fabian Pedregosa, Gael Varoquaux, Alexandre Gramfort and Vincent Michel of INRIA took leadership of the project and made the first public release, February the 1st 2010. Since then, several releases have appeared following a ~ 3-month cycle, and a thriving international community has been leading the development.

1.5.2 Governance

The decision making process and governance structure of scikit-learn is laid out in the governance document.

1.5.3 Authors

The following people are currently core contributors to scikit-learn’s development and maintenance:

Please do not email the authors directly to ask for assistance or report issues. Instead, please see What’s the best way to ask questions about scikit-learn in the FAQ.

See also:

How you can contribute to the project
1.5.4 Triage Team

The following people are active contributors who also help with triaging issues, PRs, and general maintenance:

1.5.5 Emeritus Core Developers

The following people have been active contributors in the past, but are no longer active in the project:

• Mathieu Blondel
• Matthieu Brucher
• Lars Buitinck
• David Cournapeau
• Noel Dawe
• Shiqiao Du
• Vincent Dubourg
• Edouard Duchesnay
• Alexander Fabisch
• Virgile Fritsch
• Satrajit Ghosh
• Angel Soler Gollonet
• Chris Gorgolewski
• Jaques Grobler
• Brian Holt
• Arnaud Joly
• Thouis (Ray) Jones
• Kyle Kastner
• manoj kumar
• Robert Layton
• Wei Li
• Paolo Losi
• Gilles Louppe
• Vincent Michel
• Jarrod Millman
• Alexandre Passos
• Fabian Pedregosa
• Peter Prettenhofer
• (Venkat) Raghav, Rajagopalan
• Jacob Schreiber
1.5.6 Citing scikit-learn

If you use scikit-learn in a scientific publication, we would appreciate citations to the following paper:


Bibtex entry:

```
@article{scikit-learn,
  title={Scikit-learn: Machine Learning in {P}ython},
  journal={Journal of Machine Learning Research},
  volume={12},
  pages={2825--2830},
  year={2011}
}
```

If you want to cite scikit-learn for its API or design, you may also want to consider the following paper:

API design for machine learning software: experiences from the scikit-learn project, Buitinck et al., 2013.

Bibtex entry:

```
@inproceedings{sklearn_api,
  author = {Lars Buitinck and Gilles Louppe and Mathieu Blondel and Fabian Pedregosa and Andreas Mueller and Olivier Grisel and Vlad Niculae and Peter Prettenhofer and Alexandre Gramfort and Jaques Grobler and Robert Layton and Jake VanderPlas and Arnaud Joly and Brian Holt and Ga\"{e}l Varoquaux},
  title = {{API} design for machine learning software: experiences from the scikit-learn project},
  booktitle = {ECML PKDD Workshop: Languages for Data Mining and Machine Learning},
  year = {2013},
  pages = {108--122},
}
```
1.5.7 Artwork

High quality PNG and SVG logos are available in the `doc/logos/` source directory.

1.5.8 Funding

Scikit-Learn is a community driven project, however institutional and private grants help to assure its sustainability. The project would like to thank the following funders.

The Members of the Scikit-Learn Consortium at Inria Foundation fund Olivier Grisel, Guillaume Lemaitre, Jérémie du Boisberranger and Chiara Marmo.

Columbia University funds Andreas Müller since 2016
Andreas Müller received a grant to improve scikit-learn from the Alfred P. Sloan Foundation. This grant supports the position of Nicolas Hug and Thomas J. Fan.

The University of Sydney funds Joel Nothman since July 2017.

Zalando SE funds Adrin Jalali since August 2020.

Past Sponsors

INRIA actively supports this project. It has provided funding for Fabian Pedregosa (2010-2012), Jaques Grobler (2012-2013) and Olivier Grisel (2013-2017) to work on this project full-time. It also hosts coding sprints and other events.

Paris-Saclay Center for Data Science funded one year for a developer to work on the project full-time (2014-2015), 50% of the time of Guillaume Lemaitre (2016-2017) and 50% of the time of Joris van den Bossche (2017-2018).

Anaconda, Inc funded Adrin Jalali in 2019.

NYU Moore-Sloan Data Science Environment funded Andreas Mueller (2014-2016) to work on this project. The Moore-Sloan Data Science Environment also funds several students to work on the project part-time.


The following students were sponsored by Google to work on scikit-learn through the Google Summer of Code program.

- 2007 - David Cournapeau
- 2011 - Vlad Niculae
- 2012 - Vlad Niculae, Immanuel Bayer.
- 2013 - Kemal Eren, Nicolas Trésegnie
- 2014 - Hamzeh Alsalhi, Issam Laradji, Maheshakya Wijewardena, Manoj Kumar.
- 2015 - Raghav RV, Wei Xue
- 2016 - Nelson Liu, YenChen Lin

The NeuroDebian project providing Debian packaging and contributions is supported by Dr. James V. Haxby (Dartmouth College).

### 1.5.9 Sprints

The International 2019 Paris sprint was kindly hosted by AXA. Also some participants could attend thanks to the support of the Alfred P. Sloan Foundation, the Python Software Foundation (PSF) and the DATAIA Institute.

The 2013 International Paris Sprint was made possible thanks to the support of Télécom Paristech, tinyclues, the French Python Association and the Fonds de la Recherche Scientifique.

The 2011 International Granada sprint was made possible thanks to the support of the PSF and tinyclues.
Donating to the project

If you are interested in donating to the project or to one of our code-sprints, you can use the *Paypal* button below or the NumFOCUS Donations Page (if you use the latter, please indicate that you are donating for the scikit-learn project).

All donations will be handled by NumFOCUS, a non-profit-organization which is managed by a board of Scipy community members. NumFOCUS’s mission is to foster scientific computing software, in particular in Python. As a fiscal home of scikit-learn, it ensures that money is available when needed to keep the project funded and available while in compliance with tax regulations.

The received donations for the scikit-learn project mostly will go towards covering travel-expenses for code sprints, as well as towards the organization budget of the project\(^1\).

**Notes**

1.5.10 Infrastructure support

- We would also like to thank Microsoft Azure, Travis CI, CircleCI for free CPU time on their Continuous Integration servers, and Anaconda Inc. for the storage they provide for our staging and nightly builds.

### 1.6 Who is using scikit-learn?

1.6.1 J.P.Morgan

Scikit-learn is an indispensable part of the Python machine learning toolkit at JPMorgan. It is very widely used across all parts of the bank for classification, predictive analytics, and very many other machine learning tasks. Its straightforward API, its breadth of algorithms, and the quality of its documentation combine to make scikit-learn simultaneously very approachable and very powerful.

Stephen Simmons, VP, Athena Research, JPMorgan

**J.P.Morgan**

1.6.2 Spotify

Scikit-learn provides a toolbox with solid implementations of a bunch of state-of-the-art models and makes it easy to plug them into existing applications. We’ve been using it quite a lot for music recommendations at Spotify and I think it’s the most well-designed ML package I’ve seen so far.

Erik Bernhardsson, Engineering Manager Music Discovery & Machine Learning, Spotify

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1 Regarding the organization budget, in particular, we might use some of the donated funds to pay for other project expenses such as DNS, hosting or continuous integration services.
1.6.3 Inria

At INRIA, we use scikit-learn to support leading-edge basic research in many teams: Parietal for neuroimaging, Lear for computer vision, Visages for medical image analysis, Privatics for security. The project is a fantastic tool to address difficult applications of machine learning in an academic environment as it is performant and versatile, but all easy-to-use and well documented, which makes it well suited to grad students.

Gaël Varoquaux, research at Parietal

1.6.4 betaworks

Betaworks is a NYC-based startup studio that builds new products, grows companies, and invests in others. Over the past 8 years we’ve launched a handful of social data analytics-driven services, such as Bitly, Chartbeat, digg and Scale Model. Consistently the betaworks data science team uses Scikit-learn for a variety of tasks. From exploratory analysis, to product development, it is an essential part of our toolkit. Recent uses are included in digg’s new video recommender system, and Poncho’s dynamic heuristic subspace clustering.

Gilad Lotan, Chief Data Scientist

1.6.5 Hugging Face

At Hugging Face we’re using NLP and probabilistic models to generate conversational Artificial intelligences that are fun to chat with. Despite using deep neural nets for a few of our NLP tasks, scikit-learn is still the bread-and-butter of our daily machine learning routine. The ease of use and predictability of the interface, as well as the straightforward mathematical explanations that are here when you need them, is the killer feature. We use a variety of scikit-learn models in production and they are also operationally very pleasant to work with.

Julien Chaumond, Chief Technology Officer
1.6.6 Evernote

Building a classifier is typically an iterative process of exploring the data, selecting the features (the attributes of the data believed to be predictive in some way), training the models, and finally evaluating them. For many of these tasks, we relied on the excellent scikit-learn package for Python.

Read more

Mark Ayzenshtat, VP, Augmented Intelligence

1.6.7 Télécom ParisTech

At Telecom ParisTech, scikit-learn is used for hands-on sessions and home assignments in introductory and advanced machine learning courses. The classes are for undergrads and masters students. The great benefit of scikit-learn is its fast learning curve that allows students to quickly start working on interesting and motivating problems.

Alexandre Gramfort, Assistant Professor
1.6.8 Booking.com

At Booking.com, we use machine learning algorithms for many different applications, such as recommending hotels and destinations to our customers, detecting fraudulent reservations, or scheduling our customer service agents. Scikit-learn is one of the tools we use when implementing standard algorithms for prediction tasks. Its API and documentations are excellent and make it easy to use. The scikit-learn developers do a great job of incorporating state of the art implementations and new algorithms into the package. Thus, scikit-learn provides convenient access to a wide spectrum of algorithms, and allows us to readily find the right tool for the right job.

Melanie Mueller, Data Scientist

1.6.9 AWeber

The scikit-learn toolkit is indispensable for the Data Analysis and Management team at AWeber. It allows us to do AWesome stuff we would not otherwise have the time or resources to accomplish. The documentation is excellent, allowing new engineers to quickly evaluate and apply many different algorithms to our data. The text feature extraction utilities are useful when working with the large volume of email content we have at AWeber. The RandomizedPCA implementation, along with Pipelining and FeatureUnions, allows us to develop complex machine learning algorithms efficiently and reliably.

Anyone interested in learning more about how AWeber deploys scikit-learn in a production environment should check out talks from PyData Boston by AWeber’s Michael Becker available at https://github.com/mdbecker/pydata_2013

Michael Becker, Software Engineer, Data Analysis and Management Ninjas

1.6.10 Yhat

The combination of consistent APIs, thorough documentation, and top notch implementation make scikit-learn our favorite machine learning package in Python. scikit-learn makes doing advanced analysis in Python accessible to anyone. At Yhat, we make it easy to integrate these models into your production applications. Thus eliminating the unnecessary dev time encountered productionizing analytical work.

Greg Lamp, Co-founder Yhat
1.6.11 Rangespan

The Python scikit-learn toolkit is a core tool in the data science group at Rangespan. Its large collection of well documented models and algorithms allow our team of data scientists to prototype fast and quickly iterate to find the right solution to our learning problems. We find that scikit-learn is not only the right tool for prototyping, but its careful and well tested implementation give us the confidence to run scikit-learn models in production.

Jurgen Van Gael, Data Science Director at Rangespan Ltd

1.6.12 Birchbox

At Birchbox, we face a range of machine learning problems typical to E-commerce: product recommendation, user clustering, inventory prediction, trends detection, etc. Scikit-learn lets us experiment with many models, especially in the exploration phase of a new project: the data can be passed around in a consistent way; models are easy to save and reuse; updates keep us informed of new developments from the pattern discovery research community. Scikit-learn is an important tool for our team, built the right way in the right language.

Thierry Bertin-Mahieux, Birchbox, Data Scientist

1.6.13 Bestofmedia Group

Scikit-learn is our #1 toolkit for all things machine learning at Bestofmedia. We use it for a variety of tasks (e.g. spam fighting, ad click prediction, various ranking models) thanks to the varied, state-of-the-art algorithm implementations packaged into it. In the lab it accelerates prototyping of complex pipelines. In production I can say it has proven to be robust and efficient enough to be deployed for business critical components.

Eustache Diemert, Lead Scientist Bestofmedia Group
1.6.14 Change.org

At change.org we automate the use of scikit-learn’s RandomForestClassifier in our production systems to drive email targeting that reaches millions of users across the world each week. In the lab, scikit-learn’s ease-of-use, performance, and overall variety of algorithms implemented has proved invaluable in giving us a single reliable source to turn to for our machine-learning needs.

Vijay Ramesh, Software Engineer in Data/science at Change.org

1.6.15 PHIMECA Engineering

At PHIMECA Engineering, we use scikit-learn estimators as surrogates for expensive-to-evaluate numerical models (mostly but not exclusively finite-element mechanical models) for speeding up the intensive post-processing operations involved in our simulation-based decision making framework. Scikit-learn’s fit/predict API together with its efficient cross-validation tools considerably eases the task of selecting the best-fit estimator. We are also using scikit-learn for illustrating concepts in our training sessions. Trainees are always impressed by the ease-of-use of scikit-learn despite the apparent theoretical complexity of machine learning.

Vincent Dubourg, PHIMECA Engineering, PhD Engineer

1.6.16 HowAboutWe

At HowAboutWe, scikit-learn lets us implement a wide array of machine learning techniques in analysis and in production, despite having a small team. We use scikit-learn’s classification algorithms to predict user behavior, enabling us to (for example) estimate the value of leads from a given traffic source early in the lead’s tenure on our site. Also, our users’ profiles consist of primarily unstructured data (answers to open-ended questions), so we use scikit-learn’s feature extraction and dimensionality reduction tools to translate these unstructured data into inputs for our matchmaking system.

Daniel Weitzenfeld, Senior Data Scientist at HowAboutWe
1.6.17 PeerIndex

At PeerIndex we use scientific methodology to build the Influence Graph - a unique dataset that allows us to identify who’s really influential and in which context. To do this, we have to tackle a range of machine learning and predictive modeling problems. Scikit-learn has emerged as our primary tool for developing prototypes and making quick progress. From predicting missing data and classifying tweets to clustering communities of social media users, scikit-learn proved useful in a variety of applications. Its very intuitive interface and excellent compatibility with other python tools makes it an indispensable tool in our daily research efforts.

Ferenc Huszar - Senior Data Scientist at Peerindex

1.6.18 DataRobot

DataRobot is building next generation predictive analytics software to make data scientists more productive, and scikit-learn is an integral part of our system. The variety of machine learning techniques in combination with the solid implementations that scikit-learn offers makes it a one-stop-shopping library for machine learning in Python. Moreover, its consistent API, well-tested code and permissive licensing allow us to use it in a production environment. Scikit-learn has literally saved us years of work we would have had to do ourselves to bring our product to market.

Jeremy Achin, CEO & Co-founder DataRobot Inc.

1.6.19 OkCupid

We’re using scikit-learn at OkCupid to evaluate and improve our matchmaking system. The range of features it has, especially preprocessing utilities, means we can use it for a wide variety of projects, and it’s performant enough to handle the volume of data that we need to sort through. The documentation is really thorough, as well, which makes the library quite easy to use.

David Koh - Senior Data Scientist at OkCupid
1.6.20 Lovely

At Lovely, we strive to deliver the best apartment marketplace, with respect to our users and our listings. From understanding user behavior, improving data quality, and detecting fraud, scikit-learn is a regular tool for gathering insights, predictive modeling and improving our product. The easy-to-read documentation and intuitive architecture of the API makes machine learning both explorable and accessible to a wide range of python developers. I’m constantly recommending that more developers and scientists try scikit-learn.

Simon Frid - Data Scientist, Lead at Lovely

1.6.21 Data Publica

Data Publica builds a new predictive sales tool for commercial and marketing teams called C-Radar. We extensively use scikit-learn to build segmentations of customers through clustering, and to predict future customers based on past partnerships success or failure. We also categorize companies using their website communication thanks to scikit-learn and its machine learning algorithm implementations. Eventually, machine learning makes it possible to detect weak signals that traditional tools cannot see. All these complex tasks are performed in an easy and straightforward way thanks to the great quality of the scikit-learn framework.

Guillaume Lebourgeois & Samuel Charron - Data Scientists at Data Publica

1.6.22 Machinalis

Scikit-learn is the cornerstone of all the machine learning projects carried at Machinalis. It has a consistent API, a wide selection of algorithms and lots of auxiliary tools to deal with the boilerplate. We have used it in production environments on a variety of projects including click-through rate prediction, information extraction, and even counting sheep!

In fact, we use it so much that we’ve started to freeze our common use cases into Python packages, some of them open-sourced, like FeatureForge. Scikit-learn in one word: Awesome.

Rafael Carrascosa, Lead developer
1.6.23 solido

Scikit-learn is helping to drive Moore’s Law, via Solido. Solido creates computer-aided design tools used by the majority of top-20 semiconductor companies and fabs, to design the bleeding-edge chips inside smartphones, automobiles, and more. Scikit-learn helps to power Solido’s algorithms for rare-event estimation, worst-case verification, optimization, and more. At Solido, we are particularly fond of scikit-learn’s libraries for Gaussian Process models, large-scale regularized linear regression, and classification. Scikit-learn has increased our productivity, because for many ML problems we no longer need to “roll our own” code. This PyData 2014 talk has details.

Trent McConaghy, founder, Solido Design Automation Inc.

1.6.24 INFONEA

We employ scikit-learn for rapid prototyping and custom-made Data Science solutions within our in-memory based Business Intelligence Software INFONEA®. As a well-documented and comprehensive collection of state-of-the-art algorithms and pipelining methods, scikit-learn enables us to provide flexible and scalable scientific analysis solutions. Thus, scikit-learn is immensely valuable in realizing a powerful integration of Data Science technology within self-service business analytics.

Thorsten Kranz, Data Scientist, Coma Soft AG.

1.6.25 Dataiku

Our software, Data Science Studio (DSS), enables users to create data services that combine ETL with Machine Learning. Our Machine Learning module integrates many scikit-learn algorithms. The scikit-learn library is a perfect integration with DSS because it offers algorithms for virtually all business cases. Our goal is to offer a transparent and flexible tool that makes it easier to optimize time consuming aspects of building a data service, preparing data, and training machine learning algorithms on all types of data.

Florian Douetteau, CEO, Dataiku

1.6.26 Otto Group

Here at Otto Group, one of global Big Five B2C online retailers, we are using scikit-learn in all aspects of our daily work from data exploration to development of machine learning application to the productive deployment of those services. It helps us to tackle machine learning problems ranging from e-commerce to logistics. It consistent APIs enabled us to build the Palladium REST-API framework around it and continuously deliver scikit-learn based services.

Christian Rammig, Head of Data Science, Otto Group
1.6.27 Zopa

At Zopa, the first ever Peer-to-Peer lending platform, we extensively use scikit-learn to run the business and optimize our users’ experience. It powers our Machine Learning models involved in credit risk, fraud risk, marketing, and pricing, and has been used for originating at least 1 billion GBP worth of Zopa loans. It is very well documented, powerful, and simple to use. We are grateful for the capabilities it has provided, and for allowing us to deliver on our mission of making money simple and fair.

Vlasios Vasileiou, Head of Data Science, Zopa

1.6.28 MARS

Scikit-Learn is integral to the Machine Learning Ecosystem at Mars. Whether we’re designing better recipes for petfood or closely analysing our cocoa supply chain, Scikit-Learn is used as a tool for rapidly prototyping ideas and taking them to production. This allows us to better understand and meet the needs of our consumers worldwide. Scikit-Learn’s feature-rich toolset is easy to use and equips our associates with the capabilities they need to solve the business challenges they face every day.

Michael Fitzke Next Generation Technologies Sr Leader, Mars Inc.

1.7 Release History

Release notes for all scikit-learn releases are linked in this page.

Tip: Subscribe to scikit-learn releases on libraries.io to be notified when new versions are released.

1.7.1 Version 0.24.0

December 2020

For a short description of the main highlights of the release, please refer to Release Highlights for scikit-learn 0.24.

Legend for changelogs

- [MAJOR FEATURE]: something big that you couldn’t do before.
- [FEATURE]: something that you couldn’t do before.
- [EFFICIENCY]: an existing feature now may not require as much computation or memory.
- [ENHANCEMENT]: a miscellaneous minor improvement.
- [FIX]: something that previously didn’t work as documented – or according to reasonable expectations – should now work.
• [API CHANGEd]: you will need to change your code to have the same effect in the future; or a feature will be removed in the future.

Put the changes in their relevant module.

**Changed models**

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

  - [Fix] `decomposition.KernelPCA` behaviour is now more consistent between 32-bits and 64-bits data when the kernel has small positive eigenvalues.
  - [Fix] `decomposition.TruncatedSVD` becomes deterministic by exposing a `random_state` parameter.
  - [Fix] `linear_model.Perceptron` when `penalty='elasticnet'`.

Details are listed in the changelog below.

(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)

**Changelog**

**sklearn.base**

  - [Fix] `base.BaseEstimator.get_params` now will raise an `AttributeError` if a parameter cannot be retrieved as an instance attribute. Previously it would return `None`. #17448 by Juan Carlos Alfaro Jiménez.

**sklearn_calibration**

  - [ENHANCEMENT] Allow `calibration.CalibratedClassifierCV` use with prefit `pipeline.Pipeline` where data is not X is not array-like, sparse matrix or dataframe at the start. #17546 by Lucy Liu.
  - [ENHANCEMENT] Add `ensemble` parameter to `calibration.CalibratedClassifierCV`, which enables implementation of calibration via an ensemble of calibrators (current method) or just one calibrator using all the data (similar to the built-in feature of `sklearn.svm` estimators with the `probabilities=True` parameter). #17856 by Lucy Liu and Andrea Esuli.

**sklearn.cluster**

  - [ENHANCEMENT] `cluster.AgglomerativeClustering` has a new parameter `compute_distances`. When set to `True`, distances between clusters are computed and stored in the `distances_` attribute even when the parameter `distance_threshold` is not used. This new parameter is useful to produce dendrogram visualizations, but introduces a computational and memory overhead. #17984 by Michael Riedmann, Emilie Delattre, and Francesco Casalegno.
  - [ENHANCEMENT] `cluster.SpectralClustering` and `cluster.spectral_clustering` have a new keyword argument `verbose`. When set to `True`, additional messages will be displayed which can aid with debugging. #18052 by Sean O. Stalley.
scikit-learn user guide, Release 0.24.0

- **[Enhancement]** Added `cluster.kmeans_plusplus` as public function. Initialization by KMeans++ can now be called separately to generate initial cluster centroids. #17937 by @g-walsh

- **[API Change]** `cluster.MiniBatchKMeans` attributes, `counts_` and `init_size_`, are deprecated and will be removed in 1.1 (renaming of 0.26). #17864 by Jérémie du Boisberranger.

**sklearn.compose**

- **[Fix]** `compose.ColumnTransformer` will skip transformers the column selector is a list of bools that are False. #17616 by Thomas Fan.

- **[Fix]** `compose.ColumnTransformer` now displays the remainder in the diagram display. #18167 by Thomas Fan.

- **[Fix]** `compose.ColumnTransformer` enforces strict count and order of column names between `fit` and `transform` by raising an error instead of a warning, following the deprecation cycle. #18256 by Madhura Jayratne.

**sklearn.covariance**

- **[API Change]** Deprecates `cv_alphas_` in favor of `cv_results_['alphas']` and `grid_scores_` in favor of split scores in `cv_results_` in `covariance.GraphicalLassoCV`. `cv_alphas_` and `grid_scores_` will be removed in version 1.1 (renaming of 0.26). #16392 by Thomas Fan.

**sklearn.cross_decomposition**

- **[Fix]** Fixed a bug in `cross_decomposition.PLSSVD` which would sometimes return components in the reversed order of importance. #17095 by Nicolas Hug.

- **[Fix]** Fixed a bug in `cross_decomposition.PLSSVD`, `cross_decomposition.CCA`, and `cross_decomposition.PLSCanonical`, which would lead to incorrect predictions for `est.transform(Y)` when the training data is single-target. #17095 by Nicolas Hug.

- **[Fix]** Increases the stability of `cross_decomposition.CCA` #18746 by Thomas Fan.

- **[API Change]** For `cross_decomposition.NMF`, the `init` value, when `init=None` and `n_components <= min(n_samples, n_features)` will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26). #18525 by Chiara Marmo.

- **[API Change]** The bounds of the `n_components` parameter is now restricted:
  - into `[1, min(n_samples, n_features, n_targets)]`, for `cross_decomposition.PLSSVD`, `cross_decomposition.CCA`, and `cross_decomposition.PLSCanonical`.
  - into `[1, n_features]` or `cross_decomposition.PLSRegression.`

  An error will be raised in 1.1 (renaming of 0.26). #17095 by Nicolas Hug.

- **[API Change]** For `cross_decomposition.PLSSVD`, `cross_decomposition.CCA`, and `cross_decomposition.PLSCanonical`, the `x_scores_` and `y_scores_` attributes were deprecated and will be removed in 1.1 (renaming of 0.26). They can be retrieved by calling `transform` on the training data. The `norm_y_weights` attribute will also be removed. #18768 by Maren Westermann.
• [Fix] `decomposition.TruncatedSVD` becomes deterministic by using the random_state. It controls the weights' initialization of the underlying ARPACK solver. :pr:` #18302` by Gaurav Desai and Ivan Panico.

**sklearn.datasets**

• [Feature] `datasets.fetch_openml` now validates md5 checksum of arff files downloaded or cached to ensure data integrity. #14800 by Shashank Singh and Joel Nothman.

• [Feature] `datasets.fetch_openml` now validates md5 checksum of arff files downloaded or cached to ensure data integrity. #14800 by Shashank Singh and Joel Nothman.

• [Enhancement] `datasets.fetch_openml` now allows argument as_frame to be ‘auto’, which tries to convert returned data to pandas DataFrame unless data is sparse. #17396 by Jiaxiang.

• [Enhancement] `datasets.fetch_covtype` now now supports the optional argument as_frame; when it is set to True, the returned Bunch object’s data and frame members are pandas DataFrames, and the target member is a pandas Series. #17491 by Alex Liang.

• [Enhancement] `datasets.fetch_kddcup99` now now supports the optional argument as_frame; when it is set to True, the returned Bunch object’s data and frame members are pandas DataFrames, and the target member is a pandas Series. #18280 by Alex Liang and Guillaume Lemaitre.

• [Enhancement] `datasets.fetch_20newsgroups_vectorized` now supports loading as a pandas DataFrame by setting as_frame=True. #17499 by Brigitta Sipócz and Guillaume Lemaitre.

• [API Change] The default value of as_frame in `datasets.fetch_openml` is changed from False to ‘auto’. #17610 by Jiaxiang.

**sklearn.decomposition**

• [Enhancement] `decomposition.FactorAnalysis` now supports the optional argument rotation, which can take the value None, ‘varimax’ or ‘quartimax’. #11064 by Jona Sassenhagen.

• [Enhancement] `decomposition.NMF` now supports the optional parameter regularization, which can take the values None, ‘components’, ‘transformation’ or ‘both’, in accordance with `decomposition.NMF.non_negative_factorization`. #17414 by Bharat Raghunathan.

• [Fix] `decomposition.KernelPCA` behaviour is now more consistent between 32-bits and 64-bits data input when the kernel has small positive eigenvalues. Small positive eigenvalues were not correctly discarded for 32-bits data. #18149 by Sylvain Marié.

• [Fix] Fix `decomposition.SparseCoder` such that it follows scikit-learn API and support cloning. The attribute components_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). This attribute was redundant with the dictionary attribute and constructor parameter. #17679 by Xavier Dupré.

• [Fix] `TruncatedSVD.fit_transform` consistently returns the same as `TruncatedSVD.fit` followed by `TruncatedSVD.transform`. #18528 by Albert Villanova del Moral and Ruifeng Zheng.
sklearn.discriminant_analysis

- [Enhancement] `discriminant_analysis.LinearDiscriminantAnalysis` can now use custom covariance estimate by setting the `covariance_estimator` parameter. #14446 by Hugo Richard.

sklearn.ensemble

- [Major Feature] `ensemble.HistGradientBoostingRegressor` and `ensemble.HistGradientBoostingClassifier` now have native support for categorical features with the `categorical_features` parameter. #18394 by Nicolas Hug and Thomas Fan.
- [Feature] `ensemble.HistGradientBoostingRegressor` and `ensemble.HistGradientBoostingClassifier` now support the method `staged_predict`, which allows monitoring of each stage. #16985 by Hao Chun Chang.
- [Efficiency] break cyclic references in the tree nodes used internally in `ensemble.HistGradientBoostingRegressor` and `ensemble.HistGradientBoostingClassifier` to allow for the timely garbage collection of large intermediate datastructures and to improve memory usage in `fit`. #18334 by Olivier Grisel Nicolas Hug, Thomas Fan and Andreas Müller.
- [Efficiency] Histogram initialization is now done in parallel in `ensemble.HistGradientBoostingRegressor` and `ensemble.HistGradientBoostingClassifier` which results in speed improvement for problems that build a lot of nodes on multicore machines. #18341 by Olivier Grisel, Nicolas Hug, Thomas Fan, and Egor Smirnov.
- [API Change] The parameter `n_classes_` is now deprecated in `ensemble.GradientBoostingRegressor` and returns 1. #17702 by Simona Maggio.
- [API Change] Mean absolute error (‘mae’) is now deprecated for the parameter `criterion` in `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier`. #18326 by Madhura Jayaratne.

sklearn.exceptions

- [API Change] `exceptions.ChangedBehaviorWarning` and `exceptions.NonBLASDotWarning` are deprecated and will be removed in 1.1 (renaming of 0.26). #17804 by Adrin Jalali.

sklearn.feature_extraction

- [Enhancement] `feature_extraction.DictVectorizer` accepts multiple values for one categorical feature. #17367 by Peng Yu and Chiara Marmo.
- [Fix] `feature_extraction.CountVectorizer` raises an issue if a custom token pattern which capture more than one group is provided. #15427 by Gangesh Gudmalwar and Erin R Hoffman.
**sklearn.feature_selection**

- **FEATURE** Added `feature_selection.SequentialFeatureSelector` which implements forward and backward sequential feature selection. #6545 by Sebastian Raschka and #17159 by Nicolas Hug.

- **FEATURE** A new parameter `importance_getter` was added to `feature_selection.RFE`, `feature_selection.RFECV` and `feature_selection.SelectFromModel`, allowing the user to specify an attribute name/path or a callable for extracting feature importance from the estimator. #15361 by Venkatachalam N.

- **EFFICIENCY** Reduce memory footprint in `feature_selection.mutual_info_classif` and `feature_selection.mutual_info_regression` by calling `neighbors.KDTree` for counting nearest neighbors. #17878 by Noel Rogers.

- **ENHANCEMENT** `feature_selection.RFE` supports the option for the number of `n_features_to_select` to be given as a float representing the percentage of features to select. #17090 by Lisa Schwetlick and Marija Vlajic Wheeler.

**sklearn.gaussian_process**

- **ENHANCEMENT** A new method `gaussian_process.Kernel._check_bounds_params` is called after fitting a Gaussian Process and raises a `ConvergenceWarning` if the bounds of the hyperparameters are too tight. #12638 by Sylvain Lannuzel.

**sklearn.impute**

- **FEATURE** `impute.SimpleImputer` now supports a list of strings when `strategy='most_frequent'` or `strategy='constant'`. #17526 by Ayako YAGI and Juan Carlos Alfaro Jiménez.

- **FEATURE** Added method `impute.SimpleImputer.inverse_transform` to revert imputed data to original when instantiated with `add_indicator=True`. #17612 by Srimukh Sripada.

- **FIX** replace the default values in `impute.IterativeImputer` of `min_value` and `max_value` parameters to `-np.inf` and `np.inf`, respectively instead of `None`. However, the behaviour of the class does not change since `None` was defaulting to these values already. #16493 by Darshan N.

- **FIX** `impute.IterativeImputer` will not attempt to set the estimator’s `random_state` attribute, allowing to use it with more external classes. #15636 by David Cortes.

- **EFFICIENCY** `impute.SimpleImputer` is now faster with `object` dtype array. when `strategy='most_frequent'` in `SimpleImputer`. #18987 by David Katz.

**sklearn.inspection**

- **FEATURE** `inspection.partial_dependence` and `inspection.plot_partial_dependence` now support calculating and plotting Individual Conditional Expectation (ICE) curves controlled by the `kind` parameter. #16619 by Madhura Jayratne.

- **FEATURE** Add `sample_weight` parameter to `inspection.permutation_importance`. #16906 by Roei Kahny.

- **API CHANGE** Positional arguments are deprecated in `inspection.PartialDependenceDisplay.plot` and will error in 1.1 (renaming of 0.26). #18293 by Thomas Fan.
sklearn.isotonic

- **[FEATURE]** Expose fitted attributes `X_thresholds_` and `y_thresholds_` that hold the de-duplicated interpolation thresholds of an `isotonic.IsotonicRegression` instance for model inspection purpose. #16289 by Masashi Kishimoto and Olivier Grisel.

- **[ENHANCEMENT]** `isotonic.IsotonicRegression` now accepts 2d array with 1 feature as input array. #17379 by Jiaxiang.

- **[Fix]** Add tolerance when determining duplicate X values to prevent inf values from being predicted by `isotonic.IsotonicRegression`. #18639 by Lucy Liu.

sklearn.kernel_approximation

- **[FEATURE]** Added class `kernel_approximation.PolynomialCountSketch` which implements the Tensor Sketch algorithm for polynomial kernel feature map approximation. #13003 by Daniel López Sánchez.

- **[EFFICIENCY]** `kernel_approximation.Nystroem` now supports parallelization via `joblib`. Parallel using argument `n_jobs`. #18545 by Laurenz Reitsam.

sklearn.linear_model

- **[FEATURE]** `linear_model.LinearRegression` now forces coefficients to be all positive when `positive` is set to True. #17578 by Joseph Knox, Nelle Varoquaux and Chiara Marmo.

- **[ENHANCEMENT]** `linear_model.RidgeCV` now supports finding an optimal regularization value `alpha` for each target separately by setting `alpha_per_target=True`. This is only supported when using the default efficient leave-one-out cross-validation scheme `cv=None`. #6624 by Marijn van Vliet.

- **[Fix]** Fixes bug in `linear_model.TheilSenRegressor` where `predict` and `score` would fail when `fit_intercept=False` and there was one feature during fitting. #18121 by Thomas Fan.

- **[Fix]** Fixes bug in `linear_model.ARDRegression` where `predict` was raising an error when `normalize=True` and `return_std=True` because `X_offset_` and `X_scale_` were undefined. #18607 by fhaselbeck.

- **[Fix]** Added the missing `l1_ratio` parameter in `linear_model.Perceptron`, to be used when `penalty='elasticnet'`. This changes the default from 0 to 0.15. #18622 by Haesun Park.

sklearn.manifold

- **[EFFICIENCY]** Fixed #10493. Improve Local Linear Embedding (LLE) that raised `MemoryError` exception when used with large inputs. #17997 by Bertrand Maisonneuve.

- **[ENHANCEMENT]** Add `square_distances` parameter to `manifold.TSNE`, which provides backward compatibility during deprecation of legacy squaring behavior. Distances will be squared by default in 1.1 (renaming of 0.26), and this parameter will be removed in 1.3. #17662 by Joshua Newton.

- **[Fix]** `manifold.MDS` now correctly sets its `_pairwise` attribute. #18278 by Thomas Fan.
sklearn.metrics

- [FEATURE] Added metrics.cluster.pair_confusion_matrix implementing the confusion matrix arising from pairs of elements from two clusterings. #17412 by Uwe F Mayer.

- [FEATURE] New metric metrics.top_k_accuracy_score. It's a generalization of metrics.top_k_accuracy_score, the difference is that a prediction is considered correct as long as the true label is associated with one of the k highest predicted scores. accuracy_score is the special case of k = 1. #16625 by Geoffrey Bolnier.

- [FEATURE] Added metrics.det_curve to compute Detection Error Tradeoff curve classification metric. #10591 by Jeremy Karnowski and Daniel Mohns.

- [FEATURE] Added metrics.plot_det_curve and metrics.DetCurveDisplay to ease the plot of DET curves. #18176 by Guillaume Lemaire.

- [FEATURE] Added metrics.mean_absolute_percentage_error metric and the associated scorer for regression problems. #10708 fixed with the PR #15007 by Ashutosh Hathidara. The scorer and some practical test cases were taken from PR #10711 by Mohamed Ali Jamaoui.

- [FEATURE] Added metrics.rand_score implementing the (unadjusted) Rand index. #17412 by Uwe F Mayer.

- [FEATURE] metrics.plot_confusion_matrix now supports making colorbar optional in the matplotlib plot by setting colorbar=False. #17192 by Avi Gupta

- [FEATURE] metrics.plot_confusion_matrix now supports making colorbar optional in the matplotlib plot by setting colorbar=False. #17192 by Avi Gupta.

- [ENHANCEMENT] Add sample_weight parameter to metrics.median_absolute_error. #17225 by Lucy Liu.

- [ENHANCEMENT] Add pos_label parameter in metrics.plot_precision_recall_curve in order to specify the positive class to be used when computing the precision and recall statistics. #17569 by Clara Matos.

- [ENHANCEMENT] Add pos_label parameter in metrics.plot_roc_curve in order to specify the positive class to be used when computing the roc auc statistics. #17651 by Clara Matos.

- [Fix] Fixed a bug in metrics.classification_report which was raising AttributeError when called with output_dict=True for 0-length values. #17777 by Shubhanshu Mishra.

- [Fix] Fixed a bug in metrics.classification_report which was raising AttributeError when called with output_dict=True for 0-length values. #17777 by Shubhanshu Mishra.

- [Fix] Fixed a bug in metrics.jaccard_score which recommended the zero_division parameter when called with no true or predicted samples. #17826 by Richard Decal and Joseph Willard

- [Fix] bug in metrics.hinge_loss where error occurs when y_true is missing some labels that are provided explicitly in the labels parameter. #17935 by Cary Goltermann.

- [Fix] Fix scorers that accept a pos_label parameter and compute their metrics from values returned by decision_function or predict_proba. Previously, they would return erroneous values when pos_label was not corresponding to classifier.classes_[1]. This is especially important when training classifiers directly with string labeled target classes. #18114 by Guillaume Lemaire.

- [Fix] Fixed bug in metrics.plot_confusion_matrix where error occurs when y_true contains labels that were not previously seen by the classifier while the labels and display_labels parameters are set to None. #18405 by Thomas J. Fan and Yakov Pchelintsev.

1.7. Release History

• [Feature] `model_selection.RandomizedSearchCV` and `model_selection.GridSearchCV` now have the method `score_samples` #17478 by Teon Brooks and Mohamed Maskani.

• [Enhancement] `model_selection.TimeSeriesSplit` has two new keyword arguments `test_size` and `gap`. `test_size` allows the out-of-sample time series length to be fixed for all folds. `gap` removes a fixed number of samples between the train and test set on each fold. #13204 by Kyle Kosic.

• [Enhancement] `model_selection.permutation_test_score` and `model_selection.validation_curve` now accept `fit_params` to pass additional estimator parameters. #18527 by Gaurav Dhingra, Julien Jerphanion and Amanda Dsouza.

• [Enhancement] `model_selection.cross_val_score`, `model_selection.cross_validate`, `model_selection.GridSearchCV`, and `model_selection.RandomizedSearchCV` allows estimator to fail scoring and replace the score with `error_score`. If `error_score="raise"`, the error will be raised. #18343 by Guillaume Lemaître and Devi Sandeep.

• [Enhancement] `model_selection.learning_curve` now accept `fit_params` to pass additional estimator parameters. #18595 by Amanda Dsouza.

• [Fix] Fixed the `len` of `model_selection.ParameterSampler` when all distributions are lists and `n_iter` is more than the number of unique parameter combinations. #18222 by Nicolas Hug.

• [Fix] A fix to raise warning when one or more CV splits of `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` results in non-finite scores. #18266 by Subrat Sahu, Nirvan and Arthur Book.

sklearn.multiclass

• [Enhancement] `multiclass.OneVsOneClassifier` now accepts the inputs with missing values. Hence, estimators which can handle missing values (may be a pipeline with imputation step) can be used as a estimator for multiclass wrappers. #17987 by Venkatachalam N.

• [Fix] A fix to allow `multiclass.OutputCodeClassifier` to accept sparse input data in its `fit` and `predict` methods. The check for validity of the input is now delegated to the base estimator. #17233 by Zolisa Bleki.

sklearn.multioutput

• [Enhancement] `multioutput.MultiOutputClassifier` and `multioutput.MultiOutputRegressor` now accepts the inputs with missing values. Hence, estimators which can handle missing values (may be a pipeline with imputation step, HistGradientBoosting estimators) can be used as a estimator for multiclass wrappers. #17987 by Venkatachalam N.

• [Fix] A fix to accept tuples for the `order` parameter in `multioutput.ClassifierChain`. #18124 by Gus Brocchini and Amanda Dsouza.
sklearn.naive_bayes

- [Enhancement] Adds a parameter min_categories to naive_bayes.CategoricalNB that allows a minimum number of categories per feature to be specified. This allows categories unseen during training to be accounted for. #16326 by George Armstrong.

- [API Change] The attributes coef_ and intercept_ are now deprecated in naive_bayes. MultinomialNB, naive_bayes.ComplementNB, naive_bayes.BernoulliNB and naive_bayes.CategoricalNB, and will be removed in v1.1 (renaming of 0.26). #17427 by Juan Carlos Alfaro Jiménez.

sklearn.neighbors

- [Efficiency] Speed up seuclidean, wminkowski, mahalanobis and haversine metrics in neighbors.DistanceMetric by avoiding unexpected GIL acquiring in Cython when setting n_jobs>1 in neighbors.KNeighborsClassifier, neighbors.KNeighborsRegressor, neighbors.RadiusNeighborsClassifier, neighbors.RadiusNeighborsRegressor, neighbors.pairwise_distances and by validating data out of loops. #17038 by Wenbo Zhao.

- [Efficiency] neighbors.NeighborsBase benefits of an improved algorithm = 'auto' heuristic. In addition to the previous set of rules, now, when the number of features exceeds 15, brute is selected, assuming the data intrinsic dimensionality is too high for tree-based methods. #17148 by Geoffrey Bolmier.

- [Fix] neighbors.BinaryTree will raise a ValueError when fitting on data array having points with different dimensions. #18691 by Chiara Marmo.

- [Fix] neighbors.NearestCentroid with a numerical shrink_threshold will raise a ValueError when fitting on data with all constant features. #18370 by Trevor Waite.

- [Fix] In methods radius_neighbors and radius_neighbors_graph of neighbors. NearestNeighbors, neighbors.RadiusNeighborsClassifier, neighbors.RadiusNeighborsRegressor, and neighbors.RadiusNeighborsTransformer, using sort_results=True now correctly sorts the results even when fitting with the “brute” algorithm. #18612 by Tom Dupre la Tour.

sklearn.neural_network

- [Efficiency] Neural net training and prediction are now a little faster. #17603, #17604, #17606, #17608, #17609, #17633, #17661, #17932 by Alex Henrie.


- [Fix] Fix method fit of neural_network.MLPClassifier not iterating to max_iter if warm started. #18269 by Norbert Preining and Guillaume Lemaitre.
sklearn.pipeline

- [Enhancement] References to transformers passed through `transformer_weights` to `pipeline`. `FeatureUnion` that aren’t present in `transformer_list` will raise a `ValueError`. #17876 by Cary Goltermann.
- [Fix] A slice of a `pipeline.Pipeline` now inherits the parameters of the original pipeline (`memory` and `verbose`). #18429 by Albert Villanova del Moral and Pawel Biernat.

sklearn.preprocessing

- [Feature] `preprocessing.OneHotEncoder` now supports missing values by treating them as a category. #17317 by Thomas Fan.
- [Feature] Add a new `handle_unknown` parameter with a `use_encoded_value` option, along with a new `unknown_value` parameter, to `preprocessing.OrdinalEncoder` to allow unknown categories during transform and set the encoded value of the unknown categories. #17406 by Felix Wick and #18406 by Nicolas Hug.
- [Feature] Add `clip` parameter to `preprocessing.MinMaxScaler`, which clips the transformed values of test data to `feature_range`. #17833 by Yashika Sharma.
- [Feature] Add `sample_weight` parameter to `preprocessing.StandardScaler`. Allows setting individual weights for each sample. #18510 and #18447 and #16066 and #18682 by Maria Telenczuk and Albert Villanova and @panpiort8 and Alex Gramfort.
- [Enhancement] Verbose output of `model_selection.GridSearchCV` has been improved for readability. #16935 by Raghav Rajagopalan and Chiara Marmo.
- [Enhancement] Add `unit_variance` to `preprocessing.RobustScaler`, which scales output data such that normally distributed features have a variance of 1. #17193 by Lucy Liu and Mabel Villalba.
- [Enhancement] Add `dtype` parameter to `preprocessing.KBinsDiscretizer`. #16335 by Arthur Imbert.
- [Fix] Raise error on `sklearn.preprocessing.OneHotEncoder.inverse_transform` when `handle_unknown='error'` and `drop=None` for samples encoded as all zeros. #14982 by Kevin Winata.

sklearn.semi_supervised

- [Major Feature] Added `semi_supervised.SelfTrainingClassifier`, a meta-classifier that allows any supervised classifier to function as a semi-supervised classifier that can learn from unlabeled data. #11682 by Oliver Rausch and Patrice Becker.
sklearn.svm


sklearn.tree

- [Feature] tree.DecisionTreeRegressor now supports the new splitting criterion 'poisson' useful for modeling count data. #17386 by Christian Lorentzen.
- [Enhancement] tree.plot_tree now uses colors from the matplotlib configuration settings. #17187 by Andreas Müller.
- [API Change] The parameter X_idx_sorted is now deprecated in tree.DecisionTreeClassifier. fit and tree.DecisionTreeRegressor.fit, and has not effect. #17614 by Juan Carlos Alfaro Jiménez.

sklearn.utils

- [Enhancement] Add check_methods_sample_order_invariance to check_estimator, which checks that estimator methods are invariant if applied to the same dataset with different sample order #17598 by Jason Ngo.
- [Enhancement] Add support for weights in utils.sparse_func.incr_mean_variance_axis. By Maria Telenczuk and Alex Gramfort.
- [Fix] Raise ValueError with clear error message in check_array for sparse DataFrames with mixed types. #17992 by Thomas J. Fan and Alex Shacked.
- [Fix] Allow serialized tree based models to be unpickled on a machine with different endianness. #17644 by Qi Zhang.
- [Fix] Check that we raise proper error when axis=1 and the dimensions do not match in utils.sparse_func.incr_mean_variance_axis. By Alex Gramfort.

Miscellaneous

- [Enhancement] Calls to repr are now faster when print_changed_only=True, especially with meta-estimators. #18508 by Nathan C..

Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.23, including:

1.7.2 Version 0.23.2

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.


Details are listed in the changelog below.

(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)
Changelog

sklearn.cluster

- [Fix] Fixed a bug in `cluster.KMeans` where rounding errors could prevent convergence to be declared when `tol=0`. #17959 by Jérémie du Boisberranger.
- [Fix] Fixed a bug in `cluster.KMeans` and `cluster.MiniBatchKMeans` where the reported inertia was incorrectly weighted by the sample weights. #17848 by Jérémie du Boisberranger.
- [Fix] Fixed a bug in `cluster.MeanShift` with `bin_seeding=True`. When the estimated bandwidth is 0, the behavior is equivalent to `bin_seeding=False`. #17742 by Jeremie du Boisberranger.
- [Fix] Fixed a bug in `cluster.AffinityPropagation`, that gives incorrect clusters when the array dtype is float32. #17995 by Thomaz Santana and Amanda Dsouza.

sklearn.decomposition

- [Fix] Fixed a bug in `decomposition.MiniBatchDictionaryLearning.partial_fit` which should update the dictionary by iterating only once over a mini-batch. #17433 by Chiara Marmo.
- [Fix] Avoid overflows on Windows in `decomposition.IncrementalPCA.partial_fit` for large `batch_size` and `n_samples` values. #17985 by Alan Butler and Amanda Dsouza.

sklearn.ensemble

- [Fix] Fixed bug in `ensemble.MultinomialDeviance` where the average of logloss was incorrectly calculated as sum of logloss. #17694 by Markus Rempfler and Tsutomu Kusanagi.

sklearn.feature_extraction

- [Fix] Fixes bug in `feature_extraction.text.CountVectorizer` where sample order invariance was broken when `max_features` was set and features had the same count. #18016 by Thomas Fan, Roman Yurchak, and Joel Nothman.

sklearn.linear_model

- [Fix] `linear_model.lars_path` does not overwrite `X` when `X_copy=True` and `Gram='auto'`. #17914 by Thomas Fan.
sklearn.manifold

- [Fix] Fixed a bug where `metrics.pairwise_distances` would raise an error if metric='seuclidean' and X is not type np.float64. #15730 by Forrest Koch.

sklearn.metrics

- [Fix] Fixed a bug in `metrics.mean_squared_error` where the average of multiple RMSE values was incorrectly calculated as the root of the average of multiple MSE values. #17309 by Swier Heeres.

sklearn.pipeline

- [Fix] `pipeline.FeatureUnion` raises a deprecation warning when None is included in transformer_list. #17360 by Thomas Fan.

sklearn.utils

- [Fix] Fix `utils.estimator_checks.check_estimator` so that all test cases support the binary_only estimator tag. #17812 by Bruno Charron.

1.7.3 Version 0.23.1

May 18 2020

Changelog

sklearn.cluster

- [Efficiency] `cluster.KMeans` efficiency has been improved for very small datasets. In particular it cannot spawn idle threads any more. #17210 and #17235 by Jeremie du Boisberranger.
- [Fix] Fixed a bug in `cluster.KMeans` where the sample weights provided by the user were modified in place. #17204 by Jeremie du Boisberranger.

Miscellaneous

- [Fix] Fixed a bug in the repr of third-party estimators that use a **kwargs parameter in their constructor, when changed_only is True which is now the default. #17205 by Nicolas Hug.
1.7.4 Version 0.23.0

May 12 2020

For a short description of the main highlights of the release, please refer to Release Highlights for scikit-learn 0.23.

Legend for changelogs

- [MAJOR FEATURE]: something big that you couldn’t do before.
- [FEATURE]: something that you couldn’t do before.
- [EFFICIENCY]: an existing feature now may not require as much computation or memory.
- [ENHANCEMENT]: a miscellaneous minor improvement.
- [FIX]: something that previously didn’t work as documentated – or according to reasonable expectations – should now work.
- [API CHANGE]: you will need to change your code to have the same effect in the future; or a feature will be removed in the future.

Enforcing keyword-only arguments

In an effort to promote clear and non-ambiguous use of the library, most constructor and function parameters are now expected to be passed as keyword arguments (i.e. using the `param=value` syntax) instead of positional. To ease the transition, a `FutureWarning` is raised if a keyword-only parameter is used as positional. In version 1.0 (renaming of 0.25), these parameters will be strictly keyword-only, and a `TypeError` will be raised. #15005 by Joel Nothman, Adrin Jalali, Thomas Fan, and Nicolas Hug. See SLEP009 for more details.

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- [FIX] `cluster.KMeans with algorithm="elkan" and algorithm="full"`.
- [FIX] `datasets.make_multilabel_classification`.
- [FIX] `decomposition.PCA with n_components='mle'`.
- [ENHANCEMENT] `decomposition.NMF` and `decomposition.non_negative_factorization with float32 dtype input`.
scikit-learn user guide, Release 0.24.0

- [Fix] estimator_samples_ in ensemble.BaggingClassifier, ensemble.BaggingRegressor and ensemble.IsolationForest
- [Fix] ensemble.StackingClassifier and ensemble.StackingRegressor with sample_weight
- [Fix] gaussian_process.GaussianProcessRegressor
- [Fix] linear_model.RANSACRegressor with sample_weight.
- [Fix] linear_model.RidgeClassifierCV
- [Fix] metrics.mean_squared_error with squared and multioutput='raw_values'.
- [Fix] metrics.mutual_info_score with negative scores.
- [Fix] metrics.confusion_matrix with zero length y_true and y_pred
- [Fix] neural_network.MLPClassifier
- [Fix] preprocessing.Normalizer with norm='max'.

Details are listed in the changelog below.

(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)

Changelog

sklearn.cluster

- [Efficiency] cluster.Birch implementation of the predict method avoids high memory footprint by calculating the distances matrix using a chunked scheme. #16149 by Jeremie du Boisberranger and Alex Shacked.
- [Efficiency] [Major Feature] The critical parts of cluster.KMeans have a more optimized implementation. Parallelism is now over the data instead of over initializations allowing better scalability. #11950 by Jeremie du Boisberranger.
- [Enhancement] cluster.KMeans now supports sparse data when solver = "elkan". #11950 by Jeremie du Boisberranger.
- [Enhancement] cluster.AgglomerativeClustering has a faster and more memory efficient implementation of single linkage clustering. #11514 by Leland McInnes.
- [Fix] cluster.KMeans with algorithm="elkan" now converges with tol=0 as with the default algorithm="full". #16075 by Erich Schubert.
- [Fix] Fixed a bug in cluster.Birch where the n_clusters parameter could not have a np.int64 type. #16484 by Jeremie du Boisberranger.
- [Fix] cluster.AgglomerativeClustering add specific error when distance matrix is not square and affinity=precomputed. #16257 by Simona Maggio.
• [API CHANGE] The n_jobs parameter of `cluster.KMeans`, `cluster.SpectralCoclustering` and `cluster.SpectralBiclustering` is deprecated. They now use OpenMP based parallelism. For more details on how to control the number of threads, please refer to our Parallelism notes. #11950 by Jeremie du Boisberranger.

• [API CHANGE] The precompute_distances parameter of `cluster.KMeans` is deprecated. It has no effect. #11950 by Jeremie du Boisberranger.

• [API CHANGE] The random_state parameter has been added to `cluster.AffinityPropagation`. #16801 by @rcwoolston and Chiara Marmo.

**sklearn.compose**

• [EFFICIENCY] `compose.ColumnTransformer` is now faster when working with dataframes and strings are used to specify subsets of data for transformers. #16431 by Thomas Fan.

• [ENHANCEMENT] `compose.ColumnTransformer` method `get_feature_names` now supports 'passthrough' columns, with the feature name being either the column name for a dataframe, or 'xi' for column index i. #14048 by Lewis Ball.

• [Fix] `compose.ColumnTransformer` method `get_feature_names` now returns correct results when one of the transformer steps applies on an empty list of columns #15963 by Roman Yurchak.

• [Fix] `compose.ColumnTransformer.fit` will error when selecting a column name that is not unique in the dataframe. #16431 by Thomas Fan.

**sklearn.datasets**

• [EFFICIENCY] `datasets.fetch_openml` has reduced memory usage because it no longer stores the full dataset text stream in memory. #16084 by Joel Nothman.

• [Feature] `datasets.fetch_california_housing` now supports heterogeneous data using pandas by setting as_frame=True. #15950 by Stephanie Andrews and Reshama Shaikh.

• [Feature] embedded dataset loaders `load_breast_cancer`, `load_diabetes`, `load_digits`, `load_iris`, `load_linnerud` and `load_wine` now support loading as a pandas DataFrame by setting as_frame=True. #15980 by @wconnell and Reshama Shaikh.

• [Enhancement] Added return_centers parameter in `datasets.make_blobs`, which can be used to return centers for each cluster. #15709 by @shivamgargsya and Venkatachalam N.

• [Enhancement] Functions `datasets.make_circles` and `datasets.make_moons` now accept two-element tuple. #15707 by Maciej J Mikulski.

• [Fix] `datasets.make_multilabel_classification` now generates ValueError for arguments n_classes < 1 OR length < 1. #16006 by Rushabh Vasani.

• [API CHANGE] The StreamHandler was removed from `sklearn.logger` to avoid double logging of messages in common cases where a handler is attached to the root logger, and to follow the Python logging documentation recommendation for libraries to leave the log message handling to users and application code. #16451 by Christoph Deil.
sklearn.decomposition

- **[Enhancement]** `decomposition.NMF` and `decomposition.non_negative_factorization` now preserves float32 dtype. #16280 by Jeremie du Boisberranger.
- **[Enhancement]** `TruncatedSVD.transform` is now faster on given sparse csc matrices. #16837 by @wornbb.
- **[Fix]** `decomposition.PCA` with a float `n_components` parameter, will exclusively choose the components that explain the variance greater than `n_components`. #15669 by Krishna Chaitanya
- **[Fix]** `decomposition.PCA` with `n_components='mle'` now correctly handles small eigenvalues, and does not infer 0 as the correct number of components. #16224 by Lisa Schwetlick, and Gelavizh Ahmadi and Marija Vlajic Wheeler and #16841 by Nicolas Hug.
- **[Fix]** `decomposition.KernelPCA` method `inverse_transform` now applies the correct inverse transform to the transformed data. #16655 by Lewis Ball.
- **[Fix]** Fixed bug that was causing `decomposition.KernelPCA` to sometimes raise invalid value encountered in multiply during fit. #16718 by Gui Miotto.
- **[Feature]** Added `n_components_` attribute to `decomposition.SparsePCA` and `decomposition.MiniBatchSparsePCA`. #16981 by Mateusz Górski.

sklearn.ensemble

- **[Feature]** Early stopping in `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` is now determined with a new `early_stopping` parameter instead of `n_iter_no_change`. Default value is ‘auto’, which enables early stopping if there are at least 10,000 samples in the training set. #14516 by Johann Faouzi.
- **[Major Feature]** `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` now support monotonic constraints, useful when features are supposed to have a positive/negative effect on the target. #15582 by Nicolas Hug.
- **[API Change]** Fixed a bug in `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` that would not respect the `max_leaf_nodes` parameter if the criteria was reached at the same time as the `max_depth` criteria. #16183 by Nicolas Hug.
- **[Fix]** Changed the convention for `max_depth` parameter of `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor`. The depth now corresponds to the number of edges to go from the root to the deepest leaf. Stumps (trees with one split) are now allowed. #16182 by Santhosh B
- **[Fix]** Fixed a bug in `ensemble.BaggingClassifier`, `ensemble.BaggingRegressor` and `ensemble.IsolationForest` where the attribute `estimators_samples_` did not generate the proper indices used during fit. #16437 by Jin-Hwan Cho.
- **[Fix]** Fixed a bug in `ensemble.StackingClassifier` and `ensemble.StackingRegressor` where the `sample_weight` argument was not being passed to `cross_val_predict` when evaluating the base estimators on cross-validation folds to obtain the input to the meta estimator. #16539 by Bill DeRose.
• [FEATURE] Added additional option loss="poisson" to ensemble.HistGradientBoostingRegressor, which adds Poisson deviance with log-link useful for modeling count data. #16692 by Christian Lorentzen

• [FIX] Fixed a bug where ensemble.HistGradientBoostingRegressor and ensemble.HistGradientBoostingClassifier would fail with multiple calls to fit when warm_start=True, early_stopping=True, and there is no validation set. #16663 by Thomas Fan.

sklearn.feature_extraction

• [EFFICIENCY] feature_extraction.text.CountVectorizer now sorts features after pruning them by document frequency. This improves performances for datasets with large vocabularies combined with min_df or max_df. #15834 by Santiago M. Mola.

sklearn.feature_selection

• [ENHANCEMENT] Added support for multioutput data in feature_selection.RFE and feature_selection.RFECV. #16103 by Divyaprabha M.

• [API CHANGE] Adds feature_selection.SelectorMixin back to public API. #16132 by @trimeta.

sklearn.gaussian_process

• [ENHANCEMENT] gaussian_process.kernels.Matern returns the RBF kernel when nu=np.inf. #15503 by Sam Dixon.

• [FIX] Fixed bug in gaussian_process.GaussianProcessRegressor that caused predicted standard deviations to only be between 0 and 1 when WhiteKernel is not used. #15782 by @plgreenLIRU.

sklearn.impute

• [ENHANCEMENT] impute.IterativeImputer accepts both scalar and array-like inputs for max_value and min_value. Array-like inputs allow a different max and min to be specified for each feature. #16403 by Narendra Mukherjee.

• [ENHANCEMENT] impute.SimpleImputer, impute.KNNImputer, and impute.IterativeImputer accepts pandas’ nullable integer dtype with missing values. #16508 by Thomas Fan.

sklearn.inspection

sklearn.linear_model

- [Major Feature] Added generalized linear models (GLM) with non normal error distributions, including `linear_model.PoissonRegressor`, `linear_model.GammaRegressor` and `linear_model.TweedieRegressor` which use Poisson, Gamma and Tweedie distributions respectively. #14300 by Christian Lorentzen, Roman Yurchak, and Olivier Grisel.


- [Efficiency] `linear_model.RidgeCV` and `linear_model.RidgeClassifierCV` now does not allocate a potentially large array to store dual coefficients for all hyperparameters during its `fit`, nor an array to store all error or LOO predictions unless `store_cv_values` is True. #15652 by Jérôme Dockès.

- [Enhancement] `linear_model.LassoLars` and `linear_model.Lars` now support a jitter parameter that adds random noise to the target. This might help with stability in some edge cases. #15179 by @angelaambroz.

- [Fix] Fixed a bug where if a `sample_weight` parameter was passed to the `fit` method of `linear_model.RANSACRegressor`, it would not be passed to the wrapped `base_estimator` during the fitting of the final model. #15773 by Jeremy Alexandre.


- [Fix] Fixed a bug in `linear_model.RidgeClassifierCV` to pass a specific scoring strategy. Before the internal estimator outputs score instead of predictions. #14848 by Venkatachalam N.

- [Fix] `linear_model.LogisticRegression` will now avoid an unnecessary iteration when `solver='newton-cg'` by checking for inferior or equal instead of strictly inferior for maximum of `absgrad` and `tol` in `utils.optimize._newton_cg`. #16266 by Rushabh Vasani.


- [Fix] [Efficiency] `linear_model.ARDRegression` is more stable and much faster when $n_{samples} > n_{features}$. It can now scale to hundreds of thousands of samples. The stability fix might imply changes in the number of non-zero coefficients and in the predicted output. #16849 by Nicolas Hug.


sklearn.metrics

- [Enhancement] metrics.pairwise.pairwise_distances_chunked now allows its reduce_func to not have a return value, enabling in-place operations. #16397 by Joel Nothman.
- [Fix] Fixed a bug in metrics.mean_squared_error to not ignore argument squared when argument multioutput='raw_values'. #16323 by Rushabh Vasani
- [Fix] Fixed a bug in metrics.mutual_info_score where negative scores could be returned. #16362 by Thomas Fan.
- [Fix] Fixed a bug in metrics.confusion_matrix that would raise an error when y_true and y_pred were length zero and labels was not None. In addition, we raise an error when an empty list is given to the labels parameter. #16442 by Kyle Parsons.
- [API Change] Changed the formatting of values in metrics.ConfusionMatrixDisplay.plot and metrics.plot_confusion_matrix to pick the shorter format (either '2g' or 'd'). #16159 by Rick Mackenbach and Thomas Fan.
- [API Change] From version 0.25, metrics.pairwise.pairwise_distances will no longer automatically compute the VI parameter for Mahalanobis distance and the V parameter for seuclidean distance if Y is passed. The user will be expected to compute this parameter on the training data of their choice and pass it to pairwise_distances. #16993 by Joel Nothman.

sklearn.model_selection

- [Enhancement] model_selection.GridSearchCV and model_selection.RandomizedSearchCV yields stack trace information in fit failed warning messages in addition to previously emitted type and details. #15622 by Gregory Morse.
- [Fix] model_selection.cross_val_predict supports method="predict_proba" when y=None. #15918 by Luca Kubin.
- [Fix] model_selection.fit_grid_point is deprecated in 0.23 and will be removed in 0.25. #16401 by Arie Pratama Sutiono

sklearn.multioutput

- [Feature] multioutput.MultiOutputRegressor.fit and multioutput.MultiOutputClassifier.fit now can accept fit_params to pass to the estimator.fit method of each step. #15953 #15959 by Ke Huang.
- [Enhancement] multioutput.RegressorChain now supports fit_params for base_estimator during fit. #16111 by Venkatachalam N.

sklearn.naive_bayes

- [Fix] A correctly formatted error message is shown in naive_bayes.CategoricalNB when the number of features in the input differs between predict and fit. #16090 by Madhura Jayaratne.
sklearn.neural_network

- [Efficiency] `neural_network.MLPClassifier` and `neural_network.MLPRegressor` has reduced memory footprint when using stochastic solvers, 'sgd' or 'adam', and shuffle=True. #14075 by @meyer89.

- [Fix] Increases the numerical stability of the logistic loss function in `neural_network.MLPClassifier` by clipping the probabilities. #16117 by Thomas Fan.

sklearn.inspection

- [Enhancement] `inspection.PartialDependenceDisplay` now exposes the deciles lines as attributes so they can be hidden or customized. #15785 by Nicolas Hug

sklearn.preprocessing

- [Feature] Argument `drop` of `preprocessing.OneHotEncoder` will now accept value `if_binary` and will drop the first category of each feature with two categories. #16245 by Rushabh Vasani.

- [Enhancement] `preprocessing.OneHotEncoder`'s `drop_idx_` ndarray can now contain None, where `drop_idx_[i] = None` means that no category is dropped for index i. #1685 by Chiara Marmo.


- [Efficiency] `preprocessing.OneHotEncoder` is now faster at transforming. #15762 by Thomas Fan.

- [Fix] Fix a bug in `preprocessing.StandardScaler` which was incorrectly computing statistics when calling `partial_fit` on sparse inputs. #16466 by Guillaume Lemaître.

- [Fix] Fix a bug in `preprocessing.Normalizer` with norm='max', which was not taking the absolute value of the maximum values before normalizing the vectors. #16632 by Maura Pintor and Battista Biggio.

sklearn.semi_supervised

- [Fix] `semi_supervised.LabelSpreading` and `semi_supervised.LabelPropagation` avoids divide by zero warnings when normalizing `label_distributions_`. #15946 by @ngshya.

sklearn.svm

- [Fix] [Efficiency] Improved `libsvm` and `liblinear` random number generators used to randomly select coordinates in the coordinate descent algorithms. Platform-dependent C rand() was used, which is only able to generate numbers up to 32767 on windows platform (see this blog post) and also has poor randomization power as suggested by this presentation. It was replaced with C++11 mt19937, a Mersenne Twister that correctly generates 31bits/63bits random numbers on all platforms. In addition, the crude “modulo” post-processor used to get a random number in a bounded interval was replaced by the tweaked Lemire method as suggested by this blog post. Any model using the `svm.libsvm` or the `svm.liblinear` solver, including `svm.LinearSVC`, `svm.LinearSVR`, `svm.NuSVC`, `svm.NuSVR`, `svm.OneClassSVM`, `svm.SVC`, `svm.SVR`, `linear_model.LogisticRegression`, is affected. In particular users can expect a better convergence when the number of samples (LibSVM) or the number of features (LibLinear) is large. #13511 by Sylvain Marié.
- [Fix] Fix use of custom kernel not taking float entries such as string kernels in `svm.SVC` and `svm.SVR`. Note that custom kernels are now expected to validate their input where they previously received valid numeric arrays. #11296 by Alexandre Gramfort and Georgi Peev.

- [API Change] `svm.SVR` and `svm.OneClassSVM` attributes, `probA_` and `probB_`, are now deprecated as they were not useful. #15558 by Thomas Fan.

**sklearn.tree**

- [Fix] `tree.plot_tree` `rotate` parameter was unused and has been deprecated. #15806 by Chiara Marmo.


**sklearn.utils**

- [Major Feature] Estimators can now be displayed with a rich html representation. This can be enabled in Jupyter notebooks by setting `display='diagram'` in `set_config`. The raw html can be returned by using `utils.estimator_html_repr`. #14180 by Thomas Fan.

- [Enhancement] improve error message in `utils.validation.column_or_1d`. #15926 by Loïc Estève.

- [Enhancement] add warning in `utils.check_array` for pandas sparse DataFrame. #16021 by Rushabh Vasani.

- [Enhancement] `utils.check_array` now constructs a sparse matrix from a pandas DataFrame that contains only `SparseArray` columns. #16728 by Thomas Fan.

- [Enhancement] `utils.validation.check_array` supports pandas’ nullable integer dtype with missing values when `force_all_finite` is set to `False` or `'allow-nan'` in which case the data is converted to floating point values where `pd.NA` values are replaced by `np.nan`. As a consequence, all `sklearn.preprocessing` transformers that accept numeric inputs with missing values represented as `np.nan` now also accepts being directly fed pandas dataframes with `pd.Int*` or `pd.Uint*` typed columns that use `pd.NA` as a missing value marker. #16508 by Thomas Fan.

- [API Change] Passing classes to `utils.estimator_checks.check_estimator` and `utils.estimator_checks.parametrize_with_checks` is now deprecated, and support for classes will be removed in 0.24. Pass instances instead. #17032 by Nicolas Hug.

- [API Change] The private utility `_safe_tags` in `utils.estimator_checks` was removed, hence all tags should be obtained through `estimator._get_tags()`. Note that Mixins like `RegressorMixin` must come before base classes in the MRO for `_get_tags()` to work properly. #16950 by Nicolas Hug.

- [Fix] `utils.all_estimators` now only returns public estimators. #15380 by Thomas Fan.
Miscellaneous

- [Major Feature] Adds a HTML representation of estimators to be shown in a jupyter notebook or lab. This visualization is activated by setting the `display` option in `sklearn.set_config`. #14180 by Thomas Fan.

- [Enhancement] scikit-learn now works with mypy without errors. #16726 by Roman Yurchak.

- [API Change] Most estimators now expose a `n_features_in_` attribute. This attribute is equal to the number of features passed to the `fit` method. See SLEP010 for details. #16112 by Nicolas Hug.

- [API Change] Estimators now have a `requires_y` tag which is False by default except for estimators that inherit from `~sklearn.base.RegressorMixin` or `~sklearn.base.ClassifierMixin`. This tag is used to ensure that a proper error message is raised when y was expected but None was passed. #16622 by Nicolas Hug.

- [API Change] The default setting `print_changed_only` has been changed from False to True. This means that the `repr` of estimators is now more concise and only shows the parameters whose default value has been changed when printing an estimator. You can restore the previous behaviour by using `sklearn.set_config(print_changed_only=False)`. Also, note that it is always possible to quickly inspect the parameters of any estimator using `est.get_params(deep=False)`. #17061 by Nicolas Hug.

Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.22, including:

1.7.5 Version 0.22.2.post1

March 3 2020

The 0.22.2.post1 release includes a packaging fix for the source distribution but the content of the packages is otherwise identical to the content of the wheels with the 0.22.2 version (without the .post1 suffix). Both contain the following changes.

Changelog

sklearn.impute

• [EFFICIENCY] Reduce \texttt{impute.KNNImputer} asymptotic memory usage by chunking pairwise distance computation. #16397 by Joel Nothman.

sklearn.metrics

• [Fix] Fixed a bug in \texttt{metrics.plot_roc_curve} where the name of the estimator was passed in the \texttt{metrics.RocCurveDisplay} instead of the parameter name. It results in a different plot when calling \texttt{metrics.RocCurveDisplay.plot} for the subsequent times. #16500 by Guillaume Lemaitre.

• [Fix] Fixed a bug in \texttt{metrics.plot_precision_recall_curve} where the name of the estimator was passed in the \texttt{metrics.PrecisionRecallDisplay} instead of the parameter name. It results in a different plot when calling \texttt{metrics.PrecisionRecallDisplay.plot} for the subsequent times. #16505 by Guillaume Lemaitre.

sklearn.neighbors

• [Fix] Fix a bug which converted a list of arrays into a 2-D object array instead of a 1-D array containing NumPy arrays. This bug was affecting \texttt{neighbors.NearestNeighbors.radius_neighbors}. #16076 by Guillaume Lemaitre and Alex Shacked.

1.7.6 Version 0.22.1

January 2 2020

This is a bug-fix release to primarily resolve some packaging issues in version 0.22.0. It also includes minor documentation improvements and some bug fixes.

Changelog

sklearn.cluster

• [Fix] \texttt{cluster.KMeans} with \texttt{algorithm="elkan"} now uses the same stopping criterion as with the default \texttt{algorithm="full"}. #15930 by @inder128.
sklearn.inspection

- [Fix] `inspection.permutation_importance` will return the same importances when a `random_state` is given for both `n_jobs=1` or `n_jobs>1` both with shared memory backends (thread-safety) and isolated memory, process-based backends. Also avoid casting the data as object dtype and avoid read-only error on large dataframes with `n_jobs>1` as reported in #15810. Follow-up of #15898 by Shivam Gargsysy. #15933 by Guillaume Lemaître and Olivier Grisel.

- [Fix] `inspection.plot_partial_dependence` and `inspection.PartialDependenceDisplay.plot` now consistently checks the number of axes passed in. #15760 by Thomas Fan.

sklearn.metrics

- [Fix] `metrics.plot_confusion_matrix` now raises error when `normalize` is invalid. Previously, it runs fine with no normalization. #15888 by Hanmin Qin.

- [Fix] `metrics.plot_confusion_matrix` now colors the label color correctly to maximize contrast with its background. #15936 by Thomas Fan and @DizietAsahi.

- [Fix] `metrics.classification_report` does no longer ignore the value of the `zero_division` keyword argument. #15879 by Bibhash Chandra Mitra.

- [Fix] Fixed a bug in `metrics.plot_confusion_matrix` to correctly pass the `values_format` parameter to the `ConfusionMatrixDisplay.plot()` call. #15937 by Stephen Blystone.

sklearn.model_selection

- [Fix] `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` accept scalar values provided in `fit_params`. Change in 0.22 was breaking backward compatibility. #15863 by Adrin Jalali and Guillaume Lemaître.

sklearn.naive_bayes

- [Fix] Removed `abstractmethod` decorator for the method `_check_X` in `naive_bayes.BaseNB` that could break downstream projects inheriting from this deprecated public base class. #15996 by Brigitta Sipcosz.

sklearn.preprocessing

- [Fix] `preprocessing.QuantileTransformer` now guarantees the `quantiles_` attribute to be completely sorted in non-decreasing manner. #15751 by Tirth Patel.
sklearn.semi_supervised


sklearn.utils

- [Fix] `utils.check_array` now correctly converts pandas DataFrame with boolean columns to floats. #15797 by Thomas Fan.
- [Fix] `utils.check_is_fitted` accepts back an explicit `attributes` argument to check for specific attributes as explicit markers of a fitted estimator. When no explicit `attributes` are provided, only the attributes that end with a underscore and do not start with double underscore are used as “fitted” markers. The `all_or_any` argument is also no longer deprecated. This change is made to restore some backward compatibility with the behavior of this utility in version 0.21. #15947 by Thomas Fan.

1.7.7 Version 0.22.0

December 3 2019

For a short description of the main highlights of the release, please refer to Release Highlights for scikit-learn 0.22.

Legend for changelogs

- [Major Feature]: something big that you couldn’t do before.
- [Feature]: something that you couldn’t do before.
- [Efficiency]: an existing feature now may not require as much computation or memory.
- [Enhancement]: a miscellaneous minor improvement.
- [Fix]: something that previously didn’t work as documentated — or according to reasonable expectations — should now work.
- [API Change]: you will need to change your code to have the same effect in the future; or a feature will be removed in the future.

Website update

Our website was revamped and given a fresh new look. #14849 by Thomas Fan.

Clear definition of the public API

Scikit-learn has a public API, and a private API.

We do our best not to break the public API, and to only introduce backward-compatible changes that do not require any user action. However, in cases where that’s not possible, any change to the public API is subject to a deprecation cycle of two minor versions. The private API isn’t publicly documented and isn’t subject to any deprecation cycle, so users should not rely on its stability.
A function or object is public if it is documented in the API Reference and if it can be imported with an import path without leading underscores. For example `sklearn.pipeline.make_pipeline` is public, while `sklearn.pipeline._name_estimators` is private. `sklearn.ensemble._gb.BaseEnsemble` is private too because the whole `_gb` module is private.

Up to 0.22, some tools were de-facto public (no leading underscore), while they should have been private in the first place. In version 0.22, these tools have been made properly private, and the public API space has been cleaned. In addition, importing from most sub-modules is now deprecated: you should for example `use from sklearn.cluster import Birch instead of from sklearn.cluster.birch import Birch (in practice, birch.py has been moved to _birch.py).`

**Note:** All the tools in the public API should be documented in the API Reference. If you find a public tool (without leading underscore) that isn’t in the API reference, that means it should either be private or documented. Please let us know by opening an issue!

This work was tracked in issue 9250 and issue 12927.

**Deprecations: using FutureWarning from now on**

When deprecating a feature, previous versions of scikit-learn used to raise a DeprecationWarning. Since the DeprecationWarnings aren’t shown by default by Python, scikit-learn needed to resort to a custom warning filter to always show the warnings. That filter would sometimes interfere with users custom warning filters.

Starting from version 0.22, scikit-learn will show FutureWarnings for deprecations, as recommended by the Python documentation. FutureWarnings are always shown by default by Python, so the custom filter has been removed and scikit-learn no longer hinders with user filters. #15080 by Nicolas Hug.

**Changed models**

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- `cluster.KMeans` when `n_jobs=1`. [Fix]
- `decomposition.SparseCoder` with algorithm='lasso_lars' [Fix]
- `decomposition.SparsePCA` where normalize_components has no effect due to deprecation.
- `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` [Fix], [Feature], [Enhancement].
- `impute.IterativeImputer` when X has features with no missing values. [Feature]
- `linear_model.Ridge` when X is sparse. [Fix]
- `model_selection.StratifiedKFold` and any use of cv=int with a classifier. [Fix]
- `cross_decomposition.CCA` when using scipy >= 1.3 [Fix]

Details are listed in the changelog below. (While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)
Changelog

sklearn.base

- **[API CHANGE]** From version 0.24, `base.BaseEstimator.get_params` will raise an `AttributeError` rather than return `None` for parameters that are in the estimator’s constructor but not stored as attributes on the instance. #14464 by Joel Nothman.

sklearn.calibration

- **[Fix]** Fixed a bug that made `calibration.CalibratedClassifierCV` fail when given a `sample_weight` parameter of type `list` (in the case where `sample_weights` are not supported by the wrapped estimator). #13575 by William de Vazelhes.

sklearn.cluster

- **[Feature]** `cluster.SpectralClustering` now accepts precomputed sparse neighbors graph as input. #10482 by Tom Dupre la Tour and Kumar Ashutosh.
- **[Enhancement]** `cluster.SpectralClustering` now accepts a `n_components` parameter. This parameter extends `SpectralClustering` class functionality to match `cluster.spectral_clustering`. #13726 by Shuzhe Xiao.
- **[Fix]** Fixed a bug where `cluster.KMeans` produced inconsistent results between `n_jobs=1` and `n_jobs>1` due to the handling of the random state. #9288 by Bryan Yang.
- **[Fix]** Fixed a bug where `elkan` algorithm in `cluster.KMeans` was producing Segmentation Fault on large arrays due to integer index overflow. #15057 by Vladimir Korolev.
- **[Fix]** `MeanShift` now accepts a `max_iter` with a default value of 300 instead of always using the default 300. It also now exposes an `n_iter_` indicating the maximum number of iterations performed on each seed. #15120 by Adrin Jalali.
- **[Fix]** `cluster.AgglomerativeClustering` and `cluster.FeatureAgglomeration` now raise an error if `affinity='cosine'` and X has samples that are all-zeros. #7943 by @mthorrell.

sklearn.compose

- **[Feature]** Adds `compose.make_column_selector` which is used with `compose.ColumnTransformer` to select DataFrame columns on the basis of name and dtype. #12303 by Thomas Fan.
- **[Fix]** Fixed a bug in `compose.ColumnTransformer` which failed to select the proper columns when using a boolean list, with NumPy older than 1.12. #14510 by Guillaume Lemaitre.
- **[Fix]** Fixed a bug in `compose.TransformedTargetRegressor` which did not pass **fit_params** to the underlying regressor. #14890 by Miguel Cabrera.
- **[Fix]** The `compose.ColumnTransformer` now requires the number of features to be consistent between `fit` and `transform`. A `FutureWarning` is raised now, and this will raise an error in 0.24. If the number of features isn’t consistent and negative indexing is used, an error is raised. #14544 by Adrin Jalali.

1.7. Release History
sklearn.cross_decomposition

- [Feature] `cross_decomposition.PLSCanonical` and `cross_decomposition.PLSSegression` have a new function `inverse_transform` to transform data to the original space. #15304 by Jaime Ferrando Huertas.

- [Enhancement] `decomposition.KernelPCA` now properly checks the eigenvalues found by the solver for numerical or conditioning issues. This ensures consistency of results across solvers (different choices for `eigen_solver`), including approximate solvers such as `randomized` and `lobpcg` (see #12068). #12145 by Sylvain Marié

- [Fix] Fixed a bug where `cross_decomposition.PLSCanonical` and `cross_decomposition.PLSSegression` were raising an error when fitted with a target matrix $Y$ in which the first column was constant. #13609 by Camila Williamson.

- [Fix] `cross_decomposition.CCA` now produces the same results with scipy 1.3 and previous scipy versions. #15661 by Thomas Fan.

sklearn.datasets

- [Feature] `datasets.fetch_openml` now supports heterogeneous data using pandas by setting `as_frame=True`. #13902 by Thomas Fan.

- [Feature] `datasets.fetch_openml` now includes the `target_names` in the returned Bunch. #15160 by Thomas Fan.

- [Enhancement] The parameter `return_X_y` was added to `datasets.fetch_20newsgroups` and `datasets.fetch_olivetti_faces`. #14259 by Sourav Singh.

- [Enhancement] `datasets.make_classification` now accepts array-like `weights` parameter, i.e. list or numpy.array, instead of list only. #14764 by Cat Chenal.

- [Enhancement] The parameter `normalize` was added to `datasets.fetch_20newsgroups_vectorized`. #14740 by Stéphan Tulkens

- [Fix] Fixed a bug in `datasets.fetch_openml`, which failed to load an OpenML dataset that contains an ignored feature. #14623 by Sarra Habchi.

sklearn.decomposition

- [Efficiency] `decomposition.NMF(solver='mu')` fitted on sparse input matrices now uses batching to avoid briefly allocating an array with size (#non-zero elements, n_components). #15257 by Mart Willoox.


- [Enhancement] `decomposition.IncrementalPCA` now accepts sparse matrices as input, converting them to dense in batches thereby avoiding the need to store the entire dense matrix at once. #13960 by Scott Gigante.

- [Fix] `decomposition.sparse_encode` now passes the `max_iter` to the underlying `linear_model.LassoLars` when `algorithm='lasso_lars'`. #12650 by Adrin Jalali.
sklearn.dummy

- [Fix] `dummy.DummyClassifier` now handles checking the existence of the provided constant in multioutput cases. #14908 by Martina G. Vilas.
- [API CHANGE] The default value of the `strategy` parameter in `dummy.DummyClassifier` will change from 'stratified' in version 0.22 to 'prior' in 0.24. A FutureWarning is raised when the default value is used. #15382 by Thomas Fan.
- [API CHANGE] The `outputs_2d_` attribute is deprecated in `dummy.DummyClassifier` and `dummy.DummyRegressor`. It is equivalent to `n_outputs > 1`. #14933 by Nicolas Hug

sklearn.ensemble

- [MAJOR FEATURE] Added `ensemble.StackingClassifier` and `ensemble.StackingRegressor` to stack predictors using a final classifier or regressor. #11047 by Guillaume Lemaitre and Caio Oliveira and #15138 by Jon Cusick.
- [MAJOR FEATURE] Many improvements were made to `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor`:
  - [FEATURE] Estimators now natively support dense data with missing values both for training and predicting. They also support infinite values. #13911 and #14406 by Nicolas Hug, Adrin Jalali and Olivier Grisel.
  - [FEATURE] Estimators now have an additional `warm_start` parameter that enables warm starting. #14012 by Johann Faouzi.
  - [FEATURE] `inspection.partial_dependence` and `inspection.plot_partial_dependence` now support the fast ‘recursion’ method for both estimators. #13769 by Nicolas Hug.
  - [ENHANCEMENT] for `ensemble.HistGradientBoostingClassifier` the training loss or score is now monitored on a class-wise stratified subsample to preserve the class balance of the original training set. #14194 by Johann Faouzi.
  - [Fix] Estimators now bin the training and validation data separately to avoid any data leak. #13933 by Nicolas Hug.
  - [Fix] Fixed a bug where early stopping would break with string targets. #14710 by Guillaume Lemaitre.
  - [Fix] `ensemble.HistGradientBoostingClassifier` now raises an error if `categorical_crossentropy` loss is given for a binary classification problem. #14869 by Adrin Jalali.

Note that pickles from 0.21 will not work in 0.22.

- [ENHANCEMENT] Addition of `max_samples` argument allows limiting size of bootstrap samples to be less than size of dataset. Added to `ensemble.RandomForestClassifier`, `ensemble.RandomForestRegressor`, `ensemble.ExtraTreesClassifier`, `ensemble.ExtraTreesRegressor`. #14682 by Matt Hancock and #5963 by Pablo Duboue.

- [Fix] `ensemble.VotingClassifier.predict_proba` will no longer be present when `voting='hard'`. #14287 by Thomas Fan.

- [Fix] The `named_estimators_` attribute in `ensemble.VotingClassifier` and `ensemble.VotingRegressor` now correctly maps to dropped estimators. Previously, the `named_estimators_` mapping was incorrect whenever one of the estimators was dropped. #15375 by Thomas Fan.

1.7. Release History
• [Fix] Run by default `utils.estimate_checks.check_estimator` on both `ensemble.VotingClassifier` and `ensemble.VotingRegressor`. It leads to solve issues regarding shape consistency during `predict` which was failing when the underlying estimators were not outputting consistent array dimensions. Note that it should be replaced by refactoring the common tests in the future. #14305 by Guillaume Lemaitre.

• [Fix] `ensemble.AdaBoostClassifier` computes probabilities based on the decision function as in the literature. Thus, `predict` and `predict_proba` give consistent results. #14114 by Guillaume Lemaitre.

• [Fix] Stacking and Voting estimators now ensure that their underlying estimators are either all classifiers or all regressors. `ensemble.StackingClassifier`, `ensemble.StackingRegressor`, and `ensemble.VotingClassifier` and `VotingRegressor` now raise consistent error messages. #15084 by Guillaume Lemaitre.

• [Fix] `ensemble.AdaBoostRegressor` where the loss should be normalized by the max of the samples with non-null weights only. #14294 by Guillaume Lemaitre.

• [API Change] `presort` is now deprecated in `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor`, and the parameter has no effect. Users are recommended to use `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` instead. #14907 by Adrin Jalali.

sklearn.feature_extraction

• [Enhancement] A warning will now be raised if a parameter choice means that another parameter will be unused on calling the `fit()` method for `feature_extraction.text.HashingVectorizer`, `feature_extraction.text.CountVectorizer` and `feature_extraction.text.TfidfVectorizer`. #14602 by Gaurav Chawla.

• [Fix] Functions created by `build_preprocessor` and `build_analyzer` of `feature_extraction.textVectorizerMixin` can now be pickled. #14430 by Dillon Niederhut.

• [Fix] `feature_extraction.text.strip_accents_unicode` now correctly removes accents from strings that are in NFKD normalized form. #15100 by Daniel Grady.

• [Fix] Fixed a bug that caused `feature_extraction.DictVectorizer` to raise an `OverflowError` during the `transform` operation when producing a `scipy.sparse` matrix on large input data. #15463 by Norvan Sahiner.

• [API Change] Deprecated unused `copy` param for `feature_extraction.text.TfidfVectorizer.transform` it will be removed in v0.24. #14520 by Guilemm G. Subies.

sklearn.feature_selection

• [Enhancement] Updated the following `feature_selection` estimators to allow NaN/Inf values in `transform` and `fit`: `feature_selection.RFE`, `feature_selection.RFECV`, `feature_selection.SelectFromModel`, and `feature_selection.VarianceThreshold`. Note that if the underlying estimator of the feature selector does not allow NaN/Inf then it will still error, but the feature selectors themselves no longer enforce this restriction unnecessarily. #11635 by Alec Peters.

• [Fix] Fixed a bug where `feature_selection.VarianceThreshold` with `threshold=0` did not remove constant features due to numerical instability, by using range rather than variance in this case. #13704 by Roddy MacSween.
sklearn.gaussian_process

- **[FEATURE]** Gaussian process models on structured data: `gaussian_process.GaussianProcessRegressor` and `gaussian_process.GaussianProcessClassifier` can now accept a list of generic objects (e.g. strings, trees, graphs, etc.) as the X argument to their training/prediction methods. A user-defined kernel should be provided for computing the kernel matrix among the generic objects, and should inherit from `gaussian_process.kernels.GenericKernelMixin` to notify the GPR/GPC model that it handles non-vectorial samples. #15557 by Yu-Hang Tang.

- **[EFFICIENCY]** `gaussian_process.GaussianProcessClassifier.log_marginal_likelihood` and `gaussian_process.GaussianProcessRegressor.log_marginal_likelihood` now accept a `clone_kernel=True` keyword argument. When set to False, the kernel attribute is modified, but may result in a performance improvement. #14378 by Masashi Shibata.

- **[API CHANGE]** From version 0.24 `gaussian_process.kernels.Kernel.get_params` will raise an AttributeError rather than return None for parameters that are in the estimator’s constructor but not stored as attributes on the instance. #14464 by Joel Nothman.

sklearn.impute

- **[MAJOR FEATURE]** Added `impute.KNNImputer`, to impute missing values using k-Nearest Neighbors. #12852 by Ashim Bhattarai and Thomas Fan and #15010 by Guillaume Lemaitre.

- **[FEATURE]** `impute.IterativeImputer` has new `skip_compute` flag that is False by default, which, when True, will skip computation on features that have no missing values during the fit phase. #13773 by Sergey Feldman.

- **[EFFICIENCY]** `impute.MissingIndicator.fit_transform` avoid repeated computation of the masked matrix. #14356 by Harsh Soni.

- **[FIX]** `impute.IterativeImputer` now works when there is only one feature. By Sergey Feldman.

- **[FIX]** Fixed a bug in `impute.IterativeImputer` where features where imputed in the reverse desired order with `imputation_order` either "ascending" or "descending". #15393 by Venkatachalam N.

sklearn.inspection

- **[MAJOR FEATURE]** `inspection.permutation_importance` has been added to measure the importance of each feature in an arbitrary trained model with respect to a given scoring function. #13146 by Thomas Fan.


- **[ENHANCEMENT]** `inspection.plot_partial_dependence` has been extended to now support the new visualization API described in the User Guide. #14646 by Thomas Fan.

- **[ENHANCEMENT]** `inspection.partial_dependence` accepts pandas DataFrame and `pipeline.Pipeline` containing `compose.ColumnTransformer`. In addition `inspection.plot_partial_dependence` will use the column names by default when a dataframe is passed. #14028 and #15429 by Guillaume Lemaitre.
sklearn.kernel_approximation

- [Fix] Fixed a bug where `kernel_approximation.Nystroem` raised a KeyErrors when using `kernel="precomputed"`. #14706 by Venkatachalam N.

sklearn.linear_model

- [Efficiency] The ‘liblinear’ logistic regression solver is now faster and requires less memory. #14108, #14170, #14296 by Alex Henrie.
- [Enhancement] `linear_model.BayesianRidge` now accepts hyperparameters `alpha_init` and `lambda_init` which can be used to set the initial value of the maximization procedure in `fit`. #13618 by Yoshihiro Uchida.
- [Fix] `linear_model.Ridge` now correctly fits an intercept when X is sparse, solver="auto" and `fit_intercept=True`, because the default solver in this configuration has changed to `sparse_cg`, which can fit an intercept with sparse data. #13995 by Jérôme Dockès.
- [Fix] `linear_model.Ridge` with `solver='sag'` now accepts F-ordered and non-contiguous arrays and makes a conversion instead of failing. #14458 by Guillaume Lemaitre.
- [Fix] `linear_model.LassoCV` no longer forces `precompute=False` when fitting the final model. #14591 by Andreas Müller.
- [Fix] `linear_model.RidgeCV` and `linear_model.RidgeClassifierCV` now correctly scores when `cv=None`. #14864 by Venkatachalam N.
- [Fix] Fixed a bug in `linear_model.LogisticRegressionCV` where the `scores_`, `n_iter_` and `coefs_paths_` attribute would have a wrong ordering with `penalty='elastic-net'`. #15044 by Nicolas Hug.
- [Fix] The liblinear solver now supports `sample_weight`. #15038 by Guillaume Lemaitre.

sklearn.manifold

- [Feature] `manifold.Isomap`, `manifold.TSNE`, and `manifold.SpectralEmbedding` now accept precomputed sparse neighbors graph as input. #10482 by Tom Dupre la Tour and Kumar Ashutosh.
- [Feature] Exposed the `n_jobs` parameter in `manifold.TSNE` for multi-core calculation of the neighbors graph. This parameter has no impact when `metric="precomputed"` or (metric="euclidean" and `method="exact"`). #15082 by Roman Yurchak.
- [Efficiency] Improved efficiency of `manifold.TSNE` when `method="barnes-hut"` by computing the gradient in parallel. #13213 by Thomas Moreau.
- [Fix] Fixed a bug in `manifold.spectral_embedding` (and therefore `manifold.SpectralEmbedding` and `cluster.SpectralClustering`) computed wrong eigenvalues with `eigen_solver='amg'` when `n_samples < 5 * n_components`. #14647 by Andreas Müller.
- [Fix] Fixed a bug in `manifold.spectral_embedding` used in `manifold.SpectralEmbedding` and `cluster.SpectralClustering` where `eigen_solver='amg'` would sometimes result in a LinAlgError. #13939 by Andrew Knyazev #13707 by Scott White.
- [API Change] Deprecate `training_data_` unused attribute in `manifold.Isomap`. #10482 by Tom Dupre la Tour.
**sklearn.metrics**

- **[Major Feature]** `metrics.plot_roc_curve` has been added to plot roc curves. This function introduces the visualization API described in the User Guide. #14357 by Thomas Fan.

- **[Feature]** Added a new parameter `zero_division` to multiple classification metrics: `precision_score`, `recall_score`, `f1_score`, `fbeta_score`, `precision_recall_fscore_support`, `classification_report`. This allows to set returned value for ill-defined metrics. #14900 by Marc Torrellas Socastro.

- **[Feature]** Added the `metrics.pairwise.nan_euclidean_distances` metric, which calculates euclidean distances in the presence of missing values. #12852 by Ashim Bhattarai and Thomas Fan.

- **[Feature]** New ranking metrics `metrics.ndcg_score` and `metrics.dcg_score` have been added to compute Discounted Cumulative Gain and Normalized Discounted Cumulative Gain. #9951 by Jérôme Dockès.

- **[Feature]** `metrics.plot_precision_recall_curve` has been added to plot precision recall curves. #14936 by Thomas Fan.

- **[Feature]** `metrics.plot_confusion_matrix` has been added to plot confusion matrices. #15083 by Thomas Fan.

- **[Feature]** Added multiclass support to `metrics.roc_auc_score` with corresponding scorers 'roc_auc_ovr', 'roc_auc_ovo', 'roc_auc_ovo_weighted', and 'roc_auc_ovo_weighted'. #12789 and #15274 by Kathy Chen, Mohamed Maskani, and Thomas Fan.

- **[Feature]** Add `metrics.mean_tweedie_deviance` measuring the Tweedie deviance for a given power parameter. Also add mean Poisson deviance `metrics.mean_poisson_deviance` and mean Gamma deviance `metrics.mean_gamma_deviance` that are special cases of the Tweedie deviance for power=1 and power=2 respectively. #13938 by Christian Lorentzen and Roman Yurchak.

- **[Efficiency]** Improved performance of `metrics.pairwise.manhattan_distances` in the case of sparse matrices. #15049 by Paolo Toccaeli <ptocca>.

- **[Enhancement]** The parameter `beta` in `metrics.fbeta_score` is updated to accept the zero and float('inf') value. #13231 by Dong-hee Na.

- **[Enhancement]** Added parameter `squared` in `metrics.mean_squared_error` to return root mean squared error. #13467 by Urvang Patel.

- **[Enhancement]** Allow computing averaged metrics in the case of no true positives. #14595 by Andreas Müller.

- **[Enhancement]** Multilabel metrics now supports list of lists as input. #14865 Srivatsan Ramesh, Herilalaina Rakotoarison, Léonard Binet.

- **[Enhancement]** `metrics.median_absolute_error` now supports multioutput parameter. #14732 by Agamemnon Krasoulis.

- **[Enhancement]** 'roc_auc_ovr_weighted' and 'roc_auc_ovo_weighted' can now be used as the `scoring` parameter of model-selection tools. #14417 by Thomas Fan.

- **[Enhancement]** `metrics.confusion_matrix` accepts a parameters normalize allowing to normalize the confusion matrix by column, rows, or overall. #15625 by Guillaume Lemaitre <glemaitre>.

- **[Fix]** Raise a ValueError in `metrics.silhouette_score` when a precomputed distance matrix contains non-zero diagonal entries. #12258 by Stephen Tierney.

- **[API Change]** `scoring="neg_brier_score"` should be used instead of `scoring="brier_score_loss"` which is now deprecated. #14898 by Stefan Matcovici.
sklearn.model_selection


- [Enhancement] `model_selection.learning_curve` now accepts parameter `return_times` which can be used to retrieve computation times in order to plot model scalability (see learning_curve example). #13938 by Hadrien Reboul.


- [Fix] Reimplemented `model_selection.StratifiedKFold` to fix an issue where one test set could be larger than another. Test sets should now be near-equally sized. #14704 by Joel Nothman.

- [Fix] The `cv_results_` attribute of `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` now only contains unfitted estimators. This potentially saves a lot of memory since the state of the estimators isn’t stored. #15096 by Andreas Müller.

- [API Change] `model_selection.KFold` and `model_selection.StratifiedKFold` now raise a warning if `random_state` is set but `shuffle` is False. This will raise an error in 0.24.

sklearn.multioutput

- [Fix] `multioutput.MultiOutputClassifier` now has attribute `classes_`. #14629 by Agamemnon Krasoulis.

- [Fix] `multioutput.MultiOutputClassifier` now has `predict_proba` as property and can be checked with `hasattr`. #15488 #15490 by Rebekah Kim

sklearn.naive_bayes

- [Major Feature] Added `naive_bayes.CategoricalNB` that implements the Categorical Naive Bayes classifier. #12569 by Tim Bicker and Florian Wilhelm.

sklearn.neighbors

- [Major Feature] Added `neighbors.KNeighborsTransformer` and `neighbors.RadiusNeighborsTransformer`, which transform input dataset into a sparse neighbors graph. They give finer control on nearest neighbors computations and enable easy pipeline caching for multiple use. #10482 by Tom Dupre la Tour.

- [Feature] `neighbors.KNeighborsClassifier`, `neighbors.KNeighborsRegressor`, `neighbors.RadiusNeighborsClassifier`, `neighbors.RadiusNeighborsRegressor`, and `neighbors.LocalOutlierFactor` now accept precomputed sparse neighbors graph as input. #10482 by Tom Dupre la Tour and Kumar Ashutosh.

- [Feature] `neighbors.RadiusNeighborsClassifier` now supports predicting probabilities by using `predict_proba` and supports more outlier_label options: 'most_frequent', or different outlier_labels for multi-outputs. #9597 by Wenbo Zhao.

• [Fix] `neighbors.KNeighborsRegressor` now throws error when `metric='precomputed'` and fit on non-square data. #14336 by Gregory Dexter.

**sklearn.neural_network**

• [Feature] Add `max_fun` parameter in `neural_network.BaseMultilayerPerceptron`, `neural_network.MLPRegressor`, and `neural_network.MLPClassifier` to give control over maximum number of function evaluation to not meet `tol` improvement. #9274 by Daniel Perry.

**sklearn.pipeline**

• [Enhancement] `pipeline.Pipeline` now supports `score_samples` if the final estimator does. #13806 by Anaël Beaugnon.

• [Fix] The fit in `FeatureUnion` now accepts `fit_params` to pass to the underlying transformers. #15119 by Adrin Jalali.

• [API Change] None as a transformer is now deprecated in `pipeline.FeatureUnion`. Please use 'drop' instead. #15053 by Thomas Fan.

**sklearn.preprocessing**

• [Efficiency] `preprocessing.PolynomialFeatures` is now faster when the input data is dense. #13290 by Xavier Dupré.


• [Fix] `KernelCenterer` now throws error when fit on non-square `preprocessing.KernelCenterer` #14336 by Gregory Dexter.

**sklearn.model_selection**

• [Fix] `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` now supports the `_pairwise` property, which prevents an error during cross-validation for estimators with pairwise inputs (such as `neighbors.KNeighborsClassifier` when `metric` is set to 'precomputed'). #13925 by Isaac S. Robson and #15524 by Xun Tang.

**sklearn.svm**

• [Enhancement] `svm.SVC` and `svm.NuSVC` now accept a `break_ties` parameter. This parameter results in `predict` breaking the ties according to the confidence values of `decision_function`, if `decision_function_shape='ovr'`, and the number of target classes > 2. #12557 by Adrin Jalali.

• [Enhancement] SVM estimators now throw a more specific error when `kernel='precomputed'` and fit on non-square data. #14336 by Gregory Dexter.

• [Fix] `svm.SVC, svm.SVR, svm.NuSVR` and `svm.OneClassSVM` when received values negative or zero for parameter `sample_weight` in method `fit()`, generated an invalid model. This behavior occurred only in some border scenarios. Now in these cases, `fit()` will fail with an Exception. #14286 by Alex Shacked.
• [Fix] The \texttt{n\_support} attribute of \texttt{svm.SVR} and \texttt{svm.OneClassSVM} was previously non-initialized, and
had size 2. It has now size 1 with the correct value. #15099 by Nicolas Hug.

• [Fix] fixed a bug in \texttt{BaseLibSVM\_\_sparse\_fit} where \texttt{n\_SV=0} raised a \texttt{ZeroDivisionError}. #14894 by
Danna Naser.

• [Fix] The liblinear solver now supports \texttt{sample\_weight}. #15038 by Guillaume Lemaitre.

\texttt{sklearn.tree}

• [Feature] Adds minimal cost complexity pruning, controlled by \texttt{ccp\_alpha}, to \texttt{tree. DecisionTreeClassifier}, \texttt{tree.DecisionTreeRegressor}, \texttt{tree.ExtraTreeClassifier},

• [API Change] \texttt{presort} is now deprecated in \texttt{tree.DecisionTreeClassifier} and \texttt{tree. DecisionTreeRegressor}, and the parameter has no effect. #14907 by Adrin Jalali.

• [API Change] The \texttt{classes\_} and \texttt{n\_classes\_} attributes of \texttt{tree.DecisionTreeRegressor} are now
deprecated. #15028 by Mei Guan, Nicolas Hug, and Adrin Jalali.

\texttt{sklearn.utils}

• [Feature] \texttt{check\_estimator} can now generate checks by setting \texttt{generate\_only=True}. Previously, running \texttt{check\_estimator} will stop when the first check fails. With \texttt{generate\_only=True}, all checks
can run independently and report the ones that are failing. Read more in \texttt{Rolling your own estimator}. #14381
by Thomas Fan.

• [Feature] Added a pytest specific decorator, \texttt{parametrize\_with\_checks}, to parametrize estimator
checks for a list of estimators. #14381 by Thomas Fan.

• [Feature] A new random variable, \texttt{utils\_fixes\_loguniform} implements a log-uniform random vari-
able (e.g., for use in \texttt{RandomizedSearchCV}). For example, the outcomes 1, 10 and 100 are all equally likely
for \texttt{loguniform(1, 100)}. See #11232 by Scott Sievert and Nathaniel Saul, and \texttt{SciPy PR 10815}
\url{https://github.com/scipy/scipy/pull/10815}.

• [Enhancement] \texttt{utils\_safe\_indexing} (now deprecated) accepts an \texttt{axis} parameter to index array-like
across rows and columns. The column indexing can be done on NumPy array, SciPy sparse matrix, and Pandas
DataFrame. An additional refactoring was done. #14035 and #14475 by Guillaume Lemaître.

• [Enhancement] \texttt{utils\_extmath\_safe\_sparse\_dot} works between 3D+ ndarray and sparse matrix.
#14538 by Jérémie du Boisberranger.

• [Fix] \texttt{utils\_check\_array} is now raising an error instead of casting \texttt{NaN} to integer. #14872 by
Roman Yurchak.

• [Fix] \texttt{utils\_check\_array} will now correctly detect numeric dtypes in pandas dataframes, fixing a bug
where \texttt{float32} was upcast to \texttt{float64} unnecessarily. #15094 by Andreas Müller.

• [API Change] The following \texttt{utils} have been deprecated and are now private:
  - \texttt{choose\_check\_classifiers\_labels}
  - \texttt{enforce\_estimator\_tags\_y}
  - \texttt{mocking\_MockDataFrame}
mocking.CheckingClassifier
- optimize.newton_cg
- random.random_choice_csc
- utils.choose_check_classifiers_labels
- utils.enforce_estimator_tags_y
- utils.optimize.newton_cg
- utils.random.random_choice_csc
- utils.safe_indexing
- utils.mocking
- utils.fast_dict
- utils.seq_dataset
- utils.weight_vector
- utils.fixes.parallel_helper (removed)
- All of utils.testing except for all_estimators which is now in utils.

sklearn.isotonic

- [FIX] Fixed a bug where isotonic.IsotonicRegression.fit raised error when X.dtype == 'float32' and X.dtype != y.dtype. #14902 by Lucas.

Miscellaneous

- [FIX] Port lobpcg from SciPy which implement some bug fixes but only available in 1.3+. #13609 and #14971 by Guillaume Lemaitre.
- [API CHANGE] Scikit-learn now converts any input data structure implementing a duck array to a numpy array (using __array__) to ensure consistent behavior instead of relying on __array_function__ (see NEP 18). #14702 by Andreas Müller.
- [API CHANGE] Replace manual checks with check_is_fitted. Errors thrown when using a non-fitted estimators are now more uniform. #13013 by Agamemnon Krasoulis.

Changes to estimator checks

These changes mostly affect library developers.

- Estimators are now expected to raise a NotFittedError if predict or transform is called before fit; previously an AttributeError or ValueError was acceptable. #13013 by Agamemnon Krasoulis.
- Binary only classifiers are now supported in estimator checks. Such classifiers need to have the binary_only=True estimator tag. #13875 by Trevor Stephens.
- Estimators are expected to convert input data (X, y, sample_weights) to numpy.ndarray and never call __array_function__ on the original datatype that is passed (see NEP 18). #14702 by Andreas Müller.
- requires_positive_X estimator tag (for models that require X to be non-negative) is now used by utils.estimator_checks.check_estimator to make sure a proper error message is raised if X contains some negative entries. #14680 by Alex Gramfort.

1.7. Release History
• Added check that pairwise estimators raise error on non-square data #14336 by Gregory Dexter.
• Added two common multioutput estimator tests check_classifier_multioutput and check_regressor_multioutput. #13392 by Rok Mihevc.
• [Fix] Added check_transformer_data_not_an_array to checks where missing
• [Fix] The estimators tags resolution now follows the regular MRO. They used to be overridable only once. #14884 by Andreas Müller.

Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.21, including:

1.7.8 Version 0.21.3

Legend for changelogs

- [Major Feature]: something big that you couldn’t do before.
- [Feature]: something that you couldn’t do before.
- [Efficiency]: an existing feature now may not require as much computation or memory.
- [Enhancement]: a miscellaneous minor improvement.
- [Fix]: something that previously didn’t work as documented – or according to reasonable expectations – should now work.
- [API Change]: you will need to change your code to have the same effect in the future; or a feature will be removed in the future.

July 30, 2019

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- The v0.20.0 release notes failed to mention a backwards incompatibility in `metrics.make_scorer` when `needs_proba=True` and `y_true` is binary. Now, the scorer function is supposed to accept a 1D `y_pred` (i.e., probability of the positive class, shape `(n_samples,)`), instead of a 2D `y_pred` (i.e., shape `(n_samples, 2)`).

Changelog

**sklearn.cluster**

- [Fix] Fixed a bug in `cluster.KMeans` where computation with `init='random'` was single threaded for `n_jobs > 1` or `n_jobs = -1`. #12955 by Prabakaran Kumaresshan.
- [Fix] Fixed a bug in `cluster.OPTICS` where users were unable to pass float `min_samples` and `min_cluster_size`. #14496 by Fabian Klopfer and Hanmin Qin.
- [Fix] Fixed a bug in `cluster.KMeans` where KMeans++ initialisation could rarely result in an IndexError. #11756 by Joel Nothman.

**sklearn.compose**

- [Fix] Fixed an issue in `compose.ColumnTransformer` where using DataFrames whose column order differs between :func:`fit` and :func:`transform` could lead to silently passing incorrect columns to the remainder transformer. #14237 by Andreas Schuderer <schuderer>.

1.7. Release History
sklearn.datasets

- [Fix] datasets.fetch_california_housing, datasets.fetch_covtype, datasets.fetch_kddcup99, datasets.fetch_olivetti_faces, datasets.fetch_rcv1, and datasets.fetch_species_distributions try to persist the previously cache using the new joblib if the cached data was persisted using the deprecated sklearn.externals.joblib. This behavior is set to be deprecated and removed in v0.23. #14197 by Adrin Jalali.

sklearn.ensemble


sklearn.impute

- [Fix] Fixed a bug in impute.SimpleImputer and impute.IterativeImputer so that no errors are thrown when there are missing values in training data. #13974 by Frank Hoang <fhoang7>.

sklearn.inspection

- [Fix] Fixed a bug in inspection.plot_partial_dependence where target parameter was not being taken into account for multiclass problems. #14393 by Guillem G. Subies.

sklearn.linear_model

- [Fix] Fixed a bug in linear_model.LogisticRegressionCV where refit=False would fail depending on the 'multiclass' and 'penalty' parameters (regression introduced in 0.21). #14087 by Nicolas Hug.

- [Fix] Compatibility fix for linear_model.ARDRegression and Scipy>=1.3.0. Adapts to upstream changes to the default pinvh cutoff threshold which otherwise results in poor accuracy in some cases. #14067 by Tim Staley.

sklearn.neighbors

- [Fix] Fixed a bug in neighbors.NeighborhoodComponentsAnalysis where the validation of initial parameters n_components, max_iter and tol required too strict types. #14092 by Jérémie du Boisberranger.
sklearn.tree

- [Fix] Fixed bug in tree.export_text when the tree has one feature and a single feature name is passed in. #14053 by Thomas Fan.
- [Fix] Fixed an issue with plot_tree where it displayed entropy calculations even for gini criterion in DecisionTreeClassifiers. #13947 by Frank Hoang.

1.7.9 Version 0.21.2

24 May 2019

Changelog

sklearn.decomposition

- [Fix] Fixed a bug in cross_decomposition.CCA improving numerical stability when $Y$ is close to zero. #13903 by Thomas Fan.

sklearn.metrics

- [Fix] Fixed a bug in metrics.pairwise.euclidean_distances where a part of the distance matrix was left un-instanciated for sufficiently large float32 datasets (regression introduced in 0.21). #13910 by Jérémie du Boisberranger.

sklearn.preprocessing

- [Fix] Fixed a bug in preprocessing.OneHotEncoder where the new drop parameter was not reflected in get_feature_names. #13894 by James Myatt.

sklearn.utils.sparsefuncs

- [Fix] Fixed a bug where min_max_axis would fail on 32-bit systems for certain large inputs. This affects preprocessing.MaxAbsScaler, preprocessing.normalize and preprocessing.LabelBinarizer. #13741 by Roddy MacSween.

1.7.10 Version 0.21.1

17 May 2019

This is a bug-fix release to primarily resolve some packaging issues in version 0.21.0. It also includes minor documentation improvements and some bug fixe.
Changelog

sklearn.inspection

• [Fix] Fixed a bug in `inspection.partial_dependence` to only check classifier and not regressor for the multiclass-multioutput case. #14309 by Guillaume Lemaitre.

sklearn.metrics

• [Fix] Fixed a bug in `metrics.pairwise_distances` where it would raise `AttributeError` for boolean metrics when \(X\) had a boolean dtype and \(Y == \text{None}\). #13864 by Paresh Mathur.
• [Fix] Fixed two bugs in `metrics.pairwise_distances` when \(n_{\text{jobs}} > 1\). First it used to return a distance matrix with same dtype as input, even for integer dtype. Then the diagonal was not zeros for euclidean metric when \(Y\) is \(X\). #13877 by Jérémie du Boisberranger.

sklearn.neighbors

• [Fix] Fixed a bug in `neighbors.KernelDensity` which could not be restored from a pickle if `sample_weight` had been used. #13772 by Aditya Vyas.

1.7.11 Version 0.21.0

May 2019

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

• `discriminant_analysis.LinearDiscriminantAnalysis` for multiclass classification. [Fix]
• `discriminant_analysis.LinearDiscriminantAnalysis` with 'eigen' solver. [Fix]
• `linear_model.BayesianRidge` [Fix]
• Decision trees and derived ensembles when both `max_depth` and `max_leaf_nodes` are set. [Fix]
• `linear_model.LogisticRegression` and `linear_model.LogisticRegressionCV` with 'saga' solver. [Fix]
• `ensemble.GradientBoostingClassifier` [Fix]
• `sklearn.feature_extraction.text.HashingVectorizer`, `sklearn.feature_extraction.text.TfidfVectorizer`, and `sklearn.feature_extraction.text.CountVectorizer` [Fix]
• `neural_network.MLPClassifier` [Fix]
• `svm.SVC.decision_function` and `multiclass.OneVsOneClassifier.decision_function`. [Fix]
• `linear_model.SGDClassifier` and any derived classifiers. [Fix]
• Any model using the `linear_model._sag.sag_solver` function with a `0` seed, including `linear_model.LogisticRegression`, `linear_model.LogisticRegressionCV`, `linear_model.Ridge`, and `linear_model.RidgeCV` with ‘sag’ solver. [Fix]

• `linear_model.RidgeCV` when using leave-one-out cross-validation with sparse inputs. [Fix]

Details are listed in the changelog below.

(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)

**Known Major Bugs**

• The default `max_iter` for `linear_model.LogisticRegression` is too small for many solvers given the default `tol`. In particular, we accidentally changed the default `max_iter` for the liblinear solver from 1000 to 100 iterations in #3591 released in version 0.16. In a future release we hope to choose better default `max_iter` and `tol` heuristically depending on the solver (see #13317).

**Changelog**

Support for Python 3.4 and below has been officially dropped.

**sklearn.base**

• [API Change] The R2 score used when calling `score` on a regressor will use `multioutput='uniform_average'` from version 0.23 to keep consistent with `metrics.r2_score`. This will influence the `score` method of all the multioutput regressors (except for `multioutput.MultiOutputRegressor`). #13157 by Hanmin Qin.

**sklearn.calibration**

• [Enhancement] Added support to bin the data passed into `calibration.calibration_curve` by quantiles instead of uniformly between 0 and 1. #13086 by Scott Cole.


**sklearn.cluster**

• [Major Feature] A new clustering algorithm: `cluster.OPTICS`: an algorithm related to `cluster.DBSCAN`, that has hyperparameters easier to set and that scales better, by Shane, Adrin Jalali, Erich Schubert, Hanmin Qin, and Assia Benbihi.

• [Fix] Fixed a bug where `cluster.Birch` could occasionally raise an AttributeError. #13651 by Joel Nothman.

• [Fix] Fixed a bug in `cluster.KMeans` where empty clusters weren’t correctly relocated when using sample weights. #13486 by Jérémy du Boisberranger.

• [API Change] The `n_components` attribute in `cluster.AgglomerativeClustering` and `cluster.FeatureAgglomeration` has been renamed to `n_connected_components`. #13427 by Stephane Couvreur.
• [**Enhancement**] `cluster.AgglomerativeClustering` and `cluster.FeatureAgglomeration` now accept a `distance_threshold` parameter which can be used to find the clusters instead of `n_clusters`. #9069 by Vathsala Achar and Adrin Jalali.

**sklearn.compose**

• [**API Change**] `compose.ColumnTransformer` is no longer an experimental feature. #13835 by Hanmin Qin.

**sklearn.datasets**

• [**Fix**] Added support for 64-bit group IDs and pointers in SVMLight files. #10727 by Bryan K Woods.
• [**Fix**] `datasets.load_sample_images` returns images with a deterministic order. #13250 by Thomas Fan.

**sklearn.decomposition**

• [**Enhancement**] `decomposition.KernelPCA` now has deterministic output (resolved sign ambiguity in eigenvalue decomposition of the kernel matrix). #13241 by Aurélien Bellet.
• [**Fix**] Fixed a bug in `decomposition.KernelPCA`, `fit().transform()` now produces the correct output (the same as `fit_transform()`) in case of non-removed zero eigenvalues (`remove_zero_eig=False`). `fit_inverse_transform` was also accelerated by using the same trick as `fit_transform` to compute the transform of X. #12143 by Sylvain Marié
• [**Fix**] Fixed a bug in `decomposition.KernelPCA` where `init = 'nndsvd', init = 'nndsvda', and init = 'nndsvdar'` are allowed when `n_components < n_features` instead of `n_components <= min(n_samples, n_features)`. #11650 by Hossein Pourbozorg and Zijie (ZJ) Poh.
• [**API Change**] The default value of the `init` argument in `decomposition.non_negative_factorization` will change from `random` to `None` in version 0.23 to make it consistent with `decomposition.NMF`. A FutureWarning is raised when the default value is used. #12988 by Zijie (ZJ) Poh.

**sklearn.discriminant_analysis**

• [**Enhancement**] `discriminant_analysis.LinearDiscriminantAnalysis` now preserves `float32` and `float64` dtypes. #8769 and #11000 by Thibault Sejourne
• [**Fix**] A ChangedBehaviourWarning is now raised when `discriminant_analysis.LinearDiscriminantAnalysis` is given as parameter `n_components > min(n_features, n_classes - 1)`, and `n_components` is changed to `min(n_features, n_classes - 1)` if so. Previously the change was made, but silently. #11526 by William de Vazelhes.
• [**Fix**] Fixed a bug in `discriminant_analysis.LinearDiscriminantAnalysis` where the predicted probabilities would be incorrectly computed in the multiclass case. #6848, by Agamemnon Krasoulis and Guillaume Lemaitre <glemaitre>.
• [**Fix**] Fixed a bug in `discriminant_analysis.LinearDiscriminantAnalysis` where the predicted probabilities would be incorrectly computed with `eigen` solver. #11727, by Agamemnon Krasoulis.
sklearn.dummy

- [Fix] Fixed a bug in `dummy.DummyClassifier` where the `predict_proba` method was returning int32 array instead of float64 for the stratified strategy. #13266 by Christos Aridas.
- [Fix] Fixed a bug in `dummy.DummyClassifier` where it was throwing a dimension mismatch error in prediction time if a column vector \( y \) with shape\((n, 1)\) was given at fit time. #13545 by Nick Sorros and Adrin Jalali.

sklearn.ensemble

- [Major Feature] Add two new implementations of gradient boosting trees: `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor`. The implementation of these estimators is inspired by LightGBM and can be orders of magnitude faster than `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier` when the number of samples is larger than tens of thousands of samples. The API of these new estimators is slightly different, and some of the features from `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor` are not yet supported.

These new estimators are experimental, which means that their results or their API might change without any deprecation cycle. To use them, you need to explicitly import `enable_hist_gradient_boosting`:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_hist_gradient_boosting
# noqa
>>> # now you can import normally from sklearn.ensemble
>>> from sklearn.ensemble import HistGradientBoostingClassifier
```

#12807 by Nicolas Hug.


- [Efficiency] Make `ensemble.IsolationForest` prefer threads over processes when running with \( n_{\text{jobs}} > 1 \) as the underlying decision tree fit calls do release the GIL. This changes reduces memory usage and communication overhead. #12543 by Isaac Storch and Olivier Grisel.

- [Efficiency] Make `ensemble.IsolationForest` more memory efficient by avoiding keeping in memory each tree prediction. #13260 by Nicolas Goix.

- [Efficiency] `ensemble.IsolationForest` now uses chunks of data at prediction step, thus capping the memory usage. #13283 by Nicolas Goix.

- [Efficiency] `sklearn.ensemble.GradientBoostingClassifier` and `sklearn.ensemble.GradientBoostingRegressor` now keep the input \( y \) as float64 to avoid it being copied internally by trees. #13524 by Adrin Jalali.


- [Enhancement] `ensemble.IsolationForest` now exposes `warm_start` parameter, allowing iterative addition of trees to an isolation forest. #13496 by Peter Marko.

  - sum up to 1
– all the single node trees in feature importance calculation are ignored

– in case all trees have only one single node (i.e. a root node), feature importances will be an array of all zeros.

#13636 and #13620 by Adrin Jalali.

• [FIX] Fixed a bug in `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor`, which didn’t support scikit-learn estimators as the initial estimator. Also added support of initial estimator which does not support sample weights. #12436 by Jérémie du Boisberranger and #12983 by Nicolas Hug.

• [FIX] Fixed the output of the average path length computed in `ensemble.IsolationForest` when the input is either 0, 1 or 2. #13251 by Albert Thomas and joshuakennethjones.

• [FIX] Fixed a bug in `ensemble.GradientBoostingClassifier` where the gradients would be incorrectly computed in multiclass classification problems. #12715 by Nicolas Hug.

• [FIX] Fixed a bug in `ensemble.GradientBoostingClassifier` where validation sets for early stopping were not sampled with stratification. #13164 by Nicolas Hug.

• [FIX] Fixed a bug in `ensemble.GradientBoostingClassifier` where the default initial prediction of a multiclass classifier would predict the classes priors instead of the log of the priors. #12983 by Nicolas Hug.

• [FIX] Fixed a bug in `ensemble.RandomForestClassifier` where the `predict` method would error for multiclass multioutput forests models if any targets were strings. #12834 by Elizabeth Sander.

• [FIX] Fixed a bug in `ensemble.gradient_boosting.LossFunction` and `ensemble.gradient_boosting.LeastSquaresError` where the default value of `learning_rate` in `update_terminal_regions` is not consistent with the document and the caller functions. Note however that directly using these loss functions is deprecated. #6463 by movelikeriver.

• [FIX] `ensemble.partial_dependence` (and consequently the new version `sklearn.inspection.partial_dependence`) now takes sample weights into account for the partial dependence computation when the gradient boosting model has been trained with sample weights. #13193 by Samuel O. Ronsin.

• [API CHANGE] `ensemble.partial_dependence` and `ensemble.plot_partial_dependence` are now deprecated in favor of `sklearn.inspection.partial_dependence` and `sklearn.inspection.plot_partial_dependence`. #12599 by Trevor Stephens and Nicolas Hug.

• [FIX] `ensemble.VotingClassifier` and `ensemble.VotingRegressor` were failing during `fit` in one of the estimators was set to None and `sample_weight` was not None. #13779 by Guillaume Lemaitre.

• [API CHANGE] `ensemble.VotingClassifier` and `ensemble.VotingRegressor` accept 'drop' to disable an estimator in addition to None to be consistent with other estimators (i.e., `pipeline.FeatureUnion` and `compose.ColumnTransformer`). #13780 by Guillaume Lemaitre.

`sklearn.externals`

• [API CHANGE] Deprecated `externals.six` since we have dropped support for Python 2.7. #12916 by Hanmin Qin.
sklearn.feature_extraction

- [Fix] If `input='file'` or `input='filename'`, and a callable is given as the analyzer, `sklearn.feature_extraction.text.HashingVectorizer`, `sklearn.feature_extraction.text.TfidfVectorizer`, and `sklearn.feature_extraction.text.CountVectorizer` now read the data from the file(s) and then pass it to the given analyzer, instead of passing the file name(s) or the file object(s) to the analyzer. #13641 by Adrin Jalali.

sklearn.impute

- [Major Feature] Added `impute.IterativeImputer`, which is a strategy for imputing missing values by modeling each feature with missing values as a function of other features in a round-robin fashion. #8478 and #12177 by Sergey Feldman and Ben Lawson.

The API of IterativeImputer is experimental and subject to change without any deprecation cycle. To use them, you need to explicitly import `enable_iterative_imputer`:

```python
>>> from sklearn.experimental import enable_iterative_imputer  # noqa
>>> from sklearn.impute import IterativeImputer
```

- [Feature] The `impute.SimpleImputer` and `impute.IterativeImputer` have a new parameter 'add_indicator', which simply stacks a `impute.MissingIndicator` transform into the output of the imputer's transform. That allows a predictive estimator to account for missingness. #12583, #13601 by Danylo Baibak.

- [Fix] In `impute.MissingIndicator` avoid implicit densification by raising an exception if input is sparse add `missing_values` property is set to 0. #13240 by Bartosz Telenczuk.

- [Fix] Fixed two bugs in `impute.MissingIndicator`. First, when `X` is sparse, all the non-zero non missing values used to become explicit False in the transformed data. Then, when `features='missing-only'`, all features used to be kept if there were no missing values at all. #13562 by Jérémie du Boisberranger.

sklearn.inspection

(new subpackage)

- [Feature] Partial dependence plots (`inspection.plot_partial_dependence`) are now supported for any regressor or classifier (provided that they have a `predict_proba` method). #12599 by Trevor Stephens and Nicolas Hug.

sklearn.isotonic

- [Feature] Allow different dtypes (such as float32) in `isotonic.IsotonicRegression`. #8769 by Vlad Niculae
sklearn.linear_model

- **[Enhancement]** `linear_model.Ridge` now preserves float32 and float64 dtypes. #8769 and #11000 by Guillaume Lemaitre, and Joan Massich
- **[Feature]** `linear_model.LogisticRegression` and `linear_model.LogisticRegressionCV` now support Elastic-Net penalty, with the ‘saga’ solver. #11646 by Nicolas Hug.
- **[Feature]** Added `linear_model.lars_path_gram`, which is `linear_model.lars_path` in the sufficient stats mode, allowing users to compute `linear_model.lars_path` without providing X and y. #11699 by Kuai Yu.
- **[Enhancement]** `linear_model.make_dataset` now preserves float32 and float64 dtypes, reducing memory consumption in stochastic gradient, SAG and SAGA solvers. #8769 and #11000 by Nelle Varoquaux, Arthur Imbert, Guillaume Lemaitre, and Joan Massich
- **[Enhancement]** `linear_model.LogisticRegression` now supports an unregularized objective when `penalty='none'` is passed. This is equivalent to setting `C=np.inf` with l2 regularization. Not supported by the liblinear solver. #12860 by Nicolas Hug.
- **[Enhancement]** sparse_cg solver in `linear_model.Ridge` now supports fitting the intercept (i.e. `fit_intercept=True`) when inputs are sparse. #13336 by Bartosz Telenczuk.
- **[Enhancement]** The coordinate descent solver used in Lasso, ElasticNet, etc. now issues a ConvergenceWarning when it completes without meeting the desired tolerance. #11754 and #13397 by Brent Fagan and Adrin Jalali.
- **[Fix]** Fixed a bug in `linear_model.LogisticRegression` and `linear_model.LogisticRegressionCV` with ‘saga’ solver, where the weights would not be correctly updated in some cases. #11646 by Tom Dupre la Tour.
- **[Fix]** Fixed the posterior mean, posterior covariance and returned regularization parameters in `linear_model.BayesianRidge`. The posterior mean and the posterior covariance were not the ones computed with the last update of the regularization parameters and the returned regularization parameters were not the final ones. Also fixed the formula of the log marginal likelihood used to compute the score when `compute_score=True`. #12174 by Albert Thomas.
- **[Fix]** Fixed a bug in `linear_model.LassoLarsIC`, where user input `copy_X=False` at instance creation would be overridden by default parameter value `copy_X=True` in fit. #12972 by Lucio Fernandez-Arjona
- **[Fix]** Fixed a bug in `linear_model.LinearRegression` that was not returning the same coefficients and intercepts with `fit_intercept=True` in sparse and dense case. #13279 by Alexandre Gramfort
- **[Fix]** Fixed a bug in `linear_model.HuberRegressor` that was broken when X was of dtype bool. #13328 by Alexandre Gramfort.
- **[Fix]** Fixed a performance issue of saga and sag solvers when called in a `joblib.Parallel` setting with `n_jobs > 1` and `backend="threading"`, causing them to perform worse than in the sequential case. #13389 by Pierre Glaser.
- **[Fix]** Fixed a bug in `linear_model.stochastic_gradient.BaseSGDClassifier` that was not deterministic when trained in a multi-class setting on several threads. #13422 by Clément Doumouro.
- **[Fix]** Fixed bug in `linear_model.ridge_regression`, `linear_model.Ridge` and `linear_model.RidgeClassifier` that caused unhandled exception for arguments `return_intercept=True` and `solver=auto` (default) or any other solver different from sag. #13363 by Bartosz Telenczuk
- **[Fix]** `linear_model.ridge_regression` will now raise an exception if `return_intercept=True` and solver is different from sag. Previously, only warning was issued. #13363 by Bartosz Telenczuk
• [Fix] \texttt{linear\_model.ridge\_regression} will choose \texttt{sparse\_cg} solver for sparse inputs when \texttt{solver=auto} and \texttt{sample\_weight} is provided (previously \texttt{cholesky} solver was selected). \#13363 by Bartosz Telenczuk

• [API Change] The use of \texttt{linear\_model.lars\_path} with \texttt{X=None} while passing \texttt{Gram} is deprecated in version 0.21 and will be removed in version 0.23. Use \texttt{linear\_model.lars\_path\_gram} instead. \#11699 by Kuai Yu.

• [API Change] \texttt{linear\_model.logistic\_regression\_path} is deprecated in version 0.21 and will be removed in version 0.23. \#12821 by Nicolas Hug.

• [Fix] \texttt{linear\_model.RidgeCV} with leave-one-out cross-validation now correctly fits an intercept when \texttt{fit\_intercept=True} and the design matrix is sparse. \#13350 by Jérôme Dockès

\texttt{sklearn.manifold}

• [Efficiency] Make \texttt{manifold.tsne.trustworthiness} use an inverted index instead of \texttt{np.where} lookup to find the rank of neighbors in the input space. This improves efficiency in particular when computed with lots of neighbors and/or small datasets. \#9907 by William de Vazelhes.

\texttt{sklearn.metrics}

• [Feature] Added the \texttt{metrics.max\_error} metric and a corresponding \texttt{'max\_error'} scorer for single output regression. \#12232 by Krishna Sangeeth.

• [Feature] Add \texttt{metrics.multilabel\_confusion\_matrix}, which calculates a confusion matrix with true positive, false positive, false negative and true negative counts for each class. This facilitates the calculation of set-wise metrics such as recall, specificity, fall out and miss rate. \#11179 by Shangwu Yao and Joel Nothman.

• [Feature] \texttt{metrics.jaccard\_score} has been added to calculate the Jaccard coefficient as an evaluation metric for binary, multilabel and multiclass tasks, with an interface analogous to \texttt{metrics.f1\_score}. \#13151 by Gaurav Dhingra and Joel Nothman.

• [Feature] Added \texttt{metrics.pairwise.haversine\_distances} which can be accessed with \texttt{metric='pairwise'} through \texttt{metrics.pairwise\_distances} and estimators. (Haversine distance was previously available for nearest neighbors calculation.) \#12568 by Wei Xue, Emmanuel Arias and Joel Nothman.

• [Efficiency] Faster \texttt{metrics.pairwise\_distances} with \texttt{n\_jobs>1} by using a thread-based backend, instead of process-based backends. \#8216 by Pierre Glaser and Romuald Menuet

• [Efficiency] The pairwise manhattan distances with sparse input now uses the BLAS shipped with scipy instead of the bundled BLAS. \#12732 by Jérémie du Boisberranger

• [Enhancement] Use label \texttt{accuracy} instead of \texttt{micro\_average} on \texttt{metrics.classification\_report} to avoid confusion. \texttt{micro\_average} is only shown for multi-label or multi-class with a subset of classes because it is otherwise identical to \texttt{accuracy}. \#12334 by Emmanuel Arias, Joel Nothman and Andreas Müller

• [Enhancement] Added \texttt{beta} parameter to \texttt{metrics.homogeneity\_completeness\_v\_measure} and \texttt{metrics.v\_measure\_score} to configure the tradeoff between homogeneity and completeness. \#13607 by Stephane Couvreur and and Ivan Sanchez.

• [Fix] The metric \texttt{metrics.r2\_score} is degenerate with a single sample and now it returns NaN and raises \texttt{exceptions.UndefinedMetricWarning}. \#12855 by Pawel Sendyk.

• [Fix] Fixed a bug where \texttt{metrics.brier\_score\_loss} will sometimes return incorrect result when there's only one class in \texttt{y\_true}. \#13628 by Hanmin Qin.
• [Fix] Fixed a bug in `metrics.label_ranking_average_precision_score` where `sample_weight` wasn’t taken into account for samples with degenerate labels. #13447 by Dan Ellis.

• [API Change] The parameter `labels` in `metrics.hamming_loss` is deprecated in version 0.21 and will be removed in version 0.23. #10580 by Reshma Shaikh and Sandra Mitrovic.

• [Fix] The function `metrics.pairwise.euclidean_distances`, and therefore several estimators with `metric='euclidean'`, suffered from numerical precision issues with `float32` features. Precision has been increased at the cost of a small drop of performance. #13554 by @Celelibi and Jérémie du Boisberranger.

• [API Change] `metrics.jaccard_similarity_score` is deprecated in favour of the more consistent `metrics.jaccard_score`. The former behavior for binary and multiclass targets is broken. #13151 by Joel Nothman.

**sklearn.mixture**

• [Fix] Fixed a bug in `mixture.BaseMixture` and therefore on estimators based on it, i.e. `mixture.GaussianMixture` and `mixture.BayesianGaussianMixture`, where `fit_predict` and `fit.predict` were not equivalent. #13142 by Jérémie du Boisberranger.

**sklearn.model_selection**

• [Feature] Classes `GridSearchCV` and `RandomizedSearchCV` now allow for `refit=callable` to add flexibility in identifying the best estimator. See Balance model complexity and cross-validated score. #11354 by Wenhao Zhang, Joel Nothman and Adrin Jalali.

• [Enhancement] Classes `GridSearchCV`, `RandomizedSearchCV`, and methods `cross_val_score`, `cross_val_predict`, `cross_validate`, now print train scores when `return_train_scores` is True and `verbose > 2`. For `learning_curve`, and `validation_curve` only the latter is required. #12613 and #12669 by Marc Torrellas.

• [Enhancement] Some `CV splitter` classes and `model_selection.train_test_split` now raise `ValueError` when the resulting training set is empty. #12861 by Nicolas Hug.

• [Fix] Fixed a bug where `model_selection.StratifiedKFold` shuffles each class’s samples with the same `random_state`, making `shuffle=True` ineffective. #13124 by Hanmin Qin.

• [Fix] Added ability for `model_selection.cross_val_predict` to handle multi-label (and multilabel-multiclass) targets with `predict_proba-type` methods. #8773 by Stephen Hoover.

• [Fix] Fixed an issue in `cross_val_predict` where `method="predict_proba"` returned always 0.0 when one of the classes was excluded in a cross-validation fold. #13366 by Guillaume Fournier.

**sklearn.multiclass**

• [Fix] Fixed an issue in `multiclass.OneVsOneClassifier.decision_function` where the decision_function value of a given sample was different depending on whether the decision_function was evaluated on the sample alone or on a batch containing this same sample due to the scaling used in decision_function. #10440 by Jonathan Ohayon.
sklearn.multioutput

• [Fix] Fixed a bug in `multioutput.MultiOutputClassifier` where the `predict_proba` method incorrectly checked for `predict_proba` attribute in the estimator object. #12222 by Rebekah Kim

sklearn.neighbors

• [Major Feature] Added `neighbors.NeighborhoodComponentsAnalysis` for metric learning, which implements the Neighborhood Components Analysis algorithm. #10058 by William de Vazelhes and John Chiotellis.


sklearn.neural_network

• [Fix] Fixed a bug in `neural_network.MLPClassifier` and `neural_network.MLPRegressor` where the option `shuffle=False` was being ignored. #12582 by Sam Waterbury.

• [Fix] Fixed a bug in `neural_network.MLPClassifier` where validation sets for early stopping were not sampled with stratification. In the multilabel case however, splits are still not stratified. #13164 by Nicolas Hug.

sklearn.pipeline

• [Feature] `pipeline.Pipeline` can now use indexing notation (e.g. `my_pipeline[0:-1]`) to extract a subsequence of steps as another Pipeline instance. A Pipeline can also be indexed directly to extract a particular step (e.g. `my_pipeline['svc']`), rather than accessing `named_steps`. #2568 by Joel Nothman.

• [Feature] Added optional parameter `verbose` in `pipeline.Pipeline`, `compose.ColumnTransformer` and `pipeline.FeatureUnion` and corresponding `make_` helpers for showing progress and timing of each step. #11364 by Baze Petrushev, Karan Desai, Joel Nothman, and Thomas Fan.

• [Enhancement] `pipeline.Pipeline` now supports using `passthrough` as a transformer, with the same effect as `None`. #11144 by Thomas Fan.

• [Enhancement] `pipeline.Pipeline` implements `__len__` and therefore `len(pipeline)` returns the number of steps in the pipeline. #13439 by Lakshya KD.

sklearn.preprocessing

• [Feature] `preprocessing.OneHotEncoder` now supports dropping one feature per category with a new drop parameter. #12908 by Drew Johnston.

• [Efficiency] `preprocessing.OneHotEncoder` and `preprocessing.OrdinalEncoder` now handle pandas DataFrames more efficiently. #13253 by @maikia.

• [Efficiency] Make `preprocessing.MultiLabelBinarizer` cache class mappings instead of calculating it every time on the fly. #12116 by Ekaterina Krivich and Joel Nothman.

• [Efficiency] `preprocessing.PolynomialFeatures` now supports compressed sparse row (CSR) matrices as input for degrees 2 and 3. This is typically much faster than the dense case as it scales with matrix density and expansion degree (on the order of density^degree), and is much, much faster than the compressed sparse column (CSC) case. #12197 by Andrew Nystrom.
• [EFFICIENCY] Speed improvement in `preprocessing.PolynomialFeatures`, in the dense case. Also added a new parameter `order` which controls output order for further speed performances. #12251 by Tom Dupre la Tour.

• [FIX] Fixed the calculation overflow when using a float16 dtype with `preprocessing.StandardScaler`. #13007 by Raffaello Baluyot

• [FIX] Fixed a bug in `preprocessing.QuantileTransformer` and `preprocessing.quantile_transform` to force `n_quantiles` to be at most equal to `n_samples`. Values of `n_quantiles` larger than `n_samples` were either useless or resulting in a wrong approximation of the cumulative distribution function estimator. #13333 by Albert Thomas.

• [API CHANGE] The default value of `copy` in `preprocessing.quantile_transform` will change from False to True in 0.23 in order to make it more consistent with the default `copy` values of other functions in `preprocessing` and prevent unexpected side effects by modifying the value of `X` inplace. #13459 by Hunter McGushion.

**sklearn.svm**

• [FIX] Fixed an issue in `svm.SVC.decision_function` when `decision_function_shape='ovr'`. The decision_function value of a given sample was different depending on whether the decision_function was evaluated on the sample alone or on a batch containing this same sample due to the scaling used in decision_function. #10440 by Jonathan Ohayon.

**sklearn.tree**

• [FEATURE] Decision Trees can now be plotted with matplotlib using `tree.plot_tree` without relying on the dot library, removing a hard-to-install dependency. #8508 by Andreas Müller.

• [FEATURE] Decision Trees can now be exported in a human readable textual format using `tree.export_text`. #6261 by Giuseppe Vettigli <JustGlowing>.

• [FEATURE] `get_n_leaves()` and `get_depth()` have been added to `tree.BaseDecisionTree` and consequently all estimators based on it, including `tree.DecisionTreeClassifier`, `tree.DecisionTreeRegressor`, `tree.ExtraTreeClassifier`, and `tree.ExtraTreeRegressor`. #12300 by Adrin Jalali.

• [FIX] Trees and forests did not previously predict multi-output classification targets with string labels, despite accepting them in `fit`. #11458 by Mitar Milutinovic.

• [FIX] Fixed an issue with `tree.BaseDecisionTree` and consequently all estimators based on it, including `tree.DecisionTreeClassifier`, `tree.DecisionTreeRegressor`, `tree.ExtraTreeClassifier`, and `tree.ExtraTreeRegressor`, where they used to exceed the given `max_depth` by 1 while expanding the tree if `max_leaf_nodes` and `max_depth` were both specified by the user. Please note that this also affects all ensemble methods using decision trees. #12344 by Adrin Jalali.
sklearn.utils

- **[FEATURE]** `utils.resample` now accepts a `stratify` parameter for sampling according to class distributions. #13549 by Nicolas Hug.

- **[API CHANGE]** Deprecated `warn_on_dtype` parameter from `utils.check_array` and `utils.check_X_y`. Added explicit warning for dtype conversion in `check_pairwise_arrays` if the metric being passed is a pairwise boolean metric. #13382 by Prathmesh Savale.

Multiple modules

- **[MAJOR FEATURE]** The `__repr__()` method of all estimators (used when calling `print(estimator)`) has been entirely re-written, building on Python’s pretty printing standard library. All parameters are printed by default, but this can be altered with the `print_changed_only` option in `sklearn.set_config`. #11705 by Nicolas Hug.

- **[MAJOR FEATURE]** Add estimators tags: these are annotations of estimators that allow programmatic inspection of their capabilities, such as sparse matrix support, supported output types and supported methods. Estimator tags also determine the tests that are run on an estimator when `check_estimator` is called. Read more in the User Guide. #8022 by Andreas Müller.

- **[Efficiency]** Memory copies are avoided when casting arrays to a different dtype in multiple estimators. #11973 by Roman Yurchak.

- **[Fix]** Fixed a bug in the implementation of the `our_rand_r` helper function that was not behaving consistently across platforms. #13422 by Madhura Parikh and Clément Doumouro.

Miscellaneous

- **[Enhancement]** Joblib is no longer vendored in scikit-learn, and becomes a dependency. Minimal supported version is joblib 0.11, however using version >= 0.13 is strongly recommended. #13531 by Roman Yurchak.

Changes to estimator checks

These changes mostly affect library developers.

- Add `check_fit_idempotent` to `check_estimator`, which checks that when `fit` is called twice with the same data, the output of `predict`, `predict_proba`, `transform`, and `decision_function` does not change. #12328 by Nicolas Hug

- Many checks can now be disabled or configured with `Estimator Tags`. #8022 by Andreas Müller.

Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.20, including:

adanhawth, Aditya Vyas, Adrin Jalali, Agamemnon Krasoulis, Albert Thomas, Alberto Torres, Alexandre Gramfort, amourav, Andrea Navarrete, Andreas Mueller, Andrew Nystrom, assiaben, Aurélien Bellet, Bartosz Michalowski, Bartosz Telenczuk, baurs, BenjaStudio, bertrandhaut, Bharat Raghunathan, brentfagan, Bryan Woods, Cat Chenal, Cheuk Ting Ho, Chris Choe, Christos Aridas, Clément Doumouro, Cole Smith, Connossor, Corey Levinson, Dan Ellis, Dan Stine, Danylo Baibak, data-kekie, Denis Kataev, Didi Bar-Zev, Dillon Gardner, Dmitry Mottl, Dmitry Vukolov, Dougal J. Sutherland, Dowon, drewjohnston, Dror Atariah, Edward J Brown, Ekaterina Krivich, Elizabeth Sander, Emmanuel Arias, Eric Chang, Eric Larson, Erich Schubert, esvh, Falak, Feda Curic, Federico Caselli,
This is a bug-fix release with some bug fixes applied to version 0.20.3.

Changelog

The bundled version of joblib was upgraded from 0.13.0 to 0.13.2.

**sklearn.cluster**

- [Fix] Fixed a bug in *cluster.KMeans* where KMeans++ initialisation could rarely result in an IndexError. #11756 by Joel Nothman.

**sklearn.compose**

- [Fix] Fixed an issue in *compose.ColumnTransformer* where using DataFrames whose column order differs between :func:`fit` and :func:`transform` could lead to silently passing incorrect columns to the remainder transformer. #14237 by Andreas Schuderer <schuderer>.
sklearn.decomposition

• [Fix] Fixed a bug in cross_decomposition.CCA improving numerical stability when Y is close to zero. #13903 by Thomas Fan.

sklearn.model_selection

• [Fix] Fixed a bug where model_selection.StratifiedKFold shuffles each class’s samples with the same random_state, making shuffle=True ineffective. #13124 by Hanmin Qin.

sklearn.neighbors

• [Fix] Fixed a bug in neighbors.KernelDensity which could not be restored from a pickle if sample_weight had been used. #13772 by Aditya Vyas.

1.7.13 Version 0.20.3

March 1, 2019

This is a bug-fix release with some minor documentation improvements and enhancements to features released in 0.20.0.

Changelog

sklearn.cluster

• [Fix] Fixed a bug in cluster.KMeans where computation was single threaded when n_jobs > 1 or n_jobs = -1. #12949 by Prabakaran Kumaresshan.

sklearn.compose

• [Fix] Fixed a bug in compose.ColumnTransformer to handle negative indexes in the columns list of the transformers. #12946 by Pierre Tallotte.

sklearn.covariance

• [Fix] Fixed a regression in covariance.graphical_lasso so that the case n_features=2 is handled correctly. #13276 by Aurélien Bellet.
• [Fix] Fixed a bug in `decomposition.sparse_encode` where computation was single threaded when `n_jobs > 1` or `n_jobs = -1`. #13005 by Prabakaran Kumaresshan.

**sklearn.datasets**

• [Efficiency] `sklearn.datasets.fetch_openml` now loads data by streaming, avoiding high memory usage. #13312 by Joris Van den Bossche.

**sklearn.feature_extraction**

• [Fix] Fixed a bug in `feature_extraction.text.CountVectorizer` which would result in the sparse feature matrix having conflicting `indptr` and `indices` precisions under very large vocabularies. #11295 by Gabriel Vacaliuc.

**sklearn.impute**

• [Fix] add support for non-numeric data in `sklearn.impute.MissingIndicator` which was not supported while `sklearn.impute.SimpleImputer` was supporting this for some imputation strategies. #13046 by Guillaume Lemaitre.

**sklearn.linear_model**

• [Fix] Fixed a bug in `linear_model.MultiTaskElasticNet` and `linear_model.MultiTaskLasso` which were breaking when `warm_start = True`. #12360 by Aakanksha Joshi.

**sklearn.preprocessing**

• [Fix] Fixed a bug in `preprocessing.KBinsDiscretizer` where strategy='kmeans' fails with an error during transformation due to unsorted bin edges. #13134 by Sandro Casagrande.

• [Fix] Fixed a bug in `preprocessing.OneHotEncoder` where the deprecation of `categorical_features` was handled incorrectly in combination with `handle_unknown='ignore'`. #12881 by Joris Van den Bossche.

• [Fix] Bins whose width are too small (i.e., \( \leq 1e-8 \)) are removed with a warning in `preprocessing.KBinsDiscretizer`. #13165 by Hanmin Qin.

**sklearn.svm**

• [Fix] Fixed a bug in `svm.SVC`, `svm.NuSVC`, `svm.SVR`, `svm.NuSVR` and `svm.OneClassSVM` where the `scale` option of parameter `gamma` is erroneously defined as \( 1 / (n_{features} \times X.std()) \). It's now defined as \( 1 / (n_{features} \times X.var()) \). #13221 by Hanmin Qin.
1.7.14 Version 0.20.2

December 20, 2018

This is a bug-fix release with some minor documentation improvements and enhancements to features released in 0.20.0.

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- `sklearn.neighbors` when `metric='jaccard'` (bug fix)
- use of 'seuclidean' or 'mahalanobis' metrics in some cases (bug fix)

Changelog

**sklearn.compose**

- [Fix] Fixed an issue in `compose.make_column_transformer` which raises unexpected error when columns is pandas Index or pandas Series. #12704 by Hanmin Qin.

**sklearn.metrics**

- [Fix] Fixed a bug in `metrics.pairwise_distances` and `metrics.pairwise_distances_chunked` where parameters \( V \) of "seuclidean" and \( VI \) of "mahalanobis" metrics were computed after the data was split into chunks instead of being pre-computed on whole data. #12701 by Jeremie du Boisberranger.
sklearn.neighbors

- [Fix] Fixed `sklearn.neighbors.DistanceMetric.jaccard` distance function to return 0 when two all-zero vectors are compared. #12685 by Thomas Fan.

sklearn.utils

- [Fix] Calling `utils.check_array` on `pandas.Series` with categorical data, which raised an error in 0.20.0, now returns the expected output again. #12699 by Joris Van den Bossche.

Code and Documentation Contributors

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adanhawth, Adrin Jalali, Albert Thomas, Andreas Mueller, Dan Stine, Feda Curic, Hanmin Qin, Jan S, jeremiedbb, Joel Nothman, Joris Van den Bossche, josephsalmon, Katrin Leinweber, Loic Esteve, Muhammad Hassaan Rafique, Nicolas Hug, Olivier Grisel, Paul Paczuski, Reshama Shaikh, Sam Waterbury, Shivam Kotwalia, Thomas Fan

1.7.15 Version 0.20.1

November 21, 2018

This is a bug-fix release with some minor documentation improvements and enhancements to features released in 0.20.0. Note that we also include some API changes in this release, so you might get some extra warnings after updating from 0.20.0 to 0.20.1.

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- `decomposition.IncrementalPCA` (bug fix)

Changelog

sklearn.cluster

- [Efficiency] make `cluster.MeanShift` no longer try to do nested parallelism as the overhead would hurt performance significantly when `n_jobs > 1`. #12159 by Olivier Grisel.
- [Fix] Fixed a bug in `cluster.DBSCAN` with precomputed sparse neighbors graph, which would add explicitly zeros on the diagonal even when already present. #12105 by Tom Dupre la Tour.
sklearn.compose

• [Fix] Fixed an issue in `compose.ColumnTransformer` when stacking columns with types not convertible to a numeric. #11912 by Adrin Jalali.

• [API CHANGE] `compose.ColumnTransformer` now applies the `sparse_threshold` even if all transformation results are sparse. #12304 by Andreas Müller.

• [API CHANGE] `compose.make_column_transformer` now expects `(transformer, columns)` instead of `(columns, transformer)` to keep consistent with `compose.ColumnTransformer`. #12339 by Adrin Jalali.

datasets

• [Fix] `datasets.fetch_openml` to correctly use the local cache. #12246 by Jan N. van Rijn.

• [Fix] `datasets.fetch_openml` to correctly handle ignore attributes and row id attributes. #12330 by Jan N. van Rijn.

• [Fix] Fixed integer overflow in `datasets.make_classification` for values of `n_informative` parameter larger than 64. #10811 by Roman Feldbauer.

• [Fix] Fixed olivetti faces dataset `DESCR` attribute to point to the right location in `datasets.fetch_olivetti_faces`. #12441 by Jérémie du Boisberranger

• [Fix] `datasets.fetch_openml` to retry downloading when reading from local cache fails. #12517 by Thomas Fan.

decomposition

• [Fix] Fixed a regression in `decomposition.IncrementalPCA` where 0.20.0 raised an error if the number of samples in the final batch for fitting IncrementalPCA was smaller than `n_components`. #12234 by Ming Li.

ensemble

• [Fix] Fixed a bug mostly affecting `ensemble.RandomForestClassifier` where class_weight='balanced_subsample' failed with more than 32 classes. #12165 by Joel Nothman.

• [Fix] Fixed a bug affecting `ensemble.BaggingClassifier`, `ensemble.BaggingRegressor` and `ensemble.IsolationForest`, where max_features was sometimes rounded down to zero. #12388 by Connor Tann.

feature_extraction

• [Fix] Fixed a regression in v0.20.0 where `feature_extraction.text.CountVectorizer` and other text vectorizers could error during stop words validation with custom preprocessors or tokenizers. #12393 by Roman Yurchak.
sklearn.linear_model

- [Fix] *linear_model.SGDClassifier* and variants with *early_stopping=True* would not use a consistent validation split in the multiclass case and this would cause a crash when using those estimators as part of parallel parameter search or cross-validation. #12122 by Olivier Grisel.

- [Fix] Fixed a bug affecting *SGDClassifier* in the multiclass case. Each one-versus-all step is run in a *joblib.Parallel* call and mutating a common parameter, causing a segmentation fault if called within a backend using processes and not threads. We now use *require=sharedmem* at the *joblib.Parallel* instance creation. #12518 by Pierre Glaser and Olivier Grisel.

sklearn.metrics

- [Fix] Fixed a bug in *metrics.pairwise.pairwise_distances_argmin_min* which returned the square root of the distance when the metric parameter was set to “euclidean”. #12481 by Jérémie du Boisberranger.

- [Fix] Fixed a bug in *metrics.pairwise.pairwise_distances_chunked* which didn’t ensure the diagonal is zero for euclidean distances. #12612 by Andreas Müller.

  - [API CHANGE] The *metrics.calinski_harabaz_score* has been renamed to *metrics.calinski_harabasz_score* and will be removed in version 0.23. #12211 by Lisa Thomas, Mark Hannel and Melissa Ferrari.

sklearn.mixture

- [Fix] Ensure that the *fit_predict* method of *mixture.GaussianMixture* and *mixture.BayesianGaussianMixture* always yield assignments consistent with *fit* followed by *predict* even if the convergence criterion is too loose or not met. #12451 by Olivier Grisel.

sklearn.neighbors

- [Fix] force the parallelism backend to *threading* for *neighbors.KDTree* and *neighbors.BallTree* in Python 2.7 to avoid pickling errors caused by the serialization of their methods. #12171 by Thomas Moreau.

sklearn.preprocessing


- [Fix] Fixed bug in *preprocessing.KBinsDiscretizer* where the *transform* method mutates the _encoder attribute. The *transform* method is now thread safe. #12514 by Hanmin Qin.

- [Fix] Fixed a bug in *preprocessing.PowerTransformer* where the Yeo-Johnson transform was incorrect for lambda parameters outside of [0, 2] #12522 by Nicolas Hug.

- [Fix] Fixed a bug in *preprocessing.OneHotEncoder* where transform failed when set to ignore unknown numpy strings of different lengths #12471 by Gabriel Marzinotto.

  - [API CHANGE] The default value of the *method* argument in *preprocessing.power_transform* will be changed from *box-cox* to *yeo-johnson* to match *preprocessing.PowerTransformer* in version 0.23. A FutureWarning is raised when the default value is used. #12317 by Eric Chang.
sklearn.utils

- [Fix] Use float64 for mean accumulator to avoid floating point precision issues in preprocessing. StandardScaler and decomposition.IncrementalPCA when using float32 datasets. #12338 by bauks.

- [Fix] Calling utils.check_array on pandas.Series, which raised an error in 0.20.0, now returns the expected output again. #12625 by Andreas Müller

Miscellaneous

- [Fix] When using site joblib by setting the environment variable SKLEARN_SITE_JOBLIB, added compatibility with joblib 0.11 in addition to 0.12+. #12350 by Joel Nothman and Roman Yurchak.

- [Fix] Make sure to avoid raising FutureWarning when calling np.vstack with numpy 1.16 and later (use list comprehensions instead of generator expressions in many locations of the scikit-learn code base). #12467 by Olivier Grisel.

- [API CHANGE] Removed all mentions of sklearn.externals.joblib, and deprecated joblib methods exposed in sklearn.utils, except for utils.parallel_backend and utils.register_parallel_backend, which allow users to configure parallel computation in scikit-learn. Other functionalities are part of joblib package and should be used directly, by installing it. The goal of this change is to prepare for unvendoring joblib in future version of scikit-learn. #12345 by Thomas Moreau

Code and Documentation Contributors

With thanks to:

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1.7.16 Version 0.20.0

September 25, 2018

This release packs in a mountain of bug fixes, features and enhancements for the Scikit-learn library, and improvements to the documentation and examples. Thanks to our contributors!

This release is dedicated to the memory of Raghav Rajagopalan.

**Warning:** Version 0.20 is the last version of scikit-learn to support Python 2.7 and Python 3.4. Scikit-learn 0.21 will require Python 3.5 or higher.
Highlights

We have tried to improve our support for common data-science use-cases including missing values, categorical variables, heterogeneous data, and features/targets with unusual distributions. Missing values in features, represented by NaNs, are now accepted in column-wise preprocessing such as scalers. Each feature is fitted disregarding NaNs, and data containing NaNs can be transformed. The new `impute` module provides estimators for learning despite missing data.

`ColumnTransformer` handles the case where different features or columns of a pandas.DataFrame need different preprocessing. String or pandas Categorical columns can now be encoded with `OneHotEncoder` or `OrdinalEncoder`.

`TransformedTargetRegressor` helps when the regression target needs to be transformed to be modeled. `PowerTransformer` and `KBinsDiscretizer` join `QuantileTransformer` as non-linear transformations.

Beyond this, we have added `sample_weight` support to several estimators (including `KMeans`, `BayesianRidge` and `KernelDensity`) and improved stopping criteria in others (including `MLPRegressor`, `GradientBoostingRegressor` and `SGDRegressor`).

This release is also the first to be accompanied by a **Glossary of Common Terms and API Elements** developed by Joel Nothman. The glossary is a reference resource to help users and contributors become familiar with the terminology and conventions used in Scikit-learn.

Sorry if your contribution didn’t make it into the highlights. There’s a lot here…

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- `cluster.MeanShift` (bug fix)
- `decomposition.IncrementalPCA` in Python 2 (bug fix)
- `decomposition.SparsePCA` (bug fix)
- `ensemble.GradientBoostingClassifier` (bug fix affecting feature importances)
- `isotonic.IsotonicRegression` (bug fix)
- `linear_model.ARDRegression` (bug fix)
- `linear_model.LogisticRegressionCV` (bug fix)
- `linear_model.OrthogonalMatchingPursuit` (bug fix)
- `linear_model.PassiveAggressiveClassifier` (bug fix)
- `linear_model.PassiveAggressiveRegressor` (bug fix)
- `linear_model.Perceptron` (bug fix)
- `linear_model.SGDClassifier` (bug fix)
- `linear_model.SGDRegressor` (bug fix)
- `metrics.roc_auc_score` (bug fix)
- `metrics.roc_curve` (bug fix)
- `neural_network.BaseMultilayerPerceptron` (bug fix)
- `neural_network.MLPClassifier` (bug fix)
• `neural_network.MLPRegressor` (bug fix)
  • The v0.19.0 release notes failed to mention a backwards incompatibility with `model_selection.StratifiedKFold` when `shuffle=True` due to #7823.

Details are listed in the changelog below.

(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)

### Known Major Bugs

- #11924: `linear_model.LogisticRegressionCV` with `solver='lbfgs'` and `multi_class='multinomial'` may be non-deterministic or otherwise broken on macOS. This appears to be the case on Travis CI servers, but has not been confirmed on personal MacBooks! This issue has been present in previous releases.

- #9354: `metrics.pairwise.euclidean_distances` (which is used several times throughout the library) gives results with poor precision, which particularly affects its use with 32-bit float inputs. This became more problematic in versions 0.18 and 0.19 when some algorithms were changed to avoid casting 32-bit data into 64-bit.

### Changelog

Support for Python 3.3 has been officially dropped.

`sklearn.cluster`

- [Major Feature] `cluster.AgglomerativeClustering` now supports Single Linkage clustering via `linkage='single'`. #9372 by Leland McInnes and Steve Astels.
- [Efficiency] `cluster.DBSCAN` now is parallelized according to `n_jobs` regardless of `algorithm`. #8003 by Joel Billaud.
- [Enhancement] `cluster.KMeans` now gives a warning if the number of distinct clusters found is smaller than `n_clusters`. This may occur when the number of distinct points in the data set is actually smaller than the number of cluster one is looking for. #10059 by Christian Braune.
- [Fix] Fixed a bug where the `fit` method of `cluster.AffinityPropagation` stored cluster centers as 3d array instead of 2d array in case of non-convergence. For the same class, fixed undefined and arbitrary behavior in case of training data where all samples had equal similarity. #9612. By Jonatan Samoocha.
- [Fix] Fixed a bug in `cluster.spectral_clustering` where the normalization of the spectrum was using a division instead of a multiplication. #8129 by Jan Margera, Guillaume Lemaitre, and Devansh D.
- [Fix] Fixed a bug in `cluster.k_means_elkan` where the returned iteration was 1 less than the correct value. Also added the missing `n_iter_` attribute in the docstring of `cluster.KMeans`. #11353 by Jeremie du Boisberranger.
- [Fix] Fixed a bug in `cluster.mean_shift` where the assigned labels were not deterministic if there were multiple clusters with the same intensities. #11901 by Adrin Jalali.

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• [API CHANGE] Deprecate pooling_func unused parameter in cluster. AgglomerativeClustering. #9875 by Kumar Ashutosh.

sklearn.compose

• New module.

• [MAJOR FEATURE] Added compose.ColumnTransformer, which allows to apply different transformers to different columns of arrays or pandas DataFrames. #9012 by Andreas Müller and Joris Van den Bossche, and #11315 by Thomas Fan.

• [MAJOR FEATURE] Added the compose.TransformedTargetRegressor which transforms the target y before fitting a regression model. The predictions are mapped back to the original space via an inverse transform. #9041 by Andreas Müller and Guillaume Lemaitre.

sklearn.covariance

• [EFFICIENCY] Runtime improvements to covariance.GraphicalLasso. #9858 by Steven Brown.

• [API CHANGE] The covariance.graph_lasso, covariance.GraphLasso and covariance.GraphLassoCV have been renamed to covariance.graphical_lasso, covariance.GraphicalLasso and covariance.GraphicalLassoCV respectively and will be removed in version 0.22. #9993 by Artiem Krinitsyn

sklearn.datasets

• [MAJOR FEATURE] Added datasets.fetch_openml to fetch datasets from OpenML. OpenML is a free, open data sharing platform and will be used instead of mldata as it provides better service availability. #9908 by Andreas Müller and Jan N. van Rijn.

• [FEATURE] In datasets.make_blobs, one can now pass a list to the n_samples parameter to indicate the number of samples to generate per cluster. #8617 by Maskani Filali Mohamed and Konstantinos Katrioplas.

• [FEATURE] Add filename attribute to datasets that have a CSV file. #9101 by alex-33 and Maskani Filali Mohamed.

• [FEATURE] return_X_y parameter has been added to several dataset loaders. #10774 by Chris Catalfo.

• [FIX] Fixed a bug in datasets.load_boston which had a wrong data point. #10795 by Takeshi Yoshizawa.

• [FIX] Fixed a bug in datasets.load_iris which had two wrong data points. #11082 by Sadhana Srinivasan and Hanmin Qin.

• [FIX] Fixed a bug in datasets.fetch_kddcup99, where data were not properly shuffled. #9731 by Nicolas Goix.

• [FIX] Fixed a bug in datasets.make_circles, where no odd number of data points could be generated. #10045 by Christian Braune.

• [API CHANGE] Deprecated sklearn.datasets.fetch_mldata to be removed in version 0.22. ml-data.org is no longer operational. Until removal it will remain possible to load cached datasets. #11466 by Joel Nothman.
sklearn.decomposition

- [FEATURE] `decomposition.dict_learning` functions and models now support positivity constraints. This applies to the dictionary and sparse code. #6374 by John Kirkham.

- [FEATURE] [FIX] `decomposition.SparsePCA` now exposes `normalize_components`. When set to True, the train and test data are centered with the train mean respectively during the fit phase and the transform phase. This fixes the behavior of SparsePCA. When set to False, which is the default, the previous abnormal behaviour still holds. The False value is for backward compatibility and should not be used. #11585 by Ivan Panico.

- [EFFICIENCY] Efficiency improvements in `decomposition.dict_learning`. #11420 and others by John Kirkham.

- [FIX] Fix for uninformative error in `decomposition.IncrementalPCA`: now an error is raised if the number of components is larger than the chosen batch size. The `n_components=None` case was adapted accordingly. #6452. By Wally Gauze.

- [FIX] Fixed a bug where the `partial_fit` method of `decomposition.IncrementalPCA` used integer division instead of float division on Python 2. #9492 by James Bourbeau.

- [FIX] In `decomposition.PCA` selecting a `n_components` parameter greater than the number of samples now raises an error. Similarly, the `n_components=None` case now selects the minimum of `n_samples` and `n_features`. #8484 by Wally Gauze.

- [FIX] Fixed a bug in `decomposition.PCA` where users will get unexpected error with large datasets when `n_components='mle'` on Python 3 versions. #9886 by Hanmin Qin.

- [FIX] Fixed an underflow in calculating KL-divergence for `decomposition.NMF` #10142 by Tom Dupre la Tour.

- [FIX] Fixed a bug in `decomposition.SparseCoder` when running OMP sparse coding in parallel using read-only memory mapped datastructures. #5956 by Vighnesh Birodkar and Olivier Grisel.

sklearn.discriminant_analysis

- [EFFICIENCY] Memory usage improvement for `_class_means` and `_class_cov` in `discriminant_analysis`. #10898 by Nanxin Chen.

sklearn.dummy

- [FEATURE] `dummy.DummyRegressor` now has a `return_std` option in its `predict` method. The returned standard deviations will be zeros.

- [FEATURE] `dummy.DummyClassifier` and `dummy.DummyRegressor` now only require `X` to be an object with finite length or shape. #9832 by Vrishank Bhardwaj.

- [FEATURE] `dummy.DummyClassifier` and `dummy.DummyRegressor` can now be scored without supplying test samples. #11951 by Rüdiger Busche.
**sklearn.ensemble**

- **[FEATURE]** `ensemble.BaggingRegressor` and `ensemble.BaggingClassifier` can now be fit with missing/non-finite values in X and/or multi-output Y to support wrapping pipelines that perform their own imputation. #9707 by Jimmy Wan.

- **[FEATURE]** `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor` now support early stopping via `n_iter_no_change`, `validation_fraction` and `tol`. #7071 by Raghav RV

- **[FEATURE]** Added `named_estimators_` parameter in `ensemble.VotingClassifier` to access fitted estimators. #9157 by Herilalaina Rakotoarison.

- **[Fix]** Fixed a bug when fitting `ensemble.GradientBoostingClassifier` or `ensemble.GradientBoostingRegressor` with `warm_start=True` which previously raised a segmentation fault due to a non-conversion of CSC matrix into CSR format expected by `decision_function`. Similarly, Fortran-ordered arrays are converted to C-ordered arrays in the dense case. #9991 by Guillaume Lemaitre.

- **[Fix]** Fixed a bug in `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier` to have feature importances summed and then normalized, rather than normalizing on a per-tree basis. The previous behavior over-weighted the Gini importance of features that appear in later stages. This issue only affected feature importances. #11176 by Gil Forsyth.

- **[API Change]** The default value of the `n_estimators` parameter of `ensemble.RandomForestClassifier`, `ensemble.RandomForestRegressor`, `ensemble.ExtraTreesClassifier`, `ensemble.ExtraTreesRegressor`, and `ensemble.RandomTreesEmbedding` will change from 10 in version 0.20 to 100 in 0.22. A `FutureWarning` is raised when the default value is used. #11542 by Anna Ayzenshtat.

- **[API Change]** Classes derived from `ensemble.BaseBagging`. The attribute `estimators_samples_` will return a list of arrays containing the indices selected for each bootstrap instead of a list of arrays containing the mask of the samples selected for each bootstrap. Indices allows to repeat samples while mask does not allow this functionality. #9524 by Guillaume Lemaitre.

- **[Fix]** `ensemble.BaseBagging` where one could not deterministically reproduce fit result using the object attributes when `random_state` is set. #9723 by Guillaume Lemaitre.

**sklearn.feature_extraction**

- **[FEATURE]** Enable the call to `get_feature_names` in unfitted `feature_extraction.text.CountVectorizer` initialized with a vocabulary. #10908 by Mohamed Maskani.

- **[Enhancement]** `idf_` can now be set on a `feature_extraction.text.TfidfTransformer`. #10899 by Sergey Melderis.

- **[Fix]** Fixed a bug in `feature_extraction.image.extract_patches_2d` which would throw an exception if `max_patches` was greater than or equal to the number of all possible patches rather than simply returning the number of possible patches. #10101 by Varun Agrawal

- **[Fix]** Fixed a bug in `feature_extraction.text.CountVectorizer`, `feature_extraction.text.TfidfVectorizer`, `feature_extraction.text.HashingVectorizer` to support 64 bit sparse array indexing necessary to process large datasets with more than $2 \cdot 10^9$ tokens (words or n-grams). #9147 by Claes-Fredrik Mannby and Roman Yurchak.

- **[Fix]** Fixed bug in `feature_extraction.text.TfidfVectorizer` which was ignoring the parameter `dtype`. In addition, `feature_extraction.text.TfidfTransformer` will preserve `dtype` for floating and raise a warning if `dtype` requested is integer. #10441 by Mayur Kulkarni and Guillaume Lemaitre.
sklearn.feature_selection

- [FEATURE] Added select K best features functionality to `feature_selection.SelectFromModel`. #6689 by Nihar Sheth and Quazi Rahman.
- [FEATURE] Added min_features_to_select parameter to `feature_selection.RFECV` to bound evaluated features counts. #11293 by Brent Yi.
- [FEATURE] `feature_selection.RFECV`'s fit method now supports `groups`. #9656 by Adam Greenhall.
- [FIX] Fixed computation of n_features_to_compute for edge case with tied CV scores in `feature_selection.RFECV`. #9222 by Nick Hoh.

sklearn.gaussian_process

- [EFFICIENCY] In `gaussian_process.GaussianProcessRegressor`, method `predict` is faster when using `return_std=True` in particular more when called several times in a row. #9234 by andrewww and Minghui Liu.

sklearn.impute

- New module, adopting `preprocessing.Imputer` as `impute.SimpleImputer` with minor changes (see under preprocessing below).
- [MAJOR FEATURE] Added `impute.MissingIndicator` which generates a binary indicator for missing values. #8075 by Maniteja Nandana and Guillaume Lemaitre.
- [FEATURE] The `impute.SimpleImputer` has a new strategy, 'constant', to complete missing values with a fixed one, given by the `fill_value` parameter. This strategy supports numeric and non-numeric data, and so does the 'most_frequent' strategy now. #11211 by Jeremie du Boisberranger.

sklearn.isotonic

- [FIX] Fixed a bug in `isotonic.IsotonicRegression` which incorrectly combined weights when fitting a model to data involving points with identical X values. #9484 by Dallas Card

sklearn.linear_model

- [FEATURE] `linear_model.SGDClassifier`, `linear_model.SGDRegressor`, `linear_model.PassiveAggressiveClassifier`, `linear_model.PassiveAggressiveRegressor` and `linear_model.Perceptron` now expose `early_stopping`, `validation_fraction` and `n_iter_no_change` parameters, to stop optimization monitoring the score on a validation set. A new learning rate "adaptive" strategy divides the learning rate by 5 each time `n_iter_no_change` consecutive epochs fail to improve the model. #9043 by Tom Dupre la Tour.
- [FIX] Fixed a bug in `logistic.logistic_regression_path` to ensure that the returned coefficients are correct when `multiclass='multinomial'`. Previously, some of the coefficients would override each other, leading to incorrect results in `linear_model.LogisticRegressionCV`. #11724 by Nicolas Hug.
• [Fix] Fixed a bug in `linear_model.LogisticRegression` where when using the parameter `multi_class='multinomial'`, the predict_proba method was returning incorrect probabilities in the case of binary outcomes. #9939 by Roger Westover.

• [Fix] Fixed a bug in `linear_model.LogisticRegressionCV` where the score method always computes accuracy, not the metric given by the scoring parameter. #10998 by Thomas Fan.

• [Fix] Fixed a bug in `linear_model.LogisticRegressionCV` where the 'ovr' strategy was always used to compute cross-validation scores in the multiclass setting, even if 'multinomial' was set. #8720 by William de Vazelhes.

• [Fix] Fixed a bug in `linear_model.OrthogonalMatchingPursuit` that was broken when setting `normalize=False`. #10071 by Alexandre Gramfort.

• [Fix] Fixed a bug in `linear_model.ARDRegression` which caused incorrectly updated estimates for the standard deviation and the coefficients. #10153 by Jörg Döpfert.

• [Fix] Fixed a bug in `linear_model.ARDRegression` and `linear_model.BayesianRidge` which caused NaN predictions when fitted with a constant target. #10095 by Jörg Döpfert.

• [Fix] Fixed a bug in `linear_model.RidgeClassifierCV` where using integer alphas was not implemented though it was documented in cv_values as a way to set up the storage of cross-validation values for different alphas. #10297 by Mabel Villalba-Jiménez.

• [Fix] Fixed a bug in `linear_model.ElasticNet` which caused the input to be overridden when using parameter `copy_X=True` and `check_input=False`. #10581 by Yacine Mazari.

• [Fix] Fixed a bug in `sklearn.linear_model.Lasso` where the coefficient had wrong shape when `fit_intercept=False`. #10687 by Martin Hahn.

• [Fix] Fixed a bug in `sklearn.linear_model.LogisticRegression` where the `multi_class='multinomial'` with binary output with `warm_start=True` #10836 by Aishwarya Srinivasan.


• [Fix] Fixed a bug in `linear_model.SGDClassifier`, `linear_model.SGDRegressor`, `linear_model.PassiveAggressiveClassifier`, `linear_model.PassiveAggressiveRegressor` and `linear_model.Perceptron`, where the stopping criterion was stopping the algorithm before convergence. A parameter `n_iter_no_change` was added and set by default to 5. Previous behavior is equivalent to setting the parameter to 1. #9043 by Tom Dupre la Tour.

• [Fix] Fixed a bug where liblinear and libsvm-based estimators would segfault if passed a scipy.sparse matrix with 64-bit indices. They now raise a ValueError. #11327 by Karan Dhingra and Joel Nothman.

• [API CHANGE] The default values of the solver and multi_class parameters of `linear_model.LogisticRegression` will change respectively from 'liblinear' and 'ovr' in version 0.20 to 'lbfgs' and 'auto' in version 0.22. A FutureWarning is raised when the default values are used. #11905 by Tom Dupre la Tour and Joel Nothman.

• [API CHANGE] Deprecated `positive=True` option in `linear_model.Lars` as the underlying implementation is broken. Use `linear_model.Lasso` instead. #9837 by Alexandre Gramfort.

• [API CHANGE] `n_iter_` may vary from previous releases in `linear_model.LogisticRegression` with solver='lbfgs' and `linear_model.HuberRegressor`. For Scipy <= 1.0.0, the optimizer could perform more than the requested maximum number of iterations. Now both estimators will report at most `max_iter` iterations even if more were performed. #10723 by Joel Nothman.
sklearn.manifold

- [EFFICIENCY] Speed improvements for both ‘exact’ and ‘barnes_hut’ methods in manifold.TSNE. #10593 and #10610 by Tom Dupre la Tour.
- [FEATURE] Support sparse input in manifold.Isomap.fit. #8554 by Leland McInnes.
- [FEATURE] manifold.t_sne.trustworthiness accepts metrics other than Euclidean. #9775 by William de Vazelhes.
- [FIX] Fixed a bug in manifold.spectral_embedding where the normalization of the spectrum was using a division instead of a multiplication. #8129 by Jan Margera, Guillaume Lemaire, and Devansh D.

[API CHANGE] [FEATURE] Deprecate precomputed parameter in function manifold.t_sne.trustworthiness. Instead, the new parameter metric should be used with any compatible metric including ‘precomputed’, in which case the input matrix X should be a matrix of pairwise distances or squared distances. #9775 by William de Vazelhes.

sklearn.metrics

- [MAJOR FEATURE] Added the metrics.davies_bouldin_score metric for evaluation of clustering models without a ground truth. #10827 by Luis Osa.
- [MAJOR FEATURE] Added the metrics.balanced_accuracy_score metric and a corresponding 'balanced_accuracy' scorer for binary and multiclass classification. #8066 by @xyguo and Aman Dalmia, and #10587 by Joel Nothman.
- [FEATURE] Partial AUC is available via max_fpr parameter in metrics.roc_auc_score. #3840 by Alexander Niederbühl.
- [FEATURE] A scorer based on metrics.brier_score_loss is also available. #9521 by Hanmin Qin.
- [FEATURE] Added control over the normalization in metrics.normalized mutual_info_score and metrics.adjusted mutual_info_score via the average_method parameter. In version 0.22, the default normalizer for each will become the arithmetic mean of the entropies of each clustering. #11124 by Arya McCarthy.
- [FEATURE] Added output_dict parameter in metrics.classification_report to return classification statistics as dictionary. #11160 by Dan Barkhorn.
- [FEATURE] metrics.classification_report now reports all applicable averages on the given data, including micro, macro and weighted average as well as samples average for multilabel data. #11679 by Alexander Pacha.
- [FEATURE] metrics.average_precision_score now supports binary y_true other than {0, 1} or {-1, 1} through pos_label parameter. #9980 by Hanmin Qin.
- [FEATURE] metrics.label_ranking_average_precision_score now supports sample_weight. #10845 by Jose Perez-Parras Toledano.
- [FEATURE] Add dense_output parameter to metrics.pairwise.linear_kernel. When False and both inputs are sparse, will return a sparse matrix. #10999 by Taylor G Smith.
- [EFFICIENCY] metrics.silhouette_score and metrics.silhouette_samples are more memory efficient and run faster. This avoids some reported freezes and MemoryErrors. #11135 by Joel Nothman.
• [FIX] Fixed a bug in `metrics.precision_recall_fscore_support` when truncated range(n_labels) is passed as value for `labels`. #10377 by Gaurav Dhingra.

• [FIX] Fixed a bug due to floating point error in `metrics.roc_auc_score` with non-integer sample weights. #9786 by Hanmin Qin.

• [FIX] Fixed a bug where `metrics.roc_curve` sometimes starts on y-axis instead of (0, 0), which is inconsistent with the document and other implementations. Note that this will not influence the result from `metrics.roc_auc_score`. #10093 by alexryndin and Hanmin Qin.

• [FIX] Fixed a bug where `metrics.average_precision_score` will sometimes return `nan` when `sample_weight` contains 0. #9980 by Hanmin Qin.

• [API CHANGE] Deprecated `reorder` parameter in `metrics.auc` as it’s no longer required for `metrics.roc_auc_score`. Moreover using `reorder=True` can hide bugs due to floating point error in the input. #9851 by Hanmin Qin.

• [API CHANGE] In `metrics.normalized_mutual_info_score` and `metrics.adjusted_mutual_info_score`, warn that `average_method` will have a new default value. In version 0.22, the default normalizer for each will become the arithmetic mean of the entropies of each clustering. Currently, `metrics.normalized_mutual_info_score` uses the default of `average_method='geometric'`, and `metrics.adjusted_mutual_info_score` uses the default of `average_method='max'` to match their behaviors in version 0.19. #11124 by Arya McCarthy.

sklearn.mixture

• [FEATURE] Added function `fit_predict` to `mixture.GaussianMixture` and `mixture.GaussianMixture`, which is essentially equivalent to calling `fit` and `predict`. #10336 by Shu Haoran and Andrew Peng.

• [FIX] Fixed a bug in `mixture.BaseMixture` where the reported `n_iter_` was missing an iteration. It affected `mixture.GaussianMixture` and `mixture.BayesianGaussianMixture`. #10740 by Erich Schubert and Guillaume Lemaître.

• [FIX] Fixed a bug in `mixture.BaseMixture` and its subclasses `mixture.GaussianMixture` and `mixture.BayesianGaussianMixture` where the `lower_bound_` was not the max lower bound across all initializations (when `n_init > 1`), but just the lower bound of the last initialization. #10869 by Aurélien Géron.
sklearn.model_selection

- [FEATURE] Add `return_estimator` parameter in `cross_validate` to return estimators fitted on each split. #9686 by Aurélien Bellet.

- [FEATURE] New `refit_time_` attribute will be stored in `GridSearchCV` and `RandomizedSearchCV` if `refit` is set to True. This will allow measuring the complete time it takes to perform hyperparameter optimization and refitting the best model on the whole dataset. #11310 by Matthias Feurer.

- [FEATURE] Expose `error_score` parameter in `cross_validate`, `cross_val_score`, `learning_curve` and `validation_curve` to control the behavior triggered when an error occurs in `fit_and_score`. #11576 by Samuel O. Ronsin.

- [FEATURE] BaseSearchCV now has an experimental, private interface to support customized parameter search strategies, through its `run_search` method. See the implementations in `GridSearchCV` and `RandomizedSearchCV` and please provide feedback if you use this. Note that we do not assure the stability of this API beyond version 0.20. #9599 by Joel Nothman

- [ENHANCEMENT] Add improved error message in `cross_val_score` when multiple metrics are passed in `scoring` keyword. #11006 by Ming Li.

- [API CHANGE] The default number of cross-validation folds `cv` and the default number of splits `n_splits` in `KFold`-like splitters will change from 3 to 5 in 0.22 as 3-fold has a lot of variance. #11557 by Alexandre Boucaud.

- [API CHANGE] The default of `iid` parameter of `GridSearchCV` and `RandomizedSearchCV` will change from True to False in version 0.22 to correspond to the standard definition of cross-validation, and the parameter will be removed in version 0.24 altogether. This parameter is of greatest practical significance where the sizes of different test sets in cross-validation were very unequal, i.e. in group-based CV strategies. #9085 by Laurent Dier and Andreas Müller.

- [API CHANGE] The default value of the `error_score` parameter in `GridSearchCV` and `RandomizedSearchCV` will change to `np.NaN` in version 0.22. #10677 by Kirill Zhdanovich.

- [API CHANGE] Changed ValueError exception raised in `ParameterSampler` to a UserWarning for case where the class is instantiated with a greater value of `n_iter` than the total space of parameters in the parameter grid. `n_iter` now acts as an upper bound on iterations. #10982 by Juliet Lawton.

- [API CHANGE] Invalid input for `ParameterGrid` now raises TypeError. #10928 by Solutus Immensus

sklearn.multioutput

- [MAJOR FEATURE] Added `RegressorChain` for multi-target regression. #9257 by Kumar Ashutosh.
sklearn.naive_bayes

- [Feature] Add var_smoothing parameter in naive_bayes.GaussianNB to give a precise control over variances calculation. #9681 by Dmitry Mottl.
- [Fix] Fixed a bug in naive_bayes.GaussianNB which incorrectly raised error for prior list which summed to 1. #10005 by Gaurav Dhingra.
- [Fix] Fixed a bug in naive_bayes.MultinomialNB which did not accept vector valued pseudocounts (alpha). #10346 by Tobias Madsen

sklearn.neighbors

- [Efficiency] neighbors.RadiusNeighborsRegressor and neighbors.RadiusNeighborsClassifier are now parallelized according to n_jobs regardless of algorithm. #10887 by Joël Billaud.
- [Efficiency] Nearest neighbors query methods are now more memory efficient when algorithm='brute'. #11136 by Joel Nothman and Aman Dalmia.
- [Feature] Novelty detection with neighbors.LocalOutlierFactor: Add a novelty parameter to neighbors.LocalOutlierFactor. When novelty is set to True, neighbors.LocalOutlierFactor can then be used for novelty detection, i.e. predict on new unseen data. Available prediction methods are predict, decision_function and score_samples. By default, novelty is set to False, and only the fit_predict method is available. By Albert Thomas.
- [Fix] Fixed a bug in neighbors.NearestNeighbors where fitting a NearestNeighbors model fails when a) the distance metric used is a callable and b) the input to the NearestNeighbors model is sparse. #9579 by Thomas Kober.
- [Fix] Fixed a bug so predict in neighbors.RadiusNeighborsRegressor can handle empty neighbor set when using non uniform weights. Also raises a new warning when no neighbors are found for samples. #9655 by Andreas Bjerre-Nielsen.
- [Fix] [Efficiency] Fixed a bug in KDTree construction that results in faster construction and querying times. #11556 by Jake VanderPlas.
- [Fix] Fixed a bug in neighbors.KDTree and neighbors.BallTree where pickled tree objects would change their type to the super class BinaryTree. #11774 by Nicolas Hug.

sklearn.neural_network

- [Feature] Add n_iter_no_change parameter in neural_network. BaseMultilayerPerceptron, neural_network.MLPRegressor, and neural_network.MLPClassifier to give control over maximum number of epochs to not meet tol improvement. #9456 by Nicholas Nadeau.
- [Fix] Fixed a bug in `neural_network.MLPRegressor` where fitting quit unexpectedly early due to local minima or fluctuations. #9456 by Nicholas Nadeau

**sklearn.pipeline**

- [Feature] The `predict` method of `pipeline.Pipeline` now passes keyword arguments on to the pipeline’s last estimator, enabling the use of parameters such as `return_std` in a pipeline with caution. #9304 by Breno Freitas.

- [API Change] `pipeline.FeatureUnion` now supports `drop` as a transformer to drop features. #11144 by Thomas Fan.

**sklearn.preprocessing**

- [Major Feature] Expanded `preprocessing.OneHotEncoder` to allow to encode categorical string features as a numeric array using a one-hot (or dummy) encoding scheme, and added `preprocessing.OrdinalEncoder` to convert to ordinal integers. Those two classes now handle encoding of all feature types (also handles string-valued features) and derives the categories based on the unique values in the features instead of the maximum value in the features. #9151 and #10521 by Vighnesh Birodkar and Joris Van den Bossche.

- [Major Feature] Added `preprocessing.KBinsDiscretizer` for turning continuous features into categorical or one-hot encoded features. #7668, #9647, #10195, #10192, #11272, #11467 and #11505. by Henry Lin, Hanmin Qin, Tom Dupre la Tour and Giovanni Giuseppe Costa.

- [Major Feature] Added `preprocessing.PowerTransformer`, which implements the Yeo-Johnson and Box-Cox power transformations. Power transformations try to find a set of feature-wise parametric transformations to approximately map data to a Gaussian distribution centered at zero and with unit variance. This is useful as a variance-stabilizing transformation in situations where normality and homoscedasticity are desirable. #10210 by Eric Chang and Maniteja Nandana, and #11520 by Nicolas Hug.

- [Major Feature] NaN values are ignored and handled in the following preprocessing methods: `preprocessing.MaxAbsScaler`, `preprocessing.MinMaxScaler`, `preprocessing.RobustScaler`, `preprocessing.StandardScaler`, `preprocessing.PowerTransformer`, `preprocessing.QuantileTransformer` classes and `preprocessing.maxabs_scale`, `preprocessing.minmax_scale`, `preprocessing.robust_scale`, `preprocessing.scale`, `preprocessing.power_transform`, `preprocessing.quantile_transform` functions respectively addressed in issues #11011, #11005, #11308, #11206, #11306, and #10437. By Lucija Gregov and Guillaume Lemaître.

- [Feature] `preprocessing.PolynomialFeatures` now supports sparse input. #10452 by Aman Dalmia and Joel Nothman.

- [Feature] `preprocessing.RobustScaler` and `preprocessing.robust_scale` can be fitted using sparse matrices. #11308 by Guillaume Lemaître.

- [Feature] `preprocessing.OneHotEncoder` now supports the `get_feature_names` method to obtain the transformed feature names. #10181 by Nirvan Anjirbag and Joris Van den Bossche.

- [Feature] A parameter `check_inverse` was added to `preprocessing.FunctionTransformer` to ensure that `func` and `inverse_func` are the inverse of each other. #9399 by Guillaume Lemaître.

- [Feature] The `transform` method of `sklearn.preprocessing.MultiLabelBinarizer` now ignores any unknown classes. A warning is raised stating the unknown classes classes found which are ignored. #10913 by Rodrigo Agundez.

- [Fix] Fixed bugs in `preprocessing.LabelEncoder` which would sometimes throw errors when `transform` or `inverse_transform` was called with empty arrays. #10458 by Mayur Kulkarni.
• [Fix] Fix ValueError in `preprocessing.LabelEncoder` when using `inverse_transform` on unseen labels. #9816 by Charlie Newey.

• [Fix] Fix bug in `preprocessing.OneHotEncoder` which discarded the `dtype` when returning a sparse matrix output. #11042 by Daniel Morales.

• [Fix] Fix fit and partial_fit in `preprocessing.StandardScaler` in the rare case when `with_mean=False` and `with_std=False` which was crashing by calling `fit` more than once and giving inconsistent results for `mean_` whether the input was a sparse or a dense matrix. `mean_` will be set to `None` with both sparse and dense inputs. `n_samples_seen_` will be also reported for both input types. #11235 by Guillaume Lemaire.

• [API CHANGE] Deprecate `n_values` and `categorical_features` parameters and `active_features_`, `feature_indices_` and `n_values_` attributes of `preprocessing.OneHotEncoder`. The `n_values` parameter can be replaced with the new `categories` parameter, and the attributes with the new `categories_` attribute. Selecting the categorical features with the `categorical_features` parameter is now better supported using the `compose.ColumnTransformer`. #10521 by Joris Van den Bossche.

• [API CHANGE] Deprecate `preprocessing.Imputer` and move the corresponding module to `impute.SimpleImputer`. #9726 by Kumar Ashutosh.

• [API CHANGE] The `axis` parameter that was in `preprocessing.Imputer` is no longer present in `impute.SimpleImputer`. The behavior is equivalent to `axis=0` (impute along columns). Row-wise imputation can be performed with `FunctionTransformer` (e.g., `FunctionTransformer(lambda X: SimpleImputer().fit_transform(X.T).T)`). #10829 by Guillaume Lemaire and Gilberto Olimpio.

• [API CHANGE] The NaN marker for the missing values has been changed between the `preprocessing.Imputer` and the `impute.SimpleImputer`. `missing_values='NaN'` should now be `missing_values=np.nan`. #11211 by Jeremie du Boisberranger.

• [API CHANGE] In `preprocessing.FunctionTransformer`, the default of `validate` will be from `True` to `False` in 0.22. #10655 by Guillaume Lemaire.

**sklearn.svm**

• [Fix] Fixed a bug in `svm.SVC` where when the argument `kernel` is unicode in Python2, the `predict_proba` method was raising an unexpected TypeError given dense inputs. #10412 by Jiongyan Zhang.

• [API CHANGE] Deprecate `random_state` parameter in `svm.OneClassSVM` as the underlying implementation is not random. #9497 by Albert Thomas.

• [API CHANGE] The default value of `gamma` parameter of `svm.SVC`, `NuSVC`, `SVR`, `NuSVR`, `OneClassSVM` will change from 'auto' to 'scale' in version 0.22 to account better for unscaled features. #8361 by Gaurav Dhingra and Ting Neo.
sklearn.tree

• [ENHANCEMENT] Although private (and hence not assured API stability), tree._criterion.ClassificationCriterion and tree._criterion.RegressionCriterion may now be cim-
ported and extended. #10325 by Camil Staps.

• [FIX] Fixed a bug in tree.BaseDecisionTree with splitter="best" where split threshold could
become infinite when values in X were near infinite. #10536 by Jonathan Ohayon.

• [FIX] Fixed a bug in tree.MAE to ensure sample weights are being used during the calculation of tree MAE im-
purity. Previous behaviour could cause suboptimal splits to be chosen since the impurity calculation considered
all samples to be of equal weight importance. #11464 by John Stott.

sklearn.utils

• [FEATURE] utils.check_array and utils.check_X_y now have accept_large_sparse to con-
trol whether scipy.sparse matrices with 64-bit indices should be rejected. #11327 by Karan Dhingra and
Joel Nothman.

• [EFFICIENCY] [FIX] Avoid copying the data in utils.check_array when the input data is a memmap (and
copy=False). #10663 by Arthur Mensch and Loïc Estève.

• [API CHANGE] utils.check_array yield a FutureWarning indicating that arrays of bytes/strings will
be interpreted as decimal numbers beginning in version 0.22. #10229 by Ryan Lee

Multiple modules

• [FEATURE] [API CHANGE] More consistent outlier detection API: Add a score_samples method in svm.OneClassSVM, ensemble.IsolationForest, neighbors.LocalOutlierFactor,
covariance.EllipticEnvelope. It allows to access raw score functions from original pa-
pers. A new offset_ parameter allows to link score_samples and decision_function
methods. The contamination parameter of ensemble.IsolationForest and neighbors.
LocalOutlierFactor decision_function methods is used to define this offset_ such that outliers
(resp. inliers) have negative (resp. positive) decision_function values. By default, contamination
is kept unchanged to 0.1 for a deprecation period. In 0.22, it will be set to “auto”, thus using method-specific
score offsets. In covariance.EllipticEnvelope decision_function method, the raw_values
parameter is deprecated as the shifted Mahalanobis distance will be always returned in 0.22. #9015 by
Nicolas Goix.

• [FEATURE] [API CHANGE] A behaviour parameter has been introduced in ensemble.
IsolationForest to ensure backward compatibility. In the old behaviour, the decision_function
is independent of the contamination parameter. A threshold attribute depending on the contamination
parameter is thus used. In the new behaviour the decision_function is dependent on the contamination
parameter, in such a way that 0 becomes its natural threshold to detect outliers. Setting behaviour to “old” is deprecated and will not be possible in version 0.22. Beside, the behaviour parameter
will be removed in 0.24. #11553 by Nicolas Goix.

• [API CHANGE] Added convergence warning to svm.LinearSVC and linear_model.
LogisticRegression when verbose is set to 0. #10881 by Alexandre Sevin.

• [API CHANGE] Changed warning type from UserWarning to exceptions.ConvergenceWarning
for failing convergence in linear_model.logistic_regression_path, linear_model.
RANSACRegressor, linear_model.ridge_regression, gaussian_process.
GaussianProcessRegressor, gaussian_process.GaussianProcessClassifier,
decomposition.fastica, cross_decomposition.PLSCanonical, cluster.
AffinityPropagation, and cluster.Birch. #10306 by Jonathan Siebert.

Miscellaneous

- [Major Feature] A new configuration parameter, `working_memory` was added to control memory consumption limits in chunked operations, such as the new `metrics.pairwise_distances_chunked`. See Limiting Working Memory. #10280 by Joel Nothman and Aman Dalmia.

- [Feature] The version of joblib bundled with Scikit-learn is now 0.12. This uses a new default multiprocessing implementation, named loky. While this may incur some memory and communication overhead, it should provide greater cross-platform stability than relying on Python standard library multiprocessing. #11741 by the Joblib developers, especially Thomas Moreau and Olivier Grisel.

- [Feature] An environment variable to use the site joblib instead of the vendored one was added (`Environment variables`). The main API of joblib is now exposed in sklearn.utils. #11166 by Gael Varoquaux.

- [Feature] Add almost complete PyPy 3 support. Known unsupported functionalities are datasets.load_svmlight_file, feature_extraction.FeatureHasher and feature_extraction.text.HashingVectorizer. For running on PyPy, PyPy3-v5.10+, Numpy 1.14.0+, and scipy 1.1.0+ are required. #11010 by Ronan Lamy and Roman Yurchak.

- [Feature] A utility method sklearn.show_versions was added to print out information relevant for debugging. It includes the user system, the Python executable, the version of the main libraries and BLAS binding information. #11596 by Alexandre Boucaud

- [Fix] Fixed a bug when setting parameters on meta-estimator, involving both a wrapped estimator and its parameter. #9999 by Marcus Voss and Joel Nothman.

- [Fix] Fixed a bug where calling sklearn.base.clone was not thread safe and could result in a “pop from empty list” error. #9569 by Andreas Müller.

- [API Change] The default value of `n_jobs` is changed from 1 to `None` in all related functions and classes. `n_jobs=None` means unset. It will generally be interpreted as `n_jobs=1`, unless the current joblib. Parallel backend context specifies otherwise (See Glossary for additional information). Note that this change happens immediately (i.e., without a deprecation cycle). #11741 by Olivier Grisel.

- [Fix] Fixed a bug in validation helpers where passing a Dask DataFrame results in an error. #12462 by Zachariah Miller

Changes to estimator checks

These changes mostly affect library developers.

- Checks for transformers now apply if the estimator implements `transform`, regardless of whether it inherits from sklearn.base.TransformerMixion. #10474 by Joel Nothman.

- Classifiers are now checked for consistency between `decision_function` and categorical predictions. #10500 by Narine Kokhlikyan.

- Allow tests in `utils.estimator_checks.check_estimator` to test functions that accept pairwise data. #9701 by Kyle Johnson

- Allow `utils.estimator_checks.check_estimator` to check that there is no private settings apart from parameters during estimator initialization. #9378 by Herilalaina Rakotoarison

- The set of checks in `utils.estimator_checks.check_estimator` now includes a `check_set_params` test which checks that `set_params` is equivalent to passing parameters in `__init__` and warns if it encounters parameter validation. #7738 by Alvin Chiang
• Add invariance tests for clustering metrics. #8102 by Ankita Sinha and Guillaume Lemaître.

• Add `check_methods_subset_invariance` to `check_estimator`, which checks that estimator methods are invariant if applied to a data subset. #10428 by Jonathan Ohayon

• Add tests in `utils.estimator_checks.check_estimator` to check that an estimator can handle read-only memmap input data. #10663 by Arthur Mensch and Loïc Estève.

• `check_sample_weights_pandas_series` now uses 8 rather than 6 samples to accommodate for the default number of clusters in `cluster.KMeans`. #10933 by Johannes Hansen.

• Estimators are now checked for whether `sample_weight=None` equates to `sample_weight=np.ones(...)`. #11558 by Sergul Aydore.

Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.19, including:

1.7.17 Version 0.19.2

July, 2018

This release is exclusively in order to support Python 3.7.

Related changes

- `n_iter_` may vary from previous releases in `linear_model.LogisticRegression` with (`solver='lbfgs'`) and `linear_model.HuberRegressor`. For Scipy <= 1.0.0, the optimizer could perform more than the requested maximum number of iterations. Now both estimators will report at most `max_iter` iterations even if more were performed. #10723 by Joel Nothman.

1.7.18 Version 0.19.1

October 23, 2017

This is a bug-fix release with some minor documentation improvements and enhancements to features released in 0.19.0.

Note there may be minor differences in TSNE output in this release (due to #9623), in the case where multiple samples have equal distance to some sample.

Changelog

API changes

- Reverted the addition of `metrics.ndcg_score` and `metrics.dcg_score` which had been merged into version 0.19.0 by error. The implementations were broken and undocumented.

- `return_train_score` which was added to `model_selection.GridSearchCV`, `model_selection.RandomizedSearchCV` and `model_selection.cross_validate` in version 0.19.0 will be changing its default value from True to False in version 0.21. We found that calculating training score could have a great effect on cross validation runtime in some cases. Users should explicitly set `return_train_score` to False if prediction or scoring functions are slow, resulting in a deleterious effect on CV runtime, or to True if they wish to use the calculated scores. #9677 by Kumar Ashutosh and Joel Nothman.

- `correlation_models` and `regression_models` from the legacy gaussian processes implementation have been belatedly deprecated. #9717 by Kumar Ashutosh.
Bug fixes

- Avoid integer overflows in `metrics.matthews_corrcoef`. #9693 by Sam Steingold.
- Fixed a bug in the objective function for `manifold.TSNE` (both exact and with the Barnes-Hut approximation) when `n_components` >= 3. #9711 by @goncalo-rodrigues.
- Fix regression in `model_selection.cross_val_predict` where it raised an error with method='predict_proba' for some probabilistic classifiers. #9641 by James Bourbeau.
- Fixed a bug where `datasets.make_classification` modified its input weights. #9865 by Sachin Kelkar.
- `model_selection.StratifiedShuffleSplit` now works with multioutput multiclass or multilabel data with more than 1000 columns. #9922 by Charlie Brummitt.
- Fixed a bug with nested and conditional parameter setting, e.g. setting a pipeline step and its parameter at the same time. #9945 by Andreas Müller and Joel Nothman.

Regressions in 0.19.0 fixed in 0.19.1:

- Fixed a bug where parallelised prediction in random forests was not thread-safe and could (rarely) result in arbitrary errors. #9830 by Joel Nothman.
- Fix regression in `model_selection.cross_val_predict` where it no longer accepted `X` as a list. #9600 by Rasul Kerimov.
- Fixed handling of `cross_val_predict` for binary classification with method='decision_function'. #9593 by Reiichiro Nakano and core devs.
- Fix regression in `pipeline.Pipeline` where it no longer accepted `steps` as a tuple. #9604 by Joris Van den Bossche.
- Fix bug where `n_iter` was not properly deprecated, leaving `n_iter` unavailable for interim use in `linear_model.SGDClassifier`, `linear_model.SGDRegressor`, `linear_model.PassiveAggressiveClassifier`, `linear_model.PassiveAggressiveRegressor` and `linear_model.Perceptron`. #9558 by Andreas Müller.
- Dataset fetchers make sure temporary files are closed before removing them, which caused errors on Windows. #9847 by Joan Massich.
- Fixed a regression in `manifold.TSNE` where it no longer supported metrics other than ‘euclidean’ and ‘pre-computed’. #9623 by Oli Blum.

Enhancements

- Our test suite and `utils.estimator_checks.check_estimators` can now be run without Nose installed. #9697 by Joan Massich.
- To improve usability of version 0.19’s `pipeline.Pipeline` caching, `memory` now allows joblib. Memory instances. This make use of the new `utils.validation.check_memory` helper. #9584 by Kumar Ashutosh.
- Some fixes to examples: #9750, #9788, #9815
- Made a FutureWarning in SGD-based estimators less verbose. #9802 by Vrishank Bhardwaj.
1.7.19 Version 0.19

August 12, 2017

Highlights

We are excited to release a number of great new features including neighbors.LocalOutlierFactor for anomaly detection, preprocessing.QuantileTransformer for robust feature transformation, and the multioutput.ClassifierChain meta-estimator to simply account for dependencies between classes in multilabel problems. We have some new algorithms in existing estimators, such as multiplicative update in decomposition.NMF and multinomial linear_model.LogisticRegression with L1 loss (use solver='saga').

Cross validation is now able to return the results from multiple metric evaluations. The new model_selection.cross_validate can return many scores on the test data as well as training set performance and timings, and we have extended the scoring and refit parameters for grid/randomized search to handle multiple metrics.

You can also learn faster. For instance, the new option to cache transformations in pipeline.Pipeline makes grid search over pipelines including slow transformations much more efficient. And you can predict faster: if you’re sure you know what you’re doing, you can turn off validating that the input is finite using config_context.

We’ve made some important fixes too. We’ve fixed a longstanding implementation error in metrics.average_precision_score, so please be cautious with prior results reported from that function. A number of errors in the manifold.TSNE implementation have been fixed, particularly in the default Barnes-Hut approximation. semi_supervised.LabelSpreading and semi_supervised.LabelPropagation have had substantial fixes. LabelPropagation was previously broken. LabelSpreading should now correctly respect its alpha parameter.

Changed models

The following estimators and functions, when fit with the same data and parameters, may produce different models from the previous version. This often occurs due to changes in the modelling logic (bug fixes or enhancements), or in random sampling procedures.

- cluster.KMeans with sparse X and initial centroids given (bug fix)
- cross_decomposition.PLSRegression with scale=True (bug fix)
- ensemble.GradientBoostingClassifier and ensemble.GradientBoostingRegressor where min_impurity_split is used (bug fix)
- gradient boosting loss='quantile' (bug fix)
- ensemble.IsolationForest (bug fix)
- feature_selection.SelectFdr (bug fix)
- linear_model.RANSACRegressor (bug fix)
• `linear_model.LassoLars` (bug fix)
• `linear_model.LassoLarsIC` (bug fix)
• `manifold.TSNE` (bug fix)
• `neighbors.NearestCentroid` (bug fix)
• `semi_supervised.LabelSpreading` (bug fix)
• `semi_supervised.LabelPropagation` (bug fix)
• tree based models where `min_weight_fraction_leaf` is used (enhancement)
• `model_selection.StratifiedKFold` with `shuffle=True` (this change, due to #7823 was not mentioned in the release notes at the time)

Details are listed in the changelog below.
(While we are trying to better inform users by providing this information, we cannot assure that this list is complete.)

**Changelog**

**New features**

Classifiers and regressors

• Added `multioutput.ClassifierChain` for multi-label classification. By Adam Kleczewski.
• Added solver 'saga' that implements the improved version of Stochastic Average Gradient, in `linear_model.LogisticRegression` and `linear_model.Ridge`. It allows the use of L1 penalty with multinomial logistic loss, and behaves marginally better than 'sag' during the first epochs of ridge and logistic regression. #8446 by Arthur Mensch.

Other estimators

• Added the `neighbors.LocalOutlierFactor` class for anomaly detection based on nearest neighbors. #5279 by Nicolas Goix and Alexandre Gramfort.
• Added `preprocessing.QuantileTransformer` class and `preprocessing.quantile_transform` function for features normalization based on quantiles. #8363 by Denis Engemann, Guillaume Lemaître, Olivier Grisel, Raghav RV, Thierry Guillemot, and Gael Varoquaux.
• The new solver 'mu' implements a Multiplicate Update in `decomposition.NMF`, allowing the optimization of all beta-divergences, including the Frobenius norm, the generalized Kullback-Leibler divergence and the Itakura-Saito divergence. #5295 by Tom Dupre la Tour.

Model selection and evaluation

• `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` now support simultaneous evaluation of multiple metrics. Refer to the Specifying multiple metrics for evaluation section of the user guide for more information. #7388 by Raghav RV
• Added the `model_selection.cross_validate` which allows evaluation of multiple metrics. This function returns a dict with more useful information from cross-validation such as the train scores, fit times and score times. Refer to The cross_validate function and multiple metric evaluation section of the userguide for more information. #7388 by Raghav RV
• Added `metrics.mean_squared_log_error`, which computes the mean square error of the logarithmic transformation of targets, particularly useful for targets with an exponential trend. #7655 by Karan Desai.
• Added `metrics.dcg_score` and `metrics.ndcg_score`, which compute Discounted cumulative gain (DCG) and Normalized discounted cumulative gain (NDCG). #7739 by David Gasquez.
• Added the `model_selection.RepeatedKFold` and `model_selection.RepeatedStratifiedKFold`. #8120 by Neeraj Gangwar.

Miscellaneous

• Validation that input data contains no NaN or inf can now be suppressed using `config_context`, at your own risk. This will save on runtime, and may be particularly useful for prediction time. #7548 by Joel Nothman.

• Added a test to ensure parameter listing in docstrings match the function/class signature. #9206 by Alexandre Gramfort and Raghav RV.

Enhancements

Trees and ensembles

• The `min_weight_fraction_leaf` constraint in tree construction is now more efficient, taking a fast path to declare a node a leaf if its weight is less than 2 * the minimum. Note that the constructed tree will be different from previous versions where `min_weight_fraction_leaf` is used. #7441 by Nelson Liu.

• `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor` now support sparse input for prediction. #6101 by Ibraim Ganiev.

• `ensemble.VotingClassifier` now allows changing estimators by using `ensemble.VotingClassifier.set_params`. An estimator can also be removed by setting it to None. #7674 by Yichuan Liu.

• `tree.export_graphviz` now shows configurable number of decimal places. #8698 by Guillaume Lemaître.

• Added `flatten_transform` parameter to `ensemble.VotingClassifier` to change output shape of `transform` method to 2 dimensional. #7794 by Ibraim Ganiev and Herilalaina Rakotoarison.

Linear, kernelized and related models

• `linear_model.SGDClassifier`, `linear_model.SGDRegressor`, `linear_model.PassiveAggressiveClassifier`, `linear_model.PassiveAggressiveRegressor` and `linear_model.Perceptron` now expose `max_iter` and `tol` parameters, to handle convergence more precisely. `n_iter` parameter is deprecated, and the fitted estimator exposes a `n_iter_` attribute, with actual number of iterations before convergence. #5036 by Tom Dupre la Tour.

• Added `average` parameter to perform weight averaging in `linear_model.PassiveAggressiveClassifier`. #4939 by Andrea Esuli.

• `linear_model.RANSACRegressor` no longer throws an error when calling `fit` if no inliers are found in its first iteration. Furthermore, causes of skipped iterations are tracked in newly added attributes, `n_skips_*`. #7914 by Michael Horrell.

• In `gaussian_process.GaussianProcessRegressor`, method `predict` is a lot faster with `return_std=True`. #8591 by Hadrien Bertrand.

• Added `return_std` to `predict` method of `linear_model.ARDRegression` and `linear_model.BayesianRidge`. #7838 by Sergey Feldman.

• Memory usage enhancements: Prevent cast from float32 to float64 in: `linear_model.MultiTaskElasticNet`, `linear_model.LogisticRegression` when using newton-cg solver; and `linear_model.Ridge` when using svd, sparse_cg, cholesky or lsqr solvers. #8835, #8061 by Joan Massich and Nicolas Cordier and Thierry Guillemot.

Other predictors
• Custom metrics for the neighbors binary trees now have fewer constraints: they must take two 1d-arrays and return a float. #6288 by Jake Vanderplas.

• algorithm='auto in neighbors estimators now chooses the most appropriate algorithm for all input types and metrics. #9145 by Herilalaina Rakotoarison and Reddy Chinthala.

Decomposition, manifold learning and clustering

• cluster.MiniBatchKMeans and cluster.KMeans now use significantly less memory when assigning data points to their nearest cluster center. #7721 by Jon Crall.

• decomposition.PCA, decomposition.IncrementalPCA and decomposition.TruncatedSVD now expose the singular values from the underlying SVD. They are stored in the attribute singular_values_, like in decomposition.IncrementalPCA. #7685 by Tommy Löfstedt

• decomposition.NMF now faster when beta_loss=0. #9277 by @hongkahjun.

• Memory improvements for method barnes_hut in manifold.TSNE #7089 by Thomas Moreau and Olivier Grisel.

• Optimization schedule improvements for Barnes-Hut manifold.TSNE so the results are closer to the one from the reference implementation lvdmaaten/bhtsne by Thomas Moreau and Olivier Grisel.

• Memory usage enhancements: Prevent cast from float32 to float64 in decomposition.PCA and decomposition.randomized_svd_low_rank. #9067 by Raghav RV.

Preprocessing and feature selection

• Added norm_order parameter to feature_selection.SelectFromModel to enable selection of the norm order when coef_ is more than 1D. #6181 by Antoine Wendlinger.

• Added ability to use sparse matrices in feature_selection.f_regression with center=True. #8065 by Daniel LeJeune.

• Small performance improvement to n-gram creation in feature_extraction.text by binding methods for loops and special-casing unigrams. #7567 by Jaye Doepke

• Relax assumption on the data for the kernel_approximation.SkewedChi2Sampler. Since the Skewed-Chi2 kernel is defined on the open interval (−skewedness; +∞)², the transform function should not check whether X < 0 but whether X < −self.skewedness. #7573 by Romain Brault.

• Made default kernel parameters kernel-dependent in kernel_approximation.Nystroem. #5229 by Saurabh Bansod and Andreas Müller.

Model evaluation and meta-estimators

• pipeline.Pipeline is now able to cache transformers within a pipeline by using the memory constructor parameter. #7990 by Guillaume Lemaître.

• pipeline.Pipeline steps can now be accessed as attributes of its named_steps attribute. #8586 by Herilalaina Rakotoarison.

• Added sample_weight parameter to pipeline.Pipeline.score. #7723 by Mikhail Korobov.

• Added ability to set n_jobs parameter to pipeline.make_union. A TypeError will be raised for any other kwargs. #8028 by Alexander Booth.

• model_selection.GridSearchCV, model_selection.RandomizedSearchCV and model_selection.cross_val_score now allow estimators with callable kernels which were previously prohibited. #8005 by Andreas Müller.

• model_selection.cross_val_predict now returns output of the correct shape for all values of the argument method. #7863 by Aman Dalmia.
• Added shuffle and random_state parameters to shuffle training data before taking prefixes of it based on training sizes in `model_selection.learning_curve`. #7506 by Narine Kokhlikyan.

• `model_selection.StratifiedShuffleSplit` now works with multioutput multiclass (or multilabel) data. #9044 by Vlad Niculae.

• Speed improvements to `model_selection.StratifiedShuffleSplit`. #5991 by Arthur Mensch and Joel Nothman.

• Add shuffle parameter to `model_selection.train_test_split`. #8845 by themrmax


• Add max_train_size parameter to `model_selection.TimeSeriesSplit` #8282 by Aman Dalmia.

• More clustering metrics are now available through `metrics.get_scorer` and `scoring` parameters. #8117 by Raghav RV.

• A scorer based on `metrics.explained_variance_score` is also available. #9259 by Hanmin Qin.

**Metrics**

• `metrics.matthews_corrcoef` now support multiclass classification. #8094 by Jon Crall.

• Add sample_weight parameter to `metrics.cohen_kappa_score`. #8335 by Victor Poughon.

**Miscellaneous**

• `utils.check_estimator` now attempts to ensure that methods transform, predict, etc. do not set attributes on the estimator. #7533 by Ekaterina Krivich.

• Added type checking to the accept_sparse parameter in `utils.validation` methods. This parameter now accepts only boolean, string, or list/tuple of strings. accept_sparse=None is deprecated and should be replaced by accept_sparse=False. #7880 by Josh Karnofsky.

• Make it possible to load a chunk of an svmlight formatted file by passing a range of bytes to `datasets.load_svmlight_file`. #935 by Olivier Grisel.

• `dummy.DummyClassifier` and `dummy.DummyRegressor` now accept non-finite features. #8931 by @Attractadore.

**Bug fixes**

**Trees and ensembles**

• Fixed a memory leak in trees when using trees with criterion='mae'. #8002 by Raghav RV.

• Fixed a bug where `ensemble.IsolationForest` uses an an incorrect formula for the average path length #8549 by Peter Wang.

• Fixed a bug where `ensemble.AdaBoostClassifier` throws ZeroDivisionError while fitting data with single class labels. #7501 by Dominik Krzeminski.

• Fixed a bug in `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor` where a float being compared to 0.0 using == caused a divide by zero error. #7970 by He Chen.

• Fix a bug where `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor` ignored the min_impurity_split parameter. #8006 by Sebastian Pölsterl.

• Fixed oob_score in `ensemble.BaggingClassifier`. #8936 by Michael Lewis
• Fixed excessive memory usage in prediction for random forests estimators. #8672 by Mike Benfield.

• Fixed a bug where `sample_weight` as a list broke random forests in Python 2 #8068 by @xor.

• Fixed a bug where `ensemble.IsolationForest` fails when `max_features` is less than 1. #5732 by Ishank Gulati.

• Fix a bug where gradient boosting with `loss='quantile'` computed negative errors for negative values of `ytrue - ypred` leading to wrong values when calling `__call__`. #8087 by Alexis Mignon

• Fix a bug where `ensemble.VotingClassifier` raises an error when a numpy array is passed in for weights. #7983 by Vincent Pham.

• Fixed a bug where `tree.export_graphviz` raised an error when the length of features_names does not match n_features in the decision tree. #8512 by Li Li.

Linear, kernelized and related models

• Fixed a bug where `linear_model.RANSACRegressor.fit` may run until `max_iter` if it finds a large inlier group early. #8251 by @avision2020.

• Fixed a bug where `naive_bayes.MultinomialNB` and `naive_bayes.BernoulliNB` failed when `alpha=0`. #5814 by Yichuan Liu and Herilalaina Rakotoarison.

• Fixed a bug where `linear_model.LassoLars` does not give the same result as the LassoLars implementation available in R (lars library). #7849 by Jair Montoya Martinez.

• Fixed a bug in `linear_model.RandomizedLasso`, `linear_model.Lars`, `linear_model.LassoLars`, `linear_model.LarsCV` and `linear_model.LassoLarsCV`, where the parameter `precompute` was not used consistently across classes, and some values proposed in the docstring could raise errors. #5359 by Tom Dupre la Tour.

• Fix inconsistent results between `linear_model.RidgeCV` and `linear_model.Ridge` when using `normalize=True`. #8224 by Peter Gedeck.

• Fix a bug where `linear_model.LassoLars.fit` sometimes left `coef_` as a list, rather than an ndarray. #8160 by CJ Carey.

• Fix `linear_model.BayesianRidge.fit` to return ridge parameter `alpha_` and `lambda_` consistent with calculated coefficients `coef_` and `intercept_`. #9239 by Andre Ambrosio Boechat, Utkarsh Upadhyay, and Joel Nothman.

• Fixed a bug in `svm.OneClassSVM` where it returned floats instead of integer classes. #6573 by Vathsala Achar.

• Fix AIC/BIC criterion computation in `linear_model.LassoLarsIC`. #9022 by Alexandre Gramfort and Mehmet Basbug.

• Fixed a memory leak in our LibLinear implementation. #9024 by Sergei Lebedev

• Fix bug where stratified CV splitters did not work with `linear_model.LassoCV`. #8973 by Paulo Haddad.

• Fixed a bug in `gaussian_process.GaussianProcessRegressor` when the standard deviation and covariance predicted without fit would fail with a unmeaningful error by default. #5673 by Quazi Marufur Rahman and Manoj Kumar.

Other predictors

• Fix `semi_supervised.BaseLabelPropagation` to correctly implement `LabelPropagation` and `LabelSpreading` as done in the referenced papers. #9239 by Andre Ambrosio Boechat, Utkarsh Upadhyay, and Joel Nothman.

Decomposition, manifold learning and clustering

• Fixed the implementation of `manifold.TSNE:`
• early_exageration parameter had no effect and is now used for the first 250 optimization iterations.

• Fixed the AssertionError: Tree consistency failed exception reported in #8992.

• Improve the learning schedule to match the one from the reference implementation lvdmaaten/bhtsne. by Thomas Moreau and Olivier Grisel.

• Fix a bug in decomposition.LatentDirichletAllocation where the perplexity method was returning incorrect results because the transform method returns normalized document topic distributions as of version 0.18. #7954 by Gary Foreman.

• Fix output shape and bugs with n_jobs > 1 in decomposition.SparseCoder transform and decomposition.sparse_encode for one-dimensional data and one component. This also impacts the output shape of decomposition.DictionaryLearning. #8086 by Andreas Müller.

• Fixed the implementation of explained_variance_ in decomposition.PCA, decomposition.RandomizedPCA and decomposition.IncrementalPCA. #9105 by Hanmin Qin.

• Fixed the implementation of noise_variance_ in decomposition.PCA. #9108 by Hanmin Qin.

• Fixed a bug where cluster.DBSCAN gives incorrect result when input is a precomputed sparse matrix with initial rows all zero. #8306 by Akshay Gupta

• Fix a bug regarding fitting cluster.KMeans with a sparse array X and initial centroids, where X’s means were unnecessarily being subtracted from the centroids. #7872 by Josh Karnofsky.

• Fixes to the input validation in covariance.EllipticEnvelope. #8086 by Andreas Müller.

• Fixed a bug in covariance.MinCovDet where inputting data that produced a singular covariance matrix would cause the helper method _c_step to throw an exception. #3367 by Jeremy Steward

• Fixed a bug in manifold.TSNE affecting convergence of the gradient descent. #8768 by David DeTomaso.

• Fixed a bug in manifold.TSNE where it stored the incorrect kl_divergence_. #6507 by Sebastian Saeger.

• Fixed improper scaling in cross_decomposition.PLSRegression with scale=True. #7819 by jayzed2.

• cluster.bicluster.SpectralCoclustering and cluster.bicluster.SpectralBiclustering fit method conforms with API by accepting y and returning the object. #6126, #7814 by Laurent Direr and Maniteja Nandana.

• Fix bug where feature_selection.SelectFdr did not exactly implement Benjamini-Hochberg procedure. It formerly may have selected fewer features than it should. #7702 by Levi John Wolf.

• Fixed the shrinkage implementation in neighbors.NearestCentroid. #9219 by Hanmin Qin.

Preprocessing and feature selection

• For sparse matrices, preprocessing.normalize with return_norm=True will now raise a NotImplementedError with ‘l1’ or ‘l2’ norm and with norm ‘max’ the norms returned will be the same as for dense matrices. #7771 by Ang Lu.

• Fix a bug where feature_selection.SelectFdr did not exactly implement Benjamini-Hochberg procedure. It formerly may have selected fewer features than it should. #7490 by Peng Meng.

• Fixed a bug where linear_model.RandomizedLasso and linear_model.RandomizedLogisticRegression breaks for sparse input. #8259 by Aman Dalmia.

• Fix a bug where feature_extraction.FeatureHasher mandatorily applied a sparse random projection to the hashed features, preventing the use of feature_extraction.text.HashingVectorizer in a pipeline with feature_extraction.text.TfidfTransformer. #7565 by Roman Yurchak.
• Fix a bug where `feature_selection.mutual_info_regression` did not correctly use `n_neighbors`. #8181 by Guillaume Lemaitre.

Model evaluation and meta-estimators

• Fixed a bug where `model_selection.validation_curve` reused the same estimator for each parameter value. #7365 by Aleksandr Sandrovskii.

`model_selection.permutation_test_score` now works with Pandas types. #5697 by Stijn Tonk.

• Several fixes to input validation in `multiclass.OutputCodeClassifier` #8086 by Andreas Müller.
• `multiclass.OneVsOneClassifier.partial_fit` now ensures all classes are provided up-front. #6250 by Asish Panda.
• Fix `multiclass.MultiOutputClassifier.predict_proba` to return a list of 2d arrays, rather than a 3d array. In the case where different target columns had different numbers of classes, a `ValueError` would be raised on trying to stack matrices with different dimensions. #8093 by Peter Bull.
• Cross validation now works with Pandas datatypes that have a read-only index. #9507 by Loic Esteve.

Metrics

• `metrics.average_precision_score` no longer linearly interpolates between operating points, and instead weighs precisions by the change in recall since the last operating point, as per the Wikipedia entry. (#7356). By Nick Dingwall and Gael Varoquaux.
• Fix a bug in `metrics.classification._check_targets` which would return 'binary' if `y_true` and `y_pred` were both 'binary', but the union of `y_true` and `y_pred` was 'multiclass'. #8377 by Loic Esteve.
• Fixed an integer overflow bug in `metrics.confusion_matrix` and hence `metrics.cohen_kappa_score`. #8354, #7929 by Joel Nothman and Jon Crall.
• Fixed passing of gamma parameter to the chi2 kernel in `metrics.pairwise.pairwise_kernels` #5211 by Nick Rhinehart, Saurabh Bansod and Andreas Müller.

Miscellaneous

• Fixed a bug when `datasets.make_classification` fails when generating more than 30 features. #8159 by Herilalaina Rakotoarison.
• Fixed a bug where `datasets.make_moons` gives an incorrect result when `n_samples` is odd. #8198 by Josh Levy.
• Some `fetch_` functions in `datasets` were ignoring the `download_if_missing` keyword. #7944 by Ralf Gommers.
• Fix estimators to accept a `sample_weight` parameter of type `pandas.Series` in their `fit` function. #7825 by Kathleen Chen.
• Fix a bug in cases where `numpy.cumsum` may be numerically unstable, raising an exception if instability is identified. #7376 and #7331 by Joel Nothman and @yangarbiter.
• Fix a bug where `base.BaseEstimator.__getstate__` obstructed pickling customizations of child-classes, when used in a multiple inheritance context. #8316 by Holger Peters.

• Update Sphinx-Gallery from 0.1.4 to 0.1.7 for resolving links in documentation build with Sphinx>1.5 #8010, #7986 by Oscar Najera

• Add `data_home` parameter to `sklearn.datasets.fetch_kddcup99`. #9289 by Loic Esteve.

• Fix dataset loaders using Python 3 version of makedirs to also work in Python 2. #9284 by Sebastin Santy.

• Several minor issues were fixed with thanks to the alerts of lgtm.com. #9278 by Jean Helie, among others.

API changes summary

Trees and ensembles

• Gradient boosting base models are no longer estimators. By Andreas Müller.

• All tree based estimators now accept a `min_impurity_decrease` parameter in lieu of the `min_impurity_split`, which is now deprecated. The `min_impurity_decrease` helps stop splitting the nodes in which the weighted impurity decrease from splitting is no longer at least `min_impurity_decrease`. #8449 by Raghav RV.

Linear, kernelized and related models


Other predictors

• `neighbors.LSHForest` has been deprecated and will be removed in 0.21 due to poor performance. #9078 by Laurent Diner.

• `neighbors.NearestCentroid` no longer purports to support `metric='precomputed'` which now raises an error. #8515 by Sergul Aydore.

• The alpha parameter of `semi_supervised.LabelPropagation` now has no effect and is deprecated to be removed in 0.21. #9239 by Andre Ambrosio Boechat, Utkarsh Upadhyay, and Joel Nothman.

Decomposition, manifold learning and clustering

• Deprecate the `doc_topic_distr` argument of the perplexity method in `decomposition.LatentDirichletAllocation` because the user no longer has access to the unnormalized document topic distribution needed for the perplexity calculation. #7954 by Gary Foreman.

• The `n_topics` parameter of `decomposition.LatentDirichletAllocation` has been renamed to `n_components` and will be removed in version 0.21. #8922 by @Attractadore.

• `decomposition.SparsePCA.transform`'s `ridge_alpha` parameter is deprecated in preference for class parameter. #8137 by Naoya Kanai.

• `cluster.DBSCAN` now has a `metric_params` parameter. #8139 by Naoya Kanai.

Preprocessing and feature selection

• `feature_selection.SelectFromModel` now has a `partial_fit` method only if the underlying estimator does. By Andreas Müller.

• `feature_selection.SelectFromModel` now validates the threshold parameter and sets the `threshold` attribute during the call to `fit`, and no longer during the call to `transform`. By Andreas Müller.
• The non_negative parameter in feature_extraction.FeatureHasher has been deprecated, and replaced with a more principled alternative, alternate_sign. #7565 by Roman Yurchak.
• linear_model.RandomizedLogisticRegression, and linear_model.RandomizedLasso have been deprecated and will be removed in version 0.21. #8995 by Ramana.S.

Model evaluation and meta-estimators
• Deprecate the fit_params constructor input to the model_selection.GridSearchCV and model_selection.RandomizedSearchCV in favor of passing keyword parameters to the fit methods of those classes. Data-dependent parameters needed for model training should be passed as keyword arguments to fit, and conforming to this convention will allow the hyperparameter selection classes to be used with tools such as model_selection.cross_val_predict. #2879 by Stephen Hoover.
• In version 0.21, the default behavior of splitters that use the test_size and train_size parameter will change, such that specifying train_size alone will cause test_size to be the remainder. #7459 by Nelson Liu.
• multiclass.OneVsRestClassifier now has partial_fit, decision_function and predict_proba methods only when the underlying estimator does. #7812 by Andreas Müller and Mikhail Korobov.
• multiclass.OneVsRestClassifier now has a partial_fit method only if the underlying estimator does. By Andreas Müller.
• The decision_function output shape for binary classification in multiclass. OneVsRestClassifier and multiclass.OneVsOneClassifier is now (n_samples,) to conform to scikit-learn conventions. #9100 by Andreas Müller.
• The multioutput.MultiOutputClassifier.predict_proba function used to return a 3d array (n_samples, n_classes, n_outputs). In the case where different target columns had different numbers of classes, a ValueError would be raised on trying to stack matrices with different dimensions. This function now returns a list of arrays where the length of the list is n_outputs, and each array is (n_samples, n_classes) for that particular output. #8093 by Peter Bull.
• Replace attribute named_steps dict to utils.Bunch in pipeline.Pipeline to enable tab completion in interactive environment. In the case conflict value on named_steps and dict attribute, dict behavior will be prioritized. #8481 by Herilalaina Rakotoarison.

Miscellaneous
• Deprecate the y parameter in transform and inverse_transform. The method should not accept y parameter, as it’s used at the prediction time. #8174 by Tahar Zanouda, Alexandre Gramfort and Raghav RV.
• SciPy >= 0.13.3 and NumPy >= 1.8.2 are now the minimum supported versions for scikit-learn. The following backported functions in utils have been removed or deprecated accordingly. #8854 and #8874 by Naoya Kanai
• The store_covariances and covariances_ parameters of discriminant_analysis. QuadraticDiscriminantAnalysis has been renamed to store_covariance and covariance_ to be consistent with the corresponding parameter names of the discriminant_analysis. LinearDiscriminantAnalysis. They will be removed in version 0.21. #7998 by Jiacheng

Removed in 0.19:
- utils.fixes.argpartition
- utils.fixes.array_equal
- utils.fixes.astype
- utils.fixes.bincount
- `utils.fixes.expit`
- `utils.fixes.frombuffer_empty`
- `utils.fixes.in1d`
- `utils.fixes.norm`
- `utils.fixes.rankdata`
- `utils.fixes.safe_copy`

Deprecated in 0.19, to be removed in 0.21:

- `utils.arpack.eigs`
- `utils.arpack.eigsh`
- `utils.arpack.svds`
- `utils.extmath.fast_dot`
- `utils.extmath.logsumexp`
- `utils.extmath.norm`
- `utils.extmath.pinvh`
- `utils.graph.graph_laplacian`
- `utils.random.choice`
- `utils.sparsefuncs.connected_components`
- `utils.stats.rankdata`

• Estimators with both methods `decision_function` and `predict_proba` are now required to have a monotonic relation between them. The method `check_decision_proba_consistency` has been added in `utils.estimator_checks` to check their consistency. #7578 by Shubham Bhardwaj

• All checks in `utils.estimator_checks`, in particular `utils.estimator_checks.check_estimator` now accept estimator instances. Most other checks do not accept estimator classes any more. #9019 by Andreas Müller.

• Ensure that estimators’ attributes ending with `_` are not set in the constructor but only in the `fit` method. Most notably, ensemble estimators (deriving from `ensemble.BaseEnsemble`) now only have `self.estimators_` available after `fit`. #7464 by Lars Buitinck and Loic Esteve.

### Code and Documentation Contributors

Thanks to everyone who has contributed to the maintenance and improvement of the project since version 0.18, including:

Scikit-learn 0.18 is the last major release of scikit-learn to support Python 2.6. Later versions of scikit-learn will require Python 2.7 or above.

**1.7.20 Version 0.18.2**

June 20, 2017

**Last release with Python 2.6 support**

Scikit-learn 0.18 is the last major release of scikit-learn to support Python 2.6. Later versions of scikit-learn will require Python 2.7 or above.

**Changelog**

- Fixes for compatibility with NumPy 1.13.0: #7946 #8355 by Loic Esteve.
- Minor compatibility changes in the examples #9010 #8040 #9149.

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Changelog

Enhancements

• Improved `sample_without_replacement` speed by utilizing `numpy.random.permutation` for most cases. As a result, samples may differ in this release for a fixed random state. Affected estimators:
  - `ensemble.BaggingClassifier`
  - `ensemble.BaggingRegressor`
  - `linear_model.RANSACRegressor`
  - `model_selection.RandomizedSearchCV`
  - `random_projection.SparseRandomProjection`
  This also affects the `datasets.make_classification` method.

Bug fixes

• Fix issue where `min_grad_norm` and `n_iter_without_progress` parameters were not being utilised by `manifold.TSNE`. #6497 by Sebastian Säger

• Fix bug for svm’s decision values when `decision_function_shape` is ovr in `svm.SVC`. `svm.SVC`’s decision function was incorrect from versions 0.17.0 through 0.18.0. #7724 by Bing Tian Dai

• Attribute `explained_variance_ratio` of `discriminant_analysis.LinearDiscriminantAnalysis` calculated with SVD and Eigen solver are now of the same length. #7632 by JPFrancoia

• Fixes issue in Univariate feature selection where score functions were not accepting multi-label targets. #7676 by Mohammed Affan

• Fixed setting parameters when calling `fit` multiple times on `feature_selection.SelectFromModel`. #7756 by Andreas Müller

• Fixes issue in `partial_fit` method of `multiclass.OneVsRestClassifier` when number of classes used in `partial_fit` was less than the total number of classes in the data. #7786 by Srivatsan Ramesh

• Fixes issue in `calibration.CalibratedClassifierCV` where the sum of probabilities of each class for a data was not 1, and `CalibratedClassifierCV` now handles the case where the training set has less number of classes than the total data. #7799 by Srivatsan Ramesh

• Fix a bug where `sklearn.feature_selection.SelectFdr` did not exactly implement Benjamini-Hochberg procedure. It formerly may have selected fewer features than it should. #7490 by Peng Meng.

• `sklearn.manifold.LocallyLinearEmbedding` now correctly handles integer inputs. #6282 by Jake Vanderplas.
• The `min_weight_fraction_leaf` parameter of tree-based classifiers and regressors now assumes uniform sample weights by default if the `sample_weight` argument is not passed to the `fit` function. Previously, the parameter was silently ignored. #7301 by Nelson Liu.

• Numerical issue with `linear_model.RidgeCV` on centered data when `n_features > n_samples`. #6178 by Bertrand Thirion

• Tree splitting criterion classes’ cloning/pickling is now memory safe #7680 by Ibraim Ganiev.

• Fixed a bug where `decomposition.NMF` sets its `n_iters_` attribute in `transform()`. #7553 by Ekaterina Krivich.

• `sklearn.linear_model.LogisticRegressionCV` now correctly handles string labels. #5874 by Raghav RV.

• Fixed a bug where `sklearn.model_selection.train_test_split` raised an error when `stratify` is a list of string labels. #7593 by Raghav RV.

• Fixed a bug where `sklearn.model_selection.GridSearchCV` and `sklearn.model_selection.RandomizedSearchCV` were not pickleable because of a pickling bug in `np.ma.MaskedArray`. #7594 by Raghav RV.

• All cross-validation utilities in `sklearn.model_selection` now permit one time cross-validation splitters for the `cv` parameter. Also non-deterministic cross-validation splitters (where multiple calls to `split` produce dissimilar splits) can be used as `cv` parameter. The `sklearn.model_selection.GridSearchCV` will cross-validate each parameter setting on the split produced by the first `split` call to the cross-validation splitter. #7660 by Raghav RV.

• Fix bug where `preprocessing.MultiLabelBinarizer.fit_transform` returned an invalid CSR matrix. #7750 by CJ Carey.

• Fixed a bug where `metrics.pairwise.cosine_distances` could return a small negative distance. #7732 by Artsion.

API changes summary

Trees and forests

• The `min_weight_fraction_leaf` parameter of tree-based classifiers and regressors now assumes uniform sample weights by default if the `sample_weight` argument is not passed to the `fit` function. Previously, the parameter was silently ignored. #7301 by Nelson Liu.

• Tree splitting criterion classes’ cloning/pickling is now memory safe. #7680 by Ibraim Ganiev.

Linear, kernelized and related models

• Length of `explained_variance_ratio` of `discriminant_analysis.LinearDiscriminantAnalysis` changed for both Eigen and SVD solvers. The attribute has now a length of `min(n_components, n_classes - 1)`. #7632 by JPFrancoia

• Numerical issue with `linear_model.RidgeCV` on centered data when `n_features > n_samples`. #6178 by Bertrand Thirion
Model Selection Enhancements and API Changes

• The model_selection module

The new module `sklearn.model_selection`, which groups together the functionalities of formerly `sklearn.cross_validation`, `sklearn.grid_search` and `sklearn.learning_curve`, introduces new possibilities such as nested cross-validation and better manipulation of parameter searches with Pandas.

Many things will stay the same but there are some key differences. Read below to know more about the changes.

• Data-independent CV splitters enabling nested cross-validation

The new cross-validation splitters, defined in the `sklearn.model_selection`, are no longer initialized with any data-dependent parameters such as `y`. Instead they expose a `split` method that takes in the data and yields a generator for the different splits.

This change makes it possible to use the cross-validation splitters to perform nested cross-validation, facilitated by `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` utilities.

• The enhanced cv_results_ attribute

The new `cv_results_` attribute (of `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV`) introduced in lieu of the `grid_scores_` attribute is a dict of 1D arrays with elements in each array corresponding to the parameter settings (i.e. search candidates).

The `cv_results_` dict can be easily imported into pandas as a DataFrame for exploring the search results.

The `cv_results_` arrays include scores for each cross-validation split (with keys such as 'split0_test_score'), as well as their mean ('mean_test_score') and standard deviation ('std_test_score').

The ranks for the search candidates (based on their mean cross-validation score) is available at `cv_results_['rank_test_score']`.

The parameter values for each parameter is stored separately as numpy masked object arrays. The value, for that search candidate, is masked if the corresponding parameter is not applicable. Additionally a list of all the parameter dicts are stored at `cv_results_['params']`.

• Parameters n_folds and n_iter renamed to n_splits

Some parameter names have changed: The `n_folds` parameter in new `model_selection.KFold`, `model_selection.GroupKFold` (see below for the name change), and `model_selection.StratifiedKFold` is now renamed to `n_splits`. The `n_iter` parameter in `model_selection.ShuffleSplit`, the new class `model_selection.GroupShuffleSplit` and `model_selection.StratifiedShuffleSplit` is now renamed to `n_splits`.

• Rename of splitter classes which accepts group labels along with data

Note the change from singular to plural form in `model_selection.LeavePGroupsOut`.

- **Fit parameter labels renamed to groups**

  The `labels` parameter in the `split` method of the newly renamed splitters `model_selection.GroupKFold`, `model_selection.LeaveOneGroupOut`, `model_selection.LeavePGroupsOut`, `model_selection.GroupShuffleSplit` is renamed to `groups` following the new nomenclature of their class names.

- **Parameter n_labels renamed to n_groups**

  The parameter `n_labels` in the newly renamed `model_selection.LeavePGroupsOut` is changed to `n_groups`.

- **Training scores and Timing information**

  `cv_results_` also includes the training scores for each cross-validation split (with keys such as `'split0_train_score'`), as well as their mean (`'mean_train_score'`) and standard deviation (`'std_train_score'`). To avoid the cost of evaluating training score, set `return_train_score=False`.

  Additionally the mean and standard deviation of the times taken to split, train and score the model across all the cross-validation splits is available at the key `'mean_time'` and `'std_time'` respectively.

**Changelog**

**New features**

Classifiers and Regressors

- The Gaussian Process module has been reimplemented and now offers classification and regression estimators through `gaussian_process.GaussianProcessClassifier` and `gaussian_process.GaussianProcessRegressor`. Among other things, the new implementation supports kernel engineering, gradient-based hyperparameter optimization or sampling of functions from GP prior and GP posterior. Extensive documentation and examples are provided. By Jan Hendrik Metzen.

- Added new supervised learning algorithm: **Multi-layer Perceptron** #3204 by Issam H. Laradji

- Added `linear_model.HuberRegressor`, a linear model robust to outliers. #5291 by Manoj Kumar.

- Added the `multioutput.MultiOutputRegressor` meta-estimator. It converts single output regressors to multi-output regressors by fitting one regressor per output. By Tim Head.

Other estimators

- New `mixture.GaussianMixture` and `mixture.BayesianGaussianMixture` replace former mixture models, employing faster inference for sounder results. #7295 by Wei Xue and Thierry Guillemot.

- Class `decomposition.RandomizedPCA` is now factored into `decomposition.PCA` and it is available calling with parameter `svd_solver='randomized'`. The default number of `n_iter` for 'randomized' has changed to 4. The old behavior of PCA is recovered by `svd_solver='full'`. An additional solver calls `arpack` and performs truncated (non-randomized) SVD. By default, the best solver is selected depending on the size of the input and the number of components requested. #5299 by Giorgio Patrini.

- Added two functions for mutual information estimation: `feature_selection.mutual_info_classif` and `feature_selection.mutual_info_regression`. These
functions can be used in `feature_selection.SelectKBest` and `feature_selection.SelectPercentile` as score functions. By Andrea Bravi and Nikolay Mayorov.

- **Added** the `ensemble.IsolationForest` class for anomaly detection based on random forests. By Nicolas Goix.
- **Added** `algorithm="elkan"` to `cluster.KMeans` implementing Elkan's fast K-Means algorithm. By Andreas Müller.

### Model selection and evaluation

- **Added** `metrics.cluster.fowlkes_mallows_score`, the Fowlkes Mallows Index which measures the similarity of two clusterings of a set of points. By Arnaud Fouchet and Thierry Guillemot.
- **Added** `metrics.calinski_harabaz_score`, which computes the Calinski and Harabaz score to evaluate the resulting clustering of a set of points. By Arnaud Fouchet and Thierry Guillemot.
- **Added** new cross-validation splitter `model_selection.TimeSeriesSplit` to handle time series data. #6586 by YenChen Lin
- The cross-validation iterators are replaced by cross-validation splitters available from `sklearn.model_selection`, allowing for nested cross-validation. See *Model Selection Enhancements and API Changes* for more information. #4294 by Raghav RV.

### Enhancements

#### Trees and ensembles

- **Added** a new splitting criterion for `tree.DecisionTreeRegressor`, the mean absolute error. This criterion can also be used in `ensemble.ExtraTreesRegressor`, `ensemble.RandomForestRegressor`, and the gradient boosting estimators. #6667 by Nelson Liu.
- **Added** weighted impurity-based early stopping criterion for decision tree growth. #6954 by Nelson Liu
- The random forest, extra tree and decision tree estimators now has a method `decision_path` which returns the decision path of samples in the tree. By Arnaud Joly.
- A new example has been added unveiling the decision tree structure. By Arnaud Joly.
- Random forest, extra trees, decision trees and gradient boosting estimator accept the parameter `min_samples_split` and `min_samples_leaf` provided as a percentage of the training samples. By yelite and Arnaud Joly.
- Gradient boosting estimators accept the parameter `criterion` to specify to splitting criterion used in built decision trees. #6667 by Nelson Liu.
- The memory footprint is reduced (sometimes greatly) for `ensemble.bagging.BaseBagging` and classes that inherit from it, i.e. `ensemble.BaggingClassifier`, `ensemble.BaggingRegressor`, and `ensemble.IsolationForest`, by dynamically generating attribute `estimators_samples_` only when it is needed. By David Staub.
- **Added** `n_jobs` and `sample_weight` parameters for `ensemble.VotingClassifier` to fit underlying estimators in parallel. #5805 by Ibraim Ganieva.

#### Linear, kernelized and related models

- **In** `linear_model.LogisticRegression`, the SAG solver is now available in the multinomial case. #5251 by Tom Dupre la Tour.
- `linear_model.RANSACRegressor`, `svm.LinearSVC` and `svm.LinearSVR` now support `sample_weight`. By Imaculate.
• Add parameter `loss` to `linear_model.RANSACRegressor` to measure the error on the samples for every trial. By Manoj Kumar.

• Prediction of out-of-sample events with Isotonic Regression (`isotonic.IsotonicRegression`) is now much faster (over 1000x in tests with synthetic data). By Jonathan Arfa.

• Isotonic regression (`isotonic.IsotonicRegression`) now uses a better algorithm to avoid $O(n^2)$ behavior in pathological cases, and is also generally faster (#6691). By Antony Lee.

• `naive_bayes.GaussianNB` now accepts data-independent class-priors through the parameter `priors`. By Guillaume Lemaitre.

• `linear_model.ElasticNet` and `linear_model.Lasso` now works with `np.float32` input data without converting it into `np.float64`. This allows to reduce the memory consumption. #6913 by YenChen Lin.

• `semi_supervised.LabelPropagation` and `semi_supervised.LabelSpreading` now accept arbitrary kernel functions in addition to strings `knn` and `rbf`. #5762 by Utkarsh Upadhyay.

Decomposition, manifold learning and clustering

• Added `inverse_transform` function to `decomposition.NMF` to compute data matrix of original shape. By Anish Shah.

• `cluster.KMeans` and `cluster.MiniBatchKMeans` now works with `np.float32` and `np.float64` input data without converting it. This allows to reduce the memory consumption by using `np.float32`. #6846 by Sebastian Säger and YenChen Lin.

Preprocessing and feature selection

• `preprocessing.RobustScaler` now accepts `quantile_range` parameter. #5929 by Konstantin Podshumok.

• `feature_extraction.FeatureHasher` now accepts string values. #6173 by Ryad Zenine and Devashish Deshpande.

• Keyword arguments can now be supplied to `func` in `preprocessing.FunctionTransformer` by means of the `kw_args` parameter. By Brian McFee.

• `feature_selection.SelectKBest` and `feature_selection.SelectPercentile` now accept score functions that take X, y as input and return only the scores. By Nikolay Mayorov.

Model evaluation and meta-estimators

• `multiclass.OneVsOneClassifier` and `multiclass.OneVsRestClassifier` now support `partial_fit`. By Asish Panda and Philipp Dowling.

• Added support for substituting or disabling `pipeline.Pipeline` and `pipeline.FeatureUnion` components using the `set_params` interface that powers sklearn.grid_search. See `Selecting dimensionality reduction with Pipeline and GridSearchCV` By Joel Nothman and Robert McGibbon.

• The new `cv_results_` attribute of `model_selection.GridSearchCV` (and `model_selection.RandomizedSearchCV`) can be easily imported into pandas as a DataFrame. Ref `Model Selection Enhancements and API Changes` for more information. #6697 by Raghav RV.

• Generalization of `model_selection.cross_val_predict`. One can pass method names such as `predict_proba` to be used in the cross validation framework instead of the default `predict`. By Ori Ziv and Sears Merritt.

• The training scores and time taken for training followed by scoring for each search candidate are now available at the `cv_results_` dict. See `Model Selection Enhancements and API Changes` for more information. #7325 by Eugene Chen and Raghav RV.
• Added labels flag to `metrics.log_loss` to explicitly provide the labels when the number of classes in `y_true` and `y_pred` differ. #7239 by Hong Guangguo with help from Mads Jensen and Nelson Liu.

• Support sparse contingency matrices in cluster evaluation (`metrics.cluster.supervised`) to scale to a large number of clusters. #7419 by Gregory Stupp and Joel Nothman.

• Add `sample_weight` parameter to `metrics.matthews_corrcoef`. By Jatin Shah and Raghav RV.

• Speed up `metrics.silhouette_score` by using vectorized operations. By Manoj Kumar.

• Add `sample_weight` parameter to `metrics.confusion_matrix`. By Bernardo Stein.

Miscellaneous

• Added `n_jobs` parameter to `feature_selection.RFECV` to compute the score on the test folds in parallel. By Manoj Kumar.

• Codebase does not contain C/C++ cython generated files: they are generated during build. Distribution packages will still contain generated C/C++ files. By Arthur Mensch.

• Reduce the memory usage for 32-bit float input arrays of `utils.sparse_func.mean_variance_axis` and `utils.sparse_func.incr_mean_variance_axis` by supporting cython fused types. By YenChen Lin.

• The `ignore_warnings` now accept a category argument to ignore only the warnings of a specified type. By Thierry Guillemot.

• Added parameter `return_X_y` and return type `(data, target) : tuple` option to `load_iris` dataset #7049, `load_breast_cancer` dataset #7152, `load_digits` dataset, `load_diabetes` dataset, `load_linnerud` dataset, `load_boston` dataset #7154 by Manvendra Singh.

• Simplification of the `clone` function, deprecate support for estimators that modify parameters in `__init__`. #5540 by Andreas Müller.

• When unpickling a scikit-learn estimator in a different version than the one the estimator was trained with, a `UserWarning` is raised, see the documentation on model persistence for more details. (#7248) By Andreas Müller.

Bug fixes

Trees and ensembles

• Random forest, extra trees, decision trees and gradient boosting won’t accept anymore `min_samples_split=1` as at least 2 samples are required to split a decision tree node. By Arnaud Joly

• `ensemble.VotingClassifier` now raises `NotFittedError` if `predict`, `transform` or `predict_proba` are called on the non-fitted estimator. by Sebastian Raschka.

• Fix bug where `ensemble.AdaBoostClassifier` and `ensemble.AdaBoostRegressor` would perform poorly if the `random_state` was fixed (#7411). By Joel Nothman.

• Fix bug in ensembles with randomization where the ensemble would not set `random_state` on base estimators in a pipeline or similar nesting. (#7411). Note, results for `ensemble.BaggingClassifier` `ensemble.BaggingRegressor`, `ensemble.AdaBoostClassifier` and `ensemble.AdaBoostRegressor` will now differ from previous versions. By Joel Nothman.

Linear, kernelized and related models

• Fixed incorrect gradient computation for `loss='squared_epsilon_insensitive'` in `linear_model.SGDClassifier` and `linear_model.SGDRegressor` (#6764). By Wenhua Yang.
• Fix bug in `linear_model.LogisticRegressionCV` where solver='liblinear' did not accept class_weights='balanced'. (#6817). By Tom Dupre la Tour.

• Fix bug in `neighbors.RadiusNeighborsClassifier` where an error occurred when there were outliers being labelled and a weight function specified (#6902). By LeonieBorne.

• Fix `linear_model.ElasticNet` sparse decision function to match output with dense in the multioutput case.

Decomposition, manifold learning and clustering

• `decomposition.RandomizedPCA` default number of iterated_power is 4 instead of 3. #5141 by Giorgio Patrini.

• `utils.extmath.randomized_svd` performs 4 power iterations by default, instead or 0. In practice this is enough for obtaining a good approximation of the true eigenvalues/vectors in the presence of noise. When n_components is small (< .1 * min(X.shape)) n_iter is set to 7, unless the user specifies a higher number. This improves precision with few components. #5299 by Giorgio Patrini.

• Whiten/non-whiten inconsistency between components of `decomposition.PCA` and `decomposition.RandomizedPCA` (now factored into PCA, see the New features) is fixed. components_ are stored with no whitening. #5299 by Giorgio Patrini.

• Fixed bug in `manifold.spectral_embedding` where diagonal of unnormalized Laplacian matrix was incorrectly set to 1. #4995 by Peter Fischer.


• Attribute `explained_variance_ratio_` calculated with the SVD solver of `discriminant_analysis.LinearDiscriminantAnalysis` now returns correct results. By JPFrancoia

Preprocessing and feature selection

• `preprocessing.data._transform_selected` now always passes a copy of X to transform function when copy=True (#7194). By Caio Oliveira.

Model evaluation and meta-estimators

• `model_selection.StratifiedKFold` now raises error if all n_labels for individual classes is less than n_folds. #6182 by Devashish Deshpande.

• Fixed bug in `model_selection.StratifiedShuffleSplit` where train and test sample could overlap in some edge cases, see #6121 for more details. By Loic Esteve.

• Fix in `sklearn.model_selection.StratifiedShuffleSplit` to return splits of size `train_size` and `test_size` in all cases (#6472). By Andreas Müller.

• Cross-validation of `OneVsOneClassifier` and `OneVsRestClassifier` now works with precomputed kernels. #7350 by Russell Smith.

• Fix incomplete `predict_proba` method delegation from `model_selection.GridSearchCV` to `linear_model.SGDClassifier` (#7159) by Yichuan Liu.

Metrics

• Fix bug in `metrics.silhouette_score` in which clusters of size 1 were incorrectly scored. They should get a score of 0. By Joel Nothman.

• Fix bug in `metrics.silhouette_samples` so that it now works with arbitrary labels, not just those ranging from 0 to n_clusters - 1.
• Fix bug where expected and adjusted mutual information were incorrect if cluster contingency cells exceeded $2^{16}$. By Joel Nothman.

• `metrics.pairwise.pairwise_distances` now converts arrays to boolean arrays when required in `scipy.spatial.distance`. #5460 by Tom Dupre la Tour.

• Fix sparse input support in `metrics.silhouette_score` as well as example examples/text/document_clustering.py. By YenChen Lin.

• `metrics roc_curve` and `metrics.precision_recall_curve` no longer round y_score values when creating ROC curves; this was causing problems for users with very small differences in scores (#7353).

Miscellaneous

• `model_selection.tests._search._check_param_grid` now works correctly with all types that extends/implements Sequence (except string), including range (Python 3.x) and xrange (Python 2.x). #7323 by Viacheslav Kovalevskyi.

• `utils.extmath.randomized_range_finder` is more numerically stable when many power iterations are requested, since it applies LU normalization by default. If n_iter<2 numerical issues are unlikely, thus no normalization is applied. Other normalization options are available: 'none', 'LU' and 'QR'. #5141 by Giorgio Patrini.

• Fix a bug where some formats of `scipy.sparse` matrix, and estimators with them as parameters, could not be passed to `base.clone`. By Loic Estevé.

• `datasets.load_svmlight_file` now is able to read long int QID values. #7101 by Ibraim Ganiev.

API changes summary

Linear, kernelized and related models

• `residual_metric` has been deprecated in `linear_model.RANSACRegressor`. Use `loss` instead. By Manoj Kumar.

• Access to public attributes `.X_` and `.y_` has been deprecated in `isotonic.IsotonicRegression`. By Jonathan Arfa.

Decomposition, manifold learning and clustering

• The old `mixture.DPGMM` is deprecated in favor of the new `mixture.BayesianGaussianMixture` (with the parameter `weight_concentration_prior_type='dirichlet_process'`). The new class solves the computational problems of the old class and computes the Gaussian mixture with a Dirichlet process prior faster than before. #7295 by Wei Xue and Thierry Guillemot.

• The old `mixture.VBGMM` is deprecated in favor of the new `mixture.BayesianGaussianMixture` (with the parameter `weight_concentration_prior_type='dirichlet_distribution'`). The new class solves the computational problems of the old class and computes the Variational Bayesian Gaussian mixture faster than before. #6651 by Wei Xue and Thierry Guillemot.

• The old `mixture.GMM` is deprecated in favor of the new `mixture.GaussianMixture`. The new class computes the Gaussian mixture faster than before and some of computational problems have been solved. #6666 by Wei Xue and Thierry Guillemot.

Model evaluation and meta-estimators

• The `sklearn.cross_validation`, `sklearn.grid_search` and `sklearn.learning_curve` have been deprecated and the classes and functions have been reorganized into the `sklearn.model_selection` module. Ref `Model Selection Enhancements and API Changes` for more information. #4294 by Raghav RV.
• The `grid_scores_` attribute of `model_selection.GridSearchCV` and `model_selection.RandomizedSearchCV` is deprecated in favor of the attribute `cv_results_`. Ref Model Selection Enhancements and API Changes for more information. #6697 by Raghav RV.

• The parameters `n_iter` or `n_folds` in old CV splitters are replaced by the new parameter `n_splits` since it can provide a consistent and unambiguous interface to represent the number of train-test splits. #7187 by YenChen Lin.

• `classes` parameter was renamed to `labels` in `metrics.hamming_loss`. #7260 by Sebastián Vanrell.

• The splitter classes LabelKFold, LabelShuffleSplit, LeaveOneLabelOut and LeavePLabelsOut are renamed to `model_selection.GroupKFold`, `model_selection.GroupShuffleSplit`, `model_selection.LeaveOneGroupOut` and `model_selection.LeavePGroupsOut` respectively. Also the parameter `labels` in the `split` method of the newly renamed splitters `model_selection.LeaveOneGroupOut` and `model_selection.LeavePGroupsOut` is renamed to `groups`. Additionally in `model_selection.LeavePGroupsOut`, the parameter `n_labels` is renamed to `n_groups`. #6660 by Raghav RV.

• Error and loss names for `scoring` parameters are now prefixed by 'neg_', such as `neg_mean_squared_error`. The unprefixed versions are deprecated and will be removed in version 0.20. #7261 by Tim Head.

Code Contributors

1.7.23 Version 0.17.1

February 18, 2016

Changelog

Bug fixes

- Upgrade vendored joblib to version 0.9.4 that fixes an important bug in `joblib.Parallel` that can silently yield to wrong results when working on datasets larger than 1MB: https://github.com/joblib/joblib/blob/0.9.4/CHANGES.rst

- Fixed reading of Bunch pickles generated with scikit-learn version <= 0.16. This can affect users who have already downloaded a dataset with scikit-learn 0.16 and are loading it with scikit-learn 0.17. See #6196 for how this affected `datasets.fetch_20newsgroups`. By Loic Esteve.

- Fixed a bug that prevented using ROC AUC score to perform grid search on several CPU / cores on large arrays. See #6147 By Olivier Grisel.

- Fixed a bug that prevented to properly set the `presort` parameter in `ensemble.GradientBoostingRegressor`. See #5857 By Andrew McCulloh.

- Fixed a joblib error when evaluating the perplexity of a `decomposition.LatentDirichletAllocation` model. See #6258 By Chyi-Kwei Yau.

1.7.24 Version 0.17

November 5, 2015

Changelog

New features

- All the Scaler classes but `preprocessing.RobustScaler` can be fitted online by calling `partial_fit`. By Giorgio Patrini.

- The new class `ensemble.VotingClassifier` implements a “majority rule” / “soft voting” ensemble classifier to combine estimators for classification. By Sebastian Raschka.

- The new class `preprocessing.RobustScaler` provides an alternative to `preprocessing.StandardScaler` for feature-wise centering and range normalization that is robust to outliers. By Thomas Unterthiner.

- The new class `preprocessing.MaxAbsScaler` provides an alternative to `preprocessing.MinMaxScaler` for feature-wise range normalization when the data is already centered or sparse. By Thomas Unterthiner.
• The new class `preprocessing.FunctionTransformer` turns a Python function into a `Pipeline`-compatible transformer object. By Joe Jevnik.

• The new classes `cross_validation.LabelKfold` and `cross_validation.LabelShuffleSplit` generate train-test folds, respectively similar to `cross_validation.KFold` and `cross_validation.ShuffleSplit`, except that the folds are conditioned on a label array. By Brian McFee, Jean Kosassaï and Gilles Louppe.

• `decomposition.LatentDirichletAllocation` implements the Latent Dirichlet Allocation topic model with online variational inference. By Chyi-Kwei Yau, with code based on an implementation by Matt Hoffman. (#3659)

• The new solver `sag` implements a Stochastic Average Gradient descent and is available in both `linear_model.LogisticRegression` and `linear_model.Ridge`. This solver is very efficient for large datasets. By Danny Sullivan and Tom Dupre la Tour. (#4738)

• The new solver `cd` implements a Coordinate Descent in `decomposition.NMF`. Previous solver based on Projected Gradient is still available setting new parameter `solver` to `pg`, but is deprecated and will be removed in 0.19, along with `decomposition.ProjectedGradientNMF` and parameters `sparseness`, `beta` and `nls_max_iter`. New parameters `alpha` and `l1_ratio` control L1 and L2 regularization, and shuffle adds a shuffling step in the `cd` solver. By Tom Dupre la Tour and Mathieu Blondel.

Enhancements

• `manifold.TSNE` now supports approximate optimization via the Barnes-Hut method, leading to much faster fitting. By Christopher Erick Moody. (#4025)

• `cluster.mean_shift_.MeanShift` now supports parallel execution, as implemented in the `mean_shift` function. By Martino Sorbaro.

• `naive_bayes.GaussianNB` now supports fitting with `sample_weight`. By Jan Hendrik Metzen.

• `dummy.DummyClassifier` now supports a prior fitting strategy. By Arnaud Joly.

• Added a `fit_predict` method for `mixture.GMM` and subclasses. By Cory Lorenz.

• Added the `metrics.label_ranking_loss` metric. By Arnaud Joly.

• Added the `metrics.cohen_kappa_score` metric.

• Added a `warm_start` constructor parameter to the bagging ensemble models to increase the size of the ensemble. By Tim Head.

• Added option to use multi-output regression metrics without averaging. By Konstantin Shmelkov and Michael Eickenberg.

• Added `stratify` option to `cross_validation.train_test_split` for stratified splitting. By Miroslav Batchkarov.

• The `tree.export_graphviz` function now supports aesthetic improvements for `tree.DecisionTreeClassifier` and `tree.DecisionTreeRegressor`, including options for coloring nodes by their majority class or impurity, showing variable names, and using node proportions instead of raw sample counts. By Trevor Stephens.

• Improved speed of `newton-cg` solver in `linear_model.LogisticRegression`, by avoiding loss computation. By Mathieu Blondel and Tom Dupre la Tour.

• The `class_weight="auto"` heuristic in classifiers supporting `class_weight` was deprecated and replaced by the `class_weight="balanced"` option, which has a simpler formula and interpretation. By Hanna Wallach and Andreas Müller.
• Add `class_weight` parameter to automatically weight samples by class frequency for `linear_model.PassiveAggressiveClassifier`. By Trevor Stephens.

• Added backlinks from the API reference pages to the user guide. By Andreas Müller.

• The `labels` parameter to `sklearn.metrics.f1_score`, `sklearn.metrics.fbeta_score`, `sklearn.metrics.recall_score` and `sklearn.metrics.precision_score` has been extended. It is now possible to ignore one or more labels, such as where a multiclass problem has a majority class to ignore. By Joel Nothman.

• Add `sample_weight` support to `linear_model.RidgeClassifier`. By Trevor Stephens.

• Provide an option for sparse output from `sklearn.metrics.pairwise.cosine_similarity`. By Jaidev Deshpande.

• Add `minmax_scale` to provide a function interface for `MinMaxScaler`. By Thomas Unterthiner.

• `dump_svmlight_file` now handles multi-label datasets. By Chih-Wei Chang.

• RCV1 dataset loader (`sklearn.datasets.fetch_rcv1`). By Tom Dupre la Tour.

• The “Wisconsin Breast Cancer” classical two-class classification dataset is now included in scikit-learn, available with `sklearn.datasets.load_breast_cancer`.

• Upgraded to joblib 0.9.3 to benefit from the new automatic batching of short tasks. This makes it possible for scikit-learn to benefit from parallelism when many very short tasks are executed in parallel, for instance by the `grid_search.GridSearchCV` meta-estimator with `n_jobs > 1` used with a large grid of parameters on a small dataset. By Vlad Niculae, Olivier Grisel and Loic Esteve.

• For more details about changes in joblib 0.9.3 see the release notes: https://github.com/joblib/joblib/blob/master/CHANGES.rst#release-093

• Improved speed (3 times per iteration) of `decomposition.DictLearning` with coordinate descent method from `linear_model.Lasso`. By Arthur Mensch.

• Parallel processing (threaded) for queries of nearest neighbors (using the ball-tree) by Nikolay Mayorov.

• Allow `datasets.make_multilabel_classification` to output a sparse `y`. By Kashif Rasul.

• `cluster.DBSCAN` now accepts a sparse matrix of precomputed distances, allowing memory-efficient distance precomputation. By Joel Nothman.

• `tree.DecisionTreeClassifier` now exposes an `apply` method for retrieving the leaf indices samples are predicted as. By Daniel Galvez and Gilles Louppe.

• Speed up decision tree regressors, random forest regressors, extra trees regressors and gradient boosting estimators by computing a proxy of the impurity improvement during the tree growth. The proxy quantity is such that the split that maximizes this value also maximizes the impurity improvement. By Arnaud Joly, Jacob Schreiber and Gilles Louppe.

• Speed up tree based methods by reducing the number of computations needed when computing the impurity measure taking into account linear relationship of the computed statistics. The effect is particularly visible with extra trees and on datasets with categorical or sparse features. By Arnaud Joly.

• `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier` now expose an `apply` method for retrieving the leaf indices each sample ends up in under each try. By Jacob Schreiber.

• Add `sample_weight` support to `linear_model.LinearRegression`. By Sonny Hu. (#4881)

• Add `n_iter_without_progress` to `manifold.TSNE` to control the stopping criterion. By Santi Villalba. (#5186)
• Added optional parameter `random_state` in `linear_model.Ridge`, to set the seed of the pseudo random generator used in sag solver. By Tom Dupre la Tour.

• Added optional parameter `warm_start` in `linear_model.LogisticRegression`. If set to True, the solvers lbfgs, newton-cg and sag will be initialized with the coefficients computed in the previous fit. By Tom Dupre la Tour.

• Added sample_weight support to `linear_model.LogisticRegression` for the lbfgs, newton-cg, and sag solvers. By Valentin Stolbunov. Support added to the liblinear solver. By Manoj Kumar.

• Added optional parameter `presort` to `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier`, keeping default behavior the same. This allows gradient boosters to turn off presorting when building deep trees or using sparse data. By Jacob Schreiber.

• Altered `metrics.roc_curve` to drop unnecessary thresholds by default. By Graham Clenaghan.

• Added `feature_selection.SelectFromModel` meta-transformer which can be used along with estimators that have `coef_` or `feature_importances_` attribute to select important features of the input data. By Maheshakya Wijewardena, Joel Nothman and Manoj Kumar.

• Added `metrics.pairwise.laplacian_kernel`. By Clyde Fare.

• `covariance.GraphLasso` allows separate control of the convergence criterion for the Elastic-Net subproblem via the `enet_tol` parameter.

• Improved verbosity in `decomposition.DictionaryLearning`.

• `ensemble.RandomForestClassifier` and `ensemble.RandomForestRegressor` no longer explicitly store the samples used in bagging, resulting in a much reduced memory footprint for storing random forest models.

• Added positive option to `linear_model.Lars` and `linear_model.lars_path` to force coefficients to be positive. (#5131)

• Added the `X_norm_squared` parameter to `metrics.pairwise.euclidean_distances` to provide precomputed squared norms for X.

• Added the `fit_predict` method to `pipeline.Pipeline`.

• Added the `preprocessing.min_max_scale` function.

**Bug fixes**

• Fixed non-determinism in `dummy.DummyClassifier` with sparse multi-label output. By Andreas Müller.

• Fixed the output shape of `linear_model.RANSACRegressor` to `(n_samples, )`. By Andreas Müller.

• Fixed bug in `decomposition.DictLearning` when `n_jobs < 0`. By Andreas Müller.

• Fixed bug where `grid_search.RandomizedSearchCV` could consume a lot of memory for large discrete grids. By Joel Nothman.

• Fixed bug in `linear_model.LogisticRegressionCV` where `penalty` was ignored in the final fit. By Manoj Kumar.

• Fixed bug in `ensemble.forest.ForestClassifier` while computing oob_score and X is a sparse.csc_matrix. By Ankur Ankan.

• All regressors now consistently handle and warn when given y that is of shape `(n_samples, 1)`. By Andreas Müller and Henry Lin. (#5431)

• Fix in `cluster.KMeans` cluster reassignment for sparse input by Lars Buitinck.
• Fixed a bug in `lda.LDA` that could cause asymmetric covariance matrices when using shrinkage. By Martin Billinger.

• Fixed `cross_validation.cross_val_predict` for estimators with sparse predictions. By Buddha Prakash.

• Fixed the `predict_proba` method of `linear_model.LogisticRegression` to use soft-max instead of one-vs-rest normalization. By Manoj Kumar. (#5182)

• Fixed the `partial_fit` method of `linear_model.SGDClassifier` when called with `average=True`. By Andrew Lamb. (#5282)

• Dataset fetchers use different filenames under Python 2 and Python 3 to avoid pickling compatibility issues. By Olivier Grisel. (#5355)

• Fixed a bug in `naive_bayes.GaussianNB` which caused classification results to depend on scale. By Jake Vanderplas.

• Fixed temporarily `linear_model.Ridge`, which was incorrect when fitting the intercept in the case of sparse data. The fix automatically changes the solver to ‘sag’ in this case. #5360 by Tom Dupre la Tour.

• Fixed a performance bug in `decomposition.RandomizedPCA` on data with a large number of features and fewer samples. (#4478) By Andreas Müller, Loïc Estève and Giorgio Patrini.

• Fixed bug in `cross_decomposition.PLS` that yielded unstable and platform dependent output, and failed on `fit_transform`. By Arthur Mensch.

• Fixes to the `Bunch` class used to store datasets.

• Fixed `ensemble.plot_partial_dependence` ignoring the `percentiles` parameter.

• Providing a set as vocabulary in `CountVectorizer` no longer leads to inconsistent results when pickling.

• Fixed the conditions on when a precomputed Gram matrix needs to be recomputed in `linear_model.LinearRegression`, `linear_model.OrthogonalMatchingPursuit`, `linear_model.Lasso` and `linear_model.ElasticNet`.

• Fixed inconsistent memory layout in the coordinate descent solver that affected `linear_model.DictionaryLearning` and `covariance.GraphLasso`. (#5337) By Olivier Grisel.

• `manifold.LocallyLinearEmbedding` no longer ignores the `reg` parameter.

• Nearest Neighbor estimators with custom distance metrics can now be pickled. (#4362)

• Fixed a bug in `pipeline.FeatureUnion` where `transformer_weights` were not properly handled when performing grid-searches.

• Fixed a bug in `linear_model.LogisticRegression` and `linear_model.LogisticRegressionCV` when using `class_weight='balanced'` or `class_weight='auto'`. By Tom Dupre la Tour.

• Fixed bug #5495 when doing OVR(SVC(decision_function_shape="ovr")). Fixed by Elvis Dohmatob.
API changes summary

- Attribute data_min, data_max and data_range in preprocessing.MinMaxScaler are deprecated and won’t be available from 0.19. Instead, the class now exposes data_min_, data_max_ and data_range_. By Giorgio Patrini.

- All Scaler classes now have an scale_ attribute, the feature-wise rescaling applied by their transform methods. The old attribute std_ in preprocessing.StandardScaler is deprecated and superseded by scale_; it won’t be available in 0.19. By Giorgio Patrini.

- svm.SVC` and svm.NuSVC now have an decision_function_shape parameter to make their decision function of shape (n_samples, n_classes) by setting decision_function_shape='ovr'. This will be the default behavior starting in 0.19. By Andreas Müller.

- Passing 1D data arrays as input to estimators is now deprecated as it caused confusion in how the array elements should be interpreted as features or as samples. All data arrays are now expected to be explicitly shaped (n_samples, n_features). By Vighnesh Birodkar.

- lde.LDA and qda.QDA have been moved to discriminant_analysis. LinearDiscriminantAnalysis and discriminant_analysis. QuadraticDiscriminantAnalysis.

- The store_covariance and tol parameters have been moved from the fit method to the constructor in discriminant_analysis.LinearDiscriminantAnalysis and the store_covariances and tol parameters have been moved from the fit method to the constructor in discriminant_analysis. QuadraticDiscriminantAnalysis.

- Models inheriting from _LearntSelectorMixin will no longer support the transform methods. (i.e, RandomForests, GradientBoosting, LogisticRegression, DecisionTrees, SVMs and SGD related models). Wrap these models around the metatransformer feature_selection.SelectFromModel to remove features (according to coefs_ or feature_importances_) which are below a certain threshold value instead.

- cluster.KMeans re-runs cluster-assignments in case of non-convergence, to ensure consistency of predict(X) and labels_. By Vighnesh Birodkar.

- Classifier and Regressor models are now tagged as such using the _estimator_type attribute.

- Cross-validation iterators always provide indices into training and test set, not boolean masks.

- The decision_function on all regressors was deprecated and will be removed in 0.19. Use predict instead.

- datasets.load_lfw_pairs is deprecated and will be removed in 0.19. Use datasets. fetch_lfw_pairs instead.

- The deprecated hmm module was removed.

- The deprecated Bootstrap cross-validation iterator was removed.

- The deprecated Ward and WardAgglomerative classes have been removed. Use clustering. AgglomerativeClustering instead.

- cross_validation.check_cv is now a public function.

- The property residues_ of linear_model.LinearRegression is deprecated and will be removed in 0.19.

- The deprecated n_jobs parameter of linear_model.LinearRegression has been moved to the constructor.

- Removed deprecated class_weight parameter from linear_model.SGDClassifier’s fit method. Use the construction parameter instead.
• The deprecated support for the sequence of sequences (or list of lists) multilabel format was removed. To convert to and from the supported binary indicator matrix format, use `MultiLabelBinarizer`.

• The behavior of calling the `inverse_transform` method of `Pipeline.pipeline` will change in 0.19. It will no longer reshape one-dimensional input to two-dimensional input.

• The deprecated attributes `indicator_matrix_`, `multilabel_` and `classes_` of `preprocessing.LabelBinarizer` were removed.

• Using `gamma=0` in `svm.SVC` and `svm.SVR` to automatically set the gamma to `1. / n_features` is deprecated and will be removed in 0.19. Use `gamma="auto"` instead.

**Code Contributors**


**1.7.25 Version 0.16.1**

April 14, 2015

**Changelog**

**Bug fixes**

• Allow input data larger than `block_size` in `covariance.LedoitWolf` by Andreas Müller.

• Fix a bug in `isotonic.IsotonicRegression` deduplication that caused unstable result in `calibration.CalibratedClassifierCV` by Jan Hendrik Metzen.

• Fix sorting of labels in `func:preprocessing.label_binarize` by Michael Heilman.
Fix several stability and convergence issues in `cross_decomposition.CCA` and `cross_decomposition.PLSCanonical` by Andreas Müller.

- Fix a bug in `cluster.KMeans` when `precompute_distances=False` on fortran-ordered data.
- Fix a speed regression in `ensemble.RandomForestClassifier`'s `predict` and `predict_proba` by Andreas Müller.
- Fix a regression where `utils.shuffle` converted lists and dataframes to arrays, by Olivier Grisel.

1.7.26 Version 0.16

March 26, 2015

Highlights

- Speed improvements (notably in `cluster.DBSCAN`), reduced memory requirements, bug-fixes and better default settings.
- Multinomial Logistic regression and a path algorithm in `linear_model.LogisticRegressionCV`.
- `cluster.Birch` clustering method for large-scale datasets.
- Scalable approximate nearest neighbors search with Locality-sensitive hashing forests in `neighbors.LSHForest`.
- Improved error messages and better validation when using malformed input data.
- More robust integration with pandas dataframes.

Changelog

New features

- The new `neighbors.LSHForest` implements locality-sensitive hashing for approximate nearest neighbors search. By Maheshakya Wijewardena.
- Added `svm.LinearSVR`. This class uses the liblinear implementation of Support Vector Regression which is much faster for large sample sizes than `svm.SVR` with linear kernel. By Fabian Pedregosa and Qiang Luo.
- Incremental fit for `GaussianNB`.
- Added the `metrics.label_ranking_average_precision_score` metrics. By Arnaud Joly.
- Add the `metrics.coverage_error` metrics. By Arnaud Joly.
- Added `linear_model.LogisticRegressionCV`. By Manoj Kumar, Fabian Pedregosa, Gael Varoquaux and Alexandre Gramfort.
- Added `warm_start` constructor parameter to make it possible for any trained forest model to grow additional trees incrementally. By Laurent Diner.
• Added `sample_weight` support to `ensemble.GradientBoostingClassifier` and `ensemble.GradientBoostingRegressor`. By Peter Prettenhofer.

• Added `decomposition.IncrementalPCA`, an implementation of the PCA algorithm that supports out-of-core learning with a `partial_fit` method. By Kyle Kastner.

• Averaged SGD for `SGDClassifier` and `SGDRegressor` by Danny Sullivan.

• Added `cross_val_predict` function which computes cross-validated estimates. By Luis Pedro Coelho.

• Added `linear_model.TheilSenRegressor`, a robust generalized-median-based estimator. By Florian Wilhelm.

• Added `metrics.median_absolute_error`, a robust metric. By Gael Varoquaux and Florian Wilhelm.

• Add `cluster.Birch`, an online clustering algorithm. By Manoj Kumar, Alexandre Gramfort and Joel Nothman.

• Added shrinkage support to `discriminant_analysis.LinearDiscriminantAnalysis` using two new solvers. By Clemens Brunner and Martin Billinger.

• Added `kernel_ridge.KernelRidge`, an implementation of kernelized ridge regression. By Mathieu Blondel and Jan Hendrik Metzen.

• All solvers in `linear_model.Ridge` now support `sample_weight`. By Mathieu Blondel.

• Added `cross_validation.PredefinedSplit` cross-validation for fixed user-provided cross-validation folds. By Thomas Unterthiner.

• Added `calibration.CalibratedClassifierCV`, an approach for calibrating the predicted probabilities of a classifier. By Alexandre Gramfort, Jan Hendrik Metzen, Mathieu Blondel and Balazs Kegl.

Enhancements

• Add option `return_distance` in `hierarchical.ward_tree` to return distances between nodes for both structured and unstructured versions of the algorithm. By Matteo Visconti di Oleggio Castello. The same option was added in `hierarchical.linkage_tree`. By Manoj Kumar.

• Add support for sample weights in scorer objects. Metrics with sample weight support will automatically benefit from it. By Noel Dawe and Vlad Niculae.

• Added `newton-cg` and `lbfgs` solver support in `linear_model.LogisticRegression`. By Manoj Kumar.

• Add `selection="random"` parameter to implement stochastic coordinate descent for `linear_model.Lasso`, `linear_model.ElasticNet` and related. By Manoj Kumar.

• Add `sample_weight` parameter to `metrics.jaccard_similarity_score` and `metrics.log_loss`. By Jatin Shah.

• Support sparse multilabel indicator representation in `preprocessing.LabelBinarizer` and `multiclass.OneVsRestClassifier` (by Hamzeh Alsalhi with thanks to Rohit Sivaprasad), as well as evaluation metrics (by Joel Nothman).

• Add `sample_weight` parameter to `metrics.jaccard_similarity_score`. By Jatin Shah.

• Add support for multiclass in `metrics.hinge_loss`. Added `labels=None` as optional parameter. By Saurabh Jha.

• Add `sample_weight` parameter to `metrics.hinge_loss`. By Saurabh Jha.
• Add `multi_class="multinomial"` option in `linear_model.LogisticRegression` to implement a Logistic Regression solver that minimizes the cross-entropy or multinomial loss instead of the default One-vs-Rest setting. Supports `lbfgs` and `newton-cg` solvers. By Lars Buitinck and Manoj Kumar. Solver option `newton-cg` by Simon Wu.

• DictVectorizer can now perform `fit_transform` on an iterable in a single pass, when giving the option `sort=False`. By Dan Blanchard.

• GridSearchCV and RandomizedSearchCV can now be configured to work with estimators that may fail and raise errors on individual folds. This option is controlled by the `error_score` parameter. This does not affect errors raised on re-fit. By Michal Romaniuk.

• Add digits parameter to `metrics.classification_report` to allow report to show different precision of floating point numbers. By Ian Gilmore.

• Add a quantile prediction strategy to the `dummy.DummyRegressor`. By Aaron Staple.

• Add handle_unknown option to `preprocessing.OneHotEncoder` to handle unknown categorical features more gracefully during transform. By Manoj Kumar.

• Added support for sparse input data to decision trees and their ensembles. By Fares Hedyati and Arnaud Joly.

• Optimized `cluster.AffinityPropagation` by reducing the number of memory allocations of large temporary data-structures. By Antony Lee.

• Parellization of the computation of feature importances in random forest. By Olivier Grisel and Arnaud Joly.

• Add `n_iter_` attribute to estimators that accept a `max_iter` attribute in their constructor. By Manoj Kumar.

• Added decision function for `multiclass.OneVsOneClassifier`. By Raghav RV and Kyle Beauchamp.

• `neighbors.kneighbors_graph` and `radius_neighbors_graph` support non-Euclidean metrics. By Manoj Kumar

• Parameter `connectivity` in `cluster.AgglomerativeClustering` and family now accept callables that return a connectivity matrix. By Manoj Kumar.

• Sparse support for `paired_distances`. By Joel Nothman.

• `cluster.DBSCAN` now supports sparse input and sample weights and has been optimized: the inner loop has been rewritten in Cython and radius neighbors queries are now computed in batch. By Joel Nothman and Lars Buitinck.

• Add `class_weight` parameter to automatically weight samples by class frequency for `ensemble.RandomForestClassifier`, `tree.DecisionTreeClassifier`, `ensemble.ExtraTreesClassifier` and `tree.ExtraTreeClassifier`. By Trevor Stephens.

• `grid_search.RandomizedSearchCV` now does sampling without replacement if all parameters are given as lists. By Andreas Müller.

• Parallelized calculation of `pairwise_distances` is now supported for scipy metrics and custom callables. By Joel Nothman.

• Allow the fitting and scoring of all clustering algorithms in `pipeline.Pipeline`. By Andreas Müller.

• More robust seeding and improved error messages in `cluster.MeanShift` by Andreas Müller.

• Make the stopping criterion for `mixture.GMM`, `mixture.DPGMM` and `mixture.VBGMM` less dependent on the number of samples by thresholding the average log-likelihood change instead of its sum over all samples. By Hervé Bredin.

• The outcome of `manifold.spectral_embedding` was made deterministic by flipping the sign of eigenvectors. By Hasil Sharma.

• Numerical stability improvements for `preprocessing.StandardScaler` and `preprocessing.scale`. By Nicolas Goix

• `svm.SVC` fitted on sparse input now implements `decision_function`. By Rob Zinkov and Andreas Müller.

• `cross_validation.train_test_split` now preserves the input type, instead of converting to numpy arrays.

Documentation improvements

• Added example of using `FeatureUnion` for heterogeneous input. By Matt Terry

• Documentation on scorers was improved, to highlight the handling of loss functions. By Matt Pico.

• A discrepancy between liblinear output and scikit-learn’s wrappers is now noted. By Manoj Kumar.

• Improved documentation generation: examples referring to a class or function are now shown in a gallery on the class/function’s API reference page. By Joel Nothman.

• More explicit documentation of sample generators and of data transformation. By Joel Nothman.

• `sklearn.neighbors.BallTree` and `sklearn.neighbors.KDTree` used to point to empty pages stating that they are aliases of BinaryTree. This has been fixed to show the correct class docs. By Manoj Kumar.

• Added silhouette plots for analysis of KMeans clustering using `metrics.silhouette_samples` and `metrics.silhouette_score`. See Selecting the number of clusters with silhouette analysis on KMeans clustering

Bug fixes

• Metaestimators now support ducktyping for the presence of `decision_function`, `predict_proba` and other methods. This fixes behavior of `grid_search.GridSearchCV`, `grid_search.RandomizedSearchCV`, `pipeline.Pipeline`, `feature_selection.RFE`, `feature_selection.RFECV` when nested. By Joel Nothman

• The `scoring` attribute of grid-search and cross-validation methods is no longer ignored when a `grid_search.GridSearchCV` is given as a base estimator or the base estimator doesn’t have predict.

• The function `hierarchical.ward_tree` now returns the children in the same order for both the structured and unstructured versions. By Matteo Visconti di Oleggio Castello.

• `feature_selection.RFECV` now correctly handles cases when `step` is not equal to 1. By Nikolay Mayorov

• The `decomposition.PCA` now undoes whitening in its `inverse_transform`. Also, its `components_` now always have unit length. By Michael Eickenberg.

• Fix incomplete download of the dataset when `datasets.download_20newsgroups` is called. By Manoj Kumar.

• Various fixes to the Gaussian processes subpackage by Vincent Dubourg and Jan Hendrik Metzen.

• Calling `partial_fit` with `class_weight='auto'` throws an appropriate error message and suggests a work around. By Danny Sullivan.
• **RBFSampler** with gamma=g formerly approximated *rbf_kernel* with gamma=g/2.; the definition of gamma is now consistent, which may substantially change your results if you use a fixed value. (If you cross-validated over gamma, it probably doesn’t matter too much.) By Dougal Sutherland.

• Pipeline object delegate the classes_ attribute to the underlying estimator. It allows, for instance, to make bagging of a pipeline object. By Arnaud Joly

• neighbors.NearestCentroid now uses the median as the centroid when metric is set to manhattan. It was using the mean before. By Manoj Kumar

• Fix numerical stability issues in *linear_model.SGDClassifier* and *linear_model.SGDRegressor* by clipping large gradients and ensuring that weight decay rescaling is always positive (for large l2 regularization and large learning rate values). By Olivier Grisel

• When compute_full_tree is set to “auto”, the full tree is built when n_clusters is high and is early stopped when n_clusters is low, while the behavior should be vice-versa in *cluster.AgglomerativeClustering* (and friends). This has been fixed By Manoj Kumar

• Fix lazy centering of data in *linear_model.enet_path* and *linear_model.lasso_path*. It was centered around one. It has been changed to be centered around the origin. By Manoj Kumar

• Fix handling of precomputed affinity matrices in *cluster.AgglomerativeClustering* when using connectivity constraints. By Cathy Deng

• Correct partial_fit handling of class_prior for *sklearn.naive_bayes.MultinomialNB* and *sklearn.naive_bayes.BernoulliNB*. By Trevor Stephens.

• Fixed a crash in *metrics.precision_recall_fscore_support* when using unsorted labels in the multi-label setting. By Andreas Müller.

• Avoid skipping the first nearest neighbor in the methods radius_neighbors, kneighbors, kneighbors_graph and radius_neighbors_graph in *sklearn.neighbors.NearestNeighbors* and family, when the query data is not the same as fit data. By Manoj Kumar.

• Fix log-density calculation in the *mixture.GMM* with tied covariance. By Will Dawson

• Fixed a scaling error in *feature_selection.SelectFdr* where a factor n_features was missing. By Andrew Tulloch

• Fix zero division in *neighbors.KNeighborsRegressor* and related classes when using distance weighting and having identical data points. By Garret-R.

• Fixed round off errors with non positive-definite covariance matrices in GMM. By Alexis Mignon.

• Fixed a error in the computation of conditional probabilities in *naive_bayes.BernoulliNB*. By Hanna Wallach.

• Make the method radius_neighbors of *neighbors.NearestNeighbors* return the samples lying on the boundary for algorithm='brute'. By Yan Yi.

• Flip sign of dual_coef_ of *svm.SVC* to make it consistent with the documentation and decision_function. By Artem Sobolev.

• Fixed handling of ties in *isotonic.IsotonicRegression*. We now use the weighted average of targets (secondary method). By Andreas Müller and Michael Bommarito.
API changes summary

- ``GridSearchCV`` and `cross_val_score` and other meta-estimators don’t convert pandas DataFrames into arrays any more, allowing DataFrame specific operations in custom estimators.

- ``multiclass.fit_ovr, multiclass.predict_ovr, predict_proba_ovr, multiclass.fit_ovo, multiclass.predict_ovo, multiclass.fit_ecoc and multiclass.predict_ecoc`` are deprecated. Use the underlying estimators instead.

- Nearest neighbors estimators used to take arbitrary keyword arguments and pass these to their distance metric. This will no longer be supported in scikit-learn 0.18; use the `metric_params` argument instead.

- ``n_jobs`` parameter of the `fit` method shifted to the constructor of the `LinearRegression` class.

- The `predict_proba` method of ``multiclass.OneVsRestClassifier`` now returns two probabilities per sample in the multiclass case; this is consistent with other estimators and with the method’s documentation, but previous versions accidentally returned only the positive probability. Fixed by Will Lamond and Lars Buitinck.

- Change default value of `precompute` in `ElasticNet` and `Lasso` to False. Setting `precompute` to “auto” was found to be slower when `n_samples > n_features` since the computation of the Gram matrix is computationally expensive and outweighs the benefit of fitting the Gram for just one alpha. `precompute="auto"` is now deprecated and will be removed in 0.18 By Manoj Kumar.

- Expose `positive` option in `linear_model.enet_path` and `linear_model.enet_path` which constrains coefficients to be positive. By Manoj Kumar.

- Users should now supply an explicit `average` parameter to `sklearn.metrics.f1_score, sklearn.metrics.fbeta_score, sklearn.metrics.recall_score` and `sklearn.metrics.precision_score` when performing multiclass or multilabel (i.e. not binary) classification. By Joel Nothman.

- `scoring` parameter for cross validation now accepts `'f1_micro', 'f1_macro' or 'f1_weighted'`, `'f1'` is now for binary classification only. Similar changes apply to `precision' and 'recall'`. By Joel Nothman.

- The fit_intercept, normalize and return_models parameters in `linear_model.enet_path` and `linear_model.lasso_path` have been removed. They were deprecated since 0.14

- From now onwards, all estimators will uniformly raise `NotFittedError (utils.validation.NotFittedError)`, when any of the predict like methods are called before the model is fit. By Raghav RV.

- Input data validation was refactored for more consistent input validation. The `check_arrays` function was replaced by `check_array` and `check_X_y`. By Andreas Müller.

- Allow X=None in the methods `radius_neighbors, kneighbors, kneighbors_graph` and `radius_neighbors_graph` in `sklearn.neighbors.NearestNeighbors` and family. If set to None, then for every sample this avoids setting the sample itself as the first nearest neighbor. By Manoj Kumar.

- Add parameter `include_self` in `neighbors.kneighbors_graph` and neighbors. `radius_neighbors_graph` which has to be explicitly set by the user. If set to True, then the sample itself is considered as the first nearest neighbor.

- `thresh` parameter is deprecated in favor of new `tol` parameter in `GMM, DPGMM` and `VBGMM`. See `Enhancements section for details. By Hervé Bredin.`

- Estimators will treat input with `dtype object` as numeric when possible. By Andreas Müller

- Estimators now raise `ValueError` consistently when fitted on empty data (less than 1 sample or less than 1 feature for 2D input). By Olivier Grisel.
• `cluster.DBSCAN` now uses a deterministic initialization. The `random_state` parameter is deprecated. 
  
  By Erich Schubert.

Code Contributors


1.7.27 Version 0.15.2

September 4, 2014

Bug fixes

• Fixed handling of the `p` parameter of the Minkowski distance that was previously ignored in nearest neighbors models. By Nikolay Mayorov.
• Fixed duplicated alphas in `linear_model.LassoLars` with early stopping on 32 bit Python. By Olivier Grisel and Fabian Pedregosa.
• Fixed the build under Windows when scikit-learn is built with MSVC while NumPy is built with MinGW. By Olivier Grisel and Federico Vaggi.
• Fixed an array index overflow bug in the coordinate descent solver. By Gael Varoquaux.
• Better handling of numpy 1.9 deprecation warnings. By Gael Varoquaux.
• Removed unnecessary data copy in `cluster.KMeans`. By Gael Varoquaux.
• Explicitly close open files to avoid `ResourceWarning` under Python 3. By Calvin Giles.
• The transform of `discriminant_analysis.LinearDiscriminantAnalysis` now projects the input on the most discriminant directions. By Martin Billinger.

• Fixed potential overflow in `_tree.safe_realloc` by Lars Buitinck.


• `nose` is non-longer a runtime dependency to import `sklearn`, only for running the tests. By Joel Nothman.

• Many documentation and website fixes by Joel Nothman, Lars Buitinck Matt Pico, and others.

1.7.28 Version 0.15.1

August 1, 2014

Bug fixes

• Made `cross_validation.cross_val_score` use `cross_validationKFold` instead of `cross_validation.StratifiedKFold` on multi-output classification problems. By Nikolay Mayorov.

• Support unseen labels `preprocessing.LabelBinarizer` to restore the default behavior of 0.14.1 for backward compatibility. By Hamzeh Alsalhi.

• Fixed the `cluster.KMeans` stopping criterion that prevented early convergence detection. By Edward Raff and Gael Varoquaux.

• Fixed the behavior of `multiclass.OneVsOneClassifier` in case of ties at the per-class vote level by computing the correct per-class sum of prediction scores. By Andreas Müller.

• Made `cross_validation.cross_val_score` and `grid_search.GridSearchCV` accept Python lists as input data. This is especially useful for cross-validation and model selection of text processing pipelines. By Andreas Müller.

• Fixed data input checks of most estimators to accept input data that implements the NumPy `__array__` protocol. This is the case for `pandas.Series` and `pandas.DataFrame` in recent versions of pandas. By Gael Varoquaux.

• Fixed a regression for `linear_model.SGDClassifier` with `class_weight="auto"` on data with non-contiguous labels. By Olivier Grisel.

1.7.29 Version 0.15

July 15, 2014

Highlights

• Many speed and memory improvements all across the code

• Huge speed and memory improvements to random forests (and extra trees) that also benefit better from parallel computing.

• Incremental fit to `BernoulliRBM`

• Added `cluster.AgglomerativeClustering` for hierarchical agglomerative clustering with average linkage, complete linkage and ward strategies.

• Added `linear_model.RANSACRegressor` for robust regression models.
• Added dimensionality reduction with manifold.TSNE which can be used to visualize high-dimensional data.

Changelog

New features

• Added ensemble.BaggingClassifier and ensemble.BaggingRegressor meta-estimators for ensembling any kind of base estimator. See the Bagging section of the user guide for details and examples. By Gilles Louppe.


• Added linear_model.RANSACRegressor meta-estimator for the robust fitting of regression models. By Johannes Schönberger.

• Added cluster.AgglomerativeClustering for hierarchical agglomerative clustering with average linkage, complete linkage and ward strategies, by Nelle Varoquaux and Gael Varoquaux.

• Shorthand constructors pipeline.make_pipeline and pipeline.make_union were added by Lars Buitinck.

• Shuffle option for cross_validation.StratifiedKFold. By Jeffrey Blackburne.

• Incremental learning (partial_fit) for Gaussian Naive Bayes by Imran Haque.

• Added partial_fit to BernoulliRBM By Danny Sullivan.

• Added learning_curve utility to chart performance with respect to training size. See Plotting Learning Curves. By Alexander Fabisch.

• Add positive option in LassoCV and ElasticNetCV. By Brian Wignall and Alexandre Gramfort.

• Added linear_model.MultiTaskElasticNetCV and linear_model.MultiTaskLassoCV. By Manoj Kumar.

• Added manifold.TSNE. By Alexander Fabisch.

Enhancements


• Memory improvements of decision trees, by Arnaud Joly.

• Decision trees can now be built in best-first manner by using max_leaf_nodes as the stopping criteria. Refactored the tree code to use either a stack or a priority queue for tree building. By Peter Prettenhofer and Gilles Louppe.

• Decision trees can now be fitted on fortran- and c-style arrays, and non-continuous arrays without the need to make a copy. If the input array has a different dtype than np.float32, a fortran- style copy will be made since fortran-style memory layout has speed advantages. By Peter Prettenhofer and Gilles Louppe.

• Speed improvement of regression trees by optimizing the the computation of the mean square error criterion. This lead to speed improvement of the tree, forest and gradient boosting tree modules. By Arnaud Joly

• The img_to_graph and grid_to_graph functions in sklearn.feature_extraction.image now return np.ndarray instead of np.matrix when return_as=np.ndarray. See the Notes section for more information on compatibility.
• Changed the internal storage of decision trees to use a struct array. This fixed some small bugs, while improving code and providing a small speed gain. By Joel Nothman.

• Reduce memory usage and overhead when fitting and predicting with forests of randomized trees in parallel with n_jobs != 1 by leveraging new threading backend of joblib 0.8 and releasing the GIL in the tree fitting Cython code. By Olivier Grisel and Gilles Louppe.

• Speed improvement of the sklearn.ensemble.gradient_boosting module. By Gilles Louppe and Peter Prettenhofer.

• Various enhancements to the sklearn.ensemble.gradient_boosting module: a warm_start argument to fit additional trees, a max_leaf_nodes argument to fit GBM style trees, a monitor fit argument to inspect the estimator during training, and refactoring of the verbose code. By Peter Prettenhofer.

• Faster sklearn.ensemble.ExtraTrees by caching feature values. By Arnaud Joly.

• Faster depth-based tree building algorithm such as decision tree, random forest, extra trees or gradient tree boosting (with depth based growing strategy) by avoiding trying to split on found constant features in the sample subset. By Arnaud Joly.

• Add min_weight_fraction_leaf pre-pruning parameter to tree-based methods: the minimum weighted fraction of the input samples required to be at a leaf node. By Noel Dawe.

• Added metrics.pairwise_distances_argmin_min, by Philippe Gervais.

• Added predict method to cluster.AffinityPropagation and cluster.MeanShift, by Mathieu Blondel.

• Vector and matrix multiplications have been optimised throughout the library by Denis Engemann, and Alexandre Gramfort. In particular, they should take less memory with older NumPy versions (prior to 1.7.2).

• Precision-recall and ROC examples now use train_test_split, and have more explanation of why these metrics are useful. By Kyle Kastner

• The training algorithm for decomposition.NMF is faster for sparse matrices and has much lower memory complexity, meaning it will scale up gracefully to large datasets. By Lars Buitinck.

• Added svd_method option with default value to "randomized" to decomposition.FactorAnalysis to save memory and significantly speedup computation by Denis Engemann, and Alexandre Gramfort.

• Changed cross_validation.StratifiedKFold to try and preserve as much of the original ordering of samples as possible so as not to hide overfitting on datasets with a non-negligible level of samples dependency. By Daniel Nouri and Olivier Grisel.

• Add multi-output support to gaussian_process.GaussianProcess by John Novak.

• Support for precomputed distance matrices in nearest neighbor estimators by Robert Layton and Joel Nothman.

• Norm computations optimized for NumPy 1.6 and later versions by Lars Buitinck. In particular, the k-means algorithm no longer needs a temporary data structure the size of its input.

• dummy.DummyClassifier can now be used to predict a constant output value. By Manoj Kumar.

• dummy.DummyRegressor has now a strategy parameter which allows to predict the mean, the median of the training set or a constant output value. By Maheshakya Wijewardena.

• Multi-label classification output in multilabel indicator format is now supported by metrics. roc_auc_score and metrics.average_precision_score by Arnaud Joly.

• Significant performance improvements (more than 100x speedup for large problems) in isotonic. IsotonicRegression by Andrew Tulloch.

• Speed and memory usage improvements to the SGD algorithm for linear models: it now uses threads, not separate processes, when n_jobs>1. By Lars Buitinck.
• Grid search and cross validation allow NaNs in the input arrays so that preprocessors such as `preprocessing.Imputer` can be trained within the cross validation loop, avoiding potentially skewed results.

• Ridge regression can now deal with sample weights in feature space (only sample space until then). By Michael Eickenberg. Both solutions are provided by the Cholesky solver.

• Several classification and regression metrics now support weighted samples with the new `sample_weight` argument: `metrics.accuracy_score`, `metrics.zero_one_loss`, `metrics.precision_score`, `metrics.average_precision_score`, `metrics.f1_score`, `metrics.fbeta_score`, `metrics.recall_score`, `metrics.roc_auc_score`, `metrics.explained_variance_score`, `metrics.mean_squared_error`, `metrics.mean_absolute_error`, `metrics.r2_score`. By Noel Dawe.

• Speed up of the sample generator `datasets.make_multilabel_classification`. By Joel Nothman.

Documentation improvements

• The `Working With Text Data` tutorial has now been worked in to the main documentation’s tutorial section. Includes exercises and skeletons for tutorial presentation. Original tutorial created by several authors including Olivier Grisel, Lars Buitinck and many others. Tutorial integration into the scikit-learn documentation by Jaques Grobler

• Added `Computational Performance` documentation. Discussion and examples of prediction latency / throughput and different factors that have influence over speed. Additional tips for building faster models and choosing a relevant compromise between speed and predictive power. By Eustache Diemert.

Bug fixes

• Fixed bug in `decomposition.MiniBatchDictionaryLearning.partial_fit` was not working properly.

• Fixed bug in `linear_model.stochastic_gradient: ll_ratio` was used as (1.0 - ll_ratio).

• Fixed bug in `multiclass.OneVsOneClassifier with string labels`

• Fixed a bug in `LassoCV and ElasticNetCV`: they would not pre-compute the Gram matrix with `precompute=True or precompute="auto" and n_samples > n_features`. By Manoj Kumar.

• Fixed incorrect estimation of the degrees of freedom in `feature_selection.f_regression` when variables are not centered. By Virgile Fritsch.

• Fixed a race condition in parallel processing with `pre_dispatch != "all"` (for instance, in `cross_val_score`). By Olivier Grisel.

• Raise error in `cluster.FeatureAgglomeration` and `cluster.WardAgglomeration` when no samples are given, rather than returning meaningless clustering.

• Fixed bug in `gradient_boosting.GradientBoostingRegressor with loss='huber': gamma might have not been initialized.`

• Fixed feature importances as computed with a forest of randomized trees when fit with `sample_weight != None and/or with bootstrap=True`. By Gilles Louppe.
API changes summary

- `sklearn.hmm` is deprecated. Its removal is planned for the 0.17 release.
- Use of `covariance.EllipticEnvelope` has now been removed after deprecation. Please use `covariance.EllipticEnvelope` instead.
- `cluster.Ward` is deprecated. Use `cluster.AgglomerativeClustering` instead.
- `cluster.WardClustering` is deprecated. Use `cluster.AgglomerativeClustering` instead.
- `cross_validation.Bootstrap` is deprecated. `cross_validation.KFold` or `cross_validation.ShuffleSplit` are recommended instead.
- Direct support for the sequence of sequences (or list of lists) multilabel format is deprecated. To convert to and from the supported binary indicator matrix format, use `MultiLabelBinarizer`. By Joel Nothman.
- Add score method to `PCA` following the model of probabilistic PCA and deprecate `ProbabilisticPCA` model whose score implementation is not correct. The computation now also exploits the matrix inversion lemma for faster computation. By Alexandre Gramfort.
- The score method of `FactorAnalysis` now returns the average log-likelihood of the samples. Use `score_samples` to get log-likelihood of each sample. By Alexandre Gramfort.
- Generating boolean masks (the setting `indices=False`) from cross-validation generators is deprecated. Support for masks will be removed in 0.17. The generators have produced arrays of indices by default since 0.10. By Joel Nothman.
- 1-d arrays containing strings with `dtype=object` (as used in Pandas) are now considered valid classification targets. This fixes a regression from version 0.13 in some classifiers. By Joel Nothman.
- Fix wrong `explained_variance_ratio_` attribute in `RandomizedPCA`. By Alexandre Gramfort.
- Fit alphas for each `l1_ratio` instead of `mean_l1_ratio` in `linear_model.ElasticNetCV` and `linear_model.LassoCV`. This changes the shape of `alphas_` from `(n_alphas,)` to `(n_l1_ratio, n_alphas)` if the `l1_ratio` provided is a 1-D array like object of length greater than one. By Manoj Kumar.
- Fix `linear_model.ElasticNetCV` and `linear_model.LassoCV` when fitting intercept and input data is sparse. The automatic grid of alphas was not computed correctly and the scaling with normalize was wrong. By Manoj Kumar.
- Fix wrong maximal number of features drawn (max_features) at each split for decision trees, random forests and gradient tree boosting. Previously, the count for the number of drawn features started only after one non constant features in the split. This bug fix will affect computational and generalization performance of those algorithms in the presence of constant features. To get back previous generalization performance, you should modify the value of `max_features`. By Arnaud Joly.
- Fix wrong maximal number of features drawn (max_features) at each split for `ensemble.ExtraTreesClassifier` and `ensemble.ExtraTreesRegressor`. Previously, only non constant features in the split was counted as drawn. Now constant features are counted as drawn. Furthermore at least one feature must be non constant in order to make a valid split. This bug fix will affect computational and generalization performance of extra trees in the presence of constant features. To get back previous generalization performance, you should modify the value of `max_features`. By Arnaud Joly.
- Fix `utils.compute_class_weight` when `class_weight="auto"`. Previously it was broken for input of non-integer `dtype` and the weighted array that was returned was wrong. By Manoj Kumar.
People

List of contributors for release 0.15 by number of commits.

- 312 Olivier Grisel
- 275 Lars Buitinck
- 221 Gael Varoquaux
- 148 Arnaud Joly
- 134 Johannes Schönberger
- 119 Gilles Louppe
- 113 Joel Nothman
- 111 Alexandre Gramfort
- 95 Jaques Grobler
- 89 Denis Engemann
- 83 Peter Prettenhofer
- 83 Alexander Fabisch
- 62 Mathieu Blondel
- 60 Eustache Diemert
- 60 Nelle Varoquaux
- 49 Michael Bommarito
- 45 Manoj-Kumar-S
- 28 Kyle Kastner
- 26 Andreas Mueller
- 22 Noel Dawe
- 21 Maheshakya Wijewardena
- 21 Brooke Osborn
- 21 Hamzeh Alsalhi
- 21 Jake VanderPlas
- 21 Philippe Gervais
- 19 Bala Subrahmanym Varanasi
- 12 Ronald Phlypo
- 10 Mikhail Korobov
- 8 Thomas Unterthiner
- 8 Jeffrey Blackburne
- 8 eltermann
- 8 bwignall
- 7 Ankit Agrawal
- 7 CJ Carey
• 6 Daniel Nouri
• 6 Chen Liu
• 6 Michael Eickenberg
• 6 ugurthemaster
• 5 Aaron Schumacher
• 5 Baptiste Lagarde
• 5 Rajat Khanduja
• 5 Robert McGibbon
• 5 Sergio Pascual
• 4 Alexis Metaireau
• 4 Ignacio Rossi
• 4 Virgile Fritsch
• 4 Sebastian Säger
• 4 Ilambharathi Kanniah
• 4 sdenton4
• 4 Robert Layton
• 4 Alyssa
• 4 Amos Waterland
• 3 Andrew Tulloch
• 3 murad
• 3 Steven Maude
• 3 Karol Pysniak
• 3 Jacques Kvam
• 3 cgohlke
• 3 cjlin
• 3 Michael Becker
• 3 hamzeh
• 3 Eric Jacobsen
• 3 john collins
• 3 kaushik94
• 3 Erwin Marsi
• 2 csytracy
• 2 LK
• 2 Vlad Niculae
• 2 Laurent Dierer
• 2 Erik Shilts
1.7. Release History
• Missing values with sparse and dense matrices can be imputed with the transformer `preprocessing.Imputer` by Nicolas Trésegnie.

• The core implementation of decisions trees has been rewritten from scratch, allowing for faster tree induction and lower memory consumption in all tree-based estimators. By Gilles Louppe.

• Added `ensemble.AdaBoostClassifier` and `ensemble.AdaBoostRegressor`, by Noel Dawe and Gilles Louppe. See the `AdaBoost` section of the user guide for details and examples.

• Added `grid_search.RandomizedSearchCV` and `grid_search.ParameterSampler` for randomized hyperparameter optimization. By Andreas Müller.

• Added biclustering algorithms (sklearn.cluster.bicluster.SpectralCoclustering and sklearn.cluster.bicluster.SpectralBiclustering), data generation methods (sklearn.datasets.make_biclusters and sklearn.datasets.make_checkerboard), and scoring metrics (sklearn.metrics.consensus_score). By Kemal Eren.

• Added Restricted Boltzmann Machines (`neural_network.BernoulliRBM`), By Yann Dauphin.

1.7.30 Version 0.14

August 7, 2013

Changelog

- Missing values with sparse and dense matrices can be imputed with the transformer `preprocessing.Imputer` by Nicolas Trésegnie.
- The core implementation of decisions trees has been rewritten from scratch, allowing for faster tree induction and lower memory consumption in all tree-based estimators. By Gilles Louppe.
- Added `ensemble.AdaBoostClassifier` and `ensemble.AdaBoostRegressor`, by Noel Dawe and Gilles Louppe. See the `AdaBoost` section of the user guide for details and examples.
- Added biclustering algorithms (sklearn.cluster.bicluster.SpectralCoclustering and sklearn.cluster.bicluster.SpectralBiclustering), data generation methods (sklearn.datasets.make_biclusters and sklearn.datasets.make_checkerboard), and scoring metrics (sklearn.metrics.consensus_score). By Kemal Eren.
- Added Restricted Boltzmann Machines (`neural_network.BernoulliRBM`), By Yann Dauphin.
• Python 3 support by Justin Vincent, Lars Buitinck, Subhodeep Moitra and Olivier Grisel. All tests now pass under Python 3.3.

• Ability to pass one penalty (alpha value) per target in `linear_model.Ridge`, by @eickenberg and Mathieu Blondel.

• Fixed `sklearn.linear_model.stochastic_gradient.py` L2 regularization issue (minor practical significance). By Norbert Crombach and Mathieu Blondel.

• Added an interactive version of Andreas Müller’s Machine Learning Cheat Sheet (for scikit-learn) to the documentation. See Choosing the right estimator. By Jaques Grobler.

• `grid_search.GridSearchCV` and `cross_validation.cross_val_score` now support the use of advanced scoring function such as area under the ROC curve and f-beta scores. See The scoring parameter: defining model evaluation rules for details. By Andreas Müller and Lars Buitinck. Passing a function from `sklearn.metrics` as `score_func` is deprecated.

• Multi-label classification output is now supported by `metrics.accuracy_score`, `metrics.zero_one_loss`, `metrics.f1_score`, `metrics.fbeta_score`, `metrics.classification_report`, `metrics.precision_score` and `metrics.recall_score` by Arnaud Joly.

• Two new metrics `metrics.hamming_loss` and `metrics.jaccard_similarity_score` are added with multi-label support by Arnaud Joly.

• Speed and memory usage improvements in `feature_extraction.text.CountVectorizer` and `feature_extraction.text.TfidfVectorizer`, by Jochen Wersdörfer and Roman Sinayev.

• The `min_df` parameter in `feature_extraction.text.CountVectorizer` and `feature_extraction.text.TfidfVectorizer`, which used to be 2, has been reset to 1 to avoid unpleasant surprises (empty vocabularies) for novice users who try it out on tiny document collections. A value of at least 2 is still recommended for practical use.

• `svm.LinearSVC`, `linear_model.SGDClassifier` and `linear_model.SGDRegressor` now have a `sparsify` method that converts their `coef_` into a sparse matrix, meaning stored models trained using these estimators can be made much more compact.

• `linear_model.SGDClassifier` now produces multiclass probability estimates when trained under log loss or modified Huber loss.

• Hyperlinks to documentation in example code on the website by Martin Luessi.

• Fixed bug in `preprocessing.MinMaxScaler` causing incorrect scaling of the features for non-default `feature_range` settings. By Andreas Müller.

• `max_features` in `tree.DecisionTreeClassifier`, `tree.DecisionTreeRegressor` and all derived ensemble estimators now supports percentage values. By Gilles Louppe.

• Performance improvements in `isotonic.IsotonicRegression` by Nelle Varoquaux.

• `metrics.accuracy_score` has an option normalize to return the fraction or the number of correctly classified sample by Arnaud Joly.

• Added `metrics.log_loss` that computes log loss, aka cross-entropy loss. By Jochen Wersdörfer and Lars Buitinck.

• A bug that caused `ensemble.AdaBoostClassifier`’s to output incorrect probabilities has been fixed.

• Feature selectors now share a mixin providing consistent `transform`, `inverse_transform` and `get_support` methods. By Joel Nothman.

• A fitted `grid_search.GridSearchCV` or `grid_search.RandomizedSearchCV` can now generally be pickled. By Joel Nothman.
• Refactored and vectorized implementation of `metrics.roc_curve` and `metrics.precision_recall_curve`. By Joel Nothman.

• The new estimator `sklearn.decomposition.TruncatedSVD` performs dimensionality reduction using SVD on sparse matrices, and can be used for latent semantic analysis (LSA). By Lars Buitinck.

• Added self-contained example of out-of-core learning on text data *Out-of-core classification of text documents*. By Eustache Diemert.

• The default number of components for `sklearn.decomposition.RandomizedPCA` is now correctly documented to be `n_features`. This was the default behavior, so programs using it will continue to work as they did.

• `sklearn.cluster.KMeans` now fits several orders of magnitude faster on sparse data (the speedup depends on the sparsity). By Lars Buitinck.

• Reduce memory footprint of FastICA by Denis Engemann and Alexandre Gramfort.

• Verbose output in `sklearn.ensemble.gradient_boosting` now uses a column format and prints progress in decreasing frequency. It also shows the remaining time. By Peter Prettenhofer.

• `sklearn.ensemble.gradient_boosting` provides out-of-bag improvement `oob_improvement_` rather than the OOB score for model selection. An example that shows how to use OOB estimates to select the number of trees was added. By Peter Prettenhofer.

• Most metrics now support string labels for multiclass classification by Arnaud Joly and Lars Buitinck.

• New OrthogonalMatchingPursuitCV class by Alexandre Gramfort and Vlad Niculae.

• Fixed a bug in `sklearn.covariance.GraphLassoCV`: the ‘alphas’ parameter now works as expected when given a list of values. By Philippe Gervais.

• Fixed an important bug in `sklearn.covariance.GraphLassoCV` that prevented all folds provided by a CV object to be used (only the first 3 were used). When providing a CV object, execution time may thus increase significantly compared to the previous version (bug results are correct now). By Philippe Gervais.

• `cross_validation.cross_val_score` and the `grid_search` module is now tested with multi-output data by Arnaud Joly.

• `datasets.make_multilabel_classification` can now return the output in label indicator multi-label format by Arnaud Joly.


• Random state in LibSVM-based estimators (`svm.SVC`, `NuSVC`, `OneClassSVM`, `svm.SVR`, `svm.NuSVR`) can now be controlled. This is useful to ensure consistency in the probability estimates for the classifiers trained with `probability=True`. By Vlad Niculae.

• Out-of-core learning support for discrete naive Bayes classifiers `sklearn.naive_bayes.MultinomialNB` and `sklearn.naive_bayes.BernoulliNB` by adding the `partial_fit` method by Olivier Grisel.

• New website design and navigation by Gilles Louppe, Nelle Varoquaux, Vincent Michel and Andreas Müller.

• Improved documentation on *multi-class, multi-label and multi-output classification* by Yannick Schwartz and Arnaud Joly.

• Better input and error handling in the `metrics` module by Arnaud Joly and Joel Nothman.

• Speed optimization of the `hmm` module by Mikhail Korobov

• Significant speed improvements for `sklearn.cluster.DBSCAN` by cleverless
API changes summary

- The `auc_score` was renamed `roc_auc_score`.
- Testing scikit-learn with `sklearn.test()` is deprecated. Use `nosetests sklearn` from the command line.
- Feature importances in `tree.DecisionTreeClassifier`, `tree.DecisionTreeRegressor` and all derived ensemble estimators are now computed on the fly when accessing the `feature_importances_` attribute. Setting `compute_importances=True` is no longer required. By Gilles Louppe.
- `linear_model.lasso_path` and `linear_model.enet_path` can return its results in the same format as that of `linear_model.lars_path`. This is done by setting the `return_models` parameter to `False`. By Jaques Grobler and Alexandre Gramfort.
- `grid_search.IterGrid` was renamed to `grid_search.ParameterGrid`.
- Fixed bug in `KFold` causing imperfect class balance in some cases. By Alexandre Gramfort and Tadej Janež.
- `sklearn.neighbors.BallTree` has been refactored, and a `sklearn.neighbors.KDTree` has been added which shares the same interface. The Ball Tree now works with a wide variety of distance metrics. Both classes have many new methods, including single-tree and dual-tree queries, breadth-first and depth-first searching, and more advanced queries such as kernel density estimation and 2-point correlation functions. By Jake Vanderplas.
- Support for `scipy.spatial.cKDTree` within neighbors queries has been removed, and the functionality replaced with the new `KDTree` class.
- `sklearn.neighbors.KernelDensity` has been added, which performs efficient kernel density estimation with a variety of kernels.
- `sklearn.decomposition.KernelPCA` now always returns output with `n_components` components, unless the new parameter `remove_zero_eig` is set to `True`. This new behavior is consistent with the way kernel PCA was always documented; previously, the removal of components with zero eigenvalues was tacitly performed on all data.
- `gcv_mode="auto"` no longer tries to perform SVD on a densified sparse matrix in `sklearn.linear_model.RidgeCV`.
- Sparse matrix support in `sklearn.decomposition.RandomizedPCA` is now deprecated in favor of the new `TruncatedSVD`.
- `cross_validation.KFold` and `cross_validation.StratifiedKFold` now enforce `n_folds >= 2` otherwise a `ValueError` is raised. By Olivier Grisel.
- `datasets.load_files`'s `charset` and `charset_errors` parameters were renamed `encoding` and `decode_errors`.
- Attribute `oob_score_` in `sklearn.ensemble.GradientBoostingRegressor` and `sklearn.ensemble.GradientBoostingClassifier` is deprecated and has been replaced by `oob_improvement_`.
- Attributes in `OrthogonalMatchingPursuit` have been deprecated (copy_X, Gram, ...) and `precompute_gram` renamed `precompute` for consistency. See #2224.
- `sklearn.preprocessing.StandardScaler` now converts integer input to float, and raises a warning. Previously it rounded for dense integer input.
- `sklearn.multiclass.OneVsRestClassifier` now has a `decision_function` method. This will return the distance of each sample from the decision boundary for each class, as long as the underlying estimators implement the `decision_function` method. By Kyle Kastner.
- Better input validation, warning on unexpected shapes for y.
People

List of contributors for release 0.14 by number of commits.

- 277 Gilles Louppe
- 245 Lars Buitinck
- 187 Andreas Mueller
- 124 Arnaud Joly
- 112 Jaques Grobler
- 109 Gael Varoquaux
- 107 Olivier Grisel
- 102 Noel Dawe
- 99 Kemal Eren
- 79 Joel Nothman
- 75 Jake VanderPlas
- 73 Nelle Varoquaux
- 71 Vlad Niculae
- 65 Peter Prettenhofer
- 64 Alexandre Gramfort
- 54 Mathieu Blondel
- 38 Nicolas Trésegnie
- 35 eustache
- 27 Denis Engemann
- 25 Yann N. Dauphin
- 19 Justin Vincent
- 17 Robert Layton
- 15 Doug Coleman
- 14 Michael Eickenberg
- 13 Robert Marchman
- 11 Fabian Pedregosa
- 11 Philippe Gervais
- 10 Jim Holmström
- 10 Tadej Janež
- 10 syhw
- 9 Mikhail Korobov
- 9 Steven De Gryze
- 8 sergeyf
- 7 Ben Root
• 7 Hrishikesh Huilgolkar
• 6 Kyle Kastner
• 6 Martin Luessi
• 6 Rob Speer
• 5 Federico Vaggi
• 5 Raul Garreta
• 5 Rob Zinkov
• 4 Ken Geis
• 3 A. Flaxman
• 3 Denton Cockburn
• 3 Dougal Sutherland
• 3 Ian Ozsvárd
• 3 Johannes Schönberger
• 3 Robert McGibbon
• 3 Roman Sinayev
• 3 Szabo Roland
• 2 Diego Molla
• 2 Imran Haque
• 2 Jochen Wersdörfer
• 2 Sergey Karayev
• 2 Yannick Schwartz
• 2 jamestwebber
• 1 Abhijeet Kolhe
• 1 Alexander Fabisch
• 1 Bastiaan van den Berg
• 1 Benjamin Peterson
• 1 Daniel Velkov
• 1 Fazlul Shahriar
• 1 Felix Brockherde
• 1 Félix-Antoine Fortin
• 1 Harikrishnan S
• 1 Jack Hale
• 1 JakeMick
• 1 James McDermott
• 1 John Benediktsson
• 1 John Zwinck
1.7.31 Version 0.13.1

February 23, 2013

The 0.13.1 release only fixes some bugs and does not add any new functionality.

Changelog

• Fixed a testing error caused by the function `cross_validation.train_test_split` being interpreted as a test by Yaroslav Halchenko.
• Fixed a bug in the reassignment of small clusters in the `cluster.MiniBatchKMeans` by Gael Varoquaux.
• Fixed default value of `gamma` in `decomposition.KernelPCA` by Lars Buitinck.
• Updated `joblib` to 0.7.0d by Gael Varoquaux.
• Fixed scaling of the deviance in `ensemble.GradientBoostingClassifier` by Peter Prettenhofer.
• Better tie-breaking in `multiclass.OneVsOneClassifier` by Andreas Müller.
• Other small improvements to tests and documentation.
People

List of contributors for release 0.13.1 by number of commits.

- 16 Lars Buitinck
- 12 Andreas Müller
- 8 Gael Varoquaux
- 5 Robert Marchman
- 3 Peter Prettenhofer
- 2 Hrishikesh Huilgolkar
- 1 Bastiaan van den Berg
- 1 Diego Molla
- 1 Gilles Louppe
- 1 Mathieu Blondel
- 1 Nelle Varoquaux
- 1 Rafael Cunha de Almeida
- 1 Rolando Espinoza La fuente
- 1 Vlad Niculae
- 1 Yaroslav Halchenko

1.7.32 Version 0.13

January 21, 2013

New Estimator Classes


- `decomposition.FactorAnalysis`, a transformer implementing the classical factor analysis, by Christian Osendorfer and Alexandre Gramfort. See Factor Analysis in the user guide.

- `feature_extraction.FeatureHasher`, a transformer implementing the “hashing trick” for fast, low-memory feature extraction from string fields by Lars Buitinck and feature_extraction.text. HashingVectorizer for text documents by Olivier Grisel See Feature hashing and Vectorizing a large text corpus with the hashing trick for the documentation and sample usage.

- `pipeline.FeatureUnion`, a transformer that concatenates results of several other transformers by Andreas Müller. See FeatureUnion: composite feature spaces in the user guide.

- `random_projection.GaussianRandomProjection`, `random_projection.SparseRandomProjection` and the function `random_projection.johnson_lindenstrauss_min_dim`. The first two are transformers implementing Gaussian and sparse random projection matrix by Olivier Grisel and Arnaud Joly. See Random Projection in the user guide.

• `preprocessing.OneHotEncoder`, a transformer that computes binary encodings of categorical features by Andreas Müller. See Encoding categorical features in the user guide.


• `ensemble.RandomTreesEmbedding`, a transformer for creating high-dimensional sparse representations using ensembles of totally random trees by Andreas Müller. See Totally Random Trees Embedding in the user guide.

• `manifold.SpectralEmbedding` and function `manifold.spectral_embedding`, implementing the “laplacian eigenmaps” transformation for non-linear dimensionality reduction by Wei Li. See Spectral Embedding in the user guide.

• `isotonic.IsotonicRegression` by Fabian Pedregosa, Alexandre Gramfort and Nelle Varoquaux.

**Changelog**

• `metrics.zero_one_loss` (formerly `metrics.zero_one`) now has option for normalized output that reports the fraction of misclassifications, rather than the raw number of misclassifications. By Kyle Beauchamp.

• `tree.DecisionTreeClassifier` and all derived ensemble models now support sample weighting, by Noel Dawe and Gilles Louppe.

• Speedup improvement when using bootstrap samples in forests of randomized trees, by Peter Prettenhofer and Gilles Louppe.

• Partial dependence plots for Gradient Tree Boosting in `ensemble.partial_dependence.partial_dependence` by Peter Prettenhofer. See Partial Dependence and Individual Conditional Expectation Plots for an example.

• The table of contents on the website has now been made expandable by Jaques Grobler.

• `feature_selection.SelectPercentile` now breaks ties deterministically instead of returning all equally ranked features.

• `feature_selection.SelectKBest` and `feature_selection.SelectPercentile` are more numerically stable since they use scores, rather than p-values, to rank results. This means that they might sometimes select different features than they did previously.

• Ridge regression and ridge classification fitting with `sparse_cg` solver no longer has quadratic memory complexity, by Lars Buitinck and Fabian Pedregosa.

• Ridge regression and ridge classification now support a new fast solver called `lsqr`, by Mathieu Blondel.

• Speed up of `metrics.precision_recall_curve` by Conrad Lee.

• Added support for reading/writing svmlight files with pairwise preference attribute (qid in svmlight file format) in `datasets.dump_svmlight_file` and `datasets.load_svmlight_file` by Fabian Pedregosa.

• Faster and more robust `metrics.confusion_matrix` and Clustering performance evaluation by Wei Li.

• `cross_validation.cross_val_score` now works with precomputed kernels and affinity matrices, by Andreas Müller.

• LARS algorithm made more numerically stable with heuristics to drop regressors too correlated as well as to stop the path when numerical noise becomes predominant, by Gael Varoquaux.

• Faster implementation of `metrics.precision_recall_curve` by Conrad Lee.

• New kernel `metrics.chi2_kernel` by Andreas Müller, often used in computer vision applications.
• Fix of longstanding bug in `naive_bayes.BernoulliNB` fixed by Shaun Jackman.

• Implemented `predict_proba` in `multiclass.OneVsRestClassifier`, by Andrew Winterman.

• Improve consistency in gradient boosting: estimators `ensemble.GradientBoostingRegressor` and `ensemble.GradientBoostingClassifier` use the estimator `tree.DecisionTreeRegressor` instead of the `tree._tree.Tree` data structure by Arnaud Joly.

• Fixed a floating point exception in the `decision trees` module, by Seberg.

• Fix `metrics.roc_curve` fails when `y_true` has only one class by Wei Li.

• Add the `metrics.mean_absolute_error` function which computes the mean absolute error. The `metrics.mean_squared_error`, `metrics.mean_absolute_error` and `metrics.r2_score` metrics support multioutput by Arnaud Joly.

• Fixed `class_weight` support in `svm.LinearSVC` and `linear_model.LogisticRegression` by Andreas Müller. The meaning of `class_weight` was reversed as erroneously higher weight meant less positives of a given class in earlier releases.

• Improve narrative documentation and consistency in `sklearn.metrics` for regression and classification metrics by Arnaud Joly.

• Fixed a bug in `sklearn.svm.SVC` when using csr-matrices with unsorted indices by Xinfan Meng and Andreas Müller.

• MiniBatchKMeans: Add random reassignment of cluster centers with little observations attached to them, by Gael Varoquaux.

**API changes summary**

• Renamed all occurrences of `n_atoms` to `n_components` for consistency. This applies to `decomposition.DictionaryLearning`, `decomposition.MiniBatchDictionaryLearning`, `decomposition.dict_learning`, `decomposition.dict_learning_online`.

• Renamed all occurrences of `max_iters` to `max_iter` for consistency. This applies to `semi_supervised.LabelPropagation` and `semi_supervised.label_propagation.LabelSpreading`.

• Renamed all occurrences of `learn_rate` to `learning_rate` for consistency in `ensemble.BaseGradientBoosting` and `ensemble.GradientBoostingRegressor`.

• The module `sklearn.linear_model.sparse` is gone. Sparse matrix support was already integrated into the “regular” linear models.

• `sklearn.metrics.mean_square_error`, which incorrectly returned the accumulated error, was removed. Use `mean_squared_error` instead.

• Passing `class_weight` parameters to `fit` methods is no longer supported. Pass them to estimator constructors instead.

• GMMs no longer have `decode` and `rvs` methods. Use the `score`, `predict` or `sample` methods instead.

• The `solver` fit option in Ridge regression and classification is now deprecated and will be removed in v0.14. Use the constructor option instead.

• `feature_extraction.text.DictVectorizer` now returns sparse matrices in the CSR format, instead of COO.

• Renamed `k` in `cross_validation.KFold` and `cross_validation.StratifiedKFold` to `n_folds`, renamed `n_bootstraps` to `n_iter` in `cross_validation.Bootstrap`. 

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Renamed all occurrences of `n_iterations` to `n_iter` for consistency. This applies to `cross_validation.ShuffleSplit`, `cross_validation.StratifiedShuffleSplit`, `utils.randomized_range_finder` and `utils.randomized_svd`.

Replaced `rho` in `linear_model.ElasticNet` and `linear_model.SGDClassifier` by `l1_ratio`. The `rho` parameter had different meanings; `l1_ratio` was introduced to avoid confusion. It has the same meaning as previously `rho` in `linear_model.ElasticNet` and `(1-rho)` in `linear_model.SGDClassifier`.

`linear_model.LassoLars` and `linear_model.Lars` now store a list of paths in the case of multiple targets, rather than an array of paths.

The attribute `gmm` of `hmm.GMMHMM` was renamed to `gmm_` to adhere more strictly with the API.

`cluster.spectral_embedding` was moved to `manifold.spectral_embedding`.

Renamed `eig_tol` in `manifold.spectral_embedding`, `cluster.SpectralClustering` to `eigen_tol`, renamed `mode` to `eigen_solver`.

Renamed `mode` in `manifold.spectral_embedding` and `cluster.SpectralClustering` to `eigen_solver`.

`classes_` and `n_classes_` attributes of `tree.DecisionTreeClassifier` and all derived ensemble models are now flat in case of single output problems and nested in case of multi-output problems.


`svm.SVC` and `svm.NuSVC` now provide a `classes_` attribute and support arbitrary dtypes for labels `y`. Also, the dtype returned by `predict` now reflects the dtype of `y` during `fit` (used to be np.float).

Changed default `test_size` in `cross_validation.train_test_split` to `None`, added possibility to infer `test_size` from `train_size` in `cross_validation.ShuffleSplit` and `cross_validation.StratifiedShuffleSplit`.

Renamed function `sklearn.metrics.zero_one` to `sklearn.metrics.zero_one_loss`. Be aware that the default behavior in `sklearn.metrics.zero_one_loss` is different from `sklearn.metrics.zero_one`: normalize=False is changed to normalize=True.

Renamed function `metrics.zero_one_score` to `metrics.accuracy_score`.

`datasets.make_circles` now has the same number of inner and outer points.

In the Naive Bayes classifiers, the `class_prior` parameter was moved from `fit` to `__init__`.

People

List of contributors for release 0.13 by number of commits.

- 364 Andreas Müller
- 143 Arnaud Joly
- 137 Peter Prettenhofer
- 131 Gael Varoquaux
- 117 Mathieu Blondel
- 108 Lars Buitinck
1.7.33 Version 0.12.1

October 8, 2012

The 0.12.1 release is a bug-fix release with no additional features, but is instead a set of bug fixes

Changelog

- Improved numerical stability in spectral embedding by Gael Varoquaux
- Doctest under windows 64bit by Gael Varoquaux
- Documentation fixes for elastic net by Andreas Müller and Alexandre Gramfort
- Proper behavior with fortran-ordered NumPy arrays by Gael Varoquaux
- Make GridSearchCV work with non-CSR sparse matrix by Lars Buitinck
- Fix parallel computing in MDS by Gael Varoquaux
• Fix Unicode support in count vectorizer by Andreas Müller
• Fix MinCovDet breaking with X.shape = (3, 1) by Virgile Fritsch
• Fix clone of SGD objects by Peter Prettenhofer
• Stabilize GMM by Virgile Fritsch

People

• 14 Peter Prettenhofer
• 12 Gael Varoquaux
• 10 Andreas Müller
• 5 Lars Buitinck
• 3 Virgile Fritsch
• 1 Alexandre Gramfort
• 1 Gilles Louppe
• 1 Mathieu Blondel

1.7.34 Version 0.12

September 4, 2012

Changelog

• Various speed improvements of the decision trees module, by Gilles Louppe.
• GradientBoostingRegressor and GradientBoostingClassifier now support feature subsampling via the max_features argument, by Peter Prettenhofer.
• Added Huber and Quantile loss functions to GradientBoostingRegressor, by Peter Prettenhofer.
• Decision trees and forests of randomized trees now support multi-output classification and regression problems, by Gilles Louppe.
• Added LabelEncoder, a simple utility class to normalize labels or transform non-numerical labels, by Mathieu Blondel.
• Added the epsilon-insensitive loss and the ability to make probabilistic predictions with the modified huber loss in Stochastic Gradient Descent, by Mathieu Blondel.
• Added Multi-dimensional Scaling (MDS), by Nelle Varoquaux.
• SVMlight file format loader now detects compressed (gzip/bzip2) files and decompresses them on the fly, by Lars Buitinck.
• SVMlight file format serializer now preserves double precision floating point values, by Olivier Grisel.
• A common testing framework for all estimators was added, by Andreas Müller.
• Understandable error messages for estimators that do not accept sparse input by Gael Varoquaux.
• Speedups in hierarchical clustering by Gael Varoquaux. In particular building the tree now supports early stopping. This is useful when the number of clusters is not small compared to the number of samples.
• Add MultiTaskLasso and MultiTaskElasticNet for joint feature selection, by Alexandre Gramfort.
• Added `metrics.auc_score` and `metrics.average_precision_score` convenience functions by Andreas Müller.

• Improved sparse matrix support in the Feature selection module by Andreas Müller.

• New word boundaries-aware character n-gram analyzer for the Text feature extraction module by @kernc.

• Fixed bug in spectral clustering that led to single point clusters by Andreas Müller.

• In `CountVectorizer`, added an option to ignore infrequent words, `min_df` by Andreas Müller.

• Add support for multiple targets in some linear models (ElasticNet, Lasso and OrthogonalMatchingPursuit) by Vlad Niculae and Alexandre Gramfort.

• Fixes in ProbabilisticPCA score function by Wei Li.

• Fixed feature importance computation in Gradient Tree Boosting.

API changes summary

• The old scikits.learn package has disappeared; all code should import from sklearn instead, which was introduced in 0.9.

• In `metrics.roc_curve`, the `thresholds` array is now returned with it’s order reversed, in order to keep it consistent with the order of the returned `fpr` and `tpr`.

• In hmm objects, like GaussianHMM, MultinomialHMM, etc., all parameters must be passed to the object when initialising it and not through `fit`. Now `fit` will only accept the data as an input parameter.

• For all SVM classes, a faulty behavior of `gamma` was fixed. Previously, the default gamma value was only computed the first time `fit` was called and then stored. It is now recalculated on every call to `fit`.

• All `Base` classes are now abstract meta classes so that they can not be instantiated.

• `cluster.ward_tree` now also returns the parent array. This is necessary for early-stopping in which case the tree is not completely built.

• In `CountVectorizer` the parameters `min_n` and `max_n` were joined to the parameter `n_gram_range` to enable grid-searching both at once.

• In `CountVectorizer`, words that appear only in one document are now ignored by default. To reproduce the previous behavior, set `min_df=1`.

• Fixed API inconsistency: `linear_model.SGDClassifier.predict_proba` now returns 2d array when fit on two classes.

• Fixed API inconsistency: `discriminant_analysis.QuadraticDiscriminantAnalysis.decision_function` and `discriminant_analysis.LinearDiscriminantAnalysis.decision_function` now return 1d arrays when fit on two classes.

• Grid of alphas used for fitting LassoCV and ElasticNetCV is now stored in the attribute `alphas_` rather than overriding the init parameter `alphas`.

• Linear models when alpha is estimated by cross-validation store the estimated value in the `alpha_` attribute rather than just `alpha` or `best_alpha`.

• GradientBoostingClassifier now supports `staged_predict_proba`, and `staged_predict`.

• SVC and other sparse SVM classes are now deprecated. The all classes in the Support Vector Machines module now automatically select the sparse or dense representation base on the input.

• All clustering algorithms now interpret the array X given to `fit` as input data, in particular SpectralClustering and AffinityPropagation which previously expected affinity matrices.
• For clustering algorithms that take the desired number of clusters as a parameter, this parameter is now called n_clusters.

People

• 267 Andreas Müller
• 94 Gilles Louppe
• 89 Gael Varoquaux
• 79 Peter Prettenhofer
• 60 Mathieu Blondel
• 57 Alexandre Gramfort
• 52 Vlad Niculae
• 45 Lars Buitinck
• 44 Nelle Varoquaux
• 37 Jaques Grobler
• 30 Alexis Mignon
• 30 Inmanuel Bayer
• 27 Olivier Grisel
• 16 Subhodeep Moitra
• 13 Yannick Schwartz
• 12 @kernc
• 11 Virgile Fritsch
• 9 Daniel Duckworth
• 9 Fabian Pedregosa
• 9 Robert Layton
• 8 John Benediktsson
• 7 Marko Burjek
• 5 Nicolas Pinto
• 4 Alexandre Abraham
• 4 Jake Vanderplas
• 3 Brian Holt
• 3 Edouard Duchesnay
• 3 Florian Hoenig
• 3 flyingimmidev
• 2 Francois Savard
• 2 Hannes Schulz
• 2 Peter Welinder
1.7.35 Version 0.11

May 7, 2012

Changelog

Highlights

• Gradient boosted regression trees (Gradient Tree Boosting) for classification and regression by Peter Prettenhofer and Scott White.
• Simple dict-based feature loader with support for categorical variables (DictVectorizer) by Lars Buitinck.
• Added Matthews correlation coefficient (metrics.matthews_corrcoef) and added macro and micro average options to precision_score, metrics.recall_score and f1_score by Satrajit Ghosh.
• Out of Bag Estimates of generalization error for Ensemble methods by Andreas Müller.
• Randomized sparse linear models for feature selection, by Alexandre Gramfort and Gael Varoquaux
• Label Propagation for semi-supervised learning, by Clay Woolam. Note the semi-supervised API is still work in progress, and may change.
• Added BIC/AIC model selection to classical Gaussian mixture models and unified the API with the remainder of scikit-learn, by Bertrand Thirion
• Added StratifiedShuffleSplit, which is a ShuffleSplit with balanced splits, by Yannick Schwartz.
• NearestCentroid classifier added, along with a shrink_threshold parameter, which implements shrunken centroid classification, by Robert Layton.
Other changes

- Merged dense and sparse implementations of *Stochastic Gradient Descent* module and exposed utility extension types for sequential datasets `seq_dataset` and weight vectors `weight_vector` by Peter Prettenhofer.
- Added `partial_fit` (support for online/minibatch learning) and `warm_start` to the *Stochastic Gradient Descent* module by Mathieu Blondel.
- Dense and sparse implementations of *Support Vector Machines* classes and *LogisticRegression* merged by Lars Buitinck.
- Regressors can now be used as base estimator in the *Multiclass and multioutput algorithms* module by Mathieu Blondel.
- Added `n_jobs` option to `metrics.pairwise.pairwise_distances` and `metrics.pairwise.pairwise_kernels` for parallel computation, by Mathieu Blondel.
- *K-means* can now be run in parallel, using the `n_jobs` argument to either *K-means* or KMeans, by Robert Layton.
- Improved *Cross-validation: evaluating estimator performance* and *Tuning the hyper-parameters of an estimator* documentation and introduced the new `cross_validation.train_test_split` helper function by Olivier Grisel.
- *SVC* members `coef_` and `intercept_` changed sign for consistency with `decision_function`; for `kernel==linear`, `coef_` was fixed in the one-vs-one case, by Andreas Müller.
- Performance improvements to efficient leave-one-out cross-validated Ridge regression, esp. for the `n_samples > n_features` case, in `RidgeCV`, by Reuben Fletcher-Costin.
- Refactoring and simplification of the *Text feature extraction* API and fixed a bug that caused possible negative IDF, by Olivier Grisel.
- Beam pruning option in `_BaseHMM` module has been removed since it is difficult to Cythonize. If you are interested in contributing a Cython version, you can use the python version in the git history as a reference.
- Classes in *Nearest Neighbors* now support arbitrary Minkowski metric for nearest neighbors searches. The metric can be specified by argument `p`.

API changes summary

- *EllipticEnvelop* is now deprecated - Please use *EllipticEnvelope* instead.
- *NeighborsClassifier* and *NeighborsRegressor* are gone in the module *Nearest Neighbors*. Use the classes *KNeighborsClassifier*, *RadiusNeighborsClassifier*, *KNeighborsRegressor* and/or *RadiusNeighborsRegressor* instead.
- Sparse classes in the *Stochastic Gradient Descent* module are now deprecated.
- In *GMM*, *DPGMM* and *VBGMM*, parameters must be passed to an object when initialising it and not through `fit`. Now `fit` will only accept the data as an input parameter.
- Methods `rvs` and `decode` in *GMM* module are now deprecated. `sample` and `score` or `predict` should be used instead.
- Attribute `_scores` and `_pvalues` in univariate feature selection objects are now deprecated. `scores_` or `pvalues_` should be used instead.
- In *LogisticRegression*, *LinearSVC*, *SVC* and *NuSVC*, the `class_weight` parameter is now an initialization parameter, not a parameter to fit. This makes grid searches over this parameter possible.
• LFW data is now always shape \((n_{\text{samples}}, n_{\text{features}})\) to be consistent with the Olivetti faces dataset. Use images and pairs attribute to access the natural images shapes instead.

• In `LinearSVC`, the meaning of the `multi_class` parameter changed. Options now are 'ovr' and 'crammer_singer', with 'ovr' being the default. This does not change the default behavior but hopefully is less confusing.

• Class `Vectorizer` is deprecated and replaced by `TfidfVectorizer`.

• The preprocessor / analyzer nested structure for text feature extraction has been removed. All those features are now directly passed as flat constructor arguments to `TfidfVectorizer` and `CountVectorizer`, in particular the following parameters are now used:
  - `analyzer` can be 'word' or 'char' to switch the default analysis scheme, or use a specific python callable (as previously).
  - `tokenizer` and `preprocessor` have been introduced to make it still possible to customize those steps with the new API.
  - `input` explicitly control how to interpret the sequence passed to `fit` and `predict`: filenames, file objects or direct (byte or Unicode) strings.
  - charset decoding is explicit and strict by default.
  - the `vocabulary`, fitted or not is now stored in the `vocabulary_` attribute to be consistent with the project conventions.

• Class `TfidfVectorizer` now derives directly from `CountVectorizer` to make grid search trivial.

• Methods `rvs` in `_BaseHMM` module are now deprecated. `sample` should be used instead.

• Beam pruning option in `_BaseHMM` module is removed since it is difficult to be Cythonized. If you are interested, you can look in the history codes by git.

• The SVMlight format loader now supports files with both zero-based and one-based column indices, since both occur “in the wild”.

• Arguments in class `ShuffleSplit` are now consistent with `StratifiedShuffleSplit`. Arguments `test_fraction` and `train_fraction` are deprecated and renamed to `test_size` and `train_size` and can accept both float and int.

• Arguments in class `Bootstrap` are now consistent with `StratifiedShuffleSplit`. Arguments `n_test` and `n_train` are deprecated and renamed to `test_size` and `train_size` and can accept both float and int.

• Argument `p` added to classes in `Nearest Neighbors` to specify an arbitrary Minkowski metric for nearest neighbors searches.

People

• 282 Andreas Müller
• 239 Peter Prettenhofer
• 198 Gael Varoquaux
• 129 Olivier Grisel
• 114 Mathieu Blondel
• 103 Clay Woolam
• 96 Lars Buitinck
1.7.36 Version 0.10

January 11, 2012

Changelog

- Python 2.5 compatibility was dropped; the minimum Python version needed to use scikit-learn is now 2.6.
- Sparse inverse covariance estimation using the graph Lasso, with associated cross-validated estimator, by Gael Varoquaux
- New Tree module by Brian Holt, Peter Prettenhofer, Satrajit Ghosh and Gilles Louppe. The module comes with complete documentation and examples.
- Fixed a bug in the RFE module by Gilles Louppe (issue #378).
- Fixed a memory leak in Support Vector Machines module by Brian Holt (issue #367).
- Faster tests by Fabian Pedregosa and others.
- Silhouette Coefficient cluster analysis evaluation metric added as silhouette_score by Robert Layton.
- Fixed a bug in K-means in the handling of the n_init parameter: the clustering algorithm used to be run n_init times but the last solution was retained instead of the best solution by Olivier Grisel.
- Minor refactoring in Stochastic Gradient Descent module; consolidated dense and sparse predict methods; Enhanced test time performance by converting model parameters to fortran-style arrays after fitting (only multi-class).
- Adjusted Mutual Information metric added as adjusted_mutual_info_score by Robert Layton.
- Models like SVC/SVR/LinearSVC/LogisticRegression from libsvm/liblinear now support scaling of C regularization parameter by the number of samples by Alexandre Gramfort.
- New Ensemble Methods module by Gilles Louppe and Brian Holt. The module comes with the random forest algorithm and the extra-trees method, along with documentation and examples.
- Novelty and Outlier Detection: outlier and novelty detection, by Virgile Fritsch.
- Kernel Approximation: a transform implementing kernel approximation for fast SGD on non-linear kernels by Andreas Müller.
- Fixed a bug due to atom swapping in Orthogonal Matching Pursuit (OMP) by Vlad Niculae.
- Sparse coding with a precomputed dictionary by Vlad Niculae.
- Mini Batch K-Means performance improvements by Olivier Grisel.
- K-means support for sparse matrices by Mathieu Blondel.
- Improved documentation for developers and for the sklearn.utils module, by Jake Vanderplas.
- Vectorized 20newsgroups dataset loader (fetch_20newsgroups_vectorized) by Mathieu Blondel.
• **Multiclass and multioutput algorithms** by Lars Buitinck.
• Utilities for fast computation of mean and variance for sparse matrices by Mathieu Blondel.
• Make `scale` and `Scaler` work on sparse matrices by Olivier Grisel.
• Feature importances using decision trees and/or forest of trees, by Gilles Louppe.
• Parallel implementation of forests of randomized trees by Gilles Louppe.
• `ShuffleSplit` can subsample the train sets as well as the test sets by Olivier Grisel.
• Errors in the build of the documentation fixed by Andreas Müller.

**API changes summary**

Here are the code migration instructions when upgrading from scikit-learn version 0.9:

• Some estimators that may overwrite their inputs to save memory previously had `overwrite_` parameters; these have been replaced with `copy_` parameters with exactly the opposite meaning. This particularly affects some of the estimators in `linear_model`. The default behavior is still to copy everything passed in.
• The SVMlight dataset loader `load_svmlight_file` no longer supports loading two files at once; use `load_svmlight_files` instead. Also, the (unused) `buffer_mb` parameter is gone.
• Sparse estimators in the **Stochastic Gradient Descent** module use dense parameter vector `coef_` instead of `sparse_coef_`. This significantly improves test time performance.
• The **Covariance estimation** module now has a robust estimator of covariance, the Minimum Covariance Determinant estimator.
• Cluster evaluation metrics in `metrics.cluster` have been refactored but the changes are backwards compatible. They have been moved to the `metrics.cluster.supervised`, along with `metrics.cluster.unsupervised` which contains the Silhouette Coefficient.
• The `permutation_test_score` function now behaves the same way as `cross_val_score` (i.e. uses the mean score across the folds.)
• Cross Validation generators now use integer indices (`indices=True`) by default instead of boolean masks. This make it more intuitive to use with sparse matrix data.
• The functions used for sparse coding, `sparse_encode` and `sparse_encode_parallel` have been combined into `sparse_encode`, and the shapes of the arrays have been transposed for consistency with the matrix factorization setting, as opposed to the regression setting.
• Fixed an off-by-one error in the SVMlight/LibSVM file format handling; files generated using `dump_svmlight_file` should be re-generated. (They should continue to work, but accidentally had one extra column of zeros prepended.)
• `BaseDictionaryLearning` class replaced by `SparseCodingMixin`.
• `fast_svd` has been renamed `randomized_svd` and the default oversampling is now fixed to 10 additional random vectors instead of doubling the number of components to extract. The new behavior follows the reference paper.
People

The following people contributed to scikit-learn since last release:

- 246 Andreas Müller
- 242 Olivier Grisel
- 220 Gilles Louppe
- 183 Brian Holt
- 166 Gael Varoquaux
- 144 Lars Buitinck
- 73 Vlad Niculae
- 65 Peter Prettenhofer
- 64 Fabian Pedregosa
- 60 Robert Layton
- 55 Mathieu Blondel
- 52 Jake Vanderplas
- 44 Noel Dawe
- 38 Alexandre Gramfort
- 24 Virgile Fritsch
- 23 Satrajit Ghosh
- 3 Jan Hendrik Metzen
- 3 Kenneth C. Arnold
- 3 Shiqiao Du
- 3 Tim Sheerman-Chase
- 3 Yaroslav Halchenko
- 2 Bala Subrahmanyam Varanasi
- 2 DraXus
- 2 Michael Eickenberg
- 1 Bogdan Trach
- 1 Félix-Antoine Fortin
- 1 Juan Manuel Caicedo Carvajal
- 1 Nelle Varoquaux
- 1 Nicolas Pinto
- 1 Tiziano Zito
- 1 Xinfan Meng
1.7.37 Version 0.9

September 21, 2011

scikit-learn 0.9 was released on September 2011, three months after the 0.8 release and includes the new modules Manifold learning, The Dirichlet Process as well as several new algorithms and documentation improvements.

This release also includes the dictionary-learning work developed by Vlad Niculae as part of the Google Summer of Code program.
Changelog

• New Manifold learning module by Jake Vanderplas and Fabian Pedregosa.
• New Dirichlet Process Gaussian Mixture Model by Alexandre Passos
• Nearest Neighbors module refactoring by Jake Vanderplas : general refactoring, support for sparse matrices in input, speed and documentation improvements. See the next section for a full list of API changes.
• Improvements on the Feature selection module by Gilles Louppe : refactoring of the RFE classes, documentation rewrite, increased efficiency and minor API changes.
• Sparse principal components analysis (SparsePCA and MiniBatchSparsePCA) by Vlad Niculae, Gael Varoquaux and Alexandre Gramfort
• Printing an estimator now behaves independently of architectures and Python version thanks to Jean Kossaifi.
• Loader for libsvm/svmlight format by Mathieu Blondel and Lars Buitinck
• Documentation improvements: thumbnails in example gallery by Fabian Pedregosa.
• Important bugfixes in Support Vector Machines module (segfaults, bad performance) by Fabian Pedregosa.
• Added Multinomial Naïve Bayes and Bernoulli Naïve Bayes by Lars Buitinck
• Text feature extraction optimizations by Lars Buitinck
• Chi-Square feature selection (feature_selection.univariate_selection.chi2) by Lars Buitinck.
• Generated datasets module refactoring by Gilles Louppe
• Multiclass and multioutput algorithms by Mathieu Blondel
• Ball tree rewrite by Jake Vanderplas
• Implementation of DBSCAN algorithm by Robert Layton
• Kmeans predict and transform by Robert Layton
• Preprocessing module refactoring by Olivier Grisel
• Faster mean shift by Conrad Lee
• New Bootstrap, Random permutations cross-validation a.k.a. Shuffle & Split and various other improvements in cross validation schemes by Olivier Grisel and Gael Varoquaux
• Adjusted Rand index and V-Measure clustering evaluation metrics by Olivier Grisel
• Added Orthogonal Matching Pursuit by Vlad Niculae
• Added 2D-patch extractor utilities in the Feature extraction module by Vlad Niculae
• Implementation of LassoLarsCV (cross-validated Lasso solver using the Lars algorithm) and LassoLarsIC (BIC/AIC model selection in Lars) by Gael Varoquaux and Alexandre Gramfort
• Scalability improvements to metrics.roc_curve by Olivier Hervieu
• Distance helper functions metrics.pairwise.pairwise_distances and metrics.pairwise.pairwise_kernels by Robert Layton
• Mini-Batch K-Means by Nelle Varoquaux and Peter Prettenhofer.
• mldata utilities by Pietro Berkes.
• The Olivetti faces dataset by David Warde-Farley.
API changes summary

Here are the code migration instructions when upgrading from scikit-learn version 0.8:

- The `scikits.learn` package was renamed `sklearn`. There is still a `scikits.learn` package alias for backward compatibility.

Third-party projects with a dependency on scikit-learn 0.9+ should upgrade their codebase. For instance, under Linux / MacOSX just run (make a backup first):

```bash
find -name "*.py" | xargs sed -i 's/\bscikits.learn\b/sklearn/g'
```

- Estimators no longer accept model parameters as `fit` arguments: instead all parameters must be only be passed as constructor arguments or using the now public `set_params` method inherited from `BaseEstimator`.

Some estimators can still accept keyword arguments on the `fit` but this is restricted to data-dependent values (e.g. a Gram matrix or an affinity matrix that are precomputed from the `X` data matrix.

- The `cross_val` package has been renamed to `cross_validation` although there is also a `cross_val` package alias in place for backward compatibility.

Third-party projects with a dependency on scikit-learn 0.9+ should upgrade their codebase. For instance, under Linux / MacOSX just run (make a backup first):

```bash
find -name "*.py" | xargs sed -i 's/\bcross_val\b/cross_validation/g'
```

- The `score_func` argument of the `sklearn.cross_validation.cross_val_score` function is now expected to accept `y_test` and `y_predicted` as only arguments for classification and regression tasks or `X_test` for unsupervised estimators.

- `gamma` parameter for support vector machine algorithms is set to `1 / n_features` by default, instead of `1 / n_samples`.

- The `sklearn.hmm` has been marked as orphaned: it will be removed from scikit-learn in version 0.11 unless someone steps up to contribute documentation, examples and fix lurking numerical stability issues.

- `sklearn.neighbors` has been made into a submodule. The two previously available estimators, `NeighborsClassifier` and `NeighborsRegressor` have been marked as deprecated. Their functionality has been divided among five new classes: `NearestNeighbors` for unsupervised neighbors searches, `KNeighborsClassifier` & `RadiusNeighborsClassifier` for supervised classification problems, and `KNeighborsRegressor` & `RadiusNeighborsRegressor` for supervised regression problems.

- `sklearn.ball_tree.BallTree` has been moved to `sklearn.neighbors.BallTree`. Using the former will generate a warning.

- `sklearn.linear_model.LARS()` and related classes (`LassoLARS`, `LassoLARSCV`, etc.) have been renamed to `sklearn.linear_model.Lars()`.

- All distance metrics and kernels in `sklearn.metrics.pairwise` now have a `Y` parameter, which by default is `None`. If not given, the result is the distance (or kernel similarity) between each sample in `Y`. If given, the result is the pairwise distance (or kernel similarity) between samples in `X` to `Y`.

- `sklearn.metrics.pairwise.l1_distance` is now called `manhattan_distance`, and by default returns the pairwise distance. For the component wise distance, set the parameter `sum_over_features` to `False`.

Backward compatibility package aliases and other deprecated classes and functions will be removed in version 0.11.
People

38 people contributed to this release.

- 387 Vlad Niculae
- 320 Olivier Grisel
- 192 Lars Buitinck
- 179 Gael Varoquaux
- 168 Fabian Pedregosa (INRIA, Parietal Team)
- 127 Jake Vanderplas
- 120 Mathieu Blondel
- 85 Alexandre Passos
- 67 Alexandre Gramfort
- 57 Peter Prettenhofer
- 56 Gilles Louppe
- 42 Robert Layton
- 38 Nelle Varoquaux
- 32 Jean Kossaifi
- 30 Conrad Lee
- 22 Pietro Berkes
- 18 andy
- 17 David Warde-Farley
- 12 Brian Holt
- 11 Robert
- 8 Amit Aides
- 8 Virgile Fritsch
- 7 Yaroslav Halchenko
- 6 Salvatore Masecchia
- 5 Paolo Losi
- 4 Vincent Schut
- 3 Alexis Metaireau
- 3 Bryan Silverthorn
- 3 Andreas Müller
- 2 Minwoo Jake Lee
- 1 Emmanuelle Gouillart
- 1 Keith Goodman
- 1 Lucas Wiman
- 1 Nicolas Pinto
1.7.38 Version 0.8

May 11, 2011

scikit-learn 0.8 was released on May 2011, one month after the first “international” scikit-learn coding sprint and is marked by the inclusion of important modules: Hierarchical clustering, Cross decomposition, Non-negative matrix factorization (NMF or NNMF), initial support for Python 3 and by important enhancements and bug fixes.

Changelog

Several new modules where introduced during this release:

- New Hierarchical clustering module by Vincent Michel, Bertrand Thirion, Alexandre Gramfort and Gael Varoquaux.
- Kernel PCA implementation by Mathieu Blondel
- The Labeled Faces in the Wild face recognition dataset by Olivier Grisel.
- New Cross decomposition module by Edouard Duchesnay.
- Non-negative matrix factorization (NMF or NNMF) module Vlad Niculae
- Implementation of the Oracle Approximating Shrinkage algorithm by Virgile Fritsch in the Covariance estimation module.

Some other modules benefited from significant improvements or cleanups.

- Initial support for Python 3: builds and imports cleanly, some modules are usable while others have failing tests by Fabian Pedregosa.
- PCA is now usable from the Pipeline object by Olivier Grisel.
- Guide How to optimize for speed by Olivier Grisel.
- Fixes for memory leaks in libsvm bindings, 64-bit safer BallTree by Lars Buitinck.
- bug and style fixing in K-means algorithm by Jan Schlüter.
- Add attribute converged to Gaussian Mixture Models by Vincent Schut.
- Implemented transform, predict_log_proba in LinearDiscriminantAnalysis by Mathieu Blondel.
- Refactoring in the Support Vector Machines module and bug fixes by Fabian Pedregosa, Gael Varoquaux and Amit Aides.
- Refactored SGD module (removed code duplication, better variable naming), added interface for sample weight by Peter Prettenhofer.
- Wrapped BallTree with Cython by Thouis (Ray) Jones.
- Added function svm.l1_min_c by Paolo Losi.
- Typos, doc style, etc. by Yaroslav Halchenko, Gael Varoquaux, Olivier Grisel, Yann Malet, Nicolas Pinto, Lars Buitinck and Fabian Pedregosa.
People

People that made this release possible preceded by number of commits:

- 159 Olivier Grisel
- 96 Gael Varoquaux
- 96 Vlad Niculae
- 94 Fabian Pedregosa
- 36 Alexandre Gramfort
- 32 Paolo Losi
- 31 Edouard Duchesnay
- 30 Mathieu Blondel
- 25 Peter Prettenhofer
- 22 Nicolas Pinto
- 11 Virgile Fritsch
  -  7 Lars Buitinck
  -  6 Vincent Michel
  -  5 Bertrand Thirion
  -  4 Thouis (Ray) Jones
  -  4 Vincent Schut
  -  3 Jan Schlüter
  -  2 Julien Miotte
  -  2 Matthieu Perrot
  -  2 Yann Malet
  -  2 Yaroslav Halchenko
  -  1 Amit Aides
  -  1 Andreas Müller
  -  1 Feth Arezki
  -  1 Meng Xinfan

1.7.39 Version 0.7

March 2, 2011

scikit-learn 0.7 was released in March 2011, roughly three months after the 0.6 release. This release is marked by the speed improvements in existing algorithms like k-Nearest Neighbors and K-Means algorithm and by the inclusion of an efficient algorithm for computing the Ridge Generalized Cross Validation solution. Unlike the preceding release, no new modules were added to this release.
Changelog

- Performance improvements for Gaussian Mixture Model sampling [Jan Schlüter].
- Implementation of efficient leave-one-out cross-validated Ridge in `RidgeCV` [Mathieu Blondel].
- Better handling of collinearity and early stopping in `linear_model.lars_path` [Alexandre Gramfort and Fabian Pedregosa].
- Fixes for liblinear ordering of labels and sign of coefficients [Dan Yamins, Paolo Losi, Mathieu Blondel and Fabian Pedregosa].
- Performance improvements for Nearest Neighbors algorithm in high-dimensional spaces [Fabian Pedregosa].
- Performance improvements for `KMeans` [Gael Varoquaux and James Bergstra].
- Sanity checks for SVM-based classes [Mathieu Blondel].
- Refactoring of `NeighborsClassifier` and `neighbors.kneighbors_graph`: added different algorithms for the k-Nearest Neighbor Search and implemented a more stable algorithm for finding barycenter weights. Also added some developer documentation for this module, see notes_neighbors for more information [Fabian Pedregosa].
- Documentation improvements: Added `RandomizedPCA` and `LogisticRegression` to the class reference. Also added references of matrices used for clustering and other fixes [Gael Varoquaux, Fabian Pedregosa, Mathieu Blondel, Olivier Grisel, Virgile Fritsch, Emmanuelle Gouillart].
- Binded decision_function in classes that make use of liblinear, dense and sparse variants, like `LinearSVC` or `LogisticRegression` [Fabian Pedregosa].
- Performance and API improvements to `metrics.euclidean_distances` and to `RandomizedPCA` [James Bergstra].
- Fix compilation issues under NetBSD [Kamel Ibn Hassen Derouiche].
- Allow input sequences of different lengths in `GaussianHMM` [Ron Weiss].
- Fix bug in affinity propagation caused by incorrect indexing [Xinfan Meng].

People

People that made this release possiblepreceded by number of commits:

- 85 Fabian Pedregosa
- 67 Mathieu Blondel
- 20 Alexandre Gramfort
- 19 James Bergstra
- 14 Dan Yamins
- 13 Olivier Grisel
- 12 Gael Varoquaux
- 4 Edouard Duchesnay
- 4 Ron Weiss
- 2 Satrajit Ghosh
- 2 Vincent Dubourg
- 1 Emmanuelle Gouillart
scikit-learn user guide, Release 0.24.0

• 1 Kamel Ibn Hassen Derouiche
• 1 Paolo Losi
• 1 VirgileFritsch
• 1 Yaroslav Halchenko
• 1 Xinfan Meng

1.7.40 Version 0.6

December 21, 2010

scikit-learn 0.6 was released on December 2010. It is marked by the inclusion of several new modules and a general renaming of old ones. It is also marked by the inclusion of new example, including applications to real-world datasets.

Changelog

• New stochastic gradient descent module by Peter Prettenhofer. The module comes with complete documentation and examples.

• Improved svm module: memory consumption has been reduced by 50%, heuristic to automatically set class weights, possibility to assign weights to samples (see SVM: Weighted samples for an example).

• New Gaussian Processes module by Vincent Dubourg. This module also has great documentation and some very neat examples. See example_gaussian_process_plot_gp_regression.py or example_gaussian_process_plot_gp_probabilistic_classification_after_regression.py for a taste of what can be done.

• It is now possible to use liblinear’s Multi-class SVC (option multi_class in LinearSVC)

• New features and performance improvements of text feature extraction.

• Improved sparse matrix support, both in main classes (GridSearchCV) as in modules sklearn.svm.sparse and sklearn.linear_model.sparse.

• Lots of cool new examples and a new section that uses real-world datasets was created. These include: Faces recognition example using eigenfaces and SVMs, Species distribution modeling, Libsvm GUI, Wikipedia principal eigenvector and others.

• Faster Least Angle Regression algorithm. It is now 2x faster than the R version on worst case and up to 10x times faster on some cases.

• Faster coordinate descent algorithm. In particular, the full path version of lasso (linear_model.lasso_path) is more than 200x times faster than before.

• It is now possible to get probability estimates from a LogisticRegression model.

• module renaming: the glm module has been renamed to linear_model, the gmm module has been included into the more general mixture model and the sgd module has been included in linear_model.

• Lots of bug fixes and documentation improvements.
People

People that made this release possible preceded by number of commits:

- 207 Olivier Grisel
- 167 Fabian Pedregosa
- 97 Peter Prettenhofer
- 68 Alexandre Gramfort
- 59 Mathieu Blondel
- 55 Gael Varoquaux
- 33 Vincent Dubourg
- 21 Ron Weiss
- 9 Bertrand Thirion
- 3 Alexandre Passos
- 3 Anne-Laure Fouque
- 2 Ronan Amicel
- 1 Christian Osendorfer

1.7.41 Version 0.5

October 11, 2010

Changelog

New classes

- Support for sparse matrices in some classifiers of modules `svm` and `linear_model` (see `SVC`, `SVR`, `LinearSVC`, `Lasso`, `ElasticNet`)
- New `Pipeline` object to compose different estimators.
- Recursive Feature Elimination routines in module `Feature selection`.
- Addition of various classes capable of cross validation in the linear_model module (`LassoCV`, `ElasticNetCV`, etc.).
- New, more efficient LARS algorithm implementation. The Lasso variant of the algorithm is also implemented. See `lars_path`, `Lars` and `LassoLars`.
- New Hidden Markov Models module (see classes `GaussianHMM`, `MultinomialHMM`, `GMMHMM`)
- New module `feature_extraction` (see `class reference`)
- New FastICA algorithm in module `sklearn.fastica`
Documentation

- Improved documentation for many modules, now separating narrative documentation from the class reference. As an example, see documentation for the SVM module and the complete class reference.

Fixes

- API changes: adhere variable names to PEP-8, give more meaningful names.
- Fixes for svm module to run on a shared memory context (multiprocessing).
- It is again possible to generate latex (and thus PDF) from the sphinx docs.

Examples

- new examples using some of the mlcomp datasets: sphx_glr_auto_examples_mlcomp_sparse_document_classification.py (since removed) and Classification of text documents using sparse features
- Many more examples. See here the full list of examples.

External dependencies

- Joblib is now a dependency of this package, although it is shipped with (sklearn.externals.joblib).

Removed modules

- Module ann (Artificial Neural Networks) has been removed from the distribution. Users wanting this sort of algorithms should take a look into pybrain.

Misc

- New sphinx theme for the web page.

Authors

The following is a list of authors for this release, preceded by number of commits:

- 262 Fabian Pedregosa
- 240 Gael Varoquaux
- 149 Alexandre Gramfort
- 116 Olivier Grisel
- 40 Vincent Michel
- 38 Ron Weiss
- 23 Matthieu Perrot
- 10 Bertrand Thirion
- 7 Yaroslav Halchenko
- 9 VirgileFritsch
Major changes in this release include:

- Coordinate Descent algorithm (Lasso, ElasticNet) refactoring & speed improvements (roughly 100x times faster).
- Coordinate Descent Refactoring (and bug fixing) for consistency with R’s package GLMNET.
- New metrics module.
- New GMM module contributed by Ron Weiss.
- Implementation of the LARS algorithm (without Lasso variant for now).
- feature_selection module redesign.
- Migration to GIT as version control system.
- Removal of obsolete attrselect module.
- Rename of private compiled extensions (added underscore).
- Removal of legacy unmaintained code.
- Documentation improvements (both docstring and rst).
- Improvement of the build system to (optionally) link with MKL. Also, provide a lite BLAS implementation in case no system-wide BLAS is found.
- Lots of new examples.
- Many, many bug fixes …

Authors

The committer list for this release is the following (preceded by number of commits):

- 143 Fabian Pedregosa
- 35 Alexandre Gramfort
- 34 Olivier Grisel
- 11 Gael Varoquaux
- 5 Yaroslav Halchenko
- 2 Vincent Michel
- 1 Chris Filo Gorgolewski
1.7.43 Earlier versions

Earlier versions included contributions by Fred Mailhot, David Cooke, David Huard, Dave Morrill, Ed Schofield, Travis Oliphant, Pearu Peterson.

1.8 Roadmap

1.8.1 Purpose of this document

This document list general directions that core contributors are interested to see developed in scikit-learn. The fact that an item is listed here is in no way a promise that it will happen, as resources are limited. Rather, it is an indication that help is welcomed on this topic.

1.8.2 Statement of purpose: Scikit-learn in 2018

Eleven years after the inception of Scikit-learn, much has changed in the world of machine learning. Key changes include:

- Computational tools: The exploitation of GPUs, distributed programming frameworks like Scala/Spark, etc.
- High-level Python libraries for experimentation, processing and data management: Jupyter notebook, Cython, Pandas, Dask, Numba…
- Changes in the focus of machine learning research: artificial intelligence applications (where input structure is key) with deep learning, representation learning, reinforcement learning, domain transfer, etc.

A more subtle change over the last decade is that, due to changing interests in ML, PhD students in machine learning are more likely to contribute to PyTorch, Dask, etc. than to Scikit-learn, so our contributor pool is very different to a decade ago.

Scikit-learn remains very popular in practice for trying out canonical machine learning techniques, particularly for applications in experimental science and in data science. A lot of what we provide is now very mature. But it can be costly to maintain, and we cannot therefore include arbitrary new implementations. Yet Scikit-learn is also essential in defining an API framework for the development of interoperable machine learning components external to the core library.

Thus our main goals in this era are to:

- continue maintaining a high-quality, well-documented collection of canonical tools for data processing and machine learning within the current scope (i.e. rectangular data largely invariant to column and row order; predicting targets with simple structure)
- improve the ease for users to develop and publish external components
- improve inter-operability with modern data science tools (e.g. Pandas, Dask) and infrastructures (e.g. distributed processing)

Many of the more fine-grained goals can be found under the API tag on the issue tracker.
1.8.3 Architectural / general goals

The list is numbered not as an indication of the order of priority, but to make referring to specific points easier. Please add new entries only at the bottom. Note that the crossed out entries are already done, and we try to keep the document up to date as we work on these issues.

1. Improved handling of Pandas DataFrames
   - document current handling
   - column reordering issue #7242
   - avoiding unnecessary conversion to ndarray #12147
   - returning DataFrames from transformers #5523
   - getting DataFrames from dataset loaders #10733, #13902
   - Sparse currently not considered #12800

2. Improved handling of categorical features
   - Tree-based models should be able to handle both continuous and categorical features #12866 and #15550.
   - In dataset loaders #13902
   - As generic transformers to be used with ColumnTransforms (e.g. ordinal encoding supervised by correlation with target variable) #5853, #11805
   - Handling mixtures of categorical and continuous variables

3. Improved handling of missing data
   - Making sure meta-estimators are lenient towards missing data, #15319
   - Non-trivial imputers #11977, #12852
   - Learners directly handling missing data #13911
   - An amputation sample generator to make parts of a dataset go missing #6284

4. More didactic documentation
   - More and more options have been added to scikit-learn. As a result, the documentation is crowded which makes it hard for beginners to get the big picture. Some work could be done in prioritizing the information.

5. Passing around information that is not (X, y): Sample properties
   - We need to be able to pass sample weights to scorers in cross validation.
   - We should have standard/generalised ways of passing sample-wise properties around in meta-estimators. #4497 #7646

6. Passing around information that is not (X, y): Feature properties
   - Feature names or descriptions should ideally be available to fit for, e.g. . #6425 #6424
   - Per-feature handling (e.g. “is this a nominal / ordinal / English language text?”) should also not need to be provided to estimator constructors, ideally, but should be available as metadata alongside X. #8480

7. Passing around information that is not (X, y): Target information
   - We have problems getting the full set of classes to all components when the data is split/sampled. #6231 #8100
   - We have no way to handle a mixture of categorical and continuous targets.

8. Make it easier for external users to write Scikit-learn-compatible components
• More flexible estimator checks that do not select by estimator name \#6599 \#6715
• Example of how to develop an estimator or a meta-estimator, \#14582
• More self-sufficient running of scikit-learn-contrib or a similar resource

9. Support resampling and sample reduction
• Allow subsampling of majority classes (in a pipeline?) \#3855
• Implement random forests with resampling \#8732

10. Better interfaces for interactive development
• \_repr\_ and HTML visualisations of estimators \#6323 and \#14180.
• Include plotting tools, not just as examples. \#9173

11. Improved tools for model diagnostics and basic inference
• alternative feature importances implementations, \#13146
• better ways to handle validation sets when fitting
• better ways to find thresholds / create decision rules \#8614

12. Better tools for selecting hyperparameters with transductive estimators
• Grid search and cross validation are not applicable to most clustering tasks. Stability-based selection is more relevant.

13. Better support for manual and automatic pipeline building
• Easier way to construct complex pipelines and valid search spaces \#7608 \#5082 \#8243
• provide search ranges for common estimators??
• cf. searchgrid

14. Improved tracking of fitting
• Verbose is not very friendly and should use a standard logging library \#6929, \#78
• Callbacks or a similar system would facilitate logging and early stopping

15. Distributed parallelism
• Accept data which complies with \_array\_function__

16. A way forward for more out of core
• Dask enables easy out-of-core computation. While the Dask model probably cannot be adaptable to all machine-learning algorithms, most machine learning is on smaller data than ETL, hence we can maybe adapt to very large scale while supporting only a fraction of the patterns.

17. Support for working with pre-trained models
• Estimator “freezing”. In particular, right now it’s impossible to clone a CalibratedClassifierCV with prefit. \#8370, \#6451

18. Backwards-compatible de/serialization of some estimators
• Currently serialization (with pickle) breaks across versions. While we may not be able to get around other limitations of pickle re security etc, it would be great to offer cross-version safety from version 1.0. Note: Gael and Olivier think that this can cause heavy maintenance burden and we should manage the trade-offs. A possible alternative is presented in the following point.

19. Documentation and tooling for model lifecycle management
• Document good practices for model deployments and lifecycle: before deploying a model: snapshot the code versions (numpy, scipy, scikit-learn, custom code repo), the training script and an alias on how to retrieve historical training data + snapshot a copy of a small validation set + snapshot of the predictions (predicted probabilities for classifiers) on that validation set.

• Document and tools to make it easy to manage upgrade of scikit-learn versions:
  – Try to load the old pickle, if it works, use the validation set prediction snapshot to detect that the serialized model still behave the same;
  – If joblib.load / pickle.load not work, use the versioned control training script + historical training set to retrain the model and use the validation set prediction snapshot to assert that it is possible to recover the previous predictive performance: if this is not the case there is probably a bug in scikit-learn that needs to be reported.

20. Everything in Scikit-learn should probably conform to our API contract. We are still in the process of making decisions on some of these related issues.

• Pipeline `<pipeline.Pipeline>` and FeatureUnion modify their input parameters in fit. Fixing this requires making sure we have a good grasp of their use cases to make sure all current functionality is maintained. #8157 #7382

21. (Optional) Improve scikit-learn common tests suite to make sure that (at least for frequently used) models have stable predictions across-versions (to be discussed);

• Extend documentation to mention how to deploy models in Python-free environments for instance ONNX and use the above best practices to assess predictive consistency between scikit-learn and ONNX prediction functions on validation set.

• Document good practices to detect temporal distribution drift for deployed model and good practices for re-training on fresh data without causing catastrophic predictive performance regressions.

1.8.4 Subpackage-specific goals

**sklearn.ensemble**

• a stacking implementation, #11047

**sklearn.cluster**

• kmeans variants for non-Euclidean distances, if we can show these have benefits beyond hierarchical clustering.

**sklearn.model_selection**

• multi-metric scoring is slow #9326

• perhaps we want to be able to get back more than multiple metrics

• the handling of random states in CV splitters is a poor design and contradicts the validation of similar parameters in estimators, #15177

• exploit warm-starting and path algorithms so the benefits of EstimatorCV objects can be accessed via GridSearchCV and used in Pipelines. #1626

• Cross-validation should be able to be replaced by OOB estimates whenever a cross-validation iterator is used.

• Redundant computations in pipelines should be avoided (related to point above) cf daskml

**sklearn.neighbors**

• Ability to substitute a custom/approximate/precomputed nearest neighbors implementation for ours in all/most contexts that nearest neighbors are used for learning. #10463

**sklearn.pipeline**

1.8. Roadmap
• Performance issues with Pipeline.memory
• see “Everything in Scikit-learn should conform to our API contract” above

1.9 Scikit-learn governance and decision-making

The purpose of this document is to formalize the governance process used by the scikit-learn project, to clarify how decisions are made and how the various elements of our community interact. This document establishes a decision-making structure that takes into account feedback from all members of the community and strives to find consensus, while avoiding any deadlocks.

This is a meritocratic, consensus-based community project. Anyone with an interest in the project can join the community, contribute to the project design and participate in the decision making process. This document describes how that participation takes place and how to set about earning merit within the project community.

1.9.1 Roles And Responsibilities

Contributors

Contributors are community members who contribute in concrete ways to the project. Anyone can become a contributor, and contributions can take many forms – not only code – as detailed in the contributors guide.

Triage team

The triage team is composed of community members who have permission on github to label and close issues. Their work is crucial to improve the communication in the project and limit the crowding of the issue tracker.

Similarly to what has been decided in the python project, any contributor may become a member of the scikit-learn triage team, after showing some continuity in participating to scikit-learn development (with pull requests and reviews). Any core developer is welcome to propose a scikit-learn contributor to join the triage team. Other core developers are then consulted: while it is expected that most acceptances will be unanimous, a two-thirds majority is enough. Every new triager will be announced in the mailing list. Triagers are welcome to participate in monthly core developer meetings.

Core developers

Core developers are community members who have shown that they are dedicated to the continued development of the project through ongoing engagement with the community. They have shown they can be trusted to maintain scikit-learn with care. Being a core developer allows contributors to more easily carry on with their project related activities by giving them direct access to the project’s repository and is represented as being an organization member on the scikit-learn GitHub organization. Core developers are expected to review code contributions, can merge approved pull requests, can cast votes for and against merging a pull-request, and can be involved in deciding major changes to the API.

New core developers can be nominated by any existing core developers. Once they have been nominated, there will be a vote by the current core developers. Voting on new core developers is one of the few activities that takes place on the project’s private management list. While it is expected that most votes will be unanimous, a two-thirds majority of the cast votes is enough. The vote needs to be open for at least 1 week.

Core developers that have not contributed to the project (commits or GitHub comments) in the past 12 months will be asked if they want to become emeritus core developers and recant their commit and voting rights until they become active again. The list of core developers, active and emeritus (with dates at which they became active) is public on the scikit-learn website.
Technical Committee

The Technical Committee (TC) members are core developers who have additional responsibilities to ensure the smooth running of the project. TC members are expected to participate in strategic planning, and approve changes to the governance model. The purpose of the TC is to ensure a smooth progress from the big-picture perspective. Indeed changes that impact the full project require a synthetic analysis and a consensus that is both explicit and informed. In cases that the core developer community (which includes the TC members) fails to reach such a consensus in the required time frame, the TC is the entity to resolve the issue. Membership of the TC is by nomination by a core developer. A nomination will result in discussion which cannot take more than a month and then a vote by the core developers which will stay open for a week. TC membership votes are subject to a two-third majority of all cast votes as well as a simple majority approval of all the current TC members. TC members who do not actively engage with the TC duties are expected to resign.

The Technical Committee of scikit-learn consists of Alexandre Gramfort, Olivier Grisel, Adrin Jalali, Andreas Müller, Joel Nothman, Hanmin Qin, Gaël Varoquaux, and Roman Yurchak.

1.9.2 Decision Making Process

Decisions about the future of the project are made through discussion with all members of the community. All non-sensitive project management discussion takes place on the project contributors’ mailing list and the issue tracker. Occasionally, sensitive discussion occurs on a private list.

Scikit-learn uses a “consensus seeking” process for making decisions. The group tries to find a resolution that has no open objections among core developers. At any point during the discussion, any core-developer can call for a vote, which will conclude one month from the call for the vote. Any vote must be backed by a SLEP. If no option can gather two thirds of the votes cast, the decision is escalated to the TC, which in turn will use consensus seeking with the fallback option of a simple majority vote if no consensus can be found within a month. This is what we hereafter may refer to as “the decision making process”.

Decisions (in addition to adding core developers and TC membership as above) are made according to the following rules:

- **Minor Documentation changes**, such as typo fixes, or addition / correction of a sentence, but no change of the scikit-learn.org landing page or the “about” page: Requires +1 by a core developer, no -1 by a core developer (lazy consensus), happens on the issue or pull request page. Core developers are expected to give “reasonable time” to others to give their opinion on the pull request if they're not confident others would agree.

- **Code changes and major documentation changes** require +1 by two core developers, no -1 by a core developer (lazy consensus), happens on the issue of pull-request page.

- **Changes to the API principles and changes to dependencies or supported versions** happen via a Enhancement proposals (SLEPs) and follows the decision-making process outlined above.

- **Changes to the governance model** use the same decision process outlined above.

If a veto -1 vote is cast on a lazy consensus, the proposer can appeal to the community and core developers and the change can be approved or rejected using the decision making procedure outlined above.
1.9.3 Enhancement proposals (SLEPs)

For all votes, a proposal must have been made public and discussed before the vote. Such proposal must be a consolidated document, in the form of a ‘Scikit-Learn Enhancement Proposal’ (SLEP), rather than a long discussion on an issue. A SLEP must be submitted as a pull-request to enhancement proposals using the SLEP template.
2.1 An introduction to machine learning with scikit-learn

Section contents

In this section, we introduce the machine learning vocabulary that we use throughout scikit-learn and give a simple learning example.

2.1.1 Machine learning: the problem setting

In general, a learning problem considers a set of n samples of data and then tries to predict properties of unknown data. If each sample is more than a single number and, for instance, a multi-dimensional entry (aka multivariate data), it is said to have several attributes or features.

Learning problems fall into a few categories:

- **supervised learning**, in which the data comes with additional attributes that we want to predict (Click here to go to the scikit-learn supervised learning page). This problem can be either:
  - **classification**: samples belong to two or more classes and we want to learn from already labeled data how to predict the class of unlabeled data. An example of a classification problem would be handwritten digit recognition, in which the aim is to assign each input vector to one of a finite number of discrete categories. Another way to think of classification is as a discrete (as opposed to continuous) form of supervised learning where one has a limited number of categories and for each of the n samples provided, one is to try to label them with the correct category or class.
  - **regression**: if the desired output consists of one or more continuous variables, then the task is called regression. An example of a regression problem would be the prediction of the length of a salmon as a function of its age and weight.

- **unsupervised learning**, in which the training data consists of a set of input vectors x without any corresponding target values. The goal in such problems may be to discover groups of similar examples within the data, where it is called clustering, or to determine the distribution of data within the input space, known as density estimation, or to project the data from a high-dimensional space down to two or three dimensions for the purpose of visualization (Click here to go to the Scikit-Learn unsupervised learning page).
Training set and testing set

Machine learning is about learning some properties of a data set and then testing those properties against another data set. A common practice in machine learning is to evaluate an algorithm by splitting a data set into two. We call one of those sets the training set, on which we learn some properties; we call the other set the testing set, on which we test the learned properties.

2.1.2 Loading an example dataset

scikit-learn comes with a few standard datasets, for instance the iris and digits datasets for classification and the diabetes dataset for regression.

In the following, we start a Python interpreter from our shell and then load the iris and digits datasets. Our notational convention is that $ denotes the shell prompt while >>> denotes the Python interpreter prompt:

```python
$ python
>>> from sklearn import datasets
>>> iris = datasets.load_iris()
>>> digits = datasets.load_digits()
```

A dataset is a dictionary-like object that holds all the data and some metadata about the data. This data is stored in the .data member, which is a n_samples, n_features array. In the case of supervised problem, one or more response variables are stored in the .target member. More details on the different datasets can be found in the dedicated section.

For instance, in the case of the digits dataset, digits.data gives access to the features that can be used to classify the digits samples:

```python
>>> print(digits.data)
[[ 0.  0.  5.  ...,  0.  0.  0.]
 [ 0.  0.  0.  ..., 10.  0.  0.]
 [ 0.  0.  0.  ..., 16.  9.  0.]
 ...,
 [ 0.  0.  1.  ...,  6.  0.  0.]
 [ 0.  0.  2.  ..., 12.  0.  0.]
 [ 0.  0. 10.  ..., 12.  1.  0.]]
```

and digits.target gives the ground truth for the digit dataset, that is the number corresponding to each digit image that we are trying to learn:

```python
>>> digits.target
array([0, 1, 2, ..., 8, 9, 8])
```

Shape of the data arrays

The data is always a 2D array, shape (n_samples, n_features), although the original data may have had a different shape. In the case of the digits, each original sample is an image of shape (8, 8) and can be accessed using:

```python
>>> digits.images[0]
array([[ 0.,  0.,  5., ...,  9.,  1.,  0.,  0.],
 [ 0., 13., 15., ...,  5.,  0.],
 [ 0., 15.,  2.,  0.,  11.,  8.,  0.],
 [ 0.,  4., 12.,  0.,  0.,  8.,  8.,  0.]],
```
The simple example on this dataset illustrates how starting from the original problem one can shape the data for consumption in scikit-learn.

2.1.3 Learning and predicting

In the case of the digits dataset, the task is to predict, given an image, which digit it represents. We are given samples of each of the 10 possible classes (the digits zero through nine) on which we fit an estimator to be able to predict the classes to which unseen samples belong.

In scikit-learn, an estimator for classification is a Python object that implements the methods fit(X, y) and predict(T).

An example of an estimator is the class sklearn.svm.SVC, which implements support vector classification. The estimator’s constructor takes as arguments the model’s parameters.

For now, we will consider the estimator as a black box:

```python
>>> from sklearn import svm
>>> clf = svm.SVC(gamma=0.001, C=100.)
```

Choosing the parameters of the model

In this example, we set the value of gamma manually. To find good values for these parameters, we can use tools such as grid search and cross validation.

The clf (for classifier) estimator instance is first fitted to the model; that is, it must learn from the model. This is done by passing our training set to the fit method. For the training set, we’ll use all the images from our dataset, except for the last image, which we’ll reserve for our predicting. We select the training set with the [:-1] Python syntax, which produces a new array that contains all but the last item from digits.data:

```python
>>> clf.fit(digits.data[:-1], digits.target[:-1])
SVC(C=100.0, gamma=0.001)
```

Now you can predict new values. In this case, you’ll predict using the last image from digits.data. By predicting, you’ll determine the image from the training set that best matches the last image.

```python
>>> clf.predict(digits.data[-1:])
array([8])
```

The corresponding image is:
As you can see, it is a challenging task: after all, the images are of poor resolution. Do you agree with the classifier?

A complete example of this classification problem is available as an example that you can run and study: Recognizing hand-written digits.

2.1.4 Conventions

scikit-learn estimators follow certain rules to make their behavior more predictive. These are described in more detail in the Glossary of Common Terms and API Elements.

Type casting

Unless otherwise specified, input will be cast to float64:

```python
>>> import numpy as np
>>> from sklearn import random_projection

rng = np.random.RandomState(0)
X = rng.rand(10, 2000)
X = np.array(X, dtype='float32')
X.dtype
```

```{=error}
dtype('float32')
```

```python
transformer = random_projection.GaussianRandomProjection()
X_new = transformer.fit_transform(X)
X_new.dtype
```

```{=error}
dtype('float64')
```

In this example, X is float32, which is cast to float64 by `fit_transform(X)`.

Regression targets are cast to float64 and classification targets are maintained:

```python
>>> from sklearn import datasets
>>> from sklearn.svm import SVC

iris = datasets.load_iris()
clf = SVC()
clf.fit(iris.data, iris.target)
SVC()
```

```{=error}
list(clf.predict(iris.data[:3]))
```

```{=error}
[0, 0, 0]
```

```python
>>> clf.fit(iris.data, iris.target_names[iris.target])
SVC()
```

(continues on next page)
Here, the first `predict()` returns an integer array, since `iris.target` (an integer array) was used in `fit`. The second `predict()` returns a string array, since `iris.target_names` was for fitting.

### Refitting and updating parameters

Hyper-parameters of an estimator can be updated after it has been constructed via the `set_params()` method. Calling `fit()` more than once will overwrite what was learned by any previous `fit()`:

```python
>>> import numpy as np
>>> from sklearn.datasets import load_iris
>>> from sklearn.svm import SVC

X, y = load_iris(return_X_y=True)

clf = SVC()
clf.set_params(kernel='linear').fit(X, y)
array([0, 0, 0, 0, 0])

clf.set_params(kernel='rbf').fit(X, y)
array([0, 0, 0, 0, 0])
```

Here, the default kernel `rbf` is first changed to `linear` via `SVC.set_params()` after the estimator has been constructed, and changed back to `rbf` to refit the estimator and to make a second prediction.

### Multiclass vs. multilabel fitting

When using `multiclass classifiers`, the learning and prediction task that is performed is dependent on the format of the target data fit upon:

```python
>>> from sklearn.svm import SVC
>>> from sklearn.multiclass import OneVsRestClassifier
>>> from sklearn.preprocessing import LabelBinarizer

X = [[1, 2], [2, 4], [4, 5], [3, 2], [3, 1]]
y = [0, 0, 1, 1, 2]

classif = OneVsRestClassifier(estimator=SVC(random_state=0))
classif.fit(X, y).predict(X)
array([[1, 0, 0],
      [1, 0, 0],
      [0, 1, 0]])
```

In the above case, the classifier is fit on a 1d array of multiclass labels and the `predict()` method therefore provides corresponding multiclass predictions. It is also possible to fit upon a 2d array of binary label indicators:
Here, the classifier is fit() on a 2d binary label representation of y, using the LabelBinarizer. In this case predict() returns a 2d array representing the corresponding multilabel predictions.

Note that the fourth and fifth instances returned all zeroes, indicating that they matched none of the three labels fit upon. With multilabel outputs, it is similarly possible for an instance to be assigned multiple labels:

```python
>>> from sklearn.preprocessing import MultiLabelBinarizer
>>> y = [[0, 1], [0, 2], [1, 3], [0, 2, 3], [2, 4]]
>>> y = MultiLabelBinarizer().fit_transform(y)
>>> classif.fit(X, y).predict(X)
array([[1, 1, 0, 0, 0],
       [1, 0, 1, 0, 0],
       [0, 1, 0, 1, 0],
       [1, 0, 1, 0, 0],
       [1, 0, 1, 0, 0]])
```

In this case, the classifier is fit upon instances each assigned multiple labels. The MultiLabelBinarizer is used to binarize the 2d array of multilabels to fit upon. As a result, predict() returns a 2d array with multiple predicted labels for each instance.

### 2.2 A tutorial on statistical-learning for scientific data processing

#### Statistical learning

Machine learning is a technique with a growing importance, as the size of the datasets experimental sciences are facing is rapidly growing. Problems it tackles range from building a prediction function linking different observations, to classifying observations, or learning the structure in an unlabeled dataset.

This tutorial will explore statistical learning, the use of machine learning techniques with the goal of statistical inference: drawing conclusions on the data at hand.

Scikit-learn is a Python module integrating classic machine learning algorithms in the tightly-knit world of scientific Python packages (NumPy, SciPy, matplotlib).

#### 2.2.1 Statistical learning: the setting and the estimator object in scikit-learn

### Datasets

Scikit-learn deals with learning information from one or more datasets that are represented as 2D arrays. They can be understood as a list of multi-dimensional observations. We say that the first axis of these arrays is the samples axis, while the second is the features axis.

```python
>>> from sklearn import datasets
>>> iris = datasets.load_iris()
>>> data = iris.data
```
>>> data.shape
(150, 4)

It is made of 150 observations of irises, each described by 4 features: their sepal and petal length and width, as
detailed in iris.DESCR.

When the data is not initially in the \((n_{\text{samples}}, \ n_{\text{features}})\) shape, it needs to be preprocessed in order to
be used by scikit-learn.

An example of reshaping data would be the digits dataset

The digits dataset is made of 1797 8x8 images of hand-written digits

```python
>>> digits = datasets.load_digits()
```
```python
>>> digits.images.shape
(1797, 8, 8)
```
```python
>>> import matplotlib.pyplot as plt
```
```python
>>> plt.imshow(digits.images[-1],
...     cmap=plt.cm.gray_r)
<matplotlib.image.AxesImage object at ...>
```

![Image of a digit]

To use this dataset with scikit-learn, we transform each 8x8 image into a feature vector of length 64

```python
>>> data = digits.images.reshape(
...     (digits.images.shape[0], -1)
... )
```
Estimators objects

Fitting data: the main API implemented by scikit-learn is that of the estimator. An estimator is any object that learns from data; it may be a classification, regression or clustering algorithm or a transformer that extracts/filters useful features from raw data.

All estimator objects expose a `fit` method that takes a dataset (usually a 2-d array):

```python
>>> estimator.fit(data)
```

Estimator parameters: All the parameters of an estimator can be set when it is instantiated or by modifying the corresponding attribute:

```python
>>> estimator = Estimator(param1=1, param2=2)
>>> estimator.param1
1
```

Estimated parameters: When data is fitted with an estimator, parameters are estimated from the data at hand. All the estimated parameters are attributes of the estimator object ending by an underscore:

```python
>>> estimator.estimated_param_
```

2.2.2 Supervised learning: predicting an output variable from high-dimensional observations

The problem solved in supervised learning

`Supervised learning` consists in learning the link between two datasets: the observed data $X$ and an external variable $y$ that we are trying to predict, usually called “target” or “labels”. Most often, $y$ is a 1D array of length $n_{samples}$.

All supervised estimators in scikit-learn implement a `fit(X, y)` method to fit the model and a `predict(X)` method that, given unlabeled observations $X$, returns the predicted labels $y$.

Vocabulary: classification and regression

If the prediction task is to classify the observations in a set of finite labels, in other words to “name” the objects observed, the task is said to be a classification task. On the other hand, if the goal is to predict a continuous target variable, it is said to be a regression task.

When doing classification in scikit-learn, $y$ is a vector of integers or strings.

Note: See the `Introduction to machine learning with scikit-learn Tutorial` for a quick run-through on the basic machine learning vocabulary used within scikit-learn.
Nearest neighbor and the curse of dimensionality

Classifying irises:

The iris dataset is a classification task consisting in identifying 3 different types of irises (Setosa, Versicolour, and Virginica) from their petal and sepal length and width:

```python
>>> import numpy as np
>>> from sklearn import datasets
>>> iris_X, iris_y = datasets.load_iris(return_X_y=True)
>>> np.unique(iris_y)
array([0, 1, 2])
```

k-Nearest neighbors classifier

The simplest possible classifier is the nearest neighbor: given a new observation \( X_{test} \), find in the training set (i.e. the data used to train the estimator) the observation with the closest feature vector. (Please see the Nearest Neighbors section of the online Scikit-learn documentation for more information about this type of classifier.)

Training set and testing set

While experimenting with any learning algorithm, it is important not to test the prediction of an estimator on the data used to fit the estimator as this would not be evaluating the performance of the estimator on new data. This is why datasets are often split into train and test data.

KNN (k nearest neighbors) classification example:
```python
>>> # Split iris data in train and test data
>>> # A random permutation, to split the data randomly
>>> np.random.seed(0)
>>> indices = np.random.permutation(len(iris_X))
>>> iris_X_train = iris_X[indices[:-10]]
>>> iris_y_train = iris_y[indices[:-10]]
>>> iris_X_test = iris_X[indices[-10:]]
>>> iris_y_test = iris_y[indices[-10:]]
>>> # Create and fit a nearest-neighbor classifier
>>> from sklearn.neighbors import KNeighborsClassifier
>>> knn = KNeighborsClassifier()
>>> knn.fit(iris_X_train, iris_y_train)
KNeighborsClassifier()
>>> knn.predict(iris_X_test)
array([1, 2, 1, 0, 0, 2, 1, 2, 0, 0])
```

The curse of dimensionality

For an estimator to be effective, you need the distance between neighboring points to be less than some value $d$, which depends on the problem. In one dimension, this requires on average $n \sim 1/d$ points. In the context of the above $k$-NN example, if the data is described by just one feature with values ranging from 0 to 1 and with $n$ training observations, then new data will be no further away than $1/n$. Therefore, the nearest neighbor decision rule will be efficient as soon as $1/n$ is small compared to the scale of between-class feature variations.

If the number of features is $p$, you now require $n \sim 1/d^p$ points. Let’s say that we require 10 points in one dimension: now $10^p$ points are required in $p$ dimensions to pave the $[0, 1]$ space. As $p$ becomes large, the number of training points
required for a good estimator grows exponentially.

For example, if each point is just a single number (8 bytes), then an effective $k$-NN estimator in a paltry $p \sim 20$ dimensions would require more training data than the current estimated size of the entire internet ($\pm 1000$ Exabytes or so).

This is called the curse of dimensionality and is a core problem that machine learning addresses.

**Linear model: from regression to sparsity**

### Diabetes dataset

The diabetes dataset consists of 10 physiological variables (age, sex, weight, blood pressure) measure on 442 patients, and an indication of disease progression after one year:

```python
>>> diabetes_X, diabetes_y = datasets.load_diabetes(return_X_y=True)
>>> diabetes_X_train = diabetes_X[:-20]
>>> diabetes_X_test = diabetes_X[-20:]
>>> diabetes_y_train = diabetes_y[:-20]
>>> diabetes_y_test = diabetes_y[-20:]
```

The task at hand is to predict disease progression from physiological variables.

**Linear regression**

*LinearRegression*, in its simplest form, fits a linear model to the data set by adjusting a set of parameters in order to make the sum of the squared residuals of the model as small as possible.

Linear models: $y = X\beta + \epsilon$

- $X$: data
- $y$: target variable
- $\beta$: Coefficients
- $\epsilon$: Observation noise
```python
>>> from sklearn import linear_model
>>> regr = linear_model.LinearRegression()
>>> regr.fit(diabetes_X_train, diabetes_y_train)
LinearRegression()
>>> print(regr.coef_)
[ 0.30349955 -237.63931533  510.53060544  327.73698041 -814.13170937
  492.81458798 102.84845219  184.60648906  743.51961675  76.09517222]

>>> # The mean square error
>>> np.mean((regr.predict(diabetes_X_test) - diabetes_y_test)**2)
2004.56760268...

>>> # Explained variance score: 1 is perfect prediction
>>> # and 0 means that there is no linear relationship
>>> # between X and y.
>>> regr.score(diabetes_X_test, diabetes_y_test)
0.5850753022690...
```

### Shrinkage

If there are few data points per dimension, noise in the observations induces high variance:

```python
>>> X = np.c_[.5, 1].T
>>> y = [.5, 1]
>>> test = np.c_[0, 2].T
>>> regr = linear_model.LinearRegression()

>>> import matplotlib.pyplot as plt
>>> plt.figure()
>>> np.random.seed(0)
>>> for _ in range(6):
...    this_X = .1 * np.random.normal(size=(2, 1)) + X
...    regr.fit(this_X, y)
...    plt.plot(test, regr.predict(test))
...    plt.scatter(this_X, y, s=3)
```
A solution in high-dimensional statistical learning is to *shrink* the regression coefficients to zero: any two randomly chosen set of observations are likely to be uncorrelated. This is called *Ridge* regression:

```python
>>> regr = linear_model.Ridge(alpha=.1)
>>> plt.figure()
>>> np.random.seed(0)
>>> for _ in range(6):
...    this_X = .1 * np.random.normal(size=(2, 1)) + X
...    regr.fit(this_X, y)
...    plt.plot(test, regr.predict(test))
...    plt.scatter(this_X, y, s=3)
```

This is an example of *bias/variance tradeoff*: the larger the ridge alpha parameter, the higher the bias and the lower the variance.

We can choose alpha to minimize left out error, this time using the diabetes dataset rather than our synthetic data:
Note: Capturing in the fitted parameters noise that prevents the model to generalize to new data is called **overfitting**. The bias introduced by the ridge regression is called a **regularization**.

### Sparsity

#### Fitting only features 1 and 2

Note: A representation of the full diabetes dataset would involve 11 dimensions (10 feature dimensions and one of the target variable). It is hard to develop an intuition on such representation, but it may be useful to keep in mind that it would be a fairly **empty** space.

We can see that, although feature 2 has a strong coefficient on the full model, it conveys little information on \( y \) when considered with feature 1.

To improve the conditioning of the problem (i.e. mitigating the **The curse of dimensionality**), it would be interesting to select only the informative features and set non-informative ones, like feature 2 to 0. Ridge regression will decrease their contribution, but not set them to zero. Another penalization approach, called **Lasso** (least absolute shrinkage and...
selection operator), can set some coefficients to zero. Such methods are called **sparse method** and sparsity can be seen as an application of Occam’s razor: *prefer simpler models.*

```python
>>> regr = linear_model.Lasso()
>>> scores = [regr.set_params(alpha=alpha)
... .fit(diabetes_X_train, diabetes_y_train)
... .score(diabetes_X_test, diabetes_y_test)
... for alpha in alphas]
>>> best_alpha = alphas[scores.index(max(scores))]
>>> regr.alpha = best_alpha
>>> regr.fit(diabetes_X_train, diabetes_y_train)
```

Lasso(alpha=0.025118864315095794)

```python
>>> print(regr.coef_)
[ 0. -212.437... 517.194... 313.779... -160.830...
 -0. -187.195... 69.382... 508.660... 71.842...]
```

**Different algorithms for the same problem**

Different algorithms can be used to solve the same mathematical problem. For instance the `Lasso` object in scikit-learn solves the lasso regression problem using a coordinate descent method, that is efficient on large datasets. However, scikit-learn also provides the `LassoLars` object using the LARS algorithm, which is very efficient for problems in which the weight vector estimated is very sparse (i.e. problems with very few observations).

**Classification**

For classification, as in the labeling *iris* task, linear regression is not the right approach as it will give too much weight to data far from the decision frontier. A linear approach is to fit a sigmoid function or **logistic** function:

\[
y = \text{sigmoid}(X\beta - \text{offset}) + \epsilon = \frac{1}{1 + \exp(-X\beta + \text{offset})} + \epsilon
\]

```python
>>> log = linear_model.LogisticRegression(C=1e5)
>>> log.fit(iris_X_train, iris_y_train)
LogisticRegression(C=100000.0)
```

This is known as `LogisticRegression`.
Multiclass classification

If you have several classes to predict, an option often used is to fit one-versus-all classifiers and then use a voting heuristic for the final decision.

Shrinkage and sparsity with logistic regression

The $C$ parameter controls the amount of regularization in the `LogisticRegression` object: a large value for $C$ results in less regularization. `penalty="l2"` gives Shrinkage (i.e. non-sparse coefficients), while `penalty="l1"` gives Sparsity.

Exercise

Try classifying the digits dataset with nearest neighbors and a linear model. Leave out the last 10% and test prediction performance on these observations.

```python
from sklearn import datasets, neighbors, linear_model
X_digits, y_digits = datasets.load_digits(return_X_y=True)
X_digits = X_digits / X_digits.max()
```

A solution can be downloaded here.

Support vector machines (SVMs)

Linear SVMs

Support Vector Machines belong to the discriminant model family: they try to find a combination of samples to build a plane maximizing the margin between the two classes. Regularization is set by the $C$ parameter: a small value for $C$ means the margin is calculated using many or all of the observations around the separating line (more regularization); a large value for $C$ means the margin is calculated on observations close to the separating line (less regularization).
Fig. 1: Unregularized SVM

Fig. 2: Regularized SVM (default)
Example:

- Plot different SVM classifiers in the iris dataset

SVMs can be used in regression — SVR (Support Vector Regression)—, or in classification — SVC (Support Vector Classification).

```python
>>> from sklearn import svm
>>> svc = svm.SVC(kernel='linear')
>>> svc.fit(iris_X_train, iris_y_train)
```

**Warning: Normalizing data**

For many estimators, including the SVMs, having datasets with unit standard deviation for each feature is important to get good prediction.

**Using kernels**

Classes are not always linearly separable in feature space. The solution is to build a decision function that is not linear but may be polynomial instead. This is done using the kernel trick that can be seen as creating a decision energy by positioning kernels on observations:

**Linear kernel**

```python
>>> svc = svm.SVC(kernel='linear')
```
Polynomial kernel

```python
>>> svc = svm.SVC(kernel='poly',
...               degree=3)
>>> # degree: polynomial degree
```

RBF kernel (Radial Basis Function)

```python
>>> svc = svm.SVC(kernel='rbf')
>>> # gamma: inverse of size of
>>> # radial kernel
```
Interactive example

See the SVM GUI to download svm_gui.py; add data points of both classes with right and left button, fit the model and change parameters and data.

Exercise

Try classifying classes 1 and 2 from the iris dataset with SVMs, with the 2 first features. Leave out 10% of each class and test prediction performance on these observations.

Warning: the classes are ordered, do not leave out the last 10%, you would be testing on only one class.

Hint: You can use the decision_function method on a grid to get intuitions.

```python
iris = datasets.load_iris()
X = iris.data
y = iris.target

X = X[y != 0, :2]
y = y[y != 0]
```

A solution can be downloaded here
2.2.3 Model selection: choosing estimators and their parameters

Score, and cross-validated scores

As we have seen, every estimator exposes a `score` method that can judge the quality of the fit (or the prediction) on new data. Bigger is better.

```python
from sklearn import datasets, svm
X_digits, y_digits = datasets.load_digits(return_X_y=True)
svc = svm.SVC(C=1, kernel='linear')
svc.fit(X_digits[:-100], y_digits[:-100]).score(X_digits[-100:], y_digits[-100:]), 0.98
```

To get a better measure of prediction accuracy (which we can use as a proxy for goodness of fit of the model), we can successively split the data in `folds` that we use for training and testing:

```python
import numpy as np
X_folds = np.array_split(X_digits, 3)
y_folds = np.array_split(y_digits, 3)
scores = list()
for k in range(3):
    X_train = list(X_folds)
    X_train.pop(k)
    X_train = np.concatenate(X_train)
    y_train = list(y_folds)
    y_train.pop(k)
    y_train = np.concatenate(y_train)
    scores.append(svc.fit(X_train, y_train).score(X_test, y_test))
print(scores)
[0.934..., 0.956..., 0.939...]
```

This is called a `KFold` cross-validation.

Cross-validation generators

Scikit-learn has a collection of classes which can be used to generate lists of train/test indices for popular cross-validation strategies.

They expose a `split` method which accepts the input dataset to be split and yields the train/test set indices for each iteration of the chosen cross-validation strategy.

This example shows an example usage of the `split` method.

```python
from sklearn.model_selection import KFold, cross_val_score
X = ["a", "a", "a", "b", "b", "c", "c", "c", "c", "c"]
k_fold = KFold(n_splits=5)
for train_indices, test_indices in k_fold.split(X):
    print('Train: %s | test: %s' % (train_indices, test_indices))
Train: [2 3 4 5 6 7 8 9] | test: [0 1]
Train: [0 1 4 5 6 7 8 9] | test: [2 3]
Train: [0 1 2 3 6 7 8 9] | test: [4 5]
Train: [0 1 2 3 4 5 8 9] | test: [6 7]
Train: [0 1 2 3 4 5 6 7] | test: [8 9]
```

The cross-validation can then be performed easily:
The cross-validation score can be directly calculated using the `cross_val_score` helper. Given an estimator, the cross-validation object and the input dataset, the `cross_val_score` splits the data repeatedly into a training and a testing set, trains the estimator using the training set and computes the scores based on the testing set for each iteration of cross-validation.

By default the estimator’s `score` method is used to compute the individual scores.

Refer the `metrics module` to learn more on the available scoring methods.

```
>>> cross_val_score(svc, X_digits, y_digits, cv=k_fold, n_jobs=-1)
array([0.96388889, 0.92222222, 0.9637883 , 0.9637883 , 0.93036212])
```

`n_jobs=-1` means that the computation will be dispatched on all the CPUs of the computer.

Alternatively, the `scoring` argument can be provided to specify an alternative scoring method.

```
>>> cross_val_score(svc, X_digits, y_digits, cv=k_fold,...
    scoring='precision_macro')
array([0.96578289, 0.92708922, 0.96681476, 0.96362897, 0.93192644])
```

### Cross-validation generators

- **KFold**
  - `(n_splits, shuffle, random_state)`
  - Splits it into K folds, trains on K-1 and then tests on the left-out.

- **StratifiedKFold**
  - `(n_splits, shuffle, random_state)`
  - Same as K-Fold but preserves the class distribution within each fold.

- **GroupKFold**
  - `(n_splits)`
  - Ensures that the same group is not in both testing and training sets.

- **ShuffleSplit**
  - `(n_splits, test_size, train_size, random_state)`
  - Generates train/test indices based on random permutation.

- **StratifiedShuffleSplit**
  - `()`
  - Same as shuffle split but preserves the class distribution within each iteration.

- **GroupShuffleSplit**
  - `()`
  - Ensures that the same group is not in both testing and training sets.

- **LeaveOneGroupOut()**
  - `()`
  - Takes a group array to group observations.

- **LeavePOut**
  - `(p)`
  - Leave P observations out.

- **PredefinedSplit**
  - `()`
  - Generates train/test indices based on predefined splits.

### Exercise

On the digits dataset, plot the cross-validation score of a `SVC` estimator with an linear kernel as a function of parameter `C` (use a logarithmic grid of points, from 1 to 10).

```
import numpy as np
from sklearn.model_selection import cross_val_score
from sklearn import datasets, svm
```
X, y = datasets.load_digits(return_X_y=True)

csvc = svm.SVC(kernel='linear')
C_s = np.logspace(-10, 0, 10)

scores = list()

Solution: Cross-validation on Digits Dataset Exercise

Grid-search and cross-validated estimators

Grid-search

scikit-learn provides an object that, given data, computes the score during the fit of an estimator on a parameter grid and chooses the parameters to maximize the cross-validation score. This object takes an estimator during the construction and exposes an estimator API:

```python
cs = np.logspace(-6, -1, 10)
clf = GridSearchCV(estimator=svc, param_grid=dict(C=cs),
                  ... n_jobs=-1)
clf.fit(X_digits[:1000], y_digits[:1000])
```

(continues on next page)
By default, the `GridSearchCV` uses a 5-fold cross-validation. However, if it detects that a classifier is passed, rather than a regressor, it uses a stratified 5-fold.

**Nested cross-validation**

```python
>>> cross_val_score(clf, X_digits, y_digits)
array([0.938..., 0.963..., 0.944...])
```

Two cross-validation loops are performed in parallel: one by the `GridSearchCV` estimator to set `gamma` and the other one by `cross_val_score` to measure the prediction performance of the estimator. The resulting scores are unbiased estimates of the prediction score on new data.

**Warning:** You cannot nest objects with parallel computing (`n_jobs` different than 1).

### Cross-validated estimators

Cross-validation to set a parameter can be done more efficiently on an algorithm-by-algorithm basis. This is why, for certain estimators, scikit-learn exposes **Cross-validation: evaluating estimator performance** estimators that set their parameter automatically by cross-validation:

```python
>>> from sklearn import linear_model, datasets
>>> lasso = linear_model.LassoCV()
>>> X_diabetes, y_diabetes = datasets.load_diabetes(return_X_y=True)
>>> lasso.fit(X_diabetes, y_diabetes)
LassoCV()
>>> # The estimator chose automatically its lambda:
>>> lasso.alpha_
0.00375...
```

These estimators are called similarly to their counterparts, with ‘CV’ appended to their name.

### Exercise

On the diabetes dataset, find the optimal regularization parameter alpha.

**Bonus:** How much can you trust the selection of alpha?

```python
from sklearn import datasets
from sklearn.linear_model import LassoCV
from sklearn.linear_model import Lasso
from sklearn.model_selection import KFold
from sklearn.model_selection import GridSearchCV

X, y = datasets.load_diabetes(return_X_y=True)
X = X[:150]
```
2.2.4 Unsupervised learning: seeking representations of the data

Clustering: grouping observations together

The problem solved in clustering

Given the iris dataset, if we knew that there were 3 types of iris, but did not have access to a taxonomist to label them: we could try a clustering task: split the observations into well-separated group called clusters.

K-means clustering

Note that there exist a lot of different clustering criteria and associated algorithms. The simplest clustering algorithm is K-means.

```python
>>> from sklearn import cluster, datasets
>>> X_iris, y_iris = datasets.load_iris(return_X_y=True)

>>> k_means = cluster.KMeans(n_clusters=3)
>>> k_means.fit(X_iris)
KMeans(n_clusters=3)

>>> print(k_means.labels_[::10])
[1 1 1 1 0 0 0 0 2 2 2 2 2]

>>> print(y_iris[::10])
[0 0 0 0 1 1 1 1 2 2 2 2 2]
```

Warning: There is absolutely no guarantee of recovering a ground truth. First, choosing the right number of clusters is hard. Second, the algorithm is sensitive to initialization, and can fall into local minima, although scikit-learn employs several tricks to mitigate this issue.
Don’t over-interpret clustering results

**Application example: vector quantization**

Clustering in general and KMeans, in particular, can be seen as a way of choosing a small number of exemplars to
compress the information. The problem is sometimes known as vector quantization. For instance, this can be used to posterize an image:

```python
>>> import scipy as sp
>>> try:
...    face = sp.face(gray=True)
... except AttributeError:
...    from scipy import misc
...    face = misc.face(gray=True)
>>> X = face.reshape((-1, 1))  # We need an (n_sample, n_feature) array
>>> k_means = cluster.KMeans(n_clusters=5, n_init=1)
>>> k_means.fit(X)
KMeans(n_clusters=5, n_init=1)
>>> values = k_means.cluster_centers_.squeeze()
>>> labels = k_means.labels_
>>> face_compressed = np.choose(labels, values)
>>> face_compressed.shape = face.shape
```

![Fig. 6: Raw image](image1.png)

![Fig. 7: K-means quantization](image2.png)
Hierarchical agglomerative clustering: Ward

A hierarchical clustering method is a type of cluster analysis that aims to build a hierarchy of clusters. In general, the various approaches of this technique are either:

- **Agglomerative** - bottom-up approaches: each observation starts in its own cluster, and clusters are iteratively merged in such a way to minimize a linkage criterion. This approach is particularly interesting when the clusters of interest are made of only a few observations. When the number of clusters is large, it is much more computationally efficient than k-means.

- **Divisive** - top-down approaches: all observations start in one cluster, which is iteratively split as one moves down the hierarchy. For estimating large numbers of clusters, this approach is both slow (due to all observations starting as one cluster, which it splits recursively) and statistically ill-posed.
Connectivity-constrained clustering

With agglomerative clustering, it is possible to specify which samples can be clustered together by giving a connectivity graph. Graphs in scikit-learn are represented by their adjacency matrix. Often, a sparse matrix is used. This can be useful, for instance, to retrieve connected regions (sometimes also referred to as connected components) when clustering an image.

```python
>>> from skimage.data import coins
>>> from scipy.ndimage.filters import gaussian_filter
>>> from skimage.transform import rescale

rescaled_coins = rescale(...
    gaussian_filter(coins(), sigma=2),
    0.2, mode='reflect', anti_aliasing=False, multichannel=False
... )
>>> X = np.reshape(rescaled_coins, (-1, 1))

We need a vectorized version of the image. 'rescaled_coins' is a down-scaled version of the coins image to speed up the process:

```python
>>> from sklearn.feature_extraction import grid_to_graph

connectivity = grid_to_graph(*rescaled_coins.shape)
``` Define the graph structure of the data. Pixels connected to their neighbors:

```python
>>> n_clusters = 27  # number of regions
>>> from sklearn.cluster import AgglomerativeClustering

ward = AgglomerativeClustering(n_clusters=n_clusters, linkage='ward',
    connectivity=connectivity)
>>> ward.fit(X)
AgglomerativeClustering(connectivity=..., n_clusters=27)
>>> label = np.reshape(ward.labels_, rescaled_coins.shape)
```
Feature agglomeration

We have seen that sparsity could be used to mitigate the curse of dimensionality, i.e. an insufficient amount of observations compared to the number of features. Another approach is to merge together similar features: feature agglomeration. This approach can be implemented by clustering in the feature direction, in other words clustering the transposed data.

```python
>>> digits = datasets.load_digits()
>>> images = digits.images
>>> X = np.reshape(images, (len(images), -1))
>>> connectivity = grid_to_graph(*images[0].shape)

>>> agglo = cluster.FeatureAgglomeration(connectivity=connectivity,
...                                    n_clusters=32)

>>> agglo.fit(X)
FeatureAgglomeration(connectivity=..., n_clusters=32)

>>> X_reduced = agglo.transform(X)

>>> X_approx = agglo.inverse_transform(X_reduced)

>>> images_approx = np.reshape(X_approx, images.shape)
```

**transform and inverse_transform methods**

Some estimators expose a `transform` method, for instance to reduce the dimensionality of the dataset.

**Decompositions: from a signal to components and loadings**

**Components and loadings**

If \( X \) is our multivariate data, then the problem that we are trying to solve is to rewrite it on a different observational basis: we want to learn loadings \( L \) and a set of components \( C \) such that \( X = L C \). Different criteria exist to choose the components...
Principal component analysis: PCA

Principal component analysis (PCA) selects the successive components that explain the maximum variance in the signal.

The point cloud spanned by the observations above is very flat in one direction: one of the three univariate features can almost be exactly computed using the other two. PCA finds the directions in which the data is not flat.

When used to transform data, PCA can reduce the dimensionality of the data by projecting on a principal subspace.

```python
>>> # Create a signal with only 2 useful dimensions
>>> x1 = np.random.normal(size=100)
>>> x2 = np.random.normal(size=100)
>>> x3 = x1 + x2
>>> X = np.c_[x1, x2, x3]

>>> from sklearn import decomposition
>>> pca = decomposition.PCA()
>>> pca.fit(X)
PCA()

>>> print(pca.explained_variance_)
[ 2.18565811e+00 1.19346747e+00 8.43026679e-32]

>>> # As we can see, only the 2 first components are useful
>>> pca.n_components = 2
>>> X_reduced = pca.fit_transform(X)
>>> X_reduced.shape
(100, 2)
```
Independent Component Analysis: ICA

Independent component analysis (ICA) selects components so that the distribution of their loadings carries a maximum amount of independent information. It is able to recover non-Gaussian independent signals:

```python
>>> # Generate sample data
>>> import numpy as np
>>> from scipy import signal
>>> time = np.linspace(0, 10, 2000)
>>> s1 = np.sin(2 * time)  # Signal 1 : sinusoidal signal
>>> s2 = np.sign(np.sin(3 * time))  # Signal 2 : square signal
>>> s3 = signal.sawtooth(2 * np.pi * time)  # Signal 3: saw tooth signal
>>> S = np.c_[s1, s2, s3]
>>> S += 0.2 * np.random.normal(size=S.shape)  # Add noise
>>> S /= S.std(axis=0)  # Standardize data
>>> # Mix data
>>> A = np.array([[1, 1, 1], [0.5, 2, 1], [1.5, 1, 2]])  # Mixing matrix
>>> X = np.dot(S, A.T)  # Generate observations

>>> # Compute ICA
>>> ica = decomposition.FastICA()
>>> S_ = ica.fit_transform(X)  # Get the estimated sources
>>> A_ = ica.mixing_.T
>>> np.allclose(X, np.dot(S_, A_.T) + ica.mean_)
True
```
2.2.5 Putting it all together

Pipelining

We have seen that some estimators can transform data and that some estimators can predict variables. We can also create combined estimators:

```python
import numpy as np
import matplotlib.pyplot as plt
import pandas as pd

from sklearn import datasets
from sklearn.decomposition import PCA
from sklearn.linear_model import LogisticRegression
from sklearn.pipeline import Pipeline
from sklearn.model_selection import GridSearchCV

# Define a pipeline to search for the best combination of PCA truncation
# and classifier regularization.
pca = PCA()
# set the tolerance to a large value to make the example faster
logistic = LogisticRegression(max_iter=10000, tol=0.1)
pipe = Pipeline(steps=[('pca', pca), ('logistic', logistic)])

X_digits, y_digits = datasets.load_digits(return_X_y=True)

# Parameters of pipelines can be set using '__' separated parameter names:
param_grid = {
    'pca__n_components': [5, 15, 30, 45, 64],
    'logistic__C': np.logspace(-4, 4, 4),
}
search = GridSearchCV(pipe, param_grid, n_jobs=-1)
search.fit(X_digits, y_digits)
print("Best parameter (CV score=\%0.3f):" % search.best_score_)
print(search.best_params_)

# Plot the PCA spectrum
pca.fit(X_digits)

fig, (ax0, ax1) = plt.subplots(nrows=2, sharex=True, figsize=(6, 6))
ax0.plot(np.arange(1, pca.n_components_ + 1),
        pca.explained_variance_ratio_, '+', linewidth=2)
ax0.set_ylabel('PCA explained variance ratio')
ax0.axvline(search.best_estimator_.named_steps['pca'].n_components,
            linestyle=':', label='n_components chosen')
ax0.legend(prop=dict(size=12))
```
Face recognition with eigenfaces

The dataset used in this example is a preprocessed excerpt of the “Labeled Faces in the Wild”, also known as LFW:


<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ariel Sharon</td>
<td>0.67</td>
<td>0.92</td>
<td>0.77</td>
<td>13</td>
</tr>
<tr>
<td>Colin Powell</td>
<td>0.75</td>
<td>0.78</td>
<td>0.76</td>
<td>60</td>
</tr>
<tr>
<td>Donald Rumsfeld</td>
<td>0.78</td>
<td>0.67</td>
<td>0.72</td>
<td>27</td>
</tr>
<tr>
<td>George W Bush</td>
<td>0.86</td>
<td>0.86</td>
<td>0.86</td>
<td>146</td>
</tr>
<tr>
<td>Gerhard Schroeder</td>
<td>0.76</td>
<td>0.76</td>
<td>0.76</td>
<td>25</td>
</tr>
<tr>
<td>Hugo Chavez</td>
<td>0.67</td>
<td>0.67</td>
<td>0.67</td>
<td>15</td>
</tr>
<tr>
<td>Tony Blair</td>
<td>0.81</td>
<td>0.69</td>
<td>0.75</td>
<td>36</td>
</tr>
</tbody>
</table>

(continues on next page)
```python
from sklearn.model_selection import train_test_split
from sklearn.datasets import fetch_lfw_people
from sklearn.metrics import classification_report
from sklearn.metrics import confusion_matrix
from sklearn.decomposition import PCA
from sklearn.svm import SVC

print(__doc__)

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO, format='%(asctime)s %(message)s')

# #############################################################################
# Download the data, if not already on disk and load it as numpy arrays

lfw_people = fetch_lfw_people(min_faces_per_person=70, resize=0.4)

# introspect the images arrays to find the shapes (for plotting)
n_samples, h, w = lfw_people.images.shape

# for machine learning we use the 2 data directly (as relative pixel
# positions info is ignored by this model)
X = lfw_people.data
n_features = X.shape[1]

# the label to predict is the id of the person
y = lfw_people.target
target_names = lfw_people.target_names
n_classes = target_names.shape[0]

print("Total dataset size:")
print("n_samples: %d" % n_samples)
print("n_features: %d" % n_features)
print("n_classes: %d" % n_classes)

# #############################################################################
# Split into a training set and a test set using a stratified k fold

X_train, X_test, y_train, y_test = train_test_split(
    X, y, test_size=0.25, random_state=42)

# #############################################################################
# Compute a PCA (eigenfaces) on the face dataset (treated as unlabeled

(continues on previous page)
# dataset): unsupervised feature extraction / dimensionality reduction

n_components = 150

print("Extracting the top $%d$ eigenfaces from $%d$ faces"
       % (n_components, X_train.shape[0]))
t0 = time()
pca = PCA(n_components=n_components, svd_solver='randomized',
         whiten=True).fit(X_train)
print("done in $%0.3fs$ % (time() - t0))
eigenfaces = pca.components_.reshape((n_components, h, w))

print("Projecting the input data on the eigenfaces orthonormal basis")
t0 = time()
X_train_pca = pca.transform(X_train)
X_test_pca = pca.transform(X_test)
print("done in $%0.3fs$ % (time() - t0))

# #############################################################################
# Train a SVM classification model

print("Fitting the classifier to the training set")
t0 = time()
param_grid = {'C': [1e3, 5e3, 1e4, 5e4, 1e5],
              'gamma': [0.0001, 0.0005, 0.001, 0.005, 0.01, 0.1],
}
clf = GridSearchCV(SVC(kernel='rbf', class_weight='balanced'), param_grid)
clf = clf.fit(X_train_pca, y_train)
print("done in $%0.3fs$ % (time() - t0))
print("Best estimator found by grid search:")
print(clf.best_estimator_)

# #############################################################################
# Quantitative evaluation of the model quality on the test set

print("Predicting people's names on the test set")
t0 = time()
y_pred = clf.predict(X_test_pca)
print("done in $%0.3fs$ % (time() - t0))

print(classification_report(y_test, y_pred, target_names=target_names))
print(confusion_matrix(y_test, y_pred, labels=range(n_classes)))

# #############################################################################
# Qualitative evaluation of the predictions using matplotlib

def plot_gallery(images, titles, h, w, n_row=3, n_col=4):
    """Helper function to plot a gallery of portraits""
    plt.figure(figsize=(1.8 * n_col, 2.4 * n_row))
    plt.subplots_adjust(bottom=0, left=.01, right=.99, top=.90, hspace=.35)
    for i in range(n_row * n_col):
        plt.subplot(n_row, n_col, i + 1)
        plt.imshow(images[i].reshape((h, w)), cmap=plt.cm.gray)

(continues on next page)
plt.title(titles[i], size=12)
plt.xticks(())
plt.yticks(())

# plot the result of the prediction on a portion of the test set

def title(y_pred, y_test, target_names, i):
    pred_name = target_names[y_pred[i]].rsplit(' ', 1)[-1]
    true_name = target_names[y_test[i]].rsplit(' ', 1)[-1]
    return 'predicted: %s
true: %s' % (pred_name, true_name)

prediction_titles = [title(y_pred, y_test, target_names, i)
                     for i in range(y_pred.shape[0])]

plot_gallery(X_test, prediction_titles, h, w)

# plot the gallery of the most significative eigenfaces

eigenface_titles = ["eigenface %d" % i for i in range(eigenfaces.shape[0])]
plot_gallery(eigenfaces, eigenface_titles, h, w)

plt.show()

Fig. 10: Prediction

Expected results for the top 5 most represented people in the dataset:

<table>
<thead>
<tr>
<th>Name</th>
<th>Precision</th>
<th>Recall</th>
<th>F1-score</th>
<th>Support</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gerhard_Schroeder</td>
<td>0.91</td>
<td>0.75</td>
<td>0.82</td>
<td>28</td>
</tr>
</tbody>
</table>

(continues on next page)
Open problem: Stock Market Structure

Can we predict the variation in stock prices for Google over a given time frame?

Learning a graph structure

2.3 Working With Text Data

The goal of this guide is to explore some of the main scikit-learn tools on a single practical task: analyzing a collection of text documents (newsgroups posts) on twenty different topics.

In this section we will see how to:

- load the file contents and the categories
- extract feature vectors suitable for machine learning
- train a linear model to perform categorization
- use a grid search strategy to find a good configuration of both the feature extraction components and the classifier
2.3.1 Tutorial setup

To get started with this tutorial, you must first install `scikit-learn` and all of its required dependencies.

Please refer to the `installation instructions` page for more information and for system-specific instructions.

The source of this tutorial can be found within your `scikit-learn` folder:

```
scikit-learn/doc/tutorial/text_analytics/
```

The source can also be found on Github.

The tutorial folder should contain the following sub-folders:

- *.rst files - the source of the tutorial document written with sphinx
- data - folder to put the datasets used during the tutorial
- skeletons - sample incomplete scripts for the exercises
- solutions - solutions of the exercises

You can already copy the skeletons into a new folder somewhere on your hard-drive named `sklearn_tut_workspace` where you will edit your own files for the exercises while keeping the original skeletons intact:

```
$ cp -r skeletons work_directory/sklearn_tut_workspace
```

Machine learning algorithms need data. Go to each `$TUTORIAL_HOME/data` sub-folder and run the `fetch_data.py` script from there (after having read them first).

For instance:

```
$ cd $TUTORIAL_HOME/data/languages
$ less fetch_data.py
$ python fetch_data.py
```

2.3.2 Loading the 20 newsgroups dataset

The dataset is called “Twenty Newsgroups”. Here is the official description, quoted from the website:

The 20 Newsgroups data set is a collection of approximately 20,000 newsgroup documents, partitioned (nearly) evenly across 20 different newsgroups. To the best of our knowledge, it was originally collected by Ken Lang, probably for his paper “Newsweeder: Learning to filter netnews,” though he does not explicitly mention this collection. The 20 newsgroups collection has become a popular data set for experiments in text applications of machine learning techniques, such as text classification and text clustering.

In the following we will use the built-in dataset loader for 20 newsgroups from `scikit-learn`. Alternatively, it is possible to download the dataset manually from the website and use the `sklearn.datasets.load_files` function by pointing it to the `20news-bydate-train` sub-folder of the uncompressed archive folder.

In order to get faster execution times for this first example we will work on a partial dataset with only 4 categories out of the 20 available in the dataset:

```
>>> categories = ['alt.atheism', 'soc.religion.christian',
...                'comp.graphics', 'sci.med']
```

We can now load the list of files matching those categories as follows:

```
>>> from sklearn.datasets import fetch_20newsgroups
>>> twenty_train = fetch_20newsgroups(subset='train',
... categories=categories, shuffle=True, random_state=42)
```
The returned dataset is a scikit-learn “bunch”: a simple holder object with fields that can be both accessed as python dict keys or object attributes for convenience, for instance the target_names holds the list of the requested category names:

```python
>>> twenty_train.target_names
['alt.atheism', 'comp.graphics', 'sci.med', 'soc.religion.christian']
```

The files themselves are loaded in memory in the data attribute. For reference the filenames are also available:

```python
>>> len(twenty_train.data)
2257
>>> len(twenty_train.filenames)
2257
```

Let’s print the first lines of the first loaded file:

```python
>>> print("\n".join(twenty_train.data[0].split("\n")[:3]))
From: sd345@city.ac.uk (Michael Collier)
Subject: Converting images to HP LaserJet III?
Nntp-Posting-Host: hampton

comp.graphics
```

Supervised learning algorithms will require a category label for each document in the training set. In this case the category is the name of the newsgroup which also happens to be the name of the folder holding the individual documents. For speed and space efficiency reasons scikit-learn loads the target attribute as an array of integers that corresponds to the index of the category name in the target_names list. The category integer id of each sample is stored in the target attribute:

```python
>>> twenty_train.target[:10]
array([1, 1, 3, 3, 3, 3, 3, 2, 2, 2])
```

It is possible to get back the category names as follows:

```python
>>> for t in twenty_train.target[:10]:
...    print(twenty_train.target_names[t])
...    print(twenty_train.target_names[t])
```

You might have noticed that the samples were shuffled randomly when we called fetch_20newsgroups(..., shuffle=True, random_state=42): this is useful if you wish to select only a subset of samples to quickly train a model and get a first idea of the results before re-training on the complete dataset later.
2.3.3 Extracting features from text files

In order to perform machine learning on text documents, we first need to turn the text content into numerical feature vectors.

**Bags of words**

The most intuitive way to do so is to use a bags of words representation:

1. Assign a fixed integer id to each word occurring in any document of the training set (for instance by building a dictionary from words to integer indices).
2. For each document \( \#i \), count the number of occurrences of each word \( w \) and store it in \( X[i, j] \) as the value of feature \( \#j \) where \( j \) is the index of word \( w \) in the dictionary.

The bags of words representation implies that \( n_{\text{features}} \) is the number of distinct words in the corpus: this number is typically larger than 100,000.

If \( n_{\text{samples}} == 10000 \), storing \( X \) as a NumPy array of type float32 would require \( 10000 \times 100000 \times 4 \) bytes = 4GB in RAM which is barely manageable on today’s computers.

Fortunately, most values in \( X \) will be zeros since for a given document less than a few thousand distinct words will be used. For this reason we say that bags of words are typically high-dimensional sparse datasets. We can save a lot of memory by only storing the non-zero parts of the feature vectors in memory.

scipy.sparse matrices are data structures that do exactly this, and scikit-learn has built-in support for these structures.

**Tokenizing text with scikit-learn**

Text preprocessing, tokenizing and filtering of stopwords are all included in `CountVectorizer`, which builds a dictionary of features and transforms documents to feature vectors:

```python
>>> from sklearn.feature_extraction.text import CountVectorizer
>>> count_vect = CountVectorizer()
>>> X_train_counts = count_vect.fit_transform(twenty_train.data)
>>> X_train_counts.shape
(2257, 35788)
```

`CountVectorizer` supports counts of N-grams of words or consecutive characters. Once fitted, the vectorizer has built a dictionary of feature indices:

```python
>>> count_vect.vocabulary_.get(u'algorithm')
4690
```

The index value of a word in the vocabulary is linked to its frequency in the whole training corpus.
From occurrences to frequencies

Occurrence count is a good start but there is an issue: longer documents will have higher average count values than shorter documents, even though they might talk about the same topics.

To avoid these potential discrepancies it suffices to divide the number of occurrences of each word in a document by the total number of words in the document: these new features are called tf for Term Frequencies. Another refinement on top of tf is to downscale weights for words that occur in many documents in the corpus and are therefore less informative than those that occur only in a smaller portion of the corpus. This downscaling is called tf-idf for “Term Frequency times Inverse Document Frequency”.

Both tf and tf-idf can be computed as follows using TfidfTransformer:

```python
>>> from sklearn.feature_extraction.text import TfidfTransformer
>>> tf_transformer = TfidfTransformer(use_idf=False).fit(X_train_counts)
>>> X_train_tf = tf_transformer.transform(X_train_counts)
>>> X_train_tf.shape
(2257, 35788)
```

In the above example-code, we firstly use the `fit(..)` method to fit our estimator to the data and secondly the `transform(..)` method to transform our count-matrix to a tf-idf representation. These two steps can be combined to achieve the same end result faster by skipping redundant processing. This is done through using the `fit_transform(..)` method as shown below, and as mentioned in the note in the previous section:

```python
>>> tfidf_transformer = TfidfTransformer()
>>> X_train_tfidf = tfidf_transformer.fit_transform(X_train_counts)
>>> X_train_tfidf.shape
(2257, 35788)
```

### 2.3.4 Training a classifier

Now that we have our features, we can train a classifier to try to predict the category of a post. Let’s start with a naïve Bayes classifier, which provides a nice baseline for this task. scikit-learn includes several variants of this classifier; the one most suitable for word counts is the multinomial variant:

```python
>>> from sklearn.naive_bayes import MultinomialNB
>>> clf = MultinomialNB().fit(X_train_tfidf, twenty_train.target)
```

To try to predict the outcome on a new document we need to extract the features using almost the same feature extracting chain as before. The difference is that we call `transform` instead of `fit_transform` on the transformers, since they have already been fit to the training set:

```python
>>> docs_new = ['God is love', 'OpenGL on the GPU is fast']
>>> X_new_counts = count_vect.transform(docs_new)
>>> X_new_tfidf = tfidf_transformer.transform(X_new_counts)
```

```python
>>> predicted = clf.predict(X_new_tfidf)
>>> for doc, category in zip(docs_new, predicted):
...    print('%r => %s' % (doc, twenty_train.target_names[category]))
'God is love' => soc.religion.christian
'OpenGL on the GPU is fast' => comp.graphics
```
2.3.5 Building a pipeline

In order to make the vectorizer => transformer => classifier easier to work with, scikit-learn provides a `Pipeline` class that behaves like a compound classifier:

```python
>>> from sklearn.pipeline import Pipeline
>>> text_clf = Pipeline([  
...     ('vect', CountVectorizer()),
...     ('tfidf', TfidfTransformer()),
...     ('clf', MultinomialNB()),
... ])
```

The names `vect`, `tfidf` and `clf` (classifier) are arbitrary. We will use them to perform grid search for suitable hyperparameters below. We can now train the model with a single command:

```python
>>> text_clf.fit(twenty_train.data, twenty_train.target)
Pipeline(...)
```

2.3.6 Evaluation of the performance on the test set

Evaluating the predictive accuracy of the model is equally easy:

```python
>>> import numpy as np
>>> twenty_test = fetch_20newsgroups(subset='test',
...     categories=categories, shuffle=True, random_state=42)
>>> docs_test = twenty_test.data
>>> predicted = text_clf.predict(docs_test)
>>> np.mean(predicted == twenty_test.target)
0.8348...
```

We achieved 83.5% accuracy. Let’s see if we can do better with a linear support vector machine (SVM), which is widely regarded as one of the best text classification algorithms (although it’s also a bit slower than naïve Bayes). We can change the learner by simply plugging a different classifier object into our pipeline:

```python
>>> from sklearn.linear_model import SGDClassifier
>>> text_clf = Pipeline([  
...     ('vect', CountVectorizer()),
...     ('tfidf', TfidfTransformer()),
...     ('clf', SGDClassifier(loss='hinge', penalty='l2',
...         alpha=1e-3, random_state=42,
...         max_iter=5, tol=None)),
... ])
>>> text_clf.fit(twenty_train.data, twenty_train.target)
Pipeline(...)
>>> predicted = text_clf.predict(docs_test)
>>> np.mean(predicted == twenty_test.target)
0.9101...
```

We achieved 91.3% accuracy using the SVM. scikit-learn provides further utilities for more detailed performance analysis of the results:

```python
>>> from sklearn import metrics
>>> print(metrics.classification_report(twenty_test.target, predicted,
...     target_names=twenty_test.target_names))
```

(continues on next page)
As expected the confusion matrix shows that posts from the newsgroups on atheism and Christianity are more often confused for one another than with computer graphics.

### 2.3.7 Parameter tuning using grid search

We’ve already encountered some parameters such as `use_idf` in the `TfidfTransformer`. Classifiers tend to have many parameters as well; e.g., `MultinomialNB` includes a smoothing parameter `alpha` and `SGDClassifier` has a penalty parameter `alpha` and configurable loss and penalty terms in the objective function (see the module documentation, or use the Python `help` function to get a description of these).

Instead of tweaking the parameters of the various components of the chain, it is possible to run an exhaustive search of the best parameters on a grid of possible values. We try out all classifiers on either words or bigrams, with or without idf, and with a penalty parameter of either 0.01 or 0.001 for the linear SVM:

```python
>>> from sklearn.model_selection import GridSearchCV
>>> parameters = {
... 'vect__ngram_range': [(1, 1), (1, 2)],
... 'tfidf__use_idf': (True, False),
... 'clf__alpha': (1e-2, 1e-3),
... }
```

Obviously, such an exhaustive search can be expensive. If we have multiple CPU cores at our disposal, we can tell the grid searcher to try these eight parameter combinations in parallel with the `n_jobs` parameter. If we give this parameter a value of -1, grid search will detect how many cores are installed and use them all:

```python
>>> gs_clf = GridSearchCV(text_clf, parameters, cv=5, n_jobs=-1)
```

The grid search instance behaves like a normal scikit-learn model. Let’s perform the search on a smaller subset of the training data to speed up the computation:

```python
>>> gs_clf = gs_clf.fit(twenty_train.data[:400], twenty_train.target[:400])
```

The result of calling `fit` on a `GridSearchCV` object is a classifier that we can use to predict:

```python
>>> twenty_train.target_names[gs_clf.predict(['God is love'])[0]]
'soc.religion.christian'
```
The object’s `best_score_` and `best_params_` attributes store the best mean score and the parameters setting corresponding to that score:

```python
>>> gs_clf.best_score_
0.9...
>>> for param_name in sorted(parameters.keys()):
...     print("%s: %r" % (param_name, gs_clf.best_params_[param_name]))
...     clf__alpha: 0.001
tfidf__use_idf: True
textvectorizer__ngram_range: (1, 1)
```

A more detailed summary of the search is available at `gs_clf.cv_results_`.

The `cv_results_` parameter can be easily imported into pandas as a DataFrame for further inspection.

**Exercises**

To do the exercises, copy the content of the ‘skeletons’ folder as a new folder named ‘workspace’:

```
$ cp -r skeletons workspace
```

You can then edit the content of the workspace without fear of losing the original exercise instructions.

Then fire an ipython shell and run the work-in-progress script with:

```
[1] %run workspace/exercise_XX_script.py arg1 arg2 arg3
```

If an exception is triggered, use `%debug` to fire-up a post mortem ipdb session.

Refine the implementation and iterate until the exercise is solved.

For each exercise, the skeleton file provides all the necessary import statements, boilerplate code to load the data and sample code to evaluate the predictive accuracy of the model.

### 2.3.8 Exercise 1: Language identification

- Write a text classification pipeline using a custom preprocessor and CharNGramAnalyzer using data from Wikipedia articles as training set.
- Evaluate the performance on some held out test set.

ipython command line:

```
%run workspace/exercise_01_language_train_model.py data/languages/paragraphs/
```

### 2.3.9 Exercise 2: Sentiment Analysis on movie reviews

- Write a text classification pipeline to classify movie reviews as either positive or negative.
- Find a good set of parameters using grid search.
- Evaluate the performance on a held out test set.

ipython command line:

```
%run workspace/exercise_02_sentiment.py data/movie_reviews/txt_sentoken/
```
2.3.10 Exercise 3: CLI text classification utility

Using the results of the previous exercises and the `cPickle` module of the standard library, write a command line utility that detects the language of some text provided on stdin and estimate the polarity (positive or negative) if the text is written in English.

Bonus point if the utility is able to give a confidence level for its predictions.

2.3.11 Where to from here

Here are a few suggestions to help further your scikit-learn intuition upon the completion of this tutorial:

- Try playing around with the `analyzer` and `token normalisation` under `CountVectorizer`.
- If you don’t have labels, try using `Clustering` on your problem.
- If you have multiple labels per document, e.g categories, have a look at the `Multiclass and multilabel section`.
- Try using `Truncated SVD` for latent semantic analysis.
- Have a look at using `Out-of-core Classification` to learn from data that would not fit into the computer main memory.
- Have a look at the `Hashing Vectorizer` as a memory efficient alternative to `CountVectorizer`.

2.4 Choosing the right estimator

Often the hardest part of solving a machine learning problem can be finding the right estimator for the job. Different estimators are better suited for different types of data and different problems. The flowchart below is designed to give users a bit of a rough guide on how to approach problems with regard to which estimators to try on your data.

Click on any estimator in the chart below to see its documentation.

2.5 External Resources, Videos and Talks

For written tutorials, see the `Tutorial section` of the documentation.

2.5.1 New to Scientific Python?

For those that are still new to the scientific Python ecosystem, we highly recommend the `Python Scientific Lecture Notes`. This will help you find your footing a bit and will definitely improve your scikit-learn experience. A basic understanding of NumPy arrays is recommended to make the most of scikit-learn.
2.5.2 External Tutorials

There are several online tutorials available which are geared toward specific subject areas:

- Machine Learning for NeuroImaging in Python
- Machine Learning for Astronomical Data Analysis

2.5.3 Videos

- An introduction to scikit-learn Part I and Part II at Scipy 2013 by Gael Varoquaux, Jake Vanderplas and Olivier Grisel. Notebooks on github.
- Introduction to scikit-learn by Gael Varoquaux at ICML 2010
  
  A three minute video from a very early stage of scikit-learn, explaining the basic idea and approach we are following.
- Introduction to statistical learning with scikit-learn by Gael Varoquaux at SciPy 2011
  
  An extensive tutorial, consisting of four sessions of one hour. The tutorial covers the basics of machine learning, many algorithms and how to apply them using scikit-learn. The material corresponding is now in the scikit-learn documentation section A tutorial on statistical-learning for scientific data processing.
- Statistical Learning for Text Classification with scikit-learn and NLTK (and slides) by Olivier Grisel at PyCon 2011
  
  Thirty minute introduction to text classification. Explains how to use NLTK and scikit-learn to solve real-world text classification tasks and compares against cloud-based solutions.
- Introduction to Interactive Predictive Analytics in Python with scikit-learn by Olivier Grisel at PyCon 2012
  
  3-hours long introduction to prediction tasks using scikit-learn.
- scikit-learn - Machine Learning in Python by Jake Vanderplas at the 2012 PyData workshop at Google
  
  Interactive demonstration of some scikit-learn features. 75 minutes.
- scikit-learn tutorial by Jake Vanderplas at PyData NYC 2012
  
  Presentation using the online tutorial, 45 minutes.

Note: Doctest Mode

The code-examples in the above tutorials are written in a python-console format. If you wish to easily execute these examples in IPython, use:

```
%doctest_mode
```

in the IPython-console. You can then simply copy and paste the examples directly into IPython without having to worry about removing the >>> manually.
The purpose of this guide is to illustrate some of the main features that scikit-learn provides. It assumes a very basic working knowledge of machine learning practices (model fitting, predicting, cross-validation, etc.). Please refer to our installation instructions for installing scikit-learn.

Scikit-learn is an open source machine learning library that supports supervised and unsupervised learning. It also provides various tools for model fitting, data preprocessing, model selection and evaluation, and many other utilities.

### 3.1 Fitting and predicting: estimator basics

Scikit-learn provides dozens of built-in machine learning algorithms and models, called estimators. Each estimator can be fitted to some data using its `fit` method.

Here is a simple example where we fit a `RandomForestClassifier` to some very basic data:

```python
>>> from sklearn.ensemble import RandomForestClassifier
>>> clf = RandomForestClassifier(random_state=0)
>>> X = [[1, 2, 3], # 2 samples, 3 features...
     [11, 12, 13]]
>>> y = [0, 1] # classes of each sample
>>> clf.fit(X, y)
RandomForestClassifier(random_state=0)
```

The `fit` method generally accepts 2 inputs:

- The samples matrix (or design matrix) $X$. The size of $X$ is typically $(n\_samples, n\_features)$, which means that samples are represented as rows and features are represented as columns.

- The target values $y$ which are real numbers for regression tasks, or integers for classification (or any other discrete set of values). For unsupervised learning tasks, $y$ does not need to be specified. $y$ is usually 1d array where the $i$ th entry corresponds to the target of the $i$ th sample (row) of $X$.

Both $X$ and $y$ are usually expected to be numpy arrays or equivalent `array-like` data types, though some estimators work with other formats such as sparse matrices.

Once the estimator is fitted, it can be used for predicting target values of new data. You don’t need to re-train the estimator:

```python
>>> clf.predict(X) # predict classes of the training data
array([0, 1])
>>> clf.predict([4, 5, 6], [14, 15, 16]) # predict classes of new data
array([0, 1])
```
3.2 Transformers and pre-processors

Machine learning workflows are often composed of different parts. A typical pipeline consists of a pre-processing step that transforms or imputes the data, and a final predictor that predicts target values.

In scikit-learn, pre-processors and transformers follow the same API as the estimator objects (they actually all inherit from the same BaseEstimator class). The transformer objects don’t have a predict method but rather a transform method that outputs a newly transformed sample matrix X:

```python
>>> from sklearn.preprocessing import StandardScaler
>>> X = [[0, 15], ...
...      [1, -10]]
>>> # scale data according to computed scaling values
>>> StandardScaler().fit(X).transform(X)
array([[-1., 1.],
       [ 1., -1.]]
```

Sometimes, you want to apply different transformations to different features: the ColumnTransformer is designed for these use-cases.

3.3 Pipelines: chaining pre-processors and estimators

Transformers and estimators (predictors) can be combined together into a single unifying object: a Pipeline. The pipeline offers the same API as a regular estimator: it can be fitted and used for prediction with fit and predict. As we will see later, using a pipeline will also prevent you from data leakage, i.e. disclosing some testing data in your training data.

In the following example, we load the Iris dataset, split it into train and test sets, and compute the accuracy score of a pipeline on the test data:

```python
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.metrics import accuracy_score
...
>>> # create a pipeline object
>>> pipe = make_pipeline(
...     StandardScaler(),
...     LogisticRegression()
... )
...
>>> # load the iris dataset and split it into train and test sets
>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
...
>>> # fit the whole pipeline
>>> pipe.fit(X_train, y_train)
Pipeline(steps=[('standardscaler', StandardScaler()),
               ('logisticregression', LogisticRegression())])
>>> # we can now use it like any other estimator
>>> accuracy_score(pipe.predict(X_test), y_test)
0.97...
```
3.4 Model evaluation

Fitting a model to some data does not entail that it will predict well on unseen data. This needs to be directly evaluated. We have just seen the `train_test_split` helper that splits a dataset into train and test sets, but `scikit-learn` provides many other tools for model evaluation, in particular for cross-validation.

We here briefly show how to perform a 5-fold cross-validation procedure, using the `cross_validate` helper. Note that it is also possible to manually iterate over the folds, use different data splitting strategies, and use custom scoring functions. Please refer to our User Guide for more details:

```python
>>> from sklearn.datasets import make_regression
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.model_selection import cross_validate
...
>>> X, y = make_regression(n_samples=1000, random_state=0)
>>> lr = LinearRegression()
...
>>> result = cross_validate(lr, X, y)  # defaults to 5-fold CV
>>> result['test_score']  # r_squared score is high because dataset is easy
array([1., 1., 1., 1., 1.])
```

3.5 Automatic parameter searches

All estimators have parameters (often called hyper-parameters in the literature) that can be tuned. The generalization power of an estimator often critically depends on a few parameters. For example a `RandomForestRegressor` has a `n_estimators` parameter that determines the number of trees in the forest, and a `max_depth` parameter that determines the maximum depth of each tree. Quite often, it is not clear what the exact values of these parameters should be since they depend on the data at hand.

`Scikit-learn` provides tools to automatically find the best parameter combinations (via cross-validation). In the following example, we randomly search over the parameter space of a random forest with a `RandomizedSearchCV` object. When the search is over, the `RandomizedSearchCV` behaves as a `RandomForestRegressor` that has been fitted with the best set of parameters. Read more in the User Guide:

```python
>>> from sklearn.datasets import fetch_california_housing
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.model_selection import RandomizedSearchCV
>>> from sklearn.model_selection import train_test_split
>>> from scipy.stats import randint
...
>>> X, y = fetch_california_housing(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
...
>>> # define the parameter space that will be searched over
>>> param_distributions = {'n_estimators': randint(1, 5),
                          'max_depth': randint(5, 10)}
...
>>> # now create a searchCV object and fit it to the data
>>> search = RandomizedSearchCV(estimator=RandomForestRegressor(random_state=0),
                               n_iter=5,
                               param_distributions=param_distributions,
                               random_state=0)
>>> search.fit(X_train, y_train)
```
param_distributions={"max_depth": ...,  
                      "n_estimators": ...},
                      random_state=0)

>>> search.best_params_
{'max_depth': 9, 'n_estimators': 4}

>>> # the search object now acts like a normal random forest estimator  
>>> # with max_depth=9 and n_estimators=4

>>> search.score(X_test, y_test)

0.73...

Note: In practice, you almost always want to *search over a pipeline*, instead of a single estimator. One of the main reasons is that if you apply a pre-processing step to the whole dataset without using a pipeline, and then perform any kind of cross-validation, you would be breaking the fundamental assumption of independence between training and testing data. Indeed, since you pre-processed the data using the whole dataset, some information about the test sets are available to the train sets. This will lead to over-estimating the generalization power of the estimator (you can read more in this Kaggle post).

Using a pipeline for cross-validation and searching will largely keep you from this common pitfall.

3.6 Next steps

We have briefly covered estimator fitting and predicting, pre-processing steps, pipelines, cross-validation tools and automatic hyper-parameter searches. This guide should give you an overview of some of the main features of the library, but there is much more to scikit-learn!

Please refer to our *User Guide* for details on all the tools that we provide. You can also find an exhaustive list of the public API in the *API Reference*.

You can also look at our numerous *examples* that illustrate the use of *scikit-learn* in many different contexts.

The *tutorials* also contain additional learning resources.
4.1 Supervised learning

4.1.1 Linear Models

The following are a set of methods intended for regression in which the target value is expected to be a linear combination of the features. In mathematical notation, if $\hat{y}$ is the predicted value.

$$
\hat{y}(w, x) = w_0 + w_1 x_1 + \ldots + w_p x_p
$$

Across the module, we designate the vector $w = (w_1, \ldots, w_p)$ as coef_ and $w_0$ as intercept_.

To perform classification with generalized linear models, see *Logistic regression*.

Ordinary Least Squares

*LinearRegression* fits a linear model with coefficients $w = (w_1, \ldots, w_p)$ to minimize the residual sum of squares between the observed targets in the dataset, and the targets predicted by the linear approximation. Mathematically it solves a problem of the form:

$$\min_w \|Xw - \tilde{y}\|^2_2$$

*LinearRegression* will take in its fit method arrays X, y and will store the coefficients $w$ of the linear model in its coef_ member.
The coefficient estimates for Ordinary Least Squares rely on the independence of the features. When features are correlated and the columns of the design matrix \(X\) have an approximate linear dependence, the design matrix becomes close to singular and as a result, the least-squares estimate becomes highly sensitive to random errors in the observed target, producing a large variance. This situation of \textit{multicollinearity} can arise, for example, when data are collected without an experimental design.

### Examples:
- \textit{Linear Regression Example}

### Non-Negative Least Squares

It is possible to constrain all the coefficients to be non-negative, which may be useful when they represent some physical or naturally non-negative quantities (e.g., frequency counts or prices of goods). \textit{LinearRegression} accepts a boolean \texttt{positive} parameter: when set to \texttt{True} \textit{Non Negative Least Squares} are then applied.

### Examples:
- \textit{Non-negative least squares}

### Ordinary Least Squares Complexity

The least squares solution is computed using the singular value decomposition of \(X\). If \(X\) is a matrix of shape \((n\text{ samples}, n\text{ features})\) this method has a cost of \(O(n\text{ samples} n^2\text{ features})\), assuming that \(n\text{ samples} \geq n\text{ features}\).

### Ridge regression and classification

#### Regression

\textit{Ridge} regression addresses some of the problems of \textit{Ordinary Least Squares} by imposing a penalty on the size of the coefficients. The ridge coefficients minimize a penalized residual sum of squares:

\[
\min_w \|Xw - y\|^2_2 + \alpha \|w\|^2_2
\]

The complexity parameter \(\alpha \geq 0\) controls the amount of shrinkage: the larger the value of \(\alpha\), the greater the amount of shrinkage and thus the coefficients become more robust to collinearity.

As with other linear models, \textit{Ridge} will take in its \texttt{fit} method arrays \(X, y\) and will store the coefficients \(w\) of the linear model in its \texttt{coef_} member:
>>> from sklearn import linear_model
>>> reg = linear_model.Ridge(alpha=.5)
>>> reg.fit([[0, 0], [0, 0], [1, 1]], [0, .1, 1])
Ridge(alpha=0.5)
>>> reg.coef_
array([0.34545455, 0.34545455])
>>> reg.intercept_
0.13636...

Classification

The Ridge regressor has a classifier variant: RidgeClassifier. This classifier first converts binary targets to \((-1, 1)\) and then treats the problem as a regression task, optimizing the same objective as above. The predicted class corresponds to the sign of the regressor’s prediction. For multiclass classification, the problem is treated as multi-output regression, and the predicted class corresponds to the output with the highest value.

It might seem questionable to use a (penalized) Least Squares loss to fit a classification model instead of the more traditional logistic or hinge losses. However in practice all those models can lead to similar cross-validation scores in terms of accuracy or precision/recall, while the penalized least squares loss used by the RidgeClassifier allows for a very different choice of the numerical solvers with distinct computational performance profiles.

The RidgeClassifier can be significantly faster than e.g. LogisticRegression with a high number of classes, because it is able to compute the projection matrix \((X^T X)^{-1}X^T\) only once.

This classifier is sometimes referred to as a Least Squares Support Vector Machines with a linear kernel.

Examples:

- Plot Ridge coefficients as a function of the regularization
- Classification of text documents using sparse features
- Common pitfalls in interpretation of coefficients of linear models
Ridge Complexity

This method has the same order of complexity as Ordinary Least Squares.

Setting the regularization parameter: leave-one-out Cross-Validation

*RidgeCV* implements ridge regression with built-in cross-validation of the alpha parameter. The object works in the same way as GridSearchCV except that it defaults to Leave-One-Out Cross-Validation:

```python
>>> import numpy as np
>>> from sklearn import linear_model

reg = linear_model.RidgeCV(alphas=np.logspace(-6, 6, 13))
reg.fit([[0, 0], [0, 0], [1, 1]], [0, .1, 1])
RidgeCV(alphas=array([1.e-06, 1.e-05, 1.e-04, 1.e-03, 1.e-02, 1.e-01, 1.e+00, 1.e+01,
                      1.e+02, 1.e+03, 1.e+04, 1.e+05, 1.e+06]))
reg.alpha_
0.01
```

Specifying the value of the `cv` attribute will trigger the use of cross-validation with GridSearchCV, for example `cv=10` for 10-fold cross-validation, rather than Leave-One-Out Cross-Validation.

References

- “Notes on Regularized Least Squares”, Rifkin & Lippert (technical report, course slides).

Lasso

The *Lasso* is a linear model that estimates sparse coefficients. It is useful in some contexts due to its tendency to prefer solutions with fewer non-zero coefficients, effectively reducing the number of features upon which the given solution is dependent. For this reason Lasso and its variants are fundamental to the field of compressed sensing. Under certain conditions, it can recover the exact set of non-zero coefficients (see Compressive sensing: tomography reconstruction with L1 prior (Lasso)).

Mathematically, it consists of a linear model with an added regularization term. The objective function to minimize is:

\[
\min_w \frac{1}{2n_{\text{samples}}} \|Xw - y\|^2_2 + \alpha \|w\|_1
\]

The lasso estimate thus solves the minimization of the least-squares penalty with \(\alpha \|w\|_1\) added, where \(\alpha\) is a constant and \(\|w\|_1\) is the \(\ell_1\)-norm of the coefficient vector.

The implementation in the class *Lasso* uses coordinate descent as the algorithm to fit the coefficients. See Least Angle Regression for another implementation:

```python
>>> from sklearn import linear_model
>>> reg = linear_model.Lasso(alpha=0.1)
>>> reg.fit([[0, 0], [1, 1]], [0, 1])
Lasso(alpha=0.1)
>>> reg.predict([[1, 1]])
array([0.8])
```

The function *lasso_path* is useful for lower-level tasks, as it computes the coefficients along the full path of possible values.
Examples:

- *Lasso and Elastic Net for Sparse Signals*
- *Compressive sensing: tomography reconstruction with L1 prior (Lasso)*
- *Common pitfalls in interpretation of coefficients of linear models*

**Note: Feature selection with Lasso**

As the Lasso regression yields sparse models, it can thus be used to perform feature selection, as detailed in *L1-based feature selection*.

The following two references explain the iterations used in the coordinate descent solver of scikit-learn, as well as the duality gap computation used for convergence control.

**References**


**Setting regularization parameter**

The `alpha` parameter controls the degree of sparsity of the estimated coefficients.

**Using cross-validation**

scikit-learn exposes objects that set the Lasso `alpha` parameter by cross-validation: `LassoCV` and `LassoLarsCV`. `LassoLarsCV` is based on the *Least Angle Regression* algorithm explained below.

For high-dimensional datasets with many collinear features, `LassoCV` is most often preferable. However, `LassoLarsCV` has the advantage of exploring more relevant values of `alpha` parameter, and if the number of samples is very small compared to the number of features, it is often faster than `LassoCV`. 
Information-criteria based model selection

Alternatively, the estimator `LassoLarsIC` proposes to use the Akaike information criterion (AIC) and the Bayes Information criterion (BIC). It is a computationally cheaper alternative to find the optimal value of alpha as the regularization path is computed only once instead of k+1 times when using k-fold cross-validation. However, such criteria needs a proper estimation of the degrees of freedom of the solution, are derived for large samples (asymptotic results) and assume the model is correct, i.e. that the data are actually generated by this model. They also tend to break when the problem is badly conditioned (more features than samples).

Examples:

- **Lasso model selection: Cross-Validation / AIC / BIC**
Comparison with the regularization parameter of SVM

The equivalence between alpha and the regularization parameter of SVM, \( C \) is given by \( \alpha = 1 / C \) or \( \alpha = 1 / (n_{\text{samples}} * C) \), depending on the estimator and the exact objective function optimized by the model.

**Multi-task Lasso**

The `MultiTaskLasso` is a linear model that estimates sparse coefficients for multiple regression problems jointly: \( y \) is a 2D array, of shape \( (n_{\text{samples}}, n_{\text{tasks}}) \). The constraint is that the selected features are the same for all the regression problems, also called tasks.

The following figure compares the location of the non-zero entries in the coefficient matrix \( W \) obtained with a simple Lasso or a MultiTaskLasso. The Lasso estimates yield scattered non-zeros while the non-zeros of the MultiTaskLasso are full columns.

Fitting a time-series model, imposing that any active feature be active at all times.

**Examples:**

- *Joint feature selection with multi-task Lasso*

Mathematically, it consists of a linear model trained with a mixed \( \ell_1 \ \ell_2 \)-norm for regularization. The objective function
to minimize is:
\[
\min_W \frac{1}{2n_{\text{samples}}} \|XW - Y\|^2_{\text{Fro}} + \alpha \|W\|_1
\]
where Fro indicates the Frobenius norm
\[
\|A\|_{\text{Fro}} = \sqrt{\sum_{ij} a_{ij}^2}
\]
and \(\ell_1 \ell_2\) reads
\[
\|A\|_2 = \sum_i \sqrt{\sum_j a_{ij}^2}.
\]
The implementation in the class `MultiTaskLasso` uses coordinate descent as the algorithm to fit the coefficients.

**Elastic-Net**

`ElasticNet` is a linear regression model trained with both \(\ell_1\) and \(\ell_2\)-norm regularization of the coefficients. This combination allows for learning a sparse model where few of the weights are non-zero like Lasso, while still maintaining the regularization properties of Ridge. We control the convex combination of \(\ell_1\) and \(\ell_2\) using the `l1_ratio` parameter.

Elastic-net is useful when there are multiple features which are correlated with one another. Lasso is likely to pick one of these at random, while elastic-net is likely to pick both.

A practical advantage of trading-off between Lasso and Ridge is that it allows Elastic-Net to inherit some of Ridge’s stability under rotation.

The objective function to minimize is in this case
\[
\min_w \frac{1}{2n_{\text{samples}}} \|Xw - y\|^2_2 + \alpha \rho \|w\|_1 + \frac{\alpha(1 - \rho)}{2} \|w\|_2^2
\]
The class `ElasticNetCV` can be used to set the parameters `alpha` (\(\alpha\)) and `l1_ratio` (\(\rho\)) by cross-validation.
Examples:

- Lasso and Elastic Net for Sparse Signals
- Lasso and Elastic Net

The following two references explain the iterations used in the coordinate descent solver of scikit-learn, as well as the duality gap computation used for convergence control.

References


Multi-task Elastic-Net

The `MultiTaskElasticNet` is an elastic-net model that estimates sparse coefficients for multiple regression problems jointly: \( Y \) is a 2D array of shape \((n_{\text{samples}}, n_{\text{tasks}})\). The constraint is that the selected features are the same for all the regression problems, also called tasks.

Mathematically, it consists of a linear model trained with a mixed \( \ell_1 \ell_2\)-norm and \( \ell_2\)-norm for regularization. The objective function to minimize is:

\[
\min_W \frac{1}{2n_{\text{samples}}} \|XW - Y\|_F^2 + \alpha \rho \|W\|_{21} + \frac{\alpha(1 - \rho)}{2} \|W\|_F^2
\]

The implementation in the class `MultiTaskElasticNet` uses coordinate descent as the algorithm to fit the coefficients.

The class `MultiTaskElasticNetCV` can be used to set the parameters `alpha` (\(\alpha\)) and `l1_ratio` (\(\rho\)) by cross-validation.

Least Angle Regression

Least-angle regression (LARS) is a regression algorithm for high-dimensional data, developed by Bradley Efron, Trevor Hastie, Iain Johnstone and Robert Tibshirani. LARS is similar to forward stepwise regression. At each step, it finds the feature most correlated with the target. When there are multiple features having equal correlation, instead of continuing along the same feature, it proceeds in a direction equiangular between the features.

The advantages of LARS are:

- It is numerically efficient in contexts where the number of features is significantly greater than the number of samples.
- It is computationally just as fast as forward selection and has the same order of complexity as ordinary least squares.
- It produces a full piecewise linear solution path, which is useful in cross-validation or similar attempts to tune the model.
- If two features are almost equally correlated with the target, then their coefficients should increase at approximately the same rate. The algorithm thus behaves as intuition would expect, and also is more stable.
• It is easily modified to produce solutions for other estimators, like the Lasso.

The disadvantages of the LARS method include:

• Because LARS is based upon an iterative refitting of the residuals, it would appear to be especially sensitive to
the effects of noise. This problem is discussed in detail by Weisberg in the discussion section of the Efron et al. (2004) Annals of Statistics article.

The LARS model can be used using estimator `Lars`, or its low-level implementation `lars_path` or `lars_path_gram`.

### LARS Lasso

`LassoLars` is a lasso model implemented using the LARS algorithm, and unlike the implementation based on coordinate descent, this yields the exact solution, which is piecewise linear as a function of the norm of its coefficients.

```python
>>> from sklearn import linear_model
>>> reg = linear_model.LassoLars(alpha=.1)
>>> reg.fit([[0, 0], [1, 1]], [0, 1])
LassoLars(alpha=0.1)
>>> reg.coef_
array([0.717157..., 0.])
```

**Examples:**

• **Lasso path using LARS**

The Lars algorithm provides the full path of the coefficients along the regularization parameter almost for free, thus a common operation is to retrieve the path with one of the functions `lars_path` or `lars_path_gram`.
Mathematical formulation

The algorithm is similar to forward stepwise regression, but instead of including features at each step, the estimated coefficients are increased in a direction equiangular to each one’s correlations with the residual.

Instead of giving a vector result, the LARS solution consists of a curve denoting the solution for each value of the $\ell_1$ norm of the parameter vector. The full coefficients path is stored in the array `coef_path_`, which has size $(n\_features, \text{max\_features}+1)$. The first column is always zero.

References:

- Original Algorithm is detailed in the paper *Least Angle Regression* by Hastie et al.

Orthogonal Matching Pursuit (OMP)

`OrthogonalMatchingPursuit` and `orthogonal_mp` implements the OMP algorithm for approximating the fit of a linear model with constraints imposed on the number of non-zero coefficients (i.e. the $\ell_0$ pseudo-norm).

Being a forward feature selection method like *Least Angle Regression*, orthogonal matching pursuit can approximate the optimum solution vector with a fixed number of non-zero elements:

$$
\arg \min_w ||y - Xw||_2^2 \text{ subject to } ||w||_0 \leq n_{\text{nonzero\_coeffs}}
$$

Alternatively, orthogonal matching pursuit can target a specific error instead of a specific number of non-zero coefficients. This can be expressed as:

$$
\arg \min_w ||w||_0 \text{ subject to } ||y - Xw||_2^2 \leq \text{tol}
$$

OMP is based on a greedy algorithm that includes at each step the atom most highly correlated with the current residual. It is similar to the simpler matching pursuit (MP) method, but better in that at each iteration, the residual is recomputed using an orthogonal projection on the space of the previously chosen dictionary elements.

Examples:

- *Orthogonal Matching Pursuit*

References:

Bayesian Regression

Bayesian regression techniques can be used to include regularization parameters in the estimation procedure: the regularization parameter is not set in a hard sense but tuned to the data at hand.

This can be done by introducing uninformative priors over the hyper parameters of the model. The $\ell_2$ regularization used in Ridge regression and classification is equivalent to finding a maximum a posteriori estimation under a Gaussian prior over the coefficients $w$ with precision $\lambda^{-1}$. Instead of setting lambda manually, it is possible to treat it as a random variable to be estimated from the data.

To obtain a fully probabilistic model, the output $y$ is assumed to be Gaussian distributed around $Xw$:

$$p(y|X,w,\alpha) = \mathcal{N}(y|Xw,\alpha)$$

where $\alpha$ is again treated as a random variable that is to be estimated from the data.

The advantages of Bayesian Regression are:

- It adapts to the data at hand.
- It can be used to include regularization parameters in the estimation procedure.

The disadvantages of Bayesian regression include:

- Inference of the model can be time consuming.

References

- A good introduction to Bayesian methods is given in C. Bishop: Pattern Recognition and Machine learning
- Original Algorithm is detailed in the book Bayesian learning for neural networks by Radford M. Neal

Bayesian Ridge Regression

$\texttt{BayesianRidge}$ estimates a probabilistic model of the regression problem as described above. The prior for the coefficient $w$ is given by a spherical Gaussian:

$$p(w|\lambda) = \mathcal{N}(w|0,\lambda^{-1}I_p)$$

The priors over $\alpha$ and $\lambda$ are chosen to be gamma distributions, the conjugate prior for the precision of the Gaussian. The resulting model is called Bayesian Ridge Regression, and is similar to the classical Ridge.

The parameters $w$, $\alpha$ and $\lambda$ are estimated jointly during the fit of the model, the regularization parameters $\alpha$ and $\lambda$ being estimated by maximizing the log marginal likelihood. The scikit-learn implementation is based on the algorithm described in Appendix A of (Tipping, 2001) where the update of the parameters $\alpha$ and $\lambda$ is done as suggested in (MacKay, 1992). The initial value of the maximization procedure can be set with the hyperparameters $\texttt{alpha_init}$ and $\texttt{lambda_init}$.

There are four more hyperparameters, $\alpha_1$, $\alpha_2$, $\lambda_1$ and $\lambda_2$ of the gamma prior distributions over $\alpha$ and $\lambda$. These are usually chosen to be non-informative. By default $\alpha_1 = \alpha_2 = \lambda_1 = \lambda_2 = 10^{-6}$.

Bayesian Ridge Regression is used for regression:

```python
>>> from sklearn import linear_model
>>> X = [[0., 0.], [1., 1.], [2., 2.], [3., 3.]]
>>> Y = [0., 1., 2., 3.]
```
>>> reg = linear_model.BayesianRidge()
>>> reg.fit(X, Y)
BayesianRidge()

After being fitted, the model can then be used to predict new values:

>>> reg.predict([[1, 0.]])
array([0.50000013])

The coefficients \( w \) of the model can be accessed:

>>> reg.coef_
array([0.49999993, 0.49999993])

Due to the Bayesian framework, the weights found are slightly different to the ones found by Ordinary Least Squares. However, Bayesian Ridge Regression is more robust to ill-posed problems.

**Examples:**

- Bayesian Ridge Regression
- Curve Fitting with Bayesian Ridge Regression

**References:**

- Section 3.3 in Christopher M. Bishop: Pattern Recognition and Machine Learning, 2006
Automatic Relevance Determination - ARD

ARDRegression is very similar to Bayesian Ridge Regression, but can lead to sparser coefficients \( w^1 \). ARDRegression poses a different prior over \( w \), by dropping the assumption of the Gaussian being spherical. Instead, the distribution over \( w \) is assumed to be an axis-parallel, elliptical Gaussian distribution.

This means each coefficient \( w_i \) is drawn from a Gaussian distribution, centered on zero and with a precision \( \lambda_i \):

\[
p(w|\lambda) = \mathcal{N}(w|0, A^{-1})
\]

with \( \text{diag}(A) = \lambda = \{\lambda_1, ..., \lambda_p\} \).

In contrast to Bayesian Ridge Regression, each coordinate of \( w_i \) has its own standard deviation \( \lambda_i \). The prior over all \( \lambda_i \) is chosen to be the same gamma distribution given by hyperparameters \( \lambda_1 \) and \( \lambda_2 \).

ARD is also known in the literature as Sparse Bayesian Learning and Relevance Vector Machine\(^4\).

**Examples:**

- **Automatic Relevance Determination Regression (ARD)**

---

1. Christopher M. Bishop: Pattern Recognition and Machine Learning, Chapter 7.2.1
2. David Wipf and Srikantan Nagarajan: A new view of automatic relevance determination
3. Michael E. Tipping: Sparse Bayesian Learning and the Relevance Vector Machine
4. Tristan Fletcher: Relevance Vector Machines explained
Logistic regression

Logistic regression, despite its name, is a linear model for classification rather than regression. Logistic regression is also known in the literature as logit regression, maximum-entropy classification (MaxEnt) or the log-linear classifier. In this model, the probabilities describing the possible outcomes of a single trial are modeled using a logistic function.

Logistic regression is implemented in `LogisticRegression`. This implementation can fit binary, One-vs-Rest, or multinomial logistic regression with optional $\ell_1$, $\ell_2$ or Elastic-Net regularization.

Note: Regularization is applied by default, which is common in machine learning but not in statistics. Another advantage of regularization is that it improves numerical stability. No regularization amounts to setting $C$ to a very high value.

As an optimization problem, binary class $\ell_2$ penalized logistic regression minimizes the following cost function:

$$
\min_{\mathbf{w}, c} \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^{n} \log(\exp(-y_i(X_i^T \mathbf{w} + c)) + 1).
$$

Similarly, $\ell_1$ regularized logistic regression solves the following optimization problem:

$$
\min_{\mathbf{w}, c} \|\mathbf{w}\|_1 + C \sum_{i=1}^{n} \log(\exp(-y_i(X_i^T \mathbf{w} + c)) + 1).
$$

Elastic-Net regularization is a combination of $\ell_1$ and $\ell_2$, and minimizes the following cost function:

$$
\min_{\mathbf{w}, c} \frac{1 - \rho}{2} \mathbf{w}^T \mathbf{w} + \rho \|\mathbf{w}\|_1 + C \sum_{i=1}^{n} \log(\exp(-y_i(X_i^T \mathbf{w} + c)) + 1),
$$

where $\rho$ controls the strength of $\ell_1$ regularization vs. $\ell_2$ regularization (it corresponds to the `l1_ratio` parameter).

Note that, in this notation, it’s assumed that the target $y_i$ takes values in the set $-1, 1$ at trial $i$. We can also see that Elastic-Net is equivalent to $\ell_1$ when $\rho = 1$ and equivalent to $\ell_2$ when $\rho = 0$.

The solvers implemented in the class `LogisticRegression` are “liblinear”, “newton-cg”, “lbfgs”, “sag” and “saga”:

The solver “liblinear” uses a coordinate descent (CD) algorithm, and relies on the excellent C++ LIBLINEAR library, which is shipped with scikit-learn. However, the CD algorithm implemented in liblinear cannot learn a true multinomial (multiclass) model; instead, the optimization problem is decomposed in a “one-vs-rest” fashion so separate binary classifiers are trained for all classes. This happens under the hood, so `LogisticRegression` instances using this solver behave as multiclass classifiers. For $\ell_1$ regularization `sklearn.svm.l1_min_c` allows to calculate the lower bound for $C$ in order to get a non “null” (all feature weights to zero) model.

The “lbfgs”, “sag” and “newton-cg” solvers only support $\ell_2$ regularization or no regularization, and are found to converge faster for some high-dimensional data. Setting `multi_class` to “multinomial” with these solvers learns a true multinomial logistic regression model\(^5\), which means that its probability estimates should be better calibrated than the default “one-vs-rest” setting.

\(^5\) Christopher M. Bishop: Pattern Recognition and Machine Learning, Chapter 4.3.4

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The “sag” solver uses Stochastic Average Gradient descent\(^6\). It is faster than other solvers for large datasets, when both the number of samples and the number of features are large.

The “saga” solver\(^7\) is a variant of “sag” that also supports the non-smooth penalty="l1". This is therefore the solver of choice for sparse multinomial logistic regression. It is also the only solver that supports penalty="elasticnet".

The “lbfgs” is an optimization algorithm that approximates the Broyden–Fletcher–Goldfarb–Shanno algorithm\(^8\), which belongs to quasi-Newton methods. The “lbfgs” solver is recommended for use for small data-sets but for larger datasets its performance suffers.\(^9\)

The following table summarizes the penalties supported by each solver:

<table>
<thead>
<tr>
<th>Penalties</th>
<th>‘liblinear’</th>
<th>‘lbfgs’</th>
<th>‘newton-cg’</th>
<th>‘sag’</th>
<th>‘saga’</th>
</tr>
</thead>
<tbody>
<tr>
<td>Multinomial + L2 penalty</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>OVR + L2 penalty</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>Multinomial + L1 penalty</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
</tr>
<tr>
<td>OVR + L1 penalty</td>
<td>yes</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
</tr>
<tr>
<td>Elastic-Net</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
</tr>
<tr>
<td>No penalty (‘none’)</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Behaviors</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Penalize the intercept (bad)</td>
<td>yes</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
</tr>
<tr>
<td>Faster for large datasets</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>Robust to unscaled datasets</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
<td>no</td>
</tr>
</tbody>
</table>

The “lbfgs” solver is used by default for its robustness. For large datasets the “saga” solver is usually faster. For large dataset, you may also consider using SGDClassifier with ‘log’ loss, which might be even faster but requires more tuning.

**Examples:**

- L1 Penalty and Sparsity in Logistic Regression
- Regularization path of L1- Logistic Regression
- Plot multinomial and One-vs-Rest Logistic Regression
- Multiclass sparse logistic regression on 20newsgroups
- MNIST classification using multinomial logistic + L1

**Differences from liblinear:**

There might be a difference in the scores obtained between LogisticRegression with solver=liblinear or LinearSVC and the external liblinear library directly, when fit_intercept=False and the fit coef_ (or) the data to be predicted are zeroes. This is because for the sample(s) with decision_function zero, LogisticRegression and LinearSVC predict the negative class, while liblinear predicts the positive class. Note that a model with fit_intercept=False and having many samples with decision_function zero,

---

\(^6\) Mark Schmidt, Nicolas Le Roux, and Francis Bach: Minimizing Finite Sums with the Stochastic Average Gradient.

\(^7\) Aaron Defazio, Francis Bach, Simon Lacoste-Julien: SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives.

\(^8\) https://en.wikipedia.org/wiki/Broyden%E2%80%93Fletcher%E2%80%93Goldfarb%E2%80%93Shanno_algorithm

\(^9\) “Performance Evaluation of Lbfgs vs other solvers”
is likely to be a underfit, bad model and you are advised to set fit_intercept=True and increase the intercept_scaling.

**Note: Feature selection with sparse logistic regression**

A logistic regression with $\ell_1$ penalty yields sparse models, and can thus be used to perform feature selection, as detailed in *L1-based feature selection*.

**Note: P-value estimation**

It is possible to obtain the p-values and confidence intervals for coefficients in cases of regression without penalization. The statsmodels package <https://pypi.org/project/statsmodels/> natively supports this. Within sklearn, one could use bootstrapping instead as well.

LogisticRegressionCV implements Logistic Regression with built-in cross-validation support, to find the optimal $C$ and $l1\_ratio$ parameters according to the scoring attribute. The "newton-cg", "sag", "saga" and "lbfgs" solvers are found to be faster for high-dimensional dense data, due to warm-starting (see Glossary).

### References:

#### Generalized Linear Regression

Generalized Linear Models (GLM) extend linear models in two ways\(^{10}\). First, the predicted values $\hat{y}$ are linked to a linear combination of the input variables $X$ via an inverse link function $h$ as

$$\hat{y}(w, X) = h(Xw).$$

Secondly, the squared loss function is replaced by the unit deviance $d$ of a distribution in the exponential family (or more precisely, a reproductive exponential dispersion model (EDM))\(^{11}\).

The minimization problem becomes:

$$\min_w \frac{1}{2n\text{samples}} \sum_i d(y_i, \hat{y}_i) + \frac{\alpha}{2} ||w||^2,$$

where $\alpha$ is the L2 regularization penalty. When sample weights are provided, the average becomes a weighted average. The following table lists some specific EDMs and their unit deviance (all of these are instances of the Tweedie family):

<table>
<thead>
<tr>
<th>Distribution</th>
<th>Target Domain</th>
<th>Unit Deviance $d(y, \hat{y})$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Normal</td>
<td>$y \in (-\infty, \infty)$</td>
<td>$(y - \hat{y})^2$</td>
</tr>
<tr>
<td>Poisson</td>
<td>$y \in (0, \infty)$</td>
<td>$2(\log \frac{y}{\hat{y}} - y + \hat{y})$</td>
</tr>
<tr>
<td>Gamma</td>
<td>$y \in (0, \infty)$</td>
<td>$2(\log \frac{\hat{y}}{y} + \frac{\hat{y}}{y} - 1)$</td>
</tr>
<tr>
<td>Inverse Gaussian</td>
<td>$y \in (0, \infty)$</td>
<td>$\frac{(y - \hat{y})^2}{y\hat{y}}$</td>
</tr>
</tbody>
</table>

The Probability Density Functions (PDF) of these distributions are illustrated in the following figure,

---


\(^{11}\) Jørgensen, B. (1992). The theory of exponential dispersion models and analysis of deviance. Monografias de matemática, no. 51. See also Exponential dispersion model.

---

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The choice of the distribution depends on the problem at hand:

- If the target values \( y \) are counts (non-negative integer valued) or relative frequencies (non-negative), you might use a Poisson deviance with log-link.
- If the target values are positive valued and skewed, you might try a Gamma deviance with log-link.
- If the target values seem to be heavier tailed than a Gamma distribution, you might try an Inverse Gaussian deviance (or even higher variance powers of the Tweedie family).

Examples of use cases include:

- Agriculture / weather modeling: number of rain events per year (Poisson), amount of rainfall per event (Gamma), total rainfall per year (Tweedie / Compound Poisson Gamma).
- Risk modeling / insurance policy pricing: number of claim events / policyholder per year (Poisson), cost per event (Gamma), total cost per policyholder per year (Tweedie / Compound Poisson Gamma).
- Predictive maintenance: number of production interruption events per year (Poisson), duration of interruption (Gamma), total interruption time per year (Tweedie / Compound Poisson Gamma).

References:

Usage

TweedieRegressor implements a generalized linear model for the Tweedie distribution, that allows to model any of the above mentioned distributions using the appropriate power parameter. In particular:

- power = 0: Normal distribution. Specific estimators such as Ridge, ElasticNet are generally more appropriate in this case.
- power = 1: Poisson distribution. PoissonRegressor is exposed for convenience. However, it is strictly equivalent to TweedieRegressor(power=1, link='log').
- power = 2: Gamma distribution. GammaRegressor is exposed for convenience. However, it is strictly equivalent to TweedieRegressor(power=2, link='log').
- power = 3: Inverse Gaussian distribution.
The link function is determined by the `link` parameter.

Usage example:

```python
>>> from sklearn.linear_model import TweedieRegressor

>>> reg = TweedieRegressor(power=1, alpha=0.5, link='log')

>>> reg.fit([[0, 0], [0, 1], [2, 2]], [0, 1, 2])

TweedieRegressor(alpha=0.5, link='log', power=1)

>>> reg.coef_
array([0.2463..., 0.4337...])

>>> reg.intercept_
-0.7638...
```

Examples:

- Poisson regression and non-normal loss
- Tweedie regression on insurance claims

Practical considerations

The feature matrix \(X\) should be standardized before fitting. This ensures that the penalty treats features equally.

Since the linear predictor \(Xw\) can be negative and Poisson, Gamma and Inverse Gaussian distributions don’t support negative values, it is necessary to apply an inverse link function that guarantees the non-negativeness. For example with `link='log'`, the inverse link function becomes \(h(Xw) = \exp(Xw)\).

If you want to model a relative frequency, i.e. counts per exposure (time, volume, ...) you can do so by using a Poisson distribution and passing \(y = \frac{\text{counts}}{\text{exposure}}\) as target values together with exposure as sample weights. For a concrete example see e.g. Tweedie regression on insurance claims.

When performing cross-validation for the `power` parameter of `TweedieRegressor`, it is advisable to specify an explicit `scoring` function, because the default `scorer` `TweedieRegressor.score` is a function of `power` itself.

Stochastic Gradient Descent - SGD

Stochastic gradient descent is a simple yet very efficient approach to fit linear models. It is particularly useful when the number of samples (and the number of features) is very large. The `partial_fit` method allows online/out-of-core learning.

The classes `SGDClassifier` and `SGDRegressor` provide functionality to fit linear models for classification and regression using different (convex) loss functions and different penalties. E.g., with `loss="log"`, `SGDClassifier` fits a logistic regression model, while with `loss="hinge"` it fits a linear support vector machine (SVM).

References

- Stochastic Gradient Descent
Perceptron

The Perceptron is another simple classification algorithm suitable for large scale learning. By default:

- It does not require a learning rate.
- It is not regularized (penalized).
- It updates its model only on mistakes.

The last characteristic implies that the Perceptron is slightly faster to train than SGD with the hinge loss and that the resulting models are sparser.

Passive Aggressive Algorithms

The passive-aggressive algorithms are a family of algorithms for large-scale learning. They are similar to the Perceptron in that they do not require a learning rate. However, contrary to the Perceptron, they include a regularization parameter $C$.

For classification, PassiveAggressiveClassifier can be used with loss='hinge' (PA-I) or loss='squared_hinge' (PA-II). For regression, PassiveAggressiveRegressor can be used with loss='epsilon_insensitive' (PA-I) or loss='squared_epsilon_insensitive' (PA-II).

References:


Robustness regression: outliers and modeling errors

Robust regression aims to fit a regression model in the presence of corrupt data: either outliers, or error in the model.
Different scenario and useful concepts

There are different things to keep in mind when dealing with data corrupted by outliers:

- **Outliers in X or in y?**

  - **Outliers in the y direction**

    ![Outliers in the y direction graph]

    - **Outliers in the X direction**

    ![Outliers in the X direction graph]

- **Fraction of outliers versus amplitude of error**

  The number of outlying points matters, but also how much they are outliers.

  ![Small outliers graph]

  ![Large outliers graph]

  An important notion of robust fitting is that of breakdown point: the fraction of data that can be outlying for the fit to start missing the inlying data.

  Note that in general, robust fitting in high-dimensional setting (large \( n_{\text{features}} \)) is very hard. The robust models here will probably not work in these settings.

Trade-offs: which estimator?

Scikit-learn provides 3 robust regression estimators: **RANSAC**, **Theil Sen** and **HuberRegressor**.
HuberRegressor should be faster than RANSAC and Theil Sen unless the number of samples are very large, i.e. \( n_{\text{samples}} \gg n_{\text{features}} \). This is because RANSAC and Theil Sen fit on smaller subsets of the data. However, both Theil Sen and RANSAC are unlikely to be as robust as HuberRegressor for the default parameters.

- **RANSAC** is faster than Theil Sen and scales much better with the number of samples.
- **RANSAC** will deal better with large outliers in the y direction (most common situation).
- **Theil Sen** will cope better with medium-size outliers in the X direction, but this property will disappear in high-dimensional settings.

When in doubt, use RANSAC.

---

**RANSAC: RANdom SAmple Consensus**

RANSAC (RANdom SAmple Consensus) fits a model from random subsets of inliers from the complete data set. RANSAC is a non-deterministic algorithm producing only a reasonable result with a certain probability, which is dependent on the number of iterations (see `max_trials` parameter). It is typically used for linear and non-linear regression problems and is especially popular in the field of photogrammetric computer vision.

The algorithm splits the complete input sample data into a set of inliers, which may be subject to noise, and outliers, which are e.g. caused by erroneous measurements or invalid hypotheses about the data. The resulting model is then estimated only from the determined inliers.

![RANSAC Diagram](image)

**Details of the algorithm**

Each iteration performs the following steps:

1. Select `min_samples` random samples from the original data and check whether the set of data is valid (see `is_data_valid`).
2. Fit a model to the random subset (`base_estimator.fit`) and check whether the estimated model is valid (see `is_model_valid`).
3. Classify all data as inliers or outliers by calculating the residuals to the estimated model (`base_estimator.predict(X) - y`) - all data samples with absolute residuals smaller than the `residual_threshold` are considered as inliers.
4. Save fitted model as best model if number of inlier samples is maximal. In case the current estimated model has the same number of inliers, it is only considered as the best model if it has better score.

These steps are performed either a maximum number of times (max_trials) or until one of the special stop criteria are met (see stop_n_inliers and stop_score). The final model is estimated using all inlier samples (consensus set) of the previously determined best model.

The is_data_valid and is_model_valid functions allow to identify and reject degenerate combinations of random sub-samples. If the estimated model is not needed for identifying degenerate cases, is_data_valid should be used as it is called prior to fitting the model and thus leading to better computational performance.

Examples:

- Robust linear model estimation using RANSAC
- Robust linear estimator fitting

References:


Theil-Sen estimator: generalized-median-based estimator

The TheilSenRegressor estimator uses a generalization of the median in multiple dimensions. It is thus robust to multivariate outliers. Note however that the robustness of the estimator decreases quickly with the dimensionality of the problem. It loses its robustness properties and becomes no better than an ordinary least squares in high dimension.

Examples:

- Theil-Sen Regression
- Robust linear estimator fitting

References:

- https://en.wikipedia.org/wiki/Theil%E2%80%93Sen_estimator
Theoretical considerations

TheilSenRegressor is comparable to the Ordinary Least Squares (OLS) in terms of asymptotic efficiency and as an unbiased estimator. In contrast to OLS, Theil-Sen is a non-parametric method which means it makes no assumption about the underlying distribution of the data. Since Theil-Sen is a median-based estimator, it is more robust against corrupted data aka outliers. In univariate setting, Theil-Sen has a breakdown point of about 29.3% in case of a simple linear regression which means that it can tolerate arbitrary corrupted data of up to 29.3%.

The implementation of TheilSenRegressor in scikit-learn follows a generalization to a multivariate linear regression model\textsuperscript{12} using the spatial median which is a generalization of the median to multiple dimensions\textsuperscript{13}.

In terms of time and space complexity, Theil-Sen scales according to

\[
\binom{n_{\text{samples}}}{n_{\text{subsamples}}}
\]

which makes it infeasible to be applied exhaustively to problems with a large number of samples and features. Therefore, the magnitude of a subpopulation can be chosen to limit the time and space complexity by considering only a random subset of all possible combinations.

Examples:

- Theil-Sen Regression

References:

\textsuperscript{12} Xin Dang, Hanxiang Peng, Xueqin Wang and Heping Zhang: Theil-Sen Estimators in a Multiple Linear Regression Model.

\textsuperscript{13} T. Kärkkäinen and S. Äyrämö: On Computation of Spatial Median for Robust Data Mining.
Huber Regression

The \texttt{HuberRegressor} is different to \texttt{Ridge} because it applies a linear loss to samples that are classified as outliers. A sample is classified as an inlier if the absolute error of that sample is lesser than a certain threshold. It differs from \texttt{TheilSenRegressor} and \texttt{RANSACKRegressor} because it does not ignore the effect of the outliers but gives a lesser weight to them.

The loss function that \texttt{HuberRegressor} minimizes is given by

$$\min_{w,\sigma} \sum_{i=1}^{n} \left( \sigma + H_{\epsilon} \left( \frac{X_i w - y_i}{\sigma} \right) \right) \sigma + \alpha ||w||_2^2$$

where

$$H_{\epsilon}(z) = \begin{cases} z^2, & \text{if } |z| < \epsilon, \\ 2\epsilon |z| - \epsilon^2, & \text{otherwise} \end{cases}$$

It is advised to set the parameter \texttt{epsilon} to 1.35 to achieve 95% statistical efficiency.

Notes

The \texttt{HuberRegressor} differs from using \texttt{SGDRegressor} with loss set to \texttt{huber} in the following ways.

- \texttt{HuberRegressor} is scaling invariant. Once \texttt{epsilon} is set, scaling $X$ and $y$ down or up by different values would produce the same robustness to outliers as before, as compared to \texttt{SGDRegressor} where \texttt{epsilon} has to be set again when $X$ and $y$ are scaled.

- \texttt{HuberRegressor} should be more efficient to use on data with small number of samples while \texttt{SGDRegressor} needs a number of passes on the training data to produce the same robustness.

Examples:

- \texttt{HuberRegressor vs Ridge on dataset with strong outliers}

References:

- Peter J. Huber, Elvezio M. Ronchetti: Robust Statistics, Concomitant scale estimates, pg 172
Polynomial regression: extending linear models with basis functions

One common pattern within machine learning is to use linear models trained on nonlinear functions of the data. This approach maintains the generally fast performance of linear methods, while allowing them to fit a much wider range of data.

For example, a simple linear regression can be extended by constructing polynomial features from the coefficients. In the standard linear regression case, you might have a model that looks like this for two-dimensional data:

\[ \hat{y}(w, x) = w_0 + w_1 x_1 + w_2 x_2 \]

If we want to fit a paraboloid to the data instead of a plane, we can combine the features in second-order polynomials, so that the model looks like this:

\[ \hat{y}(w, x) = w_0 + w_1 x_1 + w_2 x_2 + w_3 x_1 x_2 + w_4 x_1^2 + w_5 x_2^2 \]

The (sometimes surprising) observation is that this is still a linear model: to see this, imagine creating a new set of features

\[ z = [x_1, x_2, x_1 x_2, x_1^2, x_2^2] \]

With this re-labeling of the data, our problem can be written

\[ \hat{y}(w, z) = w_0 + w_1 z_1 + w_2 z_2 + w_3 z_3 + w_4 z_4 + w_5 z_5 \]

We see that the resulting polynomial regression is in the same class of linear models we considered above (i.e. the model is linear in \( w \)) and can be solved by the same techniques. By considering linear fits within a higher-dimensional space built with these basis functions, the model has the flexibility to fit a much broader range of data.

Here is an example of applying this idea to one-dimensional data, using polynomial features of varying degrees:

This figure is created using the `PolynomialFeatures` transformer, which transforms an input data matrix into a new data matrix of a given degree. It can be used as follows:
from sklearn.preprocessing import PolynomialFeatures
import numpy as np

X = np.arange(6).reshape(3, 2)

poly = PolynomialFeatures(degree=2)
poly.fit_transform(X)

The features of X have been transformed from \([x_1, x_2]\) to \([1, x_1, x_2, x_1^2, x_1x_2, x_2^2]\), and can now be used within any linear model.

This sort of preprocessing can be streamlined with the Pipeline tools. A single object representing a simple polynomial regression can be created and used as follows:

from sklearn.preprocessing import PolynomialFeatures
from sklearn.linear_model import LinearRegression
from sklearn.pipeline import Pipeline

model = Pipeline([('poly', PolynomialFeatures(degree=3)), ('linear', LinearRegression(fit_intercept=False))])

# fit to an order-3 polynomial data
x = np.arange(5)
y = 3 - 2 * x + x ** 2 - x ** 3
model = model.fit(x[:, np.newaxis], y)

The linear model trained on polynomial features is able to exactly recover the input polynomial coefficients.

In some cases it’s not necessary to include higher powers of any single feature, but only the so-called interaction features that multiply together at most \(d\) distinct features. These can be gotten from PolynomialFeatures with the setting interaction_only=True.

For example, when dealing with boolean features, \(x_i^n = x_i\) for all \(n\) and is therefore useless; but \(x_i x_j\) represents the conjunction of two booleans. This way, we can solve the XOR problem with a linear classifier:

from sklearn.linear_model import Perceptron
from sklearn.preprocessing import PolynomialFeatures

X = np.array([[0, 0], [0, 1], [1, 0], [1, 1]])
y = X[:, 0] ^ X[:, 1]

X = PolynomialFeatures(interaction_only=True).fit_transform(X).astype(int)

clf = Perceptron(fit_intercept=False, max_iter=10, tol=None, shuffle=False).fit(X, y)

And the classifier “predictions” are perfect:
4.1.2 Linear and Quadratic Discriminant Analysis

Linear Discriminant Analysis (``LinearDiscriminantAnalysis``) and Quadratic Discriminant Analysis (``QuadraticDiscriminantAnalysis``) are two classic classifiers, with, as their names suggest, a linear and a quadratic decision surface, respectively.

These classifiers are attractive because they have closed-form solutions that can be easily computed, are inherently multiclass, have proven to work well in practice, and have no hyperparameters to tune.

The plot shows decision boundaries for Linear Discriminant Analysis and Quadratic Discriminant Analysis. The bottom row demonstrates that Linear Discriminant Analysis can only learn linear boundaries, while Quadratic Discriminant Analysis can learn quadratic boundaries and is therefore more flexible.

Examples:
Dimensionality reduction using Linear Discriminant Analysis

`LinearDiscriminantAnalysis` can be used to perform supervised dimensionality reduction, by projecting the input data to a linear subspace consisting of the directions which maximize the separation between classes (in a precise sense discussed in the mathematics section below). The dimension of the output is necessarily less than the number of classes, so this is in general a rather strong dimensionality reduction, and only makes sense in a multiclass setting.

This is implemented in the `transform` method. The desired dimensionality can be set using the `n_components` parameter. This parameter has no influence on the `fit` and `predict` methods.

Examples:

Comparison of LDA and PCA 2D projection of Iris dataset: Comparison of LDA and PCA for dimensionality reduction of the Iris dataset

Mathematical formulation of the LDA and QDA classifiers

Both LDA and QDA can be derived from simple probabilistic models which model the class conditional distribution of the data $P(X|y = k)$ for each class $k$. Predictions can then be obtained by using Bayes’ rule, for each training sample $x \in \mathcal{R}^d$:

$$P(y = k|x) = \frac{P(x|y = k)P(y = k)}{P(x)} = \frac{P(x|y = k)P(y = k)}{\sum_l P(x|y = l) \cdot P(y = l)}$$

and we select the class $k$ which maximizes this posterior probability.

More specifically, for linear and quadratic discriminant analysis, $P(x|y)$ is modeled as a multivariate Gaussian distribution with density:

$$P(x|y = k) = \frac{1}{(2\pi)^{d/2}\Sigma_k^{1/2}} \exp\left(-\frac{1}{2}(x - \mu_k)^T\Sigma_k^{-1}(x - \mu_k)\right)$$

where $d$ is the number of features.

QDA

According to the model above, the log of the posterior is:

$$\log P(y = k|x) = \log P(x|y = k) + \log P(y = k) + Cst$$

$$= -\frac{1}{2} \log |\Sigma_k| - \frac{1}{2}(x - \mu_k)^T\Sigma_k^{-1}(x - \mu_k) + \log P(y = k) + Cst,$$

where the constant term $Cst$ corresponds to the denominator $P(x)$, in addition to other constant terms from the Gaussian. The predicted class is the one that maximises this log-posterior.

Note: Relation with Gaussian Naive Bayes

If in the QDA model one assumes that the covariance matrices are diagonal, then the inputs are assumed to be conditionally independent in each class, and the resulting classifier is equivalent to the Gaussian Naive Bayes classifier `naive_bayes.GaussianNB`.  

4.1. Supervised learning
LDA

LDA is a special case of QDA, where the Gaussians for each class are assumed to share the same covariance matrix: $\Sigma_k = \Sigma$ for all $k$. This reduces the log posterior to:

$$\log P(y = k|x) = -\frac{1}{2}(x - \mu_k)^T \Sigma^{-1}(x - \mu_k) + \log P(y = k) + Cst.$$  

The term $(x - \mu_k)^T \Sigma^{-1}(x - \mu_k)$ corresponds to the Mahalanobis Distance between the sample $x$ and the mean $\mu_k$. The Mahalanobis distance tells how close $x$ is from $\mu_k$, while also accounting for the variance of each feature. We can thus interpret LDA as assigning $x$ to the class whose mean is the closest in terms of Mahalanobis distance, while also accounting for the class prior probabilities.

The log-posterior of LDA can also be written$^3$ as:

$$\log P(y = k|x) = \omega_k^T x + \omega_{k0} + Cst.$$  

where $\omega_k = \Sigma^{-1} \mu_k$ and $\omega_{k0} = -\frac{1}{2} \mu_k^T \Sigma^{-1} \mu_k + \log P(y = k)$. These quantities correspond to the coef_ and intercept_ attributes, respectively.

From the above formula, it is clear that LDA has a linear decision surface. In the case of QDA, there are no assumptions on the covariance matrices $\Sigma_k$ of the Gaussians, leading to quadratic decision surfaces. See$^1$ for more details.

**Mathematical formulation of LDA dimensionality reduction**

First note that the K means $\mu_k$ are vectors in $\mathbb{R}^d$, and they lie in an affine subspace $H$ of dimension at least $K - 1$ (2 points lie on a line, 3 points lie on a plane, etc).

As mentioned above, we can interpret LDA as assigning $x$ to the class whose mean $\mu_k$ is the closest in terms of Mahalanobis distance, while also accounting for the class prior probabilities. Alternatively, LDA is equivalent to first sphering the data so that the covariance matrix is the identity, and then assigning $x$ to the closest mean in terms of Euclidean distance (still accounting for the class priors).

Computing Euclidean distances in this d-dimensional space is equivalent to first projecting the data points into $H$, and computing the distances there (since the other dimensions will contribute equally to each class in terms of distance). In other words, if $x$ is closest to $\mu_k$ in the original space, it will also be the case in $H$. This shows that, implicit in the LDA classifier, there is a dimensionality reduction by linear projection onto a $K - 1$ dimensional space.

We can reduce the dimension even more, to a chosen $L$, by projecting onto the linear subspace $H_L$ which maximizes the variance of the $\mu^*_k$ after projection (in effect, we are doing a form of PCA for the transformed class means $\mu^*_k$). This $L$ corresponds to the n_components parameter used in the transform method. See$^1$ for more details.

**Shrinkage and Covariance Estimator**

Shrinkage is a form of regularization used to improve the estimation of covariance matrices in situations where the number of training samples is small compared to the number of features. In this scenario, the empirical sample covariance is a poor estimator, and shrinkage helps improving the generalization performance of the classifier. Shrinkage LDA can be used by setting the shrinkage parameter of the LinearDiscriminantAnalysis class to ‘auto’. This automatically determines the optimal shrinkage parameter in an analytic way following the lemma introduced by Ledoit and Wolf$^2$. Note that currently shrinkage only works when setting the solver parameter to ‘lsqr’ or ‘eigen’.

The shrinkage parameter can also be manually set between 0 and 1. In particular, a value of 0 corresponds to no shrinkage (which means the empirical covariance matrix will be used) and a value of 1 corresponds to complete

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shrinkage (which means that the diagonal matrix of variances will be used as an estimate for the covariance matrix). Setting this parameter to a value between these two extrema will estimate a shrunk version of the covariance matrix.

The shrunk Ledoit and Wolf estimator of covariance may not always be the best choice. For example if the distribution of the data is normally distributed, the Oracle Shrinkage Approximating estimator sklearn.covariance.OAS yields a smaller Mean Squared Error than the one given by Ledoit and Wolf’s formula used with shrinkage="auto". In LDA, the data are assumed to be gaussian conditionally to the class. If these assumptions hold, using LDA with the OAS estimator of covariance will yield a better classification accuracy than if Ledoit and Wolf or the empirical covariance estimator is used.

The covariance estimator can be chosen using with the covariance_estimator parameter of the discriminant_analysis.LinearDiscriminantAnalysis class. A covariance estimator should have a fit method and a covariance_attribute like all covariance estimators in the sklearn.covariance module.

Examples:

Normal, Ledoit-Wolf and OAS Linear Discriminant Analysis for classification: Comparison of LDA classifiers with Empirical, Ledoit Wolf and OAS covariance estimator.

Estimation algorithms

Using LDA and QDA requires computing the log-posterior which depends on the class priors \(P(y = k)\), the class means \(\mu_k\), and the covariance matrices.

The ‘svd’ solver is the default solver used for LinearDiscriminantAnalysis, and it is the only available solver for QuadraticDiscriminantAnalysis. It can perform both classification and transform (for LDA). As it does not rely on the calculation of the covariance matrix, the ‘svd’ solver may be preferable in situations where the number of features is large. The ‘svd’ solver cannot be used with shrinkage. For QDA, the use of the SVD solver relies on the fact that the covariance matrix \(\Sigma_k\) is, by definition, equal to \(\frac{1}{n-k}X_k^tX_k = VS^2V^t\) where \(V\) comes from the SVD of the (centered) matrix: \(X_k = USV^t\). It turns out that we can compute the log-posterior above without having to
explicitly compute $\Sigma$: computing $S$ and $V$ via the SVD of $X$ is enough. For LDA, two SVDs are computed: the SVD of the centered input matrix $X$ and the SVD of the class-wise mean vectors.

The ‘lsqr’ solver is an efficient algorithm that only works for classification. It needs to explicitly compute the covariance matrix $\Sigma$, and supports shrinkage and custom covariance estimators. This solver computes the coefficients $\omega_k = \Sigma^{-1}\mu_k$ by solving for $\Sigma\omega = \mu_k$, thus avoiding the explicit computation of the inverse $\Sigma^{-1}$.

The ‘eigen’ solver is based on the optimization of the between class scatter to within class scatter ratio. It can be used for both classification and transform, and it supports shrinkage. However, the ‘eigen’ solver needs to compute the covariance matrix, so it might not be suitable for situations with a high number of features.

### References:

#### 4.1.3 Kernel ridge regression

Kernel ridge regression (KRR) [M2012] combines Ridge regression and classification (linear least squares with l2-norm regularization) with the kernel trick. It thus learns a linear function in the space induced by the respective kernel and the data. For non-linear kernels, this corresponds to a non-linear function in the original space.

The form of the model learned by `KernelRidge` is identical to support vector regression (SVR). However, different loss functions are used: KRR uses squared error loss while support vector regression uses $\epsilon$-insensitive loss, both combined with l2 regularization. In contrast to SVR, fitting `KernelRidge` can be done in closed-form and is typically faster for medium-sized datasets. On the other hand, the learned model is non-sparse and thus slower than SVR, which learns a sparse model for $\epsilon > 0$, at prediction-time.

The following figure compares `KernelRidge` and SVR on an artificial dataset, which consists of a sinusoidal target function and strong noise added to every fifth datapoint. The learned model of `KernelRidge` and SVR is plotted, where both complexity/regularization and bandwidth of the RBF kernel have been optimized using grid-search. The learned functions are very similar; however, fitting `KernelRidge` is approximately seven times faster than fitting SVR (both with grid-search). However, prediction of 100000 target values is more than three times faster with SVR since it has learned a sparse model using only approximately 1/3 of the 100 training datapoints as support vectors.

The next figure compares the time for fitting and prediction of `KernelRidge` and SVR for different sizes of the training set. Fitting `KernelRidge` is faster than SVR for medium-sized training sets (less than 1000 samples); however, for larger training sets SVR scales better. With regard to prediction time, SVR is faster than `KernelRidge` for all sizes of the training set because of the learned sparse solution. Note that the degree of sparsity and thus the prediction time depends on the parameters $\epsilon$ and $C$ of the SVR; $\epsilon = 0$ would correspond to a dense model.

#### References:

#### 4.1.4 Support Vector Machines

Support vector machines (SVMs) are a set of supervised learning methods used for classification, regression and outliers detection.

The advantages of support vector machines are:

- Effective in high dimensional spaces.
- Still effective in cases where number of dimensions is greater than the number of samples.
- Uses a subset of training points in the decision function (called support vectors), so it is also memory efficient.
SVR versus Kernel Ridge

- SVR (fit: 0.443s, predict: 0.274s)
- KRR (fit: 0.168s, predict: 0.243s)

SVR support vectors
data
• Versatile: different Kernel functions can be specified for the decision function. Common kernels are provided, but it is also possible to specify custom kernels.

The disadvantages of support vector machines include:

• If the number of features is much greater than the number of samples, avoid over-fitting in choosing Kernel functions and regularization term is crucial.

• SVMs do not directly provide probability estimates, these are calculated using an expensive five-fold cross-validation (see Scores and probabilities, below).

The support vector machines in scikit-learn support both dense (numpy.ndarray and convertible to that by numpy.asarray) and sparse (any scipy.sparse) sample vectors as input. However, to use an SVM to make predictions for sparse data, it must have been fit on such data. For optimal performance, use C-ordered numpy.ndarray (dense) or scipy.sparse.csr_matrix (sparse) with dtype=float64.

Classification

SVC, NuSVC and LinearSVC are classes capable of performing binary and multi-class classification on a dataset.

SVC and NuSVC are similar methods, but accept slightly different sets of parameters and have different mathematical formulations (see section Mathematical formulation). On the other hand, LinearSVC is another (faster) implementation of Support Vector Classification for the case of a linear kernel. Note that LinearSVC does not accept parameter kernel, as this is assumed to be linear. It also lacks some of the attributes of SVC and NuSVC, like support_.

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As other classifiers, SVC, NuSVC and LinearSVC take as input two arrays: an array \( X \) of shape \((n\_samples, n\_features)\) holding the training samples, and an array \( y \) of class labels (strings or integers), of shape \((n\_samples)\):

```python
>>> from sklearn import svm
>>> X = [[0, 0], [1, 1]]
>>> y = [0, 1]
>>> clf = svm.SVC()
>>> clf.fit(X, y)
SVC()
```

After being fitted, the model can then be used to predict new values:

```python
>>> clf.predict([[2., 2.]])
array([1])
```

SVMs decision function (detailed in the Mathematical formulation) depends on some subset of the training data, called the support vectors. Some properties of these support vectors can be found in attributes `support_vectors_`, `support_` and `n_support_`:

```python
>>> # get support vectors
>>> clf.support_vectors_
array([[0., 0.],
       [1., 1.]])
>>> # get indices of support vectors
>>> clf.support_
array([0, 1])
>>> # get number of support vectors for each class
>>> clf.n_support_
array([1, 1])
```

Examples:

- **SVM**: Maximum margin separating hyperplane,
- **Non-linear SVM**
- **SVM-Anova**: SVM with univariate feature selection,

Multi-class classification

SVC and NuSVC implement the “one-versus-one” approach for multi-class classification. In total, \( n\_classes \times (n\_classes - 1) / 2 \) classifiers are constructed and each one trains data from two classes. To provide a consistent interface with other classifiers, the `decision_function_shape` option allows to monotonically transform the results of the “one-versus-one” classifiers to a “one-vs-rest” decision function of shape \((n\_samples, n\_classes)\):

```python
>>> X = [[0], [1], [2], [3]]
>>> Y = [0, 1, 2, 3]
>>> clf = svm.SVC(decision_function_shape='ovo')
>>> clf.fit(X, Y)
SVC(decision_function_shape='ovo')
>>> dec = clf.decision_function([[1]])
>>> dec.shape[1] # 4 classes: 4*3/2 = 6
```
On the other hand, `LinearSVC` implements “one-vs-the-rest” multi-class strategy, thus training `n_classes` models.

```python
>>> lin_clf = svm.LinearSVC()
>>> lin_clf.fit(X, Y)
LinearSVC()
>>> dec = lin_clf.decision_function([[1]])
>>> dec.shape[1]
# 4 classes
4
```

See Mathematical formulation for a complete description of the decision function.

Note that the `LinearSVC` also implements an alternative multi-class strategy, the so-called multi-class SVM formulated by Crammer and Singer\(^\text{16}\). by using the option `multi_class='crammer_singer'`. In practice, one-vs-rest classification is usually preferred, since the results are mostly similar, but the runtime is significantly less.

For “one-vs-rest” `LinearSVC` the attributes `coef_` and `intercept_` have the shape `(n_classes, n_features)` and `(n_classes,)` respectively. Each row of the coefficients corresponds to one of the `n_classes` “one-vs-rest” classifiers and similar for the intercepts, in the order of the “one” class.

In the case of “one-vs-one” `SVC` and `NuSVC`, the layout of the attributes is a little more involved. In the case of a linear kernel, the attributes `coef_` and `intercept_` have the shape `(n_classes * (n_classes - 1) / 2, n_features)` and `(n_classes * (n_classes - 1) / 2)` respectively. This is similar to the layout for `LinearSVC` described above, with each row now corresponding to a binary classifier. The order for classes 0 to `n` is “0 vs 1”, “0 vs 2”, … “0 vs `n`` n”, “1 vs 2”, “1 vs 3”, “1 vs `n`` n”, … “`n-1` vs `n`` n`` n”.

The shape of `dual_coef_` is `(n_classes-1, n_SV)` with a somewhat hard to grasp layout. The columns correspond to the support vectors involved in any of the `n_classes` * `(n_classes - 1) / 2` “one-vs-one” classifiers. Each of the support vectors is used in `n_classes - 1` classifiers. The `n_classes - 1` entries in each row correspond to the dual coefficients for these classifiers.

This might be clearer with an example: consider a three class problem with class 0 having three support vectors \(v_{0,0}, v_{0,1}, v_{0,2}\) and class 1 and 2 having two support vectors \(v_{1,0}, v_{1,1}\) and \(v_{2,0}, v_{2,1}\) respectively. For each support vector \(v_{i,j}\), there are two dual coefficients. Let’s call the coefficient of support vector \(v_{i,j}\) in the classifier between classes \(i\) and \(k\) \(\alpha_{i,j,k}\). Then `dual_coef_` looks like this:

<table>
<thead>
<tr>
<th>(\alpha_{0,1})</th>
<th>(\alpha_{0,2})</th>
<th>Coefficients for SVs of class 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>(\alpha_{1,0})</td>
<td>(\alpha_{1,2})</td>
<td>Coefficients for SVs of class 1</td>
</tr>
<tr>
<td>(\alpha_{2,0})</td>
<td>(\alpha_{2,1})</td>
<td>Coefficients for SVs of class 2</td>
</tr>
</tbody>
</table>

Examples:

- Plot different SVM classifiers in the iris dataset,

---

Scores and probabilities

The `decision_function` method of `SVC` and `NuSVC` gives per-class scores for each sample (or a single score per sample in the binary case). When the constructor option `probability` is set to `True`, class membership probability estimates (from the methods `predict_proba` and `predict_log_proba`) are enabled. In the binary case, the probabilities are calibrated using Platt scaling:\(^9\): logistic regression on the SVM’s scores, fit by an additional cross-validation on the training data. In the multiclass case, this is extended as per\(^10\).

**Note:** The same probability calibration procedure is available for all estimators via the `CalibratedClassifierCV` (see Probability calibration). In the case of `SVC` and `NuSVC`, this procedure is builtin in libsvm which is used under the hood, so it does not rely on scikit-learn’s `CalibratedClassifierCV`.

The cross-validation involved in Platt scaling is an expensive operation for large datasets. In addition, the probability estimates may be inconsistent with the scores:

- the “argmax” of the scores may not be the argmax of the probabilities
- in binary classification, a sample may be labeled by `predict` as belonging to the positive class even if the output of `predict_proba` is less than 0.5; and similarly, it could be labeled as negative even if the output of `predict_proba` is more than 0.5.

Platt’s method is also known to have theoretical issues. If confidence scores are required, but these do not have to be probabilities, then it is advisable to set `probability=False` and use `decision_function` instead of `predict_proba`.

Please note that when `decision_function_shape='ovr'` and `n_classes > 2`, unlike `decision_function`, the `predict` method does not try to break ties by default. You can set `break_ties=True` for the output of `predict` to be the same as `np.argmax(clf.decision_function(., .), axis=1)`, otherwise the first class among the tied classes will always be returned; but have in mind that it comes with a computational cost. See `SVM Tie Breaking Example` for an example on tie breaking.

Unbalanced problems

In problems where it is desired to give more importance to certain classes or certain individual samples, the parameters `class_weight` and `sample_weight` can be used.

`SVC` (but not `NuSVC`) implements the parameter `class_weight` in the `fit` method. It’s a dictionary of the form `{class_label : value}`, where value is a floating point number > 0 that sets the parameter C of class `class_label` to C * value. The figure below illustrates the decision boundary of an unbalanced problem, with and without weight correction.

`SVC`, `NuSVC`, `SVR`, `NuSVR`, `LinearSVC`, `LinearSVR` and `OneClassSVM` implement also weights for individual samples in the `fit` method through the `sample_weight` parameter. Similar to `class_weight`, this sets the parameter C for the i-th example to C * `sample_weight[i]`, which will encourage the classifier to get these samples right. The figure below illustrates the effect of sample weighting on the decision boundary. The size of the circles is proportional to the sample weights:

**Examples:**

- **SVM:** Separating hyperplane for unbalanced classes
- **SVM:** Weighted samples,

---

\(^9\) Platt “Probabilistic outputs for SVMs and comparisons to regularized likelihood methods”.

Regression

The method of Support Vector Classification can be extended to solve regression problems. This method is called Support Vector Regression.

The model produced by support vector classification (as described above) depends only on a subset of the training data, because the cost function for building the model does not care about training points that lie beyond the margin. Analogously, the model produced by Support Vector Regression depends only on a subset of the training data, because the cost function ignores samples whose prediction is close to their target.

There are three different implementations of Support Vector Regression: SVR, NuSVR and LinearSVR. LinearSVR provides a faster implementation than SVR but only considers the linear kernel, while NuSVR implements a slightly different formulation than SVR and LinearSVR. See Implementation details for further details.

As with classification classes, the fit method will take as argument vectors X, y, only that in this case y is expected to have floating point values instead of integer values:

```python
>>> from sklearn import svm
>>> X = [[0, 0], [2, 2]]
>>> y = [0.5, 2.5]
>>> regr = svm.SVR()
>>> regr.fit(X, y)
SVR()
>>> regr.predict([[1, 1]])
array([1.5])
```

Examples:

- Support Vector Regression (SVR) using linear and non-linear kernels

Density estimation, novelty detection

The class OneClassSVM implements a One-Class SVM which is used in outlier detection. See Novelty and Outlier Detection for the description and usage of OneClassSVM.

Complexity

Support Vector Machines are powerful tools, but their compute and storage requirements increase rapidly with the number of training vectors. The core of an SVM is a quadratic programming problem (QP), separating support vectors from the rest of the training data. The QP solver used by the libsvm-based implementation scales between $O(n_{features} \times n_{samples}^2)$ and $O(n_{features} \times n_{samples}^3)$ depending on how efficiently the libsvm cache is used in practice (dataset dependent). If the data is very sparse $n_{features}$ should be replaced by the average number of non-zero features in a sample vector.

For the linear case, the algorithm used in LinearSVC by the liblinear implementation is much more efficient than its libsvm-based SVC counterpart and can scale almost linearly to millions of samples and/or features.
Tips on Practical Use

• **Avoiding data copy**: For SVC, SVR, NuSVC and NuSVR, if the data passed to certain methods is not C-ordered contiguous and double precision, it will be copied before calling the underlying C implementation. You can check whether a given numpy array is C-contiguous by inspecting its flags attribute.

  For LinearSVC (and LogisticRegression) any input passed as a numpy array will be copied and converted to the liblinear internal sparse data representation (double precision floats and int32 indices of non-zero components). If you want to fit a large-scale linear classifier without copying a dense numpy C-contiguous double precision array as input, we suggest to use the SGDClassifier class instead. The objective function can be configured to be almost the same as the LinearSVC model.

• **Kernel cache size**: For SVC, SVR, NuSVC and NuSVR, the size of the kernel cache has a strong impact on run times for larger problems. If you have enough RAM available, it is recommended to set cache_size to a higher value than the default of 200(MB), such as 500(MB) or 1000(MB).

• **Setting C**: C is 1 by default and it’s a reasonable default choice. If you have a lot of noisy observations you should decrease it: decreasing C corresponds to more regularization.

  LinearSVC and LinearSVR are less sensitive to C when it becomes large, and prediction results stop improving after a certain threshold. Meanwhile, larger C values will take more time to train, sometimes up to 10 times longer, as shown in [11].

• **Support Vector Machine algorithms are not scale invariant**, so it is **highly recommended to scale your data**. For example, scale each attribute on the input vector X to [0,1] or [-1,+1], or standardize it to have mean 0 and variance 1. Note that the same scaling must be applied to the test vector to obtain meaningful results. This can be done easily by using a Pipeline:

```python
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.svm import SVC

>>> clf = make_pipeline(StandardScaler(), SVC())
```

See section Preprocessing data for more details on scaling and normalization.

• Regarding the shrinking parameter, quoting [12]: *We found that if the number of iterations is large, then shrinking can shorten the training time. However, if we loosely solve the optimization problem (e.g., by using a large stopping tolerance), the code without using shrinking may be much faster.*

• **Parameter nu** in NuSVC/OneClassSVM/NuSVR approximates the fraction of training errors and support vectors.

• In SVC, if the data is unbalanced (e.g. many positive and few negative), set class_weight='balanced' and/or try different penalty parameters C.

• **Randomness of the underlying implementations**: The underlying implementations of SVC and NuSVC use a random number generator only to shuffle the data for probability estimation (when probability is set to True). This randomness can be controlled with the random_state parameter. If probability is set to False these estimators are not random and random_state has no effect on the results. The underlying OneClassSVM implementation is similar to the ones of SVC and NuSVC. As no probability estimation is provided for OneClassSVM, it is not random.

  The underlying LinearSVC implementation uses a random number generator to select features when fitting the model with a dual coordinate descent (i.e when dual is set to True). It is thus

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12 Chang and Lin, LIBSVM: A Library for Support Vector Machines.
not uncommon to have slightly different results for the same input data. If that happens, try with a smaller `tol` parameter. This randomness can also be controlled with the `random_state` parameter. When `dual` is set to `False` the underlying implementation of `LinearSVC` is not random and `random_state` has no effect on the results.

- Using L1 penalization as provided by `LinearSVC(penalty='l1', dual=False)` yields a sparse solution, i.e. only a subset of feature weights is different from zero and contribute to the decision function. Increasing `C` yields a more complex model (more features are selected). The `C` value that yields a “null” model (all weights equal to zero) can be calculated using `l1_min_c`.

### Kernel functions

The *kernel function* can be any of the following:

- **linear**: \( \langle x, x' \rangle \).
- **polynomial**: \( \gamma \langle x, x' \rangle + r \)\(^d\), where \( d \) is specified by parameter `degree`, \( r \) by `coef0`.
- **rbf**: \( \exp(-\gamma \|x - x'\|^2) \), where \( \gamma \) is specified by parameter `gamma`, must be greater than 0.
- **sigmoid**: \( \tanh(\gamma \langle x, x' \rangle + r) \), where \( r \) is specified by `coef0`.

Different kernels are specified by the `kernel` parameter:

```python
test = svm.SVC(kernel='linear')
test.kernel
'linear'
test = svm.SVC(kernel='rbf')
test.kernel
'rbf'
```

### Parameters of the RBF Kernel

When training an SVM with the *Radial Basis Function* (RBF) kernel, two parameters must be considered: `C` and `gamma`. The parameter `C`, common to all SVM kernels, trades off misclassification of training examples against simplicity of the decision surface. A low `C` makes the decision surface smooth, while a high `C` aims at classifying all training examples correctly. `gamma` defines how much influence a single training example has. The larger `gamma` is, the closer other examples must be to be affected.

Proper choice of `C` and `gamma` is critical to the SVM’s performance. One is advised to use `GridSearchCV` with `C` and `gamma` spaced exponentially far apart to choose good values.

### Examples:

- **RBF SVM parameters**
- **Non-linear SVM**
Custom Kernels

You can define your own kernels by either giving the kernel as a python function or by precomputing the Gram matrix. Classifiers with custom kernels behave the same way as any other classifiers, except that:

- Field `support_vectors_` is now empty, only indices of support vectors are stored in `support_`
- A reference (and not a copy) of the first argument in the `fit()` method is stored for future reference. If that array changes between the use of `fit()` and `predict()` you will have unexpected results.

Using Python functions as kernels

You can use your own defined kernels by passing a function to the `kernel` parameter.

Your kernel must take as arguments two matrices of shape `(n_samples_1, n_features), (n_samples_2, n_features)` and return a kernel matrix of shape `(n_samples_1, n_samples_2)`.

The following code defines a linear kernel and creates a classifier instance that will use that kernel:

```python
>>> import numpy as np
>>> from sklearn import svm
>>> def my_kernel(X, Y):
...     return np.dot(X, Y.T)
...
>>> clf = svm.SVC(kernel=my_kernel)
```

Examples:

- `SVM with custom kernel`.

Using the Gram matrix

You can pass pre-computed kernels by using the `kernel='precomputed'` option. You should then pass Gram matrix instead of X to the `fit` and `predict` methods. The kernel values between all training vectors and the test vectors must be provided:

```python
>>> import numpy as np
>>> from sklearn.datasets import make_classification
>>> from sklearn.model_selection import train_test_split
>>> from sklearn import svm

>>> X, y = make_classification(n_samples=10, random_state=0)

>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)

>>> clf = svm.SVC(kernel='precomputed')

>>> # linear kernel computation
>>> gram_train = np.dot(X_train, X_train.T)

>>> clf.fit(gram_train, y_train)
SVC(kernel='precomputed')

>>> # predict on training examples
>>> gram_test = np.dot(X_test, X_train.T)

>>> clf.predict(gram_test)
array([0, 1, 0])
```
Mathematical formulation

A support vector machine constructs a hyper-plane or set of hyper-planes in a high or infinite dimensional space, which can be used for classification, regression or other tasks. Intuitively, a good separation is achieved by the hyper-plane that has the largest distance to the nearest training data points of any class (so-called functional margin), since in general the larger the margin the lower the generalization error of the classifier. The figure below shows the decision function for a linearly separable problem, with three samples on the margin boundaries, called “support vectors”:

In general, when the problem isn’t linearly separable, the support vectors are the samples within the margin boundaries. We recommend\(^\text{13}\) and\(^\text{14}\) as good references for the theory and practicalities of SVMs.

SVC

Given training vectors \(x_i \in \mathbb{R}^p, i=1, \ldots, n\), in two classes, and a vector \(y \in \{1, -1\}^n\), our goal is to find \(w \in \mathbb{R}^p\) and \(b \in \mathbb{R}\) such that the prediction given by \(\text{sign}(w^T \phi(x) + b)\) is correct for most samples.

SVC solves the following primal problem:

\[
\begin{align*}
\min_{w, b, \zeta} & \quad \frac{1}{2} w^T w + C \sum_{i=1}^n \zeta_i \\
\text{subject to} & \quad y_i (w^T \phi(x_i) + b) \geq 1 - \zeta_i, \\
& \quad \zeta_i \geq 0, i = 1, \ldots, n
\end{align*}
\]

Intuitively, we’re trying to maximize the margin (by minimizing \(\|w\|^2 = w^T w\)), while incurring a penalty when a sample is misclassified or within the margin boundary. Ideally, the value \(y_i (w^T \phi(x_i) + b)\) would be \(\geq 1\) for all samples, which indicates a perfect prediction. But problems are usually not always perfectly separable with a hyperplane, so we

\(^{13}\) Bishop, Pattern recognition and machine learning, chapter 7 Sparse Kernel Machines

allow some samples to be at a distance $\zeta_i$ from their correct margin boundary. The penalty term $C$ controls the strength of this penalty, and as a result, acts as an inverse regularization parameter (see note below).

The dual problem to the primal is

$$
\min_{\alpha} \frac{1}{2} \alpha^T Q \alpha - e^T \alpha
$$

subject to

$$
y^T \alpha = 0 \quad \text{and} \quad 0 \leq \alpha_i \leq C, i = 1, \ldots, n
$$

where $e$ is the vector of all ones, and $Q$ is an $n$ by $n$ positive semidefinite matrix, $Q_{ij} \equiv y_i y_j K(x_i, x_j)$, where $K(x_i, x_j) = \phi(x_i)^T \phi(x_j)$ is the kernel. The terms $\alpha_i$ are called the dual coefficients, and they are upper-bounded by $C$. This dual representation highlights the fact that training vectors are implicitly mapped into a higher (maybe infinite) dimensional space by the function $\phi$: see kernel trick.

Once the optimization problem is solved, the output of decision function for a given sample $x$ becomes:

$$
\sum_{i \in SV} y_i \alpha_i K(x_i, x) + b,
$$

and the predicted class correspond to its sign. We only need to sum over the support vectors (i.e. the samples that lie within the margin) because the dual coefficients $\alpha_i$ are zero for the other samples.

These parameters can be accessed through the attributes dual_coef_, which holds the product $y_i \alpha_i$, support_vectors_ which holds the support vectors, and intercept_ which holds the independent term $b$

**Note:** While SVM models derived from libsvm and liblinear use $C$ as regularization parameter, most other estimators use alpha. The exact equivalence between the amount of regularization of two models depends on the exact objective function optimized by the model. For example, when the estimator used is Ridge regression, the relation between them is given as $C = \frac{1}{\alpha}$. 

### LinearSVC

The primal problem can be equivalently formulated as

$$
\min_{w, b} \frac{1}{2} w^T w + C \sum_{i=1} \max(0, y_i (w^T \phi(x_i) + b)),
$$

where we make use of the hinge loss. This is the form that is directly optimized by LinearSVC, but unlike the dual form, this one does not involve inner products between samples, so the famous kernel trick cannot be applied. This is why only the linear kernel is supported by LinearSVC ($\phi$ is the identity function).

### NuSVC

The $\nu$-SVC formulation\textsuperscript{15} is a reparameterization of the $C$-SVC and therefore mathematically equivalent.

We introduce a new parameter $\nu$ (instead of $C$) which controls the number of support vectors and margin errors: $\nu \in (0, 1]$ is an upper bound on the fraction of margin errors and a lower bound of the fraction of support vectors. A margin error corresponds to a sample that lies on the wrong side of its margin boundary: it is either misclassified, or it is correctly classified but does not lie beyond the margin.

\textsuperscript{15} Schölkopf et. al New Support Vector Algorithms
SVR

Given training vectors \( x_i \in \mathbb{R}^p \), i=1, ..., n, and a vector \( y \in \mathbb{R}^n \), \( \varepsilon \)-SVR solves the following primal problem:

\[
\begin{align*}
\min_{w,b,\zeta,\zeta^*} & \quad \frac{1}{2} w^T w + C \sum_{i=1}^n (\zeta_i + \zeta_i^*) \\
\text{subject to} & \quad y_i - w^T \phi(x_i) - b \leq \varepsilon + \zeta_i, \\
& \quad w^T \phi(x_i) + b - y_i \leq \varepsilon + \zeta_i^*, \\
& \quad \zeta_i, \zeta_i^* \geq 0, \quad i = 1, ..., n
\end{align*}
\]

Here, we are penalizing samples whose prediction is at least \( \varepsilon \) away from their true target. These samples penalize the objective by \( \zeta_i \) or \( \zeta_i^* \), depending on whether their predictions lie above or below the \( \varepsilon \) tube.

The dual problem is

\[
\begin{align*}
\min_{\alpha,\alpha^*} & \quad \frac{1}{2} (\alpha - \alpha^*)^T Q (\alpha - \alpha^*) + \varepsilon e^T (\alpha + \alpha^*) - y^T (\alpha - \alpha^*) \\
\text{subject to} & \quad e^T (\alpha - \alpha^*) = 0 \\
& \quad 0 \leq \alpha_i, \alpha_i^* \leq C, \quad i = 1, ..., n
\end{align*}
\]

where \( e \) is the vector of all ones, \( Q \) is an \( n \) by \( n \) positive semidefinite matrix, \( Q_{ij} = K(x_i, x_j) = \phi(x_i)^T \phi(x_j) \) is the kernel. Here training vectors are implicitly mapped into a higher (maybe infinite) dimensional space by the function \( \phi \).

The prediction is:

\[
\sum_{i \in SV} (\alpha_i - \alpha_i^*) K(x_i, x) + b
\]

These parameters can be accessed through the attributes dual_coef_ which holds the difference \( \alpha_i - \alpha_i^* \), support_vectors_ which holds the support vectors, and intercept_ which holds the independent term \( b \).

LinearSVR

The primal problem can be equivalently formulated as

\[
\begin{align*}
\min_{w,b} & \quad \frac{1}{2} w^T w + C \sum_{i=1}^n \max(0, |y_i - (w^T \phi(x_i) + b)| - \varepsilon),
\end{align*}
\]

where we make use of the epsilon-insensitive loss, i.e. errors of less than \( \varepsilon \) are ignored. This is the form that is directly optimized by LinearSVR.

Implementation details

Internally, we use libsvm\(^\text{12}\) and liblinear\(^\text{11}\) to handle all computations. These libraries are wrapped using C and Cython. For a description of the implementation and details of the algorithms used, please refer to their respective papers.

References:
4.1.5 Stochastic Gradient Descent

**Stochastic Gradient Descent (SGD)** is a simple yet very efficient approach to fitting linear classifiers and regressors under convex loss functions such as (linear) Support Vector Machines and Logistic Regression. Even though SGD has been around in the machine learning community for a long time, it has received a considerable amount of attention just recently in the context of large-scale learning.

SGD has been successfully applied to large-scale and sparse machine learning problems often encountered in text classification and natural language processing. Given that the data is sparse, the classifiers in this module easily scale to problems with more than $10^5$ training examples and more than $10^5$ features.

Strictly speaking, SGD is merely an optimization technique and does not correspond to a specific family of machine learning models. It is only a way to train a model. Often, an instance of `SGDClassifier` or `SGDRegressor` will have an equivalent estimator in the scikit-learn API, potentially using a different optimization technique. For example, using `SGDClassifier(loss='log')` results in logistic regression, i.e. a model equivalent to `LogisticRegression` which is fitted via SGD instead of being fitted by one of the other solvers in `LogisticRegression`. Similarly, `SGDRegressor(loss='squared_loss', penalty='l2')` and `Ridge` solve the same optimization problem, via different means.

The advantages of Stochastic Gradient Descent are:

- Efficiency.
- Ease of implementation (lots of opportunities for code tuning).

The disadvantages of Stochastic Gradient Descent include:

- SGD requires a number of hyperparameters such as the regularization parameter and the number of iterations.
- SGD is sensitive to feature scaling.

---

**Warning:** Make sure you permute (shuffle) your training data before fitting the model or use `shuffle=True` to shuffle after each iteration (used by default). Also, ideally, features should be standardized using e.g. `make_pipeline(StandardScaler(), SGDClassifier())` (see [Pipelines](#)).

### Classification

The class `SGDClassifier` implements a plain stochastic gradient descent learning routine which supports different loss functions and penalties for classification. Below is the decision boundary of a `SGDClassifier` trained with the hinge loss, equivalent to a linear SVM.

As other classifiers, SGD has to be fitted with two arrays: an array $X$ of shape $(n\_samples, n\_features)$ holding the training samples, and an array $y$ of shape $(n\_samples,)$ holding the target values (class labels) for the training samples:

```python
>>> from sklearn.linear_model import SGDClassifier
>>> X = [[0., 0.], [1., 1.]]
>>> y = [0, 1]
>>> clf = SGDClassifier(loss="hinge", penalty="l2", max_iter=5)
>>> clf.fit(X, y)
SGDClassifier(max_iter=5)
```

After being fitted, the model can then be used to predict new values:

```python
>>> clf.predict([[2., 2.]])
array([1])
```

SGD fits a linear model to the training data. The `coef_` attribute holds the model parameters:
The `intercept_` attribute holds the intercept (aka offset or bias):

```python
>>> clf.intercept_
array([-9.9...])
```

Whether or not the model should use an intercept, i.e. a biased hyperplane, is controlled by the parameter `fit_intercept`.

The signed distance to the hyperplane (computed as the dot product between the coefficients and the input sample, plus the intercept) is given by `SGDClassifier.decision_function`:

```python
>>> clf.decision_function([[2., 2.]])
array([29.6...])
```

The concrete loss function can be set via the `loss` parameter. `SGDClassifier` supports the following loss functions:

- `loss="hinge"`: (soft-margin) linear Support Vector Machine,
- `loss="modified_huber"`: smoothed hinge loss,
- `loss="log"`: logistic regression,
- and all regression losses below. In this case the target is encoded as -1 or 1, and the problem is treated as a regression problem. The predicted class then correspond to the sign of the predicted target.

Please refer to the **mathematical section below** for formulas. The first two loss functions are lazy, they only update the model parameters if an example violates the margin constraint, which makes training very efficient and may result in sparser models (i.e. with more zero coefficients), even when L2 penalty is used.
Using `loss="log"` or `loss="modified_huber"` enables the `predict_proba` method, which gives a vector of probability estimates \( P(y|x) \) per sample \( x \):

```python
>>> clf = SGDClassifier(loss="log", max_iter=5).fit(X, y)
>>> clf.predict_proba([[1., 1.]])
array([[0.00..., 0.99...]])
```

The concrete penalty can be set via the `penalty` parameter. SGD supports the following penalties:

- `penalty="l2"`: L2 norm penalty on \( coef_\).
- `penalty="l1"`: L1 norm penalty on \( coef_\).
- `penalty="elasticnet"`: Convex combination of L2 and L1; \((1 - l1\_ratio) \times L2 + l1\_ratio \times L1\).

The default setting is `penalty="l2"`. The L1 penalty leads to sparse solutions, driving most coefficients to zero. The Elastic Net\(^{11}\) solves some deficiencies of the L1 penalty in the presence of highly correlated attributes. The parameter `l1\_ratio` controls the convex combination of L1 and L2 penalty.

`SGDClassifier` supports multi-class classification by combining multiple binary classifiers in a “one versus all” (OVA) scheme. For each of the \( K \) classes, a binary classifier is learned that discriminates between that and all other \( K - 1 \) classes. At testing time, we compute the confidence score (i.e. the signed distances to the hyperplane) for each classifier and choose the class with the highest confidence. The Figure below illustrates the OVA approach on the iris dataset. The dashed lines represent the three OVA classifiers; the background colors show the decision surface induced by the three classifiers.

In the case of multi-class classification \( coef_\) is a two-dimensional array of shape \((n\_classes, n\_features)\) and \( intercept_\) is a one-dimensional array of shape \((n\_classes,)\). The \( i \)-th row of \( coef_\) holds the weight vector of the OVA classifier for the \( i \)-th class; classes are indexed in ascending order (see attribute \( classes_\)). Note that, in principle, since they allow to create a probability model, `loss="log"` and `loss="modified_huber"` are more suitable for one-vs-all classification.

**SGDClassifer** supports both weighted classes and weighted instances via the fit parameters `class_weight` and `sample_weight`. See the examples below and the docstring of `SGDClassifer.fit` for further information.

`SGDClassifer` supports averaged SGD (ASGD)\(^\text{10}\). Averaging can be enabled by setting `average=True`. ASGD performs the same updates as the regular SGD (see Mathematical formulation), but instead of using the last value of the coefficients as the `coef_` attribute (i.e. the values of the last update), `coef_` is set instead to the average value of the coefficients across all updates. The same is done for the `intercept_` attribute. When using ASGD the learning rate can be larger and even constant, leading on some datasets to a speed up in training time.

For classification with a logistic loss, another variant of SGD with an averaging strategy is available with Stochastic Average Gradient (SAG) algorithm, available as a solver in `LogisticRegression`.

### Examples:

- **SGD**: Maximum margin separating hyperplane,
- **Plot multi-class SGD on the iris dataset**
- **SGD**: Weighted samples
- **Comparing various online solvers**
- **SVM**: Separating hyperplane for unbalanced classes (See the Note in the example)

### Regression

The class `SGDRegressor` implements a plain stochastic gradient descent learning routine which supports different loss functions and penalties to fit linear regression models. `SGDRegressor` is well suited for regression problems with a large number of training samples (> 10,000), for other problems we recommend `Ridge`, `Lasso`, or `ElasticNet`.

The concrete loss function can be set via the `loss` parameter. `SGDRegressor` supports the following loss functions:

- `loss="squared_loss"`: Ordinary least squares,
- `loss="huber"`: Huber loss for robust regression,
- `loss="epsilon_insensitive"`: linear Support Vector Regression.

Please refer to the mathematical section below for formulas. The Huber and epsilon-insensitive loss functions can be used for robust regression. The width of the insensitive region has to be specified via the parameter `epsilon`. This parameter depends on the scale of the target variables.

The `penalty` parameter determines the regularization to be used (see description above in the classification section).

`SGDRegressor` also supports averaged SGD\(^\text{10}\) (here again, see description above in the classification section).

For regression with a squared loss and a l2 penalty, another variant of SGD with an averaging strategy is available with Stochastic Average Gradient (SAG) algorithm, available as a solver in `Ridge`.

\(^{10}\)“Towards Optimal One Pass Large Scale Learning with Averaged Stochastic Gradient Descent” Xu, Wei
Stochastic Gradient Descent for sparse data

Note: The sparse implementation produces slightly different results from the dense implementation, due to a shrunk learning rate for the intercept. See Implementation details.

There is built-in support for sparse data given in any matrix in a format supported by scipy.sparse. For maximum efficiency, however, use the CSR matrix format as defined in scipy.sparse.csr_matrix.

Examples:
  - Classification of text documents using sparse features

Complexity

The major advantage of SGD is its efficiency, which is basically linear in the number of training examples. If $X$ is a matrix of size $(n, p)$ training has a cost of $O(kn\bar{p})$, where $k$ is the number of iterations (epochs) and $\bar{p}$ is the average number of non-zero attributes per sample.

Recent theoretical results, however, show that the runtime to get some desired optimization accuracy does not increase as the training set size increases.

Stopping criterion

The classes SGDClassifier and SGDRegressor provide two criteria to stop the algorithm when a given level of convergence is reached:

- With early_stopping=True, the input data is split into a training set and a validation set. The model is then fitted on the training set, and the stopping criterion is based on the prediction score (using the score method) computed on the validation set. The size of the validation set can be changed with the parameter validation_fraction.

- With early_stopping=False, the model is fitted on the entire input data and the stopping criterion is based on the objective function computed on the training data.

In both cases, the criterion is evaluated once by epoch, and the algorithm stops when the criterion does not improve $n_{\text{iter\_no\_change}}$ times in a row. The improvement is evaluated with absolute tolerance tol, and the algorithm stops in any case after a maximum number of iteration max_iter.

Tips on Practical Use

- Stochastic Gradient Descent is sensitive to feature scaling, so it is highly recommended to scale your data. For example, scale each attribute on the input vector $X$ to $[0,1]$ or $[-1,+1]$, or standardize it to have mean 0 and variance 1. Note that the same scaling must be applied to the test vector to obtain meaningful results. This can be easily done using StandardScaler:

```python
from sklearn.preprocessing import StandardScaler
scaler = StandardScaler()
scaler.fit(X_train)  # Don't cheat - fit only on training data
X_train = scaler.transform(X_train)
X_test = scaler.transform(X_test)  # apply same transformation to test data
```

(continues on next page)
Or better yet: use a pipeline!

```python
from sklearn.pipeline import make_pipeline
est = make_pipeline(StandardScaler(), SGDClassifier())
est.fit(X_train)
est.predict(X_test)
```

If your attributes have an intrinsic scale (e.g. word frequencies or indicator features) scaling is not needed.

- Finding a reasonable regularization term \( \alpha \) is best done using automatic hyper-parameter search, e.g. `GridSearchCV` or `RandomizedSearchCV`, usually in the range \( 10.0^{\text{-np.arange(1,7)}} \).
- Empirically, we found that SGD converges after observing approximately \( 10^6 \) training samples. Thus, a reasonable first guess for the number of iterations is \( \text{max\_iter} = \text{np.ceil}(10^6 / n) \), where \( n \) is the size of the training set.
- If you apply SGD to features extracted using PCA we found that it is often wise to scale the feature values by some constant \( c \) such that the average L2 norm of the training data equals one.
- We found that Averaged SGD works best with a larger number of features and a higher \( \eta_0 \).

### References:


#### Mathematical formulation

We describe here the mathematical details of the SGD procedure. A good overview with convergence rates can be found in\(^\text{12}\).

Given a set of training examples \((x_1, y_1), \ldots, (x_n, y_n)\) where \( x_i \in \mathbb{R}^m \) and \( y_i \in \mathcal{R} \) (\( y_i \in -1, 1 \) for classification), our goal is to learn a linear scoring function \( f(x) = w^T x + b \) with model parameters \( w \in \mathbb{R}^m \) and intercept \( b \in \mathbb{R} \). In order to make predictions for binary classification, we simply look at the sign of \( f(x) \). To find the model parameters, we minimize the regularized training error given by

\[
E(w, b) = \frac{1}{n} \sum_{i=1}^{n} L(y_i, f(x_i)) + \alpha R(w)
\]

where \( L \) is a loss function that measures model (mis)fit and \( R \) is a regularization term (aka penalty) that penalizes model complexity; \( \alpha > 0 \) is a non-negative hyperparameter that controls the regularization strength.

Different choices for \( L \) entail different classifiers or regressors:

- **Hinge** (soft-margin): equivalent to Support Vector Classification. \( L(y_i, f(x_i)) = \max(0, 1 - y_i f(x_i)) \).
- **Perceptron**: \( L(y_i, f(x_i)) = \max(0, -y_i f(x_i)) \).
- **Modified Huber**: \( L(y_i, f(x_i)) = \max(0, 1 - y_i f(x_i))^2 \) if \( y_i f(x_i) > 1 \), and \( L(y_i, f(x_i)) = -4y_i f(x_i) \) otherwise.
- **Log**: equivalent to Logistic Regression. \( L(y_i, f(x_i)) = \log(1 + \exp(-y_i f(x_i))) \).
- **Least-Squares**: Linear regression (Ridge or Lasso depending on \( R \)). \( L(y_i, f(x_i)) = \frac{1}{2} (y_i - f(x_i))^2 \).
- **Huber**: less sensitive to outliers than least-squares. It is equivalent to least squares when \( |y_i - f(x_i)| \leq \varepsilon \), and \( L(y_i, f(x_i)) = \varepsilon |y_i - f(x_i)| - \frac{1}{2} \varepsilon^2 \) otherwise.

\(^{12}\) “Solving large scale linear prediction problems using stochastic gradient descent algorithms” T. Zhang - In Proceedings of ICML ‘04.
• Epsilon-Insensitive: (soft-margin) equivalent to Support Vector Regression. \( L(y_i, f(x_i)) = \max(0, |y_i - f(x_i)| - \varepsilon) \).

All of the above loss functions can be regarded as an upper bound on the misclassification error (Zero-one loss) as shown in the Figure below.

![Loss Functions Contours](image)

Popular choices for the regularization term \( R \) (the penalty parameter) include:

• L2 norm: \( R(w) := \frac{1}{2} \sum_{j=1}^{m} w_j^2 = ||w||_2^2 \).

• L1 norm: \( R(w) := \sum_{j=1}^{m} |w_j| \), which leads to sparse solutions.

• Elastic Net: \( R(w) := \frac{\rho}{2} \sum_{j=1}^{m} w_j^2 + (1 - \rho) \sum_{j=1}^{m} |w_j| \), a convex combination of L2 and L1, where \( \rho \) is given by \( 1 - \text{l1_ratio} \).

The Figure below shows the contours of the different regularization terms in a 2-dimensional parameter space \((m = 2)\) when \( R(w) = 1 \).

SGD

Stochastic gradient descent is an optimization method for unconstrained optimization problems. In contrast to (batch) gradient descent, SGD approximates the true gradient of \( E(w, b) \) by considering a single training example at a time.

The class `SGDClassifier` implements a first-order SGD learning routine. The algorithm iterates over the training examples and for each example updates the model parameters according to the update rule given by

\[
w \leftarrow w - \eta \left[ \alpha \frac{\partial R(w)}{\partial w} + \frac{\partial L(w^T x_i + b, y_i)}{\partial w} \right]
\]

where \( \eta \) is the learning rate which controls the step-size in the parameter space. The intercept \( b \) is updated similarly but without regularization (and with additional decay for sparse matrices, as detailed in Implementation details).
The learning rate $\eta$ can be either constant or gradually decaying. For classification, the default learning rate schedule (learning_rate='optimal') is given by

$$\eta(t) = \frac{1}{\alpha(t_0 + t)}$$

where $t$ is the time step (there are a total of $n_{\text{samples}} \times n_{\text{iter}}$ time steps), $t_0$ is determined based on a heuristic proposed by Léon Bottou such that the expected initial updates are comparable with the expected size of the weights (this assuming that the norm of the training samples is approx. 1). The exact definition can be found in init_t in BaseSGD.

For regression the default learning rate schedule is inverse scaling (learning_rate='invscaling'), given by

$$\eta(t) = \frac{\eta_0}{t^{\text{power}_t}}$$

where $\eta_0$ and $\text{power}_t$ are hyperparameters chosen by the user via eta0 and power_t, resp.

For a constant learning rate use learning_rate='constant' and use eta0 to specify the learning rate.

For an adaptively decreasing learning rate, use learning_rate='adaptive' and use eta0 to specify the starting learning rate. When the stopping criterion is reached, the learning rate is divided by 5, and the algorithm does not stop. The algorithm stops when the learning rate goes below 1e-6.

The model parameters can be accessed through the coef_ and intercept_ attributes: coef_ holds the weights $w$ and intercept_ holds $b$.

When using Averaged SGD (with the average parameter), coef_ is set to the average weight across all updates: $\text{coef}_\text{avg} = \frac{1}{T} \sum_{t=0}^{T-1} w(t)$, where $T$ is the total number of updates, found in the t_ attribute.

**Implementation details**

The implementation of SGD is influenced by the Stochastic Gradient SVM of\(^7\). Similar to SvmSGD, the weight vector is represented as the product of a scalar and a vector which allows an efficient weight update in the case of L2 regularization. In the case of sparse input $X$, the intercept is updated with a smaller learning rate (multiplied by 0.01) to account for the fact that it is updated more frequently. Training samples are picked up sequentially and the learning rate is lowered after each observed example. We adopted the learning rate schedule from\(^8\). For multi-class classification, a “one versus all” approach is used. We use the truncated gradient algorithm proposed in\(^9\) for L1 regularization (and the Elastic Net). The code is written in Cython.

**References:**

4.1.6 Nearest Neighbors

`sklearn.neighbors` provides functionality for unsupervised and supervised neighbors-based learning methods. Unsupervised nearest neighbors is the foundation of many other learning methods, notably manifold learning and spectral clustering. Supervised neighbors-based learning comes in two flavors: classification for data with discrete labels, and regression for data with continuous labels.

The principle behind nearest neighbor methods is to find a predefined number of training samples closest in distance to the new point, and predict the label from these. The number of samples can be a user-defined constant (k-nearest

---

\(^7\) "Stochastic Gradient Descent" L. Bottou - Website, 2010.

\(^8\) “Pegasos: Primal estimated sub-gradient solver for svm” S. Shalev-Shwartz, Y. Singer, N. Srebro - In Proceedings of ICML ‘07.

neighbor learning), or vary based on the local density of points (radius-based neighbor learning). The distance can, in general, be any metric measure: standard Euclidean distance is the most common choice. Neighbors-based methods are known as non-generalizing machine learning methods, since they simply “remember” all of its training data (possibly transformed into a fast indexing structure such as a Ball Tree or KD Tree).

Despite its simplicity, nearest neighbors has been successful in a large number of classification and regression problems, including handwritten digits and satellite image scenes. Being a non-parametric method, it is often successful in classification situations where the decision boundary is very irregular.

The classes in sklearn.neighbors can handle either NumPy arrays or scipy.sparse matrices as input. For dense matrices, a large number of possible distance metrics are supported. For sparse matrices, arbitrary Minkowski metrics are supported for searches.

There are many learning routines which rely on nearest neighbors at their core. One example is kernel density estimation, discussed in the density estimation section.

Unsupervised Nearest Neighbors

NearestNeighbors implements unsupervised nearest neighbors learning. It acts as a uniform interface to three different nearest neighbors algorithms: BallTree, KDTree, and a brute-force algorithm based on routines in sklearn.metrics.pairwise. The choice of neighbors search algorithm is controlled through the keyword 'algorithm', which must be one of ['auto', 'ball_tree', 'kd_tree', 'brute']. When the default value 'auto' is passed, the algorithm attempts to determine the best approach from the training data. For a discussion of the strengths and weaknesses of each option, see Nearest Neighbor Algorithms.

Warning: Regarding the Nearest Neighbors algorithms, if two neighbors $k + 1$ and $k$ have identical distances but different labels, the result will depend on the ordering of the training data.

Finding the Nearest Neighbors

For the simple task of finding the nearest neighbors between two sets of data, the unsupervised algorithms within sklearn.neighbors can be used:

```
>>> from sklearn.neighbors import NearestNeighbors
>>> import numpy as np
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> nbrs = NearestNeighbors(n_neighbors=2, algorithm='ball_tree').fit(X)
>>> distances, indices = nbrs.kneighbors(X)
>>> indices
array([[0, 1],
       [1, 0],
       [2, 1],
       [3, 4],
       [4, 3],
       [5, 4]])...
>>> distances
array([[0. , 1. ],
       [0. , 1. ],
       [0. , 1.41421356],
       [0. , 1. ],
       [0. , 1. ],
       [0. , 1.41421356]])
```
Because the query set matches the training set, the nearest neighbor of each point is the point itself, at a distance of zero.

It is also possible to efficiently produce a sparse graph showing the connections between neighboring points:

```python
>>> from sklearn.neighbors import KNeighborsGraph
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> kdt = KNeighborsGraph(X, leaf_size=30, metric='euclidean')
>>> kdt.query(X, k=2, return_distance=False)
array([[0, 1],
       [1, 0],
       [2, 1],
       [3, 4],
       [4, 3],
       [5, 4]])
```

The dataset is structured such that points nearby in index order are nearby in parameter space, leading to an approximately block-diagonal matrix of K-nearest neighbors. Such a sparse graph is useful in a variety of circumstances which make use of spatial relationships between points for unsupervised learning: in particular, see Isomap, LocallyLinearEmbedding, and SpectralClustering.

### KDTree and BallTree Classes

Alternatively, one can use the KDTree or BallTree classes directly to find nearest neighbors. This is the functionality wrapped by the NearestNeighbors class used above. The Ball Tree and KD Tree have the same interface; we’ll show an example of using the KD Tree here:

```python
>>> from sklearn.neighbors import KDTree
>>> import numpy as np
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> kdt = KDTree(X, leaf_size=30, metric='euclidean')
>>> kdt.query(X, k=2, return_distance=False)
array([[0, 1],
       [1, 0],
       [2, 1],
       [3, 4],
       [4, 3],
       [5, 4]])
```

Refer to the KDTree and BallTree class documentation for more information on the options available for nearest neighbors searches, including specification of query strategies, distance metrics, etc. For a list of available metrics, see the documentation of the DistanceMetric class.

### Nearest Neighbors Classification

Neighbors-based classification is a type of instance-based learning or non-generalizing learning: it does not attempt to construct a general internal model, but simply stores instances of the training data. Classification is computed from a simple majority vote of the nearest neighbors of each point: a query point is assigned the data class which has the most representatives within the nearest neighbors of the point.

scikit-learn implements two different nearest neighbors classifiers: KNeighborsClassifier implements learning based on the \( k \) nearest neighbors of each query point, where \( k \) is an integer value specified by the user. RadiusNeighborsClassifier implements learning based on the number of neighbors within a fixed radius \( r \) of each training point, where \( r \) is a floating-point value specified by the user.

The \( k \)-neighbors classification in KNeighborsClassifier is the most commonly used technique. The optimal choice of the value \( k \) is highly data-dependent: in general a larger \( k \) suppresses the effects of noise, but makes the classification boundaries less distinct.
In cases where the data is not uniformly sampled, radius-based neighbors classification in `RadiusNeighborsClassifier` can be a better choice. The user specifies a fixed radius $r$, such that points in sparser neighborhoods use fewer nearest neighbors for the classification. For high-dimensional parameter spaces, this method becomes less effective due to the so-called “curse of dimensionality”.

The basic nearest neighbors classification uses uniform weights: that is, the value assigned to a query point is computed from a simple majority vote of the nearest neighbors. Under some circumstances, it is better to weight the neighbors such that nearer neighbors contribute more to the fit. This can be accomplished through the `weights` keyword. The default value, `weights = 'uniform'`, assigns uniform weights to each neighbor. `weights = 'distance'` assigns weights proportional to the inverse of the distance from the query point. Alternatively, a user-defined function of the distance can be supplied to compute the weights.

Examples:

- **Nearest Neighbors Classification**: an example of classification using nearest neighbors.
Nearest Neighbors Regression

Neighbors-based regression can be used in cases where the data labels are continuous rather than discrete variables. The label assigned to a query point is computed based on the mean of the labels of its nearest neighbors.

scikit-learn implements two different neighbors regressors: `KNeighborsRegressor` implements learning based on the $k$ nearest neighbors of each query point, where $k$ is an integer value specified by the user. `RadiusNeighborsRegressor` implements learning based on the neighbors within a fixed radius $r$ of the query point, where $r$ is a floating-point value specified by the user.

The basic nearest neighbors regression uses uniform weights: that is, each point in the local neighborhood contributes uniformly to the classification of a query point. Under some circumstances, it can be advantageous to weight points such that nearby points contribute more to the regression than faraway points. This can be accomplished through the `weights` keyword. The default value, `weights = 'uniform'`, assigns equal weights to all points. `weights = 'distance'` assigns weights proportional to the inverse of the distance from the query point. Alternatively, a user-defined function of the distance can be supplied, which will be used to compute the weights.

The use of multi-output nearest neighbors for regression is demonstrated in *Face completion with a multi-output estimators*. In this example, the inputs $X$ are the pixels of the upper half of faces and the outputs $Y$ are the pixels of the lower half of those faces.

Examples:

- *Nearest Neighbors regression*: an example of regression using nearest neighbors.

- *Face completion with a multi-output estimators*: an example of multi-output regression using nearest neighbors.
Face completion with multi-output estimators

true faces | Extra trees | K-nn | Linear regression | Ridge
---|---|---|---|---

---

Chapter 4. User Guide
Nearest Neighbor Algorithms

Brute Force

Fast computation of nearest neighbors is an active area of research in machine learning. The most naive neighbor search implementation involves the brute-force computation of distances between all pairs of points in the dataset: for \( N \) samples in \( D \) dimensions, this approach scales as \( O[DN^2] \). Efficient brute-force neighbors searches can be very competitive for small data samples. However, as the number of samples \( N \) grows, the brute-force approach quickly becomes infeasible. In the classes within `sklearn.neighbors`, brute-force neighbors searches are specified using the keyword `algorithm = 'brute'`, and are computed using the routines available in `sklearn.metrics.pairwise`.

K-D Tree

To address the computational inefficiencies of the brute-force approach, a variety of tree-based data structures have been invented. In general, these structures attempt to reduce the required number of distance calculations by efficiently encoding aggregate distance information for the sample. The basic idea is that if point \( A \) is very distant from point \( B \), and point \( B \) is very close to point \( C \), then we know that points \( A \) and \( C \) are very distant, without having to explicitly calculate their distance. In this way, the computational cost of a nearest neighbors search can be reduced to \( O[DN \log(N)] \) or better. This is a significant improvement over brute-force for large \( N \).

An early approach to taking advantage of this aggregate information was the KD tree data structure (short for K-dimensional tree), which generalizes two-dimensional Quad-trees and 3-dimensional Oct-trees to an arbitrary number of dimensions. The KD tree is a binary tree structure which recursively partitions the parameter space along the data axes, dividing it into nested orthotropic regions into which data points are filed. The construction of a KD tree is very fast: because partitioning is performed only along the data axes, no \( D \)-dimensional distances need to be computed. Once constructed, the nearest neighbor of a query point can be determined with only \( O[\log(N)] \) distance computations. Though the KD tree approach is very fast for low-dimensional (\( D < 20 \)) neighbors searches, it becomes inefficient as \( D \) grows very large: this is one manifestation of the so-called “curse of dimensionality”. In scikit-learn, KD tree neighbors searches are specified using the keyword `algorithm = 'kd_tree'`, and are computed using the class `KDTree`.

References:

- “Multidimensional binary search trees used for associative searching”, Bentley, J.L., Communications of the ACM (1975)

Ball Tree

To address the inefficiencies of KD Trees in higher dimensions, the ball tree data structure was developed. Where KD trees partition data along Cartesian axes, ball trees partition data in a series of nesting hyper-spheres. This makes tree construction more costly than that of the KD tree, but results in a data structure which can be very efficient on highly structured data, even in very high dimensions.

A ball tree recursively divides the data into nodes defined by a centroid \( C \) and radius \( r \), such that each point in the node lies within the hyper-sphere defined by \( r \) and \( C \). The number of candidate points for a neighbor search is reduced through use of the triangle inequality:

\[
|x + y| \leq |x| + |y|
\]

With this setup, a single distance calculation between a test point and the centroid is sufficient to determine a lower and upper bound on the distance to all points within the node. Because of the spherical geometry of the ball tree nodes, it
can out-perform a KD-tree in high dimensions, though the actual performance is highly dependent on the structure of the training data. In scikit-learn, ball-tree-based neighbors searches are specified using the keyword `algorithm = 'ball_tree'`, and are computed using the class `BallTree`. Alternatively, the user can work with the `BallTree` class directly.

References:


### Choice of Nearest Neighbors Algorithm

The optimal algorithm for a given dataset is a complicated choice, and depends on a number of factors:

- number of samples \(N\) (i.e. `n_samples`) and dimensionality \(D\) (i.e. `n_features`).
  - Brute force query time grows as \(O[DN]\)
  - Ball tree query time grows as approximately \(O[D \log(N)]\)
  - KD tree query time changes with \(D\) in a way that is difficult to precisely characterise. For small \(D\) (less than 20 or so) the cost is approximately \(O[D \log(N)]\), and the KD tree query can be very efficient. For larger \(D\), the cost increases to nearly \(O[DN]\), and the overhead due to the tree structure can lead to queries which are slower than brute force.

For small data sets (\(N\) less than 30 or so), \(\log(N)\) is comparable to \(N\), and brute force algorithms can be more efficient than a tree-based approach. Both `KDTree` and `BallTree` address this through providing a leaf size parameter: this controls the number of samples at which a query switches to brute-force. This allows both algorithms to approach the efficiency of a brute-force computation for small \(N\).

- data structure: intrinsic dimensionality of the data and/or sparsity of the data. Intrinsic dimensionality refers to the dimension \(d \leq D\) of a manifold on which the data lies, which can be linearly or non-linearly embedded in the parameter space. Sparsity refers to the degree to which the data fills the parameter space (this is to be distinguished from the concept as used in “sparse” matrices. The data matrix may have no zero entries, but the structure can still be “sparse” in this sense).
  - Brute force query time is unchanged by data structure.
  - Ball tree and KD tree query times can be greatly influenced by data structure. In general, sparser data with a smaller intrinsic dimensionality leads to faster query times. Because the KD tree internal representation is aligned with the parameter axes, it will not generally show as much improvement as ball tree for arbitrarily structured data.

Datasets used in machine learning tend to be very structured, and are very well-suited for tree-based queries.

- number of neighbors \(k\) requested for a query point.
  - Brute force query time is largely unaffected by the value of \(k\)
  - Ball tree and KD tree query time will become slower as \(k\) increases. This is due to two effects: first, a larger \(k\) leads to the necessity to search a larger portion of the parameter space. Second, using \(k > 1\) requires internal queueing of results as the tree is traversed.

As \(k\) becomes large compared to \(N\), the ability to prune branches in a tree-based query is reduced. In this situation, Brute force queries can be more efficient.

- number of query points. Both the ball tree and the KD Tree require a construction phase. The cost of this construction becomes negligible when amortized over many queries. If only a small number of queries will
be performed, however, the construction can make up a significant fraction of the total cost. If very few query points will be required, brute force is better than a tree-based method.

Currently, `algorithm = 'auto'` selects 'brute' if any of the following conditions are verified:

- input data is sparse
- `metric = 'precomputed'`
- $D > 15$
- $k >= N/2$
- `effective_metric_` isn’t in the VALID_METRICS list for either 'kd_tree' or 'ball_tree'

Otherwise, it selects the first out of 'kd_tree' and 'ball_tree' that has `effective_metric_` in its VALID_METRICS list. This heuristic is based on the following assumptions:

- the number of query points is at least the same order as the number of training points
- `leaf_size` is close to its default value of 30
- when $D > 15$, the intrinsic dimensionality of the data is generally to high for tree-based methods

**Effect of `leaf_size`**

As noted above, for small sample sizes a brute force search can be more efficient than a tree-based query. This fact is accounted for in the ball tree and KD tree by internally switching to brute force searches within leaf nodes. The level of this switch can be specified with the parameter `leaf_size`. This parameter choice has many effects:

**construction time**  A larger `leaf_size` leads to a faster tree construction time, because fewer nodes need to be created

**query time**  Both a large or small `leaf_size` can lead to suboptimal query cost. For `leaf_size` approaching 1, the overhead involved in traversing nodes can significantly slow query times. For `leaf_size` approaching the size of the training set, queries become essentially brute force. A good compromise between these is `leaf_size = 30`, the default value of the parameter.

**memory**  As `leaf_size` increases, the memory required to store a tree structure decreases. This is especially important in the case of ball tree, which stores a $D$-dimensional centroid for each node. The required storage space for `BallTree` is approximately $1 / leaf_size$ times the size of the training set.

`leaf_size` is not referenced for brute force queries.

**Nearest Centroid Classifier**

The `NearestCentroid` classifier is a simple algorithm that represents each class by the centroid of its members. In effect, this makes it similar to the label updating phase of the `KMeans` algorithm. It also has no parameters to choose, making it a good baseline classifier. It does, however, suffer on non-convex classes, as well as when classes have drastically different variances, as equal variance in all dimensions is assumed. See Linear Discriminant Analysis (`LinearDiscriminantAnalysis`) and Quadratic Discriminant Analysis (`QuadraticDiscriminantAnalysis`) for more complex methods that do not make this assumption. Usage of the default `NearestCentroid` is simple:

```python
>>> from sklearn.neighbors import NearestCentroid
>>> import numpy as np

>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> y = np.array([1, 1, 1, 2, 2, 2])
>>> clf = NearestCentroid()

(continues on next page)```
Nearest Centroid

The `NearestCentroid` classifier has a `shrink_threshold` parameter, which implements the nearest shrunken centroid classifier. In effect, the value of each feature for each centroid is divided by the within-class variance of that feature. The feature values are then reduced by `shrink_threshold`. Most notably, if a particular feature value crosses zero, it is set to zero. In effect, this removes the feature from affecting the classification. This is useful, for example, for removing noisy features.

In the example below, using a small shrink threshold increases the accuracy of the model from 0.81 to 0.82.

```python
>>> clf.fit(X, y)
NearestCentroid()
>>> print(clf.predict([[0.8, -1]]))
[1]
```

Examples:

- **Nearest Centroid Classification**: an example of classification using nearest centroid with different shrink thresholds.

Nearest Neighbors Transformer

Many scikit-learn estimators rely on nearest neighbors: Several classifiers and regressors such as `KNeighborsClassifier` and `KNeighborsRegressor`, but also some clustering methods such as `DBSCAN` and `SpectralClustering`, and some manifold embeddings such as `TSNE` and `Isomap`.

All these estimators can compute internally the nearest neighbors, but most of them also accept precomputed nearest neighbors `sparse graph`, as given by `kneighbors_graph` and `radius_neighbors_graph`. With mode `mode='connectivity'`, these functions return a binary adjacency sparse graph as required, for instance, in `SpectralClustering`. Whereas with `mode='distance'`, they return a distance sparse graph as required, for instance, in `DBSCAN`. To include these functions in a scikit-learn pipeline, one can also use the corresponding classes `KNeighborsTransformer` and `RadiusNeighborsTransformer`. The benefits of this sparse graph API are multiple.

First, the precomputed graph can be re-used multiple times, for instance while varying a parameter of the estimator. This can be done manually by the user, or using the caching properties of the scikit-learn pipeline:
Second, precomputing the graph can give finer control on the nearest neighbors estimation, for instance enabling multiprocessing though the parameter `n_jobs`, which might not be available in all estimators.

Finally, the precomputation can be performed by custom estimators to use different implementations, such as approximate nearest neighbors methods, or implementation with special data types. The precomputed neighbors sparse graph needs to be formatted as in `radius_neighbors_graph` output:

- a CSR matrix (although COO, CSC or LIL will be accepted).
- only explicitly store nearest neighborhoods of each sample with respect to the training data. This should include those at 0 distance from a query point, including the matrix diagonal when computing the nearest neighborhoods between the training data and itself.
- each row’s `data` should store the distance in increasing order (optional. Unsorted data will be stable-sorted, adding a computational overhead).
- all values in data should be non-negative.
- there should be no duplicate `indices` in any row (see https://github.com/scipy/scipy/issues/5807).
- if the algorithm being passed the precomputed matrix uses k nearest neighbors (as opposed to radius neighborhood), at least k neighbors must be stored in each row (or k+1, as explained in the following note).

**Note:** When a specific number of neighbors is queried (using `KNeighborsTransformer`), the definition of `n_neighbors` is ambiguous since it can either include each training point as its own neighbor, or exclude them. Neither choice is perfect, since including them leads to a different number of non-self neighbors during training and testing, while excluding them leads to a difference between `fit(X).transform(X)` and `fit_transform(X)`, which is against scikit-learn API. In `KNeighborsTransformer` we use the definition which includes each training point as its own neighbor in the count of `n_neighbors`. However, for compatibility reasons with other estimators which use the other definition, one extra neighbor will be computed when `mode == 'distance'`. To maximise compatibility with all estimators, a safe choice is to always include one extra neighbor in a custom nearest neighbors estimator, since unnecessary neighbors will be filtered by following estimators.

**Examples:**

- **Approximate nearest neighbors in TSNE**: an example of pipelining `KNeighborsTransformer` and `TSNE`. Also proposes two custom nearest neighbors estimators based on external packages.
- **Caching nearest neighbors**: an example of pipelining `KNeighborsTransformer` and `KNeighborsClassifier` to enable caching of the neighbors graph during a hyper-parameter grid-search.
Neighborhood Components Analysis

Neighborhood Components Analysis (NCA, NeighborhoodComponentsAnalysis) is a distance metric learning algorithm which aims to improve the accuracy of nearest neighbors classification compared to the standard Euclidean distance. The algorithm directly maximizes a stochastic variant of the leave-one-out k-nearest neighbors (KNN) score on the training set. It can also learn a low-dimensional linear projection of data that can be used for data visualization and fast classification.

In the above illustrating figure, we consider some points from a randomly generated dataset. We focus on the stochastic KNN classification of point no. 3. The thickness of a link between sample 3 and another point is proportional to their distance, and can be seen as the relative weight (or probability) that a stochastic nearest neighbor prediction rule would assign to this point. In the original space, sample 3 has many stochastic neighbors from various classes, so the right class is not very likely. However, in the projected space learned by NCA, the only stochastic neighbors with non-negligible weight are from the same class as sample 3, guaranteeing that the latter will be well classified. See the mathematical formulation for more details.

Classification

Combined with a nearest neighbors classifier (KNeighborsClassifier), NCA is attractive for classification because it can naturally handle multi-class problems without any increase in the model size, and does not introduce additional parameters that require fine-tuning by the user.

NCA classification has been shown to work well in practice for data sets of varying size and difficulty. In contrast to related methods such as Linear Discriminant Analysis, NCA does not make any assumptions about the class distributions. The nearest neighbor classification can naturally produce highly irregular decision boundaries.

To use this model for classification, one needs to combine a NeighborhoodComponentsAnalysis instance that learns the optimal transformation with a KNeighborsClassifier instance that performs the classification in the projected space. Here is an example using the two classes:

```python
>>> from sklearn.neighbors import NeighborhoodComponentsAnalysis, ...
    KNeighborsClassifier
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.pipeline import Pipeline

>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, ...
    stratify=y, test_size=0.7, random_state=42)
>>> nca = NeighborhoodComponentsAnalysis(random_state=42)
>>> knn = KNeighborsClassifier(n_neighbors=3)
```
>>> nca_pipe = Pipeline([('nca', nca), ('knn', knn)])
>>> nca_pipe.fit(X_train, y_train)
Pipeline(...)
>>> print(nca_pipe.score(X_test, y_test))
0.96190476...

The plot shows decision boundaries for Nearest Neighbor Classification and Neighborhood Components Analysis classification on the iris dataset, when training and scoring on only two features, for visualisation purposes.

**Dimensionality reduction**

NCA can be used to perform supervised dimensionality reduction. The input data are projected onto a linear subspace consisting of the directions which minimize the NCA objective. The desired dimensionality can be set using the parameter `n_components`. For instance, the following figure shows a comparison of dimensionality reduction with Principal Component Analysis (`PCA`), Linear Discriminant Analysis (`LinearDiscriminantAnalysis`) and Neighborhood Component Analysis (`NeighborhoodComponentsAnalysis`) on the Digits dataset, a dataset with size \( n_{\text{samples}} = 1797 \) and \( n_{\text{features}} = 64 \). The data set is split into a training and a test set of equal size, then standardized. For evaluation the 3-nearest neighbor classification accuracy is computed on the 2-dimensional projected points found by each method. Each data sample belongs to one of 10 classes.

**Examples:**

- *Comparing Nearest Neighbors with and without Neighborhood Components Analysis*
- *Dimensionality Reduction with Neighborhood Components Analysis*
- *Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...*
Mathematical formulation

The goal of NCA is to learn an optimal linear transformation matrix of size \( (n\_components, n\_features) \), which maximises the sum over all samples \( i \) of the probability \( p_i \) that \( i \) is correctly classified, i.e.:

\[
\arg\max_L N^{-1} \sum_{i=0}^{N-1} p_i
\]

with \( N = n\_samples \) and \( p_i \) the probability of sample \( i \) being correctly classified according to a stochastic nearest neighbors rule in the learned embedded space:

\[
p_i = \sum_{j \in C_i} p_{ij}
\]

where \( C_i \) is the set of points in the same class as sample \( i \), and \( p_{ij} \) is the softmax over Euclidean distances in the embedded space:

\[
p_{ij} = \frac{\exp(-||Lx_i - Lx_j||^2)}{\sum_{k \neq i} \exp(-||Lx_i - Lx_k||^2)}, \quad p_{ii} = 0
\]

Mahalanobis distance

NCA can be seen as learning a (squared) Mahalanobis distance metric:

\[
||L(x_i - x_j)||^2 = (x_i - x_j)^T M (x_i - x_j),
\]

where \( M = L^T L \) is a symmetric positive semi-definite matrix of size \( (n\_features, n\_features) \).

Implementation

This implementation follows what is explained in the original paper\(^1\). For the optimisation method, it currently uses scipy’s L-BFGS-B with a full gradient computation at each iteration, to avoid to tune the learning rate and provide stable learning.

See the examples below and the docstring of \code{NeighborhoodComponentsAnalysis.fit} for further information.

Complexity

Training

NCA stores a matrix of pairwise distances, taking \( n\_samples \times n\_samples \) memory. Time complexity depends on the number of iterations done by the optimisation algorithm. However, one can set the maximum number of iterations with the argument \code{max_iter}. For each iteration, time complexity is \( O(n\_components \times n\_samples \times \min(n\_samples, n\_features)) \).

Transform

Here the transform operation returns \( L^T \), therefore its time complexity equals \( n\_components \times n\_features \times n\_samples\_test \). There is no added space complexity in the operation.

References:

- Wikipedia entry on Neighborhood Components Analysis

4.1.7 Gaussian Processes

Gaussian Processes (GP) are a generic supervised learning method designed to solve regression and probabilistic classification problems.

The advantages of Gaussian processes are:

- The prediction interpolates the observations (at least for regular kernels).
- The prediction is probabilistic (Gaussian) so that one can compute empirical confidence intervals and decide based on those if one should refit (online fitting, adaptive fitting) the prediction in some region of interest.
- Versatile: different kernels can be specified. Common kernels are provided, but it is also possible to specify custom kernels.

The disadvantages of Gaussian processes include:

- They are not sparse, i.e., they use the whole samples/features information to perform the prediction.
- They lose efficiency in high dimensional spaces – namely when the number of features exceeds a few dozens.

Gaussian Process Regression (GPR)

The GaussianProcessRegressor implements Gaussian processes (GP) for regression purposes. For this, the prior of the GP needs to be specified. The prior mean is assumed to be constant and zero (for normalize_y=False) or the training data’s mean (for normalize_y=True). The prior’s covariance is specified by passing a kernel object. The hyperparameters of the kernel are optimized during fitting of GaussianProcessRegressor by maximizing the log-marginal-likelihood (LML) based on the passed optimizer. As the LML may have multiple local optima, the optimizer can be started repeatedly by specifying n_restarts_optimizer. The first run is always conducted starting from the initial hyperparameter values of the kernel; subsequent runs are conducted from hyperparameter values that have been chosen randomly from the range of allowed values. If the initial hyperparameters should be kept fixed, None can be passed as optimizer.

The noise level in the targets can be specified by passing it via the parameter alpha, either globally as a scalar or per datapoint. Note that a moderate noise level can also be helpful for dealing with numeric issues during fitting as it is effectively implemented as Tikhonov regularization, i.e., by adding it to the diagonal of the kernel matrix. An alternative to specifying the noise level explicitly is to include a WhiteKernel component into the kernel, which can estimate the global noise level from the data (see example below).

The implementation is based on Algorithm 2.1 of [RW2006]. In addition to the API of standard scikit-learn estimators, GaussianProcessRegressor:

- allows prediction without prior fitting (based on the GP prior)
- provides an additional method sample_y(X), which evaluates samples drawn from the GPR (prior or posterior) at given inputs
- exposes a method `log_marginal_likelihood(theta)`, which can be used externally for other ways of selecting hyperparameters, e.g., via Markov chain Monte Carlo.

**GPR examples**

**GPR with noise-level estimation**

This example illustrates that GPR with a sum-kernel including a WhiteKernel can estimate the noise level of data. An illustration of the log-marginal-likelihood (LML) landscape shows that there exist two local maxima of LML.

\[
\text{Initial: } 1^{**2} \times \text{RBF(length\_scale=100)} + \text{WhiteKernel(noise\_level=1)}
\]

\[
\text{Optimum: } 0.00316^{**2} \times \text{RBF(length\_scale=109)} + \text{WhiteKernel(noise\_level=1)}
\]

\[
\text{Log-Marginal-Likelihood: } -23.87233736198489
\]

The first corresponds to a model with a high noise level and a large length scale, which explains all variations in the data by noise.

The second one has a smaller noise level and shorter length scale, which explains most of the variation by the noise-free functional relationship. The second model has a higher likelihood; however, depending on the initial value for the hyperparameters, the gradient-based optimization might also converge to the high-noise solution. It is thus important to repeat the optimization several times for different initializations.
Initial: $1^{*2} \times \text{RBF}(\text{length\_scale}=1) + \text{WhiteKernel}(\text{noise\_level}=1e-05)$
Optimum: $0.64^{*2} \times \text{RBF}(\text{length\_scale}=0.365) + \text{WhiteKernel}(\text{noise\_level}=0)$
Log-Marginal-Likelihood: $-21.805090890162035$
Comparison of GPR and Kernel Ridge Regression

Both kernel ridge regression (KRR) and GPR learn a target function by employing internally the “kernel trick”. KRR learns a linear function in the space induced by the respective kernel which corresponds to a non-linear function in the original space. The linear function in the kernel space is chosen based on the mean-squared error loss with ridge regularization. GPR uses the kernel to define the covariance of a prior distribution over the target functions and uses the observed training data to define a likelihood function. Based on Bayes theorem, a (Gaussian) posterior distribution over target functions is defined, whose mean is used for prediction.

A major difference is that GPR can choose the kernel’s hyperparameters based on gradient-ascent on the marginal likelihood function while KRR needs to perform a grid search on a cross-validated loss function (mean-squared error loss). A further difference is that GPR learns a generative, probabilistic model of the target function and can thus provide meaningful confidence intervals and posterior samples along with the predictions while KRR only provides predictions.

The following figure illustrates both methods on an artificial dataset, which consists of a sinusoidal target function and strong noise. The figure compares the learned model of KRR and GPR based on a ExpSineSquared kernel, which is suited for learning periodic functions. The kernel’s hyperparameters control the smoothness (length_scale) and periodicity of the kernel (periodicity). Moreover, the noise level of the data is learned explicitly by GPR by an additional WhiteKernel component in the kernel and by the regularization parameter alpha of KRR.

The figure shows that both methods learn reasonable models of the target function. GPR correctly identifies the periodicity of the function to be roughly $2 \times \pi$ (6.28), while KRR chooses the doubled periodicity $4 \times \pi$. Besides that, GPR provides reasonable confidence bounds on the prediction which are not available for KRR. A major difference between the two methods is the time required for fitting and predicting: while fitting KRR is fast in principle, the grid-search for hyperparameter optimization scales exponentially with the number of hyperparameters (“curse of dimensionality”). The gradient-based optimization of the parameters in GPR does not suffer from this exponential scaling and is thus considerably faster on this example with 3-dimensional hyperparameter space. The time for predicting is similar; however, generating the variance of the predictive distribution of GPR takes considerably longer than just predicting the mean.
GPR on Mauna Loa CO2 data

This example is based on Section 5.4.3 of [RW2006]. It illustrates an example of complex kernel engineering and hyperparameter optimization using gradient ascent on the log-marginal-likelihood. The data consists of the monthly average atmospheric CO2 concentrations (in parts per million by volume (ppmv)) collected at the Mauna Loa Observatory in Hawaii, between 1958 and 1997. The objective is to model the CO2 concentration as a function of the time t.

The kernel is composed of several terms that are responsible for explaining different properties of the signal:

- a long term, smooth rising trend is to be explained by an RBF kernel. The RBF kernel with a large length-scale enforces this component to be smooth; it is not enforced that the trend is rising which leaves this choice to the GP. The specific length-scale and the amplitude are free hyperparameters.

- a seasonal component, which is to be explained by the periodic ExpSineSquared kernel with a fixed periodicity of 1 year. The length-scale of this periodic component, controlling its smoothness, is a free parameter. In order to allow decaying away from exact periodicity, the product with an RBF kernel is taken. The length-scale of this RBF component controls the decay time and is a further free parameter.

- smaller, medium term irregularities are to be explained by a RationalQuadratic kernel component, whose length-scale and alpha parameter, which determines the diffuseness of the length-scales, are to be determined. According to [RW2006], these irregularities can better be explained by a RationalQuadratic than an RBF kernel component, probably because it can accommodate several length-scales.

- a “noise” term, consisting of an RBF kernel contribution, which shall explain the correlated noise components such as local weather phenomena, and a WhiteKernel contribution for the white noise. The relative amplitudes and the RBF’s length scale are further free parameters.

Maximizing the log-marginal-likelihood after subtracting the target’s mean yields the following kernel with an LML of -83.214:

\[
34.4^{\times 2} \times RBF(length\_scale=41.8) \\
+ 3.27^{\times 2} \times RBF(length\_scale=180) \times ExpSineSquared(length\_scale=1.44, \text{periodicity}=1) \\
+ 0.446^{\times 2} \times RationalQuadratic(alpha=17.7, length\_scale=0.957) \\
+ 0.197^{\times 2} \times RBF(length\_scale=0.138) \times WhiteKernel(noise\_level=0.0336)
\]

Thus, most of the target signal (34.4ppm) is explained by a long-term rising trend (length-scale 41.8 years). The periodic component has an amplitude of 3.27ppm, a decay time of 180 years and a length-scale of 1.44. The long decay time indicates that we have a locally very close to periodic seasonal component. The correlated noise has an amplitude of 0.197ppm with a length scale of 0.138 years and a white-noise contribution of 0.197ppm. Thus, the overall noise level is very small, indicating that the data can be very well explained by the model. The figure shows also that the model makes very confident predictions until around 2015.

Gaussian Process Classification (GPC)

The GaussianProcessClassifier implements Gaussian processes (GP) for classification purposes, more specifically for probabilistic classification, where test predictions take the form of class probabilities. GaussianProcessClassifier places a GP prior on a latent function \( f \), which is then squashed through a link function to obtain the probabilistic classification. The latent function \( f \) is a so-called nuisance function, whose values are not observed and are not relevant by themselves. Its purpose is to allow a convenient formulation of the model, and \( f \) is removed (integrated out) during prediction. GaussianProcessClassifier implements the logistic link function, for which the integral cannot be computed analytically but is easily approximated in the binary case.

In contrast to the regression setting, the posterior of the latent function \( f \) is not Gaussian even for a GP prior since a Gaussian likelihood is inappropriate for discrete class labels. Rather, a non-Gaussian likelihood corresponding to
Atmospheric CO₂ concentration at Mauna Loa

Year

CO₂ in ppm

the logistic link function (logit) is used. GaussianProcessClassifier approximates the non-Gaussian posterior with a Gaussian based on the Laplace approximation. More details can be found in Chapter 3 of [RW2006].

The GP prior mean is assumed to be zero. The prior’s covariance is specified by passing a kernel object. The hyperparameters of the kernel are optimized during fitting of GaussianProcessRegressor by maximizing the log-marginal-likelihood (LML) based on the passed optimizer. As the LML may have multiple local optima, the optimizer can be started repeatedly by specifying n_restarts_optimizer. The first run is always conducted starting from the initial hyperparameter values of the kernel; subsequent runs are conducted from hyperparameter values that have been chosen randomly from the range of allowed values. If the initial hyperparameters should be kept fixed, None can be passed as optimizer.

GaussianProcessClassifier supports multi-class classification by performing either one-versus-rest or one-versus-one based training and prediction. In one-versus-rest, one binary Gaussian process classifier is fitted for each class, which is trained to separate this class from the rest. In “one_vs_one”, one binary Gaussian process classifier is fitted for each pair of classes, which is trained to separate these two classes. The predictions of these binary predictors are combined into multi-class predictions. See the section on multi-class classification for more details.

In the case of Gaussian process classification, “one_vs_one” might be computationally cheaper since it has to solve many problems involving only a subset of the whole training set rather than fewer problems on the whole dataset. Since Gaussian process classification scales cubically with the size of the dataset, this might be considerably faster. However, note that “one_vs_one” does not support predicting probability estimates but only plain predictions. Moreover, note that GaussianProcessClassifier does not (yet) implement a true multi-class Laplace approximation internally, but as discussed above is based on solving several binary classification tasks internally, which are combined using one-versus-rest or one-versus-one.

**GPC examples**

**Probabilistic predictions with GPC**

This example illustrates the predicted probability of GPC for an RBF kernel with different choices of the hyperparameters. The first figure shows the predicted probability of GPC with arbitrarily chosen hyperparameters and with the hyperparameters corresponding to the maximum log-marginal-likelihood (LML).

While the hyperparameters chosen by optimizing LML have a considerably larger LML, they perform slightly worse according to the log-loss on test data. The figure shows that this is because they exhibit a steep change of the class probabilities at the class boundaries (which is good) but have predicted probabilities close to 0.5 far away from the class boundaries (which is bad) This undesirable effect is caused by the Laplace approximation used internally by GPC.

The second figure shows the log-marginal-likelihood for different choices of the kernel’s hyperparameters, highlighting the two choices of the hyperparameters used in the first figure by black dots.

**Illustration of GPC on the XOR dataset**

This example illustrates GPC on XOR data. Compared are a stationary, isotropic kernel (RBF) and a non-stationary kernel (DotProduct). On this particular dataset, the DotProduct kernel obtains considerably better results because the class-boundaries are linear and coincide with the coordinate axes. In practice, however, stationary kernels such as RBF often obtain better results.
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Gaussian process classification (GPC) on iris dataset

This example illustrates the predicted probability of GPC for an isotropic and anisotropic RBF kernel on a two-dimensional version for the iris-dataset. This illustrates the applicability of GPC to non-binary classification. The anisotropic RBF kernel obtains slightly higher log-marginal-likelihood by assigning different length-scales to the two feature dimensions.

Kernels for Gaussian Processes

Kernels (also called “covariance functions” in the context of GPs) are a crucial ingredient of GPs which determine the shape of prior and posterior of the GP. They encode the assumptions on the function being learned by defining the “similarity” of two datapoints combined with the assumption that similar datapoints should have similar target values. Two categories of kernels can be distinguished: stationary kernels depend only on the distance of two datapoints and not on their absolute values $k(x_i, x_j) = k(d(x_i, x_j))$ and are thus invariant to translations in the input space, while non-stationary kernels depend also on the specific values of the datapoints. Stationary kernels can further be subdivided into isotropic and anisotropic kernels, where isotropic kernels are also invariant to rotations in the input space. For more details, we refer to Chapter 4 of [RW2006]. For guidance on how to best combine different kernels, we refer to [Duv2014].

Gaussian Process Kernel API

The main usage of a Kernel is to compute the GP’s covariance between datapoints. For this, the method __call__ of the kernel can be called. This method can either be used to compute the “auto-covariance” of all pairs of datapoints in a 2d array $X$, or the “cross-covariance” of all combinations of datapoints of a 2d array $X$ with datapoints in a 2d array $Y$. The following identity holds true for all kernels $k$ (except for the WhiteKernel): $k(X) == K(X, Y=X)$

If only the diagonal of the auto-covariance is being used, the method diag() of a kernel can be called, which is more computationally efficient than the equivalent call to __call__: $np.diag(k(X, X)) == k.diag(X)$

Kernels are parameterized by a vector $\theta$ of hyperparameters. These hyperparameters can for instance control length-scales or periodicity of a kernel (see below). All kernels support computing analytic gradients of the kernel’s auto-covariance with respect to $log(\theta)$ via setting eval_gradient=True in the __call__ method. That is,
a \( (\text{len}(X), \text{len}(X), \text{len}(\text{theta})) \) array is returned where the entry \([i, j, l]\) contains \( \frac{\partial^2 k_i(x_i, x_j)}{\partial \log(\theta_l)} \). This gradient is used by the Gaussian process (both regressor and classifier) in computing the gradient of the log-marginal-likelihood, which in turn is used to determine the value of \( \theta \), which maximizes the log-marginal-likelihood, via gradient ascent. For each hyperparameter, the initial value and the bounds need to be specified when creating an instance of the kernel. The current value of \( \theta \) can be get and set via the property \text{theta} of the kernel object. Moreover, the bounds of the hyperparameters can be accessed by the property \text{bounds} of the kernel. Note that both properties (theta and bounds) return log-transformed values of the internally used values since those are typically more amenable to gradient-based optimization. The specification of each hyperparameter is stored in the form of an instance of \text{Hyperparameter} in the respective kernel. Note that a kernel using a hyperparameter with name “\text{x}” must have the attributes self.x and self.x_bounds.

The abstract base class for all kernels is \text{Kernel}. Kernel implements a similar interface as \text{Estimator}, providing the methods \text{get params()}, \text{set params()}, and \text{clone()}. This allows setting kernel values also via meta-estimators such as \text{Pipeline} or \text{GridSearch}. Note that due to the nested structure of kernels (by applying kernel operators, see below), the names of kernel parameters might become relatively complicated. In general, for a binary kernel operator, parameters of the left operand are prefixed with \text{k1__} and parameters of the right operand with \text{k2__}.

An additional convenience method is \text{clone_with theta(theta)}, which returns a cloned version of the kernel but with the hyperparameters set to \text{theta}. An illustrative example:

```python
>>> from sklearn.gaussian_process.kernels import ConstantKernel, RBF
>>> kernel = ConstantKernel(constant_value=1.0, constant_value_bounds=(0.0, 10.0)) *
    -RBF(length_scale=0.5, length_scale_bounds=(0.0, 10.0)) + RBF(length_scale=2.0,
    -length_scale_bounds=(0.0, 10.0))
>>> for hyperparameter in kernel.hyperparameters: print(hyperparameter)
Hyperparameter(name='k1__k1__constant_value', value_type='numeric', bounds=array([[ 0., 10.]]), n_elements=1, fixed=False)
Hyperparameter(name='k1__k2__length_scale', value_type='numeric', bounds=array([[ 0., 10.]]), n_elements=1, fixed=False)
Hyperparameter(name='k2__length_scale', value_type='numeric', bounds=array([[ 0., 10.]]), n_elements=1, fixed=False)
>>> params = kernel.get_params()
>>> for key in sorted(params): print("%s : %s % (key, params[key])")
k1 : 1**2 * RBF(length_scale=0.5)
k1__k1 : 1**2
k1__k1__constant_value : 1.0
k1__k1__constant_value_bounds : (0.0, 10.0)
k1__k2 : RBF(length_scale=0.5)
k1__k2__length_scale : 0.5
k1__k2__length_scale_bounds : (0.0, 10.0)
k2 : RBF(length_scale=2)
k2__length_scale : 2.0
k2__length_scale_bounds : (0.0, 10.0)
>>> print(kernel.theta) # Note: log-transformed
[ 0. -0.69314718 0.69314718]
>>> print(kernel.bounds) # Note: log-transformed
[[ -inf 2.30258509]
 [ -inf 2.30258509]
 [ -inf 2.30258509]]
```

All Gaussian process kernels are interoperable with \text{sklearn.metrics.pairwise} and vice versa: instances of subclasses of \text{Kernel} can be passed as metric to \text{pairwise_kernels} from \text{sklearn.metrics.pairwise}. Moreover, kernel functions from pairwise can be used as GP kernels by using the wrapper class \text{PairwiseKernel}. The only caveat is that the gradient of the hyperparameters is not analytic but numeric and all those kernels support only isotropic distances. The parameter \text{gamma} is considered to be a hyperparameter and may be optimized. The other kernel parameters are set directly at initialization and are kept fixed.
Basic kernels

The `ConstantKernel` kernel can be used as part of a `Product` kernel where it scales the magnitude of the other factor (kernel) or as part of a `Sum` kernel, where it modifies the mean of the Gaussian process. It depends on a parameter `constant_value`. It is defined as:

\[ k(x_i, x_j) = constant_value \forall x_1, x_2 \]

The main use-case of the `WhiteKernel` kernel is as part of a sum-kernel where it explains the noise-component of the signal. Tuning its parameter `noise_level` corresponds to estimating the noise-level. It is defined as:

\[ k(x_i, x_j) = noise_level \text{ if } x_i == x_j \text{ else } 0 \]

Kernel operators

Kernel operators take one or two base kernels and combine them into a new kernel. The `Sum` kernel takes two kernels \(k_1\) and \(k_2\) and combines them via \(k_{\text{sum}}(X,Y) = k_1(X,Y) + k_2(X,Y)\). The `Product` kernel takes two kernels \(k_1\) and \(k_2\) and combines them via \(k_{\text{product}}(X,Y) = k_1(X,Y) \times k_2(X,Y)\). The `Exponentiation` kernel takes one base kernel and a scalar parameter \(p\) and combines them via \(k_{\text{exp}}(X,Y) = k(X,Y)^p\). Note that magic methods `__add__`, `__mul__` and `__pow__` are overridden on the Kernel objects, so one can use e.g. `RBF() + RBF()` as a shortcut for `Sum(RBF(), RBF())`.

Radial-basis function (RBF) kernel

The `RBF` kernel is a stationary kernel. It is also known as the “squared exponential” kernel. It is parameterized by a length-scale parameter \(l > 0\), which can either be a scalar (isotropic variant of the kernel) or a vector with the same number of dimensions as the inputs \(x\) (anisotropic variant of the kernel). The kernel is given by:

\[ k(x_i, x_j) = \exp \left( -\frac{d(x_i, x_j)^2}{2l^2} \right) \]

where \(d(\cdot, \cdot)\) is the Euclidean distance. This kernel is infinitely differentiable, which implies that GPs with this kernel as covariance function have mean square derivatives of all orders, and are thus very smooth. The prior and posterior of a GP resulting from an RBF kernel are shown in the following figure:

Matérn kernel

The `Matern` kernel is a stationary kernel and a generalization of the `RBF` kernel. It has an additional parameter \(\nu\) which controls the smoothness of the resulting function. It is parameterized by a length-scale parameter \(l > 0\), which can either be a scalar (isotropic variant of the kernel) or a vector with the same number of dimensions as the inputs \(x\) (anisotropic variant of the kernel). The kernel is given by:

\[ k(x_i, x_j) = \frac{1}{\Gamma(\nu)2^{\nu-1}} \left( \frac{\sqrt{2\nu}d(x_i, x_j)}{l} \right)^\nu K_\nu \left( \frac{\sqrt{2\nu}d(x_i, x_j)}{l} \right), \]

where \(d(\cdot, \cdot)\) is the Euclidean distance, \(K_\nu(\cdot)\) is a modified Bessel function and \(\Gamma(\cdot)\) is the gamma function. As \(\nu \to \infty\), the Matérn kernel converges to the RBF kernel. When \(\nu = 1/2\), the Matérn kernel becomes identical to the absolute exponential kernel, i.e.,

\[ k(x_i, x_j) = \exp \left( -\frac{1}{l}d(x_i, x_j) \right) \quad \nu = \frac{1}{2} \]

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In particular, $\nu = 3/2$:

$$k(x_i, x_j) = \left(1 + \frac{\sqrt{3}}{l}d(x_i, x_j)\right) \exp\left(-\frac{\sqrt{3}}{l}d(x_i, x_j)\right) \quad \nu = \frac{3}{2}$$

and $\nu = 5/2$:

$$k(x_i, x_j) = \left(1 + \frac{\sqrt{5}}{l}d(x_i, x_j) + \frac{5}{3l^2}d(x_i, x_j)^2\right) \exp\left(-\frac{\sqrt{5}}{l}d(x_i, x_j)\right) \quad \nu = \frac{5}{2}$$

are popular choices for learning functions that are not infinitely differentiable (as assumed by the RBF kernel) but at least once ($\nu = 3/2$) or twice differentiable ($\nu = 5/2$).

The flexibility of controlling the smoothness of the learned function via $\nu$ allows adapting to the properties of the true underlying functional relation. The prior and posterior of a GP resulting from a Matérn kernel are shown in the following figure:

See [RW2006], pp84 for further details regarding the different variants of the Matérn kernel.

**Rational quadratic kernel**

The `RationalQuadratic` kernel can be seen as a scale mixture (an infinite sum) of RBF kernels with different characteristic length-scales. It is parameterized by a length-scale parameter $l > 0$ and a scale mixture parameter $\alpha > 0$.

Only the isotropic variant where $l$ is a scalar is supported at the moment. The kernel is given by:

$$k(x_i, x_j) = \left(1 + \frac{d(x_i, x_j)^2}{2\alpha l^2}\right)^{-\alpha}$$

The prior and posterior of a GP resulting from a `RationalQuadratic` kernel are shown in the following figure:

**Exp-Sine-Squared kernel**

The `ExpSineSquared` kernel allows modeling periodic functions. It is parameterized by a length-scale parameter $l > 0$ and a periodicity parameter $p > 0$. Only the isotropic variant where $l$ is a scalar is supported at the moment. The kernel is given by:

$$k(x_i, x_j) = \exp\left(-\frac{2\sin^2(\pi d(x_i, x_j)/p)}{l^2}\right)$$

The prior and posterior of a GP resulting from an ExpSineSquared kernel are shown in the following figure:

**Dot-Product kernel**

The `DotProduct` kernel is non-stationary and can be obtained from linear regression by putting $N(0, 1)$ priors on the coefficients of $x_d(d = 1, \ldots, D)$ and a prior of $N(0, \sigma_0^2)$ on the bias. The `DotProduct` kernel is invariant to a rotation of the coordinates about the origin, but not translations. It is parameterized by a parameter $\sigma_0^2$. For $\sigma_0^2 = 0$, the kernel is called the homogeneous linear kernel, otherwise it is inhomogeneous. The kernel is given by

$$k(x_i, x_j) = \sigma_0^2 + x_i \cdot x_j$$

The `DotProduct` kernel is commonly combined with exponentiation. An example with exponent 2 is shown in the following figure:
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Prior (kernel: $1 \times 2 \times \text{RationalQuadratic}(\alpha=0.1, \text{length\_scale}=1))$

Posterior (kernel: $0.594 \times 2 \times \text{RationalQuadratic}(\alpha=1e+05, \text{length\_scale}=0.279))$

Log-Likelihood: -0.067
4.1. Supervised learning
References

4.1.8 Cross decomposition

The cross decomposition module contains supervised estimators for dimensionality reduction and regression, belonging to the “Partial Least Squares” family.

Cross decomposition algorithms find the fundamental relations between two matrices (X and Y). They are latent variable approaches to modeling the covariance structures in these two spaces. They will try to find the multidimensional direction in the X space that explains the maximum multidimensional variance direction in the Y space. In other words, PLS projects both X and Y into a lower-dimensional subspace such that the covariance between transformed(X) and transformed(Y) is maximal.

PLS draws similarities with Principal Component Regression (PCR), where the samples are first projected into a lower-dimensional subspace, and the targets y are predicted using transformed(X). One issue with PCR is that the dimensionality reduction is unsupervised, and may lose some important variables: PCR would keep the features with the most variance, but it’s possible that features with a small variances are relevant from predicting the target. In a way, PLS allows for the same kind of dimensionality reduction, but by taking into account the targets y. An illustration of this fact is given in the following example: *Principal Component Regression vs Partial Least Squares Regression.*

Apart from CCA, the PLS estimators are particularly suited when the matrix of predictors has more variables than observations, and when there is multicollinearity among the features. By contrast, standard linear regression would fail in these cases unless it is regularized.

Classes included in this module are PLSRegression, PLSCanonical, CCA and PLSSVD
PLSCanonical

We here describe the algorithm used in PLSCanonical. The other estimators use variants of this algorithm, and are detailed below. We recommend section 1 for more details and comparisons between these algorithms. PLSCanonical corresponds to “PLSW2A”.

Given two centered matrices $X \in \mathbb{R}^{n \times d}$ and $Y \in \mathbb{R}^{n \times t}$, and a number of components $K$, PLSCanonical proceeds as follows:

Set $X_1$ to $X$ and $Y_1$ to $Y$. Then, for each $k \in [1, K]$:

- a) compute $u_k \in \mathbb{R}^d$ and $v_k \in \mathbb{R}^t$, the first left and right singular vectors of the cross-covariance matrix $C = X_k^T Y_k$. $u_k$ and $v_k$ are called the weights. By definition, $u_k$ and $v_k$ are choosen so that they maximize the covariance between the projected $X_k$ and the projected target, that is $\text{Cov}(X_k u_k, Y_k v_k)$.

- b) Project $X_k$ and $Y_k$ on the singular vectors to obtain scores: $\xi_k = X_k u_k$ and $\omega_k = Y_k v_k$

- c) Regress $X_k$ on $\xi_k$, i.e. find a vector $\gamma_k \in \mathbb{R}^d$ such that the rank-1 matrix $\xi_k \gamma_k^T$ is as close as possible to $X_k$. Do the same on $Y_k$ with $\omega_k$ to obtain $\delta_k$. The vectors $\gamma_k$ and $\delta_k$ are called the loadings.

- d) deflate $X_k$ and $Y_k$, i.e. subtract the rank-1 approximations: $X_{k+1} = X_k - \xi_k \gamma_k^T$ and $Y_{k+1} = Y_k - \omega_k \delta_k^T$.

At the end, we have approximated $X$ as a sum of rank-1 matrices: $X = \Xi \Gamma^T$ where $\Xi \in \mathbb{R}^{n \times K}$ contains the scores in its columns, and $\Gamma^T \in \mathbb{R}^{K \times d}$ contains the loadings in its rows. Similarly for $Y$, we have $Y = \Omega \Delta^T$.

Note that the scores matrices $\Xi$ and $\Omega$ correspond to the projections of the training data $X$ and $Y$, respectively.

Step a) may be performed in two ways: either by computing the whole SVD of $C$ and only retain the singular vectors with the biggest singular values, or by directly computing the singular vectors using the power method (cf section 11.3 in\textsuperscript{1}), which corresponds to the ‘nipals’ option of the algorithm parameter.

Transforming data

To transform $X$ into $\hat{X}$, we need to find a projection matrix $P$ such that $\hat{X} = XP$. We know that for the training data, $\Xi = XP$, and $X = \Xi \Gamma^T$. Setting $P = U(\Gamma^T U)^{-1}$ where $U$ is the matrix with the $u_k$ in the columns, we have $XP = XU(\Gamma^T U)^{-1} = \Xi(\Gamma^T U)(\Gamma^T U)^{-1} = \Xi$ as desired. The rotation matrix $P$ can be accessed from the \texttt{x\_rotations\_attribute}.

Similarly, $Y$ can be transformed using the rotation matrix $V(\Delta^T V)^{-1}$, accessed via the \texttt{y\_rotations\_attribute}.

Predicting the targets $Y$

To predict the targets of some data $X$, we are looking for a coefficient matrix $\beta \in \mathbb{R}^{d \times t}$ such that $Y = X \beta$.

The idea is to try to predict the transformed targets $\Omega$ as a function of the transformed samples $\Xi$, by computing $\alpha \in \mathbb{R}$ such that $\Omega = \alpha \Xi$.

Then, we have $Y = \Omega \Delta^T = \alpha \Xi \Delta^T$, and since $\Xi$ is the transformed training data we have that $Y = X \alpha P \Delta^T$, and as a result the coefficient matrix $\beta = \alpha P \Delta^T$.

$\beta$ can be accessed through the \texttt{coef\_attribute}.

\textsuperscript{1} A survey of Partial Least Squares (PLS) methods, with emphasis on the two-block case J.A. Wegelin
PLSSVD

PLSSVD is a simplified version of PLSCanonical described earlier: instead of iteratively deflating the matrices $X_k$ and $Y_k$, PLSSVD computes the SVD of $C = X^TY$ only once, and stores the n_components singular vectors corresponding to the biggest singular values in the matrices $U$ and $V$, corresponding to the x_weights_ and y_weights_ attributes. Here, the transformed data is simply $\text{transformed}(X) = XU$ and $\text{transformed}(Y) = YV$.

If n_components == 1, PLSSVD and PLSCanonical are strictly equivalent.

PLSRegression

The PLSRegression estimator is similar to PLSCanonical with algorithm='nipals', with 2 significant differences:

- at step a) in the power method to compute $u_k$ and $v_k$, $v_k$ is never normalized.
- at step c), the targets $Y_k$ are approximated using the projection of $X_k$ (i.e. $\xi_k$) instead of the projection of $Y_k$ (i.e. $\omega_k$). In other words, the loadings computation is different. As a result, the deflation in step d) will also be affected.

These two modifications affect the output of predict and transform, which are not the same as for PLSCanonical. Also, while the number of components is limited by min(n_samples, n_features, n_targets) in PLSCanonical, here the limit is the rank of $X^TX$, i.e. min(n_samples, n_features).

PLSRegression is also known as PLS1 (single targets) and PLS2 (multiple targets). Much like Lasso, PLSRegression is a form of regularized linear regression where the number of components controls the strength of the regularization.

Canonical Correlation Analysis

Canonical Correlation Analysis was developed prior and independently to PLS. But it turns out that CCA is a special case of PLS, and corresponds to PLS in “Mode B” in the literature.

CCA differs from PLSCanonical in the way the weights $u_k$ and $v_k$ are computed in the power method of step a). Details can be found in section 10 of\(^1\).

Since CCA involves the inversion of $X_k^TX_k$ and $Y_k^TY_k$, this estimator can be unstable if the number of features or targets is greater than the number of samples.

Reference:

Examples:

- Compare cross decomposition methods
- Principal Component Regression vs Partial Least Squares Regression
4.1.9 Naive Bayes

Naive Bayes methods are a set of supervised learning algorithms based on applying Bayes’ theorem with the “naive” assumption of conditional independence between every pair of features given the value of the class variable. Bayes’ theorem states the following relationship, given class variable $y$ and dependent feature vector $x_1$ through $x_n$:

$$P(y \mid x_1, \ldots, x_n) = \frac{P(y)P(x_1, \ldots, x_n \mid y)}{P(x_1, \ldots, x_n)}$$

Using the naive conditional independence assumption that

$$P(x_i \mid y, x_1, \ldots, x_i-1, x_{i+1}, \ldots, x_n) = P(x_i \mid y),$$

for all $i$, this relationship is simplified to

$$P(y \mid x_1, \ldots, x_n) = \frac{P(y) \prod_{i=1}^{n} P(x_i \mid y)}{P(x_1, \ldots, x_n)}$$

Since $P(x_1, \ldots, x_n)$ is constant given the input, we can use the following classification rule:

$$P(y \mid x_1, \ldots, x_n) \propto P(y) \prod_{i=1}^{n} P(x_i \mid y)$$

$$\downarrow$$

$$\hat{y} = \arg \max_y P(y) \prod_{i=1}^{n} P(x_i \mid y),$$

and we can use Maximum A Posteriori (MAP) estimation to estimate $P(y)$ and $P(x_i \mid y)$; the former is then the relative frequency of class $y$ in the training set.

The different naive Bayes classifiers differ mainly by the assumptions they make regarding the distribution of $P(x_i \mid y)$.

In spite of their apparently over-simplified assumptions, naive Bayes classifiers have worked quite well in many real-world situations, famously document classification and spam filtering. They require a small amount of training data to estimate the necessary parameters. (For theoretical reasons why naive Bayes works well, and on which types of data it does, see the references below.)

Naive Bayes learners and classifiers can be extremely fast compared to more sophisticated methods. The decoupling of the class conditional feature distributions means that each distribution can be independently estimated as a one dimensional distribution. This in turn helps to alleviate problems stemming from the curse of dimensionality.

On the flip side, although naive Bayes is known as a decent classifier, it is known to be a bad estimator, so the probability outputs from `predict_proba` are not to be taken too seriously.

References:

Gaussian Naive Bayes

`GaussianNB` implements the Gaussian Naive Bayes algorithm for classification. The likelihood of the features is assumed to be Gaussian:

\[
P(x_i \mid y) = \frac{1}{\sqrt{2\pi\sigma_y^2}} \exp\left(-\frac{(x_i - \mu_y)^2}{2\sigma_y^2}\right)
\]

The parameters \(\sigma_y\) and \(\mu_y\) are estimated using maximum likelihood.

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.naive_bayes import GaussianNB

>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.5, random_state=0)
>>> gnb = GaussianNB()
>>> y_pred = gnb.fit(X_train, y_train).predict(X_test)
>>> print("Number of mislabeled points out of a total %d points : %d"
... % (X_test.shape[0], (y_test != y_pred).sum()))
Number of mislabeled points out of a total 75 points : 4
```

Multinomial Naive Bayes

`MultinomialNB` implements the naive Bayes algorithm for multinomially distributed data, and is one of the two classic naive Bayes variants used in text classification (where the data are typically represented as word vector counts, although tf-idf vectors are also known to work well in practice). The distribution is parametrized by vectors \(\theta_y = (\theta_{y_1}, \ldots, \theta_{y_n})\) for each class \(y\), where \(n\) is the number of features (in text classification, the size of the vocabulary) and \(\theta_{yi}\) is the probability \(P(x_i \mid y)\) of feature \(i\) appearing in a sample belonging to class \(y\).

The parameters \(\theta_y\) is estimated by a smoothed version of maximum likelihood, i.e. relative frequency counting:

\[
\hat{\theta}_{yi} = \frac{N_{yi} + \alpha}{N_y + \alpha n}
\]

where \(N_{yi} = \sum_{x_i \in T} x_i\) is the number of times feature \(i\) appears in a sample of class \(y\) in the training set \(T\), and \(N_y = \sum_{i=1}^{n} N_{yi}\) is the total count of all features for class \(y\).

The smoothing priors \(\alpha \geq 0\) accounts for features not present in the learning samples and prevents zero probabilities in further computations. Setting \(\alpha = 1\) is called Laplace smoothing, while \(\alpha < 1\) is called Lidstone smoothing.

Complement Naive Bayes

`ComplementNB` implements the complement naive Bayes (CNB) algorithm. CNB is an adaptation of the standard multinomial naive Bayes (MNB) algorithm that is particularly suited for imbalanced data sets. Specifically, CNB uses statistics from the complement of each class to compute the model’s weights. The inventors of CNB show empirically that the parameter estimates for CNB are more stable than those for MNB. Further, CNB regularly outperforms MNB (often by a considerable margin) on text classification tasks. The procedure for calculating the weights is as follows:

\[
\hat{\theta}_{ci} = \frac{\alpha_i + \sum_{j:y_j \neq c} d_{ij}}{\alpha + \sum_{j:y_j \neq c} \sum_k d_{kj}}
\]

\[
w_{ci} = \log \hat{\theta}_{ci}
\]

\[
w_{ci} = \frac{w_{ci}}{\sum_j |w_{cj}|}
\]
where the summations are over all documents \( j \) not in class \( c \), \( d_{ij} \) is either the count or tf-idf value of term \( i \) in document \( j \), \( \alpha_i \) is a smoothing hyperparameter like that found in MNB, and \( \alpha = \sum_i \alpha_i \). The second normalization addresses the tendency for longer documents to dominate parameter estimates in MNB. The classification rule is:

\[
\hat{c} = \arg\min_c \sum_i t_i w_{ci}
\]

i.e., a document is assigned to the class that is the poorest complement match.

References:


Bernoulli Naive Bayes

`BernoulliNB` implements the naive Bayes training and classification algorithms for data that is distributed according to multivariate Bernoulli distributions; i.e., there may be multiple features but each one is assumed to be a binary-valued (Bernoulli, boolean) variable. Therefore, this class requires samples to be represented as binary-valued feature vectors; if handed any other kind of data, a `BernoulliNB` instance may binarize its input (depending on the `binarize` parameter).

The decision rule for Bernoulli naive Bayes is based on

\[
P(x_i \mid y) = P(i \mid y)x_i + (1 - P(i \mid y))(1 - x_i)
\]

which differs from multinomial NB’s rule in that it explicitly penalizes the non-occurrence of a feature \( i \) that is an indicator for class \( y \), where the multinomial variant would simply ignore a non-occurring feature.

In the case of text classification, word occurrence vectors (rather than word count vectors) may be used to train and use this classifier. `BernoulliNB` might perform better on some datasets, especially those with shorter documents. It is advisable to evaluate both models, if time permits.

References:


Categorical Naive Bayes

`CategoricalNB` implements the categorical naive Bayes algorithm for categorically distributed data. It assumes that each feature, which is described by the index \( i \), has its own categorical distribution.

For each feature \( i \) in the training set \( X \), `CategoricalNB` estimates a categorical distribution for each feature \( i \) of \( X \) conditioned on the class \( y \). The index set of the samples is defined as \( J = \{1, \ldots, m\} \), with \( m \) as the number of samples.
The probability of category $t$ in feature $i$ given class $c$ is estimated as:

$$P(x_i = t \mid y = c ; \alpha) = \frac{N_{tic} + \alpha}{N_c + \alpha n_i}$$

where $N_{tic} = |\{j \in J \mid x_{ij} = t, y_j = c\}|$ is the number of times category $t$ appears in the samples $x_i$, which belong to class $c$, $N_c = |\{j \in J \mid y_j = c\}|$ is the number of samples with class $c$, $\alpha$ is a smoothing parameter and $n_i$ is the number of available categories of feature $i$.

*CategoricalNB* assumes that the sample matrix $X$ is encoded (for instance with the help of *OrdinalEncoder*) such that all categories for each feature $i$ are represented with numbers $0, ..., n_i - 1$ where $n_i$ is the number of available categories of feature $i$.

### Out-of-core naive Bayes model fitting

Naive Bayes models can be used to tackle large scale classification problems for which the full training set might not fit in memory. To handle this case, *MultinomialNB*, *BernoulliNB*, and *GaussianNB* expose a `partial_fit` method that can be used incrementally as done with other classifiers as demonstrated in *Out-of-core classification of text documents*. All naive Bayes classifiers support sample weighting.

Contrary to the `fit` method, the first call to `partial_fit` needs to be passed the list of all the expected class labels.

For an overview of available strategies in scikit-learn, see also the *out-of-core learning* documentation.

**Note:** The `partial_fit` method call of naive Bayes models introduces some computational overhead. It is recommended to use data chunk sizes that are as large as possible, that is as the available RAM allows.

### 4.1.10 Decision Trees

**Decision Trees (DTs)** are a non-parametric supervised learning method used for *classification* and *regression*. The goal is to create a model that predicts the value of a target variable by learning simple decision rules inferred from the data features. A tree can be seen as a piecewise constant approximation.

For instance, in the example below, decision trees learn from data to approximate a sine curve with a set of if-then-else decision rules. The deeper the tree, the more complex the decision rules and the fitter the model.

Some advantages of decision trees are:

- Simple to understand and to interpret. Trees can be visualised.
- Requires little data preparation. Other techniques often require data normalisation, dummy variables need to be created and blank values to be removed. Note however that this module does not support missing values.
- The cost of using the tree (i.e., predicting data) is logarithmic in the number of data points used to train the tree.
- Able to handle both numerical and categorical data. However scikit-learn implementation does not support categorical variables for now. Other techniques are usually specialised in analysing datasets that have only one type of variable. See algorithms for more information.
- Able to handle multi-output problems.
- Uses a white box model. If a given situation is observable in a model, the explanation for the condition is easily explained by boolean logic. By contrast, in a black box model (e.g., in an artificial neural network), results may be more difficult to interpret.
- Possible to validate a model using statistical tests. That makes it possible to account for the reliability of the model.
• Performs well even if its assumptions are somewhat violated by the true model from which the data were generated.

The disadvantages of decision trees include:

• Decision-tree learners can create over-complex trees that do not generalise the data well. This is called overfitting. Mechanisms such as pruning, setting the minimum number of samples required at a leaf node or setting the maximum depth of the tree are necessary to avoid this problem.

• Decision trees can be unstable because small variations in the data might result in a completely different tree being generated. This problem is mitigated by using decision trees within an ensemble.

• Predictions of decision trees are neither smooth nor continuous, but piecewise constant approximations as seen in the above figure. Therefore, they are not good at extrapolation.

• The problem of learning an optimal decision tree is known to be NP-complete under several aspects of optimality and even for simple concepts. Consequently, practical decision-tree learning algorithms are based on heuristic algorithms such as the greedy algorithm where locally optimal decisions are made at each node. Such algorithms cannot guarantee to return the globally optimal decision tree. This can be mitigated by training multiple trees in an ensemble learner, where the features and samples are randomly sampled with replacement.

• There are concepts that are hard to learn because decision trees do not express them easily, such as XOR, parity or multiplexer problems.

• Decision tree learners create biased trees if some classes dominate. It is therefore recommended to balance the dataset prior to fitting with the decision tree.
Classification

**DecisionTreeClassifier** is a class capable of performing multi-class classification on a dataset.

As with other classifiers, **DecisionTreeClassifier** takes as input two arrays: an array X, sparse or dense, of shape (n_samples, n_features) holding the training samples, and an array Y of integer values, shape (n_samples,), holding the class labels for the training samples:

```python
>>> from sklearn import tree
>>> X = [[0, 0], [1, 1]]
>>> Y = [0, 1]
>>> clf = tree.DecisionTreeClassifier()
>>> clf = clf.fit(X, Y)
```

After being fitted, the model can then be used to predict the class of samples:

```python
>>> clf.predict([[2., 2.]])
array([1])
```

In case that there are multiple classes with the same and highest probability, the classifier will predict the class with the lowest index amongst those classes.

As an alternative to outputting a specific class, the probability of each class can be predicted, which is the fraction of training samples of the class in a leaf:

```python
>>> clf.predict_proba([[2., 2.]])
array([[0., 1.]])
```

**DecisionTreeClassifier** is capable of both binary (where the labels are [-1, 1]) classification and multiclass (where the labels are [0, ..., K-1]) classification.

Using the Iris dataset, we can construct a tree as follows:

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn import tree

>>> X, y = load_iris(return_X_y=True)

>>> clf = tree.DecisionTreeClassifier()
>>> clf = clf.fit(X, y)
```

Once trained, you can plot the tree with the `plot_tree` function:

```python
>>> tree.plot_tree(clf)
```

We can also export the tree in Graphviz format using the `export_graphviz` exporter. If you use the `conda` package manager, the graphviz binaries and the python package can be installed with `conda install python-graphviz`.

Alternatively binaries for graphviz can be downloaded from the graphviz project homepage, and the Python wrapper installed from pypi with `pip install graphviz`.

Below is an example graphviz export of the above tree trained on the entire iris dataset; the results are saved in an output file `iris.pdf`:

```python
>>> import graphviz

>>> dot_data = tree.export_graphviz(clf, out_file=None)

>>> graph = graphviz.Source(dot_data)

>>> graph.render("Iris")
```
The `export_graphviz` exporter also supports a variety of aesthetic options, including coloring nodes by their class (or value for regression) and using explicit variable and class names if desired. Jupyter notebooks also render these plots inline automatically:

```python
>>> dot_data = tree.export_graphviz(clf, out_file=None,
... feature_names=iris.feature_names,
... class_names=iris.target_names,
... filled=True, rounded=True,
... special_characters=True)
>>> graph = graphviz.Source(dot_data)
>>> graph
```

Alternatively, the tree can also be exported in textual format with the function `export_text`. This method doesn’t require the installation of external libraries and is more compact:

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.tree import DecisionTreeClassifier
>>> from sklearn.tree import export_text

>>> iris = load_iris()

>>> decision_tree = DecisionTreeClassifier(random_state=0, max_depth=2)

>>> decision_tree = decision_tree.fit(iris.data, iris.target)

>>> r = export_text(decision_tree, feature_names=iris['feature_names'])

>>> print(r)

|--- petal width (cm) <= 0.80
|   |-- class: 0
|--- petal width (cm) > 0.80
|   |--- petal width (cm) <= 1.75
|   |   |-- class: 1
|   |--- petal width (cm) > 1.75
|       |-- class: 2
```

4.1. Supervised learning
Decision surface of a decision tree using paired features
Examples:

• Plot the decision surface of a decision tree on the iris dataset
• Understanding the decision tree structure

Regression

Decision trees can also be applied to regression problems, using the `DecisionTreeRegressor` class.
As in the classification setting, the fit method will take as argument arrays X and y, only that in this case y is expected to have floating point values instead of integer values:

```python
>>> from sklearn import tree
>>> X = [[0, 0], [2, 2]]
>>> y = [0.5, 2.5]
>>> clf = tree.DecisionTreeRegressor()
>>> clf = clf.fit(X, y)
>>> clf.predict([[1, 1]])
array([0.5])
```

Examples:

• Decision Tree Regression

4.1. Supervised learning
Multi-output problems

A multi-output problem is a supervised learning problem with several outputs to predict, that is when $Y$ is a 2d array of shape $(n_{\text{samples}}, n_{\text{outputs}})$.

When there is no correlation between the outputs, a very simple way to solve this kind of problem is to build $n$ independent models, i.e. one for each output, and then to use those models to independently predict each one of the $n$ outputs. However, because it is likely that the output values related to the same input are themselves correlated, an often better way is to build a single model capable of predicting simultaneously all $n$ outputs. First, it requires lower training time since only a single estimator is built. Second, the generalization accuracy of the resulting estimator may often be increased.

With regard to decision trees, this strategy can readily be used to support multi-output problems. This requires the following changes:

- Store $n$ output values in leaves, instead of 1;
- Use splitting criteria that compute the average reduction across all $n$ outputs.

This module offers support for multi-output problems by implementing this strategy in both `DecisionTreeClassifier` and `DecisionTreeRegressor`. If a decision tree is fit on an output array $Y$ of shape $(n_{\text{samples}}, n_{\text{outputs}})$ then the resulting estimator will:

- Output $n_{\text{output}}$ values upon `predict`;
- Output a list of $n_{\text{output}}$ arrays of class probabilities upon `predict_proba`.

The use of multi-output trees for regression is demonstrated in `Multi-output Decision Tree Regression`. In this example, the input $X$ is a single real value and the outputs $Y$ are the sine and cosine of $X$.

The use of multi-output trees for classification is demonstrated in `Face completion with a multi-output estimators`. In this example, the inputs $X$ are the pixels of the upper half of faces and the outputs $Y$ are the pixels of the lower half of those faces.
Face completion with multi-output estimators

true faces  Extra trees  K-nn  Linear regression  Ridge
Examples:

- Multi-output Decision Tree Regression
- Face completion with a multi-output estimators

References:


Complexity

In general, the run time cost to construct a balanced binary tree is $O(n_{samples} n_{features} \log(n_{samples}))$ and query time $O(\log(n_{samples}))$. Although the tree construction algorithm attempts to generate balanced trees, they will not always be balanced. Assuming that the subtrees remain approximately balanced, the cost at each node consists of searching through $O(n_{features})$ to find the feature that offers the largest reduction in entropy. This has a cost of $O(n_{features} n_{samples} \log(n_{samples}))$ at each node, leading to a total cost over the entire trees (by summing the cost at each node) of $O(n_{features} n_{samples}^2 \log(n_{samples}))$.

Tips on practical use

- Decision trees tend to overfit on data with a large number of features. Getting the right ratio of samples to number of features is important, since a tree with few samples in high dimensional space is very likely to overfit.

- Consider performing dimensionality reduction (PCA, ICA, or Feature selection) beforehand to give your tree a better chance of finding features that are discriminative.

- Understanding the decision tree structure will help in gaining more insights about how the decision tree makes predictions, which is important for understanding the important features in the data.

- Visualise your tree as you are training by using the export function. Use max_depth=3 as an initial tree depth to get a feel for how the tree is fitting to your data, and then increase the depth.

- Remember that the number of samples required to populate the tree doubles for each additional level the tree grows to. Use max_depth to control the size of the tree to prevent overfitting.

- Use min_samples_split or min_samples_leaf to ensure that multiple samples inform every decision in the tree, by controlling which splits will be considered. A very small number will usually mean the tree will overfit, whereas a large number will prevent the tree from learning the data. Try min_samples_leaf=5 as an initial value. If the sample size varies greatly, a float number can be used as percentage in these two parameters. While min_samples_split can create arbitrarily small leaves, min_samples_leaf guarantees that each leaf has a minimum size, avoiding low-variance, over-fit leaf nodes in regression problems. For classification with few classes, min_samples_leaf=1 is often the best choice.

Note that min_samples_split considers samples directly and independent of sample_weight, if provided (e.g. a node with m weighted samples is still treated as having exactly m samples). Consider min_weight_fraction_leaf or min_impurity_decrease if accounting for sample weights is required at splits.

- Balance your dataset before training to prevent the tree from being biased toward the classes that are dominant. Class balancing can be done by sampling an equal number of samples from each class, or preferably by normalizing the sum of the sample weights (sample_weight) for each class to the same value. Also note that
weight-based pre-pruning criteria, such as `min_weight_fraction_leaf`, will then be less biased toward dominant classes than criteria that are not aware of the sample weights, like `min_samples_leaf`.

- If the samples are weighted, it will be easier to optimize the tree structure using weight-based pre-pruning criterion such as `min_weight_fraction_leaf`, which ensure that leaf nodes contain at least a fraction of the overall sum of the sample weights.

- All decision trees use `np.float32` arrays internally. If training data is not in this format, a copy of the dataset will be made.

- If the input matrix X is very sparse, it is recommended to convert to sparse `csc_matrix` before calling `fit` and sparse `csr_matrix` before calling `predict`. Training time can be orders of magnitude faster for a sparse matrix input compared to a dense matrix when features have zero values in most of the samples.

**Tree algorithms: ID3, C4.5, C5.0 and CART**

What are all the various decision tree algorithms and how do they differ from each other? Which one is implemented in scikit-learn?

**ID3** (Iterative Dichotomiser 3) was developed in 1986 by Ross Quinlan. The algorithm creates a multiway tree, finding for each node (i.e. in a greedy manner) the categorical feature that will yield the largest information gain for categorical targets. Trees are grown to their maximum size and then a pruning step is usually applied to improve the ability of the tree to generalise to unseen data.

C4.5 is the successor to ID3 and removed the restriction that features must be categorical by dynamically defining a discrete attribute (based on numerical variables) that partitions the continuous attribute value into a discrete set of intervals. C4.5 converts the trained trees (i.e. the output of the ID3 algorithm) into sets of if-then rules. These accuracy of each rule is then evaluated to determine the order in which they should be applied. Pruning is done by removing a rule’s precondition if the accuracy of the rule improves without it.

C5.0 is Quinlan’s latest version release under a proprietary license. It uses less memory and builds smaller rulesets than C4.5 while being more accurate.

**CART** (Classification and Regression Trees) is very similar to C4.5, but it differs in that it supports numerical target variables (regression) and does not compute rule sets. CART constructs binary trees using the feature and threshold that yield the largest information gain at each node.

scikit-learn uses an optimised version of the CART algorithm; however, scikit-learn implementation does not support categorical variables for now.

**Mathematical formulation**

Given training vectors \( x_i \in \mathbb{R}^n, i=1,\ldots, l \) and a label vector \( y \in \mathbb{R}^l \), a decision tree recursively partitions the feature space such that the samples with the same labels or similar target values are grouped together.

Let the data at node \( m \) be represented by \( Q_m \) with \( N_m \) samples. For each candidate split \( \theta = (j, t_m) \) consisting of a feature \( j \) and threshold \( t_m \), partition the data into \( Q^{left}_m(\theta) \) and \( Q^{right}_m(\theta) \) subsets

\[
Q^{left}_m(\theta) = \{ (x, y) | x_j \leq t_m \}
\]

\[
Q^{right}_m(\theta) = Q_m \setminus Q^{left}_m(\theta)
\]

The quality of a candidate split of node \( m \) is then computed using an impurity function or loss function \( H() \), the choice of which depends on the task being solved (classification or regression)

\[
G(Q_m, \theta) = \frac{N^{left}_m}{N_m} H(Q^{left}_m(\theta)) + \frac{N^{right}_m}{N_m} H(Q^{right}_m(\theta))
\]
Select the parameters that minimise the impurity

$$\theta^* = \arg\min_{\theta} G(Q_m, \theta)$$

Recurse for subsets $Q_m^{left}(\theta^*)$ and $Q_m^{right}(\theta^*)$ until the maximum allowable depth is reached, $N_m < \min_{\text{samples}}$ or $N_m = 1$.

**Classification criteria**

If a target is a classification outcome taking on values 0,1,...,K-1, for node $m$, let

$$p_{mk} = \frac{1}{N_m} \sum_{y \in Q_m} I(y = k)$$

be the proportion of class k observations in node $m$. If $m$ is a terminal node, `predict_proba` for this region is set to $p_{mk}$. Common measures of impurity are the following.

Gini:

$$H(Q_m) = \sum_k p_{mk}(1 - p_{mk})$$

Entropy:

$$H(Q_m) = -\sum_k p_{mk} \log(p_{mk})$$

Misclassification:

$$H(Q_m) = 1 - \max(p_{mk})$$

**Regression criteria**

If the target is a continuous value, then for node $m$, common criteria to minimize as for determining locations for future splits are Mean Squared Error (MSE or L2 error), Poisson deviance as well as Mean Absolute Error (MAE or L1 error). MSE and Poisson deviance both set the predicted value of terminal nodes to the learned mean value $\bar{y}_m$ of the node whereas the MAE sets the predicted value of terminal nodes to the median $\text{median}(y)_m$.

Mean Squared Error:

$$\bar{y}_m = \frac{1}{N_m} \sum_{y \in Q_m} y$$

$$H(Q_m) = \frac{1}{N_m} \sum_{y \in Q_m} (y - \bar{y}_m)^2$$

Half Poisson deviance:

$$H(Q_m) = \frac{1}{N_m} \sum_{y \in Q_m} (y \log \frac{y}{\bar{y}_m} - y + \bar{y}_m)$$

Setting criterion="poisson" might be a good choice if your target is a count or a frequency (count per some unit). In any case, $y \geq 0$ is a necessary condition to use this criterion. Note that it fits much slower than the MSE criterion.

Mean Absolute Error:

$$\text{median}(y)_m = \text{median}(y)$$

$$H(Q_m) = \frac{1}{N_m} \sum_{y \in Q_m} |y - \text{median}(y)_m|$$

Note that it fits much slower than the MSE criterion.
Minimal Cost-Complexity Pruning

Minimal cost-complexity pruning is an algorithm used to prune a tree to avoid over-fitting, described in Chapter 3 of [BRE]. This algorithm is parameterized by $\alpha \geq 0$ known as the complexity parameter. The complexity parameter is used to define the cost-complexity measure, $R_\alpha(T)$ of a given tree $T$:

$$R_\alpha(T) = R(T) + \alpha |\overline{T}|$$

where $|\overline{T}|$ is the number of terminal nodes in $T$ and $R(T)$ is traditionally defined as the total misclassification rate of the terminal nodes. Alternatively, scikit-learn uses the total sample weighted impurity of the terminal nodes for $R(T)$. As shown above, the impurity of a node depends on the criterion. Minimal cost-complexity pruning finds the subtree of $T$ that minimizes $R_\alpha(T)$.

The cost complexity measure of a single node is $R_\alpha(t) = R(t) + \alpha$. The branch, $T_t$, is defined to be a tree where node $t$ is its root. In general, the impurity of a node is greater than the sum of impurities of its terminal nodes, $R(T_t) < R(t)$. However, the cost complexity measure of a node, $t$, and its branch, $T_t$, can be equal depending on $\alpha$. We define the effective $\alpha$ of a node to be the value where they are equal, $R_\alpha(T_t) = R_\alpha(t)$ or $\alpha_{\text{eff}}(t) = \frac{R(t) - R(T_t)}{|T_t| - 1}$. A non-terminal node with the smallest value of $\alpha_{\text{eff}}$ is the weakest link and will be pruned. This process stops when the pruned tree’s minimal $\alpha_{\text{eff}}$ is greater than the ccp_alpha parameter.

Examples:

- Post pruning decision trees with cost complexity pruning

References:

- https://en.wikipedia.org/wiki/Predictive_analytics

4.1.11 Ensemble methods

The goal of ensemble methods is to combine the predictions of several base estimators built with a given learning algorithm in order to improve generalizability / robustness over a single estimator.

Two families of ensemble methods are usually distinguished:

- In averaging methods, the driving principle is to build several estimators independently and then to average their predictions. On average, the combined estimator is usually better than any of the single base estimator because its variance is reduced.

  Examples: Bagging methods, Forests of randomized trees, ...

- By contrast, in boosting methods, base estimators are built sequentially and one tries to reduce the bias of the combined estimator. The motivation is to combine several weak models to produce a powerful ensemble.

  Examples: AdaBoost, Gradient Tree Boosting, ...

4.1. Supervised learning
Bagging meta-estimator

In ensemble algorithms, bagging methods form a class of algorithms which build several instances of a black-box estimator on random subsets of the original training set and then aggregate their individual predictions to form a final prediction. These methods are used as a way to reduce the variance of a base estimator (e.g., a decision tree), by introducing randomization into its construction procedure and then making an ensemble out of it. In many cases, bagging methods constitute a very simple way to improve with respect to a single model, without making it necessary to adapt the underlying base algorithm. As they provide a way to reduce overfitting, bagging methods work best with strong and complex models (e.g., fully developed decision trees), in contrast with boosting methods which usually work best with weak models (e.g., shallow decision trees).

Bagging methods come in many flavours but mostly differ from each other by the way they draw random subsets of the training set:

- When random subsets of the dataset are drawn as random subsets of the samples, then this algorithm is known as Pasting [B1999].
- When samples are drawn with replacement, then the method is known as Bagging [B1996].
- When random subsets of the dataset are drawn as random subsets of the features, then the method is known as Random Subspaces [H1998].
- Finally, when base estimators are built on subsets of both samples and features, then the method is known as Random Patches [LG2012].

In scikit-learn, bagging methods are offered as a unified BaggingClassifier meta-estimator (resp. BaggingRegressor), taking as input a user-specified base estimator along with parameters specifying the strategy to draw random subsets. In particular, max_samples and max_features control the size of the subsets (in terms of samples and features), while bootstrap and bootstrap_features control whether samples and features are drawn with or without replacement. When using a subset of the available samples the generalization accuracy can be estimated with the out-of-bag samples by setting oob_score=True. As an example, the snippet below illustrates how to instantiate a bagging ensemble of KNeighborsClassifier base estimators, each built on random subsets of 50% of the samples and 50% of the features.

```python
>>> from sklearn.ensemble import BaggingClassifier
>>> from sklearn.neighbors import KNeighborsClassifier

>>> bagging = BaggingClassifier(KNeighborsClassifier(),
...               max_samples=0.5, max_features=0.5)
```

Examples:

- Single estimator versus bagging: bias-variance decomposition

References
Forests of randomized trees

The sklearn.ensemble module includes two averaging algorithms based on randomized decision trees: the RandomForest algorithm and the Extra-Trees method. Both algorithms are perturb-and-combine techniques [B1998] specifically designed for trees. This means a diverse set of classifiers is created by introducing randomness in the classifier construction. The prediction of the ensemble is given as the averaged prediction of the individual classifiers.

As other classifiers, forest classifiers have to be fitted with two arrays: a sparse or dense array X of shape (n_samples, n_features) holding the training samples, and an array Y of shape (n_samples,) holding the target values (class labels) for the training samples:

```python
>>> from sklearn.ensemble import RandomForestClassifier
>>> X = [[0, 0], [1, 1]]
>>> Y = [0, 1]
>>> clf = RandomForestClassifier(n_estimators=10)
>>> clf = clf.fit(X, Y)
```

Like decision trees, forests of trees also extend to multi-output problems (if Y is an array of shape (n_samples, n_outputs)).

Random Forests

In random forests (see RandomForestClassifier and RandomForestRegressor classes), each tree in the ensemble is built from a sample drawn with replacement (i.e., a bootstrap sample) from the training set.

Furthermore, when splitting each node during the construction of a tree, the best split is found either from all input features or a random subset of size max_features. (See the parameter tuning guidelines for more details).

The purpose of these two sources of randomness is to decrease the variance of the forest estimator. Indeed, individual decision trees typically exhibit high variance and tend to overfit. The injected randomness in forests yield decision trees with somewhat decoupled prediction errors. By taking an average of those predictions, some errors can cancel out. Random forests achieve a reduced variance by combining diverse trees, sometimes at the cost of a slight increase in bias. In practice the variance reduction is often significant hence yielding an overall better model.

In contrast to the original publication [B2001], the scikit-learn implementation combines classifiers by averaging their probabilistic prediction, instead of letting each classifier vote for a single class.

Extremely Randomized Trees

In extremely randomized trees (see ExtraTreesClassifier and ExtraTreesRegressor classes), randomness goes one step further in the way splits are computed. As in random forests, a random subset of candidate features is used, but instead of looking for the most discriminative thresholds, thresholds are drawn at random for each candidate feature and the best of these randomly-generated thresholds is picked as the splitting rule. This usually allows to reduce the variance of the model a bit more, at the expense of a slightly greater increase in bias:

```python
>>> from sklearn.model_selection import cross_val_score
>>> from sklearn.datasets import make_blobs
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.ensemble import ExtraTreesClassifier
>>> from sklearn.tree import DecisionTreeClassifier

>>> X, y = make_blobs(n_samples=10000, n_features=10, centers=100, ...
...     random_state=0)

>>> clf = DecisionTreeClassifier(max_depth=None, min_samples_split=2,
... (continues on next page)
Parameters

The main parameters to adjust when using these methods is `n_estimators` and `max_features`. The former is the number of trees in the forest. The larger the better, but also the longer it will take to compute. In addition, note that results will stop getting significantly better beyond a critical number of trees. The latter is the size of the random subsets of features to consider when splitting a node. The lower the greater the reduction of variance, but also the greater the increase in bias. Empirical good default values are `max_features=None` (always considering all features instead of a random subset) for regression problems, and `max_features="sqrt"` (using a random subset of size $\sqrt{n_{\text{features}}}$) for classification tasks (where $n_{\text{features}}$ is the number of features in the data). Good results are often achieved when setting `max_depth=None` in combination with `min_samples_split=2` (i.e., when fully developing the trees). Bear in mind that these values are usually not optimal, and might result in models that consume a lot of RAM. The best parameter values should always be cross-validated. In addition, note that in random forests, bootstrap samples are used by default (`bootstrap=True`) while the default strategy for
extra-trees is to use the whole dataset (bootstrap=False). When using bootstrap sampling the generalization accuracy can be estimated on the left out or out-of-bag samples. This can be enabled by setting oob_score=True.

Note: The size of the model with the default parameters is $O(M \times N \times \log(N))$, where $M$ is the number of trees and $N$ is the number of samples. In order to reduce the size of the model, you can change these parameters: min_samples_split, max_leaf_nodes, max_depth and min_samples_leaf.

Parallelization

Finally, this module also features the parallel construction of the trees and the parallel computation of the predictions through the n_jobs parameter. If n_jobs=k then computations are partitioned into k jobs, and run on k cores of the machine. If n_jobs=-1 then all cores available on the machine are used. Note that because of inter-process communication overhead, the speedup might not be linear (i.e., using k jobs will unfortunately not be k times as fast). Significant speedup can still be achieved though when building a large number of trees, or when building a single tree requires a fair amount of time (e.g., on large datasets).

Examples:

- Plot the decision surfaces of ensembles of trees on the iris dataset
- Pixel importances with a parallel forest of trees
- Face completion with a multi-output estimators

References


Feature importance evaluation

The relative rank (i.e. depth) of a feature used as a decision node in a tree can be used to assess the relative importance of that feature with respect to the predictability of the target variable. Features used at the top of the tree contribute to the final prediction decision of a larger fraction of the input samples. The expected fraction of the samples they contribute to can thus be used as an estimate of the relative importance of the features. In scikit-learn, the fraction of samples a feature contributes to is combined with the decrease in impurity from splitting them to create a normalized estimate of the predictive power of that feature.

By averaging the estimates of predictive ability over several randomized trees one can reduce the variance of such an estimate and use it for feature selection. This is known as the mean decrease in impurity, or MDI. Refer to [L2014] for more information on MDI and feature importance evaluation with Random Forests.

Warning: The impurity-based feature importances computed on tree-based models suffer from two flaws that can lead to misleading conclusions. First they are computed on statistics derived from the training dataset and therefore do not necessarily inform us on which features are most important to make good predictions on held-out dataset. Secondly, they favor high cardinality features, that is features with many unique values. Permutation feature importance is an alternative to impurity-based feature importance that does not suffer from these flaws. These two methods of obtaining feature importance are explored in: Permutation Importance vs Random Forest Feature Importance (MDI).
The following example shows a color-coded representation of the relative importances of each individual pixel for a face recognition task using an ExtraTreesClassifier model.

![Pixel importances with forests of trees](image)

In practice those estimates are stored as an attribute named feature_importances on the fitted model. This is an array with shape (n_features,) whose values are positive and sum to 1.0. The higher the value, the more important is the contribution of the matching feature to the prediction function.

**Examples:**

- **Pixel importances with a parallel forest of trees**
- **Feature importances with forests of trees**

**References**

**Totally Random Trees Embedding**

RandomTreesEmbedding implements an unsupervised transformation of the data. Using a forest of completely random trees, RandomTreesEmbedding encodes the data by the indices of the leaves a data point ends up in. This index is then encoded in a one-of-K manner, leading to a high dimensional, sparse binary coding. This coding can be computed very efficiently and can then be used as a basis for other learning tasks. The size and sparsity of the code can be influenced by choosing the number of trees and the maximum depth per tree. For each tree in the ensemble, the coding contains one entry of one. The size of the coding is at most n_estimators * 2 ** max_depth, the maximum number of leaves in the forest.

As neighboring data points are more likely to lie within the same leaf of a tree, the transformation performs an implicit, non-parametric density estimation.
Examples:

- Hashing feature transformation using Totally Random Trees
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap... compares non-linear dimensionality reduction techniques on handwritten digits.
- Feature transformations with ensembles of trees compares supervised and unsupervised tree based feature transformations.

See also:

Manifold learning techniques can also be useful to derive non-linear representations of feature space, also these approaches focus also on dimensionality reduction.

AdaBoost

The module sklearn.ensemble includes the popular boosting algorithm AdaBoost, introduced in 1995 by Freund and Schapire [FS1995].

The core principle of AdaBoost is to fit a sequence of weak learners (i.e., models that are only slightly better than random guessing, such as small decision trees) on repeatedly modified versions of the data. The predictions from all of them are then combined through a weighted majority vote (or sum) to produce the final prediction. The data modifications at each so-called boosting iteration consist of applying weights $w_1, w_2, \ldots, w_N$ to each of the training samples. Initially, those weights are all set to $w_i = 1/N$, so that the first step simply trains a weak learner on the original data. For each successive iteration, the sample weights are individually modified and the learning algorithm is reapplied to the reweighted data. At a given step, those training examples that were incorrectly predicted by the boosted model induced at the previous step have their weights increased, whereas the weights are decreased for those that were predicted correctly. As iterations proceed, examples that are difficult to predict receive ever-increasing influence. Each subsequent weak learner is thereby forced to concentrate on the examples that are missed by the previous ones in the sequence [HTF].
AdaBoost can be used both for classification and regression problems:

- For multi-class classification, `AdaBoostClassifier` implements AdaBoost-SAMME and AdaBoost-SAMME.R [ZZRH2009].
- For regression, `AdaBoostRegressor` implements AdaBoost.R2 [D1997].

**Usage**

The following example shows how to fit an AdaBoost classifier with 100 weak learners:

```python
>>> from sklearn.model_selection import cross_val_score
>>> from sklearn.datasets import load_iris
>>> from sklearn.ensemble import AdaBoostClassifier

>>> X, y = load_iris(return_X_y=True)
>>> clf = AdaBoostClassifier(n_estimators=100)
>>> scores = cross_val_score(clf, X, y, cv=5)
>>> scores.mean()
0.9...
```

The number of weak learners is controlled by the parameter `n_estimators`. The `learning_rate` parameter controls the contribution of the weak learners in the final combination. By default, weak learners are decision stumps. Different weak learners can be specified through the `base_estimator` parameter. The main parameters to tune to obtain good results are `n_estimators` and the complexity of the base estimators (e.g., its depth `max_depth` or minimum required number of samples to consider a split `min_samples_split`).

**Examples:**

- **Discrete versus Real AdaBoost** compares the classification error of a decision stump, decision tree, and a boosted decision stump using AdaBoost-SAMME and AdaBoost-SAMME.R.
- **Two-class AdaBoost** shows the decision boundary and decision function values for a non-linearly separable two-class problem using AdaBoost-SAMME.
- **Decision Tree Regression with AdaBoost** demonstrates regression with the AdaBoost.R2 algorithm.

**References**

**Gradient Tree Boosting**

Gradient Tree Boosting or Gradient Boosted Decision Trees (GBDT) is a generalization of boosting to arbitrary differentiable loss functions. GBDT is an accurate and effective off-the-shelf procedure that can be used for both regression and classification problems in a variety of areas including Web search ranking and ecology.

The module `sklearn.ensemble` provides methods for both classification and regression via gradient boosted decision trees.

**Note:** Scikit-learn 0.21 introduces two new experimental implementations of gradient boosting trees, namely
HistGradientBoostingClassifier and HistGradientBoostingRegressor, inspired by LightGBM (See [LightGBM]).

These histogram-based estimators can be orders of magnitude faster than GradientBoostingClassifier and GradientBoostingRegressor when the number of samples is larger than tens of thousands of samples.

They also have built-in support for missing values, which avoids the need for an imputer.

These estimators are described in more detail below in Histogram-Based Gradient Boosting.

The following guide focuses on GradientBoostingClassifier and GradientBoostingRegressor, which might be preferred for small sample sizes since binning may lead to split points that are too approximate in this setting.

The usage and the parameters of GradientBoostingClassifier and GradientBoostingRegressor are described below. The 2 most important parameters of these estimators are n_estimators and learning_rate.

Classification

GradientBoostingClassifier supports both binary and multi-class classification. The following example shows how to fit a gradient boosting classifier with 100 decision stumps as weak learners:

```python
>>> from sklearn.datasets import make_hastie_10_2
>>> from sklearn.ensemble import GradientBoostingClassifier

>>> X, y = make_hastie_10_2(random_state=0)
>>> X_train, X_test = X[:2000], X[2000:]
>>> y_train, y_test = y[:2000], y[2000:]

>>> clf = GradientBoostingClassifier(n_estimators=100, learning_rate=1.0,
...                                   max_depth=1, random_state=0).fit(X_train, y_train)
>>> clf.score(X_test, y_test)
0.913...
```

The number of weak learners (i.e. regression trees) is controlled by the parameter n_estimators; The size of each tree can be controlled either by setting the tree depth via max_depth or by setting the number of leaf nodes via max_leaf_nodes. The learning_rate is a hyper-parameter in the range (0.0, 1.0] that controls overfitting via shrinkage.

Note: Classification with more than 2 classes requires the induction of n_classes regression trees at each iteration, thus, the total number of induced trees equals n_classes * n_estimators. For datasets with a large number of classes we strongly recommend to use HistGradientBoostingClassifier as an alternative to GradientBoostingClassifier.
Regression

GradientBoostingRegressor supports a number of different loss functions for regression which can be specified via the argument loss; the default loss function for regression is least squares ('ls').

```python
>>> from sklearn.metrics import mean_squared_error
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.ensemble import GradientBoostingRegressor

>>> X, y = make_friedman1(n_samples=1200, random_state=0, noise=1.0)
>>> X_train, X_test = X[:200], X[200:]
>>> y_train, y_test = y[:200], y[200:]
>>> est = GradientBoostingRegressor(n_estimators=100, learning_rate=0.1,
... max_depth=1, random_state=0, loss='ls').fit(X_train, y_train)
>>> mean_squared_error(y_test, est.predict(X_test))
5.00...
```

The figure below shows the results of applying GradientBoostingRegressor with least squares loss and 500 base learners to the diabetes dataset (sklearn.datasets.load_diabetes). The plot on the left shows the train and test error at each iteration. The train error at each iteration is stored in the train_score_ attribute of the gradient boosting model. The test error at each iterations can be obtained via the staged_predict method which returns a generator that yields the predictions at each stage. Plots like these can be used to determine the optimal number of trees (i.e. n_estimators) by early stopping.
Examples:

- Gradient Boosting regression
- Gradient Boosting Out-of-Bag estimates

Fitting additional weak-learners

Both `GradientBoostingRegressor` and `GradientBoostingClassifier` support `warm_start=True` which allows you to add more estimators to an already fitted model.

```python
>>> _ = est.set_params(n_estimators=200, warm_start=True)  # set warm_start and new nr of trees
>>> _ = est.fit(X_train, y_train)  # fit additional 100 trees to est
>>> mean_squared_error(y_test, est.predict(X_test))
3.84...
```

Controlling the tree size

The size of the regression tree base learners defines the level of variable interactions that can be captured by the gradient boosting model. In general, a tree of depth $h$ can capture interactions of order $h$. There are two ways in which the size of the individual regression trees can be controlled.

If you specify `max_depth=h` then complete binary trees of depth $h$ will be grown. Such trees will have (at most) $2^h$ leaf nodes and $2^h - 1$ split nodes.

Alternatively, you can control the tree size by specifying the number of leaf nodes via the parameter `max_leaf_nodes`. In this case, trees will be grown using best-first search where nodes with the highest improvement in impurity will be expanded first. A tree with `max_leaf_nodes=k` has $k - 1$ split nodes and thus can model interactions of up to order $max_leaf_nodes - 1$.

We found that `max_leaf_nodes=k` gives comparable results to `max_depth=k-1` but is significantly faster to train at the expense of a slightly higher training error. The parameter `max_leaf_nodes` corresponds to the variable $J$ in the chapter on gradient boosting in [F2001] and is related to the parameter `interaction.depth` in R’s `gbm` package where `max_leaf_nodes == interaction.depth + 1`.

Mathematical formulation

We first present GBRT for regression, and then detail the classification case.

Regression

GBRT regressors are additive models whose prediction $\hat{y}_i$ for a given input $x_i$ is of the following form:

$$\hat{y}_i = F_M(x_i) = \sum_{m=1}^{M} h_m(x_i)$$

where the $h_m$ are estimators called weak learners in the context of boosting. Gradient Tree Boosting uses decision tree regressors of fixed size as weak learners. The constant $M$ corresponds to the `n_estimators` parameter.
Similar to other boosting algorithms, a GBRT is built in a greedy fashion:

\[ F_m(x) = F_{m-1}(x) + h_m(x), \]

where the newly added tree \( h_m \) is fitted in order to minimize a sum of losses \( L_m \), given the previous ensemble \( F_{m-1} \):

\[ h_m = \arg \min_h L_m = \arg \min_h \sum_{i=1}^n l(y_i, F_{m-1}(x_i) + h(x_i)), \]

where \( l(y_i, F(x_i)) \) is defined by the loss parameter, detailed in the next section.

By default, the initial model \( F_0 \) is chosen as the constant that minimizes the loss: for a least-squares loss, this is the empirical mean of the target values. The initial model can also be specified via the init argument.

Using a first-order Taylor approximation, the value of \( l \) can be approximated as follows:

\[ l(y_i, F_{m-1}(x_i) + h_m(x_i)) \approx l(y_i, F_{m-1}(x_i)) + h_m(x_i) \left[ \frac{\partial l(y_i, F(x_i))}{\partial F(x_i)} \right]_{F=F_{m-1}}. \]

Note: Briefly, a first-order Taylor approximation says that \( l(z) \approx l(a) + (z - a) \frac{\partial l(a)}{\partial a} \). Here, \( z \) corresponds to \( F_{m-1}(x_i) + h_m(x_i) \), and \( a \) corresponds to \( F_{m-1}(x_i) \)

The quantity \( \left[ \frac{\partial l(y_i, F(x_i))}{\partial F(x_i)} \right]_{F=F_{m-1}} \) is the derivative of the loss with respect to its second parameter, evaluated at \( F_{m-1}(x) \). It is easy to compute for any given \( F_{m-1}(x_i) \) in a closed form since the loss is differentiable. We will denote it by \( g_i \).

Removing the constant terms, we have:

\[ h_m \approx \arg \min_h \sum_{i=1}^n h(x_i) g_i \]

This is minimized if \( h(x_i) \) is fitted to predict a value that is proportional to the negative gradient \( -g_i \). Therefore, at each iteration, the estimator \( h_m \) is fitted to predict the negative gradients of the samples. The gradients are updated at each iteration. This can be considered as some kind of gradient descent in a functional space.

Note: For some losses, e.g. the least absolute deviation (LAD) where the gradients are \( \pm 1 \), the values predicted by a fitted \( h_m \) are not accurate enough: the tree can only output integer values. As a result, the leaves values of the tree \( h_m \) are modified once the tree is fitted, such that the leaves values minimize the loss \( L_m \). The update is loss-dependent: for the LAD loss, the value of a leaf is updated to the median of the samples in that leaf.
Classification

Gradient boosting for classification is very similar to the regression case. However, the sum of the trees $F_M(x_i) = \sum_m h_m(x_i)$ is not homogeneous to a prediction: it cannot be a class, since the trees predict continuous values.

The mapping from the value $F_M(x_i)$ to a class or a probability is loss-dependent. For the deviance (or log-loss), the probability that $x_i$ belongs to the positive class is modeled as $p(y_i = 1|x_i) = \sigma(F_M(x_i))$ where $\sigma$ is the sigmoid function.

For multiclass classification, K trees (for K classes) are built at each of the $M$ iterations. The probability that $x_i$ belongs to class k is modeled as a softmax of the $F_{M,k}(x_i)$ values.

Note that even for a classification task, the $h_m$ sub-estimator is still a regressor, not a classifier. This is because the sub-estimators are trained to predict (negative) gradients, which are always continuous quantities.

Loss Functions

The following loss functions are supported and can be specified using the parameter loss:

- **Regression**
  - Least squares ('ls'): The natural choice for regression due to its superior computational properties. The initial model is given by the mean of the target values.
  - Least absolute deviation ('lad'): A robust loss function for regression. The initial model is given by the median of the target values.
  - Huber ('huber'): Another robust loss function that combines least squares and least absolute deviation; use alpha to control the sensitivity with regards to outliers (see [F2001] for more details).
  - Quantile ('quantile'): A loss function for quantile regression. Use $0 < \alpha < 1$ to specify the quantile. This loss function can be used to create prediction intervals (see Prediction Intervals for Gradient Boosting Regression).

- **Classification**
  - Binomial deviance ('deviance'): The negative binomial log-likelihood loss function for binary classification (provides probability estimates). The initial model is given by the log odds-ratio.
  - Multinomial deviance ('deviance'): The negative multinomial log-likelihood loss function for multiclass classification with $n_{\text{classes}}$ mutually exclusive classes. It provides probability estimates. The initial model is given by the prior probability of each class. At each iteration $n_{\text{classes}}$ regression trees have to be constructed which makes GBRT rather inefficient for data sets with a large number of classes.
  - Exponential loss ('exponential'): The same loss function as AdaBoostClassifier. Less robust to mislabeled examples than 'deviance'; can only be used for binary classification.

Shrinkage via learning rate

[F2001] proposed a simple regularization strategy that scales the contribution of each weak learner by a constant factor $\nu$:

$$F_m(x) = F_{m-1}(x) + \nu h_m(x)$$

The parameter $\nu$ is also called the learning rate because it scales the step length the gradient descent procedure; it can be set via the learning_rate parameter.

The parameter learning_rate strongly interacts with the parameter n_estimators, the number of weak learners to fit. Smaller values of learning_rate require larger numbers of weak learners to maintain a constant training
error. Empirical evidence suggests that small values of `learning_rate` favor better test error. [HTF] recommend to set the learning rate to a small constant (e.g. `learning_rate <= 0.1`) and choose `n_estimators` by early stopping. For a more detailed discussion of the interaction between `learning_rate` and `n_estimators` see [R2007].

**Subsampling**

[F1999] proposed stochastic gradient boosting, which combines gradient boosting with bootstrap averaging (bagging). At each iteration the base classifier is trained on a fraction `subsample` of the available training data. The subsample is drawn without replacement. A typical value of `subsample` is 0.5.

The figure below illustrates the effect of shrinkage and subsampling on the goodness-of-fit of the model. We can clearly see that shrinkage outperforms no-shrinkage. Subsampling with shrinkage can further increase the accuracy of the model. Subsampling without shrinkage, on the other hand, does poorly.

![Graph illustrating the effect of shrinkage and subsampling](image)

Another strategy to reduce the variance is by subsampling the features analogous to the random splits in `RandomForestClassifier`. The number of subsampled features can be controlled via the `max_features` parameter.

**Note:** Using a small `max_features` value can significantly decrease the runtime.

Stochastic gradient boosting allows to compute out-of-bag estimates of the test deviance by computing the improvement in deviance on the examples that are not included in the bootstrap sample (i.e. the out-of-bag examples). The improvements are stored in the attribute `oob_improvement_`. `oob_improvement_[i]` holds the improvement in terms of the loss on the OOB samples if you add the i-th stage to the current predictions. Out-of-bag estimates can be used for model selection, for example to determine the optimal number of iterations. OOB estimates are usually very pessimistic thus we recommend to use cross-validation instead and only use OOB if cross-validation is too time consuming.
Examples:
  - Gradient Boosting regularization
  - Gradient Boosting Out-of-Bag estimates
  - OOB Errors for Random Forests

**Interpretation with feature importance**

Individual decision trees can be interpreted easily by simply visualizing the tree structure. Gradient boosting models, however, comprise hundreds of regression trees thus they cannot be easily interpreted by visual inspection of the individual trees. Fortunately, a number of techniques have been proposed to summarize and interpret gradient boosting models.

Often features do not contribute equally to predict the target response; in many situations the majority of the features are in fact irrelevant. When interpreting a model, the first question usually is: what are those important features and how do they contributing in predicting the target response?

Individual decision trees intrinsically perform feature selection by selecting appropriate split points. This information can be used to measure the importance of each feature; the basic idea is: the more often a feature is used in the split points of a tree the more important that feature is. This notion of importance can be extended to decision tree ensembles by simply averaging the impurity-based feature importance of each tree (see `Feature importance evaluation` for more details).

The feature importance scores of a fit gradient boosting model can be accessed via the `feature_importances_` property:

```python
>>> from sklearn.datasets import make_hastie_10_2
>>> from sklearn.ensemble import GradientBoostingClassifier

>>> X, y = make_hastie_10_2(random_state=0)
>>> clf = GradientBoostingClassifier(n_estimators=100, learning_rate=1.0,...
max_depth=1, random_state=0).fit(X, y)
>>> clf.feature_importances_
array([0.10..., 0.10..., 0.11..., ...])
```

Note that this computation of feature importance is based on entropy, and it is distinct from `sklearn.inspection.permutation_importance` which is based on permutation of the features.

Examples:
  - Gradient Boosting regression
Histogram-Based Gradient Boosting

Scikit-learn 0.21 introduced two new experimental implementations of gradient boosting trees, namely HistGradientBoostingClassifier and HistGradientBoostingRegressor, inspired by LightGBM (See [LightGBM]).

These histogram-based estimators can be orders of magnitude faster than GradientBoostingClassifier and GradientBoostingRegressor when the number of samples is larger than tens of thousands of samples.

They also have built-in support for missing values, which avoids the need for an imputer.

These fast estimators first bin the input samples $X$ into integer-valued bins (typically 256 bins) which tremendously reduces the number of splitting points to consider, and allows the algorithm to leverage integer-based data structures (histograms) instead of relying on sorted continuous values when building the trees. The API of these estimators is slightly different, and some of the features from GradientBoostingClassifier and GradientBoostingRegressor are not yet supported, for instance some loss functions.

These estimators are still experimental: their predictions and their API might change without any deprecation cycle. To use them, you need to explicitly import enable_hist_gradient_boosting:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_hist_gradient_boosting
>>> from sklearn.ensemble import HistGradientBoostingClassifier
```

Examples:

- Partial Dependence and Individual Conditional Expectation Plots

Usage

Most of the parameters are unchanged from GradientBoostingClassifier and GradientBoostingRegressor. One exception is the max_iter parameter that replaces n_estimators, and controls the number of iterations of the boosting process:

```python
>>> from sklearn.experimental import enable_hist_gradient_boosting
>>> from sklearn.ensemble import HistGradientBoostingClassifier
>>> X, y = make_hastie_10_2(random_state=0)
>>> X_train, X_test = X[:2000], X[2000:]
>>> y_train, y_test = y[:2000], y[2000:]
>>> clf = HistGradientBoostingClassifier(max_iter=100).fit(X_train, y_train)
>>> clf.score(X_test, y_test)
0.8965
```

Available losses for regression are ‘least_squares’, ‘least_absolute_deviation’, which is less sensitive to outliers, and ‘poisson’, which is well suited to model counts and frequencies. For classification, ‘binary_crossentropy’ is used for binary classification and ‘categorical_crossentropy’ is used for multiclass classification. By default the loss is ‘auto’ and will select the appropriate loss depending on $y$ passed to fit.

The size of the trees can be controlled through the max_leaf_nodes, max_depth, and min_samples_leaf parameters.
The number of bins used to bin the data is controlled with the `max_bins` parameter. Using less bins acts as a form of regularization. It is generally recommended to use as many bins as possible, which is the default.

The `l2_regularization` parameter is a regularizer on the loss function and corresponds to $\lambda$ in equation (2) of [XGBoost].

Note that early-stopping is enabled by default if the number of samples is larger than 10,000. The early-stopping behaviour is controlled via the `early-stopping`, `scoring`, `validation_fraction`, `n_iter_no_change`, and `tol` parameters. It is possible to early-stop using an arbitrary `scorer`, or just the training or validation loss. Note that for technical reasons, using a scorer is significantly slower than using the loss. By default, early-stopping is performed if there are at least 10,000 samples in the training set, using the validation loss.

**Missing values support**

`HistGradientBoostingClassifier` and `HistGradientBoostingRegressor` have built-in support for missing values (NaNs).

During training, the tree grower learns at each split point whether samples with missing values should go to the left or right child, based on the potential gain. When predicting, samples with missing values are assigned to the left or right child consequently:

```python
>>> from sklearn.experimental import enable_hist_gradient_boosting # noqa
>>> from sklearn.ensemble import HistGradientBoostingClassifier
>>> import numpy as np

>>> X = np.array([0, 1, 2, np.nan]).reshape(-1, 1)
>>> y = [0, 0, 1, 1]

>>> gbdt = HistGradientBoostingClassifier(min_samples_leaf=1).fit(X, y)
>>> gbdt.predict(X)
array([0, 0, 1, 1])
```

When the missingness pattern is predictive, the splits can be done on whether the feature value is missing or not:

```python
>>> X = np.array([0, np.nan, 1, 2, np.nan]).reshape(-1, 1)
>>> y = [0, 1, 0, 0, 1]

>>> gbdt = HistGradientBoostingClassifier(min_samples_leaf=1,
...                                          max_depth=2,
...                                          learning_rate=1,
...                                          max_iter=1).fit(X, y)

>>> gbdt.predict(X)
array([0, 1, 0, 0, 1])
```

If no missing values were encountered for a given feature during training, then samples with missing values are mapped to whichever child has the most samples.
Sample weight support

`HistGradientBoostingClassifier` and `HistGradientBoostingRegressor` sample support weights during `fit`.

The following toy example demonstrates how the model ignores the samples with zero sample weights:

```python
>>> X = [[1, 0],
    ... [1, 0],
    ... [1, 0],
    ... [0, 1]]
>>> y = [0, 0, 1, 0]
>>> # ignore the first 2 training samples by setting their weight to 0
>>> sample_weight = [0, 0, 1, 1]
>>> gb = HistGradientBoostingClassifier(min_samples_leaf=1)
>>> gb.fit(X, y, sample_weight=sample_weight)
HistGradientBoostingClassifier(...)
>>> gb.predict([[1, 0]])
array([1])
>>> gb.predict_proba([[1, 0]])[0, 1]
0.99...
```

As you can see, the `[1, 0]` is comfortably classified as `1` since the first two samples are ignored due to their sample weights.

Implementation detail: taking sample weights into account amounts to multiplying the gradients (and the hessians) by the sample weights. Note that the binning stage (specifically the quantiles computation) does not take the weights into account.

Categorical Features Support

`HistGradientBoostingClassifier` and `HistGradientBoostingRegressor` have native support for categorical features: they can consider splits on non-ordered, categorical data.

For datasets with categorical features, using the native categorical support is often better than relying on one-hot encoding (`OneHotEncoder`), because one-hot encoding requires more tree depth to achieve equivalent splits. It is also usually better to rely on the native categorical support rather than to treat categorical features as continuous (ordinal), which happens for ordinal-encoded categorical data, since categories are nominal quantities where order does not matter.

To enable categorical support, a boolean mask can be passed to the `categorical_features` parameter, indicating which feature is categorical. In the following, the first feature will be treated as categorical and the second feature as numerical:

```python
>>> gbd = HistGradientBoostingClassifier(categorical_features=[True, False])
```

Equivalently, one can pass a list of integers indicating the indices of the categorical features:

```python
>>> gbd = HistGradientBoostingClassifier(categorical_features=[0])
```

The cardinality of each categorical feature should be less than the `max_bins` parameter, and each categorical feature is expected to be encoded in `[0, max_bins - 1]`. To that end, it might be useful to pre-process the data with an `OrdinalEncoder` as done in Categorical Feature Support in Gradient Boosting.

If there are missing values during training, the missing values will be treated as a proper category. If there are no missing values during training, then at prediction time, missing values are mapped to the child node that has the most
samples (just like for continuous features). When predicting, categories that were not seen during fit time will be treated as missing values.

**Split finding with categorical features**: The canonical way of considering categorical splits in a tree is to consider all of the $2^K - 1$ partitions, where $K$ is the number of categories. This can quickly become prohibitive when $K$ is large. Fortunately, since gradient boosting trees are always regression trees (even for classification problems), there exist a faster strategy that can yield equivalent splits. First, the categories of a feature are sorted according to the variance of the target, for each category $k$. Once the categories are sorted, one can consider *continuous partitions*, i.e. treat the categories as if they were ordered continuous values (see Fisher [1958] for a formal proof). As a result, only $K - 1$ splits need to be considered instead of $2^K - 1$. The initial sorting is a $O(K \log(K))$ operation, leading to a total complexity of $O(K \log(K) + K)$, instead of $O(2^K)$.

**Examples**:

- *Categorical Feature Support in Gradient Boosting*

### Monotonic Constraints

Depending on the problem at hand, you may have prior knowledge indicating that a given feature should in general have a positive (or negative) effect on the target value. For example, all else being equal, a higher credit score should increase the probability of getting approved for a loan. Monotonic constraints allow you to incorporate such prior knowledge into the model.

A positive monotonic constraint is a constraint of the form:

$$ x_1 \leq x'_1 \implies F(x_1, x_2) \leq F(x'_1, x_2), \quad \text{where } F \text{ is the predictor with two features}. $$

Similarly, a negative monotonic constraint is of the form:

$$ x_1 \leq x'_1 \implies F(x_1, x_2) \geq F(x'_1, x_2). $$

Note that monotonic constraints only constraint the output “all else being equal”. Indeed, the following relation is **not enforced** by a positive constraint: $x_1 \leq x'_1 \implies F(x_1, x_2) \leq F(x'_1, x'_2)$.

You can specify a monotonic constraint on each feature using the `monotonic_cst` parameter. For each feature, a value of 0 indicates no constraint, while -1 and 1 indicate a negative and positive constraint, respectively:

```python
>>> from sklearn.experimental import enable_hist_gradient_boosting  # noqa
>>> from sklearn.ensemble import HistGradientBoostingRegressor
...  # positive, negative, and no constraint on the 3 features
>>> gbdt = HistGradientBoostingRegressor(monotonic_cst=[1, -1, 0])
```

In a binary classification context, imposing a monotonic constraint means that the feature is supposed to have a positive / negative effect on the probability to belong to the positive class. Monotonic constraints are not supported for multiclass context.

**Note**: Since categories are unordered quantities, it is not possible to enforce monotonic constraints on categorical features.

**Examples**:

- *Monotonic Constraints*
Low-level parallelism

`HistGradientBoostingClassifier` and `HistGradientBoostingRegressor` have implementations that use OpenMP for parallelization through Cython. For more details on how to control the number of threads, please refer to our Parallelism notes.

The following parts are parallelized:

- mapping samples from real values to integer-valued bins (finding the bin thresholds is however sequential)
- building histograms is parallelized over features
- finding the best split point at a node is parallelized over features
- during fit, mapping samples into the left and right children is parallelized over samples
- gradient and hessians computations are parallelized over samples
- predicting is parallelized over samples

Why it's faster

The bottleneck of a gradient boosting procedure is building the decision trees. Building a traditional decision tree (as in the other GBDTs `GradientBoostingClassifier` and `GradientBoostingRegressor`) requires sorting the samples at each node (for each feature). Sorting is needed so that the potential gain of a split point can be computed efficiently. Splitting a single node has thus a complexity of $O(n_{\text{features}} \times \log(n))$ where $n$ is the number of samples at the node.

`HistGradientBoostingClassifier` and `HistGradientBoostingRegressor`, in contrast, do not require sorting the feature values and instead use a data-structure called a histogram, where the samples are implicitly ordered. Building a histogram has a $O(n)$ complexity, so the node splitting procedure has a $O(n_{\text{features}} \times n)$ complexity, much smaller than the previous one. In addition, instead of considering $n$ split points, we here consider only max_bins split points, which is much smaller.

In order to build histograms, the input data $X$ needs to be binned into integer-valued bins. This binning procedure does require sorting the feature values, but it only happens once at the very beginning of the boosting process (not at each node, like in `GradientBoostingClassifier` and `GradientBoostingRegressor`).

Finally, many parts of the implementation of `HistGradientBoostingClassifier` and `HistGradientBoostingRegressor` are parallelized.

References

Voting Classifier

The idea behind the `VotingClassifier` is to combine conceptually different machine learning classifiers and use a majority vote or the average predicted probabilities (soft vote) to predict the class labels. Such a classifier can be useful for a set of equally well performing model in order to balance out their individual weaknesses.
Majority Class Labels (Majority/Hard Voting)

In majority voting, the predicted class label for a particular sample is the class label that represents the majority (mode) of the class labels predicted by each individual classifier.

E.g., if the prediction for a given sample is

- classifier 1 -> class 1
- classifier 2 -> class 1
- classifier 3 -> class 2

the VotingClassifier (with `voting='hard'`) would classify the sample as “class 1” based on the majority class label.

In the cases of a tie, the `VotingClassifier` will select the class based on the ascending sort order. E.g., in the following scenario

- classifier 1 -> class 2
- classifier 2 -> class 1

the class label 1 will be assigned to the sample.

Usage

The following example shows how to fit the majority rule classifier:

```python
>>> from sklearn import datasets
>>> from sklearn.model_selection import cross_val_score
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.naive_bayes import GaussianNB
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.ensemble import VotingClassifier

>>> iris = datasets.load_iris()
>>> X, y = iris.data[:, 1:3], iris.target

>>> clf1 = LogisticRegression(random_state=1)
>>> clf2 = RandomForestClassifier(n_estimators=50, random_state=1)
>>> clf3 = GaussianNB()

>>> eclf = VotingClassifier(...
...    estimators=[('lr', clf1), ('rf', clf2), ('gnb', clf3)],
...    voting='hard')

>>> for clf, label in zip([clf1, clf2, clf3, eclf], ['Logistic Regression', 'Random Forest', 'naive Bayes', 'Ensemble']):
...    scores = cross_val_score(clf, X, y, scoring='accuracy', cv=5)
...    print("Accuracy: $0.2f (+/- $0.2f) [%s]\)" % (scores.mean(), scores.std(), label))

Accuracy: 0.95 (+/- 0.04) [Logistic Regression]
Accuracy: 0.94 (+/- 0.04) [Random Forest]
Accuracy: 0.91 (+/- 0.04) [naive Bayes]
Accuracy: 0.95 (+/- 0.04) [Ensemble]
```
Weighted Average Probabilities (Soft Voting)

In contrast to majority voting (hard voting), soft voting returns the class label as argmax of the sum of predicted probabilities.

Specific weights can be assigned to each classifier via the weights parameter. When weights are provided, the predicted class probabilities for each classifier are collected, multiplied by the classifier weight, and averaged. The final class label is then derived from the class label with the highest average probability.

To illustrate this with a simple example, let’s assume we have 3 classifiers and a 3-class classification problems where we assign equal weights to all classifiers: \( w_1=1, w_2=1, w_3=1 \).

The weighted average probabilities for a sample would then be calculated as follows:

<table>
<thead>
<tr>
<th>classifier</th>
<th>class 1</th>
<th>class 2</th>
<th>class 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>classifier 1</td>
<td>( w_1 \times 0.2 )</td>
<td>( w_1 \times 0.5 )</td>
<td>( w_1 \times 0.3 )</td>
</tr>
<tr>
<td>classifier 2</td>
<td>( w_2 \times 0.6 )</td>
<td>( w_2 \times 0.3 )</td>
<td>( w_2 \times 0.1 )</td>
</tr>
<tr>
<td>classifier 3</td>
<td>( w_3 \times 0.3 )</td>
<td>( w_3 \times 0.4 )</td>
<td>( w_3 \times 0.3 )</td>
</tr>
<tr>
<td>weighted average</td>
<td>0.37</td>
<td>0.4</td>
<td>0.23</td>
</tr>
</tbody>
</table>

Here, the predicted class label is 2, since it has the highest average probability.

The following example illustrates how the decision regions may change when a soft VotingClassifier is used based on an linear Support Vector Machine, a Decision Tree, and a K-nearest neighbor classifier:

```python
>>> from sklearn import datasets
>>> from sklearn.tree import DecisionTreeClassifier
>>> from sklearn.neighbors import KNeighborsClassifier
>>> from sklearn.svm import SVC
>>> from itertools import product
>>> from sklearn.ensemble import VotingClassifier

>>> # Loading some example data
>>> iris = datasets.load_iris()
>>> X = iris.data[:, [0, 2]]
>>> y = iris.target

>>> # Training classifiers
>>> clf1 = DecisionTreeClassifier(max_depth=4)
>>> clf2 = KNeighborsClassifier(n_neighbors=7)
>>> clf3 = SVC(kernel='rbf', probability=True)
>>> eclf = VotingClassifier(estimators=[('dt', clf1), ('knn', clf2), ('svc', clf3)],...
\   voting='soft', weights=[2, 1, 2])

>>> clf1 = clf1.fit(X, y)
>>> clf2 = clf2.fit(X, y)
>>> clf3 = clf3.fit(X, y)
>>> eclf = eclf.fit(X, y)
```
4.1. Supervised learning
Using the VotingClassifier with GridSearchCV

The VotingClassifier can also be used together with GridSearchCV in order to tune the hyperparameters of the individual estimators:

```python
>>> from sklearn.model_selection import GridSearchCV
>>> clf1 = LogisticRegression(random_state=1)
>>> clf2 = RandomForestClassifier(random_state=1)
>>> clf3 = GaussianNB()
>>> eclf = VotingClassifier(  
...    estimators=[('lr', clf1), ('rf', clf2), ('gnb', clf3)],  
...    voting='soft'
... )
>>> params = {'lr__C': [1.0, 100.0], 'rf__n_estimators': [20, 200]}
>>> grid = GridSearchCV(estimator=eclf, param_grid=params, cv=5)
>>> grid = grid.fit(iris.data, iris.target)
```

Usage

In order to predict the class labels based on the predicted class-probabilities (scikit-learn estimators in the VotingClassifier must support predict_proba method):

```python
>>> eclf = VotingClassifier(  
...    estimators=[('lr', clf1), ('rf', clf2), ('gnb', clf3)],  
...    voting='soft'
... )
```

Optionally, weights can be provided for the individual classifiers:

```python
>>> eclf = VotingClassifier(  
...    estimators=[('lr', clf1), ('rf', clf2), ('gnb', clf3)],  
...    voting='soft', weights=[2, 5, 1]
... )
```

Voting Regressor

The idea behind the VotingRegressor is to combine conceptually different machine learning regressors and return the average predicted values. Such a regressor can be useful for a set of equally well performing models in order to balance out their individual weaknesses.

Usage

The following example shows how to fit the VotingRegressor:

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.ensemble import GradientBoostingRegressor
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.ensemble import VotingRegressor
```
### Loading some example data

```python
>>> X, y = load_diabetes(return_X_y=True)
```

### Training classifiers

```python
>>> reg1 = GradientBoostingRegressor(random_state=1)
>>> reg2 = RandomForestRegressor(random_state=1)
>>> reg3 = LinearRegression()
>>> ereg = VotingRegressor(estimators=[('gb', reg1), ('rf', reg2), ('lr', reg3)])
>>> ereg = ereg.fit(X, y)
```

**Examples:**

- *Plot individual and voting regression predictions*

#### Stacked generalization

Stacked generalization is a method for combining estimators to reduce their biases [W1992] [HTF]. More precisely, the predictions of each individual estimator are stacked together and used as input to a final estimator to compute the prediction. This final estimator is trained through cross-validation.

The `StackingClassifier` and `StackingRegressor` provide such strategies which can be applied to classification and regression problems.

The `estimators` parameter corresponds to the list of the estimators which are stacked together in parallel on the input data. It should be given as a list of names and estimators:

```python
>>> from sklearn.linear_model import RidgeCV, LassoCV
>>> from sklearn.neighbors import KNeighborsRegressor
```

(continues on next page)
The `final_estimator` will use the predictions of the estimators as input. It needs to be a classifier or a regressor when using `StackingClassifier` or `StackingRegressor`, respectively:

```python
>>> from sklearn.ensemble import GradientBoostingRegressor
>>> from sklearn.ensemble import StackingRegressor

>>> final_estimator = GradientBoostingRegressor(
...     n_estimators=25, subsample=0.5, min_samples_leaf=25, max_features=1,
...     random_state=42)
>>> reg = StackingRegressor(
...     estimators=estimators,
...     final_estimator=final_estimator)
```

To train the estimators and final_estimator, the `fit` method needs to be called on the training data:

```python
>>> from sklearn.datasets import load_diabetes
>>> X, y = load_diabetes(return_X_y=True)
>>> from sklearn.model_selection import train_test_split

>>> X_train, X_test, y_train, y_test = train_test_split(X, y,
...     random_state=42)
>>> reg.fit(X_train, y_train)
```

During training, the estimators are fitted on the whole training data `X_train`. They will be used when calling `predict` or `predict_proba`. To generalize and avoid over-fitting, the final_estimator is trained on out-samples using `sklearn.model_selection.cross_val_predict` internally.

For `StackingClassifier`, note that the output of the estimators is controlled by the parameter `stack_method` and it is called by each estimator. This parameter is either a string, being estimator method names, or 'auto' which will automatically identify an available method depending on the availability, tested in the order of preference: `predict_proba`, `decision_function` and `predict`.

A `StackingRegressor` and `StackingClassifier` can be used as any other regressor or classifier, exposing a `predict`, `predict_proba`, and `decision_function` methods, e.g.:

```python
>>> y_pred = reg.predict(X_test)
>>> from sklearn.metrics import r2_score

>>> print('R2 score: {:.2f}'.format(r2_score(y_test, y_pred)))
R2 score: 0.53
```

Note that it is also possible to get the output of the stacked estimators using the `transform` method:

```python
>>> reg.transform(X_test[:5])
```

In practice, a stacking predictor predicts as good as the best predictor of the base layer and even sometimes out-performs it by combining the different strengths of the these predictors. However, training a stacking predictor is computationally expensive.
Note: For StackingClassifier, when using stack_method_='predict_proba', the first column is dropped when the problem is a binary classification problem. Indeed, both probability columns predicted by each estimator are perfectly collinear.

Note: Multiple stacking layers can be achieved by assigning final_estimator to a StackingClassifier or StackingRegressor:

```python
>>> final_layer_rfr = RandomForestRegressor(n_estimators=10, max_features=1, max_leaf_nodes=5, random_state=42)
>>> final_layer_gbr = GradientBoostingRegressor(n_estimators=10, max_features=1, max_leaf_nodes=5, random_state=42)
>>> final_layer = StackingRegressor(estimators=[('rf', final_layer_rfr), ('gbrt', final_layer_gbr)], final_estimator=RidgeCV())
>>> multi_layer_regressor = StackingRegressor(estimators=[('ridge', RidgeCV()), ('lasso', LassoCV(random_state=42)), ('knr', KNeighborsRegressor(n_neighbors=20, metric='euclidean'))], final_estimator=final_layer)
>>> multi_layer_regressor.fit(X_train, y_train)
StackingRegressor(...)
>>> print('R2 score: {:.2f}')
... .format(multi_layer_regressor.score(X_test, y_test))
R2 score: 0.53
```

References

4.1.12 Multiclass and multioutput algorithms

This section of the user guide covers functionality related to multi-learning problems, including multiclass, multilabel, and multioutput classification and regression.

The modules in this section implement meta-estimators, which require a base estimator to be provided in their constructor. Meta-estimators extend the functionality of the base estimator to support multi-learning problems, which is accomplished by transforming the multi-learning problem into a set of simpler problems, then fitting one estimator per problem.

This section covers two modules: sklearn.multiclass and sklearn.multioutput. The chart below demonstrates the problem types that each module is responsible for, and the corresponding meta-estimators that each module provides.
The table below provides a quick reference on the differences between problem types. More detailed explanations can be found in subsequent sections of this guide.

<table>
<thead>
<tr>
<th>Problem Type</th>
<th>Number of targets</th>
<th>Target cardinality</th>
<th>Valid type of target</th>
</tr>
</thead>
<tbody>
<tr>
<td>Multiclass classification</td>
<td>1</td>
<td>&gt;2</td>
<td>‘multiclass’</td>
</tr>
<tr>
<td>Multilabel classification</td>
<td>&gt;1</td>
<td>2 (0 or 1)</td>
<td>‘multilabel-indicator’</td>
</tr>
<tr>
<td>Multiclass-multioutput classification</td>
<td>&gt;1</td>
<td>&gt;2</td>
<td>‘multiclass-multioutput’</td>
</tr>
<tr>
<td>Multioutput regression</td>
<td>&gt;1</td>
<td>Continuous</td>
<td>‘continuous-multioutput’</td>
</tr>
</tbody>
</table>

Below is a summary of scikit-learn estimators that have multi-learning support built-in, grouped by strategy. You don’t need the meta-estimators provided by this section if you’re using one of these estimators. However, meta-estimators can provide additional strategies beyond what is built-in:

- **Inherently multiclass:**
  - naive_bayes.BernoulliNB
  - tree.DecisionTreeClassifier
  - tree.ExtraTreeClassifier
  - ensemble.ExtraTreesClassifier
  - naive_bayes.GaussianNB
  - neighbors.KNeighborsClassifier
  - semi_supervised.LabelPropagation
  - semi_supervised.LabelSpreading
  - discriminant_analysis.LinearDiscriminantAnalysis
  - svm.LinearSVC (setting multi_class=”crammer_singer”)
  - linear_model.LogisticRegression (setting multi_class=”multinomial”)
  - linear_model.LogisticRegressionCV (setting multi_class=”multinomial”)
  - neural_network.MLPClassifier
- `neighbors.NearestCentroid`
- `discriminant_analysis.QuadraticDiscriminantAnalysis`
- `neighbors.RadiusNeighborsClassifier`
- `ensemble.RandomForestClassifier`
- `linear_model.RidgeClassifier`
- `linear_model.RidgeClassifierCV`

- **Multiclass as One-Vs-One:**
  - `svm.NuSVC`
  - `svm.SVC`
  - `gaussian_process.GaussianProcessClassifier` (setting `multi_class = "one_vs_one"`)

- **Multiclass as One-Vs-The-Rest:**
  - `ensemble.GradientBoostingClassifier`
  - `gaussian_process.GaussianProcessClassifier` (setting `multi_class = "one_vs_rest"`)
  - `svm.LinearSVC` (setting `multi_class="ovr"`)
  - `linear_model.LogisticRegression` (setting `multi_class="ovr"`)
  - `linear_model.LogisticRegressionCV` (setting `multi_class="ovr"`)
  - `linear_model.SGDClassifier`
  - `linear_model.Perceptron`
  - `linear_model.PassiveAggressiveClassifier`

- **Support multilabel:**
  - `tree.DecisionTreeClassifier`
  - `tree.ExtraTreeClassifier`
  - `ensemble.ExtraTreesClassifier`
  - `neighbors.KNeighborsClassifier`
  - `neural_network.MLPClassifier`
  - `neighbors.RadiusNeighborsClassifier`
  - `ensemble.RandomForestClassifier`
  - `linear_model.RidgeClassifierCV`

- **Support multiclass-multioutput:**
  - `tree.DecisionTreeClassifier`
  - `tree.ExtraTreeClassifier`
  - `ensemble.ExtraTreesClassifier`
  - `neighbors.KNeighborsClassifier`
  - `neighbors.RadiusNeighborsClassifier`
  - `ensemble.RandomForestClassifier`
Multiclass classification

**Warning:** All classifiers in scikit-learn do multiclass classification out-of-the-box. You don’t need to use the `sklearn.multiclass` module unless you want to experiment with different multiclass strategies.

Multiclass classification is a classification task with more than two classes. Each sample can only be labeled as one class.

For example, classification using features extracted from a set of images of fruit, where each image may either be of an orange, an apple, or a pear. Each image is one sample and is labeled as one of the 3 possible classes. Multiclass classification makes the assumption that each sample is assigned to one and only one label - one sample cannot, for example, be both a pear and an apple.

While all scikit-learn classifiers are capable of multiclass classification, the meta-estimators offered by `sklearn.multiclass` permit changing the way they handle more than two classes because this may have an effect on classifier performance (either in terms of generalization error or required computational resources).

**Target format**

Valid multiclass representations for `type_of_target` are:

- 1d or column vector containing more than two discrete values. An example of a vector `y` for 4 samples:
  ```python
  >>> import numpy as np
  >>> y = np.array(['apple', 'pear', 'apple', 'orange'])
  >>> print(y)
  ['apple' 'pear' 'apple' 'orange']
  ```

- Dense or sparse binary matrix of shape `(n_samples, n_classes)` with a single sample per row, where each column represents one class. An example of both a dense and sparse binary matrix `y` for 4 samples, where the columns, in order, are apple, orange, and pear:
  ```python
  >>> import numpy as np
  >>> from sklearn.preprocessing import LabelBinarizer
  >>> y = np.array(['apple', 'pear', 'apple', 'orange'])
  >>> y_dense = LabelBinarizer().fit_transform(y)
  >>> print(y_dense)
  [[1 0 0]
   [0 0 1]
   [1 0 0]
   [0 1 0]]
  >>> from scipy import sparse
  >>> y_sparse = sparse.csr_matrix(y_dense)
  >>> print(y_sparse)
  (0, 0) 1
  (1, 2) 1
  (2, 0) 1
  (3, 1) 1
  ```

For more information about `LabelBinarizer`, refer to *Transforming the prediction target*.
scikit-learn user guide, Release 0.24.0

OneVsRestClassifier
The one-vs-rest strategy, also known as one-vs-all, is implemented in OneVsRestClassifier. The strategy
consists in fitting one classifier per class. For each classifier, the class is fitted against all the other classes. In
addition to its computational efficiency (only n_classes classifiers are needed), one advantage of this approach is
its interpretability. Since each class is represented by one and only one classifier, it is possible to gain knowledge
about the class by inspecting its corresponding classifier. This is the most commonly used strategy and is a fair default
choice.
Below is an example of multiclass learning using OvR:
>>> from sklearn import datasets
>>> from sklearn.multiclass import OneVsRestClassifier
>>> from sklearn.svm import LinearSVC
>>> X, y = datasets.load_iris(return_X_y=True)
>>> OneVsRestClassifier(LinearSVC(random_state=0)).fit(X,
array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
1, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 2, 2, 1,
1, 1, 1, 1, 1, 1, 1, 1, 2, 2, 2, 2, 2, 2, 2, 2, 2,
2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 1, 2, 2,
2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2])

y).predict(X)
0, 0, 0, 0, 0,
0, 0, 0, 0, 0,
1, 1, 1, 1, 1,
1, 1, 1, 1, 1,
2, 2, 2, 2, 2,
2, 1, 2, 2, 2,

0,
0,
1,
1,
2,
2,

OneVsRestClassifier also supports multilabel classification. To use this feature, feed the classifier an indicator
matrix, in which cell [i, j] indicates the presence of label j in sample i.

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Examples:

- **Multilabel classification**

### OneVsOneClassifier

OneVsOneClassifier constructs one classifier per pair of classes. At prediction time, the class which received the most votes is selected. In the event of a tie (among two classes with an equal number of votes), it selects the class with the highest aggregate classification confidence by summing over the pair-wise classification confidence levels computed by the underlying binary classifiers.

Since it requires to fit \( n_{\text{classes}} \times (n_{\text{classes}} - 1) / 2 \) classifiers, this method is usually slower than one-vs-the-rest, due to its \( O(n_{\text{classes}}^2) \) complexity. However, this method may be advantageous for algorithms such as kernel algorithms which don’t scale well with \( n_{\text{samples}} \). This is because each individual learning problem only involves a small subset of the data whereas, with one-vs-the-rest, the complete dataset is used \( n_{\text{classes}} \) times.

The decision function is the result of a monotonic transformation of the one-versus-one classification.

Below is an example of multiclass learning using OvO:

```python
>>> from sklearn import datasets
>>> from sklearn.multiclass import OneVsOneClassifier
>>> from sklearn.svm import LinearSVC

>>> X, y = datasets.load_iris(return_X_y=True)
>>> OneVsOneClassifier(LinearSVC(random_state=0)).fit(X, y).predict(X)
array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
1, 2, 1, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
1, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2]).
```

### OutputCodeClassifier

Error-Correcting Output Code-based strategies are fairly different from one-vs-the-rest and one-vs-one. With these strategies, each class is represented in a Euclidean space, where each dimension can only be 0 or 1. Another way to put it is that each class is represented by a binary code (an array of 0 and 1). The matrix which keeps track of the location/code of each class is called the code book. The code size is the dimensionality of the aforementioned space. Intuitively, each class should be represented by a code as unique as possible and a good code book should be designed to optimize classification accuracy. In this implementation, we simply use a randomly-generated code book as advocated in\(^3\) although more elaborate methods may be added in the future.

At fitting time, one binary classifier per bit in the code book is fitted. At prediction time, the classifiers are used to project new points in the class space and the class closest to the points is chosen.

In OutputCodeClassifier, the code_size attribute allows the user to control the number of classifiers which will be used. It is a percentage of the total number of classes.

---

A number between 0 and 1 will require fewer classifiers than one-vs-the-rest. In theory, \(\log_2(n_{\text{classes}}) / n_{\text{classes}}\) is sufficient to represent each class unambiguously. However, in practice, it may not lead to good accuracy since \(\log_2(n_{\text{classes}})\) is much smaller than \(n_{\text{classes}}\).

A number greater than 1 will require more classifiers than one-vs-the-rest. In this case, some classifiers will in theory correct for the mistakes made by other classifiers, hence the name “error-correcting”. In practice, however, this may not happen as classifier mistakes will typically be correlated. The error-correcting output codes have a similar effect to bagging.

Below is an example of multiclass learning using Output-Codes:

```python
from sklearn import datasets
from sklearn.multiclass import OutputCodeClassifier
from sklearn.svm import LinearSVC

X, y = datasets.load_iris(return_X_y=True)
clf = OutputCodeClassifier(LinearSVC(random_state=0),
                           code_size=2, random_state=0)
clf.fit(X, y).predict(X)
```

References:


Multilabel classification

Multilabel classification (closely related to multioutput classification) is a classification task labeling each sample with \(m\) labels from \(n_{\text{classes}}\) possible classes, where \(m\) can be 0 to \(n_{\text{classes}}\) inclusive. This can be thought of as predicting properties of a sample that are not mutually exclusive. Formally, a binary output is assigned to each class, for every sample. Positive classes are indicated with 1 and negative classes with 0 or -1. It is thus comparable to running \(n_{\text{classes}}\) binary classification tasks, for example with MultiOutputClassifier. This approach treats each label independently whereas multilabel classifiers may treat the multiple classes simultaneously, accounting for correlated behavior among them.

For example, prediction of the topics relevant to a text document or video. The document or video may be about one of ‘religion’, ‘politics’, ‘finance’ or ‘education’, several of the topic classes or all of the topic classes.
Target format

A valid representation of *multilabel* $y$ is an either dense or sparse *binary* matrix of shape $(n_{\text{samples}}, n_{\text{classes}})$. Each column represents a class. The 1’s in each row denote the positive classes a sample has been labeled with. An example of a dense matrix $y$ for 3 samples:

```python
>>> y = np.array([[1, 0, 0, 1], [0, 0, 1, 1], [0, 0, 0, 0]])
>>> print(y)
[[1 0 0 1]
 [0 0 1 1]
 [0 0 0 0]]
```

Dense binary matrices can also be created using *MultiLabelBinarizer*. For more information, refer to *Transforming the prediction target ($y$)*.

An example of the same $y$ in sparse matrix form:

```python
>>> y_sparse = sparse.csr_matrix(y)
>>> print(y_sparse)
(0, 0) 1
(0, 3) 1
(1, 2) 1
(1, 3) 1
```

**MultiOutputClassifier**

Multilabel classification support can be added to any classifier with *MultiOutputClassifier*. This strategy consists of fitting one classifier per target. This allows multiple target variable classifications. The purpose of this class is to extend estimators to be able to estimate a series of target functions ($f_1,f_2,f_3,\ldots,f_n$) that are trained on a single $X$ predictor matrix to predict a series of responses ($y_1,y_2,y_3,\ldots,y_n$).

Below is an example of multilabel classification:

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.multioutput import MultiOutputClassifier
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.utils import shuffle
>>> import numpy as np

>>> X, y1 = make_classification(n_samples=10, n_features=100, n_informative=30, n_classes=3, random_state=1)
>>> y2 = shuffle(y1, random_state=1)
>>> y3 = shuffle(y1, random_state=2)
>>> Y = np.vstack((y1, y2, y3)).T
>>> n_samples, n_features = X.shape # 10,100
>>> n_outputs = Y.shape[1] # 3
>>> n_classes = 3
>>> forest = RandomForestClassifier(random_state=1)
>>> multi_target_forest = MultiOutputClassifier(forest, n_jobs=-1)
>>> multi_target_forest.fit(X, Y).predict(X)
array([[2, 2, 0],
 [1, 2, 1],
 [2, 1, 0],
 [0, 0, 2],
 [0, 2, 1],
 [0, 0, 2],
 [1, 1, 0],
 [0, 0, 2],
 [1, 0, 1],
 [0, 1, 0]]
```
ClassifierChains

ClassifierChains (see ClassifierChain) are a way of combining a number of binary classifiers into a single multi-label model that is capable of exploiting correlations among targets.

For a multi-label classification problem with N classes, N binary classifiers are assigned an integer between 0 and N-1. These integers define the order of models in the chain. Each classifier is then fit on the available training data plus the true labels of the classes whose models were assigned a lower number.

When predicting, the true labels will not be available. Instead the predictions of each model are passed on to the subsequent models in the chain to be used as features.

Clearly the order of the chain is important. The first model in the chain has no information about the other labels while the last model in the chain has features indicating the presence of all of the other labels. In general one does not know the optimal ordering of the models in the chain so typically many randomly ordered chains are fit and their predictions are averaged together.

References:


Multiclass-multioutput classification

Multiclass-multioutput classification (also known as multitask classification) is a classification task which labels each sample with a set of non-binary properties. Both the number of properties and the number of classes per property is greater than 2. A single estimator thus handles several joint classification tasks. This is both a generalization of the multilabel classification task, which only considers binary attributes, as well as a generalization of the multiclass classification task, where only one property is considered.

For example, classification of the properties “type of fruit” and “colour” for a set of images of fruit. The property “type of fruit” has the possible classes: “apple”, “pear” and “orange”. The property “colour” has the possible classes: “green”, “red”, “yellow” and “orange”. Each sample is an image of a fruit, a label is output for both properties and each label is one of the possible classes of the corresponding property.

Note that all classifiers handling multiclass-multioutput (also known as multitask classification) tasks, support the multilabel classification task as a special case. Multitask classification is similar to the multioutput classification task with different model formulations. For more information, see the relevant estimator documentation.

Warning: At present, no metric in sklearn.metrics supports the multiclass-multioutput classification task.
Target format

A valid representation of `multioutput` $y$ is a dense matrix of shape $(n\_samples, n\_classes)$ of class labels. A column wise concatenation of 1d `multiclass` variables. An example of $y$ for 3 samples:

```python
>>> y = np.array([['apple', 'green'], ['orange', 'orange'], ['pear', 'green']])
```

```python
>>> print(y)
[['apple' 'green']
 ['orange' 'orange']
 ['pear' 'green']]
```

Multioutput regression

Multioutput regression predicts multiple numerical properties for each sample. Each property is a numerical variable and the number of properties to be predicted for each sample is greater than or equal to 2. Some estimators that support multioutput regression are faster than just running `n\_output` estimators.

For example, prediction of both wind speed and wind direction, in degrees, using data obtained at a certain location. Each sample would be data obtained at one location and both wind speed and direction would be output for each sample.

Target format

A valid representation of `multioutput` $y$ is a dense matrix of shape $(n\_samples, n\_classes)$ of floats. A column wise concatenation of `continuous` variables. An example of $y$ for 3 samples:

```python
>>> y = np.array([[31.4, 94], [40.5, 109], [25, 30]])
```

```python
>>> print(y)
[[ 31.4  94. ]
 [ 40.5 109. ]
 [ 25.  30. ]]
```

MultiOutputRegressor

Multioutput regression support can be added to any regressor with `MultiOutputRegressor`. This strategy consists of fitting one regressor per target. Since each target is represented by exactly one regressor it is possible to gain knowledge about the target by inspecting its corresponding regressor. As `MultiOutputRegressor` fits one regressor per target it can not take advantage of correlations between targets.

Below is an example of multioutput regression:

```python
>>> from sklearn.datasets import make_regression
>>> from sklearn.multioutput import MultiOutputRegressor
>>> from sklearn.ensemble import GradientBoostingRegressor

>>> X, y = make_regression(n_samples=10, n_targets=3, random_state=1)
>>> MultiOutputRegressor(GradientBoostingRegressor(random_state=0)).fit(X, y).

array([[-154.75474165, -147.03498585, -50.03812219],
       [-141.62745778,  95.02891072, -191.48204257],
       [ 97.03260883, 165.34867495,  139.52003279],
       [ 123.92529176,  21.25719016,  -7.84253 ]],
      (continues on next page)
RegressorChain

Regressor chains (see RegressorChain) is analogous to ClassifierChain as a way of combining a number of regressions into a single multi-target model that is capable of exploiting correlations among targets.

4.1.13 Feature selection

The classes in the sklearn.feature_selection module can be used for feature selection/dimensionality reduction on sample sets, either to improve estimators’ accuracy scores or to boost their performance on very high-dimensional datasets.

Removing features with low variance

VarianceThreshold is a simple baseline approach to feature selection. It removes all features whose variance doesn’t meet some threshold. By default, it removes all zero-variance features, i.e. features that have the same value in all samples.

As an example, suppose that we have a dataset with boolean features, and we want to remove all features that are either one or zero (on or off) in more than 80% of the samples. Boolean features are Bernoulli random variables, and the variance of such variables is given by

\[ \text{Var}[X] = p(1-p) \]

so we can select using the threshold \( .8 \times (1-.8) \):

```python
>>> from sklearn.feature_selection import VarianceThreshold
>>> X = [[0, 0, 1], [0, 1, 0], [1, 0, 0], [0, 1, 1], [0, 1, 0], [0, 1, 1]]
>>> sel = VarianceThreshold(threshold=(.8 * (1-.8)))
>>> sel.fit_transform(X)
array([[0, 1],
       [1, 0],
       [0, 0],
       [1, 1],
       [1, 0],
       [1, 1]])
```

As expected, VarianceThreshold has removed the first column, which has a probability \( p = 5/6 > .8 \) of containing a zero.
Univariate feature selection

Univariate feature selection works by selecting the best features based on univariate statistical tests. It can be seen as a preprocessing step to an estimator. Scikit-learn exposes feature selection routines as objects that implement the `transform` method:

- `SelectKBest` removes all but the $k$ highest scoring features
- `SelectPercentile` removes all but a user-specified highest scoring percentage of features
- using common univariate statistical tests for each feature: false positive rate `SelectFpr`, false discovery rate `SelectFdr`, or family wise error `SelectFwe`.
- `GenericUnivariateSelect` allows to perform univariate feature selection with a configurable strategy. This allows to select the best univariate selection strategy with hyper-parameter search estimator.

For instance, we can perform a $\chi^2$ test to the samples to retrieve only the two best features as follows:

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.feature_selection import SelectKBest
>>> from sklearn.feature_selection import chi2

>>> X, y = load_iris(return_X_y=True)
>>> X.shape
(150, 4)
>>> X_new = SelectKBest(chi2, k=2).fit_transform(X, y)
>>> X_new.shape
(150, 2)
```

These objects take as input a scoring function that returns univariate scores and p-values (or only scores for `SelectKBest` and `SelectPercentile`):

- For regression: `f_regression, mutual_info_regression`
- For classification: `chi2, f_classif, mutual_info_classif`

The methods based on F-test estimate the degree of linear dependency between two random variables. On the other hand, mutual information methods can capture any kind of statistical dependency, but being nonparametric, they require more samples for accurate estimation.

Feature selection with sparse data

If you use sparse data (i.e. data represented as sparse matrices), `chi2, mutual_info_regression, mutual_info_classif` will deal with the data without making it dense.

**Warning:** Beware not to use a regression scoring function with a classification problem, you will get useless results.

**Examples:**

- Univariate Feature Selection
- Comparison of F-test and mutual information
Recursive feature elimination

Given an external estimator that assigns weights to features (e.g., the coefficients of a linear model), the goal of recursive feature elimination (RFE) is to select features by recursively considering smaller and smaller sets of features. First, the estimator is trained on the initial set of features and the importance of each feature is obtained either through any specific attribute (such as coef_, feature_importances_) or callable. Then, the least important features are pruned from current set of features. That procedure is recursively repeated on the pruned set until the desired number of features to select is eventually reached.

RFECV performs RFE in a cross-validation loop to find the optimal number of features.

Examples:
- **Recursive feature elimination**: A recursive feature elimination example showing the relevance of pixels in a digit classification task.
- **Recursive feature elimination with cross-validation**: A recursive feature elimination example with automatic tuning of the number of features selected with cross-validation.

Feature selection using SelectFromModel

SelectFromModel is a meta-transformer that can be used along with any estimator that importance of each feature through a specific attribute (such as coef_, feature_importances_) or callable after fitting. The features are considered unimportant and removed, if the corresponding importance of the feature values are below the provided threshold parameter. Apart from specifying the threshold numerically, there are built-in heuristics for finding a threshold using a string argument. Available heuristics are “mean”, “median” and float multiples of these like “0.1*mean”. In combination with the threshold criteria, one can use the max_features parameter to set a limit on the number of features to select.

For examples on how it is to be used refer to the sections below.

Examples
- **Model-based and sequential feature selection**

L1-based feature selection

Linear models penalized with the L1 norm have sparse solutions: many of their estimated coefficients are zero. When the goal is to reduce the dimensionality of the data to use with another classifier, they can be used along with SelectFromModel to select the non-zero coefficients. In particular, sparse estimators useful for this purpose are the Lasso for regression, and of LogisticRegression and LinearSVC for classification:

```python
>>> from sklearn.svm import LinearSVC
>>> from sklearn.datasets import load_iris
>>> from sklearn.feature_selection import SelectFromModel

>>> X, y = load_iris(return_X_y=True)
>>> X.shape
(150, 4)

>>> lsvc = LinearSVC(C=0.01, penalty="11", dual=False).fit(X, y)
>>> model = SelectFromModel(lsvc, prefit=True)

>>> X_new = model.transform(X)
```
With SVMs and logistic-regression, the parameter C controls the sparsity: the smaller C the fewer features selected. With Lasso, the higher the alpha parameter, the fewer features selected.

Examples:

- Classification of text documents using sparse features: Comparison of different algorithms for document classification including L1-based feature selection.

L1-recovery and compressive sensing

For a good choice of alpha, the Lasso can fully recover the exact set of non-zero variables using only few observations, provided certain specific conditions are met. In particular, the number of samples should be “sufficiently large”, or L1 models will perform at random, where “sufficiently large” depends on the number of non-zero coefficients, the logarithm of the number of features, the amount of noise, the smallest absolute value of non-zero coefficients, and the structure of the design matrix X. In addition, the design matrix must display certain specific properties, such as not being too correlated.

There is no general rule to select an alpha parameter for recovery of non-zero coefficients. It can by set by cross-validation (LassoCV or LassoLarsCV), though this may lead to under-penalized models: including a small number of non-relevant variables is not detrimental to prediction score. BIC (LassoLarsIC) tends, on the opposite, to set high values of alpha.


Tree-based feature selection

Tree-based estimators (see the sklearn.tree module and forest of trees in the sklearn.ensemble module) can be used to compute impurity-based feature importances, which in turn can be used to discard irrelevant features (when coupled with the SelectFromModel meta-transformer):

```python
>>> from sklearn.ensemble import ExtraTreesClassifier
>>> from sklearn.datasets import load_iris
>>> from sklearn.feature_selection import SelectFromModel
>>>
>>> X, y = load_iris(return_X_y=True)
>>> X.shape
(150, 4)
>>> clf = ExtraTreesClassifier(n_estimators=50)
>>> clf = clf.fit(X, y)
>>> clf.feature_importances_
array([ 0.04..., 0.05..., 0.4..., 0.4...])
>>> model = SelectFromModel(clf, prefit=True)
>>> X_new = model.transform(X)
>>> X_new.shape
(150, 2)
```
Examples:

- **Feature importances with forests of trees**: example on synthetic data showing the recovery of the actually meaningful features.
- **Pixel importances with a parallel forest of trees**: example on face recognition data.

### Sequential Feature Selection

Sequential Feature Selection [sfs] (SFS) is available in the `SequentialFeatureSelector` transformer. SFS can be either forward or backward:

Forward-SFS is a greedy procedure that iteratively finds the best new feature to add to the set of selected features. Concretely, we initially start with zero feature and find the one feature that maximizes a cross-validated score when an estimator is trained on this single feature. Once that first feature is selected, we repeat the procedure by adding a new feature to the set of selected features. The procedure stops when the desired number of selected features is reached, as determined by the `n_features_to_select` parameter.

Backward-SFS follows the same idea but works in the opposite direction: instead of starting with no feature and greedily adding features, we start with *all* the features and greedily *remove* features from the set. The `direction` parameter controls whether forward or backward SFS is used.

In general, forward and backward selection do not yield equivalent results. Also, one may be much faster than the other depending on the requested number of selected features: if we have 10 features and ask for 7 selected features, forward selection would need to perform 7 iterations while backward selection would only need to perform 3.

SFS differs from `RFE` and `SelectFromModel` in that it does not require the underlying model to expose a `coef_` or `feature_importances_` attribute. It may however be slower considering that more models need to be evaluated, compared to the other approaches. For example in backward selection, the iteration going from \( m \) features to \( m - 1 \) features using k-fold cross-validation requires fitting \( m \times k \) models, while `RFE` would require only a single fit, and `SelectFromModel` always just does a single fit and requires no iterations.

Examples

- **Model-based and sequential feature selection**

### References:

Feature selection as part of a pipeline

Feature selection is usually used as a pre-processing step before doing the actual learning. The recommended way to do this in scikit-learn is to use a `Pipeline`:

```python
clf = Pipeline([  
    ('feature_selection', SelectFromModel(LinearSVC(penalty="l1"))),  
    ('classification', RandomForestClassifier())  
])
clf.fit(X, y)
```

In this snippet we make use of a `LinearSVC` coupled with `SelectFromModel` to evaluate feature importances and select the most relevant features. Then, a `RandomForestClassifier` is trained on the transformed output,
You can perform similar operations with the other feature selection methods and also classifiers that provide a way to evaluate feature importances of course. See the `Pipeline` examples for more details.

### 4.1.14 Semi-supervised learning

Semi-supervised learning is a situation in which in your training data some of the samples are not labeled. The semi-supervised estimators in `sklearn.semi_supervised` are able to make use of this additional unlabeled data to better capture the shape of the underlying data distribution and generalize better to new samples. These algorithms can perform well when we have a very small amount of labeled points and a large amount of unlabeled points.

**Unlabeled entries in y**

It is important to assign an identifier to unlabeled points along with the labeled data when training the model with the `fit` method. The identifier that this implementation uses is the integer value `-1`. Note that for string labels, the `dtype` of `y` should be object so that it can contain both strings and integers.

**Note:** Semi-supervised algorithms need to make assumptions about the distribution of the dataset in order to achieve performance gains. See [here](#) for more details.

**Self Training**

This self-training implementation is based on Yarowsky’s¹ algorithm. Using this algorithm, a given supervised classifier can function as a semi-supervised classifier, allowing it to learn from unlabeled data. `SelfTrainingClassifier` can be called with any classifier that implements `predict_proba`, passed as the parameter `base_classifier`. In each iteration, the `base_classifier` predicts labels for the unlabeled samples and adds a subset of these labels to the labeled dataset.

The choice of this subset is determined by the selection criterion. This selection can be done using a threshold on the prediction probabilities, or by choosing the `k_best` samples according to the prediction probabilities.

The labels used for the final fit as well as the iteration in which each sample was labeled are available as attributes.

The optional `max_iter` parameter specifies how many times the loop is executed at most. The `max_iter` parameter may be set to `None`, causing the algorithm to iterate until all samples have labels or no new samples are selected in that iteration.

**Note:** When using the self-training classifier, the `calibration` of the classifier is important.

**Examples**

- *Effect of varying threshold for self-training*
- *Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset*

Label Propagation

Label propagation denotes a few variations of semi-supervised graph inference algorithms.

A few features available in this model:
- Used for classification tasks
- Kernel methods to project data into alternate dimensional spaces

scikit-learn provides two label propagation models: LabelPropagation and LabelSpreading. Both work by constructing a similarity graph over all items in the input dataset.

![An illustration of label-propagation](image)

Fig. 2: **An illustration of label-propagation:** the structure of unlabeled observations is consistent with the class structure, and thus the class label can be propagated to the unlabeled observations of the training set.

LabelPropagation and LabelSpreading differ in modifications to the similarity matrix that graph and the clamping effect on the label distributions. Clamping allows the algorithm to change the weight of the true ground labeled data to some degree. The LabelPropagation algorithm performs hard clamping of input labels, which means \( \alpha = 0 \). This clamping factor can be relaxed, to say \( \alpha = 0.2 \), which means that we will always retain 80 percent of our original label distribution, but the algorithm gets to change its confidence of the distribution within 20 percent.

LabelPropagation uses the raw similarity matrix constructed from the data with no modifications. In contrast, LabelSpreading minimizes a loss function that has regularization properties, as such it is often more robust to noise. The algorithm iterates on a modified version of the original graph and normalizes the edge weights by computing the normalized graph Laplacian matrix. This procedure is also used in Spectral clustering.

Label propagation models have two built-in kernel methods. Choice of kernel effects both scalability and performance of the algorithms. The following are available:
- \( \text{rbf} \left( \exp\left(-\gamma|x-y|^2\right), \gamma > 0 \right) \). \( \gamma \) is specified by keyword gamma.
- \( \text{knn} \left( 1[x' \in kNN(x)] \right) \). \( k \) is specified by keyword n_neighbors.

The RBF kernel will produce a fully connected graph which is represented in memory by a dense matrix. This matrix may be very large and combined with the cost of performing a full matrix multiplication calculation for each iteration of the algorithm can lead to prohibitively long running times. On the other hand, the KNN kernel will produce a much more memory-friendly sparse matrix which can drastically reduce running times.
Examples

- Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset
- Label Propagation learning a complex structure
- Label Propagation digits: Demonstrating performance
- Label Propagation digits active learning

References


4.1.15 Isotonic regression

The class IsotonicRegression fits a non-decreasing real function to 1-dimensional data. It solves the following problem:

\[
\text{minimize } \sum_i w_i(y_i - \hat{y}_i)^2 \\
\text{subject to } \hat{y}_i \leq \hat{y}_j \text{ whenever } X_i \leq X_j,
\]

where the weights \( w_i \) are strictly positive, and both \( X \) and \( y \) are arbitrary real quantities.

The increasing parameter changes the constraint to \( \hat{y}_i \geq \hat{y}_j \) whenever \( X_i \leq X_j \). Setting it to ‘auto’ will automatically choose the constraint based on Spearman’s rank correlation coefficient.

IsotonicRegression produces a series of predictions \( \hat{y}_i \) for the training data which are the closest to the targets \( y \) in terms of mean squared error. These predictions are interpolated for predicting to unseen data. The predictions of IsotonicRegression thus form a function that is piecewise linear.

4.1.16 Probability calibration

When performing classification you often want not only to predict the class label, but also obtain a probability of the respective label. This probability gives you some kind of confidence on the prediction. Some models can give you poor estimates of the class probabilities and some even do not support probability prediction (e.g., some instances of SGDClassifier). The calibration module allows you to better calibrate the probabilities of a given model, or to add support for probability prediction.

Well calibrated classifiers are probabilistic classifiers for which the output of the predict_proba method can be directly interpreted as a confidence level. For instance, a well calibrated (binary) classifier should classify the samples such that among the samples to which it gave a predict_proba value close to 0.8, approximately 80% actually belong to the positive class.
Calibration curves

The following plot compares how well the probabilistic predictions of different classifiers are calibrated, using `calibration_curve`. The x axis represents the average predicted probability in each bin. The y axis is the fraction of positives, i.e. the proportion of samples whose class is the positive class (in each bin).

`LogisticRegression` returns well calibrated predictions by default as it directly optimizes Log loss. In contrast, the other methods return biased probabilities; with different biases per method:

- `GaussianNB` tends to push probabilities to 0 or 1 (note the counts in the histograms). This is mainly because it makes the assumption that features are conditionally independent given the class, which is not the case in this dataset which contains 2 redundant features.

- `RandomForestClassifier` shows the opposite behavior: the histograms show peaks at approximately 0.2 and 0.9 probability, while probabilities close to 0 or 1 are very rare. An explanation for this is given by Niculescu-Mizil and Caruana\footnote{Predicting Good Probabilities with Supervised Learning, A. Niculescu-Mizil & R. Caruana, ICML 2005}: “Methods such as bagging and random forests that average predictions from a base set of models can have difficulty making predictions near 0 and 1 because variance in the underlying base models will bias predictions that should be near zero or one away from these values. Because predictions are restricted to the interval $[0,1]$, errors caused by variance tend to be one-sided near zero and one. For example, if a model should predict $p = 0$ for a case, the only way bagging can achieve this is if all bagged trees predict zero. If we add noise to the trees that bagging is averaging over, this noise will cause some trees to predict values larger than 0 for this case, thus moving the average prediction of the bagged ensemble away from 0. We observe this effect most strongly with random forests because the base-level trees trained with random forests have relatively high variance due to feature subsetting.” As a result, the calibration curve also referred to as the reliability diagram (Wilks 1995\footnote{On the combination of forecast probabilities for consecutive precipitation periods. Wea. Forecasting, 5, 640–650., Wilks, D. S., 1990a}) shows a characteristic sigmoid shape, indicating that the classifier could trust its “intuition” more and return probabilities closer to 0 or 1 typically.

- `Linear Support Vector Classification (LinearSVC)` shows an even more sigmoid curve than `RandomForestClassifier`, which is typical for maximum-margin methods (compare Niculescu-Mizil and Caruana\footnote{Predicting Good Probabilities with Supervised Learning, A. Niculescu-Mizil & R. Caruana, ICML 2005}).

\footnotesize

1 Predicting Good Probabilities with Supervised Learning, A. Niculescu-Mizil & R. Caruana, ICML 2005
Calibration plots (reliability curve)

Fraction of positives

0.0 0.2 0.4 0.6 0.8 1.0

0.0 0.2 0.4 0.6 0.8 1.0

Perfectly calibrated
Logistic
Naive Bayes
Support Vector Classification
Random Forest

Count

0 5000 10000 15000 20000 25000 30000 35000 40000

0.0 0.2 0.4 0.6 0.8 1.0

Mean predicted value

Logistic
Naive Bayes
Support Vector Classification
Random Forest
Calibrating a classifier

Calibrating a classifier consists of fitting a regressor (called a *calibrator*) that maps the output of the classifier (as given by `decision_function` or `predict_proba`) to a calibrated probability in $[0, 1]$. Denoting the output of the classifier for a given sample by $f_i$, the calibrator tries to predict $p(y_i = 1|f_i)$.

The samples that are used to fit the calibrator should not be the same samples used to fit the classifier, as this would introduce bias. This is because performance of the classifier on its training data would be better than for novel data. Using the classifier output of training data to fit the calibrator would thus result in a biased calibrator that maps to probabilities closer to 0 and 1 than it should.

Usage

The `CalibratedClassifierCV` class is used to calibrate a classifier.

`CalibratedClassifierCV` uses a cross-validation approach to ensure unbiased data is always used to fit the calibrator. The data is split into $k$ `(train_set, test_set)` couples (as determined by `cv`). When `ensemble=True` (default), the following procedure is repeated independently for each cross-validation split: a clone of `base_estimator` is first trained on the train subset. Then its predictions on the test subset are used to fit a calibrator (either a sigmoid or isotonic regressor). This results in an ensemble of $k$ `(classifier, calibrator)` couples where each calibrator maps the output of its corresponding classifier into $[0, 1]$. Each couple is exposed in the `calibrated_classifiers_` attribute, where each entry is a calibrated classifier with a `predict_proba` method that outputs calibrated probabilities. The output of `predict_proba` for the main `CalibratedClassifierCV` instance corresponds to the average of the predicted probabilities of the $k$ estimators in the `calibrated_classifiers_` list. The output of `predict` is the class that has the highest probability.

When `ensemble=False`, cross-validation is used to obtain ‘unbiased’ predictions for all the data, via `cross_val_predict`. These unbiased predictions are then used to train the calibrator. The attribute `calibrated_classifiers_` consists of only one `(classifier, calibrator)` couple where the classifier is the `base_estimator` trained on all the data. In this case the output of `predict_proba` for `CalibratedClassifierCV` is the predicted probabilities obtained from the single `(classifier, calibrator)` couple.

The main advantage of `ensemble=True` is to benefit from the traditional ensembling effect (similar to *Bagging meta-estimator*). The resulting ensemble should both be well calibrated and slightly more accurate than with `ensemble=False`. The main advantage of using `ensemble=False` is computational: it reduces the overall fit time by training only a single base classifier and calibrator pair, decreases the final model size and increases prediction speed.

Alternatively an already fitted classifier can be calibrated by setting `cv="prefit"`. In this case, the data is not split and all of it is used to fit the regressor. It is up to the user to make sure that the data used for fitting the classifier is disjoint from the data used for fitting the regressor.

`sklearn.metrics.brier_score_loss` may be used to assess how well a classifier is calibrated. However, this metric should be used with care because a lower Brier score does not always mean a better calibrated model. This is because the Brier score metric is a combination of calibration loss and refinement loss. Calibration loss is defined as the mean squared deviation from empirical probabilities derived from the slope of ROC segments. Refinement loss can be defined as the expected optimal loss as measured by the area under the optimal cost curve. As refinement loss can change independently from calibration loss, a lower Brier score does not necessarily mean a better calibrated model.

`CalibratedClassifierCV` supports the use of two ‘calibration’ regressors: ‘sigmoid’ and ‘isotonic’.

4.1. Supervised learning
Sigmoid

The sigmoid regressor is based on Platt’s logistic model:\(^3\):

\[
p(y_i = 1 | f_i) = \frac{1}{1 + \exp(A f_i + B)}
\]

where \( y_i \) is the true label of sample \( i \) and \( f_i \) is the output of the un-calibrated classifier for sample \( i \). \( A \) and \( B \) are real numbers to be determined when fitting the regressor via maximum likelihood.

The sigmoid method assumes the **calibration curve** can be corrected by applying a sigmoid function to the raw predictions. This assumption has been empirically justified in the case of Support Vector Machines with common kernel functions on various benchmark datasets in section 2.1 of Platt 1999\(^3\) but does not necessarily hold in general. Additionally, the logistic model works best if the calibration error is symmetrical, meaning the classifier output for each binary class is normally distributed with the same variance\(^6\). This is can be a problem for highly imbalanced classification problems, where outputs do not have equal variance.

In general this method is most effective when the un-calibrated model is under-confident and has similar calibration errors for both high and low outputs.

Isotonic

The ‘isotonic’ method fits a non-parametric isotonic regressor, which outputs a step-wise non-decreasing function (see sklearn.isotonic). It minimizes:

\[
\sum_{i=1}^{n} (y_i - \hat{f}_i)^2
\]

subject to \( \hat{f}_i \geq \hat{f}_j \) whenever \( f_i \geq f_j \). \( y_i \) is the true label of sample \( i \) and \( \hat{f}_i \) is the output of the calibrated classifier for sample \( i \) (i.e., the calibrated probability). This method is more general when compared to ‘sigmoid’ as the only restriction is that the mapping function is monotonically increasing. It is thus more powerful as it can correct any monotonic distortion of the un-calibrated model. However, it is more prone to overfitting, especially on small datasets\(^5\).

Overall, ‘isotonic’ will perform as well as or better than ‘sigmoid’ when there is enough data (greater than ~ 1000 samples) to avoid overfitting\(^1\).

Multiclass support

Both isotonic and sigmoid regressors only support 1-dimensional data (e.g., binary classification output) but are extended for multiclass classification if the base estimator supports multiclass predictions. For multiclass predictions, CalibratedClassifierCV calibrates for each class separately in a OneVsRestClassifier fashion\(^4\). When predicting probabilities, the calibrated probabilities for each class are predicted separately. As those probabilities do not necessarily sum to one, a postprocessing is performed to normalize them.

**Examples:**


• Probability Calibration curves
• Probability Calibration for 3-class classification
• Probability calibration of classifiers
• Comparison of Calibration of Classifiers

References:

4.1.17 Neural network models (supervised)

Warning: This implementation is not intended for large-scale applications. In particular, scikit-learn offers no GPU support. For much faster, GPU-based implementations, as well as frameworks offering much more flexibility to build deep learning architectures, see Related Projects.

Multi-layer Perceptron

Multi-layer Perceptron (MLP) is a supervised learning algorithm that learns a function \( f(\cdot) : \mathbb{R}^m \rightarrow \mathbb{R}^o \) by training on a dataset, where \( m \) is the number of dimensions for input and \( o \) is the number of dimensions for output. Given a set of features \( X = x_1, x_2, ..., x_m \) and a target \( y \), it can learn a non-linear function approximator for either classification or regression. It is different from logistic regression, in that between the input and the output layer, there can be one or more non-linear layers, called hidden layers. Figure 1 shows a one hidden layer MLP with scalar output.

![Figure 1: One hidden layer MLP.](image)

The leftmost layer, known as the input layer, consists of a set of neurons \( \{x_1, x_2, ..., x_m\} \) representing the input features. Each neuron in the hidden layer transforms the values from the previous layer with a weighted linear summation \( w_1 x_1 + w_2 x_2 + ... + w_m x_m \), followed by a non-linear activation function \( g(\cdot) : \mathbb{R} \rightarrow \mathbb{R} \) - like the hyperbolic tan function. The output layer receives the values from the last hidden layer and transforms them into output values.

The module contains the public attributes `coefs_` and `intercepts_`. `coefs_` is a list of weight matrices, where weight matrix at index \( i \) represents the weights between layer \( i \) and layer \( i+1 \). `intercepts_` is a list of bias vectors, where the vector at index \( i \) represents the bias values added to layer \( i+1 \).
The advantages of Multi-layer Perceptron are:

- Capability to learn non-linear models.
- Capability to learn models in real-time (on-line learning) using `partial_fit`.

The disadvantages of Multi-layer Perceptron (MLP) include:

- MLP with hidden layers have a non-convex loss function where there exists more than one local minimum. Therefore different random weight initializations can lead to different validation accuracy.
- MLP requires tuning a number of hyperparameters such as the number of hidden neurons, layers, and iterations.
- MLP is sensitive to feature scaling.

Please see *Tips on Practical Use* section that addresses some of these disadvantages.

**Classification**

Class `MLPClassifier` implements a multi-layer perceptron (MLP) algorithm that trains using Backpropagation.

MLP trains on two arrays: array X of size (n_samples, n_features), which holds the training samples represented as floating point feature vectors; and array y of size (n_samples,), which holds the target values (class labels) for the training samples:

```python
>>> from sklearn.neural_network import MLPClassifier
>>> X = [[0., 0.], [1., 1.]]
>>> y = [0, 1]
>>> clf = MLPClassifier(solver='lbfgs', alpha=1e-5, ...
                          hidden_layer_sizes=(5, 2), random_state=1)
... 
>>> clf.fit(X, y)
MLPClassifier(alpha=1e-05, hidden_layer_sizes=(5, 2), random_state=1, solver='lbfgs')
```

After fitting (training), the model can predict labels for new samples:

```python
>>> clf.predict([[2., 2.], [-1., -2.]])
array([1, 0])
```

MLP can fit a non-linear model to the training data. `clf.coefs_` contains the weight matrices that constitute the model parameters:

```python
>>> [coef.shape for coef in clf.coefs_]
[(2, 5), (5, 2), (2, 1)]
```

Currently, `MLPClassifier` supports only the Cross-Entropy loss function, which allows probability estimates by running the `predict_proba` method.

MLP trains using Backpropagation. More precisely, it trains using some form of gradient descent and the gradients are calculated using Backpropagation. For classification, it minimizes the Cross-Entropy loss function, giving a vector of probability estimates $P(y|x)$ per sample $x$:

```python
>>> clf.predict_proba([[2., 2.], [1., 2.]])
array([[1.967...e-04, 9.998...-01],
       [1.967...e-04, 9.998...-01]])
```

`MLPClassifier` supports multi-class classification by applying Softmax as the output function.
Further, the model supports multi-label classification in which a sample can belong to more than one class. For each class, the raw output passes through the logistic function. Values larger or equal to 0.5 are rounded to 1, otherwise to 0. For a predicted output of a sample, the indices where the value is 1 represents the assigned classes of that sample:

```python
>>> X = [[0., 0.], [1., 1.]]
>>> y = [[0, 1], [1, 1]]
>>> clf = MLPClassifier(solver='lbfgs', alpha=1e-5,
...                     hidden_layer_sizes=(15,), random_state=1)
...  
>>> clf.fit(X, y)
MLPClassifier(alpha=1e-05, hidden_layer_sizes=(15,), random_state=1,
              solver='lbfgs')
>>> clf.predict([[1., 2.]])
array([[1, 1]])
>>> clf.predict([[0., 0.]])
array([[0, 1]])
```

See the examples below and the docstring of `MLPClassifier.fit` for further information.

**Examples:**

- Compare Stochastic learning strategies for `MLPClassifier`
- Visualization of MLP weights on MNIST

**Regression**

Class `MLPRegressor` implements a multi-layer perceptron (MLP) that trains using backpropagation with no activation function in the output layer, which can also be seen as using the identity function as activation function. Therefore, it uses the square error as the loss function, and the output is a set of continuous values. `MLPRegressor` also supports multi-output regression, in which a sample can have more than one target.

**Regularization**

Both `MLPRegressor` and `MLPClassifier` use parameter `alpha` for regularization (L2 regularization) term which helps in avoiding overfitting by penalizing weights with large magnitudes. Following plot displays varying decision function with value of `alpha`.

See the examples below for further information.

**Examples:**

- Varying regularization in Multi-layer Perceptron
Algorithms

MLP trains using Stochastic Gradient Descent, Adam, or L-BFGS. Stochastic Gradient Descent (SGD) updates parameters using the gradient of the loss function with respect to a parameter that needs adaptation, i.e.

\[ w \leftarrow w - \eta (\frac{\partial R(w)}{\partial w} + \frac{\partial \text{Loss}}{\partial w}) \]

where \( \eta \) is the learning rate which controls the step-size in the parameter space search. \( \text{Loss} \) is the loss function used for the network.

More details can be found in the documentation of SGD.

Adam is similar to SGD in a sense that it is a stochastic optimizer, but it can automatically adjust the amount to update parameters based on adaptive estimates of lower-order moments.

With SGD or Adam, training supports online and mini-batch learning.

L-BFGS is a solver that approximates the Hessian matrix which represents the second-order partial derivative of a function. Further it approximates the inverse of the Hessian matrix to perform parameter updates. The implementation uses the Scipy version of L-BFGS.

If the selected solver is ‘L-BFGS’, training does not support online nor mini-batch learning.

Complexity

Suppose there are \( n \) training samples, \( m \) features, \( k \) hidden layers, each containing \( h \) neurons - for simplicity, and \( o \) output neurons. The time complexity of backpropagation is \( O(n \cdot m \cdot h^k \cdot o \cdot i) \), where \( i \) is the number of iterations. Since backpropagation has a high time complexity, it is advisable to start with smaller number of hidden neurons and few hidden layers for training.
Mathematical formulation

Given a set of training examples \((x_1, y_1), (x_2, y_2), \ldots, (x_n, y_n)\) where \(x_i \in \mathbb{R}^n\) and \(y_i \in \{0, 1\}\), a one hidden layer one hidden neuron MLP learns the function \(f(x) = W_2 g(W_1^T x + b_1) + b_2\) where \(W_1 \in \mathbb{R}^m\) and \(W_2, b_1, b_2 \in \mathbb{R}\) are model parameters. \(W_1, W_2\) represent the weights of the input layer and hidden layer, respectively; and \(b_1, b_2\) represent the bias added to the hidden layer and the output layer, respectively. \(g(\cdot) : \mathbb{R} \rightarrow \mathbb{R}\) is the activation function, set by default as the hyperbolic tan. It is given as,

\[
g(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}
\]

For binary classification, \(f(x)\) passes through the logistic function \(g(z) = 1/(1+e^{-z})\) to obtain output values between zero and one. A threshold, set to 0.5, would assign samples of outputs larger or equal 0.5 to the positive class, and the rest to the negative class.

If there are more than two classes, \(f(x)\) itself would be a vector of size \((n_{\text{classes}},)\). Instead of passing through logistic function, it passes through the softmax function, which is written as,

\[
\text{softmax}(z)_i = \frac{\exp(z_i)}{\sum_{k=1}^{K} \exp(z_k)}
\]

where \(z_i\) represents the \(i\)th element of the input to softmax, which corresponds to class \(i\), and \(K\) is the number of classes. The result is a vector containing the probabilities that sample \(x\) belong to each class. The output is the class with the highest probability.

In regression, the output remains as \(f(x)\); therefore, output activation function is just the identity function.

MLP uses different loss functions depending on the problem type. The loss function for classification is Cross-Entropy, which in binary case is given as,

\[
\text{Loss}(\hat{y}, y, W) = -y \ln \hat{y} - (1 - y) \ln (1 - \hat{y}) + \alpha ||W||_2^2
\]

where \(\alpha ||W||_2^2\) is an L2-regularization term (aka penalty) that penalizes complex models; and \(\alpha > 0\) is a non-negative hyperparameter that controls the magnitude of the penalty.

For regression, MLP uses the Square Error loss function; written as,

\[
\text{Loss}(\hat{y}, y, W) = \frac{1}{2} ||\hat{y} - y||_2^2 + \frac{\alpha}{2} ||W||_2^2
\]

Starting from initial random weights, multi-layer perceptron (MLP) minimizes the loss function by repeatedly updating these weights. After computing the loss, a backward pass propagates it from the output layer to the previous layers, providing each weight parameter with an update value meant to decrease the loss.

In gradient descent, the gradient \(\nabla \text{Loss}_W\) of the loss with respect to the weights is computed and deducted from \(W\). More formally, this is expressed as,

\[
W^{i+1} = W^i - \epsilon \nabla \text{Loss}_W^i
\]

where \(i\) is the iteration step, and \(\epsilon\) is the learning rate with a value larger than 0.

The algorithm stops when it reaches a preset maximum number of iterations; or when the improvement in loss is below a certain, small number.
**Tips on Practical Use**

- Multi-layer Perceptron is sensitive to feature scaling, so it is highly recommended to scale your data. For example, scale each attribute on the input vector $X$ to $[0, 1]$ or $[-1, +1]$, or standardize it to have mean 0 and variance 1. Note that you must apply the same scaling to the test set for meaningful results. You can use `StandardScaler` for standardization.

```python
>>> from sklearn.preprocessing import StandardScaler
>>> scaler = StandardScaler()
>>> # Don't cheat - fit only on training data
>>> scaler.fit(X_train)
>>> X_train = scaler.transform(X_train)
>>> # apply same transformation to test data
>>> X_test = scaler.transform(X_test)
```

An alternative and recommended approach is to use `StandardScaler` in a `Pipeline`

- Finding a reasonable regularization parameter $\alpha$ is best done using `GridSearchCV`, usually in the range $10.0^{-\text{np.arange(1, 7)}}$.

- Empirically, we observed that L-BFGS converges faster and with better solutions on small datasets. For relatively large datasets, however, Adam is very robust. It usually converges quickly and gives pretty good performance. SGD with momentum or nesterov’s momentum, on the other hand, can perform better than those two algorithms if learning rate is correctly tuned.

**More control with warm_start**

If you want more control over stopping criteria or learning rate in SGD, or want to do additional monitoring, using `warm_start=True` and `max_iter=1` and iterating yourself can be helpful:

```python
>>> X = [[0., 0.], [1., 1.]]
>>> y = [0, 1]
>>> clf = MLPClassifier(hidden_layer_sizes=(15,), random_state=1, max_iter=1, warm_start=True)
>>> for i in range(10):
...     clf.fit(X, y)
...     # additional monitoring / inspection
```

**References:**

- “Backpropagation” Andrew Ng, JiQuan Ngiam, Chuan Yu Foo, Yifan Mai, Caroline Suen - Website, 2011.
4.2 Unsupervised learning

4.2.1 Gaussian mixture models

sklearn.mixture is a package which enables one to learn Gaussian Mixture Models (diagonal, spherical, tied and full covariance matrices supported), sample them, and estimate them from data. Facilities to help determine the appropriate number of components are also provided.

A Gaussian mixture model is a probabilistic model that assumes all the data points are generated from a mixture of a finite number of Gaussian distributions with unknown parameters. One can think of mixture models as generalizing k-means clustering to incorporate information about the covariance structure of the data as well as the centers of the latent Gaussians.

Scikit-learn implements different classes to estimate Gaussian mixture models, that correspond to different estimation strategies, detailed below.

Gaussian Mixture

The GaussianMixture object implements the expectation-maximization (EM) algorithm for fitting mixture-of-Gaussian models. It can also draw confidence ellipsoids for multivariate models, and compute the Bayesian Information Criterion to assess the number of clusters in the data. A GaussianMixture.fit method is provided that learns a Gaussian Mixture Model from train data. Given test data, it can assign to each sample the Gaussian it mostly probably belong to using the GaussianMixture.predict method.

The GaussianMixture comes with different options to constrain the covariance of the difference classes estimated: spherical, diagonal, tied or full covariance.

Examples:

- See GMM covariances for an example of using the Gaussian mixture as clustering on the iris dataset.
- See Density Estimation for a Gaussian mixture for an example on plotting the density estimation.
Pros and cons of class \texttt{GaussianMixture}

Pros

\textbf{Speed} It is the fastest algorithm for learning mixture models

\textbf{Agnostic} As this algorithm maximizes only the likelihood, it will not bias the means towards zero, or bias the cluster sizes to have specific structures that might or might not apply.

Cons

\textbf{Singularities} When one has insufficiently many points per mixture, estimating the covariance matrices becomes difficult, and the algorithm is known to diverge and find solutions with infinite likelihood unless one regularizes the covariances artificially.

\textbf{Number of components} This algorithm will always use all the components it has access to, needing held-out data or information theoretical criteria to decide how many components to use in the absence of external cues.
Selecting the number of components in a classical Gaussian Mixture Model

The BIC criterion can be used to select the number of components in a Gaussian Mixture in an efficient way. In theory, it recovers the true number of components only in the asymptotic regime (i.e. if much data is available and assuming that the data was actually generated i.i.d. from a mixture of Gaussian distribution). Note that using a Variational Bayesian Gaussian mixture avoids the specification of the number of components for a Gaussian mixture model.

![BIC score per model](image)

### Examples:

- See [Gaussian Mixture Model Selection](#) for an example of model selection performed with classical Gaussian mixture.

Estimation algorithm Expectation-maximization

The main difficulty in learning Gaussian mixture models from unlabeled data is that it is one usually doesn’t know which points came from which latent component (if one has access to this information it gets very easy to fit a separate Gaussian distribution to each set of points). **Expectation-maximization** is a well-founded statistical algorithm to get around this problem by an iterative process. First one assumes random components (randomly centered on data points, learned from k-means, or even just normally distributed around the origin) and computes for each point a probability of being generated by each component of the model. Then, one tweaks the parameters to maximize the likelihood of the data given those assignments. Repeating this process is guaranteed to always converge to a local optimum.
Variational Bayesian Gaussian Mixture

The `BayesianGaussianMixture` object implements a variant of the Gaussian mixture model with variational inference algorithms. The API is similar as the one defined by `GaussianMixture`.

Estimation algorithm: variational inference

Variational inference is an extension of expectation-maximization that maximizes a lower bound on model evidence (including priors) instead of data likelihood. The principle behind variational methods is the same as expectation-maximization (that is both are iterative algorithms that alternate between finding the probabilities for each point to be generated by each mixture and fitting the mixture to these assigned points), but variational methods add regularization by integrating information from prior distributions. This avoids the singularities often found in expectation-maximization solutions but introduces some subtle biases to the model. Inference is often notably slower, but not usually as much so as to render usage impractical.

Due to its Bayesian nature, the variational algorithm needs more hyper-parameters than expectation-maximization, the most important of these being the concentration parameter `weight_concentration_prior`. Specifying a low value for the concentration prior will make the model put most of the weight on few components set the remaining components weights very close to zero. High values of the concentration prior will allow a larger number of components to be active in the mixture.

The parameters implementation of the `BayesianGaussianMixture` class proposes two types of prior for the weights distribution: a finite mixture model with Dirichlet distribution and an infinite mixture model with the Dirichlet Process. In practice Dirichlet Process inference algorithm is approximated and uses a truncated distribution with a fixed maximum number of components (called the Stick-breaking representation). The number of components actually used almost always depends on the data.

The next figure compares the results obtained for the different type of the weight concentration prior (parameter `weight_concentration_prior_type`) for different values of `weight_concentration_prior`. Here, we can see the value of the `weight_concentration_prior` parameter has a strong impact on the effective number of active components obtained. We can also notice that large values for the concentration weight prior lead to more uniform weights when the type of prior is ‘dirichlet_distribution’ while this is not necessarily the case for the ‘dirichlet_process’ type (used by default).
The examples below compare Gaussian mixture models with a fixed number of components, to the variational Gaussian mixture models with a Dirichlet process prior. Here, a classical Gaussian mixture is fitted with 5 components on a dataset composed of 2 clusters. We can see that the variational Gaussian mixture with a Dirichlet process prior is able to limit itself to only 2 components whereas the Gaussian mixture fits the data with a fixed number of components that has to be set a priori by the user. In this case the user has selected `n_components=5` which does not match the true generative distribution of this toy dataset. Note that with very little observations, the variational Gaussian mixture models with a Dirichlet process prior can take a conservative stand, and fit only one component.

On the following figure we are fitting a dataset not well-depicted by a Gaussian mixture. Adjusting the
weight_concentration_prior, parameter of the BayesianGaussianMixture controls the number of components used to fit this data. We also present on the last two plots a random sampling generated from the two resulting mixtures.

Examples:

- See Gaussian Mixture Model Ellipsoids for an example on plotting the confidence ellipsoids for both GaussianMixture and BayesianGaussianMixture.

- Gaussian Mixture Model Sine Curve shows using GaussianMixture and BayesianGaussianMixture to fit a sine wave.

- See Concentration Prior Type Analysis of Variation Bayesian Gaussian Mixture for an example plotting the confidence ellipsoids for the BayesianGaussianMixture with different weight_concentration_prior_type for different values of the parameter weight_concentration_prior.

Pros and cons of variational inference with BayesianGaussianMixture

Pros

Automatic selection when weight_concentration_prior is small enough and n_components is larger than what is found necessary by the model, the Variational Bayesian mixture model has a natural tendency to set some mixture weights values close to zero. This makes it possible to let the model choose a suitable number of effective components automatically. Only an upper bound of this number needs to be provided. Note however that the “ideal” number of active components is very application specific and is typically ill-defined in a data exploration setting.

Less sensitivity to the number of parameters unlike finite models, which will almost always use all components as much as they can, and hence will produce wildly different solutions for different numbers of components, the variational inference with a Dirichlet process prior
4.2. Unsupervised learning

Random samples from Gaussian mixture models with a Dirichlet process prior for $\gamma_0 = 0.01$.

Bayesian Gaussian mixture models with a Dirichlet process prior for $\gamma_0 = 100$.

Gaussian mixture with a Dirichlet process prior for $\gamma_0 = 0.01$ sampled with 2000 samples.

Gaussian mixture with a Dirichlet process prior for $\gamma_0 = 100$ sampled with 2000 samples.
(weight_concentration_prior_type='dirichlet_process') won’t change much with changes to the parameters, leading to more stability and less tuning.

**Regularization** due to the incorporation of prior information, variational solutions have less pathological special cases than expectation-maximization solutions.

**Cons**

- **Speed** the extra parametrization necessary for variational inference make inference slower, although not by much.
- **Hyperparameters** this algorithm needs an extra hyperparameter that might need experimental tuning via cross-validation.
- **Bias** there are many implicit biases in the inference algorithms (and also in the Dirichlet process if used), and whenever there is a mismatch between these biases and the data it might be possible to fit better models using a finite mixture.

**The Dirichlet Process**

Here we describe variational inference algorithms on Dirichlet process mixture. The Dirichlet process is a prior probability distribution on clusterings with an infinite, unbounded, number of partitions. Variational techniques let us incorporate this prior structure on Gaussian mixture models at almost no penalty in inference time, comparing with a finite Gaussian mixture model.

An important question is how can the Dirichlet process use an infinite, unbounded number of clusters and still be consistent. While a full explanation doesn’t fit this manual, one can think of its stick breaking process analogy to help understanding it. The stick breaking process is a generative story for the Dirichlet process. We start with a unit-length stick and in each step we break off a portion of the remaining stick. Each time, we associate the length of the piece of the stick to the proportion of points that falls into a group of the mixture. At the end, to represent the infinite mixture, we associate the last remaining piece of the stick to the proportion of points that don’t fall into all the other groups. The length of each piece is a random variable with probability proportional to the concentration parameter. Smaller value of the concentration will divide the unit-length into larger pieces of the stick (defining more concentrated distribution). Larger concentration values will create smaller pieces of the stick (increasing the number of components with non zero weights).

Variational inference techniques for the Dirichlet process still work with a finite approximation to this infinite mixture model, but instead of having to specify a priori how many components one wants to use, one just specifies the concentration parameter and an upper bound on the number of mixture components (this upper bound, assuming it is higher than the “true” number of components, affects only algorithmic complexity, not the actual number of components used).

**4.2.2 Manifold learning**

Look for the bare necessities
The simple bare necessities
Forget about your worries and your strife
I mean the bare necessities
Old Mother Nature’s recipes
That bring the bare necessities of life

– Baloo’s song [The Jungle Book]
Manifold learning is an approach to non-linear dimensionality reduction. Algorithms for this task are based on the idea that the dimensionality of many data sets is only artificially high.

**Introduction**

High-dimensional datasets can be very difficult to visualize. While data in two or three dimensions can be plotted to show the inherent structure of the data, equivalent high-dimensional plots are much less intuitive. To aid visualization of the structure of a dataset, the dimension must be reduced in some way.

The simplest way to accomplish this dimensionality reduction is by taking a random projection of the data. Though this allows some degree of visualization of the data structure, the randomness of the choice leaves much to be desired. In a random projection, it is likely that the more interesting structure within the data will be lost.

To address this concern, a number of supervised and unsupervised linear dimensionality reduction frameworks have been designed, such as Principal Component Analysis (PCA), Independent Component Analysis, Linear Discriminant Analysis, and others. These algorithms define specific rubrics to choose an “interesting” linear projection of the data. These methods can be powerful, but often miss important non-linear structure in the data.
Manifold Learning can be thought of as an attempt to generalize linear frameworks like PCA to be sensitive to non-linear structure in data. Though supervised variants exist, the typical manifold learning problem is unsupervised: it learns the high-dimensional structure of the data from the data itself, without the use of predetermined classifications.

Examples:

- See *Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...* for an example of dimensionality reduction on handwritten digits.
- See *Comparison of Manifold Learning methods* for an example of dimensionality reduction on a toy “S-curve” dataset.

The manifold learning implementations available in scikit-learn are summarized below

Isomap

One of the earliest approaches to manifold learning is the Isomap algorithm, short for Isometric Mapping. Isomap can be viewed as an extension of Multi-dimensional Scaling (MDS) or Kernel PCA. Isomap seeks a lower-dimensional embedding which maintains geodesic distances between all points. Isomap can be performed with the object `Isomap`. 
Complexity

The Isomap algorithm comprises three stages:

1. **Nearest neighbor search.** Isomap uses `BallTree` for efficient neighbor search. The cost is approximately $O[D \log(k)N \log(N)]$, for $k$ nearest neighbors of $N$ points in $D$ dimensions.

2. **Shortest-path graph search.** The most efficient known algorithms for this are Dijkstra’s Algorithm, which is approximately $O[N^2(k + \log(N))]$, or the Floyd-Warshall algorithm, which is $O[N^3]$. The algorithm can be selected by the user with the `path_method` keyword of `Isomap`. If unspecified, the code attempts to choose the best algorithm for the input data.

3. **Partial eigenvalue decomposition.** The embedding is encoded in the eigenvectors corresponding to the $d$ largest eigenvalues of the $N \times N$ isomap kernel. For a dense solver, the cost is approximately $O[dN^2]$. This cost can often be improved using the ARPACK solver. The eigensolver can be specified by the user with the `eigen_solver` keyword of `Isomap`. If unspecified, the code attempts to choose the best algorithm for the input data.

The overall complexity of Isomap is $O[D \log(k)N \log(N)] + O[N^2(k + \log(N))] + O[dN^2]$.

- $N$: number of training data points
- $D$: input dimension
- $k$: number of nearest neighbors
- $d$: output dimension

References:

- “A global geometric framework for nonlinear dimensionality reduction” Tenenbaum, J.B.; De Silva, V.; & Langford, J.C. Science 290 (5500)

Locally Linear Embedding

Locally linear embedding (LLE) seeks a lower-dimensional projection of the data which preserves distances within local neighborhoods. It can be thought of as a series of local Principal Component Analyses which are globally compared to find the best non-linear embedding.

Locally linear embedding can be performed with function `locally_linear_embedding` or its object-oriented counterpart `LocallyLinearEmbedding`.

Complexity

The standard LLE algorithm comprises three stages:

1. **Nearest Neighbors Search.** See discussion under Isomap above.

2. **Weight Matrix Construction.** $O[DNk^3]$. The construction of the LLE weight matrix involves the solution of a $k \times k$ linear equation for each of the $N$ local neighborhoods

3. **Partial Eigenvalue Decomposition.** See discussion under Isomap above.

The overall complexity of standard LLE is $O[D \log(k)N \log(N)] + O[DNk^3] + O[dN^2]$.

- $N$: number of training data points
- $D$: input dimension
• $k$: number of nearest neighbors
• $d$: output dimension

References:


Modified Locally Linear Embedding

One well-known issue with LLE is the regularization problem. When the number of neighbors is greater than the number of input dimensions, the matrix defining each local neighborhood is rank-deficient. To address this, standard LLE applies an arbitrary regularization parameter $r$, which is chosen relative to the trace of the local weight matrix. Though it can be shown formally that as $r \to 0$, the solution converges to the desired embedding, there is no guarantee that the optimal solution will be found for $r > 0$. This problem manifests itself in embeddings which distort the underlying geometry of the manifold.

One method to address the regularization problem is to use multiple weight vectors in each neighborhood. This is the essence of modified locally linear embedding (MLLE). MLLE can be performed with function `LocallyLinearEmbedding` or its object-oriented counterpart `locally_linear_embedding`, with the keyword `method = 'modified'`. It requires $n_{neighbors} > n_{components}$.

Complexity

The MLLE algorithm comprises three stages:

1. **Nearest Neighbors Search.** Same as standard LLE
2. **Weight Matrix Construction.** Approximately $O[DNk^3] + O[N(k-D)k^2]$. The first term is exactly equivalent to that of standard LLE. The second term has to do with constructing the weight matrix from multiple weights. In practice, the added cost of constructing the MLLE weight matrix is relatively small compared to the cost of stages 1 and 3.
3. **Partial Eigenvalue Decomposition.** Same as standard LLE

The overall complexity of MLLE is $O[\log(k)N\log(N)] + O[DNk^3] + O[N(k-D)k^2] + O[dN^2]$. 
• $N$: number of training data points
• $D$: input dimension
• $k$: number of nearest neighbors
• $d$: output dimension

References:

• “MLLE: Modified Locally Linear Embedding Using Multiple Weights” Zhang, Z. & Wang, J.

Hessian Eigenmapping

Hessian Eigenmapping (also known as Hessian-based LLE: HLLE) is another method of solving the regularization problem of LLE. It revolves around a hessian-based quadratic form at each neighborhood which is used to recover the locally linear structure. Though other implementations note its poor scaling with data size, sklearn implements some algorithmic improvements which make its cost comparable to that of other LLE variants for small output dimension. HLLE can be performed with function `locally_linear_embedding` or its object-oriented counterpart `LocallyLinearEmbedding`, with the keyword `method = 'hessian'`. It requires $n_{neighbors} > n_{components} \cdot (n_{components} + 3) / 2$. 
Complexity

The HLLE algorithm comprises three stages:

1. **Nearest Neighbors Search.** Same as standard LLE
2. **Weight Matrix Construction.** Approximately $O[DNk^3] + O[Nd^6]$. The first term reflects a similar cost to that of standard LLE. The second term comes from a QR decomposition of the local hessian estimator.
3. **Partial Eigenvalue Decomposition.** Same as standard LLE


- $N$: number of training data points
- $D$: input dimension
- $k$: number of nearest neighbors
- $d$: output dimension

References:


Spectral Embedding

Spectral Embedding is an approach to calculating a non-linear embedding. Scikit-learn implements Laplacian Eigenmaps, which finds a low dimensional representation of the data using a spectral decomposition of the graph Laplacian. The graph generated can be considered as a discrete approximation of the low dimensional manifold in the high dimensional space. Minimization of a cost function based on the graph ensures that points close to each other on the manifold are mapped close to each other in the low dimensional space, preserving local distances. Spectral embedding can be performed with the function `spectral_embedding` or its object-oriented counterpart `SpectralEmbedding`.

Complexity

The Spectral Embedding (Laplacian Eigenmaps) algorithm comprises three stages:

1. **Weighted Graph Construction.** Transform the raw input data into graph representation using affinity (adjacency) matrix representation.
2. **Graph Laplacian Construction.** Unnormalized Graph Laplacian is constructed as $L = D - A$ for and normalized one as $L = D^{-\frac{1}{2}}(D - A)D^{-\frac{1}{2}}$.
3. **Partial Eigenvalue Decomposition.** Eigenvalue decomposition is done on graph Laplacian

The overall complexity of spectral embedding is $O[D\log(k)N\log(N)] + O[DNk^3] + O[dN^2]$.

- $N$: number of training data points
- $D$: input dimension
- $k$: number of nearest neighbors
- $d$: output dimension
Local Tangent Space Alignment

Though not technically a variant of LLE, Local tangent space alignment (LTSA) is algorithmically similar enough to LLE that it can be put in this category. Rather than focusing on preserving neighborhood distances as in LLE, LTSA seeks to characterize the local geometry at each neighborhood via its tangent space, and performs a global optimization to align these local tangent spaces to learn the embedding. LTSA can be performed with function `locally_linear_embedding` or its object-oriented counterpart `LocallyLinearEmbedding`, with the keyword `method = 'ltsa'`.

Complexity

The LTSA algorithm comprises three stages:

1. **Nearest Neighbors Search.** Same as standard LLE
2. **Weight Matrix Construction.** Approximately $O[D N k^3] + O[k^2 d]$. The first term reflects a similar cost to that of standard LLE.
3. **Partial Eigenvalue Decomposition.** Same as standard LLE

The overall complexity of standard LTSA is $O[D \log(k) N \log(N)] + O[D N k^3] + O[k^2 d] + O[dN^2]$.

- $N$ : number of training data points
- $D$ : input dimension
- $k$ : number of nearest neighbors
- $d$ : output dimension

References:

- “Laplacian Eigenmaps for Dimensionality Reduction and Data Representation” M. Belkin, P. Niyogi, Neural Computation, June 2003; 15 (6):1373-1396
Multi-dimensional Scaling (MDS)

Multidimensional scaling (MDS) seeks a low-dimensional representation of the data in which the distances respect well the distances in the original high-dimensional space.

In general, MDS is a technique used for analyzing similarity or dissimilarity data. It attempts to model similarity or dissimilarity data as distances in a geometric spaces. The data can be ratings of similarity between objects, interaction frequencies of molecules, or trade indices between countries.

There exists two types of MDS algorithm: metric and non metric. In the scikit-learn, the class MDS implements both. In Metric MDS, the input similarity matrix arises from a metric (and thus respects the triangular inequality), the distances between output two points are then set to be as close as possible to the similarity or dissimilarity data. In the non-metric version, the algorithms will try to preserve the order of the distances, and hence seek for a monotonic relationship between the distances in the embedded space and the similarities/dissimilarities.

Let $S$ be the similarity matrix, and $X$ the coordinates of the $n$ input points. Disparities $\hat{d}_{ij}$ are transformation of the similarities chosen in some optimal ways. The objective, called the stress, is then defined by $\sum_{i<j} d_{ij}(X) - \hat{d}_{ij}(X)$
Metric MDS

The simplest metric MDS model, called absolute MDS, disparities are defined by \( \hat{d}_{ij} = S_{ij} \). With absolute MDS, the value \( S_{ij} \) should then correspond exactly to the distance between point \( i \) and \( j \) in the embedding point.

Most commonly, disparities are set to \( \hat{d}_{ij} = bS_{ij} \).

Nonmetric MDS

Non metric MDS focuses on the ordination of the data. If \( S_{ij} < S_{jk} \), then the embedding should enforce \( d_{ij} < d_{jk} \). A simple algorithm to enforce that is to use a monotonic regression of \( d_{ij} \) on \( S_{ij} \), yielding disparities \( \hat{d}_{ij} \) in the same order as \( S_{ij} \).

A trivial solution to this problem is to set all the points on the origin. In order to avoid that, the disparities \( \hat{d}_{ij} \) are normalized.

References:

- “Nonmetric multidimensional scaling: a numerical method” Kruskal, J. Psychometrika, 29 (1964)
- “Multidimensional scaling by optimizing goodness of fit to a nonmetric hypothesis” Kruskal, J. Psychometrika, 29, (1964)
t-distributed Stochastic Neighbor Embedding (t-SNE)

**t-SNE (TSNE)** converts affinities of data points to probabilities. The affinities in the original space are represented by Gaussian joint probabilities and the affinities in the embedded space are represented by Student’s t-distributions. This allows t-SNE to be particularly sensitive to local structure and has a few other advantages over existing techniques:

- Revealing the structure at many scales on a single map
- Revealing data that lie in multiple, different, manifolds or clusters
- Reducing the tendency to crowd points together at the center

While Isomap, LLE and variants are best suited to unfold a single continuous low dimensional manifold, t-SNE will focus on the local structure of the data and will tend to extract clustered local groups of samples as highlighted on the S-curve example. This ability to group samples based on the local structure might be beneficial to visually disentangle a dataset that comprises several manifolds at once as is the case in the digits dataset.

The Kullback-Leibler (KL) divergence of the joint probabilities in the original space and the embedded space will be minimized by gradient descent. Note that the KL divergence is not convex, i.e. multiple restarts with different initializations will end up in local minima of the KL divergence. Hence, it is sometimes useful to try different seeds and select the embedding with the lowest KL divergence.

The disadvantages to using t-SNE are roughly:

- t-SNE is computationally expensive, and can take several hours on million-sample datasets where PCA will finish in seconds or minutes
- The Barnes-Hut t-SNE method is limited to two or three dimensional embeddings.
- The algorithm is stochastic and multiple restarts with different seeds can yield different embeddings. However, it is perfectly legitimate to pick the embedding with the least error.
- Global structure is not explicitly preserved. This problem is mitigated by initializing points with PCA (using `init='pca'`).

![t-SNE embedding of the digits (time 6.30s)](image)
Optimizing t-SNE

The main purpose of t-SNE is visualization of high-dimensional data. Hence, it works best when the data will be embedded on two or three dimensions.

Optimizing the KL divergence can be a little bit tricky sometimes. There are five parameters that control the optimization of t-SNE and therefore possibly the quality of the resulting embedding:

- perplexity
- early exaggeration factor
- learning rate
- maximum number of iterations
- angle (not used in the exact method)

The perplexity is defined as $k = 2^S$ where $S$ is the Shannon entropy of the conditional probability distribution. The perplexity of a $k$-sided die is $k$, so that $k$ is effectively the number of nearest neighbors t-SNE considers when generating the conditional probabilities. Larger perplexities lead to more nearest neighbors and less sensitive to small structure. Conversely a lower perplexity considers a smaller number of neighbors, and thus ignores more global information in favour of the local neighborhood. As dataset sizes get larger more points will be required to get a reasonable sample of the local neighborhood, and hence larger perplexities may be required. Similarly noisier datasets will require larger perplexity values to encompass enough local neighbors to see beyond the background noise.

The maximum number of iterations is usually high enough and does not need any tuning. The optimization consists of two phases: the early exaggeration phase and the final optimization. During early exaggeration the joint probabilities in the original space will be artificially increased by multiplication with a given factor. Larger factors result in larger gaps between natural clusters in the data. If the factor is too high, the KL divergence could increase during this phase. Usually it does not have to be tuned. A critical parameter is the learning rate. If it is too low gradient descent will get stuck in a bad local minimum. If it is too high the KL divergence will increase during optimization. More tips can be found in Laurens van der Maaten’s FAQ (see references). The last parameter, angle, is a tradeoff between performance and accuracy. Larger angles imply that we can approximate larger regions by a single point, leading to better speed but less accurate results.

“How to Use t-SNE Effectively” provides a good discussion of the effects of the various parameters, as well as interactive plots to explore the effects of different parameters.

Barnes-Hut t-SNE

The Barnes-Hut t-SNE that has been implemented here is usually much slower than other manifold learning algorithms. The optimization is quite difficult and the computation of the gradient is $O[dN\log(N)]$, where $d$ is the number of output dimensions and $N$ is the number of samples. The Barnes-Hut method improves on the exact method where t-SNE complexity is $O[dN^2]$, but has several other notable differences:

- The Barnes-Hut implementation only works when the target dimensionality is 3 or less. The 2D case is typical when building visualizations.
- Barnes-Hut only works with dense input data. Sparse data matrices can only be embedded with the exact method or can be approximated by a dense low rank projection for instance using TruncatedSVD
- Barnes-Hut is an approximation of the exact method. The approximation is parameterized with the angle parameter, therefore the angle parameter is unused when method=“exact”
- Barnes-Hut is significantly more scalable. Barnes-Hut can be used to embed hundred of thousands of data points while the exact method can handle thousands of samples before becoming computationally intractable
For visualization purpose (which is the main use case of t-SNE), using the Barnes-Hut method is strongly recommended. The exact t-SNE method is useful for checking the theoretically properties of the embedding possibly in higher dimensional space but limit to small datasets due to computational constraints.

Also note that the digits labels roughly match the natural grouping found by t-SNE while the linear 2D projection of the PCA model yields a representation where label regions largely overlap. This is a strong clue that this data can be well separated by non linear methods that focus on the local structure (e.g. an SVM with a Gaussian RBF kernel). However, failing to visualize well separated homogeneously labeled groups with t-SNE in 2D does not necessarily imply that the data cannot be correctly classified by a supervised model. It might be the case that 2 dimensions are not low enough to accurately represents the internal structure of the data.

References:

• “t-Distributed Stochastic Neighbor Embedding” van der Maaten, L.J.P.

Tips on practical use

• Make sure the same scale is used over all features. Because manifold learning methods are based on a nearest-neighbor search, the algorithm may perform poorly otherwise. See StandardScaler for convenient ways of scaling heterogeneous data.
• The reconstruction error computed by each routine can be used to choose the optimal output dimension. For a \( d \)-dimensional manifold embedded in a \( D \)-dimensional parameter space, the reconstruction error will decrease as \( \text{n\_components} \) is increased until \( \text{n\_components} == d \).
• Note that noisy data can “short-circuit” the manifold, in essence acting as a bridge between parts of the manifold that would otherwise be well-separated. Manifold learning on noisy and/or incomplete data is an active area of research.
• Certain input configurations can lead to singular weight matrices, for example when more than two points in the dataset are identical, or when the data is split into disjointed groups. In this case, solver='arpack' will fail to find the null space. The easiest way to address this is to use solver='dense' which will work on a singular matrix, though it may be very slow depending on the number of input points. Alternatively, one can attempt to understand the source of the singularity: if it is due to disjoint sets, increasing n_neighbors may help. If it is due to identical points in the dataset, removing these points may help.

See also:

Totally Random Trees Embedding can also be useful to derive non-linear representations of feature space, also it does not perform dimensionality reduction.
4.2.3 Clustering

Clustering of unlabeled data can be performed with the module `sklearn.cluster`.

Each clustering algorithm comes in two variants: a class, that implements the `fit` method to learn the clusters on train data, and a function, that, given train data, returns an array of integer labels corresponding to the different clusters. For the class, the labels over the training data can be found in the `labels_` attribute.

**Input data**

One important thing to note is that the algorithms implemented in this module can take different kinds of matrix as input. All the methods accept standard data matrices of shape `(n_samples, n_features)`. These can be obtained from the classes in the `sklearn.feature_extraction` module. For `AffinityPropagation`, `SpectralClustering` and `DBSCAN` one can also input similarity matrices of shape `(n_samples, n_samples)`. These can be obtained from the functions in the `sklearn.metrics.pairwise` module.

**Overview of clustering methods**

![Fig. 5: A comparison of the clustering algorithms in scikit-learn](image)
**Table of Clustering Methods**

<table>
<thead>
<tr>
<th>Method name</th>
<th>Parameters</th>
<th>Scalability</th>
<th>Usecase</th>
<th>Geometry (metric used)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>K-Means</strong></td>
<td>number of clusters</td>
<td>Very large (n_{samples}), medium (n_{clusters}) with <strong>MiniBatch code</strong></td>
<td>General-purpose, even cluster size, flat geometry, not too many clusters</td>
<td>Distances between points</td>
</tr>
<tr>
<td><strong>Affinity propagation</strong></td>
<td>damping, sample preference</td>
<td>Not scalable with (n_{samples})</td>
<td>Many clusters, uneven cluster size, non-flat geometry</td>
<td>Graph distance (e.g. nearest-neighbor graph)</td>
</tr>
<tr>
<td><strong>Mean-shift</strong></td>
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<td>Not scalable with (n_{samples})</td>
<td>Many clusters, uneven cluster size, non-flat geometry</td>
<td>Distances between points</td>
</tr>
<tr>
<td><strong>Spectral clustering</strong></td>
<td>number of clusters</td>
<td>Medium (n_{samples}), small (n_{clusters})</td>
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</tr>
<tr>
<td><strong>Ward hierarchical clustering</strong></td>
<td>number of clusters or distance threshold</td>
<td>Large (n_{samples}) and (n_{clusters})</td>
<td>Many clusters, possibly connectivity constraints</td>
<td>Distances between points</td>
</tr>
<tr>
<td><strong>Agglomerative clustering</strong></td>
<td>number of clusters or distance threshold, linkage type, distance</td>
<td>Large (n_{samples}) and (n_{clusters})</td>
<td>Many clusters, possibly connectivity constraints, non Euclidean distances</td>
<td>Any pairwise distance</td>
</tr>
<tr>
<td><strong>DBSCAN</strong></td>
<td>neighborhood size</td>
<td>Very large (n_{samples}), medium (n_{clusters})</td>
<td>Non-flat geometry, uneven cluster sizes</td>
<td>Distances between nearest points</td>
</tr>
<tr>
<td><strong>OPTICS</strong></td>
<td>minimum cluster membership</td>
<td>Very large (n_{samples}), large (n_{clusters})</td>
<td>Non-flat geometry, uneven cluster sizes, variable cluster density</td>
<td>Distances between points</td>
</tr>
<tr>
<td><strong>Gaussian mixtures</strong></td>
<td>many</td>
<td>Not scalable</td>
<td>Flat geometry, good for density estimation</td>
<td>Mahalanobis distances to centers</td>
</tr>
<tr>
<td><strong>Birch</strong></td>
<td>branching factor, threshold, optional global clusterer.</td>
<td>Large (n_{clusters}) and (n_{samples})</td>
<td>Large dataset, outlier removal, data reduction.</td>
<td>Euclidean distance between points</td>
</tr>
</tbody>
</table>

Non-flat geometry clustering is useful when the clusters have a specific shape, i.e. a non-flat manifold, and the standard euclidean distance is not the right metric. This case arises in the two top rows of the figure above.

Gaussian mixture models, useful for clustering, are described in another chapter of the documentation dedicated to mixture models. **KMeans** can be seen as a special case of Gaussian mixture model with equal covariance per component.
K-means

The KMeans algorithm clusters data by trying to separate samples in n groups of equal variance, minimizing a criterion known as the inertia or within-cluster sum-of-squares (see below). This algorithm requires the number of clusters to be specified. It scales well to large number of samples and has been used across a large range of application areas in many different fields.

The k-means algorithm divides a set of \( N \) samples \( X \) into \( K \) disjoint clusters \( C \), each described by the mean \( \mu_j \) of the samples in the cluster. The means are commonly called the cluster “centroids”; note that they are not, in general, points from \( X \), although they live in the same space.

The K-means algorithm aims to choose centroids that minimise the inertia, or within-cluster sum-of-squares criterion:

\[
\sum_{i=0}^{n} \min_{\mu_j \in C}(||x_i - \mu_j||^2)
\]

Inertia can be recognized as a measure of how internally coherent clusters are. It suffers from various drawbacks:

- Inertia makes the assumption that clusters are convex and isotropic, which is not always the case. It responds poorly to elongated clusters, or manifolds with irregular shapes.
- Inertia is not a normalized metric: we just know that lower values are better and zero is optimal. But in very high-dimensional spaces, Euclidean distances tend to become inflated (this is an instance of the so-called “curse of dimensionality”). Running a dimensionality reduction algorithm such as Principal component analysis (PCA) prior to k-means clustering can alleviate this problem and speed up the computations.
K-means is often referred to as Lloyd’s algorithm. In basic terms, the algorithm has three steps. The first step chooses the initial centroids, with the most basic method being to choose $k$ samples from the dataset $X$. After initialization, K-means consists of looping between the two other steps. The first step assigns each sample to its nearest centroid. The second step creates new centroids by taking the mean value of all of the samples assigned to each previous centroid. The difference between the old and the new centroids are computed and the algorithm repeats these last two steps until this value is less than a threshold. In other words, it repeats until the centroids do not move significantly.
K-means is equivalent to the expectation-maximization algorithm with a small, all-equal, diagonal covariance matrix. The algorithm can also be understood through the concept of Voronoi diagrams. First the Voronoi diagram of the points is calculated using the current centroids. Each segment in the Voronoi diagram becomes a separate cluster. Secondly, the centroids are updated to the mean of each segment. The algorithm then repeats this until a stopping criterion is fulfilled. Usually, the algorithm stops when the relative decrease in the objective function between iterations is less than the given tolerance value. This is not the case in this implementation: iteration stops when centroids move less than the tolerance.

Given enough time, K-means will always converge, however this may be to a local minimum. This is highly dependent on the initialization of the centroids. As a result, the computation is often done several times, with different initializations of the centroids. One method to help address this issue is the k-means++ initialization scheme, which has been implemented in scikit-learn (use the init='k-means++' parameter). This initializes the centroids to be (generally) distant from each other, leading to provably better results than random initialization, as shown in the reference.

K-means++ can also be called independently to select seeds for other clustering algorithms, see sklearn.cluster.kmeans_plusplus for details and example usage.

The algorithm supports sample weights, which can be given by a parameter sample_weight. This allows to assign more weight to some samples when computing cluster centers and values of inertia. For example, assigning a weight of 2 to a sample is equivalent to adding a duplicate of that sample to the dataset $X$.

K-means can be used for vector quantization. This is achieved using the transform method of a trained model of KMeans.

Low-level parallelism

KMeans benefits from OpenMP based parallelism through Cython. Small chunks of data (256 samples) are processed in parallel, which in addition yields a low memory footprint. For more details on how to control the number of threads, please refer to our Parallelism notes.

Examples:

- Demonstration of k-means assumptions: Demonstrating when k-means performs intuitively and when it does not
- A demo of K-Means clustering on the handwritten digits data: Clustering handwritten digits

References:

**Mini Batch K-Means**

The *MiniBatchKMeans* is a variant of the *KMeans* algorithm which uses mini-batches to reduce the computation time, while still attempting to optimise the same objective function. Mini-batches are subsets of the input data, randomly sampled in each training iteration. These mini-batches drastically reduce the amount of computation required to converge to a local solution. In contrast to other algorithms that reduce the convergence time of k-means, mini-batch k-means produces results that are generally only slightly worse than the standard algorithm.

The algorithm iterates between two major steps, similar to vanilla k-means. In the first step, $b$ samples are drawn randomly from the dataset, to form a mini-batch. These are then assigned to the nearest centroid. In the second step, the centroids are updated. In contrast to k-means, this is done on a per-sample basis. For each sample in the mini-batch, the assigned centroid is updated by taking the streaming average of the sample and all previous samples assigned to that centroid. This has the effect of decreasing the rate of change for a centroid over time. These steps are performed until convergence or a predetermined number of iterations is reached. *MiniBatchKMeans* converges faster than *KMeans*, but the quality of the results is reduced. In practice this difference in quality can be quite small, as shown in the example and cited reference.

Examples:

- *Comparison of the K-Means and MiniBatchKMeans clustering algorithms*: Comparison of KMeans and MiniBatchKMeans
- *Clustering text documents using k-means*: Document clustering using sparse MiniBatchKMeans
- *Online learning of a dictionary of parts of faces*

References:

Affinity Propagation

*AffinityPropagation* creates clusters by sending messages between pairs of samples until convergence. A dataset is then described using a small number of exemplars, which are identified as those most representative of other samples. The messages sent between pairs represent the suitability for one sample to be the exemplar of the other, which is updated in response to the values from other pairs. This updating happens iteratively until convergence, at which point the final exemplars are chosen, and hence the final clustering is given.

Affinity Propagation can be interesting as it chooses the number of clusters based on the data provided. For this purpose, the two important parameters are the *preference*, which controls how many exemplars are used, and the *damping factor* which damps the responsibility and availability messages to avoid numerical oscillations when updating these messages.

The main drawback of Affinity Propagation is its complexity. The algorithm has a time complexity of the order $O(N^2T)$, where $N$ is the number of samples and $T$ is the number of iterations until convergence. Further, the memory complexity is of the order $O(N^2)$ if a dense similarity matrix is used, but reducible if a sparse similarity matrix is used. This makes Affinity Propagation most appropriate for small to medium sized datasets.

**Examples:**

- *Demo of affinity propagation clustering algorithm*: Affinity Propagation on a synthetic 2D datasets with 3 classes.
- *Visualizing the stock market structure* Affinity Propagation on Financial time series to find groups of companies

**Algorithm description:** The messages sent between points belong to one of two categories. The first is the responsibility $r(i, k)$, which is the accumulated evidence that sample $k$ should be the exemplar for sample $i$. The second is the availability $a(i, k)$ which is the accumulated evidence that sample $i$ should choose sample $k$ to be its exemplar, and considers the values for all other samples that $k$ should be an exemplar. In this way, exemplars are chosen by samples if they are (1) similar enough to many samples and (2) chosen by many samples to be representative of themselves.

More formally, the responsibility of a sample $k$ to be the exemplar of sample $i$ is given by:

$$r(i, k) \leftarrow s(i, k) - \max\{a(i, k') + s(i, k') | \forall k' \neq k\}$$

Where $s(i, k)$ is the similarity between samples $i$ and $k$. The availability of sample $k$ to be the exemplar of sample $i$ is given by:

$$a(i, k) \leftarrow \min\{0, r(k, k) + \sum_{i' \text{ s.t. } i' \notin \{i, k\}} r(i', k)\}$$
To begin with, all values for $r$ and $a$ are set to zero, and the calculation of each iterates until convergence. As discussed above, in order to avoid numerical oscillations when updating the messages, the damping factor $\lambda$ is introduced to iteration process:

$$
    r_{t+1}(i, k) = \lambda \cdot r_t(i, k) + (1 - \lambda) \cdot r_{t+1}(i, k)
$$

$$
    a_{t+1}(i, k) = \lambda \cdot a_t(i, k) + (1 - \lambda) \cdot a_{t+1}(i, k)
$$

where $t$ indicates the iteration times.

**Mean Shift**

MeanShift clustering aims to discover *blobs* in a smooth density of samples. It is a centroid based algorithm, which works by updating candidates for centroids to be the mean of the points within a given region. These candidates are then filtered in a post-processing stage to eliminate near-duplicates to form the final set of centroids.

Given a candidate centroid $x_i$ for iteration $t$, the candidate is updated according to the following equation:

$$
    x_{t+1}^i = m(x_t^i)
$$

Where $N(x_i)$ is the neighborhood of samples within a given distance around $x_i$ and $m$ is the *mean shift* vector that is computed for each centroid that points towards a region of the maximum increase in the density of points. This is computed using the following equation, effectively updating a centroid to be the mean of the samples within its neighborhood:

$$
    m(x_i) = \frac{\sum_{x_j \in N(x_i)} K(x_j - x_i)x_j}{\sum_{x_j \in N(x_i)} K(x_j - x_i)}
$$

The algorithm automatically sets the number of clusters, instead of relying on a parameter bandwidth, which dictates the size of the region to search through. This parameter can be set manually, but can be estimated using the provided estimate_bandwidth function, which is called if the bandwidth is not set.

The algorithm is not highly scalable, as it requires multiple nearest neighbor searches during the execution of the algorithm. The algorithm is guaranteed to converge, however the algorithm will stop iterating when the change in centroids is small.

Labelling a new sample is performed by finding the nearest centroid for a given sample.
Spectral clustering

*SpectralClustering* performs a low-dimension embedding of the affinity matrix between samples, followed by clustering, e.g., by KMeans, of the components of the eigenvectors in the low dimensional space. It is especially computationally efficient if the affinity matrix is sparse and the *amg* solver is used for the eigenvalue problem (Note, the *amg* solver requires that the *pyamg* module is installed.)

The present version of SpectralClustering requires the number of clusters to be specified in advance. It works well for a small number of clusters, but is not advised for many clusters.

For two clusters, SpectralClustering solves a convex relaxation of the normalised cuts problem on the similarity graph: cutting the graph in two so that the weight of the edges cut is small compared to the weights of the edges inside each cluster. This criteria is especially interesting when working on images, where graph vertices are pixels, and weights of the edges of the similarity graph are computed using a function of a gradient of the image.

**Warning:** Transforming distance to well-behaved similarities

Note that if the values of your similarity matrix are not well distributed, e.g. with negative values or with a distance matrix rather than a similarity, the spectral problem will be singular and the problem not solvable. In which case it is advised to apply a transformation to the entries of the matrix. For instance, in the case of a signed distance matrix, is common to apply a heat kernel:

\[
\text{similarity} = \exp(-\beta \times \text{distance} / \text{distance.std()})
\]

See the examples for such an application.
Examples:

- **Spectral clustering for image segmentation**: Segmenting objects from a noisy background using spectral clustering.
- **Segmenting the picture of greek coins in regions**: Spectral clustering to split the image of coins in regions.

Different label assignment strategies

Different label assignment strategies can be used, corresponding to the `assign_labels` parameter of `SpectralClustering`. The "kmeans" strategy can match finer details, but can be unstable. In particular, unless you control the `random_state`, it may not be reproducible from run-to-run, as it depends on random initialization. The alternative "discretize" strategy is 100% reproducible, but tends to create parcels of fairly even and geometrical shape.

<table>
<thead>
<tr>
<th>assign_labels=&quot;kmeans&quot;</th>
<th>assign_labels=&quot;discretize&quot;</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spectral clustering: kmeans, 1.99s</td>
<td>Spectral clustering: discretize, 1.84s</td>
</tr>
</tbody>
</table>

Spectral Clustering Graphs

Spectral Clustering can also be used to partition graphs via their spectral embeddings. In this case, the affinity matrix is the adjacency matrix of the graph, and SpectralClustering is initialized with `affinity='precomputed'`:

```python
>>> from sklearn.cluster import SpectralClustering
>>> sc = SpectralClustering(n_clusters=3, affinity='precomputed', n_init=100, ...
                               assign_labels='discretize')
>>> sc.fit_predict(adjacency_matrix)
```

References:

Hierarchical clustering

Hierarchical clustering is a general family of clustering algorithms that build nested clusters by merging or splitting them successively. This hierarchy of clusters is represented as a tree (or dendrogram). The root of the tree is the unique cluster that gathers all the samples, the leaves being the clusters with only one sample. See the Wikipedia page for more details.

The `AgglomerativeClustering` object performs a hierarchical clustering using a bottom up approach: each observation starts in its own cluster, and clusters are successively merged together. The linkage criteria determines the metric used for the merge strategy:

- **Ward** minimizes the sum of squared differences within all clusters. It is a variance-minimizing approach and in this sense is similar to the k-means objective function but tackled with an agglomerative hierarchical approach.
- **Maximum** or **complete linkage** minimizes the maximum distance between observations of pairs of clusters.
- **Average linkage** minimizes the average of the distances between all observations of pairs of clusters.
- **Single linkage** minimizes the distance between the closest observations of pairs of clusters.

`AgglomerativeClustering` can also scale to large number of samples when it is used jointly with a connectivity matrix, but is computationally expensive when no connectivity constraints are added between samples: it considers at each step all the possible merges.

### FeatureAgglomeration

The `FeatureAgglomeration` uses agglomerative clustering to group together features that look very similar, thus decreasing the number of features. It is a dimensionality reduction tool, see [Unsupervised dimensionality reduction](#).

---

**References**

- “Normalized cuts and image segmentation” Jianbo Shi, Jitendra Malik, 2000
- “On Spectral Clustering: Analysis and an algorithm” Andrew Y. Ng, Michael I. Jordan, Yair Weiss, 2001
- “Preconditioned Spectral Clustering for Stochastic Block Partition Streaming Graph Challenge” David Zhuzhunashvili, Andrew Knyazev
**Different linkage type: Ward, complete, average, and single linkage**

`AgglomerativeClustering` supports Ward, single, average, and complete linkage strategies.

Agglomerative cluster has a “rich get richer” behavior that leads to uneven cluster sizes. In this regard, single linkage is the worst strategy, and Ward gives the most regular sizes. However, the affinity (or distance used in clustering) cannot be varied with Ward, thus for non-Euclidean metrics, average linkage is a good alternative. Single linkage, while not robust to noisy data, can be computed very efficiently and can therefore be useful to provide hierarchical clustering of larger datasets. Single linkage can also perform well on non-globular data.

**Examples:**

- Various Agglomerative Clustering on a 2D embedding of digits: exploration of the different linkage strategies in a real dataset.
Visualization of cluster hierarchy

It’s possible to visualize the tree representing the hierarchical merging of clusters as a dendrogram. Visual inspection can often be useful for understanding the structure of the data, though more so in the case of small sample sizes.

Adding connectivity constraints

An interesting aspect of AgglomerativeClustering is that connectivity constraints can be added to this algorithm (only adjacent clusters can be merged together), through a connectivity matrix that defines for each sample the neighboring samples following a given structure of the data. For instance, in the swiss-roll example below, the connectivity constraints forbid the merging of points that are not adjacent on the swiss roll, and thus avoid forming clusters that extend across overlapping folds of the roll.

These constraint are useful to impose a certain local structure, but they also make the algorithm faster, especially when the number of the samples is high.

The connectivity constraints are imposed via an connectivity matrix: a scipy sparse matrix that has elements only at the intersection of a row and a column with indices of the dataset that should be connected. This matrix can be constructed from a-priori information: for instance, you may wish to cluster web pages by only merging pages with a link pointing from one to another. It can also be learned from the data, for instance using sklearn.neighbors.kneighbors_graph to restrict merging to nearest neighbors as in this example, or using sklearn.feature_extraction.image.grid_to_graph to enable only merging of neighboring pixels on an image, as in the coin example.
Examples:

- **A demo of structured Ward hierarchical clustering on an image of coins**: Ward clustering to split the image of coins in regions.
- **Hierarchical clustering: structured vs unstructured ward**: Example of Ward algorithm on a swiss-roll, comparison of structured approaches versus unstructured approaches.
- **Feature agglomeration vs. univariate selection**: Example of dimensionality reduction with feature agglomeration based on Ward hierarchical clustering.
- **Agglomerative clustering with and without structure**

**Warning:** Connectivity constraints with single, average and complete linkage

Connectivity constraints and single, complete or average linkage can enhance the ‘rich getting richer’ aspect of agglomerative clustering, particularly so if they are built with `sklearn.neighbors.kneighbors_graph`. In the limit of a small number of clusters, they tend to give a few macroscopically occupied clusters and almost empty ones. (see the discussion in Agglomerative clustering with and without structure). Single linkage is the most brittle linkage option with regard to this issue.
Varying the metric

Single, average and complete linkage can be used with a variety of distances (or affinities), in particular Euclidean distance (\(l_2\)), Manhattan distance (or Cityblock, or \(l_1\)), cosine distance, or any precomputed affinity matrix.

- \(l_1\) distance is often good for sparse features, or sparse noise: i.e. many of the features are zero, as in text mining using occurrences of rare words.
- \textit{cosine} distance is interesting because it is invariant to global scalings of the signal.

The guidelines for choosing a metric is to use one that maximizes the distance between samples in different classes, and minimizes that within each class.
DBSCAN

The DBSCAN algorithm views clusters as areas of high density separated by areas of low density. Due to this rather generic view, clusters found by DBSCAN can be any shape, as opposed to k-means which assumes that clusters are convex shaped. The central component to the DBSCAN is the concept of core samples, which are samples that are in areas of high density. A cluster is therefore a set of core samples, each close to each other (measured by some distance measure) and a set of non-core samples that are close to a core sample (but are not themselves core samples). There are two parameters to the algorithm, min_samples and eps, which define formally what we mean when we say dense. Higher min_samples or lower eps indicate higher density necessary to form a cluster.

More formally, we define a core sample as being a sample in the dataset such that there exist min_samples other samples within a distance of eps, which are defined as neighbors of the core sample. This tells us that the core sample is in a dense area of the vector space. A cluster is a set of core samples that can be built by recursively taking a core sample, finding all of its neighbors that are core samples, finding all of their neighbors that are core samples, and so on. A cluster also has a set of non-core samples, which are samples that are neighbors of a core sample in the cluster but are not themselves core samples. Intuitively, these samples are on the fringes of a cluster.

Any core sample is part of a cluster, by definition. Any sample that is not a core sample, and is at least eps in distance from any core sample, is considered an outlier by the algorithm.

While the parameter min_samples primarily controls how tolerant the algorithm is towards noise (on noisy and large data sets it may be desirable to increase this parameter), the parameter eps is crucial to choose appropriately for the data set and distance function and usually cannot be left at the default value. It controls the local neighborhood of the points. When chosen too small, most data will not be clustered at all (and labeled as -1 for “noise”). When chosen too large, it causes close clusters to be merged into one cluster, and eventually the entire data set to be returned as a single cluster. Some heuristics for choosing this parameter have been discussed in the literature, for example based on a knee in the nearest neighbor distances plot (as discussed in the references below).

In the figure below, the color indicates cluster membership, with large circles indicating core samples found by the algorithm. Smaller circles are non-core samples that are still part of a cluster. Moreover, the outliers are indicated by black points below.
Examples:

- Demo of DBSCAN clustering algorithm

Implementation

The DBSCAN algorithm is deterministic, always generating the same clusters when given the same data in the same order. However, the results can differ when data is provided in a different order. First, even though the core samples will always be assigned to the same clusters, the labels of those clusters will depend on the order in which those samples are encountered in the data. Second and more importantly, the clusters to which non-core samples are assigned can differ depending on the data order. This would happen when a non-core sample has a distance lower than $\text{eps}$ to two core samples in different clusters. By the triangular inequality, those two core samples must be more distant than $\text{eps}$ from each other, or they would be in the same cluster. The non-core sample is assigned to whichever cluster is generated first in a pass through the data, and so the results will depend on the data ordering.

The current implementation uses ball trees and kd-trees to determine the neighborhood of points, which avoids calculating the full distance matrix (as was done in scikit-learn versions before 0.14). The possibility to use custom metrics is retained; for details, see NearestNeighbors.

Memory consumption for large sample sizes

This implementation is by default not memory efficient because it constructs a full pairwise similarity matrix in the case where kd-trees or ball-trees cannot be used (e.g., with sparse matrices). This matrix will consume $n^2$ floats. A couple of mechanisms for getting around this are:

- Use OPTICS clustering in conjunction with the extract_dbscan method. OPTICS clustering also calculates the full pairwise matrix, but only keeps one row in memory at a time (memory complexity $n$).

- A sparse radius neighborhood graph (where missing entries are presumed to be out of $\text{eps}$) can be precomputed in a memory-efficient way and dbscan can be run over this with metric='precomputed'. See sklearn.neighbors.NearestNeighbors.radius_neighbors_graph.

- The dataset can be compressed, either by removing exact duplicates if these occur in your data, or by using BIRCH. Then you only have a relatively small number of representatives for a large number of points. You can then provide a sample_weight when fitting DBSCAN.

References:


### OPTICS

The OPTICS algorithm shares many similarities with the DBSCAN algorithm, and can be considered a generalization of DBSCAN that relaxes the eps requirement from a single value to a value range. The key difference between DBSCAN and OPTICS is that the OPTICS algorithm builds a reachability graph, which assigns each sample both a reachability distance, and a spot within the cluster ordering attribute; these two attributes are assigned when the model is fitted, and are used to determine cluster membership. If OPTICS is run with the default value of $inf$ set for max_eps, then DBSCAN style cluster extraction can be performed repeatedly in linear time for any given eps value using the cluster_optics_dbscan method. Setting max_eps to a lower value will result in shorter run times, and can be thought of as the maximum neighborhood radius from each point to find other potential reachable points.

The reachability distances generated by OPTICS allow for variable density extraction of clusters within a single data set. As shown in the above plot, combining reachability distances and data set ordering produces a reachability plot, where point density is represented on the Y-axis, and points are ordered such that nearby points are adjacent. Cutting the reachability plot at a single value produces DBSCAN like results; all points above the ‘cut’ are classified as noise, and each time that there is a break when reading from left to right signifies a new cluster. The default cluster extraction with OPTICS looks at the steep slopes within the graph to find clusters, and the user can define what counts as a steep slope using the parameter $xi$. There are also other possibilities for analysis on the graph itself, such as generating hierarchical representations of the data through reachability-plot dendrograms, and the hierarchy of clusters detected by the algorithm can be accessed through the cluster_hierarchy parameter. The plot above has been color-coded so that cluster colors in planar space match the linear segment clusters of the reachability plot. Note that the blue and red clusters are adjacent in the reachability plot, and can be hierarchically represented as children of a larger parent cluster.

**Examples:**

- Demo of OPTICS clustering algorithm
Comparison with DBSCAN

The results from OPTICS `cluster_optics_dbscan` method and DBSCAN are very similar, but not always identical; specifically, labeling of periphery and noise points. This is in part because the first samples of each dense area processed by OPTICS have a large reachability value while being close to other points in their area, and will thus sometimes be marked as noise rather than periphery. This affects adjacent points when they are considered as candidates for being marked as either periphery or noise.

Note that for any single value of $\text{eps}$, DBSCAN will tend to have a shorter run time than OPTICS; however, for repeated runs at varying $\text{eps}$ values, a single run of OPTICS may require less cumulative runtime than DBSCAN. It is also important to note that OPTICS’ output is close to DBSCAN’s only if $\text{eps}$ and $\text{max}_\text{eps}$ are close.

Computational Complexity

Spatial indexing trees are used to avoid calculating the full distance matrix, and allow for efficient memory usage on large sets of samples. Different distance metrics can be supplied via the `metric` keyword.

For large datasets, similar (but not identical) results can be obtained via HDBSCAN. The HDBSCAN implementation is multithreaded, and has better algorithmic runtime complexity than OPTICS, at the cost of worse memory scaling. For extremely large datasets that exhaust system memory using HDBSCAN, OPTICS will maintain $n$ (as opposed to $n^2$) memory scaling; however, tuning of the `max_eps` parameter will likely need to be used to give a solution in a reasonable amount of wall time.

References:


Birch

The Birch builds a tree called the Clustering Feature Tree (CFT) for the given data. The data is essentially lossy compressed to a set of Clustering Feature nodes (CF Nodes). The CF Nodes have a number of subclusters called Clustering Feature subclusters (CF Subclusters) and these CF Subclusters located in the non-terminal CF Nodes can have CF Nodes as children.

The CF Subclusters hold the necessary information for clustering which prevents the need to hold the entire input data in memory. This information includes:

- Number of samples in a subcluster.
- Linear Sum - An n-dimensional vector holding the sum of all samples
- Squared Sum - Sum of the squared L2 norm of all samples.
- Centroids - To avoid recalculation linear sum / n_samples.
- Squared norm of the centroids.

The Birch algorithm has two parameters, the threshold and the branching factor. The branching factor limits the number of subclusters in a node and the threshold limits the distance between the entering sample and the existing subclusters.

This algorithm can be viewed as an instance or data reduction method, since it reduces the input data to a set of subclusters which are obtained directly from the leaves of the CFT. This reduced data can be further processed by
feeding it into a global clusterer. This global clusterer can be set by `n_clusters`. If `n_clusters` is set to `None`, the subclusters from the leaves are directly read off, otherwise a global clustering step labels these subclusters into global clusters (labels) and the samples are mapped to the global label of the nearest subcluster.

**Algorithm description:**

- A new sample is inserted into the root of the CF Tree which is a CF Node. It is then merged with the subcluster of the root, that has the smallest radius after merging, constrained by the threshold and branching factor conditions. If the subcluster has any child node, then this is done repeatedly till it reaches a leaf. After finding the nearest subcluster in the leaf, the properties of this subcluster and the parent subclusters are recursively updated.

- If the radius of the subcluster obtained by merging the new sample and the nearest subcluster is greater than the square of the threshold and if the number of subclusters is greater than the branching factor, then a space is temporarily allocated to this new sample. The two farthest subclusters are taken and the subclusters are divided into two groups on the basis of the distance between these subclusters.

- If this split node has a parent subcluster and there is room for a new subcluster, then the parent is split into two. If there is no room, then this node is again split into two and the process is continued recursively, till it reaches the root.

**Birch or MiniBatchKMeans?**

- Birch does not scale very well to high dimensional data. As a rule of thumb if `n_features` is greater than twenty, it is generally better to use MiniBatchKMeans.

- If the number of instances of data needs to be reduced, or if one wants a large number of subclusters either as a preprocessing step or otherwise, Birch is more useful than MiniBatchKMeans.

**How to use partial_fit?**

To avoid the computation of global clustering, for every call of `partial_fit` the user is advised

1. To set `n_clusters=None` initially
2. Train all data by multiple calls to `partial_fit`.
3. Set `n_clusters` to a required value using `brc.set_params(n_clusters=n_clusters)`.
4. Call `partial_fit` finally with no arguments, i.e. `brc.partial_fit()` which performs the global clustering.

**References:**

Clustering performance evaluation

Evaluating the performance of a clustering algorithm is not as trivial as counting the number of errors or the precision and recall of a supervised classification algorithm. In particular any evaluation metric should not take the absolute values of the cluster labels into account but rather if this clustering define separations of the data similar to some ground truth set of classes or satisfying some assumption such that members belong to the same class are more similar than members of different classes according to some similarity metric.

Rand index

Given the knowledge of the ground truth class assignments \texttt{labels_true} and our clustering algorithm assignments of the same samples \texttt{labels_pred}, the (adjusted or unadjusted) Rand index is a function that measures the similarity of the two assignments, ignoring permutations:

\begin{verbatim}
>>> from sklearn import metrics

>>> labels_true = [0, 0, 0, 1, 1, 1]
>>> labels_pred = [0, 0, 1, 1, 2, 2]

metrics.rand_score(labels_true, labels_pred)
0.66...

metrics.adjusted_rand_score(labels_true, labels_pred)
0.24...
\end{verbatim}

The Rand index does not ensure to obtain a value close to 0.0 for a random labelling. The adjusted Rand index corrects for chance and will give such a baseline:

\begin{verbatim}
>>> metrics.adjusted_rand_score(labels_true, labels_pred)
0.24...
\end{verbatim}

As with all clustering metrics, one can permute 0 and 1 in the predicted labels, rename 2 to 3, and get the same score:

\begin{verbatim}
>>> labels_pred = [1, 1, 0, 0, 3, 3]

metrics.rand_score(labels_true, labels_pred)
0.66...

metrics.adjusted_rand_score(labels_true, labels_pred)
0.24...
\end{verbatim}

Furthermore, both rand_score adjusted_rand_score are symmetric: swapping the argument does not change the scores. They can thus be used as consensus measures:

\begin{verbatim}
>>> metrics.rand_score(labels_pred, labels_true)
0.66...

>>> metrics.adjusted_rand_score(labels_pred, labels_true)
0.24...
\end{verbatim}

Perfect labeling is scored 1.0:

\begin{verbatim}
>>> labels_pred = labels_true[:]

>>> metrics.rand_score(labels_true, labels_pred)
1.0

>>> metrics.adjusted_rand_score(labels_true, labels_pred)
1.0
\end{verbatim}
Poorly agreeing labels (e.g. independent labelings) have lower scores, and for the adjusted Rand index the score will be negative or close to zero. However, for the unadjusted Rand index the score, while lower, will not necessarily be close to zero:

```python
>>> labels_true = [0, 0, 0, 0, 0, 1, 1]
>>> labels_pred = [0, 1, 2, 3, 4, 5, 6]
>>> metrics.rand_score(labels_true, labels_pred)
0.39...
>>> metrics.adjusted_rand_score(labels_true, labels_pred)
-0.07...
```

### Advantages

- **Interpretability**: The unadjusted Rand index is proportional to the number of sample pairs whose labels are the same in both `labels_pred` and `labels_true`, or are different in both.

- **Random (uniform) label assignments have an adjusted Rand index score close to 0.0** for any value of `n_clusters` and `n_samples` (which is not the case for the unadjusted Rand index or the V-measure for instance).

- **Bounded range**: Lower values indicate different labelings, similar clusterings have a high (adjusted or unadjusted) Rand index, 1.0 is the perfect match score. The score range is [0, 1] for the unadjusted Rand index and [-1, 1] for the adjusted Rand index.

- **No assumption is made on the cluster structure**: The (adjusted or unadjusted) Rand index can be used to compare all kinds of clustering algorithms, and can be used to compare clustering algorithms such as k-means which assumes isotropic blob shapes with results of spectral clustering algorithms which can find cluster with “folded” shapes.

### Drawbacks

- Contrary to inertia, the (adjusted or unadjusted) Rand index requires knowledge of the ground truth classes which is almost never available in practice or requires manual assignment by human annotators (as in the supervised learning setting).

  However (adjusted or unadjusted) Rand index can also be useful in a purely unsupervised setting as a building block for a Consensus Index that can be used for clustering model selection (TODO).

- The unadjusted Rand index is often close to 1.0 even if the clusterings themselves differ significantly. This can be understood when interpreting the Rand index as the accuracy of element pair labeling resulting from the clusterings: In practice there often is a majority of element pairs that are assigned the different pair label under both the predicted and the ground truth clustering resulting in a high proportion of pair labels that agree, which leads subsequently to a high score.

### Examples:

- **Adjustment for chance in clustering performance evaluation**: Analysis of the impact of the dataset size on the value of clustering measures for random assignments.
Mathematical formulation

If C is a ground truth class assignment and K the clustering, let us define \( a \) and \( b \) as:

- \( a \), the number of pairs of elements that are in the same set in C and in the same set in K
- \( b \), the number of pairs of elements that are in different sets in C and in different sets in K

The unadjusted Rand index is then given by:

\[
RI = \frac{a + b}{\binom{C \text{ samples}}{2}}
\]

where \( \binom{C \text{ samples}}{2} \) is the total number of possible pairs in the dataset. It does not matter if the calculation is performed on ordered pairs or unordered pairs as long as the calculation is performed consistently.

However, the Rand index does not guarantee that random label assignments will get a value close to zero (esp. if the number of clusters is in the same order of magnitude as the number of samples).

To counter this effect we can discount the expected RI \( E[RI] \) of random labelings by defining the adjusted Rand index as follows:

\[
ARI = \frac{RI - E[RI]}{\max(RI) - E[RI]}
\]

References

- Comparing Partitions L. Hubert and P. Arabie, Journal of Classification 1985
- Properties of the Hubert-Arabie adjusted Rand index D. Steinley, Psychological Methods 2004
- Wikipedia entry for the Rand index
- Wikipedia entry for the adjusted Rand index

Mutual Information based scores

Given the knowledge of the ground truth class assignments \( \text{labels_true} \) and our clustering algorithm assignments of the same samples \( \text{labels_pred} \), the Mutual Information is a function that measures the agreement of the two assignments, ignoring permutations. Two different normalized versions of this measure are available, Normalized Mutual Information (NMI) and Adjusted Mutual Information (AMI). NMI is often used in the literature, while AMI was proposed more recently and is normalized against chance:

```python
>>> from sklearn import metrics
>>> labels_true = [0, 0, 0, 1, 1, 1]
>>> labels_pred = [0, 0, 1, 1, 2, 2]

>>> metrics.adjusted_mutual_info_score(labels_true, labels_pred)
0.22504...
```

One can permute 0 and 1 in the predicted labels, rename 2 to 3 and get the same score:

```python
>>> labels_pred = [1, 1, 0, 0, 3, 3]
>>> metrics.adjusted_mutual_info_score(labels_true, labels_pred)
0.22504...
```

All, \text{mutual_info_score}, \text{adjusted_mutual_info_score} and \text{normalized_mutual_info_score} are symmetric: swapping the argument does not change the score. Thus they can be used as a consensus measure:
Perfect labeling is scored 1.0:

```python
>>> labels_pred = labels_true[:]
>>> metrics.adjusted_mutual_info_score(labels_true, labels_pred)
1.0
>>> metrics.normalized_mutual_info_score(labels_true, labels_pred)
1.0
```

This is not true for `mutual_info_score`, which is therefore harder to judge:

```python
>>> metrics.mutual_info_score(labels_true, labels_pred)
0.69...
```

Bad (e.g. independent labelings) have non-positive scores:

```python
>>> labels_true = [0, 1, 2, 0, 3, 4, 5, 1]
>>> labels_pred = [1, 1, 0, 0, 2, 2, 2, 2]
>>> metrics.adjusted_mutual_info_score(labels_true, labels_pred)
-0.10526...
```

**Advantages**

- **Random (uniform) label assignments have a AMI score close to 0.0** for any value of `n_clusters` and `n_samples` (which is not the case for raw Mutual Information or the V-measure for instance).

- **Upper bound of 1**: Values close to zero indicate two label assignments that are largely independent, while values close to one indicate significant agreement. Further, an AMI of exactly 1 indicates that the two label assignments are equal (with or without permutation).

**Drawbacks**

- Contrary to inertia, **MI-based measures require the knowledge of the ground truth classes** while almost never available in practice or requires manual assignment by human annotators (as in the supervised learning setting).

  However MI-based measures can also be useful in purely unsupervised setting as a building block for a Consensus Index that can be used for clustering model selection.

- NMI and MI are not adjusted against chance.

**Examples:**

- *Adjustment for chance in clustering performance evaluation*: Analysis of the impact of the dataset size on the value of clustering measures for random assignments. This example also includes the Adjusted Rand Index.
Mathematical formulation

Assume two label assignments (of the same $N$ objects), $U$ and $V$. Their entropy is the amount of uncertainty for a partition set, defined by:

$$H(U) = - \sum_{i=1}^{|U|} P(i) \log(P(i))$$

where $P(i) = |U_i|/N$ is the probability that an object picked at random from $U$ falls into class $U_i$. Likewise for $V$:

$$H(V) = - \sum_{j=1}^{|V|} P'(j) \log(P'(j))$$

With $P'(j) = |V_j|/N$. The mutual information (MI) between $U$ and $V$ is calculated by:

$$\text{MI}(U, V) = \sum_{i=1}^{|U|} \sum_{j=1}^{|V|} P(i, j) \log \left( \frac{P(i, j)}{P(i)P'(j)} \right)$$

where $P(i, j) = |U_i \cap V_j|/N$ is the probability that an object picked at random falls into both classes $U_i$ and $V_j$.

It also can be expressed in set cardinality formulation:

$$\text{MI}(U, V) = \sum_{i=1}^{|U|} \sum_{j=1}^{|V|} \frac{|U_i \cap V_j|}{N} \log \left( \frac{N|U_i \cap V_j|}{|U_i||V_j|} \right)$$

The normalized mutual information is defined as

$$\text{NMI}(U, V) = \frac{\text{MI}(U, V)}{\text{mean}(H(U), H(V))}$$

This value of the mutual information and also the normalized variant is not adjusted for chance and will tend to increase as the number of different labels (clusters) increases, regardless of the actual amount of "mutual information" between the label assignments.

The expected value for the mutual information can be calculated using the following equation [VEB2009]. In this equation, $a_i = |U_i|$ (the number of elements in $U_i$) and $b_j = |V_j|$ (the number of elements in $V_j$):

$$E[\text{MI}(U, V)] = \sum_{i=1}^{|U|} \sum_{j=1}^{|V|} \min(a_i, b_j) \sum_{n_{ij}=(a_i+b_j-N)+}^{n_{ij}} \frac{n_{ij}}{N} \log \left( \frac{N.n_{ij}}{a_i.b_j} \right) \frac{a_i!b_j!(N-a_i)!!(N-b_j)!}{a_i-n_{ij}!(b_j-n_{ij})!(N-a_i-b_j+n_{ij})!}$$

Using the expected value, the adjusted mutual information can then be calculated using a similar form to that of the adjusted Rand index:

$$\text{AMI} = \frac{\text{MI} - E[\text{MI}]}{\text{mean}(H(U), H(V)) - E[\text{MI}]}$$

For normalized mutual information and adjusted mutual information, the normalizing value is typically some generalized mean of the entropies of each clustering. Various generalized means exist, and no firm rules exist for preferring one over the others. The decision is largely a field-by-field basis; for instance, in community detection, the arithmetic mean is most common. Each normalizing method provides “qualitatively similar behaviours” [YAT2016]. In our implementation, this is controlled by the average_method parameter.

Vinh et al. (2010) named variants of NMI and AMI by their averaging method [VEB2010]. Their ‘sqrt’ and ‘sum’ averages are the geometric and arithmetic means; we use these more broadly common names.
Homogeneity, completeness and V-measure

Given the knowledge of the ground truth class assignments of the samples, it is possible to define some intuitive metric using conditional entropy analysis.

In particular Rosenberg and Hirschberg (2007) define the following two desirable objectives for any cluster assignment:

- **homogeneity**: each cluster contains only members of a single class.
- **completeness**: all members of a given class are assigned to the same cluster.

We can turn those concept as scores `homogeneity_score` and `completeness_score`. Both are bounded below by 0.0 and above by 1.0 (higher is better):

```python
>>> from sklearn import metrics

>>> labels_true = [0, 0, 0, 1, 1, 1]
>>> labels_pred = [0, 0, 1, 1, 2, 2]

>>> metrics.homogeneity_score(labels_true, labels_pred)
0.66...

>>> metrics.completeness_score(labels_true, labels_pred)
0.42...
```

Their harmonic mean called **V-measure** is computed by `v_measure_score`:

```python
>>> metrics.v_measure_score(labels_true, labels_pred)
0.51...
```

This function’s formula is as follows:

\[
V = \frac{(1 + \beta) \times \text{homogeneity} \times \text{completeness}}{\beta \times \text{homogeneity} + \text{completeness}}
\]

`beta` defaults to a value of 1.0, but for using a value less than 1 for beta:

```python
>>> metrics.v_measure_score(labels_true, labels_pred, beta=0.6)
0.54...
```

more weight will be attributed to homogeneity, and using a value greater than 1:

```python
>>> metrics.v_measure_score(labels_true, labels_pred, beta=1.8)
0.48...
```

more weight will be attributed to completeness.

The V-measure is actually equivalent to the mutual information (NMI) discussed above, with the aggregation function being the arithmetic mean [B2011].
Homogeneity, completeness and V-measure can be computed at once using `homogeneity_completeness_v_measure` as follows:

```python
>>> metrics.homogeneity_completeness_v_measure(labels_true, labels_pred)
(0.66..., 0.42..., 0.51...)
```

The following clustering assignment is slightly better, since it is homogeneous but not complete:

```python
>>> labels_pred = [0, 0, 0, 1, 2, 2]
>>> metrics.homogeneity_completeness_v_measure(labels_true, labels_pred)
(1.0, 0.68..., 0.81...)
```

**Note:** `v_measure_score` is symmetric: it can be used to evaluate the agreement of two independent assignments on the same dataset.

This is not the case for `completeness_score` and `homogeneity_score`: both are bound by the relationship:

```python
homogeneity_score(a, b) == completeness_score(b, a)
```

**Advantages**

- **Bounded scores:** 0.0 is as bad as it can be, 1.0 is a perfect score.
- Intuitive interpretation: clustering with bad V-measure can be qualitatively analyzed in terms of homogeneity and completeness to better feel what ‘kind’ of mistakes is done by the assignment.
- **No assumption is made on the cluster structure:** can be used to compare clustering algorithms such as k-means which assumes isotropic blob shapes with results of spectral clustering algorithms which can find cluster with “folded” shapes.

**Drawbacks**

- The previously introduced metrics are not normalized with regards to random labeling: this means that depending on the number of samples, clusters and ground truth classes, a completely random labeling will not always yield the same values for homogeneity, completeness and hence v-measure. In particular random labeling won’t yield zero scores especially when the number of clusters is large.

This problem can safely be ignored when the number of samples is more than a thousand and the number of clusters is less than 10. **For smaller sample sizes or larger number of clusters it is safer to use an adjusted index such as the Adjusted Rand Index (ARI).**

- These metrics require the knowledge of the ground truth classes while almost never available in practice or requires manual assignment by human annotators (as in the supervised learning setting).

**Examples:**

- **Adjustment for chance in clustering performance evaluation:** Analysis of the impact of the dataset size on the value of clustering measures for random assignments.
Clustering measures for 2 random uniform labelings with equal number of clusters
Mathematical formulation

Homogeneity and completeness scores are formally given by:

\[
  h = 1 - \frac{H(C|K)}{H(C)}
\]

\[
  c = 1 - \frac{H(K|C)}{H(K)}
\]

where \( H(C|K) \) is the **conditional entropy of the classes given the cluster assignments** and is given by:

\[
  H(C|K) = - \sum_{c=1}^{[C]} \sum_{k=1}^{[K]} \frac{n_{c,k}}{n} \log \left( \frac{n_{c,k}}{n_k} \right)
\]

and \( H(C) \) is the **entropy of the classes** and is given by:

\[
  H(C) = - \sum_{c=1}^{[C]} \frac{n_c}{n} \log \left( \frac{n_c}{n} \right)
\]

with \( n \) the total number of samples, \( n_c \) and \( n_k \) the number of samples respectively belonging to class \( c \) and cluster \( k \), and finally \( n_{c,k} \) the number of samples from class \( c \) assigned to cluster \( k \).

The **conditional entropy of clusters given class** \( H(K|C) \) and the **entropy of clusters** \( H(K) \) are defined in a symmetric manner.

Rosenberg and Hirschberg further define **V-measure** as the harmonic mean of homogeneity and completeness:

\[
  v = 2 \cdot \frac{h \cdot c}{h + c}
\]

**References**

* V-Measure: A conditional entropy-based external cluster evaluation measure  Andrew Rosenberg and Julia Hirschberg, 2007

**Fowlkes-Mallows scores**

The Fowlkes-Mallows index (**sklearn.metrics.fowlkes_mallows_score**) can be used when the ground truth class assignments of the samples is known. The Fowlkes-Mallows score FMI is defined as the geometric mean of the pairwise precision and recall:

\[
  \text{FMI} = \frac{\text{TP}}{\sqrt{\text{TP} + \text{FP}} \sqrt{\text{TP} + \text{FN}}}
\]

Where \( \text{TP} \) is the number of **True Positive** (i.e. the number of pair of points that belong to the same clusters in both the true labels and the predicted labels), \( \text{FP} \) is the number of **False Positive** (i.e. the number of pair of points that belong to the same clusters in the true labels and not in the predicted labels) and \( \text{FN} \) is the number of **False Negative** (i.e the number of pair of points that belongs in the same clusters in the predicted labels and not in the true labels).

The score ranges from 0 to 1. A high value indicates a good similarity between two clusters.

```python
>>> from sklearn import metrics
>>> labels_true = [0, 0, 0, 1, 1, 1]
>>> labels_pred = [0, 0, 1, 1, 2, 2]
```
One can permute 0 and 1 in the predicted labels, rename 2 to 3 and get the same score:

```python
>>> labels_pred = [1, 1, 0, 0, 3, 3]
>>> metrics.fowlkes_mallows_score(labels_true, labels_pred)
0.47140...
```

Perfect labeling is scored 1.0:

```python
>>> labels_pred = labels_true[:]
>>> metrics.fowlkes_mallows_score(labels_true, labels_pred)
1.0
```

Bad (e.g. independent labelings) have zero scores:

```python
>>> labels_true = [0, 1, 2, 0, 3, 4, 5, 1]
>>> labels_pred = [1, 1, 0, 0, 2, 2, 2, 2]
>>> metrics.fowlkes_mallows_score(labels_true, labels_pred)
0.0
```

**Advantages**

- **Random (uniform) label assignments have a FMI score close to 0.0** for any value of `n_clusters` and `n_samples` (which is not the case for raw Mutual Information or the V-measure for instance).

- **Upper-bounded at 1**: Values close to zero indicate two label assignments that are largely independent, while values close to one indicate significant agreement. Further, values of exactly 0 indicate purely independent label assignments and a FMI of exactly 1 indicates that the two label assignments are equal (with or without permutation).

- **No assumption is made on the cluster structure**: can be used to compare clustering algorithms such as k-means which assumes isotropic blob shapes with results of spectral clustering algorithms which can find cluster with “folded” shapes.

**Drawbacks**

- Contrary to inertia, **FMI-based measures require the knowledge of the ground truth classes** while almost never available in practice or requires manual assignment by human annotators (as in the supervised learning setting).

**References**


- Wikipedia entry for the Fowlkes-Mallows Index
Silhouette Coefficient

If the ground truth labels are not known, evaluation must be performed using the model itself. The Silhouette Coefficient (sklearn.metrics.silhouette_score) is an example of such an evaluation, where a higher Silhouette Coefficient score relates to a model with better defined clusters. The Silhouette Coefficient is defined for each sample and is composed of two scores:

- $a$: The mean distance between a sample and all other points in the same class.
- $b$: The mean distance between a sample and all other points in the next nearest cluster.

The Silhouette Coefficient $s$ for a single sample is then given as:

$$ s = \frac{b - a}{\max(a, b)} $$

The Silhouette Coefficient for a set of samples is given as the mean of the Silhouette Coefficient for each sample.

```python
>>> from sklearn import metrics
>>> from sklearn.metrics import pairwise_distances
>>> from sklearn import datasets

>>> X, y = datasets.load_iris(return_X_y=True)
```

In normal usage, the Silhouette Coefficient is applied to the results of a cluster analysis.

```python
>>> import numpy as np
>>> from sklearn.cluster import KMeans

>>> kmeans_model = KMeans(n_clusters=3, random_state=1).fit(X)
>>> labels = kmeans_model.labels_
>>> metrics.silhouette_score(X, labels, metric='euclidean')
0.55...
```

References


Advantages

- The score is bounded between -1 for incorrect clustering and +1 for highly dense clustering. Scores around zero indicate overlapping clusters.
- The score is higher when clusters are dense and well separated, which relates to a standard concept of a cluster.

Drawbacks

- The Silhouette Coefficient is generally higher for convex clusters than other concepts of clusters, such as density based clusters like those obtained through DBSCAN.

Examples:

- Selecting the number of clusters with silhouette analysis on KMeans clustering: In this example the silhouette analysis is used to choose an optimal value for n_clusters.
Calinski-Harabasz Index

If the ground truth labels are not known, the Calinski-Harabasz index (sklearn.metrics.calinski_harabasz_score) - also known as the Variance Ratio Criterion - can be used to evaluate the model, where a higher Calinski-Harabasz score relates to a model with better defined clusters.

The index is the ratio of the sum of between-clusters dispersion and of inter-cluster dispersion for all clusters (where dispersion is defined as the sum of distances squared):

```python
>>> from sklearn import metrics
>>> from sklearn.metrics import pairwise_distances
>>> from sklearn import datasets

>>> X, y = datasets.load_iris(return_X_y=True)
```

In normal usage, the Calinski-Harabasz index is applied to the results of a cluster analysis:

```python
>>> import numpy as np
>>> from sklearn.cluster import KMeans

>>> kmeans_model = KMeans(n_clusters=3, random_state=1).fit(X)
>>> labels = kmeans_model.labels_
>>> metrics.calinski_harabasz_score(X, labels)
561.62...
```

Advantages

- The score is higher when clusters are dense and well separated, which relates to a standard concept of a cluster.
- The score is fast to compute.

Drawbacks

- The Calinski-Harabasz index is generally higher for convex clusters than other concepts of clusters, such as density based clusters like those obtained through DBSCAN.

Mathematical formulation

For a set of data $E$ of size $n_E$ which has been clustered into $k$ clusters, the Calinski-Harabasz score $s$ is defined as the ratio of the between-clusters dispersion mean and the within-cluster dispersion:

$$s = \frac{\text{tr}(B_k)}{\text{tr}(W_k)} \times \frac{n_E - k}{k - 1}$$

where $\text{tr}(B_k)$ is trace of the between group dispersion matrix and $\text{tr}(W_k)$ is the trace of the within-cluster dispersion matrix defined by:

$$W_k = \sum_{q=1}^{k} \sum_{x \in C_q} (x - c_q)(x - c_q)^T$$

$$B_k = \sum_{q=1}^{k} n_q(c_q - c_E)(c_q - c_E)^T$$

with $C_q$ the set of points in cluster $q$, $c_q$ the center of cluster $q$, $c_E$ the center of $E$, and $n_q$ the number of points in cluster $q$. 
Davies-Bouldin Index

If the ground truth labels are not known, the Davies-Bouldin index (sklearn.metrics.davies_bouldin_score) can be used to evaluate the model, where a lower Davies-Bouldin index relates to a model with better separation between the clusters.

This index signifies the average ‘similarity’ between clusters, where the similarity is a measure that compares the distance between clusters with the size of the clusters themselves.

Zero is the lowest possible score. Values closer to zero indicate a better partition.

In normal usage, the Davies-Bouldin index is applied to the results of a cluster analysis as follows:

```python
>>> from sklearn import datasets
>>> iris = datasets.load_iris()
>>> X = iris.data
>>> from sklearn.cluster import KMeans
>>> from sklearn.metrics import davies_bouldin_score
>>> kmeans = KMeans(n_clusters=3, random_state=1).fit(X)
>>> labels = kmeans.labels_
>>> davies_bouldin_score(X, labels)
0.6619...
```

Advantages

- The computation of Davies-Bouldin is simpler than that of Silhouette scores.
- The index is computed only quantities and features inherent to the dataset.

Drawbacks

- The Davies-Boulding index is generally higher for convex clusters than other concepts of clusters, such as density based clusters like those obtained from DBSCAN.
- The usage of centroid distance limits the distance metric to Euclidean space.

Mathematical formulation

The index is defined as the average similarity between each cluster $C_i$ for $i = 1, ..., k$ and its most similar one $C_j$. In the context of this index, similarity is defined as a measure $R_{ij}$ that trades off:

- $s_{ij}$, the average distance between each point of cluster $i$ and the centroid of that cluster – also known as cluster diameter.
- $d_{ij}$, the distance between cluster centroids $i$ and $j$.  

References

A simple choice to construct $R_{ij}$ so that it is nonnegative and symmetric is:

$$R_{ij} = \frac{s_i + s_j}{d_{ij}}$$

Then the Davies-Bouldin index is defined as:

$$DB = \frac{1}{k} \sum_{i=1}^{k} \max_{i \neq j} R_{ij}$$

**References**

- Wikipedia entry for Davies-Bouldin index.

**Contingency Matrix**

Contingency matrix (sklearn.metrics.cluster.contingency_matrix) reports the intersection cardinality for every true/predicted cluster pair. The contingency matrix provides sufficient statistics for all clustering metrics where the samples are independent and identically distributed and one doesn’t need to account for some instances not being clustered.

Here is an example:

```python
>>> from sklearn.metrics.cluster import contingency_matrix
>>> x = ["a", "a", "a", "b", "b", "b"]
>>> y = [0, 0, 1, 1, 2, 2]
>>> contingency_matrix(x, y)
array([[2, 1, 0],
       [1, 1, 2],
       [0, 0, 2]])
```

The first row of output array indicates that there are three samples whose true cluster is “a”. Of them, two are in predicted cluster 0, one is in 1, and none is in 2. And the second row indicates that there are three samples whose true cluster is “b”. Of them, none is in predicted cluster 0, one is in 1 and two are in 2.

A *confusion matrix* for classification is a square contingency matrix where the order of rows and columns correspond to a list of classes.

**Advantages**

- Allows to examine the spread of each true cluster across predicted clusters and vice versa.
- The contingency table calculated is typically utilized in the calculation of a similarity statistic (like the others listed in this document) between the two clusterings.
Drawbacks

• Contingency matrix is easy to interpret for a small number of clusters, but becomes very hard to interpret for a large number of clusters.
• It doesn’t give a single metric to use as an objective for clustering optimisation.

References

• Wikipedia entry for contingency matrix

Pair Confusion Matrix

The pair confusion matrix (sklearn.metrics.cluster.pair_confusion_matrix) is a 2x2 similarity matrix

\[
C = \begin{bmatrix}
C_{00} & C_{01} \\
C_{10} & C_{11}
\end{bmatrix}
\]

between two clusterings computed by considering all pairs of samples and counting pairs that are assigned into the same or into different clusters under the true and predicted clusterings.

It has the following entries:

- \(C_{00}\): number of pairs with both clusterings having the samples not clustered together
- \(C_{10}\): number of pairs with the true label clustering having the samples clustered together but the other clustering not having the samples clustered together
- \(C_{01}\): number of pairs with the true label clustering not having the samples clustered together but the other clustering having the samples clustered together
- \(C_{11}\): number of pairs with both clusterings having the samples clustered together

Considering a pair of samples that is clustered together a positive pair, then as in binary classification the count of true negatives is \(C_{00}\), false negatives is \(C_{10}\), true positives is \(C_{11}\) and false positives is \(C_{01}\).

Perfectly matching labelings have all non-zero entries on the diagonal regardless of actual label values:

```python
>>> from sklearn.metrics.cluster import pair_confusion_matrix
>>> pair_confusion_matrix([0, 0, 1, 1], [0, 0, 1, 1])
array([[8, 0],
       [0, 4]])
```

Labelings that assign all classes members to the same clusters are complete but may not always be pure, hence penalized, and have some off-diagonal non-zero entries:

```python
>>> pair_confusion_matrix([0, 0, 1, 1], [1, 1, 0, 0])
array([[8, 2],
       [0, 4]])
```

The matrix is not symmetric:
If classes members are completely split across different clusters, the assignment is totally incomplete, hence the matrix has all zero diagonal entries:

```python
>>> pair_confusion_matrix([0, 0, 0, 0], [0, 1, 2, 3])
array([[ 0, 0],
       [12, 0]])
```

References


4.2.4 Biclustering

Biclustering can be performed with the module `sklearn.cluster.bicluster`. Biclustering algorithms simultaneously cluster rows and columns of a data matrix. These clusters of rows and columns are known as biclusters. Each determines a submatrix of the original data matrix with some desired properties.

For instance, given a matrix of shape (10, 10), one possible bicluster with three rows and two columns induces a submatrix of shape (3, 2):

```python
>>> import numpy as np
>>> data = np.arange(100).reshape(10, 10)
>>> rows = np.array([0, 2, 3])[:, np.newaxis]
>>> columns = np.array([1, 2])
>>> data[rows, columns]
array([[ 1,  2],
       [21, 22],
       [31, 32]])
```

For visualization purposes, given a bicluster, the rows and columns of the data matrix may be rearranged to make the bicluster contiguous.

Algorithms differ in how they define biclusters. Some of the common types include:

- constant values, constant rows, or constant columns
- unusually high or low values
- submatrices with low variance
- correlated rows or columns

Algorithms also differ in how rows and columns may be assigned to biclusters, which leads to different bicluster structures. Block diagonal or checkerboard structures occur when rows and columns are divided into partitions.

If each row and each column belongs to exactly one bicluster, then rearranging the rows and columns of the data matrix reveals the biclusters on the diagonal. Here is an example of this structure where biclusters have higher average values than the other rows and columns:

In the checkerboard case, each row belongs to all column clusters, and each column belongs to all row clusters. Here is an example of this structure where the variance of the values within each bicluster is small:
Fig. 6: An example of biclusters formed by partitioning rows and columns.

Fig. 7: An example of checkerboard biclusters.
After fitting a model, row and column cluster membership can be found in the `rows_` and `columns_` attributes. `rows_[i]` is a binary vector with nonzero entries corresponding to rows that belong to bicluster i. Similarly, `columns_[i]` indicates which columns belong to bicluster i.

Some models also have `row_labels_` and `column_labels_` attributes. These models partition the rows and columns, such as in the block diagonal and checkerboard bicluster structures.

**Note:** Biclustering has many other names in different fields including co-clustering, two-mode clustering, two-way clustering, block clustering, coupled two-way clustering, etc. The names of some algorithms, such as the Spectral Co-Clustering algorithm, reflect these alternate names.

### Spectral Co-Clustering

The SpectralCoClustering algorithm finds biclusters with values higher than those in the corresponding other rows and columns. Each row and each column belongs to exactly one bicluster, so rearranging the rows and columns to make partitions contiguous reveals these high values along the diagonal.

**Note:** The algorithm treats the input data matrix as a bipartite graph: the rows and columns of the matrix correspond to the two sets of vertices, and each entry corresponds to an edge between a row and a column. The algorithm approximates the normalized cut of this graph to find heavy subgraphs.

### Mathematical formulation

An approximate solution to the optimal normalized cut may be found via the generalized eigenvalue decomposition of the Laplacian of the graph. Usually this would mean working directly with the Laplacian matrix. If the original data matrix $A$ has shape $m \times n$, the Laplacian matrix for the corresponding bipartite graph has shape $(m + n) \times (m + n)$. However, in this case it is possible to work directly with $A$, which is smaller and more efficient.

The input matrix $A$ is preprocessed as follows:

$$A_n = R^{-1/2}AC^{-1/2}$$

Where $R$ is the diagonal matrix with entry $i$ equal to $\sum_j A_{ij}$ and $C$ is the diagonal matrix with entry $j$ equal to $\sum_i A_{ij}$.

The singular value decomposition, $A_n = U\Sigma V^\top$, provides the partitions of the rows and columns of $A$. A subset of the left singular vectors gives the row partitions, and a subset of the right singular vectors gives the column partitions.

The $\ell = \lceil \log_2 k \rceil$ singular vectors, starting from the second, provide the desired partitioning information. They are used to form the matrix $Z$:

$$Z = \begin{bmatrix} R^{-1/2}U \\ C^{-1/2}V \end{bmatrix}$$

where the columns of $U$ are $u_2, \ldots, u_{\ell+1}$, and similarly for $V$.

Then the rows of $Z$ are clustered using $k$-means. The first `n_rows` labels provide the row partitioning, and the remaining `n_columns` labels provide the column partitioning.

### Examples:
• **A demo of the Spectral Co-Clustering algorithm**: A simple example showing how to generate a data matrix with biclusters and apply this method to it.

• **Biclustering documents with the Spectral Co-clustering algorithm**: An example of finding biclusters in the twenty newsgroup dataset.

**References:**


**Spectral Biclustering**

The **SpectralBiclustering** algorithm assumes that the input data matrix has a hidden checkerboard structure. The rows and columns of a matrix with this structure may be partitioned so that the entries of any bicluster in the Cartesian product of row clusters and column clusters are approximately constant. For instance, if there are two row partitions and three column partitions, each row will belong to three biclusters, and each column will belong to two biclusters.

The algorithm partitions the rows and columns of a matrix so that a corresponding blockwise-constant checkerboard matrix provides a good approximation to the original matrix.

**Mathematical formulation**

The input matrix $A$ is first normalized to make the checkerboard pattern more obvious. There are three possible methods:

1. **Independent row and column normalization**, as in Spectral Co-Clustering. This method makes the rows sum to a constant and the columns sum to a different constant.

2. **Bistochastization**: repeated row and column normalization until convergence. This method makes both rows and columns sum to the same constant.

3. **Log normalization**: the log of the data matrix is computed: $L = \log A$. Then the column mean $\overline{L}_i$, row mean $\overline{L}_j$, and overall mean $\overline{L}_\cdot$ of $L$ are computed. The final matrix is computed according to the formula

   $$K_{ij} = L_{ij} - \overline{L}_i - \overline{L}_j + \overline{L}_\cdot$$

After normalizing, the first few singular vectors are computed, just as in the Spectral Co-Clustering algorithm. If log normalization was used, all the singular vectors are meaningful. However, if independent normalization or bistochastization were used, the first singular vectors, $u_1$ and $v_1$, are discarded. From now on, the “first” singular vectors refers to $u_2 \ldots u_{p+1}$ and $v_2 \ldots v_{p+1}$ except in the case of log normalization.

Given these singular vectors, they are ranked according to which can be best approximated by a piecewise-constant vector. The approximations for each vector are found using one-dimensional k-means and scored using the Euclidean distance. Some subset of the best left and right singular vector are selected. Next, the data is projected to this best subset of singular vectors and clustered.

For instance, if $p$ singular vectors were calculated, the $q$ best are found as described, where $q < p$. Let $U$ be the matrix with columns the $q$ best left singular vectors, and similarly $V$ for the right. To partition the rows, the rows of $A$ are projected to a $q$ dimensional space: $A \ast V$. Treating the $m$ rows of this $m \times q$ matrix as samples and clustering using k-means yields the row labels. Similarly, projecting the columns to $A^\top \ast U$ and clustering this $n \times q$ matrix yields the column labels.
Examples:

- A demo of the Spectral Biclustering algorithm: a simple example showing how to generate a checkerboard matrix and bicluster it.

References:

- Kluger, Yuval, et. al., 2003. Spectral biclustering of microarray data: coclustering genes and conditions.

Biclustering evaluation

There are two ways of evaluating a biclustering result: internal and external. Internal measures, such as cluster stability, rely only on the data and the result themselves. Currently there are no internal bicluster measures in scikit-learn. External measures refer to an external source of information, such as the true solution. When working with real data the true solution is usually unknown, but biclustering artificial data may be useful for evaluating algorithms precisely because the true solution is known.

To compare a set of found biclusters to the set of true biclusters, two similarity measures are needed: a similarity measure for individual biclusters, and a way to combine these individual similarities into an overall score.

To compare individual biclusters, several measures have been used. For now, only the Jaccard index is implemented:

\[ J(A, B) = \frac{|A \cap B|}{|A| + |B| - |A \cap B|} \]

where \( A \) and \( B \) are biclusters, \( |A \cap B| \) is the number of elements in their intersection. The Jaccard index achieves its minimum of 0 when the biclusters do not overlap at all and its maximum of 1 when they are identical.

Several methods have been developed to compare two sets of biclusters. For now, only consensus_score (Hochreiter et. al., 2010) is available:

1. Compute bicluster similarities for pairs of biclusters, one in each set, using the Jaccard index or a similar measure.
2. Assign biclusters from one set to another in a one-to-one fashion to maximize the sum of their similarities. This step is performed using the Hungarian algorithm.
3. The final sum of similarities is divided by the size of the larger set.

The minimum consensus score, 0, occurs when all pairs of biclusters are totally dissimilar. The maximum score, 1, occurs when both sets are identical.

References:

- Hochreiter, Bodenhofer, et. al., 2010. FABIA: factor analysis for bicluster acquisition.
4.2.5 Decomposing signals in components (matrix factorization problems)

Principal component analysis (PCA)

Exact PCA and probabilistic interpretation

PCA is used to decompose a multivariate dataset in a set of successive orthogonal components that explain a maximum amount of the variance. In scikit-learn, PCA is implemented as a transformer object that learns $n$ components in its fit method, and can be used on new data to project it on these components.

PCA centers but does not scale the input data for each feature before applying the SVD. The optional parameter whiten=True makes it possible to project the data onto the singular space while scaling each component to unit variance. This is often useful if the models down-stream make strong assumptions on the isotropy of the signal: this is for example the case for Support Vector Machines with the RBF kernel and the K-Means clustering algorithm.

Below is an example of the iris dataset, which is comprised of 4 features, projected on the 2 dimensions that explain most variance:

![PCA of IRIS dataset](image)

The PCA object also provides a probabilistic interpretation of the PCA that can give a likelihood of data based on the amount of variance it explains. As such it implements a score method that can be used in cross-validation:

Examples:

- Comparison of LDA and PCA 2D projection of Iris dataset
- Model selection with Probabilistic PCA and Factor Analysis (FA)
Incremental PCA

The **PCA** object is very useful, but has certain limitations for large datasets. The biggest limitation is that **PCA** only supports batch processing, which means all of the data to be processed must fit in main memory. The **IncrementalPCA** object uses a different form of processing and allows for partial computations which almost exactly match the results of **PCA** while processing the data in a minibatch fashion. **IncrementalPCA** makes it possible to implement out-of-core Principal Component Analysis either by:

- Using its `partial_fit` method on chunks of data fetched sequentially from the local hard drive or a network database.
- Calling its `fit` method on a sparse matrix or a memory mapped file using `numpy.memmap`.

**IncrementalPCA** only stores estimates of component and noise variances, in order update `explained_variance_ratio_` incrementally. This is why memory usage depends on the number of samples per batch, rather than the number of samples to be processed in the dataset.

As in **PCA**, **IncrementalPCA** centers but does not scale the input data for each feature before applying the SVD.

Examples:

- **Incremental PCA**
Incremental PCA of iris dataset
Mean absolute unsigned error 0.002201
PCA using randomized SVD

It is often interesting to project data to a lower-dimensional space that preserves most of the variance, by dropping the singular vector of components associated with lower singular values.

For instance, if we work with 64x64 pixel gray-level pictures for face recognition, the dimensionality of the data is 4096 and it is slow to train an RBF support vector machine on such wide data. Furthermore we know that the intrinsic dimensionality of the data is much lower than 4096 since all pictures of human faces look somewhat alike. The samples lie on a manifold of much lower dimension (say around 200 for instance). The PCA algorithm can be used to linearly transform the data while both reducing the dimensionality and preserve most of the explained variance at the same time.

The class `PCA` used with the optional parameter `svd_solver='randomized'` is very useful in that case: since we are going to drop most of the singular vectors it is much more efficient to limit the computation to an approximated estimate of the singular vectors we will keep to actually perform the transform.

For instance, the following shows 16 sample portraits (centered around 0.0) from the Olivetti dataset. On the right hand side are the first 16 singular vectors reshaped as portraits. Since we only require the top 16 singular vectors of a dataset with size \( n_{\text{samples}} = 400 \) and \( n_{\text{features}} = 64 \times 64 = 4096 \), the computation time is less than 1s:

If we note \( n_{\text{max}} = \max(n_{\text{samples}}, n_{\text{features}}) \) and \( n_{\text{min}} = \min(n_{\text{samples}}, n_{\text{features}}) \), the time complexity of the randomized PCA is \( O(n_{\text{max}}^2 \cdot n_{\text{components}}) \) instead of \( O(n_{\text{max}}^2 \cdot n_{\text{min}}) \) for the exact method implemented in `PCA`.
The memory footprint of randomized PCA is also proportional to $2 \cdot n_{\text{max}} \cdot n_{\text{components}}$ instead of $n_{\text{max}} \cdot n_{\text{min}}$ for the exact method.

Note: the implementation of `inverse_transform` in PCA with `svd_solver='randomized'` is not the exact inverse transform of `transform` even when `whiten=False` (default).

**Examples:**

- Faces recognition example using eigenfaces and SVMs
- Faces dataset decompositions

**References:**

- “Finding structure with randomness: Stochastic algorithms for constructing approximate matrix decompositions” Halko, et al., 2009

**Kernel PCA**

*KernelPCA* is an extension of PCA which achieves non-linear dimensionality reduction through the use of kernels (see *Pairwise metrics, Affinities and Kernels*). It has many applications including denoising, compression and structured prediction (kernel dependency estimation). *KernelPCA* supports both `transform` and `inverse_transform`.

**Example:**

- Kernel PCA
Sparse principal components analysis (SparsePCA and MiniBatchSparsePCA)

SparsePCA is a variant of PCA, with the goal of extracting the set of sparse components that best reconstruct the data.

Mini-batch sparse PCA (MiniBatchSparsePCA) is a variant of SparsePCA that is faster but less accurate. The increased speed is reached by iterating over small chunks of the set of features, for a given number of iterations.

Principal component analysis (PCA) has the disadvantage that the components extracted by this method have exclusively dense expressions, i.e. they have non-zero coefficients when expressed as linear combinations of the original variables. This can make interpretation difficult. In many cases, the real underlying components can be more naturally imagined as sparse vectors; for example in face recognition, components might naturally map to parts of faces.

Sparse principal components yields a more parsimonious, interpretable representation, clearly emphasizing which of the original features contribute to the differences between samples.

The following example illustrates 16 components extracted using sparse PCA from the Olivetti faces dataset. It can be seen how the regularization term induces many zeros. Furthermore, the natural structure of the data causes the non-zero coefficients to be vertically adjacent. The model does not enforce this mathematically: each component is a vector $h \in \mathbb{R}^{4096}$, and there is no notion of vertical adjacency except during the human-friendly visualization as 64x64 pixel images. The fact that the components shown below appear local is the effect of the inherent structure of the data, which makes such local patterns minimize reconstruction error. There exist sparsity-inducing norms that take into account adjacency and different kinds of structure; see [Jen09] for a review of such methods. For more details on how to use Sparse PCA, see the Examples section, below.
Sparse comp. - MiniBatchSparsePCA - Train time 0.9s

Note that there are many different formulations for the Sparse PCA problem. The one implemented here is based on [Mrl09]. The optimization problem solved is a PCA problem (dictionary learning) with an $\ell_1$ penalty on the components:

\[
(U^*, V^*) = \arg \min_{U, V} \frac{1}{2} \|X - UV\|_2^2 + \alpha \|V\|_1
\]

subject to $\|U_k\|_2 = 1$ for all $0 \leq k < n_{\text{components}}$

The sparsity-inducing $\ell_1$ norm also prevents learning components from noise when few training samples are available. The degree of penalization (and thus sparsity) can be adjusted through the hyperparameter \texttt{alpha}. Small values lead to a gently regularized factorization, while larger values shrink many coefficients to zero.

Note: While in the spirit of an online algorithm, the class \texttt{MiniBatchSparsePCA} does not implement \texttt{partial_fit} because the algorithm is online along the features direction, not the samples direction.

Examples:

- \texttt{Faces dataset decompositions}

References:

\textbf{Truncated singular value decomposition and latent semantic analysis}

\textit{TruncatedSVD} implements a variant of singular value decomposition (SVD) that only computes the $k$ largest singular values, where $k$ is a user-specified parameter.

When truncated SVD is applied to term-document matrices (as returned by \texttt{CountVectorizer} or \texttt{TfidfVectorizer}), this transformation is known as latent semantic analysis (LSA), because it transforms such matrices to a “semantic” space of low dimensionality. In particular, LSA is known to combat the effects of synonymy and polysemy (both of which roughly mean there are multiple meanings per word), which cause term-document matrices to be overly sparse and exhibit poor similarity under measures such as cosine similarity.
**Note:** LSA is also known as latent semantic indexing, LSI, though strictly that refers to its use in persistent indexes for information retrieval purposes.

Mathematically, truncated SVD applied to training samples $X$ produces a low-rank approximation $X$:

$$X \approx X_k = U_k \Sigma_k V_k^T$$

After this operation, $U_k \Sigma_k^T$ is the transformed training set with $k$ features (called `n_components` in the API). To also transform a test set $X$, we multiply it with $V_k$:

$$X' = XV_k$$

**Note:** Most treatments of LSA in the natural language processing (NLP) and information retrieval (IR) literature swap the axes of the matrix $X$ so that it has shape $n_{\text{features}} \times n_{\text{samples}}$. We present LSA in a different way that matches the scikit-learn API better, but the singular values found are the same.

*TruncatedSVD* is very similar to *PCA*, but differs in that the matrix $X$ does not need to be centered. When the columnwise (per-feature) means of $X$ are subtracted from the feature values, truncated SVD on the resulting matrix is equivalent to PCA. In practical terms, this means that the *TruncatedSVD* transformer accepts `scipy.sparse` matrices without the need to densify them, as densifying may fill up memory even for medium-sized document collections.

While the *TruncatedSVD* transformer works with any feature matrix, using it on tf–idf matrices is recommended over raw frequency counts in an LSA/document processing setting. In particular, sublinear scaling and inverse document frequency should be turned on (`sublinear_tf=True, use_idf=True`) to bring the feature values closer to a Gaussian distribution, compensating for LSA’s erroneous assumptions about textual data.

**Examples:**

- *Clustering text documents using k-means*

**References:**

- Christopher D. Manning, Prabhakar Raghavan and Hinrich Schütze (2008), *Introduction to Information Retrieval*, Cambridge University Press, chapter 18: Matrix decompositions & latent semantic indexing

**Dictionary Learning**

**Sparse coding with a precomputed dictionary**

The *SparseCoder* object is an estimator that can be used to transform signals into sparse linear combination of atoms from a fixed, precomputed dictionary such as a discrete wavelet basis. This object therefore does not implement a `fit` method. The transformation amounts to a sparse coding problem: finding a representation of the data as a linear combination of as few dictionary atoms as possible. All variations of dictionary learning implement the following transform methods, controllable via the `transform_method` initialization parameter:

- Orthogonal matching pursuit (*Orthogonal Matching Pursuit (OMP)*)

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• Least-angle regression (*Least Angle Regression*)
• Lasso computed by least-angle regression
• Lasso using coordinate descent (*Lasso*)
• Thresholding

Thresholding is very fast but it does not yield accurate reconstructions. They have been shown useful in literature for classification tasks. For image reconstruction tasks, orthogonal matching pursuit yields the most accurate, unbiased reconstruction.

The dictionary learning objects offer, via the `split_code` parameter, the possibility to separate the positive and negative values in the results of sparse coding. This is useful when dictionary learning is used for extracting features that will be used for supervised learning, because it allows the learning algorithm to assign different weights to negative loadings of a particular atom, from to the corresponding positive loading.

The split code for a single sample has length $2 \times n_{\text{components}}$ and is constructed using the following rule: First, the regular code of length $n_{\text{components}}$ is computed. Then, the first $n_{\text{components}}$ entries of the `split_code` are filled with the positive part of the regular code vector. The second half of the split code is filled with the negative part of the code vector, only with a positive sign. Therefore, the split code is non-negative.

**Examples:**

• *Sparse coding with a precomputed dictionary*

**Generic dictionary learning**

Dictionary learning (*DictionaryLearning*) is a matrix factorization problem that amounts to finding a (usually overcomplete) dictionary that will perform well at sparsely encoding the fitted data.

Representing data as sparse combinations of atoms from an overcomplete dictionary is suggested to be the way the mammalian primary visual cortex works. Consequently, dictionary learning applied on image patches has been shown to give good results in image processing tasks such as image completion, inpainting and denoising, as well as for supervised recognition tasks.

Dictionary learning is an optimization problem solved by alternatively updating the sparse code, as a solution to multiple Lasso problems, considering the dictionary fixed, and then updating the dictionary to best fit the sparse code.

\[
(U^*, V^*) = \arg \min_{U, V} \frac{1}{2} \| X - UV \|^2 + \alpha \| U \|_1
\]

subject to $\| V_k \|_2 = 1$ for all $0 \leq k < n_{\text{atoms}}$
After using such a procedure to fit the dictionary, the transform is simply a sparse coding step that shares the same implementation with all dictionary learning objects (see Sparse coding with a precomputed dictionary).

It is also possible to constrain the dictionary and/or code to be positive to match constraints that may be present in the data. Below are the faces with different positivity constraints applied. Red indicates negative values, blue indicates positive values, and white represents zeros.
The following image shows how a dictionary learned from 4x4 pixel image patches extracted from part of the image of a raccoon face looks like.

Examples:

- Image denoising using dictionary learning

References:

Mini-batch dictionary learning

`MiniBatchDictionaryLearning` implements a faster, but less accurate version of the dictionary learning algorithm that is better suited for large datasets.

By default, `MiniBatchDictionaryLearning` divides the data into mini-batches and optimizes in an online manner by cycling over the mini-batches for the specified number of iterations. However, at the moment it does not implement a stopping condition.

The estimator also implements `partial_fit`, which updates the dictionary by iterating only once over a mini-batch. This can be used for online learning when the data is not readily available from the start, or for when the data does not fit into the memory.

Clustering for dictionary learning

Note that when using dictionary learning to extract a representation (e.g. for sparse coding) clustering can be a good proxy to learn the dictionary. For instance the `MiniBatchKMeans` estimator is computationally efficient and implements on-line learning with a `partial_fit` method.

Example: Online learning of a dictionary of parts of faces

Factor Analysis

In unsupervised learning we only have a dataset \( X = \{x_1, x_2, \ldots, x_n\} \). How can this dataset be described mathematically? A very simple continuous latent variable model for \( X \) is

\[
x_i = W h_i + \mu + \epsilon
\]

The vector \( h_i \) is called “latent” because it is unobserved. \( \epsilon \) is considered a noise term distributed according to a Gaussian with mean 0 and covariance \( \Psi \) (i.e. \( \epsilon \sim \mathcal{N}(0, \Psi) \)), \( \mu \) is some arbitrary offset vector. Such a model is called “generative” as it describes how \( x_i \) is generated from \( h_i \). If we use all the \( x_i \)'s as columns to form a matrix \( X \) and all the \( h_i \)'s as columns of a matrix \( H \) then we can write (with suitably defined \( M \) and \( E \)):

\[
X = WH + M + E
\]

In other words, we decomposed matrix \( X \).

If \( h_i \) is given, the above equation automatically implies the following probabilistic interpretation:

\[
p(x_i|h_i) = \mathcal{N}(Wh_i + \mu, \Psi)
\]
For a complete probabilistic model we also need a prior distribution for the latent variable \( h \). The most straightforward assumption (based on the nice properties of the Gaussian distribution) is \( h \sim \mathcal{N}(0, I) \). This yields a Gaussian as the marginal distribution of \( x \):

\[
p(x) = \mathcal{N}(\mu, WW^T + \Psi)
\]

Now, without any further assumptions the idea of having a latent variable \( h \) would be superfluous – \( x \) can be completely modelled with a mean and a covariance. We need to impose some more specific structure on one of these two parameters. A simple additional assumption regards the structure of the error covariance \( \Psi \):

- \( \Psi = \sigma^2 I \): This assumption leads to the probabilistic model of PCA.
- \( \Psi = \text{diag}(\psi_1, \psi_2, \ldots, \psi_n) \): This model is called FactorAnalysis, a classical statistical model. The matrix \( W \) is sometimes called the “factor loading matrix”.

Both models essentially estimate a Gaussian with a low-rank covariance matrix. Because both models are probabilistic they can be integrated in more complex models, e.g. Mixture of Factor Analysers. One gets very different models (e.g. FastICA) if non-Gaussian priors on the latent variables are assumed.

Factor analysis can produce similar components (the columns of its loading matrix) to PCA. However, one can not make any general statements about these components (e.g. whether they are orthogonal):

The main advantage for Factor Analysis over PCA is that it can model the variance in every direction of the input space independently (heteroscedastic noise):
This allows better model selection than probabilistic PCA in the presence of heteroscedastic noise:

Factor Analysis is often followed by a rotation of the factors (with the parameter rotation), usually to improve interpretability. For example, Varimax rotation maximizes the sum of the variances of the squared loadings, i.e., it tends to produce sparser factors, which are influenced by only a few features each (the “simple structure”). See e.g., the first example below.

Examples:

- Factor Analysis (with rotation) to visualize patterns
- Model selection with Probabilistic PCA and Factor Analysis (FA)
Independent component analysis (ICA)

Independent component analysis separates a multivariate signal into additive subcomponents that are maximally independent. It is implemented in scikit-learn using the Fast ICA algorithm. Typically, ICA is not used for reducing dimensionality but for separating superimposed signals. Since the ICA model does not include a noise term, for the model to be correct, whitening must be applied. This can be done internally using the whiten argument or manually using one of the PCA variants.

It is classically used to separate mixed signals (a problem known as blind source separation), as in the example below:

ICA can also be used as yet another non linear decomposition that finds components with some sparsity:

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Examples:

- Blind source separation using FastICA
- FastICA on 2D point clouds
- Faces dataset decompositions

Non-negative matrix factorization (NMF or NNMF)

NMF\(^1\) is an alternative approach to decomposition that assumes that the data and the components are non-negative. NMF can be plugged in instead of PCA or its variants, in the cases where the data matrix does not contain negative values. It finds a decomposition of samples \(X\) into two matrices \(W\) and \(H\) of non-negative elements, by optimizing the distance \(d\) between \(X\) and the matrix product \(WH\). The most widely used distance function is the squared Frobenius norm, which is an obvious extension of the Euclidean norm to matrices:

\[
D_{\text{Fro}}(X, Y) = \frac{1}{2} \|X - Y\|_{\text{Fro}}^2 = \frac{1}{2} \sum_{i,j} (X_{ij} - Y_{ij})^2
\]

Unlike PCA, the representation of a vector is obtained in an additive fashion, by superimposing the components, without subtracting. Such additive models are efficient for representing images and text.

It has been observed in [Hoyer, 2004]\(^2\) that, when carefully constrained, NMF can produce a parts-based representation of the dataset, resulting in interpretable models. The following example displays 16 sparse components found by NMF from the images in the Olivetti faces dataset, in comparison with the PCA eigenfaces.

\(^1\) “Learning the parts of objects by non-negative matrix factorization” D. Lee, S. Seung, 1999

\(^2\) “Non-negative Matrix Factorization with Sparseness Constraints” P. Hoyer, 2004
The `init` attribute determines the initialization method applied, which has a great impact on the performance of the method. **NMF** implements the method Nonnegative Double Singular Value Decomposition. NNDSVD is based on two SVD processes, one approximating the data matrix, the other approximating positive sections of the resulting partial SVD factors utilizing an algebraic property of unit rank matrices. The basic NNDSVD algorithm is better fit for sparse factorization. Its variants NNDSVDa (in which all zeros are set equal to the mean of all elements of the data), and NNDSVDar (in which the zeros are set to random perturbations less than the mean of the data divided by 100) are recommended in the dense case.

Note that the Multiplicative Update ('mu') solver cannot update zeros present in the initialization, so it leads to poorer results when used jointly with the basic NNDSVD algorithm which introduces a lot of zeros; in this case, NNDSVDa or NNDSVDar should be preferred.

**NMF** can also be initialized with correctly scaled random non-negative matrices by setting `init="random"`. An integer seed or a `RandomState` can also be passed to `random_state` to control reproducibility.

In **NMF**, L1 and L2 priors can be added to the loss function in order to regularize the model. The L2 prior uses the Frobenius norm, while the L1 prior uses an elementwise L1 norm. As in **ElasticNet**, we control the combination of L1 and L2 with the `l1_ratio` ($\rho$) parameter, and the intensity of the regularization with the `alpha` ($\alpha$) parameter. Then the priors terms are:

$$
\alpha \rho ||W||_1 + \alpha ||H||_1 + \frac{\alpha(1-\rho)}{2} ||W||^2_{Fro} + \frac{\alpha(1-\rho)}{2} ||H||^2_{Fro}
$$

---

4 “SVD based initialization: A head start for nonnegative matrix factorization” C. Boutsidis, E. Gallopoulos, 2008
and the regularized objective function is:

$$d_{\text{Fro}}(X, WH) + \alpha \rho ||W||_1 + \alpha \rho ||H||_1 + \frac{\alpha(1-\rho)}{2} ||W||^2_{\text{Fro}} + \frac{\alpha(1-\rho)}{2} ||H||^2_{\text{Fro}}$$

NMF regularizes both W and H by default. The regularization parameter allows for finer control, with which only W, only H, or both can be regularized.

**NMF with a beta-divergence**

As described previously, the most widely used distance function is the squared Frobenius norm, which is an obvious extension of the Euclidean norm to matrices:

$$d_{\text{Fro}}(X, Y) = \frac{1}{2} ||X - Y||^2_{\text{Fro}} = \frac{1}{2} \sum_{i,j} (X_{ij} - Y_{ij})^2$$

Other distance functions can be used in NMF as, for example, the (generalized) Kullback-Leibler (KL) divergence, also referred as I-divergence:

$$d_{\text{KL}}(X, Y) = \sum_{i,j} (X_{ij} \log \frac{X_{ij}}{Y_{ij}} - X_{ij} + Y_{ij})$$

Or, the Itakura-Saito (IS) divergence:

$$d_{\text{IS}}(X, Y) = \sum_{i,j} \left( \frac{X_{ij}}{Y_{ij}} - \log \left( \frac{X_{ij}}{Y_{ij}} \right) - 1 \right)$$

These three distances are special cases of the beta-divergence family, with $\beta = 2, 1, 0$ respectively. The beta-divergence are defined by:

$$d_{\beta}(X, Y) = \sum_{i,j} \frac{1}{\beta(\beta-1)} (X_{ij}^{\beta} + (\beta-1)Y_{ij}^{\beta} - \beta X_{ij}Y_{ij}^{\beta-1})$$

Note that this definition is not valid if $\beta \in (0; 1)$, yet it can be continuously extended to the definitions of $d_{\text{KL}}$ and $d_{\text{IS}}$ respectively.

NMF implements two solvers, using Coordinate Descent (‘cd’), and Multiplicative Update (‘mu’). The ‘mu’ solver can optimize every beta-divergence, including of course the Frobenius norm ($\beta = 2$), the (generalized) Kullback-Leibler divergence ($\beta = 1$) and the Itakura-Saito divergence ($\beta = 0$). Note that for $\beta \in (1; 2)$, the ‘mu’ solver is significantly faster than for other values of $\beta$. Note also that with a negative (or 0, i.e. ‘itakura-saito’) $\beta$, the input matrix cannot contain zero values.

The ‘cd’ solver can only optimize the Frobenius norm. Due to the underlying non-convexity of NMF, the different solvers may converge to different minima, even when optimizing the same distance function.

NMF is best used with the fit_transform method, which returns the matrix W. The matrix H is stored into the fitted model in the components_ attribute; the method transform will decompose a new matrix X_new based on these stored components:

```python
>>> import numpy as np
>>> X = np.array([[1, 1], [2, 1], [3, 1.2], [4, 1], [5, 0.8], [6, 1]])
>>> from sklearn.decomposition import NMF

(continues on next page)
```

---

6 “Algorithms for nonnegative matrix factorization with the beta-divergence” C. Fevotte, J. Idier, 2011

5 “Fast local algorithms for large scale nonnegative matrix and tensor factorizations.” A. Cichocki, A. Phan, 2009
model = NMF(n_components=2, init='random', random_state=0)

W = model.fit_transform(X)

H = model.components_

X_new = np.array([[1, 0], [1, 6.1], [1, 0], [1, 4], [3.2, 1], [0, 4]])

W_new = model.transform(X_new)

Examples:

• Faces dataset decompositions
• Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation
• Beta-divergence loss functions

References:

Latent Dirichlet Allocation (LDA)

Latent Dirichlet Allocation is a generative probabilistic model for collections of discrete dataset such as text corpora. It is also a topic model that is used for discovering abstract topics from a collection of documents.

The graphical model of LDA is a three-level generative model:
Note on notations presented in the graphical model above, which can be found in Hoffman et al. (2013):

- The corpus is a collection of \( D \) documents.
- A document is a sequence of \( N \) words.
- There are \( K \) topics in the corpus.
- The boxes represent repeated sampling.

In the graphical model, each node is a random variable and has a role in the generative process. A shaded node indicates an observed variable and an unshaded node indicates a hidden (latent) variable. In this case, words in the corpus are the only data that we observe. The latent variables determine the random mixture of topics in the corpus and the distribution of words in the documents. The goal of LDA is to use the observed words to infer the hidden topic structure.

When modeling text corpora, the model assumes the following generative process for a corpus with \( D \) documents and \( K \) topics, with \( K \) corresponding to `n_components` in the API:

1. For each topic \( k \in K \), draw \( \beta_k \sim \text{Dirichlet}(\eta) \). This provides a distribution over the words, i.e. the probability of a word appearing in topic \( k \). \( \eta \) corresponds to `topic_word_prior`.
2. For each document \( d \in D \), draw the topic proportions \( \theta_d \sim \text{Dirichlet}(\alpha) \). \( \alpha \) corresponds to `doc_topic_prior`.
3. For each word \( i \) in document \( d \):
   a. Draw the topic assignment \( z_{di} \sim \text{Multinomial}(\theta_d) \)
   b. Draw the observed word \( w_{i,j} \sim \text{Multinomial}(\beta_{z_{di}}) \)

For parameter estimation, the posterior distribution is:

\[
p(z, \theta, \beta|w, \alpha, \eta) = \frac{p(z, \theta, \beta|\alpha, \eta)}{p(w|\alpha, \eta)}
\]

Since the posterior is intractable, variational Bayesian method uses a simpler distribution \( q(z, \theta, \beta|\lambda, \phi, \gamma) \) to approximate it, and those variational parameters \( \lambda, \phi, \gamma \) are optimized to maximize the Evidence Lower Bound (ELBO):

\[
\log P(w|\alpha, \eta) \geq L(w, \phi, \gamma, \lambda) \triangleq E_q[\log p(w, z, \theta, \beta|\alpha, \eta)] - E_q[\log q(z, \theta, \beta)]
\]

Maximizing ELBO is equivalent to minimizing the Kullback-Leibler(KL) divergence between \( q(z, \theta, \beta) \) and the true posterior \( p(z, \theta, \beta|w, \alpha, \eta) \).

`LatentDirichletAllocation` implements the online variational Bayes algorithm and supports both online and batch update methods. While the batch method updates variational variables after each full pass through the data, the online method updates variational variables from mini-batch data points.

**Note:** Although the online method is guaranteed to converge to a local optimum point, the quality of the optimum point and the speed of convergence may depend on mini-batch size and attributes related to learning rate setting.
When `LatentDirichletAllocation` is applied on a “document-term” matrix, the matrix will be decomposed into a “topic-term” matrix and a “document-topic” matrix. While “topic-term” matrix is stored as `components_` in the model, “document-topic” matrix can be calculated from `transform` method.

`LatentDirichletAllocation` also implements `partial_fit` method. This is used when data can be fetched sequentially.

**Examples:**

- Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation

**References:**


See also Dimensionality reduction for dimensionality reduction with Neighborhood Components Analysis.

### 4.2.6 Covariance estimation

Many statistical problems require the estimation of a population’s covariance matrix, which can be seen as an estimation of data set scatter plot shape. Most of the time, such an estimation has to be done on a sample whose properties (size, structure, homogeneity) have a large influence on the estimation’s quality. The `sklearn.covariance` package provides tools for accurately estimating a population’s covariance matrix under various settings.

We assume that the observations are independent and identically distributed (i.i.d.).

**Empirical covariance**

The covariance matrix of a data set is known to be well approximated by the classical maximum likelihood estimator (or “empirical covariance”), provided the number of observations is large enough compared to the number of features (the variables describing the observations). More precisely, the Maximum Likelihood Estimator of a sample is an asymptotically unbiased estimator of the corresponding population’s covariance matrix.

The empirical covariance matrix of a sample can be computed using the `empirical_covariance` function of the package, or by fitting an `EmpiricalCovariance` object to the data sample with the `EmpiricalCovariance.fit` method. Be careful that results depend on whether the data are centered, so one may want to use the `assume_centered` parameter accurately. More precisely, if `assume_centered=False`, then the test set is supposed to have the same mean vector as the training set. If not, both should be centered by the user, and `assume_centered=True` should be used.

**Examples:**

- See Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood for an example on how to fit an `EmpiricalCovariance` object to data.
Shrunk Covariance

Basic shrinkage

Despite being an asymptotically unbiased estimator of the covariance matrix, the Maximum Likelihood Estimator is not a good estimator of the eigenvalues of the covariance matrix, so the precision matrix obtained from its inversion is not accurate. Sometimes, it even occurs that the empirical covariance matrix cannot be inverted for numerical reasons. To avoid such an inversion problem, a transformation of the empirical covariance matrix has been introduced: the shrinkage.

In scikit-learn, this transformation (with a user-defined shrinkage coefficient) can be directly applied to a pre-computed covariance with the `shrunk_covariance` method. Also, a shrunk estimator of the covariance can be fitted to data with a `ShrunkCovariance` object and its `ShrunkCovariance.fit` method. Again, results depend on whether the data are centered, so one may want to use the `assume_centered` parameter accurately.

Mathematically, this shrinkage consists in reducing the ratio between the smallest and the largest eigenvalues of the empirical covariance matrix. It can be done by simply shifting every eigenvalue according to a given offset, which is equivalent of finding the l2-penalized Maximum Likelihood Estimator of the covariance matrix. In practice, shrinkage boils down to a simple a convex transformation: $\Sigma_{\text{shrunk}} = (1 - \alpha)\hat{\Sigma} + \alpha \frac{\text{Tr}\hat{\Sigma}}{p} \text{Id}$.

Choosing the amount of shrinkage, $\alpha$ amounts to setting a bias/variance trade-off, and is discussed below.

Examples:

- See Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood for an example on how to fit a `ShrunkCovariance` object to data.

Ledoit-Wolf shrinkage

In their 2004 paper, O. Ledoit and M. Wolf propose a formula to compute the optimal shrinkage coefficient $\alpha$ that minimizes the Mean Squared Error between the estimated and the real covariance matrix.

The Ledoit-Wolf estimator of the covariance matrix can be computed on a sample with the `ledoit_wolf` function of the `sklearn.covariance` package, or it can be otherwise obtained by fitting a `LedoitWolf` object to the same sample.

Note: Case when population covariance matrix is isotropic

It is important to note that when the number of samples is much larger than the number of features, one would expect that no shrinkage would be necessary. The intuition behind this is that if the population covariance is full rank, when the number of sample grows, the sample covariance will also become positive definite. As a result, no shrinkage would necessary and the method should automatically do this.

This, however, is not the case in the Ledoit-Wolf procedure when the population covariance happens to be a multiple of the identity matrix. In this case, the Ledoit-Wolf shrinkage estimate approaches 1 as the number of samples increases. This indicates that the optimal estimate of the covariance matrix in the Ledoit-Wolf sense is multiple of the identity. Since the population covariance is already a multiple of the identity matrix, the Ledoit-Wolf solution is indeed a reasonable estimate.

---

Examples:

- See *Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood* for an example on how to fit a `LedoitWolf` object to data and for visualizing the performances of the Ledoit-Wolf estimator in terms of likelihood.

References:

Oracle Approximating Shrinkage

Under the assumption that the data are Gaussian distributed, Chen et al.\(^2\) derived a formula aimed at choosing a shrinkage coefficient that yields a smaller Mean Squared Error than the one given by Ledoit and Wolf’s formula. The resulting estimator is known as the Oracle Shrinkage Approximating estimator of the covariance.

The OAS estimator of the covariance matrix can be computed on a sample with the `oas` function of the `sklearn.covariance` package, or it can be otherwise obtained by fitting an `OAS` object to the same sample.

![Regularized covariance: likelihood and shrinkage coefficient](image)

Fig. 8: Bias-variance trade-off when setting the shrinkage: comparing the choices of Ledoit-Wolf and OAS estimators

References:

Examples:

- See *Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood* for an example on how to fit an `OAS` object to data.

---

See *Ledoit-Wolf vs OAS estimation* to visualize the Mean Squared Error difference between a *LedoitWolf* and an *OAS* estimator of the covariance.

---

**Sparse inverse covariance**

The matrix inverse of the covariance matrix, often called the precision matrix, is proportional to the partial correlation matrix. It gives the partial independence relationship. In other words, if two features are independent conditionally on the others, the corresponding coefficient in the precision matrix will be zero. This is why it makes sense to estimate a sparse precision matrix: the estimation of the covariance matrix is better conditioned by learning independence relations from the data. This is known as *covariance selection*.

In the small-samples situation, in which `n_samples` is on the order of `n_features` or smaller, sparse inverse covariance estimators tend to work better than shrunk covariance estimators. However, in the opposite situation, or for very correlated data, they can be numerically unstable. In addition, unlike shrinkage estimators, sparse estimators are able to recover off-diagonal structure.

The *GraphicalLasso* estimator uses an l1 penalty to enforce sparsity on the precision matrix: the higher its `alpha` parameter, the more sparse the precision matrix. The corresponding *GraphicalLassoCV* object uses cross-validation to automatically set the `alpha` parameter.

**Note: Structure recovery**

Recovering a graphical structure from correlations in the data is a challenging thing. If you are interested in such recovery keep in mind that:

- Recovery is easier from a correlation matrix than a covariance matrix: standardize your observations before running *GraphicalLasso*.
- If the underlying graph has nodes with much more connections than the average node, the algorithm will miss some of these connections.
Fig. 9: A comparison of maximum likelihood, shrinkage and sparse estimates of the covariance and precision matrix in the very small samples settings.

- If your number of observations is not large compared to the number of edges in your underlying graph, you will not recover it.
- Even if you are in favorable recovery conditions, the alpha parameter chosen by cross-validation (e.g. using the GraphicalLassoCV object) will lead to selecting too many edges. However, the relevant edges will have heavier weights than the irrelevant ones.

The mathematical formulation is the following:

$$
\hat{K} = \text{argmin}_K \left( \text{tr} SK - \log \text{det} K + \alpha \| K \|_1 \right)
$$

Where $K$ is the precision matrix to be estimated, and $S$ is the sample covariance matrix. $\| K \|_1$ is the sum of the absolute values of off-diagonal coefficients of $K$. The algorithm employed to solve this problem is the GLasso algorithm, from the Friedman 2008 Biostatistics paper. It is the same algorithm as in the R glasso package.

**Examples:**

- *Sparse inverse covariance estimation:* example on synthetic data showing some recovery of a structure, and comparing to other covariance estimators.
- *Visualizing the stock market structure:* example on real stock market data, finding which symbols are most linked.

**References:**

Robust Covariance Estimation

Real data sets are often subject to measurement or recording errors. Regular but uncommon observations may also appear for a variety of reasons. Observations which are very uncommon are called outliers. The empirical covariance estimator and the shrunk covariance estimators presented above are very sensitive to the presence of outliers in the data. Therefore, one should use robust covariance estimators to estimate the covariance of its real data sets. Alternatively, robust covariance estimators can be used to perform outlier detection and discard/downweight some observations according to further processing of the data.

The sklearn.covariance package implements a robust estimator of covariance, the Minimum Covariance Determinant\(^3\).

Minimum Covariance Determinant

The Minimum Covariance Determinant estimator is a robust estimator of a data set’s covariance introduced by P.J. Rousseeuw in\(^3\). The idea is to find a given proportion (h) of “good” observations which are not outliers and compute their empirical covariance matrix. This empirical covariance matrix is then rescaled to compensate the performed selection of observations (“consistency step”). Having computed the Minimum Covariance Determinant estimator, one can give weights to observations according to their Mahalanobis distance, leading to a reweighted estimate of the covariance matrix of the data set (“reweighting step”).

Rousseeuw and Van Driessen\(^4\) developed the FastMCD algorithm in order to compute the Minimum Covariance Determinant. This algorithm is used in scikit-learn when fitting an MCD object to data. The FastMCD algorithm also computes a robust estimate of the data set location at the same time.

Raw estimates can be accessed as raw_location_ and raw_covariance_ attributes of a MinCovDet robust covariance estimator object.

References:

Examples:

- See Robust vs Empirical covariance estimate for an example on how to fit a MinCovDet object to data and see how the estimate remains accurate despite the presence of outliers.
- See Robust covariance estimation and Mahalanobis distances relevance to visualize the difference between EmpiricalCovariance and MinCovDet covariance estimators in terms of Mahalanobis distance (so we get a better estimate of the precision matrix too).

---


\(^4\) A Fast Algorithm for the Minimum Covariance Determinant Estimator, 1999, American Statistical Association and the American Society for Quality, TECHNOMETRICS.
Influence of outliers on location and covariance estimates

Separating inliers from outliers using a Mahalanobis distance

4.2.7 Novelty and Outlier Detection

Many applications require being able to decide whether a new observation belongs to the same distribution as existing observations (it is an inlier), or should be considered as different (it is an outlier). Often, this ability is used to clean real data sets. Two important distinctions must be made:

**outlier detection** The training data contains outliers which are defined as observations that are far from the others. Outlier detection estimators thus try to fit the regions where the training data is the most concentrated, ignoring the deviant observations.

**novelty detection** The training data is not polluted by outliers and we are interested in detecting whether a new observation is an outlier. In this context an outlier is also called a novelty.

Outlier detection and novelty detection are both used for anomaly detection, where one is interested in detecting abnormal or unusual observations. Outlier detection is then also known as unsupervised anomaly detection and novelty detection as semi-supervised anomaly detection. In the context of outlier detection, the outliers/anomalies cannot form a dense cluster as available estimators assume that the outliers/anomalies are located in low density regions. On the contrary, in the context of novelty detection, novelties/anomalies can form a dense cluster as long as they are in a low density region of the training data, considered as normal in this context.

The scikit-learn project provides a set of machine learning tools that can be used both for novelty or outlier detection. This strategy is implemented with objects learning in an unsupervised way from the data:

```python
estimator.fit(X_train)
```

new observations can then be sorted as inliers or outliers with a predict method:

```python
estimator.predict(X_test)
```

Inliers are labeled 1, while outliers are labeled -1. The predict method makes use of a threshold on the raw scoring function computed by the estimator. This scoring function is accessible through the score_samples method, while the threshold can be controlled by the contamination parameter.

The decision_function method is also defined from the scoring function, in such a way that negative values are outliers and non-negative ones are inliers:

```python
estimator.decision_function(X_test)
```

Note that neighbors.LocalOutlierFactor does not support predict, decision_function and score_samples methods by default but only a fit_predict method, as this estimator was originally meant...
to be applied for outlier detection. The scores of abnormality of the training samples are accessible through the `negative_outlier_factor_` attribute.

If you really want to use `neighbors.LocalOutlierFactor` for novelty detection, i.e. predict labels or compute the score of abnormality of new unseen data, you can instantiate the estimator with the `novelty` parameter set to `True` before fitting the estimator. In this case, `fit_predict` is not available.

**Warning: Novelty detection with Local Outlier Factor**

When `novelty` is set to `True` be aware that you must only use `predict`, `decision_function` and `score_samples` on new unseen data and not on the training samples as this would lead to wrong results. The scores of abnormality of the training samples are always accessible through the `negative_outlier_factor_` attribute.

The behavior of `neighbors.LocalOutlierFactor` is summarized in the following table.

<table>
<thead>
<tr>
<th>Method</th>
<th>Outlier detection</th>
<th>Novelty detection</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>fit_predict</code></td>
<td>OK</td>
<td>Not available</td>
</tr>
<tr>
<td><code>predict</code></td>
<td>Not available</td>
<td>Use only on new data</td>
</tr>
<tr>
<td><code>decision_function</code></td>
<td>Not available</td>
<td>Use only on new data</td>
</tr>
<tr>
<td><code>score_samples</code></td>
<td>Use <code>negative_outlier_factor_</code></td>
<td>Use only on new data</td>
</tr>
</tbody>
</table>

**Overview of outlier detection methods**

A comparison of the outlier detection algorithms in scikit-learn. Local Outlier Factor (LOF) does not show a decision boundary in black as it has no predict method to be applied on new data when it is used for outlier detection.

`ensemble.IsolationForest` and `neighbors.LocalOutlierFactor` perform reasonably well on the data sets considered here. The `svm.OneClassSVM` is known to be sensitive to outliers and thus does not perform very well for outlier detection. That being said, outlier detection in high-dimension, or without any assumptions on the distribution of the inlying data is very challenging. `svm.OneClassSVM` may still be used with outlier detection but requires fine-tuning of its hyperparameter `nu` to handle outliers and prevent overfitting. Finally, `covariance.EllipticEnvelope` assumes the data is Gaussian and learns an ellipse. For more details on the different estimators refer to the example `Comparing anomaly detection algorithms for outlier detection on toy datasets` and the sections hereunder.

**Examples:**

- See `Comparing anomaly detection algorithms for outlier detection on toy datasets` for a comparison of the `svm.OneClassSVM`, the `ensemble.IsolationForest`, the `neighbors.LocalOutlierFactor` and `covariance.EllipticEnvelope`. 
4.2. Unsupervised learning
Novelty Detection

Consider a data set of $n$ observations from the same distribution described by $p$ features. Consider now that we add one more observation to that data set. Is the new observation so different from the others that we can doubt it is regular? (i.e. does it come from the same distribution?) Or on the contrary, is it so similar to the other that we cannot distinguish it from the original observations? This is the question addressed by the novelty detection tools and methods.

In general, it is about to learn a rough, close frontier delimiting the contour of the initial observations distribution, plotted in embedding $p$-dimensional space. Then, if further observations lay within the frontier-delimited subspace, they are considered as coming from the same population than the initial observations. Otherwise, if they lay outside the frontier, we can say that they are abnormal with a given confidence in our assessment.

The One-Class SVM has been introduced by Schölkopf et al. for that purpose and implemented in the Support Vector Machines module in the `svm.OneClassSVM` object. It requires the choice of a kernel and a scalar parameter to define a frontier. The RBF kernel is usually chosen although there exists no exact formula or algorithm to set its bandwidth parameter. This is the default in the scikit-learn implementation. The $\nu$ parameter, also known as the margin of the One-Class SVM, corresponds to the probability of finding a new, but regular, observation outside the frontier.

**References:**


**Examples:**

- See One-class SVM with non-linear kernel (RBF) for visualizing the frontier learned around some data by a `svm.OneClassSVM` object.
- Species distribution modeling
Outlier Detection

Outlier detection is similar to novelty detection in the sense that the goal is to separate a core of regular observations from some polluting ones, called outliers. Yet, in the case of outlier detection, we don’t have a clean data set representing the population of regular observations that can be used to train any tool.

Fitting an elliptic envelope

One common way of performing outlier detection is to assume that the regular data come from a known distribution (e.g. data are Gaussian distributed). From this assumption, we generally try to define the “shape” of the data, and can define outlying observations as observations which stand far enough from the fit shape.

The scikit-learn provides an object `covariance.EllipticEnvelope` that fits a robust covariance estimate to the data, and thus fits an ellipse to the central data points, ignoring points outside the central mode.

For instance, assuming that the inlier data are Gaussian distributed, it will estimate the inlier location and covariance in a robust way (i.e. without being influenced by outliers). The Mahalanobis distances obtained from this estimate is used to derive a measure of outlyingness. This strategy is illustrated below.

Examples:

- See `Robust covariance estimation and Mahalanobis distances relevance` for an illustration of the difference between using a standard (`covariance.EmpiricalCovariance`) or a robust estimate (`covariance.MinCovDet`) of location and covariance to assess the degree of outlyingness of an observation.

References:

Isolation Forest

One efficient way of performing outlier detection in high-dimensional datasets is to use random forests. The `ensemble.IsolationForest` isolates observations by randomly selecting a feature and then randomly selecting a split value between the maximum and minimum values of the selected feature.

Since recursive partitioning can be represented by a tree structure, the number of splittings required to isolate a sample is equivalent to the path length from the root node to the terminating node.

This path length, averaged over a forest of such random trees, is a measure of normality and our decision function.

Random partitioning produces noticeably shorter paths for anomalies. Hence, when a forest of random trees collectively produce shorter path lengths for particular samples, they are highly likely to be anomalies.

The implementation of `ensemble.IsolationForest` is based on an ensemble of `tree.ExtraTreeRegressor`. Following Isolation Forest original paper, the maximum depth of each tree is set to $\lceil \log_2(n) \rceil$ where $n$ is the number of samples used to build the tree (see (Liu et al., 2008) for more details).

This algorithm is illustrated below.

![IsolationForest](image)

The `ensemble.IsolationForest` supports `warm_start=True` which allows you to add more trees to an already fitted model:

```python
>>> from sklearn.ensemble import IsolationForest
>>> import numpy as np
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [0, 0], [-20, 50], [3, 5]])
>>> clf = IsolationForest(n_estimators=10, warm_start=True)
>>> clf.fit(X)  # fit 10 trees
>>> clf.set_params(n_estimators=20)  # add 10 more trees
>>> clf.fit(X)  # fit the added trees
```
Examples:

- See *IsolationForest example* for an illustration of the use of IsolationForest.
- See *Comparing anomaly detection algorithms for outlier detection on toy datasets* for a comparison of `ensemble.IsolationForest` with `neighbors.LocalOutlierFactor`, `svm.OneClassSVM` (tuned to perform like an outlier detection method) and a covariance-based outlier detection with `covariance.EllipticEnvelope`.

References:


Local Outlier Factor

Another efficient way to perform outlier detection on moderately high dimensional datasets is to use the Local Outlier Factor (LOF) algorithm.

The `neighbors.LocalOutlierFactor` (LOF) algorithm computes a score (called local outlier factor) reflecting the degree of abnormality of the observations. It measures the local density deviation of a given data point with respect to its neighbors. The idea is to detect the samples that have a substantially lower density than their neighbors.

In practice the local density is obtained from the k-nearest neighbors. The LOF score of an observation is equal to the ratio of the average local density of his k-nearest neighbors, and its own local density: a normal instance is expected to have a local density similar to that of its neighbors, while abnormal data are expected to have much smaller local density.

The number k of neighbors considered, (alias parameter n_neighbors) is typically chosen 1) greater than the minimum number of objects a cluster has to contain, so that other objects can be local outliers relative to this cluster, and 2) smaller than the maximum number of close by objects that can potentially be local outliers. In practice, such informations are generally not available, and taking n_neighbors=20 appears to work well in general. When the proportion of outliers is high (i.e. greater than 10 %, as in the example below), n_neighbors should be greater (n_neighbors=35 in the example below).

The strength of the LOF algorithm is that it takes both local and global properties of datasets into consideration: it can perform well even in datasets where abnormal samples have different underlying densities. The question is not, how isolated the sample is, but how isolated it is with respect to the surrounding neighborhood.

When applying LOF for outlier detection, there are no `predict`, `decision_function` and `score_samples` methods but only a `fit_predict` method. The scores of abnormality of the training samples are accessible through the `negative_outlier_factor_` attribute. Note that `predict`, `decision_function` and `score_samples` can be used on new unseen data when LOF is applied for novelty detection, i.e. when the `novelty` parameter is set to `True`. See *Novelty detection with Local Outlier Factor*.

This strategy is illustrated below.

Examples:

- See *Outlier detection with Local Outlier Factor (LOF)* for an illustration of the use of `neighbors.LocalOutlierFactor`. 

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- See *Comparing anomaly detection algorithms for outlier detection on toy datasets* for a comparison with other anomaly detection methods.

**References:**


**Novelty detection with Local Outlier Factor**

To use `neighbors.LocalOutlierFactor` for novelty detection, i.e. predict labels or compute the score of abnormality of new unseen data, you need to instantiate the estimator with the `novelty` parameter set to `True` before fitting the estimator:

```python
lof = LocalOutlierFactor(novelty=True)
lof.fit(X_train)
```

Note that `fit_predict` is not available in this case.

**Warning: Novelty detection with Local Outlier Factor**

When `novelty` is set to `True` be aware that you must only use `predict`, `decision_function` and `score_samples` on new unseen data and not on the training samples as this would lead to wrong results. The scores of abnormality of the training samples are always accessible through the `negative_outlier_factor_` attribute.

Novelty detection with Local Outlier Factor is illustrated below.
4.2.8 Density Estimation

Density estimation walks the line between unsupervised learning, feature engineering, and data modeling. Some of the most popular and useful density estimation techniques are mixture models such as Gaussian Mixtures (`GaussianMixture`), and neighbor-based approaches such as the kernel density estimate (`KernelDensity`). Gaussian Mixtures are discussed more fully in the context of clustering, because the technique is also useful as an unsupervised clustering scheme.

Density estimation is a very simple concept, and most people are already familiar with one common density estimation technique: the histogram.

**Density Estimation: Histograms**

A histogram is a simple visualization of data where bins are defined, and the number of data points within each bin is tallied. An example of a histogram can be seen in the upper-left panel of the following figure:
A major problem with histograms, however, is that the choice of binning can have a disproportionate effect on the resulting visualization. Consider the upper-right panel of the above figure. It shows a histogram over the same data, with the bins shifted right. The results of the two visualizations look entirely different, and might lead to different interpretations of the data.

Intuitively, one can also think of a histogram as a stack of blocks, one block per point. By stacking the blocks in the appropriate grid space, we recover the histogram. But what if, instead of stacking the blocks on a regular grid, we center each block on the point it represents, and sum the total height at each location? This idea leads to the lower-left visualization. It is perhaps not as clean as a histogram, but the fact that the data drive the block locations mean that it is a much better representation of the underlying data.

This visualization is an example of a kernel density estimation, in this case with a top-hat kernel (i.e. a square block at each point). We can recover a smoother distribution by using a smoother kernel. The bottom-right plot shows a Gaussian kernel density estimate, in which each point contributes a Gaussian curve to the total. The result is a smooth density estimate which is derived from the data, and functions as a powerful non-parametric model of the distribution of points.

**Kernel Density Estimation**

Kernel density estimation in scikit-learn is implemented in the `KernelDensity` estimator, which uses the Ball Tree or KD Tree for efficient queries (see Nearest Neighbors for a discussion of these). Though the above example uses a 1D data set for simplicity, kernel density estimation can be performed in any number of dimensions, though in practice the curse of dimensionality causes its performance to degrade in high dimensions.

In the following figure, 100 points are drawn from a bimodal distribution, and the kernel density estimates are shown for three choices of kernels:
It’s clear how the kernel shape affects the smoothness of the resulting distribution. The scikit-learn kernel density estimator can be used as follows:

```python
>>> from sklearn.neighbors import KernelDensity
>>> import numpy as np

>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])

>>> kde = KernelDensity(kernel='gaussian', bandwidth=0.2).fit(X)

>>> kde.score_samples(X)
array([-0.41075698, -0.41075698, -0.41076071, -0.41075698, -0.41075698,
       -0.41076071])
```

Here we have used `kernel='gaussian'`, as seen above. Mathematically, a kernel is a positive function $K(x; h)$ which is controlled by the bandwidth parameter $h$. Given this kernel form, the density estimate at a point $y$ within a group of points $x_i; i = 1 \cdots N$ is given by:

$$
\rho_K(y) = \sum_{i=1}^{N} K(y - x_i; h)
$$

The bandwidth here acts as a smoothing parameter, controlling the tradeoff between bias and variance in the result. A large bandwidth leads to a very smooth (i.e. high-bias) density distribution. A small bandwidth leads to an unsmooth (i.e. high-variance) density distribution.

`KernelDensity` implements several common kernel forms, which are shown in the following figure:
The form of these kernels is as follows:

- **Gaussian kernel** (kernel = 'gaussian')
  \[ K(x; h) \propto \exp\left(-\frac{x^2}{2h^2}\right) \]
- **Tophat kernel** (kernel = 'tophat')
  \[ K(x; h) \propto 1 \text{ if } x < h \]
- **Epanechnikov kernel** (kernel = 'epanechnikov')
  \[ K(x; h) \propto 1 - \frac{x^2}{h^2} \]
- **Exponential kernel** (kernel = 'exponential')
  \[ K(x; h) \propto \exp\left(-\frac{x}{h}\right) \]
- **Linear kernel** (kernel = 'linear')
  \[ K(x; h) \propto 1 - \frac{x}{h} \text{ if } x < h \]
- **Cosine kernel** (kernel = 'cosine')
  \[ K(x; h) \propto \cos\left(\frac{\pi x}{2h}\right) \text{ if } x < h \]

The kernel density estimator can be used with any of the valid distance metrics (see DistanceMetric for a list of available metrics), though the results are properly normalized only for the Euclidean metric. One particularly useful metric is the Haversine distance which measures the angular distance between points on a sphere. Here is an example of using a kernel density estimate for a visualization of geospatial data, in this case the distribution of observations of two different species on the South American continent:
One other useful application of kernel density estimation is to learn a non-parametric generative model of a dataset in order to efficiently draw new samples from this generative model. Here is an example of using this process to create a new set of hand-written digits, using a Gaussian kernel learned on a PCA projection of the data:

The “new” data consists of linear combinations of the input data, with weights probabilistically drawn given the KDE model.
**Examples:**

- *Simple 1D Kernel Density Estimation*: computation of simple kernel density estimates in one dimension.
- *Kernel Density Estimation*: an example of using Kernel Density estimation to learn a generative model of the hand-written digits data, and drawing new samples from this model.
- *Kernel Density Estimate of Species Distributions*: an example of Kernel Density estimation using the Haversine distance metric to visualize geospatial data

### 4.2.9 Neural network models (unsupervised)

#### Restricted Boltzmann machines

Restricted Boltzmann machines (RBM) are unsupervised nonlinear feature learners based on a probabilistic model. The features extracted by an RBM or a hierarchy of RBMs often give good results when fed into a linear classifier such as a linear SVM or a perceptron.

The model makes assumptions regarding the distribution of inputs. At the moment, scikit-learn only provides `BernoulliRBM`, which assumes the inputs are either binary values or values between 0 and 1, each encoding the probability that the specific feature would be turned on.

The RBM tries to maximize the likelihood of the data using a particular graphical model. The parameter learning algorithm used (*Stochastic Maximum Likelihood*) prevents the representations from straying far from the input data, which makes them capture interesting regularities, but makes the model less useful for small datasets, and usually not useful for density estimation.

The method gained popularity for initializing deep neural networks with the weights of independent RBMs. This method is known as unsupervised pre-training.

**Examples:**

- *Restricted Boltzmann Machine features for digit classification*
Graphical model and parametrization

The graphical model of an RBM is a fully-connected bipartite graph.

The nodes are random variables whose states depend on the state of the other nodes they are connected to. The model is therefore parameterized by the weights of the connections, as well as one intercept (bias) term for each visible and hidden unit, omitted from the image for simplicity.
The energy function measures the quality of a joint assignment:

$$E(v, h) = -\sum_i \sum_j w_{ij} v_i h_j - \sum_i b_i v_i - \sum_j c_j h_j$$

In the formula above, \(b\) and \(c\) are the intercept vectors for the visible and hidden layers, respectively. The joint probability of the model is defined in terms of the energy:

$$P(v, h) = \frac{e^{-E(v, h)}}{Z}$$

The word \textit{restricted} refers to the bipartite structure of the model, which prohibits direct interaction between hidden units, or between visible units. This means that the following conditional independencies are assumed:

\[h_i \perp h_j | v\]

\[v_i \perp v_j | h\]

The bipartite structure allows for the use of efficient block Gibbs sampling for inference.

**Bernoulli Restricted Boltzmann machines**

In the \textit{BernoulliRBM}, all units are binary stochastic units. This means that the input data should either be binary, or real-valued between 0 and 1 signifying the probability that the visible unit would turn on or off. This is a good model for character recognition, where the interest is on which pixels are active and which aren’t. For images of natural scenes it no longer fits because of background, depth and the tendency of neighbouring pixels to take the same values.

The conditional probability distribution of each unit is given by the logistic sigmoid activation function of the input it receives:

$$P(v_i = 1 | h) = \sigma(\sum_j w_{ij} h_j + b_i)$$

$$P(h_i = 1 | v) = \sigma(\sum_i w_{ij} v_i + c_j)$$

where \(\sigma\) is the logistic sigmoid function:

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

**Stochastic Maximum Likelihood learning**

The training algorithm implemented in \textit{BernoulliRBM} is known as Stochastic Maximum Likelihood (SML) or Persistent Contrastive Divergence (PCD). Optimizing maximum likelihood directly is infeasible because of the form of the data likelihood:

$$\log P(v) = \log \sum_h e^{-E(v, h)} - \log \sum_{x,y} e^{-E(x,y)}$$

For simplicity the equation above is written for a single training example. The gradient with respect to the weights is formed of two terms corresponding to the ones above. They are usually known as the positive gradient and the negative gradient, because of their respective signs. In this implementation, the gradients are estimated over mini-batches of samples.

In maximizing the log-likelihood, the positive gradient makes the model prefer hidden states that are compatible with the observed training data. Because of the bipartite structure of RBMs, it can be computed efficiently. The negative gradient, however, is intractable. Its goal is to lower the energy of joint states that the model prefers, therefore making
it stay true to the data. It can be approximated by Markov chain Monte Carlo using block Gibbs sampling by iteratively
sampling each of \( v \) and \( h \) given the other, until the chain mixes. Samples generated in this way are sometimes referred
as fantasy particles. This is inefficient and it is difficult to determine whether the Markov chain mixes.

The Contrastive Divergence method suggests to stop the chain after a small number of iterations, \( k \), usually even 1.
This method is fast and has low variance, but the samples are far from the model distribution.

Persistent Contrastive Divergence addresses this. Instead of starting a new chain each time the gradient is needed, and
performing only one Gibbs sampling step, in PCD we keep a number of chains (fantasy particles) that are updated \( k \)
Gibbs steps after each weight update. This allows the particles to explore the space more thoroughly.

**References:**

- “Training Restricted Boltzmann Machines using Approximations to the Likelihood Gradient” T. Tieleman, 2008

### 4.3 Model selection and evaluation

#### 4.3.1 Cross-validation: evaluating estimator performance

Learning the parameters of a prediction function and testing it on the same data is a methodological mistake: a model
that would just repeat the labels of the samples that it has just seen would have a perfect score but would fail to predict
anything useful on yet-unseen data. This situation is called **overfitting**. To avoid it, it is common practice when
performing a (supervised) machine learning experiment to hold out part of the available data as a test set \( X_{\text{test}}, y_{\text{test}} \).
Note that the word “experiment” is not intended to denote academic use only, because even in commercial
settings machine learning usually starts out experimentally. Here is a flowchart of typical cross validation workflow in
model training. The best parameters can be determined by grid search techniques.

![Flowchart of cross-validation workflow](image)

In scikit-learn a random split into training and test sets can be quickly computed with the `train_test_split`
helper function. Let’s load the iris data set to fit a linear support vector machine on it:

```python
>>> import numpy as np
>>> from sklearn.model_selection import train_test_split
>>> from sklearn import datasets
>>> from sklearn import svm
(continues on next page)```
We can now quickly sample a training set while holding out 40% of the data for testing (evaluating) our classifier:

```python
>>> X_train, X_test, y_train, y_test = train_test_split(
...     X, y, test_size=0.4, random_state=0)
>>> X_train.shape, y_train.shape
((90, 4), (90,))
>>> X_test.shape, y_test.shape
((60, 4), (60,))
>>> clf = svm.SVC(kernel='linear', C=1).fit(X_train, y_train)
>>> clf.score(X_test, y_test)
0.96...
```

When evaluating different settings ("hyperparameters") for estimators, such as the C setting that must be manually set for an SVM, there is still a risk of overfitting on the test set because the parameters can be tweaked until the estimator performs optimally. This way, knowledge about the test set can "leak" into the model and evaluation metrics no longer report on generalization performance. To solve this problem, yet another part of the dataset can be held out as a so-called "validation set": training proceeds on the training set, after which evaluation is done on the validation set, and when the experiment seems to be successful, final evaluation can be done on the test set. However, by partitioning the available data into three sets, we drastically reduce the number of samples which can be used for learning the model, and the results can depend on a particular random choice for the pair of (train, validation) sets.

A solution to this problem is a procedure called cross-validation (CV for short). A test set should still be held out for final evaluation, but the validation set is no longer needed when doing CV. In the basic approach, called k-fold CV, the training set is split into k smaller sets (other approaches are described below, but generally follow the same principles). The following procedure is followed for each of the k "folds":

- A model is trained using k − 1 of the folds as training data;
- the resulting model is validated on the remaining part of the data (i.e., it is used as a test set to compute a performance measure such as accuracy).

The performance measure reported by k-fold cross-validation is then the average of the values computed in the loop. This approach can be computationally expensive, but does not waste too much data (as is the case when fixing an arbitrary validation set), which is a major advantage in problems such as inverse inference where the number of samples is very small.
Computing cross-validated metrics

The simplest way to use cross-validation is to call the `cross_val_score` helper function on the estimator and the dataset.

The following example demonstrates how to estimate the accuracy of a linear kernel support vector machine on the iris dataset by splitting the data, fitting a model and computing the score 5 consecutive times (with different splits each time):

```python
>>> from sklearn.model_selection import cross_val_score
>>> clf = svm.SVC(kernel='linear', C=1, random_state=42)
>>> scores = cross_val_score(clf, X, y, cv=5)
>>> scores
array([0.96..., 1. , 0.96..., 0.96..., 1. ])  
```

The mean score and the standard deviation are hence given by:

```python
>>> print("%0.2f accuracy with a standard deviation of %0.2f" % (scores.mean(),
... scores.std()))
0.98 accuracy with a standard deviation of 0.02
```

By default, the score computed at each CV iteration is the `score` method of the estimator. It is possible to change this by using the scoring parameter:

```python
>>> from sklearn import metrics
>>> scores = cross_val_score(... clf, X, y, cv=5, scoring='f1_macro')
>>> scores
array([0.96..., 1. ..., 0.96..., 0.96..., 1. ])  
```

See *The scoring parameter: defining model evaluation rules* for details. In the case of the Iris dataset, the samples are balanced across target classes hence the accuracy and the F1-score are almost equal.

When the `cv` argument is an integer, `cross_val_score` uses the `KFold` or `StratifiedKFold` strategies by default, the latter being used if the estimator derives from `ClassifierMixin`.

It is also possible to use other cross validation strategies by passing a cross validation iterator instead, for instance:

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Another option is to use an iterable yielding (train, test) splits as arrays of indices, for example:

```python
>>> def custom_cv_2folds(X):
...     n = X.shape[0]
...     i = 1
...     while i <= 2:
...         idx = np.arange(n * (i - 1) / 2, n * i / 2, dtype=int)
...         yield idx, idx
...         i += 1
... >>>

>>> custom_cv = custom_cv_2folds(X)
>>> cross_val_score(clf, X, y, cv=custom_cv)
array([1. , 0.973...])
```

### Data transformation with held out data

Just as it is important to test a predictor on data held-out from training, preprocessing (such as standardization, feature selection, etc.) and similar data transformations similarly should be learnt from a training set and applied to held-out data for prediction:

```python
>>> from sklearn import preprocessing

>>> X_train, X_test, y_train, y_test = train_test_split(  
...     X, y, test_size=0.4, random_state=0)
>>> scaler = preprocessing.StandardScaler().fit(X_train)
>>> X_train_transformed = scaler.transform(X_train)
>>> clf = svm.SVC(C=1).fit(X_train_transformed, y_train)
>>> X_test_transformed = scaler.transform(X_test)
>>> clf.score(X_test_transformed, y_test)
0.9333...
```

A **Pipeline** makes it easier to compose estimators, providing this behavior under cross-validation:

```python
>>> from sklearn.pipeline import make_pipeline

>>> clf = make_pipeline(preprocessing.StandardScaler(), svm.SVC(C=1))
>>> cross_val_score(clf, X, y, cv=cv)
array([0.977..., 0.933..., 0.955..., 0.933..., 0.977...])
```

See **Pipelines and composite estimators**.

### The cross_validate function and multiple metric evaluation

The **cross_validate** function differs from **cross_val_score** in two ways:

- It allows specifying multiple metrics for evaluation.
- It returns a dict containing fit-times, score-times (and optionally training scores as well as fitted estimators) in addition to the test score.

For single metric evaluation, where the scoring parameter is a string, callable or None, the keys will be:

- ['test_score', 'fit_time', 'score_time']
And for multiple metric evaluation, the return value is a dict with the following keys:
['test_<scorer1_name>', 'test_<scorer2_name>', 'test_<scorer3...>', 'fit_time', 'score_time']

return_train_score is set to False by default to save computation time. To evaluate the scores on the training set as well you need to be set to True.

You may also retain the estimator fitted on each training set by setting return_estimator=True.

The multiple metrics can be specified either as a list, tuple or set of predefined scorer names:

```python
>>> from sklearn.model_selection import cross_validate
>>> scoring = ['precision_macro', 'recall_macro']
>>> scores = cross_validate(svc, X, y, scoring=scoring)
>>> sorted(scores.keys())
['fit_time', 'score_time', 'test_precision_macro', 'test_recall_macro']
>>> scores['test_recall_macro']
array([0.96..., 1., 0.96..., 0.96..., 1.])
```

Or as a dict mapping scorer name to a predefined or custom scoring function:

```python
>>> scoring = {'prec_macro': 'precision_macro',
...              'rec_macro': make_scorer(recall_score, average='macro')}
>>> scores = cross_validate(svc, X, y, scoring=scoring,
...                          cv=5, return_train_score=True)
>>> sorted(scores.keys())
['fit_time', 'score_time', 'test_prec_macro', 'test_rec_macro',
 'train_prec_macro', 'train_rec_macro']
>>> scores['train_rec_macro']
array([0.97..., 0.97..., 0.99..., 0.98..., 0.98...])
```

Here is an example of cross_validate using a single metric:

```python
>>> scoring = 'precision_macro', cv=5,
... return_estimator=True)
>>> sorted(scores.keys())
['estimator', 'fit_time', 'score_time', 'test_score']
```

Obtaining predictions by cross-validation

The function cross_val_predict has a similar interface to cross_val_score, but returns, for each element in the input, the prediction that was obtained for that element when it was in the test set. Only cross-validation strategies that assign all elements to a test set exactly once can be used (otherwise, an exception is raised).

**Warning:** Note on inappropriate usage of cross_val_predict

The result of cross_val_predict may be different from those obtained using cross_val_score as the elements are grouped in different ways. The function cross_val_score takes an average over cross-validation folds, whereas cross_val_predict simply returns the labels (or probabilities) from several distinct models undistinguished. Thus, cross_val_predict is not an appropriate measure of generalisation error.

The function cross_val_predict is appropriate for:
• Visualization of predictions obtained from different models.
• Model blending: When predictions of one supervised estimator are used to train another estimator in ensemble methods.

The available cross validation iterators are introduced in the following section.

Examples

• Receiver Operating Characteristic (ROC) with cross validation,
• Recursive feature elimination with cross-validation,
• Parameter estimation using grid search with cross-validation,
• Sample pipeline for text feature extraction and evaluation,
• Plotting Cross-Validated Predictions,
• Nested versus non-nested cross-validation.

Cross validation iterators

The following sections list utilities to generate indices that can be used to generate dataset splits according to different cross validation strategies.

Cross-validation iterators for i.i.d. data

Assuming that some data is Independent and Identically Distributed (i.i.d.) is making the assumption that all samples stem from the same generative process and that the generative process is assumed to have no memory of past generated samples.

The following cross-validators can be used in such cases.

Note: While i.i.d. data is a common assumption in machine learning theory, it rarely holds in practice. If one knows that the samples have been generated using a time-dependent process, it is safer to use a time-series aware cross-validation scheme. Similarly, if we know that the generative process has a group structure (samples collected from different subjects, experiments, measurement devices), it is safer to use group-wise cross-validation.

K-fold

$K$-fold divides all the samples in $k$ groups of samples, called folds (if $k = n$, this is equivalent to the Leave One Out strategy), of equal sizes (if possible). The prediction function is learned using $k - 1$ folds, and the fold left out is used for test.

Example of 2-fold cross-validation on a dataset with 4 samples:

```python
>>> import numpy as np
>>> from sklearn.model_selection import KFold

>>> X = ["a", "b", "c", "d"]
>>> kf = KFold(n_splits=2)
>>> for train, test in kf.split(X):

(continues on next page)```
Here is a visualization of the cross-validation behavior. Note that KFold is not affected by classes or groups.

![Kfold visualization](image)

Each fold is constituted by two arrays: the first one is related to the training set, and the second one to the test set. Thus, one can create the training/test sets using numpy indexing:

```python
>>> X = np.array([[0., 0.], [1., 1.], [-1., -1.], [2., 2.]])
>>> y = np.array([0, 1, 0, 1])
>>> X_train, X_test, y_train, y_test = X[train], X[test], y[train], y[test]
```

### Repeated K-Fold

RepeatedKFold repeats K-Fold n times. It can be used when one requires to run KFold n times, producing different splits in each repetition.

Example of 2-fold K-Fold repeated 2 times:

```python
>>> import numpy as np
>>> from sklearn.model_selection import RepeatedKFold
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> random_state = 12883823
>>> rkf = RepeatedKFold(n_splits=2, n_repeats=2, random_state=random_state)
>>> for train, test in rkf.split(X):
...     print("%s %s" % (train, test))
...
[2 3] [0 1]
[0 1] [2 3]
[0 2] [1 3]
[1 3] [0 2]
```

Similarly, RepeatedStratifiedKFold repeats Stratified K-Fold n times with different randomization in each repetition.
Leave One Out (LOO)

LeaveOneOut (or LOO) is a simple cross-validation. Each learning set is created by taking all the samples except one, the test set being the sample left out. Thus, for \( n \) samples, we have \( n \) different training sets and \( n \) different test sets. This cross-validation procedure does not waste much data as only one sample is removed from the training set:

```python
>>> from sklearn.model_selection import LeaveOneOut
>>> X = [1, 2, 3, 4]
>>> loo = LeaveOneOut()
>>> for train, test in loo.split(X):
...     print("%s %s" % (train, test))
[1 2 3] [0]
[0 2 3] [1]
[0 1 3] [2]
[0 1 2] [3]
```

Potential users of LOO for model selection should weigh a few known caveats. When compared with \( k \)-fold cross validation, one builds \( n \) models from \( n \) samples instead of \( k \) models, where \( n > k \). Moreover, each is trained on \( n - 1 \) samples rather than \((k - 1)n/k\). In both ways, assuming \( k \) is not too large and \( k < n \), LOO is more computationally expensive than \( k \)-fold cross validation.

In terms of accuracy, LOO often results in high variance as an estimator for the test error. Intuitively, since \( n - 1 \) of the \( n \) samples are used to build each model, models constructed from folds are virtually identical to each other and to the model built from the entire training set.

However, if the learning curve is steep for the training size in question, then \( 5 \) - or \( 10 \)-fold cross validation can overestimate the generalization error.

As a general rule, most authors, and empirical evidence, suggest that \( 5 \)- or \( 10 \)-fold cross validation should be preferred to LOO.

References:

- R. Kohavi, A Study of Cross-Validation and Bootstrap for Accuracy Estimation and Model Selection, Intl. Jnt. Conf. AI
- G. James, D. Witten, T. Hastie, R Tibshirani, An Introduction to Statistical Learning, Springer 2013.
Leave P Out (LPO)

LeavePOut is very similar to LeaveOneOut as it creates all the possible training/test sets by removing $p$ samples from the complete set. For $n$ samples, this produces $\binom{n}{p}$ train-test pairs. Unlike LeaveOneOut and KFold, the test sets will overlap for $p > 1$.

Example of Leave-2-Out on a dataset with 4 samples:

```python
>>> from sklearn.model_selection import LeavePOut
>>> X = np.ones(4)
>>> lpo = LeavePOut(p=2)
>>> for train, test in lpo.split(X):
...     print("%s %s" % (train, test))
[2 3] [0 1]
[1 3] [0 2]
[1 2] [0 3]
[0 3] [1 2]
[0 2] [1 3]
[0 1] [2 3]
```

Random permutations cross-validation a.k.a. Shuffle & Split

The ShuffleSplit iterator will generate a user defined number of independent train / test dataset splits. Samples are first shuffled and then split into a pair of train and test sets.

It is possible to control the randomness for reproducibility of the results by explicitly seeding the random_state pseudo random number generator.

Here is a usage example:

```python
>>> from sklearn.model_selection import ShuffleSplit
>>> X = np.arange(10)
>>> ss = ShuffleSplit(n_splits=5, test_size=0.25, random_state=0)
>>> for train_index, test_index in ss.split(X):
...     print("%s %s" % (train_index, test_index))
[9 1 6 7 3 0 5] [2 8 4]
[2 9 8 0 6 7 4] [3 5 1]
[4 5 1 0 6 9 7] [2 3 8]
[2 7 5 8 0 3 4] [6 1 9]
[4 1 0 6 8 9 3] [5 2 7]
```

Here is a visualization of the cross-validation behavior. Note that ShuffleSplit is not affected by classes or groups.

ShuffleSplit is thus a good alternative to KFold cross validation that allows a finer control on the number of iterations and the proportion of samples on each side of the train / test split.
Cross-validation iterators with stratification based on class labels.

Some classification problems can exhibit a large imbalance in the distribution of the target classes: for instance there could be several times more negative samples than positive samples. In such cases it is recommended to use stratified sampling as implemented in \texttt{StratifiedKFold} and \texttt{StratifiedShuffleSplit} to ensure that relative class frequencies is approximately preserved in each train and validation fold.

\textbf{Stratified k-fold}

\texttt{StratifiedKFold} is a variation of \textit{k-fold} which returns \textit{stratified} folds: each set contains approximately the same percentage of samples of each target class as the complete set.

Here is an example of stratified 3-fold cross-validation on a dataset with 50 samples from two unbalanced classes. We show the number of samples in each class and compare with \texttt{KFold}.

```python
>>> from sklearn.model_selection import StratifiedKFold, KFold
>>> import numpy as np

>>> X, y = np.ones((50, 1)), np.hstack((np.zeros(45), [1] * 5))

>>> skf = StratifiedKFold(n_splits=3)
>>> for train, test in skf.split(X, y):
...    print('train - {} | test - {}'.format(
...        np.bincount(y[train]), np.bincount(y[test])))
train - [30 3] | test - [15 2]
train - [30 3] | test - [15 2]
train - [30 4] | test - [15 1]
```

```python
>>> kf = KFold(n_splits=3)
>>> for train, test in kf.split(X, y):
...    print('train - {} | test - {}'.format(
...        np.bincount(y[train]), np.bincount(y[test])))
train - [28 5] | test - [17]
train - [28 5] | test - [17]
train - [34] | test - [11 5]
```

We can see that \texttt{StratifiedKFold} preserves the class ratios (approximately 1 / 10) in both train and test dataset.

Here is a visualization of the cross-validation behavior.

\texttt{RepeatedStratifiedKFold} can be used to repeat Stratified K-Fold \textit{n} times with different randomization in each repetition.

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Stratified Shuffle Split

`StratifiedShuffleSplit` is a variation of `ShuffleSplit`, which returns stratified splits, i.e. which creates splits by preserving the same percentage for each target class as in the complete set.

Here is a visualization of the cross-validation behavior.

Cross-validation iterators for grouped data.

The i.i.d. assumption is broken if the underlying generative process yield groups of dependent samples.

Such a grouping of data is domain specific. An example would be when there is medical data collected from multiple patients, with multiple samples taken from each patient. And such data is likely to be dependent on the individual group. In our example, the patient id for each sample will be its group identifier.

In this case we would like to know if a model trained on a particular set of groups generalizes well to the unseen groups. To measure this, we need to ensure that all the samples in the validation fold come from groups that are not represented at all in the paired training fold.

The following cross-validation splitters can be used to do that. The grouping identifier for the samples is specified via the `groups` parameter.
Group k-fold

GroupKFold is a variation of k-fold which ensures that the same group is not represented in both testing and training sets. For example if the data is obtained from different subjects with several samples per-subject and if the model is flexible enough to learn from highly person specific features it could fail to generalize to new subjects. GroupKFold makes it possible to detect this kind of overfitting situations.

Imagine you have three subjects, each with an associated number from 1 to 3:

```python
>>> from sklearn.model_selection import GroupKFold
>>> X = [0.1, 0.2, 2.2, 2.4, 2.3, 4.55, 5.8, 8.8, 9, 10]
>>> y = ["a", "b", "b", "b", "c", "c", "c", "d", "d", "d"]
>>> groups = [1, 1, 1, 2, 2, 2, 3, 3, 3, 3]

>>> gkf = GroupKFold(n_splits=3)
>>> for train, test in gkf.split(X, y, groups=groups):
...     print("%s %s") % (train, test))
[0 1 2 3 4 5] [6 7 8 9]
[0 1 2 6 7 8 9] [3 4 5]
[3 4 5 6 7 8 9] [0 1 2]
```

Each subject is in a different testing fold, and the same subject is never in both testing and training. Notice that the folds do not have exactly the same size due to the imbalance in the data.

Here is a visualization of the cross-validation behavior.

![GroupKFold visualization](image)

Leave One Group Out

LeaveOneGroupOut is a cross-validation scheme which holds out the samples according to a third-party provided array of integer groups. This group information can be used to encode arbitrary domain specific pre-defined cross-validation folds.

Each training set is thus constituted by all the samples except the ones related to a specific group.

For example, in the cases of multiple experiments, LeaveOneGroupOut can be used to create a cross-validation based on the different experiments: we create a training set using the samples of all the experiments except one:

```python
>>> from sklearn.model_selection import LeaveOneGroupOut
```
Another common application is to use time information: for instance the groups could be the year of collection of the samples and thus allow for cross-validation against time-based splits.

### Leave P Groups Out

_LeavePGroupsOut_ is similar as _LeaveOneGroupOut_, but removes samples related to _P_ groups for each training/test set.

#### Example of Leave-2-Group Out:

```python
>>> from sklearn.model_selection import LeavePGroupsOut
>>> X = np.arange(6)
>>> y = [1, 1, 1, 2, 2, 2]
>>> groups = [1, 1, 2, 2, 3, 3]
>>> lpgo = LeavePGroupsOut(n_groups=2)
>>> for train, test in lpgo.split(X, y, groups=groups):
...     print("%s %s" % (train, test))
[4 5] [0 1 2 3]
[2 3] [0 1 4 5]
[0 1] [2 3 4 5]
```

### Group Shuffle Split

The _GroupShuffleSplit_ iterator behaves as a combination of _ShuffleSplit_ and _LeavePGroupsOut_, and generates a sequence of randomized partitions in which a subset of groups are held out for each split.

Here is a usage example:

```python
>>> from sklearn.model_selection import GroupShuffleSplit
>>> X = [0.1, 0.2, 2.2, 2.4, 2.3, 4.55, 5.8, 0.001]
>>> y = ["a", "b", "b", "b", "c", "c", "c", "a"]
>>> groups = [1, 1, 2, 2, 3, 3, 4, 4]
>>> gss = GroupShuffleSplit(n_splits=4, test_size=0.5, random_state=0)
>>> for train, test in gss.split(X, y, groups=groups):
...     print("%s %s" % (train, test))
...[0 1 2 3] [4 5 6 7]
[2 3 4 5] [0 1 4 5]
[0 1 2 3] [4 5 6 7]
```

Here is a visualization of the cross-validation behavior.

---

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This class is useful when the behavior of `LeavePGroupsOut` is desired, but the number of groups is large enough that generating all possible partitions with \( P \) groups withheld would be prohibitively expensive. In such a scenario, `GroupShuffleSplit` provides a random sample (with replacement) of the train / test splits generated by `LeavePGroupsOut`.

### Predefined Fold-Splits / Validation-Sets

For some datasets, a pre-defined split of the data into training- and validation fold or into several cross-validation folds already exists. Using `PredefinedSplit` it is possible to use these folds e.g. when searching for hyperparameters.

For example, when using a validation set, set the `test_fold` to 0 for all samples that are part of the validation set, and to -1 for all other samples.

### Using cross-validation iterators to split train and test

The above group cross-validation functions may also be useful for spitting a dataset into training and testing subsets. Note that the convenience function `train_test_split` is a wrapper around `ShuffleSplit` and thus only allows for stratified splitting (using the class labels) and cannot account for groups.

To perform the train and test split, use the indices for the train and test subsets yielded by the generator output by the `split()` method of the cross-validation splitter. For example:

```python
>>> import numpy as np
>>> from sklearn.model_selection import GroupShuffleSplit

>>> X = np.array([0.1, 0.2, 2.2, 2.4, 2.3, 4.55, 5.8, 0.001])
>>> y = np.array(['a', 'b', 'b', 'b', 'c', 'c', 'c', 'a'])
>>> groups = np.array([1, 1, 2, 2, 3, 3, 4, 4])

>>> train_indx, test_indx = next(GroupShuffleSplit(random_state=7).split(X, y, groups))
>>> X_train, X_test, y_train, y_test = X[train_indx], X[test_indx], y[train_indx], y[test_indx]
>>> X_train.shape, X_test.shape
((6,), (2,))
>>> np.unique(groups[train_indx]), np.unique(groups[test_indx])
(array([1, 4], dtype=int64), array([2], dtype=int64))
```
Cross validation of time series data

Time series data is characterised by the correlation between observations that are near in time (autocorrelation). However, classical cross-validation techniques such as KFold and ShuffleSplit assume the samples are independent and identically distributed, and would result in unreasonable correlation between training and testing instances (yielding poor estimates of generalisation error) on time series data. Therefore, it is very important to evaluate our model for time series data on the “future” observations least like those that are used to train the model. To achieve this, one solution is provided by TimeSeriesSplit.

Time Series Split

TimeSeriesSplit is a variation of k-fold which returns first k folds as train set and the (k + 1) th fold as test set. Note that unlike standard cross-validation methods, successive training sets are supersets of those that come before them. Also, it adds all surplus data to the first training partition, which is always used to train the model.

This class can be used to cross-validate time series data samples that are observed at fixed time intervals.

Example of 3-split time series cross-validation on a dataset with 6 samples:

```python
>>> from sklearn.model_selection import TimeSeriesSplit

>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([1, 2, 3, 4, 5, 6])
>>> tscv = TimeSeriesSplit(n_splits=3)
>>> print(tscv)
```

```
TimeSeriesSplit(gap=0, max_train_size=None, n_splits=3, test_size=None)
```

```python
>>> for train, test in tscv.split(X):
...     print("%s %s" % (train, test))
[0 1 2] [3]
[0 1 2 3] [4]
[0 1 2 3 4] [5]
```

Here is a visualization of the cross-validation behavior.
A note on shuffling

If the data ordering is not arbitrary (e.g., samples with the same class label are contiguous), shuffling it first may be essential to get a meaningful cross-validation result. However, the opposite may be true if the samples are not independently and identically distributed. For example, if samples correspond to news articles, and are ordered by their time of publication, then shuffling the data will likely lead to a model that is overfit and an inflated validation score: it will be tested on samples that are artificially similar (close in time) to training samples.

Some cross validation iterators, such as KFold, have an inbuilt option to shuffle the data indices before splitting them. Note that:

- This consumes less memory than shuffling the data directly.
- By default no shuffling occurs, including for the (stratified) K fold cross-validation performed by specifying cv=some_integer to cross_val_score, grid search, etc. Keep in mind that train_test_split still returns a random split.
- The random_state parameter defaults to None, meaning that the shuffling will be different every time KFold(..., shuffle=True) is iterated. However, GridSearchCV will use the same shuffling for each set of parameters validated by a single call to its fit method.
- To get identical results for each split, set random_state to an integer.

For more details on how to control the randomness of cv splitters and avoid common pitfalls, see Controlling randomness.

Cross validation and model selection

Cross validation iterators can also be used to directly perform model selection using Grid Search for the optimal hyperparameters of the model. This is the topic of the next section: Tuning the hyper-parameters of an estimator.

Permutation test score

permutation_test_score offers another way to evaluate the performance of classifiers. It provides a permutation-based p-value, which represents how likely an observed performance of the classifier would be obtained by chance. The null hypothesis in this test is that the classifier fails to leverage any statistical dependency between the features and the labels to make correct predictions on left out data. permutation_test_score generates a null distribution by calculating n_permutations different permutations of the data. In each permutation the labels are randomly shuffled, thereby removing any dependency between the features and the labels. The p-value output is the fraction of permutations for which the average cross-validation score obtained by the model is better than the cross-validation score obtained by the model using the original data. For reliable results n_permutations should typically be larger than 100 and cv between 3-10 folds.

A low p-value provides evidence that the dataset contains real dependency between features and labels and the classifier was able to utilize this to obtain good results. A high p-value could be due to a lack of dependency between features and labels (there is no difference in feature values between the classes) or because the classifier was not able to use the dependency in the data. In the latter case, using a more appropriate classifier that is able to utilize the structure in the data, would result in a low p-value.

Cross-validation provides information about how well a classifier generalizes, specifically the range of expected errors of the classifier. However, a classifier trained on a high dimensional dataset with no structure may still perform better than expected on cross-validation, just by chance. This can typically happen with small datasets with less than a few hundred samples. permutation_test_score provides information on whether the classifier has found a real class structure and can help in evaluating the performance of the classifier.
It is important to note that this test has been shown to produce low p-values even if there is only weak structure in the data because in the corresponding permutated datasets there is absolutely no structure. This test is therefore only able to show when the model reliably outperforms random guessing.

Finally, **permutation_test_score** is computed using brute force and interally fits \((n_{\text{permutations}} + 1) \times n_{\text{cv}}\) models. It is therefore only tractable with small datasets for which fitting an individual model is very fast.

### Examples

- Test with permutations the significance of a classification score

### References:


## 4.3.2 Tuning the hyper-parameters of an estimator

Hyper-parameters are parameters that are not directly learnt within estimators. In scikit-learn they are passed as arguments to the constructor of the estimator classes. Typical examples include \(C\), \(kernel\) and \(gamma\) for Support Vector Classifier, \(alpha\) for Lasso, etc.

It is possible and recommended to search the hyper-parameter space for the best *cross validation* score.

Any parameter provided when constructing an estimator may be optimized in this manner. Specifically, to find the names and current values for all parameters for a given estimator, use:

```python
estimator.get_params()
```

A search consists of:

- an estimator (regressor or classifier such as `sklearn.svm.SVC()`);
- a parameter space;
- a method for searching or sampling candidates;
- a cross-validation scheme; and
- a score function.

Two generic approaches to parameter search are provided in scikit-learn: for given values, `GridSearchCV` exhaustively considers all parameter combinations, while `RandomizedSearchCV` can sample a given number of candidates from a parameter space with a specified distribution. Both these tools have successive halving counterparts `HalvingGridSearchCV` and `HalvingRandomSearchCV`, which can be much faster at finding a good parameter combination.

After describing these tools we detail *best practices* applicable to these approaches. Some models allow for specialized, efficient parameter search strategies, outlined in *Alternatives to brute force parameter search*.

Note that it is common that a small subset of those parameters can have a large impact on the predictive or computation performance of the model while others can be left to their default values. It is recommended to read the docstring of the estimator class to get a finer understanding of their expected behavior, possibly by reading the enclosed reference to the literature.
Exhaustive Grid Search

The grid search provided by `GridSearchCV` exhaustively generates candidates from a grid of parameter values specified with the `param_grid` parameter. For instance, the following `param_grid`:

```python
param_grid = [
    {'C': [1, 10, 100, 1000], 'kernel': ['linear']},
    {'C': [1, 10, 100, 1000], 'gamma': [0.001, 0.0001], 'kernel': ['rbf']},
]
```

specifies that two grids should be explored: one with a linear kernel and C values in [1, 10, 100, 1000], and the second one with an RBF kernel, and the cross-product of C values ranging in [1, 10, 100, 1000] and gamma values in [0.001, 0.0001].

The `GridSearchCV` instance implements the usual estimator API: when “fitting” it on a dataset all the possible combinations of parameter values are evaluated and the best combination is retained.

Examples:

- See [Parameter estimation using grid search with cross-validation](https://scikit-learn.org/stable/auto_examples/model_selection/plot_grid_search_digits.html) for an example of Grid Search computation on the digits dataset.
- See [Sample pipeline for text feature extraction and evaluation](https://scikit-learn.org/stable/auto_examples/text/plot_text_step_by_step.html) for an example of Grid Search coupling parameters from a text documents feature extractor (n-gram count vectorizer and TF-IDF transformer) with a classifier (here a linear SVM trained with SGD with either elastic net or L2 penalty) using a `pipeline` pipeline instance.
- See [Nested versus non-nested cross-validation](https://scikit-learn.org/stable/auto_examples/model_selection/plot_nested_cross_valid.html) for an example of Grid Search within a cross validation loop on the iris dataset. This is the best practice for evaluating the performance of a model with grid search.
- See [Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV](https://scikit-learn.org/stable/auto_examples/model_selection/plot_multi_metric_search.html) for an example of `GridSearchCV` being used to evaluate multiple metrics simultaneously.
- See [Balance model complexity and cross-validated score](https://scikit-learn.org/stable/auto_examples/model_selection/plot_grid_search.html) for an example of using `refit=callable` interface in `GridSearchCV`. The example shows how this interface adds certain amount of flexibility in identifying the “best” estimator. This interface can also be used in multiple metrics evaluation.
- See [Statistical comparison of models using grid search](https://scikit-learn.org/stable/auto_examples/model_selection/plot_grid_search_permutation.html) for an example of how to do a statistical comparison on the outputs of `GridSearchCV`.

Randomized Parameter Optimization

While using a grid of parameter settings is currently the most widely used method for parameter optimization, other search methods have more favourable properties. `RandomizedSearchCV` implements a randomized search over parameters, where each setting is sampled from a distribution over possible parameter values. This has two main benefits over an exhaustive search:

- A budget can be chosen independent of the number of parameters and possible values.
- Adding parameters that do not influence the performance does not decrease efficiency.

Specifying how parameters should be sampled is done using a dictionary, very similar to specifying parameters for `GridSearchCV`. Additionally, a computation budget, being the number of sampled candidates or sampling iterations, is specified using the `n_iter` parameter. For each parameter, either a distribution over possible values or a list of discrete choices (which will be sampled uniformly) can be specified:
This example uses the `scipy.stats` module, which contains many useful distributions for sampling parameters, such as `expon`, `gamma`, `uniform` or `randint`.

In principle, any function can be passed that provides a `rvs` (random variate sample) method to sample a value. A call to the `rvs` function should provide independent random samples from possible parameter values on consecutive calls.

**Warning:** The distributions in `scipy.stats` prior to version scipy 0.16 do not allow specifying a random state. Instead, they use the global numpy random state, that can be seeded via `np.random.seed` or set using `np.random.set_state`. However, beginning scikit-learn 0.18, the `sklearn.model_selection` module sets the random state provided by the user if scipy >= 0.16 is also available.

For continuous parameters, such as `C` above, it is important to specify a continuous distribution to take full advantage of the randomization. This way, increasing `n_iter` will always lead to a finer search.

A continuous log-uniform random variable is available through `loguniform`. This is a continuous version of log-spaced parameters. For example to specify `C` above, `loguniform(1, 100)` can be used instead of `[1, 10, 100]` or `np.logspace(0, 2, num=1000)`. This is an alias to SciPy’s `stats.reciprocal`.

Mirroring the example above in grid search, we can specify a continuous random variable that is log-uniformly distributed between `1e0` and `1e3`:

```python
from sklearn.utils.fixes import loguniform

{'C': loguniform(1e0, 1e3),
 'gamma': loguniform(1e-4, 1e-3),
 'kernel': ['rbf'],
 'class_weight': ['balanced', None]}
```

**Examples:**

- Comparing randomized search and grid search for hyperparameter estimation compares the usage and efficiency of randomized search and grid search.

**References:**

Searching for optimal parameters with successive halving

Scikit-learn also provides the `HalvingGridSearchCV` and `HalvingRandomSearchCV` estimators that can be used to search a parameter space using successive halving. Successive halving (SH) is like a tournament among candidate parameter combinations. SH is an iterative selection process where all candidates (the parameter combinations) are evaluated with a small amount of resources at the first iteration. Only some of these candidates are selected for the next iteration, which will be allocated more resources. For parameter tuning, the resource is typically the number of training samples, but it can also be an arbitrary numeric parameter such as `n_estimators` in a random forest.

As illustrated in the figure below, only a subset of candidates ‘survive’ until the last iteration. These are the candidates that have consistently ranked among the top-scoring candidates across all iterations. Each iteration is allocated an increasing amount of resources per candidate, here the number of samples.

We here briefly describe the main parameters, but each parameter and their interactions are described in more details in the sections below. The `factor (> 1)` parameter controls the rate at which the resources grow, and the rate at which the number of candidates decreases. In each iteration, the number of resources per candidate is multiplied by `factor` and the number of candidates is divided by the same factor. Along with `resource` and `min_resources`, `factor` is the most important parameter to control the search in our implementation, though a value of 3 usually works well. `factor` effectively controls the number of iterations in `HalvingGridSearchCV` and the number of candidates (by default) and iterations in `HalvingRandomSearchCV`. `aggressive_elimination=True` can also be

---

used if the number of available resources is small. More control is available through tuning the `min_resources` parameter.

These estimators are still experimental: their predictions and their API might change without any deprecation cycle. To use them, you need to explicitly import `enable_halving_search_cv`:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_halving_search_cv # noqa
>>> # now you can import normally from model_selection
>>> from sklearn.model_selection import HalvingGridSearchCV
>>> from sklearn.model_selection import HalvingRandomSearchCV
```

**Examples:**

- Comparison between grid search and successive halving
- Successive Halving Iterations

### Choosing `min_resources` and the number of candidates

Beside `factor`, the two main parameters that influence the behaviour of a successive halving search are the `min_resources` parameter, and the number of candidates (or parameter combinations) that are evaluated. `min_resources` is the amount of resources allocated at the first iteration for each candidate. The number of candidates is specified directly in `HalvingRandomSearchCV`, and is determined from the `param_grid` parameter of `HalvingGridSearchCV`.

Consider a case where the resource is the number of samples, and where we have 1000 samples. In theory, with `min_resources=10` and `factor=2`, we are able to run at most 7 iterations with the following number of samples:

\[10, 20, 40, 80, 160, 320, 640\].

But depending on the number of candidates, we might run less than 7 iterations: if we start with a small number of candidates, the last iteration might use less than 640 samples, which means not using all the available resources (samples). For example if we start with 5 candidates, we only need 2 iterations: 5 candidates for the first iteration, then \[5 \div 2 = 2\] candidates at the second iteration, after which we know which candidate performs the best (so we don’t need a third one). We would only be using at most 20 samples which is a waste since we have 1000 samples at our disposal. On the other hand, if we start with a high number of candidates, we might end up with a lot of candidates at the last iteration, which may not always be ideal: it means that many candidates will run with the full resources, basically reducing the procedure to standard search.

In the case of `HalvingRandomSearchCV`, the number of candidates is set by default such that the last iteration uses as much of the available resources as possible. For `HalvingGridSearchCV`, the number of candidates is determined by the `param_grid` parameter. Changing the value of `min_resources` will impact the number of possible iterations, and as a result will also have an effect on the ideal number of candidates.

Another consideration when choosing `min_resources` is whether or not it is easy to discriminate between good and bad candidates with a small amount of resources. For example, if you need a lot of samples to distinguish between good and bad parameters, a high `min_resources` is recommended. On the other hand if the distinction is clear even with a small amount of samples, then a small `min_resources` may be preferable since it would speed up the computation.

Notice in the example above that the last iteration does not use the maximum amount of resources available: 1000 samples are available, yet only 640 are used, at most. By default, both `HalvingRandomSearchCV` and `HalvingGridSearchCV` try to use as many resources as possible in the last iteration, with the constraint that this amount of resources must be a multiple of both `min_resources` and `factor` (this constraint will be clear in the next section). `HalvingRandomSearchCV` achieves this by sampling the right amount of candidates, while

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HalvingGridSearchCV achieves this by properly setting min_resources. Please see Exhausting the available resources for details.

**Amount of resource and number of candidates at each iteration**

At any iteration $i$, each candidate is allocated a given amount of resources which we denote $n_{resources_i}$. This quantity is controlled by the parameters factor and min_resources as follows (factor is strictly greater than 1):

$$n_{resources_i} = \text{factor}^i \times \text{min_resources},$$

or equivalently:

$$n_{resources_{i+1}} = n_{resources_i} \times \text{factor}$$

where min_resources == n_resources_0 is the amount of resources used at the first iteration. factor also defines the proportions of candidates that will be selected for the next iteration:

$$n_{candidates_i} = n_{candidates} \div (\text{factor}^i)$$

or equivalently:

$$n_{candidates_0} = n_{candidates}$$
$$n_{candidates_{i+1}} = n_{candidates_i} \div \text{factor}$$

So in the first iteration, we use min_resources resources $n_{candidates}$ times. In the second iteration, we use min_resources * factor resources $n_{candidates}$ // factor times. The third again multiplies the resources per candidate and divides the number of candidates. This process stops when the maximum amount of resource per candidate is reached, or when we have identified the best candidate. The best candidate is identified at the iteration that is evaluating factor or less candidates (see just below for an explanation).

Here is an example with min_resources=3 and factor=2, starting with 70 candidates:

<table>
<thead>
<tr>
<th>$n_{resources_i}$</th>
<th>$n_{candidates_i}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>3 (=min_resources)</td>
<td>70 (=n_candidates)</td>
</tr>
<tr>
<td>6</td>
<td>70 // 2 = 35</td>
</tr>
<tr>
<td>12</td>
<td>35 // 2 = 17</td>
</tr>
<tr>
<td>24</td>
<td>17 // 2 = 8</td>
</tr>
<tr>
<td>48</td>
<td>8 // 2 = 4</td>
</tr>
<tr>
<td></td>
<td>4 // 2 = 2</td>
</tr>
</tbody>
</table>

We can note that:

- the process stops at the first iteration which evaluates factor=2 candidates: the best candidate is the best out of these 2 candidates. It is not necessary to run an additional iteration, since it would only evaluate one candidate (namely the best one, which we have already identified). For this reason, in general, we want the last iteration to run at most factor candidates. If the last iteration evaluates more than factor candidates, then this last iteration reduces to a regular search (as in RandomizedSearchCV or GridSearchCV).

- each $n_{resources_i}$ is a multiple of both factor and min_resources (which is confirmed by its definition above).

The amount of resources that is used at each iteration can be found in the $n_{resources_\_} attribute.
Choosing a resource

By default, the resource is defined in terms of number of samples. That is, each iteration will use an increasing amount of samples to train on. You can however manually specify a parameter to use as the resource with the resource parameter. Here is an example where the resource is defined in terms of the number of estimators of a random forest:

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.experimental import enable_halving_search_cv  # noqa
>>> from sklearn.model_selection import HalvingGridSearchCV
>>> import pandas as pd

>>> param_grid = {'max_depth': [3, 5, 10],
    ... 'min_samples_split': [2, 5, 10]}
>>> base_estimator = RandomForestClassifier(random_state=0)
>>> X, y = make_classification(n_samples=1000, random_state=0)
>>> sh = HalvingGridSearchCV(base_estimator, param_grid, cv=5,
    ... factor=2, resource='n_estimators',
    ... max_resources=30).fit(X, y)
>>> sh.best_estimator_
RandomForestClassifier(max_depth=5, n_estimators=24, random_state=0)
```

Note that it is not possible to budget on a parameter that is part of the parameter grid.

Exhausting the available resources

As mentioned above, the number of resources that is used at each iteration depends on the min_resources parameter. If you have a lot of resources available but start with a low number of resources, some of them might be wasted (i.e. not used):

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.svm import SVC
>>> from sklearn.experimental import enable_halving_search_cv  # noqa
>>> from sklearn.model_selection import HalvingGridSearchCV
>>> import pandas as pd

>>> param_grid= {'kernel': ('linear', 'rbf'),
    ... 'C': [1, 10, 100]}
>>> base_estimator = SVC(gamma='scale')
>>> X, y = make_classification(n_samples=1000)
>>> sh = HalvingGridSearchCV(base_estimator, param_grid, cv=5,
    ... factor=2, min_resources=20).fit(X, y)
>>> sh.n_resources_
[20, 40, 80]
```

The search process will only use 80 resources at most, while our maximum amount of available resources is n_samples=1000. Here, we have min_resources = r_0 = 20.

For `HalvingGridSearchCV`, by default, the min_resources parameter is set to ‘exhaust’. This means that min_resources is automatically set such that the last iteration can use as many resources as possible, within the max_resources limit:

```python
>>> sh = HalvingGridSearchCV(base_estimator, param_grid, cv=5,
    ... factor=2, min_resources='exhaust').fit(X, y)
>>> sh.n_resources_
[250, 500, 1000]
```
min_resources was here automatically set to 250, which results in the last iteration using all the resources. The exact value that is used depends on the number of candidate parameter, on max_resources and on factor.

For HalvingRandomSearchCV, exhausting the resources can be done in 2 ways:

- by setting min_resources='exhaust', just like for HalvingGridSearchCV;
- by setting n_candidates='exhaust'.

Both options are mutually exclusive: using min_resources='exhaust' requires knowing the number of candidates, and symmetrically n_candidates='exhaust' requires knowing min_resources.

In general, exhausting the total number of resources leads to a better final candidate parameter, and is slightly more time-intensive.

**Aggressive elimination of candidates**

Ideally, we want the last iteration to evaluate \( \text{factor} \) candidates (see Amount of resource and number of candidates at each iteration). We then just have to pick the best one. When the number of available resources is small with respect to the number of candidates, the last iteration may have to evaluate more than \( \text{factor} \) candidates:

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.svm import SVC
>>> from sklearn.experimental import enable_halving_search_cv # noqa
>>> from sklearn.model_selection import HalvingGridSearchCV
>>> import pandas as pd

>>> param_grid = {'kernel': ('linear', 'rbf'),
...               'C': [1, 10, 100]}
>>> base_estimator = SVC(gamma='scale')
>>> X, y = make_classification(n_samples=1000)
>>> sh = HalvingGridSearchCV(base_estimator, param_grid, cv=5,
...                           factor=2, max_resources=40,
...                           aggressive_elimination=False).fit(X, y)
>>> sh.n_resources_
[20, 40]
>>> sh.n_candidates_
[6, 3]
```

Since we cannot use more than max_resources=40 resources, the process has to stop at the second iteration which evaluates more than \( \text{factor} \= 2 \) candidates.

Using the aggressive_elimination parameter, you can force the search process to end up with less than \( \text{factor} \) candidates at the last iteration. To do this, the process will eliminate as many candidates as necessary using min_resources resources:

```python
>>> sh = HalvingGridSearchCV(base_estimator, param_grid, cv=5,
...                           factor=2,
...                           max_resources=40,
...                           aggressive_elimination=True,
...                           ).fit(X, y)
>>> sh.n_resources_
[20, 20, 40]
>>> sh.n_candidates_
[6, 3, 2]
```

Notice that we end with 2 candidates at the last iteration since we have eliminated enough candidates during the first iterations, using \( \text{n_resources} = \text{min_resources} = 20 \).
Analysing results with the `cv_results_` attribute

The `cv_results_` attribute contains useful information for analysing the results of a search. It can be converted to a pandas dataframe with `df = pd.DataFrame(est.cv_results_)`. The `cv_results_` attribute of `HalvingGridSearchCV` and `HalvingRandomSearchCV` is similar to that of `GridSearchCV` and `RandomizedSearchCV`, with additional information related to the successive halving process.

Here is an example with some of the columns of a (truncated) dataframe:

<table>
<thead>
<tr>
<th>iter</th>
<th>n_resources</th>
<th>mean_test_score</th>
<th>params</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0.983667</td>
<td>{'criterion': 'entropy', 'max_depth': None, 'max_features': 9, 'min_samples_split': 5}</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>0.983667</td>
<td>{'criterion': 'gini', 'max_depth': None, 'max_features': 8, 'min_samples_split': 7}</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>0.983667</td>
<td>{'criterion': 'gini', 'max_depth': None, 'max_features': 10, 'min_samples_split': 10}</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
<td>0.983667</td>
<td>{'criterion': 'entropy', 'max_depth': None, 'max_features': 6, 'min_samples_split': 6}</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>15</td>
<td>2</td>
<td>0.951958</td>
<td>{'criterion': 'entropy', 'max_depth': None, 'max_features': 9, 'min_samples_split': 10}</td>
</tr>
<tr>
<td>16</td>
<td>2</td>
<td>0.947958</td>
<td>{'criterion': 'gini', 'max_depth': None, 'max_features': 10, 'min_samples_split': 10}</td>
</tr>
<tr>
<td>17</td>
<td>2</td>
<td>0.951958</td>
<td>{'criterion': 'gini', 'max_depth': None, 'max_features': 10, 'min_samples_split': 4}</td>
</tr>
<tr>
<td>18</td>
<td>3</td>
<td>0.961009</td>
<td>{'criterion': 'entropy', 'max_depth': None, 'max_features': 9, 'min_samples_split': 10}</td>
</tr>
<tr>
<td>19</td>
<td>3</td>
<td>0.955989</td>
<td>{'criterion': 'gini', 'max_depth': None, 'max_features': 10, 'min_samples_split': 4}</td>
</tr>
</tbody>
</table>

Each row corresponds to a given parameter combination (a candidate) and a given iteration. The iteration is given by the `iter` column. The `n_resources` column tells you how many resources were used.

In the example above, the best parameter combination is `{'criterion': 'entropy', 'max_depth': None, 'max_features': 9, 'min_samples_split': 10}` since it has reached the last iteration (3) with the highest score: 0.96.

References:

Tips for parameter search

Specifying an objective metric

By default, parameter search uses the `score` function of the estimator to evaluate a parameter setting. These are the `sklearn.metrics.accuracy_score` for classification and `sklearn.metrics.r2_score` for regression. For some applications, other scoring functions are better suited (for example in unbalanced classification, the accuracy score is often uninformative). An alternative scoring function can be specified via the `scoring` parameter of most parameter search tools. See `The scoring parameter: defining model evaluation rules` for more details.
Specifying multiple metrics for evaluation

`GridSearchCV` and `RandomizedSearchCV` allow specifying multiple metrics for the `scoring` parameter. Multimetric scoring can either be specified as a list of strings of predefined scores names or a dict mapping the scorer name to the scorer function and/or the predefined scorer name(s). See `Using multiple metric evaluation` for more details.

When specifying multiple metrics, the `refit` parameter must be set to the metric (string) for which the `best_params_` will be found and used to build the `best_estimator_` on the whole dataset. If the search should not be refit, set `refit=False`. Leaving refit to the default value `None` will result in an error when using multiple metrics.

See `Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV` for an example usage.

`HalvingRandomSearchCV` and `HalvingGridSearchCV` do not support multimetric scoring.

Composite estimators and parameter spaces

`GridSearchCV` and `RandomizedSearchCV` allow searching over parameters of composite or nested estimators such as `Pipeline`, `ColumnTransformer`, `VotingClassifier` or `CalibratedClassifierCV` using a dedicated `<estimator>__<parameter>` syntax:

```python
>>> from sklearn.model_selection import GridSearchCV
>>> from sklearn.calibration import CalibratedClassifierCV
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.datasets import make_moons

>>> X, y = make_moons()

>>> calibrated_forest = CalibratedClassifierCV(
... base_estimator=RandomForestClassifier(n_estimators=10))

>>> param_grid = {
... 'base_estimator__max_depth': [2, 4, 6, 8]
... }

>>> search = GridSearchCV(calibrated_forest, param_grid, cv=5)

>>> search.fit(X, y)
```

Here, `<estimator>` is the parameter name of the nested estimator, in this case `base_estimator`. If the meta-estimator is constructed as a collection of estimators as in `pipeline.Pipeline`, then `<estimator>` refers to the name of the estimator, see `Nested parameters`. In practice, there can be several levels of nesting:

```python
>>> from sklearn.pipeline import Pipeline
>>> from sklearn.feature_selection import SelectKBest

>>> pipe = Pipeline(
... [('select', SelectKBest()),
... ('model', calibrated_forest)])

>>> param_grid = {
... 'select__k': [1, 2],
... 'model__base_estimator__max_depth': [2, 4, 6, 8]
... }

>>> search = GridSearchCV(pipe, param_grid, cv=5).fit(X, y)
```

Please refer to `Pipeline: chaining estimators` for performing parameter searches over pipelines.
Model selection: development and evaluation

Model selection by evaluating various parameter settings can be seen as a way to use the labeled data to “train” the parameters of the grid.

When evaluating the resulting model it is important to do it on held-out samples that were not seen during the grid search process: it is recommended to split the data into a development set (to be fed to the GridSearchCV instance) and an evaluation set to compute performance metrics.

This can be done by using the train_test_split utility function.

Parallelism

The parameter search tools evaluate each parameter combination on each data fold independently. Computations can be run in parallel by using the keyword n_jobs=-1. See function signature for more details, and also the Glossary entry for n_jobs.

Robustness to failure

Some parameter settings may result in a failure to fit one or more folds of the data. By default, this will cause the entire search to fail, even if some parameter settings could be fully evaluated. Setting error_score=0 (or =np.Nan) will make the procedure robust to such failure, issuing a warning and setting the score for that fold to 0 (or NaN), but completing the search.

Alternatives to brute force parameter search

Model specific cross-validation

Some models can fit data for a range of values of some parameter almost as efficiently as fitting the estimator for a single value of the parameter. This feature can be leveraged to perform a more efficient cross-validation used for model selection of this parameter.

The most common parameter amenable to this strategy is the parameter encoding the strength of the regularizer. In this case we say that we compute the regularization path of the estimator.

Here is the list of such models:

<table>
<thead>
<tr>
<th>Model</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>linear_model.ElasticNetCV(*[, l1_ratio,...])</code></td>
<td>Elastic Net model with iterative fitting along a regularization path.</td>
</tr>
<tr>
<td><code>linear_model.LarsCV(*[, fit_intercept,...])</code></td>
<td>Cross-validated Least Angle Regression model.</td>
</tr>
<tr>
<td><code>linear_model.LassoCV(*[, eps, n_alphas,...])</code></td>
<td>Lasso linear model with iterative fitting along a regularization path.</td>
</tr>
<tr>
<td><code>linear_model.LassoLarsCV(*[, fit_intercept,...])</code></td>
<td>Cross-validated Lasso, using the LARS algorithm.</td>
</tr>
<tr>
<td><code>linear_model.LogisticRegressionCV(*[, Cs,...])</code></td>
<td>Logistic Regression CV (aka logit, MaxEnt) classifier.</td>
</tr>
<tr>
<td><code>linear_model.MultiTaskLassoCV(*[, eps,...])</code></td>
<td>Multi-task Lasso model trained with L1/L2 mixed-norm as regularizer.</td>
</tr>
</tbody>
</table>

continues on next page
Table 1 – continued from previous page

<table>
<thead>
<tr>
<th>Class</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>linear_model.RidgeCV([alphas, ...])</td>
<td>Ridge regression with built-in cross-validation.</td>
</tr>
<tr>
<td>linear_model.RidgeClassifierCV([alphas, ...])</td>
<td>Ridge classifier with built-in cross-validation.</td>
</tr>
</tbody>
</table>

**Information Criterion**

Some models can offer an information-theoretic closed-form formula of the optimal estimate of the regularization parameter by computing a single regularization path (instead of several when using cross-validation).

Here is the list of models benefiting from the Akaike Information Criterion (AIC) or the Bayesian Information Criterion (BIC) for automated model selection:

<table>
<thead>
<tr>
<th>Class</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>linear_model.LassoLarsIC([criterion, ...])</td>
<td>Lasso model fit with Lars using BIC or AIC for model selection</td>
</tr>
</tbody>
</table>

**Out of Bag Estimates**

When using ensemble methods base upon bagging, i.e. generating new training sets using sampling with replacement, part of the training set remains unused. For each classifier in the ensemble, a different part of the training set is left out.

This left out portion can be used to estimate the generalization error without having to rely on a separate validation set. This estimate comes “for free” as no additional data is needed and can be used for model selection.

This is currently implemented in the following classes:

<table>
<thead>
<tr>
<th>Class</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ensemble.RandomForestClassifier([...])</td>
<td>A random forest classifier.</td>
</tr>
<tr>
<td>ensemble.RandomForestRegressor([...])</td>
<td>A random forest regressor.</td>
</tr>
<tr>
<td>ensemble.ExtraTreesClassifier([...])</td>
<td>An extra-trees classifier.</td>
</tr>
<tr>
<td>ensemble.GradientBoostingClassifier(*[,...])</td>
<td>Gradient Boosting for classification.</td>
</tr>
<tr>
<td>ensemble.GradientBoostingRegressor(*[,...])</td>
<td>Gradient Boosting for regression.</td>
</tr>
</tbody>
</table>

**4.3.3 Metrics and scoring: quantifying the quality of predictions**

There are 3 different APIs for evaluating the quality of a model’s predictions:

- **Estimator score method**: Estimators have a score method providing a default evaluation criterion for the problem they are designed to solve. This is not discussed on this page, but in each estimator’s documentation.

- **Scoring parameter**: Model-evaluation tools using cross-validation (such as model_selection.cross_val_score and model_selection.GridSearchCV) rely on an internal scoring strategy. This is discussed in the section *The scoring parameter: defining model evaluation rules.*

- **Metric functions**: The sklearn.metrics module implements functions assessing prediction error for specific purposes. These metrics are detailed in sections on *Classification metrics, Multilabel ranking metrics,*
Regression metrics and Clustering metrics.

Finally, Dummy estimators are useful to get a baseline value of those metrics for random predictions.

See also:

For “pairwise” metrics, between samples and not estimators or predictions, see the Pairwise metrics, Affinities and Kernels section.

The scoring parameter: defining model evaluation rules

Model selection and evaluation using tools, such as model_selection.GridSearchCV and model_selection.cross_val_score, take a scoring parameter that controls what metric they apply to the estimators evaluated.

Common cases: predefined values

For the most common use cases, you can designate a scorer object with the scoring parameter; the table below shows all possible values. All scorer objects follow the convention that higher return values are better than lower return values. Thus metrics which measure the distance between the model and the data, like metrics.mean_squared_error, are available as neg_mean_squared_error which return the negated value of the metric.

<table>
<thead>
<tr>
<th>Scoring</th>
<th>Function</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Classification</td>
<td>Function</td>
<td>Comment</td>
</tr>
<tr>
<td>'accuracy'</td>
<td>metrics.accuracy_score</td>
<td></td>
</tr>
<tr>
<td>'balanced_accuracy'</td>
<td>metrics.balanced_accuracy_score</td>
<td></td>
</tr>
<tr>
<td>'top_k_accuracy'</td>
<td>metrics.top_k_accuracy_score</td>
<td></td>
</tr>
<tr>
<td>'average_precision'</td>
<td>metrics.average_precision_score</td>
<td></td>
</tr>
<tr>
<td>'neg_brier_score'</td>
<td>metrics.brier_score_loss</td>
<td></td>
</tr>
<tr>
<td>'f1'</td>
<td>metrics.f1_score</td>
<td>for binary targets</td>
</tr>
<tr>
<td>'f1_micro'</td>
<td>metrics.f1_score</td>
<td>micro-averaged</td>
</tr>
<tr>
<td>'f1_macro'</td>
<td>metrics.f1_score</td>
<td>macro-averaged</td>
</tr>
<tr>
<td>'f1_weighted'</td>
<td>metrics.f1_score</td>
<td>weighted average</td>
</tr>
<tr>
<td>'f1_samples'</td>
<td>metrics.f1_score</td>
<td>by multilabel sample</td>
</tr>
<tr>
<td>'neg_log_loss'</td>
<td>metrics.log_loss</td>
<td>requires predict_proba support</td>
</tr>
<tr>
<td>'precision' etc.</td>
<td>metrics.precision_score</td>
<td>suffixes apply as with 'f1'</td>
</tr>
<tr>
<td>'recall' etc.</td>
<td>metrics.recall_score</td>
<td>suffixes apply as with 'f1'</td>
</tr>
<tr>
<td>'jaccard' etc.</td>
<td>metrics.jaccard_score</td>
<td>suffixes apply as with 'f1'</td>
</tr>
<tr>
<td>'roc_auc'</td>
<td>metrics.roc_auc_score</td>
<td></td>
</tr>
<tr>
<td>'roc_auc_ovr'</td>
<td>metrics.roc_auc_score</td>
<td></td>
</tr>
<tr>
<td>'roc_auc_ovo'</td>
<td>metrics.roc_auc_score</td>
<td></td>
</tr>
<tr>
<td>'roc_auc_ovr_weighted'</td>
<td>metrics.roc_auc_score</td>
<td></td>
</tr>
<tr>
<td>'roc_auc_ovo_weighted'</td>
<td>metrics.roc_auc_score</td>
<td></td>
</tr>
<tr>
<td>Clustering</td>
<td>Function</td>
<td>Comment</td>
</tr>
<tr>
<td>'adjusted_mutual_info_score'</td>
<td>metrics.adjusted_mutual_info_score</td>
<td></td>
</tr>
<tr>
<td>'adjusted_rand_score'</td>
<td>metrics.adjusted_rand_score</td>
<td></td>
</tr>
<tr>
<td>'completeness_score'</td>
<td>metrics.completeness_score</td>
<td></td>
</tr>
<tr>
<td>'fowlkes_mallows_score'</td>
<td>metrics.fowlkes_mallows_score</td>
<td></td>
</tr>
<tr>
<td>'homogeneity_score'</td>
<td>metrics.homogeneity_score</td>
<td></td>
</tr>
<tr>
<td>'mutual_info_score'</td>
<td>metrics.mutual_info_score</td>
<td></td>
</tr>
<tr>
<td>'normalized_mutual_info_score'</td>
<td>metrics.normalized_mutual_info_score</td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
Table 4 – continued from previous page

<table>
<thead>
<tr>
<th>Scoring</th>
<th>Function</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>'rand_score'</td>
<td>metrics.rand_score</td>
<td></td>
</tr>
<tr>
<td>'v_measure_score'</td>
<td>metrics.v_measure_score</td>
<td></td>
</tr>
<tr>
<td><strong>Regression</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>'explained_variance'</td>
<td>metrics.explained_variance_score</td>
<td></td>
</tr>
<tr>
<td>'max_error'</td>
<td>metrics.max_error</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_absolute_error'</td>
<td>metrics.mean_absolute_error</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_squared_error'</td>
<td>metrics.mean_squared_error</td>
<td></td>
</tr>
<tr>
<td>'neg_root_mean_squared_error'</td>
<td>metrics.mean_squared_error</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_squared_log_error'</td>
<td>metrics.mean_squared_log_error</td>
<td></td>
</tr>
<tr>
<td>'neg_median_absolute_error'</td>
<td>metrics.median_absolute_error</td>
<td></td>
</tr>
<tr>
<td>'r2'</td>
<td>metrics.r2_score</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_poisson_deviance'</td>
<td>metrics.mean_poisson_deviance</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_gamma_deviance'</td>
<td>metrics.mean_gamma_deviance</td>
<td></td>
</tr>
<tr>
<td>'neg_mean_absolute_percentage_error'</td>
<td>metrics.mean_absolute_percentage_error</td>
<td></td>
</tr>
</tbody>
</table>

Usage examples:

```python
>>> from sklearn import svm, datasets
>>> from sklearn.model_selection import cross_val_score
>>> X, y = datasets.load_iris(return_X_y=True)
>>> clf = svm.SVC(random_state=0)
>>> cross_val_score(clf, X, y, cv=5, scoring='recall_macro')
array([0.96..., 0.96..., 0.96..., 0.93..., 1.      ])
>>> model = svm.SVC()
>>> cross_val_score(model, X, y, cv=5, scoring='wrong_choice')
Traceback (most recent call last):
  ValueError: 'wrong_choice' is not a valid scoring value. Use sorted(sklearn.metrics._SCORERS.keys()) to get valid options.
```

**Note:** The values listed by the `ValueError` exception correspond to the functions measuring prediction accuracy described in the following sections. The scorer objects for those functions are stored in the dictionary `sklearn.metrics.SCORERS`.

### Defining your scoring strategy from metric functions

The module `sklearn.metrics` also exposes a set of simple functions measuring a prediction error given ground truth and prediction:

- functions ending with `_score` return a value to maximize, the higher the better.
- functions ending with `_error` or `_loss` return a value to minimize, the lower the better. When converting into a scorer object using `make_scorer`, set the `greater_is_better` parameter to `False` (`True` by default; see the parameter description below).

Metrics available for various machine learning tasks are detailed in sections below.

Many metrics are not given names to be used as `scoring` values, sometimes because they require additional parameters, such as `fbeta_score`. In such cases, you need to generate an appropriate scoring object. The simplest way to generate a callable object for scoring is by using `make_scorer`. That function converts metrics into callables that can be used for model evaluation.
One typical use case is to wrap an existing metric function from the library with non-default values for its parameters, such as the `beta` parameter for the `fbeta_score` function:

```python
>>> from sklearn.metrics import fbeta_score, make_scorer
>>> ftwo_scorer = make_scorer(fbeta_score, beta=2)
>>> from sklearn.model_selection import GridSearchCV
>>> from sklearn.svm import LinearSVC
>>> grid = GridSearchCV(LinearSVC(), param_grid={'C': [1, 10]},
... scoring=ftwo_scorer, cv=5)
```

The second use case is to build a completely custom scorer object from a simple python function using `make_scorer`, which can take several parameters:

- the python function you want to use (`my_custom_loss_func` in the example below)
- whether the python function returns a score (`greater_is_better=True`, the default) or a loss (`greater_is_better=False`). If a loss, the output of the python function is negated by the scorer object, conforming to the cross validation convention that scorers return higher values for better models.
- for classification metrics only: whether the python function you provided requires continuous decision certainties (`needs_threshold=True`). The default value is False.
- any additional parameters, such as `beta` or `labels` in `f1_score`.

Here is an example of building custom scorers, and of using the `greater_is_better` parameter:

```python
>>> import numpy as np
>>> def my_custom_loss_func(y_true, y_pred):
...     diff = np.abs(y_true - y_pred).max()
...     return np.log1p(diff)
... 
... # score will negate the return value of my_custom_loss_func,
>>> # which will be np.log(2), 0.693, given the values for X
>>> # and y defined below.
>>> score = make_scorer(my_custom_loss_func, greater_is_better=False)
>>> X = [[1], [1]]
>>> y = [0, 1]
>>> from sklearn.dummy import DummyClassifier
>>> clf = DummyClassifier(strategy='most_frequent', random_state=0)
>>> clf = clf.fit(X, y)
>>> my_custom_loss_func(y, clf.predict(X))
0.69...
>>> score(clf, X, y)
-0.69...
```

### Implementing your own scoring object

You can generate even more flexible model scorers by constructing your own scoring object from scratch, without using the `make_scorer` factory. For a callable to be a scorer, it needs to meet the protocol specified by the following two rules:

- It can be called with parameters `estimator, X, y)`, where `estimator` is the model that should be evaluated, `X` is validation data, and `y` is the ground truth target for `X` (in the supervised case) or `None` (in the unsupervised case).
- It returns a floating point number that quantifies the `estimator` prediction quality on `X`, with reference to `y`. Again, by convention higher numbers are better, so if your scorer returns loss, that value should be negated.
Note: Using custom scorers in functions where n_jobs > 1

While defining the custom scoring function alongside the calling function should work out of the box with the default joblib backend (loky), importing it from another module will be a more robust approach and work independently of the joblib backend.

For example, to use n_jobs greater than 1 in the example below, custom_scoring_function function is saved in a user-created module (custom_scorer_module.py) and imported:

```python
>>> from custom_scorer_module import custom_scoring_function
>>> cross_val_score(model,
... X_train,
... y_train,
... scoring=make_scorer(custom_scoring_function, greater_is_better=False),
... cv=5,
... n_jobs=-1)
```

### Using multiple metric evaluation

Scikit-learn also permits evaluation of multiple metrics in GridSearchCV, RandomizedSearchCV and cross_validate.

There are three ways to specify multiple scoring metrics for the scoring parameter:

- As an iterable of string metrics:

  ```python
  >>> scoring = ['accuracy', 'precision']
  ```

- As a dict mapping the scorer name to the scoring function:

  ```python
  >>> from sklearn.metrics import accuracy_score
  >>> from sklearn.metrics import make_scorer
  >>> scoring = {'accuracy': make_scorer(accuracy_score),
  ...            'prec': 'precision'}
  ```

Note that the dict values can either be scorer functions or one of the predefined metric strings.

- As a callable that returns a dictionary of scores:

  ```python
  >>> from sklearn.model_selection import cross_validate
  >>> from sklearn.metrics import confusion_matrix
  >>> # A sample toy binary classification dataset
  >>> X, y = datasets.make_classification(n_classes=2, random_state=0)
  >>> svm = LinearSVC(random_state=0)
  >>> def confusion_matrix_scorer(clf, X, y):
  ...     y_pred = clf.predict(X)
  ...     cm = confusion_matrix(y, y_pred)
  ...     return {'tn': cm[0, 0], 'fp': cm[0, 1],
  ...             'fn': cm[1, 0], 'tp': cm[1, 1]}
  >>> cv_results = cross_validate(svm, X, y, cv=5,
  ...                              scoring=confusion_matrix_scorer)
  >>> # Getting the test set true positive scores
  >>> print(cv_results['test_tp'])
  [10  9  8  7  8]
  >>> # Getting the test set false negative scores
  ```
Classification metrics

The `sklearn.metrics` module implements several loss, score, and utility functions to measure classification performance. Some metrics might require probability estimates of the positive class, confidence values, or binary decisions values. Most implementations allow each sample to provide a weighted contribution to the overall score, through the `sample_weight` parameter.

Some of these are restricted to the binary classification case:

- `precision_recall_curve(y_true, probas_pred, *)` Compute precision-recall pairs for different probability thresholds.
- `roc_curve(y_true, y_score, *[pos_label, ...])` Compute Receiver operating characteristic (ROC).
- `det_curve(y_true, y_score, *[pos_label, ...])` Compute error rates for different probability thresholds.

Others also work in the multiclass case:

- `balanced_accuracy_score(y_true, y_pred, *[...])` Compute the balanced accuracy.
- `cohen_kappa_score(y1, y2, *[labels, ...])` Cohen’s kappa: a statistic that measures inter-annotator agreement.
- `confusion_matrix(y_true, y_pred, *[...])` Compute confusion matrix to evaluate the accuracy of a classification.
- `hinge_loss(y_true, pred_decision, *[...])` Average hinge loss (non-regularized).
- `matthews_corrcoef(y_true, y_pred, *[...])` Compute the Matthews correlation coefficient (MCC).
- `roc_auc_score(y_true, y_score, *[average, ...])` Compute Area Under the Receiver Operating Characteristic Curve (ROC AUC) from prediction scores.
- `top_k_accuracy_score(y_true, y_score, *[...])` Top-k Accuracy classification score.

Some also work in the multilabel case:

- `accuracy_score(y_true, y_pred, *[...])` Accuracy classification score.
- `classification_report(y_true, y_pred, *[...])` Build a text report showing the main classification metrics.
- `f1_score(y_true, y_pred, *[labels, ...])` Compute the F1 score, also known as balanced F-score or F-measure.
- `fbeta_score(y_true, y_pred, *, beta[...])` Compute the F-beta score.
- `hamming_loss(y_true, y_pred, *[sample_weight])` Compute the average Hamming loss.
- `jaccard_score(y_true, y_pred, *[labels, ...])` Jaccard similarity coefficient score.
- `log_loss(y_true, y_pred, *[eps, ...])` Log loss, aka logistic loss or cross-entropy loss.
- `multilabel_confusion_matrix(y_true, y_pred, *)` Compute a confusion matrix for each class or sample.
- `precision_recall_fscore_support(y_true, y_pred, *[...])` Compute precision, recall, F-measure and support for each class.
- `precision_score(y_true, y_pred, *[labels, ...])` Compute the precision.
- `recall_score(y_true, y_pred, *[labels, ...])` Compute the recall.

continues on next page
And some work with binary and multilabel (but not multiclass) problems:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>roc_auc_score(y_true, y_score, *[, average, . . .])</td>
<td>Compute Area Under the Receiver Operating Characteristic Curve (ROC AUC) from prediction scores.</td>
</tr>
<tr>
<td>zero_one_loss(y_true, y_pred, *[, . . .])</td>
<td>Zero-one classification loss.</td>
</tr>
<tr>
<td>average_precision_score(y_true, y_score, *)</td>
<td>Compute average precision (AP) from prediction scores.</td>
</tr>
</tbody>
</table>

In the following sub-sections, we will describe each of those functions, preceded by some notes on common API and metric definition.

### From binary to multiclass and multilabel

Some metrics are essentially defined for binary classification tasks (e.g. fl_score, roc_auc_score). In these cases, by default only the positive label is evaluated, assuming by default that the positive class is labelled 1 (though this may be configurable through the pos_label parameter).

In extending a binary metric to multiclass or multilabel problems, the data is treated as a collection of binary problems, one for each class. There are then a number of ways to average binary metric calculations across the set of classes, each of which may be useful in some scenario. Where available, you should select among these using the average parameter.

- "macro" simply calculates the mean of the binary metrics, giving equal weight to each class. In problems where infrequent classes are nonetheless important, macro-averaging may be a means of highlighting their performance. On the other hand, the assumption that all classes are equally important is often untrue, such that macro-averaging will over-emphasize the typically low performance on an infrequent class.

- "weighted" accounts for class imbalance by computing the average of binary metrics in which each class's score is weighted by its presence in the true data sample.

- "micro" gives each sample-class pair an equal contribution to the overall metric (except as a result of sample-weight). Rather than summing the metric per class, this sums the dividends and divisors that make up the per-class metrics to calculate an overall quotient. Micro-averaging may be preferred in multilabel settings, including multiclass classification where a majority class is to be ignored.

- "samples" applies only to multilabel problems. It does not calculate a per-class measure, instead calculating the metric over the true and predicted classes for each sample in the evaluation data, and returning their (sample_weight-weighted) average.

- Selecting average=None will return an array with the score for each class.

While multiclass data is provided to the metric, like binary targets, as an array of class labels, multilabel data is specified as an indicator matrix, in which cell [i, j] has value 1 if sample i has label j and value 0 otherwise.
Accuracy score

The `accuracy_score` function computes the accuracy, either the fraction (default) or the count (normalize=False) of correct predictions.

In multilabel classification, the function returns the subset accuracy. If the entire set of predicted labels for a sample strictly match with the true set of labels, then the subset accuracy is 1.0; otherwise it is 0.0.

If $\hat{y}_i$ is the predicted value of the $i$-th sample and $y_i$ is the corresponding true value, then the fraction of correct predictions over $n_{\text{samples}}$ is defined as

$$\text{accuracy}(y, \hat{y}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} 1(\hat{y}_i = y_i)$$

where $1(x)$ is the indicator function.

```python
>>> import numpy as np
>>> from sklearn.metrics import accuracy_score

>>> y_pred = [0, 2, 1, 3]
>>> y_true = [0, 1, 2, 3]
>>> accuracy_score(y_true, y_pred)
0.5
>>> accuracy_score(y_true, y_pred, normalize=False)
2
```

In the multilabel case with binary label indicators:

```python
>>> accuracy_score(np.array([[0, 1], [1, 1]]), np.ones((2, 2)))
0.5
```

Example:

- See *Test with permutations the significance of a classification score* for an example of accuracy score usage using permutations of the dataset.

Top-k accuracy score

The `top_k_accuracy_score` function is a generalization of `accuracy_score`. The difference is that a prediction is considered correct as long as the true label is associated with one of the $k$ highest predicted scores. `accuracy_score` is the special case of $k = 1$.

The function covers the binary and multiclass classification cases but not the multilabel case.

If $\hat{f}_{i,j}$ is the predicted class for the $i$-th sample corresponding to the $j$-th largest predicted score and $y_i$ is the corresponding true value, then the fraction of correct predictions over $n_{\text{samples}}$ is defined as

$$\text{top-k accuracy}(y, \hat{f}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} \sum_{j=1}^{k} 1(\hat{f}_{i,j} = y_i)$$

where $k$ is the number of guesses allowed and $1(x)$ is the indicator function.
Balanced accuracy score

The balanced_accuracy_score function computes the balanced accuracy, which avoids inflated performance estimates on imbalanced datasets. It is the macro-average of recall scores per class or, equivalently, raw accuracy where each sample is weighted according to the inverse prevalence of its true class. Thus for balanced datasets, the score is equal to accuracy.

In the binary case, balanced accuracy is equal to the arithmetic mean of sensitivity (true positive rate) and specificity (true negative rate), or the area under the ROC curve with binary predictions rather than scores:

$$\text{balanced-accuracy} = \frac{1}{2} \left( \frac{TP}{TP + FN} + \frac{TN}{TN + FP} \right)$$

If the classifier performs equally well on either class, this term reduces to the conventional accuracy (i.e., the number of correct predictions divided by the total number of predictions).

In contrast, if the conventional accuracy is above chance only because the classifier takes advantage of an imbalanced test set, then the balanced accuracy, as appropriate, will drop to $\frac{1}{n_{\text{classes}}}$.

The score ranges from 0 to 1, or when adjusted=True is used, it rescaled to the range $\frac{1}{1-n_{\text{classes}}}$ to 1, inclusive, with performance at random scoring 0.

If $y_i$ is the true value of the $i$-th sample, and $w_i$ is the corresponding sample weight, then we adjust the sample weight to:

$$\tilde{w}_i = \frac{w_i}{\sum_j 1(y_j = y_i)w_j}$$

where $1(x)$ is the indicator function. Given predicted $\hat{y}_i$ for sample $i$, balanced accuracy is defined as:

$$\text{balanced-accuracy}(y, \hat{y}, w) = \frac{1}{\sum_i \tilde{w}_i} \sum_i 1(y_i = \hat{y}_i)\tilde{w}_i$$

With adjusted=True, balanced accuracy reports the relative increase from $\text{balanced-accuracy}(y, 0, w) = \frac{1}{n_{\text{classes}}}$. In the binary case, this is also known as *Youden’s J statistic*, or informedness.

Note: The multiclass definition here seems the most reasonable extension of the metric used in binary classification, though there is no certain consensus in the literature:

- Our definition: [Mosley2013], [Kelleher2015] and [Guyon2015], where [Guyon2015] adopt the adjusted version to ensure that random predictions have a score of 0 and perfect predictions have a score of 1.
- Class balanced accuracy as described in [Mosley2013]: the minimum between the precision and the recall for each class is computed. Those values are then averaged over the total number of classes to get the balanced accuracy.
• Balanced Accuracy as described in [Urbanowicz2015]: the average of sensitivity and specificity is computed for each class and then averaged over total number of classes.

References:

Cohen’s kappa

The function cohen_kappa_score computes Cohen’s kappa statistic. This measure is intended to compare labelings by different human annotators, not a classifier versus a ground truth.

The kappa score (see docstring) is a number between -1 and 1. Scores above .8 are generally considered good agreement; zero or lower means no agreement (practically random labels).

Kappa scores can be computed for binary or multiclass problems, but not for multilabel problems (except by manually computing a per-label score) and not for more than two annotators.

```python
>>> from sklearn.metrics import cohen_kappa_score
>>> y_true = [2, 0, 2, 2, 0, 1]
>>> y_pred = [0, 0, 2, 2, 0, 2]
>>> cohen_kappa_score(y_true, y_pred)
0.4285714285714286
```

Confusion matrix

The confusion_matrix function evaluates classification accuracy by computing the confusion matrix with each row corresponding to the true class (Wikipedia and other references may use different convention for axes).

By definition, entry $i, j$ in a confusion matrix is the number of observations actually in group $i$, but predicted to be in group $j$. Here is an example:

```python
>>> from sklearn.metrics import confusion_matrix
>>> y_true = [2, 0, 2, 2, 0, 1]
>>> y_pred = [0, 0, 2, 2, 0, 2]
>>> confusion_matrix(y_true, y_pred)
array([[2, 0, 0],
       [0, 0, 1],
       [1, 0, 2]])
```

plot_confusion_matrix can be used to visually represent a confusion matrix as shown in the Confusion matrix example, which creates the following figure:
The parameter `normalize` allows to report ratios instead of counts. The confusion matrix can be normalized in 3 different ways: 'pred', 'true', and 'all' which will divide the counts by the sum of each columns, rows, or the entire matrix, respectively.

```python
>>> y_true = [0, 0, 0, 1, 1, 1, 1, 1]
>>> y_pred = [0, 1, 0, 1, 0, 1, 0, 1]
>>> confusion_matrix(y_true, y_pred, normalize='all')
array([[0.25 , 0.125],
       [0.25 , 0.375]])
```

For binary problems, we can get counts of true negatives, false positives, false negatives and true positives as follows:

```python
>>> y_true = [0, 0, 0, 1, 1, 1, 1, 1]
>>> y_pred = [0, 1, 0, 1, 0, 1, 0, 1]
>>> tn, fp, fn, tp = confusion_matrix(y_true, y_pred).ravel()
>>> tn, fp, fn, tp
(2, 1, 2, 3)
```

Example:

- See `Confusion matrix` for an example of using a confusion matrix to evaluate classifier output quality.
- See `Recognizing hand-written digits` for an example of using a confusion matrix to classify hand-written digits.
- See `Classification of text documents using sparse features` for an example of using a confusion matrix to classify text documents.
Classification report

The `classification_report` function builds a text report showing the main classification metrics. Here is a small example with custom `target_names` and inferred labels:

```python
>>> from sklearn.metrics import classification_report
>>> y_true = [0, 1, 2, 2, 0]
>>> y_pred = [0, 0, 2, 1, 0]
>>> target_names = ['class 0', 'class 1', 'class 2']
>>> print(classification_report(y_true, y_pred, target_names=target_names))

                   precision    recall  f1-score   support

  class 0       0.67      1.00      0.80         2
  class 1       0.00      0.00      0.00         1
  class 2       1.00      0.50      0.67         2

   accuracy                          0.60         5
macro avg       0.56      0.50      0.49         5
weighted avg    0.67      0.60      0.59         5
```

Example:

- See Recognizing hand-written digits for an example of classification report usage for hand-written digits.
- See Classification of text documents using sparse features for an example of classification report usage for text documents.
- See Parameter estimation using grid search with cross-validation for an example of classification report usage for grid search with nested cross-validation.

Hamming loss

The `hamming_loss` computes the average Hamming loss or Hamming distance between two sets of samples.

If $\hat{y}_j$ is the predicted value for the $j$-th label of a given sample, $y_j$ is the corresponding true value, and $n_{\text{labels}}$ is the number of classes or labels, then the Hamming loss $L_{\text{Hamming}}$ between two samples is defined as:

$$L_{\text{Hamming}}(y, \hat{y}) = \frac{1}{n_{\text{labels}}} \sum_{j=0}^{n_{\text{labels}}-1} 1(\hat{y}_j \neq y_j)$$

where $1(x)$ is the indicator function.

```python
>>> from sklearn.metrics import hamming_loss
>>> y_pred = [1, 2, 3, 4]
>>> y_true = [2, 2, 3, 4]
>>> hamming_loss(y_true, y_pred)
0.25
```

In the multilabel case with binary label indicators:

```python
>>> hamming_loss(np.array([[0, 1], [1, 1]]), np.zeros((2, 2)))
0.75
```
Note: In multiclass classification, the Hamming loss corresponds to the Hamming distance between y_true and y_pred which is similar to the Zero one loss function. However, while zero-one loss penalizes prediction sets that do not strictly match true sets, the Hamming loss penalizes individual labels. Thus the Hamming loss, upper bounded by the zero-one loss, is always between zero and one, inclusive; and predicting a proper subset or superset of the true labels will give a Hamming loss between zero and one, exclusive.

Precision, recall and F-measures

Intuitively, precision is the ability of the classifier not to label as positive a sample that is negative, and recall is the ability of the classifier to find all the positive samples.

The F-measure ($F_{\beta}$ and $F_1$ measures) can be interpreted as a weighted harmonic mean of the precision and recall. A $F_{\beta}$ measure reaches its best value at 1 and its worst score at 0. With $\beta = 1$, $F_{\beta}$ and $F_1$ are equivalent, and the recall and the precision are equally important.

The precision_recall_curve computes a precision-recall curve from the ground truth label and a score given by the classifier by varying a decision threshold.

The average_precision_score function computes the average precision (AP) from prediction scores. The value is between 0 and 1 and higher is better. AP is defined as

$$AP = \sum_{n} (R_n - R_{n-1}) P_n$$

where $P_n$ and $R_n$ are the precision and recall at the nth threshold. With random predictions, the AP is the fraction of positive samples.

References [Manning2008] and [Everingham2010] present alternative variants of AP that interpolate the precision-recall curve. Currently, average_precision_score does not implement any interpolated variant. References [Davis2006] and [Flach2015] describe why a linear interpolation of points on the precision-recall curve provides an overly-optimistic measure of classifier performance. This linear interpolation is used when computing area under the curve with the trapezoidal rule in auc.

Several functions allow you to analyze the precision, recall and F-measures score:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>average_precision_score(y_true, y_score, *)</td>
<td>Compute average precision (AP) from prediction scores.</td>
</tr>
<tr>
<td>f1_score(y_true, y_pred, *[labels, ...])</td>
<td>Compute the F1 score, also known as balanced F-score or F-measure.</td>
</tr>
<tr>
<td>fbeta_score(y_true, y_pred, *[beta[, ...]])</td>
<td>Compute the F-beta score.</td>
</tr>
<tr>
<td>precision_recall_curve(y_true, probas_pred, *)</td>
<td>Compute precision-recall pairs for different probability thresholds.</td>
</tr>
<tr>
<td>precision_recall_fscore_support(y_true, ...)</td>
<td>Compute precision, recall, F-measure and support for each class.</td>
</tr>
<tr>
<td>precision_score(y_true, y_pred, *[labels, ...])</td>
<td>Compute the precision.</td>
</tr>
<tr>
<td>recall_score(y_true, y_pred, *[labels, ...])</td>
<td>Compute the recall.</td>
</tr>
</tbody>
</table>

Note that the precision_recall_curve function is restricted to the binary case. The average_precision_score function works only in binary classification and multilabel indicator format. The plot_precision_recall_curve function plots the precision recall as follows.
Examples:

- See `Classification of text documents using sparse features` for an example of `f1_score` usage to classify text documents.
- See `Parameter estimation using grid search with cross-validation` for an example of `precision_score` and `recall_score` usage to estimate parameters using grid search with nested cross-validation.
- See `Precision-Recall` for an example of `precision_recall_curve` usage to evaluate classifier output quality.

References:

Binary classification

In a binary classification task, the terms “positive” and “negative” refer to the classifier’s prediction, and the terms “true” and “false” refer to whether that prediction corresponds to the external judgment (sometimes known as the “observation”). Given these definitions, we can formulate the following table:

<table>
<thead>
<tr>
<th>Actual class (observation)</th>
<th>Predicted class (expectation)</th>
</tr>
</thead>
<tbody>
<tr>
<td>tp (true positive) Correct result</td>
<td>fp (false positive) Unexpected result</td>
</tr>
<tr>
<td>fn (false negative) Missing result</td>
<td>tn (true negative) Correct absence of result</td>
</tr>
</tbody>
</table>

In this context, we can define the notions of precision, recall and F-measure:

\[
\text{precision} = \frac{tp}{tp + fp},
\]
Here are some small examples in binary classification:

```python
>>> from sklearn import metrics
>>> y_pred = [0, 1, 0, 0]
>>> y_true = [0, 1, 0, 1]
>>> metrics.precision_score(y_true, y_pred)
1.0
>>> metrics.recall_score(y_true, y_pred)
0.5
>>> metrics.f1_score(y_true, y_pred)
0.66...
>>> metrics.fbeta_score(y_true, y_pred, beta=0.5)
0.83...
>>> metrics.fbeta_score(y_true, y_pred, beta=1)
0.66...
>>> metrics.fbeta_score(y_true, y_pred, beta=2)
0.55...
>>> metrics.precision_recall_fscore_support(y_true, y_pred, beta=0.5)
(array([0.66..., 1.]), array([1., 0.5]), array([0.71..., 0.83...]), array([2, 2]))
```

```python
>>> import numpy as np
>>> from sklearn.metrics import precision_recall_curve
>>> from sklearn.metrics import average_precision_score
>>> y_true = np.array([0, 0, 1, 1])
>>> y_scores = np.array([0.1, 0.4, 0.35, 0.8])
>>> precision, recall, threshold = precision_recall_curve(y_true, y_scores)
>>> precision
array([0.66..., 0.5 , 1. , 1. ])
>>> recall
array([1. , 0.5, 0.5, 0. ])
>>> threshold
array([0.35, 0.4 , 0.8 ])
>>> average_precision_score(y_true, y_scores)
0.83...
```

### Multiclass and multilabel classification

In multiclass and multilabel classification task, the notions of precision, recall, and F-measures can be applied to each label independently. There are a few ways to combine results across labels, specified by the `average` argument to the `average_precision_score` (multilabel only), `f1_score`, `fbeta_score`, `precision_recall_fscore_support`, `precision_score`, and `recall_score` functions, as described above. Note that if all labels are included, “micro”-averaging in a multiclass setting will produce precision, recall and $F$ that are all identical to accuracy. Also note that “weighted” averaging may produce an F-score that is not between precision and recall.

To make this more explicit, consider the following notation:

- $y$ the set of predicted $(sample, label)$ pairs
- $\hat{y}$ the set of true $(sample, label)$ pairs
• \( L \) the set of labels
• \( S \) the set of samples
• \( y_s \) the subset of \( y \) with sample \( s \), i.e. \( y_s := \{(s', l) \mid s' = s\} \)
• \( y_l \) the subset of \( y \) with label \( l \)
• similarly, \( \hat{y}_s \) and \( \hat{y}_l \) are subsets of \( \hat{y} \)

\[
P(A, B) := \frac{|A \cap B|}{|A|} \text{ for some sets } A \text{ and } B
\]

\[
R(A, B) := \frac{|A \cap B|}{|B|} \text{ (Conventions vary on handling } B = \emptyset; \text{ this implementation uses } R(A, B) := 0, \text{ and similar for } P.\)
\]

\[
F_\beta(A, B) := \left(1 + \beta^2 \right) \frac{P(A, B) \times R(A, B)}{P(A, B) + \beta^2 R(A, B)}
\]

Then the metrics are defined as:

<table>
<thead>
<tr>
<th>average</th>
<th>Precision</th>
<th>Recall</th>
<th>F_beta</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;micro&quot;</td>
<td>( P(y, \hat{y}) )</td>
<td>( R(y, \hat{y}) )</td>
<td>( F_\beta(y, \hat{y}) )</td>
</tr>
<tr>
<td>&quot;samples&quot;</td>
<td>( \frac{1}{</td>
<td>S</td>
<td>} \sum_{s \in S} P(y_s, \hat{y}_s) )</td>
</tr>
<tr>
<td>&quot;macro&quot;</td>
<td>( \frac{1}{</td>
<td>L</td>
<td>} \sum_{l \in L} P(y_l, \hat{y}_l) )</td>
</tr>
<tr>
<td>&quot;weighted&quot;</td>
<td>( \frac{1}{\sum_{l \in L}</td>
<td>\hat{y}_l</td>
<td>} \sum_{l \in L} \frac{1}{</td>
</tr>
<tr>
<td>None</td>
<td>( \langle P(y_l, \hat{y}<em>l) \rangle</em>{l \in L} )</td>
<td>( \langle R(y_l, \hat{y}<em>l) \rangle</em>{l \in L} )</td>
<td>( \langle F_\beta(y_l, \hat{y}<em>l) \rangle</em>{l \in L} )</td>
</tr>
</tbody>
</table>

```python
>>> from sklearn import metrics
>>> y_true = [0, 1, 2, 0, 1, 2]
>>> y_pred = [0, 2, 1, 0, 0, 1]
>>> metrics.precision_score(y_true, y_pred, average='macro')
0.22...
>>> metrics.recall_score(y_true, y_pred, average='micro')
0.22...
>>> metrics.recall_score(y_true, y_pred, average='weighted')
0.23...
>>> metrics.precision_score(y_true, y_pred, average='macro', beta=0.5)
0.23...
>>> metrics.recall_score(y_true, y_pred, labels=[1, 2], average='micro')
0.0
```

For multiclass classification with a “negative class”, it is possible to exclude some labels:

```python
>>> metrics.recall_score(y_true, y_pred, labels=[1, 2], average='micro')
... # excluding 0, no labels were correctly recalled
0.0
```

Similarly, labels not present in the data sample may be accounted for in macro-averaging.

```python
>>> metrics.recall_score(y_true, y_pred, labels=[0, 1, 2, 3], average='macro')
0.166...
```
Jaccard similarity coefficient score

The \texttt{jaccard\_score} function computes the average of Jaccard similarity coefficients, also called the Jaccard index, between pairs of label sets.

The Jaccard similarity coefficient of the \(i\)-th samples, with a ground truth label set \(y_i\) and predicted label set \(\hat{y}_i\), is defined as

\[
J(y_i, \hat{y}_i) = \frac{|y_i \cap \hat{y}_i|}{|y_i \cup \hat{y}_i|}.
\]

\texttt{jaccard\_score} works like \texttt{precision\_recall\_fscore\_support} as a naively set-wise measure applying natively to binary targets, and extended to apply to multilabel and multiclass through the use of \texttt{average} (see above).

In the binary case:

```python
>>> import numpy as np
>>> from sklearn.metrics import jaccard_score
>>> y_true = np.array([[0, 1, 1], ...
... [1, 1, 0]])
>>> y_pred = np.array([[1, 1, 1], ...
... [1, 0, 0]])
>>> jaccard_score(y_true[0], y_pred[0])
0.6666...
```

In the multilabel case with binary label indicators:

```python
>>> jaccard_score(y_true, y_pred, average='samples')
0.5833...
>>> jaccard_score(y_true, y_pred, average='macro')
0.6666...
>>> jaccard_score(y_true, y_pred, average=None)
array([0.5, 0.5, 1.])
```

Multiclass problems are binarized and treated like the corresponding multilabel problem:

```python
>>> y_pred = [0, 2, 1, 2]
>>> y_true = [0, 1, 2, 2]
>>> jaccard_score(y_true, y_pred, average=None)
array([1. , 0. , 0.33...])
>>> jaccard_score(y_true, y_pred, average='macro')
0.44...
>>> jaccard_score(y_true, y_pred, average='micro')
0.33...
```

Hinge loss

The \texttt{hinge\_loss} function computes the average distance between the model and the data using hinge loss, a one-sided metric that considers only prediction errors. (Hinge loss is used in maximal margin classifiers such as support vector machines.)

If the labels are encoded with +1 and -1, \(y\) is the true value, and \(w\) is the predicted decisions as output by \texttt{decision\_function}, then the hinge loss is defined as:

\[
L_{\text{Hinge}}(y, w) = \max \{ 1 - wy, 0 \} = |1 - wy|_+
\]

If there are more than two labels, \texttt{hinge\_loss} uses a multiclass variant due to Crammer & Singer. Here is the paper describing it.
If $y_w$ is the predicted decision for true label and $y_t$ is the maximum of the predicted decisions for all other labels, where predicted decisions are output by decision function, then multiclass hinge loss is defined by:

$$L_{\text{Hinge}}(y_w, y_t) = \max \{1 + y_t - y_w, 0\}$$

Here a small example demonstrating the use of the `hinge_loss` function with a svm classifier in a binary class problem:

```python
>>> from sklearn import svm
>>> from sklearn.metrics import hinge_loss

>>> X = [[0], [1]]
>>> y = [-1, 1]
>>> est = svm.LinearSVC(random_state=0)
>>> est.fit(X, y)
LinearSVC(random_state=0)
>>> pred_decision = est.decision_function([[-2], [3], [0.5]])
>>> pred_decision
array([-2.18..., 2.36..., 0.09...])
```

Here is an example demonstrating the use of the `hinge_loss` function with a svm classifier in a multiclass problem:

```python
>>> X = np.array([[0], [1], [2], [3]])
>>> Y = np.array([0, 1, 2, 3])
>>> labels = np.array([0, 1, 2, 3])
>>> est = svm.LinearSVC()
>>> est.fit(X, Y)
LinearSVC()
>>> pred_decision = est.decision_function([[-1], [2], [3]])
>>> y_true = [0, 2, 3]
>>> hinge_loss(y_true, pred_decision, labels)
0.56...
```

### Log loss

Log loss, also called logistic regression loss or cross-entropy loss, is defined on probability estimates. It is commonly used in ( multinomial ) logistic regression and neural networks, as well as in some variants of expectation-maximization, and can be used to evaluate the probability outputs ( `predict_proba` ) of a classifier instead of its discrete predictions.

For binary classification with a true label $y \in \{0, 1\}$ and a probability estimate $p = \Pr(y = 1)$, the log loss per sample is the negative log-likelihood of the classifier given the true label:

$$L_{\log}(y, p) = -\log \Pr(y|p) = -(y \log(p) + (1 - y) \log(1 - p))$$

This extends to the multiclass case as follows. Let the true labels for a set of samples be encoded as a 1-of-K binary indicator matrix $Y$, i.e., $y_{i,k} = 1$ if sample $i$ has label $k$ taken from a set of $K$ labels. Let $P$ be a matrix of probability estimates, with $p_{i,k} = \Pr(y_{i,k} = 1)$. Then the log loss of the whole set is

$$L_{\log}(Y, P) = -\log \Pr(Y|P) = -\frac{1}{N} \sum_{i=0}^{N-1} \sum_{k=0}^{K-1} y_{i,k} \log p_{i,k}$$

To see how this generalizes the binary log loss given above, note that in the binary case, $p_{i,0} = 1 - p_{i,1}$ and $y_{i,0} = 1 - y_{i,1}$, so expanding the inner sum over $y_{i,k} \in \{0, 1\}$ gives the binary log loss.

The `log_loss` function computes log loss given a list of ground-truth labels and a probability matrix, as returned by an estimator’s `predict_proba` method.
```
>>> from sklearn.metrics import log_loss
>>> y_true = [0, 0, 1, 1]
>>> y_pred = [[.9, .1], [.8, .2], [.3, .7], [.01, .99]]
>>> log_loss(y_true, y_pred)
0.1738...
```

The first [.9, .1] in `y_pred` denotes 90% probability that the first sample has label 0. The log loss is non-negative.

**Matthews correlation coefficient**

The `matthews_corrcoef` function computes the Matthew’s correlation coefficient (MCC) for binary classes. Quoting Wikipedia:

“The Matthews correlation coefficient is used in machine learning as a measure of the quality of binary (two-class) classifications. It takes into account true and false positives and negatives and is generally regarded as a balanced measure which can be used even if the classes are of very different sizes. The MCC is in essence a correlation coefficient value between -1 and +1. A coefficient of +1 represents a perfect prediction, 0 an average random prediction and -1 an inverse prediction. The statistic is also known as the phi coefficient.”

In the binary (two-class) case, `tp`, `tn`, `fp` and `fn` are respectively the number of true positives, true negatives, false positives and false negatives, the MCC is defined as

\[
MCC = \frac{tp \times tn - fp \times fn}{\sqrt{(tp + fp)(tp + fn)(tn + fp)(tn + fn)}}.
\]

In the multiclass case, the Matthews correlation coefficient can be defined in terms of a confusion matrix `C` for `K` classes. To simplify the definition consider the following intermediate variables:

- `t_k = \sum^K_i C_{ik}` the number of times class `k` truly occurred,
- `p_k = \sum^K_i C_{ki}` the number of times class `k` was predicted,
- `c = \sum^K_k C_{kk}` the total number of samples correctly predicted,
- `s = \sum^K_i \sum^K_j C_{ij}` the total number of samples.

Then the multiclass MCC is defined as:

\[
MCC = \frac{c \times s - \sum^K_k p_k \times t_k}{\sqrt{(s^2 - \sum^K_k p_k^2) \times (s^2 - \sum^K_k t_k^2)}}
\]

When there are more than two labels, the value of the MCC will no longer range between -1 and +1. Instead the minimum value will be somewhere between -1 and 0 depending on the number and distribution of ground true labels. The maximum value is always +1.

Here is a small example illustrating the usage of the `matthews_corrcoef` function:

```
>>> from sklearn.metrics import matthews_corrcoef
>>> y_true = [+1, +1, -1, -1]
>>> y_pred = [+1, -1, +1, +1]
>>> matthews_corrcoef(y_true, y_pred)
-0.33...
```
Multi-label confusion matrix

The `multilabel_confusion_matrix` function computes class-wise (default) or sample-wise (sample-wise=True) multilabel confusion matrix to evaluate the accuracy of a classification. `multilabel_confusion_matrix` also treats multiclass data as if it were multilabel, as this is a transformation commonly applied to evaluate multiclass problems with binary classification metrics (such as precision, recall, etc.).

When calculating class-wise multilabel confusion matrix $C$, the count of true negatives for class $i$ is $C_{i,0,0}$, false negatives is $C_{i,0,1}$, true positives is $C_{i,1,1}$ and false positives is $C_{i,1,0}$.

Here is an example demonstrating the use of the `multilabel_confusion_matrix` function with multilabel indicator matrix input:

```python
>>> import numpy as np
>>> from sklearn.metrics import multilabel_confusion_matrix
>>> y_true = np.array([[1, 0, 1], ...
> [0, 1, 0]])
>>> y_pred = np.array([[1, 0, 0], ...
> [0, 1, 1]])
>>> multilabel_confusion_matrix(y_true, y_pred)
array([[1, 0],
[0, 1]])
```

Or a confusion matrix can be constructed for each sample’s labels:

```python
>>> multilabel_confusion_matrix(y_true, y_pred, samplewise=True)
array([[1, 1],
[1, 0]])
```

Here is an example demonstrating the use of the `multilabel_confusion_matrix` function with multiclass input:

```python
>>> y_true = ["cat", "ant", "cat", "ant", "bird"]
>>> y_pred = ["ant", "ant", "cat", "ant", "cat"]
>>> multilabel_confusion_matrix(y_true, y_pred,
> ... labels=["ant", "bird", "cat"])
array([[3, 1],
[0, 2]],
[[5, 0],
[1, 0]],
[[2, 1],
[1, 2]])
```

Here are some examples demonstrating the use of the `multilabel_confusion_matrix` function to calculate recall (or sensitivity), specificity, fall out and miss rate for each class in a problem with multilabel indicator matrix input.

Calculating recall (also called the true positive rate or the sensitivity) for each class:
Calculating specificity (also called the true negative rate) for each class:

```python
>>> tn / (tn + fp)
array([1.0, 0.0, 0.5])
```

Calculating fall out (also called the false positive rate) for each class:

```python
>>> fp / (fp + tn)
array([0.0, 1.0, 0.5])
```

Calculating miss rate (also called the false negative rate) for each class:

```python
>>> fn / (fn + tp)
array([0.0, 0.5, 1.0])
```

### Receiver operating characteristic (ROC)

The function `roc_curve` computes the receiver operating characteristic curve, or ROC curve. Quoting Wikipedia:

“A receiver operating characteristic (ROC), or simply ROC curve, is a graphical plot which illustrates the performance of a binary classifier system as its discrimination threshold is varied. It is created by plotting the fraction of true positives out of the positives (TPR = true positive rate) vs. the fraction of false positives out of the negatives (FPR = false positive rate), at various threshold settings. TPR is also known as sensitivity, and FPR is one minus the specificity or true negative rate.”

This function requires the true binary value and the target scores, which can either be probability estimates of the positive class, confidence values, or binary decisions. Here is a small example of how to use the `roc_curve` function:

```python
>>> from sklearn.metrics import roc_curve
>>> y = np.array([1, 1, 2, 2])
>>> scores = np.array([0.1, 0.4, 0.35, 0.8])
>>> fpr, tpr, thresholds = roc_curve(y, scores, pos_label=2)
>>> fpr
array([0.0, 0.0, 0.5, 0.5, 1.0])
>>> tpr
array([0.0, 0.5, 0.5, 1.0, 1.0])
>>> thresholds
array([1.8, 0.8, 0.4, 0.35, 0.1])
```

This figure shows an example of such an ROC curve:
The `roc_auc_score` function computes the area under the receiver operating characteristic (ROC) curve, which is also denoted by AUC or AUROC. By computing the area under the roc curve, the curve information is summarized in one number. For more information see the Wikipedia article on AUC.

Compared to metrics such as the subset accuracy, the Hamming loss, or the F1 score, ROC doesn’t require optimizing a threshold for each label.

**Binary case**

In the binary case, you can either provide the probability estimates, using the `classifier.predict_proba()` method, or the non-thresholded decision values given by the `classifier.decision_function()` method. In the case of providing the probability estimates, the probability of the class with the “greater label” should be provided. The “greater label” corresponds to `classifier.classes_[1]` and thus `classifier.predict_proba(X)[:, 1]`. Therefore, the `y_score` parameter is of size (n_samples,).

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.metrics import roc_auc_score
>>> X, y = load_breast_cancer(return_X_y=True)
>>> clf = LogisticRegression(solver="liblinear").fit(X, y)
>>> clf.classes_
array([0, 1])

We can use the probability estimates corresponding to `clf.classes_[1].`

```python
>>> y_score = clf.predict_proba(X)[:, 1]
>>> roc_auc_score(y, y_score)
0.99...
```

Otherwise, we can use the non-thresholded decision values
Multi-class case

The `roc_auc_score` function can also be used in multi-class classification. Two averaging strategies are currently supported: the one-vs-one algorithm computes the average of the pairwise ROC AUC scores, and the one-vs-rest algorithm computes the average of the ROC AUC scores for each class against all other classes. In both cases, the predicted labels are provided in an array with values from 0 to `n_classes`, and the scores correspond to the probability estimates that a sample belongs to a particular class. The OvO and OvR algorithms support weighting uniformly (average='macro') and by prevalence (average='weighted').

**One-vs-one Algorithm:** Computes the average AUC of all possible pairwise combinations of classes. [HT2001] defines a multiclass AUC metric weighted uniformly:

$$\frac{1}{c(c-1)} \sum_{j=1}^{c} \sum_{k>j}^{c} (\text{AUC}(j|k) + \text{AUC}(k|j))$$

where $c$ is the number of classes and $\text{AUC}(j|k)$ is the AUC with class $j$ as the positive class and class $k$ as the negative class. In general, $\text{AUC}(j|k) \neq \text{AUC}(k|j)$ in the multiclass case. This algorithm is used by setting the keyword argument `multiclass` to 'ovo' and `average` to 'macro'.

The [HT2001] multiclass AUC metric can be extended to be weighted by the prevalence:

$$\frac{1}{c(c-1)} \sum_{j=1}^{c} \sum_{k>j}^{c} p(j \cup k) (\text{AUC}(j|k) + \text{AUC}(k|j))$$

where $c$ is the number of classes. This algorithm is used by setting the keyword argument `multiclass` to 'ovo' and `average` to 'weighted'. The 'weighted' option returns a prevalence-weighted average as described in [FC2009].

**One-vs-rest Algorithm:** Computes the AUC of each class against the rest [PD2000]. The algorithm is functionally the same as the multilabel case. To enable this algorithm set the keyword argument `multiclass` to 'ovr'. Like OvO, OvR supports two types of averaging: 'macro' [F2006] and 'weighted' [F2001].

In applications where a high false positive rate is not tolerable the parameter `max_fpr` of `roc_auc_score` can be used to summarize the ROC curve up to the given limit.
Multi-label case

In multi-label classification, the roc_auc_score function is extended by averaging over the labels as above. In this case, you should provide a y_score of shape (n_samples, n_classes). Thus, when using the probability estimates, one needs to select the probability of the class with the greater label for each output.

```python
>>> from sklearn.datasets import make_multilabel_classification
>>> from sklearn.multioutput import MultiOutputClassifier

>>> X, y = make_multilabel_classification(random_state=0)

>>> inner_clf = LogisticRegression(solver="liblinear", random_state=0)

>>> clf = MultiOutputClassifier(inner_clf).fit(X, y)

>>> y_score = np.transpose([y_pred[:, 1] for y_pred in clf.predict_proba(X)])

>>> roc_auc_score(y, y_score, average=None)
array([0.82..., 0.86..., 0.94..., 0.85..., 0.94...])
```

And the decision values do not require such processing.

```python
>>> from sklearn.linear_model import RidgeClassifierCV

>>> clf = RidgeClassifierCV().fit(X, y)

>>> y_score = clf.decision_function(X)

>>> roc_auc_score(y, y_score, average=None)
array([0.81..., 0.84..., 0.93..., 0.87..., 0.94...])
```

Examples:

- See Receiver Operating Characteristic (ROC) for an example of using ROC to evaluate the quality of the output of a classifier.
- See Receiver Operating Characteristic (ROC) with cross validation for an example of using ROC to evaluate classifier output quality, using cross-validation.
Detection error tradeoff (DET)

The function `det_curve` computes the detection error tradeoff curve (DET) curve [WikipediaDET2017]. Quoting Wikipedia:

“A detection error tradeoff (DET) graph is a graphical plot of error rates for binary classification systems, plotting false reject rate vs. false accept rate. The x- and y-axes are scaled non-linearly by their standard normal deviates (or just by logarithmic transformation), yielding tradeoff curves that are more linear than ROC curves, and use most of the image area to highlight the differences of importance in the critical operating region.”

DET curves are a variation of receiver operating characteristic (ROC) curves where False Negative Rate is plotted on the y-axis instead of True Positive Rate. DET curves are commonly plotted in normal deviate scale by transformation with $\phi^{-1}$ (with $\phi$ being the cumulative distribution function). The resulting performance curves explicitly visualize the tradeoff of error types for given classification algorithms. See [Martin1997] for examples and further motivation.

This figure compares the ROC and DET curves of two example classifiers on the same classification task:

Properties:

- DET curves form a linear curve in normal deviate scale if the detection scores are normally (or close-to normally) distributed. It was shown by [Navratil2007] that the reverse it not necessarily true and even more general distributions are able produce linear DET curves.
- The normal deviate scale transformation spreads out the points such that a comparatively larger space of plot is occupied. Therefore curves with similar classification performance might be easier to distinguish on a DET plot.
- With False Negative Rate being “inverse” to True Positive Rate the point of perfection for DET curves is the origin (in contrast to the top left corner for ROC curves).
Applications and limitations:

DET curves are intuitive to read and hence allow quick visual assessment of a classifier’s performance. Additionally DET curves can be consulted for threshold analysis and operating point selection. This is particularly helpful if a comparison of error types is required.

One the other hand DET curves do not provide their metric as a single number. Therefore for either automated evaluation or comparison to other classification tasks metrics like the derived area under ROC curve might be better suited.

Examples:

- See Detection error tradeoff (DET) curve for an example comparison between receiver operating characteristic (ROC) curves and Detection error tradeoff (DET) curves.

References:

Zero one loss

The zero_one_loss function computes the sum or the average of the 0-1 classification loss ($L_{0-1}$) over $n_{\text{samples}}$. By default, the function normalizes over the sample. To get the sum of the $L_{0-1}$, set normalize to False.

In multilabel classification, the zero_one_loss scores a subset as one if its labels strictly match the predictions, and as a zero if there are any errors. By default, the function returns the percentage of imperfectly predicted subsets. To get the count of such subsets instead, set normalize to False.

If $\hat{y}_i$ is the predicted value of the $i$-th sample and $y_i$ is the corresponding true value, then the 0-1 loss $L_{0-1}$ is defined as:

$$L_{0-1}(y_i, \hat{y}_i) = 1(\hat{y}_i \neq y_i)$$

where $1(x)$ is the indicator function.

```python
>>> from sklearn.metrics import zero_one_loss
>>> y_pred = [1, 2, 3, 4]
>>> y_true = [2, 2, 3, 4]
>>> zero_one_loss(y_true, y_pred)
0.25
>>> zero_one_loss(y_true, y_pred, normalize=False)
1
```

In the multilabel case with binary label indicators, where the first label set [0,1] has an error:

```python
>>> zero_one_loss(np.array([[0, 1], [1, 1]]), np.ones((2, 2)))
0.5
>>> zero_one_loss(np.array([[0, 1], [1, 1]]), np.ones((2, 2)), normalize=False)
1
```
Brier score loss

The `brier_score_loss` function computes the Brier score for binary classes [Brier1950]. Quoting Wikipedia:

“The Brier score is a proper score function that measures the accuracy of probabilistic predictions. It is applicable to tasks in which predictions must assign probabilities to a set of mutually exclusive discrete outcomes.”

This function returns the mean squared error of the actual outcome $y \in \{0, 1\}$ and the predicted probability estimate $p = \Pr(y = 1)$ (predict_proba) as outputted by:

$$BS = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} (y_i - p_i)^2$$

The Brier score loss is also between 0 to 1 and the lower the value (the mean square difference is smaller), the more accurate the prediction is.

Here is a small example of usage of this function:

```python
>>> import numpy as np
>>> from sklearn.metrics import brier_score_loss
>>> y_true = np.array([0, 1, 1, 0])
>>> y_true_categorical = np.array(['spam', 'ham', 'ham', 'spam'])
>>> y_prob = np.array([0.1, 0.9, 0.8, 0.4])
>>> y_pred = np.array([0, 1, 1, 0])
>>> brier_score_loss(y_true, y_prob)
0.055
>>> brier_score_loss(y_true, 1 - y_prob, pos_label=0)
0.055
>>> brier_score_loss(y_true_categorical, y_prob, pos_label='ham')
0.055
>>> brier_score_loss(y_true, y_prob > 0.5)
0.0
```

The Brier score can be used to assess how well a classifier is calibrated. However, a lower Brier score loss does not always mean a better calibration. This is because, by analogy with the bias-variance decomposition of the mean squared error, the Brier score loss can be decomposed as the sum of calibration loss and refinement loss [Bella2012]. Calibration loss is defined as the mean squared deviation from empirical probabilities derived from the slope of ROC segments. Refinement loss can be defined as the expected optimal loss as measured by the area under the optimal cost curve. Refinement loss can change independently from calibration loss, thus a lower Brier score loss does not necessarily mean a better calibrated model. “Only when refinement loss remains the same does a lower Brier score loss always mean better calibration” [Bella2012], [Flach2008].
References:

Multilabel ranking metrics

In multilabel learning, each sample can have any number of ground truth labels associated with it. The goal is to give high scores and better rank to the ground truth labels.

Coverage error

The \texttt{coverage_error} function computes the average number of labels that have to be included in the final prediction such that all true labels are predicted. This is useful if you want to know how many top-scored-labels you have to predict in average without missing any true one. The best value of this metrics is thus the average number of true labels.

Note: Our implementation’s score is 1 greater than the one given in Tsoumakas et al., 2010. This extends it to handle the degenerate case in which an instance has 0 true labels.

Formally, given a binary indicator matrix of the ground truth labels $y \in \{0, 1\}^{n_{\text{samples}} \times n_{\text{labels}}}$ and the score associated with each label $\hat{f} \in \mathbb{R}^{n_{\text{samples}} \times n_{\text{labels}}}$, the coverage is defined as

$$
\text{coverage}(y, \hat{f}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} \max_{j:y_{ij} = 1} \text{rank}_{ij}
$$

with \text{rank}_{ij} = \left| \left\{ k : \hat{f}_{ik} \geq \hat{f}_{ij} \right\} \right|$. Given the rank definition, ties in \texttt{y_scores} are broken by giving the maximal rank that would have been assigned to all tied values.

Here is a small example of usage of this function:

```python
>>> import numpy as np
>>> from sklearn.metrics import coverage_error
>>> y_true = np.array([[1, 0, 0], [0, 0, 1]])
>>> y_score = np.array([[0.75, 0.5, 1], [1, 0.2, 0.1]])
>>> coverage_error(y_true, y_score)
2.5
```

Label ranking average precision

The \texttt{label_ranking_average_precision_score} function implements label ranking average precision (LRAP). This metric is linked to the \texttt{average_precision_score} function, but is based on the notion of label ranking instead of precision and recall.

Label ranking average precision (LRAP) averages over the samples the answer to the following question: for each ground truth label, what fraction of higher-ranked labels were true labels? This performance measure will be higher if you are able to give better rank to the labels associated with each sample. The obtained score is always strictly greater than 0, and the best value is 1. If there is exactly one relevant label per sample, label ranking average precision is equivalent to the mean reciprocal rank.

4.3. Model selection and evaluation
Formally, given a binary indicator matrix of the ground truth labels \( y \in \{0, 1\}^{n_{\text{samples}} \times n_{\text{labels}}} \) and the score associated with each label \( \hat{f} \in \mathbb{R}^{n_{\text{samples}} \times n_{\text{labels}}} \), the average precision is defined as

\[
LRAP(y, \hat{f}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} \frac{1}{||y_i||_0} \sum_{j:y_{ij}=1} ||\mathcal{L}_{ij}||_{\text{rank}_{ij}}
\]

where \( \mathcal{L}_{ij} = \{ k : y_{ik} = 1, \hat{f}_{ik} \geq \hat{f}_{ij} \} \), \( \text{rank}_{ij} = \left| \left\{ k : \hat{f}_{ik} \geq \hat{f}_{ij}, y_{ik} = 1, y_{il} = 0 \right\} \right| \) computes the cardinality of the set (i.e., the number of elements in the set), and \( || \cdot ||_0 \) is the \( \ell_0 \) “norm” (which computes the number of nonzero elements in a vector).

Here is a small example of usage of this function:

```python
>>> from sklearn.metrics import label_ranking_average_precision_score
>>> y_true = np.array([[1, 0, 0], [0, 0, 1]])
>>> y_score = np.array([[0.75, 0.5, 1], [1, 0.2, 0.1]])
>>> label_ranking_average_precision_score(y_true, y_score)
0.416...
```

**Ranking loss**

The `label_ranking_loss` function computes the ranking loss which averages over the samples the number of label pairs that are incorrectly ordered, i.e. true labels have a lower score than false labels, weighted by the inverse of the number of ordered pairs of false and true labels. The lowest achievable ranking loss is zero.

Formally, given a binary indicator matrix of the ground truth labels \( y \in \{0, 1\}^{n_{\text{samples}} \times n_{\text{labels}}} \) and the score associated with each label \( \hat{f} \in \mathbb{R}^{n_{\text{samples}} \times n_{\text{labels}}} \), the ranking loss is defined as

\[
\text{ranking}_\text{loss}(y, \hat{f}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} \frac{1}{||y_i||_0(n_{\text{labels}} - ||y_i||_0)} \left| \left\{ (k, l) : \hat{f}_{ik} \leq \hat{f}_{il}, y_{ik} = 1, y_{il} = 0 \right\} \right|
\]

where \( || \cdot || \) computes the cardinality of the set (i.e., the number of elements in the set) and \( || \cdot ||_0 \) is the \( \ell_0 \) “norm” (which computes the number of nonzero elements in a vector).

Here is a small example of usage of this function:

```python
>>> from sklearn.metrics import label_ranking_loss
>>> y_true = np.array([[1, 0, 0], [0, 0, 1]])
>>> y_score = np.array([[0.75, 0.5, 1], [1, 0.2, 0.1]])
>>> label_ranking_loss(y_true, y_score)
0.75...
>>> y_score = np.array([[1.0, 0.1, 0.2], [0.1, 0.2, 0.9]])
>>> label_ranking_loss(y_true, y_score)
0.0
```

**References:**

Normalized Discounted Cumulative Gain

Discounted Cumulative Gain (DCG) and Normalized Discounted Cumulative Gain (NDCG) are ranking metrics implemented in `dcg_score` and `ndcg_score`; they compare a predicted order to ground-truth scores, such as the relevance of answers to a query.

From the Wikipedia page for Discounted Cumulative Gain:

“Discounted cumulative gain (DCG) is a measure of ranking quality. In information retrieval, it is often used to measure effectiveness of web search engine algorithms or related applications. Using a graded relevance scale of documents in a search-engine result set, DCG measures the usefulness, or gain, of a document based on its position in the result list. The gain is accumulated from the top of the result list to the bottom, with the gain of each result discounted at lower ranks.”

DCG orders the true targets (e.g., relevance of query answers) in the predicted order, then multiplies them by a logarithmic decay and sums the result. The sum can be truncated after the first $K$ results, in which case we call it DCG@K. NDCG, or NDCG@K is DCG divided by the DCG obtained by a perfect prediction, so that it is always between 0 and 1. Usually, NDCG is preferred to DCG.

Compared with the ranking loss, NDCG can take into account relevance scores, rather than a ground-truth ranking. So if the ground-truth consists only of an ordering, the ranking loss should be preferred; if the ground-truth consists of actual usefulness scores (e.g., 0 for irrelevant, 1 for relevant, 2 for very relevant), NDCG can be used.

For one sample, given the vector of continuous ground-truth values for each target $y \in \mathbb{R}^M$, where $M$ is the number of outputs, and the prediction $\hat{y}$, which induces the ranking function $f$, the DCG score is

$$\min(K,M) \sum_{r=1}^{\min(K,M)} \frac{y_f(r)}{\log(1 + r)}$$

and the NDCG score is the DCG score divided by the DCG score obtained for $y$.

References:

- Wikipedia entry for Discounted Cumulative Gain

Regression metrics

The `sklearn.metrics` module implements several loss, score, and utility functions to measure regression performance. Some of those have been enhanced to handle the multioutput case: `mean_squared_error`, `mean_absolute_error`, `explained_variance_score` and `r2_score`.

These functions have an `multioutput` keyword argument which specifies the way the scores or losses for each individual target should be averaged. The default is 'uniform_average', which specifies a uniformly weighted mean over outputs. If an `ndarray` of shape `(n_outputs,)` is passed, then its entries are interpreted as weights and an according weighted average is returned. If `multioutput` is 'raw_values' is specified, then all unaltered individual scores or losses will be returned in an array of shape `(n_outputs,)`.

4.3. Model selection and evaluation
The `r2_score` and `explained_variance_score` accept an additional value 'variance_weighted' for the multioutput parameter. This option leads to a weighting of each individual score by the variance of the corresponding target variable. This setting quantifies the globally captured unscaled variance. If the target variables are of different scale, then this score puts more importance on well explaining the higher variance variables. multioutput='variance_weighted' is the default value for `r2_score` for backward compatibility. This will be changed to uniform_average in the future.

**Explained variance score**

The `explained_variance_score` computes the explained variance regression score.

If \(\hat{y}\) is the estimated target output, \(y\) the corresponding (correct) target output, and \(Var\) is Variance, the square of the standard deviation, then the explained variance is estimated as follow:

\[
\text{explained\_variance}(y, \hat{y}) = 1 - \frac{\text{Var}(y - \hat{y})}{\text{Var}(y)}
\]

The best possible score is 1.0, lower values are worse.

Here is a small example of usage of the `explained_variance_score` function:

```python
>>> from sklearn.metrics import explained_variance_score
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> explained_variance_score(y_true, y_pred)
0.957...
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> explained_variance_score(y_true, y_pred, multioutput='raw_values')
array([0.967..., 1.])
>>> explained_variance_score(y_true, y_pred, multioutput=[0.3, 0.7])
0.990...
```

**Max error**

The `max_error` function computes the maximum residual error, a metric that captures the worst case error between the predicted value and the true value. In a perfectly fitted single output regression model, max_error would be 0 on the training set and though this would be highly unlikely in the real world, this metric shows the extent of error that the model had when it was fitted.

If \(\hat{y}_i\) is the predicted value of the \(i\)-th sample, and \(y_i\) is the corresponding true value, then the max error is defined as

\[\text{Max Error}(y, \hat{y}) = max(|y_i - \hat{y}_i|)\]

Here is a small example of usage of the `max_error` function:

```python
>>> from sklearn.metrics import max_error
>>> y_true = [3, 2, 7, 1]
>>> y_pred = [9, 2, 7, 1]
>>> max_error(y_true, y_pred)
6
```

The `max_error` does not support multioutput.
Mean absolute error

The `mean_absolute_error` function computes mean absolute error, a risk metric corresponding to the expected value of the absolute error loss or $l_1$-norm loss.

If $\hat{y}_i$ is the predicted value of the $i$-th sample, and $y_i$ is the corresponding true value, then the mean absolute error (MAE) estimated over $n_{\text{samples}}$ is defined as

$$\text{MAE}(y, \hat{y}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} |y_i - \hat{y}_i|.$$

Here is a small example of usage of the `mean_absolute_error` function:

```python
>>> from sklearn.metrics import mean_absolute_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_absolute_error(y_true, y_pred)
0.5
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> mean_absolute_error(y_true, y_pred)
0.75
>>> mean_absolute_error(y_true, y_pred, multioutput='raw_values')
array([0.5, 1.])
>>> mean_absolute_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.85...
```

Mean squared error

The `mean_squared_error` function computes mean square error, a risk metric corresponding to the expected value of the squared (quadratic) error or loss.

If $\hat{y}_i$ is the predicted value of the $i$-th sample, and $y_i$ is the corresponding true value, then the mean squared error (MSE) estimated over $n_{\text{samples}}$ is defined as

$$\text{MSE}(y, \hat{y}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} (y_i - \hat{y}_i)^2.$$

Here is a small example of usage of the `mean_squared_error` function:

```python
>>> from sklearn.metrics import mean_squared_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_squared_error(y_true, y_pred)
0.375
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> mean_squared_error(y_true, y_pred)
0.7083...
```

Examples:

- See Gradient Boosting regression for an example of mean squared error usage to evaluate gradient boosting regression.
Mean squared logarithmic error

The `mean_squared_log_error` function computes a risk metric corresponding to the expected value of the squared logarithmic (quadratic) error or loss. If \( \hat{y}_i \) is the predicted value of the \( i \)-th sample, and \( y_i \) is the corresponding true value, then the mean squared logarithmic error (MSLE) estimated over \( n \) samples is defined as

\[
\text{MSLE}(y, \hat{y}) = \frac{1}{n} \sum_{i=0}^{n-1} (\log_e(1 + y_i) - \log_e(1 + \hat{y}_i))^2.
\]

Where \( \log_e(x) \) means the natural logarithm of \( x \). This metric is best to use when targets having exponential growth, such as population counts, average sales of a commodity over a span of years etc. Note that this metric penalizes an under-predicted estimate greater than an over-predicted estimate.

Here is a small example of usage of the `mean_squared_log_error` function:

```python
>>> from sklearn.metrics import mean_squared_log_error
>>> y_true = [3, 5, 2.5, 7]
>>> y_pred = [2.5, 5, 4, 8]
>>> mean_squared_log_error(y_true, y_pred)
0.039...
>>> y_true = [[0.5, 1], [1, 2], [7, 6]]
>>> y_pred = [[0.5, 2], [1, 2.5], [8, 8]]
>>> mean_squared_log_error(y_true, y_pred)
0.044...
```

Mean absolute percentage error

The `mean_absolute_percentage_error` (MAPE), also known as mean absolute percentage deviation (MAPD), is an evaluation metric for regression problems. The idea of this metric is to be sensitive to relative errors. It is for example not changed by a global scaling of the target variable. If \( \hat{y}_i \) is the predicted value of the \( i \)-th sample and \( y_i \) is the corresponding true value, then the mean absolute percentage error (MAPE) estimated over \( n \) samples is defined as

\[
\text{MAPE}(y, \hat{y}) = \frac{1}{n} \sum_{i=0}^{n-1} \frac{|y_i - \hat{y}_i|}{\max(\epsilon, |y_i|)}
\]

where \( \epsilon \) is an arbitrary small yet strictly positive number to avoid undefined results when \( y \) is zero.

The `mean_absolute_percentage_error` function supports multioutput.

Here is a small example of usage of the `mean_absolute_percentage_error` function:

```python
>>> from sklearn.metrics import mean_absolute_percentage_error
>>> y_true = [1, 10, 1e6]
>>> y_pred = [0.9, 15, 1.2e6]
>>> mean_absolute_percentage_error(y_true, y_pred)
0.2666...
```

In above example, if we had used `mean_absolute_error`, it would have ignored the small magnitude values and only reflected the error in prediction of highest magnitude value. But that problem is resolved in case of MAPE because it calculates relative percentage error with respect to actual output.
Median absolute error

The `median_absolute_error` is particularly interesting because it is robust to outliers. The loss is calculated by taking the median of all absolute differences between the target and the prediction.

If \( \hat{y}_i \) is the predicted value of the \( i \)-th sample and \( y_i \) is the corresponding true value, then the median absolute error (MedAE) estimated over \( n \) samples is defined as

\[
\text{MedAE}(y, \hat{y}) = \text{median}(|y_1 - \hat{y}_1|, \ldots, |y_n - \hat{y}_n|).
\]

The `median_absolute_error` does not support multioutput.

Here is a small example of usage of the `median_absolute_error` function:

```python
>>> from sklearn.metrics import median_absolute_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> median_absolute_error(y_true, y_pred)
0.5
```

\[ R^2 \text{ score, the coefficient of determination} \]

The `r2_score` function computes the coefficient of determination, usually denoted as \( R^2 \).

It represents the proportion of variance (of \( y \)) that has been explained by the independent variables in the model. It provides an indication of goodness of fit and therefore a measure of how well unseen samples are likely to be predicted by the model, through the proportion of explained variance.

As such variance is dataset dependent, \( R^2 \) may not be meaningfully comparable across different datasets. Best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

If \( \hat{y}_i \) is the predicted value of the \( i \)-th sample and \( y_i \) is the corresponding true value for total \( n \) samples, the estimated \( R^2 \) is defined as:

\[
R^2(y, \hat{y}) = 1 - \frac{\sum_{i=1}^{n}(y_i - \hat{y}_i)^2}{\sum_{i=1}^{n}(y_i - \bar{y})^2}
\]

where \( \bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i \) and \( \sum_{i=1}^{n}(y_i - \hat{y}_i)^2 = \sum_{i=1}^{n} \epsilon_i^2 \).

Note that `r2_score` calculates unadjusted \( R^2 \) without correcting for bias in sample variance of \( y \).

Here is a small example of usage of the `r2_score` function:

```python
>>> from sklearn.metrics import r2_score
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> r2_score(y_true, y_pred)
0.948...
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> r2_score(y_true, y_pred, multioutput='variance_weighted')
0.938...
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> r2_score(y_true, y_pred, multioutput='uniform_average')
0.936...
>>> r2_score(y_true, y_pred, multioutput='raw_values')
```

(continues on next page)
Example:

- See Lasso and Elastic Net for Sparse Signals for an example of $R^2$ score usage to evaluate Lasso and Elastic Net on sparse signals.

Mean Poisson, Gamma, and Tweedie deviances

The `mean_tweedie_deviance` function computes the mean Tweedie deviance error with a power parameter ($p$). This is a metric that elicits predicted expectation values of regression targets.

Following special cases exist,

- when $\text{power}=0$ it is equivalent to `mean_squared_error`.
- when $\text{power}=1$ it is equivalent to `mean_poisson_deviance`.
- when $\text{power}=2$ it is equivalent to `mean_gamma_deviance`.

If $\hat{y}_i$ is the predicted value of the $i$-th sample, and $y_i$ is the corresponding true value, then the mean Tweedie deviance error (D) for power $p$, estimated over $n_{\text{samples}}$ is defined as

\[
D(y, \hat{y}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} \begin{cases} 
(y_i - \hat{y}_i)^2, & \text{for } p = 0 \text{ (Normal)} \\
2(y_i \log(y_i/\hat{y}_i) + \hat{y}_i - y_i), & \text{for } p = 1 \text{ (Poisson)} \\
2(\log(y_i/\hat{y}_i) + y_i/\hat{y}_i - 1), & \text{for } p = 2 \text{ (Gamma)} \\
2 \left( \frac{\max(y_i,0)^{2-p}}{(1-p)(2-p)} - \frac{y_i^{1-p}}{1-p} + \frac{\hat{y}_i^{2-p}}{2-p} \right), & \text{otherwise}
\end{cases}
\]

Tweedie deviance is a homogeneous function of degree 2-$p$. Thus, Gamma distribution with $p=2$ means that simultaneously scaling $y_{\text{true}}$ and $y_{\text{pred}}$ has no effect on the deviance. For Poisson distribution $p=1$ the deviance scales linearly, and for Normal distribution ($p=0$), quadratically. In general, the higher $p$ the less weight is given to extreme deviations between true and predicted targets.

For instance, let’s compare the two predictions 1.0 and 100 that are both 50% of their corresponding true value.

The mean squared error ($p=0$) is very sensitive to the prediction difference of the second point.:

```python
>>> from sklearn.metrics import mean_tweedie_deviance
>>> mean_tweedie_deviance([1.0], [1.5], power=0)
0.25
```

If we increase $p$ to 1.:

```python
>>> mean_tweedie_deviance([1.0], [1.5], power=1)
0.18...
```

the difference in errors decreases. Finally, by setting $p=2$:

```python
>>> mean_tweedie_deviance([100.], [150.], power=2)
2500.0
```
we would get identical errors. The deviance when `power=2` is thus only sensitive to relative errors.

### Clustering metrics

The `sklearn.metrics` module implements several loss, score, and utility functions. For more information see the *Clustering performance evaluation* section for instance clustering, and *Biclustering evaluation* for biclustering.

### Dummy estimators

When doing supervised learning, a simple sanity check consists of comparing one’s estimator against simple rules of thumb. `DummyClassifier` implements several such simple strategies for classification:

- `stratified` generates random predictions by respecting the training set class distribution.
- `most_frequent` always predicts the most frequent label in the training set.
- `prior` always predicts the class that maximizes the class prior (like `most_frequent`) and `predict_proba` returns the class prior.
- `uniform` generates predictions uniformly at random.
- `constant` always predicts a constant label that is provided by the user. A major motivation of this method is F1-scoring, when the positive class is in the minority.

Note that with all these strategies, the `predict` method completely ignores the input data!

To illustrate `DummyClassifier`, first let’s create an imbalanced dataset:

```python
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
X, y = load_iris(return_X_y=True)
y[y != 1] = -1
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
```

Next, let’s compare the accuracy of `SVC` and `most_frequent`:

```python
from sklearn.dummy import DummyClassifier
from sklearn.svm import SVC
clf = SVC(kernel='linear', C=1).fit(X_train, y_train)
clf.score(X_test, y_test)
0.63...

clf = DummyClassifier(strategy='most_frequent', random_state=0)
clf.fit(X_train, y_train)
DummyClassifier(random_state=0, strategy='most_frequent')
clf.score(X_test, y_test)
0.57...
```

We see that `SVC` doesn’t do much better than a dummy classifier. Now, let’s change the kernel:

```python
clf = SVC(kernel='rbf', C=1).fit(X_train, y_train)
clf.score(X_test, y_test)
0.94...
```
We see that the accuracy was boosted to almost 100%. A cross validation strategy is recommended for a better estimate of the accuracy, if it is not too CPU costly. For more information see the Cross-validation: evaluating estimator performance section. Moreover if you want to optimize over the parameter space, it is highly recommended to use an appropriate methodology; see the Tuning the hyper-parameters of an estimator section for details.

More generally, when the accuracy of a classifier is too close to random, it probably means that something went wrong: features are not helpful, a hyperparameter is not correctly tuned, the classifier is suffering from class imbalance, etc…

**DummyRegressor** also implements four simple rules of thumb for regression:

- **mean** always predicts the mean of the training targets.
- **median** always predicts the median of the training targets.
- **quantile** always predicts a user provided quantile of the training targets.
- **constant** always predicts a constant value that is provided by the user.

In all these strategies, the predict method completely ignores the input data.

### 4.3.4 Validation curves: plotting scores to evaluate models

Every estimator has its advantages and drawbacks. Its generalization error can be decomposed in terms of bias, variance and noise. The bias of an estimator is its average error for different training sets. The variance of an estimator indicates how sensitive it is to varying training sets. Noise is a property of the data.

In the following plot, we see a function \( f(x) = \cos(\frac{3}{2} \pi x) \) and some noisy samples from that function. We use three different estimators to fit the function: linear regression with polynomial features of degree 1, 4 and 15. We see that the first estimator can at best provide only a poor fit to the samples and the true function because it is too simple (high bias), the second estimator approximates it almost perfectly and the last estimator approximates the training data perfectly but does not fit the true function very well, i.e. it is very sensitive to varying training data (high variance).

Bias and variance are inherent properties of estimators and we usually have to select learning algorithms and hyperparameters so that both bias and variance are as low as possible (see Bias-variance dilemma). Another way to reduce the variance of a model is to use more training data. However, you should only collect more training data if the true function is too complex to be approximated by an estimator with a lower variance.

In the simple one-dimensional problem that we have seen in the example it is easy to see whether the estimator suffers from bias or variance. However, in high-dimensional spaces, models can become very difficult to visualize. For this reason, it is often helpful to use the tools described below.
Examples:

• Underfitting vs. Overfitting
• Plotting Validation Curves
• Plotting Learning Curves

Validation curve

To validate a model we need a scoring function (see Metrics and scoring: quantifying the quality of predictions), for example accuracy for classifiers. The proper way of choosing multiple hyperparameters of an estimator are of course grid search or similar methods (see Tuning the hyper-parameters of an estimator) that select the hyperparameter with the maximum score on a validation set or multiple validation sets. Note that if we optimized the hyperparameters based on a validation score the validation score is biased and not a good estimate of the generalization any longer. To get a proper estimate of the generalization we have to compute the score on another test set.

However, it is sometimes helpful to plot the influence of a single hyperparameter on the training score and the validation score to find out whether the estimator is overfitting or underfitting for some hyperparameter values.

The function validation_curve can help in this case:

```python
>>> import numpy as np
>>> from sklearn.model_selection import validation_curve
>>> from sklearn.datasets import load_iris
>>> from sklearn.linear_model import Ridge

>>> np.random.seed(0)
>>> X, y = load_iris(return_X_y=True)
>>> indices = np.arange(y.shape[0])
>>> np.random.shuffle(indices)
>>> X, y = X[indices], y[indices]

>>> train_scores, valid_scores = validation_curve(Ridge(), X, y, "alpha",
...                                              np.logspace(-7, 3, 3),
...                                              cv=5)

>>> train_scores
array([[0.93..., 0.94..., 0.92..., 0.91..., 0.92...],
[0.93..., 0.94..., 0.92..., 0.91..., 0.92...],
[0.51..., 0.52..., 0.49..., 0.47..., 0.49...]])
>>> valid_scores
array([[0.90..., 0.84..., 0.94..., 0.96..., 0.93...],
[0.90..., 0.84..., 0.94..., 0.96..., 0.93...],
[0.46..., 0.25..., 0.50..., 0.49..., 0.52...]])
```

If the training score and the validation score are both low, the estimator will be underfitting. If the training score is high and the validation score is low, the estimator is overfitting and otherwise it is working very well. A low training score and a high validation score is usually not possible. Underfitting, overfitting, and a working model are shown in the in the plot below where we vary the parameter $\gamma$ of an SVM on the digits dataset.
Learning curve

A learning curve shows the validation and training score of an estimator for varying numbers of training samples. It is a tool to find out how much we benefit from adding more training data and whether the estimator suffers more from a variance error or a bias error. Consider the following example where we plot the learning curve of a naive Bayes classifier and an SVM.

For the naive Bayes, both the validation score and the training score converge to a value that is quite low with increasing size of the training set. Thus, we will probably not benefit much from more training data.

In contrast, for small amounts of data, the training score of the SVM is much greater than the validation score. Adding more training samples will most likely increase generalization.

We can use the function `learning_curve` to generate the values that are required to plot such a learning curve (number of samples that have been used, the average scores on the training sets and the average scores on the validation sets):

```python
>>> from sklearn.model_selection import learning_curve
>>> from sklearn.svm import SVC

>>> train_sizes, train_scores, valid_scores = learning_curve(... SVC(kernel='linear'), X, y, train_sizes=[50, 80, 110], cv=5)

>>> train_sizes
array([ 50, 80, 110])

>>> train_scores
array([[[0.98..., 0.98 , 0.98..., 0.98..., 0.98...],
         [0.98..., 1. , 0.98..., 0.98..., 0.98...],
         [0.98..., 1. , 0.98..., 0.98..., 0.99...]])

>>> valid_scores
array([[[1. , 0.93..., 1. , 1. , 0.96...],
         [1. , 0.96..., 1. , 1. , 0.96...],
         [1. , 0.96..., 1. , 1. , 0.96...]]])
```
4.3. Model selection and evaluation
4.4 Inspection

Predictive performance is often the main goal of developing machine learning models. Yet summarising performance with an evaluation metric is often insufficient: it assumes that the evaluation metric and test dataset perfectly reflect the target domain, which is rarely true. In certain domains, a model needs a certain level of interpretability before it can be deployed. A model that is exhibiting performance issues needs to be debugged for one to understand the model’s underlying issue. The `sklearn.inspection` module provides tools to help understand the predictions from a model and what affects them. This can be used to evaluate assumptions and biases of a model, design a better model, or to diagnose issues with model performance.

Examples:

- Common pitfalls in interpretation of coefficients of linear models

4.4.1 Partial Dependence and Individual Conditional Expectation plots

Partial dependence plots (PDP) and individual conditional expectation (ICE) plots can be used to visualize and analyze interaction between the target response and a set of input features of interest.

Both PDPs and ICEs assume that the input features of interest are independent from the complement features, and this assumption is often violated in practice. Thus, in the case of correlated features, we will create absurd data points to compute the PDP/ICE.

Partial dependence plots

Partial dependence plots (PDP) show the dependence between the target response and a set of input features of interest, marginalizing over the values of all other input features (the ‘complement’ features). Intuitively, we can interpret the partial dependence as the expected target response as a function of the input features of interest.

Due to the limits of human perception the size of the set of input feature of interest must be small (usually, one or two) thus the input features of interest are usually chosen among the most important features.

The figure below shows two one-way and one two-way partial dependence plots for the California housing dataset, with a `HistGradientBoostingRegressor`:

One-way PDPs tell us about the interaction between the target response and an input feature of interest feature (e.g. linear, non-linear). The left plot in the above figure shows the effect of the average occupancy on the median house price; we can clearly see a linear relationship among them when the average occupancy is inferior to 3 persons. Similarly, we could analyze the effect of the house age on the median house price (middle plot). Thus, these interpretations are marginal, considering a feature at a time.

PDPs with two input features of interest show the interactions among the two features. For example, the two-variable PDP in the above figure shows the dependence of median house price on joint values of house age and average occupants per household. We can clearly see an interaction between the two features: for an average occupancy greater than two, the house price is nearly independent of the house age, whereas for values less than 2 there is a strong dependence on age.

The `sklearn.inspection` module provides a convenience function `plot_partial_dependence` to create one-way and two-way partial dependence plots. In the below example we show how to create a grid of partial dependence plots: two one-way PDPs for the features 0 and 1 and a two-way PDP between the two features:

---

1 For classification, the target response may be the probability of a class (the positive class for binary classification), or the decision function.
You can access the newly created figure and Axes objects using `plt.gcf()` and `plt.gca()`.

For multi-class classification, you need to set the class label for which the PDPs should be created via the `target` argument:

```python
>>> from sklearn.datasets import load_iris
>>> iris = load_iris()
>>> mc_clf = GradientBoostingClassifier(n_estimators=10,
...   ...   max_depth=1).fit(iris.data, iris.target)
>>> features = [3, 2, (3, 2)]
>>> plot_partial_dependence(mc_clf, iris.data, features, target=0)
```

The same parameter `target` is used to specify the target in multi-output regression settings.

If you need the raw values of the partial dependence function rather than the plots, you can use the `sklearn.inspection.partial_dependence` function:

```python
>>> from sklearn.inspection import partial_dependence
>>> pdp, axes = partial_dependence(clf, X, [0])
>>> pdp
array([[ 2.466... ,  2.466... , ...
>>> axes
[array([-1.624..., -1.592..., ...
```

The values at which the partial dependence should be evaluated are directly generated from `X`. For 2-way partial dependence, a 2D-grid of values is generated. The `values` field returned by `sklearn.inspection.partial_dependence` gives the actual values used in the grid for each input feature of interest. They also corre-
spond to the axis of the plots.

**Individual conditional expectation (ICE) plot**

Similar to a PDP, an individual conditional expectation (ICE) plot shows the dependence between the target function and an input feature of interest. However, unlike a PDP, which shows the average effect of the input feature, an ICE plot visualizes the dependence of the prediction on a feature for each sample separately with one line per sample. Due to the limits of human perception, only one input feature of interest is supported for ICE plots.

The figures below show four ICE plots for the California housing dataset, with a HistGradientBoostingRegressor. The second figure plots the corresponding PD line overlaid on ICE lines.

![ICE plots](image)

While the PDPs are good at showing the average effect of the target features, they can obscure a heterogeneous relationship created by interactions. When interactions are present the ICE plot will provide many more insights. For example, we could observe a linear relationship between the median income and the house price in the PD line. However, the ICE lines show that there are some exceptions, where the house price remains constant in some ranges of the median income.

The *sklearn.inspection* module’s *plot_partial_dependence* convenience function can be used to create ICE plots by setting `kind='individual'`. In the example below, we show how to create a grid of ICE plots:

```python
>>> from sklearn.datasets import make_hastie_10_2
>>> from sklearn.ensemble import GradientBoostingClassifier
>>> from sklearn.inspection import plot_partial_dependence

>>> X, y = make_hastie_10_2(random_state=0)
>>> clf = GradientBoostingClassifier(n_estimators=100, learning_rate=1.0,
...                              ... max_depth=1, random_state=0).fit(X, y)
>>> features = [0, 1]
>>> plot_partial_dependence(clf, X, features,
...                          ... kind='individual')
```
In ICE plots it might not be easy to see the average effect of the input feature of interest. Hence, it is recommended to use ICE plots alongside PDPs. They can be plotted together with kind='both'.

```python
>>> plot_partial_dependence(clf, X, features,
... kind='both')
```

**Mathematical Definition**

Let $X_S$ be the set of input features of interest (i.e. the features parameter) and let $X_C$ be its complement.

The partial dependence of the response $f$ at a point $x_S$ is defined as:

$$
pd_{X_S}(x_S) \overset{\text{def}}{=} E_{X_C}[f(x_S, X_C)] = \int f(x_S, x_C)p(x_C)dx_C,
$$

where $f(x_S, x_C)$ is the response function (predict, predict_proba or decision_function) for a given sample whose values are defined by $x_S$ for the features in $X_S$, and by $x_C$ for the features in $X_C$. Note that $x_S$ and $x_C$ may be tuples. Computing this integral for various values of $x_S$ produces a PDP plot as above. An ICE line is defined as a single $f(x_S, x_C^{(i)})$ evaluated at $x_S$.

**Computation methods**

There are two main methods to approximate the integral above, namely the ‘brute’ and ‘recursion’ methods. The method parameter controls which method to use.

The ‘brute’ method is a generic method that works with any estimator. Note that computing ICE plots is only supported with the ‘brute’ method. It approximates the above integral by computing an average over the data $X$:

$$
pd_{X_S}(x_S) \approx \frac{1}{n_{\text{samples}}} \sum_{i=1}^{n} f(x_S, x_C^{(i)}),
$$

where $x_C^{(i)}$ is the value of the i-th sample for the features in $X_C$. For each value of $x_S$, this method requires a full pass over the dataset $X$ which is computationally intensive.

Each of the $f(x_S, x_C^{(i)})$ corresponds to one ICE line evaluated at $x_S$. Computing this for multiple values of $x_S$, one obtains a full ICE line. As one can see, the average of the ICE lines correspond to the partial dependence line.

The ‘recursion’ method is faster than the ‘brute’ method, but it is only supported for PDP plots by some tree-based estimators. It is computed as follows. For a given point $x_S$, a weighted tree traversal is performed: if a split node involves an input feature of interest, the corresponding left or right branch is followed; otherwise both branches are followed, each branch being weighted by the fraction of training samples that entered that branch. Finally, the partial dependence is given by a weighted average of all the visited leaves values.

With the ‘brute’ method, the parameter $X$ is used both for generating the grid of values $x_S$ and the complement feature values $x_C$. However with the ‘recursion’ method, $X$ is only used for the grid values: implicitly, the $x_C$ values are those of the training data.

By default, the ‘recursion’ method is used for plotting PDPs on tree-based estimators that support it, and ‘brute’ is used for the rest.

**Note:** While both methods should be close in general, they might differ in some specific settings. The ‘brute’ method assumes the existence of the data points $(x_S, x_C^{(i)})$. When the features are correlated, such artificial samples may have a very low probability mass. The ‘brute’ and ‘recursion’ methods will likely disagree regarding the value of the
partial dependence, because they will treat these unlikely samples differently. Remember, however, that the primary assumption for interpreting PDPs is that the features should be independent.

Examples:

• Partial Dependence and Individual Conditional Expectation Plots

References


C. Molnar, Interpretable Machine Learning, Section 5.1, 2019.


4.4.2 Permutation feature importance

Permutation feature importance is a model inspection technique that can be used for any fitted estimator when the data is tabular. This is especially useful for non-linear or opaque estimators. The permutation feature importance is defined to be the decrease in a model score when a single feature value is randomly shuffled. This procedure breaks the relationship between the feature and the target, thus the drop in the model score is indicative of how much the model depends on the feature. This technique benefits from being model agnostic and can be calculated many times with different permutations of the feature.

The permutation_importance function calculates the feature importance of estimators for a given dataset. The n_repeats parameter sets the number of times a feature is randomly shuffled and returns a sample of feature importances.

Let’s consider the following trained regression model:

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.linear_model import Ridge

>>> diabetes = load_diabetes()

>>> X_train, X_val, y_train, y_val = train_test_split(...
  diabetes.data, diabetes.target, random_state=0)

>>> model = Ridge(alpha=1e-2).fit(X_train, y_train)

>>> model.score(X_val, y_val)
0.356...
```

Its validation performance, measured via the $R^2$ score, is significantly larger than the chance level. This makes it possible to use the permutation_importance function to probe which features are most predictive:

```python
>>> from sklearn.inspection import permutation_importance

>>> r = permutation_importance(model, X_val, y_val,
  ... n_repeats=30,
  ... random_state=0)
```

(continues on next page)

Note that the importance values for the top features represent a large fraction of the reference score of 0.356.

Permutation importances can be computed either on the training set or on a held-out testing or validation set. Using a held-out set makes it possible to highlight which features contribute the most to the generalization power of the inspected model. Features that are important on the training set but not on the held-out set might cause the model to overfit.

**Warning:** Features that are deemed of low importance for a bad model (low cross-validation score) could be very important for a good model. Therefore it is always important to evaluate the predictive power of a model using a held-out set (or better with cross-validation) prior to computing importances. Permutation importance does not reflect to the intrinsic predictive value of a feature by itself but how important this feature is for a particular model.

**Outline of the permutation importance algorithm**

- **Inputs:** fitted predictive model $m$, tabular dataset (training or validation) $D$.
- **Compute** the reference score $s$ of the model $m$ on data $D$ (for instance the accuracy for a classifier or the $R^2$ for a regressor).
- **For each feature** $j$ (column of $D$):
  - **For** each repetition $k$ in 1, ..., $K$:
    * Randomly shuffle column $j$ of dataset $D$ to generate a corrupted version of the data named $\tilde{D}_{k,j}$.
    * Compute the score $s_{k,j}$ of model $m$ on corrupted data $\tilde{D}_{k,j}$.
  - Compute importance $i_j$ for feature $f_j$ defined as:
    \[
    i_j = s - \frac{1}{K} \sum_{k=1}^{K} s_{k,j}
    \]
Relation to impurity-based importance in trees

Tree-based models provide an alternative measure of feature importances based on the mean decrease in impurity (MDI). Impurity is quantified by the splitting criterion of the decision trees (Gini, Entropy or Mean Squared Error). However, this method can give high importance to features that may not be predictive on unseen data when the model is overfitting. Permutation-based feature importance, on the other hand, avoids this issue, since it can be computed on unseen data.

Furthermore, impurity-based feature importance for trees are strongly biased and favor high cardinality features (typically numerical features) over low cardinality features such as binary features or categorical variables with a small number of possible categories.

Permutation-based feature importances do not exhibit such a bias. Additionally, the permutation feature importance may be computed on unseen data and can be used to analyze any model class (not just tree-based models).

The following example highlights the limitations of impurity-based feature importance in contrast to permutation-based feature importance: Permutation Importance vs Random Forest Feature Importance (MDI).

Misleading values on strongly correlated features

When two features are correlated and one of the features is permuted, the model will still have access to the feature through its correlated feature. This will result in a lower importance value for both features, where they might actually be important.

One way to handle this is to cluster features that are correlated and only keep one feature from each cluster. This strategy is explored in the following example: Permutation Importance with Multicollinear or Correlated Features.

Examples:

- Permutation Importance vs Random Forest Feature Importance (MDI)
- Permutation Importance with Multicollinear or Correlated Features

References:

4.5 Visualizations

Scikit-learn defines a simple API for creating visualizations for machine learning. The key feature of this API is to allow for quick plotting and visual adjustments without recalculation. In the following example, we plot a ROC curve for a fitted support vector machine:

```python
g from sklearn.model_selection import train_test_split
g from sklearn.svm import SVC
g from sklearn.metrics import plot_roc_curve
g from sklearn.datasets import load_wine

X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)
g svc = SVC(random_state=42)
g svc.fit(X_train, y_train)
```
The returned `svc_disp` object allows us to continue using the already computed ROC curve for SVC in future plots. In this case, the `svc_disp` is a `RocCurveDisplay` that stores the computed values as attributes called `roc_auc`, `fpr`, and `tpr`. Next, we train a random forest classifier and plot the previously computed roc curve again by using the `plot` method of the `Display` object.

```python
import matplotlib.pyplot as plt
from sklearn.ensemble import RandomForestClassifier

rfc = RandomForestClassifier(random_state=42)
rfc.fit(X_train, y_train)

ax = plt.gca()
rfc_disp = plot_roc_curve(rfc, X_test, y_test, ax=ax, alpha=0.8)
svc_disp.plot(ax=ax, alpha=0.8)
```

Notice that we pass `alpha=0.8` to the plot functions to adjust the alpha values of the curves.

**Examples:**

- ROC Curve with Visualization API
- Advanced Plotting With Partial Dependence
- Visualizations with Display Objects
4.5.1 Available Plotting Utilities

Functions

- `inspection.plot_partial_dependence(...)`: Partial dependence (PD) and individual conditional expectation (ICE) plots.
- `metrics.plot_confusion_matrix(estimator, X, ...)`: Plot Confusion Matrix.
- `metrics.plot_det_curve(estimator, X, y, ...)`: Plot detection error tradeoff (DET) curve.
- `metrics.plot_precision_recall_curve(...)`: Plot Precision Recall Curve for binary classifiers.
- `metrics.plot_roc_curve(estimator, X, y, ...)`: Plot Receiver operating characteristic (ROC) curve.

Display Objects

- `metrics.DetCurveDisplay(*, fpr, fnr, ...)`: DET curve visualization.
- `metrics.PrecisionRecallDisplay(precision, ...)`: Precision Recall visualization.

4.6 Dataset transformations

scikit-learn provides a library of transformers, which may clean (see Preprocessing data), reduce (see Unsupervised dimensionality reduction), expand (see Kernel Approximation) or generate (see Feature extraction) feature representations.

Like other estimators, these are represented by classes with a fit method, which learns model parameters (e.g. mean and standard deviation for normalization) from a training set, and a transform method which applies this transformation model to unseen data. fit_transform may be more convenient and efficient for modelling and transforming the training data simultaneously.

Combining such transformers, either in parallel or series is covered in Pipelines and composite estimators. Pairwise metrics, Affinities and Kernels covers transforming feature spaces into affinity matrices, while Transforming the prediction target (y) considers transformations of the target space (e.g. categorical labels) for use in scikit-learn.
4.6.1 Pipelines and composite estimators

Transformers are usually combined with classifiers, regressors or other estimators to build a composite estimator. The most common tool is a Pipeline. Pipeline is often used in combination with FeatureUnion which concatenates the output of transformers into a composite feature space. TransformedTargetRegressor deals with transforming the target (i.e. log-transform $y$). In contrast, Pipelines only transform the observed data ($X$).

Pipeline: chaining estimators

Pipeline can be used to chain multiple estimators into one. This is useful as there is often a fixed sequence of steps in processing the data, for example feature selection, normalization and classification. Pipeline serves multiple purposes here:

Convenience and encapsulation  You only have to call `fit` and `predict` once on your data to fit a whole sequence of estimators.

Joint parameter selection  You can grid search over parameters of all estimators in the pipeline at once.

Safety  Pipelines help avoid leaking statistics from your test data into the trained model in cross-validation, by ensuring that the same samples are used to train the transformers and predictors.

All estimators in a pipeline, except the last one, must be transformers (i.e. must have a `transform` method). The last estimator may be any type (transformer, classifier, etc.).

Usage

Construction

The `Pipeline` is built using a list of (key, value) pairs, where the key is a string containing the name you want to give this step and value is an estimator object:

```python
>>> from sklearn.pipeline import Pipeline
>>> from sklearn.svm import SVC
>>> from sklearn.decomposition import PCA

>>> estimators = [('reduce_dim', PCA()), ('clf', SVC())]

>>> pipe = Pipeline(estimators)
```

The utility function `make_pipeline` is a shorthand for constructing pipelines; it takes a variable number of estimators and returns a pipeline, filling in the names automatically:

```python
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.naive_bayes import MultinomialNB
>>> from sklearn.preprocessing import Binarizer

>>> make_pipeline(Binarizer(), MultinomialNB())
```
Accessing steps

The estimators of a pipeline are stored as a list in the `steps` attribute, but can be accessed by index or name by indexing (with `[idx]`) the Pipeline:

```python
>>> pipe.steps[0]
('reduce_dim', PCA())
>>> pipe[0]
PCA()
>>> pipe['reduce_dim']
PCA()
```

Pipeline’s `named_steps` attribute allows accessing steps by name with tab completion in interactive environments:

```python
>>> pipe.named_steps.reduce_dim is pipe['reduce_dim']
True
```

A sub-pipeline can also be extracted using the slicing notation commonly used for Python Sequences such as lists or strings (although only a step of 1 is permitted). This is convenient for performing only some of the transformations (or their inverse):

```python
>>> pipe[:1]
Pipeline(steps=[('reduce_dim', PCA())])
>>> pipe[-1:]
Pipeline(steps=[('clf', SVC())])
```

Nested parameters

Parameters of the estimators in the pipeline can be accessed using the `<estimator>__<parameter>` syntax:

```python
>>> pipe.set_params(clf__C=10)
Pipeline(steps=[('reduce_dim', PCA()), ('clf', SVC(C=10))])
```

This is particularly important for doing grid searches:

```python
>>> from sklearn.model_selection import GridSearchCV
>>> param_grid = dict(reduce_dim__n_components=[2, 5, 10],
                    ... clf__C=[0.1, 10, 100])
>>> grid_search = GridSearchCV(pipe, param_grid=param_grid)
```

Individual steps may also be replaced as parameters, and non-final steps may be ignored by setting them to 'passthrough':

```python
>>> from sklearn.linear_model import LogisticRegression
>>> param_grid = dict(reduce_dim=['passthrough', PCA(5), PCA(10)],
                    ... clf=[SVC(), LogisticRegression()],
                    ... clf__C=[0.1, 10, 100])
>>> grid_search = GridSearchCV(pipe, param_grid=param_grid)
```

The estimators of the pipeline can be retrieved by index:

```python
>>> pipe[0]
PCA()
```

or by name:
Examples:

- Pipeline Anova SVM
- Sample pipeline for text feature extraction and evaluation
- Pipelining: chaining a PCA and a logistic regression
- Explicit feature map approximation for RBF kernels
- SVM-Anova: SVM with univariate feature selection
- Selecting dimensionality reduction with Pipeline and GridSearchCV

See Also:

- Composite estimators and parameter spaces

Notes

Calling fit on the pipeline is the same as calling fit on each estimator in turn, transform the input and pass it on to the next step. The pipeline has all the methods that the last estimator in the pipeline has, i.e. if the last estimator is a classifier, the Pipeline can be used as a classifier. If the last estimator is a transformer, again, so is the pipeline.

Caching transformers: avoid repeated computation

Fitting transformers may be computationally expensive. With its memory parameter set, Pipeline will cache each transformer after calling fit. This feature is used to avoid computing the fit transformers within a pipeline if the parameters and input data are identical. A typical example is the case of a grid search in which the transformers can be fitted only once and reused for each configuration.

The parameter memory is needed in order to cache the transformers. memory can be either a string containing the directory where to cache the transformers or a joblib.Memory object:

```python
>>> from tempfile import mkdtemp
>>> from shutil import rmtree
>>> from sklearn.decomposition import PCA
>>> from sklearn.svm import SVC
>>> from sklearn.pipeline import Pipeline

>>> estimators = [('reduce_dim', PCA()), ('clf', SVC())]
>>> cachedir = mkdtemp()
>>> pipe = Pipeline(estimators, memory=cachedir)
>>> pipe
Pipeline(memory=..., steps=[('reduce_dim', PCA()), ('clf', SVC())])
>>> # Clear the cache directory when you don't need it anymore
>>> rmtree(cachedir)
```
Warning: Side effect of caching transformers

Using a `Pipeline` without cache enabled, it is possible to inspect the original instance such as:

```python
>>> from sklearn.datasets import load_digits
>>> X_digits, y_digits = load_digits(return_X_y=True)
>>> pca1 = PCA()
>>> svm1 = SVC()
>>> pipe = Pipeline([('reduce_dim', pca1), ('clf', svm1)])
>>> pipe.fit(X_digits, y_digits)
Pipeline(steps=[('reduce_dim', PCA()), ('clf', SVC())])
>>> # The pca instance can be inspected directly
>>> print(pca1.components_)
[[-1.77484909e-19 ... 4.07058917e-18]]
```

Enabling caching triggers a clone of the transformers before fitting. Therefore, the transformer instance given to the pipeline cannot be inspected directly. In the following example, accessing the `PCA` instance `pca2` will raise an `AttributeError` since `pca2` will be an unfitted transformer. Instead, use the attribute `named_steps` to inspect estimators within the pipeline:

```python
>>> cachedir = mkdtemp()
>>> pca2 = PCA()
>>> svm2 = SVC()
>>> cached_pipe = Pipeline([('reduce_dim', pca2), ('clf', svm2)],
                          memory=cachedir)
>>> cached_pipe.fit(X_digits, y_digits)
Pipeline(memory=...,
         steps=[('reduce_dim', PCA()), ('clf', SVC())])
>>> print(cached_pipe.named_steps['reduce_dim'].components_)
[[-1.77484909e-19 ... 4.07058917e-18]]
>>> # Remove the cache directory
>>> rmtree(cachedir)
```

Examples:

- Selecting dimensionality reduction with `Pipeline` and `GridSearchCV`

Transforming target in regression

`TransformedTargetRegressor` transforms the targets `y` before fitting a regression model. The predictions are mapped back to the original space via an inverse transform. It takes as an argument the regressor that will be used for prediction, and the transformer that will be applied to the target variable:

```python
>>> import numpy as np
>>> from sklearn.datasets import fetch_california_housing
>>> from sklearn.compose import TransformedTargetRegressor
>>> from sklearn.preprocessing import QuantileTransformer
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.model_selection import train_test_split
>>> X, y = fetch_california_housing(return_X_y=True)
>>> X, y = X[:2000, :], y[:2000]  # select a subset of data
>>> transformer = QuantileTransformer(output_distribution='normal')
>>> regressor = LinearRegression()
>>> regr = TransformedTargetRegressor(regressor=regressor,
```

(continues on next page)
... transformer=transformer)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
>>> regr.fit(X_train, y_train)
TransformedTargetRegressor(...)
>>> print('R2 score: {0:.2f}'.format(regr.score(X_test, y_test)))
R2 score: 0.61
>>> raw_target_regr = LinearRegression().fit(X_train, y_train)
>>> print('R2 score: {0:.2f}'.format(raw_target_regr.score(X_test, y_test)))
R2 score: 0.59

For simple transformations, instead of a Transformer object, a pair of functions can be passed, defining the transformation and its inverse mapping:

```python
>>> def func(x):
...     return np.log(x)

>>> def inverse_func(x):
...     return np.exp(x)
```

Subsequently, the object is created as:

```python
>>> regr = TransformedTargetRegressor(regressor=regressor,
...     func=func,
...     inverse_func=inverse_func)
>>> regr.fit(X_train, y_train)
TransformedTargetRegressor(...)
>>> print('R2 score: {0:.2f}'.format(regr.score(X_test, y_test)))
R2 score: 0.51
```

By default, the provided functions are checked at each fit to be the inverse of each other. However, it is possible to bypass this checking by setting `check_inverse` to `False`:

```python
>>> def inverse_func(x):
...     return x

>>> regr = TransformedTargetRegressor(regressor=regressor,
...     func=func,
...     inverse_func=inverse_func,
...     check_inverse=False)
>>> regr.fit(X_train, y_train)
TransformedTargetRegressor(...)
>>> print('R2 score: {0:.2f}'.format(regr.score(X_test, y_test)))
R2 score: -1.57
```

Note: The transformation can be triggered by setting either `transformer` or the pair of functions `func` and `inverse_func`. However, setting both options will raise an error.

**Examples:**

- *Effect of transforming the targets in regression model*
FeatureUnion: composite feature spaces

FeatureUnion combines several transformer objects into a new transformer that combines their output. A FeatureUnion takes a list of transformer objects. During fitting, each of these is fit to the data independently. The transformers are applied in parallel, and the feature matrices they output are concatenated side-by-side into a larger matrix.

When you want to apply different transformations to each field of the data, see the related class ColumnTransformer (see user guide).

FeatureUnion serves the same purposes as Pipeline - convenience and joint parameter estimation and validation.

FeatureUnion and Pipeline can be combined to create complex models.

(A FeatureUnion has no way of checking whether two transformers might produce identical features. It only produces a union when the feature sets are disjoint, and making sure they are is the caller’s responsibility.)

Usage

A FeatureUnion is built using a list of (key, value) pairs, where the key is the name you want to give to a given transformation (an arbitrary string; it only serves as an identifier) and value is an estimator object:

```python
>>> from sklearn.pipeline import FeatureUnion
>>> from sklearn.decomposition import PCA
>>> from sklearn.decomposition import KernelPCA

>>> estimators = [('linear_pca', PCA()), ('kernel_pca', KernelPCA())]
>>> combined = FeatureUnion(estimators)
>>> combined
FeatureUnion(transformer_list=[('linear_pca', PCA()), ('kernel_pca', KernelPCA())])
```

Like pipelines, feature unions have a shorthand constructor called make_union that does not require explicit naming of the components.

Like Pipeline, individual steps may be replaced using set_params, and ignored by setting to 'drop':

```python
>>> combined.set_params(kernel_pca='drop')
FeatureUnion(transformer_list=[('linear_pca', PCA()), ('kernel_pca', 'drop')])
```

Examples:

- Concatenating multiple feature extraction methods
ColumnTransformer for heterogeneous data

Many datasets contain features of different types, say text, floats, and dates, where each type of feature requires separate preprocessing or feature extraction steps. Often it is easiest to preprocess data before applying scikit-learn methods, for example using pandas. Processing your data before passing it to scikit-learn might be problematic for one of the following reasons:

1. Incorporating statistics from test data into the preprocessors makes cross-validation scores unreliable (known as data leakage), for example in the case of scalers or imputing missing values.

2. You may want to include the parameters of the preprocessors in a parameter search.

The ColumnTransformer helps performing different transformations for different columns of the data, within a Pipeline that is safe from data leakage and that can be parametrized. ColumnTransformer works on arrays, sparse matrices, and pandas DataFrames.

To each column, a different transformation can be applied, such as preprocessing or a specific feature extraction method:

```python
>>> import pandas as pd
>>> X = pd.DataFrame(
... {'city': ['London', 'London', 'Paris', 'Sallisaw'],
... 'title': ['His Last Bow', 'How Watson Learned the Trick',
... 'A Moveable Feast', 'The Grapes of Wrath'],
... 'expert_rating': [5, 3, 4, 5],
... 'user_rating': [4, 5, 4, 3]})
```

For this data, we might want to encode the 'city' column as a categorical variable using OneHotEncoder but apply a CountVectorizer to the 'title' column. As we might use multiple feature extraction methods on the same column, we give each transformer a unique name, say 'city_category' and 'title_bow'. By default, the remaining rating columns are ignored (remainder='drop'):

```python
>>> from sklearn.compose import ColumnTransformer
>>> from sklearn.feature_extraction.text import CountVectorizer
>>> from sklearn.preprocessing import OneHotEncoder

>>> column_trans = ColumnTransformer(
... [('city_category', OneHotEncoder(dtype='int'), ['city']),
... ('title_bow', CountVectorizer(), 'title')],
... remainder='drop')

>>> column_trans.fit(X)
ColumnTransformer(transformers=[('city_category', OneHotEncoder(dtype='int'), ['city']), ('title_bow', CountVectorizer(), 'title')])

>>> column_trans.get_feature_names()
['city_category__x0_London', 'city_category__x0_Paris', 'city_category__x0_Sallisaw', 'title_bow__bow', 'title_bow__feast', 'title_bow__grapes', 'title_bow__his', 'title_bow__how', 'title_bow__last', 'title_bow__learned', 'title_bow__moveable', 'title_bow__of', 'title_bow__the', 'title_bow__trick', 'title_bow__watson', 'title_bow__wrath']

>>> column_trans.transform(X).toarray()
array([[1, 0, 0, 1, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0],
[1, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 0, 1, 0],
[0, 1, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0],
[0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0]])
```

In the above example, the CountVectorizer expects a 1D array as input and therefore the columns were specified
as a string ('title'). However, OneHotEncoder as most of other transformers expects 2D data, therefore in that case you need to specify the column as a list of strings (['city']).

Apart from a scalar or a single item list, the column selection can be specified as a list of multiple items, an integer array, a slice, a boolean mask, or with a make_column_selector. The make_column_selector is used to select columns based on data type or column name:

```python
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.compose import make_column_selector
>>> ct = ColumnTransformer([
    ('scale', StandardScaler(),
     make_column_selector(dtype_include=np.number)),
    ('onehot',
     OneHotEncoder(),
     make_column_selector(pattern='city', dtype_include=object))])
```

Strings can reference columns if the input is a DataFrame, integers are always interpreted as the positional columns.

We can keep the remaining rating columns by setting remainder='passthrough'. The values are appended to the end of the transformation:

```python
>>> column_trans = ColumnTransformer(
    [('city_category', OneHotEncoder(dtype='int'), ['city']),
     ('title_bow', CountVectorizer(), 'title')],
    remainder='passthrough')
```

The remainder parameter can be set to an estimator to transform the remaining rating columns. The transformed values are appended to the end of the transformation:

```python
>>> from sklearn.preprocessing import MinMaxScaler
>>> column_trans = make_column_transformer(
    (OneHotEncoder(), ['city']),
    (continues on next page)
(continued from previous page)

```python
... (CountVectorizer(), 'title'),
... remainder=MinMaxScaler())
```

```python
>>> column_trans = ColumnTransformer(remainder=MinMaxScaler(),
                                     transformers=[('onehotencoder', OneHotEncoder(), ['city']),
                                                   ('countvectorizer', CountVectorizer(),
                                                    'title')])
```

### Visualizing Composite Estimators

Estimators can be displayed with a HTML representation when shown in a jupyter notebook. This can be useful to diagnose or visualize a Pipeline with many estimators. This visualization is activated by setting the `display` option in `set_config`:

```python
>>> from sklearn import set_config
>>> set_config(display='diagram')
>>> # displays HTML representation in a jupyter context
>>> column_trans
```

An example of the HTML output can be seen in the HTML representation of Pipeline section of *Column Transformer with Mixed Types*. As an alternative, the HTML can be written to a file using `estimator_html_repr`:

```python
>>> from sklearn.utils import estimator_html_repr
>>> with open('my_estimator.html', 'w') as f:
...     f.write(estimator_html_repr(clf))
```

### Examples:

- *Column Transformer with Heterogeneous Data Sources*
- *Column Transformer with Mixed Types*

### 4.6.2 Feature extraction

The `sklearn.feature_extraction` module can be used to extract features in a format supported by machine learning algorithms from datasets consisting of formats such as text and image.

**Note:** Feature extraction is very different from *Feature selection*: the former consists in transforming arbitrary data, such as text or images, into numerical features usable for machine learning. The latter is a machine learning technique applied on these features.
Loading features from dicts

The class `DictVectorizer` can be used to convert feature arrays represented as lists of standard Python `dict` objects to the NumPy/SciPy representation used by scikit-learn estimators.

While not particularly fast to process, Python’s `dict` has the advantages of being convenient to use, being sparse (absent features need not be stored) and storing feature names in addition to values.

`DictVectorizer` implements what is called one-of-K or “one-hot” coding for categorical (aka nominal, discrete) features. Categorical features are “attribute-value” pairs where the value is restricted to a list of discrete of possibilities without ordering (e.g. topic identifiers, types of objects, tags, names...).

In the following, “city” is a categorical attribute while “temperature” is a traditional numerical feature:

```python
>>> measurements = [
...    {'city': 'Dubai', 'temperature': 33.},
...    {'city': 'London', 'temperature': 12.},
...    {'city': 'San Francisco', 'temperature': 18.},
...]

>>> from sklearn.feature_extraction import DictVectorizer
>>> vec = DictVectorizer()

>>> vec.fit_transform(measurements).toarray()
array([[ 1., 0., 0., 33.],
       [ 0., 1., 0., 12.],
       [ 0., 0., 1., 18.]]

>>> vec.get_feature_names()
['city=Dubai', 'city=London', 'city=San Francisco', 'temperature']

DictVectorizer accepts multiple string values for one feature, like, e.g., multiple categories for a movie.

Assume a database classifies each movie using some categories (not mandatories) and its year of release.

```python
>>> movie_entry = [{'category': ['thriller', 'drama'], 'year': 2003},
...    {'category': ['animation', 'family'], 'year': 2011},
...    {'year': 1974}]

>>> vec.fit_transform(movie_entry).toarray()
array([[0.000e+00, 1.000e+00, 0.000e+00, 1.000e+00, 2.003e+03],
       [1.000e+00, 0.000e+00, 1.000e+00, 0.000e+00, 2.011e+03],
       [0.000e+00, 0.000e+00, 0.000e+00, 0.000e+00, 1.974e+03]])

>>> vec.get_feature_names()
['category=animation', 'category=drama',
 ...  'category=family', 'category=thriller',
 ...  'year']

True
```

`DictVectorizer` is also a useful representation transformation for training sequence classifiers in Natural Language Processing models that typically work by extracting feature windows around a particular word of interest.

For example, suppose that we have a first algorithm that extracts Part of Speech (PoS) tags that we want to use as complementary tags for training a sequence classifier (e.g. a chunker). The following dict could be such a window of features extracted around the word ‘sat’ in the sentence ‘The cat sat on the mat.’:

```python
>>> pos_window = [
...    {'category': 'NOUN'},
...    {'category': 'VERB'},
...    {'category': 'AUX'}
...]
```

(continues on next page)
This description can be vectorized into a sparse two-dimensional matrix suitable for feeding into a classifier (maybe after being piped into a `TfidfTransformer` for normalization):

```python
>>> vec = DictVectorizer()
>>> pos_vectorized = vec.fit_transform(pos_window)
>>> pos_vectorized
<1x6 sparse matrix of type '<... 'numpy.float64'>'
  with 6 stored elements in Compressed Sparse ... format>
>>> pos_vectorized.toarray()
array([[1., 1., 1., 1., 1., 1.]])
>>> vec.get_feature_names()
['pos+1=PP', 'pos-1=NN', 'pos-2=DT', 'word+1=on', 'word-1=cat', 'word-2=the']
```

As you can imagine, if one extracts such a context around each individual word of a corpus of documents the resulting matrix will be very wide (many one-hot-features) with most of them being valued to zero most of the time. So as to make the resulting data structure able to fit in memory the `DictVectorizer` class uses a `scipy.sparse` matrix by default instead of a `numpy.ndarray`.

### Feature hashing

The class `FeatureHasher` is a high-speed, low-memory vectorizer that uses a technique known as feature hashing, or the “hashing trick”. Instead of building a hash table of the features encountered in training, as the vectorizers do, instances of `FeatureHasher` apply a hash function to the features to determine their column index in sample matrices directly. The result is increased speed and reduced memory usage, at the expense of inspectability; the hasher does not remember what the input features looked like and has no `inverse_transform` method.

Since the hash function might cause collisions between (unrelated) features, a signed hash function is used and the sign of the hash value determines the sign of the value stored in the output matrix for a feature. This way, collisions are likely to cancel out rather than accumulate error, and the expected mean of any output feature’s value is zero. This mechanism is enabled by default with `alternate_sign=True` and is particularly useful for small hash table sizes (n_features < 10000). For large hash table sizes, it can be disabled, to allow the output to be passed to estimators like `MultinomialNB` or `chi2` feature selectors that expect non-negative inputs.

`FeatureHasher` accepts either mappings (like Python’s `dict` and its variants in the `collections` module), `(feature, value)` pairs, or strings, depending on the constructor parameter `input_type`. Mapping are treated as lists of `(feature, value)` pairs, while single strings have an implicit value of 1, so `['feat1', 'feat2', 'feat3']` is interpreted as `[(‘feat1’, 1), (‘feat2’, 1), (‘feat3’, 1)]`. If a single feature occurs multiple times in a sample, the associated values will be summed (so `‘feat’, 2` and `‘feat’, 3.5`) become `‘feat’, 5.5`). The output from `FeatureHasher` is always a `scipy.sparse` matrix in the CSR format.

Feature hashing can be employed in document classification, but unlike `CountVectorizer`, `FeatureHasher` does not do word splitting or any other preprocessing except Unicode-to-UTF-8 encoding; see Vectorizing a large text corpus with the hashing trick, below, for a combined tokenizer/hasher.

As an example, consider a word-level natural language processing task that needs features extracted from `(token, part_of_speech)` pairs. One could use a Python generator function to extract features:
def token_features(token, part_of_speech):
    if token.isdigit():
        yield "numeric"
    else:
        yield "token=\{\}".format(token.lower())
        yield "token, pos=\{\},\{\}".format(token, part_of_speech)
    if token[0].isupper():
        yield "uppercase_initial"
    if token.isupper():
        yield "all_uppercase"
    yield "pos=\{\}".format(part_of_speech)

Then, the raw_X to be fed to FeatureHasher.transform can be constructed using:

raw_X = (token_features(tok, pos_tagger(tok)) for tok in corpus)

and fed to a hasher with:

hasher = FeatureHasher(input_type='string')
X = hasher.transform(raw_X)

to get a scipy.sparse matrix X.

Note the use of a generator comprehension, which introduces laziness into the feature extraction: tokens are only processed on demand from the hasher.

**Implementation details**

*FeatureHasher* uses the signed 32-bit variant of MurmurHash3. As a result (and because of limitations in scipy.sparse), the maximum number of features supported is currently $2^{31} - 1$.

The original formulation of the hashing trick by Weinberger et al. used two separate hash functions $h$ and $\xi$ to determine the column index and sign of a feature, respectively. The present implementation works under the assumption that the sign bit of MurmurHash3 is independent of its other bits.

Since a simple modulo is used to transform the hash function to a column index, it is advisable to use a power of two as the n_features parameter; otherwise the features will not be mapped evenly to the columns.

**References:**

- MurmurHash3.
Text feature extraction

The Bag of Words representation

Text Analysis is a major application field for machine learning algorithms. However the raw data, a sequence of symbols cannot be fed directly to the algorithms themselves as most of them expect numerical feature vectors with a fixed size rather than the raw text documents with variable length.

In order to address this, scikit-learn provides utilities for the most common ways to extract numerical features from text content, namely:

- **tokenizing** strings and giving an integer id for each possible token, for instance by using white-spaces and punctuation as token separators.
- **counting** the occurrences of tokens in each document.
- **normalizing** and weighting with diminishing importance tokens that occur in the majority of samples / documents.

In this scheme, features and samples are defined as follows:

- each individual token occurrence frequency (normalized or not) is treated as a feature.
- the vector of all the token frequencies for a given document is considered a multivariate sample.

A corpus of documents can thus be represented by a matrix with one row per document and one column per token (e.g. word) occurring in the corpus.

We call vectorization the general process of turning a collection of text documents into numerical feature vectors. This specific strategy (tokenization, counting and normalization) is called the Bag of Words or “Bag of n-grams” representation. Documents are described by word occurrences while completely ignoring the relative position information of the words in the document.

**Sparsity**

As most documents will typically use a very small subset of the words used in the corpus, the resulting matrix will have many feature values that are zeros (typically more than 99% of them).

For instance a collection of 10,000 short text documents (such as emails) will use a vocabulary with a size in the order of 100,000 unique words in total while each document will use 100 to 1000 unique words individually.

In order to be able to store such a matrix in memory but also to speed up algebraic operations matrix / vector, implementations will typically use a sparse representation such as the implementations available in the scipy.sparse package.

**Common Vectorizer usage**

`CountVectorizer` implements both tokenization and occurrence counting in a single class:

```python
>>> from sklearn.feature_extraction.text import CountVectorizer
>>> vectorizer = CountVectorizer()
```

This model has many parameters, however the default values are quite reasonable (please see the reference documentation for the details):

```python
>>> vectorizer = CountVectorizer()
>>> vectorizer
CountVectorizer()
```
Let’s use it to tokenize and count the word occurrences of a minimalistic corpus of text documents:

```python
>>> corpus = [
...   'This is the first document.',
...   'This is the second document.',
...   'And the third one.',
...   'Is this the first document?',
... ]
>>> X = vectorizer.fit_transform(corpus)
```

The default configuration tokenizes the string by extracting words of at least 2 letters. The specific function that does this step can be requested explicitly:

```python
>>> analyze = vectorizer.build_analyzer()
>>> analyze("This is a text document to analyze.") == (
...   ['this', 'is', 'text', 'document', 'to', 'analyze'])
True
```

Each term found by the analyzer during the fit is assigned a unique integer index corresponding to a column in the resulting matrix. This interpretation of the columns can be retrieved as follows:

```python
>>> vectorizer.get_feature_names() == (
...   ['and', 'document', 'first', 'is', 'one',
...   'second', 'the', 'third', 'this'])
True
```

The converse mapping from feature name to column index is stored in the `vocabulary_` attribute of the vectorizer:

```python
>>> vectorizer.vocabulary_.get('document')
1
```

Hence words that were not seen in the training corpus will be completely ignored in future calls to the transform method:

```python
>>> vectorizer.transform(['Something completely new.']).toarray()
array([[0, 0, 0, 0, 0, 0, 0, 0, 0]])
```

Note that in the previous corpus, the first and the last documents have exactly the same words hence are encoded in equal vectors. In particular we lose the information that the last document is an interrogative form. To preserve some of the local ordering information we can extract 2-grams of words in addition to the 1-grams (individual words):

```python
>>> bigram_vectorizer = CountVectorizer(ngram_range=(1, 2),
...   token_pattern=r'\b\w+\b', min_df=1)
>>> analyze = bigram_vectorizer.build_analyzer()
>>> analyze('Bi-grams are cool!') == (
...   ['bi', 'grams', 'are', 'cool', 'bi grams', 'grams are', 'are cool'])
True
```
The vocabulary extracted by this vectorizer is hence much bigger and can now resolve ambiguities encoded in local positioning patterns:

```python
>>> X_2 = bigram_vectorizer.fit_transform(corpus).toarray()
>>> X_2
array([[0, 0, 1, 1, 1, 1, 0, 0, 0, 1, 0, 0, 0, 0, 0, 1, 1, 0],
      [0, 0, 1, 0, 0, 1, 1, 0, 0, 2, 1, 1, 0, 1, 0, 0, 0, 1, 1, 0],
      [1, 1, 0, 0, 0, 0, 0, 0, 1, 0, 0, 1, 0, 0, 1, 0, 1, 1, 0, 0],
      [0, 0, 1, 1, 1, 1, 0, 1, 0, 0, 0, 1, 1, 0, 0, 0, 1, 0, 1, 0]])
```

In particular the interrogative form “Is this” is only present in the last document:

```python
>>> feature_index = bigram_vectorizer.vocabulary_.get('is this')
>>> X_2[:, feature_index]
array([0, 0, 0, 1])
```

### Using stop words

Stop words are words like “and”, “the”, “him”, which are presumed to be uninformative in representing the content of a text, and which may be removed to avoid them being construed as signal for prediction. Sometimes, however, similar words are useful for prediction, such as in classifying writing style or personality.

There are several known issues in our provided ‘english’ stop word list. It does not aim to be a general, ‘one-size-fits-all’ solution as some tasks may require a more custom solution. See [NQY18] for more details.

Please take care in choosing a stop word list. Popular stop word lists may include words that are highly informative to some tasks, such as `computer`.

You should also make sure that the stop word list has had the same preprocessing and tokenization applied as the one used in the vectorizer. The word `we've` is split into `we` and `ve` by CountVectorizer’s default tokenizer, so if `we've` is in stop_words, but `ve` is not, `ve` will be retained from `we've` in transformed text. Our vectorizers will try to identify and warn about some kinds of inconsistencies.

### References

**Tf–idf term weighting**

In a large text corpus, some words will be very present (e.g. “the”, “a”, “is” in English) hence carrying very little meaningful information about the actual contents of the document. If we were to feed the direct count data directly to a classifier those very frequent terms would shadow the frequencies of rarer yet more interesting terms.

In order to re-weight the count features into floating point values suitable for usage by a classifier it is very common to use the tf–idf transform.

Tf means **term-frequency** while tf–idf means term-frequency times **inverse document-frequency**: \( tf-idf(t,d) = tf(t,d) \times idf(t) \).

Using the `TfidfTransformer`'s default settings, `TfidfTransformer(norm='l2', use_idf=True, smooth_idf=True, sublinear_tf=False)` the term frequency, the number of times a term occurs in a given document, is multiplied with idf component, which is computed as

\[
idf(t) = \log \frac{1+n}{1+df(t)} + 1,
\]

where \( n \) is the total number of documents in the document set, and \( df(t) \) is the number of documents in the document set that contain term \( t \). The resulting tf-idf vectors are then normalized by the Euclidean norm:
\[ v_{\text{norm}} = \frac{v}{||v||_2} = \frac{v}{\sqrt{v_1^2 + v_2^2 + \cdots + v_n^2}}. \]

This was originally a term weighting scheme developed for information retrieval (as a ranking function for search engines results) that has also found good use in document classification and clustering.

The following sections contain further explanations and examples that illustrate how the tf-idfs are computed exactly and how the tf-idfs computed in scikit-learn's `TfidfTransformer` and `TfidfVectorizer` differ slightly from the standard textbook notation that defines the idf as:

\[ \text{idf}(t) = \log \frac{n}{df(t)}. \]

In the `TfidfTransformer` and `TfidfVectorizer` with `smooth_idf=False`, the “1” count is added to the idf instead of the idf’s denominator:

\[ \text{idf}(t) = \log \frac{n}{df(t) + 1} \]

This normalization is implemented by the `TfidfTransformer` class:

```python
>>> from sklearn.feature_extraction.text import TfidfTransformer
>>> transformer = TfidfTransformer(smooth_idf=False)
>>> transformer
TfidfTransformer(smooth_idf=False)
```

Again please see the reference documentation for the details on all the parameters.

Let’s take an example with the following counts. The first term is present 100% of the time hence not very interesting. The two other features only in less than 50% of the time hence probably more representative of the content of the documents:

```python
>>> counts = [[3, 0, 1],
...            [2, 0, 0],
...            [3, 2, 0],
...            [3, 0, 2]]
...>>> tfidf = transformer.fit_transform(counts)
...>>> tfidf
<6x3 sparse matrix of type '<... 'numpy.float64'>'
  with 9 stored elements in Compressed Sparse ... format>
...>>> tfidf.toarray()
array([[0.81940995, 0. , 0.57320793],
       [1. , 0. , 0. ],
       [1. , 0. , 0. ],
       [1. , 0. , 0. ],
       [0.47330339, 0.88089948, 0. ],
       [0.58149261, 0. , 0.81355169]])
```

Each row is normalized to have unit Euclidean norm:

\[ v_{\text{norm}} = \frac{v}{||v||_2} = \frac{v}{\sqrt{v_1^2 + v_2^2 + \cdots + v_n^2}}. \]

For example, we can compute the tf-idf of the first term in the first document in the `counts` array as follows:

\[ n = 6 \]
\[ \text{df}(t_{\text{term1}}) = 6 \]
\[ \text{idf}(t_{\text{term1}}) = \log \frac{n}{\text{df}(t_{\text{term1}})} + 1 = \log(1) + 1 = 1 \]
\[ \text{tf-idf}_{\text{term1}} = \text{tf} \times \text{idf} = 3 \times 1 = 3 \]
Now, if we repeat this computation for the remaining 2 terms in the document, we get

\[ \text{tf-idf}_{\text{term}2} = 0 \times (\log(6/1) + 1) = 0 \]
\[ \text{tf-idf}_{\text{term}3} = 1 \times (\log(6/2) + 1) \approx 2.0986 \]

and the vector of raw tf-idfs:

\[ \text{tf-idf}_{\text{raw}} = [3, 0, 2.0986] \]

Then, applying the Euclidean (L2) norm, we obtain the following tf-idfs for document 1:

\[ \sqrt{3^2 + 0^2 + 2.0986^2} = [0.819, 0, 0.573] \]

Furthermore, the default parameter smooth_idf=True adds “1” to the numerator and denominator as if an extra document was seen containing every term in the collection exactly once, which prevents zero divisions:

\[ \text{idf}(t) = \log \frac{1+n}{1+\text{df}(t)} + 1 \]

Using this modification, the tf-idf of the third term in document 1 changes to 1.8473:

\[ \text{tf-idf}_{\text{term}3} = 1 \times \log(7/3) + 1 \approx 1.8473 \]

And the L2-normalized tf-idf changes to

\[ \sqrt{3^2 + 0^2 + 1.8473^2} = [0.8515, 0, 0.5243] \]

The weights of each feature computed by the fit method call are stored in a model attribute:

```
>>> transformer = TfidfTransformer()
>>> transformer.fit_transform(counts).toarray()
array([[0.85151335, 0. , 0.52433293],
       [1. , 0. , 0.  ],
       [1. , 0. , 0.  ],
       [1. , 0. , 0.  ],
       [0.55422893, 0.83236428, 0.  ],
       [0.63035731, 0. , 0.77630514]])
```

As tf–idf is very often used for text features, there is also another class called TfidfVectorizer that combines all the options of CountVectorizer and TfidfTransformer in a single model:

```
>>> from sklearn.feature_extraction.text import TfidfVectorizer
>>> vectorizer = TfidfVectorizer()
>>> vectorizer.fit_transform(corpus)
<4x9 sparse matrix of type '<... 'numpy.float64'>'
 with 19 stored elements in Compressed Sparse ... format>
```

While the tf–idf normalization is often very useful, there might be cases where the binary occurrence markers might offer better features. This can be achieved by using the binary parameter of CountVectorizer. In particular, some estimators such as Bernoulli Naive Bayes explicitly model discrete boolean random variables. Also, very short texts are likely to have noisy tf–idf values while the binary occurrence info is more stable.

As usual the best way to adjust the feature extraction parameters is to use a cross-validated grid search, for instance by pipelining the feature extractor with a classifier:

- Sample pipeline for text feature extraction and evaluation
Decoding text files

Text is made of characters, but files are made of bytes. These bytes represent characters according to some *encoding*. To work with text files in Python, their bytes must be *decoded* to a character set called Unicode. Common encodings are ASCII, Latin-1 (Western Europe), KOI8-R (Russian) and the universal encodings UTF-8 and UTF-16. Many others exist.

**Note:** An encoding can also be called a ‘character set’, but this term is less accurate: several encodings can exist for a single character set.

The text feature extractors in scikit-learn know how to decode text files, but only if you tell them what encoding the files are in. The *CountVectorizer* takes an *encoding* parameter for this purpose. For modern text files, the correct encoding is probably UTF-8, which is therefore the default (*encoding=*utf-8*).

If the text you are loading is not actually encoded with UTF-8, however, you will get a *UnicodeDecodeError*. The vectorizers can be told to be silent about decoding errors by setting the *decode_error* parameter to either "ignore" or "replace". See the documentation for the Python function bytes.decode for more details (type help(bytes.decode) at the Python prompt).

If you are having trouble decoding text, here are some things to try:

- Find out what the actual encoding of the text is. The file might come with a header or README that tells you the encoding, or there might be some standard encoding you can assume based on where the text comes from.

- You may be able to find out what kind of encoding it is in general using the UNIX command file. The Python chardet module comes with a script called chardetect.py that will guess the specific encoding, though you cannot rely on its guess being correct.

- You could try UTF-8 and disregard the errors. You can decode byte strings with bytes.decode(errors='replace') to replace all decoding errors with a meaningless character, or set *decode_error='replace'* in the vectorizer. This may damage the usefulness of your features.

- Real text may come from a variety of sources that may have used different encodings, or even be sloppily decoded in a different encoding than the one it was encoded with. This is common in text retrieved from the Web. The Python package ftfy can automatically sort out some classes of decoding errors, so you could try decoding the unknown text as latin-1 and then using ftfy to fix errors.

- If the text is in a mish-mash of encodings that is simply too hard to sort out (which is the case for the 20 Newsgroups dataset), you can fall back on a simple single-byte encoding such as latin-1. Some text may display incorrectly, but at least the same sequence of bytes will always represent the same feature.

For example, the following snippet uses chardet (not shipped with scikit-learn, must be installed separately) to figure out the encoding of three texts. It then vectorizes the texts and prints the learned vocabulary. The output is not shown here.

```python
>>> import chardet
>>> text1 = b"Sei mir gegr\xc3\xbc\xc3\xfct mein Sauerkraut"
>>> text2 = b"holdselig sind deine Ger\xfcche"
>>> text3 = b"\xff\xfe\xa0\xe0\x00\xf0\x00\xf7\x00\xf8\x00\xe0\x00\xf9\x00\xe0\x00\xfa\x00\xe0\x00\xfb\x00\xe0\x00\xfc\x00\xe0\x00\xfd\x00\xe0\x00\xfe\x00\xe0\x00\xff\x00\xe0\x00"
>>> decoded = [x.decode(chardet.detect(x)['encoding']) for x in (text1, text2, text3)]
>>> v = CountVectorizer().fit(decoded).vocabulary_
>>> for term in v: print(v)
(Depending on the version of chardet, it might get the first one wrong.)
```
Applications and examples

The bag of words representation is quite simplistic but surprisingly useful in practice.

In particular in a supervised setting it can be successfully combined with fast and scalable linear models to train document classifiers, for instance:

• Classification of text documents using sparse features

In an unsupervised setting it can be used to group similar documents together by applying clustering algorithms such as K-means:

• Clustering text documents using k-means

Finally it is possible to discover the main topics of a corpus by relaxing the hard assignment constraint of clustering, for instance by using Non-negative matrix factorization (NMF or NNMF):

• Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation

Limitations of the Bag of Words representation

A collection of unigrams (what bag of words is) cannot capture phrases and multi-word expressions, effectively disregarding any word order dependence. Additionally, the bag of words model doesn’t account for potential misspellings or word derivations.

N-grams to the rescue! Instead of building a simple collection of unigrams (n=1), one might prefer a collection of bigrams (n=2), where occurrences of pairs of consecutive words are counted.

One might alternatively consider a collection of character n-grams, a representation resilient against misspellings and derivations.

For example, let’s say we’re dealing with a corpus of two documents: ['words', 'wprds']. The second document contains a misspelling of the word ‘words’. A simple bag of words representation would consider these two as very distinct documents, differing in both of the two possible features. A character 2-gram representation, however, would find the documents matching in 4 out of 8 features, which may help the preferred classifier decide better:

```python
>>> ngram_vectorizer = CountVectorizer(analyzer='char_wb', ngram_range=(2, 2))
>>> counts = ngram_vectorizer.fit_transform(['words', 'wprds'])
>>> ngram_vectorizer.get_feature_names() == (
...     ['w', 'ds', 'or', 'pr', 'rd', 's', 'wo', 'wp'])
True
>>> counts.toarray().astype(int)
array([[1, 1, 1, 0, 1, 1, 1, 0],
       [1, 1, 0, 1, 1, 1, 0, 1]])
```

In the above example, char_wb analyzer is used, which creates n-grams only from characters inside word boundaries (padded with space on each side). The char analyzer, alternatively, creates n-grams that span across words:

```python
>>> ngram_vectorizer = CountVectorizer(analyzer='char', ngram_range=(5, 5))
>>> ngram_vectorizer.fit_transform(['jumpy fox'])
<1x4 sparse matrix of type '<... 'numpy.int64'>'
     with 4 stored elements in Compressed Sparse ... format>
>>> ngram_vectorizer.get_feature_names() == (
...     ['fox', 'jump', 'jumpy', 'umpy'])
```

(continues on next page)
The word boundaries-aware variant `char_wb` is especially interesting for languages that use white-spaces for word separation as it generates significantly less noisy features than the raw `char` variant in that case. For such languages it can increase both the predictive accuracy and convergence speed of classifiers trained using such features while retaining the robustness with regards to misspellings and word derivations.

While some local positioning information can be preserved by extracting n-grams instead of individual words, bag of words and bag of n-grams destroy most of the inner structure of the document and hence most of the meaning carried by that internal structure.

In order to address the wider task of Natural Language Understanding, the local structure of sentences and paragraphs should thus be taken into account. Many such models will thus be casted as “Structured output” problems which are currently outside of the scope of scikit-learn.

**Vectorizing a large text corpus with the hashing trick**

The above vectorization scheme is simple but the fact that it holds an in-memory mapping from the string tokens to the integer feature indices (the `vocabulary_` attribute) causes several problems when dealing with large datasets:

- the larger the corpus, the larger the vocabulary will grow and hence the memory use too,
- fitting requires the allocation of intermediate data structures of size proportional to that of the original dataset.
- building the word-mapping requires a full pass over the dataset hence it is not possible to fit text classifiers in a strictly online manner.
- pickling and un-pickling vectorizers with a large `vocabulary_` can be very slow (typically much slower than pickling / un-pickling flat data structures such as a NumPy array of the same size),
- it is not easily possible to split the vectorization work into concurrent sub tasks as the `vocabulary_` attribute would have to be a shared state with a fine grained synchronization barrier: the mapping from token string to feature index is dependent on ordering of the first occurrence of each token hence would have to be shared, potentially harming the concurrent workers’ performance to the point of making them slower than the sequential variant.

It is possible to overcome those limitations by combining the “hashing trick” ([Feature hashing](https://scikit-learn.org/stable/modules/feature_extraction.html#hashing-trick)) implemented by the `FeatureHasher` class and the text preprocessing and tokenization features of the `CountVectorizer`.

This combination is implementing in `HashingVectorizer`, a transformer class that is mostly API compatible with `CountVectorizer`. `HashingVectorizer` is stateless, meaning that you don’t have to call `fit` on it:

```python
>>> from sklearn.feature_extraction.text import HashingVectorizer
>>> hv = HashingVectorizer(n_features=10)
>>> hv.transform(corpus)
<4x10 sparse matrix of type '<... 'numpy.float64'>'
   with 16 stored elements in Compressed Sparse ... format>
```
You can see that 16 non-zero feature tokens were extracted in the vector output: this is less than the 19 non-zeros extracted previously by the `CountVectorizer` on the same toy corpus. The discrepancy comes from hash function collisions because of the low value of the `n_features` parameter.

In a real world setting, the `n_features` parameter can be left to its default value of $2^{20}$ (roughly one million possible features). If memory or downstream models size is an issue selecting a lower value such as $2^{18}$ might help without introducing too many additional collisions on typical text classification tasks.

Note that the dimensionality does not affect the CPU training time of algorithms which operate on CSR matrices (`LinearSVC(dual=True)`, `Perceptron`, `SGDClassifier`, `PassiveAggressive`) but it does for algorithms that work with CSC matrices (`LinearSVC(dual=False)`, `Lasso`, etc).

Let’s try again with the default setting:

```python
>>> hv = HashingVectorizer()
>>> hv.transform(corpus)
<4x1048576 sparse matrix of type '<... 'numpy.float64'>'
    with 19 stored elements in Compressed Sparse ... format>
```

We no longer get the collisions, but this comes at the expense of a much larger dimensionality of the output space. Of course, other terms than the 19 used here might still collide with each other.

The `HashingVectorizer` also comes with the following limitations:

- it is not possible to invert the model (no `inverse_transform` method), nor to access the original string representation of the features, because of the one-way nature of the hash function that performs the mapping.
- it does not provide IDF weighting as that would introduce statefulness in the model. A `TfidfTransformer` can be appended to it in a pipeline if required.

### Performing out-of-core scaling with HashingVectorizer

An interesting development of using a `HashingVectorizer` is the ability to perform out-of-core scaling. This means that we can learn from data that does not fit into the computer’s main memory.

A strategy to implement out-of-core scaling is to stream data to the estimator in mini-batches. Each mini-batch is vectorized using `HashingVectorizer` so as to guarantee that the input space of the estimator has always the same dimensionality. The amount of memory used at any time is thus bounded by the size of a mini-batch. Although there is no limit to the amount of data that can be ingested using such an approach, from a practical point of view the learning time is often limited by the CPU time one wants to spend on the task.

For a full-fledged example of out-of-core scaling in a text classification task see [Out-of-core classification of text documents](#).

### Customizing the vectorizer classes

It is possible to customize the behavior by passing a callable to the vectorizer constructor:

```python
>>> def my_tokenizer(s):
...     return s.split()
... >>> vectorizer = CountVectorizer(tokenizer=my_tokenizer)
... >>> vectorizer.build_analyzer()(u"Some... punctuation!") == {
...     'some...', 'punctuation!'}
True
```

In particular we name:
scikit-learn user guide, Release 0.24.0

• preprocessor: a callable that takes an entire document as input (as a single string), and returns a possibly
transformed version of the document, still as an entire string. This can be used to remove HTML tags, lowercase
the entire document, etc.
• tokenizer: a callable that takes the output from the preprocessor and splits it into tokens, then returns a list
of these.
• analyzer: a callable that replaces the preprocessor and tokenizer. The default analyzers all call the preprocessor and tokenizer, but custom analyzers will skip this. N-gram extraction and stop word filtering take place
at the analyzer level, so a custom analyzer may have to reproduce these steps.
(Lucene users might recognize these names, but be aware that scikit-learn concepts may not map one-to-one onto
Lucene concepts.)
To make the preprocessor, tokenizer and analyzers aware of the model parameters it is possible to derive from the class
and override the build_preprocessor, build_tokenizer and build_analyzer factory methods instead
of passing custom functions.
Some tips and tricks:
• If documents are pre-tokenized by an external package, then store them in files (or strings) with the tokens
separated by whitespace and pass analyzer=str.split
• Fancy token-level analysis such as stemming, lemmatizing, compound splitting, filtering based on part-ofspeech, etc. are not included in the scikit-learn codebase, but can be added by customizing either the tokenizer
or the analyzer. Here’s a CountVectorizer with a tokenizer and lemmatizer using NLTK:
>>>
>>>
>>>
...
...
...
...
...
>>>

from nltk import word_tokenize
from nltk.stem import WordNetLemmatizer
class LemmaTokenizer:
def __init__(self):
self.wnl = WordNetLemmatizer()
def __call__(self, doc):
return [self.wnl.lemmatize(t) for t in word_tokenize(doc)]
vect = CountVectorizer(tokenizer=LemmaTokenizer())

(Note that this will not filter out punctuation.)
The following example will, for instance, transform some British spelling to American spelling:
>>> import re
>>> def to_british(tokens):
...
for t in tokens:
...
t = re.sub(r"(...)our$", r"\1or", t)
...
t = re.sub(r"([bt])re$", r"\1er", t)
...
t = re.sub(r"([iy])s(e$|ing|ation)", r"\1z\2", t)
...
t = re.sub(r"ogue$", "og", t)
...
yield t
...
>>> class CustomVectorizer(CountVectorizer):
...
def build_tokenizer(self):
...
tokenize = super().build_tokenizer()
...
return lambda doc: list(to_british(tokenize(doc)))
...
>>> print(CustomVectorizer().build_analyzer()(u"color colour"))
[...'color', ...'color']

for other styles of preprocessing; examples include stemming, lemmatization, or normalizing numerical tokens,
with the latter illustrated in:

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Biclustering documents with the Spectral Co-clustering algorithm

Customizing the vectorizer can also be useful when handling Asian languages that do not use an explicit word separator such as whitespace.

Image feature extraction

Patch extraction

The `extract_patches_2d` function extracts patches from an image stored as a two-dimensional array, or three-dimensional with color information along the third axis. For rebuilding an image from all its patches, use `reconstruct_from_patches_2d`. For example, let us generate a 4x4 pixel picture with 3 color channels (e.g. in RGB format):

```
>>> import numpy as np
>>> from sklearn.feature_extraction import image

>>> one_image = np.arange(4 * 4 * 3).reshape((4, 4, 3))

>>> one_image[:, :, 0]  # R channel of a fake RGB picture
array([[ 0,  3,  6,  9],
       [12, 15, 18, 21],
       [24, 27, 30, 33],
       [36, 39, 42, 45]])

>>> patches = image.extract_patches_2d(one_image, (2, 2), max_patches=2, ...
... random_state=0)

>>> patches.shape
(2, 2, 2, 3)

>>> patches[:, :, :, 0]
array([[ 0,  3],
       [12, 15],
       [15, 18],
       [27, 30]])

>>> patches = image.extract_patches_2d(one_image, (2, 2))

>>> patches.shape
(9, 2, 2, 3)

>>> patches[4, :, :, 0]
array([[15, 18],
       [27, 30]])

Let us now try to reconstruct the original image from the patches by averaging on overlapping areas:

```
>>> reconstructed = image.reconstruct_from_patches_2d(patches, (4, 4, 3))

>>> np.testing.assert_array_equal(one_image, reconstructed)
```

The `PatchExtractor` class works in the same way as `extract_patches_2d`, only it supports multiple images as input. It is implemented as an estimator, so it can be used in pipelines. See:

```
>>> five_images = np.arange(5 * 4 * 4 * 3).reshape(5, 4, 4, 3)

>>> patches = image.PatchExtractor(patch_size=(2, 2)).transform(five_images)

>>> patches.shape
(45, 2, 2, 3)
```
Connectivity graph of an image

Several estimators in the scikit-learn can use connectivity information between features or samples. For instance Ward clustering (Hierarchical clustering) can cluster together only neighboring pixels of an image, thus forming contiguous patches:

For this purpose, the estimators use a ‘connectivity’ matrix, giving which samples are connected.

The function `img_to_graph` returns such a matrix from a 2D or 3D image. Similarly, `grid_to_graph` build a connectivity matrix for images given the shape of these image.

These matrices can be used to impose connectivity in estimators that use connectivity information, such as Ward clustering (Hierarchical clustering), but also to build precomputed kernels, or similarity matrices.

Note: Examples

- A demo of structured Ward hierarchical clustering on an image of coins
- Spectral clustering for image segmentation
- Feature agglomeration vs. univariate selection

4.6.3 Preprocessing data

The `sklearn.preprocessing` package provides several common utility functions and transformer classes to change raw feature vectors into a representation that is more suitable for the downstream estimators.

In general, learning algorithms benefit from standardization of the data set. If some outliers are present in the set, robust scalers or transformers are more appropriate. The behaviors of the different scalers, transformers, and normalizers on a dataset containing marginal outliers is highlighted in Compare the effect of different scalers on data with outliers.
Standardization, or mean removal and variance scaling

Standardization of datasets is a common requirement for many machine learning estimators implemented in scikit-learn; they might behave badly if the individual features do not more or less look like standard normally distributed data: Gaussian with zero mean and unit variance.

In practice we often ignore the shape of the distribution and just transform the data to center it by removing the mean value of each feature, then scale it by dividing non-constant features by their standard deviation.

For instance, many elements used in the objective function of a learning algorithm (such as the RBF kernel of Support Vector Machines or the 11 and 12 regularizers of linear models) assume that all features are centered around zero and have variance in the same order. If a feature has a variance that is orders of magnitude larger than others, it might dominate the objective function and make the estimator unable to learn from other features correctly as expected.

The preprocessing module provides the StandardScaler utility class, which is a quick and easy way to perform the following operation on an array-like dataset:

```python
>>> from sklearn import preprocessing
>>> import numpy as np

>>> X_train = np.array([[ 1., -1., 2.],
                     [ 2., 0., 0.],
                     [ 0., 1., -1.]])

>>> scaler = preprocessing.StandardScaler().fit(X_train)
>>> scaler
StandardScaler()

>>> scaler.mean_
array([1. ..., 0. ..., 0.33 ...])

>>> scaler.scale_
array([0.81 ..., 0.81 ..., 1.24 ...])

>>> X_scaled = scaler.transform(X_train)
>>> X_scaled
array([[ 0. ..., -1.22 ..., 1.33 ...],
       [ 1.22 ..., 0. ..., -0.26 ...],
       [-1.22 ..., 1.22 ..., -1.06 ...]])

Scaled data has zero mean and unit variance:

```python
>>> X_scaled.mean(axis=0)
array([0., 0., 0.])

>>> X_scaled.std(axis=0)
array([1., 1., 1.])
```

This class implements the Transformer API to compute the mean and standard deviation on a training set so as to be able to later re-apply the same transformation on the testing set. This class is hence suitable for use in the early steps of a Pipeline:

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler

>>> X, y = make_classification(random_state=42)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)
```
It is possible to disable either centering or scaling by either passing `with_mean=False` or `with_std=False` to the constructor of `StandardScaler`.

### Scaling features to a range

An alternative standardization is scaling features to lie between a given minimum and maximum value, often between zero and one, or so that the maximum absolute value of each feature is scaled to unit size. This can be achieved using `MinMaxScaler` or `MaxAbsScaler`, respectively.

The motivation to use this scaling include robustness to very small standard deviations of features and preserving zero entries in sparse data.

Here is an example to scale a toy data matrix to the $[0, 1]$ range:

```python
>>> X_train = np.array([[ 1., -1., 2.],
...                      [ 2., 0., 0.],
...                      [ 0., 1., -1.]]
...)
>>> min_max_scaler = preprocessing.MinMaxScaler()
>>> X_train_minmax = min_max_scaler.fit_transform(X_train)
>>> X_train_minmax
array([[0.5 , 0. , 1. ],
       [1. , 0.5 , 0.33333333],
       [0. , 1. , 0. ]])
```

The same instance of the transformer can then be applied to some new test data unseen during the fit call: the same scaling and shifting operations will be applied to be consistent with the transformation performed on the train data:

```python
>>> X_test = np.array([[-3., -1., 4.]]
...)
>>> X_test_minmax = min_max_scaler.transform(X_test)
>>> X_test_minmax
array([[-1.5 , 0. , 1.66666667]])
```

It is possible to introspect the scaler attributes to find about the exact nature of the transformation learned on the training data:

```python
>>> min_max_scaler.scale_
array([0.5 , 0.5 , 0.33333333])
>>> min_max_scaler.min_
array([0. , 0.5 , 0.33333333])
```

If `MinMaxScaler` is given an explicit `feature_range=(min, max)` the full formula is:

$$X_{\text{std}} = \frac{X - \text{min}(axis=0)}{\text{max}(axis=0) - \text{min}(axis=0)}$$

$$X_{\text{scaled}} = X_{\text{std}} \times (\text{max} - \text{min}) + \text{min}$$
MaxAbsScaler works in a very similar fashion, but scales in a way that the training data lies within the range \([-1, 1]\) by dividing through the largest maximum value in each feature. It is meant for data that is already centered at zero or sparse data.

Here is how to use the toy data from the previous example with this scaler:

```python
generate_code_blocks
$$\text{X_train = np.array([[1., -1., 2.],
                  [2., 0., 0.],
                  [0., 1., -1.]]})$$
$$\text{max_abs_scaler = preprocessing.MaxAbsScaler()}
\text{X_train_maxabs = max_abs_scaler.fit_transform(X_train)}$$
$$\text{X_train_maxabs}
\text{array([[ 0.5, -1. , 1. ],}
                  [ 1. , 0. , 0. ],
                  [ 0. , 1. , -0.5]])}$$
$$\text{X_test = np.array([[-3., -1., 4.]]})$$
$$\text{X_test_maxabs = max_abs_scaler.transform(X_test)}$$
$$\text{X_test_maxabs}
\text{array([[-1.5, -1. , 2. ]])}$$
$$\text{max_abs_scaler.scale_}
\text{array([2., 1., 2.])}$$
```

### Scaling sparse data

Centering sparse data would destroy the sparseness structure in the data, and thus rarely is a sensible thing to do. However, it can make sense to scale sparse inputs, especially if features are on different scales.

MaxAbsScaler was specifically designed for scaling sparse data, and is the recommended way to go about this. However, StandardScaler can accept scipy.sparse matrices as input, as long as with_mean=False is explicitly passed to the constructor. Otherwise a ValueError will be raised as silently centering would break the sparseness and would often crash the execution by allocating excessive amounts of memory unintentionally. RobustScaler cannot be fitted to sparse inputs, but you can use the transform method on sparse inputs.

Note that the scalers accept both Compressed Sparse Rows and Compressed Sparse Columns format (see scipy.sparse.csr_matrix and scipy.sparse.csc_matrix). Any other sparse input will be converted to the Compressed Sparse Rows representation. To avoid unnecessary memory copies, it is recommended to choose the CSR or CSC representation upstream.

Finally, if the centered data is expected to be small enough, explicitly converting the input to an array using the toarray method of sparse matrices is another option.

### Scaling data with outliers

If your data contains many outliers, scaling using the mean and variance of the data is likely to not work very well. In these cases, you can use RobustScaler as a drop-in replacement instead. It uses more robust estimates for the center and range of your data.

### References:

Further discussion on the importance of centering and scaling data is available on this FAQ: Should I normalize/standardize/rescale the data?
Scaling vs Whitening

It is sometimes not enough to center and scale the features independently, since a downstream model can further make some assumption on the linear independence of the features.

To address this issue you can use `PCA` with `whiten=True` to further remove the linear correlation across features.

Centering kernel matrices

If you have a kernel matrix of a kernel $K$ that computes a dot product in a feature space defined by function $\phi$, a `KernelCenterer` can transform the kernel matrix so that it contains inner products in the feature space defined by $\phi$ followed by removal of the mean in that space.

Non-linear transformation

Two types of transformations are available: quantile transforms and power transforms. Both quantile and power transforms are based on monotonic transformations of the features and thus preserve the rank of the values along each feature.

Quantile transforms put all features into the same desired distribution based on the formula $G^{-1}(F(X))$ where $F$ is the cumulative distribution function of the feature and $G^{-1}$ the quantile function of the desired output distribution $G$.

This formula is using the two following facts: (i) if $X$ is a random variable with a continuous cumulative distribution function $F$ then $F(X)$ is uniformly distributed on $[0, 1]$; (ii) if $U$ is a random variable with uniform distribution on $[0, 1]$ then $G^{-1}(U)$ has distribution $G$. By performing a rank transformation, a quantile transform smooths out unusual distributions and is less influenced by outliers than scaling methods. It does, however, distort correlations and distances within and across features.

Power transforms are a family of parametric transformations that aim to map data from any distribution to as close to a Gaussian distribution.

Mapping to a Uniform distribution

`QuantileTransformer` provides a non-parametric transformation to map the data to a uniform distribution with values between 0 and 1:

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
>>> quantile_transformer = preprocessing.QuantileTransformer(random_state=0)
>>> X_train_trans = quantile_transformer.fit_transform(X_train)
>>> X_test_trans = quantile_transformer.transform(X_test)

This feature corresponds to the sepal length in cm. Once the quantile transformation applied, those landmarks approach closely the percentiles previously defined:

```python
>>> np.percentile(X_train[:, 0], [0, 25, 50, 75, 100])
array([ 4.3, 5.1, 5.8, 6.5, 7.9])
```

This can be confirmed on a independent testing set with similar remarks:
Mapping to a Gaussian distribution

In many modeling scenarios, normality of the features in a dataset is desirable. Power transforms are a family of parametric, monotonic transformations that aim to map data from any distribution to as close to a Gaussian distribution as possible in order to stabilize variance and minimize skewness.

`PowerTransformer` currently provides two such power transformations, the Yeo-Johnson transform and the Box-Cox transform.

The Yeo-Johnson transform is given by:

\[
x_i^{(\lambda)} = \begin{cases} 
\frac{(x_i + 1)^\lambda - 1}{\lambda} & \text{if } \lambda \neq 0, x_i \geq 0, \\
\ln (x_i + 1) & \text{if } \lambda = 0, x_i \geq 0 \\
-\frac{(-x_i + 1)^2 - 1}{(2 - \lambda)} & \text{if } \lambda \neq 2, x_i < 0, \\
-\ln(-x_i + 1) & \text{if } \lambda = 2, x_i < 0
\end{cases}
\]

while the Box-Cox transform is given by:

\[
x_i^{(\lambda)} = \begin{cases} 
\frac{x_i^\lambda - 1}{\lambda} & \text{if } \lambda \neq 0, \\
\ln (x_i) & \text{if } \lambda = 0
\end{cases}
\]

Box-Cox can only be applied to strictly positive data. In both methods, the transformation is parameterized by \(\lambda\), which is determined through maximum likelihood estimation. Here is an example of using Box-Cox to map samples drawn from a lognormal distribution to a normal distribution:

```python
>>> pt = preprocessing.PowerTransformer(method='box-cox', standardize=False)
>>> X_lognormal = np.random.RandomState(616).lognormal(size=(3, 3))
>>> X_lognormal
array([[1.28..., 1.18..., 0.84...],
       [0.94..., 1.60..., 0.38...],
       [1.35..., 0.21..., 1.09...]])
>>> pt.fit_transform(X_lognormal)
array([[ 0.49...,  0.17..., -0.15...],
       [-0.05...,  0.58..., -0.57...],
       [ 0.69..., -0.84...,  0.10...]])
```

While the above example sets the `standardize` option to `False`, `PowerTransformer` will apply zero-mean, unit-variance normalization to the transformed output by default.

Below are examples of Box-Cox and Yeo-Johnson applied to various probability distributions. Note that when applied to certain distributions, the power transforms achieve very Gaussian-like results, but with others, they are ineffective. This highlights the importance of visualizing the data before and after transformation.

It is also possible to map data to a normal distribution using `QuantileTransformer` by setting `output_distribution='normal'`. Using the earlier example with the iris dataset:
Thus the median of the input becomes the mean of the output, centered at 0. The normal output is clipped so that the input's minimum and maximum — corresponding to the 1e-7 and 1 - 1e-7 quantiles respectively — do not become infinite under the transformation.

**Normalization**

**Normalization** is the process of **scaling individual samples to have unit norm**. This process can be useful if you plan to use a quadratic form such as the dot-product or any other kernel to quantify the similarity of any pair of samples.

This assumption is the base of the Vector Space Model often used in text classification and clustering contexts.

The function `normalize` provides a quick and easy way to perform this operation on a single array-like dataset, either using the l1, l2, or max norms:

```python
>>> X = [[ 1., -1., 2.],
       ... [ 2., 0., 0.],
       ... [ 0., 1., -1.]]
>>> X_normalized = preprocessing.normalize(X, norm='l2')
```

The `preprocessing` module further provides a utility class `Normalizer` that implements the same operation using the Transformer API (even though the `fit` method is useless in this case: the class is stateless as this operation treats samples independently).

This class is hence suitable for use in the early steps of a **Pipeline**:

```python
>>> normalizer = preprocessing.Normalizer().fit(X)  # fit does nothing
>>> normalizer
Normalizer()
```

The normalizer instance can then be used on sample vectors as any transformer:

```python
>>> normalizer.transform(X)
array([[ 0.40..., -0.40..., 0.81...],
       [ 1. ..., 0. ..., 0. ...],
       [ 0. ..., 0.70..., -0.70...]])
```

Note: L2 normalization is also known as spatial sign preprocessing.

---

4.6. Dataset transformations
Sparse input

`normalize` and `Normalizer` accept both dense array-like and sparse matrices from scipy.sparse as input. For sparse input the data is converted to the Compressed Sparse Rows representation (see scipy.sparse.csr_matrix) before being fed to efficient Cython routines. To avoid unnecessary memory copies, it is recommended to choose the CSR representation upstream.

Encoding categorical features

Often features are not given as continuous values but categorical. For example a person could have features ["male", "female"], ["from Europe", "from US", "from Asia"], ["uses Firefox", "uses Chrome", "uses Safari", "uses Internet Explorer"]. Such features can be efficiently coded as integers, for instance ["male", "from US", "uses Internet Explorer"] could be expressed as [0, 1, 3] while ["female", "from Asia", "uses Chrome"] would be [1, 2, 1].

To convert categorical features to such integer codes, we can use the `OrdinalEncoder`. This estimator transforms each categorical feature to one new feature of integers (0 to n_categories - 1):

```python
>>> enc = preprocessing.OrdinalEncoder()
>>> X = [['male', 'from US', 'uses Safari'], ['female', 'from Europe', 'uses Firefox']]
>>> enc.fit(X)
OrdinalEncoder()
>>> enc.transform([['female', 'from US', 'uses Safari']])
```

Such integer representation can, however, not be used directly with all scikit-learn estimators, as these expect continuous input, and would interpret the categories as being ordered, which is often not desired (i.e. the set of browsers was ordered arbitrarily).

Another possibility to convert categorical features to features that can be used with scikit-learn estimators is to use a one-of-K, also known as one-hot or dummy encoding. This type of encoding can be obtained with the `OneHotEncoder`, which transforms each categorical feature with n_categories possible values into n_categories binary features, with one of them 1, and all others 0.

Continuing the example above:

```python
>>> enc = preprocessing.OneHotEncoder()
>>> X = [['male', 'from US', 'uses Safari'], ['female', 'from Europe', 'uses Firefox']]
>>> enc.fit(X)
OneHotEncoder()
>>> enc.transform([['female', 'from US', 'uses Safari'],
... ['male', 'from Europe', 'uses Safari']]).toarray()
```

By default, the values each feature can take is inferred automatically from the dataset and can be found in the `categories_` attribute:

```python
>>> enc.categories_
[array(["female", "male"], dtype=object), array(["from Europe", "from US"],
... dtype=object), array(["uses Firefox", "uses Safari"], dtype=object)]
```
It is possible to specify this explicitly using the parameter `categories`. There are two genders, four possible continents and four web browsers in our dataset:

```python
>>> genders = ['female', 'male']
>>> locations = ['from Africa', 'from Asia', 'from Europe', 'from US']
>>> browsers = ['uses Chrome', 'uses Firefox', 'uses IE', 'uses Safari']
>>> enc = preprocessing.OneHotEncoder(categories=[genders, locations, browsers])
>>> # Note that for there are missing categorical values for the 2nd and 3rd
>>> # feature
>>> X = [['male', 'from US', 'uses Safari'], ['female', 'from Europe', 'uses Firefox']]
>>> enc.fit(X)
OneHotEncoder(categories=[[‘female’, ‘male’],
                         [‘from Africa’, ‘from Asia’, ‘from Europe’,
                          ‘from US’],
                         [‘uses Chrome’, ‘uses Firefox’, ‘uses IE’,
                          ‘uses Safari’]])
>>> enc.transform([['female', 'from Asia', 'uses Chrome']]).toarray()
array([[0., 1., 0., 0., 0., 0., 0., 0.]])
```

If there is a possibility that the training data might have missing categorical features, it can often be better to specify `handle_unknown='ignore'` instead of setting the `categories` manually as above. When `handle_unknown='ignore'` is specified and unknown categories are encountered during transform, no error will be raised but the resulting one-hot encoded columns for this feature will be all zeros (`handle_unknown='ignore'` is only supported for one-hot encoding):

```python
>>> enc = preprocessing.OneHotEncoder(handle_unknown='ignore')
>>> X = [['male', 'from US', 'uses Safari'], ['female', 'from Europe', 'uses Firefox']]
>>> enc.fit(X)
OneHotEncoder(handle_unknown='ignore')
>>> enc.transform([['female', 'from Asia', 'uses Chrome']]).toarray()
array([[1., 0., 0., 1., 0., 0., 1., 0., 0., 0.]])
```

It is also possible to encode each column into \(n_{\text{categories}} - 1\) columns instead of \(n_{\text{categories}}\) columns by using the `drop` parameter. This parameter allows the user to specify a category for each feature to be dropped. This is useful to avoid co-linearity in the input matrix in some classifiers. Such functionality is useful, for example, when using non-regularized regression (`LinearRegression`), since co-linearity would cause the covariance matrix to be non-invertible. When this parameter is not None, `handle_unknown` must be set to `error`:

```python
>>> X = [['male', 'US', 'Safari'],
...       ['female', 'Europe', 'Firefox'],
...       ['female', 'Asia', 'Chrome']]
>>> drop_enc = preprocessing.OneHotEncoder(drop='first').fit(X)
>>> drop_enc.categories_
[array([‘female’, ‘male’], dtype=object), array([‘from Europe’, ‘from US’],
                                            dtype=object),
                                            array([‘uses Firefox’, ‘uses Safari’],
                                                   dtype=object)]
>>> drop_enc.transform(X).toarray()
array([[1., 1., 1.],
       [0., 0., 0.]])
```

One might want to drop one of the two columns only for features with 2 categories. In this case, you can set the parameter `drop='if_binary'`:

```python
>>> X = [['male', 'US', 'Safari'],
...       ['female', 'Europe', 'Firefox'],
...       ['female', 'Asia', 'Chrome']]
>>> drop_enc = preprocessing.OneHotEncoder(drop='if_binary').fit(X)
```

(continues on next page)
In the transformed $X$, the first column is the encoding of the feature with categories “male”/“female”, while the remaining 6 columns is the encoding of the 2 features with respectively 3 categories each.

OneHotEncoder supports categorical features with missing values by considering the missing values as an additional category:

```python
>>> X = [['male', 'Safari'], ...
     ['female', None], ...
     [np.nan, 'Firefox']]
>>> enc = preprocessing.OneHotEncoder(handle_unknown='error').fit(X)
>>> enc.categories_
[array(['female', 'male', nan], dtype=object),
 array(['Firefox', 'Safari', None], dtype=object)]
>>> enc.transform(X).toarray()
array([[0., 1., 0., 0., 1., 0.],
       [1., 0., 0., 0., 0., 1.],
       [0., 0., 1., 1., 0., 0.]])
```

If a feature contains both np.nan and None, they will be considered separate categories:

```python
>>> X = [['Safari'], [None], [np.nan], ['Firefox']]
>>> enc = preprocessing.OneHotEncoder(handle_unknown='error').fit(X)
>>> enc.categories_
[array([Firefox', 'Safari', None, nan], dtype=object)]
>>> enc.transform(X).toarray()
array([[0., 1., 0., 0.],
[0., 0., 1., 0.],
[0., 0., 0., 1.],
[1., 0., 0., 0.]])
```

See Loading features from dicts for categorical features that are represented as a dict, not as scalars.
Discretization

Discretization (otherwise known as quantization or binning) provides a way to partition continuous features into discrete values. Certain datasets with continuous features may benefit from discretization, because discretization can transform the dataset of continuous attributes to one with only nominal attributes.

One-hot encoded discretized features can make a model more expressive, while maintaining interpretability. For instance, pre-processing with a discretizer can introduce nonlinearity to linear models.

K-bins discretization

`KBinsDiscretizer` discretizes features into \( k \) bins:

```python
def X = np.array([[ -3., 5., 15 ],
                 [  0., 6., 14 ],
                 [  6., 3., 11 ]])
def est = preprocessing.KBinsDiscretizer(n_bins=[3, 2, 2], encode='ordinal').fit(X)
```

By default the output is one-hot encoded into a sparse matrix (See Encoding categorical features) and this can be configured with the `encode` parameter. For each feature, the bin edges are computed during `fit` and together with the number of bins, they will define the intervals. Therefore, for the current example, these intervals are defined as:

- **feature 1**: \([-\infty, -1), [-1, 2), [2, \infty)\]
- **feature 2**: \([-\infty, 5), [5, \infty)\]
- **feature 3**: \([-\infty, 14), [14, \infty)\]

Based on these bin intervals, \( X \) is transformed as follows:

```python
def est.transform(X)
deX = np.array([[ 0., 1., 1.],
               [ 1., 1., 1.],
               [ 2., 0., 0.]])
```

The resulting dataset contains ordinal attributes which can be further used in a `Pipeline`.

Discretization is similar to constructing histograms for continuous data. However, histograms focus on counting features which fall into particular bins, whereas discretization focuses on assigning feature values to these bins.

`KBinsDiscretizer` implements different binning strategies, which can be selected with the `strategy` parameter. The ‘uniform’ strategy uses constant-width bins. The ‘quantile’ strategy uses the quantiles values to have equally populated bins in each feature. The ‘kmeans’ strategy defines bins based on a k-means clustering procedure performed on each feature independently.

Be aware that one can specify custom bins by passing a callable defining the discretization strategy to `FunctionTransformer`. For instance, we can use the Pandas function `pandas.cut`:

```python
def import pandas as pd
>> def import numpy as np
>> def bins = [0, 1, 13, 20, 60, np.inf]
>> def labels = ['infant', 'kid', 'teen', 'adult', 'senior citizen']
>> def transformer = preprocessing.FunctionTransformer(...
    pd.cut, kw_args={'bins': bins, 'labels': labels, 'rethbins': False})
>> def X = np.array([0.2, 2, 15, 25, 97])
>> def transformer.fit_transform(X)
['infant', 'kid', 'teen', 'adult', 'senior citizen']
Categories (5, object): ['infant' < 'kid' < 'teen' < 'adult' < 'senior citizen']
```
Examples:

- Using KBinsDiscretizer to discretize continuous features
- Feature discretization
- Demonstrating the different strategies of KBinsDiscretizer

Feature binarization

Feature binarization is the process of thresholding numerical features to get boolean values. This can be useful for downstream probabilistic estimators that make assumption that the input data is distributed according to a multi-variate Bernoulli distribution. For instance, this is the case for the BernoulliRBM.

It is also common among the text processing community to use binary feature values (probably to simplify the probabilistic reasoning) even if normalized counts (a.k.a. term frequencies) or TF-IDF valued features often perform slightly better in practice.

As for the Normalizer, the utility class Binarizer is meant to be used in the early stages of Pipeline. The fit method does nothing as each sample is treated independently of others:

```python
>>> X = [[ 1., -1., 2.],
...      [ 2., 0., 0.],
...      [ 0., 1., -1.]]

>>> binarizer = preprocessing.Binarizer().fit(X)  # fit does nothing
>>> binarizer
Binarizer()

>>> binarizer.transform(X)
array([[1., 0., 1.],
       [1., 0., 0.],
       [0., 1., 0.]])
```

It is possible to adjust the threshold of the binarizer:

```python
>>> binarizer = preprocessing.Binarizer(threshold=1.1)
>>> binarizer
Binarizer()

>>> binarizer.transform(X)
array([[0., 0., 1.],
       [1., 0., 0.],
       [0., 0., 0.]])
```

As for the Normalizer class, the preprocessing module provides a companion function binarize to be used when the transformer API is not necessary.

Note that the Binarizer is similar to the KBinsDiscretizer when $k = 2$, and when the bin edge is at the value threshold.

Sparse input

binarize and Binarizer accept both dense array-like and sparse matrices from scipy.sparse as input.

For sparse input the data is converted to the Compressed Sparse Rows representation (see scipy.sparse.csr_matrix). To avoid unnecessary memory copies, it is recommended to choose the CSR representation up-stream.
Imputation of missing values

Tools for imputing missing values are discussed at Imputation of missing values.

Generating polynomial features

Often it’s useful to add complexity to the model by considering nonlinear features of the input data. A simple and common method to use is polynomial features, which can get features’ high-order and interaction terms. It is implemented in PolynomialFeatures:

```python
>>> import numpy as np
>>> from sklearn.preprocessing import PolynomialFeatures
>>> X = np.arange(6).reshape(3, 2)
>>> X
array([[0, 1],
       [2, 3],
       [4, 5]])
>>> poly = PolynomialFeatures(2)
>>> poly.fit_transform(X)
array([[ 1.,  0.,  1.,  0.,  0.,  1.],
       [ 1.,  2.,  3.,  4.,  6.,  9.],
       [ 1.,  4.,  5., 16., 20., 25.]])
```

The features of X have been transformed from \((X_1, X_2)\) to \((1, X_1, X_2, X_1^2, X_1X_2, X_2^2)\).

In some cases, only interaction terms among features are required, and it can be gotten with the setting `interaction_only=True`:

```python
>>> X = np.arange(9).reshape(3, 3)
>>> X
array([[0, 1, 2],
       [3, 4, 5],
       [6, 7, 8]])
>>> poly = PolynomialFeatures(degree=3, interaction_only=True)
>>> poly.fit_transform(X)
array([[ 1.,  0.,  1.,  2.,  0.,  0.,  2.,  0.],
       [ 1.,  3.,  4.,  5., 12., 15., 20., 60.],
       [ 1.,  6.,  7.,  8., 42., 48., 56., 336.]])
```

The features of X have been transformed from \((X_1, X_2, X_3)\) to \((1, X_1, X_2, X_3, X_1X_2, X_1X_3, X_2X_3, X_1X_2X_3)\).

Note that polynomial features are used implicitly in kernel methods (e.g., `SVC`, `KernelPCA`) when using polynomial Kernel functions.

See Polynomial interpolation for Ridge regression using created polynomial features.

Custom transformers

Often, you will want to convert an existing Python function into a transformer to assist in data cleaning or processing. You can implement a transformer from an arbitrary function with `FunctionTransformer`. For example, to build a transformer that applies a log transformation in a pipeline, do:

```python
>>> import numpy as np
>>> from sklearn.preprocessing import FunctionTransformer
>>> transformer = FunctionTransformer(np.log1p, validate=True)
>>> X = np.array([[0, 1], [2, 3]])
```

(continues on next page)
You can ensure that `func` and `inverse_func` are the inverse of each other by setting `check_inverse=True` and calling `fit` before `transform`. Please note that a warning is raised and can be turned into an error with a `filterwarnings`:

```python
>>> import warnings
>>> warnings.filterwarnings("error", message=".*check_inverse*.", category=UserWarning, append=False)
```

For a full code example that demonstrates using a `FunctionTransformer` to extract features from text data see Column Transformer with Heterogeneous Data Sources

### 4.6.4 Imputation of missing values

For various reasons, many real world datasets contain missing values, often encoded as blanks, NaNs or other placeholders. Such datasets however are incompatible with scikit-learn estimators which assume that all values in an array are numerical, and that all have and hold meaning. A basic strategy to use incomplete datasets is to discard entire rows and/or columns containing missing values. However, this comes at the price of losing data which may be valuable (even though incomplete). A better strategy is to impute the missing values, i.e., to infer them from the known part of the data. See the Glossary of Common Terms and API Elements entry on imputation.

**Univariate vs. Multivariate Imputation**

One type of imputation algorithm is univariate, which imputes values in the i-th feature dimension using only non-missing values in that feature dimension (e.g. `impute.SimpleImputer`). By contrast, multivariate imputation algorithms use the entire set of available feature dimensions to estimate the missing values (e.g. `impute.IterativeImputer`).

**Univariate feature imputation**

The `SimpleImputer` class provides basic strategies for imputing missing values. Missing values can be imputed with a provided constant value, or using the statistics (mean, median or most frequent) of each column in which the missing values are located. This class also allows for different missing values encodings.

The following snippet demonstrates how to replace missing values, encoded as `np.nan`, using the mean value of the columns (axis 0) that contain the missing values:

```python
>>> import numpy as np
>>> from sklearn.impute import SimpleImputer
>>> imp = SimpleImputer(missing_values=np.nan, strategy='mean')
>>> imp.fit([[1, 2], [np.nan, 3], [7, 6]])
SimpleImputer()
>>> X = [[np.nan, 2], [6, np.nan], [7, 6]]
>>> print(imp.transform(X))
[[4. 2.]
 [6. 3.666...]
 [7. 6.]]
```

The `SimpleImputer` class also supports sparse matrices:
```python
>>> import scipy.sparse as sp
>>> X = sp.csc_matrix([[1, 2], [0, -1], [8, 4]])
>>> imp = SimpleImputer(missing_values=-1, strategy='mean')
>>> imp.fit(X)
SimpleImputer(missing_values=-1)
>>> X_test = sp.csc_matrix([[-1, 2], [6, -1], [7, 6]])
>>> print(imp.transform(X_test).toarray())
[[3. 2.]
 [6. 3.]
 [7. 6.]]
```
Note that this format is not meant to be used to implicitly store missing values in the matrix because it would densify it at transform time. Missing values encoded by 0 must be used with dense input.

The `SimpleImputer` class also supports categorical data represented as string values or pandas categoricals when using the `most_frequent` or `constant` strategy:

```python
>>> import pandas as pd
>>> df = pd.DataFrame(["a", "x"],
...                   [np.nan, "y"],
...                   ["a", np.nan],
...                   ["b", "y"], dtype="category")
... >>> imp = SimpleImputer(strategy="most_frequent")
>>> print(imp.fit_transform(df))
[['a' 'x']
 ['a' 'y']
 ['a' 'y']
 ['b' 'y']]
```

**Multivariate feature imputation**

A more sophisticated approach is to use the `IterativeImputer` class, which models each feature with missing values as a function of other features, and uses that estimate for imputation. It does so in an iterated round-robin fashion: at each step, a feature column is designated as output $y$ and the other feature columns are treated as inputs $X$. A regressor is fit on $(X, y)$ for known $y$. Then, the regressor is used to predict the missing values of $y$. This is done for each feature in an iterative fashion, and then is repeated for max_iter imputation rounds. The results of the final imputation round are returned.

**Note:** This estimator is still experimental for now: default parameters or details of behaviour might change without any deprecation cycle. Resolving the following issues would help stabilize `IterativeImputer`: convergence criteria (#14338), default estimators (#13286), and use of random state (#15611). To use it, you need to explicitly import `enable_iterative_imputer`.

```python
>>> import numpy as np
>>> from sklearn.experimental import enable_iterative_imputer
>>> from sklearn.impute import IterativeImputer
>>> imp = IterativeImputer(max_iter=10, random_state=0)
>>> imp.fit([[1, 2], [3, 6], [4, 8], [np.nan, 3], [7, np.nan]])
IterativeImputer(random_state=0)
>>> X_test = [[np.nan, 2], [6, np.nan], [np.nan, 6]]
>>> # the model learns that the second feature is double the first
>>> print(np.round(imp.transform(X_test)))
```

(continues on next page)
Both SimpleImputer and IterativeImputer can be used in a Pipeline as a way to build a composite estimator that supports imputation. See *Imputing missing values before building an estimator*.

**Flexibility of IterativeImputer**

There are many well-established imputation packages in the R data science ecosystem: Amelia, mi, mice, missForest, etc. missForest is popular, and turns out to be a particular instance of different sequential imputation algorithms that can all be implemented with IterativeImputer by passing in different regressors to be used for predicting missing feature values. In the case of missForest, this regressor is a Random Forest. See *Imputing missing values with variants of IterativeImputer*.

**Multiple vs. Single Imputation**

In the statistics community, it is common practice to perform multiple imputations, generating, for example, $m$ separate imputations for a single feature matrix. Each of these $m$ imputations is then put through the subsequent analysis pipeline (e.g. feature engineering, clustering, regression, classification). The $m$ final analysis results (e.g. held-out validation errors) allow the data scientist to obtain understanding of how analytic results may differ as a consequence of the inherent uncertainty caused by the missing values. The above practice is called multiple imputation.

Our implementation of IterativeImputer was inspired by the R MICE package (Multivariate Imputation by Chained Equations)\(^1\), but differs from it by returning a single imputation instead of multiple imputations. However, IterativeImputer can also be used for multiple imputations by applying it repeatedly to the same dataset with different random seeds when `sample_posterior=True`. See\(^2\), chapter 4 for more discussion on multiple vs. single imputations.

It is still an open problem as to how useful single vs. multiple imputation is in the context of prediction and classification when the user is not interested in measuring uncertainty due to missing values.

Note that a call to the `transform` method of IterativeImputer is not allowed to change the number of samples. Therefore multiple imputations cannot be achieved by a single call to `transform`.

**References**

**Nearest neighbors imputation**

The KNNImputer class provides imputation for filling in missing values using the k-Nearest Neighbors approach. By default, a euclidean distance metric that supports missing values, `nan_euclidean_distances`, is used to find the nearest neighbors. Each missing feature is imputed using values from $n_{neighbors}$ nearest neighbors that have a value for the feature. The feature of the neighbors are averaged uniformly or weighted by distance to each neighbor.

If a sample has more than one feature missing, then the neighbors for that sample can be different depending on the particular feature being imputed. When the number of available neighbors is less than $n_{neighbors}$ and there are no defined distances to the training set, the training set average for that feature is used during imputation. If there is at least one neighbor with a defined distance, the weighted or unweighted average of the remaining neighbors will be used during imputation. If a feature is always missing in training, it is removed during `transform`. For more information on the methodology, see ref. [OL2001].


The following snippet demonstrates how to replace missing values, encoded as np.nan, using the mean feature value of the two nearest neighbors of samples with missing values:

```python
>>> import numpy as np
>>> from sklearn.impute import KNNImputer
>>> nan = np.nan
>>> X = [[1, 2, nan], [3, 4, 3], [nan, 6, 5], [8, 8, 7]]
>>> imputer = KNNImputer(n_neighbors=2, weights="uniform")
>>> imputer.fit_transform(X)
array([[1., 2., 4.],
[3., 4., 3.],
[5.5, 6., 5.],
[8., 8., 7.]]
```

### Marking imputed values

The `MissingIndicator` transformer is useful to transform a dataset into corresponding binary matrix indicating the presence of missing values in the dataset. This transformation is useful in conjunction with imputation. When using imputation, preserving the information about which values had been missing can be informative. Note that both the `SimpleImputer` and `IterativeImputer` have the boolean parameter `add_indicator` (False by default) which when set to True provides a convenient way of stacking the output of the `MissingIndicator` transformer with the output of the imputer.

`NaN` is usually used as the placeholder for missing values. However, it enforces the data type to be float. The parameter `missing_values` allows to specify other placeholder such as integer. In the following example, we will use `-1` as missing values:

```python
>>> from sklearn.impute import MissingIndicator
>>> X = np.array([[-1, -1, 1, 3],
... [4, -1, 0, -1],
... [8, -1, 1, 0]])
>>> indicator = MissingIndicator(missing_values=-1)
>>> mask_missing_values_only = indicator.fit_transform(X)
>>> mask_missing_values_only
array([[ True,  True, False],
[False,  True,  True],
[False,  True, False]])
```

The `features` parameter is used to choose the features for which the mask is constructed. By default, it is 'missing-only' which returns the imputer mask of the features containing missing values at fit time:

```python
>>> indicator.features_
array([0, 1, 3])
```

The `features` parameter can be set to 'all' to return all features whether or not they contain missing values:

```python
>>> indicator = MissingIndicator(missing_values=-1, features="all")
>>> mask_all = indicator.fit_transform(X)
>>> mask_all
array([[ True,  True, False, False],
[False,  True, False, True],
[False,  True, False, False]])
>>> indicator.features_
array([0, 1, 2, 3])
```

When using the `MissingIndicator` in a Pipeline, be sure to use the `FeatureUnion` or `ColumnTransformer` to add the indicator features to the regular features. First we obtain the iris dataset,
and add some missing values to it.

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.impute import SimpleImputer, MissingIndicator
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.pipeline import FeatureUnion, make_pipeline
>>> from sklearn.tree import DecisionTreeClassifier

>>> X, y = load_iris(return_X_y=True)
>>> mask = np.random.randint(0, 2, size=X.shape).astype(bool)
>>> X[mask] = np.nan
>>> X_train, X_test, y_train, _ = train_test_split(X, y, test_size=100,
... random_state=0)

Now we create a FeatureUnion. All features will be imputed using SimpleImputer, in order to enable classifiers to work with this data. Additionally, it adds the indicator variables from MissingIndicator.

```python
>>> transformer = FeatureUnion(
...     transformer_list=[
...         ('features', SimpleImputer(strategy='mean')),
...         ('indicators', MissingIndicator())
...     ]
... )
>>> transformer = transformer.fit(X_train, y_train)
>>> results = transformer.transform(X_test)
>>> results.shape
(100, 8)
```

Of course, we cannot use the transformer to make any predictions. We should wrap this in a Pipeline with a classifier (e.g., a DecisionTreeClassifier) to be able to make predictions.

```python
>>> clf = make_pipeline(transformer, DecisionTreeClassifier())
>>> clf = clf.fit(X_train, y_train)
>>> results = clf.predict(X_test)
>>> results.shape
(100,)
```

4.6.5 Unsupervised dimensionality reduction

If your number of features is high, it may be useful to reduce it with an unsupervised step prior to supervised steps. Many of the Unsupervised learning methods implement a transform method that can be used to reduce the dimensionality. Below we discuss two specific example of this pattern that are heavily used.

Pipelining

The unsupervised data reduction and the supervised estimator can be chained in one step. See Pipeline: chaining estimators.
PCA: principal component analysis

decomposition.PCA looks for a combination of features that capture well the variance of the original features. See Decomposing signals in components (matrix factorization problems).

Examples

- Faces recognition example using eigenfaces and SVMs

Random projections

The module: random_projection provides several tools for data reduction by random projections. See the relevant section of the documentation: Random Projection.

Examples

- The Johnson-Lindenstrauss bound for embedding with random projections

Feature agglomeration

cluster.FeatureAgglomeration applies Hierarchical clustering to group together features that behave similarly.

Examples

- Feature agglomeration vs. univariate selection
- Feature agglomeration

Feature scaling

Note that if features have very different scaling or statistical properties, cluster.FeatureAgglomeration may not be able to capture the links between related features. Using a preprocessing.StandardScaler can be useful in these settings.

4.6.6 Random Projection

The sklearn.random_projection module implements a simple and computationally efficient way to reduce the dimensionality of the data by trading a controlled amount of accuracy (as additional variance) for faster processing times and smaller model sizes. This module implements two types of unstructured random matrix: Gaussian random matrix and sparse random matrix.

The dimensions and distribution of random projections matrices are controlled so as to preserve the pairwise distances between any two samples of the dataset. Thus random projection is a suitable approximation technique for distance based method.
The Johnson-Lindenstrauss lemma

The main theoretical result behind the efficiency of random projection is the Johnson-Lindenstrauss lemma (quoting Wikipedia):

In mathematics, the Johnson-Lindenstrauss lemma is a result concerning low-distortion embeddings of points from high-dimensional into low-dimensional Euclidean space. The lemma states that a small set of points in a high-dimensional space can be embedded into a space of much lower dimension in such a way that distances between the points are nearly preserved. The map used for the embedding is at least Lipschitz, and can even be taken to be an orthogonal projection.

Knowing only the number of samples, the `johnson_lindenstrauss_min_dim` estimates conservatively the minimal size of the random subspace to guarantee a bounded distortion introduced by the random projection:

```python
>>> from sklearn.random_projection import johnson_lindenstrauss_min_dim
>>> johnson_lindenstrauss_min_dim(n_samples=1e6, eps=0.5)
663
>>> johnson_lindenstrauss_min_dim(n_samples=1e6, eps=[0.5, 0.1, 0.01])
array([ 663, 11841, 1112658])
>>> johnson_lindenstrauss_min_dim(n_samples=[1e4, 1e5, 1e6], eps=0.1)
array([ 7894, 9868, 11841])
```

![Johnson-Lindenstrauss bounds: n_samples vs n_components](image)
Example:

- See *The Johnson-Lindenstrauss bound for embedding with random projections* for a theoretical explication on the Johnson-Lindenstrauss lemma and an empirical validation using sparse random matrices.

References:


**Gaussian random projection**

The *GaussianRandomProjection* reduces the dimensionality by projecting the original input space on a randomly generated matrix where components are drawn from the following distribution $N(0, \frac{1}{\text{n_components}})$.

Here a small excerpt which illustrates how to use the Gaussian random projection transformer:

```
>>> import numpy as np
>>> from sklearn import random_projection
>>> X = np.random.rand(100, 10000)
>>> transformer = random_projection.GaussianRandomProjection()
>>> X_new = transformer.fit_transform(X)
>>> X_new.shape
(100, 3947)
```
Sparse random projection

The `SparseRandomProjection` reduces the dimensionality by projecting the original input space using a sparse random matrix.

Sparse random matrices are an alternative to dense Gaussian random projection matrix that guarantees similar embedding quality while being much more memory efficient and allowing faster computation of the projected data.

If we define $s = 1 / \text{density}$, the elements of the random matrix are drawn from

\[
\begin{align*}
&\begin{cases}
-\sqrt{\frac{s}{n_{\text{components}}}} & \text{with probability } \frac{1}{2} - \frac{1}{s} \\
0 & \text{with probability } 1 - \frac{1}{s} \\
\sqrt{\frac{s}{n_{\text{components}}}} & \text{with probability } \frac{1}{2} 
\end{cases}
\end{align*}
\]

where $n_{\text{components}}$ is the size of the projected subspace. By default the density of non zero elements is set to the minimum density as recommended by Ping Li et al.: $1/\sqrt{n_{\text{features}}}$.

Here a small excerpt which illustrates how to use the sparse random projection transformer:

```python
>>> import numpy as np
>>> from sklearn import random_projection
>>> X = np.random.rand(100, 10000)
>>> transformer = random_projection.SparseRandomProjection()
>>> X_new = transformer.fit_transform(X)
>>> X_new.shape
(100, 3947)
```

References:


4.6.7 Kernel Approximation

This submodule contains functions that approximate the feature mappings that correspond to certain kernels, as they are used for example in support vector machines (see Support Vector Machines). The following feature functions perform non-linear transformations of the input, which can serve as a basis for linear classification or other algorithms.

The advantage of using approximate explicit feature maps compared to the kernel trick, which makes use of feature maps implicitly, is that explicit mappings can be better suited for online learning and can significantly reduce the cost of learning with very large datasets. Standard kernelized SVMs do not scale well to large datasets, but using an approximate kernel map it is possible to use much more efficient linear SVMs. In particular, the combination of kernel map approximations with `SGDClassifier` can make non-linear learning on large datasets possible.

Since there has not been much empirical work using approximate embeddings, it is advisable to compare results against exact kernel methods when possible.

See also:

*Polynomial regression: extending linear models with basis functions* for an exact polynomial transformation.
Nystroem Method for Kernel Approximation

The Nystroem method, as implemented in Nystroem is a general method for low-rank approximations of kernels. It achieves this by essentially subsampling the data on which the kernel is evaluated. By default Nystroem uses the rbf kernel, but it can use any kernel function or a precomputed kernel matrix. The number of samples used - which is also the dimensionality of the features computed - is given by the parameter n_components.

Radial Basis Function Kernel

The RBFSampler constructs an approximate mapping for the radial basis function kernel, also known as Random Kitchen Sinks [RR2007]. This transformation can be used to explicitly model a kernel map, prior to applying a linear algorithm, for example a linear SVM:

```python
from sklearn.kernel_approximation import RBFSampler
from sklearn.linear_model import SGDClassifier
X = [[0, 0], [1, 1], [1, 0], [0, 1]]
y = [0, 0, 1, 1]
rbf_feature = RBFSampler(gamma=1, random_state=1)
X_features = rbf_feature.fit_transform(X)
clf = SGDClassifier(max_iter=5)
clf.fit(X_features, y)
clf.score(X_features, y)
```

The mapping relies on a Monte Carlo approximation to the kernel values. The fit function performs the Monte Carlo sampling, whereas the transform method performs the mapping of the data. Because of the inherent randomness of the process, results may vary between different calls to the fit function.

The fit function takes two arguments: n_components, which is the target dimensionality of the feature transform, and gamma, the parameter of the RBF-kernel. A higher n_components will result in a better approximation of the kernel and will yield results more similar to those produced by a kernel SVM. Note that “fitting” the feature function does not actually depend on the data given to the fit function. Only the dimensionality of the data is used. Details on the method can be found in [RR2007].

For a given value of n_components RBFSampler is often less accurate as Nystroem. RBFSampler is cheaper to compute, though, making use of larger feature spaces more efficient.

Examples:

- Explicit feature map approximation for RBF kernels

Additive Chi Squared Kernel

The additive chi squared kernel is a kernel on histograms, often used in computer vision.

The additive chi squared kernel as used here is given by

\[ k(x, y) = \sum_i \frac{2x_i y_i}{x_i + y_i} \]

This is not exactly the same as sklearn.metrics.additive_chi2_kernel. The authors of [VZ2010] prefer the version above as it is always positive definite. Since the kernel is additive, it is possible to treat all components
Fig. 10: Comparing an exact RBF kernel (left) with the approximation (right)

\( x_i \) separately for embedding. This makes it possible to sample the Fourier transform in regular intervals, instead of approximating using Monte Carlo sampling.

The class `AdditiveChi2Sampler` implements this component wise deterministic sampling. Each component is sampled \( n \) times, yielding \( 2n + 1 \) dimensions per input dimension (the multiple of two stems from the real and complex part of the Fourier transform). In the literature, \( n \) is usually chosen to be 1 or 2, transforming the dataset to size \( n_{\text{samples}} \times 5 \times n_{\text{features}} \) (in the case of \( n = 2 \)).

The approximate feature map provided by `AdditiveChi2Sampler` can be combined with the approximate feature map provided by `RBFSampler` to yield an approximate feature map for the exponentiated chi squared kernel. See the [VZ2010] for details and [VVZ2010] for combination with the `RBFSampler`.

**Skewed Chi Squared Kernel**

The skewed chi squared kernel is given by:

\[
k(x, y) = \prod_i \frac{2\sqrt{x_i + c}\sqrt{y_i + c}}{x_i + y_i + 2c}
\]

It has properties that are similar to the exponentiated chi squared kernel often used in computer vision, but allows for a simple Monte Carlo approximation of the feature map.

The usage of the `SkewedChi2Sampler` is the same as the usage described above for the `RBFSampler`. The only difference is in the free parameter, that is called \( c \). For a motivation for this mapping and the mathematical details see [LS2010].
Polynomial Kernel Approximation via Tensor Sketch

The polynomial kernel is a popular type of kernel function given by:

\[ k(x, y) = (\gamma x^\top y + c_0)^d \]

where:

- \( x, y \) are the input vectors
- \( d \) is the kernel degree

Intuitively, the feature space of the polynomial kernel of degree \( d \) consists of all possible degree-\( d \) products among input features, which enables learning algorithms using this kernel to account for interactions between features.

The TensorSketch [PP2013] method, as implemented in \texttt{PolynomialCountSketch}, is a scalable, input data independent method for polynomial kernel approximation. It is based on the concept of Count sketch [WIKICS] [CCF2002], a dimensionality reduction technique similar to feature hashing, which instead uses several independent hash functions. TensorSketch obtains a Count Sketch of the outer product of two vectors (or a vector with itself), which can be used as an approximation of the polynomial kernel feature space. In particular, instead of explicitly computing the outer product, TensorSketch computes the Count Sketch of the vectors and then uses polynomial multiplication via the Fast Fourier Transform to compute the Count Sketch of their outer product.

Conveniently, the training phase of TensorSketch simply consists of initializing some random variables. It is thus independent of the input data, i.e. it only depends on the number of input features, but not the data values. In addition, this method can transform samples in \( O(n_{\text{samples}}(n_{\text{features}} + n_{\text{components}} \log(n_{\text{components}}))) \) time, where \( n_{\text{components}} \) is the desired output dimension, determined by \( n_{\text{components}} \).

Examples:

- Scalable learning with polynomial kernel approximation

Mathematical Details

Kernel methods like support vector machines or kernelized PCA rely on a property of reproducing kernel Hilbert spaces. For any positive definite kernel function \( k \) (a so called Mercer kernel), it is guaranteed that there exists a mapping \( \phi \) into a Hilbert space \( \mathcal{H} \), such that

\[ k(x, y) = \langle \phi(x), \phi(y) \rangle \]

Where \( \langle \cdot, \cdot \rangle \) denotes the inner product in the Hilbert space.

If an algorithm, such as a linear support vector machine or PCA, relies only on the scalar product of data points \( x_i \), one may use the value of \( k(x_i, x_j) \), which corresponds to applying the algorithm to the mapped data points \( \phi(x_i) \). The advantage of using \( k \) is that the mapping \( \phi \) never has to be calculated explicitly, allowing for arbitrary large features (even infinite).

One drawback of kernel methods is, that it might be necessary to store many kernel values \( k(x_i, x_j) \) during optimization. If a kernelized classifier is applied to new data \( y_j \), \( k(x_i, y_j) \) needs to be computed to make predictions, possibly for many different \( x_i \) in the training set.

The classes in this submodule allow to approximate the embedding \( \phi \), thereby working explicitly with the representations \( \phi(x_i) \), which obviates the need to apply the kernel or store training examples.
4.6.8 Pairwise metrics, Affinities and Kernels

The `sklearn.metrics.pairwise` submodule implements utilities to evaluate pairwise distances or affinity of sets of samples.

This module contains both distance metrics and kernels. A brief summary is given on the two here.

Distance metrics are functions $d(a, b)$ such that $d(a, b) < d(a, c)$ if objects $a$ and $b$ are considered “more similar” than objects $a$ and $c$. Two objects exactly alike would have a distance of zero. One of the most popular examples is Euclidean distance. To be a ‘true’ metric, it must obey the following four conditions:

1. $d(a, b) \geq 0$, for all $a$ and $b$
2. $d(a, b) = 0$, if and only if $a = b$, positive definiteness
3. $d(a, b) = d(b, a)$, symmetry
4. $d(a, c) \leq d(a, b) + d(b, c)$, the triangle inequality

Kernels are measures of similarity, i.e. $s(a, b) > s(a, c)$ if objects $a$ and $b$ are considered “more similar” than objects $a$ and $c$. A kernel must also be positive semi-definite.

There are a number of ways to convert between a distance metric and a similarity measure, such as a kernel. Let $D$ be the distance, and $S$ be the kernel:

1. $S = \exp(-D \times \gamma)$, where one heuristic for choosing $\gamma$ is $1 / \text{num\_features}$
2. $S = 1 / (D / \max(D))$

The distances between the row vectors of $X$ and the row vectors of $Y$ can be evaluated using `pairwise_distances`. If $Y$ is omitted the pairwise distances of the row vectors of $X$ are calculated. Similarly, `pairwise.pairwise_kernels` can be used to calculate the kernel between $X$ and $Y$ using different kernel functions. See the API reference for more details.

```python
>>> import numpy as np
>>> from sklearn.metrics import pairwise_distances
>>> from sklearn.metrics.pairwise import pairwise_kernels

>>> X = np.array([[2, 3], [3, 5], [5, 8]])
>>> Y = np.array([[1, 0], [2, 1]])

>>> pairwise_distances(X, metric='manhattan')
array([[ 4.,  2.],
       [11.,  5.],
       [12., 10.]])

>>> pairwise_distances(X, metric='manhattan')
array([[ 4.,  2.],
       [11.,  5.],
       [12., 10.]])

>>> pairwise_kernels(X, Y, metric='linear')
array([[ 2.,  7.],
       [ 3., 11.],
       [ 5., 18.]])
```
Cosine similarity

`cosine_similarity` computes the L2-normalized dot product of vectors. That is, if \( x \) and \( y \) are row vectors, their cosine similarity \( k \) is defined as:

\[
k(x, y) = \frac{xy^\top}{\|x\| \|y\|}
\]

This is called cosine similarity, because Euclidean (L2) normalization projects the vectors onto the unit sphere, and their dot product is then the cosine of the angle between the points denoted by the vectors.

This kernel is a popular choice for computing the similarity of documents represented as tf-idf vectors. `cosine_similarity` accepts scipy.sparse matrices. (Note that the tf-idf functionality in sklearn.feature_extraction.text can produce normalized vectors, in which case `cosine_similarity` is equivalent to `linear_kernel`, only slower.)

References:


Linear kernel

The function `linear_kernel` computes the linear kernel, that is, a special case of `polynomial_kernel` with degree=1 and coef0=0 (homogeneous). If \( x \) and \( y \) are column vectors, their linear kernel is:

\[
k(x, y) = x^\top y
\]

Polynomial kernel

The function `polynomial_kernel` computes the degree-d polynomial kernel between two vectors. The polynomial kernel represents the similarity between two vectors. Conceptually, the polynomial kernels considers not only the similarity between vectors under the same dimension, but also across dimensions. When used in machine learning algorithms, this allows to account for feature interaction.

The polynomial kernel is defined as:

\[
k(x, y) = (\gamma x^\top y + c_0)^d
\]

where:

- \( x, y \) are the input vectors
- \( d \) is the kernel degree

If \( c_0 = 0 \) the kernel is said to be homogeneous.
Sigmoid kernel

The function `sigmoid_kernel` computes the sigmoid kernel between two vectors. The sigmoid kernel is also known as hyperbolic tangent, or Multilayer Perceptron (because, in the neural network field, it is often used as neuron activation function). It is defined as:

\[ k(x, y) = \tanh(\gamma x^T y + c_0) \]

where:
- \( x, y \) are the input vectors
- \( \gamma \) is known as slope
- \( c_0 \) is known as intercept

RBF kernel

The function `rbf_kernel` computes the radial basis function (RBF) kernel between two vectors. This kernel is defined as:

\[ k(x, y) = \exp(-\gamma \|x - y\|^2) \]

where \( x \) and \( y \) are the input vectors. If \( \gamma = \sigma^{-2} \) the kernel is known as the Gaussian kernel of variance \( \sigma^2 \).

Laplacian kernel

The function `laplacian_kernel` is a variant on the radial basis function kernel defined as:

\[ k(x, y) = \exp(-\gamma \|x - y\|_1) \]

where \( x \) and \( y \) are the input vectors and \( \|x - y\|_1 \) is the Manhattan distance between the input vectors.

It has proven useful in ML applied to noiseless data. See e.g. Machine learning for quantum mechanics in a nutshell.

Chi-squared kernel

The chi-squared kernel is a very popular choice for training non-linear SVMs in computer vision applications. It can be computed using `chi2_kernel` and then passed to an `SVC` with `kernel="precomputed"`:

```python
>>> from sklearn.svm import SVC
>>> from sklearn.metrics.pairwise import chi2_kernel
>>> X = [[0, 1], [1, 0], [.2, .8], [.7, .3]]
>>> y = [0, 1, 0, 1]
>>> K = chi2_kernel(X, gamma=.5)
>>> K
array([[1. , 0.36787944, 0.89483932, 0.58364548],
       [0.36787944, 1. , 0.51341712, 0.83822343],
       [0.89483932, 0.51341712, 1. , 0.7768366 ],
       [0.58364548, 0.83822343, 0.7768366 , 1. ]])
>>> svm = SVC(kernel='precomputed').fit(K, y)
>>> svm.predict(K)
array([0, 1, 0, 1])
```

It can also be directly used as the `kernel` argument:
The chi squared kernel is given by

\[
k(x, y) = \exp \left(-\gamma \sum_i \frac{(x[i] - y[i])^2}{x[i] + y[i]}\right)
\]

The data is assumed to be non-negative, and is often normalized to have an L1-norm of one. The normalization is rationalized with the connection to the chi squared distance, which is a distance between discrete probability distributions.

The chi squared kernel is most commonly used on histograms (bags) of visual words.

References:


### 4.6.9 Transforming the prediction target ()

These are transformers that are not intended to be used on features, only on supervised learning targets. See also Transforming target in regression if you want to transform the prediction target for learning, but evaluate the model in the original (untransformed) space.

**Label binarization**

**LabelBinarizer** is a utility class to help create a label indicator matrix from a list of multiclass labels:

```python
>>> from sklearn import preprocessing
>>> lb = preprocessing.LabelBinarizer()
>>> lb.fit([1, 2, 6, 4, 2])
LabelBinarizer()
>>> lb.classes_
array([1, 2, 4, 6])
>>> lb.transform([1, 6])
array([[1, 0, 0, 0],
       [0, 0, 0, 1]])
```

Using this format can enable multiclass classification in estimators that support the label indicator matrix format.

**Warning:** LabelBinarizer is not needed if you are using an estimator that already supports multiclass data.

For more information about multiclass classification, refer to Multiclass classification.
**MultiLabelBinarizer**

In *multilabel* learning, the joint set of binary classification tasks is expressed with a label binary indicator array: each sample is one row of a 2d array of shape (n_samples, n_classes) with binary values where the one, i.e. the non zero elements, corresponds to the subset of labels for that sample. An array such as `np.array([[1, 0, 0], [0, 1, 1], [0, 0, 0]])` represents label 0 in the first sample, labels 1 and 2 in the second sample, and no labels in the third sample.

Producing multilabel data as a list of sets of labels may be more intuitive. The `MultiLabelBinarizer` transformer can be used to convert between a collection of collections of labels and the indicator format:

```python
>>> from sklearn.preprocessing import MultiLabelBinarizer
>>> y = [[2, 3, 4], [2], [0, 1, 3], [0, 1, 2, 3, 4], [0, 1, 2]]
>>> MultiLabelBinarizer().fit_transform(y)
array([[0, 0, 1, 1, 1],
       [0, 0, 1, 0, 0],
       [1, 1, 0, 1, 0],
       [1, 1, 1, 1, 1],
       [1, 1, 1, 0, 0]])
```

For more information about multilabel classification, refer to *Multilabel classification*.

**Label encoding**

`LabelEncoder` is a utility class to help normalize labels such that they contain only values between 0 and n_classes-1. This is sometimes useful for writing efficient Cython routines. `LabelEncoder` can be used as follows:

```python
>>> from sklearn import preprocessing
>>> le = preprocessing.LabelEncoder()
>>> le.fit([1, 2, 2, 6])
LabelEncoder()
>>> list(le.classes_)
['1', '2', '6']
>>> le.transform([1, 1, 2, 6])
array([0, 0, 1, 2])
>>> list(le.inverse_transform([0, 0, 1, 2]))
['1', '1', '2', '6']
```

It can also be used to transform non-numerical labels (as long as they are hashable and comparable) to numerical labels:

```python
>>> le = preprocessing.LabelEncoder()
>>> le.fit(['paris', 'paris', 'tokyo', 'amsterdam'])
LabelEncoder()
>>> list(le.classes_)
['amsterdam', 'paris', 'tokyo']
>>> le.transform(['tokyo', 'tokyo', 'paris'])
array([2, 2, 1])
>>> list(le.inverse_transform([2, 2, 1]))
['tokyo', 'tokyo', 'paris']
```
4.7 Dataset loading utilities

The `sklearn.datasets` package embeds some small toy datasets as introduced in the *Getting Started* section. This package also features helpers to fetch larger datasets commonly used by the machine learning community to benchmark algorithms on data that comes from the ‘real world’.

To evaluate the impact of the scale of the dataset (n_samples and n_features) while controlling the statistical properties of the data (typically the correlation and informativeness of the features), it is also possible to generate synthetic data.

**General dataset API.** There are three main kinds of dataset interfaces that can be used to get datasets depending on the desired type of dataset.

**The dataset loaders.** They can be used to load small standard datasets, described in the *Toy datasets* section.

**The dataset fetchers.** They can be used to download and load larger datasets, described in the *Real world datasets* section.

Both loaders and fetchers functions return a *Bunch* object holding at least two items: an array of shape n_samples * n_features with key `data` (except for 20newsgroups) and a numpy array of length n_samples, containing the target values, with key `target`.

The Bunch object is a dictionary that exposes its keys are attributes. For more information about Bunch object, see *Bunch*:

It’s also possible for almost all of these function to constrain the output to be a tuple containing only the data and the target, by setting the `return_X_y` parameter to True.

The datasets also contain a full description in their `DESCR` attribute and some contain `feature_names` and `target_names`. See the dataset descriptions below for details.

**The dataset generation functions.** They can be used to generate controlled synthetic datasets, described in the *Generated datasets* section.

These functions return a tuple (X, y) consisting of a n_samples * n_features numpy array X and an array of length n_samples containing the targets y.

In addition, there are also miscellaneous tools to load datasets of other formats or from other locations, described in the *Loading other datasets* section.

### 4.7.1 Toy datasets

scikit-learn comes with a few small standard datasets that do not require to download any file from some external website.

They can be loaded using the following functions:

- `load_boston(*[, return_X_y])`: Load and return the boston house-prices dataset (regression).
- `load_iris(*[, return_X_y, as_frame])`: Load and return the iris dataset (classification).
- `load_diabetes(*[, return_X_y, as_frame])`: Load and return the diabetes dataset (regression).
- `load_digits(*[, n_class, return_X_y, as_frame])`: Load and return the digits dataset (classification).
- `load_linnerud(*[, return_X_y, as_frame])`: Load and return the physical excercise linnerud dataset.
- `load_wine(*[, return_X_y, as_frame])`: Load and return the wine dataset (classification).
- `load_breast_cancer(*[, return_X_y, as_frame])`: Load and return the breast cancer wisconsin dataset (classification).
These datasets are useful to quickly illustrate the behavior of the various algorithms implemented in scikit-learn. They are however often too small to be representative of real world machine learning tasks.

**Boston house prices dataset**

**Data Set Characteristics:**

- **Number of Instances** 506
- **Number of Attributes** 13 numeric/categorical predictive. Median Value (attribute 14) is usually the target.

**Attribute Information (in order)**

- CRIM per capita crime rate by town
- ZN proportion of residential land zoned for lots over 25,000 sq.ft.
- INDUS proportion of non-retail business acres per town
- CHAS Charles River dummy variable (= 1 if tract bounds river; 0 otherwise)
- NOX nitric oxides concentration (parts per 10 million)
- RM average number of rooms per dwelling
- AGE proportion of owner-occupied units built prior to 1940
- DIS weighted distances to five Boston employment centres
- RAD index of accessibility to radial highways
- TAX full-value property-tax rate per $10,000
- PTRATIO pupil-teacher ratio by town
- B 1000(Bk - 0.63)^2 where Bk is the proportion of blacks by town
- LSTAT % lower status of the population
- MEDV Median value of owner-occupied homes in $1000’s

**Missing Attribute Values** None

**Creator** Harrison, D. and Rubinfeld, D.L.

This is a copy of UCI ML housing dataset. [https://archive.ics.uci.edu/ml/machine-learning-databases/housing/](https://archive.ics.uci.edu/ml/machine-learning-databases/housing/)

This dataset was taken from the StatLib library which is maintained at Carnegie Mellon University.


The Boston house-price data has been used in many machine learning papers that address regression problems.

**References**

Iris plants dataset

Data Set Characteristics:

Number of Instances  150 (50 in each of three classes)

Number of Attributes  4 numeric, predictive attributes and the class

Attribute Information

• sepal length in cm
• sepal width in cm
• petal length in cm
• petal width in cm
• class:
  – Iris-Setosa
  – Iris-Versicolour
  – Iris-Virginica

Summary Statistics

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<td>0.43</td>
</tr>
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<td>3.76</td>
<td>1.76</td>
</tr>
<tr>
<td>petal width</td>
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<td>2.5</td>
<td>1.20</td>
<td>0.76</td>
</tr>
</tbody>
</table>

Missing Attribute Values  None

Class Distribution  33.3% for each of 3 classes.

Creator  R.A. Fisher

Donor  Michael Marshall (MARSHALL%PLU@io.arc.nasa.gov)

Date  July, 1988

The famous Iris database, first used by Sir R.A. Fisher. The dataset is taken from Fisher’s paper. Note that it’s the same as in R, but not as in the UCI Machine Learning Repository, which has two wrong data points.

This is perhaps the best known database to be found in the pattern recognition literature. Fisher’s paper is a classic in the field and is referenced frequently to this day. (See Duda & Hart, for example.) The data set contains 3 classes of 50 instances each, where each class refers to a type of iris plant. One class is linearly separable from the other 2; the latter are NOT linearly separable from each other.

References


Diabetes dataset

Ten baseline variables, age, sex, body mass index, average blood pressure, and six blood serum measurements were obtained for each of n = 442 diabetes patients, as well as the response of interest, a quantitative measure of disease progression one year after baseline.

Data Set Characteristics:

- Number of Instances 442
- Number of Attributes First 10 columns are numeric predictive values
- Target Column 11 is a quantitative measure of disease progression one year after baseline

Attribute Information

- age age in years
- sex
- bmi body mass index
- bp average blood pressure
- s1 tc, T-Cells (a type of white blood cells)
- s2 ldl, low-density lipoproteins
- s3 hdl, high-density lipoproteins
- s4 tch, thyroid stimulating hormone
- s5 ltg, lamotrigine
- s6 glu, blood sugar level

Note: Each of these 10 feature variables have been mean centered and scaled by the standard deviation times n_samples (i.e. the sum of squares of each column totals 1).

Source URL: https://www4.stat.ncsu.edu/~boos/var.select/diabetes.html

Optical recognition of handwritten digits dataset

Data Set Characteristics:

Number of Instances 1797
Number of Attributes 64
Attribute Information 8x8 image of integer pixels in the range 0..16.
Missing Attribute Values None
Creator E. Alpaydin (alpaydin '@' boun.edu.tr)
Date July; 1998

This is a copy of the test set of the UCI ML hand-written digits datasets https://archive.ics.uci.edu/ml/datasets/Optical+Recognition+of+Handwritten+Digits

The data set contains images of hand-written digits: 10 classes where each class refers to a digit.

Preprocessing programs made available by NIST were used to extract normalized bitmaps of handwritten digits from a preprinted form. From a total of 43 people, 30 contributed to the training set and different 13 to the test set. 32x32 bitmaps are divided into nonoverlapping blocks of 4x4 and the number of on pixels are counted in each block. This generates an input matrix of 8x8 where each element is an integer in the range 0..16. This reduces dimensionality and gives invariance to small distortions.


References


Linnerud dataset

Data Set Characteristics:

Number of Instances 20
Number of Attributes 3
Missing Attribute Values None

The Linnerud dataset is a multi-output regression dataset. It consists of three excercise (data) and three physiological (target) variables collected from twenty middle-aged men in a fitness club:

- physiological - CSV containing 20 observations on 3 physiological variables: Weight, Waist and Pulse.
- exercise - CSV containing 20 observations on 3 exercise variables: Chins, Situps and Jumps.
References


Wine recognition dataset

Data Set Characteristics:

- **Number of Instances** 178 (50 in each of three classes)
- **Number of Attributes** 13 numeric, predictive attributes and the class

Attribute Information

- Alcohol
- Malic acid
- Ash
- Alcalinity of ash
- Magnesium
- Total phenols
- Flavanoids
- Nonflavanoid phenols
- Proanthocyanins
- Color intensity
- Hue
- OD280/OD315 of diluted wines
- Proline

- **class:**
  - class_0
  - class_1
  - class_2

Summary Statistics
Alcohol: 11.0 14.8 13.0 0.8
Malic Acid: 0.74 5.80 2.34 1.12
Ash: 1.36 3.23 2.36 0.27
Alcalinity of Ash: 10.6 30.0 19.5 3.3
Magnesium: 70.0 162.0 99.7 14.3
Total Phenols: 0.98 3.88 2.29 0.63
Flavanoids: 0.34 5.08 2.03 1.00
Nonflavanoid Phenols: 0.13 0.66 0.36 0.12
Proanthocyanins: 0.41 3.58 1.59 0.57
Colour Intensity: 1.3 13.0 5.1 2.3
Hue: 0.48 1.71 0.96 0.23
OD280/OD315 of diluted wines: 1.27 4.00 2.61 0.71
Proline: 278 1680 746 315

Missing Attribute Values  None

Class Distribution  class_0 (59), class_1 (71), class_2 (48)

Creator  R.A. Fisher

Donor  Michael Marshall (MARSHALL%PLU@io.arc.nasa.gov)

Date  July, 1988

This is a copy of UCI ML Wine recognition datasets. https://archive.ics.uci.edu/ml/machine-learning-databases/wine/wine.data

The data is the results of a chemical analysis of wines grown in the same region in Italy by three different cultivators. There are thirteen different measurements taken for different constituents found in the three types of wine.

Original Owners:


Citation:


References

(1) S. Aeberhard, D. Coomans and O. de Vel, Comparison of Classifiers in High Dimensional Settings, Tech. Rep. no. 92-02, (1992), Dept. of Computer Science and Dept. of Mathematics and Statistics, James Cook University of North Queensland. (Also submitted to Technometrics).

The data was used with many others for comparing various classifiers. The classes are separable, though only RDA has achieved 100% correct classification. (RDA : 100%, QDA 99.4%, LDA 98.9%, 1NN 96.1% (z-transformed data)) (All results using the leave-one-out technique)

Breast cancer wisconsin (diagnostic) dataset

Data Set Characteristics:

Number of Instances 569

Number of Attributes 30 numeric, predictive attributes and the class

Attribute Information

- radius (mean of distances from center to points on the perimeter)
- texture (standard deviation of gray-scale values)
- perimeter
- area
- smoothness (local variation in radius lengths)
- compactness (perimeter^2 / area - 1.0)
- concavity (severity of concave portions of the contour)
- concave points (number of concave portions of the contour)
- symmetry
- fractal dimension (“coastline approximation” - 1)

The mean, standard error, and “worst” or largest (mean of the three worst/largest values) of these features were computed for each image, resulting in 30 features. For instance, field 0 is Mean Radius, field 10 is Radius SE, field 20 is Worst Radius.

- class:
  - WDBC-Malignant
  - WDBC-Benign

Summary Statistics

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Mean (std error)</th>
<th>Mean (std error)</th>
</tr>
</thead>
<tbody>
<tr>
<td>radius (mean):</td>
<td>6.981 (0.112)</td>
<td>28.11 (2.873)</td>
</tr>
<tr>
<td>texture (mean):</td>
<td>9.71 (0.36)</td>
<td>39.28 (4.885)</td>
</tr>
<tr>
<td>perimeter (mean):</td>
<td>43.79 (0.757)</td>
<td>188.5 (21.98)</td>
</tr>
<tr>
<td>area (mean):</td>
<td>143.5 (6.802)</td>
<td>2501.0 (542.2)</td>
</tr>
<tr>
<td>smoothness (mean):</td>
<td>0.053 (0.002)</td>
<td>0.163 (0.031)</td>
</tr>
<tr>
<td>compactness (mean):</td>
<td>0.019 (0.002)</td>
<td>0.345 (0.135)</td>
</tr>
<tr>
<td>concavity (mean):</td>
<td>0.0 (0.0)</td>
<td>0.427 (0.396)</td>
</tr>
<tr>
<td>concave points (mean):</td>
<td>0.0 (0.0)</td>
<td>0.201 (0.053)</td>
</tr>
<tr>
<td>symmetry (mean):</td>
<td>0.106 (0.05)</td>
<td>0.304 (0.097)</td>
</tr>
<tr>
<td>fractal dimension (mean):</td>
<td>0.05 (0.112)</td>
<td>0.097 (2.873)</td>
</tr>
<tr>
<td>radius (standard error):</td>
<td>0.112 (0.36)</td>
<td>2.873 (4.885)</td>
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<tr>
<td>texture (standard error):</td>
<td>0.36 (0.757)</td>
<td>4.885 (21.98)</td>
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<td>0.757 (6.802)</td>
<td>21.98 (542.2)</td>
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<td>area (standard error):</td>
<td>6.802 (0.002)</td>
<td>542.2 (0.053)</td>
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<td>smoothness (standard error):</td>
<td>0.002 (0.002)</td>
<td>0.031 (0.135)</td>
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<tr>
<td>compactness (standard error):</td>
<td>0.002 (0.002)</td>
<td>0.135 (0.396)</td>
</tr>
<tr>
<td>concavity (standard error):</td>
<td>0.0 (0.0)</td>
<td>0.396 (0.053)</td>
</tr>
</tbody>
</table>

continues on next page
<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>symmetry (standard error):</td>
<td>0.008</td>
<td>0.079</td>
</tr>
<tr>
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<td>0.03</td>
</tr>
<tr>
<td>radius (worst):</td>
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<td>36.04</td>
</tr>
<tr>
<td>texture (worst):</td>
<td>12.02</td>
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</tr>
<tr>
<td>perimeter (worst):</td>
<td>50.41</td>
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</tr>
<tr>
<td>area (worst):</td>
<td>185.2</td>
<td>4254.0</td>
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<tr>
<td>smoothness (worst):</td>
<td>0.071</td>
<td>0.223</td>
</tr>
<tr>
<td>compactness (worst):</td>
<td>0.027</td>
<td>1.058</td>
</tr>
<tr>
<td>concavity (worst):</td>
<td>0.0</td>
<td>1.252</td>
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<tr>
<td>concave points (worst):</td>
<td>0.0</td>
<td>0.291</td>
</tr>
<tr>
<td>symmetry (worst):</td>
<td>0.156</td>
<td>0.664</td>
</tr>
<tr>
<td>fractal dimension (worst):</td>
<td>0.055</td>
<td>0.208</td>
</tr>
</tbody>
</table>

**Missing Attribute Values**  None

**Class Distribution**  212 - Malignant, 357 - Benign

**Creator**  Dr. William H. Wolberg, W. Nick Street, Olvi L. Mangasarian

**Donor**  Nick Street

**Date**  November, 1995

This is a copy of UCI ML Breast Cancer Wisconsin (Diagnostic) datasets. [https://goo.gl/U2Uwz2](https://goo.gl/U2Uwz2)

Features are computed from a digitized image of a fine needle aspirate (FNA) of a breast mass. They describe characteristics of the cell nuclei present in the image.

Separating plane described above was obtained using Multisurface Method-Tree (MSM-T) [K. P. Bennett, “Decision Tree Construction Via Linear Programming.” Proceedings of the 4th Midwest Artificial Intelligence and Cognitive Science Society, pp. 97-101, 1992], a classification method which uses linear programming to construct a decision tree. Relevant features were selected using an exhaustive search in the space of 1-4 features and 1-3 separating planes.

The actual linear program used to obtain the separating plane in the 3-dimensional space is that described in: [K. P. Bennett and O. L. Mangasarian: “Robust Linear Programming Discrimination of Two Linearly Inseparable Sets”, Optimization Methods and Software 1, 1992, 23-34].

This database is also available through the UW CS ftp server:


**References**

4.7.2 Real world datasets

scikit-learn provides tools to load larger datasets, downloading them if necessary.

They can be loaded using the following functions:

- `fetch_olivetti_faces(*[, data_home, ...])`: Load the Olivetti faces data-set from AT&T (classification).
- `fetch_20newsgroups(*[, data_home, subset, ...])`: Load the filenames and data from the 20 newsgroups dataset (classification).
- `fetch_20newsgroups_vectorized(*[, subset, ...])`: Load and vectorize the 20 newsgroups dataset (classification).
- `fetch_lfw_people(*[, data_home, funneled, ...])`: Load the Labeled Faces in the Wild (LFW) people dataset (classification).
- `fetch_lfw_pairs(*[, subset, data_home, ...])`: Load the Labeled Faces in the Wild (LFW) pairs dataset (classification).
- `fetch_covtype(*[, data_home, ...])`: Load the covertype dataset (classification).
- `fetch_rcv1(*[, data_home, subset, ...])`: Load the RCV1 multilabel dataset (classification).
- `fetch_kddcup99(*[, subset, data_home, ...])`: Load the kddcup99 dataset (classification).
- `fetch_california_housing(*[, data_home, ...])`: Load the California housing dataset (regression).

**The Olivetti faces dataset**

This dataset contains a set of face images taken between April 1992 and April 1994 at AT&T Laboratories Cambridge. The `sklearn.datasets.fetch_olivetti_faces` function is the data fetching / caching function that downloads the data archive from AT&T.

As described on the original website:

There are ten different images of each of 40 distinct subjects. For some subjects, the images were taken at different times, varying the lighting, facial expressions (open / closed eyes, smiling / not smiling) and facial details (glasses / no glasses). All the images were taken against a dark homogeneous background with the subjects in an upright, frontal position (with tolerance for some side movement).

**Data Set Characteristics:**

<table>
<thead>
<tr>
<th>Classes</th>
<th>40</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>400</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>4096</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 1</td>
</tr>
</tbody>
</table>

The image is quantized to 256 grey levels and stored as unsigned 8-bit integers; the loader will convert these to floating point values on the interval [0, 1], which are easier to work with for many algorithms.

The “target” for this database is an integer from 0 to 39 indicating the identity of the person pictured; however, with only 10 examples per class, this relatively small dataset is more interesting from an unsupervised or semi-supervised perspective.

The original dataset consisted of 92 x 112, while the version available here consists of 64x64 images.

When using these images, please give credit to AT&T Laboratories Cambridge.
The 20 newsgroups text dataset

The 20 newsgroups dataset comprises around 18000 newsgroups posts on 20 topics split in two subsets: one for training (or development) and the other one for testing (or for performance evaluation). The split between the train and test set is based upon messages posted before and after a specific date.

This module contains two loaders. The first one, `sklearn.datasets.fetch_20newsgroups`, returns a list of the raw texts that can be fed to text feature extractors such as `CountVectorizer` with custom parameters so as to extract feature vectors. The second one, `sklearn.datasets.fetch_20newsgroups_vectorized`, returns ready-to-use features, i.e., it is not necessary to use a feature extractor.

**Data Set Characteristics:**

<table>
<thead>
<tr>
<th>Classes</th>
<th>20</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>18846</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>1</td>
</tr>
<tr>
<td>Features</td>
<td>text</td>
</tr>
</tbody>
</table>

**Usage**

The `sklearn.datasets.fetch_20newsgroups` function is a data fetching / caching functions that downloads the data archive from the original 20 newsgroups website, extracts the archive contents in the `~/scikit_learn_data/20news_home` folder and calls the `sklearn.datasets.load_files` on either the training or testing set folder, or both of them:

```python
>>> from sklearn.datasets import fetch_20newsgroups
>>> newsgroups_train = fetch_20newsgroups(subset='train')
```

```python
>>> from pprint import pprint
>>> pprint(list(newsgroups_train.target_names))
['alt.atheism',
 'comp.graphics',
 'comp.os.ms-windows.misc',
 'comp.sys.ibm.pc.hardware',
 'comp.sys.mac.hardware',
 'comp.windows.x',
 'misc.forsale',
 'rec.autos',
 'rec.motorcycles',
 'rec.sport.baseball',
 'rec.sport.hockey',
 'sci.crypt',
 'sci.electronics',
 'sci.med',
 'sci.space',
 'soc.religion.christian',
 'talk.politics.guns',
 'talk.politics.mideast',
 'talk.politics.misc',
 'talk.religion.misc']
```

The real data lies in the `filenames` and `target` attributes. The target attribute is the integer index of the category:

```python
>>> newsgroups_train.filenames.shape
(11314,)
```

(continues on next page)
It is possible to load only a sub-selection of the categories by passing the list of the categories to load to the `sklearn.datasets.fetch_20newsgroups` function:

```python
>>> cats = ['alt.atheism', 'sci.space']
>>> newsgroups_train = fetch_20newsgroups(subset='train', categories=cats)

>>> list(newsgroups_train.target_names)
['alt.atheism', 'sci.space']
>>> newsgroups_train.filenames.shape
(1073,)
>>> newsgroups_train.target.shape
(1073,)
>>> newsgroups_train.target[:10]
array([0, 1, 1, 1, 0, 1, 1, 0, 0, 0])
```

### Converting text to vectors

In order to feed predictive or clustering models with the text data, one first need to turn the text into vectors of numerical values suitable for statistical analysis. This can be achieved with the utilities of the `sklearn.feature_extraction.text` as demonstrated in the following example that extract TF-IDF vectors of unigram tokens from a subset of 20news:

```python
>>> from sklearn.feature_extraction.text import TfidfVectorizer
>>> categories = ['alt.atheism', 'talk.religion.misc', ...
...   'comp.graphics', 'sci.space']
>>> newsgroups_train = fetch_20newsgroups(subset='train', ...
...   categories=categories)
>>> vectorizer = TfidfVectorizer()
>>> vectors = vectorizer.fit_transform(newsgroups_train.data)
>>> vectors.shape
(2034, 34118)
```

The extracted TF-IDF vectors are very sparse, with an average of 159 non-zero components by sample in a more than 30000-dimensional space (less than .5% non-zero features):

```python
>>> vectors.nnz / float(vectors.shape[0])
159.01327...
```

`sklearn.datasets.fetch_20newsgroups_vectorized` is a function which returns ready-to-use token counts features instead of file names.
Filtering text for more realistic training

It is easy for a classifier to overfit on particular things that appear in the 20 Newsgroups data, such as newsgroup headers. Many classifiers achieve very high F-scores, but their results would not generalize to other documents that aren’t from this window of time.

For example, let’s look at the results of a multinomial Naive Bayes classifier, which is fast to train and achieves a decent F-score:

```python
>>> from sklearn.naive_bayes import MultinomialNB
>>> from sklearn import metrics

>>> newsgroups_test = fetch_20newsgroups(subset='test',
    categories=categories)
>>> vectors_test = vectorizer.transform(newsgroups_test.data)
>>> clf = MultinomialNB(alpha=.01)
>>> clf.fit(vectors, newsgroups_train.target)
MultinomialNB(alpha=0.01, class_prior=None, fit_prior=True)
>>> pred = clf.predict(vectors_test)
>>> metrics.f1_score(newsgroups_test.target, pred, average='macro')
0.88213...
```

(The example *Classification of text documents using sparse features* shuffles the training and test data, instead of segmenting by time, and in that case multinomial Naive Bayes gets a much higher F-score of 0.88. Are you suspicious yet of what’s going on inside this classifier?)

Let’s take a look at what the most informative features are:

```python
>>> import numpy as np
>>> def show_top10(classifier, vectorizer, categories):
...     feature_names = np.asarray(vectorizer.get_feature_names())
...     for i, category in enumerate(categories):
...         top10 = np.argsort(classifier.coef_[i])[-10:]
...         print("%s: %s" % (category, " ".join(feature_names[top10])))

>>> show_top10(clf, vectorizer, newsgroups_train.target_names)
alt.atheism: edu it and in you that is of to the
comp.graphics: edu in graphics it is for and of to the
sci.space: edu it that is in and space to of the
talk.religion.misc: not it you in is that and to of the
```

You can now see many things that these features have overfit to:

- Almost every group is distinguished by whether headers such as NNTP-Posting-Host: and Distribution: appear more or less often.
- Another significant feature involves whether the sender is affiliated with a university, as indicated either by their headers or their signature.
- The word “article” is a significant feature, based on how often people quote previous posts like this: “In article [article ID], [name] <[e-mail address]> wrote:”
- Other features match the names and e-mail addresses of particular people who were posting at the time.

With such an abundance of clues that distinguish newsgroups, the classifiers barely have to identify topics from text at all, and they all perform at the same high level.

For this reason, the functions that load 20 Newsgroups data provide a parameter called `remove`, telling it what kinds of information to strip out of each file. `remove` should be a tuple containing any subset of ('headers', 'footers', 'quotes'), telling it to remove headers, signature blocks, and quotation blocks respectively.
>>> newsgroups_test = fetch_20newsgroups(subset='test',
                      remove=('headers', 'footers', 'quotes'),
                      categories=categories)
>>> vectors_test = vectorizer.transform(newsgroups_test.data)
>>> pred = clf.predict(vectors_test)
>>> metrics.f1_score(pred, newsgroups_test.target, average='macro')
0.77310...

This classifier lost over a lot of its F-score, just because we removed metadata that has little to do with topic classification. It loses even more if we also strip this metadata from the training data:

>>> newsgroups_train = fetch_20newsgroups(subset='train',
                        remove=('headers', 'footers', 'quotes'),
                        categories=categories)
>>> vectors = vectorizer.fit_transform(newsgroups_train.data)
>>> clf = MultinomialNB(alpha=.01)
>>> clf.fit(vectors, newsgroups_train.target)
MultinomialNB(alpha=0.01, class_prior=None, fit_prior=True)

>>> vectors_test = vectorizer.transform(newsgroups_test.data)
>>> pred = clf.predict(vectors_test)
>>> metrics.f1_score(newsgroups_test.target, pred, average='macro')
0.76995...

Some other classifiers cope better with this harder version of the task. Try running Sample pipeline for text feature extraction and evaluation with and without the --filter option to compare the results.

Recommendation

When evaluating text classifiers on the 20 Newsgroups data, you should strip newsgroup-related metadata. In scikit-learn, you can do this by setting remove=('headers', 'footers', 'quotes'). The F-score will be lower because it is more realistic.

Examples

- Sample pipeline for text feature extraction and evaluation
- Classification of text documents using sparse features

The Labeled Faces in the Wild face recognition dataset

This dataset is a collection of JPEG pictures of famous people collected over the internet, all details are available on the official website:

http://vis-www.cs.umass.edu/lfw/

Each picture is centered on a single face. The typical task is called Face Verification: given a pair of two pictures, a binary classifier must predict whether the two images are from the same person.

An alternative task, Face Recognition or Face Identification is: given the picture of the face of an unknown person, identify the name of the person by referring to a gallery of previously seen pictures of identified persons.

Both Face Verification and Face Recognition are tasks that are typically performed on the output of a model trained to perform Face Detection. The most popular model for Face Detection is called Viola-Jones and is implemented in the
OpenCV library. The LFW faces were extracted by this face detector from various online websites.

**Data Set Characteristics:**

<table>
<thead>
<tr>
<th>Classes</th>
<th>5749</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>13233</td>
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<td>Dimensionality</td>
<td>5828</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 255</td>
</tr>
</tbody>
</table>

**Usage**

`scikit-learn` provides two loaders that will automatically download, cache, parse the metadata files, decode the jpeg and convert the interesting slices into memmapped numpy arrays. This dataset size is more than 200 MB. The first load typically takes more than a couple of minutes to fully decode the relevant part of the JPEG files into numpy arrays. If the dataset has been loaded once, the following times the loading times less than 200ms by using a memmapped version memoized on the disk in the `~/scikit_learn_data/lfw_home/` folder using `joblib`.

The first loader is used for the Face Identification task: a multi-class classification task (hence supervised learning):

```python
>>> from sklearn.datasets import fetch_lfw_people
>>> lfw_people = fetch_lfw_people(min_faces_per_person=70, resize=0.4)

>>> for name in lfw_people.target_names:
...     print(name)
... Ariel Sharon
... Colin Powell
... Donald Rumsfeld
... George W Bush
... Gerhard Schroeder
... Hugo Chavez
... Tony Blair
```

The default slice is a rectangular shape around the face, removing most of the background:

```python
>>> lfw_people.data.dtype
dtype('float32')

>>> lfw_people.data.shape
(1288, 1850)

>>> lfw_people.images.shape
(1288, 50, 37)
```

Each of the 1140 faces is assigned to a single person id in the `target` array:

```python
>>> lfw_people.target.shape
(1288,)

>>> list(lfw_people.target[:10])
[5, 6, 3, 1, 0, 1, 3, 4, 3, 0]
```

The second loader is typically used for the face verification task: each sample is a pair of two picture belonging or not to the same person:
Both for the `sklearn.datasets.fetch_lfw_people` and `sklearn.datasets.fetch_lfw_pairs` function it is possible to get an additional dimension with the RGB color channels by passing `color=True`, in that case the shape will be `(2200, 2, 62, 47, 3)`. 

The `sklearn.datasets.fetch_lfw_pairs` datasets is subdivided into 3 subsets: the development train set, the development test set and an evaluation 10_folds set meant to compute performance metrics using a 10-folds cross validation scheme.

**References:**


**Examples**

*Faces recognition example using eigenfaces and SVMs*

**Forest covertypes**

The samples in this dataset correspond to 30×30m patches of forest in the US, collected for the task of predicting each patch’s cover type, i.e. the dominant species of tree. There are seven covertypes, making this a multiclass classification problem. Each sample has 54 features, described on the dataset’s homepage. Some of the features are boolean indicators, while others are discrete or continuous measurements.

**Data Set Characteristics:**

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
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<tr>
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<tr>
<td>Features</td>
<td>int</td>
</tr>
</tbody>
</table>

`sklearn.datasets.fetch_covtype` will load the covertype dataset; it returns a dictionary-like ‘Bunch’ object with the feature matrix in the `data` member and the target values in `target`. If optional argument ‘as_frame’ is set to ‘True’, it will return `data` and `target` as pandas data frame, and there will be an additional member `frame` as well. The dataset will be downloaded from the web if necessary.
RCV1 dataset

Reuters Corpus Volume I (RCV1) is an archive of over 800,000 manually categorized newswire stories made available by Reuters, Ltd. for research purposes. The dataset is extensively described in\(^1\).

**Data Set Characteristics:**

<table>
<thead>
<tr>
<th>Classes</th>
<th>103</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>804414</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>47236</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 1</td>
</tr>
</tbody>
</table>

`sklearn.datasets.fetch_rcv1` will load the following version: RCV1-v2, vectors, full sets, topics multilabels:

```python
>>> from sklearn.datasets import fetch_rcv1

rcv1 = fetch_rcv1()
```

It returns a dictionary-like object, with the following attributes:

- **data**: The feature matrix is a scipy CSR sparse matrix, with 804414 samples and 47236 features. Non-zero values contains cosine-normalized, log TF-IDF vectors. A nearly chronological split is proposed in\(^1\): The first 23149 samples are the training set. The last 781265 samples are the testing set. This follows the official LYRL2004 chronological split. The array has 0.16% of non zero values:

```python
>>> rcv1.data.shape
(804414, 47236)
```

- **target**: The target values are stored in a scipy CSR sparse matrix, with 804414 samples and 103 categories. Each sample has a value of 1 in its categories, and 0 in others. The array has 3.15% of non zero values:

```python
>>> rcv1.target.shape
(804414, 103)
```

- **sample_id**: Each sample can be identified by its ID, ranging (with gaps) from 2286 to 810596:

```python
>>> rcv1.sample_id[:3]
array([2286, 2287, 2288], dtype=uint32)
```

- **target_names**: The target values are the topics of each sample. Each sample belongs to at least one topic, and to up to 17 topics. There are 103 topics, each represented by a string. Their corpus frequencies span five orders of magnitude, from 5 occurrences for ‘GMIL’, to 381327 for ‘CCAT’:

```python
>>> rcv1.target_names[:3].tolist()
['E11', 'ECAT', 'M11']
```

The dataset will be downloaded from the rcv1 homepage if necessary. The compressed size is about 656 MB.

**References**


---

4.7. Dataset loading utilities
Kddcup 99 dataset

The KDD Cup ‘99 dataset was created by processing the tcpdump portions of the 1998 DARPA Intrusion Detection System (IDS) Evaluation dataset, created by MIT Lincoln Lab\textsuperscript{2}. The artificial data (described on the dataset’s homepage) was generated using a closed network and hand-injected attacks to produce a large number of different types of attack with normal activity in the background. As the initial goal was to produce a large training set for supervised learning algorithms, there is a large proportion (80.1\%) of abnormal data which is unrealistic in real world, and inappropriate for unsupervised anomaly detection which aims at detecting ‘abnormal’ data, i.e.:

- qualitatively different from normal data
- in large minority among the observations.

We thus transform the KDD Data set into two different data sets: SA and SF:

- SA is obtained by simply selecting all the normal data, and a small proportion of abnormal data to gives an anomaly proportion of 1\%.
- SF is obtained as in\textsuperscript{3} by simply picking up the data whose attribute logged_in is positive, thus focusing on the intrusion attack, which gives a proportion of 0.3\% of attack.
- http and smtp are two subsets of SF corresponding with third feature equal to ‘http’ (resp. to ‘smtp’).

General KDD structure:

<table>
<thead>
<tr>
<th>Samples total</th>
<th>4898431</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>41</td>
</tr>
<tr>
<td>Features</td>
<td>discrete (int) or continuous (float)</td>
</tr>
<tr>
<td>Targets</td>
<td>str, ‘normal.’ or name of the anomaly type</td>
</tr>
</tbody>
</table>

SA structure:

<table>
<thead>
<tr>
<th>Samples total</th>
<th>976158</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>41</td>
</tr>
<tr>
<td>Features</td>
<td>discrete (int) or continuous (float)</td>
</tr>
<tr>
<td>Targets</td>
<td>str, ‘normal.’ or name of the anomaly type</td>
</tr>
</tbody>
</table>

SF structure:

<table>
<thead>
<tr>
<th>Samples total</th>
<th>699691</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>4</td>
</tr>
<tr>
<td>Features</td>
<td>discrete (int) or continuous (float)</td>
</tr>
<tr>
<td>Targets</td>
<td>str, ‘normal.’ or name of the anomaly type</td>
</tr>
</tbody>
</table>

http structure:

<table>
<thead>
<tr>
<th>Samples total</th>
<th>619052</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>3</td>
</tr>
<tr>
<td>Features</td>
<td>discrete (int) or continuous (float)</td>
</tr>
<tr>
<td>Targets</td>
<td>str, ‘normal.’ or name of the anomaly type</td>
</tr>
</tbody>
</table>

\textsuperscript{2} Analysis and Results of the 1999 DARPA Off-Line Intrusion Detection Evaluation, Richard Lippmann, Joshua W. Haines, David J. Fried, Jonathan Korba, Kumar Das.

smtp structure:

| Samples total | 95373 |
| Dimensionality | 3     |
| Features       | discrete (int) or continuous (float) |
| Targets        | str, ‘normal.’ or name of the anomaly type |

`sklearn.datasets.fetch_kddcup99` will load the kddcup99 dataset; it returns a dictionary-like object with the feature matrix in the `data` member and the target values in `target`. The “as_frame” optional argument converts `data` into a pandas DataFrame and `target` into a pandas Series. The dataset will be downloaded from the web if necessary.

**References**

**California Housing dataset**

**Data Set Characteristics:**

- **Number of Instances** 20640
- **Number of Attributes** 8 numeric, predictive attributes and the target

**Attribute Information**

- MedInc median income in block
- HouseAge median house age in block
- AveRooms average number of rooms
- AveBedrms average number of bedrooms
- Population block population
- AveOcccup average house occupancy
- Latitude house block latitude
- Longitude house block longitude

**Missing Attribute Values** None

This dataset was obtained from the StatLib repository. [http://lib.stat.cmu.edu/datasets/](http://lib.stat.cmu.edu/datasets/)

The target variable is the median house value for California districts.

This dataset was derived from the 1990 U.S. census, using one row per census block group. A block group is the smallest geographical unit for which the U.S. Census Bureau publishes sample data (a block group typically has a population of 600 to 3,000 people).

It can be downloaded/loaded using the `sklearn.datasets.fetch_california_housing` function.

**References**

4.7.3 Generated datasets

In addition, scikit-learn includes various random sample generators that can be used to build artificial datasets of controlled size and complexity.

Generators for classification and clustering

These generators produce a matrix of features and corresponding discrete targets.

Single label

Both `make_blobs` and `make_classification` create multiclass datasets by allocating each class one or more normally-distributed clusters of points. `make_blobs` provides greater control regarding the centers and standard deviations of each cluster, and is used to demonstrate clustering. `make_classification` specialises in introducing noise by way of: correlated, redundant and uninformative features; multiple Gaussian clusters per class; and linear transformations of the feature space.

`make_gaussian_quantiles` divides a single Gaussian cluster into near-equal-size classes separated by concentric hyperspheres. `make_hastie_10_2` generates a similar binary, 10-dimensional problem.

`make_circles` and `make_moons` generate 2d binary classification datasets that are challenging to certain algorithms (e.g. centroid-based clustering or linear classification), including optional Gaussian noise. They are useful for visualisation. `make_circles` produces Gaussian data with a spherical decision boundary for binary classification, while `make_moons` produces two interleaving half circles.
Multilabel

`make_multilabel_classification` generates random samples with multiple labels, reflecting a bag of words drawn from a mixture of topics. The number of topics for each document is drawn from a Poisson distribution, and the topics themselves are drawn from a fixed random distribution. Similarly, the number of words is drawn from Poisson, with words drawn from a multinomial, where each topic defines a probability distribution over words. Simplifications with respect to true bag-of-words mixtures include:

- Per-topic word distributions are independently drawn, where in reality all would be affected by a sparse base distribution, and would be correlated.
- For a document generated from multiple topics, all topics are weighted equally in generating its bag of words.
- Documents without labels words at random, rather than from a base distribution.

Biclustering

`make_biclusters` generates random samples with a constant block diagonal structure for biclustering.

`make_checkerboard` generates an array with block checkerboard structure for biclustering.

Generators for regression

`make_regression` produces regression targets as an optionally-sparse random linear combination of random features, with noise. Its informative features may be uncorrelated, or low rank (few features account for most of the variance).

Other regression generators generate functions deterministically from randomized features. `make_sparse_uncorrelated` produces a target as a linear combination of four features with fixed coefficients. Others encode explicitly non-linear relations: `make_friedman1` is related by polynomial and sine transforms; `make_friedman2` includes feature multiplication and reciprocation; and `make_friedman3` is similar with an arctan transformation on the target.
Generators for manifold learning

- `make_s_curve([n_samples, noise, random_state])`: Generate an S curve dataset.
- `make_swiss_roll([n_samples, noise, random_state])`: Generate a swiss roll dataset.

Generators for decomposition

- `make_low_rank_matrix([n_samples, ...])`: Generate a mostly low rank matrix with bell-shaped singular values.
- `make_sparse_coded_signal([n_samples, *, ...])`: Generate a signal as a sparse combination of dictionary elements.
- `make_spd_matrix([n_dim, *[, random_state]])`: Generate a random symmetric, positive-definite matrix.
- `make_sparse_spd_matrix([dim, alpha, ...])`: Generate a sparse symmetric definite positive matrix.

4.7.4 Loading other datasets

Sample images

Scikit-learn also embeds a couple of sample JPEG images published under Creative Commons license by their authors. Those images can be useful to test algorithms and pipelines on 2D data.

- `load_sample_images()`: Load sample images for image manipulation.
- `load_sample_image(image_name)`: Load the numpy array of a single sample image

**Warning:** The default coding of images is based on the `uint8` dtype to spare memory. Often machine learning algorithms work best if the input is converted to a floating point representation first. Also, if you plan to use `matplotlib.pyplot.imshow`, don’t forget to scale to the range 0 - 1 as done in the following example.

**Examples:**

- *Color Quantization using K-Means*
Datasets in svmlight / libsvm format

scikit-learn includes utility functions for loading datasets in the svmlight / libsvm format. In this format, each line takes the form `<label> <feature-id>:<feature-value> <feature-id>:<feature-value> .. ..`. This format is especially suitable for sparse datasets. In this module, scipy sparse CSR matrices are used for X and numpy arrays are used for y.

You may load a dataset like as follows:

```python
>>> from sklearn.datasets import load_svmlight_file
>>> X_train, y_train = load_svmlight_file("/path/to/train_dataset.txt")
...```

You may also load two (or more) datasets at once:

```python
>>> X_train, y_train, X_test, y_test = load_svmlight_files(
...   "/path/to/train_dataset.txt", "/path/to/test_dataset.txt")
...```

In this case, X_train and X_test are guaranteed to have the same number of features. Another way to achieve the same result is to fix the number of features:

```python
>>> X_test, y_test = load_svmlight_file(
...   "/path/to/test_dataset.txt", n_features=X_train.shape[1])
...```

Related links:

- Public datasets in svmlight / libsvm format: https://www.csie.ntu.edu.tw/~cjlin/libsvmtools/datasets
- Faster API-compatible implementation: https://github.com/mblondel/svmlight-loader

Downloading datasets from the openml.org repository

openml.org is a public repository for machine learning data and experiments, that allows everybody to upload open datasets.

The sklearn.datasets package is able to download datasets from the repository using the function sklearn.datasets.fetch_openml.

For example, to download a dataset of gene expressions in mice brains:

```python
>>> from sklearn.datasets import fetch_openml
>>> mice = fetch_openml(name='miceprotein', version=4)
...```

To fully specify a dataset, you need to provide a name and a version, though the version is optional, see Dataset Versions below. The dataset contains a total of 1080 examples belonging to 8 different classes:

```python
>>> mice.data.shape
(1080, 77)
>>> mice.target.shape
(1080,)
>>> np.unique(mice.target)
array(['c-CS-m', 'c-CS-s', 'c-SC-m', 'c-SC-s', 't-CS-m', 't-CS-s', 't-SC-m', 't-SC-s ..'], dtype=object)
```
You can get more information on the dataset by looking at the `DESCR` and `details` attributes:

```python
>>> print(mice.DESCR)
**Author**: Clara Higuera, Katheleen J. Gardiner, Krzysztof J. Cios
**Source**: [UCI](https://archive.ics.uci.edu/ml/datasets/Mice+Protein+Expression) 2015

```mice.details
    {'id': '40966', 'name': 'MiceProtein', 'version': '4', 'format': 'ARFF', 'upload_date': '2017-11-08T16:00:15', 'licence': 'Public', 'url': 'https://www.openml.org/data/v1/download/17928620/MiceProtein.arff', 'file_id': '17928620', 'default_target_attribute': 'class', 'row_id_attribute': 'MouseID', 'ignore_attribute': ['Genotype', 'Treatment', 'Behavior'], 'tag': ['OpenML-CC18', 'study_135', 'study_98', 'study_99'], 'visibility': 'public', 'status': 'active', 'md5_checksum': '3c479a6885bfa0438971388283a1ce32'}

The `DESCR` contains a free-text description of the data, while `details` contains a dictionary of meta-data stored by openml, like the dataset id. For more details, see the OpenML documentation. The data_id of the mice protein dataset is 40966, and you can use this (or the name) to get more information on the dataset on the openml website:

```python
>>> mice.url
'https://www.openml.org/d/40966'

The data_id also uniquely identifies a dataset from OpenML:

```python
>>> mice = fetch_openml(data_id=40966)
>>> mice.details
```

**Dataset Versions**

A dataset is uniquely specified by its data_id, but not necessarily by its name. Several different “versions” of a dataset with the same name can exist which can contain entirely different datasets. If a particular version of a dataset has been found to contain significant issues, it might be deactivated. Using a name to specify a dataset will yield the earliest version of a dataset that is still active. That means that `fetch_openml(name="miceprotein")` can yield different results at different times if earlier versions become inactive. You can see that the dataset with data_id 40966 that we fetched above is the first version of the “miceprotein” dataset:

```python
>>> mice.details['version']
'1'

In fact, this dataset only has one version. The iris dataset on the other hand has multiple versions:
Specifying the dataset by the name “iris” yields the lowest version, version 1, with the data_id 61. To make sure you always get this exact dataset, it is safest to specify it by the dataset data_id. The other dataset, with data_id 969, is version 3 (version 2 has become inactive), and contains a binarized version of the data:

```python
>>> np.unique(iris_969.target)
array(['N', 'P'], dtype=object)
```

You can also specify both the name and the version, which also uniquely identifies the dataset:

```python
>>> iris_version_3 = fetch_openml(name="iris", version=3)
>>> iris_version_3.details['version']
'3'
>>> iris_version_3.details['id']
'969'
```

References:


Loading from external datasets

scikit-learn works on any numeric data stored as numpy arrays or scipy sparse matrices. Other types that are convertible to numeric arrays such as pandas DataFrame are also acceptable.

Here are some recommended ways to load standard columnar data into a format usable by scikit-learn:

• pandas.io provides tools to read data from common formats including CSV, Excel, JSON and SQL. DataFrames may also be constructed from lists of tuples or dicts. Pandas handles heterogeneous data smoothly and provides tools for manipulation and conversion into a numeric array suitable for scikit-learn.

• scipy.io specializes in binary formats often used in scientific computing context such as .mat and .arff

• numpy/routines.io for standard loading of columnar data into numpy arrays

• scikit-learn’s datasets.load_svmlight_file for the svmlight or libSVM sparse format

4.7. Dataset loading utilities
scikit-learn user guide, Release 0.24.0

- scikit-learn's `datasets.load_files` for directories of text files where the name of each directory is the name of each category and each file inside of each directory corresponds to one sample from that category

For some miscellaneous data such as images, videos, and audio, you may wish to refer to:

- `skimage.io` or `Imageio` for loading images and videos into numpy arrays
- `scipy.io.wavfile.read` for reading WAV files into a numpy array

Categorical (or nominal) features stored as strings (common in pandas DataFrames) will need converting to numerical features using `OneHotEncoder` or `OrdinalEncoder` or similar. See Preprocessing data.

Note: if you manage your own numerical data it is recommended to use an optimized file format such as HDF5 to reduce data load times. Various libraries such as H5Py, PyTables and pandas provides a Python interface for reading and writing data in that format.

4.8 Computing with scikit-learn

4.8.1 Strategies to scale computationally: bigger data

For some applications the amount of examples, features (or both) and/or the speed at which they need to be processed are challenging for traditional approaches. In these cases scikit-learn has a number of options you can consider to make your system scale.

Scaling with instances using out-of-core learning

Out-of-core (or “external memory”) learning is a technique used to learn from data that cannot fit in a computer’s main memory (RAM).

Here is a sketch of a system designed to achieve this goal:

1. a way to stream instances
2. a way to extract features from instances
3. an incremental algorithm

Streaming instances

Basically, 1. may be a reader that yields instances from files on a hard drive, a database, from a network stream etc. However, details on how to achieve this are beyond the scope of this documentation.

Extracting features

2. could be any relevant way to extract features among the different feature extraction methods supported by scikit-learn. However, when working with data that needs vectorization and where the set of features or values is not known in advance one should take explicit care. A good example is text classification where unknown terms are likely to be found during training. It is possible to use a stateful vectorizer if making multiple passes over the data is reasonable from an application point of view. Otherwise, one can turn up the difficulty by using a stateless feature extractor. Currently the preferred way to do this is to use the so-called hashing trick as implemented by `sklearn.feature_extraction.text.HashingVectorizer` for text documents.
Incremental learning

Finally, for 3. we have a number of options inside scikit-learn. Although not all algorithms can learn incrementally (i.e. without seeing all the instances at once), all estimators implementing the `partial_fit` API are candidates. Actually, the ability to learn incrementally from a mini-batch of instances (sometimes called “online learning”) is key to out-of-core learning as it guarantees that at any given time there will be only a small amount of instances in the main memory. Choosing a good size for the mini-batch that balances relevancy and memory footprint could involve some tuning\(^1\).

Here is a list of incremental estimators for different tasks:

- **Classification**
  - `sklearn.naive_bayes.MultinomialNB`
  - `sklearn.naive_bayes.BernoulliNB`
  - `sklearn.linear_model.Perceptron`
  - `sklearn.linear_model.SGDClassifier`
  - `sklearn.linear_model.PassiveAggressiveClassifier`
  - `sklearn.neural_network.MLPClassifier`

- **Regression**
  - `sklearn.linear_model.SGDRegressor`
  - `sklearn.linear_model.PassiveAggressiveRegressor`
  - `sklearn.neural_network.MLPRegressor`

- **Clustering**
  - `sklearn.cluster.MiniBatchKMeans`
  - `sklearn.cluster.Birch`

- **Decomposition / feature Extraction**
  - `sklearn.decomposition.MiniBatchDictionaryLearning`
  - `sklearn.decomposition.IncrementalPCA`
  - `sklearn.decomposition.LatentDirichletAllocation`

- **Preprocessing**
  - `sklearn.preprocessing.StandardScaler`
  - `sklearn.preprocessing.MinMaxScaler`
  - `sklearn.preprocessing.MaxAbsScaler`

For classification, a somewhat important thing to note is that although a stateless feature extraction routine may be able to cope with new/unseen attributes, the incremental learner itself may be unable to cope with new/unseen targets classes. In this case you have to pass all the possible classes to the first `partial_fit` call using the `classes=` parameter.

Another aspect to consider when choosing a proper algorithm is that not all of them put the same importance on each example over time. Namely, the `Perceptron` is still sensitive to badly labeled examples even after many examples whereas the `SGD*` and `PassiveAggressive*` families are more robust to this kind of artifacts. Conversely, the

\(^1\) Depending on the algorithm the mini-batch size can influence results or not. SGD*, PassiveAggressive*, and discrete NaiveBayes are truly online and are not affected by batch size. Conversely, MiniBatchKMeans convergence rate is affected by the batch size. Also, its memory footprint can vary dramatically with batch size.
latter also tend to give less importance to remarkably different, yet properly labeled examples when they come late in the stream as their learning rate decreases over time.

**Examples**

Finally, we have a full-fledged example of *Out-of-core classification of text documents*. It is aimed at providing a starting point for people wanting to build out-of-core learning systems and demonstrates most of the notions discussed above.

Furthermore, it also shows the evolution of the performance of different algorithms with the number of processed examples.

![Classification accuracy as a function of training examples](chart.png)

Now looking at the computation time of the different parts, we see that the vectorization is much more expensive than learning itself. From the different algorithms, *MultinomialNB* is the most expensive, but its overhead can be mitigated by increasing the size of the mini-batches (exercise: change `minibatch_size` to 100 and 10000 in the program and compare).
### Notes

#### 4.8.2 Computational Performance

For some applications the performance (mainly latency and throughput at prediction time) of estimators is crucial. It may also be of interest to consider the training throughput but this is often less important in a production setup (where it often takes place offline).

We will review here the orders of magnitude you can expect from a number of scikit-learn estimators in different contexts and provide some tips and tricks for overcoming performance bottlenecks.

Prediction latency is measured as the elapsed time necessary to make a prediction (e.g. in micro-seconds). Latency is often viewed as a distribution and operations engineers often focus on the latency at a given percentile of this distribution (e.g. the 90 percentile).

Prediction throughput is defined as the number of predictions the software can deliver in a given amount of time (e.g. in predictions per second).

An important aspect of performance optimization is also that it can hurt prediction accuracy. Indeed, simpler models (e.g. linear instead of non-linear, or with fewer parameters) often run faster but are not always able to take into account the same exact properties of the data as more complex ones.
Prediction Latency

One of the most straight-forward concerns one may have when using/choosing a machine learning toolkit is the latency at which predictions can be made in a production environment.

The main factors that influence the prediction latency are

1. Number of features
2. Input data representation and sparsity
3. Model complexity
4. Feature extraction

A last major parameter is also the possibility to do predictions in bulk or one-at-a-time mode.

Bulk versus Atomic mode

In general doing predictions in bulk (many instances at the same time) is more efficient for a number of reasons (branching predictability, CPU cache, linear algebra libraries optimizations etc.). Here we see on a setting with few features that independently of estimator choice the bulk mode is always faster, and for some of them by 1 to 2 orders of magnitude:
To benchmark different estimators for your case you can simply change the `n_features` parameter in this example: *Prediction Latency*. This should give you an estimate of the order of magnitude of the prediction latency.

### Configuring Scikit-learn for reduced validation overhead

Scikit-learn does some validation on data that increases the overhead per call to `predict` and similar functions. In particular, checking that features are finite (not NaN or infinite) involves a full pass over the data. If you ensure that your data is acceptable, you may suppress checking for finiteness by setting the environment variable `SKLEARN_ASSUME_FINITE` to a non-empty string before importing scikit-learn, or configure it in Python with `set_config`. For more control than these global settings, a `config_context` allows you to set this configuration within a specified context:

```python
>>> import sklearn

>>> with sklearn.config_context(assume_finite=True):
...   pass  # do learning/prediction here with reduced validation
```

Note that this will affect all uses of `assert_all_finite` within the context.

### Influence of the Number of Features

Obviously when the number of features increases so does the memory consumption of each example. Indeed, for a matrix of $M$ instances with $N$ features, the space complexity is in $O(NM)$. From a computing perspective it also means that the number of basic operations (e.g., multiplications for vector-matrix products in linear models) increases too. Here is a graph of the evolution of the prediction latency with the number of features:
Overall you can expect the prediction time to increase at least linearly with the number of features (non-linear cases can happen depending on the global memory footprint and estimator).

Influence of the Input Data Representation

Scipy provides sparse matrix data structures which are optimized for storing sparse data. The main feature of sparse formats is that you don’t store zeros so if your data is sparse then you use much less memory. A non-zero value in a sparse (CSR or CSC) representation will only take on average one 32bit integer position + the 64 bit floating point value + an additional 32bit per row or column in the matrix. Using sparse input on a dense (or sparse) linear model can speedup prediction by quite a bit as only the non zero valued features impact the dot product and thus the model predictions. Hence if you have 100 non zeros in 1e6 dimensional space, you only need 100 multiply and add operation instead of 1e6.

Calculation over a dense representation, however, may leverage highly optimised vector operations and multithreading in BLAS, and tends to result in fewer CPU cache misses. So the sparsity should typically be quite high (10% non-zeros max, to be checked depending on the hardware) for the sparse input representation to be faster than the dense input representation on a machine with many CPUs and an optimized BLAS implementation.

Here is sample code to test the sparsity of your input:

```python
def sparsity_ratio(X):
    return 1.0 - np.count_nonzero(X) / float(X.shape[0] * X.shape[1])
print("input sparsity ratio:", sparsity_ratio(X))
```

As a rule of thumb you can consider that if the sparsity ratio is greater than 90% you can probably benefit from sparse formats. Check Scipy’s sparse matrix formats documentation for more information on how to build (or convert your data to) sparse matrix formats. Most of the time the CSR and CSC formats work best.
Influence of the Model Complexity

Generally speaking, when model complexity increases, predictive power and latency are supposed to increase. Increasing predictive power is usually interesting, but for many applications we would better not increase prediction latency too much. We will now review this idea for different families of supervised models.

For `sklearn.linear_model` (e.g. Lasso, ElasticNet, SGDClassifier/Regressor, Ridge & RidgeClassifier, PassiveAggressiveClassifier/Regressor, LinearSVC, LogisticRegression...) the decision function that is applied at prediction time is the same (a dot product), so latency should be equivalent.

Here is an example using `SGDClassifier` with the `elasticnet` penalty. The regularization strength is globally controlled by the `alpha` parameter. With a sufficiently high `alpha`, one can then increase the `l1_ratio` parameter of `elasticnet` to enforce various levels of sparsity in the model coefficients. Higher sparsity here is interpreted as less model complexity as we need fewer coefficients to describe it fully. Of course sparsity influences in turn the prediction time as the sparse dot-product takes time roughly proportional to the number of non-zero coefficients.

![Influence of varying 'l1_ratio' on SGDClassifier](image)

For the `sklearn.svm` family of algorithms with a non-linear kernel, the latency is tied to the number of support vectors (the fewer the faster). Latency and throughput should (asymptotically) grow linearly with the number of support vectors in a SVC or SVR model. The kernel will also influence the latency as it is used to compute the projection of the input vector once per support vector. In the following graph the `nu` parameter of `NuSVR` was used to influence the number of support vectors.
For `sklearn.ensemble` of trees (e.g. RandomForest, GBT, ExtraTrees etc) the number of trees and their depth play the most important role. Latency and throughput should scale linearly with the number of trees. In this case we used directly the `n_estimators` parameter of `GradientBoostingRegressor`.

In any case be warned that decreasing model complexity can hurt accuracy as mentioned above. For instance a non-linearly separable problem can be handled with a speedy linear model but prediction power will very likely suffer in the process.
Feature Extraction Latency

Most scikit-learn models are usually pretty fast as they are implemented either with compiled Cython extensions or optimized computing libraries. On the other hand, in many real world applications the feature extraction process (i.e. turning raw data like database rows or network packets into numpy arrays) governs the overall prediction time. For example on the Reuters text classification task the whole preparation (reading and parsing SGML files, tokenizing the text and hashing it into a common vector space) is taking 100 to 500 times more time than the actual prediction code, depending on the chosen model.

![Prediction Times (1000 instances)](image)

In many cases it is thus recommended to carefully time and profile your feature extraction code as it may be a good place to start optimizing when your overall latency is too slow for your application.

Prediction Throughput

Another important metric to care about when sizing production systems is the throughput i.e. the number of predictions you can make in a given amount of time. Here is a benchmark from the Prediction Latency example that measures this quantity for a number of estimators on synthetic data:
These throughputs are achieved on a single process. An obvious way to increase the throughput of your application is to spawn additional instances (usually processes in Python because of the **Gil**) that share the same model. One might also add machines to spread the load. A detailed explanation on how to achieve this is beyond the scope of this documentation though.

**Tips and Tricks**

**Linear algebra libraries**

As scikit-learn relies heavily on Numpy/Scipy and linear algebra in general it makes sense to take explicit care of the versions of these libraries. Basically, you ought to make sure that Numpy is built using an optimized **BLAS / LAPACK** library.

Not all models benefit from optimized BLAS and Lapack implementations. For instance models based on (randomized) decision trees typically do not rely on BLAS calls in their inner loops, nor do kernel SVMs (**SVC**, **SVR**, **NuSVC**, **NuSVR**). On the other hand a linear model implemented with a BLAS DGEMM call (**numpy.dot**) will typically benefit hugely from a tuned BLAS implementation and lead to orders of magnitude speedup over a non-optimized BLAS.

You can display the BLAS / LAPACK implementation used by your NumPy / SciPy / scikit-learn install with the following commands:

```python
from numpy.distutils.system_info import get_info
print(get_info('blas_opt'))
print(get_info('lapack_opt'))
```

**Optimized BLAS / LAPACK implementations include:**

- Atlas (need hardware specific tuning by rebuilding on the target machine)
- OpenBLAS
More information can be found on the Scipy install page and in this blog post from Daniel Nouri which has some nice step by step install instructions for Debian / Ubuntu.

### Limiting Working Memory

Some calculations when implemented using standard numpy vectorized operations involve using a large amount of temporary memory. This may potentially exhaust system memory. Where computations can be performed in fixed-memory chunks, we attempt to do so, and allow the user to hint at the maximum size of this working memory (defaulting to 1GB) using `set_config` or `config_context`. The following suggests to limit temporary working memory to 128 MiB:

```
>>> import sklearn
>>> with sklearn.config_context(working_memory=128):
...    pass  # do chunked work here
```

An example of a chunked operation adhering to this setting is `pairwise_distances_chunked`, which facilitates computing row-wise reductions of a pairwise distance matrix.

### Model Compression

Model compression in scikit-learn only concerns linear models for the moment. In this context it means that we want to control the model sparsity (i.e. the number of non-zero coordinates in the model vectors). It is generally a good idea to combine model sparsity with sparse input data representation.

Here is sample code that illustrates the use of the `sparsify()` method:

```python
clf = SGDRegressor(penalty='elasticnet', l1_ratio=0.25)
clf.fit(X_train, y_train).sparsify()
clf.predict(X_test)
```

In this example we prefer the `elasticnet` penalty as it is often a good compromise between model compactness and prediction power. One can also further tune the `l1_ratio` parameter (in combination with the regularization strength `alpha`) to control this tradeoff.

A typical benchmark on synthetic data yields a >30% decrease in latency when both the model and input are sparse (with 0.000024 and 0.027400 non-zero coefficients ratio respectively). Your mileage may vary depending on the sparsity and size of your data and model. Furthermore, sparsifying can be very useful to reduce the memory usage of predictive models deployed on production servers.

### Model Reshaping

Model reshaping consists in selecting only a portion of the available features to fit a model. In other words, if a model discards features during the learning phase we can then strip those from the input. This has several benefits. Firstly it reduces memory (and therefore time) overhead of the model itself. It also allows to discard explicit feature selection components in a pipeline once we know which features to keep from a previous run. Finally, it can help reduce processing time and I/O usage upstream in the data access and feature extraction layers by not collecting and building features that are discarded by the model. For instance if the raw data come from a database, it can make it possible to write simpler and faster queries or reduce I/O usage by making the queries return lighter records. At the moment, reshaping needs to be performed manually in scikit-learn. In the case of sparse input (particularly in CSR format), it is generally sufficient to not generate the relevant features, leaving their columns empty.
4.8.3 Parallelism, resource management, and configuration

Parallelism

Some scikit-learn estimators and utilities can parallelize costly operations using multiple CPU cores, thanks to the following components:

• via the joblib library. In this case the number of threads or processes can be controlled with the \texttt{n\_jobs} parameter.
• via OpenMP, used in C or Cython code.

In addition, some of the numpy routines that are used internally by scikit-learn may also be parallelized if numpy is installed with specific numerical libraries such as MKL, OpenBLAS, or BLIS.

We describe these 3 scenarios in the following subsections.

Joblib-based parallelism

When the underlying implementation uses joblib, the number of workers (threads or processes) that are spawned in parallel can be controlled via the \texttt{n\_jobs} parameter.

\textbf{Note:} Where (and how) parallelization happens in the estimators is currently poorly documented. Please help us by improving our docs and tackle issue 14228!

Joblib is able to support both multi-processing and multi-threading. Whether joblib chooses to spawn a thread or a process depends on the \texttt{backend} that it’s using.

Scikit-learn generally relies on the \texttt{loky} backend, which is joblib’s default backend. Loky is a multi-processing backend. When doing multi-processing, in order to avoid duplicating the memory in each process (which isn’t reasonable with big datasets), joblib will create a \texttt{memmap} that all processes can share, when the data is bigger than 1MB.

In some specific cases (when the code that is run in parallel releases the GIL), scikit-learn will indicate to joblib that a multi-threading backend is preferable.

As a user, you may control the backend that joblib will use (regardless of what scikit-learn recommends) by using a context manager:

```python
from joblib import parallel_backend

with parallel_backend('threading', n_jobs=2):
    # Your scikit-learn code here
```

Please refer to the joblib’s docs for more details.

In practice, whether parallelism is helpful at improving runtime depends on many factors. It is usually a good idea to experiment rather than assuming that increasing the number of workers is always a good thing. In some cases it can be highly detrimental to performance to run multiple copies of some estimators or functions in parallel (see oversubscription below).
OpenMP-based parallelism

OpenMP is used to parallelize code written in Cython or C, relying on multi-threading exclusively. By default (and unless joblib is trying to avoid oversubscription), the implementation will use as many threads as possible.

You can control the exact number of threads that are used via the `OMP_NUM_THREADS` environment variable:

```
$ OMP_NUM_THREADS=4 python my_script.py
```

Parallel Numpy routines from numerical libraries

Scikit-learn relies heavily on NumPy and SciPy, which internally call multi-threaded linear algebra routines implemented in libraries such as MKL, OpenBLAS or BLIS.

The number of threads used by the OpenBLAS, MKL or BLIS libraries can be set via the `MKL_NUM_THREADS`, `OPENBLAS_NUM_THREADS`, and `BLIS_NUM_THREADS` environment variables.

Please note that scikit-learn has no direct control over these implementations. Scikit-learn solely relies on Numpy and Scipy.

Note: At the time of writing (2019), NumPy and SciPy packages distributed on pypi.org (used by `pip`) and on the conda-forge channel are linked with OpenBLAS, while conda packages shipped on the “defaults” channel from anaconda.org are linked by default with MKL.

Oversubscription: spawning too many threads

It is generally recommended to avoid using significantly more processes or threads than the number of CPUs on a machine. Over-subscription happens when a program is running too many threads at the same time.

Suppose you have a machine with 8 CPUs. Consider a case where you’re running a `GridSearchCV` (parallelized with joblib) with `n_jobs=8` over a `HistGradientBoostingClassifier` (parallelized with OpenMP). Each instance of `HistGradientBoostingClassifier` will spawn 8 threads (since you have 8 CPUs). That’s a total of $8 \times 8 = 64$ threads, which leads to oversubscription of physical CPU resources and to scheduling overhead.

Oversubscription can arise in the exact same fashion with parallelized routines from MKL, OpenBLAS or BLIS that are nested in joblib calls.

Starting from `joblib >= 0.14`, when the `loky` backend is used (which is the default), joblib will tell its child processes to limit the number of threads they can use, so as to avoid oversubscription. In practice the heuristic that joblib uses is to tell the processes to use `max_threads = n_cpus // n_jobs`, via their corresponding environment variable. Back to our example from above, since the `joblib` backend of `GridSearchCV` is `loky`, each process will only be able to use 1 thread instead of 8, thus mitigating the oversubscription issue.

Note that:

- Manually setting one of the environment variables (`OMP_NUM_THREADS`, `MKL_NUM_THREADS`, `OPENBLAS_NUM_THREADS`, or `BLIS_NUM_THREADS`) will take precedence over what joblib tries to do. The total number of threads will be `n_jobs * <LIB>_NUM_THREADS`. Note that setting this limit will also impact your computations in the main process, which will only use `<LIB>_NUM_THREADS`. Joblib exposes a context manager for finer control over the number of threads in its workers (see joblib docs linked below).

- Joblib is currently unable to avoid oversubscription in a multi-threading context. It can only do so with the `loky` backend (which spawns processes).

You will find additional details about joblib mitigation of oversubscription in `joblib documentation`. 

4.8. Computing with scikit-learn
Configuration switches

Python runtime

`sklearn.set_config` controls the following behaviors:

- **assume_finite** used to skip validation, which enables faster computations but may lead to segmentation faults if the data contains NaNs.
- **working_memory** the optimal size of temporary arrays used by some algorithms.

Environment variables

These environment variables should be set before importing scikit-learn.

- **SKLEARN_SITE_JOBLIB** When this environment variable is set to a non zero value, scikit-learn uses the site joblib rather than its vendored version. Consequently, joblib must be installed for scikit-learn to run. Note that using the site joblib is at your own risks: the versions of scikit-learn and joblib need to be compatible. Currently, joblib 0.11+ is supported. In addition, dumps from joblib.Memory might be incompatible, and you might loose some caches and have to redownload some datasets.
  
  Deprecated since version 0.21: As of version 0.21 this parameter has no effect, vendored joblib was removed and site joblib is always used.

- **SKLEARN_ASSUME_FINITE** Sets the default value for the `assume_finite` argument of `sklearn.set_config`.

- **SKLEARN_WORKING_MEMORY** Sets the default value for the `working_memory` argument of `sklearn.set_config`.

- **SKLEARN_SEED** Sets the seed of the global random generator when running the tests, for reproducibility.

- **SKLEARN_SKIP_NETWORK_TESTS** When this environment variable is set to a non zero value, the tests that need network access are skipped.

### 4.9 Model persistence

After training a scikit-learn model, it is desirable to have a way to persist the model for future use without having to retrain. The following sections give you some hints on how to persist a scikit-learn model.

#### 4.9.1 Python specific serialization

It is possible to save a model in scikit-learn by using Python’s built-in persistence model, namely `pickle`:

```python
>>> from sklearn import svm
>>> from sklearn import datasets
>>> clf = svm.SVC()
>>> X, y = datasets.load_iris(return_X_y=True)
>>> clf.fit(X, y)
SVC()

>>> import pickle
>>> s = pickle.dumps(clf)
```
In the specific case of scikit-learn, it may be better to use joblib’s replacement of pickle (dump & load), which is more efficient on objects that carry large numpy arrays internally as is often the case for fitted scikit-learn estimators, but can only pickle to the disk and not to a string:

```python
>>> from joblib import dump, load
>>> dump(clf, 'filename.joblib')
```

Later you can load back the pickled model (possibly in another Python process) with:

```python
>>> clf = load('filename.joblib')
```

**Note:** dump and load functions also accept file-like object instead of filenames. More information on data persistence with Joblib is available [here](#).

### Security & maintainability limitations

pickle (and joblib by extension), has some issues regarding maintainability and security. Because of this,

- Never unpickle untrusted data as it could lead to malicious code being executed upon loading.
- While models saved using one version of scikit-learn might load in other versions, this is entirely unsupported and inadvisable. It should also be kept in mind that operations performed on such data could give different and unexpected results.

In order to rebuild a similar model with future versions of scikit-learn, additional metadata should be saved along the pickled model:

- The training data, e.g. a reference to an immutable snapshot
- The python source code used to generate the model
- The versions of scikit-learn and its dependencies
- The cross validation score obtained on the training data

This should make it possible to check that the cross-validation score is in the same range as before.

Since a model internal representation may be different on two different architectures, dumping a model on one architecture and loading it on another architecture is not a supported behaviour, even if it might work on some cases. To overcome the issue of portability, pickle models are often deployed in production using containers, like docker.

If you want to know more about these issues and explore other possible serialization methods, please refer to this talk by Alex Gaynor.
4.9.2 Interoperable formats

For reproducibility and quality control needs, when different architectures and environments should be taken into account, exporting the model in Open Neural Network Exchange format or Predictive Model Markup Language (PMML) format might be a better approach than using pickle alone. These are helpful where you may want to use your model for prediction in a different environment from where the model was trained.

ONNX is a binary serialization of the model. It has been developed to improve the usability of the interoperable representation of data models. It aims to facilitate the conversion of the data models between different machine learning frameworks, and to improve their portability on different computing architectures. More details are available from the ONNX tutorial. To convert scikit-learn model to ONNX a specific tool sklearn-onnx has been developed.

PMML is an implementation of the XML document standard defined to represent data models together with the data used to generate them. Being human and machine readable, PMML is a good option for model validation on different platforms and long term archiving. On the other hand, as XML in general, its verbosity does not help in production when performance is critical. To convert scikit-learn model to PMML you can use for example sklearn2pmml distributed under the Affero GPLv3 license.

4.10 Common pitfalls and recommended practices

The purpose of this chapter is to illustrate some common pitfalls and anti-patterns that occur when using scikit-learn. It provides examples of what not to do, along with a corresponding correct example.

4.10.1 Inconsistent preprocessing

scikit-learn provides a library of Dataset transformations, which may clean (see Preprocessing data), reduce (see Unsupervised dimensionality reduction), expand (see Kernel Approximation) or generate (see Feature extraction) feature representations. If these data transforms are used when training a model, they also must be used on subsequent datasets, whether it’s test data or data in a production system. Otherwise, the feature space will change, and the model will not be able to perform effectively.

For the following example, let’s create a synthetic dataset with a single feature:

```python
>>> from sklearn.datasets import make_regression
>>> from sklearn.model_selection import train_test_split

>>> random_state = 42
>>> X, y = make_regression(random_state=random_state, n_features=1, noise=1)

>>> X_train, X_test, y_train, y_test = train_test_split(

...     X, y, test_size=0.4, random_state=random_state)
```

Wrong

The train dataset is scaled, but not the test dataset, so model performance on the test dataset is worse than expected:

```python
>>> from sklearn.metrics import mean_squared_error
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.preprocessing import StandardScaler

>>> scaler = StandardScaler()
>>> X_train_transformed = scaler.fit_transform(X_train)
>>> model = LinearRegression().fit(X_train_transformed, y_train)
>>> mean_squared_error(y_test, model.predict(X_test))
62.80...
```
Right

Instead of passing the non-transformed \( X_{\text{test}} \) to `predict`, we should transform the test data, the same way we transformed the training data:

```python
>>> X_test_transformed = scaler.transform(X_test)
>>> mean_squared_error(y_test, model.predict(X_test_transformed))
0.90...
```

Alternatively, we recommend using a `Pipeline`, which makes it easier to chain transformations with estimators, and reduces the possibility of forgetting a transformation:

```python
>>> from sklearn.pipeline import make_pipeline

>>> model = make_pipeline(StandardScaler(), LinearRegression())

>>> model.fit(X_train, y_train)
Pipeline(steps=[('standardscaler', StandardScaler()), ('linearregression', LinearRegression())])

>>> mean_squared_error(y_test, model.predict(X_test))
0.90...
```

Pipelines also help avoiding another common pitfall: leaking the test data into the training data.

### 4.10.2 Data leakage

Data leakage occurs when information that would not be available at prediction time is used when building the model. This results in overly optimistic performance estimates, for example from cross-validation, and thus poorer performance when the model is used on actually novel data, for example during production.

A common cause is not keeping the test and train data subsets separate. Test data should never be used to make choices about the model. The **general rule is to never call `fit` on the test data**. While this may sound obvious, this is easy to miss in some cases, for example when applying certain pre-processing steps.

Although both train and test data subsets should receive the same preprocessing transformation (as described in the previous section), it is important that these transformations are only learnt from the training data. For example, if you have a normalization step where you divide by the average value, the average should be the average of the train subset, not the average of all the data. If the test subset is included in the average calculation, information from the test subset is influencing the model.

An example of data leakage during preprocessing is detailed below.

#### Data leakage during pre-processing

**Note:** We here choose to illustrate data leakage with a feature selection step. This risk of leakage is however relevant with almost all transformations in scikit-learn, including (but not limited to) `StandardScaler`, `SimpleImputer`, and `PCA`.

A number of `Feature selection` functions are available in scikit-learn. They can help remove irrelevant, redundant and noisy features as well as improve your model build time and performance. As with any other type of preprocessing, feature selection should only use the training data. Including the test data in feature selection will optimistically bias your model.

To demonstrate we will create this binary classification problem with 10,000 randomly generated features:
Wrong

Using all the data to perform feature selection results in an accuracy score much higher than chance, even though our targets are completely random. This randomness means that our \( X \) and \( y \) are independent and we thus expect the accuracy to be around 0.5. However, since the feature selection step ‘sees’ the test data, the model has an unfair advantage. In the incorrect example below we first use all the data for feature selection and then split the data into training and test subsets for model fitting. The result is a much higher than expected accuracy score:

```python
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.feature_selection import SelectKBest
>>> from sklearn.ensemble import GradientBoostingClassifier
>>> from sklearn.metrics import accuracy_score

>>> # Incorrect preprocessing: the entire data is transformed
>>> X_selected = SelectKBest(k=25).fit_transform(X, y)

>>> X_train, X_test, y_train, y_test = train_test_split(
... X, y, random_state=42)
>>> gbc = GradientBoostingClassifier(random_state=1)
>>> gbc.fit(X_train, y_train)
GradientBoostingClassifier(random_state=1)

>>> y_pred = gbc.predict(X_test)
>>> accuracy_score(y_test, y_pred)
0.76
```

Right

To prevent data leakage, it is good practice to split your data into train and test subsets first. Feature selection can then be formed using just the train dataset. Notice that whenever we use `fit` or `fit_transform`, we only use the train dataset. The score is now what we would expect for the data, close to chance:

```python
>>> X_train, X_test, y_train, y_test = train_test_split(
... X, y, random_state=42)
>>> select = SelectKBest(k=25)
>>> X_train_selected = select.fit_transform(X_train, y_train)

>>> gbc = GradientBoostingClassifier(random_state=1)
>>> gbc.fit(X_train_selected, y_train)
GradientBoostingClassifier(random_state=1)

>>> X_test_selected = select.transform(X_test)
>>> y_pred = gbc.predict(X_test_selected)
>>> accuracy_score(y_test, y_pred)
0.46
```

Here again, we recommend using a `Pipeline` to chain together the feature selection and model estimators. The pipeline ensures that only the training data is used when performing `fit` and the test data is used only for calculating the accuracy score:
>>> from sklearn.pipeline import make_pipeline
>>> X_train, X_test, y_train, y_test = train_test_split(  ...
    X, y, random_state=42)
>>> pipeline = make_pipeline(SelectKBest(k=25),  ...
    GradientBoostingClassifier(random_state=1))
>>> pipeline.fit(X_train, y_train)
Pipeline(steps=[('selectkbest', SelectKBest(k=25)),  ...
    ('gradientboostingclassifier', GradientBoostingClassifier(random_state=1))])

>>> y_pred = pipeline.predict(X_test)
>>> accuracy_score(y_test, y_pred)
0.46

The pipeline can also be fed into a cross-validation function such as `cross_val_score`. Again, the pipeline ensures that the correct data subset and estimator method is used during fitting and predicting:

```python
>>> from sklearn.model_selection import cross_val_score
>>> scores = cross_val_score(pipeline, X, y)
>>> print(f"Mean accuracy: {scores.mean():.2f}+/−{scores.std():.2f}\")
Mean accuracy: 0.45+/−0.07
```

### How to avoid data leakage

Below are some tips on avoiding data leakage:

- Always split the data into train and test subsets first, particularly before any preprocessing steps.
- Never include test data when using the `fit` and `fit_transform` methods. Using all the data, e.g., `fit(X)`, can result in overly optimistic scores.

  Conversely, the `transform` method should be used on both train and test subsets as the same preprocessing should be applied to all the data. This can be achieved by using `fit_transform` on the train subset and `transform` on the test subset.

- The scikit-learn `pipeline` is a great way to prevent data leakage as it ensures that the appropriate method is performed on the correct data subset. The pipeline is ideal for use in cross-validation and hyper-parameter tuning functions.

#### 4.10.3 Controlling randomness

Some scikit-learn objects are inherently random. These are usually estimators (e.g., `RandomForestClassifier`) and cross-validation splitters (e.g., `KFold`). The randomness of these objects is controlled via their `random_state` parameter, as described in the Glossary. This section expands on the glossary entry, and describes good practices and common pitfalls w.r.t. to this subtle parameter.

**Note:** Recommendation summary

For an optimal robustness of cross-validation (CV) results, pass `RandomState` instances when creating estimators, or leave `random_state` to `None`. Passing integers to CV splitters is usually the safest option and is preferable; passing `RandomState` instances to splitters may sometimes be useful to achieve very specific use-cases. For both estimators and splitters, passing an integer vs passing an instance (or `None`) leads to subtle but significant differences, especially for CV procedures. These differences are important to understand when reporting results.

For reproducible results across executions, remove any use of `random_state=None`.

---

4.10. Common pitfalls and recommended practices
Using None or RandomState instances, and repeated calls to fit and split

The random_state parameter determines whether multiple calls to fit (for estimators) or to split (for CV splitters) will produce the same results, according to these rules:

- If an integer is passed, calling fit or split multiple times always yields the same results.
- If None or a RandomState instance is passed: fit and split will yield different results each time they are called, and the succession of calls explores all sources of entropy. None is the default value for all random_state parameters.

We here illustrate these rules for both estimators and CV splitters.

Note: Since passing random_state=None is equivalent to passing the global RandomState instance from numpy(random_state=np.random.mtrand._rand), we will not explicitly mention None here. Everything that applies to instances also applies to using None.

Estimators

Passing instances means that calling fit multiple times will not yield the same results, even if the estimator is fitted on the same data and with the same hyper-parameters:

```python
>>> from sklearn.linear_model import SGDClassifier
>>> from sklearn.datasets import make_classification
>>> import numpy as np

>>> rng = np.random.RandomState(0)
>>> X, y = make_classification(n_features=5, random_state=rng)
>>> sgd = SGDClassifier(random_state=rng)

>>> sgd.fit(X, y).coef_
array([[ 8.85418642,  4.79084103, -3.13077794,  8.11915045, -0.56479934]])

>>> sgd.fit(X, y).coef_
array([[ 6.70814003,  5.25291366, -7.55212743,  5.18197458,  1.37845099]])
```

We can see from the snippet above that repeatedly calling sgd.fit has produced different models, even if the data was the same. This is because the Random Number Generator (RNG) of the estimator is consumed (i.e. mutated) when fit is called, and this mutated RNG will be used in the subsequent calls to fit. In addition, the rng object is shared across all objects that use it, and as a consequence, these objects become somewhat inter-dependent. For example, two estimators that share the same RandomState instance will influence each other, as we will see later when we discuss cloning. This point is important to keep in mind when debugging.

If we had passed an integer to the random_state parameter of the RandomForestClassifier, we would have obtained the same models, and thus the same scores each time. When we pass an integer, the same RNG is used across all calls to fit. What internally happens is that even though the RNG is consumed when fit is called, it is always reset to its original state at the beginning of fit.
CV splitters

Randomized CV splitters have a similar behavior when a RandomState instance is passed; calling split multiple times yields different data splits:

```python
>>> from sklearn.model_selection import KFold
>>> import numpy as np

>>> X = y = np.arange(10)
>>> rng = np.random.RandomState(0)
>>> cv = KFold(n_splits=2, shuffle=True, random_state=rng)

>>> for train, test in cv.split(X, y):
...     print(train, test)
[0 3 5 6 7] [1 2 4 8 9]
[1 2 4 8 9] [0 3 5 6 7]

>>> for train, test in cv.split(X, y):
...     print(train, test)
[0 4 6 7 8] [1 2 3 5 9]
[1 2 3 5 9] [0 4 6 7 8]
```

We can see that the splits are different from the second time split is called. This may lead to unexpected results if you compare the performance of multiple estimators by calling split many times, as we will see in the next section.

Common pitfalls and subtleties

While the rules that govern the random_state parameter are seemingly simple, they do however have some subtle implications. In some cases, this can even lead to wrong conclusions.

Estimators

Different `random_state` types lead to different cross-validation procedures

Depending on the type of the random_state parameter, estimators will behave differently, especially in cross-validation procedures. Consider the following snippet:

```python
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.datasets import make_classification
>>> from sklearn.model_selection import cross_val_score
>>> import numpy as np

>>> X, y = make_classification(random_state=0)
>>> rf_123 = RandomForestClassifier(random_state=123)
>>> cross_val_score(rf_123, X, y)
array([0.85, 0.95, 0.95, 0.9 , 0.9 ])

>>> rf_inst = RandomForestClassifier(random_state=np.random.RandomState(0))
>>> cross_val_score(rf_inst, X, y)
array([0.9 , 0.95, 0.95, 0.9 , 0.9 ])
```

We see that the cross-validated scores of rf_123 and rf_inst are different, as should be expected since we didn’t pass the same random_state parameter. However, the difference between these scores is more subtle than it looks, and the cross-validation procedures that were performed by cross_val_score significantly differ in each case.
• Since `rf_123` was passed an integer, every call to `fit` uses the same RNG: this means that all random characteristics of the random forest estimator will be the same for each of the 5 folds of the CV procedure. In particular, the (randomly chosen) subset of features of the estimator will be the same across all folds.

• Since `rf_inst` was passed a `RandomState` instance, each call to `fit` starts from a different RNG. As a result, the random subset of features will be different for each fold.

While having a constant estimator RNG across folds isn’t inherently wrong, we usually want CV results that are robust w.r.t. the estimator’s randomness. As a result, passing an instance instead of an integer may be preferable, since it will allow the estimator RNG to vary for each fold.

**Note:** Here, `cross_val_score` will use a non-randomized CV splitter (as is the default), so both estimators will be evaluated on the same splits. This section is not about variability in the splits. Also, whether we pass an integer or an instance to `make_classification` isn’t relevant for our illustration purpose: what matters is what we pass to the `RandomForestClassifier` estimator.

### Cloning

Another subtle side effect of passing `RandomState` instances is how `clone` will work:

```python
>>> from sklearn import clone
>>> from sklearn.ensemble import RandomForestClassifier
>>> import numpy as np

>>> rng = np.random.RandomState(0)
>>> a = RandomForestClassifier(random_state=rng)
>>> b = clone(a)
```

Since an `RandomState` instance was passed to `a`, `a` and `b` are not clones in the strict sense, but rather clones in the statistical sense: `a` and `b` will still be different models, even when calling `fit(X, y)` on the same data. Moreover, `a` and `b` will influence each other since they share the same internal RNG: calling `a.fit` will consume `b`'s RNG, and calling `b.fit` will consume `a`'s RNG, since they are the same. This bit is true for any estimators that share a `random_state` parameter; it is not specific to clones.

If an integer were passed, `a` and `b` would be exact clones and they would not influence each other.

**Warning:** Even though `clone` is rarely used in user code, it is called pervasively throughout scikit-learn codebase: in particular, most meta-estimators that accept non-fitted estimators call `clone` internally (`GridSearchCV`, `StackingClassifier`, `CalibratedClassifierCV`, etc.).

### CV splitters

When passed a `RandomState` instance, CV splitters yield different splits each time `split` is called. When comparing different estimators, this can lead to overestimating the variance of the difference in performance between the estimators:

```python
>>> from sklearn.naive_bayes import GaussianNB
>>> from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
>>> from sklearn.datasets import make_classification
>>> from sklearn.model_selection import KFold, cross_val_score
>>> import numpy as np
```

(continues on next page)
Directly comparing the performance of the `LinearDiscriminantAnalysis` estimator vs the `GaussianNB` estimator on each fold would be a mistake: the splits on which the estimators are evaluated are different. Indeed, `cross_val_score` will internally call `cv.split` on the same `KFold` instance, but the splits will be different each time. This is also true for any tool that performs model selection via cross-validation, e.g. `GridSearchCV` and `RandomizedSearchCV`: scores are not comparable fold-to-fold across different calls to `search.fit`, since `cv.split` would have been called multiple times. Within a single call to `search.fit`, however, fold-to-fold comparison is possible since the search estimator only calls `cv.split` once.

For comparable fold-to-fold results in all scenarios, one should pass an integer to the CV splitter: `cv = KFold(shuffle=True, random_state=0)`.

**Note:** While fold-to-fold comparison is not advisable with `RandomState` instances, one can however expect that average scores allow to conclude whether one estimator is better than another, as long as enough folds and data are used.

**Note:** What matters in this example is what was passed to `KFold`. Whether we pass a `RandomState` instance or an integer to `make_classification` is not relevant for our illustration purpose. Also, neither `LinearDiscriminantAnalysis` nor `GaussianNB` are randomized estimators.

### General recommendations

#### Getting reproducible results across multiple executions

In order to obtain reproducible (i.e. constant) results across multiple program executions, we need to remove all uses of `random_state=None`, which is the default. The recommended way is to declare a `rng` variable at the top of the program, and pass it down to any object that accepts a `random_state` parameter:
We are now guaranteed that the result of this script will always be 0.84, no matter how many times we run it. Changing the global `rng` variable to a different value should affect the results, as expected.

It is also possible to declare the `rng` variable as an integer. This may however lead to less robust cross-validation results, as we will see in the next section.

**Note:** We do not recommend setting the global `numpy` seed by calling `np.random.seed(0)`. See here for a discussion.

### Robustness of cross-validation results

When we evaluate a randomized estimator performance by cross-validation, we want to make sure that the estimator can yield accurate predictions for new data, but we also want to make sure that the estimator is robust w.r.t. its random initialization. For example, we would like the random weights initialization of a `SGDClassifier` to be consistently good across all folds: otherwise, when we train that estimator on new data, we might get unlucky and the random initialization may lead to bad performance. Similarly, we want a random forest to be robust w.r.t. the set of randomly selected features that each tree will be using.

For these reasons, it is preferable to evaluate the cross-validation performance by letting the estimator use a different RNG on each fold. This is done by passing a `RandomState` instance (or `None`) to the estimator initialization.

When we pass an integer, the estimator will use the same RNG on each fold: if if the estimator performs well (or bad), as evaluated by CV, it might just be because we got lucky (or unlucky) with that specific seed. Passing instances leads to more robust CV results, and makes the comparison between various algorithms fairer. It also helps limiting the temptation to treat the estimator’s RNG as a hyper-parameter that can be tuned.

Whether we pass `RandomState` instances or integers to CV splitters has no impact on robustness, as long as `split` is only called once. When `split` is called multiple times, fold-to-fold comparison isn’t possible anymore. As a result, passing integer to CV splitters is usually safer and covers most use-cases.
GLOSSARY OF COMMON TERMS AND API ELEMENTS

This glossary hopes to definitively represent the tacit and explicit conventions applied in Scikit-learn and its API, while providing a reference for users and contributors. It aims to describe the concepts and either detail their corresponding API or link to other relevant parts of the documentation which do so. By linking to glossary entries from the API Reference and User Guide, we may minimize redundancy and inconsistency.

We begin by listing general concepts (and any that didn’t fit elsewhere), but more specific sets of related terms are listed below: Class APIs and Estimator Types, Target Types, Methods, Parameters, Attributes, Data and sample properties.

5.1 General Concepts

1d

1d array One-dimensional array. A NumPy array whose .shape has length 1. A vector.

2d

2d array Two-dimensional array. A NumPy array whose .shape has length 2. Often represents a matrix.

API Refers to both the specific interfaces for estimators implemented in Scikit-learn and the generalized conventions across types of estimators as described in this glossary and overviewed in the contributor documentation. The specific interfaces that constitute Scikit-learn’s public API are largely documented in API Reference. However, we less formally consider anything as public API if none of the identifiers required to access it begins with _. We generally try to maintain backwards compatibility for all objects in the public API.

Private API, including functions, modules and methods beginning _ are not assured to be stable.

array-like The most common data format for input to Scikit-learn estimators and functions, array-like is any type object for which numpy.asarray will produce an array of appropriate shape (usually 1 or 2-dimensional) of appropriate dtype (usually numeric).

This includes:

• a numpy array
• a list of numbers
• a list of length-k lists of numbers for some fixed length k
• a pandas.DataFrame with all columns numeric
• a numeric pandas.Series

It excludes:

• a sparse matrix
• an iterator
• a generator

Note that output from scikit-learn estimators and functions (e.g. predictions) should generally be arrays or sparse matrices, or lists thereof (as in multi-output tree.DecisionTreeClassifier’s predict_proba). An estimator where predict() returns a list or a pandas.Series is not valid.

attribute

attributes We mostly use attribute to refer to how model information is stored on an estimator during fitting. Any public attribute stored on an estimator instance is required to begin with an alphabetic character and end in a single underscore if it is set in fit or partial_fit. These are what is documented under an estimator’s Attributes documentation. The information stored in attributes is usually either: sufficient statistics used for prediction or transformation; transductive outputs such as labels_ or embedding_; or diagnostic data, such as feature_importances_. Common attributes are listed below.

A public attribute may have the same name as a constructor parameter, with a _ appended. This is used to store a validated or estimated version of the user’s input. For example, decomposition.PCA is constructed with an n_components parameter. From this, together with other parameters and the data, PCA estimates the attribute n_components_.

Further private attributes used in prediction/transformation/etc. may also be set when fitting. These begin with a single underscore and are not assured to be stable for public access.

A public attribute on an estimator instance that does not end in an underscore should be the stored, unmodified value of an __init__ parameter of the same name. Because of this equivalence, these are documented under an estimator’s Parameters documentation.

backwards compatibility We generally try to maintain backward compatibility (i.e. interfaces and behaviors may be extended but not changed or removed) from release to release but this comes with some exceptions:

Public API only The behavior of objects accessed through private identifiers (those beginning _) may be changed arbitrarily between versions.

As documented We will generally assume that the users have adhered to the documented parameter types and ranges. If the documentation asks for a list and the user gives a tuple, we do not assure consistent behavior from version to version.

Deprecation Behaviors may change following a deprecation period (usually two releases long). Warnings are issued using Python’s warnings module.

Keyword arguments We may sometimes assume that all optional parameters (other than X and y to fit and similar methods) are passed as keyword arguments only and may be positionally reordered.

Bug fixes and enhancements Bug fixes and – less often – enhancements may change the behavior of estimators, including the predictions of an estimator trained on the same data and random_state. When this happens, we attempt to note it clearly in the changelog.

Serialization We make no assurances that pickling an estimator in one version will allow it to be unpickled to an equivalent model in the subsequent version. (For estimators in the sklearn package, we issue a warning when this unpickling is attempted, even if it may happen to work.) See Security & maintainability limitations.

utils.estimator_checks.check_estimator We provide limited backwards compatibility assurances for the estimator checks: we may add extra requirements on estimators tested with this function, usually when these were informally assumed but not formally tested.

Despite this informal contract with our users, the software is provided as is, as stated in the license. When a release inadvertently introduces changes that are not backward compatible, these are known as software regressions.

callable A function, class or an object which implements the __call__ method; anything that returns True when the argument of callable().
categorical feature  A categorical or nominal feature is one that has a finite set of discrete values across the population of data. These are commonly represented as columns of integers or strings. Strings will be rejected by most scikit-learn estimators, and integers will be treated as ordinal or count-valued. For the use with most estimators, categorical variables should be one-hot encoded. Notable exceptions include tree-based models such as random forests and gradient boosting models that often work better and faster with integer-coded categorical variables. OrdinalEncoder helps encoding string-valued categorical features as ordinal integers, and OneHotEncoder can be used to one-hot encode categorical features. See also Encoding categorical features and the categorical-encoding package for tools related to encoding categorical features.

clone

cloned  To copy an estimator instance and create a new one with identical parameters, but without any fitted attributes, using clone.

When fit is called, a meta-estimator usually clones a wrapped estimator instance before fitting the cloned instance. (Exceptions, for legacy reasons, include Pipeline and FeatureUnion.)

If the estimator’s random_state parameter is an integer (or if the estimator doesn’t have a random_state parameter), an exact clone is returned: the clone and the original estimator will give the exact same results. Otherwise, statistical clone is returned: the clone might yield different results from the original estimator. More details can be found in Controlling randomness.

common tests This refers to the tests run on almost every estimator class in Scikit-learn to check they comply with basic API conventions. They are available for external use through utils.estimator_checks.check_estimator, with most of the implementation in sklearn/utils/estimator_checks.py.

Note: Some exceptions to the common testing regime are currently hard-coded into the library, but we hope to replace this by marking exceptional behaviours on the estimator using semantic estimator tags.

deprecation  We use deprecation to slowly violate our backwards compatibility assurances, usually to to:

- change the default value of a parameter; or
- remove a parameter, attribute, method, class, etc.

We will ordinarily issue a warning when a deprecated element is used, although there may be limitations to this. For instance, we will raise a warning when someone sets a parameter that has been deprecated, but may not when they access that parameter’s attribute on the estimator instance.

See the Contributors’ Guide.

dimensionality  May be used to refer to the number of features (i.e. n_features), or columns in a 2d feature matrix. Dimensions are, however, also used to refer to the length of a NumPy array’s shape, distinguishing a 1d array from a 2d matrix.

docstring  The embedded documentation for a module, class, function, etc., usually in code as a string at the beginning of the object’s definition, and accessible as the object’s __doc__ attribute.

We try to adhere to PEP257, and follow NumpyDoc conventions.

double underscore  When specifying parameter names for nested estimators, __ may be used to separate between parent and child in some contexts. The most common use is when setting parameters through a meta-estimator with set_params and hence in specifying a search grid in parameter search. See parameter. It is also used in pipeline.Pipeline.fit for passing sample properties to the fit methods of estimators in the pipeline.

dtype  NumPy arrays assume a homogeneous data type throughout, available in the .dtype attribute of an array (or sparse matrix). We generally assume simple data types for scikit-learn data: float or integer. We may support
object or string data types for arrays before encoding or vectorizing. Our estimators do not work with struct arrays, for instance.

TODO: Mention efficiency and precision issues; casting policy.

**duck typing** We try to apply duck typing to determine how to handle some input values (e.g. checking whether a given estimator is a classifier). That is, we avoid using `isinstance` where possible, and rely on the presence or absence of attributes to determine an object’s behaviour. Some nuance is required when following this approach:

- For some estimators, an attribute may only be available once it is fitted. For instance, we cannot a priori determine if `predict_proba` is available in a grid search where the grid includes alternating between a probabilistic and a non-probabilistic predictor in the final step of the pipeline. In the following, we can only determine if `clf` is probabilistic after fitting it on some data:

  ```python
  >>> from sklearn.model_selection import GridSearchCV
  >>> from sklearn.linear_model import SGDClassifier
  >>> clf = GridSearchCV(SGDClassifier(),
      ...                      param_grid={'loss': ['log', 'hinge']})
  ```

  This means that we can only check for duck-typed attributes after fitting, and that we must be careful to make meta-estimators only present attributes according to the state of the underlying estimator after fitting.

- Checking if an attribute is present (using `hasattr`) is in general just as expensive as getting the attribute (getattr or dot notation). In some cases, getting the attribute may indeed be expensive (e.g. for some implementations of `feature_importances_`, which may suggest this is an API design flaw). So code which does `hasattr` followed by `getattr` should be avoided; `getattr` within a try-except block is preferred.

- For determining some aspects of an estimator’s expectations or support for some feature, we use estimator tags instead of duck typing.

**early stopping** This consists in stopping an iterative optimization method before the convergence of the training loss, to avoid over-fitting. This is generally done by monitoring the generalization score on a validation set. When available, it is activated through the parameter `early_stopping` or by setting a positive `n_iter_no_change`.

**estimator instance** We sometimes use this terminology to distinguish an estimator class from a constructed instance. For example, in the following, `cls` is an estimator class, while `est1` and `est2` are instances:

```python
cls = RandomForestClassifier
est1 = cls()
est2 = RandomForestClassifier()
```

**examples** We try to give examples of basic usage for most functions and classes in the API:

- as doctests in their docstrings (i.e. within the sklearn/ library code itself).
- as examples in the example gallery rendered (using sphinx-gallery) from scripts in the examples/ directory, exemplifying key features or parameters of the estimator/function. These should also be referenced from the User Guide.
- sometimes in the User Guide (built from doc/) alongside a technical description of the estimator.

**experimental** An experimental tool is already usable but its public API, such as default parameter values or fitted attributes, is still subject to change in future versions without the usual deprecation warning policy.

**evaluation metric**

**evaluation metrics** Evaluation metrics give a measure of how well a model performs. We may use this term specifically to refer to the functions in metrics (disregarding metrics.pairwise), as distinct from the score method and the scoring API used in cross validation. See Metrics and scoring: quantifying the quality of predictions.
These functions usually accept a ground truth (or the raw data where the metric evaluates clustering without a ground truth) and a prediction, be it the output of `predict (y_pred)`, of `predict_proba (y_proba)`, or of an arbitrary score function including `decision_function (y_score)`. Functions are usually named to end with `_score` if a greater score indicates a better model, and `_loss` if a lesser score indicates a better model. This diversity of interface motivates the scoring API.

Note that some estimators can calculate metrics that are not included in `metrics` and are estimator-specific, notably model likelihoods.

**estimator tags** A proposed feature (e.g. #8022) by which the capabilities of an estimator are described through a set of semantic tags. This would enable some runtime behaviors based on estimator inspection, but it also allows each estimator to be tested for appropriate invariances while being excepted from other common tests.

Some aspects of estimator tags are currently determined through the duck typing of methods like `predict_proba` and through some special attributes on estimator objects:

- `_estimator_type` This string-valued attribute identifies an estimator as being a classifier, regressor, etc. It is set by mixins such as `base.ClassifierMixin`, but needs to be more explicitly adopted on a meta-estimator. Its value should usually be checked by way of a helper such as `base.is_classifier`.

- `_pairwise` This boolean attribute indicates whether the data (X) passed to `fit` and similar methods consists of pairwise measures over samples rather than a feature representation for each sample. It is usually `True` where an estimator has a `metric` or `affinity` or `kernel` parameter with value `precomputed`. Its primary purpose is that when a meta-estimator extracts a sub-sample of data intended for a pairwise estimator, the data needs to be indexed on both axes, while other data is indexed only on the first axis.

  Deprecated since version 0.24: The `_pairwise` attribute is deprecated in 0.24. From 1.1 (renaming of 0.26) onward, the `pairwise` estimator tag should be used instead.

For more detailed info, see [Estimator Tags](#estimator_tags).

**feature**

**features**

**feature vector** In the abstract, a feature is a function (in its mathematical sense) mapping a sampled object to a numeric or categorical quantity. “Feature” is also commonly used to refer to these quantities, being the individual elements of a vector representing a sample. In a data matrix, features are represented as columns: each column contains the result of applying a feature function to a set of samples.

Elsewhere features are known as attributes, predictors, regressors, or independent variables.

Nearly all estimators in scikit-learn assume that features are numeric, finite and not missing, even when they have semantically distinct domains and distributions (categorical, ordinal, count-valued, real-valued, interval).

See also [categorical feature](#categorical_feature) and [missing values](#missing_values).

**n_features** indicates the number of features in a dataset.

**fitting** Calling `fit` (or `fit_transform`, `fit_predict`, etc.) on an estimator.

**fitted** The state of an estimator after `fitting`.

There is no conventional procedure for checking if an estimator is fitted. However, an estimator that is not fitted:

- should raise `exceptions.NotFittedError` when a prediction method (`predict`, `transform`, etc.) is called. (`utils.validation.check_is_fitted` is used internally for this purpose.)

- should not have any attributes beginning with an alphabetic character and ending with an underscore. (Note that a descriptor for the attribute may still be present on the class, but `hasattr` should return False)

**function** We provide ad hoc function interfaces for many algorithms, while estimator classes provide a more consistent interface.
In particular, Scikit-learn may provide a function interface that fits a model to some data and returns the learnt model parameters, as in `linear_model.enet_path`. For transductive models, this also returns the embedding or cluster labels, as in `manifold.spectral_embedding` or `cluster.dbscan`. Many preprocessing transformers also provide a function interface, akin to calling `fit_transform`, as in `preprocessing.maxabs_scale`. Users should be careful to avoid data leakage when making use of these `fit_transform` equivalent functions.

We do not have a strict policy about when to or when not to provide function forms of estimators, but maintainers should consider consistency with existing interfaces, and whether providing a function would lead users astray from best practices (as regards data leakage, etc.)

gallery See examples.

hyperparameter

hyper-parameter See parameter.

impute

imputation Most machine learning algorithms require that their inputs have no missing values, and will not work if this requirement is violated. Algorithms that attempt to fill in (or impute) missing values are referred to as imputation algorithms.

indexable An array-like, sparse matrix, pandas DataFrame or sequence (usually a list).

induction

inductive Inductive (contrasted with transductive) machine learning builds a model of some data that can then be applied to new instances. Most estimators in Scikit-learn are inductive, having `predict` and/or `transform` methods.

joblib A Python library (https://joblib.readthedocs.io) used in Scikit-learn to facilitate simple parallelism and caching. Joblib is oriented towards efficiently working with numpy arrays, such as through use of memory mapping. See Parallelism for more information.

label indicator matrix

multilabel indicator matrix

multilabel indicator matrices The format used to represent multilabel data, where each row of a 2d array or sparse matrix corresponds to a sample, each column corresponds to a class, and each element is 1 if the sample is labeled with the class and 0 if not.

leakage

data leakage A problem in cross validation where generalization performance can be over-estimated since knowledge of the test data was inadvertently included in training a model. This is a risk, for instance, when applying a transformer to the entirety of a dataset rather than each training portion in a cross validation split.

We aim to provide interfaces (such as pipeline and model_selection) that shield the user from data leakage.

memmapping

memory map

memory mapping A memory efficiency strategy that keeps data on disk rather than copying it into main memory. Memory maps can be created for arrays that can be read, written, or both, using numpy.memmap. When using joblib to parallelize operations in Scikit-learn, it may automatically memmap large arrays to reduce memory duplication overhead in multiprocessing.

missing values Most Scikit-learn estimators do not work with missing values. When they do (e.g. in impute.SimpleImputer), NaN is the preferred representation of missing values in float arrays. If the array has integer dtype, NaN cannot be represented. For this reason, we support specifying another missing_values
value when imputation or learning can be performed in integer space. Unlabeled data is a special case of missing values in the target.

**n_features**  The number of features.

**n_outputs**  The number of outputs in the target.

**n_samples**  The number of samples.

**n_targets**  Synonym for n_outputs.

**narrative docs**

**narrative documentation**  An alias for User Guide, i.e. documentation written in doc/modules/. Unlike the API reference provided through docstrings, the User Guide aims to:

- group tools provided by Scikit-learn together thematically or in terms of usage;
- motivate why someone would use each particular tool, often through comparison;
- provide both intuitive and technical descriptions of tools;
- provide or link to examples of using key features of a tool.

**np**  A shorthand for Numpy due to the conventional import statement:

```python
import numpy as np
```

**online learning**  Where a model is iteratively updated by receiving each batch of ground truth targets soon after making predictions on corresponding batch of data. Intrinsically, the model must be usable for prediction after each batch. See partial_fit.

**out-of-core**  An efficiency strategy where not all the data is stored in main memory at once, usually by performing learning on batches of data. See partial_fit.

**outputs**  Individual scalar/categorical variables per sample in the target. For example, in multilabel classification each possible label corresponds to a binary output. Also called responses, tasks or targets. See multiclass multioutput and continuous multioutput.

**pair**  A tuple of length two.

**parameter**

**parameters**

**param**

**params**  We mostly use parameter to refer to the aspects of an estimator that can be specified in its construction. For example, max_depth and random_state are parameters of RandomForestClassifier. Parameters to an estimator’s constructor are stored unmodified as attributes on the estimator instance, and conventionally start with an alphabetic character and end with an alphanumeric character. Each estimator’s constructor parameters are described in the estimator’s docstring.

We do not use parameters in the statistical sense, where parameters are values that specify a model and can be estimated from data. What we call parameters might be what statisticians call hyperparameters to the model: aspects for configuring model structure that are often not directly learnt from data. However, our parameters are also used to prescribe modeling operations that do not affect the learnt model, such as n_jobs for controlling parallelism.

When talking about the parameters of a meta-estimator, we may also be including the parameters of the estimators wrapped by the meta-estimator. Ordinarily, these nested parameters are denoted by using a double underscore (__) to separate between the estimator-as-parameter and its parameter. Thus clf = BaggingClassifier(base_estimator=DecisionTreeClassifier(max_depth=3)) has
a deep parameter `base_estimator__max_depth` with value 3, which is accessible with `clf.
base_estimator.max_depth` or `clf.get_params() ['base_estimator__max_depth']`.

The list of parameters and their current values can be retrieved from an estimator instance using its `get_params` method.

Between construction and fitting, parameters may be modified using `set_params`. To enable this, parameters are not ordinarily validated or altered when the estimator is constructed, or when each parameter is set. Parameter validation is performed when `fit` is called.

Common parameters are listed below.

**pairwise metric**

**pairwise metrics** In its broad sense, a pairwise metric defines a function for measuring similarity or dissimilarity between two samples (with each ordinarily represented as a feature vector). We particularly provide implementations of distance metrics (as well as improper metrics like Cosine Distance) through `metrics.pairwise_distances`, and of kernel functions (a constrained class of similarity functions) in `metrics.pairwise_kernels`. These can compute pairwise distance matrices that are symmetric and hence store data redundantly.

See also `precomputed` and `metric`.

Note that for most distance metrics, we rely on implementations from `scipy.spatial.distance`, but may reimplement for efficiency in our context. The `neighbors` module also duplicates some metric implementations for integration with efficient binary tree search data structures.

**pd** A shorthand for Pandas due to the conventional import statement:

```python
import pandas as pd
```

**precomputed** Where algorithms rely on pairwise metrics, and can be computed from pairwise metrics alone, we often allow the user to specify that the `X` provided is already in the pairwise (dis)similarity space, rather than in a feature space. That is, when passed to `fit`, it is a square, symmetric matrix, with each vector indicating (dis)similarity to every sample, and when passed to prediction/transformation methods, each row corresponds to a testing sample and each column to a training sample.

Use of precomputed `X` is usually indicated by setting a metric, affinity or kernel parameter to the string ‘precomputed’. If this is the case, then the estimator should set the pairwise estimator tag as True.

**rectangular** Data that can be represented as a matrix with `samples` on the first axis and a fixed, finite set of `features` on the second is called rectangular.

This term excludes samples with non-vectorial structures, such as text, an image of arbitrary size, a time series of arbitrary length, a set of vectors, etc. The purpose of a vectorizer is to produce rectangular forms of such data.

**sample**

**samples** We usually use this term as a noun to indicate a single feature vector. Elsewhere a sample is called an instance, data point, or observation. `n_samples` indicates the number of samples in a dataset, being the number of rows in a data array `X`.

**sample property**

**sample properties** A sample property is data for each sample (e.g. an array of length `n_samples`) passed to an estimator method or a similar function, alongside but distinct from the `features (X)` and `target (y)`. The most prominent example is `sample_weight`; see others at Data and sample properties.

As of version 0.19 we do not have a consistent approach to handling sample properties and their routing in meta-estimators, though a `fit_params` parameter is often used.
**scikit-learn-contrib** A venue for publishing Scikit-learn-compatible libraries that are broadly authorized by the core developers and the contrib community, but not maintained by the core developer team. See https://scikit-learn-contrib.github.io.

**scikit-learn enhancement proposals**

**SLEPs** Changes to the API principles and changes to dependencies or supported versions happen via a SLEP and follows the decision-making process outlined in Scikit-learn governance and decision-making. For all votes, a proposal must have been made public and discussed before the vote. Such a proposal must be a consolidated document, in the form of a ‘Scikit-Learn Enhancement Proposal’ (SLEP), rather than a long discussion on an issue. A SLEP must be submitted as a pull-request to enhancement proposals using the SLEP template.

**semi-supervised**

**semisupervised learning**

Learning where the expected prediction (label or ground truth) is only available for some samples provided as training data when fitting the model. We conventionally apply the label $-1$ to unlabeled samples in semi-supervised classification.

**sparse matrix**

**sparse graph** A representation of two-dimensional numeric data that is more memory efficient the corresponding dense numpy array where almost all elements are zero. We use the scipy.sparse framework, which provides several underlying sparse data representations, or formats. Some formats are more efficient than others for particular tasks, and when a particular format provides especial benefit, we try to document this fact in Scikit-learn parameter descriptions.

Some sparse matrix formats (notably CSR, CSC, COO and LIL) distinguish between implicit and explicit zeros. Explicit zeros are stored (i.e. they consume memory in a data array) in the data structure, while implicit zeros correspond to every element not otherwise defined in implicit storage.

Two semantics for sparse matrices are used in Scikit-learn:

**matrix semantics** The sparse matrix is interpreted as an array with implicit and explicit zeros being interpreted as the number 0. This is the interpretation most often adopted, e.g. when sparse matrices are used for feature matrices or multilabel indicator matrices.

**graph semantics** As with scipy.sparse.csgraph, explicit zeros are interpreted as the number 0, but implicit zeros indicate a masked or absent value, such as the absence of an edge between two vertices of a graph, where an explicit value indicates an edge’s weight. This interpretation is adopted to represent connectivity in clustering, in representations of nearest neighborhoods (e.g. neighbors.kneighbors_graph), and for precomputed distance representation where only distances in the neighborhood of each point are required.

When working with sparse matrices, we assume that it is sparse for a good reason, and avoid writing code that densifies a user-provided sparse matrix, instead maintaining sparsity or raising an error if not possible (i.e. if an estimator does not / cannot support sparse matrices).

**supervised**

**supervised learning** Learning where the expected prediction (label or ground truth) is available for each sample when fitting the model, provided as $y$. This is the approach taken in a classifier or regressor among other estimators.

**target**

**targets** The dependent variable in supervised (and semisupervised) learning, passed as $y$ to an estimator’s fit method. Also known as dependent variable, outcome variable, response variable, ground truth or label. Scikit-learn works with targets that have minimal structure: a class from a finite set, a finite real-valued number, multiple classes, or multiple numbers. See Target Types.
transduction

transductive A transductive (contrasted with inductive) machine learning method is designed to model a specific dataset, but not to apply that model to unseen data. Examples include manifold.TSNE, cluster.AgglomerativeClustering and neighbors.LocalOutlierFactor.

unlabeled

unlabeled data Samples with an unknown ground truth when fitting; equivalently, missing values in the target. See also semisupervised and unsupervised learning.

unsupervised

unsupervised learning Learning where the expected prediction (label or ground truth) is not available for each sample when fitting the model, as in clusterers and outlier detectors. Unsupervised estimators ignore any y passed to fit.

5.2 Class APIs and Estimator Types

classifier

classifiers A supervised (or semi-supervised) predictor with a finite set of discrete possible output values.

A classifier supports modeling some of binary, multiclass, multilabel, or multiclass multioutput targets. Within scikit-learn, all classifiers support multi-class classification, defaulting to using a one-vs-rest strategy over the binary classification problem.

Classifiers must store a classes_ attribute after fitting, and usually inherit from base.ClassifierMixin, which sets their _estimator_type attribute.

A classifier can be distinguished from other estimators with is_classifier.

A classifier must implement:

• fit
• predict
• score

It may also be appropriate to implement decision_function, predict_proba and predict_log_proba.

clusterer

clusterers A unsupervised predictor with a finite set of discrete output values.

A clusterer usually stores labels_ after fitting, and must do so if it is transductive.

A clusterer must implement:

• fit
• fit_predict if transductive
• predict if inductive

density estimator TODO

estimator

estimators An object which manages the estimation and decoding of a model. The model is estimated as a deterministic function of:

• parameters provided in object construction or with set_params;
• the global `numpy.random` random state if the estimator’s `random_state` parameter is set to None; and
• any data or sample properties passed to the most recent call to `fit`, `fit_transform` or `fit_predict`, or data similarly passed in a sequence of calls to `partial_fit`.

The estimated model is stored in public and private attributes on the estimator instance, facilitating decoding through prediction and transformation methods.

Estimators must provide a `fit` method, and should provide `set_params` and `get_params`, although these are usually provided by inheritance from `base.BaseEstimator`.

The core functionality of some estimators may also be available as a function.

**feature extractor**

**feature extractors** A transformer which takes input where each sample is not represented as an `array-like` object of fixed length, and produces an `array-like` object of features for each sample (and thus a 2-dimensional array-like for a set of samples). In other words, it (lossily) maps a non-rectangular data representation into rectangular data.

Feature extractors must implement at least:

• `fit`
• `transform`
• `get_feature_names`

**meta-estimator**

**meta-estimators**

**metaestimater**

**metaestimators** An estimator which takes another estimator as a parameter. Examples include `pipeline.Pipeline`, `model_selection.GridSearchCV`, `feature_selection.SelectFromModel` and `ensemble.BaggingClassifier`.

In a meta-estimator’s `fit` method, any contained estimators should be cloned before they are fit (although FIXME: Pipeline and FeatureUnion do not do this currently). An exception to this is that an estimator may explicitly document that it accepts a pre-fitted estimator (e.g. using `prefit=True` in `feature_selection.SelectFromModel`). One known issue with this is that the pre-fitted estimator will lose its model if the meta-estimator is cloned. A meta-estimator should have `fit` called before prediction, even if all contained estimators are pre-fitted.

In cases where a meta-estimator’s primary behaviors (e.g. `predict` or `transform` implementation) are functions of prediction/transformation methods of the provided base estimator (or multiple base estimators), a meta-estimator should provide at least the standard methods provided by the base estimator. It may not be possible to identify which methods are provided by the underlying estimator until the meta-estimator has been fitted (see also duck typing), for which `utils.metaestimators.if_delegate_has_method` may help. It should also provide (or modify) the estimator tags and classes_ attribute provided by the base estimator.

Meta-estimators should be careful to validate data as minimally as possible before passing it to an underlying estimator. This saves computation time, and may, for instance, allow the underlying estimator to easily work with data that is not rectangular.

**outlier detector**

**outlier detectors** An unsupervised binary predictor which models the distinction between core and outlying samples.

Outlier detectors must implement:

• `fit`
• `fit_predict` if transductive
• **predict** if *inductive*

Inductive outlier detectors may also implement `decision_function` to give a normalized inlier score where outliers have score below 0. `score_samples` may provide an unnormalized score per sample.

**predictor**

**predictors** An *estimator* supporting `predict` and/or `fit_predict`. This encompasses *classifier*, *regressor*, *outlier detector* and *clusterer*.

In statistics, “predictors” refers to *features*.

**regressor**

**regressors** A *supervised* (or *semi-supervised*) *predictor* with *continuous* output values.

  Regressors usually inherit from `base.RegressorMixin`, which sets their `_estimator_type` attribute.

  A regressor can be distinguished from other estimators with `is_regressor`.

  A regressor must implement:

  • `fit`
  • `predict`
  • `score`

**transformer**

**transformers** An *estimator* supporting `transform` and/or `fit_transform`. A purely *transductive* transformer, such as `manifold.TSNE`, may not implement `transform`.

**vectorizer**

**vectorizers** See *feature extractor*.

There are further APIs specifically related to a small family of estimators, such as:

**cross-validation splitter**

**CV splitter**

**cross-validation generator** A non-estimator family of classes used to split a dataset into a sequence of train and test portions (see *Cross-validation: evaluating estimator performance*), by providing `split` and `get_n_splits` methods. Note that unlike estimators, these do not have `fit` methods and do not provide `set_params` or `get_params`. Parameter validation may be performed in `__init__`.

**cross-validation estimator** An estimator that has built-in cross-validation capabilities to automatically select the best hyper-parameters (see the *User Guide*). Some example of cross-validation estimators are `ElasticNetCV` and `LogisticRegressionCV`. Cross-validation estimators are named `EstimatorCV` and tend to be roughly equivalent to `GridSearchCV(Estimator(), ...)`. The advantage of using a cross-validation estimator over the canonical `estimator` class along with `grid search` is that they can take advantage of warm-starting by reusing precomputed results in the previous steps of the cross-validation process. This generally leads to speed improvements. An exception is the `RidgeCV` class, which can instead perform efficient Leave-One-Out CV.

**scorer** A non-estimator callable object which evaluates an estimator on given test data, returning a number. Unlike *evaluation metrics*, a greater returned number must correspond with a *better* score. See *The scoring parameter: defining model evaluation rules*.

Further examples:

• `neighbors.DistanceMetric`

• `gaussian_process.kernels.Kernel`

• `tree.Criterion`
5.3 Target Types

**binary** A classification problem consisting of two classes. A binary target may be represented as for a *multiclass* problem but with only two labels. A binary decision function is represented as a 1d array.

Semantically, one class is often considered the “positive” class. Unless otherwise specified (e.g. using `pos_label` in `evaluation metrics`), we consider the class label with the greater value (numerically or lexicographically) as the positive class: of labels [0, 1], 1 is the positive class; of [1, 2], 2 is the positive class; of [‘no’, ‘yes’], ‘yes’ is the positive class; of [‘no’, ‘YES’], ‘no’ is the positive class. This affects the output of `decision_function`, for instance.

Note that a dataset sampled from a multiclass `y` or a continuous `y` may appear to be binary.

`type_of_target` will return ‘binary’ for binary input, or a similar array with only a single class present.

**continuous** A regression problem where each sample’s target is a finite floating point number represented as a 1-dimensional array of floats (or sometimes ints).

`type_of_target` will return ‘continuous’ for continuous input, but if the data is all integers, it will be identified as ‘multiclass’.

**continuous multioutput**

**multioutput continuous** A regression problem where each sample’s target consists of `n_outputs` outputs, each one a finite floating point number, for a fixed int `n_outputs > 1` in a particular dataset.

Continuous multioutput targets are represented as multiple `continuous` targets, horizontally stacked into an array of shape `(n_samples, n_outputs)`.

`type_of_target` will return ‘continuous-multioutput’ for continuous multioutput input, but if the data is all integers, it will be identified as ‘multiclass-multioutput’.

**multiclass**

**multi-class** A classification problem consisting of more than two classes. A multiclass target may be represented as a 1-dimensional array of strings or integers. A 2d column vector of integers (i.e. a single output in `multioutput` terms) is also accepted.

We do not officially support other orderable, hashable objects as class labels, even if estimators may happen to work when given classification targets of such type.

For semi-supervised classification, *unlabeled* samples should have the special label -1 in `y`.

Within scikit-learn, all estimators supporting binary classification also support multiclass classification, using One-vs-Rest by default.

A `preprocessing.LabelEncoder` helps to canonicalize multiclass targets as integers.

`type_of_target` will return ‘multiclass’ for multiclass input. The user may also want to handle ‘binary’ input identically to ‘multiclass’.

**multiclass multioutput**

**multi-class multi-output**

**multioutput multiclass**

**multi-output multi-class** A classification problem where each sample’s target consists of `n_outputs` outputs, each a class label, for a fixed int `n_outputs > 1` in a particular dataset. Each output has a fixed set of available
classes, and each sample is labeled with a class for each output. An output may be binary or multiclass, and in the case where all outputs are binary, the target is `multilabel`.

Multiclass multioutput targets are represented as multiple `multiclass` targets, horizontally stacked into an array of shape `(n_samples, n_outputs)`.

XXX: For simplicity, we may not always support string class labels for multiclass multioutput, and integer class labels should be used.

`multioutput` provides estimators which estimate multi-output problems using multiple single-output estimators. This may not fully account for dependencies among the different outputs, which methods natively handling the multioutput case (e.g. decision trees, nearest neighbors, neural networks) may do better.

`type_of_target` will return `multiclass-multioutput` for multiclass multioutput input.

**multilabel**

**multi-label** A `multiclass multioutput` target where each output is `binary`. This may be represented as a 2d (dense) array or sparse matrix of integers, such that each column is a separate binary target, where positive labels are indicated with 1 and negative labels are usually -1 or 0. Sparse multilabel targets are not supported everywhere that dense multilabel targets are supported.

Semantically, a multilabel target can be thought of as a set of labels for each sample. While not used internally, `preprocessing.MultiLabelBinarizer` is provided as a utility to convert from a list of sets representation to a 2d array or sparse matrix. One-hot encoding a multiclass target with `preprocessing.LabelBinarizer` turns it into a multilabel problem.

`type_of_target` will return `multilabel-indicator` for multilabel input, whether sparse or dense.

**multioutput**

**multi-output** A target where each sample has multiple classification/regression labels. See `multiclass multioutput` and `continuous multioutput`. We do not currently support modelling mixed classification and regression targets.

### 5.4 Methods

**decision function** In a fitted `classifier` or `outlier detector`, predicts a “soft” score for each sample in relation to each class, rather than the “hard” categorical prediction produced by `predict`. Its input is usually only some observed data, `X`.

If the estimator was not already `fitted`, calling this method should raise a `exceptions.NotFittedError`.

Output conventions:

**binary classification** A 1-dimensional array, where values strictly greater than zero indicate the positive class (i.e. the last class in `classes_`).

**multiclass classification** A 2-dimensional array, where the row-wise arg-maximum is the predicted class. Columns are ordered according to `classes_`.

**multilabel classification** Scikit-learn is inconsistent in its representation of multilabel decision functions. Some estimators represent it like multiclass multioutput, i.e. a list of 2d arrays, each with two columns. Others represent it with a single 2d array, whose columns correspond to the individual binary classification decisions. The latter representation is ambiguously identical to the multiclass classification format, though its semantics differ: it should be interpreted, like in the binary case, by thresholding at 0.

TODO: This gist highlights the use of the different formats for multilabel.

**multioutput classification** A list of 2d arrays, corresponding to each multiclass decision function.

**outlier detection** A 1-dimensional array, where a value greater than or equal to zero indicates an inlier.
**fit** The *fit* method is provided on every estimator. It usually takes some *samples* `X`, *targets* `y` if the model is supervised, and potentially other *sample properties* such as `sample_weight`. It should:

- clear any prior *attributes* stored on the estimator, unless `warm_start` is used;
- validate and interpret any *parameters*, ideally raising an error if invalid;
- validate the input data;
- estimate and store model attributes from the estimated parameters and provided data; and
- return the now *fitted* estimator to facilitate method chaining.

*Target Types* describes possible formats for `y`.

**fit_predict** Used especially for *unsupervised, transductive* estimators, this fits the model and returns the predictions (similar to `predict`) on the training data. In clusterers, these predictions are also stored in the `labels_` attribute, and the output of `.fit_predict(X)` is usually equivalent to `.fit(X).predict(X)`. The parameters to `fit_predict` are the same as those to `fit`.

**fit_transform** A method on *transformers* which fits the estimator and returns the transformed training data. It takes parameters as in `fit` and its output should have the same shape as calling `.fit(X, ...)`. `transform(X)`. There are nonetheless rare cases where `.fit_transform(X, ...) and .fit(X, ...) .transform(X)` do not return the same value, wherein training data needs to be handled differently (due to model blending in stacked ensembles, for instance; such cases should be clearly documented). *Transductive* transformers may also provide `fit_transform` but not `transform`.

One reason to implement `fit_transform` is that performing `fit` and `transform` separately would be less efficient than together. `base.TransformerMixin` provides a default implementation, providing a consistent interface across transformers where `fit_transform` is or is not specialized.

In *inductive* learning – where the goal is to learn a generalized model that can be applied to new data – users should be careful not to apply `fit_transform` to the entirety of a dataset (i.e. training and test data together) before further modelling, as this results in *data leakage*.

**get_feature_names** Primarily for *feature extractors*, but also used for other transformers to provide string names for each column in the output of the estimator’s `transform` method. It outputs a list of strings and may take a list of strings as input, corresponding to the names of input columns from which output column names can be generated. By default input features are named `x0, x1, ...`.

**get_n_splits** On a *CV splitter* (not an estimator), returns the number of elements one would get if iterating through the return value of `split` given the same parameters. Takes the same parameters as `split`.

**get_params** Gets all *parameters*, and their values, that can be set using `set_params`. A parameter `deep` can be used, when set to `False` to only return those parameters not including `__`, i.e. not due to indirection via contained estimators.

Most estimators adopt the definition from `base.BaseEstimator`, which simply adopts the parameters defined for `__init__`. `pipeline.Pipeline`, among others, reimplements `get_params` to declare the estimators named in its `steps` parameters as themselves being parameters.

**partial_fit** Facilitates fitting an estimator in an online fashion. Unlike `fit`, repeatedly calling `partial_fit` does not clear the model, but updates it with the data provided. The portion of data provided to `partial_fit` may be called a mini-batch. Each mini-batch must be of consistent shape, etc. In iterative estimators, `partial_fit` often only performs a single iteration.

`partial_fit` may also be used for *out-of-core* learning, although usually limited to the case where learning can be performed online, i.e. the model is usable after each `partial_fit` and there is no separate processing needed to finalize the model. `cluster.Birch` introduces the convention that calling `partial_fit(X)` will produce a model that is not finalized, but the model can be finalized by calling `partial_fit()` i.e. without passing a further mini-batch.
Generally, estimator parameters should not be modified between calls to `partial_fit`, although `partial_fit` should validate them as well as the new mini-batch of data. In contrast, `warm_start` is used to repeatedly fit the same estimator with the same data but varying parameters.

Like `fit`, `partial_fit` should return the estimator object.

To clear the model, a new estimator should be constructed, for instance with `base.clone`.

NOTE: Using `partial_fit` after `fit` results in undefined behavior.

**predict** Makes a prediction for each sample, usually only taking `X` as input (but see under regressor output conventions below). In a `classifier` or `regressor`, this prediction is in the same target space used in fitting (e.g. one of {‘red’, ‘amber’, ‘green’} if the `y` in fitting consisted of these strings). Despite this, even when `y` passed to `fit` is a list or other array-like, the output of `predict` should always be an array or sparse matrix. In a `clusterer` or `outlier detector` the prediction is an integer.

If the estimator was not already `fitted`, calling this method should raise a `exceptions.NotFittedError`.

Output conventions:

- **classifier** An array of shape `(n_samples,)` `(n_samples, n_outputs)`. `Multilabel` data may be represented as a sparse matrix if a sparse matrix was used in fitting. Each element should be one of the values in the classifier’s `classes_` attribute.

- **clusterer** An array of shape `(n_samples,)` where each value is from 0 to `n_clusters - 1` if the corresponding sample is clustered, and `-1` if the sample is not clustered, as in `cluster.dbscan`.

- **outlier detector** An array of shape `(n_samples,)` where each value is `-1` for an outlier and `1` otherwise.

- **regressor** A numeric array of shape `(n_samples,)`, usually float64. Some regressors have extra options in their `predict` method, allowing them to return standard deviation (`return_std=True`) or covariance (`return_cov=True`) relative to the predicted value. In this case, the return value is a tuple of arrays corresponding to `(prediction mean, std, cov)` as required.

**predict_log_proba** The natural logarithm of the output of `predict_proba`, provided to facilitate numerical stability.

**predict_proba** A method in `classifiers` and `clusterers` that can return probability estimates for each class/cluster. Its input is usually only some observed data, `X`.

If the estimator was not already `fitted`, calling this method should raise a `exceptions.NotFittedError`.

Output conventions are like those for `decision_function` except in the binary classification case, where one column is output for each class (while `decision_function` outputs a 1d array). For binary and multiclass predictions, each row should add to 1.

Like other methods, `predict_proba` should only be present when the estimator can make probabilistic predictions (see `duck typing`). This means that the presence of the method may depend on estimator parameters (e.g. in `linear_model.SGDClassifier`) or training data (e.g. in `model_selection.GridSearchCV`) and may only appear after fitting.

**score** A method on an estimator, usually a `predictor`, which evaluates its predictions on a given dataset, and returns a single numerical score. A greater return value should indicate better predictions; accuracy is used for classifiers and R^2 for regressors by default.

If the estimator was not already `fitted`, calling this method should raise a `exceptions.NotFittedError`.

Some estimators implement a custom, estimator-specific score function, often the likelihood of the data under the model.

**score_samples** TODO

If the estimator was not already `fitted`, calling this method should raise a `exceptions.NotFittedError`. 
set_params Available in any estimator, takes keyword arguments corresponding to keys in get_params. Each is provided a new value to assign such that calling get_params after set_params will reflect the changed parameters. Most estimators use the implementation in base.BaseEstimator, which handles nested parameters and otherwise sets the parameter as an attribute on the estimator. The method is overridden in pipeline, Pipeline and related estimators.

split On a CV splitter (not an estimator), this method accepts parameters \((X, y, groups)\), where all may be optional, and returns an iterator over \((\text{train\_idx, test\_idx})\) pairs. Each of \([\text{train,test}]\_\text{idx}\) is a 1d integer array, with values from 0 from \(X.\text{shape}[0] - 1\) of any length, such that no values appear in both some train_idx and its corresponding test_idx.

transform In a transformer, transforms the input, usually only \(X\), into some transformed space (conventionally notated as \(Xt\)). Output is an array or sparse matrix of length \(n\_samples\) and with the number of columns fixed after fitting.

If the estimator was not already fitted, calling this method should raise a exceptions.NotFittedError.

5.5 Parameters

These common parameter names, specifically used in estimator construction (see concept parameter), sometimes also appear as parameters of functions or non-estimator constructors.

class_weight Used to specify sample weights when fitting classifiers as a function of the target class. Where sample_weight is also supported and given, it is multiplied by the class_weight contribution. Similarly, where class_weight is used in a multioutput (including multilabel) tasks, the weights are multiplied across outputs (i.e. columns of y).

By default, all samples have equal weight such that classes are effectively weighted by their prevalence in the training data. This could be achieved explicitly with class_weight={label1: 1, label2: 1, ...} for all class labels.

More generally, class_weight is specified as a dict mapping class labels to weights \({\text{class\_label: weight}}\), such that each sample of the named class is given that weight.

class_weight='balanced' can be used to give all classes equal weight by giving each sample a weight inversely related to its class’s prevalence in the training data: \(n\_samples / (n\_classes * \text{np. bincount}(y))\). Class weights will be used differently depending on the algorithm: for linear models (such as linear SVM or logistic regression), the class weights will alter the loss function by weighting the loss of each sample by its class weight. For tree-based algorithms, the class weights will be used for reweighting the splitting criterion. Note however that this rebalancing does not take the weight of samples in each class into account.

For multioutput classification, a list of dicts is used to specify weights for each output. For example, for four-class multilabel classification weights should be \([\{0: 1, 1: 1\}, \{0: 1, 1: 5\}, \{0: 1, 1: 1\}, \{0: 1, 1: 1\}]\) instead of \([\{1:1\}, \{2:5\}, \{3:1\}, \{4:1\}]\).

The class_weight parameter is validated and interpreted with utils.compute_class_weight.

cv Determines a cross validation splitting strategy, as used in cross-validation based routines. cv is also available in estimators such as multioutput.ClassifierChain or calibration. CalibratedClassifierCV which use the predictions of one estimator as training data for another, to not overfit the training supervision.

Possible inputs for cv are usually:

- An integer, specifying the number of folds in K-fold cross validation. K-fold will be stratified over classes if the estimator is a classifier (determined by base.is_classifier) and the targets may represent a binary or multiclass (but not multioutput) classification problem (determined by utils.multiclass.type_of_target).
• A cross-validation splitter instance. Refer to the User Guide for splitters available within Scikit-learn.
• An iterable yielding train/test splits.

With some exceptions (especially where not using cross validation at all is an option), the default is 5-fold.

cv values are validated and interpreted with utils.check_cv.

kernel TODO

max_iter For estimators involving iterative optimization, this determines the maximum number of iterations to be performed in fit. If max_iter iterations are run without convergence, a exceptions. ConvergenceWarning should be raised. Note that the interpretation of “a single iteration” is inconsistent across estimators: some, but not all, use it to mean a single epoch (i.e. a pass over every sample in the data).

FIXME perhaps we should have some common tests about the relationship between ConvergenceWarning and max_iter.

memory Some estimators make use of joblib.Memory to store partial solutions during fitting. Thus when fit is called again, those partial solutions have been memoized and can be reused.

A memory parameter can be specified as a string with a path to a directory, or a joblib.Memory instance (or an object with a similar interface, i.e. a cache method) can be used.

memory values are validated and interpreted with utils.validation.check_memory.

metric As a parameter, this is the scheme for determining the distance between two data points. See metrics. pairwise_distances. In practice, for some algorithms, an improper distance metric (one that does not obey the triangle inequality, such as Cosine Distance) may be used.

XXX: hierarchical clustering uses affinity with this meaning.

We also use metric to refer to evaluation metrics, but avoid using this sense as a parameter name.

n_components The number of features which a transformer should transform the input into. See components_ for the special case of affine projection.

n_iter_no_change Number of iterations with no improvement to wait before stopping the iterative procedure.

This is also known as a patience parameter. It is typically used with early stopping to avoid stopping too early.

n_jobs This parameter is used to specify how many concurrent processes or threads should be used for routines that are parallelized with joblib.

n_jobs is an integer, specifying the maximum number of concurrently running workers. If 1 is given, no joblib parallelism is used at all, which is useful for debugging. If set to -1, all CPUs are used. For n_jobs below -1, (n_cpus + 1 + n_jobs) are used. For example with n_jobs=-2, all CPUs but one are used.

n_jobs is None by default, which means unset; it will generally be interpreted as n_jobs=1, unless the current joblib.Parallel backend context specifies otherwise.

For more details on the use of joblib and its interactions with scikit-learn, please refer to our parallelism notes.

pos_label Value with which positive labels must be encoded in binary classification problems in which the positive class is not assumed. This value is typically required to compute asymmetric evaluation metrics such as precision and recall.

random_state Whenever randomization is part of a Scikit-learn algorithm, a random_state parameter may be provided to control the random number generator used. Note that the mere presence of random_state doesn’t mean that randomization is always used, as it may be dependent on another parameter, e.g. shuffle, being set.

The passed value will have an effect on the reproducibility of the results returned by the function (fit, split, or any other function like k_means). random_state's value may be:
None (default) Use the global random state instance from `numpy.random`. Calling the function multiple times will reuse the same instance, and will produce different results.

An integer Use a new random number generator seeded by the given integer. Using an int will produce the same results across different calls. However, it may be worthwhile checking that your results are stable across a number of different distinct random seeds. Popular integer random seeds are 0 and 42.

A `numpy.random.RandomState` instance Use the provided random state, only affecting other users of that same random state instance. Calling the function multiple times will reuse the same instance, and will produce different results.

`utils.check_random_state` is used internally to validate the input `random_state` and return a `RandomState` instance.

For more details on how to control the randomness of scikit-learn objects and avoid common pitfalls, you may refer to Controlling randomness.

**scoring** Specifies the score function to be maximized (usually by cross validation), or – in some cases – multiple score functions to be reported. The score function can be a string accepted by `metrics.get_scorer` or a callable `scorer`, not to be confused with an evaluation metric, as the latter have a more diverse API. scoring may also be set to None, in which case the estimator’s `score` method is used. See The scoring parameter: defining model evaluation rules in the User Guide.

Where multiple metrics can be evaluated, `scoring` may be given either as a list of unique strings, a dictionary with names as keys and callables as values or a callable that returns a dictionary. Note that this does not specify which score function is to be maximized, and another parameter such as `refit` maybe used for this purpose.

The `scoring` parameter is validated and interpreted using `metrics.check_scoring`.

**verbose** Logging is not handled very consistently in Scikit-learn at present, but when it is provided as an option, the `verbose` parameter is usually available to choose no logging (set to False). Any True value should enable some logging, but larger integers (e.g. above 10) may be needed for full verbosity. Verbose logs are usually printed to Standard Output. Estimators should not produce any output on Standard Output with the default `verbose` setting.

**warm_start** When fitting an estimator repeatedly on the same dataset, but for multiple parameter values (such as to find the value maximizing performance as in grid search), it may be possible to reuse aspects of the model learned from the previous parameter value, saving time. When `warm_start` is true, the existing fitted model attributes are used to initialize the new model in a subsequent call to `fit`.

Note that this is only applicable for some models and some parameters, and even some orders of parameter values. For example, `warm_start` may be used when building random forests to add more trees to the forest (increasing `n_estimators`) but not to reduce their number.

`partial_fit` also retains the model between calls, but differs: with `warm_start` the parameters change and the data is (more-or-less) constant across calls to `fit`; with `partial_fit`, the mini-batch of data changes and model parameters stay fixed.

There are cases where you want to use `warm_start` to fit on different, but closely related data. For example, one may initially fit to a subset of the data, then fine-tune the parameter search on the full dataset. For classification, all data in a sequence of `warm_start` calls to `fit` must include samples from each class.
5.6 Attributes

See concept attribute.

classes_ A list of class labels known to the classifier, mapping each label to a numerical index used in the model representation our output. For instance, the array output from predict_proba has columns aligned with classes_. For multi-output classifiers, classes_ should be a list of lists, with one class listing for each output. For each output, the classes should be sorted (numerically, or lexicographically for strings).

classes_ and the mapping to indices is often managed with preprocessing.LabelEncoder.

components_ An affine transformation matrix of shape (n_components, n_features) used in many linear transformers where n_components is the number of output features and n_features is the number of input features.

See also components_ which is a similar attribute for linear predictors.

coeff_ The weight/coefficient matrix of a generalised linear model predictor, of shape (n_features,) for binary classification and single-output regression, (n_classes, n_features) for multiclass classification and (n_targets, n_features) for multi-output regression. Note this does not include the intercept (or bias) term, which is stored in intercept_.

When available, feature_importances_ is not usually provided as well, but can be calculated as the norm of each feature’s entry in coef_.

See also components_ which is a similar attribute for linear transformers.

embedding_ An embedding of the training data in manifold learning estimators, with shape (n_samples, n_components), identical to the output of fit_transform. See also labels_.

n_iter_ The number of iterations actually performed when fitting an iterative estimator that may stop upon convergence. See also max_iter.

feature_importances_ A vector of shape (n_features,) available in some predictors to provide a relative measure of the importance of each feature in the predictions of the model.

labels_ A vector containing a cluster label for each sample of the training data in clusterers, identical to the output of fit_predict. See also embedding_.

5.7 Data and sample properties

See concept sample property.

groups Used in cross-validation routines to identify samples that are correlated. Each value is an identifier such that, in a supporting CV splitter, samples from some groups value may not appear in both a training set and its corresponding test set. See Cross-validation iterators for grouped data..

sample_weight A relative weight for each sample. Intuitively, if all weights are integers, a weighted model or score should be equivalent to that calculated when repeating the sample the number of times specified in the weight. Weights may be specified as floats, so that sample weights are usually equivalent up to a constant positive scaling factor.

FIXME Is this interpretation always the case in practice? We have no common tests.

Some estimators, such as decision trees, support negative weights. FIXME: This feature or its absence may not be tested or documented in many estimators.

This is not entirely the case where other parameters of the model consider the number of samples in a region, as with min_samples in cluster.DBSCAN. In this case, a count of samples becomes to a sum of their weights.
In classification, sample weights can also be specified as a function of class with the `class_weight` estimator parameter.

\( \mathbf{X} \) Denotes data that is observed at training and prediction time, used as independent variables in learning. The notation is uppercase to denote that it is ordinarily a matrix (see rectangular). When a matrix, each sample may be represented by a feature vector, or a vector of precomputed (dis)similarity with each training sample. \( \mathbf{X} \) may also not be a matrix, and may require a feature extractor or a pairwise metric to turn it into one before learning a model.

\( \mathbf{X}_t \) Shorthand for “transformed \( \mathbf{X} \”).

\( \mathbf{y} \)

\( \mathbf{Y} \) Denotes data that may be observed at training time as the dependent variable in learning, but which is unavailable at prediction time, and is usually the target of prediction. The notation may be uppercase to denote that it is a matrix, representing multi-output targets, for instance; but usually we use \( \mathbf{y} \) and sometimes do so even when multiple outputs are assumed.
6.1 Release Highlights

These examples illustrate the main features of the releases of scikit-learn.

6.1.1 Release Highlights for scikit-learn 0.23

We are pleased to announce the release of scikit-learn 0.23! Many bug fixes and improvements were added, as well as some new key features. We detail below a few of the major features of this release. For an exhaustive list of all the changes, please refer to the release notes.

To install the latest version (with pip):

```
pip install --upgrade scikit-learn
```

or with conda:

```
conda install -c conda-forge scikit-learn
```

**Generalized Linear Models, and Poisson loss for gradient boosting**

Long-awaited Generalized Linear Models with non-normal loss functions are now available. In particular, three new regressors were implemented: `PoissonRegressor`, `GammaRegressor`, and `TweedieRegressor`. The Poisson regressor can be used to model positive integer counts, or relative frequencies. Read more in the User Guide. Additionally, `HistGradientBoostingRegressor` supports a new ‘poisson’ loss as well.

```
import numpy as np
from sklearn.model_selection import train_test_split
from sklearn.linear_model import PoissonRegressor
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor

n_samples, n_features = 1000, 20
rng = np.random.RandomState(0)
X = rng.randn(n_samples, n_features)
# positive integer target correlated with X[:, 5] with many zeros:
y = rng.poisson(lam=np.exp(X[:, 5]) / 2)
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=rng)
glm = PoissonRegressor()
gbdt = HistGradientBoostingRegressor(loss='poisson', learning_rate=.01)
glm.fit(X_train, y_train)
```

(continues on next page)
gbdt.fit(X_train, y_train)
print(glm.score(X_test, y_test))
print(gbdt.score(X_test, y_test))

Out:
0.35776189065725783
0.42425183539869415

**Rich visual representation of estimators**

Estimators can now be visualized in notebooks by enabling the `display='diagram'` option. This is particularly useful to summarise the structure of pipelines and other composite estimators, with interactivity to provide detail. Click on the example image below to expand Pipeline elements. See [Visualizing Composite Estimators](#) for how you can use this feature.

```python
from sklearn import set_config
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import OneHotEncoder, StandardScaler
from sklearn.impute import SimpleImputer
from sklearn.compose import make_column_transformer
from sklearn.linear_model import LogisticRegression

set_config(display='diagram')

num_proc = make_pipeline(SimpleImputer(strategy='median'), StandardScaler())

cat_proc = make_pipeline(
    SimpleImputer(strategy='constant', fill_value='missing'),
    OneHotEncoder(handle_unknown='ignore'))

preprocessor = make_column_transformer((num_proc, ('feat1', 'feat3')),
                                        (cat_proc, ('feat0', 'feat2')))

clf = make_pipeline(preprocessor, LogisticRegression())

clf
```

**Scalability and stability improvements to KMeans**

The `KMeans` estimator was entirely re-worked, and it is now significantly faster and more stable. In addition, the Elkan algorithm is now compatible with sparse matrices. The estimator uses OpenMP based parallelism instead of relying on joblib, so the `n_jobs` parameter has no effect anymore. For more details on how to control the number of threads, please refer to our [Parallelism notes](#).

```python
import scipy
import numpy as np
from sklearn.model_selection import train_test_split
from sklearn.cluster import KMeans
from sklearn.datasets import make_blobs
from sklearn.metrics import completeness_score

rng = np.random.RandomState(0)
X, y = make_blobs(random_state=rng)
X = scipy.sparse.csr_matrix(X)
```
X_train, X_test, _, y_test = train_test_split(X, y, random_state=rng)
kmeans = KMeans(algorithm='elkan').fit(X_train)
print(completeness_score(kmeans.predict(X_test), y_test))

Out:
0.8391458753133224

Improvements to the histogram-based Gradient Boosting estimators

Various improvements were made to HistGradientBoostingClassifier and HistGradientBoostingRegressor. On top of the Poisson loss mentioned above, these estimators now support sample weights. Also, an automatic early-stopping criterion was added: early-stopping is enabled by default when the number of samples exceeds 10k. Finally, users can now define monotonic constraints to constrain the predictions based on the variations of specific features. In the following example, we construct a target that is generally positively correlated with the first feature, with some noise. Applying monotonic constraints allows the prediction to capture the global effect of the first feature, instead of fitting the noise.

```python
import numpy as np
from matplotlib import pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.inspection import plot_partial_dependence
from sklearn.experimental import enable_hist_gradient_boosting
# noqa
from sklearn.ensemble import HistGradientBoostingRegressor

n_samples = 500
rng = np.random.RandomState(0)
X = rng.randn(n_samples, 2)
oise = rng.normal(loc=0.0, scale=0.01, size=n_samples)
y = (5 * X[:, 0] + np.sin(10 * np.pi * X[:, 0]) - noise)
gbdt_no_cst = HistGradientBoostingRegressor().fit(X, y)
gbdt_cst = HistGradientBoostingRegressor(monotonic_cst=[1, 0]).fit(X, y)

disp = plot_partial_dependence(
    gbdt_no_cst, X, features=[0], feature_names=['feature 0'],
    line_kw={'linewidth': 4, 'label': 'unconstrained', "color": "tab:blue"})
plot_partial_dependence(gbdt_cst, X, features=[0],
    line_kw={'linewidth': 4, 'label': 'constrained', "color": "tab:orange"},
    ax=disp.axes_)
disp.axes_[0, 0].plot(
    X[:, 0], y, 'o', alpha=.5, zorder=-1, label='samples', color="tab:green"
)
disp.axes_[0, 0].set_ylim(-3, 3); disp.axes_[0, 0].set_xlim(-1, 1)
plt.legend()
plt.show()
```
Sample-weight support for Lasso and ElasticNet

The two linear regressors *Lasso* and *ElasticNet* now support sample weights.

```python
from sklearn.model_selection import train_test_split
from sklearn.datasets import make_regression
from sklearn.linear_model import Lasso
import numpy as np

n_samples, n_features = 1000, 20
rng = np.random.RandomState(0)
X, y = make_regression(n_samples, n_features, random_state=rng)
sample_weight = rng.rand(n_samples)
X_train, X_test, y_train, y_test, sw_train, sw_test = train_test_split(
    X, y, sample_weight, random_state=rng)
reg = Lasso()
reg.fit(X_train, y_train, sample_weight=sw_train)
print(reg.score(X_test, y_test, sw_test))
```

Out:

```
0.999791942438998
```

**Total running time of the script:** ( 0 minutes 0.932 seconds)
6.1.2 Release Highlights for scikit-learn 0.24

We are pleased to announce the release of scikit-learn 0.24! Many bug fixes and improvements were added, as well as some new key features. We detail below a few of the major features of this release. For an exhaustive list of all the changes, please refer to the release notes.

To install the latest version (with pip):

```
pip install --upgrade scikit-learn
```

or with conda:

```
conda install -c conda-forge scikit-learn
```

Successive Halving estimators for tuning hyper-parameters

Successive Halving, a state of the art method, is now available to explore the space of the parameters and identify their best combination. HalvingGridSearchCV and HalvingRandomSearchCV can be used as drop-in replacement for GridSearchCV and RandomizedSearchCV. Successive Halving is an iterative selection process illustrated in the figure below. The first iteration is run with a small amount of resources, where the resource typically corresponds to the number of training samples, but can also be an arbitrary integer parameter such as n_estimators in a random forest. Only a subset of the parameter candidates are selected for the next iteration, which will be run with an increasing amount of allocated resources. Only a subset of candidates will last until the end of the iteration process, and the best parameter candidate is the one that has the highest score on the last iteration.

Read more in the User Guide (note: the Successive Halving estimators are still experimental).

```python
import numpy as np
from scipy.stats import randint
from sklearn.experimental import enable_halving_search_cv # noqa
from sklearn.model_selection import HalvingRandomSearchCV
from sklearn.ensemble import RandomForestClassifier
from sklearn.datasets import make_classification
rng = np.random.RandomState(0)
X, y = make_classification(n_samples=700, random_state=rng)
clf = RandomForestClassifier(n_estimators=10, random_state=rng)
param_dist = {
    "max_depth": [3, None],
    "max_features": randint(1, 11),
    "min_samples_split": randint(2, 11),
    "bootstrap": [True, False],
    "criterion": ["gini", "entropy"]
}

rsh = HalvingRandomSearchCV(estimator=clf, param_distributions=param_dist,
                             factor=2, random_state=rng)
rsh.fit(X, y)
rsh.best_params_
```

Out:

```
{'bootstrap': True, 'criterion': 'gini', 'max_depth': None, 'max_features': 10, 'min_samples_split': 10}
```
Native support for categorical features in HistGradientBoosting estimators

*HistGradientBoostingClassifier* and *HistGradientBoostingRegressor* now have native support for categorical features: they can consider splits on non-ordered, categorical data. Read more in the *User Guide*.

The plot shows that the new native support for categorical features leads to fitting times that are comparable to models where the categories are treated as ordered quantities, i.e. simply ordinal-encoded. Native support is also more expressive than both one-hot encoding and ordinal encoding. However, to use the new *categorical_features* parameter, it is still required to preprocess the data within a pipeline as demonstrated in this *example*.

Improved performances of HistGradientBoosting estimators

The memory footprint of *ensembleHistGradientBoostingRegressor* and *ensembleHistGradientBoostingClassifier* has been significantly improved during calls to *fit*. In addition, histogram initialization is now done in parallel which results in slight speed improvements. See more in the *Benchmark page*.
New self-training meta-estimator

A new self-training implementation, based on Yarowski’s algorithm can now be used with any classifier that implements `predict_proba`. The sub-classifier will behave as a semi-supervised classifier, allowing it to learn from unlabeled data. Read more in the `User guide`.

```python
import numpy as np
from sklearn import datasets
from sklearn.semi_supervised import SelfTrainingClassifier
from sklearn.svm import SVC

rng = np.random.RandomState(42)
iris = datasets.load_iris()
random_unlabeled_points = rng.rand(iris.target.shape[0]) < 0.3
iris.target[random_unlabeled_points] = -1
svc = SVC(probability=True, gamma="auto")
self_training_model = SelfTrainingClassifier(svc)
self_training_model.fit(iris.data, iris.target)
```

New SequentialFeatureSelector transformer

A new iterative transformer to select features is available: `SequentialFeatureSelector`. Sequential Feature Selection can add features one at a time (forward selection) or remove features from the list of the available features (backward selection), based on a cross-validated score maximization. See the `User Guide`.

```python
from sklearn.feature_selection import SequentialFeatureSelector
from sklearn.neighbors import KNeighborsClassifier
from sklearn.datasets import load_iris

X, y = load_iris(return_X_y=True, as_frame=True)
feature_names = X.columns
knn = KNeighborsClassifier(n_neighbors=3)
sfs = SequentialFeatureSelector(knn, n_features_to_select=2)
sfs.fit(X, y)
print("Features selected by forward sequential selection: ",
      f"{feature_names[sfs.get_support()].tolist()}"")
```

New PolynomialCountSketch kernel approximation function

The new `PolynomialCountSketch` approximates a polynomial expansion of a feature space when used with linear models, but uses much less memory than `PolynomialFeatures`.

```python
from sklearn.datasets import fetch_covtype
from sklearn.pipeline import make_pipeline
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import MinMaxScaler
from sklearn.kernel_approximation import PolynomialCountSketch
from sklearn.linear_model import LogisticRegression

(continues on next page)"
X, y = fetch_covtype(return_X_y=True)
pipe = make_pipeline(MinMaxScaler(),
    PolynomialCountSketch(degree=2, n_components=300),
    LogisticRegression(max_iter=1000))
X_train, X_test, y_train, y_test = train_test_split(X, y, train_size=5000,
    test_size=10000,
    random_state=42)
pipe.fit(X_train, y_train).score(X_test, y_test)

Out:
0.7317

For comparison, here is the score of a linear baseline for the same data:

linear_baseline = make_pipeline(MinMaxScaler(),
    LogisticRegression(max_iter=1000))
linear_baseline.fit(X_train, y_train).score(X_test, y_test)

Out:
0.7137

**Individual Conditional Expectation plots**

A new kind of partial dependence plot is available: the Individual Conditional Expectation (ICE) plot. ICE plots visualize the dependence of the prediction on a feature for each sample separately, with one line per sample. See the User Guide

```python
from sklearn.ensemble import RandomForestRegressor
from sklearn.datasets import fetch_california_housing
from sklearn.inspection import plot_partial_dependence
X, y = fetch_california_housing(return_X_y=True, as_frame=True)
features = ['MedInc', 'AveOccup', 'HouseAge', 'AveRooms']
est = RandomForestRegressor(n_estimators=10)
est.fit(X, y)
display = plot_partial_dependence(
est, X, features, kind="individual", subsample=50,
n_jobs=3, grid_resolution=20, random_state=0)
display.figure_.suptitle('Partial dependence of house value on non-location features
for the California housing dataset, with BayesianRidge')
display.figure_.subplots_adjust(hspace=0.3)
```
New Poisson splitting criterion for DecisionTreeRegressor

The integration of Poisson regression estimation continues from version 0.23. DecisionTreeRegressor now supports a new 'poisson' splitting criterion. Setting criterion="poisson" might be a good choice if your target is a count or a frequency.

```python
from sklearn.tree import DecisionTreeRegressor
from sklearn.model_selection import train_test_split
import numpy as np

n_samples, n_features = 1000, 20
rng = np.random.RandomState(0)
X = rng.randn(n_samples, n_features)
# positive integer target correlated with X[:, 5] with many zeros:
y = rng.poisson(lam=np.exp(X[:, 5]) / 2)
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=rng)
regressor = DecisionTreeRegressor(criterion='poisson', random_state=0)
regressor.fit(X_train, y_train)
```
New documentation improvements

New examples and documentation pages have been added, in a continuous effort to improve the understanding of machine learning practices:

- a new section about common pitfalls and recommended practices,
- an example illustrating how to statistically compare the performance of models evaluated using `GridSearchCV`,
- an example on how to interpret coefficients of linear models,
- an example comparing Principal Component Regression and Partial Least Squares.

Total running time of the script: ( 0 minutes 22.237 seconds)

6.1.3 Release Highlights for scikit-learn 0.22

We are pleased to announce the release of scikit-learn 0.22, which comes with many bug fixes and new features! We detail below a few of the major features of this release. For an exhaustive list of all the changes, please refer to the release notes.

To install the latest version (with pip):

```bash
pip install --upgrade scikit-learn
```

or with conda:

```bash
conda install -c conda-forge scikit-learn
```

New plotting API

A new plotting API is available for creating visualizations. This new API allows for quickly adjusting the visuals of a plot without involving any recomputation. It is also possible to add different plots to the same figure. The following example illustrates `plot_roc_curve`, but other plots utilities are supported like `plot_partial_dependence`, `plot_precision_recall_curve`, and `plot_confusion_matrix`. Read more about this new API in the User Guide.

```python
from sklearn.model_selection import train_test_split
from sklearn.svm import SVC
from sklearn.metrics import plot_roc_curve
from sklearn.ensemble import RandomForestClassifier
from sklearn.datasets import make_classification
import matplotlib.pyplot as plt

X, y = make_classification(random_state=0)
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)

svc = SVC(random_state=42)
svc.fit(X_train, y_train)
rfc = RandomForestClassifier(random_state=42)
rfc.fit(X_train, y_train)

svc_disp = plot_roc_curve(svc, X_test, y_test)
rfc_disp = plot_roc_curve(rfc, X_test, y_test, ax=svc_disp.ax_)
rfc_disp.figure_.suptitle("ROC curve comparison")
```

(continues on next page)
Stacking Classifier and Regressor

StackingClassifier and StackingRegressor allow you to have a stack of estimators with a final classifier or a regressor. Stacked generalization consists in stacking the output of individual estimators and use a classifier to compute the final prediction. Stacking allows to use the strength of each individual estimator by using their output as input of a final estimator. Base estimators are fitted on the full \( X \) while the final estimator is trained using cross-validated predictions of the base estimators using \texttt{cross_val_predict}.

Read more in the 

```python
from sklearn.datasets import load_iris
from sklearn.svm import LinearSVC
from sklearn.linear_model import LogisticRegression
from sklearn.preprocessing import StandardScaler
from sklearn.pipeline import make_pipeline
from sklearn.ensemble import StackingClassifier
from sklearn.model_selection import train_test_split

X, y = load_iris(return_X_y=True)
estimators = [
```
('rf', RandomForestClassifier(n_estimators=10, random_state=42)),
('svr', make_pipeline(StandardScaler(),
    LinearSVC(random_state=42)))
}
clf = StackingClassifier(
    estimators=estimators, final_estimator=LogisticRegression()
)
X_train, X_test, y_train, y_test = train_test_split(
    X, y, stratify=y, random_state=42
)
clf.fit(X_train, y_train).score(X_test, y_test)

Out:
0.9473684210526315

Permutation-based feature importance

The `inspection.permutation_importance` can be used to get an estimate of the importance of each feature, for any fitted estimator:

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_classification
from sklearn.ensemble import RandomForestClassifier
from sklearn.inspection import permutation_importance

X, y = make_classification(random_state=0, n_features=5, n_informative=3)
feature_names = [f'x_{i}' for i in range(X.shape[1])]

rf = RandomForestClassifier(random_state=0).fit(X, y)
result = permutation_importance(rf, X, y, n_repeats=10, random_state=0,
                                 n_jobs=-1)

fig, ax = plt.subplots()
sorted_idx = result.importances_mean.argsort()
ax.boxplot(result.importances[sorted_idx].T,
           vert=False, labels=feature_names[sorted_idx])
ax.set_title("Permutation Importance of each feature")
ax.set_ylabel("Features")
fig.tight_layout()
plt.show()
```
Native support for missing values for gradient boosting

The `ensemble.HistGradientBoostingClassifier` and `ensemble.HistGradientBoostingRegressor` now have native support for missing values (NaNs). This means that there is no need for imputing data when training or predicting.

```python
from sklearn.experimental import enable_hist_gradient_boosting # noqa
from sklearn.ensemble import HistGradientBoostingClassifier

X = np.array([0, 1, 2, np.nan]).reshape(-1, 1)
y = [0, 0, 1, 1]

gbdt = HistGradientBoostingClassifier(min_samples_leaf=1).fit(X, y)
print(gbdt.predict(X))
```

Out:

```
[0 0 1 1]
```
Precomputed sparse nearest neighbors graph

Most estimators based on nearest neighbors graphs now accept precomputed sparse graphs as input, to reuse the same graph for multiple estimator fits. To use this feature in a pipeline, one can use the memory parameter, along with one of the two new transformers, `neighbors.KNeighborsTransformer` and `neighbors.RadiusNeighborsTransformer`. The precomputation can also be performed by custom estimators to use alternative implementations, such as approximate nearest neighbors methods. See more details in the User Guide.

```python
from tempfile import TemporaryDirectory
from sklearn.neighbors import KNeighborsTransformer
from sklearn.manifold import Isomap
from sklearn.pipeline import make_pipeline

X, y = make_classification(random_state=0)

with TemporaryDirectory(prefix="sklearn_cache_") as tmpdir:
    estimator = make_pipeline(
        KNeighborsTransformer(n_neighbors=10, mode='distance'),
        Isomap(n_neighbors=10, metric='precomputed'),
        memory=tmpdir)
    estimator.fit(X)

    # We can decrease the number of neighbors and the graph will not be recomputed.
    estimator.set_params(isomap__n_neighbors=5)
    estimator.fit(X)
```

KNN Based Imputation

We now support imputation for completing missing values using k-Nearest Neighbors.

Each sample’s missing values are imputed using the mean value from `n_neighbors` nearest neighbors found in the training set. Two samples are close if the features that neither is missing are close. By default, a euclidean distance metric that supports missing values, `nan_euclidean_distances`, is used to find the nearest neighbors.

Read more in the User Guide.

```python
from sklearn.impute import KNNImputer

X = [[1, 2, np.nan], [3, 4, 3], [np.nan, 6, 5], [8, 8, 7]]
imputer = KNNImputer(n_neighbors=2)
print(imputer.fit_transform(X))
```

Out:

```
[[1. 2. 4.]
 [3. 4. 3.]
 [5.5 6. 5.]
 [8. 8. 7.]]
```
Tree pruning

It is now possible to prune most tree-based estimators once the trees are built. The pruning is based on minimal cost-complexity. Read more in the User Guide for details.

```python
X, y = make_classification(random_state=0)
rf = RandomForestClassifier(random_state=0, ccp_alpha=0).fit(X, y)
print("Average number of nodes without pruning {:.1f}"
      .format(np.mean([e.tree_.node_count for e in rf.estimators_])))

rf = RandomForestClassifier(random_state=0, ccp_alpha=0.05).fit(X, y)
print("Average number of nodes with pruning {:.1f}"
      .format(np.mean([e.tree_.node_count for e in rf.estimators_])))
```

Out:

```
Average number of nodes without pruning 22.3
Average number of nodes with pruning 6.4
```

Retrieve dataframes from OpenML

datasets.fetch_openml can now return pandas dataframe and thus properly handle datasets with heterogeneous data:

```python
from sklearn.datasets import fetch_openml
titanic = fetch_openml('titanic', version=1, as_frame=True)
print(titanic.data.head()[["pclass", 'embarked'])
```

Out:

```
pclass embarked
0  1.0 S
1  1.0 S
2  1.0 S
3  1.0 S
4  1.0 S
```

Checking scikit-learn compatibility of an estimator

Developers can check the compatibility of their scikit-learn compatible estimators using check_estimator. For instance, the check_estimator(LinearSVC()) passes.

We now provide a pytest specific decorator which allows pytest to run all checks independently and report the checks that are failing.

..note:: This entry was slightly updated in version 0.24, where passing classes isn’t supported anymore: pass instances instead.
ROC AUC now supports multiclass classification

The roc_auc_score function can also be used in multi-class classification. Two averaging strategies are currently supported: the one-vs-one algorithm computes the average of the pairwise ROC AUC scores, and the one-vs-rest algorithm computes the average of the ROC AUC scores for each class against all other classes. In both cases, the multiclass ROC AUC scores are computed from the probability estimates that a sample belongs to a particular class according to the model. The OvO and OvR algorithms support weighting uniformly (average='macro') and weighting by the prevalence (average='weighted').

Read more in the User Guide.

```python
from sklearn.datasets import make_classification
from sklearn.svm import SVC
from sklearn.metrics import roc_auc_score

X, y = make_classification(n_classes=4, n_informative=16)
clf = SVC(decision_function_shape='ovo', probability=True).fit(X, y)
print(roc_auc_score(y, clf.predict_proba(X), multi_class='ovo'))
```

Out:

```
0.9852
```

Total running time of the script: ( 0 minutes 1.977 seconds)

### 6.2 Biclustering

Examples concerning the sklearn.cluster.bicluster module.

#### 6.2.1 A demo of the Spectral Co-Clustering algorithm

This example demonstrates how to generate a dataset and bicluster it using the Spectral Co-Clustering algorithm.

The dataset is generated using the make_biclusters function, which creates a matrix of small values and implants bicluster with large values. The rows and columns are then shuffled and passed to the Spectral Co-Clustering algorithm. Rearranging the shuffled matrix to make biclusters contiguous shows how accurately the algorithm found the biclusters.
```python
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_biclusters
from sklearn.cluster import SpectralCoclustering
from sklearn.metrics import consensus_score

data, rows, columns = make_biclusters(
    shape=(300, 300), n_clusters=5, noise=5,
    shuffle=False, random_state=0)
```

Out:

```
consensus score: 1.000
```
plt.matshow(data, cmap=plt.cm.Blues)
plt.title("Original dataset")

# shuffle clusters
rng = np.random.RandomState(0)
row_idx = rng.permutation(data.shape[0])
col_idx = rng.permutation(data.shape[1])
data = data[row_idx][:, col_idx]

plt.matshow(data, cmap=plt.cm.Blues)
plt.title("Shuffled dataset")

model = SpectralCoclustering(n_clusters=5, random_state=0)
model.fit(data)
score = consensus_score(model.biclusters_,
                        {rows[:, row_idx], columns[:, col_idx]})

print("consensus score: {:.3f}".format(score))

fit_data = data[np.argsort(model.row_labels_)]
fit_data = fit_data[:, np.argsort(model.column_labels_)]

plt.matshow(fit_data, cmap=plt.cm.Blues)
plt.title("After biclustering; rearranged to show biclusters")
plt.show()

**Total running time of the script:** (0 minutes 0.395 seconds)

### 6.2.2 A demo of the Spectral Biclustering algorithm

This example demonstrates how to generate a checkerboard dataset and bicluster it using the Spectral Biclustering algorithm.

The data is generated with the `make_checkerboard` function, then shuffled and passed to the Spectral Biclustering algorithm. The rows and columns of the shuffled matrix are rearranged to show the biclusters found by the algorithm. The outer product of the row and column label vectors shows a representation of the checkerboard structure.
Original dataset

0  50  100  150  200  250

0

50

100

150

200

250

.
6.2. Biclustering
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)

print(__doc__)

# Author: Kemal Eren <kemal@kemaleren.com>
# License: BSD 3 clause
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)

print(__doc__)

# Author: Kemal Eren <kemal@kemaleren.com>
# License: BSD 3 clause
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)

print(__doc__)

# Author: Kemal Eren <kemal@kemaleren.com>
# License: BSD 3 clause
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)

print(__doc__)

# Author: Kemal Eren <kemal@kemaleren.com>
# License: BSD 3 clause
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)

print(__doc__)

# Author: Kemal Eren <kemal@kemaleren.com>
# License: BSD 3 clause
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_checkerboard
from sklearn.cluster import SpectralBiclustering
from sklearn.metrics import consensus_score
n_clusters = (4, 3)
data, rows, columns = make_checkerboard(
    shape=(300, 300), n_clusters=n_clusters, noise=10,
    random_state=0)
```python
shuffle=False, random_state=0)
plt.matshow(data, cmap=plt.cm.Blues)
plt.title("Original dataset")

# shuffle clusters
rng = np.random.RandomState(0)
row_idx = rng.permutation(data.shape[0])
col_idx = rng.permutation(data.shape[1])
data = data[row_idx][:, col_idx]
plt.matshow(data, cmap=plt.cm.Blues)
plt.title("Shuffled dataset")

model = SpectralBiclustering(n_clusters=n_clusters, method='log',
                           random_state=0)
model.fit(data)
score = consensus_score(model.biclusters_,
                        (rows[:, row_idx], columns[:, col_idx]))
print("consensus score: {:.1f}".format(score))
fit_data = data[np.argsort(model.row_labels_)]
fit_data = fit_data[:, np.argsort(model.column_labels_)]
plt.matshow(fit_data, cmap=plt.cm.Blues)
plt.title("After biclustering; rearranged to show biclusters")
plt.matshow(np.outer(np.sort(model.row_labels_) + 1,
                     np.sort(model.column_labels_) + 1),
            cmap=plt.cm.Blues)
plt.title("Checkerboard structure of rearranged data")
plt.show()
```

Total running time of the script: ( 0 minutes 0.909 seconds)

### 6.2.3 Biclustering documents with the Spectral Co-clustering algorithm

This example demonstrates the Spectral Co-clustering algorithm on the twenty newsgroups dataset. The ‘comp.os.ms-windows.misc’ category is excluded because it contains many posts containing nothing but data.

The TF-IDF vectorized posts form a word frequency matrix, which is then biclstered using Dhillon’s Spectral Co-Clustering algorithm. The resulting document-word biclusters indicate subsets words used more often in those subsets documents.

For a few of the best biclusters, its most common document categories and its ten most important words get printed. The best biclusters are determined by their normalized cut. The best words are determined by comparing their sums inside and outside the bicluster.

For comparison, the documents are also clustered using MiniBatchKMeans. The document clusters derived from the biclusters achieve a better V-measure than clusters found by MiniBatchKMeans.

Out:
Vectorizing...
Coclustering...
Done in 1.94s. V-measure: 0.4431
MiniBatchKMeans...
Done in 5.80s. V-measure: 0.3344

Best biclusters:

bicluster 0 : 1961 documents, 4388 words
  categories : 23% talk.politics.guns, 18% talk.politics.misc, 17% sci.med
  words : gun, geb, guns, banks, gordon, clinton, pitt, cdt, surrender, veal

bicluster 1 : 1269 documents, 3558 words
  categories : 27% soc.religion.christian, 25% talk.politics.mideast, 24% alt.atheism
  words : god, jesus, christians, sin, objective, kent, belief, christ, faith,
         moral

bicluster 2 : 2201 documents, 2747 words
  categories : 18% comp.sys.mac.hardware, 17% comp.sys.ibm.pc.hardware, 16% comp.
               graphics
  words : voltage, board, dsp, packages, receiver, stereo, shipping, package,
         compression, image

bicluster 3 : 1773 documents, 2620 words
  categories : 27% rec.motorcycles, 23% rec.autos, 13% misc.forsale
  words : bike, car, dod, engine, motorcycle, ride, honda, bikes, helmet, bmw

bicluster 4 : 201 documents, 1175 words
  categories : 81% talk.politics.mideast, 10% alt.atheism, 7% soc.religion.christian
  words : turkish, armenia, armenian, armenians, turks, petch, sera, zuma, argic,
         gvg47

from collections import defaultdict
import operator
from time import time
import numpy as np

from sklearn.cluster import SpectralCoclustering
from sklearn.cluster import MiniBatchKMeans
from sklearn.datasets import fetch_20newsgroups
from sklearn.feature_extraction.text import TfidfVectorizer
from sklearn.metrics.cluster import v_measure_score

print(__doc__)

def number_normalizer(tokens):
    """ Map all numeric tokens to a placeholder.

    For many applications, tokens that begin with a number are not directly
    useful, but the fact that such a token exists can be relevant. By applying
    """

(continues on next page)
this form of dimensionality reduction, some methods may perform better.

```
return ("#NUMBER" if token[0].isdigit() else token for token in tokens)
```

class NumberNormalizingVectorizer(TfidfVectorizer):
    def build_tokenizer(self):
        tokenize = super().build_tokenizer()
        return lambda doc: list(number_normalizer(tokenize(doc)))

# exclude 'comp.os.ms-windows.misc'
categories = ['alt.atheism', 'comp.graphics',
             'comp.sys.ibm.pc.hardware', 'comp.sys.mac.hardware',
             'comp.windows.x', 'misc.forsale', 'rec.autos',
             'rec.motorcycles', 'rec.sport.baseball',
             'rec.sport.hockey', 'sci.crypt', 'sci.electronics',
             'sci.med', 'sci.space', 'soc.religion.christian',
             'talk.politics.guns', 'talk.politics.mideast',
             'talk.politics.misc', 'talk.religion.misc']

ewsgroups = fetch_20newsgroups(categories=categories)
y_true = newsgroups.target

vectorizer = NumberNormalizingVectorizer(stop_words='english', min_df=5)
cocluster = SpectralCoclustering(n_clusters=len(categories),
                                 svd_method='arpack', random_state=0)
kmeans = MiniBatchKMeans(n_clusters=len(categories), batch_size=20000,
                         random_state=0)

print("Vectorizing...")
X = vectorizer.fit_transform(newsgroups.data)

print("Coclustering...")
start_time = time()
cocluster.fit(X)
y_cocluster = cocluster.row_labels_
print("Done in {:.2f}s. V-measure: {:.4f}".format(
    time() - start_time,
    v_measure_score(y_cocluster, y_true)))

print("MiniBatchKMeans...")
start_time = time()
y_kmeans = kmeans.fit_predict(X)
print("Done in {:.2f}s. V-measure: {:.4f}".format(
    time() - start_time,
    v_measure_score(y_kmeans, y_true)))

feature_names = vectorizer.get_feature_names()
document_names = list(newsgroups.target_names[i] for i in newsgroups.target)

    def bicluster_ncut(i):
        rows, cols = cocluster.get_indices(i)
        if not (np.any(rows) and np.any(cols)):
col_complement = np.nonzero(np.logical_not(cocluster.columns_[i]))[0]
# Note: the following is identical to X[rows[:, np.newaxis],
# cols].sum() but much faster in scipy <= 0.16
weight = X[rows][:, cols].sum()
cut = (X[row_complement][:, cols].sum() +
      X[rows][:, col_complement].sum())
return cut / weight

def most_common(d):
    """Items of a defaultdict(int) with the highest values.
    Like Counter.most_common in Python >=2.7.
    ""
    return sorted(d.items(), key=operator.itemgetter(1), reverse=True)

bicluster_ncuts = list(bicluster_ncut(i)
                        for i in range(len(newsgroups.target_names)))
best_idx = np.argsort(bicluster_ncuts)[:5]

print()
pd.DataFrame(bicluster_ncuts, index=newsgroups.target_names
             .translate(str.maketrans('', '', '/')).
             tolist())

print()  
print("Best biclusters:")
print("""-------")
for idx, cluster in enumerate(best_idx):
    n_rows, n_cols = cocluster.get_shape(cluster)
    cluster_docs, cluster_words = cocluster.get_indices(cluster)
    if not len(cluster_docs) or not len(cluster_words):
        continue

    # categories
    counter = defaultdict(int)
    for i in cluster_docs:
        counter[document_names[i]] += 1
    cat_string = ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 ", 
                 "
    for name, c in most_common(counter)[:3]:
        cat_string = cat_string.format(float(c) / n_rows * 100, name)

    # words
    out_of_cluster_docs = cocluster.row_labels_ != cluster
    out_of_cluster_docs = np.where(out_of_cluster_docs)[0]
    word_col = X[:, cluster_words]
    word_scores = np.array(word_col[cluster_docs, :].sum(axis=0) -
                           word_col[out_of_cluster_docs, :].sum(axis=0))
    word_scores = word_scores.ravel()
    important_words = list(feature_names[cluster_words[i]]
                           for i in word_scores.argsort()[:-11:-1])

    print("bicluster {}": {} documents, {} words".format(  
                            idx, n_rows, n_cols))
    print("categories : {}".format(cat_string))
    print("words : \n".format(\', '.join(important_words)))

Total running time of the script: ( 0 minutes 11.048 seconds)
6.3 Calibration

Examples illustrating the calibration of predicted probabilities of classifiers.

6.3.1 Comparison of Calibration of Classifiers

Well calibrated classifiers are probabilistic classifiers for which the output of the predict_proba method can be directly interpreted as a confidence level. For instance a well calibrated (binary) classifier should classify the samples such that among the samples to which it gave a predict_proba value close to 0.8, approx. 80% actually belong to the positive class.

LogisticRegression returns well calibrated predictions as it directly optimizes log-loss. In contrast, the other methods return biased probabilities, with different biases per method:

- GaussianNaiveBayes tends to push probabilities to 0 or 1 (note the counts in the histograms). This is mainly because it makes the assumption that features are conditionally independent given the class, which is not the case in this dataset which contains 2 redundant features.

- RandomForestClassifier shows the opposite behavior: the histograms show peaks at approx. 0.2 and 0.9 probability, while probabilities close to 0 or 1 are very rare. An explanation for this is given by Niculescu-Mizil and Caruana¹: “Methods such as bagging and random forests that average predictions from a base set of models can have difficulty making predictions near 0 and 1 because variance in the underlying base models will bias predictions that should be near zero or one away from these values. Because predictions are restricted to the interval [0,1], errors caused by variance tend to be one-sided near zero and one. For example, if a model should predict \( p = 0 \) for a case, the only way bagging can achieve this is if all bagged trees predict zero. If we add noise to the trees that bagging is averaging over, this noise will cause some trees to predict values larger than 0 for this case, thus moving the average prediction of the bagged ensemble away from 0. We observe this effect most strongly with random forests because the base-level trees trained with random forests have relatively high variance due to feature subsetting.” As a result, the calibration curve shows a characteristic sigmoid shape, indicating that the classifier could trust its “intuition” more and return probabilities closer to 0 or 1 typically.

- Support Vector Classification (SVC) shows an even more sigmoid curve as the RandomForestClassifier, which is typical for maximum-margin methods (compare Niculescu-Mizil and Caruana¹), which focus on hard samples that are close to the decision boundary (the support vectors).

References:

¹ Predicting Good Probabilities with Supervised Learning, A. Niculescu-Mizil & R. Caruana, ICML 2005
Calibration plots (reliability curve)

print(__doc__)

# Author: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD Style.

import numpy as np
np.random.seed(0)

import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.naive_bayes import GaussianNB
from sklearn.linear_model import LogisticRegression
from sklearn.ensemble import RandomForestClassifier

6.3. Calibration
from sklearn.svm import LinearSVC
from sklearn.calibration import calibration_curve

X, y = datasets.make_classification(n_samples=100000, n_features=20,
                                   n_informative=2, n_redundant=2)

train_samples = 100  # Samples used for training the models
X_train = X[:train_samples]
X_test = X[train_samples:]
y_train = y[:train_samples]
y_test = y[train_samples:]

# Create classifiers
lr = LogisticRegression()
gnb = GaussianNB()
svc = LinearSVC(C=1.0)
rfc = RandomForestClassifier()

# # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # #
# Plot calibration plots
plt.figure(figsize=(10, 10))
ax1 = plt.subplot2grid((3, 1), (0, 0), rowspan=2)
ax2 = plt.subplot2grid((3, 1), (2, 0))

def plot_calibration(ax, clf, name):
    if hasattr(clf, "predict_proba"):
        prob_pos = clf.predict_proba(X_train)[:, 1]
    else:
        prob_pos = clf.decision_function(X_train)
        prob_pos = (prob_pos - prob_pos.min()) / (prob_pos.max() - prob_pos.min())

    fraction_of_positives, mean_predicted_value = calibration_curve(y_train, prob_pos, n_bins=10)
    ax.plot(mean_predicted_value, fraction_of_positives, "s-", label="%s" % name)

    ax.plot([0, 1], [0, 1], "k:", label="Perfectly calibrated")

for clf, name in [(lr, 'Logistic'),
                  (gnb, 'Naive Bayes'),
                  (svc, 'Support Vector Classification'),
                  (rfc, 'Random Forest')]:
    plot_calibration(ax1, clf, name)
    clf.fit(X_train, y_train)

    if hasattr(clf, "predict_proba"):
        prob_pos = clf.predict_proba(X_test)[:, 1]
    else:
        prob_pos = clf.decision_function(X_test)
        prob_pos = (prob_pos - prob_pos.min()) / (prob_pos.max() - prob_pos.min())

    fraction_of_positives, mean_predicted_value = calibration_curve(y_test, prob_pos, n_bins=10)
    ax1.plot(mean_predicted_value, fraction_of_positives, "s-", label="%s" % name)
    ax1.plot([0, 1], [0, 1], "k:", label="Perfectly calibrated")

    ax2.hist(prob_pos, range=(0, 1), bins=10, label=name, histtype="step", lw=2)

ax1.set_ylabel("Fraction of positives")
ax1.set_ylim([-0.05, 1.05])
ax1.legend(loc="lower right")
ax1.set_title("Calibration plots (reliability curve)")

ax2.set_xlabel("Mean predicted value")
ax2.set_ylabel("Count")
ax2.legend(loc="upper center", ncol=2)
6.3.2 Probability Calibration curves

When performing classification one often wants to predict not only the class label, but also the associated probability. This probability gives some kind of confidence on the prediction. This example demonstrates how to display how well calibrated the predicted probabilities are and how to calibrate an uncalibrated classifier.

The experiment is performed on an artificial dataset for binary classification with 100,000 samples (1,000 of them are used for model fitting) with 20 features. Of the 20 features, only 2 are informative and 10 are redundant. The first figure shows the estimated probabilities obtained with logistic regression, Gaussian naive Bayes, and Gaussian naive Bayes with both isotonic calibration and sigmoid calibration. The calibration performance is evaluated with Brier score, reported in the legend (the smaller the better). One can observe here that logistic regression is well calibrated while raw Gaussian naive Bayes performs very badly. This is because of the redundant features which violate the assumption of feature-independence and result in an overly confident classifier, which is indicated by the typical transposed-sigmoid curve.

Calibration of the probabilities of Gaussian naive Bayes with isotonic regression can fix this issue as can be seen from the nearly diagonal calibration curve. Sigmoid calibration also improves the brier score slightly, albeit not as strongly as the non-parametric isotonic regression. This can be attributed to the fact that we have plenty of calibration data such that the greater flexibility of the non-parametric model can be exploited.

The second figure shows the calibration curve of a linear support-vector classifier (LinearSVC). LinearSVC shows the opposite behavior as Gaussian naive Bayes: the calibration curve has a sigmoid curve, which is typical for an under-confident classifier. In the case of LinearSVC, this is caused by the margin property of the hinge loss, which lets the model focus on hard samples that are close to the decision boundary (the support vectors).

Both kinds of calibration can fix this issue and yield nearly identical results. This shows that sigmoid calibration can deal with situations where the calibration curve of the base classifier is sigmoid (e.g., for LinearSVC) but not where it is transposed-sigmoid (e.g., Gaussian naive Bayes).
Calibration plots (reliability curve)

- Perfectly calibrated
- Logistic (0.099)
- Naive Bayes (0.118)
- Naive Bayes + Isotonic (0.098)
- Naive Bayes + Sigmoid (0.109)

Count

Mean predicted value
Out:

Logistic:
  Brier: 0.099
  Precision: 0.872
  Recall: 0.851
  F1: 0.862

Naive Bayes:
  Brier: 0.118
  Precision: 0.857
  Recall: 0.876
  F1: 0.867

Naive Bayes + Isotonic:
  Brier: 0.098
  Precision: 0.883

(continues on next page)
Recall: 0.836  
F1: 0.859  

Naive Bayes + Sigmoid:  
Brier: 0.109  
Precision: 0.861  
Recall: 0.871  
F1: 0.866  

Logistic:  
Brier: 0.099  
Precision: 0.872  
Recall: 0.851  
F1: 0.862  

SVC:  
Brier: 0.163  
Precision: 0.872  
Recall: 0.852  
F1: 0.862  

SVC + Isotonic:  
Brier: 0.100  
Precision: 0.853  
Recall: 0.878  
F1: 0.865  

SVC + Sigmoid:  
Brier: 0.099  
Precision: 0.874  
Recall: 0.849  
F1: 0.861  

---

```python
print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@telecom-paristech.fr>
# Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD Style.

import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.naive_bayes import GaussianNB
from sklearn.svm import LinearSVC
from sklearn.linear_model import LogisticRegression
from sklearn.metrics import (brier_score_loss, precision_score, recall_score,
                              f1_score)
from sklearn.calibration import CalibratedClassifierCV, calibration_curve
from sklearn.model_selection import train_test_split
```

(continues on next page)
# Create dataset of classification task with many redundant and few informative features
X, y = datasets.make_classification(n_samples=100000, n_features=20,
    n_informative=2, n_redundant=10,
    random_state=42)

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.99,
    random_state=42)

```python
def plot_calibration_curve(est, name, fig_index):
    """Plot calibration curve for est w/o and with calibration. ""
    # Calibrated with isotonic calibration
    isotonic = CalibratedClassifierCV(est, cv=2, method='isotonic')
    # Calibrated with sigmoid calibration
    sigmoid = CalibratedClassifierCV(est, cv=2, method='sigmoid')
    # Logistic regression with no calibration as baseline
    lr = LogisticRegression(C=1.)

    fig = plt.figure(fig_index, figsize=(10, 10))
    ax1 = plt.subplot2grid((3, 1), (0, 0), rowspan=2)
    ax2 = plt.subplot2grid((3, 1), (2, 0))

    ax1.plot([0, 1], [0, 1], "k:", label="Perfectly calibrated")
    for clf, name in [(lr, 'Logistic'),
                      (est, name),
                      (isotonic, name + ' + Isotonic'),
                      (sigmoid, name + ' + Sigmoid')]:
        clf.fit(X_train, y_train)
        y_pred = clf.predict(X_test)
        if hasattr(clf, "predict_proba"):
            prob_pos = clf.predict_proba(X_test)[:, 1]
        else:  # use decision function
            prob_pos = clf.decision_function(X_test)
            prob_pos = (prob_pos - prob_pos.min()) / (prob_pos.max() - prob_pos.min())

        clf_score = brier_score_loss(y_test, prob_pos, pos_label=y.max())
        print("%s: %1.3f" % (name, clf_score))
        print("Brier: %1.3f" % (clf_score))
        print("Precision: %1.3f" % precision_score(y_test, y_pred))
        print("Recall: %1.3f" % recall_score(y_test, y_pred))
        print("F1: %1.3f" % f1_score(y_test, y_pred))

        fraction_of_positives, mean_predicted_value = \\
        calibration_curve(y_test, prob_pos, n_bins=10)

        ax1.plot(mean predicted_value, fraction_of_positives, "s-",
                label="%s (%1.3f)" % (name, clf_score))

        ax2.hist(prob_pos, range=(0, 1), bins=10, label=name,
                histtype="step", lw=2)

        ax1.set_ylabel("Fraction of positives")
        ax1.set_ylim([-0.05, 1.05])
```

(continues on next page)
6.3.3 Probability calibration of classifiers

When performing classification you often want to predict not only the class label, but also the associated probability. This probability gives you some kind of confidence on the prediction. However, not all classifiers provide well-calibrated probabilities, some being over-confident while others being under-confident. Thus, a separate calibration of predicted probabilities is often desirable as a postprocessing. This example illustrates two different methods for this calibration and evaluates the quality of the returned probabilities using Brier’s score (see https://en.wikipedia.org/wiki/Brier_score).

Compared are the estimated probability using a Gaussian naive Bayes classifier without calibration, with a sigmoid calibration, and with a non-parametric isotonic calibration. One can observe that only the non-parametric model is able to provide a probability calibration that returns probabilities close to the expected 0.5 for most of the samples belonging to the middle cluster with heterogeneous labels. This results in a significantly improved Brier score.
Out:

Brier score losses: (the smaller the better)
No calibration: 0.104
With isotonic calibration: 0.084
With sigmoid calibration: 0.109

import numpy as np
import matplotlib.pyplot as plt
from matplotlib import cm
from sklearn.datasets import make_blobs
from sklearn.naive_bayes import GaussianNB
from sklearn.metrics import brier_score_loss

(continues on next page)
from sklearn.calibration import CalibratedClassifierCV
from sklearn.model_selection import train_test_split

n_samples = 50000
n_bins = 3  # use 3 bins for calibration_curve as we have 3 clusters here

# Generate 3 blobs with 2 classes where the second blob contains
# half positive samples and half negative samples. Probability in this
# blob is therefore 0.5.
centers = [(-5, -5), (0, 0), (5, 5)]
X, y = make_blobs(n_samples=n_samples, centers=center, shuffle=False,
                  random_state=42)

y[:n_samples // 2] = 0
y[n_samples // 2:] = 1
sample_weight = np.random.RandomState(42).rand(y.shape[0])

# split train, test for calibration
X_train, X_test, y_train, y_test, sw_train, sw_test = train_test_split(X, y, sample_weight, test_size=0.9, random_state=42)

# Gaussian Naive-Bayes with no calibration
clf = GaussianNB()
clf.fit(X_train, y_train)  # GaussianNB itself does not support sample-weights
prob_pos_clf = clf.predict_proba(X_test)[:, 1]

# Gaussian Naive-Bayes with isotonic calibration
clf_isotonic = CalibratedClassifierCV(clf, cv=2, method='isotonic')
clf_isotonic.fit(X_train, y_train, sample_weight=sw_train)
prob_pos_isotonic = clf_isotonic.predict_proba(X_test)[:, 1]

# Gaussian Naive-Bayes with sigmoid calibration
clf_sigmoid = CalibratedClassifierCV(clf, cv=2, method='sigmoid')
clf_sigmoid.fit(X_train, y_train, sample_weight=sw_train)
prob_pos_sigmoid = clf_sigmoid.predict_proba(X_test)[:, 1]

print("Brier score losses: (the smaller the better)")

clf_score = brier_score_loss(y_test, prob_pos_clf, sample_weight=sw_test)
print("No calibration: \$1.3f\% \$1.3f\% \$1.3f\%")

clf_isotonic_score = brier_score_loss(y_test, prob_pos_isotonic, sample_weight=sw_test)
print("With isotonic calibration: \$1.3f\% \$1.3f\% \$1.3f\%")

clf_sigmoid_score = brier_score_loss(y_test, prob_pos_sigmoid, sample_weight=sw_test)
print("With sigmoid calibration: \$1.3f\% \$1.3f\% \$1.3f\%")

# Plot the data and the predicted probabilities
plt.figure()
y_unique = np.unique(y)
colors = cm.rainbow(np.linspace(0.0, 1.0, y_unique.size))
for this_y, color in zip(y_unique, colors):
    this_X = X_train[y_train == this_y]
    # (continues on next page)
This example illustrates how sigmoid calibration changes predicted probabilities for a 3-class classification problem. Illustrated is the standard 2-simplex, where the three corners correspond to the three classes. Arrows point from the probability vectors predicted by an uncalibrated classifier to the probability vectors predicted by the same classifier after sigmoid calibration on a hold-out validation set. Colors indicate the true class of an instance (red: class 1, green: class 2, blue: class 3).

**Data**

Below, we generate a classification dataset with 2000 samples, 2 features and 3 target classes. We then split the data as follows:

- train: 600 samples (for training the classifier)
- valid: 400 samples (for calibrating predicted probabilities)
- test: 1000 samples

Note that we also create `X_train_valid` and `y_train_valid`, which consists of both the train and valid subsets. This is used when we only want to train the classifier but not calibrate the predicted probabilities.

```python
# Author: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD Style.

import numpy as np
```

---

(continues on next page)
from sklearn.datasets import make_blobs

np.random.seed(0)

X, y = make_blobs(n_samples=2000, n_features=2, centers=3, random_state=42,
                  cluster_std=5.0)
X_train, y_train = X[:600], y[:600]
X_valid, y_valid = X[600:1000], y[600:1000]
X_train_valid, y_train_valid = X[:1000], y[:1000]
X_test, y_test = X[1000:], y[1000:]

Fitting and calibration

First, we will train a RandomForestClassifier with 25 base estimators (trees) on the concatenated train and validation data (1000 samples). This is the uncalibrated classifier.

from sklearn.ensemble import RandomForestClassifier

clf = RandomForestClassifier(n_estimators=25)
clf.fit(X_train_valid, y_train_valid)

to train the calibrated classifier, we start with the same RandomForestClassifier but train it using only the train data subset (600 samples) then calibrate, with method='sigmoid', using the valid data subset (400 samples) in a 2-stage process.

from sklearn.calibration import CalibratedClassifierCV

cal_clf = CalibratedClassifierCV(clf, method="sigmoid", cv="prefit")
cal_clf.fit(X_valid, y_valid)

Compare probabilities

Below we plot a 2-simplex with arrows showing the change in predicted probabilities of the test samples.

import matplotlib.pyplot as plt

plt.figure(figsize=(10, 10))
colors = ['r', 'g', 'b']

clf_probs = clf.predict_proba(X_test)
cal_clf_probs = cal_clf.predict_proba(X_test)

# Plot arrows
for i in range(clf_probs.shape[0]):
    plt.arrow(clf_probs[i, 0], clf_probs[i, 1],
              cal_clf_probs[i, 0] - clf_probs[i, 0],
              cal_clf_probs[i, 1] - clf_probs[i, 1],
              color=colors[y_test[i]], head_width=1e-2)

# Plot perfect predictions, at each vertex
plt.plot([1.0], [0.0], 'ro', ms=20, label="Class 1")
plt.plot([0.0], [1.0], 'go', ms=20, label="Class 2")

(continues on next page)
plt.plot([0.0], [0.0], 'bo', ms=20, label="Class 3")

# Plot boundaries of unit simplex
plt.plot([0.0, 1.0, 0.0, 0.0], [0.0, 0.0, 1.0, 0.0], 'k', label="Simplex")

# Annotate points 6 points around the simplex, and mid point inside simplex
plt.annotate(r'($\frac{1}{3}$, $\frac{1}{3}$, $\frac{1}{3}$)', xy=(1.0/3, 1.0/3), xytext=(1.0/3, .23), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.plot([1.0/3], [1.0/3], 'ko', ms=5)
plt.annotate(r'($\frac{1}{2}$, 0, $\frac{1}{2}$)', xy=(.5, .0), xytext=(.5, .1), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.annotate(r'(0, $\frac{1}{2}$, $\frac{1}{2}$)', xy=(.0, .5), xytext=(.1, .5), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.annotate(r'($\frac{1}{2}$, $\frac{1}{2}$, 0)', xy=(.5, .5), xytext=(.6, .6), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.annotate(r'(0, 0, 1)', xy=(0, 0), xytext=(.1, .1), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.annotate(r'(1, 0, 0)', xy=(1, 0), xytext=(1, .1), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')
plt.annotate(r'(0, 1, 0)', xy=(0, 1), xytext=(.1, 1), xycoords='data', arrowprops=dict(facecolor='black', shrink=0.05), horizontalalignment='center', verticalalignment='center')

# Add grid
plt.grid(False)

for x in [0.0, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.0]:
    plt.plot([0, x], [x, 0], 'k', alpha=0.2)
    plt.plot([0, 0 + (1-x)/2], [x, x + (1-x)/2], 'k', alpha=0.2)
    plt.plot([x, x + (1-x)/2], [0, 0 + (1-x)/2], 'k', alpha=0.2)

plt.title("Change of predicted probabilities on test samples "
"after sigmoid calibration")
plt.xlabel("Probability class 1")
plt.ylabel("Probability class 2")
plt.xlim(-0.05, 1.05)
plt.ylim(-0.05, 1.05)
_ = plt.legend(loc="best")
In the figure above, each vertex of the simplex represents a perfectly predicted class (e.g., 1, 0, 0). The mid point inside the simplex represents predicting the three classes with equal probability (i.e., 1/3, 1/3, 1/3). Each arrow starts at the uncalibrated probabilities and end with the arrow head at the calibrated probability. The color of the arrow represents the true class of that test sample.

The uncalibrated classifier is overly confident in its predictions and incurs a large log loss. The calibrated classifier incurs a lower log loss due to two factors. First, notice in the figure above that the arrows generally point away from the edges of the simplex, where the probability of one class is 0. Second, a large proportion of the arrows point towards the true class, e.g., green arrows (samples where the true class is ‘green’) generally point towards the green vertex. This results in fewer over-confident, 0 predicted probabilities and at the same time an increase in the the predicted probabilities of the correct class. Thus, the calibrated classifier produces more accurate predicted probabilities that incur a lower log loss

We can show this objectively by comparing the log loss of the uncalibrated and calibrated classifiers on the predictions of the 1000 test samples. Note that an alternative would have been to increase the number of base estimators (trees) of
the :class:`RandomForestClassifier` which would have resulted in a similar decrease in log loss.

```python
from sklearn.metrics import log_loss

score = log_loss(y_test, clf_probs)
cal_score = log_loss(y_test, cal_clf_probs)

print("Log-loss of")
print(f" * uncalibrated classifier: {score:.3f}\n")
print(f" * calibrated classifier: {cal_score:.3f}\n")
```

Out:

```
Log-loss of
 * uncalibrated classifier: 1.290
 * calibrated classifier: 0.549
```

Finally we generate a grid of possible uncalibrated probabilities over the 2-simplex, compute the corresponding calibrated probabilities and plot arrows for each. The arrows are colored according the highest uncalibrated probability. This illustrates the learned calibration map:

```python
plt.figure(figsize=(10, 10))
# Generate grid of probability values
p1d = np.linspace(0, 1, 20)
p0, p1 = np.meshgrid(p1d, p1d)
p2 = 1 - p0 - p1
p = np.c_[p0.ravel(), p1.ravel(), p2.ravel()]
p = p[p[:, 2] >= 0]

# Use the three class-wise calibrators to compute calibrated probabilities
calibrated_classifier = cal_clf.calibrated_classifiers_[0]
prediction = np.vstack([calibrator.predict(this_p)
                        for calibrator, this_p in
                        zip(calibrated_classifier.calibrators, p.T)]).T

# Re-normalize the calibrated predictions to make sure they stay inside the
# simplex. This same renormalization step is performed internally by the
# predict method of CalibratedClassifierCV on multiclass problems.
prediction /= prediction.sum(axis=1)[:, None]

# Plot changes in predicted probabilities induced by the calibrators
for i in range(prediction.shape[0]):
    plt.arrow(p[i, 0], p[i, 1],
              prediction[i, 0] - p[i, 0], prediction[i, 1] - p[i, 1],
              head_width=1e-2, color=colors[np.argmax(p[i])])

# Plot the boundaries of the unit simplex
plt.plot([0.0, 1.0, 0.0, 0.0], [0.0, 0.0, 1.0, 0.0], 'k', label="Simplex")
plt.grid(False)
for x in [0.0, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.0]:
    plt.plot([x, x + (1-x)/2], [0, 0 + (1-x)/2], 'k', alpha=0.2)
plt.title("Learned sigmoid calibration map")
plt.xlabel("Probability class 1")
plt.ylabel("Probability class 2")
```
plt.xlim(-0.05, 1.05)
plt.ylim(-0.05, 1.05)
plt.show()

6.3. Calibration

Total running time of the script: 0 minutes 1.855 seconds
6.4 Classification

General examples about classification algorithms.

6.4.1 Recognizing hand-written digits

This example shows how scikit-learn can be used to recognize images of hand-written digits, from 0-9.

```python
print(__doc__)

# Author: Gael Varoquaux <gael dot varoquaux at normalesup dot org>
# License: BSD 3 clause

# Standard scientific Python imports
import matplotlib.pyplot as plt

# Import datasets, classifiers and performance metrics
from sklearn import datasets, svm, metrics
from sklearn.model_selection import train_test_split

digits = datasets.load_digits()
_, axes = plt.subplots(nrows=1, ncols=4, figsize=(10, 3))
for ax, image, label in zip(axes, digits.images, digits.target):
    ax.set_axis_off()
    ax.imshow(image, cmap=plt.cm.gray_r, interpolation='nearest')
    ax.set_title('Training: %i' % label)
```

Digits dataset

The digits dataset consists of 8x8 pixel images of digits. The images attribute of the dataset stores 8x8 arrays of grayscale values for each image. We will use these arrays to visualize the first 4 images. The target attribute of the dataset stores the digit each image represents and this is included in the title of the 4 plots below.

Note: if we were working from image files (e.g., ‘png’ files), we would load them using matplotlib.pyplot.imread.

```python
digits = datasets.load_digits()
_, axes = plt.subplots(nrows=1, ncols=4, figsize=(10, 3))
for ax, image, label in zip(axes, digits.images, digits.target):
    ax.set_axis_off()
    ax.imshow(image, cmap=plt.cm.gray_r, interpolation='nearest')
    ax.set_title('Training: %i' % label)
```
Classification

To apply a classifier on this data, we need to flatten the images, turning each 2-D array of grayscale values from shape $(8, 8)$ into shape $(64,)$. Subsequently, the entire dataset will be of shape $(n_samples, n_features)$, where $n_samples$ is the number of images and $n_features$ is the total number of pixels in each image.

We can then split the data into train and test subsets and fit a support vector classifier on the train samples. The fitted classifier can subsequently be used to predict the value of the digit for the samples in the test subset.

```python
# flatten the images
n_samples = len(digits.images)
data = digits.images.reshape((n_samples, -1))

# Create a classifier: a support vector classifier
clf = svm.SVC(gamma=0.001)

# Split data into 50% train and 50% test subsets
X_train, X_test, y_train, y_test = train_test_split(data, digits.target, test_size=0.5, shuffle=False)

# Learn the digits on the train subset
clf.fit(X_train, y_train)

# Predict the value of the digit on the test subset
predicted = clf.predict(X_test)

Below we visualize the first 4 test samples and show their predicted digit value in the title.

```python
_, axes = plt.subplots(nrows=1, ncols=4, figsize=(10, 3))
for ax, image, prediction in zip(axes, digits.images, predicted):
    ax.set_axis_off()
    ax.imshow(image, cmap=plt.cm.gray_r, interpolation='nearest')
    ax.set_title(f'Prediction: {prediction}')
```

classification_report builds a text report showing the main classification metrics.

```python
print(f"Classification report for classifier {clf}:
metrics.classification_report(y_test, predicted)"
)
```

Out:

```
Classification report for classifier SVC(gamma=0.001):
              precision    recall  f1-score   support

```

(continues on next page)
We can also plot a confusion matrix of the true digit values and the predicted digit values.

disp = metrics.plot_confusion_matrix(clf, X_test, y_test)
disp.figure_.suptitle("Confusion Matrix")
print(f"Confusion matrix:

{disp.confusion_matrix}
")
plt.show()
Confusion matrix:

```
[[87  0  0  0  1  0  0  0  0  0]
 [ 0 88  1  0  0  0  0  0  1  1]
 [ 0  0 85  1  0  0  0  0  0  0]
 [ 0  0  0 79  0  3  0  4  5  0]
 [ 0  0  0  88  0  0  0  0  0  4]
 [ 0  0  0  0  88  1  0  0  2  0]
 [ 0  1  0  0  0  0 90  0  0  0]
 [ 0  0  0  0  0 1  0 88  0  0]
 [ 0  0  0  0  0  0  0  0 88  0]
 [ 0  0  1  0  1  0  0  0  0 90]]
```

**Total running time of the script:** (0 minutes 0.793 seconds)

### 6.4.2 Normal, Ledoit-Wolf and OAS Linear Discriminant Analysis for classification

This example illustrates how the Ledoit-Wolf and Oracle Shrinkage Approximating (OAS) estimators of covariance can improve classification.

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_blobs
from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
```
from sklearn.covariance import OAS

n_train = 20  # samples for training
n_test = 200  # samples for testing
n_averages = 50  # how often to repeat classification
n_features_max = 75  # maximum number of features
step = 4  # step size for the calculation

def generate_data(n_samples, n_features):
    """Generate random blob-ish data with noisy features.
    This returns an array of input data with shape '(n_samples, n_features)'
    and an array of 'n_samples' target labels.
    Only one feature contains discriminative information, the other features
    contain only noise.
    ""
    X, y = make_blobs(n_samples=n_samples, n_features=1, centers=[[-2], [2]])
    # add non-discriminative features
    if n_features > 1:
        X = np.hstack((X, np.random.randn(n_samples, n_features - 1)))
    return X, y

acc_clf1, acc_clf2, acc_clf3 = [], [], []
n_features_range = range(1, n_features_max + 1, step)
for n_features in n_features_range:
    score_clf1, score_clf2, score_clf3 = 0, 0, 0
    for _ in range(n_averages):
        X, y = generate_data(n_train, n_features)
        clf1 = LinearDiscriminantAnalysis(solver='lsqr',
                                           shrinkage='auto').fit(X, y)
        clf2 = LinearDiscriminantAnalysis(solver='lsqr',
                                           shrinkage=None).fit(X, y)
        oa = OAS(store_precision=False, assume_centered=False)
        clf3 = LinearDiscriminantAnalysis(solver='lsqr',
                                           covariance_estimator=oa).fit(X, y)

        X, y = generate_data(n_test, n_features)
        score_clf1 += clf1.score(X, y)
        score_clf2 += clf2.score(X, y)
        score_clf3 += clf3.score(X, y)

    acc_clf1.append(score_clf1 / n_averages)
    acc_clf2.append(score_clf2 / n_averages)
    acc_clf3.append(score_clf3 / n_averages)

features_samples_ratio = np.array(n_features_range) / n_train
plt.plot(features_samples_ratio, acc_clf1, linewidth=2,
          label="Linear Discriminant Analysis with Ledoit Wolf", color='navy')
plt.plot(features_samples_ratio, acc_clf2, linewidth=2,
          label="Linear Discriminant Analysis", color='gold')
plt.plot(features_samples_ratio, acc_clf3, linewidth=2,
       label="Linear Discriminant Analysis with OAS", color='red')
plt.xlabel('n_features / n_samples')
plt.ylabel('Classification accuracy')
plt.legend(loc=3, prop={'size': 12})
plt.suptitle('Linear Discriminant Analysis vs. ' + '
            Shrinkage Linear Discriminant Analysis vs. ' + '
            OAS Linear Discriminant Analysis (1 discriminative feature)')
plt.show()

**Total running time of the script:** ( 0 minutes 6.352 seconds)

### 6.4.3 Plot classification probability

Plot the classification probability for different classifiers. We use a 3 class dataset, and we classify it with a Support Vector classifier, L1 and L2 penalized logistic regression with either a One-Vs-Rest or multinomial setting, and Gaussian process classification.

Linear SVC is not a probabilistic classifier by default but it has a built-in calibration option enabled in this example (probability=True).

The logistic regression with One-Vs-Rest is not a multiclass classifier out of the box. As a result it has more trouble in separating class 2 and 3 than the other estimators.
Out:

Accuracy (train) for L1 logistic: 83.3%
Accuracy (train) for L2 logistic (Multinomial): 82.7%
Accuracy (train) for L2 logistic (OvR): 79.3%
Accuracy (train) for Linear SVC: 82.0%
Accuracy (train) for GPC: 82.7%

print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

import matplotlib.pyplot as plt
import numpy as np
from sklearn.metrics import accuracy_score
from sklearn.linear_model import LogisticRegression
from sklearn.svm import SVC
from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.gaussian_process.kernels import RBF
from sklearn import datasets

iris = datasets.load_iris()
X = iris.data[:, 0:2]  # we only take the first two features for visualization
y = iris.target

n_features = X.shape[1]

C = 10
kernel = 1.0 * RBF([1.0, 1.0])  # for GPC

# Create different classifiers.
classifiers = {
    'L1 logistic': LogisticRegression(C=C, penalty='l1',
                                       solver='saga',
                                       multi_class='multinomial',
                                       max_iter=10000),
    'L2 logistic (Multinomial)': LogisticRegression(C=C, penalty='l2',
                                                solver='saga',
                                                multi_class='multinomial',
                                                max_iter=10000),
    'L2 logistic (OvR)': LogisticRegression(C=C, penalty='l2',
                                             solver='saga',
                                             multi_class='ovr',
                                             max_iter=10000),
    'Linear SVC': SVC(kernel='linear', C=C, probability=True,
                       random_state=0),
    'GPC': GaussianProcessClassifier(kernel)
}

n_classifiers = len(classifiers)

(continues on next page)
plt.figure(figsize=(3 * 2, n_classifiers * 2))
plt.subplots_adjust(bottom=.2, top=.95)

xx = np.linspace(3, 9, 100)
yy = np.linspace(1, 5, 100).T
xx, yy = np.meshgrid(xx, yy)
Xfull = np.c_[xx.ravel(), yy.ravel()]

for index, (name, classifier) in enumerate(classifiers.items()):
    classifier.fit(X, y)
    y_pred = classifier.predict(X)
    accuracy = accuracy_score(y, y_pred)
    print("Accuracy (train) for %s: %.1f%%") % (name, accuracy * 100)

    # View probabilities:
    probas = classifier.predict_proba(Xfull)
    n_classes = np.unique(y_pred).size
    for k in range(n_classes):
        plt.subplot(n_classifiers, n_classes, index * n_classes + k + 1)
        plt.title("Class %d" % k)
        if k == 0:
            plt.ylabel(name)
        imshow_handle = plt.imshow(probas[:, k].reshape((100, 100)),
                                   extent=(3, 9, 1, 5), origin='lower')
        plt.xticks(()), plt.yticks(())
        idx = (y_pred == k)
        if idx.any():
            plt.scatter(X[idx, 0], X[idx, 1], marker='o', c='w', edgecolor='k')

ax = plt.axes([0.15, 0.04, 0.7, 0.05])
plt.title("Probability")
plt.colorbar(imshow_handle, cax=ax, orientation='horizontal')
plt.show()

Total running time of the script: ( 0 minutes 1.323 seconds)

6.4.4 Classifier comparison

A comparison of a several classifiers in scikit-learn on synthetic datasets. The point of this example is to illustrate the nature of decision boundaries of different classifiers. This should be taken with a grain of salt, as the intuition conveyed by these examples does not necessarily carry over to real datasets.

Particularly in high-dimensional spaces, data can more easily be separated linearly and the simplicity of classifiers such as naive Bayes and linear SVMs might lead to better generalization than is achieved by other classifiers.

The plots show training points in solid colors and testing points semi-transparent. The lower right shows the classification accuracy on the test set.
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
from sklearn.datasets import make_moons, make_circles, make_classification
from sklearn.neural_network import MLPClassifier
from sklearn.neighbors import KNeighborsClassifier
from sklearn.svm import SVC
from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.gaussian_process.kernels import RBF
from sklearn.tree import DecisionTreeClassifier
from sklearn.ensemble import RandomForestClassifier, AdaBoostClassifier
from sklearn.naive_bayes import GaussianNB
from sklearn.discriminant_analysis import QuadraticDiscriminantAnalysis

h = .02  # step size in the mesh


classifiers = [
    KNeighborsClassifier(3),
    SVC(kernel="linear", C=0.025),
    SVC(gamma=2, C=1),
    GaussianProcessClassifier(1.0 * RBF(1.0)),
    DecisionTreeClassifier(max_depth=5),
    RandomForestClassifier(max_features=10, max_features=1),
    MLPClassifier(alpha=1, max_iter=1000),
    AdaBoostClassifier(),
    GaussianNB(),
    QuadraticDiscriminantAnalysis()]

X, y = make_classification(n_features=2, n_redundant=0, n_informative=2,
random_state=1, n_clusters_per_class=1)

rng = np.random.RandomState(2)
X += 2 * rng.uniform(size=X.shape)
linearly_separable = (X, y)

datasets = [make_moons(noise=0.3, random_state=0),
            make_circles(noise=0.2, factor=0.5, random_state=1),
            linearly_separable]

figure = plt.figure(figsize=(27, 9))
i = 1
# iterate over datasets
for ds_cnt, ds in enumerate(datasets):
    # preprocess dataset, split into training and test part
    X, y = ds
    X = StandardScaler().fit_transform(X)
    X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=.4, random_state=42)
    x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
    y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
    xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                         np.arange(y_min, y_max, h))

    # just plot the dataset first
    cm = plt.cm.RdBu
    cm_bright = ListedColormap(['#FF0000', '#0000FF'])
    ax = plt.subplot(len(datasets), len(classifiers) + 1, i)
    if ds_cnt == 0:
        ax.set_title("Input data")
    # Plot the training points
    ax.scatter(X_train[:, 0], X_train[:, 1], c=y_train, cmap=cm_bright,
               edgecolors='k')
    # Plot the testing points
    ax.scatter(X_test[:, 0], X_test[:, 1], c=y_test, cmap=cm_bright, alpha=0.6,
               edgecolors='k')
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xticks(())
    ax.set_yticks(())
    i += 1

# iterate over classifiers
for name, clf in zip(names, classifiers):
    ax = plt.subplot(len(datasets), len(classifiers) + 1, i)
    clf.fit(X_train, y_train)
    score = clf.score(X_test, y_test)

    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]x[y_min, y_max].
    if hasattr(clf, "decision_function"):
        Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
    else:
        Z = clf.predict_proba(np.c_[xx.ravel(), yy.ravel()])[:, 1]

    # Put the result into a color plot
(continues on next page)
Z = Z.reshape(xx.shape)
ax.contourf(xx, yy, Z, cmap=cm, alpha=.8)

# Plot the training points
ax.scatter(X_train[:, 0], X_train[:, 1], c=y_train, cmap=cm_bright,
edgecolors='k')
# Plot the testing points
ax.scatter(X_test[:, 0], X_test[:, 1], c=y_test, cmap=cm_bright,
edgecolors='k', alpha=0.6)

ax.set_xlim(xx.min(), xx.max())
ax.set_ylim(yy.min(), yy.max())
ax.set_xticks(())
ax.set_yticks(())
if ds_cnt == 0:
    ax.set_title(name)
    ax.text(xx.max() - .3, yy.min() + .3, ('%.2f' % score).lstrip('0'),
    size=15, horizontalalignment='right')
i += 1

plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 5.506 seconds)

6.4.5 Linear and Quadratic Discriminant Analysis with covariance ellipsoid

This example plots the covariance ellipsoids of each class and decision boundary learned by LDA and QDA. The ellipsoids display the double standard deviation for each class. With LDA, the standard deviation is the same for all the classes, while each class has its own standard deviation with QDA.
Linear Discriminant Analysis vs Quadratic Discriminant Analysis

Data with fixed covariance

Data with varying covariance

Out:

```
/home/circleci/project/examples/classification/plot_lda_qda.py:93:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',
/home/circleci/project/examples/classification/plot_lda_qda.py:93:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',
/home/circleci/project/examples/classification/plot_lda_qda.py:93:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',
/home/circleci/project/examples/classification/plot_lda_qda.py:93:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',
```

(continues on next page)
plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',

print(__doc__)

from scipy import linalg
import numpy as np
import matplotlib.pyplot as plt
import matplotlib as mpl
from matplotlib import colors
from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
from sklearn.discriminant_analysis import QuadraticDiscriminantAnalysis

# #############################################################################
# Colormap
cmap = colors.LinearSegmentedColormap(
    'red_blue_classes',
    {'red': [(0, 1, 1), (1, 0.7, 0.7)],
     'green': [(0, 0.7, 0.7), (1, 0.7, 0.7)],
     'blue': [(0, 0.7, 0.7), (1, 1, 1)]}
plt.cm.register_cmap(cmap=cmap)

# #############################################################################
# Generate datasets

def dataset_fixed_cov():
    '''Generate 2 Gaussians samples with the same covariance matrix'''
    n, dim = 300, 2
    np.random.seed(0)
    C = np.array([[0., -0.23], [0.83, 0.23]])
    X = np.r_[np.dot(np.random.randn(n, dim), C),
              np.dot(np.random.randn(n, dim), C) + np.array([1, 1])]
    y = np.hstack((np.zeros(n), np.ones(n)))
    return X, y

def dataset_cov():
    '''Generate 2 Gaussians samples with different covariance matrices'''
    n, dim = 300, 2
    np.random.seed(0)
    C = np.array([[0., -1.], [2.5, 0.7]]) + 2.
    X = np.r_[np.dot(np.random.randn(n, dim), C),
              np.dot(np.random.randn(n, dim), C.T) + np.array([1, 4])]
    y = np.hstack((np.zeros(n), np.ones(n)))
    return X, y

# # # # # # # # # # # # # # # # # # # # # # # # # # # # #
# Plot functions

def plot_data(lda, X, y, y_pred, fig_index):
    splot = plt.subplot(2, 2, fig_index)
if fig_index == 1:
    plt.title('Linear Discriminant Analysis')
    plt.ylabel('Data with
fixed covariance')
elif fig_index == 2:
    plt.title('Quadratic Discriminant Analysis')
elif fig_index == 3:
    plt.ylabel('Data with
varying covariances')

tp = (y == y_pred)  # True Positive
tp0, tp1 = tp[y == 0], tp[y == 1]
X0, X1 = X[y == 0], X[y == 1]
X0_tp, X0_fp = X0[tp0], X0[~tp0]
X1_tp, X1_fp = X1[tp1], X1[~tp1]

# class 0: dots
plt.scatter(X0_tp[:, 0], X0_tp[:, 1], marker='.', color='red')
plt.scatter(X0_fp[:, 0], X0_fp[:, 1], marker='x',
            s=20, color='#990000')  # dark red

# class 1: dots
plt.scatter(X1_tp[:, 0], X1_tp[:, 1], marker='.', color='blue')
plt.scatter(X1_fp[:, 0], X1_fp[:, 1], marker='x',
            s=20, color='#000099')  # dark blue

# class 0 and 1 : areas
nx, ny = 200, 100
x_min, x_max = plt.xlim()
y_min, y_max = plt.ylim()
xx, yy = np.meshgrid(np.linspace(x_min, x_max, nx),
                     np.linspace(y_min, y_max, ny))
Z = lda.predict_proba(np.c_[xx.ravel(), yy.ravel()])
Z = Z[:, 1].reshape(xx.shape)
plt.pcolormesh(xx, yy, Z, cmap='red_blue_classes',
               norm=colors.Normalize(0., 1.), zorder=0)
plt.contour(xx, yy, Z, [0.5], linewidths=2., colors='white')

# means
plt.plot(lda.means_[0][0], lda.means_[0][1],
         '*', color='yellow', markersize=15, markeredgecolor='grey')
plt.plot(lda.means_[1][0], lda.means_[1][1],
         '*', color='yellow', markersize=15, markeredgecolor='grey')

return splot

def plot_ellipse(splot, mean, cov, color):
    v, w = linalg.eigh(cov)
    u = w[0] / linalg.norm(w[0])
    angle = np.arctan(u[1] / u[0])
    angle = 180 * angle / np.pi  # convert to degrees
    # filled Gaussian at 2 standard deviation
    ell = mpl.patches.Ellipse(mean, 2 * v[0] ** 0.5, 2 * v[1] ** 0.5,
                               180 + angle, facecolor=color,
                               edgecolor='black', linewidth=2)
    ell.set_clip_box(splot.bbox)
    ell.set_alpha(0.2)
    splot.add_artist(ell)
splot.set_xticks(()
        splot.set_yticks(()

    def plot_lda_cov(lda, splot):
        plot_ellipse(splot, lda.means_[0], lda.covariance_, 'red')
        plot_ellipse(splot, lda.means_[1], lda.covariance_, 'blue')

    def plot_qda_cov(qda, splot):
        plot_ellipse(splot, qda.means_[0], qda.covariance_[0], 'red')
        plot_ellipse(splot, qda.means_[1], qda.covariance_[1], 'blue')

    plt.figure(figsize=(10, 8), facecolor='white')
    plt.suptitle('Linear Discriminant Analysis vs Quadratic Discriminant Analysis',
                 y=0.98, fontsize=15)
    for i, (X, y) in enumerate([dataset_fixed_cov(), dataset_cov()]):
        # Linear Discriminant Analysis
        lda = LinearDiscriminantAnalysis(solver="svd", store_covariance=True)
        y_pred = lda.fit(X, y).predict(X)
        splot = plot_data(lda, X, y, y_pred, fig_index=2 * i + 1)
        plot_lda_cov(lda, splot)
        plt.axis('tight')

        # Quadratic Discriminant Analysis
        qda = QuadraticDiscriminantAnalysis(store_covariance=True)
        y_pred = qda.fit(X, y).predict(X)
        splot = plot_data(qda, X, y, y_pred, fig_index=2 * i + 2)
        plot_qda_cov(qda, splot)
        plt.axis('tight')
    plt.tight_layout()
    plt.subplots_adjust(top=0.92)
    plt.show()

Total running time of the script: ( 0 minutes 0.325 seconds)

6.5 Clustering

Examples concerning the sklearn.cluster module.

6.5.1 An example of K-Means++ initialization

An example to show the output of the sklearn.cluster.kmeans_plusplus function for generating initial seeds for clustering.

K-Means++ is used as the default initialization for K-means.
from sklearn.cluster import kmeans_plusplus
from sklearn.datasets import make_blobs
import matplotlib.pyplot as plt

# Generate sample data
n_samples = 4000
n_components = 4

X, y_true = make_blobs(n_samples=n_samples,
                        centers=n_components,
                        cluster_std=0.60,
                        random_state=0)
X = X[:, ::-1]

# Calculate seeds from kmeans++
centers_init, indices = kmeans_plusplus(X, n_clusters=4,
                                        random_state=0)

# Plot init seeds along side sample data
plt.figure(1)
colors = ['#4EACC5', '#FF9C34', '#4E9A06', 'm']

for k, col in enumerate(colors):
    (continues on next page)
This example plots the corresponding dendrogram of a hierarchical clustering using AgglomerativeClustering and the dendrogram method available in scipy.

import numpy as np
from matplotlib import pyplot as plt
from scipy.cluster.hierarchy import dendrogram
from sklearn.datasets import load_iris
from sklearn.cluster import AgglomerativeClustering

Total running time of the script: ( 0 minutes 0.073 seconds)
def plot_dendrogram(model, **kwargs):
    # Create linkage matrix and then plot the dendrogram

    # create the counts of samples under each node
    counts = np.zeros(model.children_.shape[0])
    n_samples = len(model.labels_)
    for i, merge in enumerate(model.children_):
        current_count = 0
        for child_idx in merge:
            if child_idx < n_samples:
                current_count += 1  # leaf node
            else:
                current_count += counts[child_idx - n_samples]
        counts[i] = current_count

    linkage_matrix = np.column_stack([model.children_, model.distances_,
                                       counts]).astype(float)

    # Plot the corresponding dendrogram
    dendrogram(linkage_matrix, **kwargs)

iris = load_iris()
X = iris.data

# setting distance_threshold=0 ensures we compute the full tree.
model = AgglomerativeClustering(distance_threshold=0, n_clusters=None)
model = model.fit(X)
plt.title('Hierarchical Clustering Dendrogram')
# plot the top three levels of the dendrogram
plot_dendrogram(model, truncate_mode='level', p=3)
plt.xlabel("Number of points in node (or index of point if no parenthesis).")
plt.show()
import numpy as np
import matplotlib.pyplot as plt

from sklearn import datasets, cluster
from sklearn.feature_extraction.image import grid_to_graph

digits = datasets.load_digits()
images = digits.images
X = np.reshape(images, (len(images), -1))
connectivity = grid_to_graph(*images[0].shape)

agglo = cluster.FeatureAgglomeration(connectivity=connectivity,
n_clusters=32)

agglo.fit(X)
X_reduced = agglo.transform(X)
X_restored = agglo.inverse_transform(X_reduced)
images_restored = np.reshape(X_restored, images.shape)

plt.figure(1, figsize=(4, 3.5))
plt.clf()
plt.subplots_adjust(left=.01, right=.99, bottom=.01, top=.91)
for i in range(4):
    plt.subplot(3, 4, i + 1)
    plt.imshow(images[i], cmap=plt.cm.gray, vmax=16, interpolation='nearest')
    plt.xticks(())
    plt.yticks(())
    if i == 1:
        (continues on next page)
6.5.4 A demo of the mean-shift clustering algorithm

Reference:
```
import numpy as np
from sklearn.cluster import MeanShift, estimate_bandwidth
from sklearn.datasets import make_blobs

# #############################################################################
# Generate sample data
centers = [[1, 1], [-1, -1], [1, -1]]
X, _ = make_blobs(n_samples=10000, centers=centers, cluster_std=0.6)

# #############################################################################
# Compute clustering with MeanShift
# The following bandwidth can be automatically detected using
bandwidth = estimate_bandwidth(X, quantile=0.2, n_samples=500)
```

```
print(__doc__)

number of estimated clusters : 3
```

Estimated number of clusters: 3
ms = MeanShift(bandwidth=bandwidth, bin_seeding=True)
ms.fit(X)
labels = ms.labels_
cluster_centers = ms.cluster_centers_

labels_unique = np.unique(labels)
n_clusters_ = len(labels_unique)

print("number of estimated clusters : %d" % n_clusters_)

# #############################################################################
# Plot result
import matplotlib.pyplot as plt
from itertools import cycle

plt.figure(1)
plt.clf()

for k, col in zip(range(n_clusters_), colors):
    my_members = labels == k
    cluster_center = cluster_centers[k]
    plt.plot(X[my_members, 0], X[my_members, 1], col + '.')
    plt.plot(cluster_center[0], cluster_center[1], 'o', markerfacecolor=col,
             markeredgecolor='k', markersize=14)
plt.title('Estimated number of clusters: %d' % n_clusters_)
plt.show()

Total running time of the script: ( 0 minutes 0.517 seconds)

6.5.5 Demonstration of k-means assumptions

This example is meant to illustrate situations where k-means will produce unintuitive and possibly unexpected clusters. In the first three plots, the input data does not conform to some implicit assumption that k-means makes and undesirable clusters are produced as a result. In the last plot, k-means returns intuitive clusters despite unevenly sized blobs.
print(__doc__)

# Author: Phil Roth <mr.phil.roth@gmail.com>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn.cluster import KMeans
from sklearn.datasets import make_blobs

plt.figure(figsize=(12, 12))
n_samples = 1500

(continues on next page)
random_state = 170
X, y = make_blobs(n_samples=n_samples, random_state=random_state)

# Incorrect number of clusters
y_pred = KMeans(n_clusters=2, random_state=random_state).fit_predict(X)

plt.subplot(221)
plt.scatter(X[:, 0], X[:, 1], c=y_pred)
plt.title("Incorrect Number of Blobs")

# Anisotropicly distributed data
transformation = [[0.60834549, -0.63667341], [-0.40887718, 0.85253229]]
X_aniso = np.dot(X, transformation)
y_pred = KMeans(n_clusters=3, random_state=random_state).fit_predict(X_aniso)

plt.subplot(222)
plt.scatter(X_aniso[:, 0], X_aniso[:, 1], c=y_pred)
plt.title("Anisotropicly Distributed Blobs")

# Different variance
X_varied, y_varied = make_blobs(n_samples=n_samples, cluster_std=[1.0, 2.5, 0.5], random_state=random_state)
y_pred = KMeans(n_clusters=3, random_state=random_state).fit_predict(X_varied)

plt.subplot(223)
plt.scatter(X_varied[:, 0], X_varied[:, 1], c=y_pred)
plt.title("Unequal Variance")

# Unevenly sized blobs
X_filtered = np.vstack((X[y == 0][:500], X[y == 1][:100], X[y == 2][:10]))
y_pred = KMeans(n_clusters=3, random_state=random_state).fit_predict(X_filtered)

plt.subplot(224)
plt.scatter(X_filtered[:, 0], X_filtered[:, 1], c=y_pred)
plt.title("Unevenly Sized Blobs")

plt.show()

Total running time of the script: ( 0 minutes 0.452 seconds)

6.5.6 Online learning of a dictionary of parts of faces

This example uses a large dataset of faces to learn a set of 20 x 20 images patches that constitute faces.

From the programming standpoint, it is interesting because it shows how to use the online API of the scikit-learn to process a very large dataset by chunks. The way we proceed is that we load an image at a time and extract randomly 50 patches from this image. Once we have accumulated 500 of these patches (using 10 images), we run the `partial_fit` method of the online KMeans object, MiniBatchKMeans.

The verbose setting on the MiniBatchKMeans enables us to see that some clusters are reassigned during the successive calls to partial-fit. This is because the number of patches that they represent has become too low, and it is better to choose a random new cluster.
Patches of faces
Train time 1.8s on 3200 patches

Out:

Learning the dictionary...
Partial fit of 100 out of 2400
Partial fit of 200 out of 2400
Partial fit of 300 out of 2400
Partial fit of 400 out of 2400
Partial fit of 500 out of 2400
Partial fit of 600 out of 2400
Partial fit of 700 out of 2400
Partial fit of 800 out of 2400
Partial fit of 900 out of 2400
Partial fit of 1000 out of 2400
Partial fit of 1100 out of 2400
Partial fit of 1200 out of 2400
Partial fit of 1300 out of 2400
Partial fit of 1400 out of 2400
Partial fit of 1500 out of 2400
Partial fit of 1600 out of 2400
Partial fit of 1700 out of 2400
Partial fit of 1800 out of 2400
Partial fit of 1900 out of 2400
Partial fit of 2000 out of 2400
Partial fit of 2100 out of 2400
Partial fit of 2200 out of 2400
Partial fit of 2300 out of 2400
Partial fit of 2400 out of 2400
done in 1.76s.
import time

import matplotlib.pyplot as plt
import numpy as np

from sklearn import datasets
from sklearn.cluster import MiniBatchKMeans
from sklearn.feature_extraction.image import extract_patches_2d

faces = datasets.fetch_olivetti_faces()

# #############################################################################
# Learn the dictionary of images
# print('Learning the dictionary...')
rng = np.random.RandomState(0)
kmeans = MiniBatchKMeans(n_clusters=81, random_state=rng, verbose=True)
patch_size = (20, 20)
buffer = []
t0 = time.time()
# The online learning part: cycle over the whole dataset 6 times
index = 0
for _ in range(6):
    for img in faces.images:
        data = extract_patches_2d(img, patch_size, max_patches=50,
                                  random_state=rng)
        data = np.reshape(data, (len(data), -1))
        buffer.append(data)
        index += 1
        if index % 10 == 0:
            data = np.concatenate(buffer, axis=0)
            data -= np.mean(data, axis=0)
            data /= np.std(data, axis=0)
            kmeans.partial_fit(data)
            buffer = []
            if index % 100 == 0:
                print('Partial fit of %4i out of %i' % (index, 6 * len(faces.images)))
dt = time.time() - t0
print('done in %.2fs.' % dt)

# #############################################################################
# Plot the results
plt.figure(figsize=(4.2, 4))
for i, patch in enumerate(kmeans.cluster_centers_):
    plt.subplot(9, 9, i + 1)
    plt.imshow(patch.reshape(patch_size), cmap=plt.cm.gray,
               interpolation='nearest')
6.5.7 Vector Quantization Example

Face, a 1024 x 768 size image of a raccoon face, is used here to illustrate how \( k \)-means is used for vector quantization.
```python
# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

import numpy as np
import scipy as sp
import matplotlib.pyplot as plt
from sklearn import cluster

try:  # SciPy >= 0.16 have face in misc
    from scipy.misc import face
    face = face(gray=True)
except ImportError:
    face = sp.face(gray=True)

n_clusters = 5
np.random.seed(0)

X = face.reshape((-1, 1))  # We need an (n_sample, n_feature) array
k_means = cluster.KMeans(n_clusters=n_clusters, n_init=4)
k_means.fit(X)
values = k_means.cluster_centers_.squeeze()
```

(continues on next page)
labels = k_means.labels_

# create an array from labels and values
face_compressed = np.choose(labels, values)
face_compressed.shape = face.shape

vmin = face.min()
vmax = face.max()

# original face
plt.figure(1, figsize=(3, 2.2))
plt.imshow(face, cmap=plt.cm.gray, vmin=vmin, vmax=256)

# compressed face
plt.figure(2, figsize=(3, 2.2))
plt.imshow(face_compressed, cmap=plt.cm.gray, vmin=vmin, vmax=vmax)

# equal bins face
regular_values = np.linspace(0, 256, n_clusters + 1)
regular_labels = np.searchsorted(regular_values, face) - 1
regular_values = .5 * (regular_values[1:] + regular_values[:-1])  # mean
regular_face = np.choose(regular_labels.ravel(), regular_values, mode="clip")
regular_face.shape = face.shape
plt.figure(3, figsize=(3, 2.2))
plt.imshow(regular_face, cmap=plt.cm.gray, vmin=vmin, vmax=vmax)

# histogram
plt.figure(4, figsize=(3, 2.2))
plt.clf()
plt.axes([.01, .01, .98, .98])
plt.hist(X, bins=256, color='.5', edgecolor='.5')
plt.yticks(()
plt.xticks(regular_values)
values = np.sort(values)
for center_1, center_2 in zip(values[:-1], values[1:]):
    plt.axvline(.5 * (center_1 + center_2), color='b')
for center_1, center_2 in zip(regular_values[:-1], regular_values[1:]):
    plt.axvline(.5 * (center_1 + center_2), color='b', linestyle='--')
plt.show()

Total running time of the script: ( 0 minutes 2.223 seconds)
6.5.8 Demo of affinity propagation clustering algorithm


Out:

/home/circleci/project/sklearn/cluster/_affinity_propagation.py:148: FutureWarning:
    'random_state' has been introduced in 0.23. It will be set to None starting from 1.
    0 (renaming of 0.25) which means that results will differ at every function call.
    Set 'random_state' to None to silence this warning, or to 0 to keep the behavior of
    versions <0.23.
    warnings.warn(
Estimated number of clusters: 3
Homogeneity: 0.872
Completeness: 0.872
V-measure: 0.872
Adjusted Rand Index: 0.912
Adjusted Mutual Information: 0.871
Silhouette Coefficient: 0.753
from sklearn.cluster import AffinityPropagation
from sklearn import metrics
from sklearn.datasets import make_blobs

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

centers = [[1, 1], [-1, -1], [1, -1]]

X, labels_true = make_blobs(n_samples=300, centers=centers, cluster_std=0.5,
                           random_state=0)

af = AffinityPropagation(preference=-50).fit(X)

cluster_centers_indices = af.cluster_centers_indices_

labels = af.labels_

n_clusters_ = len(cluster_centers_indices)

print('Estimated number of clusters: %d' % n_clusters_)

print("Homogeneity: %0.3f" % metrics.homogeneity_score(labels_true, labels))

print("Completeness: %0.3f" % metrics.completeness_score(labels_true, labels))

print("V-measure: %0.3f" % metrics.v_measure_score(labels_true, labels))

print("Adjusted Rand Index: %0.3f" % metrics.adjusted_rand_score(labels_true, labels))

print("Adjusted Mutual Information: %0.3f" % metrics.adjusted_mutual_info_score(labels_true, labels))

print("Silhouette Coefficient: %0.3f" % metrics.silhouette_score(X, labels, metric='sqeuclidean'))

import matplotlib.pyplot as plt
from itertools import cycle

plt.close('all')
plt.figure(1)
plt.clf()

colors = cycle('bgrcmykbgrcmykbgrcmykbgrcmykbgrcmyk')

for k, col in zip(range(n_clusters_), colors):
    class_members = labels == k
    cluster_center = X[cluster_centers_indices[k]]
    plt.plot(X[class_members, 0], X[class_members, 1], col + '.
    plt.plot(cluster_center[0], cluster_center[1], 'o', markerfacecolor=col,
             markeredgecolor='k', markersize=14)
    for x in X[class_members]:
        plt.plot([cluster_center[0], x[0]], [cluster_center[1], x[1]], col)

plt.title('Estimated number of clusters: %d' % n_clusters_)
plt.show()
6.5.9 Agglomerative clustering with and without structure

This example shows the effect of imposing a connectivity graph to capture local structure in the data. The graph is simply the graph of 20 nearest neighbors.

Two consequences of imposing a connectivity can be seen. First clustering with a connectivity matrix is much faster. Second, when using a connectivity matrix, single, average and complete linkage are unstable and tend to create a few clusters that grow very quickly. Indeed, average and complete linkage fight this percolation behavior by considering all the distances between two clusters when merging them (while single linkage exaggerates the behavior by considering only the shortest distance between clusters). The connectivity graph breaks this mechanism for average and complete linkage, making them resemble the more brittle single linkage. This effect is more pronounced for very sparse graphs (try decreasing the number of neighbors in kneighbors_graph) and with complete linkage. In particular, having a very small number of neighbors in the graph, imposes a geometry that is close to that of single linkage, which is well known to have this percolation instability.
```python
import time
import matplotlib.pyplot as plt
import numpy as np

from sklearn.cluster import AgglomerativeClustering
from sklearn.neighbors import kneighbors_graph

# Generate sample data
n_samples = 1500
np.random.seed(0)
t = 1.5 * np.pi * (1 + 3 * np.random.rand(1, n_samples))
x = t * np.cos(t)
y = t * np.sin(t)

X = np.concatenate((x, y))
X += .7 * np.random.randn(2, n_samples)
X = X.T

# Create a graph capturing local connectivity. Larger number of neighbors
# will give more homogeneous clusters to the cost of computation
```

(continues on next page)
# time. A very large number of neighbors gives more evenly distributed
# cluster sizes, but may not impose the local manifold structure of
# the data
knn_graph = kneighbors_graph(X, 30, include_self=False)

for connectivity in (None, knn_graph):
    for n_clusters in (30, 3):
        for index, linkage in enumerate(('average',
                                          'complete',
                                          'ward',
                                          'single')):

            plt.figure(figsize=(10, 4))
            for index, linkage in enumerate(('average',
                                              'complete',
                                              'ward',
                                              'single')):

                plt.subplot(1, 4, index + 1)
                model = AgglomerativeClustering(linkage=linkage,
                                                  connectivity=connectivity,
                                                  n_clusters=n_clusters)

                t0 = time.time()
                model.fit(X)
                elapsed_time = time.time() - t0
                plt.scatter(X[:, 0], X[:, 1], c=model.labels_,
                            cmap=plt.cm.nipy_spectral)
                plt.title('linkage=%s
(time %.2f s)' % (linkage, elapsed_time),
                          fontdict=dict(verticalalignment='top'))
                plt.axis('equal')
                plt.axis('off')

plt.subplots_adjust(bottom=0, top=.83, wspace=0,
                    left=0, right=1)
plt.suptitle('n_cluster=%i, connectivity=%r' %
             (n_clusters, connectivity is not None), size=17)

plt.show()

Total running time of the script: ( 0 minutes 2.333 seconds)

6.5.10 Various Agglomerative Clustering on a 2D embedding of digits

An illustration of various linkage option for agglomerative clustering on a 2D embedding of the digits dataset.

The goal of this example is to show intuitively how the metrics behave, and not to find good clusters for the digits.
This is why the example works on a 2D embedding.

What this example shows us is the behavior “rich getting richer” of agglomerative clustering that tends to create uneven
cluster sizes. This behavior is pronounced for the average linkage strategy, that ends up with a couple of singleton
clusters, while in the case of single linkage we get a single central cluster with all other clusters being drawn from
noise points around the fringes.
6.5. Clustering

ward linkage

average linkage
Out:

Computing embedding
Done.

(continues on next page)
ward : 0.39s
average : 0.33s
complete : 0.32s
single : 0.06s

# Authors: Gael Varoquaux
# License: BSD 3 clause (C) INRIA 2014

print(__doc__)
from time import time
import numpy as np
from scipy import ndimage
from matplotlib import pyplot as plt
from sklearn import manifold, datasets

X, y = datasets.load_digits(return_X_y=True)
n_samples, n_features = X.shape
np.random.seed(0)

def nudge_images(X, y):
    # Having a larger dataset shows more clearly the behavior of the
    # methods, but we multiply the size of the dataset only by 2, as the
    # cost of the hierarchical clustering methods are strongly
    # super-linear in n_samples
    shift = lambda x: ndimage.shift(x.reshape((8, 8)),
        .3 * np.random.normal(size=2),
        mode='constant',
        ).ravel()
    X = np.concatenate([X, np.apply_along_axis(shift, 1, X)])
    Y = np.concatenate([y, y], axis=0)
    return X, Y

X, y = nudge_images(X, y)

#----------------------------------------------------------------------
# Visualize the clustering

def plot_clustering(X_red, labels, title=None):
    x_min, x_max = np.min(X_red, axis=0), np.max(X_red, axis=0)
    X_red = (X_red - x_min) / (x_max - x_min)

    plt.figure(figsize=(6, 4))
    for i in range(X_red.shape[0]):
        plt.text(X_red[i, 0], X_red[i, 1], str(y[i]),
            color=plcm.nipy_spectral(labels[i] / 10.),
            fontdict={'weight': 'bold', 'size': 9})
# 2D embedding of the digits dataset
print("Computing embedding")
X_red = manifold.SpectralEmbedding(n_components=2).fit_transform(X)
print("Done.")

from sklearn.cluster import AgglomerativeClustering

for linkage in ('ward', 'average', 'complete', 'single'):
    clustering = AgglomerativeClustering(linkage=linkage, n_clusters=10)
    t0 = time()
    clustering.fit(X_red)
    print("%s: %.2fs" % (linkage, time() - t0))
    plot_clustering(X_red, clustering.labels_, "%s linkage" % linkage)

plt.show()

Total running time of the script: ( 0 minutes 50.545 seconds)

6.5.11 Segmenting the picture of greek coins in regions

This example uses Spectral clustering on a graph created from voxel-to-voxel difference on an image to break this image into multiple partly-homogeneous regions.

This procedure (spectral clustering on an image) is an efficient approximate solution for finding normalized graph cuts.

There are two options to assign labels:

- with ‘kmeans’ spectral clustering will cluster samples in the embedding space using a kmeans algorithm
- whereas ‘discrete’ will iteratively search for the closest partition space to the embedding space.
from sklearn.utils.fixes import parse_version

# these were introduced in skimage-0.14
if parse_version(skimage.__version__) >= parse_version('0.14'):
    rescale_params = {'anti_aliasing': False, 'multichannel': False}
else:
    rescale_params = {}

# load the coins as a numpy array
orig_coins = coins()

# Resize it to 20% of the original size to speed up the processing
# Applying a Gaussian filter for smoothing prior to down-scaling
# reduces aliasing artifacts.
smoothened_coins = gaussian_filter(orig_coins, sigma=2)
rescaled_coins = rescale(smoothened_coins, 0.2, mode="reflect", **rescale_params)

# Convert the image into a graph with the value of the gradient on the
# edges.
graph = image.img_to_graph(rescaled_coins)

# Take a decreasing function of the gradient: an exponential
# The smaller beta is, the more independent the segmentation is of the
# actual image. For beta=1, the segmentation is close to a voronoi
beta = 10
eps = 1e-6
graph.data = np.exp(-beta * graph.data / graph.data.std()) + eps

# Apply spectral clustering (this step goes much faster if you have pyamg
# installed)
N_REGIONS = 25

Visualize the resulting regions

for assign_labels in ('kmeans', 'discretize'):
    t0 = time.time()
    labels = spectral_clustering(graph, n_clusters=N_REGIONS,
                                  assign_labels=assign_labels, random_state=42)
    t1 = time.time()
    labels = labels.reshape(rescaled_coins.shape)

    plt.figure(figsize=(5, 5))
    plt.imshow(rescaled_coins, cmap=plt.cm.gray)
    for l in range(N_REGIONS):
        plt.contour(labels == l, colors=[plt.cm.nipy_spectral(l / float(N_REGIONS))])
    plt.xticks(())
    plt.yticks(())
    title = 'Spectral clustering: %s, %.2fs' % (assign_labels, (t1 - t0))
    print(title)
    plt.title(title)
    plt.show()
Spectral clustering: kmeans, 1.99s
6.5.12 K-means Clustering

The plots display firstly what a K-means algorithm would yield using three clusters. It is then shown what the effect of a bad initialization is on the classification process: By setting n_init to only 1 (default is 10), the amount of times that the algorithm will be run with different centroid seeds is reduced. The next plot displays what using eight clusters would deliver and finally the ground truth.
import numpy as np
import matplotlib.pyplot as plt

from sklearn.cluster import KMeans
from sklearn import datasets

np.random.seed(5)
iris = datasets.load_iris()
X = iris.data
y = iris.target

estimators = [('k_means_iris_8', KMeans(n_clusters=8)),
              ('k_means_iris_3', KMeans(n_clusters=3)),
              ('k_means_iris_bad_init', KMeans(n_clusters=3, n_init=1,
                 init='random'))]

fignum = 1
titles = ['8 clusters', '3 clusters', '3 clusters, bad initialization']

for name, est in estimators:
    fig = plt.figure(fignum, figsize=(4, 3))
    ax = Axes3D(fig, rect=[0, 0, .95, 1], elev=48, azim=134)
    est.fit(X)
    labels = est.labels_
    ax.scatter(X[:, 3], X[:, 0], X[:, 2],
               c=labels.astype(float), edgecolor='k')
    ax.w_xaxis.set_ticklabels([])
    ax.w_yaxis.set_ticklabels([])
    ax.w_zaxis.set_ticklabels([])
    ax.set_xlabel('Petal width')
    ax.set_ylabel('Sepal length')
    ax.set_zlabel('Petal length')
    ax.set_title(titles[fignum - 1])
    ax.dist = 12
    fignum = fignum + 1

# Plot the ground truth
fig = plt.figure(fignum, figsize=(4, 3))
ax = Axes3D(fig, rect=[0, 0, .95, 1], elev=48, azim=134)

for name, label in [('Setosa', 0),
                     ('Versicolour', 1),
                     ('Virginica', 2)]:
    ax.text3D(X[y == label, 3].mean(),
              X[y == label, 0].mean(),
              X[y == label, 2].mean() + 2, name,
              horizontalalignment='center',
              bbox=dict(alpha=.2, edgecolor='w', facecolor='w'))

# Reorder the labels to have colors matching the cluster results
y = np.choose(y, [1, 2, 0]).astype(float)
ax.scatter(X[:, 3], X[:, 0], X[:, 2], c=y, edgecolor='k')

ax.w_xaxis.set_ticklabels([])
ax.w_yaxis.set_ticklabels([])
ax.w_zaxis.set_ticklabels([])
ax.set_xlabel('Petal width')
ax.set_ylabel('Sepal length')
ax.set_zlabel('Petal length')
ax.set_title('Ground Truth')
ax.dist = 12

fig.show()
Total running time of the script: ( 0 minutes 0.358 seconds)

6.5.13 Spectral clustering for image segmentation

In this example, an image with connected circles is generated and spectral clustering is used to separate the circles.

In these settings, the Spectral clustering approach solves the problem know as ‘normalized graph cuts’: the image is seen as a graph of connected voxels, and the spectral clustering algorithm amounts to choosing graph cuts defining regions while minimizing the ratio of the gradient along the cut, and the volume of the region.

As the algorithm tries to balance the volume (ie balance the region sizes), if we take circles with different sizes, the segmentation fails.

In addition, as there is no useful information in the intensity of the image, or its gradient, we choose to perform the spectral clustering on a graph that is only weakly informed by the gradient. This is close to performing a Voronoi partition of the graph.

In addition, we use the mask of the objects to restrict the graph to the outline of the objects. In this example, we are interested in separating the objects one from the other, and not from the background.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.feature_extraction import image
from sklearn.cluster import spectral_clustering

l = 100
x, y = np.indices((l, l))

center1 = (28, 24)
center2 = (40, 50)
center3 = (67, 58)
center4 = (24, 70)

radius1, radius2, radius3, radius4 = 16, 14, 15, 14

circle1 = (x - center1[0]) ** 2 + (y - center1[1]) ** 2 < radius1 ** 2
circle2 = (x - center2[0]) ** 2 + (y - center2[1]) ** 2 < radius2 ** 2
circle3 = (x - center3[0]) ** 2 + (y - center3[1]) ** 2 < radius3 ** 2
circle4 = (x - center4[0]) ** 2 + (y - center4[1]) ** 2 < radius4 ** 2

print(__doc__)
circle4 = (x - center4[0]) ** 2 + (y - center4[1]) ** 2 < radius4 ** 2
# 4 circles
img = circle1 + circle2 + circle3 + circle4

# We use a mask that limits to the foreground: the problem that we are
# interested in here is not separating the objects from the background,
# but separating them one from the other.
mask = img.astype(bool)

img = img.astype(float)
img += 1 + 0.2 * np.random.randn(*img.shape)

# Convert the image into a graph with the value of the gradient on the
# edges.
graph = image.img_to_graph(img, mask=mask)

# Take a decreasing function of the gradient: we take it weakly
# dependent from the gradient the segmentation is close to a voronoi
graph.data = np.exp(-graph.data / graph.data.std())

# Force the solver to be arpack, since amg is numerically
# unstable on this example
labels = spectral_clustering(graph, n_clusters=4, eigen_solver='arpack')
label_im = np.full(mask.shape, -1.)
label_im[mask] = labels

plt.matshow(img)
plt.matshow(label_im)

# 2 circles
img = circle1 + circle2
mask = img.astype(bool)
img = img.astype(float)

img += 1 + 0.2 * np.random.randn(*img.shape)

graph = image.img_to_graph(img, mask=mask)
graph.data = np.exp(-graph.data / graph.data.std())

labels = spectral_clustering(graph, n_clusters=2, eigen_solver='arpack')
label_im = np.full(mask.shape, -1.)
label_im[mask] = labels

plt.matshow(img)
plt.matshow(label_im)
plt.show()

Total running time of the script: 0 minutes 0.589 seconds
Compute the segmentation of a 2D image with Ward hierarchical clustering. The clustering is spatially constrained in order for each segmented region to be in one piece.

```
Compute structured hierarchical clustering...
Elapsed time: 0.20728039741516113
Number of pixels: 4697
Number of clusters: 27
```

```
# Author: Vincent Michel, 2010
#         Alexandre Gramfort, 2011
# License: BSD 3 clause

print(__doc__)

import time as time
```

(continues on next page)
import numpy as np
from scipy.ndimage.filters import gaussian_filter

import matplotlib.pyplot as plt

import skimage
from skimage.data import coins
from skimage.transform import rescale
from sklearn.feature_extraction.image import grid_to_graph
from sklearn.cluster import AgglomerativeClustering
from sklearn.utils.fixes import parse_version

# these were introduced in skimage-0.14
if parse_version(skimage.__version__) >= parse_version('0.14'):
    rescale_params = {'anti_aliasing': False, 'multichannel': False}
else:
    rescale_params = {}

# Generate data
orig_coins = coins()

# Resize it to 20% of the original size to speed up the processing
# Applying a Gaussian filter for smoothing prior to down-scaling
# reduces aliasing artifacts.
smoothened_coins = gaussian_filter(orig_coins, sigma=2)
rescaled_coins = rescale(smoothened_coins, 0.2, mode="reflect",
                        **rescale_params)

X = np.reshape(rescaled_coins, (-1, 1))

# Define the structure A of the data. Pixels connected to their neighbors.
connectivity = grid_to_graph(*rescaled_coins.shape)

# Compute clustering
print("Compute structured hierarchical clustering...")
st = time.time()
n_clusters = 27  # number of regions
ward = AgglomerativeClustering(n_clusters=n_clusters, linkage='ward',
                               connectivity=connectivity)
ward.fit(X)
label = np.reshape(ward.labels_, rescaled_coins.shape)
print("Elapsed time: ", time.time() - st)
print("Number of pixels: ", label.size)
print("Number of clusters: ", np.unique(label).size)

# Plot the results on an image
plt.figure(figsize=(5, 5))
plt.imshow(rescaled_coins, cmap=plt.cm.gray)
for l in range(n_clusters):
    plt.contour(label == l,
                colors=[plt.cm.nipy_spectral(l / float(n_clusters)), ])}

6.5. Clustering
6.5.15 Demo of DBSCAN clustering algorithm

Finds core samples of high density and expands clusters from them.

Out:

Estimated number of clusters: 3
Estimated number of noise points: 18
Homogeneity: 0.953
Completeness: 0.883
V-measure: 0.917
Adjusted Rand Index: 0.952
Adjusted Mutual Information: 0.916
Silhouette Coefficient: 0.626

Total running time of the script: 0 minutes 0.466 seconds
from sklearn.cluster import DBSCAN
from sklearn import metrics
from sklearn.datasets import make_blobs
from sklearn.preprocessing import StandardScaler

# Generate sample data
centers = [[1, 1], [-1, -1], [1, -1]]
X, labels_true = make_blobs(n_samples=750, centers=centers, cluster_std=0.4,
                            random_state=0)
X = StandardScaler().fit_transform(X)

# Compute DBSCAN
db = DBSCAN(eps=0.3, min_samples=10).fit(X)
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
labels = db.labels_

# Number of clusters in labels, ignoring noise if present.
n_clusters_ = len(set(labels)) - (1 if -1 in labels else 0)
n_noise_ = labels.count(-1)

print('Estimated number of clusters: %d' % n_clusters_)
print('Estimated number of noise points: %d' % n_noise_)
print('Homogeneity: %0.3f' % metrics.homogeneity_score(labels_true, labels))
print('Completeness: %0.3f' % metrics.completeness_score(labels_true, labels))
print('V-measure: %0.3f' % metrics.v_measure_score(labels_true, labels))
print('Adjusted Rand Index: %0.3f' % metrics.adjusted_rand_score(labels_true, labels))
print('Adjusted Mutual Information: %0.3f' % metrics.adjusted_mutual_info_score(labels_true, labels))
print('Silhouette Coefficient: %0.3f' % metrics.silhouette_score(X, labels))

# Plot result
import matplotlib.pyplot as plt
# Black removed and is used for noise instead.
unique_labels = set(labels)
colors = [plt.cm.Spectral(each) for each in np.linspace(0, 1, len(unique_labels))]
for k, col in zip(unique_labels, colors):
    if k == -1:
        # Black used for noise.
        col = [0, 0, 0, 1]
    class_member_mask = (labels == k)
    xy = X[class_member_mask & core_samples_mask]
    plt.plot(xy[:, 0], xy[:, 1], 'o', markerfacecolor=col, markeredgecolor='k', markersize=6)
plt.title('Estimated number of clusters: %d' % n_clusters_)
plt.show()
6.5.16 Color Quantization using K-Means

Performs a pixel-wise Vector Quantization (VQ) of an image of the summer palace (China), reducing the number of colors required to show the image from 96,615 unique colors to 64, while preserving the overall appearance quality.

In this example, pixels are represented in a 3D-space and K-means is used to find 64 color clusters. In the image processing literature, the codebook obtained from K-means (the cluster centers) is called the color palette. Using a single byte, up to 256 colors can be addressed, whereas an RGB encoding requires 3 bytes per pixel. The GIF file format, for example, uses such a palette.

For comparison, a quantized image using a random codebook (colors picked up randomly) is also shown.

![Original image (96,615 colors)](image-url)
Quantized image (64 colors, K-Means)
Fitting model on a small sub-sample of the data done in 0.283s.
Predicting color indices on the full image (k-means) done in 0.043s.
Predicting color indices on the full image (random) done in 0.233s.

Quantized image (64 colors, Random)

Out:

```python
# Authors: Robert Layton <robertlayton@gmail.com>
#          Olivier Grisel <olivier.grisel@ensta.org>
#          Mathieu Blondel <mathieu@mblondel.org>
#
# License: BSD 3 clause

print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.cluster import KMeans
from sklearn.metrics import pairwise_distances_argmin
from sklearn.datasets import load_sample_image
from sklearn.utils import shuffle
```
from time import time

n_colors = 64

# Load the Summer Palace photo
china = load_sample_image("china.jpg")

# Convert to floats instead of the default 8 bits integer coding. Dividing by
# 255 is important so that plt.imshow behaves works well on float data (need to
# be in the range [0-1])
china = np.array(china, dtype=np.float64) / 255

# Load Image and transform to a 2D numpy array.
w, h, d = original_shape = tuple(china.shape)
assert d == 3
image_array = np.reshape(china, (w * h, d))

print("Fitting model on a small sub-sample of the data")
t0 = time()
image_array_sample = shuffle(image_array, random_state=0)[:1000]
kmeans = KMeans(n_clusters=n_colors, random_state=0).fit(image_array_sample)
print("done in \$0.3fs." % (time() - t0))

# Get labels for all points
print("Predicting color indices on the full image (k-means)")
t0 = time()
labels = kmeans.predict(image_array)
print("done in \$0.3fs." % (time() - t0))

codebook_random = shuffle(image_array, random_state=0)[:n_colors]
print("Predicting color indices on the full image (random)")
t0 = time()
labels_random = pairwise_distances_argmin(codebook_random,
                                        image_array,
                                        axis=0)
print("done in \$0.3fs." % (time() - t0))

def recreate_image(codebook, labels, w, h):
    """Recreate the (compressed) image from the code book & labels""
    d = codebook.shape[1]
    image = np.zeros((w, h, d))
    label_idx = 0
    for i in range(w):
        for j in range(h):
            image[i][j] = codebook[labels[label_idx]]
            label_idx += 1
    return image

# Display all results, alongside original image
plt.figure(1)
plt.clf()
plt.axis('off')
plt.title('Original image (96,615 colors)')
plt.imshow(china)
6.5.17 Hierarchical clustering: structured vs unstructured ward

Example builds a swiss roll dataset and runs hierarchical clustering on their position.

For more information, see Hierarchical clustering.

In a first step, the hierarchical clustering is performed without connectivity constraints on the structure and is solely based on distance, whereas in a second step the clustering is restricted to the k-Nearest Neighbors graph: it’s a hierarchical clustering with structure prior.

Some of the clusters learned without connectivity constraints do not respect the structure of the swiss roll and extend across different folds of the manifolds. On the opposite, when opposing connectivity constraints, the clusters form a nice parcellation of the swiss roll.
`Out:

<table>
<thead>
<tr>
<th>Description</th>
<th>Time</th>
<th>Points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Compute unstructured hierarchical clustering</td>
<td>0.05s</td>
<td>1500</td>
</tr>
<tr>
<td>Compute structured hierarchical clustering</td>
<td>0.07s</td>
<td>1500</td>
</tr>
</tbody>
</table>

Authors: Vincent Michel, 2010
Alexandre Gramfort, 2010
Gael Varoquaux, 2010

License: BSD 3 clause

```python
print(__doc__)
import time as time
import numpy as np
import matplotlib.pyplot as plt
import mpl_toolkits.mplot3d.axes3d as p3
from sklearn.cluster import AgglomerativeClustering
from sklearn.datasets import make_swiss_roll
```
# Generate data (swiss roll dataset)
n_samples = 1500
noise = 0.05
X, _ = make_swiss_roll(n_samples, noise=noise)
# Make it thinner
X[:, 1] *= .5

# Compute clustering
print("Compute unstructured hierarchical clustering...")
st = time.time()
ward = AgglomerativeClustering(n_clusters=6, linkage='ward').fit(X)
elapsed_time = time.time() - st
label = ward.labels_
print("Elapsed time: %.2fs" % elapsed_time)
print("Number of points: %i" % label.size)

# Define the structure A of the data. Here a 10 nearest neighbors
from sklearn.neighbors import kneighbors_graph
connectivity = kneighbors_graph(X, n_neighbors=10, include_self=False)

# Compute clustering
print("Compute structured hierarchical clustering...")
st = time.time()
ward = AgglomerativeClustering(n_clusters=6, connectivity=connectivity,
                               linkage='ward').fit(X)
elapsed_time = time.time() - st
label = ward.labels_
print("Elapsed time: %.2fs" % elapsed_time)
print("Number of points: %i" % label.size)
6.5.18 Agglomerative clustering with different metrics

Demonstrates the effect of different metrics on the hierarchical clustering.

The example is engineered to show the effect of the choice of different metrics. It is applied to waveforms, which can be seen as high-dimensional vector. Indeed, the difference between metrics is usually more pronounced in high dimension (in particular for euclidean and cityblock).

We generate data from three groups of waveforms. Two of the waveforms (waveform 1 and waveform 2) are proportional one to the other. The cosine distance is invariant to a scaling of the data, as a result, it cannot distinguish these two waveforms. Thus even with no noise, clustering using this distance will not separate out waveform 1 and 2.

We add observation noise to these waveforms. We generate very sparse noise: only 6% of the time points contain noise. As a result, the l1 norm of this noise (ie “cityblock” distance) is much smaller than it’s l2 norm (“euclidean” distance). This can be seen on the inter-class distance matrices: the values on the diagonal, that characterize the spread of the class, are much bigger for the Euclidean distance than for the cityblock distance.

When we apply clustering to the data, we find that the clustering reflects what was in the distance matrices. Indeed, for the Euclidean distance, the classes are ill-separated because of the noise, and thus the clustering does not separate the waveforms. For the cityblock distance, the separation is good and the waveform classes are recovered. Finally, the cosine distance does not separate at all waveform 1 and 2, thus the clustering puts them in the same cluster.
Ground truth
Interclass cosine distances

Waveform 1
- 0.205
- 0.139
- 1.000

Waveform 2
- 0.139
- 0.060
- 0.980

Waveform 3
- 1.000
- 0.980
- 0.131
Interclass euclidean distances

<table>
<thead>
<tr>
<th></th>
<th>Waveform 1</th>
<th>Waveform 2</th>
<th>Waveform 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Waveform 1</td>
<td>0.168</td>
<td>0.780</td>
<td>0.400</td>
</tr>
<tr>
<td>Waveform 2</td>
<td>0.780</td>
<td>0.302</td>
<td>1.000</td>
</tr>
<tr>
<td>Waveform 3</td>
<td>0.400</td>
<td>1.000</td>
<td>0.170</td>
</tr>
</tbody>
</table>
Interclass cityblock distances
AgglomerativeClustering(affinity=cosine)
AgglomerativeClustering(affinity=euclidean)
```python
# Author: Gael Varoquaux
# License: BSD 3-Clause or CC-0

import matplotlib.pyplot as plt
import numpy as np

from sklearn.cluster import AgglomerativeClustering
from sklearn.metrics import pairwise_distances

np.random.seed(0)

# Generate waveform data
n_features = 2000
t = np.pi * np.linspace(0, 1, n_features)

def sqr(x):
    return np.sign(np.cos(x))

X = list()
y = list()

for i, (phi, a) in enumerate([(.5, .15), (.5, .6), (.3, .2)]):
    for _ in range(30):
        phase_noise = .01 * np.random.normal()
        amplitude_noise = .04 * np.random.normal()
        additional_noise = 1 - 2 * np.random.rand(n_features)
        # Make the noise sparse
        ...
```

6.5. Clustering

(continues on next page)
additional_noise[np.abs(additional_noise) < .997] = 0

X.append(12 * ((a + amplitude_noise) * (sqr(6 * (t + phi + phase_noise))) + additional_noise))
y.append(i)

X = np.array(X)
y = np.array(y)
n_clusters = 3
labels = ('Waveform 1', 'Waveform 2', 'Waveform 3')

# Plot the ground-truth labelling
plt.figure()
plt.axes([0, 0, 1, 1])
for l, c, n in zip(range(n_clusters), 'rgb', labels):
    lines = plt.plot(X[y == l].T, c=c, alpha=.5)
    lines[0].set_label(n)
plt.legend(loc='best')
plt.axis('tight')
plt.axis('off')
plt.suptitle("Ground truth", size=20)

# Plot the distances
for index, metric in enumerate(['cosine', 'euclidean', 'cityblock']):
    avg_dist = np.zeros((n_clusters, n_clusters))
    plt.figure(figsize=(5, 4.5))
    for i in range(n_clusters):
        for j in range(n_clusters):
            avg_dist[i, j] = pairwise_distances(X[y == i], X[y == j],
                metric=metric).mean()
            avg_dist /= avg_dist.max()
    for i in range(n_clusters):
        for j in range(n_clusters):
            plt.text(i, j, '%5.3f' % avg_dist[i, j],
                verticalalignment='center',
                horizontalalignment='center')

    plt.imshow(avg_dist, interpolation='nearest', cmap=plt.cm.gnuplot2,
        vmin=0)
    plt.xticks(range(n_clusters), labels, rotation=45)
    plt.yticks(range(n_clusters), labels)
    plt.colorbar()
    plt.suptitle("Interclass %s distances" % metric, size=18)
    plt.tight_layout()

# Plot clustering results
for index, metric in enumerate(['cosine', 'euclidean', 'cityblock']):
    model = AgglomerativeClustering(n_clusters=n_clusters,
        linkage="average", affinity=metric)
model.fit(X)
plt.figure()
plt.axes([0, 0, 1, 1])
for l, c in zip(np.arange(model.n_clusters), 'rgbk'):
    plt.plot(X[model.labels_ == l].T, c=c, alpha=.5)
plt.axis('tight')
plt.axis('off')
plt.suptitle("AgglomerativeClustering(affinity=%s)" % metric, size=20)
plt.show()

Total running time of the script: ( 0 minutes 1.199 seconds)

6.5.19 Inductive Clustering

Clustering can be expensive, especially when our dataset contains millions of datapoints. Many clustering algorithms are not inductive and so cannot be directly applied to new data samples without recomputing the clustering, which may be intractable. Instead, we can use clustering to then learn an inductive model with a classifier, which has several benefits:

- it allows the clusters to scale and apply to new data
- unlike re-fitting the clusters to new samples, it makes sure the labelling procedure is consistent over time
- it allows us to use the inferential capabilities of the classifier to describe or explain the clusters

This example illustrates a generic implementation of a meta-estimator which extends clustering by inducing a classifier from the cluster labels.

# Authors: Chirag Nagpal
# Christos Aridas
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.base import BaseEstimator, clone
from sklearn.cluster import AgglomerativeClustering
from sklearn.datasets import make_blobs
from sklearn.ensemble import RandomForestClassifier
from sklearn.utils.metaestimators import if_delegate_has_method

(continues on next page)
N_SAMPLES = 5000
RANDOM_STATE = 42

class InductiveClusterer(BaseEstimator):
    def __init__(self, clusterer, classifier):
        self.clusterer = clusterer
        self.classifier = classifier

    def fit(self, X, y=None):
        self.clusterer_ = clone(self.clusterer)
        self.classifier_ = clone(self.classifier)
        y = self.clusterer_.fit_predict(X)
        self.classifier_.fit(X, y)
        return self

    @if_delegate_has_method(delegate='classifier_')
    def predict(self, X):
        return self.classifier_.predict(X)

    @if_delegate_has_method(delegate='classifier_')
    def decision_function(self, X):
        return self.classifier_.decision_function(X)

def plot_scatter(X, color, alpha=0.5):
    return plt.scatter(X[:, 0], X[:, 1], c=color, alpha=alpha, edgecolor='k')

# Generate some training data from clustering
X, y = make_blobs(n_samples=N_SAMPLES,
                   cluster_std=[1.0, 1.0, 0.5],
                   centers=[(-5, -5), (0, 0), (5, 5)],
                   random_state=RANDOM_STATE)

# Train a clustering algorithm on the training data and get the cluster labels
clusterer = AgglomerativeClustering(n_clusters=3)
cluster_labels = clusterer.fit_predict(X)

plt.figure(figsize=(12, 4))
plt.subplot(131)
plot_scatter(X, cluster_labels)
plt.title("Ward Linkage")

# Generate new samples and plot them along with the original dataset
X_new, y_new = make_blobs(n_samples=10,
                          centers=[(-7, -1), (-2, 4), (3, 6)],
                          random_state=RANDOM_STATE)
plt.subplot(132)
plot_scatter(X, cluster_labels)
plot_scatter(X_new, 'black', 1)
plt.title("Unknown instances")

# Declare the inductive learning model that it will be used to
# predict cluster membership for unknown instances
classifier = RandomForestClassifier(random_state=RANDOM_STATE)
inductive_learner = InductiveClusterer(clusterer, classifier).fit(X)
probable_clusters = inductive_learner.predict(X_new)

plt.subplot(133)
plot_scatter(X, cluster_labels)
plot_scatter(X_new, probable_clusters)

# Plotting decision regions
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.1),
                     np.arange(y_min, y_max, 0.1))
Z = inductive_learner.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
plt.contourf(xx, yy, Z, alpha=0.4)
plt.title("Classify unknown instances")
plt.show()

Total running time of the script: ( 0 minutes 2.284 seconds)

6.5.20 Demo of OPTICS clustering algorithm

Finds core samples of high density and expands clusters from them. This example uses data that is generated so that the clusters have different densities. The **OPTICS** is first used with its Xi cluster detection method, and then setting specific thresholds on the reachability, which corresponds to **DBSCAN**. We can see that the different clusters of OPTICS’s Xi method can be recovered with different choices of thresholds in DBSCAN.
from sklearn.cluster import OPTICS, cluster_optics_dbscan
import matplotlib.gridspec as gridspec
import matplotlib.pyplot as plt
import numpy as np

# Generate sample data
np.random.seed(0)
n_points_per_cluster = 250

C1 = [-5, -2] + .8 * np.random.randn(n_points_per_cluster, 2)
C2 = [4, -1] + .1 * np.random.randn(n_points_per_cluster, 2)
C3 = [1, -2] + .2 * np.random.randn(n_points_per_cluster, 2)
C4 = [-2, 3] + .3 * np.random.randn(n_points_per_cluster, 2)
C5 = [3, -2] + 1.6 * np.random.randn(n_points_per_cluster, 2)
C6 = [5, 6] + 2 * np.random.randn(n_points_per_cluster, 2)

X = np.vstack((C1, C2, C3, C4, C5, C6))

clust = OPTICS(min_samples=50, xi=.05, min_cluster_size=.05)

# Run the fit
clust.fit(X)
labels_050 = cluster_optics_dbscan(reachability=clust.reachability_,
core_distances=clust.core_distances_,
ordering=clust.ordering_, eps=0.5)
labels_200 = cluster_optics_dbscan(reachability=clust.reachability_,
core_distances=clust.core_distances_,
ordering=clust.ordering_, eps=2)

space = np.arange(len(X))
reachability = clust.reachability_[clust.ordering_]
labels = clust.labels_[clust.ordering_]

plt.figure(figsize=(10, 7))
G = gridspec.GridSpec(2, 3)
ax1 = plt.subplot(G[0, :])
ax2 = plt.subplot(G[1, 0])
ax3 = plt.subplot(G[1, 1])
ax4 = plt.subplot(G[1, 2])

# Reachability plot
colors = ['g.', 'r.', 'b.', 'y.', 'c.']
for klass, color in zip(range(0, 5), colors):
    Xk = space[labels == klass]
    Rk = reachability[labels == klass]
    ax1.plot(Xk, Rk, color, alpha=0.3)
ax1.plot(space[labels == -1], reachability[labels == -1], 'k.', alpha=0.3)
ax1.plot(space, np.full_like(space, 2., dtype=float), 'k-', alpha=0.5)
ax1.plot(space, np.full_like(space, 0.5, dtype=float), 'k-.', alpha=0.5)
ax1.set_ylabel('Reachability (epsilon distance)')
ax1.set_title('Reachability Plot')

# OPTICS
colors = ['g.', 'r.', 'b.', 'y.', 'c.']
for klass, color in zip(range(0, 5), colors):
    Xk = X[clust.labels_ == klass]
    ax2.plot(Xk[:, 0], Xk[:, 1], color, alpha=0.3)
ax2.plot(X[clust.labels_ == -1, 0], X[clust.labels_ == -1, 1], 'k+', alpha=0.1)
ax2.set_title('Automatic Clustering
OPTICS')

# DBSCAN at 0.5
colors = ['g', 'greenyellow', 'olive', 'r', 'b', 'c']
for klass, color in zip(range(0, 6), colors):
    Xk = X[labels_050 == klass]
    ax3.plot(Xk[:, 0], Xk[:, 1], color, alpha=0.3, marker='x')
ax3.plot(X[labels_050 == -1, 0], X[labels_050 == -1, 1], 'k+', alpha=0.1)
ax3.set_title('Clustering at 0.5 epsilon cut
DBSCAN')

# DBSCAN at 2.
colors = ['g.', 'm.', 'y.', 'c. ']
for klass, color in zip(range(0, 4), colors):
    Xk = X[labels_200 == klass]
    ax4.plot(Xk[:, 0], Xk[:, 1], color, alpha=0.3)
ax4.plot(X[labels_200 == -1, 0], X[labels_200 == -1, 1], 'k+', alpha=0.1)
ax4.set_title('Clustering at 2.0 epsilon cut
DBSCAN')

plt.tight_layout()
plt.show()
Total running time of the script: ( 0 minutes 1.286 seconds)

6.5.21 Compare BIRCH and MiniBatchKMeans

This example compares the timing of Birch (with and without the global clustering step) and MiniBatchKMeans on a synthetic dataset having 100,000 samples and 2 features generated using make_blobs.

If n_clusters is set to None, the data is reduced from 100,000 samples to a set of 158 clusters. This can be viewed as a preprocessing step before the final (global) clustering step that further reduces these 158 clusters to 100 clusters.

Out:

Birch without global clustering as the final step took 2.83 seconds
n_clusters : 158
Birch with global clustering as the final step took 3.00 seconds
n_clusters : 100
Time taken to run MiniBatchKMeans 2.85 seconds

# Authors: Manoj Kumar <manojkumarsivaraj334@gmail.com>
# Alexandre Gramfort <alexandre.gramfort@telecom-paristech.fr>
# License: BSD 3 clause

print(__doc__)

from itertools import cycle
from time import time
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.colors as colors
from sklearn.cluster import Birch, MiniBatchKMeans
from sklearn.datasets import make_blobs

# Generate centers for the blobs so that it forms a 10 X 10 grid.
xx = np.linspace(-22, 22, 10)
yy = np.linspace(-22, 22, 10)
```python
xx, yy = np.meshgrid(xx, yy)
n_centres = np.hstack((np.ravel(xx)[:, np.newaxis],
                      np.ravel(yy)[:, np.newaxis]))

# Generate blobs to do a comparison between MiniBatchKMeans and Birch.
X, y = make_blobs(n_samples=100000, centers=n_centres, random_state=0)

# Use all colors that matplotlib provides by default.
colors_ = cycle(colors.cnames.keys())

fig = plt.figure(figsize=(12, 4))
fig.subplots_adjust(left=0.04, right=0.98, bottom=0.1, top=0.9)

# Compute clustering with Birch with and without the final clustering step
# and plot.
birch_models = [Birch(threshold=1.7, n_clusters=None),
                 Birch(threshold=1.7, n_clusters=100)]
final_step = ['without global clustering', 'with global clustering']

for ind, (birch_model, info) in enumerate(zip(birch_models, final_step)):
    t = time()
    birch_model.fit(X)
    time_ = time() - t
    print("Birch %s as the final step took %0.2f seconds" % (info, (time() - t)))

    # Plot result
    labels = birch_model.labels_
    centroids = birch_model.subcluster_centers_
    n_clusters = np.unique(labels).size
    print("n_clusters : %d" % n_clusters)
    ax = fig.add_subplot(1, 3, ind + 1)
    for this_centroid, k, col in zip(centroids, range(n_clusters), colors_):
        mask = labels == k
        ax.scatter(X[mask, 0], X[mask, 1], c='w', edgecolor=col, marker='.', alpha=0.5)
        if birch_model.n_clusters is None:
            ax.scatter(this_centroid[0], this_centroid[1], marker='+', c='k', s=25)
    ax.set_ylim([-25, 25])
    ax.set_xlim([-25, 25])
    ax.set_autoscaley_on(False)
    ax.set_title('Birch %s' % info)

# Compute clustering with MiniBatchKMeans.
mbk = MiniBatchKMeans(init='k-means++', n_clusters=100, batch_size=100,
                       n_init=10, max_no_improvement=10, verbose=0,
                       random_state=0)

t0 = time()
mbk.fit(X)
t_mini_batch = time() - t0
print("Time taken to run MiniBatchKMeans %0.2f seconds" % t_mini_batch)
mbk_means_labels_unique = np.unique(mbk.labels_)

ax = fig.add_subplot(1, 3, 3)
for this_centroid, k, col in zip(mbk.cluster_centers_,
                             colors_.cycle() if n_clusters > len(colors_.cnames.keys()) else colors_.cycle()):
    ax.scatter(this_centroid[0], this_centroid[1], marker='o', c=col, s=30, alpha=0.5)
```

(continues on next page)
6.5.22 Empirical evaluation of the impact of k-means initialization

Evaluate the ability of k-means initializations strategies to make the algorithm convergence robust as measured by the relative standard deviation of the inertia of the clustering (i.e. the sum of squared distances to the nearest cluster center).

The first plot shows the best inertia reached for each combination of the model (KMeans or MiniBatchKMeans) and the init method (init="random" or init="kmeans++") for increasing values of the n_init parameter that controls the number of initializations.

The second plot demonstrate one single run of the MiniBatchKMeans estimator using a init="random" and n_init=1. This run leads to a bad convergence (local optimum) with estimated centers stuck between ground truth clusters.

The dataset used for evaluation is a 2D grid of isotropic Gaussian clusters widely spaced.
# Evaluation of KMeans with k-means++ init
# Evaluation of KMeans with random init
# Evaluation of MiniBatchKMeans with k-means++ init
# Evaluation of MiniBatchKMeans with random init

```python
print(__doc__)

# Author: Olivier Grisel <olivier.grisel@ensta.org>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
import matplotlib.cm as cm

from sklearn.utils import shuffle
from sklearn.utils import check_random_state
from sklearn.cluster import MiniBatchKMeans
from sklearn.cluster import KMeans

random_state = np.random.RandomState(0)
```

(continues on next page)
# Number of run (with randomly generated dataset) for each strategy so as to be able to compute an estimate of the standard deviation
n_runs = 5

# k-means models can do several random inits so as to be able to trade CPU time for convergence robustness
n_init_range = np.array([1, 5, 10, 15, 20])

# Datasets generation parameters
n_samples_per_center = 100
grid_size = 3
scale = 0.1
n_clusters = grid_size ** 2

def make_data(random_state, n_samples_per_center, grid_size, scale):
    random_state = check_random_state(random_state)
    centers = np.array([[i, j]
                        for i in range(grid_size)
                        for j in range(grid_size)])
    n_clusters_true, n_features = centers.shape
    noise = random_state.normal(
        scale=scale, size=(n_samples_per_center, centers.shape[1]))
    X = np.concatenate([c + noise for c in centers])
    y = np.concatenate([i * n_samples_per_center
                        for i in range(n_clusters_true)])
    return shuffle(X, y, random_state=random_state)

# Part 1: Quantitative evaluation of various init methods

plt.figure()
plots = []
legends = []
cases = [
    (KMeans, 'k-means++', {}),
    (KMeans, 'random', {}),
    (MiniBatchKMeans, 'k-means++', {'max_no_improvement': 3}),
    (MiniBatchKMeans, 'random', {'max_no_improvement': 3, 'init_size': 500}),
]

for factory, init, params in cases:
    print("Evaluation of $s with $s init" % (factory.__name__, init))
    inertia = np.empty((len(n_init_range), n_runs))

    for run_id in range(n_runs):
        X, y = make_data(run_id, n_samples_per_center, grid_size, scale)
        for i, n_init in enumerate(n_init_range):
            km = factory(n_clusters=n_clusters_true, init=init, random_state=run_id,
                          n_init=n_init, **params).fit(X)
            inertia[i, run_id] = km.inertia_
            p = plt.errorbar(n_init_range, inertia.mean(axis=1), inertia.std(axis=1))
            plots.append(p[0])
            legends.append("$s with $s init" % (factory.__name__, init))

(continues on next page)
plt.xlabel('n_init')
plt.ylabel('inertia')
plt.legend(plots, legends)
plt.title("Mean inertia for various k-means init across %d runs" % n_runs)

# Part 2: Qualitative visual inspection of the convergence

X, y = make_data(random_state, n_samples_per_center, grid_size, scale)
km = MiniBatchKMeans(n_clusters=n_clusters, init='random', n_init=1, random_state=random_state).fit(X)

plt.figure()
for k in range(n_clusters):
    my_members = km.labels_ == k
    color = cm.nipy_spectral(float(k) / n_clusters, 1)
    plt.plot(X[my_members, 0], X[my_members, 1], 'o', marker='.', c=color)
    cluster_center = km.cluster_centers_[k]
    plt.plot(cluster_center[0], cluster_center[1], 'o',
             markerfacecolor=color, markeredgecolor='k', markersize=6)
plt.title("Example cluster allocation with a single random init
" "with MiniBatchKMeans")

plt.show()

Total running time of the script: (0 minutes 2.888 seconds)

6.5.23 Adjustment for chance in clustering performance evaluation

The following plots demonstrate the impact of the number of clusters and number of samples on various clustering performance evaluation metrics.

Non-adjusted measures such as the V-Measure show a dependency between the number of clusters and the number of samples: the mean V-Measure of random labeling increases significantly as the number of clusters is closer to the total number of samples used to compute the measure.

Adjusted for chance measure such as ARI display some random variations centered around a mean score of 0.0 for any number of samples and clusters.

Only adjusted measures can hence safely be used as a consensus index to evaluate the average stability of clustering algorithms for a given value of k on various overlapping sub-samples of the dataset.
Clustering measures for 2 random uniform labelings with equal number of clusters

Score value

Number of clusters (Number of samples is fixed to 100)
Clustering measures for random uniform labeling against reference assignment with 10 classes

Out:

```python
Computing adjusted_rand_score for 10 values of n_clusters and n_samples=100
done in 0.029s
Computing v_measure_score for 10 values of n_clusters and n_samples=100
done in 0.048s
Computing ami_score for 10 values of n_clusters and n_samples=100
done in 0.353s
Computing mutual_info_score for 10 values of n_clusters and n_samples=100
done in 0.038s
Computing adjusted_rand_score for 10 values of n_clusters and n_samples=1000
done in 0.061s
Computing v_measure_score for 10 values of n_clusters and n_samples=1000
done in 0.061s
Computing ami_score for 10 values of n_clusters and n_samples=1000
done in 0.063s
Computing mutual_info_score for 10 values of n_clusters and n_samples=1000
done in 0.228s
```

```python
print(__doc__)

# Author: Olivier Grisel <olivier.grisel@ensta.org>
```
import numpy as np
import matplotlib.pyplot as plt
from time import time
from sklearn import metrics

def uniform_labelings_scores(score_func, n_samples, n_clusters_range,
                           fixed_n_classes=None, n_runs=5, seed=42):
    """Compute score for 2 random uniform cluster labelings.
    Both random labelings have the same number of clusters for each value
    possible value in `n_clusters_range`.
    When fixed_n_classes is not None the first labeling is considered a ground
    truth class assignment with fixed number of classes.
    """
    random_labels = np.random.RandomState(seed).randint
    scores = np.zeros((len(n_clusters_range), n_runs))
    if fixed_n_classes is not None:
        labels_a = random_labels(low=0, high=fixed_n_classes, size=n_samples)
        for i, k in enumerate(n_clusters_range):
            for j in range(n_runs):
                if fixed_n_classes is None:
                    labels_b = random_labels(low=0, high=k, size=n_samples)
                scores[i, j] = score_func(labels_a, labels_b)
    return scores

def ami_score(U, V):
    return metrics.adjusted_mutual_info_score(U, V)

score_funcs = [
    metrics.adjusted_rand_score,
    metrics.v_measure_score,
    ami_score,
    metrics_mutual_info_score,
]

# 2 independent random clusterings with equal cluster number
n_samples = 100
n_clusters_range = np.linspace(2, n_samples, 10).astype(int)

plt.figure(1)
plots = []
names = []
for score_func in score_funcs:
    print("Computing %s for %d values of n_clusters and n_samples=%d" %
          (score_func.__name__, len(n_clusters_range), n_samples))
    t0 = time()
    scores = uniform_labelings_scores(score_func, n_samples, n_clusters_range)
    scores = uniform_labelings_scores(score_func, n_samples, n_clusters_range)
    (continues on next page)
print("done in \$%.3fs" % (time() - t0))
plots.append(plt.errorbar(n_clusters_range, np.median(scores, axis=1), scores.std(axis=1))[0])
names.append(score_func.__name__)

plt.title("Clustering measures for 2 random uniform labelings\n
" + "with equal number of clusters")
plt.xlabel('Number of clusters (Number of samples is fixed to \$%d\$)' % n_samples)
plt.ylabel('Score value')
plt.legend(plots, names)
plt.ylim(bottom=-0.05, top=1.05)

# Random labeling with varying n_clusters against ground class labels
# with fixed number of clusters

n_samples = 1000
n_clusters_range = np.linspace(2, 100, 10).astype(int)
n_classes = 10

plt.figure(2)
plots = []
names = []
for score_func in score_funcs:
    print("Computing %s for %d values of n_clusters and n_samples=%d" % (score_func.__name__, len(n_clusters_range), n_samples))
    t0 = time()
scores = uniform_labelings_scores(score_func, n_samples, n_clusters_range, fixed_n_classes=n_classes)
    print("done in \$%.3fs" % (time() - t0))
    plots.append(plt.errorbar(n_clusters_range, scores.mean(axis=1), scores.std(axis=1))[0])
    names.append(score_func.__name__)

plt.title("Clustering measures for random uniform labeling\n
" + "against reference assignment with %d classes" % n_classes)
plt.xlabel('Number of clusters (Number of samples is fixed to \$%d\$)' % n_samples)
plt.ylabel('Score value')
plt.legend(plots, names)
plt.show()

Total running time of the script: 0 minutes 1.088 seconds
## 6.5.24 Comparison of the K-Means and MiniBatchKMeans clustering algorithms

We want to compare the performance of the MiniBatchKMeans and KMeans: the MiniBatchKMeans is faster, but gives slightly different results (see *Mini Batch K-Means*).

We will cluster a set of data, first with KMeans and then with MiniBatchKMeans, and plot the results. We will also plot the points that are labelled differently between the two algorithms.

```python
print(__doc__)

import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn.cluster import MiniBatchKMeans, KMeans
from sklearn.metrics.pairwise import pairwise_distances_argmin
from sklearn.datasets import make_blobs

# #############################################################################
# Generate sample data
np.random.seed(0)
batch_size = 45
centers = [[1, 1], [-1, -1], [1, -1]]
n_clusters = len(centers)
X, labels_true = make_blobs(n_samples=3000, centers=centers, cluster_std=0.7)

# #############################################################################
# Compute clustering with Means
k_means = KMeans(init='k-means++', n_clusters=3, n_init=10)
t0 = time.time()
k_means.fit(X)
t_batch = time.time() - t0

# #############################################################################
# Compute clustering with MiniBatchKMeans
mbk = MiniBatchKMeans(init='k-means++', n_clusters=3, batch_size=batch_size,
                       n_init=10, max_no_improvement=10, verbose=0)
```

(continues on next page)
t0 = time.time()
mbk.fit(X)
t_mini_batch = time.time() - t0

# Plot result

fig = plt.figure(figsize=(8, 3))
fig.subplots_adjust(left=0.02, right=0.98, bottom=0.05, top=0.9)

# We want to have the same colors for the same cluster from the MiniBatchKMeans and the KMeans algorithm. Let's pair the cluster centers per closest one.
k_means_cluster_centers = k_means.cluster_centers_
order = pairwise_distances_argmin(k_means.cluster_centers_,
    mbk.cluster_centers_)
mbk_means_cluster_centers = mbk.cluster_centers_[order]

k_means_labels = pairwise_distances_argmin(X, k_means_cluster_centers)
mbk_means_labels = pairwise_distances_argmin(X, mbk_means_cluster_centers)

# KMeans
ax = fig.add_subplot(1, 3, 1)
for k, col in zip(range(n_clusters), colors):
    my_members = k_means_labels == k
    cluster_center = k_means_cluster_centers[k]
    ax.plot(X[my_members, 0], X[my_members, 1], 'w', markerfacecolor=col, marker='.'
    ax.plot(cluster_center[0], cluster_center[1], 'o', markerfacecolor=col,
            markeredgecolor='k', markersize=6)
ax.set_title('KMeans')
ax.set_xticks(())
ax.set_yticks(())
plt.text(-3.5, 1.8, 'train time: %.2f
    inertia: %.2f' % (t_batch, k_means.inertia_))

# MiniBatchKMeans
ax = fig.add_subplot(1, 3, 2)
for k, col in zip(range(n_clusters), colors):
    my_members = mbk_means_labels == k
    cluster_center = mbk_means_cluster_centers[k]
    ax.plot(X[my_members, 0], X[my_members, 1], 'w', markerfacecolor=col, marker='.'
    ax.plot(cluster_center[0], cluster_center[1], 'o', markerfacecolor=col,
            markeredgecolor='k', markersize=6)
ax.set_title('MiniBatchKMeans')
ax.set_xticks(())
ax.set_yticks(())
plt.text(-3.5, 1.8, 'train time: %.2f
    inertia: %.2f' % (t_mini_batch, mbk.inertia_))

# Initialise the different array to all False
different = (mbk_means_labels == 4)
ax = fig.add_subplot(1, 3, 3)
for k in range(n_clusters):
different += ((k_means_labels == k) != (mbk_means_labels == k))
identic = np.logical_not(different)
ax.plot(X[identic, 0], X[identic, 1], 'w',
        markerfacecolor='#bbbbbb', marker='.'
ax.plot(X[different, 0], X[different, 1], 'w',
        markerfacecolor='m', marker='.'
ax.set_title('Difference')
ax.set_xticks(())
ax.set_yticks(())
plt.show()

Total running time of the script: ( 0 minutes 0.245 seconds)

6.5.25 Feature agglomeration vs. univariate selection

This example compares 2 dimensionality reduction strategies:
- univariate feature selection with Anova
- feature agglomeration with Ward hierarchical clustering

Both methods are compared in a regression problem using a BayesianRidge as supervised estimator.

Out:

```
[Memory] Calling sklearn.cluster._agglomerative.ward_tree...
ward_tree(array([[ 0.905206, ..., 0.161245],
                  ...,
                  [-0.752966, ..., -0.675318]]), connectivity=<1600x1600 sparse matrix of type '<class 'numpy.int64'>'
with 7840 stored elements in COOrdinate format>, n_clusters=None, return_distance=False)

ward_tree - 0.1s, 0.0min
```

```
[Memory] Calling sklearn.cluster._agglomerative.ward_tree...
ward_tree(array([[ 0.905206, ..., 0.161245],
                  ...,
                  [-0.752966, ..., -0.675318]]), connectivity=<1600x1600 sparse matrix of type '<class 'numpy.int64'>'
with 7840 stored elements in COOrdinate format>, n_clusters=None, return_distance=False)

ward_tree - 0.1s, 0.0min
```
```python
import shutil
import tempfile
import numpy as np
import matplotlib.pyplot as plt
from scipy import linalg, ndimage
from joblib import Memory
from sklearn.feature_extraction.image import grid_to_graph
from sklearn import feature_selection

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

print(__doc__)

import shutil
import tempfile
import numpy as np
import matplotlib.pyplot as plt
from scipy import linalg, ndimage
from joblib import Memory
from sklearn.feature_extraction.image import grid_to_graph
from sklearn import feature_selection

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

print(__doc__)

import shutil
import tempfile
import numpy as np
import matplotlib.pyplot as plt
from scipy import linalg, ndimage
from joblib import Memory
from sklearn.feature_extraction.image import grid_to_graph
from sklearn import feature_selection
```

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from sklearn.cluster import FeatureAgglomeration
from sklearn.linear_model import BayesianRidge
from sklearn.pipeline import Pipeline
from sklearn.model_selection import GridSearchCV
from sklearn.model_selection import KFold

# #############################################################################
# Generate data
n_samples = 200
size = 40  # image size
roi_size = 15
snr = 5.
np.random.seed(0)
mask = np.ones((size, size), dtype=bool)
coef = np.zeros((size, size))
coef[0:roi_size, 0:roi_size] = -1.
coef[-roi_size:, -roi_size:] = 1.

X = np.random.randn(n_samples, size ** 2)
for x in X:
    # smooth data
    x[:] = ndimage.gaussian_filter(x.reshape(size, size), sigma=1.0).ravel()
X -= X.mean(axis=0)
X /= X.std(axis=0)

y = np.dot(X, coef.ravel())
noise = np.random.randn(y.shape[0])
noise_coef = (linalg.norm(y, 2) / np.exp(snr / 20.)) / linalg.norm(noise, 2)
y += noise_coef * noise  # add noise

# #############################################################################
# Compute the coefs of a Bayesian Ridge with GridSearch
cv = KFold(2)  # cross-validation generator for model selection
ridge = BayesianRidge()
cachedir = tempfile.mkdtemp()
mem = Memory(location=cachedir, verbose=1)

# Ward agglomeration followed by BayesianRidge
connectivity = grid_to_graph(n_x=size, n_y=size)
ward = FeatureAgglomeration(n_clusters=10, connectivity=connectivity,
                            memory=mem)
clf = Pipeline([['ward', ward], ('ridge', ridge)])
# Select the optimal number of parcels with grid search
clf = GridSearchCV(clf, {'ward__n_clusters': [10, 20, 30]}, n_jobs=1, cv=cv)
clf.fit(X, y)  # set the best parameters
coef_ = clf.best_estimator_.steps[-1][1].coef_
coef_agglomeration_ = coef_.reshape(size, size)

# Anova univariate feature selection followed by BayesianRidge
f_regression = mem.cache(feature_selection.f_regression)  # caching function
anova = feature_selection.SelectPercentile(f_regression)
clf = Pipeline([['anova', anova], ('ridge', ridge)])
# Select the optimal percentage of features with grid search
clf = GridSearchCV(clf, {'anova__percentile': [5, 10, 20]}, cv=cv)
clf.fit(X, y)  # set the best parameters
coef_ = clf.best_estimator_.steps[-1][1].coef_
Total running time of the script: ( 0 minutes 0.608 seconds)

6.5.26 Comparing different hierarchical linkage methods on toy datasets

This example shows characteristics of different linkage methods for hierarchical clustering on datasets that are “interesting” but still in 2D.

The main observations to make are:

• single linkage is fast, and can perform well on non-globular data, but it performs poorly in the presence of noise.
• average and complete linkage perform well on cleanly separated globular clusters, but have mixed results otherwise.
• Ward is the most effective method for noisy data.

While these examples give some intuition about the algorithms, this intuition might not apply to very high dimensional data.
n_samples = 1500
noisy_circles = datasets.make_circles(n_samples=n_samples, factor=.5,
    noise=.05)
noisy_moons = datasets.make_moons(n_samples=n_samples, noise=.05)
blobs = datasets.make_blobs(n_samples=n_samples, random_state=8)
no_structure = np.random.rand(n_samples, 2), None

# Anisotropically distributed data
random_state = 170
X, y = datasets.make_blobs(n_samples=n_samples, random_state=random_state)
transformation = [[0.6, -0.6], [-0.4, 0.8]]
X_aniso = np.dot(X, transformation)
aniso = (X_aniso, y)

# blobs with varied variances
varied = datasets.make_blobs(n_samples=n_samples,
    cluster_std=[1.0, 2.5, 0.5],
    random_state=random_state)

Run the clustering and plot

# Set up cluster parameters
plt.figure(figsize=(9 * 1.3 + 2, 14.5))
plt.subplots_adjust(left=.02, right=.98, bottom=.001, top=.96, wspace=.05,
    hspace=.01)
plot_num = 1
default_base = {'n_neighbors': 10,
    'n_clusters': 3}
datasets = [
    (noisy_circles, {'n_clusters': 2}),
    (noisy_moons, {'n_clusters': 2}),
    (varied, {'n_neighbors': 2}),
    (aniso, {'n_neighbors': 2}),
    (blobs, {}),
    (no_structure, {})]

for i_dataset, (dataset, algo_params) in enumerate(datasets):
    # update parameters with dataset-specific values
    params = default_base.copy()
    params.update(algo_params)
    X, y = dataset
    # normalize dataset for easier parameter selection
    X = StandardScaler().fit_transform(X)
    # ============
    # Create cluster objects
    # ============
    ward = cluster.AgglomerativeClustering(
        n_clusters=params['n_clusters'], linkage='ward')
    complete = cluster.AgglomerativeClustering(
        n_clusters=params['n_clusters'], linkage='complete')
    average = cluster.AgglomerativeClustering(}
n_clusters=params['n_clusters'], linkage='average')
single = cluster.AgglomerativeClustering(
    n_clusters=params['n_clusters'], linkage='single')

clustering_algorithms = (
    ('Single Linkage', single),
    ('Average Linkage', average),
    ('Complete Linkage', complete),
    ('Ward Linkage', ward),
)

for name, algorithm in clustering_algorithms:
    t0 = time.time()

    # catch warnings related to kneighbors_graph
    with warnings.catch_warnings():
        warnings.filterwarnings(
            "ignore",
            message="the number of connected components of the " +
            "connectivity matrix is [0-9]+\([1,2]\)" +
            " > 1. Completing it to avoid stopping the tree early.",
            category=UserWarning)
        algorithm.fit(X)

    t1 = time.time()
    if hasattr(algorithm, 'labels_'):
        y_pred = algorithm.labels_.astype(int)
    else:
        y_pred = algorithm.predict(X)

    plt.subplot(len(datasets), len(clustering_algorithms), plot_num)
    if i_dataset == 0:
        plt.title(name, size=18)

    colors = np.array(list(islice(cycle(['#377eb8', '#ff7f00', '#4daf4a',
                                           '#f781bf', '#a65628', '#984ea3',
                                           '#999999', '#e41a1c', '#dede00']),
                                          int(max(y_pred) + 1))))
    plt.scatter(X[:, 0], X[:, 1], s=10, color=colors[y_pred])
    plt.xlim(-2.5, 2.5)
    plt.ylim(-2.5, 2.5)
    plt.xticks(())
    plt.yticks(()
    plt.text(.99, .01, ('%.2fs' % (t1 - t0)).lstrip('0'),
                transform=plt.gca().transAxes, size=15,
                horizontalalignment='right')
    plot_num += 1

plt.show()
Total running time of the script: (0 minutes 2.547 seconds)
6.5.27 A demo of K-Means clustering on the handwritten digits data

In this example we compare the various initialization strategies for K-means in terms of runtime and quality of the results.

As the ground truth is known here, we also apply different cluster quality metrics to judge the goodness of fit of the cluster labels to the ground truth.

Cluster quality metrics evaluated (see Clustering performance evaluation for definitions and discussions of the metrics):

<table>
<thead>
<tr>
<th>Shorthand</th>
<th>full name</th>
</tr>
</thead>
<tbody>
<tr>
<td>homo</td>
<td>homogeneity score</td>
</tr>
<tr>
<td>compl</td>
<td>completeness score</td>
</tr>
<tr>
<td>v-meas</td>
<td>V measure</td>
</tr>
<tr>
<td>ARI</td>
<td>adjusted Rand index</td>
</tr>
<tr>
<td>AMI</td>
<td>adjusted mutual information</td>
</tr>
<tr>
<td>silhouette</td>
<td>silhouette coefficient</td>
</tr>
</tbody>
</table>

Load the dataset

We will start by loading the digits dataset. This dataset contains handwritten digits from 0 to 9. In the context of clustering, one would like to group images such that the handwritten digits on the image are the same.

```
import numpy as np
from sklearn.datasets import load_digits

data, labels = load_digits(return_X_y=True)
(n_samples, n_features), n_digits = data.shape, np.unique(labels).size

print(f"# digits: {n_digits}; # samples: {n_samples}; # features {n_features}" )
```

Out:

```
# digits: 10; # samples: 1797; # features 64
```

Define our evaluation benchmark

We will first our evaluation benchmark. During this benchmark, we intend to compare different initialization methods for KMeans. Our benchmark will:

- create a pipeline which will scale the data using a StandardScaler;
- train and time the pipeline fitting;
- measure the performance of the clustering obtained via different metrics.

```
from time import time
from sklearn import metrics
from sklearn.pipeline import make_pipeline
```

(continues on next page)
from sklearn.preprocessing import StandardScaler

def bench_k_means(kmeans, name, data, labels):
    """Benchmark to evaluate the KMeans initialization methods.

    Parameters
    ----------
    kmeans : KMeans instance
        A :class:`~sklearn.cluster.KMeans` instance with the initialization
        already set.
    name : str
        Name given to the strategy. It will be used to show the results in a
        table.
    data : ndarray of shape (n_samples, n_features)
        The data to cluster.
    labels : ndarray of shape (n_samples,)
        The labels used to compute the clustering metrics which requires some
        supervision.
    """
    t0 = time()
estimator = make_pipeline(StandardScaler(), kmeans).fit(data)
    fit_time = time() - t0
    results = [name, fit_time, estimator[-1].inertia_]

    # Define the metrics which require only the true labels and estimator
    # labels.
    clustering_metrics = [
        metrics.homogeneity_score,
        metrics.completeness_score,
        metrics.v_measure_score,
        metrics.adjusted_rand_score,
        metrics.adjusted_mutual_info_score,
    ]
    results += [m(labels, estimator[-1].labels_) for m in clustering_metrics]

    # The silhouette score requires the full dataset
    results += [
        metrics.silhouette_score(data, estimator[-1].labels_,
                                  metric="euclidean", sample_size=300,)
    ]

    # Show the results
    formatter_result = ("{:9s}t{:3f}s\t{:10f}\t{:3f}\t{:3f}\t{:3f}\t{:3f}\"""
                        "t{:3f}\t{:3f}\t{:3f}\t{:3f}\t{:3f}"")
    print(formatter_result.format(*results))
Run the benchmark

We will compare three approaches:

- an initialization using kmeans++. This method is stochastic and we will run the initialization 4 times;
- a random initialization. This method is stochastic as well and we will run the initialization 4 times;
- an initialization based on a PCA projection. Indeed, we will use the components of the PCA to initialize KMeans. This method is deterministic and a single initialization suffice.

```python
from sklearn.cluster import KMeans
from sklearn.decomposition import PCA

print(82 * '_')
print('init
time
ingertia
t homo
tcompl
tv-meas
 tARI
tAMI
tsilhouette')

kmeans = KMeans(init="k-means++", n_clusters=n_digits, n_init=4, random_state=0)
bench_k_means(kmeans=kmeans, name="k-means++", data=data, labels=labels)

kmeans = KMeans(init="random", n_clusters=n_digits, n_init=4, random_state=0)
bench_k_means(kmeans=kmeans, name="random", data=data, labels=labels)

pca = PCA(n_components=n_digits).fit(data)
kmeans = KMeans(init=pca.components_, n_clusters=n_digits, n_init=1)
bench_k_means(kmeans=kmeans, name="PCA-based", data=data, labels=labels)

print(82 * '_')
```

```python
Out:

<table>
<thead>
<tr>
<th>init</th>
<th>time</th>
<th>inertia</th>
<th>homo</th>
<th>compl</th>
<th>v-meas</th>
<th>ARI</th>
<th>AMI</th>
<th>silhouette</th>
</tr>
</thead>
<tbody>
<tr>
<td>k-means++</td>
<td>0.070s</td>
<td>69662</td>
<td>0.680</td>
<td>0.719</td>
<td>0.699</td>
<td>0.570</td>
<td>0.695</td>
<td>0.173</td>
</tr>
<tr>
<td>random</td>
<td>0.049s</td>
<td>69707</td>
<td>0.675</td>
<td>0.716</td>
<td>0.694</td>
<td>0.560</td>
<td>0.691</td>
<td>0.188</td>
</tr>
<tr>
<td>PCA-based</td>
<td>0.018s</td>
<td>72686</td>
<td>0.636</td>
<td>0.658</td>
<td>0.647</td>
<td>0.521</td>
<td>0.643</td>
<td>0.144</td>
</tr>
</tbody>
</table>
```

Visualize the results on PCA-reduced data

PCA allows to project the data from the original 64-dimensional space into a lower dimensional space. Subsequently, we can use PCA to project into a 2-dimensional space and plot the data and the clusters in this new space.

```python
import matplotlib.pyplot as plt

reduced_data = PCA(n_components=2).fit_transform(data)
kmeans = KMeans(init="k-means++", n_clusters=n_digits, n_init=4)
kmeans.fit(reduced_data)

# Step size of the mesh. Decrease to increase the quality of the VQ.
h = .02 # point in the mesh [x_min, x_max]x[y_min, y_max].

# Plot the decision boundary. For that, we will assign a color to each
x_min, x_max = reduced_data[:, 0].min() - 1, reduced_data[:, 0].max() + 1
y_min, y_max = reduced_data[:, 1].min() - 1, reduced_data[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))
```

(continues on next page)
# Obtain labels for each point in mesh. Use last trained model.
Z = kmeans.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
plt.figure(1)
plt.clf()
plt.imshow(Z, interpolation="nearest",
    extent=(xx.min(), xx.max(), yy.min(), yy.max()),
    cmap=plt.cm.Paired, aspect="auto", origin="lower")
plt.plot(reduced_data[:, 0], reduced_data[:, 1], 'k.', markersize=2)
# Plot the centroids as a white X
centroids = kmeans.cluster_centers_
plt.scatter(centroids[:, 0], centroids[:, 1], marker="x", s=169, linewidths=3,
    color="w", zorder=10)
plt.title("K-means clustering on the digits dataset (PCA-reduced data)"
    "Centroids are marked with white cross")
plt.xlim(x_min, x_max)
plt.ylim(y_min, y_max)
plt.xticks(())
plt.yticks(())
plt.show()
6.5.28 Selecting the number of clusters with silhouette analysis on KMeans clustering

Silhouette analysis can be used to study the separation distance between the resulting clusters. The silhouette plot displays a measure of how close each point in one cluster is to points in the neighboring clusters and thus provides a way to assess parameters like number of clusters visually. This measure has a range of [-1, 1].

Silhouette coefficients (as these values are referred to as) near +1 indicate that the sample is far away from the neighboring clusters. A value of 0 indicates that the sample is on or very close to the decision boundary between two neighboring clusters and negative values indicate that those samples might have been assigned to the wrong cluster.

In this example the silhouette analysis is used to choose an optimal value for n_clusters. The silhouette plot shows that the n_clusters value of 3, 5 and 6 are a bad pick for the given data due to the presence of clusters with below average silhouette scores and also due to wide fluctuations in the size of the silhouette plots. Silhouette analysis is more ambivalent in deciding between 2 and 4.

Also from the thickness of the silhouette plot the cluster size can be visualized. The silhouette plot for cluster 0 when n_clusters is equal to 2, is bigger in size owing to the grouping of the 3 sub clusters into one big cluster. However when the n_clusters is equal to 4, all the plots are more or less of similar thickness and hence are of similar sizes as can be also verified from the labelled scatter plot on the right.
Out:

For n_clusters = 2 The average silhouette_score is : 0.7049787496083262
For n_clusters = 3 The average silhouette_score is : 0.5882004012129721
For n_clusters = 4 The average silhouette_score is : 0.6505186632729437
For n_clusters = 5 The average silhouette_score is : 0.56376469026194
For n_clusters = 6 The average silhouette_score is : 0.4504666294372765
from sklearn.datasets import make_blobs
from sklearn.cluster import KMeans
from sklearn.metrics import silhouette_samples, silhouette_score

import matplotlib.pyplot as plt
import matplotlib.cm as cm
import numpy as np

print(__doc__)

# Generating the sample data from make_blobs
# This particular setting has one distinct cluster and 3 clusters placed close
# together.
X, y = make_blobs(n_samples=500,
                  n_features=2,
                  centers=4,
                  cluster_std=1,
                  center_box=(-10.0, 10.0),
                  shuffle=True,
                  random_state=1)  # For reproducibility

range_n_clusters = [2, 3, 4, 5, 6]

for n_clusters in range_n_clusters:
    # Create a subplot with 1 row and 2 columns
    fig, (ax1, ax2) = plt.subplots(1, 2)
    fig.set_size_inches(18, 7)

    # The 1st subplot is the silhouette plot
    # The silhouette coefficient can range from -1, 1 but in this example all
    # lie within [-0.1, 1]
    ax1.set_xlim([-0.1, 1])
    ax1.set_ylim([0, len(X) + (n_clusters + 1) * 10])

    # The (n_clusters+1)*10 is for inserting blank space between silhouette
    # plots of individual clusters, to demarcate them clearly.
    ax1.set_yticks([])
    ax1.set_yticks(np.arange(y_lower, y_upper, (n_clusters + 1) * 10))
    ax1.set_yticklabels(
        range(y_lower, y_upper, (n_clusters + 1) * 10)
    )

    # Initialize the clusterer with n_clusters value and a random generator
    # seed of 10 for reproducibility.
    clusterer = KMeans(n_clusters=n_clusters, random_state=10)
    cluster_labels = clusterer.fit_predict(X)

    # The silhouette_score gives the average value for all the samples.
    # This gives a perspective into the density and separation of the formed
    # clusters
    silhouette_avg = silhouette_score(X, cluster_labels)
    print("For n_clusters =", n_clusters,
       "The average silhouette_score is ": silhouette_avg)

    # Compute the silhouette scores for each sample
    sample_silhouette_values = silhouette_samples(X, cluster_labels)

    y_lower = 10
    for i in range(n_clusters):
        # Aggregate the silhouette scores for samples belonging to
        # (continues on next page)
# cluster i, and sort them
ith_cluster_silhouette_values = \
    sample_silhouette_values[cluster_labels == i]

ith_cluster_silhouette_values.sort()

size_cluster_i = ith_cluster_silhouette_values.shape[0]
y_upper = y_lower + size_cluster_i

color = cm.nipy_spectral(float(i) / n_clusters)
ax1.fill_betweenx(np.arange(y_lower, y_upper),
    0, ith_cluster_silhouette_values,
    facecolor=color, edgecolor=color, alpha=0.7)

# Label the silhouette plots with their cluster numbers at the middle
ax1.text(-0.05, y_lower + 0.5 * size_cluster_i, str(i))

# Compute the new y_lower for next plot
y_lower = y_upper + 10  # 10 for the 0 samples

ax1.set_title("The silhouette plot for the various clusters.")
ax1.set_xlabel("The silhouette coefficient values")
ax1.set_ylabel("Cluster label")

# The vertical line for average silhouette score of all the values
ax1.axvline(x=silhouette_avg, color="red", linestyle="--")

ax1.set_yticks([])  # Clear the yaxis labels / ticks
ax1.set_xticks([-0.1, 0, 0.2, 0.4, 0.6, 0.8, 1])

# 2nd Plot showing the actual clusters formed
colors = cm.nipy_spectral(cluster_labels.astype(float) / n_clusters)
ax2.scatter(X[:, 0], X[:, 1], marker='.', s=30, lw=0, alpha=0.7,
    c=colors, edgecolor='k')

# Labeling the clusters
centers = clusterer.cluster_centers_
# Draw white circles at cluster centers
ax2.scatter(c[:, 0], c[:, 1], marker='o',
    c="white", alpha=1, s=200, edgecolor='k')

for i, c in enumerate(c):
    ax2.scatter(c[0], c[1], marker='%d' % i, alpha=1,
        s=50, edgecolor='k')

ax2.set_title("The visualization of the clustered data.")
ax2.set_xlabel("Feature space for the 1st feature")
ax2.set_ylabel("Feature space for the 2nd feature")

plt.suptitle("Silhouette analysis for KMeans clustering on sample data "
    "with n_clusters = %d" % n_clusters,
    fontsize=14, fontweight='bold')

plt.show()
6.5.29 Comparing different clustering algorithms on toy datasets

This example shows characteristics of different clustering algorithms on datasets that are “interesting” but still in 2D. With the exception of the last dataset, the parameters of each of these dataset-algorithm pairs has been tuned to produce good clustering results. Some algorithms are more sensitive to parameter values than others.

The last dataset is an example of a ‘null’ situation for clustering: the data is homogeneous, and there is no good clustering. For this example, the null dataset uses the same parameters as the dataset in the row above it, which represents a mismatch in the parameter values and the data structure.

While these examples give some intuition about the algorithms, this intuition might not apply to very high dimensional data.

Out:

```python
/home/circleci/project/sklearn/cluster/_affinity_propagation.py:148: FutureWarning:
    'random_state' has been introduced in 0.23. It will be set to None starting from 1.
    Set 'random_state' to None to silence this warning, or to 0 to keep the behavior of versions <0.23.
    warnings.warn(  
/home/circleci/project/sklearn/cluster/_affinity_propagation.py:148: FutureWarning:
    'random_state' has been introduced in 0.23. It will be set to None starting from 1.
    Set 'random_state' to None to silence this warning, or to 0 to keep the behavior of versions <0.23.
    warnings.warn(  
/home/circleci/project/sklearn/cluster/_affinity_propagation.py:148: FutureWarning:
    'random_state' has been introduced in 0.23. It will be set to None starting from 1.
    Set 'random_state' to None to silence this warning, or to 0 to keep the behavior of versions <0.23.
    warnings.warn(  
(continues on next page)```
# Scikit-learn User Guide, Release 0.24.0

## 6.5. Clustering

---

```python
import warnings
import numpy as np
import matplotlib.pyplot as plt
from sklearn import cluster, datasets, mixture
from sklearn.neighbors import kneighbors_graph
from sklearn.preprocessing import StandardScaler
from itertools import cycle, islice

np.random.seed(0)

print(__doc__)

import time
import warnings
import numpy as np
import matplotlib.pyplot as plt

from sklearn import cluster, datasets, mixture
from sklearn.neighbors import kneighbors_graph
from sklearn.preprocessing import StandardScaler
from itertools import cycle, islice

np.random.seed(0)

# Generate datasets. We choose the size big enough to see the scalability
# of the algorithms, but not too big to avoid too long running times
n_samples = 1500
noisy_circles = datasets.make_circles(n_samples=n_samples, factor=.5,
    noise=.05)
noisy_moons = datasets.make_moons(n_samples=n_samples, noise=.05)
blobs = datasets.make_blobs(n_samples=n_samples, random_state=8)
no_structure = np.random.rand(n_samples, 2), None

# Anisotropically distributed data
random_state = 170
X, y = datasets.make_blobs(n_samples=n_samples, random_state=random_state)
transformation = [[0.6, -0.6], [-0.4, 0.8]]
X_aniso = np.dot(X, transformation)
```

(continues on next page)
aniso = (X_aniso, y)

# blobs with varied variances
varied = datasets.make_blobs(n_samples=n_samples,
                              cluster_std=[1.0, 2.5, 0.5],
                              random_state=random_state)

# ============
# Set up cluster parameters
# ============
plt.figure(figsize=(9 * 2 + 3, 12.5))
plt.subplots_adjust(left=.02, right=.98, bottom=.001, top=.96, wspace=.05,
                    hspace=.01)
plot_num = 1

default_base = {'quantile': .3,
                 'eps': .3,
                 'damping': .9,
                 'preference': -200,
                 'n_neighbors': 10,
                 'n_clusters': 3,
                 'min_samples': 20,
                 'xi': 0.05,
                 'min_cluster_size': 0.1}

datasets = [
    (noisy_circles, {'damping': .77, 'preference': -240,
                     'quantile': .2, 'n_clusters': 2,
                     'min_samples': 20, 'xi': 0.25}),
    (noisy_moons, {'damping': .75, 'preference': -220, 'n_clusters': 2}),
    (varied, {'eps': .18, 'n_neighbors': 2,
              'min_samples': 5, 'xi': 0.035, 'min_cluster_size': .2}),
    (aniso, {'eps': .15, 'n_neighbors': 2,
             'min_samples': 20, 'xi': 0.1, 'min_cluster_size': .2}),
    (blobs, {}),
    (no_structure, {})]

for i_dataset, (dataset, algo_params) in enumerate(datasets):
    # update parameters with dataset-specific values
    params = default_base.copy()
    params.update(algo_params)

    X, y = dataset

    # normalize dataset for easier parameter selection
    X = StandardScaler().fit_transform(X)

    # estimate bandwidth for mean shift
    bandwidth = cluster.estimate_bandwidth(X, quantile=params['quantile'])

    # connectivity matrix for structured Ward
    connectivity = kneighbors_graph(
        X, n_neighbors=params['n_neighbors'], include_self=False)
    # make connectivity symmetric
    connectivity = 0.5 * (connectivity + connectivity.T)
# Create cluster objects
ms = cluster.MeanShift(bandwidth=bandwidth, bin_seeding=True)
two_means = cluster.MiniBatchKMeans(n_clusters=params['n_clusters'])
ward = cluster.AgglomerativeClustering(
    n_clusters=params['n_clusters'], linkage='ward',
    connectivity=connectivity)
spectral = cluster.SpectralClustering(
    n_clusters=params['n_clusters'], eigen_solver='arpack',
    affinity="nearest_neighbors")
dbscan = cluster.DBSCAN(eps=params['eps'])
optics = cluster.OPTICS(min_samples=params['min_samples'],
    xi=params['xi'],
    min_cluster_size=params['min_cluster_size'])
affinity_propagation = cluster.AffinityPropagation(
    damping=params['damping'], preference=params['preference'])
average_linkage = cluster.AgglomerativeClustering(
    linkage="average", affinity="cityblock",
    n_clusters=params['n_clusters'], connectivity=connectivity)
birch = cluster.Birch(n_clusters=params['n_clusters'])
gmm = mixture.GaussianMixture(
    n_components=params['n_clusters'], covariance_type='full')

clustering_algorithms = (
    ('MiniBatchKMeans', two_means),
    ('AffinityPropagation', affinity_propagation),
    ('MeanShift', ms),
    ('SpectralClustering', spectral),
    ('Ward', ward),
    ('AgglomerativeClustering', average_linkage),
    ('DBSCAN', dbscan),
    ('OPTICS', optics),
    ('Birch', birch),
    ('GaussianMixture', gmm)
)

for name, algorithm in clustering_algorithms:
    t0 = time.time()
    try:
        warnings.catch_warnings()
        warnings.filterwarnings("ignore",
        message="the number of connected components of the " +
        "connectivity matrix is [0-9]{1,2}" +
        " > 1. Completing it to avoid stopping the tree early.",
        category=UserWarning)
        warnings.filterwarnings("ignore",
        message="Graph is not fully connected, spectral embedding" +
        " may not work as expected.",
        category=UserWarning)
        algorithm.fit(X)
    finally:
        t1 = time.time()
        if hasattr(algorithm, 'labels_'):
y_pred = algorithm.labels_.astype(int)
else:
y_pred = algorithm.predict(X)

plt.subplot(len(datasets), len(clustering_algorithms), plot_num)
if i_dataset == 0:
    plt.title(name, size=18)

colors = np.array(list(islice(cycle(['#377eb8', '#ff7f00', '#4daf4a',
                                         '#f781bf', '#a65628', '#984ea3',
                                         '#999999', '#e41a1c', '#dede00']),
                                       int(max(y_pred) + 1))))
# add black color for outliers (if any)
colors = np.append(colors, ['#000000'])
plt.scatter(X[:, 0], X[:, 1], s=10, color=colors[y_pred])

plt.xlim(-2.5, 2.5)
plt.ylim(-2.5, 2.5)
plt.xticks(())
plt.yticks(())
plt.text(.99, .01, ('%.2f s' % (t1 - t0)).lstrip('0'),
          transform=plt.gca().transAxes, size=15,
          horizontalalignment='right')
plot_num += 1

plt.show()
from sklearn.covariance import LedoitWolf, OAS
np.random.seed(0)

n_features = 100
# simulation covariance matrix (AR(1) process)
r = 0.1
real_cov = toeplitz(r ** np.arange(n_features))
coloring_matrix = cholesky(real_cov)

n_samples_range = np.arange(6, 31, 1)
repeat = 100
lw_mse = np.zeros((n_samples_range.size, repeat))
oa_mse = np.zeros((n_samples_range.size, repeat))
lw_shrinkage = np.zeros((n_samples_range.size, repeat))
oa_shrinkage = np.zeros((n_samples_range.size, repeat))

for i, n_samples in enumerate(n_samples_range):
    for j in range(repeat):
        X = np.dot(
            np.random.normal(size=(n_samples, n_features)),
            coloring_matrix.T)

        lw = LedoitWolf(store_precision=False, assume_centered=True)
        lw.fit(X)
        lw_mse[i, j] = lw.error_norm(real_cov, scaling=False)
        lw_shrinkage[i, j] = lw.shrinkage_

        oa = OAS(store_precision=False, assume_centered=True)
        oa.fit(X)
        oa_mse[i, j] = oa.error_norm(real_cov, scaling=False)
        oa_shrinkage[i, j] = oa.shrinkage_

# plot MSE
plt.subplot(2, 1, 1)
plt.errorbar(n_samples_range, lw_mse.mean(1), yerr=lw_mse.std(1),
             label='Ledoit-Wolf', color='navy', lw=2)
plt.errorbar(n_samples_range, oa_mse.mean(1), yerr=oa_mse.std(1),
             label='OAS', color='darkorange', lw=2)
plt.ylabel("Squared error")
plt.legend(loc="upper right")
plt.title("Comparison of covariance estimators")
plt.xlim(5, 31)

# plot shrinkage coefficient
plt.subplot(2, 1, 2)
plt.errorbar(n_samples_range, lw_shrinkage.mean(1), yerr=lw_shrinkage.std(1),
             label='Ledoit-Wolf', color='navy', lw=2)
plt.errorbar(n_samples_range, oa_shrinkage.mean(1), yerr=oa_shrinkage.std(1),
             label='OAS', color='darkorange', lw=2)
plt.xlabel("n_samples")
plt.ylabel("Shrinkage")
plt.legend(loc="lower right")
plt ylim([0], 1 + (plt ylim()[1] - plt ylim()[0]) / 10.)
plt.xlim(5, 31)
plt.show()
6.6.2 Sparse inverse covariance estimation

Using the GraphicalLasso estimator to learn a covariance and sparse precision from a small number of samples.

To estimate a probabilistic model (e.g. a Gaussian model), estimating the precision matrix, that is the inverse covariance matrix, is as important as estimating the covariance matrix. Indeed a Gaussian model is parametrized by the precision matrix.

To be in favorable recovery conditions, we sample the data from a model with a sparse inverse covariance matrix. In addition, we ensure that the data is not too much correlated (limiting the largest coefficient of the precision matrix) and that there are no small coefficients in the precision matrix that cannot be recovered. In addition, with a small number of observations, it is easier to recover a correlation matrix rather than a covariance, thus we scale the time series.

Here, the number of samples is slightly larger than the number of dimensions, thus the empirical covariance is still invertible. However, as the observations are strongly correlated, the empirical covariance matrix is ill-conditioned and as a result its inverse—the empirical precision matrix—is very far from the ground truth.

If we use l2 shrinkage, as with the Ledoit-Wolf estimator, as the number of samples is small, we need to shrink a lot. As a result, the Ledoit-Wolf precision is fairly close to the ground truth precision, that is not far from being diagonal, but the off-diagonal structure is lost.

The l1-penalized estimator can recover part of this off-diagonal structure. It learns a sparse precision. It is not able to recover the exact sparsity pattern: it detects too many non-zero coefficients. However, the highest non-zero coefficients of the l1 estimated correspond to the non-zero coefficients in the ground truth. Finally, the coefficients of
the l1 precision estimate are biased toward zero: because of the penalty, they are all smaller than the corresponding ground truth value, as can be seen on the figure.

Note that, the color range of the precision matrices is tweaked to improve readability of the figure. The full range of values of the empirical precision is not displayed.

The alpha parameter of the GraphicalLasso setting the sparsity of the model is set by internal cross-validation in the GraphicalLassoCV. As can be seen on figure 2, the grid to compute the cross-validation score is iteratively refined in the neighborhood of the maximum.

```
print(__doc__)
# author: Gael Varoquaux <gael.varoquaux@inria.fr>
# License: BSD 3 clause
```
import numpy as np
from scipy import linalg
from sklearn.datasets import make_sparse_spd_matrix
from sklearn.covariance import GraphicalLassoCV, ledoit_wolf
import matplotlib.pyplot as plt

# Generate the data
n_samples = 60
n_features = 20

prng = np.random.RandomState()
prec = make_sparse_spd_matrix(n_features, alpha=.98,
                             smallest_coef=.4,
                             largest_coef=.7,
                             random_state=prng)

cov = linalg.inv(prec)
d = np.sqrt(np.diag(cov))
cov /= d
cov /= d[:, np.newaxis]
prec *= d
prec *= d[:, np.newaxis]
X = prng.multivariate_normal(np.zeros(n_features), cov, size=n_samples)
X -= X.mean(axis=0)
X /= X.std(axis=0)

# Estimate the covariance
emp_cov = np.dot(X.T, X) / n_samples
model = GraphicalLassoCV()
model.fit(X)
cov_ = model.covariance_
prec_ = model.precision_

lw_cov_, _ = ledoit_wolf(X)
lw_prec_ = linalg.inv(lw_cov_)

# Plot the results
plt.figure(figsize=(10, 6))
plt.subplots_adjust(left=0.02, right=0.98)

covs = [('Empirical', emp_cov), ('Ledoit-Wolf', lw_cov_),
        ('GraphicalLassoCV', cov_),
        ('True', cov_)]
vmax = cov_.max()
for i, (name, this_cov) in enumerate(covs):
    plt.subplot(2, 4, i + 1)
    plt.imshow(this_cov, interpolation='nearest', vmin=-vmax, vmax=vmax,
                cmap=plt.cm.RdBu_r)
    plt.xticks(())
    plt.yticks(()
    plt.title('%s covariance' % name)
# plot the precisions
prec = [('Empirical', linalg.inv(emp_cov)), ('Ledoit-Wolf', lw_prec_),
        ('GraphicalLasso', prec_), ('True', prec)]
vmax = .9 * prec_.max()
for i, (name, this_prec) in enumerate(prec):
    ax = plt.subplot(2, 4, i + 5)
    plt.imshow(np.ma.masked_equal(this_prec, 0),
               interpolation='nearest', vmin=-vmax, vmax=vmax,
               cmap=plt.cm.RdBu_r)
    plt.xticks(())
    plt.yticks(()
    plt.title('Precision ' % name)
    if hasattr(ax, 'set_facecolor'):
        ax.set_facecolor('.7')
    else:
        ax.set_axis_bgcolor('.7')

# plot the model selection metric
plt.figure(figsize=(4, 3))
plt.axes([.2, .15, .75, .7])
plt.plot(model.cv_results_['alphas'], model.cv_results_['mean_score'], 'o-')
plt.axvline(model.alpha_, color='.5')
plt.title('Model selection')
plt.ylabel('Cross-validation score')
plt.xlabel('alpha')
plt.show()

Total running time of the script: ( 0 minutes 0.766 seconds)

6.6.3 Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood

When working with covariance estimation, the usual approach is to use a maximum likelihood estimator, such as the 
EmpiricalCovariance. It is unbiased, i.e. it converges to the true (population) covariance when given many 
observations. However, it can also be beneficial to regularize it, in order to reduce its variance; this, in turn, introduces 
some bias. This example illustrates the simple regularization used in Shrunk Covariance estimators. In particular, it 
focuses on how to set the amount of regularization, i.e. how to choose the bias-variance trade-off.

Here we compare 3 approaches:

- Setting the parameter by cross-validating the likelihood on three folds according to a grid of potential shrinkage parameters.
- A close formula proposed by Ledoit and Wolf to compute the asymptotically optimal regularization parameter
  (minimizing a MSE criterion), yielding the LedoitWolf covariance estimate.
- An improvement of the Ledoit-Wolf shrinkage, the OAS, proposed by Chen et al. Its convergence is significantly
  better under the assumption that the data are Gaussian, in particular for small samples.

To quantify estimation error, we plot the likelihood of unseen data for different values of the shrinkage parameter. We 
also show the choices by cross-validation, or with the LedoitWolf and OAS estimates.

Note that the maximum likelihood estimate corresponds to no shrinkage, and thus performs poorly. The Ledoit-Wolf
estimate performs really well, as it is close to the optimal and is computational not costly. In this example, the OAS
estimate is a bit further away. Interestingly, both approaches outperform cross-validation, which is significantly most 
computationally costly.
import numpy as np
import matplotlib.pyplot as plt
from scipy import linalg
from sklearn.covariance import LedoitWolf, OAS, ShrunkCovariance, log_likelihood, empirical_covariance
from sklearn.model_selection import GridSearchCV

# #############################################################################
# Generate sample data
n_features, n_samples = 40, 20
np.random.seed(42)
bases_X_train = np.random.normal(size=(n_samples, n_features))
bases_X_test = np.random.normal(size=(n_samples, n_features))

# Color samples
coloring_matrix = np.random.normal(size=(n_features, n_features))
X_train = np.dot(bases_X_train, coloring_matrix)
X_test = np.dot(bases_X_test, coloring_matrix)

# #############################################################################
# Compute the likelihood on test data
(continues on next page)
# spanning a range of possible shrinkage coefficient values
shrinkages = np.logspace(-2, 0, 30)
negative_logliks = [-ShrunkCovariance(shrinkage=s).fit(X_train).score(X_test)
    for s in shrinkages]

# under the ground-truth model, which we would not have access to in real
# settings
real_cov = np.dot(coloring_matrix.T, coloring_matrix)
emp_cov = empirical_covariance(X_train)
loglik_real = -log_likelihood(emp_cov, linalg.inv(real_cov))

# #############################################################################
# Compare different approaches to setting the parameter
# GridSearch for an optimal shrinkage coefficient
tuned_parameters = [{'shrinkage': shrinkages}]
sc = GridSearchCV(ShrunkCovariance(), tuned_parameters)
s.fit(X_train)

# Ledoit-Wolf optimal shrinkage coefficient estimate
lw = LedoitWolf()
loglik_lw = lw.fit(X_train).score(X_test)

# OAS coefficient estimate
oa = OAS()
loglik_oa = oa.fit(X_train).score(X_test)

# #############################################################################
# Plot results
fig = plt.figure()
plt.title("Regularized covariance: likelihood and shrinkage coefficient")
plt.xlabel('Regularization parameter: shrinkage coefficient')
plt.ylabel('Error: negative log-likelihood on test data')
plt.loglog(shrinkages, negative_logliks, label="Negative log-likelihood")
plt.plot(plt.xlim(), 2 * [loglik_real], '--r', label="Real covariance likelihood")
lik_max = np.amax(negative_logliks)
lik_min = np.amin(negative_logliks)
ymin = lik_min - 6. * np.log((plt.ylim())[1] - plt.ylim()[0])
ymax = lik_max + 10. * np.log(lik_max - lik_min)
xmin = shrinkages[0]
xmax = shrinkages[-1]
plt.vlines(lw.shrinkage_, ymin, -loglik_lw, color='magenta',
    linewidth=3, label="Ledoit-Wolf estimate")
plt.vlines(oa.shrinkage_, ymin, -loglik_oa, color='purple',
    linewidth=3, label="OAS estimate")
plt.vlines(s.best_estimator_.shrinkage, ymin, -s.best_estimator_.score(X_test),
    color='cyan', linewidth=3, label="Cross-validation best estimate")

(continues on next page)
6.6.4 Robust covariance estimation and Mahalanobis distances relevance

This example shows covariance estimation with Mahalanobis distances on Gaussian distributed data.

For Gaussian distributed data, the distance of an observation \( x_i \) to the mode of the distribution can be computed using its Mahalanobis distance:

\[
d(\mu, \Sigma)(x_i)^2 = (x_i - \mu)^T \Sigma^{-1} (x_i - \mu)
\]

where \( \mu \) and \( \Sigma \) are the location and the covariance of the underlying Gaussian distributions.

In practice, \( \mu \) and \( \Sigma \) are replaced by some estimates. The standard covariance maximum likelihood estimate (MLE) is very sensitive to the presence of outliers in the data set and therefore, the downstream Mahalanobis distances also are. It would be better to use a robust estimator of covariance to guarantee that the estimation is resistant to “erroneous” observations in the dataset and that the calculated Mahalanobis distances accurately reflect the true organization of the observations.

The Minimum Covariance Determinant estimator (MCD) is a robust, high-breakdown point (i.e. it can be used to estimate the covariance matrix of highly contaminated datasets, up to \( n_{\text{samples}} - n_{\text{features}} - 1 \) outliers) estimator of covariance. The idea behind the MCD is to find \( n_{\text{samples}} + n_{\text{features}} + 1 \) observations whose empirical covariance has the smallest determinant, yielding a “pure” subset of observations from which to compute standards estimates of location and covariance. The MCD was introduced by P.J.Rousseeuw in\(^1\).

This example illustrates how the Mahalanobis distances are affected by outlying data. Observations drawn from a contaminating distribution are not distinguishable from the observations coming from the real, Gaussian distribution when using standard covariance MLE based Mahalanobis distances. Using MCD-based Mahalanobis distances, the two populations become distinguishable. Associated applications include outlier detection, observation ranking and clustering.

**Note:** See also *Robust vs Empirical covariance estimate*

**References:**

Generate data

First, we generate a dataset of 125 samples and 2 features. Both features are Gaussian distributed with mean of 0 but feature 1 has a standard deviation equal to 2 and feature 2 has a standard deviation equal to 1. Next, 25 samples are replaced with Gaussian outlier samples where feature 1 has a standard deviation equal to 1 and feature 2 has a standard deviation equal to 7.

```python
import numpy as np
# for consistent results
np.random.seed(7)

n_samples = 125
n_outliers = 25
n_features = 2

# generate Gaussian data of shape (125, 2)
gen_cov = np.eye(n_features)
gen_cov[0, 0] = 2.
X = np.dot(np.random.randn(n_samples, n_features), gen_cov)
# add some outliers
outliers_cov = np.eye(n_features)
outliers_cov[np.arange(1, n_features), np.arange(1, n_features)] = 7.
X[-n_outliers:] = np.dot(np.random.randn(n_outliers, n_features), outliers_cov)
```

Comparison of results

Below, we fit MCD and MLE based covariance estimators to our data and print the estimated covariance matrices. Note that the estimated variance of feature 2 is much higher with the MLE based estimator (7.5) than that of the MCD robust estimator (1.2). This shows that the MCD based robust estimator is much more resistant to the outlier samples, which were designed to have a much larger variance in feature 2.

```python
import matplotlib.pyplot as plt
from sklearn.covariance import EmpiricalCovariance, MinCovDet

# fit a MCD robust estimator to data
robust_cov = MinCovDet().fit(X)
# fit a MLE estimator to data
emp_cov = EmpiricalCovariance().fit(X)
print('Estimated covariance matrix:

MCD (Robust):
[ [ 3.26253567e+00 -3.06695631e-03]
  [-3.06695631e-03 1.22747343e+00]]

MLE:
[ [ 3.23773583 -0.24640578]
  [-0.24640578 7.51963999]]
```

Out:

Estimated covariance matrix:
MCD (Robust):
[[ 3.26253567e+00 -3.06695631e-03]
 [-3.06695631e-03 1.22747343e+00]]

MLE:
[[ 3.23773583 -0.24640578]
 [-0.24640578 7.51963999]]

To better visualize the difference, we plot contours of the Mahalanobis distances calculated by both methods. Notice that the robust MCD based Mahalanobis distances fit the inlier black points much better, whereas the MLE based distances are more influenced by the outlier red points.
Finally, we highlight the ability of MCD based Mahalanobis distances to distinguish outliers. We take the cubic root of
the Mahalanobis distances, yielding approximately normal distributions (as suggested by Wilson and Hilferty\footnote{Wilson, E. B., & Hilferty, M. M. (1931). The distribution of chi-square. Proceedings of the National Academy of Sciences of the United States}), then...
scikit-learn user guide, Release 0.24.0

plot the values of inlier and outlier samples with boxplots. The distribution of outlier samples is more separated from
the distribution of inlier samples for robust MCD based Mahalanobis distances.
fig, (ax1, ax2) = plt.subplots(1, 2)
plt.subplots_adjust(wspace=.6)
# Calculate cubic root of MLE Mahalanobis distances for samples
emp_mahal = emp_cov.mahalanobis(X - np.mean(X, 0)) ** (0.33)
# Plot boxplots
ax1.boxplot([emp_mahal[:-n_outliers], emp_mahal[-n_outliers:]], widths=.25)
# Plot individual samples
ax1.plot(np.full(n_samples - n_outliers, 1.26), emp_mahal[:-n_outliers],
'+k', markeredgewidth=1)
ax1.plot(np.full(n_outliers, 2.26), emp_mahal[-n_outliers:],
'+k', markeredgewidth=1)
ax1.axes.set_xticklabels(('inliers', 'outliers'), size=15)
ax1.set_ylabel(r"$\sqrt[3]{\rm{(Mahal. dist.)}}$", size=16)
ax1.set_title("Using non-robust estimates\n(Maximum Likelihood)")
# Calculate cubic root of MCD Mahalanobis distances for samples
robust_mahal = robust_cov.mahalanobis(X - robust_cov.location_) ** (0.33)
# Plot boxplots
ax2.boxplot([robust_mahal[:-n_outliers], robust_mahal[-n_outliers:]],
widths=.25)
# Plot individual samples
ax2.plot(np.full(n_samples - n_outliers, 1.26), robust_mahal[:-n_outliers],
'+k', markeredgewidth=1)
ax2.plot(np.full(n_outliers, 2.26), robust_mahal[-n_outliers:],
'+k', markeredgewidth=1)
ax2.axes.set_xticklabels(('inliers', 'outliers'), size=15)
ax2.set_ylabel(r"$\sqrt[3]{\rm{(Mahal. dist.)}}$", size=16)
ax2.set_title("Using robust estimates\n(Minimum Covariance Determinant)")
plt.show()
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6.6. Covariance estimation

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6.6.5 Robust vs Empirical covariance estimate

The usual covariance maximum likelihood estimate is very sensitive to the presence of outliers in the data set. In such a case, it would be better to use a robust estimator of covariance to guarantee that the estimation is resistant to “erroneous” observations in the data set.\(^1\)\(^2\)

Minimum Covariance Determinant Estimator

The Minimum Covariance Determinant estimator is a robust, high-breakdown point (i.e. it can be used to estimate the covariance matrix of highly contaminated datasets, up to \(\frac{n_{\text{samples}}}{2} - \frac{n_{\text{features}}}{2} - 1\) outliers) estimator of covariance. The idea is to find \(\frac{n_{\text{samples}}}{2} + \frac{n_{\text{features}}}{2} + 1\) observations whose empirical covariance has the smallest determinant, yielding a “pure” subset of observations from which to compute standards estimates of location and covariance. After a correction step aiming at compensating the fact that the estimates were learned from only a portion of the initial data, we end up with robust estimates of the data set location and covariance.

The Minimum Covariance Determinant estimator (MCD) has been introduced by P.J.Rousseeuw in\(^3\).

---


Evaluation

In this example, we compare the estimation errors that are made when using various types of location and covariance estimates on contaminated Gaussian distributed data sets:

- The mean and the empirical covariance of the full dataset, which break down as soon as there are outliers in the data set
- The robust MCD, that has a low error provided $n_{\text{samples}} > 5n_{\text{features}}$
- The mean and the empirical covariance of the observations that are known to be good ones. This can be considered as a “perfect” MCD estimation, so one can trust our implementation by comparing to this case.

References

```python
print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.font_manager
from sklearn.covariance import EmpiricalCovariance, MinCovDet

# example settings
n_samples = 80
```
n_features = 5
repeat = 10
range_n_outliers = np.concatenate(
    (np.linspace(0, n_samples / 8, 5),
     np.linspace(n_samples / 8, n_samples / 2, 5)[1:-1])).astype(int)

# definition of arrays to store results
err_loc_mcd = np.zeros((range_n_outliers.size, repeat))
err_cov_mcd = np.zeros((range_n_outliers.size, repeat))
err_loc_emp_full = np.zeros((range_n_outliers.size, repeat))
err_cov_emp_full = np.zeros((range_n_outliers.size, repeat))
err_loc_emp_pure = np.zeros((range_n_outliers.size, repeat))
err_cov_emp_pure = np.zeros((range_n_outliers.size, repeat))

# computation
for i, n_outliers in enumerate(range_n_outliers):
    for j in range(repeat):
        rng = np.random.RandomState(i * j)

        # generate data
        X = rng.randn(n_samples, n_features)
        # add some outliers
        outliers_index = rng.permutation(n_samples)[n_outliers]
        outliers_offset = 10. * \
            (np.random.randint(2, size=(n_outliers, n_features)) - 0.5)
        X[outliers_index] += outliers_offset
        inliers_mask = np.ones(n_samples).astype(bool)
        inliers_mask[outliers_index] = False

        # fit a Minimum Covariance Determinant (MCD) robust estimator to data
        mcd = MinCovDet().fit(X)
        # compare raw robust estimates with the true location and covariance
        err_loc_mcd[i, j] = np.sum(mcd.location_ ** 2)
        err_cov_mcd[i, j] = mcd.error_norm(np.eye(n_features))

        # compare estimators learned from the full data set with true
        # parameters
        err_loc_emp_full[i, j] = np.sum(X.mean(0) ** 2)
        err_cov_emp_full[i, j] = EmpiricalCovariance().fit(X).error_norm(
            np.eye(n_features))

        # compare with an empirical covariance learned from a pure data set
        # (i.e. "perfect" mcd)
        pure_X = X[inliers_mask]
        pure_location = pure_X.mean(0)
        pure_emp_cov = EmpiricalCovariance().fit(pure_X)
        err_loc_emp_pure[i, j] = np.sum(pure_location ** 2)
        err_cov_emp_pure[i, j] = pure_emp_cov.error_norm(np.eye(n_features))

# Display results
font_prop = matplotlib.font_manager.FontProperties(size=11)
plt.subplot(2, 1, 1)
lw = 2
plt.errorbar(range_n_outliers, err_loc_mcd.mean(1),
    yerr=err_loc_mcd.std(1) / np.sqrt(repeat),
6.7 Cross decomposition

Examples concerning the `sklearn.cross_decomposition` module.

6.7.1 Principal Component Regression vs Partial Least Squares Regression

This example compares Principal Component Regression (PCR) and Partial Least Squares Regression (PLS) on a toy dataset. Our goal is to illustrate how PLS can outperform PCR when the target is strongly correlated with some directions in the data that have a low variance.

PCR is a regressor composed of two steps: first, PCA is applied to the training data, possibly performing dimensionality reduction; then, a regressor (e.g. a linear regressor) is trained on the transformed samples. In PCA, the transformation is purely unsupervised, meaning that no information about the targets is used. As a result, PCR may perform poorly in some datasets where the target is strongly correlated with directions that have low variance. Indeed, the dimensionality reduction of PCA projects the data into a lower dimensional space where the variance of the projected data is greedily maximized along each axis. Despite them having the most predictive power on the target, the directions with a lower variance will be dropped, and the final regressor will not be able to leverage them.
PLS is both a transformer and a regressor, and it is quite similar to PCR: it also applies a dimensionality reduction to the samples before applying a linear regressor to the transformed data. The main difference with PCR is that the PLS transformation is supervised. Therefore, as we will see in this example, it does not suffer from the issue we just mentioned.

```python
print(__doc__)
```

### The data

We start by creating a simple dataset with two features. Before we even dive into PCR and PLS, we fit a PCA estimator to display the two principal components of this dataset, i.e. the two directions that explain the most variance in the data.

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.decomposition import PCA

rng = np.random.RandomState(0)
n_samples = 500
cov = [[3, 3],
       [3, 4]]
X = rng.multivariate_normal(mean=[0, 0], cov=cov, size=n_samples)
pca = PCA(n_components=2).fit(X)

plt.scatter(X[:, 0], X[:, 1], alpha=.3, label='samples')
for i, (comp, var) in enumerate(zip(pca.components_, pca.explained_variance_)):
    comp = comp * var  # scale component by its variance explanation power
    plt.plot([0, comp[0]], [0, comp[1]], label=f'Component {i}', linewidth=5,
             color=f'C{i + 2}')
plt.gca().set(aspect='equal',
              title='2-dimensional dataset with principal components',
              xlabel='first feature', ylabel='second feature')
plt.legend()
plt.show()
```
For the purpose of this example, we now define the target $y$ such that it is strongly correlated with a direction that has a small variance. To this end, we will project $X$ onto the second component, and add some noise to it.

```python
y = X.dot(pca.components_[1]) + rng.normal(size=n_samples) / 2
```

```python
fig, axes = plt.subplots(1, 2, figsize=(10, 3))

axes[0].scatter(X.dot(pca.components_[0]), y, alpha=.3)
axes[0].set(xlabel='Projected data onto first PCA component', ylabel='y')

axes[1].scatter(X.dot(pca.components_[1]), y, alpha=.3)
axes[1].set(xlabel='Projected data onto second PCA component', ylabel='y')

plt.tight_layout()
plt.show()
```
Projection on one component and predictive power

We now create two regressors: PCR and PLS, and for our illustration purposes we set the number of components to 1. Before feeding the data to the PCA step of PCR, we first standardize it, as recommended by good practice. The PLS estimator has built-in scaling capabilities.

For both models, we plot the projected data onto the first component against the target. In both cases, this projected data is what the regressors will use as training data.

```python
from sklearn.model_selection import train_test_split
from sklearn.pipeline import make_pipeline
from sklearn.linear_model import LinearRegression
from sklearn.preprocessing import StandardScaler
from sklearn.decomposition import PCA
from sklearn.cross_decomposition import PLSRegression

X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=rng)

pcr = make_pipeline(StandardScaler(), PCA(n_components=1), LinearRegression())
pca = pcr.named_steps['pca']  # retrieve the PCA step of the pipeline

pls = PLSRegression(n_components=1)

fig, axes = plt.subplots(1, 2, figsize=(10, 3))

axes[0].scatter(pca.transform(X_test), y_test, alpha=.3, label='ground truth')
axes[0].scatter(pca.transform(X_test), pcr.predict(X_test), alpha=.3, label='predictions')
axes[0].set(xlabel='Projected data onto first PCA component', ylabel='y', title='PCR / PCA')
axes[0].legend()

axes[1].scatter(pls.transform(X_test), y_test, alpha=.3, label='ground truth')
axes[1].scatter(pls.transform(X_test), pls.predict(X_test), alpha=.3, label='predictions')
axes[1].set(xlabel='Projected data onto first PLS component', ylabel='y', title='PLS')
axes[1].legend()
plt.tight_layout()
plt.show()
```

As expected, the unsupervised PCA transformation of PCR has dropped the second component, i.e. the direction with the lowest variance, despite it being the most predictive direction. This is because PCA is a completely unsupervised transformation, and results in the projected data having a low predictive power on the target.
On the other hand, the PLS regressor manages to capture the effect of the direction with the lowest variance, thanks to its use of target information during the transformation: it can recognize that this direction is actually the most predictive. We note that the first PLS component is negatively correlated with the target, which comes from the fact that the signs of eigenvectors are arbitrary.

We also print the R-squared scores of both estimators, which further confirms that PLS is a better alternative than PCR in this case. A negative R-squared indicates that PCR performs worse than a regressor that would simply predict the mean of the target.

```python
print(f"PCR r-squared \{pcr.score(X_test, y_test):.3f}"
print(f"PLS r-squared \{pls.score(X_test, y_test):.3f}"
```

Out:

<table>
<thead>
<tr>
<th>PCR r-squared</th>
<th>-0.026</th>
</tr>
</thead>
<tbody>
<tr>
<td>PLS r-squared</td>
<td>0.658</td>
</tr>
</tbody>
</table>

As a final remark, we note that PCR with 2 components performs as well as PLS: this is because in this case, PCR was able to leverage the second component which has the most predictive power on the target.

```python
pca_2 = make_pipeline(PCA(n_components=2), LinearRegression())
pca_2.fit(X_train, y_train)
print(f"PCR r-squared with 2 components \{pca_2.score(X_test, y_test):.3f}""
```

Out:

| PCR r-squared with 2 components | 0.673 |

**Total running time of the script:** ( 0 minutes 0.484 seconds)

### 6.7.2 Compare cross decomposition methods

Simple usage of various cross decomposition algorithms:
- PLSCanonical - PLSRegression, with multivariate response, a.k.a. PLS2 - PLSRegression, with univariate response, a.k.a. PLS1 - CCA

Given 2 multivariate covarying two-dimensional datasets, X, and Y, PLS extracts the ‘directions of covariance’, i.e. the components of each datasets that explain the most shared variance between both datasets. This is apparent on the scatterplot matrix display: components 1 in dataset X and dataset Y are maximally correlated (points lie around the first diagonal). This is also true for components 2 in both dataset, however, the correlation across datasets for different components is weak: the point cloud is very spherical.
Out:

\[
\text{Corr}(X) = \begin{bmatrix}
1. & 0.52 & -0.06 & -0.03 \\
0.52 & 1. & -0.02 & -0.06 \\
-0.06 & -0.02 & 1. & 0.58 \\
-0.03 & -0.06 & 0.58 & 1. \\
\end{bmatrix}
\]

\[
\text{Corr}(Y) = \begin{bmatrix}
1. & 0.56 & -0.02 & -0. \\
0.56 & 1. & -0.05 & 0.04 \\
-0.02 & -0.05 & 1. & 0.53 \\
-0. & 0.04 & 0.53 & 1. \\
\end{bmatrix}
\]

True B (such that: \( Y = XB + \text{Err} \))

\[
\begin{bmatrix}
1 & 1 & 1 \\
2 & 2 & 2 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
\end{bmatrix}
\]

Estimated B

\[
\begin{bmatrix}
1. & 1. & 0.9 \\
2. & 2. & 2. \\
0. & -0. & 0. \\
0. & 0. & 0. \\
-0. & -0. & -0. \\
\end{bmatrix}
\]
```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.cross_decomposition import PLSCanonical, PLSRegression, CCA

# Dataset based latent variables model
n = 500
# 2 latents vars:
l1 = np.random.normal(size=n)
l2 = np.random.normal(size=n)

latents = np.array([l1, l1, l2, l2]).T
X = latents + np.random.normal(size=4 * n).reshape((n, 4))
Y = latents + np.random.normal(size=4 * n).reshape((n, 4))

X_train = X[:n // 2]
Y_train = Y[:n // 2]
X_test = X[n // 2:]
Y_test = Y[n // 2:]

print("Corr(X)")
print(np.round(np.corrcoef(X.T), 2))
print("Corr(Y)")
print(np.round(np.corrcoef(Y.T), 2))

# Canonical (symmetric) PLS
# ~~~~~~~~~~~~~
plsca = PLSCanonical(n_components=2)
```
plsca.fit(X_train, Y_train)
X_train_r, Y_train_r = plsca.transform(X_train, Y_train)
X_test_r, Y_test_r = plsca.transform(X_test, Y_test)

# Scatter plot of scores
# ~~~~~~~~~~~~~~~~~~~~~
# 1) On diagonal plot X vs Y scores on each components
plt.figure(figsize=(12, 8))
plt.subplot(221)
plt.scatter(X_train_r[:, 0], Y_train_r[:, 0], label="train",
    marker="o", s=25)
plt.scatter(X_test_r[:, 0], Y_test_r[:, 0], label="test",
    marker="o", s=25)
plt.xlabel("x scores")
plt.ylabel("y scores")
plt.title('Comp. 1: X vs Y (test corr = %.2f)'
    % np.corrcoef(X_test_r[:, 0], Y_test_r[:, 0])[0, 1])
plt.xticks(()
plt.yticks(()
plt.legend(loc="best")
plt.subplot(224)
plt.scatter(X_train_r[:, 1], Y_train_r[:, 1], label="train",
    marker="o", s=25)
plt.scatter(X_test_r[:, 1], Y_test_r[:, 1], label="test",
    marker="o", s=25)
plt.xlabel("x scores")
plt.ylabel("y scores")
plt.title('Comp. 2: X vs Y (test corr = %.2f)'
    % np.corrcoef(X_test_r[:, 1], Y_test_r[:, 1])[0, 1])
plt.xticks()
plt.yticks()
plt.legend(loc="best")
plt.subplot(222)
plt.scatter(X_train_r[:, 0], X_train_r[:, 1], label="train",
    marker="*", s=50)
plt.scatter(X_test_r[:, 0], X_test_r[:, 1], label="test",
    marker="*", s=50)
plt.xlabel("X comp. 1")
plt.ylabel("X comp. 2")
plt.title('X comp. 1 vs X comp. 2 (test corr = %.2f)'
    % np.corrcoef(X_test_r[:, 0], X_test_r[:, 1])[0, 1])
plt.legend(loc="best")
plt.xticks()
plt.yticks()
plt.subplot(223)
plt.scatter(Y_train_r[:, 0], Y_train_r[:, 1], label="train",
    marker="*", s=50)
plt.scatter(Y_test_r[:, 0], Y_test_r[:, 1], label="test",
    marker="*", s=50)
plt.xlabel("Y comp. 1")
plt.ylabel("Y comp. 2")
plt.title('Y comp. 1 vs Y comp. 2, (test corr = %.2f)'
    % np.corrcoef(Y_test_r[:, 0], Y_test_r[:, 1])[0, 1])
plt.legend(loc="best")
plt.xticks(()
plt.yticks(()
plt.show()

# PLS regression, with multivariate response, a.k.a. PLS2

n = 1000
q = 3
p = 10
X = np.random.normal(size=n * p).reshape((n, p))
B = np.array([[1, 2] + [0] * (p - 2)] * q).T
# each Yj = 1*X1 + 2*X2 + noise
Y = np.dot(X, B) + np.random.normal(size=n * q).reshape((n, q)) + 5
pls2 = PLSRegression(n_components=3)
pls2.fit(X, Y)
print("True B (such that: Y = XB + Err)")
print(B)
# compare pls2.coef_ with B
print("Estimated B")
print(np.round(pls2.coef_, 1))
pls2.predict(X)

# PLS regression, with univariate response, a.k.a. PLS1

n = 1000
p = 10
X = np.random.normal(size=n * p).reshape((n, p))
y = X[:, 0] + 2 * X[:, 1] + np.random.normal(size=n * 1) + 5
pls1 = PLSRegression(n_components=3)
pls1.fit(X, y)
# note that the number of components exceeds 1 (the dimension of y)
print("Estimated betas")
print(np.round(pls1.coef_, 1))

# CCA (PLS mode B with symmetric deflation)

cca = CCA(n_components=2)
cca.fit(X_train, Y_train)
X_train_r, Y_train_r = cca.transform(X_train, Y_train)
X_test_r, Y_test_r = cca.transform(X_test, Y_test)

Total running time of the script: (0 minutes 0.253 seconds)
6.8 Dataset examples

Examples concerning the `sklearn.datasets` module.

### 6.8.1 The Digit Dataset

This dataset is made up of 1797 8x8 images. Each image, like the one shown below, is of a hand-written digit. In order to utilize an 8x8 figure like this, we’d have to first transform it into a feature vector with length 64.

See [here](#) for more information about this dataset.

```python
print(__doc__)

# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

from sklearn import datasets
import matplotlib.pyplot as plt

# Load the digits dataset
digits = datasets.load_digits()

# Display the first digit
plt.figure(1, figsize=(3, 3))
plt.imshow(digits.images[-1], cmap=plt.cm.gray_r, interpolation='nearest')
plt.show()
```

Total running time of the script: ( 0 minutes 0.123 seconds)
6.8.2 The Iris Dataset

This data sets consists of 3 different types of irises’ (Setosa, Versicolour, and Virginica) petal and sepal length, stored in a 150x4 numpy.ndarray

The rows being the samples and the columns being: Sepal Length, Sepal Width, Petal Length and Petal Width.

The below plot uses the first two features. See here for more information on this dataset.
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from sklearn import datasets
from sklearn.decomposition import PCA

# import some data to play with
iris = datasets.load_iris()
X = iris.data[:, :2]  # we only take the first two features.
y = iris.target

x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5

plt.figure(2, figsize=(8, 6))
plt.clf()

# Plot the training points
plt.scatter(X[:, 0], X[:, 1], c=y, cmap=plt.cm.Set1, edgecolor='k')
plt.xlabel('Sepal length')
plt.ylabel('Sepal width')

plt.show()
6.8.3 Plot randomly generated classification dataset

This example plots several randomly generated classification datasets. For easy visualization, all datasets have 2
features, plotted on the x and y axis. The color of each point represents its class label.

The first 4 plots use the `make_classification` with different numbers of informative features, clusters per class and classes. The final 2 plots use `make_blobs` and `make_gaussian_quantiles`. 
import matplotlib.pyplot as plt
from sklearn.datasets import make_classification
from sklearn.datasets import make_blobs
from sklearn.datasets import make_gaussian_quantiles
plt.figure(figsize=(8, 8))
plt.subplots_adjust(bottom=.05, top=.9, left=.05, right=.95)
plt.subplot(321)
plt.title("One informative feature, one cluster per class", fontsize='small')
X1, Y1 = make_classification(n_features=2, n_redundant=0, n_informative=1,
   n_clusters_per_class=2, n_classes=2, n_samples=200, random_state=3)
plt.scatter(X1[:, 0], X1[:, 1], c=Y1, s=30, cmap=plt.cm.Paired)
plt.subplot(322)
plt.title("Two informative features, one cluster per class")
X2, Y2 = make_classification(n_features=2, n_informantive=2, n_clusters_per_class=2, n_classes=2, n_samples=200, random_state=3)
plt.scatter(X2[:, 0], X2[:, 1], c=Y2, s=30, cmap=plt.cm.Paired)
plt.subplot(323)
plt.title("Three blobs")
X3, Y3 = make_blobs(n_samples=200, centers=3, cluster_std=2.0,
   random_state=4)
plt.scatter(X3[:, 0], X3[:, 1], c=Y3, s=30, cmap=plt.cm.Paired)
plt.subplot(324)
plt.title("Gaussian divided into three quantiles")
X4, Y4 = make_gaussian_quantiles(n_features=2, n_samples=200,
   n_classes=3, n_clusters=3, flip_y=False, random_state=5)
plt.scatter(X4[:, 0], X4[:, 1], c=Y4, s=30, cmap=plt.cm.Paired)

print(__doc__)
6.8.4 Plot randomly generated multilabel dataset

This illustrates the `make_multilabel_classification` dataset generator. Each sample consists of counts of two features (up to 50 in total), which are differently distributed in each of two classes.

Points are labeled as follows, where Y means the class is present:

Total running time of the script: ( 0 minutes 0.311 seconds)
A star marks the expected sample for each class; its size reflects the probability of selecting that class label.

The left and right examples highlight the n_labels parameter: more of the samples in the right plot have 2 or 3 labels.

Note that this two-dimensional example is very degenerate: generally the number of features would be much greater than the “document length”, while here we have much larger documents than vocabulary. Similarly, with n_classes > n_features, it is much less likely that a feature distinguishes a particular class.

```python
import numpy as np
import matplotlib.pyplot as plt
```

The data was generated from (random_state=511):

| Class | P(C)   | P(w0|C) | P(w1|C) |
|-------|--------|--------|--------|
| red   | 0.20   | 0.88   | 0.12   |
| blue  | 0.61   | 0.63   | 0.37   |
| yellow| 0.18   | 0.42   | 0.58   |

(continues on next page)
from sklearn.datasets import make_multilabel_classification as make_ml_clf

print(__doc__)

COLORS = np.array(['!', '#FF3333', '#0198E1', '#BF5FFF', '#FC0116', '#FCD116', '#FF7216', '#4DBD33', '#87421F'])

# Use same random seed for multiple calls to make_multilabel_classification to
# ensure same distributions
RANDOM_SEED = np.random.randint(2 ** 10)

def plot_2d(ax, n_labels=1, n_classes=3, length=50):
    X, Y, p_c, p_w_c = make_ml_clf(n_samples=150, n_features=2,
                                n_classes=n_classes, n_labels=n_labels,
                                length=length, allow_unlabeled=False,
                                return_distributions=True,
                                random_state=RANDOM_SEED)
    ax.scatter(X[:, 0], X[:, 1], color=COLORS.take((Y * [1, 2, 4]).sum(axis=1)),
               marker='.'
    ax.scatter(p_w_c[0] * length, p_w_c[1] * length,
               marker='*', linewidth=.5, edgecolor='black',
               s=20 + 1500 * p_c ** 2,
               color=COLORS.take([1, 2, 4]))
    ax.set_xlabel('Feature 0 count')
    return p_c, p_w_c

_, (ax1, ax2) = plt.subplots(1, 2, sharex='row', sharey='row', figsize=(8, 4))
plt.subplots_adjust(bottom=.15)
p_c, p_w_c = plot_2d(ax1, n_labels=1)
ax1.set_title('n_labels=1, length=50')
ax1.set_ylabel('Feature 1 count')
plot_2d(ax2, n_labels=3)
ax2.set_title('n_labels=3, length=50')
ax2.set_xlim(left=0, auto=True)
ax2.set_ylim(bottom=0, auto=True)
plt.show()

print('The data was generated from (random_state=%d):' % RANDOM_SEED)
print('Class', 'P(C)', 'P(w0|C)', 'P(w1|C)', sep='	')
for k, p, p_w in zip(['red', 'blue', 'yellow'], p_c, p_w_c.T):
    print('%s\t%0.2f\t%0.2f\t%0.2f' % (k, p, p_w[0], p_w[1]))

Total running time of the script: ( 0 minutes 0.146 seconds)
6.9 Decision Trees

Examples concerning the `sklearn.tree` module.

6.9.1 Decision Tree Regression

A 1D regression with decision tree.

The decision tree is used to fit a sine curve with addition noisy observation. As a result, it learns local linear regressions approximating the sine curve.

We can see that if the maximum depth of the tree (controlled by the `max_depth` parameter) is set too high, the decision trees learn too fine details of the training data and learn from the noise, i.e. they overfit.

```
print(__doc__)

# Import the necessary modules and libraries
import numpy as np
from sklearn.tree import DecisionTreeRegressor
import matplotlib.pyplot as plt

# Create a random dataset
rng = np.random.RandomState(1)
X = np.sort(5 * rng.rand(80, 1), axis=0)
```
y = np.sin(X).ravel()
y[::5] += 3 * (0.5 - rng.rand(16))

# Fit regression model
regr_1 = DecisionTreeRegressor(max_depth=2)
regr_2 = DecisionTreeRegressor(max_depth=5)
regr_1.fit(X, y)
regr_2.fit(X, y)

# Predict
X_test = np.arange(0.0, 5.0, 0.01)[:, np.newaxis]
y_1 = regr_1.predict(X_test)
y_2 = regr_2.predict(X_test)

# Plot the results
plt.figure()
plt.scatter(X, y, s=20, edgecolor="black",
c="darkorange", label="data")
plt.plot(X_test, y_1, color="cornflowerblue",
label="max_depth=2", linewidth=2)
plt.plot(X_test, y_2, color="yellowgreen", label="max_depth=5", linewidth=2)
plt.xlabel("data")
plt.ylabel("target")
plt.title("Decision Tree Regression")
plt.legend()
plt.show()

Total running time of the script: ( 0 minutes 0.118 seconds)

6.9.2 Multi-output Decision Tree Regression

An example to illustrate multi-output regression with decision tree.

The decision trees is used to predict simultaneously the noisy x and y observations of a circle given a single underlying feature. As a result, it learns local linear regressions approximating the circle.

We can see that if the maximum depth of the tree (controlled by the max_depth parameter) is set too high, the decision trees learn too fine details of the training data and learn from the noise, i.e. they overfit.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.tree import DecisionTreeRegressor

# Create a random dataset
rng = np.random.RandomState(1)
X = np.sort(200 * rng.rand(100, 1) - 100, axis=0)
y = np.array([np.pi * np.sin(X).ravel(), np.pi * np.cos(X).ravel()]).T
y[::5, :] += (0.5 - rng.rand(20, 2))

# Fit regression model
regr_1 = DecisionTreeRegressor(max_depth=2)
regr_2 = DecisionTreeRegressor(max_depth=5)
regr_3 = DecisionTreeRegressor(max_depth=8)
regr_1.fit(X, y)
regr_2.fit(X, y)
regr_3.fit(X, y)

# Predict
X_test = np.arange(-100.0, 100.0, 0.01)[:, np.newaxis]
y_1 = regr_1.predict(X_test)
y_2 = regr_2.predict(X_test)
y_3 = regr_3.predict(X_test)
# Plot the results

```python
plt.figure()
s = 25
plt.scatter(y[:, 0], y[:, 1], c="navy", s=s,
            edgecolor="black", label="data")
plt.scatter(y_1[:, 0], y_1[:, 1], c="cornflowerblue", s=s,
            edgecolor="black", label="max_depth=2")
plt.scatter(y_2[:, 0], y_2[:, 1], c="red", s=s,
            edgecolor="black", label="max_depth=5")
plt.scatter(y_3[:, 0], y_3[:, 1], c="orange", s=s,
            edgecolor="black", label="max_depth=8")
plt.xlim([-6, 6])
plt.ylim([-6, 6])
plt.xlabel("target 1")
plt.ylabel("target 2")
plt.title("Multi-output Decision Tree Regression")
plt.legend(loc="best")
plt.show()
```

**Total running time of the script:** ( 0 minutes 0.313 seconds)

6.9.3 Plot the decision surface of a decision tree on the iris dataset

Plot the decision surface of a decision tree trained on pairs of features of the iris dataset.

See decision tree for more information on the estimator.

For each pair of iris features, the decision tree learns decision boundaries made of combinations of simple thresholding rules inferred from the training samples.

We also show the tree structure of a model built on all of the features.
```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load_iris
from sklearn.tree import DecisionTreeClassifier, plot_tree

# Parameters
n_classes = 3
plot_colors = "ryb"
plot_step = 0.02

# Load data
iris = load_iris()

for pairidx, pair in enumerate([[0, 1], [0, 2], [0, 3], [1, 2], [1, 3], [2, 3]]):
    # We only take the two corresponding features
    X = iris.data[:, pair]
y = iris.target

    # Train
    clf = DecisionTreeClassifier().fit(X, y)

    # Plot the decision boundary
    plt.subplot(2, 3, pairidx + 1)
    plot_tree(clf, feature_names=iris.feature_names[pair],
              class_names=iris.target_names, filled=True,
              impurity=False, ax=plt.gca(),
              class_color=plot_colors)

plt.show()
```

6.9. Decision Trees
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, plot_step),
                    np.arange(y_min, y_max, plot_step))
plt.tight_layout(h_pad=0.5, w_pad=0.5, pad=2.5)

Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
cs = plt.contourf(xx, yy, Z, cmap=plt.cm.RdYlBu)
plt.xlabel(iris.feature_names[pair[0]])
plt.ylabel(iris.feature_names[pair[1]])

# Plot the training points
for i, color in zip(range(n_classes), plot_colors):
    idx = np.where(y == i)
    plt.scatter(X[idx, 0], X[idx, 1], c=color, label=iris.target_names[i],
                cmap=plt.cm.RdYlBu, edgecolor='black', s=15)

plt.suptitle("Decision surface of a decision tree using paired features")
plt.legend(loc='lower right', borderpad=0, handletextpad=0)
plt.axis("tight")

plt.figure()
clf = DecisionTreeClassifier().fit(iris.data, iris.target)
plot_tree(clf, filled=True)
plt.show()
Total impurity of leaves vs effective alphas of pruned tree

Minimal cost complexity pruning recursively finds the node with the “weakest link”. The weakest link is characterized by an effective alpha, where the nodes with the smallest effective alpha are pruned first. To get an idea of what values of \texttt{ccp\_alpha} could be appropriate, scikit-learn provides \texttt{DecisionTreeClassifier.cost\_complexity\_pruning\_path} that returns the effective alphas and the corresponding total leaf impurities at each step of the pruning process. As alpha increases, more of the tree is pruned, which increases the total impurity of its leaves.

```python
X, y = load_breast_cancer(return_X_y=True)
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
clf = DecisionTreeClassifier(random_state=0)
path = clf.cost_complexity_pruning_path(X_train, y_train)
ccp_alphas, impurities = path.ccp_alphas, path.impurities
```

In the following plot, the maximum effective alpha value is removed, because it is the trivial tree with only one node.

```python
fig, ax = plt.subplots()
ax.plot(ccp_alphas[:-1], impurities[:-1], marker='o', drawstyle="steps-post")
ax.set_xlabel("effective alpha")
ax.set_ylabel("total impurity of leaves")
ax.set_title("Total Impurity vs effective alpha for training set")
```

Out:
Next, we train a decision tree using the effective alphas. The last value in `ccp_alphas` is the alpha value that prunes the whole tree, leaving the tree, `clfs[-1]`, with one node.

```python
clfs = []
for ccp_alpha in ccp_alphas:
    clf = DecisionTreeClassifier(random_state=0, ccp_alpha=ccp_alpha)
    clf.fit(X_train, y_train)
    clfs.append(clf)

print("Number of nodes in the last tree is: {} with ccp_alpha: {}".format(clfs[-1].tree_.node_count, ccp_alphas[-1]))
```

Out:

```
Number of nodes in the last tree is: 1 with ccp_alpha: 0.3272984419327777
```

For the remainder of this example, we remove the last element in `clfs` and `ccp_alphas`, because it is the trivial tree with only one node. Here we show that the number of nodes and tree depth decreases as alpha increases.

```python
clfs = clfs[:-1]
ccp_alphas = ccp_alphas[:-1]

node_counts = [clf.tree_.node_count for clf in clfs]
depth = [clf.tree_.max_depth for clf in clfs]
fig, ax = plt.subplots(2, 1)
ax[0].plot(ccp_alphas, node_counts, marker='o', drawstyle="steps-post")
ax[0].set_xlabel("alpha")
ax[0].set_ylabel("number of nodes")
ax[0].set_title("Number of nodes vs alpha")
ax[1].plot(ccp_alphas, depth, marker='o', drawstyle="steps-post")
ax[1].set_xlabel("alpha")
ax[1].set_ylabel("depth of tree")
ax[1].set_title("Depth vs alpha")
fig.tight_layout()
```
Accuracy vs alpha for training and testing sets

When `ccp_alpha` is set to zero and keeping the other default parameters of `DecisionTreeClassifier`, the tree overfits, leading to a 100% training accuracy and 88% testing accuracy. As alpha increases, more of the tree is pruned, thus creating a decision tree that generalizes better. In this example, setting `ccp_alpha=0.015` maximizes the testing accuracy.

```python
train_scores = [clf.score(X_train, y_train) for clf in clfs]
test_scores = [clf.score(X_test, y_test) for clf in clfs]

fig, ax = plt.subplots()
ax.set_xlabel("alpha")
ax.set_ylabel("accuracy")
ax.set_title("Accuracy vs alpha for training and testing sets")
ax.plot(ccp_alphas, train_scores, marker='o', label="train", drawstyle="steps-post")
ax.plot(ccp_alphas, test_scores, marker='o', label="test", drawstyle="steps-post")
ax.legend()
plt.show()
```
6.9.5 Understanding the decision tree structure

The decision tree structure can be analysed to gain further insight on the relation between the features and the target to predict. In this example, we show how to retrieve:

- the binary tree structure;
- the depth of each node and whether or not it’s a leaf;
- the nodes that were reached by a sample using the decision_path method;
- the leaf that was reached by a sample using the apply method;
- the rules that were used to predict a sample;
- the decision path shared by a group of samples.

```python
import numpy as np
from matplotlib import pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.datasets import load_iris
from sklearn.tree import DecisionTreeClassifier
from sklearn import tree
```

**Total running time of the script:** ( 0 minutes 0.397 seconds)
Train tree classifier

First, we fit a `DecisionTreeClassifier` using the `load_iris` dataset.

```python
iris = load_iris()
X = iris.data
y = iris.target
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
clf = DecisionTreeClassifier(max_leaf_nodes=3, random_state=0)
clf.fit(X_train, y_train)
```

Tree structure

The decision classifier has an attribute called `tree_` which allows access to low level attributes such as `node_count`, the total number of nodes, and `max_depth`, the maximal depth of the tree. It also stores the entire binary tree structure, represented as a number of parallel arrays. The i-th element of each array holds information about the node i. Node 0 is the tree’s root. Some of the arrays only apply to either leaves or split nodes. In this case the values of the nodes of the other type is arbitrary. For example, the arrays `feature` and `threshold` only apply to split nodes. The values for leaf nodes in these arrays are therefore arbitrary.

Among these arrays, we have:

- `children_left[i]`: id of the left child of node i or -1 if leaf node
- `children_right[i]`: id of the right child of node i or -1 if leaf node
- `feature[i]`: feature used for splitting node i
- `threshold[i]`: threshold value at node i
- `n_node_samples[i]`: the number of of training samples reaching node i
- `impurity[i]`: the impurity at node i

Using the arrays, we can traverse the tree structure to compute various properties. Below, we will compute the depth of each node and whether or not it is a leaf.

```python
n_nodes = clf.tree_.node_count
children_left = clf.tree_.children_left
children_right = clf.tree_.children_right
feature = clf.tree_.feature
threshold = clf.tree_.threshold

node_depth = np.zeros(shape=n_nodes, dtype=np.int64)
is_leaves = np.zeros(shape=n_nodes, dtype=bool)
stack = [(0, 0)]  # start with the root node id (0) and its depth (0)

while len(stack) > 0:
    # `pop` ensures each node is only visited once
    node_id, depth = stack.pop()
    node_depth[node_id] = depth

    # If the left and right child of a node is not the same we have a split
    # node
    is_split_node = children_left[node_id] != children_right[node_id]
    # If a split node, append left and right children and depth to `stack`
    # so we can loop through them
    if is_split_node:
        stack.append((children_left[node_id], depth + 1))
        stack.append((children_right[node_id], depth + 1))
```

(continues on next page)
stack.append((children_right[node_id], depth + 1))

else:
    is_leaves[node_id] = True

print("The binary tree structure has {n} nodes and has ",
    "the following tree structure: \n".format(n=n_nodes))

for i in range(n_nodes):
    if is_leaves[i]:
        print("\n{space}node={node} is a leaf node.\n".format(
            space=node_depth[i] * "\t",
            node=i))
    else:
        print("\n{space}node={node} is a split node: "
            "go to node {left} if X[:, {feature}] <= {threshold} "
            "else to node {right}.\n".format(
            space=node_depth[i] * "\t",
            node=i,
            left=children_left[i],
            feature=feature[i],
            threshold=threshold[i],
            right=children_right[i]))

Out:

The binary tree structure has 5 nodes and has the following tree structure:

node=0 is a split node: go to node 1 if X[:, 3] <= 0.800000011920929 else to node 2.
    node=1 is a leaf node.
    node=2 is a split node: go to node 3 if X[:, 2] <= 4.950000047683716 else to node 4.
        node=3 is a leaf node.
        node=4 is a leaf node.

We can compare the above output to the plot of the decision tree.

tree.plot_tree(clf)
plt.show()
We can also retrieve the decision path of samples of interest. The `decision_path` method outputs an indicator matrix that allows us to retrieve the nodes the samples of interest traverse through. A non zero element in the indicator matrix at position \((i, j)\) indicates that the sample \(i\) goes through the node \(j\). Or, for one sample \(i\), the positions of the non zero elements in row \(i\) of the indicator matrix designate the ids of the nodes that sample goes through.

The leaf ids reached by samples of interest can be obtained with the `apply` method. This returns an array of the node ids of the leaves reached by each sample of interest. Using the leaf ids and the `decision_path` we can obtain the splitting conditions that were used to predict a sample or a group of samples. First, let’s do it for one sample. Note that `node_index` is a sparse matrix.

```python
node_indicator = clf.decision_path(X_test)
leaf_id = clf.apply(X_test)

sample_id = 0
# obtain ids of the nodes `sample_id` goes through, i.e., row `sample_id`
node_index = node_indicator.indices[n_node_indicator.indptr[sample_id]:
                            node_indicator.indptr[sample_id + 1]]

print('Rules used to predict sample {id}:
'.format(id=sample_id))
for node_id in node_index:
    # continue to the next node if it is a leaf node
    if leaf_id[sample_id] == node_id:
```

(continues on next page)
# check if value of the split feature for sample 0 is below threshold
if (X_test[sample_id, feature[node_id]] <= threshold[node_id]):
    threshold_sign = "\leq"
else:
    threshold_sign = "\gt"

print("decision node \{node\} : (X_test\{sample\}, \{feature\} = \{value\}) \ "
      "{inequality} \{threshold}\).format(
    node=node_id,
    sample=sample_id,
    feature=feature[node_id],
    value=X_test[sample_id, feature[node_id]],
    inequality=threshold_sign,
    threshold=threshold[node_id])

Out:

Rules used to predict sample 0:

decision node 0 : (X_test[0, 3] = 2.4) \gt 0.8000000119209293

decision node 2 : (X_test[0, 2] = 5.1) \gt 4.950000047683716

For a group of samples, we can determine the common nodes the samples go through.

```
sample_ids = [0, 1]
# boolean array indicating the nodes both samples go through
common_nodes = (node_indicator.toarray()[sample_ids].sum(axis=0) ==
    len(sample_ids))
# obtain node ids using position in array
common_node_id = np.arange(n_nodes)[common_nodes]

print("\nThe following samples \{samples\} share the node(s) \{nodes\} in the "
      "tree.".format(samples=sample_ids, nodes=common_node_id))
print("This is \{prop\}% of all nodes.".format(
    prop=100 \,*\, len(common_node_id) / n_nodes))
```

Out:

The following samples [0, 1] share the node(s) [0 2] in the tree.
This is 40.0% of all nodes.

**Total running time of the script:** ( 0 minutes 0.109 seconds)

### 6.10 Decomposition

Examples concerning the `sklearn.decomposition` module.
6.10.1 Beta-divergence loss functions

A plot that compares the various Beta-divergence loss functions supported by the Multiplicative-Update (‘mu’) solver in NMF.

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.decomposition._nmf import _beta_divergence

print(__doc__)

x = np.linspace(0.001, 4, 1000)
y = np.zeros(x.shape)

for j, beta in enumerate((0., 0.5, 1., 1.5, 2.)):
    for i, xi in enumerate(x):
        y[i] = _beta_divergence(1, xi, 1, beta)
        name = "beta = %1.1f" % beta
        plt.plot(x, y, label=name, color=colors[j])

plt.xlabel("x")
plt.ylabel("beta-divergence(1, x)"
plt.legend(loc=0)
plt.axis([0, 4, 0, 3])
plt.show()
```
6.10.2 PCA example with Iris Data-set

Principal Component Analysis applied to the Iris dataset.
See here for more information on this dataset.

```
print(__doc__)

# Code source: Gaël Varoquaux
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

from sklearn import decomposition
from sklearn import datasets

np.random.seed(5)

centers = [[1, 1], [-1, -1], [1, -1]]
iris = datasets.load_iris()
X = iris.data
y = iris.target

fig = plt.figure(1, figsize=(4, 3))
plt.clf()
ax = Axes3D(fig, rect=[0, 0, .95, 1], elev=48, azim=134)

plt.cla()
pca = decomposition.PCA(n_components=3)
pca.fit(X)
X = pca.transform(X)
```

(continues on next page)
for name, label in [('Setosa', 0), ('Versicolour', 1), ('Virginica', 2)]:
    ax.text3D(X[y == label, 0].mean(),
             X[y == label, 1].mean() + 1.5,
             X[y == label, 2].mean(), name,
             horizontalalignment='center',
             bbox=dict(alpha=.5, edgecolor='w', facecolor='w'))

# Reorder the labels to have colors matching the cluster results
y = np.choose(y, [1, 2, 0]).astype(float)
ax.scatter(X[:, 0], X[:, 1], X[:, 2], c=y, cmap=plt.cm.nipy_spectral,
           edgecolor='k')
ax.w_xaxis.set_ticklabels([])
ax.w_yaxis.set_ticklabels([])
ax.w_zaxis.set_ticklabels([])
plt.show()

Total running time of the script: ( 0 minutes 0.087 seconds)

6.10.3 Incremental PCA

Incremental principal component analysis (IPCA) is typically used as a replacement for principal component analysis (PCA) when the dataset to be decomposed is too large to fit in memory. IPCA builds a low-rank approximation for the input data using an amount of memory which is independent of the number of input data samples. It is still dependent on the input data features, but changing the batch size allows for control of memory usage.

This example serves as a visual check that IPCA is able to find a similar projection of the data to PCA (to a sign flip), while only processing a few samples at a time. This can be considered a “toy example”, as IPCA is intended for large datasets which do not fit in main memory, requiring incremental approaches.
Incremental PCA of iris dataset
Mean absolute unsigned error 0.002201
import numpy as np
import matplotlib.pyplot as plt

from sklearn.datasets import load_iris
from sklearn.decomposition import PCA, IncrementalPCA

iris = load_iris()
X = iris.data
y = iris.target
n_components = 2
ipca = IncrementalPCA(n_components=n_components, batch_size=10)
X_ipca = ipca.fit_transform(X)

pca = PCA(n_components=n_components)
X_pca = pca.fit_transform(X)

colors = ['navy', 'turquoise', 'darkorange']

for X_transformed, title in [(X_ipca, "Incremental PCA"), (X_pca, "PCA")]:
    plt.figure(figsize=(8, 8))
    for color, i, target_name in zip(colors, [0, 1, 2], iris.target_names):
        plt.scatter(X_transformed[y == i, 0], X_transformed[y == i, 1],
                    color=color, lw=2, label=target_name)

    if "Incremental" in title:
        err = np.abs(np.abs(X_pca) - np.abs(X_ipca)).mean()
        plt.title(title + " of iris dataset
Mean absolute unsigned error " + "%.6f" % err)
    else:
        plt.title(title + " of iris dataset")
    plt.legend(loc="best", shadow=False, scatterpoints=1)
    plt.axis([-4, 4, -1.5, 1.5])

plt.show()
Out:

explained variance ratio (first two components): [0.92461872 0.05306648]

```python
print(__doc__)

import matplotlib.pyplot as plt

from sklearn import datasets
from sklearn.decomposition import PCA
from sklearn.discriminant_analysis import LinearDiscriminantAnalysis

iris = datasets.load_iris()
X = iris.data
y = iris.target
target_names = iris.target_names

pca = PCA(n_components=2)
X_r = pca.fit(X).transform(X)

lda = LinearDiscriminantAnalysis(n_components=2)

(continues on next page)
```
X_r2 = lda.fit(X, y).transform(X)

# Percentage of variance explained for each components
print('explained variance ratio (first two components): %s' % str(pca.explained_variance_ratio_))

plt.figure()
colors = ['navy', 'turquoise', 'darkorange']
lw = 2

for color, i, target_name in zip(colors, [0, 1, 2], target_names):
    plt.scatter(X_r[y == i, 0], X_r[y == i, 1], color=color, alpha=.8, lw=lw, label=target_name)
plt.legend(loc='best', shadow=False, scatterpoints=1)
plt.title('PCA of IRIS dataset')

plt.figure()
for color, i, target_name in zip(colors, [0, 1, 2], target_names):
    plt.scatter(X_r2[y == i, 0], X_r2[y == i, 1], alpha=.8, color=color, label=target_name)
plt.legend(loc='best', shadow=False, scatterpoints=1)
plt.title('LDA of IRIS dataset')

plt.show()

Total running time of the script: ( 0 minutes 0.231 seconds)

### 6.10.5 Factor Analysis (with rotation) to visualize patterns

Investigating the Iris dataset, we see that sepal length, petal length and petal width are highly correlated. Sepal width is less redundant. Matrix decomposition techniques can uncover these latent patterns. Applying rotations to the resulting components does not inherently improve the predictive value of the derived latent space, but can help visualise their structure; here, for example, the varimax rotation, which is found by maximizing the squared variances of the weights, finds a structure where the second component only loads positively on sepal width.

# Authors: Jona Sassenhagen
# License: BSD 3 clause

import matplotlib.pyplot as plt
import numpy as np
from sklearn.decomposition import FactorAnalysis, PCA
from sklearn.preprocessing import StandardScaler
from sklearn.datasets import load_iris

print(__doc__)

Load Iris data

data = load_iris()
X = StandardScaler().fit_transform(data["data"])
feature_names = data["feature_names"]

Plot covariance of Iris features

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Run factor analysis with Varimax rotation

```python
n_comps = 2
methods = [('PCA', PCA()), ('Unrotated FA', FactorAnalysis()), ('Varimax FA', FactorAnalysis(rotation='varimax'))]
fig, axes = plt.subplots(ncols=len(methods), figsize=(10, 8))
for ax, (method, fa) in zip(axes, methods):
    fa.set_params(n_components=n_comps)
    fa.fit(X)
```

(continues on next page)
components = fa.components_.T
print("%s:
\n" % method)
print(components)

vmax = np.abs(components).max()
ax.imshow(components, cmap="RdBu_r", vmax=vmax, vmin=-vmax)
ax.set_yticks(np.arange(len(feature_names)))
if ax.is_first_col():
    ax.set_yticklabels(feature_names)
else:
    ax.set_yticklabels([[]]
ax.set_title(str(method))
a.set_xticks([0, 1])
a.set_xticklabels(["Comp. 1", "Comp. 2"])
fig.suptitle("Factors")
plt.tight_layout()
plt.show()
PCA:

\[
\begin{bmatrix}
0.52106591 & 0.37741762 \\
-0.26934744 & 0.92329566 \\
0.58041311 & 0.02449161 \\
0.56485654 & 0.06694199 \\
\end{bmatrix}
\]

Unrotated FA:

\[
\begin{bmatrix}
0.88096009 & -0.4472869 \\
-0.41691605 & -0.55390036 \\
0.99918858 & 0.01915283 \\
0.96228895 & 0.05840206 \\
\end{bmatrix}
\]

Varimax FA:

\[
\begin{bmatrix}
0.98633022 & -0.05752333 \\
-0.16052385 & -0.67443065 \\
0.90809432 & 0.41726413 \\
0.85857475 & 0.43847489 \\
\end{bmatrix}
\]

Total running time of the script: (0 minutes 0.404 seconds)

6.10.6 Blind source separation using FastICA

An example of estimating sources from noisy data.

*Independent component analysis (ICA)* is used to estimate sources given noisy measurements. Imagine 3 instruments playing simultaneously and 3 microphones recording the mixed signals. ICA is used to recover the sources i.e. what is played by each instrument. Importantly, PCA fails at recovering our *instruments* since the related signals reflect non-Gaussian processes.
```python
import numpy as np
import matplotlib.pyplot as plt
from scipy import signal
from sklearn.decomposition import FastICA, PCA

# #############################################################################
# Generate sample data
np.random.seed(0)
n_samples = 2000
time = np.linspace(0, 8, n_samples)
s1 = np.sin(2 * time)  # Signal 1: sinusoidal signal
s2 = np.sign(np.sin(3 * time))  # Signal 2: square signal
s3 = signal.sawtooth(2 * np.pi * time)  # Signal 3: saw tooth signal
S = np.c_[s1, s2, s3]
S += 0.2 * np.random.normal(size=S.shape)  # Add noise
S /= S.std(axis=0)  # Standardize data

# Mix data
A = np.array([[1, 1, 1], [0.5, 2, 1.0], [1.5, 1.0, 2.0]])  # Mixing matrix
X = np.dot(S, A.T)  # Generate observations
```

6.10. Decomposition
# Compute ICA
ica = FastICA(n_components=3)
S_ = ica.fit_transform(X)  # Reconstruct signals
A_ = ica.mixing_  # Get estimated mixing matrix

# We can 'prove' that the ICA model applies by reverting the unmixing.
assert np.allclose(X, np.dot(S_, A_.T) + ica.mean_)

# For comparison, compute PCA
pca = PCA(n_components=3)
H = pca.fit_transform(X)  # Reconstruct signals based on orthogonal components

# Plot results
plt.figure()
models = [X, S, S_, H]
names = ['Observations (mixed signal)', 'True Sources', 'ICA recovered signals', 'PCA recovered signals']
colors = ['red', 'steelblue', 'orange']

for ii, (model, name) in enumerate(zip(models, names), 1):
    plt.subplot(4, 1, ii)
    plt.title(name)
    for sig, color in zip(model.T, colors):
        plt.plot(sig, color=color)

plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 0.284 seconds)

### 6.10.7 Principal components analysis (PCA)

These figures aid in illustrating how a point cloud can be very flat in one direction—which is where PCA comes in to choose a direction that is not flat.
from sklearn.decomposition import PCA
from mpl_toolkits.mplot3d import Axes3D
import numpy as np
import matplotlib.pyplot as plt
from scipy import stats

# Authors: Gael Varoquaux
#          Jaques Grobler
#          Kevin Hughes
# License: BSD 3 clause

# Create the data
e = np.exp(1)
np.random.seed(4)

def pdf(x):
    return 0.5 * (stats.norm(scale=0.25 / e).pdf(x)
    + stats.norm(scale=4 / e).pdf(x))

y = np.random.normal(scale=0.5, size=(30000))
x = np.random.normal(scale=0.5, size=(30000))
z = np.random.normal(scale=0.1, size=len(x))

density = pdf(x) * pdf(y)
pdf_z = pdf(5 * z)

density *= pdf_z

a = x + y
b = 2 * y
c = a - b + z

norm = np.sqrt(a.var() + b.var())
a /= norm
b /= norm

# Plot the figures

def plot_figs(fig_num, elev, azim):
    fig = plt.figure(fig_num, figsize=(4, 3))
    plt.clf()
    ax = Axes3D(fig, rect=[0, 0, .95, 1], elev=elev, azim=azim)

    ax.scatter(a[:10], b[:10], c[:10], c=density[:10], marker='+', alpha=.4)
    Y = np.c_[a, b, c]

    # Using SciPy’s SVD, this would be:
    # _, pca_score, Vt = scipy.linalg.svd(Y, full_matrices=False)
    pca = PCA(n_components=3)
    pca.fit(Y)
    V = pca.components_.T

    x_pca_axis, y_pca_axis, z_pca_axis = 3 * V
    x_pca_plane = np.r_[x_pca_axis[:2], - x_pca_axis[1::-1]]
    y_pca_plane = np.r_[y_pca_axis[:2], - y_pca_axis[1::-1]]
    z_pca_plane = np.r_[z_pca_axis[:2], - z_pca_axis[1::-1]]
    x_pca_plane.shape = (2, 2)
    y_pca_plane.shape = (2, 2)
    z_pca_plane.shape = (2, 2)
    ax.plot_surface(x_pca_plane, y_pca_plane, z_pca_plane)
    ax.w_xaxis.set_ticklabels([])
    ax.w_yaxis.set_ticklabels([])
    ax.w_zaxis.set_ticklabels([])
6.10.8 FastICA on 2D point clouds

This example illustrates visually in the feature space a comparison by results using two different component analysis techniques.

*Independent component analysis (ICA) vs Principal component analysis (PCA).*

Representing ICA in the feature space gives the view of ‘geometric ICA’: ICA is an algorithm that finds directions in the feature space corresponding to projections with high non-Gaussianity. These directions need not be orthogonal in the original feature space, but they are orthogonal in the whitened feature space, in which all directions correspond to the same variance.

PCA, on the other hand, finds orthogonal directions in the raw feature space that correspond to directions accounting for maximum variance.

Here we simulate independent sources using a highly non-Gaussian process, 2 student T with a low number of degrees of freedom (top left figure). We mix them to create observations (top right figure). In this raw observation space, directions identified by PCA are represented by orange vectors. We represent the signal in the PCA space, after whitening by the variance corresponding to the PCA vectors (lower left). Running ICA corresponds to finding a rotation in this space to identify the directions of largest non-Gaussianity (lower right).
import numpy as np
import matplotlib.pyplot as plt
from sklearn.decomposition import PCA, FastICA

# Generate sample data
rng = np.random.RandomState(42)
S = rng.standard_t(1.5, size=(20000, 2))
S[:, 0] *= 2.

# Mix data
A = np.array([[1, 1], [0, 2]])  # Mixing matrix
X = np.dot(S, A.T)  # Generate observations

pca = PCA()
S_pca_ = pca.fit(X).transform(X)
ica = FastICA(random_state=rng)

#Authors: Alexandre Gramfort, Gael Varoquaux
#License: BSD 3 clause

print(__doc__)
S_ica_ = ica.fit(X).transform(X)  # Estimate the sources
S_ica_ /= S_ica_.std(axis=0)

# Plot results

def plot_samples(S, axis_list=None):
    plt.scatter(S[:, 0], S[:, 1], s=2, marker='o', zorder=10,
                color='steelblue', alpha=0.5)
    if axis_list is not None:
        colors = ['orange', 'red']
        for color, axis in zip(colors, axis_list):
            axis /= axis.std()
            x_axis, y_axis = axis
            # Trick to get legend to work
            plt.plot(0.1 * x_axis, 0.1 * y_axis, linewidth=2, color=color)
            plt.quiver((0, 0), (0, 0), x_axis, y_axis, zorder=11, width=0.01,
                       scale=6, color=color)

    plt.hlines(0, -3, 3)
    plt.vlines(0, -3, 3)
    plt.xlim(-3, 3)
    plt.ylim(-3, 3)
    plt.xlabel('x')
    plt.ylabel('y')

plt.figure()
plt.subplot(2, 2, 1)
plot_samples(S / S.std())
plt.title('True Independent Sources')
axis_list = [pca.components_.T, ica.mixing_]
plt.plot(X / np.std(X), axis_list=axis_list)
legend = plt.legend(['PCA', 'ICA'], loc='upper right')
legend.set_zorder(100)
plt.title('Observations')

plt.subplot(2, 2, 3)
plot_samples(S_pca_ / np.std(S_pca_, axis=0))
plt.title('PCA recovered signals')

plt.subplot(2, 2, 4)
plot_samples(S_ica_ / np.std(S_ica_))
plt.title('ICA recovered signals')

plt.subplots_adjust(0.09, 0.04, 0.94, 0.94, 0.26, 0.36)
plt.show()
6.10.9 Kernel PCA

This example shows that Kernel PCA is able to find a projection of the data that makes data linearly separable.

![Original space](chart1.png) ![Projection by PCA](chart2.png) ![Projection by KPCA](chart3.png) ![Original space after inverse transf](chart4.png)

```python
print(__doc__)

# Authors: Mathieu Blondel
# Andreas Mueller
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn.decomposition import PCA, KernelPCA
from sklearn.datasets import make_circles

np.random.seed(0)

X, y = make_circles(n_samples=400, factor=.3, noise=.05)

k pca = KernelPCA(kernel="rbf", fit_inverse_transform=True, gamma=10)
X_kpca = k pca.fit_transform(X)
X_back = k pca.inverse_transform(X_kpca)
pca = PCA()
X_pca = pca.fit_transform(X)
```

(continues on next page)
# Plot results

```python
plt.figure()
plt.subplot(2, 2, 1, aspect='equal')
plt.title("Original space")
reds = y == 0
blues = y == 1
plt.scatter(X[reds, 0], X[reds, 1], c="red", s=20, edgecolor='k')
plt.scatter(X[blues, 0], X[blues, 1], c="blue", s=20, edgecolor='k')
plt.xlabel("$x_1$"
plt.ylabel("$x_2$")

X1, X2 = np.meshgrid(np.linspace(-1.5, 1.5, 50), np.linspace(-1.5, 1.5, 50))
X_grid = np.array([np.ravel(X1), np.ravel(X2)]).T
# projection on the first principal component (in the phi space)
Z_grid = kpca.transform(X_grid)[:, 0].reshape(X1.shape)
plt.contour(X1, X2, Z_grid, colors='grey', linewidths=1, origin='lower')
plt.subplot(2, 2, 2, aspect='equal')
plt.scatter(X_pca[reds, 0], X_pca[reds, 1], c="red", s=20, edgecolor='k')
plt.scatter(X_pca[blues, 0], X_pca[blues, 1], c="blue", s=20, edgecolor='k')
plt.title("Projection by PCA")
plt.xlabel("1st principal component")
plt.ylabel("2nd component")
plt.subplot(2, 2, 3, aspect='equal')
plt.scatter(X_kpca[reds, 0], X_kpca[reds, 1], c="red", s=20, edgecolor='k')
plt.scatter(X_kpca[blues, 0], X_kpca[blues, 1], c="blue", s=20, edgecolor='k')
plt.title("Projection by KPCA")
plt.xlabel(r"1st principal component in space induced by $\phi$")
plt.ylabel("2nd component")
plt.subplot(2, 2, 4, aspect='equal')
plt.scatter(X_back[reds, 0], X_back[reds, 1], c="red", s=20, edgecolor='k')
plt.scatter(X_back[blues, 0], X_back[blues, 1], c="blue", s=20, edgecolor='k')
plt.title("Original space after inverse transform")
plt.xlabel("$x_1$")
plt.ylabel("$x_2$")
plt.tight_layout()
plt.show()
```

Total running time of the script: ( 0 minutes 0.374 seconds)
6.10.10 Model selection with Probabilistic PCA and Factor Analysis (FA)

Probabilistic PCA and Factor Analysis are probabilistic models. The consequence is that the likelihood of new data can be used for model selection and covariance estimation. Here we compare PCA and FA with cross-validation on low rank data corrupted with homoscedastic noise (noise variance is the same for each feature) or heteroscedastic noise (noise variance is the different for each feature). In a second step we compare the model likelihood to the likelihoods obtained from shrinkage covariance estimators.

One can observe that with homoscedastic noise both FA and PCA succeed in recovering the size of the low rank subspace. The likelihood with PCA is higher than FA in this case. However PCA fails and overestimates the rank when heteroscedastic noise is present. Under appropriate circumstances the low rank models are more likely than shrinkage models.

The automatic estimation from Automatic Choice of Dimensionality for PCA. NIPS 2000: 598-604 by Thomas P. Minka is also compared.
Out:

```python
best n_components by PCA CV = 10
best n_components by FactorAnalysis CV = 10
best n_components by PCA MLE = 10
best n_components by PCA CV = 35
best n_components by FactorAnalysis CV = 10
best n_components by PCA MLE = 38
```
# Create the data
n_samples, n_features, rank = 1000, 50, 10
sigma = 1.
rng = np.random.RandomState(42)
U, _, _ = linalg.svd(rng.randn(n_features, n_features))
X = np.dot(rng.randn(n_samples, rank), U[:, :rank].T)

# Adding homoscedastic noise
X_homo = X + sigma * rng.randn(n_samples, n_features)

# Adding heteroscedastic noise
sigmas = sigma * rng.rand(n_features) + sigma / 2.
X_hetero = X + rng.randn(n_samples, n_features) * sigmas

# Fit the models
n_components = np.arange(0, n_features, 5)  # options for n_components

def compute_scores(X):
    pca = PCA(svd_solver='full')
    fa = FactorAnalysis()

    pca_scores, fa_scores = [], []
    for n in n_components:
        pca.n_components = n
        fa.n_components = n
        pca_scores.append(np.mean(cross_val_score(pca, X)))
        fa_scores.append(np.mean(cross_val_score(fa, X)))

    return pca_scores, fa_scores

def shrunk_cov_score(X):
    shrinkages = np.logspace(-2, 0, 30)
cv = GridSearchCV(ShrunkCovariance(), {'shrinkage': shrinkages})
    return np.mean(cross_val_score(cv.fit(X).best_estimator_, X))

def lw_score(X):
    return np.mean(cross_val_score(LedoitWolf(), X))

for X, title in [(X_homo, 'Homoscedastic Noise'), (X_hetero, 'Heteroscedastic Noise')]:
    pca_scores, fa_scores = compute_scores(X)
    n_components_pca = n_components[np.argmax(pca_scores)]
    n_components_fa = n_components[np.argmax(fa_scores)]

    pca = PCA(svd_solver='full', n_components='mle')
    pca.fit(X)
    n_components_pca_mle = pca.n_components_
print("best n_components by PCA CV = \$d\" % n_components_pca)
print("best n_components by FactorAnalysis CV = \$d\" % n_components_fa)
print("best n_components by PCA MLE = \$d\" % n_components_pca_mle)

plt.figure()
plt.plot(n_components, pca_scores, 'b', label='PCA scores')
plt.plot(n_components, fa_scores, 'r', label='FA scores')
plt.axvline(rank, color='g', label='TRUTH: \$d\" % rank, linestyle='--')
plt.axvline(n_components_pca, color='b',
            label='PCA CV: \$d\" % n_components_pca, linestyle='--')
plt.axvline(n_components_fa, color='r',
            label='FactorAnalysis CV: \$d\" % n_components_fa,
            linestyle='--')
plt.axvline(n_components_pca_mle, color='k',
            label='PCA MLE: \$d\" % n_components_pca_mle, linestyle='--')

# compare with other covariance estimators
plt.axhline(shrunk_cov_score(X), color='violet',
            label='Shrunk Covariance MLE', linestyle='-.')
plt.axhline(lw_score(X), color='orange',
            label='LedoitWolf MLE % n_components_pca_mle, linestyle='-.')

plt.xlabel('nb of components')
plt.ylabel('CV scores')
plt.legend(loc='lower right')
plt.title(title)
plt.show()

Total running time of the script: ( 0 minutes 8.567 seconds)

6.10.11 Sparse coding with a precomputed dictionary

Transform a signal as a sparse combination of Ricker wavelets. This example visually compares different sparse coding methods using the SparseCoder estimator. The Ricker (also known as Mexican hat or the second derivative of a Gaussian) is not a particularly good kernel to represent piecewise constant signals like this one. It can therefore be seen how much adding different widths of atoms matters and it therefore motivates learning the dictionary to best fit your type of signals.

The richer dictionary on the right is not larger in size, heavier subsampling is performed in order to stay on the same order of magnitude.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.decomposition import SparseCoder
from sklearn.utils.fixes import np_version, parse_version

def ricker_function(resolution, center, width):
    """Discrete sub-sampled Ricker (Mexican hat) wavelet""
    x = np.linspace(0, resolution - 1, resolution)
    x = ((2 / (np.sqrt(3 * width) * np.pi ** .25))
     * (1 - (x - center) ** 2 / width ** 2)
     * np.exp(-(x - center) ** 2 / (2 * width ** 2)))
    return x

def ricker_matrix(width, resolution, n_components):
    """Dictionary of Ricker (Mexican hat) wavelets""
    centers = np.linspace(0, resolution - 1, n_components)
    D = np.empty((n_components, resolution))
    for i, center in enumerate(centers):
        D[i] = ricker_function(resolution, center, width)
    D /= np.sqrt(np.sum(D ** 2, axis=1))[:, np.newaxis]
    return D

resolution = 1024
subsampling = 3  # subsampling factor
width = 100
n_components = resolution // subsampling

# Compute a wavelet dictionary
D_fixed = ricker_matrix(width=width, resolution=resolution,
                        n_components=n_components)
D_multi = np.r_[tuple(ricker_matrix(width=w, resolution=resolution,
                        n_components=n_components)) for w in [10, 20, 30]]
n_components=n_components // 5)

for w in (10, 50, 100, 500, 1000))

# Generate a signal
y = np.linspace(0, resolution - 1, resolution)
first_quarter = y < resolution / 4
y[first_quarter] = 3.
y[np.logical_not(first_quarter)] = -1.

# List the different sparse coding methods in the following format:
# (title, transform_algorithm, transform_alpha,
# transform_n_nozero_coefs, color)
estimators = [('OMP', 'omp', None, 15, 'navy'),
('Lasso', 'lasso_lars', 2, None, 'turquoise'), ]
lw = 2

# Avoid FutureWarning about default value change when numpy >= 1.14
lstsq_rcond = None if np_version >= parse_version('1.14') else -1

plt.figure(figsize=(13, 6))
for subplot, (D, title) in enumerate(zip((D_fixed, D_multi),
('fixed width', 'multiple widths'))):
  plt.subplot(1, 2, subplot + 1)
  plt.title('Sparse coding against %s
dictionary' % title)
  plt.plot(y, lw=lw, linestyle='--', label='Original signal')

  # Do a wavelet approximation
  for title, algo, alpha, n_nonzero, color in estimators:
    coder = SparseCoder(dictionary=D, transform_n_nonzero_coefs=n_nonzero,
      transform_alpha=alpha, transform_algorithm=algo)
    x = coder.transform(y.reshape(1, -1))
    density = len(np.flatnonzero(x))
    x = np.ravel(np.dot(x, D))
    squared_error = np.sum((y - x) ** 2)
    plt.plot(x, color=color, lw=lw,
      label='%s: %d nonzero coefs, %.2f error' %
      (title, density, squared_error))

  # Soft thresholding debiasing
  coder = SparseCoder(dictionary=D, transform_algorithm='threshold',
    transform_alpha=20)
  x = coder.transform(y.reshape(1, -1))
  _, idx = np.where(x != 0)
  x[0, idx], _, _, _ = np.linalg.lstsq(D[idx, :].T, y, rcond=lstsq_rcond)
  x = np.ravel(np.dot(x, D))
  squared_error = np.sum((y - x) ** 2)
  plt.plot(x, color='darkorange', lw=lw,
    label='Thresholding w/ debiasing: %d nonzero coefs, %.2f error' %
    (len(idx), squared_error))

plt.axis('tight')
plt.legend(shadow=False, loc='best')
plt.subplots_adjust(.04, .07, .97, .90, .09, .2)
plt.show()

Total running time of the script: ( 0 minutes 0.333 seconds)
6.10.12 Image denoising using dictionary learning

An example comparing the effect of reconstructing noisy fragments of a raccoon face image using firstly online Dictionary Learning and various transform methods.

The dictionary is fitted on the distorted left half of the image, and subsequently used to reconstruct the right half. Note that even better performance could be achieved by fitting to an undistorted (i.e. noiseless) image, but here we start from the assumption that it is not available.

A common practice for evaluating the results of image denoising is by looking at the difference between the reconstruction and the original image. If the reconstruction is perfect this will look like Gaussian noise.

It can be seen from the plots that the results of Orthogonal Matching Pursuit (OMP) with two non-zero coefficients is a bit less biased than when keeping only one (the edges look less prominent). It is in addition closer from the ground truth in Frobenius norm.

The result of Least Angle Regression is much more strongly biased: the difference is reminiscent of the local intensity value of the original image.

Thresholding is clearly not useful for denoising, but it is here to show that it can produce a suggestive output with very high speed, and thus be useful for other tasks such as object classification, where performance is not necessarily related to visualisation.

Dictionary learned from face patches
Train time 3.0s on 22692 patches
Distorted image

Orthogonal Matching Pursuit
1 atom (time: 0.8s)
Orthogonal Matching Pursuit
2 atoms (time: 1.9s)

Image | Difference (norm: 9.64)
--- | ---

Least-angle regression
5 atoms (time: 18.1s)

Image | Difference (norm: 14.04)
--- | ---
Thresholding
alpha=0.1 (time: 0.1s)

Image

Difference (norm: 14.98)

Out:

```
Distorting image...
Extracting reference patches...
done in 0.01s.
Learning the dictionary...
done in 2.98s.
Extracting noisy patches...
done in 0.00s.
Orthogonal Matching Pursuit
1 atom...
done in 0.78s.
Orthogonal Matching Pursuit
2 atoms...
done in 1.86s.
Least-angle regression
5 atoms...
done in 18.05s.
Thresholding
alpha=0.1...
done in 0.13s.
```

```
print(__doc__)

from time import time

import matplotlib.pyplot as plt
import numpy as np
import scipy as sp
```
from sklearn.decomposition import MiniBatchDictionaryLearning
from sklearn.feature_extraction.image import extract_patches_2d
from sklearn.feature_extraction.image import reconstruct_from_patches_2d

try:
    # SciPy >= 0.16 have face in misc
    from scipy.misc import face
    face = face(gray=True)
except ImportError:
    face = sp.face(gray=True)

# Convert from uint8 representation with values between 0 and 255 to
# a floating point representation with values between 0 and 1.
face = face / 255.

# downsample for higher speed
face = face[:, ::4] + face[:, 1::4] + face[1::4, ::4] + face[1::4, 1::4]
face /= 4.0
height, width = face.shape

# Distort the right half of the image
print('Distorting image...')
distorted = face.copy()
distorted[:, width // 2:] += 0.075 * np.random.randn(height, width // 2)

# Extract all reference patches from the left half of the image
print('Extracting reference patches...')
t0 = time()
patch_size = (7, 7)
data = extract_patches_2d(distorted[:, :width // 2], patch_size)
data = data.reshape(data.shape[0], -1)
data -= np.mean(data, axis=0)
data /= np.std(data, axis=0)
print('done in %.2f s.' % (time() - t0))

# Learn the dictionary from reference patches
print('Learning the dictionary...')
t0 = time()
dico = MiniBatchDictionaryLearning(n_components=100, alpha=1, n_iter=500)
V = dico.fit(data).components_
dt = time() - t0
print('done in %.2fs.' % dt)

plt.figure(figsize=(4.2, 4))
for i, comp in enumerate(V[:100]):
    plt.subplot(10, 10, i + 1)
    plt.imshow(comp.reshape(patch_size), cmap=plt.cm.gray_r, interpolation='nearest')
    plt.xticks(())
    plt.yticks(())
plt.suptitle('Dictionary learned from face patches

Train time %.2fs on %d patches' % (dt, len(data)),
fontsize=16)
plt.subplots_adjust(0.08, 0.02, 0.92, 0.85, 0.08, 0.23)

(continues on next page)
# Display the distorted image

def show_with_diff(image, reference, title):
    #"Helper function to display denoising"
    plt.figure(figsize=(5, 3.3))
    plt.subplot(1, 2, 1)
    plt.title('Image')
    plt.imshow(image, vmin=0, vmax=1, cmap=plt.cm.gray,
               interpolation='nearest')
    plt.xticks(())
    plt.yticks(()
    plt.subplot(1, 2, 2)
    difference = image - reference
    plt.title('Difference (norm: %.2f)' % np.sqrt(np.sum(difference ** 2)))
    plt.imshow(difference, vmin=-0.5, vmax=0.5, cmap=plt.cm.PuOr,
               interpolation='nearest')
    plt.xticks(())
    plt.yticks(()
    plt.suptitle(title, size=16)
    plt.subplots_adjust(0.02, 0.02, 0.98, 0.79, 0.02, 0.2)

    show_with_diff(distorted, face, 'Distorted image')

# Extract noisy patches and reconstruct them using the dictionary

def show_with_diff(image, reference, title):
    #"Helper function to display denoising"
    plt.figure(figsize=(5, 3.3))
    plt.subplot(1, 2, 1)
    plt.title('Image')
    plt.imshow(image, vmin=0, vmax=1, cmap=plt.cm.gray,
               interpolation='nearest')
    plt.xticks(())
    plt.yticks(()
    plt.subplot(1, 2, 2)
    difference = image - reference
    plt.title('Difference (norm: %.2f)' % np.sqrt(np.sum(difference ** 2)))
    plt.imshow(difference, vmin=-0.5, vmax=0.5, cmap=plt.cm.PuOr,
               interpolation='nearest')
    plt.xticks(())
    plt.yticks(()
    plt.suptitle(title, size=16)
    plt.subplots_adjust(0.02, 0.02, 0.98, 0.79, 0.02, 0.2)

    show_with_diff(distorted, face, 'Distorted image')

# Extract noisy patches and reconstruct them using the dictionary

print('Extracting noisy patches... ')
t0 = time()
data = extract_patches_2d(distorted[:, width // 2:], patch_size)
data = data.reshape(data.shape[0], -1)
intercept = np.mean(data, axis=0)
data -= intercept
print('done in %.2f s.' % (time() - t0))

transform_algorithms = [
    ('Orthogonal Matching Pursuit \n 1 atom', 'omp',
     {'transform_n_nonzero_coefs': 1}),
    ('Orthogonal Matching Pursuit \n 2 atoms', 'omp',
     {'transform_n_nonzero_coefs': 2}),
    ('Least-angle regression \n 5 atoms', 'lars',
     {'transform_n_nonzero_coefs': 5}),
    ('Thresholding \n alpha=0.1', 'threshold', {'transform_alpha': .1})
]

reconstructions = {}
for title, transform_algorithm, kwargs in transform_algorithms:
    print(title + '...')
    reconstructions[title] = face.copy()
    t0 = time()
    dico.set_params(transform_algorithm=transform_algorithm, **kwargs)
    code = dico.transform(data)
    patches = np.dot(code, V)
    patches += intercept
    patches = patches.reshape(len(data), *patch_size)
if transform_algorithm == 'threshold':
    patches -= patches.min()
    patches /= patches.max()
reconstructions[title][:, width // 2:] = reconstruct_from_patches_2d(
    patches, (height, width // 2))
dt = time() - t0
print('done in %.2f s.' % dt)
show_with_diff(reconstructions[title], face,
    title + ' (time: %.1f s)' % dt)
plt.show()

Total running time of the script: ( 0 minutes 26.422 seconds)

6.10.13 Faces dataset decompositions

This example applies to The Olivetti faces dataset different unsupervised matrix decomposition (dimension reduction) methods from the module sklearn.decomposition (see the documentation chapter Decomposing signals in components (matrix factorization problems)).

First centered Olivetti faces
Eigenfaces - PCA using randomized SVD - Train time 0.0
Non-negative components - NMF - Train time 0.1s

.
Independent components - FastICA - Train time 0.2s
Sparse comp. - MiniBatchSparsePCA - Train time 0.9s
MiniBatchDictionaryLearning - Train time 0.5s
Cluster centers - MiniBatchKMeans - Train time 0.1s

Pixelwise variance
Factor Analysis components - FA - Train time 0.2s
First centered Olivetti faces
Dictionary learning
Dictionary learning - positive dictionary
Dictionary learning - positive code
Out:

Dataset consists of 400 faces
Extracting the top 6 Eigenfaces - PCA using randomized SVD... done in 0.021s
Extracting the top 6 Non-negative components - NMF... done in 0.092s
Extracting the top 6 Independent components - FastICA... /home/circleci/project/sklearn/decomposition/_fastica.py:118: ConvergenceWarning: →FastICA did not converge. Consider increasing tolerance or the maximum number of →iterations.
warnings.warn('FastICA did not converge. Consider increasing ' done in 0.152s
Extracting the top 6 Sparse comp. - MiniBatchSparsePCA... done in 0.865s
Extracting the top 6 MiniBatchDictionaryLearning... done in 0.491s
Extracting the top 6 Cluster centers - MiniBatchKMeans... done in 0.088s
Extracting the top 6 Factor Analysis components - FA... done in 0.181s
Extracting the top 6 Dictionary learning... done in 0.588s
Extracting the top 6 Dictionary learning - positive dictionary... done in 0.567s
Extracting the top 6 Dictionary learning - positive code... done in 0.156s
Extracting the top 6 Dictionary learning - positive dictionary & code... (continues on next page)
print(__doc__)

# Authors: Vlad Niculae, Alexandre Gramfort
# License: BSD 3 clause

import logging
from time import time
from numpy.random import RandomState
import matplotlib.pyplot as plt
from sklearn.datasets import fetch_olivetti_faces
from sklearn.cluster import MiniBatchKMeans
from sklearn import decomposition

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO,
                     format='%(asctime)s %(levelname)s %(message)s')

n_row, n_col = 2, 3
n_components = n_row * n_col
image_shape = (64, 64)
rng = RandomState(0)

# Load faces data
faces, _ = fetch_olivetti_faces(return_X_y=True, shuffle=True,
                                 random_state=rng)
n_samples, n_features = faces.shape

# global centering
faces_centered = faces - faces.mean(axis=0)

# local centering
faces_centered -= faces_centered.mean(axis=1).reshape(n_samples, -1)

print("Dataset consists of %d faces" % n_samples)

def plot_gallery(title, images, n_col=n_col, n_row=n_row, cmap=plt.cm.gray):
    plt.figure(figsize=(2. * n_col, 2.26 * n_row))
    plt.suptitle(title, size=16)
    for i, comp in enumerate(images):
        plt.subplot(n_row, n_col, i + 1)
        vmax = max(comp.max(), -comp.min())
        plt.imshow(comp.reshape(image_shape), cmap=cmap,
                   interpolation='nearest',
                   vmin=-vmax, vmax=vmax)
        plt.xticks(())
        plt.yticks(())

(continues on next page)
plt.subplots_adjust(0.01, 0.05, 0.99, 0.93, 0.04, 0.)

# List of the different estimators, whether to center and transpose the
# problem, and whether the transformer uses the clustering API.
estimators = [
    ('Eigenfaces - PCA using randomized SVD',
     decomposition.PCA(n_components=n_components, svd_solver='randomized',
                    whiten=True),
     True),
    ('Non-negative components - NMF',
     decomposition.NMF(n_components=n_components, init='nndsvda', tol=5e-3),
                    False),
    ('Independent components - FastICA',
     decomposition.FastICA(n_components=n_components, whiten=True),
                    True),
    ('Sparse comp. - MiniBatchSparsePCA',
     decomposition.MiniBatchSparsePCA(n_components=n_components, alpha=0.8,
                    n_iter=100, batch_size=3,
                    random_state=rng),
                    True),
    ('MiniBatchDictionaryLearning',
     decomposition.MiniBatchDictionaryLearning(n_components=15, alpha=0.1,
                    n_iter=50, batch_size=3,
                    random_state=rng),
                    True),
    ('Cluster centers - MiniBatchKMeans',
     MiniBatchKMeans(n_clusters=n_components, tol=1e-3, batch_size=20,
                    max_iter=50, random_state=rng),
                    True),
    ('Factor Analysis components - FA',
     decomposition.FactorAnalysis(n_components=n_components, max_iter=20),
                    True),
]

# Plot a sample of the input data

plot_gallery("First centered Olivetti faces", faces_centered[:n_components])

# Do the estimation and plot it

for name, estimator, center in estimators:
    print("Extracting the top %d %s...") % (n_components, name)
    t0 = time()
    data = faces
    if center:
       data = faces_centered
    estimator.fit(data)

(continues on next page)
train_time = (time() - t0)
print("done in %0.3fs" % train_time)
if hasattr(estimator, 'cluster_centers_ '):
    components_ = estimator.cluster_centers_
else:
    components_ = estimator.components_

# Plot an image representing the pixelwise variance provided by the
# estimator e.g its noise_variance_ attribute. The Eigenfaces estimator,
# via the PCA decomposition, also provides a scalar noise_variance_
# (the mean of pixelwise variance) that cannot be displayed as an image
# so we skip it.
if (hasattr(estimator, 'noise_variance_') and
    estimator.noise_variance_.ndim > 0):  # Skip the Eigenfaces case
    plot_gallery("Pixelwise variance",
                 estimator.noise_variance_.reshape(1, -1), n_col=1,
                 n_row=1)
    plot_gallery('%.1f' % (name, train_time),
                 components_[:n_components])
plt.show()

# #############################################################################
# Various positivity constraints applied to dictionary learning.
estimators = [
    ('Dictionary learning',
     decomposition.MiniBatchDictionaryLearning(n_components=15, alpha=0.1,
                                             n_iter=50, batch_size=3,
                                             random_state=rng),
     True),
    ('Dictionary learning - positive dictionary',
     decomposition.MiniBatchDictionaryLearning(n_components=15, alpha=0.1,
                                             n_iter=50, batch_size=3,
                                             random_state=rng,
                                             positive_dict=True),
     True),
    ('Dictionary learning - positive code',
     decomposition.MiniBatchDictionaryLearning(n_components=15, alpha=0.1,
                                             n_iter=50, batch_size=3,
                                             fit_algorithm='cd',
                                             random_state=rng,
                                             positive_code=True),
     True),
    ('Dictionary learning - positive dictionary & code',
     decomposition.MiniBatchDictionaryLearning(n_components=15, alpha=0.1,
                                             n_iter=50, batch_size=3,
                                             fit_algorithm='cd',
                                             random_state=rng,
                                             positive_dict=True,
                                             positive_code=True),
     True),
]
# #############################################################################
# Plot a sample of the input data

6.10. Decomposition  965
plot_gallery("First centered Olivetti faces", faces_centered[:n_components],
               cmap=plt.cm.RdBu)

# Do the estimation and plot it

for name, estimator, center in estimators:
    print("Extracting the top %d %s..." % (n_components, name))
    t0 = time()
    data = faces
    if center:
        data = faces_centered
        estimator.fit(data)
    train_time = (time() - t0)
    print("done in %0.3fs" % train_time)
    components_ = estimator.components_
    plot_gallery(name, components_[:n_components], cmap=plt.cm.RdBu)
plt.show()

Total running time of the script: ( 0 minutes 5.639 seconds)

6.11 Ensemble methods

Examples concerning the sklearn.ensemble module.

6.11.1 Pixel importances with a parallel forest of trees

This example shows the use of forests of trees to evaluate the impurity-based importance of the pixels in an image classification task (faces). The hotter the pixel, the more important.

The code below also illustrates how the construction and the computation of the predictions can be parallelized within multiple jobs.
Fitting ExtraTreesClassifier on faces data with 1 cores...
done in 1.257s

```
print(__doc__)

from time import time
import matplotlib.pyplot as plt

from sklearn.datasets import fetch_olivetti_faces
from sklearn.ensemble import ExtraTreesClassifier

# Number of cores to use to perform parallel fitting of the forest model
n_jobs = 1

# Load the faces dataset
data = fetch_olivetti_faces()
X, y = data.data, data.target
```
mask = y < 5  # Limit to 5 classes
X = X[mask]
y = y[mask]

# Build a forest and compute the pixel importances
print("Fitting ExtraTreesClassifier on faces data with %d cores...", n_jobs)
t0 = time()
forest = ExtraTreesClassifier(n_estimators=1000,
                               max_features=128,
                               n_jobs=n_jobs,
                               random_state=0)
forest.fit(X, y)
print("done in %0.3fs", time() - t0)
importances = forest.feature_importances_
importances = importances.reshape(data.images[0].shape)

# Plot pixel importances
plt.matshow(importances, cmap=plt.cm.hot)
plt.title("Pixel importances with forests of trees")
plt.show()

Total running time of the script: ( 0 minutes 1.472 seconds)

6.11.2 Decision Tree Regression with AdaBoost

A decision tree is boosted using the AdaBoost.R2 algorithm on a 1D sinusoidal dataset with a small amount of Gaussian noise. 299 boosts (300 decision trees) is compared with a single decision tree regressor. As the number of boosts is increased the regressor can fit more detail.

# Author: Noel Dawe <noel.dawe@gmail.com>
#
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from sklearn.tree import DecisionTreeRegressor
from sklearn.ensemble import AdaBoostRegressor

# Create the dataset
rng = np.random.RandomState(1)
X = np.linspace(0, 6, 100)[:, np.newaxis]
y = np.sin(X).ravel() + np.sin(6 * X).ravel() + rng.normal(0, 0.1, X.shape[0])

# Fit regression model
regr_1 = DecisionTreeRegressor(max_depth=4)
regr_2 = AdaBoostRegressor(DecisionTreeRegressor(max_depth=4), n_estimators=300, random_state=rng)

regr_1.fit(X, y)
regr_2.fit(X, y)
# Predict
y_1 = regr_1.predict(X)
y_2 = regr_2.predict(X)

# Plot the results
plt.figure()
plt.scatter(X, y, c="k", label="training samples")
plt.plot(X, y_1, c="g", label="n_estimators=1", linewidth=2)
plt.plot(X, y_2, c="r", label="n_estimators=300", linewidth=2)
plt.xlabel("data")
plt.ylabel("target")
plt.title("Boosted Decision Tree Regression")
plt.legend()
plt.show()

Total running time of the script: ( 0 minutes 0.466 seconds)

## 6.11.3 Plot individual and voting regression predictions

A voting regressor is an ensemble meta-estimator that fits several base regressors, each on the whole dataset. Then it averages the individual predictions to form a final prediction. We will use three different regressors to predict the data: GradientBoostingRegressor, RandomForestRegressor, and LinearRegression. Then the above 3 regressors will be used for the VotingRegressor.

Finally, we will plot the predictions made by all models for comparison.

We will work with the diabetes dataset which consists of 10 features collected from a cohort of diabetes patients. The target is a quantitative measure of disease progression one year after baseline.

print(__doc__)

import matplotlib.pyplot as plt
from sklearn.datasets import load_diabetes
from sklearn.ensemble import GradientBoostingRegressor
from sklearn.ensemble import RandomForestRegressor
from sklearn.linear_model import LinearRegression
from sklearn.ensemble import VotingRegressor

Training classifiers

First, we will load the diabetes dataset and initiate a gradient boosting regressor, a random forest regressor and a linear regression. Next, we will use the 3 regressors to build the voting regressor:

X, y = load_diabetes(return_X_y=True)

# Train classifiers
reg1 = GradientBoostingRegressor(random_state=1)
reg2 = RandomForestRegressor(random_state=1)
reg3 = LinearRegression()

reg1.fit(X, y)
reg2.fit(X, y)
Making predictions

Now we will use each of the regressors to make the 20 first predictions.

```python
xt = X[:20]
pred1 = reg1.predict(xt)
pred2 = reg2.predict(xt)
pred3 = reg3.predict(xt)
pred4 = ereg.predict(xt)
```

Plot the results

Finally, we will visualize the 20 predictions. The red stars show the average prediction made by `VotingRegressor`.

```python
plt.figure()  
plt.plot(pred1, 'gd', label='GradientBoostingRegressor')  
plt.plot(pred2, 'b^', label='RandomForestRegressor')  
plt.plot(pred3, 'ys', label='LinearRegression')  
plt.plot(pred4, 'r*', ms=10, label='VotingRegressor')

plt.tick_params(axis='x', which='both', bottom=False, top=False, labelbottom=False)  
plt.ylabel('predicted')  
plt.xlabel('training samples')  
plt.legend(loc="best")  
plt.title('Regressor predictions and their average')

plt.show()
```
6.11.4 Feature importances with forests of trees

This example shows the use of forests of trees to evaluate the importance of features on an artificial classification task. The red bars are the impurity-based feature importances of the forest, along with their inter-trees variability.

As expected, the plot suggests that 3 features are informative, while the remaining are not.

**Warning:** Impurity-based feature importances can be misleading for high cardinality features (many unique values). See `sklearn.inspection.permutation_importance` as an alternative.
Feature ranking:
1. feature 1 (0.295902)
2. feature 2 (0.208351)
3. feature 0 (0.177632)
4. feature 3 (0.047121)
5. feature 6 (0.046303)
6. feature 8 (0.046013)
7. feature 7 (0.045575)
8. feature 4 (0.044614)
9. feature 9 (0.044577)
10. feature 5 (0.043912)

```python
print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_classification
```
from sklearn.ensemble import ExtraTreesClassifier

# Build a classification task using 3 informative features
X, y = make_classification(n_samples=1000,
   n_features=10,
   n_informative=3,
   n_redundant=0,
   n_repeated=0,
   n_classes=2,
   random_state=0,
   shuffle=False)

# Build a forest and compute the impurity-based feature importances
forest = ExtraTreesClassifier(n_estimators=250,
   random_state=0)
forest.fit(X, y)
importances = forest.feature_importances_
std = np.std([tree.feature_importances_ for tree in forest.estimators_],
   axis=0)
indices = np.argsort(importances)[::-1]

# Print the feature ranking
for f in range(X.shape[1]):
   print("%d. feature %d (%f)" % (f + 1, indices[f], importances[indices[f]]))

# Plot the impurity-based feature importances of the forest
plt.figure()
plt.title("Feature importances")
plt.bar(range(X.shape[1]), importances[indices],
   color="r", yerr=std[indices], align="center")
plt.xticks(range(X.shape[1]), indices)
plt.xlim([-1, X.shape[1]])
plt.show()

Total running time of the script: ( 0 minutes 0.527 seconds)

6.11.5 IsolationForest example

An example using IsolationForest for anomaly detection.

The IsolationForest ‘isolates’ observations by randomly selecting a feature and then randomly selecting a split value between the maximum and minimum values of the selected feature.

Since recursive partitioning can be represented by a tree structure, the number of splittings required to isolate a sample is equivalent to the path length from the root node to the terminating node.

This path length, averaged over a forest of such random trees, is a measure of normality and our decision function.

Random partitioning produces noticeable shorter paths for anomalies. Hence, when a forest of random trees collectively produce shorter path lengths for particular samples, they are highly likely to be anomalies.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.ensemble import IsolationForest

rng = np.random.RandomState(42)

# Generate train data
X = 0.3 * rng.randn(100, 2)
X_train = np.r_[X + 2, X - 2]
# Generate some regular novel observations
X = 0.3 * rng.randn(20, 2)
X_test = np.r_[X + 2, X - 2]
# Generate some abnormal novel observations
X_outliers = rng.uniform(low=-4, high=4, size=(20, 2))

# fit the model
clf = IsolationForest(max_samples=100, random_state=rng)
clf.fit(X_train)
y_pred_train = clf.predict(X_train)
y_pred_test = clf.predict(X_test)
y_pred_outliers = clf.predict(X_outliers)

# plot the line, the samples, and the nearest vectors to the plane

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6.11.6 Monotonic Constraints

This example illustrates the effect of monotonic constraints on a gradient boosting estimator.

We build an artificial dataset where the target value is in general positively correlated with the first feature (with some random and non-random variations), and in general negatively correlated with the second feature.

By imposing a positive (increasing) or negative (decreasing) constraint on the features during the learning process, the estimator is able to properly follow the general trend instead of being subject to the variations.

This example was inspired by the XGBoost documentation.
```python
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor
from sklearn.inspection import plot_partial_dependence
import numpy as np
import matplotlib.pyplot as plt

print(__doc__)

rng = np.random.RandomState(0)

n_samples = 5000
f_0 = rng.rand(n_samples)  # positive correlation with y
f_1 = rng.rand(n_samples)  # negative correlation with y
X = np.c_[f_0, f_1]
noise = rng.normal(loc=0.0, scale=0.01, size=n_samples)
y = (5 * f_0 + np.sin(10 * np.pi * f_0) -
     5 * f_1 - np.cos(10 * np.pi * f_1) +
     noise)

fig, ax = plt.subplots()

# Without any constraint
gbdt = HistGradientBoostingRegressor()
```

---

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gbdt.fit(X, y)
disp = plot_partial_dependence(
    gbdt,
    X,
    features=[0, 1],
    line_kw="linewidth": 4, "label": "unconstrained", "color": "tab:blue"},
    ax=ax,
)

# With positive and negative constraints
gbd = HistGradientBoostingRegressor(monotonic_cst=[1, -1])
gbd.fit(X, y)

plot_partial_dependence(
    gbdt,
    X,
    features=[0, 1],
    feature_names=(
        "First feature
        Positive constraint",
        "Second feature
        Negative constraint",
    ),
    line_kw="linewidth": 4, "label": "constrained", "color": "tab:orange"},
    ax=disp.axes_,
)

for f_idx in (0, 1):
    disp.axes_[0, f_idx].plot(
        X[:, f_idx], y, "o", alpha=0.3, zorder=-1, color="tab:green"
    )
    disp.axes_[0, f_idx].set_ylim(-6, 6)

plt.legend()
fig.suptitle("Monotonic constraints illustration")
plt.show()

**Total running time of the script:** ( 0 minutes 0.890 seconds)

## 6.11.7 Plot the decision boundaries of a VotingClassifier

Plot the decision boundaries of a *VotingClassifier* for two features of the Iris dataset.

Plot the class probabilities of the first sample in a toy dataset predicted by three different classifiers and averaged by the *VotingClassifier*.

First, three exemplary classifiers are initialized (*DecisionTreeClassifier*, *KNeighborsClassifier*, and *SVC*) and used to initialize a soft-voting *VotingClassifier* with weights [2, 1, 2], which means that the predicted probabilities of the *DecisionTreeClassifier* and *SVC* each count 2 times as much as the weights of the *KNeighborsClassifier* classifier when the averaged probability is calculated.
print(__doc__)

from itertools import product
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.tree import DecisionTreeClassifier
from sklearn.neighbors import KNeighborsClassifier
from sklearn.svm import SVC
from sklearn.ensemble import VotingClassifier

# Loading some example data
iris = datasets.load_iris()
X = iris.data[:, [0, 2]]
y = iris.target

# Training classifiers
clf1 = DecisionTreeClassifier(max_depth=4)
clf2 = KNeighborsClassifier(n_neighbors=7)
clf3 = SVC(gamma=.1, kernel='rbf', probability=True)
eclf = VotingClassifier(estimators=[('dt', clf1), ('knn', clf2),
(continues on next page)
('svc', clf3)],
voting='soft', weights=[2, 1, 2])

clf1.fit(X, y)
clf2.fit(X, y)
clf3.fit(X, y)
eclf.fit(X, y)

# Plotting decision regions
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, 0.1),
                     np.arange(y_min, y_max, 0.1))

f, axarr = plt.subplots(2, 2, sharex='col', sharey='row', figsize=(10, 8))

for idx, clf, tt in zip(product([0, 1], [0, 1]),
                        [clf1, clf2, clf3, eclf],
                        ['Decision Tree (depth=4)', 'KNN (k=7)',
                         'Kernel SVM', 'Soft Voting']):

    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)

    axarr[idx[0], idx[1]].contourf(xx, yy, Z, alpha=0.4)
    axarr[idx[0], idx[1]].scatter(X[:, 0], X[:, 1], c=y,
                                   s=20, edgecolor='k')

    axarr[idx[0], idx[1]].set_title(tt)

plt.show()

Total running time of the script: ( 0 minutes 0.515 seconds)

6.11.8 Comparing random forests and the multi-output meta estimator

An example to compare multi-output regression with random forest and the multioutput.MultiOutputRegressor meta-estimator.

This example illustrates the use of the multioutput.MultiOutputRegressor meta-estimator to perform multi-output regression. A random forest regressor is used, which supports multi-output regression natively, so the results can be compared.

The random forest regressor will only ever predict values within the range of observations or closer to zero for each of the targets. As a result the predictions are biased towards the centre of the circle.

Using a single underlying feature the model learns both the x and y coordinate as output.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.ensemble import RandomForestRegressor
from sklearn.model_selection import train_test_split
from sklearn.multioutput import MultiOutputRegressor

# Create a random dataset
rng = np.random.RandomState(1)
X = np.sort(200 * rng.rand(600, 1) - 100, axis=0)
y = np.array([np.pi * np.sin(X).ravel(), np.pi * np.cos(X).ravel()]).T
y += (0.5 - rng.rand(*y.shape))

X_train, X_test, y_train, y_test = train_test_split(X, y, train_size=400, test_size=200, random_state=4)

max_depth = 30
regr_multirf = MultiOutputRegressor(RandomForestRegressor(n_estimators=100,
max_depth=max_depth, n_jobs=-1))

# Author: Tim Head <betatim@gmail.com>
# License: BSD 3 clause
regr_multirf.fit(X_train, y_train, random_state=0))
regr_rf = RandomForestRegressor(n_estimators=100, max_depth=max_depth, random_state=2)
regr_rf.fit(X_train, y_train)

# Predict on new data
y_multirf = regr_multirf.predict(X_test)
y_rf = regr_rf.predict(X_test)

# Plot the results
plt.figure()
s = 50
a = 0.4
plt.scatter(y_test[:, 0], y_test[:, 1], edgecolor='k', c="navy", s=s, marker="s", alpha=a, label="Data")
plt.scatter(y_multirf[:, 0], y_multirf[:, 1], edgecolor='k', c="cornflowerblue", s=s, alpha=a,
            label="Multi RF score=%.2f" % regr_multirf.score(X_test, y_test))
plt.scatter(y_rf[:, 0], y_rf[:, 1], edgecolor='k', c="c", s=s, marker="^", alpha=a,
            label="RF score=%.2f" % regr_rf.score(X_test, y_test))
plt.xlim([-6, 6])
plt.ylim([-6, 6])
plt.xlabel("target 1")
plt.ylabel("target 2")
plt.title("Comparing random forests and the multi-output meta estimator")
plt.legend()
plt.show()

Total running time of the script: ( 0 minutes 0.646 seconds)

6.11.9 Prediction Intervals for Gradient Boosting Regression

This example shows how quantile regression can be used to create prediction intervals.
import numpy as np
import matplotlib.pyplot as plt

from sklearn.ensemble import GradientBoostingRegressor

np.random.seed(1)

def f(x):
    """The function to predict.""
    return x * np.sin(x)

# First the noiseless case
X = np.atleast_2d(np.random.uniform(0, 10.0, size=100)).T
X = X.astype(np.float32)

# Observations
y = f(X).ravel()

dy = 1.5 + 1.0 * np.random.random(y.shape)
noise = np.random.normal(0, dy)
y += noise
y = y.astype(np.float32)

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Mesh the input space for evaluations of the real function, the prediction and its MSE

```python
xx = np.atleast_2d(np.linspace(0, 10, 1000)).T
xx = xx.astype(np.float32)
alpha = 0.95

clf = GradientBoostingRegressor(loss='quantile', alpha=alpha,
                                 n_estimators=250, max_depth=3,
                                 learning_rate=.1, min_samples_leaf=9,
                                 min_samples_split=9)

clf.fit(X, y)

# Make the prediction on the meshed x-axis
y_upper = clf.predict(xx)

clf.set_params(alpha=1.0 - alpha)
clf.fit(X, y)

# Make the prediction on the meshed x-axis
y_lower = clf.predict(xx)

clf.set_params(loss='ls')
clf.fit(X, y)

# Make the prediction on the meshed x-axis
y_pred = clf.predict(xx)

# Plot the function, the prediction and the 95% confidence interval based on the MSE
fig = plt.figure()
plt.plot(xx, f(xx), 'g:', label=r'$f(x) = x\sin(x)$')
plt.plot(X, y, 'b.', markersize=10, label=u'Observations')
plt.plot(xx, y_pred, 'r-', label=u'Prediction')
plt.plot(xx, y_upper, 'k-')
plt.plot(xx, y_lower, 'k-')
plt.fill(np.concatenate([xx, xx[::-1]]),
         np.concatenate([y_upper, y_lower[::-1]]),
         alpha=.5, fc='b', ec='None', label='95% prediction interval')
plt.xlabel('$x$')
plt.ylabel('$f(x)$')
plt.ylim(-10, 20)
plt.legend(loc='upper left')
plt.show()
```

Total running time of the script: (0 minutes 0.804 seconds)
6.11.10 Gradient Boosting regularization

Illustration of the effect of different regularization strategies for Gradient Boosting. The example is taken from Hastie et al 2009¹.

The loss function used is binomial deviance. Regularization via shrinkage (learning_rate < 1.0) improves performance considerably. In combination with shrinkage, stochastic gradient boosting (subsample < 1.0) can produce more accurate models by reducing the variance via bagging. Subsampling without shrinkage usually does poorly. Another strategy to reduce the variance is by subsampling the features analogous to the random splits in Random Forests (via the max_features parameter).

---

X, y = datasets.make_hastie_10_2(n_samples=12000, random_state=1)
X = X.astype(np.float32)

# map labels from {-1, 1} to {0, 1}
labels, y = np.unique(y, return_inverse=True)

X_train, X_test = X[:2000], X[2000:]
y_train, y_test = y[:2000], y[2000:]

original_params = {'n_estimators': 1000, 'max_leaf_nodes': 4, 'max_depth': None, 'random_state': 2, 'min_samples_split': 5}

plt.figure()
for label, color, setting in [('No shrinkage', 'orange', {'learning_rate': 1.0, 'subsample': 1.0}), ('learning_rate=0.1', 'turquoise', {'learning_rate': 0.1, 'subsample': 1.0}), ('subsample=0.5', 'blue', {'learning_rate': 1.0, 'subsample': 0.5}), ('learning_rate=0.1, subsample=0.5', 'gray', {'learning_rate': 0.1, 'subsample': 0.5}), ('learning_rate=0.1, max_features=2', 'magenta', {'learning_rate': 0.1, 'max_features': 2})]:
    params = dict(original_params)
    params.update(setting)
    clf = ensemble.GradientBoostingClassifier(**params)
    clf.fit(X_train, y_train)
    # compute test set deviance
    test_deviance = np.zeros((params['n_estimators'],), dtype=np.float64)
    for i, y_pred in enumerate(clf.staged_decision_function(X_test)):
        # clf.loss_ assumes that y_test[i] in {0, 1}
        test_deviance[i] = clf.loss_(y_test, y_pred)
    plt.plot((np.arange(test_deviance.shape[0]) + 1)[::5], test_deviance[::5], '-', color=color, label=label)
plt.legend(loc='upper left')
plt.xlabel('Boosting Iterations')
plt.ylabel('Test Set Deviance')
plt.show()

Total running time of the script: ( 0 minutes 27.050 seconds)
6.11.11 Plot class probabilities calculated by the VotingClassifier

Plot the class probabilities of the first sample in a toy dataset predicted by three different classifiers and averaged by the VotingClassifier.

First, three exemplary classifiers are initialized (LogisticRegression, GaussianNB, and RandomForestClassifier) and used to initialize a soft-voting VotingClassifier with weights [1, 1, 5], which means that the predicted probabilities of the RandomForestClassifier count 5 times as much as the weights of the other classifiers when the averaged probability is calculated.

To visualize the probability weighting, we fit each classifier on the training set and plot the predicted class probabilities for the first sample in this example dataset.

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt

from sklearn.linear_model import LogisticRegression
from sklearn.naive_bayes import GaussianNB
from sklearn.ensemble import RandomForestClassifier
from sklearn.ensemble import VotingClassifier

clf1 = LogisticRegression(max_iter=1000, random_state=123)
clf2 = RandomForestClassifier(n_estimators=100, random_state=123)
clf3 = GaussianNB()
```

(continues on next page)
X = np.array([[-1.0, -1.0], [-1.2, -1.4], [-3.4, -2.2], [1.1, 1.2]])

y = np.array([1, 1, 2, 2])

eclf = VotingClassifier(estimators=[('lr', clf1), ('rf', clf2), ('gnb', clf3)],
    voting='soft',
    weights=[1, 1, 5])

# predict class probabilities for all classifiers
probas = [c.fit(X, y).predict_proba(X) for c in (clf1, clf2, clf3, eclf)]

# get class probabilities for the first sample in the dataset
class1_1 = [pr[0, 0] for pr in probas]
class2_1 = [pr[0, 1] for pr in probas]

# plotting
N = 4  # number of groups
ind = np.arange(N)  # group positions
width = 0.35  # bar width

fig, ax = plt.subplots()

# bars for classifier 1-3
p1 = ax.bar(ind, np.hstack((class1_1[:-1], [0])), width,
    color='green', edgecolor='k')
p2 = ax.bar(ind + width, np.hstack((class2_1[:-1], [0])), width,
    color='lightgreen', edgecolor='k')

# bars for VotingClassifier
p3 = ax.bar(ind, [0, 0, 0, class1_1[-1]], width,
    color='blue', edgecolor='k')
p4 = ax.bar(ind + width, [0, 0, 0, class2_1[-1]], width,
    color='steelblue', edgecolor='k')

# plot annotations
plt.axvline(2.8, color='k', linestyle='dashed')
ax.set_xticks(ind + width)
ax.set_xticklabels(['LogisticRegression
weight 1',
    'GaussianNB
weight 1',
    'RandomForestClassifier
weight 5',
    'VotingClassifier
(average probabilities)'],
    rotation=40,
    ha='right')
plt.ylim([0, 1])
plt.title('Class probabilities for sample 1 by different classifiers')
plt.legend([p1[0], p2[0]], ['class 1', 'class 2'], loc='upper left')
plt.tight_layout()
plt.show()
6.11.12 Gradient Boosting regression

This example demonstrates Gradient Boosting to produce a predictive model from an ensemble of weak predictive models. Gradient boosting can be used for regression and classification problems. Here, we will train a model to tackle a diabetes regression task. We will obtain the results from GradientBoostingRegressor with least squares loss and 500 regression trees of depth 4.

Note: For larger datasets (n_samples >= 10000), please refer to HistGradientBoostingRegressor.

```python
print(__doc__)

# Author: Peter Prettenhofer <peter.prettenhofer@gmail.com>
# Maria Telenczuk <https://github.com/maikia>
# Katrina Ni <https://github.com/nilichen>
#
# License: BSD 3 clause

import matplotlib.pyplot as plt
import numpy as np
from sklearn import datasets, ensemble
from sklearn.inspection import permutation_importance
from sklearn.metrics import mean_squared_error
from sklearn.model_selection import train_test_split

Load the data

First we need to load the data.

diabetes = datasets.load_diabetes()
X, y = diabetes.data, diabetes.target

Data preprocessing

Next, we will split our dataset to use 90% for training and leave the rest for testing. We will also set the regression model parameters. You can play with these parameters to see how the results change.
n_estimators : the number of boosting stages that will be performed. Later, we will plot deviance against boosting iterations.
max_depth : limits the number of nodes in the tree. The best value depends on the interaction of the input variables.
min_samples_split : the minimum number of samples required to split an internal node.
learning_rate : how much the contribution of each tree will shrink.
loss : loss function to optimize. The least squares function is used in this case however, there are many other options (see GradientBoostingRegressor).

X_train, X_test, y_train, y_test = train_test_split(    X, y, test_size=0.1, random_state=13)

params = {'n_estimators': 500,
          'max_depth': 4,
          'min_samples_split': 5,
          'learning_rate': 0.01,
          'loss': 'ls'}
Fit regression model

Now we will initiate the gradient boosting regressors and fit it with our training data. Let’s also look and the mean squared error on the test data.

```python
def fit_regression_model(reg, X_train, y_train, X_test, y_test):
    reg = ensemble.GradientBoostingRegressor(**params)
    reg.fit(X_train, y_train)
    mse = mean_squared_error(y_test, reg.predict(X_test))
    print(f"The mean squared error (MSE) on test set: {mse:.4f}\n")
```

```python
reg = ensemble.GradientBoostingRegressor(**params)
reg.fit(X_train, y_train)
 mse = mean_squared_error(y_test, reg.predict(X_test))
print("The mean squared error (MSE) on test set: {:.4f}\n".format(mse))
```

Out:

```
The mean squared error (MSE) on test set: 3017.9419
```

Plot training deviance

Finally, we will visualize the results. To do that we will first compute the test set deviance and then plot it against boosting iterations.

```python
def plot_training_deviance(reg, X_train, y_train, X_test, y_test, params):
    test_score = np.zeros((params['n_estimators'],), dtype=np.float64)
    for i, y_pred in enumerate(reg.staged_predict(X_test)):
        test_score[i] = reg.loss_(y_test, y_pred)
    fig = plt.figure(figsize=(6, 6))
    plt.subplot(1, 1, 1)
    plt.title('Deviance')
    plt.plot(np.arange(params['n_estimators']) + 1, reg.train_score_, 'b-'
             , label='Training Set Deviance')
    plt.plot(np.arange(params['n_estimators']) + 1, test_score, 'r-
             , label='Test Set Deviance')
    plt.legend(loc='upper right')
    plt.xlabel('Boosting Iterations')
    plt.ylabel('Deviance')
    plt.tight_layout()
    plt.show()
```

```python
test_score = np.zeros((params['n_estimators'],), dtype=np.float64)
for i, y_pred in enumerate(reg.staged_predict(X_test)):
    test_score[i] = reg.loss_(y_test, y_pred)
fig = plt.figure(figsize=(6, 6))
plt.subplot(1, 1, 1)
plt.title('Deviance')
plt.plot(np.arange(params['n_estimators']) + 1, reg.train_score_, 'b-'
         , label='Training Set Deviance')
plt.plot(np.arange(params['n_estimators']) + 1, test_score, 'r-
         , label='Test Set Deviance')
plt.legend(loc='upper right')
plt.xlabel('Boosting Iterations')
plt.ylabel('Deviance')
plt.tight_layout()
plt.show()
```
Plot feature importance

Careful, impurity-based feature importances can be misleading for high cardinality features (many unique values). As an alternative, the permutation importances of `reg` can be computed on a held out test set. See `Permutation feature importance` for more details.

For this example, the impurity-based and permutation methods identify the same 2 strongly predictive features but not in the same order. The third most predictive feature, “bp”, is also the same for the 2 methods. The remaining features are less predictive and the error bars of the permutation plot show that they overlap with 0.

```python
feature_importance = reg.feature_importances_
sorted_idx = np.argsort(feature_importance)
pos = np.arange(sorted_idx.shape[0]) + .5
fig = plt.figure(figsize=(12, 6))
plt.subplot(1, 2, 1)
plt.barh(pos, feature_importance[sorted_idx], align='center')
```

(continues on next page)
plt.yticks(pos, np.array(diabetes.feature_names)[sorted_idx])
plt.title('Feature Importance (MDI)')

result = permutation_importance(reg, X_test, y_test, n_repeats=10,
                                 random_state=42, n_jobs=2)
sorted_idx = result.importances_mean.argsort()
plt.subplot(1, 2, 2)
plt.boxplot(result.importances[sorted_idx].T,
            vert=False, labels=np.array(diabetes.feature_names)[sorted_idx])
plt.title("Permutation Importance (test set)")
fig.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 1.988 seconds)

6.11.13 OOB Errors for Random Forests

The RandomForestClassifier is trained using bootstrap aggregation, where each new tree is fit from a bootstrap sample of the training observations $z_i = (x_i, y_i)$. The out-of-bag (OOB) error is the average error for each $z_i$ calculated using predictions from the trees that do not contain $z_i$ in their respective bootstrap sample. This allows the RandomForestClassifier to be fit and validated whilst being trained.

The example below demonstrates how the OOB error can be measured at the addition of each new tree during training. The resulting plot allows a practitioner to approximate a suitable value of n_estimators at which the error stabilizes.

---

import matplotlib.pyplot as plt
from collections import OrderedDict
from sklearn.datasets import make_classification
from sklearn.ensemble import RandomForestClassifier

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# License: BSD 3 Clause

print(__doc__)

RANDOM_STATE = 123

# Generate a binary classification dataset.
X, y = make_classification(n_samples=500, n_features=25,
                          n_clusters_per_class=1, n_informative=15,
                          random_state=RANDOM_STATE)

# NOTE: Setting the `warm_start` construction parameter to `True` disables
# support for parallelized ensembles but is necessary for tracking the OOB
# error trajectory during training.
ensemble_clfs = [
(continues on next page)
# Map a classifier name to a list of (<n_estimators>, <error rate>) pairs.
error_rate = OrderedDict((label, []) for label, _ in ensemble_clfs)

# Range of `n_estimators` values to explore.
min_estimators = 15
max_estimators = 175

for label, clf in ensemble_clfs:
    for i in range(min_estimators, max_estimators + 1):
        clf.set_params(n_estimators=i)
        clf.fit(X, y)

        # Record the OOB error for each `n_estimators=i` setting.
        oob_error = 1 - clf.oob_score_
        error_rate[label].append((i, oob_error))

# Generate the "OOB error rate" vs. "n_estimators" plot.
for label, clf_err in error_rate.items():
    xs, ys = zip(*clf_err)
    plt.plot(xs, ys, label=label)

plt.xlim(min_estimators, max_estimators)
plt.xlabel("n_estimators")
plt.ylabel("OOB error rate")
plt.legend(loc="upper right")
plt.show()

Total running time of the script: (0 minutes 18.102 seconds)

### 6.11.14 Two-class AdaBoost

This example fits an AdaBoosted decision stump on a non-linearly separable classification dataset composed of two “Gaussian quantiles” clusters (see sklearn.datasets.make_gaussian_quantiles) and plots the decision boundary and decision scores. The distributions of decision scores are shown separately for samples of class A and B. The predicted class label for each sample is determined by the sign of the decision score. Samples with decision scores greater than zero are classified as B, and are otherwise classified as A. The magnitude of a decision score determines the degree of likeness with the predicted class label. Additionally, a new dataset could be constructed containing a desired purity of class B, for example, by only selecting samples with a decision score above some value.
# Construct dataset
X1, y1 = make_gaussian_quantiles(cov=2.,
    n_samples=200, n_features=2,
    n_classes=2, random_state=1)
X2, y2 = make_gaussian_quantiles(mean=(3, 3), cov=1.5,
    n_samples=300, n_features=2,
    n_classes=2, random_state=1)
X = np.concatenate((X1, X2))
y = np.concatenate((y1, -y2 + 1))

# Create and fit an AdaBoosted decision tree
bdt = AdaBoostClassifier(DecisionTreeClassifier(max_depth=1),
    algorithm="SAMME",
    n_estimators=200)
bdt.fit(X, y)

plot_colors = "br"
plot_step = 0.02
class_names = "AB"

plt.figure(figsize=(10, 5))

6.11. Ensemble methods
# Plot the decision boundaries
plt.subplot(121)
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, plot_step),
                     np.arange(y_min, y_max, plot_step))
Z = bdt.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
cs = plt.contourf(xx, yy, Z, cmap=plt.cm.Paired)
plt.axis("tight")

# Plot the training points
for i, n, c in zip(range(2), class_names, plot_colors):
    idx = np.where(y == i)
    plt.scatter(X[idx, 0], X[idx, 1], c=c, cmap=plt.cm.Paired,
                s=20, edgecolor='k',
                label="Class %s" % n)
plt.xlim(x_min, x_max)
plt.ylim(y_min, y_max)
plt.legend(loc='upper right')
plt.xlabel('x')
plt.ylabel('y')
plt.title('Decision Boundary')

# Plot the two-class decision scores
twoclass_output = bdt.decision_function(X)
plot_range = (twoclass_output.min(), twoclass_output.max())
plt.subplot(122)
for i, n, c in zip(range(2), class_names, plot_colors):
    plt.hist(twoclass_output[y == i], bins=10,
             range=plot_range, facecolor=c,
             label='Class %s' % n,
             alpha=.5,
             edgecolor='k')
x1, x2, y1, y2 = plt.axis()
plt.axis((x1, x2, y1, y2 * 1.2))
plt.legend(loc='upper right')
plt.xlabel('Score')
plt.ylabel('Samples')
plt.title('Decision Scores')

plt.tight_layout()
plt.subplots_adjust(wspace=0.35)
plt.show()

Total running time of the script: ( 0 minutes 2.858 seconds)
6.11.15 Hashing feature transformation using Totally Random Trees

RandomTreesEmbedding provides a way to map data to a very high-dimensional, sparse representation, which might be beneficial for classification. The mapping is completely unsupervised and very efficient.

This example visualizes the partitions given by several trees and shows how the transformation can also be used for non-linear dimensionality reduction or non-linear classification.

Points that are neighboring often share the same leaf of a tree and therefore share large parts of their hashed representation. This allows to separate two concentric circles simply based on the principal components of the transformed data with truncated SVD.

In high-dimensional spaces, linear classifiers often achieve excellent accuracy. For sparse binary data, BernoulliNB is particularly well-suited. The bottom row compares the decision boundary obtained by BernoulliNB in the transformed space with an ExtraTreesClassifier forests learned on the original data.

Out:

/home/circleci/project/examples/ensemble/plot_random_forest_embedding.py:85:   MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions as C is deprecated since 3.3. Either specify the corners of the quadrilaterals with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[ 'pcolor.shading']. This will become an error two minor releases later.
import numpy as np
import matplotlib.pyplot as plt

from sklearn.datasets import make_circles
from sklearn.ensemble import RandomTreesEmbedding, ExtraTreesClassifier
from sklearn.decomposition import TruncatedSVD
from sklearn.naive_bayes import BernoulliNB

# make a synthetic dataset
X, y = make_circles(factor=0.5, random_state=0, noise=0.05)

# use RandomTreesEmbedding to transform data
hasher = RandomTreesEmbedding(n_estimators=10, random_state=0, max_depth=3)
X_transformed = hasher.fit_transform(X)

# Visualize result after dimensionality reduction using truncated SVD
svd = TruncatedSVD(n_components=2)
X_reduced = svd.fit_transform(X_transformed)

# Learn a Naive Bayes classifier on the transformed data
nb = BernoulliNB()
nb.fit(X_transformed, y)

# Learn an ExtraTreesClassifier for comparison
trees = ExtraTreesClassifier(max_depth=3, n_estimators=10, random_state=0)
trees.fit(X, y)

# scatter plot of original and reduced data
fig = plt.figure(figsize=(9, 8))

ax = fig.subplot(221)
ax.scatter(X[:, 0], X[:, 1], c=y, s=50, edgecolor='k')
ax.set_title("Original Data (2d)")
ax.set_xticks([])
ax.set_yticks([])

ax = fig.subplot(222)
ax.scatter(X_reduced[:, 0], X_reduced[:, 1], c=y, s=50, edgecolor='k')
ax.set_title("Truncated SVD reduction (2d) of transformed data (%dd)\nX_transformed.shape[1]"

ax.set_xticks([])
# Plot the decision in original space. For that, we will assign a color
# to each point in the mesh [x_min, x_max]x[y_min, y_max].

h = .01
x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))

# transform grid using RandomTreesEmbedding
transformed_grid = hasher.transform(np.c_[xx.ravel(), yy.ravel()])
y_grid_pred = nb.predict_proba(transformed_grid)[:, 1]

ax = plt.subplot(223)
ax.set_title("Naive Bayes on Transformed data")
ax.pcolormesh(xx, yy, y_grid_pred.reshape(xx.shape))
ax.scatter(X[:, 0], X[:, 1], c=y, s=50, edgecolor='k')
ax.set_ylim(-1.4, 1.4)
ax.set_xlim(-1.4, 1.4)
ax.set_xticks(())
ax.set_yticks(())

# transform grid using ExtraTreesClassifier
y_grid_pred = trees.predict_proba(np.c_[xx.ravel(), yy.ravel()])[:, 1]

ax = plt.subplot(224)
ax.set_title("ExtraTrees predictions")
ax.pcolormesh(xx, yy, y_grid_pred.reshape(xx.shape))
ax.scatter(X[:, 0], X[:, 1], c=y, s=50, edgecolor='k')
ax.set_ylim(-1.4, 1.4)
ax.set_xlim(-1.4, 1.4)
ax.set_xticks(())
ax.set_yticks(())

plt.tight_layout()
plt.show()
import matplotlib.pyplot as plt

from sklearn.datasets import make_gaussian_quantiles
from sklearn.ensemble import AdaBoostClassifier
from sklearn.metrics import accuracy_score
from sklearn.tree import DecisionTreeClassifier

X, y = make_gaussian_quantiles(n_samples=13000, n_features=10,
                               n_classes=3, random_state=1)

n_split = 3000
X_train, X_test = X[:n_split], X[n_split:]
y_train, y_test = y[:n_split], y[n_split:]

bdt_real = AdaBoostClassifier(
    DecisionTreeClassifier(max_depth=2),
    n_estimators=600,
    learning_rate=1)

bdt_discrete = AdaBoostClassifier(
    DecisionTreeClassifier(max_depth=2),
    n_estimators=600,
    learning_rate=1.5,
    algorithm="SAMME")

bdt_real.fit(X_train, y_train)
bdt_discrete.fit(X_train, y_train)

real_test_errors = []
discrete_test_errors = []

for real_test_predict, discrete_train_predict in zip(
    bdt_real.staged_predict(X_test), bdt_discrete.staged_predict(X_test)):
    real_test_errors.append(1. - accuracy_score(real_test_predict, y_test))
(continues on next page)
discrete_test_errors.append(1. - accuracy_score(discrete_train_predict, y_test))

n_trees_discrete = len(bdt_discrete)
n_trees_real = len(bdt_real)

# Boosting might terminate early, but the following arrays are always
# n_estimators long. We crop them to the actual number of trees here:
 discrete_estimator_errors = bdt_discrete.estimator_errors_[:n_trees_discrete]
 real_estimator_errors = bdt_real.estimator_errors_[:n_trees_real]
 discrete_estimator_weights = bdt_discrete.estimator_weights_[:n_trees_discrete]

plt.figure(figsize=(15, 5))
plt.subplot(131)
plt.plot(range(1, n_trees_discrete + 1),
         discrete_test_errors, c='black', label='SAMME')
plt.plot(range(1, n_trees_real + 1),
         real_test_errors, c='black', linestyle='dashed', label='SAMME.R')
plt.legend()
plt.ylim(0.18, 0.62)
plt.ylabel('Test Error')
plt.xlabel('Number of Trees')
plt.subplot(132)
plt.plot(range(1, n_trees_discrete + 1), discrete_estimator_errors,
         'b', label='SAMME', alpha=.5)
plt.plot(range(1, n_trees_real + 1), real_estimator_errors,
         'r', label='SAMME.R', alpha=.5)
plt.legend()
plt.ylabel('Error')
plt.xlabel('Number of Trees')
plt.ylim((.2, 
         max(real_estimator_errors.max(),
             discrete_estimator_errors.max()) * 1.2))
plt.xlim((-20, len(bdt_discrete) + 20))
plt.subplot(133)
plt.plot(range(1, n_trees_discrete + 1), discrete_estimator_weights,
         'b', label='SAMME')
plt.legend()
plt.ylabel('Weight')
plt.xlabel('Number of Trees')
plt.ylim((0, discrete_estimator_weights.max() * 1.2))
plt.xlim((-20, n_trees_discrete + 20))

# prevent overlapping y-axis labels
plt.subplots_adjust(wspace=0.25)
plt.show()
6.11.17 Discrete versus Real AdaBoost

This example is based on Figure 10.2 from Hastie et al 2009\(^1\) and illustrates the difference in performance between the discrete SAMME\(^2\) boosting algorithm and real SAMME.R boosting algorithm. Both algorithms are evaluated on a binary classification task where the target $Y$ is a non-linear function of 10 input features.

Discrete SAMME AdaBoost adapts based on errors in predicted class labels whereas real SAMME.R uses the predicted class probabilities.

![Graph showing error rate vs. n_estimators](image)

```python
print(__doc__)

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#
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn import datasets
from sklearn.tree import DecisionTreeClassifier

```


from sklearn.metrics import zero_one_loss
from sklearn.ensemble import AdaBoostClassifier

n_estimators = 400
# A learning rate of 1. may not be optimal for both SAMME and SAMME.R
learning_rate = 1.

X, y = datasets.make_hastie_10_2(n_samples=12000, random_state=1)
X_test, y_test = X[2000:], y[2000:]
X_train, y_train = X[:2000], y[:2000]

dt_stump = DecisionTreeClassifier(max_depth=1, min_samples_leaf=1)
dt_stump.fit(X_train, y_train)
dt_stump_err = 1.0 - dt_stump.score(X_test, y_test)

dt = DecisionTreeClassifier(max_depth=9, min_samples_leaf=1)
dt.fit(X_train, y_train)
dt_err = 1.0 - dt.score(X_test, y_test)

ada_discrete = AdaBoostClassifier(base_estimator=dt_stump, learning_rate=learning_rate, n_estimators=n_estimators, algorithm="SAMME")
ada_discrete.fit(X_train, y_train)

ada_real = AdaBoostClassifier(base_estimator=dt_stump, learning_rate=learning_rate, n_estimators=n_estimators, algorithm="SAMME.R")
ada_real.fit(X_train, y_train)

fig = plt.figure()
ax = fig.add_subplot(111)
ax.plot([1, n_estimators], [dt_stump_err] * 2, 'k-', label='Decision Stump Error')
ax.plot([1, n_estimators], [dt_err] * 2, 'k--', label='Decision Tree Error')

ada_discrete_err = np.zeros((n_estimators,))
for i, y_pred in enumerate(ada_discrete.staged_predict(X_test)):
    ada_discrete_err[i] = zero_one_loss(y_pred, y_test)

ada_discrete_err_train = np.zeros((n_estimators,))
for i, y_pred in enumerate(ada_discrete.staged_predict(X_train)):
    ada_discrete_err_train[i] = zero_one_loss(y_pred, y_train)

ada_real_err = np.zeros((n_estimators,))
for i, y_pred in enumerate(ada_real.staged_predict(X_test)):
    ada_real_err[i] = zero_one_loss(y_pred, y_test)

ada_real_err_train = np.zeros((n_estimators,))
for i, y_pred in enumerate(ada_real.staged_predict(X_train)):


```python
ada_real_err_train[i] = zero_one_loss(y_pred, y_train)
ax.plot(np.arange(n_estimators) + 1, ada_discrete_err,
       label='Discrete AdaBoost Test Error',
       color='red')
ax.plot(np.arange(n_estimators) + 1, ada_discrete_err_train,
       label='Discrete AdaBoost Train Error',
       color='blue')
ax.plot(np.arange(n_estimators) + 1, ada_real_err,
       label='Real AdaBoost Test Error',
       color='orange')
ax.plot(np.arange(n_estimators) + 1, ada_real_err_train,
       label='Real AdaBoost Train Error',
       color='green')
ax.set_ylim((0.0, 0.5))
ax.set_xlabel('n_estimators')
ax.set_ylabel('error rate')
leg = ax.legend(loc='upper right', fancybox=True)
leg.get_frame().set_alpha(0.7)
plt.show()
```

Total running time of the script: (0 minutes 5.602 seconds)

6.11.18 Early stopping of Gradient Boosting

Gradient boosting is an ensembling technique where several weak learners (regression trees) are combined to yield a powerful single model, in an iterative fashion.

Early stopping support in Gradient Boosting enables us to find the least number of iterations which is sufficient to build a model that generalizes well to unseen data.

The concept of early stopping is simple. We specify a validation fraction which denotes the fraction of the whole dataset that will be kept aside from training to assess the validation loss of the model. The gradient boosting model is trained using the training set and evaluated using the validation set. When each additional stage of regression tree is added, the validation set is used to score the model. This is continued until the scores of the model in the last n_iter_no_change stages do not improve by at least tol. After that the model is considered to have converged and further addition of stages is “stopped early”.

The number of stages of the final model is available at the attribute n_estimators_

This example illustrates how the early stopping can be used in the GradientBoostingClassifier model to achieve almost the same accuracy as compared to a model built without early stopping using many fewer estimators. This can significantly reduce training time, memory usage and prediction latency.

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```python
import time
import numpy as np
import matplotlib.pyplot as plt
```

(continues on next page)
from sklearn import ensemble
from sklearn import datasets
from sklearn.model_selection import train_test_split

print(__doc__)

data_list = [datasets.load_iris(), datasets.load_digits()]
data_list = [(d.data, d.target) for d in data_list]
data_list += [datasets.make_hastie_10_2()]
names = ['Iris Data', 'Digits Data', 'Hastie Data']

n_gb = []
score_gb = []
time_gb = []
n_gbes = []
score_gbes = []
time_gbes = []

n_estimators = 500

for X, y in data_list:
    X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2,
                                      random_state=0)

    gb = ensemble.GradientBoostingClassifier(n_estimators=n_estimators,
                                      random_state=0)
    gb.fit(X_train, y_train)
    time_gb.append(time.time() - start)

    gbes = ensemble.GradientBoostingClassifier(n_estimators=n_estimators,
                                      validation_fraction=0.2,
                                      n_iter_no_change=5, tol=0.01,
                                      random_state=0)
    gbes.fit(X_train, y_train)
    time_gbes.append(time.time() - start)

    score_gb.append(gb.score(X_test, y_test))
    score_gbes.append(gbes.score(X_test, y_test))

    n_gb.append(gb.n_estimators_)
    n_gbes.append(gbes.n_estimators_)

bar_width = 0.2
n = len(data_list)
index = np.arange(0, n * bar_width, bar_width) * 2.5
index = index[0:n]
Compare scores with and without early stopping

```python
plt.figure(figsize=(9, 5))
bar1 = plt.bar(index, score_gb, bar_width, label='Without early stopping', color='crimson')
bar2 = plt.bar(index + bar_width, score_gbes, bar_width, label='With early stopping', color='coral')
plt.xticks(index + bar_width, names)
plt.yticks(np.arange(0, 1.3, 0.1))
def autolabel(rects, n_estimators):
    """
    Attach a text label above each bar displaying n_estimators of each model
    """
    for i, rect in enumerate(rects):
        plt.text(rect.get_x() + rect.get_width() / 2., 1.05 * rect.get_height(), 'n_est=%d' % n_estimators[i],
            ha='center', va='bottom')
autolabel(bar1, n_gb)
autolabel(bar2, n_gbes)
plt.ylim([0, 1.3])
plt.legend(loc='best')
plt.grid(True)
plt.xlabel('Datasets')
plt.ylabel('Test score')
plt.show()
```
**Compare fit times with and without early stopping**

```python
plt.figure(figsize=(9, 5))

bar1 = plt.bar(index, time_gb, bar_width, label='Without early stopping',
                color='crimson')
bar2 = plt.bar(index + bar_width, time_gbes, bar_width,
                label='With early stopping', color='coral')

max_y = np.amax(np.maximum(time_gb, time_gbes))

plt.xticks(index + bar_width, names)
plt.yticks(np.linspace(0, 1.3 * max_y, 13))

autolabel(bar1, n_gb)
autolabel(bar2, n_gbes)

plt.ylim([0, 1.3 * max_y])
plt.legend(loc='best')
plt.grid(True)
plt.xlabel('Datasets')
plt.ylabel('Fit Time')
plt.show()
```
6.11.19 Feature transformations with ensembles of trees

Transform your features into a higher dimensional, sparse space. Then train a linear model on these features.

First fit an ensemble of trees (totally random trees, a random forest, or gradient boosted trees) on the training set. Then each leaf of each tree in the ensemble is assigned a fixed arbitrary feature index in a new feature space. These leaf indices are then encoded in a one-hot fashion.

Each sample goes through the decisions of each tree of the ensemble and ends up in one leaf per tree. The sample is encoded by setting feature values for these leaves to 1 and the other feature values to 0.

The resulting transformer has then learned a supervised, sparse, high-dimensional categorical embedding of the data.
import numpy as np
np.random.seed(10)

import matplotlib.pyplot as plt

from sklearn.datasets import make_classification

from sklearn.linear_model import LogisticRegression
from sklearn.ensemble import (RandomTreesEmbedding, RandomForestClassifier, GradientBoostingClassifier)
from sklearn.preprocessing import OneHotEncoder
from sklearn.model_selection import train_test_split
from sklearn.metrics import roc_curve
from sklearn.pipeline import make_pipeline

n_estimator = 10
X, y = make_classification(n_samples=80000)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.5)

# It is important to train the ensemble of trees on a different subset # of the training data than the linear regression model to avoid # overfitting, in particular if the total number of leaves is # similar to the number of training samples
X_train, X_train_lr, y_train, y_train_lr = train_test_split(
X_train, y_train, test_size=0.5)

# Unsupervised transformation based on totally random trees
rt = RandomTreesEmbedding(max_depth=3, n_estimators=n_estimator, random_state=0)

rt_lm = LogisticRegression(max_iter=1000)
pipeline = make_pipeline(rt, rt_lm)
pipeline.fit(X_train, y_train)
y_pred_rt = pipeline.predict_proba(X_test)[:, 1]
fpr_rt_lm, tpr_rt_lm, _ = roc_curve(y_test, y_pred_rt)

# Supervised transformation based on random forests
rf = RandomForestClassifier(max_depth=3, n_estimators=n_estimator)
rf_enc = OneHotEncoder()
rf_lm = LogisticRegression(max_iter=1000)
rf.fit(X_train, y_train)
rf_enc.fit(rf.apply(X_train))
rf_lm.fit(rf_enc.transform(rf.apply(X_train_lr)), y_train_lr)
y_pred_rf_lm = rf_lm.predict_proba(rf_enc.transform(rf.apply(X_test)))[:, 1]
fpr_rf_lm, tpr_rf_lm, _ = roc_curve(y_test, y_pred_rf_lm)

# Supervised transformation based on gradient boosted trees
grd = GradientBoostingClassifier(n_estimators=n_estimator)
grd_enc = OneHotEncoder()
grd_lm = LogisticRegression(max_iter=1000)
grd.fit(X_train, y_train)
grd_enc.fit(grd.apply(X_train)[:, :, 0])
grd_lm.fit(grd_enc.transform(grd.apply(X_train_lr)[:, :, 0]), y_train_lr)
y_pred_grd_lm = grd_lm.predict_proba(grd_enc.transform(grd.apply(X_test)[:, :, 0]))[:, 1]
fpr_grd_lm, tpr_grd_lm, _ = roc_curve(y_test, y_pred_grd_lm)

# The gradient boosted model by itself
y_pred_grd = grd.predict_proba(X_test)[:, 1]
fpr_grd, tpr_grd, _ = roc_curve(y_test, y_pred_grd)

# The random forest model by itself
y_pred_rf = rf.predict_proba(X_test)[:, 1]
fpr_rf, tpr_rf, _ = roc_curve(y_test, y_pred_rf)

plt.figure(1)
plt.plot([0, 1], [0, 1], 'k--')
plt.plot(fpr_rt_lm, tpr_rt_lm, label='RT + LR')
plt.plot(fpr_rf, tpr_rf, label='RF')
plt.plot(fpr_rf_lm, tpr_rf_lm, label='RF + LR')
plt.plot(fpr_grd, tpr_grd, label='GBT')
plt.plot(fpr_grd_lm, tpr_grd_lm, label='GBT + LR')
plt.xlabel('False positive rate')
plt.ylabel('True positive rate')
plt.title('ROC curve')
plt.legend(loc='best')
plt.show()
plt.xlim(0, 0.2)
plt.ylim(0.8, 1)
plt.plot([0, 1], [0, 1], 'k--')
plt.plot(fpr_rt_lm, tpr_rt_lm, label='RT + LR')
plt.plot(fpr_rf, tpr_rf, label='RF')
plt.plot(fpr_rf_lm, tpr_rf_lm, label='RF + LR')
plt.plot(fpr_grd, tpr_grd, label='GBT')
plt.plot(fpr_grd_lm, tpr_grd_lm, label='GBT + LR')
plt.xlabel('False positive rate')
plt.ylabel('True positive rate')
plt.title('ROC curve (zoomed in at top left)')
plt.legend(loc='best')
plt.show()

Total running time of the script: ( 0 minutes 3.159 seconds)

6.11.20 Gradient Boosting Out-of-Bag estimates

Out-of-bag (OOB) estimates can be a useful heuristic to estimate the “optimal” number of boosting iterations. OOB estimates are almost identical to cross-validation estimates but they can be computed on-the-fly without the need for repeated model fitting. OOB estimates are only available for Stochastic Gradient Boosting (i.e. subsample < 1.0), the estimates are derived from the improvement in loss based on the examples not included in the bootstrap sample (the so-called out-of-bag examples). The OOB estimator is a pessimistic estimator of the true test loss, but remains a fairly good approximation for a small number of trees.

The figure shows the cumulative sum of the negative OOB improvements as a function of the boosting iteration. As you can see, it tracks the test loss for the first hundred iterations but then diverges in a pessimistic way. The figure also shows the performance of 3-fold cross validation which usually gives a better estimate of the test loss but is computationally more demanding.
Out:

Accuracy: 0.6840

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn import ensemble
from sklearn.model_selection import KFold
from sklearn.model_selection import train_test_split
from scipy.special import expit

# Generate data (adapted from G. Ridgeway's gbm example)
```
n_samples = 1000
random_state = np.random.RandomState(13)
x1 = random_state.uniform(size=n_samples)
x2 = random_state.uniform(size=n_samples)
x3 = random_state.randint(0, 4, size=n_samples)
p = expit(np.sin(3 * x1) - 4 * x2 + x3)
y = random_state.binomial(1, p, size=n_samples)
X = np.c_[x1, x2, x3]
X = X.astype(np.float32)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.5,
random_state=9)

# Fit classifier with out-of-bag estimates
params = {'n_estimators': 1200, 'max_depth': 3, 'subsample': 0.5,
'learning_rate': 0.01, 'min_samples_leaf': 1, 'random_state': 3}
clf = ensemble.GradientBoostingClassifier(**params)
clf.fit(X_train, y_train)
acc = clf.score(X_test, y_test)
print("Accuracy: {:.4f}".format(acc))

n_estimators = params['n_estimators']
x = np.arange(n_estimators) + 1

def heldout_score(clf, X_test, y_test):
    """compute deviance scores on X_test and y_test. """
    score = np.zeros((n_estimators,), dtype=np.float64)
    for i, y_pred in enumerate(clf.staged_decision_function(X_test)):
        score[i] = clf.loss_(y_test, y_pred)
    return score

def cv_estimate(n_splits=None):
    cv = KFold(n_splits=n_splits)
    cv_clf = ensemble.GradientBoostingClassifier(**params)
    val_scores = np.zeros((n_estimators,), dtype=np.float64)
    for train, test in cv.split(X_train, y_train):
        cv_clf.fit(X_train[train], y_train[train])
        val_scores += heldout_score(cv_clf, X_train[test], y_train[test])
    val_scores /= n_splits
    return val_scores

# Estimate best n_estimators using cross-validation
cv_score = cv_estimate(3)

# Compute best n_estimators for test data
test_score = heldout_score(clf, X_test, y_test)

# negative cumulative sum of OOB improvements
cumsum = -np.cumsum(clf.oob_improvement_)

# min loss according to OOB
oob_best_iter = x[np.argmin(cumsum)]

# min loss according to test (normalize such that first loss is 0)
test_score -= test_score[0]
test_best_iter = x[np.argmin(test_score)]

# min loss according to cv (normalize such that first loss is 0)
cv_score -= cv_score[0]
cv_best_iter = x[np.argmin(cv_score)]

# color brew for the three curves
oob_color = list(map(lambda x: x / 256.0, (190, 174, 212)))
test_color = list(map(lambda x: x / 256.0, (127, 201, 127)))
cv_color = list(map(lambda x: x / 256.0, (253, 192, 134)))

# plot curves and vertical lines for best iterations
plt.plot(x, cumsum, label='OOB loss', color=oob_color)
plt.plot(x, test_score, label='Test loss', color=test_color)
plt.plot(x, cv_score, label='CV loss', color=cv_color)
plt.axvline(x=oob_best_iter, color=oob_color)
plt.axvline(x=test_best_iter, color=test_color)
plt.axvline(x=cv_best_iter, color=cv_color)

# add three vertical lines to xticks
xticks = plt.xticks()
xticks_pos = np.array(xticks[0].tolist() + [oob_best_iter, cv_best_iter, test_best_iter])
xticks_label = np.array(list(map(lambda t: int(t), xticks[0])) + ['OOB', 'CV', 'Test'])
ind = np.argsort(xticks_pos)
xticks_pos = xticks_pos[ind]
xticks_label = xticks_label[ind]
plt.xticks(xticks_pos, xticks_label)

plt.legend(loc='upper right')
plt.ylabel('normalized loss')
plt.xlabel('number of iterations')
plt.show()

Total running time of the script: (0 minutes 3.547 seconds)

6.11.21 Single estimator versus bagging: bias-variance decomposition

This example illustrates and compares the bias-variance decomposition of the expected mean squared error of a single estimator against a bagging ensemble.

In regression, the expected mean squared error of an estimator can be decomposed in terms of bias, variance and noise. On average over datasets of the regression problem, the bias term measures the average amount by which the predictions of the estimator differ from the predictions of the best possible estimator for the problem (i.e., the Bayes model). The variance term measures the variability of the predictions of the estimator when fit over different instances LS of the problem. Finally, the noise measures the irreducible part of the error which is due the variability in the data.

The upper left figure illustrates the predictions (in dark red) of a single decision tree trained over a random dataset LS (the blue dots) of a toy 1d regression problem. It also illustrates the predictions (in light red) of other single decision trees trained over other (and different) randomly drawn instances LS of the problem. Intuitively, the variance term
here corresponds to the width of the beam of predictions (in light red) of the individual estimators. The larger the variance, the more sensitive are the predictions for \( x \) to small changes in the training set. The bias term corresponds to the difference between the average prediction of the estimator (in cyan) and the best possible model (in dark blue). On this problem, we can thus observe that the bias is quite low (both the cyan and the blue curves are close to each other) while the variance is large (the red beam is rather wide).

The lower left figure plots the pointwise decomposition of the expected mean squared error of a single decision tree. It confirms that the bias term (in blue) is low while the variance is large (in green). It also illustrates the noise part of the error which, as expected, appears to be constant and around 0.01.

The right figures correspond to the same plots but using instead a bagging ensemble of decision trees. In both figures, we can observe that the bias term is larger than in the previous case. In the upper right figure, the difference between the average prediction (in cyan) and the best possible model is larger (e.g., notice the offset around \( x=2 \)). In the lower right figure, the bias curve is also slightly higher than in the lower left figure. In terms of variance however, the beam of predictions is narrower, which suggests that the variance is lower. Indeed, as the lower right figure confirms, the variance term (in green) is lower than for single decision trees. Overall, the bias- variance decomposition is therefore no longer the same. The tradeoff is better for bagging: averaging several decision trees fit on bootstrap copies of the dataset slightly increases the bias term but allows for a larger reduction of the variance, which results in a lower overall mean squared error (compare the red curves int the lower figures). The script output also confirms this intuition. The total error of the bagging ensemble is lower than the total error of a single decision tree, and this difference indeed mainly stems from a reduced variance.

For further details on bias-variance decomposition, see section 7.3 of\(^1\).

References

Out:

Tree: 0.0255 (error) = 0.0003 (bias^2) + 0.0152 (var) + 0.0098 (noise)
Bagging(Tree): 0.0196 (error) = 0.0004 (bias^2) + 0.0092 (var) + 0.0098 (noise)

print(__doc__)

# Author: Gilles Louppe <g.louppe@gmail.com>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn.ensemble import BaggingRegressor
from sklearn.tree import DecisionTreeRegressor

(continues on next page)
# Settings
n_repeat = 50  # Number of iterations for computing expectations
n_train = 50  # Size of the training set
n_test = 1000  # Size of the test set
noise = 0.1  # Standard deviation of the noise
np.random.seed(0)

# Change this for exploring the bias-variance decomposition of other
# estimators. This should work well for estimators with high variance (e.g.,
# decision trees or KNN), but poorly for estimators with low variance (e.g.,
# linear models).
estimators = ["Tree", DecisionTreeRegressor()],
        ("Bagging(Tree)", BaggingRegressor(DecisionTreeRegressor()))

n_estimators = len(estimators)

# Generate data

def f(x):
    x = x.ravel()

    return np.exp(-x ** 2) + 1.5 * np.exp(-(x - 2) ** 2)

def generate(n_samples, noise, n_repeat=1):
    X = np.random.rand(n_samples) * 10 - 5
    X = np.sort(X)

    if n_repeat == 1:
        y = f(X) + np.random.normal(0.0, noise, n_samples)
    else:
        y = np.zeros((n_samples, n_repeat))

        for i in range(n_repeat):
            y[:, i] = f(X) + np.random.normal(0.0, noise, n_samples)

    X = X.reshape((n_samples, 1))

    return X, y

X_train = []
y_train = []

for i in range(n_repeat):
    X, y = generate(n_samples=n_train, noise=noise)
    X_train.append(X)
    y_train.append(y)

X_test, y_test = generate(n_samples=n_test, noise=noise, n_repeat=n_repeat)

plt.figure(figsize=(10, 8))

# Loop over estimators to compare
for n, (name, estimator) in enumerate(estimators):
    # Compute predictions
y_predict = np.zeros((n_test, n_repeat))

for i in range(n_repeat):
estimator.fit(X_train[i], y_train[i])
y_predict[:, i] = estimator.predict(X_test)

# Bias^2 + Variance + Noise decomposition of the mean squared error
y_error = np.zeros(n_test)

for i in range(n_repeat):
    for j in range(n_repeat):
y_error += (y_test[:, j] - y_predict[:, i]) ** 2

y_error /= (n_repeat * n_repeat)

y_noise = np.var(y_test, axis=1)
y_bias = (f(X_test) - np.mean(y_predict, axis=1)) ** 2
y_var = np.var(y_predict, axis=1)

print("{0}: {1:.4f} (error) = {2:.4f} (bias^2) + {3:.4f} (var) + {4:.4f} (noise)").format(name,
                                                                                       np.mean(y_error),
                                                                                       np.mean(y_bias),
                                                                                       np.mean(y_var),
                                                                                       np.mean(y_noise)))

# Plot figures
plt.subplot(2, n_estimators, n + 1)
plt.plot(X_test, f(X_test), "b", label="f(x)")
plt.plot(X_train[0], y_train[0], ".b", label="LS ~ y = f(x)+noise")

for i in range(n_repeat):
    if i == 0:
        plt.plot(X_test, y_predict[:, i], "r", label="y(x)")
    else:
        plt.plot(X_test, y_predict[:, i], "r", alpha=0.05)

plt.plot(X_test, np.mean(y_predict, axis=1), "c",
         label="\mathbb{E}_{LS} \hat{y}(x)")
plt.xlim([-5, 5])
plt.title(name)

if n == n_estimators - 1:
    plt.legend(loc=(1.1, .5))

plt.subplot(2, n_estimators, n_estimators + n + 1)
plt.plot(X_test, y_error, "r", label="error(x)")
plt.plot(X_test, y_bias, "b", label="bias^2(x)")
plt.plot(X_test, y_var, "g", label="variance(x)")
plt.plot(X_test, y_noise, "c", label="noise(x)")

plt.xlim([-5, 5])
plt.ylim([0, 0.1])

if n == n_estimators - 1:
6.11.22 Categorical Feature Support in Gradient Boosting

In this example, we will compare the training times and prediction performances of \texttt{HistGradientBoostingRegressor} with different encoding strategies for categorical features. In particular, we will evaluate:

- dropping the categorical features
- using a \texttt{OneHotEncoder}
- using an \texttt{OrdinalEncoder} and treat categories as ordered, equidistant quantities
- using an \texttt{OrdinalEncoder} and rely on the native category support of the \texttt{HistGradientBoostingRegressor} estimator.

We will work with the Ames Lowa Housing dataset which consists of numerical and categorical features, where the houses' sales prices is the target.

```python
print(__doc__)
```

Load Ames Housing dataset

First, we load the ames housing data as a pandas dataframe. The features are either categorical or numerical:

```python
from sklearn.datasets import fetch_openml
X, y = fetch_openml(data_id=41211, as_frame=True, return_X_y=True)

n_categorical_features = (X.dtypes == 'category').sum()
n_numerical_features = (X.dtypes == 'float').sum()
print(f"Number of samples: {X.shape[0]}")
print(f"Number of features: {X.shape[1]}")
print(f"Number of categorical features: {n_categorical_features}")
print(f"Number of numerical features: {n_numerical_features}")
```

Out:

```
/home/circleci/project/sklearn/datasets/_openml.py:849: UserWarning: Version 1 of dataset ames-housing is inactive, meaning that issues have been found in the dataset. Try using a newer version from this URL: https://www.openml.org/data/v1/download/20649135/ames-housing.arff
  warn("Version {} of dataset {} is inactive, meaning that issues have "
Number of samples: 2930
Number of features: 80
Number of categorical features: 46
Number of numerical features: 34
```
Gradient boosting estimator with dropped categorical features

As a baseline, we create an estimator where the categorical features are dropped:

```python
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor
from sklearn.pipeline import make_pipeline
from sklearn.compose import make_column_transformer
from sklearn.compose import make_column_selector
dropper = make_column_transformer(
    ('drop', make_column_selector(dtype_include='category')),
    remainder='passthrough')
hist_dropped = make_pipeline(dropper,
    HistGradientBoostingRegressor(random_state=42))
```

Gradient boosting estimator with one-hot encoding

Next, we create a pipeline that will one-hot encode the categorical features and let the rest of the numerical data to pass through:

```python
from sklearn.preprocessing import OneHotEncoder
one_hot_encoder = make_column_transformer(
    (OneHotEncoder(sparse=False, handle_unknown='ignore'),
     make_column_selector(dtype_include='category')),
    remainder='passthrough')
hist_one_hot = make_pipeline(one_hot_encoder,
    HistGradientBoostingRegressor(random_state=42))
```

Gradient boosting estimator with ordinal encoding

Next, we create a pipeline that will treat categorical features as if they were ordered quantities, i.e. the categories will be encoded as 0, 1, 2, etc., and treated as continuous features:

```python
from sklearn.preprocessing import OrdinalEncoder
import numpy as np
ordinal_encoder = make_column_transformer(
    (OrdinalEncoder(handle_unknown='use_encoded_value', unknown_value=np.nan),
     make_column_selector(dtype_include='category')),
    remainder='passthrough')
hist_ordinal = make_pipeline(ordinal_encoder,
    HistGradientBoostingRegressor(random_state=42))
```
Gradient boosting estimator with native categorical support

We now create a `HistGradientBoostingRegressor` estimator that will natively handle categorical features. This estimator will not treat categorical features as ordered quantities.

Since the `HistGradientBoostingRegressor` requires category values to be encoded in \([0, n_{\text{unique categories}} - 1]\), we still rely on an `OrdinalEncoder` to pre-process the data.

The main difference between this pipeline and the previous one is that in this one, we let the `HistGradientBoostingRegressor` know which features are categorical.

```python
# The ordinal encoder will first output the categorical features, and then the # continuous (passed-through) features
categorical_mask = ([True] * n_categorical_features +
                   [False] * n_numerical_features)
hist_native = make_pipeline(
    ordinal_encoder,
    HistGradientBoostingRegressor(random_state=42,
                                   categorical_features=categorical_mask)
)
```

Model comparison

Finally, we evaluate the models using cross validation. Here we compare the models performance in terms of `mean_absolute_percentage_error` and fit times.

```python
from sklearn.model_selection import cross_validate
import matplotlib.pyplot as plt

scoring = "neg_mean_absolute_percentage_error"
dropped_result = cross_validate(hist_dropped, X, y, cv=3, scoring=scoring)
one_hot_result = cross_validate(hist_one_hot, X, y, cv=3, scoring=scoring)
ordinal_result = cross_validate(hist_ordinal, X, y, cv=3, scoring=scoring)
native_result = cross_validate(hist_native, X, y, cv=3, scoring=scoring)

def plot_results(figure_title):
    fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(12, 8))
    plot_info = [('fit_time', 'Fit times (s)', ax1, None),
                 ('test_score', 'Mean Absolute Percentage Error', ax2, (0, 0.20))]

    x, width = np.arange(4), 0.9
    for key, title, ax, y_limit in plot_info:
        items = [dropped_result[key], one_hot_result[key], ordinal_result[key],
                 native_result[key]]
        ax.bar(x, [np.mean(np.abs(item)) for item in items],
               width, yerr=[np.std(item) for item in items],
               color=['C0', 'C1', 'C2', 'C3'])
        ax.set(xlabel='Model', title=title, xticks=x,
               xticklabels=['Dropped', 'One Hot', 'Ordinal', 'Native'],
               ylim=y_limit)
    fig.suptitle(figure_title)

plot_results("Gradient Boosting on Adult Census")
```
We see that the model with one-hot-encoded data is by far the slowest. This is to be expected, since one-hot-encoding creates one additional feature per category value (for each categorical feature), and thus more split points need to be considered during fitting. In theory, we expect the native handling of categorical features to be slightly slower than treating categories as ordered quantities (‘Ordinal’), since native handling requires sorting categories. Fitting times should however be close when the number of categories is small, and this may not always be reflected in practice.

In terms of prediction performance, dropping the categorical features leads to poorer performance. The three models that use categorical features have comparable error rates, with a slight edge for the native handling.

**Limiting the number of splits**

In general, one can expect poorer predictions from one-hot-encoded data, especially when the tree depths or the number of nodes are limited: with one-hot-encoded data, one needs more split points, i.e. more depth, in order to recover an equivalent split that could be obtained in one single split point with native handling.

This is also true when categories are treated as ordinal quantities: if categories are A..F and the best split is ACF – BDE the one-hot-encoder model will need 3 split points (one per category in the left node), and the ordinal non-native model will need 4 splits: 1 split to isolate A, 1 split to isolate F, and 2 splits to isolate C from BCDE.

How strongly the models’ performances differ in practice will depend on the dataset and on the flexibility of the trees. To see this, let us re-run the same analysis with under-fitting models where we artificially limit the total number of splits by both limiting the number of trees and the depth of each tree.

```python
for pipe in (hist_dropped, hist_one_hot, hist_ordinal, hist_native):
    pipe.set_params(histgradientboostingregressor__max_depth=3,
                    histgradientboostingregressor__max_iter=15)
```

(continues on next page)
The results for these under-fitting models confirm our previous intuition: the native category handling strategy performs the best when the splitting budget is constrained. The two other strategies (one-hot encoding and treating categories as ordinal values) lead to error values comparable to the baseline model that just dropped the categorical features altogether.

Total running time of the script: (0 minutes 20.856 seconds)

6.11.23 Plot the decision surfaces of ensembles of trees on the iris dataset

Plot the decision surfaces of forests of randomized trees trained on pairs of features of the iris dataset.

This plot compares the decision surfaces learned by a decision tree classifier (first column), by a random forest classifier (second column), by an extra-trees classifier (third column) and by an AdaBoost classifier (fourth column).

In the first row, the classifiers are built using the sepal width and the sepal length features only, on the second row using the petal length and sepal length only, and on the third row using the petal width and the petal length only.

In descending order of quality, when trained (outside of this example) on all 4 features using 30 estimators and scored using 10 fold cross validation, we see:
Increasing `max_depth` for AdaBoost lowers the standard deviation of the scores (but the average score does not improve).

See the console’s output for further details about each model.

In this example you might try to:

1) vary the `max_depth` for the DecisionTreeClassifier and AdaBoostClassifier, perhaps try `max_depth=3` for the DecisionTreeClassifier or `max_depth=None` for AdaBoostClassifier.

2) vary `n_estimators`

It is worth noting that RandomForesst and ExtraTrees can be fitted in parallel on many cores as each tree is built independently of the others. AdaBoost’s samples are built sequentially and so do not use multiple cores.

**Classifiers on feature subsets of the Iris dataset**

Out:

```
DecisionTree with features [0, 1] has a score of 0.9266666666666666
RandomForest with 30 estimators with features [0, 1] has a score of 0.9266666666666666
ExtraTrees with 30 estimators with features [0, 1] has a score of 0.9266666666666666
AdaBoost with 30 estimators with features [0, 1] has a score of 0.8533333333333334
```
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap

from sklearn.datasets import load_iris
from sklearn.ensemble import RandomForestClassifier, ExtraTreesClassifier, AdaBoostClassifier
from sklearn.tree import DecisionTreeClassifier

# Parameters
n_classes = 3
n_estimators = 30
cmap = plt.cm.RdYlBu
plot_step = 0.02  # fine step width for decision surface contours
plot_step_coarser = 0.5  # step widths for coarse classifier guesses
RANDOM_SEED = 13  # fix the seed on each iteration

# Load data
iris = load_iris()

plot_idx = 1
models = [DecisionTreeClassifier(max_depth=None),
          RandomForestClassifier(n_estimators=n_estimators),
          ExtraTreesClassifier(n_estimators=n_estimators),
          AdaBoostClassifier(DecisionTreeClassifier(max_depth=3),
                              n_estimators=n_estimators)]

for pair in ([0, 1], [0, 2], [2, 3]):
    for model in models:
        # We only take the two corresponding features
        X = iris.data[:, pair]
        y = iris.target

        # Shuffle
        idx = np.arange(X.shape[0])
        np.random.seed(RANDOM_SEED)
        np.random.shuffle(idx)
        X = X[idx]
        y = y[idx]
# Standardize
mean = X.mean(axis=0)
std = X.std(axis=0)
X = (X - mean) / std

# Train
model.fit(X, y)
scores = model.score(X, y)

# Create a title for each column and the console by using str() and
# slicing away useless parts of the string
model_title = str(type(model)).split('.\')[-1][:-2][:-len("Classifier")]
model_details = model_title
if hasattr(model, "estimators_"):
    model_details += " with {} estimators".format(len(model.estimators_))
print(model_details + " with features", pair,
      "has a score of", scores)

plt.subplot(3, 4, plot_idx)
if plot_idx <= len(models):
    # Add a title at the top of each column
    plt.title(model_title, fontsize=9)
    # Now plot the decision boundary using a fine mesh as input to a
    # filled contour plot
    x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
    y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
    xx, yy = np.meshgrid(np.arange(x_min, x_max, plot_step),
                         np.arange(y_min, y_max, plot_step))

    # Plot either a single DecisionTreeClassifier or alpha blend the
    # decision surfaces of the ensemble of classifiers
    if isinstance(model, DecisionTreeClassifier):
        Z = model.predict(np.c_[xx.ravel(), yy.ravel()])
        Z = Z.reshape(xx.shape)
        cs = plt.contourf(xx, yy, Z, cmap=cmap)
    else:
        # Choose alpha blend level with respect to the number
        # of estimators
        # that are in use (noting that AdaBoost can use fewer estimators
        # than its maximum if it achieves a good enough fit early on)
        estimator_alpha = 1.0 / len(model.estimators_)
        for tree in model.estimators_:
            Z = tree.predict(np.c_[xx.ravel(), yy.ravel()])
            Z = Z.reshape(xx.shape)
            cs = plt.contourf(xx, yy, Z, alpha=estimator_alpha, cmap=cmap)

        # Build a coarser grid to plot a set of ensemble classifications
        # to show how these are different to what we see in the decision
        # surfaces. These points are regularly space and do not have a
        # black outline
        xx_coarser, yy_coarser = np.meshgrid(np.arange(x_min, x_max, plot_step_coarser),
                                                np.arange(y_min, y_max, plot_step_coarser),
np.arange(y_min, y_max, plot_step_coarser))
Z_points_coarser = model.predict(np.c_[xx_coarser.ravel(),
    yy_coarser.ravel()]).reshape(xx_coarser.shape)

cs_points = plt.scatter(xx_coarser, yy_coarser, s=15,
    c=Z_points_coarser, cmap=cmap,
    edgecolors="none")

# Plot the training points, these are clustered together and have a
# black outline
plt.scatter(X[:, 0], X[:, 1], c=y,
    cmap=ListedColormap(['r', 'y', 'b']),
    edgecolor='k', s=20)

plt.suptitle("Classifiers on feature subsets of the Iris dataset", fontsize=12)
plt.axis("tight")
plt.tight_layout(h_pad=0.2, w_pad=0.2, pad=2.5)
plt.show()

Total running time of the script: ( 0 minutes 7.757 seconds)

6.11.24 Combine predictors using stacking

Stacking refers to a method to blend estimators. In this strategy, some estimators are individually fitted on some
training data while a final estimator is trained using the stacked predictions of these base estimators.

In this example, we illustrate the use case in which different regressors are stacked together and a final linear penalized
regressor is used to output the prediction. We compare the performance of each individual regressor with the stacking
strategy. Stacking slightly improves the overall performance.

Download the dataset

We will use Ames Housing dataset which was first compiled by Dean De Cock and became better known
after it was used in Kaggle challenge. It is a set of 1460 residential homes in Ames, Iowa, each described
by 80 features. We will use it to predict the final logarithmic price of the houses. In this example we
will use only 20 most interesting features chosen using GradientBoostingRegressor() and limit number of
entries (here we won’t go into the details on how to select the most interesting features).

The Ames housing dataset is not shipped with scikit-learn and therefore we will fetch it from OpenML.

import numpy as np
from sklearn.datasets import fetch_openml
from sklearn.utils import shuffle

def load_ames_housing():
df = fetch_openml(name="house_prices", as_frame=True)
X = df.data
y = df.target

features = ['YrSold', 'HeatingQC', 'Street', 'YearRemodAdd', 'Heating',
'MasVnrType', 'BsmtUnfSF', 'Foundation', 'MasVnrArea',
'MSSubClass', 'ExterQual', 'Condition2', 'GarageCars',
'GarageType', 'OverallQual', 'TotalBsmtSF', 'BsmtFinSF1',
'HouseStyle', 'MiscFeature', 'MoSold']

X = X[features]
X, y = shuffle(X, y, random_state=0)

X = X[:600]
y = y[:600]
return X, np.log(y)

X, y = load_ames_housing()

Make pipeline to preprocess the data

Before we can use Ames dataset we still need to do some preprocessing. First, the dataset has many missing values. To impute them, we will exchange categorical missing values with the new category 'missing' while the numerical missing values with the 'mean' of the column. We will also encode the categories with either `sklearn.preprocessing.OneHotEncoder` or `sklearn.preprocessing.OrdinalEncoder` depending for which type of model we will use them (linear or non-linear model). To facilitate this preprocessing we will make two pipelines. You can skip this section if your data is ready to use and does not need preprocessing.

```python
from sklearn.compose import make_column_transformer
from sklearn.impute import SimpleImputer
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import OneHotEncoder
from sklearn.preprocessing import OrdinalEncoder
from sklearn.preprocessing import StandardScaler

cat_cols = X.columns[X.dtypes == 'O']
um_cols = X.columns[X.dtypes == 'float64']
categories = [X[column].unique() for column in X[cat_cols]]

for cat in categories:
    cat[cat == None] = 'missing'  # noqa

cat_proc_nlin = make_pipeline(
    SimpleImputer(missing_values=None, strategy='constant',
    fill_value='missing'),
    OrdinalEncoder(categories=categories)
)

num_proc_nlin = make_pipeline(SimpleImputer(strategy='mean'))
```

(continues on next page)
Stack of predictors on a single data set

It is sometimes tedious to find the model which will best perform on a given dataset. Stacking provide an alternative by combining the outputs of several learners, without the need to choose a model specifically. The performance of stacking is usually close to the best model and sometimes it can outperform the prediction performance of each individual model.

Here, we combine 3 learners (linear and non-linear) and use a ridge regressor to combine their outputs together.

Note: although we will make new pipelines with the processors which we wrote in the previous section for the 3 learners, the final estimator RidgeCV() does not need preprocessing of the data as it will be fed with the already preprocessed output from the 3 learners.
estimators = [('Random Forest', rf_pipeline),
             ('Lasso', lasso_pipeline),
             ('Gradient Boosting', gradient_pipeline)]

stacking_regressor = StackingRegressor(estimators=estimators,
                                        final_estimator=RidgeCV())

Measure and plot the results

Now we can use Ames Housing dataset to make the predictions. We check the performance of each individual predictor as well as of the stack of the regressors.

The function `plot_regression_results` is used to plot the predicted and true targets.

```python
import time
import matplotlib.pyplot as plt
from sklearn.model_selection import cross_validate, cross_val_predict

def plot_regression_results(ax, y_true, y_pred, title, scores, elapsed_time):
    """Scatter plot of the predicted vs true targets.""
    ax.plot([y_true.min(), y_true.max()]
            ,[y_true.min(), y_true.max()]
            ,('--r', linewidth=2)
            ax.scatter(y_true, y_pred, alpha=0.2)
    ax.spines['top'].set_visible(False)
    ax.spines['right'].set_visible(False)
    ax.get_xaxis().tick_bottom()
    ax.get_yaxis().tick_left()
    ax.spines['left'].set_position(('outward', 10))
    ax.spines['bottom'].set_position(('outward', 10))
    ax.set_xlim([y_true.min(), y_true.max()])
    ax.set_ylim([y_true.min(), y_true.max()])
    ax.set_xlabel('Measured')
    ax.set_ylabel('Predicted')
    extra = plt.Rectangle((0, 0), 0, 0, fc="w", fill=False,
                           edgecolor='none', linewidth=0)
    ax.legend([extra], [scores], loc='upper left')
    title = title + '
    Evaluation in {:.2f} seconds'.format(elapsed_time)
    ax.set_title(title)

fig, axs = plt.subplots(2, 2, figsize=(9, 7))
axs = np.ravel(axs)

for ax, (name, est) in zip(axs, estimators + [('Stacking Regressor',
                                              stacking_regressor))):
    start_time = time.time()
    score = cross_validate(est, X, y,
                            scoring=['r2', 'neg_mean_absolute_error'],
                            n_jobs=-1, verbose=0)
    elapsed_time = time.time() - start_time
```
y_pred = cross_val_predict(est, X, y, n_jobs=-1, verbose=0)

plot_regression_results(  
    ax, y, y_pred,  
    name,  
    r'$R^2=\pm{:.2f}\n+\n+\nMAE=\pm{:.2f}$'.format(np.mean(score['test_r2']),  
          np.std(score['test_r2']),  
          -np.mean(score['test_neg_mean_absolute_error']),  
          np.std(score['test_neg_mean_absolute_error'])),  
    elapsed_time)

plt.suptitle('Single predictors versus stacked predictors')
plt.tight_layout()
plt.subplots_adjust(top=0.9)
plt.show()

The stacked regressor will combine the strengths of the different regressors. However, we also see that training the stacked regressor is much more computationally expensive.

**Total running time of the script:** ( 0 minutes 12.972 seconds)
6.12 Examples based on real world datasets

Applications to real world problems with some medium sized datasets or interactive user interface.

6.12.1 Outlier detection on a real data set

This example illustrates the need for robust covariance estimation on a real data set. It is useful both for outlier detection and for a better understanding of the data structure.

We selected two sets of two variables from the Boston housing data set as an illustration of what kind of analysis can be done with several outlier detection tools. For the purpose of visualization, we are working with two-dimensional examples, but one should be aware that things are not so trivial in high-dimension, as it will be pointed out.

In both examples below, the main result is that the empirical covariance estimate, as a non-robust one, is highly influenced by the heterogeneous structure of the observations. Although the robust covariance estimate is able to focus on the main mode of the data distribution, it sticks to the assumption that the data should be Gaussian distributed, yielding some biased estimation of the data structure, but yet accurate to some extent. The One-Class SVM does not assume any parametric form of the data distribution and can therefore model the complex shape of the data much better.

First example

The first example illustrates how the Minimum Covariance Determinant robust estimator can help concentrate on a relevant cluster when outlying points exist. Here the empirical covariance estimation is skewed by points outside of the main cluster. Of course, some screening tools would have pointed out the presence of two clusters (Support Vector Machines, Gaussian Mixture Models, univariate outlier detection, ...). But had it been a high-dimensional example, none of these could be applied that easily.

```python
print(__doc__)

# Author: Virgile Fritsch <virgile.fritsch@inria.fr>
# License: BSD 3 clause

import numpy as np
from sklearn.covariance import EllipticEnvelope
from sklearn.svm import OneClassSVM
import matplotlib.pyplot as plt
import matplotlib.font_manager
from sklearn.datasets import load_wine

# Define "classifiers" to be used
classifiers = {
    "Empirical Covariance": EllipticEnvelope(support_fraction=1., contamination=0.25),
    "Robust Covariance (Minimum Covariance Determinant)": EllipticEnvelope(contamination=0.25),
    "OCSVM": OneClassSVM(nu=0.25, gamma=0.35)}

colors = ['m', 'g', 'b']
legend1 = {}
legend2 = {}

# Get data
X1 = load_wine()['data'][:, [1, 2]]  # two clusters (continues on next page)
```
# Learn a frontier for outlier detection with several classifiers

```python
xx1, yy1 = np.meshgrid(np.linspace(0, 6, 500), np.linspace(1, 4.5, 500))
for i, (clf_name, clf) in enumerate(classifiers.items()):
    plt.figure(1)
    clf.fit(X1)
    Z1 = clf.decision_function(np.c_[xx1.ravel(), yy1.ravel()])
    Z1 = Z1.reshape(xx1.shape)
    legend1[clf_name] = plt.contour(
        xx1, yy1, Z1, levels=[0], linewidths=2, colors=colors[i])

legend1_values_list = list(legend1.values())
legend1_keys_list = list(legend1.keys())

# Plot the results (= shape of the data points cloud)
plt.figure(1)  # two clusters
plt.title("Outlier detection on a real data set (wine recognition)")
plt.scatter(X1[:, 0], X1[:, 1], color='black')
bbox_args = dict(boxstyle="round", fc="0.8")
arrow_args = dict(arrowstyle="->")
plt.annotate("outlying points", xy=(4, 2),
             xycoords="data", textcoords="data",
             xytext=(3, 1.25), bbox=bbox_args, arrowprops=arrow_args)
plt.xlim((xx1.min(), xx1.max()))
plt.ylim((yy1.min(), yy1.max()))
plt.legend((legend1_values_list[0].collections[0],
            legend1_values_list[1].collections[0],
            legend1_values_list[2].collections[0]),
            (legend1_keys_list[0], legend1_keys_list[1], legend1_keys_list[2]),
            loc="upper center",
            prop=matplotlib.font_manager.FontProperties(size=11))
plt.ylabel("ash")
plt.xlabel("malic_acid")
plt.show()
```
The second example shows the ability of the Minimum Covariance Determinant robust estimator of covariance to concentrate on the main mode of the data distribution: the location seems to be well estimated, although the covariance is hard to estimate due to the banana-shaped distribution. Anyway, we can get rid of some outlying observations. The One-Class SVM is able to capture the real data structure, but the difficulty is to adjust its kernel bandwidth parameter so as to obtain a good compromise between the shape of the data scatter matrix and the risk of over-fitting the data.
# Plot the results (= shape of the data points cloud)
plt.figure(2)  # "banana" shape
plt.title("Outlier detection on a real data set (wine recognition)")
plt.scatter(X2[:, 0], X2[:, 1], color='black')
plt.xlim((xx2.min(), xx2.max()))
plt.ylim((yy2.min(), yy2.max()))
plt.legend((legend2_values_list[0].collections[0],
            legend2_values_list[1].collections[0],
            legend2_values_list[2].collections[0]),
            (legend2_keys_list[0], legend2_keys_list[1], legend2_keys_list[2]),
            loc="upper center",
            prop=matplotlib.font_manager.FontProperties(size=11))
plt.ylabel("color_intensity")
plt.xlabel("flavanoids")
plt.show()
6.12.2 Compressive sensing: tomography reconstruction with L1 prior (Lasso)

This example shows the reconstruction of an image from a set of parallel projections, acquired along different angles. Such a dataset is acquired in **computed tomography** (CT).

Without any prior information on the sample, the number of projections required to reconstruct the image is of the order of the linear size \( l \) of the image (in pixels). For simplicity we consider here a sparse image, where only pixels on the boundary of objects have a non-zero value. Such data could correspond for example to a cellular material. Note however that most images are sparse in a different basis, such as the Haar wavelets. Only \( 1/7 \) projections are acquired, therefore it is necessary to use prior information available on the sample (its sparsity): this is an example of **compressive sensing**.

The tomography projection operation is a linear transformation. In addition to the data-fidelity term corresponding to a linear regression, we penalize the L1 norm of the image to account for its sparsity. The resulting optimization problem is called the **Lasso**. We use the class **Lasso**, that uses the coordinate descent algorithm. Importantly, this implementation is more computationally efficient on a sparse matrix, than the projection operator used here.

The reconstruction with L1 penalization gives a result with zero error (all pixels are successfully labeled with 0 or 1), even if noise was added to the projections. In comparison, an L2 penalization (**Ridge**) produces a large number of labeling errors for the pixels. Important artifacts are observed on the reconstructed image, contrary to the L1 penalization. Note in particular the circular artifact separating the pixels in the corners, that have contributed to fewer projections than the central disk.

![Original Image, L2 Penalization, L1 Penalization](image)

```python
# Author: Emmanuelle Gouillart <emmanuelle.gouillart@nsup.org>
# License: BSD 3 clause

import numpy as np
from scipy import sparse
from scipy import ndimage
from sklearn.linear_model import Lasso
from sklearn.linear_model import Ridge
import matplotlib.pyplot as plt

def _weights(x, dx=1, orig=0):
    x = np.ravel(x)
    floor_x = np.floor((x - orig) / dx).astype(np.int64)
```
alpha = (x - orig - floor_x * dx) / dx
return np.hstack((floor_x, floor_x + 1)), np.hstack((1 - alpha, alpha))

def _generate_center_coordinates(l_x):
    X, Y = np.mgrid[:l_x, :l_x].astype(np.float64)
    center = l_x / 2.
    X += 0.5 - center
    Y += 0.5 - center
    return X, Y

def build_projection_operator(l_x, n_dir):
    """ Compute the tomography design matrix. """

    Parameters
    ----------
    l_x : int
        linear size of image array
    n_dir : int
        number of angles at which projections are acquired.

    Returns
    -------
    p : sparse matrix of shape (n_dir l_x, l_x**2)
        """
    X, Y = _generate_center_coordinates(l_x)
    angles = np.linspace(0, np.pi, n_dir, endpoint=False)
    data_inds, weights, camera_inds = [], [], [
    data_unravel_indices = np.arange(l_x ** 2)
    data_unravel_indices = np.hstack((data_unravel_indices,
    for i, angle in enumerate(angles):
        Xrot = np.cos(angle) * X - np.sin(angle) * Y
        inds, w = _weights(Xrot, dx=1, orig=X.min())
        mask = np.logical_and(inds >= 0, inds < l_x)
        weights += list(w[mask])
        camera_inds += list(inds[mask] + i * l_x)
        data_inds += list(data_unravel_indices[mask])
    proj_operator = sparse.coo_matrix((weights, (camera_inds, data_inds)))
    return proj_operator

def generate_synthetic_data():
    """ Synthetic binary data """
    rs = np.random.RandomState(0)
    n_pts = 36
    x, y = np.ogrid[0:1, 0:1]
    mask_outer = (x - 0.1) ** 2 + (y - 0.1) ** 2 < (1 / 2.) ** 2
    mask = np.zeros((1, 1))
    points = 1 * rs.rand(2, n_pts)
    mask[(points[0]).astype(int), (points[1]).astype(int)] = 1
    mask = ndimage.gaussian_filter(mask, sigma=1 / n_pts)
    res = np.logical_and(mask > mask.mean(), mask_outer)
    return np.logical_xor(res, ndimage.binary_erosion(res))
# Generate synthetic images, and projections

```python
l = 128
proj_operator = build_projection_operator(l, l // 7)
data = generate_synthetic_data()
proj = proj_operator @ data.ravel()[:, np.newaxis]
proj += 0.15 * np.random.randn(*proj.shape)

# Reconstruction with L2 (Ridge) penalization
rgr_ridge = Ridge(alpha=0.2)
rgr_ridge.fit(proj_operator, proj.ravel())
rec_l2 = rgr_ridge.coef_.reshape(l, l)

# Reconstruction with L1 (Lasso) penalization
# the best value of alpha was determined using cross validation
# with LassoCV
rgr_lasso = Lasso(alpha=0.001)
rgr_lasso.fit(proj_operator, proj.ravel())
rec_l1 = rgr_lasso.coef_.reshape(l, l)
```

```python
plt.figure(figsize=(8, 3.3))
plt.subplot(131)
plt.imshow(data, cmap=plt.cm.gray, interpolation='nearest')
plt.axis('off')
plt.title('original image')
plt.subplot(132)
plt.imshow(rec_l2, cmap=plt.cm.gray, interpolation='nearest')
plt.title('L2 penalization')
plt.axis('off')
plt.subplot(133)
plt.imshow(rec_l1, cmap=plt.cm.gray, interpolation='nearest')
plt.title('L1 penalization')
plt.axis('off')

plt.subplots_adjust(hspace=0.01, wspace=0.01, top=1, bottom=0, left=0, right=1)
plt.show()
```

Total running time of the script: ( 0 minutes 9.408 seconds)

6.12.3 Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation

This is an example of applying NMF and LatentDirichletAllocation on a corpus of documents and extract additive models of the topic structure of the corpus. The output is a plot of topics, each represented as bar plot using top few words based on weights.

Non-negative Matrix Factorization is applied with two different objective functions: the Frobenius norm, and the generalized Kullback-Leibler divergence. The latter is equivalent to Probabilistic Latent Semantic Indexing.

The default parameters (n_samples / n_features / n_components) should make the example runnable in a couple of tens of seconds. You can try to increase the dimensions of the problem, but be aware that the time complexity is polynomial in NMF. In LDA, the time complexity is proportional to (n_samples * iterations).

6.12. Examples based on real world datasets
Out:

Loading dataset... done in 1.146s.
Extracting tf-idf features for NMF... done in 0.270s.
Extracting tf features for LDA... done in 0.285s.

Fitting the NMF model (Frobenius norm) with tf-idf features, n_samples=2000 and n_features=1000...
/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features, will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn("The 'init' value, when 'init=None' and " done in 0.246s.

Fitting the NMF model (generalized Kullback-Leibler divergence) with tf-idf features, n_samples=2000 and n_features=1000...
/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features, will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn("The 'init' value, when 'init=None' and " done in 0.797s.

Fitting LDA models with tf features, n_samples=2000 and n_features=1000... done in 3.757s.

# Author: Olivier Grisel <olivier.grisel@ensta.org>
# Lars Buitinck

(continues on next page)
from time import time
import matplotlib.pyplot as plt

from sklearn.feature_extraction.text import TfidfVectorizer, CountVectorizer
from sklearn.decomposition import NMF, LatentDirichletAllocation
from sklearn.datasets import fetch_20newsgroups

n_samples = 2000
n_features = 1000
n_components = 10
n_top_words = 20

def plot_top_words(model, feature_names, n_top_words, title):
    fig, axes = plt.subplots(2, 5, figsize=(30, 15), sharex=True)
    axes = axes.flatten()
    for topic_idx, topic in enumerate(model.components_):
        top_features_ind = topic.argsort()[:-n_top_words - 1:-1]
        top_features = [feature_names[i] for i in top_features_ind]
        weights = topic[top_features_ind]

        ax = axes[topic_idx]
        ax.barh(top_features, weights, height=0.7)
        ax.set_title(f'Topic {topic_idx + 1}', fontdict={'fontsize': 30})
        ax.invert_yaxis()
        ax.tick_params(axis='both', which='major', labelsize=20)
        for i in 'top right left'.split():
            ax.spines[i].set_visible(False)
    fig.suptitle(title, fontsize=40)
    plt.subplots_adjust(top=0.90, bottom=0.05, wspace=0.90, hspace=0.3)
    plt.show()

# Load the 20 newsgroups dataset and vectorize it. We use a few heuristics
# to filter out useless terms early on: the posts are stripped of headers,
# footers and quoted replies, and common English words, words occurring in
# only one document or in at least 95% of the documents are removed.

print("Loading dataset...")
t0 = time()
data, _ = fetch_20newsgroups(shuffle=True, random_state=1,
                           remove=('headers', 'footers', 'quotes'),
                           return_X_y=True)
data_samples = data[:n_samples]
print("done in %0.3fs." % (time() - t0))

# Use tf-idf features for NMF.
print("Extracting tf-idf features for NMF...")
tfidf_vectorizer = TfidfVectorizer(max_df=0.95, min_df=2,
                                   max_features=n_features,
                                   stop_words='english')
t0 = time()
tfidf = tfidf_vectorizer.fit_transform(data_samples)
print("done in \$0.3fs." % (time() - t0))

# Use tf (raw term count) features for LDA.
print("Extracting tf features for LDA...")
tf_vectorizer = CountVectorizer(max_df=0.95, min_df=2,
                                 max_features=n_features,
                                 stop_words='english')
t0 = time()
tf = tf_vectorizer.fit_transform(data_samples)
print("done in \$0.3fs." % (time() - t0))

# Fit the NMF model
print("Fitting the NMF model (Frobenius norm) with tf-idf features, ",
      "n_samples=%d and n_features=%d...")
% (n_samples, n_features))
t0 = time()
nmf = NMF(n_components=n_components, random_state=1,
         alpha=.1, l1_ratio=.5).fit(tfidf)
print("done in \$0.3fs." % (time() - t0))

tfidf_feature_names = tfidf_vectorizer.get_feature_names()
plot_top_words(nmf, tfidf_feature_names, n_top_words,
               'Topics in NMF model (Frobenius norm)')

# Fit the NMF model
print('n' * 2, "Fitting the NMF model (generalized Kullback-Leibler "
      "divergence) with tf-idf features, n_samples=%d and n_features=%d...",
% (n_samples, n_features))
t0 = time()
nmf = NMF(n_components=n_components, random_state=1,
         beta_loss='kullback-leibler', solver='mu', max_iter=1000, alpha=.1,
         l1_ratio=.5).fit(tfidf)
print("done in \$0.3fs." % (time() - t0))

tfidf_feature_names = tfidf_vectorizer.get_feature_names()
plot_top_words(nmf, tfidf_feature_names, n_top_words,
               'Topics in NMF model (generalized Kullback-Leibler divergence)')

print('n' * 2, "Fitting LDA models with tf features, ",
      "n_samples=%d and n_features=%d...")
% (n_samples, n_features))
lda = LatentDirichletAllocation(n_components=n_components, max_iter=5,
                                learning_method='online',
                                learning_offset=50.,
                                random_state=0)
t0 = time()
lda.fit(tf)
print("done in \$0.3fs." % (time() - t0))

tf_feature_names = tf_vectorizer.get_feature_names()
plot_top_words(lda, tf_feature_names, n_top_words, 'Topics in LDA model')

Total running time of the script: ( 0 minutes 10.284 seconds)
6.12.4 Faces recognition example using eigenfaces and SVMs

The dataset used in this example is a preprocessed excerpt of the “Labeled Faces in the Wild”, aka LFW:


Expected results for the top 5 most represented people in the dataset:

<table>
<thead>
<tr>
<th>Name</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>Total</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ariel Sharon</td>
<td>0.67</td>
<td>0.92</td>
<td>0.77</td>
<td>13</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Colin Powell</td>
<td>0.75</td>
<td>0.78</td>
<td>0.76</td>
<td>60</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Donald Rumsfeld</td>
<td>0.78</td>
<td>0.67</td>
<td>0.72</td>
<td>27</td>
<td></td>
<td></td>
</tr>
<tr>
<td>George W Bush</td>
<td>0.86</td>
<td>0.86</td>
<td>0.86</td>
<td>146</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Gerhard Schroeder</td>
<td>0.76</td>
<td>0.76</td>
<td>0.76</td>
<td>25</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hugo Chavez</td>
<td>0.67</td>
<td>0.67</td>
<td>0.67</td>
<td>15</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Tony Blair</td>
<td>0.81</td>
<td>0.69</td>
<td>0.75</td>
<td>36</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Avg / Total</td>
<td>0.80</td>
<td>0.80</td>
<td>0.80</td>
<td>322</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Predicted: Bush
True: Bush

Predicted: Bush
True: Bush

Predicted: Blair
True: Blair

Predicted: Bush
True: Bush

Predicted: Powell
True: Powell
Out:

Total dataset size:
n_samples: 1288
n_features: 1850
n_classes: 7
Extracting the top 150 eigenfaces from 966 faces
done in 0.090s
Projecting the input data on the eigenfaces orthonormal basis
done in 0.008s
Fitting the classifier to the training set
done in 22.001s
Best estimator found by grid search:
SVC(C=1000.0, class_weight='balanced', gamma=0.005)
Predicting people's names on the test set
done in 0.064s

<table>
<thead>
<tr>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
</table>

(continues on next page)
from time import time
import logging
import matplotlib.pyplot as plt

from sklearn.model_selection import train_test_split
from sklearn.model_selection import GridSearchCV
from sklearn.datasets import fetch_lfw_people
from sklearn.metrics import classification_report
from sklearn.metrics import confusion_matrix
from sklearn.decomposition import PCA
from sklearn.svm import SVC

print(__doc__)

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO, format='%(asctime)s %(message)s')

# Download the data, if not already on disk and load it as numpy arrays
lfw_people = fetch_lfw_people(min_faces_per_person=70, resize=0.4)

# introspect the images arrays to find the shapes (for plotting)
n_samples, h, w = lfw_people.images.shape

# for machine learning we use the 2 data directly (as relative pixel
# positions info is ignored by this model)
X = lfw_people.data

Ariel Sharon 0.75 0.46 0.57 13
Colin Powell 0.81 0.87 0.84 60
Donald Rumsfeld 0.86 0.67 0.75 27
George W Bush 0.85 0.98 0.91 146
Gerhard Schroeder 0.95 0.80 0.87 25
Hugo Chavez 1.00 0.60 0.75 15
Tony Blair 0.97 0.81 0.88 36

accuracy 0.86 322
macro avg 0.88 0.74 0.80 322
weighted avg 0.87 0.86 0.85 322

[[ 6  2  0  5  0  0  0]
 [ 1  52  1  6  0  0  0]
 [ 1  2  18  6  0  0  0]
 [ 0  3  0 143  0  0  0]
 [ 0  1  0  3  20  0  1]
 [ 0  3  0  2  1  9  0]
 [ 0  1  2  4  0  0 29]]
n_features = X.shape[1]

# the label to predict is the id of the person
y = lfw_people.target
target_names = lfw_people.target_names
n_classes = target_names.shape[0]

print("Total dataset size:")
print("n_samples: %d" % n_samples)
print("n_features: %d" % n_features)
print("n_classes: %d" % n_classes)

# Split into a training set and a test set using a stratified k fold
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.25, random_state=42)

# Compute a PCA (eigenfaces) on the face dataset (treated as unlabeled
# dataset): unsupervised feature extraction / dimensionality reduction
n_components = 150

print("Extracting the top %d eigenfaces from %d faces" % (n_components, X_train.shape[0]))
t0 = time()
pca = PCA(n_components=n_components, svd_solver='randomized',
          whiten=True).fit(X_train)
print("done in %0.3fs" % (time() - t0))
eigenfaces = pca.components_.reshape((n_components, h, w))

print("Projecting the input data on the eigenfaces orthonormal basis")
t0 = time()
X_train_pca = pca.transform(X_train)
X_test_pca = pca.transform(X_test)
print("done in %0.3fs" % (time() - t0))

# Train a SVM classification model
print("Fitting the classifier to the training set")
t0 = time()
param_grid = {"C": [1e3, 5e3, 1e4, 5e4, 1e5],
             "gamma": [0.0001, 0.0005, 0.001, 0.005, 0.01, 0.1],}
clf = GridSearchCV(SVC(kernel='rbf', class_weight='balanced'), param_grid)
clf = clf.fit(X_train_pca, y_train)
print("done in %0.3fs" % (time() - t0))
print("Best estimator found by grid search:")
print(clf.best_estimator_)

(continues on next page)
# Quantitative evaluation of the model quality on the test set

```
print("Predicting people's names on the test set")
t0 = time()
y_pred = clf.predict(X_test_pca)
print("done in %0.3fs" % (time() - t0))

print(classification_report(y_test, y_pred, target_names=target_names))
print(confusion_matrix(y_test, y_pred, labels=range(n_classes)))
```

# Qualitative evaluation of the predictions using matplotlib

```
def plot_gallery(images, titles, h, w, n_row=3, n_col=4):
    """Helper function to plot a gallery of portraits""
    plt.figure(figsize=(1.8 * n_col, 2.4 * n_row))
    plt.subplots_adjust(bottom=0, left=.01, right=.99, top=.90, hspace=.35)
    for i in range(n_row * n_col):
        plt.subplot(n_row, n_col, i + 1)
        plt.imshow(images[i].reshape((h, w)), cmap=plt.cm.gray)
        plt.title(titles[i], size=12)
        plt.xticks(())
        plt.yticks(())

# plot the result of the prediction on a portion of the test set

def title(y_pred, y_test, target_names, i):
    pred_name = target_names[y_pred[i]].rsplit(' ', 1)[-1]
    true_name = target_names[y_test[i]].rsplit(' ', 1)[-1]
    return 'predicted: %s
true: %s' % (pred_name, true_name)

prediction_titles = [title(y_pred, y_test, target_names, i)
                     for i in range(y_pred.shape[0])]

plot_gallery(X_test, prediction_titles, h, w)

# plot the gallery of the most significative eigenfaces

eigenface_titles = ["eigenface %d" % i for i in range(eigenfaces.shape[0])]

plot_gallery(eigenfaces, eigenface_titles, h, w)
```

Total running time of the script: ( 0 minutes 22.848 seconds)
6.12.5 Model Complexity Influence

Demonstrate how model complexity influences both prediction accuracy and computational performance.

We will be using two datasets:

- Diabetes dataset for regression. This dataset consists of 10 measurements taken from diabetes patients. The task is to predict disease progression;
- The 20 newsgroups text dataset for classification. This dataset consists of newsgroup posts. The task is to predict on which topic (out of 20 topics) the post is written about.

We will model the complexity influence on three different estimators:

- SGDClassifier (for classification data) which implements stochastic gradient descent learning;
- NuSVR (for regression data) which implements Nu support vector regression;
- GradientBoostingRegressor (for regression data) which builds an additive model in a forward stage-wise fashion.

We make the model complexity vary through the choice of relevant model parameters in each of our selected models. Next, we will measure the influence on both computational performance (latency) and predictive power (MSE or Hamming Loss).

```python
print(__doc__)

# Authors: Eustache Diemert <eustache@diemert.fr>
# Maria Telenczuk <https://github.com/maikia>
# Guillaume Lemaitre <g.lemaitre58@gmail.com>
# License: BSD 3 clause

import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.utils import shuffle
from sklearn.metrics import mean_squared_error
from sklearn.svm import NuSVR
from sklearn.ensemble import GradientBoostingRegressor
from sklearn.linear_model import SGDClassifier
from sklearn.metrics import hamming_loss

# Initialize random generator
np.random.seed(0)
```

Load the data

First we load both datasets.

**Note:** We are using `fetch_20newsgroups_vectorized` to download 20 newsgroups dataset. It returns ready-to-use features.

**Note:** X of the 20 newsgroups dataset is a sparse matrix while X of diabetes dataset is a numpy array.
def generate_data(case):
    """Generate regression/classification data."""
    if case == 'regression':
        X, y = datasets.load_diabetes(return_X_y=True)
    elif case == 'classification':
        X, y = datasets.fetch_20newsgroups_vectorized(subset='all',
                                                    return_X_y=True)
    X, y = shuffle(X, y)
    offset = int(X.shape[0] * 0.8)
    X_train, y_train = X[:offset], y[:offset]
    X_test, y_test = X[offset:], y[offset:]
    data = {'X_train': X_train, 'X_test': X_test, 'y_train': y_train,
            'y_test': y_test}
    return data

regression_data = generate_data('regression')
classification_data = generate_data('classification')

Benchmark influence

Next, we can calculate the influence of the parameters on the given estimator. In each round, we will set the estimator with the new value of changing_param and we will be collecting the prediction times, prediction performance and complexities to see how those changes affect the estimator. We will calculate the complexity using complexity_computer passed as a parameter.

def benchmark_influence(conf):
    """Benchmark influence of `changing_param` on both MSE and latency."
    prediction_times = []
    prediction_powers = []
    complexities = []
    for param_value in conf['changing_param_values']:
        conf['tuned_params'][conf['changing_param']] = param_value
        estimator = conf['estimator'](**conf['tuned_params'])

        estimator.fit(conf['data']['X_train'], conf['data']['y_train'])
        conf['postfit_hook'](estimator)
        complexity = conf['complexity_computer'](estimator)
        complexities.append(complexity)
        start_time = time.time()
        for _ in range(conf['n_samples']):
            y_pred = estimator.predict(conf['data']['X_test'])
            elapsed_time = (time.time() - start_time) / float(conf['n_samples'])
            prediction_times.append(elapsed_time)
            pred_score = conf['prediction_performance_computer'](
                conf['data']['y_test'], y_pred)
            prediction_powers.append(pred_score)
        print("Complexity: %d | %s: %.4f | Pred. Time: %fs\n" % (complexity, conf['prediction_performance_label'], pred_score, elapsed_time))
    return prediction_powers, prediction_times, complexities
Choose parameters

We choose the parameters for each of our estimators by making a dictionary with all the necessary values. `changing_param` is the name of the parameter which will vary in each estimator. Complexity will be defined by the `complexity_label` and calculated using `complexity_computer`. Also note that depending on the estimator type we are passing different data.

```python
def _count_nonzero_coefficients(estimator):
    a = estimator.coef_.toarray()
    return np.count_nonzero(a)

configurations = [
    {'estimator': SGDClassifier,
     'tuned_params': {'penalty': 'elasticnet', 'alpha': 0.001, 'loss': 'modified_huber', 'fit_intercept': True, 'tol': 1e-3},
     'changing_param': 'l1_ratio',
     'changing_param_values': [0.25, 0.5, 0.75, 0.9],
     'complexity_label': 'non_zero_coefficients',
     'complexity_computer': _count_nonzero_coefficients,
     'prediction_performance_computer': hamming_loss,
     'prediction_performance_label': 'Hamming Loss (Misclassification Ratio)',
     'postfit_hook': lambda x: x.sparsify(),
     'data': classification_data,
     'n_samples': 30},
    {'estimator': NuSVR,
     'tuned_params': {'C': 1e3, 'gamma': 2 ** -15},
     'changing_param': 'nu',
     'changing_param_values': [0.1, 0.25, 0.5, 0.75, 0.9],
     'complexity_label': 'n_support_vectors',
     'complexity_computer': lambda x: len(x.support_vectors_),
     'data': regression_data,
     'postfit_hook': lambda x: x,
     'prediction_performance_computer': mean_squared_error,
     'prediction_performance_label': 'MSE',
     'n_samples': 30},
    {'estimator': GradientBoostingRegressor,
     'tuned_params': {'loss': 'ls'},
     'changing_param': 'n_estimators',
     'changing_param_values': [10, 50, 100, 200, 500],
     'complexity_label': 'n_trees',
     'complexity_computer': lambda x: x.n_estimators,
     'data': regression_data,
     'postfit_hook': lambda x: x,
     'prediction_performance_computer': mean_squared_error,
     'prediction_performance_label': 'MSE',
     'n_samples': 30},
]
```
Run the code and plot the results

We defined all the functions required to run our benchmark. Now, we will loop over the different configurations that we defined previously. Subsequently, we can analyze the plots obtained from the benchmark: Relaxing the L1 penalty in the SGD classifier reduces the prediction error but leads to an increase in the training time. We can draw a similar analysis regarding the training time which increases with the number of support vectors with a Nu-SVR. However, we observed that there is an optimal number of support vectors which reduces the prediction error. Indeed, too few support vectors lead to an under-fitted model while too many support vectors lead to an over-fitted model. The exact same conclusion can be drawn for the gradient-boosting model. The only difference with the Nu-SVR is that having too many trees in the ensemble is not as detrimental.

```python
def plot_influence(conf, mse_values, prediction_times, complexities):
    
    # first axes (prediction error)
    ax1 = fig.add_subplot(111)
    line1 = ax1.plot(complexities, mse_values, c='tab:blue', ls='-')
    ax1.set_xlabel('Model Complexity (%s)' % conf['complexity_label'])
    y1_label = conf['prediction_performance_label']
    ax1.set_ylabel(y1_label)
    ax1.spines['left'].set_color(line1.get_color())
    ax1.yaxis.label.set_color(line1.get_color())
    ax1.tick_params(axis='y', colors=line1.get_color())

    # second axes (latency)
    ax2 = fig.add_subplot(111, sharex=ax1, frameon=False)
    line2 = ax2.plot(complexities, prediction_times, c='tab:orange', ls='-')
    ax2.yaxis.tick_right()
    ax2.yaxis.set_label_position("right")
    y2_label = "Time (s)"
    ax2.set_ylabel(y2_label)
    ax1.spines['right'].set_color(line2.get_color())
    ax2.yaxis.set_color(line2.get_color())
    ax2.tick_params(axis='y', colors=line2.get_color())

    plt.legend((line1, line2), ("prediction error", "latency"),
               loc='upper right')

    plt.title("Influence of varying '%s' on %s' %
               (conf['changing_param'],
                conf['estimator'].__name__))

for conf in configurations:
    prediction_performances, prediction_times, complexities =
        benchmark_influence(conf)
    plot_influence(conf, prediction_performances, prediction_times,
                   complexities)
plt.show()
```

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Out:

Benchmarking SGDClassifier(alpha=0.001, l1_ratio=0.25, loss='modified_huber', penalty='elasticnet')
Complexity: 4482 | Hamming Loss (Misclassification Ratio): 0.2541 | Pred. Time: 0.021633s

Benchmarking SGDClassifier(alpha=0.001, l1_ratio=0.5, loss='modified_huber', penalty='elasticnet')
Complexity: 1668 | Hamming Loss (Misclassification Ratio): 0.2854 | Pred. Time: 0.014051s

Benchmarking SGDClassifier(alpha=0.001, l1_ratio=0.75, loss='modified_huber', penalty='elasticnet')
Complexity: 874 | Hamming Loss (Misclassification Ratio): 0.3143 | Pred. Time: 0.011533s

Benchmarking SGDClassifier(alpha=0.001, l1_ratio=0.9, loss='modified_huber', penalty='elasticnet')
Complexity: 663 | Hamming Loss (Misclassification Ratio): 0.3268 | Pred. Time: 0.011942s

Benchmarking NuSVR(C=1000.0, gamma=3.0517578125e-05, nu=0.1)
Complexity: 36 | MSE: 7004.5333 | Pred. Time: 0.000360s

Benchmarking NuSVR(C=1000.0, gamma=3.0517578125e-05, nu=0.25)
Complexity: 90 | MSE: 6918.2577 | Pred. Time: 0.000806s

(continues on next page)
Conclusion

As a conclusion, we can deduce the following insights:

- a model which is more complex (or expressive) will require a larger training time;
- a more complex model does not guarantee to reduce the prediction error.

These aspects are related to model generalization and avoiding model under-fitting or over-fitting.

**Total running time of the script:** (0 minutes 21.471 seconds)

6.12.6 Visualizing the stock market structure

This example employs several unsupervised learning techniques to extract the stock market structure from variations in historical quotes.

The quantity that we use is the daily variation in quote price: quotes that are linked tend to cofluctuate during a day.

**Learning a graph structure**

We use sparse inverse covariance estimation to find which quotes are correlated conditionally on the others. Specifically, sparse inverse covariance gives us a graph, that is a list of connection. For each symbol, the symbols that it is connected too are those useful to explain its fluctuations.
Clustering

We use clustering to group together quotes that behave similarly. Here, amongst the various clustering techniques available in the scikit-learn, we use *Affinity Propagation* as it does not enforce equal-size clusters, and it can choose automatically the number of clusters from the data.

Note that this gives us a different indication than the graph, as the graph reflects conditional relations between variables, while the clustering reflects marginal properties: variables clustered together can be considered as having a similar impact at the level of the full stock market.

Embedding in 2D space

For visualization purposes, we need to lay out the different symbols on a 2D canvas. For this we use *Manifold learning* techniques to retrieve 2D embedding.

Visualization

The output of the 3 models are combined in a 2D graph where nodes represents the stocks and edges the:

- cluster labels are used to define the color of the nodes
- the sparse covariance model is used to display the strength of the edges
- the 2D embedding is used to position the nodes in the plan

This example has a fair amount of visualization-related code, as visualization is crucial here to display the graph. One of the challenge is to position the labels minimizing overlap. For this we use an heuristic based on the direction of the nearest neighbor along each axis.
Out:

Fetching quote history for 'AAPL'
Fetching quote history for 'AIG'
Fetching quote history for 'AMZN'
Fetching quote history for 'AXP'
Fetching quote history for 'BA'
Fetching quote history for 'BAC'
Fetching quote history for 'CAJ'
Fetching quote history for 'CAT'
Fetching quote history for 'CL'
Fetching quote history for 'CMCSA'
Fetching quote history for 'COP'
Fetching quote history for 'CSCO'
Fetching quote history for 'CVC'
Fetching quote history for 'CVS'
Fetching quote history for 'CVX'
Fetching quote history for 'DD'
Fetching quote history for 'DELL'
Fetching quote history for 'F'
Fetching quote history for 'GD'
Fetching quote history for 'GE'
Fetching quote history for 'GS'
| Cluster 1: | Apple, Amazon, Yahoo |
| Cluster 2: | Comcast, Cablevision, Time Warner |
| Cluster 3: | ConocoPhillips, Chevron, Total, Valero Energy, Exxon |
| Cluster 4: | Cisco, Dell, HP, IBM, Microsoft, SAP, Texas Instruments |
| Cluster 5: | Boeing, General Dynamics, Northrop Grumman, Raytheon |
| Cluster 6: | AIG, American express, Bank of America, Caterpillar, CVS, DuPont de Nemours, Ford, General Electrics, Goldman Sachs, Home Depot, JPMorgan Chase, Marriott, 3M, Ryder, Wells Fargo, Wal-Mart |
| Cluster 7: | McDonald's |
| Cluster 8: | GlaxoSmithKline, Novartis, Pfizer, Sanofi-Aventis, Unilever |
| Cluster 9: | Kellogg, Coca Cola, Pepsi |
| Cluster 10: | Colgate-Palmolive, Kimberly-Clark, Procter Gamble |
| Cluster 11: | Canon, Honda, Navistar, Sony, Toyota, Xerox |
import sys
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.collections import LineCollection
import pandas as pd
from sklearn import cluster, covariance, manifold

print(__doc__)

# #############################################################################
# Retrieve the data from Internet
# The data is from 2003 - 2008. This is reasonably calm: (not too long ago so
# that we get high-tech firms, and before the 2008 crash). This kind of
# historical data can be obtained for from APIs like the quandl.com and
# alphavantage.co ones.

symbol_dict = {
    'TOT': 'Total',
    'XOM': 'Exxon',
    'CVX': 'Chevron',
    'COP': 'ConocoPhillips',
    'VLO': 'Valero Energy',
    'MSFT': 'Microsoft',
    'IBM': 'IBM',
    'TWX': 'Time Warner',
    'CMCSA': 'Comcast',
    'CVC': 'Cablevision',
    'YHOO': 'Yahoo',
    'DELL': 'Dell',
    'HPQ': 'HP',
    'AMZN': 'Amazon',
    'TM': 'Toyota',
    'CAJ': 'Canon',
    'SNE': 'Sony',
    'F': 'Ford',
    'HMC': 'Honda',
    'NAV': 'Navistar',
    'NOC': 'Northrop Grumman',
    'BA': 'Boeing',
    'KO': 'Coca Cola',
    'MMM': '3M',
    'MCD': 'McDonald\'s',
    'PEP': 'Pepsi',
    'K': 'Kellogg',
    'UN': 'Unilever',
    'MAR': 'Marriott',
    'PG': 'Procter Gamble',
    'CL': 'Colgate-Palmolive',
    'GE': 'General Electrics',
}
symbols, names = np.array(sorted(symbol_dict.items())).T

quotes = []

for symbol in symbols:
    print('Fetching quote history for %r' % symbol, file=sys.stderr)
    url = ('https://raw.githubusercontent.com/scikit-learn/examples-data/master/financial-data/{}.csv'.format(symbol))
    quotes.append(pd.read_csv(url))

close_prices = np.vstack([q['close'] for q in quotes])
open_prices = np.vstack([q['open'] for q in quotes])

# The daily variations of the quotes are what carry most information
variation = close_prices - open_prices

# Learn a graphical structure from the correlations
edge_model = covariance.GraphicalLassoCV()

# standardize the time series: using correlations rather than covariance
# is more efficient for structure recovery
X = variation.copy().T
X /= X.std(axis=0)
edge_model.fit(X)

# Cluster using affinity propagation
_, labels = cluster.affinity_propagation(edge_model.covariance_,}
n_labels = labels.max()

for i in range(n_labels + 1):
    print('Cluster %i: %s' % ((i + 1), ', '.join(names[labels == i])))

# Get the nodes (the stocks) on a 2D plane

# We use a dense eigen_solver to achieve reproducibility (arpack is
# initiated with random vectors that we don't control). In addition, we
# use a large number of neighbors to capture the large-scale structure.
node_position_model = manifold.LocallyLinearEmbedding(
    n_components=2, eigen_solver='dense', n_neighbors=6)

embedding = node_position_model.fit_transform(X.T).T

# Add a label to each node. The challenge here is that we want to
# position the labels to avoid overlap with other labels
for index, (name, label, (x, y)) in enumerate(
    zip(names, labels, embedding.T)):
    dx = x - embedding[0]
    dx[index] = 1
dy = y - embedding[1]
dy[index] = 1
this_dx = dx[np.argmin(np.abs(dy))]
this_dy = dy[np.argmin(np.abs(dx))]
    if this_dx > 0:
        horizontalalignment = 'left'
        x = x + .002
    else:
        horizontalalignment = 'right'
        x = x - .002
    if this_dy > 0:
        verticalalignment = 'bottom'
        y = y + .002
    else:
        verticalalignment = 'top'
        y = y - .002
plt.text(x, y, name, size=10,
        horizontalalignment=horizontalalignment,
        verticalalignment=verticalalignment,
        bbox=dict(facecolor='w',
                    edgecolor=plt.cm.nipy_spectral(label / float(n_labels)),
                    alpha=.6))

plt.xlim(embedding[0].min() - .15 * embedding[0].ptp(),
        embedding[0].max() + .10 * embedding[0].ptp(),)
plt.ylim(embedding[1].min() - .03 * embedding[1].ptp(),
        embedding[1].max() + .03 * embedding[1].ptp())
plt.show()

**Total running time of the script:** (0 minutes 5.417 seconds)

6.12.7 Wikipedia principal eigenvector

A classical way to assert the relative importance of vertices in a graph is to compute the principal eigenvector of the adjacency matrix so as to assign to each vertex the values of the components of the first eigenvector as a centrality score:

https://en.wikipedia.org/wiki/Eigenvector_centrality

On the graph of webpages and links those values are called the PageRank scores by Google.

The goal of this example is to analyze the graph of links inside wikipedia articles to rank articles by relative importance according to this eigenvector centrality.

The traditional way to compute the principal eigenvector is to use the power iteration method:

https://en.wikipedia.org/wiki/Power_iteration

Here the computation is achieved thanks to Martinsson’s Randomized SVD algorithm implemented in scikit-learn.

The graph data is fetched from the DBpedia dumps. DBpedia is an extraction of the latent structured data of the Wikipedia content.

# Author: Olivier Grisel <olivier.grisel@ensta.org>
# License: BSD 3 clause
from `bz2` import `BZ2File`
import `os`
from `datetime` import `datetime`
from `pprint` import `pprint`
from `time` import `time`

import `numpy` as `np`

from `scipy` import `sparse`
from `sklearn.decomposition` import `randomized_svd`
from `urllib.request` import `urlopen`

print(__doc__)

# #############################################################################
# Where to download the data, if not already on disk
redirects_url = "http://downloads.dbpedia.org/3.5.1/en/redirects_en.nt.bz2"
redirects_filename = redirects_url.rsplit("/", 1)[1]

page_links_url = "http://downloads.dbpedia.org/3.5.1/en/page_links_en.nt.bz2"
page_links_filename = page_links_url.rsplit("/", 1)[1]

resources = [
    (redirects_url, redirects_filename),
    (page_links_url, page_links_filename),
]

for url, filename in resources:
    if not `os.path.exists`(filename):
        print("Downloading data from ' %s', please wait..." % url)
        opener = `urlopen`(url)
        open(filename, 'wb').write(opener.read())
        print()

# #############################################################################
# Loading the redirect files

def index(redirects, index_map, k):
    """Find the index of an article name after redirect resolution""
    k = redirects.get(k, k)
    return index_map.setdefault(k, len(index_map))

DBPEDIA_RESOURCE_PREFIX_LEN = len("http://dbpedia.org/resource/")
SHORTNAME_SLICE = slice(DBPEDIA_RESOURCE_PREFIX_LEN + 1, -1)

def short_name(nt_uri):
    """Remove the < and > URI markers and the common URI prefix""
    return nt_uri[SHORTNAME_SLICE]

def get_redirects(redirects_filename):
    (continues on next page)
Parse the redirections and build a transitively closed map out of it

```python
redirects = {}  
print("Parsing the NT redirect file")
for l, line in enumerate(BZ2File(redirects_filename)):
    split = line.split()
    if len(split) != 4:
        print("ignoring malformed line: " + line)
        continue
    redirects[short_name(split[0])] = short_name(split[2])
    if l % 100000 == 0:
        print("[%s] line: %08d % (datetime.now().isoformat(), l))

# compute the transitive closure
print("Computing the transitive closure of the redirect relation")
for l, source in enumerate(redirects.keys()):
    transitive_target = None
    target = redirects[source]
    seen = {source}
    while True:
        transitive_target = target
        target = redirects.get(target)
        if target is None or target in seen:
            break
        seen.add(target)
    redirects[source] = transitive_target
    if l % 100000 == 0:
        print("[%s] line: %08d % (datetime.now().isoformat(), l))

return redirects
```

def get_adjacency_matrix(redirects_filename, page_links_filename, limit=None):
    """Extract the adjacency graph as a scipy sparse matrix
    Redirects are resolved first.
    Returns X, the scipy sparse adjacency matrix, redirects as python
dict from article names to article names and index_map a python dict
from article names to python int (article indexes).
    ""

    print("Computing the redirect map")
    redirects = get_redirects(redirects_filename)

    print("Computing the integer index map")
    index_map = dict()
    links = list()
    for l, line in enumerate(BZ2File(page_links_filename)):
        split = line.split()
        if len(split) != 4:
            print("ignoring malformed line: " + line)
            continue
        i = index(redirects, index_map, short_name(split[0]))
        j = index(redirects, index_map, short_name(split[2]))
        links.append((i, j))
        if l % 100000 == 0:
            print("[%s] line: %08d % (datetime.now().isoformat(), l))
```

(continues on next page)
if limit is not None and l >= limit - 1:
    break

print("Computing the adjacency matrix")
X = sparse.lil_matrix((len(index_map), len(index_map)), dtype=np.float32)
for i, j in links:
    X[i, j] = 1.0
del links
print("Converting to CSR representation")
X = X.tocsr()
print("CSR conversion done")
return X, redirects, index_map

# stop after 5M links to make it possible to work in RAM
X, redirects, index_map = get_adjacency_matrix(redirects_filename, page_links_filename, limit=5000000)
names = {i: name for name, i in index_map.items()}

print("Computing the principal singular vectors using randomized_svd")
t0 = time()
U, s, V = randomized_svd(X, 5, n_iter=3)
print("done in %0.3f s" % (time() - t0))

# print the names of the wikipedia related strongest components of the
# principal singular vector which should be similar to the highest eigenvector
print("Top wikipedia pages according to principal singular vectors")
pprint([names[i] for i in np.abs(U.T[0]).argsort()[-10:]])
pprint([names[i] for i in np.abs(V[0]).argsort()[-10:]])

def centrality_scores(X, alpha=0.85, max_iter=100, tol=1e-10):
    """Power iteration computation of the principal eigenvector

    This method is also known as Google PageRank and the implementation
    is based on the one from the NetworkX project (BSD licensed too)
    with copyrights by:

    Aric Hagberg <hagberg@lanl.gov>
    Dan Schult <dschult@colgate.edu>
    Pieter Swart <swart@lanl.gov>
    """
    n = X.shape[0]
    X = X.copy()
incoming_counts = np.asarray(X.sum(axis=1)).ravel()

    print("Normalizing the graph")
    for i in incoming_counts.nonzero()[0]:
        X.data[X.indptr[i]:X.indptr[i + 1]] *= 1.0 / incoming_counts[i]
dangle = np.asarray(np.where(np.isclose(X.sum(axis=1), 0),
                            1.0 / n, 0)).ravel()

    scores = np.full(n, 1. / n, dtype=np.float32) # initial guess
    for i in range(max_iter):
        print("power iteration #\$d" % i)
        prev_scores = scores
        scores = alpha * X.dot(scores) + (1 - alpha) * dangle
scores = (alpha * (scores * X + np.dot(dangle, prev_scores))
          + (1 - alpha) * prev_scores.sum() / n)

# check convergence: normalized l_inf norm
scores_max = np.abs(scores).max()
if scores_max == 0.0:
    scores_max = 1.0
err = np.abs(scores - prev_scores).max() / scores_max
print("error: \$%.6f\$" % err)
if err < n * tol:
    return scores

print("Computing principal eigenvector score using a power iteration method")
t0 = time()
scores = centrality_scores(X, max_iter=100)
print("done in \$%.3fs\$" % (time() - t0))
pprint([names[i] for i in np.abs(scores).argsort()[-10:]]

Total running time of the script: 0 minutes 0.000 seconds

### 6.12.8 Species distribution modeling

Modeling species’ geographic distributions is an important problem in conservation biology. In this example we model the geographic distribution of two south american mammals given past observations and 14 environmental variables. Since we have only positive examples (there are no unsuccessful observations), we cast this problem as a density estimation problem and use the `OneClassSVM` as our modeling tool. The dataset is provided by Phillips et. al. (2006). If available, the example uses `basemap` to plot the coast lines and national boundaries of South America.

The two species are:

- “Bradypus variegatus”, the Brown-throated Sloth.
- “Microryzomys minutus”, also known as the Forest Small Rice Rat, a rodent that lives in Peru, Colombia, Ecuador, Peru, and Venezuela.

**References**

Modeling distribution of species 'bradypus variegatus'
- fit OneClassSVM ... done.
- plot coastlines from coverage
- predict species distribution

Area under the ROC curve : 0.868443

Modeling distribution of species 'microryzomys minutus'
- fit OneClassSVM ... done.
- plot coastlines from coverage
- predict species distribution

Area under the ROC curve : 0.993919

time elapsed: 9.76s
# Jake Vanderplas <vanderplas@astro.washington.edu>
# License: BSD 3 clause

from time import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn.utils import Bunch
from sklearn.datasets import fetch_species_distributions
from sklearn import svm, metrics

# if basemap is available, we'll use it.
# otherwise, we'll improvise later...
try:
    from mpl_toolkits.basemap import Basemap
    basemap = True
except ImportError:
    basemap = False

print(__doc__)

def construct_grids(batch):
    """Construct the map grid from the batch object
    Parameters
    ----------
    batch : Batch object
        The object returned by :func:`fetch_species_distributions`
    Returns
    -------
    (xgrid, ygrid) : 1-D arrays
        The grid corresponding to the values in batch.coverages
    """
    # x,y coordinates for corner cells
    xmin = batch.x_left_lower_corner + batch.grid_size
    xmax = xmin + (batch.Nx * batch.grid_size)
    ymin = batch.y_left_lower_corner + batch.grid_size
    ymax = ymin + (batch.Ny * batch.grid_size)

    # x coordinates of the grid cells
    xgrid = np.arange(xmin, xmax, batch.grid_size)
    # y coordinates of the grid cells
    ygrid = np.arange(ymin, ymax, batch.grid_size)

    return (xgrid, ygrid)

def create_species_bunch(species_name, train, test, coverages, xgrid, ygrid):
    """Create a bunch with information about a particular organism
    This will use the test/train record arrays to extract the
    data specific to the given species name.
    """
bunch = Bunch(name=' '.join(species_name.split('_')[:2]))
species_name = species_name.encode('ascii')
points = dict(test=test, train=train)

for label, pts in points.items():
    # choose points associated with the desired species
    pts = pts[pts['species'] == species_name]
    bunch['pts_%s' % label] = pts

    # determine coverage values for each of the training & testing points
    ix = np.searchsorted(xgrid, pts['dd long'])
    iy = np.searchsorted(ygrid, pts['dd lat'])
    bunch['cov_%s' % label] = coverages[:, -iy, ix].T

return bunch

def plot_species_distribution(species=("bradypus_variegatus_0",
                                 "microryzomys_minutus_0")):
    ""
    Plot the species distribution.
    ""
    if len(species) > 2:
        print("Note: when more than two species are provided,"
              " only the first two will be used")

    t0 = time()

    # Load the compressed data
    data = fetch_species_distributions()

    # Set up the data grid
    xgrid, ygrid = construct_grids(data)

    # The grid in x, y coordinates
    X, Y = np.meshgrid(xgrid, ygrid[::-1])

    # create a bunch for each species
    BV_bunch = create_species_bunch(species[0],
                                     data.train, data.test,
                                     data.coverages, xgrid, ygrid)
    MM_bunch = create_species_bunch(species[1],
                                     data.train, data.test,
                                     data.coverages, xgrid, ygrid)

    # background points (grid coordinates) for evaluation
    np.random.seed(13)
    background_points = np.c_[np.random.randint(low=0, high=data.Ny,
                                            size=10000),
                             np.random.randint(low=0, high=data.Nx,
                                                size=10000)].T

    # We'll make use of the fact that coverages[6] has measurements at all
    # land points. This will help us decide between land and water.
    land_reference = data.coverages[6]

    # Fit, predict, and plot for each species.
for i, species in enumerate([BV_bunch, MM_bunch]):
    print("" * 80)
    print("Modeling distribution of species '{}" % species.name)

    # Standardize features
    mean = species.cov_train.mean(axis=0)
    std = species.cov_train.std(axis=0)
    train_cover_std = (species.cov_train - mean) / std

    # Fit OneClassSVM
    print(" - fit OneClassSVM ... ", end='')
    clf = svm.OneClassSVM(nu=0.1, kernel="rbf", gamma=0.5)
    clf.fit(train_cover_std)
    print("done.")

    # Plot map of South America
    plt.subplot(1, 2, i + 1)
    if basemap:
        print(" - plot coastlines using basemap")
        m = Basemap(projection='cyl', llcrnrlat=Y.min(),
                    urcrnrlat=Y.max(), llcrnrlon=X.min(),
                    urcrnrlon=X.max(), resolution='c')
        m.drawcoastlines()
        m.drawcountries()
    else:
        print(" - plot coastlines from coverage")
        plt.contour(X, Y, land_reference,
                    levels=[-9998], colors="k",
                    linestyles="solid")
        plt.xticks([])
        plt.yticks([])

    print(" - predict species distribution")

    # Predict species distribution using the training data
    Z = np.ones((data.Ny, data.Nx), dtype=np.float64)
    # We'll predict only for the land points.
    idx = np.where(land_reference > -9999)
    coverages_land = data.coverages[:, idx[0], idx[1]].T
    pred = clf.decision_function((coverages_land - mean) / std)
    Z *= pred.min()
    Z[idx[0], idx[1]] = pred

    levels = np.linspace(Z.min(), Z.max(), 25)
    Z[land_reference == -9999] = -9999

    # plot contours of the prediction
    plt.contourf(X, Y, Z, levels=levels, cmap=plt.cm.Reds)
    plt.colorbar(format='%.2f')

    # scatter training/testing points
    plt.scatter(species.pts_train['dd long'], species.pts_train['dd lat'],
                s=2 ** 2, c='black', marker='^', label='train')
    plt.scatter(species.pts_test['dd long'], species.pts_test['dd lat'],
                s=2 ** 2, c='black', marker='^', label='test')
s = 2 ** 2, c = 'black',
     marker = 'x', label = 'test')
plt.legend()
plt.title(species.name)
plt.axis('equal')

# Compute AUC with regards to background points
pred_background = Z[background_points[0], background_points[1]]
pred_test = clf.decision_function((species.cov_test - mean) / std)
scores = np.r_[pred_test, pred_background]
y = np.r_[np.ones(pred_test.shape), np.zeros(pred_background.shape)]
fc, fpr, thresholds = metrics.roc_curve(y, scores)
roc_auc = metrics.auc(fpr, tpr)
plt.text(-35, -70, "AUC: %.3f" % roc_auc, ha="right")
print("Area under the ROC curve : %.f" % roc_auc)

plt.show()

Total running time of the script: (0 minutes 9.940 seconds)

6.12.9 Libsvm GUI

A simple graphical frontend for Libsvm mainly intended for didactic purposes. You can create data points by point
and click and visualize the decision region induced by different kernels and parameter settings.

To create positive examples click the left mouse button; to create negative examples click the right button.

If all examples are from the same class, it uses a one-class SVM.

print(__doc__)

# Author: Peter Prettenhoer <peter.prettenhofer@gmail.com>
#
# License: BSD 3 clause

import matplotlib
matplotlib.use('TkAgg')
from matplotlib.backends.backend_tkagg import FigureCanvasTkAgg
try:
    from matplotlib.backends.backend_tkagg import NavigationToolbar2Tk
except ImportError:
    # NavigationToolbar2TkAgg was deprecated in matplotlib 2.2
    from matplotlib.backends.backend_tkagg import (NavigationToolbar2TkAgg as NavigationToolbar2Tk)
from matplotlib.figure import Figure
from matplotlib.contour import ContourSet

import sys
import numpy as np
import tkinter as Tk
from sklearn import svm
from sklearn.datasets import dump_svmlight_file

y_min, y_max = -50, 50
x_min, x_max = -50, 50

class Model:
    """The Model which hold the data. It implements the observable in the observer pattern and notifies the registered observers on change event. """
    def __init__(self):
        self.observers = []
        self.surface = None
        self.data = []
        self.cls = None
        self.surface_type = 0

    def changed(self, event):
        """Notify the observers. """
        for observer in self.observers:
            observer.update(event, self)

    def add_observer(self, observer):
        """Register an observer. """
        self.observers.append(observer)

    def set_surface(self, surface):
        self.surface = surface

    def dump_svmlight_file(self, file):
        data = np.array(self.data)
        X = data[:, 0:2]
        y = data[:, 2]
        dump_svmlight_file(X, y, file)

class Controller:
    def __init__(self, model):
        self.model = model
        self.kernel = Tk.IntVar()
        self.surface_type = Tk.IntVar()
        # Whether or not a model has been fitted
        self.fitted = False

    def fit(self):
        print("fit the model")
        train = np.array(self.model.data)
        X = train[:, 0:2]
        y = train[:, 2]

        C = float(self.complexity.get())
        gamma = float(self.gamma.get())
        coef0 = float(self.coef0.get())
        degree = int(self.degree.get())
kernel_map = {0: "linear", 1: "rbf", 2: "poly"}
if len(np.unique(y)) == 1:
    clf = svm.OneClassSVM(kernel=kernel_map[self.kernel.get()],
                          gamma=gamma, coef0=coef0, degree=degree)
    clf.fit(X)
else:
    clf = svm.SVC(kernel=kernel_map[self.kernel.get()], C=C,
                  gamma=gamma, coef0=coef0, degree=degree)
    clf.fit(X, y)
if hasattr(clf, 'score'):
    print("Accuracy:", clf.score(X, y) * 100)
X1, X2, Z = self.decision_surface(clf)
self.model.clf = clf
self.model.set_surface((X1, X2, Z))
self.model.surface_type = self.surface_type.get()
self.fitted = True
self.model.changed("surface")

def decision_surface(self, cls):
    delta = 1
    x = np.arange(x_min, x_max + delta, delta)
    y = np.arange(y_min, y_max + delta, delta)
    X1, X2 = np.meshgrid(x, y)
    Z = cls.decision_function(np.c_[X1.ravel(), X2.ravel()])
    Z = Z.reshape(X1.shape)
    return X1, X2, Z

def clear_data(self):
    self.model.data = []
    self.fitted = False
    self.model.changed("clear")

def add_example(self, x, y, label):
    self.model.data.append((x, y, label))
    self.model.changed("example_added")
    # update decision surface if already fitted.
    self.refit()

def refit(self):
    
    if self.fitted:
        self.fit()
except AttributeError:
    # support for matplotlib (1.*)
    canvas.show()

canvas.get_tk_widget().pack(side=Tk.TOP, fill=Tk.BOTH, expand=1)

canvas._tkcanvas.pack(side=Tk.TOP, fill=Tk.BOTH, expand=1)

canvas.mpl_connect('button_press_event', self.onclick)

toolbar = NavigationToolbar2Tk(canvas, root)

toolbar.update()

self.controllbar = ControllBar(root, controller)

self.f = f

self.ax = ax

self.canvas = canvas

self.controller = controller

self.contours = []

self.c_labels = None

self.plot_kernels()

def plot_kernels(self):
    self.ax.text(-50, -60, r"Linear: $u^T v$"
    self.ax.text(-20, -60, r"RBF: $\exp (-\gamma \| u-v \|^2)$"
    self.ax.text(10, -60, r"Poly: $(\gamma \, u^T v + r)^d$"


def onclick(self, event):
    if event.xdata and event.ydata:
        if event.button == 1:
            self.controller.add_example(event.xdata, event.ydata, 1)
        elif event.button == 3:
            self.controller.add_example(event.xdata, event.ydata, -1)


def update_example(self, model, idx):
    x, y, l = model.data[idx]
    if l == 1:
        color = 'w'
    elif l == -1:
        color = 'k'
    self.ax.plot([x], [y], "%so % color, scalex=0.0, scaley=0.0"


def update(self, event, model):
    if event == "examples_loaded":
        for i in range(len(model.data)):
            self.update_example(model, i)

    if event == "example_added":
        self.update_example(model, -1)

    if event == "clear":
        self.ax.clear()
        self.ax.set_xticks([])
        self.ax.set_yticks([])
        self.contours = []
        self.c_labels = None
        self.plot_kernels()

    if event == "surface":
        self.remove_surface()
        self.plot_support_vectors(model.clf.support_vectors_)
        self.plot_decision_surface(model.surface, model.surface_type)
def remove_surface(self):
    """Remove old decision surface.""
    if len(self.contours) > 0:
        for contour in self.contours:
            if isinstance(contour, ContourSet):
                for lineset in contour.collections:
                    lineset.remove()
            else:
                contour.remove()
        self.contours = []
    self.canvas.draw()

def plot_support_vectors(self, support_vectors):
    """Plot the support vectors by placing circles over the corresponding data points and adds the circle collection to the contours list.""
    cs = self.ax.scatter(support_vectors[:, 0], support_vectors[:, 1], s=80, edgecolors="k", facecolors="none")
    self.contours.append(cs)

def plot_decision_surface(self, surface, type):
    X1, X2, Z = surface
    if type == 0:
        levels = [-1.0, 0.0, 1.0]
        linestyles = ['dashed', 'solid', 'dashed']
        colors = 'k'
        self.contours.append(self.ax.contour(X1, X2, Z, levels, colors=colors, linestyles=linestyles))
    elif type == 1:
        self.contours.append(self.ax.contourf(X1, X2, Z, 10, cmap=matplotlib.cm.bone, origin='lower', alpha=0.85))
        self.contours.append(self.ax.contour(X1, X2, Z, [0.0], colors='k', linestyles=['solid']))
    else:
        raise ValueError("surface type unknown")

class ControllBar:
    def __init__(self, root, controller):
        fm = Tk.Frame(root)
        kernel_group = Tk.Frame(fm)
        Tk.Radiobutton(kernel_group, text="Linear", variable=controller.kernel, value=0, command=controller.refit).pack(anchor=Tk.W)
        Tk.Radiobutton(kernel_group, text="RBF", variable=controller.kernel, value=1, command=controller.refit).pack(anchor=Tk.W)
        Tk.Radiobutton(kernel_group, text="Poly", variable=controller.kernel, value=2, command=controller.refit).pack(anchor=Tk.W)
        kernel_group.pack(side=Tk.LEFT)

        valbox = Tk.Frame(fm)
        controller.complexity = Tk.StringVar()
        controller.complexity.set("1.0")
        c = Tk.Frame(valbox)
Tk.Label(c, text="C:", anchor="e", width=7).pack(side=Tk.LEFT)
Tk.Entry(c, width=6, textvariable=controller.complexity).pack(
    side=Tk.LEFT)
c.pack()

controller.gamma = Tk.StringVar()
controller.gamma.set("0.01")
g = Tk.Frame(valbox)
Tk.Label(g, text="gamma:", anchor="e", width=7).pack(side=Tk.LEFT)
Tk.Entry(g, width=6, textvariable=controller.gamma).pack(side=Tk.LEFT)
g.pack()

controller.degree = Tk.StringVar()
controller.degree.set("3")
d = Tk.Frame(valbox)
Tk.Label(d, text="degree:", anchor="e", width=7).pack(side=Tk.LEFT)
Tk.Entry(d, width=6, textvariable=controller.degree).pack(side=Tk.LEFT)
d.pack()

controller.coef0 = Tk.StringVar()
controller.coef0.set("0")
r = Tk.Frame(valbox)
Tk.Label(r, text="coef0:", anchor="e", width=7).pack(side=Tk.LEFT)
Tk.Entry(r, width=6, textvariable=controller.coef0).pack(side=Tk.LEFT)
r.pack()
valbox.pack(side=Tk.LEFT)

cmap_group = Tk.Frame(fm)
Tk.Radiobutton(cmap_group, text="Hyperplanes",
    variable=controller.surface_type, value=0,
    command=controller.refit).pack(anchor=Tk.W)
Tk.Radiobutton(cmap_group, text="Surface",
    variable=controller.surface_type, value=1,
    command=controller.refit).pack(anchor=Tk.W)
cmap_group.pack(side=Tk.LEFT)

train_button = Tk.Button(fm, text='Fit', width=5,
    command=controller.fit)
train_button.pack()
fm.pack(side=Tk.LEFT)
Tk.Button(fm, text='Clear', width=5,
    command=controller.clear_data).pack(side=Tk.LEFT)

def get_parser():
    from optparse import OptionParser
    op = OptionParser()
    op.add_option("--output",
        action="store", type="str", dest="output",
        help="Path where to dump data.")
    return op

def main(argv):
    op = get_parser()
    opts, args = op.parse_args(argv[1:])

(continues on next page)
root = Tk.Tk()
model = Model()
controller = Controller(model)
root.wm_title("Scikit-learn Libsvm GUI")
view = View(root, controller)
model.add_observer(view)
Tk.mainloop()

if opts.output:
    model.dump_svmlight_file(opts.output)

if __name__ == "__main__":
    main(sys.argv)

Total running time of the script: ( 0 minutes 0.000 seconds)

6.12.10 Prediction Latency

This is an example showing the prediction latency of various scikit-learn estimators.
The goal is to measure the latency one can expect when doing predictions either in bulk or atomic (i.e. one by one) mode.
The plots represent the distribution of the prediction latency as a boxplot.

![Prediction Time per Instance - Atomic, 100 feats.](chart)

- Linear Model (10 non-zero coefficients)
- RandomForest (100 estimators)
- SVR (695 support vectors)
6.12. Examples based on real world datasets

### Prediction Time per Instance - Bulk (100), 100 feats.

- **Linear Model**
  - (10 non-zero coefficients)
- **RandomForest**
  - (100 estimators)
- **SVR**
  - (695 support vectors)

### Evolution of Prediction Time with #Features

- Prediction Time at 10%ile (μs)
- #Features
Out:

Benchmarking SGDRegressor(alpha=0.01, l1_ratio=0.25, penalty='elasticnet', tol=0.0001)
Benchmarking RandomForestRegressor()
Benchmarking SVR()
benchmarking with 100 features
benchmarking with 250 features
benchmarking with 500 features
example run in 11.05s

from collections import defaultdict
import time
import gc
import numpy as np
import matplotlib.pyplot as plt
from sklearn.preprocessing import StandardScaler
from sklearn.model_selection import train_test_split
from sklearn.datasets import make_regression
from sklearn.ensemble import RandomForestRegressor
from sklearn.linear_model import Ridge
from sklearn.linear_model import SGDRegressor
from sklearn.svm import SVR
from sklearn.utils import shuffle
def _not_in_sphinx():
    # Hack to detect whether we are running by the sphinx builder
    return '__file__' in globals()

def atomic_benchmark_estimator(estimator, X_test, verbose=False):
    """Measure runtime prediction of each instance."""
    n_instances = X_test.shape[0]
    runtimes = np.zeros(n_instances, dtype=float)
    for i in range(n_instances):
        instance = X_test[[i], :]
        start = time.time()
        estimator.predict(instance)
        runtimes[i] = time.time() - start
    if verbose:
        print("atomic_benchmark runtimes:",
              min(runtimes), np.percentile(
              runtimes, 50),
              max(runtimes))
    return runtimes

def bulk_benchmark_estimator(estimator, X_test, n_bulk_repeats, verbose):
    """Measure runtime prediction of the whole input."""
    n_instances = X_test.shape[0]
    runtimes = np.zeros(n_bulk_repeats, dtype=float)
    for i in range(n_bulk_repeats):
        start = time.time()
        estimator.predict(X_test)
        runtimes[i] = time.time() - start
    runtimes = np.array(list(map(lambda x: x / float(n_instances), runtimes)))
    if verbose:
        print("bulk_benchmark runtimes:",
              min(runtimes), np.percentile(
              runtimes, 50),
              max(runtimes))
    return runtimes

def benchmark_estimator(estimator, X_test, n_bulk_repeats=30, verbose=False):
    """
    Measure runtimes of prediction in both atomic and bulk mode.
    """
    Parameters
    ----------
estimator : already trained estimator supporting `predict`
X_test : test input
n_bulk_repeats : how many times to repeat when evaluating bulk mode

    Returns
    -------
atomic_runtimes, bulk_runtimes : a pair of `np.array` which contain the
runtimes in seconds.
    """
    atomic_runtimes = atomic_benchmark_estimator(estimator, X_test, verbose)
    bulk_runtimes = bulk_benchmark_estimator(estimator, X_test, n_bulk_repeats,
                                            verbose)
    return atomic_runtimes, bulk_runtimes

(continues on next page)
def generate_dataset(n_train, n_test, n_features, noise=0.1, verbose=False):
    """Generate a regression dataset with the given parameters."""
    if verbose:
        print("generating dataset...")

    X, y, coef = make_regression(n_samples=n_train + n_test,
                                n_features=n_features, noise=noise, coef=True)

    random_seed = 13
    X_train, X_test, y_train, y_test = train_test_split(
        X, y, train_size=n_train, test_size=n_test, random_state=random_seed)
    X_train, y_train = shuffle(X_train, y_train, random_state=random_seed)

    X_scaler = StandardScaler()
    X_train = X_scaler.fit_transform(X_train)
    X_test = X_scaler.transform(X_test)

    y_scaler = StandardScaler()
    y_train = y_scaler.fit_transform(y_train[:, None])[:, 0]
    y_test = y_scaler.transform(y_test[:, None])[:, 0]
    gc.collect()

    if verbose:
        print("ok")
    return X_train, y_train, X_test, y_test

def boxplot_runtimes(runtimes, pred_type, configuration):
    """
    Plot a new `Figure` with boxplots of prediction runtimes.

    Parameters
    ----------
    runtimes : list of `np.array` of latencies in micro-seconds
    cls_names : list of estimator class names that generated the runtimes
    pred_type : 'bulk' or 'atomic'
    """

    fig, ax1 = plt.subplots(figsize=(10, 6))
    bp = plt.boxplot(runtimes, )

    cls_infos = ["%s\n    estimator_conf['name'],
    estimator_conf['complexity_computer'](estimator_conf['instance']),
    estimator_conf['complexity_label']) for estimator_conf in configuration['estimators']]

    plt.setp(ax1, xticklabels=cls_infos)
    plt.setp(bp['boxes'], color='black')
    plt.setp(bp['whiskers'], color='black')
    plt.setp(bp['fliers'], color='red', marker='+')
    ax1.yaxis.grid(True, linestyle='-', which='major', color='lightgrey', alpha=0.5)
def benchmark(configuration):
    """Run the whole benchmark."""
    X_train, y_train, X_test, y_test = generate_dataset(
        configuration['n_train'], configuration['n_test'],
        configuration['n_features'])

    stats = {}  # (continued from previous page)
    for estimator_conf in configuration['estimators']:
        print("Benchmarking", estimator_conf['instance'])
        estimator_conf['instance'].fit(X_train, y_train)
        gc.collect()
        a, b = benchmark_estimator(estimator_conf['instance'], X_test)
        stats[estimator_conf['name']] = {'atomic': a, 'bulk': b}

    cls_names = [estimator_conf['name'] for estimator_conf in configuration['estimators']]
    runtimes = [1e6 * stats[clf_name]['atomic'] for clf_name in cls_names]
    boxplot_runtimes(runtimes, 'atomic', configuration)
    runtimes = [1e6 * stats[clf_name]['bulk'] for clf_name in cls_names]
    boxplot_runtimes(runtimes, 'bulk (%d)' % configuration['n_test'], configuration)

def n_feature_influence(estimators, n_train, n_test, n_features, percentile):
    """Estimate influence of the number of features on prediction time.

    Parameters
    ----------
    estimators : dict of (name (str), estimator) to benchmark
    n_train : number of training instances (int)
    n_test : number of testing instances (int)
    n_features : list of feature-space dimensionality to test (int)
    percentile : percentile at which to measure the speed (int [0-100])

    Returns:
    -------

    percentiles : dict(estimate_name,
                       dict(n_features, percentile_perf_in_us))
    """

    percentiles = defaultdict(defaultdict)
    for n in n_features:
        print("benchmarking with %d features" % n)
        X_train, y_train, X_test, y_test = generate_dataset(n_train, n_test, n)
        for cls_name, estimator in estimators.items():
            (continues on next page)
estimator.fit(X_train, y_train)
gc.collect()

runtimes = bulk_benchmark_estimator(estimator, X_test, 30, False)
percentiles[cls_name][n] = 1e6 * np.percentile(runtimes,
percentile)

return percentiles

def plot_n_features_influence(percentiles, percentile):
    fig, ax1 = plt.subplots(figsize=(10, 6))
    colors = ['r', 'g', 'b']
    for i, cls_name in enumerate(percentiles.keys()):
        x = np.array(sorted([n for n in percentiles[cls_name].keys()]))
        y = np.array([percentiles[cls_name][n] for n in x])
        plt.plot(x, y, color=colors[i],
        ax1.yaxis.grid(True, linestyle='-', which='major', color='lightgrey',
                        alpha=0.5)
        ax1.set_axisbelow(True)
        ax1.set_title('Evolution of Prediction Time with #Features')
        ax1.set_xlabel('#Features')
        ax1.set_ylabel('Prediction Time at %d%%-ile (us)' % percentile)
    plt.show()

def benchmark_throughputs(configuration, duration_secs=0.1):
    """benchmark throughput for different estimators."""
    X_train, y_train, X_test, y_test = generate_dataset(
        configuration['n_train'], configuration['n_test'],
        configuration['n_features'])
    throughputs = dict()
    for estimator_config in configuration['estimators']:
        estimator_config['instance'].fit(X_train, y_train)
        start_time = time.time()
        n_predictions = 0
        while (time.time() - start_time) < duration_secs:
            estimator_config['instance'].predict(X_test[[0]])
            n_predictions += 1
        throughputs[estimator_config['name']] = n_predictions / duration_secs
    return throughputs

def plot_benchmark_throughput(throughputs, configuration):
    fig, ax = plt.subplots(figsize=(10, 6))
    colors = ['r', 'g', 'b']
    cls_infos = ['%s
    estimator_conf['complexity_computer'],
                    estimator_conf['instance'],
                    estimator_conf['complexity_label']] for
    estimator_conf in configuration['estimators']
    cls_values = [throughputs[estimator_conf['name']] for estimator_conf in
                    configuration['estimators']]
    plt.bar(range(len(throughputs)), cls_values, width=0.5, color=colors)
    ax.set_xticks(np.linspace(0.25, len(throughputs) - 0.75, len(throughputs)))
    ax.set_xticklabels(cls_infos, fontsize=10)
    ymin = max(cls_values) * 1.2
    ax.set_ylim((0, ymax))
    ax.set_ylabel('Throughput (predictions/sec)')
ax.set_title('Prediction Throughput for different estimators (%d ' +
'features) % configuration['n_features'])
plt.show()

# # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # #
# Main code
start_time = time.time()

# # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # # #
# Benchmark bulk/atomic prediction speed for various regressors
configuration = {
    'n_train': int(1e3),
    'n_test': int(1e2),
    'n_features': int(1e2),
    'estimators': [
        {'name': 'Linear Model',
         'instance': SGDRegressor(penalty='elasticnet', alpha=0.01,
                                  l1_ratio=0.25, tol=1e-4),
         'complexity_label': 'non-zero coefficients',
         'complexity_computer': lambda clf: np.count_nonzero(clf.coef_),
        }
        {'name': 'RandomForest',
         'instance': RandomForestRegressor(),
         'complexity_label': 'estimators',
         'complexity_computer': lambda clf: clf.n_estimators},
        {'name': 'SVR',
         'instance': SVR(kernel='rbf'),
         'complexity_label': 'support vectors',
         'complexity_computer': lambda clf: len(clf.support_vectors_),
        }
    ]
}
benchmark(configuration)

# benchmark n_features influence on prediction speed
percentile = 90
percentiles = n_feature_influence({'ridge': Ridge()},
                                   configuration['n_train'],
                                   configuration['n_test'],
                                   [100, 250, 500], percentile)
plot_n_features_influence(percentiles, percentile)

# benchmark throughput
throughputs = benchmark_throughputs(configuration)
plot_benchmark_throughput(throughputs, configuration)

stop_time = time.time()
print("example run in %.2fs" % (stop_time - start_time))

total running time of the script: ( 0 minutes 11.413 seconds)
6.12.11 Out-of-core classification of text documents

This is an example showing how scikit-learn can be used for classification using an out-of-core approach: learning from data that doesn’t fit into main memory. We make use of an online classifier, i.e., one that supports the partial_fit method, that will be fed with batches of examples. To guarantee that the features space remains the same over time we leverage a HashingVectorizer that will project each example into the same feature space. This is especially useful in the case of text classification where new features (words) may appear in each batch.

```python
# Authors: Eustache Diemert <eustache@diemert.fr>
# @FedericoV <https://github.com/FedericoV/>
# License: BSD 3 clause

from glob import glob
import itertools
import os.path
import re
import tarfile
import time
import sys
import numpy as np
import matplotlib.pyplot as plt
from matplotlib import rcParams
from html.parser import HTMLParser
from urllib.request import urlretrieve
from sklearn.datasets import get_data_home
from sklearn.feature_extraction.text import HashingVectorizer
from sklearn.linear_model import SGDClassifier
from sklearn.linear_model import PassiveAggressiveClassifier
from sklearn.linear_model import Perceptron
from sklearn.naive_bayes import MultinomialNB

def _not_in_sphinx():
    # Hack to detect whether we are running by the sphinx builder
    return '__file__' in globals()

# Reuters Dataset related routines

The dataset used in this example is Reuters-21578 as provided by the UCI ML repository. It will be automatically downloaded and uncompressed on first run.

class ReutersParser(HTMLParser):
    """Utility class to parse a SGML file and yield documents one at a time."""

    def __init__(self, encoding='latin-1'):
        HTMLParser.__init__(self)
        self._reset()
        self.encoding = encoding

    def handle_starttag(self, self, tag, attrs):
        method = 'start_' + tag
        getattr(self, method, lambda x: None)(attrs)

    def handle_endtag(self, self, tag):
```

(continues on next page)
method = 'end_' + tag
getattr(self, method, lambda: None)()

def _reset(self):
    self.in_title = 0
    self.in_body = 0
    self.in_topics = 0
    self.in_topic_d = 0
    self.title = ""
    self.body = ""
    self.topics = []
    self.topic_d = ""

def parse(self, fd):
    self.docs = []
    for chunk in fd:
        self.feed(chunk.decode(self.encoding))
    for doc in self.docs:
        yield doc
    self.docs = []
    self.close()

def handle_data(self, data):
    if self.in_body:
        self.body += data
    elif self.in_title:
        self.title += data
    elif self.in_topic_d:
        self.topic_d += data

def start_reuters(self, attributes):
    pass

def end_reuters(self):
    self.body = re.sub(r'\s+', r' ', self.body)
    self.docs.append({'title': self.title,
                      'body': self.body,
                      'topics': self.topics})
    self._reset()

def start_title(self, attributes):
    self.in_title = 1

def end_title(self):
    self.in_title = 0

def start_body(self, attributes):
    self.in_body = 1

def end_body(self):
    self.in_body = 0

def start_topics(self, attributes):
    self.in_topics = 1

def end_topics(self):
    self.in_topics = 0
def start_d(self, attributes):
    self.in_topic_d = 1

def end_d(self):
    self.in_topic_d = 0
    self.topics.append(self.topic_d)
    self.topic_d = ""

def stream_reuters_documents(data_path=None):
    """Iterate over documents of the Reuters dataset.

    The Reuters archive will automatically be downloaded and uncompressed if
    the `data_path` directory does not exist.

    Documents are represented as dictionaries with 'body' (str),
    'title' (str), 'topics' (list(str)) keys.
    """

    'reuters21578-mld/reuters21578.tar.gz')
    ARCHIVE_FILENAME = 'reuters21578.tar.gz'

    if data_path is None:
        data_path = os.path.join(get_data_home(), "reuters")
    if not os.path.exists(data_path):
        """Download the dataset."""
        print("downloading dataset (once and for all) into $s" %
        data_path)
        os.mkdir(data_path)
    def progress(blocknum, bs, size):
        total_sz_mb = '%.2f MB' % (size / 1e6)
        current_sz_mb = '%.2f MB' % ((blocknum * bs) / 1e6)
        if _not_in_sphinx():
            sys.stdout.write(
                'downloaded $s / $s' % (current_sz_mb, total_sz_mb))
        archive_path = os.path.join(data_path, ARCHIVE_FILENAME)
        urlretrieve(DOWNLOAD_URL, filename=archive_path,
                    reporthook=progress)
        if _not_in_sphinx():
            sys.stdout.write('x')
        print("untarring Reuters dataset...")
        tarfile.open(archive_path, 'r:gz').extractall(data_path)
        print("done.")

    parser = ReutersParser()
    for filename in glob(os.path.join(data_path, "*.sgm")):
        for doc in parser.parse(open(filename, 'rb')):
            yield doc
Main

Create the vectorizer and limit the number of features to a reasonable maximum

```python
vectorizer = HashingVectorizer(decode_error='ignore', n_features=2 ** 18,
                                alternate_sign=False)
```

# Iterator over parsed Reuters SGML files.
data_stream = stream_reuters_documents()

# We learn a binary classification between the "acq" class and all the others.
# "acq" was chosen as it is more or less evenly distributed in the Reuters
# files. For other datasets, one should take care of creating a test set with
# a realistic portion of positive instances.
all_classes = np.array([0, 1])
positive_class = 'acq'

# Here are some classifiers that support the `partial_fit` method
partial_fit_classifiers = {
    'SGD': SGDClassifier(max_iter=5),
    'Perceptron': Perceptron(),
    'NB Multinomial': MultinomialNB(alpha=0.01),
    'Passive-Aggressive': PassiveAggressiveClassifier(),
}

def get_minibatch(doc_iter, size, pos_class=positive_class):
    """Extract a minibatch of examples, return a tuple X_text, y.
    Note: size is before excluding invalid docs with no topics assigned.
    """
    data = [('{title}'
              '{body}'.format(**doc), pos_class in doc['topics'])
            for doc in itertools.islice(doc_iter, size)
            if doc['topics']]
    if not len(data):
        return np.asarray([], dtype=int), np.asarray([], dtype=int)
    X_text, y = zip(*data)
    return X_text, np.asarray(y, dtype=int)

def iter_minibatches(doc_iter, minibatch_size):
    """Generator of minibatches.""
    X_text, y = get_minibatch(doc_iter, minibatch_size)
    while len(X_text):
        yield X_text, y
        X_text, y = get_minibatch(doc_iter, minibatch_size)

# test data statistics
test_stats = {'n_test': 0, 'n_test_pos': 0}

# First we hold out a number of examples to estimate accuracy
n_test_documents = 1000
tick = time.time()
X_test_text, y_test = get_minibatch(data_stream, 1000)
parsing_time = time.time() - tick
```

(continues on next page)
tick = time.time()
X_test = vectorizer.transform(X_test_text)
vectorizing_time = time.time() - tick
test_stats['n_test'] += len(y_test)
test_stats['n_test_pos'] += sum(y_test)
print("Test set is %d documents (%d positive)" % (len(y_test), sum(y_test)))

def progress(cls_name, stats):
    """Report progress information, return a string."""
    duration = time.time() - stats['t0']
    s = "%.20s classifier : \t " % cls_name
    s += "%(n_train)6d train docs (%(n_train_pos)6d positive) " % stats
    s += "%(n_test)6d test docs (%(n_test_pos)6d positive) " % test_stats
    s += "accuracy: %(accuracy).3f " % stats
    s += "in %.2fs (%5d docs/s)" % (duration, stats['n_train'] / duration)
    return s

cls_stats = {}

for cls_name in partial_fit_classifiers:
    stats = {'n_train': 0, 'n_train_pos': 0,
             'accuracy': 0.0, 'accuracy_history': [(0, 0)], 't0': time.time(),
             'runtime_history': [(0, 0)], 'total_fit_time': 0.0}
    cls_stats[cls_name] = stats

def get_minibatch(data_stream, n_test_documents)
    # Discard test set

    # We will feed the classifier with mini-batches of 1000 documents; this means
    # we have at most 1000 docs in memory at any time. The smaller the document
    # batch, the bigger the relative overhead of the partial fit methods.
    minibatch_size = 1000

    # Create the data_stream that parses Reuters SGML files and iterates on
    # documents as a stream.
    minibatch_iterators = iter_minibatches(data_stream, minibatch_size)
    total_vect_time = 0.0

    # Main loop : iterate on mini-batches of examples
    for i, (X_train_text, y_train) in enumerate(minibatch_iterators):
        tick = time.time()
        X_train = vectorizer.transform(X_train_text)
total_vect_time += time.time() - tick

        for cls_name, cls in partial_fit_classifiers.items():
            tick = time.time()

            # update estimator with examples in the current mini-batch
            cls.partial_fit(X_train, y_train, classes=all_classes)

            # accumulate test accuracy stats
            cls_stats[cls_name]['total_fit_time'] += time.time() - tick
            cls_stats[cls_name]['n_train'] += X_train.shape[0]
            cls_stats[cls_name]['n_train_pos'] += sum(y_train)
tick = time.time()
```python
if i % 3 == 0:
    print(progress(cls_name, cls_stats[cls_name]))
if i % 3 == 0:
    print('
')
```

Out:

<table>
<thead>
<tr>
<th>Test set is 467 documents (42 positive)</th>
<th>SGD classifier :</th>
<th>973 train docs ( 125 positive) 467</th>
<th>→ test docs ( 42 positive) accuracy: 0.916 in 0.77s (1268 docs/s)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Perceptron classifier :</td>
<td>973 train docs ( 125 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.893 in 0.77s (1262 docs/s)</td>
</tr>
<tr>
<td></td>
<td>NB Multinomial classifier :</td>
<td>973 train docs ( 125 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.910 in 0.80s (1220 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Passive-Aggressive classifier :</td>
<td>973 train docs ( 125 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.929 in 0.80s (1215 docs/s)</td>
</tr>
<tr>
<td></td>
<td>SGD classifier :</td>
<td>3881 train docs ( 458 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.951 in 2.16s (1797 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Perceptron classifier :</td>
<td>3881 train docs ( 458 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.934 in 2.16s (1795 docs/s)</td>
</tr>
<tr>
<td></td>
<td>NB Multinomial classifier :</td>
<td>3881 train docs ( 458 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.914 in 2.18s (1779 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Passive-Aggressive classifier :</td>
<td>3881 train docs ( 458 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.953 in 2.18s (1777 docs/s)</td>
</tr>
<tr>
<td></td>
<td>SGD classifier :</td>
<td>6291 train docs ( 709 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.957 in 3.51s (1792 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Perceptron classifier :</td>
<td>6291 train docs ( 709 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.936 in 3.51s (1791 docs/s)</td>
</tr>
<tr>
<td></td>
<td>NB Multinomial classifier :</td>
<td>6291 train docs ( 709 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.925 in 3.53s (1781 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Passive-Aggressive classifier :</td>
<td>6291 train docs ( 709 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.959 in 3.53s (1780 docs/s)</td>
</tr>
<tr>
<td></td>
<td>SGD classifier :</td>
<td>9053 train docs ( 1076 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.959 in 4.78s (1893 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Perceptron classifier :</td>
<td>9053 train docs ( 1076 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.953 in 4.78s (1891 docs/s)</td>
</tr>
<tr>
<td></td>
<td>NB Multinomial classifier :</td>
<td>9053 train docs ( 1076 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.934 in 4.81s (1881 docs/s)</td>
</tr>
<tr>
<td></td>
<td>Passive-Aggressive classifier :</td>
<td>9053 train docs ( 1076 positive) 467</td>
<td>→ test docs ( 42 positive) accuracy: 0.964 in 4.82s (1879 docs/s)</td>
</tr>
</tbody>
</table>
```
SGD classifier: 11940 train docs (1452 positive) 467→ test docs (42 positive) accuracy: 0.961 in 6.25s (1909 docs/s)
Perceptron classifier: 11940 train docs (1452 positive) 467→ test docs (42 positive) accuracy: 0.949 in 6.25s (1909 docs/s)
NB Multinomial classifier: 11940 train docs (1452 positive) 467→ test docs (42 positive) accuracy: 0.942 in 6.27s (1903 docs/s)
Passive-Aggressive classifier: 11940 train docs (1452 positive) 467→ test docs (42 positive) accuracy: 0.961 in 6.28s (1902 docs/s)

SGD classifier: 14780 train docs (1793 positive) 467→ test docs (42 positive) accuracy: 0.959 in 7.90s (1870 docs/s)
Perceptron classifier: 14780 train docs (1793 positive) 467→ test docs (42 positive) accuracy: 0.955 in 7.91s (1869 docs/s)
NB Multinomial classifier: 14780 train docs (1793 positive) 467→ test docs (42 positive) accuracy: 0.944 in 7.94s (1862 docs/s)
Passive-Aggressive classifier: 14780 train docs (1793 positive) 467→ test docs (42 positive) accuracy: 0.964 in 7.94s (1861 docs/s)

SGD classifier: 17706 train docs (2202 positive) 467→ test docs (42 positive) accuracy: 0.964 in 9.52s (1860 docs/s)
Perceptron classifier: 17706 train docs (2202 positive) 467→ test docs (42 positive) accuracy: 0.844 in 9.52s (1860 docs/s)
NB Multinomial classifier: 17706 train docs (2202 positive) 467→ test docs (42 positive) accuracy: 0.953 in 9.54s (1855 docs/s)
Passive-Aggressive classifier: 17706 train docs (2202 positive) 467→ test docs (42 positive) accuracy: 0.959 in 9.54s (1855 docs/s)

Plot results

The plot represents the learning curve of the classifier: the evolution of classification accuracy over the course of the mini-batches. Accuracy is measured on the first 1000 samples, held out as a validation set.

To limit the memory consumption, we queue examples up to a fixed amount before feeding them to the learner.

def plot_accuracy(x, y, x_legend):
    """Plot accuracy as a function of x."""
    x = np.array(x)
    y = np.array(y)
    plt.title('Classification accuracy as a function of %s' % x_legend)
    plt.xlabel('%s' % x_legend)
    plt.ylabel('Accuracy')
    plt.grid(True)
    plt.plot(x, y)

rcParams['legend.fontsize'] = 10
cls_names = list(sorted(cls_stats.keys()))

# Plot accuracy evolution
plt.figure()
for _, stats in sorted(cls_stats.items()):
    # Plot accuracy evolution with #examples
    accuracy, n_examples = zip(*stats['accuracy_history'])

(continues on next page)
plot_accuracy(n_examples, accuracy, "training examples (#)"
ax = plt.gca()
ax.set_ylim((0.8, 1))
plt.legend(cls_names, loc='best')

plt.figure()
for _, stats in sorted(cls_stats.items()):
    # Plot accuracy evolution with runtime
    accuracy, runtime = zip(*stats['runtime_history'])
    plot_accuracy(runtime, accuracy, 'runtime (s)'
    ax = plt.gca()
    ax.set_ylim((0.8, 1))
    plt.legend(cls_names, loc='best')

    # Plot fitting times
    plt.figure()
    fig = plt.gcf()
    cls_runtime = [stats['total_fit_time']
        for cls_name, stats in sorted(cls_stats.items())]
    cls_runtime.append(total_vect_time)
    cls_names.append('Vectorization')
    bar_colors = ['b', 'g', 'r', 'c', 'm', 'y']
    ax = plt.subplot(111)
    rectangles = plt.bar(range(len(cls_names)), cls_runtime, width=0.5,
        color=bar_colors)
    ax.set_xticks(np.linspace(0, len(cls_names) - 1, len(cls_names)))
    ax.set_xticklabels(cls_names, fontsize=10)
    ymax = max(cls_runtime) * 1.2
    ax.set_ylim((0, ymax))
    ax.set_ylabel('runtime (s)')
    ax.set_title('Training Times')

    def autolabel(rectangles):
        """attach some text vi autolabel on rectangles."""
        for rect in rectangles:
            height = rect.get_height()
            ax.text(rect.get_x() + rect.get_width() / 2.,
                1.05 * height, '%.4f' % height,
                ha='center', va='bottom')
        plt.setp(plt.xticks()[1], rotation=30)

    autolabel(rectangles)
    plt.tight_layout()
    plt.show()

    # Plot prediction times
    plt.figure()
    cls_runtime = []
    cls_names = list(sorted(cls_stats.keys()))
    for cls_name, stats in sorted(cls_stats.items()):
        cls_runtime.append(stats['prediction_time'])
        cls_runtime.append(parsing_time)
clf_names.append('Read/Parse\n+Feat.Extr.')
cls_runtime.append(vectorizing_time)
cls_names.append('Hashing\n+Vect.')

ax = plt.subplot(111)
rectangles = ax.bar(range(len(cls_names)), cls_runtime, width=0.5,
color=bar_colors)

ax.set_xticks(np.linspace(0, len(cls_names) - 1, len(cls_names)))
ax.set_xticklabels(cls_names, fontsize=8)
plt.setp(plt.xticks()[1], rotation=30)
ymax = max(cls_runtime) * 1.2
ax.set_yscale('log')
ax.set_ylim((0, ymax))
ax.set_ylabel('runtime (s)')
ax.set_title('Prediction Times (%d instances)' % n_test_documents)
autolabel(rectangles)
plt.tight_layout()
plt.show()
Classification accuracy as a function of runtime (s)

Accuracy

Runtime (s)

- NB Multinomial
- Passive-Aggressive
- Perceptron
- SGD
Total running time of the script: (0 minutes 10.762 seconds)

6.13 Feature Selection

Examples concerning the sklearn.feature_selection module.

6.13.1 Recursive feature elimination

A recursive feature elimination example showing the relevance of pixels in a digit classification task.

Note: See also Recursive feature elimination with cross-validation
from sklearn.svm import SVC
from sklearn.datasets import load_digits
from sklearn.feature_selection import RFE
import matplotlib.pyplot as plt

# Load the digits dataset
digits = load_digits()
X = digits.images.reshape((len(digits.images), -1))
y = digits.target

# Create the RFE object and rank each pixel
svc = SVC(kernel="linear", C=1)
rfe = RFE(estimator=svc, n_features_to_select=1, step=1)
rfe.fit(X, y)
ranking = rfe.ranking_.reshape(digits.images[0].shape)

# Plot pixel ranking
plt.matshow(ranking, cmap=plt.cm.Blues)
plt.colorbar()
plt.title("Ranking of pixels with RFE")
plt.show()
scikit-learn user guide, Release 0.24.0

6.13.2 Comparison of F-test and mutual information
This example illustrates the differences between univariate F-test statistics and mutual information.
We consider 3 features x_1, x_2, x_3 distributed uniformly over [0, 1], the target depends on them as follows:
y = x_1 + sin(6 * pi * x_2) + 0.1 * N(0, 1), that is the third features is completely irrelevant.
The code below plots the dependency of y against individual x_i and normalized values of univariate F-tests statistics
and mutual information.
As F-test captures only linear dependency, it rates x_1 as the most discriminative feature. On the other hand, mutual
information can capture any kind of dependency between variables and it rates x_2 as the most discriminative feature,
which probably agrees better with our intuitive perception for this example. Both methods correctly marks x_3 as
irrelevant.

print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.feature_selection import f_regression, mutual_info_regression
np.random.seed(0)
X = np.random.rand(1000, 3)
y = X[:, 0] + np.sin(6 * np.pi * X[:, 1]) + 0.1 * np.random.randn(1000)
f_test, _ = f_regression(X, y)
f_test /= np.max(f_test)
mi = mutual_info_regression(X, y)
mi /= np.max(mi)
plt.figure(figsize=(15, 5))
for i in range(3):
plt.subplot(1, 3, i + 1)
plt.scatter(X[:, i], y, edgecolor='black', s=20)
plt.xlabel("$x_{}$".format(i + 1), fontsize=14)
if i == 0:
plt.ylabel("$y$", fontsize=14)
plt.title("F-test={:.2f}, MI={:.2f}".format(f_test[i], mi[i]),
fontsize=16)
plt.show()

Total running time of the script: ( 0 minutes 0.285 seconds)

6.13. Feature Selection

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6.13.3 Pipeline Anova SVM

Simple usage of Pipeline that runs successively a univariate feature selection with anova and then a SVM of the selected features.

Using a sub-pipeline, the fitted coefficients can be mapped back into the original feature space.

Out:

<table>
<thead>
<tr>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0.75</td>
<td>0.50</td>
<td>6</td>
</tr>
<tr>
<td>1</td>
<td>0.67</td>
<td>1.00</td>
<td>6</td>
</tr>
<tr>
<td>2</td>
<td>0.67</td>
<td>0.80</td>
<td>5</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>0.75</td>
<td>8</td>
</tr>
</tbody>
</table>

Out: 0.76 25

<table>
<thead>
<tr>
<th>accuracy</th>
<th>macro avg</th>
<th>weighted avg</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.76</td>
<td>0.77</td>
<td>0.79</td>
</tr>
</tbody>
</table>

Out: 0.76 25

```
from sklearn import svm
from sklearn.datasets import make_classification
from sklearn.feature_selection import SelectKBest, f_classif
from sklearn.pipeline import make_pipeline
from sklearn.model_selection import train_test_split
from sklearn.metrics import classification_report

print(__doc__)

# import some data to play with
X, y = make_classification(
    n_features=20, n_informative=3, n_redundant=0, n_classes=4,
    n_clusters_per_class=2)

X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)
```

(continues on next page)
# ANOVA SVM-C

1) anova filter, take 3 best ranked features

```python
anova_filter = SelectKBest(f_classif, k=3)
```

2) svm

```python
clf = svm.LinearSVC()
```

```python
anova_svm = make_pipeline(anova_filter, clf)
anova_svm.fit(X_train, y_train)
y_pred = anova_svm.predict(X_test)
print(classification_report(y_test, y_pred))
coef = anova_svm[:-1].inverse_transform(anova_svm['linearsvc'].coef_)
print(coef)
```

Total running time of the script: ( 0 minutes 0.012 seconds)

## 6.13.4 Recursive feature elimination with cross-validation

A recursive feature elimination example with automatic tuning of the number of features selected with cross-validation.

Out:

```
Optimal number of features : 3
```
import matplotlib.pyplot as plt
from sklearn.svm import SVC
from sklearn.model_selection import StratifiedKFold
from sklearn.feature_selection import RFECV
from sklearn.datasets import make_classification

# Build a classification task using 3 informative features
X, y = make_classification(n_samples=1000, n_features=25, n_informative=3,
                           n_redundant=2, n_repeated=0, n_classes=8,
                           n_clusters_per_class=1, random_state=0)

# Create the RFE object and compute a cross-validated score.
svc = SVC(kernel="linear")
# The "accuracy" scoring is proportional to the number of correct
# classifications
min_features_to_select = 1  # Minimum number of features to consider
rfecv = RFECV(estimator=svc, step=1, cv=StratifiedKFold(2),
              scoring='accuracy',
              min_features_to_select=min_features_to_select)
rfecv.fit(X, y)

print("Optimal number of features : %d" % rfecv.n_features_)

# Plot number of features VS. cross-validation scores
plt.figure()
plt.xlabel("Number of features selected")
plt.ylabel("Cross validation score (nb of correct classifications)")
plt.plot(range(min_features_to_select, len(rfecv.grid_scores_) + min_features_to_select),
         rfecv.grid_scores_)
plt.show()

Total running time of the script: ( 0 minutes 2.815 seconds)

6.13.5 Model-based and sequential feature selection

This example illustrates and compares two approaches for feature selection: SelectFromModel which is based on feature importance, and SequentialFeatureSelection which relies on a greedy approach.

We use the Diabetes dataset, which consists of 10 features collected from 442 diabetes patients.

Authors: Manoj Kumar, Maria Telenczuk, Nicolas Hug.

License: BSD 3 clause
Loading the data

We first load the diabetes dataset which is available from within scikit-learn, and print its description:

```python
from sklearn.datasets import load_diabetes
diabetes = load_diabetes()
X, y = diabetes.data, diabetes.target
print(diabetes.DESCR)
```

Out:
```
.. _diabetes_dataset:

Diabetes dataset
----------------

Ten baseline variables, age, sex, body mass index, average blood pressure, and six blood serum measurements were obtained for each of n = 442 diabetes patients, as well as the response of interest, a quantitative measure of disease progression one year after baseline.

**Data Set Characteristics:**

: Number of Instances: 442

: Number of Attributes: First 10 columns are numeric predictive values

: Target: Column 11 is a quantitative measure of disease progression one year after baseline

**Attribute Information:**

- age  age in years
- sex
- bmi  body mass index
- bp  average blood pressure
- s1  tc, T-Cells (a type of white blood cells)
- s2  ldl, low-density lipoproteins
- s3  hdl, high-density lipoproteins
- s4  tch, thyroid stimulating hormone
- s5  ltg, lamotrigine
- s6  glu, blood sugar level

Note: Each of these 10 feature variables have been mean centered and scaled by the standard deviation times `n_samples` (i.e. the sum of squares of each column totals 1).

Source URL:
https://www4.stat.ncsu.edu/~boos/var.select/diabetes.html

For more information see:
Feature importance from coefficients

To get an idea of the importance of the features, we are going to use the LassoCV estimator. The features with the highest absolute coef_ value are considered the most important. We can observe the coefficients directly without needing to scale them (or scale the data) because from the description above, we know that the features were already standardized. For a more complete example on the interpretations of the coefficients of linear models, you may refer to Common pitfalls in interpretation of coefficients of linear models.

```python
import matplotlib.pyplot as plt
import numpy as np
from sklearn.linear_model import LassoCV

lasso = LassoCV().fit(X, y)
importance = np.abs(lasso.coef_)
feature_names = np.array(diabetes.feature_names)
plt.bar(height=importance, x=feature_names)
plt.title("Feature importances via coefficients")
plt.show()
```

Feature importances via coefficients
Selecting features based on importance

Now we want to select the two features which are the most important according to the coefficients. The `SelectFromModel` is meant just for that. `SelectFromModel` accepts a `threshold` parameter and will select the features whose importance (defined by the coefficients) are above this threshold.

Since we want to select only 2 features, we will set this threshold slightly above the coefficient of third most important feature.

```python
from sklearn.feature_selection import SelectFromModel
from time import time

threshold = np.sort(importance)[-3] + 0.01

tic = time()
sfm = SelectFromModel(lasso, threshold=threshold).fit(X, y)
toc = time()

print("Features selected by SelectFromModel: ",
      feature_names[sfm.get_support()])
print(f"Done in {toc - tic:.3f}s")
```

Out:

```
Features selected by SelectFromModel: ['s1' 's5']
Done in 0.055s
```

Selecting features with Sequential Feature Selection

Another way of selecting features is to use `SequentialFeatureSelector` (SFS). SFS is a greedy procedure where, at each iteration, we choose the best new feature to add to our selected features based a cross-validation score. That is, we start with 0 features and choose the best single feature with the highest score. The procedure is repeated until we reach the desired number of selected features.

We can also go in the reverse direction (backward SFS), i.e. start with all the features and greedily choose features to remove one by one. We illustrate both approaches here.

```python
from sklearn.feature_selection import SequentialFeatureSelector

tic_fwd = time()
sfs_forward = SequentialFeatureSelector(lasso, n_features_to_select=2,
                                      direction='forward').fit(X, y)
toc_fwd = time()

tic_bwd = time()
sfs_backward = SequentialFeatureSelector(lasso, n_features_to_select=2,
                                      direction='backward').fit(X, y)
toc_bwd = time()

print("Features selected by forward sequential selection: ",
      feature_names[sfs_forward.get_support()])
print(f"Done in {toc_fwd - tic_fwd:.3f}s")
print("Features selected by backward sequential selection: ",
      feature_names[sfs_backward.get_support()])
print(f"Done in {toc_bwd - tic_bwd:.3f}s")
```

Out:
Features selected by forward sequential selection: ['bmi' 's5']
Done in 4.315s
Features selected by backward sequential selection: ['bmi' 's5']
Done in 13.325s

Discussion

Interestingly, forward and backward selection have selected the same set of features. In general, this isn’t the case and the two methods would lead to different results.

We also note that the features selected by SFS differ from those selected by feature importance: SFS selects bmi instead of s1. This does sound reasonable though, since bmi corresponds to the third most important feature according to the coefficients. It is quite remarkable considering that SFS makes no use of the coefficients at all.

To finish with, we should note that SelectFromModel is significantly faster than SFS. Indeed, SelectFromModel only needs to fit a model once, while SFS needs to cross-validate many different models for each of the iterations. SFS however works with any model, while SelectFromModel requires the underlying estimator to expose a `coef_` attribute or a `feature_importances_` attribute. The forward SFS is faster than the backward SFS because it only needs to perform \( n_{\text{features to select}} = 2 \) iterations, while the backward SFS needs to perform \( n_{\text{features}} - n_{\text{features to select}} = 8 \) iterations.

Total running time of the script: (0 minutes 17.924 seconds)

### 6.13.6 Test with permutations the significance of a classification score

This example demonstrates the use of `permutation_test_score` to evaluate the significance of a cross-validated score using permutations.

```python
# Authors: Alexandre Gramfort <alexandre.gramfort@inria.fr>
#         Lucy Liu
# License: BSD 3 clause
#
# Dataset
# -------
# A We will use the :ref:`iris_dataset`, which consists of measurements taken
# from 3 types of irises.

from sklearn.datasets import load_iris

iris = load_iris()
X = iris.data
y = iris.target

# We will also generate some random feature data (i.e., 2200 features), uncorrelated with the class labels in the iris dataset.

import numpy as np

n_uncorrelated_features = 2200
rng = np.random.RandomState(seed=0)
# Use same number of samples as in iris and 2200 features
X_rand = rng.normal(size=(X.shape[0], n_uncorrelated_features))
```

We will also generate some random feature data (i.e., 2200 features), uncorrelated with the class labels in the iris dataset.
Permutation test score

Next, we calculate the `permutation_test_score` using the original iris dataset, which strongly predict the labels and the randomly generated features and iris labels, which should have no dependency between features and labels. We use the `SVC` classifier and `Accuracy score` to evaluate the model at each round.

`permutation_test_score` generates a null distribution by calculating the accuracy of the classifier on 1000 different permutations of the dataset, where features remain the same but labels undergo different permutations. This is the distribution for the null hypothesis which states there is no dependency between the features and labels. An empirical p-value is then calculated as the percentage of permutations for which the score obtained is greater that the score obtained using the original data.

```python
from sklearn.svm import SVC
from sklearn.model_selection import StratifiedKFold
from sklearn.model_selection import permutation_test_score

clf = SVC(kernel='linear', random_state=7)
cv = StratifiedKFold(2, shuffle=True, random_state=0)

score_iris, perm_scores_iris, pvalue_iris = permutation_test_score(
    clf, X, y, scoring="accuracy", cv=cv, n_permutations=1000)

score_rand, perm_scores_rand, pvalue_rand = permutation_test_score(
    clf, X_rand, y, scoring="accuracy", cv=cv, n_permutations=1000)
```

Original data

Below we plot a histogram of the permutation scores (the null distribution). The red line indicates the score obtained by the classifier on the original data. The score is much better than those obtained by using permuted data and the p-value is thus very low. This indicates that there is a low likelihood that this good score would be obtained by chance alone. It provides evidence that the iris dataset contains real dependency between features and labels and the classifier was able to utilize this to obtain good results.

```python
import matplotlib.pyplot as plt

fig, ax = plt.subplots()

ax.hist(perm_scores_iris, bins=20, density=True)
ax.axvline(score_iris, ls='--', color='r')

score_label = (f"Score on original data: {score_iris:.2f} (p-value: {pvalue_iris:.3f})")
ax.text(0.7, 260, score_label, fontsize=12)
ax.set_xlabel("Accuracy score")
ax.set_ylabel("Probability")
```
Random data

Below we plot the null distribution for the randomized data. The permutation scores are similar to those obtained using the original iris dataset because the permutation always destroys any feature label dependency present. The score obtained on the original randomized data in this case though, is very poor. This results in a large p-value, confirming that there was no feature label dependency in the original data.

```python
fig, ax = plt.subplots()
ax.hist(perm_scores_rand, bins=20, density=True)
ax.set_xlim(0.13)
ax.axvline(score_rand, ls='--', color='r')
score_label = (f"Score on original data: {score_rand:.2f}\n(p-value: {pvalue_rand:.3f})")
ax.text(0.14, 125, score_label, fontsize=12)
ax.set_xlabel("Accuracy score")
ax.set_ylabel("Probability")
plt.show()
```
Another possible reason for obtaining a high p-value is that the classifier was not able to use the structure in the data. In this case, the p-value would only be low for classifiers that are able to utilize the dependency present. In our case above, where the data is random, all classifiers would have a high p-value as there is no structure present in the data. Finally, note that this test has been shown to produce low p-values even if there is only weak structure in the data\(^1\).

References:

Total running time of the script: ( 0 minutes 29.068 seconds)

### 6.13.7 Univariate Feature Selection

An example showing univariate feature selection.

Noisy (non informative) features are added to the iris data and univariate feature selection is applied. For each feature, we plot the p-values for the univariate feature selection and the corresponding weights of an SVM. We can see that univariate feature selection selects the informative features and that these have larger SVM weights.

In the total set of features, only the 4 first ones are significant. We can see that they have the highest score with univariate feature selection. The SVM assigns a large weight to one of these features, but also Selects many of the non-informative features. Applying univariate feature selection before the SVM increases the SVM weight attributed to the significant features, and will thus improve classification.

Classification accuracy without selecting features: 0.789
Classification accuracy after univariate feature selection: 0.868

print(__doc__)

import numpy as np
import matplotlib.pyplot as plt

from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import MinMaxScaler
from sklearn.svm import LinearSVC
from sklearn.pipeline import make_pipeline
from sklearn.feature_selection import SelectKBest, f_classif

# Import some data to play with
# The iris dataset
X, y = load_iris(return_X_y=True)

# Some noisy data not correlated
E = np.random.RandomState(42).uniform(0, 0.1, size=(X.shape[0], 20))

# Add the noisy data to the informative features
X = np.hstack((X, E))

# Split dataset to select feature and evaluate the classifier
X_train, X_test, y_train, y_test = train_test_split(X, y, stratify=y, random_state=0)

plt.figure(1)
plt.clf()

X_indices = np.arange(X.shape[-1])

# Univariate feature selection with F-test for feature scoring
# We use the default selection function to select the four most significant features
selector = SelectKBest(f_classif, k=4)
selector.fit(X_train, y_train)
scores = -np.log10(selector.pvalues_)
scores /= scores.max()

plt.bar(X_indices - .45, scores, width=.2, label=r'Univariate score ($-Log(p\_value)$)')

# Compare to the weights of an SVM
clf = make_pipeline(MinMaxScaler(), LinearSVC())
clf.fit(X_train, y_train)

print('Classification accuracy without selecting features: {:.3f}'.format(clf.score(X_test, y_test)))

svm_weights = np.abs(clf[-1].coef_).sum(axis=0)
svm_weights /= svm_weights.sum()

plt.bar(X_indices - .25, svm_weights, width=.2, label='SVM weight')

clf_selected = make_pipeline(SelectKBest(f_classif, k=4), MinMaxScaler(), LinearSVC())
clf_selected.fit(X_train, y_train)

print('Classification accuracy after univariate feature selection: {:.3f}'.format(clf_selected.score(X_test, y_test)))

svm_weights_selected = np.abs(clf_selected[-1].coef_).sum(axis=0)
svm_weights_selected /= svm_weights_selected.sum()

plt.bar(X_indices[selector.get_support()] - .05, svm_weights_selected, width=.2, label='SVM weights after selection')

plt.title("Comparing feature selection")

(continues on next page)
6.14 Gaussian Mixture Models

Examples concerning the `sklearn.mixture` module.

6.14.1 Density Estimation for a Gaussian mixture

Plot the density estimation of a mixture of two Gaussians. Data is generated from two Gaussians with different centers and covariance matrices.
import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import LogNorm
from sklearn import mixture

n_samples = 300

# generate random sample, two components
np.random.seed(0)

# generate spherical data centered on (20, 20)
shifted_gaussian = np.random.randn(n_samples, 2) + np.array([20, 20])

# generate zero centered stretched Gaussian data
C = np.array([[0., -0.7], [3.5, .7]])
stretched_gaussian = np.dot(np.random.randn(n_samples, 2), C)

# concatenate the two datasets into the final training set
X_train = np.vstack([shifted_gaussian, stretched_gaussian])

# fit a Gaussian Mixture Model with two components
clf = mixture.GaussianMixture(n_components=2, covariance_type='full')
clf.fit(X_train)

# display predicted scores by the model as a contour plot
x = np.linspace(-20., 30.)
y = np.linspace(-20., 40.)
X, Y = np.meshgrid(x, y)
XX = np.array([X.ravel(), Y.ravel()]).T
Z = -clf.score_samples(XX)
Z = Z.reshape(X.shape)

CS = plt.contour(X, Y, Z, norm=LogNorm(vmin=1.0, vmax=1000.0),
                 levels=np.logspace(0, 3, 10))
CB = plt.colorbar(CS, shrink=0.8, extend='both')
plt.scatter(X_train[:, 0], X_train[:, 1], .8)
plt.title('Negative log-likelihood predicted by a GMM')
plt.axis('tight')
plt.show()
6.14.2 Gaussian Mixture Model Ellipsoids

Plot the confidence ellipsoids of a mixture of two Gaussians obtained with Expectation Maximisation (GaussianMixture class) and Variational Inference (BayesianGaussianMixture class models with a Dirichlet process prior).

Both models have access to five components with which to fit the data. Note that the Expectation Maximisation model will necessarily use all five components while the Variational Inference model will effectively only use as many as are needed for a good fit. Here we can see that the Expectation Maximisation model splits some components arbitrarily, because it is trying to fit too many components, while the Dirichlet Process model adapts its number of state automatically.

This example doesn’t show it, as we’re in a low-dimensional space, but another advantage of the Dirichlet process model is that it can fit full covariance matrices effectively even when there are less examples per cluster than there are dimensions in the data, due to regularization properties of the inference algorithm.

```python
import itertools
import numpy as np
from scipy import linalg
import matplotlib.pyplot as plt
import matplotlib as mpl
from sklearn import mixture
```
color_iter = itertools.cycle(['navy', 'c', 'cornflowerblue', 'gold', 'darkorange'])

def plot_results(X, Y_, means, covariances, index, title):
    splot = plt.subplot(2, 1, 1 + index)
    for i, (mean, covar, color) in enumerate(zip(means, covariances, color_iter)):
        v, w = linalg.eigh(covar)
        v = 2. * np.sqrt(2.) * np.sqrt(v)
        u = w[0] / linalg.norm(w[0])
        # as the DP will not use every component it has access to
        # unless it needs it, we shouldn't plot the redundant
        # components.
        if not np.any(Y_ == i):
            continue
        plt.scatter(X[Y_ == i, 0], X[Y_ == i, 1], .8, color=color)
        # Plot an ellipse to show the Gaussian component
        angle = np.arctan(u[1] / u[0])
        angle = 180. * angle / np.pi  # convert to degrees
        ell = mpl.patches.Ellipse(mean, v[0], v[1], 180. + angle, color=color)
        ell.set_clip_box(splot.bbox)
        ell.set_alpha(0.5)
        splot.add_artist(ell)

    plt.xlim(-9., 5.)
    plt.ylim(-3., 6.)
    plt.xticks(())
    plt.yticks(())
    plt.title(title)

    # Number of samples per component
    n_samples = 500

    # Generate random sample, two components
    np.random.seed(0)
    C = np.array([[0., -0.1], [1.7, .4]])
    X = np.r_[np.dot(np.random.randn(n_samples, 2), C),
              .7 * np.random.randn(n_samples, 2) + np.array([-6, 3])]

    # Fit a Gaussian mixture with EM using five components
    gmm = mixture.GaussianMixture(n_components=5, covariance_type='full').fit(X)
    plot_results(X, gmm.predict(X), gmm.means_, gmm.covariances_, 0,
                 'Gaussian Mixture')

    # Fit a Dirichlet process Gaussian mixture using five components
    dpgmm = mixture.BayesianGaussianMixture(n_components=5,
                                             covariance_type='full').fit(X)
    plot_results(X, dpgmm.predict(X), dpgmm.means_, dpgmm.covariances_, 1,
                 'Bayesian Gaussian Mixture with a Dirichlet process prior')

plt.show()
6.14.3 Gaussian Mixture Model Selection

This example shows that model selection can be performed with Gaussian Mixture Models using information-theoretic criteria (BIC). Model selection concerns both the covariance type and the number of components in the model. In that case, AIC also provides the right result (not shown to save time), but BIC is better suited if the problem is to identify the right model. Unlike Bayesian procedures, such inferences are prior-free.

In that case, the model with 2 components and full covariance (which corresponds to the true generative model) is selected.

```python
import numpy as np
import itertools
from scipy import linalg
import matplotlib.pyplot as plt
import matplotlib as mpl
from sklearn import mixture
print(__doc__)

# Number of samples per component
n_samples = 500

# Generate random sample, two components

import numpy as np
import itertools
from scipy import linalg
import matplotlib.pyplot as plt
import matplotlib as mpl
from sklearn import mixture
print(__doc__)

# Number of samples per component
n_samples = 500

# Generate random sample, two components
```
np.random.seed(0)
C = np.array([[0., -0.1], [1.7, .4]])
X = np.random.randn(n_samples, 2) + np.array([-6, 3])

lowest_bic = np.infty
bic = []
n_components_range = range(1, 7)
cv_types = ['spherical', 'tied', 'diag', 'full']
for cv_type in cv_types:
    for n_components in n_components_range:
        # Fit a Gaussian mixture with EM
        gmm = mixture.GaussianMixture(n_components=n_components,
                                    covariance_type=cv_type)
        gmm.fit(X)
        bic.append(gmm.bic(X))
if bic[-1] < lowest_bic:
    lowest_bic = bic[-1]
    best_gmm = gmm

bic = np.array(bic)
color_iter = itertools.cycle(['navy', 'turquoise', 'cornflowerblue',
                               'darkorange'])
clf = best_gmm
bars = []
# Plot the BIC scores
plt.figure(figsize=(8, 6))
spl = plt.subplot(2, 1, 1)
for i, (cv_type, color) in enumerate(zip(cv_types, color_iter)):
    xpos = np.array(n_components_range) + .2 * (i - 2)
    bars.append(plt.bar(xpos, bic[i * len(n_components_range):
                                 (i + 1) * len(n_components_range)],
                        width=.2, color=color))
plt.xticks(n_components_range)
plt.ylim([bic.min() * 1.01 - .01 * bic.max(), bic.max()])
plt.title('BIC score per model')
xpos = np.array(bic.argmin()) + .65 +
        .2 * np.floor(bic.argmin() / len(n_components_range))
plt.text(xpos, bic.min() * 0.97 + .03 * bic.max(), '*', fontsize=14)
spl.set_xlabel('Number of components')
spl.legend([b[0] for b in bars], cv_types)

# Plot the winner
splot = plt.subplot(2, 1, 2)
Y_ = clf.predict(X)
for i, (mean, cov, color) in enumerate(zip(clf.means_, clf.covariances_,
                                            color_iter)):
    v, w = linalg.eigh(cov)
    if not np.any(Y_ == i):
        continue
    plt.scatter(X[Y_ == i, 0], X[Y_ == i, 1], .8, color=color)

    # Plot an ellipse to show the Gaussian component
    angle = np.arctan2(w[0][1], w[0][0])
    angle = 180. * angle / np.pi  # convert to degrees
    v = 2. * np.sqrt(2.) * np.sqrt(v)

(continues on next page)
6.14.4 GMM covariances

Demonstration of several covariances types for Gaussian mixture models.

See Gaussian mixture models for more information on the estimator.

Although GMM are often used for clustering, we can compare the obtained clusters with the actual classes from the dataset. We initialize the means of the Gaussians with the means of the classes from the training set to make this comparison valid.

We plot predicted labels on both training and held out test data using a variety of GMM covariance types on the iris dataset. We compare GMMs with spherical, diagonal, full, and tied covariance matrices in increasing order of performance. Although one would expect full covariance to perform best in general, it is prone to overfitting on small datasets and does not generalize well to held out test data.

On the plots, train data is shown as dots, while test data is shown as crosses. The iris dataset is four-dimensional. Only the first two dimensions are shown here, and thus some points are separated in other dimensions.
import matplotlib as mpl
import matplotlib.pyplot as plt
import numpy as np
from sklearn import datasets
from sklearn.mixture import GaussianMixture
from sklearn.model_selection import StratifiedKFold

print(__doc__)

colors = ['navy', 'turquoise', 'darkorange']

```python
def make_ellipses(gmm, ax):
    for n, color in enumerate(colors):
        if gmm.covariance_type == 'full':
            covariances = gmm.covariances_[n][:2, :2]
        elif gmm.covariance_type == 'tied':
            covariances = gmm.covariances_[2, :2]
        elif gmm.covariance_type == 'diag':
            covariances = np.diag(gmm.covariances_[n][:2])
        elif gmm.covariance_type == 'spherical':
            covariances = np.eye(gmm.means_.shape[1]) * gmm.covariances_[n]
        v, w = np.linalg.eigh(covariances)
        u = w[0] / np.linalg.norm(w[0])
        angle = np.arctan2(u[1], u[0])  # convert to degrees
        v = 2. * np.sqrt(2.) * np.sqrt(v)
        ell = mpl.patches.Ellipse(gmm.means_[n, :2], v[0], v[1],
                                   180 + angle, color=color)
        ell.set_clip_box(ax.bbox)
        ell.set_alpha(0.5)
        ax.add_artist(ell)
    ax.set_aspect('equal', 'datalim')
```

iris = datasets.load_iris()

# Break up the dataset into non-overlapping training (75%) and testing (25%) sets.
skf = StratifiedKFold(n_splits=4)
# Only take the first fold.
train_index, test_index = next(iter(skf.split(iris.data, iris.target)))

X_train = iris.data[train_index]
y_train = iris.target[train_index]
X_test = iris.data[test_index]
y_test = iris.target[test_index]

n_classes = len(np.unique(y_train))

# Try GMMs using different types of covariances.
estimators = {cov_type: GaussianMixture(n_components=n_classes,
                                       covariance_type=cov_type,
                                       max_iter=20, random_state=0)
              for cov_type in ['spherical', 'diag', 'tied', 'full']}
n_estimators = len(estimators)

plt.figure(figsize=(3 * n_estimators // 2, 6))
plt.subplots_adjust(bottom=.01, top=0.95, hspace=.15, wspace=.05,
left=.01, right=.99)

for index, (name, estimator) in enumerate(estimators.items()):
    # Since we have class labels for the training data, we can
    # initialize the GMM parameters in a supervised manner.
    estimator.means_init = np.array([X_train[y_train == i].mean(axis=0)
                                     for i in range(n_classes)])
```

(continues on next page)
# Train the other parameters using the EM algorithm.
estimator.fit(X_train)

h = plt.subplot(2, n_estimators // 2, index + 1)
make_ellipses(estimator, h)

for n, color in enumerate(colors):
data = iris.data[iris.target == n]
plt.scatter(data[:, 0], data[:, 1], s=0.8, color=color,
label=iris.target_names[n])

# Plot the test data with crosses
for n, color in enumerate(colors):
data = X_test[y_test == n]
plt.scatter(data[:, 0], data[:, 1], marker='x', color=color)

y_train_pred = estimator.predict(X_train)
train_accuracy = np.mean(y_train_pred.ravel() == y_train.ravel()) * 100
plt.text(0.05, 0.9, 'Train accuracy: %.1f' % train_accuracy,
transform=h.transAxes)

y_test_pred = estimator.predict(X_test)
test_accuracy = np.mean(y_test_pred.ravel() == y_test.ravel()) * 100
plt.text(0.05, 0.8, 'Test accuracy: %.1f' % test_accuracy,
transform=h.transAxes)

plt.xticks(())
plt.yticks(())
plt.title(name)
plt.legend(scatterpoints=1, loc='lower right', prop=dict(size=12))
plt.show()

Total running time of the script: ( 0 minutes 0.333 seconds)

### 6.14.5 Gaussian Mixture Model Sine Curve

This example demonstrates the behavior of Gaussian mixture models fit on data that was not sampled from a mixture of Gaussian random variables. The dataset is formed by 100 points loosely spaced following a noisy sine curve. There is therefore no ground truth value for the number of Gaussian components.

The first model is a classical Gaussian Mixture Model with 10 components fit with the Expectation-Maximization algorithm.

The second model is a Bayesian Gaussian Mixture Model with a Dirichlet process prior fit with variational inference. The low value of the concentration prior makes the model favor a lower number of active components. This models “decides” to focus its modeling power on the big picture of the structure of the dataset: groups of points with alternating directions modeled by non-diagonal covariance matrices. Those alternating directions roughly capture the alternating nature of the original sine signal.

The third model is also a Bayesian Gaussian mixture model with a Dirichlet process prior but this time the value of the concentration prior is higher giving the model more liberty to model the fine-grained structure of the data. The result is a mixture with a larger number of active components that is similar to the first model where we arbitrarily decided to fix the number of components to 10.
Which model is the best is a matter of subjective judgment: do we want to favor models that only capture the big picture to summarize and explain most of the structure of the data while ignoring the details or do we prefer models that closely follow the high density regions of the signal?

The last two panels show how we can sample from the last two models. The resulting samples distributions do not look exactly like the original data distribution. The difference primarily stems from the approximation error we made by using a model that assumes that the data was generated by a finite number of Gaussian components instead of a continuous noisy sine curve.

import itertools
import numpy as np
from scipy import linalg
import matplotlib.pyplot as plt
import matplotlib as mpl
from sklearn import mixture
print(__doc__)

color_iter = itertools.cycle(['navy', 'c', 'cornflowerblue', 'gold', 'darkorange'])

def plot_results(X, Y, means, covariances, index, title):
    splot = plt.subplot(5, 1, 1 + index)
    for i, (mean, covar, color) in enumerate(zip(means, covariances, color_iter):
        v, w = linalg.eigh(covar)
        v = 2. * np.sqrt(2.) * np.sqrt(v)
        u = w[0] / linalg.norm(w[0])
        # as the DP will not use every component it has access to
        # unless it needs it, we shouldn’t plot the redundant
        # components.
        if not np.any(Y == i):
            continue
        plt.scatter(X[Y == i, 0], X[Y == i, 1], .8, color=color)
        # Plot an ellipse to show the Gaussian component
        angle = np.arctan(u[1] / u[0])
        angle = 180. * angle / np.pi  # convert to degrees
        ell = mpl.patches.Ellipse(mean, v[0], v[1], 180. + angle, color=color)
        ell.set_clip_box(splot.bbox)
        ell.set_alpha(0.5)
        splot.add_artist(ell)

    plt.xlim(-6., 4. * np.pi - 6.)
    plt.ylim(-5., 5.)
    plt.title(title)
    plt.xticks(())
    plt.yticks(())

def plot_samples(X, Y, n_components, index, title):
    plt.subplot(5, 1, 4 + index)
    for i, color in zip(range(n_components), color_iter):
        # as the DP will not use every component it has access to
        # unless it needs it, we shouldn’t plot the redundant
        # components.
        if not np.any(Y == i):
            continue
        plt.scatter(X[Y == i, 0], X[Y == i, 1], .8, color=color)

    plt.xlim(-6., 4. * np.pi - 6.)
    plt.ylim(-5., 5.)
    plt.title(title)
    plt.xticks(())
    plt.yticks(())

# Parameters

n_samples = 100

# Generate random sample following a sine curve
np.random.seed(0)
X = np.zeros((n_samples, 2))
step = 4. * np.pi / n_samples

for i in range(X.shape[0]):
    x = i * step - 6.
    X[i, 0] = x + np.random.normal(0, 0.1)
    X[i, 1] = 3. * (np.sin(x) + np.random.normal(0, .2))

plt.figure(fignsize=(10, 10))
plt.subplots_adjust(bottom=.04, top=.95, hspace=.2, wspace=.05,
left=.03, right=.97)

# Fit a Gaussian mixture with EM using ten components
gmm = mixture.GaussianMixture(n_components=10, covariance_type='full',
max_iter=100).fit(X)
plot_results(X, gmm.predict(X), gmm.means_, gmm.covariances_, 0,
'Expectation-maximization')

dpgmm = mixture.BayesianGaussianMixture(
    n_components=10, covariance_type='full', weight_concentration_prior=1e-2,
    weight_concentration_prior_type='dirichlet_process',
    mean_precision_prior=1e-2, covariance_prior=1e0 * np.eye(2),
    init_params="random", max_iter=100, random_state=2).fit(X)
plot_results(X, dpgmm.predict(X), dpgmm.means_, dpgmm.covariances_, 1,
"Bayesian Gaussian mixture models with a Dirichlet process prior "for $\gamma_0=0.01$.")

X_s, y_s = dpgmm.sample(n_samples=2000)
plot_samples(X_s, y_s, dpgmm.n_components, 0,
"Gaussian mixture with a Dirichlet process prior "for $\gamma_0=0.01$ sampled with $2000$ samples.")

dpgmm = mixture.BayesianGaussianMixture(
    n_components=10, covariance_type='full', weight_concentration_prior=1e+2,
    weight_concentration_prior_type='dirichlet_process',
    mean_precision_prior=1e-2, covariance_prior=1e0 * np.eye(2),
    init_params="kmeans", max_iter=100, random_state=2).fit(X)
plot_results(X, dpgmm.predict(X), dpgmm.means_, dpgmm.covariances_, 2,
"Bayesian Gaussian mixture models with a Dirichlet process prior "for $\gamma_0=100$")

X_s, y_s = dpgmm.sample(n_samples=2000)
plot_samples(X_s, y_s, dpgmm.n_components, 1,
"Gaussian mixture with a Dirichlet process prior "for $\gamma_0=100$ sampled with $2000$ samples.")

plt.show()
6.14.6 Concentration Prior Type Analysis of Variation Bayesian Gaussian Mixture

This example plots the ellipsoids obtained from a toy dataset (mixture of three Gaussians) fitted by the `BayesianGaussianMixture` class models with a Dirichlet distribution prior (weight_concentration_prior_type='dirichlet_distribution') and a Dirichlet process prior (weight_concentration_prior_type='dirichlet_process'). On each figure, we plot the results for three different values of the weight concentration prior.

The `BayesianGaussianMixture` class can adapt its number of mixture components automatically. The parameter weight_concentration_prior has a direct link with the resulting number of components with non-zero weights. Specifying a low value for the concentration prior will make the model put most of the weight on few components set the remaining components weights very close to zero. High values of the concentration prior will allow a larger number of components to be active in the mixture.

The Dirichlet process prior allows to define an infinite number of components and automatically selects the correct number of components: it activates a component only if it is necessary.

On the contrary the classical finite mixture model with a Dirichlet distribution prior will favor more uniformly weighted components and therefore tends to divide natural clusters into unnecessary sub-components.
import numpy as np
import matplotlib as mpl
import matplotlib.pyplot as plt
import matplotlib.gridspec as gridspec
from sklearn.mixture import BayesianGaussianMixture

print(__doc__)

def plot_ellipses(ax, weights, means, covars):
    for n in range(means.shape[0]):
        eig_vals, eig_vecs = np.linalg.eigh(covars[n])
        unit_eig_vec = eig_vecs[0] / np.linalg.norm(eig_vecs[0])
        angle = np.arctan2(unit_eig_vec[1], unit_eig_vec[0])
        # Ellipse needs degrees
        angle = 180 * angle / np.pi
        # eigenvector normalization
        eig_vals = 2 * np.sqrt(2) * np.sqrt(eig_vals)
        ell = mpl.patches.Ellipse(means[n], eig_vals[0], eig_vals[1],
                                180 + angle, edgecolor='black')
        ell.set_clip_box(ax.bbox)
        ell.set_alpha(weights[n])
        ell.set_facecolor('#56B4E9')
        ax.add_artist(ell)

def plot_results(ax1, ax2, estimator, X, y, title, plot_title=False):
    ax1.set_title(title)
    ax1.scatter(X[:, 0], X[:, 1], s=5, marker='o', color=colors[y], alpha=0.8)
    ax1.set_xlim(-2., 2.)
    (continues on next page)
ax1.set_ylim(-3., 3.)
ax1.set_xticks(()
ax1.set_yticks(()
plot_ellipses(ax1, estimator.weights_, estimator.means_,
estimator.covariances_)

ax2.get_xaxis().set_tick_params(direction='out')
ax2.yaxis.grid(True, alpha=0.7)
for k, w in enumerate(estimator.weights_):
    ax2.bar(k, w, width=0.9, color='#56B4E9', zorder=3,
            align='center', edgecolor='black')
    ax2.text(k, w + 0.007, "$%.1f\%\$\$" % (w * 100.),
            horizontalalignment='center')
ax2.set_xlim(-.6, 2 * n_components - .4)
ax2.set_ylim(0., 1.1)
ax2.tick_params(axis='y', which='both', left=False,
                right=False, labelleft=False)
ax2.tick_params(axis='x', which='both', top=False)

if plot_title:
    ax1.set_ylabel('Estimated Mixtures')
    ax2.set_ylabel('Weight of each component')

# Parameters of the dataset
random_state, n_components, n_features = 2, 3, 2
colors = np.array(['#0072B2', '#F0E442', '#D55E00'])
covars = np.array([[.7, .0], [.0, .1],[.5, .0], [.0, .1],[.5, .0], [.0, .1]])
samples = np.array([200, 500, 200])
means = np.array([[-.70], [0.00], [.70]])

# mean_precision_prior= 0.8 to minimize the influence of the prior
estimators = [
    ('Finite mixture with a Dirichlet distribution prior and "$\gamma_0=$$",
    BayesianGaussianMixture(
        weight_concentration_prior_type="dirichlet_distribution",
        n_components=2 * n_components, reg_covar=0, init_params='random',
        max_iter=1500, mean_precision_prior=.8,
        random_state=random_state), [0.001, 1, 1000]),
    ('Infinite mixture with a Dirichlet process prior and "$\gamma_0=$$",
    BayesianGaussianMixture(
        weight_concentration_prior_type="dirichlet_process",
        n_components=2 * n_components, reg_covar=0, init_params='random',
        max_iter=1500, mean_precision_prior=.8,
        random_state=random_state), [1, 1000, 100000])
]

# Generate data
rng = np.random.RandomState(random_state)
X = np.vstack([rng.multivariate_normal(means[j], covars[j], samples[j])
               for j in range(n_components)])
y = np.concatenate([np.full(samples[j], j, dtype=int)
                    for j in range(n_components)])
# Plot results in two different figures

```python
for (title, estimator, concentrations_prior) in estimators:
    plt.figure(figsize=(4.7 * 3, 8))
    plt.subplots_adjust(bottom=.04, top=0.90, hspace=.05, wspace=.05,
                        left=.03, right=.99)

    gs = gridspec.GridSpec(3, len(concentrations_prior))
    for k, concentration in enumerate(concentrations_prior):
        estimator.weight_concentration_prior = concentration
        estimator.fit(X)
        plot_results(plt.subplot(gs[0:2, k]), plt.subplot(gs[2, k]), estimator,
                     X, y, r"%s\$%.1e$" % (title, concentration),
                     plot_title=k == 0)

plt.show()
```

Total running time of the script: ( 0 minutes 7.658 seconds)

## 6.15 Gaussian Process for Machine Learning

Examples concerning the `sklearn.gaussian_process` module.

### 6.15.1 Illustration of Gaussian process classification (GPC) on the XOR dataset

This example illustrates GPC on XOR data. Compared are a stationary, isotropic kernel (RBF) and a non-stationary kernel (DotProduct). On this particular dataset, the DotProduct kernel obtains considerably better results because the class-boundaries are linear and coincide with the coordinate axes. In general, stationary kernels often obtain better results.

Out:
import numpy as np
import matplotlib.pyplot as plt

from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.gaussian_process.kernels import RBF, DotProduct

xx, yy = np.meshgrid(np.linspace(-3, 3, 50),
                     np.linspace(-3, 3, 50))
rng = np.random.RandomState(0)
X = rng.randn(200, 2)
Y = np.logical_xor(X[:, 0] > 0, X[:, 1] > 0)

# fit the model
plt.figure(figsize=(10, 5))
kernels = [1.0 * RBF(length_scale=1.0), 1.0 * DotProduct(sigma_0=1.0)**2]
for i, kernel in enumerate(kernels):
    clf = GaussianProcessClassifier(kernel=kernel, warm_start=True).fit(X, Y)

    # plot the decision function for each datapoint on the grid
    Z = clf.predict_proba(np.vstack((xx.ravel(), yy.ravel())).T)[:, 1]
    Z = Z.reshape(xx.shape)

    plt.subplot(1, 2, i + 1)
    image = plt.imshow(Z, interpolation='nearest',
                       extent=(xx.min(), xx.max(), yy.min(), yy.max()),
                       aspect='auto', origin='lower', cmap=plt.cm.PuOr_r)
    contours = plt.contour(xx, yy, Z, levels=[0.5], linewidths=2,
                           colors=['k'])
    plt.scatter(X[:, 0], X[:, 1], s=30, c=Y, cmap=plt.cm.Paired,
                edgecolors=(0, 0, 0))
    plt.xticks(())
    plt.yticks(())
    plt.axis([-3, 3, -3, 3])
plt.colorbar(image)
6.15.2 Gaussian process classification (GPC) on iris dataset

This example illustrates the predicted probability of GPC for an isotropic and anisotropic RBF kernel on a two-dimensional version for the iris-dataset. The anisotropic RBF kernel obtains slightly higher log-marginal-likelihood by assigning different length-scales to the two feature dimensions.
gpc_rbf_anisotropic = GaussianProcessClassifier(kernel=kernel).fit(X, y)

# create a mesh to plot in
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))

titles = ["Isotropic RBF", "Anisotropic RBF"]
plt.figure(figsize=(10, 5))
for i, clf in enumerate((gpc_rbf_isotropic, gpc_rbf_anisotropic)):
    # Plot the predicted probabilities. For that, we will assign a color to
    # each point in the mesh [x_min, m_max]x[y_min, y_max].
    plt.subplot(1, 2, i + 1)
    Z = clf.predict_proba(np.c_[xx.ravel(), yy.ravel()])
    # Put the result into a color plot
    Z = Z.reshape((xx.shape[0], xx.shape[1], 3))
    plt.imshow(Z, extent=(x_min, x_max, y_min, y_max), origin="lower")
    # Plot also the training points
    plt.scatter(X[:, 0], X[:, 1], c=np.array(['r', 'g', 'b'])[y],
                edgecolors=(0, 0, 0))
    plt.xlabel('Sepal length')
    plt.ylabel('Sepal width')
    if i == 0:
        plt.title("$s$, LML: \$%.3f\$ %
                   (titles[i], clf.log_marginal_likelihood(clf.kernel_.theta)))

plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 29.007 seconds)

6.15.3 Comparison of kernel ridge and Gaussian process regression

Both kernel ridge regression (KRR) and Gaussian process regression (GPR) learn a target function by employing internally the “kernel trick”. KRR learns a linear function in the space induced by the respective kernel which corresponds to a non-linear function in the original space. The linear function in the kernel space is chosen based on the mean-squared error loss with ridge regularization. GPR uses the kernel to define the covariance of a prior distribution over the target functions and uses the observed training data to define a likelihood function. Based on Bayes theorem, a (Gaussian) posterior distribution over target functions is defined, whose mean is used for prediction.

A major difference is that GPR can choose the kernel’s hyperparameters based on gradient-ascent on the marginal likelihood function while KRR needs to perform a grid search on a cross-validated loss function (mean-squared error loss). A further difference is that GPR learns a generative, probabilistic model of the target function and can thus provide meaningful confidence intervals and posterior samples along with the predictions while KRR only provides predictions.

This example illustrates both methods on an artificial dataset, which consists of a sinusoidal target function and strong noise. The figure compares the learned model of KRR and GPR based on a ExpSineSquared kernel, which is suited for learning periodic functions. The kernel’s hyperparameters control the smoothness (l) and periodicity of the kernel.
Moreover, the noise level of the data is learned explicitly by GPR by an additional WhiteKernel component in the kernel and by the regularization parameter alpha of KRR.

The figure shows that both methods learn reasonable models of the target function. GPR correctly identifies the periodicity of the function to be roughly 2*pi (6.28), while KRR chooses the doubled periodicity 4*pi. Besides that, GPR provides reasonable confidence bounds on the prediction which are not available for KRR. A major difference between the two methods is the time required for fitting and predicting: while fitting KRR is fast in principle, the grid-search for hyperparameter optimization scales exponentially with the number of hyperparameters ("curse of dimensionality"). The gradient-based optimization of the parameters in GPR does not suffer from this exponential scaling and is thus considerably faster on this example with 3-dimensional hyperparameter space. The time for predicting is similar; however, generating the variance of the predictive distribution of GPR takes considerably longer than just predicting the mean.

Out:

```
Time for KRR fitting: 4.181
Time for GPR fitting: 0.104
Time for KRR prediction: 0.043
Time for GPR prediction: 0.053
Time for GPR prediction with standard-deviation: 0.059
```

```
print(__doc__)

# Authors: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD 3 clause

import time

import numpy as np
```
import matplotlib.pyplot as plt
from sklearn.kernel_ridge import KernelRidge
from sklearn.model_selection import GridSearchCV
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import WhiteKernel, ExpSineSquared

rng = np.random.RandomState(0)

# Generate sample data
X = 15 * rng.rand(100, 1)
y = np.sin(X).ravel()
y += 3 * (0.5 - rng.rand(X.shape[0]))  # add noise

# Fit KernelRidge with parameter selection based on 5-fold cross validation
param_grid = {
    "alpha": [1e0, 1e-1, 1e-2, 1e-3],
    "kernel": [ExpSineSquared(l, p)
               for l in np.logspace(-2, 2, 10)
               for p in np.logspace(0, 2, 10)]
}
kr = GridSearchCV(KernelRidge(), param_grid=param_grid)
stime = time.time()
kr.fit(X, y)
print("Time for KRR fitting: %.3f" % (time.time() - stime))

gp_kernel = ExpSineSquared(1.0, 5.0, periodicity_bounds=(1e-2, 1e1)) + WhiteKernel(1e-1)
gpr = GaussianProcessRegressor(kernel=gp_kernel)
stime = time.time()
gpr.fit(X, y)
print("Time for GPR fitting: %.3f" % (time.time() - stime))

# Predict using kernel ridge
X_plot = np.linspace(0, 20, 10000)[:, None]
stime = time.time()
y_kr = kr.predict(X_plot)
print("Time for KRR prediction: %.3f" % (time.time() - stime))

# Predict using gaussian process regressor
stime = time.time()
y_gpr = gpr.predict(X_plot, return_std=False)
print("Time for GPR prediction: %.3f" % (time.time() - stime))

stime = time.time()
y_gpr, y_std = gpr.predict(X_plot, return_std=True)
print("Time for GPR prediction with standard-deviation: %.3f" % (time.time() - stime))

# Plot results
plt.figure(figsize=(10, 5))
plt.scatter(X, y, c='k', label='data')
plt.plot(X_plot, np.sin(X_plot), color='navy', lw=lw, label='True')
plt.plot(X_plot, y_kr, color='turquoise', lw=lw, label='KRR ($\alpha$)' % kr.best_params_)
plt.plot(X_plot, y_gpr, color='darkorange', lw=lw, label='GPR ($\alpha$)' % gpr.kernel_)
plt.fill_between(X_plot[:, 0], y_gpr - y_std, y_gpr + y_std, color='darkorange',
(continues on next page)
plt.xlabel('data')
plt.ylabel('target')
plt.xlim(0, 20)
plt.ylim(-4, 4)
plt.title('GPR versus Kernel Ridge')
plt.legend(loc="best", scatterpoints=1, prop={'size': 8})
plt.show()

Total running time of the script: ( 0 minutes 4.620 seconds)

6.15.4 Illustration of prior and posterior Gaussian process for different kernels

This example illustrates the prior and posterior of a GPR with different kernels. Mean, standard deviation, and 10 samples are shown for both prior and posterior.
Prior (kernel: $1^{\times}2 \times \text{RationalQuadratic}(\text{alpha}=0.1, \text{length_scale}=1))$

Posterior (kernel: $0.594^{\times}2 \times \text{RationalQuadratic}(\text{alpha}=1e+05, \text{length_scale}=0.279))$
Log-Likelihood: -0.067
6.15. Gaussian Process for Machine Learning
Out:

```
/home/circleci/project/sklearn/gaussian_process/kernels.py:411: ConvergenceWarning:
The optimal value found for dimension 0 of parameter k2__alpha is close to the
specified upper bound 100000.0. Increasing the bound and calling fit again may find
a better value.
warnings.warn("The optimal value found for "
/home/circleci/project/sklearn/gaussian_process/_gpr.py:509: ConvergenceWarning:
lbfgs failed to converge (status=2): ABNORMAL_TERMINATION_IN_LNSRCH.

Increase the number of iterations (max_iter) or scale the data as shown in:
_check_optimize_result("lbfgs", opt_res)
/home/circleci/project/sklearn/gaussian_process/_gpr.py:375: UserWarning: Predicted
variances smaller than 0. Setting those variances to 0.
warnings.warn("Predicted variances smaller than 0. "
```
# Prior (kernel: %s)  

# Generate data and fit GP
rng = np.random.RandomState(4)
X = rng.uniform(0, 5, 10)[..., np.newaxis]
y = np.sin((X[:, 0] - 2.5) ** 2)
gp.fit(X, y)

# Plot posterior
plt.subplot(2, 1, 2)
X_ = np.linspace(0, 5, 100)
y_mean, y_std = gp.predict(X_[:, np.newaxis], return_std=True)
plt.plot(X_, y_mean, 'k', lw=3, zorder=9)
plt.fill_between(X_, y_mean - y_std, y_mean + y_std,
                 alpha=0.2, color='k')
y_samples = gp.sample_y(X_[:, np.newaxis], 10)
plt.plot(X_, y_samples, lw=1)
plt.xlim(0, 5)
plt.ylim(-3, 3)
plt.title("Posterior (kernel: %s)" % kernel, fontsize=12)

(continues on next page)
6.15.5 Iso-probability lines for Gaussian Processes classification (GPC)

A two-dimensional classification example showing iso-probability lines for the predicted probabilities.
Learned kernel: 0.0256**2 * DotProduct(sigma_0=5.72)** 2
/home/circleci/project/examples/gaussian_process/plot_gpc_isoprobability.py:80:
- MatplotlibDeprecationWarning: The 'norm' parameter to Colorbar has no effect_ 
- because it is overridden by the mappable; it is deprecated since 3.3 and will be_ 
- removed two minor releases later.
- cb = plt.colorbar(cax, ticks=[0., 0.2, 0.4, 0.6, 0.8, 1.], norm=norm)

print(__doc__)

# Author: Vincent Dubourg <vincent.dubourg@gmail.com>
# Adapted to GaussianProcessClassifier:
#     Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD 3 clause

import numpy as np
from matplotlib import pyplot as plt
from matplotlib import cm
from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.gaussian_process.kernels import DotProduct, ConstantKernel as C

# A few constants
lim = 8

def g(x):
    
    """The function to predict (classification will then consist in predicting
    whether g(x) <= 0 or not)""
    return 5. - x[:, 1] - .5 * x[:, 0]** 2.

# Design of experiments
X = np.array([-4.61611719, -6.00099547],
            [4.10469096, 5.32782448],
            [0.00000000, -0.50000000],
            [-6.17289014, -4.6984743],
            [1.3109306, -6.93271427],
            [-5.03823144, 3.10584743],
            [-2.87600388, 6.74310541],
            [5.21301203, 4.26386883])

# Observations
y = np.array(g(X) > 0, dtype=int)

# Instantiate and fit Gaussian Process Model
kernel = C(0.1, (1e-5, np.inf)) * DotProduct(sigma_0=0.1)** 2
gp = GaussianProcessClassifier(kernel=kernel)
gp.fit(X, y)
print("Learned kernel: %s " % gp.kernel_)

# Evaluate real function and the predicted probability
res = 50

(continues on next page)
x1, x2 = np.meshgrid(np.linspace(- lim, lim, res),
                    np.linspace(- lim, lim, res))
xx = np.vstack([x1.reshape(x1.size), x2.reshape(x2.size)]).T

y_true = q(xx)
y_prob = gp.predict_proba(xx)[:, 1]
y_true = y_true.reshape((res, res))
y_prob = y_prob.reshape((res, res))

# Plot the probabilistic classification iso-values
fig = plt.figure(1)
ax = fig.gca()
ax.axes.set_aspect('equal')
plt.xticks([])
plt.yticks([])
ax.set_xticklabels([])
ax.set_yticklabels([])
plt.xlabel('

\$x_1\$

')
plt.ylabel('

\$x_2\$

')
cax = plt.imshow(y_prob, cmap=cm.gray_r, alpha=0.8,
                 extent=(-lim, lim, -lim, lim))
norm = plt.matplotlib.colors.Normalize(vmin=0., vmax=0.9)
cb = plt.colorbar(cax, ticks=[0., 0.2, 0.4, 0.6, 0.8, 1.], norm=norm)
cb.set_label(r'${\mathbb{P}}\left[\hat{G}(\mathbf{x}) \leq 0\right]$')
plt.clim(0, 1)
plt.plot(X[y <= 0, 0], X[y <= 0, 1], 'r.', markersize=12)
plt.plot(X[y > 0, 0], X[y > 0, 1], 'b.', markersize=12)
plt.contour(x1, x2, y_true, [0.], colors='k', linestyles='dashdot')

cs = plt.contour(x1, x2, y_prob, [0.666], colors='b',
                 linestyles='solid')
plt.clabel(cs, fontsize=11)

cs = plt.contour(x1, x2, y_prob, [0.5], colors='k',
                 linestyles='dashed')
plt.clabel(cs, fontsize=11)

cs = plt.contour(x1, x2, y_prob, [0.334], colors='r',
                 linestyles='solid')
plt.clabel(cs, fontsize=11)
plt.show()

Total running time of the script: ( 0 minutes 0.273 seconds)
6.15.6 Probabilistic predictions with Gaussian process classification (GPC)

This example illustrates the predicted probability of GPC for an RBF kernel with different choices of the hyperparameters. The first figure shows the predicted probability of GPC with arbitrarily chosen hyperparameters and with the hyperparameters corresponding to the maximum log-marginal-likelihood (LML).

While the hyperparameters chosen by optimizing LML have a considerable larger LML, they perform slightly worse according to the log-loss on test data. The figure shows that this is because they exhibit a steep change of the class probabilities at the class boundaries (which is good) but have predicted probabilities close to 0.5 far away from the class boundaries (which is bad). This undesirable effect is caused by the Laplace approximation used internally by GPC.

The second figure shows the log-marginal-likelihood for different choices of the kernel’s hyperparameters, highlighting the two choices of the hyperparameters used in the first figure by black dots.
Out:

Log Marginal Likelihood (initial): -17.598
Log Marginal Likelihood (optimized): -3.875
Accuracy: 1.000 (initial) 1.000 (optimized)
Log-loss: 0.214 (initial) 0.319 (optimized)

/home/circleci/project/examples/gaussian_process/plot_gpc.py:94:
  → MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  → as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  → with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
  → 'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolor(Theta0, Theta1, LML)

print(__doc__)

# Authors: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
#
# License: BSD 3 clause

import numpy as np

from matplotlib import pyplot as plt

(continues on next page)
from sklearn.metrics import accuracy_score, log_loss
from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.gaussian_process.kernels import RBF

# Generate data
train_size = 50
rng = np.random.RandomState(0)
X = rng.uniform(0, 5, 100)[:, np.newaxis]
y = np.array(X[:, 0] > 2.5, dtype=int)

# Specify Gaussian Processes with fixed and optimized hyperparameters
gp_fix = GaussianProcessClassifier(kernel=1.0 * RBF(length_scale=1.0), optimizer=None)
gp_fix.fit(X[:train_size], y[:train_size])
gp_opt = GaussianProcessClassifier(kernel=1.0 * RBF(length_scale=1.0))
gp_opt.fit(X[:train_size], y[:train_size])

print("Log Marginal Likelihood (initial): %.3f" % gp_fix.log_marginal_likelihood(gp_fix.kernel_.theta))
print("Log Marginal Likelihood (optimized): %.3f" % gp_opt.log_marginal_likelihood(gp_opt.kernel_.theta))

print("Accuracy: %.3f (initial) %.3f (optimized)" % (accuracy_score(y[:train_size], gp_fix.predict(X[:train_size])),
                                                      accuracy_score(y[:train_size], gp_opt.predict(X[:train_size]))))

print("Log-loss: %.3f (initial) %.3f (optimized)" % (log_loss(y[:train_size], gp_fix.predict_proba(X[:train_size])[:, 1]),
                                                   log_loss(y[:train_size], gp_opt.predict_proba(X[:train_size])[:, 1])))

# Plot posteriors
plt.figure()
plt.scatter(X[:train_size, 0], y[:train_size], c='k', label="Train data",
            edgecolors=(0, 0, 0))
plt.scatter(X[train_size:, 0], y[train_size:], c='g', label="Test data",
            edgecolors=(0, 0, 0))
X_ = np.linspace(0, 5, 100)
plt.plot(X_, gp_fix.predict_proba(X_[:, np.newaxis])[:, 1], 'r',
         label="Initial kernel: $%s$" % gp_fix.kernel_)
plt.plot(X_, gp_opt.predict_proba(X_[:, np.newaxis])[:, 1], 'b',
         label="Optimized kernel: $%s$" % gp_opt.kernel_)
plt.xlabel("Feature")
plt.ylabel("Class 1 probability")
plt.xlim(0, 5)
plt.ylim(-0.25, 1.5)
plt.legend(loc="best")

# Plot LML landscape
plt.figure()
theta0 = np.logspace(0, 8, 30)
theta1 = np.logspace(-1, 1, 29)
Theta0, Theta1 = np.meshgrid(theta0, theta1)
LML = [[gp_opt.log_marginal_likelihood(np.log([Theta0[i, j], Theta1[i, j]]))
        for i in range(Theta0.shape[0])]
       for j in range(Theta0.shape[1])]

(continues on next page)
LML = np.array(LML).T
plt.plot(np.exp(gp_fix.kernel_.theta)[0], np.exp(gp_fix.kernel_.theta)[1],
         'ko', zorder=10)
plt.plot(np.exp(gp_opt.kernel_.theta)[0], np.exp(gp_opt.kernel_.theta)[1],
         'ko', zorder=10)
plt.pcolor(Theta0, Theta1, LML)
plt.xscale("log")
plt.yscale("log")
plt.colorbar()
plt.xlabel("Magnitude")
plt.ylabel("Length-scale")
plt.title("Log-marginal-likelihood")
plt.show()

**Total running time of the script:** ( 0 minutes 3.014 seconds)

### 6.15.7 Gaussian process regression (GPR) with noise-level estimation

This example illustrates that GPR with a sum-kernel including a WhiteKernel can estimate the noise level of data. An illustration of the log-marginal-likelihood (LML) landscape shows that there exist two local maxima of LML. The first corresponds to a model with a high noise level and a large length scale, which explains all variations in the data by noise. The second one has a smaller noise level and shorter length scale, which explains most of the variation by the noise-free functional relationship. The second model has a higher likelihood; however, depending on the initial value for the hyperparameters, the gradient-based optimization might also converge to the high-noise solution. It is thus important to repeat the optimization several times for different initializations.
Initial: $1^{**2} \cdot \text{RBF}(\text{length_scale}=100) + \text{WhiteKernel}(\text{noise_level}=1)$
Optimum: $0.00315^{**2} \cdot \text{RBF}(\text{length_scale}=109) + \text{WhiteKernel}(\text{noise_level}=0)$
Log-Marginal-Likelihood: $-23.87233736198489$
Initial: 1**2 * RBF(length_scale=1) + WhiteKernel(noise_level=1e-05)
Optimum: 0.64**2 * RBF(length_scale=0.365) + WhiteKernel(noise_level=0).
Log-Marginal-Likelihood: -21.805090890162035
```python
print(__doc__)

# Authors: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
#
# License: BSD 3 clause

import numpy as np

from matplotlib import pyplot as plt
from matplotlib.colors import LogNorm

from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import RBF, WhiteKernel
```

(continues on next page)
rng = np.random.RandomState(0)
X = rng.uniform(0, 5, 20)[:, np.newaxis]
y = 0.5 * np.sin(3 * X[:, 0]) + rng.normal(0, 0.5, X.shape[0])

# First run
plt.figure()
kern = 1.0 * RBF(length_scale=100.0, length_scale_bounds=(1e-2, 1e3)) \
   + WhiteKernel(noise_level=1, noise_level_bounds=(1e-10, 1e+1))
gp = GaussianProcessRegressor(kernel=kern,
a  lpha=0.0).fit(X, y)
X_ = np.linspace(0, 5, 100)
y_mean, y_cov = gp.predict(X_[:, np.newaxis], return_cov=True)
plt.plot(X_, y_mean, 'k', lw=3, zorder=9)
plt.fill_between(X_, y_mean - np.sqrt(np.diag(y_cov)),
              y_mean + np.sqrt(np.diag(y_cov)),
              alpha=0.5, color='k')
plt.plot(X_, 0.5*np.sin(3*X_), 'r', lw=3, zorder=9)
plt.scatter(X[:, 0], y, c='r', s=50, zorder=10, edgecolors=(0, 0, 0))
plt.title("Initial: %s
Optimum: %s
Log-Marginal-Likelihood: %s"
  % (kernel, gp.kernel_,
    gp.log_marginal_likelihood(gp.kernel_.theta)))
plt.tight_layout()

# Second run
plt.figure()
kern = 1.0 * RBF(length_scale=1.0, length_scale_bounds=(1e-2, 1e3)) \
   + WhiteKernel(noise_level=1e-5, noise_level_bounds=(1e-10, 1e+1))
gp = GaussianProcessRegressor(kernel=kern,
a  lpha=0.0).fit(X, y)
X_ = np.linspace(0, 5, 100)
y_mean, y_cov = gp.predict(X_[:, np.newaxis], return_cov=True)
plt.plot(X_, y_mean, 'k', lw=3, zorder=9)
plt.fill_between(X_, y_mean - np.sqrt(np.diag(y_cov)),
              y_mean + np.sqrt(np.diag(y_cov)),
              alpha=0.5, color='k')
plt.plot(X_, 0.5*np.sin(3*X_), 'r', lw=3, zorder=9)
plt.scatter(X[:, 0], y, c='r', s=50, zorder=10, edgecolors=(0, 0, 0))
plt.title("Initial: %s
Optimum: %s
Log-Marginal-Likelihood: %s"
  % (kernel, gp.kernel_,
    gp.log_marginal_likelihood(gp.kernel_.theta)))
plt.tight_layout()

# Plot LML landscape
plt.figure()
theta0 = np.logspace(-2, 3, 49)
theta1 = np.logspace(-2, 0, 50)
Theta0, Theta1 = np.meshgrid(theta0, theta1)
LML = [gp.log_marginal_likelihood(np.log([0.36, Theta0[i, j], Theta1[i, j]]))
   for i in range(Theta0.shape[0]) for j in range(Theta0.shape[1])]
LML = np.array(LML).T
vmin, vmax = (-LML).min(), (-LML).max()
level = np.around(np.logspace(np.log10(vmin), np.log10(vmax), 50), decimals=1)
plt.contour(Theta0, Theta1, -LML,
           levels=level, norm=LogNorm(vmin=vmin, vmax=vmax))
plt.colorbar()
plt.xscale("log")
plt.yscale("log")
plt.xlabel("Length-scale")
plt.ylabel("Noise-level")
plt.title("Log-marginal-likelihood")
plt.tight_layout()
plt.show()

**Total running time of the script:** ( 0 minutes 3.746 seconds)

### 6.15.8 Gaussian Processes regression: basic introductory example

A simple one-dimensional regression example computed in two different ways:

1. A noise-free case
2. A noisy case with known noise-level per datapoint

In both cases, the kernel’s parameters are estimated using the maximum likelihood principle.

The figures illustrate the interpolating property of the Gaussian Process model as well as its probabilistic nature in the form of a pointwise 95% confidence interval.

Note that the parameter \( \alpha \) is applied as a Tikhonov regularization of the assumed covariance between the training points.
import numpy as np
from matplotlib import pyplot as plt
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import RBF, ConstantKernel as C

np.random.seed(1)

def f(x):
    return x * np.sin(x)

# First the noiseless case
X = np.atleast_2d([1., 3., 5., 6., 7., 8.]).T

# Observations
y = f(X).ravel()
# Mesh the input space for evaluations of the real function, the prediction and its MSE

```python
x = np.atleast_2d(np.linspace(0, 10, 1000)).T
```

# Instantiate a Gaussian Process model
```python
kernel = C(1.0, (1e-3, 1e3)) * RBF(10, (1e-2, 1e2))
gp = GaussianProcessRegressor(kernel=kernel, n_restarts_optimizer=9)
```

# Fit to data using Maximum Likelihood Estimation of the parameters
```python
gp.fit(X, y)
```

# Make the prediction on the meshed x-axis (ask for MSE as well)
```python
y_pred, sigma = gp.predict(x, return_std=True)
```

# Plot the function, the prediction and the 95% confidence interval based on the MSE
```python
plt.figure()
plt.plot(x, f(x), 'r:', label=r'$f(x) = x\sin(x)$')
plt.plot(X, y, 'r.', markersize=10, label='Observations')
plt.plot(x, y_pred, 'b-', label='Prediction')
plt.fill(np.concatenate([x, x[::-1]]),
         np.concatenate([y_pred - 1.9600 * sigma,
                         (y_pred + 1.9600 * sigma)[::-1]]),
         alpha=.5, fc='b', ec='None', label='95% confidence interval')
plt.xlabel('$x$')
plt.ylabel('$f(x)$')
plt.ylim(-10, 20)
plt.legend(loc='upper left')
```

# now the noisy case
```python
X = np.linspace(0.1, 9.9, 20)
X = np.atleast_2d(X).T

# Observations and noise
y = f(X).ravel()
dy = 0.5 + 1.0 * np.random.random(y.shape)
noise = np.random.normal(0, dy)
y += noise
```

# Instantiate a Gaussian Process model
```python
gp = GaussianProcessRegressor(kernel=kernel, alpha=dy ** 2,
                               n_restarts_optimizer=10)
```

# Fit to data using Maximum Likelihood Estimation of the parameters
```python
gp.fit(X, y)
```

# Make the prediction on the meshed x-axis (ask for MSE as well)
```python
y_pred, sigma = gp.predict(x, return_std=True)
```

# Plot the function, the prediction and the 95% confidence interval based on the MSE
```python
plt.figure()
plt.plot(x, f(x), 'r:', label=r'$f(x) = x\sin(x)$')
plt.errorbar(X.ravel(), y, dy, fmt='r.', markersize=10, label='Observations')
plt.plot(x, y_pred, 'b-', label='Prediction')
plt.fill(np.concatenate([x, x[::-1]]),
         np.concatenate([y_pred - 1.9600 * sigma,
                         (y_pred + 1.9600 * sigma)[::-1]]),
         alpha=.5, fc='b', ec='None', label='95% confidence interval')
plt.xlabel('$x$')
plt.ylabel('$f(x)$')
plt.ylim(-10, 20)
plt.legend(loc='upper left')
```

(continues on next page)
6.15.9 Gaussian process regression (GPR) on Mauna Loa CO2 data.

This example is based on Section 5.4.3 of “Gaussian Processes for Machine Learning” [RW2006]. It illustrates an example of complex kernel engineering and hyperparameter optimization using gradient ascent on the log-marginal-likelihood. The data consists of the monthly average atmospheric CO2 concentrations (in parts per million by volume (ppmv)) collected at the Mauna Loa Observatory in Hawaii, between 1958 and 2001. The objective is to model the CO2 concentration as a function of the time t.

The kernel is composed of several terms that are responsible for explaining different properties of the signal:

- a long term, smooth rising trend is to be explained by an RBF kernel. The RBF kernel with a large length-scale enforces this component to be smooth; it is not enforced that the trend is rising which leaves this choice to the GP. The specific length-scale and the amplitude are free hyperparameters.

- a seasonal component, which is to be explained by the periodic ExpSineSquared kernel with a fixed periodicity of 1 year. The length-scale of this periodic component, controlling its smoothness, is a free parameter. In order to allow decaying away from exact periodicity, the product with an RBF kernel is taken. The length-scale of this RBF component controls the decay time and is a further free parameter.

- smaller, medium term irregularities are to be explained by a RationalQuadratic kernel component, whose length-scale and alpha parameter, which determines the diffuseness of the length-scales, are to be determined. According to [RW2006], these irregularities can better be explained by a RationalQuadratic than an RBF kernel component, probably because it can accommodate several length-scales.

- a “noise” term, consisting of an RBF kernel contribution, which shall explain the correlated noise components such as local weather phenomena, and a WhiteKernel contribution for the white noise. The relative amplitudes and the RBF’s length scale are further free parameters.

Maximizing the log-marginal-likelihood after subtracting the target’s mean yields the following kernel with an LML of -83.214:

\[
34.4^{**2} \times \text{RBF}(\text{length}\_\text{scale}=41.8) \\
+ 3.27^{**2} \times \text{RBF}(\text{length}\_\text{scale}=180) \times \text{ExpSineSquared}(\text{length}\_\text{scale}=1.44, \text{periodicity}=1) \\
+ 0.446^{**2} \times \text{RationalQuadratic}(\text{alpha}=17.7, \text{length}\_\text{scale}=0.957) \\
+ 0.197^{**2} \times \text{RBF}(\text{length}\_\text{scale}=0.138) + \text{WhiteKernel}(\text{noise}\_\text{level}=0.0336)
\]

Thus, most of the target signal (34.4ppm) is explained by a long-term rising trend (length-scale 41.8 years). The periodic component has an amplitude of 3.27ppm, a decay time of 180 years and a length-scale of 1.44. The long decay time indicates that we have a locally very close to periodic seasonal component. The correlated noise has an amplitude of 0.197ppm with a length scale of 0.138 years and a white-noise contribution of 0.197ppm. Thus, the overall noise level is very small, indicating that the data can be very well explained by the model. The figure shows also that the model makes very confident predictions until around 2015.
Out:

GPML kernel: $66^2 \times \text{RBF}(\text{length}\_\text{scale}=67) + 2.4^2 \times \text{RBF}(\text{length}\_\text{scale}=90) \times \text{ExpSineSquared}(\text{length}\_\text{scale}=1.3, \text{periodicity}=1) + 0.66^2 \times \text{RationalQuadratic}(\text{alpha}=0.78, \text{length}\_\text{scale}=1.2) + 0.18^2 \times \text{RBF}(\text{length}\_\text{scale}=0.134) \times \text{WhiteKernel}(\text{noise}\_\text{level}=0.0361)$

Log-marginal-likelihood: 155.006

Learned kernel: $2.62^2 \times \text{RBF}(\text{length}\_\text{scale}=51.6) + 0.155^2 \times \text{RBF}(\text{length}\_\text{scale}=91.5) \times \text{ExpSineSquared}(\text{length}\_\text{scale}=1.49, \text{periodicity}=1) + 0.0315^2 \times \text{RationalQuadratic}(\text{alpha}=2.88, \text{length}\_\text{scale}=0.968) + 0.011^2 \times \text{RBF}(\text{length}\_\text{scale}=0.122) \times \text{WhiteKernel}(\text{noise}\_\text{level}=0.000126)$

Log-marginal-likelihood: 1362.655

---

# Authors: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>

# License: BSD 3 clause

```python
import numpy as np
```

(continues on next page)
from matplotlib import pyplot as plt
from sklearn.datasets import fetch_openml
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process.kernels import RBF, WhiteKernel, RationalQuadratic, ExpSineSquared

print(__doc__)

def load_mauna_loa_atmospheric_co2():
    ml_data = fetch_openml(data_id=41187, as_frame=False)
    months = []
    ppmv_sums = []
    counts = []

    y = ml_data.data[:, 0]
    m = ml_data.data[:, 1]
    month_float = y + (m - 1) / 12
    ppmvs = ml_data.target

    for month, ppmv in zip(month_float, ppmvs):
        if not months or month != months[-1]:
            months.append(month)
            ppmv_sums.append(ppmv)
            counts.append(1)
        else:
            ppmv_sums[-1] += ppmv
            counts[-1] += 1

    months = np.asarray(months).reshape(-1, 1)
    avg_ppmvs = np.asarray(ppmv_sums) / counts
    return months, avg_ppmvs

X, y = load_mauna_loa_atmospheric_co2()

# Kernel with parameters given in GPML book
k1 = 66.0**2 * RBF(length_scale=67.0)  # long term smooth rising trend
k2 = 2.4**2 * RBF(length_scale=90.0) * ExpSineSquared(length_scale=1.3, periodicity=1.0)  # seasonal component
k3 = 0.66**2  # medium term irregularity
k4 = 0.18**2 * RBF(length_scale=0.134) * WhiteKernel(noise_level=0.19**2)  # noise terms
kernel_gpml = k1 + k2 + k3 + k4

gp = GaussianProcessRegressor(kernel=kernel_gpml, alpha=0, optimizer=None, normalize_y=True)
gp.fit(X, y)

print("GPML kernel: %s" % gp.kernel_)
print("Log-marginal-likelihood: %.3f" % gp.log_marginal_likelihood(gp.kernel_.theta))
# Kernel with optimized parameters
k1 = 50.0**2 * RBF(length_scale=50.0)  # long term smooth rising trend
k2 = 2.0**2 * RBF(length_scale=100.0) \
    * ExpSineSquared(length_scale=1.0, periodicity=1.0, periodicity_bounds="fixed")  # seasonal component

# medium term irregularities
k3 = 0.5**2 * RationalQuadratic(length_scale=1.0, alpha=1.0)
k4 = 0.1**2 * RBF(length_scale=0.1) \
    + WhiteKernel(noise_level=0.1**2, noise_level_bounds=(1e-5, np.inf))  # noise terms

kernel = k1 + k2 + k3 + k4

# Illustration
plt.scatter(X, y, c='k')
plt.plot(X_, y_pred)
plt.fill_between(X_[:, 0], y_pred - y_std, y_pred + y_std, alpha=0.5, color='k')
plt.xlim(X_.min(), X_.max())
plt.xlabel("Year")
plt.ylabel(r"CO$_2$ in ppm")
plt.title(r"Atmospheric CO$_2$ concentration at Mauna Loa")
plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 13.901 seconds)

6.15.10 Gaussian processes on discrete data structures

This example illustrates the use of Gaussian processes for regression and classification tasks on data that are not in fixed-length feature vector form. This is achieved through the use of kernel functions that operates directly on discrete structures such as variable-length sequences, trees, and graphs.

Specifically, here the input variables are some gene sequences stored as variable-length strings consisting of letters ‘A’, ‘T’, ‘C’, and ‘G’, while the output variables are floating point numbers and True/False labels in the regression and classification tasks, respectively.

A kernel between the gene sequences is defined using R-convolution\(^1\) by integrating a binary letter-wise kernel over all pairs of letters among a pair of strings.

This example will generate three figures.

In the first figure, we visualize the value of the kernel, i.e. the similarity of the sequences, using a colormap. Brighter color here indicates higher similarity.


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In the second figure, we show some regression result on a dataset of 6 sequences. Here we use the 1st, 2nd, 4th, and 5th sequences as the training set to make predictions on the 3rd and 6th sequences.

In the third figure, we demonstrate a classification model by training on 6 sequences and make predictions on another 5 sequences. The ground truth here is simply whether there is at least one ‘A’ in the sequence. Here the model makes four correct classifications and fails on one.

In the second figure, we show some regression result on a dataset of 6 sequences. Here we use the 1st, 2nd, 4th, and 5th sequences as the training set to make predictions on the 3rd and 6th sequences.

In the third figure, we demonstrate a classification model by training on 6 sequences and make predictions on another 5 sequences. The ground truth here is simply whether there is at least one ‘A’ in the sequence. Here the model makes four correct classifications and fails on one.
Importing necessary modules:

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.gaussian_process.kernels import Kernel, Hyperparameter
from sklearn.gaussian_process.kernels import GenericKernelMixin
from sklearn.gaussian_process import GaussianProcessRegressor
from sklearn.gaussian_process import GaussianProcessClassifier
from sklearn.base import clone
```

Defining the `SequenceKernel` class:

```python
class SequenceKernel(GenericKernelMixin, Kernel):
    '''
    A minimal (but valid) convolutional kernel for sequences of variable
    lengths.''
    def __init__(self,
        baseline_similarity=0.5,
        baseline_similarity_bounds=(1e-5, 1)):
        self.baseline_similarity = baseline_similarity
```

Out:

```
/home/circleci/project/sklearn/gaussian_process/kernels.py:402: ConvergenceWarning:
The optimal value found for dimension 0 of parameter baseline_similarity is close
to the specified lower bound 1e-05. Decreasing the bound and calling fit again may_
find a better value.
warnings.warn("The optimal value found for "
```

Print function:

```python
print(__doc__)
```

(continues on next page)
self.baseline_similarity_bounds = baseline_similarity_bounds

@property
def hyperparameter_baseline_similarity(self):
    return Hyperparameter("baseline_similarity",
                          "numeric",
                          self.baseline_similarity_bounds)

def __f__(self, s1, s2):
    
    kernel value between a pair of sequences
    
    return sum([1.0 if c1 == c2 else self.baseline_similarity
                 for c1 in s1
                 for c2 in s2])

def __g__(self, s1, s2):
    
    kernel derivative between a pair of sequences
    
    return sum([0.0 if c1 == c2 else 1.0
                 for c1 in s1
                 for c2 in s2])

def __call__(self, X, Y=None, eval_gradient=False):
    if Y is None:
        Y = X

    if eval_gradient:
        return (np.array([[self.__f__(x, y) for y in Y] for x in X]),
                np.array([[self.__g__(x, y)] for y in Y] for x in X)))
    else:
        return np.array([[self.__f__(x, y) for y in Y] for x in X])

def diag(self, X):
    return np.array([[self.__f__(x, x) for x in X]])

def is_stationary(self):
    return False

def clone_with_theta(self, theta):
    cloned = clone(self)
    cloned.theta = theta
    return cloned

kernel = SequenceKernel()

Sequence similarity matrix under the kernel
===========================================

X = np.array(['AGCT', 'AGC', 'AACT', 'TAA', 'AAA', 'GAACA'])
K = kernel(X)
D = kernel.diag(X)
Regression
============

X = np.array(['AGCT', 'AGC', 'AACT', 'TAA', 'AAA', 'GAACA'])
Y = np.array([1.0, 1.0, 2.0, 2.0, 3.0, 3.0])
training_idx = [0, 1, 3, 4]
gp = GaussianProcessRegressor(kernel=kernel)
gp.fit(X[training_idx], Y[training_idx])

Classification
==============

X_train = np.array(['AGCT', 'CGA', 'TAAC', 'TCG', 'CTTT', 'TGCT'])
# whether there are 'A's in the sequence
Y_train = np.array([True, True, True, False, False, False])
gp = GaussianProcessClassifier(kernel)
gp.fit(X_train, Y_train)
X_test = ['AAA', 'ATAG', 'CTC', 'CT', 'C']
Y_test = [True, True, False, False, False]

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```
plt.legend()
plt.show()
```

**Total running time of the script:** (0 minutes 0.281 seconds)

## 6.16 Generalized Linear Models

Examples concerning the `sklearn.linear_model` module.

### 6.16.1 Lasso path using LARS

Computes Lasso Path along the regularization parameter using the LARS algorithm on the diabetes dataset. Each color represents a different feature of the coefficient vector, and this is displayed as a function of the regularization parameter.

Out:

```
Computing regularization path using the LARS ...
```

![LASSO Path](image)

```
print(__doc__)

# Author: Fabian Pedregosa <fabian.pedregosa@inria.fr>
# Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn import linear_model
from sklearn import datasets

X, y = datasets.load_diabetes(return_X_y=True)

print("Computing regularization path using the LARS ...")
_, _, coefs = linear_model.lars_path(X, y, method='lasso', verbose=True)

xx = np.sum(np.abs(coefs.T), axis=1)
xx /= xx[-1]

plt.plot(xx, coefs.T)
ymin, ymax = plt.ylim()
plt.vlines(xx, ymin, ymax, linestyle='dashed')
plt.xlabel('|coef| / max|coef|')
plt.ylabel('Coefficients')
plt.title('LASSO Path')
plt.axis('tight')
plt.show()

Total running time of the script: ( 0 minutes 0.102 seconds)

6.16.2 SGD: Maximum margin separating hyperplane

Plot the maximum margin separating hyperplane within a two-class separable dataset using a linear Support Vector Machines classifier trained using SGD.

6.16. Generalized Linear Models
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import SGDClassifier
from sklearn.datasets import make_blobs

# we create 50 separable points
X, Y = make_blobs(n_samples=50, centers=2, random_state=0, cluster_std=0.60)

# fit the model
clf = SGDClassifier(loss="hinge", alpha=0.01, max_iter=200)
clf.fit(X, Y)

# plot the line, the points, and the nearest vectors to the plane
xx = np.linspace(-1, 5, 10)
yy = np.linspace(-1, 5, 10)
X1, X2 = np.meshgrid(xx, yy)
Z = np.empty(X1.shape)
for (i, j), val in np.ndenumerate(X1):
    x1 = val
    x2 = X2[i, j]
    p = clf.decision_function([[x1, x2]])
    Z[i, j] = p

plt.contourf(X1, X2, Z, cmap=plt.cm.Paired)
plt.axis('tight')
plt.show()
Z[i, j] = p[0]
levels = [-1.0, 0.0, 1.0]
linestyles = ['dashed', 'solid', 'dashed']
plt.contour(X1, X2, Z, levels, colors=colors, linestyles=linestyles)
plt.scatter(X[:, 0], X[:, 1], c=Y, cmap=plt.cm.Paired,
            edgecolor='black', s=20)
plt.axis('tight')
plt.show()

Total running time of the script: ( 0 minutes 0.084 seconds)

6.16.3 Plot Ridge coefficients as a function of the regularization

Shows the effect of collinearity in the coefficients of an estimator.

**Ridge** Regression is the estimator used in this example. Each color represents a different feature of the coefficient vector, and this is displayed as a function of the regularization parameter.

This example also shows the usefulness of applying Ridge regression to highly ill-conditioned matrices. For such matrices, a slight change in the target variable can cause huge variances in the calculated weights. In such cases, it is useful to set a certain regularization (alpha) to reduce this variation (noise).

When alpha is very large, the regularization effect dominates the squared loss function and the coefficients tend to zero. At the end of the path, as alpha tends toward zero and the solution tends towards the ordinary least squares, coefficients exhibit big oscillations. In practise it is necessary to tune alpha in such a way that a balance is maintained between both.
```python
# Author: Fabian Pedregosa -- <fabian.pedregosa@inria.fr>
# License: BSD 3 clause

print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn import linear_model

# X is the 10x10 Hilbert matrix
X = 1. / (np.arange(1, 11) + np.arange(0, 10)[:, np.newaxis])
y = np.ones(10)

# Compute paths
n_alphas = 200
alphas = np.logspace(-10, -2, n_alphas)
coefs = []
for a in alphas:
    ridge = linear_model.Ridge(alpha=a, fit_intercept=False)
    ridge.fit(X, y)
    coefs.append(ridge.coef_)
```

Ridge coefficients as a function of the regularization

![Plot of Ridge coefficients as a function of the regularization](continues on next page)
### 6.16.4 SGD: convex loss functions

A plot that compares the various convex loss functions supported by `SGDClassifier`.

![Convex Loss Functions Graph](image)

```
p = print(__doc__)
import numpy as np
```
import matplotlib.pyplot as plt

def modified_huber_loss(y_true, y_pred):
    z = y_pred * y_true
    loss = -4 * z
    loss[z >= -1] = (1 - z[z >= -1]) ** 2
    loss[z >= 1.] = 0
    return loss

xmin, xmax = -4, 4
xx = np.linspace(xmin, xmax, 100)
lw = 2
plt.plot([xmin, 0, 0, xmax], [1, 1, 0, 0], color='gold', lw=lw,
         label="Zero-one loss")
plt.plot(xx, np.where(xx < 1, 1 - xx, 0), color='teal', lw=lw,
         label="Hinge loss")
plt.plot(xx, -np.minimum(xx, 0), color='yellowgreen', lw=lw,
         label="Perceptron loss")
plt.plot(xx, np.log2(1 + np.exp(-xx)), color='cornflowerblue', lw=lw,
         label="Log loss")
plt.plot(xx, np.where(xx < 1, 1 - xx, 0) ** 2, color='orange', lw=lw,
         label="Squared hinge loss")
plt.plot(xx, modified_huber_loss(xx, 1), color='darkorchid', lw=lw,
         linestyle='--', label="Modified Huber loss")
plt.ylim((0, 8))
plt.legend(loc="upper right")
plt.xlabel(r"Decision function $f(x)$")
plt.ylabel("$L(y=1, f(x))$")
plt.show()
print(__doc__)

# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from sklearn import linear_model
X_train = np.c_[.5, 1].T
y_train = [.5, 1]
X_test = np.c_[0, 2].T

(continues on next page)
```python
np.random.seed(0)

classifiers = dict(ols=linear_model.LinearRegression(),
                   ridge=linear_model.Ridge(alpha=.1))

for name, clf in classifiers.items():
    fig, ax = plt.subplots(figsize=(4, 3))
    for _ in range(6):
        this_X = .1 * np.random.normal(size=(2, 1)) + X_train
        clf.fit(this_X, y_train)
        ax.plot(X_test, clf.predict(X_test), color='gray')
        ax.scatter(this_X, y_train, s=3, c='gray', marker='o', zorder=10)

    clf.fit(X_train, y_train)
    ax.plot(X_test, clf.predict(X_test), linewidth=2, color='blue')
    ax.scatter(X_train, y_train, s=30, c='red', marker='+', zorder=10)

    ax.set_title(name)
    ax.set_xlim(0, 2)
    ax.set_ylim((0, 1.6))
    ax.set_xlabel('X')
    ax.set_ylabel('y')

    fig.tight_layout()
plt.show()
```

**Total running time of the script:** (0 minutes 0.285 seconds)

### 6.16.6 Plot Ridge coefficients as a function of the L2 regularization

*Ridge* Regression is the estimator used in this example. Each color in the left plot represents one different dimension of the coefficient vector, and this is displayed as a function of the regularization parameter. The right plot shows how exact the solution is. This example illustrates how a well defined solution is found by Ridge regression and how regularization affects the coefficients and their values. The plot on the right shows how the difference of the coefficients from the estimator changes as a function of regularization.

In this example the dependent variable Y is set as a function of the input features: \( y = X*w + c \). The coefficient vector \( w \) is randomly sampled from a normal distribution, whereas the bias term \( c \) is set to a constant.

As alpha tends toward zero the coefficients found by Ridge regression stabilize towards the randomly sampled vector \( w \). For big alpha (strong regularisation) the coefficients are smaller (eventually converging at 0) leading to a simpler and biased solution. These dependencies can be observed on the left plot.

The right plot shows the mean squared error between the coefficients found by the model and the chosen vector \( w \). Less regularised models retrieve the exact coefficients (error is equal to 0), stronger regularised models increase the error.

Please note that in this example the data is non-noisy, hence it is possible to extract the exact coefficients.
```python
# Author: Kornel Kielczewski -- <kornel.k@plusnet.pl>

import matplotlib.pyplot as plt
import numpy as np

from sklearn.datasets import make_regression
from sklearn.linear_model import Ridge
from sklearn.metrics import mean_squared_error

clf = Ridge()
X, y, w = make_regression(n_samples=10, n_features=10, coef=True,
                          random_state=1, bias=3.5)

coeefs = []
errors = []
alphas = np.logspace(-6, 6, 200)

# Train the model with different regularisation strengths
for a in alphas:
    clf.set_params(alpha=a)
    clf.fit(X, y)
    coefs.append(clf.coef_)
    errors.append(mean_squared_error(clf.coef_, w))

# Display results
plt.figure(figsize=(20, 6))
plt.subplot(121)
ax = plt.gca()
ax.plot(alphas, coefs)
ax.set_xscale('log')
plt.xlabel('alpha')
plt.ylabel('weights')
plt.title('Ridge coefficients as a function of the regularization')
plt.axis('tight')
plt.subplot(122)
ax = plt.gca()
ax.plot(alphas, errors)
ax.set_xscale('log')
```

(continues on next page)
plt.xlabel('alpha')
plt.ylabel('error')
plt.title('Coefficient error as a function of the regularization')
plt.axis('tight')
plt.show()

Total running time of the script:  0 minutes 0.506 seconds

6.16.7 SGD: Penalties

Contours of where the penalty is equal to 1 for the three penalties L1, L2 and elastic-net.

All of the above are supported by SGDClassifier and SGDRegressor.
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt

l1_color = "navy"
l2_color = "c"
elastic_net_color = "darkorange"

line = np.linspace(-1.5, 1.5, 1001)
xx, yy = np.meshgrid(line, line)

l2 = xx ** 2 + yy ** 2
l1 = np.abs(xx) + np.abs(yy)
rho = 0.5
elastic_net = rho * l1 + (1 - rho) * l2

plt.figure(figsize=(10, 10), dpi=100)
ax = plt.gca()

elastic_net_contour = plt.contour(xx, yy, elastic_net, levels=[1],
                                  colors=elastic_net_color)
l2_contour = plt.contour(xx, yy, l2, levels=[1], colors=l2_color)
l1_contour = plt.contour(xx, yy, l1, levels=[1], colors=l1_color)
ax.set_aspect("equal")
ax.spines['left'].set_position('center')
ax.spines['right'].set_color('none')
ax.spines['bottom'].set_position('center')
ax.spines['top'].set_color('none')

plt.clabel(elastic_net_contour, inline=1, fontsize=18,
           fmt={1.0: 'elastic-net'}, manual=[(-1, -1)])
plt.clabel(l2_contour, inline=1, fontsize=18,
           fmt={1.0: 'L2'}, manual=[(-1, -1)])
plt.clabel(l1_contour, inline=1, fontsize=18,
           fmt={1.0: 'L1'}, manual=[(-1, -1)])

plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 0.271 seconds)

6.16.8 Logistic function

Shown in the plot is how the logistic regression would, in this synthetic dataset, classify values as either 0 or 1, i.e. class one or two, using the logistic curve.
# Code source: Gael Varoquaux
# License: BSD 3 clause

```python
import numpy as np
import matplotlib.pyplot as plt

from sklearn import linear_model
from scipy.special import expit

# General a toy dataset: it's just a straight line with some Gaussian noise:
# x_min, x_max = -5, 5
n_samples = 100
np.random.seed(0)
X = np.random.normal(size=n_samples)
y = (X > 0).astype(float)
X[X > 0] *= 4
X += .3 * np.random.normal(size=n_samples)
X = X[:, np.newaxis]

# Fit the classifier
clf = linear_model.LogisticRegression(C=1e5)
clf.fit(X, y)

# and plot the result
plt.figure(1, figsize=(4, 3))
plt.clf()
plt.scatter(X.ravel(), y, color='black', zorder=20)
X_test = np.linspace(-5, 10, 300)
loss = expit(X_test * clf.coef_ + clf.intercept_).ravel()
plt.plot(X_test, loss, color='red', linewidth=3)
ols = linear_model.LinearRegression()
ols.fit(X, y)
plt.plot(X_test, ols.coef_ * X_test + ols.intercept_, linewidth=1)
plt.axhline(.5, color='.5')

plt.ylabel('y')
plt.xlabel('X')
plt.xticks(range(-5, 10))
plt.yticks([0, .5, 1])
plt.ylim(-.25, 1.25)
plt.xlim(-4, 10)
plt.legend(('Logistic Regression Model', 'Linear Regression Model'),
           loc='lower right', fontsize='small')
plt.tight_layout()
plt.show()
```

Total running time of the script: ( 0 minutes 0.100 seconds)
6.16.9 Polynomial interpolation

This example demonstrates how to approximate a function with a polynomial of degree n_degree by using ridge regression. Concretely, from n_samples 1d points, it suffices to build the Vandermonde matrix, which is n_samples x n_degree+1 and has the following form:

\[
[1, x_1, x_1 ** 2, x_1 ** 3, \ldots], [1, x_2, x_2 ** 2, x_2 ** 3, \ldots], \ldots
\]

Intuitively, this matrix can be interpreted as a matrix of pseudo features (the points raised to some power). The matrix is akin to (but different from) the matrix induced by a polynomial kernel.

This example shows that you can do non-linear regression with a linear model, using a pipeline to add non-linear features. Kernel methods extend this idea and can induce very high (even infinite) dimensional feature spaces.
def f(x):
    """ function to approximate by polynomial interpolation"""
    return x * np.sin(x)

# generate points used to plot
x_plot = np.linspace(0, 10, 100)

# generate points and keep a subset of them
x = np.linspace(0, 10, 100)
rng = np.random.RandomState(0)
rng.shuffle(x)
x = np.sort(x[:20])
y = f(x)

# create matrix versions of these arrays
X = x[:, np.newaxis]
X_plot = x_plot[:, np.newaxis]

colors = ['teal', 'yellowgreen', 'gold']
lw = 2
plt.plot(x_plot, f(x_plot), color='cornflowerblue', linewidth=lw,
          label="ground truth")
plt.scatter(x, y, color='navy', s=30, marker='o', label="training points")

for count, degree in enumerate([3, 4, 5]):
    model = make_pipeline(PolynomialFeatures(degree), Ridge())
    model.fit(X, y)
    y_plot = model.predict(X_plot)
    plt.plot(x_plot, y_plot, color=colors[count], linewidth=lw,
              label="degree %d" % degree)
plt.legend(loc='lower left')
plt.show()
Out:

Computing regularization path ...
This took 0.057s

print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

from time import time
import numpy as np
import matplotlib.pyplot as plt

from sklearn import linear_model
from sklearn import datasets
from sklearn.svm import l1_min_c

iris = datasets.load_iris()
X = iris.data
y = iris.target
X = X[y != 2]
y = y[y != 2]

X /= X.max()  # Normalize X to speed-up convergence

# Demo path functions

cs = l1_min_c(X, y, loss='log') * np.logspace(0, 7, 16)

print("Computing regularization path ...")
start = time()
classification = linear_model.LogisticRegression(penalty='l1', solver='liblinear',
tol=1e-6, max_iter=int(1e6),
warm_start=True,
intercept_scaling=10000.)

coefs_ = []
for c in cs:
    classification.set_params(C=c)
    classification.fit(X, y)
    coefs_.append(classification.coef_.ravel().copy())
    print("This took %0.3fs" % (time() - start))

coefs_ = np.array(coefs_)
plt.plot(np.log10(cs), coefs_, marker='o')
ymin, ymax = plt.ylim()
plt.xlabel('log(C)')
plt.ylabel('Coefficients')
plt.title('Logistic Regression Path')
plt.axis('tight')
plt.show()

Total running time of the script: ( 0 minutes 0.148 seconds)

6.16.11 Logistic Regression 3-class Classifier

Show below is a logistic-regression classifiers decision boundaries on the first two dimensions (sepal length and width) of the iris dataset. The datapoints are colored according to their labels.
```python
print(__doc__)

# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import LogisticRegression
from sklearn import datasets

# import some data to play with
iris = datasets.load_iris()
X = iris.data[:, :2]  # we only take the first two features.
Y = iris.target

# Create an instance of Logistic Regression Classifier and fit the data.
logreg = LogisticRegression(C=1e5)
logreg.fit(X, Y)

# Plot the decision boundary. For that, we will assign a color to each
# point in the mesh [x_min, x_max]x[y_min, y_max].
x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
xx, yy = np.meshgrid(np.arange(x_min, x_max, .02),
                     np.arange(y_min, y_max, .02))

Z = logreg.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)

plt.figure()
plt.pcolormesh(xx, yy, Z, cmap=plt.cm.Paired)
plt.xlabel('Sepal width (cm)')
plt.ylabel('Sepal length (cm)')
plt.scatter(X[:, 0], X[:, 1], c=Y, s=40, cmap=plt.cm.Spectral)
plt.axis('tight')
plt.show()
```
y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
h = .02  # step size in the mesh
xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))
Z = logreg.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
plt.figure(1, figsize=(4, 3))
plt.pcolormesh(xx, yy, Z, cmap=plt.cm.Paired)

# Plot also the training points
plt.scatter(X[:, 0], X[:, 1], c=Y, edgecolors='k', cmap=plt.cm.Paired)
plt.xlabel('Sepal length')
plt.ylabel('Sepal width')
plt.xlim(xx.min(), xx.max())
plt.ylim(yy.min(), yy.max())
plt.xticks(())
plt.yticks(())
plt.show()

Total running time of the script: (0 minutes 0.098 seconds)

6.16.12 SGD: Weighted samples

Plot decision function of a weighted dataset, where the size of points is proportional to its weight.
import numpy as np
import matplotlib.pyplot as plt
from sklearn import linear_model

# we create 20 points
np.random.seed(0)
X = np.r_[np.random.randn(10, 2) + [1, 1], np.random.randn(10, 2)]
y = [1] * 10 + [-1] * 10
sample_weight = 100 * np.abs(np.random.randn(20))
# and assign a bigger weight to the last 10 samples
sample_weight[:10] *= 10

# plot the weighted data points
xx, yy = np.meshgrid(np.linspace(-4, 5, 500), np.linspace(-4, 5, 500))
plt.figure()
plt.scatter(X[:, 0], X[:, 1], c=y, s=sample_weight, alpha=0.9,
cmap=plt.cm.bone, edgecolor='black')

# fit the unweighted model
clf = linear_model.SGDClassifier(alpha=0.01, max_iter=100)
clf.fit(X, y)
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
no_weights = plt.contour(xx, yy, Z, levels=[0], linestyles=['solid'])

# fit the weighted model
clf = linear_model.SGDClassifier(alpha=0.01, max_iter=100)
clf.fit(X, y, sample_weight=sample_weight)
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
samples_weights = plt.contour(xx, yy, Z, levels=[0], linestyles=['dashed'])

plt.legend([no_weights.collections[0], samples_weights.collections[0]],
            ['no weights', 'with weights'], loc='lower left')

plt.xticks(())
plt.yticks(())
plt.show()

Total running time of the script: ( 0 minutes 0.080 seconds)

### 6.16.13 Non-negative least squares

In this example, we fit a linear model with positive constraints on the regression coefficients and compare the estimated coefficients to a classic linear regression.

```python
print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.metrics import r2_score

Generate some random data

```numpy
np.random.seed(42)
n_samples, n_features = 200, 50
X = np.random.randn(n_samples, n_features)
true_coef = 3 * np.random.randn(n_features)
# Threshold coefficients to render them non-negative
true_coef[true_coef < 0] = 0
y = np.dot(X, true_coef)
# Add some noise
y += 5 * np.random.normal(size=(n_samples, ))
```

Split the data in train set and test set

```python
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.5)
```

Fit the Non-Negative least squares.

```python
from sklearn.linear_model import LinearRegression
reg_nnls = LinearRegression(positive=True)
y_pred_nnls = reg_nnls.fit(X_train, y_train).predict(X_test)
r2_score_nnls = r2_score(y_test, y_pred_nnls)
print("NNLS R2 score", r2_score_nnls)
```
Out:

NNLS R2 score 0.8225220806196525

Fit an OLS.

```python
def reg_ols
    reg_ols = LinearRegression()
    y_pred_ols = reg_ols.fit(X_train, y_train).predict(X_test)
    r2_score_ols = r2_score(y_test, y_pred_ols)
    print("OLS R2 score", r2_score_ols)
```

Out:

OLS R2 score 0.7436926291700351

Comparing the regression coefficients between OLS and NNLS, we can observe they are highly correlated (the dashed line is the identity relation), but the non-negative constraint shrinks some to 0. The Non-Negative Least squares inherently yield sparse results.

```python
fig, ax = plt.subplots()
ax.plot(reg_ols.coef_, reg_nnls.coef_, linewidth=0, marker=".", alpha=.5)
low_x, high_x = ax.get_xlim()
low_y, high_y = ax.get_ylim()
low = max(low_x, low_y)
high = min(high_x, high_y)
ax.plot([low, high], [low, high], ls="--", c=".3", alpha=.5)
ax.set_xlabel("OLS regression coefficients", fontweight="bold")
ax.set_ylabel("NNLS regression coefficients", fontweight="bold")
```
6.16.14 Linear Regression Example

The example below uses only the first feature of the diabetes dataset, in order to illustrate the data points within the two-dimensional plot. The straight line can be seen in the plot, showing how linear regression attempts to draw a straight line that will best minimize the residual sum of squares between the observed responses in the dataset, and the responses predicted by the linear approximation.

The coefficients, residual sum of squares and the coefficient of determination are also calculated.
Out:

Coefficients:
[938.23786125]
Mean squared error: 2548.07
Coefficient of determination: 0.47

print(__doc__)

# Code source: Jaques Grobler
# License: BSD 3 clause

import matplotlib.pyplot as plt
import numpy as np
from sklearn import datasets, linear_model
from sklearn.metrics import mean_squared_error, r2_score

# Load the diabetes dataset
```python
diabetes_X, diabetes_y = datasets.load_diabetes(return_X_y=True)

# Use only one feature
diabetes_X = diabetes_X[:, np.newaxis, 2]

# Split the data into training/testing sets
diabetes_X_train = diabetes_X[:-20]
diabetes_X_test = diabetes_X[-20:]

# Split the targets into training/testing sets
diabetes_y_train = diabetes_y[:-20]
diabetes_y_test = diabetes_y[-20:]

# Create linear regression object
regr = linear_model.LinearRegression()

# Train the model using the training sets
regr.fit(diabetes_X_train, diabetes_y_train)

# Make predictions using the testing set
diabetes_y_pred = regr.predict(diabetes_X_test)

# The coefficients
print('Coefficients:
', regr.coef_)

# The mean squared error
print('Mean squared error: %.2f
  ' % mean_squared_error(diabetes_y_test, diabetes_y_pred))

# The coefficient of determination: 1 is perfect prediction
print('Coefficient of determination: %.2f
  ' % r2_score(diabetes_y_test, diabetes_y_pred))

# Plot outputs
plt.scatter(diabetes_X_test, diabetes_y_test, color='black')
plt.plot(diabetes_X_test, diabetes_y_pred, color='blue', linewidth=3)
plt.xticks(()
plt.yticks(()
plt.show()

Total running time of the script: ( 0 minutes 0.049 seconds)

6.16.15 Robust linear model estimation using RANSAC

In this example we see how to robustly fit a linear model to faulty data using the RANSAC algorithm.

6.16. Generalized Linear Models
Estimated coefficients (true, linear regression, RANSAC):
82.1903908407869 [54.17236387] [82.08533159]

import numpy as np
from matplotlib import pyplot as plt
from sklearn import linear_model, datasets

n_samples = 1000
n_outliers = 50

X, y, coef = datasets.make_regression(n_samples=n_samples, n_features=1,
                                  n_informative=1, noise=10,
                                  coef=True, random_state=0)

# Add outlier data
np.random.seed(0)
X[:n_outliers] = 3 + 0.5 * np.random.normal(size=(n_outliers, 1))
y[:n_outliers] = -3 + 10 * np.random.normal(size=n_outliers)

# Fit line using all data
lr = linear_model.LinearRegression()
lr.fit(X, y)

# Robustly fit linear model with RANSAC algorithm
ransac = linear_model.RANSACRegressor()
ransac.fit(X, y)
inlier_mask = ransac.inlier_mask_
outlier_mask = np.logical_not(inlier_mask)

# Predict data of estimated models
line_X = np.arange(X.min(), X.max())[:, np.newaxis]
line_y = lr.predict(line_X)
line_y_ransac = ransac.predict(line_X)

# Compare estimated coefficients
print("Estimated coefficients (true, linear regression, RANSAC):"汇集)
print(coef, lr.coef_, ransac.estimator_.coef_)

lw = 2
plt.scatter(X[inlier_mask], y[inlier_mask], color='yellowgreen', marker='.',
        label='Inliers')
plt.scatter(X[outlier_mask], y[outlier_mask], color='gold', marker='.',
        label='Outliers')
plt.plot(line_X, line_y, color='navy', linewidth=lw, label='Linear regressor')
plt.plot(line_X, line_y_ransac, color='cornflowerblue', linewidth=lw,
        label='RANSAC regressor')
plt.legend(loc='lower right')
plt.xlabel("Input")
plt.ylabel("Response")
plt.show()

Total running time of the script: ( 0 minutes 0.128 seconds)

6.16.16 Sparsity Example: Fitting only features 1 and 2

Features 1 and 2 of the diabetes-dataset are fitted and plotted below. It illustrates that although feature 2 has a strong coefficient on the full model, it does not give us much regarding $y$ when compared to just feature 1

6.16. Generalized Linear Models
import matplotlib.pyplot as plt
import numpy as np
from mpl_toolkits.mplot3d import Axes3D
from sklearn import datasets, linear_model

X, y = datasets.load_diabetes(return_X_y=True)
indices = (0, 1)
X_train = X[:-20, indices]
X_test = X[-20:, indices]
y_train = y[:-20]
y_test = y[-20:]

ols = linear_model.LinearRegression()
ols.fit(X_train, y_train)

# Plot the figure

# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

X_1
X_2
Y

plot_figs(fig_num, elev, azim, X_train, clf):
    fig = plt.figure(fig_num, figsize=(4, 3))
    plt.clf()
    ax = Axes3D(fig, elev=elev, azim=azim)

    ax.scatter(X_train[:, 0], X_train[:, 1], y_train, c='k', marker='+')
    ax.plot_surface(np.array([[-.1, -.1], [.15, .15]]),
                    np.array([[-.1, .15], [-.1, .15]]),
                    clf.predict(np.array([[-.1, -.1, .15, .15],
                                            [-.1, .15, -.1, .15]]).T

(continues on next page)
6.16.17 HuberRegressor vs Ridge on dataset with strong outliers

Fit Ridge and HuberRegressor on a dataset with outliers.

The example shows that the predictions in ridge are strongly influenced by the outliers present in the dataset. The Huber regressor is less influenced by the outliers since the model uses the linear loss for these. As the parameter epsilon is increased for the Huber regressor, the decision function approaches that of the ridge.
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_regression
from sklearn.linear_model import HuberRegressor, Ridge

# Generate toy data.
rng = np.random.RandomState(0)
X, y = make_regression(n_samples=20, n_features=1, random_state=0, noise=4.0, bias=100.0)

# Add four strong outliers to the dataset.
X_outliers = rng.normal(0, 0.5, size=(4, 1))
y_outliers = rng.normal(0, 2.0, size=4)
X_outliers[:, :] += X.max() + X.mean() / 4.
X_outliers[:, :] += X.min() - X.mean() / 4.
y_outliers[2:] += y.min() - y.mean() / 4.
y_outliers[2:] += y.max() + y.mean() / 4.
X = np.vstack((X, X_outliers))
y = np.concatenate((y, y_outliers))

Comparison of HuberRegressor vs Ridge
```python
plt.plot(X, y, 'b."

# Fit the huber regressor over a series of epsilon values.
colors = ['r-', 'b-', 'y-', 'm-']

x = np.linspace(X.min(), X.max(), 7)
epsilon_values = [1.35, 1.5, 1.75, 1.9]
for k, epsilon in enumerate(epsilon_values):
    huber = HuberRegressor(alpha=0.0, epsilon=epsilon)
    huber.fit(X, y)
    coef_ = huber.coef_ * x + huber.intercept_
    plt.plot(x, coef_, colors[k], label="huber loss, $\epsilon$ = %s" % epsilon)

# Fit a ridge regressor to compare it to huber regressor.
ridge = Ridge(alpha=0.0, random_state=0, normalize=True)
ridge.fit(X, y)
coef_ridge = ridge.coef_
coef_ = ridge.coef_ * x + ridge.intercept_
plt.plot(x, coef_, 'g-', label="ridge regression")
plt.title("Comparison of HuberRegressor vs Ridge")
plt.xlabel("X")
plt.ylabel("y")
plt.legend(loc=0)
plt.show()
```

**Total running time of the script:** ( 0 minutes 0.133 seconds)

### 6.16.18 Lasso on dense and sparse data

We show that linear_model.Lasso provides the same results for dense and sparse data and that in the case of sparse data the speed is improved.

Out:

```{}--- Dense matrices
Sparse Lasso done in 0.120034s
Dense Lasso done in 0.049450s
Distance between coefficients : 1.0705405751792344e-13
--- Sparse matrices
Matrix density : 0.6263000000000001 %
Sparse Lasso done in 0.161027s
Dense Lasso done in 0.994537s
Distance between coefficients : 7.928463765972842e-12
```

```python
print(__doc__)

from time import time
from scipy import sparse
from scipy import linalg
```

(continues on next page)
from sklearn.datasets import make_regression
from sklearn.linear_model import Lasso

# The two Lasso implementations on Dense data
print("--- Dense matrices")
X, y = make_regression(n_samples=200, n_features=5000, random_state=0)
X_sp = sparse.coo_matrix(X)

alpha = 1
sparse_lasso = Lasso(alpha=alpha, fit_intercept=False, max_iter=1000)
dense_lasso = Lasso(alpha=alpha, fit_intercept=False, max_iter=1000)

T0 = time()
sparse_lasso.fit(X_sp, y)
print("Sparse Lasso done in %fs % (time() - T0))

T0 = time()
dense_lasso.fit(X, y)
print("Dense Lasso done in %fs % (time() - T0))

print("Distance between coefficients : %s" % linalg.norm(sparse_lasso.coef_ - dense_lasso.coef_))

# The two Lasso implementations on Sparse data
print("--- Sparse matrices")
Xs = X.copy()
Xs[Xs < 2.5] = 0.0
Xs = sparse.coo_matrix(Xs)
Xs = Xs.tocsc()

print("Matrix density : %s %" % (Xs.nnz / float(X.size) * 100))

alpha = 0.1
sparse_lasso = Lasso(alpha=alpha, fit_intercept=False, max_iter=10000)
dense_lasso = Lasso(alpha=alpha, fit_intercept=False, max_iter=10000)

T0 = time()
sparse_lasso.fit(Xs, y)
print("Sparse Lasso done in %fs % (time() - T0))

T0 = time()
dense_lasso.fit(Xs.toarray(), y)
print("Dense Lasso done in %fs % (time() - T0))

print("Distance between coefficients : %s" % linalg.norm(sparse_lasso.coef_ - dense_lasso.coef_))

Total running time of the script: ( 0 minutes 1.428 seconds)
6.16.19 Comparing various online solvers

An example showing how different online solvers perform on the hand-written digits dataset.

Out:

```
training SGD
training ASGD
training Perceptron
training Passive-Aggressive I
training Passive-Aggressive II
training SAG
```

```python
# Author: Rob Zinkov <rob at zinkov dot com>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
```

(continues on next page)
from sklearn.model_selection import train_test_split
from sklearn.linear_model import SGDClassifier, Perceptron
from sklearn.linear_model import PassiveAggressiveClassifier
from sklearn.linear_model import LogisticRegression

heldout = [0.95, 0.90, 0.75, 0.50, 0.01]
rounds = 20
X, y = datasets.load_digits(return_X_y=True)

classifiers = [
    ("SGD", SGDClassifier(max_iter=100)),
    ("ASGD", SGDClassifier(average=True)),
    ("Perceptron", Perceptron()),
    ("Passive-Aggressive I", PassiveAggressiveClassifier(loss='hinge', C=1.0, tol=1e-4)),
    ("Passive-Aggressive II", PassiveAggressiveClassifier(loss='squared_hinge', C=1.0, tol=1e-4)),
    ("SAG", LogisticRegression(solver='sag', tol=1e-1, C=1e4 / X.shape[0]))
]

xx = 1. - np.array(heldout)

for name, clf in classifiers:
    print("training %s" % name)
    rng = np.random.RandomState(42)
    yy = []
    for i in heldout:
        yy_ = []
        for r in range(rounds):
            X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=i, random_state=rng)
            clf.fit(X_train, y_train)
            y_pred = clf.predict(X_test)
            yy_.append(1 - np.mean(y_pred == y_test))
        yy.append(np.mean(yy_))
        plt.plot(xx, yy, label=name)

plt.legend(loc="upper right")
plt.xlabel("Proportion train")
plt.ylabel("Test Error Rate")
plt.show()

Total running time of the script: ( 0 minutes 19.085 seconds)
Joint feature selection with multi-task Lasso

The multi-task lasso allows to fit multiple regression problems jointly enforcing the selected features to be the same across tasks. This example simulates sequential measurements, each task is a time instant, and the relevant features vary in amplitude over time while being the same. The multi-task lasso imposes that features that are selected at one time point are select for all time point. This makes feature selection by the Lasso more stable.
# Generate some 2D coefficients with sine waves with random frequency and phase
n_samples, n_features, n_tasks = 100, 30, 40
n_relevant_features = 5
times = np.linspace(0, 2 * np.pi, n_tasks)
for k in range(n_relevant_features):
    coef[:, k] = np.sin((1. + rng.randn(1)) * times + 3 * rng.randn(1))

X = rng.randn(n_samples, n_features)
Y = np.dot(X, coef.T) + rng.randn(n_samples, n_tasks)

coef_lasso_ = np.array([Lasso(alpha=0.5).fit(X, y).coef_ for y in Y.T])
coef_multi_task_lasso_ = MultiTaskLasso(alpha=1.).fit(X, Y).coef_
# Plot support and time series

```python
fig = plt.figure(figsize=(8, 5))
plt.subplot(1, 2, 1)
plt.spy(coef_lasso_)
plt.xlabel('Feature')
plt.ylabel('Time (or Task)')
plt.text(10, 5, 'Lasso')
plt.subplot(1, 2, 2)
plt.spy(coef_multi_task_lasso_)
plt.xlabel('Feature')
plt.ylabel('Time (or Task)')
plt.text(10, 5, 'MultiTaskLasso')
fig.suptitle('Coefficient non-zero location')

feature_to_plot = 0
plt.figure()
lw = 2
plt.plot(coef[:, feature_to_plot], color='seagreen', linewidth=lw,
         label='Ground truth')
plt.plot(coef_lasso_[:, feature_to_plot], color='cornflowerblue', linewidth=lw,
         label='Lasso')
plt.plot(coef_multi_task_lasso_[:, feature_to_plot], color='gold', linewidth=lw,
         label='MultiTaskLasso')
plt.legend(loc='upper center')
plt.axis('tight')
plt.ylim([-1.1, 1.1])
plt.show()
```

Total running time of the script: (0 minutes 0.272 seconds)

## 6.16.21 MNIST classification using multinomial logistic + L1

Here we fit a multinomial logistic regression with L1 penalty on a subset of the MNIST digits classification task. We use the SAGA algorithm for this purpose: this a solver that is fast when the number of samples is significantly larger than the number of features and is able to finely optimize non-smooth objective functions which is the case with the l1-penalty. Test accuracy reaches > 0.8, while weight vectors remains sparse and therefore more easily interpretable.

Note that this accuracy of this l1-penalized linear model is significantly below what can be reached by an l2-penalized linear model or a non-linear multi-layer perceptron model on this dataset.
Classification vector for...

Out:

```
Sparsity with L1 penalty: 79.95%
Test score with L1 penalty: 0.8322
Example run in 57.867 s
```

```python
import time
import matplotlib.pyplot as plt
import numpy as np

from sklearn.datasets import fetch_openml
from sklearn.linear_model import LogisticRegression
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
from sklearn.utils import check_random_state

print(__doc__)

# Author: Arthur Mensch <arthur.mensch@m4x.org>
# License: BSD 3 clause

# Turn down for faster convergence
t0 = time.time()
train_samples = 5000

# Load data from https://www.openml.org/d/554
X, y = fetch_openml('mnist_784', version=1, return_X_y=True, as_frame=False)
random_state = check_random_state(0)
permutation = random_state.permutation(X.shape[0])
X = X[permutation]
```

(continues on next page)
y = y[permutation]
X = X.reshape((X.shape[0], -1))

X_train, X_test, y_train, y_test = train_test_split(
    X, y, train_size=train_samples, test_size=10000)

scaler = StandardScaler()
X_train = scaler.fit_transform(X_train)
X_test = scaler.transform(X_test)

# Turn up tolerance for faster convergence
clf = LogisticRegression(
    C=50. / train_samples, penalty='l1', solver='saga', tol=0.1)
clf.fit(X_train, y_train)
sparse = np.mean(clf.coef_ == 0) * 100
score = clf.score(X_test, y_test)
    # print("Best C % .4f" % clf.C_)
print("Sparsity with L1 penalty: %.2f%%" % sparse)
print("Test score with L1 penalty: %.4f" % score)

coef = clf.coef_.copy()
plt.figure(figsize=(10, 5))
scale = np.abs(coef).max()
for i in range(10):
    l1_plot = plt.subplot(2, 5, i + 1)
    l1_plot.imshow(coef[i].reshape(28, 28), interpolation='nearest',
                   cmap=plt.cm.RdBu, vmin=-scale, vmax=scale)
    l1_plot.set_xticks(())
    l1_plot.set_yticks(())
    l1_plot.set_xlabel('Class %i' % i)
plt.suptitle('Classification vector for...')

run_time = time.time() - t0
print('Example run in %.3f s' % run_time)
plt.show()

Total running time of the script: ( 0 minutes 57.955 seconds)

6.16.22 Plot multi-class SGD on the iris dataset

Plot decision surface of multi-class SGD on iris dataset. The hyperplanes corresponding to the three one-versus-all (OVA) classifiers are represented by the dashed lines.
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.linear_model import SGDClassifier

# import some data to play with
iris = datasets.load_iris()

# we only take the first two features. We could
# avoid this ugly slicing by using a two-dim dataset
X = iris.data[:, :2]
y = iris.target
colors = "bry"

# shuffle
idx = np.arange(X.shape[0])
np.random.seed(13)
np.random.shuffle(idx)
X = X[idx]
y = y[idx]

# standardize
mean = X.mean(axis=0)
std = X.std(axis=0)
X = (X - mean) / std

h = .02  # step size in the mesh

clf = SGDClassifier(alpha=0.001, max_iter=100).fit(X, y)

# create a mesh to plot in
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))

# Plot the decision boundary. For that, we will assign a color to each
# point in the mesh [x_min, x_max]x[y_min, y_max].
Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
cs = plt.contourf(xx, yy, Z, cmap=plt.cm.Paired)
plt.axis('tight')

# Plot also the training points
for i, color in zip(clf.classes_, colors):
    idx = np.where(y == i)
    plt.scatter(X[idx, 0], X[idx, 1], c=color, label=iris.target_names[i],
                cmap=plt.cm.Paired, edgecolor='black', s=20)
plt.title("Decision surface of multi-class SGD")
plt.axis('tight')

# Plot the three one-against-all classifiers
xmin, xmax = plt.xlim()
ymin, ymax = plt.ylim()
coef = clf.coef_
intercept = clf.intercept_

def plot_hyperplane(c, color):
    def line(x0):
        return -(x0 * coef[c, 0]) - intercept[c] / coef[c, 1]
    plt.plot([xmin, xmax], [line(xmin), line(xmax)],
              ls="--", color=color)

for i, color in zip(clf.classes_, colors):
    plot_hyperplane(i, color)
plt.legend()
plt.show()

Total running time of the script: ( 0 minutes 0.157 seconds)
6.16.23 Orthogonal Matching Pursuit

Using orthogonal matching pursuit for recovering a sparse signal from a noisy measurement encoded with a dictionary.

```
from sklearn.datasets import make_sparse_coded_signal
n_components, n_features = 512, 100
n_nonzero_coefs = 17
```
# generate the data
# y = Xw
# |x|_0 = n_nonzero_coefs

```python
y, X, w = make_sparse_coded_signal(n_samples=1,
                                   n_components=n_components,
                                   n_features=n_features,
                                   n_nonzero_coefs=n_nonzero_coefs,
                                   random_state=0)
```

idx, = w.nonzero()

# distort the clean signal
y_noisy = y + 0.05 * np.random.randn(len(y))

# plot the sparse signal
plt.figure(figsize=(7, 7))
plt.subplot(4, 1, 1)
plt.xlim(0, 512)
plt.title("Sparse signal")
plt.stem(idx, w[idx], use_line_collection=True)

# plot the noise-free reconstruction
omp = OrthogonalMatchingPursuit(n_nonzero_coefs=n_nonzero_coefs)
omp.fit(X, y)
coef = omp.coef_
idx_r, = coef.nonzero()
plt.subplot(4, 1, 2)
plt.xlim(0, 512)
plt.title("Recovered signal from noise-free measurements")
plt.stem(idx_r, coef[idx_r], use_line_collection=True)

# plot the noisy reconstruction
omp.fit(X, y_noisy)
coef = omp.coef_
idx_r, = coef.nonzero()
plt.subplot(4, 1, 3)
plt.xlim(0, 512)
plt.title("Recovered signal from noisy measurements")
plt.stem(idx_r, coef[idx_r], use_line_collection=True)

# plot the noisy reconstruction with number of non-zeros set by CV
omp_cv = OrthogonalMatchingPursuitCV()
omp_cv.fit(X, y_noisy)
coef = omp_cv.coef_
idx_r, = coef.nonzero()
plt.subplot(4, 1, 4)
plt.xlim(0, 512)
plt.title("Recovered signal from noisy measurements with CV")
plt.stem(idx_r, coef[idx_r], use_line_collection=True)

plt.subplots_adjust(0.06, 0.04, 0.94, 0.90, 0.20, 0.38)
plt.suptitle('Sparse signal recovery with Orthogonal Matching Pursuit', fontsize=16)
plt.show()
**Total running time of the script:** ( 0 minutes 0.231 seconds)

### 6.16.24 Lasso and Elastic Net for Sparse Signals

Estimates Lasso and Elastic-Net regression models on a manually generated sparse signal corrupted with an additive noise. Estimated coefficients are compared with the ground-truth.

Out:

```
Lasso (alpha=0.1)
r^2 on test data : 0.658064
ElasticNet (alpha=0.1, l1_ratio=0.7)
r^2 on test data : 0.642515
```

```
print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
```
from sklearn.metrics import r2_score

# #############################################################################
# Generate some sparse data to play with
np.random.seed(42)

n_samples, n_features = 50, 100
X = np.random.randn(n_samples, n_features)

# Decreasing coef w. alternated signs for visualization
idx = np.arange(n_features)
coef = (-1) ** idx * np.exp(-idx / 10)
coef[10:] = 0  # sparsify coef
y = np.dot(X, coef)

# Add noise
y += 0.01 * np.random.normal(size=n_samples)

# Split data in train set and test set
n_samples = X.shape[0]
X_train, y_train = X[:n_samples // 2], y[:n_samples // 2]
X_test, y_test = X[n_samples // 2:], y[n_samples // 2:]

# #############################################################################
# Lasso
from sklearn.linear_model import Lasso
alpha = 0.1
lasso = Lasso(alpha=alpha)
y_pred_lasso = lasso.fit(X_train, y_train).predict(X_test)
r2_score_lasso = r2_score(y_test, y_pred_lasso)
print(lasso)
print("r^2 on test data : %f" % r2_score_lasso)

# #############################################################################
# ElasticNet
from sklearn.linear_model import ElasticNet
enet = ElasticNet(alpha=alpha, l1_ratio=0.7)
y_pred_enet = enet.fit(X_train, y_train).predict(X_test)
r2_score_enet = r2_score(y_test, y_pred_enet)
print(enet)
print("r^2 on test data : %f" % r2_score_enet)

m, s, _ = plt.stem(np.where(enet.coef_)[0], enet.coef_[enet.coef_ != 0], markerfmt='x', label='Elastic net coefficients', use_line_collection=True)
plt.setp([m, s], color='#2ca02c')

m, s, _ = plt.stem(np.where(lasso.coef_)[0], lasso.coef_[lasso.coef_ != 0], markerfmt='x', label='Lasso coefficients', use_line_collection=True)
plt.setp([m, s], color='#ff7f0e')

plt.stem(np.where(coef)[0], coef[coef != 0], label='true coefficients', markerfmt='bx', use_line_collection=True)
Computes a Bayesian Ridge Regression of Sinusoids.

See Bayesian Ridge Regression for more information on the regressor.

In general, when fitting a curve with a polynomial by Bayesian ridge regression, the selection of initial values of the regularization parameters (alpha, lambda) may be important. This is because the regularization parameters are determined by an iterative procedure that depends on initial values.

In this example, the sinusoid is approximated by a polynomial using different pairs of initial values.

When starting from the default values (alpha_init = 1.90, lambda_init = 1.), the bias of the resulting curve is large, and the variance is small. So, lambda_init should be relatively small (1.e-3) so as to reduce the bias.

Also, by evaluating log marginal likelihood (L) of these models, we can determine which one is better. It can be concluded that the model with larger L is more likely.
def func(x):
    return np.sin(2*np.pi*x)

# Generate sinusoidal data with noise
size = 25
rng = np.random.RandomState(1234)
x_train = rng.uniform(0., 1., size)
y_train = func(x_train) + rng.normal(scale=0.1, size=size)
x_test = np.linspace(0., 1., 100)

# Fit by cubic polynomial
n_order = 3
X_train = np.vander(x_train, n_order + 1, increasing=True)
X_test = np.vander(x_test, n_order + 1, increasing=True)

# Plot the true and predicted curves with log marginal likelihood (L)
reg = BayesianRidge(tol=1e-6, fit_intercept=False, compute_score=True)
fig, axes = plt.subplots(1, 2, figsize=(8, 4))
for i, ax in enumerate(axes):
    # Bayesian ridge regression with different initial value pairs
    if i == 0:
        init = [1 / np.var(y_train), 1.]  # Default values
    elif i == 1:
        init = [1., 1e-3]
        reg.set_params(alpha_init=init[0], lambda_init=init[1])
    reg.fit(X_train, y_train)
    ymean, ystd = reg.predict(X_test, return_std=True)
    ax.plot(x_test, func(x_test), color="blue", label="sin($2\pi x$)"
    ax.scatter(x_train, y_train, s=50, alpha=0.5, label="observation"
    ax.plot(x_test, ymean, color="red", label="predict mean"
    ax.fill_between(x_test, ymean-ystd, ymean+ystd,
        color="pink", alpha=0.5, label="predict std"
    ax.set_ylim(-1.3, 1.3)
    ax.legend()
    title = "$\alpha_{init}=${:.2f}, $\lambda_{init}=${:.3f}".format(
        init[0], init[1])
    if i == 0:
        title += " (Default)"
    ax.set_title(title, fontsize=12)
    text = "$\alpha=${:.1f} $\lambda=${:.1f}".format(
        reg.alpha_, reg.lambda_)
    ax.text(0.05, -1.0, text, fontsize=12)
plt.tight_layout()
plt.show()

Total running time of the script: (0 minutes 0.375 seconds)
6.16.26 Theil-Sen Regression

Computes a Theil-Sen Regression on a synthetic dataset.

See Theil-Sen estimator: generalized-median-based estimator for more information on the regressor.

Compared to the OLS (ordinary least squares) estimator, the Theil-Sen estimator is robust against outliers. It has a breakdown point of about 29.3% in case of a simple linear regression which means that it can tolerate arbitrary corrupted data (outliers) of up to 29.3% in the two-dimensional case.

The estimation of the model is done by calculating the slopes and intercepts of a subpopulation of all possible combinations of \( p \) subsample points. If an intercept is fitted, \( p \) must be greater than or equal to \( n_{\text{features}} + 1 \). The final slope and intercept is then defined as the spatial median of these slopes and intercepts.

In certain cases Theil-Sen performs better than RANSAC which is also a robust method. This is illustrated in the second example below where outliers with respect to the x-axis perturb RANSAC. Tuning the residual_threshold parameter of RANSAC remedies this but in general a priori knowledge about the data and the nature of the outliers is needed. Due to the computational complexity of Theil-Sen it is recommended to use it only for small problems in terms of number of samples and features. For larger problems the max_subpopulation parameter restricts the magnitude of all possible combinations of \( p \) subsample points to a randomly chosen subset and therefore also limits the runtime. Therefore, Theil-Sen is applicable to larger problems with the drawback of losing some of its mathematical properties since it then works on a random subset.
import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import LinearRegression, TheilSenRegressor
from sklearn.linear_model import RANSACRegressor

print(__doc__)

estimators = [('OLS', LinearRegression()),
              ('Theil-Sen', TheilSenRegressor(random_state=42)),
              ('RANSAC', RANSACRegressor(random_state=42)),
             ]

colors = {'OLS': 'turquoise', 'Theil-Sen': 'gold', 'RANSAC': 'lightgreen'}
lw = 2

# Outliers only in the y direction

np.random.seed(0)
n_samples = 200
# Linear model y = 3*x + N(2, 0.1**2)
x = np.random.randn(n_samples)
w = 3.
c = 2.
o = 0.1 * np.random.randn(n_samples)
y = w * x + c + noise
# 10% outliers
y[-20:] += -20 * x[-20:]
X = x[:, np.newaxis]

plt.scatter(x, y, color='indigo', marker='x', s=40)
line_x = np.array([-3, 3])
for name, estimator in estimators:
t0 = time.time()
estimator.fit(X, y)
elapsed_time = time.time() - t0
y_pred = estimator.predict(line_x.reshape(2, 1))
plt.plot(line_x, y_pred, color=colors[name], linewidth=lw,
         label='%s (fit time: %.2fs)' % (name, elapsed_time))

plt.axis('tight')
plt.legend(loc='upper left')
plt.title("Corrupt y")

# Outliers in the X direction
np.random.seed(0)
# Linear model y = 3*x + N(2, 0.1**2)
x = np.random.randn(n_samples)
noise = 0.1 * np.random.randn(n_samples)
y = 3 * x + 2 + noise
# 10% outliers
x[-20:] = 9.9
y[-20:] += 22
X = x[:, np.newaxis]

plt.figure()
plt.scatter(x, y, color='indigo', marker='x', s=40)
line_x = np.array([-3, 10])
for name, estimator in estimators:
t0 = time.time()
estimator.fit(X, y)
elapsed_time = time.time() - t0
y_pred = estimator.predict(line_x.reshape(2, 1))
plt.plot(line_x, y_pred, color=colors[name], linewidth=lw,
         label='%s (fit time: %.2fs)' % (name, elapsed_time))

plt.axis('tight')
plt.legend(loc='upper left')
plt.title("Corrupt x")
plt.show()
6.16.27 Plot multinomial and One-vs-Rest Logistic Regression

Plot decision surface of multinomial and One-vs-Rest Logistic Regression. The hyperplanes corresponding to the three One-vs-Rest (OVR) classifiers are represented by the dashed lines.
Out:

training score : 0.995 (multinomial)
training score : 0.976 (ovr)
# print the training scores
print("training score : %.3f (" % clf.score(X, y), multi_class))

# create a mesh to plot in
h = .02  # step size in the mesh
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))

# Plot the decision boundary. For that, we will assign a color to each
# point in the mesh [x_min, x_max]x[y_min, y_max].
Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
plt.figure()
plt.contourf(xx, yy, Z, cmap=plt.cm.Paired)
plt.title("Decision surface of LogisticRegression (" % multi_class)
plt.axis('tight')

# Plot also the training points
colors = "bry"
for i, color in zip(clf.classes_, colors):
    idx = np.where(y == i)
    plt.scatter(X[idx, 0], X[idx, 1], c=color, cmap=plt.cm.Paired,
                edgecolor='black', s=20)

# Plot the three one-against-all classifiers
xmin, xmax = plt.xlim()
ymin, ymax = plt.ylim()
coef = clf.coef_
intercept = clf.intercept_

    def plot_hyperplane(c, color):
        def line(x0):
            return -(x0 * coef[c, 0]) - intercept[c] / coef[c, 1]
        plt.plot([xmin, xmax], [line(xmin), line(xmax)],
                  ls="--", color=color)

    for i, color in zip(clf.classes_, colors):
        plot_hyperplane(i, color)

plt.show()
6.16.28 Robust linear estimator fitting

Here a sine function is fit with a polynomial of order 3, for values close to zero.

Robust fitting is demoed in different situations:

- No measurement errors, only modelling errors (fitting a sine with a polynomial)
- Measurement errors in X
- Measurement errors in y

The median absolute deviation to non corrupt new data is used to judge the quality of the prediction.

What we can see that:

- RANSAC is good for strong outliers in the y direction
- TheilSen is good for small outliers, both in direction X and y, but has a break point above which it performs worse than OLS.
- The scores of HuberRegressor may not be compared directly to both TheilSen and RANSAC because it does not attempt to completely filter the outliers but lessen their effect.

![Modeling Errors Only](image_url)
```python
from matplotlib import pyplot as plt
import numpy as np

from sklearn.linear_model import (continues on next page)
```
```python
from sklearn.metrics import mean_squared_error
from sklearn.preprocessing import PolynomialFeatures
from sklearn.pipeline import make_pipeline

np.random.seed(42)
X = np.random.normal(size=400)
y = np.sin(X)
# Make sure that it X is 2D
X = X[:, np.newaxis]

X_test = np.random.normal(size=200)
y_test = np.sin(X_test)
X_test = X_test[:, np.newaxis]

y_errors = y.copy()
y_errors[::3] = 3

X_errors = X.copy()
X_errors[::3] = 3

y_errors_large = y.copy()
y_errors_large[::3] = 10

X_errors_large = X.copy()
X_errors_large[::3] = 10

estimators = [('OLS', LinearRegression()),
              ('Theil-Sen', TheilSenRegressor(random_state=42)),
              ('RANSAC', RANSACRegressor(random_state=42)),
              ('HuberRegressor', HuberRegressor())]

colors = {'OLS': 'turquoise', 'Theil-Sen': 'gold', 'RANSAC': 'lightgreen',
          'HuberRegressor': 'black'}

linestyle = {'OLS': '-', 'Theil-Sen': '-.', 'RANSAC': '--', 'HuberRegressor': '--'}

lw = 3

x_plot = np.linspace(X.min(), X.max())

for name, estimator in estimators:
    model = make_pipeline(PolynomialFeatures(3), estimator)
    model.fit(X, y)
    mse = mean_squared_error(model.predict(X), y)
    y_plot = model.predict(x_plot[:, np.newaxis])
    plt.plot(x_plot, y_plot, color=colors[name], linestyle=linestyle[name],
             linewidth=lw, label='{}: error = {:.3f}'.format(name, mse))

legend_title = 'Error of Mean Absolute Deviation to Non-corrupt Data'
legend = plt.legend(loc='upper right', frameon=False, title=legend_title,
                     handles=[plt.Line2D([0], [0], color=colors[name],
                                          label=legend_title) for name in colors.keys()]
```
6.16.29 L1 Penalty and Sparsity in Logistic Regression

Comparison of the sparsity (percentage of zero coefficients) of solutions when L1, L2 and Elastic-Net penalty are used for different values of C. We can see that large values of C give more freedom to the model. Conversely, smaller values of C constrain the model more. In the L1 penalty case, this leads to sparser solutions. As expected, the Elastic-Net penalty sparsity is between that of L1 and L2.

We classify 8x8 images of digits into two classes: 0-4 against 5-9. The visualization shows coefficients of the models for varying C.

Out:

<table>
<thead>
<tr>
<th>C</th>
<th>L1 penalty</th>
<th>Elastic-Net</th>
<th>L2 penalty</th>
</tr>
</thead>
<tbody>
<tr>
<td>C=1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>C=0.1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>C=0.01</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

C=1.00  
Sparsity with L1 penalty: 6.25%  
Sparsity with Elastic-Net penalty: 4.69%
Sparsity with L2 penalty: 4.69%
Score with L1 penalty: 0.90
Score with Elastic-Net penalty: 0.90
Score with L2 penalty: 0.90
C=0.10
Sparsity with L1 penalty: 29.69%
Sparsity with Elastic-Net penalty: 12.50%
Sparsity with L2 penalty: 4.69%
Score with L1 penalty: 0.90
Score with Elastic-Net penalty: 0.90
Score with L2 penalty: 0.90
C=0.01
Sparsity with L1 penalty: 84.38%
Sparsity with Elastic-Net penalty: 68.75%
Sparsity with L2 penalty: 4.69%
Score with L1 penalty: 0.86
Score with Elastic-Net penalty: 0.88
Score with L2 penalty: 0.89

```python
print(__doc__)

# Authors: Alexandre Gramfort <alexandre.gramfort@inria.fr>
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# Andreas Mueller <amueller@ais.uni-bonn.de>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn.linear_model import LogisticRegression
from sklearn import datasets
from sklearn.preprocessing import StandardScaler

X, y = datasets.load_digits(return_X_y=True)
X = StandardScaler().fit_transform(X)

# classify small against large digits
y = (y > 4).astype(int)

ll_ratio = 0.5  # L1 weight in the Elastic-Net regularization

fig, axes = plt.subplots(3, 3)

# Set regularization parameter
for i, (C, axes_row) in enumerate(zip((1, 0.1, 0.01), axes):
    # turn down tolerance for short training time
    clf_l1_LR = LogisticRegression(C=C, penalty='l1', tol=0.01, solver='saga')
    clf_l2_LR = LogisticRegression(C=C, penalty='l2', tol=0.01, solver='saga')
    clf_en_LR = LogisticRegression(C=C, penalty='elasticnet', solver='saga',
        l1_ratio=ll_ratio, tol=0.01)

    (continues on next page)
clf_l1_LR.fit(X, y)
clf_l2_LR.fit(X, y)
clf_en_LR.fit(X, y)

coeff_l1_LR = clf_l1_LR.coef_.ravel()
coeff_l2_LR = clf_l2_LR.coef_.ravel()
coeff_en_LR = clf_en_LR.coef_.ravel()

# coef_l1_LR contains zeros due to the L1 sparsity inducing norm
sparsity_l1_LR = np.mean(coef_l1_LR == 0) * 100
sparsity_l2_LR = np.mean(coef_l2_LR == 0) * 100
sparsity_en_LR = np.mean(coef_en_LR == 0) * 100

print("C=%.2f" % C)
print("{:<40} {:.2f} %".format("Sparsity with L1 penalty:", sparsity_l1_LR))
print("{:<40} {:.2f} %".format("Sparsity with Elastic-Net penalty:",
                        sparsity_en_LR))
print("{:<40} {:.2f} %".format("Sparsity with L2 penalty:", sparsity_l2_LR))
print("{:<40} {:.2f} %".format("Score with L1 penalty:",
                        clf_l1_LR.score(X, y)))
print("{:<40} {:.2f} %".format("Score with Elastic-Net penalty:",
                        clf_en_LR.score(X, y)))
print("{:<40} {:.2f} %".format("Score with L2 penalty:",
                        clf_l2_LR.score(X, y)))

if i == 0:
    axes_row[0].set_title("L1 penalty")
    axes_row[1].set_title("Elastic-Net\n    l1_ratio = $s$ % l1_ratio")
    axes_row[2].set_title("L2 penalty")

for ax, coefs in zip(axes_row, [coef_l1_LR, coef_en_LR, coef_l2_LR]):
    ax.imshow(np.abs(coefs.reshape(8, 8)), interpolation='nearest',
              cmap='binary', vmax=1, vmin=0)
    ax.set_xticks(())
    ax.set_yticks(())

    axes_row[0].set_ylabel('C = $s$ % C')

plt.show()
6.16.30 Lasso and Elastic Net

Lasso and elastic net (L1 and L2 penalisation) implemented using a coordinate descent. The coefficients can be forced to be positive.
Elastic-Net and positive Elastic-Net

Out:
Computing regularization path using the lasso...
Computing regularization path using the positive lasso...
Computing regularization path using the elastic net...
Computing regularization path using the positive elastic net...

print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

from itertools import cycle
import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import lasso_path, enet_path
from sklearn import datasets

X, y = datasets.load_diabetes(return_X_y=True)
X /= X.std(axis=0)  # Standardize data (easier to set the l1_ratio parameter)

# Compute paths

eps = 5e-3  # the smaller it is the longer is the path

print("Computing regularization path using the lasso...")
alphas_lasso, coefs_lasso, _ = lasso_path(X, y, eps=eps, fit_intercept=False)

print("Computing regularization path using the positive lasso...")
alphas_positive_lasso, coefs_positive_lasso, _ = lasso_path(X, y, eps=eps, positive=True, fit_intercept=False)

print("Computing regularization path using the elastic net...")
alphas_enet, coefs_enet, _ = enet_path(X, y, eps=eps, l1_ratio=0.8, fit_intercept=False)

print("Computing regularization path using the positive elastic net...")
alphas_positive_enet, coefs_positive_enet, _ = enet_path(X, y, eps=eps, l1_ratio=0.8, positive=True, fit_intercept=False)

# Display results

plt.figure(1)
colors = cycle(['b', 'r', 'g', 'c', 'k'])
neg_log_alphas_lasso = -np.log10(alphas_lasso)
neg_log_alphas_enet = -np.log10(alphas_enet)

for coef_l, coef_e, c in zip(coefs_lasso, coefs_enet, colors):
    l1 = plt.plot(neg_log_alphas_lasso, coef_l, c=c)
    l2 = plt.plot(neg_log_alphas_enet, coef_e, linestyle='--', c=c)

plt.xlabel('-Log(alpha)')
plt.ylabel('coefficients')
plt.title('Lasso and Elastic-Net Paths')
plt.legend((l1[-1], l2[-1]), ('Lasso', 'Elastic-Net'), loc='lower left')
plt.axis('tight')

plt.figure(2)
neg_log_alphas_positive_lasso = -np.log10(alphas_positive_lasso)

for coef_l, coef_pl, c in zip(coefs_lasso, coefs_positive_lasso, colors):
    l1 = plt.plot(neg_log_alphas_lasso, coef_l, c=c)
    l2 = plt.plot(neg_log_alphas_positive_lasso, coef_pl, linestyle='--', c=c)

plt.xlabel('-Log(alpha)')
plt.ylabel('coefficients')
plt.title('Lasso and positive Lasso')
plt.legend((l1[-1], l2[-1]), ('Lasso', 'Positive Lasso'), loc='lower left')
plt.axis('tight')

plt.figure(3)
neg_log_alphas_positive_enet = -np.log10(alphas_positive_enet)

for coef_e, coef_pe, c in zip(coefs_enet, coefs_positive_enet, colors):
    l1 = plt.plot(neg_log_alphas_enet, coef_e, c=c)
    l2 = plt.plot(neg_log_alphas_positive_enet, coef_pe, linestyle='--', c=c)

(continues on next page)
Fit regression model with Bayesian Ridge Regression.

See :cite:`Bishop2006` for more information on the regressor.

Compared to the OLS (ordinary least squares) estimator, the coefficient weights are slightly shifted toward zeros, which stabilises them.

The histogram of the estimated weights is very peaked, as a sparsity-inducing prior is implied on the weights.

The estimation of the model is done by iteratively maximizing the marginal log-likelihood of the observations.

We also plot predictions and uncertainties for ARD for one dimensional regression using polynomial feature expansion. Note the uncertainty starts going up on the right side of the plot. This is because these test samples are outside of the range of the training samples.
Histogram of the weights

Features

Values of the weights

Relevant features
import numpy as np
import matplotlib.pyplot as plt
from scipy import stats
from sklearn.linear_model import ARDRegression, LinearRegression

# Parameters of the example
np.random.seed(0)
n_samples, n_features = 100, 100
# Create Gaussian data
X = np.random.randn(n_samples, n_features)
# Create weights with a precision lambda_ of 4.
lambda_ = 4.
w = np.zeros(n_features)
# Only keep 10 weights of interest
relevant_features = np.random.randint(0, n_features, 10)
for i in relevant_features:
    w[i] = stats.norm.rvs(loc=0, scale=1. / np.sqrt(lambda_))
# Create noise with a precision alpha of 50.
alpha_ = 50.
noise = stats.norm.rvs(loc=0, scale=1. / np.sqrt(alpha_), size=n_samples)
# Create the target
y = np.dot(X, w) + noise

# Fit the ARD Regression
clf = ARDRegression(compute_score=True).
clf.fit(X, y)

ols = LinearRegression()
ols.fit(X, y)

# Plot the true weights, the estimated weights, the histogram of the weights, and predictions with standard deviations
plt.figure(figsize=(6, 5))
plt.title("Weights of the model")
plt.plot(clf.coef_, color='darkblue', linestyle='-', linewidth=2,
         label="ARD estimate")
plt.plot(ols.coef_, color='yellowgreen', linestyle=':', linewidth=2,
         label="OLS estimate")
plt.plot(w, color='orange', linestyle='-', linewidth=2, label="Ground truth")
plt.xlabel("Features")
plt.ylabel("Values of the weights")
plt.legend(loc=1)

plt.figure(figsize=(6, 5))
plt.title("Histogram of the weights")
plt.hist(clf.coef_, bins=n_features, color='navy', log=True)
plt.scatter(clf.coef_[relevant_features], np.full(len(relevant_features), 5.),
            color='gold', marker='o', label="Relevant features")
plt.ylabel("Features")
plt.xlabel("Values of the weights")
plt.legend(loc=1)

plt.figure(figsize=(6, 5))
plt.title("Marginal log-likelihood")
plt.plot(clf.scores_, color='navy', linewidth=2)
plt.ylabel("Score")
plt.xlabel("Iterations")

# Plotting some predictions for polynomial regression


# Plotting some predictions for polynomial regression
```python
y_plot = f(X_plot, noise_amount=0)
y_mean, y_std = clf_poly.predict(np.vander(X_plot, degree), return_std=True)
plt.figure(figsize=(6, 5))
plt.errorbar(X_plot, y_mean, y_std, color='navy',
             label="Polynomial ARD", linewidth=2)
plt.plot(X_plot, y_plot, color='gold', linewidth=2,
         label="Ground Truth")
plt.ylabel("Output y")
plt.xlabel("Feature X")
plt.legend(loc="lower left")
plt.show()
```

**Total running time of the script:** (0 minutes 0.505 seconds)

### 6.16.32 Bayesian Ridge Regression

Computes a Bayesian Ridge Regression on a synthetic dataset.

See [Bayesian Ridge Regression](#) for more information on the regressor.

Compared to the OLS (ordinary least squares) estimator, the coefficient weights are slightly shifted toward zeros, which stabilises them.

As the prior on the weights is a Gaussian prior, the histogram of the estimated weights is Gaussian.

The estimation of the model is done by iteratively maximizing the marginal log-likelihood of the observations.

We also plot predictions and uncertainties for Bayesian Ridge Regression for one dimensional regression using polynomial feature expansion. Note the uncertainty starts going up on the right side of the plot. This is because these test samples are outside of the range of the training samples.
import numpy as np
import matplotlib.pyplot as plt
from scipy import stats
from sklearn.linear_model import BayesianRidge, LinearRegression

# Generating simulated data with Gaussian weights
np.random.seed(0)
n_samples, n_features = 100, 100
X = np.random.randn(n_samples, n_features)  # Create Gaussian data
lambda_ = 4.
w = np.zeros(n_features)
relevant_features = np.random.randint(0, n_features, 10)
for i in relevant_features:
    w[i] = stats.norm.rvs(loc=0, scale=1. / np.sqrt(lambda_))  # Create weights with a precision lambda_ of 4.
alpha_ = 50.
noise = stats.norm.rvs(loc=0, scale=1. / np.sqrt(alpha_), size=n_samples)  # Create the target (continues on next page)
y = np.dot(X, w) + noise

# Fit the Bayesian Ridge Regression and an OLS for comparison
clf = BayesianRidge(compute_score=True)
clf.fit(X, y)

ols = LinearRegression()
ols.fit(X, y)

# Plot true weights, estimated weights, histogram of the weights, and
# predictions with standard deviations
lw = 2
plt.figure(figsize=(6, 5))
plt.title("Weights of the model")
plt.plot(clf.coef_, color='lightgreen', linewidth=lw,
         label="Bayesian Ridge estimate")
plt.plot(w, color='gold', linewidth=lw, label="Ground truth")
plt.plot(ols.coef_, color='navy', linestyle='--', label="OLS estimate")
plt.xlabel("Features")
plt.ylabel("Values of the weights")
plt.legend(loc="best", prop=dict(size=12))

plt.figure(figsize=(6, 5))
plt.title("Histogram of the weights")
plt.hist(clf.coef_, bins=n_features, color='gold', log=True,
         edgecolor='black')
plt.scatter(clf.coef_[relevant_features], np.full(len(relevant_features), 5.),
            color='navy', label="Relevant features")
plt.ylabel("Features")
plt.xlabel("Values of the weights")
plt.legend(loc="upper left")

plt.figure(figsize=(6, 5))
plt.title("Marginal log-likelihood")
plt.plot(clf.scores_, color='navy', linewidth=lw)
plt.ylabel("Score")
plt.xlabel("Iterations")

# Plotting some predictions for polynomial regression

def f(x, noise_amount):
    y = np.sqrt(x) * np.sin(x)
    noise = np.random.normal(0, 1, len(x))
    return y + noise_amount * noise

degree = 10
X = np.linspace(0, 10, 100)
y = f(X, noise_amount=0.1)
clf_poly = BayesianRidge()
clf_poly.fit(np.vander(X, degree), y)

X_plot = np.linspace(0, 11, 25)
y_plot = f(X_plot, noise_amount=0)
y_mean, y_std = clf_poly.predict(np.vander(X_plot, degree), return_std=True)
plt.figure(figsize=(6, 5))
plt.errorbar(X_plot, y_mean, y_std, color='navy',
    label="Polynomial Bayesian Ridge Regression", linewidth=lw)
plt.plot(X_plot, y_plot, color='gold', linewidth=lw,
    label="Ground Truth")
plt.ylabel("Output y")
plt.xlabel("Feature X")
plt.legend(loc="lower left")
plt.show()

Total running time of the script: ( 0 minutes 0.597 seconds)

6.16.33 Lasso model selection: Cross-Validation / AIC / BIC

Use the Akaike information criterion (AIC), the Bayes Information criterion (BIC) and cross-validation to select an optimal value of the regularization parameter alpha of the Lasso estimator.

Results obtained with LassoLarsIC are based on AIC/BIC criteria.

Information-criterion based model selection is very fast, but it relies on a proper estimation of degrees of freedom, are derived for large samples (asymptotic results) and assume the model is correct, i.e. that the data are actually generated by this model. They also tend to break when the problem is badly conditioned (more features than samples).

For cross-validation, we use 20-fold with 2 algorithms to compute the Lasso path: coordinate descent, as implemented by the LassoCV class, and Lars (least angle regression) as implemented by the LassoLarsCV class. Both algorithms give roughly the same results. They differ with regards to their execution speed and sources of numerical errors.

Lars computes a path solution only for each kink in the path. As a result, it is very efficient when there are only of few kinks, which is the case if there are few features or samples. Also, it is able to compute the full path without setting any meta parameter. On the opposite, coordinate descent compute the path points on a pre-specified grid (here we use the default). Thus it is more efficient if the number of grid points is smaller than the number of kinks in the path. Such a strategy can be interesting if the number of features is really large and there are enough samples to select a large amount. In terms of numerical errors, for heavily correlated variables, Lars will accumulate more errors, while the coordinate descent algorithm will only sample the path on a grid.

Note how the optimal value of alpha varies for each fold. This illustrates why nested-cross validation is necessary when trying to evaluate the performance of a method for which a parameter is chosen by cross-validation: this choice of parameter may not be optimal for unseen data.
Information-criterion for model selection (training time 0.005s)

- AIC criterion
- alpha: AIC estimate
- BIC criterion
- alpha: BIC estimate

Criterion vs. $\alpha$ for different information criteria.

6.16. Generalized Linear Models
import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import LassoCV, LassoLarsCV, LassoLarsIC
from sklearn import datasets

EPSILON = 1e-4
X, y = datasets.load_diabetes(return_X_y=True)

print(__doc__)

# Author: Olivier Grisel, Gael Varoquaux, Alexandre Gramfort
# License: BSD 3 clause

import time
import numpy as np
import matplotlib.pyplot as plt
from sklearn.linear_model import LassoCV, LassoLarsCV, LassoLarsIC
from sklearn import datasets

EPSILON = 1e-4
X, y = datasets.load_diabetes(return_X_y=True)
rng = np.random.RandomState(42)
X = np.c_[X, rng.randn(X.shape[0], 14)]  # add some bad features

# normalize data as done by Lars to allow for comparison
X /= np.sqrt(np.sum(X ** 2, axis=0))

# LassoLarsIC: least angle regression with BIC/AIC criterion
model_bic = LassoLarsIC(criterion='bic')
t1 = time.time()
model_bic.fit(X, y)
t_bic = time.time() - t1
alpha_bic_ = model_bic.alpha_

model_aic = LassoLarsIC(criterion='aic')
model_aic.fit(X, y)
alpha_aic_ = model_aic.alpha_

def plot_ic_criterion(model, name, color):
    criterion_ = model.criterion_
    plt.semilogx(model.alphas_ + EPSILON, criterion_, '--', color=color,
                 linewidth=3, label='{} criterion'.format(name))
    plt.axvline(model.alpha_ + EPSILON, color=color, linewidth=3,
                label='alpha: estimate')
    plt.xlabel(r'$\alpha$')
    plt.ylabel('criterion')

plt.figure()
plot_ic_criterion(model_aic, 'AIC', 'b')
plot_ic_criterion(model_bic, 'BIC', 'r')
plt.legend()
plt.title('Information-criterion for model selection (training time %.3fs)' % t_bic)

# LassoCV: coordinate descent

# Compute paths
print("Computing regularization path using the coordinate descent lasso...")
t1 = time.time()
model = LassoCV(cv=20).fit(X, y)
t_lasso_cv = time.time() - t1

# Display results
plt.figure()
ymin, ymax = 2300, 3800
plt.semilogx(model.alphas_ + EPSILON, model.mse_path_, ':')
plt.plot(model.alphas_ + EPSILON, model.mse_path_.mean(axis=-1), 'k',
         label='Average across the folds', linewidth=2)
plt.axvline(model.alpha_ + EPSILON, linestyle='--', color='k',
            label='alpha: CV estimate')
plt.legend()
plt.xlabel(r'$\alpha$')
plt.ylabel('Mean square error')
plt.title('Mean square error on each fold: coordinate descent ' +
          '(train time: %.2fs)' % t_lasso_cv)
plt.axis('tight')
plt.ylim(ymin, ymax)

# LassoCV: least angle regression

# Compute paths
print("Computing regularization path using the Lars lasso...")
t1 = time.time()
model = LassoLarsCV(cv=20).fit(X, y)
t_lasso_lars_cv = time.time() - t1

# Display results
plt.figure()
plt.semilogx(model.cv_alphas_ + EPSILON, model.mse_path_, ':')
plt.semilogx(model.cv_alphas_ + EPSILON, model.mse_path_.mean(axis=-1), 'k',
             label='Average across the folds', linewidth=2)
plt.axvline(model.alpha_, linestyle='--', color='k',
            label='alpha CV')
plt.legend()

plt.xlabel(r'$\alpha$')
plt.ylabel('Mean square error')
plt.title('Mean square error on each fold: Lars (train time: %.2fs)' % t_lasso_lars_cv)
plt.axis('tight')
plt.ylim(ymin, ymax)
plt.show()
Out:

Dataset 20newsgroup, train_samples=9000, n_features=130107, n_classes=20

[model=One versus Rest, solver=saga] Number of epochs: 1
[model=One versus Rest, solver=saga] Number of epochs: 2
[model=One versus Rest, solver=saga] Number of epochs: 4
Test accuracy for model ovr: 0.7490
% non-zero coefficients for model ovr, per class:
[0.31743104 0.36815852 0.4181174 0.46115889 0.24595141 0.41350581 0.31281945 0.27054655 0.58720899 0.32972861 0.4158116 0.3312658 0.41888599 0.41120001 0.59643217 0.31666244 0.34279478 0.28130692 0.35278655 0.24748861]
Run time (4 epochs) for model ovr: 2.95

[model=Multinomial, solver=saga] Number of epochs: 1
[model=Multinomial, solver=saga] Number of epochs: 3
[model=Multinomial, solver=saga] Number of epochs: 7
Test accuracy for model multinomial: 0.7450
% non-zero coefficients for model multinomial, per class:
[0.13219888 0.11452112 0.13066169 0.13681047 0.12066991 0.15909981 0.13450468 0.09146318 0.07916561 0.12143851 0.13911627 0.10760374 0.18984374 0.12143851 0.17524038 0.22289346 0.11605832 0.07916561 0.07301682 0.15141384]
Run time (7 epochs) for model multinomial: 2.84
Example run in 11.819 s
```python
import timeit
import warnings
import matplotlib.pyplot as plt
import numpy as np

from sklearn.datasets import fetch_20newsgroups_vectorized
from sklearn.linear_model import LogisticRegression
from sklearn.model_selection import train_test_split
from sklearn.exceptions import ConvergenceWarning

print(__doc__)

# Author: Arthur Mensch
warnings.filterwarnings("ignore", category=ConvergenceWarning, module="sklearn")
t0 = timeit.default_timer()

# We use SAGA solver
solver = 'saga'

# Turn down for faster run time
n_samples = 10000

X, y = fetch_20newsgroups_vectorized(subset='all', return_X_y=True)
X = X[:n_samples]
y = y[:n_samples]

X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42, stratify=y, test_size=0.1)

train_samples, n_features = X_train.shape
n_classes = np.unique(y).shape[0]

print('Dataset 20newsgroup, train_samples=%i, n_features=%i, n_classes=%i'
     % (train_samples, n_features, n_classes))

models = {'ovr': {'name': 'One versus Rest', 'iters': [1, 2, 4]},
          'multinomial': {'name': 'Multinomial', 'iters': [1, 3, 7]}}

for model in models:
    # Add initial chance-level values for plotting purpose
    accuracies = [1 / n_classes]
    times = [0]
    densities = [1]

    model_params = models[model]

    # Small number of epochs for fast runtime
    for this_max_iter in model_params['iters']:
        print('([model=%s, solver=%s] Number of epochs: %s' %
              (model, solver, this_max_iter))
        lr = LogisticRegression(solver=solver,
```

(continues on next page)
```python
multi_class=model,
penalty='l1',
max_iter=this_max_iter,
random_state=42,
)

t1 = timeit.default_timer()
lr.fit(X_train, y_train)
train_time = timeit.default_timer() - t1

y_pred = lr.predict(X_test)
accuracy = np.sum(y_pred == y_test) / y_test.shape[0]
density = np.mean(lr.coef_ != 0, axis=1) * 100
accuracies.append(accuracy)
densities.append(density)
times.append(train_time)
models[model]['times'] = times
models[model]['densities'] = densities
models[model]['accuracies'] = accuracies

print('Test accuracy for model %s: %.4f' % (model, accuracies[-1]))
print('Non-zero coefficients for model %s, per class:

%0.2f%%' % (model, densities[-1]))

for model in models:
    name = models[model]['name']
times = models[model]['times']
accuracies = models[model]['accuracies']
ax.plot(times, accuracies, marker='o',
        label='Model: %s %s' % (name))
ax.set_xlabel('Train time (s)')
ax.set_ylabel('Test accuracy')
ax.legend()
fig.suptitle('Multinomial vs One-vs-Rest Logistic L1

Dataset %s %s' % ('20newsgroups'))
fig.tight_layout()
run_time = timeit.default_timer() - t0
print('Example run in %.3f s' % run_time)
plt.show()
```

Total running time of the script: (0 minutes 11.876 seconds)
6.16.35 Early stopping of Stochastic Gradient Descent

Stochastic Gradient Descent is an optimization technique which minimizes a loss function in a stochastic fashion, performing a gradient descent step sample by sample. In particular, it is a very efficient method to fit linear models.

As a stochastic method, the loss function is not necessarily decreasing at each iteration, and convergence is only guaranteed in expectation. For this reason, monitoring the convergence on the loss function can be difficult.

Another approach is to monitor convergence on a validation score. In this case, the input data is split into a training set and a validation set. The model is then fitted on the training set and the stopping criterion is based on the prediction score computed on the validation set. This enables us to find the least number of iterations which is sufficient to build a model that generalizes well to unseen data and reduces the chance of over-fitting the training data.

This early stopping strategy is activated if `early_stopping=True`; otherwise the stopping criterion only uses the training loss on the entire input data. To better control the early stopping strategy, we can specify a parameter `validation_fraction` which set the fraction of the input dataset that we keep aside to compute the validation score. The optimization will continue until the validation score did not improve by at least `tol` during the last `n_iter_no_change` iterations. The actual number of iterations is available at the attribute `n_iter_`.

This example illustrates how the early stopping can used in the `SGDClassifier` model to achieve almost the same accuracy as compared to a model built without early stopping. This can significantly reduce training time. Note that scores differ between the stopping criteria even from early iterations because some of the training data is held out with the validation stopping criterion.

Out:

| No stopping criterion: .................................................  |
| Training loss: .........................................................  |
| Validation score: .....................................................  |

6.16. Generalized Linear Models
# Authors: Tom Dupre la Tour
# # License: BSD 3 clause
import time
import sys
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt

from sklearn import linear_model
from sklearn.datasets import fetch_openml
from sklearn.model_selection import train_test_split
from sklearn.utils._testing import ignore_warnings
from sklearn.exceptions import ConvergenceWarning
from sklearn.utils import shuffle

print(__doc__)

def load_mnist(n_samples=None, class_0='0', class_1='8'):
    """Load MNIST, select two classes, shuffle and return only n_samples.""
    # Load data from http://openml.org/d/554
    mnist = fetch_openml('mnist_784', version=1)
    # take only two classes for binary classification
    mask = np.logical_or(mnist.target == class_0, mnist.target == class_1)
    X, y = shuffle(mnist.data[mask], mnist.target[mask], random_state=42)
    if n_samples is not None:
        X, y = X[:n_samples], y[:n_samples]
    return X, y

@ignore_warnings(category=ConvergenceWarning)
def fit_and_score(estimator, max_iter, X_train, X_test, y_train, y_test):
    """Fit the estimator on the train set and score it on both sets""
    estimator.set_params(max_iter=max_iter)
    estimator.set_params(random_state=0)
    start = time.time()
    estimator.fit(X_train, y_train)
    fit_time = time.time() - start
    n_iter = estimator.n_iter_
    train_score = estimator.score(X_train, y_train)
    test_score = estimator.score(X_test, y_test)
    return fit_time, n_iter, train_score, test_score

# Define the estimators to compare
estimator_dict = {
    'No stopping criterion':
}
linear_model.SGDClassifier(n_iter_no_change=3),
'Training loss':
linear_model.SGDClassifier(early_stopping=False, n_iter_no_change=3, tol=0.1),
'Validation score':
linear_model.SGDClassifier(early_stopping=True, n_iter_no_change=3, tol=0.0001, validation_fraction=0.2)

# Load the dataset
X, y = load_mnist(n_samples=10000)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.5, random_state=0)

results = []
for estimator_name, estimator in estimator_dict.items():
    print(estimator_name + ': ', end='')
    for max_iter in range(1, 50):
        print('.', end='')
        sys.stdout.flush()
        fit_time, n_iter, train_score, test_score = fit_and_score(
            estimator, max_iter, X_train, X_test, y_train, y_test)
        results.append((estimator_name, max_iter, fit_time, n_iter, train_score, test_score))
        print('
')

# Transform the results in a pandas dataframe for easy plotting
columns = [
    'Stopping criterion', 'max_iter', 'Fit time (sec)', 'n_iter_',
    'Train score', 'Test score'
]
results_df = pd.DataFrame(results, columns=columns)

# Define what to plot (x_axis, y_axis)
lines = 'Stopping criterion'
plot_list = [
    ('max_iter', 'Train score'),
    ('max_iter', 'Test score'),
    ('max_iter', 'n_iter_'),
    ('max_iter', 'Fit time (sec)')
]

nrows = 2
ncols = int(np.ceil(len(plot_list) / 2.))
fig, axes = plt.subplots(nrows=nrows, ncols=ncols, figsize=(6 * ncols, 4 * nrows))
axes[0, 0].get_shared_y_axes().join(axes[0, 0], axes[0, 1])

for ax, (x_axis, y_axis) in zip(axes.ravel(), plot_list):
    for criterion, group_df in results_df.groupby(lines):
        group_df.plot(x=x_axis, y=y_axis, label=criterion, ax=ax)
    ax.set_title(y_axis)
    ax.legend(title=lines)

fig.tight_layout()

(continues on next page)
**6.16.36 Poisson regression and non-normal loss**

This example illustrates the use of log-linear Poisson regression on the French Motor Third-Party Liability Claims dataset from\(^1\) and compares it with a linear model fitted with the usual least squared error and a non-linear GBRT model fitted with the Poisson loss (and a log-link).

A few definitions:

- A **policy** is a contract between an insurance company and an individual: the **policyholder**, that is, the vehicle driver in this case.
- A **claim** is the request made by a policyholder to the insurer to compensate for a loss covered by the insurance.
- The **exposure** is the duration of the insurance coverage of a given policy, in years.
- The claim **frequency** is the number of claims divided by the exposure, typically measured in number of claims per year.

In this dataset, each sample corresponds to an insurance policy. Available features include driver age, vehicle age, vehicle power, etc.

Our goal is to predict the expected frequency of claims following car accidents for a new policyholder given the historical data over a population of policyholders.

```python
print(__doc__)
# Authors: Christian Lorentzen <lorentzen.ch@gmail.com>
# Roman Yurchak <rth.yurchak@gmail.com>
# Olivier Grisel <olivier.grisel@ensta.org>
# License: BSD 3 clause
import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
```

**The French Motor Third-Party Liability Claims dataset**

Let’s load the motor claim dataset from OpenML: [https://www.openml.org/d/41214](https://www.openml.org/d/41214)

```python
from sklearn.datasets import fetch_openml
df = fetch_openml(data_id=41214, as_frame=True).frame
df
```

```
/home/circleci/project/sklearn/datasets/_openml.py:849: UserWarning: Version 1 of dataset freMTPL2freq is inactive, meaning that issues have been found in the dataset. Try using a newer version from this URL: https://www.openml.org/data/v1/download/20649148/freMTPL2freq.arff
  warn("Version {} of dataset {} is inactive, meaning that issues have "
```

The number of claims ($\text{ClaimNb}$) is a positive integer that can be modeled as a Poisson distribution. It is then assumed to be the number of discrete events occurring with a constant rate in a given time interval ($\text{Exposure}$, in units of years).

Here we want to model the frequency $y = \text{ClaimNb} / \text{Exposure}$ conditionally on $X$ via a (scaled) Poisson distribution, and use $\text{Exposure}$ as sample_weight.

```python
df["Frequency"] = df["ClaimNb"] / df["Exposure"]
print("Average Frequency = \
      {0:.4f}\n      ", np.average(df["Frequency"], weights=df["Exposure"])))
print("Fraction of exposure with zero claims = {0:.1%}".format(df.loc[df["ClaimNb"] == 0, "Exposure"].sum() / df["Exposure"].sum()))
fig, (ax0, ax1, ax2) = plt.subplots(ncols=3, figsize=(16, 4))
ax0.set_title("Number of claims")
_ = df["ClaimNb"].hist(bins=30, log=True, ax=ax0)
ax1.set_title("Exposure in years")
_ = df["Exposure"].hist(bins=30, log=True, ax=ax1)
ax2.set_title("Frequency (number of claims per year)")
_ = df["Frequency"].hist(bins=30, log=True, ax=ax2)
```

Out:

```
Average Frequency = 0.10070308464041304
Fraction of exposure with zero claims = 93.9%
```

The remaining columns can be used to predict the frequency of claim events. Those columns are very heterogeneous with a mix of categorical and numeric variables with different scales, possibly very unevenly distributed.

In order to fit linear models with those predictors it is therefore necessary to perform standard feature transformations as follows:

```python
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import FunctionTransformer, OneHotEncoder
from sklearn.preprocessing import StandardScaler, KBinsDiscretizer
from sklearn.compose import ColumnTransformer

log_scale_transformer = make_pipeline(
    FunctionTransformer(np.log, validate=False),
    StandardScaler()
)
linear_model_preprocessor = ColumnTransformer(
```

(continues on next page)
```python
[  
    ("passthrough_numeric", "passthrough",  
      ["BonusMalus"]),  
    ("binned_numeric", KBinsDiscretizer(n_bins=10),  
      ["VehAge", "DrivAge"]),  
    ("log_scaled_numeric", log_scale_transformer,  
      ["Density"]),  
    ("onehot_categorical", OneHotEncoder(),  
      ["VehBrand", "VehPower", "VehGas", "Region", "Area"]),  
],
remainder="drop",
)
```

### A constant prediction baseline

It is worth noting that more than 93% of policyholders have zero claims. If we were to convert this problem into a binary classification task, it would be significantly imbalanced, and even a simplistic model that would only predict mean can achieve an accuracy of 93%.

To evaluate the pertinence of the used metrics, we will consider as a baseline a “dummy” estimator that constantly predicts the mean frequency of the training sample.

```python
from sklearn.dummy import DummyRegressor  
from sklearn.pipeline import Pipeline  
from sklearn.model_selection import train_test_split

df_train, df_test = train_test_split(df, test_size=0.33, random_state=0)  
dummy = Pipeline([  
    ("preprocessor", linear_model_preprocessor),  
    ("regressor", DummyRegressor(strategy='mean')),  
]).fit(df_train, df_train["Frequency"],  
      regressor__sample_weight=df_train["Exposure"])
```

Let’s compute the performance of this constant prediction baseline with 3 different regression metrics:

```python
from sklearn.metrics import mean_squared_error  
from sklearn.metrics import mean_absolute_error  
from sklearn.metrics import mean_poisson_deviance

def score_estimator(estimator, df_test):
    """Score an estimator on the test set."""
    y_pred = estimator.predict(df_test)  
    print("MSE: \$%.3f\$\" %  
      mean_squared_error(df_test["Frequency"], y_pred,  
                         sample_weight=df_test["Exposure"]))  
    print("MAE: \$%.3f\$\" %  
      mean_absolute_error(df_test["Frequency"], y_pred,  
                         sample_weight=df_test["Exposure"]))

    # Ignore non-positive predictions, as they are invalid for  
    # the Poisson deviance.
    mask = y_pred > 0
```
if (~mask).any():
    n_masked, n_samples = (~mask).sum(), mask.shape[0]
    print(f"WARNING: Estimator yields invalid, non-positive predictions "
          f" for {n_masked} samples out of {n_samples}. These predictions "
          f"are ignored when computing the Poisson deviance."
    
    print(f"mean Poisson deviance: %.3f" %
          mean_poisson_deviance(df_test["Frequency"][mask],
          y_pred[mask],
          sample_weight=df_test["Exposure"][mask]))

print("Constant mean frequency evaluation:")
score_estimator(dummy, df_test)

Out:

Constant mean frequency evaluation:
MSE: 0.564
MAE: 0.189
mean Poisson deviance: 0.625

(Generalized) linear models

We start by modeling the target variable with the (l2 penalized) least squares linear regression model, more commonly known as Ridge regression. We use a low penalization alpha, as we expect such a linear model to under-fit on such a large dataset.

```python
from sklearn.linear_model import Ridge

ridge_glm = Pipeline([
    ("preprocessor", linear_model_preprocessor),
    ("regressor", Ridge(alpha=1e-6)),
]).fit(df_train, df_train["Frequency"],
      regressor__sample_weight=df_train["Exposure"]
)
```

The Poisson deviance cannot be computed on non-positive values predicted by the model. For models that do return a few non-positive predictions (e.g. Ridge) we ignore the corresponding samples, meaning that the obtained Poisson deviance is approximate. An alternative approach could be to use TransformedTargetRegressor meta-estimator to map y_pred to a strictly positive domain.

```python
print("Ridge evaluation:")
score_estimator(ridge_glm, df_test)
```

Out:

Ridge evaluation:
MSE: 0.560
MAE: 0.177
WARNING: Estimator yields invalid, non-positive predictions for 1315 samples out of 223745. These predictions are ignored when computing the Poisson deviance.
mean Poisson deviance: 0.601
Next we fit the Poisson regressor on the target variable. We set the regularization strength $\alpha$ to approximately $1e-6$ over number of samples (i.e. $1e-12$) in order to mimic the Ridge regressor whose L2 penalty term scales differently with the number of samples.

Since the Poisson regressor internally models the log of the expected target value instead of the expected value directly (log vs identity link function), the relationship between $X$ and $y$ is not exactly linear anymore. Therefore the Poisson regressor is called a Generalized Linear Model (GLM) rather than a vanilla linear model as is the case for Ridge regression.

```python
from sklearn.linear_model import PoissonRegressor

n_samples = df_train.shape[0]

poisson_glm = Pipeline([
    ("preprocessor", linear_model_preprocessor),
    ("regressor", PoissonRegressor(alpha=1e-12, max_iter=300))
])

poisson_glm.fit(df_train, df_train["Frequency"],
                 regressor__sample_weight=df_train["Exposure"])

print("PoissonRegressor evaluation:")

score_estimator(poisson_glm, df_test)
```

Out:

```
PoissonRegressor evaluation:
MSE: 0.560
MAE: 0.186
mean Poisson deviance: 0.594
```

**Gradient Boosting Regression Trees for Poisson regression**

Finally, we will consider a non-linear model, namely Gradient Boosting Regression Trees. Tree-based models do not require the categorical data to be one-hot encoded: instead, we can encode each category label with an arbitrary integer using `OrdinalEncoder`. With this encoding, the trees will treat the categorical features as ordered features, which might not be always a desired behavior. However this effect is limited for deep enough trees which are able to recover the categorical nature of the features. The main advantage of the `OrdinalEncoder` over the `OneHotEncoder` is that it will make training faster.

Gradient Boosting also gives the possibility to fit the trees with a Poisson loss (with an implicit log-link function) instead of the default least-squares loss. Here we only fit trees with the Poisson loss to keep this example concise.

```python
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor
from sklearn.preprocessing import OrdinalEncoder

tree_preprocessor = ColumnTransformer(
    [  
        ("categorical", OrdinalEncoder(),
         ["VehBrand", "VehPower", "VehGas", "Region", "Area"]),
        ("numeric", "passthrough",
         ["VehAge", "DrivAge", "BonusMalus", "Density"]),
    ],
    remainder="drop",
)
```

(continues on next page)
poisson_gbrt = Pipeline(
    ("preprocessor", tree_preprocessor),
    ("regressor", HistGradientBoostingRegressor(loss="poisson",
        max_leaf_nodes=128)),
)
poisson_gbrt.fit(df_train, df_train["Frequency"],
    regressor__sample_weight=df_train["Exposure"])

print("Poisson Gradient Boosted Trees evaluation:")
score_estimator(poisson_gbrt, df_test)

Out:

Poisson Gradient Boosted Trees evaluation:
MSE: 0.560
MAE: 0.184
mean Poisson deviance: 0.575

Like the Poisson GLM above, the gradient boosted trees model minimizes the Poisson deviance. However, because of a higher predictive power, it reaches lower values of Poisson deviance.

Evaluating models with a single train / test split is prone to random fluctuations. If computing resources allow, it should be verified that cross-validated performance metrics would lead to similar conclusions.

The qualitative difference between these models can also be visualized by comparing the histogram of observed target values with that of predicted values:

```python
fig, axes = plt.subplots(nrows=2, ncols=4, figsize=(16, 6), sharey=True)
fig.subplots_adjust(bottom=0.2)
n_bins = 20
for row_idx, label, df in zip(range(2), ["train", "test"], [df_train, df_test]):
    df["Frequency"].hist(bins=np.linspace(-1, 30, n_bins),
        ax=axes[row_idx, 0])
    axes[row_idx, 0].set_title("Data")
    axes[row_idx, 0].set_yscale('log')
    axes[row_idx, 0].set_xlabel("y (observed Frequency)")
    axes[row_idx, 0].set_ylim([1e1, 5e5])
    axes[row_idx, 0].set_ylabel(label + " samples")

for idx, model in enumerate([ridge_glm, poisson_glm, poisson_gbrt]):
    y_pred = model.predict(df)
    pd.Series(y_pred).hist(bins=np.linspace(-1, 4, n_bins),
        ax=axes[row_idx, idx+1])
    axes[row_idx, idx + 1].set(
        title=model["-l1"].__class__.__name__,
        yscale='log',
        xlabel="y_pred (predicted expected Frequency)"
    )
plt.tight_layout()
```
The experimental data presents a long tail distribution for \( y \). In all models, we predict the expected frequency of a random variable, so we will have necessarily fewer extreme values than for the observed realizations of that random variable. This explains that the mode of the histograms of model predictions doesn’t necessarily correspond to the smallest value. Additionally, the normal distribution used in \texttt{Ridge} has a constant variance, while for the Poisson distribution used in \texttt{PoissonRegressor} and \texttt{HistGradientBoostingRegressor}, the variance is proportional to the predicted expected value.

Thus, among the considered estimators, \texttt{PoissonRegressor} and \texttt{HistGradientBoostingRegressor} are a-priori better suited for modeling the long tail distribution of the non-negative data as compared to the \texttt{Ridge} model which makes a wrong assumption on the distribution of the target variable.

The \texttt{HistGradientBoostingRegressor} estimator has the most flexibility and is able to predict higher expected values.

Note that we could have used the least squares loss for the \texttt{HistGradientBoostingRegressor} model. This would wrongly assume a normal distributed response variable as does the \texttt{Ridge} model, and possibly also lead to slightly negative predictions. However the gradient boosted trees would still perform relatively well and in particular better than \texttt{PoissonRegressor} thanks to the flexibility of the trees combined with the large number of training samples.

**Evaluation of the calibration of predictions**

To ensure that estimators yield reasonable predictions for different policyholder types, we can bin test samples according to \( y_{\text{pred}} \) returned by each model. Then for each bin, we compare the mean predicted \( y_{\text{pred}} \), with the mean observed target:

```python
from sklearn.utils import gen_even_slices

def _mean_frequency_by_risk_group(y_true, y_pred, sample_weight=None, n_bins=100):
    """Compare predictions and observations for bins ordered by y_pred."
    We order the samples by `y_pred` and split it in bins.
    In each bin the observed mean is compared with the predicted mean.
    Parameters
    ----------
    y_true: array-like of shape (n_samples,)
        Ground truth (correct) target values.
    (continues on next page)```
y_pred: array-like of shape (n_samples,)
Estimated target values.
sample_weight: array-like of shape (n_samples,)
Sample weights.
n_bins: int
Number of bins to use.

Returns
-------
bin_centers: ndarray of shape (n_bins,)
bin centers
y_true_bin: ndarray of shape (n_bins,)
average y_true for each bin
y_pred_bin: ndarray of shape (n_bins,)
average y_pred for each bin

```
idx_sort = np.argsort(y_pred)
bin_centers = np.arange(0, 1, 1/n_bins) + 0.5/n_bins
y_pred_bin = np.zeros(n_bins)
weights = sample_weight[idx_sort][sl]
y_pred_bin[n] = np.average(y_pred[idx_sort][sl], weights=weights)
y_true_bin[n] = np.average(y_true[idx_sort][sl], weights=weights)
```

for n, sl in enumerate(gen_even_slices(len(y_true), n_bins)):
    weights = sample_weight[idx_sort][sl]
    y_pred_bin[n] = np.average(y_pred[idx_sort][sl], weights=weights)
    y_true_bin[n] = np.average(y_true[idx_sort][sl], weights=weights)

return bin_centers, y_true_bin, y_pred_bin

print(f"Actual number of claims: {df_test['ClaimNb'].sum()}")
fig, ax = plt.subplots(nrows=2, ncols=2, figsize=(12, 8))
plt.subplots_adjust(wspace=0.3)
for axi, model in zip(ax.ravel(), [ridge_glm, poisson_glm, poisson_gbrt, dummy]):
    y_pred = model.predict(df_test)
y_true = df_test['Frequency'].values
exposure = df_test['Exposure'].values
q, y_true_seg, y_pred_seg = _mean_frequency_by_risk_group(
    y_true, y_pred, sample_weight=exposure, n_bins=10)

    # Name of the model after the estimator used in the last step of the
    # pipeline.
    print(f"Predicted number of claims by {model[-1]}: 
    f""{(np.sum(y_pred * exposure):.1f)}")

    axi.plot(q, y_pred_seg, marker='x', linestyle="--", label="predictions")
    axi.plot(q, y_true_seg, marker='o', linestyle="--", label="observations")
    axi.set_xlim(0, 1.0)
    axi.set_ylim(0, 0.5)
    axi.set(
        title=model[-1],
        xlabel='Fraction of samples sorted by y_pred',
        xlabel='Fraction of samples sorted by y_pred',
        ylabel='Number of samples in each bin')

(continues on next page)
Out:

Actual number of claims: 11935.0
Predicted number of claims by Ridge(alpha=1e-06): 10692.9
Predicted number of claims by PoissonRegressor(alpha=1e-12, max_iter=300): 11932.0
Predicted number of claims by HistGradientBoostingRegressor(loss='poisson', max_leaf_nodes=128): 12109.6
Predicted number of claims by DummyRegressor(): 11931.2

The dummy regression model predicts a constant frequency. This model does not attribute the same tied rank to all samples but is none-the-less globally well calibrated (to estimate the mean frequency of the entire population).

The Ridge regression model can predict very low expected frequencies that do not match the data. It can therefore severly under-estimate the risk for some policyholders.

PoissonRegressor and HistGradientBoostingRegressor show better consistency between predicted and observed targets, especially for low predicted target values.

The sum of all predictions also confirms the calibration issue of the Ridge model: it under-estimates by more than 3% the total number of claims in the test set while the other three models can approximately recover the total number of claims of the test portfolio.
Evaluation of the ranking power

For some business applications, we are interested in the ability of the model to rank the riskiest from the safest policyholders, irrespective of the absolute value of the prediction. In this case, the model evaluation would cast the problem as a ranking problem rather than a regression problem.

To compare the 3 models from this perspective, one can plot the cumulative proportion of claims vs the cumulative proportion of exposure for the test samples order by the model predictions, from safest to riskiest according to each model.

This plot is called a Lorenz curve and can be summarized by the Gini index:

```python
from sklearn.metrics import auc
def lorenz_curve(y_true, y_pred, exposure):
    y_true, y_pred = np.asarray(y_true), np.asarray(y_pred)
    exposure = np.asarray(exposure)

    # order samples by increasing predicted risk:
    ranking = np.argsort(y_pred)
    ranked_frequencies = y_true[ranking]
    ranked_exposure = exposure[ranking]
    cumulated_claims = np.cumsum(ranked_frequencies * ranked_exposure)
    cumulated_claims /= cumulated_claims[-1]
    cumulated_exposure = np.cumsum(ranked_exposure)
    cumulated_exposure /= cumulated_exposure[-1]
    return cumulated_exposure, cumulated_claims

fig, ax = plt.subplots(figsize=(8, 8))
for model in [dummy, ridge_glm, poisson_glm, poisson_gbrt]:
    y_pred = model.predict(df_test)
    cum_exposure, cum_claims = lorenz_curve(df_test["Frequency"], y_pred,
                                           df_test["Exposure"],
                                           df_test["Exposure"])
    gini = 1 - 2 * auc(cum_exposure, cum_claims)
    label = "{} (Gini: {:.2f})".format(model[-1], gini)
    ax.plot(cum_exposure, cum_claims, linestyle="-", label=label)

# Oracle model: y_pred == y_test
    cum_exposure, cum_claims = lorenz_curve(df_test["Frequency"],
                                           df_test["Frequency"],
                                           df_test["Exposure"])
    gini = 1 - 2 * auc(cum_exposure, cum_claims)
    label = "Oracle (Gini: {:.2f})".format(gini)
    ax.plot(cum_exposure, cum_claims, linestyle="-.", color="gray", label=label)

# Random Baseline
    ax.plot([0, 1], [0, 1], linestyle="--", color="black",
            label="Random baseline")
    ax.set(
        title="Lorenz curves by model",
        xlabel='Cumulative proportion of exposure (from safest to riskiest)',
        ylabel='Cumulative proportion of claims'
    )
    ax.legend(loc="upper left")
```

6.16. Generalized Linear Models
As expected, the dummy regressor is unable to correctly rank the samples and therefore performs the worst on this plot.

The tree-based model is significantly better at ranking policyholders by risk while the two linear models perform similarly.

All three models are significantly better than chance but also very far from making perfect predictions.

This last point is expected due to the nature of the problem: the occurrence of accidents is mostly dominated by circumstantial causes that are not captured in the columns of the dataset and can indeed be considered as purely random.
The linear models assume no interactions between the input variables which likely causes under-fitting. Inserting a polynomial feature extractor (`PolynomialFeatures`) indeed increases their discriminative power by 2 points of Gini index. In particular it improves the ability of the models to identify the top 5% riskiest profiles.

**Main takeaways**

- The performance of the models can be evaluated by their ability to yield well-calibrated predictions and a good ranking.
- The calibration of the model can be assessed by plotting the mean observed value vs the mean predicted value on groups of test samples binned by predicted risk.
- The least squares loss (along with the implicit use of the identity link function) of the Ridge regression model seems to cause this model to be badly calibrated. In particular, it tends to underestimate the risk and can even predict invalid negative frequencies.
- Using the Poisson loss with a log-link can correct these problems and lead to a well-calibrated linear model.
- The Gini index reflects the ability of a model to rank predictions irrespective of their absolute values, and therefore only assess their ranking power.
- Despite the improvement in calibration, the ranking power of both linear models are comparable and well below the ranking power of the Gradient Boosting Regression Trees.
- The Poisson deviance computed as an evaluation metric reflects both the calibration and the ranking power of the model. It also makes a linear assumption on the ideal relationship between the expected value and the variance of the response variable. For the sake of conciseness we did not check whether this assumption holds.
- Traditional regression metrics such as Mean Squared Error and Mean Absolute Error are hard to meaningfully interpret on count values with many zeros.

```python
plt.show()
```

**Total running time of the script:** (0 minutes 47.384 seconds)

### 6.16.37 Tweedie regression on insurance claims

This example illustrates the use of Poisson, Gamma and Tweedie regression on the French Motor Third-Party LiabilityClaims dataset, and is inspired by an R tutorial\(^1\).

In this dataset, each sample corresponds to an insurance policy, i.e. a contract within an insurance company and an individual (policyholder). Available features include driver age, vehicle age, vehicle power, etc.

A few definitions: a *claim* is the request made by a policyholder to the insurer to compensate for a loss covered by the insurance. The *claim amount* is the amount of money that the insurer must pay. The *exposure* is the duration of the insurance coverage of a given policy, in years.

Here our goal is to predict the expected value, i.e. the mean, of the total claim amount per exposure unit also referred to as the pure premium.

There are several possibilities to do that, two of which are:

1. Model the number of claims with a Poisson distribution, and the average claim amount per claim, also known as severity, as a Gamma distribution and multiply the predictions of both in order to get the total claim amount.
2. Model the total claim amount per exposure directly, typically with a Tweedie distribution of Tweedie power \(p \in (1, 2)\).

---


**6.16. Generalized Linear Models**

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In this example we will illustrate both approaches. We start by defining a few helper functions for loading the data and visualizing results.

```python
print(__doc__)

# Authors: Christian Lorentzen <lorentzen.ch@gmail.com>
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# License: BSD 3 clause
from functools import partial
import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from sklearn.datasets import fetch_openml
from sklearn.compose import ColumnTransformer
from sklearn.linear_model import PoissonRegressor, GammaRegressor
from sklearn.linear_model import TweedieRegressor
from sklearn.metrics import mean_tweedie_deviance
from sklearn.model_selection import train_test_split
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import FunctionTransformer, OneHotEncoder
from sklearn.preprocessing import StandardScaler, KBinsDiscretizer
from sklearn.metrics import mean_absolute_error, mean_squared_error, auc

def load_mtpl2(n_samples=100000):
    """Fetch the French Motor Third-Party Liability Claims dataset.

    Parameters
    --------
    n_samples: int, default=100000
        number of samples to select (for faster run time). Full dataset has
        678013 samples.
    ""

    # freMTPL2freq dataset from https://www.openml.org/d/41214
    df_freq = fetch_openml(data_id=41214, as_frame=True)['data']
    df_freq['IDpol'] = df_freq['IDpol'].astype(int)
    df_freq.set_index('IDpol', inplace=True)

    # freMTPL2sev dataset from https://www.openml.org/d/41215
    df_sev = fetch_openml(data_id=41215, as_frame=True)['data']

    # sum ClaimAmount over identical IDs
    df_sev = df_sev.groupby('IDpol').sum()

    # unquote string fields
    for column_name in df.columns[df.dtypes.values == object]:
        df[column_name] = df[column_name].str.strip('"

    return df.iloc[:n_samples]

def plot_obs_pred(df, feature, weight, observed, predicted, y_label=None):
```

(continues on next page)
title=None, ax=None, fill_legend=False):
    """Plot observed and predicted - aggregated per feature level.

    Parameters
    ----------
    df : DataFrame
        input data
    feature : str
        a column name of df for the feature to be plotted
    weight : str
        column name of df with the values of weights or exposure
    observed : str
        a column name of df with the observed target
    predicted : DataFrame
        a dataframe, with the same index as df, with the predicted target
    fill_legend : bool, default=False
        whether to show fill_between legend
    ""

    # aggregate observed and predicted variables by feature level
    df_ = df.loc[:, [feature, weight]].copy()
    df_['observed'] = df[observed] * df[weight]
    df_['predicted'] = predicted * df[weight]
    df_ = (df_.groupby([feature])[[weight, 'observed', 'predicted']]
          .sum()
          .assign(observed=lambda x: x['observed'] / x[weight])
          .assign(predicted=lambda x: x['predicted'] / x[weight])
          )

    ax = df_.loc[:, ['observed', 'predicted']].plot(style='.', ax=ax)
    y_max = df_.loc[:, ['observed', 'predicted']].values.max() * 0.8
    p2 = ax.fill_between(df_.index, 0, y_max * df_[weight] / df_[weight].values.max(),
                        color='g',
                        alpha=0.1,
                        )
    if fill_legend:
        ax.legend([p2], ['{} distribution'.format(feature)])
    ax.set
        ylabel=y_label if y_label is not None else None
        title=title if title is not None else 'Train: Observed vs Predicted',
    )

    def score_estimator(
        estimator, X_train, X_test, df_train, df_test, target, weights,
        tweedie_powers=None,
    ):
        """Evaluate an estimator on train and test sets with different metrics""

        metrics = [
            ('D^2 explained', None),  # Use default scorer if it exists
            ('mean abs. error', mean_absolute_error),
            ('mean squared error', mean_squared_error),
        ]

if tweedie_powers:
    metrics += [{
        "mean Tweedie dev p={:.4f}".format(power),
        partial(mean_tweedie_deviance, power=power)
    } for power in tweedie_powers]

res = []
for subset_label, X, df in ["train", X_train, df_train], ["test", X_test, df_test], :
    y, _weights = df[target], df[weights]
    for score_label, metric in metrics:
        if isinstance(estimator, tuple) and len(estimator) == 2:
            # Score the model consisting of the product of frequency and severity models.
            est_freq, est_sev = estimator
            y_pred = est_freq.predict(X) * est_sev.predict(X)
        else:
            y_pred = estimator.predict(X)

        if metric is None:
            if not hasattr(estimator, "score"):
                continue
            score = estimator.score(X, y, sample_weight=_weights)
        else:
            score = metric(y, y_pred, sample_weight=_weights)

        res.append(
            {"subset": subset_label, "metric": score_label, "score": score}
        )

res = (pd.DataFrame(res)
    .set_index(["metric", "subset"])
    .score.unstack(-1)
    .round(4)
    .loc[:, ['train', 'test']]
)
return res

Loading datasets, basic feature extraction and target definitions

We construct the freMTPL2 dataset by joining the freMTPL2freq table, containing the number of claims (ClaimNb), with the freMTPL2sev table, containing the claim amount (ClaimAmount) for the same policy ids (IDpol).

df = load_mtpl2(n_samples=60000)

# Note: filter out claims with zero amount, as the severity model requires strictly positive target values.
df.loc[(df["ClaimAmount"] == 0) & (df["ClaimNb"] >= 1), "ClaimNb"] = 0

# Correct for unreasonable observations (that might be data error) and a few exceptionally large claim amounts
df["ClaimNb"] = df["ClaimNb"].clip(upper=4)
df["Exposure"] = df["Exposure"].clip(upper=1)
df["ClaimAmount"] = df["ClaimAmount"].clip(upper=200000)

log_scale_transformer = make_pipeline(
    FunctionTransformer(func=np.log),
    StandardScaler()
)
column_trans = ColumnTransformer(
    [
        ("binned_numeric", KBinsDiscretizer(n_bins=10),
        ["VehAge", "DrivAge"]),
        ("onehot_categorical", OneHotEncoder(),
        ["VehBrand", "VehPower", "VehGas", "Region", "Area"]),
        ("passthrough_numeric", "passthrough",
        ["BonusMalus"]),
        ("log_scaled_numeric", log_scale_transformer,
        ["Density"]),
    ],
    remainder="drop",
)
X = column_trans.fit_transform(df)

# Insurances companies are interested in modeling the Pure Premium, that is
# the expected total claim amount per unit of exposure for each policyholder
# in their portfolio:
df["PurePremium"] = df["ClaimAmount"] / df["Exposure"]

# This can be indirectly approximated by a 2-step modeling: the product of the
# Frequency times the average claim amount per claim:
df["Frequency"] = df["ClaimNb"] / df["Exposure"]
df["AvgClaimAmount"] = df["ClaimAmount"] / np.fmax(df["ClaimNb"], 1)

with pd.option_context("display.max_columns", 15):
    print(df[df.ClaimAmount > 0].head())

Out:

<table>
<thead>
<tr>
<th>IDpol</th>
<th>ClaimNb</th>
<th>Exposure</th>
<th>Area</th>
<th>VehPower</th>
<th>VehAge</th>
<th>DrivAge</th>
<th>BonusMalus</th>
<th>VehBrand</th>
</tr>
</thead>
<tbody>
<tr>
<td>139</td>
<td>1.0</td>
<td>0.75</td>
<td>F</td>
<td>7.0</td>
<td>1.0</td>
<td>61.0</td>
<td>50.0</td>
<td>B12</td>
</tr>
<tr>
<td>190</td>
<td>1.0</td>
<td>0.14</td>
<td>B</td>
<td>12.0</td>
<td>5.0</td>
<td>50.0</td>
<td>60.0</td>
<td>B12</td>
</tr>
<tr>
<td>414</td>
<td>1.0</td>
<td>0.14</td>
<td>E</td>
<td>4.0</td>
<td>0.0</td>
<td>36.0</td>
<td>85.0</td>
<td>B12</td>
</tr>
</tbody>
</table>
Frequency model – Poisson distribution

The number of claims (ClaimNb) is a positive integer (0 included). Thus, this target can be modelled by a Poisson distribution. It is then assumed to be the number of discrete events occurring with a constant rate in a given time interval (Exposure, in units of years). Here we model the frequency \( y = \frac{\text{ClaimNb}}{\text{Exposure}} \), which is still a (scaled) Poisson distribution, and use Exposure as sample_weight.

```python
def_train, df_test, X_train, X_test = train_test_split(df, X, random_state=0)

# The parameters of the model are estimated by minimizing the Poisson deviance
# on the training set via a quasi-Newton solver: l-BFGS. Some of the features
# are collinear, we use a weak penalization to avoid numerical issues.
glm_freq = PoissonRegressor(alpha=1e-3, max_iter=400)
glm_freq.fit(X_train, df_train["Frequency"],
              sample_weight=df_train["Exposure"])

scores = score_estimator(
    glm_freq,
    X_train,
    X_test,
    df_train,
    df_test,
    target="Frequency",
    weights="Exposure",
)

print("Evaluation of PoissonRegressor on target Frequency")
print(scores)
```

```
Evaluation of PoissonRegressor on target Frequency
subset       train   test
metric
D^2 explained 0.0590 0.0579
mean abs. error 0.1706 0.1661
mean squared error 0.3041 0.3043
```
We can visually compare observed and predicted values, aggregated by the drivers age (DrivAge), vehicle age (VehAge) and the insurance bonus/malus (BonusMalus).

```python
fig, ax = plt.subplots(nrows=2, ncols=2, figsize=(16, 8))
fig.subplots_adjust(hspace=0.3, wspace=0.2)

plot_obs_pred(
    df=df_train,
    feature="DrivAge",
    weight="Exposure",
    observed="Frequency",
    predicted=glm_freq.predict(X_train),
    y_label="Claim Frequency",
    title="train data",
    ax=ax[0, 0],
)

plot_obs_pred(
    df=df_test,
    feature="DrivAge",
    weight="Exposure",
    observed="Frequency",
    predicted=glm_freq.predict(X_test),
    y_label="Claim Frequency",
    title="test data",
    ax=ax[0, 1],
    fill_legend=True
)

plot_obs_pred(
    df=df_test,
    feature="VehAge",
    weight="Exposure",
    observed="Frequency",
    predicted=glm_freq.predict(X_test),
    y_label="Claim Frequency",
    title="test data",
    ax=ax[1, 0],
    fill_legend=True
)

plot_obs_pred(
    df=df_test,
    feature="BonusMalus",
    weight="Exposure",
    observed="Frequency",
    predicted=glm_freq.predict(X_test),
    y_label="Claim Frequency",
    title="test data",
    ax=ax[1, 1],
    fill_legend=True
)
```

6.16. Generalized Linear Models
According to the observed data, the frequency of accidents is higher for drivers younger than 30 years old, and is positively correlated with the BonusMalus variable. Our model is able to mostly correctly model this behaviour.

### Severity Model - Gamma distribution

The mean claim amount or severity (AvgClaimAmount) can be empirically shown to follow approximately a Gamma distribution. We fit a GLM model for the severity with the same features as the frequency model.

#### Note:

- We filter out ClaimAmount == 0 as the Gamma distribution has support on (0, ∞), not [0, ∞).
- We use ClaimNb as sample_weight to account for policies that contain more than one claim.

```python
mask_train = df_train["ClaimAmount"] > 0
mask_test = df_test["ClaimAmount"] > 0

glm_sev = GammaRegressor(alpha=10., max_iter=10000)
glm_sev.fit(
    X_train[mask_train.values],
    df_train.loc[mask_train, "AvgClaimAmount"],
    sample_weight=df_train.loc[mask_train, "ClaimNb"],
)
scores = score_estimator(
    glm_sev,
    X_train[mask_train.values],
    X_test[mask_test.values],
    df_train[mask_train],
    df_test[mask_test],
    target="AvgClaimAmount",
    weights="ClaimNb",
)
print("Evaluation of GammaRegressor on target AvgClaimAmount")
print(scores)
```
Here, the scores for the test data call for caution as they are significantly worse than for the training data indicating an overfit despite the strong regularization.

Note that the resulting model is the average claim amount per claim. As such, it is conditional on having at least one claim, and cannot be used to predict the average claim amount per policy in general.

```
print("Mean AvgClaim Amount per policy: %.2f "
      % df_train["AvgClaimAmount"].mean())
print("Mean AvgClaim Amount | NbClaim > 0: %.2f"
      % df_train["AvgClaimAmount"][df_train["AvgClaimAmount"] > 0].mean())
print("Predicted Mean AvgClaim Amount | NbClaim > 0: %.2f"
      % glm_sev.predict(X_train).mean())
```

```
Mean AvgClaim Amount per policy: 97.89
Mean AvgClaim Amount | NbClaim > 0: 1899.60
Predicted Mean AvgClaim Amount | NbClaim > 0: 1884.40
```

We can visually compare observed and predicted values, aggregated for the drivers age (DrivAge).

```
fig, ax = plt.subplots(nrows=2, figsize=(16, 6))
plot_obs_pred(
    df=df_train.loc[mask_train],
    feature="DrivAge",
    weight="Exposure",
    observed="AvgClaimAmount",
    predicted=glm_sev.predict(X_train[mask_train.values]),
    y_label="Average Claim Severity",
    title="train data",
    ax=ax[0],
)
plot_obs_pred(
    df=df_test.loc[mask_test],
    feature="DrivAge",
    weight="Exposure",
    observed="AvgClaimAmount",
    predicted=glm_sev.predict(X_test[mask_test.values]),
    y_label="Average Claim Severity",
    title="test data",
    ax=ax[1],
    fill_legend=True
)
plt.tight_layout()
```
Overall, the drivers age \( \text{DrivAge} \) has a weak impact on the claim severity, both in observed and predicted data.

**Pure Premium Modeling via a Product Model vs single TweedieRegressor**

As mentioned in the introduction, the total claim amount per unit of exposure can be modeled as the product of the prediction of the frequency model by the prediction of the severity model.

Alternatively, one can directly model the total loss with a unique Compound Poisson Gamma generalized linear model (with a log link function). This model is a special case of the Tweedie GLM with a “power” parameter \( p \in (1, 2) \). Here, we fix a priori the power parameter of the Tweedie model to some arbitrary value (1.9) in the valid range. Ideally one would select this value via grid-search by minimizing the negative log-likelihood of the Tweedie model, but unfortunately the current implementation does not allow for this (yet).

We will compare the performance of both approaches. To quantify the performance of both models, one can compute the mean deviance of the train and test data assuming a Compound Poisson-Gamma distribution of the total claim amount. This is equivalent to a Tweedie distribution with a power parameter between 1 and 2.

The \texttt{sklearn.metrics.mean_tweedie_deviance} depends on a power parameter. As we do not know the true value of the power parameter, we here compute the mean deviances for a grid of possible values, and compare the models side by side, i.e. we compare them at identical values of power. Ideally, we hope that one model will be consistently better than the other, regardless of power.

\[
\text{glm}_{\text{pure premium}} = \text{TweedieRegressor}(\text{power}=1.9, \alpha=.1, \text{max\_iter}=10000)
\]

\[
\text{glm}_{\text{pure premium}}.\text{fit}(\text{X}\_\text{train}, \text{df}\_\text{train}[\"PurePremium"],
\text{sample\_weight}=\text{df}\_\text{train}[\"Exposure"])
\]

\[
\text{tweedie\_powers} = [1.5, 1.7, 1.8, 1.9, 1.99, 1.999, 1.9999]
\]

\[
\text{scores\_product\_model} = \text{score\_estimator}(\text{glm\_freq, glm\_sev),}
\text{X}\_\text{train}, \text{X}\_\text{test},
\text{df}\_\text{train}, \text{df}\_\text{test},
\text{target}="PurePremium",
\text{weights}="Exposure",
\text{tweedie\_powers}=\text{tweedie\_powers},
)
\]

\[
\text{scores\_glm\_pure\_premium} = \text{score\_estimator}(\text{continues on next page})
scores = pd.concat([scores_product_model, scores_glm_pure_premium], axis=1, sort=True, keys=('Product Model', 'TweedieRegressor'))

print("Evaluation of the Product Model and the Tweedie Regressor "
  "on target PurePremium")

with pd.option_context('display.expand_frame_repr', False):
    print(scores)

Out:

<table>
<thead>
<tr>
<th>subset</th>
<th>Product Model</th>
<th>TweedieRegressor</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>train</td>
<td>test</td>
</tr>
<tr>
<td>D² explained</td>
<td>NaN</td>
<td>NaN</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.5000</td>
<td>8.217810e+01</td>
<td>8.637570e+01</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.7000</td>
<td>3.833650e+01</td>
<td>3.919520e+01</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.8000</td>
<td>3.106840e+01</td>
<td>3.148220e+01</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.9000</td>
<td>3.396200e+01</td>
<td>3.420300e+01</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.9900</td>
<td>1.989240e+02</td>
<td>1.996400e+02</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.9990</td>
<td>1.886429e+03</td>
<td>1.892747e+03</td>
</tr>
<tr>
<td>mean Tweedie dev p=1.9999</td>
<td>1.876452e+04</td>
<td>1.882692e+04</td>
</tr>
<tr>
<td>mean abs. error</td>
<td>3.246758e+02</td>
<td>3.469564e+02</td>
</tr>
<tr>
<td>mean squared error</td>
<td>1.469184e+08</td>
<td>3.325892e+07</td>
</tr>
</tbody>
</table>

In this example, both modeling approaches yield comparable performance metrics. For implementation reasons, the percentage of explained variance $D^2$ is not available for the product model.

We can additionally validate these models by comparing observed and predicted total claim amount over the test and train subsets. We see that, on average, both model tend to underestimate the total claim (but this behavior depends on the amount of regularization).

res = []
for subset_label, X, df in [('train', X_train, df_train), ('test', X_test, df_test),]
    exposure = df['Exposure'].values
    res.append(
        {
            "subset": subset_label,
            "observed": df['ClaimAmount'].values.sum(),
            "predicted, frequency+severity model": np.sum(
                exposure * glm_freq.predict(X) * glm_sev.predict(X)
            ),
            "predicted, tweedie, power=\%.2f" % glm_pure_premium.power: np.sum(
                exposure * glm_pure_premium.predict(X),
            ),
        },
    )

(continues on next page)
Finally, we can compare the two models using a plot of cumulated claims: for each model, the policyholders are ranked from safest to riskiest and the fraction of observed total cumulated claims is plotted on the y axis. This plot is often called the ordered Lorenz curve of the model.

The Gini coefficient (based on the area under the curve) can be used as a model selection metric to quantify the ability of the model to rank policyholders. Note that this metric does not reflect the ability of the models to make accurate predictions in terms of absolute value of total claim amounts but only in terms of relative amounts as a ranking metric.

Both models are able to rank policyholders by risky-ness significantly better than chance although they are also both far from perfect due to the natural difficulty of the prediction problem from few features.

Note that the Gini index only characterize the ranking performance of the model but not its calibration: any monotonic transformation of the predictions leaves the Gini index of the model unchanged.

Finally one should highlight that the Compound Poisson Gamma model that is directly fit on the pure premium is operationally simpler to develop and maintain as it consists in a single scikit-learn estimator instead of a pair of models, each with its own set of hyperparameters.

```python
def lorenz_curve(y_true, y_pred, exposure):
    y_true, y_pred = np.asarray(y_true), np.asarray(y_pred)
    exposure = np.asarray(exposure)
    # order samples by increasing predicted risk:
    ranking = np.argsort(y_pred)
    ranked_exposure = exposure[ranking]
    ranked_pure_premium = y_true[ranking]
    cumulated_claim_amount = np.cumsum(ranked_pure_premium * ranked_exposure)
    cumulated_claim_amount /= cumulated_claim_amount[-1]
    cumulated_samples = np.linspace(0, 1, len(cumulated_claim_amount))
    return cumulated_samples, cumulated_claim_amount

fig, ax = plt.subplots(figsize=(8, 8))
y_pred_product = glm_freq.predict(X_test) * glm_sev.predict(X_test)
y_pred_total = glm_pure_premium.predict(X_test)
for label, y_pred in [("Frequency * Severity model", y_pred_product),
                     ("Compound Poisson Gamma", y_pred_total)]:
    ordered_samples, cum_claims = lorenz_curve(
        df_test["PurePremium"], y_pred, df_test["Exposure"],
        gini = 1 - 2 * auc(ordered_samples, cum_claims)
    label += " (Gini index: {:.3f})".format(gini)
    ax.plot(ordered_samples, cum_claims, linestyle="--", label=label)
```

(continues on next page)
### Oracle model: \( y_{\text{pred}} = y_{\text{test}} \)

```python
ordered_samples, cum_claims = lorenz_curve(
    df_test["PurePremium"], df_test["PurePremium"], df_test["Exposure"])
gini = 1 - 2 * auc(ordered_samples, cum_claims)
label = "Oracle (Gini index: {:.3f})".format(gini)
ax.plot(ordered_samples, cum_claims, linestyle="--", color="gray",
        label=label)
```

### Random baseline

```python
ax.plot([0, 1], [0, 1], linestyle="--", color="black",
        label="Random baseline")
ax.set(
    title="Lorenz Curves",
    xlabel=('Fraction of policyholders
     (ordered by model from safest to riskiest)'),
    ylabel='Fraction of total claim amount')
ax.legend(loc="upper left")
plt.plot()
```
Lorenz Curves

- **Frequency * Severity model (Gini index: 0.378)**
- **Compound Poisson Gamma (Gini index: 0.333)**
- **Oracle (Gini index: 0.981)**
- **Random baseline**

Out:

[]

**Total running time of the script:** ( 0 minutes 23.450 seconds)
6.17 Inspection

Examples related to the sklearn.inspection module.

6.17.1 Permutation Importance with Multicollinear or Correlated Features

In this example, we compute the permutation importance on the Wisconsin breast cancer dataset using permutation_importance. The RandomForestClassifier can easily get about 97% accuracy on a test dataset. Because this dataset contains multicollinear features, the permutation importance will show that none of the features are important. One approach to handling multicollinearity is by performing hierarchical clustering on the features’ Spearman rank-order correlations, picking a threshold, and keeping a single feature from each cluster.

Note:  See also Permutation Importance vs Random Forest Feature Importance (MDI)

```python
print(__doc__)
from collections import defaultdict
import matplotlib.pyplot as plt
import numpy as np
from scipy.stats import spearmanr
from scipy.cluster import hierarchy
from sklearn.datasets import load_breast_cancer
from sklearn.ensemble import RandomForestClassifier
from sklearn.inspection import permutation_importance
from sklearn.model_selection import train_test_split

Random Forest Feature Importance on Breast Cancer Data

First, we train a random forest on the breast cancer dataset and evaluate its accuracy on a test set:

data = load_breast_cancer()
X, y = data.data, data.target
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)

clf = RandomForestClassifier(n_estimators=100, random_state=42)
clf.fit(X_train, y_train)
print("Accuracy on test data: {:.2f}".format(clf.score(X_test, y_test)))

Out:
Accuracy on test data: 0.97

Next, we plot the tree based feature importance and the permutation importance. The permutation importance plot shows that permuting a feature drops the accuracy by at most 0.012, which would suggest that none of the features are important. This is in contradiction with the high test accuracy computed above: some feature must be important. The permutation importance is calculated on the training set to show how much the model relies on each feature during training.

result = permutation_importance(clf, X_train, y_train, n_repeats=10,
                                 random_state=42)
perm_sorted_idx = result.importances_mean.argsort()
```

(continues on next page)
```python
tree_importance_sorted_idx = np.argsort(clf.feature_importances_)
tree_indices = np.arange(0, len(clf.feature_importances_)) + 0.5

fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(12, 8))
ax1.barh(tree_indices,
        clf.feature_importances_[tree_importance_sorted_idx], height=0.7)
ax1.set_yticklabels(data.feature_names[tree_importance_sorted_idx])
ax1.set_yticks(tree_indices)
ax1.set_ylim((0, len(clf.feature_importances_)))
ax2.boxplot(result.importances[perm_sorted_idx].T, vert=False,
            labels=data.feature_names[perm_sorted_idx])
fig.tight_layout()
plt.show()
```

Out:

```
/home/circleci/project/examples/inspection/plot_permutation_importance_multicollinear.
ipy:63: UserWarning: FixedFormatter should only be used together with FixedLocator
ax1.set_yticklabels(data.feature_names[tree_importance_sorted_idx])
```
Handling Multicollinear Features

When features are collinear, permuting one feature will have little effect on the models performance because it can get the same information from a correlated feature. One way to handle multicollinear features is by performing hierarchical clustering on the Spearman rank-order correlations, picking a threshold, and keeping a single feature from each cluster. First, we plot a heatmap of the correlated features:

```python
fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(12, 8))
corr = spearmanr(X).correlation
corr_linkage = hierarchy.ward(corr)
dendro = hierarchy.dendrogram(
    corr_linkage, labels=data.feature_names.tolist(), ax=ax1, leaf_rotation=90
)
dendo_idx = np.arange(0, len(dendo['ivl']))

ax2.imshow(corr[dendo['leaves'], :, dendro['leaves']])
ax2.set_xticks(dendo_idx)
ax2.set_yticks(dendo_idx)
ax2.set_xticklabels(dendo['ivl'], rotation='vertical')
ax2.set_yticklabels(dendo['ivl'])
fig.tight_layout()
plt.show()
```

Next, we manually pick a threshold by visual inspection of the dendrogram to group our features into clusters and choose a feature from each cluster to keep, select those features from our dataset, and train a new random forest. The test accuracy of the new random forest did not change much compared to the random forest trained on the complete dataset.
```python
corr linkage = hierarchy.fcluster(corr linkage, 1, criterion='distance')
cor linkage, criterion='distance')
cluster_id_to_feature_ids = defaultdict(list)
for idx, cluster_id in enumerate(cluster_ids):
    cluster_id_to_feature_ids[cluster_id].append(idx)
selected_features = [v[0] for v in cluster_id_to_feature_ids.values()]
X_train_sel = X_train[:, selected_features]
X_test_sel = X_test[:, selected_features]
clf_sel = RandomForestClassifier(n_estimators=100, random_state=42)
clf_sel.fit(X_train_sel, y_train)
print("Accuracy on test data with features removed: {:.2f}".format(
    clf_sel.score(X_test_sel, y_test)))
```

Out:
```
Accuracy on test data with features removed: 0.97
```

**Total running time of the script:** ( 0 minutes 4.622 seconds)

### 6.17.2 Permutation Importance vs Random Forest Feature Importance (MDI)

In this example, we will compare the impurity-based feature importance of `RandomForestClassifier` with the permutation importance on the titanic dataset using `permutation_importance`. We will show that the impurity-based feature importance can inflate the importance of numerical features.

Furthermore, the impurity-based feature importance of random forests suffers from being computed on statistics derived from the training dataset: the importances can be high even for features that are not predictive of the target variable, as long as the model has the capacity to use them to overfit.

This example shows how to use Permutation Importances as an alternative that can mitigate those limitations.

References:

Data Loading and Feature Engineering

Let’s use pandas to load a copy of the titanic dataset. The following shows how to apply separate preprocessing on numerical and categorical features.

We further include two random variables that are not correlated in any way with the target variable (survived):

- **random_num** is a high cardinality numerical variable (as many unique values as records).
- **random_cat** is a low cardinality categorical variable (3 possible values).

```python
X, y = fetch_openml("titanic", version=1, as_frame=True, return_X_y=True)
rng = np.random.RandomState(seed=42)
X['random_cat'] = rng.randint(3, size=X.shape[0])
X['random_num'] = rng.randn(X.shape[0])
categorical_columns = ['pclass', 'sex', 'embarked', 'random_cat']
umerical_columns = ['age', 'sibsp', 'parch', 'fare', 'random_num']
X = X[categorical_columns + numerical_columns]
X_train, X_test, y_train, y_test = train_test_split(X, y, stratify=y, random_state=42)
categorical_encoder = OneHotEncoder(handle_unknown='ignore')
umerical_pipe = Pipeline([('imputer', SimpleImputer(strategy='mean'))])
preprocessing = ColumnTransformer([('cat', categorical_encoder, categorical_columns), ('num', numerical_pipe, numerical_columns)])
rf = Pipeline([('preprocess', preprocessing), ('classifier', RandomForestClassifier(random_state=42))])
rf.fit(X_train, y_train)
```

Accuracy of the Model

Prior to inspecting the feature importances, it is important to check that the model predictive performance is high enough. Indeed there would be little interest of inspecting the important features of a non-predictive model.

Here one can observe that the train accuracy is very high (the forest model has enough capacity to completely memorize the training set) but it can still generalize well enough to the test set thanks to the built-in bagging of random forests.

It might be possible to trade some accuracy on the training set for a slightly better accuracy on the test set by limiting the capacity of the trees (for instance by setting min_samples_leaf=5 or min_samples_leaf=10) so as to limit overfitting while not introducing too much underfitting.

However let’s keep our high capacity random forest model for now so as to illustrate some pitfalls with feature importance on variables with many unique values.

```python
print("RF train accuracy: %.3f" % rf.score(X_train, y_train))
print("RF test accuracy: %.3f" % rf.score(X_test, y_test))
```

Out:
Tree’s Feature Importance from Mean Decrease in Impurity (MDI)

The impurity-based feature importance ranks the numerical features to be the most important features. As a result, the non-predictive `random_num` variable is ranked the most important!

This problem stems from two limitations of impurity-based feature importances:

- impurity-based importances are biased towards high cardinality features;
- impurity-based importances are computed on training set statistics and therefore do not reflect the ability of feature to be useful to make predictions that generalize to the test set (when the model has enough capacity).

```python
ohe = (rf.named_steps['preprocess']
    .named_transformers_['cat'])
feature_names = ohe.get_feature_names(input_features=categorical_columns)
feature_names = np.r_[feature_names, numerical_columns]

tree_feature_importances = (  
    rf.named_steps['classifier'].feature_importances_)
sorted_idx = tree_feature_importances.argsort()

y_ticks = np.arange(0, len(feature_names))
fig, ax = plt.subplots()
ax.barh(y_ticks, tree_feature_importances[sorted_idx])  
ax.set_yticklabels(feature_names[sorted_idx])
ax.set_yticks(y_ticks)
ax.set_title("Random Forest Feature Importances (MDI)")
fig.tight_layout()
plt.show()
```
As an alternative, the permutation importances of \texttt{rf} are computed on a held out test set. This shows that the low cardinality categorical feature, \texttt{sex} is the most important feature.

Also note that both random features have very low importances (close to 0) as expected.

```python
result = permutation_importance(rf, X_test, y_test, n_repeats=10,
                               random_state=42, n_jobs=2)
sorted_idx = result.importances_mean.argsort()
fig, ax = plt.subplots()
ax.boxplot(result.importances[sorted_idx].T,
           vert=False, labels=X_test.columns[sorted_idx])
ax.set_title("Permutation Importances (test set)")
fig.tight_layout()
plt.show()
```
It is also possible to compute the permutation importances on the training set. This reveals that `random_num` gets a significantly higher importance ranking than when computed on the test set. The difference between those two plots is a confirmation that the RF model has enough capacity to use that random numerical feature to overfit. You can further confirm this by re-running this example with constrained RF with `min_samples_leaf=10`.

```python
result = permutation_importance(rf, X_train, y_train, n_repeats=10,
                                random_state=42, n_jobs=2)
sorted_idx = result.importances_mean.argsort()

fig, ax = plt.subplots()
ax.boxplot(result.importances[sorted_idx].T, vert=False, labels=X_train.columns[sorted_idx])
ax.set_title("Permutation Importances (train set)"
fig.tight_layout()
plt.show()
```
Partial dependence plots show the dependence between the target function and a set of features of interest, marginalizing over the values of all other features (the complement features). Due to the limits of human perception, the size of the set of features of interest must be small (usually, one or two) thus they are usually chosen among the most important features.

Similarly, an individual conditional expectation (ICE) plot shows the dependence between the target function and a feature of interest. However, unlike partial dependence plots, which show the average effect of the features of interest, ICE plots visualize the dependence of the prediction on a feature for each sample separately, with one line per sample. Only one feature of interest is supported for ICE plots.

This example shows how to obtain partial dependence and ICE plots from a MLPRegressor and a HistGradientBoostingRegressor trained on the California housing dataset. The example is taken from.

---

2 For classification you can think of it as the regression score before the link function.
California Housing data preprocessing

Center target to avoid gradient boosting init bias: gradient boosting with the ‘recursion’ method does not account for
the initial estimator (here the average target, by default).

```python
import pandas as pd
from sklearn.datasets import fetch_california_housing
from sklearn.model_selection import train_test_split

cal_housing = fetch_california_housing()
X = pd.DataFrame(cal_housing.data, columns=cal_housing.feature_names)
y = cal_housing.target

y -= y.mean()

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.1, random_state=0)
```

1-way partial dependence with different models

In this section, we will compute 1-way partial dependence with two different machine-learning models: (i) a multi-
layer perceptron and (ii) a gradient-boosting. With these two models, we illustrate how to compute and interpret both
partial dependence plot (PDP) and individual conditional expectation (ICE).

Multi-layer perceptron

Let’s fit a `MLPRegressor` and compute single-variable partial dependence plots.

```python
from time import time
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import QuantileTransformer
from sklearn.neural_network import MLPRegressor

print("Training MLPRegressor...")
tic = time()
est = make_pipeline(QuantileTransformer(),
    MLPRegressor(hidden_layer_sizes=(50, 50),
                 learning_rate_init=0.01,
                 early_stopping=True))
est.fit(X_train, y_train)
print(f"done in {time() - tic:.3f}s")
print(f"Test R2 score: {est.score(X_test, y_test):.2f}"
```

Out:

```
Training MLPRegressor...
done in 3.268s
Test R2 score: 0.81
```

We configured a pipeline to scale the numerical input features and tuned the neural network size and learning rate to
get a reasonable compromise between training time and predictive performance on a test set.

Importantly, this tabular dataset has very different dynamic ranges for its features. Neural networks tend to be very
sensitive to features with varying scales and forgetting to preprocess the numeric feature would lead to a very poor
model.
It would be possible to get even higher predictive performance with a larger neural network but the training would also be significantly more expensive.

Note that it is important to check that the model is accurate enough on a test set before plotting the partial dependence since there would be little use in explaining the impact of a given feature on the prediction function of a poor model.

We will plot the partial dependence, both individual (ICE) and averaged one (PDP). We limit to only 50 ICE curves to not overcrowd the plot.

```python
import matplotlib.pyplot as plt
from sklearn.inspection import partial_dependence
from sklearn.inspection import plot_partial_dependence

print('Computing partial dependence plots...')
tic = time()
features = ['MedInc', 'AveOccup', 'HouseAge', 'AveRooms']
display = plot_partial_dependence(
    est, X_train, features, kind="both", subsample=50,
    n_jobs=3, grid_resolution=20, random_state=0
)
display.figure_.suptitle("Partial dependence of house value on non-location features
for the California housing dataset, with MLPRegressor")
display.figure_.subplots_adjust(hspace=0.3)
```

Partial dependence of house value on non-location features for the California housing dataset, with MLPRegressor
Gradient boosting

Let's now fit a `HistGradientBoostingRegressor` and compute the partial dependence on the same features.

```python
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor

print("Training HistGradientBoostingRegressor...")
tic = time()
est = HistGradientBoostingRegressor()
est.fit(X_train, y_train)
print(f"done in {time() - tic:.3f}s")
print(f"Test R2 score: {est.score(X_test, y_test):.2f}")
```

Out:

```
Training HistGradientBoostingRegressor...
done in 0.474s
Test R2 score: 0.85
```

Here, we used the default hyperparameters for the gradient boosting model without any preprocessing as tree-based models are naturally robust to monotonic transformations of numerical features.

Note that on this tabular dataset, Gradient Boosting Machines are both significantly faster to train and more accurate than neural networks. It is also significantly cheaper to tune their hyperparameters (the defaults tend to work well while this is not often the case for neural networks).

We will plot the partial dependence, both individual (ICE) and averaged one (PDP). We limit to only 50 ICE curves to not overcrowd the plot.

```python
print('Computing partial dependence plots...')
tic = time()
display = plot_partial_dependence(
est, X_train, features, kind="both", subsample=50,
n_jobs=3, grid_resolution=20, random_state=0
)
print(f"done in {time() - tic:.3f}s")
display.figure_.suptitle('Partial dependence of house value on non-location features
for the California housing dataset, with Gradient Boosting')
display.figure_.subplots_adjust(wspace=0.4, hspace=0.3)
```

```
Partial dependence plots

Analysis of the plots

We can clearly see on the PDPs (thick blue line) that the median house price shows a linear relationship with the median income (top left) and that the house price drops when the average occupants per household increases (top middle). The top right plot shows that the house age in a district does not have a strong influence on the (median) house price; so does the average rooms per household.

The ICE curves (light blue lines) complement the analysis: we can see that there are some exceptions, where the house price remain constant with median income and average occupants. On the other hand, while the house age (top right) does not have a strong influence on the median house price on average, there seems to be a number of exceptions where the house price increase when between the ages 15-25. Similar exceptions can be observed for the average number of rooms (bottom left). Therefore, ICE plots show some individual effect which are attenuated by taking the averages.

In all plots, the tick marks on the x-axis represent the deciles of the feature values in the training data.

We also observe that `MLPRegressor` has much smoother predictions than `HistGradientBoostingRegressor`.

However, it is worth noting that we are creating potential meaningless synthetic samples if features are correlated.
### 2D interaction plots

PDPs with two features of interest enable us to visualize interactions among them. However, ICEs cannot be plotted in an easy manner and thus interpreted. Another consideration is linked to the performance to compute the PDPs. With the tree-based algorithm, when only PDPs are requested, they can be computed on an efficient way using the 'recursion' method.

```python
features = ['AveOccup', 'HouseAge', ('AveOccup', 'HouseAge')]
print('Computing partial dependence plots...')
tic = time()
_, ax = plt.subplots(ncols=3, figsize=(9, 4))
display = plot_partial_dependence(
    est, X_train, features, kind='average', n_jobs=3, grid_resolution=20,
    ax=ax,
)
print(f"done in {time() - tic:.3f}s")
display.figure_.suptitle('Partial dependence of house value on non-location features
for the California housing dataset, with Gradient Boosting')
display.figure_.subplots_adjust(wspace=0.4, hspace=0.3)
```

Out:

```
Computing partial dependence plots...
done in 0.235s
```

The two-way partial dependence plot shows the dependence of median house price on joint values of house age and average occupants per household. We can clearly see an interaction between the two features: for an average occupancy greater than two, the house price is nearly independent of the house age, whereas for values less than two there is a strong dependence on age.
3D interaction plots

Let’s make the same partial dependence plot for the 2 features interaction, this time in 3 dimensions.

```python
import numpy as np
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()

features = ('AveOccup', 'HouseAge')
pdp = partial_dependence(
    est, X_train, features=features, kind='average', grid_resolution=20
)
XX, YY = np.meshgrid(pdp("values")[0], pdp("values")[1])
Z = pdp.average[0].T
ax = Axes3D(fig)
surf = ax.plot_surface(XX, YY, Z, rstride=1, cstride=1,
cmap=plt.cm.BuPu, edgecolor='k')
ax.set_xlabel(features[0])
ax.set_ylabel(features[1])
ax.set_zlabel('Partial dependence')
# pretty init view
ax.view_init(elev=22, azim=122)
plt.colorbar(surf)
plt.suptitle('Partial dependence of house value on median
age and average occupancy, with Gradient Boosting')
plt.subplots_adjust(top=0.9)
plt.show()
```
6.17.4 Common pitfalls in interpretation of coefficients of linear models

In linear models, the target value is modeled as a linear combination of the features (see the Linear Models User Guide section for a description of a set of linear models available in scikit-learn). Coefficients in multiple linear models represent the relationship between the given feature, $X_i$ and the target, $y$, assuming that all the other features remain constant (conditional dependence). This is different from plotting $X_i$ versus $y$ and fitting a linear relationship: in that case all possible values of the other features are taken into account in the estimation (marginal dependence).

This example will provide some hints in interpreting coefficient in linear models, pointing at problems that arise when either the linear model is not appropriate to describe the dataset, or when features are correlated.

We will use data from the “Current Population Survey” from 1985 to predict wage as a function of various features such as experience, age, or education.

- The dataset: wages
- The machine-learning pipeline
- Processing the dataset
- Interpreting coefficients: scale matters
- Checking the variability of the coefficients
print(__doc__)

import numpy as np
import scipy as sp
import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns

The dataset: wages

We fetch the data from OpenML. Note that setting the parameter as_frame to True will retrieve the data as a pandas dataframe.

from sklearn.datasets import fetch_openml
survey = fetch_openml(data_id=534, as_frame=True)

Then, we identify features $X$ and targets $y$: the column W AGE is our target variable (i.e., the variable which we want to predict).

$X = survey.data[survey.feature_names]$  
$X.describe(include="all")$

Note that the dataset contains categorical and numerical variables. We will need to take this into account when preprocessing the dataset thereafter.

$X.head()$

Our target for prediction: the wage. Wages are described as floating-point number in dollars per hour.

$y = survey.target.values.ravel()$  
survey.target.head()

Out:

<p>| | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>5.10</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>4.95</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>6.67</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>4.00</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>7.50</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Name: WAGE, dtype: float64

We split the sample into a train and a test dataset. Only the train dataset will be used in the following exploratory analysis. This is a way to emulate a real situation where predictions are performed on an unknown target, and we don’t want our analysis and decisions to be biased by our knowledge of the test data.

6.17. Inspection
First, let's get some insights by looking at the variable distributions and at the pairwise relationships between them. Only numerical variables will be used. In the following plot, each dot represents a sample.
Looking closely at the WAGE distribution reveals that it has a long tail. For this reason, we should take its logarithm to turn it approximately into a normal distribution (linear models such as ridge or lasso work best for a normal distribution of error).

The WAGE is increasing when EDUCATION is increasing. Note that the dependence between WAGE and EDUCATION represented here is a marginal dependence, i.e., it describes the behavior of a specific variable without keeping the others fixed.

Also, the EXPERIENCE and AGE are strongly linearly correlated.

**The machine-learning pipeline**

To design our machine-learning pipeline, we first manually check the type of data that we are dealing with:

```python
survey.data.info()
```

Out:

```
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 534 entries, 0 to 533
Data columns (total 10 columns):
    # Column     Non-Null Count   Dtype 
    --- -------- -------------- ----- 
   0 EDUCATION  534 non-null    float64
   1 SOUTH     534 non-null    category
   2 SEX       534 non-null    category
   3 EXPERIENCE 534 non-null    float64
   4 UNION     534 non-null    category
   5 AGE       534 non-null    float64
   6 RACE      534 non-null    category
   7 OCCUPATION 534 non-null    category
   8 SECTOR    534 non-null    category
   9 MARR      534 non-null    category
dtypes: category(7), float64(3)
memory usage: 17.1 KB
```

As seen previously, the dataset contains columns with different data types and we need to apply a specific preprocessing for each data types. In particular categorical variables cannot be included in linear model if not coded as integers first. In addition, to avoid categorical features to be treated as ordered values, we need to one-hot-encode them. Our preprocessor will

- one-hot encode (i.e., generate a column by category) the categorical columns;
- as a first approach (we will see after how the normalisation of numerical values will affect our discussion), keep numerical values as they are.

```python
from sklearn.compose import make_column_transformer
from sklearn.preprocessing import OneHotEncoder

categorical_columns = ['RACE', 'OCCUPATION', 'SECTOR',
                       'MARR', 'UNION', 'SEX', 'SOUTH']
numerical_columns = ['EDUCATION', 'EXPERIENCE', 'AGE']

preprocessor = make_column_transformer(
    (OneHotEncoder(drop='if_binary'), categorical_columns),
    remainder='passthrough'
)
```
scikit-learn user guide, Release 0.24.0

To describe the dataset as a linear model we use a ridge regressor with a very small regularization and to model the
logarithm of the WAGE.
from sklearn.pipeline import make_pipeline
from sklearn.linear_model import Ridge
from sklearn.compose import TransformedTargetRegressor
model = make_pipeline(
preprocessor,
TransformedTargetRegressor(
regressor=Ridge(alpha=1e-10),
func=np.log10,
inverse_func=sp.special.exp10
)
)

Processing the dataset
First, we fit the model.
_ = model.fit(X_train, y_train)

Then we check the performance of the computed model plotting its predictions on the test set and computing, for
example, the median absolute error of the model.
from sklearn.metrics import median_absolute_error
y_pred = model.predict(X_train)
mae = median_absolute_error(y_train, y_pred)
string_score = f'MAE on training set: {mae:.2f} $/hour'
y_pred = model.predict(X_test)
mae = median_absolute_error(y_test, y_pred)
string_score += f'\nMAE on testing set: {mae:.2f} $/hour'
fig, ax = plt.subplots(figsize=(5, 5))
plt.scatter(y_test, y_pred)
ax.plot([0, 1], [0, 1], transform=ax.transAxes, ls="--", c="red")
plt.text(3, 20, string_score)
plt.title('Ridge model, small regularization')
plt.ylabel('Model predictions')
plt.xlabel('Truths')
plt.xlim([0, 27])
_ = plt.ylim([0, 27])

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Chapter 6. Examples


The model learnt is far from being a good model making accurate predictions: this is obvious when looking at the plot above, where good predictions should lie on the red line.

In the following section, we will interpret the coefficients of the model. While we do so, we should keep in mind that any conclusion we draw is about the model that we build, rather than about the true (real-world) generative process of the data.

**Interpreting coefficients: scale matters**

First of all, we can take a look to the values of the coefficients of the regressor we have fitted.

```python
feature_names = (model.named_steps['columntransformer']
    .named_transformers_['onehotencoder']
    .get_feature_names(input_features=categorical_columns))
feature_names = np.concatenate([feature_names, numerical_columns])
coefs = pd.DataFrame(
    model.named_steps['transformedtargetregressor'].regressor_.coef_,
    columns=['Coefficients'], index=feature_names)
coefs
```

6.17. Inspection
The AGE coefficient is expressed in “dollars/hour per living years” while the EDUCATION one is expressed in “dollars/hour per years of education”. This representation of the coefficients has the benefit of making clear the practical predictions of the model: an increase of 1 year in AGE means a decrease of 0.030867 dollars/hour, while an increase of 1 year in EDUCATION means an increase of 0.054699 dollars/hour. On the other hand, categorical variables (as UNION or SEX) are adimensional numbers taking either the value 0 or 1. Their coefficients are expressed in dollars/hour. Then, we cannot compare the magnitude of different coefficients since the features have different natural scales, and hence value ranges, because of their different unit of measure. This is more visible if we plot the coefficients.

```python
coefs.plot(kind='barh', figsize=(9, 7))
plt.title('Ridge model, small regularization')
plt.axvline(x=0, color='.5')
plt.subplots_adjust(left=.3)
```

Indeed, from the plot above the most important factor in determining WAGE appears to be the variable UNION, even if our intuition might tell us that variables like EXPERIENCE should have more impact.

Looking at the coefficient plot to gauge feature importance can be misleading as some of them vary on a small scale, while others, like AGE, varies a lot more, several decades.

This is visible if we compare the standard deviations of different features.

```python
X_train_preprocessed = pd.DataFrame(
    model.named_steps['columntransformer'].transform(X_train),
)```
Multiplying the coefficients by the standard deviation of the related feature would reduce all the coefficients to the same unit of measure. As we will see after this is equivalent to normalize numerical variables to their standard deviation, as $y = \sum coef_i \times X_i = \sum (coef_i \times std_i) \times (X_i/std_i)$.

In that way, we emphasize that the greater the variance of a feature, the larger the weight of the corresponding coefficient on the output, all else being equal.

```python
coefs = pd.DataFrame(
    model.named_steps['transformedtargetregressor'].regressor_.coef_ * 
    X_train_preprocessed.std(axis=0),
    columns=['Coefficient importance'], index=feature_names
)
coefs.plot(kind='barh', figsize=(9, 7))
plt.axvline(x=0, color='.5')
plt.subplots_adjust(left=.3)
```
Now that the coefficients have been scaled, we can safely compare them.

**Warning:** Why does the plot above suggest that an increase in age leads to a decrease in wage? Why the *initial* pairplot is telling the opposite?

The plot above tells us about dependencies between a specific feature and the target when all other features remain constant, i.e., conditional dependencies. An increase of the AGE will induce a decrease of the WAGE when all other features remain constant. On the contrary, an increase of the EXPERIENCE will induce an increase of the WAGE when all other features remain constant. Also, AGE, EXPERIENCE and EDUCATION are the three variables that most influence the model.
Checking the variability of the coefficients

We can check the coefficient variability through cross-validation: it is a form of data perturbation (related to resampling).

If coefficients vary significantly when changing the input dataset their robustness is not guaranteed, and they should probably be interpreted with caution.

```python
from sklearn.model_selection import cross_validate
from sklearn.model_selection import RepeatedKFold

cv_model = cross_validate(
    model, X, y, cv=RepeatedKFold(n_splits=5, n_repeats=5),
    return_estimator=True, n_jobs=-1
)
coefs = pd.DataFrame(
    [est.named_steps['transformedtargetregressor'].regressor_.coef_ *
     X_train_preprocessed.std(axis=0)
     for est in cv_model['estimator']],[
    columns=feature_names
)
plt.figure(figsize=(9, 7))
sns.swarmplot(data=coefs, orient='h', color='k', alpha=0.5)
sns.boxplot(data=coefs, orient='h', color='cyan', saturation=0.5)
plt.axvline(x=0, color='.5')
plt.xlabel('Coefficient importance')
plt.title('Coefficient importance and its variability')
plt.subplots_adjust(left=.3)
```
Out:

/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 88.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 76.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 68.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 72.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 80.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
    py:1296: UserWarning: 64.0% of the points cannot be placed; you may want to
decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
(continues on next page)
The problem of correlated variables

The AGE and EXPERIENCE coefficients are affected by strong variability which might be due to the collinearity between the 2 features: as AGE and EXPERIENCE vary together in the data, their effect is difficult to tease apart.

To verify this interpretation we plot the variability of the AGE and EXPERIENCE coefficient.

```python
plt.ylabel('Age coefficient')
plt.xlabel('Experience coefficient')
plt.grid(True)
plt.xlim(-0.4, 0.5)
plt.ylim(-0.4, 0.5)
plt.scatter(coefs["AGE"], coefs["EXPERIENCE"])
_ = plt.title('Co-variations of coefficients for AGE and EXPERIENCE ' 'across folds')
```
Two regions are populated: when the EXPERIENCE coefficient is positive the AGE one is negative and vice versa.

To go further we remove one of the 2 features and check what is the impact on the model stability.

```python
column_to_drop = ['AGE']

cv_model = cross_validate(
    model, X.drop(columns=column_to_drop), y,
    cv=RepeatedKFold(n_splits=5, n_repeats=5),
    return_estimator=True, n_jobs=-1
)

coops = pd.DataFrame(
    [est.named_steps['transformedtargetregressor'].regressor_.coef_ * X_train_preprocessed.drop(columns=column_to_drop).std(axis=0)
     for est in cv_model['estimator']],
    columns=feature_names[:-1]
)

t.figure(figsize=(9, 7))
sns.swarmplot(data=coops, orient='h', color='k', alpha=0.5)
sns.boxplot(data=coops, orient='h', color='cyan', saturation=0.5)
t.axvline(x=0, color='.5')
t.title('Coefficient importance and its variability')
t.xlabel('Coefficient importance')
t.subplots_adjust(left=.3)
```
Out:

/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 40.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 28.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 48.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 36.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 20.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.py:1296: UserWarning: 8.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
  warnings.warn(msg, UserWarning)

(continues on next page)
The estimation of the EXPERIENCE coefficient is now less variable and remain important for all models trained during cross-validation.

Preprocessing numerical variables

As said above (see “The machine-learning pipeline”), we could also choose to scale numerical values before training the model. This can be useful to apply a similar amount regularization to all of them in the Ridge. The preprocessor is redefined in order to subtract the mean and scale variables to unit variance.

```python
from sklearn.preprocessing import StandardScaler
preprocessor = make_column_transformer(
    (OneHotEncoder(drop='if_binary'), categorical_columns),
    (StandardScaler(), numerical_columns),
    remainder='passthrough'
)
```

The model will stay unchanged.

```python
model = make_pipeline(
    preprocessor,
    TransformedTargetRegressor(
        regressor=Ridge(alpha=1e-10),
        func=np.log10,
        inverse_func=sp.special.exp10
    )
)
_ = model.fit(X_train, y_train)
```

Again, we check the performance of the computed model using, for example, the median absolute error of the model and the R squared coefficient.

```python
y_pred = model.predict(X_train)
mae = median_absolute_error(y_train, y_pred)
string_score = f'MAE on training set: \$\{mae:.2f\}/hour'
y_pred = model.predict(X_test)
mae = median_absolute_error(y_test, y_pred)
string_score += f'MAE on testing set: \$\{mae:.2f\}/hour'
fig, ax = plt.subplots(figsize=(6, 6))
plt.scatter(y_test, y_pred)
```

(continues on next page)
ax.plot([0, 1], [0, 1], transform=ax.transAxes, ls="--", c="red")
plt.text(3, 20, string_score)
plt.title('Ridge model, small regularization, normalized variables')
plt.ylabel('Model predictions')
plt.xlabel('Truths')
plt.xlim([0, 27])
_ = plt.ylim([0, 27])

For the coefficient analysis, scaling is not needed this time.

coefs = pd.DataFrame(
    model.named_steps['transformedtargetregressor'].regressor_.coef_,
    columns=['Coefficients'], index=feature_names
)
We now inspect the coefficients across several cross-validation folds.

cv_model = cross_validate(  
    model, X, y, cv=RepeatedKFold(n_splits=5, n_repeats=5),  
    return_estimator=True, n_jobs=-1  
)
coefs = pd.DataFrame(  
    [est.named_steps['transformedtargetregressor'].regressor_.coef_  
     for est in cv_model['estimator']],  
    columns=feature_names  
)
plt.figure(figsize=(9, 7))
sns.swarmplot(data=coefs, orient='h', color='k', alpha=0.5)
sns.boxplot(data=coefs, orient='h', color='cyan', saturation=0.5)
plt.axvline(x=0, color='.5')
plt.title('Coefficient variability')
plt.subplots_adjust(left=.3)
Out:

/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 40.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 48.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 64.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 44.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 52.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)
/home/circleci/miniconda/envs/testenv/lib/python3.9/site-packages/seaborn/categorical.
  → py:1296: UserWarning: 56.0% of the points cannot be placed; you may want to decrease the size of the markers or use stripplot.
    warnings.warn(msg, UserWarning)

(continues on next page)
The result is quite similar to the non-normalized case.

**Linear models with regularization**

In machine-learning practice, Ridge Regression is more often used with non-negligible regularization.

Above, we limited this regularization to a very little amount. Regularization improves the conditioning of the problem and reduces the variance of the estimates. RidgeCV applies cross validation in order to determine which value of the regularization parameter ($\alpha$) is best suited for prediction.

```python
from sklearn.linear_model import RidgeCV
model = make_pipeline(
    preprocessor,
    TransformedTargetRegressor(
        regressor=RidgeCV(alphas=np.logspace(-10, 10, 21)),
        func=np.log10,
        inverse_func=sp.special.exp10
    )
)
_ = model.fit(X_train, y_train)
```

First we check which value of $\alpha$ has been selected.

```python
model[-1].regressor_.alpha_
```

Out:

```
10.0
```

Then we check the quality of the predictions.

```python
y_pred = model.predict(X_train)
mae = median_absolute_error(y_train, y_pred)
string_score = f'\nMAE on training set: \n{mae:.2f} \$/hour''
```

(continues on next page)
The ability to reproduce the data of the regularized model is similar to the one of the non-regularized model.

```python
coefs = pd.DataFrame(
    model.named_steps['transformedtargetregressor'].regressor_.coef_,
    columns=['Coefficients'], index=feature_names
)"
The coefficients are significantly different. AGE and EXPERIENCE coefficients are both positive but they now have less influence on the prediction.

The regularization reduces the influence of correlated variables on the model because the weight is shared between the two predictive variables, so neither alone would have strong weights.

On the other hand, the weights obtained with regularization are more stable (see the Ridge regression and classification User Guide section). This increased stability is visible from the plot, obtained from data perturbations, in a cross validation. This plot can be compared with the previous one.

```python
cv_model = cross_validate(
    model, X, y, cv=RepeatedKFold(n_splits=5, n_repeats=5),
    return_estimator=True, n_jobs=-1
)
coefs = pd.DataFrame(
    [est.named_steps['transformedtargetregressor'].regressor_.coef_ *
    X_train_preprocessed.std(axis=0)
    for est in cv_model['estimators']]
)
```
for est in cv_model['estimator'],
columns=feature_names)
plt.ylabel('Age coefficient')
plt.xlabel('Experience coefficient')
plt.grid(True)
plt.xlim(-0.4, 0.5)
plt.ylim(-0.4, 0.5)
plt.scatter(coefs['AGE'], coefs['EXPERIENCE'])
_ = plt.title('Co-variations of coefficients for AGE and EXPERIENCE ' 'across folds')

### Linear models with sparse coefficients

Another possibility to take into account correlated variables in the dataset, is to estimate sparse coefficients. In some way we already did it manually when we dropped the AGE column in a previous Ridge estimation.

Lasso models (see the Lasso User Guide section) estimates sparse coefficients. LassoCV applies cross validation in order to determine which value of the regularization parameter (alpha) is best suited for the model estimation.

```python
from sklearn.linear_model import LassoCV
```
scikit-learn user guide, Release 0.24.0

(continued from previous page)

model = make_pipeline(
preprocessor,
TransformedTargetRegressor(
regressor=LassoCV(alphas=np.logspace(-10, 10, 21), max_iter=100000),
func=np.log10,
inverse_func=sp.special.exp10
)
)
_ = model.fit(X_train, y_train)

First we verify which value of 𝛼 has been selected.
model[-1].regressor_.alpha_

Out:
0.001

Then we check the quality of the predictions.
y_pred = model.predict(X_train)
mae = median_absolute_error(y_train, y_pred)
string_score = f'MAE on training set: {mae:.2f} $/hour'
y_pred = model.predict(X_test)
mae = median_absolute_error(y_test, y_pred)
string_score += f'\nMAE on testing set: {mae:.2f} $/hour'
fig, ax = plt.subplots(figsize=(6, 6))
plt.scatter(y_test, y_pred)
ax.plot([0, 1], [0, 1], transform=ax.transAxes, ls="--", c="red")
plt.text(3, 20, string_score)
plt.title('Lasso model, regularization, normalized variables')
plt.ylabel('Model predictions')
plt.xlabel('Truths')
plt.xlim([0, 27])
_ = plt.ylim([0, 27])

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For our dataset, again the model is not very predictive.

```python
coops = pd.DataFrame(
    model.named_steps['transformedtargetregressor'].regressor_.coef_,
    columns=['Coefficients'], index=feature_names
)
coops.plot(kind='barh', figsize=(9, 7))
plt.title('Lasso model, regularization, normalized variables')
plt.axvline(x=0, color='.5')
plt.subplots_adjust(left=.3)
```
A Lasso model identifies the correlation between AGE and EXPERIENCE and suppresses one of them for the sake of the prediction.

It is important to keep in mind that the coefficients that have been dropped may still be related to the outcome by themselves: the model chose to suppress them because they bring little or no additional information on top of the other features. Additionally, this selection is unstable for correlated features, and should be interpreted with caution.

**Lessons learned**

- Coefficients must be scaled to the same unit of measure to retrieve feature importance. Scaling them with the standard-deviation of the feature is a useful proxy.

- Coefficients in multivariate linear models represent the dependency between a given feature and the target, **conditional** on the other features.

- Correlated features induce instabilities in the coefficients of linear models and their effects cannot be well teased apart.

- Different linear models respond differently to feature correlation and coefficients could significantly vary from one another.

- Inspecting coefficients across the folds of a cross-validation loop gives an idea of their stability.

**Total running time of the script:** (0 minutes 10.709 seconds)
6.18 Kernel Approximation

Examples concerning the `sklearn.kernel_approximation` module.

6.18.1 Scalable learning with polynomial kernel approximation

This example illustrates the use of `PolynomialCountSketch` to efficiently generate polynomial kernel feature-space approximations. This is used to train linear classifiers that approximate the accuracy of kernelized ones.

We use the Covtype dataset [2], trying to reproduce the experiments on the original paper of Tensor Sketch [1], i.e. the algorithm implemented by `PolynomialCountSketch`.

First, we compute the accuracy of a linear classifier on the original features. Then, we train linear classifiers on different numbers of features (`n_components`) generated by `PolynomialCountSketch`, approximating the accuracy of a kernelized classifier in a scalable manner.

```python
print(__doc__)

# Author: Daniel Lopez-Sanchez <lope@usal.es>
# License: BSD 3 clause
import matplotlib.pyplot as plt
from sklearn.datasets import fetch_covtype
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import MinMaxScaler, Normalizer
from sklearn.svm import LinearSVC
from sklearn.kernel_approximation import PolynomialCountSketch
from sklearn.pipeline import Pipeline, make_pipeline
import time

Load the Covtype dataset, which contains 581,012 samples with 54 features each, distributed among 6 classes. The goal of this dataset is to predict forest cover type from cartographic variables only (no remotely sensed data). After loading, we transform it into a binary classification problem to match the version of the dataset in the LIBSVM webpage [2], which was the one used in [1].

```python
X, y = fetch_covtype(return_X_y=True)
y[y != 2] = 0
y[y == 2] = 1  # We will try to separate class 2 from the other 6 classes.
```

Here we select 5,000 samples for training and 10,000 for testing. To actually reproduce the results in the original Tensor Sketch paper, select 100,000 for training.

```python
X_train, X_test, y_train, y_test = train_test_split(X, y, train_size=5_000,
                                                   test_size=10_000,
                                                   random_state=42)
```

Now scale features to the range [0, 1] to match the format of the dataset in the LIBSVM webpage, and then normalize to unit length as done in the original Tensor Sketch paper [1].

```python
mm = make_pipeline(MinMaxScaler(), Normalizer())
X_train = mm.fit_transform(X_train)
X_test = mm.transform(X_test)
```

As a baseline, train a linear SVM on the original features and print the accuracy. We also measure and store accuracies and training times to plot them later.
Then we train linear SVMs on the features generated by `PolynomialCountSketch` with different values for \( n_{\text{components}} \), showing that these kernel feature approximations improve the accuracy of linear classification. In typical application scenarios, \( n_{\text{components}} \) should be larger than the number of features in the input representation in order to achieve an improvement with respect to linear classification. As a rule of thumb, the optimum of evaluation score / run time cost is typically achieved at around \( n_{\text{components}} = 10 \times n_{\text{features}} \), though this might depend on the specific dataset being handled. Note that, since the original samples have 54 features, the explicit feature map of the polynomial kernel of degree four would have approximately 8.5 million features (precisely, \( 54^4 \)). Thanks to `PolynomialCountSketch`, we can condense most of the discriminative information of that feature space into a much more compact representation. We repeat the experiment 5 times to compensate for the stochastic nature of `PolynomialCountSketch`.

```python
n_runs = 5
for n_components in [250, 500, 1000, 2000]:
    ps_lsvm_time = 0
    ps_lsvm_score = 0
    for _ in range(n_runs):
        pipeline = Pipeline(steps=[
            ("kernel_approximator",
             PolynomialCountSketch(
                 n_components=n_components,
                 degree=4)),
            ("linear_classifier", LinearSVC())
        ])
        start = time.time()
        pipeline.fit(X_train, y_train)
        ps_lsvm_time += time.time() - start
        ps_lsvm_score += 100 * pipeline.score(X_test, y_test)
    ps_lsvm_time /= n_runs
    ps_lsvm_score /= n_runs
    results[f"LSVM + PS({n_components})"] = {
        "time": ps_lsvm_time, "score": ps_lsvm_score
    }
    print(f"Linear SVM score on {n_components} PolynomialCountSketch features: {ps_lsvm_score:.2f}%")
```

Out:

```
Linear SVM score on 250 PolynomialCountSketch features: 76.43%
```
Linear SVM score on 500 PolynomialCountSketch features: 77.15%
Linear SVM score on 1000 PolynomialCountSketch features: 77.97%
Linear SVM score on 2000 PolynomialCountSketch features: 78.18%

Train a kernelized SVM to see how well `PolynomialCountSketch` is approximating the performance of the kernel. This, of course, may take some time, as the SVC class has a relatively poor scalability. This is the reason why kernel approximators are so useful:

```python
from sklearn.svm import SVC

ksvm = SVC(C=500., kernel="poly", degree=4, coef0=0, gamma=1.)

start = time.time()
ksvm.fit(X_train, y_train)
ksvm_time = time.time() - start
ksvm_score = 100 * ksvm.score(X_test, y_test)

results["KSVM"] = ("time": ksvm_time, "score": ksvm_score)
print(f"Kernel-SVM score on raw features: {ksvm_score:.2f}%")
```

Out:

```
Kernel-SVM score on raw features: 79.77%
```

Finally, plot the results of the different methods against their training times. As we can see, the kernelized SVM achieves a higher accuracy, but its training time is much larger and, most importantly, will grow much faster if the number of training samples increases.

```python
N_COMPONENTS = [250, 500, 1000, 2000]

fig, ax = plt.subplots(figsize=(7, 7))
ax.scatter([results["LSVM"]['time']], [results["LSVM"]['score']], label="Linear SVM", c="green", marker="^")
ax.scatter([results["LSVM + PS(250)"]['time']], [results["LSVM + PS(250)"]['score']], label="Linear SVM + PolynomialCountSketch", c="blue")
for n_components in N_COMPONENTS:
    ax.scatter([results[f"LSVM + PS({n_components})"]['time']], [results[f"LSVM + PS({n_components})"]['score']], c="blue")
    ax.annotate(f"n_comp.={n_components}", (results[f"LSVM + PS({n_components})"]['time'], results[f"LSVM + PS({n_components})"]['score']), xytext=(-30, 10), textcoords="offset pixels")
ax.scatter([results["KSVM"]['time']], [results["KSVM"]['score']], label="Kernel SVM", c="red", marker="x")

ax.set_xlabel("Training time (s)")
ax.set_ylabel("Accuracy (%)")
ax.legend()
plt.show()
```
References


Total running time of the script: ( 1 minutes 44.211 seconds)
6.19 Manifold learning

Examples concerning the `sklearn.manifold` module.

6.19.1 Swiss Roll reduction with LLE

An illustration of Swiss Roll reduction with locally linear embedding

Out:

```
Computing LLE embedding
Done. Reconstruction error: 1.26177e-07
```

```
# Author: Fabian Pedregosa -- <fabian.pedregosa@inria.fr>
# License: BSD 3 clause (C) INRIA 2011

print(__doc__)
```

(continues on next page)
import matplotlib.pyplot as plt

# This import is needed to modify the way figure behaves
from mpl_toolkits.mplot3d import Axes3D

# Locally linear embedding of the swiss roll
from sklearn import manifold, datasets
X, color = datasets.make_swiss_roll(n_samples=1500)

print("Computing LLE embedding")
X_r, err = manifold.locally_linear_embedding(X, n_neighbors=12,
                                          n_components=2)
print("Done. Reconstruction error: $g" % err)

# Plot result
fig = plt.figure()
ax = fig.add_subplot(211, projection='3d')
av.scatter(X[:, 0], X[:, 1], X[:, 2], c=color, cmap=plt.cm.Spectral)
ax.set_title("Original data")
ax = fig.add_subplot(212)
av.scatter(X_r[:, 0], X_r[:, 1], c=color, cmap=plt.cm.Spectral)
plt.axis('tight')
plt.xticks([]), plt.yticks([])
plt.title("Projected data")
plt.show()

Total running time of the script: ( 0 minutes 0.280 seconds)

6.19.2 Comparison of Manifold Learning methods

An illustration of dimensionality reduction on the S-curve dataset with various manifold learning methods.

For a discussion and comparison of these algorithms, see the manifold module page

For a similar example, where the methods are applied to a sphere dataset, see Manifold Learning methods on a severed sphere

Note that the purpose of the MDS is to find a low-dimensional representation of the data (here 2D) in which the distances respect well the distances in the original high-dimensional space, unlike other manifold-learning algorithms, it does not seeks an isotropic representation of the data in the low-dimensional space.
Manifold Learning with 1000 points, 10 neighbors

Out:

/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_neighbors=10, n_components=2 as keyword args. From version 1.0 (renaming of 0.25) passing these as positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version "
LLE: 0.085 sec
LTSA: 0.12 sec
Hessian LLE: 0.3 sec
Modified LLE: 0.22 sec
Isomap: 0.5 sec
MDS: 2 sec
SE: 0.064 sec
t-SNE: 7.1 sec

# Author: Jake Vanderplas -- <vanderplas@astro.washington.edu>

print(__doc__)

from collections import OrderedDict
from functools import partial
from time import time

import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from matplotlib.ticker import NullFormatter
from sklearn import manifold, datasets

(continues on next page)
Axes3D
n_points = 1000
X, color = datasets.make_s_curve(n_points, random_state=0)
n_neighbors = 10
n_components = 2

Create figure
fig = plt.figure(figsize=(15, 8))
fig.suptitle("Manifold Learning with %i points, %i neighbors" % (1000, n_neighbors), fontsize=14)

Add 3d scatter plot
ax = fig.add_subplot(251, projection='3d')
ax.scatter(X[:, 0], X[:, 1], X[:, 2], c=color, cmap=plt.cm.Spectral)
ax.view_init(4, -72)

Set-up manifold methods
LLE = partial(manifold.LocallyLinearEmbedding,
               n_neighbors, n_components, eigen_solver='auto')
methods = OrderedDict()
methods['LLE'] = LLE(method='standard')
methods['LTSA'] = LLE(method='ltsa')
methods['Hessian LLE'] = LLE(method='hessian')
methods['Modified LLE'] = LLE(method='modified')
methods['Isomap'] = manifold.Isomap(n_neighbors, n_components)
methods['MDS'] = manifold.MDS(n_components, max_iter=100, n_init=1)
methods['SE'] = manifold.SpectralEmbedding(n_components=n_components,
                                          n_neighbors=n_neighbors)
methods['t-SNE'] = manifold.TSNE(n_components=n_components, init='pca',
                                  random_state=0)

Plot results
for i, (label, method) in enumerate(methods.items()):
    t0 = time()
    Y = method.fit_transform(X)
    t1 = time()
    print("%s: %.2g sec" % (label, t1 - t0))
    ax = fig.add_subplot(25, 2, 2 + i)
    ax.scatter(Y[:, 0], Y[:, 1], c=color, cmap=plt.cm.Spectral)
    ax.axis('tight')
plt.show()
6.19.3 Multi-dimensional scaling

An illustration of the metric and non-metric MDS on generated noisy data.
The reconstructed points using the metric MDS and non metric MDS are slightly shifted to avoid overlapping.

# Author: Nelle Varoquaux <nelle.varoquaux@gmail.com>
# License: BSD

print(__doc__)
import numpy as np
from matplotlib import pyplot as plt
from matplotlib.collections import LineCollection
from sklearn import manifold
from sklearn.metrics import euclidean_distances
from sklearn.decomposition import PCA

EPSILON = np.finfo(np.float32).eps
n_samples = 20
seed = np.random.RandomState(seed=3)
X_true = seed.randint(0, 20, 2 * n_samples).astype(float)
X_true = X_true.reshape((n_samples, 2))
# Center the data
X_true -= X_true.mean()
similarities = euclidean_distances(X_true)

# Add noise to the similarities
noise = np.random.rand(n_samples, n_samples)
noise = noise + noise.T
noise[np.arange(noise.shape[0]), np.arange(noise.shape[0])] = 0
similarities += noise

mds = manifold.MDS(n_components=2, max_iter=3000, eps=1e-9, random_state=seed,
                   dissimilarity="precomputed", n_jobs=1)
pos = mds.fit(similarities).embedding_

nmds = manifold.MDS(n_components=2, metric=False, max_iter=3000, eps=1e-12,
                     dissimilarity="precomputed", random_state=seed, n_jobs=1,
                     n_init=1)
npos = nmds.fit_transform(similarities, init=pos)

# Rescale the data
pos *= np.sqrt((X_true ** 2).sum()) / np.sqrt((pos ** 2).sum())
npos *= np.sqrt((X_true ** 2).sum()) / np.sqrt((npos ** 2).sum())

# Rotate the data
clf = PCA(n_components=2)
X_true = clf.fit_transform(X_true)
pos = clf.fit_transform(pos)
npos = clf.fit_transform(npos)

fig = plt.figure(1)
ax = plt.axes([0., 0., 1., 1.])
s = 100
plt.scatter(X_true[:, 0], X_true[:, 1], color='navy', s=s, lw=0,
            label='True Position')
plt.scatter(pos[:, 0], pos[:, 1], color='turquoise', s=s, lw=0, label='MDS')
plt.scatter(npos[:, 0], npos[:, 1], color='darkorange', s=s, lw=0, label='NMDS')
plt.legend(scatterpoints=1, loc='best', shadow=False)

similarities = similarities.max() / (similarities + EPSILON) * 100
np.fill_diagonal(similarities, 0)

# Plot the edges
start_idx, end_idx = np.where(pos)
segments = [[X_true[i, :], X_true[j, :]]
            for i in range(len(pos)) for j in range(len(pos))]
values = np.abs(similarities)
lc = LineCollection(segments,
                    zorder=0, cmap=plt.cm.Blues,
                    norm=plt.Normalize(0, values.max()))
lc.set_array(similarities.flatten())
lc.set_linewidths(np.full(len(segments), 0.5))
ax.add_collection(lc)

plt.show()
6.19.4 t-SNE: The effect of various perplexity values on the shape

An illustration of t-SNE on the two concentric circles and the S-curve datasets for different perplexity values.

We observe a tendency towards clearer shapes as the perplexity value increases.

The size, the distance and the shape of clusters may vary upon initialization, perplexity values and does not always convey a meaning.

As shown below, t-SNE for higher perplexities finds meaningful topology of two concentric circles, however the size and the distance of the circles varies slightly from the original. Contrary to the two circles dataset, the shapes visually diverge from S-curve topology on the S-curve dataset even for larger perplexity values.

For further details, “How to Use t-SNE Effectively” https://distill.pub/2016/misread-tsne/ provides a good discussion of the effects of various parameters, as well as interactive plots to explore those effects.
# Author: Narine Kokhlikyan <narine@slice.com>
# License: BSD

print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.ticker import NullFormatter
from sklearn import manifold, datasets
from time import time

n_samples = 300
n_components = 2
(fig, subplots) = plt.subplots(3, 5, figsize=(15, 8))
perplexities = [5, 30, 50, 100]

X, y = datasets.make_circles(n_samples=n_samples, factor=.5, noise=.05)
red = y == 0
green = y == 1
ax = subplots[0][0]
ax.scatter(X[red, 0], X[red, 1], c="r")
an.scatter(X[green, 0], X[green, 1], c="g")
ax.xaxis.set_major_formatter(NullFormatter())
am.yaxis.set_major_formatter(NullFormatter())
plt.axis('tight')
for i, perplexity in enumerate(perplexities):
    ax = subplots[0][i + 1]
    t0 = time()
    tsne = manifold.TSNE(n_components=n_components, init='random',
                         random_state=0, perplexity=perplexity)
    Y = tsne.fit_transform(X)
t1 = time()
    print("circles, perplexity=%d in %.2g sec" % (perplexity, t1 - t0))
    ax.set_title("Perplexity=%d % perplexity")
    ax.scatter(Y[red, 0], Y[red, 1], c="r")
an.scatter(Y[green, 0], Y[green, 1], c="g")
an.xaxis.set_major_formatter(NullFormatter())
am.yaxis.set_major_formatter(NullFormatter())
an.axis('tight')

# Another example using s-curve
X, color = datasets.make_s_curve(n_samples, random_state=0)
ax = subplots[1][0]
ax.scatter(X[:, 0], X[:, 2], c=color)
an.xaxis.set_major_formatter(NullFormatter())
an.yaxis.set_major_formatter(NullFormatter())
for i, perplexity in enumerate(perplexities):
    ax = subplots[1][i + 1]
    t0 = time()
tsne = manifold.TSNE(n_components=n_components, init='random',
random_state=0, perplexity=perplexity)
Y = tsne.fit_transform(X)
t1 = time()
print("S-curve, perplexity=%d in %.2g sec" % (perplexity, t1 - t0))

ax.set_title("Perplexity=%d" % perplexity)
ax.scatter(Y[:, 0], Y[:, 1], c=color)
ax.xaxis.set_major_formatter(NullFormatter())
ax.yaxis.set_major_formatter(NullFormatter())
ax.axis('tight')

# Another example using a 2D uniform grid
x = np.linspace(0, 1, int(np.sqrt(n_samples)))
xx, yy = np.meshgrid(x, x)
X = np.hstack([xx.ravel().reshape(-1, 1),
               yy.ravel().reshape(-1, 1),
               ])
color = xx.ravel()
ax = subplots[2][0]
ax.scatter(X[:, 0], X[:, 1], c=color)
ax.xaxis.set_major_formatter(NullFormatter())
ax.yaxis.set_major_formatter(NullFormatter())

for i, perplexity in enumerate(perplexities):
    ax = subplots[2][i + 1]
    t0 = time()
    tsne = manifold.TSNE(n_components=n_components, init='random',
                         random_state=0, perplexity=perplexity)
    Y = tsne.fit_transform(X)
t1 = time()
    print("uniform grid, perplexity=%d in %.2g sec" % (perplexity, t1 - t0))
    ax.set_title("Perplexity=%d" % perplexity)
    ax.scatter(Y[:, 0], Y[:, 1], c=color)
    ax.xaxis.set_major_formatter(NullFormatter())
    ax.yaxis.set_major_formatter(NullFormatter())
    ax.axis('tight')

plt.show()
6.19.5 Manifold Learning methods on a severed sphere

An application of the different Manifold learning techniques on a spherical data-set. Here one can see the use of dimensionality reduction in order to gain some intuition regarding the manifold learning methods. Regarding the dataset, the poles are cut from the sphere, as well as a thin slice down its side. This enables the manifold learning techniques to ‘spread it open’ whilst projecting it onto two dimensions.

For a similar example, where the methods are applied to the S-curve dataset, see Comparison of Manifold Learning methods

Note that the purpose of the MDS is to find a low-dimensional representation of the data (here 2D) in which the distances respect well the distances in the original high-dimensional space, unlike other manifold-learning algorithms, it does not seeks an isotropic representation of the data in the low-dimensional space. Here the manifold problem matches fairly that of representing a flat map of the Earth, as with map projection

Out:

/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_neighbors=10, n_components=2 as keyword args. From version 1.0 (renaming of 0.25) passing these as positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version ", standard: 0.06 sec
/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_neighbors=10, n_components=2 as keyword args. From version 1.0 (renaming of 0.25) passing these as positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version ", ltsa: 0.084 sec
/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_neighbors=10, n_components=2 as keyword args. From version 1.0 (renaming of 0.25) passing these as positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version ", hessian: 0.16 sec
/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_neighbors=10, n_components=2 as keyword args. From version 1.0 (renaming of 0.25) passing these as positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version ")
warnings.warn(f"Pass {args_msg} as keyword args. From version "
modified: 0.13 sec
/home/circleci/project/sklearn/utils/validation.py:70: FutureWarning: Pass n_
-→neighbors=10 as keyword args. From version 1.0 (renaming of 0.25) passing these as_
-→positional arguments will result in an error
warnings.warn(f"Pass {args_msg} as keyword args. From version "
ISO: 0.27 sec
MDS: 0.92 sec
Spectral Embedding: 0.053 sec
t-SNE: 4 sec

# Author: Jaques Grobler <jaques.grobler@inria.fr>
# License: BSD 3 clause

print(__doc__)

from time import time
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
from matplotlib.ticker import NullFormatter

from sklearn import manifold
from sklearn.utils import check_random_state

# Next line to silence pyflakes.
Axes3D

# Variables for manifold learning.
n_neighbors = 10
n_samples = 1000

# Create our sphere.
random_state = check_random_state(0)
p = random_state.rand(n_samples) * (2 * np.pi - 0.55)
t = random_state.rand(n_samples) * np.pi

# Sever the poles from the sphere.
indices = ((t < (np.pi - (np.pi / 8))) & (t > ((np.pi / 8))))

x, y, z = np.sin(t[indices]) * np.cos(p[indices]),
          np.sin(t[indices]) * np.sin(p[indices]),
          np.cos(t[indices])

# Plot our dataset.
fig = plt.figure(figsize=(15, 8))
plt.suptitle("Manifold Learning with %i points, %i neighbors"
            % (1000, n_neighbors), fontsize=14)
ax = fig.add_subplot(251, projection='3d')
ax.scatter(x, y, z, c=p[indices], cmap=plt.cm.rainbow)
ax.view_init(40, -10)
sphere_data = np.array([x, y, z]).T

# Perform Locally Linear Embedding Manifold learning
methods = ['standard', 'ltsa', 'hessian', 'modified']
labels = ['LLE', 'LTSA', 'Hessian LLE', 'Modified LLE']

for i, method in enumerate(methods):
    t0 = time()
    trans_data = manifold.LocallyLinearEmbedding(n_neighbors, 2,
                                              method=method).fit_transform(sphere_data).T
    t1 = time()
    print("%s: %.2g sec" % (methods[i], t1 - t0))
    ax = fig.add_subplot(252 + i)
    plt.scatter(trans_data[0], trans_data[1], c=colors, cmap=plt.cm.rainbow)
    plt.title("%s (%.2g sec)" % (labels[i], t1 - t0))
    ax.xaxis.set_major_formatter(NullFormatter())
    ax.yaxis.set_major_formatter(NullFormatter())
    plt.axis('tight')

# Perform Isomap Manifold learning.
t0 = time()
trans_data = manifold.Isomap(n_neighbors, n_components=2)\.
    .fit_transform(sphere_data).T
    t1 = time()
print("%s: %.2g sec" % ('ISO', t1 - t0))
    ax = fig.add_subplot(257)
    plt.scatter(trans_data[0], trans_data[1], c=colors, cmap=plt.cm.rainbow)
    plt.title("%s (%.2g sec)" % ('Isomap', t1 - t0))
    ax.xaxis.set_major_formatter(NullFormatter())
    ax.yaxis.set_major_formatter(NullFormatter())
    plt.axis('tight')

# Perform Multi-dimensional scaling.
t0 = time()
mds = manifold.MDS(2, max_iter=100, n_init=1)
trans_data = mds.fit_transform(sphere_data).T
    t1 = time()
print("MDS: %.2g sec" % (t1 - t0))
    ax = fig.add_subplot(258)
    plt.scatter(trans_data[0], trans_data[1], c=colors, cmap=plt.cm.rainbow)
    plt.title("MDS (%.2g sec)" % (t1 - t0))
    ax.xaxis.set_major_formatter(NullFormatter())
    ax.yaxis.set_major_formatter(NullFormatter())
    plt.axis('tight')

# Perform Spectral Embedding.
t0 = time()
se = manifold.SpectralEmbedding(n_components=2,
                                n_neighbors=n_neighbors)
trans_data = se.fit_transform(sphere_data).T
t1 = time()
print("Spectral Embedding: %.2g sec" % (t1 - t0))

ax = fig.add_subplot(259)
plt.scatter(trans_data[0], trans_data[1], c=colors, cmap=plt.cm.rainbow)
plt.title("Spectral Embedding (%.2g sec)" % (t1 - t0))
ax.xaxis.set_major_formatter(NullFormatter())
ax.yaxis.set_major_formatter(NullFormatter())
plt.axis('tight')

# Perform t-distributed stochastic neighbor embedding.
t0 = time()
tsne = manifold.TSNE(n_components=2, init='pca', random_state=0)
trans_data = tsne.fit_transform(sphere_data).T
t1 = time()
print("t-SNE: %.2g sec" % (t1 - t0))

ax = fig.add_subplot(2, 5, 10)
plt.scatter(trans_data[0], trans_data[1], c=colors, cmap=plt.cm.rainbow)
plt.title("t-SNE (%.2g sec)" % (t1 - t0))
ax.xaxis.set_major_formatter(NullFormatter())
ax.yaxis.set_major_formatter(NullFormatter())
plt.axis('tight')
plt.show()

Total running time of the script: (0 minutes 6.251 seconds)

6.19.6 Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...

An illustration of various embeddings on the digits dataset.

The RandomTreesEmbedding, from the `sklearn.ensemble` module, is not technically a manifold embedding method, as it learn a high-dimensional representation on which we apply a dimensionality reduction method. However, it is often useful to cast a dataset into a representation in which the classes are linearly-separable.

t-SNE will be initialized with the embedding that is generated by PCA in this example, which is not the default setting. It ensures global stability of the embedding, i.e., the embedding does not depend on random initialization.

Linear Discriminant Analysis, from the `sklearn.discriminant_analysis` module, and Neighborhood Components Analysis, from the `sklearn.neighbors` module, are supervised dimensionality reduction method, i.e. they make use of the provided labels, contrary to other methods.
A selection from the 64-dimensional digits dataset
Random Projection of the digits
Locally Linear Embedding of the digits (time 0.19s)
Random forest embedding of the digits (time 0.23s)
t-SNE embedding of the digits (time 6.30s)
Out:

```
Computing random projection
Computing PCA projection
Computing Linear Discriminant Analysis projection
Computing Isomap projection
Done.
Computing LLE embedding
Done. Reconstruction error: 2.11987e-06
Computing modified LLE embedding
Done. Reconstruction error: 0.360769
Computing Hessian LLE embedding
Done. Reconstruction error: 0.212674
Computing LTSA embedding
Done. Reconstruction error: 0.212675
Computing MDS embedding
Done. Stress: 138515189.392665
Computing Totally Random Trees embedding
Computing Spectral embedding
Computing t-SNE embedding
Computing NCA projection
```
from time import time
import numpy as np
import matplotlib.pyplot as plt
from matplotlib import offsetbox
from sklearn import manifold, datasets, decomposition, ensemble,
discriminant_analysis, random_projection, neighbors

print(__doc__)

digits = datasets.load_digits(n_class=6)
X = digits.data
y = digits.target
n_samples, n_features = X.shape
n_neighbors = 30

# Scale and visualize the embedding vectors

def plot_embedding(X, title=None):
x_min, x_max = np.min(X, 0), np.max(X, 0)
X = (X - x_min) / (x_max - x_min)
plt.figure()
ax = plt.subplot(111)
for i in range(X.shape[0]):
    plt.text(X[i, 0], X[i, 1], str(y[i]),
             color=plt.cm.Set1(y[i] / 10.),
             fontdict={'weight': 'bold', 'size': 9})

if hasattr(offsetbox, 'AnnotationBbox'):
    # only print thumbnails with matplotlib > 1.0
    shown_images = np.array([[1., 1.]])  # just something big
    for i in range(X.shape[0]):
        dist = np.sum((X[i] - shown_images) ** 2, 1)
        if np.min(dist) < 4e-3:
            # don't show points that are too close
            continue
        shown_images = np.r_[shown_images, [X[i]]]
        imagebox = offsetbox.AnnotationBbox(
            offsetbox.OffsetImage(digits.images[i], cmap=plt.cm.gray_r),
            X[i])
        ax.add_artist(imagebox)

plt.xticks(()), plt.yticks(()
if title is not None:
    plt.title(title)

# Plot images of the digits
n_img_per_row = 20
img = np.zeros((10 * n_img_per_row, 10 * n_img_per_row))
for i in range(n_img_per_row):
    plt.text(X[i, 0], X[i, 1], str(y[i]),
             color=plt.cm.Set1(y[i] / 10.),
             fontdict={'weight': 'bold', 'size': 9})

if hasattr(offsetbox, 'AnnotationBbox'):
    # only print thumbnails with matplotlib > 1.0
    shown_images = np.array([[1., 1.]])  # just something big
    for i in range(X.shape[0]):
        dist = np.sum((X[i] - shown_images) ** 2, 1)
        if np.min(dist) < 4e-3:
            # don't show points that are too close
            continue
        shown_images = np.r_[shown_images, [X[i]]]
        imagebox = offsetbox.AnnotationBbox(
            offsetbox.OffsetImage(digits.images[i], cmap=plt.cm.gray_r),
            X[i])
        ax.add_artist(imagebox)

plt.xticks(()), plt.yticks(()
if title is not None:
    plt.title(title)
ix = 10 * i + 1
for j in range(n_img_per_row):
    iy = 10 * j + 1
    img[ix:ix + 8, iy:iy + 8] = X[i * n_img_per_row + j].reshape((8, 8))
plt.imshow(img, cmap=plt.cm.binary)
plt.xticks([])
plt.yticks([])
plt.title('A selection from the 64-dimensional digits dataset')

# Random 2D projection using a random unitary matrix
print("Computing random projection")
rp = random_projection.SparseRandomProjection(n_components=2, random_state=42)
X_projected = rp.fit_transform(X)
plot_embedding(X_projected, "Random Projection of the digits")

# Projection on to the first 2 principal components
print("Computing PCA projection")
t0 = time()
X_pca = decomposition.TruncatedSVD(n_components=2).fit_transform(X)
plot_embedding(X_pca,
               "Principal Components projection of the digits (time \$%.2fs\$)" % (time() - t0))

# Projection on to the first 2 linear discriminant components
print("Computing Linear Discriminant Analysis projection")
X2 = X.copy()
X2.flat[::X.shape[1] + 1] += 0.01  # Make X invertible
t0 = time()
X_lda = discriminant_analysis.LinearDiscriminantAnalysis(n_components=2).
        fit_transform(X2, y)
plot_embedding(X_lda,
               "Linear Discriminant projection of the digits (time \$%.2fs\$)" %
               (time() - t0))

# Isomap projection of the digits dataset
print("Computing Isomap projection")
t0 = time()
X_iso = manifold.Isomap(n_neighbors=n_neighbors, n_components=2).
        fit_transform(X)
print("Done.")
plot_embedding(X_iso,
               "Isomap projection of the digits (time \$%.2fs\$)" %
               (time() - t0))

# Locally linear embedding of the digits dataset

6.19. Manifold learning
print("Computing LLE embedding")
clf = manifold.LocallyLinearEmbedding(n_neighbors=n_neighbors, n_components=2,
    method='standard')
t0 = time()
X_lle = clf.fit_transform(X)
print("Done. Reconstruction error: \$g\$ \% clf.reconstruction_error_")
plot_embedding(X_lle,
    "Locally Linear Embedding of the digits (time %.2fs)" %
    (time() - t0))
#
# Modified Locally linear embedding of the digits dataset
print("Computing modified LLE embedding")
clf = manifold.LocallyLinearEmbedding(n_neighbors=n_neighbors, n_components=2,
    method='modified')
t0 = time()
X_mlle = clf.fit_transform(X)
print("Done. Reconstruction error: \$g\$ \% clf.reconstruction_error_")
plot_embedding(X_mlle,
    "Modified Locally Linear Embedding of the digits (time %.2fs)" %
    (time() - t0))
#
# HLLE embedding of the digits dataset
print("Computing Hessian LLE embedding")
clf = manifold.LocallyLinearEmbedding(n_neighbors=n_neighbors, n_components=2,
    method='hessian')
t0 = time()
X_hlle = clf.fit_transform(X)
print("Done. Reconstruction error: \$g\$ \% clf.reconstruction_error_")
plot_embedding(X_hlle,
    "Hessian Locally Linear Embedding of the digits (time %.2fs)" %
    (time() - t0))
#
# LTSA embedding of the digits dataset
print("Computing LTSA embedding")
clf = manifold.LocallyLinearEmbedding(n_neighbors=n_neighbors, n_components=2,
    method='ltsa')
t0 = time()
X_ltsa = clf.fit_transform(X)
print("Done. Reconstruction error: \$g\$ \% clf.reconstruction_error_")
plot_embedding(X_ltsa,
    "Local Tangent Space Alignment of the digits (time %.2fs)" %
    (time() - t0))
#
# MDS embedding of the digits dataset
print("Computing MDS embedding")
clf = manifold.MDS(n_components=2, n_init=1, max_iter=100)
t0 = time()
X_mds = clf.fit_transform(X)
print("Done. Stress: \$f\$ \% clf.stress_")
plot_embedding(X_mds,
# MDS embedding of the digits (time %.2fs) %
(time() - t0))

# Random Trees embedding of the digits dataset
print("Computing Totally Random Trees embedding")
hasher = ensemble.RandomTreesEmbedding(n_estimators=200, random_state=0,
max_depth=5)
t0 = time()
X_transformed = hasher.fit_transform(X)
pca = decomposition.TruncatedSVD(n_components=2)
X_reduced = pca.fit_transform(X_transformed)

plot_embedding(X_reduced,
"Random forest embedding of the digits (time %.2fs)" %
(time() - t0))

# Spectral embedding of the digits dataset
print("Computing Spectral embedding")
embedder = manifold.SpectralEmbedding(n_components=2, random_state=0, eigen_solver="arpack")
t0 = time()
X_se = embedder.fit_transform(X)

plot_embedding(X_se,
"Spectral embedding of the digits (time %.2fs)" %
(time() - t0))

# t-SNE embedding of the digits dataset
print("Computing t-SNE embedding")
tsne = manifold.TSNE(n_components=2, init='pca', random_state=0)
t0 = time()
X_tsne = tsne.fit_transform(X)

plot_embedding(X_tsne,
"t-SNE embedding of the digits (time %.2fs)" %
(time() - t0))

# NCA projection of the digits dataset
print("Computing NCA projection")
nca = neighbors.NeighborhoodComponentsAnalysis(init='random',
n_components=2, random_state=0)
t0 = time()
X_nca = nca.fit_transform(X, y)

plot_embedding(X_nca,
"NCA embedding of the digits (time %.2fs)" %
(time() - t0))

plt.show()

Total running time of the script: ( 0 minutes 38.912 seconds)
6.20 Miscellaneous

Miscellaneous and introductory examples for scikit-learn.

6.20.1 Compact estimator representations

This example illustrates the use of the print_changed_only global parameter.

Setting print_changed_only to True will alternate the representation of estimators to only show the parameters that have been set to non-default values. This can be used to have more compact representations.

Out:

Default representation:
LogisticRegression(penalty='l1')

With changed_only option:
LogisticRegression(penalty='l1')

```
print(__doc__)

from sklearn.linear_model import LogisticRegression
from sklearn import set_config

lr = LogisticRegression(penalty='l1')
print('Default representation:')
print(lr)
# LogisticRegression(C=1.0, class_weight=None, dual=False, fit_intercept=True,
# intercept_scaling=1, l1_ratio=None, max_iter=100,
# multi_class='auto', n_jobs=None, penalty='l1',
# random_state=None, solver='warn', tol=0.0001, verbose=0,
# warm_start=False)

set_config(print_changed_only=True)
print('With changed_only option:')
print(lr)
# LogisticRegression(penalty='l1')
```

**Total running time of the script:** ( 0 minutes 0.002 seconds)
6.20.2 ROC Curve with Visualization API

Scikit-learn defines a simple API for creating visualizations for machine learning. The key features of this API is to allow for quick plotting and visual adjustments without recalculation. In this example, we will demonstrate how to use the visualization API by comparing ROC curves.

```python
print(__doc__)
```

Load Data and Train a SVC

First, we load the wine dataset and convert it to a binary classification problem. Then, we train a support vector classifier on a training dataset.

```python
import matplotlib.pyplot as plt
from sklearn.svm import SVC
from sklearn.ensemble import RandomForestClassifier
from sklearn.metrics import plot_roc_curve
from sklearn.datasets import load_wine
from sklearn.model_selection import train_test_split

X, y = load_wine(return_X_y=True)
y = y == 2
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=42)
svc = SVC(random_state=42)
svc.fit(X_train, y_train)
```

Plotting the ROC Curve

Next, we plot the ROC curve with a single call to `sklearn.metrics.plot_roc_curve`. The returned `svc_disp` object allows us to continue using the already computed ROC curve for the SVC in future plots.

```python
svc_disp = plot_roc_curve(svc, X_test, y_test)
plt.show()
```
Training a Random Forest and Plotting the ROC Curve

We train a random forest classifier and create a plot comparing it to the SVC ROC curve. Notice how `svc_disp` uses `plot` to plot the SVC ROC curve without recomputing the values of the roc curve itself. Furthermore, we pass `alpha=0.8` to the plot functions to adjust the alpha values of the curves.

```python
tfc = RandomForestClassifier(n_estimators=10, random_state=42)
tfc.fit(X_train, y_train)
ax = plt.gca()
tfc_disp = plot_roc_curve(tfc, X_test, y_test, ax=ax, alpha=0.8)
svc_disp.plot(ax=ax, alpha=0.8)
plt.show()
```
6.20.3 Visualizations with Display Objects

In this example, we will construct display objects, `ConfusionMatrixDisplay`, `RocCurveDisplay`, and `PrecisionRecallDisplay` directly from their respective metrics. This is an alternative to using their corresponding plot functions when a model’s predictions are already computed or expensive to compute. Note that this is advanced usage, and in general we recommend using their respective plot functions.

```
print(__doc__)
```

Load Data and train model

For this example, we load a blood transfusion service center data set from OpenML <https://www.openml.org/d/1464>. This is a binary classification problem where the target is whether an individual donated blood. Then the data is split into a train and test dataset and a logistic regression is fitted with the train dataset.

```
from sklearn.datasets import fetch_openml
from sklearn.preprocessing import StandardScaler
from sklearn.pipeline import make_pipeline
from sklearn.linear_model import LogisticRegression
from sklearn.model_selection import train_test_split
```
X, y = fetch_openml(data_id=1464, return_X_y=True)
X_train, X_test, y_train, y_test = train_test_split(X, y, stratify=y)
clf = make_pipeline(StandardScaler(), LogisticRegression(random_state=0))
clf.fit(X_train, y_train)

Create `ConfusionMatrixDisplay`

With the fitted model, we compute the predictions of the model on the test dataset. These predictions are used to compute the confusion matrix which is plotted with the `ConfusionMatrixDisplay`

```python
from sklearn.metrics import confusion_matrix
from sklearn.metrics import ConfusionMatrixDisplay

ty_pred = clf.predict(X_test)
cm = confusion_matrix(y_test, y_pred)

cm_display = ConfusionMatrixDisplay(cm).plot()
```
Create **RocCurveDisplay**

The roc curve requires either the probabilities or the non-thresholded decision values from the estimator. Since the logistic regression provides a decision function, we will use it to plot the roc curve:

```python
from sklearn.metrics import roc_curve
from sklearn.metrics import RocCurveDisplay

y_score = clf.decision_function(X_test)

fpr, tpr, _ = roc_curve(y_test, y_score, pos_label=clf.classes_[1])
roc_display = RocCurveDisplay(fpr=fpr, tpr=tpr).plot()
```

![Roc Curve](image)

Create **PrecisionRecallDisplay**

Similarly, the precision recall curve can be plotted using `y_score` from the previous sections.

```python
from sklearn.metrics import precision_recall_curve
from sklearn.metrics import PrecisionRecallDisplay

prec, recall, _ = precision_recall_curve(y_test, y_score, pos_label=clf.classes_[1])
pr_display = PrecisionRecallDisplay(precision=prec, recall=recall).plot()
```
Combining the display objects into a single plot

The display objects store the computed values that were passed as arguments. This allows for the visualizations to be easily combined using matplotlib’s API. In the following example, we place the displays next to each other in a row.

```python
import matplotlib.pyplot as plt
fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(12, 8))
roc_display.plot(ax=ax1)
pr_display.plot(ax=ax2)
plt.show()
```
An illustration of the isotonic regression on generated data (non-linear monotonic trend with homoscedastic uniform noise).

The isotonic regression algorithm finds a non-decreasing approximation of a function while minimizing the mean squared error on the training data. The benefit of such a non-parametric model is that it does not assume any shape for the target function besides monotonicity. For comparison a linear regression is also presented.

The plot on the right-hand side shows the model prediction function that results from the linear interpolation of thresholds points. The thresholds points are a subset of the training input observations and their matching target values are computed by the isotonic non-parametric fit.

```python
print(__doc__)

# Author: Nelle Varoquaux <nelle.varoquaux@gmail.com>
# Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.collections import LineCollection
from sklearn.linear_model import LinearRegression
from sklearn.isotonic import IsotonicRegression
from sklearn.utils import check_random_state
```
n = 100
x = np.arange(n)
rs = check_random_state(0)
y = rs.randint(-50, 50, size=(n,)) + 50. * np.log1p(np.arange(n))

Fit IsotonicRegression and LinearRegression models:

```python
ir = IsotonicRegression(out_of_bounds="clip")
y_ = ir.fit_transform(x, y)
lr = LinearRegression()
lr.fit(x[:, np.newaxis], y)  # x needs to be 2d for LinearRegression
```

Plot results:

```python
segments = [[[i, y[i]], [i, y_[i]]] for i in range(n)]
lc = LineCollection(segments, zorder=0)
lc.set_array(np.ones(len(y)))
lc.set_linewidths(np.full(n, 0.5))
fig, (ax0, ax1) = plt.subplots(ncols=2, figsize=(12, 6))
ax0.plot(x, y, 'C0.', markersize=12)
ax0.plot(x, y_, 'C1.-', markersize=12)
ax0.plot(x, lr.predict(x[:, np.newaxis]), 'C2-')
ax0.add_collection(lc)
ax0.legend(('Training data', 'Isotonic fit', 'Linear fit'), loc='lower right')
ax0.set_title('Isotonic regression fit on noisy data (n=%d)' % n)

x_test = np.linspace(-10, 110, 1000)
ax1.plot(x_test, ir.predict(x_test), 'C1-')
ax1.plot(ir.X_thresholds_, ir.y_thresholds_, 'C1.', markersize=12)
ax1.set_title("Prediction function (%d thresholds)" % len(ir.X_thresholds_))
```

plt.show()
Note that we explicitly passed `out_of_bounds="clip"` to the constructor of `IsotonicRegression` to control the way the model extrapolates outside of the range of data observed in the training set. This “clipping” extrapolation can be seen on the plot of the decision function on the right-hand.

**Total running time of the script:** ( 0 minutes 0.160 seconds)

### 6.20.5 Advanced Plotting With Partial Dependence

The `plot_partial_dependence` function returns a `PartialDependenceDisplay` object that can be used for plotting without needing to recalculate the partial dependence. In this example, we show how to plot partial dependence plots and how to quickly customize the plot with the visualization API.

---

**Note:** See also *ROC Curve with Visualization API*

```python
print(__doc__)

import pandas as pd
import matplotlib.pyplot as plt
from sklearn.datasets import load_diabetes
from sklearn.neural_network import MLPRegressor
from sklearn.preprocessing import StandardScaler
from sklearn.pipeline import make_pipeline
from sklearn.tree import DecisionTreeRegressor
from sklearn.inspection import plot_partial_dependence
```
Train models on the diabetes dataset

First, we train a decision tree and a multi-layer perceptron on the diabetes dataset.

```python
diabetes = load_diabetes()
X = pd.DataFrame(diabetes.data, columns=diabetes.feature_names)
y = diabetes.target

tree = DecisionTreeRegressor()
mlp = make_pipeline(StandardScaler(),
    MLPRegressor(hidden_layer_sizes=(100, 100),
                  tol=1e-2, max_iter=500, random_state=0))
tree.fit(X, y)
mlp.fit(X, y)
```

Plotting partial dependence for two features

We plot partial dependence curves for features “age” and “bmi” (body mass index) for the decision tree. With two features, `plot_partial_dependence` expects to plot two curves. Here the plot function place a grid of two plots using the space defined by `ax`.

```python
fig, ax = plt.subplots(figsize=(12, 6))
ax.set_title("Decision Tree")
tree_disp = plot_partial_dependence(tree, X, ["age", "bmi"], ax=ax)
```

The partial dependence curves can be plotted for the multi-layer perceptron. In this case, `line_kw` is passed to `plot_partial_dependence` to change the color of the curve.

```python
fig, ax = plt.subplots(figsize=(12, 6))
ax.set_title("Multi-layer Perceptron")
mlp Disp = plot_partial_dependence(mlp, X, ["age", "bmi"], ax=ax,
    line_kw={"color": "red"})
```
Plotting partial dependence of the two models together

The tree_dis and mlp_dis PartialDependenceDisplay objects contain all the computed information needed to recreate the partial dependence curves. This means we can easily create additional plots without needing to recompute the curves.

One way to plot the curves is to place them in the same figure, with the curves of each model on each row. First, we create a figure with two axes within two rows and one column. The two axes are passed to the plot functions of tree_dis and mlp_dis. The given axes will be used by the plotting function to draw the partial dependence. The resulting plot places the decision tree partial dependence curves in the first row of the multi-layer perceptron in the second row.

```python
fig, (ax1, ax2) = plt.subplots(2, 1, figsize=(10, 10))
tree_disp.plot(ax=ax1)
ax1.set_title("Decision Tree")
mlp_disp.plot(ax=ax2, line_kw={"color": "red"})
ax2.set_title("Multi-layer Perceptron")
```
scikit-learn user guide, Release 0.24.0

Out:
Text(0.5, 1.0, 'Multi-layer Perceptron')

Another way to compare the curves is to plot them on top of each other. Here, we create a figure with one row and two
columns. The axes are passed into the plot function as a list, which will plot the partial dependence curves of each
model on the same axes. The length of the axes list must be equal to the number of plots drawn.
fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(10, 6))
tree_disp.plot(ax=[ax1, ax2], line_kw={"label": "Decision Tree"})
mlp_disp.plot(ax=[ax1, ax2], line_kw={"label": "Multi-layer Perceptron",
"color": "red"})
ax1.legend()
ax2.legend()

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tree Disp.axes_ is a numpy array container the axes used to draw the partial dependence plots. This can be passed to mlp disp to have the same affect of drawing the plots on top of each other. Furthermore, the mlp disp. figure stores the figure, which allows for resizing the figure after calling plot. In this case tree disp. axes_ has two dimensions, thus plot will only show the y label and y ticks on the left most plot.

```python
tree Disp.plot(line_kw="label": "Decision Tree")
mlp Disp.plot(line_kw="label": "Multi-layer Perceptron", "color": "red"),
ax=tree Disp.axes_)
tree Disp.figure_.set_size_inches(10, 6)
tree Disp.axes_[0, 0].legend()
tree Disp.axes_[0, 1].legend()
plt.show()
```
Plotting partial dependence for one feature

Here, we plot the partial dependence curves for a single feature, “age”, on the same axes. In this case, `tree_disp.axes_` is passed into the second plot function.

```python
tree_disp = plot_partial_dependence(tree, X, ["age"])
mlp_disp = plot_partial_dependence(mlp, X, ["age"],
                                      ax=tree_disp.axes_,
                                      line_kw="color": "red")
```
6.20.6 Face completion with a multi-output estimators

This example shows the use of multi-output estimator to complete images. The goal is to predict the lower half of a face given its upper half.

The first column of images shows true faces. The next columns illustrate how extremely randomized trees, k nearest neighbors, linear regression and ridge regression complete the lower half of those faces.
Face completion with multi-output estimators

```
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt

from sklearn.datasets import fetch_olivetti_faces
from sklearn.utils.validation import check_random_state
from sklearn.ensemble import ExtraTreesRegressor
```

(continues on next page)
from sklearn.neighbors import KNeighborsRegressor
from sklearn.linear_model import LinearRegression
from sklearn.linear_model import RidgeCV

# Load the faces datasets
data, targets = fetch_olivetti_faces(return_X_y=True)

train = data[targets < 30]
test = data[targets >= 30]  # Test on independent people

# Test on a subset of people
n_faces = 5
rng = check_random_state(4)
face_ids = rng.randint(test.shape[0], size=(n_faces, ))
test = test[face_ids, :]

n_pixels = data.shape[1]

# Upper half of the faces
X_train = train[:, :(n_pixels + 1) // 2]
# Lower half of the faces
y_train = train[:, n_pixels // 2:]
X_test = test[:, :(n_pixels + 1) // 2]
y_test = test[:, n_pixels // 2:]

# Fit estimators
ESTIMATORS = {
    "Extra trees": ExtraTreesRegressor(n_estimators=10, max_features=32,
                                           random_state=0),
    "K-nn": KNeighborsRegressor(),
    "linear regression": LinearRegression(),
    "Ridge": RidgeCV(),
}

y_test_predict = dict()
for name, estimator in ESTIMATORS.items():
    estimator.fit(X_train, y_train)
    y_test_predict[name] = estimator.predict(X_test)

# Plot the completed faces
image_shape = (64, 64)

n_cols = 1 + len(ESTIMATORS)
plt.figure(figsize=(2. * n_cols, 2.26 * n_faces))
plt.suptitle("Face completion with multi-output estimators", size=16)

for i in range(n_faces):
    true_face = np.hstack((X_test[i], y_test[i]))

    if i:
        sub = plt.subplot(n_faces, n_cols, i * n_cols + 1)
    else:
        sub = plt.subplot(n_faces, n_cols, i * n_cols + 1,
                          title="true faces")

    sub.axis("off")
    sub.imshow(true_face.reshape(image_shape),
               cmap=plt.cm.gray,
(continues on next page)
interpolation="nearest")

for j, est in enumerate(sorted(ESTIMATORS)):
    completed_face = np.hstack((X_test[i], y_test_predict[est][i]))
    if i:
        sub = plt.subplot(n_faces, n_cols, i * n_cols + 2 + j)
    else:
        sub = plt.subplot(n_faces, n_cols, i * n_cols + 2 + j,
                          title=est)

    sub.axis("off")
    sub.imshow(completed_face.reshape(image_shape),
               cmap=plt.cm.gray,
               interpolation="nearest")

plt.show()

Total running time of the script: ( 0 minutes 1.954 seconds)

6.20.7 Multilabel classification

This example simulates a multi-label document classification problem. The dataset is generated randomly based on the following process:

- pick the number of labels: \( n \sim \text{Poisson}(n_{\text{labels}}) \)
- \( n \) times, choose a class \( c \sim \text{Multinomial}(\theta) \)
- pick the document length: \( k \sim \text{Poisson}(\text{length}) \)
- \( k \) times, choose a word: \( w \sim \text{Multinomial}(\theta_c) \)

In the above process, rejection sampling is used to make sure that \( n \) is more than 2, and that the document length is never zero. Likewise, we reject classes which have already been chosen. The documents that are assigned to both classes are plotted surrounded by two colored circles.

The classification is performed by projecting to the first two principal components found by PCA and CCA for visualisation purposes, followed by using the `OneVsRestClassifier` metaclassifier using two SVCs with linear kernels to learn a discriminative model for each class. Note that PCA is used to perform an unsupervised dimensionality reduction, while CCA is used to perform a supervised one.

Note: in the plot, “unlabeled samples” does not mean that we don’t know the labels (as in semi-supervised learning) but that the samples simply do not have a label.
```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_multilabel_classification
from sklearn.multiclass import OneVsRestClassifier
from sklearn.svm import SVC
from sklearn.decomposition import PCA
from sklearn.cross_decomposition import CCA

def plot_hyperplane(clf, min_x, max_x, linestyle, label):
    # get the separating hyperplane
    w = clf.coef_[0]
    a = -w[0] / w[1]
    xx = np.linspace(min_x - 5, max_x + 5)
    yy = a * xx - (clf.intercept_[0]) / w[1]
    plt.plot(xx, yy, linestyle, label=label)

def plot_subfigure(X, Y, subplot, title, transform):
    if transform == "pca":
        X = PCA(n_components=2).fit_transform(X)
    elif transform == "cca":
        (continues on next page)
```

6.20. Miscellaneous
```python
X = CCA(n_components=2).fit(X, Y).transform(X)
else:
    raise ValueError

min_x = np.min(X[:, 0])
max_x = np.max(X[:, 0])

min_y = np.min(X[:, 1])
max_y = np.max(X[:, 1])

classif = OneVsRestClassifier(SVC(kernel='linear'))
classif.fit(X, Y)

plt.subplot(2, 2, subplot)
plt.title(title)

zero_class = np.where(Y[:, 0])
one_class = np.where(Y[:, 1])
plt.scatter(X[:, 0], X[:, 1], s=40, c='gray', edgecolors=(0, 0, 0))
plt.scatter(X[zero_class, 0], X[zero_class, 1], s=160, edgecolors='b',
            facecolors='none', linewidths=2, label='Class 1')
plt.scatter(X[one_class, 0], X[one_class, 1], s=80, edgecolors='orange',
            facecolors='none', linewidths=2, label='Class 2')

plot_hyperplane(classif.estimators_[0], min_x, max_x, 'k--',
                'Boundary

plot_hyperplane(classif.estimators_[1], min_x, max_x, 'k-.

plt.xticks(())
plt.yticks(())
plt.xlim(min_x - .5 * max_x, max_x + .5 * max_x)
plt.ylim(min_y - .5 * max_y, max_y + .5 * max_y)
if subplot == 2:
    plt.xlabel('First principal component')
    plt.ylabel('Second principal component')
    plt.legend(loc="upper left")

plt.figure(figsize=(8, 6))
X, Y = make_multilabel_classification(n_classes=2, n_labels=1,
                                     allow_unlabeled=True,
                                     random_state=1)
plot_subfigure(X, Y, 1, "With unlabeled samples + CCA", "cca")
plot_subfigure(X, Y, 2, "With unlabeled samples + PCA", "pca")
X, Y = make_multilabel_classification(n_classes=2, n_labels=1,
                                     allow_unlabeled=False,
                                     random_state=1)
plot_subfigure(X, Y, 3, "Without unlabeled samples + CCA", "cca")
plot_subfigure(X, Y, 4, "Without unlabeled samples + PCA", "pca")
plt.subplots_adjust(.04, .02, .97, .94, .09, .2)
plt.show()
```
Total running time of the script:  ( 0 minutes 0.219 seconds)

6.20.8 Comparing anomaly detection algorithms for outlier detection on toy datasets

This example shows characteristics of different anomaly detection algorithms on 2D datasets. Datasets contain one or two modes (regions of high density) to illustrate the ability of algorithms to cope with multimodal data.

For each dataset, 15% of samples are generated as random uniform noise. This proportion is the value given to the nu parameter of the OneClassSVM and the contamination parameter of the other outlier detection algorithms. Decision boundaries between inliers and outliers are displayed in black except for Local Outlier Factor (LOF) as it has no predict method to be applied on new data when it is used for outlier detection.

The OneClassSVM is known to be sensitive to outliers and thus does not perform very well for outlier detection. This estimator is best suited for novelty detection when the training set is not contaminated by outliers. That said, outlier detection in high-dimension, or without any assumptions on the distribution of the inlying data is very challenging, and a One-class SVM might give useful results in these situations depending on the value of its hyperparameters.

EllipticEnvelope assumes the data is Gaussian and learns an ellipse. It thus degrades when the data is not unimodal. Notice however that this estimator is robust to outliers.

IsolationForest and LocalOutlierFactor seem to perform reasonably well for multi-modal data sets. The advantage of LocalOutlierFactor over the other estimators is shown for the third data set, where the two modes have different densities. This advantage is explained by the local aspect of LOF, meaning that it only compares the score of abnormality of one sample with the scores of its neighbors.

Finally, for the last data set, it is hard to say that one sample is more abnormal than another sample as they are uniformly distributed in a hypercube. Except for the OneClassSVM which overfits a little, all estimators present decent solutions for this situation. In such a case, it would be wise to look more closely at the scores of abnormality of the samples as a good estimator should assign similar scores to all the samples.

While these examples give some intuition about the algorithms, this intuition might not apply to very high dimensional data.

Finally, note that parameters of the models have been here handpicked but that in practice they need to be adjusted. In the absence of labelled data, the problem is completely unsupervised so model selection can be a challenge.
# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# Albert Thomas <albert.thomas@telecom-paristech.fr>
# License: BSD 3 clause

```python
import time
import numpy as np
import matplotlib
```

(continues on next page)
import matplotlib.pyplot as plt

from sklearn import svm
from sklearn.datasets import make_moons, make_blobs
from sklearn.covariance import EllipticEnvelope
from sklearn.ensemble import IsolationForest
from sklearn.neighbors import LocalOutlierFactor

print(__doc__)

matplotlib.rcParams['contour.negative_linestyle'] = 'solid'

# Example settings
n_samples = 300
outliers_fraction = 0.15
n_outliers = int(outliers_fraction * n_samples)
n_inliers = n_samples - n_outliers

# define outlier/anomaly detection methods to be compared
anomaly_algorithms = [
    ('Robust covariance', EllipticEnvelope(contamination=outliers_fraction)),
    ('One-Class SVM', svm.OneClassSVM(nu=outliers_fraction, kernel="rbf",
        gamma=0.1)),
    ('Isolation Forest', IsolationForest(contamination=outliers_fraction,
        random_state=42)),
    ('Local Outlier Factor', LocalOutlierFactor(
        n_neighbors=35, contamination=outliers_fraction))]

# Define datasets
blobs_params = dict(random_state=0, n_samples=n_inliers, n_features=2)
datasets = [
    make_blobs(centers=[[0, 0], [0, 0]], cluster_std=0.5,
        **blobs_params)[0],
    make_blobs(centers=[[2, 2], [-2, -2]], cluster_std=[0.5, 0.5],
        **blobs_params)[0],
    make_blobs(centers=[[2, 2], [-2, -2]], cluster_std=[1.5, .3],
        **blobs_params)[0],
    4. * (make_moons(n_samples=n_samples, noise=.05, random_state=0)[0] -
        np.array([0.5, 0.25])),
    14. * (np.random.RandomState(42).rand(n_samples, 2) - 0.5)]

# Compare given classifiers under given settings
xx, yy = np.meshgrid(np.linspace(-7, 7, 150),
    np.linspace(-7, 7, 150))

plt.figure(figsize=(len(anomaly_algorithms) * 2 + 3, 12.5))
plt.subplots_adjust(left=.02, right=.98, bottom=.001, top=.96, wspace=.05,
    hspace=.01)

plot_num = 1
rng = np.random.RandomState(42)

for i_dataset, X in enumerate(datasets):
    # Add outliers
    X = np.concatenate([X, rng.uniform(low=-6, high=6,
        size=(n_outliers, 2))], axis=0)
for name, algorithm in anomaly_algorithms:
    t0 = time.time()
    algorithm.fit(X)
    t1 = time.time()
    plt.subplot(len(datasets), len(anomaly_algorithms), plot_num)
    if i_dataset == 0:
        plt.title(name, size=18)

    # fit the data and tag outliers
    if name == "Local Outlier Factor":
        y_pred = algorithm.fit_predict(X)
    else:
        y_pred = algorithm.fit(X).predict(X)

    # plot the levels lines and the points
    if name != "Local Outlier Factor":   # LOF does not implement predict
        Z = algorithm.predict(np.c_[xx.ravel(), yy.ravel()])
        Z = Z.reshape(xx.shape)
        plt.contour(xx, yy, Z, levels=[0], linewidths=2, colors='black')

    colors = np.array(['#377eb8', '#ff7f00'])
    plt.scatter(X[:, 0], X[:, 1], s=10, color=colors[(y_pred + 1) // 2])

    plt.xlim(-7, 7)
    plt.ylim(-7, 7)
    plt.xticks(())
    plt.yticks(())
    plt.text(.99, .01, ('%.2f' % (t1 - t0)).lstrip('0'),
             transform=plt.gca().transAxes, size=15,
             horizontalalignment='right')

    plot_num += 1

plt.show()

Total running time of the script: ( 0 minutes 4.657 seconds)

6.20.9 The Johnson-Lindenstrauss bound for embedding with random projections

The Johnson-Lindenstrauss lemma states that any high dimensional dataset can be randomly projected into a lower dimensional Euclidean space while controlling the distortion in the pairwise distances.

print(__doc__)

import sys
from time import time
import numpy as np
import matplotlib
import matplotlib.pyplot as plt
from sklearn.random_projection import johnson_lindenstrauss_min_dim
from sklearn.random_projection import SparseRandomProjection
from sklearn.datasets import fetch_20newsgroups_vectorized
from sklearn.datasets import load_digits
from sklearn.metrics.pairwise import euclidean_distances
from sklearn.utils.fixes import parse_version
# `normed` is being deprecated in favor of `density` in histograms
if parse_version(matplotlib.__version__) >= parse_version('2.1'):
    density_param = {'density': True}
else:
    density_param = {'normed': True}

Theoretical bounds

The distortion introduced by a random projection \( p \) is asserted by the fact that \( p \) is defining an \( \epsilon \)-embedding with good probability as defined by:

\[
(1 - \epsilon)\|u - v\|^2 < \|p(u) - p(v)\|^2 < (1 + \epsilon)\|u - v\|^2
\]

Where \( u \) and \( v \) are any rows taken from a dataset of shape \( (n_{\text{samples}}, n_{\text{features}}) \) and \( p \) is a projection by a random Gaussian \( \mathcal{N}(0, 1) \) matrix of shape \( (n_{\text{components}}, n_{\text{features}}) \) (or a sparse Achlioptas matrix).

The minimum number of components to guarantees the \( \epsilon \)-embedding is given by:

\[
n_{\text{components}} \geq 4\log(n_{\text{samples}})/(\epsilon^2/2 - \epsilon^3/3)
\]

The first plot shows that with an increasing number of samples \( n_{\text{samples}} \), the minimal number of dimensions \( n_{\text{components}} \) increased logarithmically in order to guarantee an \( \epsilon \)-embedding.

# range of admissible distortions
eps_range = np.linspace(0.1, 0.99, 5)
colors = plt.cm.Blues(np.linspace(0.3, 1.0, len(eps_range)))

# range of number of samples (observation) to embed
n_samples_range = np.logspace(1, 9, 9)

plt.figure()
for eps, color in zip(eps_range, colors):
    min_n_components = johnson_lindenstrauss_min_dim(n_samples_range, eps=eps)
    plt.loglog(n_samples_range, min_n_components, color=color)

plt.legend(["\(\epsilon = \$0.1\%\) \(\epsilon \) for \(\epsilon \) in \(\epsilon\) range", loc="lower right"],
            title="Number of observations to \(\epsilon\)-embed")
plt.xlabel("Minimum number of dimensions")
plt.ylabel("Number of observations to \(\epsilon\)-embed")
plt.title("Johnson-Lindenstrauss bounds: \(n_{\text{samples}} vs n_{\text{components}}\)")
plt.show()
The second plot shows that an increase of the admissible distortion $\text{eps}$ allows to reduce drastically the minimal number of dimensions $\text{n\_components}$ for a given number of samples $\text{n\_samples}$.

```python
# range of admissible distortions
eps_range = np.linspace(0.01, 0.99, 100)

# range of number of samples (observation) to embed
n_samples_range = np.logspace(2, 6, 5)
colors = plt.cm.Blues(np.linspace(0.3, 1.0, len(n_samples_range)))

plt.figure()
for n_samples, color in zip(n_samples_range, colors):
    min_n_components = johnson_lindenstrauss_min_dim(n_samples, eps=eps_range)
    plt.semilogy(eps_range, min_n_components, color=color)

plt.legend(["n\_samples = %d" % n for n in n_samples_range], loc="upper right")
plt.xlabel("Distortion eps")
plt.ylabel("Minimum number of dimensions")
plt.title("Johnson-Lindenstrauss bounds: \text{n\_components vs eps}")
plt.show()
```
Empirical validation

We validate the above bounds on the 20 newsgroups text document (TF-IDF word frequencies) dataset or on the digits dataset:

- for the 20 newsgroups dataset some 500 documents with 100k features in total are projected using a sparse random matrix to smaller euclidean spaces with various values for the target number of dimensions n_components.
- for the digits dataset, some 8x8 gray level pixels data for 500 handwritten digits pictures are randomly projected to spaces for various larger number of dimensions n_components.

The default dataset is the 20 newsgroups dataset. To run the example on the digits dataset, pass the --use-digits-dataset command line argument to this script.

```python
if '--use-digits-dataset' in sys.argv:
    data = load_digits().data[:500]
else:
    data = fetch_20newsgroups_vectorized().data[:500]
```

For each value of n_components, we plot:

- 2D distribution of sample pairs with pairwise distances in original and projected spaces as x and y axis respectively.
- 1D histogram of the ratio of those distances (projected / original).
n_samples, n_features = data.shape
print("Embedding %d samples with dim %d using various random projections"
      % (n_samples, n_features))

n_components_range = np.array([300, 1000, 10000])
dists = euclidean_distances(data, squared=True).ravel()

# select only non-identical samples pairs
nonzero = dists != 0
dists = dists[nonzero]

for n_components in n_components_range:
t0 = time()
    rp = SparseRandomProjection(n_components=n_components)
    projected_data = rp.fit_transform(data)
    print("Projected %d samples from %d to %d in %0.3f s"
          % (n_samples, n_features, n_components, time() - t0))
    if hasattr(rp, 'components_'):
        n_bytes = rp.components_.data.nbytes
        n_bytes += rp.components_.indices.nbytes
        print("Random matrix with size: %0.3fMB" % (n_bytes / 1e6))

    projected_dists = euclidean_distances(
        projected_data, squared=True).ravel()[nonzero]

    plt.figure()
    min_dist = min(projected_dists.min(), dists.min())
    max_dist = max(projected_dists.max(), dists.max())
    plt.hexbin(dists, projected_dists, gridsize=100, cmap=plt.cm.PuBu,
               extent=[min_dist, max_dist, min_dist, max_dist])
    plt.xlabel("Pairwise squared distances in original space")
    plt.ylabel("Pairwise squared distances in projected space")
    plt.title("Pairwise distances distribution for n_components=%d" %
              n_components)
    cb = plt.colorbar()
    cb.set_label('Sample pairs counts')

    rates = projected_dists / dists
    print("Mean distances rate: %0.2f (%0.2f)"
          % (np.mean(rates), np.std(rates)))

    plt.figure()
    plt.hist(rates, bins=50, range=(0., 2.), edgecolor='k', **density_param)
    plt.xlabel("Squared distances rate: projected / original")
    plt.ylabel("Distribution of samples pairs")
    plt.title("Histogram of pairwise distance rates for n_components=%d" %
              n_components)

    # TODO: compute the expected value of eps and add them to the previous plot
    # as vertical lines / region

plt.show()
Pairwise distances distribution for n_components=1000
Pairwise distances distribution for n_components=10000

Pairwise squared distances in original space

Pairwise squared distances in projected space

Sample pairs counts

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Out:

Embedding 500 samples with dim 130107 using various random projections
Projected 500 samples from 130107 to 300 in 0.277s
Random matrix with size: 1.302MB
Mean distances rate: 0.98 (0.16)
Projected 500 samples from 130107 to 1000 in 0.940s
Random matrix with size: 4.323MB
Mean distances rate: 1.04 (0.11)
Projected 500 samples from 130107 to 10000 in 9.226s
Random matrix with size: 43.287MB
Mean distances rate: 1.00 (0.03)

We can see that for low values of `n_components` the distribution is wide with many distorted pairs and a skewed distribution (due to the hard limit of zero ratio on the left as distances are always positives) while for larger values of `n_components` the distortion is controlled and the distances are well preserved by the random projection.
Remarks

According to the JL lemma, projecting 500 samples without too much distortion will require at least several thousands dimensions, irrespective of the number of features of the original dataset.

Hence using random projections on the digits dataset which only has 64 features in the input space does not make sense: it does not allow for dimensionality reduction in this case.

On the twenty newsgroups on the other hand the dimensionality can be decreased from 56436 down to 10000 while reasonably preserving pairwise distances.

Total running time of the script: 0 minutes 13.612 seconds

6.20.10 Comparison of kernel ridge regression and SVR

Both kernel ridge regression (KRR) and SVR learn a non-linear function by employing the kernel trick, i.e., they learn a linear function in the space induced by the respective kernel which corresponds to a non-linear function in the original space. They differ in the loss functions (ridge versus epsilon-insensitive loss). In contrast to SVR, fitting a KRR can be done in closed-form and is typically faster for medium-sized datasets. On the other hand, the learned model is non-sparse and thus slower than SVR at prediction-time.

This example illustrates both methods on an artificial dataset, which consists of a sinusoidal target function and strong noise added to every fifth datapoint. The first figure compares the learned model of KRR and SVR when both complexity/regularization and bandwidth of the RBF kernel are optimized using grid-search. The learned functions are very similar; however, fitting KRR is approx. seven times faster than fitting SVR (both with grid-search). However, prediction of 100000 target values is more than three times faster with SVR since it has learned a sparse model using only approx. 1/3 of the 100 training datapoints as support vectors.

The next figure compares the time for fitting and prediction of KRR and SVR for different sizes of the training set. Fitting KRR is faster than SVR for medium-sized training sets (less than 1000 samples); however, for larger training sets SVR scales better. With regard to prediction time, SVR is faster than KRR for all sizes of the training set because of the learned sparse solution. Note that the degree of sparsity and thus the prediction time depends on the parameters epsilon and C of the SVR.
SVR versus Kernel Ridge

- SVR (fit: 0.443s, predict: 0.274s)
- KRR (fit: 0.168s, predict: 0.243s)
- SVR support vectors
- data
scikit-learn user guide, Release 0.24.0

Out:

SVR complexity and bandwidth selected and model fitted in 0.443 s
KRR complexity and bandwidth selected and model fitted in 0.168 s
Support vector ratio: 0.320
SVR prediction for 100000 inputs in 0.274 s
KRR prediction for 100000 inputs in 0.243 s

# Authors: Jan Hendrik Metzen <jhm@informatik.uni-bremen.de>
# License: BSD 3 clause

import time
import numpy as np
from sklearn.svm import SVR
from sklearn.model_selection import GridSearchCV
from sklearn.model_selection import learning_curve
from sklearn.kernel_ridge import KernelRidge
import matplotlib.pyplot as plt
scikit-learn user guide, Release 0.24.0

(continued from previous page)

rng = np.random.RandomState(0)
#
#
X
y

#############################################################################
Generate sample data
= 5 * rng.rand(10000, 1)
= np.sin(X).ravel()

# Add noise to targets
y[::5] += 3 * (0.5 - rng.rand(X.shape[0] // 5))
X_plot = np.linspace(0, 5, 100000)[:, None]
# #############################################################################
# Fit regression model
train_size = 100
svr = GridSearchCV(SVR(kernel='rbf', gamma=0.1),
param_grid={"C": [1e0, 1e1, 1e2, 1e3],
"gamma": np.logspace(-2, 2, 5)})
kr = GridSearchCV(KernelRidge(kernel='rbf', gamma=0.1),
param_grid={"alpha": [1e0, 0.1, 1e-2, 1e-3],
"gamma": np.logspace(-2, 2, 5)})
t0 = time.time()
svr.fit(X[:train_size], y[:train_size])
svr_fit = time.time() - t0
print("SVR complexity and bandwidth selected and model fitted in %.3f s"
% svr_fit)
t0 = time.time()
kr.fit(X[:train_size], y[:train_size])
kr_fit = time.time() - t0
print("KRR complexity and bandwidth selected and model fitted in %.3f s"
% kr_fit)
sv_ratio = svr.best_estimator_.support_.shape[0] / train_size
print("Support vector ratio: %.3f" % sv_ratio)
t0 = time.time()
y_svr = svr.predict(X_plot)
svr_predict = time.time() - t0
print("SVR prediction for %d inputs in %.3f s"
% (X_plot.shape[0], svr_predict))
t0 = time.time()
y_kr = kr.predict(X_plot)
kr_predict = time.time() - t0
print("KRR prediction for %d inputs in %.3f s"
% (X_plot.shape[0], kr_predict))

# #############################################################################
# Look at the results
sv_ind = svr.best_estimator_.support_
plt.scatter(X[sv_ind], y[sv_ind], c='r', s=50, label='SVR support vectors',
zorder=2, edgecolors=(0, 0, 0))
plt.scatter(X[:100], y[:100], c='k', label='data', zorder=1,
(continues on next page)

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edgecolors=(0, 0, 0))
plt.plot(X_plot, y_svr, c='r',
        label='SVR (fit: %.3fs, predict: %.3fs)' % (svr_fit, svr_predict))
plt.plot(X_plot, y_kr, c='g',
        label='KRR (fit: %.3fs, predict: %.3fs)' % (kr_fit, kr_predict))
plt.xlabel('data')
plt.ylabel('target')
plt.title('SVR versus Kernel Ridge')
plt.legend()

# Visualize training and prediction time
plt.figure()

# Generate sample data
X = 5 * rng.rand(10000, 1)
y = np.sin(X).ravel()
y[:5] += 3 * (0.5 - rng.rand(X.shape[0] // 5))
sizes = np.logspace(1, 4, 7).astype(int)
for name, estimator in {"KRR": KernelRidge(kernel='rbf', alpha=0.1,
                           gamma=10),
                      "SVR": SVR(kernel='rbf', C=1e1, gamma=10)}.items():
    train_time = []
    test_time = []
    for train_test_size in sizes:
        t0 = time.time()
        estimator.fit(X[:train_test_size], y[:train_test_size])
        train_time.append(time.time() - t0)
        t0 = time.time()
        estimator.predict(X_plot[:1000])
        test_time.append(time.time() - t0)
    plt.plot(sizes, train_time, 'o-', color="r" if name == "SVR" else "g",
             label='%s (train)' % name)
    plt.plot(sizes, test_time, 'o--', color="r" if name == "SVR" else "g",
             label='%s (test)' % name)
plt.xscale("log")
plt.yscale("log")
plt.xlabel("Train size")
plt.ylabel("Time (seconds)")
plt.title("Execution Time")
plt.legend(loc="best")

# Visualize learning curves
plt.figure()
svr = SVR(kernel='rbf', C=1e1, gamma=0.1)
kr = KernelRidge(kernel='rbf', alpha=0.1, gamma=0.1)
train_sizes, train_scores_svr, test_scores_svr = \
    learning_curve(svr, X[:100], y[:100], train_sizes=np.linspace(0.1, 1, 10),
                   scoring="neg_mean_squared_error", cv=10)
train_sizes_abs, train_scores_kr, test_scores_kr = \
    learning_curve(kr, X[:100], y[:100], train_sizes=np.linspace(0.1, 1, 10),
                   scoring="neg_mean_squared_error", cv=10)
plt.plot(train_sizes, -test_scores_svr.mean(1), 'o-', color="r",
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Explicit feature map approximation for RBF kernels

An example illustrating the approximation of the feature map of an RBF kernel.

It shows how to use `RBFSampler` and `Nystroem` to approximate the feature map of an RBF kernel for classification with an SVM on the digits dataset. Results using a linear SVM in the original space, a linear SVM using the approximate mappings and using a kernelized SVM are compared. Timings and accuracy for varying amounts of Monte Carlo samplings (in the case of `RBFSampler`, which uses random Fourier features) and different sized subsets of the training set (for `Nystroem`) for the approximate mapping are shown.

Please note that the dataset here is not large enough to show the benefits of kernel approximation, as the exact SVM is still reasonably fast.

Sampling more dimensions clearly leads to better classification results, but comes at a greater cost. This means there is a tradeoff between runtime and accuracy, given by the parameter `n_components`. Note that solving the Linear SVM and also the approximate kernel SVM could be greatly accelerated by using stochastic gradient descent via `SGDClassifier`. This is not easily possible for the case of the kernelized SVM.

Python package and dataset imports, load dataset

```python
# Author: Gael Varoquaux <gael dot varoquaux at normalesup dot org>
# Andreas Mueller <amueller@ais.uni-bonn.de>
# License: BSD 3 clause

print(__doc__)

# Standard scientific Python imports
import matplotlib.pyplot as plt
import numpy as np
from time import time

# Import datasets, classifiers and performance metrics
from sklearn import datasets, svm, pipeline
from sklearn.kernel_approximation import (RBFSampler, Nystroem)
from sklearn.decomposition import PCA

# The digits dataset
digits = datasets.load_digits(n_class=9)
```
Timing and accuracy plots

To apply an classifier on this data, we need to flatten the image, to turn the data in a (samples, feature) matrix:

```python
n_samples = len(digits.data)
data = digits.data / 16.
data -= data.mean(axis=0)

# We learn the digits on the first half of the digits
data_train, targets_train = (data[:n_samples // 2],
                           digits.target[:n_samples // 2])

# Now predict the value of the digit on the second half:
data_test, targets_test = (data[n_samples // 2:],
                          digits.target[n_samples // 2:])
# data_test = scaler.transform(data_test)

# Create a classifier: a support vector classifier
kernel_svm = svm.SVC(gamma=.2)
linear_svm = svm.LinearSVC()

# create pipeline from kernel approximation
# and linear svm
feature_map_fourier = RBFSampler(gamma=.2, random_state=1)
feature_map_nystroem = Nystroem(gamma=.2, random_state=1)
fourier_approx_svm = pipeline.Pipeline([("feature_map", feature_map_fourier),
                                        ("svm", svm.LinearSVC())])
nystroem_approx_svm = pipeline.Pipeline([("feature_map", feature_map_nystroem),
                                         ("svm", svm.LinearSVC())])

# fit and predict using linear and kernel svm:
kernel_svm_time = time()
kernel_svm.fit(data_train, targets_train)
kernel_svm_score = kernel_svm.score(data_test, targets_test)
kernel_svm_time = time() - kernel_svm_time

linear_svm_time = time()
linear_svm.fit(data_train, targets_train)
linear_svm_score = linear_svm.score(data_test, targets_test)
linear_svm_time = time() - linear_svm_time

sample_sizes = 30 * np.arange(1, 10)
fourier_scores = []
nystroem_scores = []
fourier_times = []
nystroem_times = []

for D in sample_sizes:
    fourier_approx_svm.set_params(feature_map__n_components=D)
nystroem_approx_svm.set_params(feature_map__n_components=D)
    start = time()
nystroem_approx_svm.fit(data_train, targets_train)
nystroem_times.append(time() - start)
    start = time()```

(continues on next page)
```python
fourier_approx_svm.fit(data_train, targets_train)
fourier_times.append(time() - start)

fourier_score = fourier_approx_svm.score(data_test, targets_test)
nystroem_score = nystroem_approx_svm.score(data_test, targets_test)
nystroem_scores.append(nystroem_score)
fourier_scores.append(fourier_score)

# plot the results:
plt.figure(figsize=(16, 4))
accuracy = plt.subplot(121)
# second y axis for timings
timescale = plt.subplot(122)

accuracy.plot(sample_sizes, nystroem_scores, label="Nystroem approx. kernel")
timescale.plot(sample_sizes, nystroem_times, '--', label='Nystroem approx. kernel')

accuracy.plot(sample_sizes, fourier_scores, label="Fourier approx. kernel")
timescale.plot(sample_sizes, fourier_times, '--', label='Fourier approx. kernel')

# horizontal lines for exact rbf and linear kernels:
accuracy.plot([sample_sizes[0], sample_sizes[-1]],
              [linear_svm_score, linear_svm_score], label="linear svm")
timescale.plot([sample_sizes[0], sample_sizes[-1]],
              [linear_svm_time, linear_svm_time], '--', label='linear svm')

accuracy.plot([sample_sizes[0], sample_sizes[-1]],
              [kernel_svm_score, kernel_svm_score], label="rbf svm")
timescale.plot([sample_sizes[0], sample_sizes[-1]],
              [kernel_svm_time, kernel_svm_time], '--', label='rbf svm')

# vertical line for dataset dimensionality = 64
accuracy.plot([64, 64], [0.7, 1], label="n_features")

# legends and labels
accuracy.set_title("Classification accuracy")
timescale.set_title("Training times")
accuracy.set_xlim(sample_sizes[0], sample_sizes[-1])
accuracy.set_xticks(())
accuracy.set_ylim(np.min(fourier_scores), 1)
timescale.set_xlim(np.min(fourier_scores), 1)
timescale.set_xlabel("Sampling steps = transformed feature dimension")
accuracy.set_ylabel("Classification accuracy")
timescale.set_ylabel("Training time in seconds")
accuracy.legend(loc='best')
timescale.legend(loc='best')
plt.tight_layout()
plt.show()
```
Decision Surfaces of RBF Kernel SVM and Linear SVM

The second plot visualized the decision surfaces of the RBF kernel SVM and the linear SVM with approximate kernel maps. The plot shows decision surfaces of the classifiers projected onto the first two principal components of the data. This visualization should be taken with a grain of salt since it is just an interesting slice through the decision surface in 64 dimensions. In particular note that a datapoint (represented as a dot) does not necessarily be classified into the region it is lying in, since it will not lie on the plane that the first two principal components span. The usage of RBFSampler and Nystroem is described in detail in Kernel Approximation.

```python
# visualize the decision surface, projected down to the first
# two principal components of the dataset
pca = PCA(n_components=8).fit(data_train)
X = pca.transform(data_train)

# Generate grid along first two principal components
multiples = np.arange(-2, 2, 0.1)
# steps along first component
first = multiples[:, np.newaxis] * pca.components_[0, :]
# steps along second component
second = multiples[:, np.newaxis] * pca.components_[1, :]
# combine
grid = first[np.newaxis, :, :] + second[:, np.newaxis, :]
flat_grid = grid.reshape(-1, data.shape[1])

# title for the plots
titles = ['SVC with rbf kernel',
          'SVC (linear kernel) with Fourier rbf feature map
           n_components=100',
          'SVC (linear kernel) with Nystroem rbf feature map
           n_components=100']

plt.figure(figsize=(18, 7.5))
plt.rcParams.update({'font.size': 14})
# predict and plot
for i, clf in enumerate((kernel_svm, nystroem_approx_svm,
                         fourier_approx_svm)):
    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]x[y_min, y_max].
    plt.subplot(1, 3, i + 1)
    Z = clf.predict(flat_grid)

    # Put the result into a color plot
    Z = Z.reshape(grid.shape[:-1])
    plt.contourf(multiples, multiples, Z, cmap=plt.cm.Paired)
```

(continues on next page)
plt.axis('off')

# Plot also the training points
plt.scatter(X[:, 0], X[:, 1], c=targets_train, cmap=plt.cm.Paired,
            edgecolors=(0, 0, 0))

plt.title(titles[i])
plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 1.476 seconds)

6.21 Missing Value Imputation

Examples concerning the `sklearn.impute` module.

6.21.1 Imputing missing values with variants of IterativeImputer

The `IterativeImputer` class is very flexible - it can be used with a variety of estimators to do round-robin regression, treating every variable as an output in turn.

In this example we compare some estimators for the purpose of missing feature imputation with `IterativeImputer`:

- `BayesianRidge`: regularized linear regression
- `DecisionTreeRegressor`: non-linear regression
- `ExtraTreesRegressor`: similar to missForest in R
- `KNeighborsRegressor`: comparable to other KNN imputation approaches

Of particular interest is the ability of `IterativeImputer` to mimic the behavior of missForest, a popular imputation package for R. In this example, we have chosen to use `ExtraTreesRegressor` instead of `RandomForestRegressor` (as in missForest) due to its increased speed.

Note that `KNeighborsRegressor` is different from KNN imputation, which learns from samples with missing values by using a distance metric that accounts for missing values, rather than imputing them.
The goal is to compare different estimators to see which one is best for the `IterativeImputer` when using a `BayesianRidge` estimator on the California housing dataset with a single value randomly removed from each row. For this particular pattern of missing values we see that `ExtraTreesRegressor` and `BayesianRidge` give the best results.

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
import pandas as pd

# To use this experimental feature, we need to explicitly ask for it:
from sklearn.experimental import enable_iterative_imputer  # noqa
from sklearn.datasets import fetch_california_housing
from sklearn.impute import SimpleImputer
from sklearn.impute import IterativeImputer
from sklearn.linear_model import BayesianRidge
from sklearn.tree import DecisionTreeRegressor
from sklearn.ensemble import ExtraTreesRegressor
from sklearn.neighbors import KNeighborsRegressor
from sklearn.pipeline import make_pipeline
from sklearn.model_selection import cross_val_score

N_SPLITS = 5
rng = np.random.RandomState(0)

X_full, y_full = fetch_california_housing(return_X_y=True)
# ~2k samples is enough for the purpose of the example.
# Remove the following two lines for a slower run with different error bars.
X_full = X_full[::10]
y_full = y_full[::10]
n_samples, n_features = X_full.shape

# Estimate the score on the entire dataset, with no missing values
br_estimator = BayesianRidge()
score_full_data = pd.DataFrame(
    cross_val_score(br_estimator, X_full, y_full, cv=N_SPLITS)
)
```

(continues on next page)
cross_val_score(
    br_estimator, X_full, y_full, scoring='neg_mean_squared_error',
    cv=N_SPLITS
),
    columns=['Full Data'])

# Add a single missing value to each row
X_missing = X_full.copy()
y_missing = y_full
missing_samples = np.arange(n_samples)
missing_features = rng.choice(n_features, n_samples, replace=True)
X_missing[missing_samples, missing_features] = np.nan

# Estimate the score after imputation (mean and median strategies)
score_simple_imputer = pd.DataFrame()
for strategy in ('mean', 'median'):
estimator = make_pipeline(
    SimpleImputer(missing_values=np.nan, strategy=strategy),
    br_estimator
)
score_simple_imputer[strategy] = cross_val_score(
    estimator, X_missing, y_missing, scoring='neg_mean_squared_error',
    cv=N_SPLITS
)

# Estimate the score after iterative imputation of the missing values
# with different estimators
estimators = [
    BayesianRidge(),
    DecisionTreeRegressor(max_features='sqrt', random_state=0),
    ExtraTreesRegressor(n_estimators=10, random_state=0),
    KNeighborsRegressor(n_neighbors=15)
]
score_iterative_imputer = pd.DataFrame()
for impute_estimator in estimators:
estimator = make_pipeline(
    IterativeImputer(random_state=0, estimator=impute_estimator),
    br_estimator
)
score_iterative_imputer[impute_estimator.__class__.__name__] = \
cross_val_score(
    estimator, X_missing, y_missing, scoring='neg_mean_squared_error',
    cv=N_SPLITS
)
scores = pd.concat(
    [score_full_data, score_simple_imputer, score_iterative_imputer],
    keys=['Original', 'SimpleImputer', 'IterativeImputer'], axis=1
)

# plot california housing results
fig, ax = plt.subplots(figsize=(13, 6))
means = -scores.mean()
errors = scores.std()
means.plot.barh(xerr=errors, ax=ax)
ax.set_title('California Housing Regression with Different Imputation Methods')
6.21.2 Imputing missing values before building an estimator

Missing values can be replaced by the mean, the median or the most frequent value using the basic `SimpleImputer`. In this example we will investigate different imputation techniques:

- imputation by the constant value 0
- imputation by the mean value of each feature combined with a missing-ness indicator auxiliary variable
- k nearest neighbor imputation
- iterative imputation

We will use two datasets: Diabetes dataset which consists of 10 feature variables collected from diabetes patients with an aim to predict disease progression and California Housing dataset for which the target is the median house value for California districts.

As neither of these datasets have missing values, we will remove some values to create new versions with artificially missing data. The performance of `RandomForestRegressor` on the full original dataset is then compared the performance on the altered datasets with the artificially missing values imputed using different techniques.

```python
print(__doc__)

# Authors: Maria Telenczuk <https://github.com/maikia>
# License: BSD 3 clause
```

### Download the data and make missing values sets

First we download the two datasets. Diabetes dataset is shipped with scikit-learn. It has 442 entries, each with 10 features. California Housing dataset is much larger with 20640 entries and 8 features. It needs to be downloaded. We will only use the first 400 entries for the sake of speeding up the calculations but feel free to use the whole dataset.

```python
import numpy as np

from sklearn.datasets import fetch_california_housing
from sklearn.datasets import load_diabetes

rng = np.random.RandomState(42)

X_diabetes, y_diabetes = load_diabetes(return_X_y=True)
X_california, y_california = fetch_california_housing(return_X_y=True)
X_california = X_california[:400]
y_california = y_california[:400]
```
def add_missing_values(X_full, y_full):
    n_samples, n_features = X_full.shape

    # Add missing values in 75% of the lines
    missing_rate = 0.75
    n_missing_samples = int(n_samples * missing_rate)

    missing_samples = np.zeros(n_samples, dtype=bool)
    missing_samples[: n_missing_samples] = True

    rng.shuffle(missing_samples)
    missing_features = rng.randint(0, n_features, n_missing_samples)
    X_missing = X_full.copy()
    X_missing[missing_samples, missing_features] = np.nan
    y_missing = y_full.copy()

    return X_missing, y_missing

X_miss_california, y_miss_california = add_missing_values(
    X_california, y_california)
X_miss_diabetes, y_miss_diabetes = add_missing_values(
    X_diabetes, y_diabetes)

Impute the missing data and score

Now we will write a function which will score the results on the differently imputed data. Let’s look at each imputer separately:

rng = np.random.RandomState(0)

from sklearn.ensemble import RandomForestRegressor

# To use the experimental IterativeImputer, we need to explicitly ask for it:
from sklearn.experimental import enable_iterative_imputer  # noqa
from sklearn.impute import SimpleImputer, KNNImputer, IterativeImputer
from sklearn.model_selection import cross_val_score
from sklearn.pipeline import make_pipeline

N_SPLITS = 5
regressor = RandomForestRegressor(random_state=0)
Missing information

In addition to imputing the missing values, the imputers have an `add_indicator` parameter that marks the values that were missing, which might carry some information.

```python
def get_scores_for_imputer(imputer, X_missing, y_missing):
    estimator = make_pipeline(imputer, regressor)
    impute_scores = cross_val_score(estimator, X_missing, y_missing,
                                      scoring='neg_mean_squared_error',
                                      cv=N_SPLITS)
    return impute_scores

x_labels = ['Full data',
            'Zero imputation',
            'Mean Imputation',
            'KNN Imputation',
            'Iterative Imputation']

mses_california = np.zeros(5)
stds_california = np.zeros(5)
mses_diabetes = np.zeros(5)
stds_diabetes = np.zeros(5)

Estimate the score

First, we want to estimate the score on the original data:

```python
def get_full_score(X_full, y_full):
    full_scores = cross_val_score(regressor, X_full, y_full,
                                   scoring='neg_mean_squared_error',
                                   cv=N_SPLITS)
    return full_scores.mean(), full_scores.std()

mses_california[0], stds_california[0] = get_full_score(X_california,
                                                        y_california)
mses_diabetes[0], stds_diabetes[0] = get_full_score(X_diabetes, y_diabetes)
```

Replace missing values by 0

Now we will estimate the score on the data where the missing values are replaced by 0:

```python
def get_impute_zero_score(X_missing, y_missing):
    imputer = SimpleImputer(missing_values=np.nan, add_indicator=True,
                            strategy='constant', fill_value=0)
    zero_impute_scores = get_scores_for_imputer(imputer, X_missing, y_missing)
    return zero_impute_scores.mean(), zero_impute_scores.std()

mses_california[1], stds_california[1] = get_impute_zero_score(
                                          X_miss_california, y_miss_california)
```

(continues on next page)
mses_diabetes[1], stds_diabetes[1] = get_impute_zero_score(X_miss_diabetes, y_miss_diabetes)

### kNN-imputation of the missing values

*KNNImputer* imputes missing values using the weighted or unweighted mean of the desired number of nearest neighbors.

```python
def get_impute_knn_score(X_missing, y_missing):
    imputer = KNNImputer(missing_values=np.nan, add_indicator=True)
    knn_impute_scores = get_scores_for_imputer(imputer, X_missing, y_missing)
    return knn_impute_scores.mean(), knn_impute_scores.std()
```

mses_california[2], stds_california[2] = get_impute_knn_score(X_miss_california, y_miss_california)
mses_diabetes[2], stds_diabetes[2] = get_impute_knn_score(X_miss_diabetes, y_miss_diabetes)

### Impute missing values with mean

```python
def get_impute_mean(X_missing, y_missing):
    imputer = SimpleImputer(missing_values=np.nan, strategy="mean",
                            add_indicator=True)
    mean_impute_scores = get_scores_for_imputer(imputer, X_missing, y_missing)
    return mean_impute_scores.mean(), mean_impute_scores.std()
```

mses_california[3], stds_california[3] = get_impute_mean(X_miss_california, y_miss_california)
mses_diabetes[3], stds_diabetes[3] = get_impute_mean(X_miss_diabetes, y_miss_diabetes)

### Iterative imputation of the missing values

Another option is the *IterativeImputer*. This uses round-robin linear regression, modeling each feature with missing values as a function of other features, in turn. The version implemented assumes Gaussian (output) variables. If your features are obviously non-normal, consider transforming them to look more normal to potentially improve performance.

```python
def get_impute_iterative(X_missing, y_missing):
    imputer = IterativeImputer(missing_values=np.nan, add_indicator=True,
                               random_state=0, n_nearest_features=5,
                               sample_posterior=True)
    iterative_impute_scores = get_scores_for_imputer(imputer, X_missing, y_missing)
    return iterative_impute_scores.mean(), iterative_impute_scores.std()
```

(continues on next page)
mses_california[4], stds_california[4] = get_impute_iterative(
    X_miss_california, y_miss_california)
mses_diabetes[4], stds_diabetes[4] = get_impute_iterative(X_miss_diabetes,
    y_miss_diabetes)

mses_diabetes = mses_diabetes * -1
mses_california = mses_california * -1

Plot the results

Finally we are going to visualize the score:

```python
import matplotlib.pyplot as plt

n_bars = len(mses_diabetes)
xval = np.arange(n_bars)

colors = ['r', 'g', 'b', 'orange', 'black']

# plot diabetes results
plt.figure(figsize=(12, 6))
ax1 = plt.subplot(121)
for j in xval:
    ax1.barh(j, mses_diabetes[j], xerr=stds_diabetes[j],
      color=colors[j], alpha=0.6, align='center')
ax1.set_title('Imputation Techniques with Diabetes Data')
ax1.set_xlim(left=np.min(mses_diabetes) * 0.9,
        right=np.max(mses_diabetes) * 1.1)
ax1.set_yticks(xval)
ax1.set_xlabel('MSE')
ax1.invert_yaxis()
ax1.set_yticklabels(x_labels)

# plot california dataset results
ax2 = plt.subplot(122)
for j in xval:
    ax2.barh(j, mses_california[j], xerr=stds_california[j],
      color=colors[j], alpha=0.6, align='center')
ax2.set_title('Imputation Techniques with California Data')
ax2.set_xticks(xval)
ax2.set_xlabel('MSE')
ax2.invert_yaxis()
ax2.set_yticklabels([''] * n_bars)

plt.show()

# You can also try different techniques. For instance, the median is a more
# robust estimator for data with high magnitude variables which could dominate
# results (otherwise known as a 'long tail').
Total running time of the script: ( 0 minutes 16.477 seconds)

6.22 Model Selection

Examples related to the `sklearn.model_selection` module.

6.22.1 Plotting Cross-Validated Predictions

This example shows how to use `cross_val_predict` to visualize prediction errors.
from sklearn import datasets
from sklearn.model_selection import cross_val_predict
from sklearn import linear_model
import matplotlib.pyplot as plt

lr = linear_model.LinearRegression()
X, y = datasets.load_diabetes(return_X_y=True)

# cross_val_predict returns an array of the same size as `y` where each entry
# is a prediction obtained by cross validation:
predicted = cross_val_predict(lr, X, y, cv=10)

fig, ax = plt.subplots()
ax.scatter(y, predicted, edgecolors=(0, 0, 0))
ax.plot([y.min(), y.max()], [y.min(), y.max()], 'k--', lw=4)
ax.set_xlabel('Measured')
ax.set_ylabel('Predicted')
plt.show()

Total running time of the script: ( 0 minutes 0.107 seconds)
6.22.2 Confusion matrix

Example of confusion matrix usage to evaluate the quality of the output of a classifier on the iris data set. The diagonal elements represent the number of points for which the predicted label is equal to the true label, while off-diagonal elements are those that are mislabeled by the classifier. The higher the diagonal values of the confusion matrix the better, indicating many correct predictions.

The figures show the confusion matrix with and without normalization by class support size (number of elements in each class). This kind of normalization can be interesting in case of class imbalance to have a more visual interpretation of which class is being misclassified.

Here the results are not as good as they could be as our choice for the regularization parameter C was not the best. In real life applications this parameter is usually chosen using Tuning the hyper-parameters of an estimator.
Out:

Confusion matrix, without normalization

[[13  0  0]
 [ 0 10  6]
 [ 0  0  9]]

Normalized confusion matrix

[[1.  0.  0. ]
 [0. 0.62 0.38]
 [0. 0.  1. ]]

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm, datasets
from sklearn.model_selection import train_test_split
from sklearn.metrics import plot_confusion_matrix

# import some data to play with
iris = datasets.load_iris()
```
X = iris.data
y = iris.target
class_names = iris.target_names

# Split the data into a training set and a test set
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)

# Run classifier, using a model that is too regularized (C too low) to see
# the impact on the results
classifier = svm.SVC(kernel='linear', C=0.01).fit(X_train, y_train)

np.set_printoptions(precision=2)
# Plot non-normalized confusion matrix
titles_options = ["Confusion matrix, without normalization", None],
                  ["Normalized confusion matrix", 'true'])
for title, normalize in titles_options:
    disp = plot_confusion_matrix(classifier, X_test, y_test,
                                  display_labels=class_names,
                                  cmap=plt.cm.Blues,
                                  normalize=normalize)
    disp.ax_.set_title(title)
    print(title)
    print(disp.confusion_matrix)
plt.show()

Total running time of the script: ( 0 minutes 0.238 seconds)

6.22.3 Plotting Validation Curves

In this plot you can see the training scores and validation scores of an SVM for different values of the kernel parameter gamma. For very low values of gamma, you can see that both the training score and the validation score are low. This is called underfitting. Medium values of gamma will result in high values for both scores, i.e. the classifier is performing fairly well. If gamma is too high, the classifier will overfit, which means that the training score is good but the validation score is poor.
import matplotlib.pyplot as plt
import numpy as np
from sklearn.datasets import load_digits
from sklearn.svm import SVC
from sklearn.model_selection import validation_curve

X, y = load_digits(return_X_y=True)
param_range = np.logspace(-6, -1, 5)
train_scores, test_scores = validation_curve(SVC(), X, y, param_name="gamma", param_range=param_range, scoring="accuracy", n_jobs=1)
train_scores_mean = np.mean(train_scores, axis=1)
train_scores_std = np.std(train_scores, axis=1)
test_scores_mean = np.mean(test_scores, axis=1)
test_scores_std = np.std(test_scores, axis=1)

plt.title("Validation Curve with SVM")
plt.xscale('log')
plt.xlabel(r"$\gamma$")
plt.ylabel("Score")
plt.ylim(0.0, 1.1)
lw = 2
In this example, we compare receiver operating characteristic (ROC) and detection error tradeoff (DET) curves for different classification algorithms for the same classification task.

DET curves are commonly plotted in normal deviate scale. To achieve this, `plot_det_curve` transforms the error rates as returned by the `det_curve` and the axis scale using `scipy.stats.norm`.

The point of this example is to demonstrate two properties of DET curves, namely:

1. It might be easier to visually assess the overall performance of different classification algorithms using DET curves over ROC curves. Due to the linear scale used for plotting ROC curves, different classifiers usually only differ in the top left corner of the graph and appear similar for a large part of the plot. On the other hand, because DET curves represent straight lines in normal deviate scale. As such, they tend to be distinguishable as a whole and the area of interest spans a large part of the plot.

2. DET curves give the user direct feedback of the detection error tradeoff to aid in operating point analysis. The user can deduct directly from the DET-curve plot at which rate false-negative error rate will improve when willing to accept an increase in false-positive error rate (or vice-versa).

The plots in this example compare ROC curves on the left side to corresponding DET curves on the right. There is no particular reason why these classifiers have been chosen for the example plot over other classifiers available in scikit-learn.

**6.22.4 Detection error tradeoff (DET) curve**

Note:

- See `sklearn.metrics.roc_curve` for further information about ROC curves.
- See `sklearn.metrics.det_curve` for further information about DET curves.
- This example is loosely based on Classifier comparison example.
import matplotlib.pyplot as plt

from sklearn.datasets import make_classification
from sklearn.ensemble import RandomForestClassifier
from sklearn.metrics import plot_det_curve
from sklearn.metrics import plot_roc_curve
from sklearn.model_selection import train_test_split
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import StandardScaler
from sklearn.svm import LinearSVC

N_SAMPLES = 1000

classifiers = {
    "Linear SVM": make_pipeline(StandardScaler(), LinearSVC(C=0.025)),
    "Random Forest": RandomForestClassifier(max_depth=5, n_estimators=10, max_features=1),
}

X, y = make_classification(n_samples=N_SAMPLES, n_features=2, n_redundant=0, n_informative=2, 
    random_state=1, n_clusters_per_class=1)

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=.4, random_state=0)

# prepare plots
fig, [ax_roc, ax_det] = plt.subplots(1, 2, figsize=(11, 5))

for name, clf in classifiers.items():
    clf.fit(X_train, y_train)

    plot_roc_curve(clf, X_test, y_test, ax=ax_roc, name=name)
    plot_det_curve(clf, X_test, y_test, ax=ax_det, name=name)

ax_roc.set_title('Receiver Operating Characteristic (ROC) curves')
ax_det.set_title('Detection Error Tradeoff (DET) curves')

(continues on next page)
6.22.5 Successive Halving Iterations

This example illustrates how a successive halving search (HalvingGridSearchCV and HalvingRandomSearchCV) iteratively chooses the best parameter combination out of multiple candidates.

```python
import pandas as pd
from sklearn import datasets
import matplotlib.pyplot as plt
from scipy.stats import randint
import numpy as np
from sklearn.experimental import enable_halving_search_cv  # noqa
from sklearn.model_selection import HalvingRandomSearchCV
from sklearn.ensemble import RandomForestClassifier

print(__doc__)

We first define the parameter space and train a HalvingRandomSearchCV instance.

```python
rng = np.random.RandomState(0)
X, y = datasets.make_classification(n_samples=700, random_state=rng)
clf = RandomForestClassifier(n_estimators=20, random_state=rng)

param_dist = {
    "max_depth": [3, None],
    "max_features": randint(1, 11),
    "min_samples_split": randint(2, 11),
    "bootstrap": [True, False],
    "criterion": ["gini", "entropy"]
}

rsh = HalvingRandomSearchCV(
    estimator=clf,
    param_distributions=param_dist,
    factor=2,
    random_state=rng)
rsh.fit(X, y)
```

We can now use the cv_results_ attribute of the search estimator to inspect and plot the evolution of the search.

```python
results = pd.DataFrame(rsh.cv_results_)
results["params_str"] = results.params.apply(str)
results.drop_duplicates(subset=('params_str', 'iter'), inplace=True)
mean_scores = results.pivot(index='iter', columns='params_str',
                           values='mean_test_score')
```

(continues on next page)
```python
ax = mean_scores.plot(legend=False, alpha=.6)

labels = [
    f'iter={i}\nn_samples={rsh.n_resources_[i]}\n'
    f'n_candidates={rsh.n_candidates_[i]}'
    for i in range(rsh.n_iterations_)
]
ax.set_xticks(range(rsh.n_iterations_))
ax.set_xticklabels(labels, rotation=45, multialignment='left')
ax.set_title('Scores of candidates over iterations')
ax.set_ylabel('mean test score', fontsize=15)
ax.set_xlabel('iterations', fontsize=15)
plt.tight_layout()
plt.show()
```

Scores of candidates over iterations
Number of candidates and amount of resource at each iteration

At the first iteration, a small amount of resources is used. The resource here is the number of samples that the estimators are trained on. All candidates are evaluated.

At the second iteration, only the best half of the candidates is evaluated. The number of allocated resources is doubled: candidates are evaluated on twice as many samples.

This process is repeated until the last iteration, where only 2 candidates are left. The best candidate is the candidate that has the best score at the last iteration.

Total running time of the script: 0 minutes 9.028 seconds

6.22.6 Underfitting vs. Overfitting

This example demonstrates the problems of underfitting and overfitting and how we can use linear regression with polynomial features to approximate nonlinear functions. The plot shows the function that we want to approximate, which is a part of the cosine function. In addition, the samples from the real function and the approximations of different models are displayed. The models have polynomial features of different degrees. We can see that a linear function (polynomial with degree 1) is not sufficient to fit the training samples. This is called underfitting. A polynomial of degree 4 approximates the true function almost perfectly. However, for higher degrees the model will overfit the training data, i.e. it learns the noise of the training data. We evaluate quantitatively overfitting / underfitting by using cross-validation. We calculate the mean squared error (MSE) on the validation set, the higher, the less likely the model generalizes correctly from the training data.

```
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.pipeline import Pipeline
from sklearn.preprocessing import PolynomialFeatures
from sklearn.linear_model import LinearRegression
from sklearn.model_selection import cross_val_score

def true_fun(X):
    return np.cos(1.5 * np.pi * X)

np.random.seed(0)
```
n_samples = 30
degrees = [1, 4, 15]

X = np.sort(np.random.rand(n_samples))
y = true_fun(X) + np.random.randn(n_samples) + 0.1

plt.figure(figsize=(14, 5))
for i in range(len(degrees)):
    ax = plt.subplot(1, len(degrees), i + 1)
    plt.setp(ax, xticks=(), yticks=())

    polynomial_features = PolynomialFeatures(degree=degrees[i],
                                              include_bias=False)

    linear_regression = LinearRegression()
    pipeline = Pipeline([
        ('polynomial_features', polynomial_features),
        ('linear_regression', linear_regression)]
    )
    pipeline.fit(X[:, np.newaxis], y)

    # Evaluate the models using crossvalidation
    scores = cross_val_score(pipeline, X[:, np.newaxis], y,
                              scoring="neg_mean_squared_error", cv=10)

    X_test = np.linspace(0, 1, 100)
    plt.plot(X_test, pipeline.predict(X_test[:, np.newaxis]), label="Model")
    plt.plot(X_test, true_fun(X_test), label="True function")
    plt.scatter(X, y, edgecolor='b', s=20, label="Samples")
    plt.xlabel("x")
    plt.ylabel("y")
    plt.xlim((0, 1))
    plt.ylim((-2, 2))
    plt.legend(loc="best")
    plt.title("Degree {}
              MSE = {:.2e} (+/- {:.2e})".format(
                              degrees[i], -scores.mean(), scores.std()))
plt.show()
Grid scores on development set:

- 0.986 (+/-0.016) for {'C': 1, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.959 (+/-0.028) for {'C': 1, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.988 (+/-0.017) for {'C': 10, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.982 (+/-0.026) for {'C': 10, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.988 (+/-0.017) for {'C': 100, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.983 (+/-0.026) for {'C': 100, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.988 (+/-0.017) for {'C': 1000, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.983 (+/-0.026) for {'C': 1000, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.974 (+/-0.012) for {'C': 1, 'kernel': 'linear'}
- 0.974 (+/-0.012) for {'C': 10, 'kernel': 'linear'}
- 0.974 (+/-0.012) for {'C': 100, 'kernel': 'linear'}
- 0.974 (+/-0.012) for {'C': 1000, 'kernel': 'linear'}

Detailed classification report:

The model is trained on the full development set.
The scores are computed on the full evaluation set.

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
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<tbody>
<tr>
<td>0</td>
<td>1.00</td>
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</table>

accuracy 0.99 899
macro avg 0.99 0.99 0.99 899
weighted avg 0.99 0.99 0.99 899

# Tuning hyper-parameters for recall

Best parameters set found on development set:

{'C': 10, 'gamma': 0.001, 'kernel': 'rbf'}

Grid scores on development set:

- 0.986 (+/-0.019) for {'C': 1, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.957 (+/-0.028) for {'C': 1, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.987 (+/-0.019) for {'C': 10, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.981 (+/-0.028) for {'C': 10, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.987 (+/-0.019) for {'C': 100, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.982 (+/-0.026) for {'C': 100, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.987 (+/-0.019) for {'C': 1000, 'gamma': 0.001, 'kernel': 'rbf'}
- 0.982 (+/-0.026) for {'C': 1000, 'gamma': 0.0001, 'kernel': 'rbf'}
- 0.971 (+/-0.010) for {'C': 1, 'kernel': 'linear'}
- 0.971 (+/-0.010) for {'C': 10, 'kernel': 'linear'}
- 0.971 (+/-0.010) for {'C': 100, 'kernel': 'linear'}
0.971 (+/-0.010) for {'C': 1000, 'kernel': 'linear'}

Detailed classification report:

The model is trained on the full development set. The scores are computed on the full evaluation set.

<table>
<thead>
<tr>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
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<tbody>
<tr>
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<tr>
<td>0.99</td>
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<td>92</td>
</tr>
</tbody>
</table>

accuracy 0.99 899
macro avg 0.99 0.99 0.99 899
weighted avg 0.99 0.99 0.99 899

```python
from sklearn import datasets
from sklearn.model_selection import train_test_split
from sklearn.model_selection import GridSearchCV
from sklearn.metrics import classification_report
from sklearn.svm import SVC

print(__doc__)

# Loading the Digits dataset
digits = datasets.load_digits()

# To apply an classifier on this data, we need to flatten the image, to
# turn the data in a (samples, feature) matrix:
n_samples = len(digits.images)
X = digits.images.reshape((n_samples, -1))
y = digits.target

# Split the dataset in two equal parts
X_train, X_test, y_train, y_test = train_test_split(
    X, y, test_size=0.5, random_state=0)

# Set the parameters by cross-validation
tuned_parameters = [{'kernel': ['rbf'], 'gamma': [1e-3, 1e-4],
    'C': [1, 10, 100, 1000]},
    {'kernel': ['linear'], 'C': [1, 10, 100, 1000]}]

scores = ['precision', 'recall']
```
for score in scores:
    print("# Tuning hyper-parameters for \$s\" % score)
    print()
    clf = GridSearchCV(SVC(), tuned_parameters, scoring='\$s\_macro\" % score
    clf.fit(X_train, y_train)

    print("Best parameters set found on development set:")
    print()
    print(clf.best_params_)
    print()
    print("Grid scores on development set:")
    print()
    means = clf.cv_results_['mean_test_score']
    stds = clf.cv_results_['std_test_score']
    for mean, std, params in zip(means, stds, clf.cv_results_['params']):
        print("%0.3f (+/-%0.03f) for \$r\" % (mean, std * 2, params))
        print()

    print("Detailed classification report:")
    print()
    print("The model is trained on the full development set.")
    print("The scores are computed on the full evaluation set.")
    print()
    y_true, y_pred = y_test, clf.predict(X_test)
    print(classification_report(y_true, y_pred))
    print()

    # Note the problem is too easy: the hyperparameter plateau is too flat and the
    # output model is the same for precision and recall with ties in quality.

Total running time of the script: (0 minutes 3.828 seconds)

6.22.8 Comparing randomized search and grid search for hyperparameter estimation

Compare randomized search and grid search for optimizing hyperparameters of a linear SVM with SGD training. All parameters that influence the learning are searched simultaneously (except for the number of estimators, which poses a time / quality tradeoff).

The randomized search and the grid search explore exactly the same space of parameters. The result in parameter settings is quite similar, while the run time for randomized search is drastically lower.

The performance may slightly worse for the randomized search, and is likely due to a noise effect and would not carry over to a held-out test set.

Note that in practice, one would not search over this many different parameters simultaneously using grid search, but pick only the ones deemed most important.

Out:
RandomizedSearchCV took 19.92 seconds for 20 candidates parameter settings.
Model with rank: 1
Mean validation score: 0.920 (std: 0.028)
Parameters: {'alpha': 0.07316411520495676, 'average': False, 'l1_ratio': 0.29007760721044407}

Model with rank: 2
Mean validation score: 0.920 (std: 0.029)
Parameters: {'alpha': 0.0005223493320259539, 'average': True, 'l1_ratio': 0.7936977033574206}

Model with rank: 3
Mean validation score: 0.918 (std: 0.031)
Parameters: {'alpha': 0.00025790124268693137, 'average': True, 'l1_ratio': 0.5699649107012649}

GridSearchCV took 105.31 seconds for 100 candidate parameter settings.
Model with rank: 1
Mean validation score: 0.931 (std: 0.026)
Parameters: {'alpha': 0.0001, 'average': True, 'l1_ratio': 0.0}

Model with rank: 2
Mean validation score: 0.928 (std: 0.030)
Parameters: {'alpha': 0.0001, 'average': True, 'l1_ratio': 0.1111111111111111}

Model with rank: 3
Mean validation score: 0.927 (std: 0.026)
Parameters: {'alpha': 0.0001, 'average': True, 'l1_ratio': 0.5555555555555556}

```python
print(__doc__)

import numpy as np
from time import time
import scipy.stats as stats
from sklearn.utils.fixes import loguniform
from sklearn.model_selection import GridSearchCV, RandomizedSearchCV
from sklearn.datasets import load_digits
from sklearn.linear_model import SGDClassifier

# get some data
X, y = load_digits(return_X_y=True)

# build a classifier
clf = SGDClassifier(loss='hinge', penalty='elasticnet', fit_intercept=True)

# Utility function to report best scores
def report(results, n_top=3):
    for i in range(1, n_top + 1):
        print(f"Model with rank: {i}
Mean validation score: {results[i - 1].mean(n=3)} (std: {results[i - 1].std(n=3)})
Parameters: {results[i - 1].params}
")
```

(continues on next page)
candidates = np.flatnonzero(results['rank_test_score'] == i)
for candidate in candidates:
    print("Model with rank: {0}".format(i))
    print("Mean validation score: {0:.3f} (std: {1:.3f})".
          format(results['mean_test_score'][candidate],
                 results['std_test_score'][candidate]))
    print("Parameters: {0}".format(results['params'][candidate]))
    print("\n")

# specify parameters and distributions to sample from
param_dist = {'average': [True, False],
              'l1_ratio': stats.uniform(0, 1),
              'alpha': loguniform(1e-4, 1e0)}

# run randomized search
n_iter_search = 20
random_search = RandomizedSearchCV(clf, param_distributions=param_dist,
                                     n_iter=n_iter_search)

start = time()
random_search.fit(X, y)
print("RandomizedSearchCV took %.2f seconds for %d candidates" % ((time() - start), n_iter_search))
report(random_search.cv_results_)

# use a full grid over all parameters
param_grid = {'average': [True, False],
              'l1_ratio': np.linspace(0, 1, num=10),
              'alpha': np.power(10, np.arange(-4, 1, dtype=float))}

# run grid search
grid_search = GridSearchCV(clf, param_grid=param_grid)
start = time()
grid_search.fit(X, y)
print("GridSearchCV took %.2f seconds for %d candidate parameter settings." % (time() - start, len(grid_search.cv_results_['params']))
report(grid_search.cv_results_)

---

**Total running time of the script:** ( 2 minutes 5.294 seconds)

### 6.22.9 Train error vs Test error

Illustration of how the performance of an estimator on unseen data (test data) is not the same as the performance on training data. As the regularization increases the performance on train decreases while the performance on test is optimal within a range of values of the regularization parameter. The example with an Elastic-Net regression model and the performance is measured using the explained variance a.k.a. $R^2$. 

---

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Out:

Optimal regularization parameter : 0.00013141473626117567

print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# License: BSD 3 clause

import numpy as nprom sklearn import linear_model

# #############################################################################
# Generate sample data
n_samples_train, n_samples_test, n_features = 75, 150, 500
np.random.seed(0)
coef = np.random.randn(n_features)
coef[50:] = 0.0  # only the top 10 features are impacting the model
X = np.random.randn(n_samples_train + n_samples_test, n_features)
y = np.dot(X, coef)
# Split train and test data
X_train, X_test = X[:n_samples_train], X[n_samples_train:]
y_train, y_test = y[:n_samples_train], y[n_samples_train:]

# Compute train and test errors
alphas = np.logspace(-5, 1, 60)
enet = linear_model.ElasticNet(l1_ratio=0.7, max_iter=10000)
train_errors = list()
test_errors = list()
for alpha in alphas:
    enet.set_params(alpha=alpha)
enet.fit(X_train, y_train)
    train_errors.append(enet.score(X_train, y_train))
tenet.fit(X_train, y_train)
    test_errors.append(enet.score(X_test, y_test))

i_alpha_optim = np.argmax(test_errors)
alpha_optim = alphas[i_alpha_optim]
print("Optimal regularization parameter : %s" % alpha_optim)

# Estimate the coef_ on full data with optimal regularization parameter
enet.set_params(alpha=alpha_optim)
coef_ = enet.fit(X, y).coef_

# Plot results functions
import matplotlib.pyplot as plt
plt.subplot(2, 1, 1)
plt.semilogx(alphas, train_errors, label='Train')
plt.semilogx(alphas, test_errors, label='Test')
plt.vlines(alpha_optim, plt.ylim()[0], np.max(test_errors), color='k',
          linewidth=3, label='Optimum on test')
plt.legend(loc='lower left')
plt.ylim((0, 1.2])
plt.xlabel('Regularization parameter')
plt.ylabel('Performance')

# Show estimated coef_ vs true coef
plt.subplot(2, 1, 2)
plt.plot(coef, label='True coef')
plt.plot(coef_, label='Estimated coef')
plt.legend()
plt.subplots_adjust(0.09, 0.04, 0.94, 0.94, 0.26, 0.26)
plt.show()

Total running time of the script: ( 0 minutes 1.784 seconds)
6.22.10 Receiver Operating Characteristic (ROC) with cross validation

Example of Receiver Operating Characteristic (ROC) metric to evaluate classifier output quality using cross-validation.

ROC curves typically feature true positive rate on the Y axis, and false positive rate on the X axis. This means that the top left corner of the plot is the "ideal" point - a false positive rate of zero, and a true positive rate of one. This is not very realistic, but it does mean that a larger area under the curve (AUC) is usually better.

The "steepness" of ROC curves is also important, since it is ideal to maximize the true positive rate while minimizing the false positive rate.

This example shows the ROC response of different datasets, created from K-fold cross-validation. Taking all of these curves, it is possible to calculate the mean area under curve, and see the variance of the curve when the training set is split into different subsets. This roughly shows how the classifier output is affected by changes in the training data, and how different the splits generated by K-fold cross-validation are from one another.

Note:

See also sklearn.metrics.roc_auc_score, sklearn.model_selection.cross_val_score, Receiver Operating Characteristic (ROC),

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
```

(continues on next page)
```python
from sklearn import svm, datasets
from sklearn.metrics import auc
from sklearn.metrics import plot_roc_curve
from sklearn.model_selection import StratifiedKFold

# Data IO and generation

# Import some data to play with
iris = datasets.load_iris()
X = iris.data
y = iris.target
X, y = X[y != 2], y[y != 2]
n_samples, n_features = X.shape

# Add noisy features
random_state = np.random.RandomState(0)
X = np.c_[X, random_state.randn(n_samples, 200 * n_features)]

# Classification and ROC analysis

# Run classifier with cross-validation and plot ROC curves
cv = StratifiedKFold(n_splits=6)
classifier = svm.SVC(kernel='linear', probability=True, random_state=random_state)
tprs = []
aucs = []
mean_fpr = np.linspace(0, 1, 100)

fig, ax = plt.subplots()
for i, (train, test) in enumerate(cv.split(X, y)):
    classifier.fit(X[train], y[train])
    viz = plot_roc_curve(classifier, X[test], y[test], name='ROC fold {}'.format(i),
                         alpha=0.3, lw=1, ax=ax)
    interp_tpr = np.interp(mean_fpr, viz.fpr, viz.tpr)
    interp_tpr[0] = 0.0
    tprs.append(interp_tpr)
aucs.append(viz.roc_auc)

ax.plot([0, 1], [0, 1], linestyle='--', lw=2, color='r',
        label='Chance', alpha=.8)
mean_tpr = np.mean(tprs, axis=0)
mean_tpr[-1] = 1.0
mean_auc = auc(mean_fpr, mean_tpr)
std_auc = np.std(aucs)
ax.plot(mean_fpr, mean_tpr, color='b',
        label='Mean ROC (AUC = %0.2f \pm %0.2f)' % (mean_auc, std_auc),
        lw=2, alpha=.8)

std_tpr = np.std(tprs, axis=0)
tprs_upper = np.minimum(mean_tpr + std_tpr, 1)
tprs_lower = np.maximum(mean_tpr - std_tpr, 0)
```

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ax.fill_between(mean_fpr, tprs_lower, tprs_upper, color='grey', alpha=.2, label=r'$\pm$ 1 std. dev. ')

ax.set(xlim=[-0.05, 1.05], ylim=[-0.05, 1.05],
       title="Receiver operating characteristic example")

ax.legend(loc="lower right")

plt.show()

Total running time of the script: ( 0 minutes 0.195 seconds)

### 6.22.11 Nested versus non-nested cross-validation

This example compares non-nested and nested cross-validation strategies on a classifier of the iris data set. Nested cross-validation (CV) is often used to train a model in which hyperparameters also need to be optimized. Nested CV estimates the generalization error of the underlying model and its (hyper)parameter search. Choosing the parameters that maximize non-nested CV biases the model to the dataset, yielding an overly-optimistic score.

Model selection without nested CV uses the same data to tune model parameters and evaluate model performance. Information may thus “leak” into the model and overfit the data. The magnitude of this effect is primarily dependent on the size of the dataset and the stability of the model. See Cawley and Talbot\(^1\) for an analysis of these issues.

To avoid this problem, nested CV effectively uses a series of train/validation/test set splits. In the inner loop (here executed by `GridSearchCV`), the score is approximately maximized by fitting a model to each training set, and then directly maximized in selecting (hyper)parameters over the validation set. In the outer loop (here in `cross_val_score`), generalization error is estimated by averaging test set scores over several dataset splits.

The example below uses a support vector classifier with a non-linear kernel to build a model with optimized hyperparameters by grid search. We compare the performance of non-nested and nested CV strategies by taking the difference between their scores.

#### See Also:

- Cross-validation: evaluating estimator performance
- Tuning the hyper-parameters of an estimator

#### References:

from sklearn.datasets import load_iris
from matplotlib import pyplot as plt
from sklearn.svm import SVC
from sklearn.model_selection import GridSearchCV, cross_val_score, KFold
import numpy as np

print(__doc__)

# Number of random trials
NUM_TRIALS = 30

# Load the dataset
iris = load_iris()
X_iris = iris.data
y_iris = iris.target

Out:

Average difference of 0.007581 with std. dev. of 0.007833.

(continues on next page)
# Set up possible values of parameters to optimize over
p_grid = {'C': [1, 10, 100],
          'gamma': [.01, .1]}

# We will use a Support Vector Classifier with "rbf" kernel
svm = SVC(kernel="rbf")

# Arrays to store scores
non_nested_scores = np.zeros(NUM_TRIALS)
nested_scores = np.zeros(NUM_TRIALS)

# Loop for each trial
for i in range(NUM_TRIALS):
    # Choose cross-validation techniques for the inner and outer loops,
    # independently of the dataset.
    # E.g "GroupKFold", "LeaveOneOut", "LeaveOneGroupOut", etc.
    inner_cv = KFold(n_splits=4, shuffle=True, random_state=i)
    outer_cv = KFold(n_splits=4, shuffle=True, random_state=i)

    # Non_nested parameter search and scoring
    clf = GridSearchCV(estimator=svm, param_grid=p_grid, cv=inner_cv)
    clf.fit(X_iris, y_iris)
    non_nested_scores[i] = clf.best_score_

    # Nested CV with parameter optimization
    nested_score = cross_val_score(clf, X=X_iris, y=y_iris, cv=outer_cv)
    nested_scores[i] = nested_score.mean()

    score_difference = non_nested_scores - nested_scores

    print("Average difference of {:.6f} with std. dev. of {:.6f}.").format(score_difference.mean(), score_difference.std()))

# Plot scores on each trial for nested and non-nested CV
plt.figure()
plt.subplot(211)
non_nested_scores_line, = plt.plot(non_nested_scores, color='r')
nested_line, = plt.plot(nested_scores, color='b')
plt.ylabel("score", fontsize="14")
plt.legend([non_nested_scores_line, nested_line],
           ["Non-Nested CV", "Nested CV"],
           bbox_to_anchor=(0, .4, .5, 0))
plt.title("Non-Nested and Nested Cross Validation on Iris Dataset",
          x=.5, y=1.1, fontsize="15")

# Plot bar chart of the difference.
plt.subplot(212)
difference_plot = plt.bar(range(NUM_TRIALS), score_difference)
plt.xlabel("Individual Trial ")
plt.legend([difference_plot],
           ["Non-Nested CV - Nested CV Score"],
           bbox_to_anchor=(0, 1, .8, 0))
plt.ylabel("score difference", fontsize="14")
plt.show()
6.22.12 Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV

Multiple metric parameter search can be done by setting the `scoring` parameter to a list of metric scorer names or a dict mapping the scorer names to the scorer callables.

The scores of all the scorers are available in the `cv_results_` dict at keys ending in `'_<scorer_name>'` ("mean_test_precision", 'rank_test_precision', etc...)

The `best_estimator_`, `best_index_`, `best_score_` and `best_params_` correspond to the scorer (key) that is set to the `refit` attribute.

```python
# Author: Raghav RV <rvraghav93@gmail.com>
# License: BSD
import numpy as np
from matplotlib import pyplot as plt
from sklearn.datasets import make_hastie_10_2
from sklearn.model_selection import GridSearchCV
from sklearn.metrics import make_scorer
from sklearn.metrics import accuracy_score
from sklearn.tree import DecisionTreeClassifier
print(__doc__)

Running GridSearchCV using multiple evaluation metrics

```x, y = make_hastie_10_2(n_samples=8000, random_state=42)

# The scorers can be either be one of the predefined metric strings or a scorer
# callable, like the one returned by make_scorer
scoring = {'AUC': 'roc_auc', 'Accuracy': make_scorer(accuracy_score)}

# Setting refit='AUC', refits an estimator on the whole dataset with the
# parameter setting that has the best cross-validated AUC score.
# That estimator is made available at `gs.best_estimator_` along with
# parameters like `gs.best_score_`, `gs.best_params_` and
# `gs.best_index_``
gs = GridSearchCV(DecisionTreeClassifier(random_state=42),
                  param_grid={'min_samples_split': range(2, 403, 10)},
                  scoring=scoring, refit='AUC', return_train_score=True)
gs.fit(X, y)
results = gs.cv_results_

Total running time of the script: (0 minutes 5.598 seconds)
Plotting the result

```python
plt.figure(figsize=(13, 13))
plt.title("GridSearchCV evaluating using multiple scorers simultaneously",
          fontsize=16)
plt.xlabel("min_samples_split")
plt.ylabel("Score")
ax = plt.gca()
ax.set_xlim(0, 402)
ax.set_ylim(0.73, 1)

# Get the regular numpy array from the MaskedArray
X_axis = np.array(results['param_min_samples_split'].data, dtype=float)

for scorer, color in zip(sorted(scoring), ['g', 'k']):
    for sample, style in (('train', '--'), ('test', '-')):
        sample_score_mean = results['mean_%s_%s' % (sample, scorer)]
        sample_score_std = results['std_%s_%s' % (sample, scorer)]
        ax.fill_between(X_axis, sample_score_mean - sample_score_std,
                        sample_score_mean + sample_score_std,
                        alpha=0.1 if sample == 'test' else 0, color=color)
        ax.plot(X_axis, sample_score_mean, style, color=color,
                alpha=1 if sample == 'test' else 0.7,
                label="%s (%s)" % (scorer, sample))
        best_index = np.nonzero(results['rank_test_%s' % scorer] == 1)[0][0]
        best_score = results['mean_test_%s' % scorer][best_index]
        ax.plot([X_axis[best_index], ] * 2, [0, best_score],
                 linestyle='-.', color=color, marker='x', markeredgewidth=3, ms=8)

        # Annotate the best score for that scorer
        ax.annotate("%.2f" % best_score,
                    (X_axis[best_index], best_score + 0.005))

plt.legend(loc="best")
plt.grid(False)
plt.show()
```
6.22.13 Sample pipeline for text feature extraction and evaluation

The dataset used in this example is the 20 newsgroups dataset which will be automatically downloaded and then cached and reused for the document classification example.

You can adjust the number of categories by giving their names to the dataset loader or setting them to None to get the 20 of them.

Here is a sample output of a run on a quad-core machine:

```
Loading 20 newsgroups dataset for categories: ['alt.atheism', 'talk.religion.misc']
```

(continues on next page)
Performing grid search...

pipeline: ['vect', 'tfidf', 'clf']

parameters:

- **clf**
  - **clf__alpha**: (1.0000000000000001e-05, 9.9999999999999995e-07),
  - **clf__max_iter**: (10, 50, 80),
  - **clf__penalty**: ('l2', 'elasticnet'),
  - **tfidf__use_idf**: (True, False),
  - **vect__max_n**: (1, 2),
  - **vect__max_df**: (0.5, 0.75, 1.0),
  - **vect__max_features**: (None, 5000, 10000, 50000)

Best score: 0.940

Best parameters set:

- **clf__alpha**: 9.9999999999999995e-07
- **clf__max_iter**: 50
- **clf__penalty**: 'elasticnet'
- **tfidf__use_idf**: True
- **vect__max_n**: 2
- **vect__max_df**: 0.75
- **vect__max_features**: 50000

# Author: Olivier Grisel <olivier.grisel@ensta.org>
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# Mathieu Blondel <mathieu@mblondel.org>
# License: BSD 3 clause

from pprint import pprint
from time import time
import logging
from sklearn.datasets import fetch_20newsgroups
from sklearn.feature_extraction.text import CountVectorizer
from sklearn.feature_extraction.text import TfidfTransformer
from sklearn.linear_model import SGDClassifier
from sklearn.model_selection import GridSearchCV
from sklearn.pipeline import Pipeline

print(__doc__)

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO,
                    format='%(asctime)s %(levelname)s %(message)s')

# Load some categories from the training set
categories = ['alt.atheism',
              'talk.religion.misc',
              ]

# Uncomment the following to do the analysis on all the categories
categories = None

(continues on next page)
print("Loading 20 newsgroups dataset for categories:")
data = fetch_20newsgroups(subset='train', categories=categories)
print("%d documents" % len(data.filenames))
print("%d categories" % len(data.target_names))

# Define a pipeline combining a text feature extractor with a simple classifier
pipeline = Pipeline([
    ('vect', CountVectorizer()),
    ('tfidf', TfidfTransformer()),
    ('clf', SGDClassifier()),
])

# uncommenting more parameters will give better exploring power but will increase processing time in a combinatorial way
parameters = {
    'vect__max_df': (0.5, 0.75, 1.0),
    # 'vect__max_features': (None, 5000, 10000, 50000),
    'vect__ngram_range': [(1, 1), (1, 2)],  # unigrams or bigrams
    # 'tfidf__use_idf': (True, False),
    # 'tfidf__norm': ('l1', 'l2'),
    'clf__max_iter': (20,),
    'clf__alpha': (0.00001, 0.000001),
    'clf__penalty': ('l2', 'elasticnet'),
    # 'clf__max_iter': (10, 50, 80),
}

if __name__ == "__main__":
    # multiprocessing requires the fork to happen in a __main__ protected block
    # find the best parameters for both the feature extraction and the classifier
    grid_search = GridSearchCV(pipeline, parameters, n_jobs=-1, verbose=1)
    print("Performing grid search...")
    print("pipeline:", [name for name, _ in pipeline.steps])
    print("parameters:")
    pprint(parameters)
    grid_search.fit(data.data, data.target)
    t0 = time()
    print("done in $0.3fs" % (time() - t0))
    print()
    print("Best score: $0.3f" % grid_search.best_score_)
    print("Best parameters set:")
    best_parameters = grid_search.best_estimator_.get_params()
    for param_name in sorted(parameters.keys()):
        print("\t%s: $r" % (param_name, best_parameters[param_name]))

Total running time of the script: ( 0 minutes 0.000 seconds)
6.22.14 Balance model complexity and cross-validated score

This example balances model complexity and cross-validated score by finding a decent accuracy within 1 standard deviation of the best accuracy score while minimising the number of PCA components [1].

The figure shows the trade-off between cross-validated score and the number of PCA components. The balanced case is when n_components=10 and accuracy=0.88, which falls into the range within 1 standard deviation of the best accuracy score.


Out:

The best_index_ is 2
The n_components selected is 10
The corresponding accuracy score is 0.88

# Author: Wenhao Zhang <wenhaoz@ucla.edu>

print(__doc__)
import numpy as np
import matplotlib.pyplot as plt

from sklearn.datasets import load_digits
from sklearn.decomposition import PCA
from sklearn.model_selection import GridSearchCV
from sklearn.pipeline import Pipeline
from sklearn.svm import LinearSVC

def lower_bound(cv_results):
    ""
    Calculate the lower bound within 1 standard deviation
    of the best 'mean_test_scores'.

    Parameters
    ----------
    cv_results : dict of numpy(masked) ndarrays
        See attribute cv_results_ of `GridSearchCV`

    Returns
    -------
    float
        Lower bound within 1 standard deviation of the
        best 'mean_test_score'.
    ""
    best_score_idx = np.argmax(cv_results['mean_test_score'])
    return (cv_results['mean_test_score'][best_score_idx]
            - cv_results['std_test_score'][best_score_idx])

def best_low_complexity(cv_results):
    ""
    Balance model complexity with cross-validated score.

    Parameters
    ----------
    cv_results : dict of numpy(masked) ndarrays
        See attribute cv_results_ of `GridSearchCV`.

    Returns
    -------
    int
        Index of a model that has the fewest PCA components
        while has its test score within 1 standard deviation of the best
        'mean_test_score'.
    ""
    threshold = lower_bound(cv_results)
    candidate_idx = np.flatnonzero(cv_results['mean_test_score'] >= threshold)
    best_idx = candidate_idx[cv_results['param_reduce_dim__n_components']
                              [candidate_idx].argmin()]
    return best_idx

pipe = Pipeline([}
param_grid = {
    'reduce_dim__n_components': [6, 8, 10, 12, 14]
}

grid = GridSearchCV(pipe, cv=10, n_jobs=1, param_grid=param_grid,
                     scoring='accuracy', refit='best_low_complexity')

X, y = load_digits(return_X_y=True)
grid.fit(X, y)

n_components = grid.cv_results_['param_reduce_dim__n_components']
test_scores = grid.cv_results_['mean_test_score']

plt.figure()
plt.bar(n_components, test_scores, width=1.3, color='b')

lower = lower_bound(grid.cv_results_)
plt.axhline(np.max(test_scores), linestyle='--', color='y',
            label='Best score')
plt.axhline(lower, linestyle='--', color='.5', label='Best score - 1 std')

plt.title("Balance model complexity and cross-validated score")
plt.xlabel('Number of PCA components used')
plt.ylabel('Digit classification accuracy')
plt.xticks(n_components.tolist())
plt.ylim((0, 1.0))
plt.legend(loc='upper left')

best_index_ = grid.best_index_
print("The best_index_ is %d" % best_index_)
print("The n_components selected is %d" % n_components[best_index_])
print("The corresponding accuracy score is %.2f" %
      grid.cv_results_['mean_test_score'][best_index_])
plt.show()
We first define the parameter space for an `SVC` estimator, and compute the time required to train a `HalvingGridSearchCV` instance, as well as a `GridSearchCV` instance.

```python
rng = np.random.RandomState(0)
X, y = datasets.make_classification(n_samples=1000, random_state=rng)

gammas = [1e-1, 1e-2, 1e-3, 1e-4, 1e-5, 1e-6, 1e-7]
Cs = [1, 10, 100, 1e3, 1e4, 1e5]
param_grid = {'gamma': gammas, 'C': Cs}
clf = SVC(random_state=rng)
tic = time()
gsh = HalvingGridSearchCV(estimator=clf, param_grid=param_grid, factor=2,
                           random_state=rng)
gsh.fit(X, y)
gsh_time = time() - tic
tic = time()
gs = GridSearchCV(estimator=clf, param_grid=param_grid)
gs.fit(X, y)
gs_time = time() - tic
```

We now plot heatmaps for both search estimators.

```python
def make_heatmap(ax, gs, is_sh=False, make_cbar=False):
    """Helper to make a heatmap."""
    results = pd.DataFrame.from_dict(gs.cv_results_)
    results['params_str'] = results.params.apply(str)
    if is_sh:
        # SH dataframe: get mean_test_score values for the highest iter
        scores_matrix = results.sort_values('iter').pivot_table(
            index='param_gamma', columns='param_C',
            values='mean_test_score', aggfunc='last'
        )
    else:
        scores_matrix = results.pivot(index='param_gamma', columns='param_C',
                                       values='mean_test_score')
    im = ax.imshow(scores_matrix)
    ax.set_xticks(np.arange(len(Cs)))
    ax.set_xticklabels(['{:0.0E}'.format(x) for x in Cs])
    ax.set_xlabel('C', fontsize=15)
    ax.set_yticks(np.arange(len(gammas)))
    ax.set_yticklabels(['{:0.0E}'.format(x) for x in gammas])
    ax.set_ylabel('gamma', fontsize=15)

    # Rotate the tick labels and set their alignment.
    plt.setp(ax.get_xticklabels(), rotation=45, ha="right",
```

(continues on next page)
rotation_mode="anchor")

if is_sh:
    iterations = results.pivot_table(index='param_gamma',
                                      columns='param_C', values='iter',
                                      aggfunc='max').values

    for i in range(len(gammas)):
        for j in range(len(Cs)):
            ax.text(j, i, iterations[i, j],
                     ha="center", va="center", color="w", fontsize=20)

if make_cbar:
    fig.subplots_adjust(right=0.8)
    cbar_ax = fig.add_axes([0.85, 0.15, 0.05, 0.7])
    fig.colorbar(im, cax=cbar_ax)
    cbar_ax.set_ylabel('mean_test_score', rotation=-90, va="bottom",
                       fontsize=15)

fig, axes = plt.subplots(ncols=2, sharey=True)
ax1, ax2 = axes

make_heatmap(ax1, gsh, is_sh=True)
make_heatmap(ax2, gs, make_cbar=True)

ax1.set_title('Successive Halving
              time = {:.3f}s'.format(gsh_time),
              fontsize=15)
ax2.set_title('GridSearch
              time = {:.3f}s'.format(gs_time), fontsize=15)

plt.show()
The heatmaps show the mean test score of the parameter combinations for an `SVC` instance. The `HalvingGridSearchCV` also shows the iteration at which the combinations were last used. The combinations marked as 0 were only evaluated at the first iteration, while the ones with 5 are the parameter combinations that are considered the best ones.

We can see that the `HalvingGridSearchCV` class is able to find parameter combinations that are just as accurate as `GridSearchCV`, in much less time.

**Total running time of the script:** ( 0 minutes 10.814 seconds)

### 6.22.16 Visualizing cross-validation behavior in scikit-learn

Choosing the right cross-validation object is a crucial part of fitting a model properly. There are many ways to split data into training and test sets in order to avoid model overfitting, to standardize the number of groups in test sets, etc.

This example visualizes the behavior of several common scikit-learn objects for comparison.

```python
from sklearn.model_selection import (TimeSeriesSplit, KFold, ShuffleSplit,
                                     StratifiedKFold, GroupShuffleSplit,
                                     GroupKFold, StratifiedShuffleSplit)

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.patches import Patch
np.random.seed(1338)
cmap_data = plt.cm.Paired
```
Visualize our data

First, we must understand the structure of our data. It has 100 randomly generated input datapoints, 3 classes split unevenly across datapoints, and 10 “groups” split evenly across datapoints.

As we’ll see, some cross-validation objects do specific things with labeled data, others behave differently with grouped data, and others do not use this information.

To begin, we’ll visualize our data.

```python
# Generate the class/group data
n_points = 100
X = np.random.randn(100, 10)

percentiles_classes = [.1, .3, .6]
y = np.hstack([[ii] * int(100 * perc)
               for ii, perc in enumerate(percentiles_classes)])

# Evenly spaced groups repeated once
groups = np.hstack([[ii] * 10 for ii in range(10)])

def visualize_groups(classes, groups, name):
    # Visualize dataset groups
    fig, ax = plt.subplots()
    ax.scatter(range(len(groups)), [.5] * len(groups), c=groups, marker='_',
               lw=50, cmap=cmap_data)
    ax.scatter(range(len(groups)), [3.5] * len(groups), c=classes, marker='_',
               lw=50, cmap=cmap_data)
    ax.set(ylim=[-1, 5], yticks=[.5, 3.5],
           yticklabels=['Data\ngroup', 'Data\nclass'], xlabel="Sample index")

visualize_groups(y, groups, 'no groups')
```
Define a function to visualize cross-validation behavior

We’ll define a function that lets us visualize the behavior of each cross-validation object. We’ll perform 4 splits of the data. On each split, we’ll visualize the indices chosen for the training set (in blue) and the test set (in red).

```python
def plot_cv_indices(cv, X, y, group, ax, n_splits, lw=10):
    """Create a sample plot for indices of a cross-validation object.""

    # Generate the training/testing visualizations for each CV split
    for ii, (tr, tt) in enumerate(cv.split(X=X, y=y, groups=group)):
        # Fill in indices with the training/test groups
        indices = np.array([np.nan] * len(X))
        indices[tt] = 1
        indices[tr] = 0

        # Visualize the results
        ax.scatter(range(len(indices)), [ii + .5] * len(indices),
                    c=indices, marker='_', lw=lw, cmap=cmap_cv,
                    vmin=-.2, vmax=1.2)

    # Plot the data classes and groups at the end
    ax.scatter(range(len(X)), [ii + 1.5] * len(X),
               c=y, marker='_', lw=lw, cmap=cmap_data)
```

(continues on next page)
Let's see how it looks for the `KFold` cross-validation object:

```
fig, ax = plt.subplots()
cv = KFold(n_splits)
plot_cv_indices(cv, X, y, groups, ax, n_splits)
```

Out:

```
<AxesSubplot:title={'center':'KFold'}, xlabel='Sample index', ylabel='CV iteration'>
```

As you can see, by default the KFold cross-validation iterator does not take either datapoint class or group into consideration. We can change this by using the `StratifiedKFold` like so.
In this case, the cross-validation retained the same ratio of classes across each CV split. Next we’ll visualize this behavior for a number of CV iterators.

**Visualize cross-validation indices for many CV objects**

Let’s visually compare the cross validation behavior for many scikit-learn cross-validation objects. Below we will loop through several common cross-validation objects, visualizing the behavior of each.

Note how some use the group/class information while others do not.

```python
cvs = [KFold, GroupKFold, ShuffleSplit, StratifiedKFold,
       GroupShuffleSplit, StratifiedShuffleSplit, TimeSeriesSplit]

for cv in cvs:
    (continues on next page)
```python
this_cv = cv(n_splits=n_splits)
fig, ax = plt.subplots(figsize=(6, 3))
plot_cv_indices(this_cv, X, y, groups, ax, n_splits)

ax.legend([Patch(color=cmap_cv(.8)), Patch(color=cmap_cv(.02))],
            ['Testing set', 'Training set'], loc=(1.02, .8))

# Make the legend fit
plt.tight_layout()
fig.subplots_adjust(right=.7)
plt.show()
```
6.22. Model Selection
6.22.17 Receiver Operating Characteristic (ROC)

Example of Receiver Operating Characteristic (ROC) metric to evaluate classifier output quality.

ROC curves typically feature true positive rate on the Y axis, and false positive rate on the X axis. This means that the top left corner of the plot is the “ideal” point - a false positive rate of zero, and a true positive rate of one. This is not very realistic, but it does mean that a larger area under the curve (AUC) is usually better.

The “steepness” of ROC curves is also important, since it is ideal to maximize the true positive rate while minimizing the false positive rate.

ROC curves are typically used in binary classification to study the output of a classifier. In order to extend ROC curve and ROC area to multi-label classification, it is necessary to binarize the output. One ROC curve can be drawn per label, but one can also draw a ROC curve by considering each element of the label indicator matrix as a binary prediction (micro-averaging).

Another evaluation measure for multi-label classification is macro-averaging, which gives equal weight to the classification of each label.

Note:

See also sklearn.metrics.roc_auc_score, Receiver Operating Characteristic (ROC) with cross validation

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from itertools import cycle

from sklearn import svm, datasets
from sklearn.metrics import roc_curve, auc
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import label_binarize
from sklearn.multiclass import OneVsRestClassifier
```

(continues on next page)
```python
from scipy import interp
from sklearn.metrics import roc_auc_score

# Import some data to play with
iris = datasets.load_iris()
X = iris.data
y = iris.target

# Binarize the output
y = label_binarize(y, classes=[0, 1, 2])
n_classes = y.shape[1]

# Add noisy features to make the problem harder
random_state = np.random.RandomState(0)
n_samples, n_features = X.shape
X = np.c_[X, random_state.randn(n_samples, 200 * n_features)]

# shuffle and split training and test sets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=.5, random_state=0)

# Learn to predict each class against the other
classifier = OneVsRestClassifier(svm.SVC(kernel='linear', probability=True, random_state=random_state))
y_score = classifier.fit(X_train, y_train).decision_function(X_test)

# Compute ROC curve and ROC area for each class
fpr = dict()
tpr = dict()
roc_auc = dict()
for i in range(n_classes):
    fpr[i], tpr[i], _ = roc_curve(y_test[:, i], y_score[:, i])
    roc_auc[i] = auc(fpr[i], tpr[i])

# Compute micro-average ROC curve and ROC area
fpr['micro'], tpr['micro'], _ = roc_curve(y_test.ravel(), y_score.ravel())
roc_auc['micro'] = auc(fpr['micro'], tpr['micro'])

Plot of a ROC curve for a specific class

plt.figure()
lw = 2
plt.plot(fpr[2], tpr[2], color='darkorange', lw=lw, label='ROC curve (area = %0.2f)' % roc_auc[2])
plt.plot([0, 1], [0, 1], color='navy', lw=lw, linestyle='--')
plt.xlim([0.0, 1.0])
plt.ylim([0.0, 1.05])
plt.xlabel('False Positive Rate')
plt.ylabel('True Positive Rate')
plt.title('Receiver operating characteristic example')
plt.legend(loc="lower right")
plt.show()
```
Plot ROC curves for the multilabel problem

Compute macro-average ROC curve and ROC area

```python
# First aggregate all false positive rates
all_fpr = np.unique(np.concatenate([fpr[i] for i in range(n_classes)]))

# Then interpolate all ROC curves at this points
mean_tpr = np.zeros_like(all_fpr)
for i in range(n_classes):
    mean_tpr += interp(all_fpr, fpr[i], tpr[i])

# Finally average it and compute AUC
mean_tpr /= n_classes
fpr["macro"] = all_fpr
tpr["macro"] = mean_tpr
roc_auc["macro"] = auc(fpr["macro"], tpr["macro"])

# Plot all ROC curves
plt.figure()
plt.plot(fpr["micro"], tpr["micro"],
         label='micro-average ROC curve (area = {0:0.2f})'.format(roc_auc["micro"])),
```
plt.plot(fpr["macro"], tpr["macro"],
    label='macro-average ROC curve (area = {0:.2f})'
    ''.format(roc_auc["macro"]),
    color='navy', linestyle=':', linewidth=4)

colors = cycle(['aqua', 'darkorange', 'cornflowerblue'])
for i, color in zip(range(n_classes), colors):
    plt.plot(fpr[i], tpr[i], color=color, lw=lw,
        label='ROC curve of class {0} (area = {1:.2f})'
        ''.format(i, roc_auc[i]))

plt.plot([0, 1], [0, 1], 'k--', lw=lw)
plt.xlim([0.0, 1.0])
plt.ylim([0.0, 1.05])
plt.xlabel('False Positive Rate')
plt.ylabel('True Positive Rate')
plt.title('Some extension of Receiver operating characteristic to multi-class')
plt.legend(loc="lower right")
plt.show()
Area under ROC for the multiclass problem

The sklearn.metrics.roc_auc_score function can be used for multi-class classification. The multi-class One-vs-One scheme compares every unique pairwise combination of classes. In this section, we calculate the AUC using the OvR and OvO schemes. We report a macro average, and a prevalence-weighted average.

```python
y_prob = classifier.predict_proba(X_test)
macro_roc_auc_ovo = roc_auc_score(y_test, y_prob, multi_class="ovo",
                                 average="macro")
weighted_roc_auc_ovo = roc_auc_score(y_test, y_prob, multi_class="ovo",
                                     average="weighted")
macro_roc_auc_ovr = roc_auc_score(y_test, y_prob, multi_class="ovr",
                                  average="macro")
weighted_roc_auc_ovr = roc_auc_score(y_test, y_prob, multi_class="ovr",
                                     average="weighted")
print("One-vs-One ROC AUC scores:
      {:.6f} (macro),
      {:.6f} (weighted by prevalence)".format(macro_roc_auc_ovo, weighted_roc_auc_ovo))
print("One-vs-Rest ROC AUC scores:
      {:.6f} (macro),
      {:.6f} (weighted by prevalence)".format(macro_roc_auc_ovr, weighted_roc_auc_ovr))
```

Out:

```
One-vs-One ROC AUC scores:
0.698586 (macro),
0.665839 (weighted by prevalence)
One-vs-Rest ROC AUC scores:
0.698586 (macro),
0.665839 (weighted by prevalence)
```

**Total running time of the script:** ( 0 minutes 0.221 seconds)

### 6.22.18 Precision-Recall

Example of Precision-Recall metric to evaluate classifier output quality.

Precision-Recall is a useful measure of success of prediction when the classes are very imbalanced. In information retrieval, precision is a measure of result relevancy, while recall is a measure of how many truly relevant results are returned.

The precision-recall curve shows the tradeoff between precision and recall for different threshold. A high area under the curve represents both high recall and high precision, where high precision relates to a low false positive rate, and high recall relates to a low false negative rate. High scores for both show that the classifier is returning accurate results (high precision), as well as returning a majority of all positive results (high recall).

A system with high recall but low precision returns many results, but most of its predicted labels are incorrect when compared to the training labels. A system with high precision but low recall is just the opposite, returning very few
results, but most of its predicted labels are correct when compared to the training labels. An ideal system with high precision and high recall will return many results, with all results labeled correctly.

Precision ($P$) is defined as the number of true positives ($T_p$) over the number of true positives plus the number of false positives ($F_p$).

$$P = \frac{T_p}{T_p + F_p}$$

Recall ($R$) is defined as the number of true positives ($T_p$) over the number of true positives plus the number of false negatives ($F_n$).

$$R = \frac{T_p}{T_p + F_n}$$

These quantities are also related to the ($F_1$) score, which is defined as the harmonic mean of precision and recall.

$$F_1 = \frac{2 \times P \times R}{P + R}$$

Note that the precision may not decrease with recall. The definition of precision ($\frac{T_p}{T_p + F_p}$) shows that lowering the threshold of a classifier may increase the denominator, by increasing the number of results returned. If the threshold was previously set too high, the new results may all be true positives, which will increase precision. If the previous threshold was about right or too low, further lowering the threshold will introduce false positives, decreasing precision.

Recall is defined as $\frac{T_p}{T_p + F_n}$, where $T_p + F_n$ does not depend on the classifier threshold. This means that lowering the classifier threshold may increase recall, by increasing the number of true positive results. It is also possible that lowering the threshold may leave recall unchanged, while the precision fluctuates.

The relationship between recall and precision can be observed in the stairstep area of the plot - at the edges of these steps a small change in the threshold considerably reduces precision, with only a minor gain in recall.

**Average precision** (AP) summarizes such a plot as the weighted mean of precisions achieved at each threshold, with the increase in recall from the previous threshold used as the weight:

$$AP = \sum_n (R_n - R_{n-1}) P_n$$

where $P_n$ and $R_n$ are the precision and recall at the $n$th threshold. A pair $(R_k, P_k)$ is referred to as an **operating point**.

AP and the trapezoidal area under the operating points (sklearn.metrics.auc) are common ways to summarize a precision-recall curve that lead to different results. Read more in the User Guide.

Precision-recall curves are typically used in binary classification to study the output of a classifier. In order to extend the precision-recall curve and average precision to multi-class or multi-label classification, it is necessary to binarize the output. One curve can be drawn per label, but one can also draw a precision-recall curve by considering each element of the label indicator matrix as a binary prediction (micro-averaging).

**Note:**

See also sklearn.metrics.average_precision_score, sklearn.metrics.recall_score, sklearn.metrics.precision_score, sklearn.metrics.f1_score
In binary classification settings

Create simple data

Try to differentiate the two first classes of the iris data

```python
from sklearn import svm, datasets
from sklearn.model_selection import train_test_split
import numpy as np

iris = datasets.load_iris()
X = iris.data
y = iris.target

# Add noisy features
random_state = np.random.RandomState(0)
n_samples, n_features = X.shape
X = np.c_[X, random_state.randn(n_samples, 200 * n_features)]

# Limit to the two first classes, and split into training and test
X_train, X_test, y_train, y_test = train_test_split(X[y < 2], y[y < 2],
                                                     test_size=.5,
                                                     random_state=random_state)

# Create a simple classifier
classifier = svm.LinearSVC(random_state=random_state)
classifier.fit(X_train, y_train)
y_score = classifier.decision_function(X_test)

Compute the average precision score

```python
from sklearn.metrics import average_precision_score
average_precision = average_precision_score(y_test, y_score)

print('Average precision-recall score: {0:0.2f}'.format(average_precision))
```

Out:

```
Average precision-recall score: 0.88
```

Plot the Precision-Recall curve

```python
from sklearn.metrics import precision_recall_curve
from sklearn.metrics import plot_precision_recall_curve
import matplotlib.pyplot as plt

disp = plot_precision_recall_curve(classifier, X_test, y_test)
disp.ax_.set_title('2-class Precision-Recall curve: ' 'AP={0:0.2f}'.format(average_precision))
```
In multi-label settings

Create multi-label data, fit, and predict

We create a multi-label dataset, to illustrate the precision-recall in multi-label settings.

```python
from sklearn.preprocessing import label_binarize

# Use label_binarize to be multi-label like settings
Y = label_binarize(y, classes=[0, 1, 2])
n_classes = Y.shape[1]

# Split into training and test
X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=.5, random_state=random_state)

# We use OneVsRestClassifier for multi-label prediction
from sklearn.multiclass import OneVsRestClassifier

# Run classifier
```

(continues on next page)
classifier = OneVsRestClassifier(svm.LinearSVC(random_state=random_state))
classifier.fit(X_train, Y_train)
y_score = classifier.decision_function(X_test)

The average precision score in multi-label settings

from sklearn.metrics import precision_recall_curve
from sklearn.metrics import average_precision_score

# For each class
precision = dict()
recall = dict()
average_precision = dict()
for i in range(n_classes):
    precision[i], recall[i], _ = precision_recall_curve(Y_test[:, i],
                                                        y_score[:, i])
    average_precision[i] = average_precision_score(Y_test[:, i], y_score[:, i])

# A "micro-average": quantifying score on all classes jointly
precision["micro"], recall["micro"], _ = precision_recall_curve(Y_test.ravel(),
                                                                  y_score.ravel())
average_precision["micro"] = average_precision_score(Y_test, y_score,
                                                             average="micro")
print('Average precision score, micro-averaged over all classes: (0:0.2f)'
      .format(average_precision["micro"]))

Out:

Average precision score, micro-averaged over all classes: 0.43

Plot the micro-averaged Precision-Recall curve

plt.figure()
plt.step(recall["micro"], precision["micro"], where='post')

plt.xlabel('Recall')
plt.ylabel('Precision')
plt.ylim([0.0, 1.05])
plt.xlim([0.0, 1.0])
plt.title('Average precision score, micro-averaged over all classes: AP=(0:0.2f)''
      .format(average_precision["micro"]))
Average precision score, micro-averaged over all classes: AP=0.43

Plot Precision-Recall curve for each class and iso-f1 curves

```python
from itertools import cycle
# setup plot details
colors = cycle(['navy', 'turquoise', 'darkorange', 'cornflowerblue', 'teal'])

plt.figure(figsize=(7, 8))
f_scores = np.linspace(0.2, 0.8, num=4)
lines = []
labels = []
for f_score in f_scores:
    x = np.linspace(0.01, 1)
y = f_score * x / (2 * x - f_score)
l, = plt.plot(x[y >= 0], y[y >= 0], color='gray', alpha=0.2)
plt.annotate('f1={0:0.1f}'.format(f_score), xy=(0.9, y[45] + 0.02))
lines.append(l)
labels.append('iso-f1 curves')
l, = plt.plot(recall['micro'], precision['micro'], color='gold', lw=2)
lines.append(l)
```

(continues on next page)
labels.append('micro-average Precision-recall (area = {0:0.2f})'''.format(average_precision['micro']))

for i, color in zip(range(n_classes), colors):
    l, = plt.plot(recall[i], precision[i], color=color, lw=2)
    lines.append(l)
    labels.append('Precision-recall for class {0} (area = {1:0.2f})'''.format(i, average_precision[i]))

fig = plt.gcf()
fig.subplots_adjust(bottom=0.25)
plt.xlim([0.0, 1.0])
plt.ylim([0.0, 1.05])
plt.xlabel('Recall')
plt.ylabel('Precision')
plt.title('Extension of Precision-Recall curve to multi-class')
plt.legend(lines, labels, loc=(0, -.38), prop=dict(size=14))

plt.show()
Extension of Precision-Recall curve to multi-class

iso-f1 curves
micro-average Precision-recall (area = 0.43)
Precision-recall for class 0 (area = 0.56)
Precision-recall for class 1 (area = 0.37)
Precision-recall for class 2 (area = 0.46)

Total running time of the script: (0 minutes 0.306 seconds)
6.22.19 Plotting Learning Curves

In the first column, first row the learning curve of a naive Bayes classifier is shown for the digits dataset. Note that the training score and the cross-validation score are both not very good at the end. However, the shape of the curve can be found in more complex datasets very often: the training score is very high at the beginning and decreases and the cross-validation score is very low at the beginning and increases. In the second column, first row we see the learning curve of an SVM with RBF kernel. We can see clearly that the training score is still around the maximum and the validation score could be increased with more training samples. The plots in the second row show the times required by the models to train with various sizes of training dataset. The plots in the third row show how much time was required to train the models for each training sizes.
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.naive_bayes import GaussianNB
from sklearn.svm import SVC
from sklearn.datasets import load_digits
from sklearn.model_selection import learning_curve
from sklearn.model_selection import ShuffleSplit

def plot_learning_curve(estimator, title, X, y, axes=None, ylim=None, cv=None, n_jobs=None, train_sizes=np.linspace(.1, 1.0, 5)):
    ""
    Generate 3 plots: the test and training learning curve, the training
    samples vs fit times curve, the fit times vs score curve.
    Parameters
    ----------
    estimator : estimator instance
        An estimator instance implementing 'fit' and 'predict' methods which
        will be cloned for each validation.
    title : str
        Title for the chart.
    X : array-like of shape (n_samples, n_features)
        Training vector, where 'n_samples' is the number of samples and
        'n_features' is the number of features.
    y : array-like of shape (n_samples) or (n_samples, n_features)
        Target relative to 'X' for classification or regression;
        None for unsupervised learning.
    axes : array-like of shape (3,), default=None
        Axes to use for plotting the curves.
    ylim : tuple of shape (2,), default=None
        Defines minimum and maximum y-values plotted, e.g. (ymin, ymax).
    cv : int, cross-validation generator or an iterable, default=None
        Determines the cross-validation splitting strategy.
        Possible inputs for cv are:
        - None, to use the default 5-fold cross-validation,
        - integer, to specify the number of folds.
        - :term:`CV splitter`
        - An iterable yielding (train, test) splits as arrays of indices.
        For integer/None inputs, if 'y' is binary or multiclass,
        :class:`StratifiedKFold` used. If the estimator is not a classifier
        or if 'y' is neither binary nor multiclass, :class:`KFold` is used.
        Refer :ref:`User Guide <cross_validation>` for the various
        cross-validators that can be used here.
    n_jobs : int or None, default=None
    """
Number of jobs to run in parallel.
`None` means 1 unless in a `joblib.parallel_backend` context.
`-1` means using all processors. See :term:`Glossary <n_jobs>` for more details.

`train_sizes` : array-like of shape (n_ticks,), dtype=(int, float)
Relative or absolute numbers of training examples that will be used to
generate the learning curve. If the `dtype` is float, it is regarded
as a fraction of the maximum size of the training set (that is
determined by the selected validation method), i.e. it has to be within
(0, 1]. Otherwise it is interpreted as absolute sizes of the training
sets. Note that for classification the number of samples usually have
to be big enough to contain at least one sample from each class.
(default: np.linspace(0.1, 1.0, 5))

```python
if axes is None:
    _, axes = plt.subplots(1, 3, figsize=(20, 5))
axes[0].set_title(title)
if ylim is not None:
    axes[0].set_ylim(*ylim)
axes[0].set_xlabel("Training examples")
axes[0].set_ylabel("Score")
train_sizes, train_scores, test_scores, fit_times, _ = 
    learning_curve(estimator, X, y, cv=cv, n_jobs=n_jobs,
                   train_sizes=train_sizes,
                   return_times=True)
train_scores_mean = np.mean(train_scores, axis=1)
train_scores_std = np.std(train_scores, axis=1)
test_scores_mean = np.mean(test_scores, axis=1)
test_scores_std = np.std(test_scores, axis=1)
fit_times_mean = np.mean(fit_times, axis=1)
fit_times_std = np.std(fit_times, axis=1)

# Plot learning curve
axes[0].grid()
axes[0].fill_between(train_sizes, train_scores_mean - train_scores_std,
                     train_scores_mean + train_scores_std, alpha=0.1,
                     color="r")
axes[0].fill_between(train_sizes, test_scores_mean - test_scores_std,
                     test_scores_mean + test_scores_std, alpha=0.1,
                     color="g")
axes[0].plot(train_sizes, train_scores_mean, 'o-', color="r",
             label="Training score")
axes[0].plot(train_sizes, test_scores_mean, 'o-', color="g",
             label="Cross-validation score")
axes[0].legend(loc="best")

# Plot n_samples vs fit_times
axes[1].grid()
axes[1].plot(train_sizes, fit_times_mean, 'o-')
axes[1].fill_between(train_sizes, fit_times_mean - fit_times_std,
                     fit_times_mean + fit_times_std, alpha=0.1)
axes[1].set_xlabel("Training examples")
axes[1].set_ylabel("fit_times")
axes[1].set_title("Scalability of the model")
```
# Plot fit_time vs score
axes[2].grid()
axes[2].plot(fit_times_mean, test_scores_mean, 'o-')
axes[2].fill_between(fit_times_mean, test_scores_mean - test_scores_std,
                    test_scores_mean + test_scores_std, alpha=0.1)
axes[2].set_xlabel("fit_times")
axes[2].set_ylabel("Score")
axes[2].set_title("Performance of the model")

return plt

fig, axes = plt.subplots(3, 2, figsize=(10, 15))
X, y = load_digits(return_X_y=True)
title = "Learning Curves (Naive Bayes)"
# Cross validation with 100 iterations to get smoother mean test and train
# score curves, each time with 20% data randomly selected as a validation set.
cv = ShuffleSplit(n_splits=100, test_size=0.2, random_state=0)
estimator = GaussianNB()
plot_learning_curve(estimator, title, X, y, axes=axes[:, 0], ylim=(0.7, 1.01),
cv=cv, n_jobs=4)
title = r"Learning Curves (SVM, RBF kernel, $\gamma=0.001$)"
# SVC is more expensive so we do a lower number of CV iterations:
cv = ShuffleSplit(n_splits=10, test_size=0.2, random_state=0)
estimator = SVC(gamma=0.001)
plot_learning_curve(estimator, title, X, y, axes=axes[:, 1], ylim=(0.7, 1.01),
cv=cv, n_jobs=4)
plt.show()

**Total running time of the script:** ( 0 minutes 3.663 seconds)

### 6.22.20 Statistical comparison of models using grid search

This example illustrates how to statistically compare the performance of models trained and evaluated using GridSearchCV.

We will start by simulating moon shaped data (where the ideal separation between classes is non-linear), adding to it a moderate degree of noise. Datapoints will belong to one of two possible classes to be predicted by two features. We will simulate 50 samples for each class:

```python
print(__doc__)
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.datasets import make_moons

X, y = make_moons(noise=0.352, random_state=1, n_samples=100)
sns.scatterplot(
    x=X[:, 0], y=X[:, 1], hue=y,
)```

(continues on next page)
We will compare the performance of SVC estimators that vary on their kernel parameter, to decide which choice of this hyper-parameter predicts our simulated data best. We will evaluate the performance of the models using RepeatedStratifiedKFold, repeating 10 times a 10-fold stratified cross validation using a different randomization of the data in each repetition. The performance will be evaluated using roc_auc_score.

```python
from sklearn.model_selection import GridSearchCV, RepeatedStratifiedKFold
from sklearn.svm import SVC

param_grid = [
    {'kernel': ['linear']},
    {'kernel': ['poly'], 'degree': [2, 3]},
    {'kernel': ['rbf']}
]

svc = SVC(random_state=0)

cv = RepeatedStratifiedKFold(n_splits=10, n_repeats=10, random_state=0)
```
search = GridSearchCV(  
estimator=svc, param_grid=param_grid,  
scorer=['roc_auc'], cv=cv  
)  
search.fit(X, y)

We can now inspect the results of our search, sorted by their mean_test_score:

```python
import pandas as pd
results_df = pd.DataFrame(search.cv_results_)
results_df = results_df.sort_values(by=['rank_test_score'])
results_df = (  
    results_df  
    .set_index(results_df['params'].apply(  
        lambda x: '_'.join(str(val) for val in x.values())  
    )  
    )  
    .rename_axis('kernel')
)
results_df[['params', 'rank_test_score', 'mean_test_score', 'std_test_score']]
```

We can see that the estimator using the 'rbf' kernel performed best, closely followed by 'linear'. Both estimators with a 'poly' kernel performed worse, with the one using a two-degree polynomial achieving a much lower performance than all other models.

Usually, the analysis just ends here, but half the story is missing. The output of `GridSearchCV` does not provide information on the certainty of the differences between the models. We don’t know if these are statistically significant. To evaluate this, we need to conduct a statistical test. Specifically, to contrast the performance of two models we should statistically compare their AUC scores. There are 100 samples (AUC scores) for each model as we repeated 10 times a 10-fold cross-validation.

However, the scores of the models are not independent: all models are evaluated on the same 100 partitions, increasing the correlation between the performance of the models. Since some partitions of the data can make the distinction of the classes particularly easy or hard to find for all models, the models scores will co-vary.

Let’s inspect this partition effect by plotting the performance of all models in each fold, and calculating the correlation between models across folds:

```python
# create df of model scores ordered by perfomance
model_scores = results_df.filter(regex=r'split\d*_test_score')

# plot 30 examples of dependency between cv fold and AUC scores
fig, ax = plt.subplots()
sns.lineplot(  
    data=model_scores.transpose().iloc[:30],  
    dashes=False, palette='Set1', marker='o', alpha=.5, ax=ax  
)
ax.set_xlabel("CV test fold", size=12, labelpad=10)
ax.set_ylabel("Model AUC", size=12)
ax.tick_params(bottom=True, labelbottom=False)
plt.show()

# print correlation of AUC scores across folds
print(f"Correlation of models:
    \{(model_scores.transpose().corr())\}")
```
Out:

```
Correlation of models:
        kernel    rbf    linear  3_poly  2_poly
    kernel    rbf  1.000000 0.882561 0.783392 0.351390
    linear  0.882561 1.000000 0.746492 0.298688
   3_poly  0.783392 0.746492 1.000000 0.355440
   2_poly  0.351390 0.298688 0.355440 1.000000
```

We can observe that the performance of the models highly depends on the fold.

As a consequence, if we assume independence between samples we will be underestimating the variance computed in our statistical tests, increasing the number of false positive errors (i.e. detecting a significant difference between models when such does not exist)\(^1\).

Several variance-corrected statistical tests have been developed for these cases. In this example we will show how to implement one of them (the so called Nadeau and Bengio’s corrected t-test) under two different statistical frameworks: frequentist and Bayesian.

Comparing two models: frequentist approach

We can start by asking: “Is the first model significantly better than the second model (when ranked by mean_test_score)?”

To answer this question using a frequentist approach we could run a paired t-test and compute the p-value. This is also known as Diebold-Mariano test in the forecast literature⁵. Many variants of such a t-test have been developed to account for the ‘non-independence of samples problem’ described in the previous section. We will use the one proven to obtain the highest replicability scores (which rate how similar the performance of a model is when evaluating it on different random partitions of the same dataset) while maintaining a low rate of false positives and false negatives: the Nadeau and Bengio’s corrected t-test² that uses a 10 times repeated 10-fold cross validation³.

This corrected paired t-test is computed as:

\[ t = \frac{1}{k \cdot r} \sum_{i=1}^{k} \sum_{j=1}^{r} x_{ij} \sqrt{\left( \frac{1}{k \cdot r} \cdot \frac{n_{test}}{n_{train}} \right) \hat{\sigma}^2} \]

where \( k \) is the number of folds, \( r \) the number of repetitions in the cross-validation, \( x \) is the difference in performance of the models, \( n_{test} \) is the number of samples used for testing, \( n_{train} \) is the number of samples used for training, and \( \hat{\sigma}^2 \) represents the variance of the observed differences.

Let’s implement a corrected right-tailed paired t-test to evaluate if the performance of the first model is significantly better than that of the second model. Our null hypothesis is that the second model performs at least as good as the first model.

```python
import numpy as np
from scipy.stats import t

def corrected_std(differences, n_train, n_test):
    """Corrects standard deviation using Nadeau and Bengio’s approach."

    Parameters
    ----------
    differences : ndarray of shape (n_samples, 1)
        Vector containing the differences in the score metrics of two models.
    n_train : int
        Number of samples in the training set.
    n_test : int
        Number of samples in the testing set.

    Returns
    -------
    corrected_std : int
        Variance-corrected standard deviation of the set of differences.

    """
    n = n_train + n_test
    corrected_var = np.var(differences, ddof=1) * ((1 / n) + (n_test / n_train))
    corrected_std = np.sqrt(corrected_var)
    return corrected_std
```

---

def compute_corrected_ttest(differences, df, n_train, n_test):
    """Computes right-tailed paired t-test with corrected variance.

    Parameters
    ----------
    differences : array-like of shape (n_samples, 1)
        Vector containing the differences in the score metrics of two models.
    df : int
        Degrees of freedom.
    n_train : int
        Number of samples in the training set.
    n_test : int
        Number of samples in the testing set.

    Returns
    -------
    t_stat : float
        Variance-corrected t-statistic.
    p_val : float
        Variance-corrected p-value.
    """
    mean = np.mean(differences)
    std = corrected_std(differences, n_train, n_test)
    t_stat = mean / std
    p_val = t.sf(np.abs(t_stat), df)  # right-tailed t-test
    return t_stat, p_val

model_1_scores = model_scores.iloc[0].values  # scores of the best model
model_2_scores = model_scores.iloc[1].values  # scores of the second-best model
differences = model_1_scores - model_2_scores
n = differences.shape[0]  # number of test sets
df = n - 1
n_train = len(list(cv.split(X, y))[0][0])
n_test = len(list(cv.split(X, y))[0][1])
t_stat, p_val = compute_corrected_ttest(differences, df, n_train, n_test)
print(f"Corrected t-value: \{t_stat:.3f}\n" f"Corrected p-value: \{p_val:.3f}\n")

Out:
Corrected t-value: 0.750
Corrected p-value: 0.227

We can compare the corrected t- and p-values with the uncorrected ones:

t_stat_uncorrected = {
    np.mean(differences) / np.sqrt(np.var(differences, ddof=1) / n)
}
p_val_uncorrected = t.sf(np.abs(t_stat_uncorrected), df)
print(f"Uncorrected t-value: \{t_stat_uncorrected:.3f}\n" f"Uncorrected p-value: \{p_val_uncorrected:.3f}\n")
Out:

<table>
<thead>
<tr>
<th>Uncorrected t-value</th>
<th>Uncorrected p-value</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.611</td>
<td>0.005</td>
</tr>
</tbody>
</table>

Using the conventional significance alpha level at $p=0.05$, we observe that the uncorrected t-test concludes that the first model is significantly better than the second.

With the corrected approach, in contrast, we fail to detect this difference.

In the latter case, however, the frequentist approach does not let us conclude that the first and second model have an equivalent performance. If we wanted to make this assertion we need to use a Bayesian approach.

**Comparing two models: Bayesian approach**

We can use Bayesian estimation to calculate the probability that the first model is better than the second. Bayesian estimation will output a distribution followed by the mean $\mu$ of the differences in the performance of two models.

To obtain the posterior distribution we need to define a prior that models our beliefs of how the mean is distributed before looking at the data, and multiply it by a likelihood function that computes how likely our observed differences are, given the values that the mean of differences could take.

Bayesian estimation can be carried out in many forms to answer our question, but in this example we will implement the approach suggested by Benavoli and colleagues\(^4\).

One way of defining our posterior using a closed-form expression is to select a prior conjugate to the likelihood function. Benavoli and colleagues\(^4\) show that when comparing the performance of two classifiers we can model the prior as a Normal-Gamma distribution (with both mean and variance unknown) conjugate to a normal likelihood, to thus express the posterior as a normal distribution. Marginalizing out the variance from this normal posterior, we can define the posterior of the mean parameter as a Student’s t-distribution. Specifically:

$$St(\mu; n-1, \overline{x}, (\frac{1}{n} + \frac{n_{\text{test}}}{n_{\text{train}}} \hat{\sigma}^2))$$

where $n$ is the total number of samples, $\overline{x}$ represents the mean difference in the scores, $n_{\text{test}}$ is the number of samples used for testing, $n_{\text{train}}$ is the number of samples used for training, and $\hat{\sigma}^2$ represents the variance of the observed differences.

Notice that we are using Nadeau and Bengio’s corrected variance in our Bayesian approach as well.

Let’s compute and plot the posterior:

```python
# intialize random variable
x = np.linspace(t_post.ppf(0.001), t_post.ppf(0.999), 100)
```

Let’s plot the posterior distribution:

```python
plt.plot(x, t_post.pdf(x))
plt.xticks(np.arange(-0.04, 0.06, 0.01))
plt.fill_between(x, t_post.pdf(x), 0, facecolor='blue', alpha=.2)
plt.ylabel("Probability density")
```

---

plt.xlabel(r"Mean difference ($\mu$)")
plt.title("Posterior distribution")
plt.show()

We can calculate the probability that the first model is better than the second by computing the area under the curve of the posterior distribution from zero to infinity. And also the reverse: we can calculate the probability that the second model is better than the first by computing the area under the curve from minus infinity to zero.

```
better_prob = 1 - t_post.cdf(0)
print(f"Probability of {model_scores.index[0]} being more accurate than {model_scores.index[1]}: \{better_prob:.3f\}")
print(f"Probability of {model_scores.index[1]} being more accurate than {model_scores.index[0]}: \{1 - better_prob:.3f\")
```

Out:

```
Probability of rbf being more accurate than linear: 0.773
Probability of linear being more accurate than rbf: 0.227
```

In contrast with the frequentist approach, we can compute the probability that one model is better than the other. Note that we obtained similar results as those in the frequentist approach. Given our choice of priors, we are essentially performing the same computations, but we are allowed to make different assertions.
Region of Practical Equivalence

Sometimes we are interested in determining the probabilities that our models have an equivalent performance, where “equivalent” is defined in a practical way. A naive approach would be to define estimators as practically equivalent when they differ by less than 1% in their accuracy. But we could also define this practical equivalence taking into account the problem we are trying to solve. For example, a difference of 5% in accuracy would mean an increase of $1000 in sales, and we consider any quantity above that as relevant for our business.

In this example we are going to define the Region of Practical Equivalence (ROPE) to be $[-0.01, 0.01]$. That is, we will consider two models as practically equivalent if they differ by less than 1% in their performance.

To compute the probabilities of the classifiers being practically equivalent, we calculate the area under the curve of the posterior over the ROPE interval:

```python
rope_interval = [-0.01, 0.01]
rope_prob = t_post.cdf(rope_interval[1]) - t_post.cdf(rope_interval[0])
print(f"Probability of {model_scores.index[0]} and {model_scores.index[1]} being practically equivalent: {rope_prob:.3f}"
```  

Out:

```
Probability of rbf and linear being practically equivalent: 0.432
```

We can plot how the posterior is distributed over the ROPE interval:

```python
x_rope = np.linspace(rope_interval[0], rope_interval[1], 100)
plt.plot(x, t_post.pdf(x))
plt.xticks(np.arange(-0.04, 0.06, 0.01))
plt.vlines([-0.01, 0.01], ymin=0, ymax=(np.max(t_post.pdf(x)) + 1))
plt.fill_between(x_rope, t_post.pdf(x_rope), 0, facecolor='blue', alpha=.2)
plt.ylabel("Probability density")
plt.xlabel(r"Mean difference ($\mu$)"")
plt.title("Posterior distribution under the ROPE")
plt.show()
```
As suggested in\(^4\), we can further interpret these probabilities using the same criteria as the frequentist approach: is the probability of falling inside the ROPE bigger than 95% (alpha value of 5%)? In that case we can conclude that both models are practically equivalent.

The Bayesian estimation approach also allows us to compute how uncertain we are about our estimation of the difference. This can be calculated using credible intervals. For a given probability, they show the range of values that the estimated quantity, in our case the mean difference in performance, can take. For example, a 50% credible interval \([x, y]\) tells us that there is a 50% probability that the true (mean) difference of performance between models is between \(x\) and \(y\).

Let’s determine the credible intervals of our data using 50%, 75% and 95%:

```python
cred_intervals = []
intervals = [0.5, 0.75, 0.95]
for interval in intervals:
    cred_interval = list(t_post.interval(interval))
    cred_intervals.append([interval, cred_interval[0], cred_interval[1]])

cred_int_df = pd.DataFrame(
    cred_intervals,
    columns=['interval', 'lower value', 'upper value']
).set_index('interval')
```

As shown in the table, there is a 50% probability that the true mean difference between models will be between 0.000977 and 0.019023, 70% probability that it will be between -0.005422 and 0.025422, and 95% probability that it...
will be between -0.016445 and 0.036445.

**Pairwise comparison of all models: frequentist approach**

We could also be interested in comparing the performance of all our models evaluated with `GridSearchCV`. In this case we would be running our statistical test multiple times, which leads us to the multiple comparisons problem.

There are many possible ways to tackle this problem, but a standard approach is to apply a Bonferroni correction. Bonferroni can be computed by multiplying the p-value by the number of comparisons we are testing.

Let’s compare the performance of the models using the corrected t-test:

```python
from itertools import combinations
from math import factorial

n_comparisons = (factorial(len(model_scores))
                 / (factorial(2) * factorial(len(model_scores) - 2)))

pairwise_t_test = [
    for model_i, model_k in combinations(range(len(model_scores)), 2):
        model_i_scores = model_scores.iloc[model_i].values
        model_k_scores = model_scores.iloc[model_k].values
        differences = model_i_scores - model_k_scores
        t_stat, p_val = compute_corrected_ttest(differences, df, n_train, n_test)
        p_val *= n_comparisons  # implement Bonferroni correction
        # Bonferroni can output p-values higher than 1
        p_val = 1 if p_val > 1 else p_val
        pairwise_t_test.append([model_scores.index[model_i], model_scores.index[model_k], t_stat, p_val])

pairwise_comp_df = pd.DataFrame(pairwise_t_test, columns=['model_1', 'model_2', 't_stat', 'p_val']).round(3)
```

We observe that after correcting for multiple comparisons, the only model that significantly differs from the others is '2_poly'. 'rbf', the model ranked first by `GridSearchCV`, does not significantly differ from 'linear' or '3_poly'.

**Pairwise comparison of all models: Bayesian approach**

When using Bayesian estimation to compare multiple models, we don’t need to correct for multiple comparisons (for reasons why see^4).

We can carry out our pairwise comparisons the same way as in the first section:

```python
pairwise_bayesian = []

for model_i, model_k in combinations(range(len(model_scores)), 2):
    # (continues on next page)
```

6.22. Model Selection
Using the Bayesian approach we can compute the probability that a model performs better, worse or practically equivalent to another.

Results show that the model ranked first by `GridSearchCV` 'rbf', has approximately a 6.8% chance of being worse than 'linear', and a 1.8% chance of being worse than '3_poly'. 'rbf' and 'linear' have a 43% probability of being practically equivalent, while 'rbf' and '3_poly' have a 10% chance of being so.

Similarly to the conclusions obtained using the frequentist approach, all models have a 100% probability of being better than '2_poly', and none have a practically equivalent performance with the latter.

**Take-home messages**

- Small differences in performance measures might easily turn out to be merely by chance, but not because one model predicts systematically better than the other. As shown in this example, statistics can tell you how likely that is.

- When statistically comparing the performance of two models evaluated in `GridSearchCV`, it is necessary to correct the calculated variance which could be underestimated since the scores of the models are not independent from each other.

- A frequentist approach that uses a (variance-corrected) paired t-test can tell us if the performance of one model is better than another with a degree of certainty above chance.

- A Bayesian approach can provide the probabilities of one model being better, worse or practically equivalent than another. It can also tell us how confident we are of knowing that the true differences of our models fall under a certain range of values.

- If multiple models are statistically compared, a multiple comparisons correction is needed when using the frequentist approach.

**References**

**Total running time of the script:** ( 0 minutes 1.349 seconds)
6.23 Multioutput methods

Examples concerning the `sklearn.multioutput` module.

6.23.1 Classifier Chain

Example of using classifier chain on a multilabel dataset.

For this example we will use the yeast dataset which contains 2417 datapoints each with 103 features and 14 possible labels. Each data point has at least one label. As a baseline we first train a logistic regression classifier for each of the 14 labels. To evaluate the performance of these classifiers we predict on a held-out test set and calculate the jaccard score for each sample.

Next we create 10 classifier chains. Each classifier chain contains a logistic regression model for each of the 14 labels. The models in each chain are ordered randomly. In addition to the 103 features in the dataset, each model gets the predictions of the preceding models in the chain as features (note that by default at training time each model gets the true labels as features). These additional features allow each chain to exploit correlations among the classes. The Jaccard similarity score for each chain tends to be greater than that of the set independent logistic models.

Because the models in each chain are arranged randomly there is significant variation in performance among the chains. Presumably there is an optimal ordering of the classes in a chain that will yield the best performance. However we do not know that ordering a priori. Instead we can construct an voting ensemble of classifier chains by averaging the binary predictions of the chains and apply a threshold of 0.5. The Jaccard similarity score of the ensemble is greater than that of the independent models and tends to exceed the score of each chain in the ensemble (although this is not guaranteed with randomly ordered chains).

![Classifier Chain Ensemble Performance Comparison](image)

# Author: Adam Kleczewski
# License: BSD 3 clause

```python
import numpy as np
import matplotlib.pyplot as plt
```

(continues on next page)
from sklearn.datasets import fetch_openml
from sklearn.multioutput import ClassifierChain
from sklearn.model_selection import train_test_split
from sklearn.multiclass import OneVsRestClassifier
from sklearn.linear_model import LogisticRegression

print(__doc__)
# Load a multi-label dataset from https://www.openml.org/d/40597
X, Y = fetch_openml('yeast', version=4, return_X_y=True)
Y = Y == 'TRUE'
X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=.2,
                                                     random_state=0)

# Fit an independent logistic regression model for each class using the
# OneVsRestClassifier wrapper.
base_lr = LogisticRegression()
ovr = OneVsRestClassifier(base_lr)
ovr.fit(X_train, Y_train)
Y_pred_ovr = ovr.predict(X_test)
ovr_jaccard_score = jaccard_score(Y_test, Y_pred_ovr, average='samples')

# Fit an ensemble of logistic regression classifier chains and take the
# average prediction of all the chains.
chains = [ClassifierChain(base_lr, order='random', random_state=i)
          for i in range(10)]
for chain in chains:
    chain.fit(X_train, Y_train)
Y_pred_chains = np.array([chain.predict(X_test) for chain in chains])
chain_jaccard_scores = [jaccard_score(Y_test, Y_pred_chain >= .5,
                                       average='samples')
                        for Y_pred_chain in Y_pred_chains]
Y_pred_ensemble = Y_pred_chains.mean(axis=0)
ensemble_jaccard_score = jaccard_score(Y_test,
                                       Y_pred_ensemble >= .5,
                                       average='samples')

model_scores = [ovr_jaccard_score] + chain_jaccard_scores
model_scores.append(ensemble_jaccard_score)
model_names = ('Independent',
               'Chain 1',
               'Chain 2',
               'Chain 3',
               'Chain 4',
               'Chain 5',
               'Chain 6',
               'Chain 7',
               'Chain 8',
               'Chain 9',
               'Chain 10',
               'Ensemble')

(continues on next page)
x_pos = np.arange(len(model_names))

# Plot the Jaccard similarity scores for the independent model, each of the
# chains, and the ensemble (note that the vertical axis on this plot does
# not begin at 0).

fig, ax = plt.subplots(figsize=(7, 4))
ax.grid(True)
ax.set_title('Classifier Chain Ensemble Performance Comparison')
ax.set_xticks(x_pos)
ax.set_xticklabels(model_names, rotation='vertical')
ax.set_ylabel('Jaccard Similarity Score')
ax.set_ylim([min(model_scores) * .9, max(model_scores) * 1.1])
colors = ['r'] + ['b'] * len(chain_jaccard_scores) + ['g']
ax.bar(x_pos, model_scores, alpha=0.5, color=colors)
plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 3.685 seconds)

6.24 Nearest Neighbors

Examples concerning the sklearn.neighbors module.

6.24.1 Nearest Neighbors regression

Demonstrate the resolution of a regression problem using a k-Nearest Neighbor and the interpolation of the target using both barycenter and constant weights.
print(__doc__)

# Author: Alexandre Gramfort <alexandre.gramfort@inria.fr>
# Fabian Pedregosa <fabian.pedregosa@inria.fr>
#
# License: BSD 3 clause (C) INRIA

# Generate sample data
import numpy as np
import matplotlib.pyplot as plt
from sklearn import neighbors

np.random.seed(0)
X = np.sort(5 * np.random.rand(40, 1), axis=0)
T = np.linspace(0, 5, 500)[:, np.newaxis]
y = np.sin(X).ravel()
# Add noise to targets
y[::5] += 1 * (0.5 - np.random.rand(8))

# Fit regression model
n_neighbors = 5

(continues on next page)
for i, weights in enumerate(['uniform', 'distance']):
    knn = neighbors.KNeighborsRegressor(n_neighbors, weights=weights)
    y_ = knn.fit(X, y).predict(T)
    plt.subplot(2, 1, i + 1)
    plt.scatter(X, y, color='darkorange', label='data')
    plt.plot(T, y_, color='navy', label='prediction')
    plt.axis('tight')
    plt.legend()
    plt.title("KNeighborsRegressor (k = %i, weights = '%s')" % (n_neighbors, weights))
plt.tight_layout()
plt.show()
import numpy as np
import matplotlib.pyplot as plt
from sklearn.neighbors import LocalOutlierFactor

print(__doc__)

np.random.seed(42)

# Generate train data
X_inliers = 0.3 * np.random.randn(100, 2)
X_inliers = np.r_[X_inliers + 2, X_inliers - 2]

# Generate some outliers
X_outliers = np.random.uniform(low=-4, high=4, size=(20, 2))
X = np.r_[X_inliers, X_outliers]

n_outliers = len(X_outliers)
ground_truth = np.ones(len(X), dtype=int)
ground_truth[-n_outliers:] = -1

# fit the model for outlier detection (default)
clf = LocalOutlierFactor(n_neighbors=20, contamination=0.1)
# use fit_predict to compute the predicted labels of the training samples
# (when LOF is used for outlier detection, the estimator has no predict,
# decision_function and score_samples methods).

(continues on next page)
```python
y_pred = clf.fit_predict(X)
n_errors = (y_pred != ground_truth).sum()
X_scores = clf.negative_outlier_factor_

plt.title("Local Outlier Factor (LOF")
plt.scatter(X[:, 0], X[:, 1], color='k', s=3., label='Data points')
# plot circles with radius proportional to the outlier scores
radius = (X_scores.max() - X_scores) / (X_scores.max() - X_scores.min())
plt.scatter(X[:, 0], X[:, 1], s=1000 * radius, edgecolors='r',
                        facecolors='none', label='Outlier scores')
plt.axis('tight')
plt.xlim((-5, 5))
plt.ylim((-5, 5))
plt.xlabel("prediction errors: $\%d$" % (n_errors))
legend = plt.legend(loc='upper left')
legend.legendHandles[0]._sizes = [10]
legend.legendHandles[1]._sizes = [20]
plt.show()
```

Total running time of the script: ( 0 minutes 0.090 seconds)

### 6.24.3 Nearest Centroid Classification

Sample usage of Nearest Centroid classification. It will plot the decision boundaries for each class.
3-Class classification (shrink_threshold=0.2)

Out:

None 0.8133333333333334
/home/circleci/project/examples/neighbors/plot_nearest_centroid.py:49:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
  'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap=cmap_light)
0.2 0.82
/home/circleci/project/examples/neighbors/plot_nearest_centroid.py:49:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
  'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap=cmap_light)

print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap

(continues on next page)
from sklearn import datasets
from sklearn.neighbors import NearestCentroid

n_neighbors = 15

# import some data to play with
iris = datasets.load_iris()
# we only take the first two features. We could avoid this ugly
# slicing by using a two-dim dataset
X = iris.data[:, :2]
y = iris.target

h = .02  # step size in the mesh

# Create color maps
cmap_light = ListedColormap(['orange', 'cyan', 'cornflowerblue'])
cmap_bold = ListedColormap(['darkorange', 'c', 'darkblue'])

for shrinkage in [None, .2]:
    # we create an instance of Neighbours Classifier and fit the data.
    clf = NearestCentroid(shrink_threshold=shrinkage)
    clf.fit(X, y)
    y_pred = clf.predict(X)
    print(shrinkage, np.mean(y == y_pred))

    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]x[y_min, y_max].
    x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
    y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
    xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                         np.arange(y_min, y_max, h))
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)

    # Put the result into a color plot
    plt.figure()
    plt.pcolormesh(xx, yy, Z, cmap=cmap_light)

    # Plot also the training points
    plt.scatter(X[:, 0], X[:, 1], c=y, cmap=cmap_bold,
                edgecolor='k', s=20)
    plt.title("3-Class classification (shrink_threshold=%r)" % shrinkage)
    plt.axis('tight')
plt.show()
6.24.4 Kernel Density Estimation

This example shows how kernel density estimation (KDE), a powerful non-parametric density estimation technique, can be used to learn a generative model for a dataset. With this generative model in place, new samples can be drawn. These new samples reflect the underlying model of the data.

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load_digits
from sklearn.neighbors import KernelDensity
from sklearn.decomposition import PCA
from sklearn.model_selection import GridSearchCV

# load the data
digits = load_digits()
```

Out:

```
best bandwidth: 3.79269019073225
```

Selection from the input data

```
0 1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9 0
 ...
5 6 5 0 5 8 9 8 4 1
```

"New" digits drawn from the kernel density model

```
1 9 1 2 3 0 5 4 9 9
3 9 0 6 9 0 3 1
 ...
5 6 0 7 9 0 9 9
```

import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load_digits
from sklearn.neighbors import KernelDensity
from sklearn.decomposition import PCA
from sklearn.model_selection import GridSearchCV

# load the data
digits = load_digits()
# project the 64-dimensional data to a lower dimension
pca = PCA(n_components=15, whiten=False)
data = pca.fit_transform(digits.data)

# use grid search cross-validation to optimize the bandwidth
params = {'bandwidth': np.logspace(-1, 1, 20)}
grid = GridSearchCV(KernelDensity(), params)
grid.fit(data)

print("best bandwidth: {0}".format(grid.best_estimator_.bandwidth))

# use the best estimator to compute the kernel density estimate
kde = grid.best_estimator_

# sample 44 new points from the data
new_data = kde.sample(44, random_state=0)
new_data = pca.inverse_transform(new_data)

# turn data into a 4x11 grid
new_data = new_data.reshape((4, 11, -1))
real_data = digits.data[:44].reshape((4, 11, -1))

# plot real digits and resampled digits
fig, ax = plt.subplots(9, 11, subplot_kw=dict(xticks=[], yticks=[]))
for j in range(11):
    ax[4, j].set_visible(False)
for i in range(4):
    im = ax[i, j].imshow(real_data[i, j].reshape((8, 8)),
                         cmap=plt.cm.binary, interpolation='nearest')
    im.set_clim(0, 16)
    im = ax[i + 5, j].imshow(new_data[i, j].reshape((8, 8)),
                             cmap=plt.cm.binary, interpolation='nearest')
    im.set_clim(0, 16)

ax[0, 5].set_title('Selection from the input data')
ax[5, 5].set_title("New" digits drawn from the kernel density model)

plt.show()

Total running time of the script: ( 0 minutes 4.990 seconds)

6.24.5 Nearest Neighbors Classification

Sample usage of Nearest Neighbors classification. It will plot the decision boundaries for each class.
3-Class classification (k = 15, weights = 'uniform')

- setosa
- versicolor
- virginica
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from matplotlib.colors import ListedColormap
from sklearn import neighbors, datasets

n_neighbors = 15

# import some data to play with
iris = datasets.load_iris()

# we only take the first two features. We could avoid this ugly
# slicing by using a two-dim dataset
X = iris.data[:, :2]
y = iris.target

h = .02  # step size in the mesh

# Create color maps

cmap_light = ListedColormap(['orange', 'cyan', 'cornflowerblue'])
cmap_bold = ['darkorange', 'c', 'darkblue']

for weights in ['uniform', 'distance']:
    # we create an instance of Neighbours Classifier and fit the data.
    clf = neighbors.KNeighborsClassifier(n_neighbors, weights=weights)
(continues on next page)
clf.fit(X, y)

# Plot the decision boundary. For that, we will assign a color to each
# point in the mesh [x_min, x_max]x[y_min, y_max].
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))
Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
plt.figure(figsize=(8, 6))
plt.contourf(xx, yy, Z, cmap=cmap_light)
# Plot also the training points
sns.scatterplot(x=X[:, 0], y=X[:, 1], hue=iris.target_names[y],
                 palette=cmap_bold, alpha=1.0, edgecolor="black")
plt.xlim(xx.min(), xx.max())
plt.ylim(yy.min(), yy.max())
plt.title("3-Class classification (k = %i, weights = '%s')" % (n_neighbors, weights))
plt.xlabel(iris.feature_names[0])
plt.ylabel(iris.feature_names[1])
plt.show()

Total running time of the script: ( 0 minutes 1.737 seconds)

### 6.24.6 Caching nearest neighbors

This examples demonstrates how to precompute the k nearest neighbors before using them in KNeighborsClassifier. KNeighborsClassifier can compute the nearest neighbors internally, but precomputing them can have several benefits, such as finer parameter control, caching for multiple use, or custom implementations.

Here we use the caching property of pipelines to cache the nearest neighbors graph between multiple fits of KNeighborsClassifier. The first call is slow since it computes the neighbors graph, while subsequent call are faster as they do not need to recompute the graph. Here the durations are small since the dataset is small, but the gain can be more substantial when the dataset grows larger, or when the grid of parameter to search is large.
# Author: Tom Dupre la Tour
# License: BSD 3 clause
from tempfile import TemporaryDirectory
import matplotlib.pyplot as plt
from sklearn.neighbors import KNeighborsTransformer, KNeighborsClassifier
from sklearn.model_selection import GridSearchCV
from sklearn.datasets import load_digits
from sklearn.pipeline import Pipeline
print(__doc__)
X, y = load_digits(return_X_y=True)
n_neighbors_list = [1, 2, 3, 4, 5, 6, 7, 8, 9]

# The transformer computes the nearest neighbors graph using the maximum number
# of neighbors necessary in the grid search. The classifier model filters the
# nearest neighbors graph as required by its own n_neighbors parameter.
graph_model = KNeighborsTransformer(n_neighbors=max(n_neighbors_list),
    mode='distance')
classifier_model = KNeighborsClassifier(metric='precomputed')

# Note that we give 'memory' a directory to cache the graph computation
# that will be used several times when tuning the hyperparameters of the
# classifier.
with TemporaryDirectory(prefix="sklearn_graph_cache_") as tmpdir:
    full_model = Pipeline(
        steps=[('graph', graph_model), ('classifier', classifier_model)],
        memory=tmpdir)

    param_grid = {'classifier__n_neighbors': n_neighbors_list}
gird_model = GridSearchCV(full_model, param_grid)
gird_model.fit(X, y)

# Plot the results of the grid search.

(continues on next page)
This example illustrates a learned distance metric that maximizes the nearest neighbors classification accuracy. It provides a visual representation of this metric compared to the original point space. Please refer to the User Guide for more information.

```python
# License: BSD 3 clause
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_classification
from sklearn.neighbors import NeighborhoodComponentsAnalysis
from matplotlib import cm
from scipy.special import logsumexp

print(__doc__)
```

**Original points**

First we create a data set of 9 samples from 3 classes, and plot the points in the original space. For this example, we focus on the classification of point no. 3. The thickness of a link between point no. 3 and another point is proportional to their distance.

```python
X, y = make_classification(n_samples=9, n_features=2, n_informative=2,
                           n_redundant=0, n_classes=3, n_clusters_per_class=1,
                           class_sep=1.0, random_state=0)
plt.figure(1)
ax = plt.gca()
for i in range(X.shape[0]):
    ax.text(X[i, 0], X[i, 1], str(i), va='center', ha='center')
    ax.scatter(X[i, 0], X[i, 1], s=300, c=cm.Set1(y[i]), alpha=0.4)
ax.set_title("Original points")
ax.axes.get_xaxis().set_visible(False)
ax.axes.get_yaxis().set_visible(False)
ax.axis('equal') # so that boundaries are displayed correctly as circles
```

```python

(continues on next page)
```
diff_embedded = X[i] - X
dist_embedded = np.einsum('ij,ij->i', diff_embedded,
                        diff_embedded)
dist_embedded[i] = np.inf

# compute exponentiated distances (use the log-sum-exp trick to
# avoid numerical instabilities
exp_dist_embedded = np.exp(-dist_embedded -
                         logsumexp(-dist_embedded))
return exp_dist_embedded

def relate_point(X, i, ax):
    pt_i = X[i]
    for j, pt_j in enumerate(X):
        thickness = link_thickness_i(X, i)
        if i != j:
            line = ([pt_i[0], pt_j[0]], [pt_i[1], pt_j[1]])
            ax.plot(*line, c=cm.Set1(y[j]),
                    linewidth=5*thickness[j])

i = 3
relate_point(X, i, ax)
plt.show()
Learning an embedding

We use `NeighborhoodComponentsAnalysis` to learn an embedding and plot the points after the transformation. We then take the embedding and find the nearest neighbors.

```python
nca = NeighborhoodComponentsAnalysis(max_iter=30, random_state=0)
nca = nca.fit(X, y)
plt.figure(2)
ax2 = plt.gca()
X_embedded = nca.transform(X)
relate_point(X_embedded, i, ax2)
for i in range(len(X)):
    ax2.text(X_embedded[i, 0], X_embedded[i, 1], str(i),
             va='center', ha='center')
    ax2.scatter(X_embedded[i, 0], X_embedded[i, 1], s=300, c=cm.Set1(y[[i]]),
                alpha=0.4)
ax2.set_title("NCA embedding")
ax2.axes.get_xaxis().set_visible(False)
ax2.axes.get_yaxis().set_visible(False)
ax2.axis('equal')
plt.show()
```

NCA embedding

Total running time of the script: ( 0 minutes 0.183 seconds)
The Local Outlier Factor (LOF) algorithm is an unsupervised anomaly detection method which computes the local density deviation of a given data point with respect to its neighbors. It considers as outliers the samples that have a substantially lower density than their neighbors. This example shows how to use LOF for novelty detection. Note that when LOF is used for novelty detection you MUST not use predict, decision_function and score_samples on the training set as this would lead to wrong results. You must only use these methods on new unseen data (which are not in the training set). See User Guide: for details on the difference between outlier detection and novelty detection and how to use LOF for outlier detection.

The number of neighbors considered, (parameter n_neighbors) is typically set 1) greater than the minimum number of samples a cluster has to contain, so that other samples can be local outliers relative to this cluster, and 2) smaller than the maximum number of close by samples that can potentially be local outliers. In practice, such informations are generally not available, and taking n_neighbors=20 appears to work well in general.

```python
import numpy as np
import matplotlib
import matplotlib.pyplot as plt
from sklearn.neighbors import LocalOutlierFactor

print(__doc__)

np.random.seed(42)
xx, yy = np.meshgrid(np.linspace(-5, 5, 500), np.linspace(-5, 5, 500))
```
# Generate normal (not abnormal) training observations
X = 0.3 * np.random.randn(100, 2)
X_train = np.r_[X + 2, X - 2]

# Generate new normal (not abnormal) observations
X = 0.3 * np.random.randn(20, 2)
X_test = np.r_[X + 2, X - 2]

# Generate some abnormal novel observations
X_outliers = np.random.uniform(low=-4, high=4, size=(20, 2))

# fit the model for novelty detection (novelty=True)
clf = LocalOutlierFactor(n_neighbors=20, novelty=True, contamination=0.1)
clf.fit(X_train)

# DO NOT use predict, decision_function and score_samples on X_train as this
# would give wrong results but only on new unseen data (not used in X_train),
# e.g. X_test, X_outliers or the meshgrid
y_pred_test = clf.predict(X_test)
y_pred_outliers = clf.predict(X_outliers)
n_error_test = y_pred_test[y_pred_test == -1].size
n_error_outliers = y_pred_outliers[y_pred_outliers == 1].size

# plot the learned frontier, the points, and the nearest vectors to the plane
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)

plt.title("Novelty Detection with LOF")
plt.contourf(xx, yy, Z, levels=np.linspace(Z.min(), 0, 7), cmap=plt.cm.PuBu)
a = plt.contour(xx, yy, Z, levels=[0], linewidths=2, colors='darkred')
plt.contourf(xx, yy, Z, levels=[0, Z.max()], colors='palevioletred')
s = 40
b1 = plt.scatter(X_train[:, 0], X_train[:, 1], c='white', s=s, edgecolors='k')
b2 = plt.scatter(X_test[:, 0], X_test[:, 1], c='blueviolet', s=s,
                 edgecolors='k')
c = plt.scatter(X_outliers[:, 0], X_outliers[:, 1], c='gold', s=s,
                 edgecolors='k')
plt.axis('tight')
plt.xlim((-5, 5))
plt.ylim((-5, 5))
plt.legend([a.collections[0], b1, b2, c],
           ['learned frontier', 'training observations',
            'new regular observations', 'new abnormal observations'],
           loc="upper left",
           prop=matplotlib.font_manager.FontProperties(size=11))
plt.xlabel("errors novel regular: %d/40 ; errors novel abnormal: %d/40" % (n_error_test, n_error_outliers))
plt.show()
6.24.9 Comparing Nearest Neighbors with and without Neighborhood Components Analysis

An example comparing nearest neighbors classification with and without Neighborhood Components Analysis.

It will plot the class decision boundaries given by a Nearest Neighbors classifier when using the Euclidean distance on the original features, versus using the Euclidean distance after the transformation learned by Neighborhood Components Analysis. The latter aims to find a linear transformation that maximises the (stochastic) nearest neighbor classification accuracy on the training set.
Out:

```
/home/circleci/project/examples/neighbors/plot_nca_classification.py:78:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap=cmap_light, alpha=.8)
/home/circleci/project/examples/neighbors/plot_nca_classification.py:78:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(xx, yy, Z, cmap=cmap_light, alpha=.8)
```

```
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap
from sklearn import datasets
from sklearn.model_selection import train_test_split
```

(continues on next page)
from sklearn.preprocessing import StandardScaler
from sklearn.neighbors import (KNeighborsClassifier,
NeighborhoodComponentsAnalysis)
from sklearn.pipeline import Pipeline

print(__doc__)

n_neighbors = 1

dataset = datasets.load_iris()
X, y = dataset.data, dataset.target

# we only take two features. We could avoid this ugly
# slicing by using a two-dim dataset
X = X[:, [0, 2]]

X_train, X_test, y_train, y_test = 
     train_test_split(X, y, stratify=y, test_size=0.7, random_state=42)

h = .01  # step size in the mesh

# Create color maps
cmap_light = ListedColormap(['#FFAAAA', '#AAFFAA', '#AAAAFF'])
cmap_bold = ListedColormap(['#FF0000', '#00FF00', '#0000FF'])

names = ['KNN', 'NCA, KNN']

classifiers = [Pipeline([[scaler', StandardScaler()]),
   ('knn', KNeighborsClassifier(n_neighbors=n_neighbors))]),
   Pipeline([[scaler', StandardScaler()]),
   ('nca', NeighborhoodComponentsAnalysis()),
   ('knn', KNeighborsClassifier(n_neighbors=n_neighbors))]]

x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
np.arange(y_min, y_max, h))

for name, clf in zip(names, classifiers):
    clf.fit(X_train, y_train)
    score = clf.score(X_test, y_test)

    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]x[y_min, y_max].
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])

    # Put the result into a color plot
    Z = Z.reshape(xx.shape)
    plt.figure()
    plt.pcolormesh(xx, yy, Z, cmap=cmap_light, alpha=.8)

    # Plot also the training and testing points

(continues on next page)
plt.scatter(X[:, 0], X[:, 1], c=y, cmap=cmap_bold, edgecolor='k', s=20)
plt.xlim(xx.min(), xx.max())
plt.ylim(yy.min(), yy.max())
plt.title("{} (k = {})".format(name, n_neighbors))
plt.text(0.9, 0.1, '{:.2f}'.format(score), size=15,
        ha='center', va='center', transform=plt.gca().transAxes)
plt.show()

**Total running time of the script:** ( 0 minutes 17.101 seconds)

### 6.24.10 Dimensionality Reduction with Neighborhood Components Analysis

Sample usage of Neighborhood Components Analysis for dimensionality reduction.

This example compares different (linear) dimensionality reduction methods applied on the Digits data set. The data set contains images of digits from 0 to 9 with approximately 180 samples of each class. Each image is of dimension 8x8 = 64, and is reduced to a two-dimensional data point.

Principal Component Analysis (PCA) applied to this data identifies the combination of attributes (principal components, or directions in the feature space) that account for the most variance in the data. Here we plot the different samples on the 2 first principal components.

Linear Discriminant Analysis (LDA) tries to identify attributes that account for the most variance between classes. In particular, LDA, in contrast to PCA, is a supervised method, using known class labels.

Neighborhood Components Analysis (NCA) tries to find a feature space such that a stochastic nearest neighbor algorithm will give the best accuracy. Like LDA, it is a supervised method.

One can see that NCA enforces a clustering of the data that is visually meaningful despite the large reduction in dimension.
PCA, KNN (k=3)
Test accuracy = 0.52
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.model_selection import train_test_split
from sklearn.decomposition import PCA
from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
from sklearn.neighbors import (KNeighborsClassifier,
                               NeighborhoodComponentsAnalysis)
from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import StandardScaler

print(__doc__)

n_neighbors = 3
random_state = 0

# Load Digits dataset
X, y = datasets.load_digits(return_X_y=True)

# Split into train/test
X_train, X_test, y_train, y_test = 
    train_test_split(X, y, test_size=0.5, stratify=y,
                      random_state=random_state)

dim = len(X[0])

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6.24. Nearest Neighbors
n_classes = len(np.unique(y))

# Reduce dimension to 2 with PCA
pca = make_pipeline(StandardScaler(),
                     PCA(n_components=2, random_state=random_state))

# Reduce dimension to 2 with LinearDiscriminantAnalysis
lda = make_pipeline(StandardScaler(),
                     LinearDiscriminantAnalysis(n_components=2))

# Reduce dimension to 2 with NeighborhoodComponentAnalysis
nca = make_pipeline(StandardScaler(),
                     NeighborhoodComponentsAnalysis(n_components=2,
                                                    random_state=random_state))

# Use a nearest neighbor classifier to evaluate the methods
knn = KNeighborsClassifier(n_neighbors=n_neighbors)

# Make a list of the methods to be compared
dim_reduction_methods = [('PCA', pca), ('LDA', lda), ('NCA', nca)]

# plt.figure()
for i, (name, model) in enumerate(dim_reduction_methods):
    plt.figure()
    # plt.subplot(1, 3, i + 1, aspect=1)

    # Fit the method's model
    model.fit(X_train, y_train)

    # Fit a nearest neighbor classifier on the embedded training set
    knn.fit(model.transform(X_train), y_train)

    # Compute the nearest neighbor accuracy on the embedded test set
    acc_knn = knn.score(model.transform(X_test), y_test)

    # Embed the data set in 2 dimensions using the fitted model
    X_embedded = model.transform(X)

    # Plot the projected points and show the evaluation score
    plt.scatter(X_embedded[:, 0], X_embedded[:, 1], c=y, s=30, cmap='Set1')
    plt.title("{}", KNN (k={}) \nTest accuracy = {:.2f}".format(name, n_neighbors, acc_knn))
plt.show()
6.24.11 Kernel Density Estimate of Species Distributions

This shows an example of a neighbors-based query (in particular a kernel density estimate) on geospatial data, using a Ball Tree built upon the Haversine distance metric – i.e. distances over points in latitude/longitude. The dataset is provided by Phillips et. al. (2006). If available, the example uses basemap to plot the coast lines and national boundaries of South America.

This example does not perform any learning over the data (see Species distribution modeling for an example of classification based on the attributes in this dataset). It simply shows the kernel density estimate of observed data points in geospatial coordinates.

The two species are:

- “Bradypus variegatus”, the Brown-throated Sloth.
- “Microryzomys minutus”, also known as the Forest Small Rice Rat, a rodent that lives in Peru, Colombia, Ecuador, Peru, and Venezuela.

References

Author: Jake Vanderplas <jakevdp@cs.washington.edu>
# License: BSD 3 clause

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import fetch_species_distributions
from sklearn.neighbors import KernelDensity

try:
    from mpl_toolkits.basemap import Basemap
    basemap = True
except ImportError:
    basemap = False

def construct_grids(batch):
    """Construct the map grid from the batch object

    Parameters
    ----------
    batch : Batch object
        The object returned by :func:`fetch_species_distributions`

    Returns
    -------
    (xgrid, ygrid) : 1-D arrays
        The grid corresponding to the values in batch.coverages
    ""
    # x, y coordinates for corner cells
    xmin = batch.x_left_lower_corner + batch.grid_size
    xmax = xmin + (batch.Nx * batch.grid_size)
    ymin = batch.y_left_lower_corner + batch.grid_size
    ymax = ymin + (batch.Ny * batch.grid_size)

    # x coordinates of the grid cells
    xgrid = np.arange(xmin, xmax, batch.grid_size)

    # y coordinates of the grid cells
    ygrid = np.arange(ymin, ymax, batch.grid_size)

    return (xgrid, ygrid)
```

# Get matrices/arrays of species IDs and locations
data = fetch_species_distributions()
species_names = ['Bradypus Variegatus', 'Microryzomys Minutus']

Xtrain = np.vstack([data['train']['dd lat'],
                    data['train']['dd long']]).T
ytrain = np.array([d.decode('ascii').startswith('micro')
                for d in data['train']['species']], dtype='int')

Xtrain *= np.pi / 180.  # Convert lat/long to radians

# Set up the data grid for the contour plot
xgrid, ygrid = construct_grids(data)
X, Y = np.meshgrid(xgrid[::5], ygrid[::5][::-1])
land_reference = data.coverages[6][::5, ::5]
land_mask = (land_reference > -9999).ravel()

xy = np.vstack([Y.ravel(), X.ravel()]).T
xy = xy[land_mask]
xy *= np.pi / 180.

# Plot map of South America with distributions of each species
fig = plt.figure()
fig.subplots_adjust(left=0.05, right=0.95, wspace=0.05)

for i in range(2):
    plt.subplot(1, 2, i + 1)
    # construct a kernel density estimate of the distribution
    print(" - computing KDE in spherical coordinates")
    kde = KernelDensity(bandwidth=0.04, metric='haversine',
                        kernel='gaussian', algorithm='ball_tree')
    kde.fit(Xtrain[ytrain == i])

    # evaluate only on the land: -9999 indicates ocean
    Z = np.full(land_mask.shape[0], -9999, dtype='int')
    Z[land_mask] = np.exp(kde.score_samples(xy))
    Z = Z.reshape(X.shape)

    # plot contours of the density
    levels = np.linspace(0, Z.max(), 25)
    plt.contourf(X, Y, Z, levels=levels, cmap=plt.cm.Reds)
    if basemap:
        print(" - plot coastlines using basemap")
        m = Basemap(projection='cyl', llcrnrlat=Y.min(),
                    urcrnrlat=Y.max(), llcrnrlon=X.min(),
                    urcrnrlon=X.max(), resolution='c')
        m.drawcoastlines()
        m.drawcountries()
    else:
        print(" - plot coastlines from coverage")
        plt.contour(X, Y, land_reference,
                    levels=[-9998], colors="k",
                    linestyles="solid")
        plt.xticks([])
        plt.yticks([])
        plt.title(species_names[i])

(continues on previous page)
6.24.12 Simple 1D Kernel Density Estimation

This example uses the `KernelDensity` class to demonstrate the principles of Kernel Density Estimation in one dimension.

The first plot shows one of the problems with using histograms to visualize the density of points in 1D. Intuitively, a histogram can be thought of as a scheme in which a unit “block” is stacked above each point on a regular grid. As the top two panels show, however, the choice of gridding for these blocks can lead to wildly divergent ideas about the underlying shape of the density distribution. If we instead center each block on the point it represents, we get the estimate shown in the bottom left panel. This is a kernel density estimation with a “top hat” kernel. This idea can be generalized to other kernel shapes: the bottom-right panel of the first figure shows a Gaussian kernel density estimate over the same distribution.

Scikit-learn implements efficient kernel density estimation using either a Ball Tree or KD Tree structure, through the `KernelDensity` estimator. The available kernels are shown in the second figure of this example.

The third figure compares kernel density estimates for a distribution of 100 samples in 1 dimension. Though this example uses 1D distributions, kernel density estimation is easily and efficiently extensible to higher dimensions as well.
import numpy as np
import matplotlib
import matplotlib.pyplot as plt
from scipy.stats import norm
from sklearn.neighbors import KernelDensity
from sklearn.utils.fixes import parse_version

# `normed` is being deprecated in favor of `density` in histograms
if parse_version(matplotlib.__version__) >= parse_version('2.1'):
    density_param = {'density': True}
else:
    density_param = {'normed': True}

# Plot the progression of histograms to kernels
np.random.seed(1)
N = 20
X = np.concatenate((np.random.normal(0, 1, int(0.3 * N)),
                    np.random.normal(5, 1, int(0.7 * N))))[:, np.newaxis]
X_plot = np.linspace(-5, 10, 1000)[:, np.newaxis]
bins = np.linspace(-5, 10, 10)

fig, ax = plt.subplots(2, 2, sharex=True, sharey=True)
fig.subplots_adjust(hspace=0.05, wspace=0.05)

(continues on next page)
# histogram 1
ax[0, 0].hist(X[:, 0], bins=bins, fc='#AAAAFF', **density_param)
ax[0, 0].text(-3.5, 0.31, "Histogram")

# histogram 2
ax[0, 1].hist(X[:, 0], bins=bins + 0.75, fc='#AAAAFF', **density_param)
ax[0, 1].text(-3.5, 0.31, "Histogram, bins shifted")

# tophat KDE
kde = KernelDensity(kernel='tophat', bandwidth=0.75).fit(X)
log_dens = kde.score_samples(X_plot)
ax[1, 0].fill(X_plot[:, 0], np.exp(log_dens), fc='#AAAAFF')
ax[1, 0].text(-3.5, 0.31, "Tophat Kernel Density")

# Gaussian KDE
kde = KernelDensity(kernel='gaussian', bandwidth=0.75).fit(X)
log_dens = kde.score_samples(X_plot)
ax[1, 1].fill(X_plot[:, 0], np.exp(log_dens), fc='#AAAAFF')
ax[1, 1].text(-3.5, 0.31, "Gaussian Kernel Density")

for axi in ax.ravel():
    axi.plot(X[:, 0], np.full(X.shape[0], -0.01), '+k')
    axi.set_xlim(-4, 9)
    axi.set_ylim(-0.02, 0.34)

for axi in ax[:, 0]:
    axi.set_ylabel('Normalized Density')

for axi in ax[1, :]
    axi.set_xlabel('x')

# Plot all available kernels
X_plot = np.linspace(-6, 6, 1000)[..., None]
X_src = np.zeros((1, 1))
fig, ax = plt.subplots(2, 3, sharex=True, sharey=True)
fig.subplots_adjust(left=0.05, right=0.95, hspace=0.05, wspace=0.05)

def format_func(x, loc):
    if x == 0:
        return '0'
    elif x == 1:
        return 'h'
    elif x == -1:
        return '-h'
    else:
        return '\$%ih$' % x

for i, kernel in enumerate(['gaussian', 'tophat', 'epanechnikov',
                            'exponential', 'linear', 'cosine']):
    axi = ax.ravel()[i]
    log_dens = KernelDensity(kernel=kernel).fit(X_src).score_samples(X_plot)
    axi.fill(X_plot[:, 0], np.exp(log_dens), '-k', fc='#AAAAFF')
    axi.text(-2.6, 0.95, kernel)
### 6.24.13 Approximate nearest neighbors in TSNE

This example presents how to chain KNeighborsTransformer and TSNE in a pipeline. It also shows how to wrap the packages annoy and nmslib to replace KNeighborsTransformer and perform approximate nearest neighbors. These packages can be installed with pip install annoy nmslib.

Note: Currently TSNE(metric='precomputed') does not modify the precomputed distances, and thus assumes that precomputed euclidean distances are squared. In future versions, a parameter in TSNE will control the optional squaring of precomputed distances (see #12401).

Note: In KNeighborsTransformer we use the definition which includes each training point as its own neighbor.
in the count of n_neighbors, and for compatibility reasons, one extra neighbor is computed when mode == 'distance'. Please note that we do the same in the proposed wrappers.

Sample output:

Benchmarking on MNIST_2000:
---------------------------
AnnoyTransformer: 0.583 sec
NMSlibTransformer: 0.321 sec
KNeighborsTransformer: 1.225 sec
TSNE with AnnoyTransformer: 4.903 sec
TSNE with NMSlibTransformer: 5.009 sec
TSNE with KNeighborsTransformer: 6.210 sec
TSNE with internal NearestNeighbors: 6.365 sec

Benchmarking on MNIST_10000:
---------------------------
AnnoyTransformer: 4.457 sec
NMSlibTransformer: 2.080 sec
KNeighborsTransformer: 30.680 sec
TSNE with AnnoyTransformer: 30.225 sec
TSNE with NMSlibTransformer: 43.295 sec
TSNE with KNeighborsTransformer: 64.845 sec
TSNE with internal NearestNeighbors: 64.984 sec

# Author: Tom Dupre la Tour
#
# License: BSD 3 clause
import time
import sys

try:
    import annoy
except ImportError:
    print("The package 'annoy' is required to run this example.")
sys.exit()

try:
    import nmslib
except ImportError:
    print("The package 'nmslib' is required to run this example.")
sys.exit()

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.ticker import NullFormatter
from scipy.sparse import csr_matrix
from sklearn.base import BaseEstimator, TransformerMixin
from sklearn.neighbors import KNeighborsTransformer
from sklearn.datasets import fetch_openml
from sklearn.pipeline import make_pipeline
from sklearn.manifold import TSNE
from sklearn.utils import shuffle

print(__doc__)
class NMSlibTransformer(TransformerMixin, BaseEstimator):
    """Wrapper for using nmslib as sklearn's KNeighborsTransformer"""

def __init__(self, n_neighbors=5, metric='euclidean', method='sw-graph',
             n_jobs=1):
    self.n_neighbors = n_neighbors
    self.method = method
    self.metric = metric
    self.n_jobs = n_jobs

def fit(self, X):
    self.n_samples_fit_ = X.shape[0]

    # see more metric in the manual
    # https://github.com/nmslib/nmslib/tree/master/manual
    space = {
        'sqeuclidean': 'l2',
        'euclidean': 'l2',
        'cosine': 'cosinesimil',
        'l1': 'l1',
        'l2': 'l2',
    }[self.metric]

    self.nmslib_ = nmslib.init(method=self.method, space=space)
    self.nmslib_.addDataPointBatch(X)
    self.nmslib_.createIndex()
    return self

def transform(self, X):
    n_samples_transform = X.shape[0]

    # For compatibility reasons, as each sample is considered as its own
    # neighbor, one extra neighbor will be computed.
    n_neighbors = self.n_neighbors + 1

    results = self.nmslib_.knnQueryBatch(X, k=n_neighbors,
                                          num_threads=self.n_jobs)

    indices, distances = zip(*results)
    indices, distances = np.vstack(indices), np.vstack(distances)

    if self.metric == 'sqeuclidean':
        distances **= 2

    indptr = np.arange(0, n_samples_transform * n_neighbors + 1,
                       n_neighbors)
    kneighbors_graph = csr_matrix((distances.ravel(), indices.ravel(),
                                    indptr), shape=(n_samples_transform,
                                                   self.n_samples_fit_))

    return kneighbors_graph

class AnnoyTransformer(TransformerMixin, BaseEstimator):
    """Wrapper for using annoy.AnnoyIndex as sklearn's KNeighborsTransformer"""

def __init__(self, n_neighbors=5, metric='euclidean', n_trees=10,
             n_jobs=1):
    # see more metric in the manual
    # https://github.com/plp/annoy/tree/master/manual
    space = {
        'euclidean': 'l2',
        'manhattan': 'l1',
        'cosine': 'cosinesimil',
    }[self.metric]

    self.annoy_ = annoy.AnnoyIndex(self.feature_dim,
                                    metric=space)

    self.annoy_.add_trees(n_trees)
    self.annoy_.build(n_trees)

    return self

def fit(self, X):
    self.n_samples_fit_ = X.shape[0]

    return self

def transform(self, X):
    n_samples_transform = X.shape[0]

    # For compatibility reasons, as each sample is considered as its own
    # neighbor, one extra neighbor will be computed.
    n_neighbors = self.n_neighbors + 1

    results = self.annoy_.get_nns_by_vector(X, k=n_neighbors,
                                             k=-1, num_threads=self.n_jobs)

    indices, distances = zip(*results)
    indices, distances = np.vstack(indices), np.vstack(distances)

    if self.metric == 'euclidean':
        distances **= 2

    indptr = np.arange(0, n_samples_transform * n_neighbors + 1,
                       n_neighbors)
    kneighbors_graph = csr_matrix((distances.ravel(), indices.ravel(),
                                    indptr), shape=(n_samples_transform,
                                                   self.n_samples_fit_))

    return kneighbors_graph
search_k=-1):  
self.n_neighbors = n_neighbors  
self.n_trees = n_trees  
self.search_k = search_k  
self.metric = metric

def fit(self, X):
    metric = self.metric if self.metric != 'sqeuclidean' else 'euclidean'
    self.annoy_ = annoy.AnnoyIndex(X.shape[1], metric=metric)
    for i, x in enumerate(X):
        self.annoy_.add_item(i, x.tolist())
    self.annoy_.build(self.n_trees)
    return self

def transform(self, X):
    return self._transform(X)

def fit_transform(self, X, y=None):
    return self.fit(X)._transform(X=None)

def _transform(self, X):
    """As `transform`, but handles X is None for faster `fit_transform`."""
    n_samples_transform = self.n_samples_fit_ if X is None else X.shape[0]

    # For compatibility reasons, as each sample is considered as its own
    # neighbor, one extra neighbor will be computed.
    n_neighbors = self.n_neighbors + 1

    indices = np.empty((n_samples_transform, n_neighbors),
                        dtype=int)
    distances = np.empty((n_samples_transform, n_neighbors))

    if X is None:
        for i in range(self.annoy_.get_n_items()):
            ind, dist = self.annoy_.get_nns_by_item(i, n_neighbors, self.search_k,
                                                     include_distances=True)
            indices[i], distances[i] = ind, dist
    else:
        for i, x in enumerate(X):
            indices[i], distances[i] = self.annoy_.get_nns_by_vector(x.tolist(),
                                                                     n_neighbors, self.search_k,
                                                                     include_distances=True)

    if self.metric == 'sqeuclidean':
        distances **= 2

    indptr = np.arange(0, n_samples_transform * n_neighbors + 1, n_neighbors)
    knighbors_graph = csr_matrix((distances.ravel(), indices.ravel(),
                                   indptr), shape=(n_samples_transform,
                                                   self.n_samples_fit_))
    return knighbors_graph

(continues on next page)
def test_transformers():
    """Test that AnnoyTransformer and KNeighborsTransformer give same results"""
    X = np.random.RandomState(42).randn(10, 2)

    knn = KNeighborsTransformer()
    Xt0 = knn.fit_transform(X)

    ann = AnnoyTransformer()
    Xt1 = ann.fit_transform(X)

    nms = NMSlibTransformer()
    Xt2 = nms.fit_transform(X)

    assert_array_almost_equal(Xt0.toarray(), Xt1.toarray(), decimal=5)
    assert_array_almost_equal(Xt0.toarray(), Xt2.toarray(), decimal=5)

def load_mnist(n_samples):
    """Load MNIST, shuffle the data, and return only n_samples."""
    mnist = fetch_openml("mnist_784")
    X, y = shuffle(mnist.data, mnist.target, random_state=2)
    return X[:n_samples] / 255, y[:n_samples]

def run_benchmark():
    datasets = [
        ('MNIST_2000', load_mnist(n_samples=2000)),
        ('MNIST_10000', load_mnist(n_samples=10000)),
    ]

    n_iter = 500
    perplexity = 30
    # TSNE requires a certain number of neighbors which depends on the
    # perplexity parameter.
    # Add one since we include each sample as its own neighbor.
    n_neighbors = int(3. * perplexity + 1) + 1

    transformers = [
        ('AnnoyTransformer', AnnoyTransformer(n_neighbors=n_neighbors,
            metric='sqeuclidean')),
        ('NMSlibTransformer', NMSlibTransformer(n_neighbors=n_neighbors,
            metric='sqeuclidean')),
        ('KNeighborsTransformer', KNeighborsTransformer(
            n_neighbors=n_neighbors, mode='distance', metric='sqeuclidean')),
        ('TSNE with AnnoyTransformer', make_pipeline(
            AnnoyTransformer(n_neighbors=n_neighbors, metric='sqeuclidean'),
            TSNE(metric='precomputed', perplexity=perplexity,
                 method="barnes_hut", random_state=42, n_iter=n_iter), )),
        ('TSNE with NMSlibTransformer', make_pipeline(
            NMSlibTransformer(n_neighbors=n_neighbors, metric='sqeuclidean'),
            TSNE(metric='precomputed', perplexity=perplexity,
                 method="barnes_hut", random_state=42, n_iter=n_iter), )),
        ('TSNE with KNeighborsTransformer', make_pipeline(
            KNeighborsTransformer(n_neighbors=n_neighbors, mode='distance',
                 metric='sqeuclidean')),
    ]
TSNE(metric='precomputed', perplexity=perplexity,  
    method="barnes_hut", random_state=42, n_iter=n_iter),
)  
('TSNE with internal NearestNeighbors',
    TSNE(metric='sqeuclidean', perplexity=perplexity, method="barnes_hut",  
        random_state=42, n_iter=n_iter)),
]

# init the plot
nrows = len(datasets)
ncols = np.sum([1 for name, model in transformers if 'TSNE' in name])
fig, axes = plt.subplots(nrows=nrows, ncols=ncols, squeeze=False,  
    figsize=(5 * ncols, 4 * nrows))
axes = axes.ravel()
i_ax = 0
for dataset_name, (X, y) in datasets:
    msg = 'Benchmarking on %s:' % dataset_name
    print(msg + ' ' * len(msg))
    for transformer_name, transformer in transformers:
        start = time.time()
        Xt = transformer.fit_transform(X)
        duration = time.time() - start

        # print the duration report
        longest = np.max([len(name) for name, model in transformers])
        whitespaces = ' ' * (longest - len(transformer_name))
        print(transformer_name + ' ' + dataset_name)
        print('in %s: %.3f sec' % (transformer_name, duration))

        # plot TSNE embedding which should be very similar across methods
        if 'TSNE' in transformer_name:
            axes[i_ax].set_title(transformer_name + ' on ' + dataset_name)
            axes[i_ax].scatter(Xt[:, 0], Xt[:, 1], c=y.astype(np.int32),  
                alpha=0.2, cmap=plt.cm.viridis)
            axes[i_ax].xaxis.set_major_formatter(NullFormatter())
            axes[i_ax].yaxis.set_major_formatter(NullFormatter())
            axes[i_ax].axis('tight')
            i_ax += 1

fig.tight_layout()
plt.show()

if __name__ == '__main__':
    test_transformers()
    run_benchmark()

Total running time of the script: ( 0 minutes 0.000 seconds)
6.25 Neural Networks

Examples concerning the `sklearn.neural_network` module.

6.25.1 Visualization of MLP weights on MNIST

Sometimes looking at the learned coefficients of a neural network can provide insight into the learning behavior. For example if weights look unstructured, maybe some were not used at all, or if very large coefficients exist, maybe regularization was too low or the learning rate too high.

This example shows how to plot some of the first layer weights in a MLPClassifier trained on the MNIST dataset.

The input data consists of 28x28 pixel handwritten digits, leading to 784 features in the dataset. Therefore the first layer weight matrix have the shape (784, hidden_layer_sizes[0]). We can therefore visualize a single column of the weight matrix as a 28x28 pixel image.

To make the example run faster, we use very few hidden units, and train only for a very short time. Training longer would result in weights with a much smoother spatial appearance. The example will throw a warning because it doesn’t converge, in this case this is what we want because of CI’s time constraints.

```
Out:
Iteration 1, loss = 0.32009978
Iteration 2, loss = 0.15347534
```
Iteration 3, loss = 0.11544755
Iteration 4, loss = 0.09279764
Iteration 5, loss = 0.07889367
Iteration 6, loss = 0.07170497
Iteration 7, loss = 0.06282111
Iteration 8, loss = 0.05530788
Iteration 9, loss = 0.04960484
Iteration 10, loss = 0.04645355
Training set score: 0.986800
Test set score: 0.970000

```python
import warnings
import matplotlib.pyplot as plt
from sklearn.datasets import fetch_openml
from sklearn.exceptions import ConvergenceWarning
from sklearn.neural_network import MLPClassifier

print(__doc__)

# Load data from https://www.openml.org/d/554
X, y = fetch_openml('mnist_784', version=1, return_X_y=True)
X = X / 255.

# rescale the data, use the traditional train/test split
X_train, X_test = X[:60000], X[60000:]
y_train, y_test = y[:60000], y[60000:]

mlp = MLPClassifier(hidden_layer_sizes=(50,), max_iter=10, alpha=1e-4,
solver='sgd', verbose=10, random_state=1,
learning_rate_init=.1)

# this example won't converge because of CI's time constraints, so we catch the
# warning and ignore it here
with warnings.catch_warnings():
    warnings.filterwarnings("ignore", category=ConvergenceWarning,
module="sklearn")
        mlp.fit(X_train, y_train)

print("Training set score: \$f\) % mlp.score(X_train, y_train))
print("Test set score: \$f\) % mlp.score(X_test, y_test))

fig, axes = plt.subplots(4, 4)
# use global min / max to ensure all weights are shown on the same scale
vmin, vmax = mlp.coefs_[0].min(), mlp.coefs_[0].max()
for coef, ax in zip(mlp.coefs_[0].T, axes.ravel()):
    ax.matshow(coef.reshape(28, 28), cmap=plt.cm.gray, vmin=.5 * vmin,
    vmax=.5 * vmax)
ax.set_xticks(())
ax.set_yticks(())
plt.show()
```

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6.25.2 Restricted Boltzmann Machine features for digit classification

For greyscale image data where pixel values can be interpreted as degrees of blackness on a white background, like handwritten digit recognition, the Bernoulli Restricted Boltzmann machine model (BernoulliRBM) can perform effective non-linear feature extraction.

In order to learn good latent representations from a small dataset, we artificially generate more labeled data by perturbing the training data with linear shifts of 1 pixel in each direction.

This example shows how to build a classification pipeline with a BernoulliRBM feature extractor and a LogisticRegression classifier. The hyperparameters of the entire model (learning rate, hidden layer size, regularization) were optimized by grid search, but the search is not reproduced here because of runtime constraints.

Logistic regression on raw pixel values is presented for comparison. The example shows that the features extracted by the BernoulliRBM help improve the classification accuracy.

### 100 components extracted by RBM

Out:

```
[BernoulliRBM] Iteration 1, pseudo-likelihood = -25.39, time = 0.15s
[BernoulliRBM] Iteration 2, pseudo-likelihood = -23.77, time = 0.21s
[BernoulliRBM] Iteration 3, pseudo-likelihood = -22.94, time = 0.21s
[BernoulliRBM] Iteration 4, pseudo-likelihood = -21.89, time = 0.20s
[BernoulliRBM] Iteration 5, pseudo-likelihood = -21.54, time = 0.20s
[BernoulliRBM] Iteration 6, pseudo-likelihood = -21.19, time = 0.20s
[BernoulliRBM] Iteration 7, pseudo-likelihood = -20.74, time = 0.20s
[BernoulliRBM] Iteration 8, pseudo-likelihood = -20.47, time = 0.19s
[BernoulliRBM] Iteration 9, pseudo-likelihood = -20.42, time = 0.19s
[BernoulliRBM] Iteration 10, pseudo-likelihood = -20.15, time = 0.19s
```

(continues on next page)
Logistic regression using RBM features:

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0.99</td>
<td>0.98</td>
<td>0.99</td>
<td>174</td>
</tr>
<tr>
<td>1</td>
<td>0.91</td>
<td>0.93</td>
<td>0.92</td>
<td>184</td>
</tr>
<tr>
<td>2</td>
<td>0.94</td>
<td>0.95</td>
<td>0.95</td>
<td>166</td>
</tr>
<tr>
<td>3</td>
<td>0.94</td>
<td>0.88</td>
<td>0.91</td>
<td>194</td>
</tr>
<tr>
<td>4</td>
<td>0.96</td>
<td>0.95</td>
<td>0.95</td>
<td>186</td>
</tr>
<tr>
<td>5</td>
<td>0.94</td>
<td>0.91</td>
<td>0.92</td>
<td>181</td>
</tr>
<tr>
<td>6</td>
<td>0.98</td>
<td>0.97</td>
<td>0.97</td>
<td>207</td>
</tr>
<tr>
<td>7</td>
<td>0.94</td>
<td>0.99</td>
<td>0.98</td>
<td>154</td>
</tr>
<tr>
<td>8</td>
<td>0.90</td>
<td>0.89</td>
<td>0.90</td>
<td>182</td>
</tr>
<tr>
<td>9</td>
<td>0.87</td>
<td>0.93</td>
<td>0.90</td>
<td>169</td>
</tr>
</tbody>
</table>

accuracy: 0.94 1797
macro avg: 0.94 0.94 0.94 1797
weighted avg: 0.94 0.94 0.94 1797

Logistic regression using raw pixel features:

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0.90</td>
<td>0.92</td>
<td>0.91</td>
<td>174</td>
</tr>
<tr>
<td>1</td>
<td>0.60</td>
<td>0.58</td>
<td>0.59</td>
<td>184</td>
</tr>
<tr>
<td>2</td>
<td>0.76</td>
<td>0.85</td>
<td>0.80</td>
<td>166</td>
</tr>
<tr>
<td>3</td>
<td>0.78</td>
<td>0.79</td>
<td>0.78</td>
<td>194</td>
</tr>
<tr>
<td>4</td>
<td>0.82</td>
<td>0.84</td>
<td>0.83</td>
<td>186</td>
</tr>
<tr>
<td>5</td>
<td>0.76</td>
<td>0.76</td>
<td>0.76</td>
<td>181</td>
</tr>
<tr>
<td>6</td>
<td>0.90</td>
<td>0.87</td>
<td>0.89</td>
<td>207</td>
</tr>
<tr>
<td>7</td>
<td>0.85</td>
<td>0.88</td>
<td>0.87</td>
<td>154</td>
</tr>
<tr>
<td>8</td>
<td>0.67</td>
<td>0.58</td>
<td>0.62</td>
<td>182</td>
</tr>
<tr>
<td>9</td>
<td>0.75</td>
<td>0.76</td>
<td>0.75</td>
<td>169</td>
</tr>
</tbody>
</table>

accuracy: 0.78 1797
macro avg: 0.78 0.78 0.78 1797
weighted avg: 0.78 0.78 0.78 1797

print(__doc__)

# Authors: Yann N. Dauphin, Vlad Niculae, Gabriel Synnaeve
# License: BSD

import numpy as np
import matplotlib.pyplot as plt
from scipy.ndimage import convolve
from sklearn import linear_model, datasets, metrics
from sklearn.model_selection import train_test_split
from sklearn.neural_network import BernoulliRBM
from sklearn.pipeline import Pipeline
from sklearn.base import clone

6.25. Neural Networks 1519
def nudge_dataset(X, Y):
    """This produces a dataset 5 times bigger than the original one,
    by moving the 8x8 images in X around by 1px to left, right, down, up
    """
    direction_vectors = [
        [[0, 1, 0],
         [0, 0, 0],
         [0, 0, 0]],
    
        [[0, 0, 0],
         [1, 0, 0],
         [0, 0, 0]],
    
        [[0, 0, 0],
         [0, 0, 1],
         [0, 0, 0]],
    
        [[0, 0, 0],
         [0, 0, 0],
         [0, 1, 0]]]

def shift(x, w):
    return convolve(x.reshape((8, 8)), mode='constant', weights=w).ravel()

X = np.concatenate([X] +
                   [np.apply_along_axis(shift, 1, X, vector)
                    for vector in direction_vectors])
Y = np.concatenate([Y for _ in range(5)], axis=0)
return X, Y

# Load Data
X, y = datasets.load_digits(return_X_y=True)
X = np.asarray(X, 'float32')
X, Y = nudge_dataset(X, y)
X = (X - np.min(X, 0)) / (np.max(X, 0) + 0.0001)  # 0-1 scaling

X_train, X_test, Y_train, Y_test = train_test_split(
    X, Y, test_size=0.2, random_state=0)

# Models we will use
logistic = linear_model.LogisticRegression(solver='newton-cg', tol=1)
rbm = BernoulliRBM(random_state=0, verbose=True)

rbm_features_classifier = Pipeline(
    steps=[('rbm', rbm), ('logistic', logistic)])

# Hyper-parameters. These were set by cross-validation,
# using a GridSearchCV. Here we are not performing cross-validation to save time.
rbm.learning_rate = 0.06
rbm.n_iter = 10
# More components tend to give better prediction performance, but larger fitting time
rbm.n_components = 100
logistic.C = 6000

# Training RBM-Logistic Pipeline
rbm_features_classifier.fit(X_train, Y_train)

# Training the Logistic regression classifier directly on the pixel
raw_pixel_classifier = clone(logistic)
raw_pixel_classifier.C = 100.
raw_pixel_classifier.fit(X_train, Y_train)

# #############################################################################
# Evaluation
Y_pred = rbm_features_classifier.predict(X_test)
print("Logistic regression using RBM features:
metrics.classification_report(Y_test, Y_pred))
Y_pred = raw_pixel_classifier.predict(X_test)
print("Logistic regression using raw pixel features:
metrics.classification_report(Y_test, Y_pred))

# #############################################################################
# Plotting
plt.figure(figsize=(4.2, 4))
for i, comp in enumerate(rbm.components_):
    plt.subplot(10, 10, i + 1)
    plt.imshow(comp.reshape((8, 8)), cmap=plt.cm.gray_r, interpolation='nearest')
    plt.xticks(()
plt.yticks(()
plt.suptitle('100 components extracted by RBM', fontsize=16)
plt.subplots_adjust(0.08, 0.02, 0.92, 0.85, 0.08, 0.23)
plt.show()
Out:

learning on dataset iris
training: constant learning-rate
Training set score: 0.980000
Training set loss: 0.096950
training: constant with momentum
Training set score: 0.980000
Training set loss: 0.049530
training: constant with Nesterov's momentum
Training set score: 0.980000
Training set loss: 0.049540
training: inv-scaling learning-rate
Training set score: 0.360000
Training set loss: 0.978444
training: inv-scaling with momentum
Training set score: 0.860000
Training set loss: 0.503452
training: inv-scaling with Nesterov's momentum
Training set score: 0.860000
Training set loss: 0.504185
training: adam
Training set score: 0.980000
Training set loss: 0.045311

learning on dataset digits
training: constant learning-rate
Training set score: 0.956038
Training set loss: 0.243802
(continues on next page)
training: constant with momentum
Training set score: 0.992766
Training set loss: 0.041297
training: constant with Nesterov's momentum
Training set score: 0.993879
Training set loss: 0.042898
training: inv-scaling learning-rate
Training set score: 0.638843
Training set loss: 1.855465
training: inv-scaling with momentum
Training set score: 0.912632
Training set loss: 0.290584
training: inv-scaling with Nesterov's momentum
Training set score: 0.909293
Training set loss: 0.318387
training: adam
Training set score: 0.991653
Training set loss: 0.045934

learning on dataset circles
training: constant learning-rate
Training set score: 0.840000
Training set loss: 0.601052
training: constant with momentum
Training set score: 0.940000
Training set loss: 0.157334
training: constant with Nesterov's momentum
Training set score: 0.940000
Training set loss: 0.154453
training: inv-scaling learning-rate
Training set score: 0.500000
Training set loss: 0.692470
training: inv-scaling with momentum
Training set score: 0.500000
Training set loss: 0.689143
training: inv-scaling with Nesterov's momentum
Training set score: 0.500000
Training set loss: 0.689751
training: adam
Training set score: 0.940000
Training set loss: 0.150527

learning on dataset moons
training: constant learning-rate
Training set score: 0.850000
Training set loss: 0.341523
training: constant with momentum
Training set score: 0.850000
Training set loss: 0.336188
training: constant with Nesterov's momentum
Training set score: 0.850000
Training set loss: 0.335919
training: inv-scaling learning-rate
Training set score: 0.500000
Training set loss: 0.689015
training: inv-scaling with momentum
Training set score: 0.830000

(continues on next page)
Training set loss: 0.512595
training: inv-scaling with Nesterov's momentum
Training set score: 0.830000
Training set loss: 0.513034
training: adam
Training set score: 0.930000
Training set loss: 0.170087

```
print(__doc__)

import warnings
import matplotlib.pyplot as plt
from sklearn.neural_network import MLPClassifier
from sklearn.preprocessing import MinMaxScaler
from sklearn import datasets
from sklearn.exceptions import ConvergenceWarning

# different learning rate schedules and momentum parameters
params = [{"solver": 'sgd', 'learning_rate': 'constant', 'momentum': 0, 'learning_rate_init': 0.2},
          {"solver": 'sgd', 'learning_rate': 'constant', 'momentum': .9, 'nesterovs_momentum': False, 'learning_rate_init': 0.2},
          {"solver": 'sgd', 'learning_rate': 'constant', 'momentum': .9, 'nesterovs_momentum': True, 'learning_rate_init': 0.2},
          {"solver": 'sgd', 'learning_rate': 'invscaling', 'momentum': 0, 'learning_rate_init': 0.2},
          {"solver": 'sgd', 'learning_rate': 'invscaling', 'momentum': .9, 'nesterovs_momentum': False, 'learning_rate_init': 0.2},
          {"solver": 'sgd', 'learning_rate': 'invscaling', 'momentum': .9, 'nesterovs_momentum': True, 'learning_rate_init': 0.2},
          {"solver": 'adam', 'learning_rate_init': 0.01}]

labels = ["constant learning-rate", "constant with momentum", "constant with Nesterov's momentum", "inv-scaling learning-rate", "inv-scaling with momentum", "inv-scaling with Nesterov's momentum", "adam"]

plot_args = [{'c': 'red', 'linestyle': '-'},
             {'c': 'green', 'linestyle': '-.'},
             {'c': 'blue', 'linestyle': '--'},
             {'c': 'red', 'linestyle': '--'},
             {'c': 'green', 'linestyle': '-.'},
             {'c': 'blue', 'linestyle': '--'},
             {'c': 'black', 'linestyle': '-'}]

def plot_on_dataset(X, y, ax, name):
    # for each dataset, plot learning for each learning strategy
    print("\nlearning on dataset %s" % name)
```
ax.set_title(name)

X = MinMaxScaler().fit_transform(X)
mlps = []
if name == "digits":  
    # digits is larger but converges fairly quickly
    max_iter = 15
else:
    max_iter = 400

for label, param in zip(labels, params):
    print("training: %s" % label)
    mlp = MLPClassifier(random_state=0,
                         max_iter=max_iter, **param)

    # some parameter combinations will not converge as can be seen on the
    # plots so they are ignored here
    with warnings.catch_warnings():
        warnings.filterwarnings("ignore", category=ConvergenceWarning,
                                 module="sklearn")
        mlp.fit(X, y)

    mlp.loss_curve_  
    mlps.append(mlp)
    print("Training set score: %f" % mlp.score(X, y))
    print("Training set loss: %f" % mlp.loss_)
    for mlp, label, args in zip(mlps, labels, plot_args):
        ax.plot(mlp.loss_curve_, label=label, **args)

fig, axes = plt.subplots(2, 2, figsize=(15, 10))
# load / generate some toy datasets
iris = datasets.load_iris()
X_digits, y_digits = datasets.load_digits(return_X_y=True)
data_sets = [(iris.data, iris.target),
             (X_digits, y_digits),
             datasets.make_circles(noise=0.2, factor=0.5, random_state=1),
             datasets.make_moons(noise=0.3, random_state=0)]

for ax, data, name in zip(axes.ravel(), data_sets, ['iris', 'digits',
                                                      'circles', 'moons']):
    plot_on_dataset(*data, ax=ax, name=name)

fig.legend(ax.get_lines(), labels, ncol=3, loc="upper center")
plt.show()
### 6.25.4 Varying regularization in Multi-layer Perceptron

A comparison of different values for regularization parameter ‘alpha’ on synthetic datasets. The plot shows that different alphas yield different decision functions.

Alpha is a parameter for regularization term, aka penalty term, that combats overfitting by constraining the size of the weights. Increasing alpha may fix high variance (a sign of overfitting) by encouraging smaller weights, resulting in a decision boundary plot that appears with lesser curvatures. Similarly, decreasing alpha may fix high bias (a sign of underfitting) by encouraging larger weights, potentially resulting in a more complicated decision boundary.

```python
print(__doc__)

# Author: Issam H. Laradji
# License: BSD 3 clause

import numpy as np
from matplotlib import pyplot as plt
from matplotlib.colors import ListedColormap
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
from sklearn.datasets import make_moons, make_circles, make_classification
from sklearn.neural_network import MLPClassifier
from sklearn.pipeline import make_pipeline

h = .02  # step size in the mesh

alphas = np.logspace(-1, 1, 5)

classifiers = []
names = []
for alpha in alphas:
    classifiers.append(make_pipeline(StandardScaler(),
```

(continues on next page)
MLPClassifier(solver='lbfgs', alpha=alpha, random_state=1, max_iter=2000, early_stopping=True, hidden_layer_sizes=[100, 100],

)  
names.append(f'alpha {alpha:.2f}')

X, y = make_classification(n_features=2, n_redundant=0, n_informative=2, random_state=0, n_clusters_per_class=1)

rng = np.random.RandomState(2)
X += 2 * rng.uniform(size=X.shape)
linearly_separable = (X, y)

datasets = [make_moons(noise=0.3, random_state=0), make_circles(noise=0.2, factor=0.5, random_state=1), linearly_separable]

figure = plt.figure(figsize=(17, 9))
i = 1

# iterate over datasets
for X, y in datasets:
    # split into training and test part
    X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=.4)

    x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
    y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
    xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))

    # just plot the dataset first
    cm = plt.cm.RdBu
    cm_bright = ListedColormap(['#FF0000', '#0000FF'])
    ax = plt.subplot(len(datasets), len(classifiers) + 1, i)
    # Plot the training points
    ax.scatter(X_train[:, 0], X_train[:, 1], c=y_train, cmap=cm_bright)
    # and testing points
    ax.scatter(X_test[:, 0], X_test[:, 1], c=y_test, cmap=cm_bright, alpha=0.6)
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xticks(())
    ax.set_yticks(())
i += 1

# iterate over classifiers
for name, clf in zip(names, classifiers):
    ax = plt.subplot(len(datasets), len(classifiers) + 1, i)
    clf.fit(X_train, y_train)
    score = clf.score(X_test, y_test)

    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max] x [y_min, y_max].
    if hasattr(clf, "decision_function"):
        Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
    else:
        Z = clf.predict_proba(np.c_[xx.ravel(), yy.ravel()])[:, 1]

    # Put the result into a color plot
(continues on next page)
6.26 Pipelines and composite estimators

Examples of how to compose transformers and pipelines from other estimators. See the User Guide.

6.26.1 Concatenating multiple feature extraction methods

In many real-world examples, there are many ways to extract features from a dataset. Often it is beneficial to combine several methods to obtain good performance. This example shows how to use FeatureUnion to combine features obtained by PCA and univariate selection.

Combining features using this transformer has the benefit that it allows cross validation and grid searches over the whole process.

The combination used in this example is not particularly helpful on this dataset and is only used to illustrate the usage of FeatureUnion.

Out:

```
Combined space has 3 features
Fitting 5 folds for each of 18 candidates, totalling 90 fits
[CV 1/5; 1/18] START features__pca__n_components=1, features__univ_select__k=1, svm__
  → C=0.1
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  → C=0.1; total time= 0.0s
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6.26. Pipelines and composite estimators
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| CV 1/5; 12/18 | START features__pca__n_components=2, features__univ_select__k=2, svm__ → C=10 |
| CV 1/5; 12/18 | END features__pca__n_components=2, features__univ_select__k=2, svm__ → C=10; total time= 0.0s |
| CV 2/5; 12/18 | START features__pca__n_components=2, features__univ_select__k=2, svm__ → C=10 |
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| CV 1/5; 13/18 | START features__pca__n_components=3, features__univ_select__k=1, svm__ → C=0.1 |
| CV 1/5; 13/18 | END features__pca__n_components=3, features__univ_select__k=1, svm__ → C=0.1; total time= 0.0s |

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[CV 1/5; 15/18] END features__pca__n_components=3, features__univ_select__k=1, svm__ →C=10; total time= 0.0s
[CV 2/5; 15/18] START features__pca__n_components=3, features__univ_select__k=1, svm__ →C=10
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Pipeline(steps=[('features',
    FeatureUnion(transformer_list=[('pca', PCA(n_components=3)),
    ('univ_select',
        SelectKBest(k=1))]),
    ('svm', SVC(C=10, kernel='linear'))])

# Author: Andreas Mueller <amueller@ais.uni-bonn.de>
# License: BSD 3 clause

from sklearn.pipeline import Pipeline, FeatureUnion
from sklearn.model_selection import GridSearchCV
from sklearn.svm import SVC
from sklearn.datasets import load_iris
from sklearn.decomposition import PCA
from sklearn.feature_selection import SelectKBest

iris = load_iris()
X, y = iris.data, iris.target

# This dataset is way too high-dimensional. Better do PCA:
pca = PCA(n_components=2)

# Maybe some original features were good, too?
selection = SelectKBest(k=1)

# Build estimator from PCA and Univariate selection:
combined_features = FeatureUnion([('pca', pca), ('univ_select', selection)])

# Use combined features to transform dataset:
X_features = combined_features.fit(X, y).transform(X)
print("Combined space has", X_features.shape[1], "features")

svm = SVC(kernel="linear")

# Do grid search over k, n_components and C:
pipeline = Pipeline([('features', combined_features), ('svm', svm)])
param_grid = dict(features__pca__n_components=[1, 2, 3],
    features__univ_select__k=[1, 2],
    svm__C=[0.1, 1, 10])
grid_search = GridSearchCV(pipeline, param_grid=param_grid, verbose=10)
grid_search.fit(X, y)
print(grid_search.best_estimator_)

Total running time of the script: 0.333 seconds
6.26.2 Pipelining: chaining a PCA and a logistic regression

The PCA does an unsupervised dimensionality reduction, while the logistic regression does the prediction. We use a GridSearchCV to set the dimensionality of the PCA

Out:

Best parameter (CV score=0.920):
{'logistic__C': 0.046415888336127774, 'pca__n_components': 45}

print(__doc__)

(continues on next page)
# Code source: Gaël Varoquaux
# Modified for documentation by Jaques Grobler
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
import pandas as pd

from sklearn import datasets
from sklearn.decomposition import PCA
from sklearn.linear_model import LogisticRegression
from sklearn.pipeline import Pipeline
from sklearn.model_selection import GridSearchCV

# Define a pipeline to search for the best combination of PCA truncation
# and classifier regularization.
pca = PCA()
# set the tolerance to a large value to make the example faster
logistic = LogisticRegression(max_iter=10000, tol=0.1)
pipe = Pipeline(steps=[('pca', pca), ('logistic', logistic)])

X_digits, y_digits = datasets.load_digits(return_X_y=True)

# Parameters of pipelines can be set using '__' separated parameter names:
param_grid = {
    'pca__n_components': [5, 15, 30, 45, 64],
    'logistic__C': np.logspace(-4, 4, 4),
}
search = GridSearchCV(pipe, param_grid, n_jobs=-1)
search.fit(X_digits, y_digits)

print("Best parameter (CV score=\$0.3f):" % search.best_score_)
print(search.best_params_)

# Plot the PCA spectrum
pca.fit(X_digits)

fig, (ax0, ax1) = plt.subplots(nrows=2, sharex=True, figsize=(6, 6))
ax0.plot(np.arange(1, pca.n_components_ + 1), pca.explained_variance_ratio_, '+', linewidth=2)
ax0.set_ylabel('PCA explained variance ratio')
ax0.axvline(search.best_estimator_.named_steps['pca'].n_components, linestyle=':', label='n_components chosen')
ax0.legend(prop=dict(size=12))

# For each number of components, find the best classifier results
results = pd.DataFrame(search.cv_results_)
components_col = 'param_pca__n_components'
best_clfs = results.groupby(components_col).apply(
    lambda g: g.nlargest(1, 'mean_test_score'))
best_clfs.plot(x=components_col, y='mean_test_score', yerr='std_test_score',
               legend=False, ax=ax1)
ax1.set_ylabel('Classification accuracy (val)')
6.26.3 Selecting dimensionality reduction with Pipeline and GridSearchCV

This example constructs a pipeline that does dimensionality reduction followed by prediction with a support vector classifier. It demonstrates the use of GridSearchCV and Pipeline to optimize over different classes of estimators in a single CV run – unsupervised PCA and NMF dimensionality reductions are compared to univariate feature selection during the grid search.

Additionally, Pipeline can be instantiated with the memory argument to memoize the transformers within the pipeline, avoiding to fit again the same transformers over and over.

Note that the use of memory to enable caching becomes interesting when the fitting of a transformer is costly.

This section illustrates the use of a Pipeline with GridSearchCV

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load_digits
from sklearn.model_selection import GridSearchCV
from sklearn.pipeline import Pipeline
from sklearn.svm import LinearSVC
from sklearn.decomposition import PCA, NMF
from sklearn.feature_selection import SelectKBest, chi2

print(__doc__)

pipe = Pipeline([(  
    # the reduce_dim stage is populated by the param_grid
    ('reduce_dim', 'passthrough'),
    ('classify', LinearSVC(dual=False, max_iter=10000))
)])

N_FEATURES_OPTIONS = [2, 4, 8]
C_OPTIONS = [1, 10, 100, 1000]

param_grid = [{
    'reduce_dim': [PCA(iterated_power=7), NMF()],
    'reduce_dim__n_components': N_FEATURES_OPTIONS,
    'classify__C': C_OPTIONS
    },
    {'reduce_dim': [SelectKBest(chi2)],
    'reduce_dim__k': N_FEATURES_OPTIONS,
    }
```

Total running time of the script: (0 minutes 7.125 seconds)

reducer_labels = ['PCA', 'NMF', 'KBest(chi2)']

grid = GridSearchCV(pipe, n_jobs=1, param_grid=param_grid)
X, y = load_digits(return_X_y=True)
grid.fit(X, y)

mean_scores = np.array(grid.cv_results_['mean_test_score'])
# scores are in the order of param_grid iteration, which is alphabetical
mean_scores = mean_scores.reshape(len(C_OPTIONS), -1, len(N_FEATURES_OPTIONS))
# select score for best C
mean_scores = mean_scores.max(axis=0)
bar_offsets = (np.arange(len(N_FEATURES_OPTIONS)) *
    (len(reducer_labels) + 1) + .5)

plt.figure()
COLORS = 'bgrcmyk'
for i, (label, reducer_scores) in enumerate(zip(reducer_labels, mean_scores)):
    plt.bar(bar_offsets + i, reducer_scores, label=label, color=COLORS[i])
plt.title("Comparing feature reduction techniques")
plt.xlabel('Reduced number of features')
plt.ylabel('Digit classification accuracy')
plt.ylim((0, 1))
plt.legend(loc='upper left')
plt.show()
Comparing feature reduction techniques

Out:

/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features, will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn(('The 'init' value, when 'init=None' and ' /home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features, will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
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    will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn("The 'init' value, when 'init=None' and "
/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features,
    will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn("The 'init' value, when 'init=None' and "
/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features,
    will be changed from 'nndsvd' to 'nndsvda' in 1.1 (renaming of 0.26).
warnings.warn("The 'init' value, when 'init=None' and "
/home/circleci/project/sklearn/decomposition/_nmf.py:312: FutureWarning: The 'init' value, when 'init=None' and n_components is less than n_samples and n_features,
6.26. Pipelines and composite estimators

(continued on previous page)
Caching transformers within a Pipeline

It is sometimes worthwhile storing the state of a specific transformer since it could be used again. Using a pipeline in GridSearchCV triggers such situations. Therefore, we use the argument memory to enable caching.

**Warning:** Note that this example is, however, only an illustration since for this specific case fitting PCA is not necessarily slower than loading the cache. Hence, use the memory constructor parameter when the fitting of a transformer is costly.
from joblib import Memory
from shutil import rmtree

# Create a temporary folder to store the transformers of the pipeline
location = 'cachedir'
memory = Memory(location=location, verbose=10)
cached_pipe = Pipeline([('reduce_dim', PCA()),
                        ('classify', LinearSVC(dual=False, max_iter=10000))],
                        memory=memory)

# This time, a cached pipeline will be used within the grid search

# Delete the temporary cache before exiting
memory.clear(warn=False)
rmtree(location)

The PCA fitting is only computed at the evaluation of the first configuration of the C parameter of the LinearSVC classifier. The other configurations of C will trigger the loading of the cached PCA estimator data, leading to save processing time. Therefore, the use of caching the pipeline using memory is highly beneficial when fitting a transformer is costly.

**Total running time of the script:** ( 0 minutes 4.149 seconds)

### 6.26.4 Column Transformer with Mixed Types

This example illustrates how to apply different preprocessing and feature extraction pipelines to different subsets of features, using ColumnTransformer. This is particularly handy for the case of datasets that contain heterogeneous data types, since we may want to scale the numeric features and one-hot encode the categorical ones.

In this example, the numeric data is standard-scaled after mean-imputation, while the categorical data is one-hot encoded after imputing missing values with a new category ('missing').

In addition, we show two different ways to dispatch the columns to the particular pre-processor: by column names and by column data types.

Finally, the preprocessing pipeline is integrated in a full prediction pipeline using Pipeline, together with a simple classification model.

```python
# Author: Pedro Morales <part.morales@gmail.com>
#
# License: BSD 3 clause

import numpy as np

from sklearn.compose import ColumnTransformer
from sklearn.datasets import fetch_openml
from sklearn.pipeline import Pipeline
from sklearn.impute import SimpleImputer
from sklearn.preprocessing import StandardScaler, OneHotEncoder
from sklearn.linear_model import LogisticRegression
from sklearn.model_selection import train_test_split, GridSearchCV

np.random.seed(0)

# Load data from https://www.openml.org/d/40945
X, y = fetch_openml("titanic", version=1, as_frame=True, return_X_y=True)
```
Alternatively X and y can be obtained directly from the frame attribute:

```python
# X = titanic.frame.drop('survived', axis=1)
# y = titanic.frame['survived']
```

**Use ColumnTransformer by selecting column by names**

We will train our classifier with the following features:

**Numeric Features:**
- `age`: float;
- `fare`: float.

**Categorical Features:**
- `embarked`: categories encoded as strings {'C', 'S', 'Q'};
- `sex`: categories encoded as strings {'female', 'male'};
- `pclass`: ordinal integers {1, 2, 3}.

We create the preprocessing pipelines for both numeric and categorical data. Note that `pclass` could either be treated as a categorical or numeric feature.

```python
numeric_features = ['age', 'fare']
numeric_transformer = Pipeline(steps=[
    ('imputer', SimpleImputer(strategy='median')),
    ('scaler', StandardScaler())
])
categorical_features = ['embarked', 'sex', 'pclass']
categorical_transformer = OneHotEncoder(handle_unknown='ignore')

preprocessor = ColumnTransformer(transformers=[
    ('num', numeric_transformer, numeric_features),
    ('cat', categorical_transformer, categorical_features)])

# Append classifier to preprocessing pipeline.
# Now we have a full prediction pipeline.
clf = Pipeline(steps=[('preprocessor', preprocessor),
                      ('classifier', LogisticRegression())])

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2,
                                                      random_state=0)

clf.fit(X_train, y_train)

print("model score: %.3f" % clf.score(X_test, y_test))
```

Out:

```
model score: 0.790
```
**HTML representation of Pipeline**

When the `Pipeline` is printed out in a jupyter notebook an HTML representation of the estimator is displayed as follows:

```python
from sklearn import set_config

set_config(display='diagram')
clf
```

**Use `ColumnTransformer` by selecting column by data types**

When dealing with a cleaned dataset, the preprocessing can be automatic by using the data types of the column to decide whether to treat a column as a numerical or categorical feature. `sklearn.compose.make_column_selector` gives this possibility. First, let's only select a subset of columns to simplify our example.

```python
subset_feature = ['embarked', 'sex', 'pclass', 'age', 'fare']
X_train, X_test = X_train[subset_feature], X_test[subset_feature]
```

Then, we introspect the information regarding each column data type.

```python
X_train.info()
```

Out:

```python
<class 'pandas.core.frame.DataFrame'>
Int64Index: 1047 entries, 1118 to 684
Data columns (total 5 columns):
   # Column    Non-Null Count  Dtype
  --- ------- ------------- ----- ----
   0 embarked 1045 non-null category
   1 sex      1047 non-null category
   2 pclass   1047 non-null float64
   3 age      841 non-null float64
   4 fare     1046 non-null float64
dtypes: category(2), float64(3)
memory usage: 35.0 KB
```

We can observe that the `embarked` and `sex` columns were tagged as `category` columns when loading the data with `fetch_openml`. Therefore, we can use this information to dispatch the categorical columns to the `categorical_transformer` and the remaining columns to the `numerical_transformer`.

**Note:** In practice, you will have to handle yourself the column data type. If you want some columns to be considered as `category`, you will have to convert them into categorical columns. If you are using pandas, you can refer to their documentation regarding Categorical data.

```python
from sklearn.compose import make_column_selector as selector

preprocessor = ColumnTransformer(transformers=[
    ('num', numeric_transformer, selector(dtype_exclude="category")),
    ('cat', categorical_transformer, selector(dtype_include="category"))
])
clf = Pipeline(steps=[('preprocessor', preprocessor),
```
('classifier', LogisticRegression())

c.fit(X_train, y_train)

print("model score: \$%.3f\$ \% c.score(X_test, y_test))

Out:

model score: 0.794

The resulting score is not exactly the same as the one from the previous pipeline because the dtype-based selector treats the pclass columns as a numeric feature instead of a categorical feature as previously:

selector(dtype_exclude="category")(X_train)

Out:

['pclass', 'age', 'fare']

selector(dtype_include="category")(X_train)

Out:

['embarked', 'sex']

### Using the prediction pipeline in a grid search

Grid search can also be performed on the different preprocessing steps defined in the ColumnTransformer object, together with the classifier's hyperparameters as part of the Pipeline. We will search for both the imputer strategy of the numeric preprocessing and the regularization parameter of the logistic regression using GridSearchCV.

```python	param_grid = {
    'preprocessor__num__imputer__strategy': ['mean', 'median'],
    'classifier__C': [0.1, 1.0, 10, 100],
}

grid_search = GridSearchCV(clf, param_grid, cv=10)
grid_search
```

Calling ‘fit’ triggers the cross-validated search for the best hyper-parameters combination:

```python
grid_search.fit(X_train, y_train)

print(f"Best params:")

print(grid_search.best_params_)
```

Out:

Best params:

{'classifier__C': 0.1, 'preprocessor__num__imputer__strategy': 'mean'}

The internal cross-validation scores obtained by those parameters is:
print(f"Internal CV score: {grid_search.best_score_:3f}\")

Out:

```
Internal CV score: 0.784
```

We can also introspect the top grid search results as a pandas dataframe:

```
import pandas as pd

cv_results = pd.DataFrame(grid_search.cv_results_)
cv_results = cv_results.sort_values("mean_test_score", ascending=False)
cv_results["mean_test_score", "std_test_score", "param_preprocessor__num__imputer__strategy", "param_classifier__C"].head(5)
```

The best hyper-parameters have be used to re-fit a final model on the full training set. We can evaluate that final model on held out test data that was not used for hyparameter tuning.

```
print("best logistic regression from grid search: \%.3f\" % grid_search.score(X_test, y_test))
```

Out:

```
best logistic regression from grid search: 0.794
```

Total running time of the script: ( 0 minutes 1.964 seconds)

### 6.26.5 Column Transformer with Heterogeneous Data Sources

Datasets can often contain components that require different feature extraction and processing pipelines. This scenario might occur when:

1. your dataset consists of heterogeneous data types (e.g. raster images and text captions),
2. your dataset is stored in a `pandas.DataFrame` and different columns require different processing pipelines.

This example demonstrates how to use `ColumnTransformer` on a dataset containing different types of features. The choice of features is not particularly helpful, but serves to illustrate the technique.

```python
# Author: Matt Terry <matt.terry@gmail.com>
#
# License: BSD 3 clause

import numpy as np

from sklearn.preprocessing import FunctionTransformer
from sklearn.datasets import fetch_20newsgroups
from sklearn.decomposition import TruncatedSVD
from sklearn.feature_extraction import DictVectorizer
from sklearn.feature_extraction.text import TfidfVectorizer
from sklearn.metrics import classification_report
from sklearn.pipeline import Pipeline
from sklearn.compose import ColumnTransformer
from sklearn.svm import LinearSVC
```
20 newsgroups dataset

We will use the 20 newsgroups dataset, which comprises posts from newsgroups on 20 topics. This dataset is split into train and test subsets based on messages posted before and after a specific date. We will only use posts from 2 categories to speed up running time.

```python
categories = ['sci.med', 'sci.space']
X_train, y_train = fetch_20newsgroups(random_state=1,
                                      subset='train',
                                      categories=categories,
                                      remove=('footers', 'quotes'),
                                      return_X_y=True)
X_test, y_test = fetch_20newsgroups(random_state=1,
                                      subset='test',
                                      categories=categories,
                                      remove=('footers', 'quotes'),
                                      return_X_y=True)
```

Each feature comprises meta information about that post, such as the subject, and the body of the news post.

```python
print(X_train[0])
```

Out:

From: mccall@mksol.dseg.ti.com (fred j mccall 575-3539)
Subject: Re: Metric vs English
Organization: Texas Instruments Inc
Lines: 31

American, perhaps, but nothing military about it. I learned (mostly) slugs when we talked English units in high school physics and while the teacher was an ex-Navy fighter jock the book certainly wasn't produced by the military.

[Poundals were just too flinking small and made the math come out funny; sort of the same reason proponents of SI give for using that.]

```
"Insisting on perfect safety is for people who don't have the balls to live in the real world."  -- Mary Shafer, NASA Ames Dryden
```

Creating transformers

First, we would like a transformer that extracts the subject and body of each post. Since this is a stateless transformation (does not require state information from training data), we can define a function that performs the data transformation then use `FunctionTransformer` to create a scikit-learn transformer.

```python
def subject_body_extractor(posts):
    # construct object dtype array with two columns
    # first column = 'subject' and second column = 'body'
    features = np.empty(shape=(len(posts), 2), dtype=object)
    for i, text in enumerate(posts):
```

(continues on next page)
# temporary variable `_` stores `'\n\n'`
headers, _, body = text.partition('\n\n')
# store body text in second column
features[i, 1] = body

prefix = 'Subject:'
sub = ''
# save text after 'Subject:' in first column
for line in headers.split('\n
'):
    if line.startswith(prefix):
        sub = line[len(prefix):]
        break
features[i, 0] = sub

return features

subject_body_transformer = FunctionTransformer(subject_body_extractor)

We will also create a transformer that extracts the length of the text and the number of sentences.

def text_stats(posts):
    return [{'length': len(text),
             'num_sentences': text.count('.')}
            for text in posts]

text_stats_transformer = FunctionTransformer(text_stats)

Classification pipeline

The pipeline below extracts the subject and body from each post using SubjectBodyExtractor, producing a (n_samples, 2) array. This array is then used to compute standard bag-of-words features for the subject and body as well as text length and number of sentences on the body, using ColumnTransformer. We combine them, with weights, then train a classifier on the combined set of features.

pipeline = Pipeline(
    # Extract subject & body
    ('subjectbody', subject_body_transformer),
    # Use ColumnTransformer to combine the subject and body features
    ('union', ColumnTransformer(
        [
            # bag-of-words for subject (col 0)
            ('subject', TfidfVectorizer(min_df=50), 0),
            # bag-of-words with decomposition for body (col 1)
            ('body_bow', Pipeline(
                [('tfidf', TfidfVectorizer()),
                 ('best', TruncatedSVD(n_components=50)),
            ], 1),
            # Pipeline for pulling text stats from post's body
            ('body_stats', Pipeline(
                [('stats', text_stats_transformer), # returns a list of dicts
                 ('vect', DictVectorizer()), # list of dicts -> feature matrix
            ], 1),
        ],
    )
)
# weight above ColumnTransformer features
transformer_weights={
    'subject': 0.8,
    'body_bow': 0.5,
    'body_stats': 1.0,
}

# Use a SVC classifier on the combined features
('svc', LinearSVC(dual=False)),
], verbose=True)

Finally, we fit our pipeline on the training data and use it to predict topics for \( X_{test} \). Performance metrics of our pipeline are then printed.

```
pipeline.fit(X_train, y_train)
y_pred = pipeline.predict(X_test)
print('Classification report:

    {}'.format(classification_report(y_test, y_pred)))
```

Out:

```
[Pipeline] ....... (step 1 of 3) Processing subjectbody, total= 0.0s
[Pipeline] ............. (step 2 of 3) Processing union, total= 0.4s
[Pipeline] ............... (step 3 of 3) Processing svc, total= 0.0s
Classification report:

    precision   recall   f1-score   support
    0.84        0.87      0.86        396
    0.87        0.83      0.85        394

    accuracy                           0.85        790
    macro avg  0.85      0.85      0.85        790
    weighted avg  0.85      0.85      0.85        790
```

Total running time of the script: ( 0 minutes 2.529 seconds)

## 6.26.6 Effect of transforming the targets in regression model

In this example, we give an overview of `TransformedTargetRegressor`. We use two examples to illustrate the benefit of transforming the targets before learning a linear regression model. The first example uses synthetic data while the second example is based on the Ames housing data set.

```
# Author: Guillaume Lemaitre <guillaume.lemaitre@inria.fr>
# License: BSD 3 clause

import numpy as np
import matplotlib
import matplotlib.pyplot as plt
from sklearn.datasets import make_regression
from sklearn.model_selection import train_test_split
from sklearn.linear_model import RidgeCV
from sklearn.compose import TransformedTargetRegressor

import numpy as np
import matplotlib
import matplotlib.pyplot as plt
from sklearn.datasets import make_regression
from sklearn.model_selection import train_test_split
from sklearn.linear_model import RidgeCV
from sklearn.compose import TransformedTargetRegressor
```

(continues on next page)
Synthetic example

```python
from sklearn.metrics import median_absolute_error, r2_score
from sklearn.utils.fixes import parse_version

# `normed` is being deprecated in favor of `density` in histograms
if parse_version(matplotlib.__version__) >= parse_version('2.1'):
    density_param = {'density': True}
else:
    density_param = {'normed': True}

A synthetic random regression dataset is generated. The targets y are modified by:

1. translating all targets such that all entries are non-negative (by adding the absolute value of the lowest y) and
2. applying an exponential function to obtain non-linear targets which cannot be fitted using a simple linear model.

Therefore, a logarithmic (np.log1p) and an exponential function (np.expm1) will be used to transform the targets before training a linear regression model and using it for prediction.

```python
X, y = make_regression(n_samples=10000, noise=100, random_state=0)
y = np.expm1((y + abs(y.min())) / 200)
y_trans = np.log1p(y)
```

Below we plot the probability density functions of the target before and after applying the logarithmic functions.

```python
f, (ax0, ax1) = plt.subplots(1, 2)
ax0.hist(y, bins=100, **density_param)
ax0.set_xlim([0, 2000])
ax0.set_ylabel('Probability')
ax0.set_xlabel('Target')
ax0.set_title('Target distribution')

ax1.hist(y_trans, bins=100, **density_param)
ax1.set_ylabel('Probability')
ax1.set_xlabel('Target')
ax1.set_title('Transformed target distribution')

f.suptitle("Synthetic data", y=0.06, x=0.53)
f.tight_layout(rect=[0.05, 0.05, 0.95, 0.95])
```

X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
At first, a linear model will be applied on the original targets. Due to the non-linearity, the model trained will not be precise during prediction. Subsequently, a logarithmic function is used to linearize the targets, allowing better prediction even with a similar linear model as reported by the median absolute error (MAE).

```python
f, (ax0, ax1) = plt.subplots(1, 2, sharey=True)
# Use linear model
regr = RidgeCV()
regr.fit(X_train, y_train)
y_pred = regr.predict(X_test)
# Plot results
ax0.scatter(y_test, y_pred)
ax0.plot([0, 2000], [0, 2000], '--k')
ax0.set_ylabel('Target predicted')
ax0.set_xlabel('True Target')
ax0.set_title('Ridge regression without target transformation')
ax0.text(100, 1750, r'$R^2$=%.2f, MAE=%.2f' % (r2_score(y_test, y_pred), median_absolute_error(y_test, y_pred)))
ax0.set_xlim([0, 2000])
ax0.set_ylim([0, 2000])
# Transform targets and use same linear model
regr_trans = TransformedTargetRegressor(regressor=RidgeCV(), func=np.log1p, inverse_func=np.expm1)
regr_trans.fit(X_train, y_train)
y_pred = regr_trans.predict(X_test)
```

(continues on next page)
Real-world data set

In a similar manner, the Ames housing data set is used to show the impact of transforming the targets before learning a model. In this example, the target to be predicted is the selling price of each house.

```python
from sklearn.datasets import fetch_openml
from sklearn.preprocessing import QuantileTransformer, quantile_transform

ames = fetch_openml(name="house_prices", as_frame=True)
# Keep only numeric columns
```
A `QuantileTransformer` is used to normalize the target distribution before applying a `RidgeCV` model.

```python
f, (ax0, ax1) = plt.subplots(1, 2)

ax0.hist(y, bins=100, **density_param)
ax0.set_ylabel('Probability')
ax0.set_xlabel('Target')
ax0.text(s='Target distribution', x=1.2e5, y=9.8e-6, fontsize=12)
ax0.ticklabel_format(axis='both', style='sci', scilimits=(0, 0))

ax1.hist(y_trans, bins=100, **density_param)
ax1.set_ylabel('Probability')
ax1.set_xlabel('Target')
ax1.text(s='Transformed target distribution', x=-6.8, y=0.479, fontsize=12)

f.suptitle("Ames housing data: selling price", y=0.04)
f.tight_layout(rect=[0.05, 0.05, 0.95, 0.95])
```

```python
X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=1)
```
The effect of the transformer is weaker than on the synthetic data. However, the transformation results in an increase in $R^2$ and a large decrease of the MAE. The residual plot (predicted target - true target vs predicted target) without target transformation takes on a curved, ‘reverse smile’ shape due to residual values that vary depending on the value of predicted target. With target transformation, the shape is more linear indicating better model fit.

```python
f, (ax0, ax1) = plt.subplots(2, 2, sharey='row', figsize=(6.5, 8))
regr = RidgeCV()
regr.fit(X_train, y_train)
y_pred = regr.predict(X_test)
ax0[0].scatter(y_pred, y_test, s=8)
ax0[0].plot([0, 7e5], [0, 7e5], '--k')
ax0[0].set_ylabel('True target')
ax0[0].set_xlabel('Predicted target')
ax0[0].text(s='Ridge regression
without target transformation', x=-5e4, y=8e5, fontsize=12, multialignment='center')
ax0[0].text(3e4, 64e4, r'$R^2$= %.2f, MAE= %.2f' % (r2_score(y_test, y_pred), median_absolute_error(y_test, y_pred)))
ax0[0].set_xlim([0, 7e5])
ax0[0].set_ylim([0, 7e5])
ax0[0].ticklabel_format(axis="both", style="sci", scilimits=(0, 0))
ax0[0].scatter(y_pred, (y_pred - y_test), s=8)
ax0[0].set_ylabel('Residual')
```

Ames housing data: selling price
```python
ax1[0].set_xlabel('Predicted target')
ax1[0].ticklabel_format(axis="both", style="sci", scilimits=(0, 0))

regr_trans = TransformedTargetRegressor(
    regressor=RidgeCV(),
    transformer=QuantileTransformer(n_quantiles=900,
        output_distribution='normal'))
regr_trans.fit(X_train, y_train)
y_pred = regr_trans.predict(X_test)

ax0[1].scatter(y_pred, y_test, s=8)
ax0[1].plot([0, 7e5], [0, 7e5], '--k')
ax0[1].set_ylabel('True target')
ax0[1].set_xlabel('Predicted target')
ax0[1].text(s='Ridge regression
with target transformation',
            x=-5e4,
            y=8e5,
            fontsize=12, multialignment='center')
ax0[1].text(3e4, 64e4, r'$R^2$=%.2f, MAE=%.2f' % (r2_score(y_test, y_pred),
                                       median_absolute_error(y_test, y_pred)))
ax0[1].set_xlim([0, 7e5])
ax0[1].set_ylim([0, 7e5])
ax0[1].ticklabel_format(axis="both", style="sci", scilimits=(0, 0))

ax1[1].scatter(y_pred, (y_pred - y_test), s=8)
ax1[1].set_ylabel('Residual')
ax1[1].set_xlabel('Predicted target')
ax1[1].ticklabel_format(axis="both", style="sci", scilimits=(0, 0))

f.suptitle("Ames housing data: selling price", y=0.035)
plt.show()
```
6.27 Preprocessing

Examples concerning the `sklearn.preprocessing` module.

### 6.27.1 Using KBinsDiscretizer to discretize continuous features

The example compares prediction result of linear regression (linear model) and decision tree (tree based model) with and without discretization of real-valued features.

As is shown in the result before discretization, linear model is fast to build and relatively straightforward to interpret, but can only model linear relationships, while decision tree can build a much more complex model of the data. One way to make linear model more powerful on continuous data is to use discretization (also known as binning). In the example, we discretize the feature and one-hot encode the transformed data. Note that if the bins are not reasonably wide, there would appear to be a substantially increased risk of overfitting, so the discretizer parameters should usually be tuned under cross validation.

After discretization, linear regression and decision tree make exactly the same prediction. As features are constant within each bin, any model must predict the same value for all points within a bin. Compared with the result before discretization, linear model become much more flexible while decision tree gets much less flexible. Note that binning features generally has no beneficial effect for tree-based models, as these models can learn to split up the data anywhere.

```python
# Author: Andreas Müller
# Hanmin Qin <qinhanmin2005@sina.com>
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt

from sklearn.linear_model import LinearRegression
from sklearn.preprocessing import KBinsDiscretizer
from sklearn.tree import DecisionTreeRegressor

print(__doc__)

# construct the dataset
rnd = np.random.RandomState(42)
X = rnd.uniform(-3, 3, size=100)

# (continues on next page)
```
```python
y = np.sin(X) + rnd.normal(size=len(X)) / 3
X = X.reshape(-1, 1)

# transform the dataset with KBinsDiscretizer
enc = KBinsDiscretizer(n_bins=10, encode='onehot')
X_binned = enc.fit_transform(X)

# predict with original dataset
fig, (ax1, ax2) = plt.subplots(nrows=2, sharey=True, figsize=(10, 4))
line = np.linspace(-3, 3, 1000, endpoint=False).reshape(-1, 1)
reg = LinearRegression().fit(X, y)
ax1.plot(line, reg.predict(line), linewidth=2, color='green',
         label="linear regression")
reg = DecisionTreeRegressor(min_samples_split=3, random_state=0).fit(X, y)
ax1.plot(line, reg.predict(line), linewidth=2, color='red',
         linestyle=':', label='decision tree')
ax1.plot(X[:, 0], y, 'o', c='k')
ax1.legend(loc="best")
ax1.set_ylabel("Regression output")
ax1.set_xlabel("Input feature")
ax1.set_title("Result before discretization")

# predict with transformed dataset
line_binned = enc.transform(line)
reg = LinearRegression().fit(X_binned, y)
ax2.plot(line, reg.predict(line_binned), linewidth=2, color='green',
         linestyle='-', label='linear regression')
reg = DecisionTreeRegressor(min_samples_split=3, random_state=0).fit(X_binned, y)
ax2.plot(line, reg.predict(line_binned), linewidth=2, color='red',
         linestyle=':', label='decision tree')
ax2.plot(X[:, 0], y, 'o', c='k')
ax2.vlines(enc.bin_edges_[0], *plt.gca().get_ylim(), linewidth=1, alpha=.2)
ax2.legend(loc="best")
ax2.set_xlabel("Input feature")
ax2.set_title("Result after discretization")

plt.tight_layout()
plt.show()
```

Total running time of the script: ( 0 minutes 0.178 seconds)

### 6.27.2 Demonstrating the different strategies of KBinsDiscretizer

This example presents the different strategies implemented in KBinsDiscretizer:

- `'uniform'`: The discretization is uniform in each feature, which means that the bin widths are constant in each dimension.
- `'quantile'`: The discretization is done on the quantiled values, which means that each bin has approximately the same number of samples.
- `'kmeans'`: The discretization is based on the centroids of a KMeans clustering procedure.

The plot shows the regions where the discretized encoding is constant.
# Author: Tom Dupré la Tour

# License: BSD 3 clause

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.preprocessing import KBinsDiscretizer
from sklearn.datasets import make_blobs

print(__doc__)

strategies = ['uniform', 'quantile', 'kmeans']

n_samples = 200
centers_0 = np.array([[0, 0], [0, 5], [2, 4], [8, 8]])
centers_1 = np.array([[0, 0], [3, 1]])

# construct the datasets
random_state = 42
X_list = [
    np.random.RandomState(random_state).uniform(-3, 3, size=(n_samples, 2)),
    make_blobs(n_samples=[n_samples // 10, n_samples * 4 // 10, n_samples // 10, n_samples * 4 // 10],
               cluster_std=0.5, centers=centers_0, random_state=random_state)[0],
    make_blobs(n_samples=[n_samples // 5, n_samples * 4 // 5],
               cluster_std=0.5, centers=centers_1, random_state=random_state)[0],
]
```

(continues on next page)
```python
figure = plt.figure(figsize=(14, 9))
i = 1
for ds_cnt, X in enumerate(X_list):
    ax = plt.subplot(len(X_list), len(strategies) + 1, i)
    ax.scatter(X[:, 0], X[:, 1], edgecolors='k')
    if ds_cnt == 0:
        ax.set_title("Input data", size=14)
    xx, yy = np.meshgrid(
        np.linspace(X[:, 0].min(), X[:, 0].max(), 300),
        np.linspace(X[:, 1].min(), X[:, 1].max(), 300))
    grid = np.c_[xx.ravel(), yy.ravel()]
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xticks(())
    ax.set_yticks(())
    i += 1

# transform the dataset with KBinsDiscretizer
for strategy in strategies:
    enc = KBinsDiscretizer(n_bins=4, encode='ordinal', strategy=strategy)
    enc.fit(X)
    grid_encoded = enc.transform(grid)
    ax = plt.subplot(len(X_list), len(strategies) + 1, i)

    # horizontal stripes
    horizontal = grid_encoded[:, 0].reshape(xx.shape)
    ax.contourf(xx, yy, horizontal, alpha=.5)
    # vertical stripes
    vertical = grid_encoded[:, 1].reshape(xx.shape)
    ax.contourf(xx, yy, vertical, alpha=.5)
    ax.scatter(X[:, 0], X[:, 1], edgecolors='k')
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xticks(())
    ax.set_yticks(())
    if ds_cnt == 0:
        ax.set_title("strategy='" + strategy + "'", size=14)
    i += 1

plt.tight_layout()
plt.show()
```

**Total running time of the script:** (0 minutes 0.710 seconds)
6.27.3 Importance of Feature Scaling

Feature scaling through standardization (or Z-score normalization) can be an important preprocessing step for many machine learning algorithms. Standardization involves rescaling the features such that they have the properties of a standard normal distribution with a mean of zero and a standard deviation of one.

While many algorithms (such as SVM, K-nearest neighbors, and logistic regression) require features to be normalized, intuitively we can think of Principle Component Analysis (PCA) as being a prime example of when normalization is important. In PCA we are interested in the components that maximize the variance. If one component (e.g., human height) varies less than another (e.g., weight) because of their respective scales (meters vs. kilos), PCA might determine that the direction of maximal variance more closely corresponds with the ‘weight’ axis, if those features are not scaled. As a change in height of one meter can be considered much more important than the change in weight of one kilogram, this is clearly incorrect.

To illustrate this, PCA is performed comparing the use of data with StandardScaler applied, to unscaled data. The results are visualized and a clear difference noted. The 1st principal component in the unscaled set can be seen. It can be seen that feature #13 dominates the direction, being a whole two orders of magnitude above the other features. This is contrasted when observing the principal component for the scaled version of the data. In the scaled version, the orders of magnitude are roughly the same across all the features.

The dataset used is the Wine Dataset available at UCI. This dataset has continuous features that are heterogeneous in scale due to differing properties that they measure (i.e., alcohol content, and malic acid).

The transformed data is then used to train a naive Bayes classifier, and a clear difference in prediction accuracies is observed wherein the dataset which is scaled before PCA vastly outperforms the unscaled version.
Prediction accuracy for the normal test dataset with PCA
81.48%

Prediction accuracy for the standardized test dataset with PCA
98.15%

PC 1 without scaling:
\[
\begin{bmatrix}
1.76e-03 & -8.36e-04 & 1.55e-04 & 2.02e-02 & 1.02e-03 & 1.53e-03 \\
-1.12e-04 & 6.31e-04 & 2.33e-03 & 1.54e-04 & 7.43e-04 & 1.00e+00
\end{bmatrix}
\]

PC 1 with scaling:
\[
\begin{bmatrix}
0.13 & -0.26 & -0.01 & -0.23 & 0.16 & 0.39 & 0.42 & -0.28 & 0.33 & -0.11 & 0.3 & 0.38 \\
0.28
\end{bmatrix}
\]

from sklearn.model_selection import train_test_split
from sklearn.preprocessing import StandardScaler
from sklearn.decomposition import PCA
from sklearn.naive_bayes import GaussianNB
from sklearn import metrics
import matplotlib.pyplot as plt
from sklearn.datasets import load_wine
from sklearn.pipeline import make_pipeline

# Code source: Tyler Lanigan <tylerlanigan@gmail.com>
# Sebastian Raschka <mail@sebastianraschka.com>
# License: BSD 3 clause
RANDOM_STATE = 42
FIG_SIZE = (10, 7)

features, target = load_wine(return_X_y=True)

# Make a train/test split using 30% test size
X_train, X_test, y_train, y_test = train_test_split(features, target, test_size=0.30, random_state=RANDOM_STATE)

# Fit to data and predict using pipelined GNB and PCA.
unscaled_clf = make_pipeline(PCA(n_components=2), GaussianNB())
unscaled_clf.fit(X_train, y_train)
pred_test = unscaled_clf.predict(X_test)

# Fit to data and predict using pipelined scaling, GNB and PCA.
std_clf = make_pipeline(StandardScaler(), PCA(n_components=2), GaussianNB())
std_clf.fit(X_train, y_train)
pred_test_std = std_clf.predict(X_test)
# Show prediction accuracies in scaled and unscaled data.
print('Prediction accuracy for the normal test dataset with PCA')
print('{:.2%}'.format(metrics.accuracy_score(y_test, pred_test)))

print('Prediction accuracy for the standardized test dataset with PCA')
print('{:.2%}'.format(metrics.accuracy_score(y_test, pred_test_std)))

# Extract PCA from pipeline
pca = unscaled_clf.named_steps['pca']
pca_std = std_clf.named_steps['pca']

# Show first principal components
print('PC 1 without scaling:
', pca.components_[0])
print('PC 1 with scaling:
', pca_std.components_[0])

# Use PCA without and with scale on X_train data for visualization.
X_train_transformed = pca.transform(X_train)
scaler = std_clf.named_steps['standardscaler']
X_train_std_transformed = pca_std.transform(scaler.transform(X_train))

# visualize standardized vs. untouched dataset with PCA performed
fig, (ax1, ax2) = plt.subplots(ncols=2, figsize=FIG_SIZE)
for l, c, m in zip(range(0, 3), ('blue', 'red', 'green'), ('^', 's', 'o')):
    ax1.scatter(X_train_transformed[y_train == l, 0],
                X_train_transformed[y_train == l, 1],
                color=c,
                label='class %s % 1,
                alpha=0.5,
                marker=m
            )
for l, c, m in zip(range(0, 3), ('blue', 'red', 'green'), ('^', 's', 'o')):
    ax2.scatter(X_train_std_transformed[y_train == l, 0],
                X_train_std_transformed[y_train == l, 1],
                color=c,
                label='class %s % 1,
                alpha=0.5,
                marker=m
            )
ax1.set_title('Training dataset after PCA')
ax2.set_title('Standardized training dataset after PCA')

for ax in (ax1, ax2):
    ax.set_xlabel('1st principal component')
    ax.set_ylabel('2nd principal component')
    ax.legend(loc='upper right')
    ax.grid()

plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 0.224 seconds)
6.27.4 Map data to a normal distribution

This example demonstrates the use of the Box-Cox and Yeo-Johnson transforms through `PowerTransformer` to map data from various distributions to a normal distribution.

The power transform is useful as a transformation in modeling problems where homoscedasticity and normality are desired. Below are examples of Box-Cox and Yeo-Johnson applied to six different probability distributions: Lognormal, Chi-squared, Weibull, Gaussian, Uniform, and Bimodal.

Note that the transformations successfully map the data to a normal distribution when applied to certain datasets, but are ineffective with others. This highlights the importance of visualizing the data before and after transformation.

Also note that even though Box-Cox seems to perform better than Yeo-Johnson for lognormal and chi-squared distributions, keep in mind that Box-Cox does not support inputs with negative values.

For comparison, we also add the output from `QuantileTransformer`. It can force any arbitrary distribution into a gaussian, provided that there are enough training samples (thousands). Because it is a non-parametric method, it is harder to interpret than the parametric ones (Box-Cox and Yeo-Johnson).

On “small” datasets (less than a few hundred points), the quantile transformer is prone to overfitting. The use of the power transform is then recommended.
# Author: Eric Chang <ericchang2017@u.northwestern.edu>
# Nicolas Hug <contact@nicolas-hug.com>
# License: BSD 3 clause

(continues on next page)
import numpy as np
import matplotlib.pyplot as plt
from sklearn.preprocessing import PowerTransformer
from sklearn.preprocessing import QuantileTransformer
from sklearn.model_selection import train_test_split
print(__doc__)

N_SAMPLES = 1000
FONT_SIZE = 6
BINS = 30
rng = np.random.RandomState(304)
bc = PowerTransformer(method='box-cox')
yj = PowerTransformer(method='yeo-johnson')
# n_quantiles is set to the training set size rather than the default value
# to avoid a warning being raised by this example
qt = QuantileTransformer(n_quantiles=500, output_distribution='normal',
                          random_state=rng)
size = (N_SAMPLES, 1)

# lognormal distribution
X_lognormal = rng.lognormal(size=size)

# chi-squared distribution
df = 3
X_chisq = rng.chisquare(df=df, size=size)

# weibull distribution
a = 50
X_weibull = rng.weibull(a=a, size=size)

# gaussian distribution
loc = 100
X_gaussian = rng.normal(loc=loc, size=size)

# uniform distribution
X_uniform = rng.uniform(low=0, high=1, size=size)

# bimodal distribution
loc_a, loc_b = 100, 105
X_a, X_b = rng.normal(loc=loc_a, size=size), rng.normal(loc=loc_b, size=size)
X_bimodal = np.concatenate([X_a, X_b], axis=0)

# create plots
distributions = [
    ('Lognormal', X_lognormal),
    ('Chi-squared', X_chisq),
    ('Weibull', X_weibull),
    ('Gaussian', X_gaussian),
    ('Uniform', X_uniform),
    ('Bimodal', X_bimodal)
colors = ['#D81B60', '#0188FF', '#FFC107', '#B7A2FF', '#000000', '#2EC5AC']
fig, axes = plt.subplots(nrows=8, ncols=3, figsize=plt.figaspect(2))
axes = axes.flatten()
axes_idxs = [(0, 3, 6, 9), (1, 4, 7, 10), (2, 5, 8, 11), (12, 15, 18, 21),
            (13, 16, 19, 22), (14, 17, 20, 23)]
axes_list = [(axes[i], axes[j], axes[k], axes[l])
             for (i, j, k, l) in axes_idxs]

for distribution, color, axes in zip(distributions, colors, axes_list):
    name, X = distribution
    X_train, X_test = train_test_split(X, test_size=.5)
    # perform power transforms and quantile transform
    X_trans_bc = bc.fit(X_train).transform(X_test)
    lmbda_bc = round(bc.lambdas_[0], 2)
    X_trans_yj = yj.fit(X_train).transform(X_test)
    lmbda_yj = round(yj.lambdas_[0], 2)
    X_trans_qt = qt.fit(X_train).transform(X_test)

    ax_original, ax_bc, ax_yj, ax_qt = axes
    ax_original.hist(X_train, color=color, bins=BINS)
    ax_original.set_title(name, fontsize=FONT_SIZE)
    ax_original.tick_params(axis='both', which='major', labelsize=FONT_SIZE)

    for ax, X_trans, meth_name, lmbda in zip(
       (ax_bc, ax_yj, ax_qt),
       (X_trans_bc, X_trans_yj, X_trans_qt),
       ('Box-Cox', 'Yeo-Johnson', 'Quantile transform'),
       (lmbda_bc, lmbda_yj, None)):
        ax.hist(X_trans, color=color, bins=BINS)
        title = 'After ' + meth_name
        if lmbda is not None:
            title += r'\n\n$
\lambda$ = {}
'.format(lmbda)
        ax.set_title(title, fontsize=FONT_SIZE)
        ax.tick_params(axis='both', which='major', labelsize=FONT_SIZE)
        ax.set_xlim([-3.5, 3.5])

plt.tight_layout()
plt.show()
6.27.5 Feature discretization

A demonstration of feature discretization on synthetic classification datasets. Feature discretization decomposes each feature into a set of bins, here equally distributed in width. The discrete values are then one-hot encoded, and given to a linear classifier. This preprocessing enables a non-linear behavior even though the classifier is linear.

On this example, the first two rows represent linearly non-separable datasets (moons and concentric circles) while the third is approximately linearly separable. On the two linearly non-separable datasets, feature discretization largely increases the performance of linear classifiers. On the linearly separable dataset, feature discretization decreases the performance of linear classifiers. Two non-linear classifiers are also shown for comparison.

This example should be taken with a grain of salt, as the intuition conveyed does not necessarily carry over to real datasets. Particularly in high-dimensional spaces, data can more easily be separated linearly. Moreover, using feature discretization and one-hot encoding increases the number of features, which easily lead to overfitting when the number of samples is small.

The plots show training points in solid colors and testing points semi-transparent. The lower right shows the classification accuracy on the test set.

Out:

dataset 0
---------
LogisticRegression: 0.86
LinearSVC: 0.86
KBinsDiscretizer + LogisticRegression: 0.86
KBinsDiscretizer + LinearSVC: 0.92
GradientBoostingClassifier: 0.90
SVC: 0.94

dataset 1
---------
LogisticRegression: 0.40
LinearSVC: 0.40
KBinsDiscretizer + LogisticRegression: 0.88
KBinsDiscretizer + LinearSVC: 0.86
GradientBoostingClassifier: 0.80
SVC: 0.84

(continues on next page)
dataset 2
---------
LogisticRegression: 0.98
LinearSVC: 0.98
KBinsDiscretizer + LogisticRegression: 0.94
KBinsDiscretizer + LinearSVC: 0.94
GradientBoostingClassifier: 0.88
SVC: 0.98

# Code source: Tom Dupré la Tour
# Adapted from plot_classifier_comparison by Gaël Varoquaux and Andreas Müller
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from matplotlib.colors import ListedColormap
from sklearn.model_selection import train_test_split,
from sklearn.preprocessing import StandardScaler,
from sklearn.datasets import make_moons, make_circles, make_classification,
from sklearn.linear_model import LogisticRegression,
from sklearn.preprocessing import KBinsDiscretizer,
from sklearn.model_selection import GridSearchCV,
from sklearn.pipeline import make_pipeline,
from sklearn.svm import SVC, LinearSVC,
from sklearn.ensemble import GradientBoostingClassifier,
from sklearn.exceptions import ConvergenceWarning
print(__doc__)

h = .02 # step size in the mesh

def get_name(estimator):
    name = estimator.__class__.__name__
    if name == 'Pipeline':
        name = [get_name(est[1]) for est in estimator.steps]
    name = '+'+'.join(name)
    return name

# list of (estimator, param_grid), where param_grid is used in GridSearchCV
classifiers = [
    (LogisticRegression(random_state=0), {
        'C': np.logspace(-2, 7, 10)
    }),
    (LinearSVC(random_state=0), {
        'C': np.logspace(-2, 7, 10)
    }),
    (make_pipeline(}
KBinsDiscretizer(encode='onehot'),
LogisticRegression(random_state=0)), {
    'kbinsdiscretizer__n_bins': np.arange(2, 10),
    'logisticregression__C': np.logspace(-2, 7, 10),
},
(make_pipeline(
    KBinsDiscretizer(encode='onehot'), LinearSVC(random_state=0)), {
    'kbinsdiscretizer__n_bins': np.arange(2, 10),
    'linearsvc__C': np.logspace(-2, 7, 10),
}),
(GradientBoostingClassifier(n_estimators=50, random_state=0), {
    'learning_rate': np.logspace(-4, 0, 10)
}),
(SVC(random_state=0), {
    'C': np.logspace(-2, 7, 10)
}),
]
names = [get_name(e) for e, g in classifiers]
n_samples = 100
datasets = [
    make_moons(n_samples=n_samples, noise=0.2, random_state=0),
    make_circles(n_samples=n_samples, noise=0.2, factor=0.5, random_state=1),
    make_classification(n_samples=n_samples, n_features=2, n_redundant=0, 
                        n_informative=2, n_clusters_per_class=1)
]
fig, axes = plt.subplots(nrows=len(datasets), ncols=len(classifiers) + 1, 
                        figsize=(21, 9))
cm = plt.cm.PiYG
cm_bright = ListedColormap(['#b30065', '#178000'])

# iterate over datasets
for ds_cnt, (X, y) in enumerate(datasets):
    print('dataset %d
---------' % ds_cnt)
    # preprocess dataset, split into training and test part
    X = StandardScaler().fit_transform(X)
    X_train, X_test, y_train, y_test = train_test_split( 
        X, y, test_size=.5, random_state=42)
    
    # create the grid for background colors
    x_min, x_max = X[:, 0].min() - .5, X[:, 0].max() + .5
    y_min, y_max = X[:, 1].min() - .5, X[:, 1].max() + .5
    xx, yy = np.meshgrid( 
        np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))
    
    # plot the dataset first
    ax = axes[ds_cnt, 0]
    if ds_cnt == 0:
        ax.set_title("Input data")
    
    # plot the training points
    ax.scatter(X_train[:, 0], X_train[:, 1], c=y_train, cmap=cm_bright,
               edgecolors='k')
# and testing points
ax.scatter(X_test[:, 0], X_test[:, 1], c=y_test, cmap=cm_bright, alpha=0.6,
edgecolors='k')
ax.set_xlim(xx.min(), xx.max())
ax.set_ylim(yy.min(), yy.max())
ax.set_xticks(())
ax.set_yticks(())

# iterate over classifiers
for est_idx, (name, (estimator, param_grid)) in enumerate(zip(names, classifiers)):
    ax = axes[ds_cnt, est_idx + 1]
    clf = GridSearchCV(estimator=estimator, param_grid=param_grid)
    with ignore_warnings(category=ConvergenceWarning):
        clf.fit(X_train, y_train)
        score = clf.score(X_test, y_test)
        print('%s: %.2f' % (name, score))

    # plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]*[y_min, y_max].
    if hasattr(clf, "decision_function"):
        Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
    else:
        Z = clf.predict_proba(np.c_[xx.ravel(), yy.ravel()])[:, 1]

    # put the result into a color plot
    Z = Z.reshape(xx.shape)
    ax.contourf(xx, yy, Z, cmap=cm, alpha=.8)

    # plot the training points
    ax.scatter(X_train[:, 0], X_train[:, 1], c=y_train, cmap=cm_bright,
               edgecolors='k')
    # and testing points
    ax.scatter(X_test[:, 0], X_test[:, 1], c=y_test, cmap=cm_bright,
               edgecolors='k', alpha=0.6)
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xticks(())
    ax.set_yticks(())
    if ds_cnt == 0:
        ax.set_title(name.replace(' + ', '
'))
        ax.text(0.95, 0.06, ('%.2f' % score).lstrip('0'), size=15,
               bbox=dict(boxstyle='round', alpha=0.8, facecolor='white'),
               transform=ax.transAxes, horizontalalignment='right')

plt.tight_layout()

# Add suptitles above the figure
plt.subplots_adjust(top=0.90)
suptitles = [
    'Linear classifiers',
    'Feature discretization and linear classifiers',
    'Non-linear classifiers',
]

(continues on next page)
for i, suptitle in zip([1, 3, 5], suptitles):
    ax = axes[0, i]
    ax.text(1.05, 1.25, suptitle, transform=ax.transAxes,
            horizontalalignment='center', size='x-large')
plt.show()

Total running time of the script: (0 minutes 20.908 seconds)

6.27.6 Compare the effect of different scalers on data with outliers

Feature 0 (median income in a block) and feature 5 (number of households) of the California Housing dataset have very different scales and contain some very large outliers. These two characteristics lead to difficulties to visualize the data and, more importantly, they can degrade the predictive performance of many machine learning algorithms. Unscaled data can also slow down or even prevent the convergence of many gradient-based estimators.

Indeed many estimators are designed with the assumption that each feature takes values close to zero or more importantly that all features vary on comparable scales. In particular, metric-based and gradient-based estimators often assume approximately standardized data (centered features with unit variances). A notable exception are decision tree-based estimators that are robust to arbitrary scaling of the data.

This example uses different scalers, transformers, and normalizers to bring the data within a pre-defined range.

Scalers are linear (or more precisely affine) transformers and differ from each other in the way they estimate the parameters used to shift and scale each feature.

QuantileTransformer provides non-linear transformations in which distances between marginal outliers and inliers are shrunk. PowerTransformer provides non-linear transformations in which data is mapped to a normal distribution to stabilize variance and minimize skewness.

Unlike the previous transformations, normalization refers to a per sample transformation instead of a per feature transformation.

The following code is a bit verbose, feel free to jump directly to the analysis of the results.

```python
# Author: Raghav RV <rvraghav93@gmail.com>
# Guillaume Lemaitre <g.lemaitre58@gmail.com>
# Thomas Unterthiner
# License: BSD 3 clause

import numpy as np
import matplotlib as mpl
import matplotlib.pyplot as plt
from matplotlib import cm

from sklearn.preprocessing import MinMaxScaler
from sklearn.preprocessing import minmax_scale
from sklearn.preprocessing import MaxAbsScaler
from sklearn.preprocessing import StandardScaler
from sklearn.preprocessing import RobustScaler
from sklearn.preprocessing import Normalizer
from sklearn.preprocessing import QuantileTransformer
from sklearn.preprocessing import PowerTransformer

from sklearn.datasets import fetch_california_housing

print(__doc__)
```

(continues on next page)
dataset = fetch_california_housing()
X_full, y_full = dataset.data, dataset.target

# Take only 2 features to make visualization easier
# Feature of 0 has a long tail distribution.
# Feature 5 has a few but very large outliers.
X = X_full[:, [0, 5]]

distributions = [
    ('Unscaled data', X),
    ('Data after standard scaling', StandardScaler().fit_transform(X)),
    ('Data after min-max scaling', MinMaxScaler().fit_transform(X)),
    ('Data after max-abs scaling', MaxAbsScaler().fit_transform(X)),
    ('Data after robust scaling', RobustScaler(quantile_range=(25, 75)).fit_transform(X)),
    ('Data after power transformation (Yeo-Johnson)', PowerTransformer(method='yeo-johnson').fit_transform(X)),
    ('Data after power transformation (Box-Cox)', PowerTransformer(method='box-cox').fit_transform(X)),
    ('Data after quantile transformation (uniform pdf)', QuantileTransformer(output_distribution='uniform').fit_transform(X)),
    ('Data after quantile transformation (gaussian pdf)', QuantileTransformer(output_distribution='normal').fit_transform(X)),
    ('Data after sample-wise L2 normalizing', Normalizer().fit_transform(X)),
]

# scale the output between 0 and 1 for the colorbar
y = minmax_scale(y_full)

# plasma does not exist in matplotlib < 1.5
cmap = getattr(cm, 'plasma_r', cm.hot_r)

def create_axes(title, figsize=(16, 6)):
    fig = plt.figure(figsize=figsize)
    fig.suptitle(title)
    # define the axis for the first plot
    left, width = 0.1, 0.22
    bottom, height = 0.1, 0.7
    bottom_h = height + 0.15
    left_h = left + width + 0.02
    rect_scatter = [left, bottom, width, height]
    rect_histx = [left, bottom_h, width, 0.1]
    rect_histy = [left_h, bottom, 0.05, height]
    ax_scatter = fig.axes(rect_scatter)
    ax_histx = fig.axes(rect_histx)
    ax_histy = fig.axes(rect_histy)
# define the axis for the zoomed-in plot
left = width + left + 0.2
left_h = left + width + 0.02
rect_scatter = [left, bottom, width, height]
rect_histx = [left, bottom_h, width, 0.1]
rect_histy = [left_h, bottom, 0.05, height]

ax_scatter_zoom = plt.axes(rect_scatter)
ax_histx_zoom = plt.axes(rect_histx)
ax_histy_zoom = plt.axes(rect_histy)

# define the axis for the colorbar
left, width = width + left + 0.13, 0.01
rect_colorbar = [left, bottom, width, height]
ax_colorbar = plt.axes(rect_colorbar)

return ((ax_scatter, ax_histy, ax_histx),
        (ax_scatter_zoom, ax_histy_zoom, ax_histx_zoom),
        ax_colorbar)

def plot_distribution(axes, X, y, hist_nbins=50, title='',
x0_label='', x1_label=''):
    ax, hist_X1, hist_X0 = axes
    ax.set_title(title)
    ax.set_xlabel(x0_label)
    ax.set_ylabel(x1_label)

    # The scatter plot
    colors = cmap(y)
    ax.scatter(X[:, 0], X[:, 1], alpha=0.5, marker='o', s=5, lw=0, c=colors)
    ax.spines['top'].set_visible(False)
    ax.spines['right'].set_visible(False)
    ax.get_xaxis().tick_bottom()
    ax.get_yaxis().tick_left()
    ax.spines['left'].set_position(('outward', 10))
    ax.spines['bottom'].set_position(('outward', 10))

    # Histogram for axis X1 (feature 5)
    hist_X1.set_ylim(ax.get_ylim())
    hist_X1.hist(X[:, 1], bins=hist_nbins, orientation='horizontal',
                 color='grey', ec='grey')
    hist_X1.axis('off')

    # Histogram for axis X0 (feature 0)
    hist_X0.set_xlim(ax.get_xlim())
    hist_X0.hist(X[:, 0], bins=hist_nbins, orientation='vertical',
                 color='grey', ec='grey')
    hist_X0.axis('off')
Two plots will be shown for each scaler/normalizer/transformer. The left figure will show a scatter plot of the full data set while the right figure will exclude the extreme values considering only 99% of the data set, excluding marginal outliers. In addition, the marginal distributions for each feature will be shown on the sides of the scatter plot.

```python
def make_plot(item_idx):
    title, X = distributions[item_idx]
    ax_zoom_out, ax_zoom_in, ax_colorbar = create_axes(title)
    axarr = (ax_zoom_out, ax_zoom_in)
    plot_distribution(axarr[0], X, y, hist_nbins=200,
                      x0_label="Median Income",
                      x1_label="Number of households",
                      title="Full data")

    # zoom-in
    zoom_in_percentile_range = (0, 99)
    cutoffs_X0 = np.percentile(X[:, 0], zoom_in_percentile_range)
    cutoffs_X1 = np.percentile(X[:, 1], zoom_in_percentile_range)
    non_outliers_mask = np.all(X > [cutoffs_X0[0], cutoffs_X1[0]], axis=1) &
                           np.all(X < [cutoffs_X0[1], cutoffs_X1[1]], axis=1)
    plot_distribution(axarr[1], X[non_outliers_mask], y[non_outliers_mask],
                      hist_nbins=50,
                      x0_label="Median Income",
                      x1_label="Number of households",
                      title="Zoom-in")

    norm = mpl.colors.Normalize(y_full.min(), y_full.max())
    mpl.colorbar.ColorbarBase(ax_colorbar, cmap=cmap,
                               norm=norm, orientation='vertical',
                               label='Color mapping for values of y')
```

Original data

Each transformation is plotted showing two transformed features, with the left plot showing the entire dataset, and the right zoomed-in to show the dataset without the marginal outliers. A large majority of the samples are compacted to a specific range, [0, 10] for the median income and [0, 6] for the number of households. Note that there are some marginal outliers (some blocks have more than 1200 households). Therefore, a specific pre-processing can be very beneficial depending of the application. In the following, we present some insights and behaviors of those pre-processing methods in the presence of marginal outliers.

```python
make_plot(0)
```
**StandardScaler**

*StandardScaler* removes the mean and scales the data to unit variance. The scaling shrinks the range of the feature values as shown in the left figure below. However, the outliers have an influence when computing the empirical mean and standard deviation. Note in particular that because the outliers on each feature have different magnitudes, the spread of the transformed data on each feature is very different: most of the data lie in the [-2, 4] range for the transformed median income feature while the same data is squeezed in the smaller [-0.2, 0.2] range for the transformed number of households.

*StandardScaler* therefore cannot guarantee balanced feature scales in the presence of outliers.
**MinMaxScaler**

*MinMaxScaler* rescales the data set such that all feature values are in the range [0, 1] as shown in the right panel below. However, this scaling compresses all inliers into the narrow range [0, 0.005] for the transformed number of households.

Both *StandardScaler* and *MinMaxScaler* are very sensitive to the presence of outliers.

```python
make_plot(2)
```

**MaxAbsScaler**

*MaxAbsScaler* is similar to *MinMaxScaler* except that the values are mapped in the range [0, 1]. On positive only data, both scalers behave similarly. *MaxAbsScaler* therefore also suffers from the presence of large outliers.

```python
make_plot(3)
```
RobustScaler

Unlike the previous scalers, the centering and scaling statistics of RobustScaler is based on percentiles and are therefore not influenced by a few number of very large marginal outliers. Consequently, the resulting range of the transformed feature values is larger than for the previous scalers and, more importantly, are approximately similar: for both features most of the transformed values lie in a [-2, 3] range as seen in the zoomed-in figure. Note that the outliers themselves are still present in the transformed data. If a separate outlier clipping is desirable, a non-linear transformation is required (see below).

PowerTransformer

PowerTransformer applies a power transformation to each feature to make the data more Gaussian-like in order to stabilize variance and minimize skewness. Currently the Yeo-Johnson and Box-Cox transforms are supported and the optimal scaling factor is determined via maximum likelihood estimation in both methods. By default, PowerTransformer applies zero-mean, unit variance normalization. Note that Box-Cox can only be applied to strictly positive data. Income and number of households happen to be strictly positive, but if negative values are present the Yeo-Johnson transformed is preferred.
QuantileTransformer (uniform output)

QuantileTransformer applies a non-linear transformation such that the probability density function of each feature will be mapped to a uniform or Gaussian distribution. In this case, all the data, including outliers, will be mapped to a uniform distribution with the range [0, 1], making outliers indistinguishable from inliers.

RobustScaler and QuantileTransformer are robust to outliers in the sense that adding or removing outliers in the training set will yield approximately the same transformation. But contrary to RobustScaler, QuantileTransformer will also automatically collapse any outlier by setting them to the a priori defined range boundaries (0 and 1). This can result in saturation artifacts for extreme values.

make_plot(7)
QuantileTransformer (Gaussian output)

To map to a Gaussian distribution, set the parameter `output_distribution='normal'`.

```python
make_plot(8)
```

![Data after quantile transformation (gaussian pdf)](image)

**Normalizer**

The `Normalizer` rescales the vector for each sample to have unit norm, independently of the distribution of the samples. It can be seen on both figures below where all samples are mapped onto the unit circle. In our example the two selected features have only positive values; therefore the transformed data only lie in the positive quadrant. This would not be the case if some original features had a mix of positive and negative values.

```python
make_plot(9)
plt.show()
```

![Data after sample-wise L2 normalizing](image)

**Total running time of the script:** (0 minutes 8.688 seconds)
6.28 Semi Supervised Classification

Examples concerning the `sklearn.semi_supervised` module.

6.28.1 Label Propagation learning a complex structure

Example of LabelPropagation learning a complex internal structure to demonstrate “manifold learning”. The outer circle should be labeled “red” and the inner circle “blue”. Because both label groups lie inside their own distinct shape, we can see that the labels propagate correctly around the circle.

```python
print(__doc__)

# Authors: Clay Woolam <clay@woolam.org>
# Andreas Mueller <amueller@ais.uni-bonn.de>
# License: BSD

import numpy as np
import matplotlib.pyplot as plt
from sklearn.semi_supervised import LabelSpreading
from sklearn.datasets import make_circles

# generate ring with inner box
n_samples = 200
X, y = make_circles(n_samples=n_samples, shuffle=False)
outer, inner = 0, 1
labels = np.full(n_samples, -1.)
labels[0] = outer
labels[-1] = inner

# #############################################################################
# Learn with LabelSpreading
label_spread = LabelSpreading(kernel='knn', alpha=0.8)
label_spread.fit(X, labels)

(continues on next page)```
# Plot output labels
output_labels = label_spread.transduction_
plt.figure(figsize=(8.5, 4))
plt.subplot(1, 2, 1)
plt.scatter(X[labels == outer, 0], X[labels == outer, 1], color='navy',
            marker='s', lw=0, label="outer labeled", s=10)
plt.scatter(X[labels == inner, 0], X[labels == inner, 1], color='c',
            marker='s', lw=0, label="inner labeled", s=10)
plt.scatter(X[labels == -1, 0], X[labels == -1, 1], color='darkorange',
            marker='.', label='unlabeled')
plt.legend(scatterpoints=1, shadow=False, loc='upper right')
plt.title("Raw data (2 classes=outer and inner)"
plt.subplot(1, 2, 2)
output_label_array = np.asarray(output_labels)
outer_numbers = np.where(output_label_array == outer)[0]
inner_numbers = np.where(output_label_array == inner)[0]
plt.scatter(X[outer_numbers, 0], X[outer_numbers, 1], color='navy',
            marker='s', lw=0, s=10, label="outer learned")
plt.scatter(X[inner_numbers, 0], X[inner_numbers, 1], color='c',
            marker='s', lw=0, s=10, label="inner learned")
plt.legend(scatterpoints=1, shadow=False, loc='upper right')
plt.title("Labels learned with Label Spreading (KNN)"
plt.subplots_adjust(left=0.07, bottom=0.07, right=0.93, top=0.92)
plt.show()

Total running time of the script: ( 0 minutes 0.162 seconds)

## 6.28.2 Label Propagation digits: Demonstrating performance

This example demonstrates the power of semisupervised learning by training a Label Spreading model to classify handwritten digits with sets of very few labels.

The handwritten digit dataset has 1797 total points. The model will be trained using all points, but only 30 will be labeled. Results in the form of a confusion matrix and a series of metrics over each class will be very good.

At the end, the top 10 most uncertain predictions will be shown.
Learning with small amount of labeled data

<table>
<thead>
<tr>
<th>predict: 1</th>
<th>predict: 2</th>
<th>predict: 8</th>
<th>predict: 1</th>
<th>predict: 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>true: 2</td>
<td>true: 2</td>
<td>true: 8</td>
<td>true: 8</td>
<td>true: 8</td>
</tr>
</tbody>
</table>

Out:

<table>
<thead>
<tr>
<th>predict: 1</th>
<th>predict: 3</th>
<th>predict: 8</th>
<th>predict: 2</th>
<th>predict: 7</th>
</tr>
</thead>
<tbody>
<tr>
<td>true: 8</td>
<td>true: 3</td>
<td>true: 8</td>
<td>true: 2</td>
<td>true: 2</td>
</tr>
</tbody>
</table>

Label Spreading model: 40 labeled & 300 unlabeled points (340 total)

<table>
<thead>
<tr>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1.00</td>
<td>1.00</td>
<td>27</td>
</tr>
<tr>
<td>1</td>
<td>0.82</td>
<td>1.00</td>
<td>37</td>
</tr>
<tr>
<td>2</td>
<td>1.00</td>
<td>0.86</td>
<td>35</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>0.80</td>
<td>35</td>
</tr>
<tr>
<td>4</td>
<td>0.92</td>
<td>1.00</td>
<td>24</td>
</tr>
<tr>
<td>5</td>
<td>0.74</td>
<td>0.94</td>
<td>34</td>
</tr>
<tr>
<td>6</td>
<td>0.89</td>
<td>0.96</td>
<td>25</td>
</tr>
<tr>
<td>7</td>
<td>0.94</td>
<td>0.89</td>
<td>35</td>
</tr>
<tr>
<td>8</td>
<td>1.00</td>
<td>0.68</td>
<td>31</td>
</tr>
<tr>
<td>9</td>
<td>0.81</td>
<td>0.88</td>
<td>24</td>
</tr>
</tbody>
</table>

accuracy: 0.90 300

macro avg: 0.91 0.90 0.90 300

weighted avg: 0.91 0.90 0.90 300

Confusion matrix

```
[[27 0 0 0 0 0 0 0 0 0]
 [0 37 0 0 0 0 0 0 0 0]
 [0 1 24 0 0 0 2 1 0 0]
 [0 0 0 28 0 5 0 1 0 1]
 [0 0 0 0 24 0 0 0 0 0]
 [0 0 0 0 0 32 0 0 0 2]]
```
print(__doc__)

# Authors: Clay Woolam <clay@woolam.org>
# License: BSD

import numpy as np
import matplotlib.pyplot as plt
from scipy import stats
from sklearn import datasets
from sklearn.semi_supervised import LabelSpreading
from sklearn.metrics import confusion_matrix, classification_report

digits = datasets.load_digits()
rng = np.random.RandomState(2)
indices = np.arange(len(digits.data))
rng.shuffle(indices)

X = digits.data[indices[:340]]
y = digits.target[indices[:340]]
images = digits.images[indices[:340]]

n_total_samples = len(y)
n_labeled_points = 40

indices = np.arange(n_total_samples)
unlabeled_set = indices[n_labeled_points:]

# Shuffle everything around
y_train = np.copy(y)
y_train[unlabeled_set] = -1

# Learn with LabelSpreading
lp_model = LabelSpreading(gamma=.25, max_iter=20)
lp_model.fit(X, y_train)
predicted_labels = lp_model.transduction_[unlabeled_set]
true_labels = y[unlabeled_set]

cm = confusion_matrix(true_labels, predicted_labels, labels=lp_model.classes_)

print("Label Spreading model: %d labeled & %d unlabeled points (%d total)" %
      (n_labeled_points, n_total_samples - n_labeled_points, n_total_samples))

print(cm)

# #############################################################################
# Shuffled everything around
# #############################################################################
(n_labeled_points, n_total_samples - n_labeled_points, n_total_samples))

print(classification_report(true_labels, predicted_labels))

print("Confusion matrix")
print(cm)

# ####################################################################
# Calculate uncertainty values for each transduced distribution
pred_entropies = stats.distributions.entropy(lp_model.label_distributions_.T)

# ####################################################################
# Pick the top 10 most uncertain labels
uncertainty_index = np.argsort(pred_entropies)[-10:]

# ####################################################################
# Plot
f = plt.figure(figsize=(7, 5))
for index, image_index in enumerate(uncertainty_index):
    image = images[image_index]
    sub = f.add_subplot(2, 5, index + 1)
    sub.imshow(image, cmap=plt.cm.gray_r)
    plt.xticks([])
    plt.yticks([])
    sub.set_title('predict: %i
        true: %i' % (lp_model.transduction_[image_index], y[image_index]))

f.suptitle('Learning with small amount of labeled data')
plt.show()

**Total running time of the script:** ( 0 minutes 0.256 seconds)

### 6.28.3 Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset

A comparison for the decision boundaries generated on the iris dataset by Label Spreading, Self-training and SVM. This example demonstrates that Label Spreading and Self-training can learn good boundaries even when small amounts of labeled data are available.

Note that Self-training with 100% of the data is omitted as it is functionally identical to training the SVC on 100% of the data.
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.svm import SVC
from sklearn.semi_supervised import LabelSpreading
from sklearn.semi_supervised import SelfTrainingClassifier

iris = datasets.load_iris()
X = iris.data[:, :2]
y = iris.target

# step size in the mesh
h = .02
rng = np.random.RandomState(0)
y_rand = rng.rand(y.shape[0])
y_30 = np.copy(y)

(continues on next page)
```python
y_30[y_rand < 0.3] = -1  # set random samples to be unlabeled
y_50 = np.copy(y)
y_50[y_rand < 0.5] = -1
# we create an instance of SVM and fit out data. We do not scale our
data since we want to plot the support vectors
ls30 = (LabelSpreading().fit(X, y_30), y_30, 'Label Spreading 30\% data')
ls50 = (LabelSpreading().fit(X, y_50), y_50, 'Label Spreading 50\% data')
ls100 = (LabelSpreading().fit(X, y), y, 'Label Spreading 100\% data')

# the base classifier for self-training is identical to the SVC
base_classifier = SVC(kernel='rbf', gamma=.5, probability=True)
st30 = (SelfTrainingClassifier(base_classifier).fit(X, y_30), y_30, 'Self-training 30\% data')
st50 = (SelfTrainingClassifier(base_classifier).fit(X, y_50), y_50, 'Self-training 50\% data')

rbf_svc = (SVC(kernel='rbf', gamma=.5).fit(X, y), y, 'SVC with rbf kernel')

# create a mesh to plot in
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))

color_map = {-1: (1, 1, 1), 0: (0, 0, .9), 1: (1, 0, 0), 2: (.8, .6, 0)}

classifiers = (ls30, st30, ls50, st50, ls100, rbf_svc)
for i, (clf, y_train, title) in enumerate(classifiers):
    # Plot the decision boundary. For that, we will assign a color to each
    # point in the mesh [x_min, x_max]x[y_min, y_max].
    plt.subplot(3, 2, i + 1)
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)
    plt.contourf(xx, yy, Z, cmap=plt.cm.Paired)
    plt.axis('off')

    # Put the result into a color plot
    Z = Z.reshape(xx.shape)
    plt.contourf(xx, yy, Z, cmap=plt.cm.Paired)
    plt.axis('off')

    # Plot also the training points
    colors = [color_map[y] for y in y_train]
    plt.scatter(X[:, 0], X[:, 1], c=colors, edgecolors='black')

plt.title(title)
plt.suptitle("Unlabeled points are colored white", y=0.1)
plt.show()
```

Total running time of the script: ( 0 minutes 1.966 seconds)
6.28.4 Effect of varying threshold for self-training

This example illustrates the effect of a varying threshold on self-training. The `breast_cancer` dataset is loaded, and labels are deleted such that only 50 out of 569 samples have labels. A `SelfTrainingClassifier` is fitted on this dataset, with varying thresholds.

The upper graph shows the amount of labeled samples that the classifier has available by the end of fit, and the accuracy of the classifier. The lower graph shows the last iteration in which a sample was labeled. All values are cross validated with 3 folds.

At low thresholds (in $[0.4, 0.5]$), the classifier learns from samples that were labeled with a low confidence. These low-confidence samples are likely have incorrect predicted labels, and as a result, fitting on these incorrect labels produces a poor accuracy. Note that the classifier labels almost all of the samples, and only takes one iteration.

For very high thresholds (in $[0.9, 1]$) we observe that the classifier does not augment its dataset (the amount of self-labeled samples is 0). As a result, the accuracy achieved with a threshold of 0.9999 is the same as a normal supervised classifier would achieve.

The optimal accuracy lies in between both of these extremes at a threshold of around 0.7.

```
print(__doc__)

# Authors: Oliver Rausch <rauscho@ethz.ch>
# License: BSD

import numpy as np
```
import matplotlib.pyplot as plt
from sklearn import datasets
from sklearn.svm import SVC
from sklearn.model_selection import StratifiedKFold
from sklearn.semi_supervised import SelfTrainingClassifier
from sklearn.metrics import accuracy_score
from sklearn.utils import shuffle

n_splits = 3

X, y = datasets.load_breast_cancer(return_X_y=True)
X, y = shuffle(X, y, random_state=42)
y_true = y.copy()
y[50:] = -1

total_samples = y.shape[0]

base_classifier = SVC(probability=True, gamma=0.001, random_state=42)

x_values = np.arange(0.4, 1.05, 0.05)
x_values = np.append(x_values, 0.99999)
scores = np.empty((x_values.shape[0], n_splits))
amount_labeled = np.empty((x_values.shape[0], n_splits))
amount_iterations = np.empty((x_values.shape[0], n_splits))

for (i, threshold) in enumerate(x_values):
    self_training_clf = SelfTrainingClassifier(base_classifier, threshold=threshold)

    # We need manual cross validation so that we don't treat -1 as a separate
class when computing accuracy
    skfolds = StratifiedKFold(n_splits=n_splits)
    for fold, (train_index, test_index) in enumerate(skfolds.split(X, y)):
        X_train = X[train_index]
y_train = y[train_index]
        X_test = X[test_index]
y_test = y[test_index]
        y_test_true = y_true[test_index]

        self_training_clf.fit(X_train, y_train)
        amount_labeled[i, fold] = total_samples - np.unique(self_training_clf.labeled_iter_, return_counts=True)[1][0]

        y_pred = self_training_clf.predict(X_test)
scores[i, fold] = accuracy_score(y_test_true, y_pred)

ax1 = plt.subplot(211)
ax1.errorbar(x_values, scores.mean(axis=1), yerr=scores.std(axis=1), capsize=2, color='b')
ax1.set_ylabel('Accuracy', color='b')
ax1.tick_params('y', colors='b')

(continues on next page)
6.28.5 Semi-supervised Classification on a Text Dataset

In this example, semi-supervised classifiers are trained on the 20 newsgroups dataset (which will be automatically downloaded).

You can adjust the number of categories by giving their names to the dataset loader or setting them to None to get all 20 of them.

Out:

11314 documents
20 categories

Supervised SGDClassifier on 100% of the data:
Number of training samples: 8485
Unlabeled samples in training set: 0
Micro-averaged F1 score on test set: 0.909
-------

Supervised SGDClassifier on 20% of the training data:
Number of training samples: 1688
Unlabeled samples in training set: 0
Micro-averaged F1 score on test set: 0.791
-------

SelfTrainingClassifier on 20% of the training data (rest is unlabeled):
Number of training samples: 8485
Unlabeled samples in training set: 6797
End of iteration 1, added 2852 new labels.
End of iteration 2, added 694 new labels.
End of iteration 3, added 183 new labels.
End of iteration 4, added 68 new labels.
End of iteration 5, added 37 new labels.
End of iteration 6, added 31 new labels.
End of iteration 7, added 11 new labels.
End of iteration 8, added 8 new labels.
End of iteration 9, added 4 new labels.
End of iteration 10, added 2 new labels.
Micro-averaged F1 score on test set: 0.835

import os

import numpy as np

from sklearn.datasets import fetch_20newsgroups
from sklearn.feature_extraction.text import CountVectorizer
from sklearn.feature_extraction.text import TfidfTransformer
from sklearn.preprocessing import FunctionTransformer
from sklearn.linear_model import SGDClassifier
from sklearn.model_selection import train_test_split
from sklearn.pipeline import Pipeline
from sklearn.semi_supervised import SelfTrainingClassifier
from sklearn.semi_supervised import LabelSpreading

data = fetch_20newsgroups(subset='train', categories=None)
print("%d documents" % len(data.filenames))
print("%d categories" % len(data.target_names))
print()

# Parameters
sdg_params = dict(alpha=1e-5, penalty='l2', loss='log')
vectorizer_params = dict(ngram_range=(1, 2), min_df=5, max_df=0.8)

# Supervised Pipeline
data = fetch_20newsgroups(subset='train', categories=None)
print("%d documents" % len(data.filenames))
print("%d categories" % len(data.target_names))
print()

# Parameters
sdg_params = dict(alpha=1e-5, penalty='l2', loss='log')
vectorizer_params = dict(ngram_range=(1, 2), min_df=5, max_df=0.8)

# Supervised Pipeline
pipeline = Pipeline([
    ('vect', CountVectorizer(**vectorizer_params)),
    ('tfidf', TfidfTransformer()),
    ('clf', SGDClassifier(**sdg_params)),
])

# SelfTraining Pipeline
st_pipeline = Pipeline([
    ('vect', CountVectorizer(**vectorizer_params)),
    ('tfidf', TfidfTransformer()),
    ('clf', SelfTrainingClassifier(SGDClassifier(**sdg_params), verbose=True)),
])

# LabelSpreading Pipeline
ls_pipeline = Pipeline([
    ('vect', CountVectorizer(**vectorizer_params)),
    ('tfidf', TfidfTransformer()),
    ('todense', FunctionTransformer(lambda x: x.todense())),
    ('clf', LabelSpreading()),
])
def eval_and_print_metrics(clf, X_train, y_train, X_test, y_test):
    print("Number of training samples: ", len(X_train))
    print("Unlabeled samples in training set:",
          sum(1 for x in y_train if x == -1))
    clf.fit(X_train, y_train)
    y_pred = clf.predict(X_test)
    print("Micro-averaged F1 score on test set: ",
          "%.3f" % f1_score(y_test, y_pred, average='micro'))
    print("-

if __name__ == "__main__":
    X, y = data.data, data.target
    X_train, X_test, y_train, y_test = train_test_split(X, y)

    print("Supervised SGDClassifier on 100% of the data:")
    eval_and_print_metrics(pipeline, X_train, y_train, X_test, y_test)

    # select a mask of 20% of the train dataset
    y_mask = np.random.rand(len(y_train)) < 0.2

    # X_20 and y_20 are the subset of the train dataset indicated by the mask
    X_20, y_20 = map(list, zip(*((x, y)
            for x, y, m in zip(X_train, y_train, y_mask) if m)))
    print("Supervised SGDClassifier on 20% of the training data:")
    eval_and_print_metrics(pipeline, X_20, y_20, X_test, y_test)

    # set the non-masked subset to be unlabeled
    y_train[~y_mask] = -1
    print("SelfTrainingClassifier on 20% of the training data (rest "
          "is unlabeled):")
    eval_and_print_metrics(st_pipeline, X_train, y_train, X_test, y_test)

    if 'CI' not in os.environ:
        # LabelSpreading takes too long to run in the online documentation
        print("LabelSpreading on 20% of the data (rest is unlabeled):")
        eval_and_print_metrics(ls_pipeline, X_train, y_train, X_test, y_test)

Total running time of the script: 0 minutes 25.581 seconds

6.28.6 Label Propagation digits active learning

Demonstrates an active learning technique to learn handwritten digits using label propagation.

We start by training a label propagation model with only 10 labeled points, then we select the top five most uncertain points to label. Next, we train with 15 labeled points (original 10 + 5 new ones). We repeat this process four times to have a model trained with 30 labeled examples. Note you can increase this to label more than 30 by changing max_iterations. Labeling more than 30 can be useful to get a sense for the speed of convergence of this active learning technique.

A plot will appear showing the top 5 most uncertain digits for each iteration of training. These may or may not contain mistakes, but we will train the next model with their true labels.
Out:

```
Iteration 0
Label Spreading model: 40 labeled & 290 unlabeled (330 total)

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>22</td>
</tr>
<tr>
<td>1</td>
<td>0.78</td>
<td>0.69</td>
<td>0.73</td>
<td>26</td>
</tr>
<tr>
<td>2</td>
<td>0.93</td>
<td>0.93</td>
<td>0.93</td>
<td>29</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>0.89</td>
<td>0.94</td>
<td>27</td>
</tr>
<tr>
<td>4</td>
<td>0.92</td>
<td>0.96</td>
<td>0.94</td>
<td>23</td>
</tr>
<tr>
<td>5</td>
<td>0.96</td>
<td>0.80</td>
<td>0.81</td>
<td>33</td>
</tr>
<tr>
<td>6</td>
<td>0.97</td>
<td>0.87</td>
<td>0.97</td>
<td>35</td>
</tr>
<tr>
<td>7</td>
<td>0.94</td>
<td>0.91</td>
<td>0.92</td>
<td>33</td>
</tr>
<tr>
<td>8</td>
<td>0.62</td>
<td>0.89</td>
<td>0.74</td>
<td>28</td>
</tr>
<tr>
<td>9</td>
<td>0.73</td>
<td>0.79</td>
<td>0.76</td>
<td>34</td>
</tr>
</tbody>
</table>

accuracy: 0.87
macro avg: 0.89
weighted avg: 0.88

Confusion matrix
[[22 0 0 0 0 0 0 0 0 0]
 [0 18 2 0 0 0 1 0 5 0]
 [0 0 27 0 0 0 0 2 0]
 [0 0 0 24 0 0 0 0 3 0]]
```

(continues on next page)
Iteration 1
Label Spreading model: 45 labeled & 285 unlabeled (330 total)

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
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<td>22</td>
</tr>
<tr>
<td>1</td>
<td>0.79</td>
<td>1.00</td>
<td>0.88</td>
<td>22</td>
</tr>
<tr>
<td>2</td>
<td>1.00</td>
<td>0.93</td>
<td>0.96</td>
<td>29</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>26</td>
</tr>
<tr>
<td>4</td>
<td>0.92</td>
<td>0.96</td>
<td>0.94</td>
<td>23</td>
</tr>
<tr>
<td>5</td>
<td>0.96</td>
<td>0.70</td>
<td>0.81</td>
<td>33</td>
</tr>
<tr>
<td>6</td>
<td>1.00</td>
<td>0.97</td>
<td>0.99</td>
<td>35</td>
</tr>
<tr>
<td>7</td>
<td>0.94</td>
<td>0.91</td>
<td>0.92</td>
<td>33</td>
</tr>
<tr>
<td>8</td>
<td>0.77</td>
<td>0.86</td>
<td>0.81</td>
<td>28</td>
</tr>
<tr>
<td>9</td>
<td>0.73</td>
<td>0.79</td>
<td>0.76</td>
<td>34</td>
</tr>
</tbody>
</table>

macro avg: 0.91, weighted avg: 0.90

Confusion matrix

Iteration 2
Label Spreading model: 50 labeled & 280 unlabeled (330 total)

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
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<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>22</td>
</tr>
<tr>
<td>1</td>
<td>0.85</td>
<td>1.00</td>
<td>0.92</td>
<td>22</td>
</tr>
<tr>
<td>2</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>28</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>26</td>
</tr>
<tr>
<td>4</td>
<td>0.87</td>
<td>1.00</td>
<td>0.93</td>
<td>20</td>
</tr>
<tr>
<td>5</td>
<td>0.96</td>
<td>0.70</td>
<td>0.81</td>
<td>33</td>
</tr>
<tr>
<td>6</td>
<td>1.00</td>
<td>0.97</td>
<td>0.99</td>
<td>35</td>
</tr>
<tr>
<td>7</td>
<td>0.94</td>
<td>1.00</td>
<td>0.97</td>
<td>32</td>
</tr>
<tr>
<td>8</td>
<td>0.92</td>
<td>0.86</td>
<td>0.89</td>
<td>28</td>
</tr>
<tr>
<td>9</td>
<td>0.73</td>
<td>0.79</td>
<td>0.76</td>
<td>34</td>
</tr>
</tbody>
</table>

accuracy: 0.92, macro avg: 0.93, weighted avg: 0.92

Confusion matrix

(continues on next page)
Iteration 3

Label Spreading model: 55 labeled & 275 unlabeled (330 total)

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
<tr>
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<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>22</td>
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<td>1</td>
<td>0.85</td>
<td>1.00</td>
<td>0.92</td>
<td>22</td>
</tr>
<tr>
<td>2</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>27</td>
</tr>
<tr>
<td>3</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>26</td>
</tr>
<tr>
<td>4</td>
<td>0.87</td>
<td>1.00</td>
<td>0.93</td>
<td>20</td>
</tr>
<tr>
<td>5</td>
<td>0.96</td>
<td>0.87</td>
<td>0.92</td>
<td>31</td>
</tr>
<tr>
<td>6</td>
<td>1.00</td>
<td>0.97</td>
<td>0.99</td>
<td>35</td>
</tr>
<tr>
<td>7</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>31</td>
</tr>
<tr>
<td>8</td>
<td>0.92</td>
<td>0.86</td>
<td>0.89</td>
<td>28</td>
</tr>
<tr>
<td>9</td>
<td>0.88</td>
<td>0.85</td>
<td>0.86</td>
<td>33</td>
</tr>
</tbody>
</table>

accuracy 0.95 275
macro avg 0.95 0.95 0.95 275
weighted avg 0.95 0.95 0.95 275

Confusion matrix

```plaintext
[[22 0 0 0 0 0 0 0 0 0]
 [ 0 22 0 0 0 0 0 0 0 0]
 [ 0 0 27 0 0 0 0 0 0 0]
 [ 0 0 0 20 0 0 0 0 0 0]
 [ 0 0 0 0 27 0 0 0 0 0]
 [ 0 1 0 0 0 34 0 0 0 0]
 [ 0 0 0 0 0 0 31 0 0 0]
 [ 0 3 0 0 1 0 0 24 0]
 [ 0 0 0 0 2 1 0 2 2 28]]
```

Iteration 4

Label Spreading model: 60 labeled & 270 unlabeled (330 total)

<table>
<thead>
<tr>
<th></th>
<th>precision</th>
<th>recall</th>
<th>f1-score</th>
<th>support</th>
</tr>
</thead>
<tbody>
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<td>0</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>22</td>
</tr>
<tr>
<td>1</td>
<td>0.96</td>
<td>1.00</td>
<td>0.98</td>
<td>22</td>
</tr>
<tr>
<td>2</td>
<td>1.00</td>
<td>0.96</td>
<td>0.98</td>
<td>27</td>
</tr>
<tr>
<td>3</td>
<td>0.96</td>
<td>1.00</td>
<td>0.98</td>
<td>25</td>
</tr>
<tr>
<td>4</td>
<td>0.86</td>
<td>1.00</td>
<td>0.93</td>
<td>19</td>
</tr>
<tr>
<td>5</td>
<td>0.96</td>
<td>0.87</td>
<td>0.92</td>
<td>31</td>
</tr>
<tr>
<td>6</td>
<td>1.00</td>
<td>0.97</td>
<td>0.99</td>
<td>35</td>
</tr>
<tr>
<td>7</td>
<td>1.00</td>
<td>1.00</td>
<td>1.00</td>
<td>31</td>
</tr>
<tr>
<td>8</td>
<td>0.92</td>
<td>0.96</td>
<td>0.94</td>
<td>25</td>
</tr>
<tr>
<td>9</td>
<td>0.88</td>
<td>0.85</td>
<td>0.86</td>
<td>33</td>
</tr>
</tbody>
</table>

accuracy 0.96 270
macro avg 0.95 0.96 0.96 270
weighted avg 0.95 0.96 0.96 270
Confusion matrix

```
[[22  0  0  0  0  0  0  0  0  0]
 [ 0 22  0  0  0  0  0  0  0  0]
 [ 0  0 26  1  0  0  0  0  0  0]
 [ 0  0  0 25  0  0  0  0  0  0]
 [ 0  0  0  0 19  0  0  0  0  0]
 [ 0  0  0  0  0 27  0  0  0  4]
 [ 0  1  0  0  0  0 34  0  0  0]
 [ 0  0  0  0  0  0 31  0  0  0]
 [ 0  0  0  0  1  0  0  24  0  0]
 [ 0  0  0  0  2  1  0  0  2 28]]
```

print(__doc__)

# Authors: Clay Woolam <clay@woolam.org>
# License: BSD

import numpy as np
import matplotlib.pyplot as plt
from scipy import stats
from sklearn import datasets
from sklearn.semi_supervised import LabelSpreading
from sklearn.metrics import classification_report, confusion_matrix

digits = datasets.load_digits()
rng = np.random.RandomState(0)
indices = np.arange(len(digits.data))
rng.shuffle(indices)
X = digits.data[indices[:330]]
y = digits.target[indices[:330]]
images = digits.images[indices[:330]]

n_total_samples = len(y)
n_labeled_points = 40
max_iterations = 5

unlabeled_indices = np.arange(n_total_samples)[n_labeled_points:]
f = plt.figure()

for i in range(max_iterations):
    if len(unlabeled_indices) == 0:
        print("No unlabeled items left to label."
        break
    y_train = np.copy(y)
y_train[unlabeled_indices] = -1
    lp_model = LabelSpreading(gamma=0.25, max_iter=20)
    lp_model.fit(X, y_train)

(continues on next page)
predicted_labels = lp_model.transduction_[unlabeled_indices]
true_labels = y[unlabeled_indices]

cm = confusion_matrix(true_labels, predicted_labels,
                         labels=lp_model.classes_)

print("Iteration %i %s % (i, 70 * ")
print("Label Spreading model: %d labeled & %d unlabeled (%d total)
       % (n_labeled_points, n_total_samples - n_labeled_points,
           n_total_samples))

print(classification_report(true_labels, predicted_labels))
print("Confusion matrix")
print(cm)

# compute the entropies of transduced label distributions
pred_entropies = stats.distributions.entropy(
    lp_model.label_distributions_.T)

# select up to 5 digit examples that the classifier is most uncertain about
uncertainty_index = np.argsort(pred_entropies)[::-1]
uncertainty_index = uncertainty_index[np.in1d(uncertainty_index, unlabeled_indices)][:5]

# keep track of indices that we get labels for
delete_indices = np.array([], dtype=int)
# for more than 5 iterations, visualize the gain only on the first 5
if i < 5:
    f.text(.05, (1 - (i + 1) * .183),
           "model %d

fit with %d labels" %
            (i + 1), i * 5 + 10), size=10)
for index, image_index in enumerate(uncertainty_index):
    image = images[image_index]
    sub.imshow(image, cmap=plt.cm.gray_r, interpolation='none')
    sub.set_title("predict:

true:

" % (lp_model.transduction_[image_index], y[image_index]), size=10)
    sub.axis('off')

# labeling 5 points, remote from labeled set
delete_index, = np.where(unlabeled_indices == image_index)
delete_indices = np.concatenate((delete_indices, delete_index))

unlabeled_indices = np.delete(unlabeled_indices, delete_indices)
n_labeled_points += len(uncertainty_index)

f.suptitle("Active learning with Label Propagation.

Rows show 5 most 
"uncertain labels to learn with the next model.", y=1.15)
plt.subplots_adjust(left=0.2, bottom=0.03, right=0.9, top=0.9, wspace=0.2,
                    hspace=0.85)
plt.show()
6.29 Support Vector Machines

Examples concerning the `sklearn.svm` module.

6.29.1 Non-linear SVM

Perform binary classification using non-linear SVC with RBF kernel. The target to predict is a XOR of the inputs. The color map illustrates the decision function learned by the SVC.

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm

xx, yy = np.meshgrid(np.linspace(-3, 3, 500),
                     np.linspace(-3, 3, 500))

np.random.seed(0)
X = np.random.randn(300, 2)
Y = np.logical_xor(X[:, 0] > 0, X[:, 1] > 0)
```
# fit the model
clf = svm.NuSVC(gamma='auto')
clf.fit(X, Y)

# plot the decision function for each datapoint on the grid
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
plt.imshow(Z, interpolation='nearest',
          extent=(xx.min(), xx.max(), yy.min(), yy.max()), aspect='auto',
          origin='lower', cmap=plt.cm.PuOr_r)
contours = plt.contour(xx, yy, Z, levels=[0], linewidths=2,
                       linestyles='dashed')
plt.scatter(X[:, 0], X[:, 1], s=30, c=Y, cmap=plt.cm.Paired,
            edgecolors='k')
plt.xticks(())
plt.yticks(())
plt.axis([-3, 3, -3, 3])
plt.show()

Total running time of the script: ( 0 minutes 3.399 seconds)

### 6.29.2 SVM: Maximum margin separating hyperplane

Plot the maximum margin separating hyperplane within a two-class separable dataset using a Support Vector Machine classifier with linear kernel.
from sklearn import svm
from sklearn.datasets import make_blobs

# we create 40 separable points
X, y = make_blobs(n_samples=40, centers=2, random_state=6)

# fit the model, don't regularize for illustration purposes
clf = svm.SVC(kernel='linear', C=1000)
clf.fit(X, y)

plt.scatter(X[:, 0], X[:, 1], c=y, s=30, cmap=plt.cm.Paired)

# plot the decision function
ax = plt.gca()
xlim = ax.get_xlim()
ylim = ax.get_ylim()

# create grid to evaluate model
xx = np.linspace(xlim[0], xlim[1], 30)
yy = np.linspace(ylim[0], ylim[1], 30)
YY, XX = np.meshgrid(yy, xx)
xy = np.vstack([XX.ravel(), YY.ravel()]).T
Z = clf.decision_function(xy).reshape(XX.shape)

# plot decision boundary and margins
ax.contour(XX, YY, Z, colors='k', levels=[-1, 0, 1], alpha=0.5,
          linestyles=['--', '-', '--'])
# plot support vectors
ax.scatter(clf.support_vectors_[:, 0], clf.support_vectors_[:, 1], s=100,
           linewidth=1, facecolors='none', edgecolors='k')
plt.show()

Total running time of the script: (0 minutes 0.076 seconds)

6.29.3 SVM with custom kernel

Simple usage of Support Vector Machines to classify a sample. It will plot the decision surface and the support vectors.

3-Class classification using Support Vector Machine with custom kernel

Out:
/home/circleci/project/examples/svm/plot_custom_kernel.py:50:
  → MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
  → as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
  → with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[→ 'pcolor.shading']. This will become an error two minor releases later.
```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm, datasets

# import some data to play with
iris = datasets.load_iris()
X = iris.data[:, :2]
# we only take the first two features. We could
# avoid this ugly slicing by using a two-dim dataset
Y = iris.target

def my_kernel(X, Y):
    """
    We create a custom kernel:
    \[ k(X, Y) = X (2 0) Y.T \]
    \[ \quad (0 1) \]
    """
    M = np.array([[2, 0], [0, 1.0]])
    return np.dot(np.dot(X, M), Y.T)

h = .02  # step size in the mesh

# we create an instance of SVM and fit out data.
clf = svm.SVC(kernel=my_kernel)
clf.fit(X, Y)

# Plot the decision boundary. For that, we will assign a color to each
# point in the mesh [x_min, x_max]x[y_min, y_max].
x_min, x_max = X[:, 0].min() - 1, X[:, 0].max() + 1
y_min, y_max = X[:, 1].min() - 1, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h), np.arange(y_min, y_max, h))
Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])

# Put the result into a color plot
Z = Z.reshape(xx.shape)
plt.pcolormesh(xx, yy, Z, cmap=plt.cm.Paired)

# Plot also the training points
plt.scatter(X[:, 0], X[:, 1], c=Y, cmap=plt.cm.Paired, edgecolors='k')
plt.title('3-Class classification using Support Vector Machine with custom'
'kernel')
plt.axis('tight')
plt.show()
```

Total running time of the script: (0 minutes 0.167 seconds)
6.29.4 SVM Tie Breaking Example

Tie breaking is costly if decision_function_shape='ovr', and therefore it is not enabled by default. This example illustrates the effect of the break_ties parameter for a multiclass classification problem and decision_function_shape='ovr'.

The two plots differ only in the area in the middle where the classes are tied. If break_ties=False, all input in that area would be classified as one class, whereas if break_ties=True, the tie-breaking mechanism will create a non-convex decision boundary in that area.
break_ties = False

break_ties = True

print(__doc__)

# Code source: Andreas Mueller, Adrin Jalali
# License: BSD 3 clause

```python
import numpy as np
dllimport matplotlib.pyplot as plt
import sklearn.svm import SVC
from sklearn.datasets import make_blobs

X, y = make_blobs(random_state=27)

fig, sub = plt.subplots(2, 1, figsize=(5, 8))
titles = (“break_ties = False”,
          “break_ties = True”)  
for break_ties, title, ax in zip((False, True), titles, sub.flatten()):
    svm = SVC(kernel="linear", C=1, break_ties=break_ties,
              decision_function_shape=’ovr‘).fit(X, y)
    xlim = [X[:, 0].min(), X[:, 0].max()]
    ylim = [X[:, 1].min(), X[:, 1].max()]
    xs = np.linspace(xlim[0], xlim[1], 1000)
    ys = np.linspace(ylim[0], ylim[1], 1000)
    xx, yy = np.meshgrid(xs, ys)
    pred = svm.predict(np.c_[xx.ravel(), yy.ravel()])
    colors = [plt.cm.Accent(i) for i in [0, 4, 7]]
    points = ax.scatter(X[:, 0], X[:, 1], c=y, cmap="Accent")
    classes = [(0, 1), (0, 2), (1, 2)]
    line = np.linspace(X[:, 1].min() - 5, X[:, 1].max() + 5)
    ax.imshow(-pred.reshape(xx.shape), cmap="Accent", alpha=.2,
              extent=(xlim[0], xlim[1], ylim[1], ylim[0]))
    for coef, intercept, col in zip(svm.coef_, svm.intercept_, classes):
        line2 = -(line * coef[1] + intercept) / coef[0]
        ax.plot(line2, line, “-", c=colors[0])
        ax.plot(line2, line, "--", c=colors[1])
    ax.set_xlim(xlim)
    ax.set_ylim(ylim)
    ax.set_title(title)
    ax.set_aspect("equal")
```

**Total running time of the script:** ( 0 minutes 1.355 seconds)
6.29.5 SVM: Weighted samples

Plot decision function of a weighted dataset, where the size of points is proportional to its weight.

The sample weighting rescales the C parameter, which means that the classifier puts more emphasis on getting these points right. The effect might often be subtle. To emphasize the effect here, we particularly weight outliers, making the deformation of the decision boundary very visible.

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm

def plot_decision_function(classifier, sample_weight, axis, title):
    # plot the decision function
    xx, yy = np.meshgrid(np.linspace(-4, 5, 500), np.linspace(-4, 5, 500))
    Z = classifier.decision_function(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)
    # plot the line, the points, and the nearest vectors to the plane
    axis.contourf(xx, yy, Z, alpha=0.75, cmap=plt.cm.bone)
    axis.scatter(X[:, 0], X[:, 1], c=y, s=100 * sample_weight, alpha=0.9, cmap=plt.cm.bone, edgecolors='black')
    axis.axis('off')
    axis.set_title(title)

# we create 20 points
np.random.seed(0)
X = np.r_[np.random.randn(10, 2) + [1, 1], np.random.randn(10, 2)]
y = [1] * 10 + [-1] * 10
sample_weight_last_ten = abs(np.random.randn(len(X)))
sample_weight_constant = np.ones(len(X))
# and bigger weights to some outliers
sample_weight_last_ten[15:] *= 5
```

(continues on next page)
sample_weight_last_ten[9] *= 15

# for reference, first fit without sample weights

# fit the model
clf_weights = svm.SVC(gamma=1)
clf_weights.fit(X, y, sample_weight=sample_weight_last_ten)

clf_no_weights = svm.SVC(gamma=1)
clf_no_weights.fit(X, y)

fig, axes = plt.subplots(1, 2, figsize=(14, 6))
plot_decision_function(clf_no_weights, sample_weight_constant, axes[0], "Constant weights")
plot_decision_function(clf_weights, sample_weight_last_ten, axes[1], "Modified weights")
plt.show()

**Total running time of the script:** ( 0 minutes 0.911 seconds)

### 6.29.6 Plot the support vectors in LinearSVC

Unlike SVC (based on LIBSVM), LinearSVC (based on LIBLINEAR) does not provide the support vectors. This example demonstrates how to obtain the support vectors in LinearSVC.

```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import make_blobs
from sklearn.svm import LinearSVC

X, y = make_blobs(n_samples=40, centers=2, random_state=0)
```
plt.figure(figsize=(10, 5))
for i, C in enumerate([1, 100]):
    # "hinge" is the standard SVM loss
    clf = LinearSVC(C=C, loss="hinge", random_state=42).fit(X, y)
    # obtain the support vectors through the decision function
    decision_function = clf.decision_function(X)
    # we can also calculate the decision function manually
    # decision_function = np.dot(X, clf.coef_[0]) + clf.intercept_[0]
    # The support vectors are the samples that lie within the margin
    # boundaries, whose size is conventionally constrained to 1
    support_vector_indices = np.where(np.abs(decision_function) <= 1 + 1e-15)[0]
    support_vectors = X[support_vector_indices]
    plt.subplot(1, 2, i + 1)
    plt.scatter(X[:, 0], X[:, 1], c=y, s=30, cmap=plt.cm.Paired)
    ax = plt.gca()
xlim = ax.get_xlim()
ylim = ax.get_ylim()
xx, yy = np.meshgrid(np.linspace(xlim[0], xlim[1], 50),
                     np.linspace(ylim[0], ylim[1], 50))
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
plt.contour(xx, yy, Z, colors='k', levels=[-1, 0, 1], alpha=0.5,
            linestyles=['--', '-', '--'])
plt.scatter(support_vectors[:, 0], support_vectors[:, 1], s=100,
            linewidth=1, facecolors='none', edgecolors='k')
plt.title("C=" + str(C))
plt.tight_layout()
plt.show()

Total running time of the script: ( 0 minutes 0.152 seconds)

6.29.7 SVM: Separating hyperplane for unbalanced classes

Find the optimal separating hyperplane using an SVC for classes that are unbalanced.
We first find the separating plane with a plain SVC and then plot (dashed) the separating hyperplane with automatically correction for unbalanced classes.

Note: This example will also work by replacing `SVC(kernel="linear")` with `SGDClassifier(loss="hinge")`. Setting the loss parameter of the `SGDClassifier` equal to `hinge` will yield behaviour such as that of a SVC with a linear kernel.

For example try instead of the SVC:

```python
clf = SGDClassifier(n_iter=100, alpha=0.01)
```
import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm
from sklearn.datasets import make_blobs

# we create two clusters of random points
n_samples_1 = 1000
n_samples_2 = 100
centers = [[0.0, 0.0], [2.0, 2.0]]
clusters_std = [1.5, 0.5]
X, y = make_blobs(n_samples=[n_samples_1, n_samples_2],
                  centers=centers,
                  cluster_std=clusters_std,
                  random_state=0, shuffle=False)

# fit the model and get the separating hyperplane
clf = svm.SVC(kernel='linear', C=1.0)
clf.fit(X, y)

# fit the model and get the separating hyperplane using weighted classes
wclf = svm.SVC(kernel='linear', class_weight={1: 10})
wclf.fit(X, y)
# plot the samples
plt.scatter(X[:, 0], X[:, 1], c=y, cmap=plt.cm.Paired, edgecolors='k')

# plot the decision functions for both classifiers
ax = plt.gca()
xlim = ax.get_xlim()
ylim = ax.get_ylim()

# create grid to evaluate model
xx = np.linspace(xlim[0], xlim[1], 30)
yy = np.linspace(ylim[0], ylim[1], 30)
YY, XX = np.meshgrid(yy, xx)
xy = np.vstack((XX.ravel(), YY.ravel())).T

# get the separating hyperplane
Z = clf.decision_function(xy).reshape(XX.shape)

# plot decision boundary and margins
a = ax.contour(XX, YY, Z, colors='k', levels=[0], alpha=0.5, linestyles=['-'])

# get the separating hyperplane for weighted classes
Z = wclf.decision_function(xy).reshape(XX.shape)

# plot decision boundary and margins for weighted classes
b = ax.contour(XX, YY, Z, colors='r', levels=[0], alpha=0.5, linestyles=['-'])

plt.legend([a.collections[0], b.collections[0]], ['non weighted', 'weighted'], loc="upper right")
plt.show()

Total running time of the script: ( 0 minutes 0.134 seconds)

## 6.29.8 SVM-Kernels

Three different types of SVM-Kernels are displayed below. The polynomial and RBF are especially useful when the data-points are not linearly separable.
"MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions. Either specify the corners of the quadrilaterals with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases later.
plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)"

print(__doc__)

# Code source: Gaël Varoquaux
# License: BSD 3 clause

import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm

(continues on next page)
# Our dataset and targets
X = np.c_[[(.4, -.7),
(-1.5, -1),
(-1.4, -.9),
(-1.3, -1.2),
(-1.1, -.2),
(-1.2, -.4),
(-.5, 1.2),
(-1.5, 2.1),
(1, 1),
# --
(1.3, .8),
(1.2, .5),
(.2, -2),
(.5, -2.4),
(.2, -2.3),
(0, -2.7),
(1.3, 2.1)].T
Y = [0] * 8 + [1] * 8

# figure number
fignum = 1

# fit the model
for kernel in ('linear', 'poly', 'rbf'):
    clf = svm.SVC(kernel=kernel, gamma=2)
    clf.fit(X, Y)

    # plot the line, the points, and the nearest vectors to the plane
    plt.figure(fignum, figsize=(4, 3))
    plt.clf()
    plt.scatter(clf.support_vectors_[:, 0], clf.support_vectors_[:, 1], s=80,
                facecolors='none', zorder=10, edgecolors='k')
    plt.scatter(X[:, 0], X[:, 1], c=Y, zorder=10, cmap=plt.cm.Paired,
                edgecolors='k')

    plt.axis('tight')
    x_min = -3
    x_max = 3
    y_min = -3
    y_max = 3

    XX, YY = np.mgrid[x_min:x_max:200j, y_min:y_max:200j]
    Z = clf.decision_function(np.c_[XX.ravel(), YY.ravel()])

    # Put the result into a color plot
    Z = Z.reshape(XX.shape)
    plt.figure(fignum, figsize=(4, 3))
    plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
    plt.contour(XX, YY, Z, colors=['k', 'k', 'k'], linestyles=['--', '-', '--'],
                levels=[-.5, 0, .5])

    plt.xlim(x_min, x_max)
    plt.ylim(y_min, y_max)

    plt.xticks(()
(continues on next page)
### 6.29.9 SVM-Anova: SVM with univariate feature selection

This example shows how to perform univariate feature selection before running a SVC (support vector classifier) to improve the classification scores. We use the iris dataset (4 features) and add 36 non-informative features. We can find that our model achieves best performance when we select around 10% of features.

```python
plt.yticks(()
fignum = fignum + 1
plt.show()
```

Total running time of the script: ( 0 minutes 0.227 seconds)

---

#### Performance of the SVM-Anova varying the percentile of features selected

![Graph showing the performance of SVM-Anova varying the percentile of features selected.]

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load_iris
from sklearn.feature_selection import SelectPercentile, chi2
from sklearn.model_selection import cross_val_score
from sklearn.pipeline import Pipeline
from sklearn.preprocessing import StandardScaler
from sklearn.svm import SVC
```

(continues on next page)
# Import some data to play with
X, y = load_iris(return_X_y=True)
# Add non-informative features
np.random.seed(0)
X = np.hstack((X, 2 * np.random.random((X.shape[0], 36))))
# Create a feature-selection transform, a scaler and an instance of SVM that we
# combine together to have a full-blown estimator
clf = Pipeline([['anova', SelectPercentile(chi2)],
                 ('scaler', StandardScaler()),
                 ('svc', SVC(gamma="auto"))])
# Plot the cross-validation score as a function of percentile of features
score_means = list()
score_stds = list()
percentiles = (1, 3, 6, 10, 15, 20, 30, 40, 60, 80, 100)
for percentile in percentiles:
    clf.set_params(anova__percentile=percentile)
    this_scores = cross_val_score(clf, X, y)
    score_means.append(this_scores.mean())
    score_stds.append(this_scores.std())
plt.errorbar(percentiles, score_means, np.array(score_stds))
plt.title('Performance of the SVM-Anova varying the percentile of features selected')
plt.xticks(np.linspace(0, 100, 11, endpoint=True))
plt.xlabel('Percentile')
plt.ylabel('Accuracy Score')
plt.axis('tight')
plt.show()

Total running time of the script: ( 0 minutes 0.303 seconds)

6.29.10 Support Vector Regression (SVR) using linear and non-linear kernels

Toy example of 1D regression using linear, polynomial and RBF kernels.
import numpy as np
from sklearn.svm import SVR
import matplotlib.pyplot as plt

# #############################################################################
# Generate sample data
X = np.sort(5 * np.random.rand(40, 1), axis=0)
y = np.sin(X).ravel()

# #############################################################################
# Add noise to targets
y[::5] += 3 * (0.5 - np.random.rand(8))

# #############################################################################
# Fit regression model
svr_rbf = SVR(kernel='rbf', C=100, gamma=0.1, epsilon=.1)
svr_lin = SVR(kernel='linear', C=100, gamma='auto')
svr_poly = SVR(kernel='poly', C=100, gamma='auto', degree=3, epsilon=.1, coef0=1)

# #############################################################################
# Look at the results
lw = 2
svrs = [svr_rbf, svr_lin, svr_poly]
kernel_label = ['RBF', 'Linear', 'Polynomial']
model_color = ['m', 'c', 'g']

fig, axes = plt.subplots(nrows=1, ncols=3, figsize=(15, 10), sharey=True)
for ix, svr in enumerate(svrs):
    axes[ix].plot(X, svr.fit(X, y).predict(X), color=model_color[ix], lw=lw,
                  label='{} model'.format(kernel_label[ix]))
    axes[ix].scatter(X[svr.support_], y[svr.support_], facecolor="none",
                      edgecolor=model_color[ix], s=50,
                      label='{} support vectors'.format(kernel_label[ix]))
    axes[ix].scatter(X[np.setdiff1d(np.arange(len(X)), svr.support_)],
                      y[np.setdiff1d(np.arange(len(X)), svr.support_)],
                      facecolor="none", edgecolor="k", s=50,
                      label='other training data')
    axes[ix].legend(loc='upper center', bbox_to_anchor=(0.5, 1.1),
                     ncol=1, fancybox=True, shadow=True)

fig.text(0.5, 0.04, 'data', ha='center', va='center')
fig.text(0.06, 0.5, 'target', ha='center', va='center', rotation='vertical')
fig.suptitle("Support Vector Regression", fontsize=14)
plt.show()

Total running time of the script: ( 0 minutes 3.239 seconds)

6.29.11 SVM Margins Example

The plots below illustrate the effect the parameter $C$ has on the separation line. A large value of $C$ basically tells our model that we do not have that much faith in our data’s distribution, and will only consider points close to line of separation.

A small value of $C$ includes more/all the observations, allowing the margins to be calculated using all the data in the area.

![SVM Margins Example](image.png)
```python
import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm

# we create 40 separable points
np.random.seed(0)
X = np.r_[np.random.randn(20, 2) - [2, 2], np.random.randn(20, 2) + [2, 2]]
Y = [0] * 20 + [1] * 20
```

(continues on next page)
fignum = 1

# fit the model
for name, penalty in [('unreg', 1), ('reg', 0.05)]:
    clf = svm.SVC(kernel='linear', C=penalty)
    clf.fit(X, Y)

    # get the separating hyperplane
    w = clf.coef_[0]
    a = -w[0] / w[1]
    xx = np.linspace(-5, 5)
    yy = a * xx - (clf.intercept_[0]) / w[1]

    # plot the parallels to the separating hyperplane that pass through the
    # support vectors (margin away from hyperplane in direction
    # perpendicular to hyperplane). This is sqrt(1+a^2) away vertically in
    # 2-d.
    margin = 1 / np.sqrt(np.sum(clf.coef_ ** 2))
    yy_down = yy - np.sqrt(1 + a ** 2) * margin
    yy_up = yy + np.sqrt(1 + a ** 2) * margin

    # plot the line, the points, and the nearest vectors to the plane
    plt.figure(fignum, figsize=(4, 3))
    plt.clf()
    plt.plot(xx, yy, 'k-')
    plt.plot(xx, yy_down, 'k--')
    plt.plot(xx, yy_up, 'k--')
    plt.scatter(clf.support_vectors_[:, 0], clf.support_vectors_[:, 1], s=80,
                facecolors='none', zorder=10, edgecolors='k')
    plt.scatter(X[:, 0], X[:, 1], c=Y, zorder=10, cmap=plt.cm.Paired,
                edgecolors='k')
    plt.axis('tight')
    x_min = -4.8
    x_max = 4.2
    y_min = -6
    y_max = 6

    XX, YY = np.mgrid[x_min:x_max:200j, y_min:y_max:200j]
    Z = clf.predict(np.c_[XX.ravel(), YY.ravel()])

    # Put the result into a color plot
    Z = Z.reshape(XX.shape)
    plt.figure(fignum, figsize=(4, 3))
    plt.pcolormesh(XX, YY, Z, cmap=plt.cm.Paired)
    plt.xlim(x_min, x_max)
    plt.ylim(y_min, y_max)
    plt.xticks(())
    plt.yticks(())
    fignum = fignum + 1

plt.show()
**6.29.12 One-class SVM with non-linear kernel (RBF)**

An example using a one-class SVM for novelty detection.

One-class SVM is an unsupervised algorithm that learns a decision function for novelty detection: classifying new data as similar or different to the training set.

```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
import matplotlib.font_manager
from sklearn import svm

xx, yy = np.meshgrid(np.linspace(-5, 5, 500), np.linspace(-5, 5, 500))
# Generate train data
X = 0.3 * np.random.randn(100, 2)
X_train = np.r_[X + 2, X - 2]
# Generate some regular novel observations
X = 0.3 * np.random.randn(20, 2)
X_test = np.r_[X + 2, X - 2]
# Generate some abnormal novel observations
X_outliers = np.random.uniform(low=-4, high=4, size=(20, 2))
```

(continues on next page)
# fit the model
clf = svm.OneClassSVM(nu=0.1, kernel="rbf", gamma=0.1)
clf.fit(X_train)
y_pred_train = clf.predict(X_train)
y_pred_test = clf.predict(X_test)
y_pred_outliers = clf.predict(X_outliers)
n_error_train = y_pred_train[y_pred_train == -1].size
n_error_test = y_pred_test[y_pred_test == -1].size
n_error_outliers = y_pred_outliers[y_pred_outliers == 1].size

# plot the line, the points, and the nearest vectors to the plane
Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
Z = Z.reshape(xx.shape)
plt.title("Novelty Detection")
plt.contourf(xx, yy, Z, levels=np.linspace(Z.min(), 0, 7), cmap=pl.cm.PuBu)
a = plt.contour(xx, yy, Z, levels=[0], linewidths=2, colors='darkred')
plt.contourf(xx, yy, Z, levels=[0, Z.max()], colors='palevioletred')
s = 40
b1 = plt.scatter(X_train[:, 0], X_train[:, 1], c='white', s=s, edgecolors='k')
b2 = plt.scatter(X_test[:, 0], X_test[:, 1], c='blueviolet', s=s,
edgecolors='k')
c = plt.scatter(X_outliers[:, 0], X_outliers[:, 1], c='gold', s=s,
edgecolors='k')
plt.axis('tight')
plt.xlim((-5, 5))
plt.ylim((-5, 5))
plt.legend([a.collections[0], b1, b2, c],
    ["learned frontier", "training observations",
     "new regular observations", "new abnormal observations"],
    loc="upper left",
    prop=matplotlib.font_manager.FontProperties(size=11))
plt.xlabel("error train: %d/200 ; errors novel regular: %d/40 ; "
    "errors novel abnormal: %d/40"
    % (n_error_train, n_error_test, n_error_outliers))
plt.show()

Total running time of the script: ( 0 minutes 0.665 seconds)

6.29.13 Plot different SVM classifiers in the iris dataset

Comparison of different linear SVM classifiers on a 2D projection of the iris dataset. We only consider the first 2 features of this dataset:

- Sepal length
- Sepal width

This example shows how to plot the decision surface for four SVM classifiers with different kernels.

The linear models LinearSVC() and SVC(kernel='linear') yield slightly different decision boundaries. This can be a consequence of the following differences:

- LinearSVC minimizes the squared hinge loss while SVC minimizes the regular hinge loss.
• **LinearSVC** uses the One-vs-All (also known as One-vs-Rest) multiclass reduction while **SVC** uses the One-vs-One multiclass reduction.

Both linear models have linear decision boundaries (intersecting hyperplanes) while the non-linear kernel models (polynomial or Gaussian RBF) have more flexible non-linear decision boundaries with shapes that depend on the kind of kernel and its parameters.

**Note:** while plotting the decision function of classifiers for toy 2D datasets can help get an intuitive understanding of their respective expressive power, be aware that those intuitions don’t always generalize to more realistic high-dimensional problems.

```python
print(__doc__)
import numpy as np
import matplotlib.pyplot as plt
from sklearn import svm, datasets
def make_meshgrid(x, y, h=.02):
    """Create a mesh of points to plot in

    Parameters
    ----------
    x: data to base x-axis meshgrid on
    y: data to base y-axis meshgrid on
    h: stepsize for meshgrid, optional
    """
    x_min, x_max = x.min() - .5, x.max() + .5
    y_min, y_max = y.min() - .5, y.max() + .5
    xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                         np.arange(y_min, y_max, h))
    return xx, yy
```
y: data to base y-axis meshgrid on
h: stepsize for meshgrid, optional

Returns
-------
xx, yy : ndarray

```
x_min, x_max = x.min() - 1, x.max() + 1
y_min, y_max = y.min() - 1, y.max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))
return xx, yy
```

def plot_contours(ax, clf, xx, yy, **params):
    """Plot the decision boundaries for a classifier.

    Parameters
    ----------
    ax: matplotlib axes object
    clf: a classifier
    xx: meshgrid ndarray
    yy: meshgrid ndarray
    params: dictionary of params to pass to contourf, optional
    ""
    Z = clf.predict(np.c_[xx.ravel(), yy.ravel()])
    Z = Z.reshape(xx.shape)
    out = ax.contourf(xx, yy, Z, **params)
    return out

# import some data to play with
iris = datasets.load_iris()
# Take the first two features. We could avoid this by using a two-dim dataset
X = iris.data[:, :2]
y = iris.target

# we create an instance of SVM and fit out data. We do not scale our
# data since we want to plot the support vectors
C = 1.0  # SVM regularization parameter
models = (svm.SVC(kernel='linear', C=C),
          svm.LinearSVC(C=C, max_iter=10000),
          svm.SVC(kernel='rbf', gamma=0.7, C=C),
          svm.SVC(kernel='poly', degree=3, gamma='auto', C=C))
models = (clf.fit(X, y) for clf in models)

# title for the plots
titles = ('SVC with linear kernel',
          'LinearSVC (linear kernel)',
          'SVC with RBF kernel',
          'SVC with polynomial (degree 3) kernel')

# Set-up 2x2 grid for plotting.
fig, sub = plt.subplots(2, 2)
plt.subplots_adjust(wspace=0.4, hspace=0.4)
X0, X1 = X[:, 0], X[:, 1]
import numpy as np

xx, yy = make_meshgrid(X0, X1)

for clf, title, ax in zip(models, titles, sub.flatten):
    plot_contours(ax, clf, xx, yy,
                   cmap=plt.cm.coolwarm, alpha=0.8)
    ax.scatter(X0, X1, c=y, cmap=plt.cm.coolwarm, s=20, edgecolors='k')
    ax.set_xlim(xx.min(), xx.max())
    ax.set_ylim(yy.min(), yy.max())
    ax.set_xlabel('Sepal length')
    ax.set_ylabel('Sepal width')
    ax.set_xticks(())
    ax.set_yticks(())
    ax.set_title(title)
plt.show()

Total running time of the script: (0 minutes 0.933 seconds)

6.29.14 Scaling the regularization parameter for SVCs

The following example illustrates the effect of scaling the regularization parameter when using Support Vector Machines for classification. For SVC classification, we are interested in a risk minimization for the equation:

\[
C \sum_{i=1,n} \mathcal{L}(f(x_i), y_i) + \Omega(w)
\]

where

- \(C\) is used to set the amount of regularization
- \(\mathcal{L}\) is a loss function of our samples and our model parameters.
- \(\Omega\) is a penalty function of our model parameters

If we consider the loss function to be the individual error per sample, then the data-fit term, or the sum of the error for each sample, will increase as we add more samples. The penalization term, however, will not increase.

When using, for example, cross validation, to set the amount of regularization with \(C\), there will be a different amount of samples between the main problem and the smaller problems within the folds of the cross validation.

Since our loss function is dependent on the amount of samples, the latter will influence the selected value of \(C\). The question that arises is How do we optimally adjust \(C\) to account for the different amount of training samples?

The figures below are used to illustrate the effect of scaling our \(C\) to compensate for the change in the number of samples, in the case of using an l1 penalty, as well as the l2 penalty.

**l1-penalty case**

In the l1 case, theory says that prediction consistency (i.e. that under given hypothesis, the estimator learned predicts as well as a model knowing the true distribution) is not possible because of the bias of the l1. It does say, however, that model consistency, in terms of finding the right set of non-zero parameters as well as their signs, can be achieved by scaling C1.
**l2-penalty case**

The theory says that in order to achieve prediction consistency, the penalty parameter should be kept constant as the number of samples grow.

**Simulations**

The two figures below plot the values of $C$ on the $x$-axis and the corresponding cross-validation scores on the $y$-axis, for several different fractions of a generated data-set.

In the l1 penalty case, the cross-validation-error correlates best with the test-error, when scaling our $C$ with the number of samples, $n$, which can be seen in the first figure.

For the l2 penalty case, the best result comes from the case where $C$ is not scaled.

<table>
<thead>
<tr>
<th>Note:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Two separate datasets are used for the two different plots. The reason behind this is the l1 case works better on sparse data, while l2 is better suited to the non-sparse case.</td>
</tr>
</tbody>
</table>
scikit-learn user guide, Release 0.24.0

6.29. Support Vector Machines

- [Graph 1]: Scaling=No scaling, penalty=l1, loss=squared_hinge
  - CV Score vs. C

- [Graph 2]: Scaling=1/n_samples, penalty=l1, loss=squared_hinge
  - CV Score vs. C
  - Lines for fraction 0.70, fraction 0.50, and fraction 0.30
import numpy as np
import matplotlib.pyplot as plt
from sklearn.svm import LinearSVC
```python
from sklearn.model_selection import ShuffleSplit
from sklearn.model_selection import GridSearchCV
from sklearn.utils import check_random_state
from sklearn import datasets

rnd = check_random_state(1)

# set up dataset
n_samples = 100
n_features = 300

# 11 data (only 5 informative features)
X_1, y_1 = datasets.make_classification(n_samples=n_samples,
                                        n_features=n_features,
                                        n_informative=5,
                                        random_state=1)

# 12 data: non sparse, but less features
y_2 = np.sign(.5 - rnd.rand(n_samples))
X_2 = rnd.randn(n_samples, n_features // 5) + y_2[:, np.newaxis]
X_2 += 5 * rnd.randn(n_samples, n_features // 5)

clf_sets = [(LinearSVC(penalty='l1', loss='squared_hinge',
                      dual=False,
                      tol=1e-3),
             np.logspace(-2.3, -1.3, 10), X_1, y_1),
             (LinearSVC(penalty='l2', loss='squared_hinge',
                        dual=True),
             np.logspace(-4.5, -2, 10), X_2, y_2)]

colors = ['navy', 'cyan', 'darkorange']
lw = 2

for clf, cs, X, y in clf_sets:
    # set up the plot for each regressor
    fig, axes = plt.subplots(nrows=2, sharey=True, figsize=(9, 10))
    for k, train_size in enumerate(np.linspace(0.3, 0.7, 3)[::-1]):
        param_grid = dict(C=cs)
        # To get nice curve, we need a large number of iterations to
        # reduce the variance
        grid = GridSearchCV(clf, refit=False, param_grid=param_grid,
         cv=ShuffleSplit(train_size=train_size,
                        test_size=.3,
                        n_splits=250, random_state=1))

        grid.fit(X, y)
        scores = grid.cv_results_['mean_test_score']

        scales = [(1, 'No scaling'),
                  (n_samples * train_size, '1/n_samples')]

        for ax, (scaler, name) in zip(axes, scales):
            ax.set_xlabel('C')
            ax.set_ylabel('CV Score')
            grid_cs = cs * float(scaler)  # scale the C's
            ax.semilogx(grid_cs, scores, label="fraciton %2f" %
                         train_size, color=colors[k], lw=lw)
            ax.set_title('scaling=%s, penalty=%s, loss=%s' %
                         (name, clf.penalty, clf.loss))
```

(continues on next page)
6.29.15 RBF SVM parameters

This example illustrates the effect of the parameters $\gamma$ and $C$ of the Radial Basis Function (RBF) kernel SVM.

Intuitively, the $\gamma$ parameter defines how far the influence of a single training example reaches, with low values meaning ‘far’ and high values meaning ‘close’. The $\gamma$ parameters can be seen as the inverse of the radius of influence of samples selected by the model as support vectors.

The $C$ parameter trades off correct classification of training examples against maximization of the decision function’s margin. For larger values of $C$, a smaller margin will be accepted if the decision function is better at classifying all training points correctly. A lower $C$ will encourage a larger margin, therefore a simpler decision function, at the cost of training accuracy. In other words $C$ behaves as a regularization parameter in the SVM.

The first plot is a visualization of the decision function for a variety of parameter values on a simplified classification problem involving only 2 input features and 2 possible target classes (binary classification). Note that this kind of plot is not possible to do for problems with more features or target classes.

The second plot is a heatmap of the classifier’s cross-validation accuracy as a function of $C$ and $\gamma$. For this example we explore a relatively large grid for illustration purposes. In practice, a logarithmic grid from $10^{-3}$ to $10^3$ is usually sufficient. If the best parameters lie on the boundaries of the grid, it can be extended in that direction in a subsequent search.

Note that the heat map plot has a special colorbar with a midpoint value close to the score values of the best performing models so as to make it easy to tell them apart in the blink of an eye.

The behavior of the model is very sensitive to the $\gamma$ parameter. If $\gamma$ is too large, the radius of the area of influence of the support vectors only includes the support vector itself and no amount of regularization with $C$ will be able to prevent overfitting.

When $\gamma$ is very small, the model is too constrained and cannot capture the complexity or “shape” of the data. The region of influence of any selected support vector would include the whole training set. The resulting model will behave similarly to a linear model with a set of hyperplanes that separate the centers of high density of any pair of two classes.

For intermediate values, we can see on the second plot that good models can be found on a diagonal of $C$ and $\gamma$. Smooth models (lower $\gamma$ values) can be made more complex by increasing the importance of classifying each point correctly (larger $C$ values) hence the diagonal of good performing models.

Finally, one can also observe that for some intermediate values of $\gamma$ we get equally performing models when $C$ becomes very large. This suggests that the set of support vectors does not change anymore. The radius of the RBF kernel alone acts as a good structural regularizer. Increasing $C$ further doesn’t help, likely because there are no more training points in violation (inside the margin or wrongly classified), or at least no better solution can be found. Scores being equal, it may make sense to use the smaller $C$ values, since very high $C$ values typically increase fitting time.

On the other hand, lower $C$ values generally lead to more support vectors, which may increase prediction time. Therefore, lowering the value of $C$ involves a trade-off between fitting time and prediction time.

We should also note that small differences in scores results from the random splits of the cross-validation procedure. Those spurious variations can be smoothed out by increasing the number of CV iterations $n_{\text{samples}}$ at the expense of compute time. Increasing the value number of $C_{\text{range}}$ and $\gamma_{\text{range}}$ steps will increase the resolution of the hyper-parameter heat map.
The best parameters are {'C': 1.0, 'gamma': 0.1} with a score of 0.97

Out:

```python
plt.pcolormesh(xx, yy, -Z, cmap=plt.cm.RdBu)
```

(continues on next page)
print(__doc__)  

import numpy as np  
import matplotlib.pyplot as plt  
from matplotlib.colors import Normalize  

from sklearn import SVC  
from sklearn.preprocessing import StandardScaler  
from sklearn.datasets import load_iris  
from sklearn.model_selection import StratifiedShuffleSplit  
from sklearn.model_selection import GridSearchCV  

# Utility function to move the midpoint of a colormap to be around  
# the values of interest.  

class MidpointNormalize(Normalize): 
    def __init__(self, vmin=None, vmax=None, midpoint=None, clip=False): 
        self.midpoint = midpoint  

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Normalize.__init__(self, vmin, vmax, clip)

def __call__(self, value, clip=None):
    x, y = [self.vmin, self.midpoint, self.vmax], [0, 0.5, 1]
    return np.ma.masked_array(np.interp(value, x, y))

# Load and prepare data set
# dataset for grid search
iris = load_iris()
X = iris.data
y = iris.target

# Dataset for decision function visualization: we only keep the first two
# features in X and sub-sample the dataset to keep only 2 classes and
# make it a binary classification problem.

X_2d = X[:, :2]
X_2d = X_2d[y > 0]
y_2d = y[y > 0]
y_2d -= 1

# It is usually a good idea to scale the data for SVM training.
# We are cheating a bit in this example in scaling all of the data,
# instead of fitting the transformation on the training set and
# just applying it on the test set.

scaler = StandardScaler()
X = scaler.fit_transform(X)
X_2d = scaler.fit_transform(X_2d)

# Train classifiers

# For an initial search, a logarithmic grid with basis
# 10 is often helpful. Using a basis of 2, a finer
# tuning can be achieved but at a much higher cost.

C_range = np.logspace(-2, 10, 13)
gamma_range = np.logspace(-9, 3, 13)
param_grid = dict(gamma=gamma_range, C=C_range)
cv = StratifiedShuffleSplit(n_splits=5, test_size=0.2, random_state=42)
grid = GridSearchCV(SVC(), param_grid=param_grid, cv=cv)
grid.fit(X, y)

print("The best parameters are %s with a score of %0.2f" %
      (grid.best_params_, grid.best_score_))

# Now we need to fit a classifier for all parameters in the 2d version
# (we use a smaller set of parameters here because it takes a while to train)

C_2d_range = [1e-2, 1, 1e2]
gamma_2d_range = [1e-1, 1, 1e1]
classifiers = []
for C in C_2d_range:
(continues on next page)
for gamma in gamma_2d_range:
    clf = SVC(C=C, gamma=gamma)
    clf.fit(X_2d, y_2d)
    classifiers.append((C, gamma, clf))

# Visualization

def draw_visualization_of_parameter_effects:
    for k, (C, gamma, clf) in enumerate(classifiers):
        Z = clf.decision_function(np.c_[xx.ravel(), yy.ravel()])
        Z = Z.reshape(xx.shape)
        plt.subplot(len(C_range), len(gamma_range), k + 1)
        plt.title("gamma=10^\%d, C=10^\%d" % (np.log10(gamma), np.log10(C)),
                  size='medium')
        plt.pcolormesh(xx, yy, -Z, cmap=plt.cm.RdBu)
        plt.scatter(X_2d[:, 0], X_2d[:, 1], c=y_2d, cmap=plt.cm.RdBu_r,
                    edgecolors='k')
        plt.xticks(())
        plt.yticks(())
        plt.axis('tight')

scores = grid.cv_results_['mean_test_score'].reshape(len(C_range),
                                                     len(gamma_range))

# Draw heatmap of the validation accuracy as a function of gamma and C

def draw_heatmap_of_validation_accuracy(gamma, C):
    scores = grid.cv_results_['mean_test_score']
    scores = scores.reshape(len(C_range), len(gamma_range))
    plt.figure(figsize=(8, 6))
    plt.imshow(scores, interpolation='nearest', cmap=plt.cm.hot,
               norm=MidpointNormalize(vmin=0.2, midpoint=0.92))
    plt.xlabel('gamma')
    plt.ylabel('C')
    plt.colorbar()
    plt.xticks(np.arange(len(gamma_range)), gamma_range, rotation=45)
    plt.yticks(np.arange(len(C_range)), C_range)
    plt.title('Validation accuracy')
    plt.show()
### 6.30 Tutorial exercises

Exercises for the tutorials

#### 6.30.1 Digits Classification Exercise

A tutorial exercise regarding the use of classification techniques on the Digits dataset.

This exercise is used in the Classification part of the Supervised learning: predicting an output variable from high-dimensional observations section of the A tutorial on statistical-learning for scientific data processing.

Out:

```
KNN score: 0.961111
LogisticRegression score: 0.933333
```

```python
print(__doc__)
from sklearn import datasets, neighbors, linear_model
X_digits, y_digits = datasets.load_digits(return_X_y=True)
X_digits = X_digits / X_digits.max()
n_samples = len(X_digits)
X_train = X_digits[:int(.9 * n_samples)]
y_train = y_digits[:int(.9 * n_samples)]
X_test = X_digits[int(.9 * n_samples):]
y_test = y_digits[int(.9 * n_samples):]

knn = neighbors.KNeighborsClassifier()
logistic = linear_model.LogisticRegression(max_iter=1000)

print('KNN score: %f' % knn.fit(X_train, y_train).score(X_test, y_test))
print('LogisticRegression score: %f' % logistic.fit(X_train, y_train).score(X_test, y_test))
```

Total running time of the script: ( 0 minutes 0.261 seconds)

#### 6.30.2 Cross-validation on Digits Dataset Exercise

A tutorial exercise using Cross-validation with an SVM on the Digits dataset.

This exercise is used in the Cross-validation generators part of the Model selection: choosing estimators and their parameters section of the A tutorial on statistical-learning for scientific data processing.
```
import numpy as np
from sklearn.model_selection import cross_val_score
from sklearn.datasets, svm
X, y = datasets.load_digits(return_X_y=True)
svc = svm.SVC(kernel='linear')
C_s = np.logspace(-10, 0, 10)
scores = list()
scores_std = list()
for C in C_s:
    svc.C = C
    this_scores = cross_val_score(svc, X, y, n_jobs=1)
    scores.append(np.mean(this_scores))
    scores_std.append(np.std(this_scores))

# Do the plotting
import matplotlib.pyplot as plt
plt.figure()
plt.semilogx(C_s, scores)
plt.semilogx(C_s, np.array(scores) + np.array(scores_std), 'b--')
```
6.30.3 SVM Exercise

A tutorial exercise for using different SVM kernels.

This exercise is used in the Using kernels part of the Supervised learning: predicting an output variable from high-dimensional observations section of the A tutorial on statistical-learning for scientific data processing.
Out:

```
/home/circleci/project/examples/exercises/plot_iris_exercise.py:62:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
    as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
    with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
    'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
/home/circleci/project/examples/exercises/plot_iris_exercise.py:62:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
    as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
    with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
    'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
/home/circleci/project/examples/exercises/plot_iris_exercise.py:62:
  MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions
    as C is deprecated since 3.3. Either specify the corners of the quadrilaterals
    with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams[
    'pcolor.shading']. This will become an error two minor releases later.
  plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
```
```python
print(__doc__)

import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets, svm

iris = datasets.load_iris()
X = iris.data
y = iris.target
X = X[y != 0, :2]
y = y[y != 0]
n_sample = len(X)

np.random.seed(0)
order = np.random.permutation(n_sample)
X = X[order]
y = y[order].astype(float)

X_train = X[:int(.9 * n_sample)]
y_train = y[:int(.9 * n_sample)]
X_test = X[int(.9 * n_sample):]
y_test = y[int(.9 * n_sample):]

# fit the model
for kernel in ('linear', 'rbf', 'poly'):
    clf = svm.SVC(kernel=kernel, gamma=10)
    clf.fit(X_train, y_train)
    plt.figure()
    plt.clf()
    plt.scatter(X[:, 0], X[:, 1], c=y, zorder=10, cmap=plt.cm.Paired,
                edgecolor='k', s=20)
    # Circle out the test data
    plt.scatter(X_test[:, 0], X_test[:, 1], s=80, facecolors='none',
                zorder=10, edgecolor='k')
    plt.axis('tight')
    x_min = X[:, 0].min()
    x_max = X[:, 0].max()
    y_min = X[:, 1].min()
    y_max = X[:, 1].max()

    XX, YY = np.mgrid[x_min:x_max:200j, y_min:y_max:200j]
    Z = clf.decision_function(np.c_[XX.ravel(), YY.ravel()])

    # Put the result into a color plot
    Z = Z.reshape(XX.shape)
    plt.pcolormesh(XX, YY, Z > 0, cmap=plt.cm.Paired)
    plt.contour(XX, YY, Z, colors=['k', 'k', 'k'],
                linestyles=['--', '-', '--'], levels=[-.5, 0, .5])
    plt.title(kernel)
    plt.show()
```

6.30. Tutorial exercises
6.30.4 Cross-validation on diabetes Dataset Exercise

A tutorial exercise which uses cross-validation with linear models.

This exercise is used in the Cross-validated estimators part of the Model selection: choosing estimators and their parameters section of the A tutorial on statistical-learning for scientific data processing.

Out:

Answer to the bonus question: how much can you trust the selection of alpha?

Alpha parameters maximising the generalization score on different subsets of the data:
[fold 0] alpha: 0.05968, score: 0.54209
[fold 1] alpha: 0.04520, score: 0.15523
[fold 2] alpha: 0.07880, score: 0.45193

Answer: Not very much since we obtained different alphas for different subsets of the data and moreover, the scores for these alphas differ quite substantially.
```python
import numpy as np
import matplotlib.pyplot as plt

from sklearn import datasets
from sklearn.linear_model import LassoCV
from sklearn.linear_model import Lasso
from sklearn.model_selection import KFold
from sklearn.model_selection import GridSearchCV

X, y = datasets.load_diabetes(return_X_y=True)
X = X[:150]
y = y[:150]

lasso = Lasso(random_state=0, max_iter=10000)
alphas = np.logspace(-4, -0.5, 30)
tuned_parameters = [{'alpha': alphas}]
n_folds = 5

clf = GridSearchCV(lasso, tuned_parameters, cv=n_folds, refit=False)
clf.fit(X, y)
scores = clf.cv_results_['mean_test_score']
scores_std = clf.cv_results_['std_test_score']
plt.figure().set_size_inches(8, 6)
plt.semilogx(alphas, scores)
# plot error lines showing +/- std. errors of the scores
std_error = scores_std / np.sqrt(n_folds)
plt.semilogx(alphas, scores + std_error, 'b--')
plt.semilogx(alphas, scores - std_error, 'b--')
plt.fill_between(alphas, scores + std_error, scores - std_error, alpha=0.2)
plt.ylabel('CV score +/- std error')
plt.xlabel('alpha')
plt.axhline(np.max(scores), linestyle='--', color='.5')
plt.xlim([alphas[0], alphas[-1]])

# Bonus: how much can you trust the selection of alpha?

# To answer this question we use the LassoCV object that sets its alpha
# parameter automatically from the data by internal cross-validation (i.e. it
# performs cross-validation on the training data it receives).
# We use external cross-validation to see how much the automatically obtained
# alphas differ across different cross-validation folds.
lasso_cv = LassoCV(alphas=alphas, random_state=0, max_iter=10000)
k_fold = KFold(3)

print("Answer to the bonus question:",
      "how much can you trust the selection of alpha?")
print()
print("Alpha parameters maximising the generalization score on different")
```
print("subsets of the data:")
for k, (train, test) in enumerate(k_fold.split(X, y)):
    lasso_cv.fit(X[train], y[train])
    print("[fold {0}] alpha: {1:.5f}, score: {2:.5f}".
          format(k, lasso_cv.alpha_, lasso_cv.score(X[test], y[test])))
print()
print("Answer: Not very much since we obtained different alphas for different")
print("subsets of the data and moreover, the scores for these alphas differ")
print("quite substantially.")
plt.show()

Total running time of the script: ( 0 minutes 0.511 seconds)

6.31 Working with text documents

Examples concerning the sklearn.feature_extraction.text module.

6.31.1 FeatureHasher and DictVectorizer Comparison

Compares FeatureHasher and DictVectorizer by using both to vectorize text documents.
The example demonstrates syntax and speed only; it doesn’t actually do anything useful with the extracted vectors.
See the example scripts {document_classification_20newsgroups,clustering}.py for actual learning on text documents.
A discrepancy between the number of terms reported for DictVectorizer and for FeatureHasher is to be expected due
to hash collisions.

Out:

Usage: /home/circleci/project/examples/text/plot_hashing_vs_dict_vectorizer.py [n_features_for_hashing]
The default number of features is 2**18.

Loading 20 newsgroups training data
3803 documents - 6.245MB

DictVectorizer
done in 1.146081s at 5.449MB/s
Found 47928 unique terms

FeatureHasher on frequency dicts
done in 0.616743s at 10.125MB/s
Found 43873 unique terms

FeatureHasher on raw tokens
done in 0.590155s at 10.582MB/s
Found 43873 unique terms
from collections import defaultdict
import re
import sys
from time import time
import numpy as np
from sklearn.datasets import fetch_20newsgroups
from sklearn.feature_extraction import DictVectorizer, FeatureHasher

def n_nonzero_columns(X):
    # Returns the number of non-zero columns in a CSR matrix X.
    return len(np.unique(X.nonzero()[1]))

def tokens(doc):
    # Extract tokens from doc.
    # This uses a simple regex to break strings into tokens. For a more
    # principled approach, see CountVectorizer or TfidfVectorizer.
    return (tok.lower() for tok in re.findall(r"\w+", doc))

def token_freqs(doc):
    # Extract a dict mapping tokens from doc to their frequencies.
    freq = defaultdict(int)
    for tok in tokens(doc):
        freq[tok] += 1
    return freq

categories = [
    'alt.atheism',
    'comp.graphics',
    'comp.sys.ibm.pc.hardware',
    'misc.forsale',
    'rec.autos',
    'sci.space',
    'talk.religion.misc',
]

# Uncomment the following line to use a larger set (11k+ documents)
# categories = None

print(__doc__)
print("Usage: %s [n_features_for_hashing]" % sys.argv[0])
print(" The default number of features is 2**18.")

try:
    n_features = int(sys.argv[1])
except IndexError:
    n_features = 2 ** 18
except ValueError:
print("not a valid number of features: \$r" % sys.argv[1])
sys.exit(1)

print("Loading 20 newsgroups training data")
raw_data, _ = fetch_20newsgroups(subset='train', categories=categories,
return_X_y=True)
data_size_mb = sum(len(s.encode('utf-8')) for s in raw_data) / 1e6
print("%d documents - %0.3f MB" % (len(raw_data), data_size_mb))
print()

print("DictVectorizer")
t0 = time()
vectorizer = DictVectorizer()
vectorizer.fit_transform(token_freqs(d) for d in raw_data)
duration = time() - t0
print("done in \$fs at \$0.3fMB/s" % (duration, data_size_mb / duration))
print("Found \$d unique terms" % len(vectorizer.get_feature_names()))
print()

print("FeatureHasher on frequency dicts")
t0 = time()
hasher = FeatureHasher(n_features=n_features)
X = hasher.transform(token_freqs(d) for d in raw_data)
duration = time() - t0
print("done in \$fs at \$0.3fMB/s" % (duration, data_size_mb / duration))
print("Found \$d unique terms" % n_nonzero_columns(X))
print()

print("FeatureHasher on raw tokens")
t0 = time()
hasher = FeatureHasher(n_features=n_features, input_type="string")
X = hasher.transform(tokens(d) for d in raw_data)
duration = time() - t0
print("done in \$fs at \$0.3fMB/s" % (duration, data_size_mb / duration))
print("Found \$d unique terms" % n_nonzero_columns(X))

Total running time of the script: ( 0 minutes 2.626 seconds)

6.31.2 Clustering text documents using k-means

This is an example showing how the scikit-learn can be used to cluster documents by topics using a bag-of-words approach. This example uses a scipy.sparse matrix to store the features instead of standard numpy arrays.

Two feature extraction methods can be used in this example:

- TfidfVectorizer uses a in-memory vocabulary (a python dict) to map the most frequent words to features indices and hence compute a word occurrence frequency (sparse) matrix. The word frequencies are then reweighted using the Inverse Document Frequency (IDF) vector collected feature-wise over the corpus.

- HashingVectorizer hashes word occurrences to a fixed dimensional space, possibly with collisions. The word count vectors are then normalized to each have l2-norm equal to one (projected to the euclidean unit-ball) which seems to be important for k-means to work in high dimensional space.

HashingVectorizer does not provide IDF weighting as this is a stateless model (the fit method does nothing). When IDF weighting is needed it can be added by pipelining its output to a TfidfTransformer instance.
Two algorithms are demoed: ordinary k-means and its more scalable cousin minibatch k-means. Additionally, latent semantic analysis can also be used to reduce dimensionality and discover latent patterns in the data.

It can be noted that k-means (and minibatch k-means) are very sensitive to feature scaling and that in this case the IDF weighting helps improve the quality of the clustering by quite a lot as measured against the “ground truth” provided by the class label assignments of the 20 newsgroups dataset.

This improvement is not visible in the Silhouette Coefficient which is small for both as this measure seem to suffer from the phenomenon called “Concentration of Measure” or “Curse of Dimensionality” for high dimensional datasets such as text data. Other measures such as V-measure and Adjusted Rand Index are information theoretic based evaluation scores: as they are only based on cluster assignments rather than distances, hence not affected by the curse of dimensionality.

Note: as k-means is optimizing a non-convex objective function, it will likely end up in a local optimum. Several runs with independent random init might be necessary to get a good convergence.

```
Usage: plot_document_clustering.py [options]
Options:
  -h, --help            show this help message and exit
  --lsa=N_COMPONENTS    Preprocess documents with latent semantic analysis.
  --no-minibatch       Use ordinary k-means algorithm (in batch mode).
  --no-idf             Disable Inverse Document Frequency feature weighting.
  --use-hashing        Use a hashing feature vectorizer
  --n-features=N_FEATURES   Maximum number of features (dimensions) to extract
                           from text.
  --verbose            Print progress reports inside k-means algorithm.

Loading 20 newsgroups dataset for categories:
['alt.atheism', 'talk.religion.misc', 'comp.graphics', 'sci.space']
3387 documents
4 categories

Extracting features from the training dataset using a sparse vectorizer
done in 0.698812s
n_samples: 3387, n_features: 10000

Clustering sparse data with MiniBatchKMeans(batch_size=1000, init_size=1000, n_
  --clusters=4, n_init=1,   verbose=False)
done in 0.062s

Homogeneity: 0.219
Completeness: 0.338
V-measure: 0.266
Adjusted Rand-Index: 0.113
Silhouette Coefficient: 0.005

Top terms per cluster:
Cluster 0: cc ibm au buffalo monash com vnet software nicho university
Cluster 1: space nasa henry access digex toronto gov pat alaska shuttle
Cluster 2: com god university article don know graphics people posting like
Cluster 3: sgi keith livesey morality jon solntze wpd caltech objective moral
```
import logging
from optparse import OptionParser
import sys
from time import time
import numpy as np

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO,
                    format='%(asctime)s %(levelname)s %(message)s')

# parse commandline arguments
op = OptionParser()
opt.add_option("--lsa",
               dest="n_components", type="int",
               help="Preprocess documents with latent semantic analysis.")
opt.add_option("--no-minibatch",
               action="store_false", dest="minibatch", default=True,
               help="Use ordinary k-means algorithm (in batch mode).")
opt.add_option("--no-idf",
               action="store_false", dest="use_idf", default=True,
               help="Disable Inverse Document Frequency feature weighting.")
opt.add_option("--use-hashing",
               action="store_true", default=False,
               help="Use a hashing feature vectorizer")
opt.add_option("--n-features", type=int, default=10000,
               help="Maximum number of features (dimensions"
               " to extract from text.")
opt.add_option("--verbose",
               action="store_true", dest="verbose", default=False,
               help="Print progress reports inside k-means algorithm.")

print(__doc__)
op.print_help()

def is_interactive():
    return not hasattr(sys.modules['__main__'], '__file__')
# work-around for Jupyter notebook and IPython console
argv = [] if is_interactive() else sys.argv[1:]
(opts, args) = op.parse_args(argv)
if len(args) > 0:
    op.error("this script takes no arguments.")
sys.exit(1)

# Load some categories from the training set
categories = ['alt.atheism',
              'talk.religion.misc',
              'comp.graphics',
              'sci.space',
          ]
# Uncomment the following to do the analysis on all the categories
# categories = None
print("Loading 20 newsgroups dataset for categories:")
print(categories)
dataset = fetch_20newsgroups(subset='all', categories=categories,
                               shuffle=True, random_state=42)
print("%d documents" % len(dataset.data))
print("%d categories" % len(dataset.target_names))
print()
labels = dataset.target
true_k = np.unique(labels).shape[0]
print("Extracting features from the training dataset "
      "using a sparse vectorizer")
t0 = time()
if opts.use_hashing:
    if opts.use_idf:
        # Perform an IDF normalization on the output of HashingVectorizer
        hasher = HashingVectorizer(n_features=opts.n_features,
                                    stop_words='english',
                                    alternate_sign=False,
                                    norm=None)
        vectorizer = make_pipeline(hasher, TfidfTransformer())
    else:
        vectorizer = HashingVectorizer(n_features=opts.n_features,
                                        stop_words='english',
                                        alternate_sign=False, norm='l2')
else:
        vectorizer = TfidfVectorizer(max_df=0.5, max_features=opts.n_features,
                                      min_df=2, stop_words='english',
                                      use_idf=opts.use_idf)
X = vectorizer.fit_transform(dataset.data)
print("done in $fs" % (time() - t0))
print("n_samples: $d, n_features: $d" % X.shape)
print()
if opts.n_components:
    print("Performing dimensionality reduction using LSA")
    t0 = time()
    # Vectorizer results are normalized, which makes KMeans behave as  
    # spherical k-means for better results. Since LSA/SVD results are  
    # not normalized, we have to redo the normalization.
    svd = TruncatedSVD(opts.n_components)
    normalizer = Normalizer(copy=False)
    lsa = make_pipeline(svd, normalizer)
    X = lsa.fit_transform(X)
    print("done in %fs % (time() - t0))

    explained_variance = svd.explained_variance_ratio_.sum()
    print("Explained variance of the SVD step: %%.3f")%".format( 
        int(explained_variance * 100))
    print()

    # Do the actual clustering
    if opts.minibatch:
        km = MiniBatchKMeans(n_clusters=true_k, init='k-means++', n_init=1, 
                             init_size=1000, batch_size=1000, verbose=opts.verbose)
    else:
        km = KMeans(n_clusters=true_k, init='k-means++', max_iter=100, n_init=1, 
                    verbose=opts.verbose)
    print("Clustering sparse data with %s" % km)
    t0 = time()
    km.fit(X)
    print("done in %0.3fs" % (time() - t0))
    print()

    print("Homogeneity: %0.3f" % metrics.homogeneity_score(labels, km.labels_))
    print("Completeness: %0.3f" % metrics.completeness_score(labels, km.labels_))
    print("V-measure: %0.3f" % metrics.v_measure_score(labels, km.labels_))
    print("Adjusted Rand-Index: %0.3f" % metrics.adjusted_rand_score(labels, km.labels_))
    print("Silhouette Coefficient: %0.3f" % metrics.silhouette_score(X, km.labels_, sample_size=1000))
    print()

if not opts.use_hashing:
    print("Top terms per cluster:")

    if opts.n_components:
        original_space_centroids = svd.inverse_transform(km.cluster_centers_)
        order_centroids = original_space_centroids.argsort()[::-1]
    else:
        order_centroids = km.cluster_centers_.argsort()[::-1]
terms = vectorizer.get_feature_names()
for i in range(true_k):
    print("Cluster %d:" % i, end='')
    for ind in order_centroids[i, :10]:
        print(' %s' % terms[ind], end='')
    print()

Total running time of the script: ( 0 minutes 1.054 seconds)

6.31.3 Classification of text documents using sparse features

This is an example showing how scikit-learn can be used to classify documents by topics using a bag-of-words approach. This example uses a scipy.sparse matrix to store the features and demonstrates various classifiers that can efficiently handle sparse matrices.

The dataset used in this example is the 20 newsgroups dataset. It will be automatically downloaded, then cached.

# Author: Peter Prettenhofer <peter.prettenhofer@gmail.com>
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# Lars Buitinck
# License: BSD 3 clause
import logging
import numpy as np
from optparse import OptionParser
import sys
from time import time
import matplotlib.pyplot as plt
from sklearn.datasets import fetch_20newsgroups
from sklearn.feature_extraction.text import TfidfVectorizer
from sklearn.feature_extraction.text import HashingVectorizer
from sklearn.feature_selection import SelectFromModel
from sklearn.feature_selection import SelectKBest, chi2
from sklearn.linear_model import RidgeClassifier
from sklearn.pipeline import Pipeline
from sklearn.svm import LinearSVC
from sklearn.linear_model import SGDClassifier
from sklearn.linear_model import Perceptron
from sklearn.naive_bayes import PassiveAggressiveClassifier
from sklearn.naive_bayes import BernoulliNB, ComplementNB, MultinomialNB
from sklearn.neighbors import KNeighborsClassifier
from sklearn.neighbors import NearestCentroid
from sklearn.ensemble import RandomForestClassifier
from sklearn.utils.extmath import density
from sklearn import metrics

# Display progress logs on stdout
logging.basicConfig(level=logging.INFO,
                    format='%(asctime)s %(levelname)s %(message)s')

op = OptionParser()
op.add_option("--report",
    action="store_true", dest="print_report",
    )
help="Print a detailed classification report.")

op.add_option("--chi2_select",
    action="store", type="int", dest="select_chi2",
    help="Select some number of features using a chi-squared test")

op.add_option("--confusion_matrix",
    action="store_true", dest="print_cm",
    help="Print the confusion matrix.")

op.add_option("--top10",
    action="store_true", dest="print_top10",
    help="Print ten most discriminative terms per class for every classifier.")

op.add_option("--all_categories",
    action="store_true", dest="all_categories",
    help="Whether to use all categories or not.")

op.add_option("--use_hashing",
    action="store_true",
    help="Use a hashing vectorizer.")

op.add_option("--n_features",
    action="store", type=int, default=2 ** 16,
    help="n_features when using the hashing vectorizer.")

op.add_option("--filtered",
    action="store_true",
    help="Remove newsgroup information that is easily overfit: headers, signatures, and quoting.")


def is_interactive():
    return not hasattr(sys.modules['__main__'], '__file__')

argv = []
if is_interactive() else sys.argv[1:]
(opts, args) = op.parse_args(argv)

if len(args) > 0:
    op.error("this script takes no arguments.")
    sys.exit(1)

print(__doc__)
op.print_help()
print()

Out:

Usage: plot_document_classification_20newsgroups.py [options]

Options:
- h, --help         show this help message and exit
--report           Print a detailed classification report.
--chi2_select=SELECT_CHI2
    Select some number of features using a chi-squared test
--confusion_matrix  Print the confusion matrix.
--top10            Print ten most discriminative terms per class for every classifier.
--all_categories    Whether to use all categories or not.
--use_hashing      Use a hashing vectorizer.
--n_features=N_FEATURES
Load data from the training set

Let's load data from the newsgroups dataset which comprises around 18000 newsgroups posts on 20 topics split in two subsets: one for training (or development) and the other one for testing (or for performance evaluation).

```python
if opts.all_categories:
    categories = None
else:
    categories = ['alt.atheism',
                  'talk.religion.misc',
                  'comp.graphics',
                  'sci.space',
                 ]
if opts.filtered:
    remove = ('headers', 'footers', 'quotes')
else:
    remove = ()
print("Loading 20 newsgroups dataset for categories:")
print(categories if categories else "all")
data_train = fetch_20newsgroups(subset='train', categories=categories,
                                 shuffle=True, random_state=42,
                                 remove=remove)
data_test = fetch_20newsgroups(subset='test', categories=categories,
                                 shuffle=True, random_state=42,
                                 remove=remove)
print('data loaded')

# order of labels in `target_names` can be different from `categories`
target_names = data_train.target_names

def size_mb(docs):
    return sum(len(s.encode('utf-8')) for s in docs) / 1e6

data_train_size_mb = size_mb(data_train.data)
data_test_size_mb = size_mb(data_test.data)
print("%d documents - $0.3fMB (training set)" % (len(data_train.data), data_train_size_mb))
print("%d documents - $0.3fMB (test set)" % (len(data_test.data), data_test_size_mb))
print("%d categories" % len(target_names))
print()

# split a training set and a test set
```

(continues on next page)
y_train, y_test = data_train.target, data_test.target

print("Extracting features from the training data using a sparse vectorizer")
t0 = time()
if opts.use_hashing:
    vectorizer = HashingVectorizer(stop_words='english', alternate_sign=False,
                                   n_features=opts.n_features)
    X_train = vectorizer.transform(data_train.data)
else:
    vectorizer = TfidfVectorizer(sublinear_tf=True, max_df=0.5,
                                  stop_words='english')
    X_train = vectorizer.fit_transform(data_train.data)
duration = time() - t0
print("done in %fs at %0.3fMB/s" % (duration, data_train_size_mb / duration))
print("n_samples: %d, n_features: %d" % X_train.shape)
print()

print("Extracting features from the test data using the same vectorizer")
t0 = time()
X_test = vectorizer.transform(data_test.data)
duration = time() - t0
print("done in %fs at %0.3fMB/s" % (duration, data_test_size_mb / duration))
print("n_samples: %d, n_features: %d" % X_test.shape)
print()

# mapping from integer feature name to original token string
if opts.use_hashing:
    feature_names = None
else:
    feature_names = vectorizer.get_feature_names()

if opts.select_chi2:
    print("Extracting %d best features by a chi-squared test" %
          opts.select_chi2)
t0 = time()
ch2 = SelectKBest(chi2, k=opts.select_chi2)
X_train = ch2.fit_transform(X_train, y_train)
X_test = ch2.transform(X_test)
if feature_names:
    # keep selected feature names
    feature_names = [feature_names[i] for i
                     in ch2.get_support(indices=True)]
    print("done in %fs" % (time() - t0))
print()

if feature_names:
    feature_names = np.asarray(feature_names)

def trim(s):
    """Trim string to fit on terminal (assuming 80-column display)""
    return s if len(s) <= 80 else s[:77] + "...">

Out:
Loading 20 newsgroups dataset for categories:
['alt.atheism', 'talk.religion.misc', 'comp.graphics', 'sci.space']
data loaded
2034 documents - 3.980MB (training set)
1353 documents - 2.867MB (test set)
4 categories

Extracting features from the training data using a sparse vectorizer
done in 0.406298s at 9.795MB/s
n_samples: 2034, n_features: 33809

Extracting features from the test data using the same vectorizer
done in 0.250454s at 11.449MB/s
n_samples: 1353, n_features: 33809

Benchmark classifiers

We train and test the datasets with 15 different classification models and get performance results for each model.

```python
def benchmark(clf):
    print('_' * 80)
    print("Training: ")
    print(clf)
    t0 = time()
    clf.fit(X_train, y_train)
    train_time = time() - t0
    print("train time: %0.3fs" % train_time)
    t0 = time()
    pred = clf.predict(X_test)
    test_time = time() - t0
    print("test time: %0.3fs" % test_time)

    score = metrics.accuracy_score(y_test, pred)
    print("accuracy: %0.3f" % score)

    if hasattr(clf, 'coef_ '):
        print("dimensionality: %d" % clf.coef_.shape[1])
        print("density: %f" % density(clf.coef_))

        if opts.print_top10 and feature_names is not None:
            print("top 10 keywords per class:")
            for i, label in enumerate(target_names):
                top10 = np.argsort(clf.coef_[i])[-10:]
                print(trim("%s: %s" % (label, " ".join(feature_names[top10]))))
            print()

        if opts.print_report:
            print("classification report:")
            print(metrics.classification_report(y_test, pred,
                                                target_names=target_names))

        if opts.print_cm:
            print("confusion matrix:")
            print(metrics.confusion_matrix(y_test, pred))
    print()
```

(continues on next page)
clf_descr = str(clf).split('(')[0]
return clf_descr, score, train_time, test_time

results = []
for clf, name in [(RidgeClassifier(tol=1e-2, solver="sag"), "Ridge Classifier"),
    (Perceptron(max_iter=50), "Perceptron"),
    (PassiveAggressiveClassifier(max_iter=50), "Passive-Aggressive"),
    (KNeighborsClassifier(n_neighbors=10), "kNN"),
    (RandomForestClassifier(), "Random forest")):
    print('=' * 80)
    print(name)
    results.append(benchmark(clf))

for penalty in ["l2", "l1"]:  # Train Liblinear model
    print('=' * 80)
    print("%s penalty" % penalty.upper())
    results.append(benchmark(LinearSVC(penalty=penalty, dual=False, tol=1e-3)))

    # Train SGD model
    results.append(benchmark(SGDClassifier(alpha=.0001, max_iter=50, penalty=penalty)))

    # Train SGD with Elastic Net penalty
    print('=' * 80)
    print("Elastic-Net penalty")
    results.append(benchmark(SGDClassifier(alpha=.0001, max_iter=50, penalty="elasticnet")))

    # Train NearestCentroid without threshold
    print('=' * 80)
    print("NearestCentroid (aka Rocchio classifier)"
    results.append(benchmark(NearestCentroid()))

    # Train sparse Naive Bayes classifiers
    print('=' * 80)
    print("Naive Bayes")
    results.append(benchmark(MultinomialNB(alpha=.01)))
    results.append(benchmark(BernoulliNB(alpha=.01)))
    results.append(benchmark(ComplementNB(alpha=.1)))

    print('=' * 80)
    print("LinearSVC with L1-based feature selection")
    results.append(benchmark(Pipeline(["feature_selection", SelectFromModel(LinearSVC(penalty="l1", dual=False, tol=1e-3))],
                      "classification", LinearSVC(penalty="l2")))))

Out:
Ridge Classifier

Training:
RidgeClassifier(solver='sag', tol=0.01)
/home/circleci/project/sklearn/linear_model/_ridge.py:555: UserWarning: "sag" solver→requires many iterations to fit an intercept with sparse inputs. Either set the→solver to "auto" or "sparse_cg", or set a low "tol" and a high "max_iter"→(especially if inputs are not standardized).
warnings.warn(
train time: 0.160s
test time: 0.001s
accuracy: 0.897
dimensionality: 33809
density: 1.000000

Perceptron

Training:
Perceptron(max_iter=50)
train time: 0.017s
test time: 0.002s
accuracy: 0.888
dimensionality: 33809
density: 0.255302

Passive-Aggressive

Training:
PassiveAggressiveClassifier(max_iter=50)
train time: 0.033s
test time: 0.002s
accuracy: 0.902
dimensionality: 33809
density: 0.692841

kNN

Training:
KNeighborsClassifier(n_neighbors=10)
train time: 0.001s
test time: 0.156s
accuracy: 0.858

Random forest

Training:
RandomForestClassifier()
train time: 1.312s
test time: 0.072s

(continues on next page)
accuracy: 0.837

================================================================================
L2 penalty

Training:
LinearSVC(dual=False, tol=0.001)
train time: 0.075s
test time: 0.001s
accuracy: 0.900
dimensionality: 33809
density: 1.000000

Training:
SGDClassifier(max_iter=50)
train time: 0.021s
test time: 0.001s
accuracy: 0.899
dimensionality: 33809
density: 0.569944

================================================================================
L1 penalty

Training:
LinearSVC(dual=False, tol=0.001)
train time: 0.183s
test time: 0.001s
accuracy: 0.873
dimensionality: 33809
density: 0.005561

Training:
SGDClassifier(max_iter=50, penalty='l1')
train time: 0.086s
test time: 0.002s
accuracy: 0.888
dimensionality: 33809
density: 0.022982

================================================================================
Elastic-Net penalty

Training:
SGDClassifier(max_iter=50, penalty='elasticnet')
train time: 0.111s
test time: 0.002s
accuracy: 0.902
dimensionality: 33809
density: 0.187502

(continues on next page)
NearestCentroid (aka Rocchio classifier)

Training:
NearestCentroid()
train time: 0.004s
test time: 0.002s
accuracy: 0.855

Naive Bayes

Training:
MultinomialNB(alpha=0.01)
train time: 0.006s
test time: 0.001s
accuracy: 0.899

/home/circleci/project/sklearn/utils/deprecation.py:101: FutureWarning: Attribute
→coef_ was deprecated in version 0.24 and will be removed in 1.1 (renaming of 0.26).
warnings.warn(msg, category=FutureWarning)
dimensionality: 33809
density: 1.000000

Training:
BernoulliNB(alpha=0.01)
train time: 0.007s
test time: 0.005s
accuracy: 0.884

/home/circleci/project/sklearn/utils/deprecation.py:101: FutureWarning: Attribute
→coef_ was deprecated in version 0.24 and will be removed in 1.1 (renaming of 0.26).
warnings.warn(msg, category=FutureWarning)
dimensionality: 33809
density: 1.000000

Training:
ComplementNB(alpha=0.1)
train time: 0.006s
test time: 0.001s
accuracy: 0.911

/home/circleci/project/sklearn/utils/deprecation.py:101: FutureWarning: Attribute
→coef_ was deprecated in version 0.24 and will be removed in 1.1 (renaming of 0.26).
warnings.warn(msg, category=FutureWarning)
dimensionality: 33809
density: 1.000000

LinearSVC with L1-based feature selection

Training:
Pipeline(steps=[('feature_selection',
    SelectFromModel(estimator=LinearSVC(dual=False, penalty='l1'),
    'Feature selector'),
    'classifier',
    LinearSVC(dual=False, penalty='l1')),
Add plots

The bar plot indicates the accuracy, training time (normalized) and test time (normalized) of each classifier.

```python
indices = np.arange(len(results))
results = [[x[i] for x in results] for i in range(4)]
clf_names, score, training_time, test_time = results
training_time = np.array(training_time) / np.max(training_time)
test_time = np.array(test_time) / np.max(test_time)

plt.figure(figsize=(12, 8))
plt.title("Score")
plt.barh(indices, score, .2, label="score", color='navy')
plt.barh(indices + .3, training_time, .2, label="training time",
         color='c')
plt.barh(indices + .6, test_time, .2, label="test time", color='darkorange')
plt.yticks(()
plt.legend(loc='best')
plt.subplots_adjust(left=.25)
plt.subplots_adjust(top=.95)
plt.subplots_adjust(bottom=.05)

for i, c in zip(indices, clf_names):
    plt.text(-.3, i, c)

plt.show()
```
Total running time of the script: 0 minutes 3.743 seconds
This is the class and function reference of scikit-learn. Please refer to the full user guide for further details, as the class and function raw specifications may not be enough to give full guidelines on their uses. For reference on concepts repeated across the API, see Glossary of Common Terms and API Elements.

7.1 sklearn.base: Base classes and utility functions

Base classes for all estimators.

7.1.1 Base classes

<table>
<thead>
<tr>
<th>Class</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>base.BaseEstimator</td>
<td>Base class for all estimators in scikit-learn.</td>
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<tr>
<td>base.BiclusterMixin</td>
<td>Mixin class for all bicluster estimators in scikit-learn.</td>
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<tr>
<td>base.ClassifierMixin</td>
<td>Mixin class for all classifiers in scikit-learn.</td>
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<td>base.ClusterMixin</td>
<td>Mixin class for all cluster estimators in scikit-learn.</td>
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<td>base.DensityMixin</td>
<td>Mixin class for all density estimators in scikit-learn.</td>
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<td>base.RegressorMixin</td>
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<td>base.TransformerMixin</td>
<td>Mixin class for all transformers in scikit-learn.</td>
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<tr>
<td>feature_selection.SelectorMixin</td>
<td>Transformer mixin that performs feature selection given a support mask.</td>
</tr>
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</table>

sklearn.base.BaseEstimator

class sklearn.base.BaseEstimator
    Base class for all estimators in scikit-learn.
Notes

All estimators should specify all the parameters that can be set at the class level in their `__init__` as explicit keyword arguments (no *args or **kwargs).

Methods

```
get_params([deep]) Get parameters for this estimator.
set_params(**params) Set the parameters of this estimator.
```

**get_params** *(deep=True)*

Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

Examples using `sklearn.base.BaseEstimator`

- *Approximate nearest neighbors in TSNE*

`sklearn.base.BiclusterMixin`

```
class sklearn.base.BiclusterMixin
    Mixin class for all bicluster estimators in scikit-learn.
```

Attributes

- **biclusters** Convenient way to get row and column indicators together.
Methods

<table>
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<tr>
<th>Method</th>
<th>Description</th>
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<tr>
<td><code>get_indices(i)</code></td>
<td>Row and column indices of the $i$'th bicluster.</td>
</tr>
<tr>
<td><code>get_shape(i)</code></td>
<td>Shape of the $i$'th bicluster.</td>
</tr>
<tr>
<td><code>get_submatrix(i, data)</code></td>
<td>Return the submatrix corresponding to bicluster $i$.</td>
</tr>
</tbody>
</table>

**property biclusters_

Convenient way to get row and column indicators together.

Returns the `rows_` and `columns_` members.

**get_indices $(i)$

Row and column indices of the $i$'th bicluster.

Only works if `rows_` and `columns_` attributes exist.

**Parameters**

- $i$ [int] The index of the cluster.

**Returns**

- `row_ind` [ndarray, dtype=np.intp] Indices of rows in the dataset that belong to the bicluster.
- `col_ind` [ndarray, dtype=np.intp] Indices of columns in the dataset that belong to the bicluster.

**get_shape $(i)$

Shape of the $i$'th bicluster.

**Parameters**

- $i$ [int] The index of the cluster.

**Returns**

- `n_rows` [int] Number of rows in the bicluster.
- `n_cols` [int] Number of columns in the bicluster.

**get_submatrix $(i, data)$

Return the submatrix corresponding to bicluster $i$.

**Parameters**

- $i$ [int] The index of the cluster.
- `data` [array-like of shape (n_samples, n_features)] The data.

**Returns**

- `submatrix` [ndarray of shape (n_rows, n_cols)] The submatrix corresponding to bicluster $i$.  

7.1. sklearn.base: Base classes and utility functions
**Notes**

Works with sparse matrices. Only works if `rows_` and `columns_` attributes exist.

```python
sklearn.base.ClassifierMixin
```

```python
class sklearn.base.ClassifierMixin
    Mixin class for all classifiers in scikit-learn.
```

**Methods**

```python
score(X, y[, sample_weight])
```

Return the mean accuracy on the given test data and labels.

```python
score (X, y, sample_weight=None)
```

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Test samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for `X`.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- `score` [float] Mean accuracy of `self.predict(X)` wrt. `y`.

```python
sklearn.base.ClusterMixin
```

```python
class sklearn.base.ClusterMixin
    Mixin class for all cluster estimators in scikit-learn.
```

**Methods**

```python
fit_predict(X[, y])
```

Perform clustering on `X` and returns cluster labels.

```python
fit_predict (X, y=None)
```

Perform clustering on `X` and returns cluster labels.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input data.
- `y` [Ignored] Not used, present for API consistency by convention.

**Returns**

- `labels` [ndarray of shape (n_samples,), dtype=np.int64] Cluster labels.
sklearn.base.DensityMixin

class sklearn.base.DensityMixin
    Mixin class for all density estimators in scikit-learn.

Methods

score(X[, y])
    Return the score of the model on the data X.

score(X, y=None)
    Return the score of the model on the data X.

Parameters

    X [array-like of shape (n_samples, n_features)] Test samples.
    y [Ignored] Not used, present for API consistency by convention.

Returns

    score [float]

sklearn.base.RegressorMixin

class sklearn.base.RegressorMixin
    Mixin class for all regression estimators in scikit-learn.

Methods

score(X, y[, sample_weight])
    Return the coefficient of determination $R^2$ of the prediction.

score(X, y, sample_weight=None)
    Return the coefficient of determination $R^2$ of the prediction.
    The coefficient $R^2$ is defined as $1- \frac{u}{v}$, where $u$ is the residual sum of squares
    $\sum((y_{true} - y_{pred})^2)$ and $v$ is the total sum of squares $\sum((y_{true} - \text{y_true.mean})^2)$. The best possible
    score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant
    model that always predicts the expected value of $y$, disregarding the input features, would get a
    $R^2$ score of 0.0.

Parameters

    X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this
    may be a precomputed kernel matrix or a list of generic objects instead with shape
    (n_samples, n_samples_fitted), where n_samples_fitted is the number
    of samples used in the fitting for the estimator.
    y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.
    sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

    score [float] $R^2$ of self.predict(X) wrt $y$.  

7.1. sklearn.base: Base classes and utility functions
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

**sklearn.base.TransformerMixin**

class sklearn.base.TransformerMixin
Mixin class for all transformers in scikit-learn.

Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>fit_transform(X, y)</code></td>
<td>Fit to data, then transform it.</td>
</tr>
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</table>

`fit_transform(X, y=None, **fit_params)`

Fit to data, then transform it.

Fits transformer to $X$ and $y$ with optional parameters `fit_params` and returns a transformed version of $X$.

Parameters

- $X$ [array-like of shape (n_samples, n_features)] Input samples.
- $y$ [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

Returns

- $X_{new}$ [ndarray array of shape (n_samples, n_features_new)] Transformed array.

Examples using `sklearn.base.TransformerMixin`

- `Approximate nearest neighbors in TSNE`

**sklearn.feature_selection.SelectorMixin**

class sklearn.feature_selection.SelectorMixin
Transformer mixin that performs feature selection given a support mask

This mixin provides a feature selector implementation with `transform` and `inverse_transform` functionality given an implementation of `get_support_mask`. 
Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_support([indices])</code></td>
<td>Get a mask, or integer index, of the features selected</td>
</tr>
<tr>
<td><code>inverse_transform(X)</code></td>
<td>Reverse the transformation operation</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

**fit_transform** *(X, y=None, **fit_params)*

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_support**(indices=False)

Get a mask, or integer index, of the features selected

**Parameters**

- **indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

**Returns**

- **support** [array] An index that selects the retained features from a feature vector. If `indices` is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If `indices` is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

**inverse_transform**(X)

Reverse the transformation operation

**Parameters**

- **X** [array of shape [n_samples, n_selected_features]] The input samples.

**Returns**

- **X_r** [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by `transform`.

**transform**(X)

Reduce X to the selected features.

**Parameters**

- **X** [array of shape [n_samples, n_features]] The input samples.

**Returns**
X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

### 7.1.2 Functions

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
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<tr>
<td><code>base.clone(estimator, *[, safe])</code></td>
<td>Constructs a new unfitted estimator with the same parameters.</td>
</tr>
<tr>
<td><code>base.is_classifier(estimator)</code></td>
<td>Return True if the given estimator is (probably) a classifier.</td>
</tr>
<tr>
<td><code>base.is_regressor(estimator)</code></td>
<td>Return True if the given estimator is (probably) a regressor.</td>
</tr>
<tr>
<td><code>config_context(**new_config)</code></td>
<td>Context manager for global scikit-learn configuration</td>
</tr>
<tr>
<td><code>get_config()</code></td>
<td>Retrieve current values for configuration set by <code>set_config</code></td>
</tr>
<tr>
<td><code>set_config([assume_finite, working_memory, ...])</code></td>
<td>Set global scikit-learn configuration</td>
</tr>
<tr>
<td><code>show_versions()</code></td>
<td>Print useful debugging information</td>
</tr>
</tbody>
</table>

**sklearn.base.clone**

`sklearn.base.clone(estimator, *, safe=True)`

Constructs a new unfitted estimator with the same parameters.

Clone does a deep copy of the model in an estimator without actually copying attached data. It yields a new estimator with the same parameters that has not been fitted on any data.

If the estimator’s `random_state` parameter is an integer (or if the estimator doesn’t have a `random_state` parameter), an *exact clone* is returned: the clone and the original estimator will give the exact same results. Otherwise, *statistical clone* is returned: the clone might yield different results from the original estimator. More details can be found in *Controlling randomness*.

**Parameters**

- **estimator** [[list, tuple, set] of estimator instance or a single estimator instance] The estimator or group of estimators to be cloned.

- **safe** [bool, default=True] If safe is False, clone will fall back to a deep copy on objects that are not estimators.

**sklearn.base.is_classifier**

`sklearn.base.is_classifier(estimator)`

Return True if the given estimator is (probably) a classifier.

**Parameters**

- **estimator** [object] Estimator object to test.

**Returns**

- **out** [bool] True if estimator is a classifier and False otherwise.
sklearn.base.is_regressor

**sklearn.base.is_regressor** *(estimator)*

Return True if the given estimator is (probably) a regressor.

**Parameters**

- **estimator** [estimator instance] Estimator object to test.

**Returns**

- **out** [bool] True if estimator is a regressor and False otherwise.

sklearn.config_context

**sklearn.config_context** (**new_config**)

Context manager for global scikit-learn configuration

**Parameters**

- **assume_finite** [bool, default=False] If True, validation for finiteness will be skipped, saving time, but leading to potential crashes. If False, validation for finiteness will be performed, avoiding error. Global default: False.

- **working_memory** [int, default=1024] If set, scikit-learn will attempt to limit the size of temporary arrays to this number of MiB (per job when parallelised), often saving both computation time and memory on expensive operations that can be performed in chunks. Global default: 1024.

- **print_changed_only** [bool, default=True] If True, only the parameters that were set to non-default values will be printed when printing an estimator. For example, `print(SVC())` while True will only print ‘SVC()’, but would print ‘SVC(C=1.0, cache_size=200, …)’ with all the non-changed parameters when False. Default is True.

  Changed in version 0.23: Default changed from False to True.

- **display** [{‘text’, ‘diagram’}, default=’text’] If ‘diagram’, estimators will be displayed as a diagram in a Jupyter lab or notebook context. If ‘text’, estimators will be displayed as text. Default is ‘text’.

  New in version 0.23.

**See also:**

- **set_config** Set global scikit-learn configuration.
- **get_config** Retrieve current values of the global configuration.

**Notes**

All settings, not just those presently modified, will be returned to their previous values when the context manager is exited. This is not thread-safe.
Examples

```python
>>> import sklearn
>>> from sklearn.utils.validation import assert_all_finite
>>> with sklearn.config_context(assume_finite=True):
...     assert_all_finite([float('nan')])
>>> with sklearn.config_context(assume_finite=True):
...    with sklearn.config_context(assume_finite=False):
...     assert_all_finite([float('nan')])
Traceback (most recent call last):
... ValueError: Input contains NaN, ...
```

`sklearn.get_config`

`sklearn.get_config()`

Retrieve current values for configuration set by `set_config`

Returns

   config [dict] Keys are parameter names that can be passed to `set_config`.

See also:

   `config_context` Context manager for global scikit-learn configuration.

   `set_config` Set global scikit-learn configuration.

`sklearn.set_config`

`sklearn.set_config(assume_finite=None, working_memory=None, print_changed_only=None, display=None)`

Set global scikit-learn configuration

New in version 0.19.

Parameters

   assume_finite [bool, default=None] If True, validation for finiteness will be skipped, saving
time, but leading to potential crashes. If False, validation for finiteness will be performed,

New in version 0.19.

   working_memory [int, default=None] If set, scikit-learn will attempt to limit the size of tempo-
ary arrays to this number of MiB (per job when parallelised), often saving both computation
time and memory on expensive operations that can be performed in chunks. Global default: 1024.

New in version 0.20.

   print_changed_only [bool, default=None] If True, only the parameters that were set to non-
default values will be printed when printing an estimator. For example, `print(SVC())`
while True will only print `'SVC()'` while the default behaviour would be to print
`'SVC(C=1.0, cache_size=200, . . . )'` with all the non-changed parameters.

New in version 0.21.
display  [{‘text’, ‘diagram’}, default=None] If ‘diagram’, estimators will be displayed as a diagram in a Jupyter lab or notebook context. If ‘text’, estimators will be displayed as text. Default is ‘text’.

New in version 0.23.

See also:

cfg_context  Context manager for global scikit-learn configuration.

get_config  Retrieve current values of the global configuration.

Examples using sklearn.set_config

• Release Highlights for scikit-learn 0.23
• Compact estimator representations
• Column Transformer with Mixed Types

sklearn.show_versions

sklearn.show_versions()

Print useful debugging information”

New in version 0.20.

7.2 sklearn.calibration: Probability Calibration

Calibration of predicted probabilities.

User guide: See the Probability calibration section for further details.

calibration.CalibratedClassifierCV([…]) Probability calibration with isotonic regression or logistic regression.

7.2.1 sklearn.calibration.CalibratedClassifierCV

class sklearn.calibration.CalibratedClassifierCV(base_estimator=None, *, method='sigmoid', cv=None, n_jobs=None, ensemble=True)

Probability calibration with isotonic regression or logistic regression.

This class uses cross-validation to both estimate the parameters of a classifier and subsequently calibrate a classifier. With default ensemble=True, for each cv split it fits a copy of the base estimator to the training subset, and calibrates it using the testing subset. For prediction, predicted probabilities are averaged across these individual calibrated classifiers. When ensemble=False, cross-validation is used to obtain unbiased predictions, via cross_val_predict, which are then used for calibration. For prediction, the base estimator, trained using all the data, is used. This is the method implemented when probabilities=True for sklearn.svm estimators.

Already fitted classifiers can be calibrated via the parameter cv="prefit". In this case, no cross-validation is used and all provided data is used for calibration. The user has to take care manually that data for model fitting and calibration are disjoint.
The calibration is based on the `decision_function` method of the `base_estimator` if it exists, else on `predict_proba`.

Read more in the `User Guide`.

**Parameters**

- **base_estimator** [estimator instance, default=None] The classifier whose output need to be calibrated to provide more accurate `predict_proba` outputs. The default classifier is a `LinearSVC`.

- **method** [['sigmoid', 'isotonic'], default='sigmoid'] The method to use for calibration. Can be 'sigmoid' which corresponds to Platt's method (i.e. a logistic regression model) or 'isotonic' which is a non-parametric approach. It is not advised to use isotonic calibration with too few calibration samples (<1000) since it tends to overfit.

- **cv** [int, cross-validation generator, iterable or “prefit”, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross-validation,
  - integer, to specify the number of folds.
  - CV splitter,
  - An iterable yielding (train, test) splits as arrays of indices.

  For integer/None inputs, if `y` is binary or multiclass, `StratifiedKFold` is used. If `y` is neither binary nor multiclass, `KFold` is used.

  Refer to the `User Guide` for the various cross-validation strategies that can be used here.

  If “prefit” is passed, it is assumed that `base_estimator` has been fitted already and all data is used for calibration.

  Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

- **n_jobs** [int, default=None] Number of jobs to run in parallel. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors.

  Base estimator clones are fitted in parallel across cross-validation iterations. Therefore parallelism happens only when `cv` != "prefit".

  See `Glossary` for more details.

  New in version 0.24.

- **ensemble** [bool, default=True] Determines how the calibrator is fitted when `cv` is not 'prefit'. Ignored if `cv='prefit'`.

  If True, the `base_estimator` is fitted using training data and calibrated using testing data, for each `cv` fold. The final estimator is an ensemble of `n_cv` fitted classifier and calibrator pairs, where `n_cv` is the number of cross-validation folds. The output is the average predicted probabilities of all pairs.

  If False, `cv` is used to compute unbiased predictions, via `cross_val_predict`, which are then used for calibration. At prediction time, the classifier used is the `base_estimator` trained on all the data. Note that this method is also internally implemented in `sklearn.svm` estimators with the `probabilities=``True` parameter.

  New in version 0.24.

**Attributes**

- **classes_** [ndarray of shape (n_classes,)] The class labels.
The list of classifier and calibrator pairs.

- When `cv="prefit"`, the fitted `base_estimator` and fitted calibrator.
- When `cv` is not “prefit” and `ensemble=True`, `n_cv` fitted `base_estimator` and calibrator pairs. `n_cv` is the number of cross-validation folds.
- When `cv` is not “prefit” and `ensemble=False`, the `base_estimator`, fitted on all the data, and fitted calibrator.

Changed in version 0.24: Single calibrated classifier case when `ensemble=False`.

References


Examples

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.naive_bayes import GaussianNB
>>> from sklearn.calibration import CalibratedClassifierCV

>>> X, y = make_classification(n_samples=100, n_features=2, ...
... n_redundant=0, random_state=42)
>>> base_clf = GaussianNB()
>>> calibrated_clf = CalibratedClassifierCV(base_estimator=base_clf, cv=3)
>>> calibrated_clf.fit(X, y)
CalibratedClassifierCV(base_estimator=GaussianNB(), cv=3)
>>> len(calibrated_clf.calibrated_classifiers_)
3
>>> calibrated_clf.predict_proba(X)[:5, :]
array([[0.110..., 0.889...],
       [0.072..., 0.927...],
       [0.928..., 0.071...],
       [0.928..., 0.071...],
       [0.071..., 0.928...]])

>>> from sklearn.model_selection import train_test_split
>>> X, y = make_classification(n_samples=100, n_features=2, ...
... n_redundant=0, random_state=42)
>>> X_train, X_calib, y_train, y_calib = train_test_split( ...
... X, y, random_state=42 ...
... )
>>> base_clf = GaussianNB()
>>> base_clf.fit(X_train, y_train)
GaussianNB()
>>> calibrated_clf = CalibratedClassifierCV( ...
... base_estimator=base_clf,
... cv="prefit"
... )
>>> calibrated_clf.fit(X_calib, y_calib)
CalibratedClassifierCV(base_estimator=GaussianNB(), cv='prefit')
>>> len(calibrated_clf.calibrated_classifiers_)
1
>>> calibrated_clf.predict_proba([[0.5]])
array([[0.936..., 0.063...]])
```
## Methods

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<th>Method</th>
<th>Description</th>
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<td>fit(X, y[, sample_weight])</td>
<td>Fit the calibrated model.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict the target of new samples.</td>
</tr>
<tr>
<td>predict_proba(X)</td>
<td>Calibrated probabilities of classification.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

### fit(X, y, sample_weight=None)

Fit the calibrated model.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Training data.
- y [array-like of shape (n_samples,)] Target values.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted.

**Returns**


### get_params(deep=True)

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

### predict(X)

Predict the target of new samples. The predicted class is the class that has the highest probability, and can thus be different from the prediction of the uncalibrated classifier.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The samples.

**Returns**

- C [ndarray of shape (n_samples,)] The predicted class.

### predict_proba(X)

Calibrated probabilities of classification.

This function returns calibrated probabilities of classification according to each class on an array of test vectors X.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The samples.

**Returns**

- C [ndarray of shape (n_samples, n_classes)] The predicted probas.
score (X, y, sample_weight=None)
    Return the mean accuracy on the given test data and labels.
    In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each
    sample that each label set be correctly predicted.

    Parameters
    X [array-like of shape (n_samples, n_features)] Test samples.
    y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
    sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

    Returns
    score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)
    Set the parameters of this estimator.
    The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
    parameters of the form <component>__<parameter> so that it’s possible to update each component
    of a nested object.

    Parameters
    **params [dict] Estimator parameters.

    Returns
    self [estimator instance] Estimator instance.

Examples using sklearn.calibration.CalibratedClassifierCV

- Probability Calibration curves
- Probability calibration of classifiers
- Probability Calibration for 3-class classification

calibration.calibration_curve(y_true, y_prob, *)
    Compute true and predicted probabilities for a calibration curve.

7.2.2 sklearn.calibration.calibration_curve

sklearn.calibration.calibration_curve(y_true, y_prob, *, normalize=False, n_bins=5, strategy='uniform')
    Compute true and predicted probabilities for a calibration curve.
    The method assumes the inputs come from a binary classifier, and discretize the [0, 1] interval into bins.
    Calibration curves may also be referred to as reliability diagrams.
    Read more in the User Guide.

    Parameters
    y_true [array-like of shape (n_samples,)] True targets.
    y_prob [array-like of shape (n_samples,)] Probabilities of the positive class.
normalize  [bool, default=False] Whether y_prob needs to be normalized into the [0, 1] interval, i.e. is not a proper probability. If True, the smallest value in y_prob is linearly mapped onto 0 and the largest one onto 1.

n_bins  [int, default=5] Number of bins to discretize the [0, 1] interval. A bigger number requires more data. Bins with no samples (i.e. without corresponding values in y_prob) will not be returned, thus the returned arrays may have less than n_bins values.

strategy  [['uniform', 'quantile'], default='uniform'] Strategy used to define the widths of the bins.

   uniform  The bins have identical widths.
   quantile  The bins have the same number of samples and depend on y_prob.

Returns

   prob_true  [ndarray of shape (n_bins,) or smaller] The proportion of samples whose class is the positive class, in each bin (fraction of positives).

   prob_pred  [ndarray of shape (n_bins,) or smaller] The mean predicted probability in each bin.

References


Examples

```python
>>> import numpy as np
>>> from sklearn.calibration import calibration_curve
>>> y_true = np.array([0, 0, 0, 0, 1, 1, 1, 1, 1])
>>> y_pred = np.array([0.1, 0.2, 0.3, 0.4, 0.65, 0.7, 0.8, 0.9, 1.])
>>> prob_true, prob_pred = calibration_curve(y_true, y_pred, n_bins=3)
>>> prob_true
array([0., 0.5, 1.])
>>> prob_pred
array([0.2 , 0.525, 0.85])
```

Examples using sklearn.calibration.calibration_curve

- *Comparison of Calibration of Classifiers*
- *Probability Calibration curves*
7.3 sklearn.cluster: Clustering

The `sklearn.cluster` module gathers popular unsupervised clustering algorithms.

**User guide:** See the Clustering and Biclustering sections for further details.

### 7.3.1 Classes

- `cluster.AffinityPropagation(*[, damping, max_iter, convergence_iter, copy, preference, affinity, random_state])` Perform Affinity Propagation Clustering of data.
- `cluster.AgglomerativeClustering([...])` Agglomerative Clustering
- `cluster.Birch(*[, threshold, ...])` Implements the Birch clustering algorithm.
- `cluster.DBSCAN(eps, min_samples, metric, ...)` Perform DBSCAN clustering from vector array or distance matrix.
- `cluster.FeatureAgglomeration([n_clusters, ...])` Agglomerate features.
- `cluster.MeanShift(*[, bandwidth, seeds, ...])` Mean shift clustering using a flat kernel.
- `cluster.OPTICS(*[, min_samples, max_eps, ...])` Estimate clustering structure from vector array.
- `cluster.SpectralClustering([n_clusters, ...])` Apply clustering to a projection of the normalized Laplacian.
- `cluster.SpectralBiclustering([n_clusters, ...])` Spectral biclustering (Kluger, 2003).
- `cluster.SpectralCoclustering([n_clusters, ...])` Spectral Co-Clustering algorithm (Dhillon, 2001).

#### sklearn.cluster.AffinityPropagation

**class sklearn.cluster.AffinityPropagation(*, damping=0.5, max_iter=200, convergence_iter=15, copy=True, preference=None, affinity='euclidean', verbose=False, random_state='warn')**

Perform Affinity Propagation Clustering of data.

Read more in the *User Guide*.

**Parameters**

- **damping** [float, default=0.5] Damping factor (between 0.5 and 1) is the extent to which the current value is maintained relative to incoming values (weighted 1 - damping). This in order to avoid numerical oscillations when updating these values (messages).
- **max_iter** [int, default=200] Maximum number of iterations.
- **convergence_iter** [int, default=15] Number of iterations with no change in the number of estimated clusters that stops the convergence.
- **copy** [bool, default=True] Make a copy of input data.
- **preference** [array-like of shape (n_samples,) or float, default=None] Preferences for each point - points with larger values of preferences are more likely to be chosen as exemplars. The
number of exemplars, ie of clusters, is influenced by the input preferences value. If the preferences are not passed as arguments, they will be set to the median of the input similarities.

affinity [{'euclidean', 'precomputed'}, default='euclidean'] Which affinity to use. At the moment 'precomputed' and euclidean are supported. 'euclidean' uses the negative squared euclidean distance between points.

verbose [bool, default=False] Whether to be verbose.

random_state [int, RandomState instance or None, default=0] Pseudo-random number generator to control the starting state. Use an int for reproducible results across function calls. See the Glossary.

New in version 0.23: this parameter was previously hardcoded as 0.

Attributes

cluster_centers_indices_ [ndarray of shape (n_clusters,)] Indices of cluster centers.

cluster_centers_ [ndarray of shape (n_clusters, n_features)] Cluster centers (if affinity != precomputed).

labels_ [ndarray of shape (n_samples,)] Labels of each point.

affinity_matrix_ [ndarray of shape (n_samples, n_samples)] Stores the affinity matrix used in fit.

n_iter_ [int] Number of iterations taken to converge.

Notes

For an example, see examples/cluster/plot_affinity_propagation.py.

The algorithmic complexity of affinity propagation is quadratic in the number of points.

When fit does not converge, cluster_centers_ becomes an empty array and all training samples will be labelled as -1. In addition, predict will then label every sample as -1.

When all training samples have equal similarities and equal preferences, the assignment of cluster centers and labels depends on the preference. If the preference is smaller than the similarities, fit will result in a single cluster center and label 0 for every sample. Otherwise, every training sample becomes its own cluster center and is assigned a unique label.

References


Examples

```python
>>> from sklearn.cluster import AffinityPropagation
>>> import numpy as np
>>> X = np.array([[1, 2], [1, 4], [1, 0], ...
...               [4, 2], [4, 4], [4, 0]])
>>> clustering = AffinityPropagation(random_state=5).fit(X)
>>> clustering
AffinityPropagation(random_state=5)
>>> clustering.labels_
array([0, 0, 0, 1, 1, 1])
```
Methods

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<td>Fit the clustering from features, or affinity matrix.</td>
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<tr>
<td>fit_predict(X[, y])</td>
<td>Fit the clustering from features or affinity matrix, and return cluster labels.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict the closest cluster each sample in X belongs to.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit** (X, y=None)

Fit the clustering from features, or affinity matrix.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features), or array-like of shape (n_samples, n_samples)) Training instances to cluster, or similarities / affinities between instances if affinity='precomputed'. If a sparse feature matrix is provided, it will be converted into a sparse csr_matrix.

- **y** [Ignored] Not used, present here for API consistency by convention.

**Returns**

**self**

**fit_predict** (X, y=None)

Fit the clustering from features or affinity matrix, and return cluster labels.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features), or array-like of shape (n_samples, n_samples)) Training instances to cluster, or similarities / affinities between instances if affinity='precomputed'. If a sparse feature matrix is provided, it will be converted into a sparse csr_matrix.

- **y** [Ignored] Not used, present here for API consistency by convention.

**Returns**

**labels** [ndarray of shape (n_samples,)] Cluster labels.

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.
predict \((X)\)
Predict the closest cluster each sample in \(X\) belongs to.

Parameters

\(X\) [{array-like, sparse matrix} of shape (n_samples, n_features)] New data to predict. If a sparse matrix is provided, it will be converted into a sparse \(\text{csr\_matrix}\).

Returns

\(labels\) [ndarray of shape (n_samples,)] Cluster labels.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \texttt{Pipeline}). The latter have parameters of the form \(<\text{component}>__<\text{parameter}>\) so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using \texttt{sklearn.cluster.AffinityPropagation}

- \texttt{Demo of affinity propagation clustering algorithm}
- \texttt{Comparing different clustering algorithms on toy datasets}

\texttt{sklearn.cluster.AgglomerativeClustering}

class sklearn.cluster.AgglomerativeClustering (n_clusters=2, *, affinity='euclidean', memory=None, connectivity=None, compute_full_tree='auto', linkage='ward', distance_threshold=None, compute_distances=False)

Agglomerative Clustering

Recursively merges the pair of clusters that minimally increases a given linkage distance.

Read more in the \textit{User Guide}.

Parameters

\(n\_clusters\) [int or None, default=2] The number of clusters to find. It must be \texttt{None} if \(distance\_threshold\) is not \texttt{None}.

\(affinity\) [str or callable, default=’euclidean’] Metric used to compute the linkage. Can be “euclidean”, “\texttt{l1}”, “\texttt{l2}”, “\texttt{manhattan}”, “cosine”, or “precomputed”. If linkage is “ward”, only “euclidean” is accepted. If “precomputed”, a distance matrix (instead of a similarity matrix) is needed as input for the fit method.

\(memory\) [str or object with the joblib\texttt{.Memory} interface, default=\texttt{None}] Used to cache the output of the computation of the tree. By default, no caching is done. If a string is given, it is the path to the caching directory.
**connectivity** [array-like or callable, default=None] Connectivity matrix. Defines for each sample the neighboring samples following a given structure of the data. This can be a connectivity matrix itself or a callable that transforms the data into a connectivity matrix, such as derived from kneighbors_graph. Default is None, i.e., the hierarchical clustering algorithm is unstructured.

**compute_full_tree** ['auto' or bool, default='auto'] Stop early the construction of the tree at n_clusters. This is useful to decrease computation time if the number of clusters is not small compared to the number of samples. This option is useful only when specifying a connectivity matrix. Note also that when varying the number of clusters and using caching, it may be advantageous to compute the full tree. It must be True if distance_threshold is not None. By default compute_full_tree is “auto”, which is equivalent to True when distance_threshold is not None or that n_clusters is inferior to the maximum between 100 or 0.02 * n_samples. Otherwise, “auto” is equivalent to False.

**linkage** [{'ward', 'complete', 'average', 'single'}, default='ward'] Which linkage criterion to use. The linkage criterion determines which distance to use between sets of observation. The algorithm will merge the pairs of cluster that minimize this criterion.

- ‘ward’ minimizes the variance of the clusters being merged.
- ‘average’ uses the average of the distances of each observation of the two sets.
- ‘complete’ or ‘maximum’ linkage uses the maximum distances between all observations of the two sets.
- ‘single’ uses the minimum of the distances between all observations of the two sets.

New in version 0.20: Added the ‘single’ option

**distance_threshold** [float, default=None] The linkage distance threshold above which, clusters will not be merged. If not None, n_clusters must be None and compute_full_tree must be True.

New in version 0.21.

**compute_distances** [bool, default=False] Computes distances between clusters even if distance_threshold is not used. This can be used to make dendrogram visualization, but introduces a computational and memory overhead.

New in version 0.24.

**Attributes**

- **n_clusters_** [int] The number of clusters found by the algorithm. If distance_threshold=None, it will be equal to the given n_clusters.
- **labels_** [ndarray of shape (n_samples)] cluster labels for each point
- **n_leaves_** [int] Number of leaves in the hierarchical tree.
- **n_connected_components_** [int] The estimated number of connected components in the graph.

New in version 0.21: n_connected_components_ was added to replace n_components_.

- **children_** [array-like of shape (n_samples-1, 2)] The children of each non-leaf node. Values less than n_samples correspond to leaves of the tree which are the original samples. A node i greater than or equal to n_samples is a non-leaf node and has children children_[i - n_samples]. Alternatively at the i-th iteration, children[i][0] and children[i][1] are merged to form node n_samples + i
distances_ [array-like of shape (n_nodes-1,)] Distances between nodes in the corresponding place in children_. Only computed if distance_threshold is used or compute_distances is set to True.

**Examples**

```python
>>> from sklearn.cluster import AgglomerativeClustering
>>> import numpy as np

>>> X = np.array([[1, 2], [1, 4], [1, 0],
                 ... [4, 2], [4, 4], [4, 0]])
>>> clustering = AgglomerativeClustering().fit(X)
>>> clustering
AgglomerativeClustering()
>>> clustering.labels_
array([1, 1, 1, 0, 0, 0])
```

**Methods**

- `fit(X[, y])` Fit the hierarchical clustering from features, or distance matrix.
- `fit_predict(X[, y])` Fit the hierarchical clustering from features or distance matrix, and return cluster labels.
- `get_params([deep])` Get parameters for this estimator.
- `set_params(**params)` Set the parameters of this estimator.

`fit (X, y=None)`
Fit the hierarchical clustering from features, or distance matrix.

Parameters

- **X** [array-like, shape (n_samples, n_features) or (n_samples, n_samples)] Training instances to cluster, or distances between instances if `affinity='precomputed'`.
- **y** [Ignored] Not used, present here for API consistency by convention.

Returns

- **self**

`fit_predict (X, y=None)`
Fit the hierarchical clustering from features or distance matrix, and return cluster labels.

Parameters

- **X** [array-like of shape (n_samples, n_features) or (n_samples, n_samples)] Training instances to cluster, or distances between instances if `affinity='precomputed'`.
- **y** [Ignored] Not used, present here for API consistency by convention.

Returns

- **labels** [ndarray of shape (n_samples,)] Cluster labels.

`get_params (deep=True)`
Get parameters for this estimator.

Parameters
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__.<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

**self** [estimator instance] Estimator instance.

**Examples using sklearn.cluster.AgglomerativeClustering**

- Plot Hierarchical Clustering Dendrogram
- Agglomerative clustering with and without structure
- Various Agglomerative Clustering on a 2D embedding of digits
- A demo of structured Ward hierarchical clustering on an image of coins
- Hierarchical clustering: structured vs unstructured ward
- Agglomerative clustering with different metrics
- Inductive Clustering
- Comparing different hierarchical linkage methods on toy datasets
- Comparing different clustering algorithms on toy datasets

**sklearn.cluster.Birch**

**class sklearn.cluster.Birch(***, *threshold=0.5, branching_factor=50, n_clusters=3, compute_labels=True, copy=True***)

Implements the Birch clustering algorithm.

It is a memory-efficient, online-learning algorithm provided as an alternative to `MiniBatchKMeans`. It constructs a tree data structure with the cluster centroids being read off the leaf. These can be either the final cluster centroids or can be provided as input to another clustering algorithm such as `AgglomerativeClustering`.

Read more in the **User Guide**.

New in version 0.16.

**Parameters**

**threshold** [float, default=0.5] The radius of the subcluster obtained by merging a new sample and the closest subcluster should be lesser than the threshold. Otherwise a new subcluster is started. Setting this value to be very low promotes splitting and vice-versa.
branching_factor [int, default=50] Maximum number of CF subclusters in each node. If a new samples enters such that the number of subclusters exceed the branching_factor then that node is split into two nodes with the subclusters redistributed in each. The parent subcluster of that node is removed and two new subclusters are added as parents of the 2 split nodes.

n_clusters [int, instance of sklearn.cluster model, default=3] Number of clusters after the final clustering step, which treats the subclusters from the leaves as new samples.

  • None : the final clustering step is not performed and the subclusters are returned as they are.
  • sklearn.cluster Estimator : If a model is provided, the model is fit treating the subclusters as new samples and the initial data is mapped to the label of the closest subcluster.
  • int : the model fit is AgglomerativeClustering with n_clusters set to be equal to the int.

compute_labels [bool, default=True] Whether or not to compute labels for each fit.

copy [bool, default=True] Whether or not to make a copy of the given data. If set to False, the initial data will be overwritten.

Attributes

  root_ [CFNode] Root of the CFTree.
  dummy_leaf_ [CFNode] Start pointer to all the leaves.
  subcluster_centers_ [ndarray] Centroids of all subclusters read directly from the leaves.
  subcluster_labels_ [ndarray] Labels assigned to the centroids of the subclusters after they are clustered globally.
  labels_ [ndarray of shape (n_samples,)] Array of labels assigned to the input data. if partial_fit is used instead of fit, they are assigned to the last batch of data.

See also:

MiniBatchKMeans Alternative implementation that does incremental updates of the centers’ positions using mini-batches.

Notes

The tree data structure consists of nodes with each node consisting of a number of subclusters. The maximum number of subclusters in a node is determined by the branching factor. Each subcluster maintains a linear sum, squared sum and the number of samples in that subcluster. In addition, each subcluster can also have a node as its child, if the subcluster is not a member of a leaf node.

For a new point entering the root, it is merged with the subcluster closest to it and the linear sum, squared sum and the number of samples of that subcluster are updated. This is done recursively till the properties of the leaf node are updated.
References

- Roberto Perdisci JBirch - Java implementation of BIRCH clustering algorithm https://code.google.com/archive/p/jbirch

Examples

```python
>>> from sklearn.cluster import Birch
>>> X = [[0, 1], [0.3, 1], [-0.3, 1], [0, -1], [0.3, -1], [-0.3, -1]]
>>> brc = Birch(n_clusters=None)
>>> brc.fit(X)
Birch(n_clusters=None)
>>> brc.predict(X)
array([0, 0, 0, 1, 1, 1])
```

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<td>Build a CF Tree for the input data.</td>
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<td><code>fit_predict(X[, y])</code></td>
<td>Perform clustering on X and returns cluster labels.</td>
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<tr>
<td><code>fit_transform(X[, y], **fit_params)</code></td>
<td>Fit to data, then transform it.</td>
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<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>partial_fit([X, y])</code></td>
<td>Online learning.</td>
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<td><code>predict(X)</code></td>
<td>Predict data using the centroids_ of subclusters.</td>
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<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Transform X into subcluster centroids dimension.</td>
</tr>
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</table>

`fit(X, y=None)`
Build a CF Tree for the input data.

Parameters

- `X` [{array-like, sparse matrix} of shape (n_samples, n_features)] Input data.
- `y` [Ignored] Not used, present here for API consistency by convention.

Returns

- `self` Fitted estimator.

`fit_predict(X, y=None)`
Perform clustering on X and returns cluster labels.

Parameters

- `X` [array-like of shape (n_samples, n_features)] Input data.
- `y` [Ignored] Not used, present for API consistency by convention.

Returns

- `labels` [ndarray of shape (n_samples,), dtype=np.int64] Cluster labels.

`fit_transform(X, y=None, **fit_params)`
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**partial_fit** *(X=None, y=None)*

Online learning. Prevents rebuilding of CFTree from scratch.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features), default=None] Input data. If X is not provided, only the global clustering step is done.
- **y** [Ignored] Not used, present here for API consistency by convention.

**Returns**

- **self** Fitted estimator.

**predict** *(X)*

Predict data using the centroids of subclusters. Avoid computation of the row norms of X.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] Input data.

**Returns**

- **labels** [ndarray of shape(n_samples,)] Labelled data.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.
self  [estimator instance] Estimator instance.

transform(X)
Transform X into subcluster centroids dimension.
Each dimension represents the distance from the sample point to each cluster centroid.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] Input data.

Returns

X_trans  [{array-like, sparse matrix} of shape (n_samples, n_clusters)] Transformed data.

Examples using sklearn.cluster.Birch

• Compare BIRCH and MiniBatchKMeans
• Comparing different clustering algorithms on toy datasets

sklearn.cluster.DBSCAN

class sklearn.cluster.DBSCAN(eps=0.5, *, min_samples=5, metric='euclidean', metric_params=None, algorithm='auto', leaf_size=30, p=None, n_jobs=None)
Perform DBSCAN clustering from vector array or distance matrix.
DBSCAN - Density-Based Spatial Clustering of Applications with Noise. Finds core samples of high density
and expands clusters from them. Good for data which contains clusters of similar density.
Read more in the User Guide.

Parameters

eps  [float, default=0.5] The maximum distance between two samples for one to be considered
as in the neighborhood of the other. This is not a maximum bound on the distances of points
within a cluster. This is the most important DBSCAN parameter to choose appropriately for
your data set and distance function.

min_samples  [int, default=5] The number of samples (or total weight) in a neighborhood for a
point to be considered as a core point. This includes the point itself.

metric  [string, or callable, default='euclidean'] The metric to use when calculating distance
between instances in a feature array. If metric is a string or callable, it must be one of the
options allowed by sklearn.metrics.pairwise_distances for its metric param-
eter. If metric is “precomputed”, X is assumed to be a distance matrix and must be square.
X may be a Glossary, in which case only “nonzero” elements may be considered neighbors
for DBSCAN.

New in version 0.17: metric precomputed to accept precomputed sparse matrix.

metric_params  [dict, default=None] Additional keyword arguments for the metric function.

New in version 0.19.

algorithm  [{‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’}, default=‘auto’] The algorithm to be used by
the NearestNeighbors module to compute pointwise distances and find nearest neighbors.
See NearestNeighbors module documentation for details.
leaf_size  [int, default=30] Leaf size passed to BallTree or cKDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

p  [float, default=None] The power of the Minkowski metric to be used to calculate distance between points. If None, then p=2 (equivalent to the Euclidean distance).

n_jobs  [int, default=None] The number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

core_sample_indices_  [ndarray of shape (n_core_samples,)] Indices of core samples.

components_  [ndarray of shape (n_core_samples, n_features)] Copy of each core sample found by training.

labels_  [ndarray of shape (n_samples)] Cluster labels for each point in the dataset given to fit(). Noisy samples are given the label -1.

See also:

OPTICS A similar clustering at multiple values of eps. Our implementation is optimized for memory usage.

Notes

For an example, see examples/cluster/plot_dbscan.py.

This implementation bulk-computes all neighborhood queries, which increases the memory complexity to O(n.d) where d is the average number of neighbors, while original DBSCAN had memory complexity O(n). It may attract a higher memory complexity when querying these nearest neighborhoods, depending on the algorithm.

One way to avoid the query complexity is to pre-compute sparse neighborhoods in chunks using NearestNeighbors.radius_neighbors_graph with mode='distance', then using metric='precomputed' here.

Another way to reduce memory and computation time is to remove (near-)duplicate points and use sample_weight instead.

cluster.OPTICS provides a similar clustering with lower memory usage.

References


### Examples

```python
>>> from sklearn.cluster import DBSCAN
>>> import numpy as np
>>> X = np.array([[1, 2], [2, 2], [2, 3], ... [8, 7], [8, 8], [25, 80]])
>>> clustering = DBSCAN(eps=3, min_samples=2).fit(X)
>>> clustering.labels_
array([ 0, 0, 0, 1, 1, -1])
>>> clustering
DBSCAN(eps=3, min_samples=2)
```

### Methods

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<td><code>fit(X, y, sample_weight) </code></td>
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#### `fit(X, y=None, sample_weight=None)`
Perform DBSCAN clustering from features, or distance matrix.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features), or (n_samples, n_samples)]
- **sample_weight** [array-like of shape (n_samples,), default=None]

**Returns**

- **self**

#### `fit_predict(X, y=None, sample_weight=None)`
Perform DBSCAN clustering from features or distance matrix, and return cluster labels.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features), or (n_samples, n_samples)]
- **sample_weight** [array-like of shape (n_samples,), default=None]

---

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y [Ignored] Not used, present here for API consistency by convention.

Returns

labels [ndarray of shape (n_samples,)] Cluster labels. Noisy samples are given the label -1.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.cluster.DBSCAN

- Demo of DBSCAN clustering algorithm
- Comparing different clustering algorithms on toy datasets

sklearn.cluster.FeatureAgglomeration

class sklearn.cluster.FeatureAgglomeration (n_clusters=2, *, affinity='euclidean',
memory=None, connectivity=None, compute_full_tree='auto', linkage='ward',
pooling_func=<function mean>, distance_threshold=None, compute_distances=False)

Agglomerate features.

Similar to AgglomerativeClustering, but recursively merges features instead of samples.

Read more in the User Guide.

Parameters

n_clusters [int, default=2] The number of clusters to find. It must be None if
distance_threshold is not None.

affinity [str or callable, default='euclidean'] Metric used to compute the linkage. Can be “eu-
clidean”, “l1”, “l2”, “manhattan”, “cosine”, or ‘precomputed’. If linkage is “ward”, only
“euclidean” is accepted.
memory [str or object with the joblib.Memory interface, default=None] Used to cache the output of the computation of the tree. By default, no caching is done. If a string is given, it is the path to the caching directory.

connectivity [array-like or callable, default=None] Connectivity matrix. Defines for each feature the neighboring features following a given structure of the data. This can be a connectivity matrix itself or a callable that transforms the data into a connectivity matrix, such as derived from kneighbors_graph. Default is None, i.e, the hierarchical clustering algorithm is unstructured.

compute_full_tree [‘auto’ or bool, default=’auto’] Stop early the construction of the tree at n_clusters. This is useful to decrease computation time if the number of clusters is not small compared to the number of features. This option is useful only when specifying a connectivity matrix. Note also that when varying the number of clusters and using caching, it may be advantageous to compute the full tree. It must be True if distance_threshold is not None. By default compute_full_tree is “auto”, which is equivalent to True when distance_threshold is not None or that n_clusters is inferior to the maximum between 100 or 0.02 * n_samples. Otherwise, “auto” is equivalent to False.

linkage [{‘ward’, ‘complete’, ‘average’, ‘single’}, default=’ward’] Which linkage criterion to use. The linkage criterion determines which distance to use between sets of features. The algorithm will merge the pairs of cluster that minimize this criterion.

- ward minimizes the variance of the clusters being merged.
- average uses the average of the distances of each feature of the two sets.
- complete or maximum linkage uses the maximum distances between all features of the two sets.
- single uses the minimum of the distances between all observations of the two sets.

pooling_func [callable, default=np.mean] This combines the values of agglomerated features into a single value, and should accept an array of shape [M, N] and the keyword argument axis=1, and reduce it to an array of size [M].

distance_threshold [float, default=None] The linkage distance threshold above which, clusters will not be merged. If not None, n_clusters must be None and compute_full_tree must be True.

New in version 0.21.

compute_distances [bool, default=False] Computes distances between clusters even if distance_threshold is not used. This can be used to make dendrogram visualization, but introduces a computational and memory overhead.

New in version 0.24.

Attributes

n_clusters_ [int] The number of clusters found by the algorithm. If distance_threshold=None, it will be equal to the given n_clusters.

labels_ [array-like of (n_features,)] cluster labels for each feature.

n_leaves_ [int] Number of leaves in the hierarchical tree.

n_connected_components_ [int] The estimated number of connected components in the graph.

New in version 0.21: n_connected_components_ was added to replace n_components_.

7.3. sklearn.cluster: Clustering
children_ [array-like of shape (n_nodes-1, 2)] The children of each non-leaf node. Values less than n_features correspond to leaves of the tree which are the original samples. A node i greater than or equal to n_features is a non-leaf node and has children children_[i - n_features]. Alternatively at the i-th iteration, children[i][0] and children[i][1] are merged to form node n_features + i.

distances_ [array-like of shape (n_nodes-1,)] Distances between nodes in the corresponding place in children_. Only computed if distance_threshold is used or compute_distances is set to True.

Examples

```python
>>> import numpy as np
>>> from sklearn import datasets, cluster
>>> digits = datasets.load_digits()
>>> images = digits.images
>>> X = np.reshape(images, (len(images), -1))
>>> agglo = cluster.FeatureAgglomeration(n_clusters=32)
>>> agglo.fit(X)
FeatureAgglomeration(n_clusters=32)
>>> X_reduced = agglo.transform(X)
>>> X_reduced.shape
(1797, 32)
```

Methods

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<td>fit(X[, y])</td>
<td>Fit the hierarchical clustering on the data</td>
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<td>fit_transform(X[, y])</td>
<td>Fit to data, then transform it.</td>
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<td>get_params([deep])</td>
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<td>inverse_transform(Xred)</td>
<td>Inverse the transformation.</td>
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<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
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<tr>
<td>transform(X)</td>
<td>Transform a new matrix using the built clustering</td>
</tr>
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fit (X, y=None, **params)

Fit the hierarchical clustering on the data

Parameters

- **X** [array-like of shape (n_samples, n_features)] The data
- **y** [Ignored]

Returns

- **self**

property fit_predict

Fit the hierarchical clustering from features or distance matrix, and return cluster labels.

Parameters

- **X** [array-like of shape (n_samples, n_features) or (n_samples, n_samples)] Training instances to cluster, or distances between instances if affinity='precomputed'.
- **y** [Ignored] Not used, present here for API consistency by convention.

Returns
labels [ndarray of shape (n_samples,)] Cluster labels.

fit_transform (X, y=None, **fit_params)
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters
X [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
**fit_params [dict] Additional fit parameters.

Returns
X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

inverse_transform (Xred)
Inverse the transformation. Return a vector of size nb_features with the values of Xred assigned to each group of features

Parameters
Xred [array-like of shape (n_samples, n_clusters) or (n_clusters,)] The values to be assigned to each cluster of samples

Returns
X [ndarray of shape (n_samples, n_features) or (n_features,)] A vector of size n_samples with the values of Xred assigned to each of the cluster of samples.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters
**params [dict] Estimator parameters.

Returns
self [estimator instance] Estimator instance.

transform (X)
Transform a new matrix using the built clustering

Parameters
X [array-like of shape (n_samples, n_features) or (n_samples,)] A M by N array of M observations in N dimensions or a length M array of M one-dimensional observations.

Returns

Y [ndarray of shape (n_samples, n_clusters) or (n_clusters,)] The pooled values for each feature cluster.

Examples using sklearn.cluster.FeatureAgglomeration

• Feature agglomeration
• Feature agglomeration vs. univariate selection

sklearn.cluster.KMeans

class sklearn.cluster.KMeans(n_clusters=8, *, init='k-means++', n_init=10, max_iter=300, tol=0.0001, precompute_distances='deprecated', verbose=0, random_state=None, copy_x=True, n_jobs='deprecated', algorithm='auto')

K-Means clustering.

Read more in the User Guide.

Parameters

n_clusters [int, default=8] The number of clusters to form as well as the number of centroids to generate.

init [['k-means++', 'random'], callable or array-like of shape (n_clusters, n_features), default='k-means++'] Method for initialization:

‘k-means++’ : selects initial cluster centers for k-mean clustering in a smart way to speed up convergence. See section Notes in k_init for more details.

‘random’: choose n_clusters observations (rows) at random from data for the initial centroids.

If an array is passed, it should be of shape (n_clusters, n_features) and gives the initial centers.

If a callable is passed, it should take arguments X, n_clusters and a random state and return an initialization.

n_init [int, default=10] Number of time the k-means algorithm will be run with different centroid seeds. The final results will be the best output of n_init consecutive runs in terms of inertia.

max_iter [int, default=300] Maximum number of iterations of the k-means algorithm for a single run.

tol [float, default=1e-4] Relative tolerance with regards to Frobenius norm of the difference in the cluster centers of two consecutive iterations to declare convergence.

precompute_distances [{'auto', True, False}, default='auto'] Precompute distances (faster but takes more memory).

‘auto’ : do not precompute distances if n_samples * n_clusters > 12 million. This corresponds to about 100MB overhead per job using double precision.

True : always precompute distances.
False: never precompute distances.

Deprecated since version 0.23: ‘precompute_distances’ was deprecated in version 0.22 and will be removed in 1.0 (renaming of 0.25). It has no effect.

**verbose** [int, default=0] Verbosity mode.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation for centroid initialization. Use an int to make the randomness deterministic. See Glossary.

**copy_x** [bool, default=True] When pre-computing distances it is more numerically accurate to center the data first. If copy_x is True (default), then the original data is not modified. If False, the original data is modified, and put back before the function returns, but small numerical differences may be introduced by subtracting and then adding the data mean. Note that if the original data is not C-contiguous, a copy will be made even if copy_x is False. If the original data is sparse, but not in CSR format, a copy will be made even if copy_x is False.

**n_jobs** [int, default=None] The number of OpenMP threads to use for the computation. Parallelism is sample-wise on the main cython loop which assigns each sample to its closest center.

None or -1 means using all processors.

Deprecated since version 0.23: n_jobs was deprecated in version 0.23 and will be removed in 1.0 (renaming of 0.25).

**algorithm** [“auto”, “full”, “elkan”], default=”auto” K-means algorithm to use. The classical EM-style algorithm is “full”. The “elkan” variation is more efficient on data with well-defined clusters, by using the triangle inequality. However it’s more memory intensive due to the allocation of an extra array of shape (n_samples, n_clusters).

For now “auto” (kept for backward compatibility) chooses “elkan” but it might change in the future for a better heuristic.

Changed in version 0.18: Added Elkan algorithm

**Attributes**

- **cluster_centers_** [ndarray of shape (n_clusters, n_features)] Coordinates of cluster centers. If the algorithm stops before fully converging (see tol and max_iter), these will not be consistent with labels_.
- **labels_** [ndarray of shape (n_samples,)] Labels of each point
- **inertia_** [float] Sum of squared distances of samples to their closest cluster center.
- **n_iter_** [int] Number of iterations run.

See also:

*MiniBatchKMeans* Alternative online implementation that does incremental updates of the centers positions using mini-batches. For large scale learning (say n_samples > 10k) MiniBatchKMeans is probably much faster than the default batch implementation.
Notes

The k-means problem is solved using either Lloyd’s or Elkan’s algorithm.

The average complexity is given by $O(k \ n \ T)$, were $n$ is the number of samples and $T$ is the number of iteration.

The worst case complexity is given by $O(n^{(k+2/p)})$ with $n = n_{\text{samples}}$, $p = n_{\text{features}}$. (D. Arthur and S. Vassilvitski, ‘How slow is the k-means method?’ SoCG2006)

In practice, the k-means algorithm is very fast (one of the fastest clustering algorithms available), but it falls in local minima. That’s why it can be useful to restart it several times.

If the algorithm stops before fully converging (because of $\text{tol}$ or $\text{max_iter}$), $\text{labels}_-$ and $\text{cluster_centers}_-$ will not be consistent, i.e. the $\text{cluster_centers}_-$ will not be the means of the points in each cluster. Also, the estimator will reassign $\text{labels}_-$ after the last iteration to make $\text{labels}_-$ consistent with $\text{predict}$ on the training set.

Examples

```python
>>> from sklearn.cluster import KMeans
>>> import numpy as np
>>> X = np.array([[1, 2], [1, 4], [1, 0], ...
... [10, 2], [10, 4], [10, 0]])
>>> kmeans = KMeans(n_clusters=2, random_state=0).fit(X)
>>> kmeans.labels_
array([1, 1, 1, 0, 0, 0], dtype=int32)
>>> kmeans.predict([[0, 0], [12, 3]])
array([1, 0], dtype=int32)
>>> kmeans.cluster_centers_
array([[10., 2.],
       [ 1., 2.]])
```

Methods

```python
fit(X[, y, sample_weight]) Compute k-means clustering.
fit_predict(X[, y, sample_weight]) Compute cluster centers and predict cluster index for each sample.
fit_transform(X[, y, sample_weight]) Compute clustering and transform X to cluster-distance space.
get_params([deep]) Get parameters for this estimator.
predict(X[, sample_weight]) Predict the closest cluster each sample in X belongs to.
score(X[, y, sample_weight]) Opposite of the value of X on the K-means objective.
set_params(**params) Set the parameters of this estimator.
transform(X) Transform X to a cluster-distance space.
```

```python
fit(X, y=None, sample_weight=None)
Compute k-means clustering.
```

Parameters

- $X$ ([array-like, sparse matrix] of shape (n_samples, n_features)) Training instances to cluster. It must be noted that the data will be converted to C ordering, which will cause a memory copy if the given data is not C-contiguous. If a sparse matrix is passed, a copy

---

**Note:** This text is based on the scikit-learn user guide, Release 0.24.0, discussing the k-means clustering algorithm and its implementation in scikit-learn. The text covers the notes, examples, and methods related to k-means clustering, including its average and worst-case complexities, and how to use it in practice. The examples demonstrate how to use the KMeans class to fit data, predict cluster labels, and transform data into cluster-distance space. The methods section outlines the functions available for k-means clustering, such as fitting the model, predicting cluster labels, and transforming data. The parameters for the `fit` method are also described, including the `X` parameter which must be provided as a training dataset.
will be made if it’s not in CSR format.

y \[\text{[Ignored]}\] Not used, present here for API consistency by convention.

**sample_weight** \[\text{array-like of shape (n\_samples,), default=None}\] The weights for each observation in X. If None, all observations are assigned equal weight.

New in version 0.20.

**Returns**

self Fitted estimator.

**fit_predict** \((X, y=\text{None, sample\_weight=\text{None}})\)

Compute cluster centers and predict cluster index for each sample.

Convenience method; equivalent to calling fit(X) followed by predict(X).

**Parameters**

- **X** \[\text{[array-like, sparse matrix] of shape (n\_samples, n\_features)}\] New data to transform.
- **y** \[\text{[Ignored]}\] Not used, present here for API consistency by convention.
- **sample_weight** \[\text{array-like of shape (n\_samples,), default=None}\] The weights for each observation in X. If None, all observations are assigned equal weight.

**Returns**

labels \[\text{ndarray of shape (n\_samples,)}\] Index of the cluster each sample belongs to.

**fit_transform** \((X, y=\text{None, sample\_weight=\text{None}})\)

Compute clustering and transform X to cluster-distance space.

Equivalent to fit(X).transform(X), but more efficiently implemented.

**Parameters**

- **X** \[\text{[array-like, sparse matrix] of shape (n\_samples, n\_features)}\] New data to transform.
- **y** \[\text{[Ignored]}\] Not used, present here for API consistency by convention.
- **sample_weight** \[\text{array-like of shape (n\_samples,), default=None}\] The weights for each observation in X. If None, all observations are assigned equal weight.

**Returns**

X\_new \[\text{ndarray of shape (n\_samples, n\_clusters)}\] X transformed in the new space.

**get_params** \((\text{deep=\text{True}})\)

Get parameters for this estimator.

**Parameters**

- **deep** \[\text{bool, default=\text{True}}\] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params \[\text{dict}\] Parameter names mapped to their values.

**predict** \((X, sample\_weight=\text{None})\)

Predict the closest cluster each sample in X belongs to.

In the vector quantization literature, `cluster\_centers_` is called the code book and each value returned by `predict` is the index of the closest code in the code book.

**Parameters**
X [\text{array-like, sparse matrix} \text{ of shape (n\_samples, n\_features)}] New data to predict.

\textbf{sample\_weight} [array-like of shape (n\_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

Returns

\textbf{labels} [ndarray of shape (n\_samples,)] Index of the cluster each sample belongs to.

\textbf{score (X, y=None, sample\_weight=None)}

Opposite of the value of X on the K-means objective.

Parameters

X [\text{array-like, sparse matrix} \text{ of shape (n\_samples, n\_features)}] New data.

y [Ignored] Not used, present here for API consistency by convention.

\textbf{sample\_weight} [array-like of shape (n\_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

Returns

\textbf{score} [float] Opposite of the value of X on the K-means objective.

\textbf{set\_params (**params)}

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \textit{Pipeline}). The latter have parameters of the form <component>\_\_<parameter> so that it’s possible to update each component of a nested object.

Parameters

\textbf{**params} [dict] Estimator parameters.

Returns

\textbf{self} [estimator instance] Estimator instance.

\textbf{transform (X)}

Transform X to a cluster-distance space.

In the new space, each dimension is the distance to the cluster centers. Note that even if X is sparse, the array returned by \textbf{transform} will typically be dense.

Parameters

X [\text{array-like, sparse matrix} \text{ of shape (n\_samples, n\_features)}] New data to transform.

Returns

\textbf{X\_new} [ndarray of shape (n\_samples, n\_clusters)] X transformed in the new space.

\textbf{Examples using sklearn.cluster.KMeans}

- Release Highlights for scikit-learn 0.23
- Demonstration of k-means assumptions
- Vector Quantization Example
- K-means Clustering
- Color Quantization using K-Means
Empirical evaluation of the impact of k-means initialization

Comparison of the K-Means and MiniBatchKMeans clustering algorithms

A demo of K-Means clustering on the handwritten digits data

Selecting the number of clusters with silhouette analysis on KMeans clustering

Clustering text documents using k-means

```
from sklearn.cluster import MiniBatchKMeans

n_clusters = 8
init = 'k-means++'
max_iter = 100
batch_size = 100
verbose = 0
compute_labels = True
random_state = None
tol = 0.0
max_no_improvement = 10
init_size = None
n_init = 3
reassignment_ratio = 0.01

Mini-Batch K-Means clustering.

Read more in the User Guide.
```

**Parameters**

- `n_clusters` [int, default=8] The number of clusters to form as well as the number of centroids to generate.

- `init` [‘k-means++’, ‘random’], callable or array-like of shape (n_clusters, n_features), default=’k-means++’ Method for initialization:

  - ‘k-means++’: selects initial cluster centers for k-mean clustering in a smart way to speed up convergence. See section Notes in k_init for more details.

  - ‘random’: choose n_clusters observations (rows) at random from data for the initial centers.

  If an array is passed, it should be of shape (n_clusters, n_features) and gives the initial centers.

  If a callable is passed, it should take arguments X, n_clusters and a random state and return an initialization.

- `max_iter` [int, default=100] Maximum number of iterations over the complete dataset before stopping independently of any early stopping criterion heuristics.

- `batch_size` [int, default=100] Size of the mini batches.

- `verbose` [int, default=0] Verbosity mode.

- `compute_labels` [bool, default=True] Compute label assignment and inertia for the complete dataset once the minibatch optimization has converged in fit.

- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for centroid initialization and random reassignment. Use an int to make the randomness deterministic. See Glossary.

- `tol` [float, default=0.0] Control early stopping based on the relative center changes as measured by a smoothed, variance-normalized of the mean center squared position changes. This early stopping heuristics is closer to the one used for the batch variant of the algorithms but induces a slight computational and memory overhead over the inertia heuristic.

  To disable convergence detection based on normalized center change, set tol to 0.0 (default).
max_no_improvement [int, default=10] Control early stopping based on the consecutive number of mini batches that does not yield an improvement on the smoothed inertia.

To disable convergence detection based on inertia, set max_no_improvement to None.

init_size [int, default=None] Number of samples to randomly sample for speeding up the initialization (sometimes at the expense of accuracy): the only algorithm is initialized by running a batch KMeans on a random subset of the data. This needs to be larger than n_clusters.

If None, init_size = 3 * batch_size.

n_init [int, default=3] Number of random initializations that are tried. In contrast to KMeans, the algorithm is only run once, using the best of the n_init initializations as measured by inertia.

reassignment_ratio [float, default=0.01] Control the fraction of the maximum number of counts for a center to be reassigned. A higher value means that low count centers are more easily reassigned, which means that the model will take longer to converge, but should converge in a better clustering.

Attributes

cluster_centers_ [ndarray of shape (n_clusters, n_features)] Coordinates of cluster centers.

labels_ [int] Labels of each point (if compute_labels is set to True).

inertia_ [float] The value of the inertia criterion associated with the chosen partition (if compute_labels is set to True). The inertia is defined as the sum of square distances of samples to their nearest neighbor.

n_iter_ [int] Number of batches processed.

counts_ [ndarray of shape (n_clusters,)] Weigth sum of each cluster.

Deprecation since version 0.24: This attribute is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).

init_size_ [int] The effective number of samples used for the initialization.

Deprecation since version 0.24: This attribute is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).

See also:

KMeans The classic implementation of the clustering method based on the Lloyd’s algorithm. It consumes the whole set of input data at each iteration.

Notes

See https://www.eecs.tufts.edu/~dsculley/papers/fastkmeans.pdf
Examples

```python
>>> from sklearn.cluster import MiniBatchKMeans
>>> import numpy as np

>>> X = np.array([[1, 2], [1, 4], [1, 0],
...               [4, 2], [4, 0], [4, 4],
...               [4, 5], [0, 1], [2, 2],
...               [3, 2], [5, 5], [1, -1]])

>>> # manually fit on batches
>>> kmeans = MiniBatchKMeans(n_clusters=2,
...                           random_state=0,
...                           batch_size=6)
>>> kmeans = kmeans.partial_fit(X[0:6,:])
>>> kmeans = kmeans.partial_fit(X[6:12,:])
>>> kmeans.cluster_centers_
array([[2. , 1. ],
       [3.5, 4.5]])

>>> kmeans.predict([[0, 0], [4, 4]])
array([0, 1], dtype=int32)

>>> # fit on the whole data
>>> kmeans = MiniBatchKMeans(n_clusters=2,
...                           random_state=0,
...                           batch_size=6,
...                           max_iter=10).fit(X)
>>> kmeans.cluster_centers_
array([[3.95918367, 2.40816327],
       [1.12195122, 1.3902439 ]])

>>> kmeans.predict([[0, 0], [4, 4]])
array([1, 0], dtype=int32)
```

Methods

- `fit(X[, y, sample_weight])`: Compute the centroids on X by chunking it into mini-batches.
- `fit_predict(X[, y, sample_weight])`: Compute cluster centers and predict cluster index for each sample.
- `fit_transform(X[, y, sample_weight])`: Compute clustering and transform X to cluster-distance space.
- `get_params([deep])`: Get parameters for this estimator.
- `partial_fit(X[, y, sample_weight])`: Update k means estimate on a single mini-batch X.
- `predict(X[, sample_weight])`: Predict the closest cluster each sample in X belongs to.
- `score(X[, y, sample_weight])`: Opposite of the value of X on the K-means objective.
- `set_params(**params)`: Set the parameters of this estimator.
- `transform(X)`: Transform X to a cluster-distance space.

```python
fit(X, y=None, sample_weight=None)
```

Compute the centroids on X by chunking it into mini-batches.

**Parameters**

- X: array-like or sparse matrix of shape (n_samples, n_features) Training instances to cluster. It must be noted that the data will be converted to C ordering, which will cause a memory copy if the given data is not C-contiguous.
y [Ignored] Not used, present here for API consistency by convention.

**sample_weight** [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight (default: None).

New in version 0.20.

Returns
self

**fit_predict** (X, y=None, sample_weight=None)

Compute cluster centers and predict cluster index for each sample.

Convenience method; equivalent to calling fit(X) followed by predict(X).

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] New data to transform.

y [Ignored] Not used, present here for API consistency by convention.

**sample_weight** [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

Returns

**labels** [ndarray of shape (n_samples,)] Index of the cluster each sample belongs to.

**fit_transform** (X, y=None, sample_weight=None)

Compute clustering and transform X to cluster-distance space.

Equivalent to fit(X).transform(X), but more efficiently implemented.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] New data to transform.

y [Ignored] Not used, present here for API consistency by convention.

**sample_weight** [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

Returns

**X_new** [ndarray of shape (n_samples, n_clusters)] X transformed in the new space.

**get_params** (deep=True)

Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**partial_fit** (X, y=None, sample_weight=None)

Update k means estimate on a single mini-batch X.

Parameters

X [array-like of shape (n_samples, n_features)] Coordinates of the data points to cluster. It must be noted that X will be copied if it is not C-contiguous.

y [Ignored] Not used, present here for API consistency by convention.
sample_weight  [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight (default: None).

Returns self

predict (X, sample_weight=None)
Predict the closest cluster each sample in X belongs to.

In the vector quantization literature, cluster_centers_ is called the code book and each value returned by predict is the index of the closest code in the code book.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] New data to predict.

sample_weight  [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight (default: None).

Returns

labels  [ndarray of shape (n_samples,)] Index of the cluster each sample belongs to.

score (X, y=None, sample_weight=None)
Opposite of the value of X on the K-means objective.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] New data.

y  [Ignored] Not used, present here for API consistency by convention.

sample_weight  [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

Returns

score  [float] Opposite of the value of X on the K-means objective.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform (X)
Transform X to a cluster-distance space.

In the new space, each dimension is the distance to the cluster centers. Note that even if X is sparse, the array returned by transform will typically be dense.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] New data to transform.

Returns

X_new  [ndarray of shape (n_samples, n_clusters)] X transformed in the new space.
Examples using `sklearn.cluster.MiniBatchKMeans`

- Biclustering documents with the Spectral Co-clustering algorithm
- Online learning of a dictionary of parts of faces
- Compare BIRCH and MiniBatchKMeans
- Empirical evaluation of the impact of k-means initialization
- Comparison of the K-Means and MiniBatchKMeans clustering algorithms
- Comparing different clustering algorithms on toy datasets
- Faces dataset decompositions
- Clustering text documents using k-means

`sklearn.cluster.MeanShift`

class `sklearn.cluster.MeanShift`(*, bandwidth=None, seeds=None, bin_seeding=False, min_bin_freq=1, cluster_all=True, n_jobs=None, max_iter=300)

Mean shift clustering using a flat kernel.

Mean shift clustering aims to discover “blobs” in a smooth density of samples. It is a centroid-based algorithm, which works by updating candidates for centroids to be the mean of the points within a given region. These candidates are then filtered in a post-processing stage to eliminate near-duplicates to form the final set of centroids.

Seeding is performed using a binning technique for scalability.

Read more in the User Guide.

Parameters

- **bandwidth** [float, default=None] Bandwidth used in the RBF kernel.
  
  If not given, the bandwidth is estimated using `sklearn.cluster.estimate_bandwidth`; see the documentation for that function for hints on scalability (see also the Notes, below).

- **seeds** [array-like of shape (n_samples, n_features), default=None] Seeds used to initialize kernels. If not set, the seeds are calculated by `clustering.get_bin_seeds` with bandwidth as the grid size and default values for other parameters.

- **bin_seeding** [bool, default=False] If true, initial kernel locations are not locations of all points, but rather the location of the discretized version of points, where points are binned onto a grid whose coarseness corresponds to the bandwidth. Setting this option to True will speed up the algorithm because fewer seeds will be initialized. The default value is False. Ignored if seeds argument is not None.

- **min_bin_freq** [int, default=1] To speed up the algorithm, accept only those bins with at least min_bin_freq points as seeds.

- **cluster_all** [bool, default=True] If true, then all points are clustered, even those orphans that are not within any kernel. Orphans are assigned to the nearest kernel. If false, then orphans are given cluster label -1.

- **n_jobs** [int, default=None] The number of jobs to use for the computation. This works by computing each of the n_init runs in parallel.
  
  None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See `Glossary` for more details.
max_iter [int, default=300] Maximum number of iterations, per seed point before the clustering operation terminates (for that seed point), if has not converged yet.

New in version 0.22.

Attributes

cluster_centers_ [ndarray of shape (n_clusters, n_features)] Coordinates of cluster centers.

labels_ [ndarray of shape (n_samples,)] Labels of each point.

n_iter_ [int] Maximum number of iterations performed on each seed.

New in version 0.22.

Notes

Scalability:

Because this implementation uses a flat kernel and a Ball Tree to look up members of each kernel, the complexity will tend towards $O(T*n*\log(n))$ in lower dimensions, with $n$ the number of samples and $T$ the number of points. In higher dimensions the complexity will tend towards $O(T*n^2)$.

Scalability can be boosted by using fewer seeds, for example by using a higher value of min_bin_freq in the get_bin_seeds function.

Note that the estimate_bandwidth function is much less scalable than the mean shift algorithm and will be the bottleneck if it is used.

References


Examples

```python
>>> from sklearn.cluster import MeanShift
>>> import numpy as np
>>> X = np.array([[1, 1], [2, 1], [1, 0],
...               [4, 7], [3, 5], [3, 6]])
>>> clustering = MeanShift(bandwidth=2).fit(X)
>>> clustering.labels_
array([1, 1, 1, 0, 0, 0])
>>> clustering.predict([[0, 0], [5, 5]])
array([1, 0])
>>> clustering
MeanShift(bandwidth=2)
```
Methods

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**fit (X, y=None)**
Perform clustering.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Samples to cluster.
- **y** [Ignored]

**fit_predict (X, y=None)**
Perform clustering on X and returns cluster labels.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Input data.
- **y** [Ignored] Not used, present for API consistency by convention.

Returns

- **labels** [ndarray of shape (n_samples,), dtype=np.int64] Cluster labels.

**get_params (deep=True)**
Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict (X)**
Predict the closest cluster each sample in X belongs to.

Parameters

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] New data to predict.

Returns

- **labels** [ndarray of shape (n_samples,)] Index of the cluster each sample belongs to.

**set_params(**params)**
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.
Returns

self [estimator instance] Estimator instance.

Examples using sklearn.cluster.MeanShift

- A demo of the mean-shift clustering algorithm
- Comparing different clustering algorithms on toy datasets

sklearn.cluster.OPTICS

class sklearn.cluster.OPTICS(*, min_samples=5, max_eps=inf, metric='minkowski', p=2, metric_params=None, cluster_method='xi', eps=None, xi=0.05, predecessor_correction=True, min_cluster_size=None, algorithm='auto', leaf_size=30, n_jobs=None)

Estimate clustering structure from vector array.

OPTICS (Ordering Points To Identify the Clustering Structure), closely related to DBSCAN, finds core sample of high density and expands clusters from them [1]. Unlike DBSCAN, keeps cluster hierarchy for a variable neighborhood radius. Better suited for usage on large datasets than the current sklearn implementation of DBSCAN.

Clusters are then extracted using a DBSCAN-like method (cluster_method = ‘dbscan’) or an automatic technique proposed in [1] (cluster_method = ‘xi’).

This implementation deviates from the original OPTICS by first performing k-nearest-neighborhood searches on all points to identify core sizes, then computing only the distances to unprocessed points when constructing the cluster order. Note that we do not employ a heap to manage the expansion candidates, so the time complexity will be O(n^2).

Read more in the User Guide.

Parameters

- min_samples [int > 1 or float between 0 and 1, default=5] The number of samples in a neighborhood for a point to be considered as a core point. Also, up and down steep regions can’t have more than min_samples consecutive non-steep points. Expressed as an absolute number or a fraction of the number of samples (rounded to be at least 2).
- max_eps [float, default=np.inf] The maximum distance between two samples for one to be considered as in the neighborhood of the other. Default value of np.inf will identify clusters across all scales; reducing max_eps will result in shorter run times.
- metric [str or callable, default=’minkowski’] Metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.

If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string. If metric is “precomputed”, X is assumed to be a distance matrix and must be square.

Valid values for metric are:

• from scipy.spatial.distance: ['braycurtis', 'canberra', 'chebyshev', 'correlation', 'dice',
  'hamming', 'jaccard', 'kulsinski', 'mahalanobis', 'minkowski', 'rogerstanimoto', 'russellrao', 'seuclidean', 'sokalmichener', 'sokalsneath', 'sqeuclidean', 'yule']

See the documentation for scipy.spatial.distance for details on these metrics.

p [int, default=2] Parameter for the Minkowski metric from pairwise_distances. When
p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p
= 2. For arbitrary p, minkowski_distance (l_p) is used.

metric_params [dict, default=None] Additional keyword arguments for the metric function.

cluster_method [str, default='xi'] The extraction method used to extract clusters using the cal-
culated reachability and ordering. Possible values are “xi” and “dbscan”.

eps [float, default=None] The maximum distance between two samples for one to be considered
as in the neighborhood of the other. By default it assumes the same value as max_eps. Used only when cluster_method='dbscan'.

xi [float between 0 and 1, default=0.05] Determines the minimum steepness on the reachability
plot that constitutes a cluster boundary. For example, an upwards point in the reachability
plot is defined by the ratio from one point to its successor being at most 1-\xi. Used only
when cluster_method='xi'.

predecessor_correction [bool, default=True] Correct clusters according to the predecessors
calculated by OPTICS \cite{optics}. This parameter has minimal effect on most datasets. Used only
when cluster_method='xi'.

min_cluster_size [int > 1 or float between 0 and 1, default=None] Minimum number of samples
in an OPTICS cluster, expressed as an absolute number or a fraction of the number of
samples (rounded to be at least 2). If None, the value of min_samples is used instead. Used only when cluster_method='xi'.

algorithm [{‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’}, default=’auto’] Algorithm used to compute
the nearest neighbors:
  • ‘ball_tree’ will use BallTree
  • ‘kd_tree’ will use KDTree
  • ‘brute’ will use a brute-force search.
  • ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed
to fit method. (default)

Note: fitting on sparse input will override the setting of this parameter, using brute force.

leaf_size [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the
speed of the construction and query, as well as the memory required to store the tree. The
optimal value depends on the nature of the problem.

n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None
means 1 unless in a joblib.parallel_backend context. -1 means using all proces-
sors. See Glossary for more details.

Attributes

labels_ [ndarray of shape (n_samples,)] Cluster labels for each point in the dataset given
to fit(). Noisy samples and points which are not included in a leaf cluster of
cluster_hierarchy_ are labeled as -1.
**reachability_** [ndarray of shape (n_samples,)] Reachability distances per sample, indexed by object order. Use clust.reachability_[clust.ordering_] to access in cluster order.

**ordering_** [ndarray of shape (n_samples,)] The cluster ordered list of sample indices.

**core_distances_** [ndarray of shape (n_samples,)] Distance at which each sample becomes a core point, indexed by object order. Points which will never be core have a distance of inf. Use clust.core_distances_[clust.ordering_] to access in cluster order.

**predecessor_** [ndarray of shape (n_samples,)] Point that a sample was reached from, indexed by object order. Seed points have a predecessor of -1.

**cluster_hierarchy_** [ndarray of shape (n_clusters, 2)] The list of clusters in the form of [start, end] in each row, with all indices inclusive. The clusters are ordered according to (end, -start) (ascending) so that larger clusters encompassing smaller clusters come after those smaller ones. Since labels_ does not reflect the hierarchy, usually len(cluster_hierarchy_) > np.unique(optics.labels_). Please also note that these indices are of the ordering_, i.e. X[ordering_][start:end + 1] form a cluster. Only available when cluster_method='xi'.

See also:

**DBSCAN** A similar clustering for a specified neighborhood radius (eps). Our implementation is optimized for runtime.

References

[1], [2]

Examples

```python
>>> from sklearn.cluster import OPTICS
>>> import numpy as np
>>> X = np.array([[1, 2], [2, 5], [3, 6], ...
...               [8, 7], [8, 8], [7, 3]])
>>> clustering = OPTICS(min_samples=2).fit(X)
>>> clustering.labels_
array([0, 0, 0, 1, 1, 1])
```

Methods

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<td><code>fit(X[, y])</code></td>
<td>Performs OPTICS clustering.</td>
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<td><code>get_params</code></td>
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<td>Set the parameters of this estimator.</td>
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**fit** *(X, y=None)*  
Perform OPTICS clustering.

Extracts an ordered list of points and reachability distances, and performs initial clustering using max_eps distance specified at OPTICS object instantiation.

Parameters
X [ndarray of shape (n_samples, n_features), or (n_samples, n_samples) if metric=’precomputed’) A feature array, or array of distances between samples if metric=’precomputed’.

y [ignored] Ignored.

Returns

self [instance of OPTICS] The instance.

fit_predict (X, y=None)
Perform clustering on X and returns cluster labels.

Parameters

X [array-like of shape (n_samples, n_features)] Input data.

y [Ignored] Not used, present for API consistency by convention.

Returns

labels [ndarray of shape (n_samples,), dtype=np.int64] Cluster labels.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.cluster.OPTICS

• Demo of OPTICS clustering algorithm
• Comparing different clustering algorithms on toy datasets
Apply clustering to a projection of the normalized Laplacian.

In practice Spectral Clustering is very useful when the structure of the individual clusters is highly non-convex or more generally when a measure of the center and spread of the cluster is not a suitable description of the complete cluster. For instance when clusters are nested circles on the 2D plane.

If affinity is the adjacency matrix of a graph, this method can be used to find normalized graph cuts.

When calling `fit`, an affinity matrix is constructed using either kernel function such the Gaussian (aka RBF) kernel of the euclidean distance d(X, X):

\[ \text{np.exp}(-\gamma \times d(X, X) ** 2) \]

or a k-nearest neighbors connectivity matrix.

Alternatively, using precomputed, a user-provided affinity matrix can be used.

Read more in the User Guide.

**Parameters**

- `n_clusters` [int, default=8] The dimension of the projection subspace.
- `eigen_solver` [‘arpack’, ‘lobpcg’, ‘amg’, default=’None’] The eigenvalue decomposition strategy to use. AMG requires pyamg to be installed. If None, then ‘arpack’ is used.
- `n_components` [int, default=n_clusters] Number of eigen vectors to use for the spectral embedding
- `random_state` [int, RandomState instance, default=’None’] A pseudo random number generator used for the initialization of the lobpcg eigen vectors decomposition when `eigen_solver=’amg’` and by the K-Means initialization. Use an int to make the randomness deterministic. See Glossary.
- `n_init` [int, default=10] Number of times the k-means algorithm will be run with different centroid seeds. The final results will be the best output of n_init consecutive runs in terms of inertia.
- `affinity` [str or callable, default=’rbf’]
  How to construct the affinity matrix.
  - ‘nearest_neighbors’ : construct the affinity matrix by computing a graph of nearest neighbors.
  - ‘rbf’ : construct the affinity matrix using a radial basis function (RBF) kernel.
  - ‘precomputed’ : interpret X as a precomputed affinity matrix.
• ‘precomputed_nearest_neighbors’ : interpret X as a sparse graph of precomputed nearest neighbors, and constructs the affinity matrix by selecting the n_neighbors nearest neighbors.

• one of the kernels supported by pairwise_kernels.

Only kernels that produce similarity scores (non-negative values that increase with similarity) should be used. This property is not checked by the clustering algorithm.

n_neighbors [int] Number of neighbors to use when constructing the affinity matrix using the nearest neighbors method. Ignored for affinity='rbf'.

eigen_tol [float, default=0.0] Stopping criterion for eigendecomposition of the Laplacian matrix when eigen_solver='arpack'.

assign_labels [{'kmeans', 'discretize'}, default='kmeans'] The strategy to use to assign labels in the embedding space. There are two ways to assign labels after the laplacian embedding. k-means can be applied and is a popular choice. But it can also be sensitive to initialization. Discretization is another approach which is less sensitive to random initialization.

degree [float, default=3] Degree of the polynomial kernel. Ignored by other kernels.

coef0 [float, default=1] Zero coefficient for polynomial and sigmoid kernels. Ignored by other kernels.

kernel_params [dict of str to any, default=None] Parameters (keyword arguments) and values for kernel passed as callable object. Ignored by other kernels.

n_jobs [int, default=None] The number of parallel jobs to run when affinity='nearest_neighbors' or affinity='precomputed_nearest_neighbors'. The neighbors search will be done in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [bool, default=False] Verbosity mode.

New in version 0.24.

Attributes

affinity_matrix_ [array-like of shape (n_samples, n_samples)] Affinity matrix used for clustering. Available only if after calling fit.

labels_ [ndarray of shape (n_samples,)] Labels of each point

Notes

If you have an affinity matrix, such as a distance matrix, for which 0 means identical elements, and high values means very dissimilar elements, it can be transformed in a similarity matrix that is well suited for the algorithm by applying the Gaussian (RBF, heat) kernel:

\[
\text{np.exp}(- \text{dist\_matrix} \times 2 / (2. \times \text{delta} \times 2))
\]

Where delta is a free parameter representing the width of the Gaussian kernel.

Another alternative is to take a symmetric version of the k nearest neighbors connectivity matrix of the points.

If the pyamg package is installed, it is used: this greatly speeds up computation.
References


Examples

```python
>>> from sklearn.cluster import SpectralClustering
>>> import numpy as np

>>> X = np.array([[1, 1], [2, 1], [1, 0], ...
   ... [4, 7], [3, 5], [3, 6]])

>>> clustering = SpectralClustering(n_clusters=2,
   ... assign_labels="discretize",
   ... random_state=0).fit(X)

>>> clustering.labels_
array([1, 1, 1, 0, 0, 0])

>>> clustering
SpectralClustering(assign_labels='discretize', n_clusters=2,
                    random_state=0)
```

Methods

- `fit(X[, y])` Perform spectral clustering from features, or affinity matrix.
- `fit_predict(X[, y])` Perform spectral clustering from features, or affinity matrix, and return cluster labels.
- `get_params([deep])` Get parameters for this estimator.
- `set_params(**params)` Set the parameters of this estimator.

```
fit(X, y=None)
```
Perform spectral clustering from features, or affinity matrix.

Parameters

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features), or array-like of shape (n_samples, n_samples)] Training instances to cluster, or similarities / affinities between instances if affinity='precomputed'. If a sparse matrix is provided in a format other than csr_matrix, csc_matrix, or coo_matrix, it will be converted into a sparse csr_matrix.

- **y** [Ignored] Not used, present here for API consistency by convention.

Returns

- **self**

```
fit_predict(X, y=None)
```
Perform spectral clustering from features, or affinity matrix, and return cluster labels.

Parameters

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features), or array-like of shape (n_samples, n_samples)] Training instances to cluster, or similarities / affinities between instances if affinity='precomputed'. If a sparse matrix is provided in a format other than csr_matrix, csc_matrix, or coo_matrix, it will be converted into a sparse csr_matrix.

- **y** [Ignored] Not used, present here for API consistency by convention.
X \{[\text{array-like, sparse matrix}] \text{ of shape } (n\_samples, n\_features), \text{ or array-like of shape } (n\_samples, n\_samples)\} \text{ Training instances to cluster, or similarities / affinities between instances if } \text{affinity}='\text{precomputed}'. \text{ If a sparse matrix is provided in a format other than } \text{csr\_matrix}, \text{csc\_matrix}, \text{or } \text{coo\_matrix}, \text{it will be converted into a sparse } \text{csr\_matrix}.

y \{\text{Ignored}\} \text{ Not used, present here for API consistency by convention.}

Returns

labels \{\text{ndarray of shape } (n\_samples,)\} \text{ Cluster labels.}

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep \{bool, default=True\} \text{ If True, will return the parameters for this estimator and contained subobjects that are estimators.}

Returns

params \{dict\} \text{ Parameter names mapped to their values.}

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \text{<component>\_<parameter>} so that it’s possible to update each component of a nested object.

Parameters

**params \{dict\} \text{ Estimator parameters.}

Returns

self \{estimator instance\} \text{ Estimator instance.}

Examples using sklearn.cluster.SpectralClustering

- Comparing different clustering algorithms on toy datasets

sklearn.cluster.SpectralBiclustering

class sklearn.cluster.SpectralBiclustering (n\_clusters=3, *, method='bistochastic', n\_components=6, n\_best=3, svd\_method='randomized', n\_svd\_vecs=None, mini\_batch=False, init='k-means++', n\_init=10, n\_jobs='deprecated', random\_state=None)

Spectral biclustering (Kluger, 2003).

Partitions rows and columns under the assumption that the data has an underlying checkerboard structure. For instance, if there are two row partitions and three column partitions, each row will belong to three biclusters, and each column will belong to two biclusters. The outer product of the corresponding row and column label vectors gives this checkerboard structure.

Read more in the User Guide.
n_clusters [int or tuple (n_row_clusters, n_column_clusters), default=3] The number of row and column clusters in the checkerboard structure.

method [{'bistochastic', 'scale', 'log'}, default='bistochastic'] Method of normalizing and converting singular vectors into biclusters. May be one of 'scale', 'bistochastic', or 'log'. The authors recommend using 'log'. If the data is sparse, however, log normalization will not work, which is why the default is 'bistochastic'.

Warning: if method='log', the data must be sparse.

n_components [int, default=6] Number of singular vectors to check.

n_best [int, default=3] Number of best singular vectors to which to project the data for clustering.

svd_method [{'randomized', 'arpack'}, default='randomized'] Selects the algorithm for finding singular vectors. May be 'randomized' or 'arpack'. If 'randomized', uses randomized_svd, which may be faster for large matrices. If 'arpack', uses scipy.sparse.linalg.svds, which is more accurate, but possibly slower in some cases.

n_svd_vecs [int, default=None] Number of vectors to use in calculating the SVD. Corresponds to ncv when svd_method=arpack and n_oversamples when svd_method is 'randomized'.

mini_batch [bool, default=False] Whether to use mini-batch k-means, which is faster but may get different results.

init [{'k-means++', 'random'} or ndarray of (n_clusters, n_features), default='k-means++'] Method for initialization of k-means algorithm; defaults to 'k-means++'.

n_init [int, default=10] Number of random initializations that are tried with the k-means algorithm.

If mini-batch k-means is used, the best initialization is chosen and the algorithm runs once. Otherwise, the algorithm is run for each initialization and the best solution chosen.

n_jobs [int, default=None] The number of jobs to use for the computation. This works by breaking down the pairwise matrix into n_jobs even slices and computing them in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Deprecated since version 0.23: n_jobs was deprecated in version 0.23 and will be removed in 1.0 (renaming of 0.25).

random_state [int, RandomState instance, default=None] Used for randomizing the singular value decomposition and the k-means initialization. Use an int to make the randomness deterministic. See Glossary.

Attributes

rows_ [array-like of shape (n_row_clusters, n_rows)] Results of the clustering. rows[i, r] is True if cluster i contains row r. Available only after calling fit.

columns_ [array-like of shape (n_column_clusters, n_columns)] Results of the clustering, like rows.

row_labels_ [array-like of shape (n_rows,)] Row partition labels.

column_labels_ [array-like of shape (n_cols,)] Column partition labels.
References

- Kluger, Yuval, et. al., 2003. Spectral biclustering of microarray data: co-clustering genes and conditions.

Examples

```python
>>> from sklearn.cluster import SpectralBiclustering
>>> import numpy as np
>>> X = np.array([[1, 1], [2, 1], [1, 0],
...               [4, 7], [3, 5], [3, 6]])
>>> clustering = SpectralBiclustering(n_clusters=2, random_state=0).fit(X)
>>> clustering.row_labels_
array([1, 1, 1, 0, 0, 0], dtype=int32)
>>> clustering.column_labels_
array([0, 1], dtype=int32)
>>> clustering
SpectralBiclustering(n_clusters=2, random_state=0)
```

Methods

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**property biclusters_**
Convenient way to get row and column indicators together.

Returns the `rows_` and `columns_` members.

**fit**(X, y=None)
Creates a biclustering for X.

Parameters

- **X** [array-like of shape (n_samples, n_features)]
- **y** [Ignored]

**get_indices**(i)
Row and column indices of the i’th bicluster.

Only works if `rows_` and `columns_` attributes exist.

Parameters

- **i** [int] The index of the cluster.

Returns

- **row_ind** [ndarray, dtype=np.intp] Indices of rows in the dataset that belong to the bicluster.
- **col_ind** [ndarray, dtype=np.intp] Indices of columns in the dataset that belong to the bicluster.
get_params (deep=True)
Get parameters for this estimator.

Parameters
- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
- params [dict] Parameter names mapped to their values.

get_shape (i)
Shape of the i’th bicluster.

Parameters
- i [int] The index of the cluster.

Returns
- n_rows [int] Number of rows in the bicluster.
- n_cols [int] Number of columns in the bicluster.

get_submatrix (i, data)
Return the submatrix corresponding to bicluster i.

Parameters
- i [int] The index of the cluster.
- data [array-like of shape (n_samples, n_features)] The data.

Returns
- submatrix [ndarray of shape (n_rows, n_cols)] The submatrix corresponding to bicluster i.

Notes
Works with sparse matrices. Only works if rows_ and columns_ attributes exist.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters
- **params [dict] Estimator parameters.

Returns
Examples using `sklearn.cluster.SpectralBiclustering`

- A demo of the Spectral Biclustering algorithm

`sklearn.cluster.SpectralCoclustering`

class `sklearn.cluster.SpectralCoclustering`(n_clusters=3, *, svd_method='randomized', n_svd_vecs=None, mini_batch=False, init='k-means++', n_init=10, n_jobs='deprecated', random_state=None)

Spectral Co-Clustering algorithm (Dhillon, 2001).

Clusters rows and columns of an array \( X \) to solve the relaxed normalized cut of the bipartite graph created from \( X \) as follows: the edge between row vertex \( i \) and column vertex \( j \) has weight \( X[i, j] \).

The resulting bicluster structure is block-diagonal, since each row and each column belongs to exactly one bicluster.

Supports sparse matrices, as long as they are nonnegative.

Read more in the User Guide.

Parameters

n_clusters [int, default=3] The number of biclusters to find.

svd_method [{'randomized', 'arpack'}, default='randomized'] Selects the algorithm for finding singular vectors. May be 'randomized' or 'arpack'. If 'randomized', use `sklearn.utils.extmath.randomized_svd`, which may be faster for large matrices. If 'arpack', use `scipy.sparse.linalg.svds`, which is more accurate, but possibly slower in some cases.

n_svd_vecs [int, default=None] Number of vectors to use in calculating the SVD. Corresponds to `ncv` when `svd_method=arpack` and `n_oversamples` when `svd_method` is 'randomized'.

mini_batch [bool, default=False] Whether to use mini-batch k-means, which is faster but may get different results.

init [{'k-means++', 'random', or ndarray of shape (n_clusters, n_features), default='k-means++'} Method for initialization of k-means algorithm; defaults to 'k-means++'.

n_init [int, default=10] Number of random initializations that are tried with the k-means algorithm. If mini-batch k-means is used, the best initialization is chosen and the algorithm runs once. Otherwise, the algorithm is run for each initialization and the best solution chosen.

n_jobs [int, default=None] The number of jobs to use for the computation. This works by breaking down the pairwise matrix into n_jobs even slices and computing them in parallel.

None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Deprecated since version 0.23: `n_jobs` was deprecated in version 0.23 and will be removed in 1.0 (renaming of 0.25).

random_state [int, RandomState instance, default=None] Used for randomizing the singular value decomposition and the k-means initialization. Use an int to make the randomness deterministic. See Glossary.

Attributes
rows_ [array-like of shape (n_row_clusters, n_rows)] Results of the clustering. rows[i, r] is True if cluster i contains row r. Available only after calling fit.

columns_ [array-like of shape (n_column_clusters, n_columns)] Results of the clustering, like rows.

row_labels_ [array-like of shape (n_rows,)] The bicluster label of each row.
column_labels_ [array-like of shape (n_cols,)] The bicluster label of each column.

References


Examples

```python
>>> from sklearn.cluster import SpectralCoclustering
>>> import numpy as np

>>> X = np.array([[1, 1], [2, 1], [1, 0], ...
                 [4, 7], [3, 5], [3, 6]])

>>> clustering = SpectralCoclustering(n_clusters=2, random_state=0).fit(X)
>>> clustering.row_labels_
array([0, 1, 1, 0, 0, 0], dtype=int32)

>>> clustering.column_labels_
array([0, 0], dtype=int32)
>>> clustering
SpectralCoclustering(n_clusters=2, random_state=0)
```

Methods

fit(X[, y]) Creates a biclustering for X.

get_indices(i) Row and column indices of the i’th bicluster. Only works if rows_ and columns_ attributes exist.

get_params([deep]) Get parameters for this estimator.

get_shape(i) Shape of the i’th bicluster.

get_submatrix(i, data) Return the submatrix corresponding to bicluster i.

set_params(**params) Set the parameters of this estimator.

property biclusters_ Convenient way to get row and column indicators together. Returns the rows_ and columns_ members.

fit (X, y=None) Creates a biclustering for X.

Parameters

X [array-like of shape (n_samples, n_features)]

y [Ignored]

get_indices (i) Row and column indices of the i’th bicluster. Only works if rows_ and columns_ attributes exist.
Parameters

i [int] The index of the cluster.

Returns

row_ind [ndarray, dtype=np.intp] Indices of rows in the dataset that belong to the bicluster.

col_ind [ndarray, dtype=np.intp] Indices of columns in the dataset that belong to the bicluster.

get_params (deep=True)
Get parameters for this estimator.

Parameters

dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

get_shape (i)
Shape of the i’th bicluster.

Parameters

i [int] The index of the cluster.

Returns

n_rows [int] Number of rows in the bicluster.

n_cols [int] Number of columns in the bicluster.

get_submatrix (i, data)
Return the submatrix corresponding to bicluster i.

Parameters

i [int] The index of the cluster.

data [array-like of shape (n_samples, n_features)] The data.

Returns

submatrix [ndarray of shape (n_rows, n_cols)] The submatrix corresponding to bicluster i.

Notes

Works with sparse matrices. Only works if rows_ and columns_ attributes exist.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.cluster.SpectralCoclustering`

- A demo of the Spectral Co-Clustering algorithm
- Biclustering documents with the Spectral Co-clustering algorithm

### 7.3.2 Functions

- `cluster.affinity_propagation(S, *[, ...])` Perform Affinity Propagation Clustering of data.
- `cluster.cluster_optics_dbscan(*[, ...])` Performs DBSCAN extraction for an arbitrary epsilon.
- `cluster.cluster_optics_xi(*[, reachability, ...])` Automatically extract clusters according to the Xi-steep method.
- `cluster.compute_optics_graph(X, *[, ...])` Computes the OPTICS reachability graph.
- `cluster.dbscan(X[, eps, min_samples, ...])` Perform DBSCAN clustering from vector array or distance matrix.
- `cluster.estimate_bandwidth(X, *[, quantile, ...])` Estimate the bandwidth to use with the mean-shift algorithm.
- `cluster.k_means(X, n_clusters, *[, ...])` K-means clustering algorithm.
- `cluster.kmeans_plusplus(X, n_clusters, *[, ...])` Init n_clusters seeds according to k-means++
- `cluster.mean_shift(X, *[, bandwidth, seeds, ...])` Perform mean shift clustering of data using a flat kernel.
- `cluster.spectral_clustering(affinity, *[, ...])` Apply clustering to a projection of the normalized Laplacian.
- `cluster.ward_tree(X, *[, connectivity, ...])` Ward clustering based on a Feature matrix.

### sklearn.cluster.affinity_propagation

Perform Affinity Propagation Clustering of data.

**Parameters**

- `S` [array-like of shape (n_samples, n_samples)] Matrix of similarities between points.
- `preference` [array-like of shape (n_samples,) or float, default=None] Preferences for each point - points with larger values of preferences are more likely to be chosen as exemplars. The number of exemplars, i.e. of clusters, is influenced by the input preferences value. If the preferences are not passed as arguments, they will be set to the median of the input similarities (resulting in a moderate number of clusters). For a smaller amount of clusters, this can be set to the minimum value of the similarities.
- `convergence_iter` [int, default=15] Number of iterations with no change in the number of estimated clusters that stops the convergence.
- `max_iter` [int, default=200] Maximum number of iterations
- `damping` [float, default=0.5] Damping factor between 0.5 and 1.
copy [bool, default=True] If copy is False, the affinity matrix is modified inplace by the algorithm, for memory efficiency.

verbose [bool, default=False] The verbosity level.

return_n_iter [bool, default=False] Whether or not to return the number of iterations.

random_state [int, RandomState instance or None, default=0] Pseudo-random number generator to control the starting state. Use an int for reproducible results across function calls. See the Glossary.

New in version 0.23: this parameter was previously hardcoded as 0.

Returns

cluster_centers_indices [ndarray of shape (n_clusters,)] Index of clusters centers.

labels [ndarray of shape (n_samples,)] Cluster labels for each point.

n_iter [int] Number of iterations run. Returned only if return_n_iter is set to True.

Notes

For an example, see examples/cluster/plot_affinity_propagation.py.

When the algorithm does not converge, it returns an empty array as cluster_center_indices and -1 as label for each training sample.

When all training samples have equal similarities and equal preferences, the assignment of cluster centers and labels depends on the preference. If the preference is smaller than the similarities, a single cluster center and label 0 for every sample will be returned. Otherwise, every training sample becomes its own cluster center and is assigned a unique label.

References


Examples using sklearn.cluster.affinity_propagation

• Visualizing the stock market structure

sklearn.cluster.cluster_optics_dbscan

sklearn.cluster.cluster_optics_dbscan (*, reachability, core_distances, ordering, eps)
Performs DBSCAN extraction for an arbitrary epsilon.

Extracting the clusters runs in linear time. Note that this results in labels_ which are close to a DBSCAN with similar settings and eps, only if eps is close to max_eps.

Parameters

reachability [array of shape (n_samples,)] Reachability distances calculated by OPTICS (reachability_)

core_distances [array of shape (n_samples,)] Distances at which points become core (core_distances_)

ordering [array of shape (n_samples,)] OPTICS ordered point indices (ordering_)
**eps** [float] DBSCAN **eps** parameter. Must be set to < **max_eps**. Results will be close to DBSCAN algorithm if **eps** and **max_eps** are close to one another.

**Returns**

- **labels** [array of shape (n_samples,)] The estimated labels.

**Examples using sklearn.cluster.cluster_optics_dbscan**

- **Demo of OPTICS clustering algorithm**

**sklearn.cluster.cluster_optics_xi**

```python
sklearn.cluster.cluster_optics_xi(*, reachability, predecessor, ordering, min_samples,
min_cluster_size=None, xi=0.05, predecessor_correction=True)
```

Automatically extract clusters according to the Xi-steep method.

**Parameters**

- **reachability** [ndarray of shape (n_samples,)] Reachability distances calculated by OPTICS (reachability_)
- **predecessor** [ndarray of shape (n_samples,)] Predecessors calculated by OPTICS.
- **ordering** [ndarray of shape (n_samples,)] OPTICS ordered point indices (ordering_)
- **min_samples** [int > 1 or float between 0 and 1] The same as the min_samples given to OPTICS. Up and down steep regions can’t have more then min_samples consecutive non-steep points. Expressed as an absolute number or a fraction of the number of samples (rounded to be at least 2).
- **min_cluster_size** [int > 1 or float between 0 and 1, default=None] Minimum number of samples in an OPTICS cluster, expressed as an absolute number or a fraction of the number of samples (rounded to be at least 2). If None, the value of min_samples is used instead.
- **xi** [float between 0 and 1, default=0.05] Determines the minimum steepness on the reachability plot that constitutes a cluster boundary. For example, an upwards point in the reachability plot is defined by the ratio from one point to its successor being at most 1-xi.
- **predecessor_correction** [bool, default=True] Correct clusters based on the calculated predecessors.

**Returns**

- **labels** [ndarray of shape (n_samples,)] The labels assigned to samples. Points which are not included in any cluster are labeled as -1.
- **clusters** [ndarray of shape (n_clusters, 2)] The list of clusters in the form of [start, end] in each row, with all indices inclusive. The clusters are ordered according to (end, -start) (ascending) so that larger clusters encompassing smaller clusters come after such nested smaller clusters. Since **labels** does not reflect the hierarchy, usually len(clusters) > np.unique(labels).
sklearn.cluster.compute_optics_graph

Computes the OPTICS reachability graph.

Read more in the User Guide.

Parameters

- **X** [ndarray of shape (n_samples, n_features), or (n_samples, n_samples) if metric='precomputed'.] A feature array, or an array of distances between samples if metric='precomputed'

- **min_samples** [int > 1 or float between 0 and 1] The number of samples in a neighborhood for a point to be considered as a core point. Expressed as an absolute number or a fraction of the number of samples (rounded to be at least 2).

- **max_eps** [float, default=np.inf] The maximum distance between two samples for one to be considered as in the neighborhood of the other. Default value of np.inf will identify clusters across all scales; reducing max_eps will result in shorter run times.

- **metric** [str or callable, default='minkowski'] Metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.

  If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string. If metric is “precomputed”, X is assumed to be a distance matrix and must be square.

  Valid values for metric are:

  - from scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']

  See the documentation for scipy.spatial.distance for details on these metrics.

- **p** [int, default=2] Parameter for the Minkowski metric from pairwise_distances. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

- **metric_params** [dict, default=None] Additional keyword arguments for the metric function.

- **algorithm** [‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default=’auto’) Algorithm used to compute the nearest neighbors:

  - ‘ball_tree’ will use BallTree
  - ‘kd_tree’ will use KDTree
  - ‘brute’ will use a brute-force search.
  - ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to fit method. (default)

  Note: fitting on sparse input will override the setting of this parameter, using brute force.

- **leaf_size** [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.
n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Returns

ordering_ [array of shape (n_samples,)] The cluster ordered list of sample indices.

core_distances_ [array of shape (n_samples,)] Distance at which each sample becomes a core point, indexed by object order. Points which will never be core have a distance of inf. Use clust.core_distances_[clust.ordering_] to access in cluster order.

reachability_ [array of shape (n_samples,)] Reachability distances per sample, indexed by object order. Use clust.reachability_[clust.ordering_] to access in cluster order.

predecessor_ [array of shape (n_samples,)] Point that a sample was reached from, indexed by object order. Seed points have a predecessor of -1.

References

[1]

sklearn.cluster.dbSCAN

sklearn.cluster.dbSCAN (X, eps=0.5, *, min_samples=5, metric='minkowski', metric_params=None, algorithm='auto', leaf_size=30, p=2, sample_weight=None, n_jobs=None)

Perform DBSCAN clustering from vector array or distance matrix.

Read more in the User Guide.

Parameters

X [{array-like, sparse (CSR) matrix} of shape (n_samples, n_features) or (n_samples, n_samples)] A feature array, or array of distances between samples if metric='precomputed'.

eps [float, default=0.5] The maximum distance between two samples for one to be considered as in the neighborhood of the other. This is not a maximum bound on the distances of points within a cluster. This is the most important DBSCAN parameter to choose appropriately for your data set and distance function.

min_samples [int, default=5] The number of samples (or total weight) in a neighborhood for a point to be considered as a core point. This includes the point itself.

metric [str or callable, default='minkowski'] The metric to use when calculating distance between instances in a feature array. If metric is a string or callable, it must be one of the options allowed by sklearn.metrics.pairwise_distances for its metric parameter. If metric is "precomputed", X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.

metric_params [dict, default=None] Additional keyword arguments for the metric function.

New in version 0.19.

algorithm [[‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default='auto'] The algorithm to be used by the NearestNeighbors module to compute pointwise distances and find nearest neighbors. See NearestNeighbors module documentation for details.
leaf_size [int, default=30] Leaf size passed to BallTree or cKDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

p [float, default=2] The power of the Minkowski metric to be used to calculate distance between points.

sample_weight [array-like of shape (n_samples,), default=None] Weight of each sample, such that a sample with a weight of at least min_samples is by itself a core sample; a sample with negative weight may inhibit its eps-neighbor from being core. Note that weights are absolute, and default to 1.

n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details. If precomputed distance are used, parallel execution is not available and thus n_jobs will have no effect.

Returns

core_samples [ndarray of shape (n_core_samples,)] Indices of core samples.

labels [ndarray of shape (n_samples,)] Cluster labels for each point. Noisy samples are given the label -1.

See also:

DBSCAN An estimator interface for this clustering algorithm.

OPTICS A similar estimator interface clustering at multiple values of eps. Our implementation is optimized for memory usage.

Notes

For an example, see examples/cluster/plot_dbscan.py.

This implementation bulk-computes all neighborhood queries, which increases the memory complexity to O(n.d) where d is the average number of neighbors, while original DBSCAN had memory complexity O(n). It may attract a higher memory complexity when querying these nearest neighborhoods, depending on the algorithm.

One way to avoid the query complexity is to pre-compute sparse neighborhoods in chunks using NearestNeighbors.radius_neighbors_graph with mode='distance', then using metric='precomputed' here.

Another way to reduce memory and computation time is to remove (near-)duplicate points and use sample_weight instead.

cluster.optics provides a similar clustering with lower memory usage.
References


sklearn.cluster.estimate_bandwidth

sklearn.cluster.estimate_bandwidth(X, *, quantile=0.3, n_samples=None, random_state=0, n_jobs=None)

Estimate the bandwidth to use with the mean-shift algorithm.

That this function takes time at least quadratic in n_samples. For large datasets, it’s wise to set that parameter to a small value.

Parameters

- X [array-like of shape (n_samples, n_features)] Input points.
- quantile [float, default=0.3] should be between [0, 1] 0.5 means that the median of all pairwise distances is used.
- n_samples [int, default=None] The number of samples to use. If not given, all samples are used.
- random_state [int, RandomState instance, default=None] The generator used to randomly select the samples from input points for bandwidth estimation. Use an int to make the randomness deterministic. See Glossary.
- n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Returns

- bandwidth [float] The bandwidth parameter.

Examples using sklearn.cluster.estimate_bandwidth

- A demo of the mean-shift clustering algorithm
- Comparing different clustering algorithms on toy datasets

sklearn.cluster.k_means

sklearn.cluster.k_means(X, n_clusters, *, sample_weight=None, init='k-means++', precompute_distances='deprecated', n_init=10, max_iter=300, verbose=False, tol=0.0001, random_state=None, copy_x=True, n_jobs='deprecated', algorithm='auto', return_n_iter=False)

K-means clustering algorithm.

Read more in the User Guide.

Parameters
X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The observations to cluster. It must be noted that the data will be converted to C ordering, which will cause a memory copy if the given data is not C-contiguous.

n_clusters  [int] The number of clusters to form as well as the number of centroids to generate.

sample_weight  [array-like of shape (n_samples,), default=None] The weights for each observation in X. If None, all observations are assigned equal weight.

init  [{'k-means++', 'random'}, callable or array-like of shape (n_clusters, n_features), default='k-means++'] Method for initialization:

  'k-means++' : selects initial cluster centers for k-mean clustering in a smart way to speed up convergence. See section Notes in k_init for more details.

  'random': choose n_clusters observations (rows) at random from data for the initial centroids.

If an array is passed, it should be of shape (n_clusters, n_features) and gives the initial centers.

If a callable is passed, it should take arguments X, n_clusters and a random state and return an initialization.

precompute_distances  [{'auto', True, False}] Precompute distances (faster but takes more memory).

  'auto' : do not precompute distances if n_samples * n_clusters > 12 million. This corresponds to about 100MB overhead per job using double precision.

  True : always precompute distances

  False : never precompute distances

  Deprecated since version 0.23: ‘precompute_distances’ was deprecated in version 0.23 and will be removed in 1.0 (renaming of 0.25). It has no effect.

n_init  [int, default=10] Number of time the k-means algorithm will be run with different centroid seeds. The final results will be the best output of n_init consecutive runs in terms of inertia.

max_iter  [int, default=300] Maximum number of iterations of the k-means algorithm to run.

verbose  [bool, default=False] Verbosity mode.

tol  [float, default=1e-4] Relative tolerance with regards to Frobenius norm of the difference in the cluster centers of two consecutive iterations to declare convergence.

random_state  [int, RandomState instance or None, default=None] Determines random number generation for centroid initialization. Use an int to make the randomness deterministic. See Glossary.

copy_x  [bool, default=True] When pre-computing distances it is more numerically accurate to center the data first. If copy_x is True (default), then the original data is not modified. If False, the original data is modified, and put back before the function returns, but small numerical differences may be introduced by subtracting and then adding the data mean. Note that if the original data is not C-contiguous, a copy will be made even if copy_x is False. If the original data is sparse, but not in CSR format, a copy will be made even if copy_x is False.

n_jobs  [int, default=None] The number of OpenMP threads to use for the computation. Parallelism is sample-wise on the main cython loop which assigns each sample to its closest center.
None or -1 means using all processors.

Deprecated since version 0.23: n_jobs was deprecated in version 0.23 and will be removed in 1.0 (renaming of 0.25).

algorithm [{“auto”, “full”, “elkan”}, default=“auto”] K-means algorithm to use. The classical EM-style algorithm is “full”. The “elkan” variation is more efficient on data with well-defined clusters, by using the triangle inequality. However it’s more memory intensive due to the allocation of an extra array of shape (n_samples, n_clusters).

For now “auto” (kept for backward compatibility) chooses “elkan” but it might change in the future for a better heuristic.

return_n_iter [bool, default=False] Whether or not to return the number of iterations.

Returns
- centroid [ndarray of shape (n_clusters, n_features)] Centroids found at the last iteration of k-means.
- label [ndarray of shape (n_samples,)] label[i] is the code or index of the centroid the i’th observation is closest to.
- inertia [float] The final value of the inertia criterion (sum of squared distances to the closest centroid for all observations in the training set).
- best_n_iter [int] Number of iterations corresponding to the best results. Returned only if return_n_iter is set to True.

sklearn.cluster.kmeans_plusplus

sklearn.cluster.kmeans_plusplus(X, n_clusters, *, x_squared_norms=None, random_state=None, n_local_trials=None)

Init n_clusters seeds according to k-means++

New in version 0.24.

Parameters
- X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to pick seeds from.
- n_clusters [int] The number of centroids to initialize
- x_squared_norms [array-like of shape (n_samples,), default=None] Squared Euclidean norm of each data point.
- random_state [int or RandomState instance, default=None] Determines random number generation for centroid initialization. Pass an int for reproducible output across multiple function calls. See Glossary.
- n_local_trials [int, default=None] The number of seeding trials for each center (except the first), of which the one reducing inertia the most is greedily chosen. Set to None to make the number of trials depend logarithmically on the number of seeds (2+log(k)).

Returns
- centers [ndarray of shape (n_clusters, n_features)] The initial centers for k-means.
- indices [ndarray of shape (n_clusters,)] The index location of the chosen centers in the data array X. For a given index and center, X[index] = center.
Notes

Selects initial cluster centers for k-mean clustering in a smart way to speed up convergence. see: Arthur, D. and Vassilvitskii, S. “k-means++: the advantages of careful seeding”. ACM-SIAM symposium on Discrete algorithms. 2007

Examples

```python
>>> from sklearn.cluster import kmeans_plusplus
>>> import numpy as np
>>> X = np.array([[1, 2], [1, 4], [1, 0], ...
    [10, 2], [10, 4], [10, 0]])
>>> centers, indices = kmeans_plusplus(X, n_clusters=2, random_state=0)
>>> centers
array([[10, 4],
       [ 1, 0]])
>>> indices
array([4, 2])
```

Examples using sklearn.cluster.kmeans_plusplus

- An example of K-Means++ initialization

sklearn.cluster.mean_shift

sklearn.cluster.mean_shift (X, *, bandwidth=None, seeds=None, bin_seeding=False, min_bin_freq=1, cluster_all=True, max_iter=300, n_jobs=None)

Perform mean shift clustering of data using a flat kernel.

Read more in the User Guide.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Input data.
  - **bandwidth** [float, default=None] Kernel bandwidth.
    - If bandwidth is not given, it is determined using a heuristic based on the median of all pairwise distances. This will take quadratic time in the number of samples. The sklearn.cluster.estimate_bandwidth function can be used to do this more efficiently.
  - **seeds** [array-like of shape (n_seeds, n_features) or None] Point used as initial kernel locations. If None and bin_seeding=False, each data point is used as a seed. If None and bin_seeding=True, see bin_seeding.
  - **bin_seeding** [bool, default=False] If true, initial kernel locations are not locations of all points, but rather the location of the discretized version of points, where points are binned onto a grid whose coarseness corresponds to the bandwidth. Setting this option to True will speed up the algorithm because fewer seeds will be initialized. Ignored if seeds argument is not None.
  - **min_bin_freq** [int, default=1] To speed up the algorithm, accept only those bins with at least min_bin_freq points as seeds.
**cluster_all** [bool, default=True] If true, then all points are clustered, even those orphans that are not within any kernel. Orphans are assigned to the nearest kernel. If false, then orphans are given cluster label -1.

**max_iter** [int, default=300] Maximum number of iterations, per seed point before the clustering operation terminates (for that seed point), if has not converged yet.

**n_jobs** [int, default=None] The number of jobs to use for the computation. This works by computing each of the n_init runs in parallel.

None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See `Glossary` for more details.

New in version 0.17: Parallel Execution using `n_jobs`.

Returns

**cluster_centers** [ndarray of shape (n_clusters, n_features)] Coordinates of cluster centers.

**labels** [ndarray of shape (n_samples,)] Cluster labels for each point.

Notes

For an example, see `examples/cluster/plot_mean_shift.py`.

**sklearn.cluster.spectral_clustering**

```python
sklearn.cluster.spectral_clustering(affinity, *, n_clusters=8, n_components=None,
  eigen_solver=None, random_state=None, n_init=10,
  eigen_tol=0.0, assign_labels='kmeans', verbose=False)
```

Apply clustering to a projection of the normalized Laplacian.

In practice Spectral Clustering is very useful when the structure of the individual clusters is highly non-convex or more generally when a measure of the center and spread of the cluster is not a suitable description of the complete cluster. For instance, when clusters are nested circles on the 2D plane.

If affinity is the adjacency matrix of a graph, this method can be used to find normalized graph cuts.

Read more in the `User Guide`.

Parameters

**affinity** [[array-like, sparse matrix] of shape (n_samples, n_samples)] The affinity matrix describing the relationship of the samples to embed. **Must be symmetric.**

Possible examples:

- adjacency matrix of a graph,
- heat kernel of the pairwise distance matrix of the samples,
- symmetric k-nearest neighbours connectivity matrix of the samples.

**n_clusters** [int, default=None] Number of clusters to extract.

**n_components** [int, default=n_clusters] Number of eigen vectors to use for the spectral embedding

**eigen_solver** [[None, ‘arpack’, ‘lobpcg’, or ‘amg’]] The eigenvalue decomposition strategy to use. AMG requires pyamg to be installed. It can be faster on very large, sparse problems, but may also lead to instabilities. If None, then ‘arpack’ is used.
**random_state** [int, RandomState instance, default=None] A pseudo random number generator used for the initialization of the lobpcg eigen vectors decomposition when eigen_solver == 'amg' and by the K-Means initialization. Use an int to make the randomness deterministic. See Glossary.

**n_init** [int, default=10] Number of time the k-means algorithm will be run with different centroid seeds. The final results will be the best output of n_init consecutive runs in terms of inertia.

**eigen_tol** [float, default=0.0] Stopping criterion for eigendecomposition of the Laplacian matrix when using arpack eigen_solver.

**assign_labels** [{'kmeans', 'discretize'}, default='kmeans'] The strategy to use to assign labels in the embedding space. There are two ways to assign labels after the laplacian embedding: k-means can be applied and is a popular choice. But it can also be sensitive to initialization. Discretization is another approach which is less sensitive to random initialization. See the ‘Multiclass spectral clustering’ paper referenced below for more details on the discretization approach.

**verbose** [bool, default=False] Verbosity mode.

New in version 0.24.

**Returns**

**labels** [array of integers, shape: n_samples] The labels of the clusters.

**Notes**

The graph should contain only one connect component, elsewhere the results make little sense.

This algorithm solves the normalized cut for k=2: it is a normalized spectral clustering.

**References**


**Examples using sklearn.cluster.spectral_clustering**

- Segmenting the picture of greek coins in regions
- Spectral clustering for image segmentation
sklearn.cluster.ward_tree

sklearn.cluster.ward_tree(X, *, connectivity=None, n_clusters=None, return_distance=False)

Ward clustering based on a Feature matrix.

Recursively merges the pair of clusters that minimally increases within-cluster variance.

The inertia matrix uses a Heapq-based representation.

This is the structured version, that takes into account some topological structure between samples.

Read more in the User Guide.

Parameters

X [array-like of shape (n_samples, n_features)] feature matrix representing n_samples samples to be clustered

connectivity [sparse matrix, default=None] connectivity matrix. Defines for each sample the neighboring samples following a given structure of the data. The matrix is assumed to be symmetric and only the upper triangular half is used. Default is None, i.e, the Ward algorithm is unstructured.

n_clusters [int, default=None] Stop early the construction of the tree at n_clusters. This is useful to decrease computation time if the number of clusters is not small compared to the number of samples. In this case, the complete tree is not computed, thus the ‘children’ output is of limited use, and the ‘parents’ output should rather be used. This option is valid only when specifying a connectivity matrix.

return_distance [bool, default=None] If True, return the distance between the clusters.

Returns

children [ndarray of shape (n_nodes-1, 2)] The children of each non-leaf node. Values less than n_samples correspond to leaves of the tree which are the original samples. A node i greater than or equal to n_samples is a non-leaf node and has children children_[i - n_samples]. Alternatively at the i-th iteration, children[i][0] and children[i][1] are merged to form node n_samples + i

n_connected_components [int] The number of connected components in the graph.

n_leaves [int] The number of leaves in the tree

parents [ndarray of shape (n_nodes,) or None] The parent of each node. Only returned when a connectivity matrix is specified, elsewhere ‘None’ is returned.

distances [ndarray of shape (n_nodes-1,)] Only returned if return_distance is set to True (for compatibility). The distances between the centers of the nodes. distances[i] corresponds to a weighted euclidean distance between the nodes children[i, 1] and children[i, 2]. If the nodes refer to leaves of the tree, then distances[i] is their unweighted euclidean distance. Distances are updated in the following way (from scipy.hierarchy.linkage):

The new entry $d(u, v)$ is computed as follows,

$$d(u, v) = \sqrt{\frac{|v| + |s|}{T} d(v, s)^2 + \frac{|v| + |t|}{T} d(v, t)^2 - \frac{|v|}{T} d(s, t)^2}$$

where $u$ is the newly joined cluster consisting of clusters $s$ and $t$, $v$ is an unused cluster in the forest, $T = |v| + |s| + |t|$, and $|*|$ is the cardinality of its argument. This is also known as the incremental algorithm.
7.4 sklearn.compose: Composite Estimators

Meta-estimators for building composite models with transformers

In addition to its current contents, this module will eventually be home to refurbished versions of Pipeline and FeatureUnion.

User guide: See the Pipelines and composite estimators section for further details.

```python
compose.ColumnTransformer(transformers, *, remainder='drop', sparse_threshold=0.3, n_jobs=None, transformer_weights=None, verbose=False)
```

Applies transformers to columns of an array or pandas DataFrame.

This estimator allows different columns or column subsets of the input to be transformed separately and the features generated by each transformer will be concatenated to form a single feature space. This is useful for heterogeneous or columnar data, to combine several feature extraction mechanisms or transformations into a single transformer.

Read more in the User Guide.

New in version 0.20.

Parameters

- **transformers** [list of tuples] List of (name, transformer, columns) tuples specifying the transformer objects to be applied to subsets of the data.

- **name** [str] Like in Pipeline and FeatureUnion, this allows the transformer and its parameters to be set using `set_params` and searched in grid search.

- **transformer** [{‘drop’, ‘passthrough’} or estimator] Estimator must support `fit` and `transform`. Special-cased strings ‘drop’ and ‘passthrough’ are accepted as well, to indicate to drop the columns or to pass them through untransformed, respectively.

- **columns** [str, array-like of str, int, array-like of int, array-like of bool, slice or callable] Indexes the data on its second axis. Integers are interpreted as positional columns, while strings can reference DataFrame columns by name. A scalar string or int should be used where `transformer` expects X to be a 1d array-like (vector), otherwise a 2d array will be passed to the transformer. A callable is passed the input data `X` and can return any of the above. To select multiple columns by name or dtype, you can use `make_column_selector`.

- **remainder** [{‘drop’, ‘passthrough’} or estimator, default='drop'] By default, only the specified columns in `transformers` are transformed and combined in the output, and the non-specified columns are dropped. (default of 'drop'). By specifying `remainder='passthrough'`, all remaining columns that were not specified in `transformers` will be automatically passed through. This subset of columns is concatenated with the output of the transformers. By setting `remainder` to be an estimator, the remaining non-specified columns will use the `remainder` estimator. The estimator
must support \texttt{fit} and \texttt{transform}. Note that using this feature requires that the DataFrame columns input at \texttt{fit} and \texttt{transform} have identical order.

\textbf{sparse\_threshold} [float, default=0.3] If the output of the different transformers contains sparse matrices, these will be stacked as a sparse matrix if the overall density is lower than this value. Use \texttt{sparse\_threshold}=0 to always return dense. When the transformed output consists of all dense data, the stacked result will be dense, and this keyword will be ignored.

\textbf{n\_jobs} [int, default=None] Number of jobs to run in parallel. \texttt{None} means 1 unless in a \texttt{joblib.parallel\_backend} context. \texttt{-1} means using all processors. See \textit{Glossary} for more details.

\textbf{transformer\_weights} [dict, default=None] Multiplicative weights for features per transformer. The output of the transformer is multiplied by these weights. Keys are transformer names, values the weights.

\textbf{verbose} [bool, default=False] If True, the time elapsed while fitting each transformer will be printed as it is completed.

\textbf{Attributes}

\textbf{transformers\_} [list] The collection of fitted transformers as tuples of (name, fitted\_transformer, column). \texttt{fitted\_transformer} can be an estimator, ‘drop’, or ‘passthrough’. In case there were no columns selected, this will be the unfitted transformer. If there are remaining columns, the final element is a tuple of the form: ('remainder', transformer, remaining\_columns) corresponding to the \texttt{remainder} parameter. If there are remaining columns, then \texttt{len(transformers\_)==len(transformers)}+1, otherwise \texttt{len(transformers\_)==len(transformers)}.

\textbf{named\_transformers\_} [\textit{Bunch}] Access the fitted transformer by name.

\textbf{sparse\_output\_} [bool] Boolean flag indicating whether the output of \texttt{transform} is a sparse matrix or a dense numpy array, which depends on the output of the individual transformers and the \texttt{sparse\_threshold} keyword.

\textbf{See also:}

\textit{make\_column\_transformer} Convenience function for combining the outputs of multiple transformer objects applied to column subsets of the original feature space.

\textit{make\_column\_selector} Convenience function for selecting columns based on datatype or the columns name with a regex pattern.

\textbf{Notes}

The order of the columns in the transformed feature matrix follows the order of how the columns are specified in the \texttt{transformers} list. Columns of the original feature matrix that are not specified are dropped from the resulting transformed feature matrix, unless specified in the \texttt{passthrough} keyword. Those columns specified with \texttt{passthrough} are added at the right to the output of the transformers.
Examples

```python
>>> import numpy as np
>>> from sklearn.compose import ColumnTransformer
>>> from sklearn.preprocessing import Normalizer

>>> ct = ColumnTransformer(
...     [('norm1', Normalizer(norm='l1'), [0, 1]),
...      ('norm2', Normalizer(norm='l1'), slice(2, 4))])

>>> X = np.array([[0., 1., 2., 2.],
...               [1., 1., 0., 1.]])

>>> # Normalizer scales each row of X to unit norm. A separate scaling
>>> # is applied for the two first and two last elements of each
>>> # row independently.
>>> ct.fit_transform(X)
array([[0. , 1. , 0.5, 0.5],
       [0.5, 0.5, 0. , 1. ]])
```

Methods

- `fit(X[, y])`: Fit all transformers using X.
- `fit_transform(X[, y])`: Fit all transformers, transform the data and concatenate results.
- `get_feature_names()`: Get feature names from all transformers.
- `get_params([deep])`: Get parameters for this estimator.
- `set_params(**kwargs)`: Set the parameters of this estimator.
- `transform(X)`: Transform X separately by each transformer, concatenate results.

**fit**(X, y=None)
Fit all transformers using X.

**Parameters**

- **X** [array-like, dataframe] of shape (n_samples, n_features)] Input data, of which specified subsets are used to fit the transformers.
- **y** [array-like of shape (n_samples,..), default=None] Targets for supervised learning.

**Returns**

- **self** [ColumnTransformer] This estimator

**fit_transform**(X, y=None)
Fit all transformers, transform the data and concatenate results.

**Parameters**

- **X** [array-like, dataframe] of shape (n_samples, n_features)] Input data, of which specified subsets are used to fit the transformers.
- **y** [array-like of shape (n_samples,..), default=None] Targets for supervised learning.

**Returns**

- **X_t** [array-like, sparse matrix] of shape (n_samples, sum_n_components)] hstack of results of transformers. sum_n_components is the sum of n_components (output dimension) over transformers. If any result is a sparse matrix, everything will be converted to sparse matrices.
**get_feature_names()**
Get feature names from all transformers.

Returns
- **feature_names** [list of strings] Names of the features produced by transform.

**get_params**(deep=True)
Get parameters for this estimator.

Returns the parameters given in the constructor as well as the estimators contained within the transformers of the ColumnTransformer.

Parameters
- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
- **params** [dict] Parameter names mapped to their values.

**property named_transformers_**
Access the fitted transformer by name.

Read-only attribute to access any transformer by given name. Keys are transformer names and values are the fitted transformer objects.

**set_params**(**kwargs)
Set the parameters of this estimator.

Valid parameter keys can be listed with get_params(). Note that you can directly set the parameters of the estimators contained in transformers of ColumnTransformer.

Returns
- **self**

**transform**(X)
Transform X separately by each transformer, concatenate results.

Parameters
- **X** [{array-like, dataframe} of shape (n_samples, n_features)] The data to be transformed by subset.

Returns
- **X_t** [{array-like, sparse matrix} of shape (n_samples, sum_n_components)] hstack of results of transformers. sum_n_components is the sum of n_components (output dimension) over transformers. If any result is a sparse matrix, everything will be converted to sparse matrices.
Examples using `sklearn.compose.ColumnTransformer`

- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
- Permutation Importance vs Random Forest Feature Importance (MDI)
- Column Transformer with Mixed Types
- Column Transformer with Heterogeneous Data Sources

### 7.4.2 sklearn.compose.TransformedTargetRegressor

```python
class sklearn.compose.TransformedTargetRegressor(regressor=None, *, transformer=None, func=None, inverse_func=None, check_inverse=True)
```

Meta-estimator to regress on a transformed target.

Useful for applying a non-linear transformation to the target $y$ in regression problems. This transformation can be given as a Transformer such as the QuantileTransformer or as a function and its inverse such as $\log$ and $\exp$.

The computation during `fit` is:

```python
regressor.fit(X, func(y))
```

or:

```python
regressor.fit(X, transformer.transform(y))
```

The computation during `predict` is:

```python
inverse_func(regressor.predict(X))
```

or:

```python
transformer.inverse_transform(regressor.predict(X))
```

Read more in the User Guide.

New in version 0.20.

**Parameters**

- **regressor** [object, default=None] Regressor object such as derived from `RegressorMixin`. This regressor will automatically be cloned each time prior to fitting. If regressor is None, `LinearRegression()` is created and used.

- **transformer** [object, default=None] Estimator object such as derived from `TransformerMixin`. Cannot be set at the same time as `func` and `inverse_func`. If `transformer` is None as well as `func` and `inverse_func`, the transformer will be an identity transformer. Note that the transformer will be cloned during fitting. Also, the transformer is restricting y to be a numpy array.

- **func** [function, default=None] Function to apply to y before passing to `fit`. Cannot be set at the same time as `transformer`. The function needs to return a 2-dimensional array. If `func` is None, the function used will be the identity function.
inverse_func [function, default=None] Function to apply to the prediction of the regressor. Cannot be set at the same time as transformer as well. The function needs to return a 2-dimensional array. The inverse function is used to return predictions to the same space of the original training labels.

check_inverse [bool, default=True] Whether to check that transform followed by inverse_transform or func followed by inverse_func leads to the original targets.

Attributes

regressor_ [object] Fitted regressor.

transformer_ [object] Transformer used in fit and predict.

Notes

Internally, the target y is always converted into a 2-dimensional array to be used by scikit-learn transformers. At the time of prediction, the output will be reshaped to have the same number of dimensions as y.

See examples/compose/plot_transformed_target.py.

Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.compose import TransformedTargetRegressor

>>> tt = TransformedTargetRegressor(regressor=LinearRegression(),
...     func=np.log, inverse_func=np.exp)

>>> X = np.arange(4).reshape(-1, 1)
>>> y = np.exp(2 * X).ravel()

>>> tt.fit(X, y)
TransformedTargetRegressor(...)

>>> tt.score(X, y)
1.0

>>> tt.regressor_.coef_
array([2.])
```

Methods

- `fit(X, y, **fit_params)` Fit the model according to the given training data.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict using the base regressor, applying inverse.
- `score(X, y[, sample_weight])` Return the coefficient of determination $R^2$ of the prediction.
- `set_params(**params)` Set the parameters of this estimator.

```python
fit(X, y, **fit_params)

Fit the model according to the given training data.

Parameters

X [(array-like, sparse matrix) of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
```
**y** [array-like of shape (n_samples,)] Target values.

**fit_params** [dict] Parameters passed to the `fit` method of the underlying regressor.

**Returns**

**self** [object]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**predict**(X)

Predict using the base regressor, applying inverse.

The regressor is used to predict and the `inverse_func` or `inverse_transform` is applied before returning the prediction.

**Parameters**

**X** [[array-like, sparse matrix] of shape (n_samples, n_features)] Samples.

**Returns**

**y_hat** [ndarray of shape (n_samples,)] Predicted values.

**score**(X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true.mean}) ** 2).sum()$.

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of y, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling score on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of $r2\_score$. This influences the score method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params(**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using `sklearn.compose.TransformedTargetRegressor`

- Poisson regression and non-normal loss
- Common pitfalls in interpretation of coefficients of linear models
- Effect of transforming the targets in regression model

```python
compose.make_column_transformer(*transformers) Construct a ColumnTransformer from the given transformers.
compose.make_column_selector([pattern, ...]) Create a callable to select columns to be used with ColumnTransformer.
```

7.4.3 sklearn.compose.make_column_transformer

`sklearn.compose.make_column_transformer(*transformers, remainder='drop', sparse_threshold=0.3, n_jobs=None, verbose=False)`

Construct a ColumnTransformer from the given transformers.

This is a shorthand for the ColumnTransformer constructor; it does not require, and does not permit, naming the transformers. Instead, they will be given names automatically based on their types. It also does not allow weighting with `transformer_weights`.

Read more in the User Guide.

Parameters

*transformers [tuples] Tuples of the form (transformer, columns) specifying the transformer objects to be applied to subsets of the data.

transformer [{‘drop’, ‘passthrough’} or estimator] Estimator must support fit and transform. Special-cased strings ‘drop’ and ‘passthrough’ are accepted as well, to indicate to drop the columns or to pass them through untransformed, respectively.

columns [str, array-like of str, int, array-like of int, slice, array-like of bool or callable] Indexes the data on its second axis. Integers are interpreted as positional columns, while strings can reference DataFrame columns by name. A scalar string or int should be
used where transformer expects X to be a 1d array-like (vector), otherwise a 2d array will be passed to the transformer. A callable is passed the input data X and can return any of the above. To select multiple columns by name or dtype, you can use make_column_selector.

**remainder** [{'drop', 'passthrough'} or estimator, default='drop'] By default, only the specified columns in transformers are transformed and combined in the output, and the non-specified columns are dropped. (default of 'drop'). By specifying remainder='passthrough', all remaining columns that were not specified in transformers will be automatically passed through. This subset of columns is concatenated with the output of the transformers. By setting remainder to be an estimator, the remaining non-specified columns will use the remainder estimator. The estimator must support fit and transform.

**sparse_threshold** [float, default=0.3] If the transformed output consists of a mix of sparse and dense data, it will be stacked as a sparse matrix if the density is lower than this value. Use sparse_threshold=0 to always return dense. When the transformed output consists of all sparse or all dense data, the stacked result will be sparse or dense, respectively, and this keyword will be ignored.

**n_jobs** [int, default=None] Number of jobs to run in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**verbose** [bool, default=False] If True, the time elapsed while fitting each transformer will be printed as it is completed.

**Returns**

- ct [ColumnTransformer]

**See also:**

**ColumnTransformer** Class that allows combining the outputs of multiple transformer objects used on column subsets of the data into a single feature space.

**Examples**

```python
>>> from sklearn.preprocessing import StandardScaler, OneHotEncoder
>>> from sklearn.compose import make_column_transformer
>>> make_column_transformer(
...     (StandardScaler(), ['numerical_column']),
...     (OneHotEncoder(), ['categorical_column']))
ColumnTransformer(transformers=[('standardscaler', StandardScaler(...),
    ['numerical_column']),
    ('onehotencoder', OneHotEncoder(...),
    ['categorical_column'])])
```
Examples using `sklearn.compose.make_column_transformer`

- Release Highlights for scikit-learn 0.23
- Categorical Feature Support in Gradient Boosting
- Combine predictors using stacking
- Common pitfalls in interpretation of coefficients of linear models

### 7.4.4 `sklearn.compose.make_column_selector`

`sklearn.compose.make_column_selector(pattern=None, *, dtype_include=None, dtype_exclude=None)`

Create a callable to select columns to be used with `ColumnTransformer`.

`make_column_selector` can select columns based on datatype or the columns name with a regex. When using multiple selection criteria, all criteria must match for a column to be selected.

**Parameters**

- `pattern` [str, default=None] Name of columns containing this regex pattern will be included. If None, column selection will not be selected based on pattern.
- `dtype_include` [column dtype or list of column dtypes, default=None] A selection of dtypes to include. For more details, see `pandas.DataFrame.select_dtypes`.
- `dtype_exclude` [column dtype or list of column dtypes, default=None] A selection of dtypes to exclude. For more details, see `pandas.DataFrame.select_dtypes`.

**Returns**

- `selector` [callable] Callable for column selection to be used by a `ColumnTransformer`.

**See also:**

- `ColumnTransformer` Class that allows combining the outputs of multiple transformer objects used on column subsets of the data into a single feature space.

**Examples**

```python
>>> from sklearn.preprocessing import StandardScaler, OneHotEncoder
>>> from sklearn.compose import make_column_transformer
>>> from sklearn.compose import make_column_selector
>>> import pandas as pd

>>> X = pd.DataFrame({'city': ['London', 'London', 'Paris', 'Sallisaw'], ...
                   'rating': [5, 3, 4, 5]})

>>> ct = make_column_transformer( ...
...     (StandardScaler(), 'rating'), # rating
...     (OneHotEncoder(), make_column_selector(dtype_include=object)), # city
...     make_column_selector(dtype_include=np.number))

>>> ct.fit_transform(X)
array([[ 0.90453403, 1. , 0. , 0. ],
       [-1.50755672, 1. , 0. , 0. ],
       [-0.30151134, 0. , 1. , 0. ],
       [ 0.90453403, 0. , 0. , 1. ]])
```
Examples using `sklearn.compose.make_column_selector`

- Categorical Feature Support in Gradient Boosting
- Column Transformer with Mixed Types

# 7.5 sklearn.covariance: Covariance Estimators

The `sklearn.covariance` module includes methods and algorithms to robustly estimate the covariance of features given a set of points. The precision matrix defined as the inverse of the covariance is also estimated. Covariance estimation is closely related to the theory of Gaussian Graphical Models.

**User guide:** See the Covariance estimation section for further details.

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## 7.5.1 sklearn.covariance.EmpiricalCovariance

```python
class sklearn.covariance.EmpiricalCovariance(*, store_precision=True, assume_centered=False)
```

Maximum likelihood covariance estimator

Read more in the User Guide.

**Parameters**

- `store_precision` [bool, default=True] Specifies if the estimated precision is stored.
- `assume_centered` [bool, default=False] If True, data are not centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False (default), data are centered before computation.

**Attributes**

- `location_` [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.
- `covariance_` [ndarray of shape (n_features, n_features)] Estimated covariance matrix
- `precision_` [ndarray of shape (n_features, n_features)] Estimated pseudo-inverse matrix. (stored only if store_precision is True)
Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import EmpiricalCovariance
>>> from sklearn.datasets import make_gaussian_quantiles

>>> real_cov = np.array([[.8, .3],
...                       [.3, .4]])
>>> rng = np.random.RandomState(0)
>>> X = rng.multivariate_normal(mean=[0, 0],
...                              cov=real_cov,
...                              size=500)
>>> cov = EmpiricalCovariance().fit(X)

>>> cov.covariance_
array([[0.7569..., 0.2818...],
       [0.2818..., 0.3928...]])

Methods

error_norm(comp_cov[, norm, scaling, squared]) Computes the Mean Squared Error between two covariance estimators.

fit(X[, y]) Fits the Maximum Likelihood Estimator covariance model according to the given training data and parameters.

get_params([deep]) Get parameters for this estimator.

get_precision() Getter for the precision matrix.

mahalanobis(X) Computes the squared Mahalanobis distances of given observations.

score(X_test[, y]) Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

set_params(**params) Set the parameters of this estimator.

error_norm(comp_cov, norm='frobenius', scaling=True, squared=True)
Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

Parameters

comp_cov [array-like of shape (n_features, n_features)] The covariance to compare with.

norm [{“frobenius”, “spectral”}, default=”frobenius”] The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A)) where A is the error (comp_cov - self.covariance_).

scaling [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the scaled error norm is not rescaled.

squared [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

Returns
result [float] The Mean Squared Error (in the sense of the Frobenius norm) between self
and comp_cov covariance estimators.

fit (X, y=None)
Fits the Maximum Likelihood Estimator covariance model according to the given training data and param-
eters.

Parameters
X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the num-
ber of samples and n_features is the number of features.
y [Ignored] Not used, present for API consistency by convention.

Returns
self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters
dep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

get_precision()
Getter for the precision matrix.

Returns
precision_ [array-like of shape (n_features, n_features)] The precision matrix associated to
the current covariance object.

mahalanobis (X)
Computes the squared Mahalanobis distances of given observations.

Parameters
X [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances
of the which we compute. Observations are assumed to be drawn from the same distribu-
tion than the data used in fit.

Returns
dist [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

score (X_test, y=None)
Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its
covariance matrix.

Parameters
X_test [array-like of shape (n_samples, n_features)] Test data of which we compute the
likelihood, where n_samples is the number of samples and n_features is the number of
features. X_test is assumed to be drawn from the same distribution than the data used in
fit (including centering).
y [Ignored] Not used, present for API consistency by convention.

Returns
res [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.covariance.EmpiricalCovariance

- Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood
- Robust covariance estimation and Mahalanobis distances relevance
- Robust vs Empirical covariance estimate

7.5.2 sklearn.covariance.EllipticEnvelope

class sklearn.covariance.EllipticEnvelope(*, store_precision=True, assume_centered=False, support_fraction=None, contamination=0.1, random_state=None)

An object for detecting outliers in a Gaussian distributed dataset.

Read more in the User Guide.

Parameters

store_precision [bool, default=True] Specify if the estimated precision is stored.

assume_centered [bool, default=False] If True, the support of robust location and covariance estimates is computed, and a covariance estimate is recomputed from it, without centering the data. Useful to work with data whose mean is significantly equal to zero but is not exactly zero. If False, the robust location and covariance are directly computed with the FastMCD algorithm without additional treatment.

support_fraction [float, default=None] The proportion of points to be included in the support of the raw MCD estimate. If None, the minimum value of support_fraction will be used within the algorithm: \[ \frac{n_{sample} + n_{features} + 1}{2} \]. Range is (0, 1).

contamination [float, default=0.1] The amount of contamination of the data set, i.e. the proportion of outliers in the data set. Range is (0, 0.5).

random_state [int, RandomState instance or None, default=None] Determines the pseudo random number generator for shuffling the data. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

Attributes

location_ [ndarray of shape (n_features,)] Estimated robust location.

covariance_ [ndarray of shape (n_features, n_features)] Estimated robust covariance matrix.

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precision_ [ndarray of shape (n_features, n_features)] Estimated pseudo inverse matrix. (stored only if store_precision is True)

support_ [ndarray of shape (n_samples,)] A mask of the observations that have been used to compute the robust estimates of location and shape.

offset_ [float] Offset used to define the decision function from the raw scores. We have the relation: decision_function = score_samples - offset_. The offset depends on the contamination parameter and is defined in such a way we obtain the expected number of outliers (samples with decision function < 0) in training.

New in version 0.20.

raw_location_ [ndarray of shape (n_features,)] The raw robust estimated location before correction and re-weighting.

raw_covariance_ [ndarray of shape (n_features, n_features)] The raw robust estimated covariance before correction and re-weighting.

raw_support_ [ndarray of shape (n_samples,)] A mask of the observations that have been used to compute the raw robust estimates of location and shape, before correction and re-weighting.

dist_ [ndarray of shape (n_samples,)] Mahalanobis distances of the training set (on which fit is called) observations.

See also:

EmpiricalCovariance, MinCovDet

Notes

Outlier detection from covariance estimation may break or not perform well in high-dimensional settings. In particular, one will always take care to work with n_samples > n_features ** 2.

References

[1]

Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import EllipticEnvelope
>>> true_cov = np.array([[.8, .3],
                      [.3, .4]])
>>> X = np.random.RandomState(0).multivariate_normal(mean=[0, 0],
                      cov=true_cov,
                      size=500)
>>> cov = EllipticEnvelope(random_state=0).fit(X)
>>> # predict returns 1 for an inlier and -1 for an outlier
>>> cov.predict([[0, 0],
                  [3, 3]])
array([ 1, -1])
>>> cov.covariance_
array([[0.7411..., 0.2535...],
        [0.2535..., 0.3053...]])
```
Correct a correction to raw Minimum Covariance Determinant estimates.

Correction using the empirical correction factor suggested by Rousseeuw and Van Driessen in [RVD].

**Parameters**

- **data** : [array-like of shape (n_samples, n_features)] The data matrix, with p features and n samples. The data set must be the one which was used to compute the raw estimates.

**Returns**

- **covariance_corrected** : [ndarray of shape (n_features, n_features)] Corrected robust covariance estimate.

**References**

[RVD]

decision_function(X)

Compute the decision function of the given observations.

**Parameters**

- **X** : [array-like of shape (n_samples, n_features)] The data matrix.

**Returns**
decision [ndarray of shape (n_samples,)] Decision function of the samples. It is equal to the shifted Mahalanobis distances. The threshold for being an outlier is 0, which ensures a compatibility with other outlier detection algorithms.

error_norm (comp_cov, norm='frobenius', scaling=True, squared=True)
Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

Parameters

comp_cov [array-like of shape (n_features, n_features)] The covariance to compare with.

norm [(“frobenius”, “spectral”), default=”frobenius“] The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A))) where A is the error (comp_cov - self.covariance_).

scaling [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.

squared [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

Returns

result [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

fit (X, y=None)
Fit the EllipticEnvelope model.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training data.

y [Ignored] Not used, present for API consistency by convention.

fit_predict (X, y=None)
Perform fit on X and returns labels for X.

Returns -1 for outliers and 1 for inliers.

Parameters

X [[array-like, sparse matrix, dataframe] of shape (n_samples, n_features)]

y [Ignored] Not used, present for API consistency by convention.

Returns

y [ndarray of shape (n_samples,)] 1 for inliers, -1 for outliers.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

get_precision ()
Getter for the precision matrix.
Returns

**precision_** [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.

**mahalanobis** (**X**) Computes the squared Mahalanobis distances of given observations.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of the which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

**Returns**

**dist** [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

**predict** (**X**) Predict the labels (1 inlier, -1 outlier) of X according to the fitted model.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] The data matrix.

**Returns**

**is_inlier** [ndarray of shape (n_samples,)] Returns -1 for anomalies/outliers and +1 for inliers.

**reweight_covariance** (**data**) Re-weight raw Minimum Covariance Determinant estimates.

Re-weight observations using Rousseeuw’s method (equivalent to deleting outlying observations from the data set before computing location and covariance estimates) described in [RVDriessen].

**Parameters**

**data** [array-like of shape (n_samples, n_features)] The data matrix, with p features and n samples. The data set must be the one which was used to compute the raw estimates.

**Returns**

**location_reweighted** [ndarray of shape (n_features,)] Re-weighted robust location estimate.

**covariance_reweighted** [ndarray of shape (n_features, n_features)] Re-weighted robust covariance estimate.

**support_reweighted** [ndarray of shape (n_samples,), dtype=bool] A mask of the observations that have been used to compute the re-weighted robust location and covariance estimates.

**References**

[RVDriessen]

**score** (**X**, **y**, **sample_weight=None**) Returns the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict(X) w.r.t. y.

score_samples (X)
Compute the negative Mahalanobis distances.

Parameters

X [array-like of shape (n_samples, n_features)] The data matrix.

Returns

negative_mahal_distances [array-like of shape (n_samples,)] Opposite of the Mahalanobis
distances.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.covariance.EllipticEnvelope

• Outlier detection on a real data set
• Comparing anomaly detection algorithms for outlier detection on toy datasets

7.5.3 sklearn.covariance.GraphicalLasso

class sklearn.covariance.GraphicalLasso(alpha=0.01, *, mode='cd', tol=0.0001,
enet_tol=0.0001, max_iter=100, verbose=False, assume_centered=False)

Sparse inverse covariance estimation with an l1-penalized estimator.

Read more in the User Guide.

Changed in version v0.20: GraphLasso has been renamed to GraphicalLasso

Parameters

alpha [float, default=0.01] The regularization parameter: the higher alpha, the more regulariza-
tion, the sparser the inverse covariance. Range is (0, inf].

mode [‘cd’, ‘lars’] The Lasso solver to use: coordinate descent or LARS. Use
LARS for very sparse underlying graphs, where p > n. Elsewhere prefer cd which is more
numerically stable.

tol [float, default=1e-4] The tolerance to declare convergence: if the dual gap goes below this
value, iterations are stopped. Range is (0, inf].
enet_tol  [float, default=1e-4] The tolerance for the elastic net solver used to calculate the descent direction. This parameter controls the accuracy of the search direction for a given column update, not of the overall parameter estimate. Only used for mode='cd'. Range is (0, inf).

max_iter  [int, default=100] The maximum number of iterations.

verbose  [bool, default=False] If verbose is True, the objective function and dual gap are plotted at each iteration.

assume_centered  [bool, default=False] If True, data are not centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False, data are centered before computation.

Attributes

location_  [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.

covariance_  [ndarray of shape (n_features, n_features)] Estimated covariance matrix

precision_  [ndarray of shape (n_features, n_features)] Estimated pseudo inverse matrix.

n_iter_  [int] Number of iterations run.

See also:

graphical_lasso, GraphicalLassoCV

Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import GraphicalLasso
>>> true_cov = np.array([[0.8, 0.0, 0.2, 0.0],
... [0.0, 0.4, 0.0, 0.0],
... [0.2, 0.0, 0.3, 0.1],
... [0.0, 0.0, 0.1, 0.7]])
>>> np.random.seed(0)
>>> X = np.random.multivariate_normal(mean=[0, 0, 0, 0],
...                  cov=true_cov,
...                  size=200)
>>> cov = GraphicalLasso().fit(X)
>>> np.around(cov.covariance_, decimals=3)
array([[0.816, 0.049, 0.218, 0.019],
        [0.049, 0.364, 0.017, 0.034],
        [0.218, 0.017, 0.322, 0.093],
        [0.019, 0.034, 0.093, 0.69 ]])
>>> np.around(cov.location_, decimals=3)
array([[0.073, 0.04 , 0.038, 0.143]])
```
Methods

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<tr>
<th>Method</th>
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<td>error_norm((comp_cov[, norm, scaling, squared]))</td>
<td>Computes the Mean Squared Error between two covariance estimators.</td>
</tr>
<tr>
<td>fit((X[, y]))</td>
<td>Fits the GraphicalLasso model to (X).</td>
</tr>
<tr>
<td>get_params([(deep)])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>get_precision()</td>
<td>Getter for the precision matrix.</td>
</tr>
<tr>
<td>mahalanobis((X))</td>
<td>Computes the squared Mahalanobis distances of given observations.</td>
</tr>
<tr>
<td>score((X_test[, y]))</td>
<td>Computes the log-likelihood of a Gaussian data set with (self.covariance_) as an estimator of its covariance matrix.</td>
</tr>
<tr>
<td>set_params(**(params))</td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

**error_norm** \((comp\_cov, norm=’frobenius’, scaling=True, squared=True)\)

Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

**Parameters**

- **\(comp\_cov\)** [array-like of shape (n_features, n_features)] The covariance to compare with.
- **\(norm\)** ["frobenius", "spectral", default="frobenius"] The type of norm used to compute the error. Available error types: - 'frobenius' (default): \(\sqrt{tr(A^t.A)}\) - 'spectral': \(\sqrt{\text{max}(\text{eigenvalues}(A^t.A))}\) where \(A\) is the error \(\text{comp\_cov} - \text{self.covariance}\).
- **\(scaling\)** [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.
- **\(squared\)** [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

**Returns**

- **\(result\)** [float] The Mean Squared Error (in the sense of the Frobenius norm) between \(self\) and \(comp\_cov\) covariance estimators.

**fit** \((\(X, y=\text{None}\))\)

Fits the GraphicalLasso model to \(X\).

**Parameters**

- **\(X\)** [array-like of shape (n_samples, n_features)] Data from which to compute the covariance estimate
- **\(y\)** [Ignored] Not used, present for API consistency by convention.

**Returns**

- **\(self\)** [object]

**get_params** \((\(deep=\text{True}\))\)

Get parameters for this estimator.

**Parameters**

- **\(deep\)** [bool, default=\(\text{True}\)] If \(\text{True}\), will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
**params**  [dict] Parameter names mapped to their values.

**get_precision**()

Getter for the precision matrix.

**Returns**

```
precision_  [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.
```

**mahalanobis**(*X*)

Computes the squared Mahalanobis distances of given observations.

**Parameters**

```
X  [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.
```

**Returns**

```
dist  [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.
```

**score**(*X_test*, *y=None*)

Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

**Parameters**

```
X_test  [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).
y  [Ignored] Not used, present for API consistency by convention.
```

**Returns**

```
res  [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.
```

**set_params**(**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

```
**params**  [dict] Estimator parameters.
```

**Returns**

```
sel  [estimator instance] Estimator instance.
```
7.5.4 sklearn.covariance.GraphicalLassoCV

class sklearn.covariance.GraphicalLassoCV(*, alphas=4, n_refinements=4, cv=None, 
tol=0.0001, enet_tol=0.0001, max_iter=100, 
mode='cd', n_jobs=None, verbose=False, 
assume_centered=False)

Sparse inverse covariance w/ cross-validated choice of the l1 penalty.
See glossary entry for cross-validation estimator.
Read more in the User Guide.

Changed in version v0.20: GraphLassoCV has been renamed to GraphicalLassoCV

Parameters

alphas [int or array-like of shape (n_alphas,), dtype=float, default=4] If an integer is given, it 
fixes the number of points on the grids of alpha to be used. If a list is given, it gives the 
grid to be used. See the notes in the class docstring for more details. Range is (0, inf] when 
floats given.

n_refinements [int, default=4] The number of times the grid is refined. Not used if explicit 
values of alphas are passed. Range is [1, inf).

cv [int, cross-validation generator or iterable, default=None] Determines the cross-validation 
splitting strategy. Possible inputs for cv are:
• None, to use the default 5-fold cross-validation,
• integer, to specify the number of folds.
• CV splitter,
• An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs KFold is used.
Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.20: cv default value if None changed from 3-fold to 5-fold.

tol [float, default=1e-4] The tolerance to declare convergence: if the dual gap goes below this 
value, iterations are stopped. Range is (0, inf).

enet_tol [float, default=1e-4] The tolerance for the elastic net solver used to calculate the de-
scent direction. This parameter controls the accuracy of the search direction for a given 
column update, not of the overall parameter estimate. Only used for mode='cd'. Range is 
(0, inf).

max_iter [int, default=100] Maximum number of iterations.

mode [{'cd', 'lars'}, default='cd'] The Lasso solver to use: coordinate descent or LARS. Use 
LARS for very sparse underlying graphs, where number of features is greater than number 
of samples. Elsewhere prefer cd which is more numerically stable.

n_jobs [int, default=None] number of jobs to run in parallel. None means 1 unless in a 
joblib.parallel_backend context. -1 means using all processors. See Glossary 
for more details.

Changed in version v0.20: n_jobs default changed from 1 to None

verbose [bool, default=False] If verbose is True, the objective function and duality gap are 
presented at each iteration.
assume_centered [bool, default=False] If True, data are not centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False, data are centered before computation.

Attributes

location_ [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.
covariance_ [ndarray of shape (n_features, n_features)] Estimated covariance matrix.
precision_ [ndarray of shape (n_features, n_features)] Estimated precision matrix (inverse covariance).
alpha_ [float] Penalization parameter selected.
cv_alphas_ [list of shape (n_alphas,), dtype=float] All penalization parameters explored.

deprecated since version 0.24: The cv_alphas_ attribute is deprecated in version 0.24 in favor of cv_results_['alphas'] and will be removed in version 1.1 (renaming of 0.26).
grid_scores_ [ndarray of shape (n_alphas, n_folds)] Log-likelihood score on left-out data across folds.

deprecated since version 0.24: The grid_scores_ attribute is deprecated in version 0.24 in favor of cv_results_ and will be removed in version 1.1 (renaming of 0.26).
cv_results_ [dict of ndarrays] A dict with keys:

alphas [ndarray of shape (n_alphas,)] All penalization parameters explored.
split(k)_score [ndarray of shape (n_alphas,)] Log-likelihood score on left-out data across (k)th fold.
mean_score [ndarray of shape (n_alphas,)] Mean of scores over the folds.
std_score [ndarray of shape (n_alphas,)] Standard deviation of scores over the folds.

New in version 0.24.
n_iter_ [int] Number of iterations run for the optimal alpha.

See also:

graphical_lasso, GraphicalLasso

Notes

The search for the optimal penalization parameter (alpha) is done on an iteratively refined grid: first the cross-validated scores on a grid are computed, then a new refined grid is centered around the maximum, and so on.

One of the challenges which is faced here is that the solvers can fail to converge to a well-conditioned estimate. The corresponding values of alpha then come out as missing values, but the optimum may be close to these missing values.
Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import GraphicalLassoCV
>>> true_cov = np.array([[0.8, 0.0, 0.2, 0.0],
                      [0.0, 0.4, 0.0, 0.0],
                      [0.2, 0.0, 0.3, 0.1],
                      [0.0, 0.0, 0.1, 0.7]])
>>> np.random.seed(0)
>>> X = np.random.multivariate_normal(mean=[0, 0, 0, 0],
                                   cov=true_cov,
                                   size=200)
>>> cov = GraphicalLassoCV().fit(X)
>>> np.around(cov.covariance_, decimals=3)
array([[0.816, 0.051, 0.220, 0.017],
       [0.051, 0.364, 0.018, 0.036],
       [0.220, 0.018, 0.322, 0.094],
       [0.017, 0.036, 0.094, 0.690]])
>>> np.around(cov.location_, decimals=3)
array([0.073, 0.040, 0.038, 0.143])
```

Methods

- `error_norm(comp_cov[, norm, scaling, squared])` Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).
- `fit(X[, y])` Fits the GraphicalLasso covariance model to X.
- `get_params([deep])` Get parameters for this estimator.
- `get_precision()` Getter for the precision matrix.
- `mahalanobis(X)` Computes the squared Mahalanobis distances of given observations.
- `score(X_test[, y])` Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.
- `set_params(**params)` Set the parameters of this estimator.

**error_norm** (comp_cov='frobenius', scaling=True, squared=True)

Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

**Parameters**

- `comp_cov` [array-like of shape (n_features, n_features)] The covariance to compare with.
- `norm` [{'frobenius', 'spectral'}, default='frobenius'] The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A)) where A is the error (comp_cov - self.covariance_).
- `scaling` [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.
- `squared` [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

**Returns**
result [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

fit (X, y=None)
Fits the GraphicalLasso covariance model to X.

Parameters
X [array-like of shape (n_samples, n_features)] Data from which to compute the covariance estimate

y [Ignored] Not used, present for API consistency by convention.

Returns
self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters
depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

generate_precision()
Getter for the precision matrix.

Returns
precision_ [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.

mahalanobis (X)
Computes the squared Mahalanobis distances of given observations.

Parameters
X [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

Returns
dist [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

score (X_test, y=None)
Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

Parameters
X_test [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).

y [Ignored] Not used, present for API consistency by convention.

Returns
res [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.covariance.GraphicalLassoCV

- Sparse inverse covariance estimation
- Visualizing the stock market structure

7.5.5 sklearn.covariance.LedoitWolf

class sklearn.covariance.LedoitWolf(*, store_precision=True, assume_centered=False, block_size=1000)

LedoitWolf Estimator


Read more in the User Guide.

Parameters

store_precision [bool, default=True] Specify if the estimated precision is stored.

assume_centered [bool, default=False] If True, data will not be centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False (default), data will be centered before computation.

block_size [int, default=1000] Size of blocks into which the covariance matrix will be split during its Ledoit-Wolf estimation. This is purely a memory optimization and does not affect results.

Attributes

covariance_ [ndarray of shape (n_features, n_features)] Estimated covariance matrix.

location_ [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.

precision_ [ndarray of shape (n_features, n_features)] Estimated pseudo inverse matrix. (stored only if store_precision is True)

shrinkage_ [float] Coefficient in the convex combination used for the computation of the shrunk estimate. Range is [0, 1].
Notes

The regularised covariance is:

\[(1 - \text{shrinkage}) \times \text{cov} + \text{shrinkage} \times \mu \times \text{np.identity(n\_features)}\]

where \(\mu = \text{trace(cov)} / \text{n\_features}\) and shrinkage is given by the Ledoit and Wolf formula (see References)

References


Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import LedoitWolf

>>> real_cov = np.array([[.4, .2],
... (.2, .8)])
>>> np.random.seed(0)
>>> X = np.random.multivariate_normal(mean=[0, 0],
... cov=real_cov,
... size=50)
>>> cov = LedoitWolf().fit(X)
>>> cov.covariance_
array([[0.4406..., 0.1616...],
       [0.1616..., 0.8022...]])
>>> cov.location_
array([ 0.0595..., -0.0075...])
```

Methods

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<th>Description</th>
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<td><code>error_norm</code></td>
<td>Computes the Mean Squared Error between two covariance estimators.</td>
</tr>
<tr>
<td><code>fit(X, y)</code></td>
<td>Fit the Ledoit-Wolf shrunk covariance model according to the given training data and parameters.</td>
</tr>
<tr>
<td><code>get_params</code></td>
<td>Get parameters for this estimator.</td>
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<td><code>mahalanobis(X)</code></td>
<td>Computes the squared Mahalanobis distances of given observations.</td>
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<tr>
<td><code>score(X_test, y)</code></td>
<td>Computes the log-likelihood of a Gaussian data set with <code>self.covariance_</code> as an estimator of its covariance matrix.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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`error_norm(comp_cov, norm='frobenius', scaling=True, squared=True)`

Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

Parameters

- `comp_cov` [array-like of shape `n\_features`, `n\_features`] The covariance to compare with.
**norm** [{“frobenius”, “spectral”}, default=”frobenius”] The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A)) where A is the error (comp_cov - self.covariance_).

**scaling** [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.

**squared** [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

**Returns**

**result** [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

**fit** *(X, y=None)*
Fit the Ledoit-Wolf shrunk covariance model according to the given training data and parameters.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

**y** [Ignored] Not used, present for API consistency by convention.

**Returns**

**self** [object]

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**get_precision**()
Getter for the precision matrix.

**Returns**

**precision_** [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.

**mahalanobis** *(X)*
Computes the squared Mahalanobis distances of given observations.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

**Returns**

**dist** [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

**score** *(X_test, y=None)*
Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.
Parameters

**X_test** [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).

**y** [Ignored] Not used, present for API consistency by convention.

Returns

**res** [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

**self** [estimator instance] Estimator instance.

Examples using sklearn.covariance.LedoitWolf

- Ledoit-Wolf vs OAS estimation
- Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood
- Model selection with Probabilistic PCA and Factor Analysis (FA)

7.5.6 sklearn.covariance.MinCovDet

class sklearn.covariance.MinCovDet(*, store_precision=True, assume_centered=False, support_fraction=None, random_state=None)

Minimum Covariance Determinant (MCD): robust estimator of covariance.

The Minimum Covariance Determinant covariance estimator is to be applied on Gaussian-distributed data, but could still be relevant on data drawn from a unimodal, symmetric distribution. It is not meant to be used with multi-modal data (the algorithm used to fit a MinCovDet object is likely to fail in such a case). One should consider projection pursuit methods to deal with multi-modal datasets.

Read more in the User Guide.

Parameters

**store_precision** [bool, default=True] Specify if the estimated precision is stored.

**assume_centered** [bool, default=False] If True, the support of the robust location and the covariance estimates is computed, and a covariance estimate is recomputed from it, without centering the data. Useful to work with data whose mean is significantly equal to zero but is not exactly zero. If False, the robust location and covariance are directly computed with the FastMCD algorithm without additional treatment.
**support_fraction** [float, default=None] The proportion of points to be included in the support of the raw MCD estimate. Default is None, which implies that the minimum value of support_fraction will be used within the algorithm: \( \frac{n_{\text{sample}} + n_{\text{features}} + 1}{2} \). The parameter must be in the range \((0, 1)\).

**random_state** [int, RandomState instance or None, default=None] Determines the pseudo random number generator for shuffling the data. Pass an int for reproducible results across multiple function calls. See :term: Glossary `<random_state>`.

**Attributes**

**raw_location_** [ndarray of shape \((n_{\text{features}},)\)] The raw robust estimated location before correction and re-weighting.

**raw_covariance_** [ndarray of shape \((n_{\text{features}}, n_{\text{features}})\)] The raw robust estimated covariance before correction and re-weighting.

**raw_support_** [ndarray of shape \((n_{\text{samples}},)\)] A mask of the observations that have been used to compute the raw robust estimates of location and shape, before correction and re-weighting.

**location_** [ndarray of shape \((n_{\text{features}},)\)] Estimated robust location.

**covariance_** [ndarray of shape \((n_{\text{features}}, n_{\text{features}})\)] Estimated robust covariance matrix.

**precision_** [ndarray of shape \((n_{\text{features}}, n_{\text{features}})\)] Estimated pseudo inverse matrix. (stored only if store_precision is True)

**support_** [ndarray of shape \((n_{\text{samples}},)\)] A mask of the observations that have been used to compute the robust estimates of location and shape.

**dist_** [ndarray of shape \((n_{\text{samples}},)\)] Mahalanobis distances of the training set (on which fit is called) observations.

**References**

[Rousseeuw1984], [Rousseeuw], [ButlerDavies]

**Examples**

```python
>>> import numpy as np
>>> from sklearn.covariance import MinCovDet
>>> from sklearn.datasets import make_gaussian_quantiles

>>> real_cov = np.array([[.8, .3],
                      ...                      [.3, .4]])
>>> rng = np.random.RandomState(0)
>>> X = rng.multivariate_normal(mean=[0, 0],
...                               cov=real_cov,
...                               size=500)
>>> cov = MinCovDet(random_state=0).fit(X)
>>> cov.covariance_
array([[0.7411..., 0.2535...],
        [0.2535..., 0.3053...]])
>>> cov.location_
array([0.0813..., 0.0427...])
```
Methods

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<td>Apply a correction to raw Minimum Covariance Determinant estimates.</td>
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<tr>
<td><code>error_norm(comp_cov[, norm, scaling, squared])</code></td>
<td>Computes the Mean Squared Error between two covariance estimators.</td>
</tr>
<tr>
<td><code>fit(X[, y])</code></td>
<td>Fits a Minimum Covariance Determinant with the FastMCD algorithm.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<td><code>get_precision()</code></td>
<td>Getter for the precision matrix.</td>
</tr>
<tr>
<td><code>mahalanobis(X)</code></td>
<td>Computes the squared Mahalanobis distances of given observations.</td>
</tr>
<tr>
<td><code>reweight_covariance(data)</code></td>
<td>Re-weight raw Minimum Covariance Determinant estimates.</td>
</tr>
<tr>
<td><code>score(X_test[, y])</code></td>
<td>Computes the log-likelihood of a Gaussian data set with <code>self.covariance_</code> as an estimator of its covariance matrix.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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**correct_covariance**(data)

Apply a correction to raw Minimum Covariance Determinant estimates.

Correction using the empirical correction factor suggested by Rousseeuw and Van Driessen in [RVD].

**Parameters**

- **data** [array-like of shape (n_samples, n_features)] The data matrix, with p features and n samples. The data set must be the one which was used to compute the raw estimates.

**Returns**

- **covariance_corrected** [ndarray of shape (n_features, n_features)] Corrected robust covariance estimate.

**References**

[RVD]

**error_norm**(comp_cov[, norm='frobenius', scaling=True, squared=True)

Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

**Parameters**

- **comp_cov** [array-like of shape (n_features, n_features)] The covariance to compare with.
- **norm** ["frobenius", "spectral"] The type of norm used to compute the error. Available error types: - 'frobenius' (default): \( \sqrt{\text{tr}(A^tA)} \) - 'spectral': \( \sqrt{\text{max(eigenvalues}(A^tA))} \) where A is the error \( \text{comp_cov} - \text{self.covariance_} \).
- **scaling** [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.
- **squared** [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

**Returns**

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result [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

fit (X, y=None)
Fits a Minimum Covariance Determinant with the FastMCD algorithm.

Parameters
X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y: Ignored Not used, present for API consistency by convention.

Returns
self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

get_precision()
Getter for the precision matrix.

Returns
precision_ [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.

mahalanobis (X)
Computes the squared Mahalanobis distances of given observations.

Parameters
X [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

Returns
dist [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

reweight_covariance (data)
Re-weight raw Minimum Covariance Determinant estimates.

Re-weight observations using Rousseeuw’s method (equivalent to deleting outlying observations from the data set before computing location and covariance estimates) described in [RVDriessen].

Parameters
data [array-like of shape (n_samples, n_features)] The data matrix, with p features and n samples. The data set must be the one which was used to compute the raw estimates.

Returns
location_reweighted [ndarray of shape (n_features,)] Re-weighted robust location estimate.
covariance_reweighted [ndarray of shape (n_features, n_features)] Re-weighted robust covariance estimate.
**support_reweighted** [ndarray of shape (n_samples,), dtype=bool] A mask of the observations that have been used to compute the re-weighted robust location and covariance estimates.

References

[RVDriessen]

**score**(*X_test, y=None*)
Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

Parameters

- **X_test** [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).
- **y** [Ignored] Not used, present for API consistency by convention.

Returns

- **res** [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.

**set_params**(**params**)  
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

Examples using `sklearn.covariance.MinCovDet`

- Robust covariance estimation and Mahalanobis distances relevance
- Robust vs Empirical covariance estimate

**7.5.7 sklearn.covariance.OAS**

**class** `sklearn.covariance.OAS`(*, store_precision=True, assume_centered=False)  
Oracle Approximating Shrinkage Estimator

Read more in the User Guide.


The formula used here does not correspond to the one given in the article. In the original article, formula (23) states that 2/p is multiplied by Trace(cov*cov) in both the numerator and denominator, but this operation is omitted because for a large p, the value of 2/p is so small that it doesn’t affect the value of the estimator.
Parameters

store_precision [bool, default=True] Specify if the estimated precision is stored.

assume_centered [bool, default=False] If True, data will not be centered before computation.
Useful when working with data whose mean is almost, but not exactly zero. If False (default), data will be centered before computation.

Attributes

covariance_ [ndarray of shape (n_features, n_features)] Estimated covariance matrix.

location_ [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.

precision_ [ndarray of shape (n_features, n_features)] Estimated pseudo inverse matrix. (stored only if store_precision is True)

shrinkage_ [float] coefficient in the convex combination used for the computation of the shrunk estimate. Range is [0, 1].

Notes

The regularised covariance is:

\[(1 - \text{shrinkage}) \times \text{cov} + \text{shrinkage} \times \mu \times \text{np.identity(n_features)}\]

where \(\mu = \text{trace(cov) / n_features}\) and shrinkage is given by the OAS formula (see References)

References


Examples

```python
>>> import numpy as np
>>> from sklearn.covariance import OAS
>>> from sklearn.datasets import make_gaussian_quantiles
>>> real_cov = np.array([[.8, .3],
... [.3, .4]])
>>> rng = np.random.RandomState(0)
>>> X = rng.multivariate_normal(mean=[0, 0],
... cov=real_cov,
... size=500)
>>> oas = OAS().fit(X)
>>> oas.covariance_
array([[0.7533..., 0.2763...],
       [0.2763..., 0.3964...]])
>>> oas.precision_
array([[ 1.7833..., -1.2431... ],
       [-1.2431..., 3.3889...]])
>>> oas.shrinkage_
0.0195...
```
## Methods

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### error_norm

**error_norm (comp_cov, norm='frobenius', scaling=True, squared=True)**

Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

**Parameters**

- **comp_cov** ([array-like of shape (n_features, n_features)]) The covariance to compare with.
- **norm** (["frobenius", “spectral”], default="frobenius") The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A))) where A is the error (comp_cov - self.covariance_).
- **scaling** [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.
- **squared** [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

**Returns**

- **result** [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

### fit

**fit (X, y=None)**

Fit the Oracle Approximating Shrinkage covariance model according to the given training data and parameters.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [Ignored] Not used, present for API consistency by convention.

**Returns**

- **self** [object]

### get_params

**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- **deep** [bool]
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

get_precision ()
Getter for the precision matrix.

Returns

precision_ [array-like of shape (n_features, n_features)] The precision matrix associated to the current covariance object.

mahalanobis (X)
Computes the squared Mahalanobis distances of given observations.

Parameters

X [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

Returns

dist [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

score (X_test, y=None)
Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

Parameters

X_test [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).

y [Ignored] Not used, present for API consistency by convention.

Returns

res [float] The likelihood of the data set with self.covariance_ as an estimator of its covariance matrix.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.covariance.OAS`

- Normal, Ledoit-Wolf and OAS Linear Discriminant Analysis for classification
- Ledoit-Wolf vs OAS estimation
- Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood

### 7.5.8 `sklearn.covariance.ShrunkCovariance`

```python
class sklearn.covariance.ShrunkCovariance(*, store_precision=True, assume_centered=False, shrinkage=0.1)
```

Covariance estimator with shrinkage

Read more in the User Guide.

**Parameters**

- `store_precision` [bool, default=True] Specify if the estimated precision is stored
- `assume_centered` [bool, default=False] If True, data will not be centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False, data will be centered before computation.
- `shrinkage` [float, default=0.1] Coefficient in the convex combination used for the computation of the shrunk estimate. Range is [0, 1].

**Attributes**

- `covariance_` [ndarray of shape (n_features, n_features)] Estimated covariance matrix
- `location_` [ndarray of shape (n_features,)] Estimated location, i.e. the estimated mean.
- `precision_` [ndarray of shape (n_features, n_features)] Estimated pseudo inverse matrix. (stored only if store_precision is True)

**Notes**

The regularized covariance is given by:

\[(1 - \text{shrinkage}) \times \text{cov} + \text{shrinkage} \times \mu \times \text{np.identity(n_features)}\]

where \(\mu = \text{trace(cov)} / n_{\text{features}}\)

**Examples**

```python
>>> import numpy as np
>>> from sklearn.covariance import ShrunkCovariance
>>> from sklearn.datasets import make_gaussian_quantiles
>>> real_cov = np.array([[.8, .3], [.3, .4]])
>>> rng = np.random.RandomState(0)
>>> X = rng.multivariate_normal(mean=[0, 0], ... cov=real_cov, ... size=500)
>>> cov = ShrunkCovariance().fit(X)
>>> cov.covariance_
array([[0.7387..., 0.2536...],
```

(continues on next page)
Methods

error_norm(comp_cov[, norm, scaling, squared]) Computes the Mean Squared Error between two covariance estimators.

fit(X[, y]) Fit the shrunk covariance model according to the given training data and parameters.

get_params([deep]) Get parameters for this estimator.

get_precision() Getter for the precision matrix.

mahalanobis(X) Computes the squared Mahalanobis distances of given observations.

score(X_test[, y]) Computes the log-likelihood of a Gaussian data set with self.covariance_ as an estimator of its covariance matrix.

set_params(**params) Set the parameters of this estimator.

error_norm(comp_cov, norm='frobenius', scaling=True, squared=True) Computes the Mean Squared Error between two covariance estimators. (In the sense of the Frobenius norm).

Parameters

comp_cov [array-like of shape (n_features, n_features)] The covariance to compare with.

norm ["frobenius", "spectral", default="frobenius"] The type of norm used to compute the error. Available error types: - ‘frobenius’ (default): sqrt(tr(A^t.A)) - ‘spectral’: sqrt(max(eigenvalues(A^t.A))) where A is the error (comp_cov - self.covariance_).

scaling [bool, default=True] If True (default), the squared error norm is divided by n_features. If False, the squared error norm is not rescaled.

squared [bool, default=True] Whether to compute the squared error norm or the error norm. If True (default), the squared error norm is returned. If False, the error norm is returned.

Returns

result [float] The Mean Squared Error (in the sense of the Frobenius norm) between self and comp_cov covariance estimators.

fit(X, y=None) Fit the shrunk covariance model according to the given training data and parameters.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y: Ignored Not used, present for API consistency by convention.

Returns

self [object]
**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**

*deep* [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

*params* [dict] Parameter names mapped to their values.

**get_precision** *

**mahalanobis** *(X)*
Computes the squared Mahalanobis distances of given observations.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] The observations, the Mahalanobis distances of the which we compute. Observations are assumed to be drawn from the same distribution than the data used in fit.

**Returns**

*dist* [ndarray of shape (n_samples,)] Squared Mahalanobis distances of the observations.

**score** *(X_test, y=None)*
Computes the log-likelihood of a Gaussian data set with *self.covariance_* as an estimator of its covariance matrix.

**Parameters**

*X_test* [array-like of shape (n_samples, n_features)] Test data of which we compute the likelihood, where n_samples is the number of samples and n_features is the number of features. X_test is assumed to be drawn from the same distribution than the data used in fit (including centering).

*y* [Ignored] Not used, present for API consistency by convention.

**Returns**

*res* [float] The likelihood of the data set with *self.covariance_* as an estimator of its covariance matrix.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

*self* [estimator instance] Estimator instance.
**Examples using sklearn.covariance.ShrunkCovariance**

- Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood
- Model selection with Probabilistic PCA and Factor Analysis (FA)

```python
covariance.empirical_covariance(X, *[, ...])
# Computes the Maximum likelihood covariance estimator

covariance.graphical_lasso(emp_cov, alpha, *)
# l1-penalized covariance estimator

covariance.ledoit_wolf(X, *[, ...])
# Estimates the shrunk Ledoit-Wolf covariance matrix.

covariance.oas(X, *[, assume_centered])
# Estimate covariance with the Oracle Approximating Shrinkage algorithm.

covariance.shrunk_covariance(emp_cov, *[, ...])
# Calculates a covariance matrix shrunk on the diagonal
```

## 7.5.9 sklearn.covariance.empirical_covariance

**sklearn.covariance.empirical_covariance(X, *, assume_centered=False)**

Computes the Maximum likelihood covariance estimator

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Data from which to compute the covariance estimate
- **assume_centered** [bool, default=False] If True, data will not be centered before computation. Useful when working with data whose mean is almost, but not exactly zero. If False, data will be centered before computation.

**Returns**

- **covariance** [ndarray of shape (n_features, n_features)] Empirical covariance (Maximum Likelihood Estimator).

**Examples**

```python
>>> from sklearn.covariance import empirical_covariance
>>> X = [[1,1,1],[1,1,1],[1,1,1],
... [0,0,0],[0,0,0],[0,0,0]]
>>> empirical_covariance(X)
array([[0.25, 0.25, 0.25],
       [0.25, 0.25, 0.25],
       [0.25, 0.25, 0.25]])
```
Examples using `sklearn.covariance.empirical_covariance`

- *Shrinkage covariance estimation: LedoitWolf vs OAS and max-likelihood*

### 7.5.10 `sklearn.covariance.graphical_lasso`

`sklearn.covariance.graphical_lasso`(`emp_cov`, `alpha`, *, `cov_init=None`, `mode='cd'`, `tol=0.0001`, `enet_tol=0.0001`, `max_iter=100`, `verbose=False`, `return_costs=False`, `eps=2.220446049250313e-16`, `return_n_iter=False`)  

11-penalized covariance estimator

Read more in the *User Guide.*

Changed in version v0.20: `graph_lasso` has been renamed to `graphical_lasso`

**Parameters**

- **emp_cov** [ndarray of shape (n_features, n_features)] Empirical covariance from which to compute the covariance estimate.
- **alpha** [float] The regularization parameter: the higher alpha, the more regularization, the sparser the inverse covariance. Range is (0, inf].
- **cov_init** [array of shape (n_features, n_features), default=None] The initial guess for the covariance. If None, then the empirical covariance is used.
- **mode** [{‘cd’, ‘lars’}, default=’cd’] The Lasso solver to use: coordinate descent or LARS. Use LARS for very sparse underlying graphs, where p > n. Elsewhere prefer cd which is more numerically stable.
- **tol** [float, default=1e-4] The tolerance to declare convergence: if the dual gap goes below this value, iterations are stopped. Range is (0, inf].
- **enet_tol** [float, default=1e-4] The tolerance for the elastic net solver used to calculate the descent direction. This parameter controls the accuracy of the search direction for a given column update, not of the overall parameter estimate. Only used for mode='cd'. Range is (0, inf].
- **max_iter** [int, default=100] The maximum number of iterations.
- **verbose** [bool, default=False] If verbose is True, the objective function and dual gap are printed at each iteration.
- **return_costs** [bool, default=False] If return_costs is True, the objective function and dual gap at each iteration are returned.
- **eps** [float, default=eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Default is `np.finfo(np.float64).eps`.
- **return_n_iter** [bool, default=False] Whether or not to return the number of iterations.

**Returns**

- **covariance** [ndarray of shape (n_features, n_features)] The estimated covariance matrix.
- **precision** [ndarray of shape (n_features, n_features)] The estimated (sparse) precision matrix.
- **costs** [list of (objective, dual_gap) pairs] The list of values of the objective function and the dual gap at each iteration. Returned only if return_costs is True.
- **n_iter** [int] Number of iterations. Returned only if return_n_iter is set to True.

---

7.5. `sklearn.covariance`: Covariance Estimators
See also:

*GraphicalLasso, GraphicalLassoCV*

Notes

The algorithm employed to solve this problem is the GLasso algorithm, from the Friedman 2008 Biostatistics paper. It is the same algorithm as in the R `glasso` package.

One possible difference with the `glasso` R package is that the diagonal coefficients are not penalized.

7.5.11 `sklearn.covariance.ledoit_wolf`

`sklearn.covariance.ledoit_wolf(X, *, assume_centered=False, block_size=1000)`

Estimates the shrunk Ledoit-Wolf covariance matrix.

Read more in the *User Guide*.

Parameters

- `X [array-like of shape (n_samples, n_features)]` Data from which to compute the covariance estimate
- `assume_centered [bool, default=False]` If True, data will not be centered before computation. Useful to work with data whose mean is significantly equal to zero but is not exactly zero. If False, data will be centered before computation.
- `block_size` [int, default=1000] Size of blocks into which the covariance matrix will be split. This is purely a memory optimization and does not affect results.

Returns

- `shrunk_cov [ndarray of shape (n_features, n_features)]` Shrunk covariance.
- `shrinkage [float]` Coefficient in the convex combination used for the computation of the shrunk estimate.

Notes

The regularized (shrunk) covariance is:

\[(1 - shrinkage) \cdot \text{cov} + shrinkage \cdot \mu \cdot \text{np.identity(n_features)}\]

where \(\mu = \text{trace(cov)} / n_{\text{features}}\)

Examples using `sklearn.covariance.ledoit_wolf`

- Sparse inverse covariance estimation
7.5.12 sklearn.covariance.oas

sklearn.covariance.oas(X, *, assume_centered=False)

Estimate covariance with the Oracle Approximating Shrinkage algorithm.

Parameters

- X [array-like of shape (n_samples, n_features)] Data from which to compute the covariance estimate.
- assume_centered [bool, default=False] If True, data will not be centered before computation. Useful to work with data whose mean is significantly equal to zero but is not exactly zero. If False, data will be centered before computation.

Returns

- shrunk_cov [array-like of shape (n_features, n_features)] Shrinked covariance.
- shrinkage [float] Coefficient in the convex combination used for the computation of the shrunk estimate.

Notes

The regularised (shrunk) covariance is:

\[(1 - \text{shrinkage}) \times \text{cov} + \text{shrinkage} \times \mu \times \text{np.identity(n_features)}\]

where \(\mu = \text{trace(cov)} / \text{n_features}\)

The formula we used to implement the OAS is slightly modified compared to the one given in the article. See OAS for more details.

7.5.13 sklearn.covariance.shrunk_covariance

sklearn.covariance.shrunk_covariance(emp_cov, shrinkage=0.1)

Calculates a covariance matrix shrunk on the diagonal.

Read more in the User Guide.

Parameters

- emp_cov [array-like of shape (n_features, n_features)] Covariance matrix to be shrunk
- shrinkage [float, default=0.1] Coefficient in the convex combination used for the computation of the shrunk estimate. Range is [0, 1].

Returns

- shrunk_cov [ndarray of shape (n_features, n_features)] Shrinked covariance.
Notes

The regularized (shrunk) covariance is given by:

\[(1 - \text{shrinkage}) \times \text{cov} + \text{shrinkage} \times \text{mu} \times \text{np.identity(n_features)}\]

where \(\text{mu} = \text{trace(cov)} / \text{n_features}\)

7.6 sklearn.cross_decomposition: Cross decomposition

User guide: See the Cross decomposition section for further details.

| sklearn.cross_decomposition.CCA([n_components, ...) | Canonical Correlation Analysis, also known as “Mode B” PLS. |
| sklearn.cross_decomposition.PLSCanonical([...]) | Partial Least Squares transformer and regressor. |
| sklearn.cross_decomposition.PLSRegression([...]) | PLS regression |
| sklearn.cross_decomposition.PLSSVD([n_components, ...]) | Partial Least Square SVD. |

7.6.1 sklearn.cross_decomposition.CCA

class sklearn.cross_decomposition.CCA(n_components=2, *, scale=True, max_iter=500, tol=1e-06, copy=True)

Canonical Correlation Analysis, also known as “Mode B” PLS.

Read more in the User Guide.

Parameters

- **n_components** [int, default=2] Number of components to keep. Should be in \([1, \min(n_{samples}, n_{features}, n_{targets})]\).  
- **scale** [bool, default=True] Whether to scale \(X\) and \(Y\).  
- **max_iter** [int, default=500] the maximum number of iterations of the power method.  
- **tol** [real, default=1e-06] The tolerance used as convergence criteria in the power method: the algorithm stops whenever the squared norm of \(u_i - u_{i-1}\) is less than \(\text{tol}\), where \(u\) corresponds to the left singular vector.  
- **copy** [bool, default=True] Whether to copy \(X\) and \(Y\) in fit before applying centering, and potentially scaling. If False, these operations will be done inplace, modifying both arrays.

Attributes

- **x_weights** [ndarray of shape (n_features, n_components)] The left singular vectors of the cross-covariance matrices of each iteration.
- **y_weights** [ndarray of shape (n_targets, n_components)] The right singular vectors of the cross-covariance matrices of each iteration.
- **x_loadings** [ndarray of shape (n_features, n_components)] The loadings of \(X\).
- **y_loadings** [ndarray of shape (n_targets, n_components)] The loadings of \(Y\).
- **x_scores** [ndarray of shape (n_samples, n_components)] The transformed training samples.
Deprecation since version 0.24: `x_scores_` is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call `transform` on the training data instead.

`y_scores_` [ndarray of shape (n_samples, n_components)] The transformed training targets.

Deprecation since version 0.24: `y_scores_` is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call `transform` on the training data instead.

`x_rotations_` [ndarray of shape (n_features, n_components)] The projection matrix used to transform `X`.

`y_rotations_` [ndarray of shape (n_features, n_components)] The projection matrix used to transform `Y`.

`coef_` [ndarray of shape (n_features, n_targets)] The coefficients of the linear model such that `y` is approximated as `Y = X @ coef_`.

`n_iter_` [list of shape (n_components,)] Number of iterations of the power method, for each component.

See also:

- PLSCanonical
- PLSSVD

Examples

```python
>>> from sklearn.cross_decomposition import CCA
>>> X = [[0., 0., 1.], [1.,0.,0.], [2.,2.,2.], [3.,5.,4.]]
>>> Y = [[0.1, -0.2], [0.9, 1.1], [6.2, 5.9], [11.9, 12.5]]
>>> cca = CCA(n_components=1)
>>> cca.fit(X, Y)
CCA(n_components=1)
>>> X_c, Y_c = cca.transform(X, Y)
```

Methods

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<td><code>fit_transform(X,y)</code></td>
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<tr>
<td><code>predict(X[, copy])</code></td>
<td>Predict targets of given samples.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X[, Y, copy])</code></td>
<td>Apply the dimension reduction.</td>
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`fit(X, Y)`

Fit model to data.

Parameters

- `X` [array-like of shape (n_samples, n_features)] Training vectors, where `n_samples` is the number of samples and `n_features` is the number of predictors.
Y [array-like of shape (n_samples,) or (n_samples, n_targets)] Target vectors, where
n_samples is the number of samples and n_targets is the number of response vari-
ables.

fit_transform (X, y=None)
Learn and apply the dimension reduction on the train data.

Parameters

X [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the
number of samples and n_features is the number of predictors.

y [array-like of shape (n_samples, n_targets), default=None] Target vectors, where
n_samples is the number of samples and n_targets is the number of response variables.

Returns

x_scores if Y is not given, (x_scores, y_scores) otherwise.

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform (X)
Transform data back to its original space.

Parameters

X [array-like of shape (n_samples, n_components)] New data, where n_samples is the
number of samples and n_components is the number of pls components.

Returns

x_reconstructed [array-like of shape (n_samples, n_features)]

Notes

This transformation will only be exact if n_components=n_features.

predict (X, copy=True)
Predict targets of given samples.

Parameters

X [array-like of shape (n_samples, n_features)] Samples.

copy [bool, default=True] Whether to copy X and Y, or perform in-place normalization.
Notes

This call requires the estimation of a matrix of shape \((n\_features, \ n\_targets)\), which may be an issue in high dimensional space.

**score \((X, y, \text{sample\_weight}=\text{None})\)**

Return the coefficient of determination \(R^2\) of the prediction.

The coefficient \(R^2\) is defined as \((1 - \frac{u}{v})\), where \(u\) is the residual sum of squares \(((y\_true - y\_pred)^2).\text{sum()}\) and \(v\) is the total sum of squares \(((y\_true - y\_true\cdot\text{mean()})^2).\text{sum()}\).

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \(y\), disregarding the input features, would get a \(R^2\) score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] \(R^2\) of self.predict \((X)\) wrt. \(y\).

Notes

The \(R^2\) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params (**params)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- ****params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**transform **(X, Y=None, copy=True)**

Apply the dimension reduction.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Samples to transform.
- **Y** [array-like of shape (n_samples, n_targets), default=None] Target vectors.
- **copy** [bool, default=True] Whether to copy \(X\) and \(Y\), or perform in-place normalization.

**Returns**

- **x\_scores** if \(Y\) is not given, \((x\_scores, y\_scores)\) otherwise.
Examples using sklearn.cross_decomposition.CCA

• Compare cross decomposition methods
• Multilabel classification

7.6.2 sklearn.cross_decomposition.PLSCanonical

class sklearn.cross_decomposition.PLSCanonical(n_components=2, *, scale=True, algorithm='nipals', max_iter=500, tol=1e-06, copy=True)

Partial Least Squares transformer and regressor.

Read more in the User Guide.

New in version 0.8.

Parameters

n_components [int, default=2] Number of components to keep. Should be in \([1, \min(n_samples, n_features, n_targets)]\).

scale [bool, default=True] Whether to scale \(X\) and \(Y\).

algorithm [\{'nipals', 'svd'\}, default='nipals'] The algorithm used to estimate the first singular vectors of the cross-covariance matrix. 'nipals' uses the power method while 'svd' will compute the whole SVD.

max_iter [int, default=500] the maximum number of iterations of the power method when algorithm='nipals'. Ignored otherwise.

tol [real, default 1e-06] The tolerance used as convergence criteria in the power method: the algorithm stops whenever the squared norm of \(u_i - u_{i-1}\) is less than \(tol\), where \(u\) corresponds to the left singular vector.

copy [bool, default=True] Whether to copy \(X\) and \(Y\) in fit before applying centering, and potentially scaling. If False, these operations will be done inplace, modifying both arrays.

Attributes

x_weights_ [ndarray of shape (n_features, n_components)] The left singular vectors of the cross-covariance matrices of each iteration.

y_weights_ [ndarray of shape (n_targets, n_components)] The right singular vectors of the cross-covariance matrices of each iteration.

x_loadings_ [ndarray of shape (n_features, n_components)] The loadings of \(X\).

y_loadings_ [ndarray of shape (n_targets, n_components)] The loadings of \(Y\).

x_scores_ [ndarray of shape (n_samples, n_components)] The transformed training samples.

.. deprecated::
   :version: 0.24
   \(x_scores\) is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call transform on the training data instead.

y_scores_ [ndarray of shape (n_samples, n_components)] The transformed training targets.

.. deprecated::
   :version: 0.24
   \(y_scores\) is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call transform on the training data instead.

x_rotations_ [ndarray of shape (n_features, n_components)] The projection matrix used to transform \(X\).
y_rotations_ [ndarray of shape (n_features, n_components)] The projection matrix used to transform Y.

c coef_ [ndarray of shape (n_features, n_targets)] The coefficients of the linear model such that Y is approximated as \( Y = X @ \text{coef}_. \)

n_iter_ [list of shape (n_components,)] Number of iterations of the power method, for each component. Empty if \text{algorithm}='svd'.

See also:

CCA

PLSSVD

Examples

```python
>>> from sklearn.cross_decomposition import PLSCanonical
>>> X = [[0., 0., 1.], [1.,0.,0.], [2.,2.,2.], [2.,5.,4.]]
>>> Y = [[0.1, -0.2], [0.9, 1.1], [6.2, 5.9], [11.9, 12.3]]
>>> plsca = PLSCanonical(n_components=2)
>>> plsca.fit(X, Y)
PLSCanonical()
>>> X_c, Y_c = plsca.transform(X, Y)
```

Methods

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<td>fit(X, Y)</td>
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</tr>
<tr>
<td>predict(X[, copy])</td>
<td>Predict targets of given samples.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination ( R^2 ) of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X[, Y, copy])</td>
<td>Apply the dimension reduction.</td>
</tr>
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</table>

**fit(X, Y)**

Fit model to data.

**Parameters**

- **X**: [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of predictors.

- **Y**: [array-like of shape (n_samples,) or (n_samples, n_targets)] Target vectors, where n_samples is the number of samples and n_targets is the number of response variables.

**fit_transform(X, y=None)**

Learn and apply the dimension reduction on the train data.

**Parameters**

- **X**: [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the
number of samples and n_features is the number of predictors.

\[ y \text{ [array-like of shape (n_samples, n_targets), default=None] Target vectors, where} \]
\[ n_{\text{samples}} \text{ is the number of samples and } n_{\text{targets}} \text{ is the number of response variables.} \]

Returns

\[ x_{\text{scores}} \text{ if } Y \text{ is not given, } (x_{\text{scores}}, y_{\text{scores}}) \text{ otherwise.} \]

get_params (deep=True)
Get parameters for this estimator.

Parameters

- **deep** : bool, default=True If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** : dict Parameter names mapped to their values.

inverse_transform (X)
Transform data back to its original space.

Parameters

- **X** : array-like of shape (n_samples, n_components) New data, where n_samples is the number of samples and n_components is the number of pls components.

Returns

- **x_reconstructed** : array-like of shape (n_samples, n_features)

Notes

This transformation will only be exact if n_components=n_features.

predict (X, copy=True)
Predict targets of given samples.

Parameters

- **X** : array-like of shape (n_samples, n_features) Samples.

- **copy** : bool, default=True Whether to copy X and Y, or perform in-place normalization.

Notes

This call requires the estimation of a matrix of shape (n_features, n_targets), which may be an issue in high dimensional space.

score (X, y, sample_weight=None)
Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( (1 - \frac{u}{v}), \) where \( u \) is the residual sum of squares \( ((y_{\text{true}} - y_{\text{pred}})^2).sum() \) and \( v \) is the total sum of squares \( ((y_{\text{true}} - y_{\text{true}}.mean())^2).sum(). \) The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of y, disregarding the input features, would get a \( R^2 \) score of 0.0.

Parameters
X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X, Y=None, copy=True)

Apply the dimension reduction.

Parameters

X [array-like of shape (n_samples, n_features)] Samples to transform.

Y [array-like of shape (n_samples, n_targets), default=None] Target vectors.

copy [bool, default=True] Whether to copy X and Y, or perform in-place normalization.

Returns

x_scores if Y is not given, (x_scores, y_scores) otherwise.

Examples using sklearn.cross_decomposition.PLSCanonical

• Compare cross decomposition methods
PLS regression

PLSRegression is also known as PLS2 or PLS1, depending on the number of targets.

Read more in the User Guide.

New in version 0.8.

Parameters

- **n_components** [int, default=2] Number of components to keep. Should be in \([1, \min(n_{samples}, n_{features}, n_{targets})]\).
- **scale** [bool, default=True] Whether to scale \(X\) and \(Y\).
- **algorithm** [{'nipals', 'svd'}, default='nipals'] The algorithm used to estimate the first singular vectors of the cross-covariance matrix. ‘nipals’ uses the power method while ‘svd’ will compute the whole SVD.
- **max_iter** [int, default=500] The maximum number of iterations of the power method when algorithm='nipals'. Ignored otherwise.
- **tol** [real, default 1e-06] The tolerance used as convergence criteria in the power method: the algorithm stops whenever the squared norm of \(u_i - u_{i-1}\) is less than \(\text{tol}\), where \(u\) corresponds to the left singular vector.
- **copy** [bool, default=True] Whether to copy \(X\) and \(Y\) in fit before applying centering, and potentially scaling. If False, these operations will be done inplace, modifying both arrays.

Attributes

- **x_weights** [ndarray of shape \((n_{features}, n_{components})\)] The left singular vectors of the cross-covariance matrices of each iteration.
- **y_weights** [ndarray of shape \((n_{targets}, n_{components})\)] The right singular vectors of the cross-covariance matrices of each iteration.
- **x_loadings** [ndarray of shape \((n_{features}, n_{components})\)] The loadings of \(X\).
- **y_loadings** [ndarray of shape \((n_{targets}, n_{components})\)] The loadings of \(Y\).
- **x_scores** [ndarray of shape \((n_{samples}, n_{components})\)] The transformed training samples.
- **y_scores** [ndarray of shape \((n_{samples}, n_{components})\)] The transformed training targets.
- **x_rotations** [ndarray of shape \((n_{features}, n_{components})\)] The projection matrix used to transform \(X\).
- **y_rotations** [ndarray of shape \((n_{features}, n_{components})\)] The projection matrix used to transform \(Y\).
- **coef** [ndarray of shape \((n_{features}, n_{targets})\)] The coefficients of the linear model such that \(Y\) is approximated as \(Y = X @ \text{coef}\).
- **n_iter** [list of shape \((n_{components})\)] Number of iterations of the power method, for each component. Empty if algorithm='svd'.

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Examples

```python
>>> from sklearn.cross_decomposition import PLSRegression
>>> X = [[0., 0., 1.], [1., 0., 0.], [2., 2., 2.], [2., 5., 4.]]
>>> Y = [[0.1, -0.2], [0.9, 1.1], [6.2, 5.9], [11.9, 12.3]]
>>> pls2 = PLSRegression(n_components=2)
>>> pls2.fit(X, Y)
PLSRegression()
>>> Y_pred = pls2.predict(X)
```

Methods

+ `fit(X, Y)` Fit model to data.
+ `fit_transform(X[, y])` Learn and apply the dimension reduction on the train data.
+ `get_params([deep])` Get parameters for this estimator.
+ `inverse_transform(X)` Transform data back to its original space.
+ `predict(X[, copy])` Predict targets of given samples.
+ `score(X, y[, sample_weight])` Return the coefficient of determination $R^2$ of the prediction.
+ `set_params(**params)` Set the parameters of this estimator.
+ `transform(X[, Y , copy])` Apply the dimension reduction.

**fit (X, Y)**

Fit model to data.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of predictors.
- **Y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target vectors, where n_samples is the number of samples and n_targets is the number of response variables.

**fit_transform (X, y=None)**

Learn and apply the dimension reduction on the train data.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of predictors.
- **y** [array-like of shape (n_samples, n_targets), default=None] Target vectors, where n_samples is the number of samples and n_targets is the number of response variables.

**Returns**

- **x_scores** if Y is not given, (x_scores, y_scores) otherwise.

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
Returns

params [dict] Parameter names mapped to their values.

inverse_transform(X)
Transform data back to its original space.

Parameters

X [array-like of shape (n_samples, n_components)] New data, where n_samples is the number of samples and n_components is the number of pls components.

Returns

x_reconstructed [array-like of shape (n_samples, n_features)]

Notes

This transformation will only be exact if n_components=n_features.

predict (X, copy=True)
Predict targets of given samples.

Parameters

X [array-like of shape (n_samples, n_features)] Samples.

copy [bool, default=True] Whether to copy X and y, or perform in-place normalization.

Notes

This call requires the estimation of a matrix of shape (n_features, n_targets), which may be an issue in high dimensional space.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $\sum((y_{true} - y_{pred})^2)$ and $v$ is the total sum of squares $\sum((y_{true} - y_{true}.mean())^2)$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of $r2\_score$. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

`transform (X, Y=None, copy=True)`

Apply the dimension reduction.

Parameters

X [array-like of shape (n_samples, n_features)] Samples to transform.

Y [array-like of shape (n_samples, n_targets), default=None] Target vectors.

copy [bool, default=True] Whether to copy X and Y, or perform in-place normalization.

Returns

x_scores if Y is not given, (x_scores, y_scores) otherwise.

Examples using `sklearn.cross_decomposition.PLSRegression`

- Principal Component Regression vs Partial Least Squares Regression
- Compare cross decomposition methods

7.6.4 sklearn.cross_decomposition.PLSSVD

class sklearn.cross_decomposition.PLSSVD (n_components=2, *, scale=True, copy=True)

Partial Least Square SVD.

This transformer simply performs a SVD on the crosscovariance matrix X’Y. It is able to project both the training data X and the targets Y. The training data X is projected on the left singular vectors, while the targets are projected on the right singular vectors.

Read more in the User Guide.

New in version 0.8.

Parameters

n_components [int, default=2] The number of components to keep. Should be in $[1, \min(n\_samples, n\_features, n\_targets)]$.

scale [bool, default=True] Whether to scale X and Y.
copy [bool, default=True] Whether to copy X and Y in fit before applying centering, and potentially scaling. If False, these operations will be done inplace, modifying both arrays.

Attributes

x_weights_ [ndarray of shape (n_features, n_components)] The left singular vectors of the SVD of the cross-covariance matrix. Used to project X in transform.

y_weights_ [ndarray of (n_targets, n_components)] The right singular vectors of the SVD of the cross-covariance matrix. Used to project X in transform.

x_scores_ [ndarray of shape (n_samples, n_components)] The transformed training samples.

Deprecated since version 0.24: x_scores_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call transform on the training data instead.

y_scores_ [ndarray of shape (n_samples, n_components)] The transformed training targets.

Deprecated since version 0.24: y_scores_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). You can just call transform on the training data instead.

See also:

PLSCanonical

CCA

Examples

```python
>>> import numpy as np
>>> from sklearn.cross_decomposition import PLSSVD
>>> X = np.array([[0., 0., 1.],
...               [1., 0., 0.],
...               [2., 2., 2.],
...               [2., 5., 4.]])
>>> Y = np.array([[0.1, -0.2],
...               [0.9, 1.1],
...               [6.2, 5.9],
...               [11.9, 12.3]])
>>> pls = PLSSVD(n_components=2).fit(X, Y)
>>> X_c, Y_c = pls.transform(X, Y)
>>> X_c.shape, Y_c.shape
((4, 2), (4, 2))
```

Methods

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<th>Method</th>
<th>Description</th>
</tr>
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<tbody>
<tr>
<td>fit(X, Y)</td>
<td>Fit model to data.</td>
</tr>
<tr>
<td>fit_transform(X[, y])</td>
<td>Learn and apply the dimensionality reduction.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X[, y])</td>
<td>Apply the dimensionality reduction.</td>
</tr>
</tbody>
</table>

fit (X, Y)

Fit model to data.

Parameters
X [array-like of shape (n_samples, n_features)] Training samples.
Y [array-like of shape (n_samples,) or (n_samples, n_targets)] Targets.

**fit_transform** *(X, y=None)*
Learn and apply the dimensionality reduction.

**Parameters**
- X [array-like of shape (n_samples, n_features)] Training samples.
- y [array-like of shape (n_samples,) or (n_samples, n_targets), default=None] Targets.

**Returns**
- out [array-like or tuple of array-like] The transformed data X_transformed if Y is not None, (X_transformed, Y_transformed) otherwise.

**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**
- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- params [dict] Parameter names mapped to their values.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**
- **params** [dict] Estimator parameters.

**Returns**

**transform** *(X, Y=None)*
Apply the dimensionality reduction.

**Parameters**
- X [array-like of shape (n_samples, n_features)] Samples to be transformed.
- Y [array-like of shape (n_samples,) or (n_samples, n_targets), default=None] Targets.

**Returns**
- out [array-like or tuple of array-like] The transformed data X_transformed if Y is not None, (X_transformed, Y_transformed) otherwise.
7.7 sklearn.datasets: Datasets

The sklearn.datasets module includes utilities to load datasets, including methods to load and fetch popular reference datasets. It also features some artificial data generators.

User guide: See the Dataset loading utilities section for further details.

7.7.1 Loaders

```python
datasets.clear_data_home([data_home]) Delete all the content of the data home cache.
datasets.dump_svmlight_file(X, y, f, *[, \ldots]) Dump the dataset in svmlight / libsvm file format.
datasets.fetch_20newsgroups(*[, data_home, \ldots]) Load the filenames and data from the 20 newsgroups dataset (classification).
datasets.fetch_20newsgroups_vectorized(*[, \ldots]) Load and vectorize the 20 newsgroups dataset (classification).
datasets.fetch_california_housing(*[, \ldots]) Load the California housing dataset (regression).
datasets.fetch_covtype(*[, data_home, \ldots]) Load the covertype dataset (classification).
datasets.fetch_kddcup99(*[, subset, \ldots]) Load the kddcup99 dataset (classification).
datasets.fetch_lfw_pairs(*[, subset, \ldots]) Load the Labeled Faces in the Wild (LFW) pairs dataset (classification).
datasets.fetch_lfw_people(*[, data_home, \ldots]) Load the Labeled Faces in the Wild (LFW) people dataset (classification).
datasets.fetch_olivetti_faces(*[, \ldots]) Load the Olivetti faces data-set from AT&T (classification).
datasets.fetch_openml([name, version, \ldots]) Fetch dataset from openml by name or dataset id.
datasets.fetch_rcv1(*[, data_home, subset, \ldots]) Load the RCV1 multilabel dataset (classification).
datasets.fetch_species_distributions(*[, \ldots]) Loader for species distribution dataset from Phillips et.
datasets.get_data_home([data_home]) Return the path of the scikit-learn data dir.
datasets.load_boston(*[, return_X_y]) Load and return the boston house-prices dataset (regression).
datasets.load_breast_cancer(*[, return_X_y, as_frame]) Load and return the breast cancer wisconsin dataset (classification).
datasets.load_diabetes(*[, return_X_y, as_frame]) Load and return the diabetes dataset (regression).
datasets.load_digits(*[, n_class, \ldots]) Load and return the digits dataset (classification).
datasets.load_files(container_path, *[, \ldots]) Load text files with categories as subfolder names.
datasets.load_iris(*[, return_X_y, as_frame]) Load and return the iris dataset (classification).
datasets.load_linnerud(*[, return_X_y, as_frame]) Load and return the physical excercise linnerud dataset.
datasets.load_sample_image(image_name) Load the numpy array of a single sample image
datasets.load_sample_images() Load sample images for image manipulation.
datasets.load_svmlight_file(f, *[, \ldots]) Load datasets in the svmlight / libsvm format into sparse CSR matrix
datasets.load_svmlight_files(files, *[, \ldots]) Load dataset from multiple files in SVMlight format
datasets.load_wine(*[, return_X_y, as_frame]) Load and return the wine dataset (classification).
```
**sklearn.datasets.clear_data_home**

`sklearn.datasets.clear_data_home(data_home=None)`
Delete all the content of the data home cache.

**Parameters**

- `data_home` [str, default=None] The path to scikit-learn data directory. If None, the default path is `~/sklearn_learn_data`.

**sklearn.datasets.dump_svmlight_file**

`sklearn.datasets.dump_svmlight_file(X, y, f, *, zero_based=True, comment=None, query_id=None, multilabel=False)`

Dump the dataset in svmlight / libsvm file format.

This format is a text-based format, with one sample per line. It does not store zero valued features hence is suitable for sparse dataset.

The first element of each line can be used to store a target variable to predict.

**Parameters**

- `X` [array-like, sparse matrix] of shape (n_samples, n_features) Training vectors, where n_samples is the number of samples and n_features is the number of features.
- `y` [array-like, sparse matrix], shape = [n_samples (, n_labels)] Target values. Class labels must be an integer or float, or array-like objects of integer or float for multilabel classifications.
- `f` [string or file-like in binary mode] If string, specifies the path that will contain the data. If file-like, data will be written to f. f should be opened in binary mode.
- `zero_based` [boolean, default=True] Whether column indices should be written zero-based (True) or one-based (False).
- `comment` [string, default=None] Comment to insert at the top of the file. This should be either a Unicode string, which will be encoded as UTF-8, or an ASCII byte string. If a comment is given, then it will be preceded by one that identifies the file as having been dumped by scikit-learn. Note that not all tools grok comments in SVMlight files.
- `query_id` [array-like of shape (n_samples,), default=None] Array containing pairwise preference constraints (qid in svmlight format).
- `multilabel` [boolean, default=False] Samples may have several labels each (see https://www.csie.ntu.edu.tw/~cjlin/libsvmtools/datasets/multilabel.html)

New in version 0.17: parameter `multilabel` to support multilabel datasets.

**Examples using sklearn.datasets.dump_svmlight_file**

- *Libsvm GUI*
sklearn.datasets.fetch_20newsgroups

sklearn.datasets.fetch_20newsgroups(*, data_home=None, subset='train', categories=None, shuffle=True, random_state=42, remove=(), download_if_missing=True, return_X_y=False)

Load the filenames and data from the 20 newsgroups dataset (classification).
Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>20</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>18846</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>1</td>
</tr>
<tr>
<td>Features</td>
<td>text</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

 - **data_home** [str, default=None] Specify a download and cache folder for the datasets. If None, all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

 - **subset** [{‘train’, ‘test’, ‘all’}, default=’train’] Select the dataset to load: ‘train’ for the training set, ‘test’ for the test set, ‘all’ for both, with shuffled ordering.

 - **categories** [array-like, dtype=str or unicode, default=None] If None (default), load all the categories. If not None, list of category names to load (other categories ignored).

 - **shuffle** [bool, default=True] Whether or not to shuffle the data: might be important for models that make the assumption that the samples are independent and identically distributed (i.i.d.), such as stochastic gradient descent.

 - **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset shuffling. Pass an int for reproducible output across multiple function calls. See Glossary.

 - **remove** [tuple, default=()] May contain any subset of (‘headers’, ‘footers’, ‘quotes’). Each of these are kinds of text that will be detected and removed from the newsgroup posts, preventing classifiers from overfitting on metadata.

 - **download_if_missing** [bool, default=True] If False, raise an IOError if the data is not locally available instead of trying to download the data from the source site.

 - **return_X_y** [bool, default=False] If True, returns (data.data, data.target) instead of a Bunch object.

New in version 0.22.

Returns

 - **bunch** [Bunch] Dictionary-like object, with the following attributes.

 - **data** [list of shape (n_samples,)] The data list to learn.

 - **target:** [ndarray of shape (n_samples,)] The target labels.

 - **filenames:** [list of shape (n_samples,)] The path to the location of the data.

 - **DESCR:** [str] The full description of the dataset.
**target_names: list of shape (n_classes,)** The names of target classes.

*(data, target)* [tuple if return_X_y=True] New in version 0.22.

**Examples using sklearn.datasets.fetch_20newsgroups**

- Sample pipeline for text feature extraction and evaluation

```python
sklearn.datasets.fetch_20newsgroups_vectorized
```

```python
sklearn.datasets.fetch_20newsgroups_vectorized(*, subset='train', remove=(),
data_home=None, download_if_missing=True,
return_X_y=False, normalize=True,
as_frame=False)
```

Load and vectorize the 20 newsgroups dataset (classification).

Download it if necessary.

This is a convenience function; the transformation is done using the default settings for CountVectorizer. For more advanced usage (stopword filtering, n-gram extraction, etc.), combine fetch_20newsgroups with a custom CountVectorizer, HashingVectorizer, TfidfTransformer or TfidfVectorizer.

The resulting counts are normalized using `sklearn.preprocessing.normalize` unless normalize is set to False.

<table>
<thead>
<tr>
<th>Classes</th>
<th>20</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>18846</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>130107</td>
</tr>
<tr>
<td>Features</td>
<td>real</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

**Parameters**

- `subset` [‘train’, ‘test’, ‘all’], default=’train’) Select the dataset to load: ‘train’ for the training set, ‘test’ for the test set, ‘all’ for both, with shuffled ordering.

- `remove` [tuple, default=()] May contain any subset of (‘headers’, ‘footers’, ‘quotes’). Each of these are kinds of text that will be detected and removed from the newsgroup posts, preventing classifiers from overfitting on metadata.

  - ‘headers’ removes newsgroup headers, ‘footers’ removes blocks at the ends of posts that look like signatures, and ‘quotes’ removes lines that appear to be quoting another post.

- `data_home` [str, default=None] Specify an download and cache folder for the datasets. If None, all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

- `download_if_missing` [bool, default=True] If False, raise an IOError if the data is not locally available instead of trying to download the data from the source site.

- `return_X_y` [bool, default=False] If True, returns `(data.data, data.target)` instead of a Bunch object.

  New in version 0.20.

- `normalize` [bool, default=True] If True, normalizes each document’s feature vector to unit norm using `sklearn.preprocessing.normalize`. 

---

7.7. sklearn.datasets: Datasets
as_frame [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric, string, or categorical). The target is a pandas DataFrame or Series depending on the number of target_columns.

Returns

bunch [Bunch] Dictionary-like object, with the following attributes.

data: {sparse matrix, dataframe} of shape (n_samples, n_features) The input data matrix. If as_frame is True, data is a pandas DataFrame with sparse columns.

target: {ndarray, series} of shape (n_samples,) The target labels. If as_frame is True, target is a pandas Series.

target_names: list of shape (n_classes,) The names of target classes.

DESCR: str The full description of the dataset.

frame: dataframe of shape (n_samples, n_features + 1) Only present when as_frame=True. Pandas DataFrame with data and target.

New in version 0.24.

(data, target) [tuple if return_X_y is True] data and target would be of the format defined in the Bunch description above.

New in version 0.20.

Examples using sklearn.datasets.fetch_20newsgroups_vectorized

- Model Complexity Influence
- Multiclass sparse logistic regression on 20newsgroups
- The Johnson-Lindenstrauss bound for embedding with random projections

sklearn.datasets.fetch_california_housing

sklearn.datasets.fetch_california_housing(*, data_home=None, download_if_missing=True, return_X_y=False, as_frame=False)

Load the California housing dataset (regression).

<table>
<thead>
<tr>
<th>Samples total</th>
<th>20640</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>8</td>
</tr>
<tr>
<td>Features</td>
<td>real</td>
</tr>
<tr>
<td>Target</td>
<td>real 0.15 - 5.0</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

data_home [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.
**download_if_missing** [bool, default=True] If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.

**return_X_y** [bool, default=False] If True, returns `(data.data, data.target)` instead of a Bunch object.

New in version 0.20.

**as_frame** [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric, string or categorical). The target is a pandas DataFrame or Series depending on the number of target_columns.

New in version 0.23.

**Returns**

**dataset** [Bunch] Dictionary-like object, with the following attributes.

- **data** [ndarray, shape (20640, 8)] Each row corresponding to the 8 feature values in order. If `as_frame` is True, `data` is a pandas object.

- **target** [numpy array of shape (20640,)] Each value corresponds to the average house value in units of 100,000. If `as_frame` is True, `target` is a pandas object.

- **feature_names** [list of length 8] Array of ordered feature names used in the dataset.

- **DESCR** [string] Description of the California housing dataset.

- **frame** [pandas DataFrame] Only present when `as_frame=True`. DataFrame with `data` and `target`.

  New in version 0.23.

- **(data, target)** [tuple if `return_X_y` is True] New in version 0.20.

**Notes**

This dataset consists of 20,640 samples and 9 features.

**Examples using sklearn.datasets.fetch_california_housing**

- **Release Highlights for scikit-learn 0.24**
- **Partial Dependence and Individual Conditional Expectation Plots**
- **Imputing missing values with variants of IterativeImputer**
- **Imputing missing values before building an estimator**
- **Compare the effect of different scalers on data with outliers**
sklearn.datasets.fetch_covtype

`sklearn.datasets.fetch_covtype(*, data_home=None, download_if_missing=True, random_state=None, shuffle=False, return_X_y=False, as_frame=False)`

Load the covertype dataset (classification).
Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>7</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>581012</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>54</td>
</tr>
<tr>
<td>Features</td>
<td>int</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

data_home [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.
download_if_missing [bool, default=True] If False, raise a IOErrror if the data is not locally available instead of trying to download the data from the source site.
random_state [int, RandomState instance or None, default=None] Determines random number generation for dataset shuffling. Pass an int for reproducible output across multiple function calls. See Glossary.
shuffle [bool, default=False] Whether to shuffle dataset.
return_X_y [bool, default=False] If True, returns (data.data, data.target) instead of a Bunch object.
New in version 0.20.
as_frame [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If `return_X_y` is True, then (data, target) will be pandas DataFrames or Series as described below.
New in version 0.24.

Returns
dataset [Bunch] Dictionary-like object, with the following attributes.
data [ndarray of shape (581012, 54)] Each row corresponds to the 54 features in the dataset.
target [ndarray of shape (581012,)] Each value corresponds to one of the 7 forest cover-types with values ranging between 1 to 7.
frame [dataframe of shape (581012, 53)] Only present when as_frame=True. Contains data and target.
DESCR [str] Description of the forest covertype dataset.
feature_names [list] The names of the dataset columns.
target_names: list The names of the target columns.
(data, target) [tuple if return_X_y is True] New in version 0.20.
Examples using `sklearn.datasets.fetch_covtype`

- Release Highlights for scikit-learn 0.24
- Scalable learning with polynomial kernel approximation

`skslearn.datasets.fetch_kddcup99`

```python
skslearn.datasets.fetch_kddcup99(*, subset=None, data_home=None, shuffle=False,
random_state=None, percent10=True, download_if_missing=True, return_X_y=False, as_frame=False)
```

Load the kddcup99 dataset (classification).

Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>23</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>4898431</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>41</td>
</tr>
<tr>
<td>Features</td>
<td>discrete (int) or continuous (float)</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

New in version 0.18.

**Parameters**

- `data_home` [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders. .. versionadded:: 0.19
- `shuffle` [bool, default=False] Whether to shuffle dataset.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset shuffling and for selection of abnormal samples if subset='SA'. Pass an int for reproducible output across multiple function calls. See Glossary.
- `percent10` [bool, default=True] Whether to load only 10 percent of the data.
- `download_if_missing` [bool, default=True] If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.
- `return_X_y` [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object. New in version 0.20.
- `as_frame` [bool, default=False] If True, returns a pandas Dataframe for the data and target objects in the Bunch returned object; Bunch return object will also have a frame member. New in version 0.24.

**Returns**

- `data` [Bunch] Dictionary-like object, with the following attributes.
  - `data` [[ndarray, dataframe] of shape (494021, 41)] The data matrix to learn. If as_frame=True, data will be a pandas DataFrame.
target  [[ndarray, series] of shape (494021,)] The regression target for each sample. If 
as_frame=True, target will be a pandas Series.

frame  [dataframe of shape (494021, 42)] Only present when as_frame=True. Contains 
data and target.

DESCR  [str] The full description of the dataset.

feature_names  [list] The names of the dataset columns

target_names: list  The names of the target columns

(data, target)  [tuple if return_X_y is True] New in version 0.20.

sklearn.datasets.fetch_lfw_pairs

sklearn.datasets.fetch_lfw_pairs(*, subset='train', data_home=None, funneled=True, resize=0.5, color=False, slice_=slice(70, 195, None), slice(78, 172, None), download_if_missing=True)

Load the Labeled Faces in the Wild (LFW) pairs dataset (classification).

Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>13233</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>5828</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 255</td>
</tr>
</tbody>
</table>

In the official README.txt this task is described as the “Restricted” task. As I am not sure as to implement the “Unrestricted” variant correctly, I left it as unsupported for now.

The original images are 250 x 250 pixels, but the default slice and resize arguments reduce them to 62 x 47.

Read more in the User Guide.

Parameters

subset  [['train', 'test', '10_folds'], default='train'] Select the dataset to load: ‘train’ for the development training set, ‘test’ for the development test set, and ‘10_folds’ for the official evaluation set that is meant to be used with a 10-folds cross validation.

data_home  [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

funneled  [bool, default=True] Download and use the funneled variant of the dataset.

resize  [float, default=0.5] Ratio used to resize the each face picture.

color  [bool, default=False] Keep the 3 RGB channels instead of averaging them to a single gray level channel. If color is True the shape of the data has one more dimension than the shape with color = False.

slice_  [tuple of slice, default=(slice(70, 195), slice(78, 172))] Provide a custom 2D slice (height, width) to extract the ‘interesting’ part of the jpeg files and avoid use statistical correlation from the background

download_if_missing  [bool, default=True] If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.

Returns
**data**  
Bunch Dictionary-like object, with the following attributes.

**data**  
(ndarray of shape (2200, 5828)). Shape depends on subset.] Each row corresponds to 2 ravel’d face images of original size 62 x 47 pixels. Changing the slice_.resize or subset parameters will change the shape of the output.

**pairs**  
(ndarray of shape (2200, 2, 62, 47)). Shape depends on subset] Each row has 2 face images corresponding to same or different person from the dataset containing 5749 people. Changing the slice_.resize or subset parameters will change the shape of the output.

**target**  
(numpy array of shape (2200,). Shape depends on subset.] Labels associated to each pair of images. The two label values being different persons or the same person.

**DESCR**  
(string) Description of the Labeled Faces in the Wild (LFW) dataset.

```python
sklearn.datasets.fetch_lfw_people
```

```
sklearn.datasets.fetch_lfw_people(*, data_home=None, funneled=True, resize=0.5, min_faces_per_person=0, color=False, slice_=slice(70, 195, None), slice_(78, 172, None), download_if_missing=True, return_X_y=False)
```

Load the Labeled Faces in the Wild (LFW) people dataset (classification).

Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>5749</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>13233</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>5828</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 255</td>
</tr>
</tbody>
</table>

Read more in the *User Guide*.

**Parameters**

**data_home**  
(str, default=None) Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

**funneled**  
(bool, default=True) Download and use the funneled variant of the dataset.

**resize**  
(float, default=0.5) Ratio used to resize the each face picture.

**min_faces_per_person**  
(int, default=None) The extracted dataset will only retain pictures of people that have at least min_faces_per_person different pictures.

**color**  
(bool, default=False) Keep the 3 RGB channels instead of averaging them to a single gray level channel. If color is True the shape of the data has one more dimension than the shape with color = False.

**slice_**  
(tuple of slice, default=(slice(70, 195), slice(78, 172)]) Provide a custom 2D slice (height, width) to extract the ‘interesting’ part of the jpeg files and avoid use statistical correlation from the background.

**download_if_missing**  
(bool, default=True) If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.

**return_X_y**  
(bool, default=False) If True, returns (dataset.data, dataset.target) instead of a Bunch object. See below for more information about the dataset.data and dataset.target object.
New in version 0.20.

Returns
dataset [Bunch] Dictionary-like object, with the following attributes.

data [numpy array of shape (13233, 2914)] Each row corresponds to a ravelled face image of original size 62 x 47 pixels. Changing the slice_ or resize parameters will change the shape of the output.

images [numpy array of shape (13233, 62, 47)] Each row is a face image corresponding to one of the 5749 people in the dataset. Changing the slice_ or resize parameters will change the shape of the output.

target [numpy array of shape (13233,)] Labels associated to each face image. Those labels range from 0-5748 and correspond to the person IDs.

DESCR [string] Description of the Labeled Faces in the Wild (LFW) dataset.

(data, target) [tuple if return_X_y is True] New in version 0.20.

Examples using sklearn.datasets.fetch_lfw_people

- Faces recognition example using eigenfaces and SVMs

sklearn.datasets.fetch_olivetti_faces

sklearn.datasets.fetch_olivetti_faces(*, data_home=None, shuffle=False, random_state=0, download_if_missing=True, return_X_y=False)

Load the Olivetti faces data-set from AT&T (classification).

Download it if necessary.

<table>
<thead>
<tr>
<th>Classes</th>
<th>40</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>400</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>4096</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 1</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters
data_home [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

shuffle [bool, default=False] If True the order of the dataset is shuffled to avoid having images of the same person grouped.

random_state [int, RandomState instance or None, default=0] Determines random number generation for dataset shuffling. Pass an int for reproducible output across multiple function calls. See Glossary.

download_if_missing [bool, default=True] If False, raise a IOErr if the data is not locally available instead of trying to download the data from the source site.

return_X_y [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object.

New in version 0.22.
Returns

data [Bunch] Dictionary-like object, with the following attributes.

data: ndarray, shape (400, 4096) Each row corresponds to a ravelled face image of ori-

ignal size 64 x 64 pixels.

images [ndarray, shape (400, 64, 64)] Each row is a face image corresponding to one of the

40 subjects of the dataset.

target [ndarray, shape (400,)] Labels associated to each face image. Those labels are rang-

ing from 0-39 and correspond to the Subject IDs.

DESCR [str] Description of the modified Olivetti Faces Dataset.

(data, target) [tuple if return_X_y=True] New in version 0.22.

Examples using sklearn.datasets.fetch_olivetti_faces

- Online learning of a dictionary of parts of faces
- Faces dataset decompositions
- Pixel importances with a parallel forest of trees
- Face completion with a multi-output estimators

sklearn.datasets.fetch_openml

sklearn.datasets.fetch_openml (name: Optional[str] = None, *, version: Union[str, int] = 'ac-

tive', data_id: Optional[int] = None, data_home: Optional[str] = None, target_column: Optional[Union[str, List]] = 'default-
target', cache: bool = True, return_X_y: bool = False, as_frame: Union[str, bool] = 'auto')

Fetch dataset from openml by name or dataset id.

Datasets are uniquely identified by either an integer ID or by a combination of name and version (i.e. there might be multiple versions of the ‘iris’ dataset). Please give either name or data_id (not both). In case a name is given, a version can also be provided.

Read more in the User Guide.

New in version 0.20.

Note: EXPERIMENTAL

The API is experimental (particularly the return value structure), and might have small backward-incompatible changes without notice or warning in future releases.

Parameters

name [str, default=None] String identifier of the dataset. Note that OpenML can have multiple
datasets with the same name.

version [int or ‘active’, default=‘active’] Version of the dataset. Can only be provided if also
name is given. If ‘active’ the oldest version that’s still active is used. Since there may be
more than one active version of a dataset, and those versions may fundamentally be different
from one another, setting an exact version is highly recommended.
data_id [int, default=None] OpenML ID of the dataset. The most specific way of retrieving a dataset. If data_id is not given, name (and potential version) are used to obtain a dataset.

data_home [str, default=None] Specify another download and cache folder for the data sets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

target_column [str, list or None, default=’default-target’] Specify the column name in the data to use as target. If ‘default-target’, the standard target column a stored on the server is used. If None, all columns are returned as data and the target is None. If list (of strings), all columns with these names are returned as multi-target (Note: not all scikit-learn classifiers can handle all types of multi-output combinations)

cache [bool, default=True] Whether to cache downloaded datasets using joblib.

return_X_y [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target objects.

as_frame [bool or ‘auto’, default=’auto’] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric, string or categorical). The target is a pandas DataFrame or Series depending on the number of target_columns. The Bunch will contain a frame attribute with the target and the data. If return_X_y is True, then (data, target) will be pandas DataFrames or Series as describe above.

If as_frame is ‘auto’, the data and target will be converted to DataFrame or Series as if as_frame is set to True, unless the dataset is stored in sparse format.

Changed in version 0.24: The default value of as_frame changed from False to ‘auto’ in 0.24.

Returns

data [Bunch] Dictionary-like object, with the following attributes.

data [np.array, scipy.sparse.csr_matrix of floats, or pandas DataFrame] The feature matrix. Categorical features are encoded as ordinals.

target [np.array, pandas Series or DataFrame] The regression target or classification labels, if applicable. Dtype is float if numeric, and object if categorical. If as_frame is True, target is a pandas object.

DESCR [str] The full description of the dataset

feature_names [list] The names of the dataset columns

target_names: list The names of the target columns

New in version 0.22.

categories [dict or None] Maps each categorical feature name to a list of values, such that the value encoded as i is ith in the list. If as_frame is True, this is None.

details [dict] More metadata from OpenML

frame [pandas DataFrame] Only present when as_frame=True. DataFrame with data and target.

(data, target) [tuple if return_X_y is True]

Note: EXPERIMENTAL

This interface is experimental and subsequent releases may change attributes without notice (although there should only be minor changes to data and target).
Missing values in the ‘data’ are represented as NaN’s. Missing values in ‘target’ are represented as NaN’s (numerical target) or None (categorical target).

**Examples using sklearn.datasets.fetch_openml**

- Approximate nearest neighbors in TSNE

**sklearn.datasets.fetch_rcv1**

```python
sklearn.datasets.fetch_rcv1(*, data_home=None, subset='all', download_if_missing=True, random_state=None, shuffle=False, return_X_y=False)
```

Load the RCV1 multilabel dataset (classification).

Download it if necessary.

Version: RCV1-v2, vectors, full sets, topics multilabels.

<table>
<thead>
<tr>
<th>Classes</th>
<th>103</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>804414</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>47236</td>
</tr>
<tr>
<td>Features</td>
<td>real, between 0 and 1</td>
</tr>
</tbody>
</table>

Read more in the *User Guide.*

New in version 0.17.

**Parameters**

- **data_home** [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

- **subset** [{'train', 'test', 'all'}, default='all'] Select the dataset to load: ‘train’ for the training set (23149 samples), ‘test’ for the test set (781265 samples), ‘all’ for both, with the training samples first if shuffle is False. This follows the official LYRL2004 chronological split.

- **download_if_missing** [bool, default=True] If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.

- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset shuffling. Pass an int for reproducible output across multiple function calls. See *Glossary.*

- **shuffle** [bool, default=False] Whether to shuffle dataset.

- **return_X_y** [bool, default=False] If True, returns `(dataset.data, dataset.target)` instead of a Bunch object. See below for more information about the dataset.data and dataset.target object.

New in version 0.20.

**Returns**

- **dataset** [Bunch] Dictionary-like object, with the following attributes.
  - **data** [sparse matrix of shape (804414, 47236), dtype=np.float64] The array has 0.16% of non zero values. Will be of CSR format.
target [sparse matrix of shape (804414, 103), dtype=np.uint8] Each sample has a value of 1 in its categories, and 0 in others. The array has 3.15% of non zero values. Will be of CSR format.

sample_id [ndarray of shape (804414,), dtype=np.uint32.] Identification number of each sample, as ordered in dataset.data.

target_names [ndarray of shape (103,), dtype=object] Names of each target (RCV1 topics), as ordered in dataset.target.

DESCR [str] Description of the RCV1 dataset.

(data, target) [tuple if return_X_y is True] New in version 0.20.

**sklearn.datasets.fetch_species_distributions**

sklearn.datasets.fetch_species_distributions(*, data_home=None, download_if_missing=True)

Loader for species distribution dataset from Phillips et. al. (2006)

Read more in the *User Guide*.

**Parameters**

- **data_home** [str, default=None] Specify another download and cache folder for the datasets. By default all scikit-learn data is stored in ‘~/scikit_learn_data’ subfolders.

- **download_if_missing** [bool, default=True] If False, raise a IOError if the data is not locally available instead of trying to download the data from the source site.

**Returns**

- **data** [Bunch] Dictionary-like object, with the following attributes.

  - **coverages** [array, shape = [14, 1592, 1212]] These represent the 14 features measured at each point of the map grid. The latitude/longitude values for the grid are discussed below. Missing data is represented by the value -9999.

  - **train** [record array, shape = (1624,)] The training points for the data. Each point has three fields:
    - train[‘species’] is the species name
    - train[‘dd long’] is the longitude, in degrees
    - train[‘dd lat’] is the latitude, in degrees

  - **test** [record array, shape = (620,)] The test points for the data. Same format as the training data.

- **Nx, Ny** [integers] The number of longitudes (x) and latitudes (y) in the grid

- **x_left_lower_corner, y_left_lower_corner** [floats] The (x,y) position of the lower-left corner, in degrees

- **grid_size** [float] The spacing between points of the grid, in degrees
Notes

This dataset represents the geographic distribution of species. The dataset is provided by Phillips et. al. (2006).

The two species are:

- “Bradypus variegatus”, the Brown-throated Sloth.
- “Microryzomys minutus”, also known as the Forest Small Rice Rat, a rodent that lives in Peru, Colombia, Ecuador, Peru, and Venezuela.
- For an example of using this dataset with scikit-learn, see examples/applications/plot_species_distribution_modeling.py.

References


Examples using sklearn.datasets.fetch_species_distributions

- Species distribution modeling
- Kernel Density Estimate of Species Distributions

sklearn.datasets.get_data_home

sklearn.datasets.get_data_home(data_home=None) → str

Return the path of the scikit-learn data dir.

This folder is used by some large dataset loaders to avoid downloading the data several times.
By default the data dir is set to a folder named ‘scikit_learn_data’ in the user home folder.
Alternatively, it can be set by the ‘SCIKIT_LEARN_DATA’ environment variable or programmatically by giving an explicit folder path. The ‘~’ symbol is expanded to the user home folder.

If the folder does not already exist, it is automatically created.

Parameters

data_home [str, default=None] The path to scikit-learn data directory. If None, the default path is ~/scikit_learn_data.

Examples using sklearn.datasets.get_data_home

- Out-of-core classification of text documents
sklearn.datasets.load_boston

sklearn.datasets.load_boston(*, return_X_y=False)

Load and return the boston house-prices dataset (regression).

<table>
<thead>
<tr>
<th>Samples total</th>
<th>506</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimensionality</td>
<td>13</td>
</tr>
<tr>
<td>Features</td>
<td>real, positive</td>
</tr>
<tr>
<td>Targets</td>
<td>real 5. - 50.</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

- **return_X_y** [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object.
  
  New in version 0.18.

Returns

- **data** [Bunch] Dictionary-like object, with the following attributes.
  
  - data [ndarray of shape (506, 13)] The data matrix.
  - target [ndarray of shape (506, )] The regression target.
  - filename [str] The physical location of boston csv dataset.
  
  New in version 0.20.

- **DESCR** [str] The full description of the dataset.

- **feature_names** [ndarray] The names of features

- **(data, target)** [tuple if return_X_y is True] New in version 0.18.

Notes

Changed in version 0.20: Fixed a wrong data point at [445, 0].

Examples

```python
>>> from sklearn.datasets import load_boston
>>> X, y = load_boston(return_X_y=True)
>>> print(X.shape)
(506, 13)
```
**sklearn.datasets.load_breast_cancer**

Load and return the breast cancer wisconsin dataset (classification).

The breast cancer dataset is a classic and very easy binary classification dataset.

<table>
<thead>
<tr>
<th>Classes</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples per class</td>
<td>212(M),357(B)</td>
</tr>
<tr>
<td>Samples total</td>
<td>569</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>30</td>
</tr>
<tr>
<td>Features</td>
<td>real, positive</td>
</tr>
</tbody>
</table>

Read more in the *User Guide*.

**Parameters**

- `return_X_y` [bool, default=False] If True, returns `(data, target)` instead of a Bunch object. See below for more information about the `data` and `target` object.

  New in version 0.18.

- `as_frame` [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If `return_X_y` is True, then `(data, target)` will be pandas DataFrames or Series as described below.

  New in version 0.23.

**Returns**

- `data` [Bunch] Dictionary-like object, with the following attributes.

  - `data` [[ndarray, dataframe] of shape (569, 30)] The data matrix. If as_frame=True, data will be a pandas DataFrame.

  - `target`: [ndarray, Series] of shape (569,) The classification target. If as_frame=True, target will be a pandas Series.

  - `feature_names`: list The names of the dataset columns.

  - `target_names`: list The names of target classes.

  - `frame`: [DataFrame of shape (569, 31)] Only present when as_frame=True. DataFrame with data and target.

    New in version 0.23.

- `DESCR`: str The full description of the dataset.

- `filename`: str The path to the location of the data.

  New in version 0.20.

- `(data, target)` [tuple if return_X_y is True] New in version 0.18.

The copy of UCI ML Breast Cancer Wisconsin (Diagnostic) dataset is downloaded from:

https://goo.gl/U2Uwz2
Examples

Let's say you are interested in the samples 10, 50, and 85, and want to know their class name.

```python
>>> from sklearn.datasets import load_breast_cancer
>>> data = load_breast_cancer()
>>> data.target[[10, 50, 85]]
array([0, 1, 0])
>>> list(data.target_names)
['malignant', 'benign']
```

Examples using `sklearn.datasets.load_breast_cancer`

- Post pruning decision trees with cost complexity pruning
- Permutation Importance with Multicollinear or Correlated Features
- Effect of varying threshold for self-training

`sklearn.datasets.load_diabetes`

`sklearn.datasets.load_diabetes` (*, `return_X_y=False, as_frame=False*)

Load and return the diabetes dataset (regression).

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples</td>
<td>442</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>10</td>
</tr>
<tr>
<td>Features</td>
<td>real, (-0.2 &lt; x &lt; 0.2)</td>
</tr>
<tr>
<td>Targets</td>
<td>integer 25 - 346</td>
</tr>
</tbody>
</table>


Parameters

- `return_X_y` [bool, default=False] If True, returns `(data, target)` instead of a Bunch object. See below for more information about the `data` and `target` object.

  New in version 0.18.

- `as_frame` [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If `return_X_y` is True, then `(data, target)` will be pandas DataFrames or Series as described below.

  New in version 0.23.

Returns

- `data` [Bunch] Dictionary-like object, with the following attributes.

  - `data` [ndarray, dataframe] of shape (442, 10) The data matrix. If `as_frame=True`, `data` will be a pandas DataFrame.
  - `target` [ndarray, Series] of shape (442,) The regression target. If `as_frame=True`, `target` will be a pandas Series.
  - `feature_names` list The names of the dataset columns.
frame: DataFrame of shape (442, 11) Only present when as_frame=True.

DataFrame with data and target.

New in version 0.23.

DESCR: str The full description of the dataset.

data_filename: str The path to the location of the data.

target_filename: str The path to the location of the target.

(data, target) [tuple if return_X_y is True] New in version 0.18.

Examples using sklearn.datasets.load_diabetes

- Plot individual and voting regression predictions
- Gradient Boosting regression
- Model Complexity Influence
- Model-based and sequential feature selection
- Lasso path using LARS
- Linear Regression Example
- Sparsity Example: Fitting only features 1 and 2
- Lasso and Elastic Net
- Lasso model selection: Cross-Validation / AIC / BIC
- Advanced Plotting With Partial Dependence
- Imputing missing values before building an estimator
- Plotting Cross-Validated Predictions
- Cross-validation on diabetes Dataset Exercise

sklearn.datasets.load_digits

sklearn.datasets.load_digits(*, n_class=10, return_X_y=False, as_frame=False)

Load and return the digits dataset (classification).

Each datapoint is a 8x8 image of a digit.

<table>
<thead>
<tr>
<th>Classes</th>
<th>10</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples per class</td>
<td>~180</td>
</tr>
<tr>
<td>Samples total</td>
<td>1797</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>64</td>
</tr>
<tr>
<td>Features</td>
<td>integers 0-16</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

n_class [int, default=10] The number of classes to return. Between 0 and 10.
return_X_y [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object.

New in version 0.18.

as_frame [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If return_X_y is True, then (data, target) will be pandas DataFrames or Series as described below.

New in version 0.23.

Returns
data [Bunch] Dictionary-like object, with the following attributes.

data [[ndarray, dataframe] of shape (1797, 64)] The flattened data matrix. If as_frame=True, data will be a pandas DataFrame.

target: [ndarray, Series] of shape (1797,) The classification target. If as_frame=True, target will be a pandas Series.

feature_names: list The names of the dataset columns.

target_names: list The names of target classes.

New in version 0.20.

frame: DataFrame of shape (1797, 65) Only present when as_frame=True. DataFrame with data and target.

New in version 0.23.

images: [ndarray] of shape (1797, 8, 8) The raw image data.

DESCR: str The full description of the dataset.

(data, target) [tuple if return_X_y is True] New in version 0.18.

This is a copy of the test set of the UCI ML hand-written digits datasets


Examples

To load the data and visualize the images:

```python
>>> from sklearn.datasets import load_digits
>>> digits = load_digits()
>>> print(digits.data.shape)
(1797, 64)
>>> import matplotlib.pyplot as plt
>>> plt.gray()
>>> plt.matshow(digits.images[0])
>>> plt.show()
```
### Examples using \texttt{sklearn.datasets.load_digits}

- Recognizing hand-written digits
- Feature agglomeration
- Various Agglomerative Clustering on a 2D embedding of digits
- A demo of K-Means clustering on the handwritten digits data
- The Digit Dataset
- Early stopping of Gradient Boosting
- Recursive feature elimination
- Comparing various online solvers
- \textit{L1} Penalty and Sparsity in Logistic Regression
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...
- The Johnson-Lindenstrauss bound for embedding with random projections
- Explicit feature map approximation for \textit{RBF} kernels
- Plotting Validation Curves
- Parameter estimation using grid search with cross-validation
- Comparing randomized search and grid search for hyperparameter estimation
- Balance model complexity and cross-validated score
- Plotting Learning Curves
- Kernel Density Estimation
- Caching nearest neighbors
- Dimensionality Reduction with Neighborhood Components Analysis
- Restricted Boltzmann Machine features for digit classification
- Compare Stochastic learning strategies for \texttt{MLPClassifier}
- Pipelining: chaining a PCA and a logistic regression
- Selecting dimensionality reduction with Pipeline and GridSearchCV
- Label Propagation digits: Demonstrating performance
- Label Propagation digits active learning
- Digits Classification Exercise
- Cross-validation on Digits Dataset Exercise

7.7. \texttt{sklearn.datasets}: Datasets
scikit-learn user guide, Release 0.24.0

**sklearn.datasets.load_files**

```python
sklearn.datasets.load_files(container_path, *, description=None, categories=None, load_content=True, shuffle=True, encoding=None, decode_error='strict', random_state=0)
```

Load text files with categories as subfolder names.

Individual samples are assumed to be files stored a two levels folder structure such as the following:

```
container_folder/
category_1_folder/ file_1.txt file_2.txt . . . file_42.txt
category_2_folder/ file_43.txt file_44.txt . . .
```

The folder names are used as supervised signal label names. The individual file names are not important.

This function does not try to extract features into a numpy array or scipy sparse matrix. In addition, if `load_content` is false it does not try to load the files in memory.

To use text files in a scikit-learn classification or clustering algorithm, you will need to use the `~sklearn.feature_extraction.text` module to build a feature extraction transformer that suits your problem.

If you set `load_content=True`, you should also specify the encoding of the text using the `encoding` parameter. For many modern text files, ‘utf-8’ will be the correct encoding. If you leave encoding equal to None, then the content will be made of bytes instead of Unicode, and you will not be able to use most functions in text.

Similar feature extractors should be built for other kind of unstructured data input such as images, audio, video, ...

Read more in the User Guide.

**Parameters**

- `container_path` [str or unicode] Path to the main folder holding one subfolder per category
- `description` [str or unicode, default=None] A paragraph describing the characteristic of the dataset: its source, reference, etc.
- `categories` [list of str, default=None] If None (default), load all the categories. If not None, list of category names to load (other categories ignored).
- `load_content` [bool, default=True] Whether to load or not the content of the different files. If true a ‘data’ attribute containing the text information is present in the data structure returned. If not, a filenames attribute gives the path to the files.
- `shuffle` [bool, default=True] Whether or not to shuffle the data: might be important for models that make the assumption that the samples are independent and identically distributed (i.i.d.), such as stochastic gradient descent.
- `encoding` [str, default=None] If None, do not try to decode the content of the files (e.g. for images or other non-text content). If not None, encoding to use to decode text files to Unicode if `load_content` is True.
- `decode_error` [{'strict', 'ignore', 'replace'}, default='strict'] Instruction on what to do if a byte sequence is given to analyze that contains characters not of the given encoding. Passed as keyword argument ‘errors’ to bytes.decode.
- `random_state` [int, RandomState instance or None, default=0] Determines random number generation for dataset shuffling. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

- `data` [Bunch] Dictionary-like object, with the following attributes.
data  [list of str] Only present when load_content=True. The raw text data to learn.

target  [ndarray] The target labels (integer index).

target_names  [list] The names of target classes.

DESCR  [str] The full description of the dataset.

filenames: ndarray  The filenames holding the dataset.

```python
sklearn.datasets.load_iris
```

Load and return the iris dataset (classification).

The iris dataset is a classic and very easy multi-class classification dataset.

<table>
<thead>
<tr>
<th>Classes</th>
<th>3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples per class</td>
<td>50</td>
</tr>
<tr>
<td>Samples total</td>
<td>150</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>4</td>
</tr>
<tr>
<td>Features</td>
<td>real, positive</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

**Parameters**

- **return_X_y** [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object.

    New in version 0.18.

- **as_frame** [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If return_X_y is True, then (data, target) will be pandas DataFrames or Series as described below.

    New in version 0.23.

**Returns**

- **data**  [Bunch] Dictionary-like object, with the following attributes.

    - **data**  [(ndarray, dataframe) of shape (150, 4)] The data matrix. If as_frame=True, data will be a pandas DataFrame.

    - **target**  [(ndarray, Series) of shape (150,)] The classification target. If as_frame=True, target will be a pandas Series.

    - **feature_names**: list  The names of the dataset columns.

    - **target_names**: list  The names of target classes.

    - **frame**  [DataFrame of shape (150, 5)] Only present when as_frame=True. DataFrame with data and target.

        New in version 0.23.

    - **DESCR**: str  The full description of the dataset.

    - **filename**: str  The path to the location of the data.

        New in version 0.20.
(data, target) [tuple if return_X_y is True] New in version 0.18.

Notes

Changed in version 0.20: Fixed two wrong data points according to Fisher’s paper. The new version is the same as in R, but not as in the UCI Machine Learning Repository.

Examples

Let’s say you are interested in the samples 10, 25, and 50, and want to know their class name.

```python
>>> from sklearn.datasets import load_iris
>>> data = load_iris()
>>> data.target[[10, 25, 50]]
array([0, 0, 1])
>>> list(data.target_names)
['setosa', 'versicolor', 'virginica']
```

Examples using sklearn.datasets.load_iris

- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22
- Plot classification probability
- Plot Hierarchical Clustering Dendrogram
- K-means Clustering
- The Iris Dataset
- Plot the decision surface of a decision tree on the iris dataset
- Understanding the decision tree structure
- PCA example with Iris Data-set
- Incremental PCA
- Comparison of LDA and PCA 2D projection of Iris dataset
- Factor Analysis (with rotation) to visualize patterns
- Plot the decision boundaries of a VotingClassifier
- Early stopping of Gradient Boosting
- Plot the decision surfaces of ensembles of trees on the iris dataset
- Test with permutations the significance of a classification score
- Univariate Feature Selection
- GMM covariances
- Gaussian process classification (GPC) on iris dataset
- Regularization path of L1- Logistic Regression
- Logistic Regression 3-class Classifier
• Plot multi-class SGD on the iris dataset
• Confusion matrix
• Receiver Operating Characteristic (ROC) with cross validation
• Nested versus non-nested cross-validation
• Receiver Operating Characteristic (ROC)
• Precision-Recall
• Nearest Centroid Classification
• Nearest Neighbors Classification
• Comparing Nearest Neighbors with and without Neighborhood Components Analysis
• Compare Stochastic learning strategies for MLPClassifier
• Concatenating multiple feature extraction methods
• Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset
• SVM with custom kernel
• SVM-Anova: SVM with univariate feature selection
• Plot different SVM classifiers in the iris dataset
• RBF SVM parameters
• SVM Exercise

sklearn.datasets.load_linnerud

sklearn.datasets.load_linnerud(*, return_X_y=False, as_frame=False)

Load and return the physical exercise linnerud dataset.

This dataset is suitable for multi-output regression tasks.

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Samples total</td>
<td>20</td>
</tr>
<tr>
<td>Dimensionality</td>
<td>3 (for both data and target)</td>
</tr>
<tr>
<td>Features</td>
<td>integer</td>
</tr>
<tr>
<td>Targets</td>
<td>integer</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

Parameters

return_X_y [bool, default=False] If True, returns (data, target) instead of a Bunch object. See below for more information about the data and target object.

New in version 0.18.

as_frame [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric, string or categorical). The target is a pandas DataFrame or Series depending on the number of target columns. If return_X_y is True, then (data, target) will be pandas DataFrames or Series as described below.

New in version 0.23.

Returns

data [Bunch] Dictionary-like object, with the following attributes.
data  [[ndarray, dataframe] of shape (20, 3)] The data matrix. If as_frame=True, data
will be a pandas DataFrame.

target: [ndarray, dataframe] of shape (20, 3) The regression targets. If
as_frame=True, target will be a pandas DataFrame.

feature_names: list The names of the dataset columns.

target_names: list The names of the target columns.

frame: DataFrame of shape (20, 6) Only present when as_frame=True. DataFrame
with data and target.

New in version 0.23.

DESCR: str The full description of the dataset.

data_filename: str The path to the location of the data.

target_filename: str The path to the location of the target.

New in version 0.20.

(data, target) [tuple if return_X_y is True] New in version 0.18.

sklearn.datasets.load_sample_image

sklearn.datasets.load_sample_image(image_name)
Load the numpy array of a single sample image

Read more in the User Guide.

Parameters

image_name  [[china.jpg, flower.jpg]] The name of the sample image loaded

Returns

img  [3D array] The image as a numpy array: height x width x color

Examples

```python
>>> from sklearn.datasets import load_sample_image
>>> china = load_sample_image('china.jpg')
>>> china.dtype
dtype('uint8')
>>> china.shape
(427, 640, 3)
>>> flower = load_sample_image('flower.jpg')
>>> flower.dtype
dtype('uint8')
>>> flower.shape
(427, 640, 3)
```
Examples using `sklearn.datasets.load_sample_image`

- **Color Quantization using K-Means**

`sklearn.datasets.load_sample_images`

`sklearn.datasets.load_sample_images()`

> Load sample images for image manipulation.

> Loads both, `china` and `flower`.

> Read more in the *User Guide*.

**Returns**

- **data** `Bunch` Dictionary-like object, with the following attributes.
  - **images** [list of ndarray of shape (427, 640, 3)] The two sample image.
  - **filenames** [list] The filenames for the images.
  - **DESCR** [str] The full description of the dataset.

**Examples**

To load the data and visualize the images:

```python
>>> from sklearn.datasets import load_sample_images
>>> dataset = load_sample_images()
>>> len(dataset.images)
2
>>> first_img_data = dataset.images[0]
>>> first_img_data.shape
(427, 640, 3)
>>> first_img_data.dtype
dtype('uint8')
```

**sklearn.datasets.load_svmlight_file**

`sklearn.datasets.load_svmlight_file(f, *, n_features=None, dtype=<class 'numpy.float64'>, multilabel=False, zero_based='auto', query_id=False, offset=0, length=-1)`

Load datasets in the svmlight / libsvm format into sparse CSR matrix

This format is a text-based format, with one sample per line. It does not store zero valued features hence is suitable for sparse dataset.

The first element of each line can be used to store a target variable to predict.

This format is used as the default format for both svmlight and the libsvm command line programs.

Parsing a text based source can be expensive. When working on repeatedly on the same dataset, it is recommended to wrap this loader with joblib.Memory.cache to store a memmapped backup of the CSR results of the first call and benefit from the near instantaneous loading of memmapped structures for the subsequent calls.

In case the file contains a pairwise preference constraint (known as “qid” in the svmlight format) these are ignored unless the query_id parameter is set to True. These pairwise preference constraints can be used to
constraint the combination of samples when using pairwise loss functions (as is the case in some learning to
rank problems) so that only pairs with the same query_id value are considered.

This implementation is written in Cython and is reasonably fast. However, a faster API-compatible loader is
also available at:

https://github.com/mblondel/svmlight-loader

**Parameters**

- **f** [str, file-like or int] (Path to) a file to load. If a path ends in “.gz” or “.bz2”, it will be uncom-
  pressed on the fly. If an integer is passed, it is assumed to be a file descriptor. A file-like
  or file descriptor will not be closed by this function. A file-like object must be opened in
  binary mode.

- **n_features** [int, default=None] The number of features to use. If None, it will be inferred.
  This argument is useful to load several files that are subsets of a bigger sliced dataset: each
  subset might not have examples of every feature, hence the inferred shape might vary from
  one slice to another. n_features is only required if offset or length are passed a non-
  default value.

- **dtype** [numpy data type, default=np.float64] Data type of dataset to be loaded. This will be the
  data type of the output numpy arrays X and y.

- **multilabel** [bool, default=False] Samples may have several labels each (see https://www.csie.
  ntu.edu.tw/~cjlin/libsvmtools/datasets/multilabel.html)

- **zero_based** [bool or “auto”, default=”auto”] Whether column indices in f are zero-based (True)
  or one-based (False). If column indices are one-based, they are transformed to zero-based
  to match Python/NumPy conventions. If set to “auto”, a heuristic check is applied to de-
  termine this from the file contents. Both kinds of files occur “in the wild”, but they are
  unfortunately not self-identifying. Using “auto” or True should always be safe when no
  offset or length is passed. If offset or length are passed, the “auto” mode falls
  back to zero_based=True to avoid having the heuristic check yield inconsistent results
  on different segments of the file.

- **query_id** [bool, default=False] If True, will return the query_id array for each file.

- **offset** [int, default=0] Ignore the offset first bytes by seeking forward, then discarding the fol-
  lowing bytes up until the next new line character.

- **length** [int, default=-1] If strictly positive, stop reading any new line of data once the position
  in the file has reached the (offset + length) bytes threshold.

**Returns**

- **X** [scipy.sparse matrix of shape (n_samples, n_features)]

- **y** [ndarray of shape (n_samples,), or, in the multilabel a list of] tuples of length n_samples.

- **query_id** [array of shape (n_samples,)] query_id for each sample. Only returned when query_id
  is set to True.

**See also:**

- **load_svmlight_files** Similar function for loading multiple files in this format, enforcing the same num-
  ber of features/columns on all of them.
Examples

To use joblib.Memory to cache the svmlight file:

```python
from joblib import Memory
from .datasets import load_svmlight_file
mem = Memory("./mycache")

@mem.cache
def get_data():
    data = load_svmlight_file("mysvmlightfile")
    return data[0], data[1]

X, y = get_data()
```

`scklearn.datasets.load_svmlight_files`

This function is equivalent to mapping `load_svmlight_file` over a list of files, except that the results are concatenated into a single, flat list and the samples vectors are constrained to all have the same number of features.

In case the file contains a pairwise preference constraint (known as “qid” in the svmlight format) these are ignored unless the `query_id` parameter is set to True. These pairwise preference constraints can be used to constraint the combination of samples when using pairwise loss functions (as is the case in some learning to rank problems) so that only pairs with the same `query_id` value are considered.

Parameters

- `files` [array-like, dtype=str, file-like or int] (Paths of) files to load. If a path ends in “.gz” or “.bz2”, it will be uncompressed on the fly. If an integer is passed, it is assumed to be a file descriptor. File-likes and file descriptors will not be closed by this function. File-like objects must be opened in binary mode.

- `n_features` [int, default=None] The number of features to use. If None, it will be inferred from the maximum column index occurring in any of the files. This can be set to a higher value than the actual number of features in any of the input files, but setting it to a lower value will cause an exception to be raised.

- `dtype` [numpy data type, default=\texttt{np.float64}] Data type of dataset to be loaded. This will be the data type of the output numpy arrays \( X \) and \( Y \).

- `multilabel` [bool, default=False] Samples may have several labels each (see \url{https://www.csie.ntu.edu.tw/~cjlin/libsvmtools/datasets/multilabel.html})

- `zero_based` [bool or “auto”, default=”auto”] Whether column indices in \( f \) are zero-based (True) or one-based (False). If column indices are one-based, they are transformed to zero-based to match Python/NumPy conventions. If set to “auto”, a heuristic check is applied to determine this from the file contents. Both kinds of indices occur “in the wild”, but they are unfortunately not self-identifying. Using “auto” or True should always be safe when no offset or length is passed. If offset or length are passed, the “auto” mode falls back to zero_based=True to avoid having the heuristic check yield inconsistent results on different segments of the file.

- `query_id` [bool, default=False] If True, will return the `query_id` array for each file.
offset [int, default=0] Ignore the offset first bytes by seeking forward, then discarding the following bytes up until the next new line character.

length [int, default=-1] If strictly positive, stop reading any new line of data once the position in the file has reached the (offset + length) bytes threshold.

Returns

\[X_1, y_1, \ldots, X_n, y_n\]

where each \((X_i, y_i)\) pair is the result from \texttt{load_svmlight_file(files[i])}.

If \texttt{query_id} is set to True, this will return instead \([X_1, y_1, q_1, \ldots, X_n, y_n, q_n]\) where \((X_i, y_i, q_i)\) is the result from \texttt{load_svmlight_file(files[i])}

See also:

\texttt{load_svmlight_file}

Notes

When fitting a model to a matrix \(X_{\text{train}}\) and evaluating it against a matrix \(X_{\text{test}}\), it is essential that \(X_{\text{train}}\) and \(X_{\text{test}}\) have the same number of features \((X_{\text{train}}.\text{shape}[1] == X_{\text{test}}.\text{shape}[1])\). This may not be the case if you load the files individually with \texttt{load_svmlight_file}.

\texttt{sklearn.datasets.load_wine}

\texttt{sklearn.datasets.load_wine(*, return_X_y=False, as_frame=False)}

Load and return the wine dataset (classification).

New in version 0.18.

The wine dataset is a classic and very easy multi-class classification dataset.

| Classes | 3 |
| Samples per class | [59, 71, 48] |
| Samples total | 178 |
| Dimensionality | 13 |
| Features | real, positive |

Read more in the \textit{User Guide}.

Parameters

\texttt{return_X_y} [bool, default=False] If True, returns \((\text{data}, \text{target})\) instead of a Bunch object. See below for more information about the \texttt{data} and \texttt{target} object.

\texttt{as_frame} [bool, default=False] If True, the data is a pandas DataFrame including columns with appropriate dtypes (numeric). The target is a pandas DataFrame or Series depending on the number of target columns. If \texttt{return_X_y} is True, then \((\text{data}, \text{target})\) will be pandas DataFrames or Series as described below.

New in version 0.23.

Returns

\texttt{data} [\textit{Bunch}] Dictionary-like object, with the following attributes.
**data** [[ndarray, dataframe] of shape (178, 13)] The data matrix. If `as_frame=True`, `data` will be a pandas DataFrame.

**target**: [ndarray, Series] of shape (178,) The classification target. If `as_frame=True`, `target` will be a pandas Series.

**feature_names**: list The names of the dataset columns.

**target_names**: list The names of target classes.

**frame**: DataFrame of shape (178, 14) Only present when `as_frame=True`. DataFrame with `data` and `target`.

New in version 0.23.

**DESCR**: str The full description of the dataset.

`(data, target)` [tuple if `return_X_y` is True]

The copy of UCI ML Wine Data Set dataset is downloaded and modified to fit standard format from:


**Examples**

Let’s say you are interested in the samples 10, 80, and 140, and want to know their class name.

```python
>>> from sklearn.datasets import load_wine
>>> data = load_wine()
>>> data.target[[10, 80, 140]]
array([0, 1, 2])
>>> list(data.target_names)
['class_0', 'class_1', 'class_2']
```

**Examples using sklearn.datasets.load_wine**

- **Outlier detection on a real data set**
- **ROC Curve with Visualization API**
- **Importance of Feature Scaling**

**7.7.2 Samples generator**

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</tr>
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<td>Generate a random regression problem with sparse uncorrelated design.</td>
</tr>
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<td><code>datasets.make_spd_matrix</code> ([n_dim, *[, …]])</td>
<td>Generate a random symmetric, positive-definite matrix.</td>
</tr>
<tr>
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<td>Generate a swiss roll dataset.</td>
</tr>
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#### sklearn.datasets.make_biclusters

`sklearn.datasets.make_biclusters` *(shape, n_clusters, *, noise=0.0, minval=10, maxval=100, shuffle=True, random_state=None)*

Generate an array with constant block diagonal structure for biclustering.

**Read more in the User Guide.**

**Parameters**

- `shape` [iterable of shape (n_rows, n_cols)] The shape of the result.
- `n_clusters` [int] The number of biclusters.
- `noise` [float, default=0.0] The standard deviation of the gaussian noise.
- `maxval` [int, default=100] Maximum value of a bicluster.
- `shuffle` [bool, default=True] Shuffle the samples.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

- `X` [ndarray of shape `shape`] The generated array.
- `rows` [ndarray of shape (n_clusters, X.shape[0])] The indicators for cluster membership of each row.
cols [ndarray of shape (n_clusters, X.shape[1])] The indicators for cluster membership of each column.

See also:

make_checkerboard

References

[1]

Examples using sklearn.datasets.make_biclusters

• A demo of the Spectral Co-Clustering algorithm

sklearn.datasets.make_blobs

sklearn.datasets.make_blobs (n_samples=100, n_features=2, *, centers=None, cluster_std=1.0, center_box=(-10.0, 10.0), shuffle=True, random_state=None, return_centers=False)

Generate isotropic Gaussian blobs for clustering.

Read more in the User Guide.

Parameters

n_samples [int or array-like, default=100] If int, it is the total number of points equally divided among clusters. If array-like, each element of the sequence indicates the number of samples per cluster.

Changed in version v0.20: one can now pass an array-like to the n_samples parameter

n_features [int, default=2] The number of features for each sample.

centers [int or ndarray of shape (n_centers, n_features), default=None] The number of centers to generate, or the fixed center locations. If n_samples is an int and centers is None, 3 centers are generated. If n_samples is array-like, centers must be either None or an array of length equal to the length of n_samples.

center_std [float or array-like of float, default=1.0] The standard deviation of the clusters.

center_box [tuple of float (min, max), default=(-10.0, 10.0)] The bounding box for each cluster center when centers are generated at random.

shuffle [bool, default=True] Shuffle the samples.

random_state [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

return_centers [bool, default=False] If True, then return the centers of each cluster

New in version 0.23.

Returns

X [ndarray of shape (n_samples, n_features)] The generated samples.

y [ndarray of shape (n_samples,)] The integer labels for cluster membership of each sample.
centers  [ndarray of shape (n_centers, n_features)] The centers of each cluster. Only returned if return_centers=True.

See also:

make_classification  A more intricate variant.

Examples

```python
>>> from sklearn.datasets import make_blobs
>>> X, y = make_blobs(n_samples=10, centers=3, n_features=2,
...                    random_state=0)
>>> print(X.shape)
(10, 2)
>>> y
array([0, 0, 1, 0, 2, 2, 2, 1, 1, 0])
>>> X, y = make_blobs(n_samples=[3, 3, 4], centers=None, n_features=2,
...                    random_state=0)
>>> print(X.shape)
(10, 2)
>>> y
array([0, 1, 2, 0, 2, 2, 2, 1, 1, 0])
```

Examples using sklearn.datasets.make_blobs

- Release Highlights for scikit-learn 0.23
- Probability calibration of classifiers
- Probability Calibration for 3-class classification
- Normal, Ledoit-Wolf and OAS Linear Discriminant Analysis for classification
- An example of K-Means++ initialization
- A demo of the mean-shift clustering algorithm
- Demonstration of k-means assumptions
- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- Inductive Clustering
- Compare BIRCH and MiniBatchKMeans
- Comparison of the K-Means and MiniBatchKMeans clustering algorithms
- Comparing different hierarchical linkage methods on toy datasets
- Selecting the number of clusters with silhouette analysis on KMeans clustering
- Comparing different clustering algorithms on toy datasets
- Plot randomly generated classification dataset
- SGD: Maximum margin separating hyperplane
- Plot multinomial and One-vs-Rest Logistic Regression
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Demonstrating the different strategies of KBinsDiscretizer

SVM: Maximum margin separating hyperplane

SVM Tie Breaking Example

Plot the support vectors in LinearSVC

SVM: Separating hyperplane for unbalanced classes

```python
sklearn.datasets.make_checkerboard
```

`sklearn.datasets.make_checkerboard(shape, n_clusters, *, noise=0.0, minval=10, maxval=100, shuffle=True, random_state=None)`

Generate an array with block checkerboard structure for biclustering.

Read more in the User Guide.

**Parameters**

- `shape` [tuple of shape (n_rows, n_cols)] The shape of the result.
- `n_clusters` [int or array-like or shape (n_row_clusters, n_column_clusters)] The number of row and column clusters.
- `noise` [float, default=0.0] The standard deviation of the gaussian noise.
- `maxval` [int, default=100] Maximum value of a bicluster.
- `shuffle` [bool, default=True] Shuffle the samples.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

- `X` [ndarray of shape `shape`] The generated array.
- `rows` [ndarray of shape (n_clusters, X.shape[0])] The indicators for cluster membership of each row.
- `cols` [ndarray of shape (n_clusters, X.shape[1])] The indicators for cluster membership of each column.

See also:

- `make_biclusters`

**References**

[1]
Examples using `sklearn.datasets.make_checkerboard`

- A demo of the Spectral Biclustering algorithm

`sklearn.datasets.make_circles`

`sklearn.datasets.make_circles(n_samples=100, *, shuffle=True, noise=None, random_state=None, factor=0.8)`

Make a large circle containing a smaller circle in 2d.

A simple toy dataset to visualize clustering and classification algorithms.

Read more in the User Guide.

**Parameters**

- `n_samples` [int or tuple of shape (2,), dtype=int, default=100] If int, it is the total number of points generated. For odd numbers, the inner circle will have one point more than the outer circle. If two-element tuple, number of points in outer circle and inner circle.
  
  Changed in version 0.23: Added two-element tuple.

- `shuffle` [bool, default=True] Whether to shuffle the samples.

- `noise` [float, default=None] Standard deviation of Gaussian noise added to the data.

- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset shuffling and noise. Pass an int for reproducible output across multiple function calls. See Glossary.

- `factor` [float, default=.8] Scale factor between inner and outer circle in the range (0, 1).

**Returns**

- `X` [ndarray of shape (n_samples, 2)] The generated samples.

- `y` [ndarray of shape (n_samples,)] The integer labels (0 or 1) for class membership of each sample.

Examples using `sklearn.datasets.make_circles`

- Classifier comparison
- Comparing different hierarchical linkage methods on toy datasets
- Comparing different clustering algorithms on toy datasets
- Kernel PCA
- Hashing feature transformation using Totally Random Trees
- t-SNE: The effect of various perplexity values on the shape
- Compare Stochastic learning strategies for MLPClassifier
- Varying regularization in Multi-layer Perceptron
- Feature discretization
- Label Propagation learning a complex structure
sklearn.datasets.make_classification

sklearn.datasets.make_classification(n_samples=100, n_features=20, *, n_informative=2, n_redundant=2, n_repeated=0, n_classes=2, n_clusters_per_class=2, weights=None, flip_y=0.01, class_sep=1.0, hypercube=True, shift=0.0, scale=1.0, shuffle=True, random_state=None)

Generate a random n-class classification problem.

This initially creates clusters of points normally distributed (std=1) about vertices of an \( n_{\text{informative}} \)-dimensional hypercube with sides of length \( 2 \times \text{class_sep} \) and assigns an equal number of clusters to each class. It introduces interdependence between these features and adds various types of further noise to the data.

Without shuffling, \( X \) horizontally stacks features in the following order: the primary \( n_{\text{informative}} \) features, followed by \( n_{\text{redundant}} \) linear combinations of the informative features, followed by \( n_{\text{repeated}} \) duplicates, drawn randomly with replacement from the informative and redundant features. The remaining features are filled with random noise. Thus, without shuffling, all useful features are contained in the columns \( X[:, :n_{\text{informative}} + n_{\text{redundant}} + n_{\text{repeated}}] \).

Read more in the User Guide.

Parameters

- **n_samples** [int, default=100] The number of samples.
- **n_features** [int, default=20] The total number of features. These comprise \( n_{\text{informative}} \) informative features, \( n_{\text{redundant}} \) redundant features, \( n_{\text{repeated}} \) duplicated features and \( n_{\text{features}} - n_{\text{informative}} - n_{\text{redundant}} - n_{\text{repeated}} \) useless features drawn at random.
- **n_informative** [int, default=2] The number of informative features. Each class is composed of a number of gaussian clusters each located around the vertices of a hypercube in a subspace of dimension \( n_{\text{informative}} \). For each cluster, informative features are drawn independently from \( \mathcal{N}(0, 1) \) and then randomly linearly combined within each cluster in order to add covariance. The clusters are then placed on the vertices of the hypercube.
- **n_redundant** [int, default=2] The number of redundant features. These features are generated as random linear combinations of the informative features.
- **n_repeated** [int, default=0] The number of duplicated features, drawn randomly from the informative and the redundant features.
- **n_classes** [int, default=2] The number of classes (or labels) of the classification problem.
- **n_clusters_per_class** [int, default=2] The number of clusters per class.
- **weights** [array-like of shape (n_classes,) or (n_classes - 1,), default=None] The proportions of samples assigned to each class. If None, then classes are balanced. Note that if \( \text{len(weights)} \neq \text{n_classes} - 1 \), then the last class weight is automatically inferred. More than \( n_{\text{samples}} \) samples may be returned if the sum of \( \text{weights} \) exceeds \( 1 \). Note that the actual class proportions will not exactly match \( \text{weights} \) when \( \text{flip_y} \) isn’t 0.
- **flip_y** [float, default=0.01] The fraction of samples whose class is assigned randomly. Larger values introduce noise in the labels and make the classification task harder. Note that the default setting \( \text{flip_y} > 0 \) might lead to less than \( n_{\text{classes}} \) in \( y \) in some cases.
- **class_sep** [float, default=1.0] The factor multiplying the hypercube size. Larger values spread out the clusters/classes and make the classification task easier.
- **hypercube** [bool, default=True] If True, the clusters are put on the vertices of a hypercube. If False, the clusters are put on the vertices of a random polytope.
**shift** [float, ndarray of shape (n_features,) or None, default=0.0] Shift features by the specified value. If None, then features are shifted by a random value drawn in [-class_sep, class_sep].

**scale** [float, ndarray of shape (n_features,) or None, default=1.0] Multiply features by the specified value. If None, then features are scaled by a random value drawn in [1, 100]. Note that scaling happens after shifting.

**shuffle** [bool, default=True] Shuffle the samples and the features.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

X [ndarray of shape (n_samples, n_features)] The generated samples.

y [ndarray of shape (n_samples,)] The integer labels for class membership of each sample.

**See also:**

- make_blobs Simplified variant.
- make_multilabel_classification Unrelated generator for multilabel tasks.

**Notes**

The algorithm is adapted from Guyon [1] and was designed to generate the “Madelon” dataset.

**References**

[1]

**Examples using sklearn.datasets.make_classification**

- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22
- Comparison of Calibration of Classifiers
- Probability Calibration curves
- Classifier comparison
- Plot randomly generated classification dataset
- Feature importances with forests of trees
- OOB Errors for Random Forests
- Feature transformations with ensembles of trees
- Pipeline Anova SVM
- Recursive feature elimination with cross-validation
- Detection error tradeoff (DET) curve
- Successive Halving Iterations
- Comparison between grid search and successive halving
Neighborhood Components Analysis Illustration
Varying regularization in Multi-layer Perceptron
Feature discretization
Scaling the regularization parameter for SVCs

`sklearn.datasets.make_friedman1`

`sklearn.datasets.make_friedman1(n_samples=100, n_features=10, *, noise=0.0, random_state=None)`

Generate the “Friedman #1” regression problem.
This dataset is described in Friedman [1] and Breiman [2].
Inputs \( X \) are independent features uniformly distributed on the interval \([0, 1]\). The output \( y \) is created according to the formula:

\[
y(X) = 10 \times \sin(\pi \times X[:, 0] \times X[:, 1]) + 20 \times (X[:, 2] - 0.5)^2 + 10 \times X[:, 3] + 5 \times X[:, 4] + \text{noise} \times N(0, 1).
\]

Out of the \( n\text{-features} \) features, only 5 are actually used to compute \( y \). The remaining features are independent of \( y \).
The number of features has to be \( >= 5 \).
Read more in the User Guide.

**Parameters**

- `n_samples` [int, default=100] The number of samples.
- `n_features` [int, default=10] The number of features. Should be at least 5.
- `noise` [float, default=0.0] The standard deviation of the gaussian noise applied to the output.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset noise. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

- `X` [ndarray of shape `(n_samples, n_features)`] The input samples.
- `y` [ndarray of shape `(n_samples,)`] The output values.

**References**

[1], [2]
sklearn.datasets.make_friedman2

sklearn.datasets.make_friedman2 (n_samples=100, *, noise=0.0, random_state=None)
Generate the “Friedman #2” regression problem.

This dataset is described in Friedman [1] and Breiman [2].

Inputs X are 4 independent features uniformly distributed on the intervals:

0 <= X[:, 0] <= 100,
40 * pi <= X[:, 1] <= 560 * pi,
0 <= X[:, 2] <= 1,
1 <= X[:, 3] <= 11.

The output y is created according to the formula:

\[ y(X) = (X[:, 0]^2 + (X[:, 1] \times X[:, 2] - 1 / (X[:, 1] \times X[:, 3]))^2)^{0.5} + \text{noise} \times \mathcal{N}(0, 1). \]

Read more in the User Guide.

Parameters

- **n_samples** [int, default=100] The number of samples.
- **noise** [float, default=0.0] The standard deviation of the gaussian noise applied to the output.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset noise. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- **X** [ndarray of shape (n_samples, 4)] The input samples.
- **y** [ndarray of shape (n_samples,)] The output values.

References

[1],[2]

sklearn.datasets.make_friedman3

sklearn.datasets.make_friedman3 (n_samples=100, *, noise=0.0, random_state=None)
Generate the “Friedman #3” regression problem.

This dataset is described in Friedman [1] and Breiman [2].

Inputs X are 4 independent features uniformly distributed on the intervals:

0 <= X[:, 0] <= 100,
40 * pi <= X[:, 1] <= 560 * pi,
0 <= X[:, 2] <= 1,
1 <= X[:, 3] <= 11.

The output y is created according to the formula:

\[ y(X) = \arctan((X[:, 1] \times X[:, 2] - 1 / (X[:, 1] \times X[:, 3])) / X[:, 0]) + \text{noise} \times \mathcal{N}(0, 1). \]
Parameters

- **n_samples** [int, default=100] The number of samples.
- **noise** [float, default=0.0] The standard deviation of the gaussian noise applied to the output.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset noise. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- X [ndarray of shape (n_samples, 4)] The input samples.
- y [ndarray of shape (n_samples,)] The output values.

References

[1], [2]

**sklearn.datasets.make_gaussian_quantiles**

Generate isotropic Gaussian and label samples by quantile.

This classification dataset is constructed by taking a multi-dimensional standard normal distribution and defining classes separated by nested concentric multi-dimensional spheres such that roughly equal numbers of samples are in each class (quantiles of the $\chi^2$ distribution).

Read more in the *User Guide*.

Parameters

- **mean** [ndarray of shape (n_features,), default=None] The mean of the multi-dimensional normal distribution. If None then use the origin (0, 0, ...).
- **cov** [float, default=1.0] The covariance matrix will be this value times the unit matrix. This dataset only produces symmetric normal distributions.
- **n_samples** [int, default=100] The total number of points equally divided among classes.
- **n_features** [int, default=2] The number of features for each sample.
- **n_classes** [int, default=3] The number of classes
- **shuffle** [bool, default=True] Shuffle the samples.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- X [ndarray of shape (n_samples, n_features)] The generated samples.
- y [ndarray of shape (n_samples,)] The integer labels for quantile membership of each sample.
Notes

The dataset is from Zhu et al [1].

References

[1]

Examples using sklearn.datasets.make_gaussian_quantiles

- Plot randomly generated classification dataset
- Two-class AdaBoost
- Multi-class AdaBoosted Decision Trees

sklearn.datasets.make_hastie_10_2

sklearn.datasets.make_hastie_10_2(n_samples=12000, *, random_state=None)

Generates data for binary classification used in Hastie et al. 2009, Example 10.2.

The ten features are standard independent Gaussian and the target $y$ is defined by:

\[
y[i] = \begin{cases} 
1 & \text{if } \sum (X[i] ** 2) > 9.34 \\
-1 & \text{else}
\end{cases}
\]

Read more in the User Guide.

Parameters

- **n_samples** [int, default=12000] The number of samples.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- **X** [ndarray of shape (n_samples, 10)] The input samples.
- **y** [ndarray of shape (n_samples,)] The output values.

See also:

- make_gaussian_quantiles A generalization of this dataset approach.

References

[1]
Examples using `sklearn.datasets.make_hastie_10_2`

- Gradient Boosting regularization
- Discrete versus Real AdaBoost
- Early stopping of Gradient Boosting
- Demonstration of multi-metric evaluation on `cross_val_score` and `GridSearchCV`

`sklearn.datasets.make_low_rank_matrix`

```python
sklearn.datasets.make_low_rank_matrix(n_samples=100, n_features=100, *
, effective_rank=10, tail_strength=0.5, ran-
dom_state=None)
```

Generate a mostly low rank matrix with bell-shaped singular values.

Most of the variance can be explained by a bell-shaped curve of width `effective_rank`: the low rank part of the singular values profile is:

\[
(1 - \text{tail_strength}) \times \exp(-1.0 \times (i / \text{effective_rank}) ^ 2)
\]

The remaining singular values’ tail is fat, decreasing as:

\[
\text{tail_strength} \times \exp(-0.1 \times i / \text{effective_rank}).
\]

The low rank part of the profile can be considered the structured signal part of the data while the tail can be considered the noisy part of the data that cannot be summarized by a low number of linear components (singular vectors).

This kind of singular profiles is often seen in practice, for instance:

- gray level pictures of faces
- TF-IDF vectors of text documents crawled from the web

Read more in the User Guide.

Parameters

- `n_samples` [int, default=100] The number of samples.
- `n_features` [int, default=100] The number of features.
- `effective_rank` [int, default=10] The approximate number of singular vectors required to explain most of the data by linear combinations.
- `tail_strength` [float, default=0.5] The relative importance of the fat noisy tail of the singular values profile. The value should be between 0 and 1.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- `X` [ndarray of shape (n_samples, n_features)] The matrix.
**sklearn.datasets.make_moons**

`sklearn.datasets.make_moons(n_samples=100, *, shuffle=True, noise=None, random_state=None)`


**Parameters**

- **n_samples**  
  [int or tuple of shape (2,), dtype=int, default=100] If int, the total number of points generated. If two-element tuple, number of points in each of two moons. Changed in version 0.23: Added two-element tuple.
- **shuffle**  
  [bool, default=True] Whether to shuffle the samples.
- **noise**  
  [float, default=None] Standard deviation of Gaussian noise added to the data.
- **random_state**  

**Returns**

- **X**  
  [ndarray of shape (n_samples, 2)] The generated samples.
- **y**  
  [ndarray of shape (n_samples,)] The integer labels (0 or 1) for class membership of each sample.

**Examples using sklearn.datasets.make_moons**

- [Classifier comparison](https://scikit-learn.org/stable/auto_examples/plot_classifier_comparison.html)
- [Comparing different hierarchical linkage methods on toy datasets](https://scikit-learn.org/stable/auto_examples/plot_linkage_methods.html)
- [Comparing different clustering algorithms on toy datasets](https://scikit-learn.org/stable/auto_examples/plot_clustering_algorithms.html)
- [Comparing anomaly detection algorithms for outlier detection on toy datasets](https://scikit-learn.org/stable/auto_examples/plot_anomaly_detection.html)
- [Statistical comparison of models using grid search](https://scikit-learn.org/stable/auto_examples/model_selection/plot_parameter_space.html)
- [Compare Stochastic learning strategies for MLPClassifier](https://scikit-learn.org/stable/auto_examples/linear_model/plot_sgd.html)

**sklearn.datasets.make_multilabel_classification**

`sklearn.datasets.make_multilabel_classification(n_samples=100, n_features=20, *, n_classes=5, n_labels=2, length=50, allow_unlabeled=True, sparse=False, return_indicator='dense', return_distributions=False, random_state=None)`

Generate a random multilabel classification problem. For each sample, the generative process is:

- pick the number of labels: n ~ Poisson(n_labels)
- n times, choose a class c: c ~ Multinomial(theta)
• pick the document length: k \sim \text{Poisson}(\text{length})
• k times, choose a word: w \sim \text{Multinomial}(\theta_c)

In the above process, rejection sampling is used to make sure that n is never zero or more than \( n_{classes} \), and that the document length is never zero. Likewise, we reject classes which have already been chosen.

Read more in the User Guide.

Parameters

n_samples [int, default=100] The number of samples.

n_features [int, default=20] The total number of features.

n_classes [int, default=5] The number of classes of the classification problem.

n_labels [int, default=2] The average number of labels per instance. More precisely, the number of labels per sample is drawn from a Poisson distribution with \( n_{labels} \) as its expected value, but samples are bounded (using rejection sampling) by \( n_{classes} \), and must be nonzero if allow_unlabeled is False.

length [int, default=50] The sum of the features (number of words if documents) is drawn from a Poisson distribution with this expected value.

allow_unlabeled [bool, default=True] If True, some instances might not belong to any class.

sparse [bool, default=False] If True, return a sparse feature matrix.

New in version 0.17: parameter to allow sparse output.

return_indicator [‘dense’, ‘sparse’] or False, default=’dense’) If ‘dense’ return Y in the dense binary indicator format. If ‘sparse’ return Y in the sparse binary indicator format. False returns a list of lists of labels.

return_distributions [bool, default=False] If True, return the prior class probability and conditional probabilities of features given classes, from which the data was drawn.

random_state [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

X [ndarray of shape (n_samples, n_features)] The generated samples.

Y [{ndarray, sparse matrix} of shape (n_samples, n_classes)] The label sets. Sparse matrix should be of CSR format.

p_c [ndarray of shape (n_classes,)] The probability of each class being drawn. Only returned if return_distributions=True.

p_w_c [ndarray of shape (n_features, n_classes)] The probability of each feature being drawn given each class. Only returned if return_distributions=True.
Examples using `sklearn.datasets.make_multilabel_classification`

- Plot randomly generated multilabel dataset
- Multilabel classification

`sklearn.datasets.make_regression`

```python
sklearn.datasets.make_regression(n_samples=100, n_features=100, *, n_informative=10,
   n_targets=1, bias=0.0, effective_rank=None,
   tail_strength=0.5, noise=0.0, shuffle=True, coef=False,
   random_state=None)
```

Generate a random regression problem.

The input set can either be well conditioned (by default) or have a low rank-fat tail singular profile. See `make_low_rank_matrix` for more details.

The output is generated by applying a (potentially biased) random linear regression model with `n_informative` nonzero regressors to the previously generated input and some gaussian centered noise with some adjustable scale.

Read more in the [User Guide](https://scikit-learn.org/stable/).  

**Parameters**

- `n_samples` [int, default=100] The number of samples.
- `n_features` [int, default=100] The number of features.
- `n_informative` [int, default=10] The number of informative features, i.e., the number of features used to build the linear model used to generate the output.
- `n_targets` [int, default=1] The number of regression targets, i.e., the dimension of the y output vector associated with a sample. By default, the output is a scalar.
- `bias` [float, default=0.0] The bias term in the underlying linear model.
- `effective_rank` [int, default=None]  
  - If not None: The approximate number of singular vectors required to explain most of the input data by linear combinations. Using this kind of singular spectrum in the input allows the generator to reproduce the correlations often observed in practice.
  - If None: The input set is well conditioned, centered and gaussian with unit variance.
- `tail_strength` [float, default=0.5] The relative importance of the fat noisy tail of the singular values profile if `effective_rank` is not None. When a float, it should be between 0 and 1.
- `noise` [float, default=0.0] The standard deviation of the gaussian noise applied to the output.
- `shuffle` [bool, default=True] Shuffle the samples and the features.
- `coef` [bool, default=False] If True, the coefficients of the underlying linear model are returned.
- `random_state` [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See [Glossary](https://scikit-learn.org/stable/glossary/).

**Returns**

- `X` [ndarray of shape (n_samples, n_features)] The input samples.
- `y` [ndarray of shape (n_samples,) or (n_samples, n_targets)] The output values.
**coef** [ndarray of shape (n_features,) or (n_features, n_targets)] The coefficient of the underlying linear model. It is returned only if coef is True.

**Examples using sklearn.datasets.make_regression**

- Release Highlights for scikit-learn 0.23
- Prediction Latency
- Plot Ridge coefficients as a function of the L2 regularization
- Robust linear model estimation using RANSAC
- HuberRegressor vs Ridge on dataset with strong outliers
- Lasso on dense and sparse data
- Effect of transforming the targets in regression model

**sklearn.datasets.make_s_curve**

sklearn.datasets.make_s_curve(n_samples=100, *, noise=0.0, random_state=None)

Generate an S curve dataset.

Read more in the User Guide.

**Parameters**

- **n_samples** [int, default=100] The number of sample points on the S curve.
- **noise** [float, default=0.0] The standard deviation of the gaussian noise.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

**Returns**

- **X** [ndarray of shape (n_samples, 3)] The points.
- **t** [ndarray of shape (n_samples,)] The univariate position of the sample according to the main dimension of the points in the manifold.

**Examples using sklearn.datasets.make_s_curve**

- Comparison of Manifold Learning methods
- t-SNE: The effect of various perplexity values on the shape
sklearn.datasets.make_sparse_coded_signal

Generate a signal as a sparse combination of dictionary elements.

Returns a matrix \( Y = DX \), such as \( D \) is \( (n\text{\_features}, n\text{\_components}) \), \( X \) is \( (n\text{\_components}, n\text{\_samples}) \) and each column of \( X \) has exactly \( n\text{\_nonzero\_coefs} \) non-zero elements.

Read more in the User Guide.

Parameters

- **n_samples**: [int] Number of samples to generate
- **n_components**: [int] Number of components in the dictionary
- **n_features**: [int] Number of features of the dataset to generate
- **n_nonzero_coefs**: [int] Number of active (non-zero) coefficients in each sample
- **random_state**: [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- **data**: [ndarray of shape \((n\text{\_features}, n\text{\_samples})\)] The encoded signal \((Y)\).
- **dictionary**: [ndarray of shape \((n\text{\_features}, n\text{\_components})\)] The dictionary with normalized components \((D)\).
- **code**: [ndarray of shape \((n\text{\_components}, n\text{\_samples})\)] The sparse code such that each column of this matrix has exactly \( n\text{\_nonzero\_coefs} \) non-zero items \((X)\).

Examples using sklearn.datasets.make_sparse_coded_signal

- Orthogonal Matching Pursuit

sklearn.datasets.make_sparse_spd_matrix

Generate a sparse symmetric definite positive matrix.

Read more in the User Guide.

Parameters

- **dim**: [int, default=1] The size of the random matrix to generate.
- **alpha**: [float, default=0.95] The probability that a coefficient is zero (see notes). Larger values enforce more sparsity. The value should be in the range \(0, 1\).
- **norm_diag**: [bool, default=False] Whether to normalize the output matrix to make the leading diagonal elements all \(1\).
- **smallest_coef**: [float, default=0.1] The value of the smallest coefficient between 0 and 1.
- **largest_coef**: [float, default=0.9] The value of the largest coefficient between 0 and 1.
**random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See *Glossary*.

**Returns**

- **prec** [sparse matrix of shape (dim, dim)] The generated matrix.

**See also:**

- `make_spd_matrix`

**Notes**

The sparsity is actually imposed on the cholesky factor of the matrix. Thus alpha does not translate directly into the filling fraction of the matrix itself.

**Examples using** `sklearn.datasets.make_sparse_spd_matrix`

- *Sparse inverse covariance estimation*

**sklearn.datasets.make_sparse_uncorrelated**

`sklearn.datasets.make_sparse_uncorrelated(n_samples=100, n_features=10, *, random_state=None)`

Generate a random regression problem with sparse uncorrelated design.

This dataset is described in Celeux et al [1]. as:

\[
X \sim N(0, 1) \\
y(X) = X[:, 0] + 2 \times X[:, 1] - 2 \times X[:, 2] - 1.5 \times X[:, 3]
\]

Only the first 4 features are informative. The remaining features are useless.

Read more in the *User Guide*.

**Parameters**

- **n_samples** [int, default=100] The number of samples.
- **n_features** [int, default=10] The number of features.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See *Glossary*.

**Returns**

- **X** [ndarray of shape (n_samples, n_features)] The input samples.
- **y** [ndarray of shape (n_samples,)] The output values.
References

[1]

sklearn.datasets.make spd_matrix

sklearn.datasets.make_spd_matrix(n_dim, *, random_state=None)
Generate a random symmetric, positive-definite matrix.
Read more in the User Guide.

Parameters

n_dim [int] The matrix dimension.
random_state [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

X [ndarray of shape (n_dim, n_dim)] The random symmetric, positive-definite matrix.

See also:

make_sparse_spd_matrix

sklearn.datasets.make swiss roll

sklearn.datasets.make_swiss_roll(n_samples=100, *, noise=0.0, random_state=None)
Generate a swiss roll dataset.
Read more in the User Guide.

Parameters

n_samples [int, default=100] The number of sample points on the S curve.
noise [float, default=0.0] The standard deviation of the gaussian noise.
random_state [int, RandomState instance or None, default=None] Determines random number generation for dataset creation. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

X [ndarray of shape (n_samples, 3)] The points.
t [ndarray of shape (n_samples,)] The univariate position of the sample according to the main dimension of the points in the manifold.
### Notes

The algorithm is from Marsland [1].

### References

[1]

### Examples using `sklearn.datasets.make_swiss_roll`

- Hierarchical clustering: structured vs unstructured ward
- Swiss Roll reduction with LLE

### 7.8 sklearn.decomposition: Matrix Decomposition

The `sklearn.decomposition` module includes matrix decomposition algorithms, including among others PCA, NMF or ICA. Most of the algorithms of this module can be regarded as dimensionality reduction techniques.

**User guide:** See the *Decomposing signals in components (matrix factorization problems)* section for further details.

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Dictionary learning

Finds a dictionary (a set of atoms) that can best be used to represent data using a sparse code.

Solves the optimization problem:

\[(U^{*}, V^{*}) = \underset{(U,V)}{\text{argmin}} \ 0.5 \ \| X - U V \|_2^2 + \alpha \ \| U \|_1 \]

with \( \| V_k \|_2 = 1 \) for all \( 0 \leq k < n_{\text{components}} \)

Read more in the User Guide.

Parameters

- **n_components** [int, default=n_features] Number of dictionary elements to extract.
- **alpha** [float, default=1.0] Sparsity controlling parameter.
- **max_iter** [int, default=1000] Maximum number of iterations to perform.
- **tol** [float, default=1e-8] Tolerance for numerical error.
- **fit_algorithm** [[‘lars’, ‘cd’], default=‘lars’] New in version 0.17: cd coordinate descent method to improve speed.
  - **lasso_lars**: uses the least angle regression method to solve the lasso problem (linear_model.lars_path);
  - **lasso_cd**: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). Lasso will be faster if the estimated components are sparse.
- **transform_algorithm** [[‘lasso_lars’, ‘lasso_cd’, ‘lars’, ‘omp’, ‘threshold’], default=‘omp’] Algorithm used to transform the data:
  - **lasso_lars**: uses the least angle regression method (linear_model.lars_path);
  - **lasso_cd**: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). 'lasso_lars' will be faster if the estimated components are sparse.
  - **omp**: uses orthogonal matching pursuit to estimate the sparse solution.
  - **threshold**: squashes to zero all coefficients less than alpha from the projection dictionary \( \star X' \).

New in version 0.17: lasso_cd coordinate descent method to improve speed.
transform_n_nonzero_coefs [int, default=None] Number of nonzero coefficients to target in each column of the solution. This is only used by algorithm='lars' and algorithm='omp' and is overridden by alpha in the omp case. If None, then transform_n_nonzero_coefs=int(n_features / 10).

transform_alpha [float, default=None] If algorithm='lasso_lars' or algorithm='lasso_cd', alpha is the penalty applied to the L1 norm. If algorithm='threshold', alpha is the absolute value of the threshold below which coefficients will be squashed to zero. If algorithm='omp', alpha is the tolerance parameter: the value of the reconstruction error targeted. In this case, it overrides n_nonzero_coefs. If None, default to 1.0

n_jobs [int or None, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

code_init [ndarray of shape (n_samples, n_components), default=None] Initial value for the code, for warm restart.

dict_init [ndarray of shape (n_components, n_features), default=None] Initial values for the dictionary, for warm restart.

verbose [bool, default=False] To control the verbosity of the procedure.

split_sign [bool, default=False] Whether to split the sparse feature vector into the concatenation of its negative part and its positive part. This can improve the performance of downstream classifiers.

random_state [int, RandomState instance or None, default=None] Used for initializing the dictionary when dict_init is not specified, randomly shuffling the data when shuffle is set to True, and updating the dictionary. Pass an int for reproducible results across multiple function calls. See Glossary.

positive_code [bool, default=False] Whether to enforce positivity when finding the code.

New in version 0.20.

positive_dict [bool, default=False] Whether to enforce positivity when finding the dictionary

New in version 0.20.

transform_max_iter [int, default=1000] Maximum number of iterations to perform if algorithm='lasso_cd' or 'lasso_lars'.

New in version 0.22.

Attributes

components_ [ndarray of shape (n_components, n_features)] dictionary atoms extracted from the data

error_ [array] vector of errors at each iteration

n_iter_ [int] Number of iterations run.

See also:

SparseCoder
MiniBatchDictionaryLearning
SparsePCA
MiniBatchSparsePCA
Notes

References:

Examples

```python
>>> import numpy as np
>>> from sklearn.datasets import make_sparse_coded_signal
>>> from sklearn.decomposition import DictionaryLearning

>>> X, dictionary, code = make_sparse_coded_signal(...    n_samples=100, n_components=15, n_features=20, n_nonzero_coefs=10, ...
    random_state=42,
...

>>> dict_learner = DictionaryLearning(...    n_components=15, transform_algorithm='lasso_lars', random_state=42,
...

>>> X_transformed = dict_learner.fit_transform(X)

We can check the level of sparsity of X_transformed:

```python
>>> np.mean(X_transformed == 0)
0.88...
```

We can compare the average squared euclidean norm of the reconstruction error of the sparse coded signal relative to the squared euclidean norm of the original signal:

```python
>>> X_hat = X_transformed @ dict_learner.components_
>>> np.mean(np.sum((X_hat - X) ** 2, axis=1) / np.sum(X ** 2, axis=1))
0.07...
```

Methods

- `fit(X[, y])` Fit the model from data in X.
- `fit_transform(X[, y])` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Encode the data as a sparse combination of the dictionary atoms.

```python
fit (X, y=None) Fit the model from data in X.

Parameters
- X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- y [Ignored]

Returns
- self [object] Returns the object itself.
```
**fit_transform** (*X*, *y=None, **fit_params*)

Fit to data, then transform it.

Fits transformer to *X* and *y* with optional parameters *fit_params* and returns a transformed version of *X*.

**Parameters**

- **X** `[array-like of shape (n_samples, n_features)]` Input samples.
- **y** `[array-like of shape (n_samples,) or (n_samples, n_outputs), default=None]` Target values (None for unsupervised transformations).

**fit_params** `[dict]` Additional fit parameters.

**Returns**

- **X_new** `[ndarray array of shape (n_samples, n_features_new)]` Transformed array.

**get_params** (*deep=True*)

Get parameters for this estimator.

**Parameters**

- **deep** `[bool, default=True]` If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** `[dict]` Parameter names mapped to their values.

**set_params** (**params**)  

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** `[dict]` Estimator parameters.

**Returns**

- **self** `[estimator instance]` Estimator instance.

**transform** (*X*)

Encode the data as a sparse combination of the dictionary atoms.

Coding method is determined by the object parameter *transform_algorithm*.

**Parameters**

- **X** `[ndarray of shape (n_samples, n_features)]` Test data to be transformed, must have the same number of features as the data used to train the model.

**Returns**

- **X_new** `[ndarray of shape (n_samples, n_components)]` Transformed data.
7.8.2 sklearn.decomposition.FactorAnalysis

class sklearn.decomposition.FactorAnalysis(n_components=None, *, tol=0.01, copy=True, max_iter=1000, noise_variance_init=None, svd_method='randomized', iterated_power=3, rotation=None, random_state=0)

Factor Analysis (FA).

A simple linear generative model with Gaussian latent variables.

The observations are assumed to be caused by a linear transformation of lower dimensional latent factors and added Gaussian noise. Without loss of generality the factors are distributed according to a Gaussian with zero mean and unit covariance. The noise is also zero mean and has an arbitrary diagonal covariance matrix.

If we would restrict the model further, by assuming that the Gaussian noise is even isotropic (all diagonal entries are the same) we would obtain PPCA.

FactorAnalysis performs a maximum likelihood estimate of the so-called **loading** matrix, the transformation of the latent variables to the observed ones, using SVD based approach.

Read more in the *User Guide*.

New in version 0.13.

**Parameters**

- `n_components` [int, default=None] Dimensionality of latent space, the number of components of X that are obtained after transform. If None, n_components is set to the number of features.
- `tol` [float, default=1e-2] Stopping tolerance for log-likelihood increase.
- `copy` [bool, default=True] Whether to make a copy of X. If False, the input X gets overwritten during fitting.
- `max_iter` [int, default=1000] Maximum number of iterations.
- `noise_variance_init` [ndarray of shape (n_features,), default=None] The initial guess of the noise variance for each feature. If None, it defaults to np.ones(n_features).
- `svd_method` [{‘lapack’, ‘randomized’}, default=’randomized’] Which SVD method to use. If ‘lapack’ use standard SVD from scipy.linalg, if ‘randomized’ use fast randomized_svd function. Defaults to ‘randomized’. For most applications ‘randomized’ will be sufficiently precise while providing significant speed gains. Accuracy can also be improved by setting higher values for **iterated_power**. If this is not sufficient, for maximum precision you should choose ‘lapack’.
- `iterated_power` [int, default=3] Number of iterations for the power method. 3 by default. Only used if `svd_method` equals ‘randomized’.
- `rotation` [{‘varimax’, ‘quartimax’}, default=None] If not None, apply the indicated rotation. Currently, varimax and quartimax are implemented. See “The varimax criterion for analytic rotation in factor analysis” H. F. Kaiser, 1958.

New in version 0.24.

- `random_state` [int or RandomState instance, default=0] Only used when `svd_method` equals ‘randomized’. Pass an int for reproducible results across multiple function calls. See *Glossary*.

**Attributes**

- `components_` [ndarray of shape (n_components, n_features)] Components with maximum variance.
loglike_  [list of shape (n_iterations,)] The log likelihood at each iteration.
noise_variance_  [ndarray of shape (n_features,)] The estimated noise variance for each feature.
n_iter_  [int] Number of iterations run.
mean_  [ndarray of shape (n_features,)] Per-feature empirical mean, estimated from the training set.

See also:

**PCA** Principal component analysis is also a latent linear variable model which however assumes equal noise variance for each feature. This extra assumption makes probabilistic PCA faster as it can be computed in closed form.

**FastICA** Independent component analysis, a latent variable model with non-Gaussian latent variables.

References

- David Barber, Bayesian Reasoning and Machine Learning, Algorithm 21.1.
- Christopher M. Bishop: Pattern Recognition and Machine Learning, Chapter 12.2.4.

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.decomposition import FactorAnalysis

>>> X, _ = load_digits(return_X_y=True)

>>> transformer = FactorAnalysis(n_components=7, random_state=0)

>>> X_transformed = transformer.fit_transform(X)

>>> X_transformed.shape
(1797, 7)
```

Methods

- **fit**(*X[, y]*) Fit the FactorAnalysis model to X using SVD based approach
- **fit_transform**(*X[, y]*) Fit to data, then transform it.
- **get_covariance**() Compute data covariance with the FactorAnalysis model.
- **get_params**(deep) Get parameters for this estimator.
- **get_precision**() Compute data precision matrix with the FactorAnalysis model.
- **score**(*X[, y]*) Compute the average log-likelihood of the samples
- **score_samples**(*X*) Compute the log-likelihood of each sample
- **set_params**(**params) Set the parameters of this estimator.
- **transform**(*X*) Apply dimensionality reduction to X using the model.

**fit**(*X, y=None*)
Fit the FactorAnalysis model to X using SVD based approach

Parameters
X [array-like of shape (n_samples, n_features)] Training data.
y [Ignored]

Returns
self

**fit_transform** *(X, y=None, **fit_params)*
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

X [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_covariance**()
Compute data covariance with the FactorAnalysis model.

cov = components_.T * components_ + diag(noise_variance)

Returns

cov [ndarray of shape (n_features, n_features)] Estimated covariance of data.

**get_params** *(deep=True)*
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**get_precision**()
Compute data precision matrix with the FactorAnalysis model.

Returns

precision [ndarray of shape (n_features, n_features)] Estimated precision of data.

**score** *(X, y=None)*
Compute the average log-likelihood of the samples

Parameters

X [ndarray of shape (n_features, n_samples)] The data
y [Ignored]

Returns

ll [float] Average log-likelihood of the samples under the current model
**score_samples**(X)
Compute the log-likelihood of each sample

**Parameters**

X [ndarray of shape (n_samples, n_features)] The data

**Returns**

ll [ndarray of shape (n_samples,)] Log-likelihood of each sample under the current model

**set_params**(**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(X)
Apply dimensionality reduction to X using the model.

Compute the expected mean of the latent variables. See Barber, 21.2.33 (or Bishop, 12.66).

**Parameters**

X [array-like of shape (n_samples, n_features)] Training data.

**Returns**

X_new [ndarray of shape (n_samples, n_components)] The latent variables of X.

**Examples using sklearn.decomposition.FactorAnalysis**

- Factor Analysis (with rotation) to visualize patterns
- Model selection with Probabilistic PCA and Factor Analysis (FA)
- Faces dataset decompositions

**7.8.3 sklearn.decomposition.FastICA**

class sklearn.decomposition.FastICA(n_components=None, *, algorithm='parallel', whiten=True, fun='logcosh', fun_args=None, max_iter=200, tol=0.0001, w_init=None, random_state=None)

FastICA: a fast algorithm for Independent Component Analysis.

Read more in the User Guide.

**Parameters**

- **n_components** [int, default=None] Number of components to use. If None is passed, all are used.
- **algorithm** [{'parallel', 'deflation'}, default='parallel'] Apply parallel or deflational algorithm for FastICA.
whiten [bool, default=True] If whiten is false, the data is already considered to be whitened, and no whitening is performed.

fun [(‘logcosh’, ‘exp’, ‘cube’) or callable, default=’logcosh’] The functional form of the G function used in the approximation to neg-entropy. Could be either ‘logcosh’, ‘exp’, or ‘cube’. You can also provide your own function. It should return a tuple containing the value of the function, and of its derivative, in the point. Example:

```python
def my_g(x):
    return x ** 3, (3 * x ** 2).mean(axis=-1)
```

fun_args [dict, default=None] Arguments to send to the functional form. If empty and if fun=’logcosh’, fun_args will take value {'alpha': 1.0}.

max_iter [int, default=200] Maximum number of iterations during fit.

tol [float, default=1e-4] Tolerance on update at each iteration.

w_init [ndarray of shape (n_components, n_components), default=None] The mixing matrix to be used to initialize the algorithm.

random_state [int, RandomState instance or None, default=None] Used to initialize w_init when not specified, with a normal distribution. Pass an int, for reproducible results across multiple function calls. See Glossary.

Attributes

components_ [ndarray of shape (n_components, n_features)] The linear operator to apply to the data to get the independent sources. This is equal to the unmixing matrix when whiten is False, and equal to np.dot(unmixing_matrix, self.whitening_) when whiten is True.

mixing_ [ndarray of shape (n_features, n_components)] The pseudo-inverse of components_. It is the linear operator that maps independent sources to the data.

mean_ [ndarray of shape(n_features,)] The mean over features. Only set if self.whiten is True.

n_iter_ [int] If the algorithm is “deflation”, n_iter is the maximum number of iterations run across all components. Else they are just the number of iterations taken to converge.

whitening_ [ndarray of shape (n_components, n_features)] Only set if whiten is ‘True’. This is the pre-whitening matrix that projects data onto the first n_components principal components.

Notes

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.decomposition import FastICA

>>> X, _ = load_digits(return_X_y=True)
>>> transformer = FastICA(n_components=7, random_state=0)
>>> X_transformed = transformer.fit_transform(X)
>>> X_transformed.shape
(1797, 7)
```

Methods

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<td>transform(X[, copy])</td>
<td>Recover the sources from X (apply the unmixing matrix).</td>
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**fit** (X, y=None)

Fit the model to X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [Ignored]

**Returns**

- **self**

**fit_transform** (X, y=None)

Fit the model and recover the sources from X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [Ignored]

**Returns**

- **X_new** [ndarray of shape (n_samples, n_components)]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

---

7.8. **sklearn.decomposition**: Matrix Decomposition
params [dict] Parameter names mapped to their values.

inverse_transform(X, copy=True)
Transform the sources back to the mixed data (apply mixing matrix).

Parameters
X [array-like of shape (n_samples, n_components)] Sources, where n_samples is the number of samples and n_components is the number of components.
copy [bool, default=True] If False, data passed to fit are overwritten. Defaults to True.

Returns
X_new [ndarray of shape (n_samples, n_features)]

set_params(**params)
Set the parameters of this estimator.

Parameters
**params [dict] Estimator parameters.

Returns
self [estimator instance] Estimator instance.

transform(X, copy=True)
Recover the sources from X (apply the unmixing matrix).

Parameters
X [array-like of shape (n_samples, n_features)] Data to transform, where n_samples is the number of samples and n_features is the number of features.
copy [bool, default=True] If False, data passed to fit can be overwritten. Defaults to True.

Returns
X_new [ndarray of shape (n_samples, n_components)]

Examples using sklearn.decomposition.FastICA

- Blind source separation using FastICA
- FastICA on 2D point clouds
- Faces dataset decompositions
## sklearn.decomposition.IncrementalPCA

**class** sklearn.decomposition.IncrementalPCA(n_components=None, *, whiten=False, copy=True, batch_size=None)

Incremental principal components analysis (IPCA).

Linear dimensionality reduction using Singular Value Decomposition of the data, keeping only the most significant singular vectors to project the data to a lower dimensional space. The input data is centered but not scaled for each feature before applying the SVD.

Depending on the size of the input data, this algorithm can be much more memory efficient than a PCA, and allows sparse input.

This algorithm has constant memory complexity, on the order of $\text{batch_size} \times n_{\text{features}}$, enabling use of np.memmap files without loading the entire file into memory. For sparse matrices, the input is converted to dense in batches (in order to be able to subtract the mean) which avoids storing the entire dense matrix at any one time.

The computational overhead of each SVD is $O(\text{batch_size} \times n_{\text{features}} \times 2)$, but only $2 \times \text{batch_size}$ samples remain in memory at a time. There will be $\frac{n_{\text{samples}}}{\text{batch_size}}$ SVD computations to get the principal components, versus 1 large SVD of complexity $O(n_{\text{samples}} \times n_{\text{features}} \times 2)$ for PCA.

Read more in the User Guide.

New in version 0.16.

**Parameters**

- **n_components** [int, default=None] Number of components to keep. If $n_{\text{components}}$ is None, then $n_{\text{components}}$ is set to $\text{min}(n_{\text{samples}}, n_{\text{features}})$.

- **whiten** [bool, default=False] When True (False by default) the components_ vectors are divided by $n_{\text{samples}} \times \text{components}_{}$ to ensure uncorrelated outputs with unit component-wise variances.

  Whitening will remove some information from the transformed signal (the relative variance scales of the components) but can sometimes improve the predictive accuracy of the downstream estimators by making data respect some hard-wired assumptions.

- **copy** [bool, default=True] If False, X will be overwritten. copy=False can be used to save memory but is unsafe for general use.

- **batch_size** [int, default=None] The number of samples to use for each batch. Only used when calling fit. If batch_size is None, then batch_size is inferred from the data and set to $5 \times n_{\text{features}}$, to provide a balance between approximation accuracy and memory consumption.

**Attributes**

- **components_** [ndarray of shape (n_components, n_features)] Components with maximum variance.

- **explained_variance_** [ndarray of shape (n_components,)] Variance explained by each of the selected components.

- **explained_variance_ratio_** [ndarray of shape (n_components,)] Percentage of variance explained by each of the selected components. If all components are stored, the sum of explained variances is equal to 1.0.

- **singular_values_** [ndarray of shape (n_components,)] The singular values corresponding to each of the selected components. The singular values are equal to the 2-norms of the $n_{\text{components}}$ variables in the lower-dimensional space.
mean_ [ndarray of shape (n_features,)] Per-feature empirical mean, aggregate over calls to partial_fit.

var_ [ndarray of shape (n_features,)] Per-feature empirical variance, aggregate over calls to partial_fit.


n_components_ [int] The estimated number of components. Relevant when n_components=None.

n_samples_seen_ [int] The number of samples processed by the estimator. Will be reset on new calls to fit, but increments across partial_fit calls.

batch_size_ [int] Inferred batch size from batch_size.

See also:

PCA
KernelPCA
SparsePCA
TruncatedSVD

Notes


We have specifically abstained from an optimization used by authors of both papers, a QR decomposition used in specific situations to reduce the algorithmic complexity of the SVD. The source for this technique is Matrix Computations, Third Edition, G. Holub and C. Van Loan, Chapter 5, section 5.4.4, pp 252-253.. This technique has been omitted because it is advantageous only when decomposing a matrix with n_samples (rows) >= 5/3 * n_features (columns), and hurts the readability of the implemented algorithm. This would be a good opportunity for future optimization, if it is deemed necessary.

References


## Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.decomposition import IncrementalPCA
>>> from scipy import sparse

>>> X, _ = load_digits(return_X_y=True)
>>> transformer = IncrementalPCA(n_components=7, batch_size=200)
>>> # either partially fit on smaller batches of data
>>> transformer.partial_fit(X[:100, :])
IncrementalPCA(batch_size=200, n_components=7)
>>> # or let the fit function itself divide the data into batches
>>> X_sparse = sparse.csr_matrix(X)
>>> X_transformed = transformer.fit_transform(X_sparse)
>>> X_transformed.shape
(1797, 7)
```

## Methods

**fit**(X[, y])

Fit the model with X, using minibatches of size batch_size.

**fit_transform**(X[, y]**, fit_params**)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**get_covariance**()

Compute data covariance with the generative model.

**get_params**(deep)

Get parameters for this estimator.

**get_precision**()

Compute data precision matrix with the generative model.

**inverse_transform**(X)

Transform data back to its original space.

**partial_fit**(X[, y, check_input])

Incremental fit with X.

**set_params**(**params)

Set the parameters of this estimator.

**transform**(X)

Apply dimensionality reduction to X.

**fit**(X, y=None)

Fit the model with X, using minibatches of size batch_size.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [Ignored]

**Returns**

- **self** [object] Returns the instance itself.

**fit_transform**(X, y=None, **fit_params**)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
**fit_params**  [dict] Additional fit parameters.

Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_covariance()
Compute data covariance with the generative model.

cov = components_.T * S**2 * components_ + sigma2 * eye(n_features)
where S**2 contains the explained variances, and sigma2 contains the noise variances.

Returns

cov  [array, shape=(n_features, n_features)] Estimated covariance of data.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

get_precision()
Compute data precision matrix with the generative model.

Equals the inverse of the covariance but computed with the matrix inversion lemma for efficiency.

Returns

precision  [array, shape=(n_features, n_features)] Estimated precision of data.

inverse_transform(X)
Transform data back to its original space.

In other words, return an input X_original whose transform would be X.

Parameters

X  [array-like, shape (n_samples, n_components)] New data, where n_samples is the number of samples and n_components is the number of components.

Returns

X_original array-like, shape (n_samples, n_features)

Notes

If whitening is enabled, inverse_transform will compute the exact inverse operation, which includes reversing whitening.

partial_fit(X, y=None, check_input=True)
Incremental fit with X. All of X is processed as a single batch.

Parameters

X  [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

check_input  [bool, default=True] Run check_array on X.
y [Ignored]

Returns

self [object] Returns the instance itself.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Apply dimensionality reduction to X.

X is projected on the first principal components previously extracted from a training set, using minibatches of size batch_size if X is sparse.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) New data, where n_samples is the number of samples and n_features is the number of features.

Returns

X_new [ndarray of shape (n_samples, n_components)]

Examples

```python
>>> import numpy as np
>>> from sklearn.decomposition import IncrementalPCA
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], ...
               [1, 1], [2, 1], [3, 2]])
>>> ipca = IncrementalPCA(n_components=2, batch_size=3)
>>> ipca.fit(X)
incrementalPCA(batch_size=3, n_components=2)
>>> ipca.transform(X)
```

Examples using sklearn.decomposition.IncrementalPCA

- Incremental PCA
7.8.5 sklearn.decomposition.KernelPCA

class sklearn.decomposition.KernelPCA (n_components=None, *, kernel='linear',
    gamma=None, degree=3, coef0=1,
    kernel_params=None, alpha=1.0,
    fit_inverse_transform=False, eigen_solver='auto',
    tol=0, max_iter=None, remove_zero_eig=False,
    random_state=None, copy_X=True, n_jobs=None)

Kernel Principal component analysis (KPCA).
Non-linear dimensionality reduction through the use of kernels (see Pairwise metrics, Affinities and Kernels).
Read more in the User Guide.

Parameters

n_components [int, default=None] Number of components. If None, all non-zero components are kept.

kernel [['linear', 'poly', 'rbf', 'sigmoid', 'cosine', 'precomputed'], default='linear'] Kernel used for PCA.

gamma [float, default=None] Kernel coefficient for rbf, poly and sigmoid kernels. Ignored by other kernels. If gamma is None, then it is set to 1/n_features.

degree [int, default=3] Degree for poly kernels. Ignored by other kernels.

coe0 [float, default=1] Independent term in poly and sigmoid kernels. Ignored by other kernels.

kernel_params [dict, default=None] Parameters (keyword arguments) and values for kernel passed as callable object. Ignored by other kernels.

alpha [float, default=1.0] Hyperparameter of the ridge regression that learns the inverse transform (when fit_inverse_transform=True).

fit_inverse_transform [bool, default=False] Learn the inverse transform for non-precomputed kernels. (i.e. learn to find the pre-image of a point)

eigen_solver [['auto', 'dense', 'arpack'], default='auto'] Select eigensolver to use. If n_components is much less than the number of training samples, arpack may be more efficient than the dense eigensolver.

tol [float, default=0] Convergence tolerance for arpack. If 0, optimal value will be chosen by arpack.

max_iter [int, default=None] Maximum number of iterations for arpack. If None, optimal value will be chosen by arpack.

remove_zero_eig [bool, default=False] If True, then all components with zero eigenvalues are removed, so that the number of components in the output may be < n_components (and sometimes even zero due to numerical instability). When n_components is None, this parameter is ignored and components with zero eigenvalues are removed regardless.

random_state [int, RandomState instance or None, default=None] Used when eigen_solver == ‘arpack’. Pass an int for reproducible results across multiple function calls. See Glossary.

New in version 0.18.

copy_X [bool, default=True] If True, input X is copied and stored by the model in the X_fit_ attribute. If no further changes will be done to X, setting copy_X=False saves memory by storing a reference.

New in version 0.18.
**n_jobs** [int, default=None] The number of parallel jobs to run. *None* means 1 unless in a *joblib.parallel_backend* context. *-1* means using all processors. See *Glossary* for more details.

New in version 0.18.

**Attributes**

**lambdas_** [ndarray of shape (n_components,)] Eigenvalues of the centered kernel matrix in decreasing order. If *n_components* and *remove_zero_eig* are not set, then all values are stored.

**alphas_** [ndarray of shape (n_samples, n_components)] Eigenvectors of the centered kernel matrix. If *n_components* and *remove_zero_eig* are not set, then all components are stored.

**dual_coef_** [ndarray of shape (n_samples, n_features)] Inverse transform matrix. Only available when *fit_inverse_transform* is True.

**X_transformed_fit_** [ndarray of shape (n_samples, n_components)] Projection of the fitted data on the kernel principal components. Only available when *fit_inverse_transform* is True.

**X_fit_** [ndarray of shape (n_samples, n_features)] The data used to fit the model. If *copy_X=False*, then *X_fit_* is a reference. This attribute is used for the calls to transform.

**References**


**Examples**

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.decomposition import KernelPCA
>>> X, _ = load_digits(return_X_y=True)
>>> transformer = KernelPCA(n_components=7, kernel='linear')
>>> X_transformed = transformer.fit_transform(X)
>>> X_transformed.shape
(1797, 7)
```

**Methods**

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<td>fit(X, y)</td>
<td>Fit the model from data in X.</td>
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<td>fit_transform(X, y)</td>
<td>Fit the model from data in X and transform X.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<tr>
<td>inverse_transform(X)</td>
<td>Transform X back to original space.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Transform X.</td>
</tr>
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</table>

**fit** (*X, y=None*)

Fit the model from data in *X*. 

---

7.8. **sklearn.decomposition**: Matrix Decomposition 1865
Parameters

\(X\) \([\text{array-like, sparse matrix} \text{ of shape } (n\text{\_samples, \text{n\_features})}]\) Training vector, where 
\(n\text{\_samples}\) in the number of samples and \(\text{n\_features}\) is the number of features.

Returns

self \([\text{object}]\) Returns the instance itself.

\textbf{fit\_transform}(X, y=None, **params)

Fit the model from data in \(X\) and transform \(X\).

Parameters

\(X\) \([\text{array-like, sparse matrix} \text{ of shape } (n\text{\_samples, \text{n\_features})}]\) Training vector, where 
\(n\text{\_samples}\) in the number of samples and \(\text{n\_features}\) is the number of features.

Returns

\(X\_\text{new}\) \([\text{ndarray of shape } (n\text{\_samples, n\_components})]\)

\textbf{get\_params}(deep=True)

Get parameters for this estimator.

Parameters

\text{deep} \([\text{bool, default=True}]\) If True, will return the parameters for this estimator and contained

subobjects that are estimators.

Returns

\text{params} \([\text{dict}]\) Parameter names mapped to their values.

\textbf{inverse\_transform}(X)

Transform \(X\) back to original space.

Parameters

\(X\) \([\text{array-like, sparse matrix} \text{ of shape } (n\text{\_samples, n\_components})]\)

Returns

\(X\_\text{new}\) \([\text{ndarray of shape } (n\text{\_samples, \text{n\_features})}]\)

\textbf{References}


\textbf{set\_params}(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \textit{Pipeline}). The latter have

parameters of the form \(<\text{component}>\_\_\text{<parameter}>\) so that it’s possible to update each component

of a nested object.

Parameters

**params \([\text{dict}]\) Estimator parameters.

Returns

self \([\text{estimator instance}]\) Estimator instance.

\textbf{transform}(X)

Transform \(X\).
Parameters

\( X \) \([\text{array-like, sparse matrix}] \) of shape (n_samples, n_features)

Returns

\( X_{\text{new}} \) \( \text{ndarray of shape (n_samples, n_components)} \)

Examples using `sklearn.decomposition.KernelPCA`

- Kernel PCA

7.8.6 `sklearn.decomposition.LatentDirichletAllocation`

class `sklearn.decomposition.LatentDirichletAllocation`

Latent Dirichlet Allocation with online variational Bayes algorithm

New in version 0.17.

Read more in the `User Guide`.

Parameters

- **n_components** \([\text{int, default=10}] \) Number of topics.
  
  Changed in version 0.19: n_topics was renamed to n_components

- **doc_topic_prior** \([\text{float, default=None}] \) Prior of document topic distribution \(\theta\). If the value is None, defaults to \(1 / n_{\text{components}}\). In [1], this is called \(alpha\).

- **topic_word_prior** \([\text{float, default=None}] \) Prior of topic word distribution \(\beta\). If the value is None, defaults to \(1 / n_{\text{components}}\). In [1], this is called \(eta\).

- **learning_method** \([\{'batch', 'online'\}] \), default='batch' Method used to update _component.

  Only used in `fit` method. In general, if the data size is large, the online update will be much faster than the batch update.

  Valid options:

  'batch': Batch variational Bayes method. Use all training data in each EM update.
  
  'online': Online variational Bayes method. In each EM update, use mini-batch of training data to update the _component.

(continues on next page)
variable incrementally. The learning rate is controlled by the ``learning_decay`` and the `learning_offset` parameters.

Changed in version 0.20: The default learning method is now "batch".

**learning_decay** [float, default=0.7] It is a parameter that control learning rate in the online learning method. The value should be set between (0.5, 1.0] to guarantee asymptotic convergence. When the value is 0.0 and batch_size is n_samples, the update method is same as batch learning. In the literature, this is called kappa.

**learning_offset** [float, default=10.] A (positive) parameter that downweights early iterations in online learning. It should be greater than 1.0. In the literature, this is called tau_0.

**max_iter** [int, default=10] The maximum number of iterations.

**batch_size** [int, default=128] Number of documents to use in each EM iteration. Only used in online learning.

**evaluate_every** [int, default=0] How often to evaluate perplexity. Only used in `fit` method. Set it to 0 or negative number to not evaluate perplexity in training at all. Evaluating perplexity can help you check convergence in training process, but it will also increase total training time. Evaluating perplexity in every iteration might increase training time up to two-fold.

**total_samples** [int, default=1e6] Total number of documents. Only used in the `partial_fit` method.

**perp_tol** [float, default=1e-1] Perplexity tolerance in batch learning. Only used when `evaluate_every` is greater than 0.

**mean_change_tol** [float, default=1e-3] Stopping tolerance for updating document topic distribution in E-step.

**max_doc_update_iter** [int, default=100] Max number of iterations for updating document topic distribution in the E-step.

**n_jobs** [int, default=None] The number of jobs to use in the E-step. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

**verbose** [int, default=0] Verbosity level.

**random_state** [int, RandomState instance or None, default=None] Pass an int for reproducible results across multiple function calls. See Glossary.

**Attributes**

**components_** [ndarray of shape (n_components, n_features)] Variational parameters for topic word distribution. Since the complete conditional for topic word distribution is a Dirichlet, components_[i, j] can be viewed as pseudocount that represents the number of times word j was assigned to topic i. It can also be viewed as distribution over the words for each topic after normalization: \( \text{model.components_} / \text{model.components_.sum(axis=1)}[:, \text{np.newaxis}] \).

**exp_dirichlet_component_** [ndarray of shape (n_components, n_features)] Exponential value of expectation of log topic word distribution. In the literature, this is \( \exp(E[\log(beta)]) \).

**n_batch_iter_** [int] Number of iterations of the EM step.

**n_iter_** [int] Number of passes over the dataset.

**bound_** [float] Final perplexity score on training set.
**doc_topic_prior** [float] Prior of document topic distribution \( \theta \). If the value is None, it is \( 1 / n\text{\_components} \).

**random_state** [RandomState instance] RandomState instance that is generated either from a seed, the random number generator or by \( \text{np\_random} \).

**topic_word_prior** [float] Prior of topic word distribution \( \beta \). If the value is None, it is \( 1 / n\text{\_components} \).

### References


### Examples

```python
>>> from sklearn.decomposition import LatentDirichletAllocation
>>> from sklearn.datasets import make_multilabel_classification

# This produces a feature matrix of token counts, similar to what
# CountVectorizer would produce on text.
>>> X, _ = make_multilabel_classification(random_state=0)

# This produces a feature matrix of token counts, similar to what
# CountVectorizer would produce on text.
>>> lda = LatentDirichletAllocation(n_components=5,
...                               random_state=0)

# get topics for some given samples:
>>> lda.transform(X[-2:])
array([[0.00360392, 0.25499205, 0.00362110, 0.64236448, 0.09541846],
       [0.15297572, 0.00362644, 0.44412786, 0.39568399, 0.003586 ]])
```

### Methods

<table>
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<th>Method</th>
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<tr>
<td><strong>fit</strong>(X[, y])</td>
<td>Learn model for the data X with variational Bayes method.</td>
</tr>
<tr>
<td><strong>fit_transform</strong>(X[, y])</td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><strong>get_params</strong>([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><strong>partial_fit</strong>(X[, y])</td>
<td>Online VB with Mini-Batch update.</td>
</tr>
<tr>
<td><strong>perplexity</strong>(X[, sub_sampling])</td>
<td>Calculate approximate perplexity for data X.</td>
</tr>
<tr>
<td><strong>score</strong>(X[, y])</td>
<td>Calculate approximate log-likelihood as score.</td>
</tr>
<tr>
<td><strong>set_params</strong>(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><strong>transform</strong>(X)</td>
<td>Transform data X according to the fitted model.</td>
</tr>
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</table>

**fit**(X, y=None)

Learn model for the data X with variational Bayes method.

When **learning_method** is ‘online’, use mini-batch update. Otherwise, use batch update.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] Document word matrix.
y [Ignored]

Returns
self

fit_transform(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters
X [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns
X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params(deep=True)
Get parameters for this estimator.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

partial_fit(X, y=None)
Online VB with Mini-Batch update.

Parameters
X [[array-like, sparse matrix] of shape (n_samples, n_features)] Document word matrix.
y [Ignored]

Returns
self

perplexity(X, sub_sampling=False)
Calculate approximate perplexity for data X.

Perplexity is defined as exp(-1. * log-likelihood per word)

Changed in version 0.19: doc_topic_distr argument has been deprecated and is ignored because user no longer has access to unnormalized distribution

Parameters
X [[array-like, sparse matrix] of shape (n_samples, n_features)] Document word matrix.
sub_sampling [bool] Do sub-sampling or not.

Returns
score [float] Perplexity score.
score(X, y=None)
Calculate approximate log-likelihood as score.

Parameters
- y : [Ignored]

Returns
- score : [float] Use approximate bound as score.

set_params(**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

Parameters
- **params : [dict] Estimator parameters.

Returns
- self : [estimator instance] Estimator instance.

transform(X)
Transform data X according to the fitted model.

Changed in version 0.18: `doc_topic_distr` is now normalized

Parameters

Returns
- `doc_topic_distr` : [ndarray of shape (n_samples, n_components)] Document topic distribution for X.

Examples using sklearn.decomposition.LatentDirichletAllocation

- *Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation*
7.8.7 `sklearn.decomposition.MiniBatchDictionaryLearning`

class `sklearn.decomposition.MiniBatchDictionaryLearning` (n_components=None, *,
alpha=1, n_iter=1000,
fit_algorithm='lars',
n_jobs=None,
batch_size=3,
shuffle=True,
dict_init=None, transform_algorithm='omp',
transform_n_nonzero_coefs=None,
transform_alpha=None,
verbose=False,
split_sign=False, random_state=None,
positive_code=False,
positive_dict=False,
transform_max_iter=1000)

Mini-batch dictionary learning

Finds a dictionary (a set of atoms) that can best be used to represent data using a sparse code.

Solves the optimization problem:

\[(U^*, V^*) = \underset{(U,V)}{\text{argmin}} \ 0.5 \ || X - U V ||_2^2 + \alpha * || U ||_1\]

with \[|| V_k ||_2 = 1 \text{ for all } 0 \leq k < n_{\text{components}}\]

Read more in the `User Guide`.

Parameters

- **n_components** [int, default=None] Number of dictionary elements to extract.
- **alpha** [float, default=1] Sparsity controlling parameter.
- **n_iter** [int, default=1000] Total number of iterations to perform.
- **fit_algorithm** [{‘lars’, ‘cd’}, default=’lars’] The algorithm used:
  - 'lars': uses the least angle regression method to solve the lasso problem
    (linear_model.lars_path)
  - 'cd': uses the coordinate descent method to compute the Lasso solution
    (linear_model.Lasso). Lars will be faster if the estimated components are sparse.
- **n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a
  `joblib.parallel_backend` context. -1 means using all processors. See `Glossary`
  for more details.
- **batch_size** [int, default=3] Number of samples in each mini-batch.
- **shuffle** [bool, default=True] Whether to shuffle the samples before forming batches.
- **dict_init** [ndarray of shape (n_components, n_features), default=None] initial value of the dic-
  tionary for warm restart scenarios
  Algorithm used to transform the data:
  - 'lars': uses the least angle regression method (linear_model.lars_path);
• 'lasso_lars': uses Lars to compute the Lasso solution.
• 'lasso_cd': uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). 'lasso_lars' will be faster if the estimated components are sparse.
• 'omp': uses orthogonal matching pursuit to estimate the sparse solution.
• 'threshold': squashes to zero all coefficients less than alpha from the projection dictionary * X'.

transform_n_nonzero_coefs [int, default=None] Number of nonzero coefficients to target in each column of the solution. This is only used by algorithm='lars' and algorithm='omp' and is overridden by alpha in the omp case. If None, then transform_n_nonzero_coefs=int(n_features / 10).

transform_alpha [float, default=None] If algorithm='lasso_lars' or algorithm='lasso_cd', alpha is the penalty applied to the L1 norm. If algorithm='threshold', alpha is the absolute value of the threshold below which coefficients will be squashed to zero. If algorithm='omp', alpha is the tolerance parameter: the value of the reconstruction error targeted. In this case, it overrides n_nonzero_coefs. If None, default to 1.

verbose [bool, default=False] To control the verbosity of the procedure.

split_sign [bool, default=False] Whether to split the sparse feature vector into the concatenation of its negative part and its positive part. This can improve the performance of downstream classifiers.

random_state [int, RandomState instance or None, default=None] Used for initializing the dictionary when dict_init is not specified, randomly shuffling the data when shuffle is set to True, and updating the dictionary. Pass an int for reproducible results across multiple function calls. See Glossary.

positive_code [bool, default=False] Whether to enforce positivity when finding the code.

New in version 0.20.

positive_dict [bool, default=False] Whether to enforce positivity when finding the dictionary.

New in version 0.20.

transform_max_iter [int, default=1000] Maximum number of iterations to perform if algorithm='lasso_cd' or 'lasso_lars'.

New in version 0.22.

Attributes

components_ [ndarray of shape (n_components, n_features)] Components extracted from the data.

inner_stats_ [tuple of (A, B) ndarrays] Internal sufficient statistics that are kept by the algorithm. Keeping them is useful in online settings, to avoid losing the history of the evolution, but they shouldn’t have any use for the end user. A (n_components, n_components) is the dictionary covariance matrix. B (n_features, n_components) is the data approximation matrix.

n_iter_ [int] Number of iterations run.

iter_offset_ [int] The number of iteration on data batches that has been performed before.

random_state_ [RandomState instance] RandomState instance that is generated either from a seed, the random number generator or by np.random.
See also:

* [SparseCoder](#)
* [DictionaryLearning](#)
* [SparsePCA](#)
* [MiniBatchSparsePCA](#)

Notes

References:


Examples

```python
>>> import numpy as np
>>> from sklearn.datasets import make_sparse_coded_signal
>>> from sklearn.decomposition import MiniBatchDictionaryLearning

>>> X, dictionary, code = make_sparse_coded_signal(...
...     n_samples=100, n_components=15, n_features=20, n_nonzero_coefs=10,
...     random_state=42)

>>> dict_learner = MiniBatchDictionaryLearning(...
...     n_components=15, transform_algorithm='lasso_lars', random_state=42,
... )

>>> X_transformed = dict_learner.fit_transform(X)

We can check the level of sparsity of `X_transformed`:

```python
>>> np.mean(X_transformed == 0)
0.87...
```

We can compare the average squared euclidean norm of the reconstruction error of the sparse coded signal relative to the squared euclidean norm of the original signal:

```python
>>> X_hat = X_transformed @ dict_learner.components_

>>> np.mean(np.sum((X_hat - X) ** 2, axis=1) / np.sum(X ** 2, axis=1))
0.10...
```

Methods

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<td>fit(X, y)</td>
<td>Fit the model from data in X.</td>
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<tr>
<td>fit_transform(X, y)</td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>partial_fit(X, y, iter_offset)</td>
<td>Updates the model using the data in X as a mini-batch.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Encode the data as a sparse combination of the dictionary atoms.</td>
</tr>
</tbody>
</table>
**fit** (*X*, *y=None*)

Fit the model from data in *X*.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

* y [Ignored]

**Returns**

* self [object] Returns the instance itself.

**fit_transform** (*X*, *y=None, **fit_params*)

Fit to data, then transform it.

Fits transformer to *X* and *y* with optional parameters *fit_params* and returns a transformed version of *X*.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Input samples.

* y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

* **fit_params** [dict] Additional fit parameters.

**Returns**

* X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** (*deep=True*)

Get parameters for this estimator.

**Parameters**

* deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

* params [dict] Parameter names mapped to their values.

**partial_fit** (*X*, *y=None, iter_offset=None*)

Updates the model using the data in *X* as a mini-batch.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

* y [Ignored]

* iter_offset [int, default=None] The number of iteration on data batches that has been performed before this call to partial_fit. This is optional: if no number is passed, the memory of the object is used.

**Returns**

* self [object] Returns the instance itself.

**set_params** (**params**)

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform** (X)

Encode the data as a sparse combination of the dictionary atoms. Coding method is determined by the object parameter `transform_algorithm`.

**Parameters**

X [ndarray of shape (n_samples, n_features)] Test data to be transformed, must have the same number of features as the data used to train the model.

**Returns**

X_new [ndarray of shape (n_samples, n_components)] Transformed data.

**Examples using sklearn.decomposition.MiniBatchDictionaryLearning**

- Image denoising using dictionary learning
- Faces dataset decompositions

**7.8.8 sklearn.decomposition.MiniBatchSparsePCA**

```python
class sklearn.decomposition.MiniBatchSparsePCA(n_components=None, *, alpha=1, ridge_alpha=0.01, n_iter=100, callback=None, batch_size=3, verbose=False, shuffle=True, n_jobs=None, method='lars', random_state=None)
```

Mini-batch Sparse Principal Components Analysis

Finds the set of sparse components that can optimally reconstruct the data. The amount of sparseness is controllable by the coefficient of the L1 penalty, given by the parameter alpha.

Read more in the User Guide.

**Parameters**

- **n_components** [int, default=None] number of sparse atoms to extract
- **alpha** [int, default=1] Sparsity controlling parameter. Higher values lead to sparser components.
- **ridge_alpha** [float, default=0.01] Amount of ridge shrinkage to apply in order to improve conditioning when calling the transform method.
- **n_iter** [int, default=100] number of iterations to perform for each mini batch
- **callback** [callable, default=None] callable that gets invoked every five iterations
- **batch_size** [int, default=3] the number of features to take in each mini batch
**verbose** [int or bool, default=False] Controls the verbosity; the higher, the more messages. Defaults to 0.

**shuffle** [bool, default=True] whether to shuffle the data before splitting it in batches

**n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**method** [{‘lars’, ‘cd’}, default=lars] lars: uses the least angle regression method to solve the lasso problem (linear_model.lars_path) cd: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). Lars will be faster if the estimated components are sparse.

**random_state** [int, RandomState instance or None, default=None] Used for random shuffling when shuffle is set to True, during online dictionary learning. Pass an int for reproducible results across multiple function calls. See Glossary.

**Attributes**

* components_ [ndarray of shape (n_components, n_features)] Sparse components extracted from the data.

* n_components_ [int] Estimated number of components. New in version 0.23.

* n_iter_ [int] Number of iterations run.

* mean_ [ndarray of shape (n_features,)] Per-feature empirical mean, estimated from the training set. Equal to X.mean(axis=0).

**See also:**

* PCA
* SparsePCA
* DictionaryLearning

**Examples**

```python
>>> import numpy as np
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.decomposition import MiniBatchSparsePCA
>>> X, _ = make_friedman1(n_samples=200, n_features=30, random_state=0)
>>> transformer = MiniBatchSparsePCA(n_components=5, batch_size=50,
...                                  random_state=0)
>>> transformer.fit(X)
MiniBatchSparsePCA(...)
>>> X_transformed = transformer.transform(X)
>>> X_transformed.shape
(200, 5)
>>> # most values in the components_ are zero (sparsity)
>>> np.mean(transformer.components_ == 0)
0.94
```
Methods

- **fit**(*X*, *y=None*)  
  Fit the model from data in X.
  
- **fit_transform**(*X*, *y=None*)  
  Fit to data, then transform it.
  
- **get_params**(deep=False)  
  Get parameters for this estimator.
  
- **set_params**(**params**)  
  Set the parameters of this estimator.
  
- **transform**(*X*)  
  Least Squares projection of the data onto the sparse components.

**fit**(*X*, *y=None*)
Fit the model from data in X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]  
  Training vector, where n_samples in the number of samples and n_features is the number of features.

- **y** [Ignored]

**Returns**

- **self** [object]  
  Returns the instance itself.

**fit_transform**(*X*, *y=None*, **fit_params**)  
Fit to data, then transform it.

Fits transformer to X and y with optional parameters **fit_params** and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]  
  Input samples.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None]  
  Target values (None for unsupervised transformations).

- **fit_params** [dict]  
  Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)]  
  Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True]  
  If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict]  
  Parameter names mapped to their values.

**set_params**(**params**)  
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict]  
  Estimator parameters.
Returns

self [estimator instance] Estimator instance.

transform (X)
Least Squares projection of the data onto the sparse components.

To avoid instability issues in case the system is under-determined, regularization can be applied (Ridge regression) via the ridge_alpha parameter.

Note that Sparse PCA components orthogonality is not enforced as in PCA hence one cannot use a simple linear projection.

Parameters

X [ndarray of shape (n_samples, n_features)] Test data to be transformed, must have the same number of features as the data used to train the model.

Returns

X_new [ndarray of shape (n_samples, n_components)] Transformed data.

Examples using sklearn.decomposition.MiniBatchSparsePCA

• Faces dataset decompositions

7.8.9 sklearn.decomposition.NMF
class sklearn.decomposition.NMF (n_components=None, *, init='warn', solver='cd', beta_loss='frobenius', tol=0.0001, max_iter=200, random_state=None, alpha=0.0, l1_ratio=0.0, verbose=0, shuffle=False, regularization='both')

Non-Negative Matrix Factorization (NMF).

Find two non-negative matrices (W, H) whose product approximates the non-negative matrix X. This factorization can be used for example for dimensionality reduction, source separation or topic extraction.

The objective function is:

$$0.5 \times ||X - WH||^2_{Fro} + alpha \times \text{l1ratio} \times ||\text{vec}(W)||_1$$
$$+alpha \times \text{l1ratio} \times ||\text{vec}(H)||_1$$
$$+0.5 \times alpha \times (1 - \text{l1ratio}) \times ||W||^2_{Fro}$$
$$+0.5 \times alpha \times (1 - \text{l1ratio}) \times ||H||^2_{Fro}$$

Where:

$$||A||^2_{Fro} = \sum_{i,j} A_{i,j}^2$$ (Frobenius norm)
$$||\text{vec}(A)||_1 = \sum_{i,j} \text{abs}(A_{i,j})$$ (Elementwise L1 norm)

For multiplicative-update (‘mu’) solver, the Frobenius norm (0.5 * ||X - WH||^2_{Fro}) can be changed into another beta-divergence loss, by changing the beta_loss parameter.

The objective function is minimized with an alternating minimization of W and H.

Read more in the User Guide.

Parameters
**n_components** [int, default=None] Number of components, if n_components is not set all features are kept.

**init** [{'random', 'nndsvd', 'nndsvda', 'nndsvdar', 'custom'}, default=None] Method used to initialize the procedure. Default: None. Valid options:
- None: ‘nndsvd’ if n_components <= min(n_samples, n_features), otherwise random.
- ‘random’: non-negative random matrices, scaled with: sqrt(X.mean()) / n_components
- ‘nndsvd’: Nonnegative Double Singular Value Decomposition (NNDSVD) initialization (better for sparseness)
- ‘nndsvda’: NNDSVD with zeros filled with the average of X (better when sparsity is not desired)
- ‘nndsvdar’: NNDSVD with zeros filled with small random values (generally faster, less accurate alternative to NNDSVDa for when sparsity is not desired)
- ‘custom’: use custom matrices W and H

**solver** [{'cd', 'mu'}, default='cd'] Numerical solver to use: ‘cd’ is a Coordinate Descent solver. ‘mu’ is a Multiplicative Update solver.
New in version 0.17: Coordinate Descent solver.
New in version 0.19: Multiplicative Update solver.

**beta_loss** [float or {'frobenius', 'kullback-leibler', 'itakura-saito'}, default='frobenius'] Beta divergence to be minimized, measuring the distance between X and the dot product WH. Note that values different from ‘frobenius’ (or 2) and ‘kullback-leibler’ (or 1) lead to significantly slower fits. Note that for beta_loss <= 0 (or ‘itakura-saito’), the input matrix X cannot contain zeros. Used only in ‘mu’ solver.
New in version 0.19.

**tol** [float, default=1e-4] Tolerance of the stopping condition.

**max_iter** [int, default=200] Maximum number of iterations before timing out.

**random_state** [int, RandomState instance or None, default=None] Used for initialisation (when init == ‘nndsvdar’ or ‘random’), and in Coordinate Descent. Pass an int for reproducible results across multiple function calls. See Glossary.

**alpha** [float, default=0.] Constant that multiplies the regularization terms. Set it to zero to have no regularization.
New in version 0.17: alpha used in the Coordinate Descent solver.

**l1_ratio** [float, default=0.] The regularization mixing parameter, with 0 <= l1_ratio <= 1. For l1_ratio = 0 the penalty is an elementwise L2 penalty (aka Frobenius Norm). For l1_ratio = 1 it is an elementwise L1 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1 and L2.
New in version 0.17: Regularization parameter l1_ratio used in the Coordinate Descent solver.

**verbose** [bool, default=False] Whether to be verbose.

**shuffle** [bool, default=False] If true, randomize the order of coordinates in the CD solver.
New in version 0.17: shuffle parameter used in the Coordinate Descent solver.
**regularization** ['both', 'components', 'transformation', None], default='both'] Select whether the regularization affects the components (H), the transformation (W), both or none of them.

New in version 0.24.

**Attributes**

- **components_** [ndarray of shape (n_components, n_features)] Factorization matrix, sometimes called ‘dictionary’.
- **n_components_** [int] The number of components. It is same as the n_components parameter if it was given. Otherwise, it will be same as the number of features.
- **reconstruction_err_** [float] Frobenius norm of the matrix difference, or beta-divergence, between the training data X and the reconstructed data WH from the fitted model.
- **n_iter_** [int] Actual number of iterations.

**References**


**Examples**

```python
>>> import numpy as np
>>> X = np.array([[1, 1], [2, 1], [3, 1.2], [4, 1], [5, 0.8], [6, 1]])
>>> from sklearn.decomposition import NMF
>>> model = NMF(n_components=2, init='random', random_state=0)
>>> W = model.fit_transform(X)
>>> H = model.components_
```

**Methods**

- **fit(X, y=None)**
  Learn a NMF model for the data X.

- **fit_transform(X, y=W, H)**
  Learn a NMF model for the data X and returns the transformed data.

- **get_params([deep])**
  Get parameters for this estimator.

- **inverse_transform(W)**
  Transform data back to its original space.

- **set_params(**params)**
  Set the parameters of this estimator.

- **transform(X)**
  Transform the data X according to the fitted NMF model.

**fit**(X, y=None, **params)

Learn a NMF model for the data X.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) Data matrix to be decomposed
y [Ignored]

Returns

self

**fit_transform** (*X*, *y=None, W=None, H=None*)
Learn a NMF model for the data *X* and returns the transformed data.

This is more efficient than calling fit followed by transform.

Parameters

*X* [{array-like, sparse matrix} of shape (n_samples, n_features)] Data matrix to be decomposed

*y* [Ignored]

*W* [array-like of shape (n_samples, n_components)] If init=‘custom’, it is used as initial guess for the solution.

*H* [array-like of shape (n_components, n_features)] If init=‘custom’, it is used as initial guess for the solution.

Returns

*W* [ndarray of shape (n_samples, n_components)] Transformed data.

**get_params** (*deep=True*)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**inverse_transform** (*W*)
Transform data back to its original space.

Parameters

*W* [{ndarray, sparse matrix} of shape (n_samples, n_components)] Transformed data matrix.

Returns

*X* [{ndarray, sparse matrix} of shape (n_samples, n_features)] Data matrix of original shape.

New in version 0.18: ..

**set_params** (**params**)  
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
transform$(X)$

Transform the data $X$ according to the fitted NMF model.

Parameters

$X$ [{array-like, sparse matrix} of shape (n_samples, n_features)] Data matrix to be transformed by the model.

Returns

$W$ [ndarray of shape (n_samples, n_components)] Transformed data.

Examples using sklearn.decomposition.NMF

• Beta-divergence loss functions
• Faces dataset decompositions
• Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation
• Selecting dimensionality reduction with Pipeline and GridSearchCV

7.8.10 sklearn.decomposition.PCA

class sklearn.decomposition.PCA(n_components=None, *, copy=True, whiten=False, svd_solver='auto', tol=0.0, iterated_power='auto', random_state=None)

Principal component analysis (PCA).

Linear dimensionality reduction using Singular Value Decomposition of the data to project it to a lower dimensional space. The input data is centered but not scaled for each feature before applying the SVD.

It uses the LAPACK implementation of the full SVD or a randomized truncated SVD by the method of Halko et al. 2009, depending on the shape of the input data and the number of components to extract.

It can also use the scipy.sparse.linalg ARPACK implementation of the truncated SVD.

Notice that this class does not support sparse input. See TruncatedSVD for an alternative with sparse data.

Read more in the User Guide.

Parameters

n_components [int, float or str, default=None] Number of components to keep. If n_components is not set all components are kept:

n_components = min(n_samples, n_features)

If n_components == 'mle' and svd_solver == 'full', Minka’s MLE is used to guess the dimension. Use of n_components == 'mle' will interpret svd_solver == 'auto' as svd_solver == 'full'.

If 0 < n_components < 1 and svd_solver == 'full', select the number of components such that the amount of variance that needs to be explained is greater than the percentage specified by n_components.

If svd_solver == 'arpack', the number of components must be strictly less than the minimum of n_features and n_samples.

Hence, the None case results in:
n_components == min(n_samples, n_features) - 1

copy [bool, default=True] If False, data passed to fit are overwritten and running fit(X).transform(X) will not yield the expected results, use fit_transform(X) instead.

whiten [bool, default=False] When True (False by default) the components_ vectors are multiplied by the square root of n_samples and then divided by the singular values to ensure uncorrelated outputs with unit component-wise variances.

Whitening will remove some information from the transformed signal (the relative variance scales of the components) but can sometime improve the predictive accuracy of the downstream estimators by making their data respect some hard-wired assumptions.

svd_solver [{‘auto’, ‘full’, ‘arpack’, ‘randomized’}, default=’auto’]

If auto: The solver is selected by a default policy based on X.shape and n_components: if the input data is larger than 500x500 and the number of components to extract is lower than 80% of the smallest dimension of the data, then the more efficient ‘randomized’ method is enabled. Otherwise the exact full SVD is computed and optionally truncated afterwards.

If full: run exact full SVD calling the standard LAPACK solver via scipy.linalg.svd and select the components by postprocessing

If arpack: run SVD truncated to n_components calling ARPACK solver via scipy.sparse.linalg.svds. It requires strictly 0 < n_components < min(X.shape)

If randomized: run randomized SVD by the method of Halko et al.

New in version 0.18.0.

tol [float, default=0.0] Tolerance for singular values computed by svd_solver == ‘arpack’. Must be of range [0.0, infinity).

New in version 0.18.0.

iterated_power [int or ‘auto’, default=’auto’] Number of iterations for the power method computed by svd_solver == ‘randomized’. Must be of range [0, infinity).

New in version 0.18.0.

random_state [int, RandomState instance or None, default=None] Used when the ‘arpack’ or ‘randomized’ solvers are used. Pass an int for reproducible results across multiple function calls. See Glossary.

New in version 0.18.0.

Attributes

components_ [ndarray of shape (n_components, n_features)] Principal axes in feature space, representing the directions of maximum variance in the data. The components are sorted by explained_variance_.

explained_variance_ [ndarray of shape (n_components,)] The amount of variance explained by each of the selected components.

Equal to n_components largest eigenvalues of the covariance matrix of X.

New in version 0.18.

explained_variance_ratio_ [ndarray of shape (n_components,)] Percentage of variance explained by each of the selected components.
If `n_components` is not set then all components are stored and the sum of the ratios is equal to 1.0.

`singular_values_` [ndarray of shape (n_components,)] The singular values corresponding to each of the selected components. The singular values are equal to the 2-norms of the `n_components` variables in the lower-dimensional space.

New in version 0.19.

`mean_` [ndarray of shape (n_features,)] Per-feature empirical mean, estimated from the training set.

Equal to \( \bar{X} \) where \( \bar{X} \) is the mean of the input data.

`n_components_` [int] The estimated number of components. When `n_components` is set to 'mle' or a number between 0 and 1 (with `svd_solver` == 'full') this number is estimated from input data. Otherwise it equals the parameter `n_components`, or the lesser value of `n_features` and `n_samples` if `n_components` is None.

`n_features_` [int] Number of features in the training data.

`n_samples_` [int] Number of samples in the training data.

`noise_variance_` [float] The estimated noise covariance following the Probabilistic PCA model from Tipping and Bishop 1999. See “Pattern Recognition and Machine Learning” by C. Bishop, 12.2.1 p. 574 or http://www.miketipping.com/papers/met-mppca.pdf. It is required to compute the estimated data covariance and score samples.

Equal to the average of (min(n_features, n_samples) - n_components) smallest eigenvalues of the covariance matrix of X.

See also:

- `KernelPCA` Kernel Principal Component Analysis.
- `SparsePCA` Sparse Principal Component Analysis.
- `TruncatedSVD` Dimensionality reduction using truncated SVD.
- `IncrementalPCA` Incremental Principal Component Analysis.

References

For `n_components` == 'mle', this class uses the method of Minka, T. P. “Automatic choice of dimensionality for PCA”. In NIPS, pp. 598-604


For `svd_solver` == ‘arpack’, refer to scipy.sparse.linalg.svds.

Examples

```python
>>> import numpy as np
>>> from sklearn.decomposition import PCA
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> pca = PCA(n_components=2)
>>> pca.fit(X)
PCA(n_components=2)

>>> print(pca.explained_variance_ratio_)
[0.9924... 0.0075...]
>>> print(pca.singular_values_)
[6.30061... 0.54980...]
>>> pca = PCA(n_components=2, svd_solver='full')
>>> pca.fit(X)
PCA(n_components=2, svd_solver='full')

>>> print(pca.explained_variance_ratio_)
[0.9924... 0.00755...]
>>> print(pca.singular_values_)
[6.30061... 0.54980...]
>>> pca = PCA(n_components=1, svd_solver='arpack')
>>> pca.fit(X)
PCA(n_components=1, svd_solver='arpack')

>>> print(pca.explained_variance_ratio_)
[0.99244...]
>>> print(pca.singular_values_)
[6.30061...]
```

Methods

- `fit(X[, y])`: Fit the model with X.
- `fit_transform(X[, y])`: Fit the model with X and apply the dimensionality reduction on X.
- `get_covariance()`: Compute data covariance with the generative model.
- `get_params([deep])`: Get parameters for this estimator.
- `get_precision()`: Compute data precision matrix with the generative model.
- `inverse_transform(X)`: Transform data back to its original space.
- `score(X[, y])`: Return the average log-likelihood of all samples.
- `score_samples(X)`: Return the log-likelihood of each sample.
- `set_params(**params)`: Set the parameters of this estimator.
- `transform(X)`: Apply dimensionality reduction to X.

```
fit(X, y=None)
```

Fit the model with X.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

- `y` [Ignored]
Returns

self [object] Returns the instance itself.

**fit_transform** *(X, y=None)*
Fit the model with X and apply the dimensionality reduction on X.

**Parameters**

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [Ignored]

**Returns**

X_new [ndarray of shape (n_samples, n_components)] Transformed values.

**Notes**

This method returns a Fortran-ordered array. To convert it to a C-ordered array, use `np.ascontiguousarray`.

**get_covariance** ()
Compute data covariance with the generative model.

cov = components_.T * S**2 * components_ + sigma2 * eye(n_features)
where S**2 contains the explained variances, and sigma2 contains the noise variances.

**Returns**

cov [array, shape=(n_features, n_features)] Estimated covariance of data.

**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**get_precision** ()
Compute data precision matrix with the generative model.

Equals the inverse of the covariance but computed with the matrix inversion lemma for efficiency.

**Returns**

precision [array, shape=(n_features, n_features)] Estimated precision of data.

**inverse_transform** *(X)*
Transform data back to its original space.

In other words, return an input X_original whose transform would be X.

**Parameters**

X [array-like, shape (n_samples, n_components)] New data, where n_samples is the number of samples and n_components is the number of components.

**Returns**

X_original array-like, shape (n_samples, n_features)
Notes

If whitening is enabled, inverse_transform will compute the exact inverse operation, which includes reversing whitening.

score \((X, y=\text{None})\)

Return the average log-likelihood of all samples.


Parameters

- X [array-like of shape (n_samples, n_features)] The data.
- y [Ignored]

Returns

- ll [float] Average log-likelihood of the samples under the current model.

score_samples \((X)\)

Return the log-likelihood of each sample.


Parameters

- X [array-like of shape (n_samples, n_features)] The data.

Returns

- ll [ndarray of shape (n_samples,)] Log-likelihood of each sample under the current model.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- **params [dict] Estimator parameters.

Returns


transform \((X)\)

Apply dimensionality reduction to X.

X is projected on the first principal components previously extracted from a training set.

Parameters

- X [array-like, shape (n_samples, n_features)] New data, where n_samples is the number of samples and n_features is the number of features.

Returns

- X_new [array-like, shape (n_samples, n_components)]
Examples

```python
>>> import numpy as np
>>> from sklearn.decomposition import IncrementalPCA
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> ipca = IncrementalPCA(n_components=2, batch_size=3)
>>> ipca.fit(X)
IncrementalPCA(batch_size=3, n_components=2)
>>> ipca.transform(X)
```

Examples using `sklearn.decomposition.PCA`

- A demo of K-Means clustering on the handwritten digits data
- Principal Component Regression vs Partial Least Squares Regression
- The Iris Dataset
- PCA example with Iris Data-set
- Incremental PCA
- Comparison of LDA and PCA 2D projection of Iris dataset
- Factor Analysis (with rotation) to visualize patterns
- Blind source separation using FastICA
- Principal components analysis (PCA)
- FastICA on 2D point clouds
- Kernel PCA
- Model selection with Probabilistic PCA and Factor Analysis (FA)
- Faces dataset decompositions
- Faces recognition example using eigenfaces and SVMs
- Multi-dimensional scaling
- Multilabel classification
- Explicit feature map approximation for RBF kernels
- Balance model complexity and cross-validated score
- Kernel Density Estimation
- Dimensionality Reduction with Neighborhood Components Analysis
- Concatenating multiple feature extraction methods
- Pipelining: chaining a PCA and a logistic regression
- Selecting dimensionality reduction with Pipeline and GridSearchCV
- Importance of Feature Scaling
7.8.11 sklearn.decomposition.SparsePCA

class sklearn.decomposition.SparsePCA(n_components=None, *, alpha=1, ridge_alpha=0.01, max_iter=1000, tol=1e-08, method='lars', n_jobs=None, U_init=None, V_init=None, verbose=False, random_state=None)

Sparse Principal Components Analysis (SparsePCA).

Finds the set of sparse components that can optimally reconstruct the data. The amount of sparseness is controllable by the coefficient of the L1 penalty, given by the parameter alpha.

Read more in the User Guide.

Parameters

- **n_components** [int, default=None] Number of sparse atoms to extract.
- **alpha** [float, default=1] Sparsity controlling parameter. Higher values lead to sparser components.
- **ridge_alpha** [float, default=0.01] Amount of ridge shrinkage to apply in order to improve conditioning when calling the transform method.
- **max_iter** [int, default=1000] Maximum number of iterations to perform.
- **tol** [float, default=1e-8] Tolerance for the stopping condition.
- **method** ['lars', 'cd', default='lars'] lars: uses the least angle regression method to solve the lasso problem (linear_model.lars_path) cd: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). Lars will be faster if the estimated components are sparse.
- **n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.
- **U_init** [ndarray of shape (n_samples, n_components), default=None] Initial values for the loadings for warm restart scenarios.
- **V_init** [ndarray of shape (n_components, n_features), default=None] Initial values for the components for warm restart scenarios.
- **verbose** [int or bool, default=False] Controls the verbosity; the higher, the more messages. Defaults to 0.
- **random_state** [int, RandomState instance or None, default=None] Used during dictionary learning. Pass an int for reproducible results across multiple function calls. See Glossary.

Attributes

- **components_** [ndarray of shape (n_components, n_features)] Sparse components extracted from the data.
- **error_** [ndarray] Vector of errors at each iteration.
- **n_components_** [int] Estimated number of components. New in version 0.23.
- **n_iter_** [int] Number of iterations run.
- **mean_** [ndarray of shape (n_features,)] Per-feature empirical mean, estimated from the training set. Equal to X.mean(axis=0).

See also:
PCA

MiniBatchSparsePCA

DictionaryLearning

Examples

```python
>>> import numpy as np
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.decomposition import SparsePCA

>>> X, _ = make_friedman1(n_samples=200, n_features=30, random_state=0)
>>> transformer = SparsePCA(n_components=5, random_state=0)
>>> Transformer.fit(X)
SparsePCA(...)
>>> X_transformed = transformer.transform(X)
>>> X_transformed.shape
(200, 5)
>>> # most values in the components_ are zero (sparsity)
>>> np.mean(transformer.components_ == 0)
0.9666...
```

Methods

- `fit(X[, y])` Fit the model from data in X.
- `fit_transform(X[, y], **fit_params)` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Least Squares projection of the data onto the sparse components.

**fit (X, y=None)**

Fit the model from data in X.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- `y` [Ignored]

**Returns**

- `self` [object] Returns the instance itself.

**fit_transform (X, y=None, **fit_params)**

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
**fit_params** [dict] Additional fit parameters.

Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform (X)
Least Squares projection of the data onto the sparse components.

To avoid instability issues in case the system is under-determined, regularization can be applied (Ridge regression) via the `ridge_alpha` parameter.

Note that Sparse PCA components orthogonality is not enforced as in PCA hence one cannot use a simple linear projection.

Parameters

X  [ndarray of shape (n_samples, n_features)] Test data to be transformed, must have the same number of features as the data used to train the model.

Returns

X_new  [ndarray of shape (n_samples, n_components)] Transformed data.

### 7.8.12 sklearn.decomposition.SparseCoder

class sklearn.decomposition.SparseCoder (dictionary, *, transform_algorithm='omp', transform_n_nonzero_coefs=None, transform_alpha=None, split_sign=False, n_jobs=None, positive_code=False, transform_max_iter=1000)

Sparse coding

Finds a sparse representation of data against a fixed, precomputed dictionary.

Each row of the result is the solution to a sparse coding problem. The goal is to find a sparse array `code` such that:
X ~= code * dictionary

Read more in the User Guide.

Parameters

- **dictionary** – [ndarray of shape (n_components, n_features)]
  
  The dictionary atoms used for sparse coding. Lines are assumed to be normalized to unit norm.

  
  Algorithm used to transform the data:

  - ‘lars’: uses the least angle regression method (linear_model.lars_path);
  - ‘lasso_lars’: uses Lars to compute the Lasso solution;
  - ‘lasso_cd’: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). ‘lasso_lars’ will be faster if the estimated components are sparse;
  - ‘omp’: uses orthogonal matching pursuit to estimate the sparse solution;
  - ‘threshold’: squashes to zero all coefficients less than alpha from the projection \( \text{dictionary} \times X' \).

- **transform_n_nonzero_coefs** – [int, default=None]
  
  Number of nonzero coefficients to target in each column of the solution. This is only used by algorithm=’lars’ and algorithm=’omp’ and is overridden by alpha in the omp case. If None, then transform_n_nonzero_coefs=int(n_features / 10).

- **transform_alpha** – [float, default=None]
  
  If algorithm=’lasso_lars’ or algorithm=’lasso_cd’, alpha is the penalty applied to the L1 norm. If algorithm=’threshold’, alpha is the absolute value of the threshold below which coefficients will be squashed to zero. If algorithm=’omp’, alpha is the tolerance parameter: the value of the reconstruction error targeted. In this case, it overrides n_nonzero_coefs. If None, default to 1.

- **split_sign** – [bool, default=False]
  
  Whether to split the sparse feature vector into the concatenation of its negative part and its positive part. This can improve the performance of downstream classifiers.

- **n_jobs** – [int, default=None]
  
  Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

- **positive_code** – [bool, default=False]
  
  Whether to enforce positivity when finding the code.

  New in version 0.20.

- **transform_max_iter** – [int, default=1000]
  
  Maximum number of iterations to perform if algorithm=’lasso_cd’ or lasso_lars.

  New in version 0.22.

Attributes

- **components_** – [ndarray of shape (n_components, n_features)]
  
  The unchanged dictionary atoms.

  Deprecated since version 0.24: This attribute is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). Use dictionary instead.

See also:

7.8. sklearn.decomposition: Matrix Decomposition
DictionaryLearning

MiniBatchDictionaryLearning

SparsePCA

MiniBatchSparsePCA

sparse_encode

Examples

```python
>>> import numpy as np
>>> from sklearn.decomposition import SparseCoder

>>> X = np.array([[[-1, -1, -1], [0, 0, 3]],
                [[1, 0, 1], [0, 1, 1], [0, 2, 1]],
                [[0, 1, 0],
                 [-1, -1, 2],
                 [1, 1, 1]],
                [[0, 1, 1],
                 [0, 2, 1]],
                dtype=np.float64])

>>> dictionary = np.array([[0, 1, 0],
                          [-1, -1, 2],
                          [1, 1, 1],
                          [0, 1, 1],
                          [0, 2, 1]],
                          dtype=np.float64)

>>> coder = SparseCoder(
                          dictionary=dictionary, transform_algorithm='lasso_lars',
                          transform_alpha=1e-10,
                          )

>>> coder.transform(X)
array([[ 0., 0., -1., 0., 0.],
    [ 0., 1., 1., 0., 0.]])
```

Methods

- `fit(X[, y])`: Do nothing and return the estimator unchanged.
- `fit_transform(X[, y])`: Fit to data, then transform it.
- `get_params([deep])`: Get parameters for this estimator.
- `set_params(**params)`: Set the parameters of this estimator.
- `transform(X[, y])`: Encode the data as a sparse combination of the dictionary atoms.

**fit**(X, y=None)
Do nothing and return the estimator unchanged.

This method is just there to implement the usual API and hence work in pipelines.

**Parameters**

- **X** [Ignored]
- **y** [Ignored]

**Returns**

- **self** [object]

**fit_transform**(X, y=None, **fit_params)
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**transform** *(X, y=None)*

Encode the data as a sparse combination of the dictionary atoms.

Coding method is determined by the object parameter *transform_algorithm*.

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Test data to be transformed, must have the same number of features as the data used to train the model.

**Returns**

- **X_new** [ndarray of shape (n_samples, n_components)] Transformed data.
Examples using `sklearn.decomposition.SparseCoder`

- Sparse coding with a precomputed dictionary

### 7.8.13 `sklearn.decomposition.TruncatedSVD`

```python
class sklearn.decomposition.TruncatedSVD(n_components=2, *, algorithm='randomized', n_iter=5, random_state=None, tol=0.0)
```

Dimensionality reduction using truncated SVD (aka LSA).

This transformer performs linear dimensionality reduction by means of truncated singular value decomposition (SVD). Contrary to PCA, this estimator does not center the data before computing the singular value decomposition. This means it can work with sparse matrices efficiently.

In particular, truncated SVD works on term count/tf-idf matrices as returned by the vectorizers in `sklearn.feature_extraction.text`. In that context, it is known as latent semantic analysis (LSA).

This estimator supports two algorithms: a fast randomized SVD solver, and a “naive” algorithm that uses ARPACK as an eigensolver on \( X \ast X^T \) or \( X^T \ast X \), whichever is more efficient.

Read more in the User Guide.

**Parameters**

- `n_components` [int, default=2] Desired dimensionality of output data. Must be strictly less than the number of features. The default value is useful for visualisation. For LSA, a value of 100 is recommended.
- `algorithm` [{'arpack', 'randomized'}, default='randomized'] SVD solver to use. Either “arpack” for the ARPACK wrapper in SciPy (`scipy.sparse.linalg.svds`), or “randomized” for the randomized algorithm due to Halko (2009).
- `n_iter` [int, default=5] Number of iterations for randomized SVD solver. Not used by ARPACK. The default is larger than the default in `randomized_svd` to handle sparse matrices that may have large slowly decaying spectrum.
- `random_state` [int, RandomState instance or None, default=None] Used during randomized svd. Pass an int for reproducible results across multiple function calls. See Glossary.
- `tol` [float, default=0.] Tolerance for ARPACK. 0 means machine precision. Ignored by randomized SVD solver.

**Attributes**

- `components_` [ndarray of shape (n_components, n_features)]
- `explained_variance_` [ndarray of shape (n_components,)] The variance of the training samples transformed by a projection to each component.
- `explained_variance_ratio_` [ndarray of shape (n_components,)] Percentage of variance explained by each of the selected components.
- `singular_values_` [ndarray of shape (n_components,)] The singular values corresponding to each of the selected components. The singular values are equal to the 2-norms of the \( n_{\text{components}} \) variables in the lower-dimensional space.

See also:

*PCA*
## Notes

SVD suffers from a problem called “sign indeterminacy”, which means the sign of the components and the output from transform depend on the algorithm and random state. To work around this, fit instances of this class to data once, then keep the instance around to do transformations.

## References

Finding structure with randomness: Stochastic algorithms for constructing approximate matrix decompositions  

## Examples

```python
>>> from sklearn.decomposition import TruncatedSVD
>>> from scipy.sparse import random as sparse_random

>>> X = sparse_random(100, 100, density=0.01, format='csr', random_state=42)
>>> svd = TruncatedSVD(n_components=5, n_iter=7, random_state=42)
>>> svd.fit(X)
TruncatedSVD(n_components=5, n_iter=7, random_state=42)
>>> print(svd.explained_variance_ratio_)
[0.0646... 0.0633... 0.0639... 0.0535... 0.0406...]
>>> print(svd.explained_variance_ratio_.sum())
0.286...
>>> print(svd.singular_values_)
[1.553... 1.512... 1.510... 1.370... 1.199...]
```

## Methods

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<td>Perform dimensionality reduction on X.</td>
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**fit** *(X, y=None)*

Fit model on training data X.

**Parameters**

- **X** | [array-like, sparse matrix] of shape (n_samples, n_features) Training data.
- **y** | [Ignored]

**Returns**

- **self** | [object] Returns the transformer object.

**fit_transform** *(X, y=None)*

Fit model to X and perform dimensionality reduction on X.

**Parameters**

- **X** | [array-like, sparse matrix] of shape (n_samples, n_features) Training data.
- **y** | [Ignored]
X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data.

y [Ignored]

Returns

X_new [ndarray of shape (n_samples, n_components)] Reduced version of X. This will always be a dense array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform (X)
Transform X back to its original space.

Returns an array X_original whose transform would be X.

Parameters

X [array-like of shape (n_samples, n_components)] New data.

Returns

X_original [ndarray of shape (n_samples, n_features)] Note that this is always a dense array.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Perform dimensionality reduction on X.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] New data.

Returns

X_new [ndarray of shape (n_samples, n_components)] Reduced version of X. This will always be a dense array.
Examples using `sklearn.decomposition.TruncatedSVD`

- Hashing feature transformation using Totally Random Trees
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...
- Column Transformer with Heterogeneous Data Sources
- Clustering text documents using k-means

```python
decomposition.dict_learning(X, n_components, ...)  # Solves a dictionary learning matrix factorization problem.
decomposition.dict_learning_online(X[, ...])  # Solves a dictionary learning matrix factorization problem online.
decomposition.fastica(X[, n_components, ...])  # Perform Fast Independent Component Analysis.
decomposition.non_negative_factorization(X)  # Compute Non-negative Matrix Factorization (NMF).
decomposition.sparse_encode(X, dictionary, *)  # Sparse coding
```

### 7.8.14 sklearn.decomposition.dict_learning

`sklearn.decomposition.dict_learning` solves a dictionary learning matrix factorization problem.

Finds the best dictionary and the corresponding sparse code for approximating the data matrix X by solving:

\[
(U^*, V^*) = \arg\min_{(U, V)} 0.5 \| X - U V \|_2^2 + \alpha \| U \|_1
\]

where V is the dictionary and U is the sparse code.

Read more in the User Guide.

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Data matrix.
- **n_components** [int] Number of dictionary atoms to extract.
- **alpha** [int] Sparsity controlling parameter.
- **max_iter** [int, default=100] Maximum number of iterations to perform.
- **tol** [float, default=1e-08] Tolerance for the stopping condition.
- **method** [‘lars’, ‘cd’], default=’lars’ The method used:
  - ‘lars’: uses the least angle regression method to solve the lasso problem (linear_model.lars_path);
  - ‘cd’: uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). Lars will be faster if the estimated components are sparse.
**n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**dict_init** [ndarray of shape (n_components, n_features), default=None] Initial value for the dictionary for warm restart scenarios.

**code_init** [ndarray of shape (n_samples, n_components), default=None] Initial value for the sparse code for warm restart scenarios.

**callback** [callable, default=None] Callable that gets invoked every five iterations

**verbose** [bool, default=False] To control the verbosity of the procedure.

**random_state** [int, RandomState instance or None, default=None] Used for randomly initializing the dictionary. Pass an int for reproducible results across multiple function calls. See Glossary.

**return_n_iter** [bool, default=False] Whether or not to return the number of iterations.

**positive_dict** [bool, default=False] Whether to enforce positivity when finding the dictionary. New in version 0.20.

**positive_code** [bool, default=False] Whether to enforce positivity when finding the code. New in version 0.20.

**method_max_iter** [int, default=1000] Maximum number of iterations to perform. New in version 0.22.

**Returns**

code [ndarray of shape (n_samples, n_components)] The sparse code factor in the matrix factorization.

dictionary [ndarray of shape (n_components, n_features).] The dictionary factor in the matrix factorization.

ersors [array] Vector of errors at each iteration.

**n_iter** [int] Number of iterations run. Returned only if return_n_iter is set to True.

See also:

dict_learning_online
DictionaryLearning
MiniBatchDictionaryLearning
SparsePCA
MiniBatchSparsePCA
Solves a dictionary learning matrix factorization problem online.

Finds the best dictionary and the corresponding sparse code for approximating the data matrix $X$ by solving:

$$\text{argmin}_{U, V} 0.5 \|X - UV\|_2^2 + \alpha \|U\|_1$$

with $\|V_k\|_2 = 1$ for all $0 \leq k < n_{\text{components}}$

where $V$ is the dictionary and $U$ is the sparse code. This is accomplished by repeatedly iterating over mini-batches by slicing the input data.

Read more in the User Guide.

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Data matrix.
- **n_components** [int, default=2] Number of dictionary atoms to extract.
- **alpha** [float, default=1] Sparsity controlling parameter.
- **n_iter** [int, default=100] Number of mini-batch iterations to perform.
- **return_code** [bool, default=True] Whether to also return the code $U$ or just the dictionary $V$.
- **dict_init** [ndarray of shape (n_components, n_features), default=None] Initial value for the dictionary for warm restart scenarios.
- **callback** [callable, default=None] Callable that gets invoked every five iterations.
- **batch_size** [int, default=3] The number of samples to take in each batch.
- **verbose** [bool, default=False] To control the verbosity of the procedure.
- **shuffle** [bool, default=True] Whether to shuffle the data before splitting it in batches.
- **n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.
- **method** ['lars', 'cd', default='lars']
  - 'lars': uses the least angle regression method to solve the lasso problem (linear_model.lars_path);
  - 'cd': uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). Lars will be faster if the estimated components are sparse.
- **iter_offset** [int, default=0] Number of previous iterations completed on the dictionary used for initialization.
- **random_state** [int, RandomState instance or None, default=None] Used for initializing the dictionary when dict_init is not specified, randomly shuffling the data when shuffle is True.

---

**7.8. sklearn.decomposition: Matrix Decomposition**

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is set to True, and updating the dictionary. Pass an int for reproducible results across multiple function calls. See Glossary.

**return_inner_stats** [bool, default=False] Return the inner statistics A (dictionary covariance) and B (data approximation). Useful to restart the algorithm in an online setting. If return_inner_stats is True, return_code is ignored.

**inner_stats** [tuple of (A, B) ndarrays, default=None] Inner sufficient statistics that are kept by the algorithm. Passing them at initialization is useful in online settings, to avoid losing the history of the evolution. A (n_components, n_components) is the dictionary covariance matrix. B (n_features, n_components) is the data approximation matrix.

**return_n_iter** [bool, default=False] Whether or not to return the number of iterations.

**positive_dict** [bool, default=False] Whether to enforce positivity when finding the dictionary.

New in version 0.20.

**positive_code** [bool, default=False] Whether to enforce positivity when finding the code.

New in version 0.20.

**method_max_iter** [int, default=1000] Maximum number of iterations to perform when solving the lasso problem.

New in version 0.22.

**Returns**

**code** [ndarray of shape (n_samples, n_components),] The sparse code (only returned if return_code=True).

**dictionary** [ndarray of shape (n_components, n_features),] The solutions to the dictionary learning problem.

**n_iter** [int] Number of iterations run. Returned only if return_n_iter is set to True.

See also:

dict_learning

DictionaryLearning

MiniBatchDictionaryLearning

SparsePCA

MiniBatchSparsePCA

**7.8.16 sklearn.decomposition.fastica**

sklearn.decomposition.fastica(X, n_components=None, *, algorithm='parallel', whiten=True, fun='logcosh', fun_args=None, max_iter=200, tol=0.0001, w_init=None, random_state=None, return_X_mean=False, compute_sources=True, return_n_iter=False)

Perform Fast Independent Component Analysis.

Read more in the User Guide.

**Parameters**

X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
n_components [int, default=None] Number of components to extract. If None no dimension reduction is performed.

algorithm [{‘parallel’, ‘deflation’}, default=’parallel’] Apply a parallel or deflational FAS-TICA algorithm.

whiten [bool, default=True] If True perform an initial whitening of the data. If False, the data is assumed to have already been preprocessed: it should be centered, normed and white. Otherwise you will get incorrect results. In this case the parameter n_components will be ignored.

fun [{‘logcosh’, ‘exp’, ‘cube’} or callable, default=’logcosh’] The functional form of the G function used in the approximation to neg-entropy. Could be either ‘logcosh’, ‘exp’, or ‘cube’. You can also provide your own function. It should return a tuple containing the value of the function, and of its derivative, in the point. The derivative should be averaged along its last dimension. Example:

def my_g(x):
    return x ** 3, np.mean(3 * x ** 2, axis=-1)

fun_args [dict, default=None] Arguments to send to the functional form. If empty or None and if fun=’logcosh’, fun_args will take value {‘alpha’ : 1.0}

max_iter [int, default=200] Maximum number of iterations to perform.

tol [float, default=1e-04] A positive scalar giving the tolerance at which the un-mixing matrix is considered to have converged.

w_init [ndarray of shape (n_components, n_components), default=None] Initial un-mixing array of dimension (n.comp.n.comp). If None (default) then an array of normal r.v.’s is used.

random_state [int, RandomState instance or None, default=None] Used to initialize w_init when not specified, with a normal distribution. Pass an int, for reproducible results across multiple function calls. See Glossary.

return_X_mean [bool, default=False] If True, X_mean is returned too.

compute_sources [bool, default=True] If False, sources are not computed, but only the rotation matrix. This can save memory when working with big data. Defaults to True.

return_n_iter [bool, default=False] Whether or not to return the number of iterations.

Returns

K [ndarray of shape (n_components, n_features) or None] If whiten is ‘True’, K is the pre-whitening matrix that projects data onto the first n_components principal components. If whiten is ‘False’, K is ‘None’.

W [ndarray of shape (n_components, n_components)] The square matrix that unmixes the data after whitening. The mixing matrix is the pseudo-inverse of matrix \( W K \) if K is not None, else it is the inverse of W.

S [ndarray of shape (n_samples, n_components) or None] Estimated source matrix

X_mean [ndarray of shape (n_features,)] The mean over features. Returned only if return_X_mean is True.

n_iter [int] If the algorithm is “deflation”, n_iter is the maximum number of iterations run across all components. Else they are just the number of iterations taken to converge. This is returned only when return_n_iter is set to True.
Notes

The data matrix X is considered to be a linear combination of non-Gaussian (independent) components i.e. \( X = AS \) where columns of S contain the independent components and A is a linear mixing matrix. In short ICA attempts to un-mix the data by estimating an un-mixing matrix \( W \) where \( `S = W X.` \) While FastICA was proposed to estimate as many sources as features, it is possible to estimate less by setting \( n\_components < n\_features \). In this case \( K \) is not a square matrix and the estimated A is the pseudo-inverse of \( W \).

This implementation was originally made for data of shape \([n\_features, n\_samples]\). Now the input is transposed before the algorithm is applied. This makes it slightly faster for Fortran-ordered input.


7.8.17 sklearn.decomposition.non_negative_factorization

sklearn.decomposition.non_negative_factorization(X, W=None, H=None, n_components=None, *, init='warn', update_H=True, solver='cd', beta_loss='frobenius', tol=0.0001, max_iter=200, alpha=0.0, l1_ratio=0.0, regularization=None, random_state=None, verbose=0, shuffle=False)

Compute Non-negative Matrix Factorization (NMF).

Find two non-negative matrices \((W, H)\) whose product approximates the non-negative matrix \( X \). This factorization can be used for example for dimensionality reduction, source separation or topic extraction.

The objective function is:

\[
0.5 \times ||X - WH||_{Fro}^2 + alpha * l1\_ratio * ||vec(W)||_1 \\
+ alpha * l1\_ratio * ||vec(H)||_1 \\
+ 0.5 * alpha * (1 - l1\_ratio) * ||W||_{Fro}^2 \\
+ 0.5 * alpha * (1 - l1\_ratio) * ||H||_{Fro}^2 
\]

Where:

\[
||A||_{Fro}^2 = \sum_{i,j} A_{ij}^2 \text{ (Frobenius norm)} \\
||vec(A)||_1 = \sum_{i,j} abs(A_{ij}) \text{ (Elementwise L1 norm)}
\]

For multiplicative-update (‘mu’) solver, the Frobenius norm \( (0.5 \times ||X - WH||_{Fro}^2) \) can be changed into another beta-divergence loss, by changing the beta_loss parameter.

The objective function is minimized with an alternating minimization of W and H. If H is given and update_H=False, it solves for W only.

Parameters

- **X** [array-like of shape \((n\_samples, n\_features)\)] Constant matrix.
- **W** [array-like of shape \((n\_samples, n\_components)\), default=None] If init='custom', it is used as initial guess for the solution.
H [array-like of shape (n_components, n_features), default=None] If init='custom', it is used as initial guess for the solution. If update_H=False, it is used as a constant, to solve for W only.

n_components [int, default=None] Number of components, if n_components is not set all features are kept.


Valid options:

• None: ‘nndsvd’ if n_components < n_features, otherwise ‘random’.
• ‘random’: non-negative random matrices, scaled with: \( \sqrt{\text{X}.\text{mean()}} / \sqrt{n\text{_components}} \)
• ‘nndsvd’: Nonnegative Double Singular Value Decomposition (NNDSVD)
  initialization (better for sparseness)
• ‘nndsvda’: NNDSVD with zeros filled with the average of X (better when sparsity is not desired)
• ‘nndsvdar’: NNDSVD with zeros filled with small random values (generally faster, less accurate alternative to NNDSVDA for when sparsity is not desired)
• ‘custom’: use custom matrices W and H if update_H=True. If update_H=False, then only custom matrix H is used.

Changed in version 0.23: The default value of init changed from ‘random’ to None in 0.23.

update_H [bool, default=True] Set to True, both W and H will be estimated from initial guesses. Set to False, only W will be estimated.

solver [{‘cd’, ‘mu’}, default=’cd’] Numerical solver to use:

• ‘cd’ is a Coordinate Descent solver that uses Fast Hierarchical Alternating Least Squares (Fast HALS).
• ‘mu’ is a Multiplicative Update solver.

New in version 0.17: Coordinate Descent solver.
New in version 0.19: Multiplicative Update solver.

beta_loss [float or {'frobenius', 'kullback-leibler', 'itakura-saito'}, default='frobenius'] Beta divergence to be minimized, measuring the distance between X and the dot product WH. Note that values different from ‘frobenius’ (or 2) and ‘kullback-leibler’ (or 1) lead to significantly slower fits. Note that for beta_loss <= 0 (or ‘itakura-saito’), the input matrix X cannot contain zeros. Used only in ‘mu’ solver.

New in version 0.19.


max_iter [int, default=200] Maximum number of iterations before timing out.

alpha [float, default=0.] Constant that multiplies the regularization terms.

l1_ratio [float, default=0.] The regularization mixing parameter, with 0 <= l1_ratio <= 1. For l1_ratio = 0 the penalty is an elementwise L2 penalty (aka Frobenius Norm). For l1_ratio = 1 it is an elementwise L1 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1 and L2.
regularization [[‘both’, ‘components’, ‘transformation’], default=None] Select whether the regularization affects the components (H), the transformation (W), both or none of them.

random_state [int, RandomState instance or None, default=None] Used for NMF initialisation (when init == ‘nndsvdar’ or ‘random’), and in Coordinate Descent. Pass an int for reproducible results across multiple function calls. See Glossary.

verbose [int, default=0] The verbosity level.

shuffle [bool, default=False] If true, randomize the order of coordinates in the CD solver.

Returns

W [ndarray of shape (n_samples, n_components)] Solution to the non-negative least squares problem.

H [ndarray of shape (n_components, n_features)] Solution to the non-negative least squares problem.

n_iter [int] Actual number of iterations.

References


Examples

```python
>>> import numpy as np
>>> X = np.array([[1, 1], [2, 1], [3, 1.2], [4, 1], [5, 0.8], [6, 1]])
>>> from sklearn.decomposition import non_negative_factorization
>>> W, H, n_iter = non_negative_factorization(X, n_components=2,
... init='random', random_state=0)
```

7.8.18 sklearn.decomposition.sparse_encode

sklearn.decomposition.sparse_encode(X, dictionary, *, gram=None, cov=None, algorithm='lasso_lars', n_nonzero_coefs=None, alpha=None, copy_cov=True, init=None, max_iter=1000, n_jobs=None, check_input=True, verbose=0, positive=False)

Sparse coding

Each row of the result is the solution to a sparse coding problem. The goal is to find a sparse array code such that:

\[ X \approx \text{code} \times \text{dictionary} \]

Read more in the User Guide.

Parameters

X [ndarray of shape (n_samples, n_features)] Data matrix.
**dictionary** [ndarray of shape (n_components, n_features)] The dictionary matrix against which to solve the sparse coding of the data. Some of the algorithms assume normalized rows for meaningful output.

**gram** [ndarray of shape (n_components, n_components), default=None] Precomputed Gram matrix, dictionary * dictionary'.

**cov** [ndarray of shape (n_components, n_samples), default=None] Precomputed covariance, dictionary' * X.

**algorithm** [{'lasso_lars', 'lasso_cd', 'lars', 'omp', 'threshold'}, default='lasso_lars'] The algorithm used:
- 'lars': uses the least angle regression method (linear_model.lars_path);
- 'lasso_lars': uses Lars to compute the Lasso solution;
- 'lasso_cd': uses the coordinate descent method to compute the Lasso solution (linear_model.Lasso). lasso_lars will be faster if the estimated components are sparse;
- 'omp': uses orthogonal matching pursuit to estimate the sparse solution;
- 'threshold': squashes to zero all coefficients less than regularization from the projection dictionary * data'.

**n_nonzero_coefs** [int, default=None] Number of nonzero coefficients to target in each column of the solution. This is only used by algorithm='lars' and algorithm='omp' and is overridden by alpha in the omp case. If None, then n_nonzero_coefs=int(n_features / 10).

**alpha** [float, default=None] If algorithm='lasso_lars' or algorithm='lasso_cd', alpha is the penalty applied to the L1 norm. If algorithm='threshold', alpha is the absolute value of the threshold below which coefficients will be squashed to zero. If algorithm='omp', alpha is the tolerance parameter: the value of the reconstruction error targeted. In this case, it overrides n_nonzero_coefs. If None, default to 1.

**copy_cov** [bool, default=True] Whether to copy the precomputed covariance matrix; if False, it may be overwritten.

**init** [ndarray of shape (n_samples, n_components), default=None] Initialization value of the sparse codes. Only used if algorithm='lasso_cd'.

**max_iter** [int, default=1000] Maximum number of iterations to perform if algorithm='lasso_cd' or 'lasso_lars'.

**n_jobs** [int, default=None] Number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**check_input** [bool, default=True] If False, the input arrays X and dictionary will not be checked.

**verbose** [int, default=0] Controls the verbosity; the higher, the more messages.

**positive** [bool, default=False] Whether to enforce positivity when finding the encoding. New in version 0.20.

**Returns**
- **code** [ndarray of shape (n_samples, n_components)] The sparse codes
See also:

- `sklearn.linear_model.lars_path`
- `sklearn.linear_model.orthogonal_mp`
- `sklearn.linear_model.Lasso`
- `SparseCoder`

### 7.9 sklearn.discriminant_analysis: Discriminant Analysis

Linear Discriminant Analysis and Quadratic Discriminant Analysis

**User guide:** See the *Linear and Quadratic Discriminant Analysis* section for further details.

| `discriminant_analysis.LinearDiscriminantAnalysis()` | Linear Discriminant Analysis |
| `discriminant_analysis.QuadraticDiscriminantAnalysis()` | Quadratic Discriminant Analysis |

### 7.9.1 sklearn.discriminant_analysis.LinearDiscriminantAnalysis

```python
class sklearn.discriminant_analysis.LinearDiscriminantAnalysis(solver='svd', shrinkage=None, priors=None, n_components=None, store_covariance=False, tol=0.0001, covariance_estimator=None)
```

**Linear Discriminant Analysis**

A classifier with a linear decision boundary, generated by fitting class conditional densities to the data and using Bayes’ rule.

The model fits a Gaussian density to each class, assuming that all classes share the same covariance matrix.

The fitted model can also be used to reduce the dimensionality of the input by projecting it to the most discriminative directions, using the `transform` method.

New in version 0.17: `LinearDiscriminantAnalysis`.

Read more in the *User Guide*.

**Parameters**

- **solver** : [‘svd’, ‘lsqr’, ‘eigen’], default=’svd’

  **Solver to use, possible values:**

  - ‘svd’: Singular value decomposition (default). Does not compute the covariance matrix, therefore this solver is recommended for data with a large number of features.
  - ‘lsqr’: Least squares solution. Can be combined with shrinkage or custom covariance estimator.
• ‘eigen’: Eigenvalue decomposition. Can be combined with shrinkage or custom covariance estimator.

**shrinkage** ['auto' or float, default=None]

**Shrinkage parameter, possible values:**

• None: no shrinkage (default).
• ‘auto’: automatic shrinkage using the Ledoit-Wolf lemma.
• float between 0 and 1: fixed shrinkage parameter.

This should be left to None if **covariance_estimator** is used. Note that shrinkage works only with ‘lsqr’ and ‘eigen’ solvers.

**priors** [array-like of shape (n_classes,), default=None] The class prior probabilities. By default, the class proportions are inferred from the training data.

**n_components** [int, default=None] Number of components (<= min(n_classes - 1, n_features)) for dimensionality reduction. If None, will be set to min(n_classes - 1, n_features). This parameter only affects the **transform** method.

**store_covariance** [bool, default=False] If True, explicitly compute the weighted within-class covariance matrix when solver is ‘svd’. The matrix is always computed and stored for the other solvers.

New in version 0.17.

**tol** [float, default=1.0e-4] Absolute threshold for a singular value of X to be considered significant, used to estimate the rank of X. Dimensions whose singular values are non-significant are discarded. Only used if solver is ‘svd’.

New in version 0.17.

**covariance_estimator** [covariance estimator, default=None] If not None, **covariance_estimator** is used to estimate the covariance matrices instead of relying on the empirical covariance estimator (with potential shrinkage). The object should have a fit method and a **covariance_** attribute like the estimators in **sklearn.covariance**. If None the shrinkage parameter drives the estimate.

This should be left to None if **shrinkage** is used. Note that **covariance_estimator** works only with ‘lsqr’ and ‘eigen’ solvers.

New in version 0.24.

**Attributes**

- **coef_** [ndarray of shape (n_features,) or (n_classes, n_features)] Weight vector(s).
- **intercept_** [ndarray of shape (n_classes,)] Intercept term.
- **covariance_** [array-like of shape (n_features, n_features)] Weighted within-class covariance matrix. It corresponds to \( \sum_k \text{prior}_k \times C_k \) where \( C_k \) is the covariance matrix of the samples in class \( k \). The \( C_k \) are estimated using the (potentially shrunk) biased estimator of covariance. If solver is ‘svd’, only exists when **store_covariance** is True.
- **explained_variance_ratio_** [ndarray of shape (n_components,)] Percentage of variance explained by each of the selected components. If **n_components** is not set then all components are stored and the sum of explained variances is equal to 1.0. Only available when eigen or svd solver is used.
- **means_** [array-like of shape (n_classes, n_features)] Class-wise means.
- **priors_** [array-like of shape (n_classes,)] Class priors (sum to 1).
scalings_ [array-like of shape (rank, n_classes - 1)] Scaling of the features in the space spanned by the class centroids. Only available for ‘svd’ and ‘eigen’ solvers.

xbar_ [array-like of shape (n_features,)] Overall mean. Only present if solver is ‘svd’.

classes_ [array-like of shape (n_classes,)] Unique class labels.

See also:

**QuadraticDiscriminantAnalysis** Quadratic Discriminant Analysis.

Examples

```python
>>> import numpy as np
>>> from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
>>> X = np.array([[[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> y = np.array([1, 1, 1, 2, 2, 2])
>>> clf = LinearDiscriminantAnalysis()
>>> clf.fit(X, y)
LinearDiscriminantAnalysis()
>>> print(clf.predict([[0.8, -1]]))
[1]
```

Methods

- `decision_function(X)` Apply decision function to an array of samples.
- `fit(X, y)` Fit LinearDiscriminantAnalysis model according to the given
- `fit_transform(X[, y])` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict class labels for samples in X.
- `predict_log_proba(X)` Estimate log probability.
- `predict_proba(X)` Estimate probability.
- `score(X, y[, sample_weight])` Return the mean accuracy on the given test data and labels.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Project data to maximize class separation.

**decision_function(X)**
Apply decision function to an array of samples.

The decision function is equal (up to a constant factor) to the log-posterior of the model, i.e. \( \log p(y = k | x) \). In a binary classification setting this instead corresponds to the difference \( \log p(y = 1 | x) - \log p(y = 0 | x) \). See *Mathematical formulation of the LDA and QDA classifiers*.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Array of samples (test vectors).

**Returns**

- **C** [ndarray of shape (n_samples,) or (n_samples, n_classes)] Decision function values related to each class, per sample. In the two-class case, the shape is (n_samples,), giving the log likelihood ratio of the positive class.

`fit(X, y)`
**Fit LinearDiscriminantAnalysis model according to the given** training data and parameters.

Changed in version 0.19: `store_covariance` has been moved to main constructor.

Changed in version 0.19: `tol` has been moved to main constructor.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Training data.
- `y` [array-like of shape (n_samples,)] Target values.

**fit_transform** (*X, y=None, **fit_params*)

Fit to data, then transform it.

Fits transformer to `X` and `y` with optional parameters `fit_params` and returns a transformed version of `X`.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- `**fit_params` [dict] Additional fit parameters.

**Returns**

- `X_new` [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** (*deep=True*)

Get parameters for this estimator.

**Parameters**

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params` [dict] Parameter names mapped to their values.

**predict** (*X*)

Predict class labels for samples in `X`.

**Parameters**

- `X` [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- `C` [array, shape [n_samples]] Predicted class label per sample.

**predict_log_proba** (*X*)

Estimate log probability.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input data.

**Returns**

- `C` [ndarray of shape (n_samples, n_classes)] Estimated log probabilities.

**predict_proba** (*X*)

Estimate probability.
Parameters

X [array-like of shape (n_samples, n_features)] Input data.

Returns

C [ndarray of shape (n_samples, n_classes)] Estimated probabilities.

score (X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Project data to maximize class separation.

Parameters

X [array-like of shape (n_samples, n_features)] Input data.

Returns

X_new [ndarray of shape (n_samples, n_components)] Transformed data.

Examples using sklearn.discriminant_analysis.LinearDiscriminantAnalysis

- Normal, Ledoit-Wolf and OAS Linear Discriminant Analysis for classification
- Linear and Quadratic Discriminant Analysis with covariance ellipsoid
- Comparison of LDA and PCA 2D projection of Iris dataset
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap…
- Dimensionality Reduction with Neighborhood Components Analysis
7.9.2 sklearn.discriminant_analysis.QuadraticDiscriminantAnalysis

```
class sklearn.discriminant_analysis.QuadraticDiscriminantAnalysis(*, priors=None, reg_param=0.0, store_covariance=False, tol=0.0001)
```

Quadratic Discriminant Analysis
A classifier with a quadratic decision boundary, generated by fitting class conditional densities to the data and using Bayes’ rule.

The model fits a Gaussian density to each class.
New in version 0.17: `QuadraticDiscriminantAnalysis`
Read more in the User Guide.

Parameters

- **priors** [ndarray of shape (n_classes,), default=None] Class priors. By default, the class proportions are inferred from the training data.
- **reg_param** [float, default=0.0] Regularizes the per-class covariance estimates by transforming $S2$ as $S2 = (1 - \text{reg\_param}) \times S2 + \text{reg\_param} \times \text{np.eye(n\_features)}$, where $S2$ corresponds to the `scaling_` attribute of a given class.
- **store_covariance** [bool, default=False] If True, the class covariance matrices are explicitly computed and stored in the `self.covariance_` attribute.
  New in version 0.17.
- **tol** [float, default=1.0e-4] Absolute threshold for a singular value to be considered significant, used to estimate the rank of $X_k$ where $X_k$ is the centered matrix of samples in class $k$. This parameter does not affect the predictions. It only controls a warning that is raised when features are considered to be colinear.
  New in version 0.17.

Attributes

- **covariance_** [list of len n_classes of ndarray of shape (n_features, n_features)] For each class, gives the covariance matrix estimated using the samples of that class. The estimations are unbiased. Only present if `store_covariance` is True.
- **means_** [array-like of shape (n_classes, n_features)] Class-wise means.
- **priors_** [array-like of shape (n_classes,)] Class priors (sum to 1).
- **rotations_** [list of len n_classes of ndarray of shape (n_features, n_k)] For each class $k$ an array of shape (n_features, n_k), where $n_k = \min(n\_features, \text{number of elements in class } k)$. It is the rotation of the Gaussian distribution, i.e. its principal axis. It corresponds to $V$, the matrix of eigenvectors coming from the SVD of $X_k = U S V^t$ where $X_k$ is the centered matrix of samples from class $k$.
- **scalings_** [list of len n_classes of ndarray of shape (n_k,)] For each class, contains the scaling of the Gaussian distributions along its principal axes, i.e. the variance in the rotated coordinate system. It corresponds to $S^2 / (n\_samples - 1)$, where $S$ is the diagonal matrix of singular values from the SVD of $X_k$, where $X_k$ is the centered matrix of samples from class $k$.
- **classes_** [ndarray of shape (n_classes,)] Unique class labels.
See also:

**LinearDiscriminantAnalysis** Linear Discriminant Analysis.

Examples

```python
>>> from sklearn.discriminant_analysis import QuadraticDiscriminantAnalysis
>>> import numpy as np

>>> X = np.array([[[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> y = np.array([[1, 1, 1, 2, 2, 2]])
>>> clf = QuadraticDiscriminantAnalysis()
>>> clf.fit(X, y)
QuadraticDiscriminantAnalysis()

>>> print(clf.predict([[[-0.8, -1]]]))
[1]
```

Methods

- `decision_function(X)` Apply decision function to an array of samples.
- `fit(X, y)` Fit the model according to the given training data and parameters.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Perform classification on an array of test vectors X.
- `predict_log_proba(X)` Return log of posterior probabilities of classification.
- `predict_proba(X)` Return posterior probabilities of classification.
- `score(X, y[, sample_weight])` Return the mean accuracy on the given test data and labels.
- `set_params(**params)` Set the parameters of this estimator.

**decision_function** *(X)*

Apply decision function to an array of samples.

The decision function is equal (up to a constant factor) to the log-posterior of the model, i.e. \( \log p(y = k | x) \). In a binary classification setting this instead corresponds to the difference \( \log p(y = 1 | x) - \log p(y = 0 | x) \). See Mathematical formulation of the LDA and QDA classifiers.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Array of samples (test vectors).

**Returns**

- **C** [ndarray of shape (n_samples,) or (n_samples, n_classes)] Decision function values related to each class, per sample. In the two-class case, the shape is (n_samples,) giving the log likelihood ratio of the positive class.

**fit**(X, y)

Fit the model according to the given training data and parameters.

Changed in version 0.19: `store_covariances` has been moved to main constructor as `store_covariance`

Changed in version 0.19: `tol` has been moved to main constructor.

**Parameters**
X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values (integers)

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Perform classification on an array of test vectors X.

The predicted class C for each sample in X is returned.

Parameters

X [array-like of shape (n_samples, n_features)]

Returns

C [ndarray of shape (n_samples,)]

predict_log_proba (X)
Return log of posterior probabilities of classification.

Parameters

X [array-like of shape (n_samples, n_features)] Array of samples/test vectors.

Returns

C [ndarray of shape (n_samples, n_classes)] Posterior log-probabilities of classification per class.

predict_proba (X)
Return posterior probabilities of classification.

Parameters

X [array-like of shape (n_samples, n_features)] Array of samples/test vectors.

Returns

C [ndarray of shape (n_samples, n_classes)] Posterior probabilities of classification per class.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.
Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.discriminant_analysis.QuadraticDiscriminantAnalysis

• Classifier comparison
• Linear and Quadratic Discriminant Analysis with covariance ellipsoid

7.10 sklearn.dummy: Dummy estimators

User guide: See the Metrics and scoring: quantifying the quality of predictions section for further details.

dummy.DummyClassifier(*[, strategy, ...])
DummyClassifier is a classifier that makes predictions using simple rules.
dummy.DummyRegressor(*[, strategy, ...])
DummyRegressor is a regressor that makes predictions using simple rules.

7.10.1 sklearn.dummy.DummyClassifier

class sklearn.dummy.DummyClassifier(*, strategy='prior', random_state=None, constant=None)
DummyClassifier is a classifier that makes predictions using simple rules.

This classifier is useful as a simple baseline to compare with other (real) classifiers. Do not use it for real problems.

Read more in the User Guide.

New in version 0.13.

Parameters

strategy ["stratified", "most_frequent", "prior", "uniform", "constant"], default="prior"]
Strategy to use to generate predictions.

• “stratified”: generates predictions by respecting the training set’s class distribution.
• “most_frequent”: always predicts the most frequent label in the training set.
• “prior”: always predicts the class that maximizes the class prior (like “most_frequent”) and predict_proba returns the class prior.
• “uniform”: generates predictions uniformly at random.
• “constant”: always predicts a constant label that is provided by the user. This is useful for metrics that evaluate a non-majority class

Changed in version 0.24: The default value of strategy has changed to “prior” in version 0.24.

random_state [int, RandomState instance or None, default=None] Controls the randomness to generate the predictions when strategy='stratified' or strategy='uniform'. Pass an int for reproducible output across multiple function calls. See Glossary.

constant [int or str or array-like of shape (n_outputs,)] The explicit constant as predicted by the “constant” strategy. This parameter is useful only for the “constant” strategy.

Attributes

classes_ [ndarray of shape (n_classes,) or list thereof] Class labels for each output.

n_classes_ [int or list of int] Number of label for each output.

class_prior_ [ndarray of shape (n_classes,) or list thereof] Probability of each class for each output.

n_outputs_ [int] Number of outputs.

sparse_output_ [bool] True if the array returned from predict is to be in sparse CSC format. Is automatically set to True if the input y is passed in sparse format.

Examples

```python
>>> import numpy as np
>>> from sklearn.dummy import DummyClassifier
>>> X = np.array([-1, 1, 1, 1])
>>> y = np.array([0, 1, 1, 1])
>>> dummy_clf = DummyClassifier(strategy="most_frequent")
>>> dummy_clf.fit(X, y)
DummyClassifier(strategy='most_frequent')
>>> dummy_clf.predict(X)
array([1, 1, 1, 1])
>>> dummy_clf.score(X, y)
0.75
```
**fit** (*X*, *y*, *sample_weight=None*)
Fit the random classifier.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Training data.
* y [array-like of shape (n_samples,) or (n_samples, n_outputs)] Target values.
* sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

self [object]

**get_params** (*deep=True*)
Get parameters for this estimator.

**Parameters**

* deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**predict** (*X*)
Perform classification on test vectors *X*.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Test data.

**Returns**

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] Predicted target values for *X*.

**predict_log_proba** (*X*)
Return log probability estimates for the test vectors *X*.

**Parameters**

* X [(array-like, object with finite length or shape)] Training data, requires length = n_samples

**Returns**

P [ndarray of shape (n_samples, n_classes) or list thereof] Returns the log probability of the sample for each class in the model, where classes are ordered arithmetically for each output.

**predict_proba** (*X*)
Return probability estimates for the test vectors *X*.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Test data.

**Returns**

P [ndarray of shape (n_samples, n_classes) or list thereof] Returns the probability of the sample for each class in the model, where classes are ordered arithmetically, for each output.
score($X, y, \text{sample_weight}=\text{None}$)

Returns the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

- $X$ [None or array-like of shape (n_samples, n_features)] Test samples. Passing None as test samples gives the same result as passing real test samples, since DummyClassifier operates independently of the sampled observations.
- $y$ [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for $X$.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- score [float] Mean accuracy of self.predict($X$) wrt. $y$.

set_params(**params)

Sets the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- **params [dict] Estimator parameters.

Returns


### 7.10.2 sklearn.dummy.DummyRegressor

**class** sklearn.dummy.DummyRegressor (*, strategy='mean', constant=None, quantile=None)

DummyRegressor is a regressor that makes predictions using simple rules.

This regressor is useful as a simple baseline to compare with other (real) regressors. Do not use it for real problems.

Read more in the User Guide.

New in version 0.13.

Parameters

- strategy ["mean", "median", "quantile", “constant”], default=”mean”] Strategy to use to generate predictions.
  - “mean”: always predicts the mean of the training set
  - “median”: always predicts the median of the training set
  - “quantile”: always predicts a specified quantile of the training set, provided with the quantile parameter.
  - “constant”: always predicts a constant value that is provided by the user.
- constant [int or float or array-like of shape (n_outputs,), default=None] The explicit constant as predicted by the “constant” strategy. This parameter is useful only for the “constant” strategy.
quantile  [float in [0.0, 1.0], default=None] The quantile to predict using the “quantile” strategy. A quantile of 0.5 corresponds to the median, while 0.0 to the minimum and 1.0 to the maximum.

Attributes

constant_  [ndarray of shape (1, n_outputs)] Mean or median or quantile of the training targets or constant value given by the user.

n_outputs_  [int] Number of outputs.

Examples

```python
>>> import numpy as np
>>> from sklearn.dummy import DummyRegressor

>>> X = np.array([1.0, 2.0, 3.0, 4.0])
>>> y = np.array([2.0, 3.0, 5.0, 10.0])

>>> dummy_regr = DummyRegressor(strategy="mean")
>>> dummy_regr.fit(X, y)
DummyRegressor()

>>> dummy_regr.predict(X)
array([5., 5., 5., 5.])

>>> dummy_regr.score(X, y)
0.0
```

Methods

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<td>Set the parameters of this estimator.</td>
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`fit(X, y, sample_weight=None)`
Fit the random regressor.

Parameters

- **X**  [array-like of shape (n_samples, n_features)] Training data.
- **y**  [array-like of shape (n_samples,) or (n_samples, n_outputs)] Target values.
- **sample_weight**  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **self**  [object]

`get_params(deep=True)`
Get parameters for this estimator.

Parameters

- **deep**  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
**params** [dict] Parameter names mapped to their values.

**predict** (*X*, *return_std*=*False*)
Perform classification on test vectors *X*.

**Parameters**

*X* [array-like of shape (*n_samples*, *n_features*)] Test data.

*return_std* [bool, default=False] Whether to return the standard deviation of posterior prediction. All zeros in this case.

**Returns**

*y* [array-like of shape (*n_samples*,) or (*n_samples*, *n_outputs*)) Predicted target values for *X*.

*y_std* [array-like of shape (*n_samples*,) or (*n_samples*, *n_outputs*)) Standard deviation of predictive distribution of query points.

**score** (*X*, *y*, *sample_weight*=*None*)
Returns the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - u/v)$, where $u$ is the residual sum of squares $\sum((y_{true} - y_{pred})^2)$ and $v$ is the total sum of squares $\sum((y_{true} - y_{true.mean})^2)$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of *y*, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

*X* [None or array-like of shape (*n_samples*, *n_features*)) Test samples. Passing None as test samples gives the same result as passing real test samples, since DummyRegressor operates independently of the sampled observations.

*y* [array-like of shape (*n_samples*,) or (*n_samples*, *n_outputs*)) True values for *X*.

*sample_weight* [array-like of shape (*n_samples*,), default=None] Sample weights.

**Returns**

*score* [float] $R^2$ of self.predict(*X*) wrt. *y*.

**set_params** (***params*)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

***params** [dict] Estimator parameters.

**Returns**

*self* [estimator instance] Estimator instance.
Examples using `sklearn.dummy.DummyRegressor`

- Poisson regression and non-normal loss

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**7.11 sklearn.ensemble: Ensemble Methods**

The `sklearn.ensemble` module includes ensemble-based methods for classification, regression and anomaly detection.

**User guide:** See the Ensemble methods section for further details.

```python
ensemble.AdaBoostClassifier(...)
```
An AdaBoost classifier.

```python
ensemble.AdaBoostRegressor(...)
```
An AdaBoost regressor.

```python
ensemble.BaggingClassifier(...)
```
A Bagging classifier.

```python
ensemble.BaggingRegressor(...)
```
A Bagging regressor.

```python
ensemble.ExtraTreesClassifier(...)
```
An extra-trees classifier.

```python
ensemble.ExtraTreesRegressor(...)
```
An extra-trees regressor.

```python
ensemble.GradientBoostingClassifier(*[, ...])
```
Gradient Boosting for classification.

```python
ensemble.GradientBoostingRegressor(*[, ...])
```
Gradient Boosting for regression.

```python
ensemble.IsolationForest(*[, n_estimators, ...])
```
Isolation Forest Algorithm.

```python
ensemble.RandomForestClassifier(...)
```
A random forest classifier.

```python
ensemble.RandomForestRegressor(...)
```
A random forest regressor.

```python
ensemble.RandomTreesEmbedding(...)
```
An ensemble of totally random trees.

```python
ensemble.StackingClassifier(estimators[, ...])
```
Stack of estimators with a final classifier.

```python
ensemble.StackingRegressor(estimators[, ...])
```
Stack of estimators with a final regressor.

```python
ensemble.VotingClassifier(estimators[, ...])
```
Soft Voting/Majority Rule classifier for unfitted estimators.

```python
ensemble.VotingRegressor(estimators[, ...])
```
Prediction voting regressor for unfitted estimators.

```python
ensemble.HistGradientBoostingRegressor(*[, ...])
```
Rotation forest based on gradient boosting.

```python
ensemble.HistGradientBoostingClassifier(*[, ...])
```
Histogram-based Gradient Boosting Classification Tree.
```
7.11.1 sklearn.ensemble.AdaBoostClassifier

class sklearn.ensemble.AdaBoostClassifier (base_estimator=None, *, n_estimators=50, learning_rate=1.0, algorithm='SAMME.R', random_state=None)

An AdaBoost classifier.

An AdaBoost [1] classifier is a meta-estimator that begins by fitting a classifier on the original dataset and then fits additional copies of the classifier on the same dataset but where the weights of incorrectly classified instances are adjusted such that subsequent classifiers focus more on difficult cases.

This class implements the algorithm known as AdaBoost-SAMME [2].

Read more in the User Guide.

New in version 0.14.

Parameters

base_estimator [object, default=None] The base estimator from which the boosted ensemble is built. Support for sample weighting is required, as well as proper classes_ and n_classes_ attributes. If None, then the base estimator is DecisionTreeClassifier initialized with max_depth=1.

n_estimators [int, default=50] The maximum number of estimators at which boosting is terminated. In case of perfect fit, the learning procedure is stopped early.

learning_rate [float, default=1.] Learning rate shrinks the contribution of each classifier by learning_rate. There is a trade-off between learning_rate and n_estimators.

algorithm ["SAMME", "SAMME.R"], default="SAMME.R"] If ‘SAMME.R’ then use the SAMME.R real boosting algorithm. base_estimator must support calculation of class probabilities. If ‘SAMME’ then use the SAMME discrete boosting algorithm. The SAMME.R algorithm typically converges faster than SAMME, achieving a lower test error with fewer boosting iterations.

random_state [int, RandomState instance or None, default=None] Controls the random seed given at each base_estimator at each boosting iteration. Thus, it is only used when base_estimator exposes a random_state. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

base_estimator_ [estimator] The base estimator from which the ensemble is grown.
estimators_ [list of classifiers] The collection of fitted sub-estimators.
classes_ [ndarray of shape (n_classes,)] The classes labels.
n_classes_ [int] The number of classes.
estimator_weights_ [ndarray of floats] Weights for each estimator in the boosted ensemble.
estimator_errors_ [ndarray of floats] Classification error for each estimator in the boosted ensemble.

feature_importances_ [ndarray of shape (n_features,)] The impurity-based feature importances.

See also:
**AdaBoostRegressor** An AdaBoost regressor that begins by fitting a regressor on the original dataset and then fits additional copies of the regressor on the same dataset but where the weights of instances are adjusted according to the error of the current prediction.

**GradientBoostingClassifier** GB builds an additive model in a forward stage-wise fashion. Regression trees are fit on the negative gradient of the binomial or multinomial deviance loss function. Binary classification is a special case where only a single regression tree is induced.

**sklearn.tree.DecisionTreeClassifier** A non-parametric supervised learning method used for classification. Creates a model that predicts the value of a target variable by learning simple decision rules inferred from the data features.

References

[1], [2]

Examples

```python
>>> from sklearn.ensemble import AdaBoostClassifier
>>> from sklearn.datasets import make_classification
>>> X, y = make_classification(n_samples=1000, n_features=4,
...    n_informative=2, n_redundant=0,
...    random_state=0, shuffle=False)
>>> clf = AdaBoostClassifier(n_estimators=100, random_state=0)
>>> clf.fit(X, y)
AdaBoostClassifier(n_estimators=100, random_state=0)
>>> clf.predict([[0, 0, 0, 0]])
array([1])
>>> clf.score(X, y)
0.983...
```

Methods

- `decision_function(X)` Compute the decision function of X.
- `fit(X, y[, sample_weight])` Build a boosted classifier from the training set (X, y).
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict classes for X.
- `predict_log_proba(X)` Predict class log-probabilities for X.
- `predict_proba(X)` Predict class probabilities for X.
- `score(X, y[, sample_weight])` Return the mean accuracy on the given test data and labels.
- `set_params(**params)` Set the parameters of this estimator.
- `staged_decision_function(X)` Compute decision function of X for each boosting iteration.
- `staged_predict(X)` Return staged predictions for X.
- `staged_predict_proba(X)` Predict class probabilities for X.
- `staged_score(X, y[, sample_weight])` Return staged scores for X, y.

```
>>> decision_function(X)
Compute the decision function of X.
```

Parameters
X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

Returns

score  [ndarray of shape of (n_samples, k)] The decision function of the input samples. The order of outputs is the same of that of the classes_ attribute. Binary classification is a special cases with k == 1, otherwise k==n_classes. For binary classification, values closer to -1 or 1 mean more like the first or second class in classes_, respectively.

property feature_importances_

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_  [ndarray of shape (n_features,)] The feature importances.

fit (X, y, sample_weight=None)

Build a boosted classifier from the training set (X, y).

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

y  [array-like of shape (n_samples,)] The target values (class labels).

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights. If None, the sample weights are initialized to 1 / n_samples.

Returns

self  [object] Fitted estimator.

get_params (deep=True)

Get parameters for this estimator.

Parameters

depth  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

predict (X)

Predict classes for X.

The predicted class of an input sample is computed as the weighted mean prediction of the classifiers in the ensemble.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.
Returns

\( y \) [ndarray of shape (n_samples,)] The predicted classes.

**predict_log_proba** \((X)\)

Predict class log-probabilities for \(X\).

The predicted class log-probabilities of an input sample is computed as the weighted mean predicted class log-probabilities of the classifiers in the ensemble.

**Parameters**

\( X \) [(array-like, sparse matrix) of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

**Returns**

\( p \) [ndarray of shape (n_samples, n_classes)] The class probabilities of the input samples. The order of outputs is the same of that of the `classes_` attribute.

**predict_proba** \((X)\)

Predict class probabilities for \(X\).

The predicted class probabilities of an input sample is computed as the weighted mean predicted class probabilities of the classifiers in the ensemble.

**Parameters**

\( X \) [(array-like, sparse matrix) of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

**Returns**

\( p \) [ndarray of shape (n_samples, n_classes)] The class probabilities of the input samples. The order of outputs is the same of that of the `classes_` attribute.

**score** \((X, y, sample_weight=None)\)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

\( X \) [array-like of shape (n_samples, n_features)] Test samples.

\( y \) [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for \(X\).

\( sample_weight \) [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

\( score \) [float] Mean accuracy of `self.predict(X)` wrt. \( y \).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.
Returns

self  [estimator instance] Estimator instance.

staged_decision_function (X)
Compute decision function of X for each boosting iteration.

This method allows monitoring (i.e. determine error on testing set) after each boosting iteration.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

Yields

cscore  [generator of ndarray of shape (n_samples, k)] The decision function of the input samples. The order of outputs is the same of that of the classes_ attribute. Binary classification is a special cases with k == 1, otherwise k==n_classes. For binary classification, values closer to -1 or 1 mean more like the first or second class in classes_, respectively.

staged_predict (X)
Return staged predictions for X.

The predicted class of an input sample is computed as the weighted mean prediction of the classifiers in the ensemble.

This generator method yields the ensemble prediction after each iteration of boosting and therefore allows monitoring, such as to determine the prediction on a test set after each boost.

Parameters

X  [array-like of shape (n_samples, n_features)] The input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

Yields

y  [generator of ndarray of shape (n_samples,)] The predicted classes.

staged_predict_proba (X)
Predict class probabilities for X.

The predicted class probabilities of an input sample is computed as the weighted mean predicted class probabilities of the classifiers in the ensemble.

This generator method yields the ensemble predicted class probabilities after each iteration of boosting and therefore allows monitoring, such as to determine the predicted class probabilities on a test set after each boost.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

Yields

p  [generator of ndarray of shape (n_samples,)] The class probabilities of the input samples. The order of outputs is the same of that of the classes_ attribute.

staged_score (X, y, sample_weight=None)
Return staged scores for X, y.
This generator method yields the ensemble score after each iteration of boosting and therefore allows monitoring, such as to determine the score on a test set after each boost.

**Parameters**

- **X** 
  
  ([array-like, sparse matrix] of shape (n_samples, n_features)) The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

- **y** 
  
  ([array-like of shape (n_samples,))] Labels for X.

- **sample_weight** 
  
  ([array-like of shape (n_samples,), default=None]) Sample weights.

**Yields**

- **z** 
  
  ([float])

**Examples using sklearn.ensemble.AdaBoostClassifier**

- Classifier comparison
- Two-class AdaBoost
- Multi-class AdaBoosted Decision Trees
- Discrete versus Real AdaBoost
- Plot the decision surfaces of ensembles of trees on the iris dataset

### 7.11.2 sklearn.ensemble.AdaBoostRegressor

**class** sklearn.ensemble.AdaBoostRegressor (base_estimator=None, *, n_estimators=50, learning_rate=1.0, loss='linear', random_state=None)

An AdaBoost regressor.

An AdaBoost [1] regressor is a meta-estimator that begins by fitting a regressor on the original dataset and then fits additional copies of the regressor on the same dataset but where the weights of instances are adjusted according to the error of the current prediction. As such, subsequent regressors focus more on difficult cases.

This class implements the algorithm known as AdaBoost.R2 [2].

Read more in the User Guide.

New in version 0.14.

**Parameters**

- **base_estimator** 
  
  ([object, default=None]) The base estimator from which the boosted ensemble is built. If None, then the base estimator is DecisionTreeRegressor initialized with max_depth=3.

- **n_estimators** 
  
  ([int, default=50]) The maximum number of estimators at which boosting is terminated. In case of perfect fit, the learning procedure is stopped early.

- **learning_rate** 
  
  ([float, default=1.0]) Learning rate shrinks the contribution of each regressor by learning_rate. There is a trade-off between learning_rate and n_estimators.

- **loss** 
  
  ([‘linear’, ‘square’, ‘exponential’], default=’linear’) The loss function to use when updating the weights after each boosting iteration.
random_state [int, RandomState instance or None, default=None] Controls the random seed given at each base_estimator at each boosting iteration. Thus, it is only used when base_estimator exposes a random_state. In addition, it controls the bootstrap of the weights used to train the base_estimator at each boosting iteration. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

base_estimator_ [estimator] The base estimator from which the ensemble is grown.
estimators_ [list of classifiers] The collection of fitted sub-estimators.
estimator_weights_ [ndarray of floats] Weights for each estimator in the boosted ensemble.
estimator_errors_ [ndarray of floats] Regression error for each estimator in the boosted ensemble.

feature_importances_ [ndarray of shape (n_features,)] The impurity-based feature importances.

See also:

AdaBoostClassifier, GradientBoostingRegressor

sklearn.tree.DecisionTreeRegressor

References

[1], [2]

Examples

```python
>>> from sklearn.ensemble import AdaBoostRegressor
>>> from sklearn.datasets import make_regression
>>> X, y = make_regression(n_features=4, n_informative=2, ...
... random_state=0, shuffle=False)
>>> regr = AdaBoostRegressor(random_state=0, n_estimators=100)
>>> regr.fit(X, y)
AdaBoostRegressor(n_estimators=100, random_state=0)
>>> regr.predict([[0, 0, 0, 0]])
array([4.7972...])
>>> regr.score(X, y)
0.9771...
```

Methods

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<tr>
<td>fit(X, y[, sample_weight])</td>
<td>Build a boosted regressor from the training set (X, y).</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict regression value for X.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>staged_predict(X)</td>
<td>Return staged predictions for X.</td>
</tr>
</tbody>
</table>

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| staged_score(X, y[, sample_weight]) | Return staged scores for X, y. |

**property** feature_importances_

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See `sklearn.inspection.permutation_importance` as an alternative.

**Returns**

- **feature_importances_**  [ndarray of shape (n_features,)] The feature importances.

**fit** (X, y, sample_weight=None)

Build a boosted regressor from the training set (X, y).

**Parameters**

- X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.
- y  [array-like of shape (n_samples,)] The target values (real numbers).
- sample_weight  [array-like of shape (n_samples,), default=None] Sample weights. If None, the sample weights are initialized to 1 / n_samples.

**Returns**

- self  [object]

**get_params** (deep=True)

Get parameters for this estimator.

**Parameters**

- deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params  [dict] Parameter names mapped to their values.

**predict** (X)

Predict regression value for X.

The predicted regression value of an input sample is computed as the weighted median prediction of the classifiers in the ensemble.

**Parameters**

- X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.

**Returns**

- y  [ndarray of shape (n_samples,)] The predicted regression values.

**score** (X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{\text{true}} - y_{\text{pred}})^2).\text{sum()}$ and $v$ is the total sum of squares $((y_{\text{true}} - y_{\text{true}}.\text{mean()}\)^2).\text{sum()}$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt. y.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params(**params)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**staged_predict**(X)

Return staged predictions for X.

The predicted regression value of an input sample is computed as the weighted median prediction of the classifiers in the ensemble.

This generator method yields the ensemble prediction after each iteration of boosting and therefore allows monitoring, such as to determine the prediction on a test set after each boost.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples.

**Yields**

- **y** [generator of ndarray of shape (n_samples,)] The predicted regression values.

**staged_score**(X, y, sample_weight=None)

Return staged scores for X, y.

This generator method yields the ensemble score after each iteration of boosting and therefore allows monitoring, such as to determine the score on a test set after each boost.
Parameters

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] The training input samples. Sparse matrix can be CSC, CSR, COO, DOK, or LIL. COO, DOK, and LIL are converted to CSR.
- **y** [array-like of shape (n_samples,)] Labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Yields

- **z** [float]

Examples using sklearn.ensemble.AdaBoostRegressor

- Decision Tree Regression with AdaBoost

7.11.3 sklearn.ensemble.BaggingClassifier

class sklearn.ensemble.BaggingClassifier(base_estimator=None, n_estimators=10, *, max_samples=1.0, max_features=1.0, bootstrap=True, bootstrap_features=False, oob_score=False, warm_start=False, n_jobs=None, random_state=None, verbose=0)

A Bagging classifier.

A Bagging classifier is an ensemble meta-estimator that fits base classifiers each on random subsets of the original dataset and then aggregate their individual predictions (either by voting or by averaging) to form a final prediction. Such a meta-estimator can typically be used as a way to reduce the variance of a black-box estimator (e.g., a decision tree), by introducing randomization into its construction procedure and then making an ensemble out of it.

This algorithm encompasses several works from the literature. When random subsets of the dataset are drawn as random subsets of the samples, then this algorithm is known as Pasting [1]. If samples are drawn with replacement, then the method is known as Bagging [2]. When random subsets of the dataset are drawn as random subsets of the features, then the method is known as Random Subspaces [3]. Finally, when base estimators are built on subsets of both samples and features, then the method is known as Random Patches [4].

Read more in the User Guide.

New in version 0.15.

Parameters

- **base_estimator** [object, default=None] The base estimator to fit on random subsets of the dataset. If None, then the base estimator is a DecisionTreeClassifier.
- **n_estimators** [int, default=10] The number of base estimators in the ensemble.
- **max_samples** [int or float, default=1.0] The number of samples to draw from X to train each base estimator (with replacement by default, see bootstrap for more details).
  - If int, then draw max_samples samples.
  - If float, then draw max_samples * X.shape[0] samples.
- **max_features** [int or float, default=1.0] The number of features to draw from X to train each base estimator (without replacement by default, see bootstrap_features for more details).
• If int, then draw \texttt{max_features} features.
• If float, then draw \texttt{max_features} \times X.shape[1] features.

\texttt{bootstrap} [bool, default=True] Whether samples are drawn with replacement. If False, sampling without replacement is performed.

\texttt{bootstrap_features} [bool, default=False] Whether features are drawn with replacement.

\texttt{oob_score} [bool, default=False] Whether to use out-of-bag samples to estimate the generalization error.

\texttt{warm_start} [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new ensemble. See the Glossary.

New in version 0.17: \texttt{warm_start} constructor parameter.

\texttt{n_jobs} [int, default=None] The number of jobs to run in parallel for both \texttt{fit} and \texttt{predict}. None means 1 unless in a \texttt{joblib.parallel_backend} context. -1 means using all processors. See Glossary for more details.

\texttt{random_state} [int, RandomState instance or None, default=None] Controls the random resampling of the original dataset (sample wise and feature wise). If the base estimator accepts a \texttt{random_state} attribute, a different seed is generated for each instance in the ensemble. Pass an int for reproducible output across multiple function calls. See Glossary.

\texttt{verbose} [int, default=0] Controls the verbosity when fitting and predicting.

Attributes

\texttt{base_estimator}_ [estimator] The base estimator from which the ensemble is grown.

\texttt{n_features}_ [int] The number of features when \texttt{fit} is performed.

\texttt{estimators}_ [list of estimators] The collection of fitted base estimators.

\texttt{estimators_samples}_ [list of arrays] The subset of drawn samples for each base estimator.

\texttt{estimators_features}_ [list of arrays] The subset of drawn features for each base estimator.

\texttt{classes}_ [ndarray of shape (n_classes,)] The classes labels.

\texttt{n_classes}_ [int or list] The number of classes.

\texttt{oob_score}_ [float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when \texttt{oob_score} is True.

\texttt{oob_decision_function}_ [ndarray of shape (n_samples, n_classes)] Decision function computed with out-of-bag estimate on the training set. If \texttt{n_estimators} is small it might be possible that a data point was never left out during the bootstrap. In this case, \texttt{oob_decision_function} might contain NaN. This attribute exists only when \texttt{oob_score} is True.
References

[1], [2], [3], [4]

Examples

```python
>>> from sklearn.svm import SVC
>>> from sklearn.ensemble import BaggingClassifier
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_samples=100, n_features=4,
...                            n_informative=2, n_redundant=0,
...                            random_state=0, shuffle=False)
>>> clf = BaggingClassifier(base_estimator=SVC(),
...                         n_estimators=10, random_state=0).fit(X, y)
>>> clf.predict([[0, 0, 0, 0]])
array([1])
```

Methods

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<td><code>decision_function(X)</code></td>
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<td><code>fit(X, y[, sample_weight])</code></td>
<td>Build a Bagging ensemble of estimators from the training</td>
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<td><code>predict_proba(X)</code></td>
<td>Predict class probabilities for X.</td>
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<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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**decision_function(X)**

Average of the decision functions of the base classifiers.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

**Returns**

- **score** (ndarray of shape (n_samples, k)) The decision function of the input samples. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`. Regression and binary classification are special cases with k == 1, otherwise k==n_classes.

**property estimators_samples_**

The subset of drawn samples for each base estimator.

Returns a dynamically generated list of indices identifying the samples used for fitting each member of the ensemble, i.e., the in-bag samples.

Note: the list is re-created at each call to the property in order to reduce the object memory footprint by not storing the sampling data. Thus fetching the property may be slower than expected.
**fit** *(X, y, sample_weight=None)*

Build a Bagging ensemble of estimators from the training set *(X, y)*.

**Parameters**

- **X** *[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.
- **y** *[array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).
- **sample_weight** *[array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if the base estimator supports sample weighting.

**Returns**

- **self** *[object]*

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** *[bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** *[dict] Parameter names mapped to their values.*

**predict** *(X)*

Predict class for X.

The predicted class of an input sample is computed as the class with the highest mean predicted probability. If base estimators do not implement a *predict_proba* method, then it resorts to voting.

**Parameters**

- **X** *[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

**Returns**

- **y** *[ndarray of shape (n_samples,)] The predicted classes.*

**predict_log_proba** *(X)*

Predict class log-probabilities for X.

The predicted class log-probabilities of an input sample is computed as the log of the mean predicted class probabilities of the base estimators in the ensemble.

**Parameters**

- **X** *[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

**Returns**

- **p** *[ndarray of shape (n_samples, n_classes)] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute *classes_*.
**predict_proba** *(X)*

Predict class probabilities for X.

The predicted class probabilities of an input sample is computed as the mean predicted class probabilities of the base estimators in the ensemble. If base estimators do not implement a `predict_proba` method, then it resorts to voting and the predicted class probabilities of an input sample represents the proportion of estimators predicting each class.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

**Returns**

- **p** [ndarray of shape (n_samples, n_classes)] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute `classes_`.

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] Mean accuracy of `self.predict(X)` wrt. y.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

### 7.11.4 sklearn.ensemble.BaggingRegressor

**class sklearn.ensemble.BaggingRegressor** *(base_estimator=None, n_estimators=10, *, max_samples=1.0, max_features=1.0, bootstrap=True, bootstrap_features=False, oob_score=False, warm_start=False, n_jobs=None, random_state=None, verbose=0)*

A Bagging regressor.

A Bagging regressor is an ensemble meta-estimator that fits base regressors each on random subsets of the original dataset and then aggregate their individual predictions (either by voting or by averaging) to form a final prediction. Such a meta-estimator can typically be used as a way to reduce the variance of a black-box
estimator (e.g., a decision tree), by introducing randomization into its construction procedure and then making an ensemble out of it.

This algorithm encompasses several works from the literature. When random subsets of the dataset are drawn as random subsets of the samples, then this algorithm is known as Pasting [1]. If samples are drawn with replacement, then the method is known as Bagging [2]. When random subsets of the dataset are drawn as random subsets of the features, then the method is known as Random Subspaces [3]. Finally, when base estimators are built on subsets of both samples and features, then the method is known as Random Patches [4].

Read more in the User Guide.

New in version 0.15.

Parameters

**base_estimator** [object, default=None] The base estimator to fit on random subsets of the dataset. If None, then the base estimator is a DecisionTreeRegressor.

**n_estimators** [int, default=10] The number of base estimators in the ensemble.

**max_samples** [int or float, default=1.0] The number of samples to draw from X to train each base estimator (with replacement by default, see bootstrap for more details).

- If int, then draw max_samples samples.
- If float, then draw max_samples * X.shape[0] samples.

**max_features** [int or float, default=1.0] The number of features to draw from X to train each base estimator (without replacement by default, see bootstrap_features for more details).

- If int, then draw max_features features.
- If float, then draw max_features * X.shape[1] features.

**bootstrap** [bool, default=True] Whether samples are drawn with replacement. If False, sampling without replacement is performed.

**bootstrap_features** [bool, default=False] Whether features are drawn with replacement.

**oob_score** [bool, default=False] Whether to use out-of-bag samples to estimate the generalization error.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new ensemble. See the Glossary.

**n_jobs** [int, default=None] The number of jobs to run in parallel for both fit and predict. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance or None, default=None] Controls the random resampling of the original dataset (sample wise and feature wise). If the base estimator accepts a random_state attribute, a different seed is generated for each instance in the ensemble. Pass an int for reproducible output across multiple function calls. See Glossary.

**verbose** [int, default=0] Controls the verbosity when fitting and predicting.

Attributes

**base_estimator_** [estimator] The base estimator from which the ensemble is grown.

**n_features_** [int] The number of features when fit is performed.

**estimators_** [list of estimators] The collection of fitted sub-estimators.
estimators_samples_ [list of arrays] The subset of drawn samples for each base estimator.
estimators_features_[list of arrays] The subset of drawn features for each base estimator.
oob_score_[float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when oob_score is True.
oob_prediction_[ndarray of shape (n_samples,) Prediction computed with out-of-bag estimate on the training set. If n_estimators is small it might be possible that a data point was never left out during the bootstrap. In this case, oob_prediction_ might contain NaN. This attribute exists only when oob_score is True.

References
[1], [2], [3], [4]

Examples

```python
>>> from sklearn.svm import SVR
>>> from sklearn.ensemble import BaggingRegressor
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_samples=100, n_features=4,
... n_informative=2, n_targets=1,
... random_state=0, shuffle=False)

>>> regr = BaggingRegressor(base_estimator=SVR(),
... n_estimators=10, random_state=0).fit(X, y)

>>> regr.predict([[0, 0, 0, 0]])
array([-2.8720...])
```

Methods

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<td>fit(X, y[, sample_weight])</td>
<td>Build a Bagging ensemble of estimators from the training</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict regression target for X.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination R^2 of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

property estimators_samples_
The subset of drawn samples for each base estimator.

Returns a dynamically generated list of indices identifying the samples used for fitting each member of the ensemble, i.e., the in-bag samples.

Note: the list is re-created at each call to the property in order to reduce the object memory footprint by not storing the sampling data. Thus fetching the property may be slower than expected.

```python
fit (X, y, sample_weight=None)
```

Build a Bagging ensemble of estimators from the training set (X, y).

Parameters
X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

y  [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if the base estimator supports sample weighting.

Returns
self  [object]

get_params  (deep=True)
Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params  [dict] Parameter names mapped to their values.

predict  (X)
Predict regression target for X.

The predicted regression target of an input sample is computed as the mean predicted regression targets of the estimators in the ensemble.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Sparse matrices are accepted only if they are supported by the base estimator.

Returns
y  [ndarray of shape (n_samples,)] The predicted values.

score  (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as \(1 - \frac{\sum \text{(y_true - y_pred)}^2}{\sum \text{(y_true - y_true.mean())}^2}\). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X  [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns
score  [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using `sklearn.ensemble.BaggingRegressor`

• Single estimator versus bagging: bias-variance decomposition

7.11.5 `sklearn.ensemble.ExtraTreesClassifier`

class sklearn.ensemble.ExtraTreesClassifier (n_estimators=100, *, criterion='gini', max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_features='auto', max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, bootstrap=False, oob_score=False, n_jobs=None, random_state=None, verbose=0, warm_start=False, class_weight=None, ccp_alpha=0.0, max_samples=None)

An extra-trees classifier.

This class implements a meta estimator that fits a number of randomized decision trees (a.k.a. extra-trees) on various sub-samples of the dataset and uses averaging to improve the predictive accuracy and control over-fitting. Read more in the User Guide.

Parameters

n_estimators [int, default=100] The number of trees in the forest.

Changed in version 0.22: The default value of `n_estimators` changed from 10 to 100 in 0.22.

criterion ["gini", "entropy"], default="gini"] The function to measure the quality of a split. Supported criteria are “gini” for the Gini impurity and “entropy” for the information gain.

max_depth [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than `min_samples_split` samples.
**min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:

- If int, then consider `min_samples_split` as the minimum number.
- If float, then `min_samples_split` is a fraction and \( \text{ceil}(\text{min_samples_split} \times \text{n_samples}) \) are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

**min_samples_leaf** [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least `min_samples_leaf` training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

- If int, then consider `min_samples_leaf` as the minimum number.
- If float, then `min_samples_leaf` is a fraction and \( \text{ceil}(\text{min_samples_leaf} \times \text{n_samples}) \) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

**min_weight_fraction_leaf** [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when `sample_weight` is not provided.

**max_features** [{"auto", “sqrt”, “log2"}, int or float, default="auto"] The number of features to consider when looking for the best split:

- If int, then consider `max_features` features at each split.
- If float, then `max_features` is a fraction and \( \text{round}(\text{max_features} \times \text{n_features}) \) features are considered at each split.
- If “auto”, then `max_features`=sqrt\( (\text{n_features}) \).
- If “sqrt”, then `max_features`=sqrt\( (\text{n_features}) \).
- If “log2”, then `max_features`=log2\( (\text{n_features}) \).
- If None, then `max_features`=n_features.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than `max_features` features.

**max_leaf_nodes** [int, default=None] Grow trees with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

**min_impurity_decrease** [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times (\text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity})
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in the right child.

\( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if `sample_weight` is passed.

New in version 0.19.
**min_impurity_split** [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` has changed from 1e-7 to 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

**bootstrap** [bool, default=False] Whether bootstrap samples are used when building trees. If False, the whole dataset is used to build each tree.

**oob_score** [bool, default=False] Whether to use out-of-bag samples to estimate the generalization accuracy.

**n_jobs** [int, default=None] The number of jobs to run in parallel. `fit`, `predict`, `decision_path` and `apply` are all parallelized over the trees. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance or None, default=None] Controls 3 sources of randomness:

- the bootstrapping of the samples used when building trees (if `bootstrap=True`)
- the sampling of the features to consider when looking for the best split at each node (if `max_features < n_features`)
- the draw of the splits for each of the `max_features`

See Glossary for details.

**verbose** [int, default=0] Controls the verbosity when fitting and predicting.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See the Glossary.

**class_weight** [{“balanced”, “balanced_subsample”}, dict or list of dicts, default=None] Weights associated with classes in the form `{class_label: weight}`. If not given, all classes are supposed to have weight one. For multi-output problems, a list of dicts can be provided in the same order as the columns of y.

Note that for multioutput (including multilabel) weights should be defined for each class of every column in its own dict. For example, for four-class multilabel classification weights should be `[[0: 1, 1: 1], [0: 1, 1: 5], [0: 1, 1: 1], [0: 1, 1: 1]]` instead of `[[1:1], [2:5], [3:1], [4:1]]`.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as `n_samples / (n_classes * np.bincount(y))`

The “balanced_subsample” mode is the same as “balanced” except that weights are computed based on the bootstrap sample for every tree grown.

For multi-output, the weights of each column of y will be multiplied.

Note that these weights will be multiplied with `sample_weight` (passed through the fit method) if `sample_weight` is specified.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than `ccp_alpha` will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.
New in version 0.22.

**max_samples** [int or float, default=None] If bootstrap is True, the number of samples to draw from X to train each base estimator.

- If None (default), then draw $X.shape[0]$ samples.
- If int, then draw $max_samples$ samples.
- If float, then draw $max_samples \times X.shape[0]$ samples. Thus, $max_samples$ should be in the interval $(0, 1)$.

New in version 0.22.

**Attributes**

**base_estimator_** [ExtraTreesClassifier] The child estimator template used to create the collection of fitted sub-estimators.

**estimators_** [list of DecisionTreeClassifier] The collection of fitted sub-estimators.

**classes_** [ndarray of shape (n_classes,) or a list of such arrays] The classes labels (single output problem), or a list of arrays of class labels (multi-output problem).

**n_classes_** [int or list] The number of classes (single output problem), or a list containing the number of classes for each output (multi-output problem).

**feature_importances_** [ndarray of shape (n_features,)] The impurity-based feature importances.

**n_features_** [int] The number of features when fit is performed.

**n_outputs_** [int] The number of outputs when fit is performed.

**oob_score_** [float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when oob_score is True.

**oob_decision_function_** [ndarray of shape (n_samples, n_classes)] Decision function computed with out-of-bag estimate on the training set. If n_estimators is small it might be possible that a data point was never left out during the bootstrap. In this case, oob_decision_function_ might contain NaN. This attribute exists only when oob_score is True.

**See also:**

**sklearn.tree.ExtraTreeClassifier** Base classifier for this ensemble.

**RandomForestClassifier** Ensemble Classifier based on trees with optimal splits.

**Notes**

The default values for the parameters controlling the size of the trees (e.g. max_depth, min_samples_leaf, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.
References

[1]

Examples

```python
>>> from sklearn.ensemble import ExtraTreesClassifier
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_features=4, random_state=0)
>>> clf = ExtraTreesClassifier(n_estimators=100, random_state=0)
>>> clf.fit(X, y)
ExtraTreesClassifier(random_state=0)

>>> clf.predict([[0, 0, 0, 0]])
array([1])
```

Methods

- **apply** *(X)*
  Apply trees in the forest to X, return leaf indices.

- **decision_path** *(X)*
  Return the decision path in the forest.

- **fit** *(X, y[, sample_weight]*)
  Build a forest of trees from the training set (X, y).

- **get_params** *(deep)*
  Get parameters for this estimator.

- **predict** *(X)*
  Predict class for X.

- **predict_log_proba** *(X)*
  Predict class log-probabilities for X.

- **predict_proba** *(X)*
  Predict class probabilities for X.

- **score** *(X, y[, sample_weight]*)
  Return the mean accuracy on the given test data and labels.

- **set_params** *(**params]*)
  Set the parameters of this estimator.

**apply** *(X)*

Apply trees in the forest to X, return leaf indices.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features))
  The input samples. Internally, its dtype will be converted to `dtype=np.float32`. If a sparse matrix is provided, it will be converted into a sparse `csr_matrix`.

**Returns**

- **X_leaves** ([ndarray] of shape (n_samples, n_estimators))
  For each datapoint x in X and for each tree in the forest, return the index of the leaf x ends up in.

**decision_path** *(X)*

Return the decision path in the forest.

New in version 0.18.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features))
  The input samples. Internally, its dtype will be converted to `dtype=np.float32`. If a sparse matrix is provided, it will be converted into a sparse `csr_matrix`.

**Returns**

- **X_leaves** ([ndarray] of shape (n_samples, n_estimators))
  For each datapoint x in X and for each tree in the forest, return the index of the leaf x ends up in.
indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator matrix where non zero elements indicates that the samples goes through the nodes. The matrix is of CSR format.

n_nodes_ptr [ndarray of shape (n_estimators + 1,)] The columns from indicator[n_nodes_ptr[i]:n_nodes_ptr[i+1]] gives the indicator value for the i-th estimator.

property feature_importances_
The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

fit (X, y, sample_weight=None)
Build a forest of trees from the training set (X, y).

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The training input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csc_matrix.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Predict class for X.

The predicted class of an input sample is a vote by the trees in the forest, weighted by their probability estimates. That is, the predicted class is the one with highest mean probability estimate across the trees.

Parameters
X [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

y [ndarray of shape (n_samples,) or (n_samples, n_outputs)] The predicted classes.

predict_log_proba (X)
Predict class log-probabilities for X.

The predicted class log-probabilities of an input sample is computed as the log of the mean predicted class probabilities of the trees in the forest.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

p [ndarray of shape (n_samples, n_classes), or a list of n_outputs] such arrays if n_outputs > 1. The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

predict_proba (X)
Predict class probabilities for X.

The predicted class probabilities of an input sample are computed as the mean predicted class probabilities of the trees in the forest. The class probability of a single tree is the fraction of samples of the same class in a leaf.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

p [ndarray of shape (n_samples, n_classes), or a list of n_outputs] such arrays if n_outputs > 1. The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict (X) wrt. y.

set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.ensemble.ExtraTreesClassifier**

- Pixel importances with a parallel forest of trees
- Feature importances with forests of trees
- Hashing feature transformation using Totally Random Trees
- Plot the decision surfaces of ensembles of trees on the iris dataset

**7.11.6 sklearn.ensemble.ExtraTreesRegressor**

class sklearn.ensemble.ExtraTreesRegressor(n_estimators=100, *, criterion='mse', max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_features='auto', max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, bootstrap=False, oob_score=False, n_jobs=None, random_state=None, verbose=0, warm_start=False, ccp_alpha=0.0, max_samples=None)

An extra-trees regressor.

This class implements a meta estimator that fits a number of randomized decision trees (a.k.a. extra-trees) on various sub-samples of the dataset and uses averaging to improve the predictive accuracy and control over-fitting.

Read more in the User Guide.

**Parameters**

**n_estimators** [int, default=100] The number of trees in the forest.

Changed in version 0.22: The default value of `n_estimators` changed from 10 to 100 in 0.22.

**criterion** ["mse", "mae", default="mse"] The function to measure the quality of a split. Supported criteria are "mse" for the mean squared error, which is equal to variance reduction as feature selection criterion, and "mae" for the mean absolute error.

New in version 0.18: Mean Absolute Error (MAE) criterion.

**max_depth** [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than `min_samples_split` samples.

**min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:
• If int, then consider `min_samples_split` as the minimum number.

• If float, then `min_samples_split` is a fraction and `ceiling(min_samples_split * n_samples)` are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

`min_samples_leaf` [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least `min_samples_leaf` training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

• If int, then consider `min_samples_leaf` as the minimum number.

• If float, then `min_samples_leaf` is a fraction and `ceiling(min_samples_leaf * n_samples)` are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

`min_weight_fraction_leaf` [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when `sample_weight` is not provided.

`max_features` [“auto”, “sqrt”, “log2”, int or float, default=“auto”] The number of features to consider when looking for the best split:

• If int, then consider `max_features` features at each split.

• If float, then `max_features` is a fraction and `round(max_features * n_features)` features are considered at each split.

• If “auto”, then `max_features=n_features`.

• If “sqrt”, then `max_features=sqrt(n_features)`.

• If “log2”, then `max_features=log2(n_features)`.

• If None, then `max_features=n_features`.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than `max_features` features.

`max_leaf_nodes` [int, default=None] Grow trees with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

`min_impurity_decrease` [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity} \right)
\]

where `N` is the total number of samples, `N_t` is the number of samples at the current node, `N_{t,R}` is the number of samples in the right child, and `N_{t,L}` is the number of samples in the left child.

`N`, `N_t`, `N_{t,R}` and `N_{t,L}` all refer to the weighted sum, if `sample_weight` is passed.

New in version 0.19.

`min_impurity_split` [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.
Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

**bootstrap** [bool, default=False] Whether bootstrap samples are used when building trees. If False, the whole dataset is used to build each tree.

**oob_score** [bool, default=False] Whether to use out-of-bag samples to estimate the $R^2$ on unseen data.

**n_jobs** [int, default=None] The number of jobs to run in parallel. `fit`, `predict`, `decision_path` and `apply` are all parallelized over the trees. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance or None, default=None] Controls 3 sources of randomness:

- the bootstrapping of the samples used when building trees (if `bootstrap=True`)
- the sampling of the features to consider when looking for the best split at each node (if `max_features < n_features`)
- the draw of the splits for each of the `max_features`

See Glossary for details.

**verbose** [int, default=0] Controls the verbosity when fitting and predicting.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See the Glossary.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than `ccp_alpha` will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

**max_samples** [int or float, default=None] If bootstrap is True, the number of samples to draw from X to train each base estimator.

- If None (default), then draw $X.shape[0]$ samples.
- If int, then draw `max_samples` samples.
- If float, then draw $max_samples * X.shape[0]$ samples. Thus, `max_samples` should be in the interval (0, 1).

New in version 0.22.

### Attributes

- **base_estimator_** [ExtraTreeRegressor] The child estimator template used to create the collection of fitted sub-estimators.

- **estimators_** [list of DecisionTreeRegressor] The collection of fitted sub-estimators.

- **feature_importances_** [ndarray of shape (n_features,)] The impurity-based feature importances.

- **n_features_** [int] The number of features.
n_outputs_  [int] The number of outputs.

oob_score_  [float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when oob_score is True.

oob_prediction_  [ndarray of shape (n_samples,)] Prediction computed with out-of-bag estimate on the training set. This attribute exists only when oob_score is True.

See also:

sklearn.tree.ExtraTreeRegressor  Base estimator for this ensemble.
RandomForestRegressor  Ensemble regressor using trees with optimal splits.

Notes

The default values for the parameters controlling the size of the trees (e.g. max_depth, min_samples_leaf, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

References

[1]

Examples

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.ensemble import ExtraTreesRegressor

>>> X, y = load_diabetes(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(...
... X, y, random_state=0)
>>> reg = ExtraTreesRegressor(n_estimators=100, random_state=0).fit(...
... X_train, y_train)
>>> reg.score(X_test, y_test)
0.2708...
```

Methods

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apply (X)

Apply trees in the forest to X, return leaf indices.
Parameters

\(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

\(X_{\text{leaves}}\) [ndarray of shape (n_samples, n_estimators)] For each datapoint \(x\) in \(X\) and for each tree in the forest, return the index of the leaf \(x\) ends up in.

\texttt{decision\_path} \((X)\)

Return the decision path in the forest.

New in version 0.18.

Parameters

\(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

\(\text{indicator}\) [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator matrix where non zero elements indicates that the samples goes through the nodes. The matrix is of CSR format.

\(n\_nodes\_ptr\) [ndarray of shape (n_estimators + 1,)] The columns from indicator[n_nodes_ptr[i]:n_nodes_ptr[i+1]] gives the indicator value for the i-th estimator.

property \texttt{feature\_importances\_}

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See \texttt{sklearn.inspection.permutation\_importance} as an alternative.

Returns

\(\text{feature\_importances\_}\) [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

\texttt{fit} \((X, y, sample\_weight=None)\)

Build a forest of trees from the training set \((X, y)\).

Parameters

\(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csc_matrix.

\(y\) [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).

\(sample\_weight\) [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.
Returns

```python
self [object]
```

**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict** *(X)*
Predict regression target for X.

The predicted regression target of an input sample is computed as the mean predicted regression targets of the trees in the forest.

**Parameters**

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

**Returns**

- **y** [ndarray of shape (n_samples,) or (n_samples, n_outputs)] The predicted values.

**score** *(X, y, sample_weight=None)*
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of y, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params(**params)`
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using `sklearn.ensemble.ExtraTreesRegressor`

- Face completion with a multi-output estimators
- Imputing missing values with variants of IterativeImputer

7.11.7 `sklearn.ensemble.GradientBoostingClassifier`

class `sklearn.ensemble.GradientBoostingClassifier`(*, loss='deviance', learning_rate=0.1, n_estimators=100, subsample=1.0, criterion='friedman_mse', min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_depth=3, min_impurity_decrease=0.0, min_impurity_split=None, init=None, random_state=None, max_features=None, verbose=0, max_leaf_nodes=None, warm_start=False, validation_fraction=0.1, n_iter_no_change=None, tol=0.0001, ccp_alpha=0.0)

Gradient Boosting for classification.

GB builds an additive model in a forward stage-wise fashion; it allows for the optimization of arbitrary differentiable loss functions. In each stage `n_classes` regression trees are fit on the negative gradient of the binomial or multinomial deviance loss function. Binary classification is a special case where only a single regression tree is induced.

Read more in the User Guide.

Parameters
loss: [‘deviance’, ‘exponential’], default=’deviance’] The loss function to be optimized. ‘deviance’ refers to deviance (= logistic regression) for classification with probabilistic outputs. For loss ‘exponential’ gradient boosting recovers the AdaBoost algorithm.

learning_rate: [float, default=0.1] Learning rate shrinks the contribution of each tree by learning_rate. There is a trade-off between learning_rate and n_estimators.

n_estimators: [int, default=100] The number of boosting stages to perform. Gradient boosting is fairly robust to over-fitting so a large number usually results in better performance.

subsample: [float, default=1.0] The fraction of samples to be used for fitting the individual base learners. If smaller than 1.0 this results in Stochastic Gradient Boosting. subsample interacts with the parameter n_estimators. Choosing subsample < 1.0 leads to a reduction of variance and an increase in bias.

criterion: [‘friedman_mse’, ‘mse’, ‘mae’], default=’friedman_mse’] The function to measure the quality of a split. Supported criteria are ‘friedman_mse’ for the mean squared error with improvement score by Friedman, ‘mse’ for mean squared error, and ‘mae’ for the mean absolute error. The default value of ‘friedman_mse’ is generally the best as it can provide a better approximation in some cases.

New in version 0.18.

Deprecated since version 0.24: criterion='mae' is deprecated and will be removed in version 1.1 (renaming of 0.26). Use criterion='friedman_mse' or 'mse' instead, as trees should use a least-square criterion in Gradient Boosting.

min_samples_split: [int or float, default=2] The minimum number of samples required to split an internal node:

- If int, then consider min_samples_split as the minimum number.
- If float, then min_samples_split is a fraction and ceil(min_samples_split * n_samples) are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

min_samples_leaf: [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least min_samples_leaf training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

- If int, then consider min_samples_leaf as the minimum number.
- If float, then min_samples_leaf is a fraction and ceil(min_samples_leaf * n_samples) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

min_weight_fraction_leaf: [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

max_depth: [int, default=3] The maximum depth of the individual regression estimators. The maximum depth limits the number of nodes in the tree. Tune this parameter for best performance; the best value depends on the interaction of the input variables.

min_impurity_decrease: [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:
\[
\frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity} \right)
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in the right child.

\( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if \( \text{sample_weight} \) is passed.

New in version 0.19.

**min_impurity_split** [float, default=\( \text{None} \)] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` has changed from \( 1e^{-7} \) to \( 0 \) in 0.23 and it will be removed in 1.0 (renaming of \( 0.25 \)). Use `min_impurity_decrease` instead.

**init** [estimator or ‘zero’, default=\( \text{None} \)] An estimator object that is used to compute the initial predictions. `init` has to provide `fit` and `predict_proba`. If ‘zero’, the initial raw predictions are set to zero. By default, a `DummyEstimator` predicting the classes priors is used.

**random_state** [int, RandomState instance or \( \text{None} \), default=\( \text{None} \)] Controls the random seed given to each Tree estimator at each boosting iteration. In addition, it controls the random permutation of the features at each split (see Notes for more details). It also controls the random splitting of the training data to obtain a validation set if `n_iter_no_change` is not None. Pass an int for reproducible output across multiple function calls. See Glossary.

**max_features** [{‘auto’, ‘sqrt’, ‘log2’}, int or float, default=\( \text{None} \)] The number of features to consider when looking for the best split:

- If int, then consider `max_features` features at each split.
- If float, then `max_features` is a fraction and \( \text{int(max_features} \times n_{\text{features}}) \) features are considered at each split.
- If ‘auto’, then `max_features=sqrt(n_{\text{features}})`.
- If ‘sqrt’, then `max_features=sqrt(n_{\text{features}})`.
- If ‘log2’, then `max_features=log2(n_{\text{features}})`.
- If None, then `max_features=n_{\text{features}}`.

Choosing `max_features < n_{\text{features}}` leads to a reduction of variance and an increase in bias.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than `max_features` features.

**verbose** [int, default=0] Enable verbose output. If 1 then it prints progress and performance once in a while (the more trees the lower the frequency). If greater than 1 then it prints progress and performance for every tree.

**max_leaf_nodes** [int, default=\( \text{None} \)] Grow trees with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.
warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just erase the previous solution. See the Glossary.

validation_fraction [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if n_iter_no_change is set to an integer.

New in version 0.20.

n_iter_no_change [int, default=None] n_iter_no_change is used to decide if early stopping will be used to terminate training when validation score is not improving. By default it is set to None to disable early stopping. If set to a number, it will set aside validation_fraction size of the training data as validation and terminate training when validation score is not improving in all of the previous n_iter_no_change numbers of iterations. The split is stratified.

New in version 0.20.

tol [float, default=1e-4] Tolerance for the early stopping. When the loss is not improving by at least tol for n_iter_no_change iterations (if set to a number), the training stops.

New in version 0.20.

ccp_alpha [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than ccp_alpha will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

Attributes

n_estimators_ [int] The number of estimators as selected by early stopping (if n_iter_no_change is specified). Otherwise it is set to n_estimators.

New in version 0.20.

feature_importances_ [ndarray of shape (n_features,)] The impurity-based feature importances.

oob_improvement_ [ndarray of shape (n_estimators,)] The improvement in loss (= deviance) on the out-of-bag samples relative to the previous iteration. oob_improvement_[0] is the improvement in loss of the first stage over the init estimator. Only available if subsample < 1.0

train_score_ [ndarray of shape (n_estimators,)] The i-th score train_score_[i] is the deviance (= loss) of the model at iteration i on the in-bag sample. If subsample == 1 this is the deviance on the training data.


init_ [estimator] The estimator that provides the initial predictions. Set via the init argument or loss.init_estimator.

estimators_ [ndarray of DecisionTreeRegressor of shape (n_estimators, loss_.K)] The collection of fitted sub-estimators. loss_.K is 1 for binary classification, otherwise n_classes.

classes_ [ndarray of shape (n_classes,)] The classes labels.

n_features_ [int] The number of data features.

n_classes_ [int] The number of classes.
max_features_  [int] The inferred value of max_features.

See also:

**HistGradientBoostingClassifier**  Histogram-based Gradient Boosting Classification Tree.

**sklearn.tree.DecisionTreeClassifier**  A decision tree classifier.

**RandomForestClassifier**  A meta-estimator that fits a number of decision tree classifiers on various sub-samples of the dataset and uses averaging to improve the predictive accuracy and control over-fitting.

**AdaBoostClassifier**  A meta-estimator that begins by fitting a classifier on the original dataset and then fits additional copies of the classifier on the same dataset where the weights of incorrectly classified instances are adjusted such that subsequent classifiers focus more on difficult cases.

Notes

The features are always randomly permuted at each split. Therefore, the best found split may vary, even with the same training data and max_features=n_features, if the improvement of the criterion is identical for several splits enumerated during the search of the best split. To obtain a deterministic behaviour during fitting, random_state has to be fixed.

References


J. Friedman, Stochastic Gradient Boosting, 1999


Examples

The following example shows how to fit a gradient boosting classifier with 100 decision stumps as weak learners.

```python
>>> from sklearn.datasets import make_hastie_10_2
>>> from sklearn.ensemble import GradientBoostingClassifier

>>> X, y = make_hastie_10_2(random_state=0)
>>> X_train, X_test = X[:2000], X[2000:]
>>> y_train, y_test = y[:2000], y[2000:]

>>> clf = GradientBoostingClassifier(n_estimators=100, learning_rate=1.0, ...
... max_depth=1, random_state=0).fit(X_train, y_train)
>>> clf.score(X_test, y_test)
0.913...
```
Methods

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**apply (X)**

Apply trees in the ensemble to X, return leaf indices.

New in version 0.17.

**Parameters**

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted to a sparse csr_matrix.

**Returns**

X_leaves [array-like of shape (n_samples, n_estimators, n_classes)] For each datapoint x in X and for each tree in the ensemble, return the index of the leaf x ends up in each estimator. In the case of binary classification n_classes is 1.

**decision_function (X)**

Compute the decision function of X.

**Parameters**

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

score [ndarray of shape (n_samples, n_classes) or (n_samples,)] The decision function of the input samples, which corresponds to the raw values predicted from the trees of the ensemble. The order of the classes corresponds to that in the attribute classes_. Regression and binary classification produce an array of shape (n_samples,).

**property feature_importances_**

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

**Returns**
**feature_importances_**  [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

**fit** (X, y, sample_weight=None, monitor=None)
Fit the gradient boosting model.

**Parameters**

X  [(array-like, sparse matrix) of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

y  [array-like of shape (n_samples,)] Target values (strings or integers in classification, real numbers in regression) For classification, labels must correspond to classes.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

monitor  [callable, default=None] The monitor is called after each iteration with the current iteration, a reference to the estimator and the local variables of _fit_stages as keyword arguments callable(i, self, locals()). If the callable returns True the fitting procedure is stopped. The monitor can be used for various things such as computing held-out estimates, early stopping, model introspect, and snapshotting.

**Returns**

self  [object]

**get_params** (deep=True)
Get parameters for this estimator.

**Parameters**

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params  [dict] Parameter names mapped to their values.

**predict** (X)
Predict class for X.

**Parameters**

X  [(array-like, sparse matrix) of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

y  [ndarray of shape (n_samples,)] The predicted values.

**predict_log_proba** (X)
Predict class log-probabilities for X.

**Parameters**
X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

Returns

p [ndarray of shape (n_samples, n_classes)] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_

Raises

AttributeError If the loss does not support probabilities.

predict_proba(X)

Predict class probabilities for X.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

Returns

p [ndarray of shape (n_samples, n_classes)] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_

Raises

AttributeError If the loss does not support probabilities.

score(X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.

y [array-like of shape (n_samples, ) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

staged_decision_function(X)

Compute decision function of X for each iteration.
This method allows monitoring (i.e. determine error on testing set) after each stage.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **score** [generator of ndarray of shape (n_samples, k)] The decision function of the input samples, which corresponds to the raw values predicted from the trees of the ensemble. The classes corresponds to that in the attribute classes_. Regression and binary classification are special cases with k == 1, otherwise k==n_classes.

**staged_predict** (X)

Predict class at each stage for X.

This method allows monitoring (i.e. determine error on testing set) after each stage.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **y** [generator of ndarray of shape (n_samples,)] The predicted value of the input samples.

**staged_predict_proba** (X)

Predict class probabilities at each stage for X.

This method allows monitoring (i.e. determine error on testing set) after each stage.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **y** [generator of ndarray of shape (n_samples,)] The predicted value of the input samples.

**Examples using sklearn.ensemble.GradientBoostingClassifier**

- Gradient Boosting regularization
- Early stopping of Gradient Boosting
- Feature transformations with ensembles of trees
- Gradient Boosting Out-of-Bag estimates
- Feature discretization
Gradient Boosting for regression.

GB builds an additive model in a forward stage-wise fashion; it allows for the optimization of arbitrary differentiable loss functions. In each stage a regression tree is fit on the negative gradient of the given loss function. Read more in the User Guide.

Parameters

- **loss** [{‘ls’, ‘lad’, ‘huber’, ‘quantile’}, default=’ls’] Loss function to be optimized. ‘ls’ refers to least squares regression. ‘lad’ (least absolute deviation) is a highly robust loss function solely based on order information of the input variables. ‘huber’ is a combination of the two. ‘quantile’ allows quantile regression (use alpha to specify the quantile).

- **learning_rate** [float, default=0.1] Learning rate shrinks the contribution of each tree by learning_rate. There is a trade-off between learning_rate and n_estimators.

- **n_estimators** [int, default=100] The number of boosting stages to perform. Gradient boosting is fairly robust to over-fitting so a large number usually results in better performance.

- **subsample** [float, default=1.0] The fraction of samples to be used for fitting the individual base learners. If smaller than 1.0 this results in Stochastic Gradient Boosting. subsample interacts with the parameter n_estimators. Choosing subsample < 1.0 leads to a reduction of variance and an increase in bias.

- **criterion** [{‘friedman_mse’, ‘mse’, ‘mae’}, default=’friedman_mse’] The function to measure the quality of a split. Supported criteria are “friedman_mse” for the mean squared error with improvement score by Friedman, “mse” for mean squared error, and “mae” for the mean absolute error. The default value of “friedman_mse” is generally the best as it can provide a better approximation in some cases. New in version 0.18.

  Deprecated since version 0.24: criterion=’mae’ is deprecated and will be removed in version 1.1 (renaming of 0.26). The correct way of minimizing the absolute error is to use loss=’lad’ instead.

- **min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:
  - If int, then consider min_samples_split as the minimum number.
• If float, then `min_samples_split` is a fraction and 
  \( \text{ceil}(\text{min_samples_split} \times n_{\text{samples}}) \) are the minimum 
  number of samples for each split.

  Changed in version 0.18: Added float values for fractions.

`min_samples_leaf` [int or float, default=1] The minimum number of samples required to be 
  at a leaf node. A split point at any depth will only be considered if it leaves at least 
  `min_samples_leaf` training samples in each of the left and right branches. This may 
  have the effect of smoothing the model, especially in regression.

  • If int, then consider `min_samples_leaf` as the minimum number.

  • If float, then `min_samples_leaf` is a fraction and 
  \( \text{ceil}(\text{min_samples_leaf} \times n_{\text{samples}}) \) are the minimum 
  number of samples for each node.

  Changed in version 0.18: Added float values for fractions.

`min_weight_fraction_leaf` [float, default=0.0] The minimum weighted fraction of the sum total 
  of weights (of all the input samples) required to be at a leaf node. Samples have equal weight 
  when sample_weight is not provided.

`max_depth` [int, default=3] Maximum depth of the individual regression estimators. The maxi-
  mum depth limits the number of nodes in the tree. Tune this parameter for best performance; 
  the best value depends on the interaction of the input variables.

`min_impurity_decrease` [float, default=0.0] A node will be split if this split induces a decrease 
  of the impurity greater than or equal to this value.

  The weighted impurity decrease equation is the following:

  \[
  \frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity} \right)
  \]

  where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, 
  \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in 
  the right child.

  \( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if sample_weight is passed.

  New in version 0.19.

`min_impurity_split` [float, default=None] Threshold for early stopping in tree growth. A node 
  will split if its impurity is above the threshold, otherwise it is a leaf.

  Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of 
  `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` 
  has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use 
  `min_impurity_decrease` instead.

`init` [estimator or ‘zero’, default=None] An estimator object that is used to compute the initial 
  predictions. `init` has to provide `fit` and `predict`. If ‘zero’, the initial raw predictions are set 
  to zero. By default a DummyEstimator is used, predicting either the average target value 
  (for loss='ls'), or a quantile for the other losses.

`random_state` [int, RandomState instance or None, default=None] Controls the random seed 
  given to each Tree estimator at each boosting iteration. In addition, it controls the random 
  permutation of the features at each split (see Notes for more details). It also controls the 
  random splitting of the training data to obtain a validation set if `n_iter_no_change` is 
  not None. Pass an int for reproducible output across multiple function calls. See Glossary.

`max_features` [‘auto’, ‘sqrt’, ‘log2’], int or float, default=None] The number of features to 
  consider when looking for the best split:
• If int, then consider `max_features` features at each split.
• If float, then `max_features` is a fraction and `int(max_features * n_features)` features are considered at each split.
• If “auto”, then `max_features=n_features`.
• If “sqrt”, then `max_features=sqrt(n_features)`.
• If “log2”, then `max_features=log2(n_features)`.
• If None, then `max_features=n_features`.

Choosing `max_features < n_features` leads to a reduction of variance and an increase in bias.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than `max_features` features.

**alpha** [float, default=0.9] The alpha-quantile of the huber loss function and the quantile loss function. Only if `loss='huber'` or `loss='quantile'`.

**verbose** [int, default=0] Enable verbose output. If 1 then it prints progress and performance once in a while (the more trees the lower the frequency). If greater than 1 then it prints progress and performance for every tree.

**max_leaf_nodes** [int, default=None] Grow trees with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just erase the previous solution. See the Glossary.

**validation_fraction** [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if `n_iter_no_change` is set to an integer.

New in version 0.20.

**n_iter_no_change** [int, default=None] `n_iter_no_change` is used to decide if early stopping will be used to terminate training when validation score is not improving. By default it is set to None to disable early stopping. If set to a number, it will set aside `validation_fraction` size of the training data as validation and terminate training when validation score is not improving in all of the previous `n_iter_no_change` numbers of iterations.

New in version 0.20.

**tol** [float, default=1e-4] Tolerance for the early stopping. When the loss is not improving by at least tol for `n_iter_no_change` iterations (if set to a number), the training stops.

New in version 0.20.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than `ccp_alpha` will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

**Attributes**
**feature_importances_** [ndarray of shape (n_features,)] The impurity-based feature importances.

**oob_improvement_** [ndarray of shape (n_estimators,)] The improvement in loss (= deviance) on the out-of-bag samples relative to the previous iteration. oob_improvement_[0] is the improvement in loss of the first stage over the init estimator. Only available if subsample < 1.0

**train_score_** [ndarray of shape (n_estimators,)] The i-th score train_score_[i] is the deviance (= loss) of the model at iteration i on the in-bag sample. If subsample == 1 this is the deviance on the training data.


**init_** [estimator] The estimator that provides the initial predictions. Set via the init argument or loss.init_estimator.

**estimators_** [ndarray of DecisionTreeRegressor of shape (n_estimators, 1)] The collection of fitted sub-estimators.

**n_classes_** [int] The number of classes, set to 1 for regressors.

Deprecation warning: Attribute n_classes_ was deprecated in version 0.24 and will be removed in 1.1 (renaming of 0.26).

**n_estimators_** [int] The number of estimators as selected by early stopping (if n_iter_no_change is specified). Otherwise it is set to n_estimators.

**n_features_** [int] The number of data features.

**max_features_** [int] The inferred value of max_features.

See also:

- **HistGradientBoostingRegressor** Histogram-based Gradient Boosting Classification Tree.
- **sklearn.tree.DecisionTreeRegressor** A decision tree regressor.
- **sklearn.tree.RandomForestRegressor** A random forest regressor.

**Notes**

The features are always randomly permuted at each split. Therefore, the best found split may vary, even with the same training data and max_features=n_features, if the improvement of the criterion is identical for several splits enumerated during the search of the best split. To obtain a deterministic behaviour during fitting, random_state has to be fixed.

**References**


J. Friedman, Stochastic Gradient Boosting, 1999

Examples

```python
>>> from sklearn.datasets import make_regression
>>> from sklearn.ensemble import GradientBoostingRegressor
>>> from sklearn.model_selection import train_test_split

>>> X, y = make_regression(random_state=0)
>>> X_train, X_test, y_train, y_test = train_test_split(
...     X, y, random_state=0)
>>> reg = GradientBoostingRegressor(random_state=0)
>>> reg.fit(X_train, y_train)
GradientBoostingRegressor(random_state=0)
>>> reg.predict(X_test[1:2])
array([-61.3096048])
>>> reg.score(X_test, y_test)
0.40705093153727366
```

Methods

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<td><code>apply(X)</code></td>
<td>Apply trees in the ensemble to X, return leaf indices.</td>
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<tr>
<td><code>fit(X, y[, sample_weight, monitor])</code></td>
<td>Fit the gradient boosting model.</td>
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<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>predict(X)</code></td>
<td>Predict regression target for X.</td>
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<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>staged_predict(X)</code></td>
<td>Predict regression target at each stage for X.</td>
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</table>

**apply** $(X)$

Apply trees in the ensemble to $X$, return leaf indices.

New in version 0.17.

**Parameters**

$X$ ([array-like, sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted to a sparse csr_matrix.

**Returns**

$X$ _leaves_ (array-like of shape (n_samples, n_estimators)) For each datapoint $x$ in $X$ and for each tree in the ensemble, return the index of the leaf $x$ ends up in each estimator.

**property feature_importances_**

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

**Returns**

`feature_importances_` (ndarray of shape (n_features,)) The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.
**fit** (*X*, *y*, *sample_weight=None*, *monitor=None*)

Fit the gradient boosting model.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.
- **y** [array-like of shape (n_samples,)] Target values (strings or integers in classification, real numbers in regression) For classification, labels must correspond to classes.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.
- **monitor** [callable, default=None] The monitor is called after each iteration with the current iteration, a reference to the estimator and the local variables of _fit_stages_ as keyword arguments callable(i, self, locals()). If the callable returns True the fitting procedure is stopped. The monitor can be used for various things such as computing held-out estimates, early stopping, model introspect, and snapshotting.

**Returns**

- **self** [object]

**get_params** (*deep=True*)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict** (*X*)

Predict regression target for *X*.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **y** [ndarray of shape (n_samples,)] The predicted values.

**score** (*X*, *y*, *sample_weight=None*)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})^2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())^2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of *y*, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

---

7.11. **sklearn.ensemble**: Ensemble Methods
X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of $r2$ score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

staged_predict (X)

Predict regression target at each stage for X.

This method allows monitoring (i.e. determine error on testing set) after each stage.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

Returns

y [generator of ndarray of shape (n_samples,)] The predicted value of the input samples.

Examples using sklearn.ensemble.GradientBoostingRegressor

- Plot individual and voting regression predictions
- Prediction Intervals for Gradient Boosting Regression
- Gradient Boosting regression
- Model Complexity Influence
Isolation Forest Algorithm.

Return the anomaly score of each sample using the IsolationForest algorithm

The IsolationForest ‘isolates’ observations by randomly selecting a feature and then randomly selecting a split value between the maximum and minimum values of the selected feature.

Since recursive partitioning can be represented by a tree structure, the number of splittings required to isolate a sample is equivalent to the path length from the root node to the terminating node.

This path length, averaged over a forest of such random trees, is a measure of normality and our decision function.

Random partitioning produces noticeably shorter paths for anomalies. Hence, when a forest of random trees collectively produce shorter path lengths for particular samples, they are highly likely to be anomalies.

Read more in the User Guide.

New in version 0.18.

Parameters

- **n_estimators** [int, default=100] The number of base estimators in the ensemble.

- **max_samples** ["auto", int or float, default="auto"]

  The number of samples to draw from X to train each base estimator.

  - If int, then draw max_samples samples.
  - If float, then draw max_samples * X.shape[0] samples.
  - If "auto", then max_samples=min(256, n_samples).

  If max_samples is larger than the number of samples provided, all samples will be used for all trees (no sampling).

- **contamination** [‘auto’ or float, default=’auto’] The amount of contamination of the data set, i.e. the proportion of outliers in the data set. Used when fitting to define the threshold on the scores of the samples.

  - If ‘auto’, the threshold is determined as in the original paper.
  - If float, the contamination should be in the range [0, 0.5].

  Changed in version 0.22: The default value of contamination changed from 0.1 to 'auto'.

- **max_features** [int or float, default=1.0] The number of features to draw from X to train each base estimator.

  - If int, then draw max_features features.
  - If float, then draw max_features * X.shape[1] features.

- **bootstrap** [bool, default=False] If True, individual trees are fit on random subsets of the training data sampled with replacement. If False, sampling without replacement is performed.
n_jobs [int, default=None] The number of jobs to run in parallel for both fit and predict. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

random_state [int, RandomState instance or None, default=None] Controls the pseudo-randomness of the selection of the feature and split values for each branching step and each tree in the forest.

Pass an int for reproducible results across multiple function calls. See Glossary.

verbose [int, default=0] Controls the verbosity of the tree building process.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See the Glossary.

New in version 0.21.

Attributes

base_estimator_ [ExtraTreeRegressor instance] The child estimator template used to create the collection of fitted sub-estimators.

estimators_ [list of ExtraTreeRegressor instances] The collection of fitted sub-estimators.

estimators_features_ [list of ndarray] The subset of drawn features for each base estimator.

estimators_samples_ [list of ndarray] The subset of drawn samples for each base estimator.

max_samples_ [int] The actual number of samples.

offset_ [float] Offset used to define the decision function from the raw scores. We have the relation: decision_function = score_samples - offset_. offset_ is defined as follows. When the contamination parameter is set to “auto”, the offset is equal to -0.5 as the scores of inliers are close to 0 and the scores of outliers are close to -1. When a contamination parameter different than “auto” is provided, the offset is defined in such a way we obtain the expected number of outliers (samples with decision function < 0) in training.

New in version 0.20.

n_features_ [int] The number of features when fit is performed.

See also:

sklearn.covariance.EllipticEnvelope An object for detecting outliers in a Gaussian distributed dataset.

sklearn.svm.OneClassSVM Unsupervised Outlier Detection. Estimate the support of a high-dimensional distribution. The implementation is based on libsvm.

sklearn.neighbors.LocalOutlierFactor Unsupervised Outlier Detection using Local Outlier Factor (LOF).
Notes
The implementation is based on an ensemble of ExtraTreeRegressor. The maximum depth of each tree is set to $\text{ceil}(\log_2(n))$ where $n$ is the number of samples used to build the tree (see (Liu et al., 2008) for more details).

References
[1], [2]

Examples
```
>>> from sklearn.ensemble import IsolationForest
>>> X = [[-1.1], [0.3], [0.5], [100]]
>>> clf = IsolationForest(random_state=0).fit(X)
>>> clf.predict([[0.1], [0], [90]])
array([ 1, 1, -1])
```

Methods

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**decision_function(X)**
Average anomaly score of X of the base classifiers.

The anomaly score of an input sample is computed as the mean anomaly score of the trees in the forest.

The measure of normality of an observation given a tree is the depth of the leaf containing this observation, which is equivalent to the number of splittings required to isolate this point. In case of several observations n_left in the leaf, the average path length of a n_left samples isolation tree is added.

**Parameters**

| X            | [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to \text{dtype=\text{np.float32}} and if a sparse matrix is provided to a sparse \text{csr_matrix}. |

**Returns**

| scores       | [ndarray of shape (n_samples,)] The anomaly score of the input samples. The lower, the more abnormal. Negative scores represent outliers, positive scores represent inliers. |

**property estimators_samples_**

The subset of drawn samples for each base estimator.

Returns a dynamically generated list of indices identifying the samples used for fitting each member of the ensemble, i.e., the in-bag samples.
Note: the list is re-created at each call to the property in order to reduce the object memory footprint by not storing the sampling data. Thus fetching the property may be slower than expected.

**fit** *(X, y=None, sample_weight=None)*

Fit estimator.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Use `dtype=np.float32` for maximum efficiency. Sparse matrices are also supported, use `sparse csc_matrix` for maximum efficiency.
- **y** [Ignored] Not used, present for API consistency by convention.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted.

**Returns**

- **self** [object] Fitted estimator.

**fit_predict** *(X, y=None)*

Perform fit on X and returns labels for X.

**Parameters**

- **X** [array-like, sparse matrix, dataframe] of shape (n_samples, n_features)]
- **y** [Ignored] Not used, present for API consistency by convention.

**Returns**

- **y** [ndarray of shape (n_samples,)] 1 for inliers, -1 for outliers.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict** *(X)*

Predict if a particular sample is an outlier or not.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to `dtype=np.float32` and if a sparse matrix is provided to a sparse `csr_matrix`.

**Returns**

- **is_inlier** [ndarray of shape (n_samples,)] For each observation, tells whether or not (+1 or -1) it should be considered as an inlier according to the fitted model.

**score_samples** *(X)*

Opposite of the anomaly score defined in the original paper.

The anomaly score of an input sample is computed as the mean anomaly score of the trees in the forest.
The measure of normality of an observation given a tree is the depth of the leaf containing this observation, which is equivalent to the number of splittings required to isolate this point. In case of several observations \( n_{\text{left}} \) in the leaf, the average path length of a \( n_{\text{left}} \) samples isolation tree is added.

**Parameters**

\( \text{X} \) ([array-like, sparse matrix] of shape (n_samples, n_features)) The input samples.

**Returns**

scores [ndarray of shape (n_samples,)] The anomaly score of the input samples. The lower, the more abnormal.

**set_params (\*\*params)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

\*\*params [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

---

**Examples using sklearn.ensemble.IsolationForest**

- IsolationForest example
- Comparing anomaly detection algorithms for outlier detection on toy datasets

**7.11.10 sklearn.ensemble.RandomForestClassifier**

```python
class sklearn.ensemble.RandomForestClassifier (n_estimators=100, *, criterion='gini',
max_depth=None, min_samples_split=2,
min_samples_leaf=1,
min_weight_fraction_leaf=0.0,
max_features='auto',
max_leaf_nodes=None,
min_impurity_decrease=0.0,
min_impurity_split=None,
bootstrap=True, oob_score=False,
n_jobs=None, random_state=None,
verbose=0, warm_start=False,
class_weight=None, ccp_alpha=0.0,
max_samples=None)
```

A random forest classifier.

A random forest is a meta estimator that fits a number of decision tree classifiers on various sub-samples of the dataset and uses averaging to improve the predictive accuracy and control over-fitting. The sub-sample size is controlled with the \text{max_samples} parameter if bootstrap=True (default), otherwise the whole dataset is used to build each tree.

Read more in the User Guide.

**Parameters**
**n_estimators** [int, default=100] The number of trees in the forest.

Changed in version 0.22: The default value of **n_estimators** changed from 10 to 100 in 0.22.

**criterion** [{“gini”, “entropy”}, default=”gini”] The function to measure the quality of a split. Supported criteria are “gini” for the Gini impurity and “entropy” for the information gain. Note: this parameter is tree-specific.

**max_depth** [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than **min_samples_split** samples.

**min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:

- If int, then consider **min_samples_split** as the minimum number.
- If float, then **min_samples_split** is a fraction and ceil(**min_samples_split** * n_samples) are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

**min_samples_leaf** [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least **min_samples_leaf** training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression:

- If int, then consider **min_samples_leaf** as the minimum number.
- If float, then **min_samples_leaf** is a fraction and ceil(**min_samples_leaf** * n_samples) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

**min_weight_fraction_leaf** [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

**max_features** [{“auto”, “sqrt”, “log2”}, int or float, default=”auto”] The number of features to consider when looking for the best split:

- If int, then consider **max_features** features at each split.
- If float, then **max_features** is a fraction and round(**max_features** * n_features) features are considered at each split.
- If “auto”, then **max_features**=sqrt(n_features).
- If “sqrt”, then **max_features**=sqrt(n_features) (same as “auto”).
- If “log2”, then **max_features**=log2(n_features).
- If None, then **max_features**=n_features.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than **max_features** features.

**max_leaf_nodes** [int, default=None] Grow trees with **max_leaf_nodes** in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

**min_impurity_decrease** [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.
The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times (\text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity})
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in the right child.

\( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if \( \text{sample_weight} \) is passed.

New in version 0.19.

**min_impurity_split** [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: \( \text{min_impurity_split} \) has been deprecated in favor of \( \text{min_impurity_decrease} \) in 0.19. The default value of \( \text{min_impurity_split} \) has changed from 1e-7 to 0.23 and it will be removed in 1.0 (renaming of 0.25). Use \( \text{min_impurity_decrease} \) instead.

**bootstrap** [bool, default=True] Whether bootstrap samples are used when building trees. If False, the whole dataset is used to build each tree.

**oob_score** [bool, default=False] Whether to use out-of-bag samples to estimate the generalization accuracy.

**n_jobs** [int, default=None] The number of jobs to run in parallel. \( \text{fit}, \text{predict}, \text{decision_path} \) and \( \text{apply} \) are all parallelized over the trees. None means 1 unless in a \text{joblib.parallel_backend} context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance or None, default=None] Controls both the randomness of the bootstrapping of the samples used when building trees (if \( \text{bootstrap} = \text{True} \)) and the sampling of the features to consider when looking for the best split at each node (if \( \text{max_features} < \text{n_features} \)). See Glossary for details.

**verbose** [int, default=0] Controls the verbosity when fitting and predicting.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See the Glossary.

**class_weight** ["balanced", "balanced_subsample"], dict or list of dicts, default=None] Weights associated with classes in the form \{class_label: weight\}. If not given, all classes are supposed to have weight one. For multi-output problems, a list of dicts can be provided in the same order as the columns of y.

Note that for multioutput (including multilabel) weights should be defined for each class of every column in its own dict. For example, for four-class multilabel classification weights should be \[{0: 1, 1: 1}, {0: 1, 1: 5}, {0: 1, 1: 1}, {0: 1, 1: 1} \} instead of \[{1:1}, {2:5}, {3:1}, {4:1} \] for \( \text{n_samples} / (\text{n_classes} \times \text{np.bincount}(y)) \)

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as \( \text{n_samples} / (\text{n_classes} \times \text{np.bincount}(y)) \)

The “balanced_subsample” mode is the same as “balanced” except that weights are computed based on the bootstrap sample for every tree grown.

For multi-output, the weights of each column of y will be multiplied.
Note that these weights will be multiplied with sample_weight (passed through the fit method) if sample_weight is specified.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than ccp_alpha will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

**max_samples** [int or float, default=None] If bootstrap is True, the number of samples to draw from X to train each base estimator.

- If None (default), then draw X.shape[0] samples.
- If int, then draw max_samples samples.
- If float, then draw max_samples * X.shape[0] samples. Thus, max_samples should be in the interval (0, 1).

New in version 0.22.

**Attributes**

- **base_estimator_** [DecisionTreeClassifier] The child estimator template used to create the collection of fitted sub-estimators.
- **estimators_** [list of DecisionTreeClassifier] The collection of fitted sub-estimators.
- **classes_** [ndarray of shape (n_classes,) or a list of such arrays] The classes labels (single output problem), or a list of arrays of class labels (multi-output problem).
- **n_classes_** [int or list] The number of classes (single output problem), or a list containing the number of classes for each output (multi-output problem).
- **n_features_** [int] The number of features when fit is performed.
- **n_outputs_** [int] The number of outputs when fit is performed.
- **feature_importances_** [ndarray of shape (n_features,)] The impurity-based feature importances.
- **oob_score_** [float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when oob_score is True.
- **oob_decision_function_** [ndarray of shape (n_samples, n_classes)] Decision function computed with out-of-bag estimate on the training set. If n_estimators is small it might be possible that a data point was never left out during the bootstrap. In this case, oob_decision_function_ might contain NaN. This attribute exists only when oob_score is True.

See also:

- **DecisionTreeClassifier**, **ExtraTreesClassifier**
Notes

The default values for the parameters controlling the size of the trees (e.g. max_depth, min_samples_leaf, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

The features are always randomly permuted at each split. Therefore, the best found split may vary, even with the same training data, max_features=n_features and bootstrap=False, if the improvement of the criterion is identical for several splits enumerated during the search of the best split. To obtain a deterministic behaviour during fitting, random_state has to be fixed.

References

[1]

Examples

```python
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_samples=1000, n_features=4,
... n_informative=2, n_redundant=0, random_state=0, shuffle=False)
>>> clf = RandomForestClassifier(max_depth=2, random_state=0)
>>> clf.fit(X, y)
RandomForestClassifier(...)
>>> print(clf.predict([[0, 0, 0, 0]]))
[1]
```

Methods

- `apply(X)`
  - Apply trees in the forest to X, return leaf indices.

- `decision_path(X)`
  - Return the decision path in the forest.

- `fit(X, y[, sample_weight])`
  - Build a forest of trees from the training set (X, y).

- `get_params([deep])`
  - Get parameters for this estimator.

- `predict(X)`
  - Predict class for X.

- `predict_log_proba(X)`
  - Predict class log-probabilities for X.

- `predict_proba(X)`
  - Predict class probabilities for X.

- `score(X, y[, sample_weight])`
  - Return the mean accuracy on the given test data and labels.

- `set_params(**params)`
  - Set the parameters of this estimator.

**apply**(X)

Apply trees in the forest to X, return leaf indices.

**Parameters**

- X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

**Returns**
X_leaves [ndarray of shape (n_samples, n_estimators)] For each datapoint x in X and for each tree in the forest, return the index of the leaf x ends up in.

decision_path (X)
Return the decision path in the forest.
New in version 0.18.

Parameters

X {array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator matrix where non zero elements indicates that the samples goes through the nodes. The matrix is of CSR format.
n_nodes_ptr [ndarray of shape (n_estimators + 1,)] The columns from indicator[n_nodes_ptr[i]:n_nodes_ptr[i+1]] gives the indicator value for the i-th estimator.

property feature_importances_
The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

fit (X, y, sample_weight=None)
Build a forest of trees from the training set (X, y).

Parameters

X {array-like, sparse matrix} of shape (n_samples, n_features)] The training input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csc_matrix.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).
sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters
deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

predict  (X)
Predict class for X.

The predicted class of an input sample is a vote by the trees in the forest, weighted by their probability estimates. That is, the predicted class is the one with highest mean probability estimate across the trees.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

y  [ndarray of shape (n_samples,), or (n_samples, n_outputs)] The predicted classes.

predict_log_proba  (X)
Predict class log-probabilities for X.

The predicted class log-probabilities of an input sample is computed as the log of the mean predicted class probabilities of the trees in the forest.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

p  [ndarray of shape (n_samples, n_classes), or a list of n_outputs] such arrays if n_outputs > 1. The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

predict_proba  (X)
Predict class probabilities for X.

The predicted class probabilities of an input sample are computed as the mean predicted class probabilities of the trees in the forest. The class probability of a single tree is the fraction of samples of the same class in a leaf.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

p  [ndarray of shape (n_samples, n_classes), or a list of n_outputs] such arrays if n_outputs > 1. The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

score  (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.
Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

cscore [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.ensemble.RandomForestClassifier

- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22
- Comparison of Calibration of Classifiers
- Probability Calibration for 3-class classification
- Classifier comparison
- Inductive Clustering
- Plot class probabilities calculated by the VotingClassifier
- OOB Errors for Random Forests
- Feature transformations with ensembles of trees
- Plot the decision surfaces of ensembles of trees on the iris dataset
- Permutation Importance with Multicollinear or Correlated Features
- Permutation Importance vs Random Forest Feature Importance (MDI)
- ROC Curve with Visualization API
- Detection error tradeoff (DET) curve
- Successive Halving Iterations
- Classification of text documents using sparse features
A random forest regressor.

A random forest is a meta estimator that fits a number of classifying decision trees on various sub-samples of the dataset and uses averaging to improve the predictive accuracy and control over-fitting. The sub-sample size is controlled with the `max_samples` parameter if `bootstrap=True` (default), otherwise the whole dataset is used to build each tree.

Read more in the User Guide.

Parameters

- **n_estimators** [int, default=100] The number of trees in the forest.
  
  Changed in version 0.22: The default value of `n_estimators` changed from 10 to 100 in 0.22.

- **criterion** ["mse", "mae", default="mse"] The function to measure the quality of a split. Supported criteria are "mse" for the mean squared error, which is equal to variance reduction as feature selection criterion, and "mae" for the mean absolute error.

  New in version 0.18: Mean Absolute Error (MAE) criterion.

- **max_depth** [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than `min_samples_split` samples.

- **min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:
  
  - If int, then consider `min_samples_split` as the minimum number.
  
  - If float, then `min_samples_split` is a fraction and `ceil(min_samples_split * n_samples)` are the minimum number of samples for each split.

  Changed in version 0.18: Added float values for fractions.

- **min_samples_leaf** [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least `min_samples_leaf` training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

  - If int, then consider `min_samples_leaf` as the minimum number.
  
  - If float, then `min_samples_leaf` is a fraction and `ceil(min_samples_leaf * n_samples)` are the minimum number of samples for each node.

  Changed in version 0.18: Added float values for fractions.
**min_weight_fraction_leaf**  [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

**max_features**  [{“auto”, “sqrt”, “log2”}, int or float, default=”auto”] The number of features to consider when looking for the best split:

- If int, then consider max_features features at each split.
- If float, then max_features is a fraction and round(max_features * n_features) features are considered at each split.
- If “auto”, then max_features=n_features.
- If “sqrt”, then max_features=sqrt(n_features).
- If “log2”, then max_features=log2(n_features).
- If None, then max_features=n_features.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than max_features features.

**max_leaf_nodes**  [int, default=None] Grow trees with max_leaf_nodes in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

**min_impurity_decrease**  [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity} \right)
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in the right child.

\( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if sample_weight is passed.

New in version 0.19.

**min_impurity_split**  [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: min_impurity_split has been deprecated in favor of min_impurity_decrease in 0.19. The default value of min_impurity_split has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use min_impurity_decrease instead.

**bootstrap**  [bool, default=True] Whether bootstrap samples are used when building trees. If False, the whole dataset is used to build each tree.

**oob_score**  [bool, default=False] whether to use out-of-bag samples to estimate the R^2 on unseen data.

**n_jobs**  [int, default=None] The number of jobs to run in parallel. fit, predict, decision_path and apply are all parallelized over the trees. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**random_state**  [int, RandomState instance or None, default=None] Controls both the randomness of the bootstrapping of the samples used when building trees (if bootstrap=True)
and the sampling of the features to consider when looking for the best split at each node (if \( \text{max\_features} < \text{n\_features} \)). See Glossary for details.

**verbose** [int, default=0] Controls the verbosity when fitting and predicting.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See the Glossary.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than ccp_alpha will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

**max_samples** [int or float, default=None] If bootstrap is True, the number of samples to draw from X to train each base estimator.

- If None (default), then draw \( X.\text{shape}[0] \) samples.
- If int, then draw \( \text{max\_samples} \) samples.
- If float, then draw \( \text{max\_samples} \times X.\text{shape}[0] \) samples. Thus, \( \text{max\_samples} \) should be in the interval (0, 1).

New in version 0.22.

**Attributes**

**base_estimator_** [DecisionTreeRegressor] The child estimator template used to create the collection of fitted sub-estimators.

**estimators_** [list of DecisionTreeRegressor] The collection of fitted sub-estimators.

**feature_importances_** [ndarray of shape (n_features,)] The impurity-based feature importances.

**n_features_** [int] The number of features when fit is performed.

**n_outputs_** [int] The number of outputs when fit is performed.

**oob_score_** [float] Score of the training dataset obtained using an out-of-bag estimate. This attribute exists only when oob_score is True.

**oob_prediction_** [ndarray of shape (n_samples,)] Prediction computed with out-of-bag estimate on the training set. This attribute exists only when oob_score is True.

See also:

**DecisionTreeRegressor, ExtraTreesRegressor**

**Notes**

The default values for the parameters controlling the size of the trees (e.g. \( \text{max\_depth}, \text{min\_samples\_leaf}, \text{etc.} \)) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

The features are always randomly permuted at each split. Therefore, the best found split may vary, even with the same training data, \( \text{max\_features} = \text{n\_features} \) and bootstrap=False, if the improvement of the criterion is identical for several splits enumerated during the search of the best split. To obtain a deterministic behaviour during fitting, random_state has to be fixed.
The default value `max_features="auto"` uses `n_features` rather than `n_features / 3`. The latter was originally suggested in [1], whereas the former was more recently justified empirically in [2].

References

[1], [2]

Examples

```python
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_features=4, n_informative=2, ...
... random_state=0, shuffle=False)
>>> regr = RandomForestRegressor(max_depth=2, random_state=0)
>>> regr.fit(X, y)
RandomForestRegressor(...)
>>> print(regr.predict([[0, 0, 0, 0]]))
[-8.32987858]
```

Methods

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**apply** *(X)*

Apply trees in the forest to X, return leaf indices.

**Parameters**

- **X**  
  [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, its dtype will be converted to `dtype=np.float32`. If a sparse matrix is provided, it will be converted into a sparse `csr_matrix`.

**Returns**

- **X_leaves**  
  [ndarray of shape (n_samples, n_estimators)] For each datapoint x in X and for each tree in the forest, return the index of the leaf x ends up in.

**decision_path** *(X)*

Return the decision path in the forest.

**Parameters**

- **X**  
  [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, its dtype will be converted to `dtype=np.float32`. If a sparse matrix is provided, it will be converted into a sparse `csr_matrix`.
Returns

Indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator matrix where non zero elements indicates that the samples goes through the nodes. The matrix is of CSR format.

n_nodes_ptr [ndarray of shape (n_estimators + 1,)] The columns from indicator[n_nodes_ptr[i]:n_nodes_ptr[i+1]] gives the indicator value for the i-th estimator.

property feature_importances_

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

fit (X, y, sample_weight=None)

Build a forest of trees from the training set (X, y).

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csc_matrix.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

self [object]

generate (deep=True)

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)

Predict regression target for X.

The predicted regression target of an input sample is computed as the mean predicted regression targets of the trees in the forest.

Parameters
The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

y [ndarray of shape (n_samples,) or (n_samples, n_outputs)] The predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})**2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())**2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using sklearn.ensemble.RandomForestRegressor

- Release Highlights for scikit-learn 0.24
- Plot individual and voting regression predictions
- Comparing random forests and the multi-output meta estimator
- Combine predictors using stacking
- Prediction Latency
- Imputing missing values before building an estimator

7.11.12 sklearn.ensemble.RandomTreesEmbedding

class sklearn.ensemble.RandomTreesEmbedding (n_estimators=100, *, max_depth=5,
min_samples_split=2, min_samples_leaf=1,
min_weight_fraction_leaf=0.0,
max_leaf_nodes=None,
min_impurity_decrease=0.0,
min_impurity_split=None,
sparse_output=True,
random_state=None,
verbose=0,
warm_start=False)

An ensemble of totally random trees.

An unsupervised transformation of a dataset to a high-dimensional sparse representation. A datapoint is coded according to which leaf of each tree it is sorted into. Using a one-hot encoding of the leaves, this leads to a binary coding with as many ones as there are trees in the forest.

The dimensionality of the resulting representation is \( n_{out} \leq n_{estimators} \times max_{leaf}_{nodes} \). If \( max_{leaf}_{nodes} == None \), the number of leaf nodes is at most \( n_{estimators} \times 2^{\text{max_depth}} \).

Read more in the User Guide.

Parameters

- **n_estimators** [int, default=100] Number of trees in the forest.

  Changed in version 0.22: The default value of n_estimators changed from 10 to 100 in 0.22.

- **max_depth** [int, default=5] The maximum depth of each tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min_samples_split samples.

- **min_samples_split** [int or float, default=2] The minimum number of samples required to split an internal node:

  - If int, then consider min_samples_split as the minimum number.

  - If float, then min_samples_split is a fraction and ceil(min_samples_split \* n_samples) is the minimum number of samples for each split.

  Changed in version 0.18: Added float values for fractions.

- **min_samples_leaf** [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least min_samples_leaf training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.
• If int, then consider `min_samples_leaf` as the minimum number.
• If float, then `min_samples_leaf` is a fraction and `ceil(min_samples_leaf * n_samples)` is the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

`min_weight_fraction_leaf` [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when `sample_weight` is not provided.

`max_leaf_nodes` [int, default=None] Grow trees with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

`min_impurity_decrease` [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
N_t / N * (impurity - N_t_R / N_t * right_impurity - N_t_L / N_t * left_impurity)
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_t_L \) is the number of samples in the left child, and \( N_t_R \) is the number of samples in the right child.

\( N, N_t, N_t_R \) and \( N_t_L \) all refer to the weighted sum, if `sample_weight` is passed.

New in version 0.19.

`min_impurity_split` [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

`sparse_output` [bool, default=True] Whether or not to return a sparse CSR matrix, as default behavior, or to return a dense array compatible with dense pipeline operators.

`n_jobs` [int, default=None] The number of jobs to run in parallel. `fit`, `transform`, `decision_path` and `apply` are all parallelized over the trees. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See `Glossary` for more details.

`random_state` [int, RandomState instance or None, default=None] Controls the generation of the random \( y \) used to fit the trees and the draw of the splits for each feature at the trees' nodes. See `Glossary` for details.

`verbose` [int, default=0] Controls the verbosity when fitting and predicting.

`warm_start` [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble, otherwise, just fit a whole new forest. See `the Glossary`.

**Attributes**

`base_estimator_` [DecisionTreeClassifier instance] The child estimator template used to create the collection of fitted sub-estimators.

`estimators_` [list of DecisionTreeClassifier instances] The collection of fitted sub-estimators.
feature_importances_  [ndarray of shape (n_features,)] The impurity-based feature importances.

n_features_  [int] The number of features when fit is performed.

n_outputs_  [int] The number of outputs when fit is performed.

one_hot_encoder_  [OneHotEncoder instance] One-hot encoder used to create the sparse embedding.

References
[1], [2]

Examples

```python
>>> from sklearn.ensemble import RandomTreesEmbedding
>>> X = [[0,0], [1,0], [0,1], [-1,0], [0,-1]]
>>> random_trees = RandomTreesEmbedding(n_estimators=5, random_state=0, max_depth=1).fit(X)
>>> X_sparse_embedding = random_trees.transform(X)
>>> X_sparse_embedding.toarray()
array([[0., 1., 1., 0., 0., 1., 1., 0., 1., 0.],
       [0., 1., 1., 0., 0., 1., 1., 0., 1., 0.],
       [0., 1., 0., 1., 0., 1., 0., 1., 0., 1.],
       [1., 0., 1., 0., 1., 0., 1., 0., 1., 0.],
       [0., 1., 1., 0., 1., 0., 0., 1., 1., 0.]])
```

Methods

| apply(X) | Apply trees in the forest to X, return leaf indices. |
| decision_path(X) | Return the decision path in the forest. |
| fit(X, y, sample_weight) | Fit estimator. |
| fit_transform(X, y, sample_weight) | Fit estimator and transform dataset. |
| get_params([deep]) | Get parameters for this estimator. |
| set_params(**params) | Set the parameters of this estimator. |
| transform(X) | Transform dataset. |

apply(X)
Apply trees in the forest to X, return leaf indices.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

X_leaves  [ndarray of shape (n_samples, n_estimators)] For each datapoint x in X and for each tree in the forest, return the index of the leaf x ends up in.

decision_path(X)
Return the decision path in the forest.
New in version 0.18.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, its dtype will be converted to dtype=np.float32. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.

Returns

indicator [{sparse matrix of shape (n_samples, n_nodes)] Return a node indicator matrix where non zero elements indicates that the samples goes through the nodes. The matrix is of CSR format.

n_nodes_ptr [ndarray of shape (n_estimators + 1,)] The columns from indicator[n_nodes_ptr[i]:n_nodes_ptr[i+1]] gives the indicator value for the i-th estimator.

property feature_importances_

The impurity-based feature importances.

The higher, the more important the feature. The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] The values of this array sum to 1, unless all trees are single node trees consisting of only the root node, in which case it will be an array of zeros.

fit (X, y=None, sample_weight=None)

Fit estimator.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Use dtype=np.float32 for maximum efficiency. Sparse matrices are also supported, use sparse csc_matrix for maximum efficiency.

y [Ignored] Not used, present for API consistency by convention.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

self [object]

fit_transform (X, y=None, sample_weight=None)

Fit estimator and transform dataset.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Input data used to build forests. Use dtype=np.float32 for maximum efficiency.

y [Ignored] Not used, present for API consistency by convention.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero
or negative weight are ignored while searching for a split in each node. In the case of classification, splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

\[ X_{\text{transformed}} \] [sparse matrix of shape (n_samples, n_out)] Transformed dataset.

get_params (deep=True)
Get parameters for this estimator.

Parameters

\text{deep} [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

\text{params} [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \texttt{Pipeline}). The latter have parameters of the form \texttt{<component>__<parameter>} so that it’s possible to update each component of a nested object.

Parameters

\**params [dict] Estimator parameters.

Returns

\text{self} [estimator instance] Estimator instance.

transform (X)
Transform dataset.

Parameters

\text{X} [[array-like, sparse matrix] of shape (n_samples, n_features)] Input data to be transformed. Use \texttt{dtype=np.float32} for maximum efficiency. Sparse matrices are also supported, use sparse \texttt{csr_matrix} for maximum efficiency.

Returns

\[ X_{\text{transformed}} \] [sparse matrix of shape (n_samples, n_out)] Transformed dataset.

Examples using \texttt{sklearn.ensemble.RandomTreesEmbedding}

- Hashing feature transformation using Totally Random Trees
- Feature transformations with ensembles of trees
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap…
Stack of estimators with a final classifier.

Stacked generalization consists in stacking the output of individual estimator and use a classifier to compute the final prediction. Stacking allows to use the strength of each individual estimator by using their output as input of a final estimator.

Note that `estimators_` are fitted on the full $X$ while `final_estimator_` is trained using cross-validated predictions of the base estimators using `cross_val_predict`.

Read more in the *User Guide*.

New in version 0.22.

**Parameters**

- **estimators** [list of (str, estimator)] Base estimators which will be stacked together. Each element of the list is defined as a tuple of string (i.e. name) and an estimator instance. An estimator can be set to 'drop' using `set_params`.

- **final_estimator** [estimator, default=None] A classifier which will be used to combine the base estimators. The default classifier is a `LogisticRegression`.

- **cv** [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy used in `cross_val_predict` to train `final_estimator`. Possible inputs for `cv` are:
  - None, to use the default 5-fold cross validation,
  - integer, to specify the number of folds in a (Stratified) KFold,
  - An object to be used as a cross-validation generator,
  - An iterable yielding train, test splits.

For integer/None inputs, if the estimator is a classifier and $y$ is either binary or multiclass, `StratifiedKFold` is used. In all other cases, `KFold` is used.

Refer *User Guide* for the various cross-validation strategies that can be used here.

**Note:** A larger number of split will provide no benefits if the number of training samples is large enough. Indeed, the training time will increase. `cv` is not used for model evaluation but for prediction.

- **stack_method** [‘auto’, ‘predict_proba’, ‘decision_function’, ‘predict’], default=’auto’] Methods called for each base estimator. It can be:
  - if 'auto', it will try to invoke, for each estimator, 'predict_proba', 'decision_function' or 'predict' in that order.
  - otherwise, one of 'predict_proba', 'decision_function' or 'predict'. If the method is not implemented by the estimator, it will raise an error.

- **n_jobs** [int, default=None] The number of jobs to run in parallel all estimators fit. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.
**passthrough** [bool, default=False] When False, only the predictions of estimators will be used as training data for final_estimator. When True, the final_estimator is trained on the predictions as well as the original training data.

**verbose** [int, default=0] Verbosity level.

**Attributes**

- **classes_** [ndarray of shape (n_classes,)] Class labels.
- **estimators_** [list of estimators] The elements of the estimators parameter, having been fitted on the training data. If an estimator has been set to 'drop', it will not appear in estimators_.
- **named_estimators_** [Bunch] Attribute to access any fitted sub-estimators by name.
- **final_estimator_** [estimator] The classifier which predicts given the output of estimators_.
- **stack_method_** [list of str] The method used by each base estimator.

**Notes**

When predict_proba is used by each estimator (i.e. most of the time for stack_method='auto' or specifically for stack_method='predict_proba'), The first column predicted by each estimator will be dropped in the case of a binary classification problem. Indeed, both feature will be perfectly collinear.

**References**

[1]

**Examples**

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.svm import LinearSVC
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.ensemble import StackingClassifier

>>> X, y = load_iris(return_X_y=True)
>>> estimators = [
...     ('rf', RandomForestClassifier(n_estimators=10, random_state=42)),
...     ('svr', make_pipeline(StandardScaler(), LinearSVC(random_state=42)))
... ]
>>> clf = StackingClassifier(
...     estimators=estimators, final_estimator=LogisticRegression()
... )
>>> from sklearn.model_selection import train_test_split
>>> X_train, X_test, y_train, y_test = train_test_split(
...     X, y, stratify=y, random_state=42
... )
>>> clf.fit(X_train, y_train).score(X_test, y_test)
0.9...
```
Methods

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### decision_function(X)

Predict decision function for samples in X using `final_estimator_.decision_function`.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vectors, where n_samples is the number of samples and n_features is the number of features.

**Returns**

- `decisions` [ndarray of shape (n_samples,), (n_samples, n_classes), or (n_samples, n_classes * (n_classes-1) / 2)] The decision function computed the final estimator.

### fit(X, y, sample_weight=None)

Fit the estimators.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vectors, where n_samples is the number of samples and n_features is the number of features.
- `y` [array-like of shape (n_samples,)] Target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if all underlying estimators support sample weights.

**Returns**

- `self` [object]

### fit_transform(X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

generate y

**get_params**(deep=True)

Get the parameters of an estimator from the ensemble.

Returns the parameters given in the constructor as well as the estimators contained within the estimators parameter.

Parameters

deep [bool, default=True] Setting it to True gets the various estimators and the parameters of the estimators as well.

property n_features_in_

Number of features seen during fit.

predict(X, **predict_params)

Predict target for X.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

**predict_params** [dict of str -> obj] Parameters to the predict called by the final_estimator. Note that this may be used to return uncertainties from some estimators with return_std or return_cov. Be aware that it will only accounts for uncertainty in the final estimator.

Returns

y_pred [ndarray of shape (n_samples,) or (n_samples, n_output)] Predicted targets.

predict_proba(X)

Predict class probabilities for X using final_estimator_.predict_proba.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

Returns

probabilities [ndarray of shape (n_samples, n_classes) or list of ndarray of shape (n_output,)] The class probabilities of the input samples.

score(X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.
Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params(**params)
Set the parameters of an estimator from the ensemble.

Valid parameter keys can be listed with get_params(). Note that you can directly set the parameters of the estimators contained in estimators.

Parameters

**params [keyword arguments] Specific parameters using e.g. set_params(parameter_name=new_value). In addition, to setting the parameters of the estimator, the individual estimator of the estimators can also be set, or can be removed by setting them to ‘drop’.

transform(X)
Return class labels or probabilities for X for each estimator.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

Returns

y_preds [ndarray of shape (n_samples, n_estimators) or (n_samples, n_classes * n_estimators)] Prediction outputs for each estimator.

Examples using sklearn.ensemble.StackingClassifier

• Release Highlights for scikit-learn 0.22

7.11.14 sklearn.ensemble.StackingRegressor

class sklearn.ensemble.StackingRegressor(estimators, final_estimator=None, *, cv=None, n_jobs=None, passthrough=False, verbose=0)

Stack of estimators with a final regressor.

Stacked generalization consists in stacking the output of individual estimator and use a regressor to compute the final prediction. Stacking allows to use the strength of each individual estimator by using their output as input of a final estimator.

Note that estimators_ are fitted on the full X while final_estimator_ is trained using cross-validated predictions of the base estimators using cross_val_predict.

Read more in the User Guide.

New in version 0.22.

Parameters

estimators [list of (str, estimator)] Base estimators which will be stacked together. Each element of the list is defined as a tuple of string (i.e. name) and an estimator instance. An estimator can be set to ‘drop’ using set_params.

final_estimator [estimator, default=None] A regressor which will be used to combine the base estimators. The default regressor is a RidgeCV.
cv  [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy used in cross_val_predict to train final_estimator. Possible inputs for cv are:

- None, to use the default 5-fold cross validation,
- integer, to specify the number of folds in a (Stratified) KFold,
- An object to be used as a cross-validation generator,
- An iterable yielding train, test splits.

For integer/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Note: A larger number of split will provide no benefits if the number of training samples is large enough. Indeed, the training time will increase. cv is not used for model evaluation but for prediction.

n_jobs  [int, default=None] The number of jobs to run in parallel for fit of all estimators. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

passthrough  [bool, default=False] When False, only the predictions of estimators will be used as training data for final_estimator. When True, the final_estimator is trained on the predictions as well as the original training data.

verbose  [int, default=0] Verbosity level.

Attributes

estimators_  [list of estimator] The elements of the estimators parameter, having been fitted on the training data. If an estimator has been set to 'drop', it will not appear in estimators_.

named_estimators_  [Bunch] Attribute to access any fitted sub-estimators by name.

final_estimator_  [estimator] The regressor to stacked the base estimators fitted.

References

[1]

Examples

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.linear_model import RidgeCV
>>> from sklearn.svm import LinearSVR
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.ensemble import StackingRegressor
>>> X, y = load_diabetes(return_X_y=True)
>>> estimators = [
...     ('lr', RidgeCV()),
...     ('svr', LinearSVR(random_state=42))
... ]
```
>>> reg = StackingRegressor(
... estimators=estimators,
... final_estimator=RandomForestRegressor(n_estimators=10,
... random_state=42)
...
)

```python
>>> from sklearn.model_selection import train_test_split
>>> X_train, X_test, y_train, y_test = train_test_split(
... X, y, random_state=42,
... )
>>> reg.fit(X_train, y_train).score(X_test, y_test)
0.3...
```

Methods

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<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
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<tr>
<td>set_params(**params)</td>
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<tr>
<td>transform(X)</td>
<td>Return the predictions for X for each estimator.</td>
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### fit(X, y, sample_weight=None)

Fit the estimators.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vectors, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)] Target values.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if all underlying estimators support sample weights.

**Returns**

- **self** [object]

### fit_transform(X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- ****fit_params [dict] Additional fit parameters.
Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get the parameters of an estimator from the ensemble.

Returns the parameters given in the constructor as well as the estimators contained within the estimators parameter.

Parameters

deep [bool, default=True] Setting it to True gets the various estimators and the parameters of the estimators as well.

property n_features_in_
Number of features seen during fit.

predict (X, **predict_params)
Predict target for X.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

**predict_params [dict of str -> obj] Parameters to the predict called by the final_estimator. Note that this may be used to return uncertainties from some estimators with return_std or return_cov. Be aware that it will only accounts for uncertainty in the final estimator.

Returns

y_pred [ndarray of shape (n_samples,) or (n_samples, n_output)] Predicted targets.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`
Set the parameters of an estimator from the ensemble.

Valid parameter keys can be listed with `get_params()`. Note that you can directly set the parameters of the estimators contained in `estimators`.

Parameters

**params [keyword arguments]** Specific parameters using e.g. `set_params(parameter_name=new_value)`. In addition, to setting the parameters of the estimator, the individual estimator of the estimators can also be set, or can be removed by setting them to ‘drop’.

`transform (X)`
Return the predictions for X for each estimator.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where `n_samples` is the number of samples and `n_features` is the number of features.

Returns

y_preds [ndarray of shape (n_samples, n_estimators)] Prediction outputs for each estimator.

Examples using `sklearn.ensemble.StackingRegressor`

- Combine predictors using stacking

7.11.15 `sklearn.ensemble.VotingClassifier`

```python
class sklearn.ensemble.VotingClassifier(estimators, *, voting='hard', weights=None, n_jobs=None, flatten_transform=True, verbose=False)
```

Soft Voting/Majority Rule classifier for unfitted estimators.

Read more in the `User Guide`.

New in version 0.17.

Parameters

estimators [list of (str, estimator) tuples] Invoking the `fit` method on the `VotingClassifier` will fit clones of those original estimators that will be stored in the class attribute `self.estimators_`. An estimator can be set to 'drop' using `set_params`.

Changed in version 0.21: ‘drop’ is accepted. Using None was deprecated in 0.22 and support was removed in 0.24.

voting [[‘hard’, ‘soft’], default=’hard’] If ‘hard’, uses predicted class labels for majority rule voting. Else if ‘soft’, predicts the class label based on the argmax of the sums of the predicted probabilities, which is recommended for an ensemble of well-calibrated classifiers.
weights [array-like of shape (n_classifiers,), default=None] Sequence of weights (float or int) to weight the occurrences of predicted class labels (hard voting) or class probabilities before averaging (soft voting). Uses uniform weights if None.

n_jobs [int, default=None] The number of jobs to run in parallel for fit. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

New in version 0.18.

flatten_transform [bool, default=True] Affects shape of transform output only when voting='soft'. If voting='soft' and flatten_transform=True, transform method returns matrix with shape (n_samples, n_classifiers * n_classes). If flatten_transform=False, it returns (n_classifiers, n_samples, n_classes).

verbose [bool, default=False] If True, the time elapsed while fitting will be printed as it is completed.

New in version 0.23.

**Attributes**

estimators_ [list of classifiers] The collection of fitted sub-estimators as defined in estimators that are not 'drop'.

named_estimators_ [Bunch] Attribute to access any fitted sub-estimators by name.

New in version 0.20.

classes_ [array-like of shape (n_predictions,)] The classes labels.

See also:

VotingRegressor Prediction voting regressor.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.naive_bayes import GaussianNB
>>> from sklearn.ensemble import RandomForestClassifier, VotingClassifier
>>> clf1 = LogisticRegression(multi_class='multinomial', random_state=1)
>>> clf2 = RandomForestClassifier(n_estimators=50, random_state=1)
>>> clf3 = GaussianNB()
>>> X = np.array([[[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> y = np.array([1, 1, 1, 2, 2, 2])
>>> eclf1 = VotingClassifier(estimators=[
...     ('lr', clf1), ('rf', clf2), ('gnb', clf3)], voting='hard')
>>> eclf1 = eclf1.fit(X, y)
>>> print(eclf1.predict(X))
[1 1 1 2 2 2]
>>> np.array_equal(eclf1.named_estimators_.lr.predict(X),
...                 eclf1.named_estimators_['lr'].predict(X))
True
>>> eclf2 = VotingClassifier(estimators=[
...     ('lr', clf1), ('rf', clf2), ('gnb', clf3)],
...     voting='soft')
>>> eclf2 = eclf2.fit(X, y)
>>> print(eclf2.predict(X))
```

(continues on next page)
```python
[1 1 2 2 2]
>>> eclf3 = VotingClassifier(estimators=[
...     ('lr', clf1), ('rf', clf2), ('gnb', clf3)],
...     voting='soft', weights=[2,1,1],
...     flatten_transform=True)
>>> eclf3 = eclf3.fit(X, y)
>>> print(eclf3.predict(X))
[1 1 1 2 2 2]
>>> print(eclf3.transform(X).shape)
(6, 6)
```

### Methods

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<td>Predict class labels for X.</td>
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<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of an estimator from the ensemble.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Return class labels or probabilities for X for each estimator.</td>
</tr>
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</table>

```python
fit (X, y, sample_weight=None)
Fit the estimators.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if all underlying estimators support sample weights.

New in version 0.18.

Returns

self [object]

fit_transform (X, y=None, **fit_params)
Return class labels or probabilities for each estimator.

Return predictions for X for each estimator.

Parameters

X [{array-like, sparse matrix, dataframe} of shape (n_samples, n_features)] Input samples

y [ndarray of shape (n_samples,), default=None] Target values (None for unsupervised transformations).
**fit_params**  [dict] Additional fit parameters.

Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params  *(deep=True)*

Get the parameters of an estimator from the ensemble.

Returns the parameters given in the constructor as well as the estimators contained within the estimators parameter.

Parameters

deep  [bool, default=True] Setting it to True gets the various estimators and the parameters of the estimators as well.

predict  *(X)*

Predict class labels for X.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples.

Returns

maj  [array-like of shape (n_samples,)] Predicted class labels.

property predict_proba

Compute probabilities of possible outcomes for samples in X.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples.

Returns

avg  [array-like of shape (n_samples, n_classes)] Weighted average probability for each class per sample.

score  *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X  [array-like of shape (n_samples, n_features)] Test samples.

y  [array-like of shape (n_samples,), or (n_samples, n_outputs)] True labels for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] Mean accuracy of self.predict (X) wrt. y.

set_params  *(**params)*

Set the parameters of an estimator from the ensemble.

Valid parameter keys can be listed with get_params(). Note that you can directly set the parameters of the estimators contained in estimators.

Parameters
**params [keyword arguments] Specific parameters using e.g. set_params(parameter_name=new_value). In addition, to setting the parameters of the estimator, the individual estimator of the estimators can also be set, or can be removed by setting them to ‘drop’.

**transform**(X)
Return class labels or probabilities for X for each estimator.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

Returns

probabilities_or_labels

If voting='soft' and flatten_transform=True: returns ndarray of shape (n_classifiers, n_samples * n_classes), being class probabilities calculated by each classifier.

If voting='soft' and flatten_transform=False: ndarray of shape (n_classifiers, n_samples, n_classes)

If voting='hard': ndarray of shape (n_samples, n_classifiers), being class labels predicted by each classifier.

Examples using sklearn.ensemble.VotingClassifier

- Plot the decision boundaries of a VotingClassifier
- Plot class probabilities calculated by the VotingClassifier

7.11.16 sklearn.ensemble.VotingRegressor

class sklearn.ensemble.VotingRegressor(estimators, *, weights=None, n_jobs=None, verbose=False)

Prediction voting regressor for unfitted estimators.

A voting regressor is an ensemble meta-estimator that fits several base regressors, each on the whole dataset. Then it averages the individual predictions to form a final prediction.

Read more in the User Guide.

New in version 0.21.

Parameters

estimators [list of (str, estimator) tuples] Invoking the fit method on the VotingRegressor will fit clones of those original estimators that will be stored in the class attribute self.estimators_. An estimator can be set to 'drop' using set_params.

Changed in version 0.21: 'drop' is accepted. Using None was deprecated in 0.22 and support was removed in 0.24.

weights [array-like of shape (n_regressors,), default=None] Sequence of weights (float or int) to weight the occurrences of predicted values before averaging. Uses uniform weights if None.
n_jobs [int, default=None] The number of jobs to run in parallel for fit. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [bool, default=False] If True, the time elapsed while fitting will be printed as it is completed.

Attributes

estimators_ [list of regressors] The collection of fitted sub-estimators as defined in estimators that are not ‘drop’.

named_estimators_ [Bunch] Attribute to access any fitted sub-estimators by name.

See also:

VotingClassifier Soft Voting/Majority Rule classifier.

Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import LinearRegression
>>> from sklearn.ensemble import RandomForestRegressor
>>> from sklearn.ensemble import VotingRegressor

>>> r1 = LinearRegression()
>>> r2 = RandomForestRegressor(n_estimators=10, random_state=1)
>>> X = np.array([[1, 1], [2, 4], [3, 9], [4, 16], [5, 25], [6, 36]])
>>> y = np.array([2, 6, 12, 20, 30, 42])
>>> er = VotingRegressor([('lr', r1), ('rf', r2)])
>>> print(er.fit(X, y).predict(X))
[ 3.3 5.7 11.8 19.7 28. 40.3]
```

Methods

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**fit** (X, y, sample_weight=None)

Fit the estimators.

Parameters

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where
n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Note that this is supported only if all underlying estimators support sample weights.

Returns
self [object] Fitted estimator.

fit_transform (X, y=None, **fit_params)
Return class labels or probabilities for each estimator.
Return predictions for X for each estimator.

Parameters
X {array-like, sparse matrix, dataframe} of shape (n_samples, n_features) Input samples
ty [ndarray of shape (n_samples,), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns
X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get the parameters of an estimator from the ensemble.
Returns the parameters given in the constructor as well as the estimators contained within the estimators parameter.

Parameters
dep [bool, default=True] Setting it to True gets the various estimators and the parameters of the estimators as well.

predict (X)
Predict regression target for X.
The predicted regression target of an input sample is computed as the mean predicted regression targets of the estimators in the ensemble.

Parameters
X {array-like, sparse matrix} of shape (n_samples, n_features) The input samples.

Returns
ty [ndarray of shape (n_samples,)] The predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$.
The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters
X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] \( R^2 \) of `self.predict(X)` wrt. y.

Notes

The \( R^2 \) score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

set_params (**params)

Set the parameters of an estimator from the ensemble.

Valid parameter keys can be listed with `get_params()`. Note that you can directly set the parameters of the estimators contained in `estimators`.

Parameters

**params [keyword arguments] Specific parameters using e.g. `set_params(parameter_name=new_value)`. In addition, to setting the parameters of the estimator, the individual estimator of the estimators can also be set, or can be removed by setting them to ‘drop’.

transform(X)

Return predictions for X for each estimator.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples.

Returns

predictions: ndarray of shape (n_samples, n_classifiers) Values predicted by each regressor.

Examples using `sklearn.ensemble.VotingRegressor`

- Plot individual and voting regression predictions
7.11.17  sklearn.ensemble.HistGradientBoostingRegressor

class sklearn.ensemble.HistGradientBoostingRegressor (loss='least_squares', *, learning_rate=0.1, max_iter=100, max_leaf_nodes=31, max_depth=None, min_samples_leaf=20, l2_regularization=0.0, max_bins=255, categorical_features=None, monotonic_cst=None, warm_start=False, early_stopping='auto', scoring='loss', validation_fraction=0.1, n_iter_no_change=10, tol=1e-07, verbose=0, random_state=None)

Histogram-based Gradient Boosting Regression Tree.

This estimator is much faster than GradientBoostingRegressor for big datasets (n_samples >= 10 000).

This estimator has native support for missing values (NaNs). During training, the tree grower learns at each split point whether samples with missing values should go to the left or right child, based on the potential gain. When predicting, samples with missing values are assigned to the left or right child consequently. If no missing values were encountered for a given feature during training, then samples with missing values are mapped to whichever child has the most samples.

This implementation is inspired by LightGBM.

Note: This estimator is still experimental for now: the predictions and the API might change without any deprecation cycle. To use it, you need to explicitly import enable_hist_gradient_boosting:

```python
>>> from sklearn.experimental import enable_hist_gradient_boosting
>>> # now you can import normally from ensemble
```

Read more in the User Guide.

New in version 0.21.

Parameters

- **loss** [{‘least_squares’, ‘least_absolute_deviation’, ‘poisson’}, default=’least_squares’] The loss function to use in the boosting process. Note that the “least squares” and “poisson” losses actually implement “half least squares loss” and “half poisson deviance” to simplify the computation of the gradient. Furthermore, “poisson” loss internally uses a log-link and requires y >= 0

  Changed in version 0.23: Added option ‘poisson’.

- **learning_rate** [float, default=0.1] The learning rate, also known as shrinkage. This is used as a multiplicative factor for the leaves values. Use 1 for no shrinkage.

- **max_iter** [int, default=100] The maximum number of iterations of the boosting process, i.e. the maximum number of trees.
max_leaf_nodes [int or None, default=31] The maximum number of leaves for each tree. Must be strictly greater than 1. If None, there is no maximum limit.

max_depth [int or None, default=None] The maximum depth of each tree. The depth of a tree is the number of edges to go from the root to the deepest leaf. Depth isn’t constrained by default.

min_samples_leaf [int, default=20] The minimum number of samples per leaf. For small datasets with less than a few hundred samples, it is recommended to lower this value since only very shallow trees would be built.

l2_regularization [float, default=0] The L2 regularization parameter. Use 0 for no regularization (default).

max_bins [int, default=255] The maximum number of bins to use for non-missing values. Before training, each feature of the input array $X$ is binned into integer-valued bins, which allows for a much faster training stage. Features with a small number of unique values may use less than max_bins bins. In addition to the max_bins bins, one more bin is always reserved for missing values. Must be no larger than 255.

monotonic_cst [array-like of int of shape (n_features), default=None] Indicates the monotonic constraint to enforce on each feature. -1, 1 and 0 respectively correspond to a negative constraint, positive constraint and no constraint. Read more in the User Guide.

New in version 0.23.

categorical_features [array-like of {bool, int} of shape (n_features) or shape (n_categorical_features,), default=None] Indicates the categorical features.

- None : no feature will be considered categorical.
- boolean array-like : boolean mask indicating categorical features.
- integer array-like : integer indices indicating categorical features.

For each categorical feature, there must be at most max_bins unique categories, and each categorical value must be in $[0, \text{max}_\text{bins} -1]$. Read more in the User Guide.

New in version 0.24.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble. For results to be valid, the estimator should be re-trained on the same data only. See the Glossary.

early_stopping [‘auto’ or bool, default=’auto’] If ‘auto’, early stopping is enabled if the sample size is larger than 10000. If True, early stopping is enabled, otherwise early stopping is disabled.

New in version 0.23.

scoring [str or callable or None, default=’loss’] Scoring parameter to use for early stopping. It can be a single string (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions). If None, the estimator’s default scorer is used. If scoring=’loss’, early stopping is checked w.r.t the loss value. Only used if early stopping is performed.

validation_fraction [int or float or None, default=0.1] Proportion (or absolute size) of training data to set aside as validation data for early stopping. If None, early stopping is done on the training data. Only used if early stopping is performed.
n_iter_no_change [int, default=10] Used to determine when to “early stop”. The fitting process is stopped when none of the last n_iter_no_change scores are better than the n_iter_no_change - 1-th-to-last one, up to some tolerance. Only used if early stopping is performed.

tol [float or None, default=1e-7] The absolute tolerance to use when comparing scores during early stopping. The higher the tolerance, the more likely we are to early stop: higher tolerance means that it will be harder for subsequent iterations to be considered an improvement upon the reference score.

verbose [int, default=0] The verbosity level. If not zero, print some information about the fitting process.

random_state [int, RandomState instance or None, default=None] Pseudo-random number generator to control the subsampling in the binning process, and the train/validation data split if early stopping is enabled. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

do_early_stopping_ [bool] Indicates whether early stopping is used during training.

n_iter_ [int] The number of iterations as selected by early stopping, depending on the early_stopping parameter. Otherwise it corresponds to max_iter.

n_trees_per_iteration_ [int] The number of tree that are built at each iteration. For regressors, this is always 1.

train_score_ [ndarray, shape (n_iter_+1,)] The scores at each iteration on the training data. The first entry is the score of the ensemble before the first iteration. Scores are computed according to the scoring parameter. If scoring is not ‘loss’, scores are computed on a subset of at most 10 000 samples. Empty if no early stopping.

validation_score_ [ndarray, shape (n_iter_+1,)] The scores at each iteration on the held-out validation data. The first entry is the score of the ensemble before the first iteration. Scores are computed according to the scoring parameter. Empty if no early stopping or if validation_fraction is None.

is_categorical_ [ndarray, shape (n_features,) or None] Boolean mask for the categorical features. None if there are no categorical features.

Examples

```python
>>> # To use this experimental feature, we need to explicitly ask for it:
>>> from sklearn.experimental import enable_hist_gradient_boosting  # noqa
>>> from sklearn.ensemble import HistGradientBoostingRegressor
>>> from sklearn.datasets import load_diabetes
>>> X, y = load_diabetes(return_X_y=True)
>>> est = HistGradientBoostingRegressor().fit(X, y)
>>> est.score(X, y)
0.92...
```
Methods

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<td>Predict regression target for each iteration</td>
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**fit (X, y, sample_weight=None)**
Fit the gradient boosting model.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The input samples.
- y [array-like of shape (n_samples,)] Target values.
- sample_weight [array-like of shape (n_samples,)] default=None] Weights of training data.
  New in version 0.23.

**Returns**

- self [object]

**get_params (deep=True)**
Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

**predict (X)**
Predict values for X.

**Parameters**

- X [array-like, shape (n_samples, n_features)] The input samples.

**Returns**

- y [ndarray, shape (n_samples,)] The predicted values.

**score (X, y, sample_weight=None)**
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $(y_{true} - y_{pred}) \approx 2 . \text{sum()}$ and $v$ is the total sum of squares $(y_{true} - y_{true}.\text{mean()}) \approx 2 . \text{sum()}$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape
(n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

staged_predict (X)

Predict regression target for each iteration

This method allows monitoring (i.e. determine error on testing set) after each stage.

New in version 0.24.

Parameters

X [array-like of shape (n_samples, n_features)] The input samples.

Yields

y [generator of ndarray of shape (n_samples,)] The predicted values of the input samples, for each iteration.

Examples using sklearn.ensemble.HistGradientBoostingRegressor

- Release Highlights for scikit-learn 0.23
- Release Highlights for scikit-learn 0.24
- Monotonic Constraints
- Gradient Boosting regression
- Categorical Feature Support in Gradient Boosting
- Combine predictors using stacking
- Poisson regression and non-normal loss
Partial Dependence and Individual Conditional Expectation Plots

7.11.18 sklearn.ensemble.HistGradientBoostingClassifier

class sklearn.ensemble.HistGradientBoostingClassifier (loss='auto', *, learning_rate=0.1, max_iter=100, max_leaf_nodes=31, max_depth=None, min_samples_leaf=20, l2_regularization=0.0, max_bins=255, categorical_features=None, monotonic_cst=None, warm_start=False, early_stopping='auto', scoring='loss', validation_fraction=0.1, n_iter_no_change=10, tol=1e-07, verbose=0, random_state=None)

Histogram-based Gradient Boosting Classification Tree.

This estimator is much faster than GradientBoostingClassifier for big datasets (n_samples >= 10 000).

This estimator has native support for missing values (NaNs). During training, the tree grower learns at each split point whether samples with missing values should go to the left or right child, based on the potential gain. When predicting, samples with missing values are assigned to the left or right child consequently. If no missing values were encountered for a given feature during training, then samples with missing values are mapped to whichever child has the most samples.

This implementation is inspired by LightGBM.

Note: This estimator is still experimental for now: the predictions and the API might change without any deprecation cycle. To use it, you need to explicitly import enable_hist_gradient_boosting:

```python
>>> from sklearn.experimental import enable_hist_gradient_boosting
>>> from sklearn.ensemble import HistGradientBoostingClassifier
```

Read more in the User Guide.

New in version 0.21.

Parameters

- **loss** ([‘auto’, ‘binary_crossentropy’, ‘categorical_crossentropy’], default=’auto’) The loss function to use in the boosting process. ‘binary_crossentropy’ (also known as logistic loss) is used for binary classification and generalizes to ‘categorical_crossentropy’ for multiclass classification. ‘auto’ will automatically choose either loss depending on the nature of the problem.

- **learning_rate** [float, default=0.1] The learning rate, also known as *shrinkage*. This is used as a multiplicative factor for the leaves values. Use 1 for no shrinkage.
**max_iter** [int, default=100] The maximum number of iterations of the boosting process, i.e. the maximum number of trees for binary classification. For multiclass classification, n_classes trees per iteration are built.

**max_leaf_nodes** [int or None, default=31] The maximum number of leaves for each tree. Must be strictly greater than 1. If None, there is no maximum limit.

**max_depth** [int or None, default=None] The maximum depth of each tree. The depth of a tree is the number of edges to go from the root to the deepest leaf. Depth isn’t constrained by default.

**min_samples_leaf** [int, default=20] The minimum number of samples per leaf. For small datasets with less than a few hundred samples, it is recommended to lower this value since only very shallow trees would be built.

**l2_regularization** [float, default=0] The L2 regularization parameter. Use 0 for no regularization.

**max_bins** [int, default=255] The maximum number of bins to use for non-missing values. Before training, each feature of the input array $X$ is binned into integer-valued bins, which allows for a much faster training stage. Features with a small number of unique values may use less than max_bins bins. In addition to the max_bins bins, one more bin is always reserved for missing values. Must be no larger than 255.

**monotonic_cst** [array-like of int of shape (n_features), default=None] Indicates the monotonic constraint to enforce on each feature. -1, 1 and 0 respectively correspond to a negative constraint, positive constraint and no constraint. Read more in the User Guide.

New in version 0.23.

**categorical_features** [array-like of {bool, int} of shape (n_features) or shape (n_categorical_features,), default=None] Indicates the categorical features.

- None : no feature will be considered categorical.
- boolean array-like : boolean mask indicating categorical features.
- integer array-like : integer indices indicating categorical features.

For each categorical feature, there must be at most max_bins unique categories, and each categorical value must be in [0, max_bins -1].

Read more in the User Guide.

New in version 0.24.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit and add more estimators to the ensemble. For results to be valid, the estimator should be re-trained on the same data only. See the Glossary.

**early_stopping** ['auto' or bool, default='auto'] If ‘auto’, early stopping is enabled if the sample size is larger than 10000. If True, early stopping is enabled, otherwise early stopping is disabled.

New in version 0.23.

**scoring** [str or callable or None, default='loss'] Scoring parameter to use for early stopping. It can be a single string (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions). If None, the estimator’s default scorer is used. If scoring='loss', early stopping is checked w.r.t the loss value. Only used if early stopping is performed.
validation_fraction  [int or float or None, default=0.1] Proportion (or absolute size) of training data to set aside as validation data for early stopping. If None, early stopping is done on the training data. Only used if early stopping is performed.

n_iter_no_change  [int, default=10] Used to determine when to “early stop”. The fitting process is stopped when none of the last n_iter_no_change scores are better than the n_iter_no_change - 1-th-to-last one, up to some tolerance. Only used if early stopping is performed.

tol  [float or None, default=1e-7] The absolute tolerance to use when comparing scores. The higher the tolerance, the more likely we are to early stop: higher tolerance means that it will be harder for subsequent iterations to be considered an improvement upon the reference score.

verbose  [int, default=0] The verbosity level. If not zero, print some information about the fitting process.

random_state  [int, RandomState instance or None, default=None] Pseudo-random number generator to control the subsampling in the binning process, and the train/validation data split if early stopping is enabled. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

classes_  [array, shape = (n_classes,)] Class labels.

do_early_stopping_  [bool] Indicates whether early stopping is used during training.

n_iter_  [int] The number of iterations as selected by early stopping, depending on the early_stopping parameter. Otherwise it corresponds to max_iter.

n_trees_per_iteration_  [int] The number of tree that are built at each iteration. This is equal to 1 for binary classification, and to n_classes for multiclass classification.

train_score_  [ndarray, shape (n_iter_+1,)] The scores at each iteration on the training data. The first entry is the score of the ensemble before the first iteration. Scores are computed according to the scoring parameter. If scoring is not ‘loss’, scores are computed on a subset of at most 10 000 samples. Empty if no early stopping.

validation_score_  [ndarray, shape (n_iter_+1,)] The scores at each iteration on the held-out validation data. The first entry is the score of the ensemble before the first iteration. Scores are computed according to the scoring parameter. Empty if no early stopping or if validation_fraction is None.

is_categorical_  [ndarray, shape (n_features, ) or None] Boolean mask for the categorical features. None if there are no categorical features.

Examples

```python
>>> # To use this experimental feature, we need to explicitly ask for it:
>>> from sklearn.experimental import enable_hist_gradient_boosting  # noqa
>>> from sklearn.ensemble import HistGradientBoostingClassifier
>>> from sklearn.datasets import load_iris
>>> X, y = load_iris(return_X_y=True)
>>> clf = HistGradientBoostingClassifier().fit(X, y)
>>> clf.score(X, y)
1.0
```
Methods

decision_function(X)  
Compute the decision function of X.

Parameters

X [array-like, shape (n_samples, n_features)] The input samples.

Returns

decision [ndarray, shape (n_samples,) or (n_samples, n_trees_per_iteration)] The raw predicted values (i.e. the sum of the trees leaves) for each sample. n_trees_per_iteration is equal to the number of classes in multiclass classification.

fit(X, y[, sample_weight])  
Fit the gradient boosting model.

Parameters

X [array-like of shape (n_samples, n_features)] The input samples.

Returns

self [object]

get_params([deep])  
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict(X)  
Predict classes for X.

Parameters

X [array-like, shape (n_samples, n_features)] The input samples.
Returns

\[y \text{ [ndarray, shape (n_samples,)]}\] The predicted classes.

\textbf{predict_proba} (X)

Predict class probabilities for X.

\textbf{Parameters}

X [array-like, shape (n_samples, n_features)] The input samples.

\textbf{Returns}

p [ndarray, shape (n_samples, n_classes)] The class probabilities of the input samples.

\textbf{score} (X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

\textbf{Parameters}

X [array-like of shape (n_samples, n_features)] Test samples.

y [array-like of shape (n_samples,)] or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

\textbf{Returns}

score [float] Mean accuracy of self.predict (X) wrt. y.

\textbf{set_params} (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \textless component\textgreater __\textless parameter\textgreater so that it's possible to update each component of a nested object.

\textbf{Parameters}

**params [dict] Estimator parameters.

\textbf{Returns}

self [estimator instance] Estimator instance.

\textbf{staged_decision_function} (X)

Compute decision function of X for each iteration.

This method allows monitoring (i.e. determine error on testing set) after each stage.

\textbf{Parameters}

X [array-like of shape (n_samples, n_features)] The input samples.

\textbf{Yields}

decision [generator of ndarray of shape (n_samples,)] or (n_samples, n_trees_per_iteration)]

The decision function of the input samples, which corresponds to the raw values predicted from the trees of the ensemble. The classes corresponds to that in the attribute \texttt{classes}.

\textbf{staged_predict} (X)

Predict classes at each iteration.

This method allows monitoring (i.e. determine error on testing set) after each stage.
New in version 0.24.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The input samples.

**Yields**

- y [generator of ndarray of shape (n_samples,)] The predicted classes of the input samples, for each iteration.

**staged_predict_proba** (X)

Predict class probabilities at each iteration.

This method allows monitoring (i.e. determine error on testing set) after each stage.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The input samples.

**Yields**

- y [generator of ndarray of shape (n_samples,)] The predicted class probabilities of the input samples, for each iteration.

### Examples using sklearn.ensemble.HistGradientBoostingClassifier

- Release Highlights for scikit-learn 0.23
- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22

---

### 7.12 sklearn.exceptions: Exceptions and warnings

The sklearn.exceptions module includes all custom warnings and error classes used across scikit-learn.

<table>
<thead>
<tr>
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<tr>
<td>exceptions.DataConversionWarning</td>
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<td>Warning used to notify the user of inefficient computation.</td>
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<td>exceptions.FitFailedWarning</td>
<td>Warning class used if there is an error while fitting the estimator.</td>
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<td>exceptions.UndefinedMetricWarning</td>
<td>Warning used when the metric is invalid</td>
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</tbody>
</table>
7.12.1 sklearn.exceptions.ConvergenceWarning

class sklearn.exceptions.ConvergenceWarning
    Custom warning to capture convergence problems
    
    Changed in version 0.18: Moved from sklearn.utils.
    
    Attributes
    
    args

    Methods

    with_traceback
        Exception.with_traceback(tb) -- set
        self.__traceback__ to tb and return self.

    with_traceback()
        Exception.with_traceback(tb) -- set self.__traceback__ to tb and return self.

Examples using sklearn.exceptions.ConvergenceWarning

- Multiclass sparse logistic regression on 20newsgroups
- Early stopping of Stochastic Gradient Descent
- Visualization of MLP weights on MNIST
- Compare Stochastic learning strategies for MLPClassifier
- Feature discretization

7.12.2 sklearn.exceptions.DataConversionWarning

class sklearn.exceptions.DataConversionWarning
    Warning used to notify implicit data conversions happening in the code.
    
    This warning occurs when some input data needs to be converted or interpreted in a way that may not match the
    user’s expectations.
    
    For example, this warning may occur when the user
    
    - passes an integer array to a function which expects float input and will convert the input
    - requests a non-copying operation, but a copy is required to meet the implementation’s data-type ex-
      penditures;
    - passes an input whose shape can be interpreted ambiguously.
    
    Changed in version 0.18: Moved from sklearn.utils.validation.
    
    Attributes
    
    args
Methods

```python
with_traceback(self, tb) – set self.__traceback__ to tb and return self.
```

### 7.12.3 sklearn.exceptions.DataDimensionalityWarning

#### class sklearn.exceptions.DataDimensionalityWarning

Custom warning to notify potential issues with data dimensionality.

For example, in random projection, this warning is raised when the number of components, which quantifies the dimensionality of the target projection space, is higher than the number of features, which quantifies the dimensionality of the original source space, to imply that the dimensionality of the problem will not be reduced.

Changed in version 0.18: Moved from sklearn.utils.

**Attributes**

- `args`

**Methods**

```python
with_traceback(self, tb) – set self.__traceback__ to tb and return self.
```

### 7.12.4 sklearn.exceptions.EfficiencyWarning

#### class sklearn.exceptions.EfficiencyWarning

Warning used to notify the user of inefficient computation.

This warning notifies the user that the efficiency may not be optimal due to some reason which may be included as a part of the warning message. This may be subclassed into a more specific Warning class.

New in version 0.18.

**Attributes**

- `args`
Methods

with_traceback

Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.

Methods

with_traceback()

Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.

7.12.5 sklearn.exceptions.FitFailedWarning

class sklearn.exceptions.FitFailedWarning

Warning class used if there is an error while fitting the estimator.

This Warning is used in meta estimators GridSearchCV and RandomizedSearchCV and the cross-validation
helper function cross_val_score to warn when there is an error while fitting the estimator.

Changed in version 0.18: Moved from sklearn.cross_validation.

Attributes

args

Methods

with_traceback

Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.

7.12.6 sklearn.exceptions.NotFittedError

class sklearn.exceptions.NotFittedError

Exception class to raise if estimator is used before fitting.

This class inherits from both ValueError and AttributeError to help with exception handling and backward
compatibility.

Attributes

args

Examples

```python
>>> from sklearn.svm import LinearSVC
>>> from sklearn.exceptions import NotFittedError
>>> try:
...     LinearSVC().predict([[1, 2], [2, 3], [3, 4]])
... except NotFittedError as e:
...     print(repr(e))
NotFittedError("This LinearSVC instance is not fitted yet. Call 'fit' with
appropriate arguments before using this estimator."...)
```
Methods

```python
with_traceback
Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.
```

```python
with_traceback()
Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.
```

### 7.12.7 sklearn.exceptions.UndefinedMetricWarning

```python
class sklearn.exceptions.UndefinedMetricWarning
Warning used when the metric is invalid
```

Changed in version 0.18: Moved from sklearn.base.

##### Attributes

- `args`

##### Methods

```python
with_traceback
Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.
```

```python
with_traceback()
Exception.with_traceback(tb) – set self.__traceback__ to tb and return self.
```

### 7.13 sklearn.experimental: Experimental

The `sklearn.experimental` module provides importable modules that enable the use of experimental features or estimators.

The features and estimators that are experimental aren’t subject to deprecation cycles. Use them at your own risks!

- `experimental.enable_hist_gradient_boost` Enables histogram-based gradient boosting estimators.
- `experimental.enable_iterative_imputer` Enables IterativeImputer
- `experimental.enable_halving_search_cv` Enables Successive Halving search-estimators
7.13.1 sklearn.experimental.enable_hist_gradient_boosting

Enables histogram-based gradient boosting estimators.
The API and results of these estimators might change without any deprecation cycle.
Importing this file dynamically sets the HistGradientBoostingClassifier and HistGradientBoostingRegressor as attributes of the ensemble module:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_hist_gradient_boosting
   # noqa
>>> from sklearn.ensemble import HistGradientBoostingClassifier
>>> from sklearn.ensemble import HistGradientBoostingRegressor
```

The # noqa comment can be removed: it just tells linters like flake8 to ignore the import, which appears as unused.

7.13.2 sklearn.experimental.enable_iterative_imputer

Enables IterativeImputer
The API and results of this estimator might change without any deprecation cycle.
Importing this file dynamically sets IterativeImputer as an attribute of the impute module:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_iterative_imputer
   # noqa
>>> from sklearn.impute import IterativeImputer
```

7.13.3 sklearn.experimental.enable_halving_search_cv

Enables Successive Halving search-estimators
The API and results of these estimators might change without any deprecation cycle.
Importing this file dynamically sets the HalvingRandomSearchCV and HalvingGridSearchCV as attributes of the model_selection module:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_halving_search_cv
   # noqa
>>> from sklearn.model_selection import HalvingRandomSearchCV
>>> from sklearn.model_selection import HalvingGridSearchCV
```

The # noqa comment can be removed: it just tells linters like flake8 to ignore the import, which appears as unused.
7.14 sklearn.feature_extraction: Feature Extraction

The `sklearn.feature_extraction` module deals with feature extraction from raw data. It currently includes methods to extract features from text and images.

User guide: See the Feature extraction section for further details.

```
dictVectorizer(*[, dtype=\texttt{numpy.float64}, separator=\texttt{=}, sparse=True, sort=True])
```

Transforms lists of feature-value mappings to vectors.

When feature values are strings, this transformer will do a binary one-hot (aka one-of-K) coding: one boolean-valued feature is constructed for each of the possible string values that the feature can take on. For instance, a feature “f” that can take on the values “ham” and “spam” will become two features in the output, one signifying “f=ham”, the other “f=spam”.

If a feature value is a sequence or set of strings, this transformer will iterate over the values and will count the occurrences of each string value.

However, note that this transformer will only do a binary one-hot encoding when feature values are of type string. If categorical features are represented as numeric values such as int or iterables of strings, the DictVectorizer can be followed by `OneHotEncoder` to complete binary one-hot encoding.

Features that do not occur in a sample (mapping) will have a zero value in the resulting array/matrix.

Read more in the User Guide.

**Parameters**

- `dtype` [dtype, default=np.float64] The type of feature values. Passed to Numpy array/scipy.sparse matrix constructors as the dtype argument.
- `separator` [str, default=“=”] Separator string used when constructing new features for one-hot coding.
- `sparse` [bool, default=True] Whether transform should produce scipy.sparse matrices.
- `sort` [bool, default=True] Whether `feature_names_` and `vocabulary_` should be sorted when fitting.

**Attributes**

- `feature_names_` [list] A list of length n_features containing the feature names (e.g., “f=ham” and “f=spam”).

See also:

- `FeatureHasher` Performs vectorization using only a hash function.
**sklearn.preprocessing.OrdinalEncoder** Handles nominal/categorical features encoded as columns of arbitrary data types.

### Examples

```python
>>> from sklearn.feature_extraction import DictVectorizer

>>> v = DictVectorizer(sparse=False)

D = [{'foo': 1, 'bar': 2}, {'foo': 3, 'baz': 1}]

>>> X = v.fit_transform(D)

>>> X
array([[2., 0., 1.],
       [0., 1., 3.]])

>>> v.inverse_transform(X) == [{'bar': 2.0, 'foo': 1.0}, ...

True

>>> v.transform({'foo': 4, 'unseen_feature': 3})
array([[0., 0., 4.]])
```

### Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tr>
<td><code>fit(X[, y])</code></td>
<td>Learn a list of feature name -&gt; indices mappings.</td>
</tr>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Learn a list of feature name -&gt; indices mappings and transform X.</td>
</tr>
<tr>
<td><code>get_feature_names()</code></td>
<td>Returns a list of feature names, ordered by their indices.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>inverse_transform(X[, dict_type])</code></td>
<td>Transform array or sparse matrix X back to feature mappings.</td>
</tr>
<tr>
<td><code>restrict</code>(support[, indices])</td>
<td>Restrict the features to those in support using feature selection.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Transform feature-&gt;value dicts to array or sparse matrix.</td>
</tr>
</tbody>
</table>

**fit**(X, y=None)

Learn a list of feature name -> indices mappings.

**Parameters**

- **X** [Mapping or iterable over Mappings] Dict(s) or Mapping(s) from feature names (arbitrary Python objects) to feature values (strings or convertible to dtype).
  - Changed in version 0.24: Accepts multiple string values for one categorical feature.

- **y** [(ignored)]

**Returns**

self

**fit_transform**(X, y=None)

Learn a list of feature name -> indices mappings and transform X.

Like fit(X) followed by transform(X), but does not require materializing X in memory.

**Parameters**
X [Mapping or iterable over Mappings] Dict(s) or Mapping(s) from feature names (arbitrary Python objects) to feature values (strings or convertible to dtype).

Changed in version 0.24: Accepts multiple string values for one categorical feature.

y [(ignored)]

Returns

Xa [{array, sparse matrix}] Feature vectors; always 2-d.

get_feature_names ()
Returns a list of feature names, ordered by their indices.

If one-of-K coding is applied to categorical features, this will include the constructed feature names but not the original ones.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform (X, dict_type=<class 'dict'>)
Transform array or sparse matrix X back to feature mappings.

X must have been produced by this DictVectorizer’s transform or fit_transform method; it may only have passed through transformers that preserve the number of features and their order.

In the case of one-hot/one-of-K coding, the constructed feature names and values are returned rather than the original ones.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Sample matrix.

dict_type [type, default=dict] Constructor for feature mappings. Must conform to the collections.Mapping API.

Returns

D [list of dict_type objects of shape (n_samples,)] Feature mappings for the samples in X.

restrict (support, indices=False)
Restrict the features to those in support using feature selection.

This function modifies the estimator in-place.

Parameters

support [array-like] Boolean mask or list of indices (as returned by the get_support member of feature selectors).

indices [bool, default=False] Whether support is a list of indices.

Returns

self
Examples

```python
>>> from sklearn.feature_extraction import DictVectorizer
>>> from sklearn.feature_selection import SelectKBest, chi2

v = DictVectorizer()
D = [{'foo': 1, 'bar': 2}, {'foo': 3, 'baz': 1}]
X = v.fit_transform(D)
support = SelectKBest(chi2, k=2).fit(X, [0, 1])
v.get_feature_names()
['bar', 'baz', 'foo']
v.restrict(support.get_support())
DictVectorizer()
v.get_feature_names()
['bar', 'foo']
```

**set_params(**params**)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform** (X)

Transform feature->value dicts to array or sparse matrix.

Named features not encountered during fit or fit_transform will be silently ignored.

**Parameters**

X [Mapping or iterable over Mappings of shape (n_samples,)] Dict(s) or Mapping(s) from feature names (arbitrary Python objects) to feature values (strings or convertible to dtype).

**Returns**

Xa [[array, sparse matrix]] Feature vectors; always 2-d.

Examples using `sklearn.feature_extraction.DictVectorizer`

- Column Transformer with Heterogeneous Data Sources
- FeatureHasher and DictVectorizer Comparison
7.14.2 sklearn.feature_extraction.FeatureHasher

`class sklearn.feature_extraction.FeatureHasher(n_features=1048576, *, input_type='dict', dtype=<class 'numpy.float64'>, alternate_sign=True)`

Implements feature hashing, aka the hashing trick.

This class turns sequences of symbolic feature names (strings) into scipy.sparse matrices, using a hash function to compute the matrix column corresponding to a name. The hash function employed is the signed 32-bit version of Murmurhash3.

Feature names of type byte string are used as-is. Unicode strings are converted to UTF-8 first, but no Unicode normalization is done. Feature values must be (finite) numbers.

This class is a low-memory alternative to DictVectorizer and CountVectorizer, intended for large-scale (online) learning and situations where memory is tight, e.g. when running prediction code on embedded devices.

Read more in the User Guide.

New in version 0.13.

Parameters

- `n_features` [int, default=2**20] The number of features (columns) in the output matrices. Small numbers of features are likely to cause hash collisions, but large numbers will cause larger coefficient dimensions in linear learners.

- `input_type` [['dict', 'pair', 'string'], default='dict'] Either “dict” (the default) to accept dictionaries over (feature_name, value); “pair” to accept pairs of (feature_name, value); or “string” to accept single strings. feature_name should be a string, while value should be a number. In the case of “string”, a value of 1 is implied. The feature_name is hashed to find the appropriate column for the feature. The value’s sign might be flipped in the output (but see non_negative, below).

- `dtype` [numpy dtype, default=np.float64] The type of feature values. Passed to scipy.sparse matrix constructors as the dtype argument. Do not set this to bool, np.boolean or any unsigned integer type.

- `alternate_sign` [bool, default=True] When True, an alternating sign is added to the features as to approximately conserve the inner product in the hashed space even for small n_features. This approach is similar to sparse random projection.

.. versionchanged:: 0.19 alternate_sign replaces the now deprecated non_negative parameter.

See also:

- `DictVectorizer` Vectorizes string-valued features using a hash table.

- `sklearn.preprocessing.OneHotEncoder` Handles nominal/categorical features.
Examples

```python
>>> from sklearn.feature_extraction import FeatureHasher
>>> h = FeatureHasher(n_features=10)
>>> D = [{'dog': 1, 'cat':2, 'elephant':4},{'dog': 2, 'run': 5}]
>>> f = h.transform(D)
>>> f.toarray()
array([[ 0.,  0., -4., -1.,  0.,  0.,  0.,  0.,  0.,  2.],
       [ 0.,  0.,  0., -2., -5.,  0.,  0.,  0.,  0.,  0.]])
```

Methods

- **fit** *(X, y)*
  No-op.

- **fit_transform** *(X, y)*
  Fit to data, then transform it.

- **get_params** *(deep)*
  Get parameters for this estimator.

- **set_params** *(**params)*
  Set the parameters of this estimator.

- **transform** *(raw_X)*
  Transform a sequence of instances to a scipy.sparse matrix.

```python
fit(X=None, y=None)
No-op.

This method doesn’t do anything. It exists purely for compatibility with the scikit-learn transformer API.

**Parameters**

- **X** [ndarray]

**Returns**

- **self** [FeatureHasher]

```python
fit_transform(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- ****fit_params [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

```python
get_params(deep=True)
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict]

```
**params**  [dict] Parameter names mapped to their values.

**set_params**(**params**)  
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params**  [dict] Estimator parameters.

**Returns**

self  [estimator instance] Estimator instance.

**transform**(raw_X)  
Transform a sequence of instances to a scipy.sparse matrix.

**Parameters**

raw_X  [iterable over iterable over raw features, length = n_samples] Samples. Each sample must be iterable (e.g., a list or tuple) containing/generating feature names (and optionally values, see the input_type constructor argument) which will be hashed. raw_X need not support the len function, so it can be the result of a generator; n_samples is determined on the fly.

**Returns**

X  [sparse matrix of shape (n_samples, n_features)] Feature matrix, for use with estimators or further transformers.

**Examples using sklearn.feature_extraction.FeatureHasher**

- FeatureHasher and DictVectorizer Comparison

## 7.14.3 From images

The `sklearn.feature_extraction.image` submodule gathers utilities to extract features from images.

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>feature_extraction.image.extract_patches_2d(...)</code></td>
<td>Reshape a 2D image into a collection of patches</td>
</tr>
<tr>
<td><code>feature_extraction.image.grid_to_graph(n_x, n_y)</code></td>
<td>Graph of the pixel-to-pixel connections</td>
</tr>
<tr>
<td><code>feature_extraction.image.img_to_graph(img, *)</code></td>
<td>Graph of the pixel-to-pixel gradient connections</td>
</tr>
<tr>
<td><code>feature_extraction.image.reconstruct_from_patches_2d(...)</code></td>
<td>Reconstruct the image from all of its patches.</td>
</tr>
<tr>
<td><code>feature_extraction.image.PatchExtractor(*[, ...])</code></td>
<td>Extracts patches from a collection of images</td>
</tr>
</tbody>
</table>
Reshape a 2D image into a collection of patches

The resulting patches are allocated in a dedicated array.

Read more in the User Guide.

Parameters

- **image** [ndarray of shape (image_height, image_width) or (image_height, image_width, n_channels)] The original image data. For color images, the last dimension specifies the channel: a RGB image would have n_channels=3.

- **patch_size** [tuple of int (patch_height, patch_width)] The dimensions of one patch.

- **max_patches** [int or float, default=None] The maximum number of patches to extract. If max_patches is a float between 0 and 1, it is taken to be a proportion of the total number of patches.

- **random_state** [int, RandomState instance, default=None] Determines the random number generator used for random sampling when max_patches is not None. Use an int to make the randomness deterministic. See Glossary.

Returns

- **patches** [array of shape (n_patches, patch_height, patch_width) or (n_patches, patch_height, patch_width, n_channels)] The collection of patches extracted from the image, where n_patches is either max_patches or the total number of patches that can be extracted.

Examples

```python
>>> from sklearn.datasets import load_sample_image
>>> from sklearn.feature_extraction import image

>>> # Use the array data from the first image in this dataset:
>>> one_image = load_sample_image("china.jpg")
>>> print('Image shape: {}'.format(one_image.shape))
Image shape: (427, 640, 3)

>>> patches = image.extract_patches_2d(one_image, (2, 2))
>>> print('Patches shape: {}'.format(patches.shape))
Patches shape: (272214, 2, 2, 3)

>>> # Here are just two of these patches:
>>> print(patches[1])
[[[174 201 231]
  [174 201 231]]
[[173 200 230]
  [173 200 230]]]

>>> print(patches[800])
[[[187 214 243]
  [188 215 244]]
[[187 214 243]
  [188 215 244]]]
```
Examples using `sklearn.feature_extraction.image.extract_patches_2d`

- Online learning of a dictionary of parts of faces
- Image denoising using dictionary learning

`sklearn.feature_extraction.image.grid_to_graph`

`sklearn.feature_extraction.image.grid_to_graph(n_x, n_y, n_z=1, *, mask=None, return_as=<class 'scipy.sparse.coo.coo_matrix'>, dtype=<class 'int'>)`

Graph of the pixel-to-pixel connections
Edges exist if 2 voxels are connected.

**Parameters**

- `n_x` [int] Dimension in x axis
- `n_y` [int] Dimension in y axis
- `n_z` [int, default=1] Dimension in z axis
- `mask` [ndarray of shape (n_x, n_y, n_z), dtype=bool, default=None] An optional mask of the image, to consider only part of the pixels.
- `return_as` [np.ndarray or a sparse matrix class, default=sparse.coo_matrix] The class to use to build the returned adjacency matrix.
- `dtype` [dtype, default=int] The data of the returned sparse matrix. By default it is int

**Notes**

For scikit-learn versions 0.14.1 and prior, return_as=np.ndarray was handled by returning a dense np.matrix instance. Going forward, np.ndarray returns an np.ndarray, as expected.

For compatibility, user code relying on this method should wrap its calls in `np.asarray` to avoid type issues.

`sklearn.feature_extraction.image.img_to_graph`

`sklearn.feature_extraction.image.img_to_graph(img, *, mask=None, return_as=<class 'scipy.sparse.coo.coo_matrix'>, dtype=None)`

Graph of the pixel-to-pixel gradient connections
Edges are weighted with the gradient values.

Read more in the [User Guide](#).

**Parameters**

- `img` [ndarray of shape (height, width) or (height, width, channel)] 2D or 3D image.
- `mask` [ndarray of shape (height, width) or (height, width, channel), dtype=bool, default=None] An optional mask of the image, to consider only part of the pixels.
- `return_as` [np.ndarray or a sparse matrix class, default=sparse.coo_matrix] The class to use to build the returned adjacency matrix.
**dtype** [dtype, default=None] The data of the returned sparse matrix. By default it is the dtype of `img`.

**Notes**

For scikit-learn versions 0.14.1 and prior, `return_as=np.ndarray` was handled by returning a dense `np.matrix` instance. Going forward, `np.ndarray` returns an `np.ndarray`, as expected.

For compatibility, user code relying on this method should wrap its calls in `np.asarray` to avoid type issues.

**Examples using sklearn.feature_extraction.image.reconstruct_from_patches_2d**

- Image denoising using dictionary learning

**sklearn.feature_extraction.image.PatchExtractor**

class sklearn.feature_extraction.image.PatchExtractor(*, patch_size=None, max_patches=None, random_state=None)

Extracts patches from a collection of images

Read more in the User Guide.

New in version 0.9.

**Parameters**

- **patch_size** [tuple of int (patch_height, patch_width), default=None] The dimensions of one patch.

- **max_patches** [int or float, default=None] The maximum number of patches per image to extract. If `max_patches` is a float in (0, 1), it is taken to mean a proportion of the total number of patches.
random_state [int, RandomState instance, default=None] Determines the random number generator used for random sampling when max_patches is not None. Use an int to make the randomness deterministic. See Glossary.

Examples

```python
>>> from sklearn.datasets import load_sample_images
>>> from sklearn.feature_extraction import image

# Use the array data from the second image in this dataset:
>>> X = load_sample_images().images[1]
>>> print('Image shape: %s' % X.shape)
Image shape: (427, 640, 3)
>>> pe = image.PatchExtractor(patch_size=(2, 2))
>>> pe.fit = pe.fit(X)
>>> pe_trans = pe.transform(X)
>>> print('Patches shape: %s' % pe_trans.shape)
Patches shape: (545706, 2, 2)
```

Methods

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<td>fit(X, y=None)</td>
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<td>get_params(deep=True)</td>
<td>Get parameters for this estimator.</td>
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<tr>
<td>transform(X)</td>
<td>Transforms the image samples in X into a matrix of patch data.</td>
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**fit (X, y=None)**

Do nothing and return the estimator unchanged.

This method is just there to implement the usual API and hence work in pipelines.

Parameters

**X** [array-like of shape (n_samples, n_features)] Training data.

**get_params (deep=True)**

Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**set_params (**params)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.
Returns

self  [estimator instance] Estimator instance.

transform(X)
Transforms the image samples in X into a matrix of patch data.

Parameters

X  [ndarray of shape (n_samples, image_height, image_width) or (n_samples, image_height, image_width, n_channels)] Array of images from which to extract patches. For color images, the last dimension specifies the channel: a RGB image would have n_channels=3.

Returns

patches  [array of shape (n_patches, patch_height, patch_width) or (n_patches, patch_height, patch_width, n_channels)] The collection of patches extracted from the images, where n_patches is either n_samples * max_patches or the total number of patches that can be extracted.

7.14.4 From text

The sklearn.feature_extraction.text submodule gathers utilities to build feature vectors from text documents.

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sklearn.feature_extraction.text.CountVectorizer

class sklearn.feature_extraction.text.CountVectorizer(*, input='content', encoding='utf-8', decode_error='strict', strip_accents=None, lowercase=True, preprocessor=None, tokenizer=None, stop_words=None, token_pattern='(?u)\b\w\w+\b', ngram_range=(1, 1), analyzer='word', max_df=1.0, min_df=1, max_features=None, vocabulary=None, binary=False, dtype=<class 'numpy.int64'>)

Convert a collection of text documents to a matrix of token counts

This implementation produces a sparse representation of the counts using scipy.sparse.csr_matrix.
If you do not provide an a-priori dictionary and you do not use an analyzer that does some kind of feature selection then the number of features will be equal to the vocabulary size found by analyzing the data.

Read more in the *User Guide*.

**Parameters**

*input* [string {'filename', 'file', 'content'}, default='content'] If ‘filename’, the sequence passed as an argument to fit is expected to be a list of filenames that need reading to fetch the raw content to analyze.

If ‘file’, the sequence items must have a ‘read’ method (file-like object) that is called to fetch the bytes in memory.

Otherwise the input is expected to be a sequence of items that can be of type string or byte.

*encoding* [string, default='utf-8'] If bytes or files are given to analyze, this encoding is used to decode.

*decode_error* [{'strict', 'ignore', 'replace'}, default='strict'] Instruction on what to do if a byte sequence is given to analyze that contains characters not of the given encoding. By default, it is ‘strict’, meaning that a UnicodeDecodeError will be raised. Other values are ‘ignore’ and ‘replace’.

*strip_accents* [{'ascii', 'unicode'}, default=None] Remove accents and perform other character normalization during the preprocessing step. ‘ascii’ is a fast method that only works on characters that have an direct ASCII mapping. ‘unicode’ is a slightly slower method that works on any characters. None (default) does nothing.

Both ‘ascii’ and ‘unicode’ use NFKD normalization from `unicodedata.normalize`.

*lowercase* [bool, default=True] Convert all characters to lowercase before tokenizing.

*preprocessor* [callable, default=None] Override the preprocessing (strip_accents and lowercase) stage while preserving the tokenizing and n-grams generation steps. Only applies if `analyzer is not callable`.

*tokenizer* [callable, default=None] Override the string tokenization step while preserving the preprocessing and n-grams generation steps. Only applies if `analyzer == 'word'`.

*stop_words* [string {'english'}, list, default=None] If ‘english’, a built-in stop word list for English is used. There are several known issues with ‘english’ and you should consider an alternative (see *Using stop words*).

If a list, that list is assumed to contain stop words, all of which will be removed from the resulting tokens. Only applies if `analyzer == 'word'`.

If None, no stop words will be used. `max_df` can be set to a value in the range [0.7, 1.0) to automatically detect and filter stop words based on intra corpus document frequency of terms.

*token_pattern* [str, default=r"(?u)\b\w+\b"] Regular expression denoting what constitutes a “token”, only used if `analyzer == 'word'`. The default regexp select tokens of 2 or more alphanumeric characters (punctuation is completely ignored and always treated as a token separator).

If there is a capturing group in token_pattern then the captured group content, not the entire match, becomes the token. At most one capturing group is permitted.

*ngram_range* [tuple (min_n, max_n), default=(1, 1)] The lower and upper boundary of the range of n-values for different word n-grams or char n-grams to be extracted. All values of n such such that min_n <= n <= max_n will be used. For example an ngram_range
of (1, 1) means only unigrams, (1, 2) means unigrams and bigrams, and (2, 2) means only bigrams. Only applies if `analyzer` is not callable.

**analyzer** ["word", "char", "char_wb"] or callable, default="word") Whether the feature should be made of word n-gram or character n-grams. Option "char_wb" creates character n-grams only from text inside word boundaries; n-grams at the edges of words are padded with space. If a callable is passed it is used to extract the sequence of features out of the raw, unprocessed input.

Changed in version 0.21.

Since v0.21, if `input` is filename or file, the data is first read from the file and then passed to the given callable analyzer.

**max_df** [float in range [0.0, 1.0] or int, default=1.0] When building the vocabulary ignore terms that have a document frequency strictly higher than the given threshold (corpus-specific stop words). If float, the parameter represents a proportion of documents, integer absolute counts. This parameter is ignored if vocabulary is not None.

**min_df** [float in range [0.0, 1.0] or int, default=1] When building the vocabulary ignore terms that have a document frequency strictly lower than the given threshold. This value is also called cut-off in the literature. If float, the parameter represents a proportion of documents, integer absolute counts. This parameter is ignored if vocabulary is not None.

**max_features** [int, default=None] If not None, build a vocabulary that only consider the top max_features ordered by term frequency across the corpus.

This parameter is ignored if vocabulary is not None.

**vocabulary** [Mapping or iterable, default=None] Either a Mapping (e.g., a dict) where keys are terms and values are indices in the feature matrix, or an iterable over terms. If not given, a vocabulary is determined from the input documents. Indices in the mapping should not be repeated and should not have any gap between 0 and the largest index.

**binary** [bool, default=False] If True, all non zero counts are set to 1. This is useful for discrete probabilistic models that model binary events rather than integer counts.

**dtype** [type, default=np.int64] Type of the matrix returned by fit_transform() or transform().

**Attributes**

- **vocabulary_** [dict] A mapping of terms to feature indices.
- **fixed_vocabulary_** : boolean True if a fixed vocabulary of term to indices mapping is provided by the user.
- **stop_words_** [set] Terms that were ignored because they either:
  - occurred in too many documents (max_df)
  - occurred in too few documents (min_df)
  - were cut off by feature selection (max_features).

This is only available if no vocabulary was given.

**See also:**

*HashingVectorizer*, *TfidfVectorizer*
Notes

The `stop_words_` attribute can get large and increase the model size when pickling. This attribute is provided only for introspection and can be safely removed using `delattr` or set to `None` before pickling.

Examples

```python
>>> from sklearn.feature_extraction.text import CountVectorizer
>>> corpus = [
... 'This is the first document.',
... 'This document is the second document.',
... 'And this is the third one.',
... 'Is this the first document?',
...]
>>> vectorizer = CountVectorizer()
>>> X = vectorizer.fit_transform(corpus)
>>> print(vectorizer.get_feature_names())
['and', 'document', 'first', 'is', 'one', 'second', 'the', 'third', 'this']
>>> print(X.toarray())
[[0 1 1 0 0 1 0 1 0]
 [0 2 0 1 0 1 0 1 0]
 [1 0 0 1 1 0 1 1 0]
 [0 1 1 1 0 0 1 0 1]]
>>> vectorizer2 = CountVectorizer(analyzer='word', ngram_range=(2, 2))
>>> X2 = vectorizer2.fit_transform(corpus)
>>> print(vectorizer2.get_feature_names())
['and this', 'document is', 'first document', 'is the', 'is this', 'second document', 'the first', 'the second', 'the third', 'third one', 'this document', 'this is', 'this the']
>>> print(X2.toarray())
[[0 0 1 0 1 0 0 1 0 0 0 1 0]
 [0 1 0 1 0 1 0 0 1 0 0 0]
 [1 0 0 1 0 0 0 1 0 1 0 0]
 [0 0 1 0 1 0 0 0 0 1 0 1]]
```

Methods

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<th>Method</th>
<th>Description</th>
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<td><code>build_analyzer()</code></td>
<td>Return a callable that handles preprocessing, tokenization and n-grams generation.</td>
</tr>
<tr>
<td><code>build_preprocessor()</code></td>
<td>Return a function to preprocess the text before tokenization.</td>
</tr>
<tr>
<td><code>build_tokenizer()</code></td>
<td>Return a function that splits a string into a sequence of tokens.</td>
</tr>
<tr>
<td><code>decode(doc)</code></td>
<td>Decode the input into a string of unicode symbols.</td>
</tr>
<tr>
<td><code>fit(raw_documents[, y])</code></td>
<td>Learn a vocabulary dictionary of all tokens in the raw documents.</td>
</tr>
<tr>
<td><code>fit_transform(raw_documents[, y])</code></td>
<td>Learn the vocabulary dictionary and return document-term matrix.</td>
</tr>
<tr>
<td><code>get_feature_names()</code></td>
<td>Array mapping from feature integer indices to feature name.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>get_stop_words()</code></td>
<td>Build or fetch the effective stop words list.</td>
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<td><code>inverse_transform</code></td>
<td>Return terms per document with nonzero entries in <code>X</code>.</td>
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<tr>
<td><code>set_params</code></td>
<td>Set the parameters of this estimator.</td>
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<tr>
<td><code>transform</code></td>
<td>Transform documents to document-term matrix.</td>
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**build_analyzer()**
Return a callable that handles preprocessing, tokenization and n-grams generation.

Returns

 analyzer: callable  A function to handle preprocessing, tokenization and n-grams generation.

**build_preprocessor()**
Return a function to preprocess the text before tokenization.

Returns

 preprocessor: callable  A function to preprocess the text before tokenization.

**build_tokenizer()**
Return a function that splits a string into a sequence of tokens.

Returns

 tokenizer: callable  A function to split a string into a sequence of tokens.

decode(doc)
Decode the input into a string of unicode symbols.

The decoding strategy depends on the vectorizer parameters.

Parameters

 doc  [str] The string to decode.

Returns

 doc: str  A string of unicode symbols.

**fit** (raw_documents, y=None)
Learn a vocabulary dictionary of all tokens in the raw documents.

Parameters

 raw_documents  [iterable] An iterable which yields either str, unicode or file objects.

Returns

 self

**fit_transform** (raw_documents, y=None)
Learn the vocabulary dictionary and return document-term matrix.

This is equivalent to fit followed by transform, but more efficiently implemented.

Parameters

 raw_documents  [iterable] An iterable which yields either str, unicode or file objects.

Returns

 X  [array of shape (n_samples, n_features)] Document-term matrix.

get_feature_names()
Array mapping from feature integer indices to feature name.
Returns

feature_names  [list] A list of feature names.

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth  [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

get_stop_words()
Build or fetch the effective stop words list.

Returns

stop_words: list or None  A list of stop words.

inverse_transform (X)
Return terms per document with nonzero entries in X.

Parameters


Returns

X_inv  [list of arrays of shape (n_samples,)] List of arrays of terms.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>_<parameter> so that it’s possible to update each component
of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform (raw_documents)
Transform documents to document-term matrix.

Extract token counts out of raw text documents using the vocabulary fitted with fit or the one provided to
the constructor.

Parameters

raw_documents  [iterable] An iterable which yields either str, unicode or file objects.

Returns

X  [sparse matrix of shape (n_samples, n_features)] Document-term matrix.
Examples using `sklearn.feature_extraction.text.CountVectorizer`

- Sample pipeline for text feature extraction and evaluation

### `sklearn.feature_extraction.text.HashingVectorizer`

```python
class sklearn.feature_extraction.text.HashingVectorizer(*, input='content', encoding='utf-8', decode_error='strict', strip_accents=None, lowercase=True, preprocessor=None, tokenizer=None, stop_words=None, token_pattern='(?u)\b\w\w+\b', ngram_range=(1, 1), analyzer='word', n_features=1048576, binary=False, norm='l2', alternate_sign=True, dtype=<class 'numpy.float64'>)
```

Convert a collection of text documents to a matrix of token occurrences

It turns a collection of text documents into a scipy.sparse matrix holding token occurrence counts (or binary occurrence information), possibly normalized as token frequencies if norm='l1' or projected on the euclidean unit sphere if norm='l2'.

This text vectorizer implementation uses the hashing trick to find the token string name to feature integer index mapping.

This strategy has several advantages:

- it is very low memory scalable to large datasets as there is no need to store a vocabulary dictionary in memory
- it is fast to pickle and un-pickle as it holds no state besides the constructor parameters
- it can be used in a streaming (partial fit) or parallel pipeline as there is no state computed during fit.

There are also a couple of cons (vs using a CountVectorizer with an in-memory vocabulary):

- there is no way to compute the inverse transform (from feature indices to string feature names) which can be a problem when trying to introspect which features are most important to a model.
- there can be collisions: distinct tokens can be mapped to the same feature index. However in practice this is rarely an issue if n_features is large enough (e.g. 2 ** 18 for text classification problems).
- no IDF weighting as this would render the transformer stateful.

The hash function employed is the signed 32-bit version of Murmurhash3.

Read more in the User Guide.

**Parameters**

- **input** [string {'filename', 'file', 'content'}, default='content'] If `filename`, the sequence passed as an argument to fit is expected to be a list of filenames that need reading to fetch the raw content to analyze.
If ‘file’, the sequence items must have a ‘read’ method (file-like object) that is called to fetch the bytes in memory.

Otherwise the input is expected to be a sequence of items that can be of type string or byte.

**encoding** [string, default=’utf-8’] If bytes or files are given to analyze, this encoding is used to decode.

**decode_error** [{'strict', 'ignore', 'replace'}, default=’strict’] Instruction on what to do if a byte sequence is given to analyze that contains characters not of the given encoding. By default, it is ‘strict’, meaning that a UnicodeDecodeError will be raised. Other values are ‘ignore’ and ‘replace’.

**strip_accents** [{'ascii', 'unicode'}, default=None] Remove accents and perform other character normalization during the preprocessing step. ‘ascii’ is a fast method that only works on characters that have an direct ASCII mapping. ‘unicode’ is a slightly slower method that works on any characters. None (default) does nothing.

Both ‘ascii’ and ‘unicode’ use NFKD normalization from `unicodedata.normalize`.

**lowercase** [bool, default=True] Convert all characters to lowercase before tokenizing.

**preprocessor** [callable, default=None] Override the preprocessing (string transformation) stage while preserving the tokenizing and n-grams generation steps. Only applies if `analyzer` is not callable.

**tokenizer** [callable, default=None] Override the string tokenization step while preserving the preprocessing and n-grams generation steps. Only applies if `analyzer` == ‘word’.

**stop_words** [string {'english'}, list, default=None] If ‘english’, a built-in stop word list for English is used. There are several known issues with ‘english’ and you should consider an alternative (see Using stop words).

If a list, that list is assumed to contain stop words, all of which will be removed from the resulting tokens. Only applies if `analyzer` == ‘word’.

**token_pattern** [str, default=r”(?u)\b\w\w+\b”] Regular expression denoting what constitutes a “token”, only used if `analyzer` == ‘word’. The default regexp selects tokens of 2 or more alphanumeric characters (punctuation is completely ignored and always treated as a token separator).

If there is a capturing group in `token_pattern` then the captured group content, not the entire match, becomes the token. At most one capturing group is permitted.

**ngram_range** [tuple (min_n, max_n), default=(1, 1)] The lower and upper boundary of the range of n-values for different n-grams to be extracted. All values of n such that min_n <= n <= max_n will be used. For example an `ngram_range` of (1, 1) means only unigrams, (1, 2) means unigrams and bigrams, and (2, 2) means only bigrams. Only applies if `analyzer` is not callable.

**analyzer** [{'word', 'char', 'char_wb'} or callable, default=‘word’] Whether the feature should be made of word or character n-grams. Option ‘char_wb’ creates character n-grams only from text inside word boundaries; n-grams at the edges of words are padded with space.

If a callable is passed it is used to extract the sequence of features out of the raw, unprocessed input.

Changed in version 0.21.

Since v0.21, if `input` is `filename` or `file`, the data is first read from the file and then passed to the given callable analyzer.
**n_features** [int, default=(2 ** 20)] The number of features (columns) in the output matrices. Small numbers of features are likely to cause hash collisions, but large numbers will cause larger coefficient dimensions in linear learners.

**binary** [bool, default=False] If True, all non zero counts are set to 1. This is useful for discrete probabilistic models that model binary events rather than integer counts.

**norm** [{'l1', 'l2'}, default='l2'] Norm used to normalize term vectors. None for no normalization.

**alternate_sign** [bool, default=True] When True, an alternating sign is added to the features as to approximately conserve the inner product in the hashed space even for small n_features. This approach is similar to sparse random projection.

New in version 0.19.

**dtype** [type, default=np.float64] Type of the matrix returned by fit_transform() or transform().

**See also:**

*CountVectorizer*, *TfidfVectorizer*

**Examples**

```python
>>> from sklearn.feature_extraction.text import HashingVectorizer
>>> corpus = [
... 'This is the first document.',
... 'This document is the second document.',
... 'And this is the third one.',
... 'Is this the first document?'
... ]
>>> vectorizer = HashingVectorizer(n_features=2**4)
>>> X = vectorizer.fit_transform(corpus)
>>> print(X.shape)
(4, 16)
```

**Methods**

- **build_analyzer()**: Return a callable that handles preprocessing, tokenization and n-grams generation.
- **build_preprocessor()**: Return a function to preprocess the text before tokenization.
- **build_tokenizer()**: Return a function that splits a string into a sequence of tokens.
- **decode(doc)**: Decode the input into a string of unicode symbols.
- **fit(X[, y])**: Does nothing: this transformer is stateless.
- **fit_transform(X[, y])**: Transform a sequence of documents to a document-term matrix.
- **get_params([deep])**: Get parameters for this estimator.
- **get_stop_words()**: Build or fetch the effective stop words list.
- **partial_fit(X[, y])**: Does nothing: this transformer is stateless.
- **set_params(**params)**: Set the parameters of this estimator.
- **transform(X)**: Transform a sequence of documents to a document-term matrix.
**build_analyzer()**
Return a callable that handles preprocessing, tokenization and n-grams generation.

Returns

**analyzer: callable** A function to handle preprocessing, tokenization and n-grams generation.

**build_preprocessor()**
Return a function to preprocess the text before tokenization.

Returns

**preprocessor: callable** A function to preprocess the text before tokenization.

**build_tokenizer()**
Return a function that splits a string into a sequence of tokens.

Returns

**tokenizer: callable** A function to split a string into a sequence of tokens.

**decode** *(doc)*
Decode the input into a string of unicode symbols.

The decoding strategy depends on the vectorizer parameters.

Parameters

**doc** [str] The string to decode.

Returns

**doc** [str] A string of unicode symbols.

**fit** *(X, y=None)*
Does nothing: this transformer is stateless.

Parameters

**X** [ndarray of shape [n_samples, n_features]] Training data.

**fit_transform** *(X, y=None)*
Transform a sequence of documents to a document-term matrix.

Parameters

**X** [iterable over raw text documents, length = n_samples] Samples. Each sample must be a text document (either bytes or unicode strings, file name or file object depending on the constructor argument) which will be tokenized and hashed.

**y** [any] Ignored. This parameter exists only for compatibility with sklearn.pipeline.Pipeline.

Returns

**X** [sparse matrix of shape (n_samples, n_features)] Document-term matrix.

**get_params** *(deep=True)*
Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.
get_stop_words ()
Build or fetch the effective stop words list.

Returns

stop_words: list or None A list of stop words.

partial_fit (X, y=None)
Does nothing: this transformer is stateless.
This method is just there to mark the fact that this transformer can work in a streaming setup.

Parameters

X [ndarray of shape [n_samples, n_features]] Training data.

set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Transform a sequence of documents to a document-term matrix.

Parameters

X [iterable over raw text documents, length = n_samples] Samples. Each sample must be a text document (either bytes or unicode strings, file name or file object depending on the constructor argument) which will be tokenized and hashed.

Returns

X [sparse matrix of shape (n_samples, n_features)] Document-term matrix.

Examples using sklearn.feature_extraction.text.HashingVectorizer

- Out-of-core classification of text documents
- Clustering text documents using k-means
- Classification of text documents using sparse features
Transform a count matrix to a normalized tf or tf-idf representation

Tf means term-frequency while tf-idf means term-frequency times inverse document-frequency. This is a common term weighting scheme in information retrieval, that has also found good use in document classification.

The goal of using tf-idf instead of the raw frequencies of occurrence of a token in a given document is to scale down the impact of tokens that occur very frequently in a given corpus and that are hence empirically less informative than features that occur in a small fraction of the training corpus.

The formula that is used to compute the tf-idf for a term t of a document d in a document set is tf-idf(t, d) = tf(t, d) * idf(t), and the idf is computed as idf(t) = log [ n / df(t) ] + 1 (if smooth_idf=False), where n is the total number of documents in the document set and df(t) is the document frequency of t; the document frequency is the number of documents in the document set that contain the term t. The effect of adding “1” to the idf in the equation above is that terms with zero idf, i.e., terms that occur in all documents in a training set, will not be entirely ignored. (Note that the idf formula above differs from the standard textbook notation that defines the idf as idf(t) = log [ n / (df(t) + 1) ].

If smooth_idf=True (the default), the constant “1” is added to the numerator and denominator of the idf as if an extra document was seen containing every term in the collection exactly once, which prevents zero divisions: idf(t) = log [ (1 + n) / (1 + df(t)) ] + 1.

Furthermore, the formulas used to compute tf and idf depend on parameter settings that correspond to the SMART notation used in IR as follows:

Tf is “n” (natural) by default, “l” (logarithmic) when sublinear_tf=True. Idf is “t” when use_idf is given, “n” (none) otherwise. Normalization is “c” (cosine) when norm='l2', “n” (none) when norm=None.

Read more in the User Guide.

Parameters

- **norm** [‘l2’, ‘l1’] Each output row will have unit norm, either: * ‘l2’: Sum of squares of vector elements is 1. The cosine similarity between two vectors is their dot product when l2 norm has been applied. * ‘l1’: Sum of absolute values of vector elements is 1. See preprocessing.normalize

- **use_idf** [bool, default=True] Enable inverse-document-frequency reweighting.

- **smooth_idf** [bool, default=True] Smooth idf weights by adding one to document frequencies, as if an extra document was seen containing every term in the collection exactly once. Prevents zero divisions.

- **sublinear_tf** [bool, default=False] Apply sublinear tf scaling, i.e. replace tf with 1 + log(tf).

Attributes

- **idf_** [array of shape (n_features)] The inverse document frequency (IDF) vector; only defined if use_idf is True.

New in version 0.20.
References

[Yates2011], [MRS2008]

Examples

```python
>>> from sklearn.feature_extraction.text import TfidfTransformer
>>> from sklearn.feature_extraction.text import CountVectorizer
>>> from sklearn.pipeline import Pipeline
>>> import numpy as np

>>> corpus = ['this is the first document',
...           'this document is the second document',
...           'and this is the third one',
...           'is this the first document']

>>> vocabulary = ['this', 'document', 'first', 'is', 'second', 'the',
...                'and', 'one']

>>> pipe = Pipeline([('count', CountVectorizer(vocabulary=vocabulary)),
...                   ('tfid', TfidfTransformer())]).fit(corpus)

>>> pipe['count'].transform(corpus).toarray()
array([[1, 1, 1, 0, 1, 0, 0, 0],
       [1, 2, 0, 1, 1, 0, 0, 0],
       [1, 0, 0, 1, 0, 1, 1, 1],
       [1, 1, 1, 1, 0, 1, 0, 0]])

>>> pipe['tfid'].idf_
array([1., 1.22314355, 1.51082562, 1., 1.91629073, 1., 1.91629073, 1.91629073])

>>> pipe.transform(corpus).shape
(4, 8)
```

Methods

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<td><code>fit(X, y=None)</code></td>
<td>Learn the idf vector (global term weights).</td>
</tr>
<tr>
<td><code>fit_transform(X, y=None, **fit_params)</code></td>
<td>Fit to data, then transform it. Fits transformer to X and y with optional parameters <code>fit_params</code> and returns a transformed version of X.</td>
</tr>
<tr>
<td><code>get_params(deep)</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X, copy=True)</code></td>
<td>Transform a count matrix to a tf or tf-idf representation.</td>
</tr>
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</table>

**fit (X, y=None)**

Learn the idf vector (global term weights).

**Parameters**

- **X** [sparse matrix of shape \(n_{samples}, n_{features}\)] A matrix of term/token counts.

**fit_transform (X, y=None, **fit_params)**

Fit to data, then transform it.

Fits transformer to \(X\) and \(y\) with optional parameters `fit_params` and returns a transformed version of \(X\).

**Parameters**

- **X** [array-like of shape \((n_{samples}, n_{features})\)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

X_new [ndarray of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X, copy=True)

Transform a count matrix to a tf or tf-idf representation

Parameters

X [sparse matrix of (n_samples, n_features)] a matrix of term/token counts

copy [bool, default=True] Whether to copy X and operate on the copy or perform in-place operations.

Returns

vectors [sparse matrix of shape (n_samples, n_features)]

Examples using sklearn.feature_extraction.text.TfidfTransformer

- Sample pipeline for text feature extraction and evaluation
**sklearn.feature_extraction.text.TfidfVectorizer**

**class sklearn.feature_extraction.text.TfidfVectorizer(**

```
*, input='content', encoding='utf-8',
    decode_error='strict',
    strip_accents=None, lowercase=True, preprocessor=None, tokenizer=None,
    analyzer='word', stop_words=None, token_pattern='(?u)\b\w\w+\b',
    ngram_range=(1, 1), max_df=1.0, min_df=1,
    max_features=None, vocabulary=None, binary=False,
    dtype=<class 'numpy.float64'>,
    norm='l2', use_idf=True, smooth_idf=True,
    sublinear_tf=False)
```

Convert a collection of raw documents to a matrix of TF-IDF features.

Equivalent to `CountVectorizer` followed by `TfidfTransformer`.

Read more in the `User Guide`.

**Parameters**

- **input** ([`'filename', 'file', 'content'`], default=`'content'`) If `filename`, the sequence passed as an argument to fit is expected to be a list of filenames that need reading to fetch the raw content to analyze.

  If `file`, the sequence items must have a `read` method (file-like object) that is called to fetch the bytes in memory.

  Otherwise the input is expected to be a sequence of items that can be of type string or byte.

- **encoding** ([str, default=`'utf-8'`]) If bytes or files are given to analyze, this encoding is used to decode.

- **decode_error** ([`'strict', 'ignore', 'replace'`], default=`'strict'`) Instruction on what to do if a byte sequence is given to analyze that contains characters not of the given encoding. By default, it is `strict`, meaning that a UnicodeDecodeError will be raised. Other values are `ignore` and `replace`.

- **strip_accents** ([`'ascii', 'unicode'`], default=`None`) Remove accents and perform other character normalization during the preprocessing step. `ascii` is a fast method that only works on characters that have an direct ASCII mapping. `unicode` is a slightly slower method that works on any characters. None (default) does nothing.

  Both `ascii` and `unicode` use NFKD normalization from `unicodedata.normalize`

- **lowercase** ([bool, default=`True`]) Convert all characters to lowercase before tokenizing.

- **preprocessor** ([callable, default=`None`]) Override the preprocessing (string transformation) stage while preserving the tokenizing and n-grams generation steps. Only applies if `analyzer` is not callable.

- **tokenizer** ([callable, default=`None`]) Override the string tokenization step while preserving the preprocessing and n-grams generation steps. Only applies if `analyzer == 'word'`.

---

7.14. **sklearn.feature_extraction**: Feature Extraction
analyzer [‘word’, ‘char’, ‘char_wb’] or callable, default=’word’] Whether the feature should be made of word or character n-grams. Option ‘char_wb’ creates character n-grams only from text inside word boundaries; n-grams at the edges of words are padded with space.

If a callable is passed it is used to extract the sequence of features out of the raw, unprocessed input.

Changed in version 0.21.

Since v0.21, if input is filename or file, the data is first read from the file and then passed to the given callable analyzer.

stop_words [{'english'}, list, default=None] If a string, it is passed to _check_stop_list and the appropriate stop list is returned. ‘english’ is currently the only supported string value. There are several known issues with ‘english’ and you should consider an alternative (see Using stop words).

If a list, that list is assumed to contain stop words, all of which will be removed from the resulting tokens. Only applies if analyzer == 'word'.

If None, no stop words will be used. max_df can be set to a value in the range [0.7, 1.0) to automatically detect and filter stop words based on intra corpus document frequency of terms.

token_pattern [str, default=r”(?u)\w\w+”] Regular expression denoting what constitutes a “token”, only used if analyzer == ‘word’. The default regexp selects tokens of 2 or more alphanumeric characters (punctuation is completely ignored and always treated as a token separator).

If there is a capturing group in token_pattern then the captured group content, not the entire match, becomes the token. At most one capturing group is permitted.

ngram_range [tuple (min_n, max_n), default=(1, 1)] The lower and upper boundary of the range of n-values for different n-grams to be extracted. All values of n such that min_n <= n <= max_n will be used. For example an ngram_range of (1, 1) means only unigrams, (1, 2) means unigrams and bigrams, and (2, 2) means only bigrams. Only applies if analyzer is not callable.

max_df [float or int, default=1.0] When building the vocabulary ignore terms that have a document frequency strictly higher than the given threshold (corpus-specific stop words). If float in range [0.0, 1.0], the parameter represents a proportion of documents, integer absolute counts. This parameter is ignored if vocabulary is not None.

min_df [float or int, default=1] When building the vocabulary ignore terms that have a document frequency strictly lower than the given threshold. This value is also called cut-off in the literature. If float in range of [0.0, 1.0], the parameter represents a proportion of documents, integer absolute counts. This parameter is ignored if vocabulary is not None.

max_features [int, default=None] If not None, build a vocabulary that only consider the top max_features ordered by term frequency across the corpus.

This parameter is ignored if vocabulary is not None.

vocabulary [Mapping or iterable, default=None] Either a Mapping (e.g., a dict) where keys are terms and values are indices in the feature matrix, or an iterable over terms. If not given, a vocabulary is determined from the input documents.

binary [bool, default=False] If True, all non-zero term counts are set to 1. This does not mean outputs will have only 0/1 values, only that the tf term in tf-idf is binary. (Set idf and normalization to False to get 0/1 outputs).

dtype [dtype, default=float64] Type of the matrix returned by fit_transform() or transform().
norm [ {'l1', 'l2'}, default='l2' ] Each output row will have unit norm, either: * 'l2': Sum of squares of vector elements is 1. The cosine similarity between two vectors is their dot product when l2 norm has been applied. * 'l1': Sum of absolute values of vector elements is 1. See preprocessing.normalize.


smooth_idf [ bool, default=True ] Smooth idf weights by adding one to document frequencies, as if an extra document was seen containing every term in the collection exactly once. Prevents zero divisions.

sublinear_tf [ bool, default=False ] Apply sublinear tf scaling, i.e. replace tf with 1 + log(tf).

Attributes

vocabulary_ [dict] A mapping of terms to feature indices.

fixed_vocabulary_: bool True if a fixed vocabulary of term to indices mapping is provided by the user

idf_ [array of shape (n_features,)] The inverse document frequency (IDF) vector; only defined if use_idf is True.

stop_words_ [set] Terms that were ignored because they either:
- occurred in too many documents (max_df)
- occurred in too few documents (min_df)
- were cut off by feature selection (max_features).

This is only available if no vocabulary was given.

See also:

CountVectorizer Transforms text into a sparse matrix of n-gram counts.

TfidfTransformer Performs the TF-IDF transformation from a provided matrix of counts.

Notes

The stop_words_ attribute can get large and increase the model size when pickling. This attribute is provided only for introspection and can be safely removed using delattr or set to None before pickling.

Examples

```python
>>> from sklearn.feature_extraction.text import TfidfVectorizer
>>> corpus = ['This is the first document.',
...        'This document is the second document.',
...        'And this is the third one.',
...        'Is this the first document?',
...        ]
>>> vectorizer = TfidfVectorizer()
>>> X = vectorizer.fit_transform(corpus)
>>> print(vectorizer.get_feature_names())
['and', 'document', 'first', 'is', 'one', 'second', 'the', 'third', 'this']
>>> print(X.shape)
(4, 9)
```
## Methods

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<th>Method</th>
<th>Description</th>
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<td><code>build_analyzer()</code></td>
<td>Return a callable that handles preprocessing, tokenization and n-grams generation.</td>
</tr>
<tr>
<td><code>build_preprocessor()</code></td>
<td>Return a function to preprocess the text before tokenization.</td>
</tr>
<tr>
<td><code>build_tokenizer()</code></td>
<td>Return a function that splits a string into a sequence of tokens.</td>
</tr>
<tr>
<td><code>decode(doc)</code></td>
<td>Decode the input into a string of unicode symbols.</td>
</tr>
<tr>
<td><code>fit(raw_documents[, y])</code></td>
<td>Learn vocabulary and idf from training set.</td>
</tr>
<tr>
<td><code>fit_transform(raw_documents[, y])</code></td>
<td>Learn vocabulary and idf, return document-term matrix.</td>
</tr>
<tr>
<td><code>get_feature_names()</code></td>
<td>Array mapping from feature integer indices to feature name.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>get_stop_words()</code></td>
<td>Build or fetch the effective stop words list.</td>
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<tr>
<td><code>inverse_transform(X)</code></td>
<td>Return terms per document with nonzero entries in X.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(raw_documents)</code></td>
<td>Transform documents to document-term matrix.</td>
</tr>
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### `build_analyzer()`
Return a callable that handles preprocessing, tokenization and n-grams generation.

**Returns**

- **analyzer**: callable  A function to handle preprocessing, tokenization and n-grams generation.

### `build_preprocessor()`
Return a function to preprocess the text before tokenization.

**Returns**

- **preprocessor**: callable  A function to preprocess the text before tokenization.

### `build_tokenizer()`
Return a function that splits a string into a sequence of tokens.

**Returns**

- **tokenizer**: callable  A function to split a string into a sequence of tokens.

### `decode(doc)`
Decode the input into a string of unicode symbols.

The decoding strategy depends on the vectorizer parameters.

**Parameters**

- **doc**: [str]  The string to decode.

**Returns**

- **doc**: str  A string of unicode symbols.

### `fit(raw_documents[, y])`
Learn vocabulary and idf from training set.

**Parameters**

- **raw_documents**: [array-like]  The raw training data.
- **y**: [array-like]  Class labels for training data (optional).
**raw_documents** [iterable] An iterable which yields either str, unicode or file objects.

**y** [None] This parameter is not needed to compute tfidf.

Returns

**self** [object] Fitted vectorizer.

**fit_transform**(raw_documents, y=None)

Learn vocabulary and idf, return document-term matrix.

This is equivalent to fit followed by transform, but more efficiently implemented.

Parameters

**raw_documents** [iterable] An iterable which yields either str, unicode or file objects.

**y** [None] This parameter is ignored.

Returns

**X** [sparse matrix of (n_samples, n_features)] Tf-idf-weighted document-term matrix.

**get_feature_names**()

Array mapping from feature integer indices to feature name.

Returns

**feature_names** [list] A list of feature names.

**get_params**(deep=True)

Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**get_stop_words**()

Build or fetch the effective stop words list.

Returns

**stop_words:** list or None A list of stop words.

**inverse_transform**(X)

Return terms per document with nonzero entries in X.

Parameters


Returns

**X_inv** [list of arrays of shape (n_samples,)] List of arrays of terms.

**set_params**(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters
**params** [dict] Estimator parameters.

Returns

**self** [estimator instance] Estimator instance.

**transform** *(raw_documents)*

Transform documents to document-term matrix.

Uses the vocabulary and document frequencies (df) learned by fit (or fit_transform).

Parameters

**raw_documents** [iterable] An iterable which yields either str, unicode or file objects.

Returns

**X** [sparse matrix of (n_samples, n_features)] Tf-idf-weighted document-term matrix.

Examples using **sklearn.feature_extraction.text.TfidfVectorizer**

- Biclustering documents with the Spectral Co-clustering algorithm
- Topic extraction with Non-negative Matrix Factorization and Latent Dirichlet Allocation
- Column Transformer with Heterogeneous Data Sources
- Clustering text documents using k-means
- Classification of text documents using sparse features

7.15 **sklearn.feature_selection**: Feature Selection

The **sklearn.feature_selection** module implements feature selection algorithms. It currently includes univariate filter selection methods and the recursive feature elimination algorithm.

User guide: See the **Feature selection** section for further details.

```
feature_selection.GenericUnivariateSelect([...])
feature_selection.SelectPercentile([...])
feature_selection.SelectKBest([score_func, k])
feature_selection.SelectFpr([score_func, alpha])
feature_selection.SelectFdr([score_func, alpha])
feature_selection.SelectFromModel(estimator, *[, ...])
feature_selection.SequentialFeatureSelector(...)
feature_selection.RFE(estimator, *[,...])
```

Filter: Select the p-values below alpha based on a FPR test.
Filter: Select the p-values for an estimated false discovery rate
Meta-transformer for selecting features based on importance weights.
Filter: Select the p-values corresponding to Family-wise error rate
Transformer that performs Sequential Feature Selection.
Feature ranking with recursive feature elimination.

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<td><code>feature_selection.RFECV</code></td>
<td>Feature ranking with recursive feature elimination and cross-validated selection of the best number of features.</td>
</tr>
<tr>
<td><code>feature_selection.VarianceThreshold</code></td>
<td>Feature selector that removes all low-variance features.</td>
</tr>
</tbody>
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7.15.1 `sklearn.feature_selection.GenericUnivariateSelect`

```python
class sklearn.feature_selection.GenericUnivariateSelect (score_func=<function f_classif>, *, mode='percentile', param=1e-05)
```

Univariate feature selector with configurable strategy.

Read more in the User Guide.

Parameters

- **score_func** [callable, default=f_classif] Function taking two arrays X and y, and returning a pair of arrays (scores, pvalues). For modes ‘percentile’ or ‘kbest’ it can return a single array scores.
- **param** [float or int depending on the feature selection mode, default=1e-5] Parameter of the corresponding mode.

Attributes

- **scores_** [array-like of shape (n_features,)] Scores of features.
- **pvalues_** [array-like of shape (n_features,)] p-values of feature scores, None if score_func returned scores only.

See also:

- `f_classif` ANOVA F-value between label/feature for classification tasks.
- `mutual_info_classif` Mutual information for a discrete target.
- `chi2` Chi-squared stats of non-negative features for classification tasks.
- `f_regression` F-value between label/feature for regression tasks.
- `mutual_info_regression` Mutual information for a continuous target.
- `SelectPercentile` Select features based on percentile of the highest scores.
- `SelectKBest` Select features based on the k highest scores.
- `SelectFpr` Select features based on a false positive rate test.
- `SelectFdr` Select features based on an estimated false discovery rate.
- `SelectFwe` Select features based on family-wise error rate.
Examples

```python
code
>>> from sklearn.datasets import load_breast_cancer
>>> X, y = load_breast_cancer(return_X_y=True)
>>> X.shape
(569, 30)
>>> transformer = GenericUnivariateSelect(chi2, mode='k_best', param=20)
>>> X_new = transformer.fit_transform(X, y)
>>> X_new.shape
(569, 20)
```

Methods

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<td><code>fit(X, y)</code></td>
<td>Run score function on (X, y) and get the appropriate features.</td>
</tr>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>get_support([indices])</code></td>
<td>Get a mask, or integer index, of the features selected.</td>
</tr>
<tr>
<td><code>inverse_transform(X)</code></td>
<td>Reverse the transformation operation.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

### fit(X, y)
Run score function on (X, y) and get the appropriate features.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] The training input samples.
- **y** [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

**Returns**

- **self** [object]

### fit_transform(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,)] or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

### get_params(deep=True)
Get parameters for this estimator.
Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

### get_support (**indices**=False)

Get a mask, or integer index, of the features selected

#### Parameters

- **indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

#### Returns

- **support** [array] An index that selects the retained features from a feature vector. If **indices** is False, this is a boolean array of shape [ # input features], in which an element is True iff its corresponding feature is selected for retention. If **indices** is True, this is an integer array of shape [ # output features] whose values are indices into the input feature vector.

### inverse_transform (**X**) 

Reverse the transformation operation

#### Parameters

- **X** [array of shape [n_samples, n_features]] The input samples.

#### Returns

- **X_r** [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

### set_params (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

#### Parameters

- **params** [dict] Estimator parameters.

#### Returns

- **self** [estimator instance] Estimator instance.

### transform (**X**) 

Reduce X to the selected features.

#### Parameters

- **X** [array of shape [n_samples, n_features]] The input samples.

#### Returns

- **X_r** [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.
7.15.2 sklearn.feature_selection.SelectPercentile

class sklearn.feature_selection.SelectPercentile(score_func=<function f_classif>, *,
percentile=10)

Select features according to a percentile of the highest scores.

Parameters

score_func [callable, default=f_classif] Function taking two arrays X and y, and returning a
pair of arrays (scores, pvalues) or a single array with scores. Default is f_classif (see below
“See Also”). The default function only works with classification tasks.

New in version 0.18.

percentile [int, default=10] Percent of features to keep.

Attributes

scores_ [array-like of shape (n_features,)] Scores of features.

pvalues_ [array-like of shape (n_features,)] p-values of feature scores, None if score_func
returned only scores.

See also:

f_classif ANOVA F-value between label/feature for classification tasks.

mutual_info_classif Mutual information for a discrete target.

chi2 Chi-squared stats of non-negative features for classification tasks.

f_regression F-value between label/feature for regression tasks.

mutual_info_regression Mutual information for a continuous target.

SelectKBest Select features based on the k highest scores.

SelectFpr Select features based on a false positive rate test.

SelectFdr Select features based on an estimated false discovery rate.

SelectFwe Select features based on family-wise error rate.

GenericUnivariateSelect Univariate feature selector with configurable mode.

Notes

Ties between features with equal scores will be broken in an unspecified way.

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.feature_selection import SelectPercentile, chi2
>>> X, y = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)
>>> X_new = SelectPercentile(chi2, percentile=10).fit_transform(X, y)
>>> X_new.shape
(1797, 7)
```
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<td>fit_transform(X[, y])</td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>get_support([indices])</td>
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</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Reduce X to the selected features.</td>
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</tbody>
</table>

#### fit(X, y)

Run score function on (X, y) and get the appropriate features.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] The training input samples.
- **y** [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

**Returns**

- **self** [object]

#### fit_transform(X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

#### get_params(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

#### get_support(indices=False)

Get a mask, or integer index, of the features selected

**Parameters**

- **indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.
Returns

support [array] An index that selects the retained features from a feature vector. If indices is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If indices is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

inverse_transform(X)
Reverse the transformation operation

Parameters

X [array of shape [n_samples, n_selected_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform(X)
Reduce X to the selected features.

Parameters

X [array of shape [n_samples, n_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

Examples using sklearn.feature_selection.SelectPercentile

- Feature agglomeration vs. univariate selection
- SVM-Anova: SVM with univariate feature selection
7.15.3 sklearn.feature_selection.SelectKBest

**class sklearn.feature_selection.SelectKBest(score_func=<function f_classif>, *, k=10)**

Select features according to the k highest scores.

Read more in the User Guide.

**Parameters**

- **score_func** [callable, default=f_classif] Function taking two arrays X and y, and returning a pair of arrays (scores, pvalues) or a single array with scores. Default is f_classif (see below “See Also”). The default function only works with classification tasks.

  New in version 0.18.

- **k** [int or “all”, default=10] Number of top features to select. The “all” option bypasses selection, for use in a parameter search.

**Attributes**

- **scores_** [array-like of shape (n_features,)] Scores of features.

- **pvalues_** [array-like of shape (n_features,)] p-values of feature scores, None if score_func returned only scores.

See also:

- `f_classif` ANOVA F-value between label/feature for classification tasks.
- `mutual_info_classif` Mutual information for a discrete target.
- `chi2` Chi-squared stats of non-negative features for classification tasks.
- `f_regression` F-value between label/feature for regression tasks.
- `mutual_info_regression` Mutual information for a continuous target.
- `SelectPercentile` Select features based on percentile of the highest scores.
- `SelectFpr` Select features based on a false positive rate test.
- `SelectFdr` Select features based on an estimated false discovery rate.
- `SelectFwe` Select features based on family-wise error rate.
- `GenericUnivariateSelect` Univariate feature selector with configurable mode.

**Notes**

Ties between features with equal scores will be broken in an unspecified way.

**Examples**

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.feature_selection import SelectKBest, chi2
>>> X, y = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)
>>> X_new = SelectKBest(chi2, k=20).fit_transform(X, y)
>>> X_new.shape
(1797, 20)
```
## Methods

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<td><code>inverse_transform(X)</code></td>
<td>Reverse the transformation operation</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

### fit (X, y)
Run score function on (X, y) and get the appropriate features.

**Parameters**
- **X** [array-like of shape (n_samples, n_features)] The training input samples.
- **y** [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

**Returns**
- **self** [object]

### fit_transform (X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**
- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Returns**
- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

### get_params (deep=True)
Get parameters for this estimator.

**Parameters**
- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- **params** [dict] Parameter names mapped to their values.

### get_support (indices=False)
Get a mask, or integer index, of the features selected

**Parameters**
- **indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.
Returns

**support** [array] An index that selects the retained features from a feature vector. If **indices** is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If **indices** is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

**inverse_transform**(*X*)
Reverse the transformation operation

**Parameters**

*X* [array of shape [n_samples, n_selected_features]] The input samples.

**Returns**

*X_r* [array of shape [n_samples, n_original_features]] *X* with columns of zeros inserted where features would have been removed by **transform**.

**set_params**(**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as **Pipeline**). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(*X*)
Reduce *X* to the selected features.

**Parameters**

*X* [array of shape [n_samples, n_features]] The input samples.

**Returns**

*X_r* [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

**Examples using sklearn.feature_selection.SelectKBest**

- **Pipeline Anova SVM**
- **Univariate Feature Selection**
- **Concatenating multiple feature extraction methods**
- **Selecting dimensionality reduction with Pipeline and GridSearchCV**
- **Classification of text documents using sparse features**
7.15.4 sklearn.feature_selection.SelectFpr

class sklearn.feature_selection.SelectFpr(score_func=<function f_classif>, *, alpha=0.05)

Filter: Select the pvalues below alpha based on a FPR test.

FPR test stands for False Positive Rate test. It controls the total amount of false detections.

Read more in the User Guide.

Parameters

score_func [callable, default=f_classif] Function taking two arrays X and y, and returning a pair of arrays (scores, pvalues). Default is f_classif (see below “See Also”). The default function only works with classification tasks.

alpha [float, default=5e-2] The highest p-value for features to be kept.

Attributes

scores_ [array-like of shape (n_features,)] Scores of features.

pvalues_ [array-like of shape (n_features,)] p-values of feature scores.

See also:

f_classif ANOVA F-value between label/feature for classification tasks.

chi2 Chi-squared stats of non-negative features for classification tasks.

mutual_info_classif Mutual information for a discrete target.

f_regression F-value between label/feature for regression tasks.

mutual_info_regression Mutual information for a continuous target.

SelectPercentile Select features based on percentile of the highest scores.

SelectKBest Select features based on the k highest scores.

SelectFdr Select features based on an estimated false discovery rate.

SelectFwe Select features based on family-wise error rate.

GenericUnivariateSelect Univariate feature selector with configurable mode.

Examples

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.feature_selection import SelectFpr, chi2
>>> X, y = load_breast_cancer(return_X_y=True)
>>> X.shape
(569, 30)
>>> X_new = SelectFpr(chi2, alpha=0.01).fit_transform(X, y)
>>> X_new.shape
(569, 16)
```
Methods

<table>
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<td>Run score function on (X, y) and get the appropriate features.</td>
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<td>Fit to data, then transform it.</td>
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<tr>
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<td>inverse_transform(X)</td>
<td>Reverse the transformation operation.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Reduce X to the selected features.</td>
</tr>
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</table>

**fit (X, y)**

Run score function on (X, y) and get the appropriate features.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The training input samples.
- y [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

**Returns**

- self [object]

**fit_transform (X, y=None, **fit_params)**

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Input samples.
- y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

**Returns**

- X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**get_support (indices=False)**

Get a mask, or integer index, of the features selected.

**Parameters**

- indices [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.
Returns

**support** [array] An index that selects the retained features from a feature vector. If **indices** is False, this is a boolean array of shape [# input features], in which an element is True if its corresponding feature is selected for retention. If **indices** is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

**inverse_transform** (X)

Reverse the transformation operation

**Parameters**

X [array of shape [n_samples, n_selected_features]] The input samples.

**Returns**

X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

**set_params**(**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(X)

Reduce X to the selected features.

**Parameters**

X [array of shape [n_samples, n_features]] The input samples.

**Returns**

X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

**7.15.5 sklearn.feature_selection.SelectFdr**

**class sklearn.feature_selection.SelectFdr**(score_func=<function f_classif>, *, alpha=0.05)

Filter: Select the p-values for an estimated false discovery rate

This uses the Benjamini-Hochberg procedure. alpha is an upper bound on the expected false discovery rate.

Read more in the User Guide.

**Parameters**

**score_func** [callable, default=f_classif] Function taking two arrays X and y, and returning a pair of arrays (scores, pvalues). Default is f_classif (see below “See Also”). The default function only works with classification tasks.

**alpha** [float, default=5e-2] The highest uncorrected p-value for features to keep.
Attributes

scores_  [array-like of shape (n_features,)] Scores of features.
pvalues_  [array-like of shape (n_features,)] p-values of feature scores.

See also:

f_classif  ANOVA F-value between label/feature for classification tasks.
mutual_info_classif  Mutual information for a discrete target.
chi2  Chi-squared stats of non-negative features for classification tasks.
f_regression  F-value between label/feature for regression tasks.
mutual_info_regression  Mutual information for a continuous target.
SelectPercentile  Select features based on percentile of the highest scores.
SelectKBest  Select features based on the k highest scores.
SelectFpr  Select features based on a false positive rate test.
SelectFwe  Select features based on family-wise error rate.
GenericUnivariateSelect  Univariate feature selector with configurable mode.

References

https://en.wikipedia.org/wiki/False_discovery_rate

Examples

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.feature_selection import SelectFdr, chi2
>>> X, y = load_breast_cancer(return_X_y=True)
>>> X.shape
(569, 30)
>>> X_new = SelectFdr(chi2, alpha=0.01).fit_transform(X, y)
>>> X_new.shape
(569, 16)
```

Methods

```python
fit(X, y)  Run score function on (X, y) and get the appropriate features.
fit_transform(X[, y])  Fit to data, then transform it.
get_params([deep])  Get parameters for this estimator.
get_support([indices])  Get a mask, or integer index, of the features selected
inverse_transform(X)  Reverse the transformation operation
set_params(**params)  Set the parameters of this estimator.
transform(X)  Reduce X to the selected features.
```

```python
fit (X, y)
Run score function on (X, y) and get the appropriate features.
```
Parameters

X [array-like of shape (n_samples, n_features)] The training input samples.

y [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

Returns

self [object]

fit_transform (X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)

Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

get_support (indices=False)

Get a mask, or integer index, of the features selected.

Parameters

indices [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

Returns

support [array] An index that selects the retained features from a feature vector. If indices is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If indices is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

inverse_transform (X)

Reverse the transformation operation.

Parameters

X [array of shape [n_samples, n_selected_features]] The input samples.

Returns
X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Reduce X to the selected features.

Parameters

X [array of shape [n_samples, n_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

7.15.6 sklearn.feature_selection.SelectFromModel

class sklearn.feature_selection.SelectFromModel (estimator, *, threshold=None, prefit=False, norm_order=1, max_features=None, importance_getter='auto')

Meta-transformer for selecting features based on importance weights.
New in version 0.17.
Read more in the User Guide.

Parameters

estimator [object] The base estimator from which the transformer is built. This can be both a fitted (if prefit is set to True) or a non-fitted estimator. The estimator must have either a feature_importances_ or coef_ attribute after fitting.

threshold [string or float, default=None] The threshold value to use for feature selection. Features whose importance is greater or equal are kept while the others are discarded. If “median” (resp. “mean”), then the threshold value is the median (resp. the mean) of the feature importances. A scaling factor (e.g., “1.25*mean”) may also be used. If None and if the estimator has a parameter penalty set to l1, either explicitly or implicitly (e.g, Lasso), the threshold used is 1e-5. Otherwise, “mean” is used by default.

prefit [bool, default=False] Whether a prefit model is expected to be passed into the constructor directly or not. If True, transform must be called directly and SelectFromModel cannot be used with cross_val_score, GridSearchCV and similar utilities that clone the estimator. Otherwise train the model using fit and then transform to do feature selection.
**norm_order** [non-zero int, inf, -inf, default=1] Order of the norm used to filter the vectors of coefficients below threshold in the case where the coef_ attribute of the estimator is of dimension 2.

**max_features** [int, default=None] The maximum number of features to select. To only select based on max_features, set threshold=-np.inf.

New in version 0.20.

**importance_getter** [str or callable, default='auto'] If ‘auto’, uses the feature importance either through a coef_ attribute or feature_importances_ attribute of estimator.

Also accepts a string that specifies an attribute name/path for extracting feature importance (implemented with attrgetter). For example, give regressor_.coef_ in case of TransformedTargetRegressor or named_steps.clf.feature_importances_ in case of Pipeline with its last step named clf.

If callable, overrides the default feature importance getter. The callable is passed with the fitted estimator and it should return importance for each feature.

New in version 0.24.

**Attributes**

**estimator_** [an estimator] The base estimator from which the transformer is built. This is stored only when a non-fitted estimator is passed to the SelectFromModel, i.e when prefit is False.

**threshold_** [float] The threshold value used for feature selection.

See also:

**RFE** Recursive feature elimination based on importance weights.

**RFECV** Recursive feature elimination with built-in cross-validated selection of the best number of features.

**SequentialFeatureSelector** Sequential cross-validation based feature selection. Does not rely on importance weights.

**Notes**

Allows NaN/Inf in the input if the underlying estimator does as well.

**Examples**

```python
>>> from sklearn.feature_selection import SelectFromModel
>>> from sklearn.linear_model import LogisticRegression
>>> X = [[ 0.87, -1.34, 0.31 ],
...      [-2.79, -0.02, -0.85 ],
...      [-1.34, -0.48, -2.55 ],
...      [ 1.92, 1.48, 0.65 ]]
>>> y = [0, 1, 0, 1]
>>> selector = SelectFromModel(estimator=LogisticRegression()).fit(X, y)
>>> selector.estimator_.coef_
array([[ 0.3252302 , 0.83462377, 0.49750423]])
>>> selector.threshold_
0.55245...
>>> selector.get_support()
array([False,  True, False])
```
Methods

- **fit**(X[, y])
  Fit the SelectFromModel meta-transformer.

- **fit_transform**(X[, y])
  Fit to data, then transform it.

- **get_params**(deep=False)
  Get parameters for this estimator.

- **get_support**(indices)
  Get a mask, or integer index, of the features selected

- **inverse_transform**(X)
  Reverse the transformation operation

- **partial_fit**(X[, y])
  Fit the SelectFromModel meta-transformer only once.

- **set_params**(**params)
  Set the parameters of this estimator.

- **transform**(X)
  Reduce X to the selected features.

**fit**(X, y=None, **fit_params)
Fit the SelectFromModel meta-transformer.

**Parameters**

X [array-like of shape (n_samples, n_features)] The training input samples.

y [array-like of shape (n_samples,), default=None] The target values (integers that correspond to classes in classification, real numbers in regression).

**fit_params** [Other estimator specific parameters]

**Returns**

self [object]

**fit_transform**(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

**Returns**

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**get_support** *(indices=False)*

Get a mask, or integer index, of the features selected

**Parameters**

**indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

**Returns**

**support** [array] An index that selects the retained features from a feature vector. If **indices** is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If **indices** is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

**inverse_transform** *(X)*

Reverse the transformation operation

**Parameters**

**X** [array of shape [n_samples, n_selected_features]] The input samples.

**Returns**

**X_r** [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by **transform**.

**partial_fit** *(X, y=None, **fit_params)*

Fit the SelectFromModel meta-transformer only once.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] The training input samples.

**y** [array-like of shape (n_samples,), default=None] The target values (integers that correspond to classes in classification, real numbers in regression).

****fit_params** [Other estimator specific parameters]

**Returns**

**self** [object]

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as **Pipeline**). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

****params** [dict] Estimator parameters.

**Returns**

**self** [estimator instance] Estimator instance.
transform \((X)\)
Reduce \(X\) to the selected features.

**Parameters**

\(X\) [array of shape [n_samples, n_features]] The input samples.

**Returns**

\(X_r\) [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

**Examples using sklearn.feature_selection.SelectFromModel**

- Model-based and sequential feature selection
- Classification of text documents using sparse features

### 7.15.7 sklearn.feature_selection.SelectFwe

**class** sklearn.feature_selection.SelectFwe(score_func=\(<f\text{\_classif}\>, \alpha=0.05)\)
Filter: Select the p-values corresponding to Family-wise error rate

Read more in the User Guide.

**Parameters**

- **score_func** [callable, default=f_classif] Function taking two arrays \(X\) and \(y\), and returning a pair of arrays (scores, pvalues). Default is f_classif (see below “See Also”). The default function only works with classification tasks.
- **alpha** [float, default=5e-2] The highest uncorrected p-value for features to keep.

**Attributes**

- **scores_** [array-like of shape (n_features,)] Scores of features.
- **pvalues_** [array-like of shape (n_features,)] p-values of feature scores.

**See also:**

- f_classif ANOVA F-value between label/feature for classification tasks.
- chi2 Chi-squared stats of non-negative features for classification tasks.
- f_regression F-value between label/feature for regression tasks.
- SelectPercentile Select features based on percentile of the highest scores.
- SelectKBest Select features based on the k highest scores.
- SelectFpr Select features based on a false positive rate test.
- SelectFdr Select features based on an estimated false discovery rate.
- GenericUnivariateSelect Univariate feature selector with configurable mode.
Examples

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.feature_selection import SelectFwe, chi2

>>> X, y = load_breast_cancer(return_X_y=True)

>>> X.shape
(569, 30)

>>> X_new = SelectFwe(chi2, alpha=0.01).fit_transform(X, y)

>>> X_new.shape
(569, 15)
```

Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tr>
<td><code>fit(X, y)</code></td>
<td>Run score function on (X, y) and get the appropriate features.</td>
</tr>
<tr>
<td><code>fit_transform(X, y)</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>get_support([indices])</code></td>
<td>Get a mask, or integer index, of the features selected.</td>
</tr>
<tr>
<td><code>inverse_transform(X)</code></td>
<td>Reverse the transformation operation</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

**fit(X, y)**

Run score function on (X, y) and get the appropriate features.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] The training input samples.
- `y` [array-like of shape (n_samples,)] The target values (class labels in classification, real numbers in regression).

**Returns**

- `self` [object]

**fit_transform(X, y=None, **fit_params)**

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Additional fit parameters** [dict] Additional fit parameters.

**Returns**

- `X_new` [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params(deep=True)**

Get parameters for this estimator.

**Parameters**

- `deep` [boolean] If True, will return the parameters for this estimator and contained subobjects that are estimators.
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

get_support (indices=False)
Get a mask, or integer index, of the features selected

Parameters

indices [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

Returns

support [array] An index that selects the retained features from a feature vector. If indices is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If indices is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

inverse_transform (X)
Reverse the transformation operation

Parameters

X [array of shape [n_samples, n_selected_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Reduce X to the selected features.

Parameters

X [array of shape [n_samples, n_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.
Transformer that performs Sequential Feature Selection.

This Sequential Feature Selector adds (forward selection) or removes (backward selection) features to form a feature subset in a greedy fashion. At each stage, this estimator chooses the best feature to add or remove based on the cross-validation score of an estimator.

Read more in the User Guide.

New in version 0.24.

Parameters

- **estimator** [estimator instance] An unfitted estimator.
- **n_features_to_select** [int or float, default=None] The number of features to select. If **None**, half of the features are selected. If integer, the parameter is the absolute number of features to select. If float between 0 and 1, it is the fraction of features to select.
- **direction**: {'forward', 'backward'}, default='forward' Whether to perform forward selection or backward selection.
- **scoring** [str, callable, list/tuple or dict, default=None] A single str (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set.

  NOTE that when using custom scorers, each scorer should return a single value. Metric functions returning a list/array of values can be wrapped into multiple scorers that return one value each.

  If None, the estimator's score method is used.

- **cv** [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross validation,
  - integer, to specify the number of folds in a *(Stratified)*KFold,
  - *CV splitter*,
  - An iterable yielding (train, test) splits as arrays of indices.

  For integer/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

  Refer User Guide for the various cross-validation strategies that can be used here.

- **n_jobs** [int, default=None] Number of jobs to run in parallel. When evaluating a new feature to add or remove, the cross-validation procedure is parallel over the folds. **None** means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

- **n_features_to_select_** [int] The number of features that were selected.
- **support_** [ndarray of shape (n_features,), dtype=bool] The mask of selected features.
See also:

**RFE** Recursive feature elimination based on importance weights.

**RFECV** Recursive feature elimination based on importance weights, with automatic selection of the number of features.

**SelectFromModel** Feature selection based on thresholds of importance weights.

### Examples

```python
>>> from sklearn.feature_selection import SequentialFeatureSelector
>>> from sklearn.neighbors import KNeighborsClassifier
>>> from sklearn.datasets import load_iris

>>> X, y = load_iris(return_X_y=True)
>>> knn = KNeighborsClassifier(n_neighbors=3)
>>> sfs = SequentialFeatureSelector(knn, n_features_to_select=3)
>>> sfs.fit(X, y)
SequentialFeatureSelector(estimator=KNeighborsClassifier(n_neighbors=3),
                         n_features_to_select=3)
>>> sfs.get_support()
array([ True, False, True, True])
>>> sfs.transform(X).shape
(150, 3)
```

### Methods

- **fit** *(X, y)*
  Learn the features to select.

- **fit_transform** *(X[, y]*)
  Fit to data, then transform it.

- **get_params** *(deep)*
  Get parameters for this estimator.

- **get_support** *(indices)*
  Get a mask, or integer index, of the features selected.

- **inverse_transform** *(X)*
  Reverse the transformation operation.

- **set_params** *(**params)*
  Set the parameters of this estimator.

- **transform** *(X)*
  Reduce X to the selected features.

**fit** *(X, y)*

Learn the features to select.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training vectors.
- **y** [array-like of shape (n_samples,)] Target values.

**Returns**

- **self** [object]

**fit_transform** *(X, y=None, **fit_params)*

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
**y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

**Returns**

**X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**get_support**(indices=False)
Get a mask, or integer index, of the features selected

**Parameters**

**indices** [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

**Returns**

**support** [array] An index that selects the retained features from a feature vector. If **indices** is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If **indices** is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

**inverse_transform**(X)
Reverse the transformation operation

**Parameters**

**X** [array of shape [n_samples, n_selected_features]] The input samples.

**Returns**

**X_r** [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by **transform**.

**set_params**(**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as **Pipeline**). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

**self** [estimator instance] Estimator instance.

**transform**(X)
Reduce X to the selected features.
Parameters

X  [array of shape [n_samples, n_features]] The input samples.

Returns

X_r  [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

Examples using sklearn.feature_selection.SequentialFeatureSelector

• Release Highlights for scikit-learn 0.24
• Model-based and sequential feature selection

7.15.9 sklearn.feature_selection.RFE

class sklearn.feature_selection.RFE(estimator, *, n_features_to_select=None, step=1, verbose=0, importance_getter='auto')

Feature ranking with recursive feature elimination.

Given an external estimator that assigns weights to features (e.g., the coefficients of a linear model), the goal of recursive feature elimination (RFE) is to select features by recursively considering smaller and smaller sets of features. First, the estimator is trained on the initial set of features and the importance of each feature is obtained either through any specific attribute or callable. Then, the least important features are pruned from current set of features. That procedure is recursively repeated on the pruned set until the desired number of features to select is eventually reached.

Read more in the User Guide.

Parameters

estimator  [Estimator instance] A supervised learning estimator with a fit method that provides information about feature importance (e.g. coef_, feature_importances_).

n_features_to_select  [int or float, default=None] The number of features to select. If None, half of the features are selected. If integer, the parameter is the absolute number of features to select. If float between 0 and 1, it is the fraction of features to select.

Changed in version 0.24: Added float values for fractions.

step  [int or float, default=1] If greater than or equal to 1, then step corresponds to the (integer) number of features to remove at each iteration. If within (0.0, 1.0), then step corresponds to the percentage (rounded down) of features to remove at each iteration.

verbose  [int, default=0] Controls verbosity of output.

importance_getter  [str or callable, default=’auto’] If ‘auto’, uses the feature importance either through a coef_ or feature_importances_ attributes of estimator.

Also accepts a string that specifies an attribute name/path for extracting feature importance (implemented with attrgetter). For example, give regressor_.coef_ in case of TransformedTargetRegressor or named_steps.clf.feature_importances_ in case of class~sklearn.pipeline.Pipeline with its last step named clf.

If callable, overrides the default feature importance getter. The callable is passed with the fitted estimator and it should return importance for each feature.

New in version 0.24.
Attributes

- **estimator_**: [Estimator instance] The fitted estimator used to select features.
- **n_features_**: [int] The number of selected features.
- **ranking_**: [ndarray of shape (n_features,)] The feature ranking, such that `ranking_[i]` corresponds to the ranking position of the i-th feature. Selected (i.e., estimated best) features are assigned rank 1.
- **support_**: [ndarray of shape (n_features,)] The mask of selected features.

See also:

- **RFECV**: Recursive feature elimination with built-in cross-validated selection of the best number of features.
- **SelectFromModel**: Feature selection based on thresholds of importance weights.
- **SequentialFeatureSelector**: Sequential cross-validation based feature selection. Does not rely on importance weights.

Notes

Allows NaN/Inf in the input if the underlying estimator does as well.

References

[1]

Examples

The following example shows how to retrieve the 5 most informative features in the Friedman #1 dataset.

```python
generate code here...
```
Methods

<table>
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<td>Compute the decision function of X.</td>
</tr>
<tr>
<td>fit(X, y)</td>
<td>Fit the RFE model and then the underlying estimator on the selected features.</td>
</tr>
<tr>
<td>fit_transform(X, y)</td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>get_support([indices])</td>
<td>Get a mask, or integer index, of the features selected.</td>
</tr>
<tr>
<td>inverse_transform(X)</td>
<td>Reverse the transformation operation</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Reduce X to the selected features and then predict using the</td>
</tr>
<tr>
<td>predict_log_proba(X)</td>
<td>Predict class log-probabilities for X.</td>
</tr>
<tr>
<td>predict_proba(X)</td>
<td>Predict class probabilities for X.</td>
</tr>
<tr>
<td>score(X, y)</td>
<td>Reduce X to the selected features and then return the score of the</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

decision_function(X)

Compute the decision function of X.

Parameters

- **X** ([array-like or sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, it will be converted to `dtype=np.float32` and if a sparse matrix is provided to a sparse `csr_matrix`.

Returns

- **score** ([array, shape = [n_samples, n_classes] or [n_samples]]) The decision function of the input samples. The order of the classes corresponds to that in the attribute `classes_`. Regression and binary classification produce an array of shape [n_samples].

fit(X, y)

Fit the RFE model and then the underlying estimator on the selected features.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The training input samples.
- **y** ([array-like of shape (n_samples,)]) The target values.

fit_transform(X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

Parameters

- **X** ([array-like of shape (n_samples, n_features)]) Input samples.
- **y** ([array-like of shape (n_samples,)] or (n_samples, n_outputs), default=None) Target values (None for unsupervised transformations).

**fit_params** ([dict] Additional fit parameters.

Returns
X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters
dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

get_support (indices=False)
Get a mask, or integer index, of the features selected

Parameters
indices [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

Returns
support [array] An index that selects the retained features from a feature vector. If indices is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If indices is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

inverse_transform (X)
Reverse the transformation operation

Parameters
X [array of shape [n_samples, n_selected_features]] The input samples.

Returns
X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

predict (X)
Reduce X to the selected features and then predict using the underlying estimator.

Parameters
X [array of shape [n_samples, n_features]] The input samples.

Returns
y [array of shape [n_samples]] The predicted target values.

predict_log_proba (X)
Predict class log-probabilities for X.

Parameters
X [array of shape [n_samples, n_features]] The input samples.

Returns
p [array of shape (n_samples, n_classes)] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

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**predict_proba** *(X)*
Predict class probabilities for X.

**Parameters**

- **X** ([array-like or sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, it will be converted to `dtype=np.float32` and if a sparse matrix is provided to a sparse `csr_matrix`.

**Returns**

- **p** [array of shape (n_samples, n_classes)] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute `classes_`.

**score** *(X, y)*
Reduce X to the selected features and then return the score of the underlying estimator.

**Parameters**

- **X** [array of shape [n_samples, n_features]] The input samples.
- **y** [array of shape [n_samples]] The target values.

**set_params** (**params**)
Set the parameters of this estimator.

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**transform** *(X)*
Reduce X to the selected features.

**Parameters**

- **X** [array of shape [n_samples, n_features]] The input samples.

**Returns**

- **X_r** [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

**Examples using sklearn.feature_selection.RFE**

- Recursive feature elimination
7.15.10 sklearn.feature_selection.RFECV

class sklearn.feature_selection.RFECV(estimator, *, step=1, min_features_to_select=1, cv=None, scoring=None, verbose=0, n_jobs=None, importance_getter='auto')

Feature ranking with recursive feature elimination and cross-validated selection of the best number of features.

See glossary entry for cross-validation estimator.

Read more in the User Guide.

Parameters

estimator [Estimator instance] A supervised learning estimator with a fit method that provides information about feature importance either through a coef_ attribute or through a feature_importances_ attribute.

step [int or float, default=1] If greater than or equal to 1, then step corresponds to the (integer) number of features to remove at each iteration. If within (0.0, 1.0), then step corresponds to the percentage (rounded down) of features to remove at each iteration. Note that the last iteration may remove fewer than step features in order to reach min_features_to_select.

min_features_to_select [int, default=1] The minimum number of features to be selected. This number of features will always be scored, even if the difference between the original feature count and min_features_to_select isn’t divisible by step.

New in version 0.20.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

• None, to use the default 5-fold cross-validation,

• integer, to specify the number of folds.

• CV splitter,

• An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if y is binary or multiclass, StratifiedKFold is used. If the estimator is a classifier or if y is neither binary nor multiclass, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value of None changed from 3-fold to 5-fold.

scoring [string, callable or None, default=None] A string (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y).

verbose [int, default=0] Controls verbosity of output.

n_jobs [int or None, default=None] Number of cores to run in parallel while fitting across folds. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

New in version 0.18.

importance_getter [str or callable, default=’auto’] If ‘auto’, uses the feature importance either through a coef_ or feature_importances_ attributes of estimator.

Also accepts a string that specifies an attribute name/path for extracting feature importance. For example, give regressor_.coef_ in case of TransformedTargetRegressor or named_steps.clf.feature_importances_ in case of Pipeline with its last step named clf.
If `callable`, overrides the default feature importance getter. The callable is passed with the fitted estimator and it should return importance for each feature.

New in version 0.24.

Attributes

- `estimator_` [Estimator instance] The fitted estimator used to select features.
- `grid_scores_` [ndarray of shape (n_subsets_of_features,)] The cross-validation scores such that `grid_scores_[i]` corresponds to the CV score of the i-th subset of features.
- `n_features_` [int] The number of selected features with cross-validation.
- `ranking_` [ndarray of shape (n_features,)] The feature ranking, such that `ranking_[i]` corresponds to the ranking position of the i-th feature. Selected (i.e., estimated best) features are assigned rank 1.
- `support_` [ndarray of shape (n_features,)] The mask of selected features.

See also:

- **RFE** Recursive feature elimination.

Notes

The size of `grid_scores_` is equal to \( \text{ceil}((\text{n_features} - \text{min_features_to_select}) / \text{step}) + 1 \), where step is the number of features removed at each iteration.

Allows NaN/Inf in the input if the underlying estimator does as well.

References

[1]

Examples

The following example shows how to retrieve the a-priori not known 5 informative features in the Friedman #1 dataset.

```python
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.feature_selection import RFECV
>>> from sklearn.svm import SVR

>>> X, y = make_friedman1(n_samples=50, n_features=10, random_state=0)
>>> estimator = SVR(kernel="linear")
>>> selector = RFECV(estimator, step=1, cv=5)
>>> selector = selector.fit(X, y)
>>> selector.support_
array([True, True, True, True, True, False, False, False, False, False])
>>> selector.ranking_
array([1, 1, 1, 1, 1, 6, 4, 3, 2, 5])
```
Methods

<table>
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<tr>
<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td><code>decision_function(X)</code></td>
<td>Compute the decision function of X.</td>
</tr>
<tr>
<td><code>fit(X, y[, groups])</code></td>
<td>Fit the RFE model and automatically tune the number of selected features.</td>
</tr>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>get_support([indices])</code></td>
<td>Get a mask, or integer index, of the features selected.</td>
</tr>
<tr>
<td><code>inverse_transform(X)</code></td>
<td>Reverse the transformation operation</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Reduce X to the selected features and then predict using the</td>
</tr>
<tr>
<td><code>predict_log_proba(X)</code></td>
<td>Predict class log-probabilities for X.</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Predict class probabilities for X.</td>
</tr>
<tr>
<td><code>score(X, y)</code></td>
<td>Reduce X to the selected features and then return the score of the</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Reduce X to the selected features.</td>
</tr>
</tbody>
</table>

`decision_function(X)`
Compute the decision function of X.

Parameters

- **X**
  - `array-like` or sparse matrix of shape `(n_samples, n_features)` The input samples. Internally, it will be converted to `dtype=np.float32` and if a sparse matrix is provided to a sparse `csr_matrix`.

Returns

- **score**
  - array, shape = `[n_samples, n_classes]` or `[n_samples]` The decision function of the input samples. The order of the classes corresponds to that in the attribute `classes_`. Regression and binary classification produce an array of shape `[n_samples]`.

`fit(X, y, groups=None)`
Fit the RFE model and automatically tune the number of selected features.

Parameters

- **X**
  - `array-like` or sparse matrix of shape `(n_samples, n_features)` Training vector, where `n_samples` is the number of samples and `n_features` is the total number of features.

- **y**
  - `array-like` of shape `(n_samples,)` Target values (integers for classification, real numbers for regression).

- **groups**
  - `array-like` of shape `(n_samples,)` or None, default=None) Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a "Group" `cv` instance (e.g., `GroupKFold`).

New in version 0.20.

`fit_transform(X, y=None, **fit_params)`
Fit to data, then transform it.

Fits transformer to `X` and `y` with optional parameters `fit_params` and returns a transformed version of `X`.

Parameters
X [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values
(Non for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

dep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

generate_support (indices=False)
Get a mask, or integer index, of the features selected

Parameters

indices [bool, default=False] If True, the return value will be an array of integers, rather than
a boolean mask.

Returns

support [array] An index that selects the retained features from a feature vector. If
indices is False, this is a boolean array of shape [# input features], in which an ele-
ment is True iff its corresponding feature is selected for retention. If indices is True,
this is an integer array of shape [# output features] whose values are indices into the input
feature vector.

inverse_transform (X)
Reverse the transformation operation

Parameters

X [array of shape [n_samples, n_selected_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted
where features would have been removed by transform.

predict (X)
Reduce X to the selected features and then predict using the underlying estimator.

Parameters

X [array of shape [n_samples, n_features]] The input samples.

Returns

y [array of shape [n_samples]] The predicted target values.

predict_log_proba (X)
Predict class log-probabilities for X.
Parameters

\(X\) [array of shape \([n_{\text{samples}}, n_{\text{features}}]\)] The input samples.

Returns

\(p\) [array of shape \((n_{\text{samples}}, n_{\text{classes}})\)] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute \(\text{classes}_-\).

\texttt{predict\_proba}(X)

Predict class probabilities for \(X\).

Parameters

\(X\) [[array-like or sparse matrix] of shape \((n_{\text{samples}}, n_{\text{features}})\)] The input samples. Internally, it will be converted to \texttt{dtype=np.float32} and if a sparse matrix is provided to a sparse \texttt{csr\_matrix}.

Returns

\(p\) [array of shape \((n_{\text{samples}}, n_{\text{classes}})\)] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute \(\text{classes}_-\).

\texttt{score}(X, y)

Reduce \(X\) to the selected features and then return the score of the underlying estimator.

Parameters

\(X\) [array of shape \([n_{\text{samples}}, n_{\text{features}}]\)] The input samples.

\(y\) [array of shape \([n_{\text{samples}}]\)] The target values.

\texttt{set\_params}(**\texttt{params})

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \texttt{Pipeline}). The latter have parameters of the form \(<\text{component}>\_\_<\text{parameter}>\) so that it’s possible to update each component of a nested object.

Parameters

**\texttt{params} [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

\texttt{transform}(X)

Reduce \(X\) to the selected features.

Parameters

\(X\) [array of shape \([n_{\text{samples}}, n_{\text{features}}]\)] The input samples.

Returns

\(X_r\) [array of shape \([n_{\text{samples}}, n_{\text{selected\_features}}]\)] The input samples with only the selected features.
Examples using `sklearn.feature_selection.RFECV`

- Recursive feature elimination with cross-validation

### 7.15.11 `sklearn.feature_selection.VarianceThreshold`

class `sklearn.feature_selection.VarianceThreshold(threshold=0.0)`

Feature selector that removes all low-variance features.

This feature selection algorithm looks only at the features (X), not the desired outputs (y), and can thus be used for unsupervised learning.

Read more in the User Guide.

**Parameters**

- **threshold** [float, default=0] Features with a training-set variance lower than this threshold will be removed. The default is to keep all features with non-zero variance, i.e. remove the features that have the same value in all samples.

**Attributes**

- **variances_** [array, shape (n_features,)] Variances of individual features.

**Notes**

Allows NaN in the input. Raises ValueError if no feature in X meets the variance threshold.

**Examples**

The following dataset has integer features, two of which are the same in every sample. These are removed with the default setting for threshold:

```python
>>> X = [[0, 2, 0, 3], [0, 1, 4, 3], [0, 1, 1, 3]]
>>> selector = VarianceThreshold()
>>> selector.fit_transform(X)
array([[2, 0],
       [1, 4],
       [1, 1]])
```

**Methods**

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**fit (X, y=None)**

Learn empirical variances from X.
Parameters

X  ([array-like, sparse matrix], shape (n_samples, n_features)) Sample vectors from which to compute variances.

y  [any, default=None] Ignored. This parameter exists only for compatibility with sklearn.pipeline.Pipeline.

Returns

self

fit_transform(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

X  [array-like of shape (n_samples, n_features)] Input samples.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params  [dict] Additional fit parameters.

Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params(deep=True)
Get parameters for this estimator.

Parameters

dep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

get_support(indices=False)
Get a mask, or integer index, of the features selected

Parameters

indices  [bool, default=False] If True, the return value will be an array of integers, rather than a boolean mask.

Returns

support  [array] An index that selects the retained features from a feature vector. If indices is False, this is a boolean array of shape [# input features], in which an element is True iff its corresponding feature is selected for retention. If indices is True, this is an integer array of shape [# output features] whose values are indices into the input feature vector.

inverse_transform(X)
Reverse the transformation operation

Parameters

X  [array of shape [n_samples, n_selected_features]] The input samples.

Returns
X_r [array of shape [n_samples, n_original_features]] X with columns of zeros inserted where features would have been removed by transform.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Reduce X to the selected features.

Parameters

X [array of shape [n_samples, n_features]] The input samples.

Returns

X_r [array of shape [n_samples, n_selected_features]] The input samples with only the selected features.

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7.15.12 sklearn.feature_selection.chi2

sklearn.feature_selection.chi2 (X,y)
Compute chi-squared stats between each non-negative feature and class.

This score can be used to select the n_features features with the highest values for the test chi-squared statistic from X, which must contain only non-negative features such as booleans or frequencies (e.g., term counts in document classification), relative to the classes.

Recall that the chi-square test measures dependence between stochastic variables, so using this function “weeds out” the features that are the most likely to be independent of class and therefore irrelevant for classification.

Read more in the User Guide.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Sample vectors.

y [array-like of shape (n_samples,)] Target vector (class labels).

Returns
chi2 [array, shape = (n_features,)] chi2 statistics of each feature.

pval [array, shape = (n_features,)] p-values of each feature.

See also:

f_classif ANOVA F-value between label/feature for classification tasks.
f_regression F-value between label/feature for regression tasks.

Notes

Complexity of this algorithm is O(n_classes * n_features).

Examples using sklearn.feature_selection.chi2

• Selecting dimensionality reduction with Pipeline and GridSearchCV
• SVM-Anova: SVM with univariate feature selection
• Classification of text documents using sparse features

7.15.13 sklearn.feature_selection.f_classif

sklearn.feature_selection.f_classif(X, y)

Compute the ANOVA F-value for the provided sample.

Read more in the User Guide.

Parameters

X [{array-like, sparse matrix} shape = [n_samples, n_features]] The set of regressors that will be tested sequentially.

y [array of shape(n_samples)] The data matrix.

Returns

F [array, shape = [n_features,]] The set of F values.
pval [array, shape = [n_features,]] The set of p-values.

See also:

chi2 Chi-squared stats of non-negative features for classification tasks.
f_regression F-value between label/feature for regression tasks.

Examples using sklearn.feature_selection.f_classif

• Pipeline Anova SVM
• Univariate Feature Selection
7.15.14 sklearn.feature_selection.f_regression

sklearn.feature_selection.f_regression(X, y, *, center=True)

Univariate linear regression tests.

Linear model for testing the individual effect of each of many regressors. This is a scoring function to be used in a feature selection procedure, not a free standing feature selection procedure.

This is done in 2 steps:

1. The correlation between each regressor and the target is computed, that is, \((X[:, i] - \text{mean}(X[:, i])) \times (y - \text{mean}_y) / (\text{std}(X[:, i]) \times \text{std}(y))\).

2. It is converted to an F score then to a p-value.

For more on usage see the User Guide.

Parameters

X [{array-like, sparse matrix} shape = (n_samples, n_features)] The set of regressors that will be tested sequentially.

y [array of shape(n_samples).] The data matrix

center [bool, default=True] If true, X and y will be centered.

Returns

F [array, shape=(n_features,)] F values of features.

pval [array, shape=(n_features,)] p-values of F-scores.

See also:

mutual_info_regression Mutual information for a continuous target.

f_classif ANOVA F-value between label/feature for classification tasks.

chi2 Chi-squared stats of non-negative features for classification tasks.

SelectKBest Select features based on the k highest scores.

SelectFpr Select features based on a false positive rate test.

SelectFdr Select features based on an estimated false discovery rate.

SelectFwe Select features based on family-wise error rate.

SelectPercentile Select features based on percentile of the highest scores.

Examples using sklearn.feature_selection.f_regression

- Feature agglomeration vs. univariate selection
- Comparison of F-test and mutual information
7.15.15 sklearn.feature_selection.mutual_info_classif

sklearn.feature_selection.mutual_info_classif(X, y, *, discrete_features='auto', n_neighbors=3, copy=True, random_state=None)

Estimate mutual information for a discrete target variable.

Mutual information (MI) [1] between two random variables is a non-negative value, which measures the dependency between the variables. It is equal to zero if and only if two random variables are independent, and higher values mean higher dependency.

The function relies on nonparametric methods based on entropy estimation from k-nearest neighbors distances as described in [2] and [3]. Both methods are based on the idea originally proposed in [4].

It can be used for univariate features selection, read more in the User Guide.

Parameters

- X [array-like or sparse matrix, shape (n_samples, n_features)] Feature matrix.
- y [array-like of shape (n_samples,)] Target vector.
- discrete_features [{'auto', bool, array-like}, default='auto'] If bool, then determines whether to consider all features discrete or continuous. If array, then it should be either a boolean mask with shape (n_features,) or array with indices of discrete features. If 'auto', it is assigned to False for dense X and to True for sparse X.
- n_neighbors [int, default=3] Number of neighbors to use for MI estimation for continuous variables, see [2] and [3]. Higher values reduce variance of the estimation, but could introduce a bias.
- copy [bool, default=True] Whether to make a copy of the given data. If set to False, the initial data will be overwritten.
- random_state [int, RandomState instance or None, default=None] Determines random number generation for adding small noise to continuous variables in order to remove repeated values. Pass an int for reproducible results across multiple function calls. See Glossary.

Returns

- mi [ndarray, shape (n_features,)] Estimated mutual information between each feature and the target.

Notes

1. The term “discrete features” is used instead of naming them “categorical”, because it describes the essence more accurately. For example, pixel intensities of an image are discrete features (but hardly categorical) and you will get better results if mark them as such. Also note, that treating a continuous variable as discrete and vice versa will usually give incorrect results, so be attentive about that.

2. True mutual information can’t be negative. If its estimate turns out to be negative, it is replaced by zero.
Estimate mutual information for a continuous target variable.

Mutual information (MI) \([1]\) between two random variables is a non-negative value, which measures the dependency between the variables. It is equal to zero if and only if two random variables are independent, and higher values mean higher dependency.

The function relies on nonparametric methods based on entropy estimation from k-nearest neighbors distances as described in \([2]\) and \([3]\). Both methods are based on the idea originally proposed in \([4]\).

It can be used for univariate features selection, read more in the User Guide.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Feature matrix.
- **y** [array-like of shape (n_samples,)] Target vector.
- **discrete_features** [{‘auto’, bool, array-like}, default=’auto’] If bool, then determines whether to consider all features discrete or continuous. If array, then it should be either a boolean mask with shape (n_features,) or array with indices of discrete features. If ‘auto’, it is assigned to False for dense X and to True for sparse X.
- **n_neighbors** [int, default=3] Number of neighbors to use for MI estimation for continuous variables, see \([2]\) and \([3]\). Higher values reduce variance of the estimation, but could introduce a bias.
- **copy** [bool, default=True] Whether to make a copy of the given data. If set to False, the initial data will be overwritten.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for adding small noise to continuous variables in order to remove repeated values. Pass an int for reproducible results across multiple function calls. See Glossary.

**Returns**

- **mi** [ndarray, shape (n_features,)] Estimated mutual information between each feature and the target.

**Notes**

1. The term “discrete features” is used instead of naming them “categorical”, because it describes the essence more accurately. For example, pixel intensities of an image are discrete features (but hardly categorical) and you will get better results if mark them as such. Also note, that treating a continuous variable as discrete and vice versa will usually give incorrect results, so be attentive about that.
2. True mutual information can’t be negative. If its estimate turns out to be negative, it is replaced by zero.
The `sklearn.gaussian_process` module implements Gaussian Process based regression and classification.

**User guide**: See the Gaussian Processes section for further details.

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### 7.16.1 sklearn.gaussian_process.GaussianProcessClassifier

A class `GaussianProcessClassifier` for Gaussian process classification (GPC) based on Laplace approximation.

The implementation is based on Algorithm 3.1, 3.2, and 5.1 of Gaussian Processes for Machine Learning (GPML) by Rasmussen and Williams.

Internally, the Laplace approximation is used for approximating the non-Gaussian posterior by a Gaussian.

Currently, the implementation is restricted to using the logistic link function. For multi-class classification, several binary one-versus rest classifiers are fitted. Note that this class thus does not implement a true multi-class Laplace approximation.

**Parameters**

- `kernel` [kernel instance, default=None] The kernel specifying the covariance function of the GP. If None is passed, the kernel “1.0 * RBF(1.0)” is used as default. Note that the kernel’s hyperparameters are optimized during fitting.

- `optimizer` ['fmin_l_bfgs_b' or callable, default='fmin_l_bfgs_b'] Can either be one of the internally supported optimizers for optimizing the kernel’s parameters, specified by a string, or an externally defined optimizer passed as a callable. If a callable is passed, it must have the signature:
```python
def optimizer(obj_func, initial_theta, bounds):
    # * 'obj_func' is the objective function to be maximized, which
    # takes the hyperparameters theta as parameter and an
    # optional flag eval_gradient, which determines if the
    # gradient is returned additionally to the function value
    # * 'initial_theta': the initial value for theta, which can be
    # used by local optimizers
    # * 'bounds': the bounds on the values of theta
    ....
    # Returned are the best found hyperparameters theta and
    # the corresponding value of the target function.
    return theta_opt, func_min
```

Per default, the ‘L-BFGS-B’ algorithm from scipy.optimize.minimize is used. If None is
passed, the kernel’s parameters are kept fixed. Available internal optimizers are:

'fmin_l_bfgs_b'

**n_restarts_optimizer** [int, default=0] The number of restarts of the optimizer for finding the
kernel’s parameters which maximize the log-marginal likelihood. The first run of the op-
timizer is performed from the kernel’s initial parameters, the remaining ones (if any) from
thetas sampled log-uniform randomly from the space of allowed theta-values. If greater
than 0, all bounds must be finite. Note that n_restarts_optimizer=0 implies that one run is
performed.

**max_iter_predict** [int, default=100] The maximum number of iterations in Newton’s method
for approximating the posterior during predict. Smaller values will reduce computation time
at the cost of worse results.

**warm_start** [bool, default=False] If warm-starts are enabled, the solution of the last Newton
iteration on the Laplace approximation of the posterior mode is used as initialization for
the next call of _posterior_mode(). This can speed up convergence when _posterior_mode
is called several times on similar problems as in hyperparameter optimization. See the
Glossary.

**copy_X_train** [bool, default=True] If True, a persistent copy of the training data is stored in
the object. Otherwise, just a reference to the training data is stored, which might cause
predictions to change if the data is modified externally.

**random_state** [int, RandomState instance or None, default=None] Determines random number
generation used to initialize the centers. Pass an int for reproducible results across multiple
function calls. See :term: Glossary <random_state>.

**multi_class** [{‘one_vs_rest’, ‘one_vs_one’}, default=‘one_vs_rest’] Specifies how multi-class
classification problems are handled. Supported are ‘one_vs_rest’ and ‘one_vs_one’. In
‘one_vs_rest’, one binary Gaussian process classifier is fitted for each class, which is trained
to separate this class from the rest. In ‘one_vs_one’, one binary Gaussian process classifier is
fitted for each pair of classes, which is trained to separate these two classes. The predictions
of these binary predictors are combined into multi-class predictions. Note that ‘one_vs_one’
does not support predicting probability estimates.

**n_jobs** [int, default=None] The number of jobs to use for the computation: the spec-
ified multiclass problems are computed in parallel. None means 1 unless in a
joblib.parallel_backend context. -1 means using all processors. See Glossary
for more details.

Attributes
**base_estimator_** [Estimator instance] The estimator instance that defines the likelihood function using the observed data.

**kernel_** [kernel instance] The kernel used for prediction. In case of binary classification, the structure of the kernel is the same as the one passed as parameter but with optimized hyperparameters. In case of multi-class classification, a CompoundKernel is returned which consists of the different kernels used in the one-versus-rest classifiers.

**log_marginal_likelihood_value_** [float] The log-marginal-likelihood of `self.kernel_`. theta

**classes_** [array-like of shape (n_classes,)] Unique class labels.

**n_classes_** [int] The number of classes in the training data

### Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.gaussian_process import GaussianProcessClassifier
>>> from sklearn.gaussian_process.kernels import RBF

>>> X, y = load_iris(return_X_y=True)
>>> kernel = 1.0 * RBF(1.0)
>>> gpc = GaussianProcessClassifier(kernel=kernel, ...
...    random_state=0).fit(X, y)
>>> gpc.score(X, y)
0.9866...
>>> gpc.predict_proba(X[:2,:])
array([[0.83548752, 0.03228706, 0.13222543],
       [0.79064206, 0.06525643, 0.14410151]])
```

New in version 0.18.

### Methods

- **fit**(X, y) Fit Gaussian process classification model

- **get_params**(deep) Get parameters for this estimator.

- **log_marginal_likelihood**(theta, ...) Returns log-marginal likelihood of theta for training data.

- **predict**(X) Perform classification on an array of test vectors X.

- **predict_proba**(X) Return probability estimates for the test vector X.

- **score**(X, y[, sample_weight]) Return the mean accuracy on the given test data and labels.

- **set_params**(**params) Set the parameters of this estimator.

**fit**(X, y)

Fit Gaussian process classification model

**Parameters**

- **X** [array-like of shape (n_samples, n_features) or list of object] Feature vectors or other representations of training data.

- **y** [array-like of shape (n_samples,)] Target values, must be binary

**Returns**
self  [returns an instance of self.]

get_params (deep=True)
Get parameters for this estimator.

Parameters

   deep [bool, default=True] If True, will return the parameters for this estimator and contained
   subobjects that are estimators.

Returns

   params [dict] Parameter names mapped to their values.

log_marginal_likelihood (theta=None, eval_gradient=False, clone_kernel=True)
Returns log-marginal likelihood of theta for training data.

In the case of multi-class classification, the mean log-marginal likelihood of the one-versus-rest classifiers
are returned.

Parameters

   theta [array-like of shape (n_kernel_params,), default=None] Kernel hyperparameters for
   which the log-marginal likelihood is evaluated. In the case of multi-class classification,
   theta may be the hyperparameters of the compound kernel or of an individual kernel.
   In the latter case, all individual kernel get assigned the same theta values. If None, the
   precomputed log_marginal_likelihood of self.kernel_.theta is returned.

   eval_gradient [bool, default=False] If True, the gradient of the log-marginal likelihood with
   respect to the kernel hyperparameters at position theta is returned additionally. Note that
   gradient computation is not supported for non-binary classification. If True, theta must not
   be None.

   clone_kernel [bool, default=True] If True, the kernel attribute is copied. If False, the kernel
   attribute is modified, but may result in a performance improvement.

Returns

   log_likelihood [float] Log-marginal likelihood of theta for training data.

   log_likelihood_gradient [ndarray of shape (n_kernel_params,), optional] Gradient of the
   log-marginal likelihood with respect to the kernel hyperparameters at position theta. Only
   returned when eval_gradient is True.

predict (X)
Perform classification on an array of test vectors X.

Parameters

   X [array-like of shape (n_samples, n_features) or list of object] Query points where the GP
   is evaluated for classification.

Returns

   C [ndarray of shape (n_samples,)] Predicted target values for X, values are from classes_

predict_proba (X)
Return probability estimates for the test vector X.

Parameters

   X [array-like of shape (n_samples, n_features) or list of object] Query points where the GP
   is evaluated for classification.

Returns
**C** [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`.

**score** *(X, y, sample_weight=None)*
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**
- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**
- **score** [float] Mean accuracy of `self.predict(X)` wrt. y.

**set_params**( **params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**
- **params** [dict] Estimator parameters.

**Returns**
- **self** [estimator instance] Estimator instance.

**Examples using sklearn.gaussian_process.GaussianProcessClassifier**
- **Plot classification probability**
- **Classifier comparison**
- **Illustration of Gaussian process classification (GPC) on the XOR dataset**
- **Gaussian process classification (GPC) on iris dataset**
- **Iso-probability lines for Gaussian Processes classification (GPC)**
- **Probabilistic predictions with Gaussian process classification (GPC)**
- **Gaussian processes on discrete data structures**
Gaussian process regression (GPR).

The implementation is based on Algorithm 2.1 of Gaussian Processes for Machine Learning (GPML) by Rasmussen and Williams.

In addition to standard scikit-learn estimator API, GaussianProcessRegressor:

- allows prediction without prior fitting (based on the GP prior)
- provides an additional method `sample_y(X)`, which evaluates samples drawn from the GPR (prior or posterior) at given inputs
- exposes a method `log_marginal_likelihood(theta)`, which can be used externally for other ways of selecting hyperparameters, e.g., via Markov chain Monte Carlo.

Read more in the User Guide.

New in version 0.18.

### Parameters

- **kernel** [kernel instance, default=None] The kernel specifying the covariance function of the GP. If None is passed, the kernel `ConstantKernel(1.0, constant_value_bounds="fixed") + RBF(1.0, length_scale_bounds="fixed")` is used as default. Note that the kernel hyperparameters are optimized during fitting unless the bounds are marked as “fixed”.

- **alpha** [float or ndarray of shape (n_samples,), default=1e-10] Value added to the diagonal of the kernel matrix during fitting. This can prevent a potential numerical issue during fitting, by ensuring that the calculated values form a positive definite matrix. It can also be interpreted as the variance of additional Gaussian measurement noise on the training observations. Note that this is different from using a `WhiteKernel`. If an array is passed, it must have the same number of entries as the data used for fitting and is used as datapoint-dependent noise level. Allowing to specify the noise level directly as a parameter is mainly for convenience and for consistency with Ridge.

- **optimizer** [“fmin_l_bfgs_b” or callable, default=”fmin_l_bfgs_b”] Can either be one of the internally supported optimizers for optimizing the kernel’s parameters, specified by a string, or an externally defined optimizer passed as a callable. If a callable is passed, it must have the signature:

```python
def optimizer(obj_func, initial_theta, bounds):  
    # * 'obj_func' is the objective function to be minimized, which  
    #   takes the hyperparameters theta as parameter and an  
    #   optional flag eval_gradient, which determines if the  
    #   gradient is returned additionally to the function value  
    # * 'initial_theta': the initial value for theta, which can be  
    #   used by local optimizers  
    # * 'bounds': the bounds on the values of theta  
    ....  
    # Returned are the best found hyperparameters theta and
```

(continues on next page)
Per default, the ‘L-BGFS-B’ algorithm from scipy.optimize.minimize is used. If None is passed, the kernel’s parameters are kept fixed. Available internal optimizers are:

- `'fmin_l_bfgs_b'`

**n_restarts_optimizer** [int, default=0] The number of restarts of the optimizer for finding the kernel’s parameters which maximize the log-marginal likelihood. The first run of the optimizer is performed from the kernel’s initial parameters, the remaining ones (if any) from thetas sampled log-uniform randomly from the space of allowed theta-values. If greater than 0, all bounds must be finite. Note that n_restarts_optimizer == 0 implies that one run is performed.

**normalize_y** [bool, default=False] Whether the target values y are normalized, the mean and variance of the target values are set equal to 0 and 1 respectively. This is recommended for cases where zero-mean, unit-variance priors are used. Note that, in this implementation, the normalisation is reversed before the GP predictions are reported.

Changed in version 0.23.

**copy_X_train** [bool, default=True] If True, a persistent copy of the training data is stored in the object. Otherwise, just a reference to the training data is stored, which might cause predictions to change if the data is modified externally.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation used to initialize the centers. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

**Attributes**

- **X_train_** [array-like of shape (n_samples, n_features) or list of object] Feature vectors or other representations of training data (also required for prediction).
- **y_train_** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values in training data (also required for prediction)
- **kernel_** [kernel instance] The kernel used for prediction. The structure of the kernel is the same as the one passed as parameter but with optimized hyperparameters
- **L_** [array-like of shape (n_samples, n_samples)] Lower-triangular Cholesky decomposition of the kernel in X_train_
- **alpha_** [array-like of shape (n_samples,)] Dual coefficients of training data points in kernel space
- **log_marginal_likelihood_value_** [float] The log-marginal-likelihood of self.kernel_.
- **theta**
Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import DotProduct, WhiteKernel

>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = DotProduct() + WhiteKernel()
>>> gpr = GaussianProcessRegressor(kernel=kernel, ...  random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.3680...
>>> gpr.predict(X[:, :], return_std=True)
(array([653.0..., 592.1...]), array([316.6..., 316.6...]))
```

Methods

- `fit(X, y)` Fit Gaussian process regression model.

  Parameters

  - `X` [array-like of shape (n_samples, n_features) or list of object] Feature vectors or other representations of training data.
  - `y` [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values

  Returns

  - `self` [returns an instance of self.]

- `get_params([deep])` Get parameters for this estimator.

  Parameters

  - `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

  Returns

  - `params` [dict] Parameter names mapped to their values.

- `log_marginal_likelihood([theta, ...])` Returns log-marginal likelihood of theta for training data.

  Parameters

  - `theta` [None, default=None] Return log-marginal likelihood of theta for training data.
  - `eval_gradient` [False, default=False] Return the gradient of the log-marginal likelihood with respect to theta.
  - `clone_kernel` [True, default=True] If True, the kernel will be a independant clone of the kernel.

- `predict(X[, return_std, return_cov])` Predict using the Gaussian process regression model

- `sample_y(X[, n_samples, random_state])` Draw samples from Gaussian process and evaluate at X.

- `score(X, y[, sample_weight])` Return the coefficient of determination $R^2$ of the prediction.

- `set_params(**params)` Set the parameters of this estimator.
theta [array-like of shape (n_kernel_params,) default=None] Kernel hyperparameters for which the log-marginal likelihood is evaluated. If None, the precomputed log_marginal_likelihood of self.kernel_.theta is returned.

eval_gradient [bool, default=False] If True, the gradient of the log-marginal likelihood with respect to the kernel hyperparameters at position theta is returned additionally. If True, theta must not be None.

clone_kernel [bool, default=True] If True, the kernel attribute is copied. If False, the kernel attribute is modified, but may result in a performance improvement.

Returns

log_likelihood [float] Log-marginal likelihood of theta for training data.

log_likelihood_gradient [ndarray of shape (n_kernel_params,), optional] Gradient of the log-marginal likelihood with respect to the kernel hyperparameters at position theta. Only returned when eval_gradient is True.

predict (X, return_std=False, return_cov=False)
Predict using the Gaussian process regression model

We can also predict based on an unfitted model by using the GP prior. In addition to the mean of the predictive distribution, also its standard deviation (return_std=True) or covariance (return_cov=True). Note that at most one of the two can be requested.

Parameters

X [array-like of shape (n_samples, n_features) or list of object] Query points where the GP is evaluated.

return_std [bool, default=False] If True, the standard-deviation of the predictive distribution at the query points is returned along with the mean.

return_cov [bool, default=False] If True, the covariance of the joint predictive distribution at the query points is returned along with the mean.

Returns

y_mean [ndarray of shape (n_samples, [n_output_dims])] Mean of predictive distribution a query points.

y_std [ndarray of shape (n_samples,), optional] Standard deviation of predictive distribution at query points. Only returned when return_std is True.

y_cov [ndarray of shape (n_samples, n_samples), optional] Covariance of joint predictive distribution a query points. Only returned when return_cov is True.

sample_y (X, n_samples=1, random_state=0)
Draw samples from Gaussian process and evaluate at X.

Parameters

X [array-like of shape (n_samples, n_features) or list of object] Query points where the GP is evaluated.

n_samples [int, default=1] The number of samples drawn from the Gaussian process

random_state [int, RandomState instance or None, default=0] Determines random number generation to randomly draw samples. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

Returns
**y_samples** [ndarray of shape (n_samples_X, [n_output_dims], n_samples)] Values of n_samples samples drawn from Gaussian process and evaluated at query points.

**score** *(X, y, sample_weight=None)*

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $(y_{true} - y_{pred})^2 \cdot \text{sum()}$ and $v$ is the total sum of squares $(y_{true} - y_{true} \cdot \text{mean()})^2 \cdot \text{sum()}$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt $y$.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- ****params [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.gaussian_process.GaussianProcessRegressor**

- Comparison of kernel ridge and Gaussian process regression
- Illustration of prior and posterior Gaussian process for different kernels
- Gaussian process regression (GPR) with noise-level estimation
- Gaussian Processes regression: basic introductory example
- Gaussian process regression (GPR) on Mauna Loa CO2 data.
- Gaussian processes on discrete data structures
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### 7.16.3 sklearn.gaussian_process.kernels.CompoundKernel

**class** `sklearn.gaussian_process.kernels.CompoundKernel(kernels)`

Kernel which is composed of a set of other kernels.

New in version 0.18.

**Parameters**

- `kernels` [list of Kernels] The other kernels

**Attributes**

- `bounds` Returns the log-transformed bounds on the theta.
- `hyperparameters` Returns a list of all hyperparameter specifications.
- `n_dims` Returns the number of non-fixed hyperparameters of the kernel.
- `requires_vector_input` Returns whether the kernel is defined on discrete structures.
- `theta` Returns the (flattened, log-transformed) non-fixed hyperparameters.
Examples

```python
>>> from sklearn.gaussian_process.kernels import WhiteKernel
>>> from sklearn.gaussian_process.kernels import RBF
>>> from sklearn.gaussian_process.kernels import CompoundKernel

>>> kernel = CompoundKernel(...
[WhiteKernel(noise_level=3.0), RBF(length_scale=2.0)])

>>> print(kernel.bounds)

[[[-11.51292546 11.51292546]
  [-11.51292546 11.51292546]]

>>> print(kernel.n_dims)

2

>>> print(kernel.theta)

[1.09861229 0.69314718]
```

Methods

```python
__call__(X, Y=None, eval_gradient=False)  
Return the kernel k(X, Y) and optionally its gradient.

Parameters
  X [array-like of shape (n_samples_X, n_features) or list of object, default=None] Left argument of the returned kernel k(X, Y)
  Y [array-like of shape (n_samples_X, n_features) or list of object, default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) is evaluated instead.
  eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed.

Returns
  K [ndarray of shape (n_samples_X, n_samples_Y, n_kernels)] Kernel k(X, Y)
  K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims, n_kernels), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.
```

```python
property bounds
  Returns the log-transformed bounds on the theta.

Returns
  bounds [array of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta
```
clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

Parameters
theta [ndarray of shape (n_dims,)] The hyperparameters
diag(X)
Returns the diagonal of the kernel k(X, X).
The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters
X [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

Returns
K_diag [ndarray of shape (n_samples_X, n_kernels)] Diagonal of kernel k(X, X)
get_params(deep=True)
Get parameters of this kernel.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

property hyperparameters
Returns a list of all hyperparameter specifications.

is_stationary()
Returns whether the kernel is stationary.

property n_dims
Returns the number of non-fixed hyperparameters of the kernel.

property requires_vector_input
Returns whether the kernel is defined on discrete structures.

set_params(**params)
Set the parameters of this kernel.
The method works on simple kernels as well as on nested kernels. The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Returns
self

property theta
Returns the (flattened, log-transformed) non-fixed hyperparameters.
Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns
theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel
7.16.4 sklearn.gaussian_process.kernels.ConstantKernel

class sklearn.gaussian_process.kernels.ConstantKernel(constant_value=1.0, constant_value_bounds=(1e-05, 100000.0))

Constant kernel.

Can be used as part of a product-kernel where it scales the magnitude of the other factor (kernel) or as part of a sum-kernel, where it modifies the mean of the Gaussian process.

\[ k(x_1, x_2) = \text{constant\_value} \forall x_1, x_2 \]

Adding a constant kernel is equivalent to adding a constant:

```python
kernel = RBF() + ConstantKernel(constant_value=2)
```

is the same as:

```python
kernel = RBF() + 2
```

Read more in the User Guide.

New in version 0.18.

Parameters

- **constant_value** [float, default=1.0] The constant value which defines the covariance: \( k(x_1, x_2) = \text{constant\_value} \)

- **constant_value_bounds** [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on \( \text{constant\_value} \). If set to “fixed”, \( \text{constant\_value} \) cannot be changed during hyperparameter tuning.

Attributes

- **bounds** Returns the log-transformed bounds on the theta.

- **hyperparameter_constant_value**

- **hyperparameters** Returns a list of all hyperparameter specifications.

- **n_dims** Returns the number of non-fixed hyperparameters of the kernel.

- **requires_vector_input** Whether the kernel works only on fixed-length feature vectors.

- **theta** Returns the (flattened, log-transformed) non-fixed hyperparameters.

Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import RBF, ConstantKernel

>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = RBF() + ConstantKernel(constant_value=2)
>>> gpr = GaussianProcessRegressor(kernel=kernel, alpha=5,...
... random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.3696...
>>> gpr.predict(X[:,1:], return_std=True)
(array([[606.1...]], array([[0.24...]]))
```
Methods

| __call__(X[, Y, eval_gradient]) | Return the kernel k(X, Y) and optionally its gradient. |
| clone_with_theta(theta) | Returns a clone of self with given hyperparameters theta. |
| diag(X) | Returns the diagonal of the kernel k(X, X). |
| get_params([deep]) | Get parameters of this kernel. |
| is_stationary() | Returns whether the kernel is stationary. |
| set_params(**params) | Set the parameters of this kernel. |

__call__(X, Y=None, eval_gradient=False)
Return the kernel k(X, Y) and optionally its gradient.

Parameters

- X [array-like of shape (n_samples_X, n_features) or list of object] Left argument of the returned kernel k(X, Y)
- Y [array-like of shape (n_samples_X, n_features) or list of object, default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) is evaluated instead.
- eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

Returns

- K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)
- K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

property bounds
Returns the log-transformed bounds on the theta.

Returns

- bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

Parameters

- theta [ndarray of shape (n_dims,)] The hyperparameters

diag(X)
Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters

- X [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

Returns

- K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

get_params (deep=True)
Get parameters of this kernel.
Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

property hyperparameters
Returns a list of all hyperparameter specifications.

is_stationary()
Returns whether the kernel is stationary.

property n_dims
Returns the number of non-fixed hyperparameters of the kernel.

property requires_vector_input
Whether the kernel works only on fixed-length feature vectors.

set_params (**params)
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form
<component>__<parameter> so that it’s possible to update each component of a nested object.

Returns

self

property theta
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representa-
tion of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales
naturally live on a log-scale.

Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the
kernel

Examples using sklearn.gaussian_process.kernels.ConstantKernel

• Illustration of prior and posterior Gaussian process for different kernels
• Iso-probability lines for Gaussian Processes classification (GPC)
• Gaussian Processes regression: basic introductory example

7.16.5 sklearn.gaussian_process.kernels.DotProduct

class sklearn.gaussian_process.kernels.DotProduct (sigma_0=1.0,
sigma_0_bounds=1e-05,
        100000.0)

Dot-Product kernel.

The DotProduct kernel is non-stationary and can be obtained from linear regression by putting \( N(0, 1) \) priors on
the coefficients of \( x_d(d = 1, ..., D) \) and a prior of \( N(0, \sigma_0^2) \) on the bias. The DotProduct kernel is invariant to a
rotation of the coordinates about the origin, but not translations. It is parameterized by a parameter \( \sigma_0 \).
which controls the inhomogeneity of the kernel. For \( \sigma_0^2 = 0 \), the kernel is called the homogeneous linear kernel, otherwise it is inhomogeneous. The kernel is given by

\[
k(x_i, x_j) = \sigma_0^2 + x_i \cdot x_j
\]

The DotProduct kernel is commonly combined with exponentiation.

See [1], Chapter 4, Section 4.2, for further details regarding the DotProduct kernel.

Read more in the User Guide.

New in version 0.18.

Parameters

- **sigma_0** [float >= 0, default=1.0] Parameter controlling the inhomogeneity of the kernel. If \( \sigma_0=0 \), the kernel is homogenous.

- **sigma_0_bounds** [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on \( \sigma_0 \). If set to “fixed”, \( \sigma_0 \) cannot be changed during hyperparameter tuning.

Attributes

- **bounds** Returns the log-transformed bounds on the theta.

- **hyperparameter_sigma_0**

- **hyperparameters** Returns a list of all hyperparameter specifications.

- **n_dims** Returns the number of non-fixed hyperparameters of the kernel.

- **requires_vector_input** Returns whether the kernel is defined on fixed-length feature vectors or generic objects.

- **theta** Returns the (flattened, log-transformed) non-fixed hyperparameters.

References

[1]

Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import DotProduct, WhiteKernel
>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = DotProduct() + WhiteKernel()
>>> gpr = GaussianProcessRegressor(kernel=kernel,
...                                random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.3680...
>>> gpr.predict(X[:2,:], return_std=True)
(array([653.0..., 592.1...]), array([316.6..., 316.6...]))
```
scikit-learn user guide, Release 0.24.0

Methods

```python
__call__(X[, Y, eval_gradient])
```
Return the kernel $k(X, Y)$ and optionally its gradient.

```python
clone_with_theta(theta)
```
Returns a clone of self with given hyperparameters theta.

```python
diag(X)
```
Returns the diagonal of the kernel $k(X, X)$.

```python
get_params([deep])
```
Get parameters of this kernel.

```python
is_stationary()
```
Returns whether the kernel is stationary.

```python
set_params(**params)
```
Set the parameters of this kernel.

```python
__call__((X, Y=None, eval_gradient=False))
```
Return the kernel $k(X, Y)$ and optionally its gradient.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel $k(X, Y)$.
- **Y** [ndarray of shape (n_samples_Y, n_features), default=None] Right argument of the returned kernel $k(X, Y)$. If None, $k(X, X)$ if evaluated instead.
- **eval_gradient** [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

**Returns**

- **K** [ndarray of shape (n_samples_X, n_samples_Y)] Kernel $k(X, Y)$
- **K_gradient** [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel $k(X, X)$ with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

**property bounds**

Returns the log-transformed bounds on the theta.

**Returns**

- **bounds** [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

```python
clone_with_theta(theta)
```
Returns a clone of self with given hyperparameters theta.

**Parameters**

- **theta** [ndarray of shape (n_dims,)] The hyperparameters

```python
diag(X)
```
Returns the diagonal of the kernel $k(X, X)$.

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel $k(X, Y)$.

**Returns**

- **K_diag** [ndarray of shape (n_samples_X,)] Diagonal of kernel $k(X, X)$.
**get_params** *(deep=True)*
Get parameters of this kernel.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**property hyperparameters**
Returns a list of all hyperparameter specifications.

**is_stationary()**
Returns whether the kernel is stationary.

**property n_dims**
Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**
Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

**set_params(**params**)
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Returns**

- **self**

**property theta**
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

**Returns**

- **theta** [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

---

**Examples using `sklearn.gaussian_process.kernels.DotProduct`**

- Illustration of Gaussian process classification (GPC) on the XOR dataset
- Illustration of prior and posterior Gaussian process for different kernels
- Iso-probability lines for Gaussian Processes classification (GPC)
Exp-Sine-Squared kernel (aka periodic kernel).

The ExpSineSquared kernel allows one to model functions which repeat themselves exactly. It is parameterized by a length scale parameter \( l > 0 \) and a periodicity parameter \( p > 0 \). Only the isotropic variant where \( l \) is a scalar is supported at the moment. The kernel is given by:

\[
k(x_i, x_j) = \exp \left( -\frac{2 \sin^2(\pi d(x_i, x_j)/p)}{l^2} \right)
\]

where \( l \) is the length scale of the kernel, \( p \) the periodicity of the kernel and \( d(cdot, cdot) \) is the Euclidean distance.

Read more in the User Guide.

New in version 0.18.

**Parameters**

- `length_scale` [float > 0, default=1.0] The length scale of the kernel.
- `periodicity` [float > 0, default=1.0] The periodicity of the kernel.
- `length_scale_bounds` [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘length_scale’. If set to “fixed”, ‘length_scale’ cannot be changed during hyperparameter tuning.
- `periodicity_bounds` [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘periodicity’. If set to “fixed”, ‘periodicity’ cannot be changed during hyperparameter tuning.

**Attributes**

- `bounds` Returns the log-transformed bounds on the theta.
- `hyperparameter_length_scale` Returns the length scale
- `hyperparameter_periodicity`
- `hyperparameters` Returns a list of all hyperparameter specifications.
- `n_dims` Returns the number of non-fixed hyperparameters of the kernel.
- `requires_vector_input` Returns whether the kernel is defined on fixed-length feature vectors or generic objects.
- `theta` Returns the (flattened, log-transformed) non-fixed hyperparameters.
Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import ExpSineSquared

>>> X, y = make_friedman2(n_samples=50, noise=0, random_state=0)
>>> kernel = ExpSineSquared(length_scale=1, periodicity=1)
>>> gpr = GaussianProcessRegressor(kernel=kernel, alpha=5,
... random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.0144...
>>> gpr.predict(X[:2, :], return_std=True)
(array([425.6..., 457.5...]), array([0.3894..., 0.3467...]))
```

Methods

```
__call__(X[, Y , eval_gradient])
Return the kernel k(X, Y) and optionally its gradient.

clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

diag(X)
Returns the diagonal of the kernel k(X, X).

going_get_params([deep])
Get parameters of this kernel.

is_stationary()
Returns whether the kernel is stationary.

set_params(**params)
Set the parameters of this kernel.
```

```
__call__(X, Y=None, eval_gradient=False)
Return the kernel k(X, Y) and optionally its gradient.

Parameters

X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

Y [ndarray of shape (n_samples_Y, n_features), default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.

eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

Returns

K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.
```

```
property bounds
Returns the log-transformed bounds on the theta.

Returns

bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta
```

```
clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

Parameters

```
theta [ndarray of shape (n_dims,)] The hyperparameters

diag(X)
Returns the diagonal of the kernel \( k(X, X) \).
The result of this method is identical to \( \text{np.diag}(\text{self}(X)) \); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters

\( X \) [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel \( k(X, Y) \)

Returns

\( K_{\text{diag}} \) [ndarray of shape (n_samples_X,)] Diagonal of kernel \( k(X, X) \)

get_params (deep=True)
Get parameters of this kernel.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

property hyperparameter_length_scale
Returns the length scale

property hyperparameters
Returns a list of all hyperparameter specifications.

is_stationary ()
Returns whether the kernel is stationary.

property n_dims
Returns the number of non-fixed hyperparameters of the kernel.

property requires_vector_input
Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

set_params (**params)
Set the parameters of this kernel.
The method works on simple kernels as well as on nested kernels. The latter have parameters of the form \(<\text{component}>___<\text{parameter}>\) so that it’s possible to update each component of a nested object.

Returns

self

property theta
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel
Examples using `sklearn.gaussian_process.kernels.ExpSineSquared`

- Comparison of kernel ridge and Gaussian process regression
- Illustration of prior and posterior Gaussian process for different kernels
- Gaussian process regression (GPR) on Mauna Loa CO2 data.

### 7.16.7 `sklearn.gaussian_process.kernels.Exponentiation`

```python
class sklearn.gaussian_process.kernels.Exponentiation(kernel, exponent)
```

The Exponentiation kernel takes one base kernel and a scalar parameter \( p \) and combines them via

\[
k_{\text{exp}}(X, Y) = k(X, Y)^p
\]

Note that the `__pow__` magic method is overridden, so `Exponentiation(RBF(), 2)` is equivalent to using the `**` operator with `RBF() ** 2`.

Read more in the User Guide.

New in version 0.18.

**Parameters**

- `kernel` [Kernel] The base kernel
- `exponent` [float] The exponent for the base kernel

**Attributes**

- `bounds` Returns the log-transformed bounds on the theta.
- `hyperparameters` Returns a list of all hyperparameter.
- `n_dims` Returns the number of non-fixed hyperparameters of the kernel.
- `requires_vector_input` Returns whether the kernel is defined on discrete structures.
- `theta` Returns the (flattened, log-transformed) non-fixed hyperparameters.

**Examples**

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import (RationalQuadratic, ...
... Exponentiation)
>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = Exponentiation(RationalQuadratic(), exponent=2)
>>> gpr = GaussianProcessRegressor(kernel=kernel, alpha=5, ...
... random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.419...
>>> gpr.predict(X[:,1:], return_std=True)
(array([635.5...]), array([0.559...]))
```
## Methods

<table>
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<tr>
<th>Method</th>
<th>Description</th>
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<tr>
<td><strong>call</strong></td>
<td>Return the kernel $k(X, Y)$ and optionally its gradient.</td>
</tr>
<tr>
<td>clone_with_theta(theta)</td>
<td>Returns a clone of self with given hyperparameters theta.</td>
</tr>
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<td>diag(X)</td>
<td>Returns the diagonal of the kernel $k(X, X)$.</td>
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<tr>
<td>get_params([deep])</td>
<td>Get parameters of this kernel.</td>
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<td>is_stationary()</td>
<td>Returns whether the kernel is stationary.</td>
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<td>set_params(**params)</td>
<td>Set the parameters of this kernel.</td>
</tr>
<tr>
<td><strong>call</strong> (X, Y=None, eval_gradient=False)</td>
<td>Return the kernel $k(X, Y)$ and optionally its gradient.</td>
</tr>
</tbody>
</table>

**Parameters**

X [array-like of shape (n_samples_X, n_features) or list of object] Left argument of the returned kernel $k(X, Y)$

Y [array-like of shape (n_samples_Y, n_features) or list of object, default=None] Right argument of the returned kernel $k(X, Y)$. If None, $k(X, X)$ is evaluated instead.

eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed.

**Returns**

K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel $k(X, Y)$

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel $k(X, X)$ with respect to the log of the hyperparameter of the kernel. Only returned when `eval_gradient` is True.

**property bounds**

Returns the log-transformed bounds on the theta.

**Returns**

bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

**clone_with_theta(theta)**

Returns a clone of self with given hyperparameters theta.

**Parameters**

theta [ndarray of shape (n_dims,)] The hyperparameters

diag(X)

Returns the diagonal of the kernel $k(X, X)$.

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

X [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

**Returns**

K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel $k(X, X)$

**get_params (deep=True)**

Get parameters of this kernel.
Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**property hyperparameters**
Returns a list of all hyperparameter.

**is_stationary()**
Returns whether the kernel is stationary.

**property n_dims**
Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**
Returns whether the kernel is defined on discrete structures.

**set_params(**params**)**
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Returns

**self**

**property theta**
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

**theta** [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

7.16.8 sklearn.gaussian_process.kernels.Hyperparameter

class sklearn.gaussian_process.kernels.Hyperparameter(name, value_type, bounds, n_elements=1, fixed=None)

A kernel hyperparameter’s specification in form of a namedtuple.

New in version 0.18.

Attributes

**name** [str] The name of the hyperparameter. Note that a kernel using a hyperparameter with name “x” must have the attributes self.x and self.x_bounds

**value_type** [str] The type of the hyperparameter. Currently, only “numeric” hyperparameters are supported.

**bounds** [pair of floats >= 0 or “fixed”] The lower and upper bound on the parameter. If n_elements>1, a pair of 1d array with n_elements each may be given alternatively. If the string “fixed” is passed as bounds, the hyperparameter’s value cannot be changed.
**n_elements** [int, default=1] The number of elements of the hyperparameter value. Defaults to 1, which corresponds to a scalar hyperparameter. n_elements > 1 corresponds to a hyperparameter which is vector-valued, such as, e.g., anisotropic length-scales.

**fixed** [bool, default=None] Whether the value of this hyperparameter is fixed, i.e., cannot be changed during hyperparameter tuning. If None is passed, the “fixed” is derived based on the given bounds.

**Examples**

```python
>>> from sklearn.gaussian_process.kernels import ConstantKernel
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process.kernels import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import Hyperparameter

>>> X, y = make_friedman2(n_samples=50, noise=0, random_state=0)
>>> kernel = ConstantKernel(constant_value=1.0,
... constand_value_bounds=(0.0, 10.0))

We can access each hyperparameter:

```python
>>> for hyperparameter in kernel.hyperparameters:
... print(hyperparameter)
Hyperparameter(name='constant_value', value_type='numeric',
bounds=array([[ 0., 10.]]), n_elements=1, fixed=False)
```

```python
>>> params = kernel.get_params()
>>> for key in sorted(params): print(f"{key} : {params[key]}")
constant_value : 1.0
constant_value_bounds : (0.0, 10.0)
```

**Methods**

- `count(value, /)` Return number of occurrences of value.
- `index(value[, start, stop])` Return first index of value.

- `__call__(*args, **kwargs)` Call self as a function.

- `bounds` Alias for field number 2

- `count` (value, /) Return number of occurrences of value.

- `fixed` Alias for field number 4

- `index` (value, start=0, stop=sys.maxsize, /) Return first index of value.
  Raises ValueError if the value is not present.

- `n_elements` Alias for field number 3
name
   Alias for field number 0

value_type
   Alias for field number 1

Examples using sklearn.gaussian_process.kernels.Hyperparameter
    • Gaussian processes on discrete data structures

7.16.9 sklearn.gaussian_process.kernels.Kernel

class sklearn.gaussian_process.kernels.Kernel
   Base class for all kernels.
   New in version 0.18.

   Attributes

   bounds Returns the log-transformed bounds on the theta.

   hyperparameters Returns a list of all hyperparameter specifications.

   n_dims Returns the number of non-fixed hyperparameters of the kernel.

   requires_vector_input Returns whether the kernel is defined on fixed-length feature vectors or generic objects.

   theta Returns the (flattened, log-transformed) non-fixed hyperparameters.

   Methods

   __call__(X[, Y, eval_gradient]) Evaluate the kernel.

   clone_with_theta(theta) Returns a clone of self with given hyperparameters theta.

   diag(X) Returns the diagonal of the kernel k(X, X).

   get_params([deep]) Get parameters of this kernel.

   is_stationary() Returns whether the kernel is stationary.

   set_params(**params) Set the parameters of this kernel.

   abstract __call__(X, Y=None, eval_gradient=False)
      Evaluate the kernel.

   property bounds
      Returns the log-transformed bounds on the theta.

      Returns

      bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

   clone_with_theta(theta)
      Returns a clone of self with given hyperparameters theta.

      Parameters

      theta [ndarray of shape (n_dims,)] The hyperparameters
**abstract diag** (*X*)

Returns the diagonal of the kernel *k*(*X*, *X*).

The result of this method is identical to `np.diag(self(X))`; however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

*X* [array-like of shape (*n_samples,*))] Left argument of the returned kernel *k*(*X*, *Y*)

**Returns**

*K_diag* [ndarray of shape (*n_samples_*X*,)] Diagonal of kernel *k*(*X*, *X*)

**get_params** (*deep=True*)

Get parameters of this kernel.

**Parameters**

*deep* [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

*params* [dict] Parameter names mapped to their values.

**property hyperparameters**

Returns a list of all hyperparameter specifications.

**abstract is_stationary** ()

Returns whether the kernel is stationary.

**property n_dims**

Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**

Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

**set_params** (**params**)

Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Returns**

*self*

**property theta**

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

**Returns**

*theta* [ndarray of shape (*n_dims,*))] The non-fixed, log-transformed hyperparameters of the kernel.
Examples using sklearn.gaussian_process.kernels.Kernel

- Gaussian processes on discrete data structures

7.16.10 sklearn.gaussian_process.kernels.Matern

class sklearn.gaussian_process.kernels.Matern(length_scale=1.0, length_scale_bounds=(1e-05, 100000.0), nu=1.5)

Matern kernel.

The class of Matern kernels is a generalization of the RBF. It has an additional parameter $\nu$ which controls the smoothness of the resulting function. The smaller $\nu$, the less smooth the approximated function is. As $\nu \to \infty$, the kernel becomes equivalent to the RBF kernel. When $\nu = 1/2$, the Matérn kernel becomes identical to the absolute exponential kernel. Important intermediate values are $\nu = 1.5$ (once differentiable functions) and $\nu = 2.5$ (twice differentiable functions).

The kernel is given by:

$$k(x_i, x_j) = \frac{1}{\Gamma(\nu)2^{\nu-1}} \left( \frac{\sqrt{2\nu}}{l} d(x_i, x_j) \right)^\nu K_\nu \left( \frac{\sqrt{2\nu}}{l} d(x_i, x_j) \right)$$

where $d(\cdot, \cdot)$ is the Euclidean distance, $K_\nu(\cdot)$ is a modified Bessel function and $\Gamma(\cdot)$ is the gamma function. See [1], Chapter 4, Section 4.2, for details regarding the different variants of the Matern kernel.

Parameters

- **length_scale** [float or ndarray of shape (n_features,), default=1.0] The length scale of the kernel. If a float, an isotropic kernel is used. If an array, an anisotropic kernel is used where each dimension of $l$ defines the length-scale of the respective feature dimension.

- **length_scale_bounds** [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘length_scale’. If set to “fixed”, ‘length_scale’ cannot be changed during hyperparameter tuning.

- **nu** [float, default=1.5] The parameter nu controlling the smoothness of the learned function. The smaller nu, the less smooth the approximated function is. For nu=inf, the kernel becomes equivalent to the RBF kernel and for nu=0.5 to the absolute exponential kernel. Important intermediate values are nu=1.5 (once differentiable functions) and nu=2.5 (twice differentiable functions). Note that values of nu not in [0.5, 1.5, 2.5, inf] incur a considerably higher computational cost (appr. 10 times higher) since they require to evaluate the modified Bessel function. Furthermore, in contrast to l, nu is kept fixed to its initial value and not optimized.

Attributes

- **anisotropic**
- **bounds** Returns the log-transformed bounds on the theta.
- **hyperparameter_length_scale**
- **hyperparameters** Returns a list of all hyperparameter specifications.
- **n_dims** Returns the number of non-fixed hyperparameters of the kernel.
Requires whether the kernel is defined on fixed-length feature vectors or generic objects.

\textbf{theta} Returns the (flattened, log-transformed) non-fixed hyperparameters.

\section*{References}

[1]

\section*{Examples}

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.gaussian_process import GaussianProcessClassifier
>>> from sklearn.gaussian_process.kernels import Matern

>>> X, y = load_iris(return_X_y=True)
>>> kernel = 1.0 * Matern(length_scale=1.0, nu=1.5)
>>> gpc = GaussianProcessClassifier(kernel=kernel, random_state=0).fit(X, y)
>>> gpc.score(X, y)
0.9866...
>>> gpc.predict_proba(X[:2,:])
anomaly([[0.8513..., 0.0368..., 0.1117...],
         [0.8086..., 0.0693..., 0.1220...]])
```

\section*{Methods}

\begin{itemize}
  \item \texttt{\_call\_}(X[, Y, eval\_gradient]) Return the kernel k(X, Y) and optionally its gradient.
  \item \texttt{clone\_with\_theta}(theta) Returns a clone of self with given hyperparameters theta.
  \item \texttt{diag}(X) Returns the diagonal of the kernel k(X, X).
  \item \texttt{get\_params}(deep) Get parameters of this kernel.
  \item \texttt{is\_stationary}() Returns whether the kernel is stationary.
  \item \texttt{set\_params}(**params) Set the parameters of this kernel.
\end{itemize}

\begin{itemize}
  \item \texttt{\_call\_}(X, Y=None, eval\_gradient=False) Return the kernel k(X, Y) and optionally its gradient.
\end{itemize}

\section*{Parameters}

\begin{itemize}
  \item \texttt{X} [ndarray of shape (n\_samples\_X, n\_features)] Left argument of the returned kernel k(X, Y).
  \item \texttt{Y} [ndarray of shape (n\_samples\_Y, n\_features), default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.
  \item \texttt{eval\_gradient} [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.
\end{itemize}

\section*{Returns}

\begin{itemize}
  \item \texttt{K} [ndarray of shape (n\_samples\_X, n\_samples\_Y)] Kernel k(X, Y).
  \item \texttt{K\_gradient} [ndarray of shape (n\_samples\_X, n\_samples\_X, n\_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval\_gradient is True.
\end{itemize}
property bounds
Returns the log-transformed bounds on the theta.

Returns

bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyper-
parameters theta

cClone_with_theta (theta)
Returns a clone of self with given hyperparameters theta.

Parameters

theta [ndarray of shape (n_dims,)] The hyperparameters
diag (X)
Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently
since only the diagonal is evaluated.

Parameters

X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

Returns

K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

get_params (deep=True)
Get parameters of this kernel.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

property hyperparameters
Returns a list of all hyperparameter specifications.

is_stationary ()
Returns whether the kernel is stationary.

property n_dims
Returns the number of non-fixed hyperparameters of the kernel.

property requires_vector_input
Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True
for backward compatibility.

set_params (**params)
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form
<component>__<parameter> so that it’s possible to update each component of a nested object.

Returns

self
property theta

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

Examples using sklearn.gaussian_process.kernels.Matern

• Illustration of prior and posterior Gaussian process for different kernels

7.16.11 sklearn.gaussian_process.kernels.PairwiseKernel
class sklearn.gaussian_process.kernels.PairwiseKernel (gamma=1.0, gamma_bounds=1e-05, 1e5, metric='linear', pairwise_kernels_kwargs=None)

Wrapper for kernels in sklearn.metrics.pairwise.

A thin wrapper around the functionality of the kernels in sklearn.metrics.pairwise.

Note: Evaluation of eval_gradient is not analytic but numeric and all kernels support only isotropic distances. The parameter gamma is considered to be a hyperparameter and may be optimized. The other kernel parameters are set directly at initialization and are kept fixed.

New in version 0.18.

Parameters

gamma [float, default=1.0] Parameter gamma of the pairwise kernel specified by metric. It should be positive.

gamma_bounds [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘gamma’. If set to “fixed”, ‘gamma’ cannot be changed during hyperparameter tuning.

metric [{“linear”, “additive_chisq”, “chisq”, “poly”, “polynomial”, “rbf”, “laplacian”, “sigmoid”, “cosine”} or callable, default=”linear”] The metric to use when calculating kernel between instances in a feature array. If metric is a string, it must be one of the metrics in pairwise.PAIRWISE_KERNEL_FUNCTIONS. If metric is “precomputed”, X is assumed to be a kernel matrix. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays from X as input and return a value indicating the distance between them.

pairwise_kernels_kwargs [dict, default=None] All entries of this dict (if any) are passed as keyword arguments to the pairwise kernel function.

Attributes

bounds Returns the log-transformed bounds on the theta.

hyperparameters gamma

hyperparameters Returns a list of all hyperparameter specifications.

n_dims Returns the number of non-fixed hyperparameters of the kernel.
requires_vector_input Returns whether the kernel is defined on fixed-length feature vectors or generic objects.

theta Returns the (flattened, log-transformed) non-fixed hyperparameters.

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.gaussian_process import GaussianProcessClassifier
>>> from sklearn.gaussian_process.kernels import PairwiseKernel

>>> X, y = load_iris(return_X_y=True)
>>> kernel = PairwiseKernel(metric='rbf')
>>> gpc = GaussianProcessClassifier(kernel=kernel, random_state=0).fit(X, y)
>>> gpc.score(X, y)
0.9733...
>>> gpc.predict_proba(X[:2,:])
array([[0.8880..., 0.05663..., 0.05532...],
       [0.8676..., 0.07073..., 0.06165...]])
```

Methods

__call__(X[, Y, eval_gradient]) Return the kernel k(X, Y) and optionally its gradient.

call_with_theta(theta) Returns a clone of self with given hyperparameters theta.

diag(X) Returns the diagonal of the kernel k(X, X).

gp_params([deep]) Get parameters of this kernel.

is_stationary() Returns whether the kernel is stationary.

property bounds Returns the log-transformed bounds on the theta.

__call__(X, Y=None, eval_gradient=False)

Return the kernel k(X, Y) and optionally its gradient.

Parameters

X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

Y [ndarray of shape (n_samples_Y, n_features), default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.

eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

Returns

K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

property bounds

Returns the log-transformed bounds on the theta.

property eval_gradient

Returns the gradient of the kernel with respect to its hyperparameters.

property feature_length

Returns the feature length of the kernel.

__call__(X, Y, eval_gradient)

Return the kernel k(X, Y) and optionally its gradient.

Parameters

X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

Y [ndarray of shape (n_samples_Y, n_features), default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.

eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

Returns

K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

property bounds

Returns the log-transformed bounds on the theta.

property eval_gradient

Returns the gradient of the kernel with respect to its hyperparameters.

property feature_length

Returns the feature length of the kernel.
**bounds** [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

**clone_with_theta**(theta)
Returns a clone of self with given hyperparameters theta.

**Parameters**

theta [ndarray of shape (n_dims,)] The hyperparameters

**diag**(X)
Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

**Returns**

K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

**get_params**(deep=True)
Get parameters of this kernel.

**Parameters**

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**property hyperparameters**
Returns a list of all hyperparameter specifications.

**is_stationary**()
Returns whether the kernel is stationary.

**property n_dims**
Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**
Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

**set_params**(**params)
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Returns**

self

**property theta**
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.
Returns

\textbf{theta} [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

### 7.16.12 sklearn.gaussian_process.kernels.Product

class sklearn.gaussian_process.kernels.Product (k1, k2)

The Product kernel takes two kernels $k_1$ and $k_2$ and combines them via

$$k_{\text{prod}}(X, Y) = k_1(X, Y) \ast k_2(X, Y)$$

Note that the \_\_mul\_ magic method is overridden, so \texttt{Product(RBF(), RBF())} is equivalent to using the \* operator with \texttt{RBF() \* RBF()}. Read more in the User Guide.

New in version 0.18.

Parameters

- \texttt{k1} [Kernel] The first base-kernel of the product-kernel
- \texttt{k2} [Kernel] The second base-kernel of the product-kernel

Attributes

- \texttt{bounds} Returns the log-transformed bounds on the theta.
- \texttt{hyperparameters} Returns a list of all hyperparameter.
- \texttt{n_dims} Returns the number of non-fixed hyperparameters of the kernel.
- \texttt{requires_vector_input} Returns whether the kernel is stationary.
- \texttt{theta} Returns the (flattened, log-transformed) non-fixed hyperparameters.

Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import (RBF, Product,
...                             ConstantKernel)
>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = Product(ConstantKernel(2), RBF())
>>> gpr = GaussianProcessRegressor(kernel=kernel,
...                                random_state=0).fit(X, y)
>>> gpr.score(X, y)
1.0
>>> kernel
1.41**2 \ast RBF(length_scale=1)
```
Methods

Methods

__call__(X[, Y, eval_gradient])
Return the kernel k(X, Y) and optionally its gradient.

clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

diag(X)
Returns the diagonal of the kernel k(X, X).

get_params([deep])
Get parameters of this kernel.

is_stationary()
Returns whether the kernel is stationary.

set_params(**params)
Set the parameters of this kernel.

__call__(X, Y=None, eval_gradient=False)
Return the kernel k(X, Y) and optionally its gradient.

Parameters

X [array-like of shape (n_samples_X, n_features) or list of object] Left argument of the returned kernel k(X, Y)

Y [array-like of shape (n_samples_Y, n_features) or list of object, default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) is evaluated instead.

eval_gradient [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed.

Returns

K [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

property bounds
Returns the log-transformed bounds on the theta.

Returns

bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel's hyperparameters theta

clone_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

Parameters

theta [ndarray of shape (n_dims,)] The hyperparameters

diag(X)
Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters

X [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

Returns

K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

get_params (deep=True)
Get parameters of this kernel.
Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**property hyperparameters**

Returns a list of all hyperparameter.

**is_stationary()**

Returns whether the kernel is stationary.

**property n_dims**

Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**

Returns whether the kernel is stationary.

**set_params(**params**)**

Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Returns

self

**property theta**

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

7.16.13 sklearn.gaussian_process.kernels.RBF

class sklearn.gaussian_process.kernels.RBF (length_scale=1.0,  length_scale_bounds=(1e-05, 100000.0))

Radial-basis function kernel (aka squared-exponential kernel).

The RBF kernel is a stationary kernel. It is also known as the “squared exponential” kernel. It is parameterized by a length scale parameter \( l > 0 \), which can either be a scalar (isotropic variant of the kernel) or a vector with the same number of dimensions as the inputs X (anisotropic variant of the kernel). The kernel is given by:

\[
k(x_i, x_j) = \exp \left( -\frac{d(x_i, x_j)^2}{2l^2} \right)
\]

where \( l \) is the length scale of the kernel and \( d(\cdot, \cdot) \) is the Euclidean distance. For advice on how to set the length scale parameter, see e.g. [1].

This kernel is infinitely differentiable, which implies that GPs with this kernel as covariance function have mean square derivatives of all orders, and are thus very smooth. See [2], Chapter 4, Section 4.2, for further details of the RBF kernel.
Read more in the *User Guide*.

New in version 0.18.

**Parameters**

- **length_scale** [float or ndarray of shape (n_features,), default=1.0] The length scale of the kernel. If a float, an isotropic kernel is used. If an array, an anisotropic kernel is used where each dimension of l defines the length-scale of the respective feature dimension.

- **length_scale_bounds** [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘length_scale’. If set to “fixed”, ‘length_scale’ cannot be changed during hyperparameter tuning.

**Attributes**

- **anisotropic**

- **bounds** Returns the log-transformed bounds on the theta.

- **hyperparameter_length_scale**

- **hyperparameters** Returns a list of all hyperparameter specifications.

- **n_dims** Returns the number of non-fixed hyperparameters of the kernel.

- **requires_vector_input** Returns whether the kernel is defined on fixed-length feature vectors or generic objects.

- **theta** Returns the (flattened, log-transformed) non-fixed hyperparameters.

**References**

[1], [2]

**Examples**

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.gaussian_process import GaussianProcessClassifier
>>> from sklearn.gaussian_process.kernels import RBF

X, y = load_iris(return_X_y=True)
kernel = 1.0 * RBF(1.0)
gpc = GaussianProcessClassifier(kernel=kernel, random_state=0).fit(X, y)
gpc.score(X, y)
0.9866...

>>> gpc.predict_proba(X[:2, :])
array([[0.8354..., 0.03228..., 0.1322...],
       [0.7906..., 0.0652..., 0.1441...]])
```
Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td><code>__call__(X, Y, eval_gradient)</code></td>
<td>Return the kernel k(X, Y) and optionally its gradient.</td>
</tr>
<tr>
<td><code>clone_with_theta(theta)</code></td>
<td>Returns a clone of self with given hyperparameters theta.</td>
</tr>
<tr>
<td><code>diag(X)</code></td>
<td>Returns the diagonal of the kernel k(X, X).</td>
</tr>
<tr>
<td><code>get_params()</code></td>
<td>Get parameters of this kernel.</td>
</tr>
<tr>
<td><code>is_stationary()</code></td>
<td>Returns whether the kernel is stationary.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this kernel.</td>
</tr>
</tbody>
</table>

**__call__ (X: ndarray of shape (n_samples_X, n_features), Y: ndarray of shape (n_samples_Y, n_features), default=None, eval_gradient: bool, default=False)\**

Return the kernel k(X, Y) and optionally its gradient.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)
- **Y** [ndarray of shape (n_samples_Y, n_features), default=None] Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.
- **eval_gradient** [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

**Returns**

- **K** [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)
- **K_gradient** [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

**property bounds**

Returns the log-transformed bounds on the theta.

**Returns**

- **bounds** [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

**clone_with_theta(theta)**

Returns a clone of self with given hyperparameters theta.

**Parameters**

- **theta** [ndarray of shape (n_dims,)] The hyperparameters

**diag(X)**

Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

**Returns**

- **K_diag** [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)
**get_params** *(deep=True)*

Get parameters of this kernel.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**property hyperparameters**

Returns a list of all hyperparameter specifications.

**is_stationary()**

Returns whether the kernel is stationary.

**property n_dims**

Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**

Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

**set_params(**params**)**

Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Returns**

self

**property theta**

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

**Returns**

**theta** [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

**Examples using sklearn.gaussian_process.kernels.RBF**

- **Plot classification probability**
- **Classifier comparison**
- **Illustration of Gaussian process classification (GPC) on the XOR dataset**
- **Gaussian process classification (GPC) on iris dataset**
- **Illustration of prior and posterior Gaussian process for different kernels**
- **Probabilistic predictions with Gaussian process classification (GPC)**
- **Gaussian process regression (GPR) with noise-level estimation**
- **Gaussian Processes regression: basic introductory example**
Gaussian process regression (GPR) on Mauna Loa CO2 data.

7.16.14 sklearn.gaussian_process.kernels.RationalQuadratic

class sklearn.gaussian_process.kernels.RationalQuadratic (length_scale=1.0, alpha=1.0, length_scale_bounds=(1e-05, 100000.0), alpha_bounds=(1e-05, 100000.0))

Rational Quadratic kernel.

The RationalQuadratic kernel can be seen as a scale mixture (an infinite sum) of RBF kernels with different characteristic length scales. It is parameterized by a length scale parameter \( l > 0 \) and a scale mixture parameter \( \alpha > 0 \). Only the isotropic variant where length_scale \( l \) is a scalar is supported at the moment. The kernel is given by:

\[
k(x_i, x_j) = \left(1 + \frac{d(x_i, x_j)^2}{2\alpha l^2}\right)^{-\alpha}
\]

where \( \alpha \) is the scale mixture parameter, \( l \) is the length scale of the kernel and \( d(\cdot, \cdot) \) is the Euclidean distance. For advice on how to set the parameters, see e.g. [1].

Read more in the User Guide.

New in version 0.18.

Parameters

length_scale [float > 0, default=1.0] The length scale of the kernel.

alpha [float > 0, default=1.0] Scale mixture parameter

length_scale_bounds [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘length_scale’. If set to “fixed”, ‘length_scale’ cannot be changed during hyperparameter tuning.

alpha_bounds [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘alpha’. If set to “fixed”, ‘alpha’ cannot be changed during hyperparameter tuning.

Attributes

bounds Returns the log-transformed bounds on the theta.

hyperparameter_alpha

hyperparameter_length_scale

hyperparameters Returns a list of all hyperparameter specifications.

n_dims Returns the number of non-fixed hyperparameters of the kernel.

requires_vector_input Returns whether the kernel is defined on fixed-length feature vectors or generic objects.

theta Returns the (flattened, log-transformed) non-fixed hyperparameters.
Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.gaussian_process import GaussianProcessClassifier
>>> from sklearn.gaussian_process.kernels import Matern

>>> X, y = load_iris(return_X_y=True)
>>> kernel = RationalQuadratic(length_scale=1.0, alpha=1.5)
>>> gpc = GaussianProcessClassifier(kernel=kernel, ... random_state=0).fit(X, y)
>>> gpc.score(X, y)
0.9733...
>>> gpc.predict_proba(X[:2,:])
array([[0.8881..., 0.0566..., 0.05518...],
       [0.8678..., 0.0707..., 0.0614...]])
```

Methods

```python
__call__(X[, Y, eval_gradient])  Return the kernel k(X, Y) and optionally its gradient.

clone_with_theta(theta)  Returns a clone of self with given hyperparameters theta.

diag(X)  Returns the diagonal of the kernel k(X, X).

get_params([deep])  Get parameters of this kernel.

is_stationary()  Returns whether the kernel is stationary.

set_params(**params)  Set the parameters of this kernel.
```

```python
__call__(X, Y=None, eval_gradient=False)

Return the kernel k(X, Y) and optionally its gradient.

Parameters

X [ndarray of shape (n_samples_X, n_features)]  Left argument of the returned kernel k(X, Y).

Y [ndarray of shape (n_samples_Y, n_features), default=None]  Right argument of the returned kernel k(X, Y). If None, k(X, X) if evaluated instead.

eval_gradient [bool, default=False]  Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.

Returns

K [ndarray of shape (n_samples_X, n_samples_Y)]  Kernel k(X, Y).

K_gradient [ndarray of shape (n_samples_X, n_samples_X, n_dims)]  The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

property bounds

Returns the log-transformed bounds on the theta.
```

7.16. sklearn.gaussian_process: Gaussian Processes
bounds [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

cloned_with_theta(theta)
Returns a clone of self with given hyperparameters theta.

Parameters
theta [ndarray of shape (n_dims,)] The hyperparameters

diag(X)
Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters
X [ndarray of shape (n_samples_X, n_features)] Left argument of the returned kernel k(X, Y)

Returns
K_diag [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

get_params (deep=True)
Get parameters of this kernel.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

property hyperparameters
Returns a list of all hyperparameter specifications.

is_stationary()
Returns whether the kernel is stationary.

property n_dims
Returns the number of non-fixed hyperparameters of the kernel.

property requires_vector_input
Returns whether the kernel is defined on fixed-length feature vectors or generic objects. Defaults to True for backward compatibility.

set_params (**params)
Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Returns
self

property theta
Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.
Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

Examples using sklearn.gaussian_process.kernels.RationalQuadratic

- Illustration of prior and posterior Gaussian process for different kernels
- Gaussian process regression (GPR) on Mauna Loa CO2 data.

7.16.15 sklearn.gaussian_process.kernels.Sum

class sklearn.gaussian_process.kernels.Sum(k1, k2)

The Sum kernel takes two kernels $k_1$ and $k_2$ and combines them via

$$k_{\text{sum}}(X, Y) = k_1(X, Y) + k_2(X, Y)$$

Note that the __add__ magic method is overridden, so `Sum(RBF(), RBF())` is equivalent to using the + operator with `RBF() + RBF()`.

Read more in the User Guide.

New in version 0.18.

Parameters

- k1 [Kernel] The first base-kernel of the sum-kernel
- k2 [Kernel] The second base-kernel of the sum-kernel

Attributes

- bounds Returns the log-transformed bounds on the theta.
- hyperparameters Returns a list of all hyperparameter.
- n_dims Returns the number of non-fixed hyperparameters of the kernel.
- requires_vector_input Returns whether the kernel is stationary.
- theta Returns the (flattened, log-transformed) non-fixed hyperparameters.

Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import RBF, Sum, ConstantKernel

>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = Sum(ConstantKernel(2), RBF())
>>> gpr = GaussianProcessRegressor(kernel=kernel, ...
                random_state=0).fit(X, y)
>>> gpr.score(X, y)
1.0
>>> kernel
1.41**2 + RBF(length_scale=1)
```
## Methods

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<th>Method</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td><strong>call</strong> (X, Y, eval_gradient)</td>
<td>Return the kernel ( k(X, Y) ) and optionally its gradient.</td>
</tr>
<tr>
<td>clone_with_theta (theta)</td>
<td>Returns a clone of self with given hyperparameters theta.</td>
</tr>
<tr>
<td>diag (X)</td>
<td>Returns the diagonal of the kernel ( k(X, X) ).</td>
</tr>
<tr>
<td>get_params (deep)</td>
<td>Get parameters of this kernel.</td>
</tr>
<tr>
<td>is_stationary ()</td>
<td>Returns whether the kernel is stationary.</td>
</tr>
<tr>
<td>set_params (**params)</td>
<td>Set the parameters of this kernel.</td>
</tr>
</tbody>
</table>

### __call__ (X, Y=None, eval_gradient=False)

Return the kernel \( k(X, Y) \) and optionally its gradient.

**Parameters**

- **X** [array-like of shape (n_samples_X, n_features) or list of object] Left argument of the returned kernel \( k(X, Y) \).
- **Y** [array-like of shape (n_samples_X, n_features) or list of object, default=None] Right argument of the returned kernel \( k(X, Y) \). If None, \( k(X, X) \) is evaluated instead.
- **eval_gradient** [bool, default=False] Determines whether the gradient with respect to the log of the kernel hyperparameter is computed.

**Returns**

- **K** [ndarray of shape (n_samples_X, n_samples_Y)] Kernel \( k(X, Y) \)
- **K_gradient** [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel \( k(X, X) \) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

### property bounds

Returns the log-transformed bounds on the theta.

**Returns**

- **bounds** [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

### clone_with_theta (theta)

Returns a clone of self with given hyperparameters theta.

**Parameters**

- **theta** [ndarray of shape (n_dims,)] The hyperparameters

### diag (X)

Returns the diagonal of the kernel \( k(X, X) \).

The result of this method is identical to \( \text{np.diag(self(X))} \); however, it can be evaluated more efficiently since only the diagonal is evaluated.

**Parameters**

- **X** [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

**Returns**

- **K_diag** [ndarray of shape (n_samples_X,)] Diagonal of kernel \( k(X, X) \)

### get_params (deep=True)

Get parameters of this kernel.
Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**property hyperparameters**

Returns a list of all hyperparameter.

**is_stationary()**

Returns whether the kernel is stationary.

**property n_dims**

Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**

Returns whether the kernel is stationary.

**set_params(**params**)**

Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Returns

**self**

**property theta**

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

**theta** [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

### 7.16.16 sklearn.gaussian_process.kernels.WhiteKernel

**class** sklearn.gaussian_process.kernels.WhiteKernel

White kernel.

The main use-case of this kernel is as part of a sum-kernel where it explains the noise of the signal as independently and identically normally-distributed. The parameter noise_level equals the variance of this noise.

\[
k(x_1, x_2) = \text{noise_level} \text{ if } x_i == x_j \text{ else } 0
\]

Read more in the User Guide.

New in version 0.18.

**Parameters**

**noise_level** [float, default=1.0] Parameter controlling the noise level (variance)
noise_level_bounds  [pair of floats >= 0 or “fixed”, default=(1e-5, 1e5)] The lower and upper bound on ‘noise_level’. If set to “fixed”, ‘noise_level’ cannot be changed during hyperparameter tuning.

Attributes

- **bounds**  Returns the log-transformed bounds on the theta.
- **hyperparameter_noise_level**
- **hyperparameters**  Returns a list of all hyperparameter specifications.
- **n_dims**  Returns the number of non-fixed hyperparameters of the kernel.
- **requires_vector_input**  Whether the kernel works only on fixed-length feature vectors.
- **theta**  Returns the (flattened, log-transformed) non-fixed hyperparameters.

Examples

```python
>>> from sklearn.datasets import make_friedman2
>>> from sklearn.gaussian_process import GaussianProcessRegressor
>>> from sklearn.gaussian_process.kernels import DotProduct, WhiteKernel

>>> X, y = make_friedman2(n_samples=500, noise=0, random_state=0)
>>> kernel = DotProduct() + WhiteKernel(noise_level=0.5)
>>> gpr = GaussianProcessRegressor(kernel=kernel,
...                               random_state=0).fit(X, y)
>>> gpr.score(X, y)
0.3680...
>>> gpr.predict(X[:2,:], return_std=True)
(array([653.0..., 592.1...]), array([316.6..., 316.6...]))
```

Methods

- **__call__(X, Y=None, eval_gradient=False)**
  Return the kernel k(X, Y) and optionally its gradient.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>Left argument of the returned kernel k(X, Y)</td>
</tr>
<tr>
<td>Y</td>
<td>Right argument of the returned kernel k(X, Y). If None, k(X, X) is evaluated instead.</td>
</tr>
<tr>
<td>eval_gradient</td>
<td>Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.</td>
</tr>
</tbody>
</table>

  Parameters

  - **X**  [array-like of shape (n_samples_X, n_features) or list of object]  Left argument of the returned kernel k(X, Y)  
  - **Y**  [array-like of shape (n_samples_X, n_features) or list of object, default=None]  Right argument of the returned kernel k(X, Y). If None, k(X, X) is evaluated instead.  
  - **eval_gradient**  [bool, default=False]  Determines whether the gradient with respect to the log of the kernel hyperparameter is computed. Only supported when Y is None.  

  Returns
**K** [ndarray of shape (n_samples_X, n_samples_Y)] Kernel k(X, Y)

**K_gradient** [ndarray of shape (n_samples_X, n_samples_X, n_dims), optional] The gradient of the kernel k(X, X) with respect to the log of the hyperparameter of the kernel. Only returned when eval_gradient is True.

---

**property bounds**

Returns the log-transformed bounds on the theta.

Returns

**bounds** [ndarray of shape (n_dims, 2)] The log-transformed bounds on the kernel’s hyperparameters theta

**clone_with_theta**(theta)

Returns a clone of self with given hyperparameters theta.

Parameters

**theta** [ndarray of shape (n_dims,)] The hyperparameters

**diag**(X)

Returns the diagonal of the kernel k(X, X).

The result of this method is identical to np.diag(self(X)); however, it can be evaluated more efficiently since only the diagonal is evaluated.

Parameters

**X** [array-like of shape (n_samples_X, n_features) or list of object] Argument to the kernel.

Returns

**K_diag** [ndarray of shape (n_samples_X,)] Diagonal of kernel k(X, X)

**get_params**(deep=True)

Get parameters of this kernel.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

---

**property hyperparameters**

Returns a list of all hyperparameter specifications.

**is_stationary**()

Returns whether the kernel is stationary.

**property n_dims**

Returns the number of non-fixed hyperparameters of the kernel.

**property requires_vector_input**

Whether the kernel works only on fixed-length feature vectors.

**set_params**(**params)**

Set the parameters of this kernel.

The method works on simple kernels as well as on nested kernels. The latter have parameters of the form <component>_<parameter> so that it’s possible to update each component of a nested object.

Returns
self

property theta

Returns the (flattened, log-transformed) non-fixed hyperparameters.

Note that theta are typically the log-transformed values of the kernel’s hyperparameters as this representation of the search space is more amenable for hyperparameter search, as hyperparameters like length-scales naturally live on a log-scale.

Returns

theta [ndarray of shape (n_dims,)] The non-fixed, log-transformed hyperparameters of the kernel

Examples using sklearn.gaussian_process.kernels.WhiteKernel

- Comparison of kernel ridge and Gaussian process regression
- Gaussian process regression (GPR) with noise-level estimation
- Gaussian process regression (GPR) on Mauna Loa CO2 data.

7.17 sklearn.impute: Impute

Transformers for missing value imputation

User guide: See the Imputation of missing values section for further details.

| impute.SimpleImputer(*[, missing_values, ...]) | Imputation transformer for completing missing values. |
| impute.IterativeImputer([estimator, ...]) | Multivariate imputer that estimates each feature from all the others. |
| impute.MissingIndicator(*[, missing_values, ...]) | Binary indicators for missing values. |
| impute.KNNImputer(*[, missing_values, ...]) | Imputation for completing missing values using k-Nearest Neighbors. |

7.17.1 sklearn.impute.SimpleImputer

class sklearn.impute.SimpleImputer (*, missing_values=nan, strategy='mean', fill_value=None, verbose=0, copy=True, add_indicator=False)

Imputation transformer for completing missing values.

Read more in the User Guide.

New in version 0.20: SimpleImputer replaces the previous sklearn.preprocessing.Imputer estimator which is now removed.

Parameters

- missing_values [int, float, str, np.nan or None, default=np.nan] The placeholder for the missing values. All occurrences of missing_values will be imputed. For pandas’ dataframes with nullable integer dtypes with missing values, missing_values should be set to np.nan, since pd.NA will be converted to np.nan.
- strategy [string, default=’mean’] The imputation strategy.
• If “mean”, then replace missing values using the mean along each column. Can only be
  used with numeric data.
• If “median”, then replace missing values using the median along each column. Can only
  be used with numeric data.
• If “most_frequent”, then replace missing using the most frequent value along each col-
  umn. Can be used with strings or numeric data. If there is more than one such value, only
  the smallest is returned.
• If “constant”, then replace missing values with fill_value. Can be used with strings or
  numeric data.

New in version 0.20: strategy="constant" for fixed value imputation.

fill_value [string or numerical value, default=None] When strategy == “constant”, fill_value is
used to replace all occurrences of missing_values. If left to the default, fill_value will be 0
when imputing numerical data and “missing_value” for strings or object data types.

verbose [integer, default=0] Controls the verbosity of the imputer.

copy [boolean, default=True] If True, a copy of X will be created. If False, imputation will be
done in-place whenever possible. Note that, in the following cases, a new copy will always
be made, even if copy=False:
  • If X is not an array of floating values;
  • If X is encoded as a CSR matrix;
  • If add_indicator=True.

add_indicator [boolean, default=False] If True, a MissingIndicator transform will stack
onto output of the imputer’s transform. This allows a predictive estimator to account for
missingness despite imputation. If a feature has no missing values at fit/train time, the fea-
ture won’t appear on the missing indicator even if there are missing values at transform/test
time.

Attributes

statistics_ [array of shape (n_features,)] The imputation fill value for each feature. Computing
statistics can result in np.nan values. During transform, features corresponding to
np.nan statistics will be discarded.

indicator_ [MissingIndicator] Indicator used to add binary indicators for missing values.
None if add_indicator is False.

See also:

IterativeImputer Multivariate imputation of missing values.

Notes

Columns which only contained missing values at fit are discarded upon transform if strategy is not “con-
stant”.

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Examples

```python
>>> import numpy as np
>>> from sklearn.impute import SimpleImputer

>>> imp_mean = SimpleImputer(missing_values=np.nan, strategy='mean')
>>> imp_mean.fit([[7, 2, 3], [4, np.nan, 6], [10, 5, 9]])
SimpleImputer()

>>> X = [[np.nan, 2, 3], [4, np.nan, 6], [10, np.nan, 9]]
>>> print(imp_mean.transform(X))
[[7. 2. 3.]
 [4. 3.5 6.]
 [10. 3.5 9.]]
```

Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td>fit(X[, y])</td>
<td>Fit the imputer on X.</td>
</tr>
<tr>
<td>fit_transform(X[, y], **fit_params)</td>
<td>Fit to data, then transform it. Fits transformer to X and y with optional parameters fit_params and returns a transposed version of X.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>inverse_transform(X)</td>
<td>Convert the data back to the original representation.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Impute all missing values in X.</td>
</tr>
</tbody>
</table>

**fit** (X, y=None)

Fit the imputer on X.

**Parameters**

- **X** ([array-like, sparse matrix], shape (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

**Returns**

- **self** [SimpleImputer]

**fit_transform** (X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** (deep=True)

Get parameters for this estimator.

**Parameters**
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform(X)
Convert the data back to the original representation.

Inverts the transform operation performed on an array. This operation can only be performed after SimpleImputer is instantiated with add_indicator=True.

Note that inverse_transform can only invert the transform in features that have binary indicators for missing values. If a feature has no missing values at fit time, the feature won’t have a binary indicator, and the imputation done at transform time won’t be inverted.

New in version 0.24.

Parameters

X [array-like of shape (n_samples, n_features + n_features_missing_indicator)] The imputed data to be reverted to original data. It has to be an augmented array of imputed data and the missing indicator mask.

Returns

X_original [ndarray of shape (n_samples, n_features)] The original X with missing values as it was prior to imputation.

set_params(**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform(X)
Impute all missing values in X.

Parameters

X [{array-like, sparse matrix}, shape (n_samples, n_features)] The input data to complete.

Examples using sklearn.impute.SimpleImputer

• Release Highlights for scikit-learn 0.23
• Combine predictors using stacking
• Permutation Importance vs Random Forest Feature Importance (MDI)
• Imputing missing values with variants of IterativeImputer
• Imputing missing values before building an estimator
• Column Transformer with Mixed Types


7.17.2 sklearn.impute.IterativeImputer

class sklearn.impute.IterativeImputer (estimator=None, *, missing_values=nan, sample_posterior=False, max_iter=10, tol=0.001, n_nearest_features=None, initial_strategy='mean', imputation_order='ascending', skip_complete=False, min_value=-inf, max_value=inf, verbose=0, random_state=None, add_indicator=False)

Multivariate imputer that estimates each feature from all the others.

A strategy for imputing missing values by modeling each feature with missing values as a function of other features in a round-robin fashion.

Read more in the User Guide.

New in version 0.21.

Note: This estimator is still experimental for now: the predictions and the API might change without any deprecation cycle. To use it, you need to explicitly import enable_iterative_imputer:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_iterative_imputer  # noqa
>>> # now you can import normally from sklearn.impute
>>> from sklearn.impute import IterativeImputer
```

Parameters

- **estimator** [estimator object, default=BayesianRidge()] The estimator to use at each step of the round-robin imputation. If sample_posterior is True, the estimator must support return_std in its predict method.

- **missing_values** [int, np.nan, default=np.nan] The placeholder for the missing values. All occurrences of missing_values will be imputed. For pandas’ dataframes with nullable integer dtypes with missing values, missing_values should be set to np.nan, since pd.NA will be converted to np.nan.

- **sample_posterior** [boolean, default=False] Whether to sample from the (Gaussian) predictive posterior of the fitted estimator for each imputation. Estimator must support return_std in its predict method if set to True. Set to True if using IterativeImputer for multiple imputations.

- **max_iter** [int, default=10] Maximum number of imputation rounds to perform before returning the imputations computed during the final round. A round is a single imputation of each feature with missing values. The stopping criterion is met once \( \frac{\max(\|X_t - X_{(t-1)}\|)}{\max(\|X[\text{known_vals}]\|)} < \text{tol} \), where \( X_t \) is \( X \) at iteration \( t \). Note that early stopping is only applied if \`sample_posterior=False`.

- **tol** [float, default=1e-3] Tolerance of the stopping condition.

- **n_nearest_features** [int, default=None] Number of other features to use to estimate the missing values of each feature column. Nearness between features is measured using the absolute correlation coefficient between each feature pair (after initial imputation). To ensure coverage of features throughout the imputation process, the neighbor features are not necessarily nearest, but are drawn with probability proportional to correlation for each imputed target feature. Can provide significant speed-up when the number of features is huge. If None, all features will be used.
**initial_strategy** [str, default='mean'] Which strategy to use to initialize the missing values. Same as the strategy parameter in SimpleImputer. Valid values: (“mean”, “median”, “most_frequent”, or “constant”).

**imputation_order** [str, default='ascending'] The order in which the features will be imputed. Possible values:
- “ascending” From features with fewest missing values to most.
- “descending” From features with most missing values to fewest.
- “roman” Left to right.
- “arabic” Right to left.
- “random” A random order for each round.

**skip_complete** [boolean, default=False] If True then features with missing values during transform which did not have any missing values during fit will be imputed with the initial imputation method only. Set to True if you have many features with no missing values at both fit and transform time to save compute.

**min_value** [float or array-like of shape (n_features,), default=-np.inf] Minimum possible imputed value. Broadcast to shape (n_features,) if scalar. If array-like, expects shape (n_features,), one min value for each feature. The default is -np.inf.

Changed in version 0.23: Added support for array-like.

**max_value** [float or array-like of shape (n_features,), default=np.inf] Maximum possible imputed value. Broadcast to shape (n_features,) if scalar. If array-like, expects shape (n_features,), one max value for each feature. The default is np.inf.

Changed in version 0.23: Added support for array-like.

**verbose** [int, default=0] Verbosity flag, controls the debug messages that are issued as functions are evaluated. The higher, the more verbose. Can be 0, 1, or 2.

**random_state** [int, RandomState instance or None, default=None] The seed of the pseudo random number generator to use. Randomizes selection of estimator features if n_nearest_features is not None, the imputation_order if random, and the sampling from posterior if sample_posterior is True. Use an integer for determinism. See the Glossary.

**add_indicator** [boolean, default=False] If True, a MissingIndicator transform will stack onto output of the imputer’s transform. This allows a predictive estimator to account for missingness despite imputation. If a feature has no missing values at fit/train time, the feature won’t appear on the missing indicator even if there are missing values at transform/test time.

**Attributes**

**initial_imputer_** [object of type SimpleImputer] Imputer used to initialize the missing values.

**imputation_sequence_** [list of tuples] Each tuple has (feat_idx, neighbor_feat_idx, estimator), where feat_idx is the current feature to be imputed, neighbor_feat_idx is the array of other features used to impute the current feature, and estimator is the trained estimator used for the imputation. Length is self.n_features_with_missing_ * self.n_iter_.

**n_iter_** [int] Number of iteration rounds that occurred. Will be less than self.max_iter if early stopping criterion was reached.
n_features_with_missing_ [int] Number of features with missing values.

indicator_ [MissingIndicator] Indicator used to add binary indicators for missing values.
None if add_indicator is False.

random_state_ [RandomState instance] RandomState instance that is generated either from a
seed, the random number generator or by np.random.

See also:

SimpleImputer Univariate imputation of missing values.

Notes

To support imputation in inductive mode we store each feature’s estimator during the fit phase, and predict
without refitting (in order) during the transform phase.

Features which contain all missing values at fit are discarded upon transform.

References

[1],[2]

Examples

```python
>>> import numpy as np
>>> from sklearn.experimental import enable_iterative_imputer
>>> from sklearn.impute import IterativeImputer

>>> imp_mean = IterativeImputer(random_state=0)
>>> imp_mean.fit([[7, 2, 3], [4, np.nan, 6], [10, 5, 9]])
IterativeImputer(random_state=0)

>>> X = [[np.nan, 2, 3], [4, np.nan, 6], [10, np.nan, 9]]
>>> imp_mean.transform(X)
array([[ 6.9584..., 2. , 3. ],
       [ 4. , 2.6000..., 6. ],
       [10. , 4.9999..., 9. ]])
```

Methods

**fit**(*X*, *y*)
Fits the imputer on X and return self.

**fit_transform**(*X*, *y*)
Fits the imputer on X and return the transformed X.

**get_params**([**deep**])
Get parameters for this estimator.

**set_params**(**params**)
Set the parameters of this estimator.

**transform**(*X*)
Imputes all missing values in X.

**fit**(*X*, *y=None*)
Fits the imputer on X and return self.

**Parameters**

**X** [array-like, shape (n_samples, n_features)] Input data, where “n_samples” is the number
of samples and “n_features” is the number of features.
Returns

self [object] Returns self.

**fit_transform**(X, y=None)
Fits the imputer on X and return the transformed X.

Parameters

X [array-like, shape (n_samples, n_features)] Input data, where “n_samples” is the number of samples and “n_features” is the number of features.

y [ignored.]

Returns

Xt [array-like, shape (n_samples, n_features)] The imputed input data.

**get_params**(deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**set_params**(**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

**transform**(X)
Imputes all missing values in X.

Note that this is stochastic, and that if random_state is not fixed, repeated calls, or permuted input, will yield different results.

Parameters

X [array-like of shape (n_samples, n_features)] The input data to complete.

Returns

Xt [array-like, shape (n_samples, n_features)] The imputed input data.
Examples using `sklearn.impute.IterativeImputer`

- Imputing missing values with variants of `IterativeImputer`
- Imputing missing values before building an estimator

### 7.17.3 `sklearn.impute.MissingIndicator`

**class** `sklearn.impute.MissingIndicator(*, missing_values=nan, features='missing-only', sparse='auto', error_on_new=True)`

Binary indicators for missing values.

Note that this component typically should not be used in a vanilla `Pipeline` consisting of transformers and a classifier, but rather could be added using a `FeatureUnion` or `ColumnTransformer`.

Read more in the *User Guide*.

New in version 0.20.

**Parameters**

- **missing_values** ([int, float, string, `np.nan` or None, default=`np.nan`]) The placeholder for the missing values. All occurrences of `missing_values` will be imputed. For pandas' dataframes with nullable integer dtypes with missing values, `missing_values` should be set to `np.nan`, since `pd.NA` will be converted to `np.nan`.

- **features** ([`'missing-only'`, `'all'`, default=`'missing-only'`]) Whether the imputer mask should represent all or a subset of features.
  - If `missing-only` (default), the imputer mask will only represent features containing missing values during fit time.
  - If `all`, the imputer mask will represent all features.

- **sparse** ([bool or `auto`, default=`auto`]) Whether the imputer mask format should be sparse or dense.
  - If `auto` (default), the imputer mask will be of same type as input.
  - If `True`, the imputer mask will be a sparse matrix.
  - If `False`, the imputer mask will be a numpy array.

- **error_on_new** ([bool, default=True]) If `True`, transform will raise an error when there are features with missing values in transform that have no missing values in fit. This is applicable only when `features='missing-only'`.

**Attributes**

- **features_** ([ndarray, shape (n_missing_features,) or (n_features,))] The features indices which will be returned when calling `transform`. They are computed during `fit`. For `features='all'`, it is to range(n_features).
Examples

```python
>>> import numpy as np
>>> from sklearn.impute import MissingIndicator

>>> X1 = np.array([[np.nan, 1, 3],
                 [4, 0, np.nan],
                 [8, 1, 0]])

>>> X2 = np.array([[5, 1, np.nan],
                 [np.nan, 2, 3],
                 [2, 4, 0]])

>>> indicator = MissingIndicator()

>>> indicator.fit(X1)

>>> X2_tr = indicator.transform(X2)

>>> X2_tr
array([[False,  True],
       [ True, False],
       [False, False]])
```

Methods

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<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td><code>fit(X, y)</code></td>
<td>Fit the transformer on X.</td>
</tr>
<tr>
<td><code>fit_transform(X, y)</code></td>
<td>Generate missing values indicator for X.</td>
</tr>
<tr>
<td><code>get_params(deep)</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Generate missing values indicator for X.</td>
</tr>
</tbody>
</table>

`fit(X, y=None)`

Fit the transformer on X.

Parameters

- **X** ([array-like, sparse matrix], shape (n_samples, n_features)) Input data, where n_samples is the number of samples and n_features is the number of features.

Returns

- **self** [object] Returns self.

`fit_transform(X, y=None)`

Generate missing values indicator for X.

Parameters

- **X** ([array-like, sparse matrix], shape (n_samples, n_features)) The input data to complete.

Returns

- **Xt** [ndarray or sparse matrix], shape (n_samples, n_features) or (n_samples, n_features_with_missing) The missing indicator for input data. The data type of Xt will be boolean.

`get_params(deep=True)`

Get parameters for this estimator.

Parameters
deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Generate missing values indicator for X.

Parameters

X [{array-like, sparse matrix}, shape (n_samples, n_features)] The input data to complete.

Returns

Xt [{ndarray or sparse matrix}, shape (n_samples, n_features) or (n_samples,
n_features_with_missing)] The missing indicator for input data. The data type of Xt will
be boolean.

7.17.4 sklearn.impute.KNNImputer

class sklearn.impute.KNNImputer(*, missing_values=nan, n_neighbors=5, weights='uniform',
metric='nan_euclidean', copy=True, add_indicator=False)
Imputation for completing missing values using k-Nearest Neighbors.

Each sample’s missing values are imputed using the mean value from n_neighbors nearest neighbors found
in the training set. Two samples are close if the features that neither is missing are close.

Read more in the User Guide.

New in version 0.22.

Parameters

missing_values [int, float, str, np.nan or None, default=np.nan] The placeholder for the missing
values. All occurrences of missing_values will be imputed. For pandas’ dataframes
with nullable integer dtypes with missing values, missing_values should be set to
np.nan, since pd.NA will be converted to np.nan.

n_neighbors [int, default=5] Number of neighboring samples to use for imputation.

weights [{‘uniform’, ‘distance’} or callable, default=’uniform’] Weight function used in pre-
diction. Possible values:

• ‘uniform’ : uniform weights. All points in each neighborhood are weighted equally.
• ‘distance’ : weight points by the inverse of their distance. in this case, closer neighbors
of a query point will have a greater influence than neighbors which are further away.
• callable : a user-defined function which accepts an array of distances, and returns an array of the same shape containing the weights.

metric : ['nan_euclidean'] or callable, default='nan_euclidean' Distance metric for searching neighbors. Possible values:
  • 'nan_euclidean'
  • callable : a user-defined function which conforms to the definition of _pairwise_callable(X, Y, metric, **kwds). The function accepts two arrays, X and Y, and a missing_values keyword in kwds and returns a scalar distance value.

copy : bool, default=True] If True, a copy of X will be created. If False, imputation will be done in-place whenever possible.

default=False] If True, a MissingIndicator transform will stack onto the output of the imputer’s transform. This allows a predictive estimator to account for missingness despite imputation. If a feature has no missing values at fit/train time, the feature won’t appear on the missing indicator even if there are missing values at transform/test time.

Attributes

indicator_ : [MissingIndicator] Indicator used to add binary indicators for missing values. None if add_indicator is False.

References

• Olga Troyanskaya, Michael Cantor, Gavin Sherlock, Pat Brown, Trevor Hastie, Robert Tibshirani, David Botstein and Russ B. Altman, Missing value estimation methods for DNA microarrays, BIOINFORMATICS Vol. 17 no. 6, 2001 Pages 520-525.

Examples

```python
>>> import numpy as np
>>> from sklearn.impute import KNNImputer
>>> X = [[1, 2, np.nan], [3, 4, 3], [np.nan, 6, 5], [8, 8, 7]]
>>> imputer = KNNImputer(n_neighbors=2)
>>> imputer.fit_transform(X)
array([[1., 2., 4.],
       [3., 4., 3.],
       [5.5, 6., 5.],
       [8., 8., 7.]])
```

Methods

```python
fit(X[, y]) Fit the imputer on X.
fit_transform(X[, y]) Fit to data, then transform it.
get_params([deep]) Get parameters for this estimator.
set_params(**params) Set the parameters of this estimator.
transform(X) Impute all missing values in X.
```
Fit the imputer on X.

**Parameters**

- **X** [array-like shape of (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

**Returns**

- **self** [object] fit_transform(X, y=None, **fit_params)**

  Fit to data, then transform it.

  Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

  **Parameters**

  - **X** [array-like of shape (n_samples, n_features)] Input samples.
  - **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

  ****fit_params [dict] Additional fit parameters.

  **Returns**

  - **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** (**deep=True**) Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**set_params** (****params**) Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- ****params [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**transform** (**X**) Impute all missing values in X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] The input data to complete.

**Returns**
X [array-like of shape (n_samples, n_output_features)] The imputed dataset. n_output_features is the number of features that is not always missing during fit.

Examples using sklearn.impute.KNNImputer

- Release Highlights for scikit-learn 0.22
- Imputing missing values before building an estimator

7.18 sklearn.inspection: Inspection

The sklearn.inspection module includes tools for model inspection.

```
import inspect.partial_dependence(estimator, X, ...)  
import inspect.permutation_importance(estimator, X, ...)  
```

7.18.1 sklearn.inspection.partial_dependence

sklearn.inspection.partial_dependence (estimator, X, features, *response_method='auto', percentiles=0.05, 0.95, grid_resolution=100, method='auto', kind='legacy')

Partial dependence of features.

Partial dependence of a feature (or a set of features) corresponds to the average response of an estimator for each possible value of the feature.

Read more in the User Guide.

**Warning:** For GradientBoostingClassifier and GradientBoostingRegressor, the 'recursion' method (used by default) will not account for the init predictor of the boosting process. In practice, this will produce the same values as 'brute' up to a constant offset in the target response, provided that init is a constant estimator (which is the default). However, if init is not a constant estimator, the partial dependence values are incorrect for 'recursion' because the offset will be sample-dependent. It is preferable to use the 'brute' method. Note that this only applies to GradientBoostingClassifier and GradientBoostingRegressor, not to HistGradientBoostingClassifier and HistGradientBoostingRegressor.

**Parameters**

- **estimator** [BaseEstimator] A fitted estimator object implementing predict, predict_proba, or decision_function. Multioutput-multiclass classifiers are not supported.

- **X** [array-like or dataframe] of shape (n_samples, n_features) X is used to generate a grid of values for the target features (where the partial dependence will be evaluated), and also to generate values for the complement features when the method is ‘brute’.

- **features** [array-like of {int, str}] The feature (e.g. [0]) or pair of interacting features (e.g. [(0, 1)]) for which the partial dependency should be computed.
**response_method** ([‘auto’, ‘predict_proba’, ‘decision_function’], default=’auto’) Specifies whether to use `predict_proba` or `decision_function` as the target response. For regressors this parameter is ignored and the response is always the output of `predict`. By default, `predict_proba` is tried first and we revert to `decision_function` if it doesn’t exist. If method is ‘recursion’, the response is always the output of `decision_function`.

**percentiles** [tuple of float, default=(0.05, 0.95)] The lower and upper percentile used to create the extreme values for the grid. Must be in [0, 1].

**grid_resolution** [int, default=100] The number of equally spaced points on the grid, for each target feature.

**method** ([‘auto’, ‘recursion’, ‘brute’], default=’auto’) The method used to calculate the averaged predictions:

- 'recursion' is only supported for some tree-based estimators (namely `GradientBoostingClassifier`, `GradientBoostingRegressor`, `HistGradientBoostingClassifier`, `HistGradientBoostingRegressor`, `DecisionTreeRegressor`, `RandomForestRegressor`,) when kind='average'. This is more efficient in terms of speed. With this method, the target response of a classifier is always the decision function, not the predicted probabilities. Since the 'recursion' method implicitly computes the average of the Individual Conditional Expectation (ICE) by design, it is not compatible with ICE and thus kind must be 'average'.

- 'brute' is supported for any estimator, but is more computationally intensive.

- 'auto': the 'recursion' is used for estimators that support it, and 'brute' is used otherwise.

Please see this note for differences between the 'brute' and 'recursion' method.

**kind** ([‘legacy’, ‘average’, ‘individual’, ‘both’], default=‘legacy’) Whether to return the partial dependence averaged across all the samples in the dataset or one line per sample or both. See Returns below.

Note that the fast method='recursion' option is only available for kind='average'. Plotting individual dependencies requires using the slower method='brute' option.

New in version 0.24.

Deprecated since version 0.24: kind='legacy' is deprecated and will be removed in version 1.1. kind='average' will be the new default. It is intended to migrate from the ndarray output to Bunch output.

**Returns**

**predictions** [ndarray or Bunch]

- if kind='legacy', return value is ndarray of shape (n_outputs, len(values[0]), len(values[1]), . . . ) The predictions for all the points in the grid, averaged over all samples in X (or over the training data if method is 'recursion').

- if kind='individual', 'average' or 'both', return value is Bunch Dictionary-like object, with the following attributes.

  **individual** [ndarray of shape (n_outputs, n_instances, len(values[0]), len(values[1]), . . .)] The predictions for all the points in the grid for all samples in X. This is also known as Individual Conditional Expectation (ICE)
average [ndarray of shape (n_outputs, len(values[0]), len(values[1]), ...)] The predictions for all the points in the grid, averaged over all samples in X (or over the training data if method is 'recursion'). Only available when kind='both'.

values [seq of 1d ndarrays] The values with which the grid has been created. The generated grid is a cartesian product of the arrays in values. len(values) == len(features). The size of each array values[j] is either grid_resolution, or the number of unique values in X[:, j], whichever is smaller.

n_outputs corresponds to the number of classes in a multi-class setting, or to the number of tasks for multi-output regression. For classical regression and binary classification n_outputs==1.

n_values_feature_j corresponds to the size values[j].

values [seq of 1d ndarrays] The values with which the grid has been created. The generated grid is a cartesian product of the arrays in values. len(values) == len(features). The size of each array values[j] is either grid_resolution, or the number of unique values in X[:, j], whichever is smaller. Only available when kind="legacy".

See also:

plot_partial_dependence Plot Partial Dependence.

PartialDependenceDisplay Partial Dependence visualization.

Examples

```python
>>> X = [[0, 0, 2], [1, 0, 0]]
>>> y = [0, 1]
>>> from sklearn.ensemble import GradientBoostingClassifier
>>> gb = GradientBoostingClassifier(random_state=0).fit(X, y)
>>> partial_dependence(gb, features=[0], X=X, percentiles=(0, 1),
... grid_resolution=2)
(array([[-4.52..., 4.52...]], [array([ 0., 1.])])
```

Examples using sklearn.inspection.partial_dependence

- Partial Dependence and Individual Conditional Expectation Plots

7.18.2 sklearn.inspection.permutation_importance

```python
sklearn.inspection.permutation_importance(estimator, X, y, *, scoring=None, n_repeats=5, n_jobs=None, random_state=None, sample_weight=None)
```

Permutation importance for feature evaluation [BRE].

The estimator is required to be a fitted estimator. X can be the data set used to train the estimator or a hold-out set. The permutation importance of a feature is calculated as follows. First, a baseline metric, defined by scoring, is evaluated on a (potentially different) dataset defined by the X. Next, a feature column from the validation set is permuted and the metric is evaluated again. The permutation importance is defined to be the difference between the baseline metric and metric from permutating the feature column.

Read more in the User Guide.

7.18. sklearn.inspection: Inspection

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Parameters

**estimator** [object] An estimator that has already been fitted and is compatible with scorer.

**X** [ndarray or DataFrame, shape (n_samples, n_features)] Data on which permutation importance will be computed.

**y** [array-like or None, shape (n_samples, ) or (n_samples, n_classes)] Targets for supervised or None for unsupervised.

**scoring** [string, callable or None, default=None] Scorer to use. It can be a single string (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions). If None, the estimator’s default scorer is used.

**n_repeats** [int, default=5] Number of times to permute a feature.

**n_jobs** [int or None, default=None] Number of jobs to run in parallel. The computation is done by computing permutation score for each columns and parallelized over the columns. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance, default=None] Pseudo-random number generator to control the permutations of each feature. Pass an int to get reproducible results across function calls. See :term: Glossary <random_state>.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights used in scoring.

New in version 0.24.

Returns

**result** [Bunch] Dictionary-like object, with the following attributes.

**importances_mean** [ndarray, shape (n_features, )] Mean of feature importance over n_repeats.

**importances_std** [ndarray, shape (n_features, )] Standard deviation over n_repeats.

**importances** [ndarray, shape (n_features, n_repeats)] Raw permutation importance scores.

References

[BRE]

Examples

```python
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.inspection import permutation_importance

>>> X = [[1, 9, 9],[1, 9, 9],[1, 9, 9],
      ... [0, 9, 9],[0, 9, 9],[0, 9, 9]]
>>> y = [1, 1, 1, 0, 0, 0]
>>> clf = LogisticRegression().fit(X, y)
>>> result = permutation_importance(clf, X, y, n_repeats=10,
...                                  random_state=0)

>>> result.importances_mean
array([0.4666..., 0., 0.])
>>> result.importances_std
array([0.2211..., 0., 0.])
```
Examples using sklearn.inspection.permutation_importance

- Release Highlights for scikit-learn 0.22
- Feature importances with forests of trees
- Gradient Boosting regression
- Permutation Importance with Multicollinear or Correlated Features
- Permutation Importance vs Random Forest Feature Importance (MDI)

7.18.3 Plotting

```
sklearn.inspection.PartialDependenceDisplay(...[, Partial Dependence Plot (PDP).

sklearn.inspection.PartialDependenceDisplay

class sklearn.inspection.PartialDependenceDisplay(pd_results, *, features, feature_names, target_idx, pdp_lim, deciles, kind='average', subsample=1000, random_state=None)

Partial Dependence Plot (PDP).
This can also display individual partial dependencies which are often referred to as: Individual Condition Expectation (ICE).
It is recommended to use plot_partial_dependence to create a PartialDependenceDisplay. All parameters are stored as attributes.
Read more in Advanced Plotting With Partial Dependence and the User Guide.

New in version 0.22.

Parameters

pd_results [list of Bunch] Results of partial_dependence for features.
features [list of (int,) or list of (int, int)] Indices of features for a given plot. A tuple of one integer will plot a partial dependence curve of one feature. A tuple of two integers will plot a two-way partial dependence curve as a contour plot.
feature_names [list of str] Feature names corresponding to the indices in features.
target_idx [int]
  • In a multiclass setting, specifies the class for which the PDPs should be computed. Note that for binary classification, the positive class (index 1) is always used.
  • In a multioutput setting, specifies the task for which the PDPs should be computed. Ignored in binary classification or classical regression settings.
pdp_lim [dict] Global min and max average predictions, such that all plots will have the same scale and y limits. pdp_lim[1] is the global min and max for single partial dependence curves. pdp_lim[2] is the global min and max for two-way partial dependence curves.
deciles [dict] Deciles for feature indices in features.
kind [{‘average’, ‘individual’, ‘both’}, default=‘average’]

Whether to plot the partial dependence averaged across all the samples in the dataset or one line per sample or both.

- kind='average' results in the traditional PD plot;
- kind='individual' results in the ICE plot.

Note that the fast method='recursion' option is only available for kind='average'. Plotting individual dependencies requires using the slower method='brute' option.

New in version 0.24.

subsample [float, int or None, default=1000] Sampling for ICE curves when kind is ‘individual’ or ‘both’. If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to be used to plot ICE curves. If int, represents the maximum absolute number of samples to use.

Note that the full dataset is still used to calculate partial dependence when kind='both'.

New in version 0.24.

random_state [int, RandomState instance or None, default=None] Controls the randomness of the selected samples when subsamples is not None. See Glossary for details.

New in version 0.24.

Attributes

bounding_ax_ [matplotlib Axes or None] If ax is an axes or None, the bounding_ax_ is the axes where the grid of partial dependence plots are drawn. If ax is a list of axes or a numpy array of axes, bounding_ax_ is None.

axes_ [ndarray of matplotlib Axes] If ax is an axes or None, axes_ [i, j] is the axes on the i-th row and j-th column. If ax is a list of axes, axes_- [i] is the i-th item in ax. Elements that are None correspond to a nonexisting axes in that position.

lines_ [ndarray of matplotlib Artists] If ax is an axes or None, lines_- [i, j] is the partial dependence curve on the i-th row and j-th column. If ax is a list of axes, lines_- [i] is the partial dependence curve corresponding to the i-th item in ax. Elements that are None correspond to a nonexisting axes or an axes that does not include a line plot.

deciles_vlines_ [ndarray of matplotlib LineCollection] If ax is an axes or None, vlines_- [i, j] is the line collection representing the x axis deciles of the i-th row and j-th column. If ax is a list of axes, vlines_- [i] corresponds to the i-th item in ax. Elements that are None correspond to a nonexisting axes or an axes that does not include a PDP plot.

New in version 0.23.

deciles_hlines_ [ndarray of matplotlib LineCollection] If ax is an axes or None, hlines_- [i, j] is the line collection representing the y axis deciles of the i-th row and j-th column. If ax is a list of axes, hlines_- [i] corresponds to the i-th item in ax. Elements that are None correspond to a nonexisting axes or an axes that does not include a 2-way plot.

New in version 0.23.

contours_ [ndarray of matplotlib Artists] If ax is an axes or None, contours_- [i, j] is the partial dependence plot on the i-th row and j-th column. If ax is a list of axes, contours_- [i] is the partial dependence plot corresponding to the i-th item in ax. Elements that are None correspond to a nonexisting axes or an axes that does not include a contour plot.
**figure** [matplotlib Figure] Figure containing partial dependence plots.

See also:

*partial_dependence* Compute Partial Dependence values.

*plot_partial_dependence* Plot Partial Dependence.

**Methods**

```
plot(*[, ax, n_cols, line_kw, contour_kw]) Plot partial dependence plots.
```

```
plot (*, ax=None, n_cols=3, line_kw=None, contour_kw=None)
Plot partial dependence plots.
```

**Parameters**

*ax* [Matplotlib axes or array-like of Matplotlib axes, default=None]

- **If a single axis is passed in, it is treated as a bounding axes** and a grid of partial dependence plots will be drawn within these bounds. The `n_cols` parameter controls the number of columns in the grid.
- **If an array-like of axes are passed in, the partial dependence** plots will be drawn directly into these axes.
- **If None, a figure and a bounding axes is created and treated** as the single axes case.

*n_cols* [int, default=3] The maximum number of columns in the grid plot. Only active when `ax` is a single axes or `None`.

*line_kw* [dict, default=None] Dict with keywords passed to the `matplotlib.pyplot.plot` call. For one-way partial dependence plots.

*contour_kw* [dict, default=None] Dict with keywords passed to the `matplotlib.pyplot.contourf` call for two-way partial dependence plots.

**Returns**

*display* [PartialDependenceDisplay]

**Examples using sklearn.inspection.PartialDependenceDisplay**

- **Advanced Plotting With Partial Dependence**

```
inspection.plot_partial_dependence(...[, ...
```

Partial dependence (PD) and individual conditional expectation (ICE) plots.
**sklearn.inspection.plot_partial_dependence**

The `sklearn.inspection.plot_partial_dependence` function can be used to generate partial dependence plots (PDPs) and individual conditional expectation (ICE) plots.

- **estimator** ([BaseEstimator]) A fitted estimator object implementing `predict`, `predict_proba`, or `decision_function`. Multioutput-multiclass classifiers are not supported.
- **X** ([array-like or dataframe] of shape (n_samples, n_features)) `X` is used to generate a grid of values for the target features (where the partial dependence will be evaluated), and also to generate values for the complement features when the method is 'brute'.
- **features** (list of (int, str, pair of int, pair of str)) The target features for which to create the PDPs. If `features[i]` is an integer or a string, a one-way PDP is created; if `features[i]` is

**Warning:** For `GradientBoostingClassifier` and `GradientBoostingRegressor`, the 'recursion' method (used by default) will not account for the `init` predictor of the boosting process. In practice, this will produce the same values as 'brute' up to a constant offset in the target response, provided that `init` is a constant estimator (which is the default). However, if `init` is not a constant estimator, the partial dependence values are incorrect for 'recursion' because the offset will be sample-dependent. It is preferable to use the 'brute' method. Note that this only applies to `GradientBoostingClassifier` and `GradientBoostingRegressor`, not to `HistGradientBoostingClassifier` and `HistGradientBoostingRegressor`.

Note: `plot_partial_dependence` does not support using the same axes with multiple calls. To plot the dependence for multiple estimators, please pass the axes created by the first call to the second call:

```python
>>> from sklearn.inspection import plot_partial_dependence
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.linear_model import LinearRegression
>>> X, y = make_friedman1()
>>> est1 = LinearRegression().fit(X, y)
>>> disp1 = plot_partial_dependence(est1, X, ...
... [1, 2])
>>> disp2 = plot_partial_dependence(est2, X, [1, 2],
... ax=disp1.axes_)
```
a tuple, a two-way PDP is created (only supported with kind='average'). Each tuple must be of size 2, if any entry is a string, then it must be in feature_names.

**feature_names** [array-like of shape (n_features,), dtype=str, default=None] Name of each feature; feature_names[i] holds the name of the feature with index i. By default, the name of the feature corresponds to their numerical index for NumPy array and their column name for pandas dataframe.

**target** [int, default=None]

- In a multiclass setting, specifies the class for which the PDPs should be computed. Note that for binary classification, the positive class (index 1) is always used.
- In a multioutput setting, specifies the task for which the PDPs should be computed.

Ignored in binary classification or classical regression settings.

**response_method** [{'auto', 'predict_proba', 'decision_function'}, default='auto'] Specifies whether to use predict_proba or decision_function as the target response. For regressors this parameter is ignored and the response is always the output of predict. By default, predict_proba is tried first and we revert to decision_function if it doesn’t exist. If method is 'recursion', the response is always the output of decision_function.

**n_cols** [int, default=3] The maximum number of columns in the grid plot. Only active when ax is a single axis or None.

**grid_resolution** [int, default=100] The number of equally spaced points on the axes of the plots, for each target feature.

**percentiles** [tuple of float, default=(0.05, 0.95)] The lower and upper percentile used to create the extreme values for the PDP axes. Must be in [0, 1].

**method** [str, default='auto'] The method used to calculate the averaged predictions:

- 'recursion' is only supported for some tree-based estimators (namely GradientBoostingClassifier, GradientBoostingRegressor, HistGradientBoostingClassifier, HistGradientBoostingRegressor, DecisionTreeRegressor, RandomForestRegressor but is more efficient in terms of speed. With this method, the target response of a classifier is always the decision function, not the predicted probabilities. Since the 'recursion' method implicitly computes the average of the ICEs by design, it is not compatible with ICE and thus kind must be 'average'.
- 'brute' is supported for any estimator, but is more computationally intensive.
- 'auto': the 'recursion' is used for estimators that support it, and 'brute' is used otherwise.

Please see this note for differences between the 'brute' and 'recursion' method.

**n_jobs** [int, default=None] The number of CPUs to use to compute the partial dependences. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**verbose** [int, default=0] Verbose output during PD computations.

**line_kw** [dict, default=None] Dict with keywords passed to the matplotlib.pyplot.plot call. For one-way partial dependence plots.

**contour_kw** [dict, default=None] Dict with keywords passed to the matplotlib.pyplot.contourf call. For two-way partial dependence plots.
**ax** [Matplotlib axes or array-like of Matplotlib axes, default=None]

- If a single axis is passed in, it is treated as a bounding axes and a grid of partial dependence plots will be drawn within these bounds. The `n_cols` parameter controls the number of columns in the grid.
- If an array-like of axes are passed in, the partial dependence plots will be drawn directly into these axes.
- If None, a figure and a bounding axes is created and treated as the single axes case.

New in version 0.22.

**kind** [{'average', 'individual', 'both'}, default='average']

Whether to plot the partial dependence averaged across all the samples in the dataset or one line per sample or both.

- kind='average' results in the traditional PD plot;
- kind='individual' results in the ICE plot.

Note that the fast method='recursion' option is only available for kind='average'. Plotting individual dependencies requires using the slower method='brute' option.

New in version 0.24.

**subsample** [float, int or None, default=1000] Sampling for ICE curves when kind is 'individual' or 'both'. If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to be used to plot ICE curves. If int, represents the absolute number samples to use.

Note that the full dataset is still used to calculate averaged partial dependence when kind='both'.

New in version 0.24.

**random_state** [int, RandomState instance or None, default=None] Controls the randomness of the selected samples when subsamples is not None and kind is either 'both' or 'individual'. See Glossary for details.

New in version 0.24.

**Returns**

**display** [PartialDependenceDisplay]

**See also:**

partial_dependence Compute Partial Dependence values.

PartialDependenceDisplay Partial Dependence visualization.
Examples

```python
>>> from sklearn.datasets import make_friedman1
>>> from sklearn.ensemble import GradientBoostingRegressor
>>> X, y = make_friedman1()
>>> clf = GradientBoostingRegressor(n_estimators=10).fit(X, y)
>>> plot_partial_dependence(clf, X, [0, (0, 1)])
```

Examples using `sklearn.inspection.plot_partial_dependence`

- Release Highlights for scikit-learn 0.23
- Release Highlights for scikit-learn 0.24
- Monotonic Constraints
- Partial Dependence and Individual Conditional Expectation Plots
- Advanced Plotting With Partial Dependence

## 7.19 sklearn.isotonic: Isotonic regression

**User guide:** See the *Isotonic regression* section for further details.

```python
isotonic.IsotonicRegression(*[, y_min, ...])
```

### 7.19.1 sklearn.isotonic.IsotonicRegression

```python
class sklearn.isotonic.IsotonicRegression(*, y_min=None, y_max=None, increasing=True, out_of_bounds='nan')
```

Isotonic regression model.

Read more in the *User Guide*.

New in version 0.13.

**Parameters**

- `y_min` [float, default=None] Lower bound on the lowest predicted value (the minimum value may still be higher). If not set, defaults to -inf.
- `y_max` [float, default=None] Upper bound on the highest predicted value (the maximum may still be lower). If not set, defaults to +inf.
- `increasing` [bool or ‘auto’, default=True] Determines whether the predictions should be constrained to increase or decrease with \( X \). ‘auto’ will decide based on the Spearman correlation estimate’s sign.
- `out_of_bounds` [‘nan’, ‘clip’, ‘raise’], default=’nan’] Handles how \( X \) values outside of the training domain are handled during prediction.
  - ‘nan’, predictions will be NaN.
  - ‘clip’, predictions will be set to the value corresponding to the nearest train interval endpoint.
• 'raise', a `ValueError` is raised.

Attributes

**X_min_**  [float] Minimum value of input array `X_` for left bound.

**X_max_**  [float] Maximum value of input array `X_` for right bound.

**X_thresholds_** [ndarray of shape (n_thresholds,)] Unique ascending `X` values used to interpo-
late the `y = f(X)` monotonic function.

New in version 0.24.

**y_thresholds_** [ndarray of shape (n_thresholds,)] De-duplicated `y` values suitable to interpolate
the `y = f(X)` monotonic function.

New in version 0.24.

**f_**  [function] The stepwise interpolating function that covers the input domain `X`.

**increasing_**  [bool] Inferred value for `increasing`.

Notes

Ties are broken using the secondary method from de Leeuw, 1977.

References

Isotonic Median Regression: A Linear Programming Approach Nilotpal Chakravarti Mathematics of Operations
Research Vol. 14, No. 2 (May, 1989), pp. 303-308

Isotone Optimization in R : Pool-Adjacent-Violators Algorithm (PAVA) and Active Set Methods de Leeuw,
Hornik, Mair Journal of Statistical Software 2009

Correctness of Kruskal’s algorithms for monotone regression with ties de Leeuw, Psychometrica, 1977

Examples

```python
>>> from sklearn.datasets import make_regression
>>> from sklearn.isotonic import IsotonicRegression
>>> X, y = make_regression(n_samples=10, n_features=1, random_state=41)
>>> iso_reg = IsotonicRegression().fit(X, y)
>>> iso_reg.predict([.1, .2])
array([1.8628..., 3.7256...])
```

Methods

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</table>
| `score(X, y[, sample_weight])` | Return the coefficient of determination $R^2$ of the pre-
diction. |
| `set_params(**params)` | Set the parameters of this estimator. |
| `transform(T)` | Transform new data by linear interpolation |
**fit** *(X, y, sample_weight=None)*  
Fit the model using X, y as training data.

Parameters

- **X** [array-like of shape (n_samples,) or (n_samples, 1)] Training data.
  
  Changed in version 0.24: Also accepts 2d array with 1 feature.

- **y** [array-like of shape (n_samples,)] Training target.

- **sample_weight** [array-like of shape (n_samples,), default=None] Weights. If set to None, all weights will be set to 1 (equal weights).

Returns

- **self** [object] Returns an instance of self.

Notes

X is stored for future use, as *transform* needs X to interpolate new input data.

**fit_transform** *(X, y=None, **fit_params)*  
Fit to data, then transform it.

Fits transformer to X and y with optional parameters *fit_params* and returns a transformed version of X.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Input samples.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

- ****fit_params** [dict] Additional fit parameters.

Returns

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** *(deep=True)*  
Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict** *(T)*  
Predict new data by linear interpolation.

Parameters

- **T** [array-like of shape (n_samples,) or (n_samples, 1)] Data to transform.

Returns

- **y_pred** [ndarray of shape (n_samples,)] Transformed data.
score \((X, y, \text{sample\_weight}=\text{None})\)

Return the coefficient of determination \(R^2\) of the prediction.

The coefficient \(R^2\) is defined as \((1 - \frac{u}{v})\), where \(u\) is the residual sum of squares \(((y_{\text{true}} - y_{\text{pred}})^2).\text{sum}()\) and \(v\) is the total sum of squares \(((y_{\text{true}} - y_{\text{true}}.\text{mean()})^2).\text{sum}()\).

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \(y\), disregarding the input features, would get a \(R^2\) score of 0.0.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \(X\).
- **sample\_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **score** [float] \(R^2\) of self.predict \((X)\) wrt \(y\).

Notes

The \(R^2\) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

transform \((T)\)

Transform new data by linear interpolation

Parameters

- **T** [array-like of shape (n_samples,) or (n_samples, 1)] Data to transform.

Changed in version 0.24: Also accepts 2d array with 1 feature.

Returns

- **y\_pred** [ndarray of shape (n_samples,)] The transformed data
Examples using `sklearn.isotonic.IsotonicRegression`

- **Isotonic Regression**

  - `isotonic.check_increasing(x, y)` Determine whether y is monotonically correlated with x.
  - `isotonic.isotonic_regression(y, *[...])` Solve the isotonic regression model.

7.19.2 `sklearn.isotonic.check_increasing`

`sklearn.isotonic.check_increasing(x, y)`

Determine whether y is monotonically correlated with x.

- y is found increasing or decreasing with respect to x based on a Spearman correlation test.

  **Parameters**
  
  - x [array-like of shape (n_samples,)] Training data.
  - y [array-like of shape (n_samples,)] Training target.

  **Returns**
  
  - **increasing_bool** [boolean] Whether the relationship is increasing or decreasing.

  **Notes**

  The Spearman correlation coefficient is estimated from the data, and the sign of the resulting estimate is used as the result.

  In the event that the 95% confidence interval based on Fisher transform spans zero, a warning is raised.

  **References**


7.19.3 `sklearn.isotonic.isotonic_regression`

`sklearn.isotonic.isotonic_regression(y, *, sample_weight=None, y_min=None, y_max=None, increasing=True)`

Solve the isotonic regression model.

Read more in the *User Guide*.

**Parameters**

- y [array-like of shape (n_samples,)] The data.
  - `sample_weight` [array-like of shape (n_samples,), default=None] Weights on each point of the regression. If None, weight is set to 1 (equal weights).
  - `y_min` [float, default=None] Lower bound on the lowest predicted value (the minimum value may still be higher). If not set, defaults to -inf.
  - `y_max` [float, default=None] Upper bound on the highest predicted value (the maximum may still be lower). If not set, defaults to +inf.
increasing [bool, default=True] Whether to compute \( y_\) is increasing (if set to True) or decreasing (if set to False)

Returns

\( y_\) [list of floats] Isotonic fit of \( y\).

References

“Active set algorithms for isotonic regression; A unifying framework” by Michael J. Best and Nilotpal Chakravarti, section 3.

7.20 sklearn.kernel_approximation: Kernel Approximation

The `sklearn.kernel_approximation` module implements several approximate kernel feature maps based on Fourier transforms and Count Sketches.

**User guide:** See the Kernel Approximation section for further details.

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7.20.1 sklearn.kernel_approximation.AdditiveChi2Sampler

**class sklearn.kernel_approximation.AdditiveChi2Sampler(*, sample_steps=2, sample_interval=None)**

Approximate feature map for additive chi2 kernel.

Uses sampling the fourier transform of the kernel characteristic at regular intervals.

Since the kernel that is to be approximated is additive, the components of the input vectors can be treated separately. Each entry in the original space is transformed into \( 2*\text{sample_steps}+1 \) features, where \( \text{sample_steps} \) is a parameter of the method. Typical values of \( \text{sample_steps} \) include 1, 2 and 3.

Optimal choices for the sampling interval for certain data ranges can be computed (see the reference). The default values should be reasonable.

Read more in the User Guide.

**Parameters**

- **sample_steps** [int, default=2] Gives the number of (complex) sampling points.
- **sample_interval** [float, default=None] Sampling interval. Must be specified when \( \text{sample_steps} \) not in \{1,2,3\}.

**Attributes**
sample_interval_ [float] Stored sampling interval. Specified as a parameter if sample_steps not in {1,2,3}.

See also:

SkewedChi2Sampler A Fourier-approximation to a non-additive variant of the chi squared kernel.
sklearn.metrics.pairwise.chi2_kernel The exact chi squared kernel.
sklearn.metrics.pairwise.additive_chi2_kernel The exact additive chi squared kernel.

Notes

This estimator approximates a slightly different version of the additive chi squared kernel then metric.additive_chi2 computes.

References

See “Efficient additive kernels via explicit feature maps” A. Vedaldi and A. Zisserman, Pattern Analysis and Machine Intelligence, 2011

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.linear_model import SGDClassifier
>>> from sklearn.kernel_approximation import AdditiveChi2Sampler
>>> X, y = load_digits(return_X_y=True)
>>> chi2sampler = AdditiveChi2Sampler(sample_steps=2)
>>> X_transformed = chi2sampler.fit_transform(X, y)
>>> clf = SGDClassifier(max_iter=5, random_state=0, tol=1e-3)
>>> clf.fit(X_transformed, y)
SGDClassifier(max_iter=5, random_state=0)
>>> clf.score(X_transformed, y)
0.9499...
```

Methods

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<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>set_params(**params)</code></td>
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<tr>
<td><code>transform(X)</code></td>
<td>Apply approximate feature map to X.</td>
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</table>

`fit(X, y=None)`

Set the parameters

Parameters

- **X** [array-like, shape (n_samples, n_features)] Training data, where n_samples in the number of samples and n_features is the number of features.

Returns
self [object] Returns the transformer.

**fit_transform**(X, y=None, **fit_params)**
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values.

**fit_params** [dict] Additional fit parameters.

**Returns**

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**set_params**(**params)**
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<\text{component}>__<\text{parameter}>\) so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(X)
Apply approximate feature map to X.

**Parameters**

X [array-like, sparse matrix] of shape (n_samples, n_features)]

**Returns**

X_new [ndarray, sparse matrix], shape = (n_samples, n_features * (2*sample_steps + 1))]
Whether the return value is an array of sparse matrix depends on the type of the input X.
Approximate a kernel map using a subset of the training data.

Constructs an approximate feature map for an arbitrary kernel using a subset of the data as basis.

Read more in the User Guide.

New in version 0.13.

**Parameters**

- `kernel` [string or callable, default='rbf'] Kernel map to be approximated. A callable should accept two arguments and the keyword arguments passed to this object as kernel_params, and should return a floating point number.

- `gamma` [float, default=None] Gamma parameter for the RBF, laplacian, polynomial, exponential chi2 and sigmoid kernels. Interpretation of the default value is left to the kernel; see the documentation for sklearn.metrics.pairwise. Ignored by other kernels.

- `coef0` [float, default=None] Zero coefficient for polynomial and sigmoid kernels. Ignored by other kernels.

- `degree` [float, default=None] Degree of the polynomial kernel. Ignored by other kernels.

- `kernel_params` [dict, default=None] Additional parameters (keyword arguments) for kernel function passed as callable object.

- `n_components` [int, default=100] Number of features to construct. How many data points will be used to construct the mapping.

- `random_state` [int, RandomState instance or None, default=None] Pseudo-random number generator to control the uniform sampling without replacement of n_components of the training data to construct the basis kernel. Pass an int for reproducible output across multiple function calls. See Glossary.

- `n_jobs` [int, default=None] The number of jobs to use for the computation. This works by breaking down the kernel matrix into n_jobs even slices and computing them in parallel.

  None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

  New in version 0.24.

**Attributes**

- `components_` [ndarray of shape (n_components, n_features)] Subset of training points used to construct the feature map.

- `component_indices_` [ndarray of shape (n_components)] Indices of components_ in the training set.

- `normalization_` [ndarray of shape (n_components, n_components)] Normalization matrix needed for embedding. Square root of the kernel matrix on components_.

**See also:**

- `RBFSampler` An approximation to the RBF kernel using random Fourier features.

- `sklearn.metrics.pairwise.kernel_metrics` List of built-in kernels.
References

- Williams, C.K.I. and Seeger, M. “Using the Nystroem method to speed up kernel machines”, Advances in neural information processing systems 2001

Examples

```python
>>> from sklearn import datasets, svm
>>> from sklearn.kernel_approximation import Nystroem
>>> X, y = datasets.load_digits(n_class=9, return_X_y=True)
>>> data = X / 16.
>>> clf = svm.LinearSVC()
>>> feature_map_nystroem = Nystroem(gamma=.2,
... random_state=1,
... n_components=300)
>>> data_transformed = feature_map_nystroem.fit_transform(data)
>>> clf.fit(data_transformed, y)
LinearSVC()
>>> clf.score(data_transformed, y)
0.9987...
```

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<td><code>fit_transform(X, y)</code></td>
<td>Fit to data, then transform it.</td>
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<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Apply feature map to X.</td>
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**fit (X, y=None)**

Fit estimator to data.

Samples a subset of training points, computes kernel on these and computes normalization matrix.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data.

**fit_transform (X, y=None, **fit_params)**

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Returns**
X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

   deep  [bool, default=True] If True, will return the parameters for this estimator and contained
          subobjects that are estimators.

Returns

   params  [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

   The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
   parameters of the form <component>__<parameter> so that it’s possible to update each component
   of a nested object.

Parameters

   **params  [dict] Estimator parameters.

Returns

   self  [estimator instance] Estimator instance.

transform (X)
Apply feature map to X.

   Computes an approximate feature map using the kernel between some training points and X.

Parameters

   X  [array-like of shape (n_samples, n_features)] Data to transform.

Returns

   X_transformed  [ndarray of shape (n_samples, n_components)] Transformed data.

Examples using sklearn.kernel_approximation.Nystroem

   • Explicit feature map approximation for RBF kernels

7.20.3 sklearn.kernel_approximation.PolynomialCountSketch

class sklearn.kernel_approximation.PolynomialCountSketch(*,  gamma=1.0,  degree=2,  coef0=0,  
n_components=100,  random_state=None)

Polynomial kernel approximation via Tensor Sketch.

   Implements Tensor Sketch, which approximates the feature map of the polynomial kernel:

   \[ K(X, Y) = (\gamma \cdot \langle X, Y \rangle + \text{coef0})^{\text{degree}} \]

   by efficiently computing a Count Sketch of the outer product of a vector with itself using Fast Fourier Transforms
   (FFT). Read more in the User Guide.

   New in version 0.24.
Parameters

- **gamma** [float, default=1.0] Parameter of the polynomial kernel whose feature map will be approximated.
- **degree** [int, default=2] Degree of the polynomial kernel whose feature map will be approximated.
- **coef0** [int, default=0] Constant term of the polynomial kernel whose feature map will be approximated.
- **n_components** [int, default=100] Dimensionality of the output feature space. Usually, n_components should be greater than the number of features in input samples in order to achieve good performance. The optimal score / run time balance is typically achieved around n_components = 10 * n_features, but this depends on the specific dataset being used.
- **random_state** [int, RandomState instance, default=None] Determines random number generation for indexHash and bitHash initialization. Pass an int for reproducible results across multiple function calls. See Glossary.

Attributes

- **indexHash_** [ndarray of shape (degree, n_features), dtype=int64] Array of indexes in range [0, n_components) used to represent the 2-wise independent hash functions for Count Sketch computation.
- **bitHash_** [ndarray of shape (degree, n_features), dtype=float32] Array with random entries in {+1, -1}, used to represent the 2-wise independent hash functions for Count Sketch computation.

Examples

```python
>>> from sklearn.kernel_approximation import PolynomialCountSketch
>>> from sklearn.linear_model import SGDClassifier

>>> X = [[0, 0], [1, 1], [1, 0], [0, 1]]
>>> y = [0, 0, 1, 1]
>>> ps = PolynomialCountSketch(degree=3, random_state=1)
>>> X_features = ps.fit_transform(X)
>>> clf = SGDClassifier(max_iter=10, tol=1e-3)
>>> clf.fit(X_features, y)
SGDClassifier(max_iter=10)
>>> clf.score(X_features, y)
1.0
```

Methods

- **fit** (X[, y]) Fit the model with X.
- **fit_transform** (X[, y]) Fit to data, then transform it.
- **get_params** (deep) Get parameters for this estimator.
- **set_params** (**params) Set the parameters of this estimator.
- **transform** (X) Generate the feature map approximation for X.

**fit** (X, y=None) Fit the model with X.
Initializes the internal variables. The method needs no information about the distribution of data, so we only care about n_features in X.

**Parameters**

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data, where n_samples in the number of samples and n_features is the number of features.

**Returns**

self [object] Returns the transformer.

**fit_transform** (X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

**Returns**

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** (deep=True)

Get parameters for this estimator.

**Parameters**

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**set_params** (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform** (X)

Generate the feature map approximation for X.

**Parameters**

X [{array-like}, shape (n_samples, n_features)] New data, where n_samples in the number of samples and n_features is the number of features.

**Returns**
X_new [array-like, shape (n_samples, n_components)]

Examples using sklearn.kernel_approximation.PolynomialCountSketch

- Release Highlights for scikit-learn 0.24
- Scalable learning with polynomial kernel approximation

7.20.4 sklearn.kernel_approximation.RBFSampler

class sklearn.kernel_approximation.RBFSampler(*, gamma=1.0, n_components=100, random_state=None)

Approximates feature map of an RBF kernel by Monte Carlo approximation of its Fourier transform. It implements a variant of Random Kitchen Sinks.[1]

Read more in the User Guide.

Parameters

gamma [float, default=1.0] Parameter of RBF kernel: \(\exp(-\gamma x^2)\)

n_components [int, default=100] Number of Monte Carlo samples per original feature. Equals the dimensionality of the computed feature space.

random_state [int, RandomState instance or None, default=None] Pseudo-random number generator to control the generation of the random weights and random offset when fitting the training data. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

random_offset_ [ndarray of shape (n_components,), dtype=float64] Random offset used to compute the projection in the n_components dimensions of the feature space.

random_weights_ [ndarray of shape (n_features, n_components), dtype=float64] Random projection directions drawn from the Fourier transform of the RBF kernel.

Notes

See “Random Features for Large-Scale Kernel Machines” by A. Rahimi and Benjamin Recht.


Examples

```python
>>> from sklearn.kernel_approximation import RBFSampler
>>> from sklearn.linear_model import SGDClassifier
>>> X = [[0, 0], [1, 1], [1, 0], [0, 1]]
>>> y = [0, 0, 1, 1]
>>> rbf_feature = RBFSampler(gamma=1, random_state=1)
>>> X_features = rbf_feature.fit_transform(X)
>>> clf = SGDClassifier(max_iter=5, tol=1e-3)
>>> clf.fit(X_features, y)
SGDClassifier(max_iter=5)
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</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Apply the approximate feature map to X.</td>
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</table>

```python
>>> clf.score(X_features, y)
1.0
```

**fit** *(X, y=None)*
Fit the model with X.

Samples random projection according to n_features.

**Parameters**

- **X** [[array-like, sparse matrix], shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

**Returns**

- **self** [object] Returns the transformer.

**fit_transform** *(X, y=None, **fit_params)*
Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

****fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**set_params** (**params**)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform(X)

Apply the approximate feature map to X.

Parameters

X  [[array-like, sparse matrix], shape (n_samples, n_features)] New data, where n_samples in the number of samples and n_features is the number of features.

Returns

X_new  [array-like, shape (n_samples, n_components)]

Examples using sklearn.kernel_approximation.RBFSampler

- Explicit feature map approximation for RBF kernels

7.20.5 sklearn.kernel_approximation.SkewedChi2Sampler

class sklearn.kernel_approximation.SkewedChi2Sampler(*, skewedness=1.0, n_components=100, random_state=None)

Approximates feature map of the “skewed chi-squared” kernel by Monte Carlo approximation of its Fourier transform.

Read more in the User Guide.

Parameters

skewedness  [float, default=1.0] “skewedness” parameter of the kernel. Needs to be cross-validated.

n_components  [int, default=100] number of Monte Carlo samples per original feature. Equals the dimensionality of the computed feature space.

random_state  [int, RandomState instance or None, default=None] Pseudo-random number generator to control the generation of the random weights and random offset when fitting the training data. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

random_weights_  [ndarray of shape (n_features, n_components)] Weight array, sampled from a secant hyperbolic distribution, which will be used to linearly transform the log of the data.

random_offset_  [ndarray of shape (n_features, n_components)] Bias term, which will be added to the data. It is uniformly distributed between 0 and 2*pi.

See also:
**AdditiveChi2Sampler** A different approach for approximating an additive variant of the chi squared kernel.

**sklearn.metrics.pairwise.chi2_kernel** The exact chi squared kernel.

**References**

See “Random Fourier Approximations for Skewed Multiplicative Histogram Kernels” by Fuxin Li, Catalin Ionescu and Cristian Sminchisescu.

**Examples**

```python
>>> from sklearn.kernel_approximation import SkewedChi2Sampler
>>> from sklearn.linear_model import SGDClassifier

>>> X = [[0, 0], [1, 1], [1, 0], [0, 1]]
>>> y = [0, 0, 1, 1]

>>> chi2_feature = SkewedChi2Sampler(skewedness=.01,
...                                   n_components=10,
...                                   random_state=0)

>>> X_features = chi2_feature.fit_transform(X, y)
>>> clf = SGDClassifier(max_iter=10, tol=1e-3)
>>> clf.fit(X_features, y)
SGDClassifier(max_iter=10)
>>> clf.score(X_features, y)
1.0
```

**Methods**

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<td><code>fit_transform(X[, y])</code></td>
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<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<td><code>set_params(**params)</code></td>
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</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Apply the approximate feature map to X.</td>
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**fit** *(X, y=None)*

Fit the model with X.

Samples random projection according to `n_features`.

**Parameters**

- `X` [array-like, shape (n_samples, n_features)] Training data, where n_samples in the number of samples and n_features is the number of features.

**Returns**

- `self` [object] Returns the transformer.

**fit_transform** *(X, y=None, **fit_params)*

Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**
X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Apply the approximate feature map to X.

Parameters

X [array-like, shape (n_samples, n_features)] New data, where n_samples in the number of samples and n_features is the number of features. All values of X must be strictly greater than “-skewedness”.

Returns

X_new [array-like, shape (n_samples, n_components)]

7.21 sklearn.kernel_ridge: Kernel Ridge Regression

Module sklearn.kernel_ridge implements kernel ridge regression.

User guide: See the Kernel ridge regression section for further details.

```
kernel_ridge.KernelRidge([alpha,    kernel,    Kernel ridge regression.
   ...])
```

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7.21.1 sklearn.kernel_ridge.KernelRidge

class sklearn.kernel_ridge.KernelRidge(alpha=1.0, *, kernel='linear', gamma=None, degree=3, coef0=1, kernel_params=None)

Kernel ridge regression.

Kernel ridge regression (KRR) combines ridge regression (linear least squares with l2-norm regularization) with the kernel trick. It thus learns a linear function in the space induced by the respective kernel and the data. For non-linear kernels, this corresponds to a non-linear function in the original space.

The form of the model learned by KRR is identical to support vector regression (SVR). However, different loss functions are used: KRR uses squared error loss while support vector regression uses epsilon-insensitive loss, both combined with l2 regularization. In contrast to SVR, fitting a KRR model can be done in closed-form and is typically faster for medium-sized datasets. On the other hand, the learned model is non-sparse and thus slower than SVR, which learns a sparse model for epsilon > 0, at prediction-time.

This estimator has built-in support for multi-variate regression (i.e., when y is a 2d-array of shape [n_samples, n_targets]).

Read more in the User Guide.

Parameters

- alpha [float or array-like of shape (n_targets,), default=1.0] Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to 1 / (2C) in other linear models such as LogisticRegression or LinearSVC. If an array is passed, penalties are assumed to be specific to the targets. Hence they must correspond in number. See Ridge regression and classification for formula.

- kernel [string or callable, default="linear"] Kernel mapping used internally. This parameter is directly passed to pairwise_kernel. If kernel is a string, it must be one of the metrics in pairwise.PAIRWISE_KERNEL_FUNCTIONS. If kernel is "precomputed", X is assumed to be a kernel matrix. Alternatively, if kernel is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two rows from X as input and return the corresponding kernel value as a single number. This means that callables from sklearn.metrics.pairwise are not allowed, as they operate on matrices, not single samples. Use the string identifying the kernel instead.

- gamma [float, default=None] Gamma parameter for the RBF, laplacian, polynomial, exponential chi2 and sigmoid kernels. Interpretation of the default value is left to the kernel; see the documentation for sklearn.metrics.pairwise. Ignored by other kernels.

- degree [float, default=3] Degree of the polynomial kernel. Ignored by other kernels.

- coef0 [float, default=1] Zero coefficient for polynomial and sigmoid kernels. Ignored by other kernels.

- kernel_params [mapping of string to any, default=None] Additional parameters (keyword arguments) for kernel function passed as callable object.

Attributes

- dual_coef_ [ndarray of shape (n_samples,) or (n_samples, n_targets)] Representation of weight vector(s) in kernel space

- X_fit_ [ndarray, sparse matrix] of shape (n_samples, n_features)] Training data, which is also required for prediction. If kernel == "precomputed" this is instead the precomputed training matrix, of shape (n_samples, n_samples).

See also:
sklearn.linear_model.Ridge  Linear ridge regression.

sklearn.svm.SVR  Support Vector Regression implemented using libsvm.

References


Examples

```python
>>> from sklearn.kernel_ridge import KernelRidge
>>> import numpy as np

>>> n_samples, n_features = 10, 5
>>> rng = np.random.RandomState(0)
>>> y = rng.randn(n_samples)
>>> X = rng.randn(n_samples, n_features)
>>> clf = KernelRidge(alpha=1.0)
>>> clf.fit(X, y)
KernelRidge(alpha=1.0)
```

Methods

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<td>fit(X, y[, sample_weight])</td>
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<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<td>predict(X)</td>
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</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

```python
fit (X, y, sample_weight=None)
Fit Kernel Ridge regression model

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] Training data. If kernel == “precomputed” this is instead a precomputed kernel matrix, of shape (n_samples, n_samples).

y  [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values

sample_weight  [float or array-like of shape (n_samples,), default=None] Individual weights for each sample, ignored if None is passed.

Returns

self  [returns an instance of self.]
```

```python
get_params (deep=True)
Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
```
Returns

**params** [dict] Parameter names mapped to their values.

**predict** *(X)*
Predict using the kernel ridge model

**Parameters**

**X** [(array-like, sparse matrix) of shape (n_samples, n_features)] Samples. If kernel == “precomputed” this is instead a precomputed kernel matrix, shape = [n_samples, n_samples_fitted], where n_samples_fitted is the number of samples used in the fitting for this estimator.

**Returns**

**C** [ndarray of shape (n_samples,) or (n_samples, n_targets)] Returns predicted values.

**score** *(X, y, sample_weight=None)*
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) \times 2 \times sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) \times 2 \times sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] $R^2$ of self.predict(X) wrt $y$.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

**self** [estimator instance] Estimator instance.
Examples using `sklearn.kernel_ridge.KernelRidge`

- Comparison of kernel ridge and Gaussian process regression
- Comparison of kernel ridge regression and SVR

7.22 `sklearn.linear_model`: Linear Models

The `sklearn.linear_model` module implements a variety of linear models.

User guide: See the Linear Models section for further details.

The following subsections are only rough guidelines: the same estimator can fall into multiple categories, depending on its parameters.

7.22.1 Linear classifiers

```python
linear_model.LogisticRegression([penalty, ...])
```

Logistic Regression (aka logit, MaxEnt) classifier.

```python
linear_model.LogisticRegressionCV([Cs, ...])
```

Logistic Regression CV (aka logit, MaxEnt) classifier.

```python
linear_model.PassiveAggressiveClassifier()
```

Passive Aggressive Classifier

```python
linear_model.Perceptron([penalty, alpha, ...])
```

Read more in the User Guide.

```python
linear_model.RidgeClassifier([alpha, ...])
```

Classifier using Ridge regression.

```python
linear_model.RidgeClassifierCV([alphas, ...])
```

Ridge classifier with built-in cross-validation.

```python
linear_model.SGDClassifier([loss, penalty, ...])
```

Linear classifiers (SVM, logistic regression, etc.) with SGD training.

**sklearn.linear_model.LogisticRegression**

```python
class sklearn.linear_model.LogisticRegression(penalty='l2', *, dual=False, tol=0.0001, C=1.0, fit_intercept=True, intercept_scaling=1, class_weight=None, random_state=None, solver='lbfgs', max_iter=100, multi_class='auto', verbose=0, warm_start=False, n_jobs=None, l1_ratio=None)
```

Logistic Regression (aka logit, MaxEnt) classifier.

In the multiclass case, the training algorithm uses the one-vs-rest (OvR) scheme if the ‘multi_class’ option is set to ‘ovr’, and uses the cross-entropy loss if the ‘multi_class’ option is set to ‘multinomial’. (Currently the ‘multinomial’ option is supported only by the ‘lbfgs’, ‘sag’ and ‘newton-cg’ solvers.)

This class implements regularized logistic regression using the ‘liblinear’ library, ‘newton-cg’, ‘sag’, ‘saga’ and ‘lbfgs’ solvers. **Note that regularization is applied by default.** It can handle both dense and sparse input. Use C-ordered arrays or CSR matrices containing 64-bit floats for optimal performance; any other input format will be converted (and copied).

The ‘newton-cg’, ‘sag’, and ‘lbfgs’ solvers support only L2 regularization with primal formulation, or no regularization. The ‘liblinear’ solver supports both L1 and L2 regularization, with a dual formulation only for the
L2 penalty. The Elastic-Net regularization is only supported by the ‘saga’ solver.

Read more in the User Guide.

Parameters

- **penalty** [{'l1', 'l2', 'elasticnet', 'none'}, default='l2'] Used to specify the norm used in the penalization. The ‘newton-cg’, ‘sag’ and ‘lbfgs’ solvers support only l2 penalties. ‘elasticnet’ is only supported by the ‘saga’ solver. If ‘none’ (not supported by the liblinear solver), no regularization is applied.

  New in version 0.19: l1 penalty with SAGA solver (allowing ‘multinomial’ + L1)

- **dual** [bool, default=False] Dual or primal formulation. Dual formulation is only implemented for l2 penalty with liblinear solver. Prefer dual=False when n_samples > n_features.

- **tol** [float, default=1e-4] Tolerance for stopping criteria.

- **C** [float, default=1.0] Inverse of regularization strength; must be a positive float. Like in support vector machines, smaller values specify stronger regularization.

- **fit_intercept** [bool, default=True] Specifies if a constant (a.k.a. bias or intercept) should be added to the decision function.

- **intercept_scaling** [float, default=1] Useful only when the solver ‘liblinear’ is used and self.fit_intercept is set to True. In this case, x becomes [x, self.intercept_scaling], i.e. a “synthetic” feature with constant value equal to intercept_scaling is appended to the instance vector. The intercept becomes \(\text{intercept} = \text{intercept scaling} \times \text{synthetic feature weight}\).

  Note! the synthetic feature weight is subject to l1/l2 regularization as all other features. To lessen the effect of regularization on synthetic feature weight (and therefore on the intercept) intercept_scaling has to be increased.

- **class_weight** [dict or ‘balanced’, default=None] Weights associated with classes in the form {class_label: weight}. If not given, all classes are supposed to have weight one.

  The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as \(\text{n_samples} / (\text{n_classes} \times \text{np.bincount(y)})\).

  Note that these weights will be multiplied with sample_weight (passed through the fit method) if sample_weight is specified.

  New in version 0.17: class_weight=’balanced’

- **random_state** [int, RandomState instance, default=None] Used when solver == ‘sag’, ‘saga’ or ‘liblinear’ to shuffle the data. See Glossary for details.


  • For small datasets, ‘liblinear’ is a good choice, whereas ‘sag’ and ‘saga’ are faster for large ones.

  • For multiclass problems, only ‘newton-cg’, ‘sag’, ‘saga’ and ‘lbfgs’ handle multinomial loss; ‘liblinear’ is limited to one-versus-rest schemes.

  • ‘newton-cg’, ‘lbfgs’, ‘sag’ and ‘saga’ handle L2 or no penalty

  • ‘liblinear’ and ‘saga’ also handle L1 penalty

  • ‘saga’ also supports ‘elasticnet’ penalty

  • ‘liblinear’ does not support setting penalty='none'
Note that ‘sag’ and ‘saga’ fast convergence is only guaranteed on features with approximately the same scale. You can preprocess the data with a scaler from sklearn.preprocessing.

New in version 0.17: Stochastic Average Gradient descent solver.

New in version 0.19: SAGA solver.

Changed in version 0.22: The default solver changed from ‘liblinear’ to ‘lbfgs’ in 0.22.

max_iter [int, default=100] Maximum number of iterations taken for the solvers to converge.

multi_class [‘auto’, ‘ovr’, ‘multinomial’], default=’auto’ If the option chosen is ‘ovr’, then a binary problem is fit for each label. For ‘multinomial’ the loss minimised is the multinomial loss fit across the entire probability distribution, even when the data is binary. ‘multinomial’ is unavailable when solver=’liblinear’. ‘auto’ selects ‘ovr’ if the data is binary, or if solver=’liblinear’, and otherwise selects ‘multinomial’.

New in version 0.18: Stochastic Average Gradient descent solver for ‘multinomial’ case.

Changed in version 0.22: Default changed from ‘ovr’ to ‘auto’ in 0.22.

verbose [int, default=0] For the liblinear and lbfgs solvers set verbose to any positive number for verbosity.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. Useless for liblinear solver. See the Glossary.

New in version 0.17: warm_start to support lbfgs, newton-cg, sag, saga solvers.

n_jobs [int, default=None] Number of CPU cores used when parallelizing over classes if multi_class='ovr'. This parameter is ignored when the solver is set to ‘liblinear’ regardless of whether ‘multi_class’ is specified or not. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

l1_ratio [float, default=None] The Elastic-Net mixing parameter, with 0 <= l1_ratio <= 1. Only used if penalty=’elasticnet’. Setting l1_ratio=0 is equivalent to using penalty=’l2’, while setting l1_ratio=1 is equivalent to using penalty=’l1’. For 0 < l1_ratio <1, the penalty is a combination of L1 and L2.

Attributes

classes_ [ndarray of shape (n_classes, )] A list of class labels known to the classifier.

coef_ [ndarray of shape (1, n_features) or (n_classes, n_features)] Coefficient of the features in the decision function.

coef_ is of shape (1, n_features) when the given problem is binary. In particular, when multi_class='multinomial', coef_ corresponds to outcome 1 (True) and -coef_ corresponds to outcome 0 (False).

intercept_ [ndarray of shape (1,) or (n_classes,)] Intercept (a.k.a. bias) added to the decision function.

If fit_intercept is set to False, the intercept is set to zero. intercept_ is of shape (1,) when the given problem is binary. In particular, when multi_class='multinomial', intercept_ corresponds to outcome 1 (True) and -intercept_ corresponds to outcome 0 (False).

n_iter_ [ndarray of shape (n_classes,) or (1,)] Actual number of iterations for all classes. If binary or multinomial, it returns only 1 element. For liblinear solver, only the maximum number of iteration across all classes is given.
**Notes**

The underlying C implementation uses a random number generator to select features when fitting the model. It is thus not uncommon, to have slightly different results for the same input data. If that happens, try with a smaller tol parameter.

Predict output may not match that of standalone liblinear in certain cases. See *differences from liblinear* in the narrative documentation.

**References**


**LIBLINEAR – A Library for Large Linear Classification**  https://www.csie.ntu.edu.tw/~cjlin/liblinear/

**SAG – Mark Schmidt, Nicolas Le Roux, and Francis Bach**  Minimizing Finite Sums with the Stochastic Average Gradient https://hal.inria.fr/hal-00860051/document


**Examples**

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.linear_model import LogisticRegression
>>> X, y = load_iris(return_X_y=True)
>>> clf = LogisticRegression(random_state=0).fit(X, y)
>>> clf.predict(X[:2, :])
array([0, 0])
>>> clf.predict_proba(X[:2, :])
array([[0.98...e-01, 1.8...e-02, 1.4...e-08],
       [0.97...e-01, 2.8...e-02, ...e-08]])
>>> clf.score(X, y)
0.97...
```
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<td>Predict confidence scores for samples.</td>
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<tr>
<td><code>densify()</code></td>
<td>Convert coefficient matrix to dense array format.</td>
</tr>
<tr>
<td><code>fit(X, y[, sample_weight])</code></td>
<td>Fit the model according to the given training data.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict class labels for samples in X.</td>
</tr>
<tr>
<td><code>predict_log_proba(X)</code></td>
<td>Predict logarithm of probability estimates.</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Probability estimates.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>sparsify()</code></td>
<td>Convert coefficient matrix to sparse format.</td>
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**decision_function (X)**

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **array, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes)** Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

**densify()**

Convert coefficient matrix to dense array format.

Converts the `coef_` member (back) to a numpy.ndarray. This is the default format of `coef_` and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

**Returns**

- **self** Fitted estimator.

**fit (X, y, sample_weight=None)**

Fit the model according to the given training data.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)] Target vector relative to X.
- **sample_weight** [array-like of shape (n_samples,) default=None] Array of weights that are assigned to individual samples. If not provided, then each sample is given unit weight.

New in version 0.17: `sample_weight` support to LogisticRegression.

**Returns**

- **self** Fitted estimator.
Notes

The SAGA solver supports both float64 and float32 bit arrays.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Predict class labels for samples in X.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape [n_samples]] Predicted class label per sample.

predict_log_proba (X)
Predict logarithm of probability estimates.

The returned estimates for all classes are ordered by the label of classes.

Parameters

X [array-like of shape (n_samples, n_features)] Vector to be scored, where n_samples is
the number of samples and n_features is the number of features.

Returns

T [array-like of shape (n_samples, n_classes)] Returns the log-probability of the sample for
each class in the model, where classes are ordered as they are in self.classes_.

predict_proba (X)
Probability estimates.

The returned estimates for all classes are ordered by the label of classes.

For a multi_class problem, if multi_class is set to be “multinomial” the softmax function is used to find
the predicted probability of each class. Else use a one-vs-rest approach, i.e calculate the probability of
each class assuming it to be positive using the logistic function, and normalize these values across all the
classes.

Parameters

X [array-like of shape (n_samples, n_features)] Vector to be scored, where n_samples is
the number of samples and n_features is the number of features.

Returns

T [array-like of shape (n_samples, n_classes)] Returns the probability of the sample for each
class in the model, where classes are ordered as they are in self.classes_.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,,), default=None] Sample weights.

**Returns**

- **score** [float] Mean accuracy of self.predict(X) wrt. y.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- ****params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**sparsify** ()

Convert coefficient matrix to sparse format.

Converts the coef_ member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The intercept_ member is not converted.

**Returns**

- **self** Fitted estimator.

**Notes**

For non-sparse models, i.e. when there are not many zeros in coef_, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with (coef_ == 0).sum(), must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the partial_fit method (if any) will not work until you call densify.

**Examples using sklearn.linear_model.LogisticRegression**

- Release Highlights for scikit-learn 0.23
- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22
- Comparison of Calibration of Classifiers
- Probability Calibration curves
- Plot classification probability
Logit Regression CV (aka logit, MaxEnt) classifier.

See glossary entry for cross-validation estimator.

This class implements logistic regression using liblinear, newton-cg, sag of lbfgs optimizer. The newton-cg, sag and lbfgs solvers support only L2 regularization with primal formulation. The liblinear solver supports both L1 and L2 regularization, with a dual formulation only for the L2 penalty. Elastic-Net penalty is only supported by the saga solver.

For the grid of Cs values and l1_ratios values, the best hyperparameter is selected by the cross-validator StratifiedKFold, but it can be changed using the cv parameter. The ‘newton-cg’, ‘sag’, ‘saga’ and ‘lbfgs’ solvers can warm-start the coefficients (see Glossary).

Read more in the User Guide.

Parameters
Cs [int or list of floats, default=10] Each of the values in Cs describes the inverse of regularization strength. If Cs is as an int, then a grid of Cs values are chosen in a logarithmic scale between 1e-4 and 1e4. Like in support vector machines, smaller values specify stronger regularization.

fit_intercept [bool, default=True] Specifies if a constant (a.k.a. bias or intercept) should be added to the decision function.

cv [int or cross-validation generator, default=None] The default cross-validation generator used is Stratified K-Folds. If an integer is provided, then it is the number of folds used. See the module sklearn.model_selection module for the list of possible cross-validation objects.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

dual [bool, default=False] Dual or primal formulation. Dual formulation is only implemented for l2 penalty with liblinear solver. Prefer dual=False when n_samples > n_features.

penalty [{'l1', 'l2', 'elasticnet'}, default='l2'] Used to specify the norm used in the penalization. The ‘newton-cg’, ‘sag’ and ‘lbfgs’ solvers support only l2 penalties. ‘elasticnet’ is only supported by the ‘saga’ solver.

scoring [str or callable, default=None] A string (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y). For a list of scoring functions that can be used, look at sklearn.metrics. The default scoring option used is ‘accuracy’.

solver [{'newton-cg', 'lbfgs', 'liblinear', 'sag', 'saga'}, default='lbfgs'] Algorithm to use in the optimization problem.

• For small datasets, ‘liblinear’ is a good choice, whereas ‘sag’ and ‘saga’ are faster for large ones.

• For multiclass problems, only ‘newton-cg’, ‘sag’, ‘saga’ and ‘lbfgs’ handle multinomial loss; ‘liblinear’ is limited to one-versus-rest schemes.

• ‘newton-cg’, ‘lbfgs’ and ‘sag’ only handle L2 penalty, whereas ‘liblinear’ and ‘saga’ handle L1 penalty.

• ‘liblinear’ might be slower in LogisticRegressionCV because it does not handle warm-starting.

Note that ‘sag’ and ‘saga’ fast convergence is only guaranteed on features with approximately the same scale. You can preprocess the data with a scaler from sklearn.preprocessing.

New in version 0.17: Stochastic Average Gradient descent solver.

New in version 0.19: SAGA solver.

tol [float, default=1e-4] Tolerance for stopping criteria.

max_iter [int, default=100] Maximum number of iterations of the optimization algorithm.

class_weight [dict or ‘balanced’, default=None] Weights associated with classes in the form {class_label: weight}. If not given, all classes are supposed to have weight one.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as n_samples / (n_classes * np.bincount(y)).

Note that these weights will be multiplied with sample_weight (passed through the fit method) if sample_weight is specified.

New in version 0.17: class_weight == ‘balanced’
**n_jobs** [int, default=None] Number of CPU cores used during the cross-validation loop. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**verbose** [int, default=0] For the ‘liblinear’, ‘sag’ and ‘lbfgs’ solvers set verbose to any positive number for verbosity.

**refit** [bool, default=True] If set to True, the scores are averaged across all folds, and the coefs and the C that corresponds to the best score is taken, and a final refit is done using these parameters. Otherwise the coefs, intercepts and C that correspond to the best scores across folds are averaged.

**intercept_scaling** [float, default=1] Useful only when the solver ‘liblinear’ is used and self.fit_intercept is set to True. In this case, x becomes [x, self.intercept_scaling], i.e. a “synthetic” feature with constant value equal to intercept_scaling is appended to the instance vector. The intercept becomes intercept_scaling * synthetic_feature_weight.

Note! the synthetic feature weight is subject to l1/l2 regularization as all other features. To lessen the effect of regularization on synthetic feature weight (and therefore on the intercept) intercept_scaling has to be increased.

**multi_class** [‘auto, ‘ovr’, ‘multinomial’], default=’auto’] If the option chosen is ‘ovr’, then a binary problem is fit for each label. For ‘multinomial’ the loss minimised is the multinomial loss fit across the entire probability distribution, even when the data is binary. ‘multinomial’ is unavailable when solver=’liblinear’. ‘auto’ selects ‘ovr’ if the data is binary, or if solver=’liblinear’, and otherwise selects ‘multinomial’.

New in version 0.18: Stochastic Average Gradient descent solver for ‘multinomial’ case.

Changed in version 0.22: Default changed from ‘ovr’ to ‘auto’ in 0.22.

**random_state** [int, RandomState instance, default=None] Used when solver='sag', ‘saga’ or ‘liblinear’ to shuffle the data. Note that this only applies to the solver and not the cross-validation generator. See Glossary for details.

**l1_ratios** [list of float, default=None] The list of Elastic-Net mixing parameter, with $0 \leq l1\_ratio \leq 1$. Only used if penalty='elasticnet'. A value of 0 is equivalent to using penalty='l2', while 1 is equivalent to using penalty='l1'. For $0 < l1\_ratio <1$, the penalty is a combination of L1 and L2.

**Attributes**

**classes_** [ndarray of shape (n_classes,)] A list of class labels known to the classifier.

**coef_** [ndarray of shape (1, n_features) or (n_classes, n_features)] Coefficient of the features in the decision function.

**intercept_** [ndarray of shape (1,) or (n_classes,)] Intercept (a.k.a. bias) added to the decision function.

If fit_intercept is set to False, the intercept is set to zero. intercept_ is of shape(1,) when the problem is binary.

**Cs_** [ndarray of shape (n_cs)] Array of C i.e. inverse of regularization parameter values used for cross-validation.

**l1_ratios_** [ndarray of shape (n_l1_ratios)] Array of l1_ratios used for cross-validation. If no l1_ratio is used (i.e. penalty is not ‘elasticnet’), this is set to [None]
coefs_paths_[ndarray of shape (n_folds, n_cs, n_features) or (n_folds, n_cs, n_features + 1)] dict with classes as the keys, and the path of coefficients obtained during cross-validating across each fold and then across each Cs after doing an OvR for the corresponding class as values. If the ‘multi_class’ option is set to ‘multinomial’, then the coefs_paths are the coefficients corresponding to each class. Each dict value has shape (n_folds, n_cs, n_features) or (n_folds, n_cs, n_features + 1) depending on whether the intercept is fit or not. If penalty='elasticnet', the shape is (n_folds, n_cs, n_l1_ratios_, n_features) or (n_folds, n_cs, n_l1_ratios_, n_features + 1).

scores_[dict] dict with classes as the keys, and the values as the grid of scores obtained during cross-validating each fold, after doing an OvR for the corresponding class. If the ‘multi_class’ option given is ‘multinomial’ then the same scores are repeated across all classes, since this is the multinomial class. Each dict value has shape (n_folds, n_cs or (n_folds, n_cs, n_l1_ratios) if penalty='elasticnet'.

C_[ndarray of shape (n_classes,) or (n_classes - 1,)] Array of C that maps to the best scores across every class. If refit is set to False, then for each class, the best C is the average of the C’s that correspond to the best scores for each fold. C_ is of shape(n_classes,) when the problem is binary.

l1_ratio_[ndarray of shape (n_classes,) or (n_classes - 1,)] Array of l1_ratio that maps to the best scores across every class. If refit is set to False, then for each class, the best l1_ratio is the average of the l1_ratio’s that correspond to the best scores for each fold. l1_ratio_ is of shape(n_classes,) when the problem is binary.

n_iter_[ndarray of shape (n_classes, n_folds, n_cs) or (1, n_folds, n_cs)] Actual number of iterations for all classes, folds and Cs. In the binary or multinomial cases, the first dimension is equal to 1. If penalty='elasticnet', the shape is (n_classes, n_folds, n_cs, n_l1_ratios) or (1, n_folds, n_cs, n_l1_ratios).

See also:

LogisticRegression

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.linear_model import LogisticRegressionCV
>>> X, y = load_iris(return_X_y=True)
>>> clf = LogisticRegressionCV(cv=5, random_state=0).fit(X, y)
>>> clf.predict(X[:2, :])
array([0, 0])
>>> clf.predict_proba(X[:2, :]).shape
(2, 3)
>>> clf.score(X, y)
0.98...
```
Methods

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<td>sparsify()</td>
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**decision_function**(*X*)

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- array, shape=(n_samples,) if `n_classes` == 2 else (n_samples, n_classes) Confidence scores per (sample, class) combination. In the binary case, confidence score for `self.classes_[1]` where >0 means this class would be predicted.

**densify()**

Convert coefficient matrix to dense array format.

Converts the `coef_` member (back) to a numpy.ndarray. This is the default format of `coef_` and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

**Returns**

- self Fitted estimator.

**fit**(*X*, *y*, *sample_weight*=None)

Fit the model according to the given training data.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) Training vector, where n_samples is the number of samples and n_features is the number of features.

- **y** [array-like of shape (n_samples,)] Target vector relative to X.

- **sample_weight** [array-like of shape (n_samples,) default=None] Array of weights that are assigned to individual samples. If not provided, then each sample is given unit weight.

**Returns**

- self [object]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict** *(X)*

Predict class labels for samples in X.

Parameters

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

- **C** [array, shape [n_samples]] Predicted class label per sample.

**predict_log_proba** *(X)*

Predict logarithm of probability estimates.

The returned estimates for all classes are ordered by the label of classes.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Vector to be scored, where `n_samples` is the number of samples and `n_features` is the number of features.

Returns

- **T** [array-like of shape (n_samples, n_classes)] Returns the log-probability of the sample for each class in the model, where classes are ordered as they are in `self.classes_`.

**predict_proba** *(X)*

Probability estimates.

The returned estimates for all classes are ordered by the label of classes.

For a multi_class problem, if multi_class is set to be “multinomial” the softmax function is used to find the predicted probability of each class. Else use a one-vs-rest approach, i.e calculate the probability of each class assuming it to be positive using the logistic function, and normalize these values across all the classes.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Vector to be scored, where `n_samples` is the number of samples and `n_features` is the number of features.

Returns

- **T** [array-like of shape (n_samples, n_classes)] Returns the probability of the sample for each class in the model, where classes are ordered as they are in `self.classes_`.

**score** *(X, y, sample_weight=None)*

Returns the score using the `scoring` option on the given test data and labels.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **score** [float] Score of `self.predict(X)` wrt. y.
set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

sparsify()

Convert coefficient matrix to sparse format.

Converts the `coef_` member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The `intercept_` member is not converted.

Returns

self Fitted estimator.

Notes

For non-sparse models, i.e. when there are not many zeros in `coef_`, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with `(coef_ == 0).sum()`, must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the partial_fit method (if any) will not work until you call densify.

sklearn.linear_model.PassiveAggressiveClassifier

class sklearn.linear_model.PassiveAggressiveClassifier(*,

```
C=1.0,
fit_intercept=True,
max_iter=1000, tol=0.001,
early_stopping=False,
validation_fraction=0.1,
n_iter_no_change=5,
shuffle=True, verbose=0,
loss='hinge', n_jobs=None,
random_state=None,
warm_start=False,
class_weight=None, average=False)
```

Passive Aggressive Classifier

Read more in the User Guide.

Parameters

** C [float, default=1.0] Maximum step size (regularization). Defaults to 1.0.

fit_intercept [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered.
**max_iter** [int, default=1000] The maximum number of passes over the training data (aka epochs). It only impacts the behavior in the `fit` method, and not the `partial_fit` method.

New in version 0.19.

**tol** [float or None, default=1e-3] The stopping criterion. If it is not None, the iterations will stop when \( \text{loss} > \text{previous_loss} - \text{tol} \).

New in version 0.19.

**early_stopping** [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to True, it will automatically set aside a stratified fraction of training data as validation and terminate training when validation score is not improving by at least tol for n_iter_no_change consecutive epochs.

New in version 0.20.

**validation_fraction** [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True.

New in version 0.20.

**n_iter_no_change** [int, default=5] Number of iterations with no improvement to wait before early stopping.

New in version 0.20.

**shuffle** [bool, default=True] Whether or not the training data should be shuffled after each epoch.

**verbose** [integer, default=0] The verbosity level

**loss** [string, default="hinge"] The loss function to be used: hinge: equivalent to PA-I in the reference paper. squared_hinge: equivalent to PA-II in the reference paper.

**n_jobs** [int or None, default=None] The number of CPUs to use to do the OVA (One Versus All, for multi-class problems) computation. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance, default=None] Used to shuffle the training data, when shuffle is set to True. Pass an int for reproducible output across multiple function calls. See Glossary.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

Repeatedly calling fit or partial_fit when warm_start is True can result in a different solution than when calling fit a single time because of the way the data is shuffled.

**class_weight** [dict, {class_label: weight} or “balanced” or None, default=None] Preset for the class_weight fit parameter.

Weights associated with classes. If not given, all classes are supposed to have weight one.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as \( \frac{\text{n_samples}}{\text{n_classes} \times \text{np.bincount(y)}} \)

New in version 0.17: parameter class_weight to automatically weight samples.

**average** [bool or int, default=False] When set to True, computes the averaged SGD weights and stores the result in the `coef_` attribute. If set to an int greater than 1, averaging will begin
once the total number of samples seen reaches average. So average=10 will begin averaging after seeing 10 samples.

New in version 0.19: parameter *average* to use weights averaging in SGD

**Attributes**

- **coef_** [array, shape = [1, n_features] if n_classes == 2 else [n_classes, n_features]] Weights assigned to the features.
- **intercept_** [array, shape = [1] if n_classes == 2 else [n_classes]] Constants in decision function.
- **n_iter_** [int] The actual number of iterations to reach the stopping criterion. For multiclass fits, it is the maximum over every binary fit.
- **classes_** [array of shape (n_classes,)] The unique classes labels.
- **t_** [int] Number of weight updates performed during training. Same as \((n\_iter_ * n\_samples)\).
- **loss_function_** [callable] Loss function used by the algorithm.

See also:

- *SGDClassifier*
- *Perceptron*

**References**


**Examples**

```python
>>> from sklearn.linear_model import PassiveAggressiveClassifier
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_features=4, random_state=0)
>>> clf = PassiveAggressiveClassifier(max_iter=1000, random_state=0, ...
... tol=1e-3)
>>> clf.fit(X, y)
PassiveAggressiveClassifier(random_state=0)
>>> print(clf.coef_)
[[0.26642044 0.45070924 0.67251877 0.64185414]]
>>> print(clf.intercept_)
[1.84127814]
>>> print(clf.predict([[0, 0, 0, 0]]))
[1]
```
**Methods**

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<td>Predict confidence scores for samples.</td>
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<tr>
<td><code>densify()</code></td>
<td>Convert coefficient matrix to dense array format.</td>
</tr>
<tr>
<td><code>fit(X, y[, coef_init, intercept_init])</code></td>
<td>Fit linear model with Passive Aggressive algorithm.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>partial_fit(X, y[, classes])</code></td>
<td>Fit linear model with Passive Aggressive algorithm.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict class labels for samples in X.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
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<td><code>set_params(**kwargs)</code></td>
<td>Set and validate the parameters of estimator.</td>
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<tr>
<td><code>sparsify()</code></td>
<td>Convert coefficient matrix to sparse format.</td>
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`decision_function (X)`
Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **array**, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes) Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

`densify()`
Convert coefficient matrix to dense array format.

Converting the `coef_` member (back) to a numpy.ndarray. This is the default format of `coef_` and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

**Returns**

- **self** Fitted estimator.

`fit (X, y, coef_init=None, intercept_init=None)`
Fit linear model with Passive Aggressive algorithm.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data
- **y** [numpy array of shape [n_samples]] Target values
- **coef_init** [array, shape = [n_classes, n_features]] The initial coefficients to warm-start the optimization.
- **intercept_init** [array, shape = [n_classes]] The initial intercept to warm-start the optimization.

**Returns**

- **self** [returns an instance of self.]
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**partial_fit** *(X, y, classes=None)*
Fit linear model with Passive Aggressive algorithm.

**Parameters**

- **X** [{array-like, sparse matrix] of shape (n_samples, n_features)] Subset of the training data
- **y** [numpy array of shape [n_samples]] Subset of the target values
- **classes** [array, shape = [n_classes]] Classes across all calls to partial_fit. Can be obtained by via `np.unique(y_all)`, where `y_all` is the target vector of the entire dataset. This argument is required for the first call to partial_fit and can be omitted in the subsequent calls. Note that `y` doesn’t need to contain all labels in classes.

**Returns**

**self** [returns an instance of self.]

**predict** *(X)*
Predict class labels for samples in X.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

**C** [array, shape [n_samples]] Predicted class label per sample.

**score** *(X, y, sample_weight=None)*
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] Mean accuracy of `self.predict(X)` wrt. `y`.

**set_params** (**kwargs**)
Set and validate the parameters of estimator.

**Parameters**

- **kwargs** [dict] Estimator parameters.

**Returns**

**self** [object] Estimator instance.

**sparsify** ()
Convert coefficient matrix to sparse format.
Converts the coef_ member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The intercept_ member is not converted.

Returns

self  Fitted estimator.

Notes

For non-sparse models, i.e. when there are not many zeros in coef_, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with (coef_ == 0).sum(), must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the partial_fit method (if any) will not work until you call densify.

Examples using sklearn.linear_model.PassiveAggressiveClassifier

- Out-of-core classification of text documents
- Comparing various online solvers
- Classification of text documents using sparse features

sklearn.linear_model.Perceptron

class sklearn.linear_model.Perceptron(*, penalty=None, alpha=0.0001, l1_ratio=0.15, fit_intercept=True, max_iter=1000, tol=0.001, shuffle=True, verbose=0, eta0=1.0, n_jobs=None, random_state=0, early_stopping=False, validation_fraction=0.1, n_iter_no_change=5, class_weight=None, warm_start=False)

Read more in the User Guide.

Parameters

penalty  [{‘l2’,’l1’,’elasticnet’}, default=None] The penalty (aka regularization term) to be used.

alpha  [float, default=0.0001] Constant that multiplies the regularization term if regularization is used.

l1_ratio  [float, default=0.15] The Elastic Net mixing parameter, with 0 <= l1_ratio <= 1. l1_ratio=0 corresponds to L2 penalty, l1_ratio=1 to L1. Only used if penalty='elasticnet'.

New in version 0.24.

fit_intercept  [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered.

max_iter  [int, default=1000] The maximum number of passes over the training data (aka epochs). It only impacts the behavior in the fit method, and not the partial_fit method.

New in version 0.19.
tol [float, default=1e-3] The stopping criterion. If it is not None, the iterations will stop when \((\text{loss} > \text{previous_loss} - \text{tol})\).

New in version 0.19.

shuffle [bool, default=True] Whether or not the training data should be shuffled after each epoch.

verbose [int, default=0] The verbosity level

eta0 [double, default=1] Constant by which the updates are multiplied.

n_jobs [int, default=None] The number of CPUs to use to do the OVA (One Versus All, for multi-class problems) computation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

random_state [int, RandomState instance, default=None] Used to shuffle the training data, when shuffle is set to True. Pass an int for reproducible output across multiple function calls. See Glossary.

early_stopping [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to True, it will automatically set aside a stratified fraction of training data as validation and terminate training when validation score is not improving by at least tol for n_iter_no_change consecutive epochs.

New in version 0.20.

validation_fraction [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True.

New in version 0.20.

n_iter_no_change [int, default=5] Number of iterations with no improvement to wait before early stopping.

New in version 0.20.

class_weight [dict, {class_label: weight} or “balanced”, default=None] Preset for the class_weight fit parameter.

Weights associated with classes. If not given, all classes are supposed to have weight one.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as \(n\_\text{samples} / (n\_\text{classes} * \text{np.bincount}(y))\)

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

Attributes

classes_ [ndarray of shape (n_classes,)] The unique classes labels.

coeef_ [ndarray of shape (1, n_features) if n_classes == 2 else (n_classes, n_features)] Weights assigned to the features.

intercept_ [ndarray of shape (1,) if n_classes == 2 else (n_classes,)] Constants in decision function.

loss_function_ [concrete LossFunction] The function that determines the loss, or difference between the output of the algorithm and the target values.

n_iter_ [int] The actual number of iterations to reach the stopping criterion. For multiclass fits, it is the maximum over every binary fit.
t_ [int] Number of weight updates performed during training. Same as \((n\_iter_ \times n\_samples)\).

See also:

**SGDClassifier**

**Notes**

Perceptron is a classification algorithm which shares the same underlying implementation with SGDClassifier. In fact, Perceptron() is equivalent to SGDClassifier(loss="perceptron", eta0=1, learning_rate="constant", penalty=None).

**References**


**Examples**

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.linear_model import Perceptron
>>> X, y = load_digits(return_X_y=True)
>>> clf = Perceptron(tol=1e-3, random_state=0)
>>> clf.fit(X, y)
Perceptron()
>>> clf.score(X, y)
0.939...
```

**Methods**

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**decision_function(X)**

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- X [array-like or sparse matrix, shape \((n\_samples, n\_features)\)] Samples.

**Returns**
array, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes)  Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

densify()
Convert coefficient matrix to dense array format.

Converts the coef_ member (back) to a numpy.ndarray. This is the default format of coef_ and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

Returns

self  Fitted estimator.

fit(X, y, coef_init=None, intercept_init=None, sample_weight=None)
Fit linear model with Stochastic Gradient Descent.

Parameters

X  [{array-like, sparse matrix}, shape (n_samples, n_features)] Training data.
y  [ndarray of shape (n_samples,)] Target values.
coef_init  [ndarray of shape (n_classes, n_features), default=None] The initial coefficients to warm-start the optimization.
intercept_init  [ndarray of shape (n_classes,), default=None] The initial intercept to warm-start the optimization.
sample_weight  [array-like, shape (n_samples,), default=None] Weights applied to individual samples. If not provided, uniform weights are assumed. These weights will be multiplied with class_weight (passed through the constructor) if class_weight is specified.

Returns

self  :  Returns an instance of self.

get_params(deep=True)
Get parameters for this estimator.

Parameters

dep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

partial_fit(X, y, classes=None, sample_weight=None)
Perform one epoch of stochastic gradient descent on given samples.

Internally, this method uses max_iter = 1. Therefore, it is not guaranteed that a minimum of the cost function is reached after calling it once. Matters such as objective convergence and early stopping should be handled by the user.

Parameters

X  [{array-like, sparse matrix}, shape (n_samples, n_features)] Subset of the training data.
y  [ndarray of shape (n_samples,)] Subset of the target values.
classes  [ndarray of shape (n_classes,), default=None] Classes across all calls to partial_fit. Can be obtained by via np.unique(y_all), where y_all is the target vector of the
entire dataset. This argument is required for the first call to partial_fit and can be omitted in the subsequent calls. Note that y doesn’t need to contain all labels in \texttt{classes}.

\textbf{sample_weight} [array-like, shape (n_samples,), default=None] Weights applied to individual samples. If not provided, uniform weights are assumed.

**Returns**

\texttt{self} : Returns an instance of self.

\textbf{predict (X)}

Predict class labels for samples in \texttt{X}.

**Parameters**

\texttt{X} [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

\texttt{C} [array, shape [n_samples]] Predicted class label per sample.

\textbf{score (X, y, sample_weight=None)}

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

\texttt{X} [array-like of shape (n_samples, n_features)] Test samples.

\texttt{y} [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for \texttt{X}.

\textbf{sample_weight} [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

\texttt{score} [float] Mean accuracy of \texttt{self.predict (X)} wrt. \texttt{y}.

\textbf{set_params (**kwargs)}

Set and validate the parameters of estimator.

**Parameters**

**kwargs [dict] Estimator parameters.

**Returns**

\texttt{self} [object] Estimator instance.

\textbf{sparsify ()}

Convert coefficient matrix to sparse format.

Converts the \texttt{coef} member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The \texttt{intercept} member is not converted.

**Returns**

\texttt{self} Fitted estimator.
Notes

For non-sparse models, i.e., when there are not many zeros in `coef_`, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with `(coef_ == 0).sum()`, must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the `partial_fit` method (if any) will not work until you call `densify`.

Examples using `sklearn.linear_model.Perceptron`

- Out-of-core classification of text documents
- Comparing various online solvers
- Classification of text documents using sparse features

`sklearn.linear_model.RidgeClassifier`

```python
class sklearn.linear_model.RidgeClassifier(alpha=1.0, *, fit_intercept=True, normalize=False, copy_X=True, max_iter=None, tol=0.001, class_weight=None, solver='auto', random_state=None)
```

Classifier using Ridge regression.

This classifier first converts the target values into \{-1, 1\} and then treats the problem as a regression task (multi-output regression in the multiclass case).

Read more in the User Guide.

Parameters

- **alpha** [float, default=1.0] Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to \(1 / (2C)\) in other linear models such as `LogisticRegression` or `LinearSVC`.

- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (e.g. data is expected to be already centered).

- **normalize** [bool, default=False] This parameter is ignored when `fit_intercept` is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the 2-norm. If you wish to standardize, please use `StandardScaler` before calling `fit` on an estimator with `normalize=False`.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

- **max_iter** [int, default=None] Maximum number of iterations for conjugate gradient solver. The default value is determined by scipy.sparse.linalg.

- **tol** [float, default=1e-3] Precision of the solution.

- **class_weight** [dict or ‘balanced’, default=None] Weights associated with classes in the form `{class_label: weight}`. If not given, all classes are supposed to have weight one.

  The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as \(n_{samples} / (n_{classes} \times \text{np.bincount(y)})\).
**solver**  ['auto', 'svd', 'cholesky', 'lsqr', 'sparse_cg', 'sag', 'saga'], default='auto'] Solver to use in the computational routines:

- 'auto' chooses the solver automatically based on the type of data.
- 'svd' uses a Singular Value Decomposition of X to compute the Ridge coefficients. More stable for singular matrices than 'cholesky'.
- 'cholesky' uses the standard scipy.linalg.solve function to obtain a closed-form solution.
- 'sparse_cg' uses the conjugate gradient solver as found in scipy.sparse.linalg.cg. As an iterative algorithm, this solver is more appropriate than 'cholesky' for large-scale data (possibility to set tol and max_iter).
- 'lsqr' uses the dedicated regularized least-squares routine scipy.sparse.linalg.lsqr. It is the fastest and uses an iterative procedure.
- 'sag' uses a Stochastic Average Gradient descent, and 'saga' uses its unbiased and more flexible version named SAGA. Both methods use an iterative procedure, and are often faster than other solvers when both n_samples and n_features are large. Note that 'sag' and 'saga' fast convergence is only guaranteed on features with approximately the same scale. You can preprocess the data with a scaler from sklearn.preprocessing.

New in version 0.17: Stochastic Average Gradient descent solver.

New in version 0.19: SAGA solver.

**random_state** [int, RandomState instance, default=None] Used when solver == 'sag' or 'saga' to shuffle the data. See Glossary for details.

Attributes

- **coef_** [ndarray of shape (1, n_features) or (n_classes, n_features)] Coefficient of the features in the decision function. 

  coef_ is of shape (1, n_features) when the given problem is binary.

- **intercept_** [float or ndarray of shape (n_targets,)] Independent term in decision function. Set to 0.0 if fit_intercept = False.

- **n_iter_** [None or ndarray of shape (n_targets,)] Actual number of iterations for each target. 

  Available only for sag and lsqr solvers. Other solvers will return None.

- **classes_** [ndarray of shape (n_classes,)] The classes labels.

See also:

*Ridge* Ridge regression.

*RidgeClassifierCV* Ridge classifier with built-in cross validation.

**Notes**

For multi-class classification, n_class classifiers are trained in a one-versus-all approach. Concretely, this is implemented by taking advantage of the multi-variate response support in Ridge.
Examples

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.linear_model import RidgeClassifier

>>> X, y = load_breast_cancer(return_X_y=True)
>>> clf = RidgeClassifier().fit(X, y)

>>> clf.score(X, y)
0.9595...
```

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<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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`decision_function(X)`

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

Parameters

- `X` [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

- `array, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes)` Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

`fit(X, y, sample_weight=None)`

Fit Ridge classifier model.

Parameters

- `X` [[ndarray, sparse matrix] of shape (n_samples, n_features)] Training data.
- `y` [ndarray of shape (n_samples,)] Target values.
- `sample_weight` [float or ndarray of shape (n_samples,), default=None] Individual weights for each sample. If given a float, every sample will have the same weight.

New in version 0.17: `sample_weight` support to Classifier.

Returns

- `self` [object] Instance of the estimator.

`get_params(deep=True)`

Get parameters for this estimator.

Parameters

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
Returns

`params` [dict] Parameter names mapped to their values.

`predict (X)`
Predict class labels for samples in X.

Parameters

- `X` [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

- `C` [array, shape [n_samples]] Predicted class label per sample.

`sctore (X, y, sample_weight=None)`
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

- `X` [array-like of shape (n_samples, n_features)] Test samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- `score` [float] Mean accuracy of `self.predict (X)` wrt. y.

`set_params (**params)`
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- `**params` [dict] Estimator parameters.

Returns


Examples using `sklearn.linear_model.RidgeClassifier`

- Classification of text documents using sparse features

`sklearn.linear_model.RidgeClassifierCV`

`class sklearn.linear_model.RidgeClassifierCV (alphas=0.1, 1.0, 10.0, *, fit_intercept=True, normalize=False, scoring=None, cv=None, class_weight=None, store_cv_values=False)`

Ridge classifier with built-in cross-validation.

See glossary entry for cross-validation estimator.
By default, it performs Leave-One-Out Cross-Validation. Currently, only the n_features > n_samples case is handled efficiently.

Read more in the User Guide.

Parameters

**alphas** [ndarray of shape (n_alphas,), default=(0.1, 1.0, 10.0)] Array of alpha values to try. Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to $1 / (2C)$ in other linear models such as *LogisticRegression* or *LinearSVC*.

**fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to False, no intercept will be used in calculations (i.e. data is expected to be centered).

**normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use *StandardScaler* before calling fit on an estimator with normalize=False.

**scoring** [string, callable, default=None] A string (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y).

**cv** [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the efficient Leave-One-Out cross-validation
- integer, to specify the number of folds.
- *CV splitter*,
- An iterable yielding (train, test) splits as arrays of indices.

Refer User Guide for the various cross-validation strategies that can be used here.

**class_weight** [dict or ‘balanced’, default=None] Weights associated with classes in the form {class_label: weight}. If not given, all classes are supposed to have weight one. The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as n_samples / (n_classes * np.bincount(y))

**store_cv_values** [bool, default=False] Flag indicating if the cross-validation values corresponding to each alpha should be stored in the cv_values_ attribute (see below). This flag is only compatible with cv=None (i.e. using Leave-One-Out Cross-Validation).

Attributes

**cv_values_** [ndarray of shape (n_samples, n_targets, n_alphas), optional] Cross-validation values for each alpha (if store_cv_values=True and cv=None). After fit() has been called, this attribute will contain the mean squared errors (by default) or the values of the {loss,score}_func function (if provided in the constructor). This attribute exists only when store_cv_values is True.

**coef_** [ndarray of shape (1, n_features) or (n_targets, n_features)] Coefficient of the features in the decision function.

**intercept_** [float or ndarray of shape (n_targets,)] Independent term in decision function. Set to 0.0 if fit_intercept = False.
alpha_  [float] Estimated regularization parameter.

best_score_  [float] Score of base estimator with best alpha.

    New in version 0.23.

classes_  [ndarray of shape (n_classes,)] The classes labels.

See also:

Ridge  Ridge regression.

RidgeClassifier  Ridge classifier.

RidgeCV  Ridge regression with built-in cross validation.

Notes

For multi-class classification, n_class classifiers are trained in a one-versus-all approach. Concretely, this is implemented by taking advantage of the multi-variate response support in Ridge.

Examples

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.linear_model import RidgeClassifierCV
>>> X, y = load_breast_cancer(return_X_y=True)
>>> clf = RidgeClassifierCV(alphas=[1e-3, 1e-2, 1e-1, 1]).fit(X, y)
>>> clf.score(X, y)
0.9630...
```

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<td>score(X, y[, sample_weight])</td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
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</table>

**decision_function (X)**

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **array, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes)** Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

**fit (X, y, sample_weight=None)**
Fit Ridge classifier with cv.

**Parameters**

- X [ndarray of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features. When using GCV, will be cast to float64 if necessary.

- y [ndarray of shape (n_samples,)] Target values. Will be cast to X’s dtype if necessary.

- sample_weight [float or ndarray of shape (n_samples,), default=None] Individual weights for each sample. If given a float, every sample will have the same weight.

**Returns**

- self [object]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

**predict**(X)

Predict class labels for samples in X.

**Parameters**

- X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- C [array, shape [n_samples]] Predicted class label per sample.

**score**(X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Test samples.

- y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- score [float] Mean accuracy of self.predict(X) wrt. y.

**set_params**(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- **params [dict] Estimator parameters.
Returns

self [estimator instance] Estimator instance.

sklearn.linear_model.SGDClassifier

class sklearn.linear_model.SGDClassifier(loss='hinge', *, penalty='l2', alpha=0.0001, l1_ratio=0.15, fit_intercept=True, max_iter=1000, tol=0.001, shuffle=True, verbose=0, epsilon=0.1, n_jobs=None, random_state=None, learning_rate='optimal', eta0=0.0, power_t=0.5, early_stopping=False, validation_fraction=0.1, n_iter_no_change=5, class_weight=None, warm_start=False, average=False)

Linear classifiers (SVM, logistic regression, etc.) with SGD training.

This estimator implements regularized linear models with stochastic gradient descent (SGD) learning: the gradient of the loss is estimated each sample at a time and the model is updated along the way with a decreasing strength schedule (aka learning rate). SGD allows minibatch (online/out-of-core) learning via the partial_fit method. For best results using the default learning rate schedule, the data should have zero mean and unit variance.

This implementation works with data represented as dense or sparse arrays of floating point values for the features. The model it fits can be controlled with the loss parameter; by default, it fits a linear support vector machine (SVM).

The regularizer is a penalty added to the loss function that shrinks model parameters towards the zero vector using either the squared euclidean norm L2 or the absolute norm L1 or a combination of both (Elastic Net). If the parameter update crosses the 0.0 value because of the regularizer, the update is truncated to 0.0 to allow for learning sparse models and achieve online feature selection.

Read more in the User Guide.

Parameters

loss [str, default='hinge'] The loss function to be used. Defaults to ‘hinge’, which gives a linear SVM.


The ‘log’ loss gives logistic regression, a probabilistic classifier. ‘modified_huber’ is another smooth loss that brings tolerance to outliers as well as probability estimates. ‘squared_hinge’ is like hinge but is quadratically penalized. ‘perceptron’ is the linear loss used by the perceptron algorithm. The other losses are designed for regression but can be useful in classification as well; see SGDRegressor for a description.

More details about the losses formulas can be found in the User Guide.

penalty [{‘l2’, ‘l1’, ‘elasticnet’}, default=’l2’] The penalty (aka regularization term) to be used. Defaults to ‘l2’ which is the standard regularizer for linear SVM models. ‘l1’ and ‘elasticnet’ might bring sparsity to the model (feature selection) not achievable with ‘l2’.

alpha [float, default=0.0001] Constant that multiplies the regularization term. The higher the value, the stronger the regularization. Also used to compute the learning rate when set to learning_rate is set to ‘optimal’.
**l1_ratio** [float, default=0.15] The Elastic Net mixing parameter, with 0 <= l1_ratio <= 1. l1_ratio=0 corresponds to L2 penalty, l1_ratio=1 to L1. Only used if `penalty` is 'elasticnet'.

**fit_intercept** [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered.

**max_iter** [int, default=1000] The maximum number of passes over the training data (aka epochs). It only impacts the behavior in the `fit` method, and not the `partial_fit` method.

New in version 0.19.

**tol** [float, default=1e-3] The stopping criterion. If it is not None, training will stop when (loss > best_loss - tol) for `n_iter_no_change` consecutive epochs.

New in version 0.19.

**shuffle** [bool, default=True] Whether or not the training data should be shuffled after each epoch.

**verbose** [int, default=0] The verbosity level.

**epsilon** [float, default=0.1] Epsilon in the epsilon-insensitive loss functions; only if `loss` is 'huber', 'epsilon_insensitive', or 'squared_epsilon_insensitive'. For 'huber', determines the threshold at which it becomes less important to get the prediction exactly right. For epsilon-insensitive, any differences between the current prediction and the correct label are ignored if they are less than this threshold.

**n_jobs** [int, default=None] The number of CPUs to use to do the OVA (One Versus All, for multi-class problems) computation. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

**random_state** [int, RandomState instance, default=None] Used for shuffling the data, when `shuffle` is set to True. Pass an int for reproducible output across multiple function calls. See Glossary.

**learning_rate** [str, default=‘optimal’] The learning rate schedule:

- ‘constant’: eta = eta0
- ‘optimal’: eta = 1.0 / (alpha * (t + t0)) where t0 is chosen by a heuristic proposed by Leon Bottou.
- ‘invscaling’: eta = eta0 / pow(t, power_t)
- ‘adaptive’: eta = eta0, as long as the training keeps decreasing. Each time `n_iter_no_change` consecutive epochs fail to decrease the training loss by tol or fail to increase validation score by tol if `early_stopping` is True, the current learning rate is divided by 5.

New in version 0.20: Added ‘adaptive’ option

**eta0** [double, default=0.0] The initial learning rate for the ‘constant’, ‘invscaling’ or ‘adaptive’ schedules. The default value is 0.0 as eta0 is not used by the default schedule ‘optimal’.

**power_t** [double, default=0.5] The exponent for inverse scaling learning rate [default 0.5].

**early_stopping** [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to True, it will automatically set aside a stratified fraction of training data as validation and terminate training when validation score returned
by the score method is not improving by at least tol for n_iter_no_change consecutive epochs.

New in version 0.20: Added ‘early_stopping’ option

**validation_fraction** [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True.

New in version 0.20: Added ‘validation_fraction’ option

**n_iter_no_change** [int, default=5] Number of iterations with no improvement to wait before early stopping.

New in version 0.20: Added ‘n_iter_no_change’ option

**class_weight** [dict, {class_label: weight} or “balanced”, default=None] Preset for the class_weight fit parameter.

Weights associated with classes. If not given, all classes are supposed to have weight one.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as n_samples / (n_classes * np.bincount(y)).

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

Repeatedly calling fit or partial_fit when warm_start is True can result in a different solution than when calling fit a single time because of the way the data is shuffled. If a dynamic learning rate is used, the learning rate is adapted depending on the number of samples already seen. Calling fit resets this counter, while partial_fit will result in increasing the existing counter.

**average** [bool or int, default=False] When set to True, computes the averaged SGD weights accross all updates and stores the result in the coef_ attribute. If set to an int greater than 1, averaging will begin once the total number of samples seen reaches average. So average=10 will begin averaging after seeing 10 samples.

Attributes

**coef_** [ndarray of shape (1, n_features) if n_classes == 2 else (n_classes, n_features)] Weights assigned to the features.

**intercept_** [ndarray of shape (1,) if n_classes == 2 else (n_classes,)] Constants in decision function.

**n_iter_** [int] The actual number of iterations before reaching the stopping criterion. For multi-class fits, it is the maximum over every binary fit.

**loss_function_** [concrete LossFunction]

**classes_** [array of shape (n_classes,)]

**t_** [int] Number of weight updates performed during training. Same as (n_iter_ * n_samples).

See also:

**sklearn.svm.LinearSVC** Linear support vector classification.

**LogisticRegression** Logistic regression.
**Perceptron** Inheriting from SGDClassifier. Perceptron() is equivalent to SGDClassifier(loss="perceptron", eta0=1, learning_rate="constant", penalty=None).

### Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import SGDClassifier
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.pipeline import make_pipeline

>>> X = np.array([[[-1, -1], [-2, -1], [1, 1], [2, 1]])
>>> Y = np.array([1, 1, 2, 2])

# Always scale the input. The most convenient way is to use a pipeline.
>>> clf = make_pipeline(StandardScaler(),
...                      SGDClassifier(max_iter=1000, tol=1e-3))
>>> clf.fit(X, Y)
Pipeline(steps=[('standardscaler', StandardScaler()),
                ('sgdclassifier', SGDClassifier())])
>>> print(clf.predict([[[-0.8, -1]])
[1]
```

### Methods

- **decision_function(X)** Predict confidence scores for samples.
- **densify()** Convert coefficient matrix to dense array format.
- **fit(X, y[, coef_init, intercept_init, ...])** Fit linear model with Stochastic Gradient Descent.
- **get_params([deep])** Get parameters for this estimator.
- **partial_fit(X, y[, classes, sample_weight])** Perform one epoch of stochastic gradient descent on given samples.
- **predict(X)** Predict class labels for samples in X.
- **score(X, y[, sample_weight])** Return the mean accuracy on the given test data and labels.
- **set_params(**kwargs)** Set and validate the parameters of estimator.
- **sparsify()** Convert coefficient matrix to sparse format.

**decision_function(X)**

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **array, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes)** Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

**densify()**

Convert coefficient matrix to dense array format.

Converts the coef_ member (back) to a numpy.ndarray. This is the default format of coef_ and is required for fitting, so calling this method is only required on models that have previously been sparsified;
otherwise, it is a no-op.

Returns

self  Fitted estimator.

**fit** (*X, y, coef_init=None, intercept_init=None, sample_weight=None*)

Fit linear model with Stochastic Gradient Descent.

Parameters

- **X**  [[array-like, sparse matrix], shape (n_samples, n_features)] Training data.
- **y**  [ndarray of shape (n_samples,)] Target values.
- **coef_init**  [ndarray of shape (n_classes, n_features), default=None] The initial coefficients to warm-start the optimization.
- **intercept_init**  [ndarray of shape (n_classes,), default=None] The initial intercept to warm-start the optimization.
- **sample_weight**  [array-like, shape (n_samples,), default=None] Weights applied to individual samples. If not provided, uniform weights are assumed. These weights will be multiplied with class_weight (passed through the constructor) if class_weight is specified.

Returns

self : Returns an instance of self.

**get_params** *(deep=True)*

Get parameters for this estimator.

Parameters

- **deep**  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

**partial_fit** (*X, y, classes=None, sample_weight=None*)

Perform one epoch of stochastic gradient descent on given samples.

Internally, this method uses max_iter = 1. Therefore, it is not guaranteed that a minimum of the cost function is reached after calling it once. Matters such as objective convergence and early stopping should be handled by the user.

Parameters

- **X**  [[array-like, sparse matrix], shape (n_samples, n_features)] Subset of the training data.
- **y**  [ndarray of shape (n_samples,)] Subset of the target values.
- **classes**  [ndarray of shape (n_classes,), default=None] Classes across all calls to partial_fit. Can be obtained via np.unique(y_all), where y_all is the target vector of the entire dataset. This argument is required for the first call to partial_fit and can be omitted in the subsequent calls. Note that y doesn’t need to contain all labels in classes.
- **sample_weight**  [array-like, shape (n_samples,), default=None] Weights applied to individual samples. If not provided, uniform weights are assumed.

Returns

self : Returns an instance of self.
**predict** *(X)*

Predict class labels for samples in X.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **C** [array, shape [n_samples]] Predicted class label per sample.

**property predict_log_proba**

Log of probability estimates.

This method is only available for log loss and modified Huber loss.

When loss="modified_huber", probability estimates may be hard zeros and ones, so taking the logarithm is not possible.

See predict_proba for details.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] Input data for prediction.

**Returns**

- **T** [array-like, shape (n_samples, n_classes)] Returns the log-probability of the sample for each class in the model, where classes are ordered as they are in self.classes_

**property predict_proba**

Probability estimates.

This method is only available for log loss and modified Huber loss.

Multiclass probability estimates are derived from binary (one-vs.-rest) estimates by simple normalization, as recommended by Zadrozny and Elkan.

Binary probability estimates for loss="modified_huber" are given by (clip(decision_function(X), -1, 1) + 1) / 2. For other loss functions it is necessary to perform proper probability calibration by wrapping the classifier with CalibratedClassifierCV instead.

**Parameters**

- **X** [{array-like, sparse matrix}, shape (n_samples, n_features)] Input data for prediction.

**Returns**

- ndarray of shape (n_samples, n_classes) Returns the probability of the sample for each class in the model, where classes are ordered as they are in self.classes_

**References**


The justification for the formula in the loss="modified_huber" case is in the appendix B in: http://jmlr.csail.mit.edu/papers/volume2/zhang02c/zhang02c.pdf

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.
Parameters

X  [array-like of shape (n_samples, n_features)] Test samples.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] Mean accuracy of self.predict (X) wrt. y.

set_params(**kwargs)

Set and validate the parameters of estimator.

Parameters

**kwargs  [dict] Estimator parameters.

Returns

self  [object] Estimator instance.

sparsify()

Convert coefficient matrix to sparse format.

Converts the coef_ member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The intercept_ member is not converted.

Returns

self  Fitted estimator.

Notes

For non-sparse models, i.e. when there are not many zeros in coef_, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with (coef_ == 0).sum(), must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the partial_fit method (if any) will not work until you call densify.

Examples using sklearn.linear_model.SGDClassifier

• Sample pipeline for text feature extraction and evaluation

7.22.2 Classical linear regressors

| linear_model.LinearRegression(*[, ...]) | Ordinary least squares Linear Regression. |
| linear_model.Ridge(alpha, fit_intercept, ...) | Linear least squares with L2 regularization. |
| linear_model.RidgeCV([alphas, ...]) | Ridge regression with built-in cross-validation. |
| linear_model.SGDRegressor(loss, penalty, ...]) | Linear model fitted by minimizing a regularized empirical loss with SGD |
sklearn.linear_model.LinearRegression

class sklearn.linear_model.LinearRegression(*, fit_intercept=True, normalize=False, copy_X=True, n_jobs=None, positive=False)

Ordinary least squares Linear Regression.

LinearRegression fits a linear model with coefficients $w = (w_1, \ldots, w_p)$ to minimize the residual sum of squares between the observed targets in the dataset, and the targets predicted by the linear approximation.

**Parameters**

- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to False, no intercept will be used in calculations (i.e. data is expected to be centered).
- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the L2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.
- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
- **n_jobs** [int, default=None] The number of jobs to use for the computation. This will only provide speedup for n_targets > 1 and sufficient large problems. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.
- **positive** [bool, default=False] When set to True, forces the coefficients to be positive. This option is only supported for dense arrays.

New in version 0.24.

**Attributes**

- **coef_** [array of shape (n_features,) or (n_targets, n_features)] Estimated coefficients for the linear regression problem. If multiple targets are passed during the fit (y 2D), this is a 2D array of shape (n_targets, n_features), while if only one target is passed, this is a 1D array of length n_features.
- **rank_** [int] Rank of matrix X. Only available when X is dense.
- **singular_** [array of shape (min(X, y),)] Singular values of X. Only available when X is dense.
- **intercept_** [float or array of shape (n_targets,)] Independent term in the linear model. Set to 0.0 if fit_intercept = False.

See also:

- **Ridge** Ridge regression addresses some of the problems of Ordinary Least Squares by imposing a penalty on the size of the coefficients with l2 regularization.
- **Lasso** The Lasso is a linear model that estimates sparse coefficients with l1 regularization.
- **ElasticNet** Elastic-Net is a linear regression model trained with both l1 and l2 -norm regularization of the coefficients.
Notes

From the implementation point of view, this is just plain Ordinary Least Squares (scipy.linalg.lstsq) or Non Negative Least Squares (scipy.optimize.nnls) wrapped as a predictor object.

Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import LinearRegression

>>> X = np.array([[1, 1], [1, 2], [2, 2], [2, 3]])
>>> # y = 1 * x_0 + 2 * x_1 + 3
>>> y = np.dot(X, np.array([1, 2])) + 3
>>> reg = LinearRegression().fit(X, y)
>>> reg.score(X, y)
1.0
>>> reg.coef_
array([1., 2.])
>>> reg.intercept_
3.0000...
>>> reg.predict(np.array([[3, 5]]))
array([16.])
```

Methods

- `fit(X, y[, sample_weight])` Fit linear model.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict using the linear model.
- `score(X, y[, sample_weight])` Return the coefficient of determination $R^2$ of the prediction.
- `set_params(**params)` Set the parameters of this estimator.

**Methods**

- `fit(X, y[, sample_weight])` Fit linear model.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] Training data
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values. Will be cast to X’s dtypes if necessary
- **sample_weight** [array-like of shape (n_samples,), default=None] Individual weights for each sample

**Returns**

- **self** [returns an instance of self.]

- `get_params(deep=True)` Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
Returns

**params** [dict] Parameter names mapped to their values.

**predict** *(X)*
Predict using the linear model.

**Parameters**

**X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

**C** [array, shape (n_samples,)] Returns predicted values.

**score** *(X, y, sample_weight=None)*
Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( 1 - \frac{u}{v} \), where \( u \) is the residual sum of squares \( ((y_{true} - y_{pred}) ** 2).sum() \) and \( v \) is the total sum of squares \( ((y_{true} - y_{true}.mean()) ** 2).sum() \). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \( X \).

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] \( R^2 \) of self.predict(\( X \)) wrt. \( y \).

**Notes**

The \( R^2 \) score used when calling **score** on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of \( r2_score \). This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

**self** [estimator instance] Estimator instance.
Examples using `sklearn.linear_model.LinearRegression`

- Principal Component Regression vs Partial Least Squares Regression
- Plot individual and voting regression predictions
- Ordinary Least Squares and Ridge Regression Variance
- Logistic function
- Non-negative least squares
- Linear Regression Example
- Robust linear model estimation using RANSAC
- Sparsity Example: Fitting only features 1 and 2
- Theil-Sen Regression
- Robust linear estimator fitting
- Automatic Relevance Determination Regression (ARD)
- Bayesian Ridge Regression
- Isotonic Regression
- Face completion with a multi-output estimators
- Plotting Cross-Validated Predictions
- Underfitting vs. Overfitting
- Using KBinsDiscretizer to discretize continuous features

`sklearn.linear_model.Ridge`

The `sklearn.linear_model.Ridge` class minimizes the objective function:

\[ ||y - Xw||^2_2 + \alpha \times ||w||^2_2 \]

This model solves a regression model where the loss function is the linear least squares function and regularization is given by the l2-norm. Also known as Ridge Regression or Tikhonov regularization. This estimator has built-in support for multi-variate regression (i.e., when y is a 2d-array of shape (n_samples, n_targets)).

Read more in the User Guide.

**Parameters**

- `alpha` ([float, ndarray of shape (n_targets,)], default=1.0) Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to \( 1 / (2C) \) in other linear models such as LogisticRegression or LinearSVC. If an array is passed, penalties are assumed to be specific to the targets. Hence they must correspond in number.

- `fit_intercept` [bool, default=True] Whether to fit the intercept for this model. If set to false, no intercept will be used in calculations (i.e. \( X \) and \( y \) are expected to be centered).
normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

max_iter [int, default=None] Maximum number of iterations for conjugate gradient solver. For ‘sparse_cg’ and ‘lsqr’ solvers, the default value is determined by scipy.sparse.linalg. For ‘sag’ solver, the default value is 1000.

tol [float, default=1e-3] Precision of the solution.


• ‘auto’ chooses the solver automatically based on the type of data.
• ‘svd’ uses a Singular Value Decomposition of X to compute the Ridge coefficients. More stable for singular matrices than ‘cholesky’.
• ‘cholesky’ uses the standard scipy.linalg.solve function to obtain a closed-form solution.
• ‘sparse_cg’ uses the conjugate gradient solver as found in scipy.sparse.linalg.cg. As an iterative algorithm, this solver is more appropriate than ‘cholesky’ for large-scale data (possibility to set tol and max_iter).
• ‘lsqr’ uses the dedicated regularized least-squares routine scipy.sparse.linalg.lsqr. It is the fastest and uses an iterative procedure.
• ‘sag’ uses a Stochastic Average Gradient descent, and ‘saga’ uses its improved, unbiased version named SAGA. Both methods also use an iterative procedure, and are often faster than other solvers when both n_samples and n_features are large. Note that ‘sag’ and ‘saga’ fast convergence is only guaranteed on features with approximately the same scale.

You can preprocess the data with a scaler from sklearn.preprocessing. All last five solvers support both dense and sparse data. However, only ‘sag’ and ‘sparse_cg’ supports sparse input when fit_intercept is True.

New in version 0.17: Stochastic Average Gradient descent solver.

New in version 0.19: SAGA solver.

random_state [int, RandomState instance, default=None] Used when solver == ‘sag’ or ‘saga’ to shuffle the data. See Glossary for details.

New in version 0.17: random_state to support Stochastic Average Gradient.

Attributes

coef_ [ndarray of shape (n_features,) or (n_targets, n_features)] Weight vector(s).

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function. Set to 0.0 if fit_intercept = False.

n_iter_ [None or ndarray of shape (n_targets,)] Actual number of iterations for each target. Available only for sag and lsqr solvers. Other solvers will return None.

New in version 0.17.

See also:

RidgeClassifier Ridge classifier.

RidgeCV Ridge regression with built-in cross validation.
**KernelRidge**  Kernel ridge regression combines ridge regression with the kernel trick.

### Examples

```python
>>> from sklearn.linear_model import Ridge
>>> import numpy as np

>>> n_samples, n_features = 10, 5
>>> rng = np.random.RandomState(0)

>>> y = rng.randn(n_samples)
>>> X = rng.randn(n_samples, n_features)
>>> clf = Ridge(alpha=1.0)
>>> clf.fit(X, y)
```

### Methods

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<th>Description</th>
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<td>Fit Ridge regression model.</td>
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<td><code>get_params([deep])</code></td>
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<td>Predict using the linear model.</td>
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<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
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**fit**(X, y, sample_weight=None)

Fit Ridge regression model.

**Parameters**

- **X**  
  [ndarray, sparse matrix] of shape (n_samples, n_features)  
  Training data  

- **y**  
  [ndarray of shape (n_samples,) or (n_samples, n_targets)]  
  Target values  

- **sample_weight**  
  [float or ndarray of shape (n_samples,), default=None]  
  Individual weights for each sample. If given a float, every sample will have the same weight.

**Returns**

- **self**  
  [returns an instance of self.]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep**  
  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params**  
  [dict] Parameter names mapped to their values.

**predict**(X)

Predict using the linear model.

**Parameters**

- **X**  
  [array-like or sparse matrix, shape (n_samples, n_features)]  
  Samples.

**Returns**

...
C [array, shape (n_samples,)] Returns predicted values.

**score** *(X, y, sample_weight=None)*

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt. y.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.linear_model.Ridge**

- **Compressive sensing: tomography reconstruction with L1 prior (Lasso)**
- **Prediction Latency**
- **Plot Ridge coefficients as a function of the regularization**
- **Ordinary Least Squares and Ridge Regression Variance**
- **Plot Ridge coefficients as a function of the L2 regularization**
- **Polynomial interpolation**
- **HuberRegressor vs Ridge on dataset with strong outliers**
• Poisson regression and non-normal loss
• Common pitfalls in interpretation of coefficients of linear models

sklearn.linear_model.RidgeCV

class sklearn.linear_model.RidgeCV(alphas=(0.1, 1.0, 10.0), *, fit_intercept=True, normalize=False, scoring=None, cv=None, gcv_mode=None, store_cv_values=False, alpha_per_target=False)

Ridge regression with built-in cross-validation. See glossary entry for cross-validation estimator.

By default, it performs Leave-One-Out Cross-Validation, which is a form of efficient Leave-One-Out cross-validation.

Read more in the User Guide.

Parameters

alphas [ndarray of shape (n_alphas,), default=(0.1, 1.0, 10.0)] Array of alpha values to try. Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to $1 / (2C)$ in other linear models such as LogisticRegression or LinearSVC. If using Leave-One-Out cross-validation, alphas must be positive.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

scoring [string, callable, default=None] A string (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y). If None, the negative mean squared error if cv is ‘auto’ or None (i.e. when using leave-one-out cross-validation), and r2 score otherwise.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

• integer, to specify the number of folds.

• CV splitter,

• An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if y is binary or multiclass, StratifiedKFold is used, else, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

gcv_mode [‘auto’, ‘svd’, ‘eigen’], default=‘auto’] Flag indicating which strategy to use when performing Leave-One-Out Cross-Validation. Options are:
The ‘auto’ mode is the default and is intended to pick the cheaper option of the two depending on the shape of the training data.

store_cv_values [bool, default=False] Flag indicating if the cross-validation values corresponding to each alpha should be stored in the cv_values_ attribute (see below). This flag is only compatible with cv=None (i.e. using Leave-One-Out Cross-Validation).

alpha_per_target [bool, default=False] Flag indicating whether to optimize the alpha value (picked from the alphas parameter list) for each target separately (for multi-output settings: multiple prediction targets). When set to True, after fitting, the alpha_ attribute will contain a value for each target. When set to False, a single alpha is used for all targets.

New in version 0.24.

Attributes

cv_values_ [ndarray of shape (n_samples, n_alphas) or shape (n_samples, n_targets, n_alphas), optional] Cross-validation values for each alpha (only available if store_cv_values=True and cv=None). After fit() has been called, this attribute will contain the mean squared errors (by default) or the values of the {loss, score}_func function (if provided in the constructor).

coeff_ [ndarray of shape (n_features) or (n_targets, n_features)] Weight vector(s).

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function. Set to 0.0 if fit_intercept = False.

alpha_ [float or ndarray of shape (n_targets,)] Estimated regularization parameter, or, if alpha_per_target=True, the estimated regularization parameter for each target.

best_score_ [float or ndarray of shape (n_targets,)] Score of base estimator with best alpha, or, if alpha_per_target=True, a score for each target.

New in version 0.23.

See also:

Ridge Ridge regression.
RidgeClassifier Ridge classifier.
RidgeClassifierCV Ridge classifier with built-in cross validation.

Examples

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.linear_model import RidgeCV
>>> X, y = load_diabetes(return_X_y=True)
>>> clf = RidgeCV(alphas=[1e-3, 1e-2, 1e-1, 1]).fit(X, y)
>>> clf.score(X, y)
0.5166...
```
## Methods

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<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

### `fit(X, y, sample_weight=None)`
Fit Ridge regression model with cv.

**Parameters**
- **X** [ndarray of shape (n_samples, n_features)] Training data. If using GCV, will be cast to float64 if necessary.
- **y** [ndarray of shape (n_samples,) or (n_samples, n_targets)] Target values. Will be cast to X’s dtype if necessary.
- **sample_weight** [float or ndarray of shape (n_samples,), default=None] Individual weights for each sample. If given a float, every sample will have the same weight.

**Returns**
- **self** [object]

### Notes

When `sample_weight` is provided, the selected hyperparameter may depend on whether we use leave-one-out cross-validation (cv=None or cv='auto') or another form of cross-validation, because only leave-one-out cross-validation takes the sample weights into account when computing the validation score.

### `get_params(deep=True)`
Get parameters for this estimator.

**Parameters**
- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- **params** [dict] Parameter names mapped to their values.

### `predict(X)`
Predict using the linear model.

**Parameters**
- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**
- **C** [array, shape (n_samples,)] Returns predicted values.

### `score(X, y, sample_weight=None)`
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. 

---

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The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of `self.predict(X)` wrt. `y`.

**Notes**

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

**set_params(**params**)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

- ****params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using `sklearn.linear_model.RidgeCV`**

- Combine predictors using stacking
- Common pitfalls in interpretation of coefficients of linear models
- Face completion with a multi-output estimators
- Effect of transforming the targets in regression model
**scikit-learn user guide, Release 0.24.0**

**sklearn.linear_model.SGDRegressor**

```python
class sklearn.linear_model.SGDRegressor(loss='squared_loss', *, penalty='l2', alpha=0.0001, l1_ratio=0.15, fit_intercept=True, max_iter=1000, tol=0.001, shuffle=True, verbose=0, epsilon=0.1, random_state=None, learning_rate='invscaling', eta0=0.01, power_t=0.25, early_stopping=False, validation_fraction=0.1, n_iter_no_change=5, warm_start=False, average=False)
```

Linear model fitted by minimizing a regularized empirical loss with SGD

SGD stands for Stochastic Gradient Descent: the gradient of the loss is estimated each sample at a time and the model is updated along the way with a decreasing strength schedule (aka learning rate).

The regularizer is a penalty added to the loss function that shrinks model parameters towards the zero vector using either the squared euclidean norm L2 or the absolute norm L1 or a combination of both (Elastic Net). If the parameter update crosses the 0.0 value because of the regularizer, the update is truncated to 0.0 to allow for learning sparse models and achieve online feature selection.

This implementation works with data represented as dense numpy arrays of floating point values for the features.

Read more in the User Guide.

**Parameters**

- **loss** [str, default=’squared_loss’] The loss function to be used. The possible values are ‘squared_loss’, ‘huber’, ‘epsilon_insensitive’, or ‘squared_epsilon_insensitive’

  The ‘squared_loss’ refers to the ordinary least squares fit. ‘huber’ modifies ‘squared_loss’ to focus less on getting outliers correct by switching from squared to linear loss past a distance of epsilon. ‘epsilon_insensitive’ ignores errors less than epsilon and is linear past that; this is the loss function used in SVR. ‘squared_epsilon_insensitive’ is the same but becomes squared loss past a tolerance of epsilon.

  More details about the losses formulas can be found in the User Guide.

- **penalty** [‘l2’, ‘l1’, ‘elasticnet’], default=’l2’] The penalty (aka regularization term) to be used. Defaults to ‘l2’ which is the standard regularizer for linear SVM models. ‘l1’ and ‘elasticnet’ might bring sparsity to the model (feature selection) not achievable with ‘l2’.

- **alpha** [float, default=0.0001] Constant that multiplies the regularization term. The higher the value, the stronger the regularization. Also used to compute the learning rate when set to learning_rate is set to ‘optimal’.

- **l1_ratio** [float, default=0.15] The Elastic Net mixing parameter, with 0 <= l1_ratio <= 1. l1_ratio=0 corresponds to L2 penalty, l1_ratio=1 to L1. Only used if penalty is ‘elasticnet’.

- **fit_intercept** [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered.

- **max_iter** [int, default=1000] The maximum number of passes over the training data (aka epochs). It only impacts the behavior in the fit method, and not the partial_fit method.

  New in version 0.19.

- **tol** [float, default=1e-3] The stopping criterion. If it is not None, training will stop when (loss > best_loss - tol) for n_iter_no_change consecutive epochs.

  New in version 0.19.
shuffle [bool, default=True] Whether or not the training data should be shuffled after each epoch.

verbose [int, default=0] The verbosity level.

epsilon [float, default=0.1] Epsilon in the epsilon-insensitive loss functions; only if loss is ‘huber’, ‘epsilon_insensitive’, or ‘squared_epsilon_insensitive’. For ‘huber’, determines the threshold at which it becomes less important to get the prediction exactly right. For epsilon-insensitive, any differences between the current prediction and the correct label are ignored if they are less than this threshold.

random_state [int, RandomState instance, default=None] Used for shuffling the data, when shuffle is set to True. Pass an int for reproducible output across multiple function calls. See Glossary.

learning_rate [string, default='invscaling'] The learning rate schedule:

• ‘constant’: \(\eta = \eta_0\)
• ‘optimal’: \(\eta = 1.0 / (\alpha * (t + t0))\) where t0 is chosen by a heuristic proposed by Leon Bottou.
• ‘invscaling’: \(\eta = \eta_0 / pow(t, power_t)\)
• ‘adaptive’: \(\eta = \eta_0\), as long as the training keeps decreasing. Each time n_iter_no_change consecutive epochs fail to decrease the training loss by tol or fail to increase validation score by tol if early_stopping is True, the current learning rate is divided by 5.

New in version 0.20: Added ‘adaptive’ option

eta0 [double, default=0.01] The initial learning rate for the ‘constant’, ‘invscaling’ or ‘adaptive’ schedules. The default value is 0.01.

power_t [double, default=0.25] The exponent for inverse scaling learning rate.

early_stopping [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to True, it will automatically set aside a fraction of training data as validation and terminate training when validation score returned by the score method is not improving by at least tol for n_iter_no_change consecutive epochs.

New in version 0.20: Added ‘early_stopping’ option

validation_fraction [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True.

New in version 0.20: Added ‘validation_fraction’ option

n_iter_no_change [int, default=5] Number of iterations with no improvement to wait before early stopping.

New in version 0.20: Added ‘n_iter_no_change’ option

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

Repeatedly calling fit or partial_fit when warm_start is True can result in a different solution than when calling fit a single time because of the way the data is shuffled. If a dynamic learning rate is used, the learning rate is adapted depending on the number of samples already seen. Calling fit resets this counter, while partial_fit will result in increasing the existing counter.
average [bool or int, default=False] When set to True, computes the averaged SGD weights accross all updates and stores the result in the coef_ attribute. If set to an int greater than 1, averaging will begin once the total number of samples seen reaches average. So average=10 will begin averaging after seeing 10 samples.

Attributes

coef_ [ndarray of shape (n_features,)] Weights assigned to the features.

intercept_ [ndarray of shape (1,)] The intercept term.

average_coef_ [ndarray of shape (n_features,)] Averaged weights assigned to the features. Only available if average=True.

average_intercept_ [ndarray of shape (1,)] The averaged intercept term. Only available if average=True.

n_iter_ [int] The actual number of iterations before reaching the stopping criterion.

t_ [int] Number of weight updates performed during training. Same as (n_iter_ * n_samples).

See also:

Ridge, ElasticNet, Lasso, sklearn.svm.SVR

Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import SGDRegressor
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler

>>> n_samples, n_features = 10, 5
>>> rng = np.random.RandomState(0)
>>> y = rng.randn(n_samples)
>>> X = rng.randn(n_samples, n_features)

>>> # Always scale the input. The most convenient way is to use a pipeline.
>>> reg = make_pipeline(StandardScaler(),
...                      SGDRegressor(max_iter=1000, tol=1e-3))

>>> reg.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()),
               ('sgdregressor', SGDRegressor())])
```
# Methods

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<td>Convert coefficient matrix to dense array format.</td>
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<tr>
<td>fit(X, y[, coef_init, intercept_init, ...])</td>
<td>Fit linear model with Stochastic Gradient Descent.</td>
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<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<tr>
<td>partial_fit(X, y[, sample_weight])</td>
<td>Perform one epoch of stochastic gradient descent on given samples.</td>
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<tr>
<td>predict(X)</td>
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</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**kwargs)</td>
<td>Set and validate the parameters of estimator.</td>
</tr>
<tr>
<td>sparsify()</td>
<td>Convert coefficient matrix to sparse format.</td>
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## densify()

Convert coefficient matrix to dense array format.

Converts the `coef_` member (back) to a `numpy.ndarray`. This is the default format of `coef_` and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

**Returns**

- `self`  Fitted estimator.

## fit (X, y, coef_init=None, intercept_init=None, sample_weight=None)

Fit linear model with Stochastic Gradient Descent.

**Parameters**

- `X`  [[array-like, sparse matrix], shape (n_samples, n_features)] Training data
- `y`  [ndarray of shape (n_samples,)] Target values
- `coef_init` [ndarray of shape (n_features,), default=None] The initial coefficients to warm-start the optimization.
- `intercept_init` [ndarray of shape (1,), default=None] The initial intercept to warm-start the optimization.
- `sample_weight` [array-like, shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

**Returns**

- `self`  [returns an instance of self.]

## get_params (deep=True)

Get parameters for this estimator.

**Parameters**

- `deep`  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params`  [dict] Parameter names mapped to their values.

## partial_fit (X, y, sample_weight=None)

Perform one epoch of stochastic gradient descent on given samples.
Internally, this method uses \( \text{max\_iter} = 1 \). Therefore, it is not guaranteed that a minimum of the cost function is reached after calling it once. Matters such as objective convergence and early stopping should be handled by the user.

**Parameters**

- **X** ([array-like, sparse matrix], shape (n_samples, n_features)) Subset of training data
- **y** [numpy array of shape (n_samples,)] Subset of target values
- **sample_weight** [array-like, shape (n_samples,), default=None] Weights applied to individual samples. If not provided, uniform weights are assumed.

**Returns**

- **self** [returns an instance of self.]

**predict** (X)

Predict using the linear model

**Parameters**

- **X** ([array-like, sparse matrix], shape (n_samples, n_features))

**Returns**

- ndarray of shape (n_samples,) Predicted target values per element in X.

**score** (X, y, sample_weight=None)

Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( 1 - \frac{u}{v} \), where \( u \) is the residual sum of squares \( \sum((y \_true - y \_pred)^2) \) and \( v \) is the total sum of squares \( \sum((y \_true - y \_true \_mean)^2) \). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples\_fitted), where n_samples\_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] \( R^2 \) of \text{self} . \text{predict} (X) wrt. \( y \).

**Notes**

The \( R^2 \) score used when calling score on a regressor uses multioutput='uniform\_average' from version 0.23 to keep consistent with default value of \text{r2\_score}. This influences the score method of all the multioutput regressors (except for \text{MultiOutputRegressor}).

**set_params** (**kwargs)

Set and validate the parameters of estimator.

**Parameters**

- **kwargs** [dict] Estimator parameters.
Returns

**self** [object] Estimator instance.

**sparsify()**
Convert coefficient matrix to sparse format.
Converts the **coef_** member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.
The **intercept_** member is not converted.

Returns

**self** Fitted estimator.

Notes

For non-sparse models, i.e. when there are not many zeros in **coef_**, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with (**coef_ == 0**).sum(), must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the partial_fit method (if any) will not work until you call densify.

Examples using **sklearn.linear_model.SGDRegressor**

- **Prediction Latency**
- **SGD: Penalties**

### 7.22.3 Regressors with variable selection

The following estimators have built-in variable selection fitting procedures, but any estimator using a L1 or elastic-net penalty also performs variable selection: typically **SGDRegressor** or **SGDClassifier** with an appropriate penalty.

| **linear_model.ElasticNet([alpha, II_ratio, ...])** | Linear regression with combined L1 and L2 priors as regularizer. |
| **linear_model.ElasticNetCV([*, II_ratio, ...])** | Elastic Net model with iterative fitting along a regularization path. |
| **linear_model.Lars(*[fit_intercept, ...])** | Least Angle Regression model a.k.a. |
| **linear_model.LarsCV(*[fit_intercept, ...])** | Cross-validated Least Angle Regression model. |
| **linear_model.Lasso([alpha, fit_intercept, ...])** | Linear Model trained with L1 prior as regularizer (aka the Lasso) |
| **linear_model.LassoCV([*, eps, n_alphas, ...])** | Lasso linear model with iterative fitting along a regularization path. |
| **linear_model.LassoLars([alpha, ...])** | Lasso model fit with Least Angle Regression a.k.a. |
| **linear_model.LassoLarsCV(*[fit_intercept, ...])** | Cross-validated Lasso, using the LARS algorithm. |
| **linear_model.LassoLarsIC([criterion, ...])** | Lasso model fit with Lars using BIC or AIC for model selection |

continues on next page
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<tr>
<th>Cross-validated Orthogonal Matching Pursuit model (OMP).</th>
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</table>

**sklearn.linear_model.ElasticNet**

**class** sklearn.linear_model.ElasticNet (alpha=1.0, *, l1_ratio=0.5, fit_intercept=True, normalize=False, precompute=False, max_iter=1000, copy_X=True, tol=0.0001, warm_start=False, positive=False, random_state=None, selection='cyclic')

Linear regression with combined L1 and L2 priors as regularizer.

Minimizes the objective function:

\[
\frac{1}{2 \times n_{\text{samples}}} \| y - Xw \|^2_2 + \alpha \cdot l1_{\text{ratio}} \cdot \| w \|_1 + 0.5 \cdot \alpha \cdot (1 - l1_{\text{ratio}}) \cdot \| w \|^2_2
\]

If you are interested in controlling the L1 and L2 penalty separately, keep in mind that this is equivalent to:

\[
a \cdot L1 + b \cdot L2
\]

where:

\[
\text{alpha} = a + b \quad \text{and} \quad l1_{\text{ratio}} = a / (a + b)
\]

The parameter l1_ratio corresponds to alpha in the glmnet R package while alpha corresponds to the lambda parameter in glmnet. Specifically, l1_ratio = 1 is the lasso penalty. Currently, l1_ratio <= 0.01 is not reliable, unless you supply your own sequence of alpha.

Read more in the User Guide.

**Parameters**

- **alpha** [float, default=1.0] Constant that multiplies the penalty terms. Defaults to 1.0. See the notes for the exact mathematical meaning of this parameter. alpha = 0 is equivalent to an ordinary least square, solved by the LinearRegression object. For numerical reasons, using alpha = 0 with the Lasso object is not advised. Given this, you should use the LinearRegression object.

- **l1_ratio** [float, default=0.5] The ElasticNet mixing parameter, with 0 <= l1_ratio <= 1. For l1_ratio = 0 the penalty is an L2 penalty. For l1_ratio = 1 it is an L1 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1 and L2.

- **fit_intercept** [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered.

- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

- **precompute** [bool or array-like of shape (n_features, n_features), default=False] Whether to use a precomputed Gram matrix to speed up calculations. The Gram matrix can also be passed as argument. For sparse input this option is always True to preserve sparsity.

- **max_iter** [int, default=1000] The maximum number of iterations.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
tol [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

positive [bool, default=False] When set to True, forces the coefficients to be positive.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == ‘random’. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [{‘cyclic’, ‘random’}, default=’cyclic’] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

coef_ [ndarray of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the cost function formula).

sparse_coef_ [sparse matrix of shape (n_features,) or (n_tasks, n_features)] Sparse representation of the fitted coef_.

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function.

n_iter_ [list of int] Number of iterations run by the coordinate descent solver to reach the specified tolerance.

dual_gap_ [float or ndarray of shape (n_targets,)] Given param alpha, the dual gaps at the end of the optimization, same shape as each observation of y.

See also:

ElasticNetCV Elastic net model with best model selection by cross-validation.

SGDRegressor Implements elastic net regression with incremental training.

SGDClassifier Implements logistic regression with elastic net penalty (SGDClassifier(loss="log", penalty="elasticnet")).

Notes

To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a Fortran-contiguous numpy array.

Examples

```python
>>> from sklearn.linear_model import ElasticNet
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_features=2, random_state=0)
>>> regr = ElasticNet(random_state=0)
>>> regr.fit(X, y)
ElasticNet(random_state=0)
>>> print(regr.coef_)
```
Methods

**fit**(X, y[, sample_weight, check_input])  
Fit model with coordinate descent.

**get_params**(deep=False)  
Get parameters for this estimator.

**path**(args, **kwargs)  
Compute elastic net path with coordinate descent.

**predict**(X)  
Predict using the linear model.

**score**(X, y[, sample_weight])  
Return the coefficient of determination $R^2$ of the prediction.

**set_params**(**params)  
Set the parameters of this estimator.

**fit**(X, y, sample_weight=None, check_input=True)  
Fit model with coordinate descent.

**Parameters**

- **X**  
  [[ndarray, sparse matrix] of (n_samples, n_features)] Data.

- **y**  
  [[ndarray, sparse matrix] of shape (n_samples,)] or (n_samples, n_targets)] Target. Will be cast to X’s dtype if necessary.

- **sample_weight**  
  [float or array-like of shape (n_samples,), default=None] Sample weight.

  New in version 0.23.

- **check_input**  
  [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**Notes**

Coordinate descent is an algorithm that considers each column of data at a time hence it will automatically convert the X input as a Fortran-contiguous numpy array if necessary.

To avoid memory re-allocation it is advised to allocate the initial data in memory directly using that format.

**get_params**(deep=True)  
Get parameters for this estimator.

**Parameters**

- **deep**  
  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params**  
  [dict] Parameter names mapped to their values.

**static path**(args, **kwargs)  
Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.
For mono-output tasks it is:

\[
\frac{1}{(2 \times n_{\text{samples}})} \times ||y - Xw||^2_2
+ \alpha \times l1_{\text{ratio}} \times ||w||_1
+ 0.5 \times \alpha \times (1 - l1_{\text{ratio}}) \times ||w||^2_2
\]

For multi-output tasks it is:

\[
(\frac{1}{(2 \times n_{\text{samples}})}) \times ||Y - XW||^{\text{Fro}}_2
+ \alpha \times l1_{\text{ratio}} \times ||W||_21
+ 0.5 \times \alpha \times (1 - l1_{\text{ratio}}) \times ||W||_{\text{Fro}}^2
\]

Where:

\[
||W||_21 = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

y [{array-like, sparse matrix} of shape (n_samples,) or (n_samples, n_outputs)] Target values.

l1_ratio [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.

eps [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

n_alphas [int, default=100] Number of alphas along the regularization path.

alphas [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.

precompute ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

Xy [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

coeff_init [ndarray of shape (n_features, ), default=None] The initial values of the coefficients.

verbose [bool or int, default=False] Amount of verbosity.

return_n_iter [bool, default=False] Whether to return the number of iterations or not.

positive [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).

check_input [bool, default=True] If set to False, the input validation checks are skipped (including the Gram matrix when provided). It is assumed that they are handled by the caller.
**params**  [kwargs] Keyword arguments passed to the coordinate descent solver.

**Returns**

**alphas**  [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.

**coefs**  [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.

**dual_gaps**  [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

**n_iters**  [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha. (Is returned when return_n_iter is set to True).

**See also:**

*MultiTaskElasticNet*

*MultiTaskElasticNetCV*

*ElasticNet*

*ElasticNetCV*

**Notes**

For an example, see `examples/linear_model/plot_lasso_coordinate_descent_path.py`.

**predict**  (**X**)  
Predict using the linear model.

**Parameters**

**X**  [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

**C**  [array, shape (n_samples,)] Returns predicted values.

**score**  (**X**,  **y**,  **sample_weight=None**)  
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

**X**  [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

**y**  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

**sample_weight**  [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**
score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

property sparse_coef_

Sparse representation of the fitted coef_.

Examples using sklearn.linear_model.ElasticNet

- Release Highlights for scikit-learn 0.23
- Lasso and Elastic Net for Sparse Signals
- Train error vs Test error

sklearn.linear_model.ElasticNetCV

class sklearn.linear_model.ElasticNetCV(*, l1_ratio=0.5, eps=0.001, n_alphas=100, alphas=None, fit_intercept=True, normalize=False, precompute='auto', max_iter=1000, tol=0.0001, cv=None, copy_X=True, verbose=0, n_jobs=None, random_state=None, selection='cyclic')

Elastic Net model with iterative fitting along a regularization path.

See glossary entry for cross-validation estimator.

Read more in the User Guide.

Parameters

l1_ratio [float or list of float, default=0.5] float between 0 and 1 passed to ElasticNet (scaling between l1 and l2 penalties). For l1_ratio = 0 the penalty is an L2 penalty. For l1_ratio = 1 it is an L1 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1 and L2 This parameter can be a list, in which case the different values are tested by cross-validation and the one giving the best prediction score is used. Note that a good choice of list of values for l1_ratio is often to put more values close to 1 (i.e. Lasso) and less close to 0 (i.e. Ridge), as in [.1, .5, .7, .9, .95, .99, 1].
eps [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

n_alphas [int, default=100] Number of alphas along the regularization path, used for each l1_ratio.

alphas [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

precompute ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

max_iter [int, default=1000] The maximum number of iterations.

tol [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

cv [int, cross-validation generator or iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross-validation,
- int, to specify the number of folds.
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

verbose [bool or int, default=0] Amount of verbosity.

n_jobs [int, default=None] Number of CPUs to use during the cross validation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

positive [bool, default=False] When set to True, forces the coefficients to be positive.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == 'random'. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [‘cyclic’, ‘random’], default='cyclic'] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes
The parameter l1_ratio corresponds to alpha in the glmnet R package while alpha corresponds to the lambda parameter in glmnet. More specifically, the optimization objective is:

\[
\frac{1}{2n_{\text{samples}}} || y - Xw ||^2_2 + \alpha \cdot l1_{\text{ratio}} \cdot ||w||_1 + 0.5 \cdot \alpha \cdot (1 - l1_{\text{ratio}}) \cdot ||w||^2_2
\]

If you are interested in controlling the L1 and L2 penalty separately, keep in mind that this is equivalent to:

\[
a \cdot L1 + b \cdot L2
\]

for:

\[
\text{alpha} = a + b \quad \text{and} \quad l1_{\text{ratio}} = \frac{a}{a + b}.
\]

Examples

```python
>>> from sklearn.linear_model import ElasticNetCV
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_features=2, random_state=0)
>>> regr = ElasticNetCV(cv=5, random_state=0)
>>> regr.fit(X, y)
ElasticNetCV(cv=5, random_state=0)
```
>>> print(regr.alpha_)
0.199...
>>> print(regr.intercept_)
0.398...
>>> print(regr.predict([[0, 0]]))
[0.398...]

Methods

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<td>Fit linear model with coordinate descent.</td>
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<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<td>path(*args, **kwargs)</td>
<td>Compute elastic net path with coordinate descent.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

**fit** $(X, y)$
Fit linear model with coordinate descent.

- Fit is on grid of alphas and best alpha estimated by cross-validation.

**Parameters**

- $X$ [array-like, sparse matrix] of shape (n_samples, n_features)] Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output, X can be sparse.
- $y$ [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values.

**get_params** *(deep= True)*
Get parameters for this estimator.

- **Parameters**
  - **deep** [bool, default= True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

- **Returns**
  - **params** [dict] Parameter names mapped to their values.

**static path** *(*args, **kwargs)*
Compute elastic net path with coordinate descent.

- The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

$$\frac{1}{2n_{\text{samples}}} \cdot \| y - Xw \|^2_2 + \alpha \cdot \text{l1_ratio} \cdot \| w \|_1 + 0.5 \cdot \alpha \cdot (1 - \text{l1_ratio}) \cdot \| w \|^2_2$$

For multi-output tasks it is:
\[
\frac{1}{(2 \times n_{\text{samples}})} \times \|Y - XW\|_F^2
+ \alpha \times l1_{\text{ratio}} \times \|W\|_21
+ 0.5 \times \alpha \times (1 - l1_{\text{ratio}}) \times \|W\|_F^2
\]

Where:

\[\|W\|_21 = \sum_i \sqrt{\sum_j w_{ij}^2}\]

i.e. the sum of norm of each row.

Read more in the *User Guide*.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.
- **y** ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values.
- **l1_ratio** [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.
- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.
- **n_alphas** [int, default=100] Number of alphas along the regularization path.
- **alphas** [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.
- **precompute** [‘auto’, bool or array-like of shape (n_features, n_features), default=’auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to ‘auto’ let us decide. The Gram matrix can also be passed as argument.
- **Xy** [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.
- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
- **coef_init** [ndarray of shape (n_features, ), default=None] The initial values of the coefficients.
- **verbose** [bool or int, default=False] Amount of verbosity.
- **return_n_iter** [bool, default=False] Whether to return the number of iterations or not.
- **positive** [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).
- **check_input** [bool, default=True] If set to False, the input validation checks are skipped (including the Gram matrix when provided). It is assumed that they are handled by the caller.
- ****params** [kwargs] Keyword arguments passed to the coordinate descent solver.

**Returns**

- **alphas** [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.
...coefficients along the path.

dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

n_iter [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha. (Is returned when return_n_iter is set to True).

See also:

MultiTaskElasticNet
MultiTaskElasticNetCV
ElasticNet
ElasticNetCV

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

predict (X)
Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape (n_samples,)] Returns predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares \((y\_true - y\_pred)^2\).sum() and $v$ is the total sum of squares \((y\_true - y\_true.mean())^2\).sum().

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict (X) wrt. $y$. 
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params(**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

sklearn.linear_model.Lars

class sklearn.linear_model.Lars(*, fit_intercept=True, verbose=False, normalize=True, precompute='auto', n_nonzero_coefs=500, eps=2.220446049250313e-16, copy_X=True, fit_path=True, jitter=None, random_state=None)

Least Angle Regression model a.k.a. LAR

Read more in the User Guide.

**Parameters**

**fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

**verbose** [bool or int, default=False] Sets the verbosity amount.

**normalize** [bool, default=True] This parameter is ignored when `fit_intercept` is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use `StandardScaler` before calling fit on an estimator with normalize=False.

**precompute** [bool, ‘auto’ or array-like , default=‘auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

**n_nonzero_coefs** [int, default=500] Target number of non-zero coefficients. Use `np.inf` for no limit.

**eps** [float, default= np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the `tol` parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.

**copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

**fit_path** [bool, default=True] If True the full path is stored in the `coef_path_` attribute. If you compute the solution for a large problem or many targets, setting `fit_path` to False will lead to a speedup, especially with a small alpha.
**jitter** [float, default=None] Upper bound on a uniform noise parameter to be added to the $y$ values, to satisfy the model’s assumption of one-at-a-time computations. Might help with stability.

New in version 0.23.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation for jittering. Pass an int for reproducible output across multiple function calls. See *Glossary*. Ignored if **jitter** is None.

New in version 0.23.

**Attributes**

**alphas_** [array-like of shape (n_alphas + 1,) or list of thereof of shape (n_targets,)] Maximum of covariances (in absolute value) at each iteration. $n_{alphas}$ is either $max_{iter}$, $n_{features}$ or the number of nodes in the path with $alpha \geq alpha_{min}$, whichever is smaller.

**active_** [list of shape (n_alphas,) or list of thereof of shape (n_targets,)] Indices of active variables at the end of the path.

**coef_path_** [array-like of shape (n_features, n_alphas + 1) or list of thereof of shape (n_targets,)] The varying values of the coefficients along the path. It is not present if the **fit_path** parameter is False.

**coef_** [array-like of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the formulation formula).

**intercept_** [float or array-like of shape (n_targets,)] Independent term in decision function.

**n_iter_** [array-like or int] The number of iterations taken by lars_path to find the grid of alphas for each target.

See also:

*lars_path*, *LarsCV*

*sklearn.decomposition.sparse_encode*

**Examples**

```python
>>> from sklearn import linear_model
>>> reg = linear_model.Lars(n_nonzero_coefs=1)
>>> reg.fit([[[-1, 1], [0, 0], [1, 1]], [-1.1111, 0, -1.1111]])
Lars(n_nonzero_coefs=1)
>>> print(reg.coef_)
[ 0. -1.11...]
```
Methods

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<tbody>
<tr>
<td><code>fit(X, y[, Xy])</code></td>
<td>Fit the model using X, y as training data.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit (X, y, Xy=None)**
Fit the model using X, y as training data.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Training data.
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values.
- **Xy** [array-like of shape (n_samples,) or (n_samples, n_targets), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.

Returns

- **self** [object] returns an instance of self.

**get_params (deep=True)**
Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict (X)**
Predict using the linear model.

Parameters

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

- **C** [array, shape (n_samples,)] Returns predicted values.

**score (X, y, sample_weight=None)**
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_true - y_pred)**2).sum()$ and $v$ is the total sum of squares $((y_true - y_true.mean())**2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape

---

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(n_samples, n_samples_fitted), where n_samples_fitted is the number
of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average'
from version 0.23 to keep consistent with default value of r2_score. This influences the score method
of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

sklearn.linear_model.LarsCV

class sklearn.linear_model.LarsCV(*, fit_intercept=True, verbose=False,
max_iter=500, normalize=True, precompute='auto',
cv=None, max_n_alphas=1000, n_jobs=None,
eps=2.220446049250313e-16, copy_X=True)

Cross-validated Least Angle Regression model.

See glossary entry for cross-validation estimator.

Read more in the User Guide.

Parameters

fit_intercept [bool, default=True] whether to calculate the intercept for this model. If set to
false, no intercept will be used in calculations (i.e. data is expected to be centered).

verbose [bool or int, default=False] Sets the verbosity amount.

max_iter [int, default=500] Maximum number of iterations to perform.

normalize [bool, default=True] This parameter is ignored when fit_intercept is set to
False. If True, the regressors X will be normalized before regression by subtracting the mean
and dividing by the l2-norm. If you wish to standardize, please use StandardScaler
before calling fit on an estimator with normalize=False.

precompute [bool, ‘auto’ or array-like , default=’auto’] Whether to use a precomputed Gram
matrix to speed up calculations. If set to ‘auto’ let us decide. The Gram matrix cannot be
passed as argument since we will use only subsets of X.
cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation
splitting strategy. Possible inputs for cv are:
  • None, to use the default 5-fold cross-validation,
  • integer, to specify the number of folds.
  • CV splitter,
  • An iterable yielding (train, test) splits as arrays of indices.
For integer/None inputs, KFold is used.
Refer User Guide for the various cross-validation strategies that can be used here.
Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

max_n_alphas [int, default=1000] The maximum number of points on the path used to com-
pute the residuals in the cross-validation

n_jobs [int or None, default=None] Number of CPUs to use during the cross validation. None
means 1 unless in a joblib.parallel_backend context. -1 means using all proces-
sors. See Glossary for more details.

eps [float, default=np.finfo(float).eps] The machine-precision regularization in the computation
of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike
the tol parameter in some iterative optimization-based algorithms, this parameter does not
control the tolerance of the optimization.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

Attributes
  active_ [list of length n_alphas or list thereof of shape (n_targets,)] Indices of active variables
  at the end of the path.
  coef_ [array-like of shape (n_features,)] parameter vector (w in the formulation formula)
  intercept_ [float] independent term in decision function
  coef_path_ [array-like of shape (n_features, n_alphas)] the varying values of the coefficients
  along the path
  alpha_ [float] the estimated regularization parameter alpha
  alphas_ [array-like of shape (n_alphas,)] the different values of alpha along the path
  cv_alphas_ [array-like of shape (n_cv_alphas,)] all the values of alpha along the path for the
different folds
  mse_path_ [array-like of shape (n_folds, n_cv_alphas)] the mean square error on left-out for
each fold along the path (alpha values given by cv_alphas)
  n_iter_ [array-like or int] the number of iterations run by Lars with the optimal alpha.

See also:

lars_path, LassoLars, LassoLarsCV
Examples

```python
>>> from sklearn.linear_model import LarsCV
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_samples=200, noise=4.0, random_state=0)
>>> reg = LarsCV(cv=5).fit(X, y)
>>> reg.score(X, y)
0.9996...
>>> reg.alpha_
0.0254...

>>> reg.predict(X[:1,:])
array([154.0842...])
```

Methods

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<td>Set the parameters of this estimator.</td>
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**fit** *(X, y)*

Fit the model using X, y as training data.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data.
- **y** [array-like of shape (n_samples,)] Target values.

**Returns**

- **self** [object] returns an instance of self.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict** *(X)*

Predict using the linear model.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **C** [array, shape (n_samples,)] Returns predicted values.

**score** *(X, y[, sample_weight=None])* Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})^2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())^2).sum()$.

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.

- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of `self.predict(X)` wrt. $y$.

**Notes**

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

**set_params(**params)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**sklearn.linear_model.Lasso**

**class sklearn.linear_model.Lasso(alpha=1.0, *, fit_intercept=True, normalize=False, precompute=False, copy_X=True, max_iter=1000, tol=0.0001, warm_start=False, positive=False, random_state=None, selection='cyclic' )**

Linear Model trained with L1 prior as regularizer (aka the Lasso)

The optimization objective for Lasso is:

$\frac{1}{(2 \times n_{samples})} \times \|y - Xw\|^2 + \alpha \times |w|_1$

Technically the Lasso model is optimizing the same objective function as the Elastic Net with $l1_ratio=1.0$ (no L2 penalty).

Read more in the User Guide.

**Parameters**
alpha [float, default=1.0] Constant that multiplies the L1 term. Defaults to 1.0. alpha = 0 is equivalent to an ordinary least square, solved by the LinearRegression object. For numerical reasons, using alpha = 0 with the Lasso object is not advised. Given this, you should use the LinearRegression object.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to False, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

precompute ['auto', bool or array-like of shape (n_features, n_features), default=False] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument. For sparse input this option is always True to preserve sparsity.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

max_iter [int, default=1000] The maximum number of iterations.

tol [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

positive [bool, default=False] When set to True, forces the coefficients to be positive.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == 'random'. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [{‘cyclic’, ‘random’}, default=’cyclic’] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

coeff_ [ndarray of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the cost function formula).

dual_gap_ [float or ndarray of shape (n_targets,)] Given param alpha, the dual gaps at the end of the optimization, same shape as each observation of y.

sparse_coef_ [sparse matrix of shape (n_features, 1) or (n_targets, n_features)] Sparse representation of the fitted coef_.

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function.

n_iter_ [int or list of int] Number of iterations run by the coordinate descent solver to reach the specified tolerance.

See also:

lars_path
lasso_path
LassoLars
LassoCV
LassoLarsCV
sklearn.decomposition.sparse_encode

Notes

The algorithm used to fit the model is coordinate descent.
To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a
Fortran-contiguous numpy array.

Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.Lasso(alpha=0.1)
>>> clf.fit([[0,0], [1, 1], [2, 2]], [0, 1, 2])
Lasso(alpha=0.1)
>>> print(clf.coef_)
[0.85 0.]
>>> print(clf.intercept_)
0.15...
```

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</tr>
<tr>
<td>set_params</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

```
def fit(X, y, sample_weight=None, check_input=True):
    Fit model with coordinate descent.
```

Parameters

- **X** [(ndarray, sparse matrix) of (n_samples, n_features)] Data.
- **y** [(ndarray, sparse matrix) of shape (n_samples,) or (n_samples, n_targets)] Target. Will be cast to X’s dtype if necessary.
- **sample_weight** [float or array-like of shape (n_samples,), default=None] Sample weight.
  - New in version 0.23.
- **check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.
Notes

Coordinate descent is an algorithm that considers each column of data at a time hence it will automatically convert the X input as a Fortran-contiguous numpy array if necessary.

To avoid memory re-allocation it is advised to allocate the initial data in memory directly using that format.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

static path (*args, **kwargs)
Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
\frac{1}{2 \times n_{\text{samples}}} \times ||y - Xw||^2_2 \\
+ \alpha \times \text{l1_ratio} \times ||w||_1 \\
+ 0.5 \times \alpha \times (1 - \text{l1_ratio}) \times ||w||^2_2
\]

For multi-output tasks it is:

\[
\left(\frac{1}{2 \times n_{\text{samples}}}\right) \times ||Y - XW||_{\text{Fro}}^2 \\
+ \alpha \times \text{l1_ratio} \times ||W||_{21} \\
+ 0.5 \times \alpha \times (1 - \text{l1_ratio}) \times ||W||_{\text{Fro}}^2
\]

Where:

\[
||W||_{21} = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

y [array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs) Target values.

l1_ratio [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.

eps [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

n_alphas [int, default=100] Number of alphas along the regularization path.

alphas [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.
precompute ['auto', bool or array-like of shape (n_features, n_features), default='auto']
Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let
us decide. The Gram matrix can also be passed as argument.

Xy [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy =
np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is pre-
computed.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

ccoef_init [ndarray of shape (n_features,), default=None] The initial values of the coeffi-
cients.

verbose [bool or int, default=False] Amount of verbosity.

return_n_iter [bool, default=False] Whether to return the number of iterations or not.

positive [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed
when y.ndim == 1).

check_input [bool, default=True] If set to False, the input validation checks are skipped
(including the Gram matrix when provided). It is assumed that they are handled by the
caller.

**params [kwargs] Keyword arguments passed to the coordinate descent solver.

Returns

alphas [ndarray of shape (n_alphas,)] The alphas along the path where models are com-
puted.

coeefs [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficient-
s along the path.

dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for
each alpha.

n_iters [list of int] The number of iterations taken by the coordinate descent optimizer to
reach the specified tolerance for each alpha. (Is returned when return_n_iter is set
to True).

See also:

MultiTaskElasticNet
MultiTaskElasticNetCV
ElasticNet
ElasticNetCV

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

predict (X)
Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

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C [array, shape (n_samples,)] Returns predicted values.

**score** *(X, y, sample_weight=None)*  
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $(y_{true} - y_{pred})^2$.sum() and $v$ is the total sum of squares $(y_{true} - y_{true.mean()})^2$.sum(). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt. $y$.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**property sparse_coef_**

Sparse representation of the fitted coef_.

**Examples using sklearn.linear_model.Lasso**

- Release Highlights for scikit-learn 0.23
- Compressive sensing: tomography reconstruction with L1 prior (Lasso)
- Lasso on dense and sparse data
- Joint feature selection with multi-task Lasso
- Lasso and Elastic Net for Sparse Signals
• Cross-validation on diabetes Dataset Exercise

**sklearn.linear_model.LassoCV**

class sklearn.linear_model.LassoCV(*, eps=0.001, n_alphas=100, alphas=None, fit_intercept=True, normalize=False, precompute='auto', max_iter=1000, tol=0.0001, copy_X=True, cv=None, verbose=False, n_jobs=None, positive=False, random_state=None, selection='cyclic')

Lasso linear model with iterative fitting along a regularization path.

See glossary entry for cross-validation estimator.

The best model is selected by cross-validation.

The optimization objective for Lasso is:

\[
\frac{1}{(2 \times n\text{\_samples})} \times ||y - Xw||^2_2 + \alpha \times ||w||_1
\]

Read more in the User Guide.

**Parameters**

- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that \(\frac{\text{alpha\_min}}{\text{alpha\_max}} = 1e-3\).

- **n_alphas** [int, default=100] Number of alphas along the regularization path.

- **alphas** [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.

- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the L2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

- **precompute** ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

- **max_iter** [int, default=1000] The maximum number of iterations.

- **tol** [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

- **cv** [int, cross-validation generator or iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross-validation,
  - int, to specify the number of folds.
  - CV splitter,
  - An iterable yielding (train, test) splits as arrays of indices.
For int/None inputs, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

verbose [bool or int, default=False] Amount of verbosity.

n_jobs [int, default=None] Number of CPUs to use during the cross validation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

positive [bool, default=False] If positive, restrict regression coefficients to be positive.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == 'random'. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [‘cyclic’, ‘random’], default=’cyclic’] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

alpha_ [float] The amount of penalization chosen by cross validation.

coeff_ [ndarray of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the cost function formula).

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function.

mse_path_ [ndarray of shape (n_alphas, n_folds)] Mean square error for the test set on each fold, varying alpha.

alphas_ [ndarray of shape (n_alphas,)] The grid of alphas used for fitting.

dual_gap_ [float or ndarray of shape (n_targets,)] The dual gap at the end of the optimization for the optimal alpha (alpha_).

n_iter_ [int] Number of iterations run by the coordinate descent solver to reach the specified tolerance for the optimal alpha.

See also:

lars_path
lasso_path
LassoLars
Lasso
LassoLarsCV
Notes

For an example, see examples/linear_model/plot_lasso_model_selection.py.

To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a Fortran-contiguous numpy array.

Examples

```python
>>> from sklearn.linear_model import LassoCV
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(noise=4, random_state=0)
>>> reg = LassoCV(cv=5, random_state=0).fit(X, y)
>>> reg.score(X, y)
0.9993...
>>> reg.predict(X[:,1])
array([-78.4951...])
```

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<tr>
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<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

fit (X, y)

Fit linear model with coordinate descent.

Fit is on grid of alphas and best alpha estimated by cross-validation.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output, X can be sparse.
- **y** ([array-like of shape (n_samples,) or (n_samples, n_targets)]) Target values.

get_params (deep=True)

Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

static path (*args, **kwargs)

Compute Lasso path with coordinate descent.

The Lasso optimization function varies for mono and multi-outputs.
For mono-output tasks it is:

$$\left(\frac{1}{2 \times n_{\text{samples}}}\right) \ast ||y - Xw||^2_2 + \alpha \ast ||w||_1$$

For multi-output tasks it is:

$$\left(\frac{1}{2 \times n_{\text{samples}}}\right) \ast ||Y - XW||^2_{\text{Fro}} + \alpha \ast ||W||_{21}$$

Where:

$$||W||_{21} = \sum_i \sqrt{\sum_j w_{ij}^2}$$

i.e. the sum of norm of each row.

Read more in the User Guide.

**Parameters**

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features)] Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.
- **y** [[array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)] Target values
- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3
- **n_alphas** [int, default=100] Number of alphas along the regularization path
- **alphas** [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically
- **precompute** ['',false, bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.
- **Xy** [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.
- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
- **coef_init** [ndarray of shape (n_features,), default=None] The initial values of the coefficients.
- **verbose** [bool or int, default=False] Amount of verbosity.
- **return_n_iter** [bool, default=False] whether to return the number of iterations or not.
- **positive** [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).
- **params** [kwargs] keyword arguments passed to the coordinate descent solver.

**Returns**

- **alphas** [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.
- **coefs** [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.
**dual_gaps** [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

**n_iters** [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha.

See also:

- lars_path
- Lasso
- LassoLars
- LassoCV
- LassoLarsCV
- sklearn.decomposition.sparse_encode

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a Fortran-contiguous numpy array.

Note that in certain cases, the Lars solver may be significantly faster to implement this functionality. In particular, linear interpolation can be used to retrieve model coefficients between the values output by lars_path

Examples

Comparing lasso_path and lars_path with interpolation:

```python
>>> X = np.array([[1, 2, 3.1], [2.3, 5.4, 4.3]]).T
>>> y = np.array([1, 2, 3.1])
>>> # Use lasso_path to compute a coefficient path
>>> _, coef_path, _ = lasso_path(X, y, alphas=[5., 1., .5])
>>> print(coef_path)
[[0. 0. 0.46874778]
 [0.2159048 0.4425765 0.23689075]]

>>> # Now use lars_path and 1D linear interpolation to compute the same path
>>> from sklearn.linear_model import lars_path
>>> from scipy import interpolate
>>> alphas, active, coef_path_lars = lars_path(X, y, method='lasso')
>>> coef_path_continuous = interpolate.interp1d(alphas[::-1],
...     coef_path_lars[:, ::-1])
>>> print(coef_path_continuous([5., 1., .5]))
[[0. 0. 0.46915237]
 [0.2159048 0.4425765 0.23668876]]
```

**predict** *(X)*

Predict using the linear model.

Parameters
X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape (n_samples,)] Returns predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( 1 - \frac{u}{v} \), where \( u \) is the residual sum of squares \( \sum((y_{true} - y_{pred})^2) \) and \( v \) is the total sum of squares \( \sum((y_{true} - y_{true.mean})^2) \).

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] \( R^2 \) of self.predict(X) wrt. y.

Notes

The \( R^2 \) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.linear_model.LassoCV`

- Combine predictors using stacking
- Model-based and sequential feature selection
- Lasso model selection: Cross-Validation / AIC / BIC
- Common pitfalls in interpretation of coefficients of linear models
- Cross-validation on diabetes Dataset Exercise

`sklearn.linear_model.LassoLars`

```python
class sklearn.linear_model.LassoLars(alpha=1.0, *, fit_intercept=True, verbose=False, normalize=True, precompute='auto', max_iter=500, eps=2.220446049250313e-16, copy_X=True, fit_path=True, positive=False, jitter=None, random_state=None)
```

Lasso model fit with Least Angle Regression a.k.a. Lars

It is a Linear Model trained with an L1 prior as regularizer.

The optimization objective for Lasso is:

$$
(1 / (2 \times n_{\text{samples}})) \times ||y - Xw||^2_2 + \alpha \times ||w||_1
$$

Read more in the User Guide.

**Parameters**

- **alpha** [float, default=1.0] Constant that multiplies the penalty term. Defaults to 1.0. alpha = 0 is equivalent to an ordinary least square, solved by `LinearRegression`. For numerical reasons, using alpha = 0 with the LassoLars object is not advised and you should prefer the LinearRegression object.

- **fit_intercept** [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

- **verbose** [bool or int, default=False] Sets the verbosity amount.

- **normalize** [bool, default=True] This parameter is ignored when `fit_intercept` is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use `StandardScaler` before calling `fit` on an estimator with `normalize=False`.

- **precompute** [bool, ‘auto’ or array-like, default=’auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

- **max_iter** [int, default=500] Maximum number of iterations to perform.

- **eps** [float, default=np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the `tol` parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
fit_path [bool, default=True] If True the full path is stored in the coef_path_ attribute. If you compute the solution for a large problem or many targets, setting fit_path to False will lead to a speedup, especially with a small alpha.

positive [bool, default=False] Restrict coefficients to be >= 0. Be aware that you might want to remove fit_intercept which is set True by default. Under the positive restriction the model coefficients will not converge to the ordinary-least-squares solution for small values of alpha. Only coefficients up to the smallest alpha value (alphas_[alphas_ > 0.].min() when fit_path=True) reached by the stepwise Lars-Lasso algorithm are typically in congruence with the solution of the coordinate descent Lasso estimator.

jitter [float, default=None] Upper bound on a uniform noise parameter to be added to the y values, to satisfy the model’s assumption of one-at-a-time computations. Might help with stability.

New in version 0.23.

random_state [int, RandomState instance or None, default=None] Determines random number generation for jittering. Pass an int for reproducible output across multiple function calls. See Glossary. Ignored if jitter is None.

New in version 0.23.

Attributes

alphas_ [array-like of shape (n_alphas + 1,) or list of thereof of shape (n_targets,)] Maximum of covariances (in absolute value) at each iteration. n_alphas is either max_iter, n_features or the number of nodes in the path with alpha >= alpha_min, whichever is smaller.

active_ [list of length n_alphas or list of thereof of shape (n_targets,)] Indices of active variables at the end of the path.

coeff_path_ [array-like of shape (n_features, n_alphas + 1) or list of thereof of shape (n_targets,)] If a list is passed it’s expected to be one of n_targets such arrays. The varying values of the coefficients along the path. It is not present if the fit_path parameter is False.

coeff_ [array-like of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the formulation formula).

intercept_ [float or array-like of shape (n_targets,)] Independent term in decision function.

n_iter_ [array-like or int] The number of iterations taken by lars_path to find the grid of alphas for each target.

See also:

lars_path
lasso_path
Lasso
LassoCV
LassoLarsCV
LassoLarsIC
sklearn.decomposition.sparse_encode
### Examples

```python
>>> from sklearn import linear_model
>>> reg = linear_model.LassoLars(alpha=0.01)
>>> reg.fit([[[-1, 1], [0, 0], [1, 1]], [-1, 0, -1]])
LassoLars(alpha=0.01)
>>> print(reg.coef_)
[ 0. -0.963257...]
```

### Methods

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<td><code>fit(X, y[, Xy])</code></td>
<td>Fit the model using X, y as training data.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit** (X, y=None, Xy=None)

Fit the model using X, y as training data.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data.
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values.
- **Xy** [array-like of shape (n_samples,) or (n_samples, n_targets), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.

**Returns**

- **self** [object] returns an instance of self.

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict**(X)

Predict using the linear model.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **C** [array, shape (n_samples,)] Returns predicted values.

**score**(X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})^2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())^2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.

- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **score** [float] $R^2$ of self.predict(X) wrt. $y$.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

sklearn.linear_model.LassoLarsCV

class sklearn.linear_model.LassoLarsCV(*, fit_intercept=True, verbose=False, max_iter=500, normalize=True, precompute='auto', cv=None, max_n_alphas=1000, n_jobs=None, eps=2.220446049250313e-16, copy_X=True, positive=False)

Cross-validated Lasso, using the LARS algorithm.

See glossary entry for cross-validation estimator.

The optimization objective for Lasso is:

$$\frac{1}{(2 \times n_{samples})} \times ||y - Xw||^2_2 + \alpha \times ||w||_1$$

Read more in the User Guide.
fit_intercept [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

verbose [bool or int, default=False] Sets the verbosity amount.

max_iter [int, default=500] Maximum number of iterations to perform.

normalize [bool, default=True] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

precompute [bool or ‘auto’, default=’auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to ‘auto’ let us decide. The Gram matrix cannot be passed as argument since we will use only subsets of X.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross-validation,
- integer, to specify the number of folds,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, KFold is used. Refer User Guide for the various cross-validation strategies that can be used here. Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

max_n_alphas [int, default=1000] The maximum number of points on the path used to compute the residuals in the cross-validation

n_jobs [int or None, default=None] Number of CPUs to use during the cross validation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

eps [float, default=np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the tol parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

positive [bool, default=False] Restrict coefficients to be >= 0. Be aware that you might want to remove fit_intercept which is set True by default. Under the positive restriction the model coefficients do not converge to the ordinary-least-squares solution for small values of alpha. Only coefficients up to the smallest alpha value (alphas_[alphas_ > 0.].min() when fit_path=True) reached by the stepwise Lars-Lasso algorithm are typically in congruence with the solution of the coordinate descent Lasso estimator. As a consequence using LassoLarsCV only makes sense for problems where a sparse solution is expected and/or reached.

Attributes

coeff_ [array-like of shape (n_features,)] parameter vector (w in the formulation formula)

intercept_ [float] independent term in decision function.

coef_path_ [array-like of shape (n_features, n_alphas)] the varying values of the coefficients along the path
alpha_ [float] the estimated regularization parameter alpha
alphas_ [array-like of shape (n_alphas,)] the different values of alpha along the path
cv_alphas_ [array-like of shape (n_cv_alphas,)] all the values of alpha along the path for the different folds
mse_path_ [array-like of shape (n_folds, n_cv_alphas)] the mean square error on left-out for each fold along the path (alpha values given by cv_alphas)
n_iter_ [array-like or int] the number of iterations run by Lars with the optimal alpha.
active_ [list of int] Indices of active variables at the end of the path.

See also:

lars_path, LassoLars, LarsCV, LassoCV

Notes

The object solves the same problem as the LassoCV object. However, unlike the LassoCV, it find the relevant alphas values by itself. In general, because of this property, it will be more stable. However, it is more fragile to heavily multicollinear datasets.

It is more efficient than the LassoCV if only a small number of features are selected compared to the total number, for instance if there are very few samples compared to the number of features.

Examples

```python
>>> from sklearn.linear_model import LassoLarsCV
>>> from sklearn.datasets import make_regression
>>> X, y = make_regression(noise=4.0, random_state=0)
>>> reg = LassoLarsCV(cv=5).fit(X, y)
>>> reg.score(X, y)
0.9992...
>>> reg.alpha_
0.0484...
>>> reg.predict(X[:,:1])
array([-77.8723...])
```

Methods

- `fit(X, y)` Fit the model using X, y as training data.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict using the linear model.
- `score(X, y[, sample_weight])` Return the coefficient of determination $R^2$ of the prediction.
- `set_params(**params)` Set the parameters of this estimator.

```python
>>> fit(X, y)
Fit the model using X, y as training data.
```

Parameters

- `X` [array-like of shape (n_samples, n_features)] Training data.
y [array-like of shape (n_samples,)] Target values.

Returns

get_params (deep=True)
Get parameters for this estimator.

Parameters

dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape (n_samples,)] Returns predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{\sum}{\sum})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - \mu)^2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,)] or (n_samples, n_outputs) True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict (X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.linear_model.LassoLarsCV**

- Lasso model selection: Cross-Validation / AIC / BIC

**sklearn.linear_model.LassoLarsIC**

```python
class sklearn.linear_model.LassoLarsIC(criterion='aic', *, fit_intercept=True, verbose=False, normalize=True, precompute='auto', max_iter=500, eps=2.220446049250313e-16, copy_X=True, positive=False)
```

Lasso model fit with Lars using BIC or AIC for model selection

The optimization objective for Lasso is:

```
(1 / (2 * n_samples)) * ||y - Xw||^2_2 + alpha * ||w||_1
```

AIC is the Akaike information criterion and BIC is the Bayes Information criterion. Such criteria are useful to select the value of the regularization parameter by making a trade-off between the goodness of fit and the complexity of the model. A good model should explain well the data while being simple.

Read more in the User Guide.

**Parameters**

criterion [(‘bic’, ‘aic’), default=‘aic’] The type of criterion to use.

fit_intercept [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

verbose [bool or int, default=False] Sets the verbosity amount.

normalize [bool, default=True] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

precompute [bool, ‘auto’ or array-like, default=’auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

max_iter [int, default=500] Maximum number of iterations to perform. Can be used for early stopping.

eps [float, default=np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the tol parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.
copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

positive [bool, default=False] Restrict coefficients to be $\geq 0$. Be aware that you might want to remove fit_intercept which is set True by default. Under the positive restriction the model coefficients do not converge to the ordinary-least-squares solution for small values of alpha. Only coefficients up to the smallest alpha value ($\text{alphas}_\text{[alphas_} > 0.]\text{.min()}$ when fit_path=True) reached by the stepwise Lars-Lasso algorithm are typically in congruence with the solution of the coordinate descent Lasso estimator. As a consequence using LassoLarsIC only makes sense for problems where a sparse solution is expected and/or reached.

Attributes

coeff_ [array-like of shape (n_features,)] parameter vector (\(w\) in the formulation formula)

intercept_ [float] independent term in decision function.

alpha_ [float] the alpha parameter chosen by the information criterion

alphas_ [array-like of shape (n_alphas + 1,) or list thereof] Maximum of covariances (in absolute value) at each iteration. \(n\_\text{alphas}\) is either \(\text{max\_iter}, n\_\text{features}\) or the number of nodes in the path with \(\alpha \geq \alpha\_\text{min},\) whichever is smaller. If a list, it will be of length \(n\_\text{targets}\).

n_iter_ [int] number of iterations run by lars_path to find the grid of alphas.

criterion_ [array-like of shape (n_alphas,)] The value of the information criteria (‘aic’, ‘bic’) across all alphas. The alpha which has the smallest information criterion is chosen. This value is larger by a factor of \(n\_\text{samples}\) compared to Eqns. 2.15 and 2.16 in (Zou et al, 2007).

See also:

lars_path, LassoLars, LassoLarsCV

Notes

The estimation of the number of degrees of freedom is given by:


Examples

```python
>>> from sklearn import linear_model
>>> reg = linear_model.LassoLarsIC(criterion='bic')
>>> reg.fit([[-1, 1], [0, 0], [1, 1]], [-1.1111, 0, -1.1111])
LassoLarsIC(criterion='bic')
>>> print(reg.coef_)
[ 0. -1.11...]
```
### Methods

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<tbody>
<tr>
<td><code>fit(X, y[, copy_X])</code></td>
<td>Fit the model using $X$, $y$ as training data.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
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<td><code>predict(X)</code></td>
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<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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</tbody>
</table>

**fit ($X$, $y$, copy_X=None)**

Fit the model using $X$, $y$ as training data.

**Parameters**

- $X$ [array-like of shape (n_samples, n_features)] training data.
- $y$ [array-like of shape (n_samples,)] target values. Will be cast to $X$’s dtype if necessary
- copy_X [bool, default=None] If provided, this parameter will override the choice of copy_X made at instance creation. If True, $X$ will be copied; else, it may be overwritten.

**Returns**


**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

**predict ($X$)**

Predict using the linear model.

**Parameters**

- $X$ [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- $C$ [array, shape (n_samples,)] Returns predicted values.

**score ($X$, $y$, sample_weight=None)**

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})**2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())**2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- $X$ [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.linear_model.LassoLarsIC

• Lasso model selection: Cross-Validation / AIC / BIC

sklearn.linear_model.OptimalMatchingPursuit

class sklearn.linear_model.OptimalMatchingPursuit (*, n_nonzero_coefs=None, to=None, fit_intercept=True, normalize=True, precom-pute='auto')

Orthogonal Matching Pursuit model (OMP).

Read more in the User Guide.

Parameters

n_nonzero_coefs [int, default=None] Desired number of non-zero entries in the solution. If None (by default) this value is set to 10% of n_features.

tol [float, default=None] Maximum norm of the residual. If not None, overrides n_nonzero_coefs.

fit_intercept [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=True] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.
precompute ['auto' or bool, default='auto'] Whether to use a precomputed Gram and Xy matrix to speed up calculations. Improves performance when n_targets or n_samples is very large. Note that if you already have such matrices, you can pass them directly to the fit method.

Attributes

coef_ [ndarray of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the formula).

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function.

n_iter_ [int or array-like] Number of active features across every target.

n_nonzero_coefs_ [int] The number of non-zero coefficients in the solution. If n_nonzero_coefs is None and tol is None this value is either set to 10% of n_features or 1, whichever is greater.

See also:

orthogonal_mp
orthogonal_mp_gram
lars_path
Lars
LassoLars
sklearn.decomposition.sparse_encode
OrthogonalMatchingPursuitCV

Notes


Examples

```python
>>> from sklearn.linear_model import OrthogonalMatchingPursuit
>>> from sklearn.datasets import make_regression
>>> X, y = make_regression(noise=4, random_state=0)
>>> reg = OrthogonalMatchingPursuit().fit(X, y)
>>> reg.score(X, y)
0.9991...
>>> reg.predict(X[:1,])
array([-78.3854...])
```
Methods

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<td>set_params()</td>
<td>Set the parameters of this estimator.</td>
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**fit(X, y)**
- Fit the model using X, y as training data.

**Parameters**
- **X** [array-like of shape (n_samples, n_features)] Training data.
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values. Will be cast to X’s dtype if necessary

**Returns**
- **self** [object] returns an instance of self.

**get_params**(deep=True)
- Get parameters for this estimator.

**Parameters**
- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- **params** [dict] Parameter names mapped to their values.

**predict**(X)
- Predict using the linear model.

**Parameters**
- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**
- **C** [array, shape (n_samples,)] Returns predicted values.

**score**(X, y, sample_weight=None)
- Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**
- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] $R^2$ of self.predict(X) wrt. y.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params**(\*\*params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

**Parameters**

**\*\*params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.linear_model.OrthogonalMatchingPursuit**

- Orthogonal Matching Pursuit

**sklearn.linear_model.OrthogonalMatchingPursuitCV**

**class** sklearn.linear_model.OrthogonalMatchingPursuitCV(*, copy=True, fit_intercept=True, normalize=True, max_iter=None, cv=None, n_jobs=None, verbose=False)

Cross-validated Orthogonal Matching Pursuit model (OMP).

See glossary entry for cross-validation estimator.

Read more in the User Guide.

**Parameters**

**copy** [bool, default=True] Whether the design matrix X must be copied by the algorithm. A false value is only helpful if X is already Fortran-ordered, otherwise a copy is made anyway.

**fit_intercept** [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

**normalize** [bool, default=True] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

**max_iter** [int, default=None] Maximum numbers of iterations to perform, therefore maximum features to include. 10% of n_features but at least 5 if available.
cv [int, cross-validation generator or iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross-validation,
- integer, to specify the number of folds.
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, KFold is used. Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

n_jobs [int, default=None] Number of CPUs to use during the cross validation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [bool or int, default=False] Sets the verbosity amount.

Attributes

intercept_ [float or ndarray of shape (n_targets,)] Independent term in decision function.

coef_ [ndarray of shape (n_features,) or (n_targets, n_features)] Parameter vector (w in the problem formulation).

n_nonzero_coefs_ [int] Estimated number of non-zero coefficients giving the best mean squared error over the cross-validation folds.

n_iter_ [int or array-like] Number of active features across every target for the model refit with the best hyperparameters got by cross-validating across all folds.

See also:

orthogonal_mp
orthogonal_mp_gram
lars_path
Lars
LassoLars
OrthogonalMatchingPursuit
LarsCV
LassoLarsCV
sklearn.decomposition.sparse_encode
Examples

```python
>>> from sklearn.linear_model import OrthogonalMatchingPursuitCV
>>> from sklearn.datasets import make_regression
>>> X, y = make_regression(n_features=100, n_informative=10, ...
... noise=4, random_state=0)
>>> reg = OrthogonalMatchingPursuitCV(cv=5).fit(X, y)
>>> reg.score(X, y)
0.9991...
>>> reg.n_nonzero_coefs_
10
>>> reg.predict(X[:1,])
array([-78.3854...])
```

Methods

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<td>Fit the model using X, y as training data.</td>
</tr>
<tr>
<td><code>get_params</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit (X, y)**

Fit the model using X, y as training data.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Training data.
- y [array-like of shape (n_samples,)] Target values. Will be cast to X’s dtype if necessary.

**Returns**


**get_params**  

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

**predict (X)**

Predict using the linear model.

**Parameters**

- X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- C [array, shape (n_samples,)] Returns predicted values.
score \((X, y, \text{sample\_weight}=\text{None})\)

Return the coefficient of determination \(R^2\) of the prediction.

The coefficient \(R^2\) is defined as \((1 - \frac{u}{v})\), where \(u\) is the residual sum of squares \(((y\_true - y\_pred) ** 2).\text{sum()}\) and \(v\) is the total sum of squares \(((y\_true - y\_true.mean()) ** 2).\text{sum()}\).

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \(y\), disregarding the input features, would get a \(R^2\) score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \(X\).
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] \(R^2\) of self.predict \((X)\) wrt \(y\).

**Notes**

The \(R^2\) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of \(r2\_score\). This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<\text{component}>\__<\text{parameter}>\) so that it's possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.linear_model.OrthogonalMatchingPursuitCV**

- Orthogonal Matching Pursuit
7.22.4 Bayesian regressors

linear_model.ARDRegression(*[, n_iter, tol, ...])

Bayesian ARD regression.

linear_model.BayesianRidge(*[, n_iter, tol, ...])

Bayesian ridge regression.

sklearn.linear_model.ARDRegression

class sklearn.linear_model.ARDRegression(*, n_iter=300, tol=0.001, alpha_1=1e-06, alpha_2=1e-06, lambda_1=1e-06, lambda_2=1e-06, compute_score=False, threshold_lambda=10000.0, fit_intercept=True, normalize=False, copy_X=True, verbose=False)

Bayesian ARD regression.

Fit the weights of a regression model, using an ARD prior. The weights of the regression model are assumed to be in Gaussian distributions. Also estimate the parameters lambda (precisions of the distributions of the weights) and alpha (precision of the distribution of the noise). The estimation is done by an iterative procedures (Evidence Maximization)

Read more in the User Guide.

Parameters

n_iter  [int, default=300] Maximum number of iterations.

tol  [float, default=1e-3] Stop the algorithm if w has converged.

alpha_1  [float, default=1e-6] Hyper-parameter : shape parameter for the Gamma distribution prior over the alpha parameter.

alpha_2  [float, default=1e-6] Hyper-parameter : inverse scale parameter (rate parameter) for the Gamma distribution prior over the alpha parameter.

lambda_1  [float, default=1e-6] Hyper-parameter : shape parameter for the Gamma distribution prior over the lambda parameter.

lambda_2  [float, default=1e-6] Hyper-parameter : inverse scale parameter (rate parameter) for the Gamma distribution prior over the lambda parameter.

compute_score  [bool, default=False] If True, compute the objective function at each step of the model.

threshold_lambda  [float, default=10 000] threshold for removing (pruning) weights with high precision from the computation.

fit_intercept  [bool, default=True] whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize  [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

copy_X  [bool, default=True] If True, X will be copied; else, it may be overwritten.

verbose  [bool, default=False] Verboso mode when fitting the model.

Attributes
**coef_** [array-like of shape (n_features,)] Coefficients of the regression model (mean of distribution)

**alpha_** [float] estimated precision of the noise.

**lambda_** [array-like of shape (n_features,)] estimated precisions of the weights.

**sigma_** [array-like of shape (n_features, n_features)] estimated variance-covariance matrix of the weights

**scores_** [float] if computed, value of the objective function (to be maximized)

**intercept_** [float] Independent term in decision function. Set to 0.0 if `fit_intercept = False`.

**X offset_** [float] If `normalize=True`, offset subtracted for centering data to a zero mean.

**X scale_** [float] If `normalize=True`, parameter used to scale data to a unit standard deviation.

### Notes
For an example, see `examples/linear_model/plot_ard.py`.

### References
D. J. C. MacKay, Bayesian nonlinear modeling for the prediction competition, ASHRAE Transactions, 1994.

R. Salakhutdinov, Lecture notes on Statistical Machine Learning, http://www.utstat.toronto.edu/~rsalakhu/sta4273/notes/Lecture2.pdf#page=15 Their beta is our self.alpha_ Their alpha is our self.lambda_ ARD is a little different than the slide: only dimensions/features for which self.lambda_ < self.threshold_lambda are kept and the rest are discarded.

### Examples
```python
>>> from sklearn import linear_model
>>> clf = linear_model.ARDRegression()
>>> clf.fit([[0,0], [1, 1], [2, 2]], [0, 1, 2])
ARDRegression()
>>> clf.predict([[1, 1]])
array([1.])
```

### Methods

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<td><code>fit(X, y)</code></td>
<td>Fit the ARDRegression model according to the given training data and parameters.</td>
</tr>
<tr>
<td><code>get_params</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X[, return_std])</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination ( R^2 ) of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

```python
>>> fit (X, y)
Fit the ARDRegression model according to the given training data and parameters.
```
Iterative procedure to maximize the evidence

Parameters

X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values (integers). Will be cast to X’s dtype if necessary

Returns

self [returns an instance of self.]

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X, return_std=False)
Predict using the linear model.

In addition to the mean of the predictive distribution, also its standard deviation can be returned.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Samples.

return_std [bool, default=False] Whether to return the standard deviation of posterior prediction.

Returns

y_mean [array-like of shape (n_samples,)] Mean of predictive distribution of query points.

y_std [array-like of shape (n_samples,)] Standard deviation of predictive distribution of query points.

score (X, y, sample_weight=None)
Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( 1 - \frac{u}{v} \), where \( u \) is the residual sum of squares \( ((y_{true} - y_{pred}) ** 2).sum() \) and \( v \) is the total sum of squares \( ((y_{true} - y_{true.mean()}) ** 2).sum() \).

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,)] or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.
score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.linear_model.ARDRegression

- Automatic Relevance Determination Regression (ARD)

sklearn.linear_model.BayesianRidge

class sklearn.linear_model.BayesianRidge(*, n_iter=300, tol=0.001, alpha_1=1e-06, alpha_2=1e-06, lambda_1=1e-06, lambda_2=1e-06, alpha_init=None, lambda_init=None, compute_score=False, fit_intercept=True, normalize=False, copy_X=True, verbose=False)

Bayesian ridge regression.

Fit a Bayesian ridge model. See the Notes section for details on this implementation and the optimization of the regularization parameters lambda (precision of the weights) and alpha (precision of the noise).

Read more in the User Guide.

Parameters

n_iter [int, default=300] Maximum number of iterations. Should be greater than or equal to 1.

tol [float, default=1e-3] Stop the algorithm if w has converged.

alpha_1 [float, default=1e-6] Hyper-parameter : shape parameter for the Gamma distribution prior over the alpha parameter.

alpha_2 [float, default=1e-6] Hyper-parameter : inverse scale parameter (rate parameter) for the Gamma distribution prior over the alpha parameter.

lambda_1 [float, default=1e-6] Hyper-parameter : shape parameter for the Gamma distribution prior over the lambda parameter.

lambda_2 [float, default=1e-6] Hyper-parameter : inverse scale parameter (rate parameter) for the Gamma distribution prior over the lambda parameter.
alpha_init [float, default=None] Initial value for alpha (precision of the noise). If not set, alpha_init is 1/Var(y).

    New in version 0.22.

lambda_init [float, default=None] Initial value for lambda (precision of the weights). If not set, lambda_init is 1.

    New in version 0.22.

compute_score [bool, default=False] If True, compute the log marginal likelihood at each iteration of the optimization.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. The intercept is not treated as a probabilistic parameter and thus has no associated variance. If set to False, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

verbose [bool, default=False] Verbose mode when fitting the model.

Attributes

coef_ [array-like of shape (n_features,)] Coefficients of the regression model (mean of distribution)

intercept_ [float] Independent term in decision function. Set to 0.0 if fit_intercept = False.

alpha_ [float] Estimated precision of the noise.

lambda_ [float] Estimated precision of the weights.

sigma_ [array-like of shape (n_features, n_features)] Estimated variance-covariance matrix of the weights

scores_ [array-like of shape (n_iter_+1,)] If computed_score is True, value of the log marginal likelihood (to be maximized) at each iteration of the optimization. The array starts with the value of the log marginal likelihood obtained for the initial values of alpha and lambda and ends with the value obtained for the estimated alpha and lambda.

n_iter_ [int] The actual number of iterations to reach the stopping criterion.

X_offset_ [float] If normalize=True, offset subtracted for centering data to a zero mean.

X_scale_ [float] If normalize=True, parameter used to scale data to a unit standard deviation.
Notes

There exist several strategies to perform Bayesian ridge regression. This implementation is based on the algorithm described in Appendix A of (Tipping, 2001) where updates of the regularization parameters are done as suggested in (MacKay, 1992). Note that according to A New View of Automatic Relevance Determination (Wipf and Nagarajan, 2008) these update rules do not guarantee that the marginal likelihood is increasing between two consecutive iterations of the optimization.

References


Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.BayesianRidge()
>>> clf.fit([[0,0], [1, 1], [2, 2]], [0, 1, 2])
BayesianRidge()
>>> clf.predict ([[1, 1]])
array([1.])
```

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<td>set_params(**params)</td>
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**fit (X, y, sample_weight=None)**

Fit the model

Parameters

- **X** [ndarray of shape (n_samples, n_features)] Training data
- **y** [ndarray of shape (n_samples,)] Target values. Will be cast to X’s dtype if necessary
- **sample_weight** [ndarray of shape (n_samples,), default=None] Individual weights for each sample

Returns

- **self** [returns an instance of self.]

**get_params**(deep=True)

Get parameters for this estimator.

Parameters

- **deep** [True]
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**predict** (*X*, *return_std*=False)

Predict using the linear model.

In addition to the mean of the predictive distribution, also its standard deviation can be returned.

**Parameters**

*X* [{array-like, sparse matrix} of shape (n_samples, n_features)] Samples.

*return_std* [bool, default=False] Whether to return the standard deviation of posterior prediction.

**Returns**

*y_mean* [array-like of shape (n_samples,)] Mean of predictive distribution of query points.

*y_std* [array-like of shape (n_samples,)] Standard deviation of predictive distribution of query points.

**score** (*X*, *y*, *sample_weight*=None)

Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \( (1 - \frac{u}{v}) \), where \( u \) is the residual sum of squares \((y_{true} - y_{pred})**2).sum()\) and \( v \) is the total sum of squares \((y_{true} - y_{true}.mean())**2).sum()\). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

*y* [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \( X \).

*sample_weight* [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

*score* [float] \( R^2 \) of self.predict(*X*) wrt. \( y \).

**Notes**

The \( R^2 \) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**
**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

Examples using sklearn.linear_model.BayesianRidge

- Feature agglomeration vs. univariate selection
- Curve Fitting with Bayesian Ridge Regression
- Bayesian Ridge Regression
- Imputing missing values with variants of IterativeImputer

7.22.5 Multi-task linear regressors with variable selection

These estimators fit multiple regression problems (or tasks) jointly, while inducing sparse coefficients. While the inferred coefficients may differ between the tasks, they are constrained to agree on the features that are selected (non-zero coefficients).

```
from sklearn.linear_model import MultiTaskElasticNet

MultiTaskElasticNet(alpha=1.0, *, l1_ratio=0.5, fit_intercept=True, normalize=False, copy_X=True, max_iter=1000, tol=0.0001, warm_start=False, random_state=None, selection='cyclic')
```

Multi-task ElasticNet model trained with L1/L2 mixed-norm as regularizer.

The optimization objective for MultiTaskElasticNet is:

\[
\frac{1}{2n_{\text{samples}}} ||Y - XW||_{\text{Fro}}^2 + \alpha * l1_{\text{ratio}} * ||W||_{21} + 0.5 * \alpha * (1 - l1_{\text{ratio}}) * ||W||_{\text{Fro}}^2
\]

Where:

\[
||W||_{21} = \text{sum}_i \text{sqrt}(\text{sum}_j W_{ij}^2)
\]

i.e. the sum of norms of each row.

Read more in the User Guide.

Parameters

7.22. sklearn.linear_model: Linear Models
alpha [float, default=1.0] Constant that multiplies the L1/L2 term. Defaults to 1.0.

l1_ratio [float, default=0.5] The ElasticNet mixing parameter, with 0 < l1_ratio <= 1. For l1_ratio = 1 the penalty is an L1/L2 penalty. For l1_ratio = 0 it is an L2 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1/L2 and L2.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to False, no intercept will be used in calculations (i.e. data is expected to be centered).

normalize [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

max_iter [int, default=1000] The maximum number of iterations.

tol [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == 'random'. Pass an int for reproduducible output across multiple function calls. See Glossary.

selection [{‘cyclic’, ‘random’}, default='cyclic'] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

intercept_ [ndarray of shape (n_tasks,)] Independent term in decision function.

ccoef_ [ndarray of shape (n_features)] Parameter vector (W in the cost function formula). If a 1D y is passed in at fit (non multi-task usage), coef_ is then a 1D array. Note that coef_ stores the transpose of W, W.T.

n_iter_ [int] Number of iterations run by the coordinate descent solver to reach the specified tolerance.

dual_gap_ [float] The dual gaps at the end of the optimization.

eps_ [float] The tolerance scaled scaled by the variance of the target y.

sparse_coef_ [sparse matrix of shape (n_features,) or (n_tasks, n_features)] Sparse representation of the fitted coef_.

See also:

MultiTaskElasticNetCV Multi-task L1/L2 ElasticNet with built-in cross-validation.

ElasticNet

MultiTaskLasso
Notes

The algorithm used to fit the model is coordinate descent.

To avoid unnecessary memory duplication the X and y arguments of the fit method should be directly passed as Fortran-contiguous numpy arrays.

Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.MultiTaskElasticNet(alpha=0.1)
>>> clf.fit([[0,0], [1, 1], [2, 2]], [[0, 0], [1, 1], [2, 2]])
MultiTaskElasticNet(alpha=0.1)
>>> print(clf.coef_)
[[0.45663524 0.45612256]
 [0.45663524 0.45612256]]
>>> print(clf.intercept_)
[0.0872422 0.0872422]
```

Methods

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<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>path(*args, **kwargs)</code></td>
<td>Compute elastic net path with coordinate descent.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

**fit (X, y)**

Fit MultiTaskElasticNet model with coordinate descent

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Data.
- **y** [ndarray of shape (n_samples, n_tasks)] Target. Will be cast to X’s dtype if necessary.

**Notes**

Coordinate descent is an algorithm that considers each column of data at a time hence it will automatically convert the X input as a Fortran-contiguous numpy array if necessary.

To avoid memory re-allocation it is advised to allocate the initial data in memory directly using that format.

**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
\frac{1}{2 n_{\text{samples}}} \|y - Xw\|^2_2 + \alpha \cdot l1_{\text{ratio}} \|w\|_1 + 0.5 \cdot \alpha \cdot (1 - l1_{\text{ratio}}) \|w\|^2_2
\]

For multi-output tasks it is:

\[
\frac{1}{2 n_{\text{samples}}} \|Y - XW\|^2_{\text{Fro}} + \alpha \cdot l1_{\text{ratio}} \|W\|_{21} + 0.5 \cdot \alpha \cdot (1 - l1_{\text{ratio}}) \|W\|^2_{\text{Fro}}
\]

Where:

\[
\|W\|_{21} = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

- **y** ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values.

- **l1_ratio** (float, default=0.5) Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.

- **eps** (float, default=1e-3) Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

- **n_alphas** (int, default=100) Number of alphas along the regularization path.

- **alphas** (ndarray, default=None) List of alphas where to compute the models. If None alphas are set automatically.

- **precompute** (‘auto’, bool or array-like of shape (n_features, n_features), default=’auto’) Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

- **Xy** (array-like of shape (n_features,) or (n_features, n_outputs), default=None) Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is pre-computed.

- **copy_X** (bool, default=True) If True, X will be copied; else, it may be overwritten.

- **coef_init** (ndarray of shape (n_features,), default=None) The initial values of the coefficients.

- **verbose** (bool or int, default=False) Amount of verbosity.

- **return_n_iter** (bool, default=False) Whether to return the number of iterations or not.
positive [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).

check_input [bool, default=True] If set to False, the input validation checks are skipped (including the Gram matrix when provided). It is assumed that they are handled by the caller.

**params [kwargs] Keyword arguments passed to the coordinate descent solver.

Returns

alphas [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.

coaef [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.

dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

n_iters [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha. (Is returned when return_n_iter is set to True).

See also:

MultiTaskElasticNet
MultiTaskElasticNetCV
ElasticNet
ElasticNetCV

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

predict (X)

Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape (n_samples,)] Returns predicted values.

score (X, y, sample_weight=None)

Return the coefficient of determination \( R^2 \) of the prediction.

The coefficient \( R^2 \) is defined as \((1 - u/v)\), where \( u \) is the residual sum of squares \( ((y_true - y_pred)^2) \).sum() and \( v \) is the total sum of squares \( ((y_true - y_true.mean())^2) \).sum(). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape
(n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

property sparse_coef_
Sparse representation of the fitted coef_.

sklearn.linear_model.MultiTaskElasticNetCV

class sklearn.linear_model.MultiTaskElasticNetCV(*, l1_ratio=0.5, eps=0.001, n_alphas=100, alphas=None, fit_intercept=True, normalize=False, max_iter=1000, tol=0.0001, cv=None, copy_X=True, verbose=0, n_jobs=None, random_state=None, selection='cyclic')

Multi-task L1/L2 ElasticNet with built-in cross-validation.

See glossary entry for cross-validation estimator.

The optimization objective for MultiTaskElasticNet is:

\[
\frac{1}{(2 \times n_{\text{samples}})} \times | |Y - XW||_{\text{Fro}}^2 + \text{alpha} \times \text{l1_ratio} \times | |W||_{21} + 0.5 \times \text{alpha} \times (1 - \text{l1_ratio}) \times | |W||_{\text{Fro}}^2
\]

Where:

\[
| |W||_{21} = \sum_i \sqrt{\sum_j w_{ij}^2}
\]
i.e. the sum of norm of each row.

Read more in the User Guide.

New in version 0.15.

Parameters

- **l1_ratio** [float or list of float, default=0.5] The ElasticNet mixing parameter, with 0 < l1_ratio <= 1. For l1_ratio = 1 the penalty is an L1/L2 penalty. For l1_ratio = 0 it is an L2 penalty. For 0 < l1_ratio < 1, the penalty is a combination of L1/L2 and L2. This parameter can be a list, in which case the different values are tested by cross-validation and the one giving the best prediction score is used. Note that a good choice of list of values for l1_ratio is often to put more values close to 1 (i.e. Lasso) and less close to 0 (i.e. Ridge), as in [.1, .5, .7, .9, .95, .99, 1]

- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

- **n_alphas** [int, default=100] Number of alphas along the regularization path.

- **alphas** [array-like, default=None] List of alphas where to compute the models. If not provided, set automatically.

- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).

- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the L2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=True.

- **max_iter** [int, default=1000] The maximum number of iterations.

- **tol** [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.

- **cv** [int, cross-validation generator or iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross-validation,
  - int, to specify the number of folds.
  - **CV splitter**,
  - An iterable yielding (train, test) splits as arrays of indices.

  For int/None inputs, KFold is used.

  Refer User Guide for the various cross-validation strategies that can be used here.

  Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

- **verbose** [bool or int, default=0] Amount of verbosity.

- **n_jobs** [int, default=None] Number of CPUs to use during the cross validation. Note that this is used only if multiple values for l1_ratio are given. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.
random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == ‘random’. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [‘cyclic’, ‘random’], default=’cyclic’ If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

intercept_ [ndarray of shape (n_tasks,)] Independent term in decision function.

coeff_ [ndarray of shape (n_tasks, n_features)] Parameter vector (W in the cost function formula). Note that coeff_ stores the transpose of W, W.T.

alpha_ [float] The amount of penalization chosen by cross validation.

mse_path_ [ndarray of shape (n_alphas, n_folds) or (n_l1_ratio, n_alphas, n_folds)] Mean square error for the test set on each fold, varying alpha.

alphas_ [ndarray of shape (n_alphas,) or (n_l1_ratio, n_alphas)] The grid of alphas used for fitting, for each l1_ratio.

l1_ratio_ [float] Best l1_ratio obtained by cross-validation.

n_iter_ [int] Number of iterations run by the coordinate descent solver to reach the specified tolerance for the optimal alpha.

dual_gap_ [float] The dual gap at the end of the optimization for the optimal alpha.

See also:

MultiTaskElasticNet
ElasticNetCV
MultiTaskLassoCV

Notes

The algorithm used to fit the model is coordinate descent.

To avoid unnecessary memory duplication the X and y arguments of the fit method should be directly passed as Fortran-contiguous numpy arrays.

Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.MultiTaskElasticNetCV(cv=3)
>>> clf.fit([[0, 1], [1, 2]], ...
        [[0, 1], [1, 2]])
MultiTaskElasticNetCV(cv=3)
>>> print(clf.coef_)
[[0.52875032 0.46958558]
 [0.52875032 0.46958558]]
>>> print(clf.intercept_)
[0.00166409 0.00166409]
```
Methods

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</tr>
<tr>
<td>predict(X)</td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit(X, y)**

Fit linear model with coordinate descent.

Fit is on grid of alphas and best alpha estimated by cross-validation.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output, X can be sparse.
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values.

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**static path(*args, **kwargs)**

Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

$$
\frac{1}{(2 \times n_{\text{samples}})} \times ||y - Xw||^2_2 \\
+ \alpha \times l1\_ratio \times ||w||_1 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||w||^2_2
$$

For multi-output tasks it is:

$$
(\frac{1}{(2 \times n_{\text{samples}})}) \times ||Y - XW||^{\text{Fro}}_2 \\
+ \alpha \times l1\_ratio \times ||W||_21 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||W||^{\text{Fro}}2
$$

Where:

$$||W||_21 = \sum_i \sqrt{\sum_j w_{ij}^2}$$

i.e. the sum of norm of each row.

Read more in the User Guide.

**Parameters**
X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

y [{array-like, sparse matrix} of shape (n_samples,) or (n_samples, n_outputs)] Target values.

l1_ratio [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.

eps [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

n_alphas [int, default=100] Number of alphas along the regularization path.

alphas [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.

precompute ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

Xy [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is precomputed.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

coeff_init [ndarray of shape (n_features, ), default=None] The initial values of the coefficients.

verbose [bool or int, default=False] Amount of verbosity.

return_n_iter [bool, default=False] Whether to return the number of iterations or not.

positive [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).

check_input [bool, default=True] If set to False, the input validation checks are skipped (including the Gram matrix when provided). It is assumed that they are handled by the caller.

**params [kwargs] Keyword arguments passed to the coordinate descent solver.

Returns

alphas [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.

coeffs [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.

dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

n_iters [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha. (Is returned when return_n_iter is set to True).

See also:

MultiTaskElasticNet

MultiTaskElasticNetCV
ElasticNet
ElasticNetCV

Notes
For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

predict \((X)\)
Predict using the linear model.

Parameters
\(X\) [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns
\(C\) [array, shape (n_samples,)] Returns predicted values.

score \((X, y, \text{sample_weight=None})\)
Return the coefficient of determination \(R^2\) of the prediction.

The coefficient \(R^2\) is defined as \((1 - \frac{u}{v})\), where \(u\) is the residual sum of squares \(((y_{true} - y_{pred})**2).sum()\) and \(v\) is the total sum of squares \(((y_{true} - y_{true}.mean())**2).sum()\). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \(y\), disregarding the input features, would get a \(R^2\) score of 0.0.

Parameters
\(X\) [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

\(y\) [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \(X\).

\(\text{sample_weight}\) [array-like of shape (n_samples,), default=None] Sample weights.

Returns
\(score\) [float] \(R^2\) of self.predict \((X)\) wrt. \(y\).

Notes
The \(R^2\) score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of \(r2\_score\). This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<component>__<parameter>\) so that it’s possible to update each component of a nested object.

Parameters
**params [dict] Estimator parameters.

Returns
self [estimator instance] Estimator instance.
Multi-task Lasso model trained with L1/L2 mixed-norm as regularizer.

The optimization objective for Lasso is:

$\frac{1}{(2 \times n_{\text{samples}})} \times ||Y - XW||_{2\text{Fro}}^2 + \alpha \times ||W||_{21}$

Where:

$||W||_{21} = \sum_i \sqrt{\sum_j w_{ij}^2}$

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

- **alpha** [float, default=1.0] Constant that multiplies the L1/L2 term. Defaults to 1.0.
- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).
- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.
- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
- **max_iter** [int, default=1000] The maximum number of iterations.
- **tol** [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.
- **warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.
- **random_state** [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == 'random'. Pass an int for reproducible output across multiple function calls. See Glossary.
- **selection** [{'cyclic', 'random'}, default='cyclic'] If set to 'random', a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to 'random') often leads to significantly faster convergence especially when tol is higher than 1e-4

Attributes

- **coef_** [ndarray of shape (n_tasks, n_features)] Parameter vector (W in the cost function formula). Note that coef_ stores the transpose of W, W.T.
- **intercept_** [ndarray of shape (n_tasks,)] Independent term in decision function.
- **n_iter_** [int] Number of iterations run by the coordinate descent solver to reach the specified tolerance.
**dual_gap_** [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

**eps_** [float] The tolerance scaled scaled by the variance of the target y.

**sparse_coef_** [sparse matrix of shape (n_features,) or (n_tasks, n_features)] Sparse representation of the fitted coef_.

See also:

**MultiTaskLasso** Multi-task L1/L2 Lasso with built-in cross-validation.

**Lasso**

**MultiTaskElasticNet**

**Notes**

The algorithm used to fit the model is coordinate descent.

To avoid unnecessary memory duplication the X and y arguments of the fit method should be directly passed as Fortran-contiguous numpy arrays.

**Examples**

```python
>>> from sklearn import linear_model
>>> clf = linear_model.MultiTaskLasso(alpha=0.1)
>>> clf.fit([[0, 1], [1, 2], [2, 4]], [[0, 0], [1, 1], [2, 3]])
MultiTaskLasso(alpha=0.1)
>>> print(clf.coef_)
[[0. 0.60809415]
 [0. 0.94592424]]
>>> print(clf.intercept_)
[-0.41888636 -0.87382323]
```

**Methods**

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**fit (X, y)**

Fit MultiTaskElasticNet model with coordinate descent

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Data.
- **y** [ndarray of shape (n_samples, n_tasks)] Target. Will be cast to X’s dtype if necessary.
Notes

Coordinate descent is an algorithm that considers each column of data at a time hence it will automatically convert the X input as a Fortran-contiguous numpy array if necessary.

To avoid memory re-allocation it is advised to allocate the initial data in memory directly using that format.

get_params (deep=True)

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

static path (*args, **kwargs)

Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
\frac{1}{(2 \times n\_samples)} \times ||y - Xw||^2_2 \\
+ \alpha \times l1\_ratio \times ||w||_1 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||w||^2_2
\]

For multi-output tasks it is:

\[
(1 / (2 \times n\_samples)) \times ||Y - XW||^\text{Fro}_2 \\
+ \alpha \times l1\_ratio \times ||W||_21 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||W||_\text{Fro}^2
\]

Where:

\[||W||_21 = \sum_i \sqrt{\sum_j w_{ij}^2}\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

y [{array-like, sparse matrix} of shape (n_samples,) or (n_samples, n_outputs)] Target values.

l1_ratio [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.

eps [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.

n_alphas [int, default=100] Number of alphas along the regularization path.

alphas [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.
precompute ['auto', bool or array-like of shape (n_features, n_features), default='auto']
Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let
us decide. The Gram matrix can also be passed as argument.

Xy [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy =
np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is pre-
computed.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.
coef_init [ndarray of shape (n_features,), default=None] The initial values of the coeffi-
cients.
verbose [bool or int, default=False] Amount of verbosity.
return_n_iter [bool, default=False] Whether to return the number of iterations or not.
positive [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed
when y.ndim == 1).
check_input [bool, default=True] If set to False, the input validation checks are skipped
(including the Gram matrix when provided). It is assumed that they are handled by the
caller.

**params [kwargs] Keyword arguments passed to the coordinate descent solver.

Returns

alphas [ndarray of shape (n_alphas,)] The alphas along the path where models are com-
puted.

coeffs [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coeffi-
cients along the path.
dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for
each alpha.
n_iters [list of int] The number of iterations taken by the coordinate descent optimizer to
reach the specified tolerance for each alpha. (Is returned when return_n_iter is set
to True).

See also:

MultiTaskElasticNet
MultiTaskElasticNetCV
ElasticNet
ElasticNetCV

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

predict (X)
Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns
C [array, shape (n_samples,)] Returns predicted values.

`score(X, y, sample_weight=None)`

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as \(1 - \frac{u}{v}\), where \(u\) is the residual sum of squares \(((y_{true} - y_{pred}) \times 2).sum()\) and \(v\) is the total sum of squares \(((y_{true} - y_{true}.mean()) \times 2).sum()\). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for $X$.

- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **score** [float] $R^2$ of self.predict(X) wrt. $y$.

Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params(**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- ****params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

`property sparse_coef_`

Sparse representation of the fitted coef_.

Examples using `sklearn.linear_model.MultiTaskLasso`

- Joint feature selection with multi-task Lasso
Multi-task Lasso model trained with L1/L2 mixed-norm as regularizer.

See glossary entry for cross-validation estimator.

The optimization objective for MultiTaskLasso is:

\[
\frac{1}{2n_samples} \|Y - XW\|_Fro_2 + \alpha \|W\|_21
\]

Where:

\[
\|W\|_21 = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the User Guide.

New in version 0.15.

Parameters

- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that \( \alpha_{\text{min}} / \alpha_{\text{max}} = 1e-3 \).
- **n_alphas** [int, default=100] Number of alphas along the regularization path.
- **alphas** [array-like, default=None] List of alphas where to compute the models. If not provided, set automatically.
- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be centered).
- **normalize** [bool, default=False] This parameter is ignored when fit_intercept is set to False. If True, the regressors X will be normalized before regression by subtracting the mean and dividing by the l2-norm. If you wish to standardize, please use StandardScaler before calling fit on an estimator with normalize=False.
- **max_iter** [int, default=1000] The maximum number of iterations.
- **tol** [float, default=1e-4] The tolerance for the optimization: if the updates are smaller than tol, the optimization code checks the dual gap for optimality and continues until it is smaller than tol.
- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.
- **cv** [int, cross-validation generator or iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross-validation,
  - int, to specify the number of folds.
  - CV splitter,
  - An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, KFold is used. Refer User Guide for the various cross-validation strategies that can be used here.
Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

verbose [bool or int, default=False] Amount of verbosity.

n_jobs [int, default=None] Number of CPUs to use during the cross validation. Note that this is used only if multiple values for l1_ratio are given. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

random_state [int, RandomState instance, default=None] The seed of the pseudo random number generator that selects a random feature to update. Used when selection == ‘random’. Pass an int for reproducible output across multiple function calls. See Glossary.

selection [{‘cyclic’, ‘random’}, default='cyclic'] If set to ‘random’, a random coefficient is updated every iteration rather than looping over features sequentially by default. This (setting to ‘random’) often leads to significantly faster convergence especially when tol is higher than 1e-4.

Attributes

intercept_ [ndarray of shape (n_tasks,)] Independent term in decision function.

coef_ [ndarray of shape (n_tasks, n_features)] Parameter vector (W in the cost function formula). Note that coef_ stores the transpose of W, W.T.

alpha_ [float] The amount of penalization chosen by cross validation.

mse_path_ [ndarray of shape (n_alphas, n_folds)] Mean square error for the test set on each fold, varying alpha.

alphas_ [ndarray of shape (n_alphas,)] The grid of alphas used for fitting.

n_iter_ [int] Number of iterations run by the coordinate descent solver to reach the specified tolerance for the optimal alpha.

dual_gap_ [float] The dual gap at the end of the optimization for the optimal alpha.

See also:

MultiTaskElasticNet
ElasticNetCV
MultiTaskElasticNetCV

Notes

The algorithm used to fit the model is coordinate descent.

To avoid unnecessary memory duplication the X and y arguments of the fit method should be directly passed as Fortran-contiguous numpy arrays.
Examples

```python
>>> from sklearn.linear_model import MultiTaskLassoCV
>>> from sklearn.datasets import make_regression
>>> from sklearn.metrics import r2_score

>>> X, y = make_regression(n_targets=2, noise=4, random_state=0)
>>> reg = MultiTaskLassoCV(cv=5, random_state=0).fit(X, y)
>>> r2_score(y, reg.predict(X))
0.9994...
>>> reg.alpha_
0.5713...
>>> reg.predict(X[:1,])
array([[153.7971..., 94.9015...]])
```

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<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination R^2 of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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**`fit`** *(X, y)*

Fit linear model with coordinate descent.

Fit is on grid of alphas and best alpha estimated by cross-validation.

**Parameters**

- **X** *(array-like, sparse matrix) of shape (n_samples, n_features) [*]* Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output, X can be sparse.
- **y** *(array-like of shape (n_samples,)) or (n_samples, n_targets) [*]* Target values.

**`get_params`** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** *[bool, default=True] [*]* If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** *[dict] Parameter names mapped to their values.*

**`static path`** *(*args, **kwargs)*

Compute Lasso path with coordinate descent

The Lasso optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
\frac{1}{(2 + n_{samples})} \times ||y - Xw||^2 + \alpha \times ||w||_1
\]
For multi-output tasks it is:

\[
\frac{1}{(2 \times n_{\text{samples}})} \times ||Y - XW||_{}^2_{\text{Fro}} + \alpha \times ||W||_{}_{2,1}
\]

Where:

\[
||W||_{}_{2,1} = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the *User Guide*.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If \(y\) is mono-output then \(X\) can be sparse.
- **y** ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values
- **eps** [float, default=1e-3] Length of the path. \(\text{eps}=1e-3\) means that \(\alpha_{\text{max}} / \alpha_{\text{min}} = 1e-3\)
- **n_alphas** [int, default=100] Number of alphas along the regularization path
- **alphas** [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically
- **precompute** ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.
- **Xy** [array-like of shape (n_features,) or (n_features, n_outputs), default=None] \(Xy = \text{np.dot}(X.T, y)\) that can be precomputed. It is useful only when the Gram matrix is precomputed.
- **copy_X** [bool, default=True] If True, \(X\) will be copied; else, it may be overwritten.
- **coef_init** [ndarray of shape (n_features, ), default=None] The initial values of the coefficients.
- **verbose** [bool or int, default=False] Amount of verbosity.
- **return_n_iter** [bool, default=False] whether to return the number of iterations or not.
- **positive** [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when \(y\).ndim == 1).
- ****params** [kwargs] keyword arguments passed to the coordinate descent solver.

**Returns**

- **alphas** [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.
- **coefs** [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.
- **dual_gaps** [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.
- **n_iters** [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha.
See also:

- `lars_path`
- `Lasso`
- `LassoLars`
- `LassoCV`
- `LassoLarsCV`
- `sklearn.decomposition.sparse_encode`

Notes

For an example, see `examples/linear_model/plot_lasso_coordinate_descent_path.py`.

To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a Fortran-contiguous numpy array.

Note that in certain cases, the Lars solver may be significantly faster to implement this functionality. In particular, linear interpolation can be used to retrieve model coefficients between the values output by `lars_path`.

Examples

Comparing `lasso_path` and `lars_path` with interpolation:

```python
>>> X = np.array([[1, 2, 3.1], [2.3, 5.4, 4.3]]).T
>>> y = np.array([1, 2, 3.1])
>>> # Use lasso_path to compute a coefficient path
>>> _, coef_path, _ = lasso_path(X, y, alphas=[5., 1., .5])
>>> print(coef_path)
[[ 0.          0.         0.46874778]
 [ 0.21590478  0.4425765  0.23689075]]

>>> # Now use lars_path and 1D linear interpolation to compute the
>>> # same path
>>> from sklearn.linear_model import lars_path
>>> alphas, active, coef_path_lars = lars_path(X, y, method='lasso')
>>> from scipy import interpolate
>>> coef_path_continuous = interpolate.interp1d(alphas[::-1],
...                                              coef_path_lars[:, ::-1])
>>> print(coef_path_continuous([5., 1., .5]))
[[ 0.          0.         0.46915237]
 [ 0.2159048  0.4425765  0.23668876]]
```

`predict (X)`

Predict using the linear model.

**Parameters**

- `X` [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- `C` [array, shape (n_samples,)] Returns predicted values.
score \((X, y, \text{sample\_weight}=\text{None})\)

Return the coefficient of determination \(R^2\) of the prediction.

The coefficient \(R^2\) is defined as \(1 - \frac{u}{v}\), where \(u\) is the residual sum of squares \((y_{\text{true}} - y_{\text{pred}})^2\).sum() and \(v\) is the total sum of squares \((y_{\text{true}} - y_{\text{true}.\text{mean}})^2\).sum().

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \(y\), disregarding the input features, would get a \(R^2\) score of 0.0.

Parameters

\(X\) [array-like of shape \((n\_samples, n\_features)\)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape \((n\_samples, n\_samples\_fitted)\), where \(n\_samples\_fitted\) is the number of samples used in the fitting for the estimator.

\(y\) [array-like of shape \((n\_samples,)\) or \((n\_samples, n\_outputs)\)] True values for \(X\).

\(\text{sample\_weight}\) [array-like of shape \((n\_samples,)\), default=None] Sample weights.

Returns

\(score\) [float] \(R^2\) of self.predict \((X)\) wrt. \(y\).

Notes

The \(R^2\) score used when calling score on a regressor uses \(\text{multioutput=}'\text{uniform\_average}'\) from version 0.23 to keep consistent with default value of \(r2\_score\). This influences the score method of all the multioutput regressors (except for \(\text{MultiOutputRegressor}\)).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \(\text{Pipeline}\)). The latter have parameters of the form \(<\text{component}>\_\_<\text{parameter}>\) so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.22.6 Outlier-robust regressors

Any estimator using the Huber loss would also be robust to outliers, e.g. \(\text{SGDRegressor}\) with \(\text{loss=}'\text{huber}'\).

- linear_model.HuberRegressor(*[, epsilon, ...]) Linear regression model that is robust to outliers.
- linear_model.RANSACRegressor(*[, ...]) RANSAC (RANdom SAmple Consensus) algorithm.
The Huber Regressor optimizes the squared loss for the samples where \(|(y - X'w) / sigma| < \epsilon\) and the absolute loss for the samples where \(|(y - X'w) / sigma| > \epsilon\), where \(w\) and \(sigma\) are parameters to be optimized. The parameter sigma makes sure that if \(y\) is scaled up or down by a certain factor, one does not need to rescale epsilon to achieve the same robustness. Note that this does not take into account the fact that the different features of \(X\) may be of different scales.

This makes sure that the loss function is not heavily influenced by the outliers while not completely ignoring their effect.

Read more in the User Guide

New in version 0.18.

Parameters

**epsilon** [float, greater than 1.0, default=1.35] The parameter epsilon controls the number of samples that should be classified as outliers. The smaller the epsilon, the more robust it is to outliers.

**max_iter** [int, default=100] Maximum number of iterations that *scipy.optimize.minimize(method="L-BFGS-B")* should run for.

**alpha** [float, default=0.0001] Regularization parameter.

**warm_start** [bool, default=False] This is useful if the stored attributes of a previously used model has to be reused. If set to False, then the coefficients will be rewritten for every call to fit. See the Glossary.

**fit_intercept** [bool, default=True] Whether or not to fit the intercept. This can be set to False if the data is already centered around the origin.

**tol** [float, default=1e-05] The iteration will stop when \(\max\{|{proj g_i | i = 1, \ldots, n|} <= \text{tol}\} \) where \(pg_i\) is the i-th component of the projected gradient.

Attributes

**coef_** [array, shape (n_features,)] Features got by optimizing the Huber loss.

**intercept_** [float] Bias.

**scale_** [float] The value by which \(|y - X'w - c|\) is scaled down.

**n_iter_** [int] Number of iterations that *scipy.optimize.minimize(method="L-BFGS-B")* has run for.

Changed in version 0.20: In SciPy <= 1.0.0 the number of lbfgs iterations may exceed max_iter. n_iter_ will now report at most max_iter.

**outliers_** [array, shape (n_samples,)] A boolean mask which is set to True where the samples are identified as outliers.
References

[1], [2]

Examples

```python
>>> import numpy as np
>>> from sklearn.linear_model import HuberRegressor, LinearRegression
>>> from sklearn.datasets import make_regression

>>> rng = np.random.RandomState(0)

>>> X, y, coef = make_regression(...
...     n_samples=200, n_features=2, noise=4.0, coef=True, random_state=0)
>>> X[:4] = rng.uniform(10, 20, (4, 2))
>>> y[:4] = rng.uniform(10, 20, 4)
>>> huber = HuberRegressor().fit(X, y)
>>> huber.score(X, y)
-7.284...
>>> huber.predict(X[:1,])
array([806.7200...])
>>> linear = LinearRegression().fit(X, y)
>>> print("True coefficients:", coef)
True coefficients: [20.4923... 34.1698...]
>>> print("Huber coefficients:", huber.coef_)
Huber coefficients: [17.7906... 31.0106...]
>>> print("Linear Regression coefficients:", linear.coef_)
Linear Regression coefficients: [-1.9221... 7.0226...]
```

Methods

```python
fit(X, y[, sample_weight])
    Fit the model according to the given training data.

get_params([deep])
    Get parameters for this estimator.

predict(X)
    Predict using the linear model.

score(X, y[, sample_weight])
    Return the coefficient of determination \( R^2 \) of the prediction.

set_params(**params)
    Set the parameters of this estimator.
```

**fit** *(X, y, sample_weight=None)*

Fit the model according to the given training data.

**Parameters**

- **X** [array-like, shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like, shape (n_samples,)] Target vector relative to X.
- **sample_weight** [array-like, shape (n_samples,)] Weight given to each sample.

**Returns**

- **self** [object]

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool] Whether to also return parameters of the base estimator if the estimator has a base estimator.
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Predict using the linear model.

Parameters

X [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

Returns

C [array, shape (n_samples,)] Returns predicted values.

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $\sum((y_{true} - y_{pred})**2)$ and $v$ is the total sum of squares $\sum((y_{true} - y_{true.mean})**2)$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict (X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of $r2_score$. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.linear_model.HuberRegressor`

- HuberRegressor vs Ridge on dataset with strong outliers
- Robust linear estimator fitting

`sklearn.linear_model.RANSACRegressor` class

```python
class sklearn.linear_model.RANSACRegressor(base_estimator=None, *, min_samples=None, residual_threshold=None, is_data_valid=None, is_model_valid=None, max_trials=100, max_skips=inf, stop_n_inliers=inf, stop_score=inf, stop_probability=0.99, loss='absolute_loss', random_state=None)
```

RANSAC (RANdom SAmple Consensus) algorithm.

RANSAC is an iterative algorithm for the robust estimation of parameters from a subset of inliers from the complete data set.

Read more in the User Guide.

**Parameters**

- **base_estimator** [object, default=None] Base estimator object which implements the following methods:
  - `fit(X, y)`: Fit model to given training data and target values.
  - `score(X, y)`: Returns the mean accuracy on the given test data, which is used for the stop criterion defined by `stop_score`. Additionally, the score is used to decide which of two equally large consensus sets is chosen as the better one.
  - `predict(X)`: Returns predicted values using the linear model, which is used to compute residual error using loss function.

  If `base_estimator` is None, then `LinearRegression` is used for target values of dtype float.

  Note that the current implementation only supports regression estimators.

- **min_samples** [int (>= 1) or float ([0, 1]), default=None] Minimum number of samples chosen randomly from original data. Treated as an absolute number of samples for `min_samples` >= 1, treated as a relative number `ceil(min_samples * X.shape[0])` for `min_samples` < 1. This is typically chosen as the minimal number of samples necessary to estimate the given `base_estimator`. By default a sklearn.linear_model.LinearRegression() estimator is assumed and `min_samples` is chosen as `X.shape[1] + 1`.

- **residual_threshold** [float, default=None] Maximum residual for a data sample to be classified as an inlier. By default the threshold is chosen as the MAD (median absolute deviation) of the target values y.

- **is_data_valid** [callable, default=None] This function is called with the randomly selected data before the model is fitted to it: `is_data_valid(X, y)`. If its return value is False the current randomly chosen sub-sample is skipped.

- **is_model_valid** [callable, default=None] This function is called with the estimated model and the randomly selected data: `is_model_valid(model, X, y)`. If its return value is False the current randomly chosen sub-sample is skipped. Rejecting samples with this
function is computationally costlier than with is_data_valid. is_model_valid should therefore only be used if the estimated model is needed for making the rejection decision.

**max_trials** [int, default=100] Maximum number of iterations for random sample selection.

**max_skips** [int, default=np.inf] Maximum number of iterations that can be skipped due to finding zero inliers or invalid data defined by is_data_valid or invalid models defined by is_model_valid.

New in version 0.19.

**stop_n_inliers** [int, default=np.inf] Stop iteration if at least this number of inliers are found.

**stop_score** [float, default=np.inf] Stop iteration if score is greater equal than this threshold.

**stop_probability** [float in range [0, 1], default=0.99] RANSAC iteration stops if at least one outlier-free set of the training data is sampled in RANSAC. This requires to generate at least N samples (iterations):

\[
N \geq \log(1 - \text{probability}) / \log(1 - e^{-m})
\]

where the probability (confidence) is typically set to high value such as 0.99 (the default) and e is the current fraction of inliers w.r.t. the total number of samples.

**loss** [string, callable, default='absolute_loss'] String inputs, “absolute_loss” and “squared_loss” are supported which find the absolute loss and squared loss per sample respectively.

If loss is a callable, then it should be a function that takes two arrays as inputs, the true and predicted value and returns a 1-D array with the i-th value of the array corresponding to the loss on \(X[i]\).

If the loss on a sample is greater than the residual_threshold, then this sample is classified as an outlier.

New in version 0.18.

**random_state** [int, RandomState instance, default=None] The generator used to initialize the centers. Pass an int for reproducible output across multiple function calls. See Glossary.

**Attributes**

**estimator_** [object] Best fitted model (copy of the base_estimator object).

**n_trials_** [int] Number of random selection trials until one of the stop criteria is met. It is always \(<=\) max_trials.

**inlier_mask_** [bool array of shape [n_samples]] Boolean mask of inliers classified as True.

**n_skips_no_inliers_** [int] Number of iterations skipped due to finding zero inliers.

New in version 0.19.

**n_skips_invalid_data_** [int] Number of iterations skipped due to invalid data defined by is_data_valid.

New in version 0.19.

**n_skips_invalid_model_** [int] Number of iterations skipped due to an invalid model defined by is_model_valid.

New in version 0.19.
References

[1], [2], [3]

Examples

```python
>>> from sklearn.linear_model import RANSACRegressor
>>> from sklearn.datasets import make_regression

X, y = make_regression(...
    n_samples=200, n_features=2, noise=4.0, random_state=0)

reg = RANSACRegressor(random_state=0).fit(X, y)
reg.score(X, y)
0.9885...
reg.predict(X[:1,])
array([-31.9417...])
```

Methods

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<th>Method</th>
<th>Description</th>
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<tr>
<td>fit(X, y[, sample_weight])</td>
<td>Fit estimator using RANSAC algorithm.</td>
</tr>
<tr>
<td>get_params(deep)</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict using the estimated model.</td>
</tr>
<tr>
<td>score(X, y)</td>
<td>Returns the score of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit** (X, y, sample_weight=None)

Fit estimator using RANSAC algorithm.

Parameters

- **X** [array-like or sparse matrix, shape [n_samples, n_features]] Training data.
- **y** [array-like of shape (n_samples,) or (n_samples, n_targets)] Target values.
- **sample_weight** [array-like of shape (n_samples,), default=None] Individual weights for each sample raises error if sample_weight is passed and base_estimator fit method does not support it.

New in version 0.18.

Raises

- **ValueError** If no valid consensus set could be found. This occurs if is_data_valid and is_model_valid return False for all max_trials randomly chosen sub-samples.

**get_params**(deep=True)

Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict**(X)

Predict using the estimated model.
This is a wrapper for \texttt{estimator\_.predict(X)}.

\textbf{Parameters}

\begin{itemize}
  \item \texttt{X} [numpy array of shape [n\_samples, n\_features]]
\end{itemize}

\textbf{Returns}

\begin{itemize}
  \item \texttt{y} [array, shape = [n\_samples] or [n\_samples, n\_targets]] Returns predicted values.
\end{itemize}

\textbf{score}(X, y)

Returns the score of the prediction.

This is a wrapper for \texttt{estimator\_.score(X, y)}.

\textbf{Parameters}

\begin{itemize}
  \item \texttt{X} [numpy array or sparse matrix of shape [n\_samples, n\_features]] Training data.
  \item \texttt{y} [array, shape = [n\_samples] or [n\_samples, n\_targets]] Target values.
\end{itemize}

\textbf{Returns}

\begin{itemize}
  \item \texttt{z} [float] Score of the prediction.
\end{itemize}

\textbf{set\_params} (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as \texttt{Pipeline}). The latter have parameters of the form \texttt{<component>\_<parameter>} so that it’s possible to update each component of a nested object.

\textbf{Parameters}

\begin{itemize}
  \item \texttt{**params} [dict] Estimator parameters.
\end{itemize}

\textbf{Returns}

\begin{itemize}
  \item \texttt{self} [estimator instance] Estimator instance.
\end{itemize}

\textbf{Examples using} \texttt{sklearn.linear\_model.RANSACRegressor}

- Robust linear model estimation using RANSAC
- Theil-Sen Regression
- Robust linear estimator fitting

\textbf{sklearn.linear\_model.TheilSenRegressor}

\textbf{class} \texttt{sklearn.linear\_model.TheilSenRegressor}(*, \texttt{fit\_intercept=True}, \texttt{copy\_X=True}, \texttt{max\_subpopulation=10000.0}, \texttt{n\_subsamples=None}, \texttt{max\_iter=300}, \texttt{tol=0.001}, \texttt{random\_state=None}, \texttt{n\_jobs=None}, \texttt{verbose=False})

Theil-Sen Estimator: robust multivariate regression model.

The algorithm calculates least square solutions on subsets with size \texttt{n\_subsamples} of the samples in \texttt{X}. Any value of \texttt{n\_subsamples} between the number of features and samples leads to an estimator with a compromise between robustness and efficiency. Since the number of least square solutions is “\texttt{n\_samples choose n\_subsamples}”, it can be extremely large and can therefore be limited with \texttt{max\_subpopulation}. If this limit is reached, the subsets are chosen randomly. In a final step, the spatial median (or L1 median) is calculated of all least square solutions.
Parameters

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations.

copy_X [bool, default=True] If True, X will be copied; else, it may be overwritten.

max_subpopulation [int, default=1e4] Instead of computing with a set of cardinality ‘n choose k’, where n is the number of samples and k is the number of subsamples (at least number of features), consider only a stochastic subpopulation of a given maximal size if ‘n choose k’ is larger than max_subpopulation. For other than small problem sizes this parameter will determine memory usage and runtime if n_subsamples is not changed.

n_subsamples [int, default=None] Number of samples to calculate the parameters. This is at least the number of features (plus 1 if fit_intercept=True) and the number of samples as a maximum. A lower number leads to a higher breakdown point and a low efficiency while a high number leads to a low breakdown point and a high efficiency. If None, take the minimum number of subsamples leading to maximal robustness. If n_subsamples is set to n_samples, Theil-Sen is identical to least squares.

max_iter [int, default=300] Maximum number of iterations for the calculation of spatial median.

tol [float, default=1.e-3] Tolerance when calculating spatial median.

random_state [int, RandomState instance or None, default=None] A random number generator instance to define the state of the random permutations generator. Pass an int for reproducible output across multiple function calls. See Glossary

n_jobs [int, default=None] Number of CPUs to use during the cross validation. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [bool, default=False] Verbose mode when fitting the model.

Attributes

coeff_ [ndarray of shape (n_features,)] Coefficients of the regression model (median of distribution).

intercept_ [float] Estimated intercept of regression model.

breakdown_ [float] Approximated breakdown point.

n_iter_ [int] Number of iterations needed for the spatial median.

n_subpopulation_ [int] Number of combinations taken into account from ‘n choose k’, where n is the number of samples and k is the number of subsamples.

References

• Theil-Sen Estimators in a Multiple Linear Regression Model, 2009 Xin Dang, Hanxiang Peng, Xueqin Wang and Heping Zhang http://home.olemiss.edu/~xdang/papers/MTSE.pdf
Examples

```python
>>> from sklearn.linear_model import TheilSenRegressor
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(
...     n_samples=200, n_features=2, noise=4.0, random_state=0)
>>> reg = TheilSenRegressor(random_state=0).fit(X, y)
>>> reg.score(X, y)
0.9884...
>>> reg.predict(X[:,:1])
array([-31.5871...])
```

Methods

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<td><code>fit(X, y)</code></td>
<td>Fit linear model.</td>
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<tr>
<td><code>get_params()</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit (X, y)**
Fit linear model.

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Training data.
- **y** [ndarray of shape (n_samples,)] Target values.

**Returns**

- **self** [returns an instance of self.]

**get_params**(deep=True)
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict (X)**
Predict using the linear model.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **C** [array, shape (n_samples,)] Returns predicted values.

**score (X, y, sample_weight=None)**
Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $1 - \frac{u}{v}$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})^2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())^2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt y.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- ****params [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.linear_model.TheilSenRegressor**

- Theil-Sen Regression
- Robust linear estimator fitting

### 7.22.7 Generalized linear models (GLM) for regression

These models allow for response variables to have error distributions other than a normal distribution:

```python
linear_model.PoissonRegressor(*[, alpha, ...])
```

Generalized Linear Model with a Poisson distribution.

```python
linear_model.TweedieRegressor(*[, power, ...])
```

Generalized Linear Model with a Tweedie distribution.

continues on next page
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linear_model.GammaRegressor(*[, alpha, ...])

Generalized Linear Model with a Gamma distribution.

sklearn.linear_model.PoissonRegressor

class sklearn.linear_model.PoissonRegressor(*, alpha=1.0, fit_intercept=True, max_iter=100, tol=0.0001, warm_start=False, verbose=0)

Generalized Linear Model with a Poisson distribution.

Read more in the User Guide.

New in version 0.23.

Parameters

alpha [float, default=1] Constant that multiplies the penalty term and thus determines the regularization strength. alpha = 0 is equivalent to unpenalized GLMs. In this case, the design matrix X must have full column rank (no collinearities).

fit_intercept [bool, default=True] Specifies if a constant (a.k.a. bias or intercept) should be added to the linear predictor (X @ coef + intercept).

max_iter [int, default=100] The maximal number of iterations for the solver.

tol [float, default=1e-4] Stopping criterion. For the lbfgs solver, the iteration will stop when max{|g_j|, j = 1, ..., d} <= tol where g_j is the j-th component of the gradient (derivative) of the objective function.

warm_start [bool, default=False] If set to True, reuse the solution of the previous call to fit as initialization for coef_ and intercept_.

verbose [int, default=0] For the lbfgs solver set verbose to any positive number for verbosity.

Attributes

coef_ [array of shape (n_features,)] Estimated coefficients for the linear predictor (X @ coef_ + intercept_) in the GLM.

intercept_ [float] Intercept (a.k.a. bias) added to linear predictor.

n_iter_ [int] Actual number of iterations used in the solver.

Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.PoissonRegressor()
>>> X = [[1, 2], [2, 3], [3, 4], [4, 3]]
>>> y = [12, 17, 22, 21]
>>> clf.fit(X, y)
```

`PoissonRegressor`

```
>>> clf.score(X, y)
0.990...
```

```python
>>> clf.coef_.array([0.121..., 0.158...])
```

```python
>>> clf.intercept_ 2.088...
```

(continues on next page)
Methods

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<th>Description</th>
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<td><code>fit(X, y[, sample_weight])</code></td>
<td>Fit a Generalized Linear Model.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict using GLM with feature matrix X.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Compute $D^2$, the percentage of deviance explained.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit** $(X, y, \text{sample_weight}=\text{None})$

Fit a Generalized Linear Model.

Parameters

- **X**  
  [array-like, sparse matrix] of shape (n_samples, n_features)  
  Training data.
- **y**  
  array-like of shape (n_samples,)  
  Target values.
- **sample_weight**  
  array-like of shape (n_samples,), default=None  
  Sample weights.

Returns

- **self**  
  [returns an instance of self.]

**get_params**(deep=True)

Get parameters for this estimator.

Parameters

- **deep**  
  [bool, default=True]  
  If True, will return the parameters for this estimator and contained  
  subobjects that are estimators.

Returns

- **params**  
  [dict] Parameter names mapped to their values.

**predict** $(X)$

Predict using GLM with feature matrix X.

Parameters

- **X**  
  [array-like, sparse matrix] of shape (n_samples, n_features)  
  Samples.

Returns

- **y_pred**  
  [array of shape (n_samples,)]  
  Returns predicted values.

**score** $(X, y, \text{sample_weight}=\text{None})$

Compute $D^2$, the percentage of deviance explained.

$D^2$ is a generalization of the coefficient of determination $R^2$.  
$R^2$ uses squared error and $D^2$ deviance.  
Note that those two are equal for family='normal'.

$D^2$ is defined as  
$$D^2 = 1 - \frac{D(\text{true}, \text{pred})}{D_{null}}$$  
$D_{null}$ is the null deviance, i.e. the deviance of a model with  
intercept alone, which corresponds to $\hat{y}_{pred} = \bar{y}$.  
The mean $\bar{y}$ is averaged by sample_weight.  
Best possible score is 1.0 and it can be negative (because the model  
can be arbitrarily worse).

Parameters
X  [{array-like, sparse matrix} of shape (n_samples, n_features)] Test samples.
y  [array-like of shape (n_samples,)] True values of target.
sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] D^2 of self.predict(X) w.r.t. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

Examples using sklearn.linear_model.PoissonRegressor

- Release Highlights for scikit-learn 0.23
- Poisson regression and non-normal loss
- Tweedie regression on insurance claims

sklearn.linear_model.TweedieRegressor

class sklearn.linear_model.TweedieRegressor (*, power=0.0, alpha=1.0, fit_intercept=True,
link='auto', max_iter=100, tol=0.0001, warm_start=False, verbose=0)

Generalized Linear Model with a Tweedie distribution.

This estimator can be used to model different GLMs depending on the power parameter, which determines the underlying distribution.

Read more in the User Guide.

New in version 0.23.

Parameters

power  [float, default=0] The power determines the underlying target distribution according to the following table:

<table>
<thead>
<tr>
<th>Power</th>
<th>Distribution</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Normal</td>
</tr>
<tr>
<td>1</td>
<td>Poisson</td>
</tr>
<tr>
<td>(1,2)</td>
<td>Compound Poisson Gamma</td>
</tr>
<tr>
<td>2</td>
<td>Gamma</td>
</tr>
<tr>
<td>3</td>
<td>Inverse Gaussian</td>
</tr>
</tbody>
</table>

For 0 < power < 1, no distribution exists.
alpha [float, default=1] Constant that multiplies the penalty term and thus determines the regularization strength. alpha = 0 is equivalent to unpenalized GLMs. In this case, the design matrix X must have full column rank (no collinearities).

link [‘auto’, ‘identity’, ‘log’], default=’auto’) The link function of the GLM, i.e. mapping from linear predictor X @ coeff + intercept to prediction y_pred. Option ‘auto’ sets the link depending on the chosen family as follows:

- ‘identity’ for Normal distribution
- ‘log’ for Poisson, Gamma and Inverse Gaussian distributions

fit_intercept [bool, default=True] Specifies if a constant (a.k.a. bias or intercept) should be added to the linear predictor (X @ coef + intercept).

max_iter [int, default=100] The maximal number of iterations for the solver.

tol [float, default=1e-4] Stopping criterion. For the lbfgs solver, the iteration will stop when max{|g_j|, j = 1, ..., d} <= tol where g_j is the j-th component of the gradient (derivative) of the objective function.

warm_start [bool, default=False] If set to True, reuse the solution of the previous call to fit as initialization for coef_ and intercept_.

verbose [int, default=0] For the lbfgs solver set verbose to any positive number for verbosity.

Attributes

coef_ [array of shape (n_features,)] Estimated coefficients for the linear predictor (X @ coef_ + intercept_) in the GLM.

intercept_ [float] Intercept (a.k.a. bias) added to linear predictor.

n_iter_ [int] Actual number of iterations used in the solver.

Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.TweedieRegressor()
>>> X = [[1, 2], [2, 3], [3, 4], [4, 3]]
>>> y = [2, 3.5, 5, 5.5]
>>> clf.fit(X, y)
TweedieRegressor()
>>> clf.score(X, y)
0.839...
>>> clf.coef_
array([[0.599..., 0.299...]])
>>> clf.intercept_
1.600...
>>> clf.predict([[1, 1], [3, 4]])
array([2.500..., 4.599...])
```
Methods

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**fit (X, y, sample_weight=None)**
Fit a Generalized Linear Model.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data.
- **y** [array-like of shape (n_samples,)] Target values.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **self** [returns an instance of self.]

**get_params (deep=True)**
Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**predict (X)**
Predict using GLM with feature matrix X.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Samples.

Returns

- **y_pred** [array of shape (n_samples,)] Returns predicted values.

**score (X, y, sample_weight=None)**
Compute $D^2$, the percentage of deviance explained.

$D^2$ is a generalization of the coefficient of determination $R^2$. $R^2$ uses squared error and $D^2$ deviance. Note that those two are equal for family='normal'.

$D^2$ is defined as $D^2 = 1 - \frac{D(y_{true}, y_{pred})}{D_{null}}$, $D_{null}$ is the null deviance, i.e. the deviance of a model with intercept alone, which corresponds to $y_{pred} = \bar{y}$. The mean $\bar{y}$ is averaged by sample_weight. Best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse).

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Test samples.
- **y** [array-like of shape (n_samples,)] True values of target.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

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score [float] \( D^2 \) of self.predict(X) w.r.t. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.linear_model.TweedieRegressor

- Release Highlights for scikit-learn 0.23
- Tweedie regression on insurance claims

sklearn.linear_model.GammaRegressor

class sklearn.linear_model.GammaRegressor(*, alpha=1.0, fit_intercept=True, max_iter=100, tol=0.0001, warm_start=False, verbose=0)

Generalized Linear Model with a Gamma distribution.

Read more in the User Guide.

New in version 0.23.

Parameters

alpha [float, default=1] Constant that multiplies the penalty term and thus determines the regularization strength. \( \alpha = 0 \) is equivalent to unpenalized GLMs. In this case, the design matrix \( X \) must have full column rank (no collinearities).

fit_intercept [bool, default=True] Specifies if a constant (a.k.a. bias or intercept) should be added to the linear predictor \( (X @ \text{coef} + \text{intercept}) \).

max_iter [int, default=100] The maximal number of iterations for the solver.

tol [float, default=1e-4] Stopping criterion. For the lbfgs solver, the iteration will stop when \( \max\{|g_j|, j = 1, \ldots, d\} \leq \text{tol} \) where \( g_j \) is the j-th component of the gradient (derivative) of the objective function.

warm_start [bool, default=False] If set to True, reuse the solution of the previous call to fit as initialization for coef_ and intercept_.

verbose [int, default=0] For the lbfgs solver set verbose to any positive number for verbosity.

Attributes

coef_ [array of shape (n_features,)] Estimated coefficients for the linear predictor \( (X \ast \text{coef} + \text{intercept}) \) in the GLM.

intercept_ [float] Intercept (a.k.a. bias) added to linear predictor.

n_iter_ [int] Actual number of iterations used in the solver.
Examples

```python
>>> from sklearn import linear_model
>>> clf = linear_model.GammaRegressor()
>>> X = [[1, 2], [2, 3], [3, 4], [4, 3]]
>>> y = [19, 26, 33, 30]
>>> clf.fit(X, y)
GammaRegressor()
>>> clf.score(X, y)
0.773...
>>> clf.coef_
array([0.072..., 0.066...])
>>> clf.intercept_
2.896...
>>> clf.predict([[1, 0], [2, 8]])
array([19.483..., 35.795...])
```
y_pred [array of shape (n_samples,)] Returns predicted values.

score \( (X, y, \text{sample_weight=None}) \)
Compute D^2, the percentage of deviance explained.

D^2 is a generalization of the coefficient of determination R^2. R^2 uses squared error and D^2 deviance. Note that those two are equal for family='normal'.

D^2 is defined as 
\[
D^2 = 1 - \frac{D(y_{true}, y_{pred})}{D_{null}},
\]
\(D_{null}\) is the null deviance, i.e. the deviance of a model with intercept alone, which corresponds to \(y_{pred} = \bar{y}\). The mean \(\bar{y}\) is averaged by sample_weight. Best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse).

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,)] True values of target.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] D^2 of self.predict(X) w.r.t. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<\text{component}>\__<\text{parameter}>\) so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.linear_model.GammaRegressor

- Release Highlights for scikit-learn 0.23
- Tweedie regression on insurance claims

7.22.8 Miscellaneous

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**sklearn.linear_model.PassiveAggressiveRegressor**

```python
sklearn.linear_model.PassiveAggressiveRegressor(*, C=1.0, fit_intercept=True, max_iter=1000, tol=0.001, early_stopping=False, validation_fraction=0.1, n_iter_no_change=5, shuffle=True, verbose=0, loss='epsilon_insensitive', epsilon=0.1, random_state=None, warm_start=False, average=False)
```

Passive Aggressive Regressor

Read more in the *User Guide*.

**Parameters**

- **C** [float, default=1.0] Maximum step size (regularization). Defaults to 1.0.
- **fit_intercept** [bool, default=True] Whether the intercept should be estimated or not. If False, the data is assumed to be already centered. Defaults to True.
- **max_iter** [int, default=1000] The maximum number of passes over the training data (aka epochs). It only impacts the behavior in the `fit` method, and not the `partial_fit` method.
  
  New in version 0.19.
- **tol** [float or None, default=1e-3] The stopping criterion. If it is not None, the iterations will stop when (loss > previous_loss - tol).
  
  New in version 0.19.
- **early_stopping** [bool, default=False] Whether to use early stopping to terminate training when validation. score is not improving. If set to True, it will automatically set aside a fraction of training data as validation and terminate training when validation score is not improving by at least tol for `n_iter_no_change` consecutive epochs.
  
  New in version 0.20.
- **validation_fraction** [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if `early_stopping` is True.
  
  New in version 0.20.
- **n_iter_no_change** [int, default=5] Number of iterations with no improvement to wait before early stopping.
  
  New in version 0.20.
- **shuffle** [bool, default=True] Whether or not the training data should be shuffled after each epoch.
- **verbose** [integer, default=0] The verbosity level
loss [string, default="epsilon_insensitive"] The loss function to be used: epsilon_insensitive: equivalent to PA-I in the reference paper. squared_epsilon_insensitive: equivalent to PA-II in the reference paper.

epsilon [float, default=DEFAULT_EPSILON] If the difference between the current prediction and the correct label is below this threshold, the model is not updated.

random_state [int, RandomState instance, default=None] Used to shuffle the training data, when shuffle is set to True. Pass an int for reproducible output across multiple function calls. See Glossary.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

Repeatedly calling fit or partial_fit when warm_start is True can result in a different solution than when calling fit a single time because of the way the data is shuffled.

average [bool or int, default=False] When set to True, computes the averaged SGD weights and stores the result in the coef_ attribute. If set to an int greater than 1, averaging will begin once the total number of samples seen reaches average. So average=10 will begin averaging after seeing 10 samples.

New in version 0.19: parameter average to use weights averaging in SGD

Attributes

c_coef [array, shape = [1, n_features] if n_classes == 2 else [n_classes, n_features]] Weights assigned to the features.

intercept_ [array, shape = [1] if n_classes == 2 else [n_classes]] Constants in decision function.

n_iter_ [int] The actual number of iterations to reach the stopping criterion.

t_ [int] Number of weight updates performed during training. Same as \( n \_iter \_ * n \_samples \).

See also:

SGDRegressor

References


Examples

```python
>>> from sklearn.linear_model import PassiveAggressiveRegressor
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_features=4, random_state=0)
>>> regr = PassiveAggressiveRegressor(max_iter=100, random_state=0, ...
... tol=1e-3)
>>> regr.fit(X, y)
PassiveAggressiveRegressor(max_iter=100, random_state=0)
>>> print (regr.coef_)
[20.48736655 34.18818427 67.59122734 87.94731329]
>>> print (regr.intercept_)
```

(continues on next page)
>>> print(regr.predict([[0, 0, 0, 0]]))
[-0.02306214]

```
import sklearn.linear_model
sklearn.linear_model.enet_path
```

`sklearn.linear_model.enet_path(X, y, *, l1_ratio=0.5, eps=0.001, n_alphas=100, alphas=None, precompute='auto', Xy=None, copy_X=True, coef_init=None, verbose=False, return_n_iter=False, positive=False, check_input=True, **params)`

Compute elastic net path with coordinate descent.

The elastic net optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
\frac{1}{(2 \times n\_samples)} \times ||y - Xw||^2_2 \\
+ \alpha \times l1\_ratio \times ||w||_1 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||w||^2_2
\]

For multi-output tasks it is:

\[
\left( \frac{1}{(2 \times n\_samples)} \right) \times ||Y - XW||^\text{Fro}_2 \\
+ \alpha \times l1\_ratio \times ||W||_21 \\
+ 0.5 \times \alpha \times (1 - l1\_ratio) \times ||W||_{\text{Fro}}^2
\]

Where:

\[||W||_21 = \sum_i \sqrt{\sum_j w_{ij}^2}\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.
- `y` ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values.
- `l1_ratio` [float, default=0.5] Number between 0 and 1 passed to elastic net (scaling between l1 and l2 penalties). l1_ratio=1 corresponds to the Lasso.
- `eps` [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3.
- `n_alphas` [int, default=100] Number of alphas along the regularization path.
- `alphas` [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically.
- `precompute` [‘auto’, bool or array-like of shape (n_features, n_features), default=’auto’] Whether to use a precomputed Gram matrix to speed up calculations. If set to ‘auto’ let us decide. The Gram matrix can also be passed as argument.
**Xy** [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is pre-computed.

**copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

**coef_init** [ndarray of shape (n_features,), default=None] The initial values of the coefficients.

**verbose** [bool or int, default=False] Amount of verbosity.

**return_n_iter** [bool, default=False] Whether to return the number of iterations or not.

**positive** [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).

**check_input** [bool, default=True] If set to False, the input validation checks are skipped (including the Gram matrix when provided). It is assumed that they are handled by the caller.

**params** [kwargs] Keyword arguments passed to the coordinate descent solver.

**Returns**

**alphas** [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.

**coefs** [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.

**dual_gaps** [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

**n_iters** [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha. (Is returned when return_n_iter is set to True).

**See also:**

*MultiTaskElasticNet*

*MultiTaskElasticNetCV*

*ElasticNet*

*ElasticNetCV*

**Notes**

For an example, see *examples/linear_model/plot_lasso_coordinate_descent_path.py*.

**Examples using sklearn.linear_model.enet_path**

- *Lasso and Elastic Net*
**sklearn.linear_model.lars_path**

```python
sklearn.linear_model.lars_path(X, y, Xy=None, *, Gram=None, max_iter=500, alpha_min=0, method='lar', copy_X=True, eps=2.220446049250313e-16, copy_Gram=True, verbose=0, return_path=True, return_n_iter=False, positive=False)
```

Compute Least Angle Regression or Lasso path using LARS algorithm [1]

The optimization objective for the case method='lasso' is:

\[
\frac{1}{(2 \times n_{samples})} \times ||y - Xw||^2_2 + \alpha \times ||w||_1
\]

in the case of method='lars', the objective function is only known in the form of an implicit equation (see discussion in [1])

Read more in the User Guide.

**Parameters**

- **X** [None or array-like of shape (n_samples, n_features)] Input data. Note that if X is None then the Gram matrix must be specified, i.e., cannot be None or False.
- **y** [None or array-like of shape (n_samples,)] Input targets.
- **Xy** [array-like of shape (n_samples,) or (n_samples, n_targets), default=None] \(Xy = \text{np.dot}(X.T, y)\) that can be precomputed. It is useful only when the Gram matrix is pre-computed.
- **Gram** [None, 'auto', array-like of shape (n_features, n_features), default=None] Precomputed Gram matrix \((X' * X)\), if 'auto', the Gram matrix is precomputed from the given X, if there are more samples than features.
- **max_iter** [int, default=500] Maximum number of iterations to perform, set to infinity for no limit.
- **alpha_min** [float, default=0] Minimum correlation along the path. It corresponds to the regularization parameter alpha parameter in the Lasso.
- **method** [{'lar', 'lasso'}, default='lar'] Specifies the returned model. Select 'lar' for Least Angle Regression, 'lasso' for the Lasso.
- **copy_X** [bool, default=True] If False, X is overwritten.
- **eps** [float, default=np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the tol parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.
- **copy_Gram** [bool, default=True] If False, Gram is overwritten.
- **verbose** [int, default=0] Controls output verbosity.
- **return_path** [bool, default=True] If return_path==True returns the entire path, else returns only the last point of the path.
- **return_n_iter** [bool, default=False] Whether to return the number of iterations.
- **positive** [bool, default=False] Restrict coefficients to be >= 0. This option is only allowed with method 'lasso'. Note that the model coefficients will not converge to the ordinary-least-squares solution for small values of alpha. Only coefficients up to the smallest alpha value \((alphas_[alphas_ > 0.].min())\) when fit_path=True) reached by the step-wise Lars-Lasso algorithm are typically in congruence with the solution of the coordinate descent lasso_path function.
Returns

- **alphas** [array-like of shape (n_alphas + 1,)] Maximum of covariances (in absolute value) at each iteration. n_alphas is either max_iter, n_features or the number of nodes in the path with alpha >= alpha_min, whichever is smaller.
- **active** [array-like of shape (n_alphas,)] Indices of active variables at the end of the path.
- **coefs** [array-like of shape (n_features, n_alphas + 1)] Coefficients along the path
- **n_iter** [int] Number of iterations run. Returned only if return_n_iter is set to True.

See also:

- `lars_path_gram`
- `lasso_path`
- `lasso_path_gram`
- `LassoLars`
- `Lars`
- `LassoLarsCV`
- `LarsCV`
- `sklearn.decomposition.sparse_encode`

References

[1], [2], [3]

Examples using `sklearn.linear_model.lars_path`

- **Lasso path using LARS**

```python
sklearn.linear_model.lars_path(Xy, Gram, *, n_samples, max_iter=500, alpha_min=0, method='lar', copy_X=True, eps=2.220446049250313e-16, copy_Gram=True, verbose=0, return_path=True, return_n_iter=False, positive=False)
```

lars_path in the sufficient stats mode [1]

The optimization objective for the case method='lasso' is:

\[
\frac{1}{2(n_samples)} \| y - Xw \|^2 \_2 + \alpha \| w \| \_1
\]

in the case of method='lars', the objective function is only known in the form of an implicit equation (see discussion in [1])

Read more in the User Guide.

Parameters

- **Xy** [array-like of shape (n_samples,) or (n_samples, n_targets)] Xy = np.dot(X.T, y).
- **Gram** [array-like of shape (n_features, n_features)] Gram = np.dot(X.T * X).
n_samples  [int or float] Equivalent size of sample.

max_iter  [int, default=500] Maximum number of iterations to perform, set to infinity for no limit.

alpha_min  [float, default=0] Minimum correlation along the path. It corresponds to the regularization parameter alpha parameter in the Lasso.

method  ['lar', 'lasso'], default='lar'] Specifies the returned model. Select 'lar' for Least Angle Regression, 'lasso' for the Lasso.

copy_X  [bool, default=True] If False, X is overwritten.

eps  [float, default=np.finfo(float).eps] The machine-precision regularization in the computation of the Cholesky diagonal factors. Increase this for very ill-conditioned systems. Unlike the tol parameter in some iterative optimization-based algorithms, this parameter does not control the tolerance of the optimization.

copy_Gram  [bool, default=True] If False, Gram is overwritten.

verbose  [int, default=0] Controls output verbosity.

return_path  [bool, default=True] If return_path==True returns the entire path, else returns only the last point of the path.

return_n_iter  [bool, default=False] Whether to return the number of iterations.

positive  [bool, default=False] Restrict coefficients to be >= 0. This option is only allowed with method 'lasso'. Note that the model coefficients will not converge to the ordinary-least-squares solution for small values of alpha. Only coefficients up to the smallest alpha value (alphas_[alphas_ > 0.].min() when fit_path=True) reached by the stepwise Lars-Lasso algorithm are typically in congruence with the solution of the coordinate descent lasso_path function.

Returns

alphas  [array-like of shape (n_alphas + 1,)] Maximum of covariances (in absolute value) at each iteration. n_alphas is either max_iter, n_features or the number of nodes in the path with alpha >= alpha_min, whichever is smaller.

active  [array-like of shape (n_alphas,)] Indices of active variables at the end of the path.

coeefs  [array-like of shape (n_features, n_alphas + 1)] Coefficients along the path

n_iter  [int] Number of iterations run. Returned only if return_n_iter is set to True.

See also:

lars_path
lasso_path
lasso_path_gram
LassoLars
Lars
LassoLarsCV
LarsCV
sklearn.decomposition.sparse_encode
Compute Lasso path with coordinate descent
The Lasso optimization function varies for mono and multi-outputs.

For mono-output tasks it is:

\[
(1 / (2 \times n\_samples)) \times ||y - Xw||^2_2 + \alpha \times ||w||_1
\]

For multi-output tasks it is:

\[
(1 / (2 \times n\_samples)) \times ||Y - XW||^2_{\text{Fro}} + \alpha \times ||W||_21
\]

Where:

\[
||W||_21 = \sum_i \sqrt{\sum_j w_{ij}^2}
\]

i.e. the sum of norm of each row.

Read more in the User Guide.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data. Pass directly as Fortran-contiguous data to avoid unnecessary memory duplication. If y is mono-output then X can be sparse.

- **y** ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values

- **eps** [float, default=1e-3] Length of the path. eps=1e-3 means that alpha_min / alpha_max = 1e-3

- **n_alphas** [int, default=100] Number of alphas along the regularization path

- **alphas** [ndarray, default=None] List of alphas where to compute the models. If None alphas are set automatically

- **precompute** ['auto', bool or array-like of shape (n_features, n_features), default='auto'] Whether to use a precomputed Gram matrix to speed up calculations. If set to 'auto' let us decide. The Gram matrix can also be passed as argument.

- **Xy** [array-like of shape (n_features,) or (n_features, n_outputs), default=None] Xy = np.dot(X.T, y) that can be precomputed. It is useful only when the Gram matrix is pre-computed.

- **copy_X** [bool, default=True] If True, X will be copied; else, it may be overwritten.

- **coef_init** [ndarray of shape (n_features,), default=None] The initial values of the coefficients.

- **verbose** [bool or int, default=False] Amount of verbosity.

- **return_n_iter** [bool, default=False] whether to return the number of iterations or not.
**positive** [bool, default=False] If set to True, forces coefficients to be positive. (Only allowed when y.ndim == 1).

**params** [kwargs] keyword arguments passed to the coordinate descent solver.

Returns

alphas [ndarray of shape (n_alphas,)] The alphas along the path where models are computed.

coefs [ndarray of shape (n_features, n_alphas) or (n_outputs, n_features, n_alphas)] Coefficients along the path.

dual_gaps [ndarray of shape (n_alphas,)] The dual gaps at the end of the optimization for each alpha.

n_iters [list of int] The number of iterations taken by the coordinate descent optimizer to reach the specified tolerance for each alpha.

See also:

lars_path
Lasso
LassoLars
LassoCV
LassoLarsCV
sklearn.decomposition.sparse_encode

Notes

For an example, see examples/linear_model/plot_lasso_coordinate_descent_path.py.

To avoid unnecessary memory duplication the X argument of the fit method should be directly passed as a Fortran-contiguous numpy array.

Note that in certain cases, the Lars solver may be significantly faster to implement this functionality. In particular, linear interpolation can be used to retrieve model coefficients between the values output by lars_path.

Examples

Comparing lasso_path and lars_path with interpolation:

```python
>>> X = np.array([[1, 2, 3.1], [2.3, 5.4, 4.3]]).T
>>> y = np.array([1, 2, 3.1])
>>> # Use lasso_path to compute a coefficient path
>>> _, coef_path, _ = lasso_path(X, y, alphas=[5., 1., .5])
>>> print(coef_path)
[[0. 0. 0.46874778]
 [0.2159048 0.4425765 0.23689075]]

>>> # Now use lars_path and 1D linear interpolation to compute the same path
>>> from sklearn.linear_model import lars_path
>>> alphas, active, coef_path_lars = lars_path(X, y, method='lasso')
>>> from scipy import interpolate
>>> coef_path_continuous = interpolate.interp1d(alphas[::-1],
```
Examples using sklearn.linear_model.lasso_path

- Lasso and Elastic Net

sklearn.linear_model.orthogonal_mp

sklearn.linear_model.orthogonal_mp(X, y, *, n_nonzero_coefs=None, tol=None, precompute=False, copy_X=True, return_path=False, return_n_iter=False)

Orthogonal Matching Pursuit (OMP).

Solves n_targets Orthogonal Matching Pursuit problems. An instance of the problem has the form:

When parametrized by the number of non-zero coefficients using n_nonzero_coefs: argmin ||y - Xgamma||^2 subject to ||gamma||_0 <= n_{nonzero coefs}

When parametrized by error using the parameter tol: argmin ||gamma||_0 subject to ||y - Xgamma||^2 <= tol

Read more in the User Guide.

Parameters

X [ndarray of shape (n_samples, n_features)] Input data. Columns are assumed to have unit norm.

y [ndarray of shape (n_samples,) or (n_samples, n_targets)] Input targets.

n_nonzero_coefs [int, default=None] Desired number of non-zero entries in the solution. If None (by default) this value is set to 10% of n_features.

tol [float, default=None] Maximum norm of the residual. If not None, overrides n_nonzero_coefs.

precompute ['auto' or bool, default=False] Whether to perform precomputations. Improves performance when n_targets or n_samples is very large.

copy_X [bool, default=True] Whether the design matrix X must be copied by the algorithm. A false value is only helpful if X is already Fortran-ordered, otherwise a copy is made anyway.

return_path [bool, default=False] Whether to return every value of the nonzero coefficients along the forward path. Useful for cross-validation.

return_n_iter [bool, default=False] Whether or not to return the number of iterations.

Returns

coef [ndarray of shape (n_features,) or (n_features, n_targets)] Coefficients of the OMP solution. If return_path=True, this contains the whole coefficient path. In this case its shape is (n_features, n_features) or (n_features, n_targets, n_features) and iterating over the last axis yields coefficients in increasing order of active features.

n_iters [array-like or int] Number of active features across every target. Returned only if return_n_iter is set to True.

See also:
OrthogonalMatchingPursuit

orthogonal_mp_gram

lars_path

sklearn.decomposition.sparse_encode

Notes


sklearn.linear_model.orthogonal_mp_gram

`sklearn.linear_model.orthogonal_mp_gram(Gram, Xy, *, n_nonzero_coefs=None, tol=None, norms_squared=None, copy_Gram=True, copy_Xy=True, return_path=False, return_n_iter=False)`

Gram Orthogonal Matching Pursuit (OMP).

Solves n_targets Orthogonal Matching Pursuit problems using only the Gram matrix X.T * X and the product X.T * y.

Read more in the User Guide.

Parameters

- **Gram** [ndarray of shape (n_features, n_features)] Gram matrix of the input data: X.T * X.
- **Xy** [ndarray of shape (n_features,) or (n_features, n_targets)] Input targets multiplied by X: X.T * y.
- **n_nonzero_coefs** [int, default=None] Desired number of non-zero entries in the solution. If None (by default) this value is set to 10% of n_features.
- **tol** [float, default=None] Maximum norm of the residual. If not None, overrides n_nonzero_coefs.
- **norms_squared** [array-like of shape (n_targets,), default=None] Squared L2 norms of the lines of y. Required if tol is not None.
- **copy_Gram** [bool, default=True] Whether the gram matrix must be copied by the algorithm. A false value is only helpful if it is already Fortran-ordered, otherwise a copy is made anyway.
- **copy_Xy** [bool, default=True] Whether the covariance vector Xy must be copied by the algorithm. If False, it may be overwritten.
- **return_path** [bool, default=False] Whether to return every value of the nonzero coefficients along the forward path. Useful for cross-validation.
- **return_n_iter** [bool, default=False] Whether or not to return the number of iterations.

Returns
**coef** [ndarray of shape (n_features,) or (n_features, n_targets)] Coefficients of the OMP solution. If `return_path=True`, this contains the whole coefficient path. In this case its shape is (n_features, n_features) or (n_features, n_targets, n_features) and iterating over the last axis yields coefficients in increasing order of active features.

**n_iters** [array-like or int] Number of active features across every target. Returned only if `return_n_iter` is set to True.

See also:

- `OrthogonalMatchingPursuit`
- `orthogonal_mp`
- `lars_path`
- `sklearn.decomposition.sparse_encode`

**Notes**


**sklearn.linear_model.ridge_regression**

**sklearn.linear_model.ridge_regression** (X, y, alpha, *, sample_weight=None, solver='auto', max_iter=None, tol=0.001, verbose=0, random_state=None, return_n_iter=False, return_intercept=False, check_input=True)

Solve the ridge equation by the method of normal equations.

Read more in the *User Guide*.

**Parameters**

- **X** [[ndarray, sparse matrix, LinearOperator] of shape (n_samples, n_features)] Training data
- **y** [[ndarray of shape (n_samples,) or (n_samples, n_targets)] Target values
- **alpha** [float or array-like of shape (n_targets,)] Regularization strength; must be a positive float. Regularization improves the conditioning of the problem and reduces the variance of the estimates. Larger values specify stronger regularization. Alpha corresponds to \(1 / (2C)\) in other linear models such as `LogisticRegression` or `LinearSVC`. If an array is passed, penalties are assumed to be specific to the targets. Hence they must correspond in number.
- **sample_weight** [float or array-like of shape (n_samples,), default=None] Individual weights for each sample. If given a float, every sample will have the same weight. If `sample_weight` is not None and solver='auto', the solver will be set to ‘cholesky’.
  
  New in version 0.17.
• ‘auto’ chooses the solver automatically based on the type of data.
• ‘svd’ uses a Singular Value Decomposition of X to compute the Ridge coefficients. More stable for singular matrices than ‘cholesky’.
• ‘cholesky’ uses the standard scipy.linalg.solve function to obtain a closed-form solution via a Cholesky decomposition of dot(X.T, X)
• ‘sparse_cg’ uses the conjugate gradient solver as found in scipy.sparse.linalg.cg. As an iterative algorithm, this solver is more appropriate than ‘cholesky’ for large-scale data (possibility to set tol and max_iter).
• ‘lsqr’ uses the dedicated regularized least-squares routine scipy.sparse.linalg.lsqr. It is the fastest and uses an iterative procedure.
• ‘sag’ uses a Stochastic Average Gradient descent, and ‘saga’ uses its improved, unbiased version named SAGA. Both methods also use an iterative procedure, and are often faster than other solvers when both n_samples and n_features are large. Note that ‘sag’ and ‘saga’ fast convergence is only guaranteed on features with approximately the same scale. You can preprocess the data with a scaler from sklearn.preprocessing.

All last five solvers support both dense and sparse data. However, only ‘sag’ and ‘sparse_cg’ supports sparse input when fit_intercept is True.

New in version 0.17: Stochastic Average Gradient descent solver.
New in version 0.19: SAGA solver.

max_iter [int, default=None] Maximum number of iterations for conjugate gradient solver. For the ‘sparse_cg’ and ‘lsqr’ solvers, the default value is determined by scipy.sparse.linalg. For ‘sag’ and saga solver, the default value is 1000.
tol [float, default=1e-3] Precision of the solution.
verbose [int, default=0] Verbosity level. Setting verbose > 0 will display additional information depending on the solver used.
random_state [int, RandomState instance, default=None] Used when solver == ‘sag’ or ‘saga’ to shuffle the data. See Glossary for details.
return_n_iter [bool, default=False] If True, the method also returns n_iter, the actual number of iteration performed by the solver.

New in version 0.17.
return_intercept [bool, default=False] If True and if X is sparse, the method also returns the intercept, and the solver is automatically changed to ‘sag’. This is only a temporary fix for fitting the intercept with sparse data. For dense data, use sklearn.linear_model._preprocess_data before your regression.

New in version 0.17.
check_input [bool, default=True] If False, the input arrays X and y will not be checked.

New in version 0.21.

Returns

coef [ndarray of shape (n_features,) or (n_targets, n_features)] Weight vector(s).
n_iter [int, optional] The actual number of iteration performed by the solver. Only returned if return_n_iter is True.
intercept [float or ndarray of shape (n_targets,)] The intercept of the model. Only returned if return_intercept is True and if X is a scipy sparse array.
Notes

This function won’t compute the intercept.

7.23 sklearn.manifold: Manifold Learning

The sklearn.manifold module implements data embedding techniques.

User guide: See the Manifold learning section for further details.

| manifold.Isomap(*[, n_neighbors, ...]) | Isomap Embedding |
| manifold.LocallyLinearEmbedding(*[, ...]) | Locally Linear Embedding |
| manifold.MDS([n_components, metric, n_init, ...]) | Multidimensional scaling. |
| manifold.SpectralEmbedding([n_components, ...]) | Spectral embedding for non-linear dimensionality reduction. |
| manifold.TSNE([n_components, perplexity, ...]) | t-distributed Stochastic Neighbor Embedding. |

7.23.1 sklearn.manifold.Isomap

class sklearn.manifold.Isomap(*, n_neighbors=5, n_components=2, eigen_solver='auto', tol=0, max_iter=None, path_method='auto', neighbors_algorithm='auto', n_jobs=None, metric='minkowski', p=2, metric_params=None)

Isomap Embedding

Non-linear dimensionality reduction through Isometric Mapping

Read more in the User Guide.

Parameters

n_neighbors [int, default=5] number of neighbors to consider for each point.
n_components [int, default=2] number of coordinates for the manifold
eigen_solver [{‘auto’, ‘arpack’, ‘dense’}, default=’auto’] ‘auto’ : Attempt to choose the most efficient solver for the given problem.

‘arpack’ : Use Arnoldi decomposition to find the eigenvalues and eigenvectors.
‘dense’ : Use a direct solver (i.e. LAPACK) for the eigenvalue decomposition.
tol [float, default=0] Convergence tolerance passed to arpack or lobpcg. not used if eigen_solver == ‘dense’.
max_iter [int, default=None] Maximum number of iterations for the arpack solver. not used if eigen_solver == ‘dense’.

‘auto’ : attempt to choose the best algorithm automatically.
‘FW’ : Floyd-Warshall algorithm.
‘D’ : Dijkstra’s algorithm.
n_jobs [int or None, default=None] The number of parallel jobs to run. None means 1 unless in a \texttt{joblib.parallel_backend} context. \texttt{-1} means using all processors. See \texttt{Glossary} for more details.

metric [string, or callable, default=“minkowski”] The metric to use when calculating distance between instances in a feature array. If metric is a string or callable, it must be one of the options allowed by \texttt{sklearn.metrics.pairwise_distances} for its metric parameter. If metric is “precomputed”, \(X\) is assumed to be a distance matrix and must be square. \(X\) may be a \texttt{Glossary}.

New in version 0.22.

p [int, default=2] Parameter for the Minkowski metric from \texttt{sklearn.metrics.pairwise.pairwise_distances}. When \(p = 1\), this is equivalent to using \texttt{manhattan_distance} (L1), and \texttt{euclidean_distance} (L2) for \(p = 2\). For arbitrary \(p\), \texttt{minkowski_distance} (L_p) is used.

New in version 0.22.

metric_params [dict, default=None] Additional keyword arguments for the metric function.

New in version 0.22.

Attributes

\texttt{embedding_} [array-like, shape (n_samples, n_components)] Stores the embedding vectors.

\texttt{kernel_pca_} [object] \texttt{KernelPCA} object used to implement the embedding.

\texttt{nbrs_} [sklearn.neighbors.NearestNeighbors instance] Stores nearest neighbors instance, including BallTree or KDtree if applicable.

\texttt{dist_matrix_} [array-like, shape (n_samples, n_samples)] Stores the geodesic distance matrix of training data.

References

[1]

Examples

```
>>> from sklearn.datasets import load_digits
>>> from sklearn.manifold import Isomap
>>> X, _ = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)
>>> embedding = Isomap(n_components=2)
>>> X_transformed = embedding.fit_transform(X[:100])
>>> X_transformed.shape
(100, 2)
```
Methods

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<td><code>fit(X[, y])</code></td>
<td>Compute the embedding vectors for data X</td>
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<td><code>fit_transform(X[, y])</code></td>
<td>Fit the model from data in X and transform X.</td>
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<td>Transform X.</td>
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**fit** \( (X, y=\text{None}) \)

Compute the embedding vectors for data X

**Parameters**

- **X** \( \{\text{array-like, sparse graph, BallTree, KDTree, NearestNeighbors}\} \) Sample data, shape = \((n\_\text{samples}, n\_\text{features})\), in the form of a numpy array, sparse graph, precomputed tree, or NearestNeighbors object.
- **y** \( \text{[Ignored]} \)

**Returns**

- **self** \( \text{[returns an instance of self.]} \)

**fit_transform** \( (X, y=\text{None}) \)

Fit the model from data in X and transform X.

**Parameters**

- **X** \( \{\text{array-like, sparse graph, BallTree, KDTree}\} \) Training vector, where \( n\_\text{samples} \) in the number of samples and \( n\_\text{features} \) is the number of features.
- **y** \( \text{[Ignored]} \)

**Returns**

- **X\_new** \( \{\text{array-like, shape (n\_samples, n\_components)}\} \)

**get_params** \( \text{deep=True} \)

Get parameters for this estimator.

**Parameters**

- **deep** \( \{\text{bool, default=True}\} \) If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** \( \{\text{dict}\} \) Parameter names mapped to their values.

**reconstruction_error**

Compute the reconstruction error for the embedding.

**Returns**

- **reconstruction_error** \( \{\text{float}\} \)
Notes

The cost function of an isomap embedding is

\[ E = \text{frobenius\_norm}[K(D) - K(D_{\text{fit}})] / n_{\text{samples}} \]

Where \( D \) is the matrix of distances for the input data \( X \), \( D_{\text{fit}} \) is the matrix of distances for the output embedding \( X_{\text{fit}} \), and \( K \) is the isomap kernel:

\[ K(D) = -0.5 \times (I - 1/n_{\text{samples}}) \times D^2 \times (I - 1/n_{\text{samples}}) \]

**set_params(**\*params\*)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it's possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**\((X)\)

Transform \( X \).

This is implemented by linking the points \( X \) into the graph of geodesic distances of the training data. First the \( n_{\text{neighbors}} \) nearest neighbors of \( X \) are found in the training data, and from these the shortest geodesic distances from each point in \( X \) to each point in the training data are computed in order to construct the kernel. The embedding of \( X \) is the projection of this kernel onto the embedding vectors of the training set.

**Parameters**

\( X \) [array-like, shape (n_queries, n_features)] If \( \text{neighbors\_algorithm}='\text{precomputed}' \), \( X \) is assumed to be a distance matrix or a sparse graph of shape (n_queries, n_samples_fit).

**Returns**

\( X_{\text{new}} \) [array-like, shape (n_queries, n_components)]

Examples using `sklearn.manifold.Isomap`

- *Release Highlights for scikit-learn 0.22*
- *Comparison of Manifold Learning methods*
- *Manifold Learning methods on a severed sphere*
- *Manifold learning on handwritten digits: Locally Linear Embedding, Isomap…*
7.23.2 `sklearn.manifold.LocallyLinearEmbedding`

```python
class sklearn.manifold.LocallyLinearEmbedding(*, n_neighbors=5, n_components=2, reg=0.001, eigen_solver='auto', tol=1e-06, max_iter=100, method='standard', hessian_tol=0.0001, modified_tol=1e-12, neighbors_algorithm='auto', random_state=None, n_jobs=None)
```

Locally Linear Embedding

Read more in the User Guide.

Parameters

- **n_neighbors** [int, default=5] number of neighbors to consider for each point.
- **n_components** [int, default=2] number of coordinates for the manifold
- **reg** [float, default=1e-3] regularization constant, multiplies the trace of the local covariance matrix of the distances.
- **eigen_solver** ['auto', 'arpack', 'dense'], default='auto' auto : algorithm will attempt to choose the best method for input data
  - **arpack** [use arnoldi iteration in shift-invert mode.] For this method, M may be a dense matrix, sparse matrix, or general linear operator. Warning: ARPACK can be unstable for some problems. It is best to try several random seeds in order to check results.
  - **dense** [use standard dense matrix operations for the eigenvalue decomposition. For this method, M must be an array or matrix type. This method should be avoided for large problems.
- **tol** [float, default=1e-6] Tolerance for 'arpack' method Not used if eigen_solver=='dense'.
- **max_iter** [int, default=100] maximum number of iterations for the arpack solver. Not used if eigen_solver=='dense'.
- **method** ['standard', 'hessian', 'modified', 'ltsa'], default='standard' standard [use the standard locally linear embedding algorithm. see reference [1]
  - **hessian** [use the Hessian eigenmap method. This method requires] n_neighbors > n_components * (1 + (n_components + 1) / 2 see reference [2]
  - **modified** [use the modified locally linear embedding algorithm.] see reference [3]
  - **ltsa** [use local tangent space alignment algorithm] see reference [4]
- **hessian_tol** [float, default=1e-4] Tolerance for Hessian eigenmapping method. Only used if method == 'hessian'
- **modified_tol** [float, default=1e-12] Tolerance for modified LLE method. Only used if method == 'modified'
- **neighbors_algorithm** ['auto', 'brute', 'kd_tree', 'ball_tree'], default='auto' algorithm to use for nearest neighbors search, passed to neighbors.NearestNeighbors instance
- **random_state** [int, RandomState instance, default=None] Determines the random number generator when eigen_solver == 'arpack'. Pass an int for reproducible results across multiple function calls. See `Glossary <random_state>`.
- **n_jobs** [int or None, default=None] The number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See `Glossary` for more details.
Attributes

- **embedding_** [array-like, shape [n_samples, n_components]] Stores the embedding vectors.
- **reconstruction_error_** [float] Reconstruction error associated with **embedding_**.
- **nbrs_** [NearestNeighbors object] Stores nearest neighbors instance, including BallTree or KDtree if applicable.

References

[1], [2], [3], [4]

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.manifold import LocallyLinearEmbedding
>>> X, _ = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)
>>> embedding = LocallyLinearEmbedding(n_components=2)
>>> X_transformed = embedding.fit_transform(X[:100])
>>> X_transformed.shape
(100, 2)
```

Methods

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<td>fit(X, y=None)</td>
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<tr>
<td>fit_transform(X, y=None)</td>
<td>Compute the embedding vectors for data X and transform X.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
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<td>transform(X)</td>
<td>Transform new points into embedding space.</td>
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**fit (X, y=None)**

Compute the embedding vectors for data X.

**Parameters**

- X [array-like of shape [n_samples, n_features]] training set.
- y [Ignored]

**Returns**

- self [returns an instance of self.]

**fit_transform (X, y=None)**

Compute the embedding vectors for data X and transform X.

**Parameters**

- X [array-like of shape [n_samples, n_features]] training set.
- y [Ignored]

**Returns**
get_params

Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Transform new points into embedding space.

Parameters

X [array-like of shape (n_samples, n_features)]

Returns

X_new [array, shape = [n_samples, n_components]]

Notes

Because of scaling performed by this method, it is discouraged to use it together with methods that are not scale-invariant (like SVMs)

Examples using sklearn.manifold.LocallyLinearEmbedding

- Visualizing the stock market structure
- Comparison of Manifold Learning methods
- Manifold Learning methods on a severed sphere
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...
Multidimensional scaling.

Read more in the User Guide.

Parameters

- **n_components** [int, default=2] Number of dimensions in which to immerse the dissimilarities.
- **metric** [bool, default=True] If True, perform metric MDS; otherwise, perform nonmetric MDS.
- **n_init** [int, default=4] Number of times the SMACOF algorithm will be run with different initializations. The final results will be the best output of the runs, determined by the run with the smallest final stress.
- **max_iter** [int, default=300] Maximum number of iterations of the SMACOF algorithm for a single run.
- **verbose** [int, default=0] Level of verbosity.
- **eps** [float, default=1e-3] Relative tolerance with respect to stress at which to declare convergence.
- **n_jobs** [int, default=None] The number of jobs to use for the computation. If multiple initializations are used (n_init), each run of the algorithm is computed in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.
- **random_state** [int, RandomState instance or None, default=None] Determines the random number generator used to initialize the centers. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.
- **dissimilarity** [‘euclidean’, ‘precomputed’], default=’euclidean’] Dissimilarity measure to use:
  - ‘euclidean’: Pairwise Euclidean distances between points in the dataset.
  - ‘precomputed’: Pre-computed dissimilarities are passed directly to fit and fit_transform.

Attributes

- **embedding_** [ndarray of shape (n_samples, n_components)] Stores the position of the dataset in the embedding space.
- **stress_** [float] The final value of the stress (sum of squared distance of the disparities and the distances for all constrained points).
- **dissimilarity_matrix_** [ndarray of shape (n_samples, n_samples)] Pairwise dissimilarities between the points. Symmetric matrix that:
  - either uses a custom dissimilarity matrix by setting dissimilarity to ‘precomputed’;
  - or constructs a dissimilarity matrix from data using Euclidean distances.
- **n_iter_** [int] The number of iterations corresponding to the best stress.
References


“Nonmetric multidimensional scaling: a numerical method” Kruskal, J. Psychometrika, 29 (1964)

“Multidimensional scaling by optimizing goodness of fit to a nonmetric hypothesis” Kruskal, J. Psychometrika, 29, (1964)

Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.manifold import MDS

>>> X, _ = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)

>>> embedding = MDS(n_components=2)
>>> X_transformed = embedding.fit_transform(X[:100])
>>> X_transformed.shape
(100, 2)
```

Methods

**fit**(X[, y, init]) Computes the position of the points in the embedding space.

**fit_transform**(X[, y, init]) Fit the data from X, and returns the embedded coordinates.

**get_params**(deep) Get parameters for this estimator.

**set_params**(**params) Set the parameters of this estimator.

**fit** *(X, y=None, init=None)*

Computes the position of the points in the embedding space.

**Parameters**

- **X**: [array-like of shape (n_samples, n_features) or (n_samples, n_samples)] Input data. If `dissimilarity='precomputed'`, the input should be the dissimilarity matrix.
- **y**: [Ignored]
- **init**: [ndarray of shape (n_samples,)], default=None] Starting configuration of the embedding to initialize the SMACOF algorithm. By default, the algorithm is initialized with a randomly chosen array.

**fit_transform** *(X, y=None, init=None)*

Fit the data from X, and returns the embedded coordinates.

**Parameters**

- **X**: [array-like of shape (n_samples, n_features) or (n_samples, n_samples)] Input data. If `dissimilarity='precomputed'`, the input should be the dissimilarity matrix.
- **y**: [Ignored]
- **init**: [ndarray of shape (n_samples,), default=None] Starting configuration of the embedding to initialize the SMACOF algorithm. By default, the algorithm is initialized with a randomly chosen array.
to initialize the SMACOF algorithm. By default, the algorithm is initialized with a randomly chosen array.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.manifold.MDS**

- Comparison of Manifold Learning methods
- Multi-dimensional scaling
- Manifold Learning methods on a severed sphere
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap…

### 7.23.4 sklearn.manifold.SpectralEmbedding

**class** sklearn.manifold.SpectralEmbedding *(n_components=2, *, affinity='nearest_neighbors', gamma=None, random_state=None, eigen_solver=None, n_neighbors=None, n_jobs=None)*

Spectral embedding for non-linear dimensionality reduction.

Forms an affinity matrix given by the specified function and applies spectral decomposition to the corresponding graph laplacian. The resulting transformation is given by the value of the eigenvectors for each data point.

Note: Laplacian Eigenmaps is the actual algorithm implemented here.

Read more in the *User Guide*.

**Parameters**

- **n_components** [int, default=2] The dimension of the projected subspace.
- **affinity** [‘nearest_neighbors’, ‘rbf’, ‘precomputed’, ‘precomputed_nearest_neighbors’] or callable, default=‘nearest_neighbors’

How to construct the affinity matrix.
• 'nearest_neighbors': construct the affinity matrix by computing a graph of nearest neighbors.
• 'rbf': construct the affinity matrix by computing a radial basis function (RBF) kernel.
• 'precomputed': interpret X as a precomputed affinity matrix.
• 'precomputed_nearest_neighbors': interpret X as a sparse graph of precomputed nearest neighbors, and constructs the affinity matrix by selecting the n_neighbors nearest neighbors.
• callable: use passed in function as affinity the function takes in data matrix (n_samples, n_features) and return affinity matrix (n_samples, n_samples).

gamma [float, default=None] Kernel coefficient for rbf kernel. If None, gamma will be set to 1/n_features.

random_state [int, RandomState instance or None, default=None] Determines the random number generator used for the initialization of the lobpcg eigenvectors when solver == 'amg'. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

eigen_solver [{‘arpack’, ‘lobpcg’, ‘amg’}, default=None] The eigenvalue decomposition strategy to use. AMG requires pyamg to be installed. It can be faster on very large, sparse problems. If None, then ‘arpack’ is used.

n_neighbors [int, default=None] Number of nearest neighbors for nearest_neighbors graph building. If None, n_neighbors will be set to max(n_samples/10, 1).

n_jobs [int, default=None] The number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

embedding_ [ndarray of shape (n_samples, n_components)] Spectral embedding of the training matrix.

affinity_matrix_ [ndarray of shape (n_samples, n_samples)] Affinity_matrix constructed from samples or precomputed.

n_neighbors_ [int] Number of nearest neighbors effectively used.

References


Examples

```python
>>> from sklearn.datasets import load_digits
>>> from sklearn.manifold import SpectralEmbedding

>>> X, _ = load_digits(return_X_y=True)
>>> X.shape
(1797, 64)

>>> embedding = SpectralEmbedding(n_components=2)
>>> X_transformed = embedding.fit_transform(X[:100])

Methods

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<tr>
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<th>Description</th>
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<tr>
<td><code>fit(X[, y])</code></td>
<td>Fit the model from data in X.</td>
</tr>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Fit the model from data in X and transform X.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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</table>

**fit** *(X, y=∇None)*

Fit the model from data in X.

Parameters

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)]
  Training vector, where n_samples is the number of samples and n_features is the number of features.

  If affinity is “precomputed” X : {array-like, sparse matrix}, shape (n_samples, n_samples),
  Interpret X as precomputed adjacency graph computed from samples.

- **y** [Ignored]

Returns

- **self** [object]
  Returns the instance itself.

**fit_transform** *(X, y=∇None)*

Fit the model from data in X and transform X.

Parameters

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)]
  Training vector, where n_samples is the number of samples and n_features is the number of features.

  If affinity is “precomputed” X : {array-like, sparse matrix} of shape (n_samples, n_samples),
  Interpret X as precomputed adjacency graph computed from samples.

- **y** [Ignored]

Returns

- **X_new** [array-like of shape (n_samples, n_components)]

**get_params**(deep=∇True)

Get parameters for this estimator.

Parameters

- **deep** [bool, default=∇True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
Returns

params [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.manifold.SpectralEmbedding

- Various Agglomerative Clustering on a 2D embedding of digits
- Comparison of Manifold Learning methods
- Manifold Learning methods on a severed sphere
- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...

7.23.5 sklearn.manifold.TSNE

class sklearn.manifold.TSNE (n_components=2, *, perplexity=30.0, early_exaggeration=12.0, learning_rate=200.0, n_iter=1000, n_iter_without_progress=300, min_grad_norm=1e-07, metric='euclidean', init='random', verbose=0, random_state=None, method='barnes_hut', angle=0.5, n_jobs=None, square_distances='legacy')

t-distributed Stochastic Neighbor Embedding.

t-SNE [1] is a tool to visualize high-dimensional data. It converts similarities between data points to joint probabilities and tries to minimize the Kullback-Leibler divergence between the joint probabilities of the low-dimensional embedding and the high-dimensional data. t-SNE has a cost function that is not convex, i.e. with different initializations we can get different results.

It is highly recommended to use another dimensionality reduction method (e.g. PCA for dense data or TruncatedSVD for sparse data) to reduce the number of dimensions to a reasonable amount (e.g. 50) if the number of features is very high. This will suppress some noise and speed up the computation of pairwise distances between samples. For more tips see Laurens van der Maaten’s FAQ [2].

Read more in the User Guide.

Parameters

n_components [int, default=2] Dimension of the embedded space.

perplexity [float, default=30.0] The perplexity is related to the number of nearest neighbors that is used in other manifold learning algorithms. Larger datasets usually require a larger perplexity. Consider selecting a value between 5 and 50. Different values can result in significantly different results.
**early_exaggeration** [float, default=12.0] Controls how tight natural clusters in the original space are in the embedded space and how much space will be between them. For larger values, the space between natural clusters will be larger in the embedded space. Again, the choice of this parameter is not very critical. If the cost function increases during initial optimization, the early exaggeration factor or the learning rate might be too high.

**learning_rate** [float, default=200.0] The learning rate for t-SNE is usually in the range [10.0, 1000.0]. If the learning rate is too high, the data may look like a ‘ball’ with any point approximately equidistant from its nearest neighbours. If the learning rate is too low, most points may look compressed in a dense cloud with few outliers. If the cost function gets stuck in a bad local minimum increasing the learning rate may help.

**n_iter** [int, default=1000] Maximum number of iterations for the optimization. Should be at least 250.

**n_iter_without_progress** [int, default=300] Maximum number of iterations without progress before we abort the optimization, used after 250 initial iterations with early exaggeration. Note that progress is only checked every 50 iterations so this value is rounded to the next multiple of 50.

New in version 0.17: parameter `n_iter_without_progress` to control stopping criteria.

**min_grad_norm** [float, default=1e-7] If the gradient norm is below this threshold, the optimization will be stopped.

**metric** [str or callable, default=’euclidean’] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options allowed by scipy.spatial.distance.pdist for its metric parameter, or a metric listed in pairwise.PAIRWISE_DISTANCE_FUNCTIONS. If metric is “precomputed”, X is assumed to be a distance matrix. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays from X as input and return a value indicating the distance between them. The default is “euclidean” which is interpreted as squared euclidean distance.

**init** [{'random', 'pca'} or ndarray of shape (n_samples, n_components), default='random'] Initialization of embedding. Possible options are ‘random’, ‘pca’, and a numpy array of shape (n_samples, n_components). PCA initialization cannot be used with precomputed distances and is usually more globally stable than random initialization.

**verbose** [int, default=0] Verbosity level.

**random_state** [int, RandomState instance or None, default=None] Determines the random number generator. Pass an int for reproducible results across multiple function calls. Note that different initializations might result in different local minima of the cost function. See :term: Glossary <random_state>.

**method** [str, default='barnes_hut'] By default the gradient calculation algorithm uses Barnes-Hut approximation running in O(NlogN) time. method='exact' will run on the slower, but exact, algorithm in O(N^2) time. The exact algorithm should be used when nearest-neighbor errors need to be better than 3%. However, the exact method cannot scale to millions of examples.

New in version 0.17: Approximate optimization `method` via the Barnes-Hut.

**angle** [float, default=0.5] Only used if method='barnes_hut' This is the trade-off between speed and accuracy for Barnes-Hut T-SNE. ‘angle’ is the angular size (referred to as theta in [3]) of a distant node as measured from a point. If this size is below ‘angle’ then it is used as a summary node of all points contained within it. This method is not very sensitive to changes in this parameter in the range of 0.2 - 0.8. Angle less than 0.2 has quickly increasing computation time and angle greater 0.8 has quickly increasing error.
n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. This parameter has no impact when metric="precomputed" or (metric="euclidean" and method="exact"). None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

New in version 0.22.
	square_distances [True or ‘legacy’, default='legacy'] Whether TSNE should square the distance values. 'legacy' means that distance values are squared only when metric="euclidean". True means that distance values are squared for all metrics.

New in version 0.24: Added to provide backward compatibility during deprecation of legacy squaring behavior.

Deprecated since version 0.24: Legacy squaring behavior was deprecated in 0.24. The 'legacy' value will be removed in 1.1 (renaming of 0.26), at which point the default value will change to True.

Attributes

embedding_ [array-like of shape (n_samples, n_components)] Stores the embedding vectors.

kl_divergence_ [float] Kullback-Leibler divergence after optimization.

n_iter_ [int] Number of iterations run.

References


Examples

```python
>>> import numpy as np
>>> from sklearn.manifold import TSNE
>>> X = np.array([[0, 0, 0], [0, 1, 1], [1, 0, 1], [1, 1, 1]])
>>> X_embedded = TSNE(n_components=2).fit_transform(X)
>>> X_embedded.shape
(4, 2)
```

Methods

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<tr>
<th>Method</th>
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<tr>
<td>fit(X[, y])</td>
<td>Fit X into an embedded space.</td>
</tr>
<tr>
<td>fit_transform(X[, y])</td>
<td>Fit X into an embedded space and return that transformed output.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

```python
>>> fit(X, y=None)
Fit X into an embedded space.
```
Parameters

X [ndarray of shape (n_samples, n_features) or (n_samples, n_samples)] If the metric is ‘precomputed’ X must be a square distance matrix. Otherwise it contains a sample per row. If the method is ‘exact’, X may be a sparse matrix of type ‘csr’, ‘csc’ or ‘coo’. If the method is ‘barnes_hut’ and the metric is ‘precomputed’, X may be a precomputed sparse graph.

y [Ignored]

**fit_transform**(X, y=None)
Fit X into an embedded space and return that transformed output.

Parameters

X [ndarray of shape (n_samples, n_features) or (n_samples, n_samples)] If the metric is ‘precomputed’ X must be a square distance matrix. Otherwise it contains a sample per row. If the method is ‘exact’, X may be a sparse matrix of type ‘csr’, ‘csc’ or ‘coo’. If the method is ‘barnes_hut’ and the metric is ‘precomputed’, X may be a precomputed sparse graph.

y [Ignored]

Returns

X_new [ndarray of shape (n_samples, n_components)] Embedding of the training data in low-dimensional space.

**get_params**(deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**set_params**(**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.manifold.TSNE`

- Approximate nearest neighbors in TSNE

```python
manifold.locally_linear_embedding(X, *, ...
...)
```
Perform a Locally Linear Embedding analysis on the data.

```python
manifold.smacof(dissimilarities, *
..., . . .)
```
Computes multidimensional scaling using the SMACOF algorithm.

```python
manifold.spectral_embedding(adjacency, *
..., . . .)
```
Project the sample on the first eigenvectors of the graph Laplacian.

```python
manifold.trustworthiness(X, X_embedded,
..., . . .)
```
Expresses to what extent the local structure is retained.

### 7.23.6 sklearn.manifold.locally_linear_embedding

`sklearn.manifold.locally_linear_embedding(X, *, n_neighbors, n_components, reg=0.001,
eigen_solver=’auto’, tol=1e-06, max_iter=100,
method=’standard’, hessian_tol=0.0001,
modified_tol=1e-12, random_state=None,
n_jobs=None)`

Perform a Locally Linear Embedding analysis on the data. Read more in the User Guide.

**Parameters**

- **X** ([array-like, NearestNeighbors]) Sample data, shape = (n_samples, n_features), in the form of a numpy array or a NearestNeighbors object.
- **n_neighbors** [int] number of neighbors to consider for each point.
- **n_components** [int] number of coordinates for the manifold.
- **reg** [float, default=1e-3] regularization constant, multiplies the trace of the local covariance matrix of the distances.
- **eigen_solver** [‘auto’, ‘arpack’, ‘dense’], default=’auto’ auto : algorithm will attempt to choose the best method for input data
  - **arpack** use arnoldi iteration in shift-invert mode. For this method, M may be a dense matrix, sparse matrix, or general linear operator. Warning: ARPACK can be unstable for some problems. It is best to try several random seeds in order to check results.
  - **dense** use standard dense matrix operations for the eigenvalue decomposition. For this method, M must be an array or matrix type. This method should be avoided for large problems.
- **tol** [float, default=1e-6] Tolerance for ‘arpack’ method Not used if eigen_solver==’dense’.
- **max_iter** [int, default=100] maximum number of iterations for the arpack solver.
- **method** [‘standard’, ‘hessian’, ‘modified’, ‘ltsa’], default=’standard’
  - **standard** use the standard locally linear embedding algorithm. see reference [1]
  - **hessian** use the Hessian eigenmap method. This method requires n_neighbors > n_components * (1 + (n_components + 1) / 2. see reference [2]
  - **modified** use the modified locally linear embedding algorithm. see reference [3]
ltsa [use local tangent space alignment algorithm] see reference [4]

hessian_tol [float, default=1e-4] Tolerance for Hessian eigenmapping method. Only used if method == 'hessian'

modified_tol [float, default=1e-12] Tolerance for modified LLE method. Only used if method == ‘modified’


n_jobs [int or None, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Returns

Y [array-like, shape [n_samples, n_components]] Embedding vectors.

squared_error [float] Reconstruction error for the embedding vectors. Equivalent to norm(Y - W Y, 'fro')**2, where W are the reconstruction weights.

References

[1], [2], [3], [4]

Examples using sklearn.manifold.locally_linear_embedding

• Swiss Roll reduction with LLE

7.23.7 sklearn.manifold.smacof

sklearn.manifold.smacof (dissimilarities, *, metric=True, n_components=2, init=None, n_init=8, n_jobs=None, max_iter=300, verbose=0, eps=0.001, random_state=None, return_n_iter=False)

Computes multidimensional scaling using the SMACOF algorithm.

The SMACOF (Scaling by MAjorizing a COmplicated Function) algorithm is a multidimensional scaling algorithm which minimizes an objective function (the stress) using a majorization technique. Stress majorization, also known as the Guttman Transform, guarantees a monotone convergence of stress, and is more powerful than traditional techniques such as gradient descent.

The SMACOF algorithm for metric MDS can summarized by the following steps:

1. Set an initial start configuration, randomly or not.
2. Compute the stress
3. Compute the Guttman Transform
4. Iterate 2 and 3 until convergence.

The nonmetric algorithm adds a monotonic regression step before computing the stress.

Parameters

dissimilarities [ndarray of shape (n_samples, n_samples)] Pairwise dissimilarities between the points. Must be symmetric.
**metric** [bool, default=True] Compute metric or nonmetric SMACOF algorithm.

**n_components** [int, default=2] Number of dimensions in which to immerse the dissimilarities. If an *init* array is provided, this option is overridden and the shape of *init* is used to determine the dimensionality of the embedding space.

**init** [ndarray of shape (n_samples, n_components), default=None] Starting configuration of the embedding to initialize the algorithm. By default, the algorithm is initialized with a randomly chosen array.

**n_init** [int, default=8] Number of times the SMACOF algorithm will be run with different initializations. The final results will be the best output of the runs, determined by the run with the smallest final stress. If *init* is provided, this option is overridden and a single run is performed.

**n_jobs** [int, default=None] The number of jobs to use for the computation. If multiple initializations are used (*n_init*), each run of the algorithm is computed in parallel.

None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**max_iter** [int, default=300] Maximum number of iterations of the SMACOF algorithm for a single run.

**verbose** [int, default=0] Level of verbosity.

**eps** [float, default=1e-3] Relative tolerance with respect to stress at which to declare convergence.

**random_state** [int, RandomState instance or None, default=None] Determines the random number generator used to initialize the centers. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

**return_n_iter** [bool, default=False] Whether or not to return the number of iterations.

**Returns**

**X** [ndarray of shape (n_samples, n_components)] Coordinates of the points in a n_components-space.

**stress** [float] The final value of the stress (sum of squared distance of the disparities and the distances for all constrained points).

**n_iter** [int] The number of iterations corresponding to the best stress. Returned only if return_n_iter is set to True.

**Notes**


“Nonmetric multidimensional scaling: a numerical method” Kruskal, J. Psychometrika, 29 (1964)

“Multidimensional scaling by optimizing goodness of fit to a nonmetric hypothesis” Kruskal, J. Psychometrika, 29, (1964)
7.23.8 sklearn.manifold.spectral_embedding

sklearn.manifold.spectral_embedding(adjacency, *, n_components=8, eigen_solver=None, random_state=None, norm_laplacian=True, drop_first=True)

Project the sample on the first eigenvectors of the graph Laplacian.

The adjacency matrix is used to compute a normalized graph Laplacian whose spectrum (especially the eigenvectors associated to the smallest eigenvalues) has an interpretation in terms of minimal number of cuts necessary to split the graph into comparably sized components.

This embedding can also 'work' even if the adjacency variable is not strictly the adjacency matrix of a graph but more generally an affinity or similarity matrix between samples (for instance the heat kernel of a euclidean distance matrix or a k-NN matrix).

However care must taken to always make the affinity matrix symmetric so that the eigenvector decomposition works as expected.

Note : Laplacian Eigenmaps is the actual algorithm implemented here.

Read more in the User Guide.

Parameters

- **adjacency** [{array-like, sparse graph} of shape (n_samples, n_samples)] The adjacency matrix of the graph to embed.
- **n_components** [int, default=8] The dimension of the projection subspace.
- **eigen_solver** [{'arpack', 'lobpcg', 'amg'}, default=None] The eigenvalue decomposition strategy to use. AMG requires pyamg to be installed. It can be faster on very large, sparse problems, but may also lead to instabilities. If None, then 'arpack' is used.
- **random_state** [int, RandomState instance or None, default=None] Determines the random number generator used for the initialization of the lobpcg eigenvectors decomposition when solver == 'amg'. Pass an int for reproducible results across multiple function calls. See :term: Glossary.<random_state>.
- **eigen_tol** [float, default=0.0] Stopping criterion for eigendecomposition of the Laplacian matrix when using arpack eigen_solver.
- **norm_laplacian** [bool, default=True] If True, then compute normalized Laplacian.
- **drop_first** [bool, default=True] Whether to drop the first eigenvector. For spectral embedding, this should be True as the first eigenvector should be constant vector for connected graph, but for spectral clustering, this should be kept as False to retain the first eigenvector.

Returns

- **embedding** [ndarray of shape (n_samples, n_components)] The reduced samples.
Notes

Spectral Embedding (Laplacian Eigenmaps) is most useful when the graph has one connected component. If there are many components, the first few eigenvectors will simply uncover the connected components of the graph.

References

- Toward the Optimal Preconditioned Eigensolver: Locally Optimal Block Preconditioned Conjugate Gradient Method Andrew V. Knyazev https://doi.org/10.1137%2FS1064827500366124

7.23.9 `sklearn.manifold.trustworthiness`

`sklearn.manifold.trustworthiness` \((X, X_{\text{embedded}}, *, n_{\text{neighbors}}=5, \text{metric}='\text{euclidean}')\)

Expresses to what extent the local structure is retained.

The trustworthiness is within \([0, 1]\). It is defined as

\[
T(k) = 1 - \frac{2}{nk(2n - 3k - 1)} \sum_{i=1}^{n} \sum_{j \in N_i^k} \max(0, (r(i, j) - k))
\]

where for each sample \(i\), \(N_i^k\) are its \(k\) nearest neighbors in the output space, and every sample \(j\) is its \(r(i, j)\)-th nearest neighbor in the input space. In other words, any unexpected nearest neighbors in the output space are penalised in proportion to their rank in the input space.

- “Neighborhood Preservation in Nonlinear Projection Methods: An Experimental Study” J. Venna, S. Kaski
- “Learning a Parametric Embedding by Preserving Local Structure” L.J.P. van der Maaten

Parameters

- **X** [ndarray of shape (n_samples, n_features) or (n_samples, n_samples)] If the metric is ‘precomputed’ \(X\) must be a square distance matrix. Otherwise it contains a sample per row.

- **X_{\text{embedded}}** [ndarray of shape (n_samples, n_components)] Embedding of the training data in low-dimensional space.

- **n_{\text{neighbors}}** [int, default=5] Number of neighbors \(k\) that will be considered.

- **metric** [str or callable, default='euclidean'] Which metric to use for computing pairwise distances between samples from the original input space. If metric is ‘precomputed’, \(X\) must be a matrix of pairwise distances or squared distances. Otherwise, see the documentation of argument metric in sklearn.pairwise.pairwise_distances for a list of available metrics.

New in version 0.20.

Returns

- **trustworthiness** [float] Trustworthiness of the low-dimensional embedding.
7.24 sklearn.metrics: Metrics

See the Metrics and scoring: quantifying the quality of predictions section and the Pairwise metrics, Affinities and Kernels section of the user guide for further details.

The sklearn.metrics module includes score functions, performance metrics and pairwise metrics and distance computations.

### 7.24.1 Model Selection Interface

See the The scoring parameter: defining model evaluation rules section of the user guide for further details.

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**sklearn.metrics.check_scoring**

sklearn.metrics.check_scoring(estimator[, scoring, *...])

Determine scorer from user options.

A TypeError will be thrown if the estimator cannot be scored.

**Parameters**

- estimator [estimator object implementing ‘fit’] The object to use to fit the data.
- scoring [str or callable, default=None] A string (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y).
- allow_none [bool, default=False] If no scoring is specified and the estimator has no score function, we can either return None or raise an exception.

**Returns**

- scoring [callable] A scorer callable object / function with signature scorer(estimator, X, y).

**sklearn.metrics.get_scorer**

sklearn.metrics.get_scorer(scoring)

Get a scorer from string.

Read more in the User Guide.

**Parameters**

- scoring [str or callable] Scoring method as string. If callable it is returned as is.

**Returns**

- scorer [callable] The scorer.
sklearn.metrics.make_scorer

sklearn.metrics.make_scorer(score_func, *, greater_is_better=True, needs_proba=False, needs_threshold=False, **kwargs)

Make a scorer from a performance metric or loss function.

This factory function wraps scoring functions for use in GridSearchCV and cross_val_score. It takes a score function, such as accuracy_score, mean_squared_error, adjusted_rand_index or average_precision and returns a callable that scores an estimator's output. The signature of the call is (estimator, X, y) where estimator is the model to be evaluated, X is the data and y is the ground truth labeling (or None in the case of unsupervised models).

Read more in the User Guide.

Parameters

- **score_func** [callable] Score function (or loss function) with signature `score_func(y, y_pred, **kwargs)`.
- **greater_is_better** [bool, default=True] Whether score_func is a score function (default), meaning high is good, or a loss function, meaning low is good. In the latter case, the scorer object will sign-flip the outcome of the score_func.
- **needs_proba** [bool, default=False] Whether score_func requires predict_proba to get probability estimates out of a classifier.
  
  If True, for binary `y_true`, the score function is supposed to accept a 1D `y_pred` (i.e., probability of the positive class, shape `(n_samples,)`).

  **needs_threshold** [bool, default=False] Whether score_func takes a continuous decision certainty. This only works for binary classification using estimators that have either a decision_function or predict_proba method.
  
  If True, for binary `y_true`, the score function is supposed to accept a 1D `y_pred` (i.e., probability of the positive class or the decision function, shape `(n_samples,)`).

  For example average_precision or the area under the roc curve can not be computed using discrete predictions alone.

- **kwargs** [additional arguments] Additional parameters to be passed to score_func.

Returns

- **scorer** [callable] Callable object that returns a scalar score; greater is better.

Notes

If `needs_proba=False` and `needs_threshold=False`, the score function is supposed to accept the output of `predict`. If `needs_proba=True`, the score function is supposed to accept the output of `predict_proba` (For binary `y_true`, the score function is supposed to accept probability of the positive class).

If `needs_threshold=True`, the score function is supposed to accept the output of `decision_function`.
Examples

```python
>>> from sklearn.metrics import fbeta_score, make_scorer
>>> ftwo_scorer = make_scorer(fbeta_score, beta=2)
>>> ftwo_scorer
make_scorer(fbeta_score, beta=2)
>>> from sklearn.model_selection import GridSearchCV
>>> from sklearn.svm import LinearSVC
>>> grid = GridSearchCV(LinearSVC(), param_grid={'C': [1, 10]},
                      scoring=ftwo_scorer)
```

Examples using `sklearn.metrics.make_scorer`

- Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV

## 7.24.2 Classification metrics

See the Classification metrics section of the user guide for further details.

```python
metrics.accuracy_score(y_true, y_pred, *[, ...])  # Accuracy classification score.
metrics.auc(x, y)  # Compute Area Under the Curve (AUC) using the trapezoidal rule.
metrics.average_precision_score(y_true, *[, ...])  # Compute average precision (AP) from prediction scores.
metrics.balanced_accuracy_score(y_true, *[, ...])  # Compute the balanced accuracy.
metrics.brier_score_loss(y_true, y_prob, *[, eps, ...])  # Compute the Brier score loss.
metrics.classification_report(y_true, y_pred, *[, ...])  # Build a text report showing the main classification metrics.
metrics.cohen_kappa_score(y1, y2, *[, ...])  # Cohen’s kappa: a statistic that measures inter-annotator agreement.
metrics.confusion_matrix(y_true, y_pred, *[, ...])  # Compute confusion matrix to evaluate the accuracy of a classification.
metrics.dcg_score(y_true, y_score, *[, k, ...])  # Compute Discounted Cumulative Gain.
metrics.det_curve(y_true, y_score, *[, ...])  # Compute error rates for different probability thresholds.
metrics.f1_score(y_true, y_pred, *[, ...])  # Compute the F1 score, also known as balanced F-score or F-measure.
metrics.fbeta_score(y_true, y_pred, *[, beta])  # Compute the F-beta score.
metrics.hamming_loss(y_true, y_pred, *[, eps, ...])  # Compute the average Hamming loss.
metrics.hinge_loss(y_true, pred_decision, *[, ...])  # Average hinge loss (non-regularized).
metrics.jaccard_score(y_true, y_pred, *[, eps, ...])  # Jaccard similarity coefficient score.
metrics.log_loss(y_true, y_pred, *[, eps, ...])  # Log loss, aka logistic loss or cross-entropy loss.
metrics.matthews_corrcoef(y_true, y_pred, *[, ...])  # Compute the Matthews correlation coefficient (MCC).
metrics.multilabel_confusion_matrix(y_true, y_pred, *[, ...])  # Compute a confusion matrix for each class or sample.
metrics.ndcg_score(y_true, y_score, *[, k, ...])  # Compute Normalized Discounted Cumulative Gain.
```
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</tr>
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### sklearn.metrics.accuracy_score

**sklearn.metrics.accuracy_score** *(y_true, y_pred, *, normalize=True, sample_weight=None)*

Accuracy classification score.

In multilabel classification, this function computes subset accuracy: the set of labels predicted for a sample must exactly match the corresponding set of labels in y_true.

Read more in the User Guide.

**Parameters**

- **y_true**  [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) labels.
- **y_pred**  [1d array-like, or label indicator array / sparse matrix] Predicted labels, as returned by a classifier.
- **normalize**  [bool, default=True] If False, return the number of correctly classified samples. Otherwise, return the fraction of correctly classified samples.
- **sample_weight**  [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score**  [float] If normalize == True, return the fraction of correctly classified samples (float), else returns the number of correctly classified samples (int).

The best performance is 1 with normalize == True and the number of samples with normalize == False.

See also:

- jaccard_score
- hamming_loss
- zero_one_loss
Notes

In binary and multiclass classification, this function is equal to the `jaccard_score` function.

Examples

```python
>>> from sklearn.metrics import accuracy_score
>>> y_pred = [0, 2, 1, 3]
>>> y_true = [0, 1, 2, 3]
>>> accuracy_score(y_true, y_pred)
0.5
>>> accuracy_score(y_true, y_pred, normalize=False)
2
```

In the multilabel case with binary label indicators:

```python
>>> import numpy as np
>>> accuracy_score(np.array([[0, 1], [1, 1]]), np.ones((2, 2)))
0.5
```

Examples using `sklearn.metrics.accuracy_score`

- Plot classification probability
- Multi-class AdaBoosted Decision Trees
- Probabilistic predictions with Gaussian process classification (GPC)
- Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV
- Importance of Feature Scaling
- Effect of varying threshold for self-training
- Classification of text documents using sparse features

`sklearn.metrics.auc`

`sklearn.metrics.auc(x, y)`

Compute Area Under the Curve (AUC) using the trapezoidal rule.

This is a general function, given points on a curve. For computing the area under the ROC-curve, see `roc_auc_score`. For an alternative way to summarize a precision-recall curve, see `average_precision_score`.

Parameters

- `x` [ndarray of shape (n,)] x coordinates. These must be either monotonic increasing or monotonic decreasing.
- `y` [ndarray of shape, (n,)] y coordinates.

Returns

- `auc` [float]

See also:
roc_auc_score  Compute the area under the ROC curve.

average_precision_score  Compute average precision from prediction scores.

precision_recall_curve  Compute precision-recall pairs for different probability thresholds.

Examples

```python
>>> import numpy as np
>>> from sklearn import metrics

>>> y = np.array([1, 1, 2, 2])
>>> pred = np.array([0.1, 0.4, 0.35, 0.8])
>>> fpr, tpr, thresholds = metrics.roc_curve(y, pred, pos_label=2)
>>> metrics.auc(fpr, tpr)
0.75
```

Examples using sklearn.metrics.auc

- Species distribution modeling
- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
- Receiver Operating Characteristic (ROC) with cross validation
- Receiver Operating Characteristic (ROC)
- Precision-Recall

sklearn.metrics.average_precision_score

sklearn.metrics.average_precision_score(y_true, y_score, *, average='macro', pos_label=1, sample_weight=None)

Compute average precision (AP) from prediction scores.

AP summarizes a precision-recall curve as the weighted mean of precisions achieved at each threshold, with the increase in recall from the previous threshold used as the weight:

\[
AP = \sum_{n} (R_n - R_{n-1}) P_n
\]

where \(P_n\) and \(R_n\) are the precision and recall at the nth threshold [1]. This implementation is not interpolated and is different from computing the area under the precision-recall curve with the trapezoidal rule, which uses linear interpolation and can be too optimistic.

Note: this implementation is restricted to the binary classification task or multilabel classification task.

Read more in the User Guide.

Parameters

- y_true  [ndarray of shape (n_samples,) or (n_samples, n_classes)] True binary labels or binary label indicators.
- y_score  [ndarray of shape (n_samples,) or (n_samples, n_classes)] Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by decision_function on some classifiers).
average [[‘micro’, ‘samples’, ‘weighted’, ‘macro’] or None, default=’macro’] If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

'\textbf{micro}': Calculate metrics globally by considering each element of the label indicator matrix as a label.

'\textbf{macro}': Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.

'\textbf{weighted}': Calculate metrics for each label, and find their average, weighted by support (the number of true instances for each label).

'\textbf{samples}': Calculate metrics for each instance, and find their average.

Will be ignored when \texttt{y_true} is binary.

\textbf{pos_label} [int or str, default=1] The label of the positive class. Only applied to binary \texttt{y_true}. For multilabel-indicator \texttt{y_true}, \texttt{pos_label} is fixed to 1.

\textbf{sample_weight} [array-like of shape (n_samples,), default=None] Sample weights.

\textbf{Returns}

\textbf{average_precision} [float]

See also:

\texttt{roc_auc_score} Compute the area under the ROC curve.

\texttt{precision_recall_curve} Compute precision-recall pairs for different probability thresholds.

\textbf{Notes}

Changed in version 0.19: Instead of linearly interpolating between operating points, precisions are weighted by the change in recall since the last operating point.

\textbf{References}

[1]

\textbf{Examples}

```python
>>> import numpy as np
>>> from sklearn.metrics import average_precision_score
>>> y_true = np.array([0, 0, 1, 1])
>>> y_scores = np.array([0.1, 0.4, 0.35, 0.8])
>>> average_precision_score(y_true, y_scores)
0.83...
```
sklearn.metrics.balanced_accuracy_score

sklearn.metrics.balanced_accuracy_score(y_true, y_pred, *, sample_weight=None, adjusted=False)

Compute the balanced accuracy.

The balanced accuracy in binary and multiclass classification problems to deal with imbalanced datasets. It is defined as the average of recall obtained on each class.

The best value is 1 and the worst value is 0 when adjusted=False.

Read more in the User Guide.

New in version 0.20.

**Parameters**

- `y_true` [1d array-like] Ground truth (correct) target values.
- `y_pred` [1d array-like] Estimated targets as returned by a classifier.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `adjusted` [bool, default=False] When true, the result is adjusted for chance, so that random performance would score 0, and perfect performance scores 1.

**Returns**

- `balanced_accuracy` [float]

**See also:**

recall_score, roc_auc_score

**Notes**

Some literature promotes alternative definitions of balanced accuracy. Our definition is equivalent to accuracy_score with class-balanced sample weights, and shares desirable properties with the binary case. See the User Guide.

**References**

[1], [2]
**Examples**

```python
>>> from sklearn.metrics import balanced_accuracy_score
>>> y_true = [0, 1, 0, 0, 1, 0]
>>> y_pred = [0, 1, 0, 0, 0, 1]
>>> balanced_accuracy_score(y_true, y_pred)
0.625
```

**sklearn.metrics.brier_score_loss**

`sklearn.metrics.brier_score_loss(y_true, y_prob, *, sample_weight=None, pos_label=None)`

Compute the Brier score loss.

The smaller the Brier score loss, the better, hence the naming with “loss”. The Brier score measures the mean squared difference between the predicted probability and the actual outcome. The Brier score always takes on a value between zero and one, since this is the largest possible difference between a predicted probability (which must be between zero and one) and the actual outcome (which can take on values of only 0 and 1). It can be decomposed is the sum of refinement loss and calibration loss.

The Brier score is appropriate for binary and categorical outcomes that can be structured as true or false, but is inappropriate for ordinal variables which can take on three or more values (this is because the Brier score assumes that all possible outcomes are equivalently “distant” from one another). Which label is considered to be the positive label is controlled via the parameter `pos_label`, which defaults to the greater label unless `y_true` is all 0 or all -1, in which case `pos_label` defaults to 1.


**Parameters**

- `y_true` [array of shape (n_samples,)] True targets.
- `y_prob` [array of shape (n_samples,)] Probabilities of the positive class.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `pos_label` [int or str, default=None] Label of the positive class. `pos_label` will be inferred in the following manner:
  - if `y_true` in {-1, 1} or {0, 1}, `pos_label` defaults to 1;
  - else if `y_true` contains string, an error will be raised and `pos_label` should be explicitly specified;
  - otherwise, `pos_label` defaults to the greater label, i.e. `np.unique(y_true)[-1]`.

**Returns**

- `score` [float] Brier score loss.
References

[1]

Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import brier_score_loss
>>> y_true = np.array([0, 1, 1, 0])
>>> y_true_categorical = np.array(['spam', 'ham', 'ham', 'spam'])
>>> y_prob = np.array([0.1, 0.9, 0.8, 0.3])
>>> brier_score_loss(y_true, y_prob)
0.037...
>>> brier_score_loss(y_true, 1-y_prob, pos_label=0)
0.037...
>>> brier_score_loss(y_true_categorical, y_prob, pos_label='ham')
0.037...
>>> brier_score_loss(y_true, np.array(y_prob) > 0.5)
0.0
```

Examples using `sklearn.metrics.brier_score_loss`

- Probability Calibration curves
- Probability calibration of classifiers

`sklearn.metrics.classification_report`

```python
sklearn.metrics.classification_report(y_true, y_pred, *, labels=None, target_names=None, sample_weight=None, digits=2, output_dict=False, zero_division='warn')
```

Build a text report showing the main classification metrics.

Read more in the `User Guide`.

Parameters

- `y_true` [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target values.
- `y_pred` [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by a classifier.
- `labels` [array-like of shape (n_labels,), default=None] Optional list of label indices to include in the report.
- `target_names` [list of str of shape (n_labels,), default=None] Optional display names matching the labels (same order).
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `digits` [int, default=2] Number of digits for formatting output floating point values. When `output_dict` is True, this will be ignored and the returned values will not be rounded.
- `output_dict` [bool, default=False] If True, return output as dict.

New in version 0.20.
**zero_division**  ["warn", 0 or 1, default="warn"]  Sets the value to return when there is a zero division. If set to “warn”, this acts as 0, but warnings are also raised.

**Returns**

**report**  [string / dict]  Text summary of the precision, recall, F1 score for each class. Dictionary returned if `output_dict` is True. Dictionary has the following structure:

```python
{'label 1': {'precision':0.5,
'recall':1.0,
'f1-score':0.67,
'support':1},
'label 2': { ... },
...
}
```

The reported averages include macro average (averaging the unweighted mean per label), weighted average (averaging the support-weighted mean per label), and sample average (only for multilabel classification). Micro average (averaging the total true positives, false negatives and false positives) is only shown for multi-label or multi-class with a subset of classes, because it corresponds to accuracy otherwise and would be the same for all metrics. See also `precision_recall_fscore_support` for more details on averages.

Note that in binary classification, recall of the positive class is also known as “sensitivity”; recall of the negative class is “specificity”.

**See also:**

`precision_recall_fscore_support`, `confusion_matrix`

`multilabel_confusion_matrix`

**Examples**

```python
>>> from sklearn.metrics import classification_report
>>> y_true = [0, 1, 2, 2, 2]
>>> y_pred = [0, 0, 2, 2, 1]
>>> target_names = ['class 0', 'class 1', 'class 2']
>>> print(classification_report(y_true, y_pred, target_names=target_names))
    precision    recall  f1-score   support
  class 0       0.50      1.00      0.67           1
  class 1       0.00      0.00      0.00           1
  class 2       1.00      0.67      0.80           3
    accuracy                          0.60           5
    macro avg  0.50      0.56      0.49           5
   weighted avg  0.70      0.60      0.61           5

>>> y_pred = [1, 1, 0]
>>> y_true = [1, 1, 1]
>>> print(classification_report(y_true, y_pred, labels=[1, 2, 3]))
    precision    recall  f1-score   support
      1           1.00      0.67      0.80           3
      2           0.00      0.00      0.00           0
      3           0.00      0.00      0.00           0
```

(continues on next page)
Examples using `sklearn.metrics.classification_report`

- Recognizing hand-written digits
- Faces recognition example using eigenfaces and SVMs
- Pipeline Anova SVM
- Parameter estimation using grid search with cross-validation
- Restricted Boltzmann Machine features for digit classification
- Column Transformer with Heterogeneous Data Sources
- Label Propagation digits: Demonstrating performance
- Label Propagation digits active learning
- Classification of text documents using sparse features

`sklearn.metrics.cohen_kappa_score`

The function `sklearn.metrics.cohen_kappa_score(y1, y2, *, labels=None, weights=None, sample_weight=None)` computes Cohen’s kappa [1], a score that expresses the level of agreement between two annotators on a classification problem. It is defined as

\[ \kappa = \frac{p_o - p_e}{1 - p_e} \]

where \( p_o \) is the empirical probability of agreement on the label assigned to any sample (the observed agreement ratio), and \( p_e \) is the expected agreement when both annotators assign labels randomly. \( p_e \) is estimated using a per-annotator empirical prior over the class labels [2].

Read more in the [User Guide](#).

**Parameters**

- **y1** [array of shape (n_samples,)] Labels assigned by the first annotator.
- **y2** [array of shape (n_samples,)] Labels assigned by the second annotator. The kappa statistic is symmetric, so swapping \( y1 \) and \( y2 \) doesn’t change the value.
- **labels** [array-like of shape (n_classes,), default=None] List of labels to index the matrix. This may be used to select a subset of labels. If None, all labels that appear at least once in \( y1 \) or \( y2 \) are used.
- **weights** [{‘linear’, ‘quadratic’}, default=None] Weighting type to calculate the score. None means no weighted; “linear” means linear weighted; “quadratic” means quadratic weighted.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

<table>
<thead>
<tr>
<th>metric</th>
<th>micro avg</th>
<th>macro avg</th>
<th>weighted avg</th>
</tr>
</thead>
<tbody>
<tr>
<td>value</td>
<td>1.00</td>
<td>0.67</td>
<td>1.00</td>
</tr>
<tr>
<td>precision</td>
<td>0.80</td>
<td>0.27</td>
<td>0.80</td>
</tr>
<tr>
<td>recall</td>
<td>0.67</td>
<td>0.22</td>
<td>0.67</td>
</tr>
<tr>
<td>support</td>
<td>3</td>
<td>3</td>
<td>3</td>
</tr>
</tbody>
</table>

*(continued from previous page)*
kappa [float] The kappa statistic, which is a number between -1 and 1. The maximum value means complete agreement; zero or lower means chance agreement.

References

[1], [2], [3]

sklearn.metrics.confusion_matrix

sklearn.metrics.confusion_matrix(y_true, y_pred, *, labels=None, sample_weight=None, normalize=None)

Compute confusion matrix to evaluate the accuracy of a classification.

By definition a confusion matrix $C$ is such that $C_{i,j}$ is equal to the number of observations known to be in group $i$ and predicted to be in group $j$.

Thus in binary classification, the count of true negatives is $C_{0,0}$, false negatives is $C_{1,0}$, true positives is $C_{1,1}$ and false positives is $C_{0,1}$.

Read more in the User Guide.

Parameters

- y_true [array-like of shape (n_samples,)] Ground truth (correct) target values.
- y_pred [array-like of shape (n_samples,)] Estimated targets as returned by a classifier.
- labels [array-like of shape (n_classes), default=None] List of labels to index the matrix. This may be used to reorder or select a subset of labels. If None is given, those that appear at least once in y_true or y_pred are used in sorted order.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.
  New in version 0.18.
- normalize [{‘true’, ‘pred’, ‘all’}, default=None] Normalizes confusion matrix over the true (rows), predicted (columns) conditions or all the population. If None, confusion matrix will not be normalized.

Returns

- C [ndarray of shape (n_classes, n_classes)] Confusion matrix whose i-th row and j-th column entry indicates the number of samples with true label being i-th class and predicted label being j-th class.

See also:

plot_confusion_matrix Plot Confusion Matrix.

ConfusionMatrixDisplay Confusion Matrix visualization.
References

[1]

Examples

```python
>>> from sklearn.metrics import confusion_matrix
>>> y_true = [2, 0, 2, 2, 0, 1]
>>> y_pred = [0, 0, 2, 2, 0, 2]
>>> confusion_matrix(y_true, y_pred)
array([[2, 0, 0],
       [1, 0, 1],
       [1, 0, 2]])

>>> y_true = ["cat", "ant", "cat", "ant", "bird"]
>>> y_pred = ["ant", "ant", "cat", "ant", "cat"]
>>> confusion_matrix(y_true, y_pred, labels=["ant", "bird", "cat"])
array([[2, 0, 0],
       [0, 0, 1],
       [1, 0, 2]])
```

In the binary case, we can extract true positives, etc as follows:

```python
>>> tn, fp, fn, tp = confusion_matrix([0, 1, 0, 1], [1, 1, 1, 0]).ravel()
>>> (tn, fp, fn, tp)
(0, 2, 1, 1)
```

Examples using `sklearn.metrics.confusion_matrix`

- Faces recognition example using eigenfaces and SVMs
- Visualizations with Display Objects
- Label Propagation digits: Demonstrating performance
- Label Propagation digits active learning
- Classification of text documents using sparse features

`sklearn.metrics.dcg_score`

`sklearn.metrics.dcg_score(y_true, y_score, *, k=None, log_base=2, sample_weight=None, ignore_ties=False)`

Compute Discounted Cumulative Gain.

Sum the true scores ranked in the order induced by the predicted scores, after applying a logarithmic discount. This ranking metric yields a high value if true labels are ranked high by `y_score`.

Usually the Normalized Discounted Cumulative Gain (NDCG, computed by ndcg_score) is preferred.

Parameters

- `y_true` [ndarray of shape (n_samples, n_labels)] True targets of multi-label classification, or true scores of entities to be ranked.
y_score  [ndarray of shape (n_samples, n_labels)] Target scores, can either be probability estimates, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).

k  [int, default=None] Only consider the highest k scores in the ranking. If None, use all outputs.

log_base  [float, default=2] Base of the logarithm used for the discount. A low value means a sharper discount (top results are more important).

sample_weight  [ndarray of shape (n_samples,), default=None] Sample weights. If None, all samples are given the same weight.

ignore_ties  [bool, default=False] Assume that there are no ties in y_score (which is likely to be the case if y_score is continuous) for efficiency gains.

Returns

discounted_cumulative_gain  [float] The averaged sample DCG scores.

See also:

ndcg_score  The Discounted Cumulative Gain divided by the Ideal Discounted Cumulative Gain (the DCG obtained for a perfect ranking), in order to have a score between 0 and 1.

References

Wikipedia entry for Discounted Cumulative Gain.


Examples

```python
>>> from sklearn.metrics import dcg_score
>>> # we have groud-truth relevance of some answers to a query:
>>> true_relevance = np.asarray([[10, 0, 0, 1, 5]])
>>> # we predict scores for the answers
>>> scores = np.asarray([[.1, .2, .3, 4, 70]])
>>> dcg_score(true_relevance, scores)
9.49...
>>> # we can set k to truncate the sum; only top k answers contribute
>>> dcg_score(true_relevance, scores, k=2)
5.63...
>>> # now we have some ties in our prediction
>>> scores = np.asarray([[1, 0, 0, 0, 1]])
>>> # by default ties are averaged, so here we get the average true
>>> # relevance of our top predictions: (10 + 5) / 2 = 7.5
>>> dcg_score(true_relevance, scores, k=1)
7.5
>>> # we can choose to ignore ties for faster results, but only
>>> # if we know there aren't ties in our scores, otherwise we get
```
```python
>>> # wrong results:
>>> dcg_score(true_relevance,
...    scores, k=1, ignore_ties=True)
5.0
```

**sklearn.metrics.det_curve**

`sklearn.metrics.det_curve(y_true, y_score, pos_label=None, sample_weight=None)`

Compute error rates for different probability thresholds.

**Note:** This metric is used for evaluation of ranking and error tradeoffs of a binary classification task.

Read more in the *User Guide*.

New in version 0.24.

**Parameters**

- `y_true` [ndarray of shape (n_samples,)] True binary labels. If labels are not either {-1, 1} or {0, 1}, then pos_label should be explicitly given.
- `y_score` [ndarray of shape of (n_samples,)] Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- `pos_label` [int or str, default=None] The label of the positive class. When `pos_label=None`, if `y_true` is in {-1, 1} or {0, 1}, `pos_label` is set to 1, otherwise an error will be raised.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- `fpr` [ndarray of shape (n_thresholds,)] False positive rate (FPR) such that element i is the false positive rate of predictions with score >= thresholds[i]. This is occasionally referred to as false acceptance probability or fall-out.
- `fnr` [ndarray of shape (n_thresholds,)] False negative rate (FNR) such that element i is the false negative rate of predictions with score >= thresholds[i]. This is occasionally referred to as false rejection or miss rate.
- `thresholds` [ndarray of shape (n_thresholds,)] Decreasing score values.

**See also:**

- `plot_det_curve` Plot detection error tradeoff (DET) curve.
- `DetCurveDisplay` DET curve visualization.
- `roc_curve` Compute Receiver operating characteristic (ROC) curve.
- `precision_recall_curve` Compute precision-recall curve.
Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import det_curve
>>> y_true = np.array([0, 0, 1, 1])
>>> y_scores = np.array([0.1, 0.4, 0.35, 0.8])
>>> fpr, fnr, thresholds = det_curve(y_true, y_scores)
>>> fpr
array([0.5, 0.5, 0.])
>>> fnr
array([0. , 0.5, 0.5])
>>> thresholds
array([0.35, 0.4 , 0.8])
```

Examples using `sklearn.metrics.det_curve`

- Detection error tradeoff (DET) curve

`sklearn.metrics.f1_score`

`sklearn.metrics.f1_score(y_true, y_pred, *, labels=None, pos_label=1, average='binary', sample_weight=None, zero_division='warn')`

Compute the F1 score, also known as balanced F-score or F-measure.

The F1 score can be interpreted as a weighted average of the precision and recall, where an F1 score reaches its best value at 1 and worst score at 0. The relative contribution of precision and recall to the F1 score are equal. The formula for the F1 score is:

\[
F1 = 2 \times \frac{\text{precision} \times \text{recall}}{\text{precision} + \text{recall}}
\]

In the multi-class and multi-label case, this is the average of the F1 score of each class with weighting depending on the `average` parameter.

Read more in the User Guide.

Parameters

- **y_true** [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target values.
- **y_pred** [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by a classifier.
- **labels** [array-like, default=None] The set of labels to include when `average` != 'binary', and their order if `average` is None. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro average. For multilabel targets, labels are column indices. By default, all labels in `y_true` and `y_pred` are used in sorted order.
  Changed in version 0.17: Parameter `labels` improved for multiclass problem.
- **pos_label** [str or int, default=1] The class to report if `average='binary'` and the data is binary. If the data are multiclass or multilabel, this will be ignored; setting `labels=[pos_label]` and `average != 'binary'` will report scores for that label only.
average ([‘micro’, ‘macro’, ‘samples’, ‘weighted’, ‘binary’) or None, default=’binary’] This parameter is required for multiclass/multilabel targets. If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

- **'binary'**: Only report results for the class specified by pos_label. This is applicable only if targets \((y_{true, pred})\) are binary.
- **'micro'**: Calculate metrics globally by counting the total true positives, false negatives and false positives.
- **'macro'**: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.
- **'weighted'**: Calculate metrics for each label, and find their average weighted by support (the number of true instances for each label). This alters ‘macro’ to account for label imbalance; it can result in an F-score that is not between precision and recall.
- **'samples'**: Calculate metrics for each instance, and find their average (only meaningful for multilabel classification where this differs from accuracy_score).

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

zero_division ["warn", 0 or 1, default="warn"] Sets the value to return when there is a zero division, i.e. when all predictions and labels are negative. If set to “warn”, this acts as 0, but warnings are also raised.

Returns

- **f1_score** [float or array of float, shape = [n_unique_labels]] F1 score of the positive class in binary classification or weighted average of the F1 scores of each class for the multiclass task.

See also:

- fbeta_score, precision_recall_fscore_support, jaccard_score
- multilabel_confusion_matrix

Notes

When `true positive + false positive == 0`, precision is undefined. When `true positive + false negative == 0`, recall is undefined. In such cases, by default the metric will be set to 0, as will F-score, and UndefinedMetricWarning will be raised. This behavior can be modified with zero_division.

References

[1]
Examples

```python
>>> from sklearn.metrics import f1_score
>>> y_true = [0, 1, 2, 0, 1, 2]
>>> y_pred = [0, 2, 1, 0, 0, 1]
>>> f1_score(y_true, y_pred, average='macro')
0.26...
>>> f1_score(y_true, y_pred, average='micro')
0.33...
>>> f1_score(y_true, y_pred, average='weighted')
0.26...
>>> f1_score(y_true, y_pred, average=None)
array([0.8, 0 , 0 ])
>>> y_true = [0, 0, 0, 0, 0, 0]
>>> y_pred = [0, 0, 0, 0, 0, 0]
>>> f1_score(y_true, y_pred, zero_division=1)
1.0...
```

Examples using `sklearn.metrics.f1_score`

- Probability Calibration curves
- Precision-Recall
- Semi-supervised Classification on a Text Dataset

`sklearn.metrics.fbeta_score`

`sklearn.metrics.fbeta_score(y_true, y_pred, *, beta, labels=None, pos_label=1, average='binary', sample_weight=None, zero_division='warn')`

Compute the F-beta score.

The F-beta score is the weighted harmonic mean of precision and recall, reaching its optimal value at 1 and its worst value at 0.

The `beta` parameter determines the weight of recall in the combined score. `beta < 1` lends more weight to precision, while `beta > 1` favors recall (`beta -> 0` considers only precision, `beta -> +inf` only recall).

Read more in the User Guide.

Parameters

- `y_true` [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target values.
- `y_pred` [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by a classifier.
- `beta` [float] Determines the weight of recall in the combined score.
- `labels` [array-like, default=None] The set of labels to include when `average` is not `'binary'`, and their order if `average` is `None`. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro average. For multilabel targets, labels are column indices. By default, all labels in `y_true` and `y_pred` are used in sorted order.
Changed in version 0.17: Parameter labels improved for multiclass problem.

pos_label [str or int, default=1] The class to report if average='binary' and the data is binary. If the data are multiclass or multilabel, this will be ignored; setting labels=[pos_label] and average != 'binary' will report scores for that label only.

average [['micro', 'macro', 'samples', 'weighted', 'binary'] or None default='binary'] This parameter is required for multiclass/multilabel targets. If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

'binary': Only report results for the class specified by pos_label. This is applicable only if targets (y_{true,pred}) are binary.

'micro': Calculate metrics globally by counting the total true positives, false negatives and false positives.

'macro': Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.

'weighted': Calculate metrics for each label, and find their average weighted by support (the number of true instances for each label). This alters ‘macro’ to account for label imbalance; it can result in an F-score that is not between precision and recall.

'samples': Calculate metrics for each instance, and find their average (only meaningful for multilabel classification where this differs from accuracy_score).

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

zero_division ['warn', 0 or 1, default='warn'] Sets the value to return when there is a zero division, i.e. when all predictions and labels are negative. If set to “warn”, this acts as 0, but warnings are also raised.

Returns

fbeta_score [float (if average is not None) or array of float, shape = [n_unique_labels]] F-beta score of the positive class in binary classification or weighted average of the F-beta score of each class for the multiclass task.

See also:

precision_recall_fscore_support, multilabel_confusion_matrix

Notes

When true positive + false positive == 0 or true positive + false negative == 0, f-score returns 0 and raises UndefinedMetricWarning. This behavior can be modified with zero_division.
References

[1], [2]

Examples

```python
>>> from sklearn.metrics import fbeta_score
>>> y_true = [0, 1, 2, 0, 1, 2]
>>> y_pred = [0, 2, 1, 0, 0, 1]
>>> fbeta_score(y_true, y_pred, average='macro', beta=0.5)
0.23...
>>> fbeta_score(y_true, y_pred, average='micro', beta=0.5)
0.33...
>>> fbeta_score(y_true, y_pred, average='weighted', beta=0.5)
0.23...
>>> fbeta_score(y_true, y_pred, average=None, beta=0.5)
array([0.71..., 0., 0.])
```

**sklearn.metrics.hamming_loss**

`sklearn.metrics.hamming_loss(y_true, y_pred, *, sample_weight=None)`  
Compute the average Hamming loss.

The Hamming loss is the fraction of labels that are incorrectly predicted.

Read more in the *User Guide*.

**Parameters**

- `y_true`  
  [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) labels.

- `y_pred`  
  [1d array-like, or label indicator array / sparse matrix] Predicted labels, as returned by a classifier.

- `sample_weight`  
  [array-like of shape (n_samples,), default=None] Sample weights.
  
  New in version 0.18.

**Returns**

- `loss`  
  [float or int] Return the average Hamming loss between element of `y_true` and `y_pred`.

**See also:**

*accuracy_score, jaccard_score, zero_one_loss*

**Notes**

In multiclass classification, the Hamming loss corresponds to the Hamming distance between `y_true` and `y_pred` which is equivalent to the subset `zero_one_loss` function, when `normalize` parameter is set to True.

In multilabel classification, the Hamming loss is different from the subset zero-one loss. The zero-one loss considers the entire set of labels for a given sample incorrect if it does not entirely match the true set of labels. Hamming loss is more forgiving in that it penalizes only the individual labels.

The Hamming loss is upperbounded by the subset zero-one loss, when `normalize` parameter is set to True. It is always between 0 and 1, lower being better.
Examples using `sklearn.metrics.hamming_loss`

- Model Complexity Influence

```
>>> from sklearn.metrics import hamming_loss
>>> y_pred = [1, 2, 3, 4]
>>> y_true = [2, 2, 3, 4]
>>> hamming_loss(y_true, y_pred)
0.25
```

In the multilabel case with binary label indicators:

```
>>> import numpy as np
>>> hamming_loss(np.array([[0, 1], [1, 1]]), np.zeros((2, 2)))
0.75
```

```
sklearn.metrics.hinge_loss

sklearn.metrics.hinge_loss(y_true, pred_decision, *, labels=None, sample_weight=None)

Average hinge loss (non-regularized).

In binary class case, assuming labels in `y_true` are encoded with +1 and -1, when a prediction mistake is made, `margin = y_true * pred_decision` is always negative (since the signs disagree), implying `1 - margin` is always greater than 1. The cumulated hinge loss is therefore an upper bound of the number of mistakes made by the classifier.

In multiclass case, the function expects that either all the labels are included in `y_true` or an optional `labels` argument is provided which contains all the labels. The multilabel margin is calculated according to Crammer-Singer’s method. As in the binary case, the cumulated hinge loss is an upper bound of the number of mistakes made by the classifier.

Read more in the `User Guide`.

Parameters

- `y_true` [array of shape (n_samples,)] True target, consisting of integers of two values. The positive label must be greater than the negative label.

- `pred_decision` [array of shape (n_samples,) or (n_samples, n_classes)] Predicted decisions, as output by `decision_function` (floats).

- `labels` [array-like, default=None] Contains all the labels for the problem. Used in multiclass hinge loss.

- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- `loss` [float]
References

[1], [2], [3]

Examples

```python
>>> from sklearn import svm
>>> from sklearn.metrics import hinge_loss
>>> X = [[0], [1]]
>>> y = [-1, 1]
>>> est = svm.LinearSVC(random_state=0)
>>> est.fit(X, y)
LinearSVC(random_state=0)
>>> pred_decision = est.decision_function([[-2], [3], [0.5]])
>>> pred_decision
array([-2.18..., 2.36..., 0.09...])
>>> hinge_loss([-1, 1, 1], pred_decision)
0.30...
```

In the multiclass case:

```python
>>> import numpy as np
>>> X = np.array([[0], [1], [2], [3]])
>>> Y = np.array([0, 1, 2, 3])
>>> labels = np.array([0, 1, 2, 3])
>>> est = svm.LinearSVC()
>>> est.fit(X, Y)
LinearSVC()
>>> pred_decision = est.decision_function([[-1], [2], [3]])
>>> y_true = [0, 2, 3]
>>> hinge_loss(y_true, pred_decision, labels=labels)
0.56...
```

**sklearn.metrics.jaccard_score**

`sklearn.metrics.jaccard_score`(y_true, y_pred, *, labels=None, pos_label=1, average='binary', sample_weight=None, zero_division='warn')

Jaccard similarity coefficient score.

The Jaccard index [1], or Jaccard similarity coefficient, defined as the size of the intersection divided by the size of the union of two label sets, is used to compare set of predicted labels for a sample to the corresponding set of labels in y_true.

Read more in the User Guide.

Parameters

- **y_true** [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) labels.
- **y_pred** [1d array-like, or label indicator array / sparse matrix] Predicted labels, as returned by a classifier.
- **labels** [array-like of shape (n_classes,), default=None] The set of labels to include when average != 'binary', and their order if average is None. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro...
average. For multilabel targets, labels are column indices. By default, all labels in `y_true` and `y_pred` are used in sorted order.

**pos_label** [str or int, default=1] The class to report if `average='binary'` and the data is binary. If the data are multiclass or multilabel, this will be ignored; setting `labels=[pos_label]` and `average != 'binary'` will report scores for that label only.

**average** [{None, ‘micro’, ‘macro’, ‘samples’, ‘weighted’, ‘binary’}, default='binary'] If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

- **'binary'**: Only report results for the class specified by `pos_label`. This is applicable only if targets (`y_{true,pred}`) are binary.
- **'micro'**: Calculate metrics globally by counting the total true positives, false negatives and false positives.
- **'macro'**: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.
- **'weighted'**: Calculate metrics for each label, and find their average, weighted by support (the number of true instances for each label). This alters ‘macro’ to account for label imbalance.
- **'samples'**: Calculate metrics for each instance, and find their average (only meaningful for multilabel classification).

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**zero_division** [“warn”, {0.0, 1.0}, default=”warn”] Sets the value to return when there is a zero division, i.e. when there are no negative values in predictions and labels. If set to “warn”, this acts like 0, but a warning is also raised.

**Returns**

- **score** [float (if average is not None) or array of floats, shape = [n_unique_labels]]

See also:

- `accuracy_score`
- `f_score`
- `multilabel_confusion_matrix`

**Notes**

`jaccard_score` may be a poor metric if there are no positives for some samples or classes. Jaccard is undefined if there are no true or predicted labels, and our implementation will return a score of 0 with a warning.

**References**

[1]
Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import jaccard_score
>>> y_true = np.array([[0, 1, 1], ...
                      [1, 1, 0]])
>>> y_pred = np.array([[1, 1, 1], ...
                      [1, 0, 0]])
```

In the binary case:

```python
>>> jaccard_score(y_true[0], y_pred[0])
0.6666...
```

In the multilabel case:

```python
>>> jaccard_score(y_true, y_pred, average='samples')
0.5833...
>>> jaccard_score(y_true, y_pred, average='macro')
0.6666...
>>> jaccard_score(y_true, y_pred, average='None')
array([0.5, 0.5, 1.])
```

In the multiclass case:

```python
>>> y_pred = [0, 2, 1, 2]
>>> y_true = [0, 1, 2, 2]
>>> jaccard_score(y_true, y_pred, average='None')
array([1. , 0. , 0.33...])
```

Examples using sklearn.metrics.jaccard_score

- Classifier Chain

sklearn.metrics.log_loss

sklearn.metrics.log_loss(y_true, y_pred, *, eps=1e-15, normalize=True, sample_weight=None, labels=None)

Log loss, aka logistic loss or cross-entropy loss.

This is the loss function used in (multinomial) logistic regression and extensions of it such as neural networks, defined as the negative log-likelihood of a logistic model that returns y_pred probabilities for its training data y_true. The log loss is only defined for two or more labels. For a single sample with true label \( y \in \{0, 1\} \) and and a probability estimate \( p = Pr(y = 1) \), the log loss is:

\[
L_{\log}(y, p) = -(y \log(p) + (1 - y) \log(1 - p))
\]

Read more in the User Guide.

Parameters

- `y_true` [array-like or label indicator matrix] Ground truth (correct) labels for n_samples samples.
- `y_pred` [array-like of float, shape = (n_samples, n_classes) or (n_samples,)] Predicted probabilities, as returned by a classifier’s predict_proba method. If `y_pred.shape` =
log_loss

Parameters

n_samples,  the probabilities provided are assumed to be that of the positive class. The
labels in y_pred are assumed to be ordered alphabetically, as done by preprocessing.
LabelBinarizer.

eps  [float, default=1e-15] Log loss is undefined for p=0 or p=1, so probabilities are clipped to
max(eps, min(1 - eps, p)).

normalize  [bool, default=True] If true, return the mean loss per sample. Otherwise, return the
sum of the per-sample losses.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

labels  [array-like, default=None] If not provided, labels will be inferred from y_true. If
labels is None and y_pred has shape (n_samples,) the labels are assumed to be bi-
nary and are inferred from y_true.

New in version 0.18.

Returns

loss  [float]

Notes

The logarithm used is the natural logarithm (base-e).

References


Examples

```python
>>> from sklearn.metrics import log_loss
>>> log_loss(["spam", "ham", "ham", "spam"],
...          [[.1, .9], [.9, .1], [.8, .2], [.35, .65]])
0.21616...
```

Examples using sklearn.metrics.log_loss

- Probability Calibration for 3-class classification
- Probabilistic predictions with Gaussian process classification (GPC)

sklearn.metrics.matthews_corrcoef

sklearn.metrics.matthews_corrcoef (y_true, y_pred, *, sample_weight=None)

Compute the Matthews correlation coefficient (MCC).

The Matthews correlation coefficient is used in machine learning as a measure of the quality of binary and
multiclass classifications. It takes into account true and false positives and negatives and is generally regarded
as a balanced measure which can be used even if the classes are of very different sizes. The MCC is in essence a
correlation coefficient value between -1 and +1. A coefficient of +1 represents a perfect prediction, 0 an average
random prediction and -1 an inverse prediction. The statistic is also known as the phi coefficient. [source: Wikipedia]
Binary and multiclass labels are supported. Only in the binary case does this relate to information about true and false positives and negatives. See references below.

Read more in the User Guide.

Parameters

- **y_true** [array, shape = [n_samples]] Ground truth (correct) target values.
- **y_pred** [array, shape = [n_samples]] Estimated targets as returned by a classifier.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. New in version 0.18.

Returns

- **mcc** [float] The Matthews correlation coefficient (+1 represents a perfect prediction, 0 an average random prediction and -1 and inverse prediction).

References

[1], [2], [3], [4]

Examples

```python
>>> from sklearn.metrics import matthews_corrcoef
>>> y_true = [+1, +1, +1, -1]
>>> y_pred = [+1, -1, +1, +1]
>>> matthews_corrcoef(y_true, y_pred)
-0.33...
```

**sklearn.metrics.multilabel_confusion_matrix**

`sklearn.metrics.multilabel_confusion_matrix(y_true, y_pred, *, sample_weight=None, labels=None, samplewise=False)`

Compute a confusion matrix for each class or sample.

New in version 0.21.

Compute class-wise (default) or sample-wise (samplewise=True) multilabel confusion matrix to evaluate the accuracy of a classification, and output confusion matrices for each class or sample.

In multilabel confusion matrix $MCM$, the count of true negatives is $MCM_{0, 0}$, false negatives is $MCM_{1, 0}$, true positives is $MCM_{1, 1}$ and false positives is $MCM_{0, 1}$.

Multiclass data will be treated as if binarized under a one-vs-rest transformation. Returned confusion matrices will be in the order of sorted unique labels in the union of (y_true, y_pred).

Read more in the User Guide.

Parameters

- **y_true** [{array-like, sparse matrix} of shape (n_samples, n_outputs) or (n_samples,)] Ground truth (correct) target values.
- **y_pred** [{array-like, sparse matrix} of shape (n_samples, n_outputs) or (n_samples,)] Estimated targets as returned by a classifier.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.
labels [array-like of shape (n_classes,), default=None] A list of classes or column indices to select some (or to force inclusion of classes absent from the data).

samplewise [bool, default=False] In the multilabel case, this calculates a confusion matrix per sample.

Returns

multi_confusion [ndarray of shape (n_outputs, 2, 2)] A 2x2 confusion matrix corresponding to each output in the input. When calculating class-wise multi_confusion (default), then n_outputs = n_labels; when calculating sample-wise multi_confusion (samplewise=True), n_outputs = n_samples. If labels is defined, the results will be returned in the order specified in labels, otherwise the results will be returned in sorted order by default.

See also:

confusion_matrix

Notes

The multilabel_confusion_matrix calculates class-wise or sample-wise multilabel confusion matrices, and in multiclass tasks, labels are binarized under a one-vs-rest way; while confusion_matrix calculates one confusion matrix for confusion between every two classes.

Examples

Multilabel-indicator case:

```python
>>> import numpy as np
>>> from sklearn.metrics import multilabel_confusion_matrix
>>> y_true = np.array([[1, 0, 1], ...
                   [0, 1, 0]])
>>> y_pred = np.array([[1, 0, 0], ...
                   [0, 1, 1]])
>>> multilabel_confusion_matrix(y_true, y_pred)
array([[1, 0],
       [0, 1]])
```

Multiclass case:

```python
>>> y_true = ['cat', 'ant', 'cat', 'cat', 'ant', 'bird']
>>> y_pred = ['ant', 'ant', 'cat', 'cat', 'ant', 'cat']
>>> multilabel_confusion_matrix(y_true, y_pred, ... labels=['ant', 'bird', 'cat'])
array([[3, 1],
       [0, 2]],
       [[5, 0],
       [1, 0]])
```
sklearn.metrics.ndcg_score

sklearn.metrics.ndcg_score(y_true, y_score, *, k=None, sample_weight=None, ignore_ties=False)

Compute Normalized Discounted Cumulative Gain.

Sum the true scores ranked in the order induced by the predicted scores, after applying a logarithmic discount. Then divide by the best possible score (Ideal DCG, obtained for a perfect ranking) to obtain a score between 0 and 1.

This ranking metric yields a high value if true labels are ranked high by y_score.

Parameters

- y_true [ndarray of shape (n_samples, n_labels)] True targets of multilabel classification, or true scores of entities to be ranked.
- y_score [ndarray of shape (n_samples, n_labels)] Target scores, can either be probability estimates, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- k [int, default=None] Only consider the highest k scores in the ranking. If None, use all outputs.
- sample_weight [ndarray of shape (n_samples,), default=None] Sample weights. If None, all samples are given the same weight.
- ignore_ties [bool, default=False] Assume that there are no ties in y_score (which is likely to be the case if y_score is continuous) for efficiency gains.

Returns

- normalized_discounted_cumulative_gain [float in [0., 1.]] The averaged NDCG scores for all samples.

See also:

- dcg_score Discounted Cumulative Gain (not normalized).

References

Wikipedia entry for Discounted Cumulative Gain


Examples

```python
from sklearn.metrics import ndcg_score

# we have ground-truth relevance of some answers to a query:
true_relevance = np.asarray([[10, 0, 0, 1, 5]])

# we predict some scores (relevance) for the answers
scores = np.asarray([[.1, .2, .3, 4, 70]])

ndcg_score(true_relevance, scores)  # 0.69...

scores = np.asarray([[.05, 1.1, 1., .5, .0]])

ndcg_score(true_relevance, scores)  # 0.49...

# we can set k to truncate the sum; only top k answers contribute.
ndcg_score(true_relevance, scores, k=4)  # 0.35...

# the normalization takes k into account so a perfect answer
# would still get 1.0
ndcg_score(true_relevance, true_relevance, k=4)  # 1.0

# now we have some ties in our prediction
scores = np.asarray([[1, 0, 0, 0, 1]])

# by default ties are averaged, so here we get the average (normalized)
# true relevance of our top predictions: (10 / 10 + 5 / 10) / 2 = .75
ndcg_score(true_relevance, scores, k=1)  # 0.75

# we can choose to ignore ties for faster results, but only
# if we know there aren't ties in our scores, otherwise we get
# wrong results:
ndcg_score(true_relevance, scores, k=1, ignore_ties=True)  # 0.5
```

sklearn.metrics.precision_recall_curve

sklearn.metrics.precision_recall_curve(y_true, probas_pred, *, pos_label=None, sample_weight=None)

Compute precision-recall pairs for different probability thresholds.

Note: this implementation is restricted to the binary classification task.

The precision is the ratio \( \frac{tp}{tp + fp} \) where \( tp \) is the number of true positives and \( fp \) the number of false positives. The precision is intuitively the ability of the classifier not to label as positive a sample that is negative.

The recall is the ratio \( \frac{tp}{tp + fn} \) where \( tp \) is the number of true positives and \( fn \) the number of false negatives. The recall is intuitively the ability of the classifier to find all the positive samples.

The last precision and recall values are 1. and 0. respectively and do not have a corresponding threshold. This ensures that the graph starts on the y axis.

Read more in the User Guide.

Parameters

- **y_true** [ndarray of shape (n_samples,)] True binary labels. If labels are not either \(-1, 1\) or \(0, 1\), then pos_label should be explicitly given.

- **probas_pred** [ndarray of shape (n_samples,)] Estimated probabilities or output of a decision function.
pos_label [int or str, default=None] The label of the positive class. When pos_label=None, if y_true is in {-1, 1} or {0, 1}, pos_label is set to 1, otherwise an error will be raised.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

precision [ndarray of shape (n_thresholds + 1,)] Precision values such that element i is the precision of predictions with score >= thresholds[i] and the last element is 1.

recall [ndarray of shape (n_thresholds + 1,)] Decreasing recall values such that element i is the recall of predictions with score >= thresholds[i] and the last element is 0.

thresholds [ndarray of shape (n_thresholds,)] Increasing thresholds on the decision function used to compute precision and recall. n_thresholds <= len(np.unique(probas_pred)).

See also:

plot_precision_recall_curve Plot Precision Recall Curve for binary classifiers.

PrecisionRecallDisplay Precision Recall visualization.

average_precision_score Compute average precision from prediction scores.

det_curve Compute error rates for different probability thresholds.

roc_curve Compute Receiver operating characteristic (ROC) curve.

Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import precision_recall_curve
>>> y_true = np.array([0, 0, 1, 1])
>>> y_scores = np.array([0.1, 0.4, 0.35, 0.8])
>>> precision, recall, thresholds = precision_recall_curve(  ...
    y_true, y_scores)
>>> precision
array([0.66666667, 0.5, 1., 1.])
>>> recall
array([1., 0.5, 0.5, 0.])
>>> thresholds
array([0.35, 0.4, 0.8])
```
Compute precision, recall, F-measure and support for each class.

The precision is the ratio \( \frac{tp}{tp + fp} \) where \( tp \) is the number of true positives and \( fp \) the number of false positives. The precision is intuitively the ability of the classifier not to label as positive a sample that is negative.

The recall is the ratio \( \frac{tp}{tp + fn} \) where \( tp \) is the number of true positives and \( fn \) the number of false negatives. The recall is intuitively the ability of the classifier to find all the positive samples.

The F-beta score can be interpreted as a weighted harmonic mean of the precision and recall, where an F-beta score reaches its best value at 1 and worst score at 0.

The F-beta score weights recall more than precision by a factor of \( \beta \). \( \beta = 1.0 \) means recall and precision are equally important.

The support is the number of occurrences of each class in \( y_{true} \).

If \( pos \_label \) is None and in binary classification, this function returns the average precision, recall and F-measure if \( average \) is one of 'micro', 'macro', 'weighted' or 'samples'.

Read more in the User Guide.

Parameters

- **y_true** [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target values.
- **y_pred** [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by a classifier.
- **beta** [float, default=1.0] The strength of recall versus precision in the F-score.
- **labels** [array-like, default=None] The set of labels to include when \( average \neq 'binary' \) and their order if \( average \) is None. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro average. For multilabel targets, labels are column indices. By default, all labels in \( y_{true} \) and \( y_{pred} \) are used in sorted order.
- **pos_label** [str or int, default=1] The class to report if \( average='binary' \) and the data is binary. If the data are multiclass or multilabel, this will be ignored; setting \( labels=[pos\_label] \) and \( average \neq 'binary' \) will report scores for that label only.
- **average** [{'binary', 'micro', 'macro', 'samples','weighted'}, default=None] If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:
  - `'binary'`: Only report results for the class specified by \( pos\_label \). This is applicable only if targets \( y_{true,pred} \) are binary.
  - `'micro'`: Calculate metrics globally by counting the total true positives, false negatives and false positives.
  - `'macro'`: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.
'weighted': Calculate metrics for each label, and find their average weighted by support (the number of true instances for each label). This alters ‘macro’ to account for label imbalance; it can result in an F-score that is not between precision and recall.

'samples': Calculate metrics for each instance, and find their average (only meaningful for multilabel classification where this differs from accuracy_score).

warn_for [tuple or set, for internal use] This determines which warnings will be made in the case that this function is being used to return only one of its metrics.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

zero_division ['warn', 0 or 1, default='warn']

Sets the value to return when there is a zero division:

- recall: when there are no positive labels
- precision: when there are no positive predictions
- f-score: both

If set to “warn”, this acts as 0, but warnings are also raised.

Returns

precision [float (if average is not None) or array of float, shape = [n_unique_labels]]
recall [float (if average is not None) or array of float, shape = [n_unique_labels]]
fbeta_score [float (if average is not None) or array of float, shape = [n_unique_labels]]
support [None (if average is not None) or array of int, shape = [n_unique_labels]] The number of occurrences of each label in y_true.

Notes

When true positive + false positive == 0, precision is undefined. When true positive + false negative == 0, recall is undefined. In such cases, by default the metric will be set to 0, as will f-score, and UndefinedMetricWarning will be raised. This behavior can be modified with zero_division.

References

[1], [2], [3]

Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import precision_recall_fscore_support
>>> y_true = np.array(['cat', 'dog', 'pig', 'cat', 'dog', 'pig'])
>>> y_pred = np.array(['cat', 'pig', 'dog', 'cat', 'cat', 'dog'])
>>> precision_recall_fscore_support(y_true, y_pred, average='macro')
(0.22..., 0.33..., 0.26..., None)
>>> precision_recall_fscore_support(y_true, y_pred, average='micro')
(0.33..., 0.33..., 0.33..., None)
>>> precision_recall_fscore_support(y_true, y_pred, average='weighted')
(0.22..., 0.33..., 0.26..., None)
```
It is possible to compute per-label precisions, recalls, F1-scores and supports instead of averaging:

```python
>>> precision_recall_fscore_support(y_true, y_pred, average=None,
... labels=['pig', 'dog', 'cat'])
(array([0. , 0. , 0.66...]),
array([0., 0., 1.]), array([0. , 0. , 0.8]),
array([2, 2, 2]))
```

`sklearn.metrics.precision_score`

`sklearn.metrics.precision_score(y_true, y_pred, *, labels=None, pos_label=1, average='binary', sample_weight=None, zero_division='warn')`

Compute the precision.

The precision is the ratio $tp / (tp + fp)$ where $tp$ is the number of true positives and $fp$ the number of false positives. The precision is intuitively the ability of the classifier not to label as positive a sample that is negative.

The best value is 1 and the worst value is 0.


**Parameters**

- `y_true` [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target values.
- `y_pred` [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by a classifier.
- `labels` [array-like, default=None] The set of labels to include when `average != 'binary'`, and their order if `average` is None. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro average. For multilabel targets, labels are column indices. By default, all labels in `y_true` and `y_pred` are used in sorted order.

  Changed in version 0.17: Parameter `labels` improved for multiclass problem.
- `pos_label` [str or int, default=1] The class to report if `average='binary'` and the data is binary. If the data are multiclass or multilabel, this will be ignored; setting `labels=[pos_label]` and `average != 'binary'` will report scores for that label only.
- `average` [None, 'micro', 'macro', 'samples', 'weighted', 'binary'] This parameter is required for multiclass/multilabel targets. If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

  - `'binary'`: Only report results for the class specified by `pos_label`. This is applicable only if targets `y_{true,pred}` are binary.
  - `'micro'`: Calculate metrics globally by counting the total true positives, false negatives and false positives.
  - `'macro'`: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.
  - `'weighted'`: Calculate metrics for each label, and find their average weighted by support (the number of true instances for each label). This alters `macro` to account for label imbalance; it can result in an F-score that is not between precision and recall.
'samples': Calculate metrics for each instance, and find their average (only meaningful for multilabel classification where this differs from accuracy_score).

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

type: sample_weight | array-like of shape (n_samples,) | default=None

zero_division ["warn", 0 or 1, default="warn"] Sets the value to return when there is a zero division. If set to "warn", this acts as 0, but warnings are also raised.

type: zero_division | ["warn", 0 or 1, default="warn"]

Returns

precision [float (if average is not None) or array of float of shape] (n_unique_labels,) Precision of the positive class in binary classification or weighted average of the precision of each class for the multiclass task.

See also:

precision_recall_Fscore_support, multilabel_confusion_matrix

Notes

When true positive + false positive == 0, precision returns 0 and raises UndefinedMetricWarning. This behavior can be modified with zero_division.

Examples

```python
>>> from sklearn.metrics import precision_score
>>> y_true = [0, 1, 2, 0, 1, 2]
>>> y_pred = [0, 2, 1, 0, 0, 1]
>>> precision_score(y_true, y_pred, average='macro')
0.22...
>>> precision_score(y_true, y_pred, average='micro')
0.33...
>>> precision_score(y_true, y_pred, average='weighted')
0.22...
>>> precision_score(y_true, y_pred, average=None)  
array([0.66..., 0. , 0. ])
>>> y_pred = [0, 0, 0, 0, 0, 0]
>>> precision_score(y_true, y_pred, average=None)  
array([0.33..., 0. , 0. ])
>>> precision_score(y_true, y_pred, average=None, zero_division=1)  
array([0.33..., 1. , 1. ])
```

Examples using sklearn.metrics.precision_score

- Probability Calibration curves
- Precision-Recall
sklearn.metrics.recall_score

\texttt{sklearn.metrics.recall_score(y\_true, y\_pred, *, labels=None, pos\_label=1, average='binary',
    sample\_weight=None, zero\_division='warn')}

Compute the recall.

The recall is the ratio $\frac{tp}{tp + fn}$ where $tp$ is the number of true positives and $fn$ the number of false

negatives. The recall is intuitively the ability of the classifier to find all the positive samples.

The best value is 1 and the worst value is 0.

Read more in the \textit{User Guide}.

**Parameters**

- \texttt{y\_true} [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) target
  values.

- \texttt{y\_pred} [1d array-like, or label indicator array / sparse matrix] Estimated targets as returned by
  a classifier.

- \texttt{labels} [array-like, default=None] The set of labels to include when average != 'binary', and their order if
  average is None. Labels present in the data can be excluded, for example to calculate a multiclass average ignoring a majority negative class, while labels not present in the data will result in 0 components in a macro average. For multilabel targets, labels are column indices. By default, all labels in \texttt{y\_true} and \texttt{y\_pred} are used in sorted order.

  Changed in version 0.17: Parameter \texttt{labels} improved for multiclass problem.

- \texttt{pos\_label} [str or int, default=1] The class to report if average='binary' and the
data is binary. If the data are multiclass or multilabel, this will be ignored; setting
labels=[pos\_label] and average != 'binary' will report scores for that la-
bel only.

- \texttt{average} [‘micro’, ‘macro’, ‘samples’, ‘weighted’, ‘binary’] This parameter is required for multiclass/multilabel targets. If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data:

  - ‘binary’: Only report results for the class specified by \texttt{pos\_label}. This is applicable
    only if targets (y_{true,pred}) are binary.

  - ‘micro’: Calculate metrics globally by counting the total true positives, false negatives and false positives.

  - ‘macro’: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.

  - ‘weighted’: Calculate metrics for each label, and find their average weighted by support (the number of true instances for each label). This alters ‘macro’ to account for label imbalance; it can result in an F-score that is not between precision and recall.

  - ‘samples’: Calculate metrics for each instance, and find their average (only meaningful for multilabel classification where this differs from \texttt{accuracy_score}).

- \texttt{sample\_weight} [array-like of shape (n\_samples,), default=None] Sample weights.

- \texttt{zero\_division} [‘warn’, 0 or 1, default=’warn’] Sets the value to return when there is a zero
division. If set to “warn”, this acts as 0, but warnings are also raised.

**Returns**
**recall** [float (if average is not None) or array of float of shape (n_unique_labels,)] Recall of the positive class in binary classification or weighted average of the recall of each class for the multiclass task.

**See also:**

* precision_recall_fscore_support, balanced_accuracy_score*

* multilabel_confusion_matrix*

**Notes**

When `true positive + false negative == 0`, `recall` returns 0 and raises UndefinedMetricWarning. This behavior can be modified with `zero_division`.

**Examples**

```python
>>> from sklearn.metrics import recall_score
>>> y_true = [0, 1, 2, 0, 1, 2]
>>> y_pred = [0, 2, 1, 0, 0, 1]
>>> recall_score(y_true, y_pred, average='macro')
0.33...
>>> recall_score(y_true, y_pred, average='micro')
0.33...
>>> recall_score(y_true, y_pred, average='weighted')
0.33...
>>> recall_score(y_true, y_pred, average=None)
array([1., 0., 0.])
>>> y_true = [0, 0, 0, 0, 0, 0]
>>> recall_score(y_true, y_pred, average=None)
array([0.5, 0., 0.])
```
**y_true** [array-like of shape (n_samples,) or (n_samples, n_classes)] True labels or binary label indicators. The binary and multiclass cases expect labels with shape (n_samples,) while the multilabel case expects binary label indicators with shape (n_samples, n_classes).

**y_score** [array-like of shape (n_samples,) or (n_samples, n_classes)] Target scores.

- In the binary case, it corresponds to an array of shape (n_samples,). Both probability estimates and non-thresholded decision values can be provided. The probability estimates correspond to the **probability of the class with the greater label**, i.e. estimator.classes_[1] and thus estimator.predict_proba(X, y)[:, 1]. The decision values corresponds to the output of estimator.decision_function(X, y). See more information in the User guide;

- In the multiclass case, it corresponds to an array of shape (n_samples, n_classes) of probability estimates provided by the predict_proba method. The probability estimates must sum to 1 across the possible classes. In addition, the order of the class scores must correspond to the order of labels, if provided, or else to the numerical or lexicographical order of the labels in y_true. See more information in the User guide;

- In the multilabel case, it corresponds to an array of shape (n_samples, n_classes). Probability estimates are provided by the predict_proba method and the non-thresholded decision values by the decision_function method. The probability estimates correspond to the **probability of the class with the greater label for each output** of the classifier. See more information in the User guide.

**average** [{‘micro’, ‘macro’, ‘samples’, ‘weighted’} or None, default=’macro’] If None, the scores for each class are returned. Otherwise, this determines the type of averaging performed on the data: Note: multiclass ROC AUC currently only handles the ‘macro’ and ‘weighted’ averages.

- ‘micro’: Calculate metrics globally by considering each element of the label indicator matrix as a label.

- ‘macro’: Calculate metrics for each label, and find their unweighted mean. This does not take label imbalance into account.

- ‘weighted’: Calculate metrics for each label, and find their average, weighted by support (the number of true instances for each label).

- ‘samples’: Calculate metrics for each instance, and find their average.

Will be ignored when y_true is binary.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**max_fpr** [float > 0 and <= 1, default=None] If not None, the standardized partial AUC [2] over the range [0, max_fpr] is returned. For the multiclass case, max_fpr should be either equal to None or 1.0 as AUC ROC partial computation currently is not supported for multiclass.

**multi_class** [{‘raise’, ‘ovr’, ‘ovo’}, default=’raise’] Only used for multiclass targets. Determines the type of configuration to use. The default value raises an error, so either ‘ovr’ or ‘ovo’ must be passed explicitly.

- ‘ovr’: Stands for One-vs-rest. Computes the AUC of each class against the rest [3] [4]. This treats the multiclass case in the same way as the multilabel case. Sensitive to class imbalance even when average == ‘macro’, because class imbalance affects the composition of each of the ‘rest’ groupings.

- ‘ovo’: Stands for One-vs-one. Computes the average AUC of all possible pairwise combinations of classes [5]. Insensitive to class imbalance when average == ‘macro’.
labels [array-like of shape (n_classes,), default=None] Only used for multiclass targets. List of labels that index the classes in y_score. If None, the numerical or lexicographical order of the labels in y_true is used.

Returns

auc [float]

See also:

average_precision_score Area under the precision-recall curve.
roc_curve Compute Receiver operating characteristic (ROC) curve.
plot_roc_curve Plot Receiver operating characteristic (ROC) curve.

References

[1], [2], [3], [4], [5]

Examples

Binary case:

```python
>>> from sklearn.datasets import load_breast_cancer
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.metrics import roc_auc_score

>>> X, y = load_breast_cancer(return_X_y=True)
>>> clf = LogisticRegression(solver="liblinear", random_state=0).fit(X, y)
>>> roc_auc_score(y, clf.predict_proba(X)[:, 1])
0.99...
>>> roc_auc_score(y, clf.decision_function(X))
0.99...
```

Multiclass case:

```python
>>> from sklearn.datasets import load_iris

>>> X, y = load_iris(return_X_y=True)
>>> clf = LogisticRegression(solver="liblinear").fit(X, y)
>>> roc_auc_score(y, clf.predict_proba(X), multi_class='ovr')
0.99...
```

Multilabel case:

```python
>>> from sklearn.datasets import make_multilabel_classification

>>> X, y = make_multilabel_classification(random_state=0)
>>> clf = MultiOutputClassifier(clf).fit(X, y)
>>> # get a list of n_output containing probability arrays of shape
>>> # (n_samples, n_classes)
>>> y_pred = clf.predict_proba(X)
>>> # extract the positive columns for each output
>>> y_pred = np.transpose([pred[:, 1] for pred in y_pred])
>>> roc_auc_score(y, y_pred, average=None)
array([0.82..., 0.86..., 0.94..., 0.85..., 0.94...])
```

(continues on next page)
Examples using `sklearn.metrics.roc_auc_score`

- Release Highlights for scikit-learn 0.22
- Receiver Operating Characteristic (ROC) with cross validation
- Receiver Operating Characteristic (ROC)
- Statistical comparison of models using grid search

`sklearn.metricsROC_CURVE`

`sklearn.metrics.roc_curve` computes Receiver operating characteristic (ROC).

Note: this implementation is restricted to the binary classification task.

Read more in the User Guide.

Parameters

- `y_true` [ndarray of shape (n_samples,)] True binary labels. If labels are not either {-1, 1} or {0, 1}, then pos_label should be explicitly given.
- `y_score` [ndarray of shape (n_samples,)] Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- `pos_label` [int or str, default=None] The label of the positive class. When pos_label=None, if y_true is in {-1, 1} or {0, 1}, pos_label is set to 1, otherwise an error will be raised.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `drop_intermediate` [bool, default=True] Whether to drop some suboptimal thresholds which would not appear on a plotted ROC curve. This is useful in order to create lighter ROC curves.

Returns

- `fpr` [ndarray of shape (>2,)] Increasing false positive rates such that element i is the false positive rate of predictions with score >= thresholds[i].
- `tpr` [ndarray of shape (>2,)] Increasing true positive rates such that element i is the true positive rate of predictions with score >= thresholds[i].
- `thresholds` [ndarray of shape = (n_thresholds,)] Decreasing thresholds on the decision function used to compute fpr and tpr. thresholds[0] represents no instances being predicted and is arbitrarily set to max(y_score) + 1.

See also:

- `plot_roc_curve` Plot Receiver operating characteristic (ROC) curve.
- `RocCurveDisplay` ROC Curve visualization.
**det_curve** Compute error rates for different probability thresholds.

**roc_auc_score** Compute the area under the ROC curve.

**Notes**

Since the thresholds are sorted from low to high values, they are reversed upon returning them to ensure they correspond to both fpr and tpr, which are sorted in reversed order during their calculation.

**References**

[1], [2]

**Examples**

```python
>>> import numpy as np
>>> from sklearn import metrics

>>> y = np.array([1, 1, 2, 2])
>>> scores = np.array([0.1, 0.4, 0.35, 0.8])

>>> fpr, tpr, thresholds = metrics.roc_curve(y, scores, pos_label=2)
>>> fpr
array([0. , 0. , 0.5, 0.5, 1. ])
>>> tpr
array([0. , 0.5, 0.5, 1. , 1. ])
>>> thresholds
array([1.8 , 0.8 , 0.4 , 0.35, 0.1 ])
```

**Examples using sklearn.metrics.roc_curve**

- Feature transformations with ensembles of trees
- Species distribution modeling
- Visualizations with Display Objects
- Detection error tradeoff (DET) curve
- Receiver Operating Characteristic (ROC)

**sklearn.metrics.top_k_accuracy_score**

```python
sklearn.metrics.top_k_accuracy_score(y_true, y_score, *, k=2, normalize=True, sample_weight=None, labels=None)
```

Top-k Accuracy classification score.

This metric computes the number of times where the correct label is among the top k labels predicted (ranked by predicted scores). Note that the multilabel case isn’t covered here.

Read more in the User Guide

**Parameters**

- **y_true** [array-like of shape (n_samples,)] True labels.
y_score [array-like of shape (n_samples,) or (n_samples, n_classes)] Target scores. These can be either probability estimates or non-thresholded decision values (as returned by decision_function on some classifiers). The binary case expects scores with shape (n_samples,) while the multiclass case expects scores with shape (n_samples, n_classes). In the multiclass case, the order of the class scores must correspond to the order of labels, if provided, or else to the numerical or lexicographical order of the labels in y_true.

k [int, default=2] Number of most likely outcomes considered to find the correct label.

normalize [bool, default=True] If True, return the fraction of correctly classified samples. Otherwise, return the number of correctly classified samples.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, all samples are given the same weight.

labels [array-like of shape (n_classes,), default=None] Multiclass only. List of labels that index the classes in y_score. If None, the numerical or lexicographical order of the labels in y_true is used.

Returns

score [float] The top-k accuracy score. The best performance is 1 with normalize == True and the number of samples with normalize == False.

See also:

accuracy_score

Notes

In cases where two or more labels are assigned equal predicted scores, the labels with the highest indices will be chosen first. This might impact the result if the correct label falls after the threshold because of that.

Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import top_k_accuracy_score
>>> y_true = np.array([0, 1, 2, 2])
>>> y_score = np.array([[0.5, 0.2, 0.2],  # 0 is in top 2
                      ...       [0.3, 0.4, 0.2],  # 1 is in top 2
                      ...       [0.2, 0.4, 0.3],  # 2 is in top 2
                      ...       [0.7, 0.2, 0.1]]) # 2 isn't in top 2
>>> top_k_accuracy_score(y_true, y_score, k=2)
0.75
>>> # Not normalizing gives the number of "correctly" classified samples
>>> top_k_accuracy_score(y_true, y_score, k=2, normalize=False)
3
```
sklearn.metrics.zero_one_loss

sklearn.metrics.zero_one_loss(y_true, y_pred, *, normalize=True, sample_weight=None)

Zero-one classification loss.

If normalize is True, return the fraction of misclassifications (float), else it returns the number of misclassifications (int). The best performance is 0.

Read more in the User Guide.

Parameters

- y_true [1d array-like, or label indicator array / sparse matrix] Ground truth (correct) labels.
- y_pred [1d array-like, or label indicator array / sparse matrix] Predicted labels, as returned by a classifier.
- normalize [bool, default=True] If False, return the number of misclassifications. Otherwise, return the fraction of misclassifications.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- loss [float or int] If normalize == True, return the fraction of misclassifications (float), else it returns the number of misclassifications (int).

See also:

accuracy_score, hamming_loss, jaccard_score

Notes

In multilabel classification, the zero_one_loss function corresponds to the subset zero-one loss: for each sample, the entire set of labels must be correctly predicted, otherwise the loss for that sample is equal to one.

Examples

```python
>>> from sklearn.metrics import zero_one_loss
>>> y_pred = [1, 2, 3, 4]
>>> y_true = [2, 2, 3, 4]
>>> zero_one_loss(y_true, y_pred)
0.25
>>> zero_one_loss(y_true, y_pred, normalize=False)
1
```

In the multilabel case with binary label indicators:

```python
>>> import numpy as np
>>> zero_one_loss(np.array([[0, 1], [1, 1]]), np.ones((2, 2)))
0.5
```
Examples using `sklearn.metrics.zero_one_loss`

- Discrete versus Real AdaBoost

### 7.24.3 Regression metrics

See the Regression metrics section of the user guide for further details.

```python
metrics.explained_variance_score(y_true, y_pred, ...)  # Explained variance regression score function.
metrics.max_error(y_true, y_pred)  # max_error metric calculates the maximum residual error.
metrics.mean_absolute_error(y_true, y_pred, ...)  # Mean absolute error regression loss.
metrics.mean_squared_error(y_true, y_pred, ...)  # Mean squared error regression loss.
metrics.mean_squared_log_error(y_true, y_pred, ...)  # Mean squared logarithmic error regression loss.
metrics.median_absolute_error(y_true, y_pred, ...)  # Median absolute error regression loss.
metrics.mean_absolute_percentage_error(y_true, y_pred, ...)  # Mean absolute percentage error regression loss.
metrics.r2_score(y_true, y_pred, ...)  # R^2 (coefficient of determination) regression score function.
metrics.mean_poisson_deviance(y_true, y_pred, ...)  # Mean Poisson deviance regression loss.
metrics.mean_gamma_deviance(y_true, y_pred, ...)  # Mean Gamma deviance regression loss.
metrics.mean_tweedie_deviance(y_true, y_pred, ...)  # Mean Tweedie deviance regression loss.
```

### sklearn.metrics.explained_variance_score

`sklearn.metrics.explained_variance_score(y_true, y_pred, *, sample_weight=None, multioutput='uniform_average')`

Explained variance regression score function.

Best possible score is 1.0, lower values are worse.

Read more in the User Guide.

Parameters

- `y_true` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `multioutput` [‘raw_values’, ‘uniform_average’, ‘variance_weighted’] or array-like of shape (n_outputs,), default=’uniform_average’) Defines aggregating of multiple output scores. Array-like value defines weights used to average scores.

- ‘raw_values’: Returns a full set of scores in case of multioutput input.
- ‘uniform_average’: Scores of all outputs are averaged with uniform weight.
‘variance_weighted’ : Scores of all outputs are averaged, weighted by the variances of each individual output.

**Returns**

- **score** [float or ndarray of floats] The explained variance or ndarray if ‘multioutput’ is ‘raw_values’.

**Notes**

This is not a symmetric function.

**Examples**

```python
>>> from sklearn.metrics import explained_variance_score
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> explained_variance_score(y_true, y_pred)
0.957...

>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> explained_variance_score(y_true, y_pred, multioutput='uniform_average')
0.983...
```

**sklearn.metrics.max_error**

sklearn.metrics.max_error(y_true, y_pred)

max_error metric calculates the maximum residual error.

Read more in the *User Guide*.

**Parameters**

- **y_true** [array-like of shape (n_samples,)] Ground truth (correct) target values.
- **y_pred** [array-like of shape (n_samples,)] Estimated target values.

**Returns**

- **max_error** [float] A positive floating point value (the best value is 0.0).

**Examples**

```python
>>> from sklearn.metrics import max_error

>>> y_true = [3, 2, 7, 1]
>>> y_pred = [4, 2, 7, 1]
>>> max_error(y_true, y_pred)
1
```
**sklearn.metrics.mean_absolute_error**

```
sklearn.metrics.mean_absolute_error(y_true, y_pred, *, sample_weight=None, multioutput='uniform_average')
```

Mean absolute error regression loss.

Read more in the `User Guide`.

**Parameters**

- `y_true` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `multioutput` [‘raw_values’, ‘uniform_average’ or array-like of shape (n_outputs,), default=’uniform_average’] Defines aggregating of multiple output values. Array-like value defines weights used to average errors.
  - ‘raw_values’: Returns a full set of errors in case of multioutput input.
  - ‘uniform_average’: Errors of all outputs are averaged with uniform weight.

**Returns**

- `loss` [float or ndarray of floats] If multioutput is ‘raw_values’, then mean absolute error is returned for each output separately. If multioutput is ‘uniform_average’ or an ndarray of weights, then the weighted average of all output errors is returned.

MAE output is non-negative floating point. The best value is 0.0.

**Examples**

```python
>>> from sklearn.metrics import mean_absolute_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_absolute_error(y_true, y_pred)
0.5
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> mean_absolute_error(y_true, y_pred)
0.75
>>> mean_absolute_error(y_true, y_pred, multioutput='raw_values')
array([0.5, 1.])
>>> mean_absolute_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.85...
```
Examples using `sklearn.metrics.mean_absolute_error`

- Poisson regression and non-normal loss
- Tweedie regression on insurance claims

**sklearn.metrics.mean_squared_error**

`sklearn.metrics.mean_squared_error(y_true, y_pred, *, sample_weight=None, multioutput='uniform_average', squared=True)`

Mean squared error regression loss.

Read more in the *User Guide*.

**Parameters**

- `y_true` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `multioutput` [‘raw_values’, ‘uniform_average’ or array-like of shape (n_outputs,), default=’uniform_average’] Defines aggregating of multiple output values. Array-like value defines weights used to average errors.
  - ‘raw_values’ : Returns a full set of errors in case of multioutput input.
  - ‘uniform_average’ : Errors of all outputs are averaged with uniform weight.
- `squared` [bool, default=True] If True returns MSE value, if False returns RMSE value.

**Returns**

- `loss` [float or ndarray of floats] A non-negative floating point value (the best value is 0.0), or an array of floating point values, one for each individual target.

**Examples**

```python
>>> from sklearn.metrics import mean_squared_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_squared_error(y_true, y_pred)
0.375

>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_squared_error(y_true, y_pred, squared=False)
0.612...

>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> mean_squared_error(y_true, y_pred)
0.708...

>>> mean_squared_error(y_true, y_pred, squared=False)
0.822...

>>> mean_squared_error(y_true, y_pred, multioutput='raw_values')
array([0.41666667, 1.])

>>> mean_squared_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.825...
```
Examples using `sklearn.metrics.mean_squared_error`

- Gradient Boosting regression
- Model Complexity Influence
- Plot Ridge coefficients as a function of the L2 regularization
- Linear Regression Example
- Robust linear estimator fitting
- Poisson regression and non-normal loss
- Tweedie regression on insurance claims

`sklearn.metrics.mean_squared_log_error`

\[ \text{sklearn.metrics.mean_squared_log_error}(y_{true}, y_{pred}, *, \text{sample_weight}=\text{None}, \text{multioutput}='\text{uniform_average}') \]

Mean squared logarithmic error regression loss. Read more in the User Guide.

**Parameters**

- `y_true` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `multioutput` ['raw_values', 'uniform_average'] or array-like of shape (n_outputs,), default='uniform_average' Defines aggregating of multiple output values. Array-like value defines weights used to average errors.
  - `'raw_values'`: Returns a full set of errors when the input is of multioutput format.
  - `'uniform_average'`: Errors of all outputs are averaged with uniform weight.

**Returns**

- `loss` [float or ndarray of floats] A non-negative floating point value (the best value is 0.0), or an array of floating point values, one for each individual target.

**Examples**

```python
>>> from sklearn.metrics import mean_squared_log_error
>>> y_true = [3, 5, 2.5, 7]
>>> y_pred = [2.5, 5, 4, 8]
>>> mean_squared_log_error(y_true, y_pred)
0.039...
>>> y_true = [[0.5, 1], [1, 2], [7, 6]]
>>> y_pred = [[0.5, 2], [1, 2.5], [8, 8]]
>>> mean_squared_log_error(y_true, y_pred)
0.044...
>>> mean_squared_log_error(y_true, y_pred, multioutput='raw_values')
array([0.00462428, 0.08377444])
>>> mean_squared_log_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.060...
```
sklearn.metrics.median_absolute_error

sklearn.metrics.median_absolute_error(y_true, y_pred, *, multioutput='uniform_average', sample_weight=None)

Median absolute error regression loss.

Median absolute error output is non-negative floating point. The best value is 0.0. Read more in the User Guide.

Parameters

- **y_true** [array-like of shape = (n_samples) or (n_samples, n_outputs)] Ground truth (correct) target values.
- **y_pred** [array-like of shape = (n_samples) or (n_samples, n_outputs)] Estimated target values.
- **multioutput** [{‘raw_values’, ‘uniform_average’} or array-like of shape (n_outputs,), default=’uniform_average’] Defines aggregating of multiple output values. Array-like value defines weights used to average errors.
  - ‘raw_values’ : Returns a full set of errors in case of multioutput input.
  - ‘uniform_average’ : Errors of all outputs are averaged with uniform weight.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.
  New in version 0.24.

Returns

- **loss** [float or ndarray of floats] If multioutput is ‘raw_values’, then mean absolute error is returned for each output separately. If multioutput is ‘uniform_average’ or an ndarray of weights, then the weighted average of all output errors is returned.

Examples

```python
>>> from sklearn.metrics import median_absolute_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> median_absolute_error(y_true, y_pred)
0.5
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> median_absolute_error(y_true, y_pred)
0.75
>>> median_absolute_error(y_true, y_pred, multioutput='raw_values')
array([0.5, 1.])
>>> median_absolute_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.85
```
Examples using `sklearn.metrics.median_absolute_error`

- Common pitfalls in interpretation of coefficients of linear models
- Effect of transforming the targets in regression model

`sklearn.metrics.mean_absolute_percentage_error`

`sklearn.metrics.mean_absolute_percentage_error(y_true, y_pred, sample_weight=None, multioutput='uniform_average')`

Mean absolute percentage error regression loss.

Note here that we do not represent the output as a percentage in range [0, 100]. Instead, we represent it in range [0, 1/eps]. Read more in the User Guide.

New in version 0.24.

Parameters

- `y_true` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.
- `multioutput` [‘raw_values’, ‘uniform_average’ or array-like] Defines aggregating of multiple output values. Array-like value defines weights used to average errors. If input is list then the shape must be (n_outputs,).
  - ‘raw_values’: Returns a full set of errors in case of multioutput input.
  - ‘uniform_average’: Errors of all outputs are averaged with uniform weight.

Returns

- `loss` [float or ndarray of floats in the range [0, 1/eps]] If multioutput is ‘raw_values’, then mean absolute percentage error is returned for each output separately. If multioutput is ‘uniform_average’ or an ndarray of weights, then the weighted average of all output errors is returned.

MAPE output is non-negative floating point. The best value is 0.0. But note the fact that bad predictions can lead to arbitrarily large MAPE values, especially if some y_true values are very close to zero. Note that we return a large value instead of inf when y_true is zero.

Examples

``` python
>>> from sklearn.metrics import mean_absolute_percentage_error
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> mean_absolute_percentage_error(y_true, y_pred)
0.3273...
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> mean_absolute_percentage_error(y_true, y_pred)
0.5515...
>>> mean_absolute_percentage_error(y_true, y_pred, multioutput=[0.3, 0.7])
0.6198...
```
sklearn.metrics.r2_score

sklearn.metrics.r2_score(y_true, y_pred, *, sample_weight=None, multioutput='uniform_average')

$R^2$ (coefficient of determination) regression score function.

Best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Read more in the User Guide.

**Parameters**

- **y_true** [array-like of shape (n_samples,) or (n_samples, n_outputs)] Ground truth (correct) target values.
- **y_pred** [array-like of shape (n_samples,) or (n_samples, n_outputs)] Estimated target values.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.
- **multioutput** [{‘raw_values’, ‘uniform_average’, ‘variance_weighted’}, array-like of shape (n_outputs,) or None, default=’uniform_average’] Defines aggregating of multiple output scores. Array-like value defines weights used to average scores. Default is “uniform_average”.
  - ‘raw_values’ : Returns a full set of scores in case of multioutput input.
  - ‘uniform_average’ : Scores of all outputs are averaged with uniform weight.
  - ‘variance_weighted’ : Scores of all outputs are averaged, weighted by the variances of each individual output.

    Changed in version 0.19: Default value of multioutput is ‘uniform_average’.

**Returns**

- **z** [float or ndarray of floats] The $R^2$ score or ndarray of scores if ‘multioutput’ is ‘raw_values’.

**Notes**

This is not a symmetric function.

Unlike most other scores, $R^2$ score may be negative (it need not actually be the square of a quantity $R$).

This metric is not well-defined for single samples and will return a NaN value if n_samples is less than two.

**References**

[1]
Examples

```python
>>> from sklearn.metrics import r2_score
>>> y_true = [3, -0.5, 2, 7]
>>> y_pred = [2.5, 0.0, 2, 8]
>>> r2_score(y_true, y_pred)
0.948...
>>> y_true = [[0.5, 1], [-1, 1], [7, -6]]
>>> y_pred = [[0, 2], [-1, 2], [8, -5]]
>>> r2_score(y_true, y_pred, multioutput='variance_weighted')
0.938...
>>> y_true = [1, 2, 3]
>>> y_pred = [1, 2, 3]
>>> r2_score(y_true, y_pred)
1.0
>>> y_true = [1, 2, 3]
>>> y_pred = [2, 2, 2]
>>> r2_score(y_true, y_pred)
0.0
>>> y_true = [1, 2, 3]
>>> y_pred = [3, 2, 1]
>>> r2_score(y_true, y_pred)
-3.0
```

Examples using `sklearn.metrics.r2_score`

- Non-negative least squares
- Linear Regression Example
- Lasso and Elastic Net for Sparse Signals
- Effect of transforming the targets in regression model

`sklearn.metrics.mean_poisson_deviance`

`sklearn.metrics.mean_poisson_deviance(y_true, y_pred, *, sample_weight=None)`

Mean Poisson deviance regression loss.

Poisson deviance is equivalent to the Tweedie deviance with the power parameter `power=1`.

Read more in the User Guide.

Parameters

- `y_true` [array-like of shape (n_samples,)] Ground truth (correct) target values. Requires `y_true >= 0`.
- `y_pred` [array-like of shape (n_samples,)] Estimated target values. Requires `y_pred > 0`.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- `loss` [float] A non-negative floating point value (the best value is 0.0).
Examples

```python
>>> from sklearn.metrics import mean_poisson_deviance
>>> y_true = [2, 0, 1, 4]
>>> y_pred = [0.5, 0.5, 2., 2.]
>>> mean_poisson_deviance(y_true, y_pred)
1.4260...
```

Examples using `sklearn.metrics.mean_poisson_deviance`

- Poisson regression and non-normal loss

`sklearn.metrics.mean_gamma_deviance`

`sklearn.metrics.mean_gamma_deviance(y_true, y_pred, *, sample_weight=None)`

Mean Gamma deviance regression loss.

Gamma deviance is equivalent to the Tweedie deviance with the power parameter `power=2`. It is invariant to scaling of the target variable, and measures relative errors.

Read more in the User Guide.

Parameters

- `y_true` [array-like of shape (n_samples,)] Ground truth (correct) target values. Requires `y_true > 0`.
- `y_pred` [array-like of shape (n_samples,)] Estimated target values. Requires `y_pred > 0`.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- `loss` [float] A non-negative floating point value (the best value is 0.0).

Examples

```python
>>> from sklearn.metrics import mean_gamma_deviance
>>> y_true = [2, 0.5, 1, 4]
>>> y_pred = [0.5, 0.5, 2., 2.]
>>> mean_gamma_deviance(y_true, y_pred)
1.0568...
```

`sklearn.metrics.mean_tweedie_deviance`

`sklearn.metrics.mean_tweedie_deviance(y_true, y_pred, *, sample_weight=None, power=0)`

Mean Tweedie deviance regression loss.

Read more in the User Guide.

Parameters

- `y_true` [array-like of shape (n_samples,)] Ground truth (correct) target values.
- `y_pred` [array-like of shape (n_samples,)] Estimated target values.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

Examples

```python
>>> from sklearn.metrics import mean_tweedie_deviance
>>> y_true = [2, 0, 1, 4]
>>> y_pred = [0.5, 0.5, 2., 2.]
>>> mean_tweedie_deviance(y_true, y_pred)
1.4260...
```
**power** [float, default=0] Tweedie power parameter. Either power <= 0 or power >= 1.

The higher \( p \) the less weight is given to extreme deviations between true and predicted targets.

- power < 0: Extreme stable distribution. Requires: \( y_{\text{pred}} > 0 \).
- power = 0 : Normal distribution, output corresponds to mean_squared_error. \( y_{\text{true}} \) and \( y_{\text{pred}} \) can be any real numbers.
- power = 1 : Poisson distribution. Requires: \( y_{\text{true}} >= 0 \) and \( y_{\text{pred}} > 0 \).
- \( 1 < p < 2 \) : Compound Poisson distribution. Requires: \( y_{\text{true}} >= 0 \) and \( y_{\text{pred}} > 0 \).
- power = 2 : Gamma distribution. Requires: \( y_{\text{true}} > 0 \) and \( y_{\text{pred}} > 0 \).
- power = 3 : Inverse Gaussian distribution. Requires: \( y_{\text{true}} > 0 \) and \( y_{\text{pred}} > 0 \).
- otherwise : Positive stable distribution. Requires: \( y_{\text{true}} > 0 \) and \( y_{\text{pred}} > 0 \).

**Returns**

**loss** [float] A non-negative floating point value (the best value is 0.0).

**Examples**

```python
>>> from sklearn.metrics import mean_tweedie_deviance
>>> y_true = [2, 0, 1, 4]
>>> y_pred = [0.5, 0.5, 2., 2.]
>>> mean_tweedie_deviance(y_true, y_pred, power=1)
1.4260...
```

**Examples using sklearn.metrics.mean_tweedie_deviance**

- Tweedie regression on insurance claims

### 7.24.4 Multilabel ranking metrics

See the Multilabel ranking metrics section of the user guide for further details.

```python
metrics.coverage_error(y_true, y_score, *, [., .])
metrics.label_ranking_average_precision_score(y_true, y_score, *)
metrics.label_ranking_loss(y_true, y_score, *)
```
**sklearn.metrics.coverage_error**

`sklearn.metrics.coverage_error(y_true, y_score, *, sample_weight=None)`

Coverage error measure.

Compute how far we need to go through the ranked scores to cover all true labels. The best value is equal to the average number of labels in `y_true` per sample.

Ties in `y_scores` are broken by giving maximal rank that would have been assigned to all tied values.

Note: Our implementation’s score is 1 greater than the one given in Tsoumakas et al., 2010. This extends it to handle the degenerate case in which an instance has 0 true labels.

Read more in the *User Guide*.

**Parameters**

- **y_true** [ndarray of shape (n_samples, n_labels)] True binary labels in binary indicator format.
- **y_score** [ndarray of shape (n_samples, n_labels)] Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **coverage_error** [float]

**References**

[1]

**sklearn.metrics.label_ranking_average_precision_score**

`sklearn.metrics.label_ranking_average_precision_score(y_true, y_score, *, sample_weight=None)`

Compute ranking-based average precision.

Label ranking average precision (LRAP) is the average over each ground truth label assigned to each sample, of the ratio of true vs. total labels with lower score.

This metric is used in multilabel ranking problem, where the goal is to give better rank to the labels associated to each sample.

The obtained score is always strictly greater than 0 and the best value is 1.

Read more in the *User Guide*.

**Parameters**

- **y_true** [(ndarray, sparse matrix) of shape (n_samples, n_labels)] True binary labels in binary indicator format.
- **y_score** [ndarray of shape (n_samples, n_labels)] Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

New in version 0.20.

**Returns**
score [float]

Examples

```python
>>> import numpy as np
>>> from sklearn.metrics import label_ranking_average_precision_score

>>> y_true = np.array([[1, 0, 0], [0, 0, 1]])
>>> y_score = np.array([[0.75, 0.5, 1], [1, 0.2, 0.1]])

>>> label_ranking_average_precision_score(y_true, y_score)
0.416...
```

**sklearn.metrics.label_ranking_loss**

`sklearn.metrics.label_ranking_loss(y_true, y_score, *, sample_weight=None)`

Compute Ranking loss measure.

Compute the average number of label pairs that are incorrectly ordered given `y_score` weighted by the size of the label set and the number of labels not in the label set.

This is similar to the error set size, but weighted by the number of relevant and irrelevant labels. The best performance is achieved with a ranking loss of zero.

Read more in the *User Guide*.

New in version 0.17: A function `label_ranking_loss`

**Parameters**

- `y_true` [ndarray, sparse matrix] of shape (n_samples, n_labels): True binary labels in binary indicator format.
- `y_score` [ndarray of shape (n_samples, n_labels)]: Target scores, can either be probability estimates of the positive class, confidence values, or non-thresholded measure of decisions (as returned by “decision_function” on some classifiers).
- `sample_weight` [array-like of shape (n_samples,), default=None]: Sample weights.

**Returns**

- `loss` [float]

**References**

[1]

### 7.24.5 Clustering metrics

See the *Clustering performance evaluation* section of the user guide for further details.

The `sklearn.metrics.cluster` submodule contains evaluation metrics for cluster analysis results. There are two forms of evaluation:

- supervised, which uses a ground truth class values for each sample.
- unsupervised, which does not and measures the ‘quality’ of the model itself.
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### sklearn.metrics.adjusted_mutual_info_score

**sklearn.metrics.adjusted_mutual_info_score**(labels_true, labels_pred, *, average_method='arithmetic')

Adjusted Mutual Information between two clusterings.

Adjusted Mutual Information (AMI) is an adjustment of the Mutual Information (MI) score to account for chance. It accounts for the fact that the MI is generally higher for two clusterings with a larger number of clusters, regardless of whether there is actually more information shared. For two clusterings $U$ and $V$, the AMI is given as:

$$AMI(U, V) = \frac{MI(U, V) - E(MI(U, V))}{\frac{1}{2}(H(U) + H(V)) - E(MI(U, V))}$$

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.

This metric is furthermore symmetric: switching label_true with label_pred will return the same score value. This can be useful to measure the agreement of two independent label assignments strategies on the same dataset when the real ground truth is not known.

Be mindful that this function is an order of magnitude slower than other metrics, such as the Adjusted Rand Index.

Read more in the *User Guide*.

**Parameters**
labels_true [int array, shape = [n_samples]] A clustering of the data into disjoint subsets.

labels_pred [int array-like of shape (n_samples,)] A clustering of the data into disjoint subsets.

average_method [str, default='arithmetic'] How to compute the normalizer in the denominator. Possible options are ‘min’, ‘geometric’, ‘arithmetic’, and ‘max’.

New in version 0.20.

Changed in version 0.22: The default value of average_method changed from ‘max’ to ‘arithmetic’.

Returns

ami: float (upperlimited by 1.0) The AMI returns a value of 1 when the two partitions are identical (ie perfectly matched). Random partitions (independent labellings) have an expected AMI around 0 on average hence can be negative.

See also:

adjusted_rand_score Adjusted Rand Index.

mutual_info_score Mutual Information (not adjusted for chance).

References

[1], [2]

Examples

Perfect labelings are both homogeneous and complete, hence have score 1.0:

```python
>>> from sklearn.metrics.cluster import adjusted_mutual_info_score
>>> adjusted_mutual_info_score([0, 0, 1, 1], [0, 0, 1, 1])
... 1.0
>>> adjusted_mutual_info_score([0, 0, 1, 1], [1, 1, 0, 0])
... 1.0
```

If classes members are completely split across different clusters, the assignment is totally in-complete, hence the AMI is null:

```python
>>> adjusted_mutual_info_score([0, 0, 0, 0], [0, 1, 2, 3])
... 0.0
```

Examples using sklearn.metrics.adjusted_mutual_info_score

- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- Adjustment for chance in clustering performance evaluation
- A demo of K-Means clustering on the handwritten digits data
sklearn.metrics.adjusted_rand_score

sklearn.metrics.adjusted_rand_score(labels_true, labels_pred)

Rand index adjusted for chance.

The Rand Index computes a similarity measure between two clusterings by considering all pairs of samples and counting pairs that are assigned in the same or different clusters in the predicted and true clusterings.

The raw RI score is then “adjusted for chance” into the ARI score using the following scheme:

\[
ARI = \frac{RI - Expected_{RI}}{\max(RI) - Expected_{RI}}
\]

The adjusted Rand index is thus ensured to have a value close to 0.0 for random labeling independently of the number of clusters and samples and exactly 1.0 when the clusterings are identical (up to a permutation).

ARI is a symmetric measure:

\[
\text{adjusted_rand_score}(a, b) == \text{adjusted_rand_score}(b, a)
\]

Read more in the User Guide.

Parameters

- labels_true [int array, shape = [n_samples]] Ground truth class labels to be used as a reference
- labels_pred [array-like of shape (n_samples,)] Cluster labels to evaluate

Returns

ARI [float] Similarity score between -1.0 and 1.0. Random labelings have an ARI close to 0.0. 1.0 stands for perfect match.

See also:

adjusted_mutual_info_score Adjusted Mutual Information.

References

[Hubert1985], [Steinley2004], [wk]

Examples

Perfectly matching labelings have a score of 1 even

```python
>>> from sklearn.metrics.cluster import adjusted_rand_score
>>> adjusted_rand_score([0, 0, 1, 1], [0, 0, 1, 1])
1.0
>>> adjusted_rand_score([0, 0, 1, 1], [1, 1, 0, 0])
1.0
```

Labelings that assign all classes members to the same clusters are complete but may not always be pure, hence penalized:

```python
>>> adjusted_rand_score([0, 0, 1, 2], [0, 0, 1, 1])
0.57...
```

ARI is symmetric, so labelings that have pure clusters with members coming from the same classes but unnecessary splits are penalized:
>>> adjusted_rand_score([0, 0, 1, 1], [0, 0, 1, 2])
0.57...

If classes members are completely split across different clusters, the assignment is totally incomplete, hence the ARI is very low:

>>> adjusted_rand_score([0, 0, 0, 0], [0, 1, 2, 3])
0.0

Examples using `sklearn.metrics.adjusted_rand_score`

- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- Adjustment for chance in clustering performance evaluation
- A demo of K-Means clustering on the handwritten digits data
- Clustering text documents using k-means

`sklearn.metrics.calinski_harabasz_score`

`sklearn.metrics.calinski_harabasz_score(X, labels)`

Compute the Calinski and Harabasz score.

It is also known as the Variance Ratio Criterion.

The score is defined as ratio between the within-cluster dispersion and the between-cluster dispersion.

Read more in the User Guide.

**Parameters**

- X [array-like of shape (n_samples, n_features)] A list of n_features-dimensional data points. Each row corresponds to a single data point.
- labels [array-like of shape (n_samples,)] Predicted labels for each sample.

**Returns**

- score [float] The resulting Calinski-Harabasz score.

**References**

[1]
**sklearn.metrics.davies_bouldin_score**

*sklearn.metrics.davies_bouldin_score*(X, labels)

Computes the Davies-Bouldin score.

The score is defined as the average similarity measure of each cluster with its most similar cluster, where similarity is the ratio of within-cluster distances to between-cluster distances. Thus, clusters which are farther apart and less dispersed will result in a better score.

The minimum score is zero, with lower values indicating better clustering.

Read more in the *User Guide*.

New in version 0.20.

Parameters

- **X** [array-like of shape (n_samples, n_features)] A list of n_features-dimensional data points. Each row corresponds to a single data point.
- **labels** [array-like of shape (n_samples,)] Predicted labels for each sample.

Returns

- **score**: float The resulting Davies-Bouldin score.

References

[1]

**sklearn.metrics.completeness_score**

*sklearn.metrics.completeness_score*(labels_true, labels_pred)

Completeness metric of a cluster labeling given a ground truth.

A clustering result satisfies completeness if all the data points that are members of a given class are elements of the same cluster.

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.

This metric is not symmetric: switching label_true with label_pred will return the homogeneity_score which will be different in general.

Read more in the *User Guide*.

Parameters

- **labels_true** [int array, shape = [n_samples]] ground truth class labels to be used as a reference
- **labels_pred** [array-like of shape (n_samples,)] cluster labels to evaluate

Returns

- **completeness**: float score between 0.0 and 1.0. 1.0 stands for perfectly complete labeling

See also:

- homogeneity_score
- v_measure_score
Examples

Perfect labelings are complete:

```python
>>> from sklearn.metrics.cluster import completeness_score
>>> completeness_score([0, 0, 1, 1], [1, 1, 0, 0])
1.0
```

Non-perfect labelings that assign all classes members to the same clusters are still complete:

```python
>>> print(completeness_score([0, 0, 1, 1], [0, 0, 0, 0]))
1.0
>>> print(completeness_score([0, 1, 2, 3], [0, 0, 1, 1]))
0.999...
```

If classes members are split across different clusters, the assignment cannot be complete:

```python
>>> print(completeness_score([0, 0, 1, 1], [0, 1, 0, 1]))
0.0
>>> print(completeness_score([0, 0, 0, 0], [0, 1, 2, 3]))
0.0
```

Examples using `sklearn.metrics.completeness_score`

- Release Highlights for scikit-learn 0.23
- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- A demo of K-Means clustering on the handwritten digits data
- Clustering text documents using k-means

`sklearn.metrics.cluster.contingency_matrix`

`sklearn.metrics.cluster.contingency_matrix(labels_true, labels_pred, *, eps=None, sparse=False, dtype=<class 'numpy.int64'>)`

Build a contingency matrix describing the relationship between labels.

**Parameters**

- `labels_true` [int array, shape = [n_samples]] Ground truth class labels to be used as a reference.
- `labels_pred` [array-like of shape (n_samples,)] Cluster labels to evaluate.
- `eps` [float, default=None] If a float, that value is added to all values in the contingency matrix. This helps to stop NaN propagation. If `None`, nothing is adjusted.
- `sparse` [bool, default=False] If True, return a sparse CSR continency matrix. If `eps` is not `None` and `sparse` is `True` will raise `ValueError`.

New in version 0.18.
**dtype** [numeric type, default=np.int64] Output dtype. Ignored if eps is not None.

New in version 0.24.

**Returns**

contingency [:array-like, sparse], shape=[n_classes_true, n_classes_pred]] Matrix C such that C_{i,j} is the number of samples in true class i and in predicted class j. If eps is None, the dtype of this array will be integer unless set otherwise with the dtype argument. If eps is given, the dtype will be float. Will be a sklearn.sparse.csr_matrix if sparse=True.

**sklearn.metrics.cluster.pair_confusion_matrix**

sklearn.metrics.cluster.pair_confusion_matrix(labels_true, labels_pred)

Pair confusion matrix arising from two clusterings.

The pair confusion matrix C computes a 2 by 2 similarity matrix between two clusterings by considering all pairs of samples and counting pairs that are assigned into the same or into different clusters under the true and predicted clusterings.

Considering a pair of samples that is clustered together a positive pair, then as in binary classification the count of true negatives is C_{00}, false negatives is C_{10}, true positives is C_{11} and false positives is C_{01}.

Read more in the User Guide.

**Parameters**

labels_true [:array-like of shape (n_samples,), dtype=integral] Ground truth class labels to be used as a reference.

labels_pred [:array-like of shape (n_samples,), dtype=integral] Cluster labels to evaluate.

**Returns**

C [:ndarray of shape (2, 2), dtype=np.int64] The contingency matrix.

**See also:**

rand_score Rand Score

adjusted_rand_score Adjusted Rand Score

adjusted_mutual_info_score Adjusted Mutual Information

**References**

**Examples**

Perfectly matching labelings have all non-zero entries on the diagonal regardless of actual label values:

```python
>>> from sklearn.metrics.cluster import pair_confusion_matrix
>>> pair_confusion_matrix([[0, 0, 1, 1], [1, 1, 0, 0]])
array([[8, 0],
       [0, 4]])
```

Labelings that assign all classes members to the same clusters are complete but may be not always pure, hence penalized, and have some off-diagonal non-zero entries:
Note that the matrix is not symmetric.

**sklearn.metrics.fowlkes_mallows_score**

`sklearn.metrics.fowlkes_mallows_score(labels_true, labels_pred, *, sparse=False)`

Measure the similarity of two clusterings of a set of points.

New in version 0.18.

The Fowlkes-Mallows index (FMI) is defined as the geometric mean between of the precision and recall:

\[
FMI = \frac{TP}{\sqrt{(TP + FP) \times (TP + FN)}}
\]

Where **TP** is the number of **True Positive** (i.e. the number of pair of points that belongs in the same clusters in both `labels_true` and `labels_pred`), **FP** is the number of **False Positive** (i.e. the number of pair of points that belongs in the same clusters in `labels_true` and not in `labels_pred`) and **FN** is the number of **False Negative** (i.e. the number of pair of points that belongs in the same clusters in `labels_pred` and not in `labels_true`).

The score ranges from 0 to 1. A high value indicates a good similarity between two clusters.

Read more in the User Guide.

**Parameters**

- `labels_true` [int array, shape = (n_samples,)] A clustering of the data into disjoint subsets.
- `labels_pred` [array, shape = (n_samples,)] A clustering of the data into disjoint subsets.
- `sparse` [bool, default=False] Compute contingency matrix internally with sparse matrix.

**Returns**

- `score` [float] The resulting Fowlkes-Mallows score.

**References**

[1], [2]

**Examples**

Perfect labelings are both homogeneous and complete, hence have score 1.0:

```python
>>> from sklearn.metrics.cluster import fowlkes_mallows_score
>>> fowlkes_mallows_score([[0, 0, 1, 1], [0, 0, 1, 1]], [0, 0, 1, 1])
1.0
>>> fowlkes_mallows_score([[0, 0, 1, 1], [1, 1, 0, 0]], [0, 0, 1, 1])
1.0
```

If classes members are completely split across different clusters, the assignment is totally random, hence the FMI is null:

```python
>>> fowlkes_mallows_score([[0, 0, 0, 0], [0, 1, 2, 3]], [0, 1, 2, 3])
0.0
```
sklearn.metrics.homogeneity_completeness_v_measure

sklearn.metrics.homogeneity_completeness_v_measure(labels_true, labels_pred, beta=1.0)

Compute the homogeneity and completeness and V-Measure scores at once.

Those metrics are based on normalized conditional entropy measures of the clustering labeling to evaluate given the knowledge of a Ground Truth class labels of the same samples.

A clustering result satisfies homogeneity if all of its clusters contain only data points which are members of a single class.

A clustering result satisfies completeness if all the data points that are members of a given class are elements of the same cluster.

Both scores have positive values between 0.0 and 1.0, larger values being desirable.

Those 3 metrics are independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score values in any way.

V-Measure is furthermore symmetric: swapping labels_true and labels_pred will give the same score. This does not hold for homogeneity and completeness. V-Measure is identical to normalized_mutual_info_score with the arithmetic averaging method.

Read more in the User Guide.

Parameters

- **labels_true** [int array, shape = [n_samples]] ground truth class labels to be used as a reference
- **labels_pred** [array-like of shape (n_samples,)] cluster labels to evaluate
- **beta** [float, default=1.0] Ratio of weight attributed to homogeneity vs completeness. If beta is greater than 1, completeness is weighted more strongly in the calculation. If beta is less than 1, homogeneity is weighted more strongly.

Returns

- **homogeneity** [float] score between 0.0 and 1.0. 1.0 stands for perfectly homogeneous labeling
- **completeness** [float] score between 0.0 and 1.0. 1.0 stands for perfectly complete labeling
- **v_measure** [float] harmonic mean of the first two

See also:

- homogeneity_score
- completeness_score
- v_measure_score

sklearn.metrics.homogeneity_score

sklearn.metrics.homogeneity_score(labels_true, labels_pred)

Homogeneity metric of a cluster labeling given a ground truth.

A clustering result satisfies homogeneity if all of its clusters contain only data points which are members of a single class.

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.
This metric is not symmetric: switching `label_true` with `label_pred` will return the `completeness_score` which will be different in general.

Read more in the *User Guide*.

**Parameters**

- `labels_true` [int array, shape = [n_samples]] ground truth class labels to be used as a reference
- `labels_pred` [array-like of shape (n_samples,)] cluster labels to evaluate

**Returns**

- `homogeneity` [float] score between 0.0 and 1.0. 1.0 stands for perfectly homogeneous labeling

**See also:**

- `completeness_score`
- `v_measure_score`

**References**

[1]  

**Examples**

Perfect labelings are homogeneous:

```python
>>> from sklearn.metrics.cluster import homogeneity_score
>>> homogeneity_score([0, 0, 1, 1], [1, 1, 0, 0])
1.0
```

Non-perfect labelings that further split classes into more clusters can be perfectly homogeneous:

```python
>>> print("%.6f" % homogeneity_score([0, 0, 1, 1], [0, 0, 1, 2]))
1.000000
>>> print("%.6f" % homogeneity_score([0, 0, 1, 1], [0, 1, 2, 3]))
1.000000
```

Clusters that include samples from different classes do not make for an homogeneous labeling:

```python
>>> print("%.6f" % homogeneity_score([0, 0, 1, 1], [0, 1, 0, 1]))
0.0...
>>> print("%.6f" % homogeneity_score([0, 0, 1, 1], [0, 0, 0, 0]))
0.0...
```

**Examples using `sklearn.metrics.homogeneity_score`**

- *Demo of affinity propagation clustering algorithm*
- *Demo of DBSCAN clustering algorithm*
- *A demo of K-Means clustering on the handwritten digits data*
- *Clustering text documents using k-means*
**sklearn.metrics.mutual_info_score**

`sklearn.metrics.mutual_info_score(labels_true, labels_pred, *, contingency=None)`

*sklearn.metrics.mutual_info_score* (labels_true, labels_pred, *, contingency=None)

Mutual Information between two clusterings.

The Mutual Information is a measure of the similarity between two labels of the same data. Where $|U_i|$ is the number of the samples in cluster $U_i$ and $|V_j|$ is the number of the samples in cluster $V_j$, the Mutual Information between clusterings $U$ and $V$ is given as:

$$MI(U, V) = \sum_{i=1}^{[U]} \sum_{j=1}^{[V]} \frac{|U_i \cap V_j|}{N} \log \frac{N|U_i \cap V_j|}{|U_i||V_j|}$$

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.

This metric is furthermore symmetric: switching `label_true` with `label_pred` will return the same score value. This can be useful to measure the agreement of two independent label assignments strategies on the same dataset when the real ground truth is not known.

Read more in the User Guide.

**Parameters**

- **labels_true** [int array, shape = [n_samples]] A clustering of the data into disjoint subsets.
- **labels_pred** [int array-like of shape (n_samples,)] A clustering of the data into disjoint subsets.
- **contingency** [{ndarray, sparse matrix} of shape (n_classes_true, n_classes_pred), default=None] A contingency matrix given by the `contingency_matrix` function. If value is `None`, it will be computed, otherwise the given value is used, with `labels_true` and `labels_pred` ignored.

**Returns**

- **mi** [float] Mutual information, a non-negative value

**See also:**

- `adjusted_mutual_info_score` Adjusted against chance Mutual Information.
- `normalized_mutual_info_score` Normalized Mutual Information.

**Notes**

The logarithm used is the natural logarithm (base-e).

**Examples using sklearn.metrics.mutual_info_score**

- *Adjustment for chance in clustering performance evaluation*
sklearn.metrics.normalized_mutual_info_score

**sklearn.metrics.normalized_mutual_info_score** (labels_true, labels_pred, *, average_method='arithmetic')

Normalized Mutual Information between two clusterings.

Normalized Mutual Information (NMI) is a normalization of the Mutual Information (MI) score to scale the results between 0 (no mutual information) and 1 (perfect correlation). In this function, mutual information is normalized by some generalized mean of \(H(labels\_true)\) and \(H(labels\_pred)\), defined by the **average_method**.

This measure is not adjusted for chance. Therefore **adjusted_mutual_info_score** might be preferred.

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.

This metric is furthermore symmetric: switching **label_true** with **label_pred** will return the same score value. This can be useful to measure the agreement of two independent label assignments strategies on the same dataset when the real ground truth is not known.

Read more in the **User Guide**.

**Parameters**

- **labels_true** [int array, shape = [n_samples]] A clustering of the data into disjoint subsets.
- **labels_pred** [int array-like of shape (n_samples,)] A clustering of the data into disjoint subsets.
- **average_method** [str, default='arithmetic'] How to compute the normalizer in the denominator. Possible options are ‘min’, ‘geometric’, ‘arithmetic’, and ‘max’.

  New in version 0.20.

  Changed in version 0.22: The default value of **average_method** changed from ‘geometric’ to ‘arithmetic’.

**Returns**

- **nmi** [float] score between 0.0 and 1.0. 1.0 stands for perfectly complete labeling

**See also:**

- **v_measure_score** V-Measure (NMI with arithmetic mean option).
- **adjusted_rand_score** Adjusted Rand Index.
- **adjusted_mutual_info_score** Adjusted Mutual Information (adjusted against chance).

**Examples**

Perfect labelings are both homogeneous and complete, hence have score 1.0:

```python
>>> from sklearn.metrics.cluster import normalized_mutual_info_score
>>> normalized_mutual_info_score([0, 0, 1, 1], [0, 0, 1, 1])
1.0
>>> normalized_mutual_info_score([0, 1, 1, 1], [1, 0, 0, 0])
1.0
```

If classes members are completely split across different clusters, the assignment is totally in-complete, hence the NMI is null:
sklearn.metrics.rand_score

`sklearn.metrics.rand_score(labels_true, labels_pred)`

Rand index.

The Rand Index computes a similarity measure between two clusterings by considering all pairs of samples and counting pairs that are assigned in the same or different clusters in the predicted and true clusterings.

The raw RI score is:

\[ RI = \frac{\text{number of agreeing pairs}}{\text{number of pairs}} \]

Read more in the User Guide.

Parameters

- `labels_true` [array-like of shape (n_samples,), dtype=integral] Ground truth class labels to be used as a reference.
- `labels_pred` [array-like of shape (n_samples,), dtype=integral] Cluster labels to evaluate.

Returns

- `RI` [float] Similarity score between 0.0 and 1.0, inclusive, 1.0 stands for perfect match.

See also:

- `adjusted_rand_score` Adjusted Rand Score
- `adjusted_mutual_info_score` Adjusted Mutual Information

References

Examples

Perfectly matching labelings have a score of 1 even

```python
>>> from sklearn.metrics.cluster import rand_score
>>> rand_score([0, 0, 1, 1], [1, 1, 0, 0])
1.0
```

Labelings that assign all classes members to the same clusters are complete but may not always be pure, hence penalized:

```python
>>> rand_score([0, 0, 1, 2], [0, 0, 1, 1])
0.83...
```
sklearn.metrics.silhouette_score

**sklearn.metrics.silhouette_score** *(X, labels, *, metric='euclidean', sample_size=None, random_state=None, **kwds)*

Compute the mean Silhouette Coefficient of all samples.

The Silhouette Coefficient is calculated using the mean intra-cluster distance \((a)\) and the mean nearest-cluster distance \((b)\) for each sample. The Silhouette Coefficient for a sample is \((b - a) / \max(a, b)\). To clarify, \(b\) is the distance between a sample and the nearest cluster that the sample is not a part of. Note that Silhouette Coefficient is only defined if number of labels is \(2 \leq n\_labels \leq n\_samples - 1\).

This function returns the mean Silhouette Coefficient over all samples. To obtain the values for each sample, use **silhouette_samples**.

The best value is 1 and the worst value is -1. Values near 0 indicate overlapping clusters. Negative values generally indicate that a sample has been assigned to the wrong cluster, as a different cluster is more similar. Read more in the User Guide.

**Parameters**

- **X** [array-like of shape (n_samples_a, n_samples_a) if metric == “precomputed” or (n_samples_a, n_features) otherwise] An array of pairwise distances between samples, or a feature array.
- **labels** [array-like of shape (n_samples,)] Predicted labels for each sample.
- **metric** [str or callable, default='euclidean'] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options allowed by metrics.pairwise.pairwise_distances. If X is the distance array itself, use metric="precomputed".
- **sample_size** [int, default=None] The size of the sample to use when computing the Silhouette Coefficient on a random subset of the data. If sample_size is None, no sampling is used.
- **random_state** [int, RandomState instance or None, default=None] Determines random number generation for selecting a subset of samples. Used when sample_size is not None. Pass an int for reproducible results across multiple function calls. See Glossary.
- **kwds** [optional keyword parameters] Any further parameters are passed directly to the distance function. If using a scipy.spatial.distance metric, the parameters are still metric dependent. See the scipy docs for usage examples.

**Returns**

- **silhouette** [float] Mean Silhouette Coefficient for all samples.

**References**

[1], [2]
Examples using sklearn.metrics.silhouette_score

- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- A demo of K-Means clustering on the handwritten digits data
- Selecting the number of clusters with silhouette analysis on KMeans clustering
- Clustering text documents using k-means

sklearn.metrics.silhouette_samples

sklearn.metrics.silhouette_samples(X, labels, *, metric='euclidean', **kwds)

Compute the Silhouette Coefficient for each sample.

The Silhouette Coefficient is a measure of how well samples are clustered with samples that are similar to themselves. Clustering models with a high Silhouette Coefficient are said to be dense, where samples in the same cluster are similar to each other, and well separated, where samples in different clusters are not very similar to each other.

The Silhouette Coefficient is calculated using the mean intra-cluster distance \( a \) and the mean nearest-cluster distance \( b \) for each sample. The Silhouette Coefficient for a sample is \( \frac{(b - a)}{\max(a, b)} \). Note that Silhouette Coefficient is only defined if number of labels \( 2 \leq n_{labels} \leq n_{samples} - 1 \).

This function returns the Silhouette Coefficient for each sample.

The best value is 1 and the worst value is -1. Values near 0 indicate overlapping clusters.

Read more in the User Guide.

Parameters

- **X** [array-like of shape \( (n_{samples}, n_{samples}) \) if metric == “precomputed” or \( (n_{samples}, n_{features}) \) otherwise] An array of pairwise distances between samples, or a feature array.
- **labels** [array-like of shape \( (n_{samples},) \)] Label values for each sample.
- **metric** [str or callable, default=’euclidean’] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options allowed by sklearn.metrics.pairwise.pairwise_distances. If X is the distance array itself, use “precomputed” as the metric. Precomputed distance matrices must have 0 along the diagonal.
- **\**kwds\** [optional keyword parameters] Any further parameters are passed directly to the distance function. If using a scipy.spatial.distance metric, the parameters are still metric dependent. See the scipy docs for usage examples.

Returns

- **silhouette** [array-like of shape \( (n_{samples},) \)] Silhouette Coefficients for each sample.
References

[1], [2]

Examples using `sklearn.metrics.silhouette_samples`

• Selecting the number of clusters with silhouette analysis on KMeans clustering

`sklearn.metrics.v_measure_score`

`sklearn.metrics.v_measure_score(labels_true, labels_pred, *, beta=1.0)`

V-measure cluster labeling given a ground truth.

This score is identical to `normalized_mutual_info_score` with the 'arithmetic' option for averaging.

The V-measure is the harmonic mean between homogeneity and completeness:

\[
v = \frac{(1 + \beta) \cdot \text{homogeneity} \cdot \text{completeness}}{\beta \cdot \text{homogeneity} + \text{completeness}}
\]

This metric is independent of the absolute values of the labels: a permutation of the class or cluster label values won’t change the score value in any way.

This metric is furthermore symmetric: switching `label_true` with `label_pred` will return the same score value. This can be useful to measure the agreement of two independent label assignments strategies on the same dataset when the real ground truth is not known.

Read more in the User Guide.

Parameters

- `labels_true` [int array, shape = [n_samples]] ground truth class labels to be used as a reference
- `labels_pred` [array-like of shape (n_samples,)] cluster labels to evaluate
- `beta` [float, default=1.0] Ratio of weight attributed to homogeneity vs completeness. If `beta` is greater than 1, completeness is weighted more strongly in the calculation. If `beta` is less than 1, homogeneity is weighted more strongly.

Returns

- `v_measure` [float] score between 0.0 and 1.0. 1.0 stands for perfectly complete labeling

See also:

- `homogeneity_score`
- `completeness_score`
- `normalized_mutual_info_score`
## Examples

Perfect labelings are both homogeneous and complete, hence have score 1.0:

```python
>>> from sklearn.metrics.cluster import v_measure_score
>>> v_measure_score([0, 0, 1, 1], [0, 0, 1, 1])
1.0
>>> v_measure_score([0, 0, 1, 1], [1, 1, 0, 0])
1.0
```

Labelings that assign all classes members to the same clusters are complete be not homogeneous, hence penalized:

```python
>>> print("%.6f" % v_measure_score([0, 0, 1, 2], [0, 0, 1, 1]))
0.8...
>>> print("%.6f" % v_measure_score([0, 1, 2, 3], [0, 0, 1, 1]))
0.66...
```

Labelings that have pure clusters with members coming from the same classes are homogeneous but unnecessary splits harms completeness and thus penalize V-measure as well:

```python
>>> print("%.6f" % v_measure_score([0, 0, 1, 1], [0, 0, 1, 2]))
0.8...
>>> print("%.6f" % v_measure_score([0, 0, 1, 1], [0, 1, 2, 3]))
0.66...
```

If classes members are completely split across different clusters, the assignment is totally incomplete, hence the V-Measure is null:

```python
>>> print("%.6f" % v_measure_score([0, 0, 0, 0], [0, 1, 2, 3]))
0.0...
```

Clusters that include samples from totally different classes totally destroy the homogeneity of the labeling, hence:

```python
>>> print("%.6f" % v_measure_score([0, 0, 1, 1], [0, 0, 0, 0]))
0.0...
```

## Examples using sklearn.metrics.v_measure_score

- Biclustering documents with the Spectral Co-clustering algorithm
- Demo of affinity propagation clustering algorithm
- Demo of DBSCAN clustering algorithm
- Adjustment for chance in clustering performance evaluation
- A demo of K-Means clustering on the handwritten digits data
- Clustering text documents using k-means
### 7.24.6 Biclustering metrics

See the *Biclustering evaluation* section of the user guide for further details.

```python
metrics.consensus_score(a, b, *[ similarity])  # The similarity of two sets of biclusters.
```

**sklearn.metrics.consensus_score**

```python
sklearn.metrics.consensus_score(a, b, *, similarity=’jaccard’)  # The similarity of two sets of biclusters.
```

Similarity between individual biclusters is computed. Then the best matching between sets is found using the Hungarian algorithm. The final score is the sum of similarities divided by the size of the larger set.

Read more in the *User Guide*.

**Parameters**

- **a** [(rows, columns)] Tuple of row and column indicators for a set of biclusters.
- **b** [(rows, columns)] Another set of biclusters like `a`.
- **similarity** [‘jaccard’ or callable, default=’jaccard’] May be the string “jaccard” to use the Jaccard coefficient, or any function that takes four arguments, each of which is a 1d indicator vector: (a_rows, a_columns, b_rows, b_columns).

**References**

- Hochreiter, Bodenhofer, et. al., 2010. FABIA: factor analysis for bicluster acquisition.

**Examples using sklearn.metrics.consensus_score**

- *A demo of the Spectral Co-Clustering algorithm*
- *A demo of the Spectral Biclustering algorithm*

### 7.24.7 Pairwise metrics

See the *Pairwise metrics, Affinities and Kernels* section of the user guide for further details.

```python
metrics.pairwise.additive_chi2_kernel(X[, Y])  # Computes the additive chi-squared kernel between observations in X and Y.
metrics.pairwise.chi2_kernel(X[, Y, gamma])  # Computes the exponential chi-squared kernel X and Y.
metrics.pairwise.cosine_similarity(X[, Y, …])  # Compute cosine similarity between samples in X and Y.
metrics.pairwise.cosine_distances(X[, Y])  # Compute cosine distance between samples in X and Y.
metrics.pairwise.distance_metrics()  # Valid metrics for pairwise_distances.
metrics.pairwise.euclidean_distances(X[, Y, …])  # Considering the rows of X (and Y=X) as vectors, compute the distance matrix between each pair of vectors.
```

continues on next page
Table 216 – continued from previous page

**metrics.pairwise.**

- **haversine_distances(X[, Y])**
  - Compute the Haversine distance between samples in X and Y.
- **kernel_metrics()**
  - Valid metrics for pairwise_kernels.
- **laplacian_kernel(X[, Y, gamma])**
  - Compute the laplacian kernel between X and Y.
- **linear_kernel(X[, Y, ...])**
  - Compute the linear kernel between X and Y.
- **manhattan_distances(X[, Y, ...])**
  - Compute the L1 distances between the vectors in X and Y.
- **nan_euclidean_distances(X)**
  - Calculate the euclidean distances in the presence of missing values.
- **pairwise_kernels(X[, Y, ...])**
  - Compute the kernel between arrays X and optional array Y.
- **polynomial_kernel(X[, Y, ...])**
  - Compute the polynomial kernel between X and Y.
- **rbf_kernel(X[, Y, gamma])**
  - Compute the rbf (gaussian) kernel between X and Y.
- **sigmoid_kernel(X[, Y, ...])**
  - Compute the sigmoid kernel between X and Y.
- **paired_euclidean_distances(X, Y)**
  - Computes the paired euclidean distances between X and Y.
- **paired_manhattan_distances(X, Y)**
  - Compute the L1 distances between the vectors in X and Y.
- **paired_cosine_distances(X, Y)**
  - Computes the paired cosine distances between X and Y.
- **paired_distances(X, Y, *[,...])**
  - Computes the paired distances between X and Y.
- **pairwise_distances(X[, Y, metric, ...])**
  - Compute the distance matrix from a vector array X and optional Y.
- **pairwise_distances_argmin(X, Y, *[,...])**
  - Compute minimum distances between one point and a set of points.
- **pairwise_distances_argmin_min(X, Y, *)**
  - Compute minimum distances between one point and a set of points.
- **pairwise_distances_chunked(X[, Y, ...])**
  - Generate a distance matrix chunk by chunk with optional reduction.

**sklearn.metrics.pairwise.additive_chi2_kernel**

**sklearn.metrics.pairwise.additive_chi2_kernel** *(X, Y=None)*

Computes the additive chi-squared kernel between observations in X and Y.

The chi-squared kernel is computed between each pair of rows in X and Y. X and Y have to be non-negative. This kernel is most commonly applied to histograms.

The chi-squared kernel is given by:

\[
\kappa(x, y) = -\text{Sum} \left[ \frac{(x - y)^2}{x + y} \right]
\]

It can be interpreted as a weighted difference per entry.

Read more in the User Guide.

Parameters
X [array-like of shape (n_samples_X, n_features)]
Y [ndarray of shape (n_samples_Y, n_features), default=None]

Returns
  kernel_matrix [ndarray of shape (n_samples_X, n_samples_Y)]

See also:
  chi2_kernel The exponentiated version of the kernel, which is usually preferable.
  sklearn.kernel_approximation.AdditiveChi2Sampler A Fourier approximation to this kernel.

Notes
As the negative of a distance, this kernel is only conditionally positive definite.

References
References


**sklearn.metrics.pairwise.cosine_similarity**

```python
sklearn.metrics.pairwise.cosine_similarity(X, Y=None, dense_output=True)
```

Compute cosine similarity between samples in X and Y.

Cosine similarity, or the cosine kernel, computes similarity as the normalized dot product of X and Y:

\[ K(X, Y) = \frac{<X, Y>}{\|X\| \|Y\|} \]

On L2-normalized data, this function is equivalent to linear_kernel.

Read more in the User Guide.

**Parameters**

- **X** [ndarray, sparse matrix] of shape (n_samples_X, n_features)] Input data.
- **Y** [ndarray, sparse matrix] of shape (n_samples_Y, n_features), default=None] Input data. If None, the output will be the pairwise similarities between all samples in X.
- **dense_output** [bool, default=True] Whether to return dense output even when the input is sparse. If False, the output is sparse if both input arrays are sparse.

**Returns**

- **kernel matrix** [ndarray of shape (n_samples_X, n_samples_Y)]

**sklearn.metrics.pairwise.cosine_distances**

```python
sklearn.metrics.pairwise.cosine_distances(X, Y=None)
```

Compute cosine distance between samples in X and Y.

Cosine distance is defined as 1.0 minus the cosine similarity.

Read more in the User Guide.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples_X, n_features)] Matrix X.
- **Y** [array-like, sparse matrix] of shape (n_samples_Y, n_features), default=None] Matrix Y.

**Returns**

- **distance matrix** [ndarray of shape (n_samples_X, n_samples_Y)]

**See also:**

- `cosine_similarity`
- `scipy.spatial.distance.cosine` Dense matrices only.
**sklearn.metrics.pairwise.distance_metrics**

This function simply returns the valid pairwise distance metrics. It exists to allow for a description of the mapping for each of the valid strings.

The valid distance metrics, and the function they map to, are:

<table>
<thead>
<tr>
<th>metric</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>'cityblock'</td>
<td>sklearn.metrics.pairwise.manhattan_distances</td>
</tr>
<tr>
<td>'cosine'</td>
<td>sklearn.metrics.pairwise.cosine_distances</td>
</tr>
<tr>
<td>'euclidean'</td>
<td>sklearn.metrics.pairwise.euclidean_distances</td>
</tr>
<tr>
<td>'haversine'</td>
<td>sklearn.metrics.pairwise.haversine_distances</td>
</tr>
<tr>
<td>'l1'</td>
<td>sklearn.metrics.pairwise.manhattan_distances</td>
</tr>
<tr>
<td>'l2'</td>
<td>sklearn.metrics.pairwise.euclidean_distances</td>
</tr>
<tr>
<td>'manhattan'</td>
<td>sklearn.metrics.pairwise.manhattan_distances</td>
</tr>
<tr>
<td>'nan_euclidean'</td>
<td>sklearn.metrics.pairwise.nan_euclidean_distances</td>
</tr>
</tbody>
</table>

Read more in the *User Guide*.

**sklearn.metrics.pairwise.euclidean_distances**

Considering the rows of X (and Y=X) as vectors, compute the distance matrix between each pair of vectors.

For efficiency reasons, the euclidean distance between a pair of row vector x and y is computed as:

\[
dist(x, y) = \sqrt{\text{dot}(x, x) - 2 \times \text{dot}(x, y) + \text{dot}(y, y)}
\]

This formulation has two advantages over other ways of computing distances. First, it is computationally efficient when dealing with sparse data. Second, if one argument varies but the other remains unchanged, then \(\text{dot}(x, x)\) and/or \(\text{dot}(y, y)\) can be pre-computed.

However, this is not the most precise way of doing this computation, because this equation potentially suffers from “catastrophic cancellation”. Also, the distance matrix returned by this function may not be exactly symmetric as required by, e.g., *scipy.spatial.distance* functions.

Read more in the *User Guide*.

**Parameters**

- **X** *(array-like, sparse matrix) of shape (n_samples_X, n_features)]*
- **Y** *(array-like, sparse matrix) of shape (n_samples_Y, n_features), default=None]*
- **Y_norm_squared** *(array-like of shape (n_samples_Y), default=None) Pre-computed dot-products of vectors in Y (e.g., \(Y**2\).sum(axis=1)) May be ignored in some cases, see the note below.*
- **squared** *(bool, default=False) Return squared Euclidean distances.*
- **X_norm_squared** *(array-like of shape (n_samples,), default=None) Pre-computed dot-products of vectors in X (e.g., \(X**2\).sum(axis=1)) May be ignored in some cases, see the note below.*

**Returns**
distances [ndarray of shape (n_samples_X, n_samples_Y)]

See also:

paired_distances Distances between pairs of elements of X and Y.

Notes

To achieve better accuracy, X_norm_squared and Y_norm_squared may be unused if they are passed as float32.

Examples

```python
>>> from sklearn.metrics.pairwise import euclidean_distances
>>> X = [[0, 1], [1, 1]]
>>> # distance between rows of X
>>> euclidean_distances(X, X)
array([[0., 1.],
       [1., 0.]])
>>> # get distance to origin
>>> euclidean_distances(X, [[0, 0]])
array([[1. ],
       [1.41421356]])
```

sklearn.metrics.pairwise.haversine_distances

sklearn.metrics.pairwise.haversine_distances(X, Y=None)
Compute the Haversine distance between samples in X and Y.

The Haversine (or great circle) distance is the angular distance between two points on the surface of a sphere. The first coordinate of each point is assumed to be the latitude, the second is the longitude, given in radians. The dimension of the data must be 2.

\[
D(x, y) = 2 \arcsin(\sqrt{\sin^2((x_1 - y_1)/2) + \cos(x_1) \cos(y_1) \sin^2((x_2 - y_2)/2)})
\]

Parameters

- **X** [array-like of shape (n_samples_X, 2)]
- **Y** [array-like of shape (n_samples_Y, 2), default=None]

Returns

- **distance** [ndarray of shape (n_samples_X, n_samples_Y)]

Notes

As the Earth is nearly spherical, the haversine formula provides a good approximation of the distance between two points of the Earth surface, with a less than 1% error on average.
Examples

We want to calculate the distance between the Ezeiza Airport (Buenos Aires, Argentina) and the Charles de Gaulle Airport (Paris, France).

```python
>>> from sklearn.metrics.pairwise import haversine_distances
>>> from math import radians

>>> bsas = [-34.83333, -58.5166646]
>>> paris = [49.0083899664, 2.53844117956]
>>> bsas_in_radians = [radians(_) for _ in bsas]
>>> paris_in_radians = [radians(_) for _ in paris]
>>> result = haversine_distances([bsas_in_radians, paris_in_radians])
>>> result * 6371000/1000  # multiply by Earth radius to get kilometers
array([[  0.        , 11099.54035582],
       [11099.54035582,    0.00000000]])
```

**sklearn.metrics.pairwise.kernel_metrics**

**sklearn.metrics.pairwise.kernel_metrics()**

Valid metrics for pairwise_kernels.

This function simply returns the valid pairwise distance metrics. It exists, however, to allow for a verbose description of the mapping for each of the valid strings.

The valid distance metrics, and the function they map to, are:

<table>
<thead>
<tr>
<th>metric</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>'additive_chi2'</td>
<td>sklearn.pairwise.additive_chi2_kernel</td>
</tr>
<tr>
<td>'chi2'</td>
<td>sklearn.pairwise.chi2_kernel</td>
</tr>
<tr>
<td>'linear'</td>
<td>sklearn.pairwise.linear_kernel</td>
</tr>
<tr>
<td>'poly'</td>
<td>sklearn.pairwise.polynomial_kernel</td>
</tr>
<tr>
<td>'polynomial'</td>
<td>sklearn.pairwise.polynomial_kernel</td>
</tr>
<tr>
<td>'rbf'</td>
<td>sklearn.pairwise.rbf_kernel</td>
</tr>
<tr>
<td>'laplacian'</td>
<td>sklearn.pairwise.laplacian_kernel</td>
</tr>
<tr>
<td>'sigmoid'</td>
<td>sklearn.pairwise.sigmoid_kernel</td>
</tr>
<tr>
<td>'cosine'</td>
<td>sklearn.pairwise.cosine_similarity</td>
</tr>
</tbody>
</table>

Read more in the User Guide.

**sklearn.metrics.pairwise.laplacian_kernel**

**sklearn.metrics.pairwise.laplacian_kernel(X, Y=None, gamma=None)**

Compute the laplacian kernel between X and Y.

The laplacian kernel is defined as:

\[ K(x, y) = \exp(-\gamma ||x-y||_1) \]

for each pair of rows x in X and y in Y. Read more in the User Guide.

New in version 0.17.

**Parameters**

X [ndarray of shape (n_samples_X, n_features)]
**sklearn.metrics.pairwise.linear_kernel**

**sklearn.metrics.pairwise.linear_kernel** *(X, Y=None, dense_output=True)*

Compute the linear kernel between *X* and *Y*.

Read more in the *User Guide*.

**Parameters**

- **X** *(ndarray of shape (n_samples_X, n_features))*
- **Y** *(ndarray of shape (n_samples_Y, n_features), default=None)*
- **dense_output** *(bool, default=True)* Whether to return dense output even when the input is sparse. If False, the output is sparse if both input arrays are sparse.

**Returns**

**Gram matrix** *(ndarray of shape (n_samples_X, n_samples_Y))*

**sklearn.metrics.pairwise.manhattan_distances**

**sklearn.metrics.pairwise.manhattan_distances** *(X, Y=None, *, sum_over_features=True)*

Compute the L1 distances between the vectors in *X* and *Y*.

With sum_over_features equal to False it returns the componentwise distances.

Read more in the *User Guide*.

**Parameters**

- **X** *(array-like of shape (n_samples_X, n_features))*
- **Y** *(array-like of shape (n_samples_Y, n_features), default=None)*
- **sum_over_features** *(bool, default=True)* If True the function returns the pairwise distance matrix else it returns the componentwise L1 pairwise-distances. Not supported for sparse matrix inputs.

**Returns**

**D** *(ndarray of shape (n_samples_X * n_samples_Y, n_features) or (n_samples_X, n_samples_Y)) If sum_over_features is False shape is (n_samples_X * n_samples_Y, n_features) and D contains the componentwise L1 pairwise-distances (ie. absolute difference), else shape is (n_samples_X, n_samples_Y) and D contains the pairwise L1 distances.*
Notes

When X and/or Y are CSR sparse matrices and they are not already in canonical format, this function modifies them in-place to make them canonical.

Examples

```python
>>> from sklearn.metrics.pairwise import manhattan_distances
>>> manhattan_distances([[3]], [[3]])
array([[0.]])
>>> manhattan_distances([[3]], [[2]])
array([[1.]])
>>> manhattan_distances([[2]], [[3]])
array([[1.]])
>>> manhattan_distances([[1, 2], [3, 4]], [[1, 2], [0, 3]])
array([[0., 2.],
       [4., 4.]])
>>> import numpy as np
>>> X = np.ones((1, 2))
>>> y = np.full((2, 2), 2.)
>>> manhattan_distances(X, y, sum_over_features=False)
array([[1., 1.],
       [1., 1.]])
```

**sklearn.metrics.pairwise.nan_euclidean_distances**

The function `sklearn.metrics.pairwise.nan_euclidean_distances` calculates the Euclidean distances in the presence of missing values.

It takes two parameters, `X` and `Y`, which are array-like of shape `(n_samples_X, n_features)` and `(n_samples_Y, n_features)` respectively. The parameter `squared` is a boolean value indicating whether to return squared Euclidean distances. The parameter `missing_values` is the value to treat as missing. The parameter `copy` is a boolean indicating whether to make a copy of the input arrays before computing the distances.

Compute the Euclidean distance between each pair of samples in X and Y, where Y=X is assumed if Y=None. When calculating the distance between a pair of samples, this formulation ignores feature coordinates with a missing value in either sample and scales up the weight of the remaining coordinates:

\[
dist(x,y) = \sqrt{weight \times \text{sq. distance from present coordinates}}
\]

where, weight = Total # of coordinates / # of present coordinates

For example, the distance between `[3, na, na, 6]` and `[1, na, 4, 5]` is:

\[
\sqrt{\frac{4}{2}((3-1)^2 + (6-5)^2)}
\]

If all the coordinates are missing or if there are no common present coordinates then NaN is returned for that pair.

Read more in the *User Guide*.

New in version 0.22.

**Parameters**

- **X** [array-like of shape=(n_samples_X, n_features)]
- **Y** [array-like of shape=(n_samples_Y, n_features), default=None]
- **squared** [bool, default=False] Return squared Euclidean distances.
missing_values [np.nan or int, default=np.nan] Representation of missing value.

copy [bool, default=True] Make and use a deep copy of X and Y (if Y exists).

Returns
distances [ndarray of shape (n_samples_X, n_samples_Y)]

See also:

paired_distances Distances between pairs of elements of X and Y.

References


Examples

```python
>>> from sklearn.metrics.pairwise import nan_euclidean_distances
>>> nan = float("NaN")
>>> X = [[0, 1], [1, nan]]
>>> nan_euclidean_distances(X, X)  # distance between rows of X
array([[0. , 1.41421356],
       [1.41421356, 0. ]])

>>> # get distance to origin
>>> nan_euclidean_distances(X, [[0, 0]])
array([[1. ],
       [1.41421356]])
```

sklearn.metrics.pairwise.pairwise_kernels

`sklearn.metrics.pairwise.pairwise_kernels(X, Y=None, metric='linear', *, filter_params=False, n_jobs=None, **kwds)`

Compute the kernel between arrays X and optional array Y.

This method takes either a vector array or a kernel matrix, and returns a kernel matrix. If the input is a vector array, the kernels are computed. If the input is a kernel matrix, it is returned instead.

This method provides a safe way to take a kernel matrix as input, while preserving compatibility with many other algorithms that take a vector array.

If Y is given (default is None), then the returned matrix is the pairwise kernel between the arrays from both X and Y.

Valid values for metric are: ['additive_chi2', 'chi2', 'linear', 'poly', 'polynomial', 'rbf', 'laplacian', 'sigmoid', 'cosine']

Read more in the User Guide.

Parameters

X [ndarray of shape (n_samples_X, n_samples_X) or (n_samples_X, n_features)] Array of pairwise kernels between samples, or a feature array. The shape of the array should be
(n_samples_X, n_samples_X) if metric == “precomputed” and (n_samples_X, n_features) otherwise.

Y [ndarray of shape (n_samples_Y, n_features), default=None] A second feature array only if X has shape (n_samples_X, n_features).

metric [str or callable, default=”linear”] The metric to use when calculating kernel between instances in a feature array. If metric is a string, it must be one of the metrics in pairwise.PAIRWISE_KERNEL_FUNCTIONS. If metric is “precomputed”, X is assumed to be a kernel matrix. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two rows from X as input and return the corresponding kernel value as a single number. This means that callables from sklearn.metrics.pairwise are not allowed, as they operate on matrices, not single samples. Use the string identifying the kernel instead.

filter_params [bool, default=False] Whether to filter invalid parameters or not.

n_jobs [int, default=None] The number of jobs to use for the computation. This works by breaking down the pairwise matrix into n_jobs even slices and computing them in parallel.

None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**kwds [optional keyword parameters] Any further parameters are passed directly to the kernel function.

Returns

K [ndarray of shape (n_samples_X, n_samples_X) or (n_samples_X, n_samples_Y)] A kernel matrix K such that K_{i, j} is the kernel between the ith and jth vectors of the given matrix X, if Y is None. If Y is not None, then K_{i, j} is the kernel between the ith array from X and the jth array from Y.

Notes

If metric is ‘precomputed’, Y is ignored and X is returned.

```python
sklearn.metrics.pairwise.polynomial_kernel
```

sklearn.metrics.pairwise.polynomial_kernel(X, Y=None, degree=3, gamma=None, coef0=1)

Compute the polynomial kernel between X and Y:

\[ K(X, Y) = (\gamma \langle X, Y \rangle + \text{coef0})^\text{degree} \]

Read more in the User Guide.

Parameters

X [ndarray of shape (n_samples_X, n_features)]

Y [ndarray of shape (n_samples_Y, n_features), default=None]

degree [int, default=3]

gamma [float, default=None] If None, defaults to 1.0 / n_features.

coef0 [float, default=1]

Returns
**Gram matrix** [ndarray of shape (n_samples_X, n_samples_Y)]

**sklearn.metrics.pairwise.rbf_kernel**

```python
sklearn.metrics.pairwise.rbf_kernel(X, Y=None, gamma=None)
```

Compute the rbf (gaussian) kernel between X and Y:

\[
K(x, y) = \exp(-\gamma ||x-y||^2)
\]

for each pair of rows x in X and y in Y.

Read more in the *User Guide*.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)]
- **Y** [ndarray of shape (n_samples_Y, n_features), default=None]
- **gamma** [float, default=None] If None, defaults to 1.0 / n_features.

**Returns**

**kernel_matrix** [ndarray of shape (n_samples_X, n_samples_Y)]

**sklearn.metrics.pairwise.sigmoid_kernel**

```python
sklearn.metrics.pairwise.sigmoid_kernel(X, Y=None, gamma=None, coef0=1)
```

Compute the sigmoid kernel between X and Y:

\[
K(X, Y) = \tanh(\gamma \langle X, Y \rangle + \text{coef0})
\]

Read more in the *User Guide*.

**Parameters**

- **X** [ndarray of shape (n_samples_X, n_features)]
- **Y** [ndarray of shape (n_samples_Y, n_features), default=None]
- **gamma** [float, default=None] If None, defaults to 1.0 / n_features.
- **coef0** [float, default=1]

**Returns**

**Gram matrix** [ndarray of shape (n_samples_X, n_samples_Y)]

**sklearn.metrics.pairwise.paired_euclidean_distances**

```python
sklearn.metrics.pairwise.paired_euclidean_distances(X, Y)
```

Computes the paired euclidean distances between X and Y.

Read more in the *User Guide*.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]
- **Y** [array-like of shape (n_samples, n_features)]

**Returns**
sklearn.metrics.pairwise.paired_manhattan_distances

**sklearn.metrics.pairwise.paired_manhattan_distances** *(X, Y)*
Compute the L1 distances between the vectors in X and Y.

**Read more in the User Guide.**

**Parameters**
- **X** [array-like of shape (n_samples, n_features)]
- **Y** [array-like of shape (n_samples, n_features)]

**Returns**
- **distances** [ndarray of shape (n_samples,)]

sklearn.metrics.pairwise.paired_cosine_distances

**sklearn.metrics.pairwise.paired_cosine_distances** *(X, Y)*
Computes the paired cosine distances between X and Y.

**Read more in the User Guide.**

**Parameters**
- **X** [array-like of shape (n_samples, n_features)]
- **Y** [array-like of shape (n_samples, n_features)]

**Returns**
- **distances** [ndarray of shape (n_samples,)]

**Notes**

The cosine distance is equivalent to the half the squared euclidean distance if each sample is normalized to unit norm.

sklearn.metrics.pairwise.paired_distances

**sklearn.metrics.pairwise.paired_distances** *(X, Y, metric='euclidean', **kwds)*
Computes the paired distances between X and Y.

Computes the distances between (X[0], Y[0]), (X[1], Y[1]), etc…

**Read more in the User Guide.**

**Parameters**
- **X** [ndarray of shape (n_samples, n_features)] Array 1 for distance computation.
- **Y** [ndarray of shape (n_samples, n_features)] Array 2 for distance computation.
- **metric** [str or callable, default="euclidean"] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options specified in PAIRED_DISTANCES, including “euclidean”, “manhattan”, or “cosine”. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting
value recorded. The callable should take two arrays from X as input and return a value indicating the distance between them.

Returns

- **distances** [ndarray of shape (n_samples,)]

See also:

- **pairwise_distances** Computes the distance between every pair of samples.

### Examples

```python
>>> from sklearn.metrics.pairwise import paired_distances
>>> X = [[0, 1], [1, 1]]
>>> Y = [[0, 1], [2, 1]]
>>> paired_distances(X, Y)
array([[0., 1.],
       [1., 1.]])
```

### sklearn.metrics.pairwise_distances

This method takes either a vector array or a distance matrix, and returns a distance matrix. If the input is a vector array, the distances are computed. If the input is a distances matrix, it is returned instead.

This method provides a safe way to take a distance matrix as input, while preserving compatibility with many other algorithms that take a vector array.

If Y is given (default is None), then the returned matrix is the pairwise distance between the arrays from both X and Y.

Valid values for metric are:

- From scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']. These metrics support sparse matrix inputs. ['nan_euclidean'] but it does not yet support sparse matrices.
- From scipy.spatial.distance: ['braycurtis', 'canberra', 'chebyshev', 'correlation', 'dice', 'hamming', 'jaccard', 'kulsinski', 'mahalanobis', 'minkowski', 'rogerstanimoto', 'russellrao', 'sokalmichener', 'sokalsneath', 'sqeuclidean', 'yule'] See the documentation for scipy.spatial.distance for details on these metrics. These metrics do not support sparse matrix inputs.

Note that in the case of 'cityblock', 'cosine' and 'euclidean' (which are valid scipy.spatial.distance metrics), the scikit-learn implementation will be used, which is faster and has support for sparse matrices (except for 'cityblock'). For a verbose description of the metrics from scikit-learn, see the __doc__ of the sklearn.pairwise.distance_metrics function.

Read more in the [User Guide](#).

### Parameters

- **X** [ndarray of shape (n_samples_X, n_samples_X) or (n_samples_X, n_features)] Array of pairwise distances between samples, or a feature array. The shape of the array should be (n_samples_X, n_samples_X) if metric == "precomputed" and (n_samples_X, n_features) otherwise.
**Y** [ndarray of shape (n\_samples\_Y, n\_features), default=None] An optional second feature array. Only allowed if metric != “precomputed”.

**metric** [str or callable, default=’euclidean’] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options allowed by scipy.spatial.distance.pdist for its metric parameter, or a metric listed in pairwise.PAIRWISE\_DISTANCE\_FUNCTIONS. If metric is “precomputed”, X is assumed to be a distance matrix. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays from X as input and return a value indicating the distance between them.

**n\_jobs** [int, default=None] The number of jobs to use for the computation. This works by breaking down the pairwise matrix into n\_jobs even slices and computing them in parallel. None means 1 unless in a joblib.parallel\_backend context. -1 means using all processors. See Glossary for more details.

**force\_all\_finite** [bool or ‘allow-nan’, default=True] Whether to raise an error on np.inf, np.nan, pd.NA in array. Ignored for a metric listed in pairwise.PAIRWISE\_DISTANCE\_FUNCTIONS. The possibilities are:

- True: Force all values of array to be finite.
- False: accepts np.inf, np.nan, pd.NA in array.
- ‘allow-nan’: accepts only np.nan and pd.NA values in array. Values cannot be infinite.

New in version 0.22: force\_all\_finite accepts the string 'allow-nan'.

Changed in version 0.23: Accepts pd.NA and converts it into np.nan.

**kwds** [optional keyword parameters] Any further parameters are passed directly to the distance function. If using a scipy.spatial.distance metric, the parameters are still metric dependent. See the scipy docs for usage examples.

**Returns**

**D** [ndarray of shape (n\_samples\_X, n\_samples\_X) or (n\_samples\_X, n\_samples\_Y)] A distance matrix D such that D\_[i, j] is the distance between the ith and jth vectors of the given matrix X, if Y is None. If Y is not None, then D\_[i, j] is the distance between the ith array from X and the jth array from Y.

See also:

* pairwise\_distances\_chunked* Performs the same calculation as this function, but returns a generator of chunks of the distance matrix, in order to limit memory usage.

* paired\_distances* Computes the distances between corresponding elements of two arrays.

**Examples using sklearn.metrics.pairwise\_distances**

- Agglomerative clustering with different metrics
scikit-learn user guide, Release 0.24.0

sklearn.metrics.pairwise_distances_argmin

Compute minimum distances between one point and a set of points.

This function computes for each row in X, the index of the row of Y which is closest (according to the specified distance).

This is mostly equivalent to calling:

```
pairwise_distances(X, Y=Y, metric=metric).argmin(axis=axis)
```

but uses much less memory, and is faster for large arrays.

This function works with dense 2D arrays only.

**Parameters**

- `X` [array-like of shape (n_samples_X, n_features)] Array containing points.
- `Y` [array-like of shape (n_samples_Y, n_features)] Arrays containing points.
- `axis` [int, default=1] Axis along which the argmin and distances are to be computed.
- `metric` [str or callable, default="euclidean"] Metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.
  
  If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string.
  
  Distance matrices are not supported.
  
  Valid values for metric are:
  
  - from scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']
  
  See the documentation for scipy.spatial.distance for details on these metrics.

- `metric_kwargs` [dict, default=None] Keyword arguments to pass to specified metric function.

**Returns**

- `argmin` [numpy.ndarray] Y[argmin[i], :] is the row in Y that is closest to X[i, :].

**See also:**

- `sklearn.metrics.pairwise_distances`
- `sklearn.metrics.pairwise_distances_argmin_min`
Examples using `sklearn.metrics.pairwise_distances_argmin`

- Color Quantization using K-Means
- Comparison of the K-Means and MiniBatchKMeans clustering algorithms

`sklearn.metrics.pairwise_distances_argmin_min`  

`sklearn.metrics.pairwise_distances_argmin_min(X, Y, *, axis=1, metric='euclidean', metric_kwargs=None)`  

Compute minimum distances between one point and a set of points.  
This function computes for each row in X, the index of the row of Y which is closest (according to the specified distance). The minimal distances are also returned.  
This is mostly equivalent to calling:  

```
(pairwise_distances(X, Y=Y, metric=metric).argmin(axis=axis), pairwise_distances(X, Y=Y, metric=metric).min(axis=axis))
```

but uses much less memory, and is faster for large arrays.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples_X, n_features)) Array containing points.
- **Y** ([array-like, sparse matrix] of shape (n_samples_Y, n_features)) Array containing points.
- **axis** ([int, default=1]) Axis along which the argmin and distances are to be computed.
- **metric** [str or callable, default='euclidean'] Metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.  
  If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string.  
  Distance matrices are not supported.  
  Valid values for metric are:  
  - from scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']  
  See the documentation for scipy.spatial.distance for details on these metrics.
- **metric_kwargs** [dict, default=None] Keyword arguments to pass to specified metric function.

**Returns**

- **argmin** [ndarray] Y[argmin[i], :] is the row in Y that is closest to X[i, :].
- **distances** [ndarray] distances[i] is the distance between the i-th row in X and the argmin[i]-th row in Y.

**See also:**

- `sklearn.metrics.pairwise_distances`
- `sklearn.metrics.pairwise_distances_argmin`
sklearn.metrics.pairwise_distances_chunked

sklearn.metrics.pairwise_distances_chunked(X, Y=None, *, reduce_func=None, metric='euclidean', n_jobs=None, working_memory=None, **kwds)

Generate a distance matrix chunk by chunk with optional reduction.

In cases where not all of a pairwise distance matrix needs to be stored at once, this is used to calculate pairwise distances in working_memory-sized chunks. If reduce_func is given, it is run on each chunk and its return values are concatenated into lists, arrays or sparse matrices.

Parameters

X [ndarray of shape (n_samples_X, n_samples_X) or (n_samples_X, n_features)] Array of pairwise distances between samples, or a feature array. The shape the array should be (n_samples_X, n_samples_X) if metric='precomputed' and (n_samples_X, n_features) otherwise.

Y [ndarray of shape (n_samples_Y, n_features), default=None] An optional second feature array. Only allowed if metric != "precomputed".

reduce_func [callable, default=None] The function which is applied on each chunk of the distance matrix, reducing it to needed values. reduce_func(D_chunk, start) is called repeatedly, where D_chunk is a contiguous vertical slice of the pairwise distance matrix, starting at row start. It should return one of: None; an array, a list, or a sparse matrix of length D_chunk.shape[0]; or a tuple of such objects. Returning None is useful for in-place operations, rather than reductions.

If None, pairwise_distances_chunked returns a generator of vertical chunks of the distance matrix.

metric [str or callable, default='euclidean'] The metric to use when calculating distance between instances in a feature array. If metric is a string, it must be one of the options allowed by scipy.spatial.distance.pdist for its metric parameter, or a metric listed in pairwise.PAIRWISE_DISTANCE_FUNCTIONS. If metric is “precomputed”, X is assumed to be a distance matrix. Alternatively, if metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays from X as input and return a value indicating the distance between them.

n_jobs [int, default=None] The number of jobs to use for the computation. This works by breaking down the pairwise matrix into n_jobs even slices and computing them in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

working_memory [int, default=None] The sought maximum memory for temporary distance matrix chunks. When None (default), the value of sklearn.get_config()['working_memory'] is used.

**kwds [optional keyword parameters] Any further parameters are passed directly to the distance function. If using a scipy.spatial.distance metric, the parameters are still metric dependent. See the scipy docs for usage examples.

Yields

D_chunk [[ndarray, sparse matrix]] A contiguous slice of distance matrix, optionally processed by reduce_func.
Examples

Without reduce_func:

```python
>>> import numpy as np
>>> from sklearn.metrics import pairwise_distances_chunked
>>> X = np.random.RandomState(0).rand(5, 3)
>>> D_chunk = next(pairwise_distances_chunked(X))
>>> D_chunk
array([[0. ..., 0.29..., 0.41..., 0.19..., 0.57...],
       [0.29..., 0. ..., 0.57..., 0.41..., 0.76...],
       [0.41..., 0.57..., 0. ..., 0.44..., 0.90...],
       [0.19..., 0.41..., 0.44..., 0. ..., 0.51...],
       [0.57..., 0.76..., 0.90..., 0.51..., 0. ...]])
```

Retrieve all neighbors and average distance within radius r:

```python
>>> r = .2
>>> def reduce_func(D_chunk, start):
...     neigh = [np.flatnonzero(d < r) for d in D_chunk]
...     avg_dist = (D_chunk * (D_chunk < r)).mean(axis=1)
...     return neigh, avg_dist
>>> gen = pairwise_distances_chunked(X, reduce_func=reduce_func)
>>> neigh, avg_dist = next(gen)
>>> neigh
[array([0, 3]), array([1]), array([2]), array([0, 3]), array([4])]
>>> avg_dist
array([0.039..., 0. , 0. , 0.039..., 0. ])
```

Where r is defined per sample, we need to make use of start:

```python
>>> r = [.2, .4, .4, .3, .1]
>>> def reduce_func(D_chunk, start):
...     neigh = [np.flatnonzero(d < r[i])
...              for i, d in enumerate(D_chunk, start)]
...     return neigh
>>> neigh = next(pairwise_distances_chunked(X, reduce_func=reduce_func))
>>> neigh
[array([0, 3]), array([0, 1]), array([2]), array([0, 3]), array([4])]
```

Force row-by-row generation by reducing working_memory:

```python
>>> gen = pairwise_distances_chunked(X, reduce_func=reduce_func,
...                                   working_memory=0)
>>> next(gen)
[array([0, 3])]
>>> next(gen)
[array([0, 1])]
```
### 7.24.8 Plotting

See the [Visualizations](#) section of the user guide for further details.

- `metrics.plot_confusion_matrix(estimator, X, y, ...)` Plot Confusion Matrix.
- `metrics.plot_det_curve(estimator, X, y, ...)` Plot detection error tradeoff (DET) curve.
- `metrics.plot_precision_recall_curve(...)` Plot Precision Recall Curve for binary classifiers.
- `metrics.plot_roc_curve(estimator, X, y, ...)` Plot Receiver operating characteristic (ROC) curve.

### sklearn.metrics.plot_confusion_matrix

#### sklearn.metrics.plot_confusion_matrix(estimator, X, y_true, *, labels=None, sample_weight=None, normalize=None, display_labels=None, include_values=True, xticks_rotation='horizontal', values_format=None, cmap='viridis', ax=None, colorbar=True)

Plot Confusion Matrix.

Read more in the [User Guide](#).

**Parameters**

- **estimator** [estimator instance] Fitted classifier or a fitted `Pipeline` in which the last estimator is a classifier.
- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] Input values.
- **y_true** [array-like of shape (n_samples,)] Target values.
- **labels** [array-like of shape (n_classes,), default=None] List of labels to index the matrix. This may be used to reorder or select a subset of labels. If None is given, those that appear at least once in y_true or y_pred are used in sorted order.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.
- **normalize** [{‘true’, ‘pred’, ‘all’}, default=None] Normalizes confusion matrix over the true (rows), predicted (columns) conditions or all the population. If None, confusion matrix will not be normalized.
- **display_labels** [array-like of shape (n_classes,), default=None] Target names used for plotting. By default, labels will be used if it is defined, otherwise the unique labels of y_true and y_pred will be used.
- **include_values** [bool, default=True] Includes values in confusion matrix.
- **xticks_rotation** [{‘vertical’, ‘horizontal’} or float, default=’horizontal’] Rotation of xtick labels.
- **values_format** [str, default=None] Format specification for values in confusion matrix. If None, the format specification is ‘d’ or ‘.2g’ whichever is shorter.
- **cmap** [str or matplotlib Colormap, default=’viridis’] Colormap recognized by matplotlib.
- **ax** [matplotlib Axes, default=None] Axes object to plot on. If None, a new figure and axes is created.
colorbar [bool, default=True] Whether or not to add a colorbar to the plot.

New in version 0.24.

Returns

display [ConfusionMatrixDisplay]

See also:

confusion_matrix Compute Confusion Matrix to evaluate the accuracy of a classification.

ConfusionMatrixDisplay Confusion Matrix visualization.

Examples

```python
>>> import matplotlib.pyplot as plt
>>> from sklearn.datasets import make_classification
>>> from sklearn.metrics import plot_confusion_matrix
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.svm import SVC

>>> X, y = make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = train_test_split(...
...   X, y, random_state=0)
>>> clf = SVC(random_state=0)
>>> clf.fit(X_train, y_train)
>>> plot_confusion_matrix(clf, X_test, y_test)
>>> plt.show()
```

Examples using sklearn.metrics.plot_confusion_matrix

- Recognizing hand-written digits
- Confusion matrix

sklearn.metrics.plot_det_curve

sklearn.metrics.plot_det_curve(estimator, X, y, *, sample_weight=None, response_method='auto', name=None, ax=None, pos_label=None, **kwargs)

Plot detection error tradeoff (DET) curve.

Extra keyword arguments will be passed to matplotlib’s plot.

Read more in the User Guide.

New in version 0.24.

Parameters

- estimator [estimator instance] Fitted classifier or a fitted Pipeline in which the last estimator is a classifier.
- X [{array-like, sparse matrix} of shape (n_samples, n_features)] Input values.
- y [array-like of shape (n_samples,)] Target values.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.
response_method [{‘predict_proba’, ‘decision_function’, ‘auto’} default=’auto’] Specifies whether to use predict_proba or decision_function as the predicted target response. If set to ‘auto’, predict_proba is tried first and if it does not exist decision_function is tried next.

name [str, default=None] Name of DET curve for labeling. If None, use the name of the estimator.

ax [matplotlib axes, default=None] Axes object to plot on. If None, a new figure and axes is created.

pos_label [str or int, default=None] The label of the positive class. When pos_label=None, if y_true is in {-1, 1} or {0, 1}, pos_label is set to 1, otherwise an error will be raised.

Returns
display [DetCurveDisplay] Object that stores computed values.

See also:
det_curve Compute error rates for different probability thresholds.
DetCurveDisplay DET curve visualization.
plot_roc_curve Plot Receiver operating characteristic (ROC) curve.

Examples

```python
>>> import matplotlib.pyplot as plt
>>> from sklearn import datasets, metrics, model_selection, svm
>>> X, y = datasets.make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = model_selection.train_test_split(...
... X, y, random_state=0)
>>> clf = svm.SVC(random_state=0)
>>> clf.fit(X_train, y_train)
SVC(random_state=0)
>>> metrics.plot_det_curve(clf, X_test, y_test)
>>> plt.show()
```

Examples using sklearn.metrics.plot_det_curve

- Detection error tradeoff (DET) curve

sklearn.metrics.plot_precision_recall_curve

sklearn.metrics.plot_precision_recall_curve (estimator, X, y, *, sample_weight=None, response_method=’auto’, name=None, ax=None, pos_label=None, **kwargs)

Plot Precision Recall Curve for binary classifiers.
Extra keyword arguments will be passed to matplotlib’s plot.
Read more in the User Guide.

Parameters

- estimator [estimator instance] Fitted classifier or a fitted Pipeline in which the last estimator is a classifier.
X  [array-like, sparse matrix] of shape (n_samples, n_features) Input values.
y  [array-like of shape (n_samples,)] Binary target values.
sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.
response_method  [{'predict_proba', 'decision_function', 'auto'}, default='auto'] Specifies whether to use predict_proba or decision_function as the target response. If set to 'auto', predict_proba is tried first and if it does not exist decision_function is tried next.
name  [str, default=None] Name for labeling curve. If None, the name of the estimator is used.
ax  [matplotlib axes, default=None] Axes object to plot on. If None, a new figure and axes is created.
pos_label  [str or int, default=None] The class considered as the positive class when computing the precision and recall metrics. By default, estimators.classes_[1] is considered as the positive class.

New in version 0.24.
**kwargs  [dict] Keyword arguments to be passed to matplotlib’s plot.

Returns

display  [PrecisionRecallDisplay] Object that stores computed values.

See also:

precision_recall_curve  Compute precision-recall pairs for different probability thresholds.
PrecisionRecallDisplay  Precision Recall visualization.

Examples using sklearn.metrics.plot_precision_recall_curve

- Precision-Recall

sklearn.metrics.plot_precision_recall_curve

sklearn.metrics.plot_precision_recall_curve(estimator,  X,  y,  *,  sample_weight=None,  drop_intermediate=True,  response_method='auto',  name=None,  ax=None,  pos_label=None,  **kwargs)

Plot Receiver operating characteristic (ROC) curve.

Extra keyword arguments will be passed to matplotlib’s plot.

Read more in the User Guide.

Parameters

estimator  [estimator instance] Fitted classifier or a fitted Pipeline in which the last estimator is a classifier.
X  [array-like, sparse matrix] of shape (n_samples, n_features) Input values.
y  [array-like of shape (n_samples,)] Target values.
sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.
drop_intermediate  [boolean, default=True] Whether to drop some suboptimal thresholds which would not appear on a plotted ROC curve. This is useful in order to create lighter ROC curves.
response_method

Parameters:

- `response_method`: ['predict_proba', 'decision_function', 'auto'] default='auto'
  Specifies whether to use `predict_proba` or `decision_function` as the target response. If set to 'auto', `predict_proba` is tried first and if it does not exist `decision_function` is tried next.

- `name`: [str, default=None]
  Name of ROC Curve for labeling. If None, use the name of the estimator.

- `ax`: [matplotlib axes, default=None]
  Axes object to plot on. If None, a new figure and axes is created.

- `pos_label`: [str or int, default=None]
  The class considered as the positive class when computing the roc auc metrics. By default, `estimators.classes_[1]` is considered as the positive class.

New in version 0.24.

Returns:

- `display` [RocCurveDisplay]
  Object that stores computed values.

See also:

- `roc_curve`
  Compute Receiver operating characteristic (ROC) curve.

- `RocCurveDisplay`
  ROC Curve visualization.

- `roc_auc_score`
  Compute the area under the ROC curve.

Examples

```python
>>> import matplotlib.pyplot as plt
>>> from sklearn import datasets, metrics, model_selection, svm
>>> X, y = datasets.make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = model_selection.train_test_split(...
>>>      X, y, random_state=0)
>>> clf = svm.SVC(random_state=0)
>>> clf.fit(X_train, y_train)
SVC(random_state=0)
>>> metrics.plot_roc_curve(clf, X_test, y_test)
>>> plt.show()
```

Examples using `sklearn.metrics.plot_roc_curve`

- Release Highlights for scikit-learn 0.22
- ROC Curve with Visualization API
- Detection error tradeoff (DET) curve
- Receiver Operating Characteristic (ROC) with cross validation

```
metrics.ConfusionMatrixDisplay(...[, ...
metrics.DetCurveDisplay(*, fpr, fnr[, ...])
metrics.PrecisionRecallDisplay(precision, ...
metrics.RocCurveDisplay(*, fpr, tpr[, ...])
```

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sklearn.metrics.ConfusionMatrixDisplay

class sklearn.metrics.ConfusionMatrixDisplay(  
    confusion_matrix, *, display_labels=None
)

Confusion Matrix visualization.

It is recommended to use `plot_confusion_matrix` to create a `ConfusionMatrixDisplay`. All parameters are stored as attributes.

Read more in the `User Guide`.

Parameters

confusion_matrix [ndarray of shape (n_classes, n_classes)] Confusion matrix.
display_labels [ndarray of shape (n_classes,), default=None] Display labels for plot. If None, display labels are set from 0 to n_classes - 1.

Attributes

im_ [matplotlib AxesImage] Image representing the confusion matrix.
text_ [ndarray of shape (n_classes, n_classes), dtype=matplotlib Text, or None] Array of matplotlib axes. None if `include_values` is false.
ax_ [matplotlib Axes] Axes with confusion matrix.
figure_ [matplotlib Figure] Figure containing the confusion matrix.

See also:

confusion_matrix Compute Confusion Matrix to evaluate the accuracy of a classification.

plot_confusion_matrix Plot Confusion Matrix.

Examples

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.svm import SVC

>>> X, y = make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, ...
...     random_state=0)

>>> clf = SVC(random_state=0)
>>> clf.fit(X_train, y_train)

SVC(random_state=0)

>>> predictions = clf.predict(X_test)

>>> cm = confusion_matrix(y_test, predictions, labels=clf.classes_)

>>> disp = ConfusionMatrixDisplay(confusion_matrix=cm, ...
...     display_labels=clf.classes_)

>>> disp.plot()
```
Methods

```
plot(*[, include_values, cmap, . . . ])  # Plot visualization.

plot(*, include_values=True, cmap='viridis', xticks_rotation='horizontal', values_format=None, ax=None, colorbar=True)  # Plot visualization.
```

**Parameters**

- `include_values` [bool, default=True] Includes values in confusion matrix.
- `cmap` [str or matplotlib Colormap, default='viridis'] Colormap recognized by matplotlib.
- `xticks_rotation` [{'vertical', 'horizontal'} or float, default='horizontal'] Rotation of xtick labels.
- `values_format` [str, default=None] Format specification for values in confusion matrix. If None, the format specification is ‘d’ or ‘.2g’ whichever is shorter.
- `ax` [matplotlib axes, default=None] Axes object to plot on. If None, a new figure and axes is created.
- `colorbar` [bool, default=True] Whether or not to add a colorbar to the plot.

**Returns**

- `display` [ConfusionMatrixDisplay]

**Examples using sklearn.metrics.ConfusionMatrixDisplay**

- Visualizations with Display Objects

**sklearn.metrics.DetCurveDisplay**

```
class sklearn.metrics.DetCurveDisplay (*, fpr, fnr, estimator_name=None, pos_label=None)  # DET curve visualization.
```

It is recommend to use `plot_det_curve` to create a visualizer. All parameters are stored as attributes.

Read more in the User Guide.

New in version 0.24.

**Parameters**

- `fpr` [ndarray] False positive rate.
- `tpr` [ndarray] True positive rate.
- `estimator_name` [str, default=None] Name of estimator. If None, the estimator name is not shown.
- `pos_label` [str or int, default=None] The label of the positive class.

**Attributes**

- `line_` [matplotlib Artist] DET Curve.
- `ax_` [matplotlib Axes] Axes with DET Curve.
- `figure_` [matplotlib Figure] Figure containing the curve.
See also:

**det_curve** Compute error rates for different probability thresholds.

**plot_det_curve** Plot detection error tradeoff (DET) curve.

**Examples**

```python
>>> import matplotlib.pyplot as plt
>>> import numpy as np
>>> from sklearn import metrics

>>> y = np.array([0, 0, 1, 1])
>>> pred = np.array([0.1, 0.4, 0.35, 0.8])
>>> fpr, fnr, thresholds = metrics.det_curve(y, pred)
>>> display = metrics.DetCurveDisplay(fpr=fpr, fnr=fnr, estimator_name='example estimator')
>>> display.plot()
>>> plt.show()
```

**Methods**

- **plot** *(ax, name)*

  Plot visualization.

```python
plot(ax=None, *, name=None, **kwargs)
```

  Plot visualization.

  **Parameters**

  - **ax** [matplotlib axes, default=None] Axes object to plot on. If None, a new figure and axes is created.

  - **name** [str, default=None] Name of DET curve for labeling. If None, use the name of the estimator.

  **Returns**

  - **display** [DetCurveDisplay] Object that stores computed values.

**sklearn.metrics.PrecisionRecallDisplay**

```python
class sklearn.metrics.PrecisionRecallDisplay(precision, recall, *, average_precision=None, estimator_name=None, pos_label=None)
```

Precision Recall visualization.

It is recommend to use **plot_precision_recall_curve** to create a visualizer. All parameters are stored as attributes.

Read more in the *User Guide*.

**Parameters**

- **precision** [ndarray] Precision values.

- **recall** [ndarray] Recall values.
average_precision [float, default=None] Average precision. If None, the average precision is not shown.

estimator_name [str, default=None] Name of estimator. If None, then the estimator name is not shown.

pos_label [str or int, default=None] The class considered as the positive class. If None, the class will not be shown in the legend.

New in version 0.24.

Attributes

- line_ [matplotlib Artist] Precision recall curve.
- ax_ [matplotlib Axes] Axes with precision recall curve.
- figure_ [matplotlib Figure] Figure containing the curve.

See also:

- precision_recall_curve Compute precision-recall pairs for different probability thresholds.
- plot_precision_recall_curve Plot Precision Recall Curve for binary classifiers.

Examples

```python
>>> from sklearn.datasets import make_classification
>>> from sklearn.metrics import (precision_recall_curve, ...
... PrecisionRecallDisplay)
>>> from sklearn.model_selection import train_test_split
>>> from sklearn import svm
>>> X, y = make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y,
... random_state=0)
>>> clf = svm.SVC(random_state=0)
>>> clf.fit(X_train, y_train)
SVC(random_state=0)
>>> predictions = clf.predict(X_test)
>>> precision, recall, _ = precision_recall_curve(y_test, predictions)
>>> disp = PrecisionRecallDisplay(precision=precision, recall=recall)
>>> disp.plot()
```

Methods

- plot([ax, name]) Plot visualization.

```python
plot (ax=None, *, name=None, **kwargs)
```

Plot visualization.

Extra keyword arguments will be passed to matplotlib's plot.

Parameters

- ax [Matplotlib Axes, default=None] Axes object to plot on. If None, a new figure and axes is created.

- name [str, default=None] Name of precision recall curve for labeling. If None, use the
name of the estimator.

**kwargs [dict] Keyword arguments to be passed to matplotlib’s plot.

Returns

display [PrecisionRecallDisplay] Object that stores computed values.

Examples using sklearn.metrics.PrecisionRecallDisplay

- Visualizations with Display Objects

sklearn.metrics.RocCurveDisplay

**class** sklearn.metrics.RocCurveDisplay(*, fpr, tpr, roc_auc=None, estimator_name=None, pos_label=None)

ROC Curve visualization.

It is recommend to use plot_roc_curve to create a visualizer. All parameters are stored as attributes.

Read more in the User Guide.

Parameters

- **fpr** [ndarray] False positive rate.
- **tpr** [ndarray] True positive rate.
- **roc_auc** [float, default=None] Area under ROC curve. If None, the roc_auc score is not shown.
- **estimator_name** [str, default=None] Name of estimator. If None, the estimator name is not shown.
- **pos_label** [str or int, default=None] The class considered as the positive class when computing the roc auc metrics. By default, estimators.classes_[1] is considered as the positive class.

    New in version 0.24.

Attributes

- **line_** [matplotlib Artist] ROC Curve.
- **ax_** [matplotlib Axes] Axes with ROC Curve.
- **figure_** [matplotlib Figure] Figure containing the curve.

See also:

- **roc_curve** Compute Receiver operating characteristic (ROC) curve.
- **plot_roc_curve** Plot Receiver operating characteristic (ROC) curve.
- **roc_auc_score** Compute the area under the ROC curve.
Examples

```python
>>> import matplotlib.pyplot as plt
>>> import numpy as np
>>> from sklearn import metrics

>>> y = np.array([0, 0, 1, 1])
>>> pred = np.array([0.1, 0.4, 0.35, 0.8])

>>> fpr, tpr, thresholds = metrics.roc_curve(y, pred)
>>> roc_auc = metrics.auc(fpr, tpr)

>>> display = metrics.RocCurveDisplay(fpr=fpr, tpr=tpr, roc_auc=roc_auc,
                                          estimator_name='example estimator')

>>> display.plot()
>>> plt.show()
```

Methods

```python
plot([ax, name]) Plot visualization
```

`plot (ax=None, *, name=None, **kwargs)` Plot visualization

Extra keyword arguments will be passed to matplotlib’s `plot`.

Parameters

- `ax` [matplotlib axes, default=None] Axes object to plot on. If `None`, a new figure and axes is created.
- `name` [str, default=None] Name of ROC Curve for labeling. If `None`, use the name of the estimator.

Returns

- `display` [RocCurveDisplay] Object that stores computed values.

Examples using `sklearn.metrics.RocCurveDisplay`

- Visualizations with Display Objects

7.25 sklearn.mixture: Gaussian Mixture Models

The `sklearn.mixture` module implements mixture modeling algorithms.

User guide: See the Gaussian mixture models section for further details.

- `mixture.BayesianGaussianMixture(*[, ...])` Variational Bayesian estimation of a Gaussian mixture.
- `mixture.GaussianMixture([n_components, ...])` Gaussian Mixture.
7.25.1 sklearn.mixture.BayesianGaussianMixture

class sklearn.mixture.BayesianGaussianMixture(*, n_components=1, covariance_type='full', tol=0.001, reg_covar=1e-6, max_iter=100, n_init=1, init_params='kmeans', weight_concentration_prior_type='dirichlet_process', weight_concentration_prior=None, mean_precision_prior=None, mean_prior=None, degrees_of_freedom_prior=None, covariance_prior=None, random_state=None, warm_start=False, verbose=0, verbose_interval=10)

Variational Bayesian estimation of a Gaussian mixture.

This class allows to infer an approximate posterior distribution over the parameters of a Gaussian mixture distribution. The effective number of components can be inferred from the data.

This class implements two types of prior for the weights distribution: a finite mixture model with Dirichlet distribution and an infinite mixture model with the Dirichlet Process. In practice Dirichlet Process inference algorithm is approximated and uses a truncated distribution with a fixed maximum number of components (called the Stick-breaking representation). The number of components actually used almost always depends on the data.

New in version 0.18.

Read more in the User Guide.

Parameters

- **n_components** [int, default=1] The number of mixture components. Depending on the data and the value of the weight_concentration_prior the model can decide to not use all the components by setting some component weights to values very close to zero. The number of effective components is therefore smaller than n_components.

- **covariance_type** ['full', 'tied', 'diag', 'spherical', default='full'] String describing the type of covariance parameters to use. Must be one of:

  - 'full' (each component has its own general covariance matrix),
  - 'tied' (all components share the same general covariance matrix),
  - 'diag' (each component has its own diagonal covariance matrix),
  - 'spherical' (each component has its own single variance).

- **tol** [float, default=1e-3] The convergence threshold. EM iterations will stop when the lower bound average gain on the likelihood (of the training data with respect to the model) is below this threshold.

- **reg_covar** [float, default=1e-6] Non-negative regularization added to the diagonal of covariance. Allows to assure that the covariance matrices are all positive.

- **max_iter** [int, default=100] The number of EM iterations to perform.

- **n_init** [int, default=1] The number of initializations to perform. The result with the highest lower bound value on the likelihood is kept.

- **init_params** ['kmeans', 'random', default='kmeans'] The method used to initialize the weights, the means and the covariances. Must be one of:
'kmeans' : responsibilities are initialized using kmeans.
'random' : responsibilities are initialized randomly.

**weight_concentration_prior_type** [str, default='dirichlet_process'] String describing the type of the weight concentration prior. Must be one of:

- 'dirichlet_process' (using the Stick-breaking representation),
- 'dirichlet_distribution' (can favor more uniform weights).

**weight_concentration_prior** [float | None, default=None.] The dirichlet concentration of each component on the weight distribution (Dirichlet). This is commonly called gamma in the literature. The higher concentration puts more mass in the center and will lead to more components being active, while a lower concentration parameter will lead to more mass at the edge of the mixture weights simplex. The value of the parameter must be greater than 0. If it is None, it’s set to 1. / n_components.

**mean_precision_prior** [float | None, default=None.] The precision prior on the mean distribution (Gaussian). Controls the extent of where means can be placed. Larger values concentrate the cluster means around mean_prior. The value of the parameter must be greater than 0. If it is None, it is set to 1.

**mean_prior** [array-like, shape (n_features,), default=None.] The prior on the mean distribution (Gaussian). If it is None, it is set to the mean of X.

**degrees_of_freedom_prior** [float | None, default=None] The prior of the number of degrees of freedom on the covariance distributions (Wishart). If it is None, it’s set to n_features.

**covariance_prior** [float or array-like, default=None.] The prior on the covariance distribution (Wishart). If it is None, the empirical covariance prior is initialized using the covariance of X. The shape depends on covariance_type:

- (n_features, n_features) if 'full',
- (n_features, n_features) if 'tied',
- (n_features) if 'diag',
- float if 'spherical'

**random_state** [int, RandomState instance or None, default=None] Controls the random seed given to the method chosen to initialize the parameters (see init_params). In addition, it controls the generation of random samples from the fitted distribution (see the method sample). Pass an int for reproducible output across multiple function calls. See Glossary.

**warm_start** [bool, default=False] If ‘warm_start’ is True, the solution of the last fitting is used as initialization for the next call of fit(). This can speed up convergence when fit is called several times on similar problems. See the Glossary.

**verbose** [int, default=0] Enable verbose output. If 1 then it prints the current initialization and each iteration step. If greater than 1 then it prints also the log probability and the time needed for each step.

**verbose_interval** [int, default=10] Number of iteration done before the next print.

**Attributes**

- **weights_** [array-like of shape (n_components,)] The weights of each mixture components.
- **means_** [array-like of shape (n_components, n_features)] The mean of each mixture component.
- **covariances_** [array-like] The covariance of each mixture component. The shape depends on covariance_type:
**precisions_** [array-like] The precision matrices for each component in the mixture. A precision matrix is the inverse of a covariance matrix. A covariance matrix is symmetric positive definite so the mixture of Gaussian can be equivalently parameterized by the precision matrices. Storing the precision matrices instead of the covariance matrices makes it more efficient to compute the log-likelihood of new samples at test time. The shape depends on `covariance_type`:

```
(n_components,) if 'spherical',
(n_features, n_features) if 'tied',
(n_components, n_features) if 'diag',
(n_components, n_features, n_features) if 'full'
```

**precisions_chol** [array-like] The cholesky decomposition of the precision matrices of each mixture component. A precision matrix is the inverse of a covariance matrix. A covariance matrix is symmetric positive definite so the mixture of Gaussian can be equivalently parameterized by the precision matrices. Storing the precision matrices instead of the covariance matrices makes it more efficient to compute the log-likelihood of new samples at test time. The shape depends on `covariance_type`:

```
(n_components,) if 'spherical',
(n_features, n_features) if 'tied',
(n_components, n_features) if 'diag',
(n_components, n_features, n_features) if 'full'
```

**converged_** [bool] True when convergence was reached in `fit()`, False otherwise.

**n_iter_** [int] Number of step used by the best fit of inference to reach the convergence.

**lower_bound_** [float] Lower bound value on the likelihood (of the training data with respect to the model) of the best fit of inference.

**weight_concentration_prior_** [tuple or float] The dirichlet concentration of each component on the weight distribution (Dirichlet). The type depends on `weight_concentration_prior_type`:

```
(float, float) if 'dirichlet_process' (Beta parameters),
float      if 'dirichlet_distribution' (Dirichlet parameters).
```

The higher concentration puts more mass in the center and will lead to more components being active, while a lower concentration parameter will lead to more mass at the edge of the simplex.

**weight_concentration_** [array-like of shape (n_components,)] The dirichlet concentration of each component on the weight distribution (Dirichlet).

**mean_precision_prior_** [float] The precision prior on the mean distribution (Gaussian). Controls the extent of where means can be placed. Larger values concentrate the cluster means around `mean_prior`. If `mean_precision_prior` is set to None, `mean_precision_prior_` is set to 1.

**mean_precision_** [array-like of shape (n_components,)] The precision of each components on the mean distribution (Gaussian).

**mean_prior_** [array-like of shape (n_features,)] The prior on the mean distribution (Gaussian).
degrees_of_freedom_prior_ [float] The prior of the number of degrees of freedom on the covariance distributions (Wishart).

degrees_of_freedom_ [array-like of shape (n_components,)] The number of degrees of freedom of each components in the model.

covariance_prior_ [float or array-like] The prior on the covariance distribution (Wishart). The shape depends on covariance_type:

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<tr>
<td>(n_features, n_features)</td>
<td>'full',</td>
</tr>
<tr>
<td>(n_features, n_features)</td>
<td>'tied',</td>
</tr>
<tr>
<td>(n_features)</td>
<td>'diag',</td>
</tr>
<tr>
<td>float</td>
<td>'spherical'</td>
</tr>
</tbody>
</table>

See also:

**GaussianMixture** Finite Gaussian mixture fit with EM.

References

[1], [2], [3]

Examples

```python
>>> import numpy as np
>>> from sklearn.mixture import BayesianGaussianMixture
>>> X = np.array([[1, 2], [1, 4], [1, 0], [4, 2], [12, 4], [10, 7]])
>>> bgm = BayesianGaussianMixture(n_components=2, random_state=42).fit(X)
>>> bgm.means_
array([[2.49... , 2.29...],
       [8.45..., 4.52... ]])
>>> bgm.predict([[0, 0], [9, 3]])
array([0, 1])
```

Methods

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<th>Description</th>
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<td>Estimate model parameters with the EM algorithm.</td>
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<td>fit_predict(X[, y])</td>
<td>Estimate model parameters using X and predict the labels for X.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict the labels for the data samples in X using trained model.</td>
</tr>
<tr>
<td>predict_proba(X)</td>
<td>Predict posterior probability of each component given the data.</td>
</tr>
<tr>
<td>sample([n_samples])</td>
<td>Generate random samples from the fitted Gaussian distribution.</td>
</tr>
<tr>
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<td>Compute the per-sample average log-likelihood of the given data X.</td>
</tr>
<tr>
<td>score_samples(X)</td>
<td>Compute the weighted log probabilities for each sample.</td>
</tr>
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<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
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</table>
**fit** (*X, y=None*)
Estimate model parameters with the EM algorithm.

The method fits the model n_init times and sets the parameters with which the model has the largest likelihood or lower bound. Within each trial, the method iterates between E-step and M-step for max_iter times until the change of likelihood or lower bound is less than tol, otherwise, a ConvergenceWarning is raised. If warm_start is True, then n_init is ignored and a single initialization is performed upon the first call. Upon consecutive calls, training starts where it left off.

**Parameters**

*X*  [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

self

**fit_predict** (*X, y=None*)
Estimate model parameters using X and predict the labels for X.

The method fits the model n_init times and sets the parameters with which the model has the largest likelihood or lower bound. Within each trial, the method iterates between E-step and M-step for max_iter times until the change of likelihood or lower bound is less than tol, otherwise, a ConvergenceWarning is raised. After fitting, it predicts the most probable label for the input data points.

New in version 0.20.

**Parameters**

*X*  [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*labels*  [array, shape (n_samples,)] Component labels.

**get_params** (*deep=True*)
Get parameters for this estimator.

**Parameters**

*deep*  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

*params*  [dict] Parameter names mapped to their values.

**predict** (*X*)
Predict the labels for the data samples in X using trained model.

**Parameters**

*X*  [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*labels*  [array, shape (n_samples,)] Component labels.

**predict_proba** (*X*)
Predict posterior probability of each component given the data.

**Parameters**
X [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

Returns

resp [array, shape (n_samples, n_components)] Returns the probability each Gaussian (state) in the model given each sample.

sample (n_samples=1)
Generate random samples from the fitted Gaussian distribution.

Parameters

n_samples [int, default=1] Number of samples to generate.

Returns

X [array, shape (n_samples, n_features)] Randomly generated sample
y [array, shape (n_samples,)] Component labels

score (X, y=None)
Compute the per-sample average log-likelihood of the given data X.

Parameters

X [array-like of shape (n_samples, n_dimensions)] List of n_features-dimensional data points. Each row corresponds to a single data point.

Returns

log_likelihood [float] Log likelihood of the Gaussian mixture given X.

score_samples (X)
Compute the weighted log probabilities for each sample.

Parameters

X [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

Returns

log_prob [array, shape (n_samples,)] Log probabilities of each data point in X.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.
Examples using `sklearn.mixture.BayesianGaussianMixture`

- Gaussian Mixture Model Ellipsoids
- Gaussian Mixture Model Sine Curve
- Concentration Prior Type Analysis of Variation Bayesian Gaussian Mixture

7.25.2 `sklearn.mixture.GaussianMixture`

class `sklearn.mixture.GaussianMixture`(n_components=1, *, covariance_type='full', tol=0.001, reg_covar=1e-06, max_iter=100, n_init=1, init_params='kmeans', weights_init=None, means_init=None, precisions_init=None, random_state=None, warm_start=False, verbose=0, verbose_interval=10)

Gaussian Mixture.

Representation of a Gaussian mixture model probability distribution. This class allows to estimate the parameters of a Gaussian mixture distribution.

Read more in the User Guide.

New in version 0.18.

Parameters

- **n_components** [int, default=1] The number of mixture components.
- **covariance_type** [set of ‘full’, ‘tied’, ‘diag’, ‘spherical’, default=’full’] String describing the type of covariance parameters to use. Must be one of:
  - ‘full’ each component has its own general covariance matrix
  - ‘tied’ all components share the same general covariance matrix
  - ‘diag’ each component has its own diagonal covariance matrix
  - ‘spherical’ each component has its own single variance
- **tol** [float, default=1e-3] The convergence threshold. EM iterations will stop when the lower bound average gain is below this threshold.
- **reg_covar** [float, default=1e-6] Non-negative regularization added to the diagonal of covariance. Allows to assure that the covariance matrices are all positive.
- **max_iter** [int, default=100] The number of EM iterations to perform.
- **n_init** [int, default=1] The number of initializations to perform. The best results are kept.
- **init_params** [set of ‘kmeans’, ‘random’, default=’kmeans’] The method used to initialize the weights, the means and the precisions. Must be one of:

  `'kmeans'` : responsibilities are initialized using kmeans.
  `'random'` : responsibilities are initialized randomly.

- **weights_init** [array-like of shape (n_components, ), default=None] The user-provided initial weights. If it is None, weights are initialized using the init_params method.
- **means_init** [array-like of shape (n_components, n_features), default=None] The user-provided initial means, If it is None, means are initialized using the init_params method.
precisions_init  [array-like, default=None]  The user-provided initial precisions (inverse of the covariance matrices). If it is None, precisions are initialized using the 'init_params' method. The shape depends on 'covariance_type':

<table>
<thead>
<tr>
<th>Shape</th>
<th>Covariance Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>(n_components,)</td>
<td>'spherical',</td>
</tr>
<tr>
<td>(n_features, n_features)</td>
<td>'tied',</td>
</tr>
<tr>
<td>(n_components, n_features)</td>
<td>'diag',</td>
</tr>
<tr>
<td>(n_components, n_features, n_features)</td>
<td>'full'</td>
</tr>
</tbody>
</table>

random_state  [int, RandomState instance or None, default=None]  Controls the random seed given to the method chosen to initialize the parameters (see init_params). In addition, it controls the generation of random samples from the fitted distribution (see the method sample). Pass an int for reproducible output across multiple function calls. See Glossary.

warm_start  [bool, default=False]  If 'warm_start' is True, the solution of the last fitting is used as initialization for the next call of fit(). This can speed up convergence when fit is called several times on similar problems. In that case, 'n_init' is ignored and only a single initialization occurs upon the first call. See the Glossary.

verbose  [int, default=0]  Enable verbose output. If 1 then it prints the current initialization and each iteration step. If greater than 1 then it prints also the log probability and the time needed for each step.

verbose_interval  [int, default=10]  Number of iteration done before the next print.

Attributes

weights_  [array-like of shape (n_components,)]  The weights of each mixture component.

means_  [array-like of shape (n_components, n_features)]  The mean of each mixture component.

covariances_  [array-like]  The covariance of each mixture component. The shape depends on covariance_type:

<table>
<thead>
<tr>
<th>Shape</th>
<th>Covariance Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>(n_components,)</td>
<td>'spherical',</td>
</tr>
<tr>
<td>(n_features, n_features)</td>
<td>'tied',</td>
</tr>
<tr>
<td>(n_components, n_features)</td>
<td>'diag',</td>
</tr>
<tr>
<td>(n_components, n_features, n_features)</td>
<td>'full'</td>
</tr>
</tbody>
</table>

precisions_  [array-like]  The precision matrices for each component in the mixture. A precision matrix is the inverse of a covariance matrix. A covariance matrix is symmetric positive definite so the mixture of Gaussian can be equivalently parameterized by the precision matrices. Storing the precision matrices instead of the covariance matrices makes it more efficient to compute the log-likelihood of new samples at test time. The shape depends on covariance_type:

<table>
<thead>
<tr>
<th>Shape</th>
<th>Covariance Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>(n_components,)</td>
<td>'spherical',</td>
</tr>
<tr>
<td>(n_features, n_features)</td>
<td>'tied',</td>
</tr>
<tr>
<td>(n_components, n_features)</td>
<td>'diag',</td>
</tr>
<tr>
<td>(n_components, n_features, n_features)</td>
<td>'full'</td>
</tr>
</tbody>
</table>

precisions_cholesky_  [array-like]  The cholesky decomposition of the precision matrices of each mixture component. A precision matrix is the inverse of a covariance matrix. A covariance matrix is symmetric positive definite so the mixture of Gaussian can be equivalently parameterized by the precision matrices. Storing the precision matrices instead of the covariance matrices makes it more efficient to compute the log-likelihood of new samples at test time. The shape depends on covariance_type:
converged_ [bool] True when convergence was reached in fit(), False otherwise.

n_iter_ [int] Number of step used by the best fit of EM to reach the convergence.

lower_bound_ [float] Lower bound value on the log-likelihood (of the training data with respect to the model) of the best fit of EM.

See also:

BayesianGaussianMixture Gaussian mixture model fit with a variational inference.

Examples

```python
>>> import numpy as np
>>> from sklearn.mixture import GaussianMixture
>>> X = np.array([[1, 2], [1, 4], [1, 0], [10, 2], [10, 4], [10, 0]])
>>> gm = GaussianMixture(n_components=2, random_state=0).fit(X)
>>> gm.means_
array([[10., 2.],
       [ 1., 2.]])
>>> gm.predict([[0, 0], [12, 3]])
array([1, 0])
```

Methods

- `aic(X)` Akaike information criterion for the current model on the input X.
- `bic(X)` Bayesian information criterion for the current model on the input X.
- `fit(X[, y])` Estimate model parameters with the EM algorithm.
- `fit_predict(X[, y])` Estimate model parameters using X and predict the labels for X.
- `get_params([deep])` Get parameters for this estimator.
- `predict(X)` Predict the labels for the data samples in X using trained model.
- `predict_proba(X)` Predict posterior probability of each component given the data.
- `sample([n_samples])` Generate random samples from the fitted Gaussian distribution.
- `score(X[, y])` Compute the per-sample average log-likelihood of the given data X.
- `score_samples(X)` Compute the weighted log probabilities for each sample.
- `set_params(**params)` Set the parameters of this estimator.

```python
aic(X)
Akaike information criterion for the current model on the input X.
```
Parameters
X [array of shape (n_samples, n_dimensions)]

Returns
aic [float] The lower the better.

bic(X)
Bayesian information criterion for the current model on the input X.

Parameters
X [array of shape (n_samples, n_dimensions)]

Returns
bic [float] The lower the better.

fit (X, y=None)
Estimate model parameters with the EM algorithm.

The method fits the model n_init times and sets the parameters with which the model has the largest likelihood or lower bound. Within each trial, the method iterates between E-step and M-step for max_iter times until the change of likelihood or lower bound is less than tol, otherwise, a ConvergenceWarning is raised. If warm_start is True, then n_init is ignored and a single initialization is performed upon the first call. Upon consecutive calls, training starts where it left off.

Parameters
X [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

Returns
self

fit_predict (X, y=None)
Estimate model parameters using X and predict the labels for X.

The method fits the model n_init times and sets the parameters with which the model has the largest likelihood or lower bound. Within each trial, the method iterates between E-step and M-step for max_iter times until the change of likelihood or lower bound is less than tol, otherwise, a ConvergenceWarning is raised. After fitting, it predicts the most probable label for the input data points.

New in version 0.20.

Parameters
X [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

Returns
labels [array, shape (n_samples,)] Component labels.

get_params (deep=True)
Get parameters for this estimator.

Parameters
dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

**predict** (*X*)
Predict the labels for the data samples in *X* using trained model.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*labels* [array, shape (n_samples,)] Component labels.

**predict_proba** (*X*)
Predict posterior probability of each component given the data.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*resp* [array, shape (n_samples, n_components)] Returns the probability each Gaussian (state) in the model given each sample.

**sample** (*n_samples=1*)
Generate random samples from the fitted Gaussian distribution.

**Parameters**

*n_samples* [int, default=1] Number of samples to generate.

**Returns**

*X* [array, shape (n_samples, n_features)] Randomly generated sample

*y* [array, shape (nsamples,)] Component labels

**score** (*X*, *y=None*)
Compute the per-sample average log-likelihood of the given data *X*.

**Parameters**

*X* [array-like of shape (n_samples, n_dimensions)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*log_likelihood* [float] Log likelihood of the Gaussian mixture given *X*.

**score_samples** (*X*)
Compute the weighted log probabilities for each sample.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] List of n_features-dimensional data points. Each row corresponds to a single data point.

**Returns**

*log_prob* [array, shape (n_samples,)] Log probabilities of each data point in *X*.

**set_params** (**params**) Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.mixture.GaussianMixture**

- Comparing different clustering algorithms on toy datasets
- Density Estimation for a Gaussian mixture
- Gaussian Mixture Model Ellipsoids
- Gaussian Mixture Model Selection
- GMM covariances
- Gaussian Mixture Model Sine Curve

7.26 sklearn.model_selection: Model Selection

User guide: See the Cross-validation: evaluating estimator performance, Tuning the hyper-parameters of an estimator and Learning curve sections for further details.

7.26.1 Splitter Classes

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
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<td><code>model_selection.GroupKFold(n_splits)</code></td>
<td>K-fold iterator variant with non-overlapping groups.</td>
</tr>
<tr>
<td><code>model_selection.GroupShuffleSplit(...)</code></td>
<td>Shuffle-Group(s)-Out cross-validation iterator</td>
</tr>
<tr>
<td><code>model_selection.KFold([n_splits, shuffle,...])</code></td>
<td>K-Folds cross-validator</td>
</tr>
<tr>
<td><code>model_selection.LeaveOneGroupOut()</code></td>
<td>Leave One Group Out cross-validator</td>
</tr>
<tr>
<td><code>model_selection.LeavePGroupsOut(n_groups)</code></td>
<td>Leave P Group(s) Out cross-validator</td>
</tr>
<tr>
<td><code>model_selection.LeaveOneOut()</code></td>
<td>Leave-One-Out cross-validator</td>
</tr>
<tr>
<td><code>model_selection.LeavePOut(p)</code></td>
<td>Leave-P-Out cross-validator</td>
</tr>
<tr>
<td><code>model_selection.PredefinedSplit(test_fold)</code></td>
<td>Predefined split cross-validator</td>
</tr>
<tr>
<td><code>model_selection.ShuffleSplit([n_splits,...])</code></td>
<td>Random permutation cross-validator</td>
</tr>
<tr>
<td><code>model_selection.StratifiedKFold([n_splits,...])</code></td>
<td>Stratified K-Folds cross-validator.</td>
</tr>
</tbody>
</table>

continues on next page
### sklearn.model_selection.GroupKFold

**class sklearn.model_selection.GroupKFold(n_splits=5)**

K-fold iterator variant with non-overlapping groups.

The same group will not appear in two different folds (the number of distinct groups has to be at least equal to the number of folds).

The folds are approximately balanced in the sense that the number of distinct groups is approximately the same in each fold.


**Parameters**

- **n_splits** [int, default=5] Number of folds. Must be at least 2.

  Changed in version 0.22: `n_splits` default value changed from 3 to 5.

**See also:**


**Examples**

```python
>>> import numpy as np
>>> from sklearn.model_selection import GroupKFold
>>> X = np.array([[1, 2], [3, 4], [5, 6], [7, 8]])
>>> y = np.array([1, 2, 3, 4])
>>> groups = np.array([0, 0, 2, 2])
>>> group_kfold = GroupKFold(n_splits=2)
>>> group_kfold.get_n_splits(X, y, groups)
2
>>> for train_index, test_index in group_kfold.split(X, y, groups):
...     print("TRAIN: ", train_index, " TEST: ", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
...     print(X_train, X_test, y_train, y_test)

TRAIN: [0 1] TEST: [2 3]
[[1 2]
 [3 4]] [[5 6]
 [7 8]]
TRAIN: [2 3] TEST: [0 1]
[[5 6]
 [7 8]] [[1 2]
 [3 4]]
```
## Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>get_n_splits</code></td>
<td>Returns the number of splitting iterations in the cross-validator.</td>
</tr>
<tr>
<td><code>split</code></td>
<td>Generate indices to split data into training and test set.</td>
</tr>
</tbody>
</table>

### `get_n_splits`(X=None, y=None, groups=None)
Returns the number of splitting iterations in the cross-validator

**Parameters**

- **X** [object] Always ignored, exists for compatibility.
- **y** [object] Always ignored, exists for compatibility.
- **groups** [object] Always ignored, exists for compatibility.

**Returns**

- **n_splits** [int] Returns the number of splitting iterations in the cross-validator.

### `split`(X, y=None, groups=None)
Generate indices to split data into training and test set.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,), default=None] The target variable for supervised learning problems.
- **groups** [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set.

**Yields**

- **train** [ndarray] The training set indices for that split.
- **test** [ndarray] The testing set indices for that split.

### Examples using `sklearn.model_selection.GroupKFold`

- Visualizing cross-validation behavior in scikit-learn

### `sklearn.model_selection.GroupShuffleSplit`

**class** `sklearn.model_selection.GroupShuffleSplit`(n_splits=5, *, test_size=None, train_size=None, random_state=None)

Shuffle-Group(s)-Out cross-validation iterator

Provides randomized train/test indices to split data according to a third-party provided group. This group information can be used to encode arbitrary domain specific stratifications of the samples as integers.

For instance the groups could be the year of collection of the samples and thus allow for cross-validation against time-based splits.
The difference between LeavePGroupsOut and GroupShuffleSplit is that the former generates splits using all subsets of size \(p\) unique groups, whereas GroupShuffleSplit generates a user-determined number of random test splits, each with a user-determined fraction of unique groups.

For example, a less computationally intensive alternative to `LeavePGroupsOut(p=10)` would be `GroupShuffleSplit(test_size=10, n_splits=100).

Note: The parameters `test_size` and `train_size` refer to groups, and not to samples, as in ShuffleSplit. Read more in the *User Guide*.

**Parameters**

- **n_splits** [int, default=5] Number of re-shuffling & splitting iterations.
- **test_size** [float, int, default=0.2] If float, should be between 0.0 and 1.0 and represent the proportion of groups to include in the test split (rounded up). If int, represents the absolute number of test groups. If None, the value is set to the complement of the train size. The default will change in version 0.21. It will remain 0.2 only if `train_size` is unspecified, otherwise it will complement the specified `train_size`.
- **train_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the groups to include in the train split. If int, represents the absolute number of train groups. If None, the value is automatically set to the complement of the test size.
- **random_state** [int, RandomState instance or None, default=None] Controls the randomness of the training and testing indices produced. Pass an int for reproducible output across multiple function calls. See *Glossary*.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.model_selection import GroupShuffleSplit
>>> X = np.ones(shape=(8, 2))
>>> y = np.ones(shape=(8, 1))
>>> groups = np.array([1, 1, 2, 2, 2, 3, 3, 3])
>>> print(groups.shape)
(8,)
>>> gss = GroupShuffleSplit(n_splits=2, train_size=.7, random_state=42)
>>> gss.get_n_splits()
2
>>> for train_idx, test_idx in gss.split(X, y, groups):
...    print("TRAIN: ", train_idx, "TEST: ", test_idx)
TRAIN: [2 3 4 5 6 7] TEST: [0 1]
TRAIN: [0 1 5 6 7] TEST: [2 3 4]
```

**Methods**

- **get_n_splits([X, y, groups])** Returns the number of splitting iterations in the cross-validator
- **split(X, y, groups)** Generate indices to split data into training and test set.

**get_n_splits(X=None, y=None, groups=None)** Returns the number of splitting iterations in the cross-validator
Parameters

X [object] Always ignored, exists for compatibility.
y [object] Always ignored, exists for compatibility.
groups [object] Always ignored, exists for compatibility.

Returns

n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
y [array-like of shape (n_samples,), default=None] The target variable for supervised learning problems.
groups [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.
test [ndarray] The testing set indices for that split.

Notes

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting random_state to an integer.

Examples using sklearn.model_selection.GroupShuffleSplit

- Visualizing cross-validation behavior in scikit-learn

sklearn.model_selection.KFold

class sklearn.model_selection.KFold(n_splits=5, *, shuffle=False, random_state=None)
K-Folds cross-validator

Provides train/test indices to split data in train/test sets. Split dataset into k consecutive folds (without shuffling by default).

Each fold is then used once as a validation while the k - 1 remaining folds form the training set.

Read more in the User Guide.

Parameters

n_splits [int, default=5] Number of folds. Must be at least 2.

Changed in version 0.22: n_splits default value changed from 3 to 5.

shuffle [bool, default=False] Whether to shuffle the data before splitting into batches. Note that the samples within each split will not be shuffled.
random_state  [int, RandomState instance or None, default=None] When shuffle is True, random_state affects the ordering of the indices, which controls the randomness of each fold. Otherwise, this parameter has no effect. Pass an int for reproducible output across multiple function calls. See Glossary.

See also:

StratifiedKFold Takes group information into account to avoid building folds with imbalanced class distributions (for binary or multiclass classification tasks).

GroupKFold K-fold iterator variant with non-overlapping groups.

RepeatedKFold Repeats K-Fold n times.

Notes

The first \( n_{samples} \% n_{splits} \) folds have size \( n_{samples} / n_{splits} + 1 \), other folds have size \( n_{samples} / n_{splits} \), where \( n_{samples} \) is the number of samples.

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting random_state to an integer.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import KFold
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([1, 2, 3, 4])
>>> kf = KFold(n_splits=2)
>>> kf.get_n_splits(X)
2
>>> print(kf)
KFold(n_splits=2, random_state=None, shuffle=False)
>>> for train_index, test_index in kf.split(X):
    ... print("TRAIN:", train_index, "TEST:", test_index)
    ... X_train, X_test = X[train_index], X[test_index]
    ... y_train, y_test = y[train_index], y[test_index]
TRAIN: [2 3] TEST: [0 1]
TRAIN: [0 1] TEST: [2 3]
```

Methods

- **get_n_splits([X, y, groups])**  
  Returns the number of splitting iterations in the cross-validator

- **split(X[, y, groups])**  
  Generate indices to split data into training and test set.

- **get_n_splits(X=None, y=None, groups=None)**  
  Returns the number of splitting iterations in the cross-validator

  **Parameters**

  - X  [object]  Always ignored, exists for compatibility.
  - y  [object]  Always ignored, exists for compatibility.
groups [object] Always ignored, exists for compatibility.

Returns

n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)], default=None] The target variable for supervised learning problems.

groups [array-like of shape (n_samples,)], default=None] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.

Examples using sklearn.model_selection.KFold

- Feature agglomeration vs. univariate selection
- Gradient Boosting Out-of-Bag estimates
- Nested versus non-nested cross-validation
- Visualizing cross-validation behavior in scikit-learn
- Cross-validation on diabetes Dataset Exercise

sklearn.model_selection.LeaveOneGroupOut

class sklearn.model_selection.LeaveOneGroupOut

Leaves One Group Out cross-validator

Provides train/test indices to split data according to a third-party provided group. This group information can be used to encode arbitrary domain specific stratifications of the samples as integers.

For instance the groups could be the year of collection of the samples and thus allow for cross-validation against time-based splits.

Read more in the User Guide.
Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import LeaveOneGroupOut

>>> X = np.array([[1, 2], [3, 4], [5, 6], [7, 8]])
>>> y = np.array([1, 2, 1, 2])
>>> groups = np.array([1, 1, 2, 2])

>>> logo = LeaveOneGroupOut()

>>> logo.get_n_splits(X, y, groups)
2

>>> logo.get_n_splits(groups=groups)  # 'groups' is always required
2

>>> print(logo)
LeaveOneGroupOut()

>>> for train_index, test_index in logo.split(X, y, groups):
...     print("TRAIN:", train_index, "TEST:", test_index)

TRAIN: [2 3] TEST: [0 1]
[5 6]
[7 8] [1 2]
[3 4] [1 2] [1 2]

TRAIN: [0 1] TEST: [2 3]
[1 2]
[3 4] [5 6]
[7 8] [1 2] [1 2]
```

Methods

```python
get_n_splits(X, y, groups=None)  Returns the number of splitting iterations in the cross-validator

split(X, y=None, groups=None)  Generate indices to split data into training and test set.

get_n_splits(X=None, y=None, groups=None)  Returns the number of splitting iterations in the cross-validator

Parameters

- `X` [object] Always ignored, exists for compatibility.
- `y` [object] Always ignored, exists for compatibility.
- `groups` [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set. This 'groups' parameter must always be specified to calculate the number of splits, though the other parameters can be omitted.

Returns

- `n_splits` [int] Returns the number of splitting iterations in the cross-validator.

split(X=None, y=None, groups=None)  Generate indices to split data into training and test set.

Parameters
scikit-learn user guide, Release 0.24.0

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,), default=None] The target variable for supervised learning problems.

groups [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.

sklearn.model_selection.LeavePGroupsOut

class sklearn.model_selection.LeavePGroupsOut (n_groups)

Leaves P Group(s) Out cross-validator

Provides train/test indices to split data according to a third-party provided group. This group information can be used to encode arbitrary domain specific stratifications of the samples as integers.

For instance the groups could be the year of collection of the samples and thus allow for cross-validation against time-based splits.

The difference between LeavePGroupsOut and LeaveOneGroupOut is that the former builds the test sets with all the samples assigned to p different values of the groups while the latter uses samples all assigned the same groups.

Read more in the User Guide.

Parameters

n_groups [int] Number of groups (p) to leave out in the test split.

See also:

GroupKFold K-fold iterator variant with non-overlapping groups.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import LeavePGroupsOut
>>> X = np.array([[1, 2], [3, 4], [5, 6]])
>>> y = np.array([1, 2, 1])
>>> groups = np.array([1, 2, 3])
>>> lpgo = LeavePGroupsOut(n_groups=2)
>>> lpgo.get_n_splits(X, y, groups)
3
>>> lpgo.get_n_splits(groups=groups)  # 'groups' is always required
3
>>> print(lpgo)
LeavePGroupsOut(n_groups=2)
>>> for train_index, test_index in lpgo.split(X, y, groups):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     print(X_train, X_test = X[train_index], X[test_index])
...     print(y_train, y_test = y[train_index], y[test_index])
...     print(X_train, X_test, y_train, y_test)
```

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<table>
<thead>
<tr>
<th>TRAIN: [2]</th>
<th>TEST: [0 1]</th>
</tr>
</thead>
<tbody>
<tr>
<td>[5 6] [1 2]</td>
<td>[1 2]</td>
</tr>
<tr>
<td>[3 4] [1]</td>
<td>[1 2]</td>
</tr>
<tr>
<td>TRAIN: [1]</td>
<td>TEST: [0 2]</td>
</tr>
<tr>
<td>[3 4] [1 2]</td>
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</tr>
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<td>[1 1]</td>
</tr>
<tr>
<td>TRAIN: [0]</td>
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</tr>
<tr>
<td>[1 2] [3 4]</td>
<td>[2]</td>
</tr>
<tr>
<td>[5 6] [1]</td>
<td>[2 1]</td>
</tr>
</tbody>
</table>

**Methods**

| `get_n_splits([X, y, groups])` | Returns the number of splitting iterations in the cross-validator |
| `split(X[, y, groups])` | Generate indices to split data into training and test set. |

**get_n_splits** *(X=None, y=None, groups=None)*

Returns the number of splitting iterations in the cross-validator

**Parameters**

- **X** [object] Always ignored, exists for compatibility.
- **y** [object] Always ignored, exists for compatibility.
- **groups** [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set. This ‘groups’ parameter must always be specified to calculate the number of splits, though the other parameters can be omitted.

**Returns**

- **n_splits** [int] Returns the number of splitting iterations in the cross-validator.

**split** *(X, y=None, groups=None)*

Generate indices to split data into training and test set.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,), default=None] The target variable for supervised learning problems.
- **groups** [array-like of shape (n_samples,)] Group labels for the samples used while splitting the dataset into train/test set.

**Yields**

- **train** [ndarray] The training set indices for that split.
- **test** [ndarray] The testing set indices for that split.
**sklearn.model_selection.LeaveOneOut**

**class sklearn.model_selection.LeaveOneOut**

Leave-One-Out cross-validator

Provides train/test indices to split data in train/test sets. Each sample is used once as a test set (singleton) while the remaining samples form the training set.

**Note:** LeaveOneOut() is equivalent to KFold(n_splits=n) and LeavePOut(p=1) where n is the number of samples.

Due to the high number of test sets (which is the same as the number of samples) this cross-validation method can be very costly. For large datasets one should favor KFold, ShuffleSplit or StratifiedKFold.

Read more in the User Guide.

**See also:**

*LeaveOneGroupOut* For splitting the data according to explicit, domain-specific stratification of the dataset.

*GroupKFold* K-fold iterator variant with non-overlapping groups.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.model_selection import LeaveOneOut
>>> X = np.array([[1, 2], [3, 4]])
>>> y = np.array([1, 2])
>>> loo = LeaveOneOut()
>>> loo.get_n_splits(X)
2
>>> print(loo)
LeaveOneOut()

>>> for train_index, test_index in loo.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
...     print(X_train, X_test, y_train, y_test)
TRAIN: [1] TEST: [0]
[[1 2]] [[3 4]] [2] [1]
TRAIN: [0] TEST: [1]
[[3 4]] [[1 2]] [1] [2]
```

**Methods**

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>get_n_splits(X[, y, groups])</code></td>
<td>Returns the number of splitting iterations in the cross-validator</td>
</tr>
<tr>
<td><code>split(X[, y, groups])</code></td>
<td>Generate indices to split data into training and test set.</td>
</tr>
</tbody>
</table>

```python
get_n_splits(X, y=None, groups=None)

Returns the number of splitting iterations in the cross-validator

Parameters

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the num-
```
ber of samples and n_features is the number of features.

y [object] Always ignored, exists for compatibility.

groups [object] Always ignored, exists for compatibility.

Returns

n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X, y=None, groups=None)

Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] The target variable for supervised learning problems.

groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.

sklearn.model_selection.LeavePOut

class sklearn.model_selection.LeavePOut(p)

Leave-P-Out cross-validator

Provides train/test indices to split data in train/test sets. This results in testing on all distinct samples of size p, while the remaining n - p samples form the training set in each iteration.

Note: LeavePOut(p) is NOT equivalent to KFold(n_splits=n_samples // p) which creates non-overlapping test sets.

Due to the high number of iterations which grows combinatorically with the number of samples this cross-validation method can be very costly. For large datasets one should favor KFold, StratifiedKFold or ShuffleSplit.

Read more in the User Guide.

Parameters

p [int] Size of the test sets. Must be strictly less than the number of samples.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import LeavePOut
>>> X = np.array([[1, 2], [3, 4], [5, 6], [7, 8]])
>>> y = np.array([1, 2, 3, 4])
>>> lpo = LeavePOut(2)
>>> lpo.get_n_splits(X)
6
>>> print(lpo)
LeavePOut(p=2)
```
» for train_index, test_index in lpo.split(X):
...    print("TRAIN:", train_index, "TEST:", test_index)
...    X_train, X_test = X[train_index], X[test_index]
...    y_train, y_test = y[train_index], y[test_index]
TRAIN: [2 3] TEST: [0 1]
TRAIN: [1 3] TEST: [0 2]
TRAIN: [1 2] TEST: [0 3]
TRAIN: [0 3] TEST: [1 2]
TRAIN: [0 2] TEST: [1 3]
TRAIN: [0 1] TEST: [2 3]

Methods

get_n_splits(X[, y, groups])
Returns the number of splitting iterations in the cross-validator

split(X[, y, groups])
Generate indices to split data into training and test set.

get_n_splits (X, y=None, groups=None)
Returns the number of splitting iterations in the cross-validator

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [object] Always ignored, exists for compatibility.

groups [object] Always ignored, exists for compatibility.

split (X, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] The target variable for supervised learning problems.

groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.
sklearn.model_selection.PredefinedSplit

class sklearn.model_selection.PredefinedSplit(test_fold)

Predefined split cross-validator

Provides train/test indices to split data into train/test sets using a predefined scheme specified by the user with the test_fold parameter.

Read more in the User Guide.

New in version 0.16.

Parameters

test_fold [array-like of shape (n_samples,)] The entry test_fold[i] represents the index of the test set that sample i belongs to. It is possible to exclude sample i from any test set (i.e. include sample i in every training set) by setting test_fold[i] equal to -1.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import PredefinedSplit
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([0, 0, 1, 1])
>>> test_fold = [0, 1, -1, 1]
>>> ps = PredefinedSplit(test_fold)
>>> ps.get_n_splits()
2
>>> for train_index, test_index in ps.split():
...     print("TRAIN: ", train_index, "TEST: ", test_index)
TRAIN: [1 2 3] TEST: [0]
TRAIN: [0 2] TEST: [1 3]
```

Methods

get_n_splits([X, y, groups]) Returns the number of splitting iterations in the cross-validator

split([X, y, groups]) Generate indices to split data into training and test set.

get_n_splits (X=None, y=None, groups=None)

Returns the number of splitting iterations in the cross-validator

Parameters

X [object] Always ignored, exists for compatibility.

y [object] Always ignored, exists for compatibility.

groups [object] Always ignored, exists for compatibility.

Returns
n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X=None, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X [object] Always ignored, exists for compatibility.

y [object] Always ignored, exists for compatibility.

groups [object] Always ignored, exists for compatibility.

Yields

train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.

sklearn.model_selection.RepeatedKFold
class sklearn.model_selection.RepeatedKFold(*, n_splits=5, n_repeats=10, random_state=None)
Repeated K-Fold cross validator.
Repeats K-Fold n times with different randomization in each repetition.
Read more in the User Guide.

Parameters

n_splits [int, default=5] Number of folds. Must be at least 2.

n_repeats [int, default=10] Number of times cross-validator needs to be repeated.

random_state [int, RandomState instance or None, default=None] Controls the randomness of each repeated cross-validation instance. Pass an int for reproducible output across multiple function calls. See Glossary.

See also:

RepeatedStratifiedKFold Repeats Stratified K-Fold n times.

Notes

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting random_state to an integer.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import RepeatedKFold
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([0, 0, 1, 1])
>>> rkf = RepeatedKFold(n_splits=2, n_repeats=2, random_state=2652124)
>>> for train_index, test_index in rkf.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
``` (continues on next page)
Methods

**get_n_splits** ([X, y, groups])
Returns the number of splitting iterations in the cross-validator.

**split** ([X[, y, groups]])
Generates indices to split data into training and test set.

---

**get_n_splits** (*X=None, y=None, groups=None*)
Returns the number of splitting iterations in the cross-validator.

**Parameters**

- **X** [object] Always ignored, exists for compatibility. np.zeros(n_samples) may be used as a placeholder.
- **y** [object] Always ignored, exists for compatibility. np.zeros(n_samples) may be used as a placeholder.
- **groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set.

**Returns**

- **n_splits** [int] Returns the number of splitting iterations in the cross-validator.

**split** (*X, y=None, groups=None*)
Generates indices to split data into training and test set.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)] The target variable for supervised learning problems.
- **groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set.

**Yields**

- **train** [ndarray] The training set indices for that split.
- **test** [ndarray] The testing set indices for that split.
Examples using `sklearn.model_selection.RepeatedKFold`

- Common pitfalls in interpretation of coefficients of linear models

`sklearn.model_selection.RepeatedStratifiedKFold`

class `sklearn.model_selection.RepeatedStratifiedKFold(*, n_splits=5, n_repeats=10, random_state=None)`

Repeated Stratified K-Fold cross validator.

Repeats Stratified K-Fold n times with different randomization in each repetition.

Read more in the User Guide.

Parameters

- `n_splits` [int, default=5] Number of folds. Must be at least 2.
- `n_repeats` [int, default=10] Number of times cross-validator needs to be repeated.
- `random_state` [int, RandomState instance or None, default=None] Controls the generation of the random states for each repetition. Pass an int for reproducible output across multiple function calls. See Glossary.

See also:

`RepeatedKFold` Repeats K-Fold n times.

Notes

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting `random_state` to an integer.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import RepeatedStratifiedKFold
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([0, 0, 1, 1])
>>> rskf = RepeatedStratifiedKFold(n_splits=2, n_repeats=2,
...                               random_state=36851234)
>>> for train_index, test_index in rskf.split(X, y):
...     print("TRAIN: ", train_index, " TEST: ", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
...     print("TRAIN: ", X_train, " TEST: ", X_test)
TRAIN: [1 2] TEST: [0 3]
TRAIN: [0 3] TEST: [1 2]
TRAIN: [1 3] TEST: [0 2]
TRAIN: [0 2] TEST: [1 3]
```
## Methods

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<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>get_n_splits([X, y, groups])</code></td>
<td>Returns the number of splitting iterations in the cross-validator.</td>
</tr>
<tr>
<td><code>split(X[, y, groups])</code></td>
<td>Generates indices to split data into training and test set.</td>
</tr>
</tbody>
</table>

### `get_n_splits(X=None, y=None, groups=None)`

Returns the number of splitting iterations in the cross-validator

**Parameters**

- **X** [object]  Always ignored, exists for compatibility. `np.zeros(n_samples)` may be used as a placeholder.
- **y** [object]  Always ignored, exists for compatibility. `np.zeros(n_samples)` may be used as a placeholder.
- **groups** [array-like of shape (n_samples,), default=None]  Group labels for the samples used while splitting the dataset into train/test set.

**Returns**

- **n_splits** [int]  Returns the number of splitting iterations in the cross-validator.

### `split(X, y=None, groups=None)`

Generates indices to split data into training and test set.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]  Training data, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)]  The target variable for supervised learning problems.
- **groups** [array-like of shape (n_samples,), default=None]  Group labels for the samples used while splitting the dataset into train/test set.

**Yields**

- **train** [ndarray]  The training set indices for that split.
- **test** [ndarray]  The testing set indices for that split.

### Examples using `sklearn.model_selection.RepeatedStratifiedKFold`

- Statistical comparison of models using grid search

### `sklearn.model_selection.ShuffleSplit`

**class sklearn.model_selection.ShuffleSplit (n_splits=10, *, test_size=None, train_size=None, random_state=None)**

Random permutation cross-validator

Yields indices to split data into training and test sets.

Note: contrary to other cross-validation strategies, random splits do not guarantee that all folds will be different, although this is still very likely for sizeable datasets.

Read more in the User Guide.
Parameters

- **n_splits** [int, default=10] Number of re-shuffling & splitting iterations.
- **test_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the test split. If int, represents the absolute number of test samples. If None, the value is set to the complement of the train size. If `train_size` is also None, it will be set to 0.1.
- **train_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the train split. If int, represents the absolute number of train samples. If None, the value is automatically set to the complement of the test size.
- **random_state** [int, RandomState instance or None, default=None] Controls the randomness of the training and testing indices produced. Pass an int for reproducible output across multiple function calls. See *Glossary*.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import ShuffleSplit
>>> X = np.array([[1, 2], [3, 4], [5, 6], [7, 8], [3, 4], [5, 6]])
>>> y = np.array([1, 2, 1, 2, 1, 2])
>>> rs = ShuffleSplit(n_splits=5, test_size=.25, random_state=0)
>>> rs.get_n_splits(X)
5
>>> print(rs)
ShuffleSplit(n_splits=5, random_state=0, test_size=0.25, train_size=None)
>>> for train_index, test_index in rs.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
TRAIN: [1 3 0 4] TEST: [5 2]
TRAIN: [4 0 2 5] TEST: [1 3]
TRAIN: [1 2 4 0] TEST: [3 5]
TRAIN: [3 4 1 0] TEST: [5 2]
TRAIN: [3 5 1 0] TEST: [2 4]
```

Methods

- **get_n_splits**([X, y, groups]) Returns the number of splitting iterations in the cross-validator
- **split**(X[, y, groups]) Generate indices to split data into training and test set.

```python
get_n_splits (X=None, y=None, groups=None)
    Returns the number of splitting iterations in the cross-validator
```
Parameters

X [object] Always ignored, exists for compatibility.
y [object] Always ignored, exists for compatibility.
groups [object] Always ignored, exists for compatibility.

Returns

n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
y [array-like of shape (n_samples,)] The target variable for supervised learning problems.
groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set.

Yields

train [ndarray] The training set indices for that split.
test [ndarray] The testing set indices for that split.

Notes

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting random_state to an integer.

Examples using sklearn.model_selection.ShuffleSplit

- Visualizing cross-validation behavior in scikit-learn
- Plotting Learning Curves
- Scaling the regularization parameter for SVCs

sklearn.model_selection.StratifiedKFold

class sklearn.model_selection.StratifiedKFold (n_splits=5, *, shuffle=False, random_state=None)

Stratified K-Folds cross-validator.

Provides train/test indices to split data in train/test sets.

This cross-validation object is a variation of KFold that returns stratified folds. The folds are made by preserving the percentage of samples for each class.

Read more in the User Guide.

Parameters

n_splits [int, default=5] Number of folds. Must be at least 2.

Changed in version 0.22: n_splits default value changed from 3 to 5.
shuffle [bool, default=False] Whether to shuffle each class’s samples before splitting into batches. Note that the samples within each split will not be shuffled.

random_state [int, RandomState instance or None, default=None] When shuffle is True, random_state affects the ordering of the indices, which controls the randomness of each fold for each class. Otherwise, leave random_state as None. Pass an int for reproducible output across multiple function calls. See Glossary.

See also:

RepeatedStratifiedKFold Repeats Stratified K-Fold n times.

Notes

The implementation is designed to:

• Generate test sets such that all contain the same distribution of classes, or as close as possible.
• Be invariant to class label: relabelling y = ["Happy", "Sad"] to y = [1, 0] should not change the indices generated.
• Preserve order dependencies in the dataset ordering, when shuffle=False: all samples from class k in some test set were contiguous in y, or separated in y by samples from classes other than k.
• Generate test sets where the smallest and largest differ by at most one sample.

Changed in version 0.22: The previous implementation did not follow the last constraint.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import StratifiedKFold
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([0, 0, 1, 1])
>>> skf = StratifiedKFold(n_splits=2)
>>> skf.get_n_splits(X, y)
2
>>> for train_index, test_index in skf.split(X, y):
...     print("TRAIN: ", train_index, " TEST: ", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
TRAIN: [1 3] TEST: [0 2]
TRAIN: [0 2] TEST: [1 3]
```

Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
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<tbody>
<tr>
<td>get_n_splits((X, y, groups))</td>
<td>Returns the number of splitting iterations in the cross-validator</td>
</tr>
<tr>
<td>split(X, y, [groups])</td>
<td>Generate indices to split data into training and test set.</td>
</tr>
<tr>
<td>get_n_splits(X=None, y=None, groups=None)</td>
<td>Returns the number of splitting iterations in the cross-validator</td>
</tr>
</tbody>
</table>
Parameters

X [object] Always ignored, exists for compatibility.
y [object] Always ignored, exists for compatibility.

groups [object] Always ignored, exists for compatibility.

Returns

n_splits [int] Returns the number of splitting iterations in the cross-validator.

split (X, y, groups=None)
Generate indices to split data into training and test set.

Parameters

X [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.

Note that providing y is sufficient to generate the splits and hence np.zeros(n_samples) may be used as a placeholder for X instead of actual training data.

y [array-like of shape (n_samples,)] The target variable for supervised learning problems. Stratification is done based on the y labels.

groups [object] Always ignored, exists for compatibility.

Yields

train [ndarray] The training set indices for that split.
test [ndarray] The testing set indices for that split.

Notes

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting random_state to an integer.

Examples using sklearn.model_selection.StratifiedKFold

- Recursive feature elimination with cross-validation
- Test with permutations the significance of a classification score
- GMM covariances
- Receiver Operating Characteristic (ROC) with cross validation
- Visualizing cross-validation behavior in scikit-learn
- Effect of varying threshold for self-training
sklearn.model_selection.StratifiedShuffleSplit

class sklearn.model_selection.StratifiedShuffleSplit(n_splits=10, *, test_size=None, train_size=None, random_state=None)

Stratified ShuffleSplit cross-validator

Provides train/test indices to split data in train/test sets.

This cross-validation object is a merge of StratifiedKFold and ShuffleSplit, which returns stratified randomized folds. The folds are made by preserving the percentage of samples for each class.

Note: like the ShuffleSplit strategy, stratified random splits do not guarantee that all folds will be different, although this is still very likely for sizeable datasets.

Read more in the User Guide.

Parameters

- **n_splits** [int, default=10] Number of re-shuffling & splitting iterations.
- **test_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the test split. If int, represents the absolute number of test samples. If None, the value is set to the complement of the train size. If train_size is also None, it will be set to 0.1.
- **train_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the train split. If int, represents the absolute number of train samples. If None, the value is automatically set to the complement of the test size.
- **random_state** [int, RandomState instance or None, default=None] Controls the randomness of the training and testing indices produced. Pass an int for reproducible output across multiple function calls. See Glossary.

Examples

```python
>>> import numpy as np
>>> from sklearn.model_selection import StratifiedShuffleSplit
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([0, 0, 0, 1, 1, 1])
>>> sss = StratifiedShuffleSplit(n_splits=5, test_size=0.5, random_state=0)
>>> sss.get_n_splits(X, y)
5
>>> print(sss)
StratifiedShuffleSplit(n_splits=5, random_state=0, ...)
>>> for train_index, test_index in sss.split(X, y):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
TRAIN: [5 2 3] TEST: [4 1 0]
TRAIN: [5 1 4] TEST: [0 2 3]
TRAIN: [5 0 2] TEST: [4 3 1]
TRAIN: [4 1 0] TEST: [2 3 5]
TRAIN: [0 5 1] TEST: [3 4 2]
```
Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>get_n_splits([X, y, groups])</code></td>
<td>Returns the number of splitting iterations in the cross-validator</td>
</tr>
<tr>
<td><code>split(X, y[, groups])</code></td>
<td>Generate indices to split data into training and test set.</td>
</tr>
</tbody>
</table>

**get_n_splits** (`X=None, y=None, groups=None`)

Returns the number of splitting iterations in the cross-validator.

**Parameters**

- `X` [object] Always ignored, exists for compatibility.
- `y` [object] Always ignored, exists for compatibility.
- `groups` [object] Always ignored, exists for compatibility.

**Returns**

- `n_splits` [int] Returns the number of splitting iterations in the cross-validator.

**split** (`X, y, groups=None`)

Generate indices to split data into training and test set.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Training data, where n_samples is the number of samples and n_features is the number of features.
  
  Note that providing `y` is sufficient to generate the splits and hence `np.zeros(n_samples)` may be used as a placeholder for `X` instead of actual training data.
- `y` [array-like of shape (n_samples,) or (n_samples, n_labels)] The target variable for supervised learning problems. Stratification is done based on the y labels.
- `groups` [object] Always ignored, exists for compatibility.

**Yields**

- `train` [ndarray] The training set indices for that split.
- `test` [ndarray] The testing set indices for that split.

**Notes**

Randomized CV splitters may return different results for each call of split. You can make the results identical by setting `random_state` to an integer.

**Examples using sklearn.model_selection.StratifiedShuffleSplit**

- Visualizing cross-validation behavior in scikit-learn
- RBF SVM parameters
sklearn.model_selection.TimeSeriesSplit

class sklearn.model_selection.TimeSeriesSplit (n_splits=5, *, max_train_size=None, test_size=None, gap=0)

Time Series cross-validator

Provides train/test indices to split time series data samples that are observed at fixed time intervals, in train/test sets. In each split, test indices must be higher than before, and thus shuffling in cross validator is inappropriate.

This cross-validation object is a variation of KFold. In the kth split, it returns first k folds as train set and the (k+1)th fold as test set.

Note that unlike standard cross-validation methods, successive training sets are supersets of those that come before them.

Read more in the User Guide.

New in version 0.18.

Parameters

n_splits [int, default=5] Number of splits. Must be at least 2.

Changed in version 0.22: n_splits default value changed from 3 to 5.

max_train_size [int, default=None] Maximum size for a single training set.

test_size [int, default=None] Used to limit the size of the test set. Defaults to n_samples // (n_splits + 1), which is the maximum allowed value with gap=0.

New in version 0.24.

gap [int, default=0] Number of samples to exclude from the end of each train set before the test set.

New in version 0.24.

Notes

The training set has size i * n_samples // (n_splits + 1) + n_samples % (n_splits + 1) in the i th split, with a test set of size n_samples//(n_splits + 1) by default, where n_samples is the number of samples.

Examples

>>> import numpy as np
>>> from sklearn.model_selection import TimeSeriesSplit
>>> X = np.array([[1, 2], [3, 4], [1, 2], [3, 4], [1, 2], [3, 4]])
>>> y = np.array([1, 2, 3, 4, 5, 6])
>>> tscv = TimeSeriesSplit()
>>> print(tscv)
TimeSeriesSplit(gap=0, max_train_size=None, n_splits=5, test_size=None)
>>> for train_index, test_index in tscv.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
TRAIN: [0] TEST: [1]
TRAIN: [0 1] TEST: [2]
TRAIN: [0 1 2] TEST: [3]
TRAIN: [0 1 2 3] TEST: [4]
TRAIN: [0 1 2 3 4] TEST: [5]

>>> # Fix test_size to 2 with 12 samples
>>> X = np.random.randn(12, 2)
>>> y = np.random.randint(0, 2, 12)
>>> tscv = TimeSeriesSplit(n_splits=3, test_size=2)
>>> for train_index, test_index in tscv.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
TRAIN: [0 1 2 3 4 5] TEST: [6 7]
TRAIN: [0 1 2 3 4 5 6 7] TEST: [8 9]
TRAIN: [0 1 2 3 4 5 6 7 8 9] TEST: [10 11]

>>> # Add in a 2 period gap
>>> tscv = TimeSeriesSplit(n_splits=3, test_size=2, gap=2)
>>> for train_index, test_index in tscv.split(X):
...     print("TRAIN:", train_index, "TEST:", test_index)
...     X_train, X_test = X[train_index], X[test_index]
...     y_train, y_test = y[train_index], y[test_index]
TRAIN: [0 1 2 3] TEST: [6 7]
TRAIN: [0 1 2 3 4 5] TEST: [8 9]
TRAIN: [0 1 2 3 4 5 6 7] TEST: [10 11]

Methods

get_n_splits(X, y, groups)  Returns the number of splitting iterations in the cross-validator

split(X, y, groups)  Generate indices to split data into training and test set.

get_n_splits(X=None, y=None, groups=None)
Returns the number of splitting iterations in the cross-validator

Parameters

X  [object]  Always ignored, exists for compatibility.
y  [object]  Always ignored, exists for compatibility.
groups  [object]  Always ignored, exists for compatibility.

Returns

n_splits  [int]  Returns the number of splitting iterations in the cross-validator.

split(X, y=None, groups=None)
Generate indices to split data into training and test set.

Parameters

X  [array-like of shape (n_samples, n_features)]  Training data, where n_samples is the number of samples and n_features is the number of features.
y  [array-like of shape (n_samples,)]  Always ignored, exists for compatibility.
groups  [array-like of shape (n_samples,)]  Always ignored, exists for compatibility.

Yields
train [ndarray] The training set indices for that split.

test [ndarray] The testing set indices for that split.

Examples using sklearn.model_selection.TimeSeriesSplit

• Visualizing cross-validation behavior in scikit-learn

7.26.2 Splitter Functions

| sklearn.model_selection.check_cv((cv, y, classifier)) | Input checker utility for building a cross-validator |
| sklearn.model_selection.train_test_split(*arrays[, . . .]) | Split arrays or matrices into random train and test subsets |

sklearn.model_selection.check_cv

sklearn.model_selection.check_cv (cv=5, y=None, *, classifier=False)
Input checker utility for building a cross-validator

Parameters

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are: - None, to use the default 5-fold cross validation, - integer, to specify the number of folds. - CV splitter, - An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if classifier is True and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value changed from 3-fold to 5-fold.

y [array-like, default=None] The target variable for supervised learning problems.

classifier [bool, default=False] Whether the task is a classification task, in which case stratified KFold will be used.

Returns

cHECKED Cv [a cross-validator instance.] The return value is a cross-validator which generates the train/test splits via the split method.

sklearn.model_selection.train_test_split

sklearn.model_selection.train_test_split (*arrays, test_size=None, train_size=None, random_state=None, shuffle=True, stratify=None)
Split arrays or matrices into random train and test subsets

Quick utility that wraps input validation and next(ShuffleSplit().split(X, y)) and application to input data into a single call for splitting (and optionally subsampling) data in a oneliner.

Read more in the User Guide.

Parameters
*arrays* [sequence of indexables with same length / shape[0]] Allowed inputs are lists, numpy arrays, scipy-sparse matrices or pandas dataframes.

**test_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the test split. If int, represents the absolute number of test samples. If None, the value is set to the complement of the train size. If train_size is also None, it will be set to 0.25.

**train_size** [float or int, default=None] If float, should be between 0.0 and 1.0 and represent the proportion of the dataset to include in the train split. If int, represents the absolute number of train samples. If None, the value is automatically set to the complement of the test size.

**random_state** [int, RandomState instance or None, default=None] Controls the shuffling applied to the data before applying the split. Pass an int for reproducible output across multiple function calls. See Glossary.

**shuffle** [bool, default=True] Whether or not to shuffle the data before splitting. If shuffle=False then stratify must be None.

**stratify** [array-like, default=None] If not None, data is split in a stratified fashion, using this as the class labels. Read more in the User Guide.

**Returns**

**splitting** [list, length=2 * len(arrays)] List containing train-test split of inputs.

New in version 0.16: If the input is sparse, the output will be a `scipy.sparse.csr_matrix`. Else, output type is the same as the input type.

**Examples**

```python
code
>>> import numpy as np
>>> from sklearn.model_selection import train_test_split
>>> X, y = np.arange(10).reshape((5, 2)), range(5)
>>> X
array([[0, 1],
       [2, 3],
       [4, 5],
       [6, 7],
       [8, 9]])
>>> list(y)
[0, 1, 2, 3, 4]

>>> X_train, X_test, y_train, y_test = train_test_split(.... X, y, test_size=0.33, random_state=42)
...
>>> X_train
array([[4, 5],
       [0, 1],
       [6, 7]])
>>> y_train
[2, 0, 3]
>>> X_test
array([[2, 3],
       [8, 9]])
>>> y_test
[1, 4]
```
Examples using sklearn.model_selection.train_test_split

- Release Highlights for scikit-learn 0.23
- Release Highlights for scikit-learn 0.24
- Release Highlights for scikit-learn 0.22
- Probability Calibration curves
- Probability calibration of classifiers
- Recognizing hand-written digits
- Classifier comparison
- Principal Component Regression vs Partial Least Squares Regression
- Post pruning decision trees with cost complexity pruning
- Understanding the decision tree structure
- Comparing random forests and the multi-output meta estimator
- Gradient Boosting regression
- Early stopping of Gradient Boosting
- Feature transformations with ensembles of trees
- Gradient Boosting Out-of-Bag estimates
- Faces recognition example using eigenfaces and SVMs
- Prediction Latency
- Pipeline Anova SVM
- Univariate Feature Selection
- Non-negative least squares
- Comparing various online solvers
- MNIST classification using multinomial logistic + L1
- Multiclass sparse logistic regression on 20newsgroups
- Early stopping of Stochastic Gradient Descent
- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
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- Permutation Importance vs Random Forest Feature Importance (MDI)
- Partial Dependence and Individual Conditional Expectation Plots
- Common pitfalls in interpretation of coefficients of linear models
- Scalable learning with polynomial kernel approximation
• ROC Curve with Visualization API
• Visualizations with Display Objects
• Confusion matrix
• Detection error tradeoff (DET) curve
• Parameter estimation using grid search with cross-validation
• Receiver Operating Characteristic (ROC)
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• Effect of transforming the targets in regression model
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• Map data to a normal distribution
• Feature discretization
• Semi-supervised Classification on a Text Dataset

7.26.3 Hyper-parameter optimizers

```
model_selection.GridSearchCV(estimator, ...
...)
```
Exhaustive search over specified parameter values for an estimator.

```
model_selection.HalvingGridSearchCV(...[...])
```
Search over specified parameter values with successive halving.

```
model_selection.ParameterGrid(param_grid)
```
Grid of parameters with a discrete number of values for each.

```
model_selection.ParameterSampler(...[, ...])
```
Generator on parameters sampled from given distributions.

```
model_selection.RandomizedSearchCV(...[...])
```
Randomized search on hyper parameters.

```
model_selection.HalvingRandomSearchCV(...[...])
```
Randomized search on hyper parameters.
sklearn.model_selection.GridSearchCV

class sklearn.model_selection.GridSearchCV(estimator, param_grid, *, scoring=None, n_jobs=None, refit=True, cv=None, verbose=0, pre_dispatch='2*n_jobs', error_score=nan, return_train_score=False)

Exhaustive search over specified parameter values for an estimator.

Important members are fit, predict.

GridSearchCV implements a “fit” and a “score” method. It also implements “score_samples”, “predict”, “predict_proba”, “decision_function”, “transform” and “inverse_transform” if they are implemented in the estimator used.

The parameters of the estimator used to apply these methods are optimized by cross-validated grid-search over a parameter grid.

Read more in the User Guide.

Parameters

estimator [estimator object.] This is assumed to implement the scikit-learn estimator interface. Either estimator needs to provide a score function, or scoring must be passed.

param_grid [dict or list of dictionaries] Dictionary with parameters names (str) as keys and lists of parameter settings to try as values, or a list of such dictionaries, in which case the grids spanned by each dictionary in the list are explored. This enables searching over any sequence of parameter settings.

scoring [str, callable, list/tuple or dict, default=None] A single str (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set.

For evaluating multiple metrics, either give a list of (unique) strings or a dict with names as keys and callables as values.

NOTE that when using custom scorers, each scorer should return a single value. Metric functions returning a list/array of values can be wrapped into multiple scorers that return one value each.

See Specifying multiple metrics for evaluation for an example.

If None, the estimator’s score method is used.

n_jobs [int, default=None] Number of jobs to run in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Changed in version v0.20: n_jobs default changed from 1 to None

pre_dispatch [int, or str, default=n_jobs] Controls the number of jobs that get dispatched during parallel execution. Reducing this number can be useful to avoid an explosion of memory consumption when more jobs get dispatched than CPUs can process. This parameter can be:

• None, in which case all the jobs are immediately created and spawned. Use this for lightweight and fast-running jobs, to avoid delays due to on-demand spawning of the jobs

• An int, giving the exact number of total jobs that are spawned

• A str, giving an expression as a function of n_jobs, as in ‘2*n_jobs’

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
• None, to use the default 5-fold cross validation,
• integer, to specify the number of folds in a (Stratified)KFold,
• CV splitter,
• An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if the estimator is a classifier and $y$ is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

refit [bool, str, or callable, default=True] Refit an estimator using the best found parameters on the whole dataset.

For multiple metric evaluation, this needs to be a str denoting the scorer that would be used to find the best parameters for refitting the estimator at the end.

Where there are considerations other than maximum score in choosing a best estimator, refit can be set to a function which returns the selected best_index_ given cv_results_. In that case, the best_estimator_ and best_params_ will be set according to the returned best_index_ while the best_score_ attribute will not be available.

The refitted estimator is made available at the best_estimator_ attribute and permits using predict directly on this GridSearchCV instance.

Also for multiple metric evaluation, the attributes best_index_, best_score_ and best_params_ will only be available if refit is set and all of them will be determined w.r.t this specific scorer.

See scoring parameter to know more about multiple metric evaluation.

Changed in version 0.20: Support for callable added.

verbose [int] Controls the verbosity: the higher, the more messages.

• >1 : the computation time for each fold and parameter candidate is displayed;
• >2 : the score is also displayed;
• >3 : the fold and candidate parameter indexes are also displayed together with the starting time of the computation.

error_score ['raise' or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised. This parameter does not affect the refit step, which will always raise the error.

return_train_score [bool, default=False] If False, the cv_results_ attribute will not include training scores. Computing training scores is used to get insights on how different parameter settings impact the overfitting/underfitting trade-off. However computing the scores on the training set can be computationally expensive and is not strictly required to select the parameters that yield the best generalization performance.

New in version 0.19.

Changed in version 0.21: Default value was changed from True to False

Attributes
cv_results_ [dict of numpys (masked) ndarrays] A dict with keys as column headers and values as columns, that can be imported into a pandas DataFrame.

For instance the below given table

<table>
<thead>
<tr>
<th>param_kernel</th>
<th>param_gamma</th>
<th>param_degree</th>
<th>split0_test_score</th>
<th>...</th>
<th>rank_t...</th>
</tr>
</thead>
<tbody>
<tr>
<td>'poly'</td>
<td>--</td>
<td>2</td>
<td>0.80</td>
<td>...</td>
<td>2</td>
</tr>
<tr>
<td>'poly'</td>
<td>--</td>
<td>3</td>
<td>0.70</td>
<td>...</td>
<td>4</td>
</tr>
<tr>
<td>'rbf'</td>
<td>0.1</td>
<td>--</td>
<td>0.80</td>
<td>...</td>
<td>3</td>
</tr>
<tr>
<td>'rbf'</td>
<td>0.2</td>
<td>--</td>
<td>0.93</td>
<td>...</td>
<td>1</td>
</tr>
</tbody>
</table>

will be represented by a cv_results__dict of:

```python
{
    'param_kernel': masked_array(data = ['poly', 'poly', 'rbf', 'rbf'],
                                 mask = [False False False False]...),
    'param_gamma': masked_array(data = [ -- -- 0.1 0.2],
                               mask = [ True True False False]...),
    'param_degree': masked_array(data = [2.0 3.0 -- --],
                                  mask = [False False True True]...),
    'split0_test_score' : [0.80, 0.70, 0.80, 0.93],
    'split1_test_score' : [0.82, 0.50, 0.70, 0.78],
    'mean_test_score' : [0.81, 0.60, 0.75, 0.85],
    'std_test_score' : [0.01, 0.10, 0.05, 0.08],
    'rank_test_score' : [2, 4, 3, 1],
    'split0_train_score' : [0.80, 0.92, 0.70, 0.93],
    'split1_train_score' : [0.82, 0.55, 0.70, 0.87],
    'mean_train_score' : [0.81, 0.74, 0.70, 0.90],
    'std_train_score' : [0.01, 0.19, 0.00, 0.03],
    'mean_fit_time' : [0.73, 0.63, 0.43, 0.49],
    'std_fit_time' : [0.01, 0.02, 0.01, 0.01],
    'mean_score_time' : [0.01, 0.06, 0.04, 0.04],
    'std_score_time' : [0.00, 0.00, 0.00, 0.01],
    'params' : [{"kernel": 'poly', 'degree': 2}, ...],
}
```

NOTE

The key 'params' is used to store a list of parameter settings dicts for all the parameter candidates.

The mean_fit_time, std_fit_time, mean_score_time and std_score_time are all in seconds.

For multi-metric evaluation, the scores for all the scorers are available in the cv_results_dict at the keys ending with that scorer's name ('_<scorer_name>') instead of '_score' shown above. ('split0_test_precision', 'mean_train_precision' etc.)

best_estimator_ [estimator] Estimator that was chosen by the search, i.e. estimator which gave highest score (or smallest loss if specified) on the left out data. Not available if refit=False.

See refit parameter for more information on allowed values.

best_score_ [float] Mean cross-validated score of the best_estimator

For multi-metric evaluation, this is present only if refit is specified.

This attribute is not available if refit is a function.
best_params_  [dict] Parameter setting that gave the best results on the hold out data.
  For multi-metric evaluation, this is present only if refit is specified.

best_index_  [int] The index (of the cv_results_ arrays) which corresponds to the best candidate parameter setting.
  The dict at search.cv_results_['params'][search.best_index_] gives the parameter setting for the best model, that gives the highest mean score (search.best_score_).
  For multi-metric evaluation, this is present only if refit is specified.

scorer_  [function or a dict] Scorer function used on the held out data to choose the best parameters for the model.
  For multi-metric evaluation, this attribute holds the validated scoring dict which maps the scorer key to the scorer callable.

n_splits_  [int] The number of cross-validation splits (folds/iterations).

refit_time_  [float] Seconds used for refitting the best model on the whole dataset.
  This is present only if refit is not False.
  New in version 0.20.

multimetric_  [bool] Whether or not the scorers compute several metrics.

See also:

ParameterGrid Generates all the combinations of a hyperparameter grid.

train_test_split Utility function to split the data into a development set usable for fitting a GridSearchCV instance and an evaluation set for its final evaluation.

sklearn.metrics.make_scorer Make a scorer from a performance metric or loss function.

Notes

The parameters selected are those that maximize the score of the left out data, unless an explicit score is passed in which case it is used instead.

If n_jobs was set to a value higher than one, the data is copied for each point in the grid (and not n_jobs times). This is done for efficiency reasons if individual jobs take very little time, but may raise errors if the dataset is large and not enough memory is available. A workaround in this case is to set pre_dispatch. Then, the memory is copied only pre_dispatch many times. A reasonable value for pre_dispatch is 2 * n_jobs.

Examples

```python
>>> from sklearn import svm, datasets
>>> from sklearn.model_selection import GridSearchCV
>>> iris = datasets.load_iris()
>>> parameters = {'kernel':('linear', 'rbf'), 'C':[1, 10]}
>>> svc = svm.SVC()
>>> clf = GridSearchCV(svc, parameters)
>>> clf.fit(iris.data, iris.target)
GridSearchCV(estimator=SVC(),
            param_grid={'C': [1, 10], 'kernel': ('linear', 'rbf')})
```

(continues on next page)
Methods

- **decision_function**(*X*)
  
  Call decision_function on the estimator with the best found parameters.

- **fit**(*X*, *y*, *groups*)
  
  Run fit with all sets of parameters.

- **get_params**(deep)
  
  Get parameters for this estimator.

- **inverse_transform**(*Xt*)
  
  Call inverse_transform on the estimator with the best found params.

- **predict**(*X*)
  
  Call predict on the estimator with the best found parameters.

- **predict_log_proba**(*X*)
  
  Call predict_log_proba on the estimator with the best found parameters.

- **predict_proba**(*X*)
  
  Call predict_proba on the estimator with the best found parameters.

- **score**(*X*, *y*)
  
  Returns the score on the given data, if the estimator has been refit.

- **score_samples**(*X*)
  
  Call score_samples on the estimator with the best found parameters.

- **set_params**(**params)
  
  Set the parameters of this estimator.

- **transform**(*X*)
  
  Call transform on the estimator with the best found parameters.

**decision_function**(*X*)

Call decision_function on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports decision_function.

**Parameters**

- **X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**fit**(*X*, *y*=None, *groups*=None, **fit_params*)

Run fit with all sets of parameters.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

- **y** [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

- **groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

- ****fit_params** [dict of str -> object] Parameters passed to the fit method of the estimator.
**get_params** *(deep=True)*
Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**inverse_transform** *(Xt)*
Call inverse_transform on the estimator with the best found params.
Only available if the underlying estimator implements inverse_transform and refit=True.

Parameters

**Xt** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict** *(X)*
Call predict on the estimator with the best found parameters.
Only available if refit=True and the underlying estimator supports predict.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict_log_proba** *(X)*
Call predict_log_proba on the estimator with the best found parameters.
Only available if refit=True and the underlying estimator supports predict_log_proba.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict_proba** *(X)*
Call predict_proba on the estimator with the best found parameters.
Only available if refit=True and the underlying estimator supports predict_proba.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**score** *(X, y=None)*
Returns the score on the given data, if the estimator has been refit.
This uses the score defined by scoring where provided, and the best_estimator_.score method otherwise.

Parameters

**X** [array-like of shape (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

**y** [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

Returns
score [float]

```python
score_samples(X)
```
Call score_samples on the estimator with the best found parameters.
Only available if refit=True and the underlying estimator supports score_samples.
New in version 0.24.

Parameters

- **X** [iterable] Data to predict on. Must fulfill input requirements of the underlying estimator.

Returns

- **y_score** [ndarray of shape (n_samples,)]

```python
set_params(**params)
```
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

- **params** [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

```python
transform(X)
```
Call transform on the estimator with the best found parameters.
Only available if the underlying estimator supports transform and refit=True.

Parameters

- **X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

Examples using `sklearn.model_selection.GridSearchCV`

- Sample pipeline for text feature extraction and evaluation

```python
sklearn.model_selection.HalvingGridSearchCV
```

7.26. `sklearn.model_selection`: Model Selection

Search over specified parameter values with successive halving.

The search strategy starts evaluating all the candidates with a small amount of resources and iteratively selects the best candidates, using more and more resources.
Read more in the User guide.

**Note:** This estimator is still experimental for now: the predictions and the API might change without any deprecation cycle. To use it, you need to explicitly import `enable_halving_search_cv`:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_halving_search_cv # noqa
>>> # now you can import normally from model_selection
>>> from sklearn.model_selection import HalvingGridSearchCV
```

**Parameters**

- **estimator** [estimator object.] This is assumed to implement the scikit-learn estimator interface. Either estimator needs to provide a `score` function, or `scoring` must be passed.

- **param_grid** [dict or list of dictionaries] Dictionary with parameters names (string) as keys and lists of parameter settings to try as values, or a list of such dictionaries, in which case the grids spanned by each dictionary in the list are explored. This enables searching over any sequence of parameter settings.

- **factor** [int or float, default=3] The ‘halving’ parameter, which determines the proportion of candidates that are selected for each subsequent iteration. For example, `factor=3` means that only one third of the candidates are selected.

- **resource** [‘n_samples’ or str, default=‘n_samples’] Defines the resource that increases with each iteration. By default, the resource is the number of samples. It can also be set to any parameter of the base estimator that accepts positive integer values, e.g. ‘n_iterations’ or ‘n_estimators’ for a gradient boosting estimator. In this case `max_resources` cannot be ‘auto’ and must be set explicitly.

- **max_resources** [int, default=’auto’] The maximum amount of resource that any candidate is allowed to use for a given iteration. By default, this is set to `n_samples` when `resource=’n_samples’` (default), else an error is raised.

- **min_resources** [‘exhaust’, ‘smallest’] or int, default=’exhaust’] The minimum amount of resource that any candidate is allowed to use for a given iteration. Equivalently, this defines the amount of resources `r0` that are allocated for each candidate at the first iteration.
  - ‘smallest’ is a heuristic that sets `r0` to a small value:
    - `n_splits * 2` when `resource=’n_samples’` for a regression problem
    - `n_classes * n_splits * 2` when `resource=’n_samples’` for a classification problem
    - `1` when `resource != ’n_samples’`
  - ‘exhaust’ will set `r0` such that the last iteration uses as much resources as possible. Namely, the last iteration will use the highest value smaller than `max_resources` that is a multiple of both `min_resources` and `factor`. In general, using ‘exhaust’ leads to a more accurate estimator, but is slightly more time consuming.

Note that the amount of resources used at each iteration is always a multiple of `min_resources`.

- **aggressive_elimination** [bool, default=False] This is only relevant in cases where there isn’t enough resources to reduce the remaining candidates to at most `factor` after the last iteration. If `True`, then the search process will ‘replay’ the first iteration for as long as needed until the number of candidates is small enough. This is `False` by default, which means that
the last iteration may evaluate more than factor candidates. See Aggressive elimination of candidates for more details.

cv [int, cross-validation generator or iterable, default=5] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- integer, to specify the number of folds in a (Stratified)KFold,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if the estimator is a classifier and $y$ is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Note: Due to implementation details, the folds produced by cv must be the same across multiple calls to cv.split(). For built-in scikit-learn iterators, this can be achieved by deactivating shuffling (shuffle=False), or by setting the cv’s random_state parameter to an integer.

scoring [string, callable, or None, default=None] A single string (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set. If None, the estimator’s score method is used.

refit [bool, default=True] If True, refit an estimator using the best found parameters on the whole dataset.

The refitted estimator is made available at the best_estimator_ attribute and permits using predict directly on this GridSearchCV instance.

error_score ['raise' or numeric] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised. This parameter does not affect the refit step, which will always raise the error. Default is np.nan

return_train_score [bool, default=False] If False, the cv_results_ attribute will not include training scores. Computing training scores is used to get insights on how different parameter settings impact the overfitting/underfitting trade-off. However computing the scores on the training set can be computationally expensive and is not strictly required to select the parameters that yield the best generalization performance.

random_state [int, RandomState instance or None, default=None] Pseudo random number generator state used for subsampling the dataset when resources != 'n_samples'. Ignored otherwise. Pass an int for reproducible output across multiple function calls. See Glossary.

n_jobs [int or None, default=None] Number of jobs to run in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [int] Controls the verbosity: the higher, the more messages.

Attributes

n_resources_ [list of int] The amount of resources used at each iteration.

n_candidates_ [list of int] The number of candidate parameters that were evaluated at each iteration.
**n_remaining_candidates_** [int] The number of candidate parameters that are left after the last iteration. It corresponds to \( \text{ceil}(n\_\text{candidates}[-1] / \text{factor}) \)

**max_resources_** [int] The maximum number of resources that any candidate is allowed to use for a given iteration. Note that since the number of resources used at each iteration must be a multiple of **min_resources_**, the actual number of resources used at the last iteration may be smaller than **max_resources_**.

**min_resources_** [int] The amount of resources that are allocated for each candidate at the first iteration.

**n_iterations_** [int] The actual number of iterations that were run. This is equal to

\[ n\_\text{iterations} \] if **aggressive_elimination** is True. Else, this is equal to \( \text{min}(n\_\text{possible} \_\text{iterations}, n\_\text{required} \_\text{iterations}) \).

**n_possible_iterations_** [int] The number of iterations that are possible starting with **min_resources_** resources and without exceeding **max_resources_**.

**n_required_iterations_** [int] The number of iterations that are required to end up with less than \( \text{factor} \) candidates at the last iteration, starting with **min_resources_** resources. This will be smaller than **n_possible_iterations_** when there isn’t enough resources.

**cv_results_** [dict of numpy (masked) ndarrays] A dict with keys as column headers and values as columns, that can be imported into a pandas DataFrame. It contains many informations for analysing the results of a search. Please refer to the User guide for details.

**best_estimator_** [estimator or dict] Estimator that was chosen by the search, i.e. estimator which gave highest score (or smallest loss if specified) on the left out data. Not available if **refit=False**.

**best_score_** [float] Mean cross-validated score of the best estimator.

**best_params_** [dict] Parameter setting that gave the best results on the hold out data.

**best_index_** [int] The index (of the cv_results_ arrays) which corresponds to the best candidate parameter setting.

The dict at `search.cv_results_['params'][search.best_index_]` gives the parameter setting for the best model, that gives the highest mean score (`search.best_score_`).

**scorer_** [function or a dict] Scorer function used on the held out data to choose the best parameters for the model.

**n_splits_** [int] The number of cross-validation splits (folds/iterations).

**refit_time_** [float] Seconds used for refitting the best model on the whole dataset.

This is present only if **refit** is not False.

See also:

*HalvingRandomSearchCV* Random search over a set of parameters using successive halving.
Notes

The parameters selected are those that maximize the score of the held-out data, according to the scoring parameter.

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.experimental import enable_halving_search_cv # noqa
>>> from sklearn.model_selection import HalvingGridSearchCV
... >>> X, y = load_iris(return_X_y=True)
>>> clf = RandomForestClassifier(random_state=0)
... >>> param_grid = {"max_depth": [3, None],
... "min_samples_split": [5, 10]}
>>> search = HalvingGridSearchCV(clf, param_grid, resource='n_estimators',
... max_resources=10,
... random_state=0).fit(X, y)
>>> search.best_params_
{'max_depth': None, 'min_samples_split': 10, 'n_estimators': 9}
```

Methods

- `decision_function(X)`
  - Call decision_function on the estimator with the best found parameters.
- `fit(X[, y, groups])`
  - Run fit with all sets of parameters.
- `get_params([deep])`
  - Get parameters for this estimator.
- `inverse_transform(Xt)`
  - Call inverse_transform on the estimator with the best found params.
- `predict(X)`
  - Call predict on the estimator with the best found parameters.
- `predict_log_proba(X)`
  - Call predict_log_proba on the estimator with the best found parameters.
- `predict_proba(X)`
  - Call predict_proba on the estimator with the best found parameters.
- `score(X[, y])`
  - Returns the score on the given data, if the estimator has been refit.
- `score_samples(X)`
  - Call score_samples on the estimator with the best found parameters.
- `set_params(**params)`
  - Set the parameters of this estimator.
- `transform(X)`
  - Call transform on the estimator with the best found parameters.

- `decision_function(X)`
  - Call decision_function on the estimator with the best found parameters.
  - Only available if `refit=True` and the underlying estimator supports `decision_function`.

Parameters

- `X` [indexable, length n_samples] Must fulfill the input assumptions of the underlying esti-
fit (X, y=None, groups=None, **fit_params)

Run fit with all sets of parameters.

Parameters

X [array-like, shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

y [array-like, shape (n_samples,) or (n_samples, n_output), optional] Target relative to X for classification or regression; None for unsupervised learning.

groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

**fit_params [dict of string -> object] Parameters passed to the fit method of the estimator

get_params (deep=True)

Get parameters for this estimator.

Parameters

dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform (Xt)

Call inverse_transform on the estimator with the best found params.

Only available if the underlying estimator implements inverse_transform and refit=True.

Parameters

Xt [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict (X)

Call predict on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict.

Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict_log_proba (X)

Call predict_log_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_log_proba.

Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict_proba (X)

Call predict_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_proba.
Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

score (X, y=None)

Returns the score on the given data, if the estimator has been refit.

This uses the score defined by scoring where provided, and the best estimator_.score method otherwise.

Parameters

X [array-like of shape (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

Returns

score [float]

score_samples (X)

Call score_samples on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports score_samples.

New in version 0.24.

Parameters

X [iterable] Data to predict on. Must fulfill input requirements of the underlying estimator.

Returns

y_score [ndarray of shape (n_samples,)]

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Call transform on the estimator with the best found parameters.

Only available if the underlying estimator supports transform and refit=True.

Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.
Examples using `sklearn.model_selection.HalvingGridSearchCV`

- Release Highlights for scikit-learn 0.24
- Successive Halving Iterations
- Comparison between grid search and successive halving

`sklearn.model_selection.ParameterGrid`

class `sklearn.model_selection.ParameterGrid(param_grid)`

Grid of parameters with a discrete number of values for each.

Can be used to iterate over parameter value combinations with the Python built-in function `iter`. The order of the generated parameter combinations is deterministic.

Read more in the User Guide.

Parameters

- `param_grid` [dict of str to sequence, or sequence of such] The parameter grid to explore, as a dictionary mapping estimator parameters to sequences of allowed values.

  An empty dict signifies default parameters.

  A sequence of dicts signifies a sequence of grids to search, and is useful to avoid exploring parameter combinations that make no sense or have no effect. See the examples below.

See also:

- `GridSearchCV` Uses `ParameterGrid` to perform a full parallelized parameter search.

Examples

```python
>>> from sklearn.model_selection import ParameterGrid
>>> param_grid = {'a': [1, 2], 'b': [True, False]}
>>> list(ParameterGrid(param_grid)) == (...
)... [{'a': 1, 'b': True}, {'a': 1, 'b': False},
... {'a': 2, 'b': True}, {'a': 2, 'b': False}]
True

>>> grid = [{'kernel': ['linear']}, {'kernel': ['rbf'], 'gamma': [1, 10]}]
>>> list(ParameterGrid(grid)) == [{'kernel': 'linear'},
... {'kernel': 'rbf', 'gamma': 1},
... {'kernel': 'rbf', 'gamma': 10}]
True
>>> ParameterGrid(grid)[1] == {'kernel': 'rbf', 'gamma': 1}
True
```
class sklearn.model_selection.ParameterSampler(param_distributions, n_iter, *, random_state=None)

Generator on parameters sampled from given distributions. Non-deterministic iterable over random candidate combinations for hyper-parameter search. If all parameters are presented as a list, sampling without replacement is performed. If at least one parameter is given as a distribution, sampling with replacement is used. It is highly recommended to use continuous distributions for continuous parameters.

Read more in the User Guide.

Parameters

- **param_distributions** [dict] Dictionary with parameters names (str) as keys and distributions or lists of parameters to try. Distributions must provide a rvs method for sampling (such as those from scipy.stats.distributions). If a list is given, it is sampled uniformly. If a list of dicts is given, first a dict is sampled uniformly, and then a parameter is sampled using that dict as above.
- **n_iter** [int] Number of parameter settings that are produced.
- **random_state** [int, RandomState instance or None, default=None] Pseudo random number generator state used for random uniform sampling from lists of possible values instead of scipy.stats distributions. Pass an int for reproducible output across multiple function calls. See Glossary.

Returns

- **params** [dict of str to any] Yields dictionaries mapping each estimator parameter to as sampled value.

Examples

```python
>>> from sklearn.model_selection import ParameterSampler
>>> from scipy.stats.distributions import expon
>>> import numpy as np

>>> rng = np.random.RandomState(0)
>>> param_grid = {'a':[1, 2], 'b': expon()}
>>> param_list = list(ParameterSampler(param_grid, n_iter=4, random_state=rng))
>>> rounded_list = [{k: round(v, 6) for k, v in d.items()} for d in param_list]
>>> rounded_list == [{b: 0.89856, a: 1}, {b: 0.923223, a: 1}, {b: 1.878964, a: 2}, {b: 1.038159, a: 2}]
True
```
Randomized search on hyper parameters.

RandomizedSearchCV implements a “fit” and a “score” method. It also implements “score_samples”, “predict”, “predict_proba”, “decision_function”, “transform” and “inverse_transform” if they are implemented in the estimator used.

The parameters of the estimator used to apply these methods are optimized by cross-validated search over parameter settings.

In contrast to GridSearchCV, not all parameter values are tried out, but rather a fixed number of parameter settings is sampled from the specified distributions. The number of parameter settings that are tried is given by `n_iter`.

If all parameters are presented as a list, sampling without replacement is performed. If at least one parameter is given as a distribution, sampling with replacement is used. It is highly recommended to use continuous distributions for continuous parameters.

Read more in the User Guide.

New in version 0.14.

Parameters

- **estimator** [estimator object.] A object of that type is instantiated for each grid point. This is assumed to implement the scikit-learn estimator interface. Either estimator needs to provide a `score` function, or `scoring` must be passed.

- **param_distributions** [dict or list of dicts] Dictionary with parameters names (str) as keys and distributions or lists of parameters to try. Distributions must provide a `rvs` method for sampling (such as those from scipy.stats.distributions). If a list is given, it is sampled uniformly. If a list of dicts is given, first a dict is sampled uniformly, and then a parameter is sampled using that dict as above.

- **n_iter** [int, default=10] Number of parameter settings that are sampled. `n_iter` trades off runtime vs quality of the solution.

- **scoring** [str, callable, list/tuple or dict, default=None] A single str (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set.

For evaluating multiple metrics, either give a list of (unique) strings or a dict with names as keys and callables as values.

NOTE that when using custom scorers, each scorer should return a single value. Metric functions returning a list/array of values can be wrapped into multiple scorers that return one value each.

See Specifying multiple metrics for evaluation for an example.

If None, the estimator’s score method is used.
n_jobs [int, default=None] Number of jobs to run in parallel. None means 1 unless in a 
joblib.parallel_backend context. -1 means using all processors. See Glossary 
for more details.

Changed in version v0.20: n_jobs default changed from 1 to None

pre_dispatch [int, or str, default=None] Controls the number of jobs that get dispatched during parallel execution. Reducing this number can be useful to avoid an explosion of memory consumption when more jobs get dispatched than CPUs can process. This parameter can be:

- None, in which case all the jobs are immediately created and spawned. Use this for lightweight and fast-running jobs, to avoid delays due to on-demand spawning of the jobs
- An int, giving the exact number of total jobs that are spawned
- A str, giving an expression as a function of n_jobs, as in ’2*n_jobs’

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross validation,
- integer, to specify the number of folds in a (Stratified)KFold,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

refit [bool, str, or callable, default=True] Refit an estimator using the best found parameters on 
the whole dataset.

For multiple metric evaluation, this needs to be a str denoting the scorer that would be used to find the best parameters for refitting the estimator at the end.

Where there are considerations other than maximum score in choosing a best estimator, refit can be set to a function which returns the selected best_index_ given the cv_results. In that case, the best_estimator_ and best_params_ will be set according to the returned best_index_ while the best_score_ attribute will not be available.

The refitted estimator is made available at the best_estimator_ attribute and permits using predict directly on this RandomizedSearchCV instance.

Also for multiple metric evaluation, the attributes best_index_, best_score_ and best_params_ will only be available if refit is set and all of them will be determined w.r.t this specific scorer.

See scoring parameter to know more about multiple metric evaluation.

Changed in version 0.20: Support for callable added.

verbose [int] Controls the verbosity: the higher, the more messages.

random_state [int, RandomState instance or None, default=None] Pseudo random number 
generator state used for random uniform sampling from lists of possible values instead of scipy.stats distributions. Pass an int for reproducible output across multiple function calls. See Glossary.
**error_score** ['raise' or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to 'raise', the error is raised. If a numeric value is given, FitFailedWarning is raised. This parameter does not affect the refit step, which will always raise the error.

**return_train_score** [bool, default=False] If False, the cv_results_ attribute will not include training scores. Computing training scores is used to get insights on how different parameter settings impact the overfitting/underfitting trade-off. However computing the scores on the training set can be computationally expensive and is not strictly required to select the parameters that yield the best generalization performance.

New in version 0.19.

Changed in version 0.21: Default value was changed from True to False

**Attributes**

**cv_results_** [dict of numpy (masked) ndarrays] A dict with keys as column headers and values as columns, that can be imported into a pandas DataFrame.

For instance the below given table

<table>
<thead>
<tr>
<th>param_kernel</th>
<th>param_gamma</th>
<th>split0_test_score</th>
<th>...</th>
<th>rank_test_score</th>
</tr>
</thead>
<tbody>
<tr>
<td>'rbf'</td>
<td>0.1</td>
<td>0.80</td>
<td></td>
<td></td>
</tr>
<tr>
<td>'rbf'</td>
<td>0.2</td>
<td>0.84</td>
<td></td>
<td>3</td>
</tr>
<tr>
<td>'rbf'</td>
<td>0.3</td>
<td>0.70</td>
<td></td>
<td>2</td>
</tr>
</tbody>
</table>

will be represented by a cv_results_ dict of:

```python
{
    'param_kernel' : masked_array(data = ['rbf', 'rbf', 'rbf'], mask = False),
    'param_gamma'   : masked_array(data = [0.1 0.2 0.3], mask = False),
    'split0_test_score' : [0.80, 0.84, 0.70],
    'split1_test_score' : [0.82, 0.50, 0.70],
    'mean_test_score' : [0.81, 0.67, 0.70],
    'std_test_score' : [0.01, 0.24, 0.00],
    'rank_test_score' : [1, 3, 2],
    'split0_train_score' : [0.80, 0.92, 0.70],
    'split1_train_score' : [0.82, 0.55, 0.70],
    'mean_train_score' : [0.81, 0.74, 0.70],
    'std_train_score' : [0.01, 0.19, 0.00],
    'mean_fit_time' : [0.73, 0.63, 0.43],
    'std_fit_time' : [0.01, 0.02, 0.01],
    'mean_score_time' : [0.01, 0.06, 0.04],
    'std_score_time' : [0.00, 0.00, 0.00],
    'params' : [{'kernel' : 'rbf', 'gamma' : 0.1}, ...],
}
```

**NOTE**

The key 'params' is used to store a list of parameter settings dicts for all the parameter candidates.

The mean_fit_time, std_fit_time, mean_score_time and std_score_time are all in seconds.

For multi-metric evaluation, the scores for all the scorers are available in the cv_results_ dict at the keys ending with that scorer's name ('_<scorer_name>') instead of '_score' shown above. (‘split0_test_precision’, ‘mean_train_precision’ etc.)
best_estimator_ [estimator] Estimator that was chosen by the search, i.e. estimator which gave highest score (or smallest loss if specified) on the left out data. Not available if refit=False.

For multi-metric evaluation, this attribute is present only if refit is specified.
See refit parameter for more information on allowed values.

best_score_ [float] Mean cross-validated score of the best_estimator.

For multi-metric evaluation, this is not available if refit is False. See refit parameter for more information.
This attribute is not available if refit is a function.

best_params_ [dict] Parameter setting that gave the best results on the hold out data.

For multi-metric evaluation, this is not available if refit is False. See refit parameter for more information.

best_index_ [int] The index (of the cv_results_ arrays) which corresponds to the best candidate parameter setting.

The dict at search.cv_results_['params'][search.best_index_] gives the parameter setting for the best model, that gives the highest mean score (search.best_score_).

For multi-metric evaluation, this is not available if refit is False. See refit parameter for more information.

scorer_ [function or a dict] Scorer function used on the held out data to choose the best parameters for the model.

For multi-metric evaluation, this attribute holds the validated scoring dict which maps the scorer key to the scorer callable.

n_splits_ [int] The number of cross-validation splits (folds/iterations).

refit_time_ [float] Seconds used for refitting the best model on the whole dataset.
This is present only if refit is not False.
New in version 0.20.

multimetric_ [bool] Whether or not the scorers compute several metrics.

See also:

GridSearchCV Does exhaustive search over a grid of parameters.

ParameterSampler A generator over parameter settings, constructed from param_distributions.

Notes

The parameters selected are those that maximize the score of the held-out data, according to the scoring parameter.
If n_jobs was set to a value higher than one, the data is copied for each parameter setting (and not n_jobs times). This is done for efficiency reasons if individual jobs take very little time, but may raise errors if the dataset is large and not enough memory is available. A workaround in this case is to set pre_dispatch. Then, the memory is copied only pre_dispatch many times. A reasonable value for pre_dispatch is 2 * n_jobs.
Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.model_selection import RandomizedSearchCV
>>> from scipy.stats import uniform

>>> iris = load_iris()

>>> logistic = LogisticRegression(solver='saga', tol=1e-2, max_iter=200,
...                             random_state=0)

>>> distributions = dict(C=uniform(loc=0, scale=4),
...                        penalty=['l2', 'l1'])

>>> clf = RandomizedSearchCV(logistic, distributions, random_state=0)

>>> search = clf.fit(iris.data, iris.target)

>>> search.best_params_
{'C': 2..., 'penalty': 'l1'}
```

Methods

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<td>decision_function(X)</td>
<td>Call decision_function on the estimator with the best found parameters.</td>
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<tr>
<td>fit(X, y, groups])</td>
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<tr>
<td>inverse_transform(Xt)</td>
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<tr>
<td>predict(X)</td>
<td>Call predict on the estimator with the best found parameters.</td>
</tr>
<tr>
<td>predict_log_proba(X)</td>
<td>Call predict_log_proba on the estimator with the best found parameters.</td>
</tr>
<tr>
<td>predict_proba(X)</td>
<td>Call predict_proba on the estimator with the best found parameters.</td>
</tr>
<tr>
<td>score(X[, y])</td>
<td>Returns the score on the given data, if the estimator has been refit.</td>
</tr>
<tr>
<td>score_samples(X)</td>
<td>Call score_samples on the estimator with the best found parameters.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X)</td>
<td>Call transform on the estimator with the best found parameters.</td>
</tr>
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</table>

**decision_function(X)**

Call decision_function on the estimator with the best found parameters.

Only available if `refit=True` and the underlying estimator supports decision_function.

**Parameters**

- **X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**fit**(X, y=None, *, groups=None, **fit_params)

Run fit with all sets of parameters.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
**y** [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

**groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

**fit_params** [dict of str -> object] Parameters passed to the fit method of the estimator

get_params (**deep=True**) Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

inverse_transform (**Xt**) Call inverse_transform on the estimator with the best found params.

Only available if the underlying estimator implements inverse_transform and refit=True.

Parameters

**Xt** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict (**X**) Call predict on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict_log_proba (**X**) Call predict_log_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_log_proba.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

predict_proba (**X**) Call predict_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_proba.

Parameters

**X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

score (**X**, **y=None**) Returns the score on the given data, if the estimator has been refit.

This uses the score defined by scoring where provided, and the best_estimator_.score method otherwise.
Parameters

X [array-like of shape (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

Returns

score [float]

call score_samples(X)

Call score_samples on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports score_samples.

New in version 0.24.

Parameters

X [iterable] Data to predict on. Must fulfill input requirements of the underlying estimator.

Returns

y_score [ndarray of shape (n_samples,)]

set_params(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform(X)

Call transform on the estimator with the best found parameters.

Only available if the underlying estimator supports transform and refit=True.

Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

Examples using sklearn.model_selection.RandomizedSearchCV

- Release Highlights for scikit-learn 0.24
- Comparing randomized search and grid search for hyperparameter estimation
**sklearn.model_selection.HalvingRandomSearchCV**

class sklearn.model_selection.HalvingRandomSearchCV(estimator, param_distributions, *, n_candidates='exhaust', factor=3, resource='n_samples', max_resources='auto', min_resources='smallest', aggressive_elimination=False, cv=5, scoring=None, refit=True, error_score=nan, return_train_score=True, random_state=None, n_jobs=None, verbose=0)

Randomized search on hyper parameters.

The search strategy starts evaluating all the candidates with a small amount of resources and iteratively selects the best candidates, using more and more resources.

The candidates are sampled at random from the parameter space and the number of sampled candidates is determined by `n_candidates`.

Read more in the **User guide**.

**Note:** This estimator is still **experimental** for now: the predictions and the API might change without any deprecation cycle. To use it, you need to explicitly import `enable_halving_search_cv`:

```python
>>> # explicitly require this experimental feature
>>> from sklearn.experimental import enable_halving_search_cv
>>> # now you can import normally from model_selection
>>> from sklearn.model_selection import HalvingRandomSearchCV
```

**Parameters**

- **estimator** [estimator object.] This is assumed to implement the scikit-learn estimator interface. Either estimator needs to provide a `score` function, or `scoring` must be passed.

- **param_distributions** [dict] Dictionary with parameters names (string) as keys and distributions or lists of parameters to try. Distributions must provide a `rvs` method for sampling (such as those from scipy.stats.distributions). If a list is given, it is sampled uniformly.

- **n_candidates** [int, default='exhaust'] The number of candidate parameters to sample, at the first iteration. Using 'exhaust' will sample enough candidates so that the last iteration uses as many resources as possible, based on `min_resources`, `max_resources` and `factor`. In this case, `min_resources` cannot be 'exhaust'.

- **factor** [int or float, default=3] The ‘halving’ parameter, which determines the proportion of candidates that are selected for each subsequent iteration. For example, `factor=3` means that only one third of the candidates are selected.

- **resource** [‘n_samples’ or str, default=’n_samples’] Defines the resource that increases with each iteration. By default, the resource is the number of samples. It can also be set to any parameter of the base estimator that accepts positive integer values, e.g. ‘n_iterations’ or ‘n_estimators’ for a gradient boosting estimator. In this case `max_resources` cannot be ‘auto’ and must be set explicitly.

- **max_resources** [int, default=’auto’] The maximum number of resources that any candidate is allowed to use for a given iteration. By default, this is set `n_samples` when
resource='n_samples' (default), else an error is raised.

**min_resources** ['exhaust', 'smallest'] or int, default='smallest'] The minimum amount of resource that any candidate is allowed to use for a given iteration. Equivalently, this defines the amount of resources \( r_0 \) that are allocated for each candidate at the first iteration.

- **smallest** is a heuristic that sets \( r_0 \) to a small value:
  - \( n \_splits \times 2 \) when resource='n_samples' for a regression problem
  - \( n \_classes \times n \_splits \times 2 \) when resource='n_samples' for a classification problem
  - 1 when resource != 'n_samples'

- **exhaust** will set \( r_0 \) such that the last iteration uses as much resources as possible. Namely, the last iteration will use the highest value smaller than max_resources that is a multiple of both min_resources and factor. In general, using 'exhaust' leads to a more accurate estimator, but is slightly more time consuming. 'exhaust' isn’t available when n_candidates='exhaust'.

Note that the amount of resources used at each iteration is always a multiple of min_resources.

**aggressive_elimination** [bool, default=False] This is only relevant in cases where there isn’t enough resources to reduce the remaining candidates to at most factor after the last iteration. If True, then the search process will ‘replay’ the first iteration for as long as needed until the number of candidates is small enough. This is False by default, which means that the last iteration may evaluate more than factor candidates. See Aggressive elimination of candidates for more details.

**cv** [int, cross-validation generator or an iterable, default=5] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- integer, to specify the number of folds in a (Stratified)KFold,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For integer/None inputs, if the estimator is a classifier and \( y \) is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

**Note:** Due to implementation details, the folds produced by cv must be the same across multiple calls to cv.split(). For built-in scikit-learn iterators, this can be achieved by deactivating shuffling (shuffle=False), or by setting the cv's random_state parameter to an integer.

**scoring** [string, callable, or None, default=None] A single string (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set. If None, the estimator’s score method is used.

**refit** [bool, default=True] If True, refit an estimator using the best found parameters on the whole dataset.

The refitted estimator is made available at the best_estimator_ attribute and permits using predict directly on this GridSearchCV instance.
error_score ['raise' or numeric] Value to assign to the score if an error occurs in estimator fitting. If set to 'raise', the error is raised. If a numeric value is given, FitFailedWarning is raised. This parameter does not affect the refit step, which will always raise the error. Default is np.nan.

return_train_score [bool, default=False] If False, the cv_results_ attribute will not include training scores. Computing training scores is used to get insights on how different parameter settings impact the overfitting/underfitting trade-off. However computing the scores on the training set can be computationally expensive and is not strictly required to select the parameters that yield the best generalization performance.

random_state [int, RandomState instance or None, default=None] Pseudo random number generator state used for subsampling the dataset when resources != 'n_samples'. Also used for random uniform sampling from lists of possible values instead of scipy.stats distributions. Pass an int for reproducible output across multiple function calls. See Glossary.

n_jobs [int or None, default=None] Number of jobs to run in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [int] Controls the verbosity: the higher, the more messages.

Attributes

n_resources_ [list of int] The amount of resources used at each iteration.

n_candidates_ [list of int] The number of candidate parameters that were evaluated at each iteration.

n_remaining_candidates_ [int] The number of candidate parameters that are left after the last iteration. It corresponds to ceil(n_candidates[-1] / factor)

max_resources_ [int] The maximum number of resources that any candidate is allowed to use for a given iteration. Note that since the number of resources used at each iteration must be a multiple of min_resources_, the actual number of resources used at the last iteration may be smaller than max_resources_.

min_resources_ [int] The amount of resources that are allocated for each candidate at the first iteration.

n_iterations_ [int] The actual number of iterations that were run. This is equal to n_required_iterations_ if aggressive_elimination is True. Else, this is equal to min(n_possible_iterations_, n_required_iterations_).

n_possible_iterations_ [int] The number of iterations that are possible starting with min_resources_ resources and without exceeding max_resources_.

n_required_iterations_ [int] The number of iterations that are required to end up with less than factor candidates at the last iteration, starting with min_resources_ resources. This will be smaller than n_possible_iterations_ when there isn’t enough resources.

cv_results_ [dict of numpy (masked) ndarrays] A dict with keys as column headers and values as columns, that can be imported into a pandas DataFrame. It contains many informations for analysing the results of a search. Please refer to the User guide for details.

best_estimator_ [estimator or dict] Estimator that was chosen by the search, i.e. estimator which gave highest score (or smallest loss if specified) on the left out data. Not available if refit=False.

best_score_ [float] Mean cross-validated score of the best_estimator.
best_params_ [dict] Parameter setting that gave the best results on the hold out data.

best_index_ [int] The index (of the cv_results_ arrays) which corresponds to the best candidate parameter setting.

The dict at search.cv_results_['params'][search.best_index_] gives the parameter setting for the best model, that gives the highest mean score (search.best_score_).

scorer_ [function or a dict] Scorer function used on the held out data to choose the best parameters for the model.

n_splits_ [int] The number of cross-validation splits (folds/iterations).

refit_time_ [float] Seconds used for refitting the best model on the whole dataset.

This is present only if refit is not False.

See also:

HalvingGridSearchCV Search over a grid of parameters using successive halving.

Notes

The parameters selected are those that maximize the score of the held-out data, according to the scoring parameter.

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.experimental import enable_halving_search_cv  # noqa
>>> from sklearn.model_selection import HalvingRandomSearchCV
>>> from scipy.stats import randint
...
>>> X, y = load_iris(return_X_y=True)
>>> clf = RandomForestClassifier(random_state=0)
>>> np.random.seed(0)
...
>>> param_distributions = {
...    "max_depth": [3, None],
...    "min_samples_split": randint(2, 11)
...}
>>> search = HalvingRandomSearchCV(clf, param_distributions,
...                                  resource='n_estimators',
...                                  max_resources=10,
...                                  random_state=0).fit(X, y)
>>> search.best_params_  
{'max_depth': None, 'min_samples_split': 10, 'n_estimators': 9}
```
## Methods

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<tr>
<td><code>fit(X[, y, groups])</code></td>
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<td>Get parameters for this estimator.</td>
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<td><code>inverse_transform(Xt)</code></td>
<td>Call <code>inverse_transform</code> on the estimator with the best found params.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Call <code>predict</code> on the estimator with the best found parameters.</td>
</tr>
<tr>
<td><code>predict_log_proba(X)</code></td>
<td>Call <code>predict_log_proba</code> on the estimator with the best found parameters.</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Call <code>predict_proba</code> on the estimator with the best found parameters.</td>
</tr>
<tr>
<td><code>score(X[, y])</code></td>
<td>Returns the score on the given data, if the estimator has been refit.</td>
</tr>
<tr>
<td><code>score_samples(X)</code></td>
<td>Call <code>score_samples</code> on the estimator with the best found parameters.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Call <code>transform</code> on the estimator with the best found parameters.</td>
</tr>
</tbody>
</table>

### `decision_function(X)`
Call `decision_function` on the estimator with the best found parameters.

Only available if `refit=True` and the underlying estimator supports `decision_function`.

#### Parameters
- **X** [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

### `fit(X[, y, groups])`
Run fit with all sets of parameters.

#### Parameters
- **X** [array-like, shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like, shape (n_samples,) or (n_samples, n_output), optional] Target relative to X for classification or regression; None for unsupervised learning.
- **groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., `GroupKFold`).
- ****fit_params** [dict of string -> object] Parameters passed to the `fit` method of the estimator

### `get_params`(deep=True)
Get parameters for this estimator.

#### Parameters
- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

### Returns
params [dict] Parameter names mapped to their values.

**inverse_transform**(*X*)
Call inverse_transform on the estimator with the best found params.

Only available if the underlying estimator implements inverse_transform and refit=True.

**Parameters**

* X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict**(*X*)
Call predict on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict.

**Parameters**

* X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict_log_proba**(*X*)
Call predict_log_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_log_proba.

**Parameters**

* X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**predict_proba**(*X*)
Call predict_proba on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports predict_proba.

**Parameters**

* X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

**score**(*X*, y=None)
Returns the score on the given data, if the estimator has been refit.

This uses the score defined by scoring where provided, and the best_estimator_.score method otherwise.

**Parameters**

* X [array-like of shape (n_samples, n_features)] Input data, where n_samples is the number of samples and n_features is the number of features.

* y [array-like of shape (n_samples, n_output) or (n_samples,), default=None] Target relative to X for classification or regression; None for unsupervised learning.

**Returns**

* score [float]

**score_samples**(*X*)
Call score_samples on the estimator with the best found parameters.

Only available if refit=True and the underlying estimator supports score_samples.

New in version 0.24.
Parameters

X [iterable] Data to predict on. Must fulfill input requirements of the underlying estimator.

Returns

y_score [ndarray of shape (n_samples,)]

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Call transform on the estimator with the best found parameters.

Only available if the underlying estimator supports transform and refit=True.

Parameters

X [indexable, length n_samples] Must fulfill the input assumptions of the underlying estimator.

Examples using sklearn.model_selection.HalvingRandomSearchCV

- Release Highlights for scikit-learn 0.24
- Successive Halving Iterations

7.26.4 Model validation

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<td>Evaluate metric(s) by cross-validation and also record fit/score times.</td>
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<tr>
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<td>model_selection.</td>
<td>Evaluate the significance of a cross-validated score with permutations</td>
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<tr>
<td>cross_val_score(estimator, X)</td>
<td>Validation curve.</td>
</tr>
<tr>
<td>model_selection.</td>
<td></td>
</tr>
<tr>
<td>learning_curve(estimator, X, ...)</td>
<td></td>
</tr>
<tr>
<td>model_selection.</td>
<td></td>
</tr>
<tr>
<td>permutation_test_score(...)</td>
<td></td>
</tr>
<tr>
<td>model_selection.</td>
<td></td>
</tr>
<tr>
<td>validation_curve(estimator, ...)</td>
<td></td>
</tr>
</tbody>
</table>
Evaluate metric(s) by cross-validation and also record fit/score times.

Read more in the User Guide.

Parameters

**estimator** [estimator object implementing ‘fit’] The object to use to fit the data.

**X** [array-like of shape (n_samples, n_features)] The data to fit. Can be for example a list, or an array.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] The target variable to try to predict in the case of supervised learning.

**groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

**scoring** [str, callable, list/tuple, or dict, default=None] A single str (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set.

For evaluating multiple metrics, either give a list of (unique) strings or a dict with names as keys and callables as values.

NOTE that when using custom scorers, each scorer should return a single value. Metric functions returning a list/array of values can be wrapped into multiple scorers that return one value each.

See Specifying multiple metrics for evaluation for an example.

If None, the estimator’s score method is used.

**cv** [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross validation,
- int, to specify the number of folds in a (Stratified)KFold,
- **CV splitter**,
- An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

**n_jobs** [int, default=None] Number of jobs to run in parallel. Training the estimator and computing the score are parallelized over the cross-validation splits. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**verbose** [int, default=0] The verbosity level.
**fit_params** [dict, default=None] Parameters to pass to the fit method of the estimator.

**pre_dispatch** [int or str, default='2*n_jobs'] Controls the number of jobs that get dispatched during parallel execution. Reducing this number can be useful to avoid an explosion of memory consumption when more jobs get dispatched than CPUs can process. This parameter can be:

- None, in which case all the jobs are immediately created and spawned. Use this for lightweight and fast-running jobs, to avoid delays due to on-demand spawning of the jobs
- An int, giving the exact number of total jobs that are spawned
- A str, giving an expression as a function of n_jobs, as in ‘2*n_jobs’

**return_train_score** [bool, default=False] Whether to include train scores. Computing training scores is used to get insights on how different parameter settings impact the overfitting/underfitting trade-off. However computing the scores on the training set can be computationally expensive and is not strictly required to select the parameters that yield the best generalization performance.

New in version 0.19.

Changed in version 0.21: Default value was changed from True to False

**return_estimator** [bool, default=False] Whether to return the estimators fitted on each split.

New in version 0.20.

**error_score** ['raise' or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised.

New in version 0.20.

Returns

**scores** [dict of float arrays of shape (n_splits,)] Array of scores of the estimator for each run of the cross validation.

A dict of arrays containing the score/time arrays for each scorer is returned. The possible keys for this dict are:

- **test_score** The score array for test scores on each cv split. Suffix `_score` in `test_score` changes to a specific metric like `test_r2` or `test_auc` if there are multiple scoring metrics in the scoring parameter.
- **train_score** The score array for train scores on each cv split. Suffix `_score` in `train_score` changes to a specific metric like `train_r2` or `train_auc` if there are multiple scoring metrics in the scoring parameter. This is available only if `return_train_score` parameter is True.
- **fit_time** The time for fitting the estimator on the train set for each cv split.
- **score_time** The time for scoring the estimator on the test set for each cv split. (Note time for scoring on the train set is not included even if `return_train_score` is set to True.
- **estimator** The estimator objects for each cv split. This is available only if `return_estimator` parameter is set to True.

See also:

- **cross_val_score** Run cross-validation for single metric evaluation.
**cross_val_predict**  Get predictions from each split of cross-validation for diagnostic purposes.

**sklearn.metrics.make_scorer**  Make a scorer from a performance metric or loss function.

**Examples**

```python
>>> from sklearn import datasets, linear_model
>>> from sklearn.model_selection import cross_validate
>>> from sklearn.metrics import confusion_matrix
>>> from sklearn.svm import LinearSVC
>>> diabetes = datasets.load_diabetes()
>>> X = diabetes.data[:150]
>>> y = diabetes.target[:150]
>>> lasso = linear_model.Lasso()

Single metric evaluation using `cross_validate`

```python
>>> cv_results = cross_validate(lasso, X, y, cv=3)
>>> sorted(cv_results.keys())
['fit_time', 'score_time', 'test_score']
>>> cv_results['test_score']
array([0.33150734, 0.08022311, 0.03531764])
```

Multiple metric evaluation using `cross_validate` (please refer the `scoring` parameter doc for more information)

```python
>>> scores = cross_validate(lasso, X, y, cv=3,
...     scoring=('r2', 'neg_mean_squared_error'),
...     return_train_score=True)
>>> print(scores['test_neg_mean_squared_error'])
[-3635.5... -3573.3... -6114.7...]
>>> print(scores['train_r2'])
[0.28010158 0.39088426 0.22784852]
```

**Examples using sklearn.model_selection.cross_validate**

- **Categorical Feature Support in Gradient Boosting**
- **Combine predictors using stacking**
- **Common pitfalls in interpretation of coefficients of linear models**

**sklearn.model_selection.cross_val_predict**

The data is split according to the cv parameter. Each sample belongs to exactly one test set, and its prediction is computed with an estimator fitted on the corresponding training set.
Passing these predictions into an evaluation metric may not be a valid way to measure generalization performance. Results can differ from `cross_validate` and `cross_val_score` unless all tests sets have equal size and the metric decomposes over samples.

Read more in the *User Guide*.

**Parameters**

- **estimator** [estimator object implementing ‘fit’ and ‘predict’] The object to use to fit the data.

- **X** [array-like of shape (n_samples, n_features)] The data to fit. Can be, for example a list, or an array at least 2d.

- **y** [array-like of shape (n_samples,), or (n_samples, n_outputs), default=None] The target variable to try to predict in the case of supervised learning.

- **groups** [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” `cv` instance (e.g., `GroupKFold`).

- **cv** [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  - None, to use the default 5-fold cross validation,
  - int, to specify the number of folds in a (Stratified)KFold,
  - `CV splitter`,
  - An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and `y` is either binary or multiclass, `StratifiedKFold` is used. In all other cases, `KFold` is used.

Refer *User Guide* for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

- **n_jobs** [int, default=None] Number of jobs to run in parallel. Training the estimator and predicting are parallelized over the cross-validation splits. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See *Glossary* for more details.

- **verbose** [int, default=0] The verbosity level.

- **fit_params** [dict, default=None] Parameters to pass to the fit method of the estimator.

- **pre_dispatch** [int or str, default='2*n_jobs'] Controls the number of jobs that get dispatched during parallel execution. Reducing this number can be useful to avoid an explosion of memory consumption when more jobs get dispatched than CPUs can process. This parameter can be:
  - None, in which case all the jobs are immediately created and spawned. Use this for lightweight and fast-running jobs, to avoid delays due to on-demand spawning of the jobs
  - An int, giving the exact number of total jobs that are spawned
  - A str, giving an expression as a function of n_jobs, as in ‘2*n_jobs’

- **method** [{'predict', 'predict_proba', 'predict_log_proba', 'decision_function'}, default='predict'] The method to be invoked by estimator.

**Returns**

- **predictions** [ndarray] This is the result of calling method. Shape:
• When method is ‘predict’ and in special case where method is ‘decision_function’ and the target is binary: (n_samples,)
• When method is one of {'predict_proba', 'predict_log_proba', 'decision_function'} (unless special case above): (n_samples, n_classes)
• If estimator is multioutput, an extra dimension ‘n_outputs’ is added to the end of each shape above.

See also:

cross_val_score Calculate score for each CV split.
cross_validate Calculate one or more scores and timings for each CV split.

Notes

In the case that one or more classes are absent in a training portion, a default score needs to be assigned to all instances for that class if method produces columns per class, as in {'decision_function', 'predict_proba', 'predict_log_proba'}. For predict_proba this value is 0. In order to ensure finite output, we approximate negative infinity by the minimum finite float value for the dtype in other cases.

Examples

```python
>>> from sklearn import datasets, linear_model
>>> from sklearn.model_selection import cross_val_predict
>>> diabetes = datasets.load_diabetes()
>>> X = diabetes.data[:150]
>>> y = diabetes.target[:150]
>>> lasso = linear_model.Lasso()
>>> y_pred = cross_val_predict(lasso, X, y, cv=3)
```

Examples using sklearn.model_selection.cross_val_predict

• Combine predictors using stacking
• Plotting Cross-Validated Predictions

sklearn.model_selection.cross_val_score

sklearn.model_selection.cross_val_score(estimator, X, y=None, *, groups=None, scoring=None, cv=None, n_jobs=None, verbose=0, fit_params=None, pre_dispatch='2*n_jobs', error_score=nan)

Evaluate a score by cross-validation

Read more in the User Guide.

Parameters

  estimator [estimator object implementing ‘fit’] The object to use to fit the data.

  X [array-like of shape (n_samples, n_features)] The data to fit. Can be for example a list, or an array.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] The target variable to try to predict in the case of supervised learning.

groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

scoring [str or callable, default=None] A str (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y) which should return only a single value.

Similar to cross_validate but only a single metric is permitted.

If None, the estimator’s default scorer (if available) is used.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

• None, to use the default 5-fold cross validation,

• int, to specify the number of folds in a (Stratified)KFold,

• CV splitter,

• An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

n_jobs [int, default=None] Number of jobs to run in parallel. Training the estimator and computing the score are parallelized over the cross-validation splits. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

verbose [int, default=0] The verbosity level.

fit_params [dict, default=None] Parameters to pass to the fit method of the estimator.

pre_dispatch [int or str, default='2*n_jobs'] Controls the number of jobs that get dispatched during parallel execution. Reducing this number can be useful to avoid an explosion of memory consumption when more jobs get dispatched than CPUs can process. This parameter can be:

• None, in which case all the jobs are immediately created and spawned. Use this for lightweight and fast-running jobs, to avoid delays due to on-demand spawning of the jobs

• An int, giving the exact number of total jobs that are spawned

• A str, giving an expression as a function of n_jobs, as in ‘2*n_jobs’

error_score ['raise' or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised.

New in version 0.20.

Returns

scores [ndarray of float of shape=(len(list(cv)),)] Array of scores of the estimator for each run of the cross validation.

See also:
**cross_validate** To run cross-validation on multiple metrics and also to return train scores, fit times and score times.

**cross_val_predict** Get predictions from each split of cross-validation for diagnostic purposes.

**sklearn.metrics.make_scorer** Make a scorer from a performance metric or loss function.

**Examples**

```python
>>> from sklearn import datasets, linear_model
>>> from sklearn.model_selection import cross_val_score
>>> diabetes = datasets.load_diabetes()
>>> X = diabetes.data[:150]
>>> y = diabetes.target[:150]
>>> lasso = linear_model.Lasso()
>>> print(cross_val_score(lasso, X, y, cv=3))
[0.33150734 0.08022311 0.03531764]
```

**Examples using sklearn.model_selection.cross_val_score**

- Model selection with Probabilistic PCA and Factor Analysis (FA)
- Imputing missing values with variants of IterativeImputer
- Imputing missing values before building an estimator
- Underfitting vs. Overfitting
- Receiver Operating Characteristic (ROC) with cross validation
- Nested versus non-nested cross-validation
- SVM-Anova: SVM with univariate feature selection
- Cross-validation on Digits Dataset Exercise

**sklearn.model_selection.learning_curve**

```python
sklearn.model_selection.learning_curve(estimator, X, y, *, groups=None, train_sizes=array([0.1, 0.33, 0.55, 0.78, 1.0]), cv=None, scoring=None, exploit_incremental_learning=False, n_jobs=None, pre_dispatch='all', verbose=0, shuffle=False, random_state=None, error_score=nan, return_times=False, fit_params=None)
```

Learning curve.

Determines cross-validated training and test scores for different training set sizes.

A cross-validation generator splits the whole dataset k times in training and test data. Subsets of the training set with varying sizes will be used to train the estimator and a score for each training subset size and the test set will be computed. Afterwards, the scores will be averaged over all k runs for each training subset size.

Read more in the User Guide.

**Parameters**

- **estimator** [object type that implements the “fit” and “predict” methods] An object of that type which is cloned for each validation.
X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] Target relative to X for classification or regression; None for unsupervised learning.

groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).

train_sizes [array-like of shape (n_ticks,), default=np.linspace(0.1, 1.0, 5)] Relative or absolute numbers of training examples that will be used to generate the learning curve. If the dtype is float, it is regarded as a fraction of the maximum size of the training set (that is determined by the selected validation method), i.e. it has to be within (0, 1]. Otherwise it is interpreted as absolute sizes of the training sets. Note that for classification the number of samples usually have to be big enough to contain at least one sample from each class.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

- None, to use the default 5-fold cross validation,
- int, to specify the number of folds in a (Stratified)KFold,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

scoring [str or callable, default=None] A str (see model evaluation documentation) or a scorer callable object / function with signature scorer(estimator, X, y).

exploit_incremental_learning [bool, default=False] If the estimator supports incremental learning, this will be used to speed up fitting for different training set sizes.

n_jobs [int, default=None] Number of jobs to run in parallel. Training the estimator and computing the score are parallelized over the different training and test sets. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

pre_dispatch [int or str, default=’all’] Number of predispatched jobs for parallel execution (default is all). The option can reduce the allocated memory. The str can be an expression like ‘2*n_jobs’.

verbose [int, default=0] Controls the verbosity: the higher, the more messages.

shuffle [bool, default=False] Whether to shuffle training data before taking prefixes of it based on “train_sizes”.

random_state [int, RandomState instance or None, default=None] Used when shuffle is True. Pass an int for reproducible output across multiple function calls. See Glossary.

error_score [‘raise’ or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised.

New in version 0.20.
**return_times** [bool, default=False] Whether to return the fit and score times.

**fit_params** [dict, default=None] Parameters to pass to the fit method of the estimator.

    New in version 0.24.

**Returns**

- **train_sizes_abs** [array of shape (n_unique_ticks,)] Numbers of training examples that has been used to generate the learning curve. Note that the number of ticks might be less than n_ticks because duplicate entries will be removed.

- **train_scores** [array of shape (n_ticks, n_cv_folds)] Scores on training sets.

- **test_scores** [array of shape (n_ticks, n_cv_folds)] Scores on test set.

- **fit_times** [array of shape (n_ticks, n_cv_folds)] Times spent for fitting in seconds. Only present if return_times is True.

- **score_times** [array of shape (n_ticks, n_cv_folds)] Times spent for scoring in seconds. Only present if return_times is True.

**Notes**

See examples/model_selection/plot_learning_curve.py

**Examples using sklearn.model_selection.learning_curve**

- *Comparison of kernel ridge regression and SVR*
- *Plotting Learning Curves*

**sklearn.model_selection.permutation_test_score**

```
from sklearn.model_selection import permutation_test_score

def example_permutation_test_score(X, y):
    results = permutation_test_score(
        estimator=svm.SVR(),
        X=X,
        y=y,
        cv=4,
        n_permutations=1000,
        random_state=42
    )
    return results
```

Evaluate the significance of a cross-validated score with permutations

Permutates targets to generate ‘randomized data’ and compute the empirical p-value against the null hypothesis that features and targets are independent.

The p-value represents the fraction of randomized data sets where the estimator performed as well or better than in the original data. A small p-value suggests that there is a real dependency between features and targets which has been used by the estimator to give good predictions. A large p-value may be due to lack of real dependency between features and targets or the estimator was not able to use the dependency to give good predictions.

Read more in the User Guide.

**Parameters**

- **estimator** [estimator object implementing ‘fit’] The object to use to fit the data.

- **X** [array-like of shape at least 2D] The data to fit.

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs) or None] The target variable to try to predict in the case of supervised learning.
groups [array-like of shape (n_samples,), default=None] Labels to constrain permutation within groups, i.e. y values are permuted among samples with the same group identifier. When not specified, y values are permuted among all samples.

When a grouped cross-validator is used, the group labels are also passed on to the split method of the cross-validator. The cross-validator uses them for grouping the samples while splitting the dataset into train/test set.

scoring [str or callable, default=None] A single str (see The scoring parameter: defining model evaluation rules) or a callable (see Defining your scoring strategy from metric functions) to evaluate the predictions on the test set.

If None the estimator’s score method is used.

cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:

• None, to use the default 5-fold cross validation,
• int, to specify the number of folds in a (Stratified)KFold,
• CV splitter,
• An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.

Refer User Guide for the various cross-validation strategies that can be used here.

Changed in version 0.22: cv default value if None changed from 3-fold to 5-fold.

n_permutations [int, default=100] Number of times to permute y.

n_jobs [int, default=None] Number of jobs to run in parallel. Training the estimator and computing the cross-validated score are parallelized over the permutations. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

random_state [int, RandomState instance or None, default=0] Pass an int for reproducible output for permutation of y values among samples. See Glossary.

verbose [int, default=0] The verbosity level.

fit_params [dict, default=None] Parameters to pass to the fit method of the estimator.

New in version 0.24.

Returns

score [float] The true score without permuting targets.

permutation_scores [array of shape (n_permutations,)] The scores obtained for each permutations.

pvalue [float] The p-value, which approximates the probability that the score would be obtained by chance. This is calculated as:

\[
\frac{(C + 1)}{(n\_permutations + 1)}
\]

Where C is the number of permutations whose score >= the true score.

The best possible p-value is 1/(n_permutations + 1), the worst is 1.0.
Notes

This function implements Test 1 in:


Examples using sklearn.model_selection.permutation_test_score

- Test with permutations the significance of a classification score

sklearn.model_selection.validation_curve

sklearn.model_selection.validation_curve(estimator, X, y, *, param_name, param_range, groups=None, cv=None, scoring=None, n_jobs=None, pre_dispatch='all', verbose=0, error_score=nan, fit_params=None)

Validation curve.

Determine training and test scores for varying parameter values.

Compute scores for an estimator with different values of a specified parameter. This is similar to grid search with one parameter. However, this will also compute training scores and is merely a utility for plotting the results.

Read more in the User Guide.

Parameters

- estimator [object type that implements the “fit” and “predict” methods] An object of that type which is cloned for each validation.
- X [array-like of shape (n_samples, n_features)] Training vector, where n_samples is the number of samples and n_features is the number of features.
- y [array-like of shape (n_samples,) or (n_samples, n_outputs) or None] Target relative to X for classification or regression; None for unsupervised learning.
- param_name [str] Name of the parameter that will be varied.
- param_range [array-like of shape (n_values,)] The values of the parameter that will be evaluated.
- groups [array-like of shape (n_samples,), default=None] Group labels for the samples used while splitting the dataset into train/test set. Only used in conjunction with a “Group” cv instance (e.g., GroupKFold).
- cv [int, cross-validation generator or an iterable, default=None] Determines the cross-validation splitting strategy. Possible inputs for cv are:
  • None, to use the default 5-fold cross validation,
  • int, to specify the number of folds in a (Stratified)KFold,
  • CV splitter,
  • An iterable yielding (train, test) splits as arrays of indices.

For int/None inputs, if the estimator is a classifier and y is either binary or multiclass, StratifiedKFold is used. In all other cases, KFold is used.
Refer *User Guide* for the various cross-validation strategies that can be used here.

Changed in version 0.22: `cv` default value if None changed from 3-fold to 5-fold.

**scoring** [str or callable, default=None] A str (see model evaluation documentation) or a scorer callable object / function with signature `scorer(estimator, X, y)`.

**n_jobs** [int, default=None] Number of jobs to run in parallel. Training the estimator and computing the score are parallelized over the combinations of each parameter value and each cross-validation split. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See *Glossary* for more details.

**pre_dispatch** [int or str, default='all'] Number of predispatched jobs for parallel execution (default is all). The option can reduce the allocated memory. The str can be an expression like ‘2*n_jobs’.

**verbose** [int, default=0] Controls the verbosity: the higher, the more messages.

**fit_params** [dict, default=None] Parameters to pass to the fit method of the estimator.

New in version 0.24.

**error_score** ['raise' or numeric, default=np.nan] Value to assign to the score if an error occurs in estimator fitting. If set to ‘raise’, the error is raised. If a numeric value is given, FitFailedWarning is raised.

New in version 0.20.

**Returns**

- **train_scores** [array of shape (n_ticks, n_cv_folds)] Scores on training sets.
- **test_scores** [array of shape (n_ticks, n_cv_folds)] Scores on test set.

**Notes**

See *Plotting Validation Curves*

**Examples using sklearn.model_selection.validation_curve**

- *Plotting Validation Curves*

**7.27 sklearn.multiclass: Multiclass classification**

**7.27.1 Multiclass classification strategies**

This module implements multiclass learning algorithms:

- one-vs-the-rest / one-vs-all
- one-vs-one
- error correcting output codes

The estimators provided in this module are meta-estimators: they require a base estimator to be provided in their constructor. For example, it is possible to use these estimators to turn a binary classifier or a regressor into a multiclass classifier. It is also possible to use these estimators with multiclass estimators in the hope that their accuracy or runtime performance improves.
All classifiers in scikit-learn implement multiclass classification; you only need to use this module if you want to experiment with custom multiclass strategies.

The one-vs-the-rest meta-classifier also implements a `predict_proba` method, so long as such a method is implemented by the base classifier. This method returns probabilities of class membership in both the single label and multilabel case. Note that in the multilabel case, probabilities are the marginal probability that a given sample falls in the given class. As such, in the multilabel case the sum of these probabilities over all possible labels for a given sample will not sum to unity, as they do in the single label case.

User guide: See the Multiclass classification section for further details.

```python
multiclass.OneVsRestClassifier(estimator, *, n_jobs=None)
```

One-vs-the-rest (OvR) multiclass strategy.

Also known as one-vs-all, this strategy consists in fitting one classifier per class. For each classifier, the class is fitted against all the other classes. In addition to its computational efficiency (only `n_classes` classifiers are needed), one advantage of this approach is its interpretability. Since each class is represented by one and only one classifier, it is possible to gain knowledge about the class by inspecting its corresponding classifier. This is the most commonly used strategy for multiclass classification and is a fair default choice.

OneVsRestClassifier can also be used for multilabel classification. To use this feature, provide an indicator matrix for the target `y` when calling `.fit`. In other words, the target labels should be formatted as a 2D binary (0/1) matrix, where `[i, j] == 1` indicates the presence of label `j` in sample `i`. This estimator uses the binary relevance method to perform multilabel classification, which involves training one binary classifier independently for each label.

Read more in the User Guide.

**Parameters**

- `estimator` [estimator object] An estimator object implementing `fit` and one of `decision_function` or `predict_proba`.
- `n_jobs` [int, default=None] The number of jobs to use for the computation: the `n_classes` one-vs-rest problems are computed in parallel.

None means 1 unless in a `joblib.parallel_backend` context. `-1` means using all processors. See Glossary for more details.

Changed in version v0.20: `n_jobs` default changed from 1 to None

**Attributes**

- `estimators_` [list of `n_classes` estimators] Estimators used for predictions.
- `coef_` [ndarray of shape `(1, n_features)` or `(n_classes, n_features)`,] Coefficient of the features in the decision function. This attribute exists only if the `estimators_` defines `coef_`.

Deprecated since version 0.24: This attribute is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). If you use this attribute in `RFE` or `SelectFromModel`, you may
pass a callable to the `importance_getter` parameter that extracts feature importances from `estimators_`.

`intercept_` [ndarray of shape (1, 1) or (n_classes, 1)] If `y` is binary, the shape is (1, 1) else (n_classes, 1) This attribute exists only if the `estimators_` defines `intercept_`.

Deprecated since version 0.24: This attribute is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26). If you use this attribute in `RFE` or `SelectFromModel`, you may pass a callable to the `importance_getter` parameter that extracts feature importances from `estimators_`.

`classes_` [array, shape = [n_classes]] Class labels.

`n_classes_` [int] Number of classes.

`label_binarizer_` [LabelBinarizer object] Object used to transform multiclass labels to binary labels and vice-versa.

`multilabel_` [boolean] Whether this is a multilabel classifier

See also:

`sklearn.multiclass.MultiOutputClassifier` Alternate way of extending an estimator for multilabel classification.

`sklearn.preprocessing.MultiLabelBinarizer` Transform iterable of iterables to binary indicator matrix.

Examples

```python
>>> import numpy as np
>>> from sklearn.multiclass import OneVsRestClassifier
>>> from sklearn.svm import SVC

>>> X = np.array([[10, 10],
                [8, 10],
                [-5, 5.5],
                [-5.4, 5.5],
                [-20, -20],
                [-15, -20]])

>>> y = np.array([0, 0, 1, 1, 2, 2])

>>> clf = OneVsRestClassifier(SVC()).fit(X, y)

>>> clf.predict([[[-19, -20], [9, 9], [-5, 5]])
array([2, 0, 1])
```

Methods

- `decision_function(X)` Returns the distance of each sample from the decision boundary for each class.
- `fit(X, y)` Fit underlying estimators.
- `get_params([deep])` Get parameters for this estimator.
- `partial_fit(X, y[, classes])` Partially fit underlying estimators
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<th>Method</th>
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| `predict(X)`         | Predict multi-class targets using underlying esti-
|                      | mators.                                          |
| `predict_proba(X)`   | Probability estimates.                           |
| `score(X, y[, sample_weight])` | Return the mean accuracy on the given test data and labels. |
| `set_params(**params)` | Set the parameters of this estimator.        |

**`decision_function(X)`**

Returns the distance of each sample from the decision boundary for each class. This can only be used with estimators which implement the decision_function method.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]

**Returns**

- **T** [array-like of shape (n_samples, n_classes) or (n_samples,) for binary classification.]

  Changed in version 0.19: output shape changed to (n_samples,) to conform to scikit-learn conventions for binary classification.

**`fit(X, y)`**

Fit underlying estimators.

**Parameters**

- **X** [(sparse) array-like of shape (n_samples, n_features)] Data.
- **y** [(sparse) array-like of shape (n_samples,) or (n_samples, n_classes)] Multi-class targets. An indicator matrix turns on multilabel classification.

**Returns**

- **self**

**`get_params`(deep=True)**

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**property multilabel_**

Whether this is a multilabel classifier

**`partial_fit(X, y, classes=None)`**

Partially fit underlying estimators.

Should be used when memory is inefficient to train all data. Chunks of data can be passed in several iteration.

**Parameters**

- **X** [(sparse) array-like of shape (n_samples, n_features)] Data.
- **y** [(sparse) array-like of shape (n_samples,) or (n_samples, n_classes)] Multi-class targets. An indicator matrix turns on multilabel classification.
classes [array, shape (n_classes,)] Classes across all calls to partial_fit. Can be obtained via np.unique(y_all), where y_all is the target vector of the entire dataset. This argument is only required in the first call of partial_fit and can be omitted in the subsequent calls.

Returns
self

predict (X)
Predict multi-class targets using underlying estimators.

Parameters
X [(sparse) array-like of shape (n_samples, n_features)] Data.

Returns
y [(sparse) array-like of shape (n_samples,) or (n_samples, n_classes)] Predicted multi-class targets.

predict_proba (X)
Probability estimates.

The returned estimates for all classes are ordered by label of classes.

Note that in the multilabel case, each sample can have any number of labels. This returns the marginal probability that the given sample has the label in question. For example, it is entirely consistent that two labels both have a 90% probability of applying to a given sample.

In the single label multiclass case, the rows of the returned matrix sum to 1.

Parameters
X [array-like of shape (n_samples, n_features)]

Returns
T [(sparse) array-like of shape (n_samples, n_classes)] Returns the probability of the sample for each class in the model, where classes are ordered as they are in self.classes_.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters
X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns
score [float] Mean accuracy of self.predict (X) wrt. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>_<parameter> so that it’s possible to update each component of a nested object.

Parameters
**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.multiclass.OneVsRestClassifier

- Multilabel classification
- Receiver Operating Characteristic (ROC)
- Precision-Recall
- Classifier Chain

7.27.3 sklearn.multiclass.OneVsOneClassifier

class sklearn.multiclass.OneVsOneClassifier(estimator, *, n_jobs=None)

One-vs-one multiclass strategy

This strategy consists in fitting one classifier per class pair. At prediction time, the class which received the most votes is selected. Since it requires to fit \( \frac{n_{classes} \times (n_{classes} - 1)}{2} \) classifiers, this method is usually slower than one-vs-the-rest, due to its \( O(n_{classes}^2) \) complexity. However, this method may be advantageous for algorithms such as kernel algorithms which don’t scale well with \( n_{samples} \). This is because each individual learning problem only involves a small subset of the data whereas, with one-vs-the-rest, the complete dataset is used \( n_{classes} \) times.

Read more in the User Guide.

Parameters

- **estimator** [estimator object] An estimator object implementing fit and one of decision_function or predict_proba.

- **n_jobs** [int, default=None] The number of jobs to use for the computation: the \( n_{classes} \times (n_{classes} - 1) / 2 \) OVO problems are computed in parallel.

  None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

- **estimators_** [list of \( \frac{n_{classes} \times (n_{classes} - 1)}{2} \) estimators] Estimators used for predictions.

- **classes_** [numpy array of shape [n_classes]] Array containing labels.

- **n_classes_** [int] Number of classes

- **pairwise_indices_** [list, length = len(estimators_), or None] Indices of samples used when training the estimators. None when estimator's pairwise tag is False.

  Deprecated since version 0.24: The _pairwise attribute is deprecated in 0.24. From 1.1 (renaming of 0.25) and onward, pairwise_indices_ will use the pairwise estimator tag instead.
Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.multiclass import OneVsOneClassifier
>>> from sklearn.svm import LinearSVC

>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(
...     X, y, test_size=0.33, shuffle=True, random_state=0)
>>> clf = OneVsOneClassifier(LinearSVC(random_state=0)).fit(X_train, y_train)
>>> clf.predict(X_test[:10])
array([2, 1, 0, 2, 0, 2, 0, 1, 1, 1])
```

Methods

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<td>decision_function(X)</td>
<td>Decision function for the OneVsOneClassifier.</td>
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<tr>
<td>fit(X, y)</td>
<td>Fit underlying estimators.</td>
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<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
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<tr>
<td>partial_fit(X, y[, classes])</td>
<td>Partially fit underlying estimators</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Estimate the best class label for each sample in X.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the mean accuracy on the given test data and</td>
</tr>
<tr>
<td></td>
<td>labels.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

**decision_function(X)**

Decision function for the OneVsOneClassifier.

The decision values for the samples are computed by adding the normalized sum of pair-wise classification confidence levels to the votes in order to disambiguate between the decision values when the votes for all the classes are equal leading to a tie.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]

**Returns**

- **Y** [array-like of shape (n_samples, n_classes) or (n_samples,) for binary classification.]

**fit** (X, y)

Fit underlying estimators.

**Parameters**

- **X** [(sparse) array-like of shape (n_samples, n_features)] Data.
- **y** [array-like of shape (n_samples,)] Multi-class targets.

**Returns**

- **self**

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool]
**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**partial_fit** *(X, y, classes=None)*

Partially fit underlying estimators
Should be used when memory is inefficient to train all data. Chunks of data can be passed in several iteration, where the first call should have an array of all target variables.

**Parameters**

- **X** [(sparse) array-like of shape (n_samples, n_features)] Data.
- **y** [array-like of shape (n_samples,)] Multi-class targets.
- **classes** [array, shape (n_classes,)] Classes across all calls to partial_fit. Can be obtained via np.unique(y_all), where y_all is the target vector of the entire dataset. This argument is only required in the first call of partial_fit and can be omitted in the subsequent calls.

**Returns**

**self**

**predict** *(X)*

Estimate the best class label for each sample in X.
This is implemented as argmax(decision_function(X), axis=1) which will return the label of the class with most votes by estimators predicting the outcome of a decision for each possible class pair.

**Parameters**

- **X** [(sparse) array-like of shape (n_samples, n_features)] Data.

**Returns**

**y** [numpy array of shape [n_samples]] Predicted multi-class targets.

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] Mean accuracy of self.predict(X) wrt. y.

**set_params**(**params**)

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>_<parameter> so that it’s possible to update each component of a nested object.
Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.27.4 sklearn.multiclass.OutputCodeClassifier

class sklearn.multiclass.OutputCodeClassifier (estimator, *, code_size=1.5, random_state=None, n_jobs=None)

(Error-Correcting) Output-Code multiclass strategy

Output-code based strategies consist in representing each class with a binary code (an array of 0s and 1s). At fitting time, one binary classifier per bit in the code book is fitted. At prediction time, the classifiers are used to project new points in the class space and the class closest to the points is chosen. The main advantage of these strategies is that the number of classifiers used can be controlled by the user, either for compressing the model ($0 < \text{code\_size} < 1$) or for making the model more robust to errors ($\text{code\_size} > 1$). See the documentation for more details.

Read more in the User Guide.

Parameters

estimator [estimator object] An estimator object implementing `fit` and one of `decision_function` or `predict_proba`.

code_size [float] Percentage of the number of classes to be used to create the code book. A number between 0 and 1 will require fewer classifiers than one-vs-the-rest. A number greater than 1 will require more classifiers than one-vs-the-rest.

random_state [int, RandomState instance, default=None] The generator used to initialize the codebook. Pass an int for reproducible output across multiple function calls. See Glossary.

n_jobs [int, default=None] The number of jobs to use for the computation: the multiclass problems are computed in parallel.

None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details.

Attributes

estimators_ [list of int (n_classes * code_size) estimators] Estimators used for predictions.

classes_ [numpy array of shape [n_classes]] Array containing labels.

code_book_ [numpy array of shape [n_classes, code_size]] Binary array containing the code of each class.
References

[1], [2], [3]

Examples

```python
>>> from sklearn.multiclass import OutputCodeClassifier
>>> from sklearn.ensemble import RandomForestClassifier
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_samples=100, n_features=4,
... n_informative=2, n_redundant=0,
... random_state=0, shuffle=False)

>>>clf = OutputCodeClassifier(
... estimator=RandomForestClassifier(random_state=0),
... random_state=0).fit(X, y)

>>>clf.predict([[0, 0, 0, 0]])
array([1])
```

Methods

```python
fit(X, y) Fit underlying estimators.

get_params([deep]) Get parameters for this estimator.

predict(X) Predict multi-class targets using underlying estimators.

score(X, y[, sample_weight]) Return the mean accuracy on the given test data and labels.

set_params(**params) Set the parameters of this estimator.
```

**fit (X, y)**

Fit underlying estimators.

**Parameters**

- **X**  
  [(sparse) array-like of shape (n_samples, n_features)] Data.

- **y**  
  [numpy array of shape [n_samples]] Multi-class targets.

**Returns**

- **self**

**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- **deep**  
  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params**  
  [dict] Parameter names mapped to their values.

**predict (X)**

Predict multi-class targets using underlying estimators.

**Parameters**

```
X  [(sparse) array-like of shape (n_samples, n_features)] Data.

Returns

y  [numpy array of shape [n_samples]] Predicted multi-class targets.

score (X, y, sample_weight=None)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

X  [array-like of shape (n_samples, n_features)] Test samples.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

7.28 sklearn.multioutput: Multioutput regression and classification

This module implements multioutput regression and classification.

The estimators provided in this module are meta-estimators: they require a base estimator to be provided in their constructor. The meta-estimator extends single output estimators to multioutput estimators.

User guide: See the Multilabel classification, Multiclass-multioutput classification, and Multioutput regression sections for further details.

| multioutputClassifierChain(base_estimator,  | A multi-label model that arranges binary classifiers into a chain. |
| multioutput.MultiOutputRegressor(estimator,  | Multi target regression |
| multioutput.MultiOutputClassifier(estimator,  | Multi target classification |
| multioutput.RegressorChain(base_estimator,  | A multi-label model that arranges regressions into a chain. |
| multioutput.RegressorChain(base_estimator,  | A multi-label model that arranges regressions into a chain. |
7.28.1 sklearn.multioutput.ClassifierChain

class sklearn.multioutput.ClassifierChain(base_estimator, *, order=None, cv=None, random_state=None)

A multi-label model that arranges binary classifiers into a chain.

Each model makes a prediction in the order specified by the chain using all of the available features provided to the model plus the predictions of models that are earlier in the chain.

Read more in the User Guide.

New in version 0.19.

Parameters

- **base_estimator** [estimator] The base estimator from which the classifier chain is built.
- **order** [array-like of shape (n_outputs,) or ‘random’, default=None] If None, the order will be determined by the order of columns in the label matrix Y.:

  \[
  \text{order} = [0, 1, 2, \ldots, \text{Y.shape}[1] - 1]
  \]

  The order of the chain can be explicitly set by providing a list of integers. For example, for a chain of length 5.:

  \[
  \text{order} = [1, 3, 2, 4, 0]
  \]

  means that the first model in the chain will make predictions for column 1 in the Y matrix, the second model will make predictions for column 3, etc.

  If order is ‘random’ a random ordering will be used.

- **cv** [int, cross-validation generator or an iterable, default=None] Determines whether to use cross validated predictions or true labels for the results of previous estimators in the chain. Possible inputs for cv are:
  - None, to use true labels when fitting,
  - integer, to specify the number of folds in a (Stratified)KFold,
  - CV splitter,
  - An iterable yielding (train, test) splits as arrays of indices.

- **random_state** [int, RandomState instance or None, optional (default=None)] If \text{order}='random', determines random number generation for the chain order. In addition, it controls the random seed given at each \text{base_estimator} at each chaining iteration. Thus, it is only used when \text{base_estimator} exposes a \text{random_state}. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

- **classes_** [list] A list of arrays of length \text{len(estimators_)} containing the class labels for each estimator in the chain.

- **estimators_** [list] A list of clones of base_estimator.

- **order_** [list] The order of labels in the classifier chain.

See also:

- **RegressorChain** Equivalent for regression.

- **MultioutputClassifier** Classifies each output independently rather than chaining.
References


Examples

```python
>>> from sklearn.datasets import make_multilabel_classification
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.multioutput import ClassifierChain

>>> X, Y = make_multilabel_classification(...
    n_samples=12, n_classes=3, random_state=0
...)
>>> X_train, X_test, Y_train, Y_test = train_test_split(...
    X, Y, random_state=0
...)
>>> base_lr = LogisticRegression(solver='lbfgs', random_state=0)
>>> chain = ClassifierChain(base_lr, order='random', random_state=0)
>>> chain.fit(X_train, Y_train).predict(X_test)
array([[1., 1., 0.],
       [1., 0., 0.],
       [0., 1., 0.]])
>>> chain.predict_proba(X_test)
array([[0.8387..., 0.9431..., 0.4576...],
       [0.8878..., 0.3684..., 0.2640...],
       [0.0321..., 0.9935..., 0.0625...]])
```

Methods

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<td><code>decision_function(X)</code></td>
<td>Evaluate the decision_function of the models in the chain.</td>
</tr>
<tr>
<td><code>fit(X, Y)</code></td>
<td>Fit the model to data matrix X and targets Y.</td>
</tr>
<tr>
<td><code>get_params</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Predict on the data matrix X using the Classifier-Chain model.</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Predict probability estimates.</td>
</tr>
<tr>
<td><code>score(X, y[; sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**decision_function (X)**

Evaluate the decision_function of the models in the chain.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)]

**Returns**

- `Y_decision` [array-like of shape (n_samples, n_classes)] Returns the decision function of the sample for each model in the chain.
Fit the model to data matrix \(X\) and targets \(Y\).

**Parameters**
- \(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)] The input data.
- \(Y\) [array-like of shape (n_samples, n_classes)] The target values.

**Returns**
- \(self\) [object]

**get_params** (*deep=True*)
Get parameters for this estimator.

**Parameters**
- \(deep\) [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- \(params\) [dict] Parameter names mapped to their values.

**predict** (*\(X\)*)
Predict on the data matrix \(X\) using the ClassifierChain model.

**Parameters**
- \(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)] The input data.

**Returns**
- \(Y_{\text{pred}}\) [array-like of shape (n_samples, n_classes)] The predicted values.

**predict_proba** (*\(X\)*)
Predict probability estimates.

**Parameters**
- \(X\) [[array-like, sparse matrix] of shape (n_samples, n_features)]

**Returns**
- \(Y_{\text{prob}}\) [array-like of shape (n_samples, n_classes)]

**score** (*\(X\), *\(y\), sample_weight=None*)
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**
- \(X\) [array-like of shape (n_samples, n_features)] Test samples.
- \(y\) [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for \(X\).
- \(sample_weight\) [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**
- \(score\) [float] Mean accuracy of \(self.predict(X)\) wrt. \(y\).

**set_params** (*\(**params\)*)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using `sklearn.multioutput.ClassifierChain`**

- Classifier Chain

**7.28.2 sklearn.multioutput.MultiOutputRegressor**

```python
class sklearn.multioutput.MultiOutputRegressor(estimator, *, n_jobs=None)
```

Multi target regression

This strategy consists of fitting one regressor per target. This is a simple strategy for extending regressors that do not natively support multi-target regression.

New in version 0.18.

**Parameters**

- **estimator** [estimator object] An estimator object implementing `fit` and `predict`.

- **n_jobs** [int or None, optional (default=None)] The number of jobs to run in parallel. `fit`, `predict` and `partial_fit` (if supported by the passed estimator) will be parallelized for each target.

When individual estimators are fast to train or predict, using `n_jobs > 1` can result in slower performance due to the parallelism overhead.

None means 1 unless in a `joblib.parallel_backend` context. `-1` means using all available processes / threads. See `Glossary` for more details.

Changed in version 0.20: `n_jobs` default changed from 1 to None

**Attributes**

- **estimators_** [list of n_output estimators] Estimators used for predictions.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.datasets import load_linnerud
>>> from sklearn.multioutput import MultiOutputRegressor
>>> from sklearn.linear_model import Ridge

>>> X, y = load_linnerud(return_X_y=True)
>>> clf = MultiOutputRegressor(Ridge(random_state=123)).fit(X, y)
>>> clf.predict(X[[0]])
array([[176..., 35..., 57...]])
```
Methods

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<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
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</table>

`fit(X, y, sample_weight=None, **fit_params)`

Fit the model to data. Fit a separate model for each output variable.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Data.
- `y` ([array-like, sparse matrix] of shape (n_samples, n_outputs)) Multi-output targets. An indicator matrix turns on multilabel estimation.
- `sample_weight` (array-like of shape (n_samples, ), default=None) Sample weights. If None, then samples are equally weighted. Only supported if the underlying regressor supports sample weights.
- **fit_params** (dict of string -> object) Parameters passed to the `estimator.fit` method of each step.

**Returns**

- `self` [object]

`get_params(deep=True)`

Get parameters for this estimator.

**Parameters**

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params` [dict] Parameter names mapped to their values.

`partial_fit(X, y, sample_weight=None)`

Incrementally fit the model to data. Fit a separate model for each output variable.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Data.
- `y` ([array-like, sparse matrix] of shape (n_samples, n_outputs)) Multi-output targets.
- `sample_weight` (array-like of shape (n_samples, ), default=None) Sample weights. If None, then samples are equally weighted. Only supported if the underlying regressor supports sample weights.

**Returns**

- `self` [object]

`predict(X)`
Predict multi-output variable using a model trained for each target variable.

Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] Data.

Returns

y  [[array-like, sparse matrix] of shape (n_samples, n_outputs)] Multi-output targets predicted across multiple predictors. Note: Separate models are generated for each predictor.

score (X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1-\frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})**2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())**2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X  [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.
Examples using `sklearn.multioutput.MultiOutputRegressor`

- Comparing random forests and the multi-output meta estimator

### 7.28.3 sklearn.multioutput.MultiOutputClassifier

```python
class sklearn.multioutput.MultiOutputClassifier(estimator, *, n_jobs=None)
```

Multi target classification

This strategy consists of fitting one classifier per target. This is a simple strategy for extending classifiers that do not natively support multi-target classification.

**Parameters**

- `estimator` [estimator object] An estimator object implementing `fit`, `score` and `predict_proba`.
- `n_jobs` [int or None, optional (default=None)] The number of jobs to run in parallel. `fit`, `predict` and `partial_fit` (if supported by the passed estimator) will be parallelized for each target.

When individual estimators are fast to train or predict, using `n_jobs > 1` can result in slower performance due to the parallelism overhead.

None means 1 unless in a `joblib.parallel_backend` context. `-1` means using all available processes / threads. See `Glossary` for more details.

Changed in version 0.20: `n_jobs` default changed from 1 to None

**Attributes**

- `classes_` [ndarray of shape (n_classes,)] Class labels.
- `estimators_` [list of n_output estimators] Estimators used for predictions.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.datasets import make_multilabel_classification
>>> from sklearn.multioutput import MultiOutputClassifier
>>> from sklearn.neighbors import KNeighborsClassifier

>>> X, y = make_multilabel_classification(n_classes=3, random_state=0)
>>> clf = MultiOutputClassifier(KNeighborsClassifier()).fit(X, y)
>>> clf.predict(X[-2:]),
array([[1, 1, 0], [1, 1, 1]])
```

**Methods**

- `fit(X, Y[, sample_weight])` Fit the model to data matrix `X` and targets `Y`.
- `get_params([deep])` Get parameters for this estimator.
- `partial_fit(X, y[, classes, sample_weight])` Incrementally fit the model to data.
- `predict(X)` Predict multi-output variable using a model
- `score(X, y)` Returns the mean accuracy on the given test data and labels.
- `set_params(**params)` Set the parameters of this estimator.
**fit** *(X, Y, sample_weight=None, **fit_params)*
Fit the model to data matrix X and targets Y.

** Parameters **

- **X**  
  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.

- **Y**  
  [array-like of shape (n_samples, n_classes)] The target values.

- **sample_weight**  
  [array-like of shape (n_samples, ), default=None] Sample weights. If None, then samples are equally weighted. Only supported if the underlying classifier supports sample weights.

- **fit_params**  
  [dict of string -> object] Parameters passed to the estimator.fit method of each step.
  
  New in version 0.23.

** Returns **

- **self**  
  [object]

**get_params**(deep=True)
Get parameters for this estimator.

** Parameters **

- **deep**  
  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

** Returns **

- **params**  
  [dict] Parameter names mapped to their values.

**partial_fit** *(X, y, classes=None, sample_weight=None)*
Incrementally fit the model to data. Fit a separate model for each output variable.

** Parameters **

- **X**  
  [{array-like, sparse matrix} of shape (n_samples, n_features)] Data.

- **y**  
  [{array-like, sparse matrix} of shape (n_samples, n_outputs)] Multi-output targets.

- **classes**  
  [list of ndarray of shape (n_outputs,)] Each array is unique classes for one output in str/int Can be obtained by via [np.unique(y[:, i]) for i in range(y.shape[1])], where y is the target matrix of the entire dataset. This argument is required for the first call to partial_fit and can be omitted in the subsequent calls. Note that y doesn’t need to contain all labels in classes.

- **sample_weight**  
  [array-like of shape (n_samples, ), default=None] Sample weights. If None, then samples are equally weighted. Only supported if the underlying regressor supports sample weights.

** Returns **

- **self**  
  [object]

**predict** *(X)*
Predict multi-output variable using a model trained for each target variable.

** Parameters **

- **X**  
  [{array-like, sparse matrix} of shape (n_samples, n_features)] Data.

** Returns **
y [[array-like, sparse matrix] of shape (n_samples, n_outputs)] Multi-output targets predicted across multiple predictors. Note: Separate models are generated for each predictor.

**property predict_proba**
Probability estimates. Returns prediction probabilities for each class of each output.

This method will raise a ValueError if any of the estimators do not have predict_proba.

Parameters

X [array-like of shape (n_samples, n_features)] Data

Returns

p [array of shape (n_samples, n_classes), or a list of n_outputs such arrays if n_outputs > 1.] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

Changed in version 0.19: This function now returns a list of arrays where the length of the list is n_outputs, and each array is (n_samples, n_classes) for that particular output.

**score** (X, y)
Returns the mean accuracy on the given test data and labels.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples
y [array-like of shape (n_samples, n_outputs)] True values for X

Returns

scores [float] accuracy_score of self.predict(X) versus y

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.28.4 sklearn.multioutput.RegressorChain

class sklearn.multioutput.RegressorChain(base_estimator, *, order=None, cv=None, random_state=None)
A multi-label model that arranges regressions into a chain.

Each model makes a prediction in the order specified by the chain using all of the available features provided to the model plus the predictions of models that are earlier in the chain.

Read more in the User Guide.

New in version 0.20.

Parameters
**base_estimator** [estimator] The base estimator from which the classifier chain is built.

**order** [array-like of shape (n_outputs,) or ‘random’, default=None] If None, the order will be determined by the order of columns in the label matrix Y:

\[
\text{order} = [0, 1, 2, \ldots, \text{Y.shape[1]} - 1]
\]

The order of the chain can be explicitly set by providing a list of integers. For example, for a chain of length 5:

\[
\text{order} = [1, 3, 2, 4, 0]
\]

means that the first model in the chain will make predictions for column 1 in the Y matrix, the second model will make predictions for column 3, etc.

If order is ‘random’ a random ordering will be used.

**cv** [int, cross-validation generator or an iterable, default=None] Determines whether to use cross validated predictions or true labels for the results of previous estimators in the chain. Possible inputs for cv are:

- None, to use true labels when fitting,
- integer, to specify the number of folds in a (Stratified)KFold,
- CV splitter,
- An iterable yielding (train, test) splits as arrays of indices.

**random_state** [int, RandomState instance or None, optional (default=None)] If order='random', determines random number generation for the chain order. In addition, it controls the random seed given at each base_estimator at each chaining iteration. Thus, it is only used when base_estimator exposes a random_state. Pass an int for reproducible output across multiple function calls. See *Glossary.*

**Attributes**

- **estimators_** [list] A list of clones of base_estimator.

- **order_** [list] The order of labels in the classifier chain.

See also:

- **ClassifierChain** Equivalent for classification.

- **MultioutputRegressor** Learns each output independently rather than chaining.

**Examples**

```python
>>> from sklearn.multioutput import RegressorChain
>>> from sklearn.linear_model import LogisticRegression
>>> logreg = LogisticRegression(solver='lbfgs', multi_class='multinomial')
>>> X, Y = [[1, 0], [0, 1], [1, 1]], [[0, 2], [1, 1], [2, 0]]
>>> chain = RegressorChain(base_estimator=logreg, order=[0, 1]).fit(X, Y)
>>> chain.predict(X)
array([[0., 2.],
       [1., 1.],
       [2., 0.]])
```
Methods

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<td>fit(X, Y, **fit_params)</td>
<td>Fit the model to data matrix X and targets Y.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Predict on the data matrix X using the Classifier-Chain model.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

### fit ($X, Y, **fit\_params$)

Fit the model to data matrix $X$ and targets $Y$.

**Parameters**

- $X$ [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.
- $Y$ [array-like of shape (n_samples, n_classes)] The target values.
- **fit\_params** [dict of string -> object] Parameters passed to the fit method at each step of the regressor chain.
  - New in version 0.23.

**Returns**

- self [object]

### get_params (deep=True)

Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- params [dict] Parameter names mapped to their values.

### predict ($X$)

Predict on the data matrix $X$ using the ClassifierChain model.

**Parameters**

- $X$ [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.

**Returns**

- $Y\_pred$ [array-like of shape (n_samples, n_classes)] The predicted values.

### score ($X, y, \text{sample\_weight}=\text{None}$)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{\text{true}} - y_{\text{pred}})^{**2}).\text{sum()}$ and $v$ is the total sum of squares $((y_{\text{true}} - y_{\text{true}.\text{mean()}})^{**2}).\text{sum()}$.

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**


X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.29 sklearn.naive_bayes: Naive Bayes

The sklearn.naive_bayes module implements Naive Bayes algorithms. These are supervised learning methods based on applying Bayes’ theorem with strong (naive) feature independence assumptions.

User guide: See the Naive Bayes section for further details.

| naive_bayes.BernoulliNB([, alpha, ...]) | Naive Bayes classifier for multivariate Bernoulli models. |
| naive_bayes.CategoricalNB([, alpha, ...]) | Naive Bayes classifier for categorical features |
| naive_bayes.ComplementNB([, alpha, ...]) | The Complement Naive Bayes classifier described in Rennie et al. |
| naive_bayes.GaussianNB([, priors, ...]) | Gaussian Naive Bayes (GaussianNB) |
| naive_bayes.MultinomialNB([, alpha, ...]) | Naive Bayes classifier for multinomial models |
Naive Bayes classifier for multivariate Bernoulli models.

Like MultinomialNB, this classifier is suitable for discrete data. The difference is that while MultinomialNB works with occurrence counts, BernoulliNB is designed for binary/boolean features.

Read more in the User Guide.

Parameters

- **alpha** [float, default=1.0] Additive (Laplace/Lidstone) smoothing parameter (0 for no smoothing).
- **binarize** [float or None, default=0.0] Threshold for binarizing (mapping to booleans) of sample features. If None, input is presumed to already consist of binary vectors.
- **fit_prior** [bool, default=True] Whether to learn class prior probabilities or not. If false, a uniform prior will be used.
- **class_prior** [array-like of shape (n_classes,), default=None] Prior probabilities of the classes. If specified the priors are not adjusted according to the data.

Attributes

- **class_count_** [ndarray of shape (n_classes)] Number of samples encountered for each class during fitting. This value is weighted by the sample weight when provided.
- **class_log_prior_** [ndarray of shape (n_classes)] Log probability of each class (smoothed).
- **classes_** [ndarray of shape (n_classes,)] Class labels known to the classifier
- **coef_** [ndarray of shape (n_classes, n_features)] Mirrors feature_log_prob_ for interpreting BernoulliNB as a linear model.
- **feature_count_** [ndarray of shape (n_classes, n_features)] Number of samples encountered for each (class, feature) during fitting. This value is weighted by the sample weight when provided.
- **feature_log_prob_** [ndarray of shape (n_classes, n_features)] Empirical log probability of features given a class, \(P(x_i|y)\).
- **intercept_** [ndarray of shape (n_classes,)] Mirrors class_log_prior_ for interpreting BernoulliNB as a linear model.
- **n_features_** [int] Number of features of each sample.

References


Examples

```python
>>> import numpy as np
>>> rng = np.random.RandomState(1)
>>> X = rng.randint(5, size=(6, 100))
>>> Y = np.array([1, 2, 3, 4, 4, 5])
>>> from sklearn.naive_bayes import BernoulliNB
>>> clf = BernoulliNB()
>>> clf.fit(X, Y)
BernoulliNB()
>>> print(clf.predict(X[2:3]))
[3]
```

Methods

- `fit(X, y[, sample_weight])`: Fit Naive Bayes classifier according to X, y
- `get_params([deep])`: Get parameters for this estimator.
- `partial_fit(X, y[, classes, sample_weight])`: Incremental fit on a batch of samples.
- `predict(X)`: Perform classification on an array of test vectors X.
- `predict_log_proba(X)`: Return log-probability estimates for the test vector X.
- `predict_proba(X)`: Return probability estimates for the test vector X.
- `score(X, y[, sample_weight])`: Return the mean accuracy on the given test data and labels.
- `set_params(**params)`: Set the parameters of this estimator.

```python
fit (X, y, sample_weight=None)
    Fit Naive Bayes classifier according to X, y

Parameters

    X  [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

    y  [array-like of shape (n_samples,)] Target values.

    sample_weight  [array-like of shape (n_samples,)] Weights applied to individual samples (1. for unweighted).

Returns

    self  [object]

get_params (deep=True)
    Get parameters for this estimator.

Parameters

    deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

    params  [dict] Parameter names mapped to their values.

partial_fit (X, y, classes=None, sample_weight=None)
    Incremental fit on a batch of samples.
```
This method is expected to be called several times consecutively on different chunks of a dataset so as to implement out-of-core or online learning.

This is especially useful when the whole dataset is too big to fit in memory at once.

This method has some performance overhead hence it is better to call partial_fit on chunks of data that are as large as possible (as long as fitting in the memory budget) to hide the overhead.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vectors, where n_samples is the number of samples and n_features is the number of features.
- **y** (array-like of shape (n_samples,)) Target values.
- **classes** ([array-like of shape (n_classes), default=None]) List of all the classes that can possibly appear in the y vector.
  - Must be provided at the first call to partial_fit, can be omitted in subsequent calls.
- **sample_weight** ([array-like of shape (n_samples,), default=None]) Weights applied to individual samples (1. for unweighted).

Returns

- **self** [object]

  **predict**(X)
  Perform classification on an array of test vectors X.

  Parameters

  - **X** [array-like of shape (n_samples, n_features)]

  Returns

  - C [ndarray of shape (n_samples,)] Predicted target values for X

  **predict_log_proba**(X)
  Return log-probability estimates for the test vector X.

  Parameters

  - **X** [array-like of shape (n_samples, n_features)]

  Returns

  - C [array-like of shape (n_samples, n_classes)] Returns the log-probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`.

  **predict_proba**(X)
  Return probability estimates for the test vector X.

  Parameters

  - **X** [array-like of shape (n_samples, n_features)]

  Returns

  - C [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`.

  **score**(X, y, sample_weight=None)
  Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- X [array-like of shape (n_samples, n_features)] Test samples.
- y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- score [float] Mean accuracy of self.predict(X) wrt. y.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**


**Examples using sklearn.naive_bayes.BernoulliNB**

- Hashing feature transformation using Totally Random Trees
- Classification of text documents using sparse features

**7.29.2 sklearn.naive_bayes.CategoricalNB**

**class** sklearn.naive_bayes.CategoricalNB (*, alpha=1.0, fit_prior=True, class_prior=None, min_categories=None)

Naive Bayes classifier for categorical features

The categorical Naive Bayes classifier is suitable for classification with discrete features that are categorically distributed. The categories of each feature are drawn from a categorical distribution.

Read more in the User Guide.

**Parameters**

- alpha [float, default=1.0] Additive (Laplace/Lidstone) smoothing parameter (0 for no smoothing).
- fit_prior [bool, default=True] Whether to learn class prior probabilities or not. If false, a uniform prior will be used.
- class_prior [array-like of shape (n_classes,), default=None] Prior probabilities of the classes. If specified the priors are not adjusted according to the data.
- min_categories [int or array-like of shape (n_features,), default=None] Minimum number of categories per feature.
  - integer: Sets the minimum number of categories per feature to n_categories for each feature.
array-like: shape (n_features,) where n_categories[i] holds the minimum number of categories for the ith column of the input.

• None (default): Determines the number of categories automatically from the training data.

New in version 0.24.

Attributes

- **category_count_** [list of arrays of shape (n_features, , n_categories of respective feature)] Holds arrays of shape (n_classes, n_categories of respective feature) for each feature. Each array provides the number of samples encountered for each class and category of the specific feature.

- **class_count_** [ndarray of shape (n_classes,)] Number of samples encountered for each class during fitting. This value is weighted by the sample weight when provided.

- **class_log_prior_** [ndarray of shape (n_classes,)] Smoothed empirical log probability for each class.

- **classes_** [ndarray of shape (n_classes,)] Class labels known to the classifier

- **feature_log_prob_** [list of arrays of shape (n_features, , n_categories of respective feature)] Holds arrays of shape (n_classes, n_categories of respective feature) for each feature. Each array provides the empirical log probability of categories given the respective feature and class, \( P(x_i|y) \).

- **n_features_** [int] Number of features of each sample.

- **n_categories_** [ndarray of shape (n_features, , dtype=np.int64)] Number of categories for each feature. This value is inferred from the data or set by the minimum number of categories.

New in version 0.24.

Examples

```python
>>> import numpy as np
>>> rng = np.random.RandomState(1)
>>> X = rng.randint(5, size=(6, 100))
>>> y = np.array([1, 2, 3, 4, 5, 6])
>>> from sklearn.naive_bayes import CategoricalNB
>>> clf = CategoricalNB()
>>> clf.fit(X, y)
CategoricalNB()
>>> print(clf.predict(X[2:3]))
[3]
```

Methods

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<td><strong>predict_proba</strong>&lt;br&gt;(X)</td>
<td>Return probability estimates for the test vector X.</td>
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<td><strong>score</strong>&lt;br&gt;(X, y[, sample_weight])</td>
<td>Return the mean accuracy on the given test data and labels.</td>
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</table>
set_params(**params) Set the parameters of this estimator.

fit(X, y, sample_weight=None)
Fit Naive Bayes classifier according to X, y

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features. Here, each feature of X is assumed to be from a different categorical distribution. It is further assumed that all categories of each feature are represented by the numbers 0, ..., n - 1, where n refers to the total number of categories for the given feature. This can, for instance, be achieved with the help of OrdinalEncoder.

y [array-like of shape (n_samples,)] Target values.

sample_weight [array-like of shape (n_samples), default=None] Weights applied to individual samples (1. for unweighted).

Returns

self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

partial_fit(X, y, classes=None, sample_weight=None)
Incremental fit on a batch of samples.

This method is expected to be called several times consecutively on different chunks of a dataset so as to implement out-of-core or online learning.

This is especially useful when the whole dataset is too big to fit in memory at once.

This method has some performance overhead hence it is better to call partial_fit on chunks of data that are as large as possible (as long as fitting in the memory budget) to hide the overhead.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features. Here, each feature of X is assumed to be from a different categorical distribution. It is further assumed that all categories of each feature are represented by the numbers 0, ..., n - 1, where n refers to the total number of categories for the given feature. This can, for instance, be achieved with the help of OrdinalEncoder.

y [array-like of shape (n_samples)] Target values.

classes [array-like of shape (n_classes), default=None] List of all the classes that can possibly appear in the y vector.

Must be provided at the first call to partial_fit, can be omitted in subsequent calls.
sample_weight  [array-like of shape (n_samples), default=None] Weights applied to individual samples (1. for unweighted).

Returns
    self  [object]

predict  (X)
    Perform classification on an array of test vectors X.

    Parameters
      X  [array-like of shape (n_samples, n_features)]

    Returns
      C  [ndarray of shape (n_samples,)] Predicted target values for X

predict_log_proba  (X)
    Return log-probability estimates for the test vector X.

    Parameters
      X  [array-like of shape (n_samples, n_features)]

    Returns
      C  [array-like of shape (n_samples, n_classes)] Returns the log-probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

predict_proba  (X)
    Return probability estimates for the test vector X.

    Parameters
      X  [array-like of shape (n_samples, n_features)]

    Returns
      C  [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

score  (X, y, sample_weight=None)
    Return the mean accuracy on the given test data and labels.

    In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

    Parameters
      X  [array-like of shape (n_samples, n_features)] Test samples.
      y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
      sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

    Returns
      score  [float] Mean accuracy of self.predict(X) wrt. y.

set_params  (**params)
    Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

### 7.29.3 sklearn.naive_bayes.ComplementNB

**class** sklearn.naive_bayes.ComplementNB(*, alpha=1.0, fit_prior=True, class_prior=None, norm=False)

The Complement Naive Bayes classifier described in Rennie et al. (2003).

The Complement Naive Bayes classifier was designed to correct the “severe assumptions” made by the standard Multinomial Naive Bayes classifier. It is particularly suited for imbalanced data sets.

Read more in the *User Guide*.

New in version 0.20.

**Parameters**

**alpha** [float, default=1.0] Additive (Laplace/Lidstone) smoothing parameter (0 for no smoothing).

**fit_prior** [bool, default=True] Only used in edge case with a single class in the training set.

**class_prior** [array-like of shape (n_classes,), default=None] Prior probabilities of the classes. Not used.

**norm** [bool, default=False] Whether or not a second normalization of the weights is performed. The default behavior mirrors the implementations found in Mahout and Weka, which do not follow the full algorithm described in Table 9 of the paper.

**Attributes**

**class_count_** [ndarray of shape (n_classes,)] Number of samples encountered for each class during fitting. This value is weighted by the sample weight when provided.

**class_log_prior_** [ndarray of shape (n_classes,)] Smoothed empirical log probability for each class. Only used in edge case with a single class in the training set.

**classes_** [ndarray of shape (n_classes,)] Class labels known to the classifier

**coef_** [ndarray of shape (n_classes, n_features)] Mirrors feature_log_prob_ for interpreting ComplementNB as a linear model. Deprecated since version 0.24: coef_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).

**feature_all_** [ndarray of shape (n_features,)] Number of samples encountered for each feature during fitting. This value is weighted by the sample weight when provided.

**feature_count_** [ndarray of shape (n_classes, n_features)] Number of samples encountered for each (class, feature) during fitting. This value is weighted by the sample weight when provided.

**feature_log_prob_** [ndarray of shape (n_classes, n_features)] Empirical weights for class complements.
**intercept_** [ndarray of shape (n_classes,)] Mirrors class_log_prior_ for interpreting ComplementNB as a linear model.

Deprecated since version 0.24: coef_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).

**n_features_** [int] Number of features of each sample.

**References**


**Examples**

```python
>>> import numpy as np
>>> rng = np.random.RandomState(1)
>>> X = rng.randint(5, size=(6, 100))
>>> y = np.array([1, 2, 3, 4, 5, 6])
>>> from sklearn.naive_bayes import ComplementNB
>>> clf = ComplementNB()
>>> clf.fit(X, y)
ComplementNB()
>>> print(clf.predict(X[2:3]))
[3]
```

**Methods**

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<td><strong>fit(X, y[, sample_weight])</strong></td>
<td>Fit Naive Bayes classifier according to X, y</td>
</tr>
<tr>
<td><strong>get_params([deep])</strong></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><strong>partial_fit(X, y[, classes, sample_weight])</strong></td>
<td>Incremental fit on a batch of samples.</td>
</tr>
<tr>
<td><strong>predict(X)</strong></td>
<td>Perform classification on an array of test vectors X.</td>
</tr>
<tr>
<td><strong>predict_log_proba(X)</strong></td>
<td>Return log-probability estimates for the test vector X.</td>
</tr>
<tr>
<td><strong>predict_proba(X)</strong></td>
<td>Return probability estimates for the test vector X.</td>
</tr>
<tr>
<td><strong>score(X, y[, sample_weight])</strong></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td>**set_params(<strong>params)</strong></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit** *(X, y, sample_weight=None)*

Fit Naive Bayes classifier according to X, y

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)] Target values.
- **sample_weight** [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

**Returns**
get_params (deep=True)  
Get parameters for this estimator.

Parameters

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- params [dict] Parameter names mapped to their values.

partial_fit (X, y, classes=None, sample_weight=None)  
Incremental fit on a batch of samples.

This method is expected to be called several times consecutively on different chunks of a dataset so as to implement out-of-core or online learning.

This is especially useful when the whole dataset is too big to fit in memory at once.

This method has some performance overhead hence it is better to call partial_fit on chunks of data that are as large as possible (as long as fitting in the memory budget) to hide the overhead.

Parameters

- X [array-like, sparse matrix] of shape (n_samples, n_features) Training vectors, where n_samples is the number of samples and n_features is the number of features.
- y [array-like of shape (n_samples,)] Target values.
- classes [array-like of shape (n_classes), default=None] List of all the classes that can possibly appear in the y vector.
  Must be provided at the first call to partial_fit, can be omitted in subsequent calls.
- sample_weight [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

Returns

- self [object]

predict (X)  
Perform classification on an array of test vectors X.

Parameters

- X [array-like of shape (n_samples, n_features)]

Returns

- C [ndarray of shape (n_samples,)] Predicted target values for X

predict_log_proba (X)  
Return log-probability estimates for the test vector X.

Parameters

- X [array-like of shape (n_samples, n_features)]

Returns

- C [array-like of shape (n_samples, n_classes)] Returns the log-probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.
**predict_proba** *(X)*  
Return probability estimates for the test vector X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]

**Returns**

- **C** [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

**score** *(X, y, sample_weight=None)*  
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] Mean accuracy of self.predict(X) wrt. y.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- ****params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

**Examples using sklearn.naive_bayes.ComplementNB**

- Classification of text documents using sparse features

**7.29.4 sklearn.naive_bayes.GaussianNB**

**class** sklearn.naive_bayes.GaussianNB (***, priors=None, var_smoothing=1e-09**)
Gaussian Naive Bayes (GaussianNB)

Can perform online updates to model parameters via **partial_fit**. For details on algorithm used to update feature means and variance online, see Stanford CS tech report STAN-CS-79-773 by Chan, Golub, and LeVeque:


Read more in the **User Guide**.

**Parameters**
priors [array-like of shape (n_classes,)] Prior probabilities of the classes. If specified the priors are not adjusted according to the data.

var_smoothing [float, default=1e-9] Portion of the largest variance of all features that is added to variances for calculation stability.

New in version 0.20.

Attributes

class_count_ [ndarray of shape (n_classes,)] number of training samples observed in each class.

class_prior_ [ndarray of shape (n_classes,)] probability of each class.

classes_ [ndarray of shape (n_classes,)] class labels known to the classifier

epsilon_ [float] absolute additive value to variances

sigma_ [ndarray of shape (n_classes, n_features)] variance of each feature per class

theta_ [ndarray of shape (n_classes, n_features)] mean of each feature per class

Examples

```python
>>> import numpy as np
>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])
>>> Y = np.array([1, 1, 1, 2, 2, 2])
>>> from sklearn.naive_bayes import GaussianNB
>>> clf = GaussianNB()
>>> clf.fit(X, Y)
GaussianNB()
>>> print(clf.predict([[-0.8, -1]]))
[1]
>>> clf_pf = GaussianNB()
>>> clf_pf.partial_fit(X, Y, np.unique(Y))
GaussianNB()
>>> print(clf_pf.predict([[-0.8, -1]]))
[1]
```

Methods

- `fit(X, y[, sample_weight])`: Fit Gaussian Naive Bayes according to X, y
- `get_params([deep])`: Get parameters for this estimator.
- `partial_fit(X, y[, classes, sample_weight])`: Incremental fit on a batch of samples.
- `predict(X)`: Perform classification on an array of test vectors X.
- `predict_log_proba(X)`: Return log-probability estimates for the test vector X.
- `predict_proba(X)`: Return probability estimates for the test vector X.
- `score(X, y[, sample_weight])`: Return the mean accuracy on the given test data and labels.
- `set_params(**params)`: Set the parameters of this estimator.

```python
fit (X, y, sample_weight=None)
Fit Gaussian Naive Bayes according to X, y
```

Parameters
X [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values.

**sample_weight** [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

New in version 0.17: Gaussian Naive Bayes supports fitting with *sample_weight*.

**Returns**

self [object]

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

params [dict] Parameter names mapped to their values.

**partial_fit**(X, y, classes=None, sample_weight=None)

Incremental fit on a batch of samples.

This method is expected to be called several times consecutively on different chunks of a dataset so as to implement out-of-core or online learning.

This is especially useful when the whole dataset is too big to fit in memory at once.

This method has some performance and numerical stability overhead, hence it is better to call partial_fit on chunks of data that are as large as possible (as long as fitting in the memory budget) to hide the overhead.

**Parameters**

X [array-like of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.

y [array-like of shape (n_samples,)] Target values.

classes [array-like of shape (n_classes,), default=None] List of all the classes that can possibly appear in the y vector.

Must be provided at the first call to partial_fit, can be omitted in subsequent calls.

**sample_weight** [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

New in version 0.17.

**Returns**

self [object]

**predict**(X)

Perform classification on an array of test vectors X.

**Parameters**

X [array-like of shape (n_samples, n_features)]

**Returns**

C [ndarray of shape (n_samples,)] Predicted target values for X
predict_log_proba \(X\)
Return log-probability estimates for the test vector \(X\).

**Parameters**

\(X\) [array-like of shape (n_samples, n_features)]

**Returns**

\(C\) [array-like of shape (n_samples, n_classes)] Returns the log-probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute \(classes_\).

predict_proba \(X\)
Return probability estimates for the test vector \(X\).

**Parameters**

\(X\) [array-like of shape (n_samples, n_features)]

**Returns**

\(C\) [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute \(classes_\).

cscore \((X, y, \text{sample_weight}=\text{None})\)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

\(X\) [array-like of shape (n_samples, n_features)] Test samples.

\(y\) [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for \(X\).

\(\text{sample_weight}\) [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

\(\text{score}\) [float] Mean accuracy of self.predict \((X)\) wrt. \(y\).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<\text{component}>__<\text{parameter}>\) so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.
Examples using `sklearn.naive_bayes.GaussianNB`

- Comparison of Calibration of Classifiers
- Probability Calibration curves
- Probability calibration of classifiers
- Classifier comparison
- Plot class probabilities calculated by the VotingClassifier
- Plotting Learning Curves
- Importance of Feature Scaling

7.29.5 `sklearn.naive_bayes.MultinomialNB`

class `sklearn.naive_bayes.MultinomialNB(*, alpha=1.0, fit_prior=True, class_prior=None)`

Naive Bayes classifier for multinomial models

The multinomial Naive Bayes classifier is suitable for classification with discrete features (e.g., word counts for text classification). The multinomial distribution normally requires integer feature counts. However, in practice, fractional counts such as tf-idf may also work.

Read more in the `User Guide`.

Parameters

- `alpha` [float, default=1.0] Additive (Laplace/Lidstone) smoothing parameter (0 for no smoothing).
- `fit_prior` [bool, default=True] Whether to learn class prior probabilities or not. If false, a uniform prior will be used.
- `class_prior` [array-like of shape (n_classes,), default=None] Prior probabilities of the classes. If specified the priors are not adjusted according to the data.

Attributes

- `class_count_` [ndarray of shape (n_classes,)] Number of samples encountered for each class during fitting. This value is weighted by the sample weight when provided.
- `class_log_prior_` [ndarray of shape (n_classes,)] Smoothed empirical log probability for each class.
- `classes_` [ndarray of shape (n_classes,)] Class labels known to the classifier
- `coef_` [ndarray of shape (n_classes, n_features)] Mirrors `feature_log_prob_` for interpreting `MultinomialNB` as a linear model.

    Deprecated since version 0.24: `coef_` is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).
- `feature_count_` [ndarray of shape (n_classes, n_features)] Number of samples encountered for each (class, feature) during fitting. This value is weighted by the sample weight when provided.
- `feature_log_prob_` [ndarray of shape (n_classes, n_features)] Empirical log probability of features given a class, $P(x_i | y)$. 

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**intercept_** [ndarray of shape (n_classes,)] Mirrors **class_log_prior_** for interpreting MultinomialNB as a linear model.

Deprecated since version 0.24: intercept_ is deprecated in 0.24 and will be removed in 1.1 (renaming of 0.26).

**n_features_** [int] Number of features of each sample.

**Notes**

For the rationale behind the names **coef_** and **intercept_**, i.e. naive Bayes as a linear classifier, see J. Rennie et al. (2003), Tackling the poor assumptions of naive Bayes text classifiers, ICML.

**References**


**Examples**

```python
>>> import numpy as np
>>> rng = np.random.RandomState(1)
>>> X = rng.randint(5, size=(6, 100))
>>> y = np.array([1, 2, 3, 4, 5, 6])
>>> from sklearn.naive_bayes import MultinomialNB
>>> clf = MultinomialNB()
>>> clf.fit(X, y)
MultinomialNB()
>>> print(clf.predict(X[2:3]))
[3]
```

**Methods**

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<tr>
<td><code>fit(X, y[, sample_weight])</code></td>
<td>Fit Naive Bayes classifier according to X, y</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>partial_fit(X, y[, classes, sample_weight])</code></td>
<td>Incremental fit on a batch of samples.</td>
</tr>
<tr>
<td><code>predict(X)</code></td>
<td>Perform classification on an array of test vectors X.</td>
</tr>
<tr>
<td><code>predict_log_proba(X)</code></td>
<td>Return log-probability estimates for the test vector X.</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Return probability estimates for the test vector X.</td>
</tr>
<tr>
<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>

**fit**(X, y, sample_weight=None)

Fit Naive Bayes classifier according to X, y

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vectors, where n_samples is the number of samples and n_features is the number of features.
y [array-like of shape (n_samples,)] Target values.

sample_weight [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

Returns
self [object]

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

partial_fit (X, y, classes=None, sample_weight=None)
Incremental fit on a batch of samples.
This method is expected to be called several times consecutively on different chunks of a dataset so as to implement out-of-core or online learning.
This is especially useful when the whole dataset is too big to fit in memory at once.
This method has some performance overhead hence it is better to call partial_fit on chunks of data that are as large as possible (as long as fitting in the memory budget) to hide the overhead.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] Training vectors, where n_samples is the number of samples and n_features is the number of features.
y [array-like of shape (n_samples,)] Target values.
classes [array-like of shape (n_classes), default=None] List of all the classes that can possibly appear in the y vector.
   Must be provided at the first call to partial_fit, can be omitted in subsequent calls.
sample_weight [array-like of shape (n_samples,), default=None] Weights applied to individual samples (1. for unweighted).

Returns
self [object]

predict (X)
Perform classification on an array of test vectors X.

Parameters

X [array-like of shape (n_samples, n_features)]

Returns
C [ndarray of shape (n_samples,)] Predicted target values for X

predict_log_proba (X)
Return log-probability estimates for the test vector X.

Parameters

X [array-like of shape (n_samples, n_features)]
Returns

C [array-like of shape (n_samples, n_classes)] Returns the log-probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

**predict_proba** *(X)*

Return probability estimates for the test vector X.

**Parameters**

X [array-like of shape (n_samples, n_features)]

**Returns**

C [array-like of shape (n_samples, n_classes)] Returns the probability of the samples for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

X [array-like of shape (n_samples, n_features)] Test samples.

y [array-like of shape (n_samples,), or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

score [float] Mean accuracy of self.predict(X) wrt. y.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.naive_bayes.MultinomialNB**

- Out-of-core classification of text documents
- Classification of text documents using sparse features
7.30 sklearn.neighbors: Nearest Neighbors

The sklearn.neighbors module implements the k-nearest neighbors algorithm.

User guide: See the Nearest Neighbors section for further details.

neighbors.BallTree(X[, leaf_size, metric]) BallTree for fast generalized N-point problems
neighbors.DistanceMetric DistanceMetric class
neighbors.KDTree(X[, leaf_size, metric]) KDTree for fast generalized N-point problems
neighbors.KNeighborsClassifier([...]) Classifier implementing the k-nearest neighbors vote.
neighbors.KNeighborsRegressor([n_neighbors, ...]) Regression based on k-nearest neighbors.
neighbors.KNeighborsTransformer(*[, mode, ...]) Transform X into a (weighted) graph of k nearest neighbors
neighbors.LocalOutlierFactor([...]) Unsupervised Outlier Detection using Local Outlier Factor (LOF)
neighbors.RadiusNeighborsClassifier([...]) Classifier implementing a vote among neighbors within a given radius
neighbors.RadiusNeighborsRegressor([radius, ...]) Regression based on neighbors within a fixed radius.
neighbors.RadiusNeighborsTransformer(*[, mode, ...]) Transform X into a (weighted) graph of neighbors nearer than a radius
neighbors.NearestCentroid([metric, ...]) Nearest centroid classifier.
neighbors.NearestNeighbors([..., n_neighbors, ...]) Unsupervised learner for implementing neighbor searches.
neighbors.NeighborhoodComponentsAnalysis Neighborhood Components Analysis

7.30.1 sklearn.neighbors.BallTree

class sklearn.neighbors.BallTree(X, leaf_size=40, metric='minkowski', **kwargs)
BallTree for fast generalized N-point problems

Read more in the User Guide.

Parameters

X [array-like of shape (n_samples, n_features)] n_samples is the number of points in the data set, and n_features is the dimension of the parameter space. Note: if X is a C-contiguous array of doubles then data will not be copied. Otherwise, an internal copy will be made.

leaf_size [positive int, default=40] Number of points at which to switch to brute-force. Changing leaf_size will not affect the results of a query, but can significantly impact the speed of a query and the memory required to store the constructed tree. The amount of memory needed to store the tree scales as approximately n_samples / leaf_size. For a specified leaf_size, a leaf node is guaranteed to satisfy leaf_size <= n_points <= 2 * leaf_size, except in the case that n_samples < leaf_size.

metric [str or DistanceMetric object] the distance metric to use for the tree. Default='minkowski' with p=2 (that is, a euclidean metric). See the documentation of the DistanceMetric class for a list of available metrics. ball_tree.valid_metrics gives a list of the metrics which are valid for BallTree.

Additional keywords are passed to the distance metric class.
Note: Callable functions in the metric parameter are NOT supported for KDTree and Ball Tree. Function call overhead will result in very poor performance.

Attributes

data [memory view] The training data

Examples

Query for k-nearest neighbors

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = BallTree(X, leaf_size=2)
>>> dist, ind = tree.query(X[:1], k=3)
>>> print(ind)  # indices of 3 closest neighbors
[0 3 1]
>>> print(dist)  # distances to 3 closest neighbors
[ 0. 0.19662693 0.29473397]
```

Pickle and Unpickle a tree. Note that the state of the tree is saved in the pickle operation: the tree needs not be rebuilt upon unpickling.

```python
>>> import numpy as np
>>> import pickle
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = BallTree(X, leaf_size=2)
>>> s = pickle.dumps(tree)
>>> tree_copy = pickle.loads(s)
>>> dist, ind = tree_copy.query(X[:1], k=3)
>>> print(ind)  # indices of 3 closest neighbors
[0 3 1]
>>> print(dist)  # distances to 3 closest neighbors
[ 0. 0.19662693 0.29473397]
```

Query for neighbors within a given radius

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = BallTree(X, leaf_size=2)
>>> print(tree.query_radius(X[:1], r=0.3, count_only=True))
3
>>> ind = tree.query_radius(X[:1], r=0.3)
>>> print(ind)  # indices of neighbors within distance 0.3
[3 0 1]
```

Compute a gaussian kernel density estimate:

```python
>>> import numpy as np
>>> rng = np.random.RandomState(42)
>>> X = rng.random_sample((100, 3))
>>> tree = BallTree(X)
>>> tree.kernel_density(X[:3], h=0.1, kernel='gaussian')
array([ 6.94114649, 7.83281226, 7.2071716 ])
```
Compute a two-point auto-correlation function

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((30, 3))
>>> r = np.linspace(0, 1, 5)
>>> tree = BallTree(X)
>>> tree.two_point_correlation(X, r)
array([ 30, 62, 278, 580, 820])
```

Methods

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>get_arrays(self)</code></td>
<td>Get data and node arrays.</td>
</tr>
<tr>
<td><code>get_n_calls(self)</code></td>
<td>Get number of calls.</td>
</tr>
<tr>
<td><code>get_tree_stats(self)</code></td>
<td>Get tree status.</td>
</tr>
<tr>
<td><code>kernel_density(self, X, h[, kernel, atol, ...])</code></td>
<td>Compute the kernel density estimate at points X with the given kernel, using the distance metric specified at tree creation.</td>
</tr>
<tr>
<td><code>query(X[, k, return_distance, dualtree, ...])</code></td>
<td>query the tree for the k nearest neighbors</td>
</tr>
<tr>
<td><code>query_radius(X, r[, return_distance, ...])</code></td>
<td>query the tree for neighbors within a radius r</td>
</tr>
<tr>
<td><code>reset_n_calls(self)</code></td>
<td>Reset number of calls to 0.</td>
</tr>
<tr>
<td><code>two_point_correlation(X, r[, dualtree])</code></td>
<td>Compute the two-point correlation function</td>
</tr>
</tbody>
</table>

**Methods**

- **get_arrays** `get_arrays(self)`
  Get data and node arrays.

  Returns

  arrays: tuple of array  Arrays for storing tree data, index, node data and node bounds.

- **get_n_calls** `get_n_calls(self)`
  Get number of calls.

  Returns

  n_calls: int  number of distance computation calls

- **get_tree_stats** `get_tree_stats(self)`
  Get tree status.

  Returns

  tree_stats: tuple of int  (number of trims, number of leaves, number of splits)

- **kernel_density** `kernel_density(self, X, h[, kernel, atol, ...])`
  Compute the kernel density estimate at points X with the given kernel, using the distance metric specified at tree creation.

  Parameters

  - X  [array-like of shape (n_samples, n_features)] An array of points to query. Last dimension should match dimension of training data.
  - h  [float] the bandwidth of the kernel
  - kernel  [str, default="gaussian"] specify the kernel to use. Options are - `gaussian` - `tophat` - `epanechnikov` - `exponential` - `linear` - `cosine` Default is kernel = `gaussian`
atol, rtol [float, default=0, 1e-8] Specify the desired relative and absolute tolerance of the result. If the true result is \(K_{\text{true}}\), then the returned result \(K_{\text{ret}}\) satisfies \(\text{abs}(K_{\text{true}} - K_{\text{ret}}) < \text{atol} + \text{rtol} \times K_{\text{ret}}\) The default is zero (i.e. machine precision) for both.

breadth_first [bool, default=False] If True, use a breadth-first search. If False (default) use a depth-first search. Breadth-first is generally faster for compact kernels and/or high tolerances.

return_log [bool, default=False] Return the logarithm of the result. This can be more accurate than returning the result itself for narrow kernels.

Returns
density [ndarray of shape X.shape[:1]] The array of (log)-density evaluations

query \((X, k=1, \text{return\_distance=True, dualtree=False, breadth\_first=False})\)
query the tree for the \(k\) nearest neighbors

Parameters
X [array-like of shape (n_samples, n_features)] An array of points to query
k [int, default=1] The number of nearest neighbors to return
return_distance [bool, default=True] if True, return a tuple \((d, i)\) of distances and indices if False, return array \(i\)
dualtree [bool, default=False] if True, use the dual tree formalism for the query: a tree is built for the query points, and the pair of trees is used to efficiently search this space. This can lead to better performance as the number of points grows large.
breadth_first [bool, default=False] if True, then query the nodes in a breadth-first manner. Otherwise, query the nodes in a depth-first manner.
sort_results [bool, default=True] if True, then distances and indices of each point are sorted on return, so that the first column contains the closest points. Otherwise, neighbors are returned in an arbitrary order.

Returns
\(i\) [if return_distance == False]
\((d,i)\) [if return_distance == True]
d [ndarray of shape X.shape[:1] + (k,), dtype=double] Each entry gives the list of distances to the neighbors of the corresponding point.
i [ndarray of shape X.shape[:1] + (k,), dtype=int] Each entry gives the list of indices of neighbors of the corresponding point.

query_radius \((X, r, \text{return\_distance=False, count\_only=False, sort\_results=False})\)
query the tree for neighbors within a radius \(r\)

Parameters
X [array-like of shape (n_samples, n_features)] An array of points to query
r [distance within which neighbors are returned] \(r\) can be a single value, or an array of values of shape x.shape[:1] if different radii are desired for each point.
return_distance [bool, default=False] if True, return distances to neighbors of each point if False, return only neighbors Note that unlike the query() method, setting return_distance=True here adds to the computation time. Not all distances need to be
calculated explicitly for return_distance=False. Results are not sorted by default: see sort_results keyword.

**count_only** [bool, default=False] if True, return only the count of points within distance r if False, return the indices of all points within distance r If return_distance==True, setting count_only=True will result in an error.

**sort_results** [bool, default=False] if True, the distances and indices will be sorted before being returned. If False, the results will not be sorted. If return_distance == False, setting sort_results = True will result in an error.

**Returns**

- **count** [if count_only == True]
- **ind** [if count_only == False and return_distance == False]
- **(ind, dist)** [if count_only == False and return_distance == True]

- **count** [ndarray of shape X.shape[:-1], dtype=int] Each entry gives the number of neighbors within a distance r of the corresponding point.
- **ind** [ndarray of shape X.shape[:-1], dtype=object] Each element is a numpy integer array listing the indices of neighbors of the corresponding point. Note that unlike the results of a k-neighbors query, the returned neighbors are not sorted by distance by default.
- **dist** [ndarray of shape X.shape[:-1], dtype=object] Each element is a numpy double array listing the distances corresponding to indices in i.

**reset_n_calls** (self)
Reset number of calls to 0.

**two_point_correlation** *(X, r, dualtree=False)*
Compute the two-point correlation function

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] An array of points to query. Last dimension should match dimension of training data.
- **r** [array-like] A one-dimensional array of distances
- **dualtree** [bool, default=False] If True, use a dualtree algorithm. Otherwise, use a single-tree algorithm. Dual tree algorithms can have better scaling for large N.

**Returns**

- **counts** [ndarray] counts[i] contains the number of pairs of points with distance less than or equal to r[i]

### 7.30.2 sklearn.neighbors.DistanceMetric

**class sklearn.neighbors.DistanceMetric**

DistanceMetric class

This class provides a uniform interface to fast distance metric functions. The various metrics can be accessed via the get_metric class method and the metric string identifier (see below).
Examples

```python
>>> from sklearn.neighbors import DistanceMetric
>>> dist = DistanceMetric.get_metric('euclidean')
>>> X = [[0, 1, 2],
    [3, 4, 5]]
>>> dist.pairwise(X)
aparray([[ 0. , 5.19615242],
    [ 5.19615242,  0. ]])
```

Available Metrics

The following lists the string metric identifiers and the associated distance metric classes:

**Metrics intended for real-valued vector spaces:**

<table>
<thead>
<tr>
<th>identifier</th>
<th>class name</th>
<th>args</th>
<th>distance function</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;euclidean&quot;</td>
<td>EuclideanDistance</td>
<td>•</td>
<td>[\sqrt{\sum((x - y)^2)}]</td>
</tr>
<tr>
<td>&quot;manhattan&quot;</td>
<td>ManhattanDistance</td>
<td>•</td>
<td>[\sum(</td>
</tr>
<tr>
<td>&quot;chebyshev&quot;</td>
<td>ChebyshevDistance</td>
<td>•</td>
<td>[\max(</td>
</tr>
<tr>
<td>&quot;minkowski&quot;</td>
<td>MinkowskiDistance</td>
<td>p</td>
<td>[\sum(</td>
</tr>
<tr>
<td>&quot;wminkowski&quot;</td>
<td>WMinkowskiDistance</td>
<td>p, w</td>
<td>[\sum(</td>
</tr>
<tr>
<td>&quot;seuclidean&quot;</td>
<td>SEuclideanDistance</td>
<td>V</td>
<td>[\sqrt{\sum((x - y)^2 / V)}]</td>
</tr>
<tr>
<td>&quot;mahalanobis&quot;</td>
<td>MahalanobisDistance</td>
<td>V or VI</td>
<td>[\sqrt{\sum((x - y)^2 / V - 1 (x - y))}]</td>
</tr>
</tbody>
</table>

**Metrics intended for two-dimensional vector spaces:** Note that the haversine distance metric requires data in the form of [latitude, longitude] and both inputs and outputs are in units of radians.

<table>
<thead>
<tr>
<th>identifier</th>
<th>class name</th>
<th>distance function</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;haversine&quot;</td>
<td>HaversineDistance</td>
<td>[2 \arcsin(\sqrt{\sin^2(0.5 \times dx) + \cos(x1) \cos(x2) \sin^2(0.5 \times dy)})]</td>
</tr>
</tbody>
</table>

**Metrics intended for integer-valued vector spaces:** Though intended for integer-valued vectors, these are also valid metrics in the case of real-valued vectors.

<table>
<thead>
<tr>
<th>identifier</th>
<th>class name</th>
<th>distance function</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;hamming&quot;</td>
<td>HammingDistance</td>
<td>[\frac{N_{\text{unequal}(x, y)}}{N_{\text{tot}}}]</td>
</tr>
<tr>
<td>&quot;canberra&quot;</td>
<td>CanberraDistance</td>
<td>[\frac{\sum(</td>
</tr>
<tr>
<td>&quot;braycurtis&quot;</td>
<td>BrayCurtisDistance</td>
<td>[\frac{\sum(</td>
</tr>
</tbody>
</table>

**Metrics intended for boolean-valued vector spaces:** Any nonzero entry is evaluated to “True”. In the listings below, the following abbreviations are used:

- N : number of dimensions
• NTT : number of dims in which both values are True
• NTF : number of dims in which the first value is True, second is False
• NFT : number of dims in which the first value is False, second is True
• NFF : number of dims in which both values are False
• NNEQ : number of non-equal dimensions, NNEQ = NTF + NFT
• NNZ : number of nonzero dimensions, NNZ = NTF + NFT + NTT

<table>
<thead>
<tr>
<th>identifier</th>
<th>class name</th>
<th>distance function</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;jaccard&quot;</td>
<td>JaccardDistance</td>
<td>NNEQ / NNZ</td>
</tr>
<tr>
<td>&quot;matching&quot;</td>
<td>MatchingDistance</td>
<td>NNEQ / N</td>
</tr>
<tr>
<td>&quot;dice&quot;</td>
<td>DiceDistance</td>
<td>NNEQ / (NTT + NNZ)</td>
</tr>
<tr>
<td>&quot;kulsinski&quot;</td>
<td>KulsinskiDistance</td>
<td>(NNEQ + N - NTT) / (NNEQ + N)</td>
</tr>
<tr>
<td>&quot;rogerstanimoto&quot;</td>
<td>RogersTanimotoDistance</td>
<td>2 * NNEQ / (N + NNEQ)</td>
</tr>
<tr>
<td>&quot;russellrao&quot;</td>
<td>RussellRaoDistance</td>
<td>NNZ / N</td>
</tr>
<tr>
<td>&quot;sokalmichener&quot;</td>
<td>SokalMichenerDistance</td>
<td>2 * NNEQ / (N + NNEQ)</td>
</tr>
<tr>
<td>&quot;sokalsneath&quot;</td>
<td>SokalSneathDistance</td>
<td>NNEQ / (NNEQ + 0.5 * NTT)</td>
</tr>
</tbody>
</table>

User-defined distance:

<table>
<thead>
<tr>
<th>identifier</th>
<th>class name</th>
<th>args</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;pyfunc&quot;</td>
<td>PyFuncDistance</td>
<td>func</td>
</tr>
</tbody>
</table>

Here func is a function which takes two one-dimensional numpy arrays, and returns a distance. Note that in order to be used within the BallTree, the distance must be a true metric: i.e. it must satisfy the following properties

1) Non-negativity: d(x, y) >= 0
2) Identity: d(x, y) = 0 if and only if x == y
3) Symmetry: d(x, y) = d(y, x)
4) Triangle Inequality: d(x, y) + d(y, z) >= d(x, z)

Because of the Python object overhead involved in calling the python function, this will be fairly slow, but it will have the same scaling as other distances.

Methods

- **dist_to_rdist**
  Convert the true distance to the reduced distance.
- **get_metric**
  Get the given distance metric from the string identifier.
- **pairwise**
  Compute the pairwise distances between X and Y
- **rdist_to_dist**
  Convert the Reduced distance to the true distance.

### dist_to_rdist ()

Convert the true distance to the reduced distance.

The reduced distance, defined for some metrics, is a computationally more efficient measure which preserves the rank of the true distance. For example, in the Euclidean distance metric, the reduced distance is the squared-euclidean distance.
get_metric() Get the given distance metric from the string identifier.

See the docstring of DistanceMetric for a list of available metrics.

Parameters

metric [string or class name] The distance metric to use

**kwargs additional arguments will be passed to the requested metric

pairwise() Compute the pairwise distances between X and Y

This is a convenience routine for the sake of testing. For many metrics, the utilities in
scipy.spatial.distance.cdist and scipy.spatial.distance.pdist will be faster.

Parameters

X [array-like] Array of shape (Nx, D), representing Nx points in D dimensions.

Y [array-like (optional)] Array of shape (Ny, D), representing Ny points in D dimensions. If not specified, then Y=X.

Returns

——-

dist [ndarray] The shape (Nx, Ny) array of pairwise distances between points in X and Y.

rdist_to_dist() Convert the Reduced distance to the true distance.

The reduced distance, defined for some metrics, is a computationally more efficient measure which preserves the rank of the true distance. For example, in the Euclidean distance metric, the reduced distance is the squared-euclidean distance.

7.30.3 sklearn.neighbors.KDTree

class sklearn.neighbors.KDTree (X, leaf_size=40, metric='minkowski', **kwargs)

KDTree for fast generalized N-point problems

Read more in the User Guide.

Parameters

X [array-like of shape (n_samples, n_features)] n_samples is the number of points in the data set, and n_features is the dimension of the parameter space. Note: if X is a C-contiguous array of doubles then data will not be copied. Otherwise, an internal copy will be made.

leaf_size [positive int, default=40] Number of points at which to switch to brute-force. Changing leaf_size will not affect the results of a query, but can significantly impact the speed of a query and the memory required to store the constructed tree. The amount of memory needed to store the tree scales as approximately n_samples / leaf_size. For a specified leaf_size, a leaf node is guaranteed to satisfy leaf_size <= n_points <= 2 * leaf_size, except in the case that n_samples < leaf_size.

metric [str or DistanceMetric object] the distance metric to use for the tree. Default='minkowski' with p=2 (that is, a euclidean metric). See the documentation of the DistanceMetric class for a list of available metrics. kd_tree.valid_metrics gives a list of the metrics which are valid for KDTree.

Additional keywords are passed to the distance metric class.
Note: Callable functions in the metric parameter are NOT supported for KDTree and Ball Tree. Function call overhead will result in very poor performance.

Attributes

| data | [memory view] The training data |

Examples

Query for k-nearest neighbors

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = KDTree(X, leaf_size=2)
>>> dist, ind = tree.query(X[:1], k=3)
>>> print(ind)  # indices of 3 closest neighbors
[0 3 1]
>>> print(dist)  # distances to 3 closest neighbors
[0. 0.19662693 0.29473397]
```

Pickle and Unpickle a tree. Note that the state of the tree is saved in the pickle operation: the tree needs not be rebuilt upon unpickling.

```python
>>> import numpy as np
>>> import pickle

>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = KDTree(X, leaf_size=2)
>>> s = pickle.dumps(tree)
>>> tree_copy = pickle.loads(s)
>>> dist, ind = tree_copy.query(X[:1], k=3)
>>> print(ind)  # indices of 3 closest neighbors
[0 3 1]
>>> print(dist)  # distances to 3 closest neighbors
[0. 0.19662693 0.29473397]
```

Query for neighbors within a given radius

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((10, 3))  # 10 points in 3 dimensions
>>> tree = KDTree(X, leaf_size=2)
>>> print(tree.query_radius(X[:1], r=0.3, count_only=True))
3
>>> ind = tree.query_radius(X[:1], r=0.3)
>>> print(ind)  # indices of neighbors within distance 0.3
[3 0 1]
```

Compute a gaussian kernel density estimate:

```python
>>> import numpy as np
>>> rng = np.random.RandomState(42)
>>> X = rng.random_sample((100, 3))
>>> tree = KDTree(X)
>>> tree.kernel_density(X[:3], h=0.1, kernel='gaussian')
array([ 6.94114649, 7.83281226, 7.20717164])
```
Compute a two-point auto-correlation function

```python
>>> import numpy as np
>>> rng = np.random.RandomState(0)
>>> X = rng.random_sample((30, 3))
>>> r = np.linspace(0, 1, 5)
>>> tree = KDTree(X)
>>> tree.two_point_correlation(X, r)
array([ 30, 62, 278, 580, 820])
```

**Methods**

- `get_arrays(self)` Get data and node arrays.
- `get_n_calls(self)` Get number of calls.
- `get_tree_stats(self)` Get tree status.
- `kernel_density(self, X, h[, kernel, atol, ...])` Compute the kernel density estimate at points X with the given kernel, using the distance metric specified at tree creation.
- `query(X[, k, return_distance, dualtree, ...])` query the tree for the k nearest neighbors
- `query_radius(X, r[, return_distance, ...])` query the tree for neighbors within a radius r
- `reset_n_calls(self)` Reset number of calls to 0.
- `two_point_correlation(X, r[, dualtree])` Compute the two-point correlation function

### Methods

- **get_arrays** (`self`) Get data and node arrays.
  
  **Returns**
  
  arrays: tuple of array Arrays for storing tree data, index, node data and node bounds.

- **get_n_calls** (`self`) Get number of calls.
  
  **Returns**
  
  n_calls: int number of distance computation calls

- **get_tree_stats** (`self`) Get tree status.
  
  **Returns**
  
  tree_stats: tuple of int (number of trims, number of leaves, number of splits)

- **kernel_density** (`self, X, h[, kernel, atol, ...]`) Compute the kernel density estimate at points X with the given kernel, using the distance metric specified at tree creation.
  
  **Parameters**
  
  - X [array-like of shape (n_samples, n_features)] An array of points to query. Last dimension should match dimension of training data.
  - h [float] the bandwidth of the kernel
  - kernel [str, default="gaussian"] specify the kernel to use. Options are - 'gaussian' - 'tophat' - 'epanechnikov' - 'exponential' - 'linear' - 'cosine' Default is kernel = 'gaussian'
atol, rtol [float, default=0, 1e-8] Specify the desired relative and absolute tolerance of the result. If the true result is $K_{true}$, then the returned result $K_{ret}$ satisfies $\text{abs}(K_{true} - K_{ret}) < \text{atol} + \text{rtol} \times K_{ret}$ The default is zero (i.e. machine precision) for both.

breadth_first [bool, default=False] If True, use a breadth-first search. If False (default) use a depth-first search. Breadth-first is generally faster for compact kernels and/or high tolerances.

return_log [bool, default=False] Return the logarithm of the result. This can be more accurate than returning the result itself for narrow kernels.

Returns

density [ndarray of shape X.shape[:-1]] The array of (log)-density evaluations

query \((X, k=1, \text{return\_distance=True}, \text{dualtree=False}, \text{breadth\_first=False})\)
query the tree for the k nearest neighbors

Parameters

\(X\) [array-like of shape (n_samples, n_features)] An array of points to query

\(k\) [int, default=1] The number of nearest neighbors to return

\(\text{return\_distance}\) [bool, default=True] if True, return a tuple (d, i) of distances and indices if False, return array i

dualtree [bool, default=False] if True, use the dual tree formalism for the query: a tree is built for the query points, and the pair of trees is used to efficiently search this space. This can lead to better performance as the number of points grows large.

breadth_first [bool, default=False] if True, then query the nodes in a breadth-first manner. Otherwise, query the nodes in a depth-first manner.

sort_results [bool, default=True] if True, then distances and indices of each point are sorted on return, so that the first column contains the closest points. Otherwise, neighbors are returned in an arbitrary order.

Returns

\(i\) [if \(\text{return\_distance} == \text{False}\)]

\((d, i)\) [if \(\text{return\_distance} == \text{True}\)]

d [ndarray of shape X.shape[:-1] + (k,), dttype=double] Each entry gives the list of distances to the neighbors of the corresponding point.

i [ndarray of shape X.shape[:-1] + (k,), dttype=int] Each entry gives the list of indices of neighbors of the corresponding point.

query_radius \((X, r, \text{return\_distance=False}, \text{count\_only=False}, \text{sort\_results=False})\)
query the tree for neighbors within a radius r

Parameters

\(X\) [array-like of shape (n_samples, n_features)] An array of points to query

\(r\) [distance within which neighbors are returned] r can be a single value, or an array of values of shape X.shape[:-1] if different radii are desired for each point.

\(\text{return\_distance}\) [bool, default=False] if True, return distances to neighbors of each point if False, return only neighbors Note that unlike the query() method, setting return_distance=True here adds to the computation time. Not all distances need to be
calculated explicitly for return_distance=False. Results are not sorted by default: see sort_results keyword.

count_only [bool, default=False] if True, return only the count of points within distance \( r \) if False, return the indices of all points within distance \( r \) If return_distance==True, setting count_only=True will result in an error.

sort_results [bool, default=False] if True, the distances and indices will be sorted before being returned. If False, the results will not be sorted. If return_distance == False, setting sort_results = True will result in an error.

Returns

count [if count_only == True]

ind [if count_only == False and return_distance == False]

(ind, dist) [if count_only == False and return_distance == True]

count [ndarray of shape X.shape[:-1], dtype=int] Each entry gives the number of neighbors within a distance \( r \) of the corresponding point.

ind [ndarray of shape X.shape[:-1], dtype=object] Each element is a numpy integer array listing the indices of neighbors of the corresponding point. Note that unlike the results of a k-neighbors query, the returned neighbors are not sorted by distance by default.

dist [ndarray of shape X.shape[:-1], dtype=object] Each element is a numpy double array listing the distances corresponding to indices in \( i \).

reset_n_calls (self)
Reset number of calls to 0.

two_point_correlation (X, r, dualtree=False)
Compute the two-point correlation function

Parameters

X [array-like of shape (n_samples, n_features)] An array of points to query. Last dimension should match dimension of training data.

r [array-like] A one-dimensional array of distances

dualtree [bool, default=False] If True, use a dualtree algorithm. Otherwise, use a single-tree algorithm. Dual tree algorithms can have better scaling for large \( N \).

Returns

counts [ndarray] counts[i] contains the number of pairs of points with distance less than or equal to \( r[i] \)

7.30.4 sklearn.neighbors.KernelDensity

class sklearn.neighbors.KernelDensity (*, bandwidth=1.0, algorithm='auto', kernel='gaussian', metric='euclidean', atol=0, rtol=0, breadth_first=True, leaf_size=40, metric_params=None)

Kernel Density Estimation.

Read more in the User Guide.

Parameters

bandwidth [float, default=1.0] The bandwidth of the kernel.
algorithm  [{‘kd_tree’, ‘ball_tree’, ‘auto’}, default=’auto’] The tree algorithm to use.


metric  [str, default=’euclidian’] The distance metric to use. Note that not all metrics are valid with all algorithms. Refer to the documentation of BallTree and KDTree for a description of available algorithms. Note that the normalization of the density output is correct only for the Euclidean distance metric. Default is ‘euclidean’.

atol  [float, default=0] The desired absolute tolerance of the result. A larger tolerance will generally lead to faster execution.

rtol  [float, default=0] The desired relative tolerance of the result. A larger tolerance will generally lead to faster execution.

breadth_first  [bool, default=True] If true (default), use a breadth-first approach to the problem. Otherwise use a depth-first approach.

leaf_size  [int, default=40] Specify the leaf size of the underlying tree. See BallTree or KDTree for details.

metric_params  [dict, default=None] Additional parameters to be passed to the tree for use with the metric. For more information, see the documentation of BallTree or KDTree.

Attributes


See also:

sklearn.neighbors.KDTree  K-dimensional tree for fast generalized N-point problems.

sklearn.neighbors.BallTree  Ball tree for fast generalized N-point problems.

Examples

Compute a gaussian kernel density estimate with a fixed bandwidth.

```python
>>> import numpy as np
>>> rng = np.random.RandomState(42)
>>> X = rng.random_sample((100, 3))
>>> kde = KernelDensity(kernel='gaussian', bandwidth=0.5).fit(X)
>>> log_density = kde.score_samples(X[:3])
>>> log_density
array([-1.52955942, -1.51462041, -1.60244657])
```

Methods

- `fit(X, y, sample_weight)`: Fit the Kernel Density model on the data.
- `get_params([deep])`: Get parameters for this estimator.
- `sample([n_samples, random_state])`: Generate random samples from the model.
- `score(X[, y])`: Compute the total log probability density under the model.
- `score_samples(X)`: Evaluate the log density model on the data.
- `set_params(**params)`: Set the parameters of this estimator.
fit \((X, y=None, sample_weight=None)\)
Fit the Kernel Density model on the data.

Parameters
- \(X\) [array-like of shape \((n_samples, n_features)\)] List of \(n_features\)-dimensional data points. Each row corresponds to a single data point.
- \(y\) [None] Ignored. This parameter exists only for compatibility with \(\text{Pipeline}\).
- \(sample_weight\) [array-like of shape \((n_samples,)\), default=None] List of sample weights attached to the data \(X\).
  
  New in version 0.20.

Returns
- \(self\) [object] Returns instance of object.

get_params \((deep=True)\)
Get parameters for this estimator.

Parameters
- \(deep\) [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
- \(params\) [dict] Parameter names mapped to their values.

sample \((n_samples=1, random_state=None)\)
Generate random samples from the model.

Currently, this is implemented only for gaussian and tophat kernels.

Parameters
- \(n_samples\) [int, default=1] Number of samples to generate.
- \(random_state\) [int, \(\text{RandomState}\) instance or None, default=None] Determines random number generation used to generate random samples. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

Returns
- \(X\) [array-like of shape \((n_samples, n_features)\)] List of samples.

score \((X, y=None)\)
Compute the total log probability density under the model.

Parameters
- \(X\) [array-like of shape \((n_samples, n_features)\)] List of \(n_features\)-dimensional data points. Each row corresponds to a single data point.
- \(y\) [None] Ignored. This parameter exists only for compatibility with \(\text{Pipeline}\).

Returns
- \(logprob\) [float] Total log-likelihood of the data in \(X\). This is normalized to be a probability density, so the value will be low for high-dimensional data.

score_samples \((X)\)
Evaluate the log density model on the data.

Parameters
X [array-like of shape (n_samples, n_features)] An array of points to query. Last dimension should match dimension of training data (n_features).

Returns
density [ndarray of shape (n_samples,)] The array of log(density) evaluations. These are normalized to be probability densities, so values will be low for high-dimensional data.

set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.neighbors.KernelDensity

- Kernel Density Estimation
- Kernel Density Estimate of Species Distributions
- Simple 1D Kernel Density Estimation

7.30.5 sklearn.neighbors.KNeighborsClassifier
class sklearn.neighbors.KNeighborsClassifier(n_neighbors=5, *, weights='uniform', algorithm='auto', leaf_size=30, p=2, metric='minkowski', metric_params=None, n_jobs=None, **kwargs)

Classifier implementing the k-nearest neighbors vote.

Read more in the User Guide.

Parameters

n_neighbors [int, default=5] Number of neighbors to use by default for kneighbors queries.

weights ["uniform", "distance"] or callable, default="uniform" weight function used in prediction. Possible values:
  • ‘uniform’ : uniform weights. All points in each neighborhood are weighted equally.
  • ‘distance’ : weight points by the inverse of their distance. in this case, closer neighbors of a query point will have a greater influence than neighbors which are further away.
  • [callable] : a user-defined function which accepts an array of distances, and returns an array of the same shape containing the weights.

algorithm ["auto", "ball_tree", "kd_tree", "brute"], default="auto"] Algorithm used to compute the nearest neighbors:
  • ‘ball_tree’ will use BallTree
  • ‘kd_tree’ will use KDTree
• ‘brute’ will use a brute-force search.

• ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to fit method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

**leaf_size** [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

**p** [int, default=2] Power parameter for the Minkowski metric. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

**metric** [str or callable, default=’minkowski’] the distance metric to use for the tree. The default metric is minkowski, and with p=2 is equivalent to the standard Euclidean metric. See the documentation of DistanceMetric for a list of available metrics. If metric is “precomputed”, X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.

**metric_params** [dict, default=None] Additional keyword arguments for the metric function.

**n_jobs** [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details. Doesn’t affect fit method.

**Attributes**

**classes_** [array of shape (n_classes,)] Class labels known to the classifier

**effective_metric_** [str or callable] The distance metric used. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and p parameter set to 2.

**effective_metric_params_** [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the p parameter value if the effective_metric_ attribute is set to ‘minkowski’.

**n_samples_fit_** [int] Number of samples in the fitted data.

**outputs_2d_** [bool] False when y’s shape is (n_samples,) or (n_samples, 1) during fit otherwise True.

See also:

RadiusNeighborsClassifier
KNeighborsRegressor
RadiusNeighborsRegressor
NearestNeighbors
Notes

See *Nearest Neighbors* in the online documentation for a discussion of the choice of algorithm and leaf_size.

**Warning:** Regarding the Nearest Neighbors algorithms, if it is found that two neighbors, neighbor k+1 and k, have identical distances but different labels, the results will depend on the ordering of the training data.


Examples

```python
>>> X = [[0], [1], [2], [3]]
>>> y = [0, 0, 1, 1]
>>> from sklearn.neighbors import KNeighborsClassifier
>>> neigh = KNeighborsClassifier(n_neighbors=3)
>>> neigh.fit(X, y)
KNeighborsClassifier(...)
>>> print(neigh.predict([[1.1]]))
[0]
>>> print(neigh.predict_proba([[0.9]]))
[[0.66666667 0.33333333]]
```

Methods

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<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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**fit(X, y)**

Fit the k-nearest neighbors classifier from the training dataset.

**Parameters**

- **X** [[array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples) if metric=’precomputed’] Training data.

- **y** [[array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)] Target values.

**Returns**

- **self** [KNeighborsClassifier] The fitted k-nearest neighbors classifier.
get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

kneighbors (X=None, n_neighbors=None, return_distance=True)
Finds the K-neighbors of a point.

Returns indices of and distances to the neighbors of each point.

Parameters

X [array-like, shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-
computed', default=None] The query point or points. If not provided, neighbors of each
indexed point are returned. In this case, the query point is not considered its own neighbor.

n_neighbors [int, default=None] Number of neighbors required for each sample. The de-
fault is the value passed to the constructor.

return_distance [bool, default=True] Whether or not to return the distances.

Returns

neigh_dist [ndarray of shape (n_queries, n_neighbors)] Array representing the lengths to
points, only present if return_distance=True

neigh_ind [ndarray of shape (n_queries, n_neighbors)] Indices of the nearest points in the
population matrix.

Examples

In the following example, we construct a NearestNeighbors class from an array representing our data set
and ask who’s the closest point to [1,1,1]

```python
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=1)
>>> neigh.fit(samples)
NearestNeighbors(n_neighbors=1)
>>> print(neigh.kneighbors([[1., 1., 1.]]))
(array([[0.5]]), array([[2]]))
```

As you can see, it returns [[0.5]], and [[2]], which means that the element is at distance 0.5 and is the third
element of samples (indexes start at 0). You can also query for multiple points:

```python
>>> X = [[0., 1., 0.], [1., 0., 1.]]
>>> print(neigh.kneighbors(X, return_distance=False))
array([[1],
       [2]])
```

kneighbors_graph (X=None, n_neighbors=None, mode='connectivity')
Computes the (weighted) graph of k-Neighbors for points in X

Parameters
X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == ‘precomputed’, default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor. For metric='precomputed' the shape should be (n_queries, n_indexed). Otherwise the shape should be (n_queries, n_features).

n_neighbors [int, default=None] Number of neighbors for each sample. The default is the value passed to the constructor.

mode [{‘connectivity’, ‘distance’}, default=’connectivity’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

Returns

A [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

See also:

NearestNeighbors.radius_neighbors_graph

Examples

```
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=2)
>>> neigh.fit(X)
NearestNeighbors(n_neighbors=2)
>>> A = neigh.kneighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 1.],
       [1., 0., 1.]])
```

**predict (X)**
Predict the class labels for the provided data.

**Parameters**

X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == ‘precomputed’] Test samples.

**Returns**

y [ndarray of shape (n_queries,) or (n_queries, n_outputs)] Class labels for each data sample.

**predict_proba (X)**
Return probability estimates for the test data X.

**Parameters**

X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == ‘precomputed’] Test samples.

**Returns**

p [ndarray of shape (n_queries, n_classes), or a list of n_outputs] of such arrays if n_outputs > 1. The class probabilities of the input samples. Classes are ordered by lexicographic order.
**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] Mean accuracy of *self.predict(X)* wrt. *y*.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

---

**Examples using sklearn.neighbors.KNeighborsClassifier**

- *Release Highlights for scikit-learn 0.24*
- *Classifier comparison*
- *Plot the decision boundaries of a VotingClassifier*
- *Nearest Neighbors Classification*
- *Caching nearest neighbors*
- *Comparing Nearest Neighbors with and without Neighborhood Components Analysis*
- *Dimensionality Reduction with Neighborhood Components Analysis*
- *Digits Classification Exercise*
- *Classification of text documents using sparse features*

---

**7.30.6 sklearn.neighbors.KNeighborsRegressor**

**class** sklearn.neighbors.KNeighborsRegressor *(n_neighbors=5, *, weights='uniform', algorithm='auto', leaf_size=30, p=2, metric='minkowski', metric_params=None, n_jobs=None, **kwargs)*

Regression based on k-nearest neighbors.

The target is predicted by local interpolation of the targets associated of the nearest neighbors in the training set. Read more in the *User Guide.*
New in version 0.9.

Parameters

**n_neighbors** [int, default=5] Number of neighbors to use by default for `kneighbors` queries.

**weights** ['uniform’, ‘distance’] or callable, default='uniform'] weight function used in prediction. Possible values:

- ‘uniform’: uniform weights. All points in each neighborhood are weighted equally.
- ‘distance’: weight points by the inverse of their distance. In this case, closer neighbors of a query point will have a greater influence than neighbors which are further away.
- [callable]: a user-defined function which accepts an array of distances, and returns an array of the same shape containing the weights.

Uniform weights are used by default.

**algorithm** ['auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default='auto'] Algorithm used to compute the nearest neighbors:

- ‘ball_tree’ will use `BallTree`
- ‘kd_tree’ will use `KDTree`
- ‘brute’ will use a brute-force search.
- ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to `fit` method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

**leaf_size** [int, default=30] Leaf size passed to `BallTree` or `KDTree`. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

**p** [int, default=2] Power parameter for the Minkowski metric. When p = 1, this is equivalent to using `manhattan_distance` (l1), and `euclidean_distance` (l2) for p = 2. For arbitrary p, `minkowski_distance` (l_p) is used.

**metric** [str or callable, default='minkowski'] the distance metric to use for the tree. The default metric is minkowski, and with p=2 is equivalent to the standard Euclidean metric. See the documentation of `DistanceMetric` for a list of available metrics. If metric is ”precomputed”, X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.

**metric_params** [dict, default=None] Additional keyword arguments for the metric function.

**n_jobs** [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See Glossary for more details. Doesn’t affect `fit` method.

Attributes

**effective_metric_** [str or callable] The distance metric to use. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and p parameter set to 2.

**effective_metric_params_** [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the p parameter value if the effective_metric_ attribute is set to ‘minkowski’.

**n_samples_fit_** [int] Number of samples in the fitted data.
See also:

*NearestNeighbors*

*RadiusNeighborsRegressor*

*KNeighborsClassifier*

*RadiusNeighborsClassifier*

Notes

See *Nearest Neighbors* in the online documentation for a discussion of the choice of algorithm and leaf_size.

**Warning:** Regarding the Nearest Neighbors algorithms, if it is found that two neighbors, neighbor $k+1$ and $k$, have identical distances but different labels, the results will depend on the ordering of the training data.


Examples

```python
>>> X = [[0], [1], [2], [3]]
>>> y = [0, 0, 1, 1]
>>> from sklearn.neighbors import KNeighborsRegressor
>>> neigh = KNeighborsRegressor(n_neighbors=2)
>>> neigh.fit(X, y)
KNeighborsRegressor(...)
>>> neigh.predict([[1.5]])
[0.5]
```

Methods

```
fit(X, y)    Fit the k-nearest neighbors regressor from the training dataset.
get_params([deep]) Get parameters for this estimator.
kneighbors([X, n_neighbors, return_distance]) Finds the K-neighbors of a point.
kneighbors_graph([X, n_neighbors, mode]) Computes the (weighted) graph of k-Neighbors for points in X
predict(X) Predict the target for the provided data
score(X, y[, sample_weight]) Return the coefficient of determination $R^2$ of the prediction.
set_params(**params) Set the parameters of this estimator.
```

**fit** *(X, y)*

Fit the k-nearest neighbors regressor from the training dataset.

**Parameters**

* X * [[array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples)
  if metric=’precomputed’] Training data.
y  [[array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)] Target values.

Returns

self  [KNeighborsRegressor] The fitted k-nearest neighbors regressor.

get_params  (deep=True)
Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

kneighbors  (X=None, n_neighbors=None, return_distance=True)
Finds the K-neighbors of a point.

Returns indices of and distances to the neighbors of each point.

Parameters

X  [array-like, shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

n_neighbors  [int, default=None] Number of neighbors required for each sample. The default is the value passed to the constructor.

return_distance  [bool, default=True] Whether or not to return the distances.

Returns

neigh_dist  [ndarray of shape (n_queries, n_neighbors)] Array representing the lengths to points, only present if return_distance=True

neigh_ind  [ndarray of shape (n_queries, n_neighbors)] Indices of the nearest points in the population matrix.

Examples

In the following example, we construct a NearestNeighbors class from an array representing our data set and ask who’s the closest point to [1,1,1]

```python
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=1)
>>> neigh.fit(samples)
>>> print(neigh.kneighbors([[1., 1., 1.]]))
(array([[0.5]]), array([[2]]))
```

As you can see, it returns [[0.5]], and [[2]], which means that the element is at distance 0.5 and is the third element of samples (indexes start at 0). You can also query for multiple points:
```python
>>> X = [[0., 1., 0.], [1., 0., 1.]]
>>> neigh.kneighbors(X, return_distance=False)
array([[1],
       [2]])...
```

**kneighbors_graph** *(X=None, n_neighbors=None, mode='connectivity')*

Computes the (weighted) graph of k-Neighbors for points in X

**Parameters**

- **X** [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'precomputed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor. For metric='precomputed' the shape should be (n_queries, n_indexed). Otherwise the shape should be (n_queries, n_features).

- **n_neighbors** [int, default=None] Number of neighbors for each sample. The default is the value passed to the constructor.

- **mode** ['{'connectivity', 'distance'}, default='connectivity'] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

**Returns**

- **A** [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

See also:

*NearestNeighbors.radius_neighbors_graph*

**Examples**

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=2)
>>> neigh.fit(X)
NearestNeighbors(n_neighbors=2)
>>> A = neigh.kneighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 1.],
       [1., 0., 1.]])
```

**predict** *(X)*

Predict the target for the provided data

**Parameters**

- **X** [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'precomputed'] Test samples.

**Returns**

- **y** [ndarray of shape (n_queries,) or (n_queries, n_outputs), dtype=int] Target values.
score(X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares \(((y_{\text{true}} - y_{\text{pred}})^2).\text{sum()}\) and $v$ is the total sum of squares \(((y_{\text{true}} - y_{\text{true}}.\text{mean()})^2).\text{sum()}\). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- **score** [float] $R^2$ of self.predict(X) wrt y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

- ****params [dict] Estimator parameters.

Returns

- **self** [estimator instance] Estimator instance.

Examples using sklearn.neighbors.KNeighborsRegressor

- Face completion with a multi-output estimators
- Imputing missing values with variants of IterativeImputer
- Nearest Neighbors regression
7.30.7 sklearn.neighbors.KNeighborsTransformer

class sklearn.neighbors.KNeighborsTransformer(*, mode='distance', n_neighbors=5, algorithm='auto', leaf_size=30, metric='minkowski', p=2, metric_params=None, n_jobs=1)

Transform X into a (weighted) graph of k nearest neighbors

The transformed data is a sparse graph as returned by kneighbors_graph.

Read more in the User Guide.

New in version 0.22.

Parameters

mode [{‘distance’, ‘connectivity’}, default=’distance’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, and ‘distance’ will return the distances between neighbors according to the given metric.

n_neighbors [int, default=5] Number of neighbors for each sample in the transformed sparse graph. For compatibility reasons, as each sample is considered as its own neighbor, one extra neighbor will be computed when mode == ‘distance’. In this case, the sparse graph contains (n_neighbors + 1) neighbors.

algorithm [{‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’}, default=’auto’] Algorithm used to compute the nearest neighbors:

• ‘ball_tree’ will use BallTree
• ‘kd_tree’ will use KDTree
• ‘brute’ will use a brute-force search.
• ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to fit method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

leaf_size [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

metric [str or callable, default=’minkowski’] metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.

If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string.

Distance matrices are not supported.

Valid values for metric are:


See the documentation for scipy.spatial.distance for details on these metrics.
**p** [int, default=2] Parameter for the Minkowski metric from sklearn.metrics.pairwise.pairwise_distances. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

**metric_params** [dict, default=None] Additional keyword arguments for the metric function.

**n_jobs** [int, default=1] The number of parallel jobs to run for neighbors search. If -1, then the number of jobs is set to the number of CPU cores.

**Attributes**

**effective_metric_** [str or callable] The distance metric used. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and p parameter set to 2.

**effective_metric_params_** [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the p parameter value if the effective_metric_ attribute is set to ‘minkowski’.

**n_samples_fit_** [int] Number of samples in the fitted data.

**Examples**

```python
>>> from sklearn.manifold import Isomap
>>> from sklearn.neighbors import KNeighborsTransformer
>>> from sklearn.pipeline import make_pipeline
... estimator = make_pipeline(... KNeighborsTransformer(n_neighbors=5, mode='distance'),... Isomap(neighbors_algorithm='precomputed'))
```

**Methods**

**fit(X[, y])** Fit the k-nearest neighbors transformer from the training dataset.

**fit_transform(X[, y])** Fit to data, then transform it.

**get_params**(deep) Get parameters for this estimator.

**kneighbors**(X, n_neighbors, return_distance) Finds the K-neighbors of a point.

**kneighbors_graph**(X, n_neighbors, mode) Computes the (weighted) graph of k-Neighbors for points in X

**set_params**(**params) Set the parameters of this estimator.

**transform**(X) Computes the (weighted) graph of Neighbors for points in X

**fit**(X, y=None) Fit the k-nearest neighbors transformer from the training dataset.

**Parameters**

**X** [{array-like, sparse matrix} of shape (n_samples, n_features) or (n_samples, n_samples) if metric=‘precomputed’] Training data.

**Returns**

**self** [KNeighborsTransformer] The fitted k-nearest neighbors transformer.
**fit_transform** *(X, y=None)*

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Training set.
- **y** [ignored]

**Returns**

- **Xt** [sparse matrix of shape (n_samples, n_samples)] Xt[i, j] is assigned the weight of edge that connects i to j. Only the neighbors have an explicit value. The diagonal is always explicit. The matrix is of CSR format.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**kneighbors** *(X=None, n_neighbors=None, return_distance=True)*

Finds the K-neighbors of a point.

Returns indices of and distances to the neighbors of each point.

**Parameters**

- **X** [array-like, shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.
- **n_neighbors** [int, default=None] Number of neighbors required for each sample. The default is the value passed to the constructor.
- **return_distance** [bool, default=True] Whether or not to return the distances.

**Returns**

- **neigh_dist** [ndarray of shape (n_queries, n_neighbors)] Array representing the lengths to points, only present if return_distance=True
- **neigh_ind** [ndarray of shape (n_queries, n_neighbors)] Indices of the nearest points in the population matrix.

**Examples**

In the following example, we construct a NearestNeighbors class from an array representing our data set and ask who’s the closest point to [1,1,1]

```python
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=1)
>>> neigh.fit(samples)
NearestNeighbors(n_neighbors=1)
```
As you can see, it returns [[0.5]], and [[2]], which means that the element is at distance 0.5 and is the third
element of samples (indexes start at 0). You can also query for multiple points:

```python
>> X = [[0., 1., 0.], [1., 0., 1.]]
>>> neigh.kneighbors(X, return_distance=False)
array([[1],
       [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
        [2]],
       [[1],
```

**kneighbors_graph** *(X=None, n_neighbors=None, mode='connectivity')*

Computes the (weighted) graph of k-Neighbors for points in X

**Parameters**

- **X** [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor. For metric='precomputed' the shape should be (n_queries, n_indexed). Otherwise the shape should be (n_queries, n_features).

- **n_neighbors** [int, default=None] Number of neighbors for each sample. The default is the value passed to the constructor.

- **mode** [‘connectivity’, ‘distance’, default=’connectivity’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

**Returns**

- **A** [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data. A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

**See also:**

- **NearestNeighbors.radius_neighbors_graph**

**Examples**

```python
>>> X = [[0, 3, 1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=2)
>>> neigh.fit(X)
NearestNeighbors(n_neighbors=2)
>>> A = neigh.kneighbors_graph(X)
>>> A.toarray()
array([[1, 0, 1],
       [0, 1, 1],
       [1, 0, 1]])
```

**set_params(**params**)

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(X)

Computes the (weighted) graph of Neighbors for points in X

**Parameters**

X [array-like of shape (n_samples_transform, n_features)] Sample data.

**Returns**

Xt [sparse matrix of shape (n_samples_transform, n_samples_fit)] Xt[i, j] is assigned the weight of edge that connects i to j. Only the neighbors have an explicit value. The diagonal is always explicit. The matrix is of CSR format.

**Examples using sklearn.neighbors.KNeighborsTransformer**

- Approximate nearest neighbors in TSNE

**7.30.8 sklearn.neighbors.LocalOutlierFactor**

**class** sklearn.neighbors.LocalOutlierFactor (n_neighbors=20, *, algorithm='auto', leaf_size=30, metric='minkowski', p=2, metric_params=None, contamination='auto', novelty=False, n_jobs=None)

Unsupervised Outlier Detection using Local Outlier Factor (LOF)

The anomaly score of each sample is called Local Outlier Factor. It measures the local deviation of density of a given sample with respect to its neighbors. It is local in that the anomaly score depends on how isolated the object is with respect to the surrounding neighborhood. More precisely, locality is given by k-nearest neighbors, whose distance is used to estimate the local density. By comparing the local density of a sample to the local densities of its neighbors, one can identify samples that have a substantially lower density than their neighbors. These are considered outliers.

New in version 0.19.

**Parameters**

- n_neighbors [int, default=20] Number of neighbors to use by default for kneighbors queries. If n_neighbors is larger than the number of samples provided, all samples will be used.

- algorithm [‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default=’auto’] Algorithm used to compute the nearest neighbors:
  - ‘ball_tree’ will use BallTree
  - ‘kd_tree’ will use KDTree
  - ‘brute’ will use a brute-force search.
• ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed
to fit method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

leaf_size [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the
speed of the construction and query, as well as the memory required to store the tree. The
optimal value depends on the nature of the problem.

metric [str or callable, default='minkowski'] metric used for the distance computation. Any
metric from scikit-learn or scipy.spatial.distance can be used.

If metric is “precomputed”, X is assumed to be a distance matrix and must be square. X may
be a sparse matrix, in which case only “nonzero” elements may be considered neighbors.

If metric is a callable function, it is called on each pair of instances (rows) and the resulting
value recorded. The callable should take two arrays as input and return one value indicating
the distance between them. This works for Scipy’s metrics, but is less efficient than passing
the metric name as a string.

Valid values for metric are:

• from scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']

• from scipy.spatial.distance: ['braycurtis', 'canberra', 'chebyshev', 'correlation', 'dice',
  'hamming', 'jaccard', 'kulsinski', 'mahalanobis', 'minkowski', 'rogerstanimoto', 'russellrao',
  'seuclidean', 'sokalmichener', 'sokalsneath', 'sqeuclidean', 'yule']

See the documentation for scipy.spatial.distance for details on these metrics: https://docs.
scipy.org/doc/scipy/reference/spatial.distance.html

p [int, default=2] Parameter for the Minkowski metric from sklearn.metrics.
pairwise.pairwise_distances. When p = 1, this is equivalent to using manhat-
tan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance
(l_p) is used.

metric_params [dict, default=None] Additional keyword arguments for the metric function.

contamination ['auto' or float, default='auto'] The amount of contamination of the data set,
i.e. the proportion of outliers in the data set. When fitting this is used to define the threshold
on the scores of the samples.

• if ‘auto’, the threshold is determined as in the original paper,

• if a float, the contamination should be in the range [0, 0.5].

Changed in version 0.22: The default value of contamination changed from 0.1 to
'auto'.

novelty [bool, default=False] By default, LocalOutlierFactor is only meant to be used for out-
lier detection (novelty=False). Set novelty to True if you want to use LocalOutlierFactor
for novelty detection. In this case be aware that that you should only use predict, deci-
sion_function and score_samples on new unseen data and not on the training set.

New in version 0.20.

n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None
means 1 unless in a joblib.parallel_backend context. -1 means using all proces-
sors. See Glossary for more details.

Attributes

negative_outlier_factor_ [ndarray of shape (n_samples,)] The opposite LOF of the training
samples. The higher, the more normal. Inliers tend to have a LOF score close to 1
The local outlier factor (LOF) of a sample captures its supposed ‘degree of abnormality’. It is the average of the ratio of the local reachability density of a sample and those of its k-nearest neighbors.

- **n_neighbors** [int] The actual number of neighbors used for \texttt{kneighbors} queries.
- **offset_** [float] Offset used to obtain binary labels from the raw scores. Observations having a negative outlier factor smaller than offset are detected as abnormal. The offset is set to -1.5 (inliers score around -1), except when a contamination parameter different than “auto” is provided. In that case, the offset is defined in such a way we obtain the expected number of outliers in training.

New in version 0.20.

- **effective_metric_** [str] The effective metric used for the distance computation.
- **effective_metric_params_** [dict] The effective additional keyword arguments for the metric function.

- **n_samples_fit_** [int] It is the number of samples in the fitted data.

**Methods**

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**property decision_function**

Shifted opposite of the Local Outlier Factor of X. Bigger is better, i.e. large values correspond to inliers.

**Only available for novelty detection (when novelty is set to True).** The shift offset allows a zero thresh-
old for being an outlier. The argument X is supposed to contain new data: if X contains a point from training, it considers the later in its own neighborhood. Also, the samples in X are not considered in the neighborhood of any point.

Parameters

X [array-like of shape (n_samples, n_features)] The query sample or samples to compute the Local Outlier Factor w.r.t. the training samples.

Returns

shifted_opposite_lof_scores [ndarray of shape (n_samples,)] The shifted opposite of the Local Outlier Factor of each input samples. The lower, the more abnormal. Negative scores represent outliers, positive scores represent inliers.

fit (X, y=None)
Fit the local outlier factor detector from the training dataset.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features) or (n_samples, n_samples) if metric='precomputed'] Training data.

y [Ignored] Not used, present for API consistency by convention.

Returns

self [LocalOutlierFactor] The fitted local outlier factor detector.

property fit_predict
Fits the model to the training set X and returns the labels.

Not available for novelty detection (when novelty is set to True). Label is 1 for an inlier and -1 for an outlier according to the LOF score and the contamination parameter.

Parameters

X [array-like of shape (n_samples, n_features), default=None] The query sample or samples to compute the Local Outlier Factor w.r.t. to the training samples.

y [Ignored] Not used, present for API consistency by convention.

Returns

is_inlier [ndarray of shape (n_samples,)] Returns -1 for anomalies/outliers and 1 for inliers.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

kneighbors (X=None, n_neighbors=None, return_distance=True)
Finds the K-neighbors of a point.

Returns indices of and distances to the neighbors of each point.

Parameters
scikit-learn user guide, Release 0.24.0

X [array-like, shape (n_queries, n_features), or (n_queries, n_indexed) if metric == ‘pre-computed’, default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

n_neighbors [int, default=None] Number of neighbors required for each sample. The default is the value passed to the constructor.

return_distance [bool, default=True] Whether or not to return the distances.

Returns

neigh_dist [ndarray of shape (n_queries, n_neighbors)] Array representing the lengths to points, only present if return_distance=True

neigh_ind [ndarray of shape (n_queries, n_neighbors)] Indices of the nearest points in the population matrix.

Examples

In the following example, we construct a NearestNeighbors class from an array representing our data set and ask who’s the closest point to [1,1,1]

```python
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=1)
>>> neigh.fit(samples)
NearestNeighbors(n_neighbors=1)
>>> print(neigh.kneighbors([[1., 1., 1.]]))
(array([[0.5]]), array([[2]]))
```

As you can see, it returns [[0.5]], and [[2]], which means that the element is at distance 0.5 and is the third element of samples (indexes start at 0). You can also query for multiple points:

```python
>>> X = [[0., 1., 0.], [1., 0., 1.]]
>>> neigh.kneighbors(X, return_distance=False)
array([[1],
       [2]]...)
```

kneighbors_graph (X=None, n_neighbors=None, mode='connectivity')
Computes the (weighted) graph of k-Neighbors for points in X

Parameters

X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor. For metric='precomputed' the shape should be (n_queries, n_indexed). Otherwise the shape should be (n_queries, n_features).

n_neighbors [int, default=None] Number of neighbors for each sample. The default is the value passed to the constructor.

mode [‘connectivity’, ‘distance’, default=’connectivity’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

Returns
A [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data $A[i, j]$ is assigned the weight of edge that connects $i$ to $j$. The matrix is of CSR format.

See also:

$\text{NearestNeighbors.radius_neighbors_graph}$

### Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=2)
>>> neigh.fit(X)
NearestNeighbors(n_neighbors=2)
>>> A = neigh.kneighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 1.],
       [1., 0., 1.]])
```

**property predict**

Predict the labels (1 inlier, -1 outlier) of $X$ according to LOF.

*Only available for novelty detection (when novelty is set to True).* This method allows to generalize prediction to new observations (not in the training set).

**Parameters**

- $X$ [array-like of shape (n_samples, n_features)] The query sample or samples to compute the Local Outlier Factor w.r.t. to the training samples.

**Returns**

- $\text{is\_inlier}$ [ndarray of shape (n_samples,)] Returns -1 for anomalies/outliers and +1 for inliers.

**property score_samples**

Opposite of the Local Outlier Factor of $X$.

It is the opposite as bigger is better, i.e. large values correspond to inliers.

*Only available for novelty detection (when novelty is set to True).* The argument $X$ is supposed to contain new data: if $X$ contains a point from training, it considers the later in its own neighborhood. Also, the samples in $X$ are not considered in the neighborhood of any point. The score_samples on training data is available by considering the the $\text{negative\_outlier\_factor\_attribute}$ attribute.

**Parameters**

- $X$ [array-like of shape (n_samples, n_features)] The query sample or samples to compute the Local Outlier Factor w.r.t. the training samples.

**Returns**

- $\text{opposite\_lof\_scores}$ [ndarray of shape (n_samples,)] The opposite of the Local Outlier Factor of each input samples. The lower, the more abnormal.

**set_params** (**params**)

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**Examples using sklearn.neighbors.LocalOutlierFactor**

- Comparing anomaly detection algorithms for outlier detection on toy datasets
- Outlier detection with Local Outlier Factor (LOF)
- Novelty detection with Local Outlier Factor (LOF)

**7.30.9 sklearn.neighbors.RadiusNeighborsClassifier**

*class* sklearn.neighbors.RadiusNeighborsClassifier(*radius=1.0, *, weights='uniform', algorithm='auto', leaf_size=30, p=2, metric='minkowski', outlier_label=None, metric_params=None, n_jobs=None, **kwargs)*

Classifier implementing a vote among neighbors within a given radius

Read more in the *User Guide*.

**Parameters**

radius [float, default=1.0] Range of parameter space to use by default for *radius_neighbors* queries.

weights [[‘uniform’, ‘distance’] or callable, default=’uniform’] weight function used in prediction. Possible values:

- ‘uniform’: uniform weights. All points in each neighborhood are weighted equally.
- ‘distance’: weight points by the inverse of their distance. In this case, closer neighbors of a query point will have a greater influence than neighbors which are further away.
- [callable]: a user-defined function which accepts an array of distances, and returns an array of the same shape containing the weights.

Uniform weights are used by default.

algorithm [[‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default=’auto’] Algorithm used to compute the nearest neighbors:

- ‘ball_tree’ will use *BallTree*
- ‘kd_tree’ will use *KDTree*
- ‘brute’ will use a brute-force search.
- ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to *fit* method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.
**leaf_size** [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

**p** [int, default=2] Power parameter for the Minkowski metric. When \( p = 1 \), this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for \( p = 2 \). For arbitrary \( p \), minkowski_distance (l_p) is used.

**metric** [str or callable, default='minkowski'] the distance metric to use for the tree. The default metric is minkowski, and with \( p=2 \) is equivalent to the standard Euclidean metric. See the documentation of DistanceMetric for a list of available metrics. If metric is "precomputed", X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.

**outlier_label** [{manual label, 'most_frequent'}, default=None] label for outlier samples (samples with no neighbors in given radius).

- manual label: str or int label (should be the same type as y) or list of manual labels if multi-output is used.
- 'most_frequent': assign the most frequent label of y to outliers.
- None: when any outlier is detected, ValueError will be raised.

**metric_params** [dict, default=None] Additional keyword arguments for the metric function.

**n_jobs** [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**Attributes**

- **classes_** [ndarray of shape (n_classes,)] Class labels known to the classifier.
- **effective_metric_** [str or callable] The distance metric used. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and \( p \) parameter set to 2.
- **effective_metric_params_** [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the \( p \) parameter value if the effective_metric_attribute is set to ‘minkowski’.
- **n_samples_fit_** [int] Number of samples in the fitted data.
- **outlier_label_** [int or array-like of shape (n_class,)] Label which is given for outlier samples (samples with no neighbors on given radius).
- **outputs_2d_** [bool] False when y’s shape is (n_samples,) or (n_samples, 1) during fit otherwise True.

See also:

- KNeighborsClassifier
- RadiusNeighborsRegressor
- KNeighborsRegressor
- NearestNeighbors
Notes

See *Nearest Neighbors* in the online documentation for a discussion of the choice of algorithm and leaf_size.


Examples

```python
>>> X = [[0], [1], [2], [3]]
>>> y = [0, 0, 1, 1]
>>> from sklearn.neighbors import RadiusNeighborsClassifier
>>> neigh = RadiusNeighborsClassifier(radius=1.0)
>>> neigh.fit(X, y)
RadiusNeighborsClassifier(...)
>>> print(neigh.predict([[1.5]]))
[0]
>>> print(neigh.predict_proba([[1.0]]))
[[0.66666667 0.33333333]]
```

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### fit(X, y)

Fit the radius neighbors classifier from the training dataset.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples) if metric='precomputed') Training data.
- **y** ([array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)) Target values.

**Returns**

- **self** [RadiusNeighborsClassifier] The fitted radius neighbors classifier.

### get_params(deep=True)

Get parameters for this estimator.

**Parameters**
deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Predict the class labels for the provided data.

Parameters

X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed'] Test samples.

Returns

y [ndarray of shape (n_queries,) or (n_queries, n_outputs)] Class labels for each data sample.

predict_proba (X)
Return probability estimates for the test data X.

Parameters

X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed'] Test samples.

Returns

p [ndarray of shape (n_queries, n_classes), or a list of n_outputs] of such arrays if n_outputs > 1. The class probabilities of the input samples. Classes are ordered by lexicographic order.

radius_neighbors (X=None, radius=None, return_distance=True, sort_results=False)
Finds the neighbors within a given radius of a point or points.

Return the indices and distances of each point from the dataset lying in a ball with size radius around the points of the query array. Points lying on the boundary are included in the results.

The result points are not necessarily sorted by distance to their query point.

Parameters

X [array-like of (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

radius [float, default=None] Limiting distance of neighbors to return. The default is the value passed to the constructor.

return_distance [bool, default=True] Whether or not to return the distances.

sort_results [bool, default=False] If True, the distances and indices will be sorted by increasing distances before being returned. If False, the results may not be sorted. If return_distance=False, setting sort_results=True will result in an error.

New in version 0.22.

Returns

neigh_dist [ndarray of shape (n_samples,) of arrays] Array representing the distances to each point, only present if return_distance=True. The distance values are computed according to the metric constructor parameter.
**neigh_ind** [ndarray of shape (n_samples,) of arrays] An array of arrays of indices of the approximate nearest points from the population matrix that lie within a ball of size `radius` around the query points.

**Notes**

Because the number of neighbors of each point is not necessarily equal, the results for multiple query points cannot be fit in a standard data array. For efficiency, `radius_neighbors` returns arrays of objects, where each object is a 1D array of indices or distances.

**Examples**

In the following example, we construct a NeighborsClassifier class from an array representing our data set and ask who’s the closest point to [1, 1, 1]:

```python
>>> import numpy as np

>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]

>>> from sklearn.neighbors import NearestNeighbors

>>> neigh = NearestNeighbors(radius=1.6)

>>> neigh.fit(samples)

>>> rng = neigh.radius_neighbors([[1., 1., 1.]])

>>> print(np.asarray(rng[0][0]))

[1.5 0.5]

>>> print(np.asarray(rng[1][0]))

[1 2]
```

The first array returned contains the distances to all points which are closer than 1.6, while the second array returned contains their indices. In general, multiple points can be queried at the same time.

**radius_neighbors_graph** *(X=None, radius=None, mode='connectivity', sort_results=False)*

Computes the (weighted) graph of Neighbors for points in X

Neighborhoods are restricted the points at a distance lower than radius.

**Parameters**

- **X** [array-like of shape (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

- **radius** [float, default=None] Radius of neighborhoods. The default is the value passed to the constructor.

- **mode** [{‘connectivity’, ‘distance’}, default=’connectivity’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

- **sort_results** [bool, default=False] If True, in each row of the result, the non-zero entries will be sorted by increasing distances. If False, the non-zero entries may not be sorted. Only used with mode=’distance’.

**Returns**

- **A** [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix if of format CSR.
See also:

* kneighbors_graph

**Examples**

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.5)
>>> neigh.fit(X)
NearestNeighbors(radius=1.5)
>>> A = neigh.radius_neighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 0.],
       [1., 0., 1.]])
```

`score(X, y, sample_weight=None)`

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Test samples.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for `X`.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- `score` [float] Mean accuracy of `self.predict(X)` wrt. `y`.

`set_params(**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

Regression based on neighbors within a fixed radius.
The target is predicted by local interpolation of the targets associated of the nearest neighbors in the training set.
Read more in the User Guide.
New in version 0.9.

Parameters

radius [float, default=1.0] Range of parameter space to use by default for radius_neighbors queries.
weights [‘uniform’, ‘distance’] or callable, default=’uniform’] weight function used in prediction. Possible values:
• ‘uniform’ : uniform weights. All points in each neighborhood are weighted equally.
• ‘distance’ : weight points by the inverse of their distance. in this case, closer neighbors of a query point will have a greater influence than neighbors which are further away.
• [callable] : a user-defined function which accepts an array of distances, and returns an array of the same shape containing the weights.
Uniform weights are used by default.
algorithm [‘auto’, ‘ball_tree’, ‘kd_tree’, ‘brute’], default=’auto’] Algorithm used to compute the nearest neighbors:
• ‘ball_tree’ will use BallTree
• ‘kd_tree’ will use KDTree
• ‘brute’ will use a brute-force search.
• ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to fit method.
Note: fitting on sparse input will override the setting of this parameter, using brute force.
leaf_size [int, default=30] Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.
p [int, default=2] Power parameter for the Minkowski metric. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.
metric [str or callable, default=’minkowski’] the distance metric to use for the tree. The default metric is minkowski, and with p=2 is equivalent to the standard Euclidean metric. See the documentation of DistanceMetric for a list of available metrics. If metric is “precomputed”, X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.
metric_params [dict, default=None] Additional keyword arguments for the metric function.
n_jobs [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

effective_metric_ [str or callable] The distance metric to use. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and p parameter set to 2.

effective_metric_params_ [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the p parameter value if the effective_metric_ attribute is set to ‘minkowski’.

n_samples_fit_ [int] Number of samples in the fitted data.

See also:

NearestNeighbors
KNeighborsRegressor
KNeighborsClassifier
RadiusNeighborsClassifier

Notes

See Nearest Neighbors in the online documentation for a discussion of the choice of algorithm and leaf_size.


Examples

```python
>>> X = [[0], [1], [2], [3]]
>>> y = [0, 0, 1, 1]
>>> from sklearn.neighbors import RadiusNeighborsRegressor
>>> neigh = RadiusNeighborsRegressor(radius=1.0)
>>> neigh.fit(X, y)
RadiusNeighborsRegressor(...)
>>> print(neigh.predict([[1.5]]))
[0.5]
```

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<td>get_params([deep])</td>
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<tr>
<td>radius_neighbors([X, radius,...])</td>
<td>Finds the neighbors within a given radius of a point or points.</td>
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<tr>
<td>radius_neighbors_graph([X, radius, mode,...])</td>
<td>Computes the (weighted) graph of Neighbors for points in X</td>
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<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
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<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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**fit** $(X, y)$

Fit the radius neighbors regressor from the training dataset.

**Parameters**

- $X$ [[array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples) if metric='precomputed'] Training data.
- $y$ [[array-like, sparse matrix] of shape (n_samples,) or (n_samples, n_outputs)] Target values.

**Returns**


**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params` [dict] Parameter names mapped to their values.

**predict** $(X)$

Predict the target for the provided data.

**Parameters**

- $X$ [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'precomputed'] Test samples.

**Returns**

- $y$ [ndarray of shape (n_queries,) or (n_queries, n_outputs), dtype=double] Target values.

**radius_neighbors** *(X=None, radius=None, return_distance=True, sort_results=False)*

Finds the neighbors within a given radius of a point or points. Return the indices and distances of each point from the dataset lying in a ball with size $radius$ around the points of the query array. Points lying on the boundary are included in the results.

The result points are not necessarily sorted by distance to their query point.

**Parameters**

- $X$ [array-like of (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.
- $radius$ [float, default=None] Limiting distance of neighbors to return. The default is the value passed to the constructor.
- `return_distance` [bool, default=True] Whether or not to return the distances.
sort_results [bool, default=False] If True, the distances and indices will be sorted by increasing distances before being returned. If False, the results may not be sorted. If return_distance=False, setting sort_results=True will result in an error.

New in version 0.22.

Returns

neigh_dist [ndarray of shape (n_samples,) of arrays] Array representing the distances to each point, only present if return_distance=True. The distance values are computed according to the metric constructor parameter.

neigh_ind [ndarray of shape (n_samples,) of arrays] An array of arrays of indices of the approximate nearest points from the population matrix that lie within a ball of size radius around the query points.

Notes

Because the number of neighbors of each point is not necessarily equal, the results for multiple query points cannot be fit in a standard data array. For efficiency, radius_neighbors returns arrays of objects, where each object is a 1D array of indices or distances.

Examples

In the following example, we construct a NeighborsClassifier class from an array representing our data set and ask who’s the closest point to [1, 1, 1]:

```python
>>> import numpy as np
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.6)
>>> neigh.fit(samples)
NearestNeighbors(radius=1.6)
>>> rng = neigh.radius_neighbors([[1., 1., 1.]])
>>> print(np.asarray(rng[0][0]))
[1.5 0.5]
>>> print(np.asarray(rng[1][0]))
[1 2]
```

The first array returned contains the distances to all points which are closer than 1.6, while the second array returned contains their indices. In general, multiple points can be queried at the same time.

radius_neighbors_graph (X=None, radius=None, mode='connectivity', sort_results=False)
Computes the (weighted) graph of Neighbors for points in X

Neighborhoods are restricted the points at a distance lower than radius.

Parameters

X [array-like of shape (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

radius [float, default=None] Radius of neighborhoods. The default is the value passed to the constructor.

mode [‘{‘connectivity’, ‘distance’}, default=’connectivity’] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.
sort_results [bool, default=False] If True, in each row of the result, the non-zero entries will be sorted by increasing distances. If False, the non-zero entries may not be sorted. Only used with mode='distance'.

New in version 0.22.

Returns

A [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix if of format CSR.

See also:

kneighbors_graph

Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.5)
>>> neigh.fit(X)
NearestNeighbors(radius=1.5)
>>> A = neigh.radius_neighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 0.],
       [1., 0., 1.]])
```

score (X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares \((y_{true} - y_{pred})**2\).sum() and $v$ is the total sum of squares \((y_{true} - y_{true}.mean())**2\).sum(). The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y [array-like of shape (n_samples,)] or (n_samples, n_outputs)] True values for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict(X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.30.11 sklearn.neighbors.RadiusNeighborsTransformer

class sklearn.neighbors.RadiusNeighborsTransformer(*, mode='distance', radius=1.0, algorithm='auto', leaf_size=30, metric='minkowski', p=2, metric_params=None, n_jobs=1)

Transform X into a (weighted) graph of neighbors nearer than a radius.

The transformed data is a sparse graph as returned by `radius_neighbors_graph`.

Read more in the User Guide.

New in version 0.22.

Parameters

mode [({'distance', 'connectivity'}, default='distance')] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, and ‘distance’ will return the distances between neighbors according to the given metric.

radius [float, default=1.] Radius of neighborhood in the transformed sparse graph.

algorithm [({'auto', 'ball_tree', 'kd_tree', 'brute'}, default='auto')] Algorithm used to compute the nearest neighbors:

- ‘ball_tree’ will use `BallTree`
- ‘kd_tree’ will use `KDTree`
- ‘brute’ will use a brute-force search.
- ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to `fit` method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

leaf_size [int, default=30] Leaf size passed to `BallTree` or `KDTree`. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.
metric [str or callable, default='minkowski'] metric to use for distance computation. Any metric from scikit-learn or scipy.spatial.distance can be used.

If metric is a callable function, it is called on each pair of instances (rows) and the resulting value recorded. The callable should take two arrays as input and return one value indicating the distance between them. This works for Scipy’s metrics, but is less efficient than passing the metric name as a string.

Distance matrices are not supported.

Valid values for metric are:

- from scikit-learn: ['cityblock', 'cosine', 'euclidean', 'l1', 'l2', 'manhattan']

See the documentation for scipy.spatial.distance for details on these metrics.

p [int, default=2] Parameter for the Minkowski metric from sklearn.metrics.pairwise.pairwise_distances. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

metric_params [dict, default=None] Additional keyword arguments for the metric function.

n_jobs [int, default=1] The number of parallel jobs to run for neighbors search. If -1, then the number of jobs is set to the number of CPU cores.

Attributes

effective_metric_ [str or callable] The distance metric used. It will be same as the metric parameter or a synonym of it, e.g. ‘euclidean’ if the metric parameter set to ‘minkowski’ and p parameter set to 2.

effective_metric_params_ [dict] Additional keyword arguments for the metric function. For most metrics will be same with metric_params parameter, but may also contain the p parameter value if the effective_metric attribute is set to ‘minkowski’.

n_samples_fit_ [int] Number of samples in the fitted data.

Examples

```python
>>> from sklearn.cluster import DBSCAN
>>> from sklearn.neighbors import RadiusNeighborsTransformer
>>> from sklearn.pipeline import make_pipeline
>>> estimator = make_pipeline(
...   RadiusNeighborsTransformer(radius=42.0, mode='distance'),
...   DBSCAN(min_samples=30, metric='precomputed'))
```
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**fit (X, y=None)**
Fit the radius neighbors transformer from the training dataset.

Parameters

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features) or (n_samples, n_samples) if metric='precomputed'] Training data.

Returns

- **self** [RadiusNeighborsTransformer] The fitted radius neighbors transformer.

**fit_transform (X, y=None)**
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Training set.
- **y** [ignored]

Returns

- **Xt** [sparse matrix of shape (n_samples, n_samples)] Xt[i, j] is assigned the weight of edge that connects i to j. Only the neighbors have an explicit value. The diagonal is always explicit. The matrix is of CSR format.

**get_params (deep=True)**
Get parameters for this estimator.

Parameters

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** [dict] Parameter names mapped to their values.

**radius_neighbors (X=None, radius=None, return_distance=True, sort_results=False)**
Finds the neighbors within a given radius of a point or points.

Return the indices and distances of each point from the dataset lying in a ball with size radius around the points of the query array. Points lying on the boundary are included in the results.

The result points are not necessarily sorted by distance to their query point.
Parameters

- **X** [array-like of (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

- **radius** [float, default=None] Limiting distance of neighbors to return. The default is the value passed to the constructor.

- **return_distance** [bool, default=True] Whether or not to return the distances.

- **sort_results** [bool, default=False] If True, the distances and indices will be sorted by increasing distances before being returned. If False, the results may not be sorted. If return_distance=False, setting sort_results=True will result in an error.

New in version 0.22.

Returns

- **neigh_dist** [ndarray of shape (n_samples,) of arrays] Array representing the distances to each point, only present if return_distance=True. The distance values are computed according to the metric constructor parameter.

- **neigh_ind** [ndarray of shape (n_samples,) of arrays] An array of arrays of indices of the approximate nearest points from the population matrix that lie within a ball of size radius around the query points.

Notes

Because the number of neighbors of each point is not necessarily equal, the results for multiple query points cannot be fit in a standard data array. For efficiency, `radius_neighbors` returns arrays of objects, where each object is a 1D array of indices or distances.

Examples

In the following example, we construct a NeighborsClassifier class from an array representing our data set and ask who’s the closest point to [1, 1, 1]:

```python
>>> import numpy as np
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.6)
>>> neigh.fit(samples)
NearestNeighbors(radius=1.6)
>>> rng = neigh.radius_neighbors([[1., 1., 1.]])
>>> print(np.asarray(rng[0][0]))
[1.5 0.5]
>>> print(np.asarray(rng[1][0]))
[1 2]
```

The first array returned contains the distances to all points which are closer than 1.6, while the second array returned contains their indices. In general, multiple points can be queried at the same time.

`radius_neighbors_graph` (**X**, **radius**, **mode**, **sort_results**) Computes the (weighted) graph of Neighbors for points in X

Neighborhoods are restricted the points at a distance lower than radius.
X [array-like of shape (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

radius [float, default=None] Radius of neighborhoods. The default is the value passed to the constructor.

mode [‘connectivity’, ‘distance’], default=’connectivity’ Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

sort_results [bool, default=False] If True, in each row of the result, the non-zero entries will be sorted by increasing distances. If False, the non-zero entries may not be sorted. Only used with mode=’distance’.

New in version 0.22.

Returns

A [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix if of format CSR.

See also:

kneighbors_graph

Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.5)
>>> neigh.fit(X)
NearestNeighbors(radius=1.5)
>>> A = neigh.radius_neighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 0.],
       [1., 0., 1.]])
```

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Computes the (weighted) graph of Neighbors for points in X

Parameters

X [array-like of shape (n_samples_transform, n_features)] Sample data
Returns

$X_t$ [sparse matrix of shape (n_samples_transform, n_samples_fit)] $X_t[i, j]$ is assigned the weight of edge that connects $i$ to $j$. Only the neighbors have an explicit value. The diagonal is always explicit. The matrix is of CSR format.

7.30.12 sklearn.neighbors.NearestCentroid

class sklearn.neighbors.NearestCentroid (metric='euclidean', *, shrink_threshold=None)

Nearest centroid classifier.

Each class is represented by its centroid, with test samples classified to the class with the nearest centroid.

Read more in the User Guide.

Parameters

- **metric** [str or callable] The metric to use when calculating distance between instances in a feature array. If metric is a string or callable, it must be one of the options allowed by metrics.pairwise.pairwise_distances for its metric parameter. The centroids for the samples corresponding to each class is the point from which the sum of the distances (according to the metric) of all samples that belong to that particular class are minimized. If the “manhattan” metric is provided, this centroid is the median and for all other metrics, the centroid is now set to be the mean.

  Changed in version 0.19: metric='precomputed' was deprecated and now raises an error

- **shrink_threshold** [float, default=None] Threshold for shrinking centroids to remove features.

Attributes

- **centroids_** [array-like of shape (n_classes, n_features)] Centroid of each class.

- **classes_** [array of shape (n_classes,)] The unique classes labels.

See also:

KNeighborsClassifier Nearest neighbors classifier.

Notes

When used for text classification with tf-idf vectors, this classifier is also known as the Rocchio classifier.

References

Examples

```python
>>> from sklearn.neighbors import NearestCentroid
>>> import numpy as np

>>> X = np.array([[-1, -1], [-2, -1], [-3, -2], [1, 1], [2, 1], [3, 2]])

>>> y = np.array([1, 1, 1, 2, 2, 2])

>>> clf = NearestCentroid()

>>> clf.fit(X, y)

>>> print(clf.predict([[-0.8, -1]]))
[1]
```

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<td><code>score(X, y[, sample_weight])</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
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<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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</table>

**fit (X, y)**
Fit the NearestCentroid model according to the given training data.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) Training vector, where n_samples is the number of samples and n_features is the number of features. Note that centroid shrinking cannot be used with sparse matrices.
- **y** [array-like of shape (n_samples,)] Target values (integers)

**get_params (deep=True)**
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**predict (X)**
Perform classification on an array of test vectors X.

The predicted class C for each sample in X is returned.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)]

**Returns**

- **C** [ndarray of shape (n_samples,)]
Notes

If the metric constructor parameter is “precomputed”, X is assumed to be the distance matrix between the
data to be predicted and self.centroids_.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each
sample that each label set be correctly predicted.

Parameters

- X [array-like of shape (n_samples, n_features)] Test samples.
- y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
- sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

- score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

- **params [dict] Estimator parameters.

Returns


Examples using sklearn.neighbors.NearestCentroid

- Nearest Centroid Classification
- Classification of text documents using sparse features

7.30.13 sklearn.neighbors.NearestNeighbors

class sklearn.neighbors.NearestNeighbors(*, n_neighbors=5, radius=1.0, algorithm='auto',
leaf_size=30, metric='minkowski', p=2, metric_params=None, n_jobs=None)

Unsupervised learner for implementing neighbor searches.

Read more in the User Guide.

New in version 0.9.

Parameters

- n_neighbors [int, default=5] Number of neighbors to use by default for kneighbors queries.
- radius [float, default=1.0] Range of parameter space to use by default for
  radius_neighbors queries.
algorithm

Algorithm used to compute the nearest neighbors:

- ‘ball_tree’ will use BallTree
- ‘kd_tree’ will use KDTree
- ‘brute’ will use a brute-force search.
- ‘auto’ will attempt to decide the most appropriate algorithm based on the values passed to fit method.

Note: fitting on sparse input will override the setting of this parameter, using brute force.

leaf_size

Leaf size passed to BallTree or KDTree. This can affect the speed of the construction and query, as well as the memory required to store the tree. The optimal value depends on the nature of the problem.

metric

The distance metric to use for the tree. The default metric is minkowski, and with p=2 is equivalent to the standard Euclidean metric. See the documentation of DistanceMetric for a list of available metrics. If metric is “precomputed”, X is assumed to be a distance matrix and must be square during fit. X may be a sparse graph, in which case only “nonzero” elements may be considered neighbors.

p

Parameter for the Minkowski metric from sklearn.metrics.pairwise.pairwise_distances. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

metric_params

Additional keyword arguments for the metric function.

n_jobs

The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

effective_metric_

Metric used to compute distances to neighbors.

effective_metric_params_

Parameters for the metric used to compute distances to neighbors.

n_samples_fit_

Number of samples in the fitted data.

See also:

KNeighborsClassifier
RadiusNeighborsClassifier
KNeighborsRegressor
RadiusNeighborsRegressor
BallTree
Notes

See *Nearest Neighbors* in the online documentation for a discussion of the choice of algorithm and leaf_size.


Examples

```python
>>> import numpy as np
>>> from sklearn.neighbors import NearestNeighbors

>>> samples = [[0, 0, 2], [1, 0, 0], [0, 0, 1]]

>>> neigh = NearestNeighbors(n_neighbors=2, radius=0.4)
>>> neigh.fit(samples)
NearestNeighbors(...)

>>> neigh.kneighbors([[0, 0, 1.3]], 2, return_distance=False)
array([[2, 0]], ...)

>>> nbrs = neigh.radius_neighbors(
    ... [[0, 0, 1.3]], 0.4, return_distance=False
    ... )
>>> np.asarray(nbrs[0][0])
array(2)
```

Methods

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<td><code>kneighbors([X, n_neighbors, return_distance])</code></td>
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<td>Computes the (weighted) graph of k-Neighbors for points in X</td>
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<tr>
<td><code>radius_neighbors([X, radius, ...])</code></td>
<td>Finds the neighbors within a given radius of a point or points.</td>
</tr>
<tr>
<td><code>radius_neighbors_graph([X, radius, mode, ...])</code></td>
<td>Computes the (weighted) graph of Neighbors for points in X</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

**fit (X, y=None)**

Fit the nearest neighbors estimator from the training dataset.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples) if metric='precomputed') Training data.

**Returns**

get_params (deep=True)
Get parameters for this estimator.

Parameters

deepe [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

kneighbors (X=None, n_neighbors=None, return_distance=True)
Finds the K-neighbors of a point.

Returns indices of and distances to the neighbors of each point.

Parameters

X [array-like, shape (n_queries, n_features), or (n_queries, n_indexed) if metric == 'pre-computed', default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.
n_neighbors [int, default=None] Number of neighbors required for each sample. The default is the value passed to the constructor.
return_distance [bool, default=True] Whether or not to return the distances.

Returns

neigh_dist [ndarray of shape (n_queries, n_neighbors)] Array representing the lengths to points, only present if return_distance=True
neigh_ind [ndarray of shape (n_queries, n_neighbors)] Indices of the nearest points in the population matrix.

Examples

In the following example, we construct a NearestNeighbors class from an array representing our data set and ask who’s the closest point to [1,1,1]

```python
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=1)
>>> neigh.fit(samples)
NearestNeighbors(n_neighbors=1)
>>> print(neigh.kneighbors([[1., 1., 1.]]))
(array([[0.5]]), array([[2]]))
```

As you can see, it returns [[0.5]], and [[2]], which means that the element is at distance 0.5 and is the third element of samples (indexes start at 0). You can also query for multiple points:

```python
>>> X = [[0., 1., 0.], [1., 0., 1.]]
>>> neigh.kneighbors(X, return_distance=False)
array([[1.],
       [2]])...
```

kneighbors_graph (X=None, n_neighbors=None, mode='connectivity')
Computes the (weighted) graph of k-Neighbors for points in X

Parameters
X [array-like of shape (n_queries, n_features), or (n_queries, n_indexed) if metric == ‘pre-computed’, default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor. For metric='precomputed' the shape should be (n_queries, n_indexed). Otherwise the shape should be (n_queries, n_features).

n_neighbors [int, default=None] Number of neighbors for each sample. The default is the value passed to the constructor.

mode [{'connectivity', 'distance'}, default='connectivity'] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

Returns

A [sparse-matrix of shape (n_queries, n_samples_fit)] n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

See also:

NearestNeighbors.radius_neighbors_graph

Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(n_neighbors=2)
>>> neigh.fit(X)
NearestNeighbors(n_neighbors=2)
>>> A = neigh.kneighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 1.],
       [1., 0., 1.]])
```

radius_neighbors (X=None, radius=None, return_distance=True, sort_results=False) Finds the neighbors within a given radius of a point or points.

Return the indices and distances of each point from the dataset lying in a ball with size radius around the points of the query array. Points lying on the boundary are included in the results.

The result points are not necessarily sorted by distance to their query point.

Parameters

X [array-like of (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

radius [float, default=None] Limiting distance of neighbors to return. The default is the value passed to the constructor.

return_distance [bool, default=True] Whether or not to return the distances.

sort_results [bool, default=False] If True, the distances and indices will be sorted by increasing distances before being returned. If False, the results may not be sorted. If return_distance=False, setting sort_results=True will result in an error.

New in version 0.22.
Returns

**neigh_dist** [ndarray of shape (n_samples,) of arrays] Array representing the distances to each point, only present if `return_distance=True`. The distance values are computed according to the `metric` constructor parameter.

**neigh_ind** [ndarray of shape (n_samples,) of arrays] An array of arrays of indices of the approximate nearest points from the population matrix that lie within a ball of size `radius` around the query points.

Notes

Because the number of neighbors of each point is not necessarily equal, the results for multiple query points cannot be fit in a standard data array. For efficiency, `radius_neighbors` returns arrays of objects, where each object is a 1D array of indices or distances.

Examples

In the following example, we construct a NeighborsClassifier class from an array representing our data set and ask who’s the closest point to \( [1, 1, 1] \):

```python
>>> import numpy as np
>>> samples = [[0., 0., 0.], [0., .5, 0.], [1., 1., .5]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.6)
>>> neigh.fit(samples)
NearestNeighbors(radius=1.6)
>>> rng = neigh.radius_neighbors([[1., 1., 1.]])
>>> print(np.asarray(rng[0][0]))
[1.5 0.5]
>>> print(np.asarray(rng[1][0]))
[1 2]
```

The first array returned contains the distances to all points which are closer than 1.6, while the second array returned contains their indices. In general, multiple points can be queried at the same time.

**radius_neighbors_graph** (X=None, radius=None, mode='connectivity', sort_results=False)

Computes the (weighted) graph of Neighbors for points in X

Neighborhoods are restricted the points at a distance lower than radius.

Parameters

**X** [array-like of shape (n_samples, n_features), default=None] The query point or points. If not provided, neighbors of each indexed point are returned. In this case, the query point is not considered its own neighbor.

**radius** [float, default=None] Radius of neighborhoods. The default is the value passed to the constructor.

**mode** ['connectivity', 'distance'], default='connectivity'] Type of returned matrix: ‘connectivity’ will return the connectivity matrix with ones and zeros, in ‘distance’ the edges are Euclidean distance between points.

**sort_results** [bool, default=False] If True, in each row of the result, the non-zero entries will be sorted by increasing distances. If False, the non-zero entries may not be sorted. Only used with mode='distance'.

New in version 0.22.
Returns

A [sparse-matrix of shape (n_queries, n_samples_fit)]

n_samples_fit is the number of samples in the fitted data A[i, j] is assigned the weight of edge that connects i to j. The matrix if of format CSR.

See also:

kneighbors_graph

Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import NearestNeighbors
>>> neigh = NearestNeighbors(radius=1.5)
>>> neigh.fit(X)
NearestNeighbors(radius=1.5)
>>> A = neigh.radius_neighbors_graph(X)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 0.],
       [1., 0., 1.]])
```

set_params(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.30.14 sklearn.neighbors.NeighborhoodComponentsAnalysis

class sklearn.neighbors.NeighborhoodComponentsAnalysis (n_components=None,

*,

init='auto',

warm_start=False,

max_iter=50,

tol=1e-05,

callback=None,

verbose=0,

random_state=None)

Neighborhood Components Analysis

Neighborhood Component Analysis (NCA) is a machine learning algorithm for metric learning. It learns a linear transformation in a supervised fashion to improve the classification accuracy of a stochastic nearest neighbors rule in the transformed space.

Read more in the User Guide.

Parameters

n_components [int, default=None] Preferred dimensionality of the projected space. If None it will be set to n_features.
**init** [\{'auto', 'pca', 'lda', 'identity', 'random'\} or ndarray of shape (n_features_a, n_features_b), default='auto'] Initialization of the linear transformation. Possible options are 'auto', 'pca', 'lda', 'identity', 'random', and a numpy array of shape (n_features_a, n_features_b).

- **'auto'** Depending on n_components, the most reasonable initialization will be chosen. If n_components <= n_classes we use 'lda', as it uses labels information. If not, but n_components < min(n_features, n_samples), we use 'pca', as it projects data in meaningful directions (those of higher variance). Otherwise, we just use 'identity'.
  - **'pca'** n_components principal components of the inputs passed to fit will be used to initialize the transformation. (See PCA)
  - **'lda'** min(n_components, n_classes) most discriminative components of the inputs passed to fit will be used to initialize the transformation. (If n_components > n_classes, the rest of the components will be zero.) (See LinearDiscriminantAnalysis)
  - **'identity'** If n_components is strictly smaller than the dimensionality of the inputs passed to fit, the identity matrix will be truncated to the first n_components rows.
  - **'random'** The initial transformation will be a random array of shape (n_components, n_features). Each value is sampled from the standard normal distribution.

**numpy array** n_features_b must match the dimensionality of the inputs passed to fit and n_features_a must be less than or equal to that. If n_components is not None, n_features_a must match it.

**warm_start** [bool, default=False] If True and fit has been called before, the solution of the previous call to fit is used as the initial linear transformation (n_components and init will be ignored).

**max_iter** [int, default=50] Maximum number of iterations in the optimization.

**tol** [float, default=1e-5] Convergence tolerance for the optimization.

**callback** [callable, default=None] If not None, this function is called after every iteration of the optimizer, taking as arguments the current solution (flattened transformation matrix) and the number of iterations. This might be useful in case one wants to examine or store the transformation found after each iteration.

**verbose** [int, default=0] If 0, no progress messages will be printed. If 1, progress messages will be printed to stdout. If > 1, progress messages will be printed and the disp parameter of scipy.optimize.minimize will be set to verbose - 2.

**random_state** [int or numpy.RandomState, default=None] A pseudo random number generator object or a seed for it if int. If init='random', random_state is used to initialize the random transformation. If init='pca', random_state is passed as an argument to PCA when initializing the transformation. Pass an int for reproducible results across multiple function calls. See :term: Glossary <random_state>.

**Attributes**

- **components_** [ndarray of shape (n_components, n_features)] The linear transformation learned during fitting.
- **n_iter_** [int] Counts the number of iterations performed by the optimizer.
- **random_state_** [numpy.RandomState] Pseudo random number generator object used during initialization.
References

[1]. [2]

Examples

```python
>>> from sklearn.neighbors import NeighborhoodComponentsAnalysis
>>> from sklearn.neighbors import KNeighborsClassifier
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split

>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, ...
... stratify=y, test_size=0.7, random_state=42)
>>> nca = NeighborhoodComponentsAnalysis(random_state=42)
>>> nca.fit(X_train, y_train)
NeighborhoodComponentsAnalysis(...)
>>> knn = KNeighborsClassifier(n_neighbors=3)
>>> knn.fit(X_train, y_train)
KNeighborsClassifier(...)
>>> print(knn.score(X_test, y_test))
0.933333...
>>> knn.fit(nca.transform(X_train), y_train)
KNeighborsClassifier(...)
>>> print(knn.score(nca.transform(X_test), y_test))
0.961904...
```

Methods

```markdown
<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
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<tbody>
<tr>
<td>fit(X, y)</td>
<td>Fit the model according to the given training data.</td>
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<td>fit_transform(X[, y])</td>
<td>Fit to data, then transform it.</td>
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<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>set_params(**params)</td>
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</tr>
<tr>
<td>transform(X)</td>
<td>Applies the learned transformation to the given data.</td>
</tr>
</tbody>
</table>
```

**`fit (X, y)`**

Fit the model according to the given training data.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] The training samples.
- `y` [array-like of shape (n_samples,)] The corresponding training labels.

**Returns**

- `self` [object] returns a trained NeighborhoodComponentsAnalysis model.

**`fit_transform (X, y=None, **fit_params)`**

Fit to data, then transform it.

Fits transformer to `X` and `y` with optional parameters `fit_params` and returns a transformed version of `X`.

**Parameters**

- `X` [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)
Applies the learned transformation to the given data.

Parameters

X [array-like of shape (n_samples, n_features)] Data samples.

Returns

X_embedded: ndarray of shape (n_samples, n_components) The data samples transformed.

Raises

NotFittedError If fit has not been called before.

Examples using sklearn.neighbors.NeighborhoodComponentsAnalysis

- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap…
- Neighborhood Components Analysis Illustration
- Comparing Nearest Neighbors with and without Neighborhood Components Analysis
- Dimensionality Reduction with Neighborhood Components Analysis

neighbors.kneighbors_graph(X, n_neighbors, *) Computes the (weighted) graph of k-Neighbors for points in X
**7.30.15 sklearn.neighbors.kneighbors_graph**

sklearn.neighbors.kneighbors_graph (X, n_neighbors, *, mode='connectivity', metric='minkowski', p=2, metric_params=None, include_self=False, n_jobs=None)

Computes the (weighted) graph of k-Neighbors for points in X

Read more in the User Guide.

**Parameters**

- **X** [array-like of shape (n_samples, n_features) or BallTree] Sample data, in the form of a numpy array or a precomputed BallTree.

- **n_neighbors** [int] Number of neighbors for each sample.

- **mode** ['connectivity', 'distance', default='connectivity'] Type of returned matrix: 'connectivity' will return the connectivity matrix with ones and zeros, and 'distance' will return the distances between neighbors according to the given metric.

- **metric** [str, default='minkowski'] The distance metric used to calculate the k-Neighbors for each sample point. The DistanceMetric class gives a list of available metrics. The default distance is 'euclidean' ('minkowski' metric with the p param equal to 2.)

- **p** [int, default=2] Power parameter for the Minkowski metric. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.

- **metric_params** [dict, default=None] additional keyword arguments for the metric function.

- **include_self** [bool or 'auto', default=False] Whether or not to mark each sample as the first nearest neighbor to itself. If 'auto', then True is used for mode='connectivity' and False for mode='distance'.

- **n_jobs** [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

**Returns**

- **A** [sparse matrix of shape (n_samples, n_samples)] Graph where A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

See also:

radius_neighbors_graph
Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import kneighbors_graph
>>> A = kneighbors_graph(X, 2, mode='connectivity', include_self=True)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 1.],
       [1., 0., 1.]])
```

Examples using `sklearn.neighbors.kneighbors_graph`

- Agglomerative clustering with and without structure
- Hierarchical clustering: structured vs unstructured ward
- Comparing different clustering algorithms on toy datasets

7.30.16 `sklearn.neighbors.radius_neighbors_graph`

`sklearn.neighbors.radius_neighbors_graph` computes the (weighted) graph of Neighbors for points in `X`.

Parameters:

- `X` [array-like of shape (n_samples, n_features) or BallTree] Sample data, in the form of a numpy array or a precomputed BallTree.
- `radius` [float] Radius of neighborhoods.
- `mode` [str, default='connectivity'] Type of returned matrix: 'connectivity' will return the connectivity matrix with ones and zeros, and 'distance' will return the distances between neighbors according to the given metric.
- `metric` [str, default='minkowski'] The distance metric used to calculate the neighbors within a given radius for each sample point. The DistanceMetric class gives a list of available metrics. The default distance is 'euclidean' ('minkowski' metric with the param equal to 2.)
- `p` [int, default=2] Power parameter for the Minkowski metric. When p = 1, this is equivalent to using manhattan_distance (l1), and euclidean_distance (l2) for p = 2. For arbitrary p, minkowski_distance (l_p) is used.
- `metric_params` [dict, default=None] additional keyword arguments for the metric function.
- `include_self` [bool or 'auto', default=False] Whether or not to mark each sample as the first nearest neighbor to itself. If 'auto', then True is used for mode='connectivity' and False for mode='distance'.
- `n_jobs` [int, default=None] The number of parallel jobs to run for neighbors search. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Returns
A [sparse matrix of shape (n_samples, n_samples)] Graph where A[i, j] is assigned the weight of edge that connects i to j. The matrix is of CSR format.

See also:

**kneighbors_graph**

Examples

```python
>>> X = [[0], [3], [1]]
>>> from sklearn.neighbors import radius_neighbors_graph
>>> A = radius_neighbors_graph(X, 1.5, mode='connectivity',
...  include_self=True)
>>> A.toarray()
array([[1., 0., 1.],
       [0., 1., 0.],
       [1., 0., 1.]])
```

### 7.31 sklearn.neural_network: Neural network models

The `sklearn.neural_network` module includes models based on neural networks.

**User guide:** See the Neural network models (supervised) and Neural network models (unsupervised) sections for further details.


#### 7.31.1 sklearn.neural_network.BernoulliRBM

```python
class sklearn.neural_network.BernoulliRBM(n_components=256, *, learning_rate=0.1,
batch_size=10, n_iter=10, verbose=0, random_state=None)
```

Bernoulli Restricted Boltzmann Machine (RBM).

A Restricted Boltzmann Machine with binary visible units and binary hidden units. Parameters are estimated using Stochastic Maximum Likelihood (SML), also known as Persistent Contrastive Divergence (PCD) [2].

The time complexity of this implementation is $O(d \times n)$ assuming $d \sim n_{\text{features}} \sim n_{\text{components}}$.

Read more in the User Guide.

**Parameters**

- `n_components` [int, default=256] Number of binary hidden units.
- `learning_rate` [float, default=0.1] The learning rate for weight updates. It is highly recommended to tune this hyper-parameter. Reasonable values are in the $10^{0.1}$ range.
- `batch_size` [int, default=10] Number of examples per minibatch.
- `n_iter` [int, default=10] Number of iterations/sweeps over the training dataset to perform during training.
verbose [int, default=0] The verbosity level. The default, zero, means silent mode.

random_state [int, RandomState instance or None, default=None] Determines random number generation for:
  • Gibbs sampling from visible and hidden layers.
  • Initializing components, sampling from layers during fit.
  • Corrupting the data when scoring samples.

Pass an int for reproducible results across multiple function calls. See Glossary.

Attributes

intercept_hidden_ [array-like of shape (n_components,)] Biases of the hidden units.

intercept_visible_ [array-like of shape (n_features,)] Biases of the visible units.

components_ [array-like of shape (n_components, n_features)] Weight matrix, where
n_features in the number of visible units and n_components is the number of hidden units.

h_samples_ [array-like of shape (batch_size, n_components)] Hidden Activation sampled from
the model distribution, where batch_size is the number of examples per minibatch and
n_components is the number of hidden units.

References


Examples

```python
>>> import numpy as np
>>> from sklearn.neural_network import BernoulliRBM
>>> X = np.array([[0, 0, 0], [0, 1, 1], [1, 0, 1], [1, 1, 1]])
>>> model = BernoulliRBM(n_components=2)
>>> model.fit(X)
```

Methods

<table>
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<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>fit(X[, y])</code></td>
<td>Fit the model to the data X.</td>
</tr>
<tr>
<td><code>fit_transform(X[, y])</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>gibbs(v)</code></td>
<td>Perform one Gibbs sampling step.</td>
</tr>
<tr>
<td><code>partial_fit(X[, y])</code></td>
<td>Fit the model to the data X which should contain a partial segment of the data.</td>
</tr>
<tr>
<td><code>score_samples(X)</code></td>
<td>Compute the pseudo-likelihood of X.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Compute the hidden layer activation probabilities, P(h=1</td>
</tr>
</tbody>
</table>
**fit** *(X, y=None)*  
Fit the model to the data X.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) Training data.

**Returns**

- **self** [BernoulliRBM] The fitted model.

**fit_transform** *(X, y=None, **fit_params)*  
Fit to data, then transform it.

Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params** *(deep=True)*  
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**gibbs** *(v)*  
Perform one Gibbs sampling step.

**Parameters**

- **v** [ndarray of shape (n_samples, n_features)] Values of the visible layer to start from.

**Returns**

- **v_new** [ndarray of shape (n_samples, n_features)] Values of the visible layer after one Gibbs step.

**partial_fit** *(X, y=None)*  
Fit the model to the data X which should contain a partial segment of the data.

**Parameters**

- **X** [ndarray of shape (n_samples, n_features)] Training data.

**Returns**

- **self** [BernoulliRBM] The fitted model.

**score_samples** *(X)*  
Compute the pseudo-likelihood of X.
Parameters

X  ([array-like, sparse matrix] of shape (n_samples, n_features)) Values of the visible layer. Must be all-boolean (not checked).

Returns

pseudo_likelihood  [ndarray of shape (n_samples,)] Value of the pseudo-likelihood (proxy for likelihood).

Notes

This method is not deterministic: it computes a quantity called the free energy on X, then on a randomly corrupted version of X, and returns the log of the logistic function of the difference.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform (X)

Compute the hidden layer activation probabilities, \( P(h=1|v=X) \).

Parameters

X  ([array-like, sparse matrix] of shape (n_samples, n_features)) The data to be transformed.

Returns

h  [ndarray of shape (n_samples, n_components)] Latent representations of the data.

Examples using sklearn.neural_network.BernoulliRBM

• Restricted Boltzmann Machine features for digit classification
7.31.2 sklearn.neural_network.MLPClassifier

class sklearn.neural_network.MLPClassifier(hidden_layer_sizes=100, activation='relu', *, solver='adam', alpha=0.0001, batch_size='auto', learning_rate='constant', learning_rate_init=0.001, power_t=0.5, max_iter=200, shuffle=True, random_state=None, tol=0.0001, verbose=False, warm_start=False, momentum=0.9, nesterovs_momentum=True, early_stopping=False, validation_fraction=0.1, beta_1=0.9, beta_2=0.999, epsilon=1e-08, n_iter_no_change=10, max_fun=15000)

Multi-layer Perceptron classifier.

This model optimizes the log-loss function using LBFGS or stochastic gradient descent.

New in version 0.18.

Parameters

hidden_layer_sizes [tuple, length = n_layers - 2, default=(100,)] The ith element represents the number of neurons in the ith hidden layer.


• ‘identity’, no-op activation, useful to implement linear bottleneck, returns f(x) = x
• ‘logistic’, the logistic sigmoid function, returns f(x) = 1 / (1 + exp(-x)).
• ‘tanh’, the hyperbolic tan function, returns f(x) = tanh(x).
• ‘relu’, the rectified linear unit function, returns f(x) = max(0, x)

solver [‘lbfgs’, ‘sgd’, ‘adam’], default=’adam’] The solver for weight optimization.

• ‘lbfgs’ is an optimizer in the family of quasi-Newton methods.
• ‘sgd’ refers to stochastic gradient descent.
• ‘adam’ refers to a stochastic gradient-based optimizer proposed by Kingma, Diederik, and Jimmy Ba

Note: The default solver ‘adam’ works pretty well on relatively large datasets (with thousands of training samples or more) in terms of both training time and validation score. For small datasets, however, ‘lbfgs’ can converge faster and perform better.

alpha [float, default=0.0001] L2 penalty (regularization term) parameter.

batch_size [int, default=’auto’] Size of minibatches for stochastic optimizers. If the solver is ‘lbfgs’, the classifier will not use minibatch. When set to “auto”, batch_size=min(200, n_samples)

learning_rate [‘constant’, ‘invscaling’, ‘adaptive’], default=’constant’] Learning rate schedule for weight updates.

• ‘constant’ is a constant learning rate given by ‘learning_rate_init’.
• ‘invscaling’ gradually decreases the learning rate at each time step ‘t’ using an inverse scaling exponent of ‘power_t’. effective_learning_rate = learning_rate_init / pow(t, power_t)
• ‘adaptive’ keeps the learning rate constant to ‘learning_rate_init’ as long as training loss keeps decreasing. Each time two consecutive epochs fail to decrease training loss by at least tol, or fail to increase validation score by at least tol if ‘early_stopping’ is on, the current learning rate is divided by 5.

Only used when solver='sgd'.

learning_rate_init [double, default=0.001] The initial learning rate used. It controls the step-size in updating the weights. Only used when solver='sgd' or 'adam'.

power_t [double, default=0.5] The exponent for inverse scaling learning rate. It is used in updating effective learning rate when the learning_rate is set to ‘invscaling’. Only used when solver='sgd'.

max_iter [int, default=200] Maximum number of iterations. The solver iterates until convergence (determined by ‘tol’) or this number of iterations. For stochastic solvers (‘sgd’, ‘adam’), note that this determines the number of epochs (how many times each data point will be used), not the number of gradient steps.

shuffle [bool, default=True] Whether to shuffle samples in each iteration. Only used when solver='sgd' or ‘adam’.

random_state [int, RandomState instance, default=None] Determines random number generation for weights and bias initialization, train-test split if early stopping is used, and batch sampling when solver='sgd' or ‘adam’. Pass an int for reproducible results across multiple function calls. See Glossary.

tol [float, default=1e-4] Tolerance for the optimization. When the loss or score is not improving by at least tol for n_iter_no_change consecutive iterations, unless learning_rate is set to ‘adaptive’, convergence is considered to be reached and training stops.

verbose [bool, default=False] Whether to print progress messages to stdout.

warm_start [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.

momentum [float, default=0.9] Momentum for gradient descent update. Should be between 0 and 1. Only used when solver='sgd'.

nesterovs_momentum [bool, default=True] Whether to use Nesterov’s momentum. Only used when solver='sgd’ and momentum > 0.

early_stopping [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to true, it will automatically set aside 10% of training data as validation and terminate training when validation score is not improving by at least tol for n_iter_no_change consecutive epochs. The split is stratified, except in a multilabel setting. Only effective when solver='sgd’ or ‘adam’.

validation_fraction [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True

beta_1 [float, default=0.9] Exponential decay rate for estimates of first moment vector in adam, should be in [0, 1). Only used when solver='adam’

beta_2 [float, default=0.999] Exponential decay rate for estimates of second moment vector in adam, should be in [0, 1). Only used when solver='adam’

epsilon [float, default=1e-8] Value for numerical stability in adam. Only used when solver='adam’
**n_iter_no_change** [int, default=10] Maximum number of epochs to not meet tol improvement. Only effective when solver='sgd' or 'adam'

New in version 0.20.

**max_fun** [int, default=15000] Only used when solver='lbfgs'. Maximum number of loss function calls. The solver iterates until convergence (determined by 'tol'), number of iterations reaches max_iter, or this number of loss function calls. Note that number of loss function calls will be greater than or equal to the number of iterations for the MLPClassifier.

New in version 0.22.

**Attributes**

- **classes_** [ndarray or list of ndarray of shape (n_classes,)] Class labels for each output.
- **loss_** [float] The current loss computed with the loss function.
- **best_loss_** [float] The minimum loss reached by the solver throughout fitting.
- **loss_curve_** [list of shape (n_iter_,)] The ith element in the list represents the loss at the ith iteration.
- **t_** [int] The number of training samples seen by the solver during fitting.
- **coeffs_** [list of shape (n_layers - 1,)] The ith element in the list represents the weight matrix corresponding to layer i.
- **intercepts_** [list of shape (n_layers - 1,)] The ith element in the list represents the bias vector corresponding to layer i + 1.
- **n_iter_** [int] The number of iterations the solver has ran.
- **n_layers_** [int] Number of layers.
- **n_outputs_** [int] Number of outputs.
- **out_activation_** [str] Name of the output activation function.

**Notes**

MLPClassifier trains iteratively since at each time step the partial derivatives of the loss function with respect to the model parameters are computed to update the parameters.

It can also have a regularization term added to the loss function that shrinks model parameters to prevent overfitting.

This implementation works with data represented as dense numpy arrays or sparse scipy arrays of floating point values.

**References**

Examples

```python
>>> from sklearn.neural_network import MLPClassifier
>>> from sklearn.datasets import make_classification
>>> from sklearn.model_selection import train_test_split

>>> X, y = make_classification(n_samples=100, random_state=1)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, stratify=y,
... random_state=1)

>>> clf = MLPClassifier(random_state=1, max_iter=300).fit(X_train, y_train)
>>> clf.predict_proba(X_test[:1])
array([[0.038..., 0.961...]])

>>> clf.predict(X_test[:5, :])
array([1, 0, 1, 0, 1])

>>> clf.score(X_test, y_test)
0.8...
```

Methods

```python
fit(X, y) Fit the model to data matrix X and target(s) y.

get_params([deep]) Get parameters for this estimator.

predict(X) Predict using the multi-layer perceptron classifier

predict_log_proba(X) Return the log of probability estimates.

predict_proba(X) Probability estimates.

score(X, y[, sample_weight]) Return the mean accuracy on the given test data and labels.

set_params(**params) Set the parameters of this estimator.
```

**fit (X, y)**

Fit the model to data matrix X and target(s) y.

**Parameters**

- **X** [ndarray or sparse matrix of shape (n_samples, n_features)] The input data.
- **y** [ndarray of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).

**Returns**

- **self** [returns a trained MLP model.]

**get_params (deep=True)**

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**property partial_fit**

Update the model with a single iteration over the given data.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.
y [array-like of shape (n_samples,)] The target values.

classes [array of shape (n_classes,), default=None] Classes across all calls to partial_fit.
Can be obtained via np.unique(y_all), where y_all is the target vector of the entire
dataset. This argument is required for the first call to partial_fit and can be omitted in the
subsequent calls. Note that y doesn’t need to contain all labels in classes.

Returns

self [returns a trained MLP model.]

predict (X)
Predict using the multi-layer perceptron classifier

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.

Returns

y [ndarray, shape (n_samples,) or (n_samples, n_classes)] The predicted classes.

predict_log_proba (X)
Return the log of probability estimates.

Parameters

X [ndarray of shape (n_samples, n_features)] The input data.

Returns

log_y_prob [ndarray of shape (n_samples, n_classes)] The predicted log-probability of the
sample for each class in the model, where classes are ordered as they are in self.
classes_. Equivalent to log(predict_proba(X))

predict_proba (X)
Probability estimates.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input data.

Returns

y_prob [ndarray of shape (n_samples, n_classes)] The predicted probability of the sample
for each class in the model, where classes are ordered as they are in self.classes_.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each
sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict (X) wrt. y.
set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.neural_network.MLPClassifier

- Classifier comparison
- Visualization of MLP weights on MNIST
- Compare Stochastic learning strategies for MLPClassifier
- Varying regularization in Multi-layer Perceptron

7.31.3 sklearn.neural_network.MLPRegressor

class sklearn.neural_network.MLPRegressor (hidden_layer_sizes=100, activation='relu', *, solver='adam', alpha=0.0001, batch_size='auto', learning_rate='constant', learning_rate_init=0.001, power_t=0.5, max_iter=200, shuffle=True, random_state=None, tol=0.0001, verbose=False, warm_start=False, momentum=0.9, nesterovs_momentum=True, early_stopping=False, validation_fraction=0.1, beta_1=0.9, beta_2=0.999, epsilon=1e-08, n_iter_no_change=10, max_fun=15000)

Multi-layer Perceptron regressor.

This model optimizes the squared-loss using LBFGS or stochastic gradient descent.

New in version 0.18.

Parameters

hidden_layer_sizes [tuple, length = n_layers - 2, default=(100,)] The ith element represents the number of neurons in the ith hidden layer.


- ‘identity’, no-op activation, useful to implement linear bottleneck, returns f(x) = x
- ‘logistic’, the logistic sigmoid function, returns f(x) = 1 / (1 + exp(-x)).
- ‘tanh’, the hyperbolic tan function, returns f(x) = tanh(x).
- ‘relu’, the rectified linear unit function, returns f(x) = max(0, x)

solver [‘lbfgs’, ‘sgd’, ‘adam’], default=’adam’] The solver for weight optimization.
• ‘lbfgs’ is an optimizer in the family of quasi-Newton methods.
• ‘sgd’ refers to stochastic gradient descent.
• ‘adam’ refers to a stochastic gradient-based optimizer proposed by Kingma, Diederik, and Jimmy Ba

Note: The default solver ‘adam’ works pretty well on relatively large datasets (with thousands of training samples or more) in terms of both training time and validation score. For small datasets, however, ‘lbfgs’ can converge faster and perform better.

**alpha** [float, default=0.0001] L2 penalty (regularization term) parameter.

**batch_size** [int, default=’auto’] Size of minibatches for stochastic optimizers. If the solver is ‘lbfgs’, the classifier will not use minibatch. When set to ‘auto’, batch_size=min(200, n_samples)

**learning_rate** [‘constant’, ‘invscaling’, ‘adaptive’], default=’constant’ Learning rate schedule for weight updates.

  • ‘constant’ is a constant learning rate given by ‘learning_rate_init’.
  • ‘invscaling’ gradually decreases the learning rate at each time step ‘t’ using an inverse scaling exponent of ‘power_t’. effective_learning_rate = learning_rate_init / pow(t, power_t)
  • ‘adaptive’ keeps the learning rate constant to ‘learning_rate_init’ as long as training loss keeps decreasing. Each time two consecutive epochs fail to decrease training loss by at least tol, or fail to increase validation score by at least tol if ‘early_stopping’ is on, the current learning rate is divided by 5.

  Only used when solver=’sgd’.

**learning_rate_init** [double, default=0.001] The initial learning rate used. It controls the stepsize in updating the weights. Only used when solver=’sgd’ or ‘adam’.

**power_t** [double, default=0.5] The exponent for inverse scaling learning rate. It is used in updating effective learning rate when the learning_rate is set to ‘invscaling’. Only used when solver=’sgd’.

**max_iter** [int, default=200] Maximum number of iterations. The solver iterates until convergence (determined by ‘tol’) or this number of iterations. For stochastic solvers (‘sgd’, ‘adam’), note that this determines the number of epochs (how many times each data point will be used), not the number of gradient steps.

**shuffle** [bool, default=True] Whether to shuffle samples in each iteration. Only used when solver=’sgd’ or ‘adam’.

**random_state** [int, RandomState instance, default=None] Determines random number generation for weights and bias initialization, train-test split if early stopping is used, and batch sampling when solver=’sgd’ or ‘adam’. Pass an int for reproducible results across multiple function calls. See Glossary.

**tol** [float, default=1e-4] Tolerance for the optimization. When the loss or score is not improving by at least tol for n_iter_no_change consecutive iterations, unless learning_rate is set to ‘adaptive’, convergence is considered to be reached and training stops.

**verbose** [bool, default=False] Whether to print progress messages to stdout.

**warm_start** [bool, default=False] When set to True, reuse the solution of the previous call to fit as initialization, otherwise, just erase the previous solution. See the Glossary.
**momentum** [float, default=0.9] Momentum for gradient descent update. Should be between 0 and 1. Only used when solver='sgd'.

**nesterovs_momentum** [bool, default=True] Whether to use Nesterov’s momentum. Only used when solver='sgd' and momentum > 0.

**early_stopping** [bool, default=False] Whether to use early stopping to terminate training when validation score is not improving. If set to true, it will automatically set aside 10% of training data as validation and terminate training when validation score is not improving by at least tol for n_iter_no_change consecutive epochs. Only effective when solver='sgd' or 'adam'

**validation_fraction** [float, default=0.1] The proportion of training data to set aside as validation set for early stopping. Must be between 0 and 1. Only used if early_stopping is True

**beta_1** [float, default=0.9] Exponential decay rate for estimates of first moment vector in adam, should be in [0, 1). Only used when solver='adam'

**beta_2** [float, default=0.999] Exponential decay rate for estimates of second moment vector in adam, should be in [0, 1). Only used when solver='adam'

**epsilon** [float, default=1e-8] Value for numerical stability in adam. Only used when solver='adam'

**n_iter_no_change** [int, default=10] Maximum number of epochs to not meet tol improvement. Only effective when solver='sgd' or 'adam'

    New in version 0.20.

**max_fun** [int, default=15000] Only used when solver='lbfgs'. Maximum number of function calls. The solver iterates until convergence (determined by 'tol'), number of iterations reaches max_iter, or this number of function calls. Note that number of function calls will be greater than or equal to the number of iterations for the MLPRegressor.

    New in version 0.22.

**Attributes**

- **loss_** [float] The current loss computed with the loss function.
- **best_loss_** [float] The minimum loss reached by the solver throughout fitting.
- **loss_curve_** [list of shape (n_iter_,)] The ith element in the list represents the loss at the ith iteration.
- **t_** [int] The number of training samples seen by the solver during fitting.
- **coefs_** [list of shape (n_layers - 1,)] The ith element in the list represents the weight matrix corresponding to layer i.
- **intercepts_** [list of shape (n_layers - 1,)] The ith element in the list represents the bias vector corresponding to layer i + 1.
- **n_iter_** [int] The number of iterations the solver has ran.
- **n_layers_** [int] Number of layers.
- **n_outputs_** [int] Number of outputs.
- **out_activation_** [str] Name of the output activation function.
- **loss_curve_** [list of shape (n_iters,)] Loss value evaluated at the end of each training step.
- **t_** [int] Mathematically equals n_iters * X.shape[0], it means time_step and it is used by optimizer’s learning rate scheduler.
Notes

MLPRegressor trains iteratively since at each time step the partial derivatives of the loss function with respect to the model parameters are computed to update the parameters.

It can also have a regularization term added to the loss function that shrinks model parameters to prevent overfitting.

This implementation works with data represented as dense and sparse numpy arrays of floating point values.

References


Examples

```python
>>> from sklearn.neural_network import MLPRegressor
>>> from sklearn.datasets import make_regression
>>> from sklearn.model_selection import train_test_split

>>> X, y = make_regression(n_samples=200, random_state=1)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, ...
... random_state=1)
>>> regr = MLPRegressor(random_state=1, max_iter=500).fit(X_train, y_train)
>>> regr.predict(X_test[:2])
array([-0.9..., -7.1...])
>>> regr.score(X_test, y_test)
0.4...
```

Methods

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<td><code>fit(X, y)</code></td>
<td>Fit the model to data matrix X and target(s) y.</td>
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<td><code>get_params()</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>predict(X)</code></td>
<td>Predict using the multi-layer perceptron model.</td>
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<tr>
<td><code>score(X, y, sample_weight)</code></td>
<td>Return the coefficient of determination $R^2$ of the prediction.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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`fit (X, y)`

Fit the model to data matrix X and target(s) y.

Parameters

- **X** [ndarray or sparse matrix of shape (n_samples, n_features)] The input data.
- **y** [ndarray of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels in classification, real numbers in regression).
Returns

   self [returns a trained MLP model.]

def get_params (deep=True)
   Get parameters for this estimator.

   Parameters

   deep [bool, default=True] If True, will return the parameters for this estimator and contained
   subobjects that are estimators.

   Returns

   params [dict] Parameter names mapped to their values.

@property partial_fit
   Update the model with a single iteration over the given data.

   Parameters

   X [(array-like, sparse matrix) of shape (n_samples, n_features)] The input data.
   y [ndarray of shape (n_samples,)] The target values.

   Returns

   self [returns a trained MLP model.]

def predict (X)
   Predict using the multi-layer perceptron model.

   Parameters

   X [(array-like, sparse matrix) of shape (n_samples, n_features)] The input data.

   Returns

   y [ndarray of shape (n_samples, n_outputs)] The predicted values.

def score (X, y, sample_weight=None)
   Return the coefficient of determination \( R^2 \) of the prediction.

   The coefficient \( R^2 \) is defined as \( 1 - \frac{u}{v} \), where \( u \) is the residual sum of squares \( (y_{true} - y_{pred}) ** 2 \).sum() and \( v \) is the total sum of squares \( (y_{true} - y_{true}.mean()) ** 2 \).sum().
   The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of \( y \), disregarding the input features, would get a \( R^2 \) score of 0.0.

   Parameters

   X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this
   may be a precomputed kernel matrix or a list of generic objects instead with shape
   (n_samples, n_samples_fitted), where n_samples_fitted is the number
   of samples used in the fitting for the estimator.
   y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for \( X \).
   sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

   Returns

   score [float] \( R^2 \) of self.predict (X) wrt. \( y \).
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of $r2\_score$. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

Examples using `sklearn.neural_network.MLPRegressor`  

- Partial Dependence and Individual Conditional Expectation Plots
- Advanced Plotting With Partial Dependence

7.32 `sklearn.pipeline`: Pipeline

The `sklearn.pipeline` module implements utilities to build a composite estimator, as a chain of transforms and estimators.

**User guide:** See the `Pipelines and composite estimators` section for further details.

```python
pipeline.FeatureUnion(transformer_list, *, TransformerList, n_jobs=None, transformer_weights=None, verbose=False)
```

Concatenates results of multiple transformer objects.

```python
pipeline.Pipeline(steps, *, Pipeline)
```

Pipeline of transforms with a final estimator.

7.32.1 `sklearn.pipeline.FeatureUnion`

```python
class sklearn.pipeline.FeatureUnion(transformer_list, *, n_jobs=None, transformer_weights=None, verbose=False)
```

Concatenates results of multiple transformer objects.

This estimator applies a list of transformer objects in parallel to the input data, then concatenates the results. This is useful to combine several feature extraction mechanisms into a single transformer.

Parameters of the transformers may be set using its name and the parameter name separated by a `__`. A transformer may be replaced entirely by setting the parameter with its name to another transformer, or removed by setting to `drop`.

Read more in the `User Guide`.

New in version 0.13.

**Parameters**
transformer_list [list of (string, transformer) tuples] List of transformer objects to be applied to the data. The first half of each tuple is the name of the transformer. The transformer can be ‘drop’ for it to be ignored.

Changed in version 0.22: Deprecated None as a transformer in favor of ‘drop’.

n_jobs [int, default=None] Number of jobs to run in parallel. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Changed in version v0.20: n_jobs default changed from 1 to None

transformer_weights [dict, default=None] Multiplicative weights for features per transformer.

Keys are transformer names, values the weights. Raises ValueError if key not present in transformer_list.

verbose [bool, default=False] If True, the time elapsed while fitting each transformer will be printed as it is completed.

Attributes

n_features_in_

See also:

make_union Convenience function for simplified feature union construction.

Examples

```python
>>> from sklearn.pipeline import FeatureUnion
>>> from sklearn.decomposition import PCA, TruncatedSVD
>>> union = FeatureUnion([("pca", PCA(n_components=1)),
...                       ("svd", TruncatedSVD(n_components=2))])
>>> X = [[0., 1., 3], [2., 2., 5]]
>>> union.fit_transform(X)
array([[ 1.5 , 3.0..., 0.8...
[ -1.5 , 5.7..., -0.4...]])
```

Methods

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<td><code>fit_transform(X[, y])</code></td>
<td>Fit all transformers, transform the data and concatenate results.</td>
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<tr>
<td><code>get_feature_names()</code></td>
<td>Get feature names from all transformers.</td>
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<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<td><code>set_params(**kwargs)</code></td>
<td>Set the parameters of this estimator.</td>
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<tr>
<td><code>transform(X)</code></td>
<td>Transform X separately by each transformer, concatenate results.</td>
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```python
fit (X, y=None, **fit_params)
```

Fit all transformers using X.

Parameters

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<td>X</td>
<td>[iterable or array-like, depending on transformers] Input data, used to fit transformers.</td>
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| y | [array-like of shape (n_samples, n_outputs), default=None] Targets for supervised learn-
Returns

self [FeatureUnion] This estimator

**fit_transform**(X, y=None, **fit_params)

Fit all transformers, transform the data and concatenate results.

Parameters

X [iterable or array-like, depending on transformers] Input data to be transformed.

y [array-like of shape (n_samples, n_outputs), default=None] Targets for supervised learning.

Returns

X_t [array-like or sparse matrix of shape (n_samples, sum_n_components)] hstack of results of transformers. sum_n_components is the sum of n_components (output dimension) over transformers.

**get_feature_names**()

Get feature names from all transformers.

Returns

feature_names [list of strings] Names of the features produced by transform.

**get_params**(deep=True)

Get parameters for this estimator.

Returns the parameters given in the constructor as well as the estimators contained within the transformer_list of the FeatureUnion.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [mapping of string to any] Parameter names mapped to their values.

**set_params**(**kwargs)

Set the parameters of this estimator.

Valid parameter keys can be listed with get_params(). Note that you can directly set the parameters of the estimators contained in transformer_list.

Returns

self

**transform**(X)

Transform X separately by each transformer, concatenate results.

Parameters

X [iterable or array-like, depending on transformers] Input data to be transformed.

Returns

X_t [array-like or sparse matrix of shape (n_samples, sum_n_components)] hstack of results of transformers. sum_n_components is the sum of n_components (output dimension) over transformers.
Examples using `sklearn.pipeline.FeatureUnion`

- Concatenating multiple feature extraction methods

### 7.32.2 sklearn.pipeline.Pipeline

```python
from sklearn.pipeline import Pipeline
```

**class sklearn.pipeline.Pipeline(steps, *, memory=None, verbose=False)**

Pipeline of transforms with a final estimator.

Sequentially apply a list of transforms and a final estimator. Intermediate steps of the pipeline must be ‘transforms’, that is, they must implement fit and transform methods. The final estimator only needs to implement fit. The transformers in the pipeline can be cached using `memory` argument.

The purpose of the pipeline is to assemble several steps that can be cross-validated together while setting different parameters. For this, it enables setting parameters of the various steps using their names and the parameter name separated by a ‘__’, as in the example below. A step’s estimator may be replaced entirely by setting the parameter with its name to another estimator, or a transformer removed by setting it to ‘passthrough’ or `None`.

Read more in the User Guide.

New in version 0.5.

**Parameters**

- **`steps`** [list] List of (name, transform) tuples (implementing `fit/transform`) that are chained, in the order in which they are chained, with the last object an estimator.

- **`memory`** [str or object with the joblib.Memory interface, default=None] Used to cache the fitted transformers of the pipeline. By default, no caching is performed. If a string is given, it is the path to the caching directory. Enabling caching triggers a clone of the transformers before fitting. Therefore, the transformer instance given to the pipeline cannot be inspected directly. Use the attribute `named_steps` or `steps` to inspect estimators within the pipeline. Caching the transformers is advantageous when fitting is time consuming.

- **`verbose`** [bool, default=False] If True, the time elapsed while fitting each step will be printed as it is completed.

**Attributes**

- **`named_steps`** [Bunch] Dictionary-like object, with the following attributes. Read-only attribute to access any step parameter by user given name. Keys are step names and values are steps parameters.

See also:

`make_pipeline` Convenience function for simplified pipeline construction.

**Examples**

```python
>>> from sklearn.svm import SVC
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.datasets import make_classification
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.pipeline import Pipeline

>>> X, y = make_classification(random_state=0)
>>> X_train, X_test, y_train, y_test = train_test_split(X, y, random_state=0)
```

(continues on next page)
```python
>>> pipe = Pipeline([('scaler', StandardScaler()), ('svc', SVC())])
>>> # The pipeline can be used as any other estimator
>>> # and avoids leaking the test set into the train set
>>> pipe.fit(X_train, y_train)
Pipeline(steps=[('scaler', StandardScaler()), ('svc', SVC())])
>>> pipe.score(X_test, y_test)
0.88
```

### Methods

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<td><code>fit(X[, y])</code></td>
<td>Fit the model</td>
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<td><code>fit_predict(X[, y])</code></td>
<td>Applies fit_predict of last step in pipeline after transforms.</td>
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<td><code>fit_transform(X[, y])</code></td>
<td>Fit the model and transform with the final estimator</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>predict(X, **predict_params)</code></td>
<td>Apply transforms to the data, and predict with the final estimator</td>
</tr>
<tr>
<td><code>predict_log_proba(X)</code></td>
<td>Apply transforms, and predict_log_proba of the final estimator</td>
</tr>
<tr>
<td><code>predict_proba(X)</code></td>
<td>Apply transforms, and predict_proba of the final estimator</td>
</tr>
<tr>
<td><code>score(X[, y, sample_weight])</code></td>
<td>Apply transforms, and score with the final estimator</td>
</tr>
<tr>
<td><code>score_samples(X)</code></td>
<td>Apply transforms, and score_samples of the final estimator.</td>
</tr>
<tr>
<td><code>set_params(**kwargs)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
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</table>

#### `decision_function(X)`
Apply transforms, and decision_function of the final estimator

**Parameters**

- **X** [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.

**Returns**

- **y_score** [array-like of shape (n_samples, n_classes)]

#### `fit(X[, y], **fit_params)`
Fit the model

Fit all the transforms one after the other and transform the data, then fit the transformed data using the final estimator.

**Parameters**

- **X** [iterable] Training data. Must fulfill input requirements of first step of the pipeline.
- **y** [iterable, default=None] Training targets. Must fulfill label requirements for all steps of the pipeline.
- ****fit_params [dict of string -> object] Parameters passed to the fit method of each step, where each parameter name is prefixed such that parameter `p` for step `s` has key `s__p`.

**Returns**
This estimator

**fit_predict** (*X*, *y=None, **fit_params*)
Applies fit_predict of last step in pipeline after transforms.

Applies fit_transforms of a pipeline to the data, followed by the fit_predict method of the final estimator in the pipeline. Valid only if the final estimator implements fit_predict.

**Parameters**

- **X** [iterable] Training data. Must fulfill input requirements of first step of the pipeline.
- **y** [iterable, default=None] Training targets. Must fulfill label requirements for all steps of the pipeline.
- **fit_params** [dict of string -> object] Parameters passed to the fit method of each step, where each parameter name is prefixed such that parameter *p* for step *s* has key *s__p*.

**Returns**

- **y_pred** [array-like]

**fit_transform** (*X*, *y=None, **fit_params*)
Fits all the transforms one after the other and transforms the data, then uses fit_transform on transformed data with the final estimator.

**Parameters**

- **X** [iterable] Training data. Must fulfill input requirements of first step of the pipeline.
- **y** [iterable, default=None] Training targets. Must fulfill label requirements for all steps of the pipeline.
- **fit_params** [dict of string -> object] Parameters passed to the fit method of each step, where each parameter name is prefixed such that parameter *p* for step *s* has key *s__p*.

**Returns**

- **Xt** [array-like of shape (*n_samples*, *n_transformed_features*)) Transformed samples

**get_params** (*deep=True*)
Get parameters for this estimator.

Returns the parameters given in the constructor as well as the estimators contained within the steps of the Pipeline.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [mapping of string to any] Parameter names mapped to their values.

**property inverse_transform**
Apply inverse transformations in reverse order

All estimators in the pipeline must support inverse_transform.

**Parameters**

- **Xt** [array-like of shape (*n_samples*, *n_transformed_features*)) Data samples, where *n_samples* is the number of samples and *n_features* is the number of features. Must fulfill input requirements of last step of pipeline’s inverse_transform method.
Returns

\(X_t\) [array-like of shape (n_samples, n_features)]

**predict** \((X, \**predict_params)\)
Apply transforms to the data, and predict with the final estimator

Parameters

\(X\) [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.

\**predict_params\) [dict of string -> object] Parameters to the predict called at the end of all transformations in the pipeline. Note that while this may be used to return uncertainties from some models with return_std or return_cov, uncertainties that are generated by the transformations in the pipeline are not propagated to the final estimator.

New in version 0.20.

Returns

\(y\_pred\) [array-like]

**predict_log_proba** \((X)\)
Apply transforms, and predict_log_proba of the final estimator

Parameters

\(X\) [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.

Returns

\(y\_score\) [array-like of shape (n_samples, n_classes)]

**predict_proba** \((X)\)
Apply transforms, and predict_proba of the final estimator

Parameters

\(X\) [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.

Returns

\(y\_proba\) [array-like of shape (n_samples, n_classes)]

**score** \((X, y=None, sample_weight=None)\)
Apply transforms, and score with the final estimator

Parameters

\(X\) [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.

\(y\) [iterable, default=None] Targets used for scoring. Must fulfill label requirements for all steps of the pipeline.

\(sample_weight\) [array-like, default=None] If not None, this argument is passed as sample_weight keyword argument to the score method of the final estimator.

Returns

\(score\) [float]

**score_samples** \((X)\)
Apply transforms, and score_samples of the final estimator

Parameters

\(X\) [iterable] Data to predict on. Must fulfill input requirements of first step of the pipeline.
Returns

y_score [ndarray of shape (n_samples,)]

set_params (**kwargs)
Set the parameters of this estimator.

Valid parameter keys can be listed with get_params(). Note that you can directly set the parameters
of the estimators contained in steps.

Returns

self

property transform
Apply transforms, and transform with the final estimator

This also works where final estimator is None: all prior transformations are applied.

Parameters

X [iterable] Data to transform. Must fulfill input requirements of first step of the pipeline.

Returns

Xt [array-like of shape (n_samples, n_transformed_features)]

Examples using sklearn.pipeline.Pipeline

- Sample pipeline for text feature extraction and evaluation

```python
pipeline.make_pipeline(*steps[, memory, verbose])
```

Construct a Pipeline from the given estimators.

```python
pipeline.make_union(*transformers[, n_jobs, ...])
```

Construct a FeatureUnion from the given transformers.

7.32.3 sklearn.pipeline.make_pipeline

sklearn.pipeline.make_pipeline(*steps, memory=0, verbose=False)

Construct a Pipeline from the given estimators.

This is a shorthand for the Pipeline constructor; it does not require, and does not permit, naming the estimators.
Instead, their names will be set to the lowercase of their types automatically.

Parameters

*steps [list of estimators.]

memory [str or object with the joblib.Memory interface, default=None] Used to cache the fitted transformers of the pipeline. By default, no caching is performed. If a string is given, it is the path to the caching directory. Enabling caching triggers a clone of the transformers before fitting. Therefore, the transformer instance given to the pipeline cannot be inspected directly. Use the attribute named_steps or steps to inspect estimators within the pipeline. Caching the transformers is advantageous when fitting is time consuming.

verbose [bool, default=False] If True, the time elapsed while fitting each step will be printed as it is completed.

Returns

p [Pipeline]
See also:

**Pipeline** Class for creating a pipeline of transforms with a final estimator.

Examples

```python
>>> from sklearn.naive_bayes import GaussianNB
>>> from sklearn.preprocessing import StandardScaler

>>> make_pipeline(StandardScaler(), GaussianNB(priors=None))
Pipeline(steps=[('standardscaler', StandardScaler()), ('gaussiannb', GaussianNB())])
```

Examples using `sklearn.pipeline.make_pipeline`

- *Approximate nearest neighbors in TSNE*

### 7.32.4 `sklearn.pipeline.make_union`

`sklearn.pipeline.make_union(*transformers, n_jobs=None, verbose=False)`  
Construct a FeatureUnion from the given transformers.

This is a shorthand for the FeatureUnion constructor; it does not require, and does not permit, naming the transformers. Instead, they will be given names automatically based on their types. It also does not allow weighting.

**Parameters**

- *transformers* [list of estimators]

  - **n_jobs** [int, default=None] Number of jobs to run in parallel. None means 1 unless in a `joblib.parallel_backend` context. -1 means using all processors. See *Glossary* for more details.

  Changed in version v0.20: *n_jobs* default changed from 1 to None

  - **verbose** [bool, default=False] If True, the time elapsed while fitting each transformer will be printed as it is completed.

**Returns**

- *f* [FeatureUnion]

See also:

**FeatureUnion** Class for concatenating the results of multiple transformer objects.
Examples

```python
>>> from sklearn.decomposition import PCA, TruncatedSVD
>>> from sklearn.pipeline import make_union
>>> make_union(PCA(), TruncatedSVD())
FeatureUnion(transformer_list=[('pca', PCA()), ('truncatedsvd', TruncatedSVD())])
```

## 7.33 sklearn.preprocessing: Preprocessing and Normalization

The `sklearn.preprocessing` module includes scaling, centering, normalization, binarization methods.

**User guide:** See the *Preprocessing data* section for further details.

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7.33.1 sklearn.preprocessing.Binarizer

class sklearn.preprocessing.Binarizer (*, threshold=0.0, copy=True)

Binarize data (set feature values to 0 or 1) according to a threshold.

Values greater than the threshold map to 1, while values less than or equal to the threshold map to 0. With the default threshold of 0, only positive values map to 1.

Binarization is a common operation on text count data where the analyst can decide to only consider the presence or absence of a feature rather than a quantified number of occurrences for instance.

It can also be used as a pre-processing step for estimators that consider boolean random variables (e.g. modelled using the Bernoulli distribution in a Bayesian setting).

Read more in the User Guide.

Parameters

threshold [float, default=0.0] Feature values below or equal to this are replaced by 0, above it by 1. Threshold may not be less than 0 for operations on sparse matrices.

copy [bool, default=True] set to False to perform inplace binarization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSR matrix).

See also:

binarize Equivalent function without the estimator API.

Notes

If the input is a sparse matrix, only the non-zero values are subject to update by the Binarizer class.

This estimator is stateless (besides constructor parameters), the fit method does nothing but is useful when used in a pipeline.

Examples

```python
>>> from sklearn.preprocessing import Binarizer
>>> X = [[ 1., -1., 2.],
      ... [ 2., 0., 0.],
      ... [ 0., 1., -1.]]
>>> transformer = Binarizer().fit(X)  # fit does nothing.
>>> transformer
Binarizer()
>>> transformer.transform(X)
array([[0., 0., 1.],
       [1., 0., 0.],
       [0., 1., 0.]])
```
Methods

<table>
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<td>Fit to data, then transform it.</td>
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<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
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<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X[, copy])</code></td>
<td>Binarize each element of X.</td>
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</table>

**fit (X, y=None)**
Do nothing and return the estimator unchanged.

This method is just there to implement the usual API and hence work in pipelines.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) The data.
- **y** [None] Ignored.

**Returns**

- **self** [object] Fitted transformer.

**fit_transform (X, y=None, **fit_params)**
Fit to data, then transform it.
Fits transformer to X and y with optional parameters `fit_params` and returns a transformed version of X.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,), or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- **fit_params** [dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params (deep=True)**
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**set_params (**params**)**
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.
Returns

self [estimator instance] Estimator instance.

transform (X, copy=None)
Binarize each element of X.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to binarize, element by element. scipy.sparse matrices should be in CSR format to avoid an unnecessary copy.

copy [bool] Copy the input X or not.

Returns

X_tr {{ndarray, sparse matrix} of shape (n_samples, n_features)} Transformed array.

7.33.2 sklearn.preprocessing.FunctionTransformer

class sklearn.preprocessing.FunctionTransformer (func=None, inverse_func=None, *, validate=False, accept_sparse=False, check_inverse=True, kw_args=None, inv_kw_args=None)

Constructs a transformer from an arbitrary callable.

A FunctionTransformer forwards its X (and optionally y) arguments to a user-defined function or function object and returns the result of this function. This is useful for stateless transformations such as taking the log of frequencies, doing custom scaling, etc.

Note: If a lambda is used as the function, then the resulting transformer will not be pickleable.

New in version 0.17.

Read more in the User Guide.

Parameters

func [callable, default=None] The callable to use for the transformation. This will be passed the same arguments as transform, with args and kw_args forwarded. If func is None, then func will be the identity function.

inverse_func [callable, default=None] The callable to use for the inverse transformation. This will be passed the same arguments as inverse transform, with args and kw_args forwarded. If inverse_func is None, then inverse_func will be the identity function.

validate [bool, default=False] Indicate that the input X array should be checked before calling func. The possibilities are:

• If False, there is no input validation.

• If True, then X will be converted to a 2-dimensional NumPy array or sparse matrix. If the conversion is not possible an exception is raised.

Changed in version 0.22: The default of validate changed from True to False.

accept_sparse [bool, default=False] Indicate that func accepts a sparse matrix as input. If validate is False, this has no effect. Otherwise, if accept_sparse is False, sparse matrix inputs will cause an exception to be raised.
check_inverse [bool, default=True] Whether to check that or func followed by inverse_func leads to the original inputs. It can be used for a sanity check, raising a warning when the condition is not fulfilled.

New in version 0.20.

kw_args [dict, default=None] Dictionary of additional keyword arguments to pass to func.

New in version 0.18.

inv_kw_args [dict, default=None] Dictionary of additional keyword arguments to pass to inverse_func.

New in version 0.18.

Examples

```python
>>> import numpy as np
>>> from sklearn.preprocessing import FunctionTransformer
>>> transformer = FunctionTransformer(np.log1p)
>>> X = np.array([[0, 1], [2, 3]])
>>> transformer.transform(X)
array([[0. , 0.6931..., 1.0986..., 1.3862...]])
```

Methods

- `fit(X, y=None)` Fit transformer by checking X.
- `fit_transform(X, y=None)` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `inverse_transform(X)` Transform X using the inverse function.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Transform X using the forward function.

```python
fit (X, y=None)
Fit transformer by checking X.

If validate is True, X will be checked.

Parameters
X [array-like, shape (n_samples, n_features)] Input array.

Returns
self

fit_transform (X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters
X [array-like of shape (n_samples, n_features)] Input samples.
**y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

**X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)

Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

**inverse_transform**(X)

Transform X using the inverse function.

Parameters

**X** [array-like, shape (n_samples, n_features)] Input array.

Returns

**X_out** [array-like, shape (n_samples, n_features)] Transformed input.

**set_params**(**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

**self** [estimator instance] Estimator instance.

**transform**(X)

Transform X using the forward function.

Parameters

**X** [array-like, shape (n_samples, n_features)] Input array.

Returns

**X_out** [array-like, shape (n_samples, n_features)] Transformed input.
Examples using `sklearn.preprocessing.FunctionTransformer`

- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
- Column Transformer with Heterogeneous Data Sources
- Semi-supervised Classification on a Text Dataset

### 7.33.3 `sklearn.preprocessing.KBinsDiscretizer`

**class** `sklearn.preprocessing.KBinsDiscretizer(n_bins=5, *, encode='onehot', strategy='quantile', dtype=None)`

Bin continuous data into intervals.

Read more in the *User Guide*.

New in version 0.20.

**Parameters**

- `n_bins` [int or array-like of shape (n_features,), default=5] The number of bins to produce. Raises `ValueError` if `n_bins < 2`.
- `encode` [{'onehot', 'onehot-dense', 'ordinal'}, default='onehot'] Method used to encode the transformed result.
  - `onehot` Encode the transformed result with one-hot encoding and return a sparse matrix. Ignored features are always stacked to the right.
  - `onehot-dense` Encode the transformed result with one-hot encoding and return a dense array. Ignored features are always stacked to the right.
  - `ordinal` Return the bin identifier encoded as an integer value.
- `strategy` [{'uniform', 'quantile', 'kmeans'}, default='quantile'] Strategy used to define the widths of the bins.
  - `uniform` All bins in each feature have identical widths.
  - `quantile` All bins in each feature have the same number of points.
  - `kmeans` Values in each bin have the same nearest center of a 1D k-means cluster.
- `dtype` [{np.float32, np.float64}, default=None] The desired data-type for the output. If None, output dtype is consistent with input dtype. Only np.float32 and np.float64 are supported.

New in version 0.24.

**Attributes**

- `n_bins_` [ndarray of shape (n_features,), dtype=np.int_] Number of bins per feature. Bins whose width are too small (i.e., <= 1e-8) are removed with a warning.
- `bin_edges_` [ndarray of shape (n_features,)] The edges of each bin. Contain arrays of varying shapes (n_bins, ) Ignored features will have empty arrays.

**See also:**

- **Binarizer**: Class used to bin values as 0 or 1 based on a parameter `threshold`.
Notes

In bin edges for feature $i$, the first and last values are used only for `inverse_transform`. During transform, bin edges are extended to:

```
np.concatenate([-np.inf, bin_edges_[i][1:-1], np.inf])
```

You can combine `KBinsDiscretizer` with `ColumnTransformer` if you only want to preprocess part of the features.

`KBinsDiscretizer` might produce constant features (e.g., when `encode = 'onehot'` and certain bins do not contain any data). These features can be removed with feature selection algorithms (e.g., `VarianceThreshold`).

Examples

```python
>>> X = [[-2, 1, -4, -1],
     ...  [-1, 2, -3, -0.5],
     ...  [ 0, 3, -2, 0.5],
     ...  [ 1, 4, -1, 2]]
>>> est = KBinsDiscretizer(n_bins=3, encode='ordinal', strategy='uniform')
>>> est.fit(X)
KBinsDiscretizer(n_bins=3, encode='ordinal', strategy='uniform')
>>> Xt = est.transform(X)
>>> Xt
array([[ 0., 0., 0., 0.],
       [ 1., 1., 1., 0.],
       [ 2., 2., 2., 1.],
       [ 2., 2., 2., 2.]])
```

Sometimes it may be useful to convert the data back into the original feature space. The `inverse_transform` function converts the binned data into the original feature space. Each value will be equal to the mean of the two bin edges.

```python
>>> est.bin_edges_[0]
array([-2., -1., 0., 1.])
>>> est.inverse_transform(Xt)
array([[-1.5, 1.5, -3.5, -0.5],
       [-0.5, 2.5, -2.5, -0.5],
       [ 0.5, 3.5, -1.5, 0.5],
       [ 0.5, 3.5, -1.5, 1.5]])
```

Methods

```
fit(X[, y]) Fit the estimator.
fit_transform(X[, y]) Fit to data, then transform it.
get_params([deep]) Get parameters for this estimator.
inverse_transform(Xt) Transform discretized data back to original feature space.
set_params(**params) Set the parameters of this estimator.
transform(X) Discretize the data.
```

`fit (X, y=None)"
Fit the estimator.

Parameters
X [array-like of shape (n_samples, n_features), dtype={int, float}] Data to be discretized.
y [None] Ignored. This parameter exists only for compatibility with Pipeline.

Returns
self

fit_transform (X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters
X [array-like of shape (n_samples, n_features)] Input samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns
X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters
dep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params [dict] Parameter names mapped to their values.

inverse_transform (Xt)
Transform discretized data back to original feature space.

Note that this function does not regenerate the original data due to discretization rounding.

Parameters
Xt [array-like of shape (n_samples, n_features), dtype={int, float}] Transformed data in the binned space.

Returns
Xinv [ndarray, dtype={np.float32, np.float64}] Data in the original feature space.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it's possible to update each component of a nested object.

Parameters
**params [dict] Estimator parameters.
Returns

```python
self [estimator instance] Estimator instance.
```

```python
transform(X)
Discretize the data.
```

Parameters

```python
X [array-like of shape (n_samples, n_features), dtype={int, float}] Data to be discretized.
```

Returns

```python
Xt [ndarray, sparse matrix, dtype={np.float32, np.float64}] Data in the binned space. Will be a sparse matrix if self.encode='onehot' and ndarray otherwise.
```

Examples using `sklearn.preprocessing.KBinsDiscretizer`

- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
- Using KBinsDiscretizer to discretize continuous features
- Demonstrating the different strategies of KBinsDiscretizer
- Feature discretization

### 7.33.4 sklearn.preprocessing.KernelCenterer

```python
class sklearn.preprocessing.KernelCenterer
Center a kernel matrix.
```

Let $K(x, z)$ be a kernel defined by $\phi(x)^T \phi(z)$, where $\phi$ is a function mapping $x$ to a Hilbert space. KernelCenterer centers (i.e., normalize to have zero mean) the data without explicitly computing $\phi(x)$. It is equivalent to centering $\phi(x)$ with sklearn.preprocessing.StandardScaler(with_std=False).

Read more in the User Guide.

Attributes

- `K_fit_rows` [array of shape (n_samples,)] Average of each column of kernel matrix.
- `K_fit_all` [float] Average of kernel matrix.

Examples

```python
>>> from sklearn.preprocessing import KernelCenterer
>>> from sklearn.metrics.pairwise import pairwise_kernels

>>> X = [[1., -2., 2.],
      ... [-2., 1., 3.],
      ... [4., 1., -2.]]

>>> K = pairwise_kernels(X, metric='linear')

>>> K
array([[  9.,  2., -2.],
        [  2., 14., -13.],
        [-2., -13., 21.]])

>>> transformer = KernelCenterer().fit(K)

>>> transformer
```

(continues on next page)
KernelCenterer()

```python
>>> transformer.transform(K)
array([[ 5.,  0., -5.],
       [ 0., 14., -14.],
       [-5.,-14., 19.]]
```

**Methods**

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<td>Fit KernelCenterer</td>
</tr>
<tr>
<td><code>fit_transform(X, y=None, **fit_params)</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(K[, copy])</code></td>
<td>Center kernel matrix.</td>
</tr>
</tbody>
</table>

**`fit(K, y=None)`**

Fit KernelCenterer

**Parameters**

- **K** (ndarray of shape (n_samples, n_samples)) Kernel matrix.
- **y** (None) Ignored.

**Returns**

- **self** (object) Fitted transformer.

**`fit_transform(X, y=None, **fit_params)`**

Fit to data, then transform it.

Fits transformer to `X` and `y` with optional parameters `fit_params` and returns a transformed version of `X`.

**Parameters**

- **X** (array-like of shape (n_samples, n_features)) Input samples.
- **y** (array-like of shape (n_samples,) or (n_samples, n_outputs), default=None) Target values (None for unsupervised transformations).
- ****fit_params (dict) Additional fit parameters.

**Returns**

- **X_new** (ndarray array of shape (n_samples, n_features_new)) Transformed array.

**`get_params([deep])`**

Get parameters for this estimator.

**Parameters**

- **deep** (bool, default=True) If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** (dict) Parameter names mapped to their values.

**`set_params(**params)`**

Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform** *(K, copy=True)*

Center kernel matrix.

**Parameters**

K [ndarray of shape (n_samples1, n_samples2)] Kernel matrix.

copy [bool, default=True] Set to False to perform inplace computation.

**Returns**

K_new [ndarray of shape (n_samples1, n_samples2)]

### 7.33.5 sklearn.preprocessing.LabelBinarizer

**class** sklearn.preprocessing.LabelBinarizer(*, neg_label=0, pos_label=1, sparse_output=False)*

Binarize labels in a one-vs-all fashion.

Several regression and binary classification algorithms are available in scikit-learn. A simple way to extend these algorithms to the multi-class classification case is to use the so-called one-vs-all scheme.

At learning time, this simply consists in learning one regressor or binary classifier per class. In doing so, one needs to convert multi-class labels to binary labels (belong or does not belong to the class). LabelBinarizer makes this process easy with the transform method.

At prediction time, one assigns the class for which the corresponding model gave the greatest confidence. LabelBinarizer makes this easy with the inverse_transform method.

Read more in the User Guide.

**Parameters**

neg_label [int, default=0] Value with which negative labels must be encoded.

pos_label [int, default=1] Value with which positive labels must be encoded.

sparse_output [bool, default=False] True if the returned array from transform is desired to be in sparse CSR format.

**Attributes**

classes_ [ndarray of shape (n_classes,)] Holds the label for each class.


sparse_input_ [bool] True if the input data to transform is given as a sparse matrix, False otherwise.

See also:
**label_binarize** Function to perform the transform operation of LabelBinarizer with fixed classes.

**OneHotEncoder** Encode categorical features using a one-hot aka one-of-K scheme.

### Examples

```python
>>> from sklearn import preprocessing
>>> lb = preprocessing.LabelBinarizer()
>>> lb.fit([1, 2, 6, 4, 2])
LabelBinarizer()
>>> lb.classes_
array([1, 2, 4, 6])
>>> lb.transform([1, 6])
array([[1, 0, 0, 0],
       [0, 0, 0, 1]])
```

Binary targets transform to a column vector

```python
>>> lb = preprocessing.LabelBinarizer()
>>> lb.fit_transform(['yes', 'no', 'no', 'yes'])
array([[1],
       [0],
       [0],
       [1]])
```

Passing a 2D matrix for multilabel classification

```python
>>> import numpy as np
>>> lb.fit(np.array([[0, 1, 1], [1, 0, 0]]))
LabelBinarizer()
>>> lb.classes_
array([0, 1, 2])
>>> lb.transform([0, 1, 2, 1])
array([[1, 0, 0],
       [0, 1, 0],
       [0, 0, 1],
       [0, 1, 0]])
```

### Methods

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<td>Fit label binarizer.</td>
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<tr>
<td><code>fit_transform(y)</code></td>
<td>Fit label binarizer and transform multi-class labels to binary labels.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>inverse_transform(Y[, threshold])</code></td>
<td>Transform binary labels back to multi-class labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(y)</code></td>
<td>Transform multi-class labels to binary labels.</td>
</tr>
</tbody>
</table>

**fit**

Fit label binarizer.

**Parameters**

- `y` [ndarray of shape (n_samples,) or (n_samples, n_classes)] Target values. The 2-d matrix
should only contain 0 and 1, represents multilabel classification.

Returns

self [returns an instance of self.]

**fit_transform** *(y)*

Fit label binarizer and transform multi-class labels to binary labels.

The output of transform is sometimes referred to as the 1-of-K coding scheme.

Parameters

y [[ndarray, sparse matrix] of shape (n_samples,) or (n_samples, n_classes)] Target values. The 2-d matrix should only contain 0 and 1, represents multilabel classification. Sparse matrix can be CSR, CSC, COO, DOK, or LIL.

Returns

Y [[ndarray, sparse matrix] of shape (n_samples, n_classes)] Shape will be (n_samples, 1) for binary problems. Sparse matrix will be of CSR format.

**get_params** *(deep=True)*

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**inverse_transform** *(Y, threshold=None)*

Transform binary labels back to multi-class labels.

Parameters

Y [[ndarray, sparse matrix] of shape (n_samples, n_classes)] Target values. All sparse matrices are converted to CSR before inverse transformation.

threshold [float, default=None] Threshold used in the binary and multi-label cases.

Use 0 when \( Y \) contains the output of decision_function (classifier). Use 0.5 when \( Y \) contains the output of predict_proba.

If None, the threshold is assumed to be half way between neg_label and pos_label.

Returns

y [[ndarray, sparse matrix] of shape (n_samples,)] Target values. Sparse matrix will be of CSR format.
Notes

In the case when the binary labels are fractional (probabilistic), inverse_transform chooses the class with
the greatest value. Typically, this allows to use the output of a linear model’s decision_function method
directly as the input of inverse_transform.

**set_params(**params)**
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self  [estimator instance] Estimator instance.

**transform**(y)
Transform multi-class labels to binary labels.

The output of transform is sometimes referred to by some authors as the 1-of-K coding scheme.

**Parameters**

y  [[array, sparse matrix] of shape (n_samples,) or (n_samples, n_classes)] Target values.

The 2-d matrix should only contain 0 and 1, represents multilabel classification. Sparse
matrix can be CSR, CSC, COO, DOK, or LIL.

**Returns**

Y  [[ndarray, sparse matrix] of shape (n_samples, n_classes)] Shape will be (n_samples, 1)
for binary problems. Sparse matrix will be of CSR format.

7.33.6 sklearn.preprocessing.LabelEncoder

class sklearn.preprocessing.LabelEncoder

Encode target labels with value between 0 and n_classes-1.

This transformer should be used to encode target values, i.e. y, and not the input X.

Read more in the User Guide.

New in version 0.12.

**Attributes**

classes_  [ndarray of shape (n_classes,)] Holds the label for each class.

**See also:**

OrdinalEncoder Encode categorical features using an ordinal encoding scheme.

OneHotEncoder Encode categorical features as a one-hot numeric array.
Examples

LabelEncoder can be used to normalize labels.

```python
>>> from sklearn import preprocessing
>>> le = preprocessing.LabelEncoder()
>>> le.fit([1, 2, 2, 6])
LabelEncoder()
>>> le.classes_
array([1, 2, 6])
>>> le.transform([1, 1, 2, 6])
array([0, 0, 1, 2])
>>> le.inverse_transform([0, 0, 1, 2])
array([1, 1, 2, 6])
```

It can also be used to transform non-numerical labels (as long as they are hashable and comparable) to numerical labels.

```python
>>> le = preprocessing.LabelEncoder()
>>> le.fit(['paris', 'paris', 'tokyo', 'amsterdam'])
LabelEncoder()
>>> list(le.classes_)
['amsterdam', 'paris', 'tokyo']
>>> le.transform(['tokyo', 'tokyo', 'paris'])
array([2, 2, 1])
>>> list(le.inverse_transform([2, 2, 1]))
['tokyo', 'tokyo', 'paris']
```

Methods

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<td>Fit label encoder.</td>
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</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>inverse_transform(y)</code></td>
<td>Transform labels back to original encoding.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(y)</code></td>
<td>Transform labels to normalized encoding.</td>
</tr>
</tbody>
</table>

**fit**

Fit label encoder.

**Parameters**

- `y` [array-like of shape (n_samples,)] Target values.

**Returns**

- `self` [returns an instance of self.]

**fit_transform**

Fit label encoder and return encoded labels.

**Parameters**

- `y` [array-like of shape (n_samples,)] Target values.

**Returns**

- `y` [array-like of shape (n_samples,)]
get_params (deep=True)
Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform (y)
Transform labels back to original encoding.

Parameters

y [ndarray of shape (n_samples,)] Target values.

Returns

y [ndarray of shape (n_samples,)]

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (y)
Transform labels to normalized encoding.

Parameters

y [array-like of shape (n_samples,)] Target values.

Returns

y [array-like of shape (n_samples,)]

7.33.7 sklearn.preprocessing.MultiLabelBinarizer

class sklearn.preprocessing.MultiLabelBinarizer(*,
classes=None,
sparse_output=False)
Transform between iterable of iterables and a multilabel format.

Although a list of sets or tuples is a very intuitive format for multilabel data, it is unwieldy to process. This
transformer converts between this intuitive format and the supported multilabel format: a (samples x classes)
binary matrix indicating the presence of a class label.

Parameters

classes [array-like of shape (n_classes,), default=None] Indicates an ordering for the class la-

bels. All entries should be unique (cannot contain duplicate classes).
sparse_output  [bool, default=False] Set to True if output binary array is desired in CSR sparse format.

Attributes

classes_  [ndarray of shape (n_classes,)] A copy of the classes parameter when provided. Otherwise it corresponds to the sorted set of classes found when fitting.

See also:

OneHotEncoder  Encode categorical features using a one-hot aka one-of-K scheme.

Examples

```python
>>> from sklearn.preprocessing import MultiLabelBinarizer
>>> mlb = MultiLabelBinarizer()
>>> mlb.fit_transform([(1, 2), (3,)]
array([[1, 1, 0],
       [0, 0, 1]])
>>> mlb.classes_
array([1, 2, 3])

>>> mlb.fit_transform([('sci-fi', 'thriller'), {'comedy'})
array([[0, 1, 1],
       [1, 0, 0]])
>>> list(mlb.classes_)
['comedy', 'sci-fi', 'thriller']
```

A common mistake is to pass in a list, which leads to the following issue:

```python
>>> mlb = MultiLabelBinarizer()
>>> mlb.fit(['sci-fi', 'thriller', 'comedy'])
MultiLabelBinarizer()
>>> mlb.classes_
array(['-', 'c', 'd', 'e', 'f', 'h', 'i', 'l', 'm', 'o', 'r', 's', 't', 'y'], dtype=object)
```

To correct this, the list of labels should be passed in as:

```python
>>> mlb = MultiLabelBinarizer()
>>> mlb.fit([['sci-fi', 'thriller', 'comedy']])
MultiLabelBinarizer()
>>> mlb.classes_
array(['comedy', 'sci-fi', 'thriller'], dtype=object)
```

Methods

```python
fit(y)  Fit the label sets binarizer, storing classes_.
fit_transform(y)  Fit the label sets binarizer and transform the given label sets.
get_params([deep])  Get parameters for this estimator.
inverse_transform(yt)  Transform the given indicator matrix into label sets.
set_params(**params)  Set the parameters of this estimator.
transform(y)  Transform the given label sets.
```
**fit** *(y)*

Fit the label sets binarizer, storing `classes_`.

**Parameters**

- `y` [iterable of iterables] A set of labels (any orderable and hashable object) for each sample. If the `classes` parameter is set, `y` will not be iterated.

**Returns**

- `self` [returns this MultiLabelBinarizer instance]

**fit_transform** *(y)*

Fit the label sets binarizer and transform the given label sets.

**Parameters**

- `y` [iterable of iterables] A set of labels (any orderable and hashable object) for each sample. If the `classes` parameter is set, `y` will not be iterated.

**Returns**

- `y_indicator` [[ndarray, sparse matrix] of shape (n_samples, n_classes)] A matrix such that `y_indicator[i, j] = 1` if `classes_[j]` is in `y[i]`, and 0 otherwise. Sparse matrix will be of CSR format.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params` [dict] Parameter names mapped to their values.

**inverse_transform** *(yt)*

Transform the given indicator matrix into label sets.

**Parameters**

- `yt` [[ndarray, sparse matrix] of shape (n_samples, n_classes)] A matrix containing only 1s ands 0s.

**Returns**

- `y` [list of tuples] The set of labels for each sample such that `y[i]` consists of `classes_[j]` for each `yt[i, j] == 1`.

**set_params** **(**`**params`**)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- `**params` [dict] Estimator parameters.

**Returns**

**transform**(
    y
)

Transform the given label sets.

Parameters

- **y** [iterable of iterables] A set of labels (any orderable and hashable object) for each sample. If the classes parameter is set, y will not be iterated.

Returns

- **y_indicator** [array or CSR matrix, shape (n_samples, n_classes)] A matrix such that y_indicator[i, j] = 1 iff classes_[j] is in y[i], and 0 otherwise.

### 7.33.8 sklearn.preprocessing.MaxAbsScaler

**class sklearn.preprocessing.MaxAbsScaler(*, copy=True)**

Scale each feature by its maximum absolute value.

This estimator scales and translates each feature individually such that the maximal absolute value of each feature in the training set will be 1.0. It does not shift/center the data, and thus does not destroy any sparsity.

This scaler can also be applied to sparse CSR or CSC matrices.

New in version 0.17.

Parameters

- **copy** [bool, default=True] Set to False to perform inplace scaling and avoid a copy (if the input is already a numpy array).

Attributes

- **scale_** [ndarray of shape (n_features,)] Per feature relative scaling of the data.
  
  New in version 0.17: scale_ attribute.
- **max_abs_** [ndarray of shape (n_features,)] Per feature maximum absolute value.
- **n_samples_seen_** [int] The number of samples processed by the estimator. Will be reset on new calls to fit, but increments across partial_fit calls.

See also:

- **maxabs_scale** Equivalent function without the estimator API.

Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.
Examples

```python
>>> from sklearn.preprocessing import MaxAbsScaler
>>> X = [[ 1., -1., 2.],
       ... [ 2., 0., 0.],
       ... [ 0., 1., -1.]]
>>> transformer = MaxAbsScaler().fit(X)
>>> transformer
MaxAbsScaler()
>>> transformer.transform(X)
array([[ 0.5, -1., 1.],
       [ 1., 0., 0.],
       [ 0., 1., -0.5]])
```

Methods

- `fit(X[, y])` Compute the maximum absolute value to be used for later scaling.
- `fit_transform(X[, y])` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `inverse_transform(X)` Scale back the data to the original representation.
- `partial_fit(X[, y])` Online computation of max absolute value of X for later scaling.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Scale the data.

**fit**(X, y=None)
Compute the maximum absolute value to be used for later scaling.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The data used to compute the per-feature minimum and maximum used for later scaling along the features axis.
- **y** (None) Ignored.

**Returns**

- **self** [object] Fitted scaler.

**fit_transform**(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**

- **X** ([array-like of shape (n_samples, n_features)]) Input samples.
- **y** ([array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).
- ****fit_params **[dict] Additional fit parameters.

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.
get_params (deep=True)
Get parameters for this estimator.

Parameters

  deep [bool, default=True] If True, will return the parameters for this estimator and contained
  subobjects that are estimators.

Returns

  params [dict] Parameter names mapped to their values.

inverse_transform (X)
Scale back the data to the original representation

Parameters

  X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data that should be
  transformed back.

Returns

  X_tr [{ndarray, sparse matrix} of shape (n_samples, n_features)] Transformed array.

partial_fit (X, y=None)
Online computation of max absolute value of X for later scaling.
All of X is processed as a single batch. This is intended for cases when fit is not feasible due to very
large number of n_samples or because X is read from a continuous stream.

Parameters

  X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data used to compute
  the mean and standard deviation used for later scaling along the features axis.

  y [None] Ignored.

Returns


set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it’s possible to update each component
of a nested object.

Parameters

  **params [dict] Estimator parameters.

Returns

  self [estimator instance] Estimator instance.

transform (X)
Scale the data

Parameters

  X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data that should be
  scaled.

Returns

  X_tr [{ndarray, sparse matrix} of shape (n_samples, n_features)] Transformed array.
Examples using `sklearn.preprocessing.MaxAbsScaler`

- Compare the effect of different scalers on data with outliers

### 7.33.9 `sklearn.preprocessing.MinMaxScaler`

class `sklearn.preprocessing.MinMaxScaler` *(feature_range=0, 1, *, copy=True, clip=False)*

Transform features by scaling each feature to a given range.

This estimator scales and translates each feature individually such that it is in the given range on the training set, e.g. between zero and one.

The transformation is given by:

\[
X_{\text{std}} = \frac{X - X_{\text{min}}(axis=0)}{X_{\text{max}}(axis=0) - X_{\text{min}}(axis=0)}
\]

\[
X_{\text{scaled}} = X_{\text{std}} \times (\text{max} - \text{min}) + \text{min}
\]

where min, max = feature_range.

This transformation is often used as an alternative to zero mean, unit variance scaling.

Read more in the *User Guide*.

**Parameters**

- `feature_range` [tuple (min, max), default=(0, 1)] Desired range of transformed data.
- `copy` [bool, default=True] Set to False to perform inplace row normalization and avoid a copy (if the input is already a numpy array).
- `clip`: bool, default=False Set to True to clip transformed values of held-out data to provided feature range.

New in version 0.24.

**Attributes**

- `min_` [ndarray of shape (n_features,)] Per feature adjustment for minimum. Equivalent to \(X - X_{\text{min}}(axis=0) \times \text{self.scale}_\)
- `scale_` [ndarray of shape (n_features,)] Per feature relative scaling of the data. Equivalent to \((\text{max} - \text{min}) / (X_{\text{max}}(axis=0) - X_{\text{min}}(axis=0))\)

New in version 0.17: `scale_` attribute.
- `data_min_` [ndarray of shape (n_features,)] Per feature minimum seen in the data

New in version 0.17: `data_min_`
- `data_max_` [ndarray of shape (n_features,)] Per feature maximum seen in the data

New in version 0.17: `data_max_`
- `data_range_` [ndarray of shape (n_features,)] Per feature range \((\text{data_max_ - data_min_})\) seen in the data

New in version 0.17: `data_range_`
- `n_samples_seen_` [int] The number of samples processed by the estimator. It will be reset on new calls to fit, but increments across partial_fit calls.

**See also:**

- `minmax_scale` Equivalent function without the estimator API.
Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Examples

```python
>>> from sklearn.preprocessing import MinMaxScaler
>>> data = [[-1, 2], [-0.5, 6], [0, 10], [1, 18]]
>>> scaler = MinMaxScaler()
>>> print(scaler.fit(data))
MinMaxScaler()
>>> print(scaler.data_max_)
[ 1. 18.]
>>> print(scaler.transform(data))
[[0. 0.]
 [0.25 0.25]
 [0.5 0.5]
 [1. 1.]]
>>> print(scaler.transform([[2, 2]]))
[[1.5 0.]]
```

Methods

- `fit(X[, y])` Compute the minimum and maximum to be used for later scaling.
- `fit_transform(X[, y])` Fit to data, then transform it.
- `get_params([deep])` Get parameters for this estimator.
- `inverse_transform(X)` Undo the scaling of X according to feature_range.
- `partial_fit(X[, y])` Online computation of min and max on X for later scaling.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Scale features of X according to feature_range.

**fit**(X, y=None)
Compute the minimum and maximum to be used for later scaling.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] The data used to compute the per-feature minimum and maximum used for later scaling along the features axis.
- **y** [None] Ignored.

**Returns**

- **self** [object] Fitted scaler.

**fit_transform**(X, y=None, **fit_params)
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.
Parameters

**X** [array-like of shape (n_samples, n_features)] Input samples.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

**X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (**deep=True**)

Get parameters for this estimator.

Parameters

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

**params** [dict] Parameter names mapped to their values.

inverse_transform(**X**)

Undo the scaling of X according to feature_range.

Parameters

**X** [array-like of shape (n_samples, n_features)] Input data that will be transformed. It cannot be sparse.

Returns

**Xt** [ndarray of shape (n_samples, n_features)] Transformed data.

partial_fit(**X**, **y=None**)

Online computation of min and max on X for later scaling.

All of X is processed as a single batch. This is intended for cases when fit is not feasible due to very large number of n_samples or because X is read from a continuous stream.

Parameters

**X** [array-like of shape (n_samples, n_features)] The data used to compute the mean and standard deviation used for later scaling along the features axis.

**y** [None] Ignored.

Returns

**self** [object] Fitted scaler.

set_params (****params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

**self** [estimator instance] Estimator instance.
transform(X)
Scale features of X according to feature_range.

Parameters
X [array-like of shape (n_samples, n_features)] Input data that will be transformed.

Returns
Xt [ndarray of shape (n_samples, n_features)] Transformed data.

Examples using sklearn.preprocessing.MinMaxScaler

- Release Highlights for scikit-learn 0.24
- Univariate Feature Selection
- Scalable learning with polynomial kernel approximation
- Compare Stochastic learning strategies for MLPClassifier
- Compare the effect of different scalers on data with outliers

7.33.10 sklearn.preprocessing.Normalizer

class sklearn.preprocessing.Normalizer(norm='l2', *, copy=True)
Normalize samples individually to unit norm.

Each sample (i.e. each row of the data matrix) with at least one non zero component is rescaled independently of other samples so that its norm (l1, l2 or inf) equals one.

This transformer is able to work both with dense numpy arrays and scipy.sparse matrix (use CSR format if you want to avoid the burden of a copy / conversion).

Scaling inputs to unit norms is a common operation for text classification or clustering for instance. For instance the dot product of two l2-normalized TF-IDF vectors is the cosine similarity of the vectors and is the base similarity metric for the Vector Space Model commonly used by the Information Retrieval community.

Read more in the User Guide.

Parameters

- norm [‘l1’, ‘l2’, ‘max’], default=’l2’ The norm to use to normalize each non zero sample. If norm=’max’ is used, values will be rescaled by the maximum of the absolute values.
- copy [bool, default=True] set to False to perform inplace row normalization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSR matrix).

See also:

normalize Equivalent function without the estimator API.
Notes

This estimator is stateless (besides constructor parameters), the fit method does nothing but is useful when used in a pipeline.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Examples

```python
>>> from sklearn.preprocessing import Normalizer
>>> X = [[4, 1, 2, 2], ...
... [1, 3, 9, 3], ...
... [5, 7, 5, 1]]
>>> transformer = Normalizer().fit(X)  # fit does nothing.
>>> transformer
Normalizer()
>>> transformer.transform(X)
array([[0.8, 0.2, 0.4, 0.4],
       [0.1, 0.3, 0.9, 0.3],
       [0.5, 0.7, 0.5, 0.1]])
```

Methods

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<tr>
<th>Method</th>
<th>Description</th>
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<td>fit(X[, y])</td>
<td>Do nothing and return the estimator unchanged</td>
</tr>
<tr>
<td>fit_transform(X[, y])</td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>set_params(**params)</td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td>transform(X[, copy])</td>
<td>Scale each non zero row of X to unit norm</td>
</tr>
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</table>

**fit** (X, y=None)

Do nothing and return the estimator unchanged

This method is just there to implement the usual API and hence work in pipelines.

Parameters

- X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to estimate the normalization parameters.
- y [None] Ignored.

Returns


**fit_transform** (X, y=None, **fit_params)

Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

- X [array-like of shape (n_samples, n_features)] Input samples.
y  [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params**  [dict] Additional fit parameters.

Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params  *(deep=True)*

Get parameters for this estimator.

Parameters

deep  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

set_params  (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params**  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform  *(X, copy=None)*

Scale each non zero row of X to unit norm

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to normalize, row by row. scipy.sparse matrices should be in CSR format to avoid an un-necessary copy.

copy  [bool, default=None] Copy the input X or not.

Returns

X_tr  [{ndarray, sparse matrix} of shape (n_samples, n_features)] Transformed array.

Examples using sklearn.preprocessing.Normalizer

- Scalable learning with polynomial kernel approximation
- Compare the effect of different scalers on data with outliers
- Clustering text documents using k-means
7.33.11 sklearn.preprocessing.OneHotEncoder

class sklearn.preprocessing.OneHotEncoder (*, categories='auto', drop=None, sparse=True,
dtype=<class 'numpy.float64'>, handle_unknown='error')

Encode categorical features as a one-hot numeric array.

The input to this transformer should be an array-like of integers or strings, denoting the values taken on by categorical (discrete) features. The features are encoded using a one-hot (aka ‘one-of-K’ or ‘dummy’) encoding scheme. This creates a binary column for each category and returns a sparse matrix or dense array (depending on the sparse parameter).

By default, the encoder derives the categories based on the unique values in each feature. Alternatively, you can also specify the categories manually.

This encoding is needed for feeding categorical data to many scikit-learn estimators, notably linear models and SVMs with the standard kernels.

Note: a one-hot encoding of y labels should use a LabelBinarizer instead.

Read more in the User Guide.

Changed in version 0.20.

Parameters

categories ['auto' or a list of array-like, default='auto'] Categories (unique values) per feature:

• ‘auto’ : Determine categories automatically from the training data.

• list : categories[i] holds the categories expected in the ith column. The passed categories should not mix strings and numeric values within a single feature, and should be sorted in case of numeric values.

The used categories can be found in the categories_ attribute.

New in version 0.20.

drop [{'first’, ‘if_binary’} or a array-like of shape (n_features.), default=None] Specifies a methodology to use to drop one of the categories per feature. This is useful in situations where perfectly collinear features cause problems, such as when feeding the resulting data into a neural network or an unregularized regression.

However, dropping one category breaks the symmetry of the original representation and can therefore induce a bias in downstream models, for instance for penalized linear classification or regression models.

• None : retain all features (the default).

• ‘first’ : drop the first category in each feature. If only one category is present, the feature will be dropped entirely.

• ‘if_binary’ : drop the first category in each feature with two categories. Features with 1 or more than 2 categories are left intact.

array : drop[i] is the category in feature X[:, i] that should be dropped.

Changed in version 0.23: Added option ‘if_binary’.

sparse [bool, default=True] Will return sparse matrix if set True else will return an array.

dtype [number type, default=float] Desired dtype of output.

handle_unknown [{'error’, ‘ignore’}, default='error’] Whether to raise an error or ignore if an unknown categorical feature is present during transform (default is to raise). When this
parameter is set to ‘ignore’ and an unknown category is encountered during transform, the resulting one-hot encoded columns for this feature will be all zeros. In the inverse transform, an unknown category will be denoted as None.

Attributes

categories_ [list of arrays] The categories of each feature determined during fitting (in order of the features in X and corresponding with the output of transform). This includes the category specified in drop (if any).

drop_idx_ [array of shape (n_features,)]

- drop_idx_[i] is the index in categories_[i] of the category to be dropped for each feature.
- drop_idx_[i] = None if no category is to be dropped from the feature with index i, e.g. when drop='if_binary' and the feature isn’t binary.
- drop_idx_ = None if all the transformed features will be retained.

Changed in version 0.23: Added the possibility to contain None values.

See also:

OrdinalEncoder Performs an ordinal (integer) encoding of the categorical features.

sklearn.feature_extraction.DictVectorizer Performs a one-hot encoding of dictionary items (also handles string-valued features).

sklearn.feature_extraction.FeatureHasher Performs an approximate one-hot encoding of dictionary items or strings.

LabelBinarizer Binarizes labels in a one-vs-all fashion.

MultiLabelBinarizer Transforms between iterable of iterables and a multilabel format, e.g. a (samples x classes) binary matrix indicating the presence of a class label.

Examples

Given a dataset with two features, we let the encoder find the unique values per feature and transform the data to a binary one-hot encoding.

```python
>>> from sklearn.preprocessing import OneHotEncoder
```

One can discard categories not seen during fit:

```python
>>> enc = OneHotEncoder(handle_unknown='ignore')
>>> X = [['Male', 1], ['Female', 3], ['Female', 2]]
>>> enc.fit(X)
OneHotEncoder(handle_unknown='ignore')
>>> enc.categories_
[array(['Female', 'Male'], dtype=object), array([1, 2, 3], dtype=object)]
>>> enc.transform([[1, 2, 3], [2, 3, 4]])
array([[1., 0., 0., 0., 0.],
       [0., 1., 0., 0., 0.]])
>>> enc.inverse_transform([[0, 1, 1, 0, 0], [0, 0, 1, 0, 0]])
array(['Male', 1],
      [None, 2],
      dtype=object)
>>> enc.get_feature_names(['gender', 'group'])
array(['gender_Female', 'gender_Male', 'group_1', 'group_2', 'group_3'],
      dtype=object)
```
One can always drop the first column for each feature:

```python
>>> drop_enc = OneHotEncoder(drop='first').fit(X)
>>> drop_enc.categories_
[array(['Female', 'Male'], dtype=object), array([1, 2, 3], dtype=object)]
>>> drop_enc.transform([[['Female', 1], ['Male', 2]]].toarray()
array([[0., 0., 0.],
       [1., 1., 0.]])
```

Or drop a column for feature only having 2 categories:

```python
>>> drop_binary_enc = OneHotEncoder(drop='if_binary').fit(X)
>>> drop_binary_enc.transform([[['Female', 1], ['Male', 2]]].toarray()
array([[0., 1., 0., 0.],
       [1., 0., 1., 0.]])
```

**Methods**

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**fit**

Fit OneHotEncoder to X.

**Parameters**

- **X** [array-like, shape [n_samples, n_features]] The data to determine the categories of each feature.
- **y** [None] Ignored. This parameter exists only for compatibility with Pipeline.

**Returns**

- **self**

**fit_transform**

Fit OneHotEncoder to X, then transform X.

Equivalent to fit(X).transform(X) but more convenient.

**Parameters**

- **X** [array-like, shape [n_samples, n_features]] The data to encode.
- **y** [None] Ignored. This parameter exists only for compatibility with Pipeline.

**Returns**

- **X_out** [sparse matrix if sparse= True else a 2-d array] Transformed input.

**get_feature_names**

Return feature names for output features.

**Parameters**
**input_features**  [list of str of shape (n_features,)] String names for input features if available. By default, “x0”, “x1”, … “xn_features” is used.

**Returns**

**output_feature_names**  [ndarray of shape (n_output_features,)] Array of feature names.

**get_params** *(deep=True)*
Get parameters for this estimator.

**Parameters**

**deep**  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params**  [dict] Parameter names mapped to their values.

**inverse_transform** *(X)*
Convert the data back to the original representation.

In case unknown categories are encountered (all zeros in the one-hot encoding), None is used to represent this category.

**Parameters**

**X**  [array-like or sparse matrix, shape [n_samples, n_encoded_features]] The transformed data.

**Returns**

**X_tr**  [array-like, shape [n_samples, n_features]] Inverse transformed array.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as **Pipeline**). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

**Parameters**

**params**  [dict] Estimator parameters.

**Returns**

**self**  [estimator instance] Estimator instance.

**transform** *(X)*
Transform X using one-hot encoding.

**Parameters**

**X**  [array-like, shape [n_samples, n_features]] The data to encode.

**Returns**

**X_out**  [sparse matrix if sparse=True else a 2-d array] Transformed input.
Examples using sklearn.preprocessing.OneHotEncoder

- Release Highlights for scikit-learn 0.23
- Feature transformations with ensembles of trees
- Categorical Feature Support in Gradient Boosting
- Combine predictors using stacking
- Poisson regression and non-normal loss
- Tweedie regression on insurance claims
- Permutation Importance vs Random Forest Feature Importance (MDI)
- Common pitfalls in interpretation of coefficients of linear models
- Column Transformer with Mixed Types

7.33.12 sklearn.preprocessing.OrdinalEncoder

```python
class sklearn.preprocessing.OrdinalEncoder(*, categories='auto', dtype=\<class 'numpy.float64'>, handle_unknown='error', unknown_value=None)
```

Encode categorical features as an integer array.

The input to this transformer should be an array-like of integers or strings, denoting the values taken on by categorical (discrete) features. The features are converted to ordinal integers. This results in a single column of integers (0 to n_categories - 1) per feature.

Read more in the User Guide.

New in version 0.20.

**Parameters**

- **categories** ['auto' or a list of array-like, default='auto'] Categories (unique values) per feature:
  - 'auto': Determine categories automatically from the training data.
  - list: categories[i] holds the categories expected in the ith column. The passed categories should not mix strings and numeric values, and should be sorted in case of numeric values.

  The used categories can be found in the `categories_` attribute.

- **dtype** [number type, default np.float64] Desired dtype of output.

- **handle_unknown** [{'error', 'use_encoded_value'}, default='error'] When set to 'error' an error will be raised in case an unknown categorical feature is present during transform. When set to 'use_encoded_value', the encoded value of unknown categories will be set to the value given for the parameter `unknown_value` during `fit`. In `inverse_transform` an unknown category will be denoted as `None`.

  New in version 0.24.

- **unknown_value** [int or np.nan, default=None] When the parameter `handle_unknown` is set to 'use_encoded_value', this parameter is required and will set the encoded value of unknown categories. It has to be distinct from the values used to encode any of the categories in `fit`.

  If set to `np.nan`, the `dtype` parameter must be a float dtype.

  New in version 0.24.
Attributes

```
categories_  [list of arrays] The categories of each feature determined during fit (in order of the features in X and corresponding with the output of transform). This does not include categories that weren’t seen during fit.
```

See also:

`OneHotEncoder` Performs a one-hot encoding of categorical features.

`LabelEncoder` Encodes target labels with values between 0 and n_classes-1.

Examples

Given a dataset with two features, we let the encoder find the unique values per feature and transform the data to an ordinal encoding.

```
>>> from sklearn.preprocessing import OrdinalEncoder
>>> enc = OrdinalEncoder()
>>> X = [['Male', 1], ['Female', 3], ['Female', 2]]
>>> enc.fit(X)
OrdinalEncoder()
>>> enc.categories_
[array(['Female', 'Male'], dtype=object), array([1, 2, 3], dtype=object)]
>>> enc.transform([['Female', 3], ['Male', 1]])
array([[0., 2.],
       [1., 0.]])
```

Methods

```
fit(X[, y])  Fit the OrdinalEncoder to X.
fit_transform(X[, y], **fit_params)  Fit to data, then transform it.
get_params([deep])  Get parameters for this estimator.
inverse_transform(X)  Convert the data back to the original representation.
set_params(**params)  Set the parameters of this estimator.
transform(X)  Transform X to ordinal codes.
```

```
fit(X, y=None)  Fit the OrdinalEncoder to X.

Parameters

X  [array-like, shape [n_samples, n_features]] The data to determine the categories of each feature.

y  [None] Ignored. This parameter exists only for compatibility with Pipeline.

Returns

self

fit_transform(X, y=None, **fit_params)
```
Fit to data, then transform it.

Fits transformer to \( X \) and \( y \) with optional parameters \( \text{fit\_params} \) and returns a transformed version of \( X \).

**Parameters**

- **\( X \)** [array-like of shape (\( n\_\text{samples}, n\_\text{features} \))] Input samples.
- **\( y \)** [array-like of shape (\( n\_\text{samples} \), or (\( n\_\text{samples}, n\_\text{outputs} \)), default=None] Target values (None for unsupervised transformations).

**\( \text{fit\_params} \)** [dict] Additional fit parameters.

**Returns**

- **\( X\_\text{new} \)** [ndarray array of shape (\( n\_\text{samples}, n\_\text{features\_new} \))] Transformed array.

**get\_params** (\( \text{deep}=\text{True} \))

Get parameters for this estimator.

**Parameters**

- **\( \text{deep} \)** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **\( \text{params} \)** [dict] Parameter names mapped to their values.

**inverse\_transform** (\( X \))

Convert the data back to the original representation.

**Parameters**

- **\( X \)** [array-like or sparse matrix, shape [\( n\_\text{samples, n\_\text{encoded\_features}} \])] The transformed data.

**Returns**

- **\( X\_\text{tr} \)** [array-like, shape [\( n\_\text{samples, n\_\text{features}} \])] Inverse transformed array.

**set\_params** (**\( \text{params} \))

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as :class:`Pipeline`). The latter have parameters of the form \(<\text{component}>__<\text{parameter}>\) so that it’s possible to update each component of a nested object.

**Parameters**

- **\( \text{params} \)** [dict] Estimator parameters.

**Returns**

- **\( \text{self} \)** [estimator instance] Estimator instance.

**transform** (\( X \))

Transform \( X \) to ordinal codes.

**Parameters**

- **\( X \)** [array-like, shape [\( n\_\text{samples, n\_\text{features}} \])] The data to encode.

**Returns**

- **\( X\_\text{out} \)** [sparse matrix or a 2-d array] Transformed input.
Examples using `sklearn.preprocessing.OrdinalEncoder`

- Categorical Feature Support in Gradient Boosting
- Combine predictors using stacking
- Poisson regression and non-normal loss

### 7.33.13 sklearn.preprocessing.PolynomialFeatures

```python
class sklearn.preprocessing.PolynomialFeatures (degree=2, *, interaction_only=False, include_bias=True, order='C')
```

Generate polynomial and interaction features.

Generate a new feature matrix consisting of all polynomial combinations of the features with degree less than or equal to the specified degree. For example, if an input sample is two dimensional and of the form \([a, b]\), the degree-2 polynomial features are \([1, a, b, a^2, ab, b^2]\).

**Parameters**

- `degree` [int, default=2] The degree of the polynomial features.
- `interaction_only` [bool, default=False] If true, only interaction features are produced: features that are products of at most `degree` distinct input features (so not \(x[1] \times 2, x[0] \times x[2] \times 3\), etc.).
- `include_bias` [bool, default=True] If True (default), then include a bias column, the feature in which all polynomial powers are zero (i.e. a column of ones - acts as an intercept term in a linear model).
- `order` [{‘C’, ‘F’}, default=’C’] Order of output array in the dense case. ‘F’ order is faster to compute, but may slow down subsequent estimators.

**Attributes**

- `powers_` [ndarray of shape (n_output_features, n_input_features)] `powers_[i, j]` is the exponent of the jth input in the ith output.
- `n_input_features_` [int] The total number of input features.
- `n_output_features_` [int] The total number of polynomial output features. The number of output features is computed by iterating over all suitably sized combinations of input features.

**Notes**

Be aware that the number of features in the output array scales polynomially in the number of features of the input array, and exponentially in the degree. High degrees can cause overfitting.

See `examples/linear_model/plot_polynomial_interpolation.py`
Examples

```python
>>> import numpy as np
>>> from sklearn.preprocessing import PolynomialFeatures
>>> X = np.arange(6).reshape(3, 2)
>>> X
array([[0, 1],
       [2, 3],
       [4, 5]])
>>> poly = PolynomialFeatures(2)
>>> poly.fit_transform(X)
array([[ 1., 0., 1., 0., 0., 1.],
       [ 1., 2., 3., 4., 6., 9.],
       [ 1., 4., 5., 16., 20., 25.]])
>>> poly = PolynomialFeatures(interaction_only=True)
>>> poly.fit_transform(X)
array([[ 1., 0., 1.],
       [ 1., 2., 3., 6.],
       [ 1., 4., 5., 20.]])
```

Methods

- `fit(X[, y])` Compute number of output features.
- `fit_transform(X[, y])` Fit to data, then transform it.
- `get_feature_names([input_features])` Return feature names for output features
- `get_params([deep])` Get parameters for this estimator.
- `set_params(**params)` Set the parameters of this estimator.
- `transform(X)` Transform data to polynomial features

```python
fit(X, y=None)  
Compute number of output features.

Parameters

X  [array-like, sparse matrix] of shape (n_samples, n_features)] The data.

y  [None] Ignored.

Returns


fit_transform(X, y=None, **fit_params)
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

X  [array-like of shape (n_samples, n_features)] Input samples.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params  [dict] Additional fit parameters.

Returns
```
X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_feature_names (input_features=None)
Return feature names for output features

Parameters
input_features  [list of str of shape (n_features,), default=None] String names for input features if available. By default, “x0”, “x1”, … “xn_features” is used.

Returns
output_feature_names  [list of str of shape (n_output_features,)]

get_params (deep=True)
Get parameters for this estimator.

Parameters
depth  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns
params  [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>._<parameter> so that it’s possible to update each component of a nested object.

Parameters
**params  [dict] Estimator parameters.

Returns
self  [estimator instance] Estimator instance.

transform (X)
Transform data to polynomial features

Parameters

X  [(array-like, sparse matrix) of shape (n_samples, n_features)] The data to transform, row by row.

Prefer CSR over CSC for sparse input (for speed), but CSC is required if the degree is 4 or higher. If the degree is less than 4 and the input format is CSC, it will be converted to CSR, have its polynomial features generated, then converted back to CSC.

If the degree is 2 or 3, the method described in “Leveraging Sparsity to Speed Up Polynomial Feature Expansions of CSR Matrices Using K-Simplex Numbers” by Andrew Nyström and John Hughes is used, which is much faster than the method used on CSC input. For this reason, a CSC input will be converted to CSR, and the output will be converted back to CSC prior to being returned, hence the preference of CSR.

Returns
XP  [(ndarray, sparse matrix) of shape (n_samples, NP)] The matrix of features, where NP is the number of polynomial features generated from the combination of inputs. If a sparse matrix is provided, it will be converted into a sparse csr_matrix.
Examples using sklearn.preprocessing.PolynomialFeatures

• Release Highlights for scikit-learn 0.24
• Polynomial interpolation
• Robust linear estimator fitting
• Poisson regression and non-normal loss
• Underfitting vs. Overfitting

7.33.14 sklearn.preprocessing.PowerTransformer
class sklearn.preprocessing.PowerTransformer(method='yeo-johnson', *, standardize=True, copy=True)

Apply a power transform featurewise to make data more Gaussian-like.

Power transforms are a family of parametric, monotonic transformations that are applied to make data more Gaussian-like. This is useful for modeling issues related to heteroscedasticity (non-constant variance), or other situations where normality is desired.

Currently, PowerTransformer supports the Box-Cox transform and the Yeo-Johnson transform. The optimal parameter for stabilizing variance and minimizing skewness is estimated through maximum likelihood.

Box-Cox requires input data to be strictly positive, while Yeo-Johnson supports both positive or negative data.

By default, zero-mean, unit-variance normalization is applied to the transformed data.

Read more in the User Guide.

New in version 0.20.

Parameters

method [{'yeo-johnson', 'box-cox'}, default='yeo-johnson'] The power transform method. Available methods are:
• 'yeo-johnson' [1], works with positive and negative values
• 'box-cox' [2], only works with strictly positive values

standardize [bool, default=True] Set to True to apply zero-mean, unit-variance normalization to the transformed output.

copy [bool, default=True] Set to False to perform inplace computation during transformation.

Attributes

lambdas_ [ndarray of float of shape (n_features,)] The parameters of the power transformation for the selected features.

See also:

power_transform Equivalent function without the estimator API.
QuantileTransformer Maps data to a standard normal distribution with the parameter output_distribution='normal'.

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Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

References

[1], [2]

Examples

```python
>>> import numpy as np
>>> from sklearn.preprocessing import PowerTransformer
>>> pt = PowerTransformer()
>>> data = [[1, 2], [3, 2], [4, 5]]
>>> print(pt.fit(data))
PowerTransformer()
>>> print(pt.lambdas_)
[ 1.386... -3.100...]
>>> print(pt.transform(data))
[[-1.316... -0.707...]
 [ 0.209... -0.707...]
 [ 1.106... 1.414...]]
```

Methods

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<td>Estimate the optimal parameter lambda for each feature.</td>
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<tr>
<td><code>fit_transform(X, y)</code></td>
<td>Fit to data, then transform it.</td>
</tr>
<tr>
<td><code>get_params([deep])</code></td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td><code>inverse_transform(X)</code></td>
<td>Apply the inverse power transformation using the fitted lambdas.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
</tr>
<tr>
<td><code>transform(X)</code></td>
<td>Apply the power transform to each feature using the fitted lambdas.</td>
</tr>
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</table>

`fit(X, y=None)`

Estimate the optimal parameter lambda for each feature.

The optimal lambda parameter for minimizing skewness is estimated on each feature independently using maximum likelihood.

Parameters:

- **X** [array-like of shape (n_samples, n_features)] The data used to estimate the optimal transformation parameters.
- **y** [None] Ignored.

Returns:

- **self** [object] Fitted transformer.
**fit_transform** (*X*, *y=None*)

Fit to data, then transform it.

Fits transformer to *X* and *y* with optional parameters **fit_params** and returns a transformed version of *X*.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**Returns**

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.

**inverse_transform** (*X*)

Apply the inverse power transformation using the fitted lambdas.

The inverse of the Box-Cox transformation is given by:

```
if lambda_ == 0:
    X = exp(X_trans)
else:
    X = (X_trans * lambda_ + 1) ** (1 / lambda_)
```

The inverse of the Yeo-Johnson transformation is given by:

```
if X >= 0 and lambda_ == 0:
    X = exp(X_trans) - 1
elif X >= 0 and lambda_ != 0:
    X = (X_trans * lambda_ + 1) ** (1 / lambda_) - 1
elif X < 0 and lambda_ != 2:
    X = 1 - (-2 - lambda_) * X_trans + 1) ** (1 / (2 - lambda_))
elif X < 0 and lambda_ == 2:
    X = 1 - exp(-X_trans)
```

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] The transformed data.

**Returns**

- **X** [ndarray of shape (n_samples, n_features)] The original data.

**set_params**(**params**)  
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform**(X)

Apply the power transform to each feature using the fitted lambdas.

**Parameters**

X [array-like of shape (n_samples, n_features)] The data to be transformed using a power transformation.

**Returns**

X_trans [ndarray of shape (n_samples, n_features)] The transformed data.

**Examples using sklearn.preprocessing.PowerTransformer**

- Map data to a normal distribution
- Compare the effect of different scalers on data with outliers

**7.33.15 sklearn.preprocessing.QuantileTransformer**

class sklearn.preprocessing.QuantileTransformer(*, n_quantiles=1000, output_distribution='uniform', ignore_implicit_zeros=False, subsample=100000, random_state=None, copy=True)

Transform features using quantiles information.

This method transforms the features to follow a uniform or a normal distribution. Therefore, for a given feature, this transformation tends to spread out the most frequent values. It also reduces the impact of (marginal) outliers: this is therefore a robust preprocessing scheme.

The transformation is applied on each feature independently. First an estimate of the cumulative distribution function of a feature is used to map the original values to a uniform distribution. The obtained values are then mapped to the desired output distribution using the associated quantile function. Features values of new/unseen data that fall below or above the fitted range will be mapped to the bounds of the output distribution. Note that this transform is non-linear. It may distort linear correlations between variables measured at the same scale but renders variables measured at different scales more directly comparable.

Read more in the User Guide.

New in version 0.19.

**Parameters**

**n_quantiles** [int, default=1000 or n_samples] Number of quantiles to be computed. It corresponds to the number of landmarks used to discretize the cumulative distribution function. If n_quantiles is larger than the number of samples, n_quantiles is set to the number of samples as a larger number of quantiles does not give a better approximation of the cumulative distribution function estimator.
**output_distribution** ([{'uniform', 'normal'}, default='uniform'] Marginal distribution for the transformed data. The choices are ‘uniform’ (default) or ‘normal’.

**ignore_implicit_zeros** [bool, default=False] Only applies to sparse matrices. If True, the sparse entries of the matrix are discarded to compute the quantile statistics. If False, these entries are treated as zeros.

**subsample** [int, default=1e5] Maximum number of samples used to estimate the quantiles for computational efficiency. Note that the subsampling procedure may differ for value-identical sparse and dense matrices.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation for subsampling and smoothing noise. Please see subsample for more details. Pass an int for reproducible results across multiple function calls. See Glossary

**copy** [bool, default=True] Set to False to perform inplace transformation and avoid a copy (if the input is already a numpy array).

**Attributes**

- **n_quantiles_** [int] The actual number of quantiles used to discretize the cumulative distribution function.
- **quantiles_** [ndarray of shape (n_quantiles, n_features)] The values corresponding the quantiles of reference.
- **references_** [ndarray of shape (n_quantiles, )] Quantiles of references.

**See also:**

- **quantile_transform** Equivalent function without the estimator API.
- **PowerTransformer** Perform mapping to a normal distribution using a power transform.
- **StandardScaler** Perform standardization that is faster, but less robust to outliers.
- **RobustScaler** Perform robust standardization that removes the influence of outliers but does not put outliers and inliers on the same scale.

**Notes**

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.preprocessing import QuantileTransformer
>>> rng = np.random.RandomState(0)
>>> X = np.sort(rng.normal(loc=0.5, scale=0.25, size=(25, 1)), axis=0)
>>> qt = QuantileTransformer(n_quantiles=10, random_state=0)
>>> qt.fit_transform(X)
array([...])
```
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**fit** `(X, y=None)`

Compute the quantiles used for transforming.

Parameters

- **X** *(array-like, sparse matrix)* of shape *(n_samples, n_features)* The data used to scale along the features axis. If a sparse matrix is provided, it will be converted into a sparse *csc_matrix*. Additionally, the sparse matrix needs to be nonnegative if *ignore_implicit_zeros* is False.

- **y** *(None)* Ignored.

Returns

- **self** *(object)* Fitted transformer.

**fit_transform** `(X, y=None, **fit_params)`

Fit to data, then transform it.

Fits transformer to `X` and `y` with optional parameters `fit_params` and returns a transformed version of `X`.

Parameters

- **X** *(array-like of shape (n_samples, n_features))* Input samples.

- **y** *(array-like of shape (n_samples,) or (n_samples, n_outputs), default=None)* Target values (None for unsupervised transformations).

- ****fit_params** *(dict)* Additional fit parameters.

Returns

- **X_new** *(ndarray array of shape (n_samples, n_features_new))* Transformed array.

**get_params** *(deep=True)*

Get parameters for this estimator.

Parameters

- **deep** *(bool, default=True)* If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- **params** *(dict)* Parameter names mapped to their values.

**inverse_transform** `(X)`

Back-projection to the original space.

Parameters

- **X** *(array-like, sparse matrix)* of shape *(n_samples, n_features)* The data used to scale along the features axis. If a sparse matrix is provided, it will be converted into
a sparse csc_matrix. Additionally, the sparse matrix needs to be nonnegative if ignore_implicit_zeros is False.

Returns

Xt [(ndarray, sparse matrix) of (n_samples, n_features)] The projected data.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Feature-wise transformation of the data.

Parameters

X [(array-like, sparse matrix) of shape (n_samples, n_features)] The data used to scale along the features axis. If a sparse matrix is provided, it will be converted into a sparse csc_matrix. Additionally, the sparse matrix needs to be nonnegative if ignore_implicit_zeros is False.

Returns

Xt [(ndarray, sparse matrix) of shape (n_samples, n_features)] The projected data.

Examples using sklearn.preprocessing.QuantileTransformer

- Partial Dependence and Individual Conditional Expectation Plots
- Effect of transforming the targets in regression model
- Map data to a normal distribution
- Compare the effect of different scalers on data with outliers

7.33.16 sklearn.preprocessing.RobustScaler

class sklearn.preprocessing.RobustScaler(*, with_centering=True, with_scaling=True, quantile_range=25.0, 75.0, copy=True, unit_variance=False)

Scale features using statistics that are robust to outliers.

This Scaler removes the median and scales the data according to the quantile range (defaults to IQR: Interquartile Range). The IQR is the range between the 1st quartile (25th quantile) and the 3rd quartile (75th quantile).

Centering and scaling happen independently on each feature by computing the relevant statistics on the samples in the training set. Median and interquartile range are then stored to be used on later data using the transform method.
Standardization of a dataset is a common requirement for many machine learning estimators. Typically this is done by removing the mean and scaling to unit variance. However, outliers can often influence the sample mean / variance in a negative way. In such cases, the median and the interquartile range often give better results.

New in version 0.17.

Read more in the User Guide.

Parameters

- **with_centering** [bool, default=True] If True, center the data before scaling. This will cause transform to raise an exception when attempted on sparse matrices, because centering them entails building a dense matrix which in common use cases is likely to be too large to fit in memory.
- **with_scaling** [bool, default=True] If True, scale the data to interquartile range.
- **quantile_range** [tuple (q_min, q_max), 0.0 < q_min < q_max < 100.0, default=(25.0, 75.0), == (1st quantile, 3rd quantile), == IQR] Quantile range used to calculate scale_.
  New in version 0.18.
- **copy** [bool, default=True] If False, try to avoid a copy and do inplace scaling instead. This is not guaranteed to always work inplace; e.g. if the data is not a NumPy array or scipy.sparse CSR matrix, a copy may still be returned.
- **unit_variance** [bool, default=False] If True, scale data so that normally distributed features have a variance of 1. In general, if the difference between the x-values of \( q_{\text{max}} \) and \( q_{\text{min}} \) for a standard normal distribution is greater than 1, the dataset will be scaled down. If less than 1, the dataset will be scaled up.
  New in version 0.24.

Attributes

- **center_** [array of floats] The median value for each feature in the training set.
- **scale_** [array of floats] The (scaled) interquartile range for each feature in the training set.
  New in version 0.17: scale_ attribute.

See also:

- **robust_scale** Equivalent function without the estimator API.
- **PCA** Further removes the linear correlation across features with ‘whiten=True’.

Notes

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Examples

```python
>>> from sklearn.preprocessing import RobustScaler
>>> X = [[ 1., -2., 2.],
...      [ -2., 1., 3.],
...      [ 4., 1., -2.]]
>>> transformer = RobustScaler().fit(X)
>>> transformer
RobustScaler()
>>> transformer.transform(X)
array([[ 0., -2.,  0.],
       [-1.,  0.,  0.4],
       [ 1.,  0., -1.6]])
```

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**fit (X, y=None)**
Compute the median and quantiles to be used for scaling.

Parameters

- **X** ([array-like, sparse matrix] of shape [n_samples, n_features]) The data used to compute the median and quantiles used for later scaling along the features axis.
- **y** [None] Ignored.

Returns

- **self** [object] Fitted scaler.

**fit_transform (X, y=None, **fit_params)**
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

- **X** [array-like of shape (n_samples, n_features)] Input samples.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params** [dict] Additional fit parameters.

Returns

- **X_new** [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.
Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

inverse_transform(X)
Scale back the data to the original representation

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) The rescaled data to be transformed back.

Returns

X_tr [ndarray, sparse matrix] of shape (n_samples, n_features) Transformed array.

set_params(**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform(X)
Center and scale the data.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) The data used to scale along the specified axis.

Returns

X_tr [ndarray, sparse matrix] of shape (n_samples, n_features) Transformed array.

Examples using sklearn.preprocessing.RobustScaler

- Compare the effect of different scalers on data with outliers

7.33.17 sklearn.preprocessing.StandardScaler

class sklearn.preprocessing.StandardScaler(*, copy=True, with_mean=True, with_std=True)
Standardize features by removing the mean and scaling to unit variance

The standard score of a sample $x$ is calculated as:

$$ z = (x - u) / s $$
where $u$ is the mean of the training samples or zero if $\text{with_mean}=\text{False}$, and $s$ is the standard deviation of the training samples or one if $\text{with_std}=\text{False}$.

Centering and scaling happen independently on each feature by computing the relevant statistics on the samples in the training set. Mean and standard deviation are then stored to be used on later data using $\text{transform}$.

Standardization of a dataset is a common requirement for many machine learning estimators: they might behave badly if the individual features do not more or less look like standard normally distributed data (e.g. Gaussian with 0 mean and unit variance).

For instance many elements used in the objective function of a learning algorithm (such as the RBF kernel of Support Vector Machines or the L1 and L2 regularizers of linear models) assume that all features are centered around 0 and have variance in the same order. If a feature has a variance that is orders of magnitude larger than others, it might dominate the objective function and make the estimator unable to learn from other features correctly as expected.

This scaler can also be applied to sparse CSR or CSC matrices by passing $\text{with_mean}=\text{False}$ to avoid breaking the sparsity structure of the data.

Read more in the User Guide.

**Parameters**

- **copy** [bool, default=True] If False, try to avoid a copy and do inplace scaling instead. This is not guaranteed to always work inplace; e.g. if the data is not a NumPy array or scipy.sparse CSR matrix, a copy may still be returned.

- **with_mean** [bool, default=True] If True, center the data before scaling. This does not work (and will raise an exception) when attempted on sparse matrices, because centering them entails building a dense matrix which in common use cases is likely to be too large to fit in memory.

- **with_std** [bool, default=True] If True, scale the data to unit variance (or equivalently, unit standard deviation).

**Attributes**

- **scale_** [ndarray of shape (n_features,) or None] Per feature relative scaling of the data. This is calculated using np.sqrt(var_). Equal to None when $\text{with_std}=\text{False}$.

  New in version 0.17: scale_

- **mean_** [ndarray of shape (n_features,) or None] The mean value for each feature in the training set. Equal to None when $\text{with_mean}=\text{False}$.

- **var_** [ndarray of shape (n_features,) or None] The variance for each feature in the training set. Used to compute scale_. Equal to None when $\text{with_std}=\text{False}$.

- **n_samples_seen_** [int or ndarray of shape (n_features,)] The number of samples processed by the estimator for each feature. If there are no missing samples, the n_samples_seen will be an integer, otherwise it will be an array of dtype int. If sample_weights are used it will be a float (if no missing data) or an array of dtype float that sums the weights seen so far. Will be reset on new calls to fit, but increments across partial_fit calls.

**See also:**

- **scale** Equivalent function without the estimator API.

- **PCA** Further removes the linear correlation across features with ‘whiten=True’.
Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.
We use a biased estimator for the standard deviation, equivalent to $\text{numpy.std}(x, \text{ddof}=0)$. Note that the choice of $\text{ddof}$ is unlikely to affect model performance.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Examples

```python
>>> from sklearn.preprocessing import StandardScaler
>>> data = [[0, 0], [0, 0], [1, 1], [1, 1]]
>>> scaler = StandardScaler()
>>> print(scaler.fit(data))
StandardScaler()
>>> print(scaler.mean_)
[0.5 0.5]
>>> print(scaler.transform(data))
[[-1. -1.]
 [-1. -1.]
 [ 1.  1.]
 [ 1.  1.]]
>>> print(scaler.transform([[2, 2]]))
[[3. 3.]]
```

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```

```python
fit (X, y=None, sample_weight=None)

Compute the mean and std to be used for later scaling.

Parameters

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] The data used to compute the mean and standard deviation used for later scaling along the features axis.
- **y** [None] Ignored.
- **sample_weight** [array-like of shape (n_samples,), default=None] Individual weights for each sample.

New in version 0.24: parameter `sample_weight` support to StandardScaler.

Returns

**fit_transform**(X, y=None, **fit_params)
Fit to data, then transform it.
Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

Parameters

X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values (None for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

**get_params**(deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**inverse_transform**(X, copy=None)
Scale back the data to the original representation.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data used to scale along the features axis.

copy [bool, default=None] Copy the input X or not.

Returns

X_tr [{ndarray, sparse matrix} of shape (n_samples, n_features)] Transformed array.

**partial_fit**(X, y=None, sample_weight=None)
Online computation of mean and std on X for later scaling.
All of X is processed as a single batch. This is intended for cases when fit is not feasible due to very large number of n_samples or because X is read from a continuous stream.


Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data used to compute the mean and standard deviation used for later scaling along the features axis.

y [None] Ignored.

sample_weight [array-like of shape (n_samples,), default=None] Individual weights for each sample.
New in version 0.24: parameter `sample_weight` support to StandardScaler.

**Returns**


**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**transform** (X, copy=None)

Perform standardization by centering and scaling

**Parameters**

X [{array-like, sparse matrix of shape (n_samples, n_features)] The data used to scale along the features axis.

copy [bool, default=None] Copy the input X or not.

**Returns**

X_tr [{ndarray, sparse matrix} of shape (n_samples, n_features)] Transformed array.

 Examples using `sklearn.preprocessing.StandardScaler`

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• Importance of Feature Scaling
• Feature discretization
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• SVM-Anova: SVM with univariate feature selection
• RBF SVM parameters

```python
preprocessing.add_dummy_feature(X, value=1.0)
```
Augment dataset with an additional dummy feature.

```python
preprocessing.binarize(X, *, threshold, copy)
```
Boolean thresholding of array-like or scipy.sparse matrix.

```python
preprocessing.label_binarize(y, *, classes)
```
Binarize labels in a one-vs-all fashion.

```python
preprocessing.maxabs_scale(X, *, axis, copy)
```
Scale each feature to the [-1, 1] range without breaking the sparsity.

```python
preprocessing.minmax_scale(X, *[, axis, copy])
```
Transform features by scaling each feature to a given range.

```python
preprocessing.normalize(X, *[, norm, axis, copy])
```
Scale input vectors individually to unit norm (vector length).

```python
preprocessing.quantile_transform(X, *[, axis, copy])
```
Transform features using quantiles information.

```python
preprocessing.robust_scale(X, *[, axis, copy])
```
Standardize a dataset along any axis

```python
preprocessing.scale(X, *[, axis, with_mean, copy])
```
Standardize a dataset along any axis.

```python
preprocessing.power_transform(X, *[, method, copy])
```
Power transforms are a family of parametric, monotonic transformations that are applied to make data more Gaussian-like.

### 7.33.18 sklearn.preprocessing.add_dummy_feature

**sklearn.preprocessing.add_dummy_feature** *(X, value=1.0)*

Augment dataset with an additional dummy feature.

This is useful for fitting an intercept term with implementations which cannot otherwise fit it directly.

**Parameters**

- *X* [{array-like, sparse matrix} of shape (n_samples, n_features)] Data.
- *value* [float] Value to use for the dummy feature.

**Returns**
X [{ndarray, sparse matrix} of shape (n_samples, n_features + 1)] Same data with dummy feature added as first column.

Examples

```python
>>> from sklearn.preprocessing import add_dummy_feature
>>> add_dummy_feature([[0, 1], [1, 0]])
array([[1., 0., 1.],
       [1., 1., 0.]])
```

### 7.33.19 sklearn.preprocessing.binarize

**sklearn.preprocessing.binarize** *(X, *, threshold=0.0, copy=True)*

Boolean thresholding of array-like or scipy.sparse matrix.

Read more in the *User Guide*.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to binarize, element by element. scipy.sparse matrices should be in CSR or CSC format to avoid an un-necessary copy.

- **threshold** [float, default=0.0] Feature values below or equal to this are replaced by 0, above it by 1. Threshold may not be less than 0 for operations on sparse matrices.

- **copy** [bool, default=True] set to False to perform inplace binarization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSR / CSC matrix and if axis is 1).

**Returns**

- **X_tr** [{ndarray, sparse matrix} of shape (n_samples, n_features)] The transformed data.

**See also:**

* Binarizer Performs binarization using the Transformer API (e.g. as part of a preprocessing Pipeline)*.

### 7.33.20 sklearn.preprocessing.label_binarize

**sklearn.preprocessing.label_binarize** *(y, *, classes, neg_label=0, pos_label=1, sparse_output=False)*

Binarize labels in a one-vs-all fashion.

Several regression and binary classification algorithms are available in scikit-learn. A simple way to extend these algorithms to the multi-class classification case is to use the so-called one-vs-all scheme.

This function makes it possible to compute this transformation for a fixed set of class labels known ahead of time.

**Parameters**

- **y** [array-like] Sequence of integer labels or multilabel data to encode.

- **classes** [array-like of shape (n_classes,)] Uniquely holds the label for each class.

- **neg_label** [int, default=0] Value with which negative labels must be encoded.

- **pos_label** [int, default=1] Value with which positive labels must be encoded.
sparse_output [bool, default=False] Set to true if output binary array is desired in CSR sparse format.

Returns

Y [{ndarray, sparse matrix} of shape (n_samples, n_classes)] Shape will be (n_samples, 1) for binary problems. Sparse matrix will be of CSR format.

See also:

LabelBinarizer Class used to wrap the functionality of label_binarize and allow for fitting to classes independently of the transform operation.

Examples

```python
>>> from sklearn.preprocessing import label_binarize
>>> label_binarize([1, 6], classes=[1, 2, 4, 6])
array([[1, 0, 0, 0],
       [0, 0, 0, 1]])
```

The class ordering is preserved:

```python
>>> label_binarize([1, 6], classes=[1, 6, 4, 2])
array([[1, 0, 0, 0],
       [0, 1, 0, 0]])
```

Binary targets transform to a column vector

```python
>>> label_binarize([\'yes\', \'no\', \'no\', \'yes\'], classes=[\'no\', \'yes\'])
array([[1],
       [0],
       [0],
       [1]])
```

Examples using sklearn.preprocessing.label_binarize

- Receiver Operating Characteristic (ROC)
- Precision-Recall

7.33.21 sklearn.preprocessing.maxabs_scale

sklearn.preprocessing.maxabs_scale (X, *, axis=0, copy=True)

Scale each feature to the [-1, 1] range without breaking the sparsity.

This estimator scales each feature individually such that the maximal absolute value of each feature in the training set will be 1.0.

This scaler can also be applied to sparse CSR or CSC matrices.

Parameters

- X [{array-like, sparse matrix} of shape (n_samples, n_features)] The data.
- axis [int, default=0] axis used to scale along. If 0, independently scale each feature, otherwise (if 1) scale each sample.
copy [bool, default=True] Set to False to perform inplace scaling and avoid a copy (if the input is already a numpy array).

Returns
X_tr [{ndarray, sparse matrix} of shape (n_samples, n_features)] The transformed data.

Warning: Risk of data leak Do not use maxabs_scale unless you know what you are doing. A common mistake is to apply it to the entire data before splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using MaxAbsScaler within a Pipeline in order to prevent most risks of data leaking: pipe = make_pipeline(MaxAbsScaler(), LogisticRegression()).

See also:

MaxAbsScaler Performs scaling to the [-1, 1] range using the Transformer API (e.g. as part of a preprocessing Pipeline).

Notes
NaNs are treated as missing values: disregarded to compute the statistics, and maintained during the data transformation.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

7.33.22 sklearn.preprocessing.minmax_scale

sklearn.preprocessing.minmax_scale (X, feature_range=0, 1, *, axis=0, copy=True)

Transform features by scaling each feature to a given range.

This estimator scales and translates each feature individually such that it is in the given range on the training set, i.e. between zero and one.

The transformation is given by (when axis=0):

\[
X_{std} = \frac{(X - X_{\text{min}}(axis=0))}{(X_{\text{max}}(axis=0) - X_{\text{min}}(axis=0))} \\
X_{scaled} = X_{std} \times (max - min) + min
\]

where min, max = feature_range.

The transformation is calculated as (when axis=0):

\[
X_{scaled} = scale \times X + min - X_{\text{min}}(axis=0) \times scale \\
where scale = (max - min) / (X_{\text{max}}(axis=0) - X_{\text{min}}(axis=0))
\]

This transformation is often used as an alternative to zero mean, unit variance scaling.

Read more in the User Guide.

New in version 0.17: minmax_scale function interface to MinMaxScaler.

Parameters
X [array-like of shape (n_samples, n_features)] The data.
**feature_range** [tuple (min, max), default=(0, 1)] Desired range of transformed data.

**axis** [int, default=0] Axis used to scale along. If 0, independently scale each feature, otherwise (if 1) scale each sample.

**copy** [bool, default=True] Set to False to perform inplace scaling and avoid a copy (if the input is already a numpy array).

**Returns**

**X_tr** [ndarray of shape (n_samples, n_features)] The transformed data.

**Warning:** Risk of data leak. Do not use *minmax_scale* unless you know what you are doing. A common mistake is to apply it to the entire data *before* splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using *MinMaxScaler* within a *Pipeline* in order to prevent most risks of data leaking: `pipe = make_pipeline(MinMaxScaler(), LogisticRegression())`.

**See also:**

*MinMaxScaler* Performs scaling to a given range using the Transformer API (e.g. as part of a preprocessing *Pipeline*).

**Notes**

For a comparison of the different scalers, transformers, and normalizers, see *examples/preprocessing/plot_all_scaling.py*.

**Examples using sklearn.preprocessing.minmax_scale**

- Compare the effect of different scalers on data with outliers

**7.33.23 sklearn.preprocessing.normalize**

`sklearn.preprocessing.normalize(X, norm='l2', *, axis=1, copy=True, return_norm=False)`

Scale input vectors individually to unit norm (vector length).

Read more in the *User Guide*.

**Parameters**

- **X** [{array-like, sparse matrix}] of shape (n_samples, n_features)] The data to normalize, element by element. scipy.sparse matrices should be in CSR format to avoid an unnecessary copy.
- **norm** [{‘l1’, ‘l2’, ‘max’}, default=’l2’] The norm to use to normalize each non zero sample (or each non-zero feature if axis is 0).
- **axis** [{0, 1}, default=1] axis used to normalize the data along. If 1, independently normalize each sample, otherwise (if 0) normalize each feature.
- **copy** [bool, default=True] set to False to perform inplace row normalization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSR matrix and if axis is 1).
- **return_norm** [bool, default=False] whether to return the computed norms
Returns

X  [{ndarray, sparse matrix} of shape (n_samples, n_features)] Normalized input X.

norms  [ndarray of shape (n_samples,) if axis=1 else (n_features,)] An array of norms along
given axis for X. When X is sparse, a NotImplementedError will be raised for norm ‘l1’ or
‘l2’.

See also:

Normalizer Performs normalization using the Transformer API (e.g. as part of a preprocessing
Pipeline).

Notes

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

7.33.24 sklearn.preprocessing.quantile_transform

sklearn.preprocessing.quantile_transform(X, *, axis=0, n_quantiles=1000,
output_distribution='uniform', ignore_implicit_zeros=False, subsample=100000,
random_state=None, copy=True)

Transform features using quantiles information.

This method transforms the features to follow a uniform or a normal distribution. Therefore, for a given feature,
this transformation tends to spread out the most frequent values. It also reduces the impact of (marginal) outliers:
this is therefore a robust preprocessing scheme.

The transformation is applied on each feature independently. First an estimate of the cumulative distribution
function of a feature is used to map the original values to a uniform distribution. The obtained values are then
mapped to the desired output distribution using the associated quantile function. Features values of new/unseen
data that fall below or above the fitted range will be mapped to the bounds of the output distribution. Note that
this transform is non-linear. It may distort linear correlations between variables measured at the same scale but
renders variables measured at different scales more directly comparable.

Read more in the User Guide.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The data to transform.

axis  [int, default=0] Axis used to compute the means and standard deviations along. If 0, trans-
form each feature, otherwise (if 1) transform each sample.

n_quantiles  [int, default=1000 or n_samples] Number of quantiles to be computed. It corre-
sponds to the number of landmarks used to discretize the cumulative distribution function.
If n_quantiles is larger than the number of samples, n_quantiles is set to the number of sam-
ples as a larger number of quantiles does not give a better approximation of the cumulative
distribution function estimator.

output_distribution  [{‘uniform’, ‘normal’}, default=’uniform’] Marginal distribution for the
transformed data. The choices are ‘uniform’ (default) or ‘normal’.

ignore_implicit_zeros  [bool, default=False] Only applies to sparse matrices. If True, the sparse
entries of the matrix are discarded to compute the quantile statistics. If False, these entries
are treated as zeros.
**subsample** [int, default=1e5] Maximum number of samples used to estimate the quantiles for computational efficiency. Note that the subsampling procedure may differ for value-identical sparse and dense matrices.

**random_state** [int, RandomState instance or None, default=None] Determines random number generation for subsampling and smoothing noise. Please see subsample for more details. Pass an int for reproducible results across multiple function calls. See Glossary

**copy** [bool, default=True] Set to False to perform inplace transformation and avoid a copy (if the input is already a numpy array). If True, a copy of X is transformed, leaving the original X unchanged

.. versionchanged:: 0.23 The default value of copy changed from False to True in 0.23.

Returns

Xt [ndarray, sparse matrix] of shape (n_samples, n_features) The transformed data.

See also:

QuantileTransformer Performs quantile-based scaling using the Transformer API (e.g. as part of a preprocessing Pipeline).

power_transform Maps data to a normal distribution using a power transformation.

scale Performs standardization that is faster, but less robust to outliers.

robust_scale Performs robust standardization that removes the influence of outliers but does not put outliers and inliers on the same scale.

Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

**Warning:** Risk of data leak

Do not use quantile_transform unless you know what you are doing. A common mistake is to apply it to the entire data before splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using QuantileTransformer within a Pipeline in order to prevent most risks of data leaking:

```python
pipe = make_pipeline(QuantileTransformer(), LogisticRegression())
```

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Examples

```python
>>> import numpy as np
>>> from sklearn.preprocessing import quantile_transform
>>> rng = np.random.RandomState(0)
>>> X = np.sort(rng.normal(loc=0.5, scale=0.25, size=(25, 1)), axis=0)
>>> quantile_transform(X, n_quantiles=10, random_state=0, copy=True)
array([...])
```
Examples using sklearn.preprocessing.quantile_transform

- Effect of transforming the targets in regression model

7.33.25 sklearn.preprocessing.robust_scale

sklearn.preprocessing.robust_scale(X, *, axis=0, with_centering=True, with_scaling=True, quantile_range=(25.0, 75.0), copy=True, unit_variance=False)

Standardize a dataset along any axis
Center to the median and component wise scale according to the interquartile range.
Read more in the User Guide.

Parameters

- **X**  
  [[array-like, sparse matrix] of shape (n_sample, n_features)] The data to center and scale.

- **axis**  
  [int, default=0] axis used to compute the medians and IQR along. If 0, independently scale each feature, otherwise (if 1) scale each sample.

- **with_centering**  
  [bool, default=True] If True, center the data before scaling.

- **with_scaling**  
  [bool, default=True] If True, scale the data to unit variance (or equivalently, unit standard deviation).

- **quantile_range**  
  [tuple (q_min, q_max), 0.0 < q_min < q_max < 100.0] default=(25.0, 75.0), == (1st quantile, 3rd quantile), == IQR Quantile range used to calculate scale_.
  New in version 0.18.

- **copy**  
  [bool, default=True] set to False to perform inplace row normalization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSR matrix and if axis is 1).

- **unit_variance**  
  [bool, default=False] If True, scale data so that normally distributed features have a variance of 1. In general, if the difference between the x-values of \( q_{\text{max}} \) and \( q_{\text{min}} \) for a standard normal distribution is greater than 1, the dataset will be scaled down. If less than 1, the dataset will be scaled up.
  New in version 0.24.

Returns

- **X_tr**  
  [[ndarray, sparse matrix] of shape (n_samples, n_features)] The transformed data.

See also:

RobustScaler Performs centering and scaling using the Transformer API (e.g. as part of a preprocessing Pipeline).
Notes

This implementation will refuse to center scipy.sparse matrices since it would make them non-sparse and would potentially crash the program with memory exhaustion problems.

Instead the caller is expected to either set explicitly with_centering=False (in that case, only variance scaling will be performed on the features of the CSR matrix) or to call X.toarray() if he/she expects the materialized dense array to fit in memory.

To avoid memory copy the caller should pass a CSR matrix.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

Warning: Risk of data leak

Do not use robust_scale unless you know what you are doing. A common mistake is to apply it to the entire data before splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using RobustScaler within a Pipeline in order to prevent most risks of data leaking: pipe = make_pipeline(RobustScaler(), LogisticRegression()).

7.33.26 sklearn.preprocessing.scale

sklearn.preprocessing.scale(X, *, axis=0, with_mean=True, with_std=True, copy=True)

Standardize a dataset along any axis.

Center to the mean and component wise scale to unit variance.

Read more in the User Guide.

Parameters

- X [{array-like, sparse matrix}] of shape (n_samples, n_features)] The data to center and scale.
- axis [int, default=0] axis used to compute the means and standard deviations along. If 0, independently standardize each feature, otherwise (if 1) standardize each sample.
- with_mean [bool, default=True] If True, center the data before scaling.
- with_std [bool, default=True] If True, scale the data to unit variance (or equivalently, unit standard deviation).
- copy [bool, default=True] set to False to perform inplace row normalization and avoid a copy (if the input is already a numpy array or a scipy.sparse CSC matrix and if axis is 1).

Returns

- X_tr [{ndarray, sparse matrix}] of shape (n_samples, n_features)] The transformed data.

See also:

StandardScaler Performs scaling to unit variance using the Transformer API (e.g. as part of a preprocessing Pipeline).
Notes

This implementation will refuse to center scipy.sparse matrices since it would make them non-sparse and would potentially crash the program with memory exhaustion problems.

Instead the caller is expected to either set explicitly with_mean=False (in that case, only variance scaling will be performed on the features of the CSC matrix) or to call X.toarray() if he/she expects the materialized dense array to fit in memory.

To avoid memory copy the caller should pass a CSC matrix.

NaNs are treated as missing values: disregarded to compute the statistics, and maintained during the data transformation.

We use a biased estimator for the standard deviation, equivalent to numpy.std(x, ddof=0). Note that the choice of ddof is unlikely to affect model performance.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

**Warning: Risk of data leak**

Do not use scale unless you know what you are doing. A common mistake is to apply it to the entire data before splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using StandardScaler within a Pipeline in order to prevent most risks of data leaking: pipe = make_pipeline(StandardScaler(), LogisticRegression()).

### 7.33.27 sklearn.preprocessing.power_transform

sklearn.preprocessing.power_transform(X, method='yeo-johnson', *, standardize=True, copy=True)

Power transforms are a family of parametric, monotonic transformations that are applied to make data more Gaussian-like. This is useful for modeling issues related to heteroscedasticity (non-constant variance), or other situations where normality is desired.

Currently, power_transform supports the Box-Cox transform and the Yeo-Johnson transform. The optimal parameter for stabilizing variance and minimizing skewness is estimated through maximum likelihood.

Box-Cox requires input data to be strictly positive, while Yeo-Johnson supports both positive or negative data.

By default, zero-mean, unit-variance normalization is applied to the transformed data.

Read more in the User Guide.

**Parameters**

X [array-like of shape (n_samples, n_features)] The data to be transformed using a power transformation.

method [‘yeo-johnson’, ‘box-cox’], default=‘yeo-johnson’] The power transform method.

Available methods are:

- ‘yeo-johnson’ [1], works with positive and negative values
- ‘box-cox’ [2], only works with strictly positive values

Changed in version 0.23: The default value of the method parameter changed from ‘box-cox’ to ‘yeo-johnson’ in 0.23.
standardize [bool, default=True] Set to True to apply zero-mean, unit-variance normalization to the transformed output.

copy [bool, default=True] Set to False to perform inplace computation during transformation.

Returns

X_trans [ndarray of shape (n_samples, n_features)] The transformed data.

See also:

PowerTransformer Equivalent transformation with the Transformer API (e.g. as part of a preprocessing Pipeline).

quantile_transform Maps data to a standard normal distribution with the parameter

output_distribution='normal'.

Notes

NaNs are treated as missing values: disregarded in fit, and maintained in transform.

For a comparison of the different scalers, transformers, and normalizers, see examples/preprocessing/plot_all_scaling.py.

References

[1], [2]

Examples

```python
>>> import numpy as np
>>> from sklearn.preprocessing import power_transform
>>> data = [[1, 2], [3, 2], [4, 5]]
>>> print(power_transform(data, method='box-cox'))
[[-1.332... -0.707...]
 [ 0.256... -0.707...]
 [ 1.076... 1.414...]]
```

Warning: Risk of data leak. Do not use power_transform unless you know what you are doing. A common mistake is to apply it to the entire data before splitting into training and test sets. This will bias the model evaluation because information would have leaked from the test set to the training set. In general, we recommend using PowerTransformer within a Pipeline in order to prevent most risks of data leaking, e.g.: pipe = make_pipeline(PowerTransformer(), LogisticRegression()).
7.34 sklearn.random_projection: Random projection

Random Projection transformers.

Random Projections are a simple and computationally efficient way to reduce the dimensionality of the data by trading a controlled amount of accuracy (as additional variance) for faster processing times and smaller model sizes.

The dimensions and distribution of Random Projections matrices are controlled so as to preserve the pairwise distances between any two samples of the dataset.

The main theoretical result behind the efficiency of random projection is the Johnson-Lindenstrauss lemma (quoting Wikipedia):

In mathematics, the Johnson-Lindenstrauss lemma is a result concerning low-distortion embeddings of points from high-dimensional into low-dimensional Euclidean space. The lemma states that a small set of points in a high-dimensional space can be embedded into a space of much lower dimension in such a way that distances between the points are nearly preserved. The map used for the embedding is at least Lipschitz, and can even be taken to be an orthogonal projection.

User guide: See the Random Projection section for further details.

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7.34.1 sklearn.random_projection.GaussianRandomProjection

class sklearn.random_projection.GaussianRandomProjection

Reduce dimensionality through Gaussian random projection.

The components of the random matrix are drawn from N(0, 1 / n_components).

Read more in the User Guide.

New in version 0.13.

Parameters

n_components [int or ‘auto’, default=’auto’] Dimensionality of the target projection space.

n_components can be automatically adjusted according to the number of samples in the dataset and the bound given by the Johnson-Lindenstrauss lemma. In that case the quality of the embedding is controlled by the eps parameter.

It should be noted that Johnson-Lindenstrauss lemma can yield very conservative estimated of the required number of components as it makes no assumption on the structure of the dataset.

eps [float, default=0.1] Parameter to control the quality of the embedding according to the Johnson-Lindenstrauss lemma when n_components is set to ‘auto’. The value should be strictly positive.

Smaller values lead to better embedding and higher number of dimensions (n_components) in the target projection space.
random_state [int, RandomState instance or None, default=None] Controls the pseudo random number generator used to generate the projection matrix at fit time. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

n_components_ [int] Concrete number of components computed when n_components="auto".

components_ [ndarray of shape (n_components, n_features)] Random matrix used for the projection.

See also:

SparseRandomProjection

Examples

```python
>>> import numpy as np
>>> from sklearn.random_projection import GaussianRandomProjection
>>> rng = np.random.RandomState(42)
>>> X = rng.rand(100, 10000)
>>> transformer = GaussianRandomProjection(random_state=rng)
>>> X_new = transformer.fit_transform(X)
>>> X_new.shape
(100, 3947)
```

Methods

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**fit (X, y=None)**
Generate a sparse random projection matrix.

**Parameters**

X [[ndarray, sparse matrix] of shape (n_samples, n_features)] Training set: only the shape is used to find optimal random matrix dimensions based on the theory referenced in the afore mentioned papers.

y Ignored

**Returns**

self

**fit_transform (X, y=None, **fit_params)**
Fit to data, then transform it.

Fits transformer to X and y with optional parameters fit_params and returns a transformed version of X.

**Parameters**
X [array-like of shape (n_samples, n_features)] Input samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] Target values
(0 for unsupervised transformations).

**fit_params [dict] Additional fit parameters.

Returns

X_new [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)

Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it's possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

transform (X)

Project the data by using matrix product with the random matrix

Parameters

X [{ndarray, sparse matrix] of shape (n_samples, n_features)] The input data to project into
a smaller dimensional space.

Returns

X_new [{ndarray, sparse matrix] of shape (n_samples, n_components)] Projected array.

7.34.2 sklearn.random_projection.SparseRandomProjection

class sklearn.random_projection.SparseRandomProjection(n_components='auto', *,
density='auto', eps=0.1,
dense_output=False, random_state=None)

Reduce dimensionality through sparse random projection.

Sparse random matrix is an alternative to dense random projection matrix that guarantees similar embedding
quality while being much more memory efficient and allowing faster computation of the projected data.

If we note s = 1 / density the components of the random matrix are drawn from:

- sqrt(s) / sqrt(n_components) with probability 1 / 2s
- 0 with probability 1 - 1 / s
- +sqrt(s) / sqrt(n_components) with probability 1 / 2s

Read more in the *User Guide*.

New in version 0.13.

**Parameters**

- **n_components** [int or ‘auto’, default=’auto’] Dimensionality of the target projection space.
  
  n_components can be automatically adjusted according to the number of samples in the dataset and the bound given by the Johnson-Lindenstrauss lemma. In that case the quality of the embedding is controlled by the **eps** parameter.

  It should be noted that Johnson-Lindenstrauss lemma can yield very conservative estimated of the required number of components as it makes no assumption on the structure of the dataset.

- **density** [float or ‘auto’, default=’auto’] Ratio in the range (0, 1] of non-zero component in the random projection matrix.
  
  If density = ‘auto’, the value is set to the minimum density as recommended by Ping Li et al.: 1 / sqrt(n_features).

  Use density = 1 / 3.0 if you want to reproduce the results from Achlioptas, 2001.

- **eps** [float, default=0.1] Parameter to control the quality of the embedding according to the Johnson-Lindenstrauss lemma when n_components is set to ‘auto’. This value should be strictly positive.

  Smaller values lead to better embedding and higher number of dimensions (n_components) in the target projection space.

- **dense_output** [bool, default=False] If True, ensure that the output of the random projection is a dense numpy array even if the input and random projection matrix are both sparse.

  In practice, if the number of components is small the number of zero components in the projected data will be very small and it will be more CPU and memory efficient to use a dense representation.

  If False, the projected data uses a sparse representation if the input is sparse.

- **random_state** [int, RandomState instance or None, default=None] Controls the pseudo random number generator used to generate the projection matrix at fit time. Pass an int for reproducible output across multiple function calls. See *Glossary*.

**Attributes**

- **n_components_** [int] Concrete number of components computed when n_components=’auto’.

- **components_** [sparse matrix of shape (n_components, n_features)] Random matrix used for the projection. Sparse matrix will be of CSR format.

- **density_** [float in range 0.0 - 1.0] Concrete density computed from when density = “auto”.

**See also:**

*GaussianRandomProjection*
Examples

```python
>>> import numpy as np
>>> from sklearn.random_projection import SparseRandomProjection
>>> rng = np.random.RandomState(42)
>>> X = rng.rand(100, 10000)
>>> transformer = SparseRandomProjection(random_state=rng)
>>> X_new = transformer.fit_transform(X)
>>> X_new.shape
(100, 3947)
>>> # very few components are non-zero
>>> np.mean(transformer.components_ != 0)
0.0100...
```

Methods

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**fit** *(X, y=None)*

Generate a sparse random projection matrix.

Parameters

- **X** *[[ndarray, sparse matrix] of shape (n_samples, n_features)]* Training set: only the shape is used to find optimal random matrix dimensions based on the theory referenced in the above mentioned papers.
- **y** Ignored

Returns

- **self**

**fit_transform** *(X, y=None, **fit_params)*

Fit to data, then transform it.

Fits transformer to X and y with optional parameters *fit_params* and returns a transformed version of X.

Parameters

- **X** *[[array-like of shape (n_samples, n_features)]]* Input samples.
- **y** *[[array-like of shape (n_samples,) or (n_samples, n_outputs), default=None]]* Target values (None for unsupervised transformations).

- ****fit_params* [dict] Additional fit parameters.
Returns

X_new  [ndarray array of shape (n_samples, n_features_new)] Transformed array.

get_params (deep=True)
Get parameters for this estimator.

Parameters

depth  [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params  [dict] Parameter names mapped to their values.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.

transform(X)
Project the data by using matrix product with the random matrix

Parameters

X  [ndarray, sparse matrix] of shape (n_samples, n_features)] The input data to project into a smaller dimensional space.

Returns

X_new  [ndarray, sparse matrix] of shape (n_samples, n_components)] Projected array.

Examples using sklearn.random_projection.SparseRandomProjection

- Manifold learning on handwritten digits: Locally Linear Embedding, Isomap...
- The Johnson-Lindenstrauss bound for embedding with random projections

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7.34.3 sklearn.random_projection.johnson_lindenstrauss_min_dim

`sklearn.random_projection.johnson_lindenstrauss_min_dim(n_samples, *, eps=0.1)`

Find a ‘safe’ number of components to randomly project to.

The distortion introduced by a random projection $\mathbf{p}$ only changes the distance between two points by a factor $(1 + \varepsilon)$ in an euclidean space with good probability. The projection $\mathbf{p}$ is an eps-embedding as defined by:

$$(1 - \varepsilon) \|u - v\|^2 < \|p(u) - p(v)\|^2 < (1 + \varepsilon) \|u - v\|^2$$

Where $u$ and $v$ are any rows taken from a dataset of shape $(n_{\text{samples}}, n_{\text{features}})$, $\varepsilon$ is in $[0, 1]$ and $\mathbf{p}$ is a projection by a random Gaussian $N(0, 1)$ matrix of shape $(n_{\text{components}}, n_{\text{features}})$ (or a sparse Achlioptas matrix).

The minimum number of components to guarantee the eps-embedding is given by:

$$n_{\text{components}} \geq 4 \log(n_{\text{samples}}) / (\varepsilon^2/2 - \varepsilon^3/3)$$

Note that the number of dimensions is independent of the original number of features but instead depends on the size of the dataset: the larger the dataset, the higher is the minimal dimensionality of an eps-embedding. Read more in the User Guide.

**Parameters**

- **n_samples** [int or array-like of int] Number of samples that should be a integer greater than 0. If an array is given, it will compute a safe number of components array-wise.

- **eps** [float or ndarray of shape (n_components,), dtype=float, default=0.1] Maximum distortion rate in the range $(0, 1)$ as defined by the Johnson-Lindenstrauss lemma. If an array is given, it will compute a safe number of components array-wise.

**Returns**

- **n_components** [int or ndarray of int] The minimal number of components to guarantee with good probability an eps-embedding with n_samples.

**References**

[1], [2]

**Examples**

```python
>>> johnson_lindenstrauss_min_dim(1e6, eps=0.5)
663
```

```python
>>> johnson_lindenstrauss_min_dim(1e6, eps=[0.5, 0.1, 0.01])
array([ 663, 11841, 1112658])
```

```python
>>> johnson_lindenstrauss_min_dim([1e4, 1e5, 1e6], eps=0.1)
array([7894, 9868, 11841])
```
Examples using `sklearn.random_projection.johnson_lindenstrauss_min_dim`

- The Johnson-Lindenstrauss bound for embedding with random projections

## 7.35 sklearn.semi_supervised: Semi-Supervised Learning

The `sklearn.semi_supervised` module implements semi-supervised learning algorithms. These algorithms utilize small amounts of labeled data and large amounts of unlabeled data for classification tasks. This module includes Label Propagation.

**User guide:** See the *Semi-supervised learning* section for further details.

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### 7.35.1 sklearn.semi_supervised.LabelPropagation

```python
class sklearn.semi_supervised.LabelPropagation (kernel='rbf', *, gamma=20, n_neighbors=7, max_iter=1000, tol=0.001, n_jobs=None)
```

Label Propagation classifier

Read more in the *User Guide*.

**Parameters**

- `kernel` [[`'knn', 'rbf'`] or callable, default='rbf'] String identifier for kernel function to use or the kernel function itself. Only 'rbf' and 'knn' strings are valid inputs. The function passed should take two inputs, each of shape (n_samples, n_features), and return a (n_samples, n_samples) shaped weight matrix.


- `n_neighbors` [int, default=7] Parameter for knn kernel which need to be strictly positive.

- `max_iter` [int, default=1000] Change maximum number of iterations allowed.

- `tol` [float, 1e-3] Convergence tolerance: threshold to consider the system at steady state.

- `n_jobs` [int, default=None] The number of parallel jobs to run. *None* means 1 unless in a `joblib.parallel_backend` context. `-1` means using all processors. See *Glossary* for more details.

**Attributes**

- `X_` [ndarray of shape (n_samples, n_features)] Input array.

- `classes_` [ndarray of shape (n_classes,)] The distinct labels used in classifying instances.

- `label_distributions_` [ndarray of shape (n_samples, n_classes)] Categorical distribution for each item.

- `transduction_` [ndarray of shape (n_samples)] Label assigned to each item via the transduction.
n_iter_  [int] Number of iterations run.

See also:

LabelSpreading  Alternate label propagation strategy more robust to noise.

References


Examples

```python
>>> import numpy as np
>>> from sklearn import datasets
>>> from sklearn.semi_supervised import LabelPropagation
>>> label_prop_model = LabelPropagation()
>>> iris = datasets.load_iris()
>>> rng = np.random.RandomState(42)
>>> random_unlabeled_points = rng.rand(len(iris.target)) < 0.3
>>> labels = np.copy(iris.target)
>>> labels[random_unlabeled_points] = -1
>>> label_prop_model.fit(iris.data, labels)
LabelPropagation(...)
```

Methods

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<th>Method</th>
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<td><code>fit(X, y)</code></td>
<td>Fit a semi-supervised label propagation model based on the input data.</td>
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<td><code>score(X, y, sample_weight)</code></td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
<tr>
<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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</table>

<table>
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<tr>
<th>Method</th>
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<tbody>
<tr>
<td><code>fit(X, y)</code></td>
<td>Fit a semi-supervised label propagation model based on the input data.</td>
</tr>
</tbody>
</table>

All the input data is provided matrix X (labeled and unlabeled) and corresponding label matrix y with a dedicated marker value for unlabeled samples.

Parameters

- **X**  [array-like of shape (n_samples, n_features)] A matrix of shape (n_samples, n_samples) will be created from this.
- **y**  [array-like of shape (n_samples,)]  n_labeled_samples (unlabeled points are marked as -1) All unlabeled samples will be transductively assigned labels.

Returns

- **self**  [object]
get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Performs inductive inference across the model.

Parameters

X [array-like of shape (n_samples, n_features)] The data matrix.

Returns

y [ndarray of shape (n_samples,)] Predictions for input data.

predict_proba (X)
Predict probability for each possible outcome.
Compute the probability estimates for each single sample in X and each possible outcome seen during
training (categorical distribution).

Parameters

X [array-like of shape (n_samples, n_features)] The data matrix.

Returns

probabilities [ndarray of shape (n_samples, n_classes)] Normalized probability distribu-
tions across class labels.

score (X, y, sample_weight=None)
Return the mean accuracy on the given test data and labels.
In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each
sample that each label set be correctly predicted.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)
Set the parameters of this estimator.
The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have
parameters of the form <component>__<parameter> so that it's possible to update each component
of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns
self [estimator instance] Estimator instance.

7.35.2 sklearn.semi_supervised.LabelSpreading

class sklearn.semi_supervised.LabelSpreading(kernel='rbf', *, gamma=20, n_neighbors=7, alpha=0.2, max_iter=30, tol=0.001, n_jobs=None)

LabelSpreading model for semi-supervised learning

This model is similar to the basic Label Propagation algorithm, but uses affinity matrix based on the normalized graph Laplacian and soft clamping across the labels.

Read more in the User Guide.

Parameters

- kernel [['knn', 'rbf'] or callable, default='rbf'] String identifier for kernel function to use or the kernel function itself. Only ‘rbf’ and ‘knn’ strings are valid inputs. The function passed should take two inputs, each of shape (n_samples, n_features), and return a (n_samples, n_samples) shaped weight matrix.


- n_neighbors [int, default=7] Parameter for knn kernel which is a strictly positive integer.

- alpha [float, default=0.2] Clamping factor. A value in (0, 1) that specifies the relative amount that an instance should adopt the information from its neighbors as opposed to its initial label. alpha=0 means keeping the initial label information; alpha=1 means replacing all initial information.

- max_iter [int, default=30] Maximum number of iterations allowed.

- tol [float, default=1e-3] Convergence tolerance: threshold to consider the system at steady state.

- n_jobs [int, default=None] The number of parallel jobs to run. None means 1 unless in a joblib.parallel_backend context. -1 means using all processors. See Glossary for more details.

Attributes

- X_ [ndarray of shape (n_samples, n_features)] Input array.

- classes_ [ndarray of shape (n_classes,)] The distinct labels used in classifying instances.

- label_distributions_ [ndarray of shape (n_samples, n_classes)] Categorical distribution for each item.

- transduction_ [ndarray of shape (n_samples,)] Label assigned to each item via the transduction.

- n_iter_ [int] Number of iterations run.

See also:

LabelPropagation Unregularized graph based semi-supervised learning.
References


Examples

```python
>>> import numpy as np
>>> from sklearn import datasets
>>> from sklearn.semi_supervised import LabelSpreading

>>> label_prop_model = LabelSpreading()
>>> iris = datasets.load_iris()
>>> rng = np.random.RandomState(42)
>>> random_unlabeled_points = rng.rand(len(iris.target)) < 0.3
>>> labels = np.copy(iris.target)
>>> labels[random_unlabeled_points] = -1
>>> label_prop_model.fit(iris.data, labels)
```

Methods

```python
fit(X, y)
```

Fit a semi-supervised label propagation model based

All the input data is provided matrix \( X \) (labeled and unlabeled) and corresponding label matrix \( y \) with a dedicated marker value for unlabeled samples.

Parameters

\( X \) [array-like of shape \( (n\_samples, n\_features) \)] A matrix of shape \( (n\_samples, n\_samples) \) will be created from this.

\( y \) [array-like of shape \( (n\_samples, ) \)] \( n\_labeled\_samples \) (unlabeled points are marked as -1) All unlabeled samples will be transductively assigned labels.

Returns

\( \text{self} \) [object]

```python
def get_params([deep])
```

Get parameters for this estimator.

Parameters

\( \text{deep} \) [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

\( \text{self} \) [object]
**params** [dict] Parameter names mapped to their values.

**predict** (*X*)
Performs inductive inference across the model.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] The data matrix.

**Returns**

*y* [ndarray of shape (n_samples,)] Predictions for input data.

**predict_proba** (*X*)
Predict probability for each possible outcome.

Compute the probability estimates for each single sample in *X* and each possible outcome seen during training (categorical distribution).

**Parameters**

*X* [array-like of shape (n_samples, n_features)] The data matrix.

**Returns**

*probabilities* [ndarray of shape (n_samples, n_classes)] Normalized probability distributions across class labels.

**score** (*X*, *y*, *sample_weight=None*)
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

*X* [array-like of shape (n_samples, n_features)] Test samples.

*y* [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for *X*.

*sample_weight* [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

*score* [float] Mean accuracy of `self.predict(X)` wrt. *y*.

**set_params** (**params**)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

*self* [estimator instance] Estimator instance.
Examples using `sklearn.semi_supervised.LabelSpreading`

- Label Propagation learning a complex structure
- Label Propagation digits: Demonstrating performance
- Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset
- Semi-supervised Classification on a Text Dataset
- Label Propagation digits active learning

7.35.3 `sklearn.semi_supervised.SelfTrainingClassifier`

```python
class sklearn.semi_supervised.SelfTrainingClassifier(base_estimator,
                                                  threshold=0.75,
                                                  criterion='threshold',
                                                  k_best=10,
                                                  max_iter=10, verbose=False)
```

Self-training classifier.

This class allows a given supervised classifier to function as a semi-supervised classifier, allowing it to learn from unlabeled data. It does this by iteratively predicting pseudo-labels for the unlabeled data and adding them to the training set.

The classifier will continue iterating until either max_iter is reached, or no pseudo-labels were added to the training set in the previous iteration.

Read more in the *User Guide*.

**Parameters**

- `base_estimator` [estimator object] An estimator object implementing `fit` and `predict_proba`. Invoking the `fit` method will fit a clone of the passed estimator, which will be stored in the `base_estimator_` attribute.

- `criterion` [‘threshold’, ‘k_best’], default=’threshold’] The selection criterion used to select which labels to add to the training set. If ‘threshold’, pseudo-labels with prediction probabilities above `threshold` are added to the dataset. If ‘k_best’, the `k_best` pseudo-labels with highest prediction probabilities are added to the dataset. When using the ‘threshold’ criterion, a *well calibrated classifier* should be used.

- `threshold` [float, default=0.75] The decision threshold for use with criterion='threshold'. Should be in [0, 1). When using the ‘threshold’ criterion, a *well calibrated classifier* should be used.

- `k_best` [int, default=10] The amount of samples to add in each iteration. Only used when criterion is ‘k_best’.

- `max_iter` [int or None, default=10] Maximum number of iterations allowed. Should be greater than or equal to 0. If it is None, the classifier will continue to predict labels until no new pseudo-labels are added, or all unlabeled samples have been labeled.

- `verbose`: bool, default=False Enable verbose output.

**Attributes**

- `base_estimator_` [estimator object] The fitted estimator.

- `classes_` [ndarray or list of ndarray of shape (n_classes,)] Class labels for each output. (Taken from the trained `base_estimator_`).
transduction_ [ndarray of shape (n_samples,)] The labels used for the final fit of the classifier, including pseudo-labels added during fit.

labeled_iter_ [ndarray of shape (n_samples,)] The iteration in which each sample was labeled. When a sample has iteration 0, the sample was already labeled in the original dataset. When a sample has iteration -1, the sample was not labeled in any iteration.

n_iter_ [int] The number of rounds of self-training, that is the number of times the base estimator is fitted on relabeled variants of the training set.

termination_condition_ [dict{‘max_iter’, ‘no_change’, ‘all_labeled’}] The reason that fitting was stopped.
  • ‘max_iter’: n_iter_ reached max_iter.
  • ‘no_change’: no new labels were predicted.
  • ‘all_labeled’: all unlabeled samples were labeled before max_iter was reached.

References


Examples

```python
>>> import numpy as np
>>> from sklearn import datasets
>>> from sklearn.semi_supervised import SelfTrainingClassifier
>>> from sklearn.svm import SVC

>>> rng = np.random.RandomState(42)
>>> iris = datasets.load_iris()
>>> random_unlabeled_points = rng.rand(iris.target.shape[0]) < 0.3
>>> iris.target[random_unlabeled_points] = -1
>>> svc = SVC(probability=True, gamma="auto")
>>> self_training_model = SelfTrainingClassifier(svc)
>>> self_training_model.fit(iris.data, iris.target)
```

Methods

decision_function(X) Calls decision function of the base_estimator.

fit(X, y) Fits this SelfTrainingClassifier to a dataset.

get_params([deep]) Get parameters for this estimator.

predict(X) Predict the classes of X.

predict_log_proba(X) Predict log probability for each possible outcome.

predict_proba(X) Predict probability for each possible outcome.

score(X, y) Calls score on the base_estimator.

set_params(**params) Set the parameters of this estimator.

decision_function(X) Calls decision function of the base_estimator.
Parameters

**X**  ([array-like, sparse matrix] of shape (n_samples, n_features)) Array representing the data.

Returns

**y**  ([ndarray of shape (n_samples, n_features)]) Result of the decision function of the

base_estimator.

**fit** (*X, y*)

Fits this SelfTrainingClassifier to a dataset.

Parameters

**X**  ([array-like, sparse matrix] of shape (n_samples, n_features)) Array representing the data.

**y**  ([array-like, sparse matrix] of shape (n_samples,)) Array representing the labels. Unla-

beled samples should have the label -1.

Returns

**self**  [object] Returns an instance of self.

**get_params** (*deep=True*)

Get parameters for this estimator.

Parameters

**deep**  [bool, default=True] If True, will return the parameters for this estimator and contained

subobjects that are estimators.

Returns

**params**  [dict] Parameter names mapped to their values.

**predict** (*X*)

Predict the classes of X.

Parameters

**X**  ([array-like, sparse matrix] of shape (n_samples, n_features)) Array representing the data.

Returns

**y**  ([ndarray of shape (n_samples,))] Array with predicted labels.

**predict_log_proba** (*X*)

Predict log probability for each possible outcome.

Parameters

**X**  ([array-like, sparse matrix] of shape (n_samples, n_features)) Array representing the data.

Returns

**y**  ([ndarray of shape (n_samples, n_features)]) Array with log prediction probabilities.

**predict_proba** (*X*)

Predict probability for each possible outcome.

Parameters

**X**  ([array-like, sparse matrix] of shape (n_samples, n_features)) Array representing the data.

Returns

**y**  ([ndarray of shape (n_samples, n_features)]) Array with prediction probabilities.
**score** *(X, y)*

Calls score on the *base_estimator*.

**Parameters**

- **X** [array-like, sparse matrix] of shape *(n_samples, n_features)* Array representing the data.
- **y** [array-like of shape *(n_samples,)*] Array representing the labels.

**Returns**

- **score** [float] Result of calling score on the *base_estimator*.

**set_params** (**params**)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as *Pipeline*). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.

---

**Examples using sklearn.semi_supervised.SelfTrainingClassifier**

- Release Highlights for scikit-learn 0.24
- Decision boundary of semi-supervised classifiers versus SVM on the Iris dataset
- Effect of varying threshold for self-training
- Semi-supervised Classification on a Text Dataset

---

7.36 `sklearn.svm`: Support Vector Machines

The `sklearn.svm` module includes Support Vector Machine algorithms.

**User guide**: See the Support Vector Machines section for further details.

### 7.36.1 Estimators

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</tr>
<tr>
<td>sklearn.svm.NuSVR( [nu, C, kernel, degree, gamma, ...])</td>
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</tr>
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<tr>
<td>sklearn.svm.SVR( [kernel, degree, gamma, coef0, ...])</td>
<td>Epsilon-Support Vector Regression.</td>
</tr>
</tbody>
</table>
sklearn.svm.LinearSVC

class sklearn.svm.LinearSVC (penalty='l2', loss='squared_hinge', *, dual=True, tol=0.0001, C=1.0, multi_class='ovr', fit_intercept=True, intercept_scaling=1, class_weight=None, verbose=0, random_state=None, max_iter=1000)

Linear Support Vector Classification.

Similar to SVC with parameter kernel='linear', but implemented in terms of liblinear rather than libsvm, so it has more flexibility in the choice of penalties and loss functions and should scale better to large numbers of samples.

This class supports both dense and sparse input and the multiclass support is handled according to a one-vs-the-rest scheme.

Read more in the User Guide.

Parameters

penalty ['l1', 'l2'], default='l2'] Specifies the norm used in the penalization. The ‘l2’ penalty is the standard used in SVC. The ‘l1’ leads to coef_vectors that are sparse.

loss ['hinge', 'squared_hinge'], default='squared_hinge'] Specifies the loss function. ‘hinge’ is the standard SVM loss (used e.g. by the SVC class) while ‘squared_hinge’ is the square of the hinge loss. The combination of penalty='l1' and loss='hinge' is not supported.

dual [bool, default=True] Select the algorithm to either solve the dual or primal optimization problem. Prefer dual=False when n_samples > n_features.

tol [float, default=1e-4] Tolerance for stopping criteria.

C [float, default=1.0] Regularization parameter. The strength of the regularization is inversely proportional to C. Must be strictly positive.

multi_class ['ovr', 'crammer_singer'], default='ovr'] Determines the multi-class strategy if y contains more than two classes. "ovr" trains n_classes one-vs-rest classifiers, while "crammer_singer" optimizes a joint objective over all classes. While crammer_singer is interesting from a theoretical perspective as it is consistent, it is seldom used in practice as it rarely leads to better accuracy and is more expensive to compute. If "crammer_singer" is chosen, the options loss, penalty and dual will be ignored.

fit_intercept [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be already centered).

intercept_scaling [float, default=1] When self.fit_intercept is True, instance vector x becomes [x, self.intercept_scaling], i.e. a “synthetic” feature with constant value equals to intercept_scaling is appended to the instance vector. The intercept becomes intercept_scaling * synthetic feature weight Note! the synthetic feature weight is subject to 11/l2 regularization as all other features. To lessen the effect of regularization on synthetic feature weight (and therefore on the intercept) intercept_scaling has to be increased.

class_weight [dict or ‘balanced’, default=None] Set the parameter C of class i to class_weight[i] * C for SVC. If not given, all classes are supposed to have weight one. The "balanced" mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as n_samples / (n_classes * np.bincount(y)).

verbose [int, default=0] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in liblinear that, if enabled, may not work properly in a multithreaded context.
**random_state** [int, RandomState instance or None, default=None] Controls the pseudo random number generation for shuffling the data for the dual coordinate descent (if dual=True). When dual=False the underlying implementation of LinearSVC is not random and random_state has no effect on the results. Pass an int for reproducible output across multiple function calls. See Glossary.

**max_iter** [int, default=1000] The maximum number of iterations to be run.

**Attributes**

- **coef_** [ndarray of shape (1, n_features) if n_classes == 2 else (n_classes, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

  coef_ is a readonly property derived from raw_coef_ that follows the internal memory layout of liblinear.

- **intercept_** [ndarray of shape (1,) if n_classes == 2 else (n_classes,)] Constants in decision function.

- **classes_** [ndarray of shape (n_classes,)] The unique classes labels.

- **n_iter_** [int] Maximum number of iterations run across all classes.

**See also:**

- **SVC** Implementation of Support Vector Machine classifier using libsvm: the kernel can be non-linear but its SMO algorithm does not scale to large number of samples as LinearSVC does. Furthermore SVC multi-class mode is implemented using one vs one scheme while LinearSVC uses one vs the rest. It is possible to implement one vs the rest with SVC by using the OneVsRestClassifier wrapper. Finally SVC can fit dense data without memory copy if the input is C-contiguous. Sparse data will still incur memory copy though.

- **sklearn.linear_model.SGDClassifier** SGDClassifier can optimize the same cost function as LinearSVC by adjusting the penalty and loss parameters. In addition it requires less memory, allows incremental (online) learning, and implements various loss functions and regularization regimes.

**Notes**

The underlying C implementation uses a random number generator to select features when fitting the model. It is thus not uncommon to have slightly different results for the same input data. If that happens, try with a smaller tol parameter.

The underlying implementation, liblinear, uses a sparse internal representation for the data that will incur a memory copy.

Predict output may not match that of standalone liblinear in certain cases. See differences from liblinear in the narrative documentation.
References

LIBLINEAR: A Library for Large Linear Classification

Examples

```python
>>> from sklearn.svm import LinearSVC
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.datasets import make_classification

>>> X, y = make_classification(n_features=4, random_state=0)

>>> clf = make_pipeline(StandardScaler(),
    LinearSVC(random_state=0, tol=1e-5))

>>> clf.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()),
    ('linearsvc', LinearSVC(random_state=0, tol=1e-05))])

>>> print(clf.named_steps['linearsvc'].coef_.
[[0.141... 0.526... 0.679... 0.493...]])

>>> print(clf.named_steps['linearsvc'].intercept_.
[0.1693...]

>>> print(clf.predict([[0, 0, 0, 0]]))
[1]
```

Methods

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**decision_function(X)**

Predict confidence scores for samples.

The confidence score for a sample is the signed distance of that sample to the hyperplane.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**

- **array**, shape=(n_samples,) if n_classes == 2 else (n_samples, n_classes) Confidence scores per (sample, class) combination. In the binary case, confidence score for self.classes_[1] where >0 means this class would be predicted.

**densify()**

Convert coefficient matrix to dense array format.
Converts the `coef_` member (back) to a numpy.ndarray. This is the default format of `coef_` and is required for fitting, so calling this method is only required on models that have previously been sparsified; otherwise, it is a no-op.

**Returns**

- `self` Fitted estimator.

**fit** *(X, y, sample_weight=None)*

Fit the model according to the given training data.

**Parameters**

- `X` [array-like, sparse matrix] of shape (n_samples, n_features) Training vector, where n_samples is the number of samples and n_features is the number of features.
- `y` array-like of shape (n_samples,) Target vector relative to X.
- `sample_weight` [array-like of shape (n_samples,), default=None] Array of weights that are assigned to individual samples. If not provided, then each sample is given unit weight.

New in version 0.18.

**Returns**

- `self` object An instance of the estimator.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- `deep` bool, default=True If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- `params` dict Parameter names mapped to their values.

**predict** *(X)*

Predict class labels for samples in X.

**Parameters**

- `X` array-like or sparse matrix, shape (n_samples, n_features) Samples.

**Returns**

- `C` array, shape [n_samples] Predicted class label per sample.

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- `X` array-like of shape (n_samples, n_features) Test samples.
- `y` array-like of shape (n_samples,) or (n_samples, n_outputs) True labels for X.
- `sample_weight` array-like of shape (n_samples,), default=None Sample weights.

**Returns**

- `score` float Mean accuracy of `self.predict(X)` wrt. `y`.  

---

7.36. sklearn.svm: Support Vector Machines
**set_params(**\*params\*)**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

**params** [dict] Estimator parameters.

**Returns**

self [estimator instance] Estimator instance.

**sparsify**()

Convert coefficient matrix to sparse format.

Converts the `coef_` member to a scipy.sparse matrix, which for L1-regularized models can be much more memory- and storage-efficient than the usual numpy.ndarray representation.

The `intercept_` member is not converted.

**Returns**

self Fitted estimator.

**Notes**

For non-sparse models, i.e. when there are not many zeros in `coef_`, this may actually increase memory usage, so use this method with care. A rule of thumb is that the number of zero elements, which can be computed with `(coef_ == 0).sum()`, must be more than 50% for this to provide significant benefits.

After calling this method, further fitting with the `partial_fit` method (if any) will not work until you call `densify`.

**Examples using sklearn.svm.LinearSVC**

- Release Highlights for scikit-learn 0.22
- Comparison of Calibration of Classifiers
- Probability Calibration curves
- Pipeline Anova SVM
- Univariate Feature Selection
- Scalable learning with polynomial kernel approximation
- Explicit feature map approximation for RBF kernels
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- Precision-Recall
- Selecting dimensionality reduction with Pipeline and GridSearchCV
- Column Transformer with Heterogeneous Data Sources
- Feature discretization
• Plot the support vectors in LinearSVC
• Plot different SVM classifiers in the iris dataset
• Scaling the regularization parameter for SVCs
• Classification of text documents using sparse features

**sklearn.svm.LinearSVR**

class sklearn.svm.LinearSVR(*, epsilon=0.0, tol=0.0001, C=1.0, loss='epsilon_insensitive', fit_intercept=True, intercept_scaling=1.0, dual=True, verbose=0, random_state=None, max_iter=1000)

Linear Support Vector Regression.

Similar to SVR with parameter kernel='linear', but implemented in terms of liblinear rather than libsvm, so it has more flexibility in the choice of penalties and loss functions and should scale better to large numbers of samples.

This class supports both dense and sparse input.

Read more in the [User Guide](#).

New in version 0.16.

Parameters

- **epsilon** [float, default=0.0] Epsilon parameter in the epsilon-insensitive loss function. Note that the value of this parameter depends on the scale of the target variable y. If unsure, set epsilon=0.

- **tol** [float, default=1e-4] Tolerance for stopping criteria.

- **C** [float, default=1.0] Regularization parameter. The strength of the regularization is inversely proportional to C. Must be strictly positive.

- **loss** [{‘epsilon_insensitive’, ‘squared_epsilon_insensitive’}, default=’epsilon_insensitive’] Specifies the loss function. The epsilon-insensitive loss (standard SVR) is the L1 loss, while the squared epsilon-insensitive loss (‘squared_epsilon_insensitive’) is the L2 loss.

- **fit_intercept** [bool, default=True] Whether to calculate the intercept for this model. If set to false, no intercept will be used in calculations (i.e. data is expected to be already centered).

- **intercept_scaling** [float, default=1.0] When self.fit_intercept is True, instance vector x becomes [x, self.intercept_scaling], i.e. a "synthetic" feature with constant value equals to intercept scaling appended to the instance vector. The intercept becomes intercept_scaling * synthetic feature weight Note! the synthetic feature weight is subject to l1/l2 regularization as all other features. To lessen the effect of regularization on synthetic feature weight (and therefore on the intercept) intercept_scaling has to be increased.

- **dual** [bool, default=True] Select the algorithm to either solve the dual or primal optimization problem. Prefer dual=False when n_samples > n_features.

- **verbose** [int, default=0] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in liblinear that, if enabled, may not work properly in a multithreaded context.

- **random_state** [int, RandomState instance or None, default=None] Controls the pseudo random number generation for shuffling the data. Pass an int for reproducible output across multiple function calls. See [Glossary](#).

- **max_iter** [int, default=1000] The maximum number of iterations to be run.
Attributes

**coef_** [ndarray of shape (n_features) if n_classes == 2 else (n_classes, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

*coef_* is a readonly property derived from *raw_coef_* that follows the internal memory layout of liblinear.

**intercept_** [ndarray of shape (1) if n_classes == 2 else (n_classes)] Constants in decision function.

**n_iter_** [int] Maximum number of iterations run across all classes.

See also:

**LinearSVC** Implementation of Support Vector Machine classifier using the same library as this class (liblinear).

**SVR** Implementation of Support Vector Machine regression using libsvm: the kernel can be non-linear but its SMO algorithm does not scale to large number of samples as LinearSVC does.

**sklearn.linear_model.SGDRegressor** SGDRegressor can optimize the same cost function as LinearSVR by adjusting the penalty and loss parameters. In addition it requires less memory, allows incremental (online) learning, and implements various loss functions and regularization regimes.

Examples

```python
>>> from sklearn.svm import LinearSVR
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.datasets import make_regression

>>> X, y = make_regression(n_features=4, random_state=0)

>>> regr = make_pipeline(StandardScaler(),
...                       LinearSVR(random_state=0, tol=1e-5))

>>> regr.fit(X, y)

Pipeline(steps=[('standardscaler', StandardScaler()),
                ('linearsvr', LinearSVR(random_state=0, tol=1e-05))])

>>> print(regr.named_steps['linearsvr'].coef_)
[18.582... 27.023... 44.357... 64.522...]

>>> print(regr.named_steps['linearsvr'].intercept_)
[-4...]

>>> print(regr.predict([[0, 0, 0, 0]]))
[-2.384...]
```

Methods

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<td><strong>fit(X, y[, sample_weight])</strong></td>
<td>Fit the model according to the given training data.</td>
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<tr>
<td><strong>get_params([deep])</strong></td>
<td>Get parameters for this estimator.</td>
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<td><strong>predict(X)</strong></td>
<td>Predict using the linear model.</td>
</tr>
<tr>
<td><strong>score(X, y[, sample_weight])</strong></td>
<td>Return the coefficient of determination ( R^2 ) of the prediction.</td>
</tr>
<tr>
<td>**set_params(<strong>params)</strong></td>
<td>Set the parameters of this estimator.</td>
</tr>
</tbody>
</table>
**fit** (*X, y, sample_weight=None*)
Fit the model according to the given training data.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features)] Training vector, where n_samples in the number of samples and n_features is the number of features.
- **y** [array-like of shape (n_samples,)] Target vector relative to X
- **sample_weight** [array-like of shape (n_samples,), default=None] Array of weights that are assigned to individual samples. If not provided, then each sample is given unit weight.

**Returns**
- **self** [object] An instance of the estimator.

**get_params** (*deep=True*)
Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**
- **params** [dict] Parameter names mapped to their values.

**predict** (*X*)
Predict using the linear model.

**Parameters**

- **X** [array-like or sparse matrix, shape (n_samples, n_features)] Samples.

**Returns**
- **C** [array, shape (n_samples,)] Returns predicted values.

**score** (*X, y, sample_weight=None*)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $(y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $(y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**
- **score** [float] $R^2$ of `self.predict(X)` wrt. $y$.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params (**params)`
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

`skslearn.svm.NuSVC`

class sklearn.svm.NuSVC (*, nu=0.5, kernel='rbf', degree=3, gamma='scale', coef0=0.0, shrinking=True, probability=False, tol=0.001, cache_size=200, class_weight=None, verbose=False, max_iter=-1, decision_function_shape='ovr', break_ties=False, random_state=None)

Nu-Support Vector Classification.

Similar to SVC but uses a parameter to control the number of support vectors.

The implementation is based on libsvm.

Read more in the User Guide.

Parameters

nu [float, default=0.5] An upper bound on the fraction of margin errors (see User Guide) and a lower bound of the fraction of support vectors. Should be in the interval (0, 1].

kernel [{‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’}, default=’rbf’] Specifies the kernel type to be used in the algorithm. It must be one of ‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’ or a callable. If none is given, ‘rbf’ will be used. If a callable is given it is used to precompute the kernel matrix.

degree [int, default=3] Degree of the polynomial kernel function (‘poly’). Ignored by all other kernels.

gamma [{‘scale’, ‘auto’} or float, default=’scale’] Kernel coefficient for ‘rbf’, ‘poly’ and ‘sigmoid’.

• if gamma=’scale’ (default) is passed then it uses $1 / (n_{features} * X.var())$ as value of gamma,

• if ‘auto’, uses $1 / n_{features}$.

Changed in version 0.22: The default value of gamma changed from ‘auto’ to ‘scale’.

coef0 [float, default=0.0] Independent term in kernel function. It is only significant in ‘poly’ and ‘sigmoid’.

shrinking [bool, default=True] Whether to use the shrinking heuristic. See the User Guide.
**probability** [bool, default=False] Whether to enable probability estimates. This must be enabled prior to calling `fit`, will slow down that method as it internally uses 5-fold cross-validation, and `predict_proba` may be inconsistent with `predict`. Read more in the User Guide.

**tol** [float, default=1e-3] Tolerance for stopping criterion.

**cache_size** [float, default=200] Specify the size of the kernel cache (in MB).

**class_weight** [{dict, ‘balanced’}, default=None] Set the parameter C of class i to class_weight[i]*C for SVC. If not given, all classes are supposed to have weight one. The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies as n_samples / (n_classes * np.bincount(y))

**verbose** [bool, default=False] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in libsvm that, if enabled, may not work properly in a multithreaded context.

**max_iter** [int, default=-1] Hard limit on iterations within solver, or -1 for no limit.

**decision_function_shape** [{‘ovo’, ‘ovr’}, default=’ovr’] Whether to return a one-vs-rest (‘ovr’) decision function of shape (n_samples, n_classes) as all other classifiers, or the original one-vs-one (‘ovo’) decision function of libsvm which has shape (n_samples, n_classes * (n_classes - 1) / 2). However, one-vs-one (‘ovo’) is always used as multi-class strategy. The parameter is ignored for binary classification.

Changed in version 0.19: decision_function_shape is ‘ovr’ by default.

New in version 0.17: `decision_function_shape='ovr'` is recommended.

Changed in version 0.17: Deprecated decision_function_shape=’ovo’ and None.

**break_ties** [bool, default=False] If true, decision_function_shape='ovr', and number of classes > 2, `predict` will break ties according to the confidence values of decision_function; otherwise the first class among the tied classes is returned. Please note that breaking ties comes at a relatively high computational cost compared to a simple predict.

New in version 0.22.

**random_state** [int, RandomState instance or None, default=None] Controls the pseudo random number generation for shuffling the data for probability estimates. Ignored when probability is False. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

**class_weight_** [ndarray of shape (n_classes,)] Multipliers of parameter C of each class. Computed based on the class_weight parameter.

**classes_** [ndarray of shape (n_classes,)] The unique classes labels.

**coef_** [ndarray of shape (n_classes * (n_classes -1) / 2, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

**coef_ is readonly property derived from dual_coef_ and support_vectors_.

**dual_coef_** [ndarray of shape (n_classes - 1, n_SV)] Dual coefficients of the support vector in the decision function (see Mathematical formulation), multiplied by their targets. For multiclass, coefficient for all 1-vs-1 classifiers. The layout of the coefficients in the multiclass case is somewhat non-trivial. See the multi-class section of the User Guide for details.

**fit_status_** [int] 0 if correctly fitted, 1 if the algorithm did not converge.
intercept_ [ndarray of shape (n_classes * (n_classes - 1) / 2,)] Constants in decision function.

support_ [ndarray of shape (n_SV,)] Indices of support vectors.

support_vectors_ [ndarray of shape (n_SV, n_features)] Support vectors.

n_support_ [ndarray of shape (n_classes,), dtype=int32] Number of support vectors for each class.

fit_status_ [int] 0 if correctly fitted, 1 if the algorithm did not converge.

probA_ [ndarray of shape (n_classes * (n_classes - 1) / 2,)]

probB_ [ndarray of shape (n_classes * (n_classes - 1) / 2,)] If probability=True, it corresponds to the parameters learned in Platt scaling to produce probability estimates from decision values. If probability=False, it’s an empty array. Platt scaling uses the logistic function 1 / (1 + exp(decision_value * probA_ + probB_)) where probA_ and probB_ are learned from the dataset [2]. For more information on the multiclass case and training procedure see section 8 of [1].

shape_fit_ [tuple of int of shape (n_dimensions_of_X,)] Array dimensions of training vector X.

See also:

SVC Support Vector Machine for classification using libsvm.

LinearSVC Scalable linear Support Vector Machine for classification using liblinear.

References

[1], [2]

Examples

```python
>>> import numpy as np
>>> X = np.array([[-1, -1], [-2, -1], [1, 1], [2, 1]])
>>> y = np.array([1, 1, 2, 2])
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> from sklearn.svm import NuSVC
>>> clf = make_pipeline(StandardScaler(), NuSVC())
>>> clf.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()), ('nusvc', NuSVC())])
>>> print(clf.predict([[0.8, 1]]))
[1]
```

Methods

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<tr>
<td>decision_function(X)</td>
<td>Evaluates the decision function for the samples in X.</td>
</tr>
<tr>
<td>fit(X, y[, sample_weight])</td>
<td>Fit the SVM model according to the given training data.</td>
</tr>
<tr>
<td>get_params([deep])</td>
<td>Get parameters for this estimator.</td>
</tr>
<tr>
<td>predict(X)</td>
<td>Perform classification on samples in X.</td>
</tr>
<tr>
<td>score(X, y[, sample_weight])</td>
<td>Return the mean accuracy on the given test data and labels.</td>
</tr>
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continues on next page
`set_params(**params)` Set the parameters of this estimator.

**decision_function**(X)
Evaluates the decision function for the samples in X.

**Parameters**

- X [array-like of shape (n_samples, n_features)]

**Returns**

- X [ndarray of shape (n_samples, n_classes * (n_classes-1) / 2)] Returns the decision function of the sample for each class in the model. If decision_function_shape='ovr', the shape is (n_samples, n_classes).

**Notes**

If decision_function_shape='ovo', the function values are proportional to the distance of the samples X to the separating hyperplane. If the exact distances are required, divide the function values by the norm of the weight vector (coef_). See also this question for further details. If decision_function_shape='ovr', the decision function is a monotonic transformation of ovo decision function.

`fit`(X, y, sample_weight=None)
Fit the SVM model according to the given training data.

**Parameters**

- X [array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples)
  Training vectors, where n_samples is the number of samples and n_features is the number of features. For kernel="precomputed", the expected shape of X is (n_samples, n_samples).

- y [array-like of shape (n_samples,)] Target values (class labels in classification, real numbers in regression).

- sample_weight [array-like of shape (n_samples,), default=None] Per-sample weights. Rescale C per sample. Higher weights force the classifier to put more emphasis on these points.

**Returns**

- self [object]

**Notes**

If X and y are not C-ordered and contiguous arrays of np.float64 and X is not a scipy.sparse.csr_matrix, X and/or y may be copied.

If X is a dense array, then the other methods will not support sparse matrices as input.

`get_params`(deep=True)
Get parameters for this estimator.

**Parameters**

- deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

```
**params**  [dict] Parameter names mapped to their values.

**predict** *(X)*

Perform classification on samples in X.

For an one-class model, +1 or -1 is returned.

**Parameters**

X [[array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples_test, n_samples_train)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

y_pred [ndarray of shape (n_samples,)] Class labels for samples in X.

**property predict_log_proba**

Compute log probabilities of possible outcomes for samples in X.

The model need to have probability information computed at training time: fit with attribute probability set to True.

**Parameters**

X [array-like of shape (n_samples, n_features) or (n_samples_test, n_samples_train)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

T [ndarray of shape (n_samples, n_classes)] Returns the log-probabilities of the sample for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

**Notes**

The probability model is created using cross validation, so the results can be slightly different than those obtained by predict. Also, it will produce meaningless results on very small datasets.

**property predict_proba**

Compute probabilities of possible outcomes for samples in X.

The model need to have probability information computed at training time: fit with attribute probability set to True.

**Parameters**

X [array-like of shape (n_samples, n_features)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

T [ndarray of shape (n_samples, n_classes)] Returns the probability of the sample for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute classes_.

Notes

The probability model is created using cross validation, so the results can be slightly different than those obtained by predict. Also, it will produce meaningless results on very small datasets.

score \((X, y, \text{sample_weight=None})\)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

Parameters

\(X\) [array-like of shape (n_samples, n_features)] Test samples.

\(y\) [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for \(X\).

\(\text{sample_weight}\) [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict \((X)\) wrt. \(y\).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form \(<\text{component}>__<\text{parameter}>\) so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.svm.NuSVC

- Non-linear SVM

sklearn.svm.NuSVR

class sklearn.svm.NuSVR (**, nu=0.5, C=1.0, kernel='rbf', degree=3, gamma='scale', coef0=0.0, shrinking=True, tol=0.001, cache_size=200, verbose=False, max_iter=-1)

Nu Support Vector Regression.

Similar to NuSVC, for regression, uses a parameter nu to control the number of support vectors. However, unlike NuSVC, where nu replaces C, here nu replaces the parameter epsilon of epsilon-SVR.

The implementation is based on libsvm.

Read more in the User Guide.

Parameters

\(\text{nu}\) [float, default=0.5] An upper bound on the fraction of training errors and a lower bound of the fraction of support vectors. Should be in the interval (0, 1]. By default 0.5 will be taken.

\(C\) [float, default=1.0] Penalty parameter \(C\) of the error term.
kernel [‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’], default=’rbf’] Specifies the kernel type to be used in the algorithm. It must be one of ‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’ or a callable. If none is given, ‘rbf’ will be used. If a callable is given it is used to precompute the kernel matrix.

degree [int, default=3] Degree of the polynomial kernel function (‘poly’). Ignored by all other kernels.

gamma [‘scale’, ‘auto’] or float, default=’scale’] Kernel coefficient for ‘rbf’, ‘poly’ and ‘sigmoid’.
• if gamma=’scale’ (default) is passed then it uses 1 / (n_features * X.var()) as value of gamma,
• if ‘auto’, uses 1 / n_features.

Changed in version 0.22: The default value of gamma changed from ‘auto’ to ‘scale’.

coeff [float, default=0.0] Independent term in kernel function. It is only significant in ‘poly’ and ‘sigmoid’.

shrinking [bool, default=True] Whether to use the shrinking heuristic. See the User Guide.
tol [float, default=1e-3] Tolerance for stopping criterion.

Attributes

class_weight_ [ndarray of shape (n_classes,)] Multipliers of parameter C for each class. Computed based on the class_weight parameter.

coef_ [ndarray of shape (1, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

coef_ is readonly property derived from dual_coef_ and support_vectors_.

dual_coef_ [ndarray of shape (1, n_SV)] Coefficients of the support vector in the decision function.

fit_status_ [int] 0 if correctly fitted, 1 otherwise (will raise warning)

intercept_ [ndarray of shape (1,)] Constants in decision function.

n_support_ [ndarray of shape (n_classes,), dtype=int32] Number of support vectors for each class.

shape_fit_ [tuple of int of shape (n_dimensions_of_X,)] Array dimensions of training vector X.

support_ [ndarray of shape (n_SV,)] Indices of support vectors.

support_vectors_ [ndarray of shape (n_SV, n_features)] Support vectors.

See also:

NuSVC Support Vector Machine for classification implemented with libsvm with a parameter to control the number of support vectors.

SVR Epsilon Support Vector Machine for regression implemented with libsvm.
References

[1], [2]

Examples

```python
>>> from sklearn.svm import NuSVR
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> import numpy as np

>>> n_samples, n_features = 10, 5
>>> np.random.seed(0)

>>> y = np.random.randn(n_samples)

>>> X = np.random.randn(n_samples, n_features)

>>> regr = make_pipeline(StandardScaler(), NuSVR(C=1.0, nu=0.1))

>>> regr.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()), ('nusvr', NuSVR(nu=0.1))])
```

Methods

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**fit (X, y, sample_weight=None)**

Fit the SVM model according to the given training data.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features) or (n_samples, n_samples)]
  
  Training vectors, where n_samples is the number of samples and n_features is the number of features. For kernel="precomputed", the expected shape of X is (n_samples, n_samples).

- **y** [array-like of shape (n_samples,)]
  
  Target values (class labels in classification, real numbers in regression).

- **sample_weight** [array-like of shape (n_samples,), default=None]
  Per-sample weights. Rescale C per sample. Higher weights force the classifier to put more emphasis on these points.

**Returns**

- **self** [object]
Notes

If X and y are not C-ordered and contiguous arrays of np.float64 and X is not a scipy.sparse.csr_matrix, X
and/or y may be copied.

If X is a dense array, then the other methods will not support sparse matrices as input.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained
subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X)
Perform regression on samples in X.
For an one-class model, +1 (inlier) or -1 (outlier) is returned.

Parameters

X [array-like, sparse matrix] of shape (n_samples, n_features) For kernel="precomputed",
the expected shape of X is (n_samples_test, n_samples_train).

Returns

y_pred [ndarray of shape (n_samples,)]

score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.
The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares
$((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0
and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value
of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel
matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number
of samples used in the fitting for the estimator.
y [array-like of shape (n_samples,), or (n_samples, n_outputs)] True values for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] $R^2$ of self.predict (X) wrt. y.
Notes

The $R^2$ score used when calling `score` on a regressor uses `multioutput='uniform_average'` from version 0.23 to keep consistent with default value of `r2_score`. This influences the `score` method of all the multioutput regressors (except for `MultiOutputRegressor`).

`set_params(**params)`
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as `Pipeline`). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params** [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using `sklearn.svm.NuSVR`

- Model Complexity Influence

`sklearn.svm.OneClassSVM`

```python
class sklearn.svm.OneClassSVM(*, kernel='rbf', degree=3, gamma='scale', coef0=0.0, tol=0.001, nu=0.5, shrinking=True, cache_size=200, verbose=False, max_iter=-1)
```

Unsupervised Outlier Detection.
Estimate the support of a high-dimensional distribution.

The implementation is based on libsvm.

Read more in the `User Guide`.

Parameters

kernel [[`linear`, `poly`, `rbf`, `sigmoid`, `precomputed`], default=`rbf`] Specifies the kernel type to be used in the algorithm. It must be one of `linear`, `poly`, `rbf`, `sigmoid`, `precomputed` or a callable. If none is given, `rbf` will be used. If a callable is given it is used to precompute the kernel matrix.

degree [int, default=3] Degree of the polynomial kernel function (‘poly’). Ignored by all other kernels.

gamma [[‘scale’, ‘auto’) or float, default=’scale’] Kernel coefficient for ‘rbf’, ‘poly’ and ‘sigmoid’.
  • if `gamma='scale'` (default) is passed then it uses $1 / (n_features * X.var())$ as value of `gamma`,
  • if ‘auto’, uses $1 / n_features$.
  Changed in version 0.22: The default value of `gamma` changed from `auto` to `scale`.

coeff0 [float, default=0.0] Independent term in kernel function. It is only significant in ‘poly’ and ‘sigmoid’.

7.36. `sklearn.svm`: Support Vector Machines
tol [float, default=1e-3] Tolerance for stopping criterion.

nu [float, default=0.5] An upper bound on the fraction of training errors and a lower bound of the fraction of support vectors. Should be in the interval (0, 1]. By default 0.5 will be taken.

shrinking [bool, default=True] Whether to use the shrinking heuristic. See the User Guide.

cache_size [float, default=200] Specify the size of the kernel cache (in MB).

verbose [bool, default=False] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in libsvm that, if enabled, may not work properly in a multithreaded context.

max_iter [int, default=-1] Hard limit on iterations within solver, or -1 for no limit.

Attributes

class_weight_ [ndarray of shape (n_classes,)] Multipliers of parameter C for each class. Computed based on the class_weight parameter.

coeff_ [ndarray of shape (1, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

coeff_ is readonly property derived from dual_coeff_ and support_vectors_.

dual_coeff_ [ndarray of shape (1, n_SV)] Coefficients of the support vectors in the decision function.

fit_status_ [int] 0 if correctly fitted, 1 otherwise (will raise warning)

intercept_ [ndarray of shape (1,)] Constant in the decision function.

n_support_ [ndarray of shape (n_classes,), dtype=int32] Number of support vectors for each class.

offset_ [float] Offset used to define the decision function from the raw scores. We have the relation: decision_function = score_samples - offset_. The offset is the opposite of intercept_ and is provided for consistency with other outlier detection algorithms. New in version 0.20.

shape_fit_ [tuple of int of shape (n_dimensions_of_X,)] Array dimensions of training vector X.

support_ [ndarray of shape (n_SV,)] Indices of support vectors.

support_vectors_ [ndarray of shape (n_SV, n_features)] Support vectors.

Examples

```python
>>> from sklearn.svm import OneClassSVM
>>> X = [[0], [0.44], [0.45], [0.46], [1]]
>>> clf = OneClassSVM(gamma='auto').fit(X)
>>> clf.predict(X)
array([-1, 1, 1, 1, -1])
>>> clf.score_samples(X)
array([1.7798..., 2.0547..., 2.0556..., 2.0561..., 1.7332...])
```
Methods

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**decision_function** (X)

Signed distance to the separating hyperplane.

Signed distance is positive for an inlier and negative for an outlier.

**Parameters**

- X [array-like of shape (n_samples, n_features)] The data matrix.

**Returns**

- dec [ndarray of shape (n_samples,)] Returns the decision function of the samples.

**fit** (X, y=None, sample_weight=None, **params)

Detects the soft boundary of the set of samples X.

**Parameters**

- X [{array-like, sparse matrix} of shape (n_samples, n_features)] Set of samples, where n_samples is the number of samples and n_features is the number of features.
- sample_weight [array-like of shape (n_samples,), default=None] Per-sample weights. Rescale C per sample. Higher weights force the classifier to put more emphasis on these points.
- y [Ignored] not used, present for API consistency by convention.

**Returns**

- self [object]

**Notes**

If X is not a C-ordered contiguous array it is copied.

**fit_predict** (X, y=None)

Perform fit on X and returns labels for X.

Returns -1 for outliers and 1 for inliers.

**Parameters**

- X [{array-like, sparse matrix, dataframe} of shape (n_samples, n_features)]
- y [Ignored] Not used, present for API consistency by convention.

**Returns**

- y [ndarray of shape (n_samples,)] 1 for inliers, -1 for outliers.

**get_params**(deep=True)

Get parameters for this estimator.
Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

**predict (X)**

Perform classification on samples in X.

For a one-class model, +1 or -1 is returned.

Parameters

X [(array-like, sparse matrix) of shape (n_samples, n_features) or (n_samples_test, n_samples_train)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

Returns

y_pred [ndarray of shape (n_samples,)] Class labels for samples in X.

**score_samples (X)**

Raw scoring function of the samples.

Parameters

X [array-like of shape (n_samples, n_features)] The data matrix.

Returns

score_samples [ndarray of shape (n_samples,)] Returns the (unshifted) scoring function of the samples.

**set_params (**)params**

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.svm.OneClassSVM

- Libsvm GUI
C-Support Vector Classification.

The implementation is based on libsvm. The fit time scales at least quadratically with the number of samples and may be impractical beyond tens of thousands of samples. For large datasets consider using LinearSVC or SGDClassifier instead, possibly after a Nystroem transformer.

The multiclass support is handled according to a one-vs-one scheme.

For details on the precise mathematical formulation of the provided kernel functions and how gamma, coef0 and degree affect each other, see the corresponding section in the narrative documentation: Kernel functions.

Read more in the User Guide.

Parameters

- **C** [float, default=1.0] Regularization parameter. The strength of the regularization is inversely proportional to C. Must be strictly positive. The penalty is a squared l2 penalty.

- **kernel** [{'linear', 'poly', 'rbf', 'sigmoid', 'precomputed'}, default='rbf'] Specifies the kernel type to be used in the algorithm. It must be one of 'linear', 'poly', 'rbf', 'sigmoid', 'precomputed' or a callable. If none is given, 'rbf' will be used. If a callable is given it is used to pre-compute the kernel matrix from data matrices; that matrix should be an array of shape (n_samples, n_samples).

- **degree** [int, default=3] Degree of the polynomial kernel function ('poly'). Ignored by all other kernels.

- **gamma** [{'scale', 'auto'} or float, default='scale'] Kernel coefficient for 'rbf', 'poly' and 'sigmoid'.
  - if gamma='scale' (default) is passed then it uses 1 / (n_features * X.var()) as value of gamma,
  - if 'auto', uses 1 / n_features.
  
  Changed in version 0.22: The default value of gamma changed from 'auto' to 'scale'.

- **coef0** [float, default=0.0] Independent term in kernel function. It is only significant in 'poly' and 'sigmoid'.

- **shrinking** [bool, default=True] Whether to use the shrinking heuristic. See the User Guide.

- **probability** [bool, default=False] Whether to enable probability estimates. This must be enabled prior to calling fit, will slow down that method as it internally uses 5-fold cross-validation, and predict_proba may be inconsistent with predict. Read more in the User Guide.

- **tol** [float, default=1e-3] Tolerance for stopping criterion.

- **cache_size** [float, default=200] Specify the size of the kernel cache (in MB).

- **class_weight** [dict or ‘balanced’, default=None] Set the parameter C of class i to class_weight[i]*C for SVC. If not given, all classes are supposed to have weight one. The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as n_samples / (n_classes * np.bincount(y))
verbose [bool, default=False] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in libsvm that, if enabled, may not work properly in a multithreaded context.

max_iter [int, default=-1] Hard limit on iterations within solver, or -1 for no limit.

decision_function_shape [\{'ovo', 'ovr',\} default='ovr'] Whether to return a one-vs-rest ('ovr') decision function of shape (n_samples, n_classes) as all other classifiers, or the original one-vs-one ('ovo') decision function of libsvm which has shape (n_samples, n_classes * (n_classes - 1) / 2). However, one-vs-one ('ovo') is always used as multi-class strategy. The parameter is ignored for binary classification.

Changed in version 0.19: decision_function_shape is 'ovr' by default.

New in version 0.17: decision_function_shape='ovr' is recommended.

Changed in version 0.17: Deprecated decision_function_shape='ovo' and None.

break_ties [bool, default=False] If true, decision_function_shape='ovr', and number of classes > 2, predict will break ties according to the confidence values of decision_function; otherwise the first class among the tied classes is returned. Please note that breaking ties comes at a relatively high computational cost compared to a simple predict.

New in version 0.22.

random_state [int, RandomState instance or None, default=None] Controls the pseudo random number generation for shuffling the data for probability estimates. Ignored when probability is False. Pass an int for reproducible output across multiple function calls. See Glossary.

Attributes

class_weight_ [ndarray of shape (n_classes,)] Multipliers of parameter C for each class. Computed based on the class_weight parameter.

classes_ [ndarray of shape (n_classes,)] The classes labels.

coef_ [ndarray of shape (n_classes * (n_classes - 1) / 2, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

    coef_ is a readonly property derived from dual_coef_ and support_vectors_.

dual_coef_ [ndarray of shape (n_classes -1, n_SV)] Dual coefficients of the support vector in the decision function (see Mathematical formulation), multiplied by their targets. For multiclass, coefficient for all 1-vs-1 classifiers. The layout of the coefficients in the multiclass case is somewhat non-trivial. See the multi-class section of the User Guide for details.

fit_status_ [int] 0 if correctly fitted, 1 otherwise (will raise warning)

intercept_ [ndarray of shape (n_classes * (n_classes - 1) / 2,)] Constants in decision function.

support_ [ndarray of shape (n_SV)] Indices of support vectors.

support_vectors_ [ndarray of shape (n_SV, n_features)] Support vectors.

n_support_ [ndarray of shape (n_classes,), dtype=int32] Number of support vectors for each class.

probA_ [ndarray of shape (n_classes * (n_classes - 1) / 2)]

probB_ [ndarray of shape (n_classes * (n_classes - 1) / 2)] If probability=True, it corresponds to the parameters learned in Platt scaling to produce probability estimates from decision values. If probability=False, it’s an empty array. Platt scaling uses
the logistic function $\frac{1}{1 + \exp(\text{decision_value} \times \text{probA}_\text{ } + \text{probB}_\text{ })}$

where probA_ and probB_ are learned from the dataset [2]. For more information on the multiclass case and training procedure see section 8 of [1].

shape_fit_ [tuple of int of shape (n_dimensions_of_X,)] Array dimensions of training vector X.

See also:

SVR Support Vector Machine for Regression implemented using libsvm.

LinearSVC Scalable Linear Support Vector Machine for classification implemented using liblinear. Check the See Also section of LinearSVC for more comparison element.

References

[1], [2]

Examples

```python
>>> import numpy as np
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler

>>> X = np.array([[-1, -1], [-2, -1], [1, 1], [2, 1]])
>>> y = np.array([1, 1, 2, 2])

>>> from sklearn.svm import SVC

>>> clf = make_pipeline(StandardScaler(), SVC(gamma='auto'))
>>>clf.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()),
('svc', SVC(gamma='auto'))])

>>> print(clf.predict([[-0.8, -1]]))
[1]
```

Methods

decision_function(X) Evaluates the decision function for the samples in X.

fit(X, y[, sample_weight]) Fit the SVM model according to the given training data.

get_params([deep]) Get parameters for this estimator.

predict(X) Perform classification on samples in X.

score(X, y[, sample_weight]) Return the mean accuracy on the given test data and labels.

set_params(**params) Set the parameters of this estimator.

decision_function(X)

Evaluates the decision function for the samples in X.

Parameters

X [array-like of shape (n_samples, n_features)]

Returns

X [ndarray of shape (n_samples, n_classes * (n_classes-1) / 2)] Returns the decision function
of the sample for each class in the model. If decision_function_shape='ovr', the shape is (n_samples, n_classes).

Notes

If decision_function_shape='ovo', the function values are proportional to the distance of the samples X to the separating hyperplane. If the exact distances are required, divide the function values by the norm of the weight vector (coef_). See also this question for further details. If decision_function_shape='ovr', the decision function is a monotonic transformation of ovo decision function.

**fit** *(X, y, sample_weight=None)*

Fit the SVM model according to the given training data.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features) or (n_samples, n_samples)]
  Training vectors, where n_samples is the number of samples and n_features is the number of features. For kernel="precomputed", the expected shape of X is (n_samples, n_samples).

- **y** [array-like of shape (n_samples,)]
  Target values (class labels in classification, real numbers in regression).

- **sample_weight** [array-like of shape (n_samples,), default=None]
  Per-sample weights. Rescale C per sample. Higher weights force the classifier to put more emphasis on these points.

**Returns**

- **self** [object]

Notes

If X and y are not C-ordered and contiguous arrays of np.float64 and X is not a scipy.sparse.csr_matrix, X and/or y may be copied.

If X is a dense array, then the other methods will not support sparse matrices as input.

**get_params** *(deep=True)*

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True]
  If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict]
  Parameter names mapped to their values.

**predict** *(X)*

Perform classification on samples in X.

For an one-class model, +1 or -1 is returned.

**Parameters**

- **X** [(array-like, sparse matrix) of shape (n_samples, n_features) or (n_samples_test, n_samples_train)]
  For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**
**y_pred** [ndarray of shape (n_samples,)] Class labels for samples in X.

**property predict_log_proba**
Compute log probabilities of possible outcomes for samples in X.

The model need to have probability information computed at training time: fit with attribute probability set to True.

**Parameters**

**X** [array-like of shape (n_samples, n_features) or (n_samples_test, n_samples_train)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

**T** [ndarray of shape (n_samples, n_classes)] Returns the log-probabilities of the sample for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`.

**Notes**

The probability model is created using cross validation, so the results can be slightly different than those obtained by predict. Also, it will produce meaningless results on very small datasets.

**property predict_proba**
Compute probabilities of possible outcomes for samples in X.

The model need to have probability information computed at training time: fit with attribute probability set to True.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

**T** [ndarray of shape (n_samples, n_classes)] Returns the probability of the sample for each class in the model. The columns correspond to the classes in sorted order, as they appear in the attribute `classes_`.

**Notes**

The probability model is created using cross validation, so the results can be slightly different than those obtained by predict. Also, it will produce meaningless results on very small datasets.

**score** *(X, y, sample_weight=None)*
Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

**X** [array-like of shape (n_samples, n_features)] Test samples.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

**score** [float] Mean accuracy of `self.predict(X)` wrt. y.
set_params(**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.svm.SVC

- Libsvm GUI

sklearn.svm.SVR

class sklearn.svm.SVR(*, kernel='rbf', degree=3, gamma='scale', coef0=0.0, tol=0.001, C=1.0, epsilon=0.1, shrinking=True, cache_size=200, verbose=False, max_iter=-1)

Epsilon-Support Vector Regression.

The free parameters in the model are C and epsilon.

The implementation is based on libsvm. The fit time complexity is more than quadratic with the number of samples which makes it hard to scale to datasets with more than a couple of 10000 samples. For large datasets consider using LinearSVR or SGDRegressor instead, possibly after a Nystroem transformer.

Read more in the User Guide.

Parameters

- kernel [‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’] Specifies the kernel type to be used in the algorithm. It must be one of ‘linear’, ‘poly’, ‘rbf’, ‘sigmoid’, ‘precomputed’ or a callable. If none is given, ‘rbf’ will be used. If a callable is given it is used to precompute the kernel matrix.

- degree [int, default=3] Degree of the polynomial kernel function (‘poly’). Ignored by all other kernels.

- gamma [‘scale’, ‘auto’) or float, default=’scale’] Kernel coefficient for ‘rbf’, ‘poly’ and ‘sigmoid’.

  - if gamma=’scale’ (default) is passed then it uses 1 / (n_features * X.var()) as value of gamma,

  - if ‘auto’, uses 1 / n_features.

  Changed in version 0.22: The default value of gamma changed from ‘auto’ to ‘scale’.

- coef0 [float, default=0.0] Independent term in kernel function. It is only significant in ‘poly’ and ‘sigmoid’.


- C [float, default=1.0] Regularization parameter. The strength of the regularization is inversely proportional to C. Must be strictly positive. The penalty is a squared l2 penalty.
epsilon [float, default=0.1] Epsilon in the epsilon-SVR model. It specifies the epsilon-tube within which no penalty is associated in the training loss function with points predicted within a distance epsilon from the actual value.

shrinkage [bool, default=True] Whether to use the shrinking heuristic. See the User Guide.

cache_size [float, default=200] Specify the size of the kernel cache (in MB).

verbose [bool, default=False] Enable verbose output. Note that this setting takes advantage of a per-process runtime setting in libsvm that, if enabled, may not work properly in a multithreaded context.

max_iter [int, default=-1] Hard limit on iterations within solver, or -1 for no limit.

Attributes

class_weight_ [ndarray of shape (n_classes,)] Multipliers of parameter C for each class. Computed based on the class_weight parameter.

coeff_ [ndarray of shape (1, n_features)] Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

coef_ is readonly property derived from dual_coef_ and support_vectors_

dual_coef_ [ndarray of shape (1, n_SV)] Coefficients of the support vector in the decision function.

fit_status_ [int] 0 if correctly fitted, 1 otherwise (will raise warning)

intercept_ [ndarray of shape (1,)] Constants in decision function.

n_support_ [ndarray of shape (n_classes,), dtype=int32] Number of support vectors for each class.

shape_fit_ [tuple of int of shape (n_dimensions_of_X,)] Array dimensions of training vector X.

support_ [ndarray of shape (n_SV,)] Indices of support vectors.

support_vectors_ [ndarray of shape (n_SV, n_features)] Support vectors.

See also:

NuSVR Support Vector Machine for regression implemented using libsvm using a parameter to control the number of support vectors.

LinearSVR Scalable Linear Support Vector Machine for regression implemented using liblinear.

References

[1], [2]

Examples

```python
>>> from sklearn.svm import SVR
>>> from sklearn.pipeline import make_pipeline
>>> from sklearn.preprocessing import StandardScaler
>>> import numpy as np

>>> n_samples, n_features = 10, 5
>>> rng = np.random.RandomState(0)
>>> y = rng.randn(n_samples)
>>> X = rng.randn(n_samples, n_features)
```
>>> regr = make_pipeline(StandardScaler(), SVR(C=1.0, epsilon=0.2))
>>> regr.fit(X, y)
Pipeline(steps=[('standardscaler', StandardScaler()), ('svr', SVR(epsilon=0.2))])

Methods

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**fit** (X, y, sample_weight=None)

Fit the SVM model according to the given training data.

**Parameters**

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features) or (n_samples, n_samples]) Training vectors, where n_samples is the number of samples and n_features is the number of features. For kernel="precomputed", the expected shape of X is (n_samples, n_samples).
- **y** [array-like of shape (n_samples,)] Target values (class labels in classification, real numbers in regression).
- **sample_weight** [array-like of shape (n_samples,), default=None] Per-sample weights. Rescale C per sample. Higher weights force the classifier to put more emphasis on these points.

**Returns**

- **self** [object]

**Notes**

If X and y are not C-ordered and contiguous arrays of np.float64 and X is not a scipy.sparse.csr_matrix, X and/or y may be copied.

If X is a dense array, then the other methods will not support sparse matrices as input.

**get_params** (deep=True)

Get parameters for this estimator.

**Parameters**

- **deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

- **params** [dict] Parameter names mapped to their values.
**predict**(X)
Perform regression on samples in X.

For an one-class model, +1 (inlier) or -1 (outlier) is returned.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] For kernel="precomputed", the expected shape of X is (n_samples_test, n_samples_train).

**Returns**

- **y_pred** [ndarray of shape (n_samples,)]

**score**(X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred})^2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean())^2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
- **sample_weight** [array-like of shape (n_samples,), default=None] Sample weights.

**Returns**

- **score** [float] $R^2$ of self.predict(X) wrt. y.

**Notes**

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

**set_params**(**params)**
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form `<component>__<parameter>` so that it’s possible to update each component of a nested object.

**Parameters**

- **params** [dict] Estimator parameters.

**Returns**

- **self** [estimator instance] Estimator instance.
Examples using `sklearn.svm.SVR`

- Prediction Latency
- Comparison of kernel ridge regression and SVR
- Support Vector Regression (SVR) using linear and non-linear kernels

```python
svm.l1_min_c(X, y, *, loss='squared_hinge', fit_intercept=True, intercept_scaling=1.0)
```

Return the lowest bound for C such that for C in \((l1\_min\_C, \infty)\) the model is guaranteed not to be empty. This applies to l1 penalized classifiers, such as LinearSVC with penalty='l1' and linear_model.LogisticRegression with penalty='l1'.

This value is valid if class_weight parameter in fit() is not set.

**Parameters**

- `X` ([array-like, sparse matrix] of shape (n_samples, n_features)) Training vector, where n_samples is the number of samples and n_features is the number of features.
- `y` [array-like of shape (n_samples,)] Target vector relative to X.
- `loss` [{'squared_hinge', 'log'}, default='squared_hinge'] Specifies the loss function. With ‘squared_hinge’ it is the squared hinge loss (a.k.a. L2 loss). With ‘log’ it is the loss of logistic regression models.
- `fit_intercept` [bool, default=True] Specifies if the intercept should be fitted by the model. It must match the fit() method parameter.
- `intercept_scaling` [float, default=1.0] when fit_intercept is True, instance vector x becomes [x, intercept_scaling], i.e. a “synthetic” feature with constant value equals to intercept_scaling is appended to the instance vector. It must match the fit() method parameter.

**Returns**

- `l1_min_c` [float] minimum value for C

Examples using `sklearn.svm.l1_min_c`

- Regularization path of L1- Logistic Regression
7.37 sklearn.tree: Decision Trees

The sklearn.tree module includes decision tree-based models for classification and regression.

User guide: See the Decision Trees section for further details.

```python
tree.DecisionTreeClassifier(*[, criterion, ...])
tree.DecisionTreeRegressor(*[, criterion, ...])
tree.ExtraTreeClassifier(*[, criterion, ...])
tree.ExtraTreeRegressor(*[, criterion, ...])
```

A decision tree classifier.

A decision tree regressor.

An extremely randomized tree classifier.

An extremely randomized tree regressor.

7.37.1 sklearn.tree.DecisionTreeClassifier

class sklearn.tree.DecisionTreeClassifier(*, criterion='gini', splitter='best', max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_features=None, random_state=None, max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, class_weight=None, ccp_alpha=0.0)

A decision tree classifier.

Read more in the User Guide.

Parameters

criterion [“gini”, “entropy”), default=”gini”) The function to measure the quality of a split. Supported criteria are “gini” for the Gini impurity and “entropy” for the information gain.

splitter [“best”, “random”), default=”best”) The strategy used to choose the split at each node. Supported strategies are “best” to choose the best split and “random” to choose the best random split.

max_depth [int, default=None) The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min_samples_split samples.

min_samples_split [int or float, default=2] The minimum number of samples required to split an internal node:

- If int, then consider min_samples_split as the minimum number.
- If float, then min_samples_split is a fraction and ceil(min_samples_split * n_samples) are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

min_samples_leaf [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least min_samples_leaf training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

- If int, then consider min_samples_leaf as the minimum number.
• If float, then \( \text{min\_samples\_leaf} \) is a fraction and \( \text{ceil}(\text{min\_samples\_leaf} \times \text{n\_samples}) \) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

\textbf{min\_weight\_fraction\_leaf} [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

\textbf{max\_features} [int, float or \{“auto”, “sqrt”, “log2”\}, default=None] The number of features to consider when looking for the best split:

• If int, then consider \( \text{max\_features} \) features at each split.
• If float, then \( \text{max\_features} \) is a fraction and \( \text{int}(\text{max\_features} \times \text{n\_features}) \) features are considered at each split.
• If “auto”, then \( \text{max\_features} = \sqrt{\text{n\_features}} \).
• If “sqrt”, then \( \text{max\_features} = \sqrt{\text{n\_features}} \).
• If “log2”, then \( \text{max\_features} = \log_2(\text{n\_features}) \).
• If None, then \( \text{max\_features} = \text{n\_features} \).

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than \( \text{max\_features} \) features.

\textbf{random\_state} [int, RandomState instance or None, default=None] Controls the randomness of the estimator. The features are always randomly permuted at each split, even if \text{splitter} is set to "best". When \( \text{max\_features} < \text{n\_features} \), the algorithm will select \( \text{max\_features} \) at random at each split before finding the best split among them. But the best found split may vary across different runs, even if \( \text{max\_features} = \text{n\_features} \). That is the case, if the improvement of the criterion is identical for several splits and one split has to be selected at random. To obtain a deterministic behaviour during fitting, \text{random\_state} has to be fixed to an integer. See \textit{Glossary} for details.

\textbf{max\_leaf\_nodes} [int, default=None] Grow a tree with \( \text{max\_leaf\_nodes} \) in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

\textbf{min\_impurity\_decrease} [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} (\text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right\_impurity} - \frac{N_{t,L}}{N_t} \times \text{left\_impurity})
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t,L} \) is the number of samples in the left child, and \( N_{t,R} \) is the number of samples in the right child.

\( N, N_t, N_{t,R} \) and \( N_{t,L} \) all refer to the weighted sum, if sample_weight is passed.

New in version 0.19.

\textbf{min\_impurity\_split} [float, default=0] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: \text{min\_impurity\_split} has been deprecated in favor of \text{min\_impurity\_decrease} in 0.19. The default value of \text{min\_impurity\_split}
has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

**class_weight** [dict, list of dict or “balanced”, default=None] Weights associated with classes in the form `{class_label: weight}`. If None, all classes are supposed to have weight one. For multi-output problems, a list of dicts can be provided in the same order as the columns of y.

Note that for multiclass (including multilabel) weights should be defined for each class of every column in its own dict. For example, for four-class multilabel classification weights should be [{0: 1, 1: 1}, {0: 1, 1: 5}, {0: 1, 1: 1}, {0: 1, 1: 1}] instead of [{1:1}, {2:5}, {3:1}, {4:1}].

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as `n_samples / (n_classes * np.bincount(y))`

For multi-output, the weights of each column of y will be multiplied.

Note that these weights will be multiplied with sample_weight (passed through the fit method) if sample_weight is specified.

**cpen** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than `cpen` will be chosen. By default, no pruning is performed. See *Minimal Cost-Complexity Pruning* for details.

New in version 0.22.

Attributes

**classes_** [ndarray of shape (n_classes,) or list of ndarray] The classes labels (single output problem), or a list of arrays of class labels (multi-output problem).

**feature_importances_** [ndarray of shape (n_features,)] Return the feature importances.

**max_features_** [int] The inferred value of max_features.

**n_classes_** [int or list of int] The number of classes (for single output problems), or a list containing the number of classes for each output (for multi-output problems).

**n_features_** [int] The number of features when `fit` is performed.

**n_outputs_** [int] The number of outputs when `fit` is performed.

**tree_** [Tree instance] The underlying Tree object. Please refer to `help(sklearn.tree._tree.Tree)` for attributes of Tree object and *Understanding the decision tree structure* for basic usage of these attributes.

See also:

*DecisionTreeRegressor* A decision tree regressor.
Notes

The default values for the parameters controlling the size of the trees (e.g. `max_depth`, `min_samples_leaf`, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

The `predict` method operates using the `numpy.argmax` function on the outputs of `predict_proba`. This means that in case the highest predicted probabilities are tied, the classifier will predict the tied class with the lowest index in `classes_`.

References

[1], [2], [3], [4]

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import cross_val_score
>>> from sklearn.tree import DecisionTreeClassifier

>>> clf = DecisionTreeClassifier(random_state=0)
>>> iris = load_iris()
>>> cross_val_score(clf, iris.data, iris.target, cv=10)
...
... array([ 1.    , 0.93..., 0.86..., 0.93..., 0.93..., 0.93..., 0.93..., 1.    , 0.93..., 1.    ])
```

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<td>Build a decision tree classifier from the training set <code>(X, y)</code>.</td>
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<td><code>score(X, y[, sample_weight])</code></td>
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<td><code>set_params(**params)</code></td>
<td>Set the parameters of this estimator.</td>
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**apply** `(X, check_input=True)`

Return the index of the leaf that each sample is predicted as.
Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

X_leaves [array-like of shape (n_samples,)] For each datapoint x in X, return the index of the leaf x ends up in. Leaves are numbered within [0; self.tree_.node_count), possibly with gaps in the numbering.

cost_complexity_pruning_path (X, y, sample_weight=None)
Compute the pruning path during Minimal Cost-Complexity Pruning.

See Minimal Cost-Complexity Pruning for details on the pruning process.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels) as integers or strings.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

ccp_path [Bunch] Dictionary-like object, with the following attributes.

ccp_alphas [ndarray] Effective alphas of subtree during pruning.

impurities [ndarray] Sum of the impurities of the subtree leaves for the corresponding alpha value in ccp_alphas.

decision_path (X, check_input=True)
Return the decision path in the tree.

New in version 0.18.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator CSR matrix where non zero elements indicates that the samples goes through the nodes.
property feature_importances_
Return the feature importances.

The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See `sklearn.inspection.permutation_importance` as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] Normalized total reduction of criteria by feature (Gini importance).

fit (X, y, sample_weight=None, check_input=True, X_idx_sorted='deprecated')
Build a decision tree classifier from the training set (X, y).

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels) as integers or strings.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

X_idx_sorted [deprecated, default="deprecated"] This parameter is deprecated and has no effect. It will be removed in 1.1 (renaming of 0.26).

Deprecated since version 0.24.

Returns

self [DecisionTreeClassifier] Fitted estimator.

get_depth ()
Return the depth of the decision tree.

The depth of a tree is the maximum distance between the root and any leaf.

Returns

self.tree_.max_depth [int] The maximum depth of the tree.

get_n_leaves ()
Return the number of leaves of the decision tree.

Returns

self.tree_.n_leaves [int] Number of leaves.

get_params (deep=True)
Get parameters for this estimator.

Parameters

deep [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.
**Returns**

**params** [dict] Parameter names mapped to their values.

**predict** *(X, check_input=True)*

Predict class or regression value for X.

For a classification model, the predicted class for each sample in X is returned. For a regression model, the predicted value based on X is returned.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

- **check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**Returns**

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] The predicted classes, or the predict values.

**predict_log_proba** *(X)*

Predict class log-probabilities of the input samples X.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **proba** [ndarray of shape (n_samples, n_classes) or list of n_outputs such arrays if n_outputs > 1] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute `classes_`.

**predict_proba** *(X, check_input=True)*

Predict class probabilities of the input samples X.

The predicted class probability is the fraction of samples of the same class in a leaf.

**Parameters**

- **X** [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

- **check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**Returns**

- **proba** [ndarray of shape (n_samples, n_classes) or list of n_outputs such arrays if n_outputs > 1] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute `classes_`.

**score** *(X, y, sample_weight=None)*

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.
Parameters

X [array-like of shape (n_samples, n_features)] Test samples.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

Examples using sklearn.tree.DecisionTreeClassifier

- Classifier comparison
- Plot the decision surface of a decision tree on the iris dataset
- Post pruning decision trees with cost complexity pruning
- Understanding the decision tree structure
- Plot the decision boundaries of a VotingClassifier
- Two-class AdaBoost
- Multi-class AdaBoosted Decision Trees
- Discrete versus Real AdaBoost
- Plot the decision surfaces of ensembles of trees on the iris dataset
- Demonstration of multi-metric evaluation on cross_val_score and GridSearchCV

7.37.2 sklearn.tree.DecisionTreeRegressor

class sklearn.tree.DecisionTreeRegressor(*, criterion='mse', splitter='best', max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_features=None, random_state=None, max_leaf_nodes=None, min_impurity_decrease=0.0, min_impurity_split=None, ccp_alpha=0.0)

A decision tree regressor.

Read more in the User Guide.

Parameters
criterion  [{“mse”, “friedman_mse”, “mae”, “poisson”}, default=”mse”] The function to measure the quality of a split. Supported criteria are “mse” for the mean squared error, which is equal to variance reduction as feature selection criterion and minimizes the L2 loss using the mean of each terminal node, “friedman_mse”, which uses mean squared error with Friedman’s improvement score for potential splits, “mae” for the mean absolute error, which minimizes the L1 loss using the median of each terminal node, and “poisson” which uses reduction in Poisson deviance to find splits.

New in version 0.18: Mean Absolute Error (MAE) criterion.

New in version 0.24: Poisson deviance criterion.

splitter  [{“best”, “random”}, default=”best”] The strategy used to choose the split at each node. Supported strategies are “best” to choose the best split and “random” to choose the best random split.

max_depth  [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min_samples_split samples.

min_samples_split  [int or float, default=2] The minimum number of samples required to split an internal node:

• If int, then consider min_samples_split as the minimum number.

• If float, then min_samples_split is a fraction and ceil(min_samples_split * n_samples) are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

min_samples_leaf  [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least min_samples_leaf training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

• If int, then consider min_samples_leaf as the minimum number.

• If float, then min_samples_leaf is a fraction and ceil(min_samples_leaf * n_samples) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

min_weight_fraction_leaf  [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

max_features  [int, float or {“auto”, “sqrt”, “log2”}, default=None] The number of features to consider when looking for the best split:

• If int, then consider max_features features at each split.

• If float, then max_features is a fraction and int(max_features * n_features) features are considered at each split.

• If “auto”, then max_features=n_features.

• If “sqrt”, then max_features=sqrt(n_features).

• If “log2”, then max_features=log2(n_features).

• If None, then max_features=n_features.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than max_features features.
**random_state** [int, RandomState instance or None, default=None] Controls the randomness of the estimator. The features are always randomly permuted at each split, even if splitter is set to "best". When `max_features < n_features`, the algorithm will select `max_features` at random at each split before finding the best split among them. But the best found split may vary across different runs, even if `max_features=n_features`. That is the case, if the improvement of the criterion is identical for several splits and one split has to be selected at random. To obtain a deterministic behaviour during fitting, random_state has to be fixed to an integer. See Glossary for details.

**max_leaf_nodes** [int, default=None] Grow a tree with `max_leaf_nodes` in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

**min_impurity_decrease** [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right_impurity} - \frac{N_{t,L}}{N_t} \times \text{left_impurity} \right)
\]

where \(N\) is the total number of samples, \(N_t\) is the number of samples at the current node, \(N_{t,L}\) is the number of samples in the left child, and \(N_{t,R}\) is the number of samples in the right child.

\(N, N_t, N_{t,R}\) and \(N_{t,L}\) all refer to the weighted sum, if `sample_weight` is passed.

New in version 0.19.

**min_impurity_split** [float, default=0] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: `min_impurity_split` has been deprecated in favor of `min_impurity_decrease` in 0.19. The default value of `min_impurity_split` has changed from 1e-7 to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than `ccp_alpha` will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

Attributes

**feature_importances_** [ndarray of shape (n_features,)] Return the feature importances.

**max_features_** [int] The inferred value of max_features.

**n_features_** [int] The number of features when fit is performed.

**n_outputs_** [int] The number of outputs when fit is performed.

**tree_** [Tree instance] The underlying Tree object. Please refer to help(sklearn.tree._tree.Tree) for attributes of Tree object and Understanding the decision tree structure for basic usage of these attributes.

See also:

*DecisionTreeClassifier* A decision tree classifier.
Notes

The default values for the parameters controlling the size of the trees (e.g. max_depth, min_samples_leaf, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

References

[1], [2], [3], [4]

Examples

```python
>>> from sklearn.datasets import load_diabetes
>>> from sklearn.model_selection import cross_val_score
>>> from sklearn.tree import DecisionTreeRegressor

>>> X, y = load_diabetes(return_X_y=True)
>>> regressor = DecisionTreeRegressor(random_state=0)
>>> cross_val_score(regressor, X, y, cv=10)
......
array([-0.39..., -0.46..., 0.02..., 0.06..., -0.50..., 0.16..., 0.11..., -0.73..., -0.30..., -0.00...])
```

Methods

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**apply** (X, check_input=True)

Return the index of the leaf that each sample is predicted as.

New in version 0.17.

Parameters

- **X** ([array-like, sparse matrix] of shape (n_samples, n_features)) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.
check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

X_leaves [array-like of shape (n_samples,)] For each datapoint x in X, return the index of the leaf x ends up in. Leaves are numbered within [0; self.tree_.node_count), possibly with gaps in the numbering.

cost_complexity_pruning_path (X, y, sample_weight=None)
Compute the pruning path during Minimal Cost-Complexity Pruning.

See Minimal Cost-Complexity Pruning for details on the pruning process.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels) as integers or strings.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

ccp_path [Bunch] Dictionary-like object, with the following attributes.

ccp_alphas [ndarray] Effective alphas of subtree during pruning.

impurities [ndarray] Sum of the impurities of the subtree leaves for the corresponding alpha value in ccp_alphas.

decision_path (X, check_input=True)
Return the decision path in the tree.

New in version 0.18.

Parameters

X [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator CSR matrix where non zero elements indicates that the samples goes through the nodes.

property feature_importances_
Return the feature importances.

The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.
Returns

**feature_importances_** [ndarray of shape (n_features,)] Normalized total reduction of criteria by feature (Gini importance).

**fit** (X, y, **sample_weight=None**, **check_input=True**, **X_idx_sorted='deprecated'**)  
Build a decision tree regressor from the training set (X, y).

**Parameters**

**X** [array-like, sparse matrix] of shape (n_samples, n_features) The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.

**y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (real numbers). Use dtype=np.float64 and order='C' for maximum efficiency.

**sample_weight** [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node.

**check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**X_idx_sorted** [deprecated, default='deprecated'] This parameter is deprecated and has no effect. It will be removed in 1.1 (renaming of 0.26).

**Returns**

**self** [DecisionTreeRegressor] Fitted estimator.

**get_depth** ()

> Return the depth of the decision tree.

> The depth of a tree is the maximum distance between the root and any leaf.

**Returns**

self.tree_.max_depth [int] The maximum depth of the tree.

**get_n_leaves** ()

> Return the number of leaves of the decision tree.

**Returns**

self.tree_.n_leaves [int] Number of leaves.

**get_params** (**deep=True**)  
Get parameters for this estimator.

**Parameters**

**deep** [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

**Returns**

**params** [dict] Parameter names mapped to their values.

**predict** (X, **check_input=True**)  
Predict class or regression value for X.

For a classification model, the predicted class for each sample in X is returned. For a regression model, the predicted value based on X is returned.
Parameters

X  [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input  [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] The predicted classes, or the predict values.

score (X, y, sample_weight=None)

Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{\text{true}} - y_{\text{pred}})^2).\text{sum()}$ and $v$ is the total sum of squares $((y_{\text{true}} - y_{\text{true}}.\text{mean()})^2).\text{sum()}$.

The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of y, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters

X  [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights.

Returns

score  [float] $R^2$ of self.predict(X) wrt. y.

Notes

The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)

Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params  [dict] Estimator parameters.

Returns

self  [estimator instance] Estimator instance.
An extremely randomized tree classifier.

Extra-trees differ from classic decision trees in the way they are built. When looking for the best split to separate the samples of a node into two groups, random splits are drawn for each of the max_features randomly selected features and the best split among those is chosen. When max_features is set 1, this amounts to building a totally random decision tree.

Warning: Extra-trees should only be used within ensemble methods.

Read more in the User Guide.

Parameters

criterion ([“gini”, “entropy”), default=”gini”] The function to measure the quality of a split. Supported criteria are “gini” for the Gini impurity and “entropy” for the information gain.

splitter {[“random”, “best”], default=”random”] The strategy used to choose the split at each node. Supported strategies are “best” to choose the best split and “random” to choose the best random split.

max_depth [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min_samples_split samples.

min_samples_split [int or float, default=2] The minimum number of samples required to split an internal node:

• If int, then consider min_samples_split as the minimum number.

• If float, then min_samples_split is a fraction and \( \text{ceil}(\text{min_samples_split} \times n_{\text{samples}}) \) are the minimum number of samples for each split.
min_samples_leaf [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least \( \text{min_samples_leaf} \) training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

- If int, then consider \( \text{min_samples_leaf} \) as the minimum number.
- If float, then \( \text{min_samples_leaf} \) is a fraction and \( \text{ceil}(\text{min_samples_leaf} \times n\_samples) \) are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

min_weight_fraction_leaf [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

max_features [int, float, {"auto", "sqrt", "log2"} or None, default="auto"] The number of features to consider when looking for the best split:

- If int, then consider \( \text{max_features} \) features at each split.
- If float, then \( \text{max_features} \) is a fraction and \( \text{int}(\text{max_features} \times n\_features) \) features are considered at each split.
- If "auto", then \( \text{max_features}=\sqrt{n\_features} \).
- If "sqrt", then \( \text{max_features}=\sqrt{n\_features} \).
- If "log2", then \( \text{max_features} = \log_2(n\_features) \).
- If None, then \( \text{max_features}=n\_features \).

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than \( \text{max_features} \) features.

random_state [int, RandomState instance or None, default=None] Used to pick randomly the \( \text{max_features} \) used at each split. See Glossary for details.

max_leaf_nodes [int, default=None] Grow a tree with \( \text{max_leaf_nodes} \) in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

min_impurity_decrease [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times \left( \text{impurity} - \frac{N_{t\_R}}{N_t} \times \text{right_impurity} - \frac{N_{t\_L}}{N_t} \times \text{left_impurity} \right)
\]

where \( N \) is the total number of samples, \( N_t \) is the number of samples at the current node, \( N_{t\_L} \) is the number of samples in the left child, and \( N_{t\_R} \) is the number of samples in the right child.

\( N, N_t, N_{t\_R}, \text{and } N_{t\_L} \) all refer to the weighted sum, if sample_weight is passed.

New in version 0.19.

min_impurity_split [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.

Deprecated since version 0.19: \( \text{min_impurity_split} \) has been deprecated in favor of \( \text{min_impurity_decrease} \) in 0.19. The default value of \( \text{min_impurity_split} \)
has changed from $1e^{-7}$ to 0 in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use `min_impurity_decrease` instead.

**class_weight** [dict, list of dict or “balanced”, default=None] Weights associated with classes in the form `{class_label: weight}`. If None, all classes are supposed to have weight one. For multi-output problems, a list of dicts can be provided in the same order as the columns of y.

Note that for multioutput (including multilabel) weights should be defined for each class of every column in its own dict. For example, for four-class multilabel classification weights should be `[[0: 1, 1: 1], [0: 1, 1: 5], [0: 1, 1: 1], [0: 1, 1: 1]]` instead of `[[1:1], [2:5], [3:1], [4:1]]`.

The “balanced” mode uses the values of y to automatically adjust weights inversely proportional to class frequencies in the input data as $n_{samples} / (n_{classes} * np.bincount(y))$

For multi-output, the weights of each column of y will be multiplied.

Note that these weights will be multiplied with sample_weight (passed through the fit method) if sample_weight is specified.

**ccp_alpha** [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than ccp_alpha will be chosen. By default, no pruning is performed. See Minimal Cost-Complexity Pruning for details.

New in version 0.22.

Attributes

- **classes_** [ndarray of shape (n_classes,) or list of ndarray] The classes labels (single output problem), or a list of arrays of class labels (multi-output problem).
- **max_features_** [int] The inferred value of max_features.
- **n_classes_** [int or list of int] The number of classes (for single output problems), or a list containing the number of classes for each output (for multi-output problems).
- **feature_importances_** [ndarray of shape (n_features,)] Return the feature importances.
- **n_features_** [int] The number of features when fit is performed.
- **n_outputs_** [int] The number of outputs when fit is performed.
- **tree_** [Tree instance] The underlying Tree object. Please refer to help(sklearn.tree._tree.Tree) for attributes of Tree object and Understanding the decision tree structure for basic usage of these attributes.

See also:

- **ExtraTreeRegressor** An extremely randomized tree regressor.
- **sklearn.ensemble.ExtraTreesClassifier** An extra-trees classifier.
- **sklearn.ensemble.ExtraTreesRegressor** An extra-trees regressor.
Notes

The default values for the parameters controlling the size of the trees (e.g. `max_depth`, `min_samples_leaf`, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

References

[1]

Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.ensemble import BaggingClassifier
>>> from sklearn.tree import ExtraTreeClassifier

>>> X, y = load_iris(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(...
    X, y, random_state=0)
>>> extra_tree = ExtraTreeClassifier(random_state=0)
>>> cls = BaggingClassifier(extra_tree, random_state=0).fit(...
    X_train, y_train)
>>> cls.score(X_test, y_test)
0.8947...
```

Methods

- `apply(X[, check_input])`: Return the index of the leaf that each sample is predicted as.
- `cost_complexity_pruning_path(X, y[, ...])`: Compute the pruning path during Minimal Cost-Complexity Pruning.
- `decision_path(X[, check_input])`: Return the decision path in the tree.
- `fit(X, y[, sample_weight, check_input, ...])`: Build a decision tree classifier from the training set (X, y).
- `get_depth()`: Return the depth of the decision tree.
- `get_n_leaves()`: Return the number of leaves of the decision tree.
- `get_params([deep])`: Get parameters for this estimator.
- `predict(X[, check_input])`: Predict class or regression value for X.
- `predict_log_proba(X)`: Predict class log-probabilities of the input samples X.
- `predict_proba(X[, check_input])`: Predict class probabilities of the input samples X.
- `score(X, y[, sample_weight])`: Return the mean accuracy on the given test data and labels.
- `set_params(**params)`: Set the parameters of this estimator.

apply (X, check_input=True)

Return the index of the leaf that each sample is predicted as.

New in version 0.17.

Parameters
X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=numpy.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

X_leaves  [array-like of shape (n_samples,)] For each datapoint x in X, return the index of the leaf x ends up in. Leaves are numbered within [0; self.tree_.node_count), possibly with gaps in the numbering.

cost_complexity_pruning_path (X, y, sample_weight=None)
Compute the pruning path during Minimal Cost-Complexity Pruning.

See Minimal Cost-Complexity Pruning for details on the pruning process.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=numpy.float32 and if a sparse matrix is provided to a sparse csc_matrix.

y  [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels) as integers or strings.

sample_weight  [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

ccp_path  [Bunch] Dictionary-like object, with the following attributes.

ccp_alphas  [ndarray] Effective alphas of subtree during pruning.

impurities  [ndarray] Sum of the impurities of the subtree leaves for the corresponding alpha value in ccp_alphas.

decision_path (X, check_input=True)
Return the decision path in the tree.

New in version 0.18.

Parameters

X  [{array-like, sparse matrix} of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=numpy.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

indicator  [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator CSR matrix where non zero elements indicates that the samples goes through the nodes.

property feature_importances_
Return the feature importances.

The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.
Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See `sklearn.inspection.permutation_importance` as an alternative.

Returns

- `feature_importances_` [ndarray of shape (n_features,)] Normalized total reduction of criteria by feature (Gini importance).

`fit(X, y, sample_weight=None, check_input=True, X_idx_sorted='deprecated')` Build a decision tree classifier from the training set (X, y).

Parameters

- `X` [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to `dtype=np.float32` and if a sparse matrix is provided to a sparse `csc_matrix`.
- `y` [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (class labels) as integers or strings.
- `sample_weight` [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.
- `check_input` [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.
- `X_idx_sorted` [deprecated, default="deprecated"] This parameter is deprecated and has no effect. It will be removed in 1.1 (renaming of 0.26).

Returns

- `self` [DecisionTreeClassifier] Fitted estimator.

`get_depth()` Return the depth of the decision tree.

The depth of a tree is the maximum distance between the root and any leaf.

Returns

- `self.tree_.max_depth` [int] The maximum depth of the tree.

`get_n_leaves()` Return the number of leaves of the decision tree.

Returns

- `self.tree_.n_leaves` [int] Number of leaves.

`get_params`(deep=True) Get parameters for this estimator.

Parameters

- `deep` [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

- `params` [dict] Parameter names mapped to their values.
**predict** (*X, check_input=True*)

Predict class or regression value for *X*.

For a classification model, the predicted class for each sample in *X* is returned. For a regression model, the predicted value based on *X* is returned.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.
- **check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**Returns**

- **y** [array-like of shape (n_samples,) or (n_samples, n_outputs)] The predicted classes, or the predict values.

**predict_log_proba** (*X*)

Predict class log-probabilities of the input samples *X*.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

**Returns**

- **proba** [ndarray of shape (n_samples, n_classes) or list of n_outputs such arrays if n_outputs > 1] The class log-probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

**predict_proba** (*X, check_input=True*)

Predict class probabilities of the input samples *X*.

The predicted class probability is the fraction of samples of the same class in a leaf.

**Parameters**

- **X** [array-like, sparse matrix] of shape (n_samples, n_features) The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.
- **check_input** [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

**Returns**

- **proba** [ndarray of shape (n_samples, n_classes) or list of n_outputs such arrays if n_outputs > 1] The class probabilities of the input samples. The order of the classes corresponds to that in the attribute classes_.

**score** (*X, y, sample_weight=None*)

Return the mean accuracy on the given test data and labels.

In multi-label classification, this is the subset accuracy which is a harsh metric since you require for each sample that each label set be correctly predicted.

**Parameters**

- **X** [array-like of shape (n_samples, n_features)] Test samples.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True labels for X.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns

cscore [float] Mean accuracy of self.predict(X) wrt. y.

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters

**params [dict] Estimator parameters.

Returns

self [estimator instance] Estimator instance.

7.37.4 sklearn.tree.ExtraTreeRegressor

class sklearn.tree.ExtraTreeRegressor (*, criterion='mse', splitter='random', max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0, max_features='auto', random_state=None, min_impurity_decrease=0.0, min_impurity_split=None, max_leaf_nodes=None, ccp_alpha=0.0)

An extremely randomized tree regressor.

Extra-trees differ from classic decision trees in the way they are built. When looking for the best split to separate the samples of a node into two groups, random splits are drawn for each of the max_features randomly selected features and the best split among those is chosen. When max_features is set 1, this amounts to building a totally random decision tree.

Warning: Extra-trees should only be used within ensemble methods.

Read more in the User Guide.

Parameters

criterion [{“mse”, “friedman_mse”, “mae”}, default=”mse”] The function to measure the quality of a split. Supported criteria are “mse” for the mean squared error, which is equal to variance reduction as feature selection criterion and “mae” for the mean absolute error.

New in version 0.18: Mean Absolute Error (MAE) criterion.

New in version 0.24: Poisson deviance criterion.
splitter [{“random”, “best”}, default=“random”] The strategy used to choose the split at each node. Supported strategies are “best” to choose the best split and “random” to choose the best random split.

max_depth [int, default=None] The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min_samples_split samples.

min_samples_split [int or float, default=2] The minimum number of samples required to split an internal node:
• If int, then consider `min_samples_split` as the minimum number.
• If float, then `min_samples_split` is a fraction and `ceil(min_samples_split * n_samples)` are the minimum number of samples for each split.

Changed in version 0.18: Added float values for fractions.

`min_samples_leaf` [int or float, default=1] The minimum number of samples required to be at a leaf node. A split point at any depth will only be considered if it leaves at least `min_samples_leaf` training samples in each of the left and right branches. This may have the effect of smoothing the model, especially in regression.

• If int, then consider `min_samples_leaf` as the minimum number.
• If float, then `min_samples_leaf` is a fraction and `ceil(min_samples_leaf * n_samples)` are the minimum number of samples for each node.

Changed in version 0.18: Added float values for fractions.

`min_weight_fraction_leaf` [float, default=0.0] The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node. Samples have equal weight when sample_weight is not provided.

`max_features` [int, float, {"auto", “sqrt”, “log2”} or None, default="auto"] The number of features to consider when looking for the best split:

• If int, then consider `max_features` features at each split.
• If float, then `max_features` is a fraction and `int(max_features * n_features)` features are considered at each split.
• If “auto”, then `max_features=n_features`.
• If “sqrt”, then `max_features=sqrt(n_features)`.
• If “log2”, then `max_features=log2(n_features)`.
• If None, then `max_features=n_features`.

Note: the search for a split does not stop until at least one valid partition of the node samples is found, even if it requires to effectively inspect more than `max_features` features.

`random_state` [int, RandomState instance or None, default=None] Used to pick randomly the `max_features` used at each split. See Glossary for details.

`min_impurity_decrease` [float, default=0.0] A node will be split if this split induces a decrease of the impurity greater than or equal to this value.

The weighted impurity decrease equation is the following:

\[
\frac{N_t}{N} \times (\text{impurity} - \frac{N_{t,R}}{N_t} \times \text{right\_impurity} - \frac{N_{t,L}}{N_t} \times \text{left\_impurity})
\]

where `N` is the total number of samples, `N_t` is the number of samples at the current node, `N_{t,L}` is the number of samples in the left child, and `N_{t,R}` is the number of samples in the right child.

`N, N_t, N_{t,R}` and `N_{t,L}` all refer to the weighted sum, if sample_weight is passed.

New in version 0.19.

`min_impurity_split` [float, default=None] Threshold for early stopping in tree growth. A node will split if its impurity is above the threshold, otherwise it is a leaf.
Deprecated since version 0.19: \texttt{min\_impurity\_split} has been deprecated in favor of \texttt{min\_impurity\_decrease} in 0.19. The default value of \texttt{min\_impurity\_split} has changed from \texttt{1e-7} to \texttt{0} in 0.23 and it will be removed in 1.0 (renaming of 0.25). Use \texttt{min\_impurity\_decrease} instead.

\textbf{max\_leaf\_nodes} [int, default=None] Grow a tree with \texttt{max\_leaf\_nodes} in best-first fashion. Best nodes are defined as relative reduction in impurity. If None then unlimited number of leaf nodes.

\textbf{ccp\_alpha} [non-negative float, default=0.0] Complexity parameter used for Minimal Cost-Complexity Pruning. The subtree with the largest cost complexity that is smaller than \texttt{ccp\_alpha} will be chosen. By default, no pruning is performed. See \textit{Minimal Cost-Complexity Pruning} for details.

New in version 0.22.

Attributes

\textbf{max\_features\_} [int] The inferred value of max\_features.

\textbf{n\_features\_} [int] The number of features when \texttt{fit} is performed.

\textbf{feature\_importances\_} [ndarray of shape (n\_features,)] Return the feature importances.

\textbf{n\_outputs\_} [int] The number of outputs when \texttt{fit} is performed.

\textbf{tree\_} [Tree instance] The underlying Tree object. Please refer to \texttt{help(sklearn.tree.\_tree.Tree)} for attributes of Tree object and \textit{Understanding the decision tree structure} for basic usage of these attributes.

See also:

\texttt{ExtraTreeClassifier} An extremely randomized tree classifier.

\texttt{sklearn.ensemble.ExtraTreesClassifier} An extra-trees classifier.

\texttt{sklearn.ensemble.ExtraTreesRegressor} An extra-trees regressor.

Notes

The default values for the parameters controlling the size of the trees (e.g. \texttt{max\_depth}, \texttt{min\_samples\_leaf}, etc.) lead to fully grown and unpruned trees which can potentially be very large on some data sets. To reduce memory consumption, the complexity and size of the trees should be controlled by setting those parameter values.

References

[1]
Examples

>>> from sklearn.datasets import load_diabetes
>>> from sklearn.model_selection import train_test_split
>>> from sklearn.ensemble import BaggingRegressor
>>> from sklearn.tree import ExtraTreeRegressor

>>> X, y = load_diabetes(return_X_y=True)
>>> X_train, X_test, y_train, y_test = train_test_split(...
    X, y, random_state=0)
>>> extra_tree = ExtraTreeRegressor(random_state=0)
>>> reg = BaggingRegressor(extra_tree, random_state=0).fit(...
    X_train, y_train)
>>> reg.score(X_test, y_test)
0.33...

Methods

apply(X[, check_input])
Return the index of the leaf that each sample is predicted as.

New in version 0.17.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

X_leaves [array-like of shape (n_samples,)] For each datapoint x in X, return the index of the leaf x ends up in. Leaves are numbered within [0; self.tree_.node_count), possibly with gaps in the numbering.

cost_complexity_pruning_path (X, y, sample_weight=None)
Compute the pruning path during Minimal Cost-Complexity Pruning.

See Minimal Cost-Complexity Pruning for details on the pruning process.
Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.

y [array-like of shape (n_samples,)] or (n_samples, n_outputs)] The target values (class labels) as integers or strings.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node. Splits are also ignored if they would result in any single class carrying a negative weight in either child node.

Returns

ccp_path [Bunch] Dictionary-like object, with the following attributes.

ccp_alphas [ndarray] Effective alphas of subtree during pruning.

impurities [ndarray] Sum of the impurities of the subtree leaves for the corresponding alpha value in ccp_alphas.

decision_path (X, check_input=True)
Return the decision path in the tree.
New in version 0.18.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

indicator [sparse matrix of shape (n_samples, n_nodes)] Return a node indicator CSR matrix where non zero elements indicates that the samples goes through the nodes.

property feature_importances_
Return the feature importances.

The importance of a feature is computed as the (normalized) total reduction of the criterion brought by that feature. It is also known as the Gini importance.

Warning: impurity-based feature importances can be misleading for high cardinality features (many unique values). See sklearn.inspection.permutation_importance as an alternative.

Returns

feature_importances_ [ndarray of shape (n_features,)] Normalized total reduction of criteria by feature (Gini importance).

fit (X, y, sample_weight=None, check_input=True, X_idx_sorted='deprecated')
Build a decision tree regressor from the training set (X, y).

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The training input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csc_matrix.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The target values (real numbers). Use dtype=np.float64 and order='C' for maximum efficiency.

sample_weight [array-like of shape (n_samples,), default=None] Sample weights. If None, then samples are equally weighted. Splits that would create child nodes with net zero or negative weight are ignored while searching for a split in each node.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

X_idx_sorted [deprecated, default="deprecated"] This parameter is deprecated and has no effect. It will be removed in 1.1 (renaming of 0.26).

Deprecated since version 0.24.

Returns

self [DecisionTreeRegressor] Fitted estimator.

get_depth ()

Return the depth of the decision tree.

The depth of a tree is the maximum distance between the root and any leaf.

Returns

self.tree_.max_depth [int] The maximum depth of the tree.

get_n_leaves ()

Return the number of leaves of the decision tree.

Returns

self.tree_.n_leaves [int] Number of leaves.

get_params (deep=True)

Get parameters for this estimator.

Parameters

depth [bool, default=True] If True, will return the parameters for this estimator and contained subobjects that are estimators.

Returns

params [dict] Parameter names mapped to their values.

predict (X, check_input=True)

Predict class or regression value for X.

For a classification model, the predicted class for each sample in X is returned. For a regression model, the predicted value based on X is returned.

Parameters

X [[array-like, sparse matrix] of shape (n_samples, n_features)] The input samples. Internally, it will be converted to dtype=np.float32 and if a sparse matrix is provided to a sparse csr_matrix.

check_input [bool, default=True] Allow to bypass several input checking. Don’t use this parameter unless you know what you do.

Returns

y [array-like of shape (n_samples,) or (n_samples, n_outputs)] The predicted classes, or the predict values.
score (X, y, sample_weight=None)
Return the coefficient of determination $R^2$ of the prediction.

The coefficient $R^2$ is defined as $(1 - \frac{u}{v})$, where $u$ is the residual sum of squares $((y_{true} - y_{pred}) ** 2).sum()$ and $v$ is the total sum of squares $((y_{true} - y_{true}.mean()) ** 2).sum()$. The best possible score is 1.0 and it can be negative (because the model can be arbitrarily worse). A constant model that always predicts the expected value of $y$, disregarding the input features, would get a $R^2$ score of 0.0.

Parameters
X [array-like of shape (n_samples, n_features)] Test samples. For some estimators this may be a precomputed kernel matrix or a list of generic objects instead with shape (n_samples, n_samples_fitted), where n_samples_fitted is the number of samples used in the fitting for the estimator.
y [array-like of shape (n_samples,) or (n_samples, n_outputs)] True values for X.
sample_weight [array-like of shape (n_samples,), default=None] Sample weights.

Returns
score [float] $R^2$ of self.predict(X) wrt. y.

Notes
The $R^2$ score used when calling score on a regressor uses multioutput='uniform_average' from version 0.23 to keep consistent with default value of r2_score. This influences the score method of all the multioutput regressors (except for MultiOutputRegressor).

set_params (**params)
Set the parameters of this estimator.

The method works on simple estimators as well as on nested objects (such as Pipeline). The latter have parameters of the form <component>__<parameter> so that it’s possible to update each component of a nested object.

Parameters
**params [dict] Estimator parameters.

Returns
self [estimator instance] Estimator instance.

---

Export a decision tree in DOT format.

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Export a decision tree in DOT format.
The sample counts that are shown are weighted with any sample_weights that might be present.

Read more in the User Guide.

Parameters

- **decision_tree** [decision tree classifier] The decision tree to be exported to GraphViz.
- **out_file** [object or str, default=None] Handle or name of the output file. If None, the result is returned as a string.

  Changed in version 0.20: Default of out_file changed from “tree.dot” to None.

- **max_depth** [int, default=None] The maximum depth of the representation. If None, the tree is fully generated.

- **feature_names** [list of str, default=None] Names of each of the features. If None generic names will be used (“feature_0”, “feature_1”, ...).

- **class_names** [list of str or bool, default=None] Names of each of the target classes in ascending numerical order. Only relevant for classification and not supported for multi-output. If True, shows a symbolic representation of the class name.

- **label** [{‘all’, ‘root’, ‘none’}, default=’all’] Whether to show informative labels for impurity, etc. Options include ‘all’ to show at every node, ‘root’ to show only at the top root node, or ‘none’ to not show at any node.

- **filled** [bool, default=False] When set to True, paint nodes to indicate majority class for classification, extremity of values for regression, or purity of node for multi-output.

- **leaves_parallel** [bool, default=False] When set to True, draw all leaf nodes at the bottom of the tree.

- **impurity** [bool, default=True] When set to True, show the impurity at each node.

- **node_ids** [bool, default=False] When set to True, show the ID number on each node.

- **proportion** [bool, default=False] When set to True, change the display of ‘values’ and/or ‘samples’ to be proportions and percentages respectively.

- **rotate** [bool, default=False] When set to True, orient tree left to right rather than top-down.

- **rounded** [bool, default=False] When set to True, draw node boxes with rounded corners and use Helvetica fonts instead of Times-Roman.

- **special_characters** [bool, default=False] When set to False, ignore special characters for PostScript compatibility.

- **precision** [int, default=3] Number of digits of precision for floating point in the values of impurity, threshold and value attributes of each node.

Returns

- **dot_data** [string] String representation of the input tree in GraphViz dot format. Only returned if out_file is None.

  New in version 0.18.
Examples

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn import tree

>>> clf = tree.DecisionTreeClassifier()
>>> iris = load_iris()

>>> clf = clf.fit(iris.data, iris.target)
>>> tree.export_graphviz(clf)
'digraph Tree{...
```

### 7.37.6 sklearn.tree.export_text

```python
sklearn.tree.export_text(decision_tree, *, feature_names=None, max_depth=10, spacing=3, decimals=2, show_weights=False)
```

Build a text report showing the rules of a decision tree.

Note that backwards compatibility may not be supported.

**Parameters**

- `decision_tree` [object] The decision tree estimator to be exported. It can be an instance of DecisionTreeClassifier or DecisionTreeRegressor.
- `feature_names` [list of str, default=None] A list of length n_features containing the feature names. If None generic names will be used ("feature_0", "feature_1", ...).
- `max_depth` [int, default=10] Only the first max_depth levels of the tree are exported. Truncated branches will be marked with "...".
- `spacing` [int, default=3] Number of spaces between edges. The higher it is, the wider the result.
- `decimals` [int, default=2] Number of decimal digits to display.
- `show_weights` [bool, default=False] If true the classification weights will be exported on each leaf. The classification weights are the number of samples each class.

**Returns**

- `report` [string] Text summary of all the rules in the decision tree.

**Examples**

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn.tree import DecisionTreeClassifier
>>> from sklearn.tree import export_text

>>> iris = load_iris()

>>> X = iris['data']

>>> y = iris['target']

>>> decision_tree = DecisionTreeClassifier(random_state=0, max_depth=2)

>>> decision_tree = decision_tree.fit(X, y)

>>> r = export_text(decision_tree, feature_names=iris['feature_names'])

>>> print(r)
|--- petal width (cm) <= 0.80
|   |--- class: 0
|--- petal width (cm) > 0.80
```

(continues on next page)
7.37.7 Plotting

```python
from sklearn import tree

tree.plot_tree(decision_tree, *, max_depth=None, feature_names=None, class_names=None, label='all', filled=False, impurity=True, node_ids=False, proportion=False, rotate='deprecated', rounded=False, precision=3, ax=None, fontsize=None)
```

Plot a decision tree.

The sample counts that are shown are weighted with any sample_weights that might be present.

The visualization is fit automatically to the size of the axis. Use the figsize or dpi arguments of plt.figure to control the size of the rendering.

Read more in the User Guide.

New in version 0.21.

**Parameters**

- `decision_tree` [decision tree regressor or classifier] The decision tree to be plotted.
- `max_depth` [int, default=None] The maximum depth of the representation. If None, the tree is fully generated.
- `feature_names` [list of strings, default=None] Names of each of the features. If None, generic names will be used (“X[0]”, “X[1]”, …).
- `class_names` [list of str or bool, default=None] Names of each of the target classes in ascending numerical order. Only relevant for classification and not supported for multi-output. If True, shows a symbolic representation of the class name.
- `label` [{'all', 'root', 'none'}, default='all'] Whether to show informative labels for impurity, etc. Options include ‘all’ to show at every node, ‘root’ to show only at the top root node, or ‘none’ to not show at any node.
- `filled` [bool, default=False] When set to True, paint nodes to indicate majority class for classification, extremity of values for regression, or purity of node for multi-output.
- `impurity` [bool, default=True] When set to True, show the impurity at each node.
- `node_ids` [bool, default=False] When set to True, show the ID number on each node.
- `proportion` [bool, default=False] When set to True, change the display of ‘values’ and/or ‘samples’ to be proportions and percentages respectively.
- `rotate` [bool, default=False] This parameter has no effect on the matplotlib tree visualisation and it is kept here for backward compatibility.
scikit-learn user guide, Release 0.24.0

Deprecated since version 0.23: `rotate` is deprecated in 0.23 and will be removed in 1.0 (renaming of 0.25).

**rounded** [bool, default=False] When set to True, draw node boxes with rounded corners and use Helvetica fonts instead of Times-Roman.

**precision** [int, default=3] Number of digits of precision for floating point in the values of impurity, threshold and value attributes of each node.

**ax** [matplotlib axis, default=None] Axes to plot to. If None, use current axis. Any previous content is cleared.

**fontsize** [int, default=None] Size of text font. If None, determined automatically to fit figure.

**Returns**

**annotations** [list of artists] List containing the artists for the annotation boxes making up the tree.

**Examples**

```python
>>> from sklearn.datasets import load_iris
>>> from sklearn import tree

>>> clf = tree.DecisionTreeClassifier(random_state=0)
>>> iris = load_iris()

>>> clf = clf.fit(iris.data, iris.target)
>>> tree.plot_tree(clf)
[Text(251.5,345.217,'X[3] <= 0.8...]
```

**Examples using sklearn.tree.plot_tree**

- Plot the decision surface of a decision tree on the iris dataset
- Understanding the decision tree structure

## 7.38 sklearn.utils: Utilities

The *sklearn.utils* module includes various utilities.

**Developer guide:** See the *Utilities for Developers* page for further details.

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7.38.1 sklearn.utils.arrayfuncs.min_pos

sklearn.utils.arrayfuncs.min_pos()

Find the minimum value of an array over positive values

Returns a huge value if none of the values are positive

7.38.2 sklearn.utils.as_float_array

sklearn.utils.as_float_array(X, *, copy=True, force_all_finite=True)

Converts an array-like to an array of floats.

The new dtypes will be np.float32 or np.float64, depending on the original type. The function can create a copy or modify the argument depending on the argument copy.

Parameters

X [{array-like, sparse matrix}]

copy [bool, default=True] If True, a copy of X will be created. If False, a copy may still be returned if X’s dtype is not a floating point type.

force_all_finite [bool or ‘allow-nan’, default=True] Whether to raise an error on np.inf, np.nan, pd.NA in X. The possibilities are:

• True: Force all values of X to be finite.
• False: accepts np.inf, np.nan, pd.NA in X.
• ‘allow-nan’: accepts only np.nan and pd.NA values in X. Values cannot be infinite.

New in version 0.20: force_all_finite accepts the string 'allow-nan'.

Changed in version 0.23: Accepts pd.NA and converts it into np.nan

Returns
XT  [{ndarray, sparse matrix}] An array of type float.

### 7.38.3 sklearn.utils.assert_all_finite

`sklearn.utils.assert_all_finite(X, *, allow_nan=False)`

Throw a ValueError if X contains NaN or infinity.

**Parameters**

- **X**  [{ndarray, sparse matrix}]
- **allow_nan** [bool, default=False]

### 7.38.4 sklearn.utils.Bunch

`sklearn.utils.Bunch(**kwargs)`

Container object exposing keys as attributes.

Bunch objects are sometimes used as an output for functions and methods. They extend dictionaries by enabling values to be accessed by key, `bunch["value_key"]`, or by an attribute, `bunch.value_key`.

**Examples**

```python
>>> b = Bunch(a=1, b=2)
>>> b['b']
2
>>> b.b
2
>>> b.a = 3
>>> b['a']
3
>>> b.c = 6
>>> b['c']
6
```

**Examples using sklearn.utils.Bunch**

- *Species distribution modeling*

### 7.38.5 sklearn.utils.check_X_y

`sklearn.utils.check_X_y(X, y, accept_sparse=False, *, accept_large_sparse=True, dtype=’numeric’, order=None, copy=False, force_allFinite=True, ensure_2d=True, allow_nd=False, multi_output=False, ensure_min_samples=1, ensure_min_features=1, y_numeric=False, estimator=None)`

Input validation for standard estimators.

Checks X and y for consistent length, enforces X to be 2D and y 1D. By default, X is checked to be non-empty and containing only finite values. Standard input checks are also applied to y, such as checking that y does not have np.nan or np.inf targets. For multi-label y, set multi_output=True to allow 2D and sparse y. If the dtype of X is object, attempt converting to float, raising on failure.

**Parameters**
X  [{ndarray, list, sparse matrix}] Input data.

y  [{ndarray, list, sparse matrix}] Labels.

accept_sparse  [str, bool or list of str, default=False] String[s] representing allowed sparse matrix formats, such as ‘csc’, ‘csr’, etc. If the input is sparse but not in the allowed format, it will be converted to the first listed format. True allows the input to be any format. False means that a sparse matrix input will raise an error.

accept_large_sparse  [bool, default=True] If a CSR, CSC, COO or BSR sparse matrix is supplied and accepted by accept_sparse, accept_large_sparse will cause it to be accepted only if its indices are stored with a 32-bit dtype.

New in version 0.20.

dtype  ['numeric', type, list of type or None, default='numeric'] Data type of result. If None, the dtype of the input is preserved. If “numeric”, dtype is preserved unless array.dtype is object. If dtype is a list of types, conversion on the first type is only performed if the dtype of the input is not in the list.

order  ['F', 'C', default=None] Whether an array will be forced to be fortran or c-style.

copy  [bool, default=False] Whether a forced copy will be triggered. If copy=False, a copy might be triggered by a conversion.

force_all_finite  [bool or 'allow-nan', default=True] Whether to raise an error on np.inf, np.nan, pd.NA in X. This parameter does not influence whether y can have np.inf, np.nan, pd.NA values. The possibilities are:

- True: Force all values of X to be finite.
- False: accepts np.inf, np.nan, pd.NA in X.
- ‘allow-nan’: accepts only np.nan or pd.NA values in X. Values cannot be infinite.

New in version 0.20: force_all_finite accepts the string 'allow-nan'.

Changed in version 0.23: Accepts pd.NA and converts it into np.nan.

ensure_2d  [bool, default=True] Whether to raise a value error if X is not 2D.

allow_nd  [bool, default=False] Whether to allow X.ndim > 2.

multi_output  [bool, default=False] Whether to allow 2D y (array or sparse matrix). If false, y will be validated as a vector. y cannot have np.nan or np.inf values if multi_output=True.

ensure_min_samples  [int, default=1] Make sure that X has a minimum number of samples in its first axis (rows for a 2D array).

ensure_min_features  [int, default=1] Make sure that the 2D array has some minimum number of features (columns). The default value of 1 rejects empty datasets. This check is only enforced when X has effectively 2 dimensions or is originally 1D and ensure_2d is True. Setting to 0 disables this check.

y_numeric  [bool, default=False] Whether to ensure that y has a numeric type. If dtype of y is object, it is converted to float64. Should only be used for regression algorithms.

estimator  [str or estimator instance, default=None] If passed, include the name of the estimator in warning messages.

Returns

- X_converted  [object] The converted and validated X.
- y_converted  [object] The converted and validated y.
Input validation on an array, list, sparse matrix or similar.

By default, the input is checked to be a non-empty 2D array containing only finite values. If the dtype of the array is object, attempt converting to float, raising on failure.

**Parameters**

- **array** [object] Input object to check / convert.
- **accept_sparse** [str, bool or list/tuple of str, default=False] String[s] representing allowed sparse matrix formats, such as ‘csc’, ‘csr’, etc. If the input is sparse but not in the allowed format, it will be converted to the first listed format. True allows the input to be any format. False means that a sparse matrix input will raise an error.
- **accept_large_sparse** [bool, default=True] If a CSR, CSC, COO or BSR sparse matrix is supplied and accepted by accept_sparse, accept_large_sparse=False will cause it to be accepted only if its indices are stored with a 32-bit dtype.
  - New in version 0.20.
- **dtype** ['numeric', type, list of type or None, default='numeric'] Data type of result. If None, the dtype of the input is preserved. If “numeric”, dtype is preserved unless array.dtype is object. If dtype is a list of types, conversion on the first type is only performed if the dtype of the input is not in the list.
- **order** [{‘F’, ‘C’} or None, default=None] Whether an array will be forced to be fortran or c-style. When order is None (default), then if copy=False, nothing is ensured about the memory layout of the output array; otherwise (copy=True) the memory layout of the returned array is kept as close as possible to the original array.
- **copy** [bool, default=False] Whether a forced copy will be triggered. If copy=False, a copy might be triggered by a conversion.
- **force_all_finite** [bool or ‘allow-nan’, default=True] Whether to raise an error on np.inf, np.nan, pd.NA in array. The possibilities are:
  - True: Force all values of array to be finite.
  - False: accepts np.inf, np.nan, pd.NA in array.
  - ‘allow-nan’: accepts only np.nan and pd.NA values in array. Values cannot be infinite.
  - New in version 0.20: force_all_finite accepts the string ‘allow-nan’.
  - Changed in version 0.23: Accepts pd.NA and converts it into np.nan
- **ensure_2d** [bool, default=True] Whether to raise a value error if array is not 2D.
- **allow_nd** [bool, default=False] Whether to allow array.ndim > 2.
- **ensure_min_samples** [int, default=1] Make sure that the array has a minimum number of samples in its first axis (rows for a 2D array). Setting to 0 disables this check.
- **ensure_min_features** [int, default=1] Make sure that the 2D array has some minimum number of features (columns). The default value of 1 rejects empty datasets. This check is only enforced when the input data has effectively 2 dimensions or is originally 1D and ensure_2d is True. Setting to 0 disables this check.
**Acquire**

**estimator** [str or estimator instance, default=None] If passed, include the name of the estimator in warning messages.

**Returns**

array_converted [object] The converted and validated array.

### 7.38.7 sklearn.utils.check_scalar

sklearn.utils.check_scalar(x, name, target_type, *, min_val=None, max_val=None)

Validate scalar parameters type and value.

**Parameters**

- x [object] The scalar parameter to validate.
- name [str] The name of the parameter to be printed in error messages.
- target_type [type or tuple] Acceptable data types for the parameter.
- min_val [float or int, default=None] The minimum valid value the parameter can take. If None (default) it is implied that the parameter does not have a lower bound.
- max_val [float or int, default=None] The maximum valid value the parameter can take. If None (default) it is implied that the parameter does not have an upper bound.

**Raises**

- TypeError If the parameter’s type does not match the desired type.
- ValueError If the parameter’s value violates the given bounds.

### 7.38.8 sklearn.utils.check_consistent_length

sklearn.utils.check_consistent_length(*arrays)

Check that all arrays have consistent first dimensions.

Checks whether all objects in arrays have the same shape or length.

**Parameters**

*arrays [list or tuple of input objects.] Objects that will be checked for consistent length.

### 7.38.9 sklearn.utils.check_random_state

sklearn.utils.check_random_state(seed)

Turn seed into a np.random.RandomState instance

**Parameters**

- seed [None, int or instance of RandomState] If seed is None, return the RandomState singleton used by np.random. If seed is an int, return a new RandomState instance seeded with seed. If seed is already a RandomState instance, return it. Otherwise raise ValueError.
Examples using `sklearn.utils.check_random_state`

- Empirical evaluation of the impact of k-means initialization
- MNIST classification using multinomial logistic + L1
- Manifold Learning methods on a severed sphere
- Isotonic Regression
- Face completion with a multi-output estimators
- Scaling the regularization parameter for SVCs

### 7.38.10 `sklearn.utils.class_weight.compute_class_weight`

`sklearn.utils.class_weight.compute_class_weight`(class_weight, *, classes, y)

Estimate class weights for unbalanced datasets.

**Parameters**

- **class_weight** [dict, ‘balanced’ or None] If ‘balanced’, class weights will be given by \( \frac{n_{samples}}{n_{classes} \times \text{np.bincount}(y)} \). If a dictionary is given, keys are classes and values are corresponding class weights. If None is given, the class weights will be uniform.

- **classes** [ndarray] Array of the classes occurring in the data, as given by \( \text{np.unique}(y\_org) \) with \( y\_org \) the original class labels.

- **y** [array-like of shape (n_samples,)] Array of original class labels per sample.

**Returns**

- **class_weight_vect** [ndarray of shape (n_classes,)] Array with class_weight_vect[i] the weight for i-th class.

**References**

The “balanced” heuristic is inspired by Logistic Regression in Rare Events Data, King, Zen, 2001.

### 7.38.11 `sklearn.utils.class_weight.compute_sample_weight`

`sklearn.utils.class_weight.compute_sample_weight`(class_weight, y, *, indices=None)

Estimate sample weights by class for unbalanced datasets.

**Parameters**

- **class_weight** [dict, list of dicts, “balanced”, or None] Weights associated with classes in the form `{class_label: weight}`. If not given, all classes are supposed to have weight one. For multi-output problems, a list of dicts can be provided in the same order as the columns of y.

    Note that for multioutput (including multilabel) weights should be defined for each class of every column in its own dict. For example, for four-class multilabel classification weights should be `[[0: 1, 1: 1], [0: 1, 1: 5], [0: 1, 1: 1], [0: 1, 1: 1]]` instead of `[[1:1], [2:5], [3:1], [4:1]]`. 


The “balanced” mode uses the values of \( y \) to automatically adjust weights inversely proportional to class frequencies in the input data: \( n_{\text{samples}} / (n_{\text{classes}} \times \text{n. bincount}(y)) \).

For multi-output, the weights of each column of \( y \) will be multiplied.

\( y \) [array-like of shape (n_samples,) or (n_samples, n_outputs)] Array of original class labels per sample.

\( \text{indices} \) [array-like of shape (n_subsample,), default=None] Array of indices to be used in a subsample. Can be of length less than \( n_{\text{samples}} \) in the case of a subsample, or equal to \( n_{\text{samples}} \) in the case of a bootstrap subsample with repeated indices. If None, the sample weight will be calculated over the full sample. Only “balanced” is supported for class_weight if this is provided.

Returns

\( \text{sample_weight_vect} \) [ndarray of shape (n_samples,)] Array with sample weights as applied to the original \( y \).

### 7.38.12 sklearn.utils.deprecated

sklearn.utils.deprecated\((\text{extra}='')\)

Decorator to mark a function or class as deprecated.

Issue a warning when the function is called/the class is instantiated and adds a warning to the docstring.

The optional extra argument will be appended to the deprecation message and the docstring. Note: to use this with the default value for extra, put in an empty of parentheses:

```python
>>> from sklearn.utils import deprecated
>>> deprecated()
<sklearn.utils.deprecation.deprecated object at ...
```

```python
>>> @deprecated()
... def some_function():
...     pass
```

Parameters

\( \text{extra} \) [str, default=""] To be added to the deprecation messages.

### 7.38.13 sklearn.utils.estimator_checks.check_estimator

sklearn.utils.estimator_checks.check_estimator\((\text{Estimator}, \text{generate_only}=\text{False})\)

Check if estimator adheres to scikit-learn conventions.

This estimator will run an extensive test-suite for input validation, shapes, etc, making sure that the estimator complies with scikit-learn conventions as detailed in Rolling your own estimator. Additional tests for classifiers, regressors, clustering or transformers will be run if the Estimator class inherits from the corresponding mixin from sklearn.base.

Setting \( \text{generate_only}=\text{True} \) returns a generator that yields (estimator, check) tuples where the check can be called independently from each other, i.e. check(estimator). This allows all checks to be run independently and report the checks that are failing.

scikit-learn provides a pytest specific decorator, parametrize_with_checks, making it easier to test multiple estimators.
Parameters

**Estimator** [estimator object] Estimator instance to check.

Changed in version 0.24: Passing a class was deprecated in version 0.23, and support for classes was removed in 0.24.

**generate_only** [bool, default=False] When False, checks are evaluated when check_estimator is called. When True, check_estimator returns a generator that yields (estimator, check) tuples. The check is run by calling check(estimator).

New in version 0.22.

Returns

**checks_generator** [generator] Generator that yields (estimator, check) tuples. Returned when generate_only=True.

7.38.14 sklearn.utils.estimator_checks.parametrize_with_checks

sklearn.utils.estimator_checks.parametrize_with_checks(estimators)

Pytest specific decorator for parametrizing estimator checks.

The id of each check is set to be a pprint version of the estimator and the name of the check with its keyword arguments. This allows to use pytest -k to specify which tests to run:

```
pytest test_check_estimators.py -k check_estimators_fit_returns_self
```

Parameters

**estimators** [list of estimators instances] Estimators to generated checks for.

Changed in version 0.24: Passing a class was deprecated in version 0.23, and support for classes was removed in 0.24. Pass an instance instead.

New in version 0.24.

Returns

**decorator** [pytest.mark.parametrize]

Examples

```
>>> from sklearn.utils.estimator_checks import parametrize_with_checks
>>> from sklearn.linear_model import LogisticRegression
>>> from sklearn.tree import DecisionTreeRegressor

>>> @parametrize_with_checks([[LogisticRegression()],
... DecisionTreeRegressor()]])
... def test_sklearn_compatible_estimator(estimator, check):
...     check(estimator)
```
Examples using sklearn.utils.estimator_checks.parametrize_with_checks

- Release Highlights for scikit-learn 0.22

7.38.15 sklearn.utils.estimator_html_repr

sklearn.utils.estimator_html_repr(estimator)
Build a HTML representation of an estimator.
Read more in the User Guide.

Parameters

estimator [estimator object] The estimator to visualize.

Returns

html: str HTML representation of estimator.

7.38.16 sklearn.utils.extmath.safe_sparse_dot

sklearn.utils.extmath.safe_sparse_dot(a, b, *, dense_output=False)
Dot product that handle the sparse matrix case correctly.

Parameters

a [ndarray, sparse matrix]
b [ndarray, sparse matrix]
dense_output [bool, default=False] When False, a and b both being sparse will yield sparse output. When True, output will always be a dense array.

Returns

dot_product [ndarray, sparse matrix] Sparse if a and b are sparse and dense_output=False.

7.38.17 sklearn.utils.extmath.randomized_range_finder

sklearn.utils.extmath.randomized_range_finder(A, *, size, n_iter, power_iteration_normalizer='auto', random_state=None)
Computes an orthonormal matrix whose range approximates the range of A.

Parameters

size [int] Size of the return array.
n_iter [int] Number of power iterations used to stabilize the result.
power_iteration_normalizer [{‘auto’, ‘QR’, ‘LU’, ‘none’}, default=’auto’] Whether the power iterations are normalized with step-by-step QR factorization (the slowest but most accurate), ‘none’ (the fastest but numerically unstable when n_iter is large, e.g. typically 5 or larger), or ‘LU’ factorization (numerically stable but can lose slightly in accuracy). The ‘auto’ mode applies no normalization if n_iter <= 2 and switches to LU otherwise.

New in version 0.18.
random_state [int, RandomState instance or None, default=None] The seed of the pseudo random number generator to use when shuffling the data, i.e. getting the random vectors to initialize the algorithm. Pass an int for reproducible results across multiple function calls. See Glossary.

Returns

Q [ndarray] A (size x size) projection matrix, the range of which approximates well the range of the input matrix A.

Notes


An implementation of a randomized algorithm for principal component analysis A. Szlam et al. 2014

7.38.18 sklearn.utils.extmath.randomized_svd

sklearn.utils.extmath.randomized_svd(M, n_components, *, n_oversamples=10, n_iter='auto', power_iteration_normalizer='auto', transpose='auto', flip_sign=True, random_state=0)

Computes a truncated randomized SVD.

Parameters

M [{ndarray, sparse matrix}] Matrix to decompose.

n_components [int] Number of singular values and vectors to extract.

n_oversamples [int, default=10] Additional number of random vectors to sample the range of M so as to ensure proper conditioning. The total number of random vectors used to find the range of M is n_components + n_oversamples. Smaller number can improve speed but can negatively impact the quality of approximation of singular vectors and singular values.

n_iter [int or ‘auto’, default=’auto’] Number of power iterations. It can be used to deal with very noisy problems. When ‘auto’, it is set to 4, unless n_components is small (< .1 * min(X.shape)) n_iter in which case is set to 7. This improves precision with few components.

Changed in version 0.18.

power_iteration_normalizer [{‘auto’, ‘QR’, ‘LU’, ‘none’}, default=’auto’] Whether the power iterations are normalized with step-by-step QR factorization (the slowest but most accurate), ‘none’ (the fastest but numerically unstable when n_iter is large, e.g. typically 5 or larger), or ‘LU’ factorization (numerically stable but can lose slightly in accuracy). The ‘auto’ mode applies no normalization if n_iter <= 2 and switches to LU otherwise.

New in version 0.18.

transpose [bool or ‘auto’, default=’auto’] Whether the algorithm should be applied to M.T instead of M. The result should approximately be the same. The ‘auto’ mode will trigger the transposition if M.shape[1] > M.shape[0] since this implementation of randomized SVD tend to be a little faster in that case.

Changed in version 0.18.

flip_sign [bool, default=True] The output of a singular value decomposition is only unique up to a permutation of the signs of the singular vectors. If flip_sign is set to True, the sign
ambiguity is resolved by making the largest loadings for each component in the left singular vectors positive.

**random_state** [int, RandomState instance or None, default=0] The seed of the pseudo random number generator to use when shuffling the data, i.e. getting the random vectors to initialize the algorithm. Pass an int for reproducible results across multiple function calls. See *Glossary*.

**Notes**

This algorithm finds a (usually very good) approximate truncated singular value decomposition using randomization to speed up the computations. It is particularly fast on large matrices on which you wish to extract only a small number of components. In order to obtain further speed up, `n_iter` can be set <=2 (at the cost of loss of precision).

**References**

- A randomized algorithm for the decomposition of matrices Per-Gunnar Martinsson, Vladimir Rokhlin and Mark Tygert
- An implementation of a randomized algorithm for principal component analysis A. Szlam et al. 2014

### 7.38.19 sklearn.utils.extmath.fast_logdet

```python
sklearn.utils.extmath.fast_logdet(A)
```

Compute log(det(A)) for A symmetric.

Equivalent to : np.log(nl.det(A)) but more robust. It returns -Inf if det(A) is non positive or is not defined.

**Parameters**


### 7.38.20 sklearn.utils.extmath.density

```python
sklearn.utils.extmath.density(w, **kwargs)
```

Compute density of a sparse vector.

**Parameters**

- `w` [array-like] The sparse vector.

**Returns**

- `float` The density of w, between 0 and 1.
Examples using `sklearn.utils.extmath.density`

- Classification of text documents using sparse features

### 7.38.21 `sklearn.utils.extmath.weighted_mode`

`sklearn.utils.extmath.weighted_mode(a, w, *, axis=0)`

Returns an array of the weighted modal (most common) value in `a`.

If there is more than one such value, only the first is returned. The bin-count for the modal bins is also returned.

This is an extension of the algorithm in `scipy.stats.mode`.

**Parameters**

- `a` [array-like] n-dimensional array of which to find mode(s).
- `w` [array-like] n-dimensional array of weights for each value.
- `axis` [int, default=0] Axis along which to operate. Default is 0, i.e. the first axis.

**Returns**

- `vals` [ndarray] Array of modal values.
- `score` [ndarray] Array of weighted counts for each mode.

**See also:**

`scipy.stats.mode`

**Examples**

```python
>>> from sklearn.utils.extmath import weighted_mode
>>> x = [4, 1, 4, 2, 4, 2]
>>> weights = [1, 1, 1, 1, 1, 1]
>>> weighted_mode(x, weights)
(array([4.]), array([3.]))

The value 4 appears three times: with uniform weights, the result is simply the mode of the distribution.

```python
>>> weights = [1, 3, 0.5, 1.5, 1, 2]  # deweight the 4's
>>> weighted_mode(x, weights)
(array([2.]), array([3.5]))

The value 2 has the highest score: it appears twice with weights of 1.5 and 2: the sum of these is 3.5.

### 7.38.22 `sklearn.utils.gen_even_slices`

`sklearn.utils.gen_even_slices(n, n_packs, *, n_samples=None)`

Generator to create `n_packs` slices going up to `n`.

**Parameters**

- `n` [int]
- `n_packs` [int] Number of slices to generate.
**n_samples** [int, default=None] Number of samples. Pass n_samples when the slices are to be used for sparse matrix indexing; slicing off-the-end raises an exception, while it works for NumPy arrays.

**Yields**

```
slice
```

**Examples**

```python
>>> from sklearn.utils import gen_even_slices
>>> list(gen_even_slices(10, 1))
[slice(0, 10, None)]
>>> list(gen_even_slices(10, 10))
[slice(0, 1, None), slice(1, 2, None), ..., slice(9, 10, None)]
>>> list(gen_even_slices(10, 5))
[slice(0, 2, None), slice(2, 4, None), ..., slice(8, 10, None)]
>>> list(gen_even_slices(10, 3))
[slice(0, 4, None), slice(4, 7, None), slice(7, 10, None)]
```

**Examples using sklearn.utils.gen_even_slices**

- Poisson regression and non-normal loss

### 7.38.23 sklearn.utils.graph.single_source_shortest_path_length

The function `sklearn.utils.graph.single_source_shortest_path_length` returns the shortest path length from source to all reachable nodes.

**Parameters**

- **graph** [{sparse matrix, ndarray} of shape (n, n)] Adjacency matrix of the graph. Sparse matrix of format LIL is preferred.
- **source** [int] Starting node for path.
- **cutoff** [int, default=None] Depth to stop the search - only paths of length <= cutoff are returned.

**Examples**

```python
>>> from sklearn.utils.graph import single_source_shortest_path_length
>>> import numpy as np

graph = np.array([[ 0, 1, 0, 0],
                 ... [ 1, 0, 1, 0],
                 ... [ 0, 1, 0, 1],
                 ... [ 0, 0, 1, 0]])

list(sorted(single_source_shortest_path_length(graph, 0).items()))
[(0, 0), (1, 1), (2, 2), (3, 3)]

graph = np.ones((6, 6))

list(sorted(single_source_shortest_path_length(graph, 2).items()))
[(0, 1), (1, 1), (2, 0), (3, 1), (4, 1), (5, 1)]
```
**7.38.24 sklearn.utils.graph_shortest_path.graph_shortest_path**

Perform a shortest-path graph search on a positive directed or undirected graph.

**Parameters**

- **dist_matrix** [arraylike or sparse matrix, shape = (N,N)] Array of positive distances. If vertex i is connected to vertex j, then dist_matrix[i,j] gives the distance between the vertices. If vertex i is not connected to vertex j, then dist_matrix[i,j] = 0

- **directed** [boolean] if True, then find the shortest path on a directed graph: only progress from a point to its neighbors, not the other way around. if False, then find the shortest path on an undirected graph: the algorithm can progress from a point to its neighbors and vice versa.

- **method** [string ['auto'|'FW'|'D']] method to use. Options are ‘auto’ : attempt to choose the best method for the current problem ‘FW’ : Floyd-Warshall algorithm. O[N^3] ‘D’ : Dijkstra’s algorithm with Fibonacci stacks. O[(k+log(N))N^2]

**Returns**

- **G** [np.ndarray, float, shape = [N,N]] G[i,j] gives the shortest distance from point i to point j along the graph.

**Notes**

As currently implemented, Dijkstra’s algorithm does not work for graphs with direction-dependent distances when directed == False. i.e., if dist_matrix[i,j] and dist_matrix[j,i] are not equal and both are nonzero, method=“D” will not necessarily yield the correct result.

Also, these routines have not been tested for graphs with negative distances. Negative distances can lead to infinite cycles that must be handled by specialized algorithms.

**7.38.25 sklearn.utils.indexable**

Make arrays indexable for cross-validation.

**Parameters**

- ***iterables** [{lists, dataframes, ndarrays, sparse matrices}] List of objects to ensure sliceability.

**7.38.26 sklearn.utils.metaestimators.if_delegate_has_method**

Create a decorator for methods that are delegated to a sub-estimator

This enables ducktyping by hasattr returning True according to the sub-estimator.

**Parameters**

- **delegate** [string, list of strings or tuple of strings] Name of the sub-estimator that can be accessed as an attribute of the base object. If a list or a tuple of names are provided, the first sub-estimator that is an attribute of the base object will be used.
Examples using `sklearn.utils.metaestimators.if_delegate_has_method`

**Inductive Clustering**

7.38.27 `sklearn.utils.multiclass.type_of_target`

`sklearn.utils.multiclass.type_of_target(y)`

Determine the type of data indicated by the target.

Note that this type is the most specific type that can be inferred. For example:

- `binary` is more specific but compatible with `multiclass`.
- `multiclass` of integers is more specific but compatible with `continuous`.
- `multilabel-indicator` is more specific but compatible with `multiclass-multioutput`.

Parameters

- `y` [array-like]

Returns

- `target_type` [str] One of:
  - `continuous`: `y` is an array-like of floats that are not all integers, and is 1d or a column vector.
  - `continuous-multioutput`: `y` is a 2d array of floats that are not all integers, and both dimensions are of size > 1.
  - `binary`: `y` contains <= 2 discrete values and is 1d or a column vector.
  - `multiclass`: `y` contains more than two discrete values, is not a sequence of sequences, and is 1d or a column vector.
  - `multiclass-multioutput`: `y` is a 2d array that contains more than two discrete values, is not a sequence of sequences, and both dimensions are of size > 1.
  - `multilabel-indicator`: `y` is a label indicator matrix, an array of two dimensions with at least two columns, and at most 2 unique values.
  - `unknown`: `y` is array-like but none of the above, such as a 3d array, sequence of sequences, or an array of non-sequence objects.

Examples

```python
>>> import numpy as np
>>> type_of_target([0.1, 0.6])
'continuous'
>>> type_of_target([1, -1, -1, 1])
'binary'
>>> type_of_target(['a', 'b', 'a'])
'binary'
>>> type_of_target([1.0, 2.0])
'binary'
>>> type_of_target([1, 0, 2])
'multiclass'
>>> type_of_target([1.0, 0.0, 3.0])
(continues on next page)
```
`'multiclass`

```python
>>> type_of_target(['a', 'b', 'c'])
'multiclass'
```

```python
>>> type_of_target(np.array([[1, 2], [3, 1]]))
'multiclass-multioutput'
```  
```python
>>> type_of_target([1, 2])
'multilabel-indicator'
```

```python
>>> type_of_target(np.array([[1.5, 2.0], [3.0, 1.6]]))
'continuous-multioutput'
```  
```python
>>> type_of_target(np.array([[0, 1], [1, 1]]))
'multilabel-indicator'
```  

### 7.38.28 sklearn.utils.multiclass.is_multilabel

`sklearn.utils.multiclass.is_multilabel(y)`

Check if `y` is in a multilabel format.

**Parameters**

- `y` ([ndarray of shape (n_samples,)]) Target values.

**Returns**

- `out` [bool] Return `True`, if `y` is in a multilabel format, else `False`.

**Examples**

```python
>>> import numpy as np
>>> from sklearn.utils.multiclass import is_multilabel
>>> is_multilabel([0, 1, 0, 1])
False
>>> is_multilabel([[1], [0, 2], []])
False
>>> is_multilabel(np.array([[1, 0], [0, 0]]))
True
>>> is_multilabel(np.array([[1], [0], [0]]))
False
>>> is_multilabel(np.array([[1, 0, 0]]))
True
```  

### 7.38.29 sklearn.utils.multiclass.unique_labels

`sklearn.utils.multiclass.unique_labels(*ys)`

```
Extract an ordered array of unique labels.

**We don’t allow:**

- mix of multilabel and multiclass (single label) targets
- mix of label indicator matrix and anything else, because there are no explicit labels
- mix of label indicator matrices of different sizes
- mix of string and integer labels

At the moment, we also don’t allow “multiclass-multioutput” input type.
```
Parameters

*ys [array-likes]

Returns

out [ndarray of shape (n_unique_labels,)] An ordered array of unique labels.

Examples

```python
>>> from sklearn.utils.multiclass import unique_labels
>>> unique_labels([3, 5, 5, 5, 7, 7])
array([3, 5, 7])
>>> unique_labels([1, 2, 3, 4], [2, 2, 3, 4])
array([1, 2, 3, 4])
>>> unique_labels([1, 2, 10], [5, 11])
array([ 1,  2, 10, 11])
```

7.38.30 sklearn.utils.murmurhash3_32

sklearn.utils.murmurhash3_32()

Compute the 32bit murmurhash3 of key at seed.

The underlying implementation is MurmurHash3_x86_32 generating low latency 32bits hash suitable for implementing lookup tables, Bloom filters, count min sketch or feature hashing.

Parameters

key [np.int32, bytes, unicode or ndarray of dtype=np.int32] The physical object to hash.

seed [int, default=0] Integer seed for the hashing algorithm.

positive [bool, default=False] True: the results is casted to an unsigned int from 0 to 2 ** 32 - 1 False: the results is casted to a signed int from -(2 ** 31) to 2 ** 31 - 1

7.38.31 sklearn.utils.resample

sklearn.utils.resample(*arrays, replace=True, n_samples=None, random_state=None, stratify=None)

Resample arrays or sparse matrices in a consistent way.

The default strategy implements one step of the bootstrapping procedure.

Parameters

*arrays [sequence of array-like of shape (n_samples,) or (n_samples, n_outputs)] Indexable data-structures can be arrays, lists, dataframes or scipy sparse matrices with consistent first dimension.

replace [bool, default=True] Implements resampling with replacement. If False, this will implement (sliced) random permutations.

n_samples [int, default=None] Number of samples to generate. If left to None this is automatically set to the first dimension of the arrays. If replace is False it should not be larger than the length of arrays.
**random_state** [int, RandomState instance or None, default=None] Determines random number generation for shuffling the data. Pass an int for reproducible results across multiple function calls. See *Glossary*.

**stratify** [array-like of shape (n_samples,) or (n_samples, n_outputs), default=None] If not None, data is split in a stratified fashion, using this as the class labels.

**Returns**

resampled_arrays [sequence of array-like of shape (n_samples,) or (n_samples, n_outputs)] Sequence of resampled copies of the collections. The original arrays are not impacted.

**See also:**

*shuffle*

**Examples**

It is possible to mix sparse and dense arrays in the same run:

```python
>>> X = np.array([[1., 0.], [2., 1.], [0., 0.]])
>>> y = np.array([0, 1, 2])
>>> from scipy.sparse import coo_matrix
>>> X_sparse = coo_matrix(X)
>>> from sklearn.utils import resample
>>> X, X_sparse, y = resample(X, X_sparse, y, random_state=0)
>>> X
array([[1., 0.],
        [2., 1.],
        [1., 0.]])

>>> X_sparse
<3x2 sparse matrix of type '<... 'numpy.float64'>'
          with 4 stored elements in Compressed Sparse Row format>

>>> X_sparse.toarray()
array([[1., 0.],
        [2., 1.],
        [1., 0.]])

>>> y
array([0, 1, 0])

>>> resample(y, n_samples=2, random_state=0)
array([0, 1])
```

Example using stratification:

```python
>>> y = [0, 0, 1, 1, 1, 1, 1, 1, 1]
>>> resample(y, n_samples=5, replace=False, stratify=y,
...          random_state=0)
[1, 1, 1, 0, 1]
```
7.38.32 sklearn.utils.safe_indexing

sklearn.utils.safe_indexing(X, indices, *, axis=0)
Return rows, items or columns of X using indices.

Warning: This utility is documented, but private. This means that backward compatibility might be broken without any deprecation cycle.

Parameters

X [array-like, sparse-matrix, list, pandas.DataFrame, pandas.Series] Data from which to sample rows, items or columns. list are only supported when axis=0.

indices [bool, int, str, slice, array-like]
- If axis=0, boolean and integer array-like, integer slice, and scalar integer are supported.
- If axis=1:
  - to select a single column, indices can be of int type for all X types and str only for dataframe. The selected subset will be 1D, unless X is a sparse matrix in which case it will be 2D.
  - to select multiples columns, indices can be one of the following: list, array, slice. The type used in these containers can be one of the following: int, ‘bool’ and str. However, str is only supported when X is a dataframe. The selected subset will be 2D.

axis [int, default=0] The axis along which X will be subsampled. axis=0 will select rows while axis=1 will select columns.

Returns

subset Subset of X on axis 0 or 1.

Notes

CSR, CSC, and LIL sparse matrices are supported. COO sparse matrices are not supported.

7.38.33 sklearn.utils.safe_mask

sklearn.utils.safe_mask(X, mask)
Return a mask which is safe to use on X.

Parameters

X [{array-like, sparse matrix}] Data on which to apply mask.
mask [ndarray] Mask to be used on X.

Returns

mask
7.38.34 sklearn.utils.safe_sqr

sklearn.utils.safe_sqr(X, *, copy=True)
Element wise squaring of array-likes and sparse matrices.

Parameters

- X [{array-like, ndarray, sparse matrix}]
- copy [bool, default=True] Whether to create a copy of X and operate on it or to perform in-place computation (default behaviour).

Returns

- X ** 2 [element wise square]

7.38.35 sklearn.utils.shuffle

sklearn.utils.shuffle(*arrays, random_state=None, n_samples=None)
Shuffle arrays or sparse matrices in a consistent way.

This is a convenience alias to resample(*arrays, replace=False) to do random permutations of the collections.

Parameters

- *arrays [sequence of indexable data-structures] Indexable data-structures can be arrays, lists, dataframes or scipy sparse matrices with consistent first dimension.
- random_state [int, RandomState instance or None, default=None] Determines random number generation for shuffling the data. Pass an int for reproducible results across multiple function calls. See Glossary.
- n_samples [int, default=None] Number of samples to generate. If left to None this is automatically set to the first dimension of the arrays. It should not be larger than the length of arrays.

Returns

- shuffled_arrays [sequence of indexable data-structures] Sequence of shuffled copies of the collections. The original arrays are not impacted.

See also:

- resample

Examples

It is possible to mix sparse and dense arrays in the same run:

```python
>>> X = np.array([[1., 0.], [2., 1.], [0., 0.]])
>>> y = np.array([0, 1, 2])
>>> from scipy.sparse import coo_matrix
>>> X_sparse = coo_matrix(X)
>>> from sklearn.utils import shuffle
>>> X, X_sparse, y = shuffle(X, X_sparse, y, random_state=0)
>>> X
```
array([[0., 0.],
       [2., 1.],
       [1., 0.]]))

>>> X_sparse
<3x2 sparse matrix of type '<... 'numpy.float64'>'
    with 3 stored elements in Compressed Sparse Row format>

>>> X_sparse.toarray()
array([[0., 0.],
       [2., 1.],
       [1., 0.]]))

>>> y
array([2, 1, 0])

>>> shuffle(y, n_samples=2, random_state=0)
array([0, 1])

Examples using `sklearn.utils.shuffle`

- Approximate nearest neighbors in TSNE

7.38.36 sklearn.utils.sparsefuncs.incr_mean_variance_axis

sklearn.utils.sparsefuncs.incr_mean_variance_axis(X, *, axis, last_mean, last_var, last_n, weights=None)

Compute incremental mean and variance along an axis on a CSR or CSC matrix.

last_mean, last_var are the statistics computed at the last step by this function. Both must be initialized to 0-
arrays of the proper size, i.e. the number of features in X. last_n is the number of samples encountered until
now.

Parameters

X [CSR or CSC sparse matrix of shape (n_samples, n_features)] Input data.
axis [{0, 1}] Axis along which the axis should be computed.
last_mean [ndarray of shape (n_features,) or (n_samples,), dtype=floating] Array of means to
    update with the new data X. Should be of shape (n_features,) if axis=0 or (n_samples,) if
    axis=1.
last_var [ndarray of shape (n_features,) or (n_samples,), dtype=floating] Array of variances to
    update with the new data X. Should be of shape (n_features,) if axis=0 or (n_samples,) if
    axis=1.
last_n [float or ndarray of shape (n_features,) or (n_samples,), dtype=floating] Sum of the
    weights seen so far, excluding the current weights. If not float, it should be of shape
    (n_samples,) if axis=0 or (n_features,) if axis=1. If float it corresponds to having same
    weights for all samples (or features).
weights [ndarray of shape (n_samples,) or (n_features,), default=None] If axis is set to 0 shape
    is (n_samples,) or if axis is set to 1 shape is (n_features,). If it is set to None, then samples
    are equally weighted.

New in version 0.24.
Returns

- **means** [ndarray of shape (n_features,) or (n_samples,), dtype=float32] Updated feature-wise means if axis = 0 or sample-wise means if axis = 1.
- **variances** [ndarray of shape (n_features,) or (n_samples,), dtype=float32] Updated feature-wise variances if axis = 0 or sample-wise variances if axis = 1.
- **n** [ndarray of shape (n_features,) or (n_samples,), dtype=int] Updated number of seen samples per feature if axis=0 or number of seen features per sample if axis=1.
  
  If weights is not None, n is a sum of the weights of the seen samples or features instead of the actual number of seen samples or features.

Notes

NaNs are ignored in the algorithm.

7.38.37 sklearn.utils.sparsefuncs.inplace_column_scale

**sklearn.utils.sparsefuncs.inplace_column_scale(X, scale)**

Inplace column scaling of a CSC/CSR matrix.

Scale each feature of the data matrix by multiplying with specific scale provided by the caller assuming a (n_samples, n_features) shape.

Parameters

- **X** [sparse matrix of shape (n_samples, n_features)] Matrix to normalize using the variance of the features. It should be of CSC or CSR format.
- **scale** [ndarray of shape (n_features,), dtype={np.float32, np.float64}] Array of precomputed feature-wise values to use for scaling.

7.38.38 sklearn.utils.sparsefuncs.inplace_row_scale

**sklearn.utils.sparsefuncs.inplace_row_scale(X, scale)**

Inplace row scaling of a CSR or CSC matrix.

Scale each row of the data matrix by multiplying with specific scale provided by the caller assuming a (n_samples, n_features) shape.

Parameters

- **X** [sparse matrix of shape (n_samples, n_features)] Matrix to be scaled. It should be of CSR or CSC format.
- **scale** [ndarray of shape (n_features,), dtype={np.float32, np.float64}] Array of precomputed sample-wise values to use for scaling.
7.38.39 sklearn.utils.sparsefuncs.inplace_swap_row

sklearn.utils.sparsefuncs.inplace_swap_row(X, m, n)
Swaps two rows of a CSC/CSR matrix in-place.

Parameters
X [sparse matrix of shape (n_samples, n_features)] Matrix whose two rows are to be swapped. It should be of CSR or CSC format.
m [int] Index of the row of X to be swapped.
n [int] Index of the row of X to be swapped.

7.38.40 sklearn.utils.sparsefuncs.inplace_swap_column

sklearn.utils.sparsefuncs.inplace_swap_column(X, m, n)
Swaps two columns of a CSC/CSR matrix in-place.

Parameters
X [sparse matrix of shape (n_samples, n_features)] Matrix whose two columns are to be swapped. It should be of CSR or CSC format.
m [int] Index of the column of X to be swapped.
n [int] Index of the column of X to be swapped.

7.38.41 sklearn.utils.sparsefuncs.mean_variance_axis

sklearn.utils.sparsefuncs.mean_variance_axis(X, axis, weights=None, return_sum_weights=False)
Compute mean and variance along an axis on a CSR or CSC matrix.

Parameters
X [sparse matrix of shape (n_samples, n_features)] Input data. It can be of CSR or CSC format.
axis [0, 1]] Axis along which the axis should be computed.
weights [ndarray of shape (n_samples,) or (n_features,), default=None] if axis is set to 0 shape is (n_samples,) or if axis is set to 1 shape is (n_features,). If it is set to None, then samples are equally weighted. New in version 0.24.
return_sum_weights [bool, default=False] If True, returns the sum of weights seen for each feature if axis=0 or each sample if axis=1. New in version 0.24.

Returns
variances [ndarray of shape (n_features,), dtype=floating] Feature-wise variances.
sum_weights [ndarray of shape (n_features,), dtype=floating] Returned if return_sum_weights is True.
7.38.42 sklearn.utils.sparsefuncs.inplace_csr_column_scale

sklearn.utils.sparsefuncs.inplace_csr_column_scale(X, scale)

Inplace column scaling of a CSR matrix.

Scale each feature of the data matrix by multiplying with specific scale provided by the caller assuming a (n_samples, n_features) shape.

Parameters

X [sparse matrix of shape (n_samples, n_features)] Matrix to normalize using the variance of the features. It should be of CSR format.

scale [ndarray of shape (n_features,), dtype={np.float32, np.float64}] Array of precomputed feature-wise values to use for scaling.

7.38.43 sklearn.utils.sparsefuncs_fast.inplace_csr_row_normalize_l1

sklearn.utils.sparsefuncs_fast.inplace_csr_row_normalize_l1()

Inplace row normalize using the l1 norm

7.38.44 sklearn.utils.sparsefuncs_fast.inplace_csr_row_normalize_l2

sklearn.utils.sparsefuncs_fast.inplace_csr_row_normalize_l2()

Inplace row normalize using the l2 norm

7.38.45 sklearn.utils.random.sample_without_replacement

sklearn.utils.random.sample_without_replacement()

Sample integers without replacement.

Select n_samples integers from the set [0, n_population) without replacement.

Parameters

n_population [int] The size of the set to sample from.

n_samples [int] The number of integer to sample.

random_state [int, RandomState instance or None, default=None] If int, random_state is the seed used by the random number generator; If RandomState instance, random_state is the random number generator; If None, the random number generator is the RandomState instance used by np.random.

method [{“auto”, “tracking_selection”, “reservoir_sampling”, “pool”}, default=’auto’] If method == “auto”, the ratio of n_samples / n_population is used to determine which algorithm to use: If ratio is between 0 and 0.01, tracking selection is used. If ratio is between 0.01 and 0.99, numpy.random.permutation is used. If ratio is greater than 0.99, reservoir sampling is used. The order of the selected integers is undefined. If a random order is desired, the selected subset should be shuffled.

If method ==”tracking_selection”, a set based implementation is used which is suitable for n_samples <<< n_population.

If method == “reservoir_sampling”, a reservoir sampling algorithm is used which is suitable for high memory constraint or when O(n_samples) ~ O(n_population). The order of
the selected integers is undefined. If a random order is desired, the selected subset should be shuffled.

If method == “pool”, a pool based algorithm is particularly fast, even faster than the tracking selection method. However, a vector containing the entire population has to be initialized.

If n_samples ~ n_population, the reservoir sampling method is faster.

Returns

out [ndarray of shape (n_samples,)] The sampled subsets of integer. The subset of selected integer might not be randomized, see the method argument.

7.38.46 sklearn.utils.validation.check_is_fitted

Check if the estimator is fitted by verifying the presence of fitted attributes (ending with a trailing underscore) and otherwise raises a NotFittedError with the given message.

This utility is meant to be used internally by estimators themselves, typically in their own predict / transform methods.

Parameters

estimator [estimator instance] estimator instance for which the check is performed.

attributes [str, list or tuple of str, default=None] Attribute name(s) given as string or a list/tuple of strings Eg.: ["coef_", "estimator_", ...], "coef_"

If None, estimator is considered fitted if there exist an attribute that ends with a underscore and does not start with double underscore.

msg [str, default=None] The default error message is, “This %(name)s instance is not fitted yet. Call ‘fit’ with appropriate arguments before using this estimator.”

For custom messages if “%(name)s” is present in the message string, it is substituted for the estimator name.

Eg. : “Estimator, %(name)s, must be fitted before sparsifying”.

all_or_any [callable, {all, any}, default=all] Specify whether all or any of the given attributes must exist.

Returns

None

Raises

NotFittedError If the attributes are not found.
7.38.47 sklearn.utils.validation.check_memory

sklearn.utils.validation.check_memory(memory)

Check that memory is joblib.Memory-like.

joblib.Memory-like means that memory can be converted into a joblib.Memory instance (typically a str denoting the location) or has the same interface (has a cache method).

Parameters

memory [None, str or object with the joblib.Memory interface]

Returns

memory [object with the joblib.Memory interface]

Raises

ValueError If memory is not joblib.Memory-like.

7.38.48 sklearn.utils.validation.check_symmetric

sklearn.utils.validation.check_symmetric(array, *, tol=1e-10, raise_warning=True, raise_exception=False)

Make sure that array is 2D, square and symmetric.

If the array is not symmetric, then a symmetrized version is returned. Optionally, a warning or exception is raised if the matrix is not symmetric.

Parameters

array [{ndarray, sparse matrix}] Input object to check / convert. Must be two-dimensional and square, otherwise a ValueError will be raised.


raise_warning [bool, default=True] If True then raise a warning if conversion is required.

raise_exception [bool, default=False] If True then raise an exception if array is not symmetric.

Returns

array_sym [{ndarray, sparse matrix}] Symmetrized version of the input array, i.e. the average of array and array.transpose(). If sparse, then duplicate entries are first summed and zeros are eliminated.

7.38.49 sklearn.utils.validation.column_or_1d

sklearn.utils.validation.column_or_1d(y, *, warn=False)

Ravel column or 1d numpy array, else raises an error.

Parameters

y [array-like]

warn [bool, default=False] To control display of warnings.

Returns

y [ndarray]
7.38.50 sklearn.utils.validation.has_fit_parameter

```python
sklearn.utils.validation.has_fit_parameter(estimator, parameter)
```

Checks whether the estimator’s fit method supports the given parameter.

**Parameters**

- **estimator** [object] An estimator to inspect.
- **parameter** [str] The searched parameter.

**Returns**

- **is_parameter**: bool Whether the parameter was found to be a named parameter of the estimator’s fit method.

**Examples**

```python
>>> from sklearn.svm import SVC
>>> has_fit_parameter(SVC(), "sample_weight")
True
```

7.38.51 sklearn.utils.all_estimators

```python
sklearn.utils.all_estimators(type_filter=None)
```

Get a list of all estimators from sklearn.

This function crawls the module and gets all classes that inherit from BaseEstimator. Classes that are defined in test-modules are not included.

**Parameters**

- **type_filter** [{"classifier", “regressor”, “cluster”, “transformer”} or list of such str, default=None] Which kind of estimators should be returned. If None, no filter is applied and all estimators are returned. Possible values are ‘classifier’, ‘regressor’, ‘cluster’ and ‘transformer’ to get estimators only of these specific types, or a list of these to get the estimators that fit at least one of the types.

**Returns**

- **estimators**: list of tuples List of (name, class), where name is the class name as string and class is the actual type of the class.

Utilities from joblib:

```python
utils.parallel_backend(backend[, n_jobs,...])
```

Change the default backend used by Parallel inside a with block.

```python
utils.register_parallel_backend(name, factory)
```

Register a new Parallel backend factory.
7.38.52 sklearn.utils.parallel_backend

sklearn.utils.parallel_backend (backend, n_jobs=-1, inner_max_num_threads=None, **backend_params)

Change the default backend used by Parallel inside a with block.

If backend is a string it must match a previously registered implementation using the register_parallel_backend function.

By default the following backends are available:

- ‘loky’: single-host, process-based parallelism (used by default),
- ‘threading’: single-host, thread-based parallelism,
- ‘multiprocessing’: legacy single-host, process-based parallelism.

‘loky’ is recommended to run functions that manipulate Python objects. ‘threading’ is a low-overhead alternative that is most efficient for functions that release the Global Interpreter Lock: e.g. I/O-bound code or CPU-bound code in a few calls to native code that explicitly releases the GIL.

In addition, if the dask and distributed Python packages are installed, it is possible to use the ‘dask’ backend for better scheduling of nested parallel calls without over-subscription and potentially distribute parallel calls over a networked cluster of several hosts.

It is also possible to use the distributed ‘ray’ backend for distributing the workload to a cluster of nodes. To use the ‘ray’ joblib backend add the following lines:

```python
>>> from ray.util.joblib import register_ray
>>> register_ray()
>>> with parallel_backend("ray"):
...     print(Parallel()(delayed(neg)(i + 1) for i in range(5)))
[-1, -2, -3, -4, -5]
```

Alternatively the backend can be passed directly as an instance.

By default all available workers will be used (n_jobs=-1) unless the caller passes an explicit value for the n_jobs parameter.

This is an alternative to passing a backend='backend_name' argument to the Parallel class constructor. It is particularly useful when calling into library code that uses joblib internally but does not expose the backend argument in its own API.

```python
>>> from operator import neg
>>> with parallel_backend('threading'):
...     print(Parallel()(delayed(neg)(i + 1) for i in range(5)))
...  
[-1, -2, -3, -4, -5]
```

Warning: this function is experimental and subject to change in a future version of joblib.

Joblib also tries to limit the oversubscription by limiting the number of threads usable in some third-party library threadpools like OpenBLAS, MKL or OpenMP. The default limit in each worker is set to `max(cpu_count() // effective_n_jobs, 1)` but this limit can be overwritten with the inner_max_num_threads argument which will be used to set this limit in the child processes.

New in version 0.10.
7.38.53 sklearn.utils.register_parallel_backend

`sklearn.utils.register_parallel_backend(name, factory, make_default=False)`

Register a new Parallel backend factory.

The new backend can then be selected by passing its name as the backend argument to the `Parallel` class. Moreover, the default backend can be overwritten globally by setting `make_default=True`.

The factory can be any callable that takes no argument and return an instance of `ParallelBackendBase`.

Warning: this function is experimental and subject to change in a future version of joblib.

New in version 0.10.

7.39 Recently deprecated

7.39.1 To be removed in 1.0 (renaming of 0.25)
8.1 Contributing

This project is a community effort, and everyone is welcome to contribute.

The project is hosted on https://github.com/scikit-learn/scikit-learn

The decision making process and governance structure of scikit-learn is laid out in the governance document: Scikit-learn governance and decision-making.

Scikit-learn is somewhat selective when it comes to adding new algorithms, and the best way to contribute and to help the project is to start working on known issues. See Issues for New Contributors to get started.

Our community, our values

We are a community based on openness and friendly, didactic, discussions.

We aspire to treat everybody equally, and value their contributions. We are particularly seeking people from under-represented backgrounds in Open Source Software and scikit-learn in particular to participate and contribute their expertise and experience.

Decisions are made based on technical merit and consensus.

Code is not the only way to help the project. Reviewing pull requests, answering questions to help others on mailing lists or issues, organizing and teaching tutorials, working on the website, improving the documentation, are all priceless contributions.

We abide by the principles of openness, respect, and consideration of others of the Python Software Foundation: https://www.python.org/psf/codeofconduct/

In case you experience issues using this package, do not hesitate to submit a ticket to the GitHub issue tracker. You are also welcome to post feature requests or pull requests.
8.1.1 Ways to contribute

There are many ways to contribute to scikit-learn, with the most common ones being contribution of code or documentation to the project. Improving the documentation is no less important than improving the library itself. If you find a typo in the documentation, or have made improvements, do not hesitate to send an email to the mailing list or preferably submit a GitHub pull request. Full documentation can be found under the doc/ directory.

But there are many other ways to help. In particular helping to improve, triage, and investigate issues and reviewing other developers’ pull requests are very valuable contributions that decrease the burden on the project maintainers.

Another way to contribute is to report issues you’re facing, and give a “thumbs up” on issues that others reported and that are relevant to you. It also helps us if you spread the word: reference the project from your blog and articles, link to it from your website, or simply star to say “I use it”:

In case a contribution/issue involves changes to the API principles or changes to dependencies or supported versions, it must be backed by a Enhancement proposals (SLEPs), where a SLEP must be submitted as a pull-request to enhancement proposals using the SLEP template and follows the decision-making process outlined in Scikit-learn governance and decision-making.

Contributing to related projects

Scikit-learn thrives in an ecosystem of several related projects, which also may have relevant issues to work on, including smaller projects such as:

- scikit-learn-contrib
- joblib
- sphinx-gallery
- numpydoc
- liac-arff

and larger projects:

- numpy
- scipy
- matplotlib
- and so on.

Look for issues marked “help wanted” or similar. Helping these projects may help Scikit-learn too. See also Related Projects.

8.1.2 Submitting a bug report or a feature request

We use GitHub issues to track all bugs and feature requests; feel free to open an issue if you have found a bug or wish to see a feature implemented.

In case you experience issues using this package, do not hesitate to submit a ticket to the Bug Tracker. You are also welcome to post feature requests or pull requests.

It is recommended to check that your issue complies with the following rules before submitting:

- Verify that your issue is not being currently addressed by other issues or pull requests.
- If you are submitting an algorithm or feature request, please verify that the algorithm fulfills our new algorithm requirements.
• If you are submitting a bug report, we strongly encourage you to follow the guidelines in *How to make a good bug report*.

**How to make a good bug report**

When you submit an issue to Github, please do your best to follow these guidelines! This will make it a lot easier to provide you with good feedback:

• The ideal bug report contains a **short reproducible code snippet**, this way anyone can try to reproduce the bug easily (see this for more details). If your snippet is longer than around 50 lines, please link to a gist or a github repo.

• If not feasible to include a reproducible snippet, please be specific about what **estimators and/or functions are involved and the shape of the data**.

• If an exception is raised, please **provide the full traceback**.

• Please include your **operating system type and version number**, as well as your **Python, scikit-learn, numpy, and scipy versions**. This information can be found by running the following code snippet:

```python
>>> import sklearn
>>> sklearn.show_versions()
```

**Note:** This utility function is only available in scikit-learn v0.20+. For previous versions, one has to explicitly run:

```python
import platform; print(platform.platform())
import sys; print("Python", sys.version)
import numpy; print("NumPy", numpy.__version__)
import scipy; print("SciPy", scipy.__version__)
import sklearn; print("Scikit-Learn", sklearn.__version__)
```

• Please ensure all **code snippets and error messages are formatted in appropriate code blocks**. See [Creating and highlighting code blocks](#) for more details.

If you want to help curate issues, read *the following*.

**8.1.3 Contributing code**

**Note:** To avoid duplicating work, it is highly advised that you search through the [issue tracker](#) and the [PR list](#). If in doubt about duplicated work, or if you want to work on a non-trivial feature, it’s recommended to first open an issue in the [issue tracker](#) to get some feedbacks from core developers.

One easy way to find an issue to work on is by applying the “help wanted” label in your search. This lists all the issues that have been unclaimed so far. In order to claim an issue for yourself, please comment exactly **take on it** for the CI to automatically assign the issue to you.
Video resources

These videos are step-by-step introductions on how to contribute to scikit-learn, and are a great companion to the following text guidelines. Please make sure to still check our guidelines below, since they describe our latest up-to-date workflow.

• Crash Course in Contributing to Scikit-Learn & Open Source Projects: Video, Transcript
• Example of Submitting a Pull Request to scikit-learn: Video, Transcript

How to contribute

The preferred way to contribute to scikit-learn is to fork the main repository on GitHub, then submit a “pull request” (PR).

In the first few steps, we explain how to locally install scikit-learn, and how to set up your git repository:

1. Create an account on GitHub if you do not already have one.
2. Fork the project repository: click on the ‘Fork’ button near the top of the page. This creates a copy of the code under your account on the GitHub user account. For more details on how to fork a repository see this guide.
3. Clone your fork of the scikit-learn repo from your GitHub account to your local disk:
   
   $ git clone git@github.com:YourLogin/scikit-learn.git  
   $ cd scikit-learn

4. Install the development dependencies:
   
   $ pip install cython pytest pytest-cov flake8 mypy

5. Install scikit-learn in editable mode:
   
   $ pip install --no-build-isolation --editable .
   
   If you receive errors in building scikit-learn, see the Building from source section.

6. Add the upstream remote. This saves a reference to the main scikit-learn repository, which you can use to keep your repository synchronized with the latest changes:
   
   $ git remote add upstream https://github.com/scikit-learn/scikit-learn.git

You should now have a working installation of scikit-learn, and your git repository properly configured. The next steps now describe the process of modifying code and submitting a PR:

7. Synchronize your master branch with the upstream master branch:
   
   $ git checkout master
   $ git pull upstream master

8. Create a feature branch to hold your development changes:
   
   $ git checkout -b my_feature

   and start making changes. Always use a feature branch. It’s good practice to never work on the master branch!

9. (Optional) Install pre-commit to run code style checks before each commit:
   
   $ pip install pre-commit
   $ pre-commit install

   pre-commit checks can be disabled for a particular commit with git commit -n.

10. Develop the feature on your feature branch on your computer, using Git to do the version control. When you’re done editing, add changed files using git add and then git commit:
$ git add modified_files
$ git commit

to record your changes in Git, then push the changes to your GitHub account with:

$ git push -u origin my_feature

11. Follow these instructions to create a pull request from your fork. This will send an email to the committers. You may want to consider sending an email to the mailing list for more visibility.

**Note:** If you are modifying a Cython module, you have to re-compile after modifications and before testing them:

$ pip install --no-build-isolation -e

Use the `--no-build-isolation` flag to avoid compiling the whole project each time, only the files you have modified.

It is often helpful to keep your local feature branch synchronized with the latest changes of the main scikit-learn repository:

$ git fetch upstream
$ git merge upstream/master

Subsequently, you might need to solve the conflicts. You can refer to the Git documentation related to resolving merge conflict using the command line.

---

**Learning git:**

The [Git documentation](https://git-scm.com) and [http://try.github.io](http://try.github.io) are excellent resources to get started with git, and understanding all of the commands shown here.

---

### Pull request checklist

Before a PR can be merged, it needs to be approved by two core developers. Please prefix the title of your pull request with `[MRG]` if the contribution is complete and should be subjected to a detailed review. An incomplete contribution – where you expect to do more work before receiving a full review – should be prefixed with `[WIP]` (to indicate a work in progress) and changed to `[MRG]` when it matures. WIPs may be useful to: indicate you are working on something to avoid duplicated work, request broad review of functionality or API, or seek collaborators. WIPs often benefit from the inclusion of a task list in the PR description.

In order to ease the reviewing process, we recommend that your contribution complies with the following rules before marking a PR as `[MRG]`. The **bolded** ones are especially important:

1. **Give your pull request a helpful title** that summarises what your contribution does. This title will often become the commit message once merged so it should summarise your contribution for posterity. In some cases “Fix <ISSUE TITLE>” is enough. “Fix #<ISSUE NUMBER>” is never a good title.

2. **Make sure your code passes the tests.** The whole test suite can be run with `pytest`, but it is usually not recommended since it takes a long time. It is often enough to only run the test related to your changes: for example, if you changed something in `sklearn/linear_model/logistic.py`, running the following commands will usually be enough:
   - `pytest sklearn/linear_model/logistic.py` to make sure the doctest examples are correct
   - `pytest sklearn/linear_model/tests/test_logistic.py` to run the tests specific to the file
   - `pytest sklearn/linear_model` to test the whole `linear_model` module

---

8.1. Contributing
• pytest doc/modules/linear_model.rst to make sure the user guide examples are correct.

• pytest sklearn/tests/test_common.py -k LogisticRegression to run all our estimator checks (specifically for LogisticRegression, if that’s the estimator you changed).

There may be other failing tests, but they will be caught by the CI so you don’t need to run the whole test suite locally. For guidelines on how to use pytest efficiently, see the Useful pytest aliases and flags.

3. Make sure your code is properly commented and documented, and make sure the documentation renders properly. To build the documentation, please refer to our Documentation guidelines. The CI will also build the docs: please refer to Generated documentation on CircleCI.

4. Tests are necessary for enhancements to be accepted. Bug-fixes or new features should be provided with non-regression tests. These tests verify the correct behavior of the fix or feature. In this manner, further modifications on the code base are granted to be consistent with the desired behavior. In the case of bug fixes, at the time of the PR, the non-regression tests should fail for the code base in the master branch and pass for the PR code.

5. Make sure that your PR does not add PEP8 violations. To check the code that you changed, you can run the following command (see above to set up the upstream remote):

$ git diff upstream/master -u -- "*.py" | flake8 --diff

or make flake8-diff which should work on unix-like system.

6. Follow the Coding guidelines.

7. When applicable, use the validation tools and scripts in the sklearn.utils submodule. A list of utility routines available for developers can be found in the Utilities for Developers page.

8. Often pull requests resolve one or more other issues (or pull requests). If merging your pull request means that some other issues/PRs should be closed, you should use keywords to create link to them (e.g., Fixes #1234; multiple issues/PRs are allowed as long as each one is preceded by a keyword). Upon merging, those issues/PRs will automatically be closed by GitHub. If your pull request is simply related to some other issues/PRs, create a link to them without using the keywords (e.g., See also #1234).

9. PRs should often substantiate the change, through benchmarks of performance and efficiency (see Monitoring performance) or through examples of usage. Examples also illustrate the features and intricacies of the library to users. Have a look at other examples in the examples/ directory for reference. Examples should demonstrate why the new functionality is useful in practice and, if possible, compare it to other methods available in scikit-learn.

10. New features often need to be illustrated with narrative documentation in the user guide, with small code snippets. If relevant, please also add references in the literature, with PDF links when possible.

11. The user guide should also include expected time and space complexity of the algorithm and scalability, e.g. “this algorithm can scale to a large number of samples > 100000, but does not scale in dimensionality: n_features is expected to be lower than 100”.

You can also check our Code Review Guidelines to get an idea of what reviewers will expect.

You can check for common programming errors with the following tools:

• Code with a good unittest coverage (at least 80%, better 100%), check with:

$ pip install pytest pytest-cov
$ pytest --cov sklearn path/to/tests_for_package

see also Testing and improving test coverage

Run static analysis with mypy:

$ mypy sklearn
must not produce new errors in your pull request. Using # type: ignore annotation can be a workaround for a few cases that are not supported by mypy, in particular,

- when importing C or Cython modules
- on properties with decorators

Bonus points for contributions that include a performance analysis with a benchmark script and profiling output (see Monitoring performance).

Also check out the How to optimize for speed guide for more details on profiling and Cython optimizations.

**Note:** The current state of the scikit-learn code base is not compliant with all of those guidelines, but we expect that enforcing those constraints on all new contributions will get the overall code base quality in the right direction.

**Note:** For two very well documented and more detailed guides on development workflow, please pay a visit to the Scipy Development Workflow - and the Astropy Workflow for Developers sections.

### Continuous Integration (CI)

- Azure pipelines are used for testing scikit-learn on Linux, Mac and Windows, with different dependencies and settings.

- CircleCI is used to build the docs for viewing, for linting with flake8, and for testing with PyPy on Linux

Please note that if one of the following markers appear in the latest commit message, the following actions are taken.

<table>
<thead>
<tr>
<th>Commit Marker</th>
<th>Message</th>
<th>Action Taken by CI</th>
</tr>
</thead>
<tbody>
<tr>
<td>[ci skip]</td>
<td></td>
<td>CI is skipped completely</td>
</tr>
<tr>
<td>[cd build]</td>
<td></td>
<td>CD is run (wheels and source distribution are built)</td>
</tr>
<tr>
<td>[lint skip]</td>
<td></td>
<td>Azure pipeline skips linting</td>
</tr>
<tr>
<td>[scipy-dev]</td>
<td></td>
<td>Add a Travis build with our dependencies (numpy, scipy, etc …) development builds</td>
</tr>
<tr>
<td>[icc-build]</td>
<td></td>
<td>Add a Travis build with the Intel C compiler (ICC)</td>
</tr>
<tr>
<td>[arm64]</td>
<td></td>
<td>Add a Travis build for the ARM64 / aarch64 little endian architecture</td>
</tr>
<tr>
<td>[doc skip]</td>
<td></td>
<td>Docs are not built</td>
</tr>
<tr>
<td>[doc quick]</td>
<td></td>
<td>Docs built, but excludes example gallery plots</td>
</tr>
<tr>
<td>[doc build]</td>
<td></td>
<td>Docs built including example gallery plots (very long)</td>
</tr>
</tbody>
</table>

Note that, by default, the documentation is built but only the examples that are directly modified by the pull request are executed.
Stalled pull requests

As contributing a feature can be a lengthy process, some pull requests appear inactive but unfinished. In such a case, taking them over is a great service for the project.

A good etiquette to take over is:

- **Determine if a PR is stalled**
  - A pull request may have the label “stalled” or “help wanted” if we have already identified it as a candidate for other contributors.
  - To decide whether an inactive PR is stalled, ask the contributor if she/he plans to continue working on the PR in the near future. Failure to respond within 2 weeks with an activity that moves the PR forward suggests that the PR is stalled and will result in tagging that PR with “help wanted”.
    
    Note that if a PR has received earlier comments on the contribution that have had no reply in a month, it is safe to assume that the PR is stalled and to shorten the wait time to one day.
    
    After a sprint, follow-up for un-merged PRs opened during sprint will be communicated to participants at the sprint, and those PRs will be tagged “sprint”. PRs tagged with “sprint” can be reassigned or declared stalled by sprint leaders.

- **Taking over a stalled PR**: To take over a PR, it is important to comment on the stalled PR that you are taking over and to link from the new PR to the old one. The new PR should be created by pulling from the old one.

Stalled and Unclaimed Issues

Generally speaking, issues which are up for grabs will have a “help wanted” tag. However, not all issues which need contributors will have this tag, as the “help wanted” tag is not always up-to-date with the state of the issue. Contributors can find issues which are still up for grabs using the following guidelines:

- **First, to determine if an issue is claimed:**
  - Check for linked pull requests
  - Check the conversation to see if anyone has said that they’re working on creating a pull request

- If a contributor comments on an issue to say they are working on it, a pull request is expected within 2 weeks (new contributor) or 4 weeks (contributor or core dev), unless an larger time frame is explicitly given. Beyond that time, another contributor can take the issue and make a pull request for it. We encourage contributors to comment directly on the stalled or unclaimed issue to let community members know that they will be working on it.

- If the issue is linked to a stalled pull request, we recommend that contributors follow the procedure described in the Stalled pull requests section rather than working directly on the issue.

Issues for New Contributors

New contributors should look for the following tags when looking for issues. We strongly recommend that new contributors tackle “easy” issues first: this helps the contributor become familiar with the contribution workflow, and for the core devs to become acquainted with the contributor; besides which, we frequently underestimate how easy an issue is to solve!
good first issue tag

A great way to start contributing to scikit-learn is to pick an item from the list of good first issues in the issue tracker. Resolving these issues allow you to start contributing to the project without much prior knowledge. If you have already contributed to scikit-learn, you should look at Easy issues instead.

Easy tag

If you have already contributed to scikit-learn, another great way to contribute to scikit-learn is to pick an item from the list of Easy issues in the issue tracker. Your assistance in this area will be greatly appreciated by the more experienced developers as it helps free up their time to concentrate on other issues.

help wanted tag

We often use the help wanted tag to mark issues regardless of difficulty. Additionally, we use the help wanted tag to mark Pull Requests which have been abandoned by their original contributor and are available for someone to pick up where the original contributor left off. The list of issues with the help wanted tag can be found here.

Note that not all issues which need contributors will have this tag.

8.1.4 Documentation

We are glad to accept any sort of documentation: function docstrings, reStructuredText documents (like this one), tutorials, etc. reStructuredText documents live in the source code repository under the doc/ directory.

You can edit the documentation using any text editor, and then generate the HTML output by typing make from the doc/ directory. Alternatively, make html may be used to generate the documentation with the example gallery (which takes quite some time). The resulting HTML files will be placed in _build/html/stable and are viewable in a web browser.

Building the documentation

First, make sure you have properly installed the development version.

Building the documentation requires installing some additional packages:

```bash
$ pip install sphinx sphinx-gallery numpydoc matplotlib Pillow pandas scikit-image packaging seaborn sphinx-prompt
```

To build the documentation, you need to be in the doc folder:

```bash
$ cd doc
```

In the vast majority of cases, you only need to generate the full web site, without the example gallery:

```bash
$ make
```

The documentation will be generated in the _build/html/stable directory. To also generate the example gallery you can use:

```bash
$ make html
```

This will run all the examples, which takes a while. If you only want to generate a few examples, you can use:

```bash
$ EXAMPLES_PATTERN=your_regex_goes_here make html
```
This is particularly useful if you are modifying a few examples.

Set the environment variable NO_MATHJAX=1 if you intend to view the documentation in an offline setting.

To build the PDF manual, run:

```
$ make latexpdf
```

---

**Warning: Sphinx version**

While we do our best to have the documentation build under as many versions of Sphinx as possible, the different versions tend to behave slightly differently. To get the best results, you should use the same version as the one we used on CircleCI. Look at this [github search](https://github.com) to know the exact version.

---

**Guidelines for writing documentation**

It is important to keep a good compromise between mathematical and algorithmic details, and give intuition to the reader on what the algorithm does.

Basically, to elaborate on the above, it is best to always start with a small paragraph with a hand-waving explanation of what the method does to the data. Then, it is very helpful to point out why the feature is useful and when it should be used - the latter also including “big O” \( O(g(n)) \) complexities of the algorithm, as opposed to just rules of thumb, as the latter can be very machine-dependent. If those complexities are not available, then rules of thumb may be provided instead.

Secondly, a generated figure from an example (as mentioned in the previous paragraph) should then be included to further provide some intuition.

Next, one or two small code examples to show its use can be added.

Next, any math and equations, followed by references, can be added to further the documentation. Not starting the documentation with the maths makes it more friendly towards users that are just interested in what the feature will do, as opposed to how it works “under the hood”.

Finally, follow the formatting rules below to make it consistently good:

- Add “See Also” in docstrings for related classes/functions.
- “See Also” in docstrings should be one line per reference, with a colon and an explanation, for example:

```
See Also
--------
SelectKBest : Select features based on the k highest scores.
SelectFpr : Select features based on a false positive rate test.
```

- When documenting the parameters and attributes, here is a list of some well-formatted examples:

```
array_parameter : {array-like, sparse matrix} of shape (n_samples, n_features) or
\( \rightarrow (n_samples,) \)
    This parameter accepts data in either of the mentioned forms, with one
```

(continues on next page)
of the mentioned shapes. The default value is `np.ones(shape=(n_samples,))`.

<table>
<thead>
<tr>
<th>list_param</th>
<th>list of int</th>
</tr>
</thead>
<tbody>
<tr>
<td>typed_ndarray</td>
<td>ndarray of shape (n_samples,), dtype=np.int32</td>
</tr>
<tr>
<td>sample_weight</td>
<td>array-like of shape (n_samples,), default=None</td>
</tr>
</tbody>
</table>

In general have the following in mind:

1. Use Python basic types. (`bool` instead of `boolean`)
2. Use parenthesis for defining shapes: `array-like of shape (n_samples,)` or `array-like of shape (n_samples, n_features)`
3. For strings with multiple options, use brackets: `input: {'log', 'squared', 'multinomial'}`
4. 1D or 2D data can be a subset of `{array-like, ndarray, sparse matrix, dataframe}. Note that `array-like` can also be a `list`, while `ndarray` is explicitly only a `numpy.ndarray`.
5. Specify `dataframe` when “frame-like” features are being used, such as the column names.
6. When specifying the data type of a list, use `of` as a delimiter: `list of int`.
7. When specifying the dtype of an `ndarray`, use e.g. `dtype=np.int32` after defining the shape: `ndarray of shape (n_samples,), dtype=np.int32`.
8. When the default is `None`, `None` only needs to be specified at the end with `default=None`. Be sure to include in the docstring, what it means for the parameter or attribute to be `None`.

- For unwritten formatting rules, try to follow existing good works:
  - For “References” in docstrings, see the Silhouette Coefficient (`sklearn.metrics.silhouette_score`).
- When editing reStructuredText (.rst) files, try to keep line length under 80 characters when possible (exceptions include links and tables).
- Do not modify sphinx labels as this would break existing cross references and external links pointing to specific sections in the scikit-learn documentation.
- Before submitting your pull request check if your modifications have introduced new sphinx warnings and try to fix them.

**Generated documentation on CircleCI**

When you change the documentation in a pull request, CircleCI automatically builds it. To view the documentation generated by CircleCI, simply go at the bottom of your PR page and look for the “ci/circleci: doc artifact” link.
8.1.5 Testing and improving test coverage

High-quality unit testing is a corner-stone of the scikit-learn development process. For this purpose, we use the pytest package. The tests are functions appropriately named, located in tests subdirectories, that check the validity of the algorithms and the different options of the code.

Running pytest in a folder will run all the tests of the corresponding subpackages. For a more detailed pytest workflow, please refer to the Pull request checklist.

We expect code coverage of new features to be at least around 90%.

Writing matplotlib related tests

Test fixtures ensure that a set of tests will be executing with the appropriate initialization and cleanup. The scikit-learn test suite implements a fixture which can be used with matplotlib.

```python
pyplot
```
The `pyplot` fixture should be used when a test function is dealing with matplotlib. matplotlib is a soft dependency and is not required. This fixture is in charge of skipping the tests if matplotlib is not installed. In addition, figures created during the tests will be automatically closed once the test function has been executed.

To use this fixture in a test function, one needs to pass it as an argument:

```python
def test_requiring_mpl_fixture(pyplot):
    # you can now safely use matplotlib
```

Workflow to improve test coverage

To test code coverage, you need to install the coverage package in addition to pytest.

1. Run `make test-coverage`. The output lists for each file the line numbers that are not tested.
2. Find a low hanging fruit, looking at which lines are not tested, write or adapt a test specifically for these lines.
3. Loop.

8.1.6 Monitoring performance

This section is heavily inspired from the pandas documentation.

When proposing changes to the existing code base, it's important to make sure that they don't introduce performance regressions. Scikit-learn uses asv benchmarks to monitor the performance of a selection of common estimators and functions. The benchmark suite can be found in the scikit-learn/asv_benchmarks directory.

To use all features of asv, you will need either conda or virtualenv. For more details please check the asv installation webpage.

First of all you need to install the development version of asv:

```bash
$ pip install git+https://github.com/airspeed-velocity/asv
```

and change your directory to asv_benchmarks/:

```bash
$ cd asv_benchmarks/
```

The benchmark suite is configured to run against your local clone of scikit-learn. Make sure it is up to date:

```bash
$ git fetch upstream
```
In the benchmark suite, the benchmarks are organized following the same structure as scikit-learn. For example, you can compare the performance of a specific estimator between upstream/master and the branch you are working on:

```bash
$ asv continuous -b LogisticRegression upstream/master HEAD
```

The command uses conda by default for creating the benchmark environments. If you want to use virtualenv instead, use the `-E` flag:

```bash
$ asv continuous -E virtualenv -b LogisticRegression upstream/master HEAD
```

You can also specify a whole module to benchmark:

```bash
$ asv continuous -b linear_model upstream/master HEAD
```

You can replace `HEAD` by any local branch. By default it will only report the benchmarks that have change by at least 10%. You can control this ratio with the `-f` flag.

To run the full benchmark suite, simply remove the `-b` flag:

```bash
$ asv continuous upstream/master HEAD
```

However this can take up to two hours. The `-b` flag also accepts a regular expression for a more complex subset of benchmarks to run.

To run the benchmarks without comparing to another branch, use the `run` command:

```bash
$ asv run -b linear_model HEAD^!
```

You can also run the benchmark suite using the version of scikit-learn already installed in your current Python environment:

```bash
$ asv run --python=same
```

It’s particulary useful when you installed scikit-learn in editable mode to avoid creating a new environment each time you run the benchmarks. By default the results are not saved when using an existing installation. To save the results you must specify a commit hash:

```bash
$ asv run --python=same --set-commit-hash=<commit hash>
```

Benchmarks are saved and organized by machine, environment and commit. To see the list of all saved benchmarks:

```bash
$ asv show
```

and to see the report of a specific run:

```bash
$ asv show <commit hash>
```

When running benchmarks for a pull request you’re working on please report the results on github.

The benchmark suite supports additional configurable options which can be set in the `benchmarks/config.json` configuration file. For example, the benchmarks can run for a provided list of values for the `n_jobs` parameter.

More information on how to write a benchmark and how to use asv can be found in the `asv` documentation.

### 8.1.7 Issue Tracker Tags

All issues and pull requests on the GitHub issue tracker should have (at least) one of the following tags:

- **Bug / Crash** Something is happening that clearly shouldn’t happen. Wrong results as well as unexpected errors from estimators go here.
- **Cleanup / Enhancement** Improving performance, usability, consistency.
- **Documentation** Missing, incorrect or sub-standard documentations and examples.
- **New Feature** Feature requests and pull requests implementing a new feature.

---

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There are four other tags to help new contributors:

**good first issue**  This issue is ideal for a first contribution to scikit-learn. Ask for help if the formulation is unclear. If you have already contributed to scikit-learn, look at Easy issues instead.

**Easy**  This issue can be tackled without much prior experience.

**Moderate**  Might need some knowledge of machine learning or the package, but is still approachable for someone new to the project.

**help wanted**  This tag marks an issue which currently lacks a contributor or a PR that needs another contributor to take over the work. These issues can range in difficulty, and may not be approachable for new contributors. Note that not all issues which need contributors will have this tag.

### 8.1.8 Maintaining backwards compatibility

#### Deprecation

If any publicly accessible method, function, attribute or parameter is renamed, we still support the old one for two releases and issue a deprecation warning when it is called/passed/accessed. E.g., if the function `zero_one` is renamed to `zero_one_loss`, we add the decorator `deprecated` from `sklearn.utils` to `zero_one` and call `zero_one_loss` from that function:

```python
from ..utils import deprecated
def zero_one_loss(y_true, y_pred, normalize=True):
    # actual implementation
    pass
@deprecated("Function 'zero_one' was renamed to 'zero_one_loss' in version 0.13 and will be removed in release 0.15. "
            "Default behavior is changed from 'normalize=False' to "
            "'normalize=True'")
def zero_one(y_true, y_pred, normalize=False):
    return zero_one_loss(y_true, y_pred, normalize)
```

If an attribute is to be deprecated, use the decorator `deprecated` on a property. Please note that the `property` decorator should be placed before the `deprecated` decorator for the docstrings to be rendered properly. E.g., renaming an attribute `labels_` to `classes_` can be done as:

```python
@deprecated("Attribute labels_ was deprecated in version 0.13 and "
            "will be removed in 0.15. Use 'classes_' instead")
@property
def labels_(self):
    return self.classes_
```

If a parameter has to be deprecated, a `FutureWarning` warning must be raised too. In the following example, `k` is deprecated and renamed to `n_clusters`:

```python
import warnings
def example_function(n_clusters=8, k='deprecated'):
    if k != 'deprecated':
        warnings.warn("'k' was renamed to n_clusters in version 0.13 and "
                      "will be removed in 0.15.",
                      FutureWarning)
    n_clusters = k
```
scikit-learn user guide, Release 0.24.0

When the change is in a class, we validate and raise warning in fit:
import warnings
class ExampleEstimator(BaseEstimator):
def __init__(self, n_clusters=8, k='deprecated'):
self.n_clusters = n_clusters
self.k = k
def fit(self, X, y):
if self.k != 'deprecated':
warnings.warn("'k' was renamed to n_clusters in version 0.13 and "
"will be removed in 0.15.",
FutureWarning)
self._n_clusters = self.k
else:
self._n_clusters = self.n_clusters

As in these examples, the warning message should always give both the version in which the deprecation happened
and the version in which the old behavior will be removed. If the deprecation happened in version 0.x-dev, the message
should say deprecation occurred in version 0.x and the removal will be in 0.(x+2), so that users will have enough time
to adapt their code to the new behaviour. For example, if the deprecation happened in version 0.18-dev, the message
should say it happened in version 0.18 and the old behavior will be removed in version 0.20.
In addition, a deprecation note should be added in the docstring, recalling the same information as the deprecation
warning as explained above. Use the .. deprecated:: directive:
.. deprecated:: 0.13
``k`` was renamed to ``n_clusters`` in version 0.13 and will be removed
in 0.15.

What’s more, a deprecation requires a test which ensures that the warning is raised in relevant cases but not in other
cases. The warning should be caught in all other tests (using e.g., @pytest.mark.filterwarnings), and there
should be no warning in the examples.
Change the default value of a parameter
If the default value of a parameter needs to be changed, please replace the default value with a specific value (e.g.,
warn) and raise FutureWarning when users are using the default value. In the following example, we change the
default value of n_clusters from 5 to 10 (current version is 0.20):
import warnings
def example_function(n_clusters='warn'):
if n_clusters == 'warn':
warnings.warn("The default value of n_clusters will change from "
"5 to 10 in 0.22.", FutureWarning)
n_clusters = 5

When the change is in a class, we validate and raise warning in fit:
import warnings
class ExampleEstimator:
def __init__(self, n_clusters='warn'):
self.n_clusters = n_clusters
(continues on next page)

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def fit(self, X, y):
    if self.n_clusters == 'warn':
        warnings.warn("The default value of n_clusters will change from "
                      "5 to 10 in 0.22.", FutureWarning)
    self._n_clusters = 5

Similar to deprecations, the warning message should always give both the version in which the change happened and
the version in which the old behavior will be removed. The docstring needs to be updated accordingly. We need a test
which ensures that the warning is raised in relevant cases but not in other cases. The warning should be caught in all
other tests (using e.g., @pytest.mark.filterwarnings), and there should be no warning in the examples.

### 8.1.9 Code Review Guidelines

Reviewing code contributed to the project as PRs is a crucial component of scikit-learn development. We encourage
anyone to start reviewing code of other developers. The code review process is often highly educational for everybody
involved. This is particularly appropriate if it is a feature you would like to use, and so can respond critically about
whether the PR meets your needs. While each pull request needs to be signed off by two core developers, you can
speed up this process by providing your feedback.

Here are a few important aspects that need to be covered in any code review, from high-level questions to a more
detailed check-list.

- Do we want this in the library? Is it likely to be used? Do you, as a scikit-learn user, like the change and intend
to use it? Is it in the scope of scikit-learn? Will the cost of maintaining a new feature be worth its benefits?
- Is the code consistent with the API of scikit-learn? Are public functions/classes/parameters well named and
  intuitively designed?
- Are all public functions/classes and their parameters, return types, and stored attributes named according to
  scikit-learn conventions and documented clearly?
- Is any new functionality described in the user-guide and illustrated with examples?
- Is every public function/class tested? Are a reasonable set of parameters, their values, value types, and combi-
nations tested? Do the tests validate that the code is correct, i.e. doing what the documentation says it does? If
  the change is a bug-fix, is a non-regression test included? Look at this to get started with testing in Python.
- Do the tests pass in the continuous integration build? If appropriate, help the contributor understand why tests
  failed.
- Do the tests cover every line of code (see the coverage report in the build log)? If not, are the lines missing
  coverage good exceptions?
- Is the code easy to read and low on redundancy? Should variable names be improved for clarity or consistency?
  Should comments be added? Should comments be removed as unhelpful or extraneous?
- Could the code easily be rewritten to run much more efficiently for relevant settings?
- Is the code backwards compatible with previous versions? (or is a deprecation cycle necessary?)
- Will the new code add any dependencies on other libraries? (this is unlikely to be accepted)
- Does the documentation render properly (see the Documentation section for more details), and are the plots
  instructive?

*Standard replies for reviewing* includes some frequent comments that reviewers may make.
8.1.10 Reading the existing code base

Reading and digesting an existing code base is always a difficult exercise that takes time and experience to master. Even though we try to write simple code in general, understanding the code can seem overwhelming at first, given the sheer size of the project. Here is a list of tips that may help make this task easier and faster (in no particular order).

- Get acquainted with the APIs of scikit-learn objects: understand what `fit`, `predict`, `transform`, etc. are used for.
- Before diving into reading the code of a function / class, go through the docstrings first and try to get an idea of what each parameter / attribute is doing. It may also help to stop a minute and think how would I do this myself if I had to?
- The trickiest thing is often to identify which portions of the code are relevant, and which are not. In scikit-learn a lot of input checking is performed, especially at the beginning of the `fit` methods. Sometimes, only a very small portion of the code is doing the actual job. For example looking at the `fit()` method of `LinearRegression`, what you’re looking for might just be the call the `scipy.linalg.lstsq`, but it is buried into multiple lines of input checking and the handling of different kinds of parameters.
- Due to the use of Inheritance, some methods may be implemented in parent classes. All estimators inherit at least from `BaseEstimator`, and from a `Mixin` class (e.g. `ClassifierMixin`) that enables default behaviour depending on the nature of the estimator (classifier, regressor, transformer, etc.).
- Sometimes, reading the tests for a given function will give you an idea of what its intended purpose is. You can use `git grep` (see below) to find all the tests written for a function. Most tests for a specific function/class are placed under the `tests/` folder of the module
- You’ll often see code looking like this: `out = Parallel(...) (delayed(some_function)(param) for param in some_iterable)`. This runs `some_function` in parallel using `Joblib`. `out` is then an iterable containing the values returned by `some_function` for each call.
- We use Cython to write fast code. Cython code is located in `.pyx` and `.pxd` files. Cython code has a more C-like flavor: we use pointers, perform manual memory allocation, etc. Having some minimal experience in C / C++ is pretty much mandatory here.
- Master your tools.
  - With such a big project, being efficient with your favorite editor or IDE goes a long way towards digesting the code base. Being able to quickly jump (or `peek`) to a function/class/attribute definition helps a lot. So does being able to quickly see where a given name is used in a file.
  - `git` also has some built-in killer features. It is often useful to understand how a file changed over time, using e.g. `git blame` (manual). This can also be done directly on GitHub. `git grep` (examples) is also extremely useful to see every occurrence of a pattern (e.g. a function call or a variable) in the code base.

8.2 Developing scikit-learn estimators

Whether you are proposing an estimator for inclusion in scikit-learn, developing a separate package compatible with scikit-learn, or implementing custom components for your own projects, this chapter details how to develop objects that safely interact with scikit-learn Pipelines and model selection tools.
8.2.1 APIs of scikit-learn objects

To have a uniform API, we try to have a common basic API for all the objects. In addition, to avoid the proliferation of framework code, we try to adopt simple conventions and limit to a minimum the number of methods an object must implement.

Elements of the scikit-learn API are described more definitively in the *Glossary of Common Terms and API Elements*.

**Different objects**

The main objects in scikit-learn are (one class can implement multiple interfaces):

**Estimator** The base object, implements a `fit` method to learn from data, either:

```python
estimator = estimator.fit(data, targets)
```

or:

```python
estimator = estimator.fit(data)
```

**Predictor** For supervised learning, or some unsupervised problems, implements:

```python
prediction = predictor.predict(data)
```

Classification algorithms usually also offer a way to quantify certainty of a prediction, either using `decision_function` or `predict_proba`:

```python
probability = predictor.predict_proba(data)
```

**Transformer** For filtering or modifying the data, in a supervised or unsupervised way, implements:

```python
new_data = transformer.transform(data)
```

When fitting and transforming can be performed much more efficiently together than separately, implements:

```python
new_data = transformer.fit_transform(data)
```

**Model** A model that can give a goodness of fit measure or a likelihood of unseen data, implements (higher is better):

```python
score = model.score(data)
```

**Estimators**

The API has one predominant object: the estimator. An estimator is an object that fits a model based on some training data and is capable of inferring some properties on new data. It can be, for instance, a classifier or a regressor. All estimators implement the fit method:

```python
estimator.fit(X, y)
```

All built-in estimators also have a `set_params` method, which sets data-independent parameters (overriding previous parameter values passed to `__init__`).

All estimators in the main scikit-learn codebase should inherit from `sklearn.base.BaseEstimator`. 

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Instantiation

This concerns the creation of an object. The object’s `__init__` method might accept constants as arguments that determine the estimator’s behavior (like the C constant in SVMs). It should not, however, take the actual training data as an argument, as this is left to the `fit()` method:

```python
clf2 = SVC(C=2.3)
clf3 = SVC([[1, 2], [2, 3]], [-1, 1]) # WRONG!
```

The arguments accepted by `__init__` should all be keyword arguments with a default value. In other words, a user should be able to instantiate an estimator without passing any arguments to it. The arguments should all correspond to hyperparameters describing the model or the optimisation problem the estimator tries to solve. These initial arguments (or parameters) are always remembered by the estimator. Also note that they should not be documented under the “Attributes” section, but rather under the “Parameters” section for that estimator.

In addition, **every keyword argument accepted by `__init__` should correspond to an attribute on the instance.** Scikit-learn relies on this to find the relevant attributes to set on an estimator when doing model selection.

To summarize, an `__init__` should look like:

```python
def __init__(self, param1=1, param2=2):
    self.param1 = param1
    self.param2 = param2
```

There should be no logic, not even input validation, and the parameters should not be changed. The corresponding logic should be put where the parameters are used, typically in `fit`. The following is wrong:

```python
def __init__(self, param1=1, param2=2, param3=3):
    # WRONG: parameters should not be modified
    if param1 > 1:
        param2 += 1
    self.param1 = param1
    # WRONG: the object’s attributes should have exactly the name of
    # the argument in the constructor
    self.param3 = param2
```

The reason for postponing the validation is that the same validation would have to be performed in `set_params`, which is used in algorithms like `GridSearchCV`.

Fitting

The next thing you will probably want to do is to estimate some parameters in the model. This is implemented in the `fit()` method.

The `fit()` method takes the training data as arguments, which can be one array in the case of unsupervised learning, or two arrays in the case of supervised learning.

Note that the model is fitted using `X` and `y`, but the object holds no reference to `X` and `y`. There are, however, some exceptions to this, as in the case of precomputed kernels where this data must be stored for use by the predict method.

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>array-like of shape (n_samples, n_features)</td>
</tr>
<tr>
<td>y</td>
<td>array-like of shape (n_samples,)</td>
</tr>
<tr>
<td>kwargs</td>
<td>optional data-dependent parameters</td>
</tr>
</tbody>
</table>
X.shape[0] should be the same as y.shape[0]. If this requisite is not met, an exception of type ValueError should be raised.

y might be ignored in the case of unsupervised learning. However, to make it possible to use the estimator as part of a pipeline that can mix both supervised and unsupervised transformers, even unsupervised estimators need to accept a y=None keyword argument in the second position that is just ignored by the estimator. For the same reason, fit_predict, fit_transform, score and partial_fit methods need to accept a y argument in the second place if they are implemented.

The method should return the object (self). This pattern is useful to be able to implement quick one liners in an IPython session such as:

```python
y_predicted = SVC(C=100).fit(X_train, y_train).predict(X_test)
```

Depending on the nature of the algorithm, fit can sometimes also accept additional keywords arguments. However, any parameter that can have a value assigned prior to having access to the data should be an __init__ keyword argument. fit parameters should be restricted to directly data dependent variables. For instance a Gram matrix or an affinity matrix which are precomputed from the data matrix X are data dependent. A tolerance stopping criterion tol is not directly data dependent (although the optimal value according to some scoring function probably is).

When fit is called, any previous call to fit should be ignored. In general, calling estimator.fit(X1) and then estimator.fit(X2) should be the same as only calling estimator.fit(X2). However, this may not be true in practice when fit depends on some random process, see random_state. Another exception to this rule is when the hyper-parameter warm_start is set to True for estimators that support it. warm_start=True means that the previous state of the trainable parameters of the estimator are reused instead of using the default initialization strategy.

**Estimated Attributes**

Attributes that have been estimated from the data must always have a name ending with trailing underscore, for example the coefficients of some regression estimator would be stored in a coef_ attribute after fit has been called.

The estimated attributes are expected to be overridden when you call fit a second time.

**Optional Arguments**

In iterative algorithms, the number of iterations should be specified by an integer called n_iter.

**Pairwise Attributes**

An estimator that accepts X of shape (n_samples, n_samples) and defines a _pairwise property equal to True allows for cross-validation of the dataset, e.g. when X is a precomputed kernel matrix. Specifically, the _pairwise property is used by utils.metaestimators._safe_split to slice rows and columns.

Deprecated since version 0.24: The _pairwise attribute is deprecated in 0.24. From 1.1 (renaming of 0.26) onward, the pairwise estimator tag should be used instead.
Universal attributes

Estimators that expect tabular input should set a `n_features_in_` attribute at `fit` time to indicate the number of features that the estimator expects for subsequent calls to `predict` or `transform`. See SLEP010 for details.

8.2.2 Rolling your own estimator

If you want to implement a new estimator that is scikit-learn-compatible, whether it is just for you or for contributing it to scikit-learn, there are several internals of scikit-learn that you should be aware of in addition to the scikit-learn API outlined above. You can check whether your estimator adheres to the scikit-learn interface and standards by running `check_estimator` on an instance. The `parametrize_with_checks` pytest decorator can also be used (see its docstring for details and possible interactions with pytest):

```python
>>> from sklearn.utils.estimator_checks import check_estimator
>>> from sklearn.svm import LinearSVC

>>> check_estimator(LinearSVC())  # passes
```

The main motivation to make a class compatible to the scikit-learn estimator interface might be that you want to use it together with model evaluation and selection tools such as `model_selection.GridSearchCV` and `pipeline.Pipeline`.

Before detailing the required interface below, we describe two ways to achieve the correct interface more easily.

Project template:

We provide a project template which helps in the creation of Python packages containing scikit-learn compatible estimators. It provides:

- an initial git repository with Python package directory structure
- a template of a scikit-learn estimator
- an initial test suite including use of `check_estimator`
- directory structures and scripts to compile documentation and example galleries
- scripts to manage continuous integration (testing on Linux and Windows)
- instructions from getting started to publishing on PyPi

BaseEstimator and mixins:

We tend to use “duck typing”, so building an estimator which follows the API suffices for compatibility, without needing to inherit from or even import any scikit-learn classes.

However, if a dependency on scikit-learn is acceptable in your code, you can prevent a lot of boilerplate code by deriving a class from `BaseEstimator` and optionally the mixin classes in `sklearn.base`. For example, below is a custom classifier, with more examples included in the scikit-learn-contrib project template.

```python
>>> import numpy as np

>>> from sklearn.base import BaseEstimator, ClassifierMixin

>>> from sklearn.utils.validation import check_X_y, check_array, check_is_fitted

>>> from sklearn.metrics import euclidean_distances

>>> class TemplateClassifier(BaseEstimator, ClassifierMixin):
...  ...
```
... def __init__(self, demo_param='demo'):
...     self.demo_param = demo_param
...
... def fit(self, X, y):
...     # Check that X and y have correct shape
...     X, y = check_X_y(X, y)
...     # Store the classes seen during fit
...     self.classes_ = unique_labels(y)
...     self.X_ = X
...     self.y_ = y
...     # Return the classifier
...     return self
...
... def predict(self, X):
...     # Check is fit had been called
...     check_is_fitted(self)
...     # Input validation
...     X = check_array(X)
...     closest = np.argmin(euclidean_distances(X, self.X_), axis=1)
...     return self.y_[closest]

get_params and set_params

All scikit-learn estimators have get_params and set_params functions. The get_params function takes no arguments and returns a dict of the __init__ parameters of the estimator, together with their values.

It must take one keyword argument, deep, which receives a boolean value that determines whether the method should return the parameters of sub-estimators (for most estimators, this can be ignored). The default value for deep should be True. For instance considering the following estimator:

```python
>>> from sklearn.base import BaseEstimator
>>> from sklearn.linear_model import LogisticRegression
>>> class MyEstimator(BaseEstimator):
...     def __init__(self, subestimator=None, my_extra_param="random"):
...         self.subestimator = subestimator
...         self.my_extra_param = my_extra_param
```

The parameter deep will control whether or not the parameters of the subestimator should be reported. Thus when deep=True, the output will be:

```python
>>> my_estimator = MyEstimator(subestimator=LogisticRegression())
>>> for param, value in my_estimator.get_params(deep=True).items():
...     print(f"{param} -> {value}")
my_extra_param -> random
subestimator__C -> 1.0
subestimator__class_weight -> None
subestimator__dual -> False
subestimator__fit_intercept -> True
subestimator__intercept_scaling -> 1
subestimator__l1_ratio -> None
```
subestimator__max_iter -> 100
subestimator__multi_class -> auto
subestimator__n_jobs -> None
subestimator__penalty -> l2
subestimator__random_state -> None
subestimator__solver -> lbfgs
subestimator__tol -> 0.0001
subestimator__verbose -> 0
subestimator__warm_start -> False
subestimator -> LogisticRegression()

Often, the subestimator has a name (as e.g. named steps in a Pipeline object), in which case the key should become <name>__C, <name>__class_weight, etc.

While when deep=False, the output will be:

```python
>>> for param, value in my_estimator.get_params(deep=False).items():
...     print(f"{param} -> {value}")
my_extra_param -> random
subestimator -> LogisticRegression()
```

The set_params on the other hand takes as input a dict of the form 'parameter': value and sets the parameter of the estimator using this dict. Return value must be estimator itself.

While the get_params mechanism is not essential (see Cloning below), the set_params function is necessary as it is used to set parameters during grid searches.

The easiest way to implement these functions, and to get a sensible __repr__ method, is to inherit from sklearn.base.BaseEstimator. If you do not want to make your code dependent on scikit-learn, the easiest way to implement the interface is:

```python
def get_params(self, deep=True):
    # suppose this estimator has parameters "alpha" and "recursive"
    return {"alpha": self.alpha, "recursive": self.recursive}

def set_params(self, **parameters):
    for parameter, value in parameters.items():
        setattr(self, parameter, value)
    return self
```

Parameters and init

As model_selection.GridSearchCV uses set_params to apply parameter setting to estimators, it is essential that calling set_params has the same effect as setting parameters using the __init__ method. The easiest and recommended way to accomplish this is to not do any parameter validation in __init__. All logic behind estimator parameters, like translating string arguments into functions, should be done in fit.

Also it is expected that parameters with trailing _ are not to be set inside the __init__ method. All and only the public attributes set by fit have a trailing _. As a result the existence of parameters with trailing _ is used to check if the estimator has been fitted.
Cloning

For use with the `model_selection` module, an estimator must support the `base.clone` function to replicate an estimator. This can be done by providing a `get_params` method. If `get_params` is present, then `clone(estimator)` will be an instance of `type(estimator)` on which `set_params` has been called with clones of the result of `estimator.get_params()`.

Objects that do not provide this method will be deep-copied (using the Python standard function `copy.deepcopy`) if `safe=False` is passed to `clone`.

Pipeline compatibility

For an estimator to be usable together with `pipeline.Pipeline` in any but the last step, it needs to provide a `fit` or `fit_transform` function. To be able to evaluate the pipeline on any data but the training set, it also needs to provide a `transform` function. There are no special requirements for the last step in a pipeline, except that it has a `fit` function. All `fit` and `fit_transform` functions must take arguments `X`, `y`, even if `y` is not used. Similarly, for `score` to be usable, the last step of the pipeline needs to have a `score` function that accepts an optional `y`.

Estimator types

Some common functionality depends on the kind of estimator passed. For example, cross-validation in `model_selection.GridSearchCV` and `model_selection.cross_val_score` defaults to being stratified when used on a classifier, but not otherwise. Similarly, scorers for average precision that take a continuous prediction need to call `decision_function` for classifiers, but `predict` for regressors. This distinction between classifiers and regressors is implemented using the `_estimator_type` attribute, which takes a string value. It should be "classifier" for classifiers and "regressor" for regressors and "clusterer" for clustering methods, to work as expected. Inheriting from `ClassifierMixin`, `RegressorMixin` or `ClusterMixin` will set the attribute automatically. When a meta-estimator needs to distinguish among estimator types, instead of checking `_estimator_type` directly, helpers like `base.is_classifier` should be used.

Specific models

Classifiers should accept `y` (target) arguments to `fit` that are sequences (lists, arrays) of either strings or integers. They should not assume that the class labels are a contiguous range of integers; instead, they should store a list of classes in a `classes_` attribute or property. The order of class labels in this attribute should match the order in which `predict_proba`, `predict_log_proba` and `decision_function` return their values. The easiest way to achieve this is to put:

```python
self.classes_, y = np.unique(y, return_inverse=True)
```

in `fit`. This returns a new `y` that contains class indexes, rather than labels, in the range `[0, n_classes)`.

A classifier's `predict` method should return arrays containing class labels from `classes_`. In a classifier that implements `decision_function`, this can be achieved with:

```python
def predict(self, X):
    D = self.decision_function(X)
    return self.classes_[np.argmax(D, axis=1)]
```

In linear models, coefficients are stored in an array called `coef_`, and the independent term is stored in `intercept_`. `sklearn.linear_model._base` contains a few base classes and mixins that implement common linear model patterns.
The `sklearn.utils.multiclass` module contains useful functions for working with multiclass and multilabel problems.

### Estimator Tags

**Warning:** The estimator tags are experimental and the API is subject to change.

Scikit-learn introduced estimator tags in version 0.21. These are annotations of estimators that allow programmatic inspection of their capabilities, such as sparse matrix support, supported output types and supported methods. The estimator tags are a dictionary returned by the method `_get_tags()`. These tags are used in the common checks run by the `check_estimator` function and the `parametrize_with_checks` decorator. Tags determine which checks to run and what input data is appropriate. Tags can depend on estimator parameters or even system architecture and can in general only be determined at runtime.

The current set of estimator tags are:

- **allow_nan (default=False)** whether the estimator supports data with missing values encoded as np.NaN
- **binary_only (default=False)** whether estimator supports binary classification but lacks multi-class classification support.
- **multilabel (default=False)** whether the estimator supports multilabel output
- **multioutput (default=False)** whether a regressor supports multi-target outputs or a classifier supports multi-class multi-output.
- **multioutput_only (default=False)** whether estimator supports only multi-output classification or regression.
- **no_validation (default=False)** whether the estimator skips input-validation. This is only meant for stateless and dummy transformers!
- **non_deterministic (default=False)** whether the estimator is not deterministic given a fixed `random_state`
- **pairwise (default=False)** This boolean attribute indicates whether the data (X) fit and similar methods consists of pairwise measures over samples rather than a feature representation for each sample. It is usually `True` where an estimator has a metric or affinity or kernel parameter with value ‘precomputed’. Its primary purpose is that when a *meta-estimator* extracts a sub-sample of data intended for a pairwise estimator, the data needs to be indexed on both axes, while other data is indexed only on the first axis.
- **preserves_dtype (default=[np.float64])** applies only on transformers. It corresponds to the data types which will be preserved such that X_trans.dtype is the same as X.dtype after calling transformer.transform(X). If this list is empty, then the transformer is not expected to preserve the data type. The first value in the list is considered as the default data type, corresponding to the data type of the output when the input data type is not going to be preserved.
- **poor_score (default=False)** whether the estimator fails to provide a “reasonable” test-set score, which currently for regression is an R2 of 0.5 on a subset of the boston housing dataset, and for classification an accuracy of 0.83 on `make_blobs(n_samples=300, random_state=0)`. These datasets and values are based on current estimators in sklearn and might be replaced by something more systematic.
- **requires_fit (default=True)** whether the estimator requires to be fitted before calling one of `transform`, `predict`, `predict_proba`, or `decision_function`.
- **requires_positive_X (default=False)** whether the estimator requires positive X.
- **requires_y (default=False)** whether the estimator requires y to be passed to fit, fit_predict or fit_transform methods. The tag is True for estimators inheriting from `~sklearn.base.RegressorMixin` and `~sklearn.base.ClassifierMixin`.

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requires_positive_y (default=False) whether the estimator requires a positive y (only applicable for regression).

_skip_test (default=False) whether to skip common tests entirely. Don’t use this unless you have a very good reason.

_xfail_checks (default=False) dictionary {check_name: reason} of common checks that will be marked as XFAIL for pytest, when using parametrize_with_checks. These checks will be simply ignored and not run by check_estimator, but a SkipTestWarning will be raised. Don’t use this unless there is a very good reason for your estimator not to pass the check. Also note that the usage of this tag is highly subject to change because we are trying to make it more flexible: be prepared for breaking changes in the future.

stateless (default=False) whether the estimator needs access to data for fitting. Even though an estimator is stateless, it might still need a call to fit for initialization.

X_types (default=['2darray']) Supported input types for X as list of strings. Tests are currently only run if ‘2darray’ is contained in the list, signifying that the estimator takes continuous 2d numpy arrays as input. The default value is ['2darray']. Other possible types are 'string', 'sparse', 'categorical', dict, '1dlabels' and '2dlabels'. The goal is that in the future the supported input type will determine the data used during testing, in particular for 'string', 'sparse' and 'categorical' data. For now, the test for sparse data do not make use of the 'sparse' tag.

It is unlikely that the default values for each tag will suit the needs of your specific estimator. Additional tags can be created or default tags can be overridden by defining a _more_tags() method which returns a dict with the desired overridden tags or new tags. For example:

class MyMultiOutputEstimator(BaseEstimator):
    def _more_tags(self):
        return {'multioutput_only': True, 'non_deterministic': True}

Any tag that is not in _more_tags() will just fall-back to the default values documented above.

Even if it is not recommended, it is possible to override the method _get_tags(). Note however that all tags must be present in the dict. If any of the keys documented above is not present in the output of _get_tags(), an error will occur.

In addition to the tags, estimators also need to declare any non-optional parameters to __init__ in the _required_parameters class attribute, which is a list or tuple. If _required_parameters is only ["estimator"] or ["base_estimator"], then the estimator will be instantiated with an instance of LinearDiscriminantAnalysis (or RidgeRegression if the estimator is a regressor) in the tests. The choice of these two models is somewhat idiosyncratic but both should provide robust closed-form solutions.

### 8.2.3 Coding guidelines

The following are some guidelines on how new code should be written for inclusion in scikit-learn, and which may be appropriate to adopt in external projects. Of course, there are special cases and there will be exceptions to these rules. However, following these rules when submitting new code makes the review easier so new code can be integrated in less time.

Uniformly formatted code makes it easier to share code ownership. The scikit-learn project tries to closely follow the official Python guidelines detailed in PEP8 that detail how code should be formatted and indented. Please read it and follow it.

In addition, we add the following guidelines:

- Use underscores to separate words in non class names: n_samples rather than nsamples.
- Avoid multiple statements on one line. Prefer a line return after a control flow statement (if/for).
- Use relative imports for references inside scikit-learn.
• Unit tests are an exception to the previous rule; they should use absolute imports, exactly as client code would. A corollary is that, if `sklearn.foo` exports a class or function that is implemented in `sklearn.foo.bar.baz`, the test should import it from `sklearn.foo`.

• **Please don’t use `import *` in any case.** It is considered harmful by the official Python recommendations. It makes the code harder to read as the origin of symbols is no longer explicitly referenced, but most important, it prevents using a static analysis tool like `pyflakes` to automatically find bugs in scikit-learn.

• Use the numpy docstring standard in all your docstrings.

A good example of code that we like can be found here.

**Input validation**

The module `sklearn.utils` contains various functions for doing input validation and conversion. Sometimes, `np.asarray` suffices for validation; do *not* use `np.asanyarray` or `np.atleast_2d`, since those let NumPy’s `np.matrix` through, which has a different API (e.g., `*` means dot product on `np.matrix`, but Hadamard product on `np.ndarray`).

In other cases, be sure to call `check_array` on any array-like argument passed to a scikit-learn API function. The exact parameters to use depends mainly on whether and which `scipy.sparse` matrices must be accepted.

For more information, refer to the [Utilities for Developers](https://scikit-learn.org/stable/developers/developing.html) page.

**Random Numbers**

If your code depends on a random number generator, do not use `numpy.random.random()` or similar routines. To ensure repeatability in error checking, the routine should accept a keyword `random_state` and use this to construct a `numpy.random.RandomState` object. See `sklearn.utils.check_random_state` in [Utilities for Developers](https://scikit-learn.org/stable/developers/developing.html).

Here’s a simple example of code using some of the above guidelines:

```python
from sklearn.utils import check_array, check_random_state

def choose_random_sample(X, random_state=0):
    """Choose a random point from X.
    Parameters
    ----------
    X : array-like of shape (n_samples, n_features)
        An array representing the data.
    random_state : int or RandomState instance, default=0
        The seed of the pseudo random number generator that selects a random sample. Pass an int for reproducible output across multiple function calls.
        See :term:`Glossary <random_state>`.
    Returns
    -------
    x : ndarray of shape (n_features,)
        A random point selected from X.
    """
    X = check_array(X)
    random_state = check_random_state(random_state)
    i = random_state.randint(X.shape[0])
    return X[i]
```

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If you use randomness in an estimator instead of a freestanding function, some additional guidelines apply.
First off, the estimator should take a random_state argument to its __init__ with a default value of
None. It should store that argument’s value, unmodified, in an attribute random_state. fit can call
check_random_state on that attribute to get an actual random number generator. If, for some reason, randomness is needed after fit, the RNG should be stored in an attribute random_state_. The following example
should make this clear:
class GaussianNoise(BaseEstimator, TransformerMixin):
"""This estimator ignores its input and returns random Gaussian noise.
It also does not adhere to all scikit-learn conventions,
but showcases how to handle randomness.
"""
def __init__(self, n_components=100, random_state=None):
self.random_state = random_state
self.n_components = n_components
# the arguments are ignored anyway, so we make them optional
def fit(self, X=None, y=None):
self.random_state_ = check_random_state(self.random_state)
def transform(self, X):
n_samples = X.shape[0]
return self.random_state_.randn(n_samples, self.n_components)

The reason for this setup is reproducibility: when an estimator is fit twice to the same data, it should produce an
identical model both times, hence the validation in fit, not __init__.

8.3 Developers’ Tips and Tricks
8.3.1 Productivity and sanity-preserving tips
In this section we gather some useful advice and tools that may increase your quality-of-life when reviewing pull
requests, running unit tests, and so forth. Some of these tricks consist of userscripts that require a browser extension
such as TamperMonkey or GreaseMonkey; to set up userscripts you must have one of these extensions installed,
enabled and running. We provide userscripts as GitHub gists; to install them, click on the “Raw” button on the gist
page.
Folding and unfolding outdated diffs on pull requests
GitHub hides discussions on PRs when the corresponding lines of code have been changed in the mean while. This
userscript provides a shortcut (Control-Alt-P at the time of writing but look at the code to be sure) to unfold all such
hidden discussions at once, so you can catch up.

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Checking out pull requests as remote-tracking branches

In your local fork, add to your .git/config, under the [remote "upstream"] heading, the line:

```bash
fetch = +refs/pull/*/head:refs/remotes/upstream/pr/*
```

You may then use `git checkout pr/PR_NUMBER` to navigate to the code of the pull-request with the given number. (Read more in this gist.)

Display code coverage in pull requests

To overlay the code coverage reports generated by the CodeCov continuous integration, consider this browser extension. The coverage of each line will be displayed as a color background behind the line number.

Useful pytest aliases and flags

The full test suite takes fairly long to run. For faster iterations, it is possibly to select a subset of tests using pytest selectors. In particular, one can run a single test based on its node ID:

```bash
$ pytest -v sklearn/linear_model/tests/test_logistic.py::test_sparsify
```

or use the `-k pytest parameter to select tests based on their name. For instance,:`

```bash
$ pytest sklearn/tests/test_common.py -v -k LogisticRegression
```

will run all *common tests* for the *LogisticRegression* estimator.

When a unit test fails, the following tricks can make debugging easier:

1. The command line argument `pytest -l` instructs pytest to print the local variables when a failure occurs.
2. The argument `pytest --pdb` drops into the Python debugger on failure. To instead drop into the rich IPython debugger `ipdb`, you may set up a shell alias to:

```bash
$ pytest --pdbcls=IPython.terminal.debugger:TerminalPdb --capture no
```

Other `pytest` options that may become useful include:

- `-x` which exits on the first failed test
- `--lf` to rerun the tests that failed on the previous run
- `--ff` to rerun all previous tests, running the ones that failed first
- `--s` so that pytest does not capture the output of `print()` statements
- `--tb=short` or `--tb=line` to control the length of the logs
- `--runxfail also run tests marked as a known failure (XFAIL) and report errors.

Since our continuous integration tests will error if `FutureWarning` isn’t properly caught, it is also recommended to run `pytest` along with the `--Werror::FutureWarning` flag.
Standard replies for reviewing

It may be helpful to store some of these in GitHub’s saved replies for reviewing:

**Issue: Usage questions**

You are asking a usage question. The issue tracker is for bugs and new features. For usage questions, it is recommended to try [Stack Overflow](https://stackoverflow.com/questions/tagged/scikit-learn) or [the Mailing List](https://mail.python.org/mailman/listinfo/scikit-learn).

Unfortunately, we need to close this issue as this issue tracker is a communication tool used for the development of scikit-learn. The additional activity created by usage questions crowds it too much and impedes this development. The conversation can continue here, however there is no guarantee that is will receive attention from core developers.

**Issue: You’re welcome to update the docs**

Please feel free to offer a pull request updating the documentation if you feel it could be improved.

**Issue: Self-contained example for bug**

Please provide [self-contained example code](https://stackoverflow.com/help/mcve), including imports and data (if possible), so that other contributors can just run it and reproduce your issue. Ideally your example code should be minimal.

**Issue: Software versions**

To help diagnose your issue, please paste the output of:

```py
import sklearn; sklearn.show_versions()
```

Thanks.

**Issue: Code blocks**

Readability can be greatly improved if you [format](https://help.github.com/articles/creating-and-highlighting-code-blocks/) your code snippets and complete error messages appropriately. For example:

```python
print(something)
```

generates:

```python
print(something)
```

And:

```pytb
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
ImportError: No module named 'hello'
```

generates:

```pytb
(continues on next page)```
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
ImportError: No module named 'hello'
```
You can edit your issue descriptions and comments at any time to improve readability. This helps maintainers a lot. Thanks!

Issue/Comment: Linking to code

Friendly advice: for clarity's sake, you can link to code like [this](https://help.github.com/articles/creating-a-permanent-link-to-a-code-snippet/).

Issue/Comment: Linking to comments

Please use links to comments, which make it a lot easier to see what you are referring to, rather than just linking to the issue. See [this](https://stackoverflow.com/questions/25163598/how-do-i-reference-a-specific-issue-comment-on-github) for more details.

PR-NEW: Better description and title

Thanks for the pull request! Please make the title of the PR more descriptive. The title will become the commit message when this is merged. You should state what issue (or PR) it fixes/resolves in the description using the syntax described [here](http://scikit-learn.org/dev/developers/contributing.html#contributing-pull-requests).

PR-NEW: Fix #

Please use "Fix #issueNumber" in your PR description (and you can do it more than once). This way the associated issue gets closed automatically when the PR is merged. For more details, look at [this](https://github.com/blog/1506-closing-issues-via-pull-requests).

PR-NEW or Issue: Maintenance cost

Every feature we include has a [maintenance cost](http://scikit-learn.org/dev/faq.html#why-are-you-so-selective-on-what-algorithms-you-include-in-scikit-learn). Our maintainers are mostly volunteers. For a new feature to be included, we need evidence that it is often useful and, ideally, [well-established](http://scikit-learn.org/dev/faq.html#what-are-the-inclusion-criteria-for-new-algorithms) in the literature or in practice. That doesn't stop you implementing it for yourself and publishing it in a separate repository, or even [scikit-learn-contrib](https://scikit-learn-contrib.github.io).

PR-WIP: What’s needed before merge?

Please clarify (perhaps as a TODO list in the PR description) what work you believe still needs to be done before it can be reviewed for merge. When it is ready, please prefix the PR title with `[MRG]`.

PR-WIP: Regression test needed

Please add a [non-regression test](https://en.wikipedia.org/wiki/Non-regression_testing) that would fail at master but pass in this PR.

PR-WIP: PEP8

8.3. Developers’ Tips and Tricks
You have some [PEP8](https://www.python.org/dev/peps/pep-0008/) violations, whose details you can see in the Circle CI `lint` job. It might be worth configuring your code editor to check for such errors on the fly, so you can catch them before committing.

**PR-MRG: Patience**

Before merging, we generally require two core developers to agree that your pull request is desirable and ready. [Please be patient](http://scikit-learn.org/dev/faq.html#why-is-my-pull-request-not-getting-any-attention), as we mostly rely on volunteered time from busy core developers. (You are also welcome to help us out with [reviewing other PRs](http://scikit-learn.org/dev/developers/contributing.html#code-review-guidelines).)

**PR-MRG: Add to what’s new**

Please add an entry to the change log at `doc/whats_new/v*.rst`. Like the other entries there, please reference this pull request with `:pr:` and credit yourself (and other contributors if applicable) with `:user:`.

**PR: Don’t change unrelated**

Please do not change unrelated lines. It makes your contribution harder to review and may introduce merge conflicts to other pull requests.

### 8.3.2 Debugging memory errors in Cython with valgrind

While python/numpy’s built-in memory management is relatively robust, it can lead to performance penalties for some routines. For this reason, much of the high-performance code in scikit-learn in written in cython. This performance gain comes with a tradeoff, however: it is very easy for memory bugs to crop up in cython code, especially in situations where that code relies heavily on pointer arithmetic.

Memory errors can manifest themselves a number of ways. The easiest ones to debug are often segmentation faults and related glibc errors. Uninitialized variables can lead to unexpected behavior that is difficult to track down. A very useful tool when debugging these sorts of errors is valgrind.

Valgrind is a command-line tool that can trace memory errors in a variety of code. Follow these steps:

1. Install valgrind on your system.
2. Download the python valgrind suppression file: [valgrind-python.supp](http://scikit-learn.org/dev/). Follow the directions in the README.valgrind file to customize your python suppressions. If you don’t, you will have spurious output coming related to the python interpreter instead of your own code.
3. Run valgrind as follows:

   $ valgrind -v --suppressions=valgrind-python.supp python my_test_script.py

   The result will be a list of all the memory-related errors, which reference lines in the C-code generated by cython from your .pyx file. If you examine the referenced lines in the .c file, you will see comments which indicate the corresponding location in your .pyx source file. Hopefully the output will give you clues as to the source of your memory error.

   For more information on valgrind and the array of options it has, see the tutorials and documentation on the valgrind web site.
8.3.3 Building and testing for the ARM64 platform on a x86_64 machine

ARM-based machines are a popular target for mobile, edge or other low-energy deployments (including in the cloud, for instance on Scaleway or AWS Graviton).

Here are instructions to setup a local dev environment to reproduce ARM-specific bugs or test failures on a x86_64 host laptop or workstation. This is based on QEMU user mode emulation using docker for convenience (see https://github.com/multiarch/qemu-user-static).

**Note:** The following instructions are illustrated for ARM64 but they also apply to ppc64le, after changing the Docker image and Miniforge paths appropriately.

Prepare a folder on the host filesystem and download the necessary tools and source code:

```
$ mkdir arm64
$ pushd arm64
$ wget https://github.com/conda-forge/miniforge/releases/latest/download/Miniforge3-Linux-aarch64.sh
$ git clone https://github.com/scikit-learn/scikit-learn.git
```

Use docker to install QEMU user mode and run an ARM64v8 container with access to your shared folder under the `/io` mount point:

```
$ docker run --rm --privileged multiarch/qemu-user-static --reset -p yes
$ docker run -v`pwd`:/io --rm -it arm64v8/ubuntu /bin/bash
```

In the container, install miniforge3 for the ARM64 (a.k.a. aarch64) architecture:

```
$ bash Miniforge3-Linux-aarch64.sh
$ # Choose to install miniforge3 under: `/io/miniforge3`
```

Whenever you restart a new container, you will need to reinit the conda env previously installed under `/io/miniforge3`:

```
$ /io/miniforge3/bin/conda init
$ source /root/.bashrc
```

as the `/root` home folder is part of the ephemeral docker container. Every file or directory stored under `/io` is persistent on the other hand.

You can then build scikit-learn as usual (you will need to install compiler tools and dependencies using apt or conda as usual). Building scikit-learn takes a lot of time because of the emulation layer, however it needs to be done only once if you put the scikit-learn folder under the `/io` mount point.

Then use pytest to run only the tests of the module you are interested in debugging.

### 8.4 Utilities for Developers

Scikit-learn contains a number of utilities to help with development. These are located in `sklearn.utils`, and include tools in a number of categories. All the following functions and classes are in the module `sklearn.utils`.

**Warning:** These utilities are meant to be used internally within the scikit-learn package. They are not guaranteed to be stable between versions of scikit-learn. Backports, in particular, will be removed as the scikit-learn dependencies evolve.
8.4.1 Validation Tools

These are tools used to check and validate input. When you write a function which accepts arrays, matrices, or sparse matrices as arguments, the following should be used when applicable.

- **assert_all_finite**: Throw an error if array contains NaNs or Infs.
- **as_float_array**: convert input to an array of floats. If a sparse matrix is passed, a sparse matrix will be returned.
- **check_array**: check that input is a 2D array, raise error on sparse matrices. Allowed sparse matrix formats can be given optionally, as well as allowing 1D or N-dimensional arrays. Calls **assert_all_finite** by default.
- **check_X_y**: check that X and y have consistent length, calls check_array on X, and column_or_1d on y. For multilabel classification or multitarget regression, specify multi_output=True, in which case check_array will be called on y.
- **checkable**: check that all input arrays have consistent length and can be sliced or indexed using safe_index. This is used to validate input for cross-validation.
- **validation.check_memory** checks that input is joblib.Memory-like, which means that it can be converted into a sklearn.utils.Memory instance (typically a str denoting the cachedir) or has the same interface.

If your code relies on a random number generator, it should never use functions like numpy.random.random or numpy.random.normal. This approach can lead to repeatability issues in unit tests. Instead, a numpy.random.RandomState object should be used, which is built from a random_state argument passed to the class or function. The function **check_random_state**, below, can then be used to create a random number generator object.

- **check_random_state**: create a np.random.RandomState object from a parameter random_state.
  - If random_state is None or np.random, then a randomly-initialized RandomState object is returned.
  - If random_state is an integer, then it is used to seed a new RandomState object.
  - If random_state is a RandomState object, then it is passed through.

For example:

```python
>>> from sklearn.utils import check_random_state
>>> random_state = 0
>>> random_state = check_random_state(random_state)
>>> random_state.rand(4)
array([0.5488135 , 0.71518937, 0.60276338, 0.54488318])
```

When developing your own scikit-learn compatible estimator, the following helpers are available.

- **validation.check_is_fitted**: check that the estimator has been fitted before calling transform, predict, or similar methods. This helper allows to raise a standardized error message across estimator.
- **validation.has_fit_parameter**: check that a given parameter is supported in the fit method of a given estimator.
8.4.2 Efficient Linear Algebra & Array Operations

- `extmath.randomized_range_finder`: construct an orthonormal matrix whose range approximates the range of the input. This is used in `extmath.randomized_svd`, below.

- `extmath.randomized_svd`: compute the k-truncated randomized SVD. This algorithm finds the exact truncated singular values decomposition using randomization to speed up the computations. It is particularly fast on large matrices on which you wish to extract only a small number of components.

- `arrayfuncs.cholesky_delete`: (used in `lars_path`) Remove an item from a cholesky factorization.

- `arrayfuncs.min_pos`: (used in `sklearn.linear_model.least_angle`) Find the minimum of the positive values within an array.

- `extmath.fast_logdet`: efficiently compute the log of the determinant of a matrix.

- `extmath.density`: efficiently compute the density of a sparse vector

- `extmath.safe_sparse_dot`: dot product which will correctly handle scipy.sparse inputs. If the inputs are dense, it is equivalent to numpy.dot.

- `extmath.weighted_mode`: an extension of scipy.stats.mode which allows each item to have a real-valued weight.

- `resample`: Resample arrays or sparse matrices in a consistent way. used in `shuffle`, below.

- `shuffle`: Shuffle arrays or sparse matrices in a consistent way. Used in `k_means`.

8.4.3 Efficient Random Sampling

- `random.sample_without_replacement`: implements efficient algorithms for sampling `n_samples` integers from a population of size `n_population` without replacement.

8.4.4 Efficient Routines for Sparse Matrices

The `sklearn.utils.sparsefuncs` cython module hosts compiled extensions to efficiently process scipy.sparse data.

- `sparsefuncs.mean_variance_axis`: compute the means and variances along a specified axis of a CSR matrix. Used for normalizing the tolerance stopping criterion in KMeans.

- `sparsefuncs_fast.inplace_csr_row_normalize_l1` and `sparsefuncs_fast.inplace_csr_row_normalize_l2`: can be used to normalize individual sparse samples to unit L1 or L2 norm as done in Normalizer.

- `sparsefuncs.inplace_csr_column_scale`: can be used to multiply the columns of a CSR matrix by a constant scale (one scale per column). Used for scaling features to unit standard deviation in StandardScaler.
8.4.5 Graph Routines

- `graph.single_source_shortest_path_length`: (not currently used in scikit-learn) Return the shortest path from a single source to all connected nodes on a graph. Code is adapted from networkx. If this is ever needed again, it would be far faster to use a single iteration of Dijkstra’s algorithm from `graph_shortest_path`.

- `graph_shortest_path.graph_shortest_path`: (used in Isomap) Return the shortest path between all pairs of connected points on a directed or undirected graph. Both the Floyd-Warshall algorithm and Dijkstra’s algorithm are available. The algorithm is most efficient when the connectivity matrix is a `scipy.sparse.csr_matrix`

8.4.6 Testing Functions

- `all_estimators`: returns a list of all estimators in scikit-learn to test for consistent behavior and interfaces.

8.4.7 Multiclass and multilabel utility function

- `multiclass.is_multilabel`: Helper function to check if the task is a multi-label classification one.

- `multiclass.unique_labels`: Helper function to extract an ordered array of unique labels from different formats of target.

8.4.8 Helper Functions

- `gen_even_slices`: generator to create n-packs of slices going up to n. Used in `dict_learning` and `k_means`.

- `safe_mask`: Helper function to convert a mask to the format expected by the numpy array or scipy sparse matrix on which to use it (sparse matrices support integer indices only while numpy arrays support both boolean masks and integer indices).

- `safe_sqr`: Helper function for unified squaring (**2) of array-likes, matrices and sparse matrices.

8.4.9 Hash Functions

- `murmurhash3_32` provides a python wrapper for the MurmurHash3_x86_32 C++ non cryptographic hash function. This hash function is suitable for implementing lookup tables, Bloom filters, Count Min Sketch, feature hashing and implicitly defined sparse random projections:

```python
>>> from sklearn.utils import murmurhash3_32
>>> murmurhash3_32("some feature", seed=0) == -384616559
True
>>> murmurhash3_32("some feature", seed=0, positive=True) == 3910350737
True
```

The `sklearn.utils.murmurhash` module can also be “cimported” from other cython modules so as to benefit from the high performance of MurmurHash while skipping the overhead of the Python interpreter.
8.4.10 Warnings and Exceptions

- **deprecated**: Decorator to mark a function or class as deprecated.
- **ConvergenceWarning**: Custom warning to catch convergence problems. Used in sklearn.covariance.graphical_lasso.

8.5 How to optimize for speed

The following gives some practical guidelines to help you write efficient code for the scikit-learn project.

**Note**: While it is always useful to profile your code so as to check performance assumptions, it is also highly recommended to review the literature to ensure that the implemented algorithm is the state of the art for the task before investing into costly implementation optimization.

Times and times, hours of efforts invested in optimizing complicated implementation details have been rendered irrelevant by the subsequent discovery of simple algorithmic tricks, or by using another algorithm altogether that is better suited to the problem.

The section *A simple algorithmic trick: warm restarts* gives an example of such a trick.

8.5.1 Python, Cython or C/C++?

In general, the scikit-learn project emphasizes the readability of the source code to make it easy for the project users to dive into the source code so as to understand how the algorithm behaves on their data but also for ease of maintainability (by the developers).

When implementing a new algorithm is thus recommended to start implementing it in Python using Numpy and Scipy by taking care of avoiding looping code using the vectorized idioms of those libraries. In practice this means trying to replace any nested for loops by calls to equivalent Numpy array methods. The goal is to avoid the CPU wasting time in the Python interpreter rather than crunching numbers to fit your statistical model. It’s generally a good idea to consider NumPy and SciPy performance tips: https://scipy.github.io/old-wiki/pages/PerformanceTips

Sometimes however an algorithm cannot be expressed efficiently in simple vectorized Numpy code. In this case, the recommended strategy is the following:

1. **Profile** the Python implementation to find the main bottleneck and isolate it in a dedicated module level function. This function will be reimplemented as a compiled extension module.

2. If there exists a well maintained BSD or MIT C/C++ implementation of the same algorithm that is not too big, you can write a Cython wrapper for it and include a copy of the source code of the library in the scikit-learn source tree: this strategy is used for the classes `svm.LinearSVC`, `svm.SVC` and `linear_model.LogisticRegression` (wrappers for liblinear and libsvm).

3. Otherwise, write an optimized version of your Python function using Cython directly. This strategy is used for the `linear_model.ElasticNet` and `linear_model.SGDClassifier` classes for instance.

4. **Move the Python version of the function in the tests** and use it to check that the results of the compiled extension are consistent with the gold standard, easy to debug Python version.

5. Once the code is optimized (not simple bottleneck spottable by profiling), check whether it is possible to have coarse grained parallelism that is amenable to multi-processing by using the `joblib.Parallel` class.

When using Cython, use either
to generate C files. You are responsible for adding `.c/.cpp` extensions along with build parameters in each submodule `setup.py`.

C/C++ generated files are embedded in distributed stable packages. The goal is to make it possible to install scikit-learn stable version on any machine with Python, Numpy, Scipy and C/C++ compiler.

### 8.5.2 Profiling Python code

In order to profile Python code we recommend to write a script that loads and prepare your data and then use the IPython integrated profiler for interactively exploring the relevant part for the code.

Suppose we want to profile the Non Negative Matrix Factorization module of scikit-learn. Let us setup a new IPython session and load the digits dataset and as in the Recognizing hand-written digits example:

```python
In [1]: from sklearn.decomposition import NMF
In [2]: from sklearn.datasets import load_digits
In [3]: X, _ = load_digits(return_X_y=True)
```

Before starting the profiling session and engaging in tentative optimization iterations, it is important to measure the total execution time of the function we want to optimize without any kind of profiler overhead and save it somewhere for later reference:

```python
In [4]: %timeit NMF(n_components=16, tol=1e-2).fit(X)
1 loop, best of 3: 1.7 s per loop
```

To have a look at the overall performance profile using the `%prun` magic command:

```python
In [5]: %prun -l nmf.py NMF(n_components=16, tol=1e-2).fit(X)

14496 function calls in 1.682 CPU seconds
Ordered by: internal time
list reduced from 90 to 9 due to restriction <'nmf.py'>
```

The `tottime` column is the most interesting: it gives to total time spent executing the code of a given function ignoring the time spent in executing the sub-functions. The real total time (local code + sub-function calls) is given by the `cumtime` column.

Note the use of the `-l nmf.py` that restricts the output to lines that contains the “nmf.py” string. This is useful to have a quick look at the hotspot of the nmf Python module itself ignoring anything else.

Here is the beginning of the output of the same command without the `-l nmf.py` filter:
The above results show that the execution is largely dominated by dot products operations (delegated to blas). Hence there is probably no huge gain to expect by rewriting this code in Cython or C/C++: in this case out of the 1.7s total execution time, almost 0.7s are spent in compiled code we can consider optimal. By rewriting the rest of the Python code and assuming we could achieve a 1000% boost on this portion (which is highly unlikely given the shallowness of the Python loops), we would not gain more than a 2.4x speed-up globally.

Hence major improvements can only be achieved by **algorithmic improvements** in this particular example (e.g. trying to find operation that are both costly and useless to avoid computing them rather than trying to optimize their implementation).

It is however still interesting to check what’s happening inside the _nls_subproblem function which is the hotspot if we only consider Python code: it takes around 100% of the accumulated time of the module. In order to better understand the profile of this specific function, let us install line_profiler and wire it to IPython:

```
$ pip install line_profiler
```

- **Under IPython 0.13+**, first create a configuration profile:

```
$ ipython profile create
```

Then register the line_profiler extension in ~/.ipython/profile_default/ipython_config.py:

```python
c.TerminalIPythonApp.extensions.append('line_profiler')
c.InteractiveShellApp.extensions.append('line_profiler')
```

This will register the %%lprun magic command in the IPython terminal application and the other frontends such as qtconsole and notebook.

Now restart IPython and let us use this new toy:

```
In [1]: from sklearn.datasets import load_digits

In [2]: from sklearn.decomposition import NMF
   ... : from sklearn.decomposition._nmf import _nls_subproblem

In [3]: X, _ = load_digits(return_X_y=True)

In [4]: %%lprun -f _nls_subproblem NMF(n_components=16, tol=1e-2).fit(X)
```

(continues on next page)
By looking at the top values of the % Time column it is really easy to pin-point the most expensive expressions that would deserve additional care.
8.5.3 Memory usage profiling

You can analyze in detail the memory usage of any Python code with the help of memory_profiler. First, install the latest version:

$ pip install -U memory_profiler

Then, setup the magics in a manner similar to line_profiler.

- Under IPython 0.11+, first create a configuration profile:

  $ ipython profile create

  Then register the extension in ~/.ipython/profile_default/ipython_config.py alongside the line profiler:

  ```python
  c.TerminalIPythonApp.extensions.append('memory_profiler')
  c.InteractiveShellApp.extensions.append('memory_profiler')
  ```

  This will register the %memit and %mprun magic commands in the IPython terminal application and the other frontends such as qtconsole and notebook.

  %mprun is useful to examine, line-by-line, the memory usage of key functions in your program. It is very similar to %lprun, discussed in the previous section. For example, from the memory_profiler examples directory:

  ```python
  In [1]: from example import my_func
  In [2]: %mprun -f my_func my_func()
  Filename: example.py
  Line #  Mem usage  Increment  Line Contents
  -----------------------------------------------
  3  5.97 MB  0.00 MB  @profile
def my_func():
  4  13.61 MB  7.64 MB  a = [1] * (10 ** 6)
  5 166.20 MB 152.59 MB  b = [2] * (2 * 10 ** 7)
  6 13.61 MB  -152.59 MB  del b
  8 13.61 MB  0.00 MB  return a
  ```

  Another useful magic that memory_profiler defines is %memit, which is analogous to %timeit. It can be used as follows:

  ```python
  In [1]: import numpy as np
  In [2]: %memit np.zeros(1e7)
  maximum of 3: 76.402344 MB per loop
  ```

  For more details, see the docstrings of the magics, using %memit? and %mprun?.
8.5.4 Performance tips for the Cython developer

If profiling of the Python code reveals that the Python interpreter overhead is larger by one order of magnitude or more than the cost of the actual numerical computation (e.g. for loops over vector components, nested evaluation of conditional expression, scalar arithmetic...), it is probably adequate to extract the hotspot portion of the code as a standalone function in a .pyx file, add static type declarations and then use Cython to generate a C program suitable to be compiled as a Python extension module.

The official documentation available at http://docs.cython.org/ contains a tutorial and reference guide for developing such a module. In the following we will just highlight a couple of tricks that we found important in practice on the existing cython codebase in the scikit-learn project.

TODO: html report, type declarations, bound checks, division by zero checks, memory alignment, direct blas calls...

- https://www.youtube.com/watch?v=gMvkiQ-gOW8

Using OpenMP

Since scikit-learn can be built without OpenMP, it’s necessary to protect each direct call to OpenMP. This can be done using the following syntax:

```python
# importing OpenMP
IF SKLEARN_OPENMP_PARALLELISM_ENABLED:
    cimport openmp

# calling OpenMP
IF SKLEARN_OPENMP_PARALLELISM_ENABLED:
    max_threads = openmp.omp_get_max_threads()
ELSE:
    max_threads = 1
```

Note: Protecting the parallel loop, prange, is already done by cython.

8.5.5 Profiling compiled extensions

When working with compiled extensions (written in C/C++ with a wrapper or directly as Cython extension), the default Python profiler is useless: we need a dedicated tool to introspect what’s happening inside the compiled extension itself.

Using yep and gperftools

Easy profiling without special compilation options use yep:

- https://pypi.org/project/yep/
- http://fa.bianp.net/blog/2011/a-profiler-for-python-extensions
Using gprof

In order to profile compiled Python extensions one could use gprof after having recompiled the project with gcc -pg and using the python-db variant of the interpreter on debian / ubuntu: however this approach requires to also have numpy and scipy recompiled with -pg which is rather complicated to get working.

Fortunately there exist two alternative profilers that don’t require you to recompile everything.

Using valgrind / callgrind / kcachegrind

kcachegrind

yep can be used to create a profiling report. kcachegrind provides a graphical environment to visualize this report:

$ # Run yep to profile some python script
$ python -m yep -c my_file.py
$ # open my_file.py.callgrin with kcachegrind
$ kcachegrind my_file.py.prof

Note: yep can be executed with the argument --lines or -l to compile a profiling report ‘line by line’.

8.5.6 Multi-core parallelism using joblib.Parallel

See joblib documentation

8.5.7 A simple algorithmic trick: warm restarts

See the glossary entry for warm_start

8.6 Installing the development version of scikit-learn

This section introduces how to install the master branch of scikit-learn. This can be done by either installing a nightly build or building from source.

8.6.1 Installing nightly builds

The continuous integration servers of the scikit-learn project build, test and upload wheel packages for the most recent Python version on a nightly basis.

Installing a nightly build is the quickest way to:

- try a new feature that will be shipped in the next release (that is, a feature from a pull-request that was recently merged to the master branch);
- check whether a bug you encountered has been fixed since the last release.

$ pip install --pre --extra-index https://pypi.anaconda.org/scipy-wheels-nightly/simple scikit-learn
8.6.2 Building from source

Building from source is required to work on a contribution (bug fix, new feature, code or documentation improvement).

1. Use Git to check out the latest source from the scikit-learn repository on Github.:
   
   $ git clone git://github.com/scikit-learn/scikit-learn.git  # add --depth 1 if your connection is slow
   $ cd scikit-learn

   If you plan on submitting a pull-request, you should clone from your fork instead.

2. Install a compiler with OpenMP support for your platform. See instructions for Windows, macOS, Linux and FreeBSD.

3. Optional (but recommended): create and activate a dedicated virtualenv or conda environment.

4. Install Cython and build the project with pip in Editable mode:

   $ pip install cython
   $ pip install --verbose --no-build-isolation --editable .

5. Check that the installed scikit-learn has a version number ending with .dev0:

   $ python -c "import sklearn; sklearn.show_versions()"

6. Please refer to the Developer's Guide and Useful pytest aliases and flags to run the tests on the module of your choice.

Note: You will have to run the pip install --no-build-isolation --editable . command every time the source code of a Cython file is updated (ending in .pyx or .pxd). Use the --no-build-isolation flag to avoid compiling the whole project each time, only the files you have modified.

Dependencies

Runtime dependencies

Scikit-learn requires the following dependencies both at build time and at runtime:

- Python (>= 3.6),
- NumPy (>= 1.13.3),
- SciPy (>= 0.19.1),
- Joblib (>= 0.11),
- threadpoolctl (>= 2.0.0).

Those dependencies are automatically installed by pip if they were missing when building scikit-learn from source.

Note: For running on PyPy, PyPy3-v5.10+, Numpy 1.14.0+, and scipy 1.1.0+ are required. For PyPy, only installation instructions with pip apply.
Build dependencies

Building Scikit-learn also requires:

- Cython >= 0.28.5
- A C/C++ compiler and a matching OpenMP runtime library. See the platform system specific instructions for more details.

**Note:** If OpenMP is not supported by the compiler, the build will be done with OpenMP functionalities disabled. This is not recommended since it will force some estimators to run in sequential mode instead of leveraging thread-based parallelism. Setting the SKLEARN_FAIL_NO_OPENMP environment variable (before cythonization) will force the build to fail if OpenMP is not supported.

Since version 0.21, scikit-learn automatically detects and use the linear algebra library used by SciPy at runtime. Scikit-learn has therefore no build dependency on BLAS/LAPACK implementations such as OpenBlas, Atlas, Blis or MKL.

Test dependencies

Running tests requires:

- pytest >= 5.0.1

Some tests also require pandas.

Building a specific version from a tag

If you want to build a stable version, you can git checkout <VERSION> to get the code for that particular version, or download an zip archive of the version from github.

Editable mode

If you run the development version, it is cumbersome to reinstall the package each time you update the sources. Therefore it is recommended that you install in with the pip install --no-build-isolation --editable . command, which allows you to edit the code in-place. This builds the extension in place and creates a link to the development directory (see the pip docs).

This is fundamentally similar to using the command python setup.py develop (see the setuptools docs). It is however preferred to use pip.

On Unix-like systems, you can equivalently type make in from the top-level folder. Have a look at the Makefile for additional utilities.
8.6.3 Platform-specific instructions

Here are instructions to install a working C/C++ compiler with OpenMP support to build scikit-learn Cython extensions for each supported platform.

Windows


Secondly, find out if you are running 64-bit or 32-bit Python. The building command depends on the architecture of the Python interpreter. You can check the architecture by running the following in `cmd` or `powershell` console:

```bash
$ python -c "import struct; print(struct.calcsize('P') * 8)"
```

For 64-bit Python, configure the build environment with:

```bash
$ SET DISTUTILS_USE_SDK=1
$ "C:\Program Files (x86)\Microsoft Visual Studio\2019\BuildTools\VC\Auxiliary\Build\vcvarsall.bat" x64
```

Replace `x64` by `x86` to build for 32-bit Python.

Please be aware that the path above might be different from user to user. The aim is to point to the `vcvarsall.bat` file that will set the necessary environment variables in the current command prompt.

Finally, build scikit-learn from this command prompt:

```bash
$ pip install --verbose --no-build-isolation --editable .
```

macOS

The default C compiler on macOS, Apple clang (confusingly aliased as `/usr/bin/gcc`), does not directly support OpenMP. We present two alternatives to enable OpenMP support:

- either install `conda-forge::compilers` with conda;
- or install `libomp` with Homebrew to extend the default Apple clang compiler.

macOS compilers from conda-forge

If you use the conda package manager (version >= 4.7), you can install the `compilers` meta-package from the conda-forge channel, which provides OpenMP-enabled C/C++ compilers based on the llvm toolchain.

First install the macOS command line tools:

```bash
$ xcode-select --install
```

It is recommended to use a dedicated `conda` environment to build scikit-learn from source:

```bash
$ conda create -n sklearn-dev -c conda-forge python numpy scipy cython joblib threadpoolctl pytest "compilers>=1.0.4,!=1.1.0" llvm-openmp
$ conda activate sklearn-dev
$ make clean
$ pip install --verbose --no-build-isolation --editable .
```
You can check that the custom compilers are properly installed from conda forge using the following command:

```
$ conda list
```

which should include `compilers` and `llvm-openmp`.

The compilers meta-package will automatically set custom environment variables:

```
$ echo $CC
$ echo $CXX
$ echo $CFLAGS
$ echo $CXXFLAGS
$ echo $LDFLAGS
```

They point to files and folders from your `sklearn-dev` conda environment (in particular in the `bin/`, `include/` and `lib/` subfolders). For instance `-L/path/to/conda/envs/sklearn-dev/lib` should appear in `LDFLAGS`.

In the log, you should see the compiled extension being built with the clang and clang++ compilers installed by conda with the `-fopenmp` command line flag.

### macOS compilers from Homebrew

Another solution is to enable OpenMP support for the clang compiler shipped by default on macOS.

First install the macOS command line tools:

```
$ xcode-select --install
```

Install the Homebrew package manager for macOS.

Install the LLVM OpenMP library:

```
$ brew install libomp
```

Set the following environment variables:

```
$ export CC=/usr/bin/clang
$ export CXX=/usr/bin/clang++
$ export CPPFLAGS="$CPPFLAGS -Xpreprocessor -fopenmp"
$ export CFLAGS="$CFLAGS -I/usr/local/opt/libomp/include"
$ export CXXFLAGS="$CXXFLAGS -I/usr/local/opt/libomp/include"
$ export LDFLAGS="$LDFLAGS -Wl,-rpath,/usr/local/opt/libomp/lib -L/usr/local/opt/libomp/lib -lomp"
```

Finally, build scikit-learn in verbose mode (to check for the presence of the `-fopenmp` flag in the compiler commands):

```
$ make clean
$ pip install --verbose --no-build-isolation --editable .
```
Linux

Linux compilers from the system

Installing scikit-learn from source without using conda requires you to have installed the scikit-learn Python development headers and a working C/C++ compiler with OpenMP support (typically the GCC toolchain).

Install build dependencies for Debian-based operating systems, e.g. Ubuntu:

$ sudo apt-get install build-essential python3-dev python3-pip

then proceed as usual:

$ pip3 install cython
$ pip3 install --verbose --editable .

Cython and the pre-compiled wheels for the runtime dependencies (numpy, scipy and joblib) should automatically be installed in $HOME/.local/lib/pythonX.Y/site-packages. Alternatively you can run the above commands from a virtualenv or a conda environment to get full isolation from the Python packages installed via the system packager. When using an isolated environment, pip3 should be replaced by pip in the above commands.

When precompiled wheels of the runtime dependencies are not available for your architecture (e.g. ARM), you can install the system versions:

$ sudo apt-get install cython3 python3-numpy python3-scipy

On Red Hat and clones (e.g. CentOS), install the dependencies using:

$ sudo yum -y install gcc gcc-c++ python3-devel numpy scipy

Linux compilers from conda-forge

Alternatively, install a recent version of the GNU C Compiler toolchain (GCC) in the user folder using conda:

$ conda create -n sklearn-dev -c conda-forge python numpy scipy cython joblib threadpoolctl pytest compilers
$ conda activate sklearn-dev
$ pip install --verbose --no-build-isolation --editable .

FreeBSD

The clang compiler included in FreeBSD 12.0 and 11.2 base systems does not include OpenMP support. You need to install the openmp library from packages (or ports):

$ sudo pkg install openmp

This will install header files in /usr/local/include and libs in /usr/local/lib. Since these directories are not searched by default, you can set the environment variables to these locations:

$ export CFLAGS="$CFLAGS -I/usr/local/include"
$ export CXXFLAGS="$CXXFLAGS -I/usr/local/include"
$ export LDFLAGS="$LDFLAGS -L/usr/local/lib -lomp"

Finally, build the package using the standard command:

$ pip install --verbose --no-build-isolation --editable .

For the upcoming FreeBSD 12.1 and 11.3 versions, OpenMP will be included in the base system and these steps will not be necessary.
8.6.4 Alternative compilers

The command:

```bash
$ pip install --verbose --editable .
```

will build scikit-learn using your default C/C++ compiler. If you want to build scikit-learn with another compiler handled by distutils or by numpy.distutils, use the following command:

```bash
$ python setup.py build_ext --compiler=<compiler> -i build_clib --compiler=<compiler>
```

To see the list of available compilers run:

```bash
$ python setup.py build_ext --help-compiler
```

If your compiler is not listed here, you can specify it via the CC and LDSHARE environment variables (does not work on windows):

```bash
$ CC=<compiler> LDSHARE="<compiler> -shared" python setup.py build_ext -i
```

**Building with Intel C Compiler (ICC) using oneAPI on Linux**

Intel provides access to all of its oneAPI toolkits and packages through a public APT repository. First you need to get and install the public key of this repository:

```bash
$ sudo apt-key add GPG-PUB-KEY-INTEL-SW-PRODUCTS-2023.PUB
$ rm GPG-PUB-KEY-INTEL-SW-PRODUCTS-2023.PUB
```

Then, add the oneAPI repository to your APT repositories:

```bash
$ sudo add-apt-repository "deb https://apt.repos.intel.com/oneapi all main"
$ sudo apt-get update
```

Install ICC, packaged under the name intel-oneapi-icc:

```bash
$ sudo apt-get install intel-oneapi-icc
```

Before using ICC, you need to set up environment variables:

```bash
$ source /opt/intel/oneapi/setvars.sh
```

Finally, you can build scikit-learn. For example on Linux x86_64:

```bash
$ python setup.py build_ext --compiler=intelem -i build_clib --compiler=intelem
```

8.6.5 Parallel builds

It is possible to build scikit-learn compiled extensions in parallel by setting and environment variable as follows before calling the `pip install` or `python setup.py build_ext` commands:

```bash
export SKLEARN_BUILD_PARALLEL=3
```

```bash
pip install --verbose --no-build-isolation --editable .
```

On a machine with 2 CPU cores, it can be beneficial to use a parallelism level of 3 to overlap IO bound tasks (reading and writing files on disk) with CPU bound tasks (actually compiling).
8.7 Bug triaging and issue curation

The issue tracker is important to the communication in the project: it helps developers identify major projects to work on, as well as to discuss priorities. For this reason, it is important to curate it, adding labels to issues and closing issues that are not necessary.

8.7.1 Working on issues to improve them

Improving issues increases their chances of being successfully resolved. Guidelines on submitting good issues can be found [here](#). A third party can give useful feedback or even add comments on the issue. The following actions are typically useful:

- documenting issues that are missing elements to reproduce the problem such as code samples
- suggesting better use of code formatting
- suggesting to reformulate the title and description to make them more explicit about the problem to be solved
- linking to related issues or discussions while briefly describing how they are related, for instance “See also #xyz for a similar attempt at this” or “See also #xyz where the same thing happened in SomeEstimator” provides context and helps the discussion.

Fruitful discussions

Online discussions may be harder than it seems at first glance, in particular given that a person new to open-source may have a very different understanding of the process than a seasoned maintainer.

Overall, it is useful to stay positive and assume good will. The following article explores how to lead online discussions in the context of open source.

8.7.2 Working on PRs to help review

Reviewing code is also encouraged. Contributors and users are welcome to participate to the review process following our [review guidelines](#).

8.7.3 Triaging operations for members of the core and triage teams

In addition to the above, members of the core team and the triage team can do the following important tasks:

- Update labels for issues and PRs: see the list of the available github labels.
- Determine if a PR must be relabeled as stalled or needs help (this is typically very important in the context of sprints, where the risk is to create many unfinished PRs)
- Triage issues:
  - close usage questions and politely point the reporter to use Stack Overflow instead.
  - close duplicate issues, after checking that they are indeed duplicate. Ideally, the original submitter moves the discussion to the older, duplicate issue
  - close issues that cannot be replicated, after leaving time (at least a week) to add extra information

Saved replies are useful to gain time and yet be welcoming and polite when triaging.

See the github description for roles in the organization.
Closing issues: a tough call

When uncertain on whether an issue should be closed or not, it is best to strive for consensus with the original poster, and possibly to seek relevant expertise. However, when the issue is a usage question, or when it has been considered as unclear for many years it should be closed.

8.7.4 A typical workflow for triaging issues

The following workflow is a good way to approach issue triaging:

1. Thank the reporter for opening an issue

   The issue tracker is many people’s first interaction with the scikit-learn project itself, beyond just using the library. As such, we want it to be a welcoming, pleasant experience.

2. Is this a usage question? If so close it with a polite message (here is an example).

3. Is the necessary information provided?

   If crucial information (like the version of scikit-learn used), is missing feel free to ask for that and label the issue with “Needs info”.

4. Is this a duplicate issue?

   We have many open issues. If a new issue seems to be a duplicate, point to the original issue. If it is a clear duplicate, or consensus is that it is redundant, close it. Make sure to still thank the reporter, and encourage them to chime in on the original issue, and perhaps try to fix it.

   If the new issue provides relevant information, such as a better or slightly different example, add it to the original issue as a comment or an edit to the original post.

5. Make sure that the title accurately reflects the issue. If you have the necessary permissions edit it yourself if it’s not clear.

6. Is the issue minimal and reproducible?

   For bug reports, we ask that the reporter provide a minimal reproducible example. See this useful post by Matthew Rocklin for a good explanation. If the example is not reproducible, or if it’s clearly not minimal, feel free to ask the reporter if they can provide and example or simplify the provided one. Do acknowledge that writing minimal reproducible examples is hard work. If the reporter is struggling, you can try to write one yourself.

   If a reproducible example is provided, but you see a simplification, add your simpler reproducible example.

7. Add the relevant labels, such as “Documentation” when the issue is about documentation, “Bug” if it is clearly a bug, “Enhancement” if it is an enhancement request, . . .

   If the issue is clearly defined and the fix seems relatively straightforward, label the issue as “Good first issue”.

   An additional useful step can be to tag the corresponding module e.g. sklearn.linear_models when relevant.

---

1 Adapted from the pandas project maintainers guide
8.8 Maintainer / core-developer information

8.8.1 Releasing

This section is about preparing a major release, incrementing the minor version, or a bug fix release incrementing the patch version. Our convention is that we release one or more release candidates (0.RRrcN) before releasing the final distributions. We follow the PEP101 to indicate release candidates, post, and minor releases.

Before a release

1. Update authors table:

   $ cd build_tools; make authors; cd ..

   and commit. This is only needed if the authors have changed since the last release. This step is sometimes done independent of the release. This updates the maintainer list and is not the contributor list for the release.

2. Confirm any blockers tagged for the milestone are resolved, and that other issues tagged for the milestone can be postponed.

3. Ensure the change log and commits correspond (within reason!), and that the change log is reasonably well curated. Some tools for these tasks include:
   
   • maint_tools/sort_whats_new.py can put what’s new entries into sections. It’s not perfect, and requires manual checking of the changes. If the whats new list is well curated, it may not be necessary.
   
   • The maint_tools/whats_missing.sh script may be used to identify pull requests that were merged but likely missing from What’s New.

4. Make sure the deprecations, FIXME and TODOs tagged for the release have been taken care of.

Permissions

The release manager requires a set of permissions on top of the usual permissions given to maintainers, which includes:

   • maintainer role on scikit-learn projects on pypi.org and test.pypi.org, separately.
   
   • become a member of the scikit-learn team on conda-forge by editing the recipe/meta.yaml file on https://github.com/conda-forge/scikit-learn-feedstock

Preparing a release PR

Major version release

Prior to branching please do not forget to prepare a Release Highlights page as a runnable example and check that its HTML rendering looks correct. These release highlights should be linked from the doc/whats_new/v0.99.rst file for the new version of scikit-learn.

Releasing the first RC of e.g. version 0.99.0 involves creating the release branch 0.99.X directly on the main repo, where X really is the letter X, not a placeholder. The development for the major and minor releases of 0.99 should also happen under 0.99.X. Each release (rc, major, or minor) is a tag under that branch.

This is done only once, as the major and minor releases happen on the same branch:

   $ # Assuming upstream is an alias for the main scikit-learn repo:
   $ git fetch upstream master
   $ git checkout upstream/master
   $ git checkout -b 0.99.X
   $ git push --set-upstream upstream 0.99.X
Again, \( X \) is literal here, and 99 is replaced by the release number. The branches are called 0.19.X, 0.20.X, etc.

In terms of including changes, the first RC ideally counts as a feature freeze. Each coming release candidate and the final release afterwards will include only minor documentation changes and bug fixes. Any major enhancement or feature should be excluded.

Then you can prepare a local branch for the release itself, for instance: release-0.99.0rc1, push it to your github fork and open a PR to the scikit-learn/0.99.X branch. Copy the Release checklist templates in the description of the Pull Request to track progress.

This PR will be used to push commits related to the release as explained in Making a release.

You can also create a second PR from master and targeting master to increment the \_version\_ variable in \sklearn/\_init\_.py to increment the dev version. This means while we’re in the release candidate period, the latest stable is two versions behind the master branch, instead of one. In this PR targeting master you should also include a new file for the matching version under the doc/whats_new/ folder so PRs that target the next version can contribute their changelog entries to this file in parallel to the release process.

## Minor version release

The minor releases should include bug fixes and some relevant documentation changes only. Any PR resulting in a behavior change which is not a bug fix should be excluded.

First, create a branch, on your own fork (to release e.g. 0.99.3):

$ # assuming master and upstream/master are the same
$ git checkout -b release-0.99.3 master

Then, create a PR to the scikit-learn/0.99.X branch (not to master!) with all the desired changes:

$ git rebase -i upstream/0.99.2

Copy the Release checklist templates in the description of the Pull Request to track progress.

Do not forget to add a commit updating \sklearn.__version__.

It’s nice to have a copy of the \git rebase -i\ log in the PR to help others understand what’s included.

## Making a release

0. Ensure that you have checked out the branch of the release PR as explained in Preparing a release PR above.

1. Update docs. Note that this is for the final release, not necessarily for the RC releases. These changes should be made in master and cherry-picked into the release branch, only before the final release.

   • Edit the doc/whats_new/v0.99.rst file to add release title and list of contributors. You can retrieve the list of contributor names with:

   ```bash
   $ git shortlog -s 0.98.33.. | cut -f2- | sort --ignore-case | tr \'
   s/;\/, /g;s/, $//' | fold -s
   ```

   – For major releases, link the release highlights example from the doc/whats_new/v0.99.rst file.

   • Update the release date in whats_new.rst

   • Edit the doc/templates/index.html to change the ‘News’ entry of the front page (with the release month as well).
2. On the branch for releasing, update the version number in `sklearn/__init__.py`, the `__version__`. For major releases, please add a 0 at the end: 0.99.0 instead of 0.99.
   For the first release candidate, use the `rc1` suffix on the expected final release number: 0.99.0rc1.

3. Trigger the wheel builder with the `[cd build]` commit marker using the command:

   ```
   $ git commit --allow-empty -m "Trigger wheel builder workflow: [cd build]"
   ```

   The wheel building workflow is managed by GitHub Actions and the results be browsed at: https://github.com/scikit-learn/scikit-learn/actions?query=workflow%3A%22Wheel+builder%22

   **Note:** Before building the wheels, make sure that the `pyproject.toml` file is up to date and using the oldest version of `numpy` for each Python version to avoid ABI incompatibility issues. Moreover, a new line have to be included in the `pyproject.toml` file for each new supported version of Python.

   **Note:** The acronym CD in `[cd build]` stands for Continuous Delivery and refers to the automation used to generate the release artifacts (binary and source packages). This can be seen as an extension to CI which stands for Continuous Integration. The CD workflow on GitHub Actions is also used to automatically create nightly builds and publish packages for the developement branch of scikit-learn. See **Installing nightly builds**.

4. Once all the CD jobs have completed successfully in the PR, merge it, again with the `[cd build]` marker in the commit message. This time the results will be uploaded to the staging area.

   You should then be able to upload the generated artifacts (.tar.gz and .whl files) to https://test.pypi.org using the “Run workflow” form for the following GitHub Actions workflow:

   https://github.com/scikit-learn/scikit-learn/actions?query=workflow%3A%22Publish+to+Pypi%22

5. If this went fine, you can proceed with tagging. Proceed with caution. Ideally, tags should be created when you’re almost certain that the release is ready, since adding a tag to the main repo can trigger certain automated processes.

   Create the tag and push it (if it’s an RC, it can be 0.xx.0rc1 for instance):

   ```
   $ git tag -a 0.99.0 # in the 0.99.X branch
   $ git push git@github.com:scikit-learn/scikit-learn.git 0.99.0
   ```

6. Trigger the GitHub Actions workflow again but this time to upload the artifacts to the real https://pypi.org (replace “testpypi” by “pypi” in the “Run workflow” form).

7. Alternatively, it’s possible to collect locally the generated binary wheel packages and source tarball and upload them all to PyPI by running the following commands in the scikit-learn source folder (checked out at the release tag):

   ```
   $ rm -r dist
   $ pip install -U wheelhouse_uploader twine
   $ python setup.py fetch_artifacts
   ```

   This command will download all the binary packages accumulated in the staging area on the anaconda.org hosting service and put them in your local ./dist folder.

   Check the content of the ./dist folder: it should contain all the wheels along with the source tarball (“scikit-learn-RRR.tar.gz”).

   Make sure that you do not have developer versions or older versions of the scikit-learn package in that folder.

   Before uploading to pypi, you can test upload to test.pypi.org:

   ```
   $ twine upload --verbose --repository-url https://test.pypi.org/legacy/ dist/*
   ```
Upload everything at once to https://pypi.org:

$ twine upload dist/*

8. For major/minor (not bug-fix release), update the symlink for `stable` and the `latestStable` variable in
https://github.com/scikit-learn/scikit-learn.github.io:

$ cd /tmp
$ git clone --depth 1 --no-checkout git@github.com:scikit-learn/scikit-learn.github.io.git
$ cd scikit-learn.github.io
$ git checkout master
$ rm stable
$ ln -s 0.999 stable
$ sed -i "s/\s/latestStable = '.*/latestStable = '0.999';/" versionwarning.js
$ git add stable/ versionwarning.js
$ git commit -m "Update stable to point to 0.999"
$ git push origin master

Release checklist

The following GitHub checklist might be helpful in a release PR:

- [ ] update news and what's new date in release branch
- [ ] update news and what's new date and sklearn dev0 version in master branch
- [ ] check that the for the release wheels can be built successfully
- [ ] merge the PR with `[cd build]` commit message to upload wheels to the staging repo
- [ ] upload the wheels and source tarball to https://test.pypi.org
- [ ] create tag on the main github repo
- [ ] upload the wheels and source tarball to PyPI
- [ ] https://github.com/scikit-learn/scikit-learn/releases draft
- [ ] confirm bot detected at https://github.com/conda-forge/scikit-learn-feedstock and wait for merge
- [ ] https://github.com/scikit-learn/scikit-learn/releases publish
- [ ] fix the binder release version in ```.binder/requirement.txt``` (see #15847)
- [ ] announce on mailing list and on twitter

8.8.2 Merging Pull Requests

Individual commits are squashed when a Pull Request (PR) is merged on Github. Before merging,

- the resulting commit title can be edited if necessary. Note that this will rename the PR title by default.
- the detailed description, containing the titles of all the commits, can be edited or deleted.
- for PRs with multiple code contributors care must be taken to keep the `Co-authored-by: name <name@example.com>` tags in the detailed description. This will mark the PR as having multiple co-authors. Whether code contributions are significantly enough to merit co-authorship is left to the maintainer’s discretion, same as for the “what’s new” entry.
8.8.3 The scikit-learn.org web site

The scikit-learn web site (http://scikit-learn.org) is hosted at GitHub, but should rarely be updated manually by pushing to the https://github.com/scikit-learn/scikit-learn.github.io repository. Most updates can be made by pushing to master (for /dev) or a release branch like 0.99.X, from which Circle CI builds and uploads the documentation automatically.

8.8.4 Travis Cron jobs

From https://docs.travis-ci.com/user/cron-jobs: Travis CI cron jobs work similarly to the cron utility, they run builds at regular scheduled intervals independently of whether any commits were pushed to the repository. Cron jobs always fetch the most recent commit on a particular branch and build the project at that state. Cron jobs can run daily, weekly or monthly, which in practice means up to an hour after the selected time span, and you cannot set them to run at a specific time.

For scikit-learn, Cron jobs are used for builds that we do not want to run in each PR. As an example the build with the dev versions of numpy and scipy is run as a Cron job. Most of the time when this numpy-dev build fail, it is related to a numpy change and not a scikit-learn one, so it would not make sense to blame the PR author for the Travis failure.

The definition of what gets run in the Cron job is done in the .travis.yml config file, exactly the same way as the other Travis jobs. We use a if: type = cron filter in order for the build to be run only in Cron jobs.

The branch targeted by the Cron job and the frequency of the Cron job is set via the web UI at https://www.travis-ci.org/scikit-learn/scikit-learn/settings.

8.8.5 Experimental features

The sklearn.experimental module was introduced in 0.21 and contains experimental features / estimators that are subject to change without deprecation cycle.

To create an experimental module, you can just copy and modify the content of enable_hist_gradient_boosting.py, or enable_iterative_imputer.py.

Note that the public import path must be to a public subpackage (like sklearn/ensemble or sklearn/impute), not just a .py module. Also, the (private) experimental features that are imported must be in a submodule/subpackage of the public subpackage, e.g. sklearn/ensemble/_hist_gradient_boosting/ or sklearn/impute/_iterative.py. This is needed so that pickles still work in the future when the features aren’t experimental anymore.

To avoid type checker (e.g. mypy) errors a direct import of experimental estimators should be done in the parent module, protected by the if typing.TYPE_CHECKING check. See sklearn/ensemble/__init__.py, or sklearn/impute/__init__.py for an example.

Please also write basic tests following those in test_enable_hist_gradient_boosting.py.

Make sure every user-facing code you write explicitly mentions that the feature is experimental, and add a # noqa comment to avoid pep8-related warnings:

```
# To use this experimental feature, we need to explicitly ask for it:
from sklearn.experimental import enable_hist_gradient_boosting  # noqa
from sklearn.ensemble import HistGradientBoostingRegressor
```

For the docs to render properly, please also import enable_my_experimental_feature in doc/conf.py, else sphinx won’t be able to import the corresponding modules. Note that using from sklearn.experimental import * does not work.

Note that some experimental classes / functions are not included in the sklearn.experimental module: sklearn.datasets.fetch_openml.
8.9 Developing with the Plotting API

Scikit-learn defines a simple API for creating visualizations for machine learning. The key features of this API is to run calculations once and to have the flexibility to adjust the visualizations after the fact. This section is intended for developers who wish to develop or maintain plotting tools. For usage, users should refer to the :ref `User Guide <visualizations>`.

### 8.9.1 Plotting API Overview

This logic is encapsulated into a display object where the computed data is stored and the plotting is done in a `plot` method. The display object’s `__init__` method contains only the data needed to create the visualization. The `plot` method takes in parameters that only have to do with visualization, such as a matplotlib axes. The `plot` method will store the matplotlib artists as attributes allowing for style adjustments through the display object. A `plot_*` helper function accepts parameters to do the computation and the parameters used for plotting. After the helper function creates the display object with the computed values, it calls the display’s `plot` method. Note that the `plot` method defines attributes related to matplotlib, such as the line artist. This allows for customizations after calling the `plot` method.

For example, the `RocCurveDisplay` defines the following methods and attributes:

```python
class RocCurveDisplay:
    def __init__(self, fpr, tpr, roc_auc, estimator_name):
        ...
        self.fpr = fpr
        self.tpr = tpr
        self.roc_auc = roc_auc
        self.estimator_name = estimator_name

    def plot(self, ax=None, name=None, **kwargs):
        ...
        self.line_ = ...
        self.ax_ = ax
        self.figure_ = ax.figure_

    def plot_roc_curve(self, estimator, X, y, pos_label=None, sample_weight=None, drop_intermediate=True, response_method="auto", name=None, ax=None, **kwargs):
        # do computation
        viz = RocCurveDisplay(fpr, tpr, roc_auc, estimator.__class__.__name__)
        return viz.plot(ax=ax, name=name, **kwargs)
```

Read more in `ROC Curve with Visualization API` and the `User Guide`.

### 8.9.2 Plotting with Multiple Axes

Some of the plotting tools like `plot_partial_dependence` and `PartialDependenceDisplay` support plotting on multiple axes. Two different scenarios are supported:

1. If a list of axes is passed in, `plot` will check if the number of axes is consistent with the number of axes it expects and then draws on those axes. 2. If a single axes is passed in, that axes defines a space for multiple axes to be placed. In this case, we suggest using matplotlib’s `~matplotlib.gridspec.GridSpecFromSubplotSpec` to split up the space:
import matplotlib.pyplot as plt
from matplotlib.gridspec import GridSpecFromSubplotSpec

fig, ax = plt.subplots()
gs = GridSpecFromSubplotSpec(2, 2, subplot_spec=ax.get_subplotspec())

ax_top_left = fig.add_subplot(gs[0, 0])
ax_top_right = fig.add_subplot(gs[0, 1])
ax_bottom = fig.add_subplot(gs[1, :])

By default, the ax keyword in plot is None. In this case, the single axes is created and the gridspec api is used to create the regions to plot in.

See for example, plot_partial_dependence which plots multiple lines and contours using this API. The axes defining the bounding box is saved in a bounding_ax attribute. The individual axes created are stored in an axes ndarray, corresponding to the axes position on the grid. Positions that are not used are set to None. Furthermore, the matplotlib Artists are stored in lines and contours where the key is the position on the grid. When a list of axes is passed in, the axes_, lines_, and contours_ is a 1d ndarray corresponding to the list of axes passed in.


[Brier1950] G. Brier, Verification of forecasts expressed in terms of probability, Monthly weather review 78.1 (1950)


[PP2013] “Fast and scalable polynomial kernels via explicit feature maps” Pham, N., & Pagh, R. - 2013


[WIKICS] “Wikipedia: Count sketch”

[1] Obtaining calibrated probability estimates from decision trees and naive Bayesian classifiers, B. Zadrozny & C. Elkan, ICML 2001


Wikipedia entry for the Brier score.


Wikipedia entry for the Cohen’s kappa.

Wikipedia entry for the Confusion matrix (Wikipedia and other references may use a different convention for axes).

Wikipedia entry for the F1-score.


Wikipedia entry for the F1-score.


Wikipedia entry on the Hamming distance.

Wikipedia entry on the Hinge loss.


L1 AND L2 Regularization for Multiclass Hinge Loss Models by Robert C. Moore, John DeNero.


Wikipedia entry for the Matthews Correlation Coefficient.


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